Sub-Group Chassis

Team overview

Purpose:

- -Build the majority of the robot. Starting from the wheels up to the superstructure that holds the manipulators.
- -Power transmission system- Chain, gears, belts, Gearboxes, sprockets.
- -Glides, slides, pivots- moving parts of the robot.

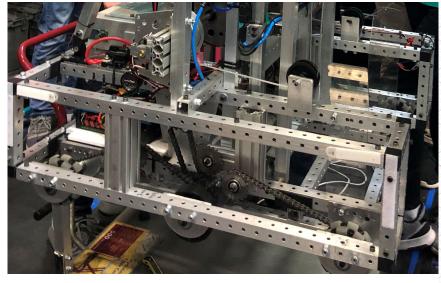
Tasks:

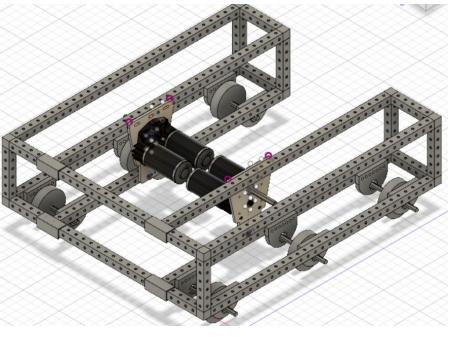
- Work with the Strategy subgroup to determine proper drive system.
 - Proper wheel choice
 - Direct drive vs non-direct
 - Chassis volume
 - Chassis tiers
 - Placement of major components
 - Electrical board
 - Pneumatics
 - Gearboxes

Knowledge:

- Measurement
- SAFETY
- Tool use
- Cutting/drilling accurately
- Reading plans / sketches
- Making plans / sketches

Examples:





Seasonal Timeline

