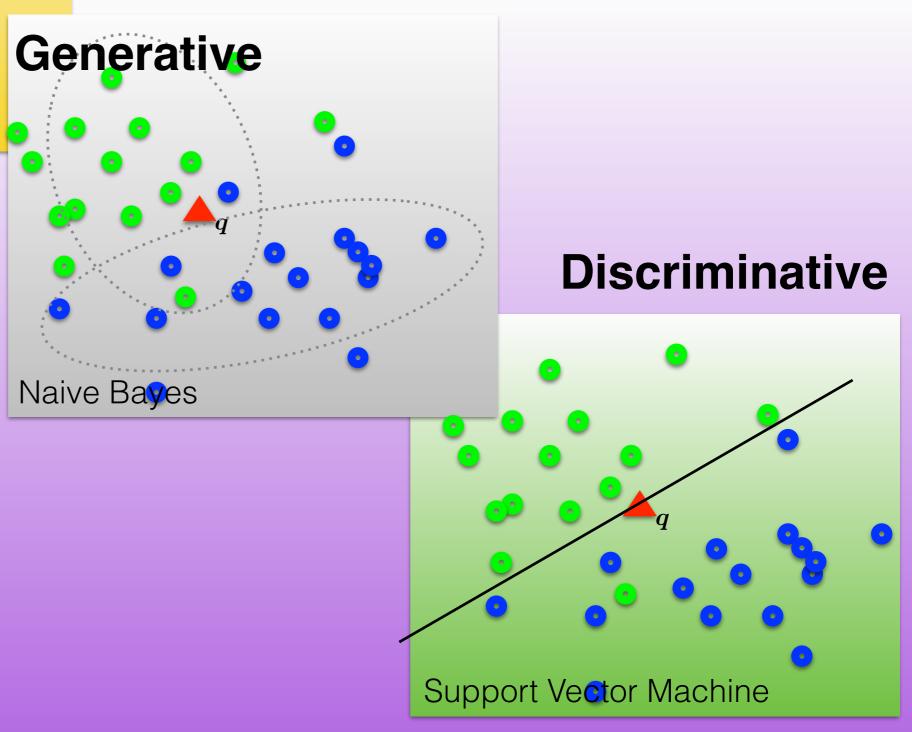
# Support Vector Machine

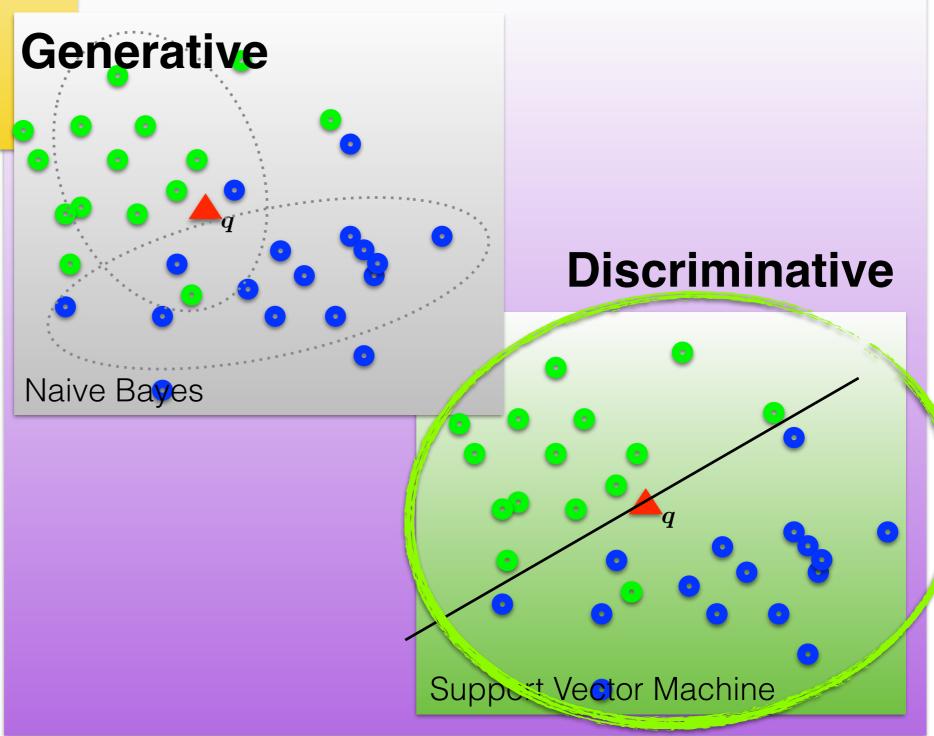
# Non-parametric Nearest Neighbor

#### **Parametric**

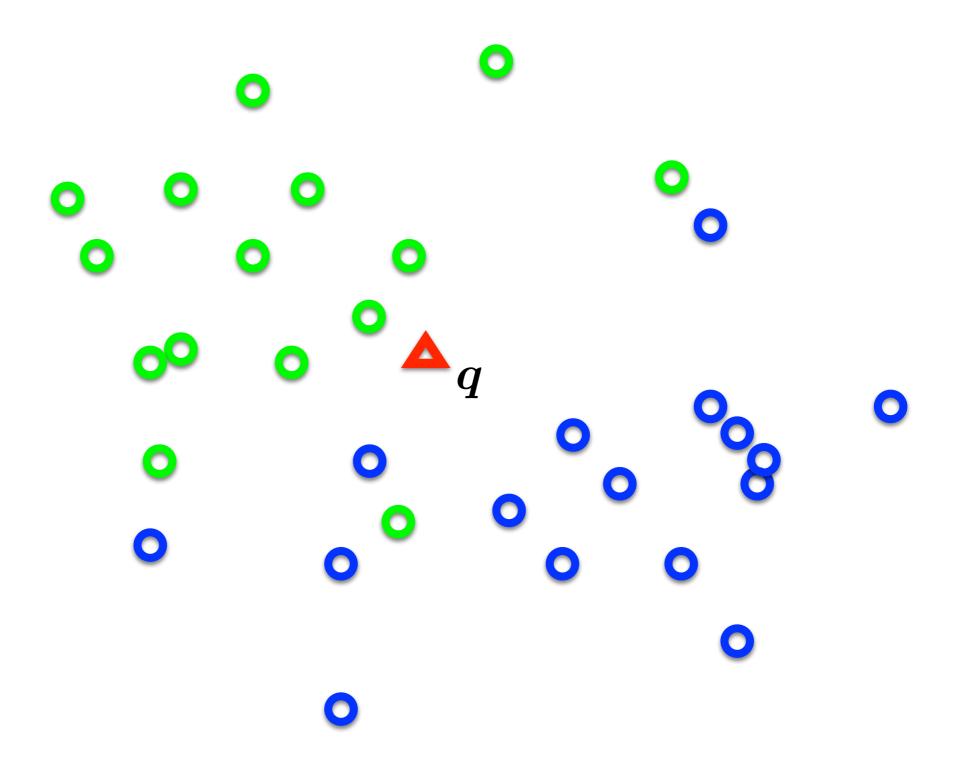


# Non-parametric Nearest Neighbor

#### **Parametric**

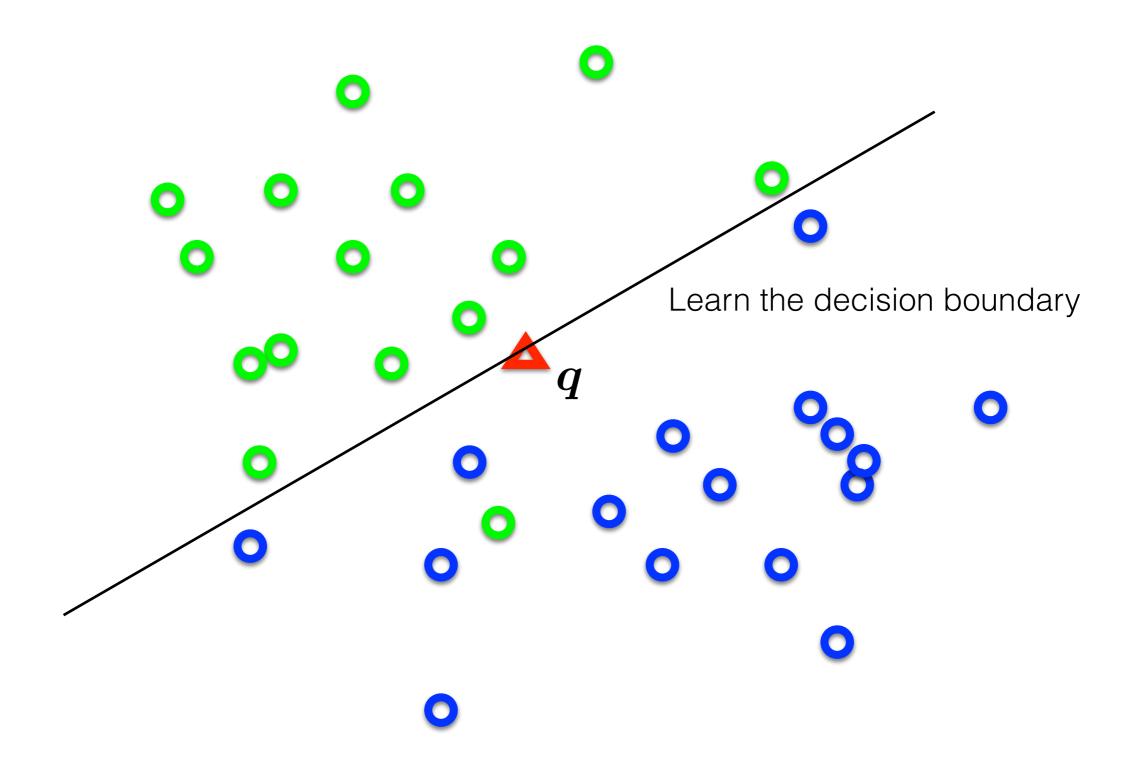


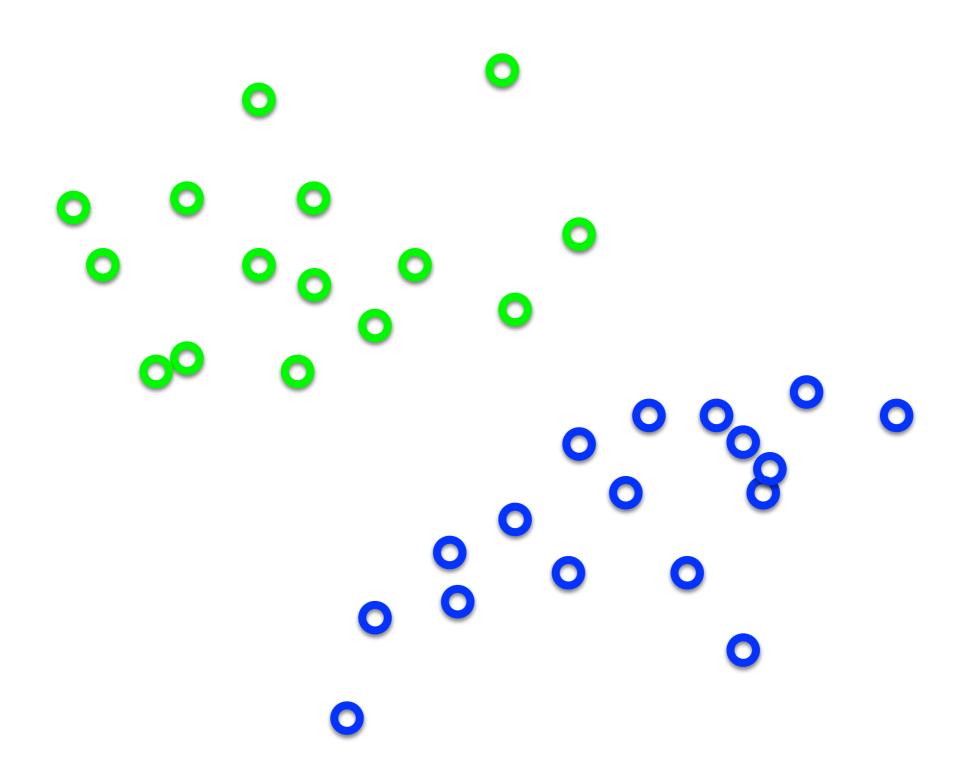
#### Distribution of data from two classes

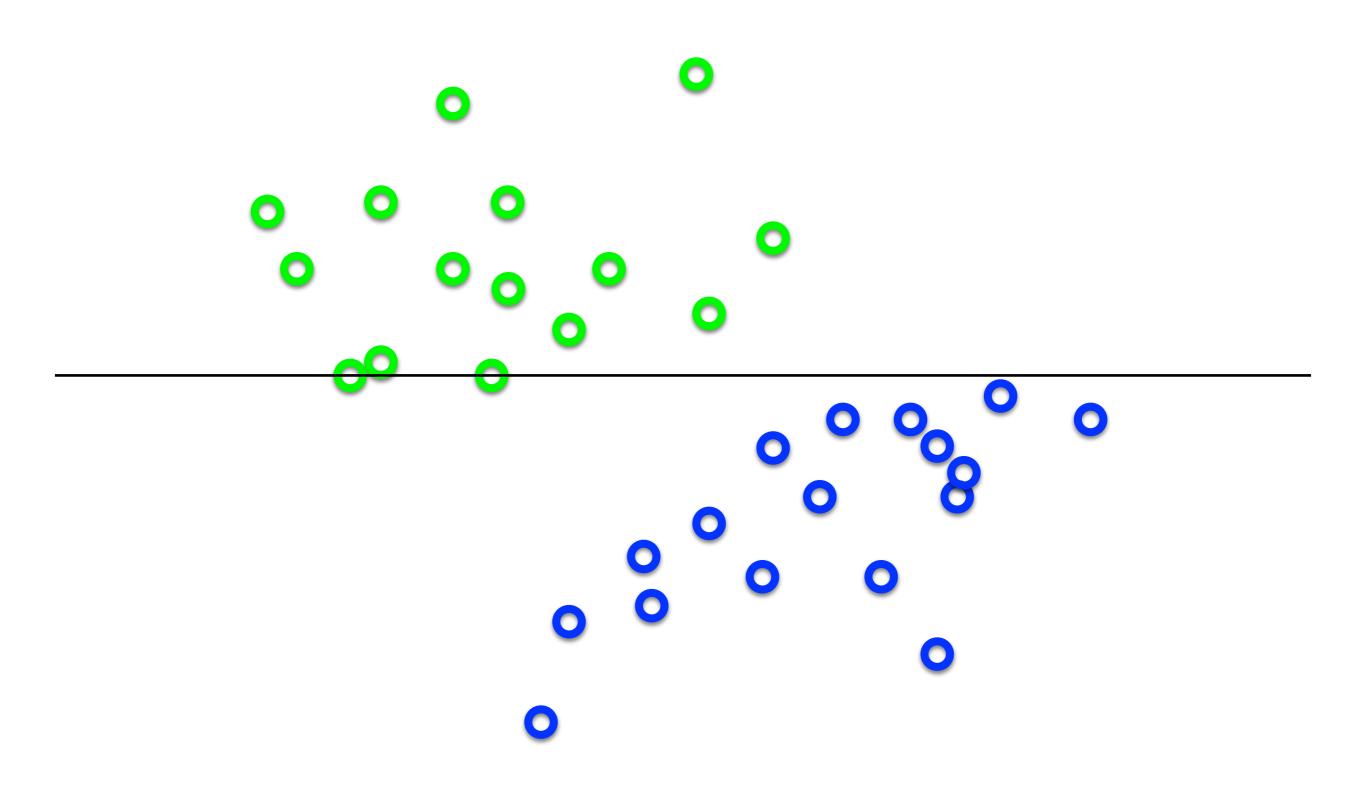


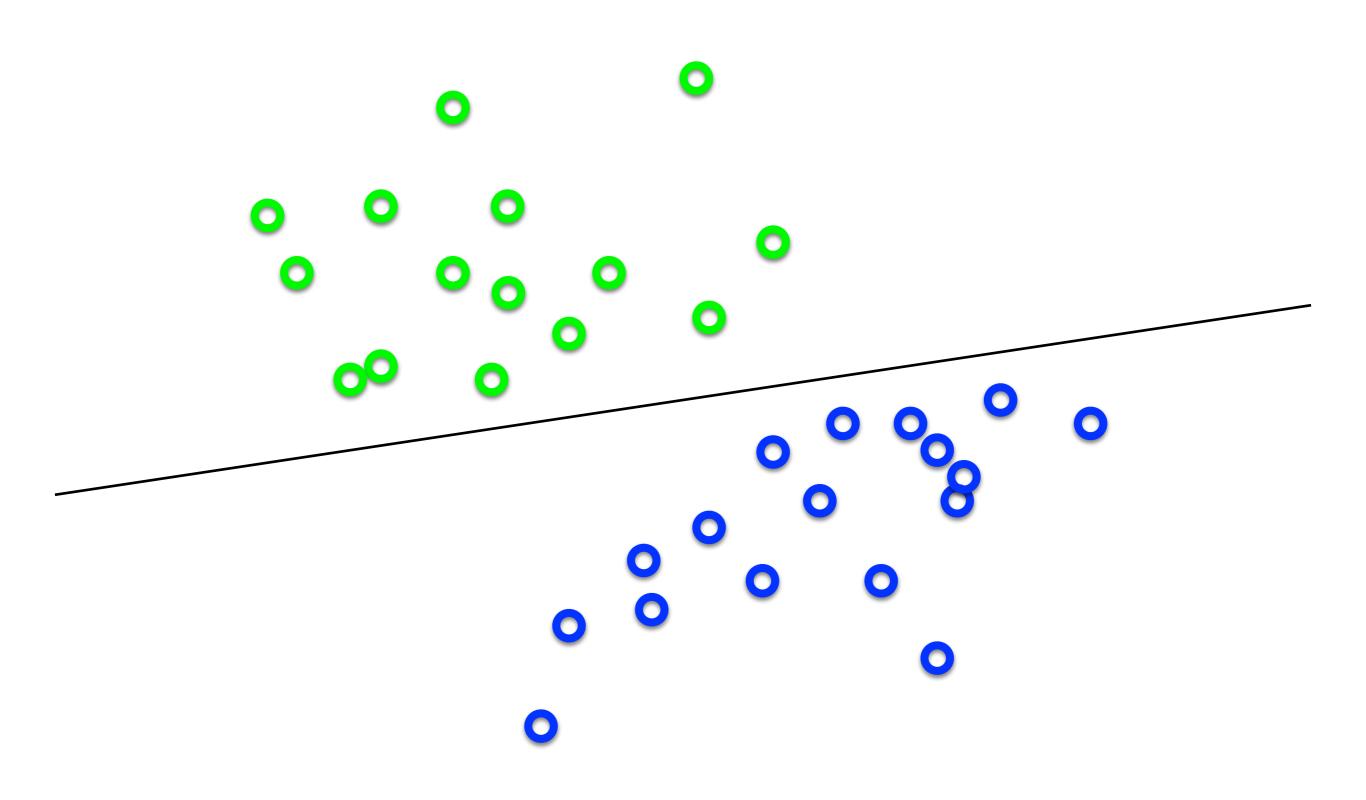
Which class does q belong too?

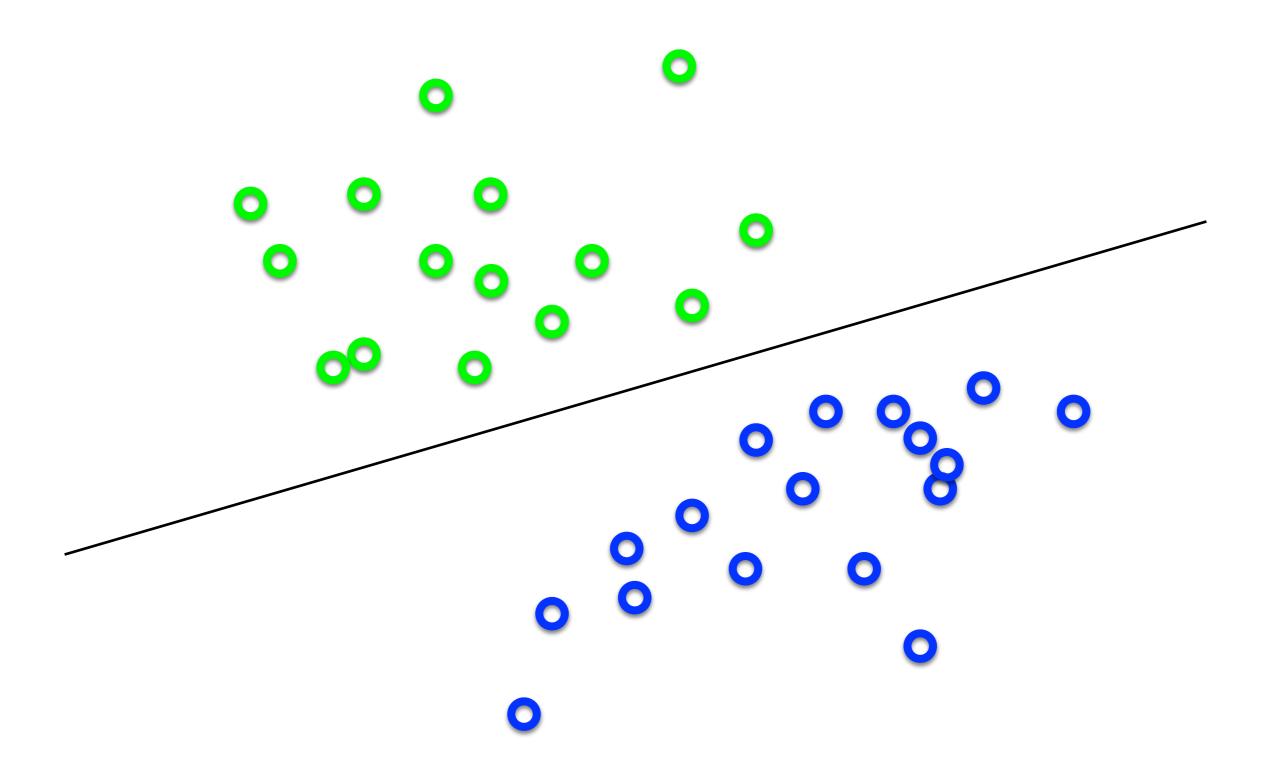
#### Distribution of data from two classes



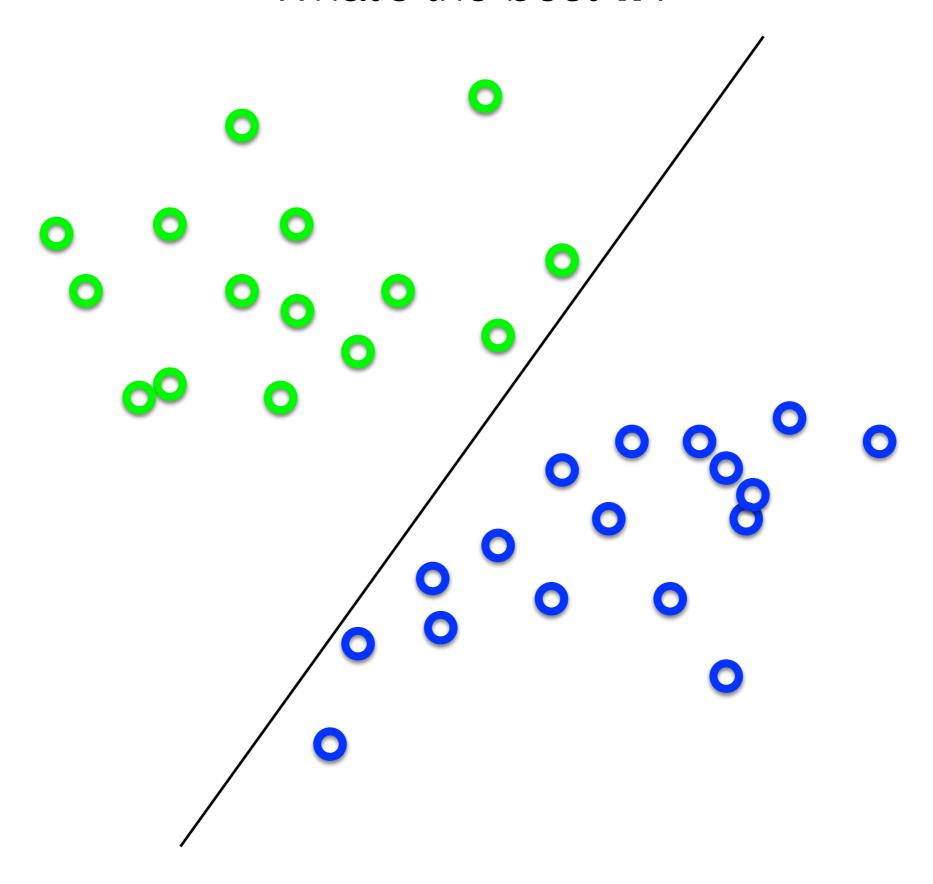


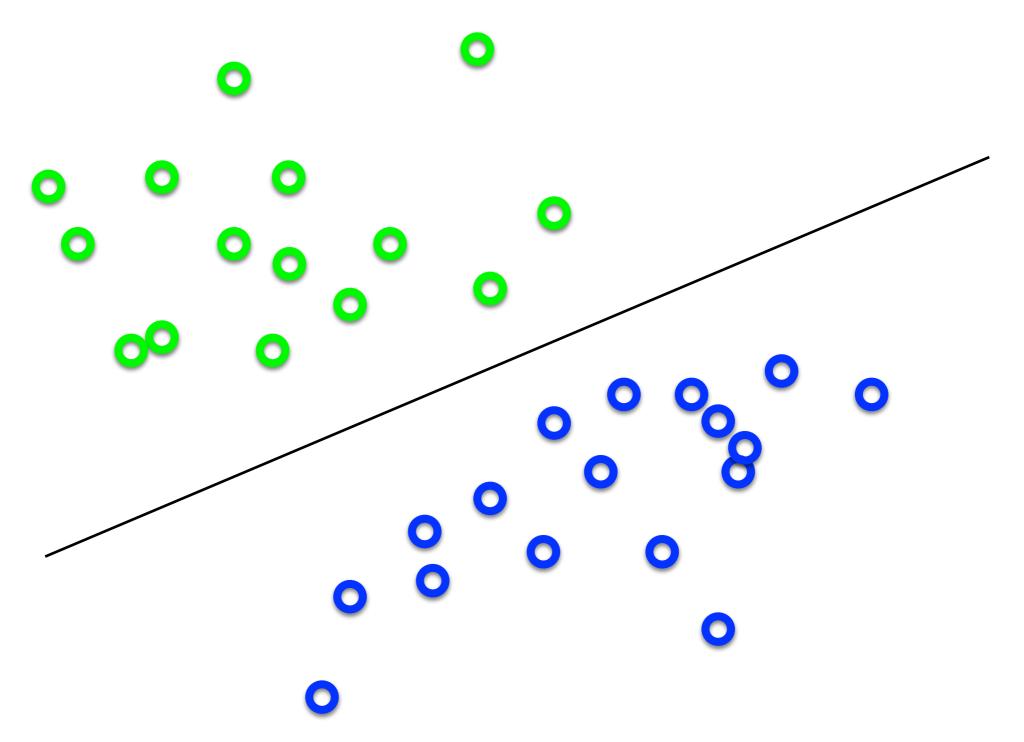




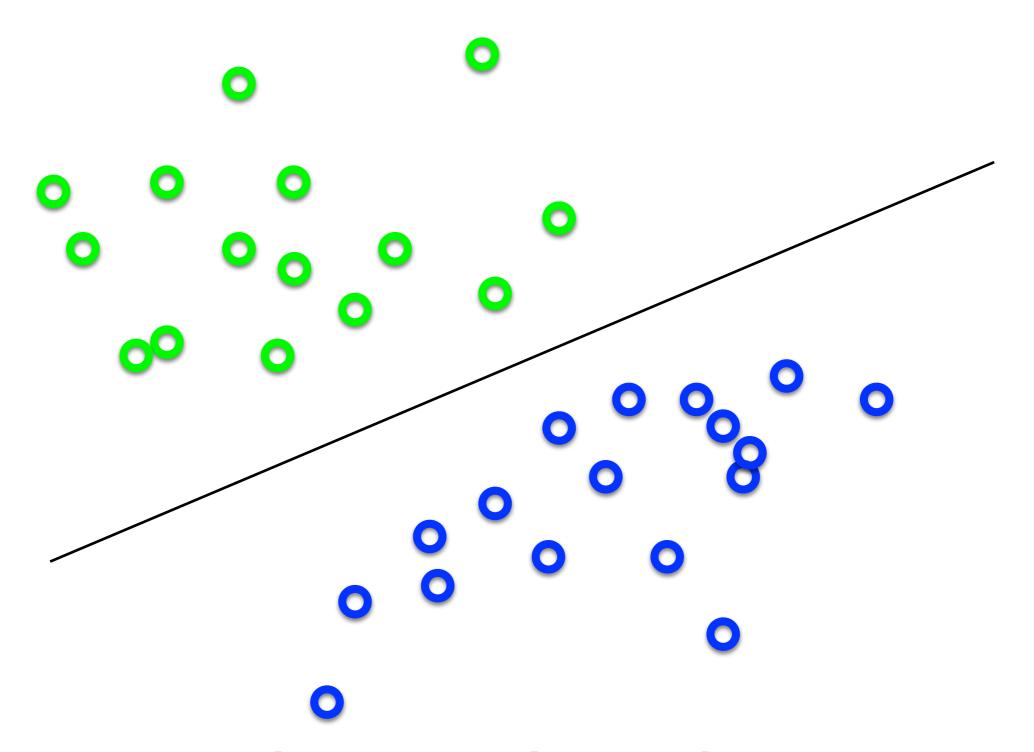


What's the best **w**?



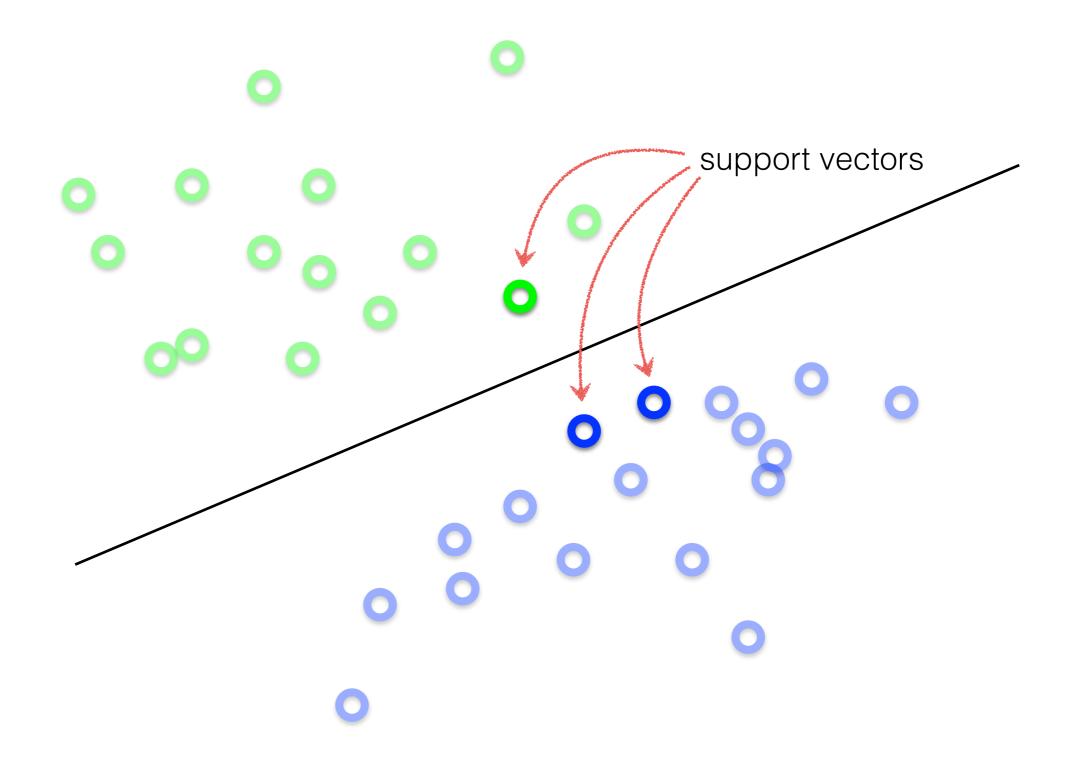


**Intuitively,** the line that is the farthest from all interior points



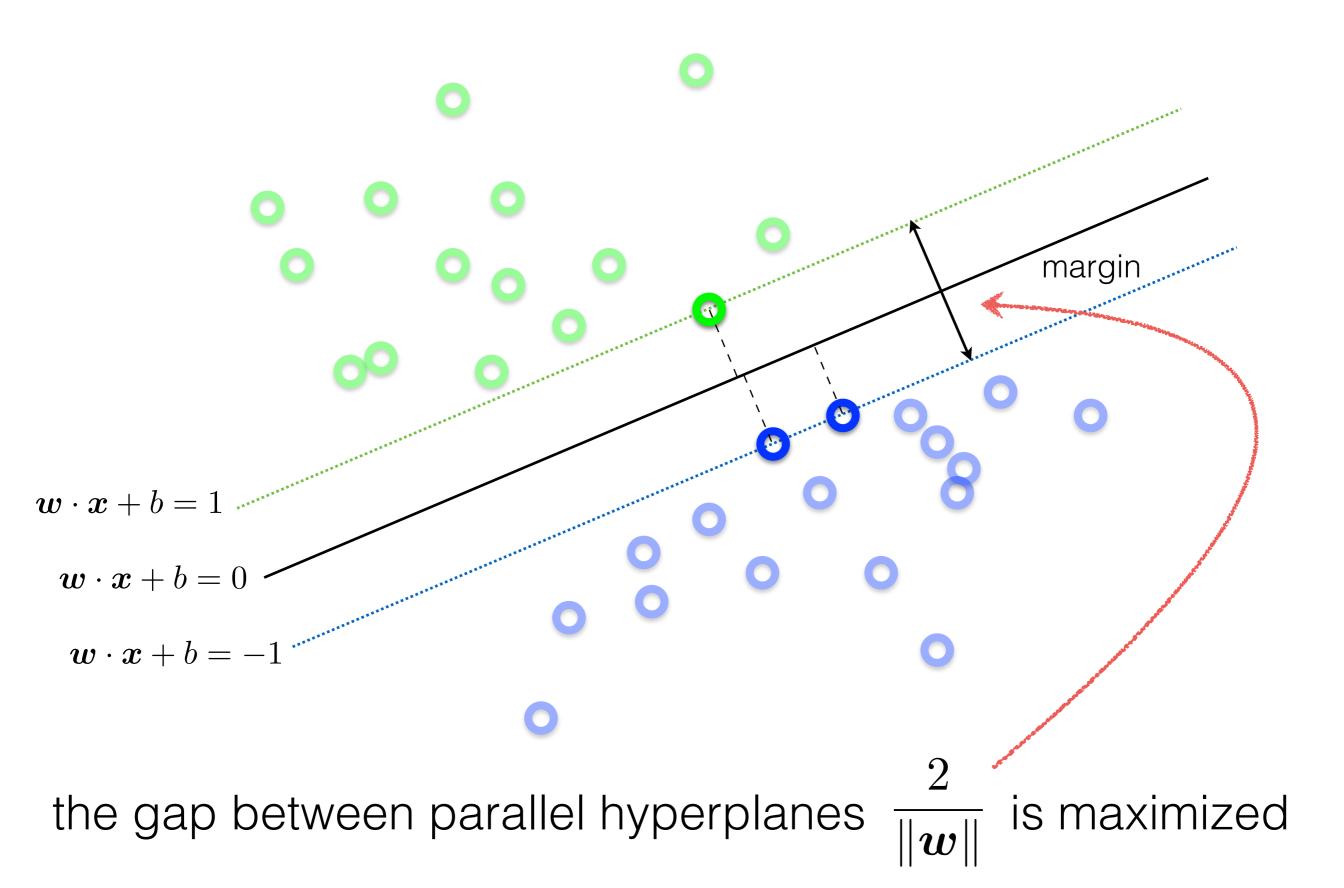
## **Maximum Margin solution:**

most stable to perturbations of data



Want a hyperplane that is far away from 'inner points'

#### Find hyperplane w such that ...



#### Can be formulated as a maximization problem

$$\max_{m{w}} rac{2}{\|m{w}\|}$$

subject to 
$$\boldsymbol{w} \cdot \boldsymbol{x}_i + b \stackrel{\geq}{\leq} +1$$
 if  $y_i = +1$  for  $i = 1, \dots, N$ 

What does this constraint mean?



label of the data point

Why is it +1 and -1?

#### Can be formulated as a maximization problem

Equivalently,

Where did the 2 go?

$$\min_{\boldsymbol{w}} \|\boldsymbol{w}\|$$
 subject to  $y_i(\boldsymbol{w}\cdot\boldsymbol{x}_i+b)\geq 1$  for  $i=1,\ldots,N$ 

What happened to the labels?

#### 'Primal formulation' of a linear SVM

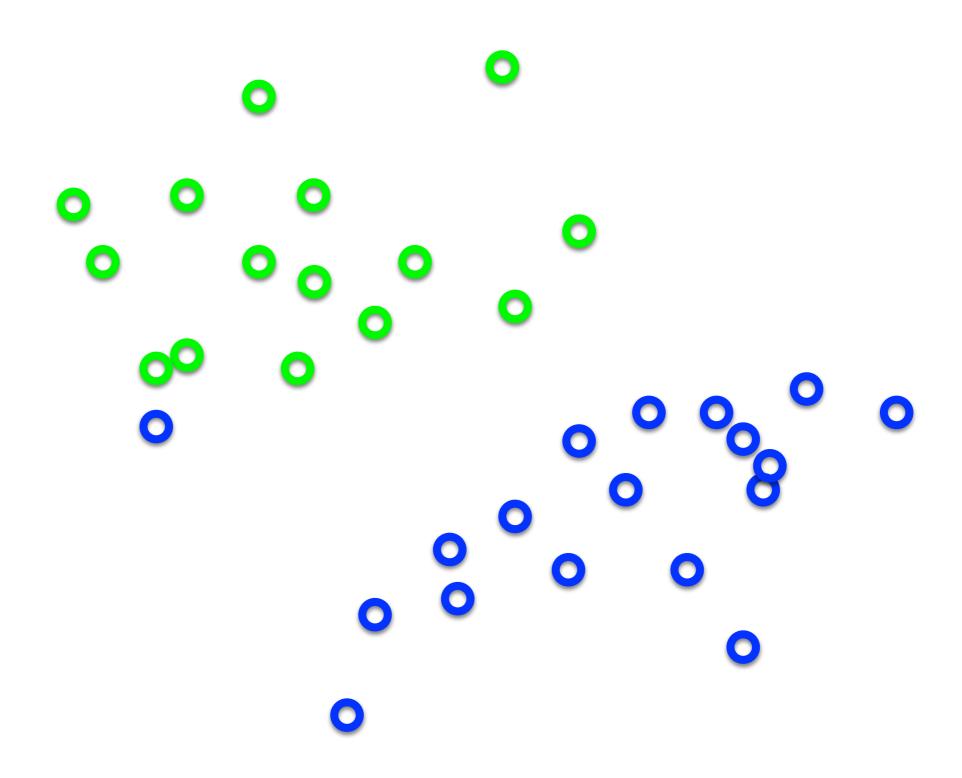
 $\min_{oldsymbol{w}} \|oldsymbol{w}\|$ 

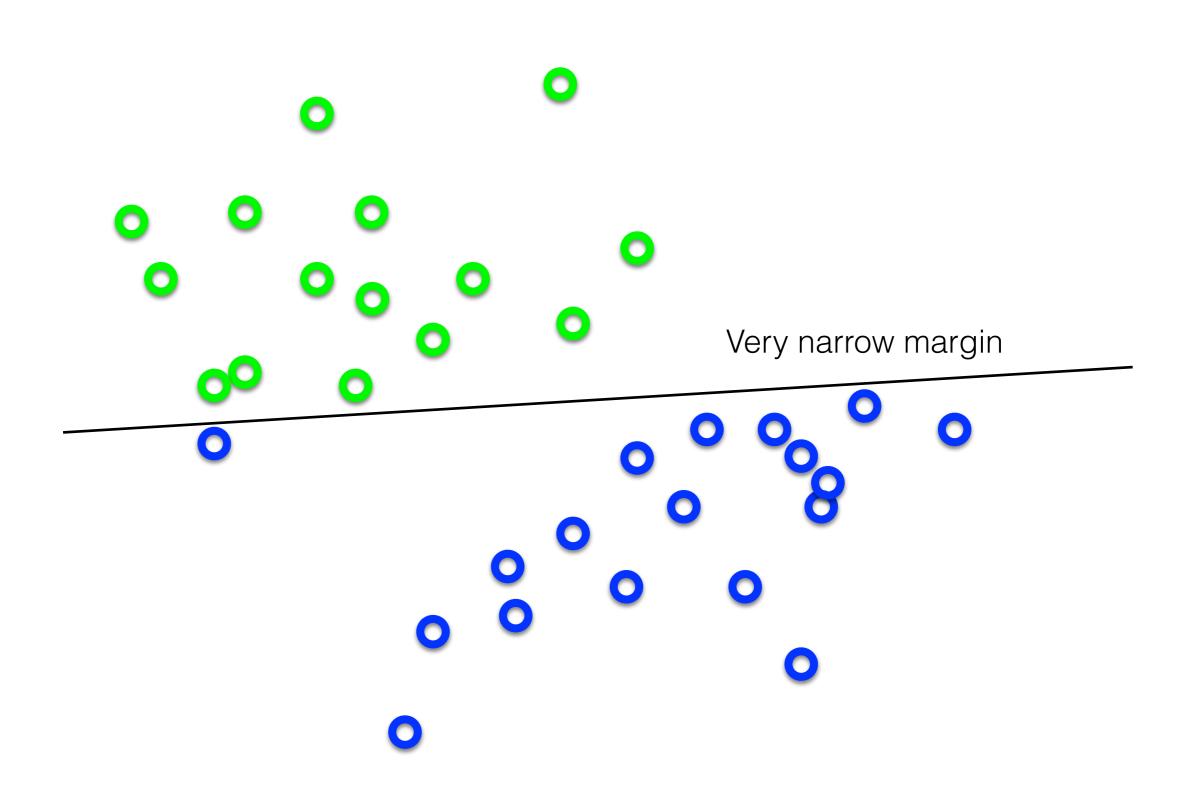
Objective Function

subject to 
$$y_i(\boldsymbol{w} \cdot \boldsymbol{x}_i + b) \ge 1$$
 for  $i = 1, ..., N$ 

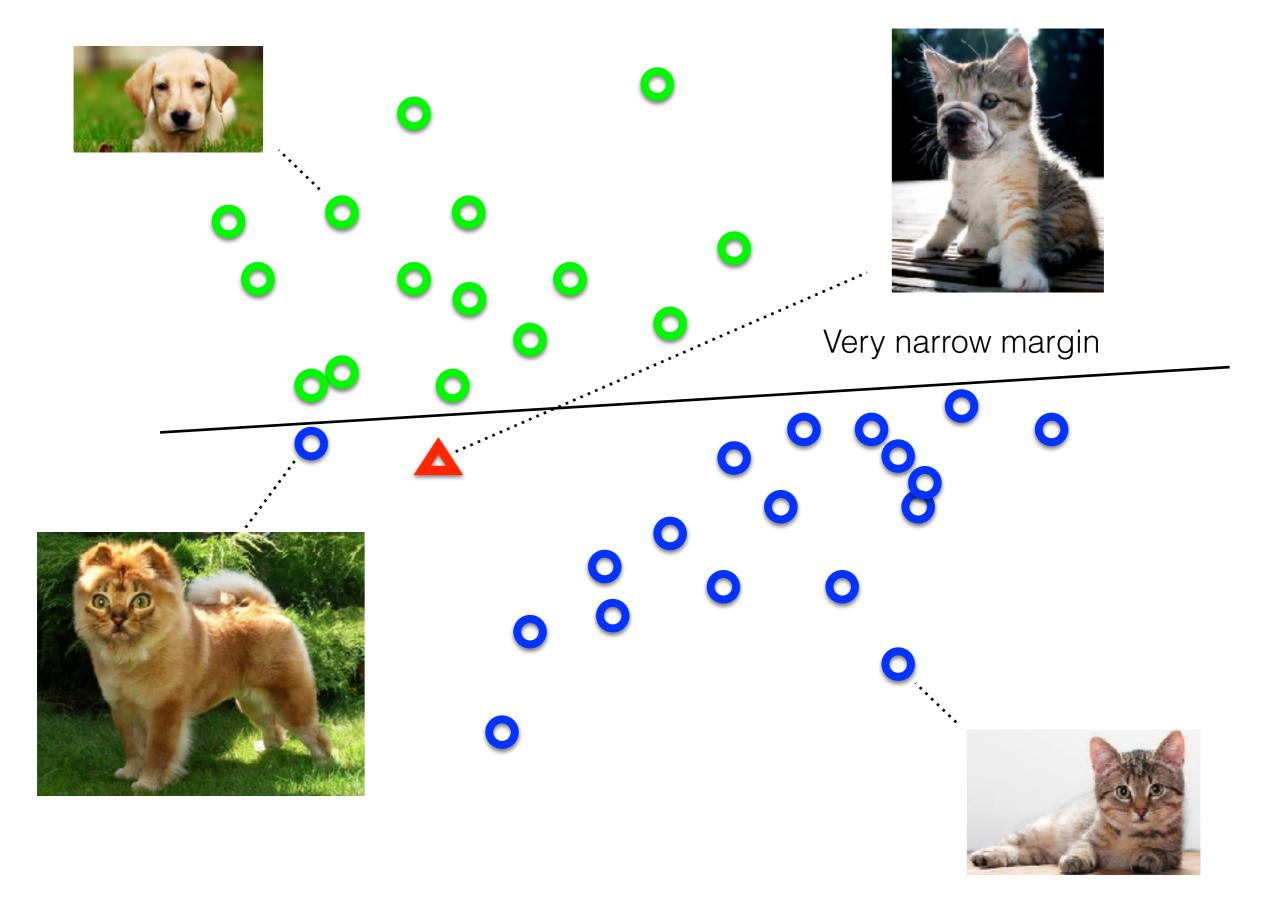
This is a convex quadratic programming (QP) problem (a unique solution exists)

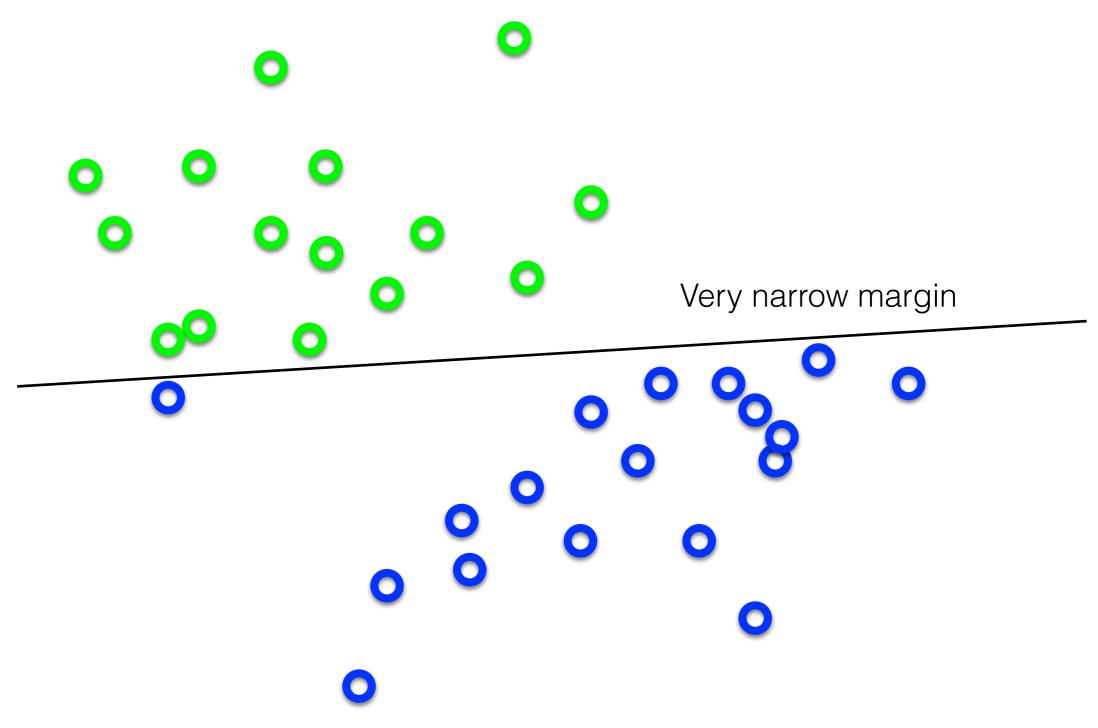
(you can learn more about this in convex optimization)



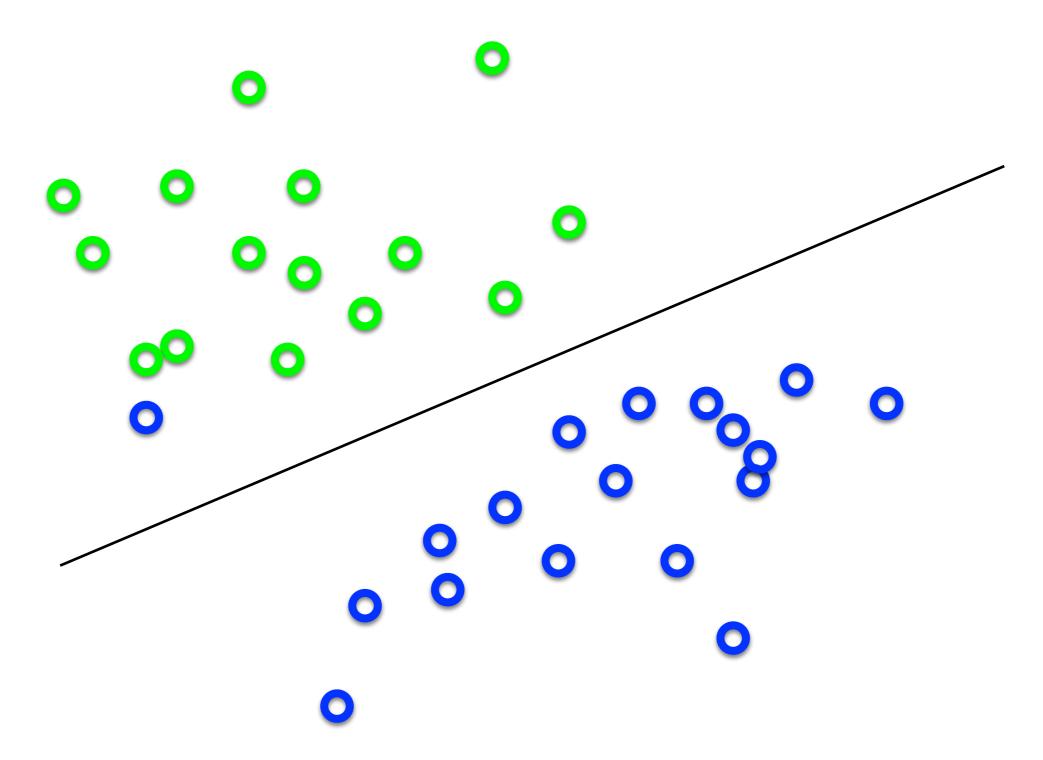


## Separating cats and dogs



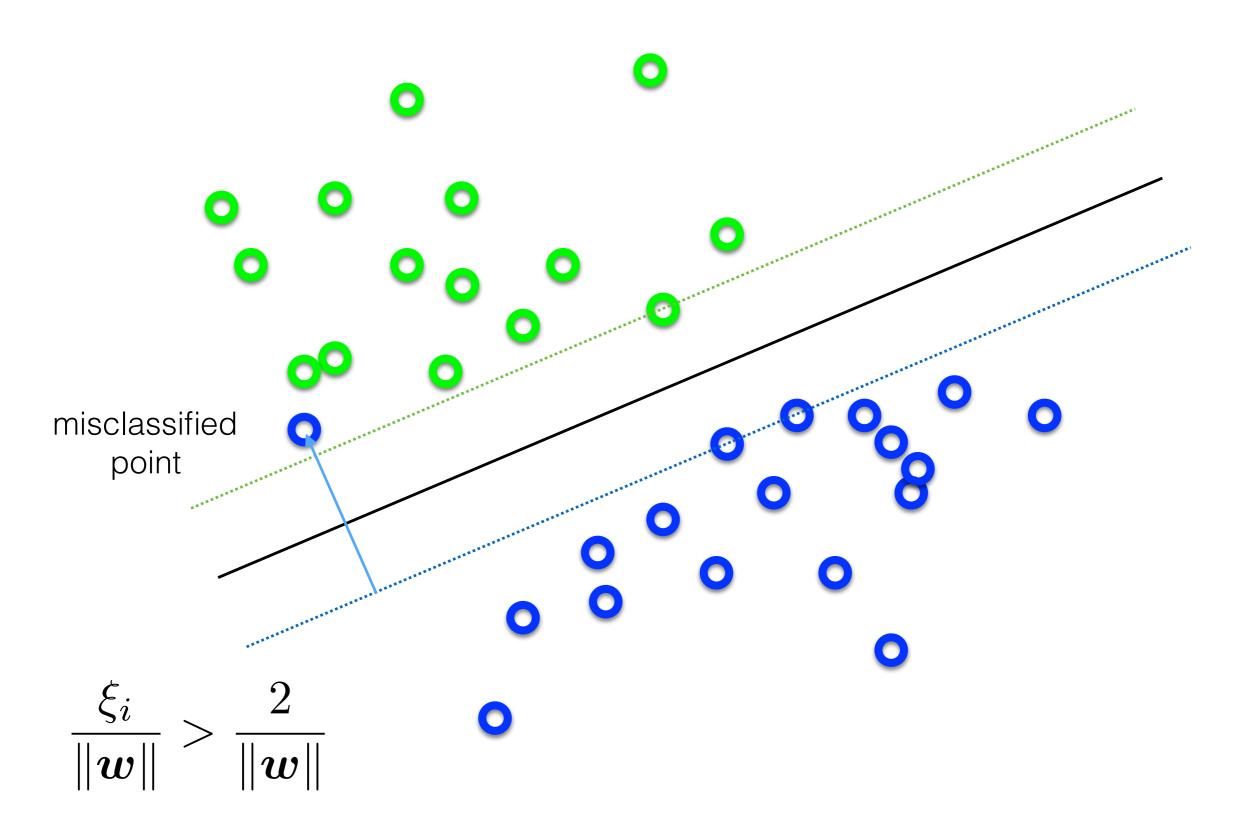


Intuitively, we should allow for some misclassification if we can get more robust classification



Trade-off between the MARGIN and the MISTAKES (might be a better solution)

## Adding slack variables $\xi_i \geq 0$



objective

subject to

$$\min_{\boldsymbol{w},\boldsymbol{\xi}} \|\boldsymbol{w}\|^2 + C \sum_i \xi_i$$

$$y_i(\boldsymbol{w}^{ op}\boldsymbol{x}_i+b)\geq 1-\xi_i$$
 for  $i=1,\ldots,N$ 

objective

subject to

$$\min_{\boldsymbol{w},\boldsymbol{\xi}} \|\boldsymbol{w}\|^2 + C \sum_{i} \xi_i$$

$$y_i(\boldsymbol{w}^{ op}\boldsymbol{x}_i+b) \geq 1-\xi_i$$
 for  $i=1,\ldots,N$ 

The slack variable allows for mistakes, as long as the inverse margin is minimized.

objective

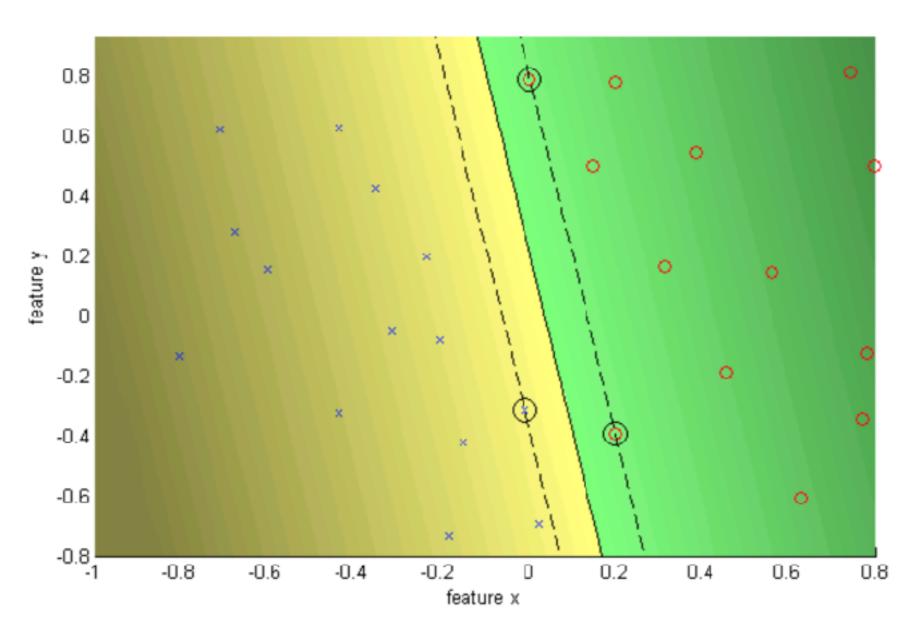
subject to

$$\min_{\boldsymbol{w},\boldsymbol{\xi}} \|\boldsymbol{w}\|^2 + C \sum_{i} \xi_i$$

$$y_i(\boldsymbol{w}^{\top}\boldsymbol{x}_i+b) \geq 1-\xi_i$$
 for  $i=1,\ldots,N$ 

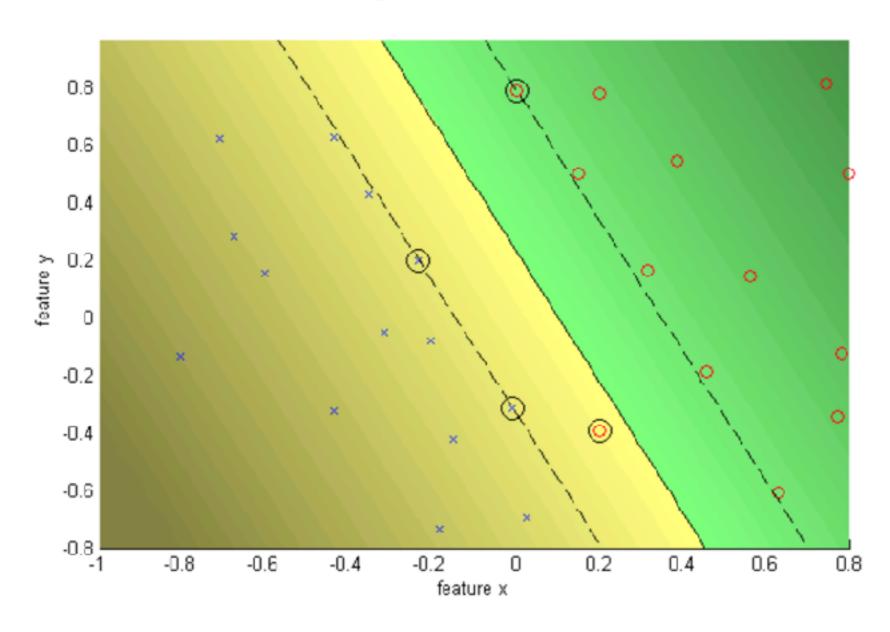
- Every constraint can be satisfied if slack is large
- C is a regularization parameter
  - Small C: ignore constraints (larger margin)
  - Big C: constraints (small margin)
- Still QP problem (unique solution)

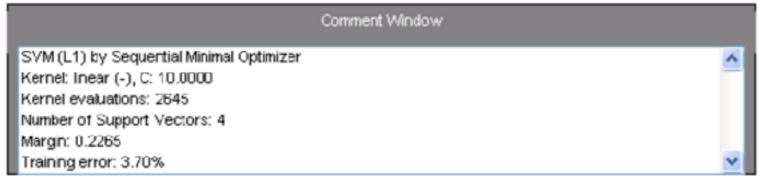
## C = Infinity hard margin





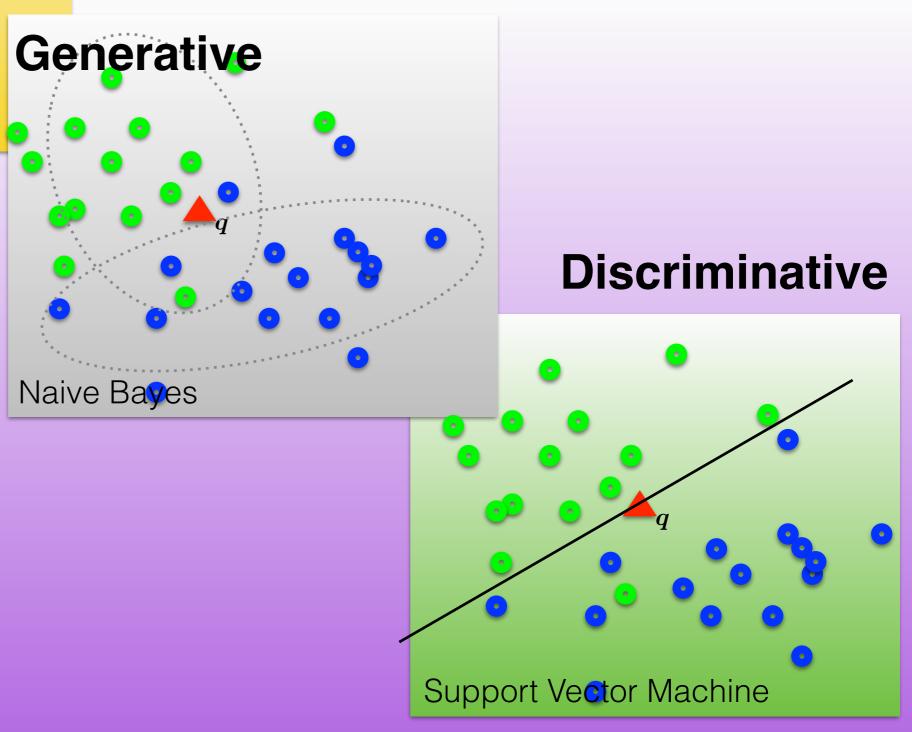
## C = 10 soft margin





# Non-parametric Nearest Neighbor

#### **Parametric**



# 'Classical' Image Classification Pipeline

