

Assignment - 1

Foundations of Machine Learning

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[1] Given n points, we imagine two classes of data each of $n/2$ points overlapped to some extent in 2D space -

(a) Using all the available data, the training error varies ~~between~~ on the choice of 'K' in K-NN classifier.

Overfitting
 $K=1$, for each data point, x , in the training set, we want to find another point, x' , that has the least distance from x . Here the shortest possible distance is always 0 (zero) which means the nearest neighbour is the data point itself, $x = x'$.
For this reason, the training error will be zero.

underfitting
 $K=n$, Here the training error become very high and in some specific cases be even 100%!
This is because for uneven datasets where one class is having very few samples but the other class is having more than the other class then by majority voting the new test sample of the other class would always be classified incorrectly. ~~The~~
~~Generally, if $K=n$ then model ends up predicting the~~
For this reason, the training error ~~can~~ may be can reach 100%.

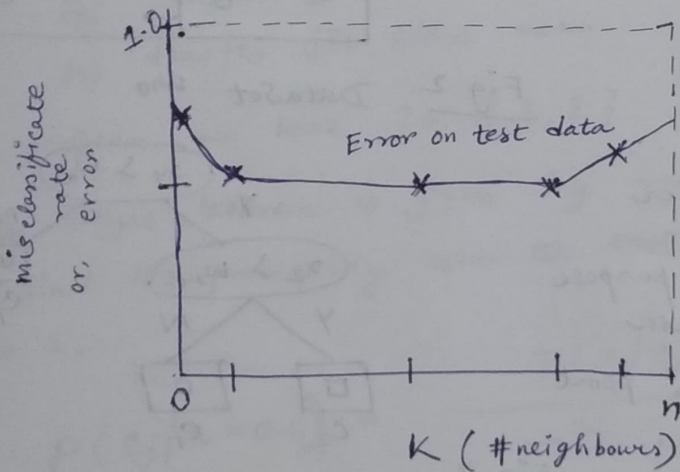
Model ends up predicting the majority level of the whole data-set.
~~For~~ $K > 1$ and $K < n$, Generally K value is chosen empirically so that neither it ~~is~~ overfits ($K=1$) nor it ~~is~~ underfits ($K=n$).

(b) Generalization error is the expected value of the misclassification rate when averaged over future data. It can be approximated by computing the misclassification rate on a large independent test set not used during model training. The misclassification error can be defined as follows -

$$\text{error} = \frac{1}{N} \sum_{i=1}^N \mathbb{I}(f(x_i) \neq y_i)$$

where, $f(x)$ is the classifier.

$$\mathbb{I}(e) = \begin{cases} 1 & e = \text{TRUE} \\ 0 & e = \text{FALSE} \end{cases} \quad \text{is the indicator function.}$$



Here we plot the test error rate vs K . It has a U-shaped curve. For complex model (small K) the method overfits and for simple mode (big K) the method underfits.

(c) The two reasons due to which K -NN is undesirable when input dimension is high are -

i) Distance between points increases exponentially as the number of dimensions increase - We know K -NN classifier

makes the assumption that similar points share similar labels.

Unfortunately, in high-dimension spaces, points that are drawn from a probability distribution, never tend to be close to each other.

For K -NN it requires a point to be close in every dimension.

As gaps between data ~~points~~ increases errors also increase

and K -NN will not be able to predict/accurately based on measured distance.

As the number of dimensions increases the size of the data space increases and hence for K -NN to work correctly the amount of data needed to maintain density should also increase.

ii) Space complexity increases as dimensions increase -

K-NN classifier requires all data to be stored in memory so if we have n data points and each point is of m dimension then the space complexity will be of the order $O(nm)$. This will increase as $(m \gg n)$ and hence will be difficult to store and query.

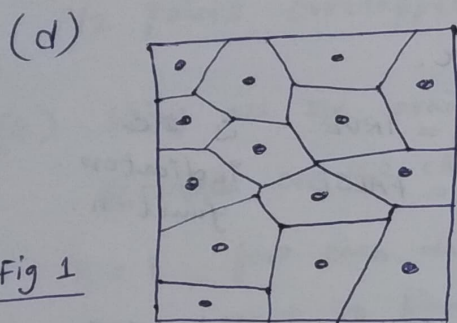


Fig 1

1-NN decision boundaries under euclidean distance

1-NN is a simple classifier which divides the input space for classification purpose into a convex region each of which corresponds to a point in the instance set.

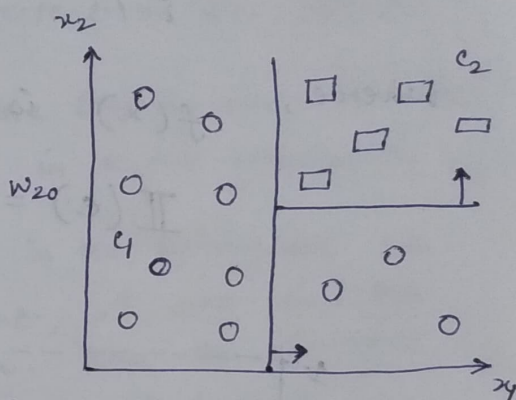


Fig 2 Dataset w_{10}

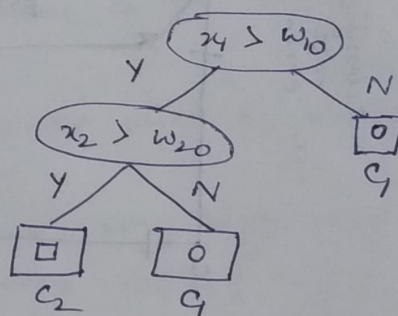


Fig 3

Decision Tree corresponding to the above dataset

Now we can see, that the decision boundaries for 1-NN correspond to the cell boundaries of each point as shown in Fig 1 but they are not parallel to the co-ordinate axes.

Fig 2 is the dataset corresponding to the decision trees in Fig 3 and we can clearly observe that the boundaries are always parallel to co-ordinate axes based on the kind of questions asked at each node of the decision tree.

Now, since the univariate decision node splits along one-axis and successive splits are orthogonal to each other, it is not possible to mimic the same using 1-NN classifiers. Hence it is not possible, to build a decision tree which classifies exactly according to the 1-NN scheme using euclidean distance measure.

2 (a) The gaussian likelihood is given by -

$$P(x|c_j) = \frac{1}{\sqrt{2\pi\sigma_j^2}} e^{-\frac{1}{2} \left(\frac{x - \mu_j}{\sigma_j} \right)^2}$$

where c_j denotes j^{th} class

σ_j denotes j^{th} class variance

μ_j denotes j^{th} class mean

$$\mu_j = \frac{1}{N_j} \sum_{i=1}^{N_j} x_i$$

As per problem, we have $j = \{1, 2\}$

Bayes theorem is given by -

to find the probability that the test point $x=0.6$ belongs to class 1,

$$P(c_j|x=0.6) = \frac{P(x|c_j) P(c_j)}{\sum_{k=1}^K P(x|c_k) P(c_k)}$$

$$P(c_j) = \frac{N_j}{\sum_{k=1}^K N_k}$$

N_j is the # samples in the j^{th} class data set.

let us find the maximum likelihood parameters,

$$N_1 = 10$$

$$\mu_1 = \frac{2.6}{10} = 0.26$$

$$\sigma_1^2 = 0.0149$$

$$p_1 = P(c_1) = \frac{10}{14} = 0.714$$

$$N_2 = 4$$

$$\mu_2 = \frac{3.45}{4} = 0.8625$$

$$\sigma_2^2 = 0.0092$$

$$p_2 = P(c_2) = \frac{4}{14} = 0.2857$$

we have to find,

$$P(C_1 | x=0.6) = \frac{P(x=0.6 | C_1) P(C_1)}{P(x|C_1) P(C_1) + P(x|C_2) P(C_2)}$$

let us find the posterior, prior and evidence -

$$P(x=0.6 | C_1) = \frac{1}{\sqrt{2\pi \sigma_1^2}} e^{-\frac{1}{2} \left(\frac{x - \mu_1}{\sigma_1} \right)^2}$$

$$= 0.0675466$$

$$P(x=0.6 | C_2) = \frac{1}{\sqrt{2\pi \sigma_2^2}} e^{-\frac{1}{2} \left(\frac{x - \mu_2}{\sigma_2} \right)^2}$$

$$= 0.0983161$$

Therefore,

$$P(C_1 | x=0.6) = 0.631945$$

Also, we already have found,

$$P_1 = P(C_1) = 0.714$$

$$P_2 = P(C_2) = 0.2857$$

(Ans.)

(b) let $y = \begin{cases} 1 & \text{represent class politics} \\ 0 & \text{represent class sports} \end{cases}$

$x = (\text{goal, football, golf, defense, offence, wicket, office, strategy})$

$x_j = j^{\text{th}}$ word among the n words.

~~words~~
 $n = 8$

$m = \text{total \# samples}$ ~~120(6+6)~~
 $= 12$

Assuming Bernoulli distribution, ~~we estimate~~ the parameters, ~~namely~~,
~~so far as~~

$$P(y)$$

$$P(x_j = 1 | y = 0)$$

$$P(x_j = 1 | y = 1)$$

Using joint likelihood, we can estimate these parameters,

$$P(x_1, \dots, x_8 | y) = P(x_1 | y) P(x_2 | y, x_1) P(x_3 | y, x_1, x_2) \dots$$

[By Assume x_j are conditionally independent]

$$P(x_1, \dots, x_8 | y) = P(x_1 | y) P(x_2 | y) P(x_3 | y) \dots$$

$$P(x_1, \dots, x_8 | y) = \prod_{j=1}^n P(x_j | y) \dots \dots \dots (1)$$

or

$$\prod_{i=1}^m \prod_{j=1}^n P(x_j | y)$$

Therefore, the joint likelihood is calculated as —

$$\mathcal{L}(y, x_j | y) = \prod_{i=1}^m \prod_{j=1}^n P(x_j^i, y^i)$$

$$= \prod_{i=1}^m \prod_{j=1}^n P(x_j^i | y^i) P(y^i) \quad \dots (2)$$

$$P(y) = \frac{\sum_i I\{y^i=1\}}{m} = \frac{6}{12} \quad \text{is } I(\cdot) \text{ is the indicator function}$$

$$= 0.5$$

$$P(x_j=1 | y=1)$$

$$= \frac{\sum_i I\{y^i=1, x_j^i=1\}}{\sum_i I\{y^i=1\}}$$

$$= \frac{1}{6} [2 \quad 1 \quad 1 \quad 5 \quad 5 \quad 1 \quad 4 \quad 5]$$

$$= \left[\frac{2}{6} \quad \frac{1}{6} \quad \frac{1}{6} \quad \frac{5}{6} \quad \frac{5}{6} \quad \frac{1}{6} \quad \frac{4}{6} \quad \frac{5}{6} \right]$$

$$P(x_j=1 | y=0)$$

$$= \frac{\sum_i I\{y^i=0, x_j^i=1\}}{\sum_i I\{y^i=0\}}$$

$$= \frac{1}{6} [4 \quad 4 \quad 1 \quad 4 \quad 1 \quad 1 \quad 0 \quad 1]$$

$$= \left[\frac{4}{6} \quad \frac{4}{6} \quad \frac{1}{6} \quad \frac{4}{6} \quad \frac{1}{6} \quad \frac{1}{6} \quad 0 \quad \frac{1}{6} \right]$$

To predict we maximize as —

$$\arg \max_y P(y | \vec{x}) = \arg \max_y P(\vec{x} | y) P(y)$$

Given document, $\vec{x} = (1, 0, 0, 1, 1, 1, 1, 0)$

$$P(y=1 | \vec{x}) = P(\vec{x} | y=1) P(y=1)$$

$$= \prod_{j=1}^n P(x_j^i | y^i=1) P(y^i=1)$$

$$= \prod_{j=1}^n P(x_j=1 | y=1)^{x_j^i} \cdot \left(1 - P(x_j=1 | y=0)\right)^{1-x_j^i} \cdot P(y^i=1) \quad \dots (3)$$

Also,

$$P(y=0 | \vec{x}) = P(\vec{x} | y=0) P(y=0)$$

$$= \prod_{j=1}^n P(x_j^i | y^i=0) P(y^i=0)$$

$$= \prod_{j=1}^n P(x_j=1 | y=0)^{x_j^i} \cdot \left(1 - P(x_j=1 | y=0)\right)^{1-x_j^i} \cdot (1 - P(y^i)) \quad \dots (4)$$

Taking log on both sides for (3), we get —

$$\log P(y=1 | \vec{x}) = \sum_{j=1}^{n=8} \left[x_j^i \log(P(x_j=1 | y=1)) + (1-x_j^i) \log(1 - P(x_j=1 | y=1)) \right] + \log(P(y^i=1))$$

~~compute using numpy python~~

Here $i=1$.

After computing, we get —

$$\log(P(y=1 | \vec{x})) = 0.128 + 0.16 = 0.288$$

$$\log P(y=0 | \vec{x})$$

$$= \sum_{j=1}^{n=8} \left[x_j^i \log(P(x_j=1|y=0)) + (1-x_j^i) \log(1-P(x_j=1|y=0)) \right] + \log(1-P(y))$$

After computing, we get —

$$= -1.192 + 0.374$$

$$\Rightarrow \log(P(y=0 | \vec{x})) = -0.818$$

$$\text{since, } \log(P(y=1 | \vec{x})) > \log(P(y=0 | \vec{x})) \quad (\text{Ans.})$$

we classify \vec{x} as politics.
