Pit Stuff

Climber is reset Zip tie on battery

Field Setup Stuff

Make sure robot is lined up properly
Robot intake is facing driver stations
Coral in robot intake
Plug in climber
Plug in orange pi
Elevator is all the way down
Ropes on elevator are taught
Turn robot on
Verify lights on all motor controllers
Verify lights on orange pi

Driver Station Stuff

Verify correct auto is selected Verify controller is connected Verify controller is in slot 0