### Deep Learning: Principal Component Analysis

Lecture 05

# Principal Component Analysis (PCA)

- A technique widely used for:
  - dimensionality reduction.
  - data compression.
  - feature extraction.
  - data visualization.

maximum variance

- Two equivalent definitions of PCA:
  - 1) Project the data onto a lower dimensional space such that the variance of the projected data is *maximized*.
  - Project the data onto a lower dimensional space such that the mean squared distance between data points and their projections (average projection cost) is *minimized*.

minimum error

## PCA (Maximum Variance)

- Let  $X = \{x_n\}_{1 \le n \le N}$  be a set of observations:
  - Each  $\mathbf{x}_n \in \mathbb{R}^D(D \text{ is the dimensionality of } \mathbf{x}_n)$ .
- Project X onto an M dimensional space (M < D) such that the *variance* of the projected X is *maximized*.
  - Minimum error formulation leads to the same solution [PRML 12.1.2].
    - shows how PCA can be used for compression.
- Work out solution for M = 1, then generalize to any M < D.

# PCA (Maximum Variance, M=1)

- The lower dimensional space is defined by a vector  $\mathbf{u}_1 \in \mathbb{R}^D$ .
  - Only direction is important  $\Rightarrow$  choose  $\|\mathbf{u}_1\|=1$ .
- Each  $\mathbf{x}_n$  is projected onto a scalar  $\mathbf{u}_1^T \mathbf{x}_n$
- The (sample) mean of the data is:

$$\overline{\mathbf{x}} = \frac{1}{N} \sum_{n=1}^{N} \mathbf{x}_n$$

• The (sample) mean of the projected data is  $\mathbf{u}_{1}^{T} \mathbf{x}$ 

#### PCA (Maximum Variance, M = 1)

• The (sample) variance of the projected data:

$$\frac{1}{N} \sum_{n=1}^{N} \left( \mathbf{u}_{1}^{T} \mathbf{x}_{n} - \mathbf{u}_{1}^{T} \mathbf{x} \right)^{2} = \mathbf{u}_{1}^{T} \mathbf{\Sigma} \mathbf{u}_{1}$$

where  $\Sigma$  is the data covariance matrix:

$$\sum = \frac{1}{N} \sum_{n=1}^{N} (x_n - \overline{x}) (x_n - \overline{x})^T$$

• Optimization problem is:

minimize:

$$-u_1^T \sum u_1$$

subject to:

$$\mathbf{u}_1^T \mathbf{u}_1 = 1$$

# PCA (Maximum Variance, M=1)

• Lagrangian function:

$$L_P(\mathbf{u}_1, \lambda_1) = -\mathbf{u}_1^T \mathbf{\Sigma} \mathbf{u}_1 + \lambda_1 (\mathbf{u}_1^T \mathbf{u}_1 - 1)$$

where  $\lambda_1$  is the Lagrangian multiplier for constraint  $\mathbf{u}^T \mathbf{u}_1 = 1$ 

Solve:

$$\frac{\partial L_P}{\partial \mathbf{u}_1} = 0 \Rightarrow \mathbf{\Sigma} \mathbf{u}_1 = \lambda_1 \mathbf{u}_1 \Rightarrow \begin{cases} \mathbf{u}_1 \text{ is an eigenvector of } \mathbf{\Sigma} \\ \lambda_1 \text{ is an eigenvalue of } \mathbf{\Sigma} \end{cases}$$

$$\bullet \quad -\mathbf{u}_1^T \mathbf{\Sigma} \mathbf{u}_1 = -\lambda_1 \mathbf{u}_1^T \mathbf{u}_1 = -\lambda_1$$

•  $\lambda_1$  is the largest eigenvalue of  $\Sigma$ .

# PCA (Maximum Variance, M = 1)

- $\lambda_1$  is the largest eigenvalue of  $\Sigma$ .
- $\mathbf{u}_1$  is the eigenvector corresponding to  $\lambda_1$ :
  - also called the first principal component.
- For M < D dimensions:
  - $\mathbf{u}_1 \mathbf{u}_2 \dots \mathbf{u}_M$  are the eigenvectors corresponding to the largest eigenvalues  $\lambda_1 \lambda_2 \dots \lambda_M$  of  $\Sigma$ .
  - proof by induction.

### PCA on Normalized Data

- Preprocess data  $X = \{x^{(i)}\}_{1 \le i \le m}$  such that:
  - features have the same *mean* (0).
  - features have the same *variance* (1).
- 1. Let  $\mu = \frac{1}{m} \sum_{i=1}^{m} x^{(i)}$ .
- 2. Replace each  $x^{(i)}$  with  $x^{(i)} \mu$ .
- 3. Let  $\sigma_j^2 = \frac{1}{m} \sum_i (x_j^{(i)})^2$
- 4. Replace each  $x_j^{(i)}$  with  $x_j^{(i)}/\sigma_j$ .

### PCA on Natural Images

- Stationarity: the statistics in one part of the image should be the same as any other.
  - no need for variance normalization.
  - do mean normalization by substracting from each image its mean intensity.

$$\mu^{(i)} := \frac{1}{n} \sum_{j=1}^{n} x_j^{(i)}$$
$$x_j^{(i)} := x_j^{(i)} - \mu^{(i)}$$

### PCA on Normalized Data

• The covariance matrix is:

$$\Sigma = \frac{1}{m} X X^{T} = \frac{1}{m} \sum_{i=1}^{m} \mathbf{x}^{(i)} (\mathbf{x}^{(i)})^{T}$$

• The eigenvectors are:

$$\sum \mathbf{u}_j = \lambda_j \mathbf{u}_j$$
 where  $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_D$  and  $u_j^T u_j = 1$ 

• Equivalent with:

$$\Sigma U = U\Lambda$$

$$U = [u_1, u_2, ..., u_D] \qquad \lambda_1 \ge \lambda_2 \ge ... \ge \lambda_D \text{ and } U^T U = I$$

$$\Lambda = diag(\lambda_1, \lambda_2, ..., \lambda_D)$$

### PCA on Normalized Data

- *U* is an orthogonal (rotation) matrix, i.e.  $U^TU = I$ .
- The full transformation (rotation) of  $x^{(i)}$  through PCA is:

$$y^{(i)} = U^T x^{(i)}$$
$$x^{(i)} = U y^{(i)}$$

• The *k*-dimensional projection of  $x^{(i)}$  through PCA is:

$$\hat{y}^{(i)} = U_{1,k}^T x^{(i)} = [u_1, \dots, u_k]^T x^{(i)}$$

$$\bullet \quad \hat{x}^{(i)} = U_{1,k} y^{(i)}$$

• How many components *k* should be used?

### How many components *k* should be used?

• Compute *percentage of variance retained* by  $Y = \{y^{(i)}\}$ , for each value of k:

$$\hat{y}^{(i)} = [u_1, \dots, u_k]^T x^{(i)}$$

$$Var(k) = \sum_{j=1}^k Var[\hat{y}_j] = \sum_{j=1}^k Var[u_j^T x]$$

$$= \sum_{j=1}^k \frac{1}{m} \sum_{i=1}^m (u_j^T x^{(i)} - u_j^T \overline{x})^2 = \sum_{j=1}^k \frac{1}{m} \sum_{i=1}^m (u_j^T x^{(i)})^2 = \sum_{j=1}^k \lambda_j$$

$$\text{HW: Prove it is } \lambda_j$$

#### How many components *k* should be used?

- Compute percentage of variance retained by  $Y = \{y^{(i)}\}$ , for each value of k:
  - Variance retained:

$$Var(k) = \sum_{j=1}^{k} \lambda_j$$

– Total variance:

$$Var(D) = \sum_{j=1}^{D} \lambda_j$$

 $Var(D) = \sum_{j=1}^{\kappa} \lambda_{j}$ - Percentage of variance retained:  $P(k) = \frac{\sum_{j=1}^{\kappa} \lambda_{j}}{\sum_{j=1}^{\kappa} \lambda_{j}}$ 

#### How many components *k* should be used?

• Compute *percentage of variance retained* by  $Y = \{y^{(i)}\}$ , for each value of k:

$$P(k) = \frac{\sum_{j=1}^{k} \lambda_{j}}{\sum_{j=1}^{D} \lambda_{j}}$$

• Choose smallest k as to retain 99% of variance:

$$\hat{k} = \underset{1 \le k \le D}{\operatorname{argmin}} [P(k) \ge 0.99]$$

### PCA as a Linear Auto-Encoder

• The full transformation (rotation) of  $x^{(i)}$  through PCA is:

$$y = U^T x \Rightarrow x = Uy$$

• The *k*-dimensional projection of  $x^{(i)}$  through PCA is:

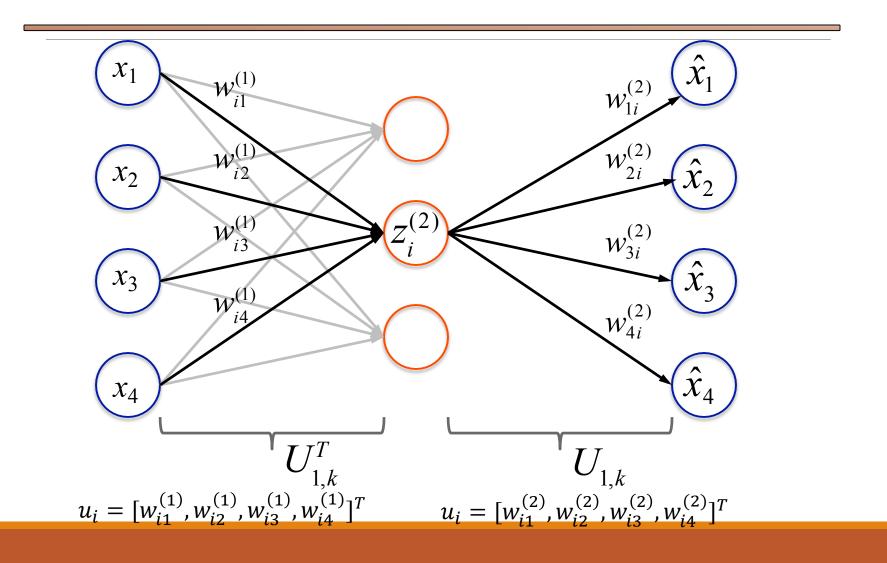
$$\hat{y} = U_{1,k}^T x = [u_1, \dots, u_k]^T x \Rightarrow \hat{x} = U_{1,k} \hat{y} = U_{1,k} U_{1,k}^T x$$

• The minimum error formulation of PCA:

$$U_{1,k}^* = \underset{U_{1,k}}{\operatorname{argmin}} \sum_{i=1}^{m} \left\| U_{1,k} U_{1,k}^T x^{(i)} - x^{(i)} \right\|^2$$

a linear auto-encoder with tied weights!

### PCA as a Linear Auto-Encoder



### PCA and Decorrelation

• The full transformation (rotation) of  $x^{(i)}$  through PCA is:

$$y^{(i)} = U^T x^{(i)} \Longrightarrow Y = U^T X$$

• What is the covariance matrix of the rotated data Y?

$$\frac{1}{m}YY^{T} = \frac{1}{m}(U^{T}X)(U^{T}X)^{T} = \frac{1}{m}U^{T}XX^{T}U$$

$$= U^{T}(\frac{1}{m}XX^{T})U = U^{T} \sum U = \Lambda$$

$$= \operatorname{diag}(\lambda_{1}, \lambda_{2}, ..., \lambda_{D}) = > \text{ the features in } y$$

$$= \text{ are decorrelated!}$$

# PCA Whitening (Sphering)

- The goal of **whitening** is to make the input *less redundant*, i.e. the learning algorithm sees a training input where:
  - 1. The features are not correlated with each other.
  - 2. The features all have the same variance.
- 1. PCA already results in uncorrelated features:

$$y^{(i)} = U^T x^{(i)} \Leftrightarrow Y = U^T X \qquad \frac{1}{m} Y Y^T = diag(\lambda_1, \lambda_2, \dots, \lambda_D)$$

2. Transform to identity covariance (PCA Whitening):

$$y_j^{(i)} = \frac{u_j^T x^{(i)}}{\sqrt{\lambda_j}} \Leftrightarrow y^{(i)} = \Lambda^{-\frac{1}{2}} U^T x^{(i)} \Leftrightarrow Y = \Lambda^{-\frac{1}{2}} U^T X$$

# ZCA Whitening (Sphering)

- Observation: If Y has identity covariance and R is an orthogonal matrix, then RY has identity covariance.
  - 1. PCA Whitening:

$$Y_{PCA} = \Lambda^{-1/2} U^T X$$

#### 2. ZCA Whitening:

$$Y_{ZCA} = UY_{PCA} = U\Lambda^{-1/2}U^TX$$

Out of all rotations, U makes  $Y_{ZCA}$  closest to original X.

## Smoothing

- When eigenvalues  $\lambda_j$  are very close to 0, dividing by  $\lambda_j^{-1/2}$  is numerically unstable.
- **Smoothing**: add a small ε to eigenvalues before scaling for PCA/ZCA whitening:

$$y_j^{(i)} = \frac{u^T x^{(i)}}{\sqrt{\lambda_j + \varepsilon}} \qquad \varepsilon \approx 10^{-5}$$

• ZCA whitening is a rough model of how the biological eye (the retina) processes images (through retinal neurons).