

Power-and-Connection

MCU

Sensors-and-telemetry

Parachute-Deployment

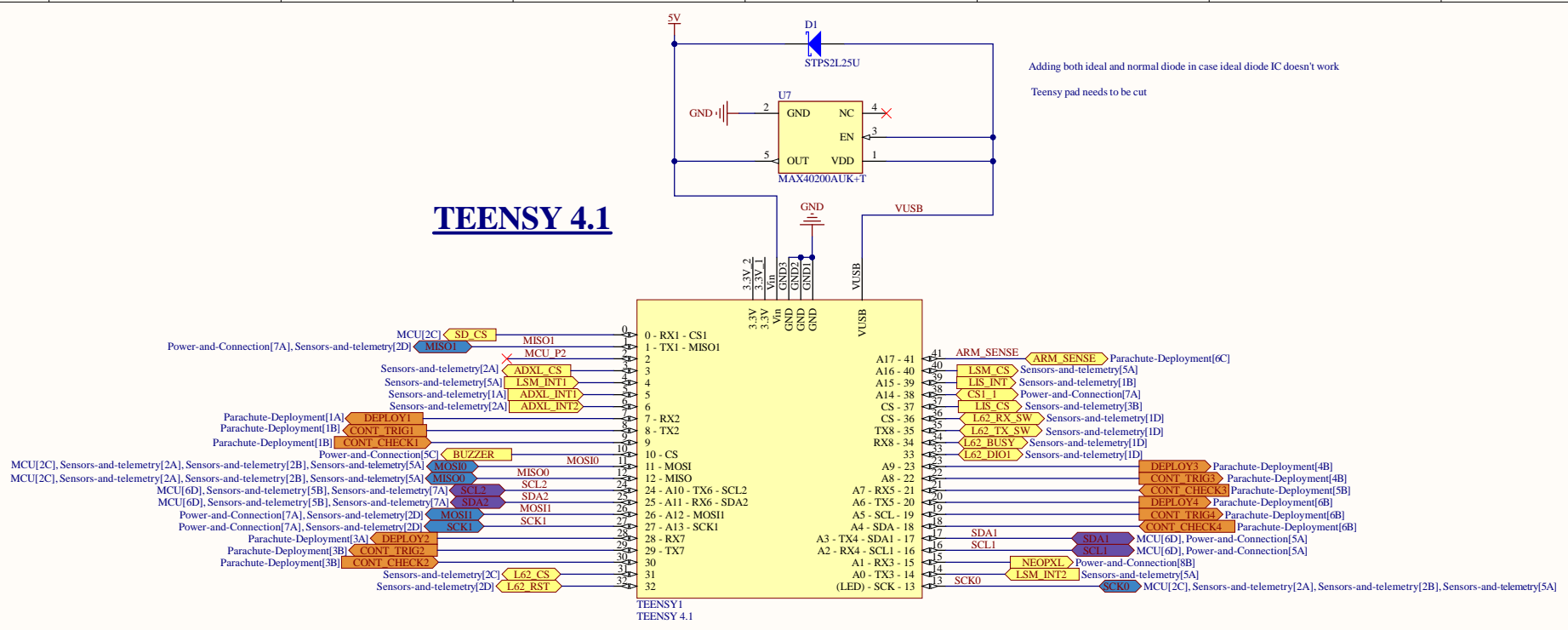
A

B

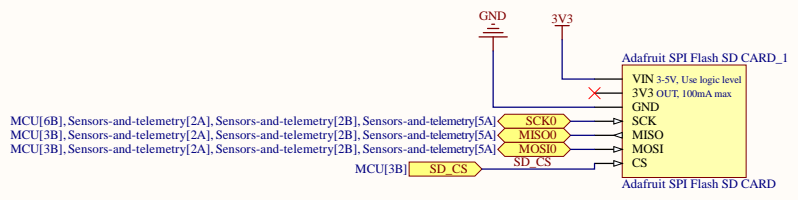
A

B

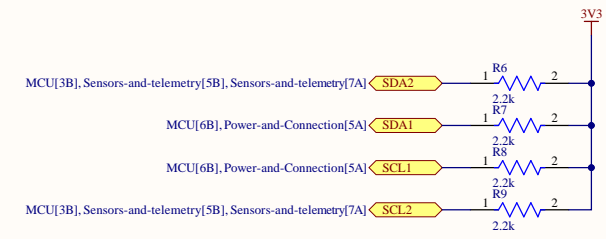
TEENSY 4.1



SPI SD CARD



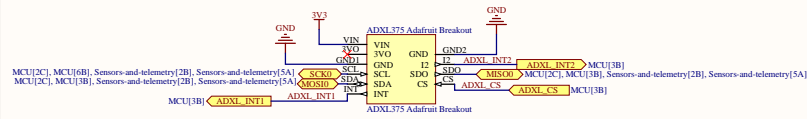
I2C PULL UP RESISTORS



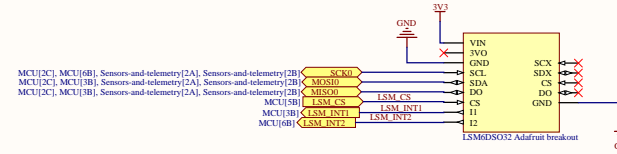
D

D

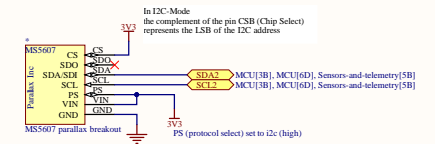
ADXL375 Accelerometer



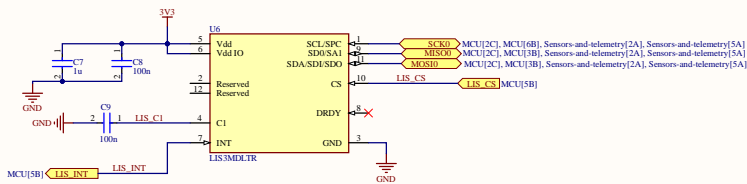
LSM6DS032 6DOF



MS5607 Altimeter

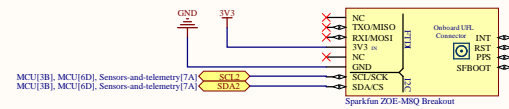


LIS3MDL Magnetometer

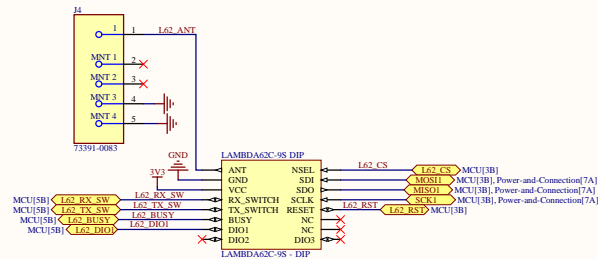


Magnetometer must be kept away from high currents ($>10\text{mA}$)

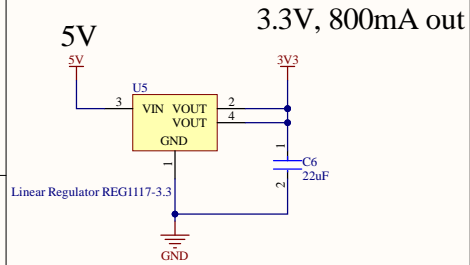
ZOE M8Q GPS



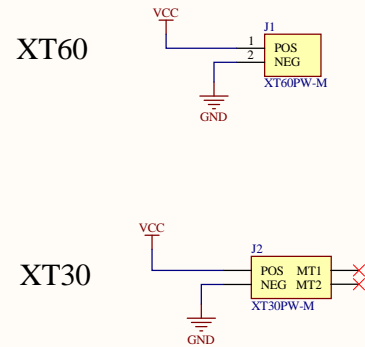
LAMBDA62C-9S Transceiver



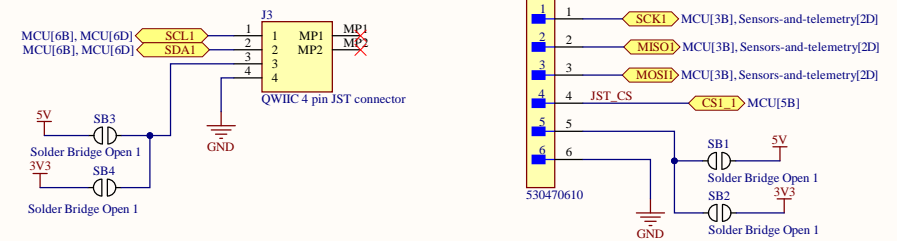
3.3V Regulator



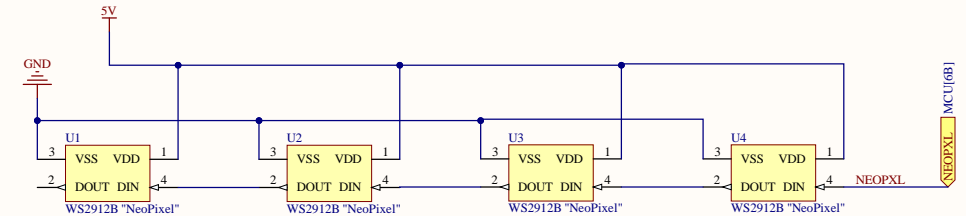
Battery connections



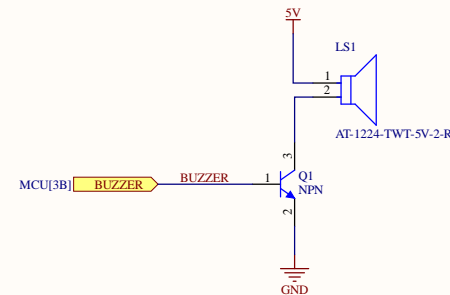
I2C and SPI connectors



NEOPIXEL Array



Buzzer



Power Requirements:

5V:

Teensy 4.1: Assume 200mA MAX
 NEOPIXELS: 4x60ma = 240mA
 Buzzer: Assume 100mA
 3.3v regulator (@ 66% efficiency) : 477mA

3.3V

SPI SD card: 30mA max. (operating read)
 ZOE-M8Q GPS: 67mA max. (~25 mA normal)
 Lambda62-9S: 118mA (max. @ 22dBm)
 LIS3MDL: 0.27mA (max @ odr 20Hz)
 ADXL375: 0.145mA (max. @ odr > 100Hz)
 LSM6DSO32: 0.55mA (max.)
 QWIIC: assume some generic module ~100mA

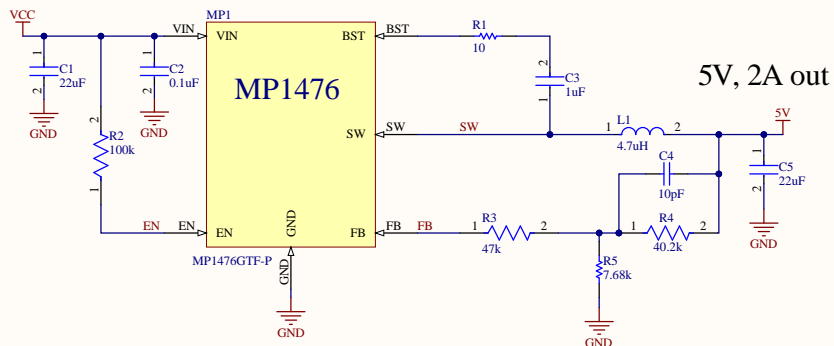
3.3V max overall current
 30 + 67 + 118 + 0.27 + 0.145 + 0.55 + 100 = 318mA

TOTAL max overall current:

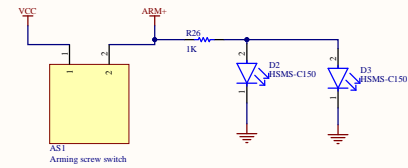
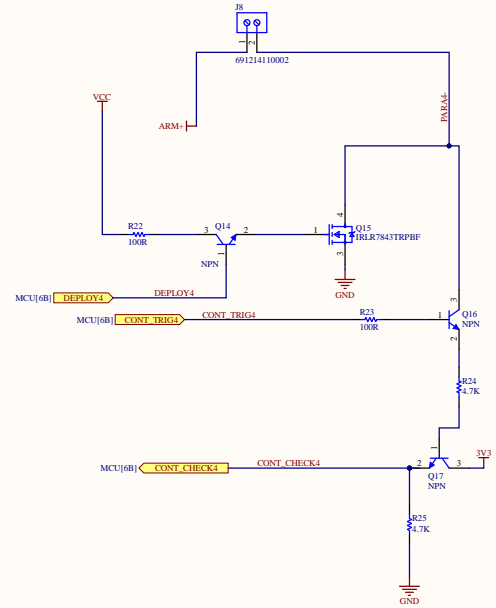
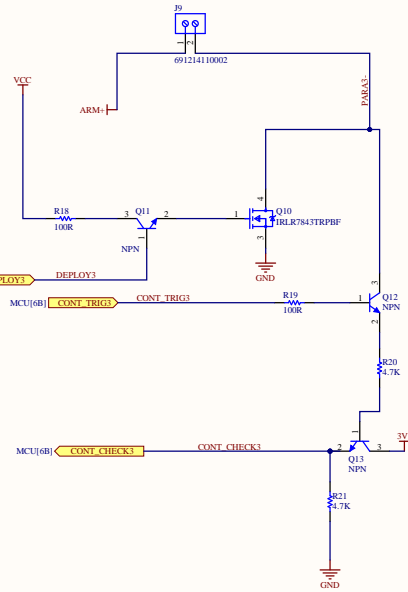
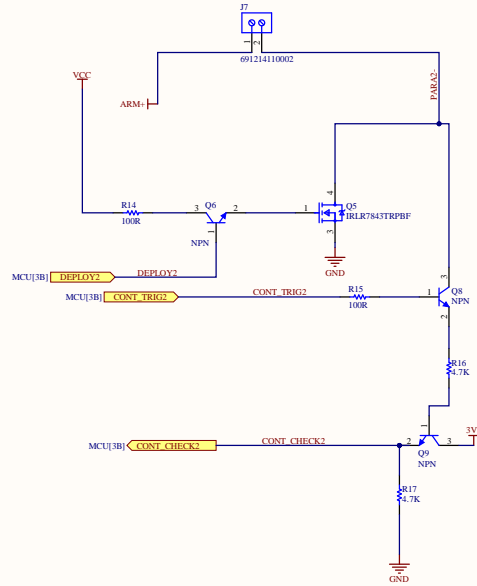
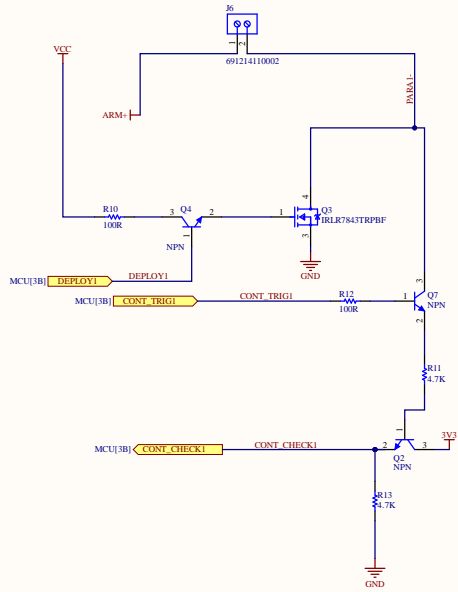
200 + 240 + 100 + 477 = 1017mA

5V Buck Converter

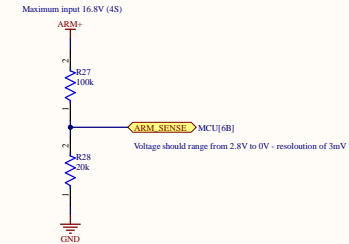
Max 4S - 16.8V IN



Parachute deployment system



Switch for arming pyro channels



Voltage divider to sense arming

Battery

35.56x185.42mm

7300x1400mil - These are FINAL

PARA channels are 80 mil

Parachute Deployment

Power

Sensors and Processor

