

# Learning to Adapt in Dynamic, Real-World Environments Through Meta-Reinforcement Learning



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## Problem

Our Deep-RL agents mostly operate in the regime where they are very good at succeeding in specific settings, but fail in the face of any changes or new settings at run time.

- Need **adaptation**

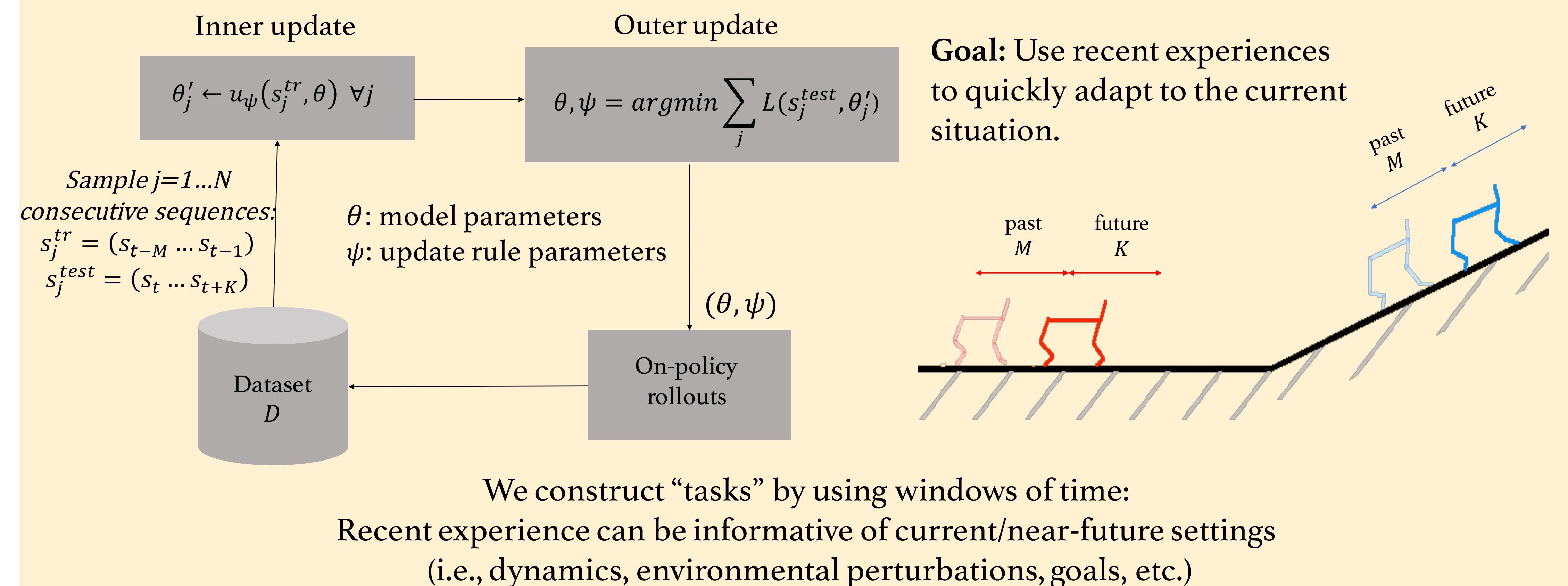
Large function approximators cannot naively be updated online, using small amount of data

- Need **meta-learning** to allow for fast adaptation

We want to adapt to dynamics changes, and also, collecting training data is expensive

- Use a **sample-efficient**, model-based reinforcement learning algorithm

## Train time: Learning to Adapt



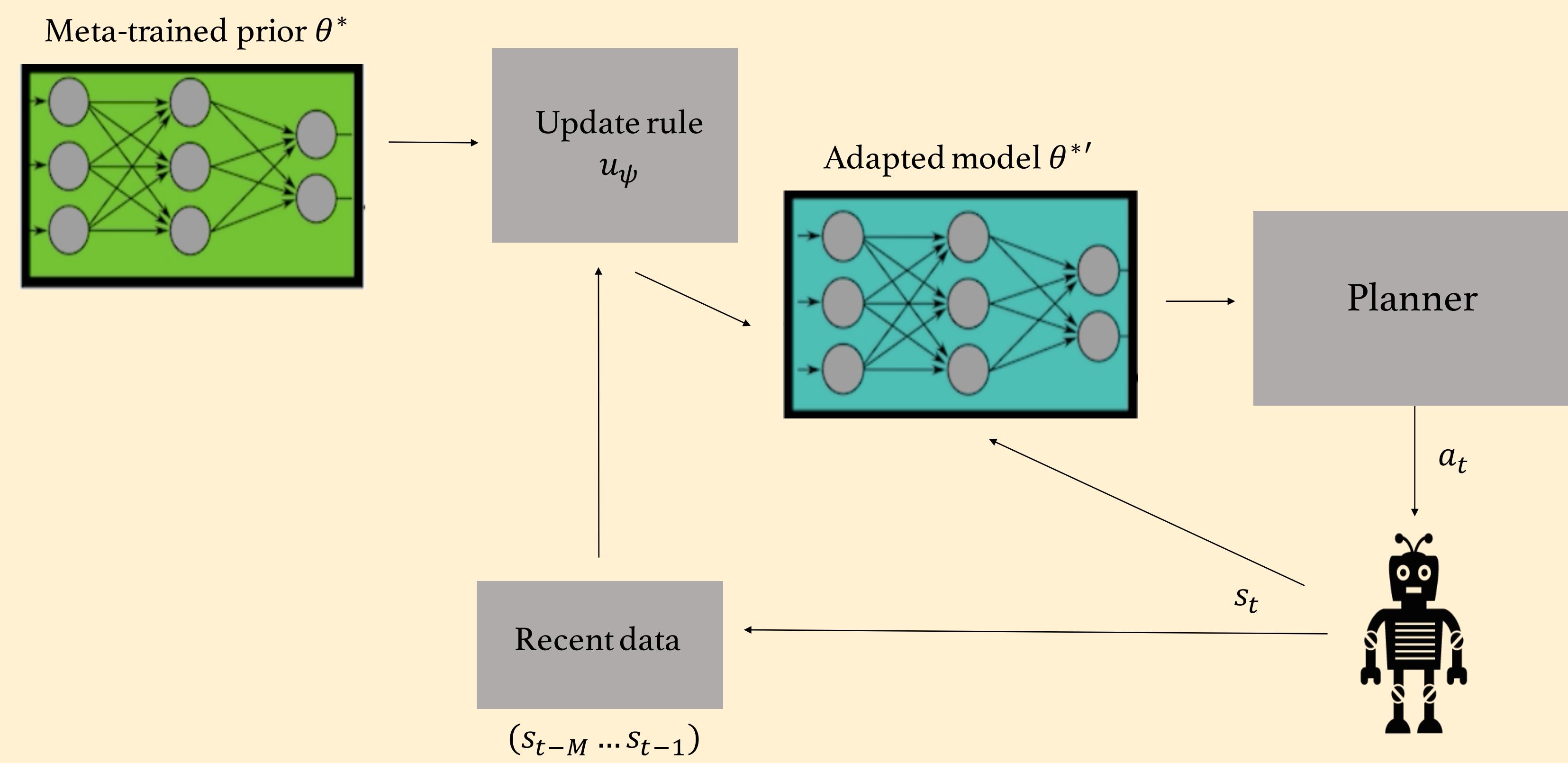
## Background: Meta-Learning

**Goal:** find optimal parameters  $(\theta, \psi)$  such that updated model parameters  $\theta'$  produced by the update rule  $u_\phi$  optimize our objective, across tasks T:

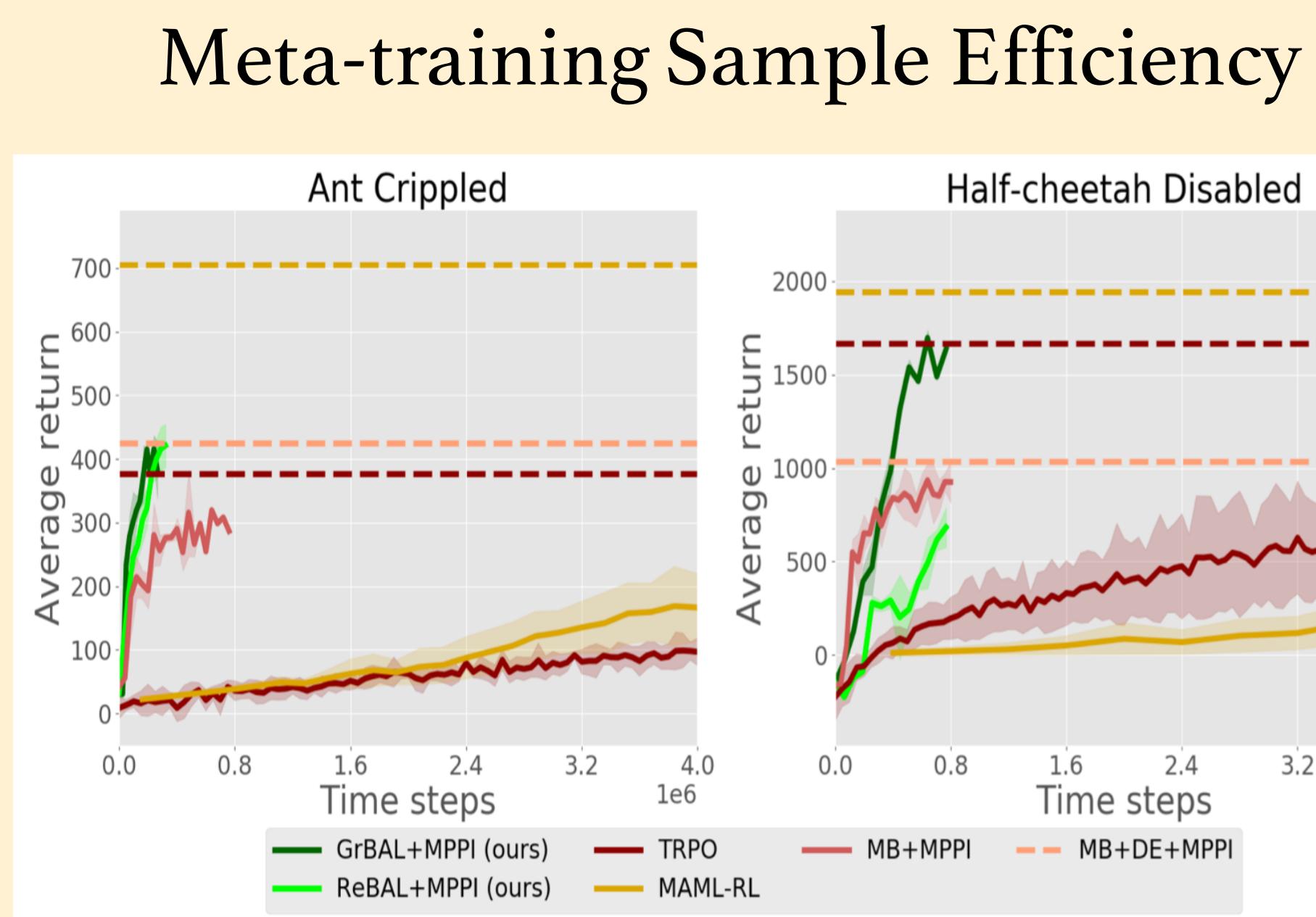
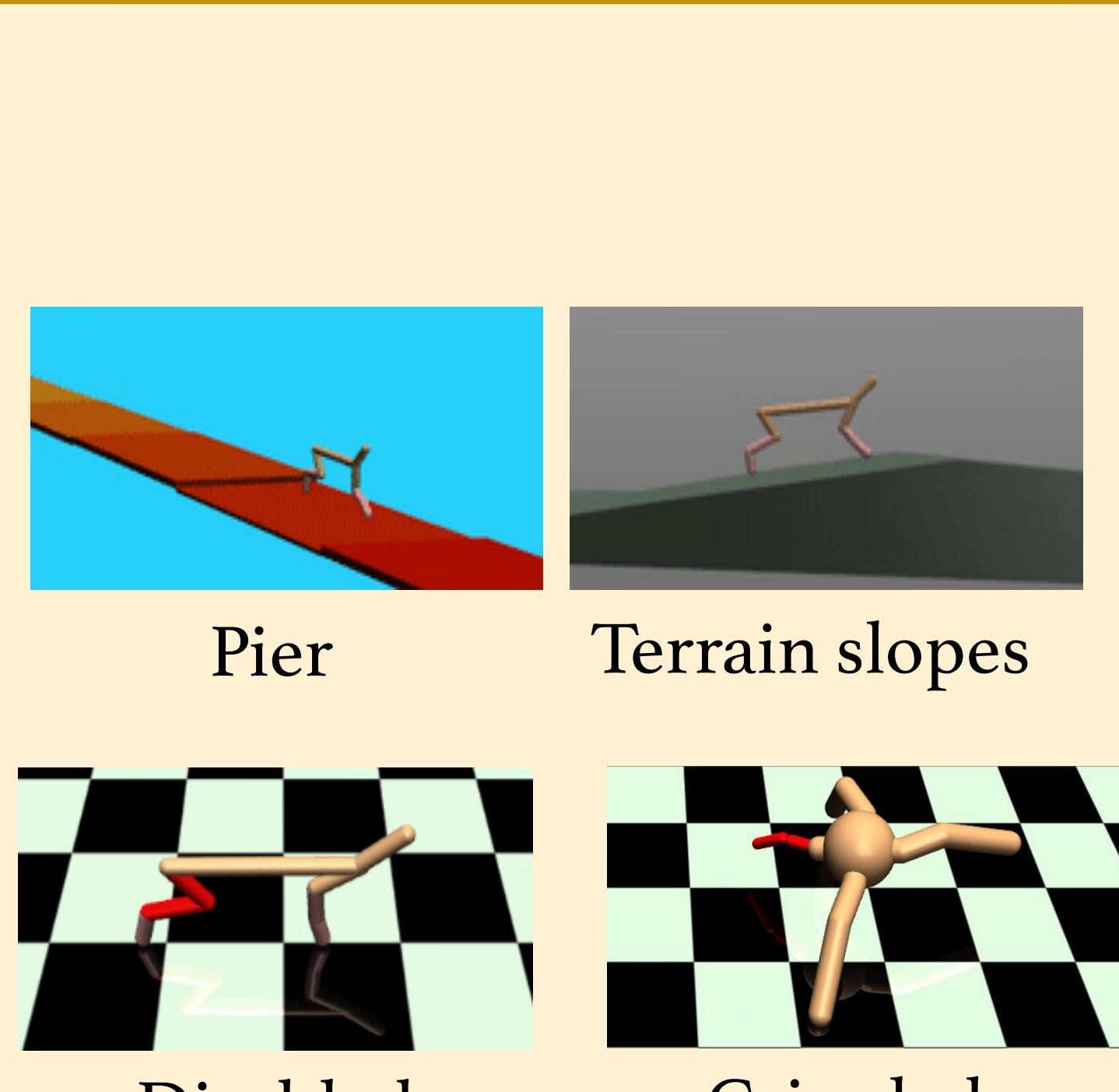
$$\min_{\theta, \psi} \sum_T L(D_T^{test}, \theta') \text{ s.t. } \theta' = u_\psi(D_T^{tr}, \theta)$$

Update rule  $u$  uses recent data  $D_T^{tr}$  from a given task to adapt for other data  $D_T^{test}$  from the same task.

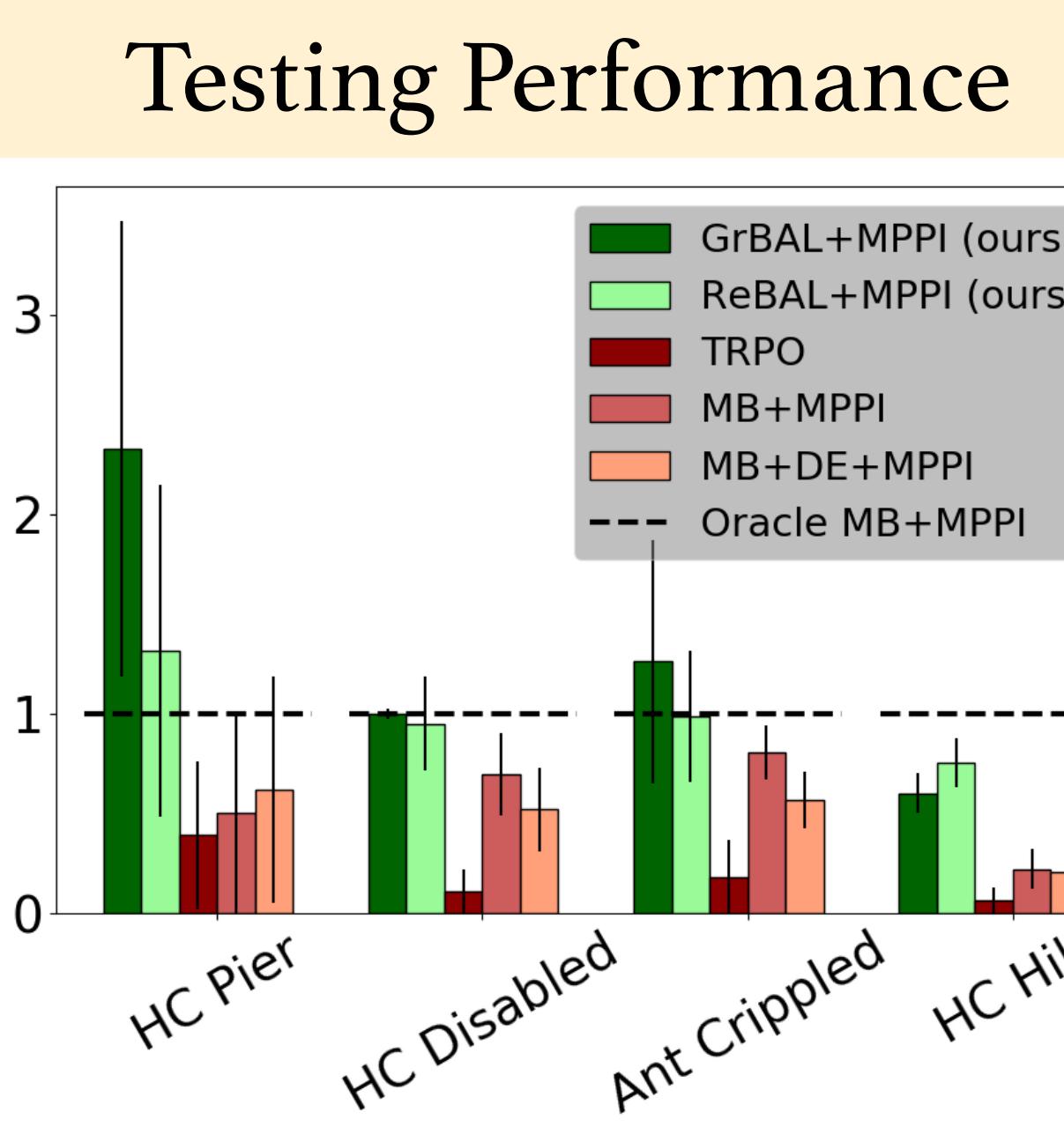
## Test time: Model-Based Meta-RL



## Simulation Results

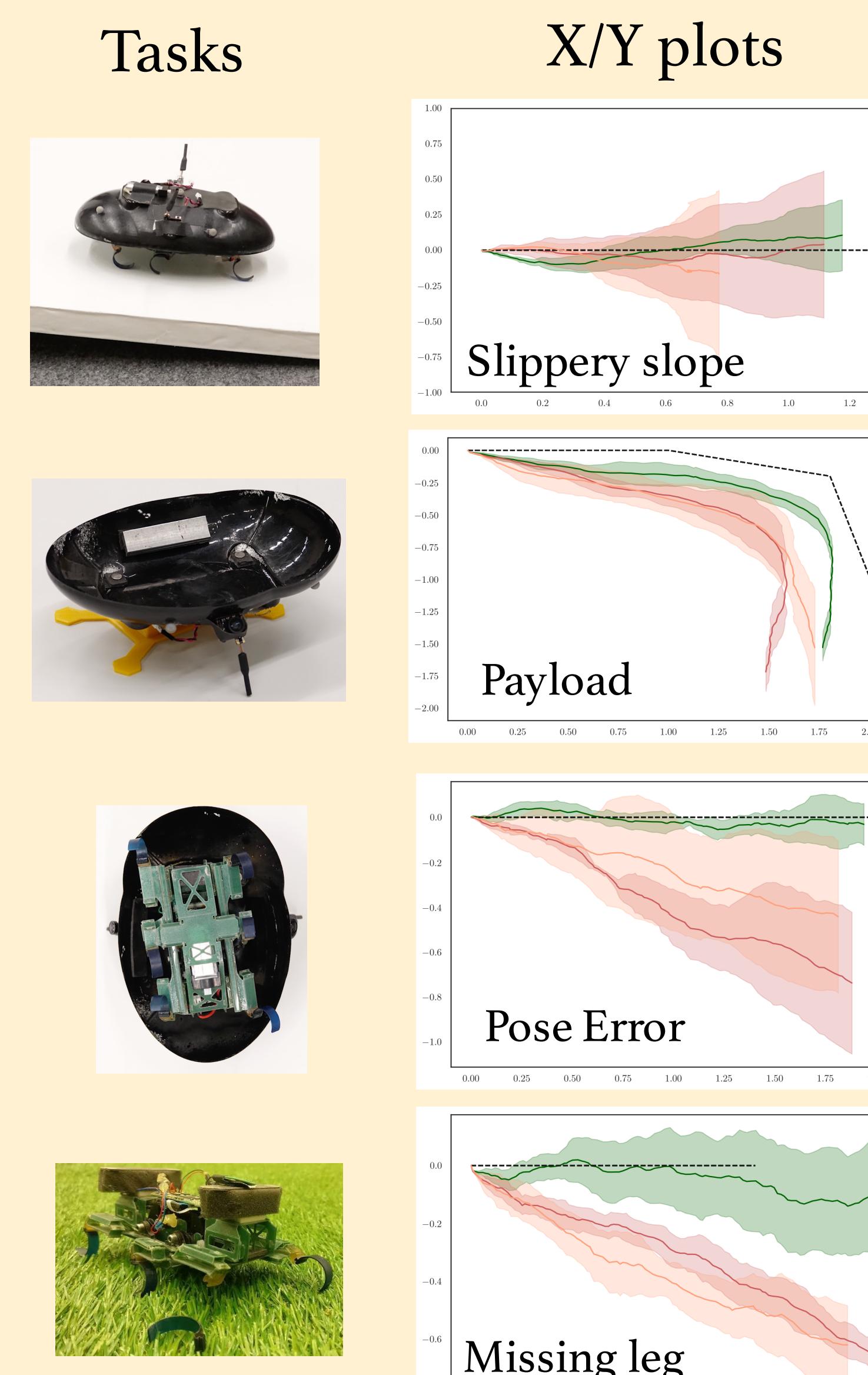


**Sample efficiency:** requires 1000x less meta-training data than the model-free methods, and achieves higher performance than the model-based methods.

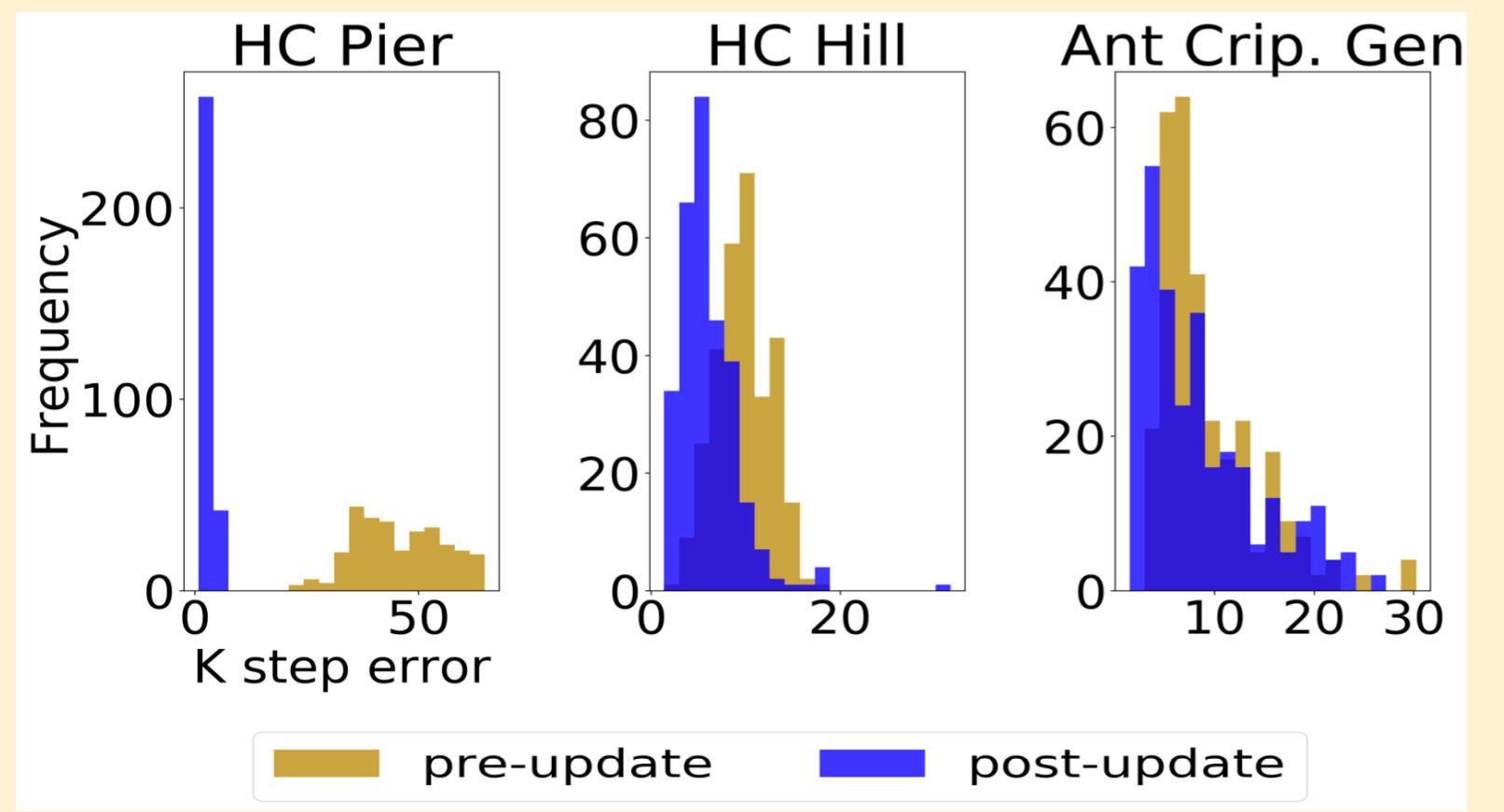


**Comparison:** Outperforms previous model-free (TRPO), model-based (MB), and adaptive (MB+DE) model-based methods.

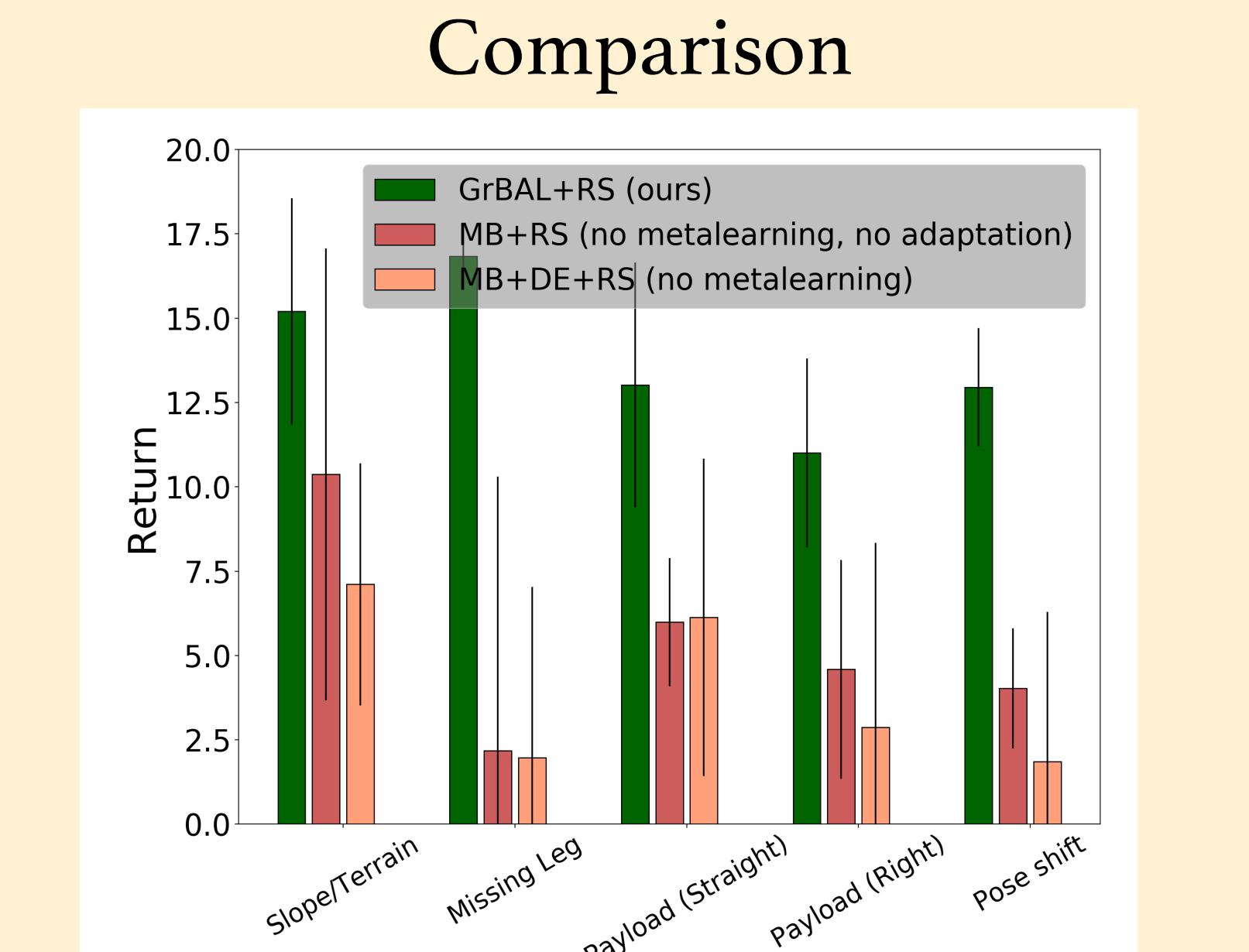
## Real-world Results



## Model Adaptation



**Model accuracy:** Model prediction errors are reduced after model adaptation.



## Takeaways

- Use of meta-learning to enable **fast adaptation** (i.e. k-shot) of large function approximators
- **Sample-efficient** meta-training via our model-based formulation
- Local fine-tuning of a prior precludes need for a globally accurate model and allows for online adaptation to changes