

Area Scanning Control System for Back-packable Robot Boats

Report for CS39440 Major Project

Author: Elizabeth Stone (eas12)
Supervisor: Mark Neal (mjn)

Version: 1.0 - Draft
Friday 14th April, 2017



This report was submitted as partial fulfilment
of a BSc degree in Space Science and Robotics (FH56)

Acknowledgements

i thank...

Abstract

this project...

Contents

Acknowledgements	1
Abstract	2
Background & Objectives	4
Background	4
Analysis	4
Process	4
Design	5
Overall Architecture	5
Implementation	6
Testing	7
Overall Approach	7
Unit tests	7
Integration Testing	7
Evaluation	8

Background & Objectives

Background

previously was used manually using RC. Create a working controll system to autonomously control the boat.

Analysis

To autonomize the robotic boat - I learnt this...

Process

I used FDD...

Design

this is some words hello world?

Overall Architecture

Stuff

Implementation

this is some words hello world?

Testing

this is some words hello world?

Overall Approach

Stuff

Unit tests

more stuff

Integration Testing

More more stuff

Evaluation

this is some words hello world?