

NIDAR Drone Competition

Team Avadhi: Design Phase

■ Agenda and Current status

■ Team Composition

Sl NO	Name	Department
1	Sinchan K N	Avionics and propulsion
2	Vaishnav Sabari girish	Avionics and Navigation
3	Spoorti Hannikeri	Propulsion
4	Dhruv Bhandari	Structure
5	Madaka Rakshita	Navigation
6	Huzaifa Afzal	Structure and Payload
7	Moiz Arsiwala	Payload
8	Rishikesh Bitla	Avionics and Payload
9	Manasvi Ravi	Navigation
10	Vrishank S C	Control

■ Mission Objective

Locate and deliver survival kits to 10 stranded survivors in a flooded coastal town within 30 minutes.

■ Mission Requirements

- Scan area, detect survivors , geotag locations and communicate via speaker.
- Deliver 10 survival kits (each 200 g) with <1.5 m accuracy from 20 ft altitude.
- Both drones must operate from a single command station (manual mode incurs penalty).

■ Design Requirements

- Weight per drone: $\leq 25\text{kg}$
- Launch area: 6×6 ft
- De-licensed frequencies only (e.g., 2.4 GHz, 5.8 GHz, 868 MHz)
- Mandatory fail-safes: Return-to-home (RTH) for link loss, low battery, geofence breach, altitude breach

Pre-mission Setup

GPS Calibration

Verify fail-safes

RTH on Link Loss

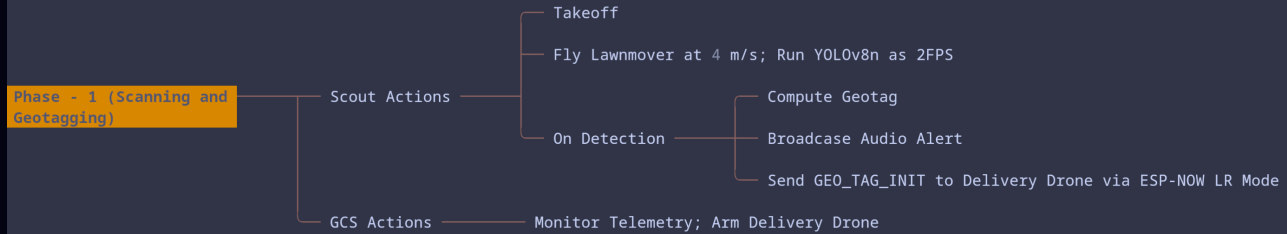
RTL at 25% battery

Geofence Polygon

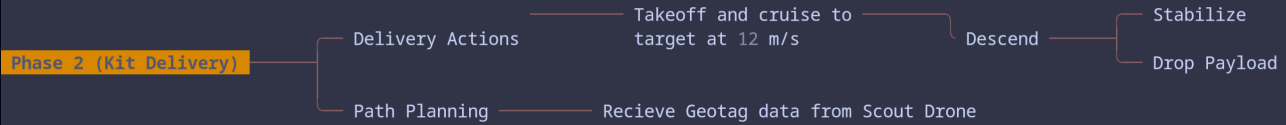
Load KML File into Scout
Drone's Onboard Computer

Generate Lawnmower Pattern

Phase 1



Phase 2



Phase 3 (Verification and RTH)

Scout visually confirms drops

Both drones execute RTL

Land within Launch Zone

■ Our Progress

1. Preliminary CAD design.
2. Initial communication tests.
3. Yolo tests
4. Preliminary weight estimation
5. Preliminary Payload dropping mechanism design
6. Sponsor Mapping

