Quantum Mechanics II

Thomas Brosnan

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" I am the one who knocks "

- Heisenberg

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1 Symmetries

1.1 3D Schrodinger equation

• In QM the Hamiltonian is written in terms of operators. Momenta becomes $\mathbf{p} \to -i\hbar\nabla$ and the potential $V \to \hat{V}$ also an operator. So the Hamiltonian becomes:

$$\frac{-\hbar^2}{2m}\nabla^2 + \hat{V} \tag{1.1}$$

• The (time independent) Schrodinger equation is:

$$H\psi(x,y,z) = E\psi \tag{1.2}$$

• If we then have a central potential, that is V = V(r), so rotation symmetry generated by a rotational group, we find it best to change co-ords to spherical co-ords. Here the Laplacian is:

$$\nabla^2 = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \right) + \frac{1}{r^2 \sin(\theta)} \frac{\partial}{\partial \theta} (\sin \theta \frac{\partial \Phi}{\partial \theta}) + \frac{1}{r^2 \sin^2(\theta)} \frac{\partial^2 \Phi}{\partial \phi^2} = 0$$
 (1.3)

We then make the typical assumption of separation of variables, that is:

The Schrodinger equation then becomes:

$$-\frac{\hbar^{2}}{2m} \left[\frac{Y}{r^{2}} \frac{\partial}{\partial r} \left(r^{2} \frac{\partial R}{\partial r} \right) + \frac{R}{r^{2} \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta \frac{\partial Y}{\partial \theta}) + \frac{R}{r^{2} \sin^{2} \theta} \frac{\partial^{2} Y}{\partial \phi^{2}} \right] + V(r)R(r)Y(\theta, \phi) = ER(r)Y(\theta, \phi)$$
(1.5)

Dividing by $R(r)Y(\theta,\phi)$ and multiplying by r^2 , we get two terms, one a function of r only and one a function of θ and ϕ , adding to a constant E. This means that both these terms must themselves be constant. This gives us two separate equations.

$$\left[-\frac{1}{R} \frac{d}{dr} \left(r^2 \frac{dR}{dr} \right) - \frac{2mr^2}{\hbar^2} [V(r) - E] = l(l+1) \right]
\frac{1}{Y} \left[\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} (\sin \theta \frac{\partial Y}{\partial \theta}) + \frac{1}{\sin^2 \theta} \frac{\partial^2 Y}{\partial \phi^2} \right] = -l(l+1)$$
(1.6)

The choice l(l+1) as a constant, may seem strange at first but makes sense later. On the later equation we again perform separation of variables, $Y = \Theta(\theta)\Phi(\phi)$, so we get two more equations:

$$\frac{1}{\Phi} \frac{d^2 \Phi}{d\phi^2} = -m^2$$

$$\sin \theta \frac{d}{d\theta} \left(\sin \theta \frac{d\Theta}{d\theta} \right) + \left(l(l+1)\sin^2 \theta - m^2 \right) \Theta = 0$$
(1.7)

The first equation here is solved by the usual:

$$\Phi \propto e^{\pm im\phi} \tag{1.8}$$

And Linear combinations of this. Since we would expect that $\Phi(\phi+2\pi) = \Phi(\phi)$, as ϕ is multi-valued, this sets the restriction on m, that m must be an integer.

The solution to Θ solved by the associated Legendre functions P_l^m :

$$\Theta \propto P_l^m(\cos \theta)$$

$$P_l^m(x) = (1 - x^2)^{\frac{|m|}{2}} \left(\frac{d}{dx}\right)^{|m|} P_l(x)$$
(1.9)

Here $P_l(x)$ are the Legendre polynomials, which can be generated from the Rodrigues' formula:

$$P_l(x) = \frac{1}{2^l l!} \frac{d^l}{dx^l} (x^2 - 1)^l$$
(1.10)

This generates a polynomial of degree l, this means that 1.9 vanishes if |m| > l as the nth derivative of a (n-1)th order polynomial is 0. So we have that:

$$|m| \le l$$

$$\implies m \in \{-l, ..., 0, ..., l\}$$
(1.11)

There are 2l+1 allowed values for m. Because the Radial equation 1.6, does not contain m but does depend on l. We get degenerate solutions as the only restriction is $|m| \leq l$. This leads to degenerate solutions due to symmetry.

1.2 Spherical Harmonics

• With the above equations we can now calculate the form of $Y_l^m(\theta,\phi) = \Theta(\theta)\Phi(\phi)$, these functions are known as the spherical harmonics. The first harmonic Y_0^0 is just a constant, It can be of any form to satisfy the differential equation set for Y, but we usually specify it so that the wavefunction is normalised. This turns out to set:

$$Y_0^0 = \sqrt{\frac{1}{4\pi}} \tag{1.12}$$

There is only one harmonic for $l=0 \implies m=0$, but for $l=1, m \in \{-1, 0, 1\}$, so there are three harmonics:

$$Y_1^{-1} = \sqrt{\frac{3}{8\pi}} \sin \theta e^{-i\phi}, \quad Y_1^0 = \sqrt{\frac{3}{4\pi}} \cos \theta, \quad Y_1^1 = \sqrt{\frac{3}{8\pi}} \sin \theta e^{i\phi}$$
 (1.13)

• We can realise some cool things if we notice how these relate to the standard conversion from Cartesian to spherical co-ords, given by:

$$\begin{cases} x_1 = r \sin \theta \cos \theta \\ x_2 = r \sin \theta \cos \theta \\ x_3 = r \cos \theta \end{cases}$$
 (1.14)

We can construct three new functions \tilde{Y}_1^{α} , $\alpha = 1, 2, 3$, where:

$$\tilde{Y}_{1}^{3} \equiv Y_{1}^{0} = \sqrt{\frac{3}{4\pi}} \frac{x_{3}}{r}$$

$$\tilde{Y}_{1}^{1} = \frac{1}{\sqrt{2}} (Y_{1}^{-1} - Y_{1}^{1}) = \sqrt{\frac{3}{4\pi}} \frac{x_{1}}{r}$$

$$\tilde{Y}_{1}^{2} = \frac{1}{\sqrt{2}} (Y_{1}^{-1} + Y_{1}^{1}) = \sqrt{\frac{3}{4\pi}} \frac{x_{2}}{r}$$
(1.15)

If we rotate around the origin by an angle γ then **x** transforms by:

$$\mathbf{x}' = \Lambda(\gamma)\mathbf{x} \tag{1.16}$$

Where Λ is just a rotation matrix. It can then be seen that the by the form of the three Y_1^{α} , that they transform the same way (as r remains constant). They are like the components of the vector $\tilde{\mathbf{Y}}$, with:

$$\tilde{\mathbf{Y}}' = \Lambda(\gamma)\tilde{\mathbf{Y}} \tag{1.17}$$

These \tilde{Y}_1^{α} form a representation of the group of rotations. When l=2 this becomes a tensor representation.

 \bullet We can combine Y_l^m in combinations to form others. Take for instance Y_2^0 given by:

$$Y_2^0 = \sqrt{\frac{5}{16\pi}} (3z\cos^2\theta - 1)$$
 (1.18)

From examining the above expressions we can see that this must be related to $(Y_1^0)^2 = \frac{3}{4}\cos^2\theta$. In fact we can write Y_1^0 in terms of Y_2^0 , where we can take care of any constant term by writing it in

terms of Y_0^0 . This takes the form:

$$(Y_1^0)^2 = \frac{1}{\sqrt{4\pi}}(Y_0^0 + \frac{2}{\sqrt{5}}Y_2^0)$$
 (1.19)

It can be noted that for m's the two sides add, 0 + 0 = 0 + 0, and l's 1 + 1 = 0 + 2. This becomes important later on.

1.3 Angular Momentum

• Classically angular momentum is defined as $\mathbf{L} = \mathbf{p} \times \mathbf{x}$. In quantum mechanics $P_k \to -i\hbar \frac{\partial}{\partial x_k}$. So the angular momentum operators are:

$$\hat{L}_{1} = -i\hbar(x_{2}\frac{\partial}{\partial x_{3}} - x_{3}\frac{\partial}{\partial x_{2}})$$

$$\hat{L}_{2} = -i\hbar(x_{2}\frac{\partial}{\partial x_{3}} - x_{3}\frac{\partial}{\partial x_{2}})$$

$$\hat{L}_{3} = -i\hbar(x_{2}\frac{\partial}{\partial x_{3}} - x_{3}\frac{\partial}{\partial x_{2}})$$

$$(1.20)$$

These have the useful property that $[\hat{L}_{\alpha}, L_{\beta}] = i\hbar\epsilon_{\alpha\beta\gamma}\hat{L}_{\gamma}$

• We also define the total angular momentum operator as:

$$\hat{L}^2 = \hat{L}_1^2 + \hat{L}_2^2 + \hat{L}_3^2 \tag{1.21}$$

This has the property that, $[\hat{L}^2, \hat{L}_k] = 0$, for all k = 1, 2, 3.