

5 AVL trees: deletion

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Definition of AVL trees

Definition: A binary search tree is called **AVL tree** or **height-balanced tree**, if for each node v the **height of the right subtree** $h(T_r)$ of v and the **height of the left subtree** $h(T_l)$ of v **differ by at most 1**.

Balance factor:

$$bal(v) = h(T_r) - h(T_l) \in \{-1, 0, +1\}$$

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Theory 1 - AVL trees: deletion

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Deletion from an AVL tree

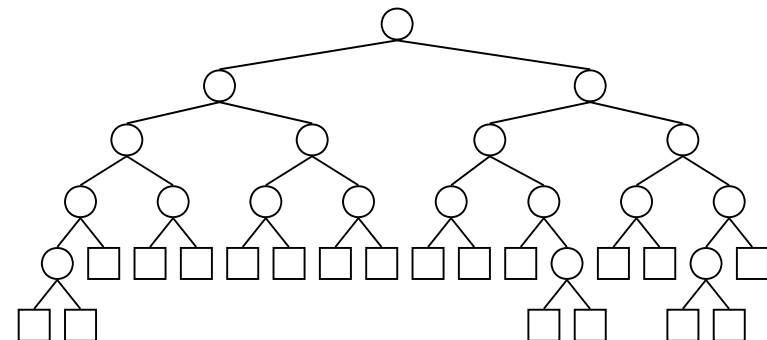
- We proceed similarly to standard search trees:
 1. Search for the key to be deleted.
 2. If the key is not contained, we are done.
 3. Otherwise we distinguish three cases:
 - (a) The node to be deleted has **no internal nodes as its children**.
 - (b) The node to be deleted has **exactly one internal child node**.
 - (c) The node to be deleted has **two internal children**.
- After deleting a node the AVL property may be violated (similar to insertion).
- This must be fixed appropriately.

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Example

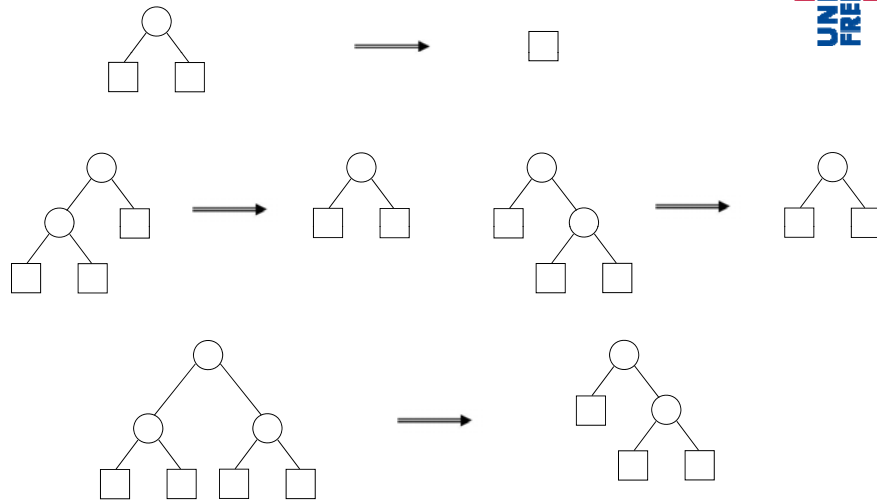


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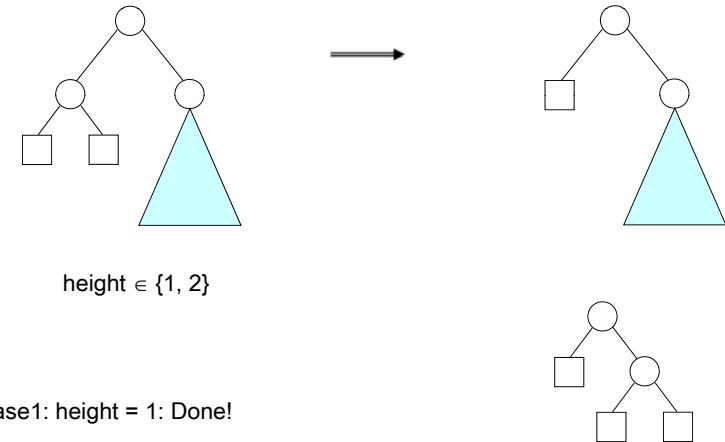
Theory 1 - AVL trees: deletion

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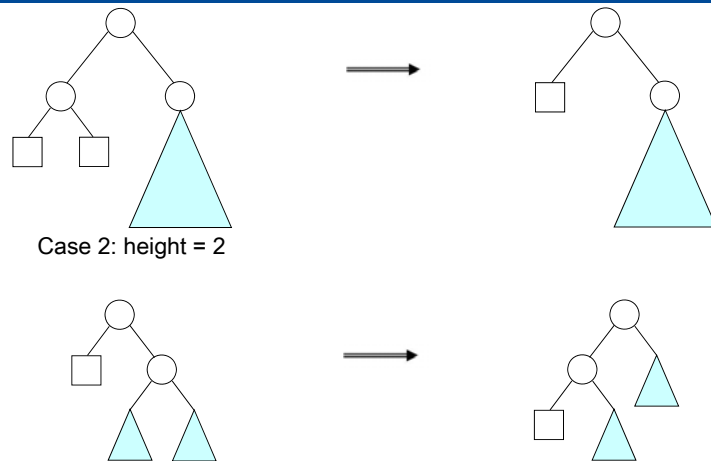
Node has only leaves at children



Node has only leaves at children

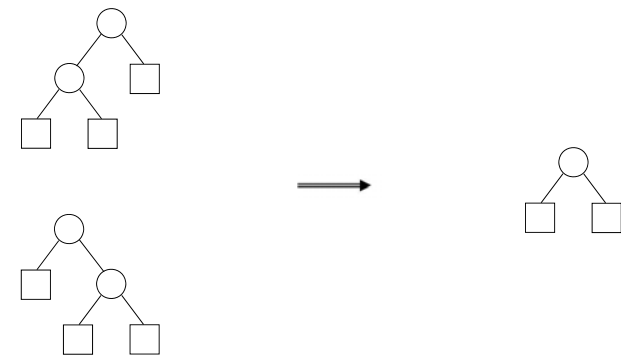


Node has only leaves at children



Note: height may have decreased by 1!

Node has one internal node as a child



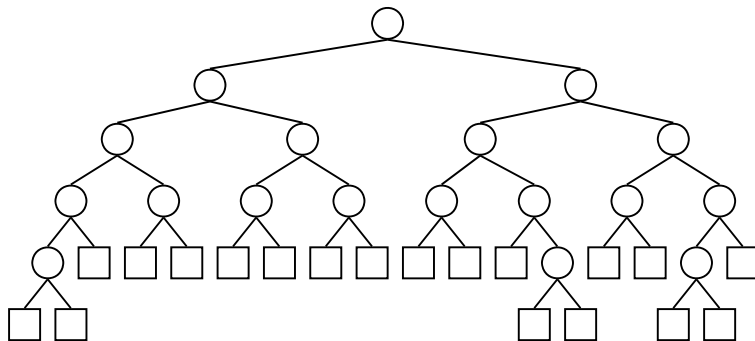
Node has two internal nodes as children

- First we proceed just like we do in standard search trees:
 1. Replace the content of the node to be deleted p by the content of its **symmetrical successor** q .
 2. Then delete node q .
- Since q can have at most one internal node as a child (the right one), **cases 1 and 2 apply for q** .

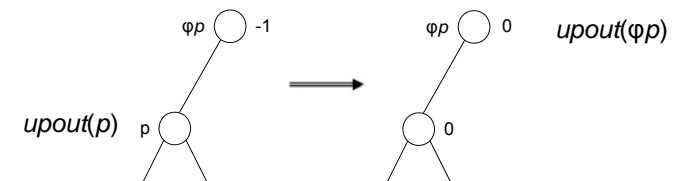
The method *upout*

- The method *upout* works similarly to *upin*.
- It is called recursively along the search path and adjusts the balance factors via rotations and double rotations.
- When *upout* is called for a node p , we have (see above):
 1. $bal(p) = 0$
 2. The height of the subtree rooted in p has decreased by 1.
- upout* will be called recursively as long as these conditions are fulfilled (invariant).
- Again, we distinguish 2 cases, depending on whether p is the left or the right child of its parent ϕp .
- Since the two cases are symmetrical, we only consider the case where p is the left child of ϕp .

Example

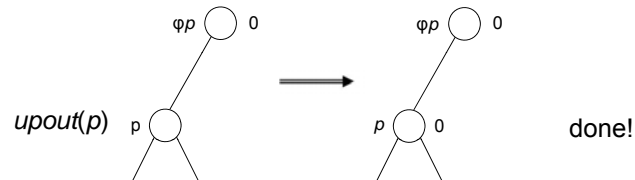


Case 1.1: p is the left child of ϕp and $bal(\phi p) = -1$



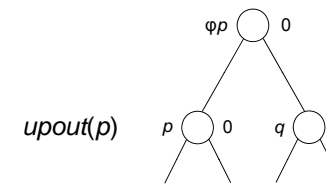
- Since the height of the subtree rooted in p has decreased by 1, the balance factor of ϕp changes to 0.
- By this, the height of the subtree rooted in ϕp has also decreased by 1 and we have to call *upout*(ϕp) (the invariant now holds for ϕp).

Case 1.2: p is the left child of ϕp and $bal(\phi p) = 0$



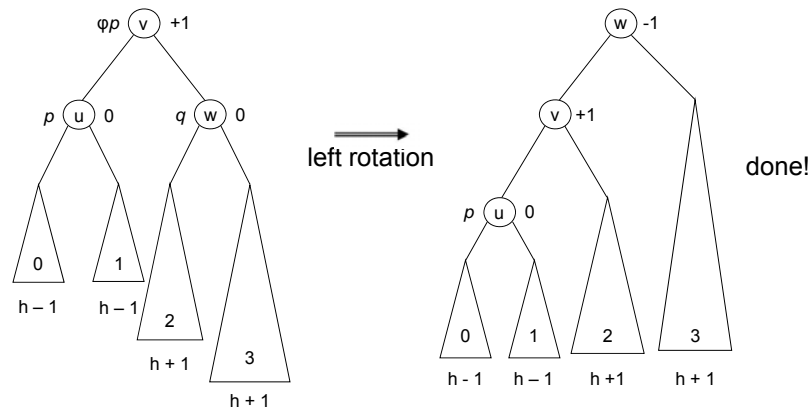
- Since the height of the subtree rooted in p has decreased by 1, the balance factor of ϕp changes to 1.
- Then we are done, because the height of the subtree rooted in ϕp has not changed.

Case 1.3: p is the left child of ϕp and $bal(\phi p) = +1$

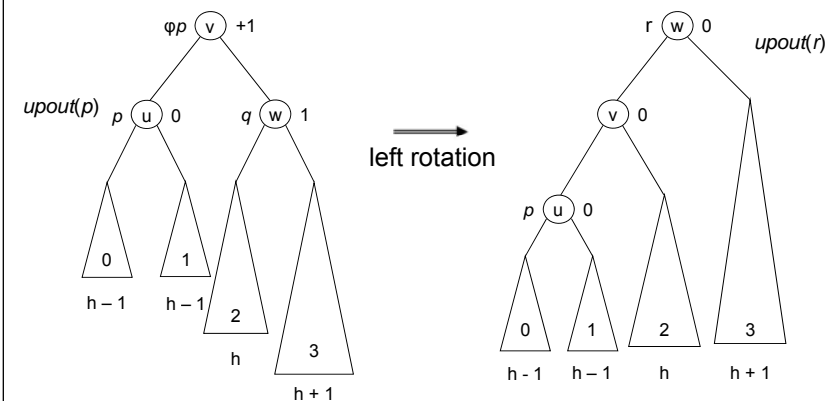


- Then the right subtree of ϕp was higher (by 1) than the left subtree before the deletion.
- Hence, in the subtree rooted in ϕp the AVL property is now violated.
- We distinguish three cases according to the balance factor of q .

Case 1.3.1: $bal(q) = 0$

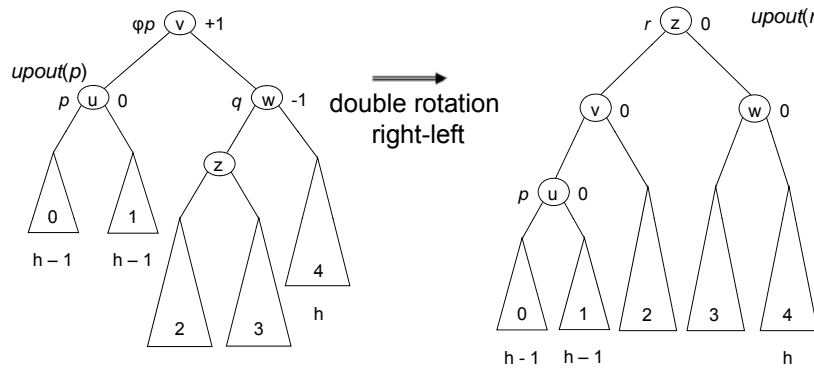


Case 1.3.2: $bal(q) = +1$



- Again, the height of the subtree has decreased by 1, while $bal(r) = 0$ (invariant).
- Hence we call $upout(r)$.

Case 1.3.3: $bal(q) = -1$



- Since $bal(q) = -1$, one of the trees 2 or 3 must have height h .
- Therefore, the height of the complete subtree has decreased by 1, while $bal(r) = 0$ (invariant).
- Hence, we again call $upout(r)$.

Observation

- Unlike insertions, deletions may cause recursive calls of *upout* after a double rotation.
- Therefore, in general a single rotation or double rotation is not sufficient to rebalance the tree.
- There are examples where for all nodes along the search path rotations or double rotations must be carried out.
- Since $h \leq 1.44 \dots \log_2(n) + 1$, we may conclude that the deletion of a key from an AVL tree with n keys can be carried out in at most $O(\log n)$ steps.
- AVL trees are a *worst-case efficient* data structure for finding, inserting and deleting keys.