# Quantum Molecular Dynamics: Representation & Solution

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How to represent & solve Kohn-Sham equations in QMD?

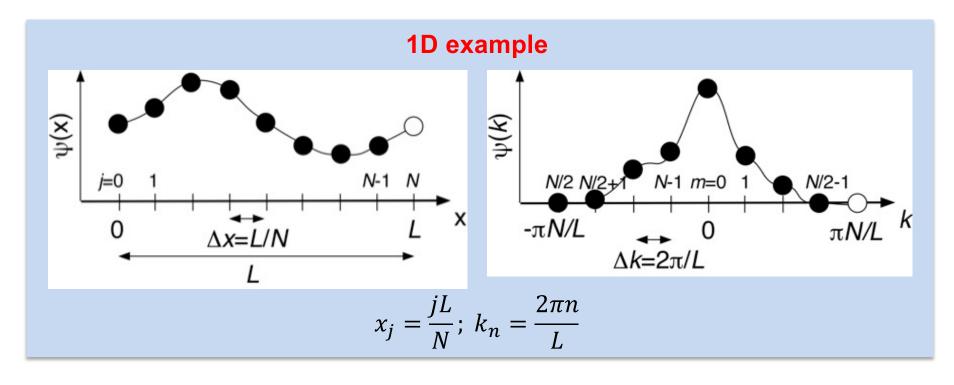




#### Representation: Plane-Wave Basis

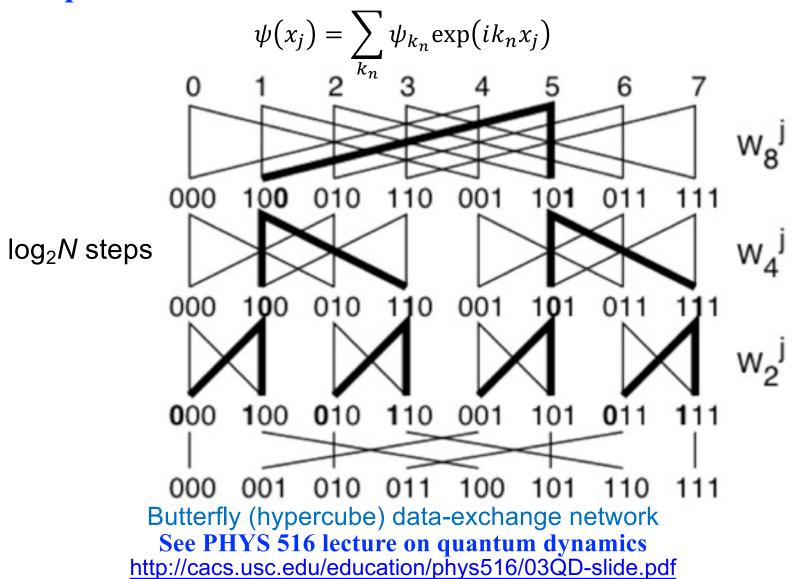
• Pseudopotentials result in slowly varying wave functions that can be represented on a regular grid, which in turn can be represented as a linear combination of plane waves, *i.e.*, Fourier transform

$$\psi(\mathbf{r}_j) = \sum_{\mathbf{k}_n} \psi_{\mathbf{k}_n} \exp(i\mathbf{k}_n \cdot \mathbf{r}_j)$$



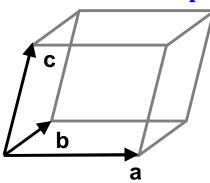
#### **Numerics: Fast Fourier Transform**

• O(NlogN) fast Fourier-transform (FFT) algorithm is typically used to perform Fourier transform



#### **Periodic Solid**

• Consider a periodic solid with the unit cell spanned by vectors a, b & c



Fourier transform of a periodic function

$$u(\mathbf{r}) = \sum_{\mathbf{G}} u_{\mathbf{G}} \exp(i\mathbf{G} \cdot \mathbf{r})$$

$$\mathbf{G} = \frac{2\pi}{\mathbf{a} \cdot (\mathbf{b} \times \mathbf{c})} [l(\mathbf{b} \times \mathbf{c}), m(\mathbf{c} \times \mathbf{a}), n(\mathbf{a} \times \mathbf{b})] \quad (l, m, n \in \mathbb{Z})$$

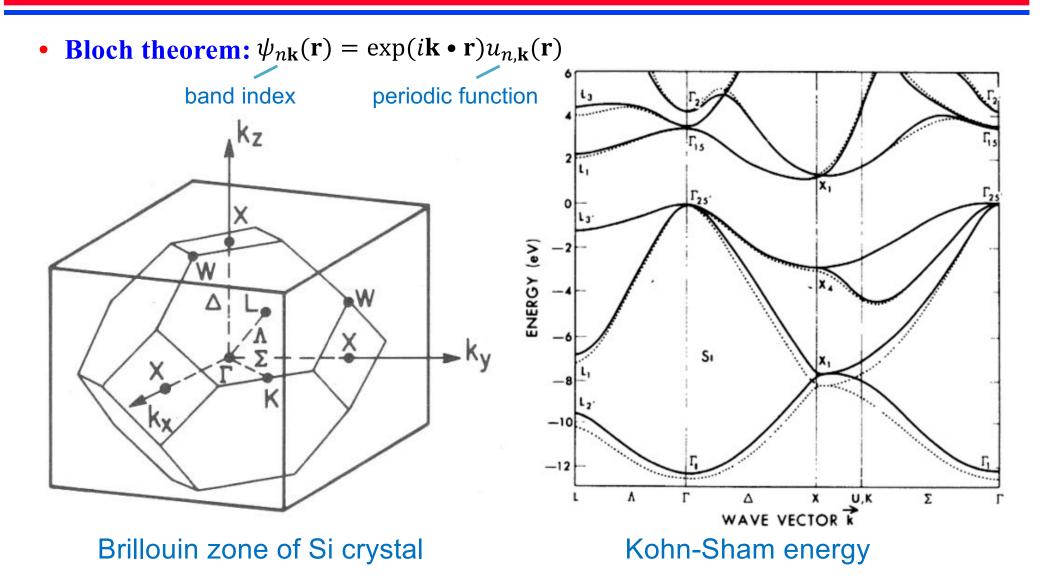
Bloch's theorem

band index
$$\psi_{n\mathbf{k}}(\mathbf{r}) = \exp(i\mathbf{k} \cdot \mathbf{r}) u_{n,\mathbf{k}}(\mathbf{r})$$

$$= \sum_{\mathbf{G}} u_{n,\mathbf{k}}(\mathbf{G}) \exp(i(\mathbf{k} + \mathbf{G}) \cdot \mathbf{r})$$

**k** ∈ first Brillouin zone in the reciprocal space

#### **Electronic Bands: Infinite Lattice**



J. R. Chelikowsky & M. L. Cohen, *Phys. Rev. B* 10, 5095 ('74)

See notes on (1) plane-wave basis & (2) supercell

## **QMD** Algorithm

time t = 0 coordinates & velocities of atoms,  $\{\vec{R}_I(t)\}, \{\vec{V}_I(t)\}$ 

minimize energy functional  $E[\{\psi_n\}, \{\vec{R}_I(t)\}]$  by conjugate-gradient method

atomic force 
$$\vec{F}_I(t) = -\frac{\partial E[\{\psi_n\}, \{\vec{R}_I(t)\}]}{\partial \vec{R}_I(t)}$$

new coordinates and velocities of atoms at time  $t + \Delta t$ 

$$\{\vec{R}_I(t+\Delta t)\},\{\vec{V}_I(t+\Delta t)\}$$

by integrating Newton's equations of motion

$$M_I \frac{d^2 \vec{R}_I(t)}{dt^2} = \vec{F}_I(t)$$

$$t \leftarrow t + \Delta t$$

## Molecular Dynamics Modes

- Structural optimization, e.g., quasi-Newton method, see <a href="http://cacs.usc.edu/education/cs699/MNK.pdf">http://cacs.usc.edu/education/cs699/MNK.pdf</a>
  - > Relax atomic positions  $\{\mathbf{R}_I\}$  to minimize the energy  $\{\mathbf{R}_I^*\} = \operatorname{argmin}_{\{\mathbf{R}_I\}} \left( \min_{\{\psi_n(\mathbf{r})\}} E[\{\psi_n(\mathbf{r})\}, \{\mathbf{R}_I\}] \right)$
- Molecular dynamics
  - > Follow atomic trajectories by numerically integrating Newton's second law of motion

$$M \frac{d^2}{dt^2} \mathbf{R}_I = -\left\langle \Psi_0 \middle| \frac{\partial h(\mathbf{r}, \mathbf{R}(t), t)}{\partial \mathbf{R}(t)} \middle| \Psi_0 \right\rangle$$

> Microcanonical (NVE), canonical (NVT) & isobaric (NPT) ensembles are supported

Martyna et al., Mol. Phys. 87, 1117 ('96)

For classical molecular dynamics, see PHYS 516 (Methods of Computational Physics, <a href="http://cacs.usc.edu/education/phys516/02MD-slide.pdf">http://cacs.usc.edu/education/phys516/02MD-slide.pdf</a>) & MASC 575 (Basics of Atomistic Simulation of Materials)

#### **Self-Consistent Field Iteration**

$$\left(-\frac{\hbar^2}{2m}\frac{\partial^2}{\partial \mathbf{r}^2} + \hat{V}_{\text{ion}} + \hat{V}_{\text{H,xc}}[\rho(\mathbf{r})]\right)\psi_n(\mathbf{r}) = \epsilon_n\psi_n(\mathbf{r})$$

Given ho(r), iteratively obtain  $\{\psi_n, \epsilon_n\}$ , e.g., by preconditioned conjugate gradient

Given  $\{\psi_n, \epsilon_n\}$ , determine  $\mu$  and compute  $\rho(\mathbf{r})$ 

$$\rho(\mathbf{r}) = \sum_{n} |\psi_n(\mathbf{r})|^2 \Theta(\mu - \epsilon_n)$$

Chemical potential

$$N = \int d\mathbf{r} \rho(\mathbf{r})$$

## **Self-Consistent Field Iteration**

initial wave function  $\{\psi_n | n = 1, ..., N_{\text{band}}\}$  & charge  $\rho$ 

solve  $\nabla^2 V_{\text{Hartree}}(\vec{x}) = -4\pi e^2 \rho(\vec{x})$ set up the electronic potential,  $V = V_{\text{ion}} + V_{\text{Hartree}} + V_{\text{xc}}$ 

unitary transformation to diagonalize  $\int d^3 x \psi_m(\vec{x}) \left\{ -\frac{\hbar^2}{2m} \nabla^2 + V(\vec{x}) \right\} \psi_n(\vec{x})$ 

iterative improvement of  $\{\psi_n\}$  & orthonormalization

calculate new  $\rho$  from updated  $\{\psi_n\}$ 

if not converged

#### Orthogonalization by Matrix Decomposition

• Gram-Schmidt orthonormalization: The orthonormal basis set  $Q = [q_1...q_m]$ is obtained starting from an arbitrary set of m vectors,  $S = [s_1...s_m]$  as

$$\mathbf{q}_{1} = \mathbf{s}_{1} / |\mathbf{s}_{1}|$$
for  $i = 2$  to  $m$ 

$$\mathbf{q}'_{i} = \mathbf{s}_{i} - \sum_{j=1}^{i-1} \mathbf{q}_{j} (\mathbf{q}_{j} \cdot \mathbf{s}_{i}) \quad \text{Projection!}$$

$$\mathbf{q}_{i} = \mathbf{q}'_{i} / |\mathbf{q}'_{i}| \quad \widehat{P} \quad |s_{i}\rangle$$

$$\mathbf{q}_{i} = \mathbf{q}'_{i} / |\mathbf{q}'_{i}| \quad \Sigma_{j=1}^{i-1} |\widetilde{q}_{j}\rangle \langle q_{j}|$$
endfor

• The Gram-Schmidt procedure amounts to QR decomposition, S = QR, where R is an  $m \times m$  right-triangle matrix

where K is all 
$$m \times m$$
 right-triangle matrix
$$n \begin{bmatrix} \mathbf{q}_1 & \mathbf{q}_1 & \mathbf{q}_2 & \mathbf{q}_3 & \mathbf{q}_4 \end{bmatrix} \begin{bmatrix} |\mathbf{q}_1'| & \mathbf{q}_1 \cdot \mathbf{s}_2 & \mathbf{q}_1 \cdot \mathbf{s}_3 & \mathbf{q}_1 \cdot \mathbf{s}_4 \\ 0 & |\mathbf{q}_2'| & \mathbf{q}_2 \cdot \mathbf{s}_3 & \mathbf{q}_2 \cdot \mathbf{s}_4 \\ 0 & 0 & |\mathbf{q}_3'| & \mathbf{q}_3 \cdot \mathbf{s}_4 \end{bmatrix} m$$

$$\therefore \mathbf{s}_i = |\mathbf{q}_i'| \mathbf{q}_i + \sum_{j=1}^{i-1} \mathbf{q}_j (\mathbf{q}_j \cdot \mathbf{s}_i)$$
• For higher parallelization. Cholesky decomposition is used instead.

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# **Charge Mixing**

- Fixed-point charge mapping in self-consistent field iteration  $\rho_{\text{in}}(\mathbf{r}) \mapsto v_{\text{Hxc}}(\mathbf{r}) \mapsto \{\psi_n(\mathbf{r})\} \mapsto \rho_{\text{out}}(\mathbf{r})$
- Directly using  $\rho_{out}(\mathbf{r})$  as  $\rho_{in}(\mathbf{r})$  in the next iteration step often destabilizes numerical iteration
- Charge mixing  $\rho_{\text{in}}^{i} \leftarrow \sum_{j=1}^{n} \alpha_{i} \rho_{\text{in}}^{i-j}$
- Determine the mixing coefficients  $\alpha_i$  in order to minimize the residual  $R[\rho_{\rm in}(\mathbf{r})] \equiv \rho_{\rm out}[\rho_{\rm in}] \rho_{\rm in}$
- See note on Pulay charge mixing

# Conjugate-Gradient Minimization of Energy Functional

*i*: iteration index; *n*: band index

"gradient" 
$$g_n^{(i)} = -\frac{\delta E\left[\left\{\psi_n^{(i)}\right\}, \left\{\vec{R}_l(t)\right\}\right]}{\delta \psi_n^{(i)}} + \varepsilon_n^{(i)} \psi_n^{(i)} \equiv -H \psi_n^{(i)} + \varepsilon_n^{(i)} \psi_n^{(i)}$$

$$\varepsilon_n^{(i)} = \int d^3 r \psi_n^{(i)*} H \psi_n^{(i)}$$
"preconditioning"  $\tilde{g}_n^{(i)} = \hat{P} g_n^{(i)}$ 

"conjugate gradient"  $h_n^{(i)} = \tilde{g}_n^{(i)} + \beta h_n^{(i-1)}, \beta = \int d^3 r g_n^{(i)} \cdot g_n^{(i)} / \int d^3 r g_n^{(i-1)} \cdot g_n^{(i-1)}$ 

"new wave function"  $\psi_n^{(i+1)} = C(\lambda) \left(\psi_n^{(i)} + \lambda h_n^{(i)}\right)$ 

with constraint  $\int d^3 r \psi_n^{(i+1)*} \psi_m = 0 \ (m \le n)$ 

$$i \leftarrow i+1 \qquad \text{if } \left|\varepsilon_n^{(i+1)} - \varepsilon_n^{(i)}\right| > \varepsilon$$

See lecture on iterative minimization (<a href="http://cacs.usc.edu/education/phys516/QD2CG.pdf">http://cacs.usc.edu/education/phys516/QD2CG.pdf</a>) & notes on (1) conjugate-gradient (CG) method, (2) CG electronic-state solver, (3) CG DFT solver & (4) 2D electron example

### Real-Space Grid as a Basis

- Wave functions & electron density are represented by numerical values on real-space grid points
- Finite difference expansion for the kinetic-energy operator

$$\left. \frac{\partial^2 \psi_n}{\partial x^2} \right|_{\mathbf{r}_{ijk} = (x_i, y_j, z_k)} = \sum_{l=-L}^{L} C_l \psi_n(x_i + lh, y_j, z_k) + O(h^{2L+2})$$

(short-ranged operation)

The calculations are performed completely in "real space"



- Suitable for systems with vacuum (e.g., clusters, surfaces)
- Efficient implementation on parallel computers

J.R. Chelikowsky, N. Troullier & Y.Saad, *Phys. Rev. Lett.* **72**, 1240 ('94)

## **Acceleration of Convergence**

#### **Preconditioning**

Enhanced convergence rate of short  $\frac{-)(H-\varepsilon)\psi = -g}{(H-\varepsilon)\delta = g} \quad \text{invert?}$   $\delta \leftarrow (H-\varepsilon)^{-1}g$ wavelength components of the residual

$$(H - \varepsilon)(\psi + \delta) = 0$$

$$-)(H - \varepsilon)\psi = -g$$

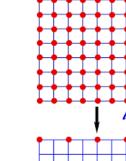
$$(H - \varepsilon)\delta = g$$

approximately

$$\delta \leftarrow (H - \varepsilon)^{-1} g$$

$$\tilde{g}_n(x_i, y_j, z_k) = \hat{P}g_n^{(i)}$$

$$= \sum_{l_1=-1}^{1} \sum_{l_2=-1}^{1} \sum_{l_3=-1}^{1} c_{l_1 l_2 l_3} g_n(x_i + l_1 h, y_j + l_2 h, z_k + l_3 h)$$

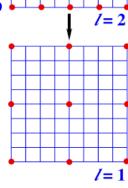


Multigrid method [Brandt '77, Bernholc et al. '96, Beck, '00]

To reduce long wavelength components of the residual,

$$\left(-\frac{\hbar^2}{2m}\nabla^2 + V\right)\varphi = g_n^{(i)}$$
$$\psi_n^{(i)} \leftarrow \psi_n^{(i)} + \varphi$$

on a coarse grid



## **Iterative Solution of Linear Systems**

Fixed-point equation

$$x = D^{-1}[-(L+U)x + b]$$

Jacobi iteration

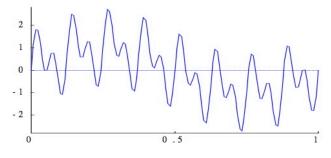
$$x^{(n+1)} = D^{-1}[-(L+U)x^{(n)} + b]$$

$$x_i^{(n+1)} = \frac{1}{a_{ii}} \begin{pmatrix} \sum_{j=1}^{N} a_{ij} x_j^{(n)} + b_i \\ j=1 \\ (j \neq i) \end{pmatrix}$$

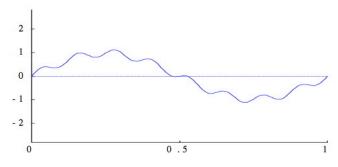
• Over (under) relaxation:  $\Delta > 1$  ( $\Delta < 1$ )

$$\begin{aligned} x_i^{(n+1)} &= \frac{1}{a_{ii}} \left| -\sum_{\substack{j=1\\(j \neq i)}}^N a_{ij} x_j^{(n)} + b_i \right| \\ &= x_i^{(n)} + \frac{1}{a_{ii}} \left( -\sum_{j=1}^N a_{ij} x_j^{(n)} + b_i \right) \rightarrow x_i^{(n)} + \frac{\Delta}{a_{ii}} \left( -\sum_{j=1}^N a_{ij} x_j^{(n)} + b_i \right) \end{aligned}$$

• Initial error:

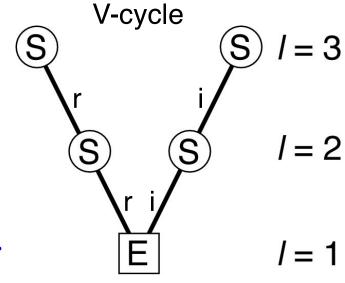


Error after 35 iteration sweeps:

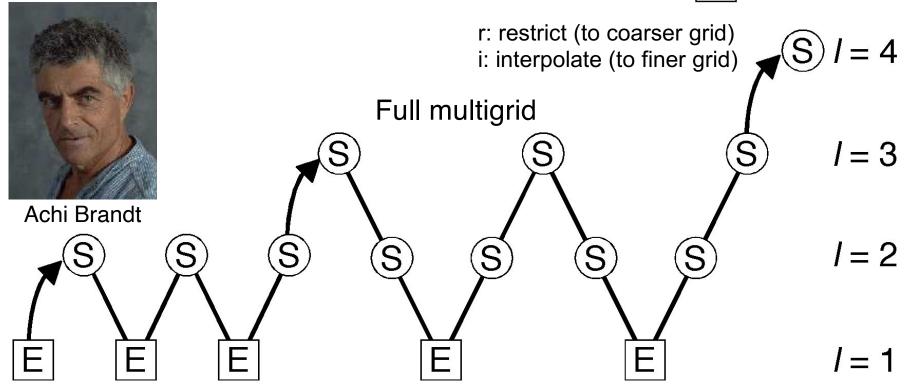


## **Multigrid Method**

- Residual equation:  $A^{(l)}(\psi + e) = 0$   $\frac{-)A^{(l)}\psi = r}{A^{(l)}e = -r}$
- Smoothing:  $e \leftarrow [1 + Z^{(l)}A^{(l)}]e + Z^{(l)}r$

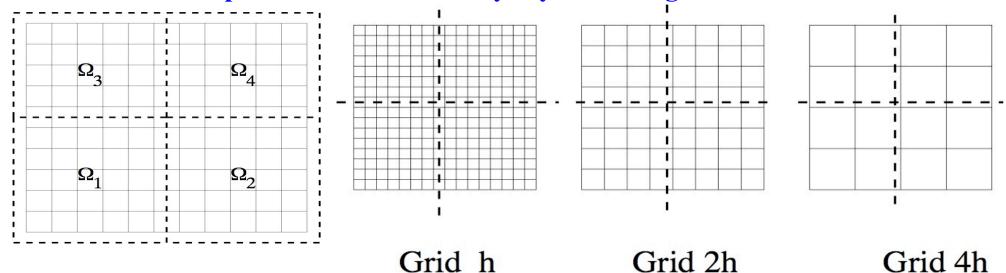


• Coarsening of residual & interpolation of error



## Parallel Multigrid Method

#### • Domain decomposition with boundary-layer caching



• 2D computational & communication costs (isogranular or weak scaling)

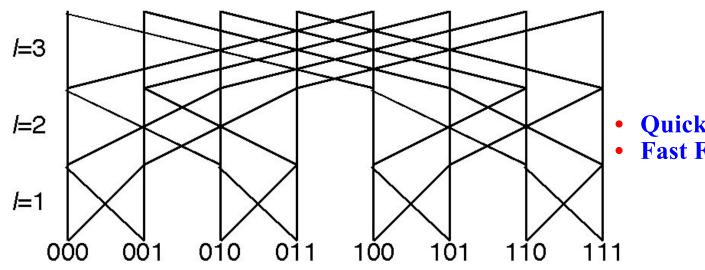
 $N \times N$  grids each on  $P \times P$  processors:  $T(N^2P^2, P^2) = a \log NP + bN + cN^2$ 

$$\begin{split} S_{P^2} &= \frac{N^2 P^2 T(N^2, 1)}{N^2 T(N^2, P^2)} = \frac{P^2 \Big( c N^2 \Big)}{a \log NP + b N + c N^2} = \frac{P^2}{1 + \frac{b}{c N} + \frac{a}{c N} \log NP} \\ E_{P^2} &= \frac{S_{P^2}}{P^2} = \frac{1}{1 + \frac{b}{c N} + \frac{a}{c N} \log NP} \end{split}$$

Nakano et al., Comput. Phys. Commun. 83, 181 ('94)

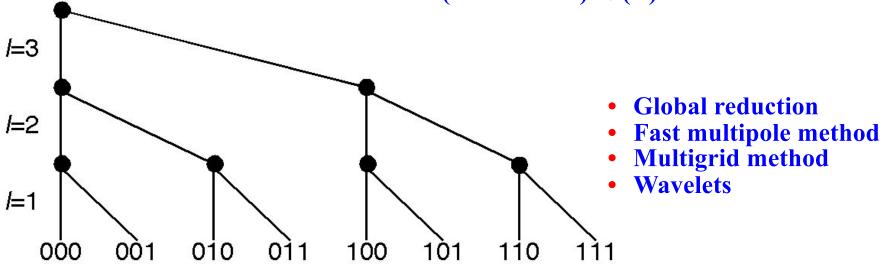
#### **Global Communications**





- **Quicksort**
- Fast Fourier transform



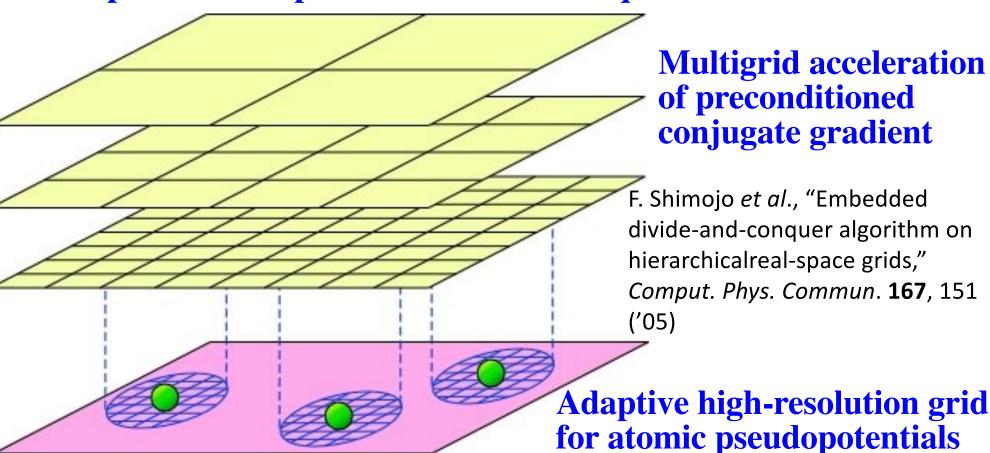


See note on multigrid preconditioned CG

#### Real-Space DFT on Hierarchical Grids

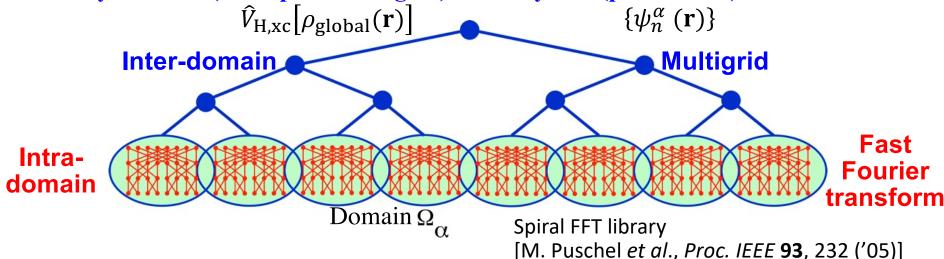
#### Efficient parallelization of DFT: real-space approaches

- High-order finite difference [Chelikowsky, Troullier, Saad, '94]
- Multigrid acceleration [Bernholc et al., '96; Beck, '00]
- Double-grid method [Ono, Hirose, '99] ~ obsolete, with PAW
- Spatial decomposition/divide-&-conquer

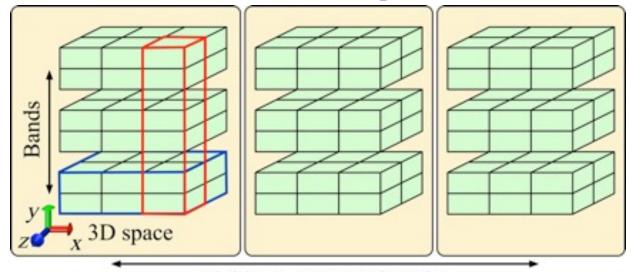


#### **Hierarchical Computing**

• Globally scalable (real-space multigrid) + locally fast (plane wave) electronic solver



• Hierarchical band (i.e. Kohn-Sham orbital) + space + domain (BSD) decomposition



Divide-&-conquer domains

F. Shimojo et al., J. Chem. Phys. **140**, 18A529 ('14)