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MEE 472: SENIOR CAPSTONE DESIGN SPRING  
2024

# Universal Adjustable Antenna Mounting System

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**STUDENT TEAM:**

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REN

**FACULTY MENTOR:**

DR. MICHELLE BLUM

MAY 1, 2024

# Student Team

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**Teagan Kilian**  
CAD

**Nick Frank**  
Failure Analysis

**Pei Ren**  
Materials Research



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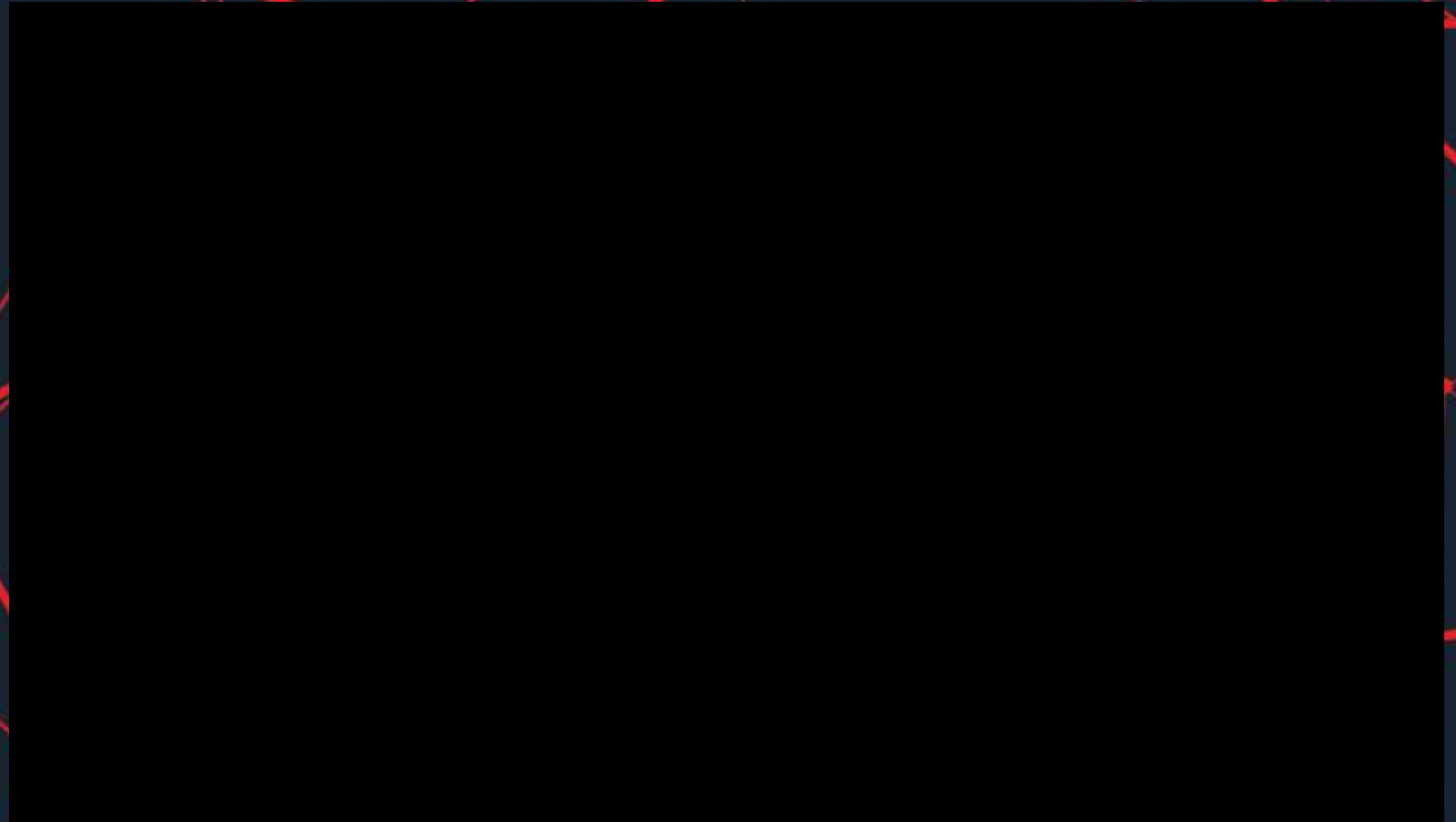
**Company**

**Mentors**

Peter Burke

Pete Hunt

Tim Gerlach



# Problem

Antennas need to be installed *temporarily*, *quickly*, and *securely* onto helicopters for product demonstrations

- Flights last a few hours
- Antennas must be able to
  - Be recovered easily
  - Leave no modification to the helicopter

Current Solution:

- Zip tie antennas to the exterior of the helicopter



## FALCON III® RF-7850A-TM001 ROLL-ON / ROLL-OFF AIRBORNE SYSTEM

For use with the L3Harris Falcon III RF-7850A-MR, the L3Harris RF-7850A-TM001 Roll-On/Roll-Off System enables any mission-critical airborne platform to add multiband networking capabilities for enhanced and secure air-to-ground interoperability and greater mission success.



## ACCESSORIES



RF-3024-HS001 Headset



RF-6705-SW001 Tactical Chat™ IP

# Project Specifications

**Task: Create a universal antenna mounting system to temporarily attach to a helicopter**

## Reliable

- Withstands windspeeds up to 150 mph
- Secures antennas up to 10lbs
- Performs under flight weather conditions

## Universal

- Mounts variety of antennas
- Attaches to various helicopters
- Functions as counterpoise for monopole antennas

## User-friendly

- Installation and removal with little to no training
- Minimal parts

## Sustainable

- No damage or permanent modification to helicopter/antenna
- Reusable for other helicopters



# Common Helicopter for this Application

## UH-1 Huey



Red indicates possible attachment points for the antenna mounting system

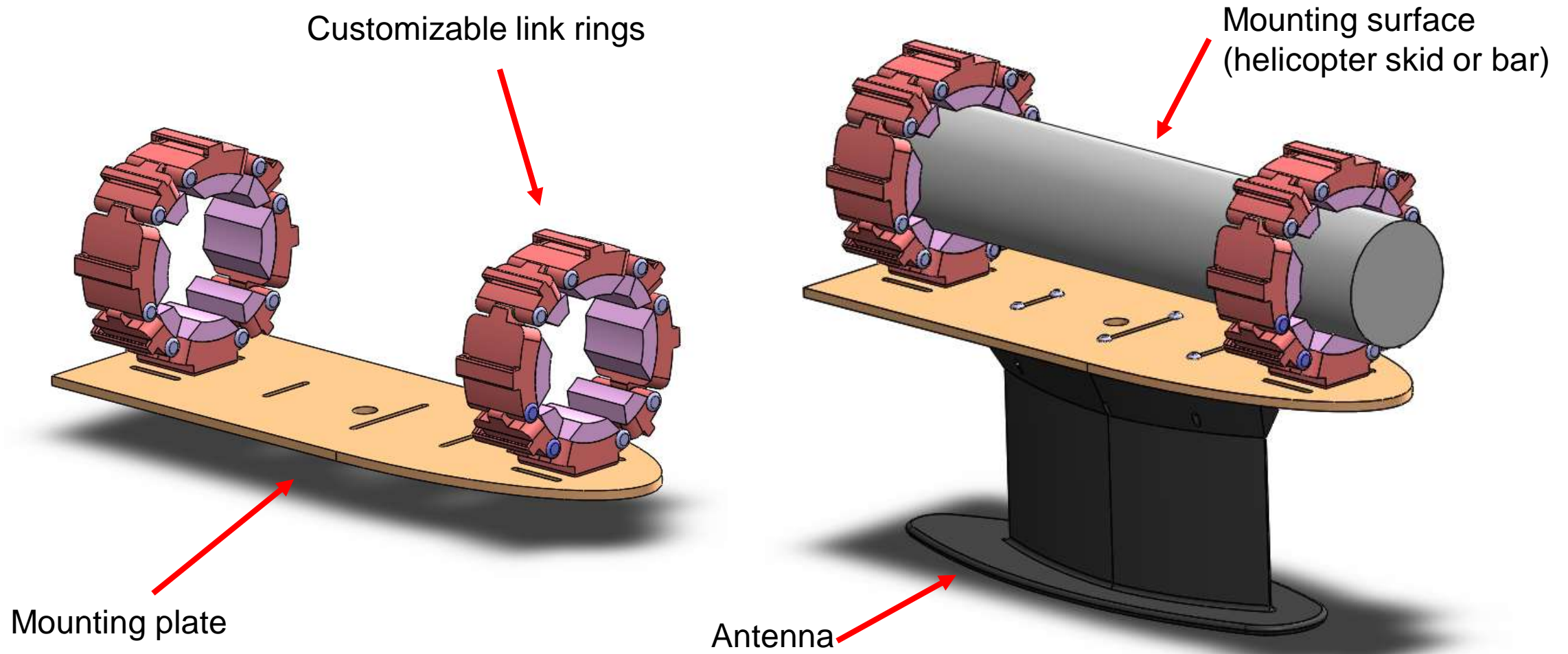
# Pugh Matrix: The Need for New Design

Selection Criteria	Current Solutions			Design Concepts for New Solutions		
	Zip-tie	Velcro strap	Custom mount	Suction cup	Modular links	Ratchet strap
Withstand up to 150 mph windspeed	1	1	2	0	2	2
Secure antennas up to 10 lbs.	2	1	2	0	1	2
User-friendly for installation and removal	2	2	0	2	0	1
Adaptable to various antennas	1	1	0	2	2	1
Adaptable to various helicopters	1	2	0	2	2	2
Secure counterpoise for monopoles	0	0	2	1	2	1
No permanent modification to helicopter or antenna	2	2	0	2	2	2
Sustainable	0	0	1	2	2	1
Limit possibility of airborne projectiles	2	2	2	1	2	2
Reliable for use case period	0	0	2	0	1	0
Economically efficient	2	2	0	2	1	2
Score for Design Selection	13	13	11	15	17	16

**Key:**

- 0 – Not Satisfactory**
- 1 – Somewhat Satisfactory**
- 2 – Satisfactory**

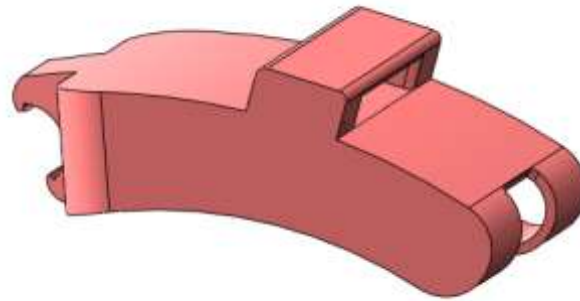
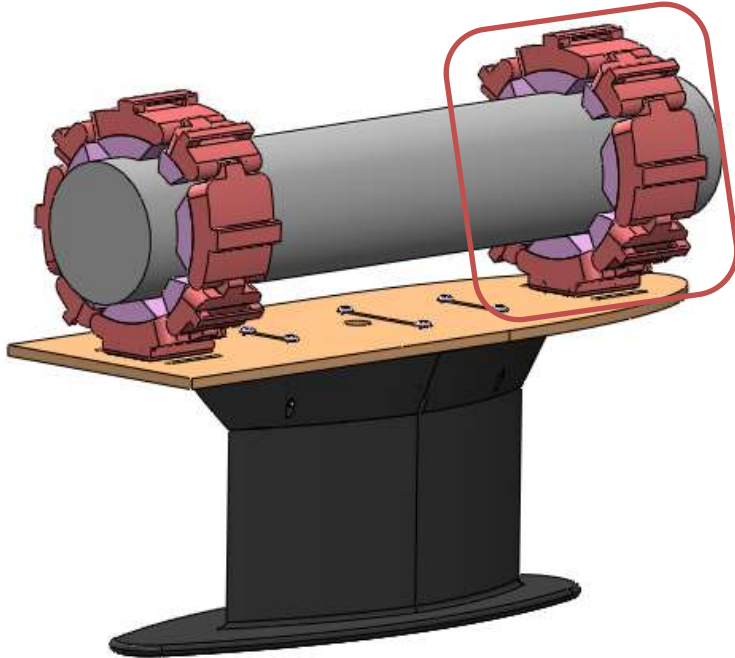
# UAAMS Assembly



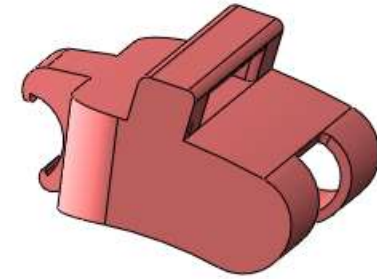


# Link Ring Concept

- Providing “large links” and “small links” to our client
- Magnetic attraction between adjacent links for **ease of assembly**
- Strap fed through each link **provides compressive force**
- Safety wire fed through each link as a **safety precaution**

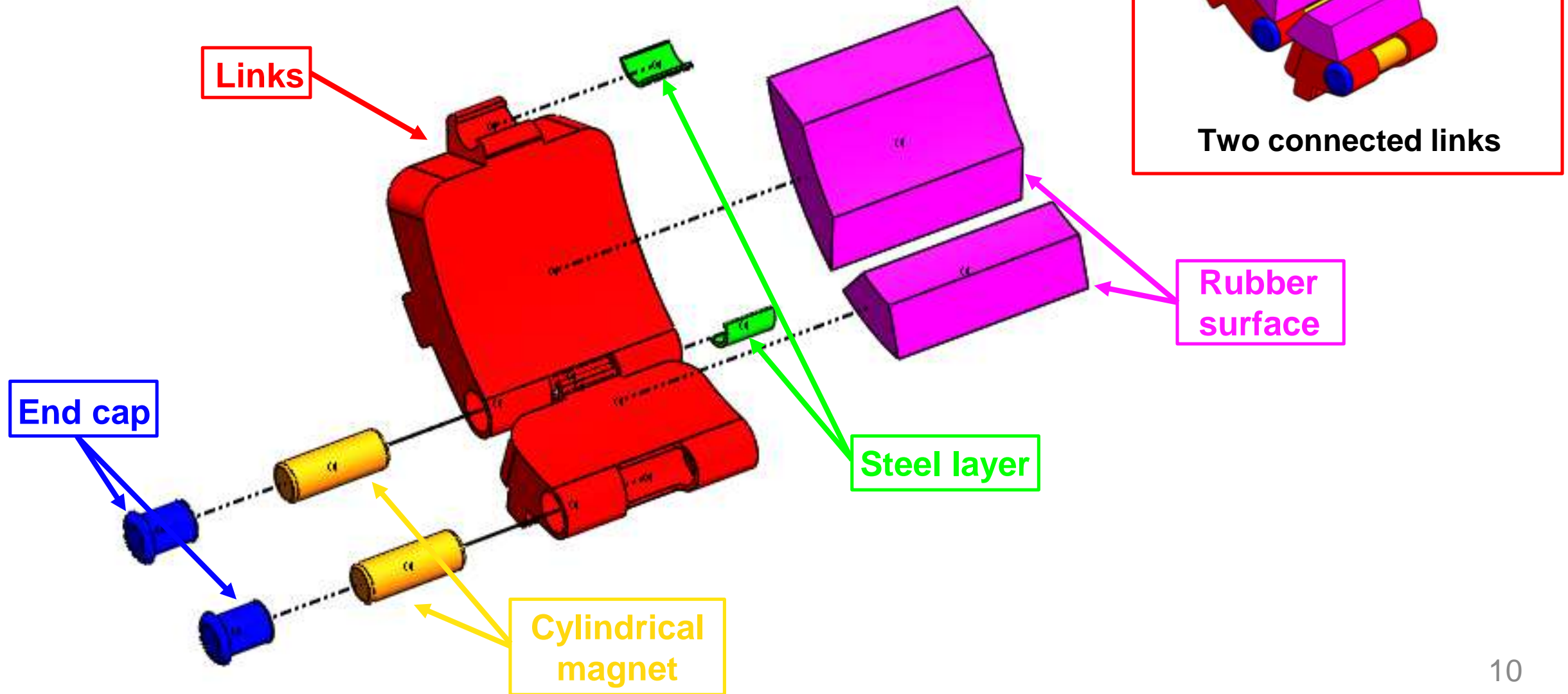


Large Link

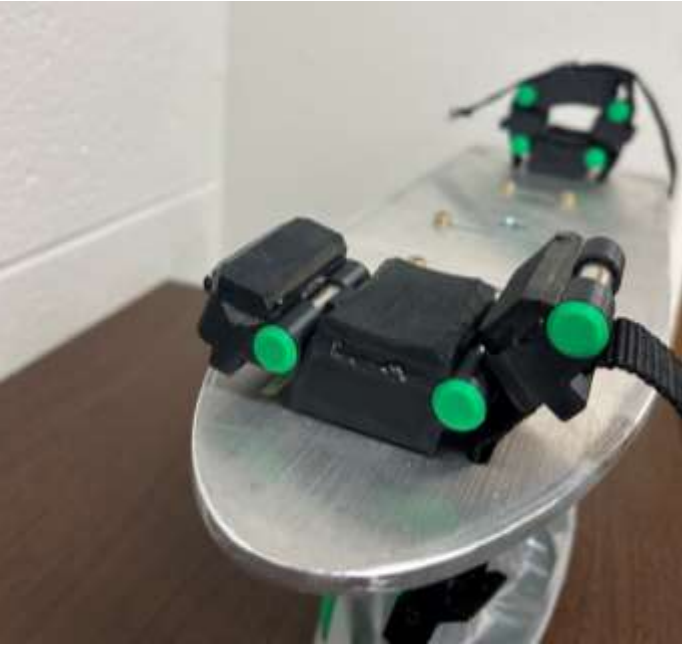


Small Link

# Key Design Points

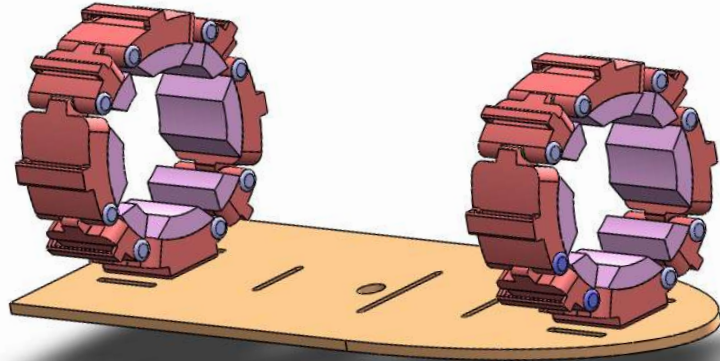


# Magnets



# Cost

- 10 initial UAAMS's to be manufactured
- 16 links per UAAMS
- Cost per UAAMS: **\$401.21**
- Majority of the cost is due to manufacturing
- Chosen materials are relatively cheap

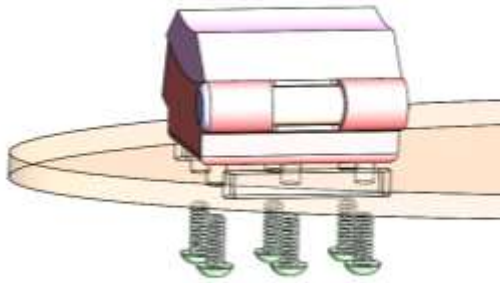


[https://m.media-amazon.com/images/I/71Hb9mv7Y4L.\\_AC\\_UL960\\_QL65\\_.jpg](https://m.media-amazon.com/images/I/71Hb9mv7Y4L._AC_UL960_QL65_.jpg)



# 6 Step Installation Process

**1** Check parts for serviceability: structural integrity and EPDM grip wear.



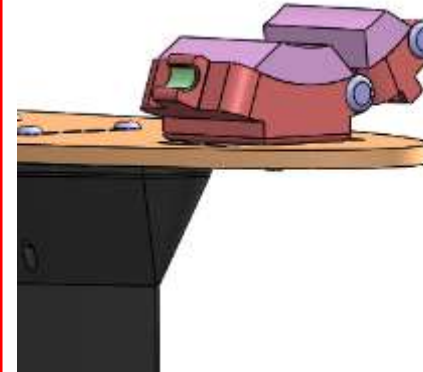
**2**

Affix mount links to  
mount plate



**3**

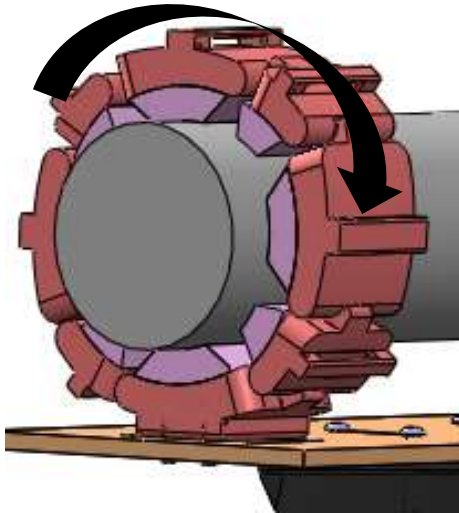
Affix antenna to  
mount plate



**4**

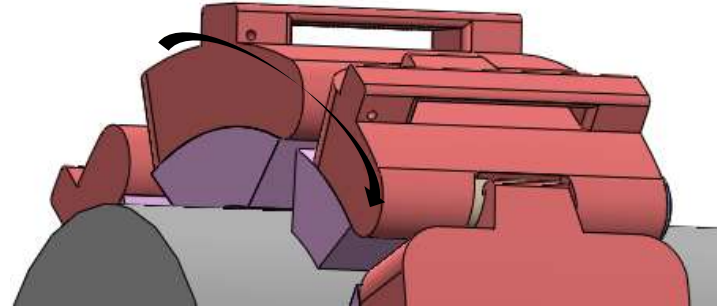
Magnetically assemble  
links to fit  
around helicopter  
attachment point

# 6 Step Installation Process (cont.)



5

Feed strap through loops of links and plate and tighten

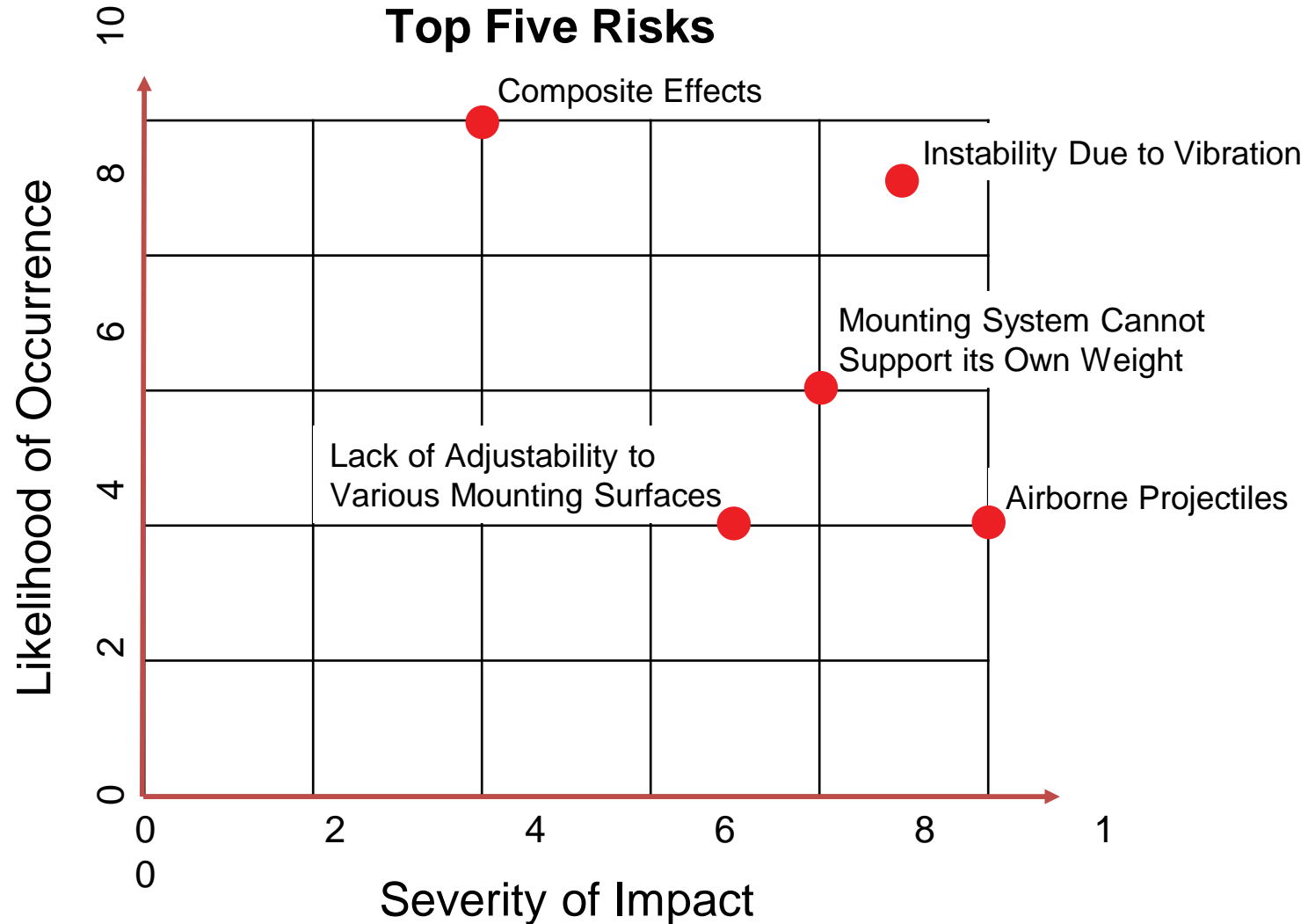


6

Feed safety wire through side channels and secure to safety attachment point on helicopter

Ready for takeoff!

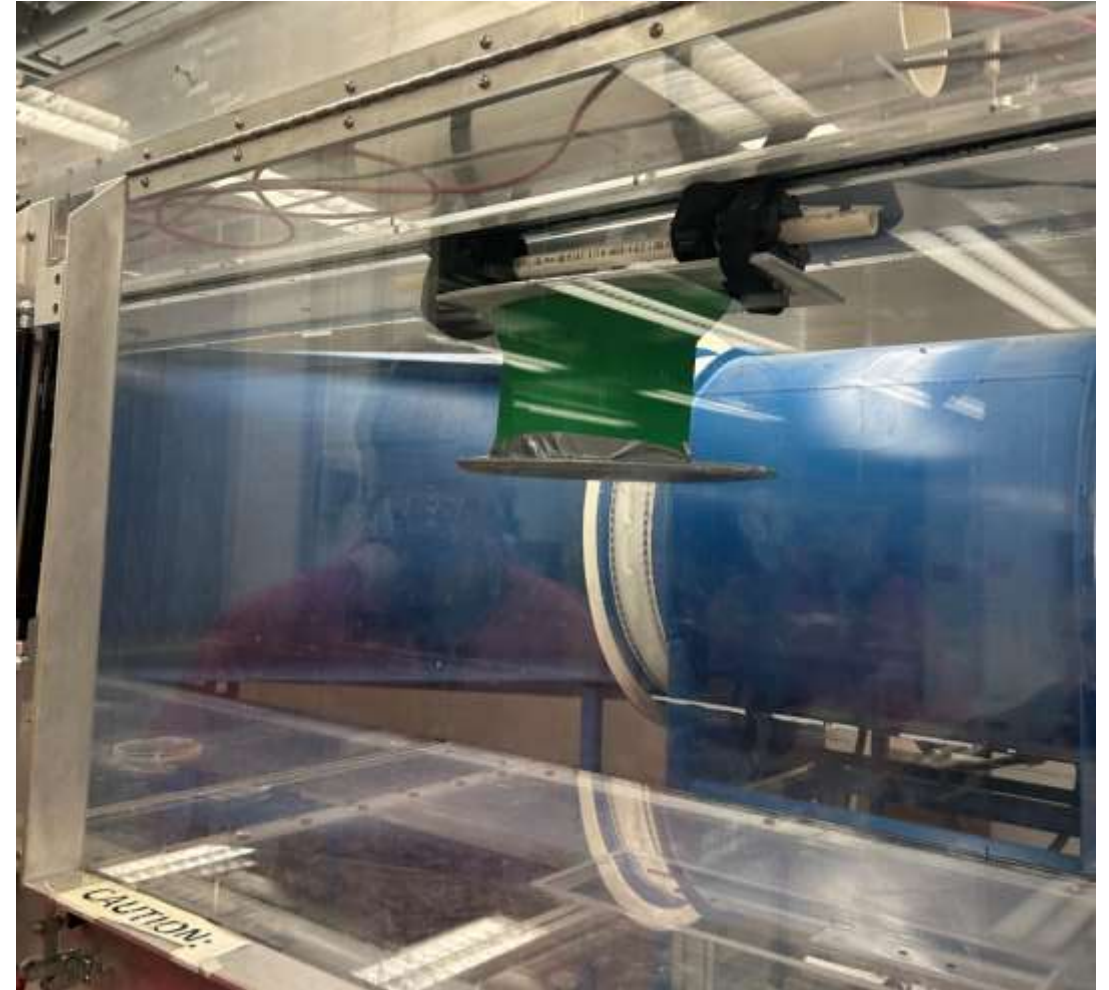
# Risk Management



# Wind Tunnel Test

- Mounted in low-speed closed-return wind tunnel
- Test points at 30, 40, 50, and 60 Hz (67 to 134 mph)
- Duration of 30 seconds each
- Based on MIL-STD-810H

**Results:** No measurable movement of the UAAMS relative to the mounting surface



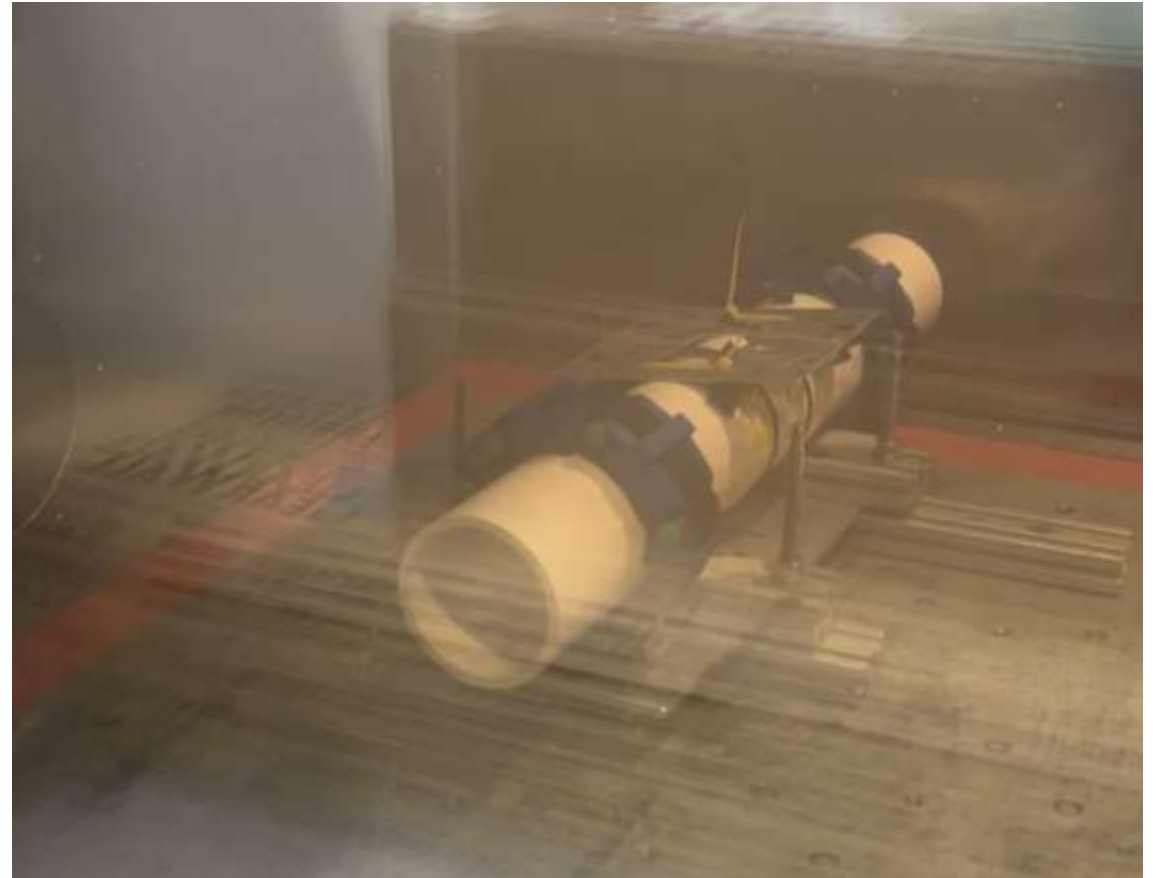
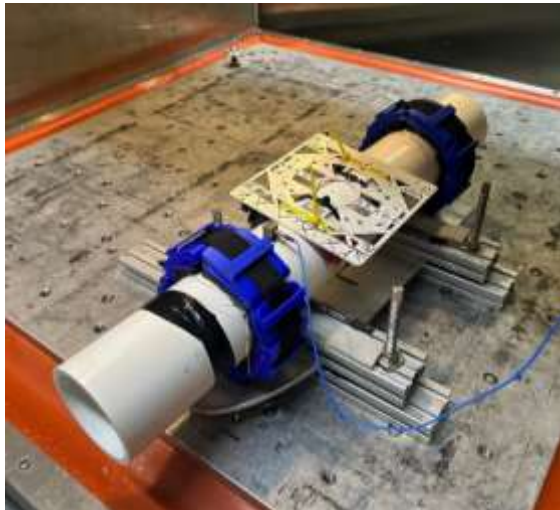
UAAMS mounted inside wind tunnel



# Vibration Table Test

- Tri-axial vibration table
- Test set points at 5g's and 7g's
- Duration of 5 minutes each
- Based on MIL-STD-202

**Results:** The UAAMS can withstand random vibrations that occur in flight



UAAMS inside vibration testing system

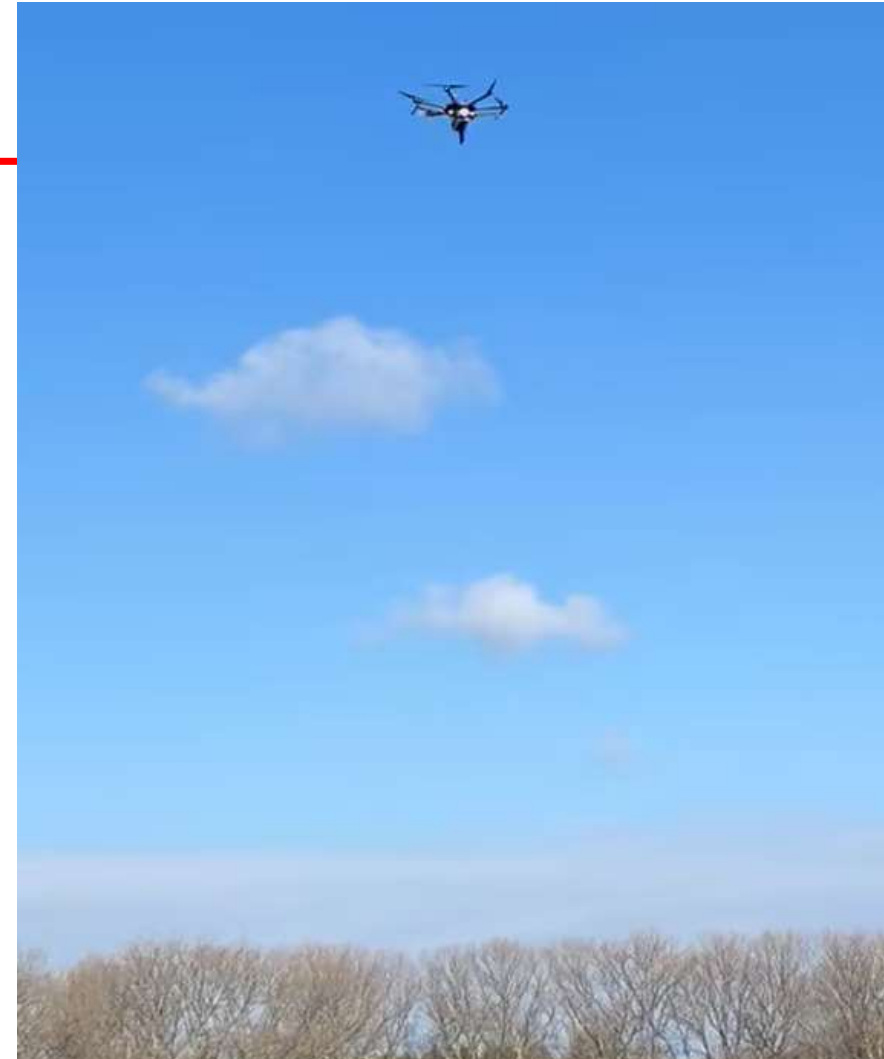
# Drone Flight Test

- The antenna was attached to a drone
- Flew up to 400 feet
- Speeds up to 35 miles per hour
- Withstood a 45-degree turn
- Provided a G force between 2.5 and 3
- Based on MIL-STD-810H

**Results:** No detectable motion of the antenna relative to the drone



UAAMS mounted on drone



Drone changing altitude and making turns

# Future Work

L3Harris  
UAAMS



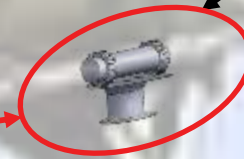


# Conclusion



**UH-60 Black Hawk**

**L3Harris  
UAAMS  
(patent pending)**



Thank you to our company mentors:  
Peter Burke, Pete Hunt, and Tim Gerlach

And to our faculty mentors:  
Professor Alex Deyhim, Dr. Michelle Blum,  
Dr. Ed Bogucz, and Dr. Mehmet Sarimurat



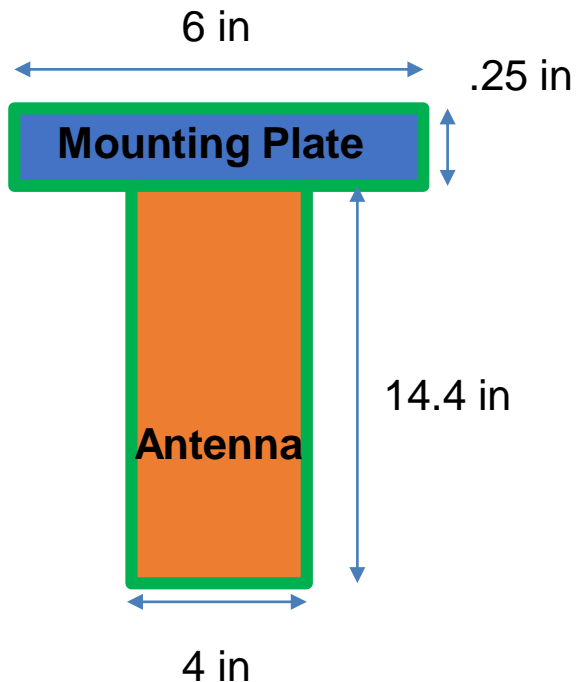
# Design Inspirations



# Simplified FBD for Mounting System

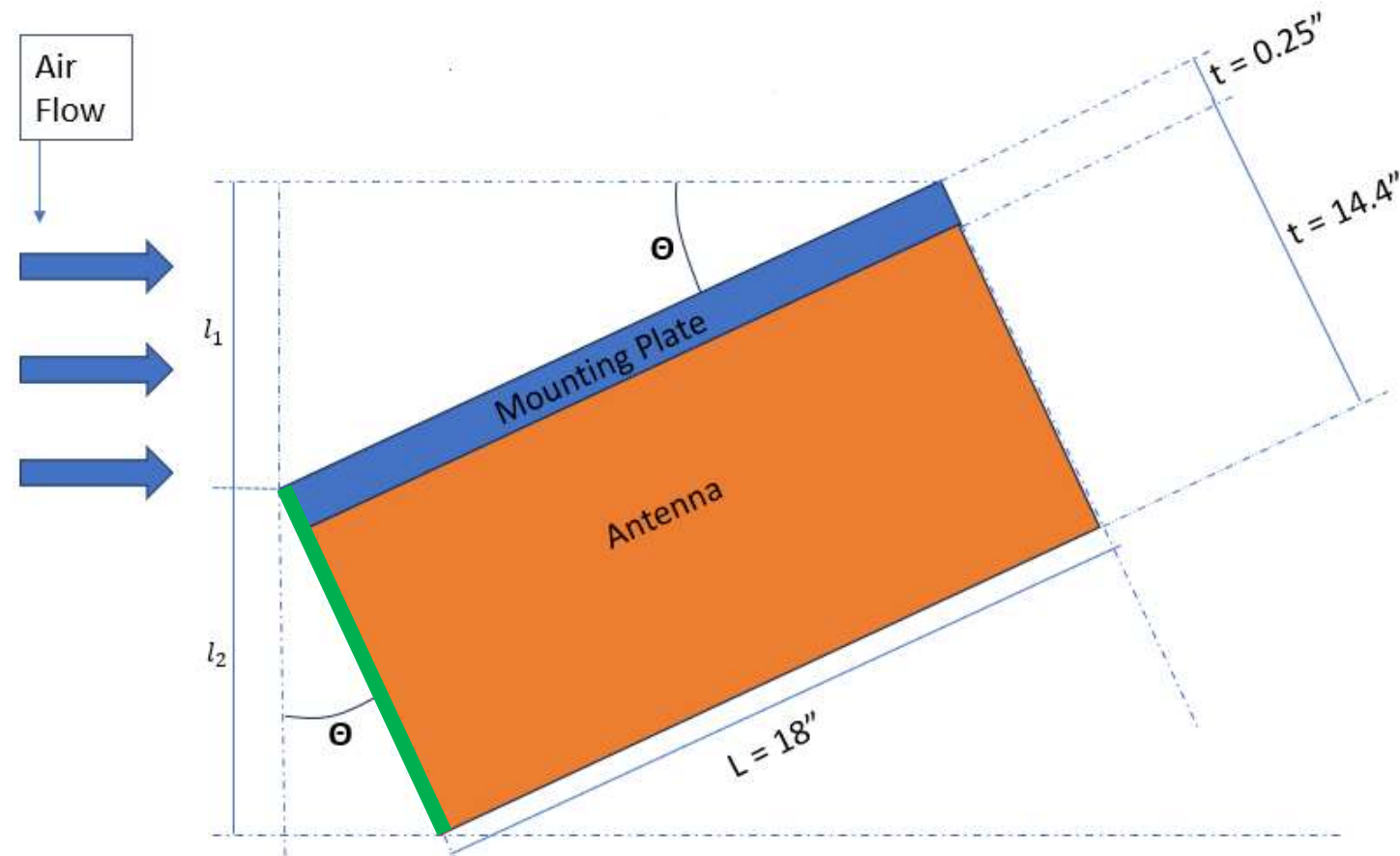
Front View

\*Not to scale



$$A_{w,\theta=0} = (4 \text{ in} \times 14.4 \text{ in}) + (6 \text{ in} \times 0.25 \text{ in}) = 59.1 \text{ in}^2$$

Side View At Variable Tilt Angle  $\Theta$



# Drag Force Calculations

Side View At Variable Tilt Angle  $\Theta$

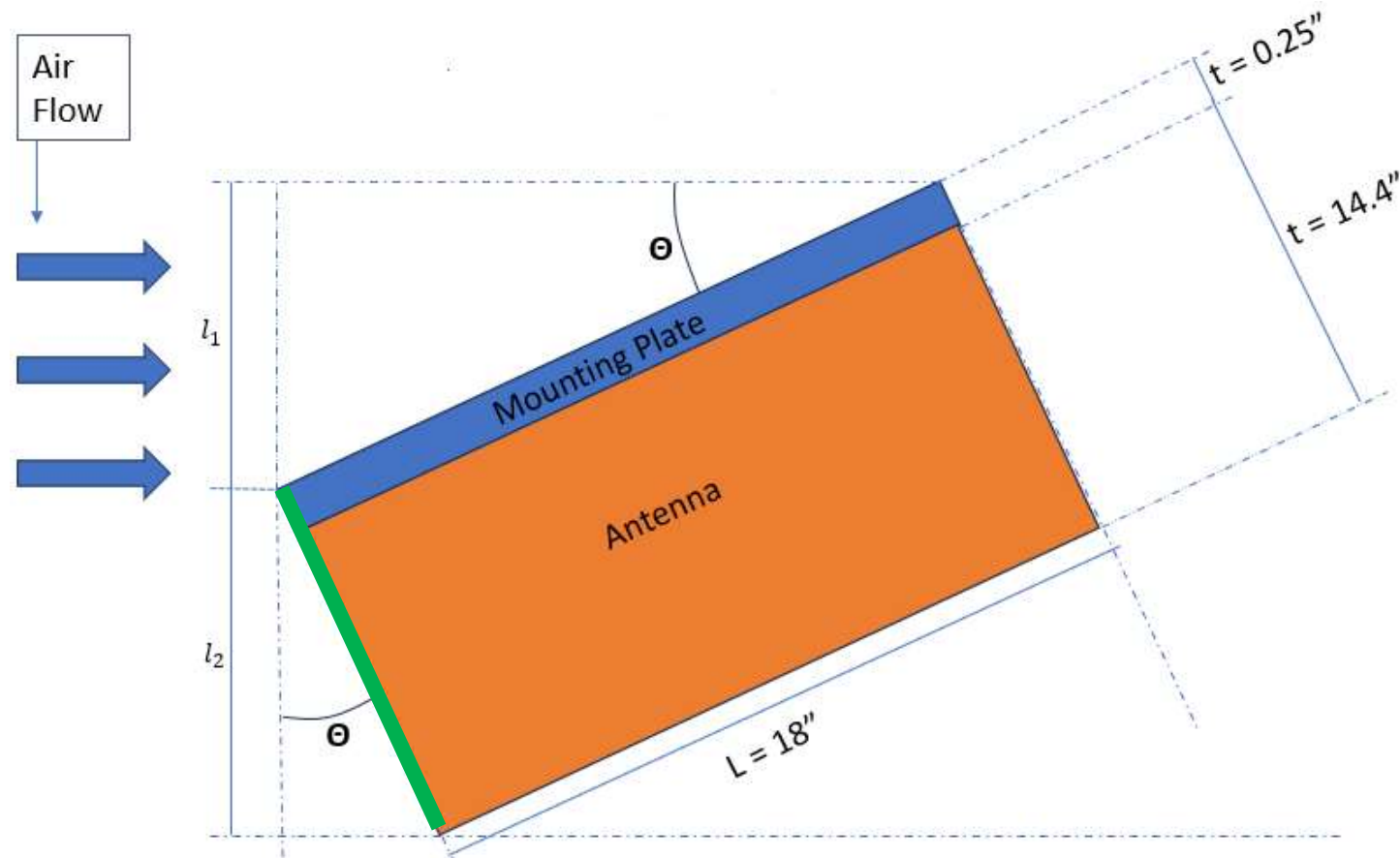
$$F_d = \frac{1}{2} C_d \rho A_w V^2$$

$$C_d = 1.1806$$

$$V = 67.1 \left[ \frac{m}{s} \right]$$

$$\rho = 1.225 \left[ \frac{kg}{m^3} \right]$$

$$A_{w,\theta=0} = 59.1 \text{ in}^2$$



# Drag Calculation: Additional Details

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## Assumptions:

1. No holes in the plate
2. Velocity is a constant top speed of 150 mph
3. Air density is constant
4. Wind is negligible
5. Plate area is a full rectangle

## Wetted Area Derivation:

$$\begin{aligned}l_1 &= L \sin \theta \\l_2 &= t \cos \theta \\L' &= l_1 + l_2 \\L' &= L \sin \theta + t \cos \theta \\A_w &= W * L' \\A_w &= W (L \sin \theta + t \cos \theta)\end{aligned}$$



# Drag Calculation: Additional Details

## Drag Coefficient Calculation

$$\frac{L}{W} = 1 \quad C_d = 1.16$$

$$\frac{L}{W} = 5 \quad C_d = 1.20$$

$$\frac{L}{W} = \frac{18''}{5.88''} = 3.06 \quad C_d = 1.1806$$

$$\begin{aligned} A_w &= 0.15(0.48\sin\theta + 0.37\cos\theta) \\ &= 0.072\sin\theta + 0.0566\cos\theta \text{ [m}^2\text{]} \end{aligned}$$

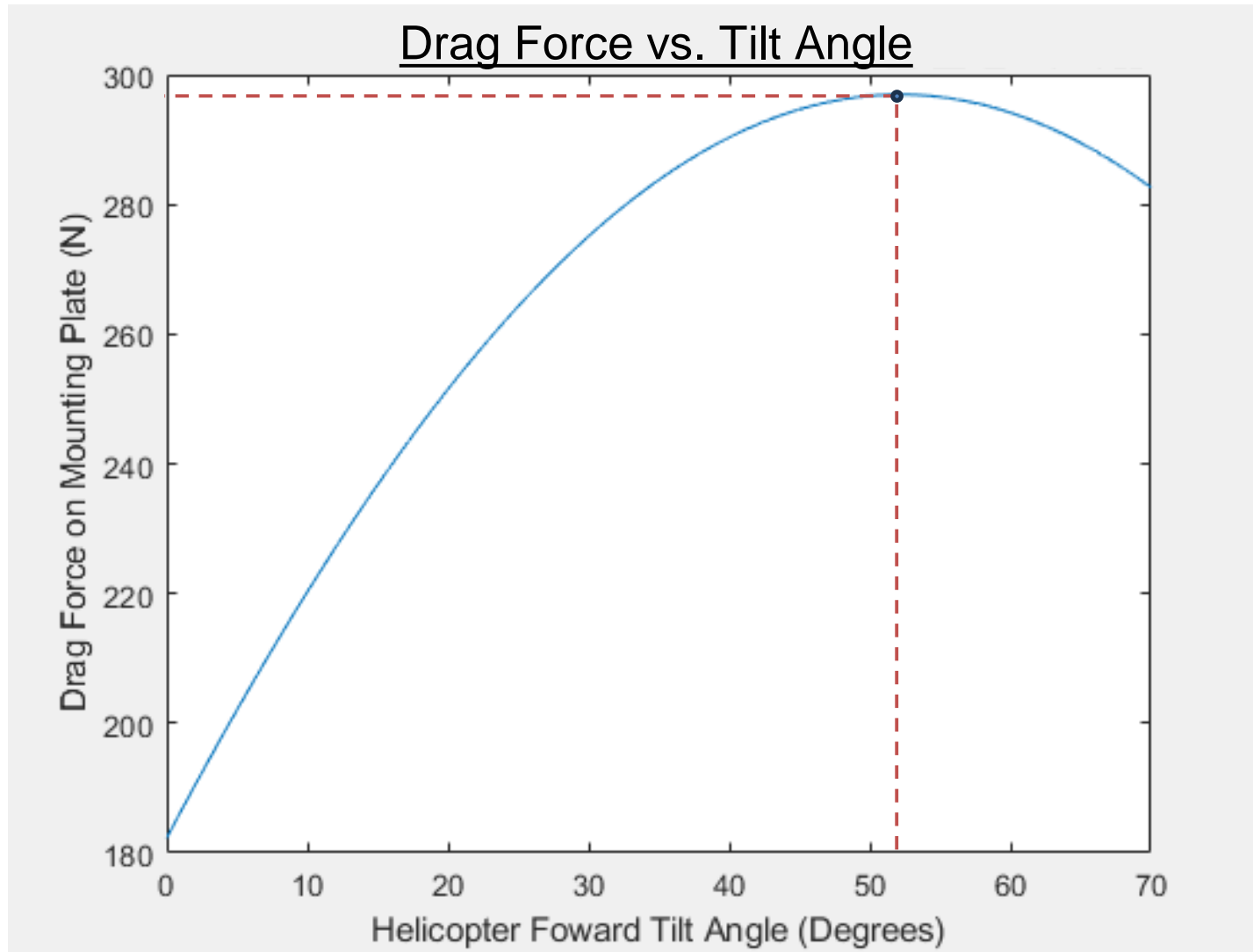
$$V = 150 \text{ [mph]} = 67.1 \left[ \frac{\text{m}}{\text{s}} \right]$$

$$\rho = 1.225 \left[ \frac{\text{kg}}{\text{m}^3} \right]$$

$$F_d = \frac{1}{2} (1.1806)(1.225)(0.072\sin\theta + 0.056\cos\theta)(67.1)^2$$

$$F_d = 234.4\sin\theta + 182.3\cos\theta \text{ [N]}$$

# Theoretical Calculations



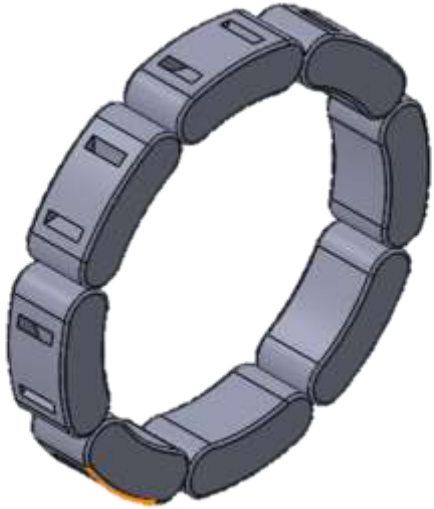
$$F_d = 234.4\sin\theta + 182.3\cos\theta \text{ [N]}$$

Max Drag Force = 296.95 [N]  
Angle at Max Drag = 52.1°

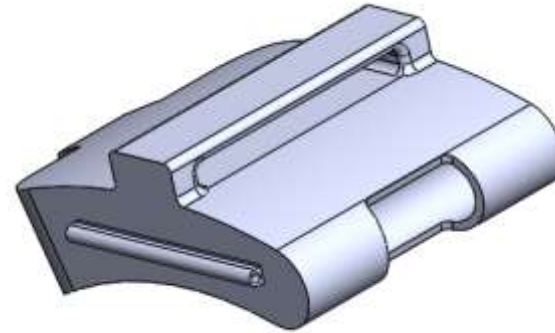
# Risk Analysis and Mitigation

Failure Mode	Severity	Control Methods				RPN	Rank
		Prevention Control	Occurrence	Detection Control	Detection		
Instability due to vibration	9	Multi-axial vibration testing	9	Monitor the mounting system throughout the flight mission	4	324	1
Airborne projectiles	10	Designing with minimal parts that can be removed; Safety wire to catch parts; Simulation testing and experimental testing in <b>wind tunnel</b>	4	Field test with L3Harris; Appearance and torque check before takeoff	6	240	2
Lack of Adjustability to Various Mounting Surfaces	7	EPDM rubber allows links to conform to more shapes; Designing two sizes of links, limiting gap size in ring; <b>Testing prototype for rotational degree of freedom</b>	4	Before helicopter takes off, ensure the links are conforming tightly to the mounting surface	4	112	3
Mounting System Cannot Support its Own Weight	8	Specialized polymer with 3D printing to allow for complex, lighter, and stronger geometries	6	<b>Field test</b> with UAV	2	96	4
Composite Effects	6	<b>Field test</b> with UAV	10	Appearance check for fatigue failure effects before installation on helicopter	1	60	5

# Design Progression

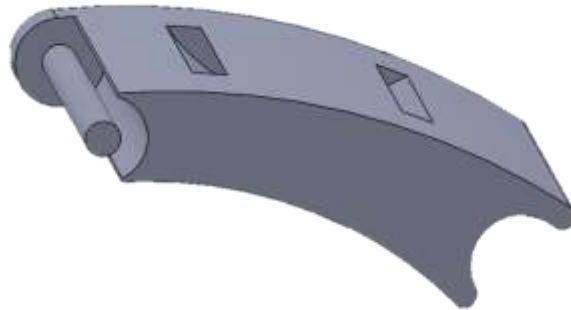


- Mating surfaces
- Addition of magnetic connection between links

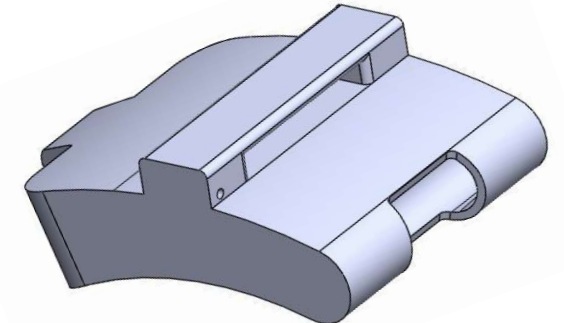


- Safety wire channel is changed to a hole on the strap extrusion

- Symmetric removable links
- Held together by strap



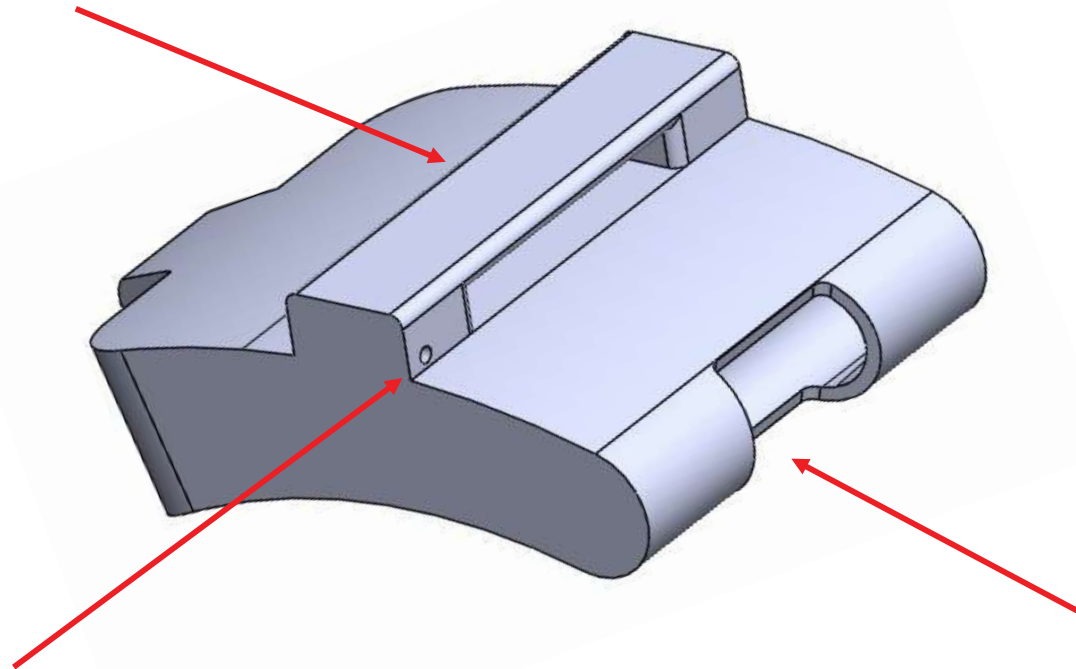
- Extrusion for strap to be fed through
- Channel for safety wire





# Additional Link Features

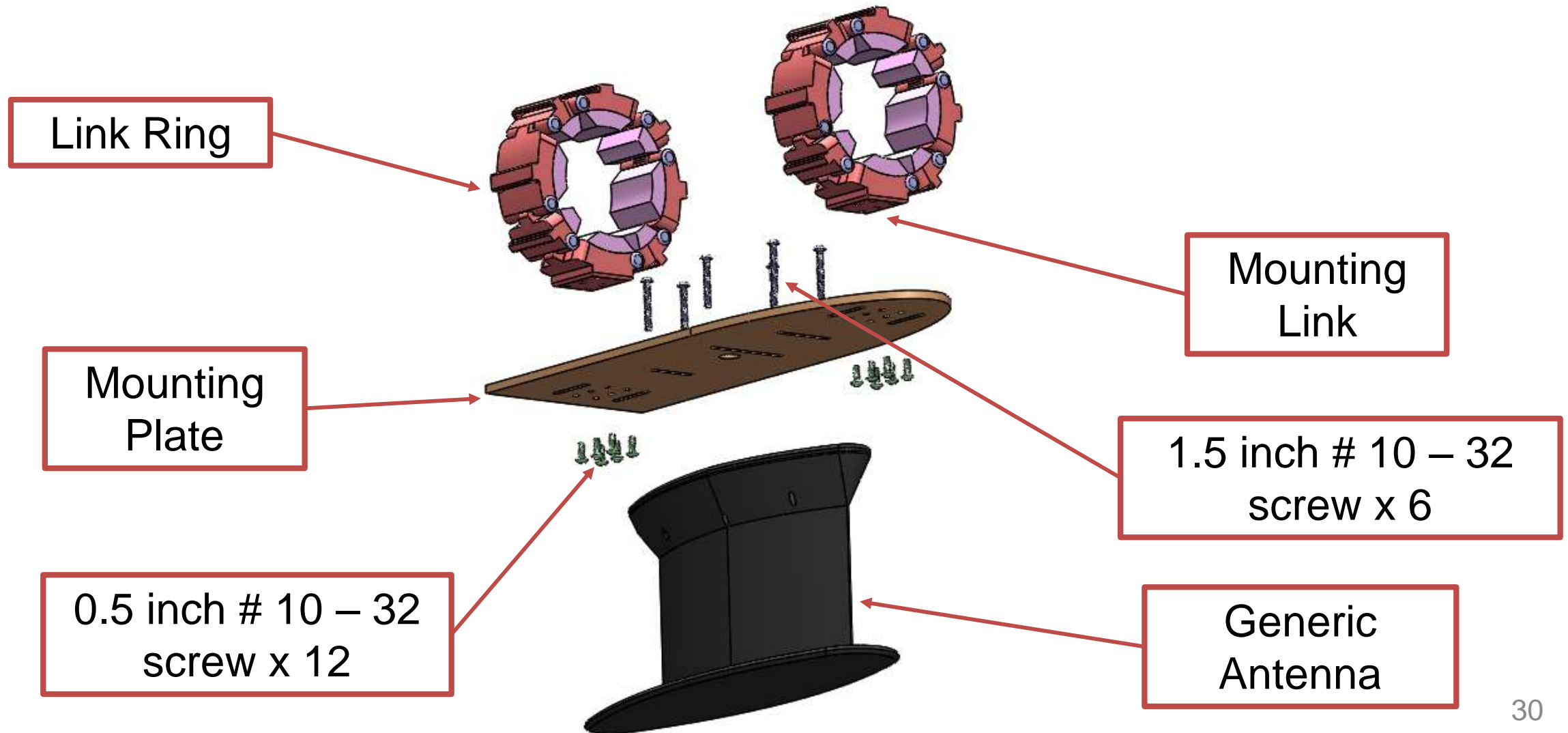
Slot for ratchet strap  
which holds the links  
together



Separate channel for  
safety wire to feed  
through each piece of  
the assembly

Window exposing  
magnet to provide a  
stronger connection

# Plate to Link Connection

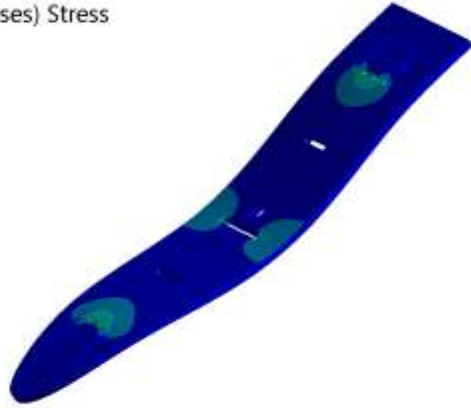
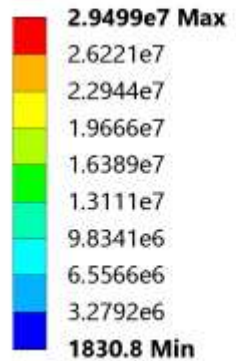


# Timeline and Milestones

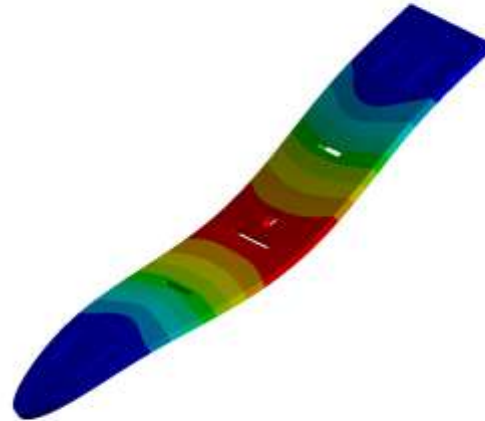
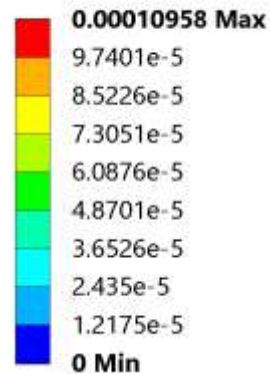
	Sept	Oct	Nov	Dec	Jan	Feb	Mar	Apr	May
<b>Design Concepts</b>									
<b>Materials Research</b>									
<b>CAD Design</b>									
<b>ANSYS Failure Analysis</b>									
<b>Risk Assessment</b>									
<b>Prototype</b>									
<b>Order Materials</b>									
<b>Experimental Testing</b>									
<b>Safety Review</b>									
<b>Field Testing</b>									
<b>Finalize Design</b>									
<b>Instruction Sheet for Kit</b>									

# Static-Structural Simulations

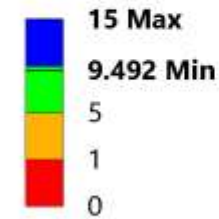
**A: Static Structural**  
Equivalent Stress  
Type: Equivalent (von-Mises) Stress  
Unit: Pa  
Time: 1  
12/11/2023 4:20 PM



**A: Static Structural**  
Total Deformation  
Type: Total Deformation  
Unit: m  
Time: 1  
12/11/2023 4:19 PM



**A: Static Structural**  
Safety Factor  
Type: Safety Factor  
Time: 1  
12/11/2023 4:20 PM



## Von-Mises Stress

- Maximum = 29.5 MPa
- Stress concentration at screw holes

## Total Deformation

- Maximum = 0.11 mm
- Occurs in the center of the plate

## Safety Factor

- Minimum = 9.5



# MIL-STD-202 Vibration Testing

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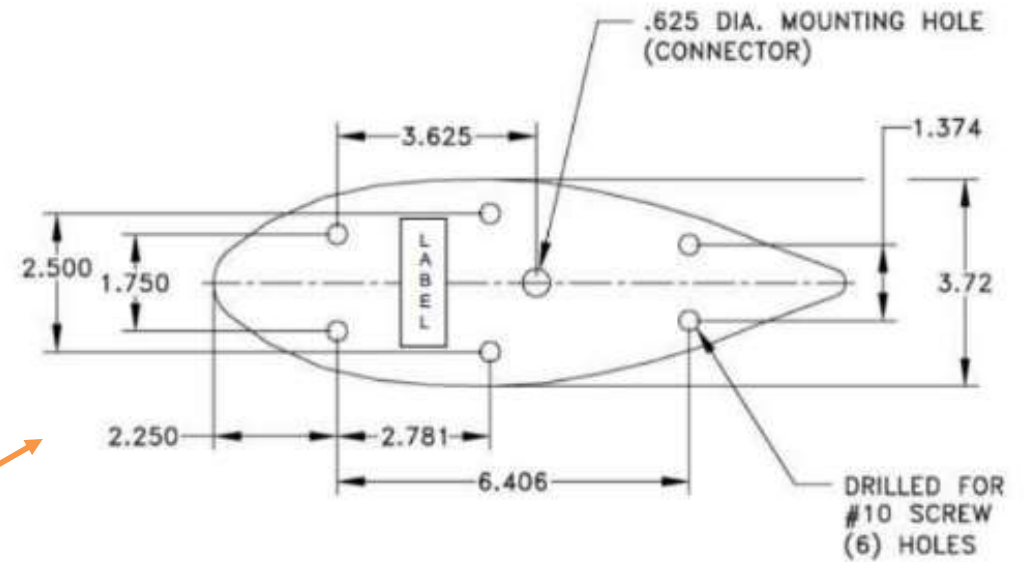
Specifies frequency sweep testing (Amplitude 0.03 inches)

- Testing of each axis of motion for two hours
- Predominant frequencies encountered during field service: 10 Hz – 55 Hz
- Previous ANSYS modal analysis will inform critical frequencies
- Results presented in table by frequency, orientation of motion, and failures observed. Maybe further expanded quantitatively by categorizing by failure size (diameter or deflection)
- Likeliest to fail between link rings and mounting plate
- Observations to be recorded during and after each test

# Antenna Attachment to Mounting Plate

Antenna will be  
screwed onto the  
plate using six #10-32  
screws

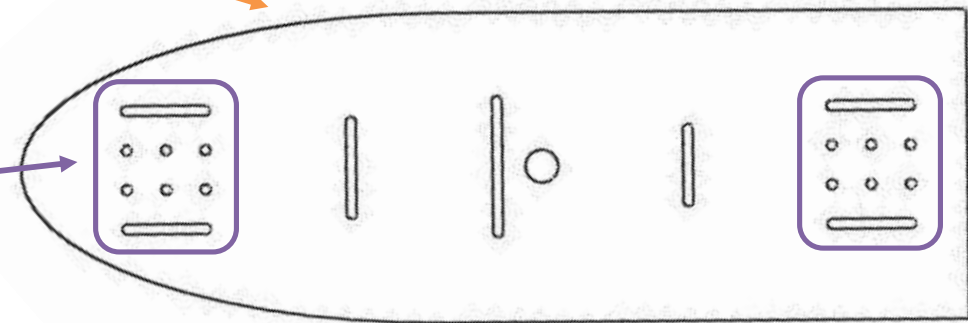
Universal  
mounting  
pattern



Source: Specifications provided by L3Harris

Our mounting  
plate

Link  
attachment  
points



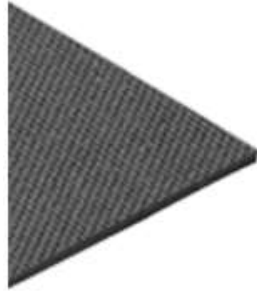
# Materials

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## **ASA filament**

Rigid and scratch resistant,  
exceptional resistance to  
weathering, including long-  
term moisture and UV  
exposure



## **High-Strength Weather-Resistant EPDM Rubber with Criss-Cross Texture**

Adds friction, damping, and  
conformity to links



## **1 mm Steel Sheet**

Magnetically attracted to  
male end of the links



## **1/4" Aluminum Sheet**

Lightweight mounting plate,  
counterpoise for monopole  
antenna

# Materials (cont.)

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## Neodymium Cylinder

Lightweight and connects links together with 15lbs pull force



## Thumb Ratchet

Holds mount assembly together and to the helicopter, with low profile



## Epoxy Glue

Attaches EPDM layer to links



## Safety Wire

Resists loosening from vibration



# References

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Drag coefficient

[Drag coefficients for different shapes and dimensions \(based on Prasuhn... | Download Scientific Diagram \(researchgate.net\)](#)

Air Density

[Air Density Table and Specific Weight Table, Equations and Calculator \(engineersedge.com\)](#)

Shock Testing

[mil-std-810h-shock.pdf \(trentonsystems.com\)](#)

Wind Tunnel Testing

[https://simpleflying.com/pitot-tubes/](#)

Air Flow Calculations

[Navier-Stokes Equation | Glenn Research Center | NASA](#)

Vibration Testing

[MIL-STD-202 Vibration Testing | Keystone Compliance](#)