Quantum Molecular Dynamics: Representation & Solution

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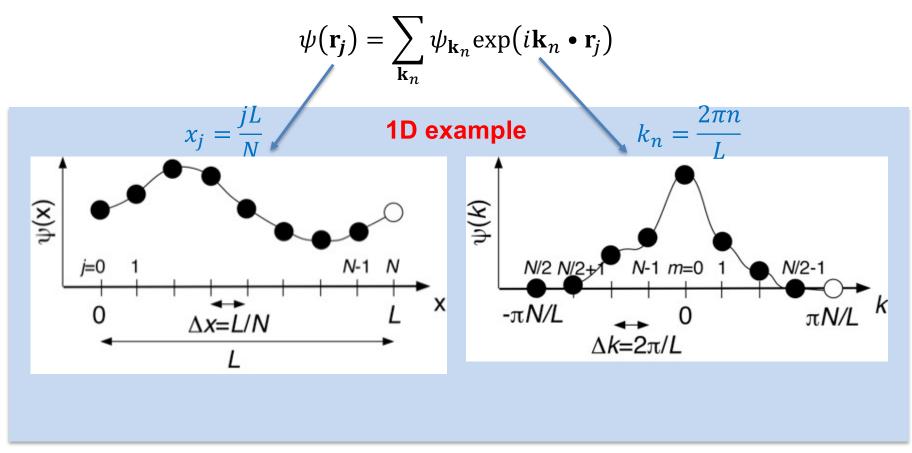
How to represent & solve Kohn-Sham equations in QMD?





Representation: Plane-Wave Basis

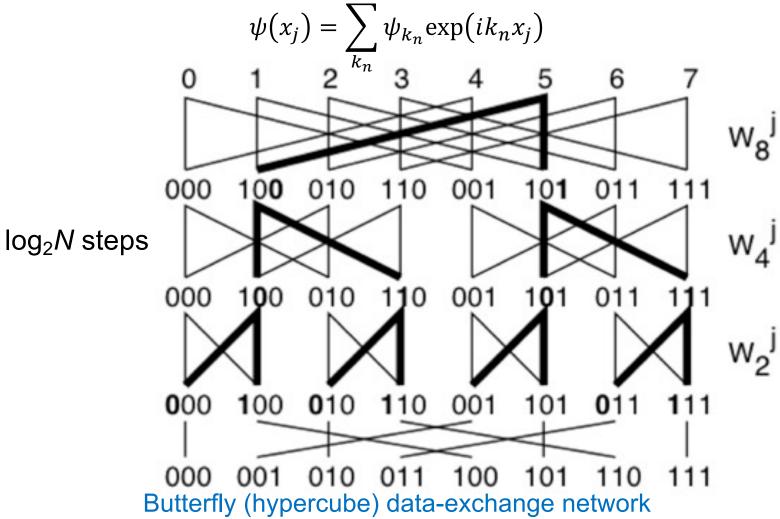
• Pseudopotentials result in slowly varying wave functions that can be represented on a regular grid, which in turn can be represented as a linear combination of plane waves, *i.e.*, Fourier transform



See "Fourier transform as a resolution of unity in a vector space" https://aiichironakano.github.io/phys516/03QD-slide.pdf

Numerics: Fast Fourier Transform

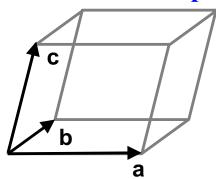
• O(NlogN) fast Fourier-transform (FFT) algorithm is typically used to perform Fourier transform



See "divide-&-conquer and FFT" https://aiichironakano.github.io/phys516/03QD-slide.pdf

Periodic Solid

Consider a periodic solid with the unit cell spanned by vectors a, b & c



Fourier transform of a periodic function

$$u(\mathbf{r}) = \sum_{\mathbf{G}} u_{\mathbf{G}} \exp(i\mathbf{G} \cdot \mathbf{r})$$

$$\mathbf{G} = \frac{2\pi}{\mathbf{a} \cdot (\mathbf{b} \times \mathbf{c})} [l(\mathbf{b} \times \mathbf{c}), m(\mathbf{c} \times \mathbf{a}), n(\mathbf{a} \times \mathbf{b})] \quad (l, m, n \in \mathbb{Z})$$

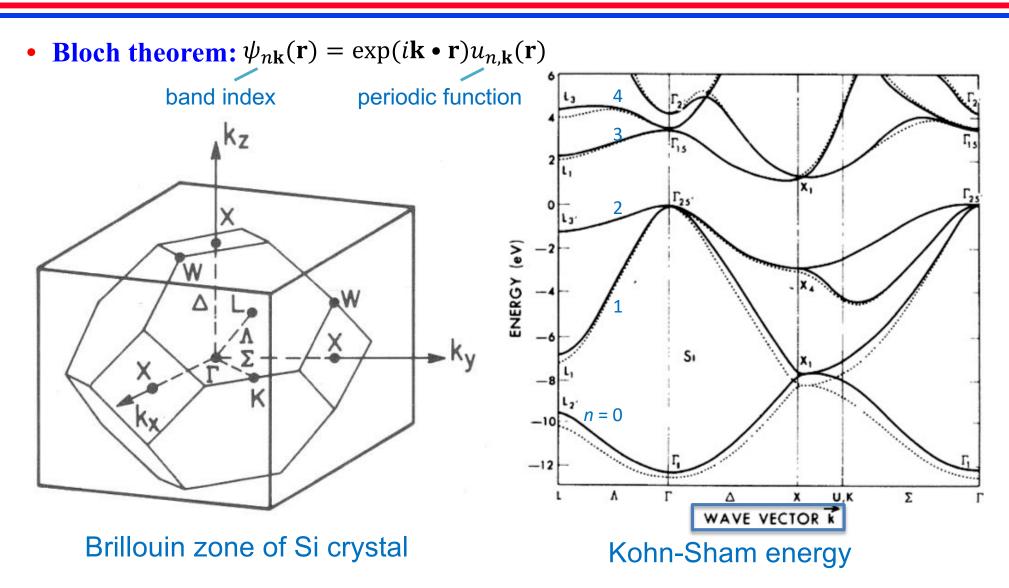
Bloch's theorem

n: band index
$$\psi_{n\mathbf{k}}(\mathbf{r}) = \exp(i\mathbf{k} \cdot \mathbf{r}) u_{n,\mathbf{k}}(\mathbf{r})$$

$$= \sum_{\mathbf{G}} u_{n,\mathbf{k}}(\mathbf{G}) \exp(i(\mathbf{k} + \mathbf{G}) \cdot \mathbf{r})$$

k ∈ first Brillouin zone in the reciprocal space

Electronic Bands: Infinite Lattice



J. R. Chelikowsky & M. L. Cohen, *Phys. Rev. B* 10, 5095 ('74)

See notes on (1) plane-wave basis & (2) supercell

QMD Algorithm

time t = 0 coordinates & velocities of atoms, $\{\vec{R}_I(t)\}, \{\vec{V}_I(t)\}$

minimize energy functional $E[\{\psi_n\}, \{\vec{R}_I(t)\}]$ by conjugate-gradient method

atomic force
$$\vec{F}_I(t) = -\frac{\partial E\left[\{\psi_n\}, \{\vec{R}_I(t)\}\right]}{\partial \vec{R}_I(t)}$$
 Hellmann-Feynman theorem

new coordinates and velocities of atoms at time $t + \Delta t$

$$\{\vec{R}_I(t+\Delta t)\},\{\vec{V}_I(t+\Delta t)\}$$

by integrating Newton's equations of motion

$$M_I \frac{d^2 \vec{R}_I(t)}{dt^2} = \vec{F}_I(t)$$

$$t \leftarrow t + \Delta t$$

Molecular Dynamics Modes

QXMD software supports various **MD** modes

Use gradient & Hessian information

- Structural optimization, *e.g.*, quasi-Newton method, see https://aiichironakano.github.io/phys760/MNK.pdf
 - > Relax atomic positions $\{\mathbf{R}_I\}$ to minimize the energy $\{\mathbf{R}_I^*\} = \operatorname{argmin}_{\{\mathbf{R}_I\}} \left(\min_{\{\psi_n(\mathbf{r})\}} E[\{\psi_n(\mathbf{r})\}, \{\mathbf{R}_I\}] \right)$
- Molecular dynamics
 - > Follow atomic trajectories by numerically integrating Newton's second law of motion

$$M \frac{d^2}{dt^2} \mathbf{R}_I = -\left\langle \Psi_0 \middle| \frac{\partial h(\mathbf{r}, \mathbf{R}(t), t)}{\partial \mathbf{R}(t)} \middle| \Psi_0 \right\rangle$$

> Microcanonical (NVE), canonical (NVT) & isobaric (NPT) ensembles are supported

Martyna et al., Mol. Phys. 87, 1117 ('96)

For classical molecular dynamics (e.g., velocity Verlet algorithm), see PHYS 516 (Methods of Computational Physics, https://aiichironakano.github.io/phys516/02MD-slide.pdf) & MASC 575 (Basics of Atomistic Simulation of Materials)

Self-Consistent Field Iteration

$$\left(-\frac{\hbar^2}{2m}\frac{\partial^2}{\partial \mathbf{r}^2} + \hat{V}_{\text{ion}} + \hat{V}_{\text{H,xc}}[\rho(\mathbf{r})]\right)\psi_n(\mathbf{r}) = \epsilon_n\psi_n(\mathbf{r})$$

Given $\rho(\mathbf{r})$, iteratively obtain $\{\psi_n, \epsilon_n\}$, e.g., by preconditioned conjugate gradient

Given $\{\psi_n, \epsilon_n\}$, determine μ and compute $\rho(\mathbf{r})$

$$\rho(\mathbf{r}) = \sum_{n} |\psi_n(\mathbf{r})|^2 \Theta(\mu - \epsilon_n)$$

Chemical potential

$$N = \int d\mathbf{r} \rho(\mathbf{r})$$

Self-Consistent Field Iteration

initial wave function $\{\psi_n | n = 1, ..., N_{band}\}$ & charge ρ

solve $\nabla^2 V_{\text{Hartree}}(\vec{x}) = -4\pi e^2 \rho(\vec{x})$ set up the electronic potential, $V = V_{\text{ion}} + V_{\text{Hartree}} + V_{\text{xc}}$

subspace diagonalization

unitary transformation to diagonalize $\int d^3 x \psi_m(\vec{x}) \left\{ -\frac{\hbar^2}{2m} \nabla^2 + V(\vec{x}) \right\} \psi_n(\vec{x})$

preconditioned conjugate gradient Gram-Schmidt or Cholesky

iterative improvement of $\{\psi_n\}$ & orthonormalization

calculate new ρ from updated $\{\psi_n\}$

if not converged

Orthogonalization by Matrix Decomposition

• Gram-Schmidt orthonormalization: The orthonormal basis set $Q = [q_1...q_m]$ is obtained starting from an arbitrary set of m vectors, $S = [s_1...s_m]$ as

$$\mathbf{q}_{1} = \mathbf{s}_{1} / |\mathbf{s}_{1}|$$
for $i = 2$ to m

$$\mathbf{q}'_{i} = \mathbf{s}_{i} - \sum_{j=1}^{i-1} \mathbf{q}_{j} (\mathbf{q}_{j} \cdot \mathbf{s}_{i}) \text{ Projection!}$$

$$\mathbf{q}_{i} = \mathbf{q}'_{i} / |\mathbf{q}'_{i}| \qquad \qquad \sum_{j=1}^{i-1} |\mathbf{q}_{j}\rangle \langle q_{j}|$$
endfor

• The Gram-Schmidt procedure amounts to QR decomposition, S = QR, where R is an $m \times m$ right-triangle matrix

$$n \begin{bmatrix} \mathbf{s}_{1} & \mathbf{s}_{2} & \mathbf{s}_{3} & \mathbf{s}_{4} \end{bmatrix} = n \begin{bmatrix} \mathbf{q}_{1} & \mathbf{q}_{2} & \mathbf{q}_{3} & \mathbf{q}_{4} \end{bmatrix} \begin{bmatrix} |\mathbf{q}_{1}'| & \mathbf{q}_{1} \cdot \mathbf{s}_{2} & \mathbf{q}_{1} \cdot \mathbf{s}_{3} & \mathbf{q}_{1} \cdot \mathbf{s}_{4} \\ 0 & |\mathbf{q}_{2}'| & \mathbf{q}_{2} \cdot \mathbf{s}_{3} & \mathbf{q}_{2} \cdot \mathbf{s}_{4} \\ 0 & 0 & |\mathbf{q}_{3}'| & \mathbf{q}_{3} \cdot \mathbf{s}_{4} \\ 0 & 0 & 0 & |\mathbf{q}_{4}'| \end{bmatrix} m$$

$$\mathbf{s}_i = |\mathbf{q}_i'|\mathbf{q}_i + \sum_{j=1}^{i-1} \mathbf{q}_j(\mathbf{q}_j \cdot \mathbf{s}_i)$$
Hasegawa et al., SC ('11)

• For higher parallelization, Cholesky decomposition (BLAS3) is used instead https://aiichironakano.github.io/phys516/Cholesky.pdf

Charge Mixing

- Fixed-point charge mapping in self-consistent field iteration $\rho_{\text{in}}(\mathbf{r}) \mapsto v_{\text{Hxc}}(\mathbf{r}) \mapsto \{\psi_n(\mathbf{r})\} \mapsto \rho_{\text{out}}(\mathbf{r})$
- Directly using $\rho_{out}(\mathbf{r})$ as $\rho_{in}(\mathbf{r})$ in the next iteration step often destabilizes numerical iteration
- Charge mixing

$$\rho_{\text{in}}^i \leftarrow \sum_{j=1}^n \alpha_i \, \rho_{\text{in}}^{i-j}$$

- Determine the mixing coefficients α_i in order to minimize the residual $R[\rho_{\rm in}(\mathbf{r})] \equiv \rho_{\rm out}[\rho_{\rm in}] \rho_{\rm in}$
- See note on Pulay charge mixing

Conjugate-Gradient Minimization of Energy Functional

i: iteration index; *n*: band index

"gradient"
$$g_n^{(i)} = -\frac{\delta E\left[\left\{\psi_n^{(i)}\right\}, \left\{\vec{R}_l(t)\right\}\right]}{\delta \psi_n^{(i)}} + \varepsilon_n^{(i)} \psi_n^{(i)} \equiv -H \psi_n^{(i)} + \varepsilon_n^{(i)} \psi_n^{(i)}$$

$$\varepsilon_n^{(i)} = \int d^3 r \psi_n^{(i)*} H \psi_n^{(i)}$$
"preconditioning" $\tilde{g}_n^{(i)} = \hat{P} g_n^{(i)}$

"conjugate gradient" $h_n^{(i)} = \tilde{g}_n^{(i)} + \beta h_n^{(i-1)}, \beta = \int d^3 r g_n^{(i)} \cdot g_n^{(i)} / \int d^3 r g_n^{(i-1)} \cdot g_n^{(i-1)}$
"new wave function" $\psi_n^{(i+1)} = C(\lambda) \left(\psi_n^{(i)} + \lambda h_n^{(i)}\right)$
with constraint $\int d^3 r \psi_n^{(i+1)*} \psi_m = 0 \ (m \le n)$

$$i \leftarrow i+1 \qquad \text{if } \left|\varepsilon_n^{(i+1)} - \varepsilon_n^{(i)}\right| > \varepsilon$$

See lecture on iterative minimization (https://aiichironakano.github.io/phys516/QD2CG.pdf) & notes on (1) conjugate-gradient (CG) method, (2) CG electronic-state solver, (3) CG DFT solver & (4) 2D electron example

Real-Space Grid as a Basis

- Wave functions & electron density are represented by numerical values on real-space grid points
- Finite difference expansion for the kinetic-energy operator

$$\left. \frac{\partial^2 \psi_n}{\partial x^2} \right|_{\mathbf{r}_{ijk} = (x_i, y_j, z_k)} = \sum_{l=-L}^{L} C_l \psi_n(x_i + lh, y_j, z_k) + O(h^{2L+2})$$

(short-ranged operation)

The calculations are performed completely in "real space"



- Suitable for systems with vacuum (e.g., clusters, surfaces)
- Efficient implementation on parallel computers

Acceleration of Convergence

Preconditioning

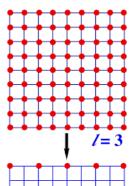
 $(H - \varepsilon)(\psi + \delta) = 0$

approximately

Enhanced convergence rate of short $\frac{-)(H-\varepsilon)\psi = -g}{(H-\varepsilon)\delta = g} \quad \text{invert?}$ $\delta \leftarrow (H-\varepsilon)^{-1}g$ wavelength components of the residual

$$\delta \leftarrow (H - \varepsilon)^{-1} g$$

$$\begin{split} \tilde{g}_n \big(x_i, y_j, z_k \big) &= \hat{P} g_n^{(i)} \\ &= \sum_{l_1 = -1}^1 \sum_{l_2 = -1}^1 \sum_{l_3 = -1}^1 c_{l_1 l_2 l_3} g_n \big(x_i + l_1 h, y_j + l_2 h, z_k + l_3 h \big) \end{split}$$

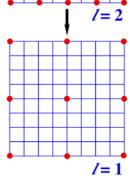


Multigrid method [Brandt '77, Bernholc et al. '96, Beck, '00]

To reduce long wavelength components of the residual,

$$\left(-\frac{\hbar^2}{2m}\nabla^2 + V\right)\varphi = g_n^{(i)}$$
$$\psi_n^{(i)} \leftarrow \psi_n^{(i)} + \varphi$$

on a coarse grid



Iterative Solution of Linear Systems

Fixed-point equation

$$x = D^{-1}[-(L+U)x + b]$$

Jacobi iteration

$$x^{(n+1)} = D^{-1}[-(L+U)x^{(n)} + b]$$

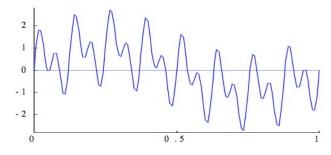
$$x_i^{(n+1)} = \frac{1}{a_{ii}} \begin{pmatrix} \sum_{j=1}^{N} a_{ij} x_j^{(n)} + b_i \\ j=1 \\ (j \neq i) \end{pmatrix}$$

Over (under) relaxation: $\Delta > 1$ ($\Delta < 1$)

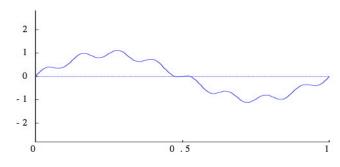
$$x_i^{(n+1)} = \frac{1}{a_{ii}} \left(-\sum_{\substack{j=1\\(j\neq i)}}^{N} a_{ij} x_j^{(n)} + b_i \right)$$

$$= x_i^{(n)} + \frac{1}{a_{ii}} \left(-\sum_{j=1}^{N} a_{ij} x_j^{(n)} + b_i \right) \rightarrow x_i^{(n)} + \frac{\Delta}{a_{ii}} \left(-\sum_{j=1}^{N} a_{ij} x_j^{(n)} + b_i \right)$$

· Initial error:

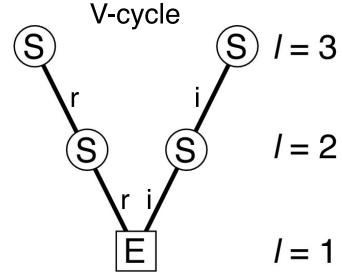


Error after 35 iteration sweeps:

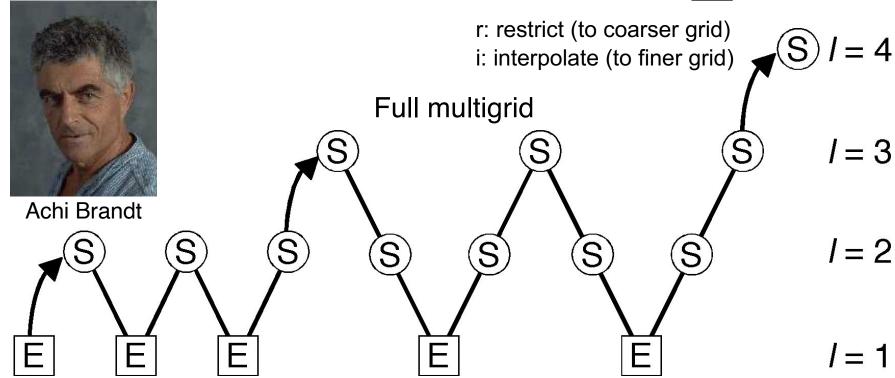


Multigrid Method

- Residual equation: $A^{(l)}(\psi + e) = 0$ $\frac{-)A^{(l)}\psi = r}{A^{(l)}e = -r}$
- Smoothing: $e \leftarrow [1 + Z^{(l)}A^{(l)}]e + Z^{(l)}r$

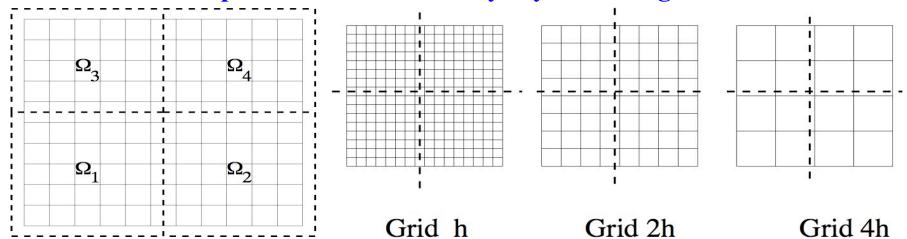


• Coarsening of residual & interpolation of error



Parallel Multigrid Method

Domain decomposition with boundary-layer caching



• 2D computational & communication costs (isogranular or weak scaling)

 $N \times N$ grids each on $P \times P$ processors: $T(N^2P^2, P^2) = a \log NP + bN + cN^2$

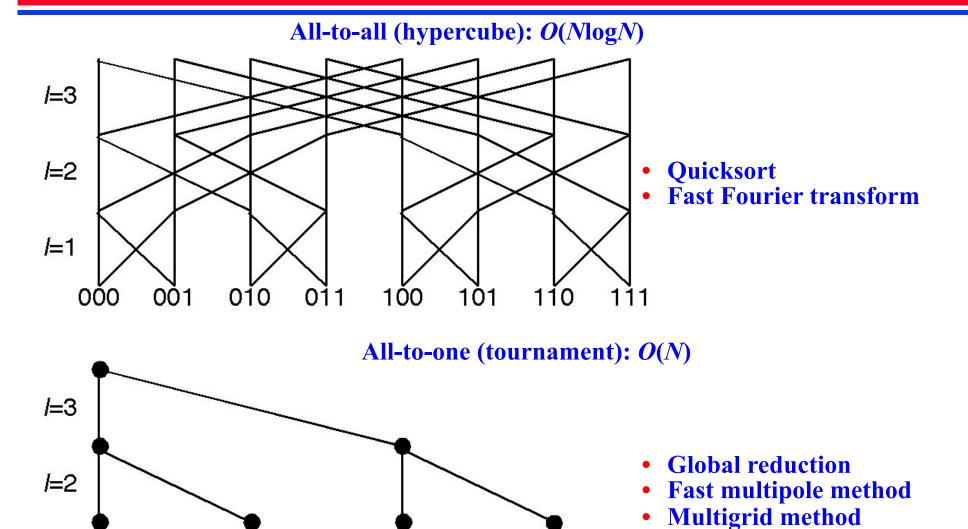
Speedup
$$S_{P^2} = \frac{N^2 P^2 T(N^2,1)}{N^2 T(N^2,P^2)} = \frac{P^2 \left(cN^2\right)}{a \log NP + bN + cN^2} = \frac{P^2}{1 + \frac{b}{cN} + \frac{a}{cN} \log NP}$$

Parallel efficiency $E_{P^2} = \frac{S_{P^2}}{P^2} = \frac{1}{1 + \frac{b}{cN} + \frac{a}{cN} \log NP}$ Highly scalable!

Nakano et al., Comput. Phys. Commun. 83, 181 ('94)

For the definition of parallel efficiency, see https://aiichironakano.github.io/cs596/MPI-Pi.pdf

Global Communications



l=1

See note on multigrid preconditioned CG

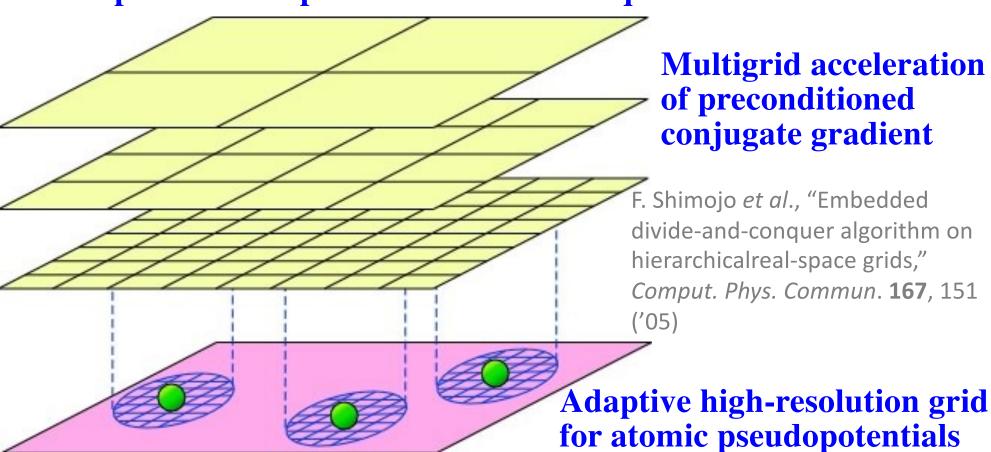
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Wavelets

Real-Space DFT on Hierarchical Grids

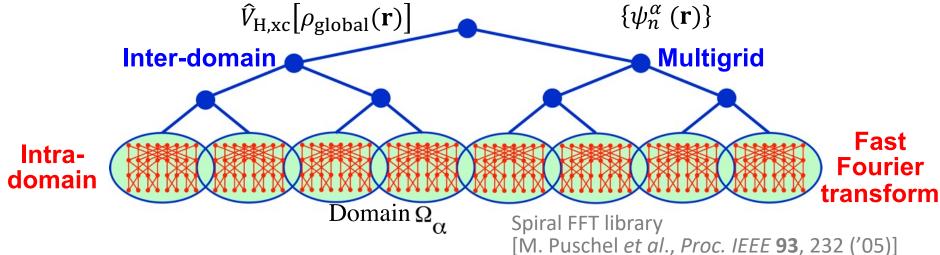
Efficient parallelization of DFT: real-space approaches

- High-order finite difference [Chelikowsky, Troullier, Saad, '94]
- Multigrid acceleration [Bernholc et al., '96; Beck, '00]
- Double-grid method [Ono, Hirose, '99] ~ obsolete, with PAW
- Spatial decomposition/divide-&-conquer



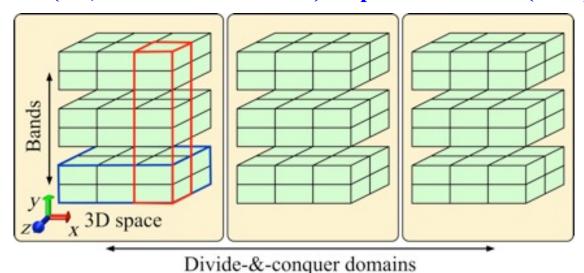
Hierarchical Computing

• Globally scalable (real-space multigrid) + locally fast (plane wave) electronic solver

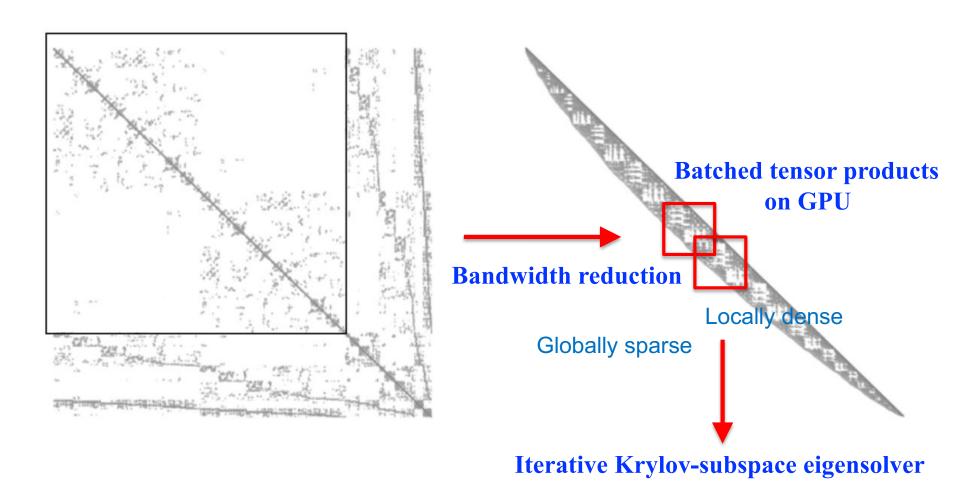


cf. globally- sparse-yet-locally-dense eigensolver [J. H. Lam et al., Nature Commun. 15, 3479 ('24)]

• Hierarchical band (i.e., Kohn-Sham orbital) + space + domain (BSD) decomposition



Globally-Sparse Yet Locally-Dense Eigensolver



 250-fold speed-up over state-of-the-art for 2.4M atom molecular vibrational modes

J. H. Lam et al., Nature Commun. 15, 3479 ('24)

Finite-Element DFT

- DFT calculation using a higher-order adaptive spectral finite-element (FE) basis outperforms that with the plane-wave basis for larger (e.g., > 10,000 electrons) systems: see DFT-FE code [S. Das et al., Comput. Phys. Commun. 280, 108473 ('22); https://github.com/dftfeDevelopers/dftfe]
- 2023 Gordon-Bell award: 659.7 Pflop/s (43.1% of the peak) by the DFT-FE code for 619,124 electrons on 8,000 GPU nodes of the Frontier supercomputer [S. Das et al., Proc. Supercomputing, SC ('23)]

