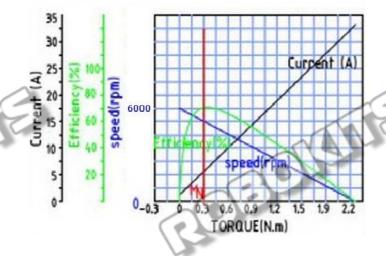
Planetary Encoder Geared motor 24V 175RPM 100W

General Specifications	
Rated Torque (Kgcm)	142
Stall Torque (Kgcm)	311
No Load Current (A)	1,12
No Load Speed (RPM)	175
Stall Current (A)	Upto 30 (Max)
Gearbox Ratio	1:36 planetary 2 stage
Encoder Type	500 Lines 2000CPR
Shaft Diameter (mm)	10
Mator Weight (gms)	1450

• Power and Input Terminal Assignments

Terminal No.	Terminal Name	Wire Colour	Description
Terminal 1	GNO	BLACK	Ground should be connected to -ve supply
Terminal 2	VCC	REO	VCC should be connected to +ve supply
Terminal 3	Enc A	GREEN	Quadrature encoded output A
Terminal 3	Enc B	YELLOW	Quadrature encoded output B

• Dimensions



Base Motor Specific	ations
Rated Voltage (V)	24
No Load Speed (RPM)	6600
Rated Speed (RPM)	6000
Rated Torque (Kgcm)	5.2
Stall Torque (Kgcm)	22
Rotor Inertia (Gcm2)	600
Starting Current (A)	29 .5

All Dimensions are in mm RMCS-2004 28-11-2016 PM 04:58:57 Rhino Motion Controls Sheet: 1/1