

OpenMP Target Offload for Heterogeneous Architectures

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Goal: Unified open high-level programming of both CPU & GPU



Exaflop/s Supercomputing

- Diverse exaflop/s supercomputing platforms



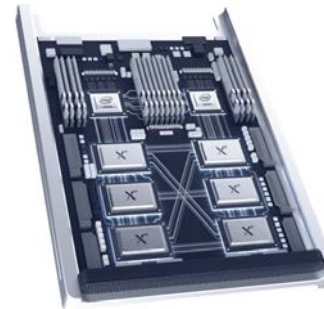
Summit (0.2 Exaflop/s, current)
IBM CPU/NVIDIA GPU

GPU Architecture

X^e arch-based “Ponte Vecchio”
GPUPile-based, chiplets, HBM
stack, Foveros 3D integration, 7nm

On-Node Interconnect

CPU-GPU: PCIe
GPU-GPU: X^e Link



Aurora (Exaflop/s)
Intel CPU/Intel GPU



1 HPC and AI Optimized
AMD EPYC CPU
4 Purpose Built AMD
Radeon Instinct GPU



Frontier (1.5 Exaflop/s)
AMD CPU/AMD GPU

- Need an open programming model for heterogeneous (*e.g.* GPU-accelerated) clusters (note CUDA is a proprietary language by NVIDIA)

See <http://press3.mcs.anl.gov/atpesc/files/2021/08/ATPESC-2021-Track-1-Talk-8-Muralidharan-Aurora.pdf>

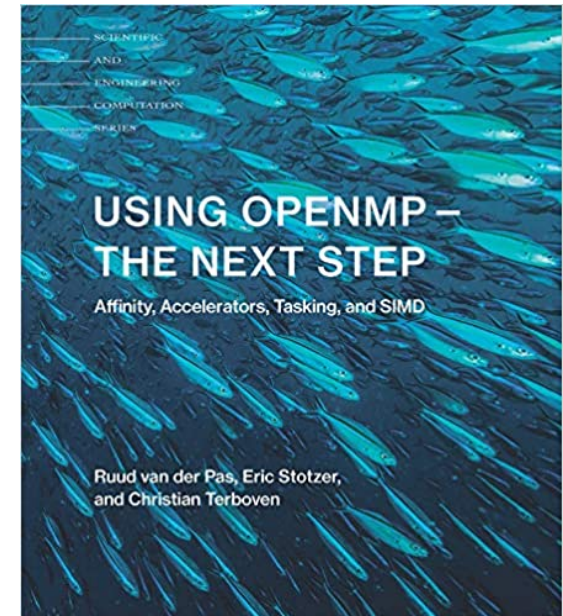
Open Programming Models

- **OpenACC (Open Computing Language)**
Open standard for directive-based programming of heterogeneous devices

<https://www.openacc.org/>

- **OpenMP 4.5/5.0**
Starting specification version 4.5, OpenMP allows offloading the execution of the code & data to heterogeneous devices

<https://www.openmp.org/specifications/>



OpenMP Offload

- Latest version of OpenMP allows one to maintain one version of a code, which can run on either a general-purpose central processing unit (CPU) or an accelerator (*e.g.* graphic processing unit, GPU; tensor processing unit, TPU; digital signal processor, DSP; field-programmable gate array, FPGA)
- Objective is to execute parts of the program on a heterogeneous *accelerator device* (or *target device*), *i.e.*, dedicated computer hardware outside CPU (which will be called *host device*) to execute certain functions faster than CPU
- In OpenMP, program execution begins on the host, which offloads the execution of parts of the code & data to accelerator

See “OpenMP 4.5 Target Offload” (NASA Ames)

https://aiichironakano.github.io/cs596/OpenMP4.5_3-20-19.pdf

OpenMP Target Construct

- Simple example

```
main() {  
    float a[1000], b[1000], c, d;  
    ...  
    #pragma omp target map(a,b,c,d)  
    {  
        int i;  
        #pragma omp parallel for  
        for (i=0; i<N; i++)  
            a[i] = b[i]*c+d;  
    }  
    ...  
}
```

- When a host thread encounter the `#pragma omp target` directive, the target region specified by it will be executed by a new thread running on an accelerator, *cf.* CUDA GPU kernel
- Before the new thread starts executing the target region, the variable in the `map()` clause are mapped onto accelerator memory, which often is disjunct from the host memory, *cf.* `cudaMemcpy()`
- The offloaded code is usually a data-parallel structured block, which can be handled by multiple threads on accelerator using standard OpenMP constructs like `#pragma parallel for`

Asynchronous Offload

```
main() {  
    float a[1000], b[1000], c, d;  
    ...  
    #pragma omp target nowait map(a, b, c, d)  
    {  
        int i;  
        #pragma omp parallel for  
        for (i=0; i<N; i++)  
            a[i] = b[i]*c+d;  
    }  
    func(b);    // perform computation independent of device output  
    #pragma omp taskwait  
    func(a);    // perform computation dependent on device output  
}
```

- By default, the thread that encounters a device construct waits for the construct to complete before executing the next line
- When a **nowait** clause is added to the device construct, the encountering thread does not wait but instead continues executing the code passed the construct
- The **taskwait** constructs lets the original thread wait for the completion of the target task generated by it before continuing to the next line

Overlap CPU & GPU computations for high performance

Computing the Value of π on GPU

omp_target_pi.c

```
#include <omp.h>
#include <stdio.h>
#define NBIN 1000000
#define NTRD 96

int main() {
    float step, sum=0.0, pi;
    step = 1.0/(float)NBIN;
    #pragma omp target map(step, sum)
    {
        # pragma omp parallel for reduction(+:sum) num_threads(NTRD)
        for (long long i=0; i<NBIN; i++) {
            float x = (i+0.5)*step;
            sum += 4.0/(1.0+x*x);
        }
    }

    pi = sum*step;
    printf("PI = %f\n", pi);
    return 0;
}
```

The only addition for GPU offload

Thread reduction of sum

Specify # of GPU threads

This line is identical for CPU & GPU

1. Black: original serial code
2. Green: one-line multithreading
3. Red: another line for GPU offload

GPU: Easy & Hard Ways

Serial: pi.c

```
#include <stdio.h>
#define NBIN 100000000
int main() {
    double step, x, sum=0.0, pi;
    step = 1.0/NBIN;
    for (long long i=0; i<NBIN; i++) {
        x = (i+0.5)*step;
        sum += 4.0/(1.0+x*x);
    }
    pi = sum*step;
    printf("PI = %f\n", pi);
    return 0;
}
```

OpenMP: omp_target_pi.c

```
#include <omp.h>
#include <stdio.h>
#define NBIN 1000000
int main() {
    float step, sum=0.0, pi;
    step = 1.0/(float)NBIN;
    #pragma omp target map(step, sum)
    {
        #pragma omp parallel for reduction(+:sum)
        for (long long i=0; i<NBIN; i++) {
            float x = (i+0.5)*step;
            sum += 4.0/(1.0+x*x);
        }
    }
    pi = sum*step;
    printf("PI = %f\n", pi);
    return 0;
}
```

DPC++: pi.cpp

```
#include <CL/sycl.hpp>
#include <iostream>
#include <array>

using namespace cl::sycl;

#define NBIN 1000000 // # of bins for quadrature
#define NTRD 512 // # of threads

int main()
{
    float step = 1.0f/NBIN;
    std::array<float, NTRD> sum;
    for (int i=0; i<NTRD; ++i) sum[i] = 0.0f;

    queue q(gpu_selector{});

    std::cout << "Running on: " <<
    q.get_device().get_info<info::device::name>() << std::endl;

    range<1> sizeBuf(NTRD);

    {
        buffer<float, 1> sumBuf(sum.data(), sizeBuf);
        q.submit([&](handler sh){
            auto sumAccessor =
            sumBuf.get_access<access::mode::read_write>(h);
            h.parallel_for(sizeBuf, [=](id<1> tid) {
                for (int i=0; i<NBIN; i+=NTRD) {
                    float x = (i+0.5f)*step;
                    sumAccessor[tid] += 4.0f/(1.0f+x*x);
                }
            }); // End parallel for
        }); // End queue submit
    }

    float pi=0.0f;
    for (int i=0; i<NTRD; i++) // Inter-thread reduction
        pi += sum[i];
    pi *= step; // Multiply bin width to complete integration

    std::cout << "Pi = " << pi << std::endl;

    return 0;
}
```

CUDA: pi.cu

```
// Using CUDA device to calculate pi
#include <stdio.h>
#include <cuda.h>

#define NBIN 10000000 // Number of bins
#define NUM_BLOCK 13 // Number of thread blocks
#define NUM_THREAD 192 // Number of threads per block
int tid;
float pi = 0;

// Kernel that executes on the CUDA device
__global__ void cal_pi(float *sum, int nbins, float step, int nthreads, int nblocks) {
    int i;
    float x;
    int idx = blockIdx.x*blockDim.x+threadIdx.x; // Sequential thread index across the blocks
    for (i=idx; i< nbins; i+=nthreads*nblocks) {
        x = (i+0.5)*step;
        sum[idx] += 4.0/(1.0+x*x);
    }
}

// Main routine that executes on the host
int main(void) {
    dim3 dimGrid(NUM_BLOCK, 1, 1); // Grid dimensions
    dim3 dimBlock(NUM_THREAD, 1, 1); // Block dimensions
    float *sumHost, *sumDev; // Pointer to host & device arrays

    float step = 1.0/NBIN; // Step size
    size_t size = NUM_BLOCK*NUM_THREAD*sizeof(float); // Array memory size
    sumHost = (float *)malloc(size); // Allocate array on host
    cudaMalloc((void **) &sumDev, size); // Allocate array on device
    // Initialize array in device to 0
    cudaMemset(sumDev, 0, size);
    // Do calculation on device
    cal_pi <<<dimGrid, dimBlock>>> (sumDev, NBIN, step, NUM_THREAD, NUM_BLOCK); // call CUDA kernel
    // Retrieve result from device and store it in host array
    cudaMemcpy(sumHost, sumDev, size, cudaMemcpyDeviceToHost);
    for(tid=0; tid<NUM_THREAD*NUM_BLOCK; tid++)
        pi += sumHost[tid];
    pi *= step;

    // Print results
    printf("PI = %f\n", pi);

    // Cleanup
    free(sumHost);
    cudaFree(sumDev);

    return 0;
}
```


Hierarchical Parallelization

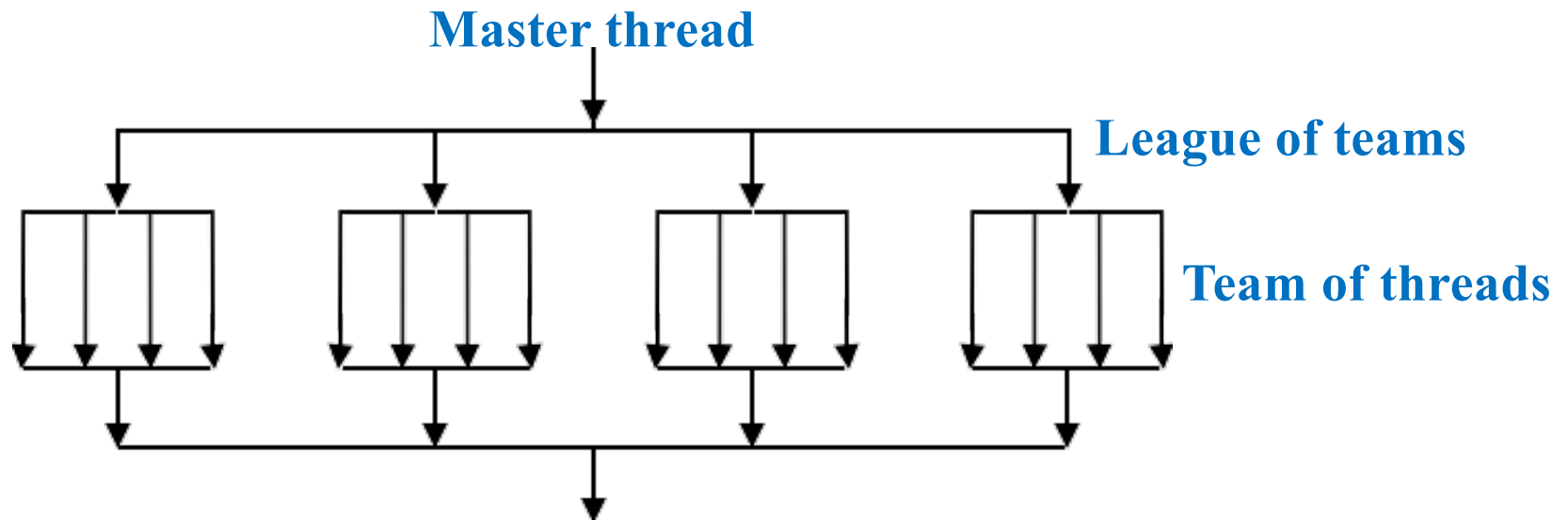
- `#pragma omp teams`

Starts a **league** of multiple thread **teams**; teams construct must be nested immediately inside a target construct, so they are commonly used as `#pragma omp target teams`; `num_teams` clause can be used to specify the number of teams

(Example) `#pragma omp target teams num_teams(13)`

- `#pragma omp distribute`

Distribute the work across the teams



cf. CUDA grid of blocks & block of threads

Teams for Computing π

- Spatial decomposition *via* offset among teams & data privatization

```
#define NTMS 12
float sum_teams[NTMS];
for (int j=0; j<NTMS; j++) sum_teams[j] = 0.0;
...
#pragma omp target teams map(step,sum_teams) num_teams(NTMS)
{
    #pragma omp distribute
    for (int j=0; j<NTMS; j++) {
        long long ibgn = NBIN/NTMS*j;
        long long iend = NBIN/NTMS*(j+1);
        if (j == NTMS-1) iend = NBIN;
        # pragma omp parallel for reduction(+:sum_teams[j]) num_threads(NTRD)
        for (long long i=ibgn; i<iend; i++) {
            float x = (i+0.5)*step;
            sum_teams[j] += 4.0/(1.0+x*x);
        }
    }
}

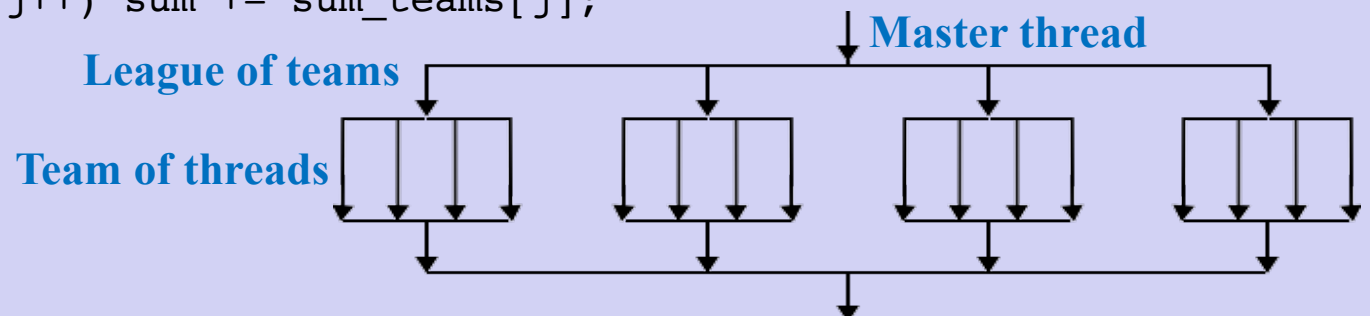
for (int j=0; j<NTMS; j++) sum += sum_teams[j];
```

Data privatization among teams

New: teams & distribute constructs

Modified: offset & private accumulator

[NBIN/NTMS]*NTMS could be less than NBIN



Using OpenMP Target on Discovery

- **Necessary module**

```
module purge
module load llvm // Use LLVM compiler
```

- **Compilation**

— Type all in one line

```
clang -fopenmp -fopenmp-targets=nvptx64-nvidia-cuda -
Xopenmp-target -march=sm_70 --gcc-
toolchain=/spack/apps/gcc/8.3.0 omp_target_pi.c -o
omp_target_pi
```

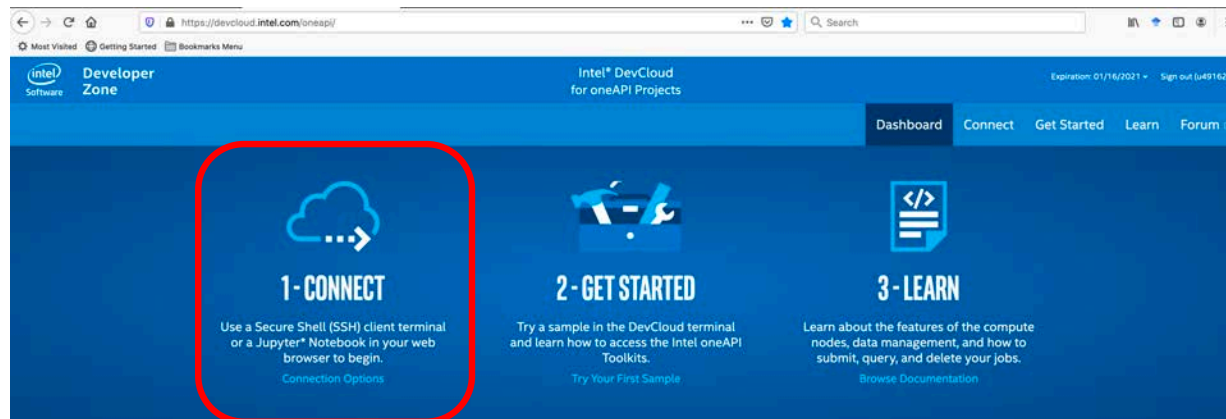
- **Execute on a GPU-accelerated node**

```
[anakano@discovery]$ salloc --partition=gpu --gres=gpu:v100:1 --time=00:30:00
salloc: Nodes d11-02 are ready for job
[anakano@d11-02]$ ./omp_target_pi
PI = 3.141593
```

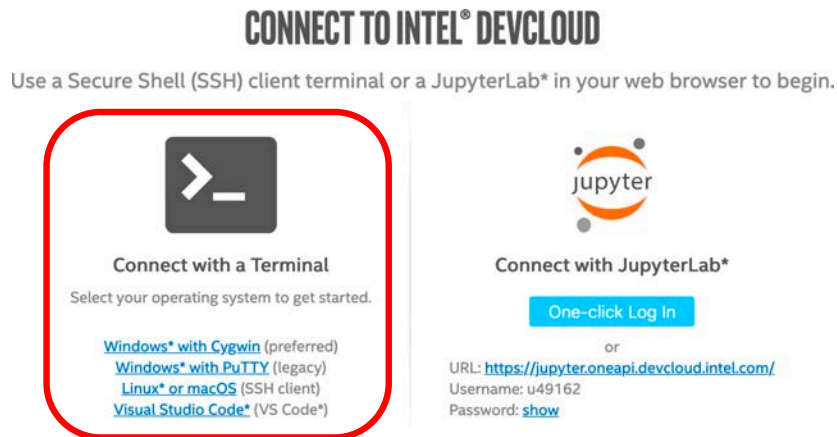
(Optional) Using Intel DevCloud (1)

- Sign up at the Intel developer's cloud (DevCloud) site:

<https://devcloud.intel.com/oneapi>



- Setup terminal connection to devcloud server



- Log in to devcloud server

```
macbook-pro:~ aiichironakano$ ssh devcloud
u49162@login-2:~$
```

Using Intel DevCloud (2)

- **Transfer** `omp_target_pi.c` to devcloud server, *e.g.*, using `sftp`

- **Compile**

```
u49162@login-2:~$ cc -o omp_target_pi omp_target_pi.c -fopenmp
```

- **Interactive job on a GPU-accelerated computing node using PBS (portable batch system) job scheduler**

```
u49162@login-2:~$ qsub -I -l nodes=1:gpu:ppn=2
qsub: waiting for job 694715.v-qsvr-1.aidevcloud to start
qsub: job 694715.v-qsvr-1.aidevcloud ready
u49162@s001-n177:~$
```

- **Run**

```
u49162@s001-n177:~$ ./omp_target_pi
PI = 3.141593
```

- **Start developing your own OpenMP target offload codes for GPU acceleration!**

Where to Go from Here

- **Start developing your own OpenMP target offload codes for GPU acceleration**
- **Explore other new features, *e.g.*, `omp simd` for explicit control of single-instruction multiple-data vectorization**
- **Plenty of room for performance optimization**

See “OpenMP Offload Optimization” (Ye Luo, Argonne National Lab.)

<https://aiichironakano.github.io/cs596/Luo-OpenMPoffload-SC20.pdf>