

Rider Telemetry System (ESP32 + GPS + MPU6050 + Flutter App)

Overview

The Rider Telemetry System monitors a rider's movement in real time using sensors on an ESP32 board. It detects speed, acceleration, lean angle, and GPS location, and transmits this data via Bluetooth to a custom Flutter mobile app. The app shows live telemetry and automatically saves all data locally every 5 seconds.

Hardware Used

Component	Function
ESP32	Main controller with Bluetooth
MPU6050	Accelerometer + Gyroscope (motion & lean detection)
NEO-6M GPS	Location and speed tracking
Android Phone	Runs Flutter telemetry app

Connections

ESP32 Pin	GPS	MPU6050
3.3V	VCC	VCC
GND	GND	GND
GPIO4	TX	—
GPIO2	RX	—
GPIO21	—	SDA
GPIO22	—	SCL

Firmware

File: rider_telemetry_v5_3_lite.ino

Platform: Arduino IDE

Key Features:

- Reads real-time GPS + MPU6050 data
- Calculates speed, acceleration, and lean angle
- Detects crash or harsh braking
- Sends clean formatted data via Bluetooth

Example Output:

[GPS] Lat:12.934567 Lon:77.600231 Spd:27.53 km/h Sats:7 Sig:Strong
[MPU] X:0.02 Y:-0.03 Z:0.98 | Lean:3.8 deg
[MODE] Moving | Speed:27.53 km/h | Signal:Strong

Mobile App

Framework: Flutter (Kotlin backend)

Project Name: ascend

Main Features:

- Auto-connects to Bluetooth device 'RiderTelemetry'
- Displays: State, Activity, Speed, Lean, Acceleration, GPS & Signal
- Saves telemetry every 5 seconds in local memory
- History view accessible from top-right corner

Setup Instructions

1. Install Flutter SDK → Extract to C:\src\flutter and run 'flutter doctor'

2. Get Project Dependencies:

 flutter clean

 flutter pub get

3. Connect Device:

- Pair ESP32 via Bluetooth (named RiderTelemetry)
- Enable Developer Mode & USB Debugging on Android

4. Run the App:

 flutter run

App Interface

Dashboard Shows:

- State (Idle/Moving)
- Activity (Standing/Walking/Scooter)
- Speed (km/h)
- Lean Angle (°)
- Acceleration (X, Y, Z)
- GPS Coordinates
- Signal Strength

History Tab:

- Stores last 500 readings locally in plain text
- Updates every 5 seconds automatically

Technologies Used

- C++ / Arduino (ESP32 firmware)
- Flutter + Dart (Mobile UI)

- SharedPreferences (Local storage)
- BluetoothSerial (Wireless data transfer)

Results

- Successfully displayed live telemetry from rider sensors.
- Reliable Bluetooth communication up to ~10 meters.
- Automatic local data logging for post-ride analysis.

Output in the Serial Monitor looks like this:



The screenshot shows the Arduino Serial Monitor window titled "Serial Monitor X". The message input field contains the placeholder "Message (Enter to send message to 'ESP32 Dev Module' on 'COM11')". The main text area displays a continuous stream of sensor data messages. Each message is a line of text starting with "Accel" followed by various parameters separated by spaces. The parameters include X, Y, Z coordinates, Lean angle, Mode (Moving or NoFix), Source (MPU or LatLon), Speed (km/h), and other status information like Sig:None and State:IDLE. The data is repeated in a loop, indicating a real-time feed.

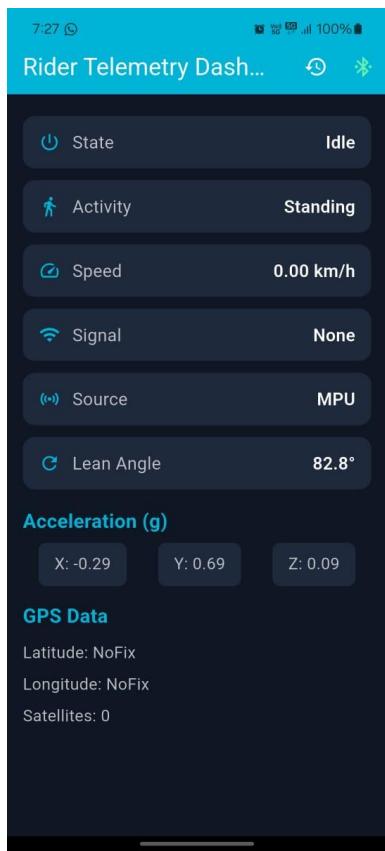
```

Serial Monitor X
Message (Enter to send message to 'ESP32 Dev Module' on 'COM11')

Accel X:-0.28 Y:0.69 Z:0.07 | Lean:84.2° | Normal
: Mode:Moving | Source:MPU | Speed:0.00 km/h | Sig:None
Accel X:-0.29 Y:0.70 Z:0.08 | Lean:83.6° | Normal
: Mode:Moving | Source:MPU | Speed:0.00 km/h | Sig:None
Accel X:-0.29 Y:0.69 Z:0.07 | Lean:83.9° | Normal
: Mode:Moving | Source:MPU | Speed:0.00 km/h | Sig:None
: Lat:NoFix | Lon:NoFix | Alt:NoAlt | Spd:0.00 km/h | Dir:NoCr | Sat:0 | Sig:None | State:IDLE
Accel X:-0.30 Y:0.70 Z:0.07 | Lean:84.0° | Normal
: Mode:Moving | Source:MPU | Speed:0.00 km/h | Sig:None
Accel X:-0.29 Y:0.69 Z:0.07 | Lean:84.3° | Normal
: Mode:Moving | Source:MPU | Speed:0.00 km/h | Sig:None
Accel X:-0.29 Y:0.68 Z:0.07 | Lean:84.2° | Normal
: Mode:Moving | Source:MPU | Speed:0.00 km/h | Sig:None
: Lat:NoFix | Lon:NoFix | Alt:NoAlt | Spd:0.00 km/h | Dir:NoCr | Sat:0 | Sig:None | State:IDLE
Accel X:-0.29 Y:0.69 Z:0.07 | Lean:84.0° | Normal
: Mode:Moving | Source:MPU | Speed:0.00 km/h | Sig:None

```

Output on the mobile app we designed looks like this:



This is how the terminal history looks like:

```
7:28 100% ← Telemetry History [2025-11-08T07:28:01.118408] State:Idle Activity:Standing Speed:0.00 Lean:83.1 X:-0.30 Y:0.69 Z:0.08 Lat:NoFix Lon:NoFix Sat:0 [2025-11-08T07:27:56.117729] State:Idle Activity:Standing Speed:0.00 Lean:83.8 X:-0.29 Y:0.69 Z:0.07 Lat:NoFix Lon:NoFix Sat:0 [2025-11-08T07:27:51.112702] State:Idle Activity:Standing Speed:0.00 Lean:85.1 X:-0.27 Y:0.69 Z:0.06 Lat:NoFix Lon:NoFix Sat:0 [2025-11-08T07:27:46.112628] State:Idle Activity:Standing Speed:0.00 Lean:84.9 X:-0.30 Y:0.69 Z:0.06 Lat:NoFix Lon:NoFix Sat:0 [2025-11-08T07:27:41.112565] State:Idle Activity:Standing Speed:0.00 Lean:83.1 X:-0.30 Y:0.69 Z:0.08 Lat:NoFix Lon:NoFix Sat:0 [2025-11-08T07:27:36.113097] State:Idle Activity:Standing Speed:0.00 Lean:85.3 X:-0.28 Y:0.69 Z:0.06 Lat:NoFix Lon:NoFix Sat:0 [2025-11-08T07:27:31.112362] State:Idle
```

How to run:

1. Hardware Setup

- Use ESP32 + NEO-6M GPS + MPU6050 sensors.
 - Wiring:
 - GPS → RX = 4, TX = 2
 - MPU6050 → SDA = 21, SCL = 22
 - Connect GND and 3.3V for both modules.
 - Upload the Arduino sketch (e.g. RiderTelemetry_v5.3-Lite.ino) to the ESP32.
 - Power the ESP32. It will broadcast Bluetooth with the name: RiderTelemetry.
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2. Pairing with Phone

- On your Android phone, go to Bluetooth settings.
 - Find and pair with **RiderTelemetry** (ESP32).
 - Make sure Bluetooth and Location are both turned ON.
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3. Flutter App Setup

- Install Flutter SDK from their official website.
 - Open the Flutter project folder (e.g. ascend/) in VS Code or Android Studio.
 - Run the following commands in the terminal:
 - flutter clean
 - flutter pub get
 - flutter run
 - Connect your Android phone via USB (enable Developer mode + USB debugging).
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4. Using the App

- The app will automatically try to connect to the ESP32 Bluetooth.

- Once connected, the dashboard will display:
 - State: Idle or Moving
 - Activity: Standing, Walking, or Scooter
 - Speed, Lean Angle, Acceleration (X/Y/Z), GPS data, and Signal strength
 - Data updates in real time.
 - Every 5 seconds, readings are automatically saved to local memory.
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5. Viewing History

- Tap the **History** button (top-right corner in the app).
 - You'll see timestamped sensor data stored as plain text logs.
 - You can clear history from the same page.
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