ICAPS 2019 Schedule overview

	Saturday 13th	
8.15-8.30	Opening Remarks	
8.30-9.30	Invited talk: Anca Dragan	
9.40-10.40	Classical Planning	Planetary Exploration
10.40-11.00	Coffee break	
11.00-12.30	Probabilistic Planning I	LTL & Temporal Planning
12.30-14.00	Lunch	
14.00-15.30	Search	Reinforcement Learning
15.30-15.50	Coffee break	
15.50-16.30	Invited Industry Session	Hybrid Planning & Algorithm Selection
16.40-17.40		Complexity
	18.00-20.00 Poster & Demo session (drinks & appetizers provided)	

	Sunday 14th	
8.30-9.30	Invited talk: J. Christopher Beck	
9.40-10.40	Multi-Agent Planning	Knowledge Engineering and Execution
10.40-11.00	Coffee break	
11.00-12.30	Optimal & Oversubscription Planning	Scheduling under Uncertainty
12.30-14.00	Lunch	
14.00-15.30	Recognition, Goal and Model Reasoning	Applications I
15.30-15.50	Coffee break	
15.50-16.30	Recognition II	Robotics I
16.40-17.40	Awards + Community meeting (ends at 18:30)	
	19:00 - Banquet	

	Monday 15th	
8.30-9.30	Invited talk: Derek Long	
9.40-10.40	Probabilistic Planning II	Applications II
10.40-11.00	Coffee break	
11.00-12.30	Learning	Constraint Reasoning and OR
12.30-14.00	Lunch	
14.00-15.30	Path and Motion Planning	Robotics II
15.30-15.50	Coffee break	
15.50-16.30	Path Planning	Transportation Scheduling
16.40-17.40	Applications III	Hybrid Planning

Saturday 13th

8.15-8.30	Opening Remarks				
8.30-9.30	Invited talk: Anca Dragan				
9.40-10.40	1a: Classical Planning	Chair: Sheila McIlraith		1b: Planetary Exploration	Chair:
	Theoretical Foundations for Structural Symmetries of Lifted PDDL Tasks	Silvan Sievers, Gabriele Röger, Martin Wehrle and Michael Katz		Robust Operations Management on Mars	Michael Saint-Guillain
	Relaxed BDDs: An Admissible Heuristic for Delete-Free Planning Based on a Discrete Relaxation	Margarita Castro, Chiara Piacentini, Andre Augusto Cire and Chris Beck		Temporal Brittleness Analysis of Task Networks for Planetary Rovers	Tiago Vaquero, Steve Chien, Jagriti Agrawal, Wayne Chi and Terrance Huntsberger
	Planning with Global State Constraints and State-Dependent Action Costs	Franc Ivankovic, Patrik Haslum and Dan Gordon	Short Paper	Mars On-site Shared Analytics, Information, and Computing	Joshua Vander Hook, Tiago Stegun Vaquero, Federico Rossi, Martina Troesch, Marc Sanchez-Net, Joshua Schoolcraft, Jean-Pierre de la Croix and Steve Chien
	Advanced Factoring Strategies for Decoupled Search using Linear Programming	Frederik Schmitt, Daniel Gnad and Joerg Hoffmann	Short Paper		
10.40-11.00	Coffee break				
11.00-12.30	2a: Probabilistic Planning I	Chair: Florent Teichteil-Koenigsbuch		2b: LTL & Temporal Planning	Chair: Patrik Haslum
	Robust Bayes-Adaptive Planning under Model Uncertainty	Apoorva Sharma, James Harrison, Matthew Tsao and Marco Pavone		Planning under LTL Environment Specifications	Benjamin Aminof, Giuseppe De Giacomo, Aniello Murano and Sasha Rubin
	POMHDP: Search-based Belief Space Planning using Multiple Heuristics	Sung-Kyun Kim, Oren Salzman and Maxim Likhachev		Learning Interpretable Models Expressed in Linear Temporal Logic	Alberto Camacho and Sheila A. McIlraith
	An Exact Algorithm to make a Trade-off between Cost and Probability in SSPs	Valdinei Freire, Karina Valdivia Delgado and Willy Arthur Silva Reis		Towards a Unified View of AI Planning and Reactive Synthesis	Alberto Camacho, Meghyn Bienvenu and Sheila A. McIlraith
	Discovery of Optimal Solution Horizons in Non-Stationary Markov Decision Processes with Unbounded Rewards	Grigory Neustroev, Mathijs de Weerdt and Remco Verzijlbergh		Replanning for Situated Robots	Michael Cashmore, Andrew Coles, Bence Cserna, Erez Karpas, Daniele Magazzeni and Wheeler Ruml
				Temporal Planning as Refinement-Based Model Checking	Alexander Heinz, Martin Wehrle, Sergiy Bogomolov, Daniele Magazzeni, Marius Greitschus and Andreas Podelski	Short Paper
12.30-14.00	Lunch				
14.00-15.30	3a: Search	Chair: Erez Karpas		3b: Reinforcement Learning	Chair: Alan Fern
	On the Pathological Search Behavior of Distributed Greedy Best First Search	Ryo Kuroiwa and Alex Fukunaga		Foundations for Restraining Bolts: Reinforcement Learning with LTLf/LDLf restraining specifications	Giuseppe De Giacomo, Marco Favorito, Luca Iocchi and Fabio Patrizi
	Symbolic Planning with Axioms	David Speck, Florian Geißer, Robert Mattmüller and Álvaro Torralba		Deep Policies for Width-Based Planning in Pixel Domains	Miquel Junyent, Anders Jonsson and Vicenç Gómez
	Bridging the Gap Between Abstractions and Critical-Path Heuristics via Hypergraphs	Marcel Steinmetz and Álvaro Torralba		Resource Constrained Deep Reinforcement Learning	Abhinav Bhatia, Pradeep Varakantham and Akshat Kumar
	T-REX: SAT-based Tree Exploration for Efficient and High-Quality HTN Planning	Dominik Schreiber, Tomáš Balyo, Damien Pellier and Humbert Fiorino		Learning Classical Planning Strategies with Policy Gradient	Pawel Gomoluch, Dalal Alrajeh and Alessandra Russo
	Solving Graph Problems in Euclidean Space Using FastMap	Jiaoyang Li, Ariel Felner, Sven Koenig and T. K. Satish Kumar	Short Paper	Size-Independent Neural Transfer for RDDL Planning	Sankalp Garg, Aniket Bajpai and Mausam	Short Paper
15.30-15.50	Coffee break				
15.50-17.40	4a & 5a: Invited Industry Session	Chair: Siddharth Srivastava		4b: Hybrid Planning & Algorithm Selectio	Chair: Pascal Bercher
	Large Scale Analysis of Satellite Imagery and Other Geospatial Data	James Crawford (Orbital Insight)		Combined time and energy optimal trajectory planning with quadratic drag for mixed discrete-continuous task planning	Ayal Taitler, Ilya Ioslovich, Per-Olof Gutman and Erez Karpas	Journal Paper
	Planning for Transportation Influence and Other Problems	Matthew Klenk (PARC)		Algorithm Selection in Optimization and Application to Angry Birds	Shahaf S. Shperberg, Avinoam Yehezkel and Solomon Eyal Shimony	
	TBA	Richa Varma (United Technologies Research Center)		5b: Complexity (16.40-17.40)	Chair: Malte Helmert	
	TBA	Stefan Witwicki (Alliance Innovation Lab Silicon Valley, Renault-Nissan-Mitsubishi)		Eliminating Redundant Actions in Partially Ordered Plans -- A Complexity Analysis	Conny Olz and Pascal Bercher	
	Balancing Search and Optimization in a Self-Driving Car	Omer Baror (Waymo)		On Computational Complexity of Automorphism Groups in Classical Planning	Alexander Shleyfman	
	High-level decision making and planning using large-scale data	Sammy Omari (Lyft)		On the Relation between Star-Topology Decoupling and Petri Net Unfolding	Daniel Gnad and Joerg Hoffmann	
18.00-20.00	Poster and Demo Session				

Sunday 14th

8.30-9.30	Invited talk: J. Christopher Beck					
9.40-10.40	6a: Multi-Agent Planning	Chair: Tathagata Chakraborti		6b: Knowledge Engineering and Executio	Chair: Daniele Magazzini	
	Best-First Width Search for Multi Agent Privacy-preserving Planning	Alfonso E. Gerevini, Nir Lipovetzky, Francesco Percassi, Alessandro Saetti and Ivan Serina		PLASP 3: Towards Effective ASP Planning	Yannis Dimopoulos, Martin Gebser, Patrick Lühne, Javier Romero and Torsten Schaub	Journal Paper
	A Factored Approach to Contingent Multi-Agent Planning	Michal Štolba, Daniel Fišer and Antonín Komenda		On Compiling Away PDDL3 Qualitative Preferences without Using Automata	Francesco Percassi and Alfonso Emilio Gerevini	
	Privacy Leakage of Search-based Multi-Agent Planning Algorithms	Shashank Shekhar, Ronen Brafman and Guy Shani		Goal Reasoning in a CLIPS-based Executive for Integrated Planning and Execution	Tim Niemueller, Till Hofmann and Gerhard Lakemeyer	
10.40-11.00	Coffee break					
11.00-12.30	7a: Optimal & Oversubscription Planning	Chair: Joerg Hoffman		7b: Scheduling under Uncertainty	Chair: Steve Chien	
	Subset Saturated Cost Partitioning for Optimal Classical Planning	Jendrik Seipp and Malte Helmert		Tabu-Based Large Neighbourhood Search for Time/Sequence-Dependent Scheduling Problems with Time Windows	Lei He, Mathijs de Weerdt and Neil Yorke-Smith	
	Counterexample-Guided Abstraction Refinement for Pattern Selection in Optimal Classical Planning	Alexander Rovner, Silvan Sievers and Malte Helmert	Short Paper	Quantifying Degrees of Controllability in Temporal Networks with Uncertainty	Shyan Akmal, Savana Ammons, Maggie Li and Jim Boerkoel	Honorable Mention - Best Student Paper Award
	An Empirical Study of Perfect Potential Heuristics	Augusto B. Corrêa and Florian Pommerening	Short Paper	Propagating Piecewise-Linear Weights in Temporal Networks	Luke Hunsberger and Roberto Posenato	
	Lagrangian Decomposition for Optimal Cost Partitioning	Florian Pommerening, Gabriele Röger, Malte Helmert, Hadrien Cambazard, Louis-Martin Rousseau and Domenico Salvagnin	Best Paper Award	Measuring and Optimizing Durability Against Scheduling Disturbances	Joon Lee, Vivaswat Ojha and Jim Boerkoel	Short Paper
	Oversubscription Planning as Classical Planning with Multiple Cost Functions	Michael Katz, Emil Keyder, Florian Pommerening and Dominik Winterer		Reducing the Computational and Communication Overhead of Robust Agent Rescheduling	Jordan Abrahams, William Lloyd, Grace Diehl, Marina Knittel, Judy Lin, David Chu, Jeremy Frank and Jim Boerkoel	
12.30-14.00	Lunch					
14.00-15.30	8a: Recognition, Goal and Model Reasonir	Chair: Mark Roberts		8b: Applications I	Chair:	
	Foundations of Human-Aware Planning – A Tale of Three Models	Tathagata Chakraborti	Honorable Mention - Best Dissertation Award	ZAC: A Zone pAth Construction Approach for Effective Real Time Ride Sharing	Meghna Lowalekar, Pradeep Varakantham and Patrick Jaillet	UTRC Best Application Paper
	Model Recognition as Planning	Diego Aineto, Sergio Jiménez, Eva Onaindia and Miquel Ramírez		Reinforcement Learning Based Querying in Camera Networks for Efficient Target Tracking	Anil Sharma, Saket Anand and Sanjit Kaul	
	Explicability? Legibility? Predictability? Transparency? Privacy? Security? The Emerging Landscape of Interpretable Robot Behavior	Tathagata Chakraborti, Anagha Kulkarni, Sarath Sreedharan, David Smith and Subbarao Kambhampati		Optimizing Parameters for Uncertain Execution and Rescheduling Robustness	Wayne Chi, Jagriti Agrawal and Steve Chien	
	Efficient Heuristic Search for Optimal Environment Redesign	Sarah Keren, Luis Pineda, Avigdor Gal, Erez Karpas and Shlomo Zilberstein		Front delineation and tracking with multiple underwater vehicles	Andrew Branch, Mar M. Flexas, Brian Claus, Andrew F. Thompson, Yanwu Zhang, Evan B. Clark, Steve Chien, David M. Fratantoni, James C. Kinsey, Brett Hobson, Brian Kieft and Francisco P. Chavez	Journal Paper
	Finding Centroids and Minimum Covering States in Planning	Alberto Pozanco, Yolanda E-Martín, Susana Fernández and Daniel Borrajo	Short Paper			
15.30-15.50	Coffee break					
15.50-16.30	9a: Recognition II	Chair: Sarah Keren		9b: Robotics I	Chair: Alberto Finzi	
	Landmark-Enhanced Heuristics for Goal Recognition in Incomplete Domain Models	Ramon Fraga Pereira, André Grahl Pereira and Felipe Meneguzzi		POMDP-based Candy Server: Lessons Learned from a Seven Day Demo	Marcus Hoerger, Joshua Mun Liang Song, Hanna Kurniawati and Alberto Elfes	
	Error-Tolerant Anytime Approach for Plan Recognition using a Particle Filter	Jean Massardi, Mathieu Gravel and Éric Beaudry		Trajectory Tracking Control for Robotic Vehicles using Counterexample Guided Training of Neural Networks	Arthur Claviere, Souradeep Dutta and Sriram Sankaranarayanan	
16.40-18.30	Awards Session & Community Meeting					
19.00-21.00	Banquet					

Monday 15th

8.30-9.30	Invited talk: Derek Long				
9.40-10.40	10a: Probabilistic Planning II	Chair: Florent TeichTeil-Koenigsbuch		10b: Applications II	Chair:
	Online Risk-Bounded Motion Planning for Autonomous Vehicles in Dynamic Environments	Xin Huang, Sungkweon Hong, Andreas Hofmann and Brian Williams		Towards Automating Crime Prevention through Environmental Design (CPTED) Analysis to Predict Burglary	Leanne Monchuk, Simon Parkinson and James Kitchen
	A theoretical and algorithmic analysis of configurable MDPs	Rui Silva, Gabriele Farina, Francisco S. Melo and Manuela Veloso		The Clustered Dial-a-Ride Problem	Fabian Feitsch and Sabine Storandt
	Stochastic Planning with Lifted Symbolic Trajectory Optimization	Hao Cui, Thomas Keller and Roni Khardon		Mixed Integer Programming versus Evolutionary Computation for Optimizing a Hard Real-World Staff Assignment Problem	Jannik Peters, Daniel Stephan, Isabel Amon, Hans Gawendowicz, Julius Lischeid, Lennart Salabarria, Jonas Umland, Felix Werner, Martin S. Krejca, Ralf Rothenberger, Timo Kötzing and Tobias Friedrich
10.40-11.00	Coffee break				
11.00-12.30	11a: Learning	Chair: Alan Fern		11b: Constraint Reasoning and OR	Chair: Jeremy Frank
	Towards Stable Symbol Grounding with Zero-Suppressed State AutoEncoder	Masataro Asai and Hiroshi Kajino		Learning Scheduling Models from Event Data	Arik Senderovich, Kyle E. C. Booth and J. Christopher Beck
	Unsupervised Grounding of Plannable First-Order Logic Representation from Images	Masataro Asai		Efficiently Exploring Ordering Problems through Conflict-directed Search	Jingkai Chen, Cheng Fang, David Wang, Andrew Wang and Brian Williams
	Fast Feature Selection for Linear Value Function Approximation	Bahram Behzadian, Soheil Gharatappeh and Marek Petrik		Analysis of Backward Sequence in Cluster Tools with Processing Time Variations	Jun-Ho Lee and Hyun-Jung Kim	Short Paper
	Maximum Entropy based Independent Learning in Anonymous Multi-Agent Settings	Tanvi Verma, Pradeep Varakantham and Hoong Chuin Lau		An MDD-based Lagrangian Approach to the Multi-Commodity Pickup-and-Delivery TSP	Margarita Castro, Andre Augusto Cire and Chris Beck	Journal Paper
				A stochastic dual dynamic integer programming for the uncapacitated lot-sizing problem with uncertain demand and costs	Franco Quezada, Céline Gicquel and Safia Kedad-Sidhoum
12.30-14.00	Lunch				
14.00-15.30	12a: Path and Motion Planning	Chair: Sven Koenig		12b: Robotics II	Chair: Alberto Finzi
	Implicitly Coordinated Multi-Agent Path Finding under Destination Uncertainty: Success Guarantees and Computational Complexity	Bernhard Nebel, Thomas Bolander, Thorsten Engesser and Robert Mattmüller	Journal Paper	Open-world Reasoning for Service Robots	Yuqian Jiang, Nick Walker, Justin Hart and Peter Stone
	Lazy CBS: Implict Conflict-Based Search Using Lazy Clause Generation	Graeme Gange, Daniel Harabor and Peter J. Stuckey		Intruder Alert! Optimization Models for Solving the Mobile Robot Graph-Clear Problem	Michael Morin, Margarita Castro, Kyle Booth and Chris Beck	Journal Paper
	Improving the Combination of JPS and Geometric Containers	Yue Hu, Long Qin, Quanjun Yin, Daniel Harabor and Cong Hu	Short Paper	Provable Infinite-Horizon Real-Time Planning for Repetitive Tasks	Fahad Islam, Oren Salzman and Maxim Likhachev	
	Learning Heuristic for Mobile Robot Path Planning Using Deep Neural Network	Takeshi Takahashi, He Sun, Dong Tian and Yebin Wang		Speeding Up Search-based Motion Planning via Conservative Heuristics	Ishani Chatterjee, Maxim Likhachev, Ashwin Khadke and Manuela Veloso	Short Paper
	Generalized Lazy Search for Robot Motion Planning: Interleaving Search and Edge Evaluations via Event-based Toggles	Aditya Mandalika, Sanjiban Choudhury, Oren Salzman and Siddhartha Srinivasa	Best Student Paper Award	An Hierarchical Approach to Active Semantic Mapping Using Probabilistic Logic and Information Reward POMDP	Tiago Veiga, Miguel Silva, Rodrigo Ventura and Pedro U. Lima
15.30-15.50	Coffee break				
15.50-16.30	13a: Path Planning	Chair: Roman Bartak		13b: Transportation Scheduling	Chair:
	Cutting the Size of Compressed Path Databases With Wildcards and Redundant Symbols	Mattia Chiari, Shizhe Zhao, Adi Botea, Alfonso Gerevini, Daniel Harabor, Alessandro Saetti, Matteo Salvetti and Peter J. Stuckey		Approximate Gradient Descent Convergence Dynamics for Adaptive Control on Heterogeneous Networks	Jean Carpentier and Sebastien Blandin
	Disjoint Splitting for Conflict-Based Search for Multi-Agent Path Finding	Jiaoyang Li, Daniel Harabor, Peter Stuckey, Ariel Felner, Hang Ma and Sven Koenig	Short Paper	Using Bi-Directional Information Exchange to Improve Decentralized Schedule-Driven Traffic Control	Hsu-Chieh Hu and Stephen Smith
	A Multi-Label A* Algorithm for Multi-Agent Pathfinding	Florian Grenouilleau, Willem-Jan van Hoeve and J. N. Hooker	Short Paper		
16.40-17.40	14a: Applications III	Chair: Sara Bernardini		14b: Hybrid Planning	Chair: Christopher Beck
	Exact Methods for Extended Rotating Workforce Scheduling Problems	Lucas Kletzander, Nysret Musliu, Johannes Gärtner, Werner Schafhauser and Thomas Krennwallner		A Logical Semantics for PDDL+	Vitaliy Batusov and Mikhail Soutchanski
	Solution Approaches for an Automotive Paint Shop Scheduling Problem	Felix Winter, Emir Demirović, Nysret Musliu and Christoph Mrkvicka		Mixed Discrete Continuous Non-Linear Planning Through Piecewise Linear Approximation	Elad Denenberg and Amanda Coles
	Personalized Medication and Activity Planning in PDDL+	Fares K. Alaboud and Andrew Coles		Cyber-Physical Planning: Deliberation for Hybrid Systems with a Continuous Numeric State	Arthur Bit-Monnot, Luca Pulina and Armando Tacchella