pyTempico

Release 1.0.0

Tausand Electronics

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Tausand

pyTempico was built to simplify the usage of Tausand Tempico family of time-to-digital converters (TDCs), providing a library aimed to interface these devices using Python coding.

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CHAPTER

ONE

CONTENTS

1.1 pyTempico package

Created on Jan 30 2024

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Core class and methods for PyTempico library.

To use with Tausand Electronics' Time-to-Digital Converters (TDCs) of the family *Tausand Tempico*.

Last edited on 2024-02-08.

1.2 TempicoDevice class

class pyTempico.core.TempicoDevice(com_port)

Tausand Tempico TDC device object.

To create an object of the TempicoDevice class, it is required to send as parameter the desired com_port. For example,

```
>>> my_tempico_device_object = pyTempico.TempicoDevice('COM5')
```

To modify or access attributes, **please use methods**. For example,

```
>>> my_tempico_device_object.getIdn()
```

To access attributes of a particular channel, use methods of the TempicoChannel class through attributes ch1, ch2, ch3, ch4 of this class. For example, to get average cycles on channel 2,

```
>>> my_tempico_device_object.ch2.getAverageCycles()
```

Changing attributes without using methods, do not change the actual parameters in the device.

Accesing attributes without using methods, returns values registered in local memory, that may not be updated.

To begin a measurement and read its results, use methods measure() and fetch().

```
id_tempico_device
     Unique identifier of the TausandDevice object.
         Type
             int
ch1
     Object of the TempicoChannel class linked to TDC in channel 1 (input A).
         Type
             TempicoChannel
ch2
     Object of the TempicoChannel class linked to TDC in channel 2 (input B).
         Type
             TempicoChannel
ch3
     Object of the TempicoChannel class linked to TDC in channel 3 (input C).
         Type
             TempicoChannel
ch4
     Object of the TempicoChannel class linked to TDC in channel 4 (input D).
         Type
             TempicoChannel
device
     Serial port object.
         Type
             Serial
idn
     Identification string.
         Type
             str
number_of_channels
     number of stop inputs of the device.
         Type
             int
number_of_runs
     Number of measurement runs of the TDCs in TempicoDevice.
         Type
             int
port
     Serial port string.
         Type
             str
```

threshold

Threshold voltage on the rising edge of start and stops inputs of TDCs in the TempicoDevice.

Type

float

close()

Ends (closes) a connection with a TausandDevice.

It is recommended to close connection at the end of a routine, to free the device's port for future use.

Parameters

(none) -

closeTempico()

Ends (closes) a connection with a TausandDevice.

Same as method *close()*.

Parameters

(none) -

convertReadDataToIntList(data_string)

Converts a string with a read dataset message issued by a TempicoDevice, into an integer 2D-list.

The dataset of a TempicoDevice is in the following format:

```
[[ch,run,start_us,stop_ps1,...,stop_psN],...,[ch,run,start_time_us,stop_ps1,...,

⇒stop_psN]]
```

where

- 'ch' indicates the TDC channel,
- 'run' goes from 1 to NumberOfRuns,
- 'start_us' is the timestamp of start pulse, in microseconds; this value overflows (go back to zero) after 2^32-1 microseconds, about 4294 seconds,
- 'stop_ps1' is the measured precision timelapse between start and the 1st stop pulse, in picoseconds,
- 'N' is the NumberOfStops.

Every value in the dataset is an integer.

Parameters

data_string (*str*) – dataset message to convert.

Returns

dataset message converted.

Return type

list(int)

decrementThresholdVoltage()

Reduces the threshold voltage on the rising edge of start and stops inputs of TDCs in the TempicoDevice.

To validate the actual threshold voltage applied, method getThresholdVoltage() should be called.

This function requires that a connection is established with the TempicoDevice.

Parameters

(none) -

fetch()

Reads the most recent measurement data set form a TempicoDevice.

The dataset of a TempicoDevice is in the following format:

```
[[ch,run,start_us,stop_ps1,...,stop_psN],...,[ch,run,start_time_us,stop_ps1,...,

⇒stop_psN]]
```

where

- 'ch' indicates the TDC channel,
- 'run' goes from 1 to NumberOfRuns,
- 'start_us' is the timestamp of start pulse, in microseconds; this value overflows (go back to zero) after 2^32-1 microseconds, about 4294 seconds,
- 'stop_ps1' is the measured precision timelapse between start and the 1st stop pulse, in picoseconds,
- 'N' is the NumberOfStops.

Every value in the dataset is an integer.

If no measurement has been done, the device may respond with an empty dataset. To make a measmurement, method *measure()* must be used.

This function requires that a connection is established with the TempicoDevice.

```
Parameters (none) –
```

Returns

measured dataset.

Return type

list(int)

getBaudRate()

Returns the TempicoDevice baud rate.

```
Parameters (none) –
```

Returns

baud rate.

Return type

int

getFirmware()

Returns the TempicoDevice firmware version.

```
Parameters (none) –
```

Returns

firmware version.

Return type

str

getIdn()

Returns the TempicoDevice identification string.

If the connection is established with the TempicoDevice, this function request the device for the string. If not, the most recent read string is returned.

Parameters

(none) -

Returns

identification string.

Return type

str

getNumberOfRuns()

Returns the number of measurement runs of the TDCs in TempicoDevice.

By default, number of runs = 1 (single measurement).

If the connection is established with the TempicoDevice, this function request the device for the value. If not, the most recent value is returned.

Parameters

(none) -

Returns

Number of number of runs.

Return type

integer

getSettings()

Reads the current settings form a TempicoDevice.

The response for settings query on a TempicoDevice is in the following format:

```
CH1:ACYC 1;CH1:ENAB 1;CH1:NST 1;...;CH4:STOP:MASK 0;NRUN 1;THR 1.00
```

This function requires that a connection is established with the TempicoDevice.

Parameters

(none) -

Returns

device settings.

Return type

str

getThresholdVoltage()

Returns the threshold voltage on the rising edge of start and stops inputs of TDCs in the TempicoDevice.

Start and stop inputs are coupled to 50 ohms.

By default, threshold voltage = 1.00V (recommended for TTL>2.5V).

All inputs are 5V tolerant.

Gate input. This parameter does not have effect on the gate input. Gate input accepts $3.3V\ TTL$ and $5V\ TTL$ signals.

• When gate is disconnected, system is enabled.

- When gate is connected to 0V, system is disabled.
- When gate is connected to 3.3V/5V, system is enabled.

If the connection is established with the TempicoDevice, this function request the device for the value. If not, the most recent value is returned.

Parameters

(none) -

Returns

start and stop inputs threshold voltage.

Return type

float

incrementThresholdVoltage()

Increases the threshold voltage on the rising edge of start and stops inputs of TDCs in the TempicoDevice.

To validate the actual threshold voltage applied, method getThresholdVoltage() should be called.

This function requires that a connection is established with the TempicoDevice.

Parameters

(none) -

isOpen()

Returns if a TDC TempicoDevice connection is established (open).

Parameters

(none) -

Returns

True when TempicoDevice connection is open.

Return type

bool

isPendingReadMessage()

Determines if a pending message is available to be read in a TempicoDevice serial port.

Parameters

(none) -

Returns

True, when a pending message is found.

Return type

bool

measure()

Begins a measurement sequence and reads its dataset from a TempicoDevice.

The dataset of a TempicoDevice is in the following format:

```
[[ch,run,start_us,stop_ps1,...,stop_psN],...,[ch,run,start_time_us,stop_ps1,...,

⇒stop_psN]]
```

where

- 'ch' indicates the TDC channel,
- 'run' goes from 1 to NumberOfRuns,

- 'start_us' is the timestamp of start pulse, in microseconds; this value overflows (go back to zero) after 2^32-1 microseconds, about 4294 seconds,
- 'stop_ps1' is the measured precision timelapse between start and the 1st stop pulse, in picoseconds,
- 'N' is the NumberOfStops.

Every value in the dataset is an integer.

If measurement cannot be completed within timeout, the device may respond with an incomplete or empty dataset. In this case, to obtain a complete dataset, the method *fetch()* may be called later.

This function requires that a connection is established with the TempicoDevice.

Parameters

(none) -

Returns

measured dataset.

Return type

list(int)

open()

Establishes (opens) a connection with a TausandDevice.

It is mandatory to establish a connection with this method before to be able to send/to receive data to/from the device.

Parameters

(none) -

openTempico()

Establishes (opens) a connection with a TausandDevice.

Same as method open().

Parameters

(none) -

readIdnFromDevice()

Returns the TempicoDevice identification string, by requesting it to the device.

This function requires that a connection is established with the TempicoDevice. As an alternative, method getIdn() may be used.

Parameters

(none) -

Returns

identification string.

Return type

str

readMessage()

Reads pending messages sent by a TempicoDevice from its serial port.

If no message is received, it waits the port timeout, typically 1s.

This function requires that a connection is established with the TempicoDevice.

Parameters

(none) -

Returns

read message.

Return type

str

reset()

Sends a reset command to the TempicoDevice.

Applying a reset clears all the settings of the TempicoDevice and its TempicoChannels to their default values.

This function requires that a connection is established with the TempicoDevice.

Parameters

(none) -

setNumberOfRuns(number)

Modifies the number of measurement runs of the TDCs in TempicoDevice.

By default, number of runs = 1 (single measurement).

This function requires that a connection is established with the TempicoDevice.

Parameters

number (int) – desired number of runs for every TDC. Valid values are from 1 to 1000.

setThresholdVoltage(desired_voltage)

Changes the threshold voltage on the rising edge of start and stops inputs of TDCs in the TempicoDevice.

Start and stop inputs are coupled to 50 ohms.

By default, threshold voltage = 1.00V (recommended for TTL>2.5V).

All inputs are 5V tolerant.

Gate input. This parameter does not have effect on the gate input. Gate input accepts 3.3V TTL and 5V TTL signals.

- When gate is disconnected, system is enabled.
- When gate is connected to 0V, system is disabled.
- When gate is connected to 3.3V/5V, system is enabled.

To validate the actual threshold voltage applied, method getThresholdVoltage() should be called.

This function requires that a connection is established with the TempicoDevice.

Parameters

desired_voltage (*float*) – desired start and stop inputs threshold voltage. Valid parameters are MINimum|MAXimum|DOWN|UP or a number from 0.90 to 1.60.

setThresholdVoltageToMaximum()

Sets to the maximum valid value the threshold voltage on the rising edge of start and stops inputs of TDCs in the TempicoDevice.

To validate the actual threshold voltage applied, method *getThresholdVoltage()* should be called.

This function requires that a connection is established with the TempicoDevice.

Parameters

(none) -

setThresholdVoltageToMinimum()

Sets to the minimum valid value the threshold voltage on the rising edge of start and stops inputs of TDCs in the TempicoDevice.

To validate the actual threshold voltage applied, method getThresholdVoltage() should be called.

This function requires that a connection is established with the TempicoDevice.

Parameters

(none) -

waitAndReadMessage(wait_time_ms=1)

Waits the specified time, and then reads pending messages sent by a TempicoDevice from its serial port, if any.

If no message is received, it does not wait for a port timeout.

This function requires that a connection is established with the TempicoDevice.

Parameters

```
wait_time_ms (int, optional) - Waiting time, in miliseconds. Defaults to 1.
```

Returns

read message.

Return type

str

writeMessage(message)

Writes a message to a TempicoDevice in its serial port.

If a response is expected after writing a message, the *readMessage()* method should be called afterwards to obtain the response.

This function requires that a connection is established with the TempicoDevice.

Parameters

message (str) – message to be sent.

1.3 TempicoChannel class

class pyTempico.core.TempicoChannel(id_device, ch_num)

Single channel on a Tempico Device.

To modify or access attributes, **please use methods**. For example, to get average cycles on channel 2,

```
>>> my_tempico_device_object.ch2.getAverageCycles()
```

Changing attributes without using methods, do not change the actual parameters in the device.

Accesing attributes without using methods, returns values registered in local memory that may not be updated.

id_tempico_channel

Unique identifier for a TempicoChannel object.

Type

int

id_tempico_device Identifier of the TausandDevice linked to this TempicoChannel object. Type int average_cycles Average cycles. Type int channel_number Number of the channel in the device (1=A, 2=B,...). **Type** int enable True when the channel is enabled. **Type** bool mode Measurement mode. 1|2. • 1: Short measurement range. Start-stop times from 12ns to 500ns. • 2: Large measurement range. Start-stop times from 125ns to 4ms. Type int number_of_stops Number of stop pulses expected after a start pulse arrives. 1..5. **Type** int parent_tempico_device

Pointer reference to parent object of TempicoDevice() class.

Type

TempicoDevice

start_edge

Edge type on the start pulse used to begin timing. RISE|FALL.

```
Type str
```

stop_edge

Edge type on the stop pulses used to end timing. RISE|FALL.

```
Type str
```

stop_mask

Time that stop pulses are ignored after receiving a start pulse on the TDC. Value in microseconds. 0..4000.

Type

int

disableChannel()

Disables a TDC TempicoChannel.

By default, channels are enabled.

This function requires that a connection is established with the TempicoDevice of the TempicoChannel.

To validate the status of the channel, method <code>isEnabled()</code> may be used.

Parameters

(none) -

enableChannel()

Enables a TDC TempicoChannel.

By default, channels are enabled.

This function requires that a connection is established with the TempicoDevice of the TempicoChannel.

To validate the status of the channel, method *isEnabled()* may be used.

Parameters

(none) -

getAverageCycles()

Returns the average cycles of the TDC TempicoChannel.

By default, average cycles = 1 (no multi-cycle averaging).

If the connection is established with the TempicoDevice, this function request the device for the value. If not, the most recent value is returned.

Parameters

(none) -

Returns

Number of average cycles.

Return type

integer

getMode()

Returns the measurement mode of the TDC TempicoChannel.

By default, mode = 1.

If the connection is established with the TempicoDevice, this function request the device for the value. If not, the most recent value is returned.

Parameters

(none) -

Returns

Mode. Possible values are,

- 1: Short measurement range. Start-stop times from 12ns to 500ns.
- 2: Large measurement range. Start-stop times from 125ns to 4ms.

Return type

integer

getNumberOfStops()

Returns the expected number of stop pulses of the TDC TempicoChannel.

By default, number of stops = 1 (single start -> single stop).

The TDC must receive all the expected number of stops to register them as a valid measurement; otherwise, the measurements are discarded.

If the connection is established with the TempicoDevice, this function request the device for the value. If not, the most recent value is returned.

Parameters

(none) -

Returns

Number of stops.

Return type

integer

getStartEdge()

Returns the edge type used on start pulses of the TDC TempicoChannel.

By default, start edge = 'RISE'.

If the connection is established with the TempicoDevice, this function request the device for the value. If not, the most recent value is returned.

Parameters

(none) -

Returns

start edge type. Possible values are,

- 'RISE': TDC timing starts on a rising edge of the start pulse.
- 'FALL': TDC timing starts on a falling edge of the start pulse.

Return type

string

getStopEdge()

Returns the edge type used on stop pulses of the TDC TempicoChannel.

By default, stop edge = 'RISE'.

If the connection is established with the TempicoDevice, this function request the device for the value. If not, the most recent value is returned.

Parameters

(none) -

Returns

stop edge type. Possible values are,

- 'RISE': TDC timing ends on a rising edge of the stop pulse.
- 'FALL': TDC timing ends on a falling edge of the stop pulse.

Return type

string

getStopMask()

Returns the time that stop pulses are ignored after receiving a start pulse on the TDC TempicoChannel. In microseconds.

By default, stop mask = 0 (no masking).

If the connection is established with the TempicoDevice, this function request the device for the value. If not, the most recent value is returned.

Parameters

(none) -

Returns

stop mask time, in microseconds.

Return type

integer

isEnabled()

Returns if a TDC TempicoChannel is enabled.

By default, channels are enabled.

If the connection is established with the TempicoDevice, this function request the device for the value. If not, the most recent value is returned.

Parameters

(none) –

Returns

True, when TDC channel is enabled.

Return type

bool

setAverageCycles(number)

Modifies the average cycles of the TDC TempicoChannel.

By default, average cycles = 1 (no multi-cycle averaging).

This function requires that a connection is established with the TempicoDevice of the TempicoChannel.

Parameters

number (int) – desired average cycles for the TDC. Valid values are 1|2|4|8|16|32|64|128.

setMode(number)

Modifies the measurement mode of the TDC TempicoChannel.

By default, mode = 1. Possible values are,

- 1: Short measurement range. Start-stop times from 12ns to 500ns.
- 2: Large measurement range. Start-stop times from 125ns to 4ms.

This function requires that a connection is established with the TempicoDevice of the TempicoChannel.

Parameters

number (int) – desired measurement mode for the TDC. Valid values are 1 or 2.

setNumberOfStops(number)

Modifies the expected number of stop pulses of the TDC TempicoChannel.

By default, number of stops = 1 (single start -> single stop).

The TDC must receive all the expected number of stops to register them as a valid measurement; otherwise, the measurements are discarded. For extending the valid time range, consider using measurement mode 2.

This function requires that a connection is established with the TempicoDevice of the TempicoChannel.

Parameters

number (*int*) – desired number of stops for the TDC. Valid values are from 1 to 5.

setStartEdge(edge_type)

Sets the edge type used on start pulses of the TDC TempicoChannel.

By default, start edge = 'RISE'. Possible values are,

- 'RISE': TDC timing starts on a rising edge of the start pulse.
- 'FALL': TDC timing starts on a falling edge of the start pulse.

This function requires that a connection is established with the TempicoDevice of the TempicoChannel.

Parameters

edge_type (*str*) – desired start edge type for the TDC. Valid values are 'RISE', 1, 'FALL', 0.

setStopEdge(edge_type)

Sets the edge type used on stop pulses of the TDC TempicoChannel.

By default, stop edge = 'RISE'. Possible values are,

- 'RISE': TDC timing ends on a rising edge of the stop pulse.
- 'FALL': TDC timing ends on a falling edge of the stop pulse.

This function requires that a connection is established with the TempicoDevice of the TempicoChannel.

Parameters

edge_type (str) – desired stop edge type for the TDC. Valid values are 'RISE', 1, 'FALL', 0

setStopMask(stop_mask_in_us)

Modifies the time that stop pulses are ignored after receiving a start pulse on the TDC TempicoChannel.

By default, stop mask = 0 (no masking).

This function requires that a connection is established with the TempicoDevice of the TempicoChannel.

Parameters

stop_mask_in_us (*int*) – desired stop mask for the TDC, in microseconds. Valid values are from 0 to 4000.

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TWO

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