

RelayServer

v0.1

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Contents

1	Class Index	1
1.1	Class Hierarchy	1
2	Class Index	3
2.1	Class List	3
3	File Index	5
3.1	File List	5
4	Class Documentation	7
4.1	serverSocket Class Reference	7
4.2	Socket Class Reference	7
4.2.1	Constructor & Destructor Documentation	8
4.2.1.1	Socket	8
4.2.2	Member Function Documentation	8
4.2.2.1	accept	8
4.2.2.2	bind	8
4.2.2.3	connect	9
4.2.2.4	create	9
4.2.2.5	disc	9
4.2.2.6	getSocketfd	9
4.2.2.7	initInter	9
4.2.2.8	IsReadable	9
4.2.2.9	IsWritable	9
4.2.2.10	listen	9
4.2.2.11	recv	10

4.2.2.12	send	10
4.2.2.13	setSocketd	10
4.2.3	Member Data Documentation	10
4.2.3.1	read_flag	10
4.2.3.2	socketd	10
4.2.3.3	write_flag	10
4.3	TCPServer Class Reference	10
4.3.1	Detailed Description	11
4.3.2	Constructor & Destructor Documentation	11
4.3.2.1	TCPServer	11
4.3.2.2	TCPServer	11
4.3.3	Member Function Documentation	11
4.3.3.1	accept	11
4.3.3.2	connect	11
4.3.3.3	disc	12
4.3.3.4	operator<<	12
4.3.3.5	operator>>	12
4.4	UDPServer Class Reference	12
4.4.1	Constructor & Destructor Documentation	13
4.4.1.1	UDPServer	13
4.4.1.2	UDPServer	13
4.4.2	Member Function Documentation	13
4.4.2.1	connect	13
4.4.2.2	disc	13
4.4.2.3	operator<<	13
4.4.2.4	operator>>	13
5	File Documentation	15
5.1	Relay Server.cpp File Reference	15
5.1.1	Define Documentation	15
5.1.1.1	BOARD_IP	15
5.1.1.2	BOARD_PORT	16
5.1.2	Function Documentation	16
5.1.2.1	main	16

5.1.2.2	tcpTh	16
5.1.2.3	udpTh	16
5.2	RelayTest.cpp File Reference	16
5.3	ServerSocket.h File Reference	16
5.4	Socket.cpp File Reference	16
5.5	Socket.h File Reference	16
5.5.1	Define Documentation	17
5.5.1.1	MAX_BUF	17
5.6	SocketTCP.cpp File Reference	17
5.7	SocketTCP.h File Reference	17
5.8	SocketUDP.cpp File Reference	17
5.9	SocketUDP.h File Reference	17

Chapter 1

Class Index

1.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

serverSocket	7
Socket	7
TCPServer	10
UDPServer	12

Chapter 2

Class Index

2.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

serverSocket	7
Socket	7
TCPServer	
TCPServer (p. 10) Class	10
UDPServer	12

Chapter 3

File Index

3.1 File List

Here is a list of all files with brief descriptions:

Relay Server.cpp	15
RelayTest.cpp	16
ServerSocket.h	16
Socket.cpp	16
Socket.h	16
SocketTCP.cpp	17
SocketTCP.h	17
SocketUDP.cpp	17
SocketUDP.h	17

Chapter 4

Class Documentation

4.1 serverSocket Class Reference

```
#include <ServerSocket.h>
```

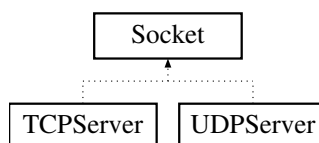
The documentation for this class was generated from the following file:

- **ServerSocket.h**

4.2 Socket Class Reference

```
#include <Socket.h>
```

Inheritance diagram for Socket:



Public Member Functions

- **Socket** ()
- bool **create** (int type)
Create socket.
- bool **bind** (unsigned short port)
Bind socket to a port and ipaddress "localhost".
- bool **listen** (int queueLen)
Bring server up and listen to the specified port for a maximum of connections.

- bool **accept** (**Socket** &)
Accept new connection, this generates a new socket description.
- bool **disc** (**Socket** &)
Shutdown socket, and drop all the data received or send.
- bool **connect** (**Socket** &, char *, unsigned short port, short int type)
*Create connection to a **TCPServer** (p. 10).*
- bool **send** (std::string)
Data Transmission.
- int **recv** (std::string &)
- void **setSocketd** (int dsocket)
- int **getSocketd** ()
- bool **initInter** ()
Communication interrupts - Setting up the interrupts.
- bool **IsReadable** ()
Communication interrupts - Read.
- bool **IsWritable** ()
Communication interrupts - Write.

Private Attributes

- int **socketd**
- fd_set **read_flag**
- fd_set **write_flag**

4.2.1 Constructor & Destructor Documentation

4.2.1.1 Socket::Socket ()

4.2.2 Member Function Documentation

4.2.2.1 bool Socket::accept (**Socket** & *new_socket*)

Accept new connection, this generates a new socket description.

4.2.2.2 bool Socket::bind (unsigned short *port*)

Bind socket to a port and ipaddress "localhost".

Parameters

<i>port</i>	bind socket to this port
-------------	--------------------------

4.2.2.3 `bool Socket::connect (Socket & dsocket, char * ip, unsigned short port, short int type)`

Create connection to a **TCPServer** (p. 10).

Parameters

<i>char</i>	* IP address of the server to connect to
<i>port</i>	Port number of the server to connect to

4.2.2.4 `bool Socket::create (int type)`

Create socket.

Parameters

<i>type</i>	0 for TCP server 1 for UDP server
-------------	-----------------------------------

Note: UDP server not implemented yet.

4.2.2.5 `bool Socket::disc (Socket & new_socket)`

Shutdown socket, and drop all the data received or send.

4.2.2.6 `int Socket::getSocketd () [inline]`

4.2.2.7 `bool Socket::initInter ()`

Communication interrupts - Setting up the interrupts.

Note: Further implementation

4.2.2.8 `bool Socket::IsReadable ()`

Communication interrupts - Read.

Note: Further implementation, interrupts in read communication.

4.2.2.9 `bool Socket::IsWritable ()`

Communication interrupts - Write.

Note: Further implementation, interrupts in the write communication.

4.2.2.10 `bool Socket::listen (int queueLen)`

Bring server up and listen to the specified port for a maximum of connections.

Parameters

<code>queueLen</code>	define the maximum number of connections allowed
-----------------------	--

4.2.2.11 `int Socket::recv (std::string & s)`

4.2.2.12 `bool Socket::send (std::string s)`

Data Transmission.

4.2.2.13 `void Socket::setSocketd (int dsocket)` `[inline]`

4.2.3 Member Data Documentation

4.2.3.1 `fd.set Socket::read_flag` `[private]`

4.2.3.2 `int Socket::socketd` `[private]`

4.2.3.3 `fd.set Socket::write_flag` `[private]`

The documentation for this class was generated from the following files:

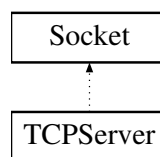
- **Socket.h**
- **Socket.cpp**

4.3 TCPServer Class Reference

TCPServer (p. 10) Class.

```
#include <SocketTCP.h>
```

Inheritance diagram for TCPServer:



Public Member Functions

- **TCPServer** (unsigned short port, int queue)
Simple socket object constructor.
- **TCPServer** ()
- **TCPServer & operator>>** (std::string)

Operator >> is overwrite to write.

- **TCPServer** & **operator**<< (std::string &)

Operator << is overwrite to read.

- void **accept** (TCPServer &)
- void **disc** (TCPServer &)

Shutdown socket.

- void **connect** (TCPServer &, char *, unsigned short port)

*Create connection to a **TCPServer** (p. 10).*

4.3.1 Detailed Description

TCPServer (p. 10) Class.

This class initialize and makes the communication between sockets.

4.3.2 Constructor & Destructor Documentation

4.3.2.1 TCPServer::TCPServer (unsigned short *port*, int *queue*)

Simple socket object contructor.

brief **TCPServer** (p. 10) socket constructor

Parameters

<i>port</i>	port which server will be listen.
<i>queue</i>	define queue of allwoing connections to the server.

Description: Initialization of the server. 1 - Create **Socket** (p. 7) 2 - Bind to port and IP address 3 - Listen

4.3.2.2 TCPServer::TCPServer () [inline]

4.3.3 Member Function Documentation

4.3.3.1 void TCPServer::accept (TCPServer & *new_socket*)

4.3.3.2 void TCPServer::connect (TCPServer & *dsocket*, char * *ip*, unsigned short *port*)

Create connection to a **TCPServer** (p. 10).

Parameters

<i>char</i>	* IP address of the server to connect to
<i>port</i>	Port number of the server to connect to

4.3.3.3 void TCPServer::disc (TCPServer & new_socket)

Shutdown socket.

Note: shutdown() used instead of close() since the function shutdown gives more control over what happen to the data in the socket to be closed.

4.3.3.4 TCPServer & TCPServer::operator<< (std::string & s)

Operator << is overwrite to read.

Parameters

<i>string</i>	string to allocate received data. Accept new connection to the TCP-Server (p. 10).
---------------	---

4.3.3.5 TCPServer & TCPServer::operator>> (std::string s)

Operator >> is overwrite to write.

Parameters

<i>string</i>	string to be send.
---------------	--------------------

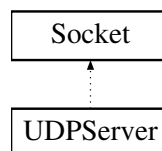
The documentation for this class was generated from the following files:

- **SocketTCP.h**
- **SocketTCP.cpp**

4.4 UDPServer Class Reference

```
#include <SocketUDP.h>
```

Inheritance diagram for UDPServer:



Public Member Functions

- **UDPServer** (unsigned short port)
- **UDPServer** ()

- **UDPServer & operator>>** (std::string)
- **UDPServer & operator<<** (std::string &)
- void **disc** (UDPServer &)
- void **connect** (UDPServer &)

4.4.1 Constructor & Destructor Documentation

4.4.1.1 UDPServer::UDPServer (unsigned short *port*)

4.4.1.2 UDPServer::UDPServer () [inline]

4.4.2 Member Function Documentation

4.4.2.1 void UDPServer::connect (UDPServer & *dsocket*)

4.4.2.2 void UDPServer::disc (UDPServer & *new_socket*)

4.4.2.3 UDPServer & UDPServer::operator<< (std::string & *s*)

4.4.2.4 UDPServer & UDPServer::operator>> (std::string *s*)

The documentation for this class was generated from the following files:

- **SocketUDP.h**
- **SocketUDP.cpp**

Chapter 5

File Documentation

5.1 Relay Server.cpp File Reference

```
#include "SocketTCP.h"    #include "SocketUDP.h"    #include
<iostream> #include <sys/socket.h> #include <netdb.h> ×
#include <string> #include <pthread.h>
```

Defines

- **#define BOARD_IP "127.0.0.1"**
< Localhost is used in this example since daemon is not yet implemented
- **#define BOARD_PORT 5555**
Port to connect to daemon.

Functions

- void * **tcpTh** (void *)
- int **main** ()
- void * **udpTh** (void *)

5.1.1 Define Documentation

5.1.1.1 #define BOARD_IP "127.0.0.1"

< Localhost is used in this example since daemon is not yet implemented

EA-LPC2478 Board IP address daemon

5.1.1.2 `#define BOARD_PORT 5555`

Port to connect to daemon.

Prototyping threads procedures.

5.1.2 Function Documentation

5.1.2.1 `int main ()`

5.1.2.2 `void * tcpTh (void *)`

Fork new process in parallel, this creates a new process with a different ID (Important to exit the process when done "exit(0)")

5.1.2.3 `void* udpTh (void *)`

5.2 RelayTest.cpp File Reference

5.3 ServerSocket.h File Reference

Classes

- class **serverSocket**

5.4 Socket.cpp File Reference

```
#include "Socket.h" #include <sys/types.h> #include <sys/socket.-
h> #include <sys/time.h> #include <netinet/in.h> #include
<netdb.h> #include <stdio.h> #include <string.h> #include
<unistd.h> #include <stdlib.h> #include <fcntl.h> #include
"string"
```

5.5 Socket.h File Reference

```
#include <sys/types.h> #include <sys/socket.h> #include
<netinet/in.h> #include <netdb.h> #include <unistd.h> ×
#include <string> #include <arpa/inet.h>
```

Classes

- class **Socket**

Defines

- `#define MAX_BUF 1000`

5.5.1 Define Documentation

5.5.1.1 `#define MAX_BUF 1000`

5.6 SocketTCP.cpp File Reference

```
#include "SocketTCP.h" #include <iostream>
```

5.7 SocketTCP.h File Reference

```
#include "Socket.h"
```

Classes

- class **TCPServer**
TCPServer (p. 10) Class.

5.8 SocketUDP.cpp File Reference

```
#include "SocketUDP.h" #include <iostream>
```

5.9 SocketUDP.h File Reference

```
#include "Socket.h"
```

Classes

- class **UDPServer**