# Hybrid MPI+OpenMP+CUDA Programming

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Objective: Hands-on experience in MPI+OpenMP+CUDA programming for hybrid parallel computing on a cluster of GPU-accelerated multicore computing nodes

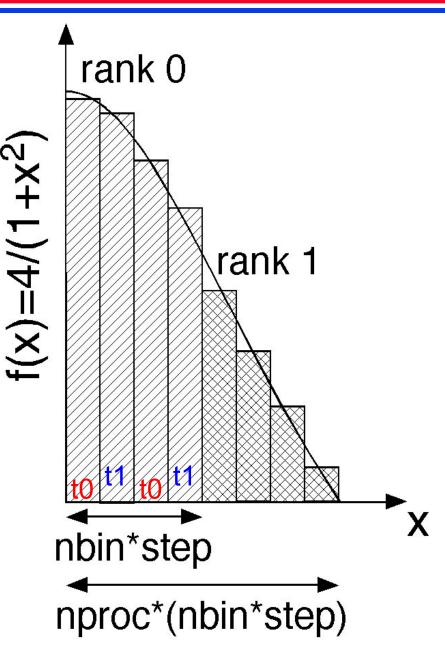




#### MPI+CUDA Calculation of $\pi$

- Spatial decomposition by offset: Each MPI process integrates over a range of width 1/nproc, as a discrete sum of nbin bins each of width step
- Interleaving by skipping indices: Within each MPI process, NUM\_BLOCK\*NUM\_THREAD CUDA threads perform part of the sum

$$\pi = \int_0^1 \frac{4}{1+x^2} dx \cong \Delta \sum_{i=0}^{N-1} \frac{4}{1+x_i^2}$$



cf. Hybrid MPI+OpenMP program, https://aiichironakano.github.io/cs653/src/parallel/hpi.c

## Calculate Pi with MPI+CUDA: hypi.cu (1)

```
#include <stdio.h>
                                              Difference from base pi.cu program in red
#include <mpi.h>
#include <cuda.h>
#define NBIN 10000000 // Number of bins
#define NUM BLOCK
                   13 // Number of thread blocks
#define NUM THREAD 192 // Number of threads per block
// Kernel that executes on the CUDA device
 global void cal pi(float *sum,int nbin,float step,float offset,int nthreads,int nblocks)
  int i;
  float x;
                                                  Sequential thread index across blocks
  int idx = blockIdx.x*blockDim.x+threadIdx.x;
  for (i=idx; i< nbin; i+=nthreads*nblocks) {</pre>
                                               // Interleaved bin assignment to threads
     x = offset+(i+0.5)*step;
     sum[idx] += 4.0/(1.0+x*x);
                                     rank 0
}
                                            rank 1
MPI spatial decomposition
                                                       CUDA thread interleaving
 via offset (how many bins
                                                       (give way bins to the other
have been computed before
                                                     x threads)
                                    nbin*step
me?)
                                    nproc*(nbin*step)
```

cf. Kernel in https://aiichironakano.github.io/cs596/src/cuda/pi.cu

## Calculate Pi with MPI+CUDA: hypi.cu (2)

```
int main(int argc,char **argv) {
                                      Difference from base pi.cu program in red
  int myid, nproc, nbin, tid;
  float step, offset, pi=0.0, pig;
  dim3 dimGrid(NUM BLOCK,1,1); // Grid dimensions (only use 1D)
  dim3 dimBlock(NUM THREAD, 1, 1); // Block dimensions (only use 1D)
  float *sumHost, *sumDev; // Pointers to host & device arrays
  MPI Init(&argc,&argv);
  MPI_Comm_rank(MPI_COMM WORLD, &myid); // My MPI rank
  MPI Comm size(MPI COMM WORLD, &nproc); // Number of MPI processes
  nbin = NBIN/nproc; // Number of bins per MPI process
  step = 1.0/(float)(nbin*nproc); // Step size with redefined number of bins
  offset = myid*step*nbin; // Quadrature-point offset
  size t size = NUM BLOCK*NUM THREAD*sizeof(float); //Array memory size
  sumHost = (float *)malloc(size); // Allocate array on host
  cudaMalloc((void **) &sumDev,size); // Allocate array on device
  cudaMemset(sumDev,0,size); // Reset array in device to 0
  // Calculate on device (call CUDA kernel)
  cal pi <<<dimGrid,dimBlock>>> (sumDev, nbin, step, offset, NUM THREAD, NUM BLOCK);
  // Retrieve result from device and store it in host array
  cudaMemcpy(sumHost,sumDev,size,cudaMemcpyDeviceToHost);
  // Reduction over CUDA threads
  for(tid=0; tid<NUM THREAD*NUM BLOCK; tid++) pi += sumHost[tid];</pre>
  pi *= step;
  // CUDA cleanup
                                 nbin per MPI rank instead of total NBIN in pi.cu
  free(sumHost);
  cudaFree(sumDev);
  printf("myid = %d: partial pi = %f\n",myid,pi);
  // Reduction over MPI processes
  MPI Allreduce(&pi,&pig,1,MPI FLOAT,MPI SUM,MPI COMM WORLD);
  if (myid==0) printf("PI = %f\n",pig);
  MPI Finalize();
  return 0;}
```

## **Compiling MPI+CUDA on Discovery**

• Set an environment (add the following lines in your .bashrc)

```
module purge
module load usc
module load cuda/10.1.243
```

• Compilation (this also works for MPI+OpenMP+CUDA programs) — this should be typed all in one line:

```
nvcc -Xcompiler -fopenmp hypi.cu -o hypi -
I${OPENMPI_ROOT}/include -L${OPENMPI_ROOT}/lib -lmpi -lgomp
```

This should be all in one line

## Running MPI+CUDA on Discovery

Submit the following Slurm script using the sbatch command

```
#!/bin/bash
#SBATCH --nodes=2
#SBATCH --ntasks-per-node=1
#SBATCH --cpus-per-task=1
#SBATCH --gres=gpu:1
#SBATCH --time=00:00:59
#SBATCH --output=hypi.out
#SBATCH -A anakano_429
mpirun -n 2 ./hypi
```

#### • Output

```
myid = 1: partial pi = 1.287001
myid = 0: partial pi = 1.854596
PI = 3.141597
```

## Variation: Using 2 GPUs per Node (1)

• Run multiple MPI processes on each node, and assign different GPUs to different processes

#### hypi\_setdevice.cu

```
int main(int argc,char **argv) {
  int dev_used;
  ...
  MPI_Comm_rank(MPI_COMM_WORLD,&myid); // My MPI rank
  cudaSetDevice(myid%2); // Pick one of the 2 GPUs (0 or 1)
  ...
  cudaGetDevice(&dev_used); // Find which GPU is being used
  printf("myid = %d: device used = %d; partial pi = %f\n",myid,dev_used,pi);
  ...
}
```

## Variation: Using 2 GPUs per Node (2)

Submit the following Slurm script using the sbatch command

```
#!/bin/bash
#SBATCH --nodes=2
#SBATCH --ntasks-per-node=2
#SBATCH --cpus-per-task=1
#SBATCH --gres=gpu:2
#SBATCH --time=00:00:59
#SBATCH --output=hypi_setdevice.out
#SBATCH -A anakano_429
mpirun -n 4 ./hypi setdevice
```

#### • Output

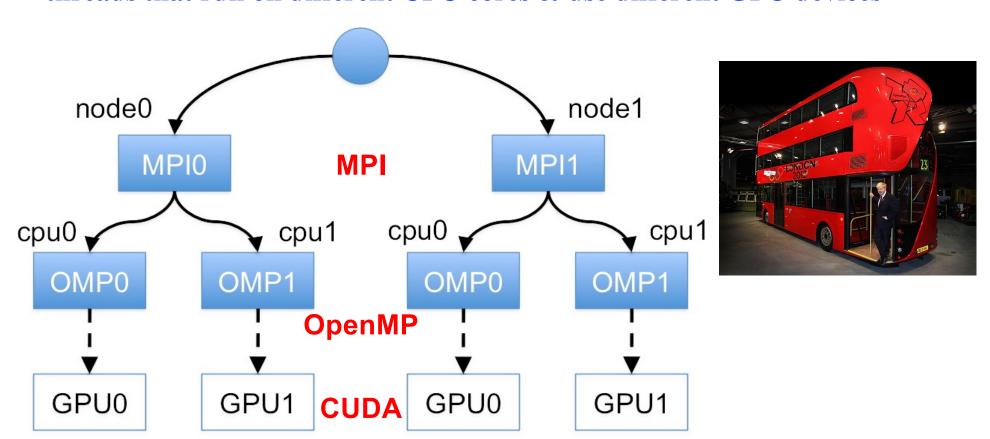
```
myid = 0: device used = 0; partial pi = 0.979926
myid = 1: device used = 1; partial pi = 0.874671
myid = 2: device used = 0; partial pi = 0.719409
myid = 3: device used = 1; partial pi = 0.567582
PI = 3.141588
```

**Problem:** What if ranks 0 & 2 are assigned to the same node → recommended to MPI+OpenMP+CUDA instead

https://carc.usc.edu/user-information/user-guides/hpc-basics/running-jobs https://carc.usc.edu/user-information/user-guides/hpc-basics/slurm-templates

## MPI+OpenMP+CUDA Computation of $\pi$

- Write a triple-decker MPI+OpenMP+CUDA program, pi3.cu, by inserting an OpenMP layer to the double-decker MPI+CUDA program, hypi\_setdevice.cu
- Launch one MPI rank per node, where each rank spawns two OpenMP threads that run on different CPU cores & use different GPU devices



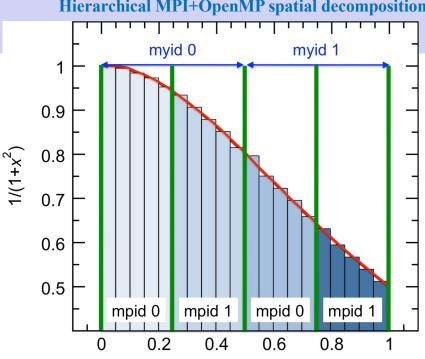
https://aiichironakano.github.io/cs653/src/parallel/hypi\_setdevice.cu

## **MPI+OpenMP Spatial Decompositions**

```
#include <omp.h>
#define NUM_DEVICE 2 // # of GPU devices = # of OpenMP threads
...
// In main()
MPI_Comm_rank(MPI_COMM_WORLD,&myid); // My MPI rank
MPI_Comm_size(MPI_COMM_WORLD,&nproc); // # of MPI processes
omp_set_num_threads(NUM_DEVICE); // One OpenMP thread per GPU device
nbin = NBIN/(nproc*NUM_DEVICE); // # of bins per OpenMP thread
step = 1.0/(float)(nbin*nproc*NUM_DEVICE);
#pragma omp parallel private(list the variables that need private copies)
{
   int mpid = omp_get_thread_num();
   offset = (NUM_DEVICE*myid+mpid)*step*nbin; // Quadrature-point offset
   cudaSetDevice(mpid%2);
   ...
   Hierarchical MPI+OpenMP spatial decomposition
}
```



For the CUDA layer, leave the interleaved assignment of quadrature points to CUDA threads in hypi\_setdevice.cu as it is



X

#### **Data Privatization**

• Circumvent the race condition for variable pi, by defining a private accumulator per OepnMP thread (or GPU device):

float pid[NUM\_DEVICE];

- Use the array elements as dedicated accumulators for the OepnMP threads
- Upon exiting from the OpenMP parallel section, perform reduction over the elements of pid[] to obtain the partial sum, pi, per MPI rank
- Alternatively use (recall false sharing)

```
#pragma omp parallel reduction(+:pi)
```

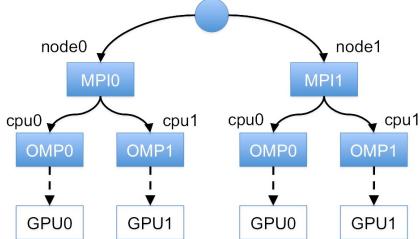
#### Output

To report which of the two GPUs has been used for the run, insert the following lines within the OpenMP parallel block:

```
cudaGetDevice(&dev used);
printf("myid = %d; mpid = %d: device used = %d; partial pi =
%f\n", myid, mpid, dev used, pi);
MPI rank
           OpenMP
                      ID of the GPU device
                                              Partial sum per OpenMP
          thread ID
                      (0 or 1) that was used
                                              thread or pid[mpid] if
                                            data privatized manually
```

#### • Output

```
myid = 0; mpid = 0: device used = 0; partial pi = 0.979926
myid = 0; mpid = 1: device used = 1; partial pi = 0.874671
myid = 1; mpid = 0: device used = 0; partial pi = 0.719409
myid = 1; mpid = 1: device used = 1; partial pi = 0.567582
PI = 3.141588
```



## Compiling MPI+OpenMP+CUDA

• Set an environment (add the following lines in your .bashrc)

```
module purge
module load usc
module load cuda/10.1.243
```

Compilation

nvcc option to pass the following option (-fopenmpi) to gcc

```
nvcc -Xcompiler -fopenmp pi3.cu -o pi3 -I${OPENMPI_ROOT}/include
-L${OPENMPI_ROOT}/lib -lmpi -lgomp
```

This should be all in one line, and no space between - sign & next letter

## Running MPI+OpenMP+CUDA

Submit the following Slurm script using the sbatch command

```
#!/bin/bash
#SBATCH --nodes=2
#SBATCH --ntasks-per-node=1
#SBATCH --cpus-per-task=2
#SBATCH --gres=gpu:2
#SBATCH --time=00:00:59
#SBATCH --output=pi3.out
#SBATCH -A anakano_429
mpirun -bind-to none -n 2 ./pi3
```

#### • Output

```
myid = 1; mpid = 1: device used = 1; partial pi = 0.567582 myid = 1; mpid = 0: device used = 0; partial pi = 0.719409 myid = 0; mpid = 0: device used = 0; partial pi = 0.979926 myid = 0; mpid = 1: device used = 1; partial pi = 0.874671 PI = 3.141588
```

# Q: Why MPI+OpenMP+CUDA?

- **A:** All US supercomputers will be GPU-accelerated.
- Q: Why calculus (quantum dynamics) on GPU?
- A: Differentiable machine learning for all.
   (Example) Natural language processing (NLP)
   DP (dynamic programming) → DL (deep learning) → DiffL (differentiable learning)

#### **Take-home lessons:**

- GPU-offload basics: host2device  $\rightarrow$  kernel  $\rightarrow$  device2host
- Multiple GPUs per node (6 on Summit): cudaSetDevice(OMP thread ID%NUM\_DEVICE)

cudaGetDeviceCount(int \*)

#### Where to go from here = make it orders-of-magnitude faster:

- Overlap CPU+GPU computations: Persistent & asynchronous kernels
- Minimize CPU-GPU communication

