05_week1_quiz

Recurrent Neural Networks

测验, 10 个问题 第 1 个问题 1 point

1。第1个问题

Suppose your training examples are sentences (sequences of words). Which of the following refers to the jth word in the ith training example?

x(i)<j>

x < i > (j)

x(j) < i >

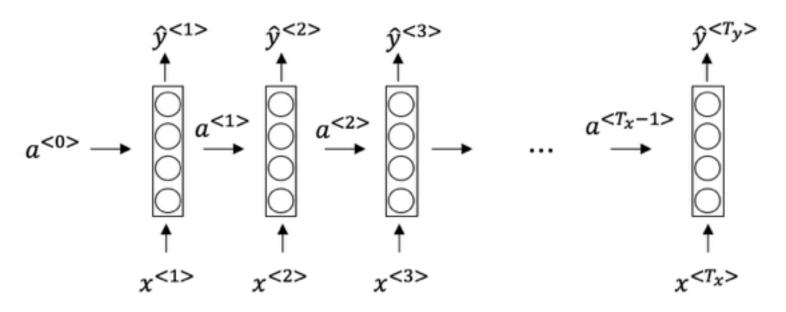
x<j>(i)

第2个问题

point

2。第2个问题

Consider this RNN:



This specific type of architecture is appropriate when:

Tx=Ty

Tx<Ty

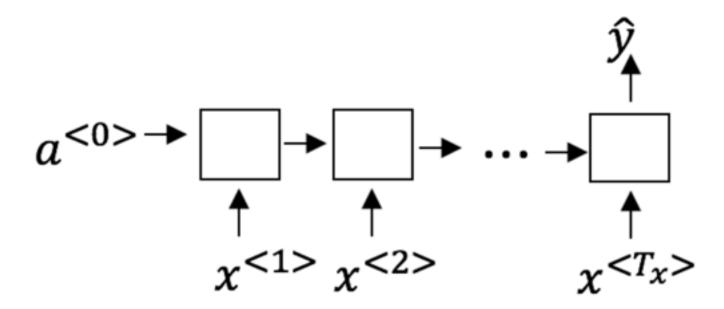
Tx>Ty

Tx=1 第 3 个问题

point

3。第3个问题

To which of these tasks would you apply a many-to-one RNN architecture? (Check all that apply).



Speech recognition (input an audio clip and output a transcript)

Sentiment classification (input a piece of text and output a 0/1 to denote positive or negative sentiment)

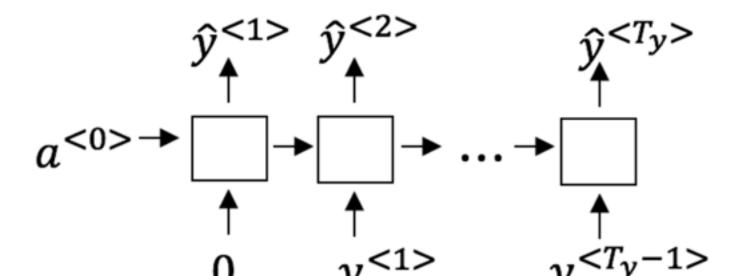
Image classification (input an image and output a label)

Gender recognition from speech (input an audio clip and output a label indicating the speaker's gender)

第 4 个问题 1 point

4。第4个问题

You are training this RNN language model.



At the tth time step, what is the RNN doing? Choose the best answer.

Estimating P(y<1>,y<2>,...,y<t-1>)

Estimating P(y<t>)

Estimating P(y<t>|y<1>,y<2>,...,y<t-1>)

Estimating P(y<t>|y<1>,y<2>,...,y<t>)

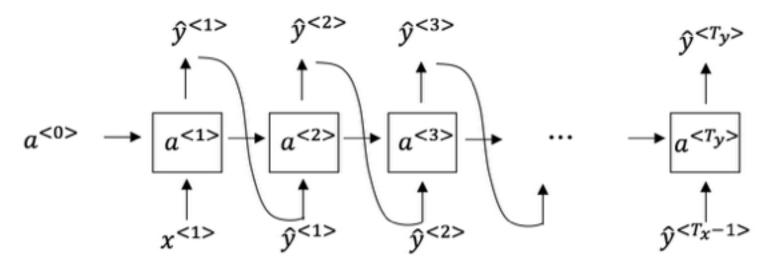
第5个问题

1

point

5。第5个问题

You have finished training a language model RNN and are using it to sample random sentences, as follows:



What are you doing at each time step t?

- (i) Use the probabilities output by the RNN to pick the highest probability word for that time-step as $y^{<t>}$. (ii) Then pass the ground-truth word from the training set to the next time-step.
- (i) Use the probabilities output by the RNN to randomly sample a chosen word for that time-step as $y^{<t>}$. (ii) Then pass the ground-truth word from the training set to the next time-step.
- (i) Use the probabilities output by the RNN to pick the highest probability word for that time-step as $y^{<t>}$. (ii) Then pass this selected word to the next time-step.
- (i) Use the probabilities output by the RNN to randomly sample a chosen word for that time-step as $y^{<t>}$. (ii) Then pass this selected word to the next time-step.

第6个问题 1 point

6。第6个问题

Vou are training an PNN, and find that your weights and activations are all taking on the value of NaN ("Net a

Number"). Which of these is the most likely cause of this problem?

Vanishing gradient problem.

Exploding gradient problem.

ReLU activation function g(.) used to compute g(z), where z is too large.

Sigmoid activation function g(.) used to compute g(z), where z is too large.

第 7 个问题 1

point

7。第7个问题

Suppose you are training a LSTM. You have a 10000 word vocabulary, and are using an LSTM with 100-dimensional activations a < t >. What is the dimension of Γu at each time step?

1

100

300

10000

第8个问题

1

point

8。第8个问题

Here're the update equations for the GRU.

GRU

$$\tilde{c}^{} = \tanh(W_c[\Gamma_r * c^{}, x^{}] + b_c)$$

$$\Gamma_u = \sigma(W_u[c^{}, x^{}] + b_u)$$

$$\Gamma_r = \sigma(W_r[c^{}, x^{}] + b_r)$$

$$c^{} = \Gamma_u * \tilde{c}^{} + (1 - \Gamma_u) * c^{}$$

$$a^{} = c^{}$$

Alice proposes to simplify the GRU by always removing the Γ u. I.e., setting Γ u = 1. Betty proposes to simplify the GRU by removing the Γ r. I. e., setting Γ r = 1 always. Which of these models is more likely to work without vanishing gradient problems even when trained on very long input sequences?

Alice's model (removing Γu), because if $\Gamma r \approx 0$ for a timestep, the gradient can propagate back through that timestep without much decay.

Alice's model (removing Γu), because if $\Gamma r \approx 1$ for a timestep, the gradient can propagate back through that timestep without much decay.

Betty's model (removing Γr), because if $\Gamma u \approx 0$ for a timestep, the gradient can propagate back through that timestep without much decay.

Betty's model (removing Γr), because if $\Gamma u \approx 1$ for a timestep, the gradient can propagate back through that timestep without much decay.

第 9 个问题 1 point

9。第9个问题

Here are the equations for the GRU and the LSTM:

GRU

$$\tilde{c}^{} = \tanh(W_c[\Gamma_r * c^{}, x^{}] + b_c)$$

$$\Gamma_u = \sigma(W_u[c^{}, x^{}] + b_u)$$

$$\Gamma_r = \sigma(W_r[c^{}, x^{}] + b_r)$$

$$c^{} = \Gamma_u * \tilde{c}^{} + (1 - \Gamma_u) * c^{}$$

$$a^{} = c^{}$$

LSTM

$$\tilde{c}^{} = \tanh(W_c[a^{}, x^{}] + b_c)$$

$$\Gamma_u = \sigma(W_u[a^{}, x^{}] + b_u)$$

$$\Gamma_f = \sigma(W_f[a^{}, x^{}] + b_f)$$

$$\Gamma_o = \sigma(W_o[a^{}, x^{}] + b_o)$$

$$c^{} = \Gamma_u * \tilde{c}^{} + \Gamma_f * c^{}$$

$$a^{} = \Gamma_o * c^{}$$

From these, we can see that the Update Gate and Forget Gate in the LSTM play a role similar to _____ and ____ in the GRU. What should go in the blanks?

Γu and 1−Γu

Γu and Γr

1-\(\text{u} \) and \(\text{U} \)

Γr and Γu

第 10 个问题

point

10。第 10 个问题

You have a pet dog whose mood is heavily dependent on the current and past few days' weather. You've collected data for the past 365 days on the weather, which you represent as a sequence as x<1>,...,x<365>. You've also collected data on your dog's mood, which you represent as y<1>,...,y<365>. You'd like to build a model to map from $x\rightarrow y$. Should you use a Unidirectional RNN or Bidirectional RNN for this problem?

Bidirectional RNN, because this allows the prediction of mood on day t to take into account more information.

Bidirectional RNN, because this allows backpropagation to compute more accurate gradients.

Unidirectional RNN, because the value of y<t> depends only on x<1>,...,x<t> , but not on x<t+1>,...,x<365>

Unidirectional RNN, because the value of y < t > depends only on x < t >, and not other days' weather.

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