# Visualizing Molecular Dynamics

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Goal: Visualize simulation to "understand" it



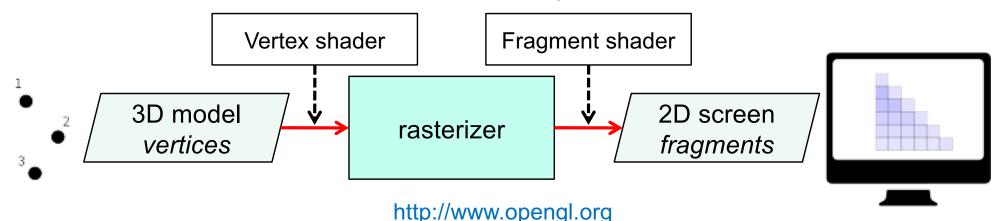


# **OpenGL: Getting Started**

#### **Installing OpenGL & GLUT libraries:**

- OpenGL (Open Graphics Language): Standard, hardware-independent interface to graphics hardware.
- GLUT (OpenGL Utility Toolkit): Window-system-independent toolkit for window application programming interfaces (APIs). How to install OpenGL & GLUT: http://web.eecs.umich.edu/~sugih/courses/eecs487/glut-howto
- \* This lecture describes basic graphics concepts common with earlier versions of OpenGL. In newer versions, shaders written in the OpenGL Shading Language (GLSL) determine various rendering attributes.

OpenGL rendering pipeline



### **OpenGL History**

**1992 OpenGL released by Silicon** Graphics, Inc. (SGI)

1994

1997

**Beowulf cluster computer** MPI 1.0 (message passing)
 MPI\_Send(), MPI\_Recv()

**OpenMP 1.0 (multithreading)** 

#pragma omp parallel

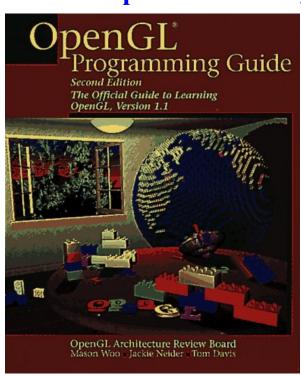
**OpenGL2.0: OpenGL Shading** 2004 Language (GLSL) included for

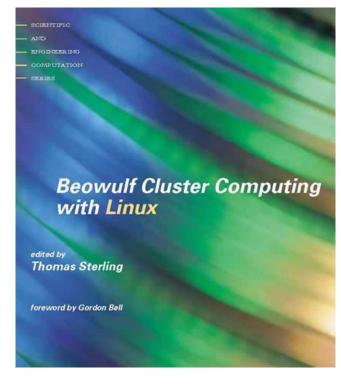
controlling graphics cards

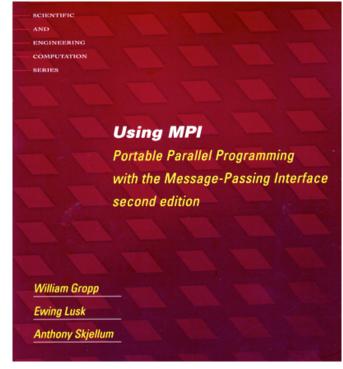
OpenGL3.0: Major revision 2008

2007

CUDA 1.0 (graphics cards)



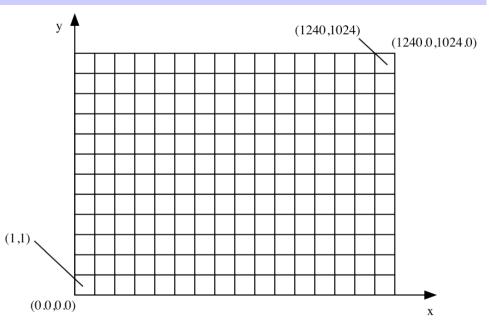




# **OpenGL Programming Basics**

atomv.c (https://aiichironakano.github.io/cs596/src/viz)

• Frame buffer: A collection of buffers in memory, which store data for screen pixels (e.g., 1280 pixels wide & 1024 pixels high) such as color, depth information for hidden surface removal, etc.



## **OpenGL Event-Handling Loop**

```
main() {
    /* Set a glut callback functions */
    glutDisplayFunc(display);
    glutReshapeFunc(reshape); events
    /* Start main display loop */
    glutMainLoop();
}

/* Definition of callback functions */
display() {...}
reshape() {...}
```

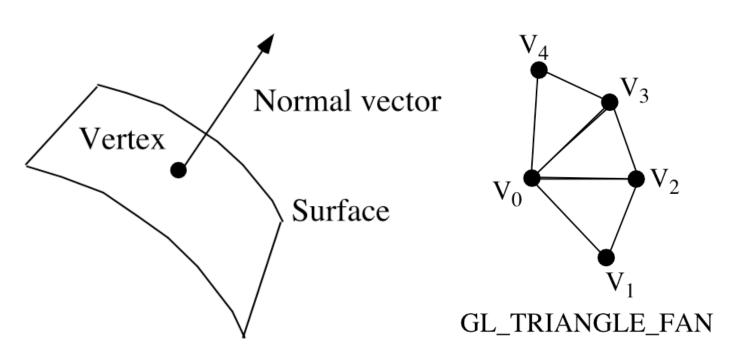
➤ Glut runtime system keeps listening if any event happens; when an even happens, it invokes the corresponding user-specified event handler function.

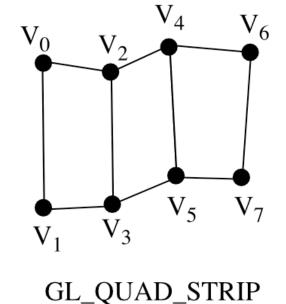
All topics in this presentation are detailed in https://aiichironakano.github.io/cs596/Visual.pdf

#### **Polygonal Surfaces**

#### Drawing a set of polygons

```
float normal_vector[MAX_VERTICES][3], vertex_position[MAX_VERTICES][3];
glBegin(GL_QUAD_STRIP);
  for (i=0; i<number_of_vertices; i++) {
     glNormal3f(normal_vector[i]);
     glVertex3f(vertex_position[i]);
  }
glEnd();</pre>
```





## **Polygonal Sphere**

```
int nlon=18, nlat=9;
                                                    /* North-pole triangular fan */
loninc = 2*M PI/nlon; /* \Delta \phi */
                                                    glBegin(GL TRIANGLE FAN);
latinc = M \overline{PI}/nlat;
                                                      qlNormal3f(0,1,0);
                       /* Δθ */
/* South-pole triangular fan */
                                                      glVertex3f(0, radius, 0);
                                                                                          north
qlBegin(GL TRIANGLE FAN);
                                                      y = \sin(lat);
                                                                                          cap
  qlNormal3f(0,-1,0);
                                                      lon = 0;
  qlVertex3f(0,-radius,0);
                                                      for (i=0; i<=nlon; i++) {
  lon = 0;
                                     south
                                                        x = cos(lon)*cos(lat);
  lat = -M PI/2 + latinc;
                                                        z = -\sin(\log) * \cos(\log);
                                     bowl
  y = \sin(\overline{lat});
                                                        qlNormal3f(x,y,z);
  for (i=0; i<=nlon; i++) {
                                                        glVertex3f(x*radius,y*radius,z*radius);
    x = \cos(\log x) \cdot \cos(\log x);
                                                        lon += loninc;
    z = -\sin(\log) *\cos(\log);
    qlNormal3f(x,y,z);
                                                    glEnd();
    glVertex3f(x*radius,y*radius,z*radius);
    lon += loninc;}
qlEnd();
/* Quadrilateral strips to cover the sphere */
for (j=1; j<nlat-1; j++) {
                                                                       (r\cos\theta\cos\phi, r\sin\theta, -r\cos\theta\sin\phi)
  lon = 0;
  qlBeqin(GL QUAD STRIP);
                                                      Δφ
                                                                 Triangle
    for (i=0; i<=nlon; i++) {
                                                  \pi
      x = \cos(\log) * \cos(\log);
      y = \sin(lat);
                                                                 ΙΔθ
      z = -\sin(\log) *\cos(\log);
                                                 θ
      glNormal3f(x,y,z);
      glVertex3f(x*radius,y*radius,z*radius);
      x = \cos(\log) \cdot \cos(\arctan);
      y = sin(lat+latinc);
                                                                        Ouadrilateral
      z = -\sin(\log) *\cos(\log t + \log);
      glNormal3f(x,y,z);
      qlVertex3f(x*radius,y*radius,z*radius);
      lon += loninc;}
  glEnd();
  lat += latinc;}
```

#### **Display Lists**

• Display list: A group of OpenGL commands that have been stored for later execution.

```
/* Generates one new display-list ID */
GLuint sphereid = glGenLists(1);

/* Define a routine to draw a sphere*/
glNewList(sphereid, GL_COMPILE);
    ...code to draw a sphere (previous slide)...
glEndList();

/* Execute sphere drawing */
glCallList(sphereid);
```

#### **Transformation Matrix**

#### Drawing spheres at many atom positions

• Transformation matrix: Specifies the amount by which the object's coordinate system is to be rotated, scaled, or translated, *i.e.*, affine transformation.

$$\vec{r'} = \vec{A}\vec{r} + \vec{b}$$

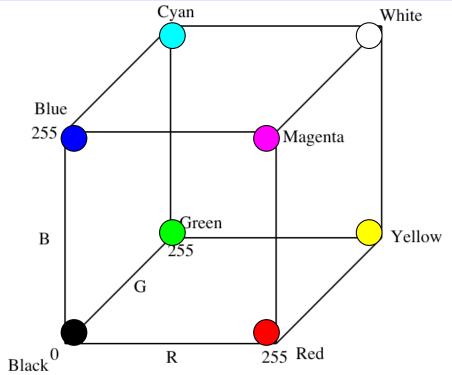
$$\begin{bmatrix} x' \\ y' \\ z' \\ 1 \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} & a_{13} & b_1 \\ a_{21} & a_{22} & a_{23} & b_2 \\ a_{31} & a_{32} & a_{33} & b_3 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

• Matrix stack: A stack of transformation matrices—at the top of the stack is the current transformation matrix applied to all vertices. Initially the transformation matrix is the identity matrix.

### **Color Display**

- RGB(A) mode: Specifying color by providing red, green & blue intensities (& alpha component).
- Alpha component: Specifies the opacity of a material; default value is 1.0 (nontransparent), if not specified.

```
float r=1.0, g=0.0, b=0.0;
glColor3f(r,g,b);
```



OpenGL as a state machine: Color change stays.

## Lighting & Materials

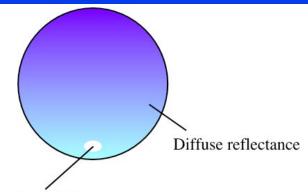
OpenGL color = light × material-reflectance

#### **OpenGL Color Types**

- Diffuse component: Gives the appearance of Specular highlight a matter or flat reflection from an object's surface.
- Ambient illumination: Simulates light reflected from other objects.
- Specular light: Creates highlights.
- Emission: Simulates the appearance of lights in the scene.

#### **Materials Definition**

- Refelectance: Material is characterized by ambient, diffuse & specular reflectance, *i.e.*, how the object reflects light.
- glEnable(GL\_COLOR\_MATERIAL)
  In this mode, the current color specified by glColor\*()
  will change the ambient & diffuse reflectance.



#### **Lighting Source**

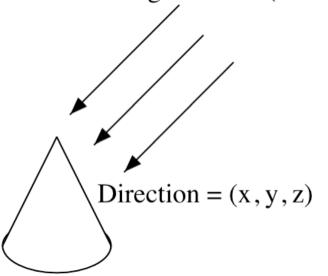
color = light × material (e.g.,  $\alpha = \alpha_{light} \times \alpha_{material}$ )

```
float light_diffuse[4] = {1.0,1.0,1.0,1.0};
float light_position[4] = {0.5,0.5,1.0,0.0};

/* Define a lighting source */
glLightfv(GL_LIGHTO,GL_DIFFUSE,light_diffuse);
glLightfv(GL_LIGHTO,GL_POSITION,light_position);

/* Enable a single OpenGL light */
glEnable(GL_LIGHTING);
glEnable(GL_LIGHTO);
```

Directional light source (w = 0)

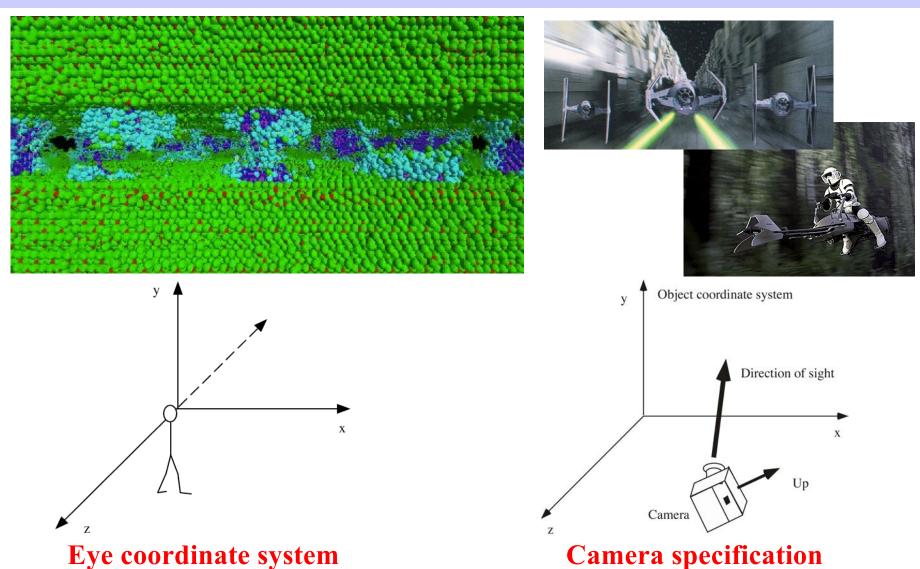


Point light source (w  $\neq$  0)  $\begin{array}{c|c}
 & & \\
 & & \\
 & & \\
 & & \\
\end{array}$ Position = (x/w, y/w, z/w)

# **Viewing Transformation**

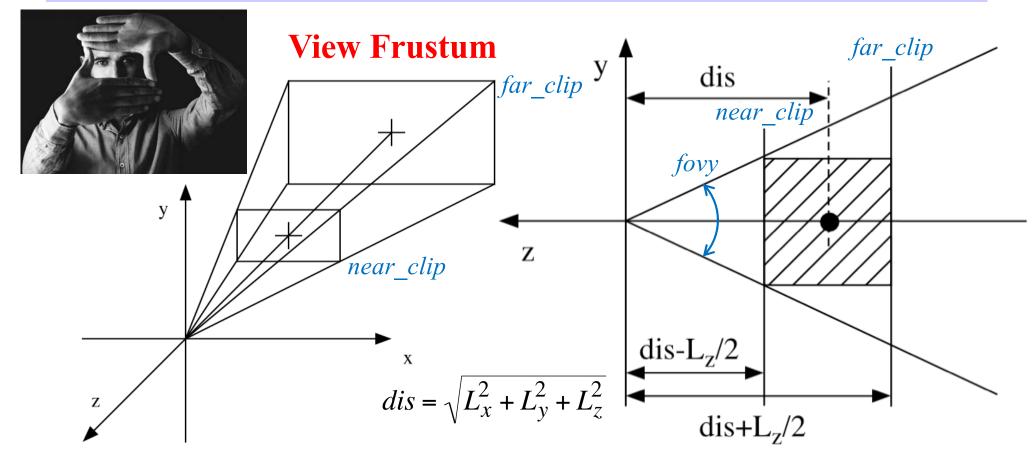
• Viewing transformation: Transforms object coordinates to eye coordinates.

gluLookat(eyx, eyey, eyz, centerx, centery, centerz, upx, upy, upz);

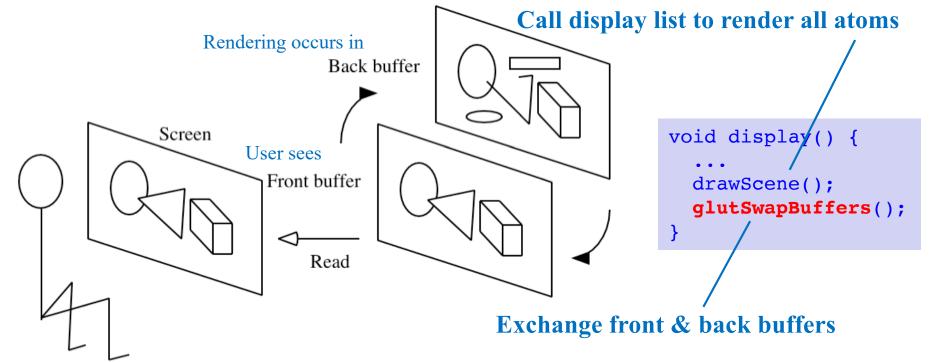


## **Clipping**

```
void reshape (int w, int h) { ... /* set the GL viewport to match the full size of the window */ glviewport(0, 0, (GLsizei)w, (GLsizei)h); aspect = w/(float)h; glMatrixMode(GL_PROJECTION); glLoadIdentity(); gluPerspective(fovy,aspect,near_clip,far_clip); fovy = 2 \tan^{-1} \left( \frac{L_y/2}{dis - L_z/2} \right) }
```



#### **Animation**



#### **Do-It-Yourself MD Animation**

• Combine md.c (https://aiichironakano.github.io/cs596/src/md/) & atomv.c (https://aiichironakano.github.io/cs596/src/viz/) to write a C+OpenGL program for in situ animation of simulation, following the lecture note on "Visualizing Molecular Dynamics III—Animation": https://aiichironakano.github.io/cs596/Visual.pdf

1. Initialize atomic coordinates, velocities, accelerations & step count before entering the GLUT main loop in main()

```
InitParams(); // Read and initialize MD parameters
InitConf();
ComputeAccel(); // Compute initial accelerations
stepCount = 1; // Initialize the MD step count
```

- 2. Register single-MD-step update function, say animate(), as glutIdleFunc() callback function glutIdleFunc(animate);
- 3. In the callback function, animate()

if  $stepCount \leq StepLimit$ 

- (i) velocity-Verlet integration for one MD step, SingleStep();
- (ii) make a display list for a collection of atoms with the updated atomic coordinates, *i.e.*, call makeCurframeGeom();
- (iii)call glutPostRedisplay() to redraw the updated scene;
- (iv) increment the time step, stepCount;

endif

### **Do-It-Yourself MD Animation (2)**

#### 4. Base program is atomv.c (it will be an OpenGL program)

Rename atomv.h|c to mdv.h|c

Copy (a) all contents of md.h into atomv.h & (b) all functions but main() from md.c to atomv.h; note most contents of main() in md.c have been used in animate() & main() in mdv.c in the previous slides

atomv.h	md.h
int natoms	int nAtom
AtomType *atoms	double r[NMAX][3]

Only used in makeAtoms() — replace by md.h counterparts