CPSC 320 – Assignment 2

The University of British Columbia
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Collaboration Policy

1 Olympic Scheduling

You are in charge of a live-streaming YouTube channel for the Olympics that promises never to interrupt an event. (So, once you start playing an event, you must play only that event from the time it starts to the time it finishes.) You have a list of the events, where each event includes its: **start time, finish time (which must be after its start time), and expected audience value**. Your goal is to **make a schedule to broadcast the most valuable complete events**. **The best schedule is the one with the highest-valued event**; **in case of ties, compare second-highest valued events, and so on**. (So, for example, you obviously **will** include the single highest-valued event in the Olympics—presumably the hockey gold medal game—no matter what else it blocks you from showing.) (Times when you're not broadcasting events will be filled with "human interest stories" that have zero value; so, they're irrelevant.) **ASSUME: all event values are distinct and all event times are distinct.** I.e., for any two values v_i and v_j with $i \neq j$, $v_i \neq v_j$. The same holds for start and end times (e.g., for any two start times s_i and s_j with $i \neq j$, $s_i \neq s_j$). Further, for any two start and finish times s_i and f_j, whether $i = j$ or not, $s_i \neq f_j$.

1.1 Naïve Algorithm

Consider the following algorithm. Assume that deleting an event from a list of events takes constant time.

```
Naive(E):
  result = new empty list of events
  while E is not empty:
    bestEvent = E[0]
    for each e in E:
      if value(e) > value(bestEvent):
        bestEvent = e
    delete bestEvent from E
    for each e in E:
      if start(e) < finish(bestEvent) and finish(e) > start(bestEvent):
        delete e from E
    add bestEvent to result
  return result
```

1.1.1 Finiteness

Briefly sketch a proof that the `while` loop in the algorithm above terminates. You need not give a formal proof, but you should include all key insights in the proof. **Representing the problem:** Let E denote the set of all events to be streamed $E = \{e_1, \cdots, e_n\}$ where $n = |E|$. For every event $e \in E$, let e comprise an ordered triple $e_i = (v_i, s_i, f_i)$ where v, s and f denote the audience value, start time, and finish time accordingly.

Proof. Let n be the cardinality of E (i.e. $n = |E|$). **Base Case:** if $n = 0$, then the while loop is never intiated Otherwise if $n = 1$ then the event e where $e \in E$ is the bestEvent as assigned and is removed after the execution of the first for loop. **Inductive Step:** Assume true for $n = k$ events, then for $n = k + 1$ events we have two cases as such:

- In the first case, we delete the bestEvent and no conflicting events leaving us with $n = k + 1 - 1 = k$. By the inductive assumption the algorithm holds true.

- As for the second case, we delete the bestEvent and some number of events which leaves u with $n < k$. By the inductive step, the algorithm holds true.

∎

1.1.2 Efficiency

Give and briefly justify a good asymptotic bound on the runtime of the algorithm. Assuming all elementary operation execute in constant time, the worst case executions are $O(n^2)$ where the worst case execution is defined as when we only delete the assigned bestEvent and there are no conflicts. Within the outer while loop, the first for loop executes n times for comparing the values of bestEvent and another event e. Then for every iteration of the while loop, we delete the bestEvent in constant time. Finally, the ending nested for loop executes $(n-1)$ per iteration. Then we add bestEvent at constant time. In total, we have:

$$n\big(n + 1 + (n - 1) + 1\big) = O(n^2)$$

1.1.3 Correctness

Briefly sketch a proof that the algorithm is correct. You need not give a formal proof, but you should include all key insights in the proof. **Correctness:** Let us define a correct solution returned by the algorithm as a set $R \subset E$. For $R = \{r_1, r_2, \ldots, r_k\}$, we have that $v_1 > v_2 > \ldots > v_k$. And to prevent conflicted showtimes of events we have $\forall r_i, r_j \in R$, if $s_i < s_j$, then $f_i < s_j$; or less formally, if an event in our schedule R begins before the next event, then it will also end before the start of our next event.

Proof. We will show that the Naive(E) algorithm returns a correct solution but not necessarily the optimal solution. If we can show that (1) the bestEvent (i.e. $e_i \in E$ such that v_i is a max) is removed from E and added to our result R, (2) all conflicting events to bestEvent are removed from E, and (3) the algorithm repeats steps (1) and (2) for all remaing events in E, then we have shown Naive(E) returns a correct solution.

1. The bestEvent e_{best} is assigned as the first element of E, then the value of the bestEvent is compared to the value of another element, e_{other} . If $v_{\text{other}} > v_{\text{best}}$ then we assign the bestEvent $e_{\text{best}} = e_{\text{other}}$. Hence, v_{best} is the maximum audience value in E.

   After the execution of the first for loop, we remove the bestEvent from E and regardless of the execution of the second for loop this bestEvent is added to R.

2. In order to handle the conflicts, the second for loop removes events that satisfy the following condition: for all $e_i \in E - \{e_{\text{best}}\}$ if an event e_i has a start time before or during the bestEvent (i.e. $s_i < f_{\text{best}}$), and the finish time of e_i is during or after the bestEvent (i.e. $f_i > s_{\text{best}}$), then the event e_i interrupts the bestEvent. To see why, let us break the start time of e_i into two cases.

   Case 1: event e_i starts before the bestEvent. If e_i ends after the start of the bestEvent (i.e. the second condition $f_i > s_{\text{best}}$), then we have an overlap.

   Case 2: event e_i starts during the bestEvent. By definition, we have an overlap.

3. After steps (1) and (2) we are now left with the subset $E' \subset E$, such that E' does not contain the bestEvent (1) and any conflicting events (2). According to the while loop, if E' is non-empty, then the algorithm will repeat steps (1) and (2) for this new E'.

   ∎

1.2   Reduction on Simplified Problem

To make the Olympic Broadcasting problem simpler, we completely remove start time and finish times from the problem. So, now events only have values (not times), and a "schedule" is just a set of selected events. To make it slightly harder again, you are not allowed to select two events i and j if their values are within 10 units of each other: $|v_i - v_j| \leq 10$. Give a correct reduction from this simplified Olympic Broadcasting problem to the sorting problem (where you provide both a list of items and a function to compare two items). Your reduction should take $O(n \lg n)$ time. **Reduction:**   We will reduce the Olympic Broadcasting problem to a Heapifying Array problem. In order to do this we will recycle the set of all events E and pass it as an array to Heapify(E). This will return our

desired schedule of events as H. This will take $O(n \lg n)$. For our comparaison function, we want to know if we can add an event e_j if we have already added event e_i. The pseudocode is given below.

```
canAdd(e_i, e_j):
  if |value(e_i) - value(e_j)| > 10
    return true
  else
    return false
```

Translation to Olympic Broadcasting: Now that we have our resulting H, for all events $e \in H$ and their respective values we have $v_1 > v_2 > \cdots > v_k$ where $k = |H|$. This satisfies the first half of our definition of correctness from 1.1.3. **NOTE:** You will likely find that (a) you can solve this with a single call to the sorting problem's solution algorithm and (b) producing the sorting instance is the easier part and transforming the solution to sorting into a solution to this simplified Olympic Broadcasting problem is the harder part. Don't forget to do both!

1.3 Olympic Reduction, BONUS ONLY

This was significantly harder than we intended it to be! So, we removed it from the quiz/assignment. It's a bonus problem worth two CPSC 320 bonus points for extremely clear, correct, and efficient responses. (Extremely clear reductions that take $O(n)$ time—not counting an $O(1)$ number of calls to a sorting algorithm—may receive 3 bonus points, but we don't know if such reductions are possible.) Give a correct and efficient reduction from the Olympic broadcasting problem to the sorting problem (where you provide both a list of items and a function to compare two items). Your reduction—combined with an $O(n \lg n)$ sorting algorithm—should be asymptotically more efficient than the naïve algorithm above.

1.3.1 Correctness

Briefly sketch a proof that your algorithm is correct. You need not give a formal proof, but you should include all key insights in the proof.

1.3.2 Efficiency

Give and briefly justify a good asymptotic bound on the runtime of **just** your reduction, **not** including the call to the sorting algorithm. So, for the purposes of this asymptotic

bound, you can imagine that we somehow solve sorting in constant time. (Note: it's possible to give a reduction that takes $O(n)$ time.)

2 Exhausted of Marriage

We modify SMP with the very reasonable change that not every woman need list every man in her preferences. She prefers to be unmarried to marrying unlisted men. Note that she clearly prefers any man on her preference list to any man not on her preference list. Men can similarly truncate their lists of women. Here is the Gale-Shapley algorithm:

1: **procedure** STABLE-MARRIAGE(M, W)
2:     initialize all men in M and women in W to unengaged
3:     **while** an unengaged man with at least one woman on his preference list remains **do**
4:         choose such a man $m \in M$
5:         propose to the next woman $w \in W$ on his preference list
6:         **if** w is unengaged **then**
7:             engage m to w
8:         **else if** w prefers m to her fiancé m' **then**
9:             break engagement of m' to w
10:            engage m to w
11:        **end if**
12:        cross w off m's preference list
13:    **end while**
14:    report the set of engaged pairs as the final matching
15: **end procedure**

With one small change, we can apply this algorithm and ensure that the (not necessarily perfect) matching produced never marries a person to someone they left off of their preference list.

1. Make the small change necessary **to the algorithm above**.   Line 6: if (w is unengaged & m in w's preference list) then

2. Briefly sketch the key elements of a proof that the algorithm terminates.

   In the worst case, the algorithm will terminate in n^2 iterations, i.e. men have complete preference lists. Let $S(k)$ be the set of pairs (m, w) such that m has proposed to w on iteration k of the Gale-Shapley algorithm. Then we can see that every new iteration increases the number of pairs (or in mathematical notation: $\forall k, |S(k+1)| > S(k)$). However, since in the worst case we have n^2 possible pairs of men and women we know that there can be at most n^2 iterations of the while loop, hence the algorithm must terminate.

3. We need a new definition of instability now that some people may end up unmarried. Here is one new type of instability that we call an *elopement instability*: m_i and w_j

are both unmarried but list each other on their preference lists (in which case they have incentive to break the imposed matching and marry each other).

Describe another new type of instability involving an unmarried woman. (Note: an analogous instability exists involving an unmarried man.)

The mistress instability: We can define a new instability with the following conditions:

(a) w_j is unmarried, m_i is married

(b) w_j prefers m_i to being unmarried

(c) m_i prefers w_j to current partner

The poolboy instability: *(to be referenced in 2.1)* An instability analogous to the above has the following conditions:

(a) w_j is married, m_i is unmarried

(b) w_j prefers m_i to current partner

(c) m_i prefers w_j to being unmarried

4. Briefly sketch the key elements of a proof that your modified G-S algorithm cannot generate an elopement instability.

Proof. In order to show that the *elopement instability* is not a feasible result of the modified G-S algorithm, we will show that the algorithm terminates with a man left married or unmarried with an empty preference list. The precondition of the **while** loop outlines that an unengaged man must have a preference list, otherwise we terminate the procedure. This means that we cannot have an unengaged man and unengaged woman that prefer each other. This is because the while loop ensures that every man gets engaged or is left with an empty preference list. In the case of the latter, it is not possible that an unmarried man prefers any woman. ∎

2.1 Even More Exhausted

Briefly sketch the key elements of a proof that your modified G-S algorithm cannot generate any of the other three types of instability (the classic SMP instability, the instability you defined above, and the analogous instability with the roles of men and women swapped).

Proof. Because Taj is a poopie poop pooop. ∎

3 Footblog

The massive social network Footblog tracks relationships based on whether two people have "enemied" each other. ("Enemyship" is a mutual agreement, meaning that a person is not allowed to "enemy" another person unless the other person agrees to "enemy" them back. No one can "enemy" themselves.)

3.1 Isolationism

We investigate whether Footblog's network is a single connected component. Footblog's founder created the first Footblog account, and that account has no "sponsor" (and cannot be assigned one). Every other account must have a single, designated "sponsor" who they have "enemied". If a sponsors b, we call b the *sponsee* of a. There are then four major actions to consider on Footblog, some of which involve others as steps:

Joining When a new Footblog member joins, they must do so by choosing as sponsor (and "enemying") someone already in the network who agrees to be their sponsor (and their enemy). After members join, they're free to "enemy" and "unenemy" anyone except their sponsor and their sponsees.

Enemying Already described above. Remember that when one person "enemies" another, the other must agree to "enemy" that person back.

Un-Enemying Unlike making an "enemy" link, one person alone can "unenemy" another person, in which case neither "enemies" the other any more.

Change Sponsor If a person wishes to change their sponsor, they must "unenemy" their sponsor and simultaneously "enemy" a new sponsor. The new sponsor must agree to act as sponsor and enemy and **must be a new enemy** (i.e., must not already be the person's enemy). Note that while a sponsee can choose to change their sponsor, a sponsor cannot choose to change their sponsee.

You may assume these actions never happen in parallel, i.e., a defined sequence occurs of the operations: joining, enemying, un-enemying, and changing sponsors.

1. Based on these rules, sketch a brief proof that when a person changes their sponsor, their new sponsor cannot also be one of their sponsees.

   Proof. Assume to the contrary that for a person p their new sponsor s is also their sponsee. Since s was originally a sponsee, then p and s were already enemies. However this contradicts the definition of "Change Sponsor", as the new sponsor must be a new enemy. ∎

2. Based on these rules, either **sketch the key points in a proof that Footblog's enemy graph forms a single connected component** or **give a small sequence of actions that creates multiple components**.

   Circle **one**: **SINGLE ONLY   MAY BE MULTIPLE**   Provide your proof sketch or example:

   Let the creator be denoted by the vertex C. Then a sequence of steps that will generate multiple components is

   ```
   join(A, C)
   join(B, A)
   join(D, B)
   changeSponsor(A, D)
   ```

   where join(v_i, v_j) adds the vertex v_i to the network with v_j as its sponsor and changeSponsor(v_i, v_j) changes the sponsor of vertex v_i to be v_j.

   To help visualize these steps, let us represent it as a graph $G = (V, E)$ such that an edge (v_i, v_j) is defined if v_i and v_j are enemies. For ease of clarity, we will show a sponsor-sponsee relationship by a directed arrow, where the arrow head points to the sponsor. The graph G prior to the call to changeSponsor is shown in Figure 1a and the graph G' after the call to changeSponsor in Figure 1b.
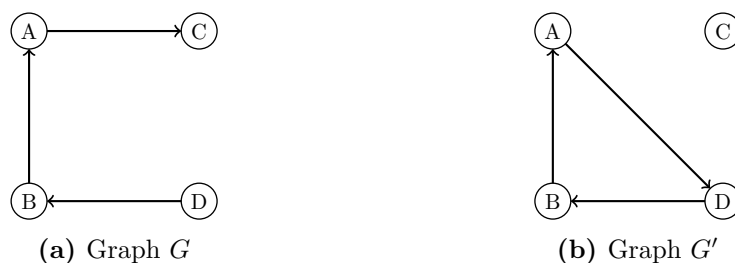

(a) Graph G **(b)** Graph G'

Figure 1: A simply connected Footblog graph G and the same graph G' after changeSponsor is called.

3.2   Centrality

Footblog has defined a notion of "centrality" for its users: a user's "centrality" is the minimum number of people they'd need to go through to get a message to the person farthest from them on the network, following "enemy" links. (The "farthest" person is exactly the one to whom there is the longest minimum-length path of enemies.) For this problem, **assume that the Footblog network does indeed form a single connected**

component. Briefly describe an algorithm to compute the centrality of a usern given a graph G represented as a number of users $n > 0$ (where the users themselves are vertices named $\{v_1, v_2, \ldots, v_n\}$, a vertex number i (where $1 \leq i \leq n$) of the user whose centrality we wish to compute, and an adjacency list A of edges (i.e., an array of linked lists, where the entries in the list $A[j]$ are the vertex numbers of the users j has "enemied"). You may use any common data structures you need. **Your algorithm must run in linear (i.e., $O(n+m)$ for n nodes and m edges) time.**

```
Centrality(n, i, A):
  // Initialize distances
  V := set of all vertices in graph G
  for each vertx v in V - {v_i}
    dist[v] := infinity
  dist[i] := 0

  // Modified Dijkstra algorithm: compute shortest distance between
  // v_i and all other vertices
  while V is not empty:
    u: node in V with smallest dist[]
    remove u from V

    for each v in A[u]     // all of u's neighbours
      temp := dist[u] + 1
      if temp < dist[v]
        dist[v] := temp

  // Find maximium of the shortest distances
  max_dist = 0
  for each vertex v in V:
    if dist[v] > max_dist
      max_dist := dist[v]

  return max_dist
```

Runtime Analysis: since the initialization of distances is done over n vertices and the modified Dijkstra algorithm runs over m edges, we have $O(n + m)$.

4 Heaps of Fun Might Be OK

You're managing a major online tournament of the hot new game Flappy Squirrel. There are a huge number of users, each with a competitiveness rating (a floating point number). You need an algorithm that—given a desired number of competitors c and a list of these competitiveness ratings (an array A of length n)—returns a list of the c highest ratings. You're guaranteed that $c \leq n$. (Note: we use 1-based indexing on arrays.)

4.1 Algorithm 1

Give and briefly justify a good asymptotic upper-bound (i.e., big-O bound) on the runtime of the following algorithm to solve this problem. (**Note:** the `buildMaxHeap` operation returns a max-heap built from the elements of a given array of length n in $O(n)$ time.)

```
TopC(A, c):
  best <- empty list
  h <- buildMaxHeap(A)
  for i = 1 to c:
    add findMax(h) to best
    deleteMax(h)
  return best
```

Answer: The asymptotic upper-bound seems to be $O(cn)$. Given that `buildMaxHeap` operates at $O(n)$ we proceed to the `for` loop that executes c times. In this loop, we call `deleteMax` which removes the maximum element in the heap and calls the necessary percolations to rebalance the heap. This should take $O(n)$. Hence, we have $n + 1 + c(1 + n) + 1 = O(cn)$.

4.2 Algorithm 2

Give and briefly justify a good asymptotic upper-bound (i.e., big-O bound) on the runtime of the following algorithm to solve this problem. (Note: the notation `A[1..c]` produces a list of the elements `A[1]`, `A[2]`, `A[3]`, ..., `A[c]` in $O(c)$ time.)

```
TopC(A, c):
  for i = 1 to c:
    maxIndex = i
    for j = i+1 to n:
      if A[j] > A[maxIndex]:
        maxIndex = j
    max = A[maxIndex]
```

```
    A[maxIndex] = A[i]
    A[i] = max
  return A[1..c]
```

Answer: Algorithm 2 executes in $O(cn)$ time. The outer `for` loop performs c operations. The nested `for` loop performs n operations. Thus, by the end of algorithm we have $O(cn + c) = O(cn)$

4.3   Algorithm 3

Give and briefly justify a good asymptotic upper-bound (i.e., big-O bound) on the runtime of the following algorithm to solve this problem.

```
TopC(A, c):
  sort A using an efficient, comparison-based sorting algorithm
  return A[1..c]
```

Answer: Using a QuickSort as our comparison-based sorting algorithm, it takes $O(n \lg n)$ to sort `A`. Then to `return A[1...c]` it takes $O(c)$. The upper bound is then $O(c + n \lg n)$.

4.4   Algorithm 4

Give and briefly justify a good asymptotic upper-bound (i.e., big-O bound) on the runtime of the following algorithm to solve this problem. (Note: `Elements(h)` produces all elements in the heap `h` in constant time, but `h` can no longer be used after that point.)

```
TopC(A, c):
  h <- empty min-heap
  for i = 1 to n:
    if Size(h) < c:
      Insert(h, A[i])
    else if A[i] > FindMin(h):
      DeleteMin(h)
      Insert(h, A[i])
  return Elements(h)
```

Answer: Given that `Insert` operates in $O(\lg n)$, `FindMin` returns the minimum in constant time, and `DeleteMin` takes $O(n)$ to call the necssary percolations to re-heapify the array, the Algorithm operates in $O(n^2)$. The worst case runtime occurs when control is passed to the `else` statement, where we iterate n times over $n + \lg n$ operations.