	GM110-8 Specifications Standard
Appearance requirements	

NO.	Project	Requirement		
1	Motor diameter (mm)	Ф110±0.05mm	/	
2	Motor length (mm)	33.9±0.2 (with encoder) mm	vith encoder) mm	
3	Motor slot/pole number 24N/28P		/	
4	Axial outer diameter (mm)		/	
5	Inner diameter of shaft (mm) /		/	
6	wire length (mm) 610mm±3mm Without Plug		/	
7	The color of the line 24# black silicone wire		/	
8	weight (g) 559±1g		/	
9	plug	2.5 pitch connector	/	
10	Axial clearance (virtual 0		/	
	position)			

Performance Requirement

NO.	Project		Requirement	Remarks
1	No-load	voltage (V)	20V	KV box
		current (A)	0.09±0.1 A	/
		speed (RPM)	125~139 RPM	/
_	Load	voltage (V)	20	/
2		current (A)	2	/
		torsion $(G \bullet cm)$	8000-12000	/
3	Numbe	er of windings (T)	0.33*1-150T Y connection method	
4	Wired internal resistance of finished product $(m\Omega)$		20.19Ω±5%(The resistance will change with the ambient temperature. If the resistance exceeds the standard range due to environmental changes, the standard should be signed again)	/
5	high voltage test		DC500V 1mA 2 Seconds	/
6	The rotor housing jumps		≤0.1mm	/
7	Translation (shaft extension view)		Clockwise (unified test wiring)	/
8	High temperature test		60°C Keep 100 hours, and the motor can work normally after 24 hours at room temperature	/
9	Cold test		-20°C Keep for 100 hours, and the motor can work normally after 24 hours at room temperature	/
10	maximum power		≤60W	
11	Use	voltage range	4-6S (calculated according to lithium battery 3.7-4.2V/S)	Constant power
12	service environment		Temperature: -20~60°C, humidity: 10~90%RH	Normal temperature and humidity