

Welcome to Computer Vision



# Computer Vision

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Dr. Muhammad Tahir

DEPARTMENT OF COMPUTER SCIENCE,  
FAST-NUCES, Peshawar

# Course Details

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**LECTURES:** Monday  
& Wednesday

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**TIMINGS:**  
9:30 am – 11:00 am

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**MY OFFICE:**

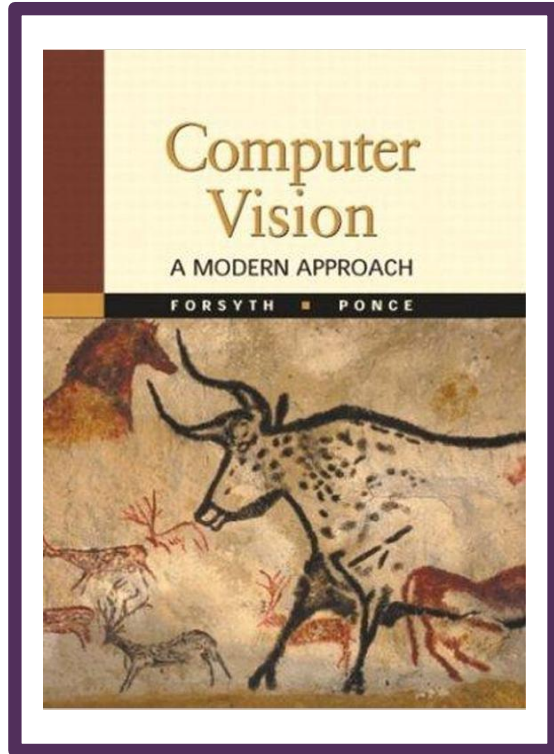
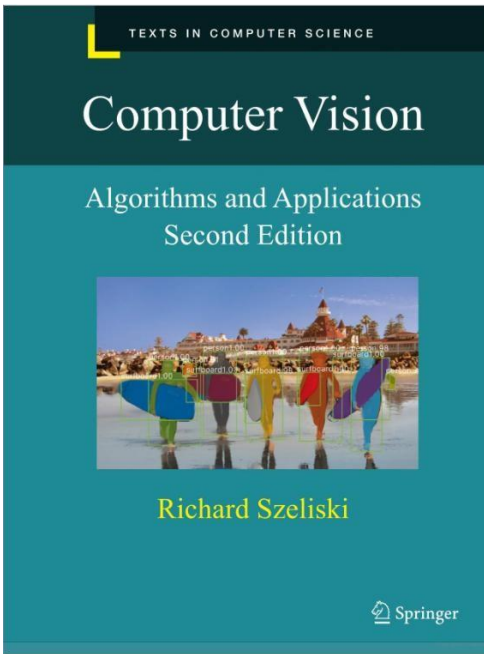
**OFFICE HOURS:**

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**EMAIL:** [m.tahir@nu.edu.pk](mailto:m.tahir@nu.edu.pk)

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# References

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The material in these slides are based on:

1

Rick Szeliski's book: [Computer Vision: Algorithms and Applications](#)

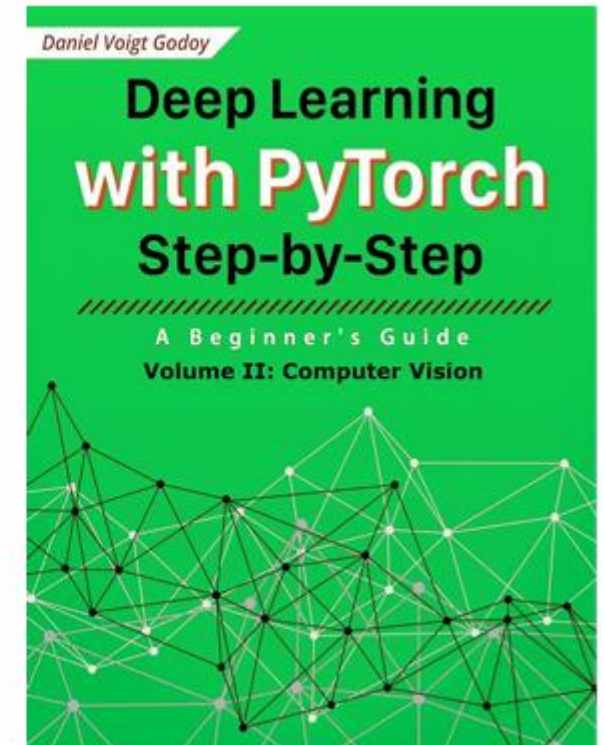
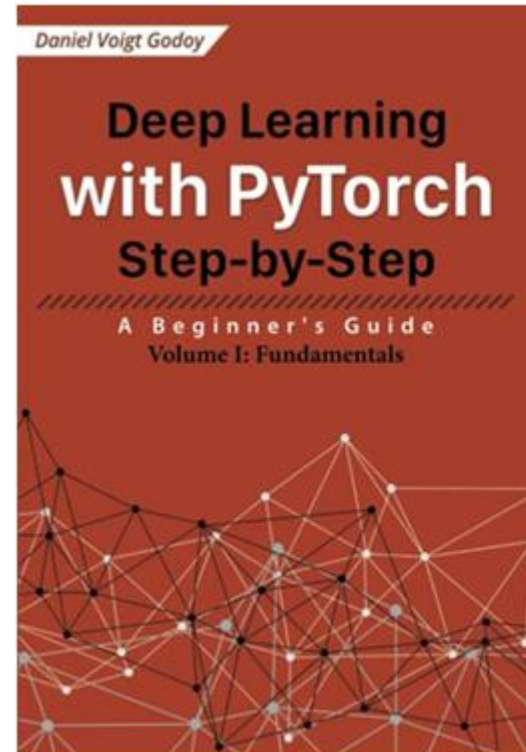
2

Forsythe and Ponce: [Computer Vision: A Modern Approach](#)

# Recommended Books

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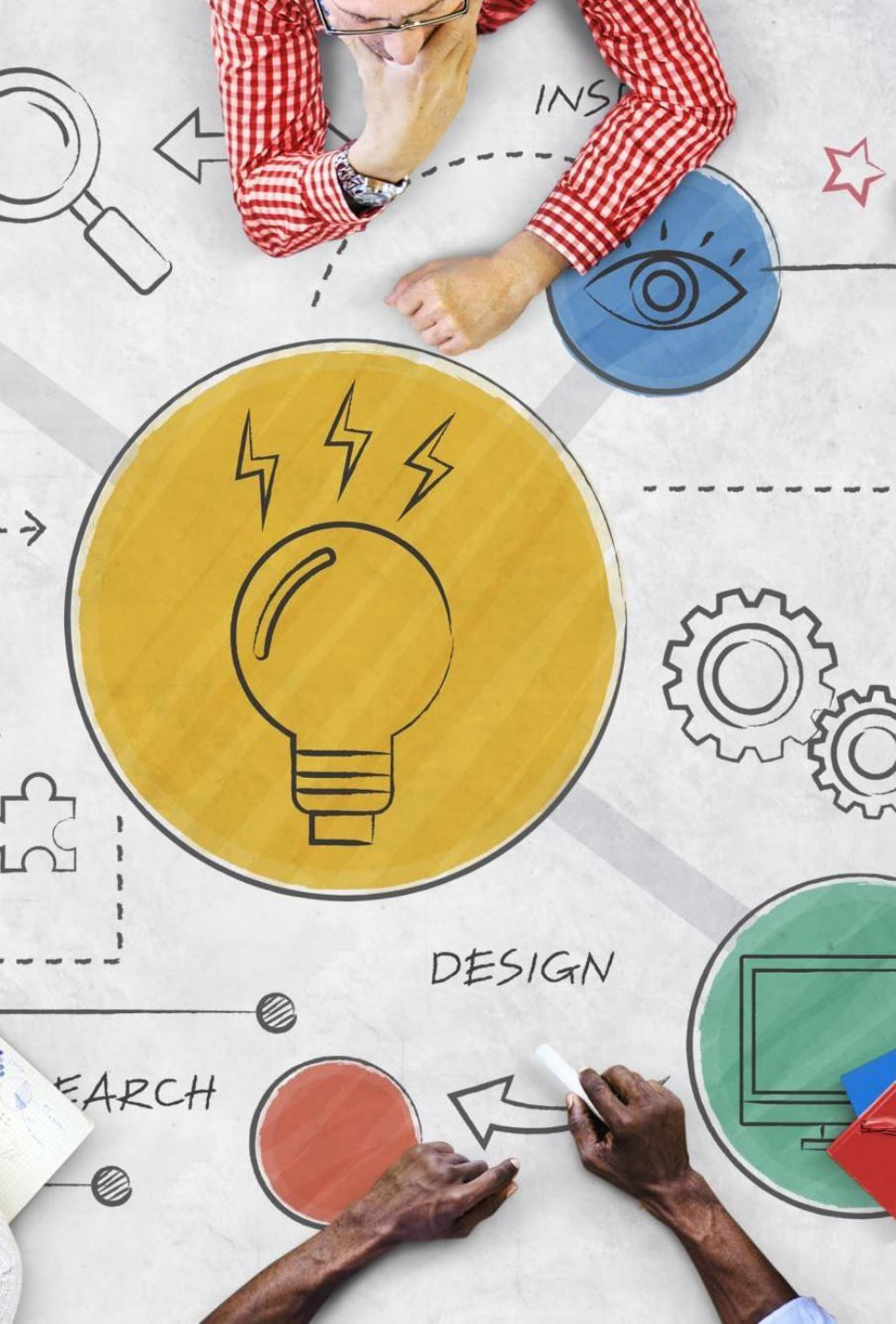
Deep Learning with PyTorch Step-by-Step by Daniel Voigt Godoy



# Course Learning Outcomes

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No	CLO (Tentative)	Domain	Taxonomy Level	PLO
1	Understanding basics of Computer Vision: algorithms, tools, and techniques	Cognitive	2	
2	Develop solutions for image/video understanding and recognition	Cognitive	3	
3	Design solutions to solve practical Computer Vision problems	Cognitive	3	



# Outline

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## Image Formation

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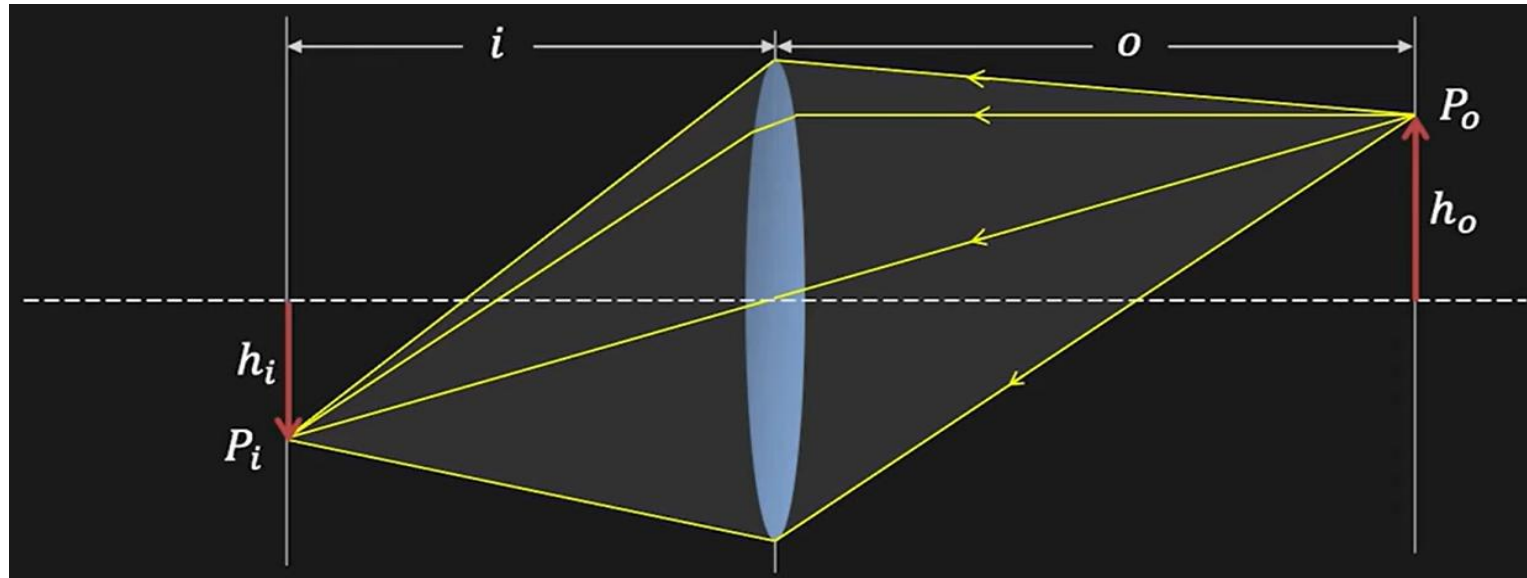
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# Image Magnification due to Lens



# Image Magnification due to Lens

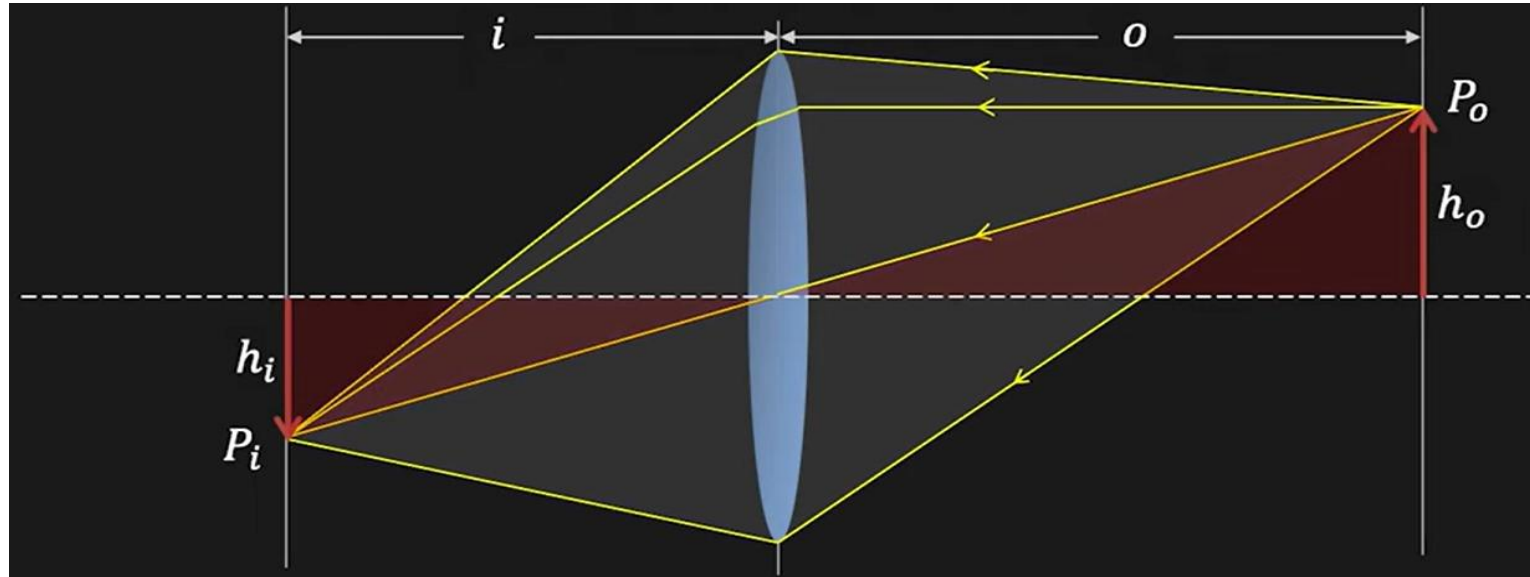


So, **magnification** is defined as  $h_i$  divided by  $h_o$

$$m = \frac{h_i}{h_o}$$

- The distance of the object from the lens is  $o$
- The distance of the image from the lens is  $i$
- The height of the object is  $h_o$
- We want to know what is the height of the image  $h_i$

# Image Magnification due to Lens

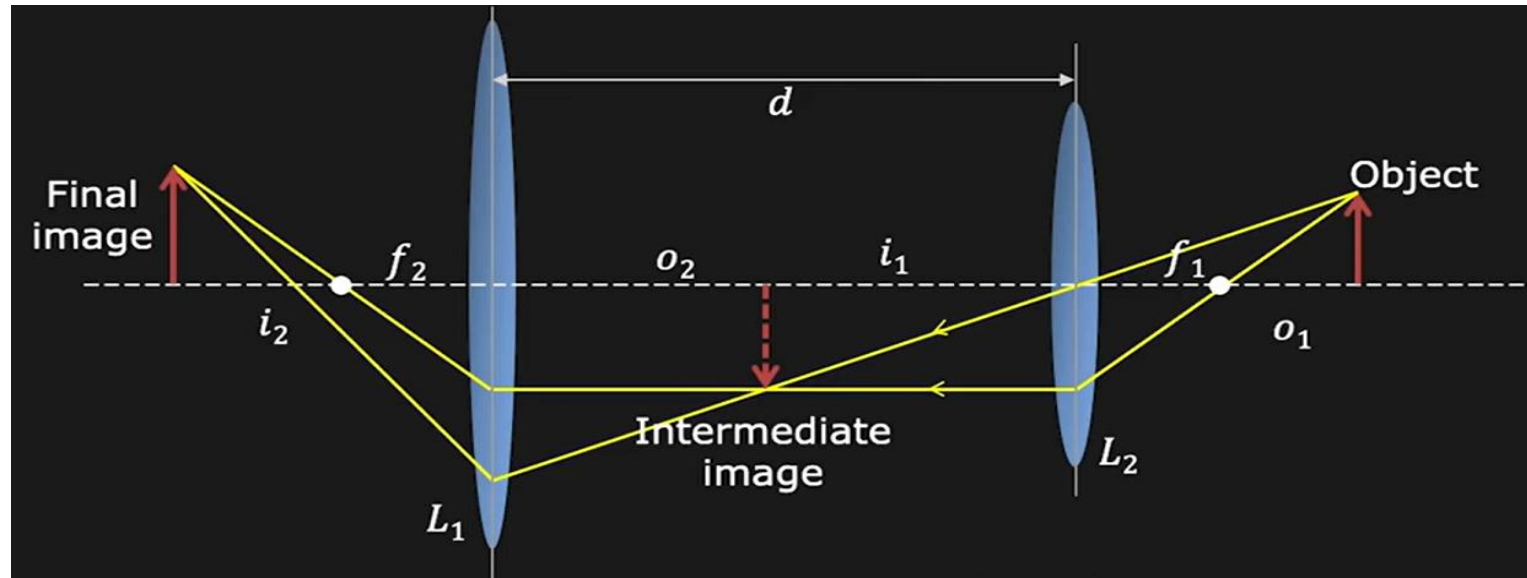


- Consider the two similar triangles, then  $\frac{h_i}{h_o} = \frac{i}{o}$

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# Two Lens System

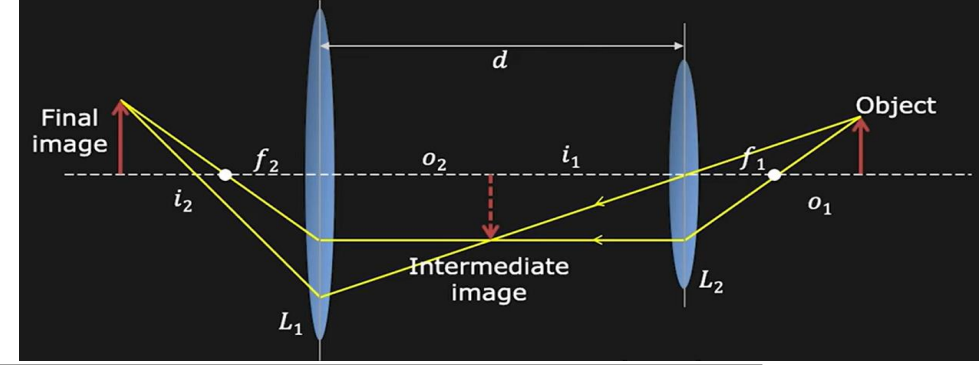
# Two Lens System



- The magnification of a lens system can be changed by using multiple lenses.

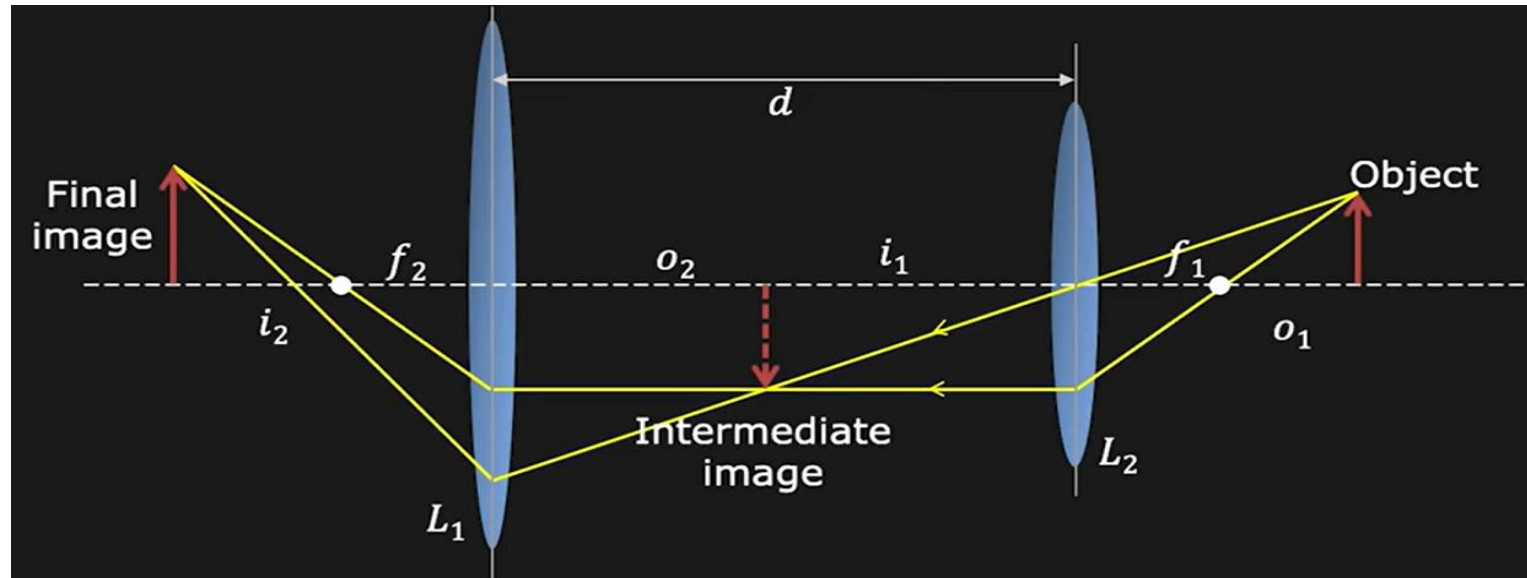


# Two Lens System



- Consider the two-lens system where we have lens  $L_1$  and  $L_2$
- Object is placed at distance  $o_1$  from  $L_2$ , which is imaged as an **intermediate image** between  $L_1$  and  $L_2$
- The intermediate image is a new object for the final image that is formed at distance  $i_2$  from  $L_1$
- So, the magnification of the complete system is a **magnification due to lens  $L_2$**  times **the magnification due to lens  $L_1$**
- So,  $m = \frac{i_2}{o_2} \times \frac{i_1}{o_1}$

# Two Lens System



- No need to change the distance between the object and the image plane.
- Instead, the effective magnification of the complete system is achieved by moving the lenses  $L_1$  and  $L_2$ . That is the process of zooming.

**Zooming:** Move lenses to change magnification

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# Aperture of Lens

# Aperture of Lens



- Aperture is the light receiving area of lens, indicated by lens **diameter**.



# Aperture of Lens

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- Aperture can be **reduced / increased** to control image brightness

# f-number (f-stop, f-ratio) of Lens

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- The aperture of a lens can be expressed **as a fraction of focal length** of the lens that is called the *f – number* represented here by  $N$ .

$$\text{Aperture: } D = \frac{f}{N}$$

$$f - \text{Number: } N = \frac{f}{D}$$

- Example:** A 50 mm focal length,  $\frac{f}{1.8}$  lens implies:
  - $N = 1.8$  ( $D = 27.8 \text{ mm}$ ) when aperture is fully open



# $f$ – number (f-stop, f-ratio) of Lens



- $f$  – number goes up, the **diameter** goes down
- The  $f$  – number tells you **how “open” or “closed”** the camera lens is.
  - A **small**  $f$  – number → large aperture (wide opening) → more light enters.
  - A **large**  $f$  – number → small aperture → less light enters.

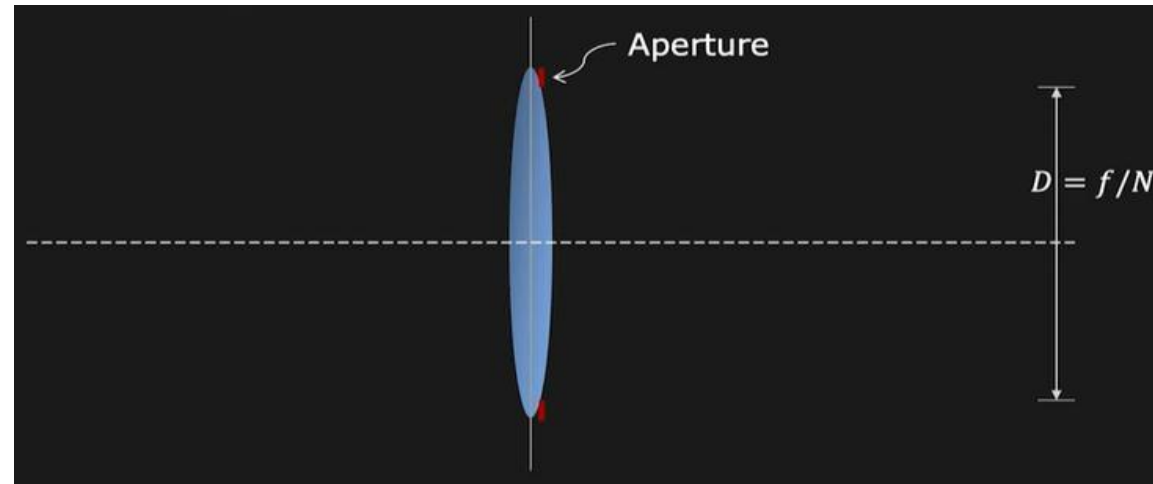
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# Lens Defocus



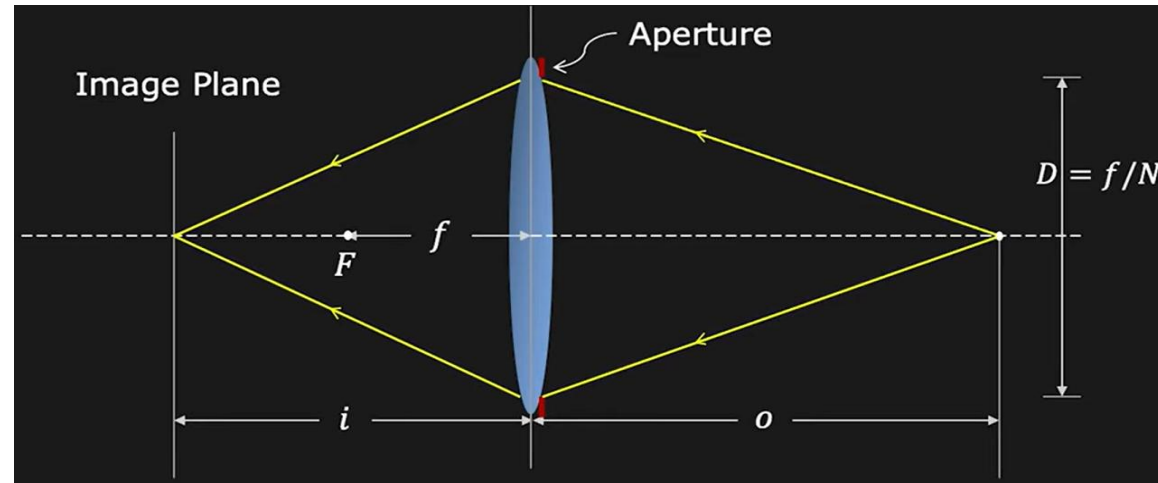
# Lens Defocus

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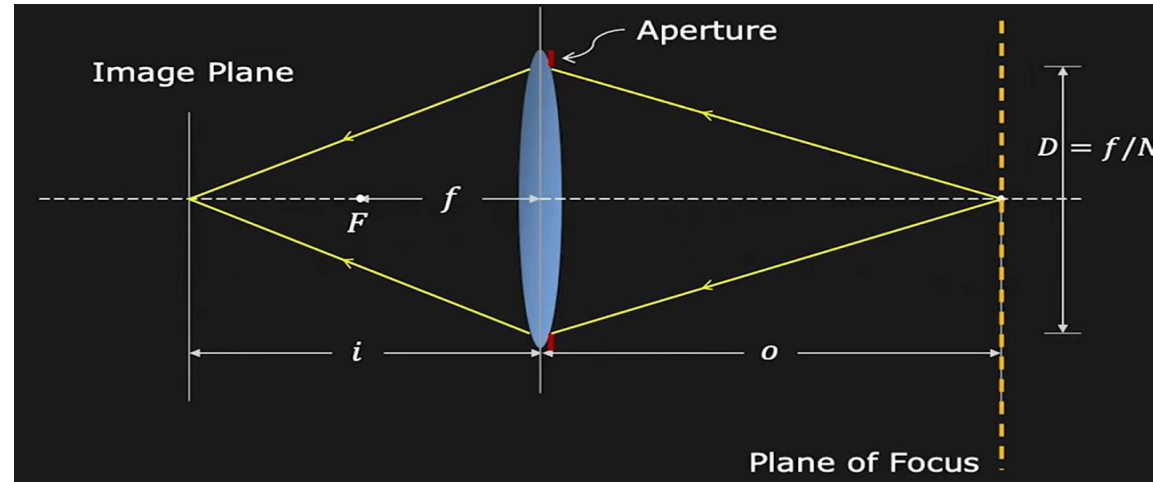
- **Lens defocus** occurs when a point in the scene **is not in perfect focus** on the image sensor.
- Lens gathers more light compared to a pinhole camera
- However, there is only one plane in the scene that is perfectly focused onto the image plane by lens

# Lens Defocus



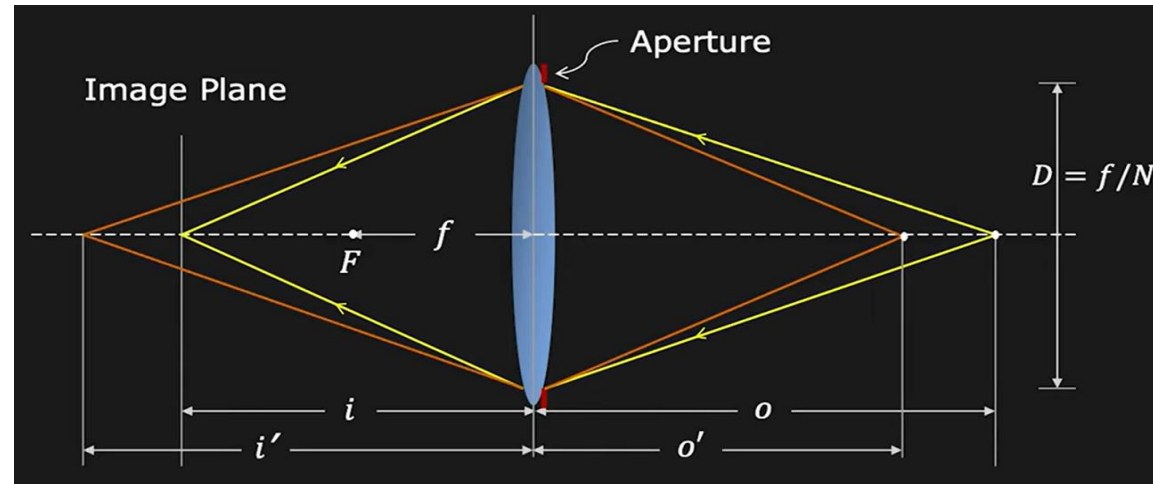
- The point at the distance  $o$  will be focused on the distance  $i$
- The image plane is placed exactly at that location

# Lens Defocus



- For this particular position of the image plane, there is exactly one plane which is going to be completely in focus.
- This is called the **plane of focus** corresponding to the lens system

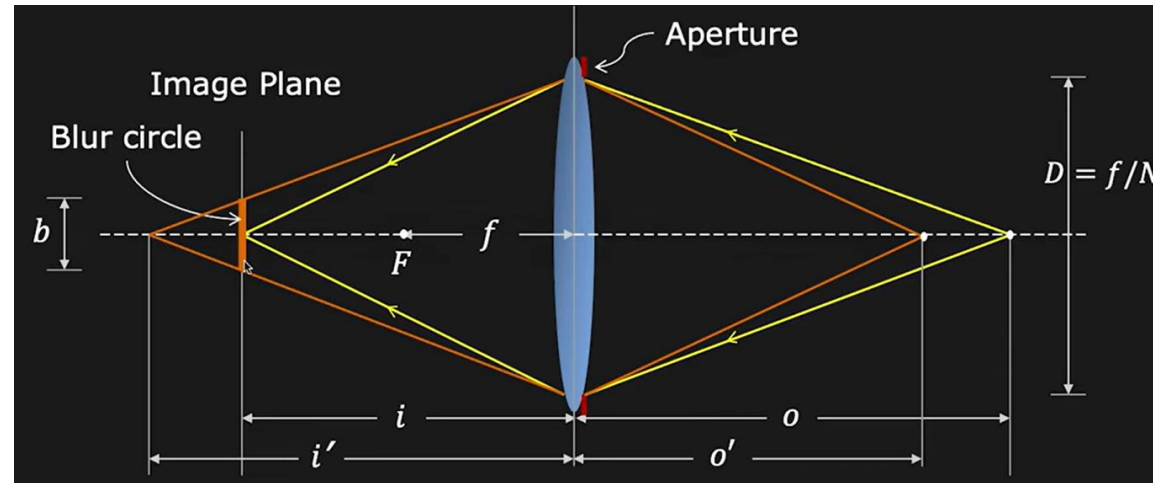
# Lens Defocus



- If a point lies out of this plane of focus, For example the point at distance  $o$  from the lens
- Since it is closer to the lens, its image is going to be formed at a distance  $i$  that is behind the image plane



# Lens Defocus



- The light that the lens receives from this point is not going to end as a single point on the image plane but rather distributed over a **circular disk** on the image plane
- It is going to be blurred that is called the **blur circle** with a **diameter  $b$** .

# Lens Defocus

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- For any given position of the object in the scene, the diameter  $b$  can be calculated
- From similar triangles:

$$\frac{b}{D} = \frac{|\acute{i} - i|}{\acute{i}}$$

- So, the blur circle diameter:

$$b = \frac{D}{\acute{i}} |\acute{i} - i|$$

$$b \propto D \propto \frac{1}{N}$$

# Blur Circle (Defocus)

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## Focused Point

$$\frac{1}{i} + \frac{1}{o} = \frac{1}{f}$$

$$i = \frac{of}{o - f}$$

## Defocused Point

$$\frac{1}{i'} + \frac{1}{o'} = \frac{1}{f}$$

$$i' = \frac{o' f}{o' - f}$$

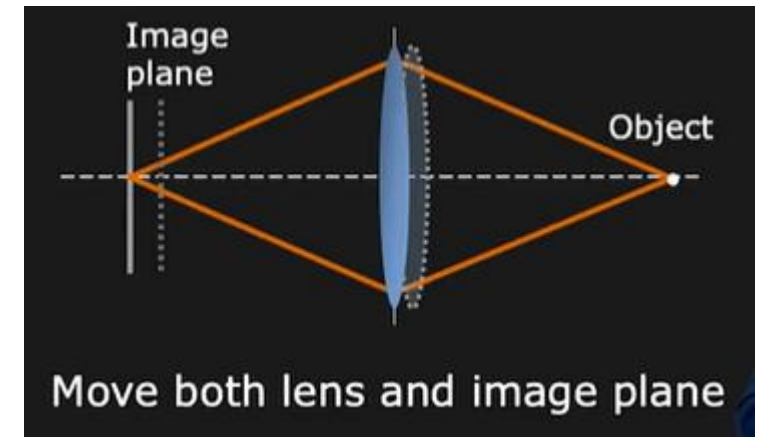
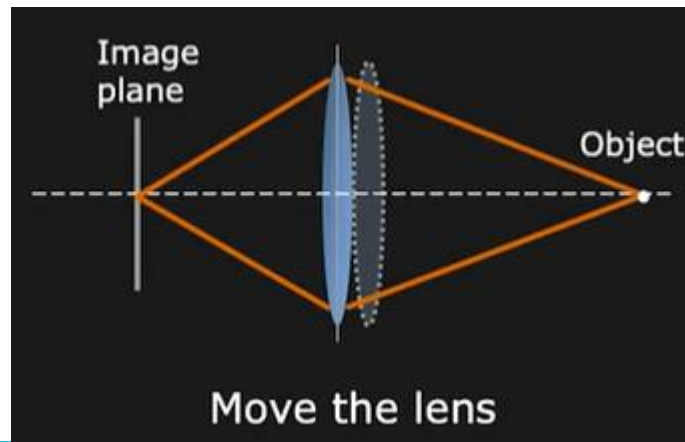
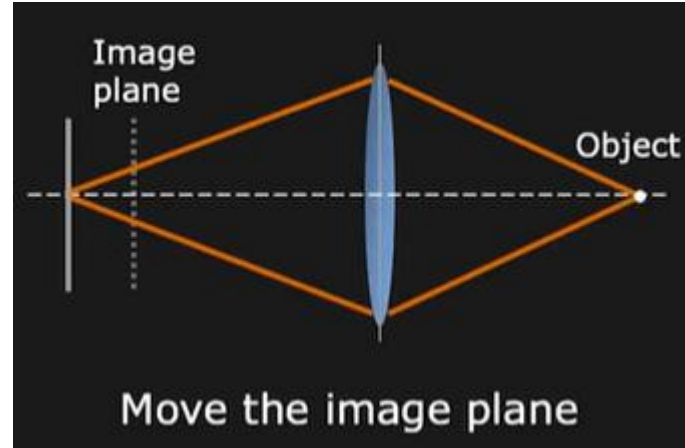
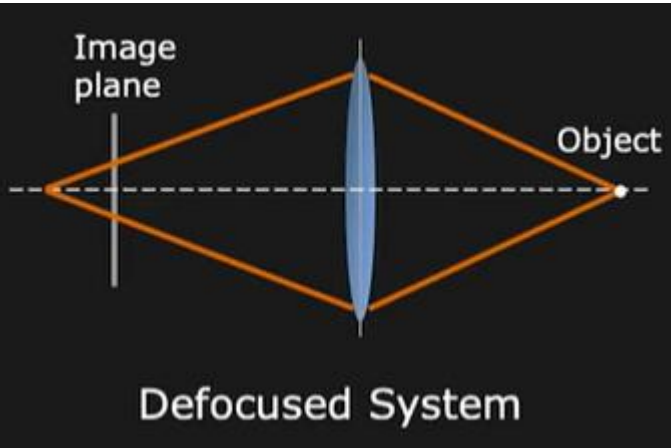
Gaussian Lens Law

$$i' - i = \frac{f}{(o' - f)} \times \frac{f}{(o - f)} \times (o - o')$$

$$b = Df \left| \frac{o - o'}{o' (o - f)} \right|$$

$$b = \frac{f^2}{N} \left| \frac{o - o'}{o' (o - f)} \right|$$

# Focusing



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Thank you

