

# Servo Test Cases

## Absolute Mode:

Using: 1280 pixels, fov = 180, initial calibration = 90, 90

X	Y	PAN	TILT
0	0	90	90
-640	-640	0	180
-320	-320	45	135
0	0	90	90
320	320	135	45
640	640	180	0
320	0	135	90
0	-320	90	135
0	320	90	45
-320	0	45	90
0	-320	90	135

## Relative Mode:

Using: 1280 pixels, fov = 180, initial calibration = 90, 90

X	Y	PAN	TILT
0	0	90	90
-320	-320	45	135

-320	-320	0	180
-320	-320	0	180
320	0	45	180
320	0	90	180
320	0	135	180
320	0	180	180
320	0	180	180
0	320	180	135
0	320	180	90
0	320	180	45
0	320	180	0
0	320	180	0
-320	-320	135	45
-320	-320	90	90
0	0	90	90