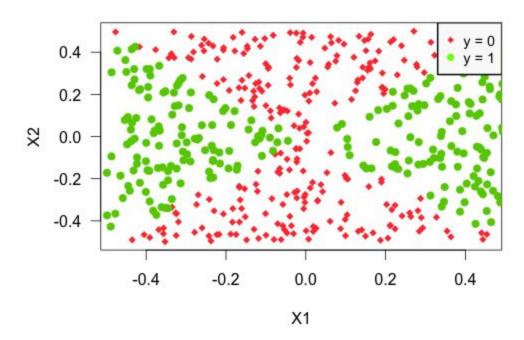
- 5. We have seen that we can fit an SVM with a non-linear kernel in order to perform classification using a nonlinear decision boundary. We will now see that we can also obtain a nonlinear decision boundary by performing logistic regression using nonlinear transformations of the features.
- (a) Generate a data set with n = 500 and p = 2, such that the observations belong to two classes with a quadratic decision boundary between them. For instance, you can do this as follows:

>
$$x1 = runif (500) -0.5$$

> $x2 = runif (500) -0.5$
> $y = 1*(x1 ^2 - x2 ^2 > 0)$

(b) Plot the observations, colored according to their class labels. Your plot should display X 1 on the x-axis, and X 2 on the y-axis.

Two classes with a quadratic decision boundary



(c) Fit a logistic regression model to the data, using X1 and X2 as predictors.

 $glm(formula = y \sim x1 + x2, family = "binomial")$

Deviance Residuals:

Min 1Q Median 3Q Max -1.179 -1.139 -1.112 1.206 1.257

Coefficients:

Estimate Std. Error z value Pr(>|z|)
(Intercept) -0.087260 0.089579 -0.974 0.330
x1 0.196199 0.316864 0.619 0.536
x2 -0.002854 0.305712 -0.009 0.993

(Dispersion parameter for binomial family taken to be 1) Null deviance: 692.18 on 499 degrees of freedom Residual deviance: 691.79 on 497 degrees of freedom

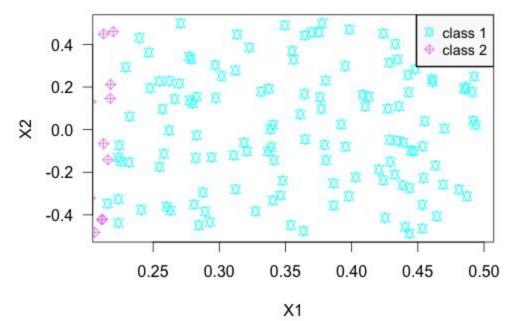
AIC: 697.79

Number of Fisher Scoring iterations: 3

The variables do not appear to have a significant relationship with the response variable.

(d) Apply this model to the training data in order to obtain a predicted class label for each training observation. Plot the observations, colored according to the predicted class labels. The decision boundary should be linear.

Observations classified by a logistic regression model



I used the probability threshold of .489 to produce two classes. The decision boundary seems linear and clear.

(e) Now fit a logistic regression model to the data using nonlinear functions of X1 and X2 as predictors (e.g. $X1^2$, $X1 \times X2$, log(X2), and so forth).

Call:

```
glm(formula = y \sim log2(x1) + poly(x2, 2) + l(x1 * x2), family = "binomial")
```

Deviance Residuals:

```
Min 1Q Median 3Q Max -1.98542 -0.06837 0.00753 0.09873 2.37857
```

Coefficients:

```
Estimate Std. Error z value Pr(>|z|)
(Intercept) 10.1540 1.9023 5.338 9.41e-08 ***
log2(x1) 4.8614 0.9048 5.373 7.75e-08 ***
poly(x2, 2)1 -41.0661 24.2062 -1.697 0.0898 .
poly(x2, 2)2 -104.6153 18.6898 -5.597 2.18e-08 ***
l(x1 * x2) 18.8225 10.5556 1.783 0.0746 .
---
```

Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

(Dispersion parameter for binomial family taken to be 1) Null deviance: 318.830 on 229 degrees of freedom Residual deviance: 65.559 on 225 degrees of freedom

(270 observations deleted due to missingness)

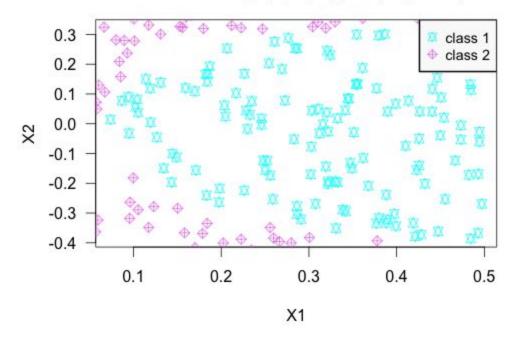
AIC: 75.559

Number of Fisher Scoring iterations: 8

I used log2(x1) + poly(x2, 2) + I(x1 * x2) as independent variables, and all of the relationships appear very significant.

(f) Apply this model to the training data in order to obtain a predicted class label for each training observation. Plot the observations, colored according to the predicted class labels. The decision boundary should be obviously non-linear. If it is not, then repeat (a)-(e) until you come up with an example in which the predicted class labels are obviously non-linear.

Observations classified by a logistic regression model with log2(x1) + poly(x2, 2) + I(x1 * x2)



The boundary is nonlinear, but does not resemble the original decision boundary.

(g) Fit a support vector classifier to the data with X1 and X2 as predictors. Obtain a class prediction for each training observation. Plot the observations, colored according to the predicted class labels.

Parameter tuning of 'svm':

- sampling method: 10-fold cross validation

best parameters:cost0.1

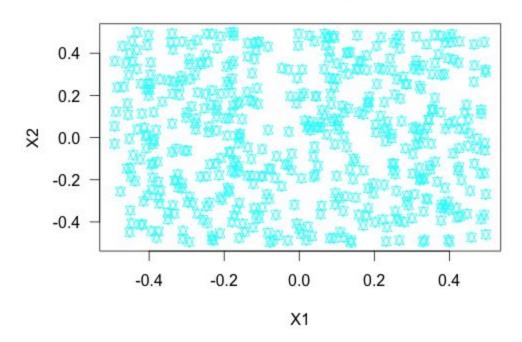
- best performance: 0.478

- Detailed performance results: cost error dispersion
- 1 1e-05 0.484 0.04599517
- 2 1e-04 0.484 0.04599517
- 3 1e-03 0.484 0.04599517
- 4 1e-02 0.484 0.04599517
- 5 1e-01 0.478 0.05996295

```
6 1e+00 0.492 0.03794733
7 1e+01 0.492 0.03794733
8 5e+01 0.492 0.03794733
9 1e+02 0.492 0.03794733
```

Best performance is close to other results and is a pretty high error rate. All the observations are classified into one and the same class.

Observations classified by an SVM model



(h) Fit a SVM using a non-linear kernel to the data. Obtain a class prediction for each training observation. Plot the observations, colored according to the predicted class labels.

Parameter tuning of 'svm':

- sampling method: 10-fold cross validation
- best parameters:

cost

50

- best performance: 0.022

- Detailed performance results: cost error dispersion

1 1e-05 0.456 0.15770577

2 1e-04 0.456 0.15770577

3 1e-03 0.456 0.15770577

4 1e-02 0.456 0.15770577

5 1e-01 0.084 0.03502380

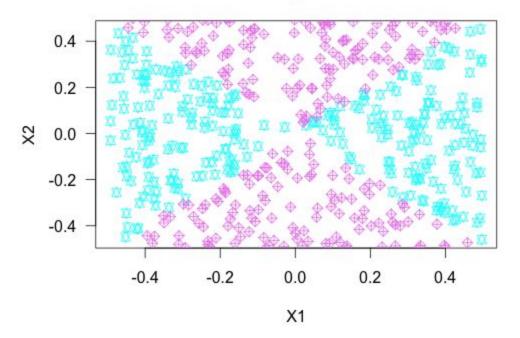
6 1e+00 0.056 0.02270585

7 1e+01 0.026 0.02674987

8 5e+01 0.022 0.01988858

9 1e+02 0.024 0.02065591

Observations classified by an SVM model using a non linear kernel



(i) Comment on your results.

The SVM model with non-linear kernel produced the best result. With the help of the tune() function, I was able to quickly find out the best tuning parameter from a range of parameters.