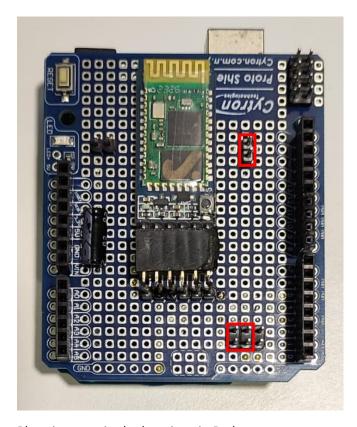
Setting HC-05 for Uploading



Place jumpers in the locations in Red

```
#include <SoftwareSerial.h>

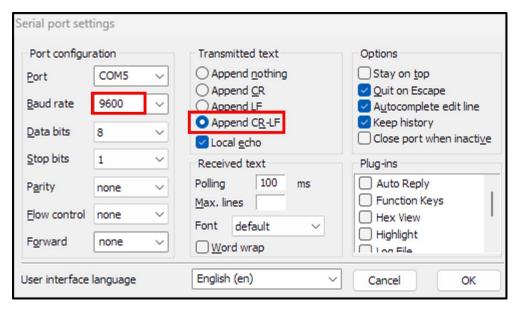
SoftwareSerial mySerial(5, 4); // RX, TX

void setup() {

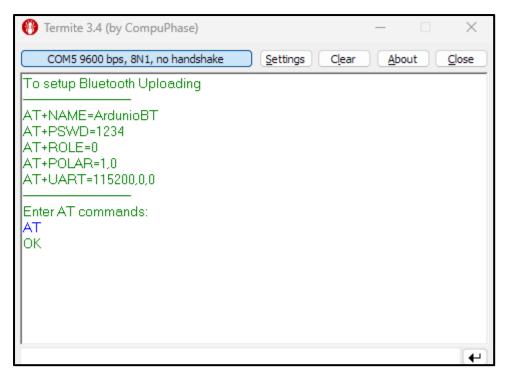
Serial.begin(9600);
Serial.println("To setup Bluetooth Uploading");
Serial.println("------");
Serial.println("AT+NAME=ArdunioBT");
Serial.println("AT+PSWD=1234");
Serial.println("AT+ROLE=0");
Serial.println("AT+POLAR=1,0");
Serial.println("AT+UART=115200,0,0");
Serial.println("-------");
Serial.println("------");
Serial.println("Enter AT commands:");
```

Upload the Arduino code via USB cable

Filename: "BTSetup"



Port Setup for connection

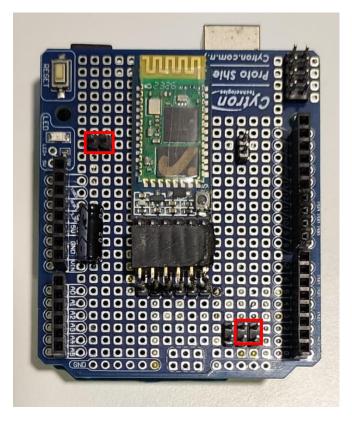


The output should be as above,

Send **AT** to test connection, if **OK** send the command as shown in the serial Monitor.

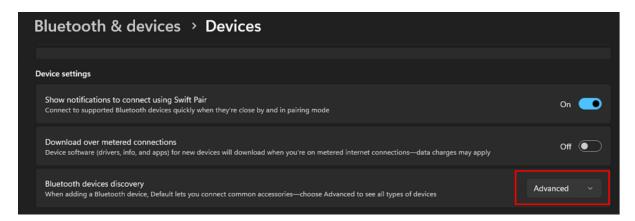
If **Error** from **AT**, check jumper and restart.

Uploading Mode

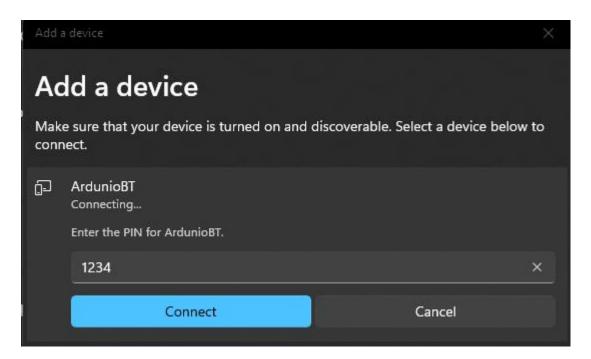


Place jumpers in the locations in Red

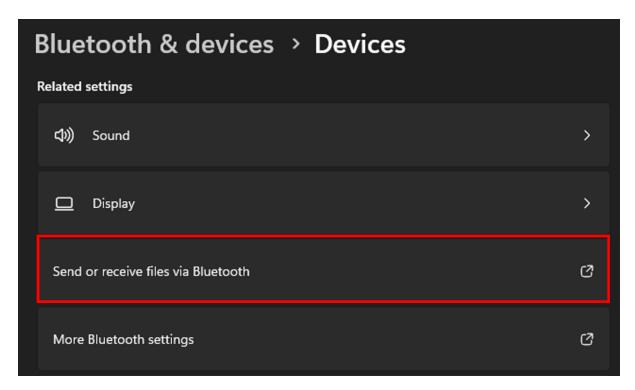
To connect on Windows 11



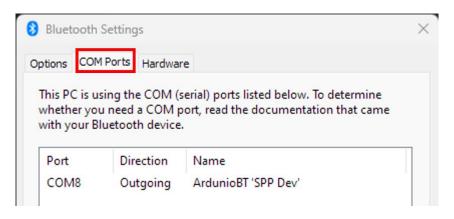
Must enable Advanced setting.



Connect to Bluetooth



Open this to check the port.



Find outgoing Port to Arduino



This is the port for the connection for uploading.

Using Serial Monitor Via BT

Use the same port as uploading(like normal)

Can only use 115200 speed for monitoring via Bluetooth

```
[env:uno]
platform = atmelavr
board = uno
framework = arduino
upload_port = COM8
monitor_port = COM8
monitor_speed = 115200
```

Platformio setting are as shown above.

Known issue with the serial on platformio:

■ Cannot see what is being typed.

So, use termite