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## Lecture 2: Newton–Cotes Quadrature

See Chapter 7 of Süli and Mayers.

**Terminology:** Quadrature  $\equiv$  numerical integration.

**Setup:** given  $f(x_k)$  at  $n + 1$  equally spaced points  $x_k = x_0 + k \cdot h$ ,  $k = 0, 1, \dots, n$ , where  $h = (x_n - x_0)/n$ . Suppose that  $p_n(x)$  interpolates this data.

**Idea:** does

$$\int_{x_0}^{x_n} f(x) dx \approx \int_{x_0}^{x_n} p_n(x) dx?$$

We investigate the error in such an approximation below, but note that

$$\int_{x_0}^{x_n} p_n(x) dx = \int_{x_0}^{x_n} \sum_{k=0}^n f(x_k) \cdot L_{n,k}(x) dx \quad (1)$$

$$= \sum_{k=0}^n f(x_k) \cdot \int_{x_0}^{x_n} L_{n,k}(x) dx \quad (2)$$

$$= \sum_{k=0}^n w_k f(x_k), \quad (3)$$

where the coefficients

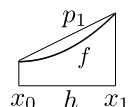
$$w_k = \int_{x_0}^{x_n} L_{n,k}(x) dx$$

$k = 0, 1, \dots, n$ , are independent of  $f$ . A formula

$$\int_a^b f(x) dx \approx \sum_{k=0}^n w_k f(x_k)$$

with  $x_k \in [a, b]$  and  $w_k$  independent of  $f$  for  $k = 0, 1, \dots, n$  is called a quadrature formula; the coefficients  $w_k$  are known as weights. The specific form (1)–(3), based on equally spaced points, is called a Newton–Cotes formula of order  $n$ .

**Examples: Trapezium Rule:**  $n = 1$  (also known as the trapezoid or trapezoidal rule):



A diagram showing a trapezium formed by the x-axis and a line segment connecting points (x0, 0) and (x1, p1). A curve labeled 'f' is shown below the line segment. The width of the trapezium is labeled 'h'.

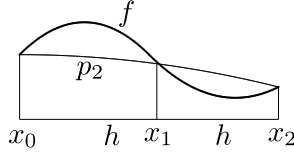
$$\int_{x_0}^{x_1} f(x) dx \approx \frac{h}{2} [f(x_0) + f(x_1)]$$

**Proof**

$$\begin{aligned} \int_{x_0}^{x_1} p_1(x) dx &= f(x_0) \int_{x_0}^{x_1} L_{1,0}(x) dx + f(x_1) \int_{x_0}^{x_1} L_{1,1}(x) dx \\ &= f(x_0) \int_{x_0}^{x_1} \frac{x - x_1}{x_0 - x_1} dx + f(x_1) \int_{x_0}^{x_1} \frac{x - x_0}{x_1 - x_0} dx \\ &= f(x_0) \frac{(x_1 - x_0)}{2} + f(x_1) \frac{(x_1 - x_0)}{2} \end{aligned}$$

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**Simpson's Rule:**  $n = 2$ :



$$\int_{x_0}^{x_2} f(x)dx \approx \frac{h}{3}[f(x_0) + 4f(x_1) + f(x_2)]$$

**Note:** The trapezium rule is exact if  $f \in \Pi_1$ , since if  $f \in \Pi_1$ , therefore  $p_1 = f$ . Similarly, Simpson's Rule is exact if  $f \in \Pi_2$ , since if  $f \in \Pi_2$ , therefore  $p_2 = f$ . The highest degree of polynomial exactly integrated by a quadrature rule is called the (polynomial) degree of accuracy (or degree of exactness).

**Error:** we can use the error in interpolation directly to obtain

$$\int_{x_0}^{x_n} [f(x) - p_n(x)]dx = \int_{x_0}^{x_n} \frac{\pi(x)}{(n+1)!} f^{(n+1)}(\xi(n))dx$$

so that

$$\int_{x_0}^{x_n} [f(x) - p_n(x)]dx \leq \frac{1}{(n+1)!} \max_{\xi \in [x_0, x_n]} |f^{(n+1)}(\xi)| \int_{x_0}^{x_n} |\pi(x)|dx, \quad (4)$$

which, e.g., for the trapezium rule,  $n = 1$ , gives

$$\left| \int_{x_0}^{x_1} f(x)dx - \frac{(x_1 - x_0)}{2} [f(x_0) + f(x_1)] \right| \leq \frac{(x_1 - x_0)^3}{12} \max_{\xi \in [x_0, x_1]} |f''(\xi)|.$$

In fact, we can prove a tighter result:

**Theorem.** Error in Trapezoidal Rule:

$$\left| \int_{x_0}^{x_1} f(x)dx - \frac{(x_1 - x_0)}{2} [f(x_0) + f(x_1)] \right| = \frac{(x_1 - x_0)^3}{12} f''(\xi)$$

for some  $\xi \in (x_0, x_1)$ . (And note equality)

**Proof.** Omitted (uses Integral Mean-Value Theorem).

For  $n > 1$ , (4) gives pessimistic bounds. But one can prove better results, e.g., using Taylor Series.

**Theorem.** Error in Simpson's Rule: if  $f'''$  is continuous on  $(x_0, x_2)$ , then

$$\left| \int_{x_0}^{x_2} f(x)dx - \frac{x_2 - x_0}{6} [f(x_0) + 4f(x_1) + f(x_2)] \right| = \frac{(x_2 - x_0)^5}{2880} f'''(\xi)$$

for some  $\xi \in (x_0, x_2)$ .

**Proof.** See, e.g., Süli and Mayers, Thm. 7.2.

**Note:** Simpson's Rule is exact if  $f \in \Pi_3$  since then  $f''' \equiv 0$ . (c.f. earlier statement viz.  $f \in \Pi_2$ ).

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## Composite Quadrature (optional material)

**Motivation:** we've seen oscillations in polynomial interpolation—the Runge phenomenon—for high-degree polynomials on equispaced grids.

**Idea:** split a required integration interval  $[a, b] = [x_0, x_n]$  into  $n$  equal intervals  $[x_{i-1}, x_i]$  for  $i = 1, \dots, n$ . Then use a **composite rule**:

$$\int_a^b f(x) \, dx = \int_{x_0}^{x_n} f(x) \, dx = \sum_{i=1}^n \int_{x_{i-1}}^{x_i} f(x) \, dx$$

in which each  $\int_{x_{i-1}}^{x_i} f(x) \, dx$  is approximated by quadrature.

Thus rather than increasing the degree of the polynomials to attain high accuracy, instead increase the number of intervals.

### Composite Trapezium Rule:

$$\begin{aligned} \int_{x_0}^{x_n} f(x) \, dx &= \sum_{i=1}^n \left[ \frac{h}{2} [f(x_{i-1}) + f(x_i)] - \frac{h^3}{12} f''(\xi_i) \right] \\ &= \frac{h}{2} [f(x_0) + 2f(x_1) + 2f(x_2) + \dots + 2f(x_{n-1}) + f(x_n)] + e_h^T \end{aligned}$$

where  $\xi_i \in (x_{i-1}, x_i)$  and  $h = x_i - x_{i-1} = (x_n - x_0)/n = (b - a)/n$ , and the error  $e_h^T$  is given by

$$e_h^T = -\frac{h^3}{12} \sum_{i=1}^n f''(\xi_i) = -\frac{nh^3}{12} f''(\xi) = -(b - a) \frac{h^2}{12} f''(\xi)$$

for some  $\xi \in (a, b)$ , using the Intermediate-Value Theorem  $n$  times. Note that if we halve the stepsize  $h$  by introducing a new point halfway between each current pair  $(x_{i-1}, x_i)$ , the factor  $h^2$  in the error will decrease by four.

Alternatively, divide  $[a, b]$  into  $2n + 1$  intervals:  $[a, b] = [x_0, x_{2n}]$ . Then:

### Composite Simpson's Rule:

$$\begin{aligned} \int_{x_0}^{x_{2n}} f(x) \, dx &= \sum_{i=1}^n \left[ \frac{h}{3} [f(x_{2i-2}) + 4f(x_{2i-1}) + f(x_{2i})] - \frac{(2h)^5}{2880} f''''(\xi_i) \right] \\ &= \frac{h}{3} [f(x_0) + 4f(x_1) + 2f(x_2) + 4f(x_3) + 2f(x_4) + \dots \\ &\quad + 2f(x_{2n-2}) + 4f(x_{2n-1}) + f(x_{2n})] + e_h^S \end{aligned}$$

where  $\xi_i \in (x_{2i-2}, x_{2i})$  and  $h = x_i - x_{i-1} = (x_{2n} - x_0)/2n = (b - a)/2n$ , and the error  $e_h^S$  is given by

$$e_h^S = -\frac{(2h)^5}{2880} \sum_{i=1}^n f''''(\xi_i) = -\frac{n(2h)^5}{2880} f''''(\xi) = -(b - a) \frac{h^4}{180} f''''(\xi)$$

for some  $\xi \in (a, b)$ . Note that if we halve the stepsize  $h$  by introducing a new point halfway between each current pair  $(x_{i-1}, x_i)$ , the factor  $h^4$  in the error will decrease by sixteen.

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**Adaptive (or automatic) procedure:** if  $S_h$  is the value given by composite Simpson's rule with a stepsize  $h$ , then

$$S_h - S_{\frac{1}{2}h} \approx -\frac{15}{16}e_h^S.$$

This suggests that if we wish to compute  $\int_a^b f(x) dx$  with an absolute error  $\varepsilon$ , we should compute the sequence  $S_h, S_{\frac{1}{2}h}, S_{\frac{1}{4}h}, \dots$  and stop when the difference, in absolute value, between two consecutive values is smaller than  $\frac{16}{15}\varepsilon$ . That will ensure that (approximately)  $|e_h^S| \leq \varepsilon$ .

Sometimes much better accuracy may be obtained: for example, as might happen when computing Fourier coefficients, if  $f$  is periodic with period  $b-a$  so that  $f(a+x) = f(b+x)$  for all  $x$ .

### Matlab:

```
>> help adaptive_simpson
```

```
ADAPTIVE_SIMPSON Adaptive (or automatic) Simpson's rule.
```

```
S = ADAPTIVE_SIMPSON(F,A,B,NMAX,TOL) computes an approximation  
to the integral of F on the interval [A,B]. It will take a  
maximum of NMAX steps and will attempt to determine the  
integral to a tolerance of TOL.
```

```
The function uses an adaptive Simpson's rule, as described  
in lectures.
```

```
>> f = @(x) sin(x);
```

```
>> adaptive_simpson(f, 0, pi, 100, 1e-7);
```

```
Step 1 integral is 2.0943951024, with error estimate 2.0944.
```

```
Step 2 integral is 2.0045597550, with error estimate 0.089835.
```

```
Step 3 integral is 2.0002691699, with error estimate 0.0042906.
```

```
Step 4 integral is 2.0000165910, with error estimate 0.00025258.
```

```
Step 5 integral is 2.0000010334, with error estimate 1.5558e-05.
```

```
Step 6 integral is 2.0000000645, with error estimate 9.6884e-07.
```

```
Successful termination at iteration 7:
```

```
The integral is 2.0000000040, with error estimate 6.0498e-08.
```

```
>> g = @(x) sin(sin(x));
```

```
>> fplot(g, [0 pi])
```

```
>> adaptive_simpson(g, 0, pi, 100, 1e-7);
```

```
Step 1 integral is 1.7623727094, with error estimate 1.7624.
```

```
Step 2 integral is 1.8011896009, with error estimate 0.038817.
```

```
Step 3 integral is 1.7870879453, with error estimate 0.014102.
```

```
Step 4 integral is 1.7865214631, with error estimate 0.00056648.
```

```
Step 5 integral is 1.7864895607, with error estimate 3.1902e-05.
```

```
Step 6 integral is 1.7864876112, with error estimate 1.9495e-06.
```

```
Step 7 integral is 1.7864874900, with error estimate 1.2118e-07.
```

```
Successful termination at iteration 8:
```

```
The integral is 1.7864874825, with error estimate 7.5634e-09.
```