Hough Transform for Circles

- ▶ Equation...
- ▶ Centered at (x_0, y_0) with radius r

$$(x-x_0)^2 + (y-y_0)^2 = r^2$$

- ▶ Three unknowns... $x_0 y_0 r$
- ▶ Three dimensional parameter space
- Conceptually...?

How to simplify this algorithm

• Use of gradient direction, θ

$$x_0 = x - r\cos\theta$$

$$y_0 = y - r\sin\theta$$

▶ Algorithm?...

Hough transform

- Can be applied to any parametric representation f (x, a)=0
- Initialize accumulator array, A to zeros...
- A is |a| dimensional
- For each pixel \mathbf{x} , and each \mathbf{a} such that $f(\mathbf{x},\mathbf{a})=0$, $A[\mathbf{a}]=A[\mathbf{a}]+1$
- Local maxima of A corresponds to curves f in image.

Finding more than one curve

- Parameter space will have multiple maxima
- ▶ Threshold
- Or use better methods to find maximum points

Hough Transform

- ▶ Given parametric representation of a curve
 - LINE: $p = x cos \theta + y sin \theta$
 - CIRCLE: $x_0 = x r \cos\theta$

$$y_0 = y - r \sin\theta$$

▶ ELLIPSE: $x_0 = x - a \cos\theta$

$$y_0 = y - b \sin\theta$$

• GENERAL: $f(\mathbf{x}, \mathbf{a}) = 0$

Hough Transform

- ▶ Initialize **A** (accumulator array) to all zeros
- ▶ A is |a| dimensional
- For each pixel \mathbf{x} , and each \mathbf{a} such that $f(\mathbf{x},\mathbf{a})=0,A[\mathbf{a}]=A[\mathbf{a}]+I$
- \blacktriangleright Local maxima of A corresponds to curves f in image.

Generalized Hough Transform

- ▶ To find arbitrary shapes in images
- Shapes which do not have an easy parametric representation

Centroid and Area

The average location of all pixels of all pixels in a region R

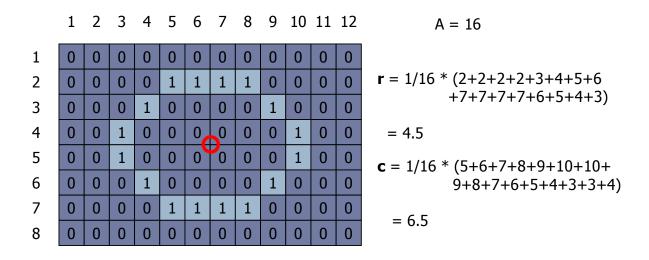
$$\overline{r} = \frac{1}{A} \sum_{(r,c) \in R} r$$

$$\bar{c} = \frac{1}{A} \sum_{(r,c) \in R} c$$

where A is the area of region R

$$A = \sum_{(r,c)\in R} 1$$

Example



Generalized Hough Transform

Training

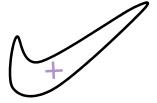
A representation of shape of interest is built in the form of an R-Table

Detection

Using R-Table, a given shape is matched to the shape of interest

GHT - Training

▶ Given the shape of interest

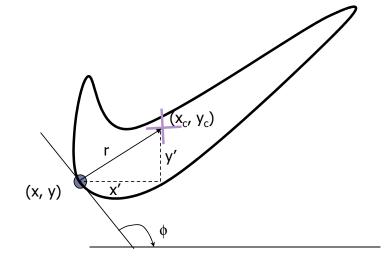


Find Centroid (x_c, y_c) of shape

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GHT - Training

- Find r = (x', y') for each edge point
- $y_c = y + y'$



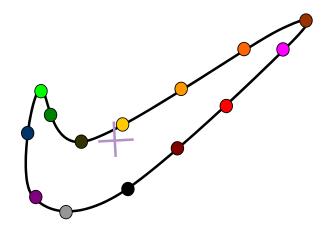
\$\phi\$ is the angle tangent at (x,y) makes with x-axis

GHT - Training

▶ R-Table is indexed by ♦

ϕ_1	$r_1^1, r_2^1, r_3^1, \dots, r_{m_1}^1$
ϕ_2	$r_1^2, r_2^2, r_3^2, \dots, r_{m_2}^2$
ϕ_3	$r_1^3, r_2^3, r_3^3, \dots, r_{m_3}^3$
•	•
•	•
•	•

Example - Training



ф=0	0
ф=45	
ф=90	
ф=135	
ф=180	• 0
φ=225	000
ф=270	
ф=315	

Detection

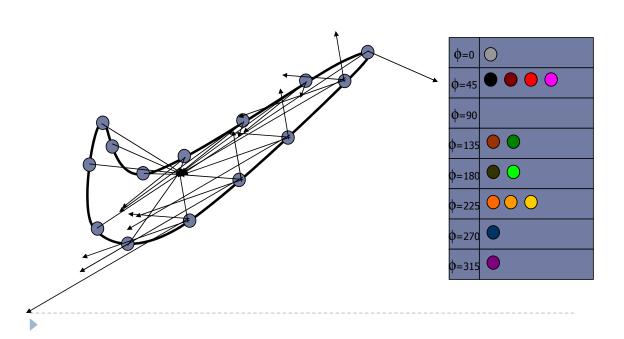
- Go to each (x,y) in image
- Find ♦
- For corresponding entry in R Table
- Find all possible locations of centriods

$$\mathbf{x}_{c} = \mathbf{x} + \mathbf{x}'$$

$$y_c = y + y'$$

Increment centroid accumulator by 1

Detection



GHT - Algorithm

- Quantize parameter space $P[x_{cmin}, ..., x_{cmax}, y_{cmin}, ..., y_{cmax}]$
- 2. For each edge point (x,y)Compute ϕ from gradient direction For each table entry in row ϕ $x_c = x + x'$

$$x_c = x + x'$$

 $y_c = y + y'$
 $P[x_c, y_c] = P[x_c, y_c] + 1;$

3. Find local maxima in P

GHT - Questions

- Uniqueness of R-Table?
- ▶ Invariance to translation?
- Invariance to rotation?
- Invariance to scaling?

Rotation and Scaling Invariance

▶ Rotation invariance...

$$x'' = x' \cos\theta + y' \sin\theta$$
$$y'' = -x' \sin\theta + y' \cos\theta$$

Rotation + Scaling invariance

$$x'' = s_x (x' \cos\theta + y' \sin\theta)$$

$$y'' = s_y (-x' \sin\theta + y' \cos\theta)$$

Substitute in

$$x_c = x + x'$$

 $y_c = y + y'$

To get

$$x_c = x + s_x (x' \cos\theta + y' \sin\theta)$$

 $y_c = y + s_y (-x' \sin\theta + y' \cos\theta)$

▶ Substitute these values of (x_c, y_c) in GHT algorithm