

ISOMAP

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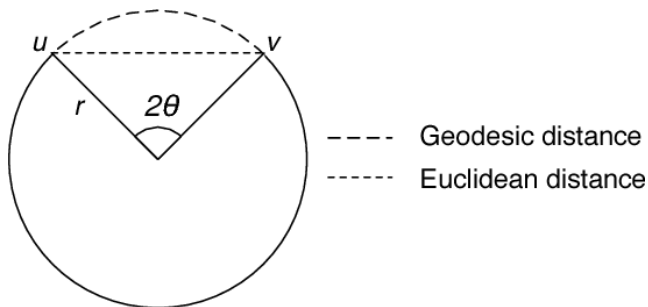
AMMI-Ghana

December 18, 2019

OUTLINE

- 1 The problem
- 2 Definition
- 3 Relationship with other methods
- 4 Isomap steps
- 5 Implementation
- 6 Pros/Cons

Problem??



Definitions

- **Euclidean distance** between points p and q is the length of the line segment connecting them denoted by \overline{pq} .
- In Cartesian coordinates, if $p = (p_1, p_2, \dots, p_n)$ and $q = (q_1, q_2, \dots, q_n)$ are two points in Euclidean n -space, by using **Pythagorean formula** one has:

$$d(p, q) = d(q, p) = \sqrt{\sum_{i=1}^n (q_i - p_i)^2}$$

- **The Euclidean norm**

$$\begin{aligned}\|p\| &= \sqrt{p_1^2 + p_2^2 + \dots + p_n^2} \\ &= \sqrt{p \cdot p}\end{aligned}$$

Geodesic distance

Is the length of the shortest curve between those two points along the surface like the earth

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- Stands for isometric mapping
- Is a non-linear dimensionality reduction method
- Preserve the geodesic distances in the lower dimension.
- If we measure the distance between two points by following the manifold, we will have a better approximation of how far or near two points are.

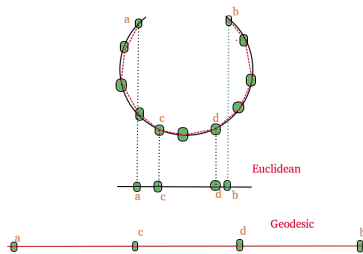


Figure: Isomap

How Isomap operates?

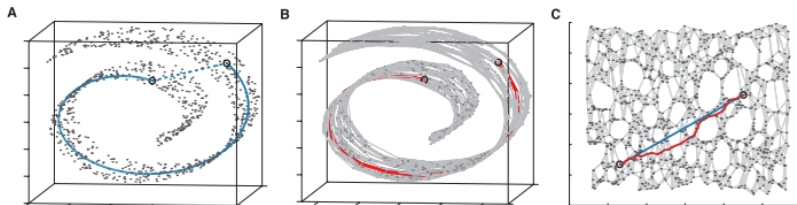


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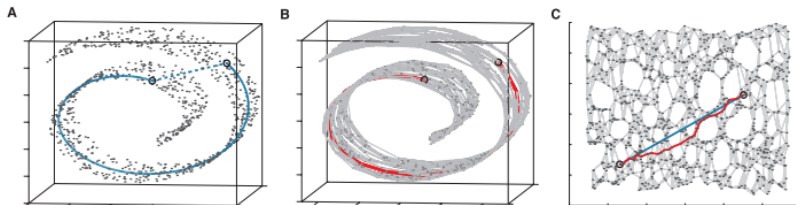


Figure: Isomap

- In A we see that two points that are close together in Euclidean Space in this “Swiss roll” dataset may not reflect the intrinsic similarity between these two points.

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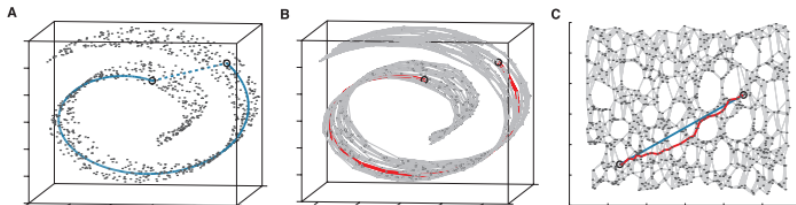


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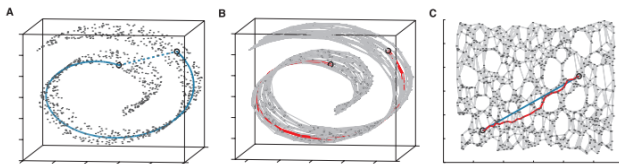


Figure: Isomap

- In B a graph is constructed with each point as n nearest neighbours. The shortest geodesic distance is then calculated by a path finding algorithm such as **Dijkstra's Shortest Path**.
- In C, this is the 2D graph is recovered from applying classical MDS (Multidimensional scaling) to the matrix of graph distances. A straight line has been applied to represent a simpler and cleaner approximation to the true geodesic path shown in A.

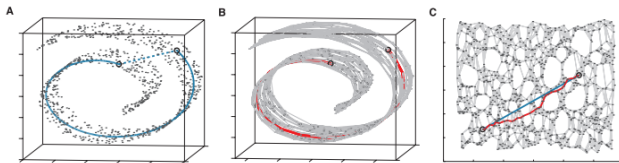


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- Isomap should be used when there is a non-linear mapping between your higher-dimensional data and your lower-dimensional manifold (e.g. data on a sphere).

The doubly centered geodesic distance matrix K in Isomap is of the form:

$$K = -\frac{1}{2}HD^2H$$

where $D^2 = D_{ij}^2 := (D_{ij})^2$ is the elementwise square of the geodesic distance matrix $D = [D_{ij}]$, H is the centering matrix, given by $H = I_n - \frac{1}{N}e_N e_N^T$ where $e_N = [1 \dots 1]^T \in \mathbb{R}^N$

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- Like PCA, compute the eigenvectors and the corresponding eigenvalues of the centered distance
- choose two principales components

Implementation

- Pros
 - Nonlinear
 - Non-iterative
 - Globally optimal

- Pros

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- Drawbacks

- Graph discreteness overestimates the geodesic distance
- K must be high to avoid linear shortcuts near regions of high surface curvature
- Isomap performs poorly when manifold is not well sampled and contains holes. As mentioned earlier neighborhood graph creation is tricky and slightly wrong parameters can produce bad results.

- <http://axon.cs.byu.edu/papers/gashler2007nips.pdf>
- <https://en.wikipedia.org/wiki/Isomap>
<https://blog.paperspace.com/dimension-reduction-with-isomap/>
- <http://benalexkeen.com/isomap-for-dimensionality-reduction-in-python/>
- <https://www.youtube.com/watch?v=RPjPLIGefzw>
- <https://www.quora.com/What-kind-of-datasets-is-ISOMAP-most-effective-on>