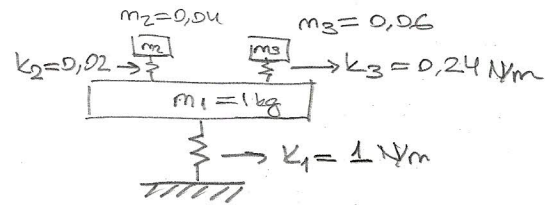


Elle yapılar kontrol



$$\text{In[1]}:= \mathbf{M} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0.04 & 0 \\ 0 & 0 & 0.06 \end{pmatrix} \underline{\mathbf{M}}$$

$$\text{Out[1]}:= \{\{1, 0, 0\}, \{0, 0.04, 0\}, \{0, 0, 0.06\}\}$$

$$\text{In[2]}:= \mathbf{K} = \begin{pmatrix} 1.26 & -0.02 & -0.24 \\ -0.02 & 0.02 & 0 \\ -0.24 & 0 & 0.24 \end{pmatrix} \underline{\mathbf{K}}$$

$$\text{Out[2]}:= \{\{1.26, -0.02, -0.24\}, \{-0.02, 0.02, 0\}, \{-0.24, 0, 0.24\}\}$$

$$\text{In[3]}:=$$

`Inverse[M] // MatrixForm`

$$\text{Out[3]//MatrixForm}:=$$

$$\begin{pmatrix} 1. & 0. & 0. \\ 0. & 25. & 0. \\ 0. & 0. & 16.6667 \end{pmatrix} \mathbf{M}^{-1} \underline{\mathbf{K}}$$

$$\text{In[4]}:=$$

`Inverse[M].K // MatrixForm`

$$\text{Out[4]//MatrixForm}:=$$

$$\begin{pmatrix} 1.26 & -0.02 & -0.24 \\ -0.5 & 0.5 & 0. \\ -4. & 0. & 4. \end{pmatrix} \mathbf{M}^{-1} \underline{\mathbf{K}}$$

$$\text{In[5]}:= \text{Inverse[M].K} - \lambda \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}; (\mathbf{M}^{-1} \underline{\mathbf{K}} - \lambda) \text{ Eigenvalue prob.}$$

`% // MatrixForm`

$$\text{Out[6]//MatrixForm}:=$$

$$\begin{pmatrix} 1.26 - \lambda & -0.02 & -0.24 \\ -0.5 & 0.5 - \lambda & 0. \\ -4. & 0. & 4. - \lambda \end{pmatrix} \longrightarrow (\mathbf{M}^{-1} \underline{\mathbf{K}} - \lambda)$$

$$\text{In[7]}:= \text{Det[\%]}$$

$$\text{Solve[\% == 0]}$$

$$\omega_n = \lambda / . \%$$

$$\text{Out[7]}:= 2. - 6.7 \lambda + 5.76 \lambda^2 - \lambda^3 \longrightarrow \text{karakteristik denk } \det(\mathbf{M}^{-1} \underline{\mathbf{K}} - \lambda)$$

$$\text{Out[8]}:= \{\{\lambda \rightarrow 0.480275\}, \{\lambda \rightarrow 0.96517\}, \{\lambda \rightarrow 4.31455\}\} \longrightarrow \lambda_{1,2,3}$$

$$\text{Out[9]}:= \{0.480275, 0.96517, 4.31455\} \longrightarrow \{\omega_i^2\}$$

★ ÖRNEK PROBLEM ÜZERİNDEN DECOUPLING
MODAL TRANSFORMASYON-MODAL ENERJİ KAVRAMI
NIN SONUÇ BAĞIRNMA ÇALIŞMASI.

```

In[10]:= esys = Eigensystem[Inverse[M].K];
U = Transpose[Reverse[esys[[2]]]];
ω2e = Reverse[esys[[1]]];
ω2 = {{%[[1]], 0, 0}, {0, %[[2]], 0}, {0, 0, %[[3]]}};
% // MatrixForm
U // MatrixForm
Um = U;
Table[
  Um[[All, i]] = U[[All, i]] / Sqrt[ U[[All, i]].M.U[[All, i]] ]
, {i, 1, 3}];
Um // MatrixForm

```

```

Out[14]//MatrixForm=

```

$$\begin{pmatrix} 0.480275 & 0 & 0 \\ 0 & 0.96517 & 0 \\ 0 & 0 & 4.31455 \end{pmatrix} \rightarrow [\omega_i^2]$$

```

Out[15]//MatrixForm=

```

$$\begin{pmatrix} -0.0393794 & 0.506853 & -0.0783925 \\ -0.998222 & -0.544804 & 0.0102754 \\ -0.0447528 & 0.668048 & 0.99687 \end{pmatrix} \rightarrow U \text{ (özevektörler)}$$

```

Out[18]//MatrixForm=

```

$$\begin{pmatrix} -0.193239 & 0.932324 & -0.305665 \\ -4.89838 & -1.00213 & 0.0400656 \\ -0.219607 & 1.22883 & 3.88695 \end{pmatrix} \rightarrow \text{Kütte normalize özevektörler } U_m$$

```

Mm = Round[Transpose[U].M.U, 0.000000000000001];
% // MatrixForm
Km = Round[Transpose[U].K.U, 0.000000000000001];
% // MatrixForm

```

> Nodal Transformasyonu
üçgenin kütte ve yay matris-
leri

```

Out[20]//MatrixForm=

```

$$\begin{pmatrix} 0.0415288 & 0 & 0 \\ 0 & 0.29555 & 0 \\ 0 & 0 & 0.0657746 \end{pmatrix} \rightarrow U' = U_m = U^T U U$$

```

Out[22]//MatrixForm=

```

$$\begin{pmatrix} 0.0199452 & 0 & 0 \\ 0 & 0.285256 & 0 \\ 0 & 0 & 0.283788 \end{pmatrix} \rightarrow K' = K_m = U^T K U$$

Diagonalize edilmiş (Uncoupling)

```

In[26]:= {Km // MatrixForm, ω2 // MatrixForm, Mm // MatrixForm}

```

```

Out[26]= {

```

$$\begin{pmatrix} 0.0199452 & 0 & 0 \\ 0 & 0.285256 & 0 \\ 0 & 0 & 0.283788 \end{pmatrix} \rightarrow K_m$$

$$\begin{pmatrix} 0.480275 & 0 & 0 \\ 0 & 0.96517 & 0 \\ 0 & 0 & 4.31455 \end{pmatrix}, \begin{pmatrix} 0.0415288 & 0 & 0 \\ 0 & 0.29555 & 0 \\ 0 & 0 & 0.0657746 \end{pmatrix} \rightarrow M_m$$

```

In[27]:= Km - ω2.Mm // MatrixForm
Round[Det[%], .000000000000001] == 0

```

```

Out[27]//MatrixForm=

```

$$\begin{pmatrix} 2.76515 \times 10^{-15} & 0 & 0 \\ 0 & 3.33067 \times 10^{-15} & 0 \\ 0 & 0 & 2.10942 \times 10^{-15} \end{pmatrix} \rightarrow \underline{\underline{K_m - \lambda M_m \approx 0}}$$

```

Out[28]= True

```

$\leftarrow K_m - \lambda M_m = ? 0$

In[29]:= True

"Aynisinin Mass Normalizationla"

Mm = Round[Transpose[Um].M.Um, 0.000000000000001];

% // MatrixForm

Km = Round[Transpose[Um].K.Um, 0.000000000000001];

% // MatrixForm

{Km // MatrixForm, ω2 // MatrixForm, Mm // MatrixForm}

Km - ω2.Mm // MatrixForm

Round[Det[%], .000000000000001] == 0

Out[29]= True

Out[30]= Aynisinin Mass Normalizationla

Out[32]//MatrixForm=

$$\begin{pmatrix} 1. & 0 & 0 \\ 0 & 1. & 0 \\ 0 & 0 & 1. \end{pmatrix} \rightarrow \tilde{M} = U^T M U \rightarrow \text{Kütle normalize ve diagonalize edilmiş modal M}$$

Out[34]//MatrixForm=

$$\begin{pmatrix} 0.480275 & 0 & 0 \\ 0 & 0.96517 & 0 \\ 0 & 0 & 4.31455 \end{pmatrix} \rightarrow \tilde{K} = U^T K U \rightarrow \text{Kütle normalize ve diag... moda K}$$

$$\text{Out[35]} = \left\{ \begin{pmatrix} 0.480275 & 0 & 0 \\ 0 & 0.96517 & 0 \\ 0 & 0 & 4.31455 \end{pmatrix}, \begin{pmatrix} 0.480275 & 0 & 0 \\ 0 & 0.96517 & 0 \\ 0 & 0 & 4.31455 \end{pmatrix}, \begin{pmatrix} 1. & 0 & 0 \\ 0 & 1. & 0 \\ 0 & 0 & 1. \end{pmatrix} \right\}$$

Out[36]//MatrixForm=

$$\begin{pmatrix} 2.77556 \times 10^{-16} & 0. & 0. \\ 0. & -2.22045 \times 10^{-15} & 0. \\ 0. & 0. & -1.77636 \times 10^{-15} \end{pmatrix} \rightarrow \tilde{K} - \lambda \tilde{M} = \lambda - \lambda I = 0$$

$\tilde{K} = \lambda = [\omega_i^2]$ $\lambda = [\omega_i^2]$ $\tilde{M} = I$

Out[37]= True

$$\text{Det}[\tilde{K} - \lambda \tilde{M}] \stackrel{?}{=} 0$$

In[174]= "Modal Cozum"

ηm = Table[Ci * Cos[Sqrt[ω2[[i, i]]] * t - φi], {i, 1, 3}];

% // MatrixForm

xm = Um.ηm;

% // MatrixForm

x = xm;

1/2 * (D[x, t].M.D[x, t] + x.K.x)

Simplify[%]

1/2 * (ω2.ηm^2 + D[ηm, t]^2)

Simplify[%]

Out[174]= Modal Cozum

Out[176]//MatrixForm=

$$\begin{pmatrix} \text{Cos}[0.693019 t - \phi_1] C_1 \\ \text{Cos}[0.982431 t - \phi_2] C_2 \\ \text{Cos}[2.07715 t - \phi_3] C_3 \end{pmatrix} \rightarrow \text{Modal koordinatlar } \{\eta_m\}$$

Out[178]//MatrixForm=

$$\begin{pmatrix} -0.193239 \text{Cos}[0.693019 t - \phi_1] C_1 + 0.932324 \text{Cos}[0.982431 t - \phi_2] C_2 - 0.305665 \text{Cos}[2.07715 t - \phi_3] \\ -4.89838 \text{Cos}[0.693019 t - \phi_1] C_1 - 1.00213 \text{Cos}[0.982431 t - \phi_2] C_2 + 0.0400656 \text{Cos}[2.07715 t - \phi_3] \\ -0.219607 \text{Cos}[0.693019 t - \phi_1] C_1 + 1.22883 \text{Cos}[0.982431 t - \phi_2] C_2 + 3.88695 \text{Cos}[2.07715 t - \phi_3] \end{pmatrix}$$

$$\rightarrow x = U \cdot \eta_m \quad (\text{Genelleştirilmiş esas koordinatlar modal koordinatlarda yazılışı})$$

4)

$$\text{Out[180]} = \frac{1}{2} (0.06 (0.152192 \sin[0.693019 t - \phi_1] C_1 -$$

$$\begin{aligned} & 1.20724 \sin[0.982431 t - \phi_2] C_2 - 8.07379 \sin[2.07715 t - \phi_3] C_3)^2 + \\ & 0.04 (3.39467 \sin[0.693019 t - \phi_1] C_1 + 0.984525 \sin[0.982431 t - \phi_2] C_2 - \\ & 0.0832223 \sin[2.07715 t - \phi_3] C_3)^2 + \\ & (0.133918 \sin[0.693019 t - \phi_1] C_1 - 0.915943 \sin[0.982431 t - \phi_2] C_2 + \\ & 0.634912 \sin[2.07715 t - \phi_3] C_3)^2 + \\ & (-4.89838 \cos[0.693019 t - \phi_1] C_1 - 1.00213 \cos[0.982431 t - \phi_2] C_2 + \\ & 0.0400656 \cos[2.07715 t - \phi_3] C_3) \\ & (-0.02 (-0.193239 \cos[0.693019 t - \phi_1] C_1 + 0.932324 \cos[0.982431 t - \phi_2] C_2 - \\ & 0.305665 \cos[2.07715 t - \phi_3] C_3) + 0.02 (-4.89838 \cos[0.693019 t - \phi_1] C_1 - \\ & 1.00213 \cos[0.982431 t - \phi_2] C_2 + 0.0400656 \cos[2.07715 t - \phi_3] C_3)) + \\ & (-0.193239 \cos[0.693019 t - \phi_1] C_1 + 0.932324 \cos[0.982431 t - \phi_2] C_2 - \\ & 0.305665 \cos[2.07715 t - \phi_3] C_3) \\ & (1.26 (-0.193239 \cos[0.693019 t - \phi_1] C_1 + 0.932324 \cos[0.982431 t - \phi_2] C_2 - \\ & 0.305665 \cos[2.07715 t - \phi_3] C_3) - 0.02 (-4.89838 \cos[0.693019 t - \phi_1] C_1 - \\ & 1.00213 \cos[0.982431 t - \phi_2] C_2 + 0.0400656 \cos[2.07715 t - \phi_3] C_3) - \\ & 0.24 (-0.219607 \cos[0.693019 t - \phi_1] C_1 + 1.22883 \cos[0.982431 t - \phi_2] C_2 + \\ & 3.88695 \cos[2.07715 t - \phi_3] C_3)) + \\ & (-0.219607 \cos[0.693019 t - \phi_1] C_1 + 1.22883 \cos[0.982431 t - \phi_2] C_2 + \\ & 3.88695 \cos[2.07715 t - \phi_3] C_3) \\ & (-0.24 (-0.193239 \cos[0.693019 t - \phi_1] C_1 + 0.932324 \cos[0.982431 t - \phi_2] C_2 - \\ & 0.305665 \cos[2.07715 t - \phi_3] C_3) + 0.24 (-0.219607 \cos[0.693019 t - \phi_1] C_1 + \\ & 1.22883 \cos[0.982431 t - \phi_2] C_2 + 3.88695 \cos[2.07715 t - \phi_3] C_3)) \end{aligned}$$

$$\begin{aligned} \text{Out[181]} = & (0.240138 \cos[0.693019 t - \phi_1]^2 + 0.240138 \sin[0.693019 t - \phi_1]^2) C_1^2 + \\ & (0.482585 \cos[0.982431 t - \phi_2]^2 + 0.482585 \sin[0.982431 t - \phi_2]^2) C_2^2 + \\ & (-1.22645 \times 10^{-15} \cos[0.982431 t - \phi_2] \cos[2.07715 t - \phi_3] - \\ & 1.22125 \times 10^{-15} \sin[0.982431 t - \phi_2] \sin[2.07715 t - \phi_3]) C_2 C_3 + \\ & (2.15728 \cos[2.07715 t - \phi_3]^2 + 2.15728 \sin[2.07715 t - \phi_3]^2) C_3^2 + \\ & C_1 ((-1.94289 \times 10^{-16} \cos[0.693019 t - \phi_1] \cos[0.982431 t - \phi_2] - \\ & 4.71845 \times 10^{-16} \sin[0.693019 t - \phi_1] \sin[0.982431 t - \phi_2]) C_2 + \\ & (1.38778 \times 10^{-16} \cos[0.693019 t - \phi_1] \cos[2.07715 t - \phi_3] - \\ & 2.498 \times 10^{-16} \sin[0.693019 t - \phi_1] \sin[2.07715 t - \phi_3]) C_3) \end{aligned}$$

$$\begin{aligned} \text{Out[182]} = & \left\{ \frac{1}{2} (0.480275 \cos[0.693019 t - \phi_1]^2 C_1^2 + 0.480275 \sin[0.693019 t - \phi_1]^2 C_1^2), \right. \\ & \frac{1}{2} (0.96517 \cos[0.982431 t - \phi_2]^2 C_2^2 + 0.96517 \sin[0.982431 t - \phi_2]^2 C_2^2), \\ & \left. \frac{1}{2} (4.31455 \cos[2.07715 t - \phi_3]^2 C_3^2 + 4.31455 \sin[2.07715 t - \phi_3]^2 C_3^2) \right\} \end{aligned}$$

$$\text{Out[183]} = \{0.240138 C_1^2, 0.482585 C_2^2, (2.15728 \cos[2.07715 t - \phi_3]^2 + 2.15728 \sin[2.07715 t - \phi_3]^2) C_3^2\}$$

$$\text{yani } E_{\text{TOP}} = E_{\text{modal}}$$

$$\Rightarrow \frac{1}{2} (x^T K x + \dot{x}^T M \dot{x}) = \frac{1}{2} (\omega_1^2 \dot{q}^2 + \dot{q}^2)$$

$$= \frac{1}{2} (\omega_1^2 C_1^2 + \omega_2^2 C_2^2 + \omega_3^2 C_3^2)$$

C'ler bağımsız koşullarına bağlı

* Peki burada Primary'nin ayrı sattaalıkların ayrı modal Enerjisi gözüküyor Neden? (Çünkü bu Modal Enerji TOPLAM)

Enerji Top:

$$E_{\text{TOP}} = \frac{1}{2} (x^T K x + \dot{x}^T M \dot{x})$$

Quadratik

E_{TOP} basitleştirilmiş

$$0.240138 C_1^2 + 0.482585 C_2^2 + 2.15728 C_3^2$$

$$E_M = \frac{1}{2} (\omega_1^2 \dot{q}^2 + \dot{q}^2)$$