AP Calculus BC

2024-2025 Syllabus

1. Limits & Continuity

- a. Limits mean "approach", not "equal"
 - i. When a limit doesn't seem to exist (when plugged in directly), evaluate from the left and the right.
 - ii. The limit is equal to the left and the right limit (if they're both equal)

iii.

- b. Unbounded limit (approaches infinity) when n/0 for $n \neq 0$
- c. Limit is indeterminate (use methods to solve for) when 0/0, ∞/∞
 - i. Algebraic manipulation (factoring so "hole" cancels out)
 - ii. Rationalization (rationalizing denominator so "hole" cancels out), use conjugates
- iii. Common denominator (fraction/fraction, "hole" cancels out)
- iv. L'Hôpital's Rule: the limit of $f(x)/g(x) = \lim_{x \to \infty} f'(x)/g'(x)$ if f(x)/g(x) is indeterminate
- v. Graph Composite Functions: In composite piecewise functions, the limit might not be apparent. E.g. f(g(x)), evaluate $x \rightarrow a$ from left and right side and if g(x) approaches that value from up, then evaluate $g(x) \rightarrow b+$. If from below then $g(x) \rightarrow b-$, etc. Then evaluate f(x) accordingly.
- d. Squeeze Theorem Used when the value of a function or its limit is not apparent but you know the function's range
 - i. Only conclusive when lower bound = upper bound for the value you want to find
 - ii. E.g. $f(x) \le g(x) \le h(x)$ then Squeeze Theorem works when f(x) = h(x), thus g(x) = f(x) = h(x)
- e. Continuity at a point occurs when...

$$\lim_{x \to a} f(x) = f(a)$$

$$\lim_{x \to a} f(x) = \lim_{x \to a^{+}} f(x) = \lim_{x \to a^{-}} f(x)$$

- f. Continuity over an interval occurs for polynomial, some trigonometric, exponential, etc. functions and evaluate continuity at a point on uncertain points
- g. You can remove a discontinuity with algebraic manipulations (factorization, rationalization, etc.)
- h. Limits toward infinity is the end behavior of a function (horizontal or slant asymptote)
- i. Discontinuities: Jump, Point (Removable), Asymptotic
- j. Intermediate Value Theorem On a continuous function there must exist at least one point (c, f(c)) if f(a) < f(c) < f(b) or f(b) < f(c) < f(a) and a < c < b.
 - i. Justification requires continuity, interval (and the inequality), and stating the IVT

2. Differentiation: Basics

a. Definition

$$\lim_{h \to 0} \frac{f(x+h) - f(x)}{h} \quad \text{or} \quad \lim_{x \to a} \frac{f(x) - f(a)}{x - a}$$

b. Power Rule

$$\frac{d}{dx}[x^n] = n \cdot x^{n-1}$$

c. Product Rule

$$\frac{d}{dx}[u \cdot v] = u' \cdot v + u \cdot v'$$

d. Quotient Rule

$$\frac{d}{dx}\left[u \div v\right] = \frac{u' \cdot v - u \cdot v'}{v^2}$$

e. Trig Functions

| <u>FUNCTION</u> | <u>DERIVATIVE</u> | <u>FUNCTION</u> | <u>DERIVATIVE</u> |
|-----------------|----------------------|-----------------|-----------------------|
| sin(x) | cos(x) | sec(x) | sec(x)tan(x) |
| cos(x) | -sin(x) | csc(x) | -csc(x)cot(x) |
| tan(x) | sec ² (x) | cot(x) | -csc ² (x) |

3. Differentiation: Advanced

a. Chain Rule

$$\frac{d}{dx}[u(v)] = v' \cdot u'(v)$$

b. Implicit Differentiation

$$\frac{d}{dx}[y] = \frac{dy}{dx}$$

When differentiating a variable you're not explicitly differentiating it to (e.g. t, time), make sure to multiply by the derivative of that variable with respect to the independent variable.

c. Inverse Differentiation

$$\frac{d}{dx}[f^{-1}(x)] = \frac{1}{f'(f^{-1}(x))}$$

- d. Higher Derivatives Differentiate the derivative as normal and substitute lower derivatives if needed for simplification
- e. Inverse Trig Functions

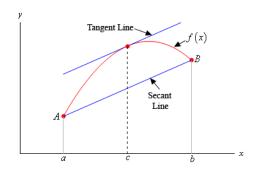
| <u>FUNCTION</u> | <u>DERIVATIVE</u> | <u>FUNCTION</u> | <u>DERIVATIVE</u> |
|-----------------|---------------------------|-----------------|------------------------------|
| arcsin(x) | $\frac{1}{\sqrt{1-x^2}}$ | arcsec(x) | $\frac{1}{ x \sqrt{x^2-1}}$ |
| arccos(x) | $-\frac{1}{\sqrt{1-x^2}}$ | arccsc(x) | $-\frac{1}{ x \sqrt{x^2-1}}$ |
| arctan(x) | $\frac{1}{x^2+1}$ | arccot(x) | $-\frac{1}{x^2+1}$ |

4. Differentiation: Contextual application

- a. Related Rates Using implicit differentiation, you can relate the rates of different variables in a multivariable equation (e.g. Pythagorean Theorem).
 - i. Be attentive to constant variables (derivative = 0) and substitute in the original equation if needed.
- b. Local linearity You can approximate nearby points with a tangent line to the curve. The value is underestimated when concave up, overestimated when concave down.

5. Differentiation: Analyzing functions

- a. Mean Value Theorem Differentiable function over interval must have an instantaneous slope somewhere on the interval equal to the average rate of change of the interval.
 - i. Justify with differentiability, f'(c) = (f(b)-f(a))/(b-a) for a < c < b, and MVT



- b. Critical Point Points where the derivative = 0 or undefined (vertical tangents included). Has a chance of being a relative extremUM.
- c. Extreme Value Theorem If a function is continuous over a closed interval, then there must exist absolute extrema value over that interval
- d. Candidates Test To find absolute extrema. Find critical points and evaluate end point values and critical point values. Determine the absolute extrema.
- e. First Derivative Test A relative minimum occurs when the function's derivative changes from negative to positive. A relative maximum occurs when the function's derivative changes from positive to negative.
- f. Second Derivative Test A relative minimum occurs when the function's derivative is 0 or undefined and the function's second derivative is positive. A relative maximum occurs when the function's derivative is 0 or undefined and the function's second derivative is negative.
- g. Inflection point is a point at which a function changes concavity (second derivative changes signs)
- h. Optimization To maximize or minimize a value in a related rates problem (through first/second derivative tests or candidate tests). Analyze given variables carefully.

6. Integration and accumulation of change

- a. Integration is anti-differentiation (accumulating change), area under the curve
- b. Riemann sum can approximate area under the curve

| APPROXIMATI ON | INCREASING | <u>DECREASING</u> | CONCAVE UP | CONCAVE DOWN |
|----------------------------|---------------|-------------------|---------------|-------------------|
| Left Riemann Sum | Underestimate | Overestimate | No effect | No effect |
| Right Riemann Sum | Overestimate | Underestimate | No effect | No effect |
| Midpoint Riemann Sum | No effect | No effect | Overestimate | Underestimat e |
| Trapezoidal Riemann Sum | No effect | No effect | Underestimate | Overestimate |

c. Riemann approximation with infinite summation

Left Riemann

$$\int_{a}^{b} f(x)dx = \lim_{n \to \infty} \left(\sum_{k=0}^{n-1} \left[\left(\frac{b-a}{n} \right) \cdot f\left(a + \frac{b-a}{n}k \right) \right] \right)$$

Right Riemann

$$\int_{a}^{b} f(x)dx = \lim_{n \to \infty} \left(\sum_{k=1}^{n} \left[\left(\frac{b-a}{n} \right) \cdot f(a + \frac{b-a}{n}k) \right] \right)$$

- d. Definite integrals Accumulation with definite bounds
- e. Indefinite integrals General formula with no definite bounds (has a +c in the end to denote vertical shifts)

f. Integral Properties

$$\int_{a}^{a} f(x)dx = 0$$

$$\int_{a}^{b} f(x)dx = -\int_{b}^{a} f(x)dx$$

$$\int_{a}^{c} f(x)dx = \int_{a}^{b} f(x)dx + \int_{b}^{c} f(x)dx$$

g. Fundamental Theorem of Calculus

$$\frac{d}{dx} \left[\int_{a}^{x} f(t)dt \right] = f(x)$$

$$\frac{d}{dx} \left[\int_{h(x)}^{g(x)} f(t)dt \right] = \left[f(g(x)) \cdot g'(x) \right] - \left[f(h(x)) \cdot h'(x) \right]$$

$$F(b) = F(a) + \int_{a}^{b} f(t)dt$$

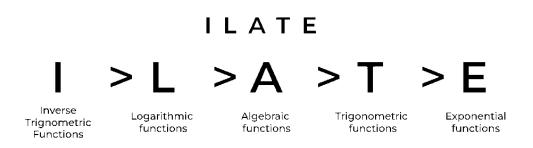
h. U-Substitution - Method to integrate composite functions (opposite of chain rule). Substitute u for the internal function and then solve for du in terms of dx (by differentiating u). This allows you to differentiate in u instead of x. Be aware of bounds in the case of definite integrals (x= is not the same as u=)

i. Integration by Parts - Method to integrate product of functions (opposite of product rule).

$$\int f(x) \cdot g(x) dx = f(x) \cdot g(x) - \int f'(x) \cdot g(x) dx$$

$$\int uv'dx = uv - \int v \, du$$

Select u or f(x) based on the following priorities:



j. Integration using linear partial fractions - Method to integrate by splitting a fraction into multiple.

$$\int \frac{ax+b}{f(x)\cdot g(x)} dx = \int \frac{A}{f(x)} + \frac{B}{g(x)} dx$$

Solve for A and B by equating A*g(x) + B*f(x) with ax + b

k. Improper integrals - Some integrals are asymptotic or involve an infinite bound. You can evaluate this by setting a limit (this does not guarantee that the integral will exist).

$$\int_{a}^{\infty} f(x)dx = \lim_{n \to \infty} \int_{a}^{n} f(x)dx = \lim_{n \to \infty} F(n) - F(a)$$

7. Differential Equations

a. Euler's method - Method to approximate a differential equation solution. Start at an initial value, calculate dy/dx at that x-value. Move onto the next x-value (+step size), to calculate the new y, increment the old y by dy/dx at the previous point (divided by step size). E.g:

| X-VALUE (step = 0.5) | Y-VALUE | <u>DY/DX</u> (dy/dx=y) |
|----------------------|-----------|------------------------|
| 0 | 1 (given) | 1 |
| 0.5 | 1.5 | 1.5 |
| 1 | 2.25 | 2.25 |
| 1.5 | 3.375 | 3.375 |