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United States Patent	12390878
Kind Code	B2
Date of Patent	August 19, 2025
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### System and method for metal forming and layering using inductive heating

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#### Abstract

The present disclosure is directed, in certain embodiments, a system for depositing material from a metal feedstock. The system includes a feedstock guide configured to guide a metal feedstock from a material feeder to extend beyond a terminal end of the feedstock guide. The system includes a ceramic collar disposed at the terminal end of the feedstock guide and configured to guide the metal feedstock extending from the terminal end of the feedstock guide to a deposition outlet of the ceramic collar. An induction coil disposed adjacent to the ceramic collar and configured to heat a portion of the metal feedstock within the ceramic collar, such that material of the metal feedstock can be deposited on a surface from the deposition end of the ceramic collar.

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**Appl. No.:** 17/547387

**Filed:** December 10, 2021

#### Prior Publication Data

Document Identifier	Publication Date
US 20230182229 A1	Jun. 15, 2023

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#### Publication Classification

**Int. Cl.:** B23K13/01 (20060101); B23K13/08 (20060101); B23K35/32 (20060101); B33Y10/00 (20150101); B33Y30/00 (20150101); B33Y50/02 (20150101); B33Y70/00 (20200101)

## U.S. Cl.:

CPC     **B23K13/01** (20130101); **B23K13/08** (20130101); **B23K35/327** (20130101); **B33Y10/00** (20141201); **B33Y30/00** (20141201); **B33Y50/02** (20141201); **B33Y70/00** (20141201);

## Field of Classification Search

**CPC:**    B33Y (50/02); B33Y (10/00); B33Y (70/00); B33Y (70/10); B33Y (30/00); B23K (13/01); B23K (13/02); B23K (13/08); B23K (35/327); B29C (64/00); B29C (64/118); B29C (64/141); B29C (64/209); B29C (64/227); B29C (64/232); B29C (64/236); B29C (64/241); B29C (64/295); B29C (64/321); B29C (64/393)

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## Background/Summary

### TECHNICAL FIELD OF THE DISCLOSED SUBJECT MATTER

(1) The present disclosure generally relates to metal forming processes and systems, and more specifically to a system and method for metal forming and layering using inductive heating.

### BACKGROUND OF THE DISCLOSED SUBJECT MATTER

(2) In metal forming processes, metal from a source is generally heated sufficiently for it to be formed into a desired structure. In some cases, a large mechanical force may be applied to generate friction where a metal source contacts a substrate. This friction heats the metal source, and the metal source is deposited on the surface once it reaches a sufficiently high temperature. There exists a need for improved metal forming and layering processes and improved systems for performing these processes.

### SUMMARY OF THE DISCLOSED SUBJECT MATTER

(3) The purpose and advantages of the disclosed subject matter will be set forth in and are apparent from the description that follows, as well as will be learned by practice of the disclosed subject matter. Additional advantages of the disclosed subject matter will be realized and attained by the devices particularly pointed out in the written description and claims hereof, as well as from the appended drawings.

(4) To achieve these and other advantages and in accordance with the purpose of the disclosed subject matter, as embodied and broadly described, the disclosed subject matter includes a feedstock guide configured to guide a metal feedstock from a material feeder to extend beyond a terminal end of the feedstock guide. A ceramic collar is disposed at the terminal end of the feedstock guide and configured to guide the metal feedstock extending from the terminal end of the feedstock guide to a deposition outlet of the ceramic collar. At least one induction coil is disposed adjacent to the ceramic collar and configured to heat a portion of the metal feedstock within the ceramic collar and allow material of the metal feedstock to be deposited on a surface from the deposition end of the ceramic collar.

(5) Additionally, the system may include a drive system configured to rotate the metal feedstock when the at least one induction coil is powered. The material feeder may be configured to store the metal feedstock and release the metal feedstock at a controlled rate when the drive system rotates the metal feedstock. The system may include a movable table configured to hold a substrate on which the material of the metal feedstock is deposited. A control system may cause the movable table to move while the material of the metal feedstock is deposited.

(6) Moreover, the system may include an infrared thermometer configured to measure a temperature of the heated portion of the metal feedstock. A control system may receive the temperature measured by the infrared thermometer and adjust the power provided to the induction coil based on a comparison of the temperature and a target temperature.

(7) Furthermore, the metal feedstock may be a metal or alloy wire. For example, the material of the metal feedstock may be an alloy with a softening temperature of about 1500° F. or greater.

(8) In accordance with another aspect of the disclosed subject matter, a material deposition system includes a feedstock guide configured to guide a metal feedstock from a material feeder to extend beyond a terminal end of the feedstock guide. A ceramic collar is disposed around the metal feedstock extending from the terminal end of the feedstock guide and extending at least partially around a plurality of ceramic bearings configured to guide the metal feedstock extending from the terminal end of the feedstock guide to a deposition outlet of the ceramic collar. At least one induction coil is disposed adjacent to the ceramic collar and configured to heat a portion of the metal feedstock surrounded by the ceramic bearings and allow material of the metal feedstock to be deposited on a surface from the deposition end of the ceramic collar.

(9) Moreover, the system may include a drive system configured to rotate the metal feedstock when the at least one induction coil is powered. The material feeder may be configured to store the metal feedstock and release the metal feedstock at a controlled rate when the drive system rotates the metal feedstock. The system may include a movable table configured to hold a substrate on which the material of the metal feedstock is deposited. A control system may cause the movable table to move while the material of the metal feedstock is deposited.

(10) Additionally, the system may include an infrared thermometer configured to measure a temperature of the heated portion of the metal feedstock. A control system may receive the temperature measured by the infrared thermometer and adjust the power provided to the induction coil based on a comparison of the temperature and a target temperature.

(11) Furthermore, the metal feedstock may be a metal or alloy wire. For example, the material of the metal feedstock may be an alloy with a softening temperature of about 1500° F. or greater.

(12) In accordance with another aspect of the disclosed subject matter, a method of depositing material from a metal feedstock includes steps of contacting metal feedstock extending from a deposition end of a ceramic collar to a surface, inductively heating a portion of the metal feedstock within the ceramic collar, and, while inductively heating the portion of the metal feedstock, rotating the metal feedstock, thereby depositing material of the metal feedstock on the surface.

(13) Furthermore, the method may include a step of releasing the metal feedstock from a material feeder at a controlled rate while rotating the metal feedstock. The method may include a step of moving a table holding the surface while the material of the metal feedstock is deposited on the

surface. The method may include a step of heating the portion of the metal feedstock within the ceramic collar by providing power to an induction coil positioned adjacent to the ceramic collar. (14) The method may include a step of measuring a temperature of the heated portion of the metal feedstock. The method may include a step of adjusting an amount of induction heating provided to the portion of the metal feedstock within the ceramic collar based on a comparison of the measured temperature and a target temperature.

(15) Previous metal forming and layering technology suffers from various drawbacks and limitations, the recognition which are encompassed by this disclosure. For instance, this disclosure recognizes that components made of refractory materials (i.e., metals or alloys with very high softening temperatures) cannot be reliably formed using conventional material deposition systems. The temperature required to deposit these refractory materials may be too high, resulting in damage to the deposition system and/or a substrate on which the material is initially deposited. If a deposition system that employs high mechanical forces is used to deposit the refractory materials, the excessively high mechanical forces needed may damage the deposition system and/or a substrate on which the material is initially deposited. In some cases previous deposition technologies may not be capable of being adapted to withstand the temperatures and/or mechanical forces required to deposit the refractory materials. Even if such adaptation is possible, the resulting system may be prohibitively costly for practical applications. This disclosure also recognizes that if previous deposition approaches are attempted for these refractory materials, the deposited material is relatively low quality with uneven layers of the material deposited irregularly. These low quality deposited layers may not be suitable for their intended purpose, such that desired structures cannot be prepared from refractory materials using previous technology. In some cases, these limitations may be a crucial bottleneck in the preparation of components from refractory materials and the development of technologies using such components.

(16) Technical advantages of certain embodiments of this disclosure may include one or more of the following. For example, this disclosure facilitates the layer-by-layer deposition of refractory materials (or other metals or alloys) using induction (e.g., inductive heating) to locally heat a metal feedstock near a deposition point. The system includes a ceramic structure (e.g., a ceramic collar and/or ceramic beads, also generally referred to as bearings herein) around the end of a metal feedstock. An induction coil is located on or near the ceramic structure. When the induction coil is powered, the portion of the metal feedstock within the ceramic structure is heated without significantly heating the ceramic structure itself. The metal feedstock receives the vast majority of the energy that inductively heats only the metal or alloy of the feedstock. This approach facilitates controlled heating of the metal feedstock near the point where deposition is performed without significant heating of other components of the system. Using this approach, the metal feedstock can be deposited with significantly less mechanical force applied to a deposition surface or substrate. As such, damage to the deposition system, the underlying surface/substrate, and any previously deposited layers is decreased or eliminated. Since less mechanical force is needed for deposition, the deposition system can also have a simpler construction (e.g., with less mechanical reinforcement) and lower cost. The induction-based deposition approach of this disclosure also allows components to be formed in a precise, layer-by-layer process using refractory materials that were previously inaccessible to previous deposition technologies. In certain embodiments, this approach provides unprecedented control of the structure of such components. For example, a refractory material, such as a rhenium alloy or titanium-aluminum alloy, can be deposited in a precise layer-by-layer fashion to achieve a desired structure.

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## Description

## BRIEF DESCRIPTION OF THE DRAWINGS

- (1) The subject matter of the application will be more readily understood from the following detailed description when read in conjunction with the accompanying drawings, in which:
- (2) FIG. 1A is a diagram illustrating a material deposition system, in accordance with certain embodiments;
- (3) FIG. 1B is a diagram illustrating a region that includes a metal feedstock outlet portion of the system of FIG. 1A, in accordance with certain embodiments;
- (4) FIG. 2A is a diagram illustrating a material deposition system with ceramic bearings, in accordance with certain embodiments;
- (5) FIG. 2B is a diagram illustrating a region that includes a metal feedstock outlet portion of the system of FIG. 2A, in accordance with certain embodiments;
- (6) FIG. 3 is a diagram illustrating material deposition using a material deposition system of FIG. 1A or 2A, in accordance with certain embodiments;
- (7) FIG. 4 is a flowchart illustrating a method of material deposition using a material deposition system of FIG. 1A or 2A, in accordance with certain embodiments; and
- (8) FIG. 5 is a diagram of a system for performing the method of FIG. 4, in accordance with certain embodiments.

## DETAILED DESCRIPTION

(9) As described above, previous material deposition technology suffers from various drawbacks and limitations, particularly with respect to the deposition of refractory materials. As used in this disclosure, a refractory material refers to a metal or alloy that needs to reach a very high temperature in order to become sufficiently soft for deposition. The temperature required to become sufficiently soft for deposition is referred to herein as a “softening temperature.” A refractory material may have a softening temperature of greater than 1500° F., greater than 2000° F., greater than 3000° F., greater than 4000° F., or higher. Previous metal and alloy deposition technologies generally only function reliably with metal or alloys with softening temperatures of less than 1000° F. or lower. Previous deposition technology also tends to fail when the substrate has a lower softening temperature than the material being deposited. The new material deposition systems of this disclosure overcome this limitation by directing the majority of heating only to the metal feedstock, such that refractory materials can be deposited on substrates with lower softening temperatures than that of the deposited material.

(10) Reference will now be made in detail to embodiments of the disclosed subject matter, an example of which is illustrated in the accompanying drawings. FIG. 1A illustrates an example material deposition system with a ceramic collar around the heated end of metal feedstock. FIG. 1B illustrates the heated end of the metal feedstock from FIG. 1A in greater detail. FIG. 2A illustrates an exemplary material deposition system with ceramic bearings around the heated end of metal feedstock. FIG. 2B illustrates the heated end of the metal feedstock from FIG. 2A in greater detail. FIG. 3 illustrates an exemplary material deposition process in progress. FIG. 4 is a flowchart of an exemplary material deposition process. FIG. 5 illustrates a system that includes the material deposition system of this disclosure. While these figures often depict or refer to depositing layers of materials, such as metals or alloys, it is to be understood that the present disclosure is not necessarily limited to the deposition of such layers, and the principles disclosed herein may have applicability to various types or forms of components, as understood by one of skill in the art.

### (11) Material Deposition Systems

(12) FIGS. 1A and 1B illustrate an exemplary material deposition system **100** with a ceramic collar **116** around the end of a metal feedstock **114** and one or more induction coils **118** adjacent to the ceramic collar **116** that inductively heat the metal feedstock **114** in the ceramic collar **116**. The material deposition system **100** includes a frame **102**, a material feeder **104**, a drive system **106**, an induction controller **108**, a feedstock guide **110**, a ceramic guide block **112**, the metal feedstock

**114**, a ceramic collar **116**, and the induction coil(s) **118**. Region **150** near the end of the feedstock guide **110** is shown in greater detail in FIG. **1B**. Exemplary operation of the material deposition system **100** is described in greater detail with respect to FIGS. **3** and **4** below. A system that includes the material deposition system **100** as a subcomponent is described in greater detail with respect to FIG. **5**.

(13) The frame **102** holds components of the material deposition system **100** in position. The frame **102** may be mounted on another surface. For example, the frame **102** may be affixed to an industrial robot or to a computerized numerical control (CNC) machine. In some embodiments, such as is illustrated in FIG. **3**, the frame **102** is stationary and a surface is moved below the material deposition system **100** to facilitate the deposition of continuous layers of material from the metal feedstock **114**. However, in some embodiments, the frame **102** may be movable (e.g., mounted on a movable arm), such that the material deposition system **100** can move while material is deposited from the metal feedstock.

(14) The material feeder **104** stores the metal feedstock **114** and releases the metal feedstock **114** during material deposition. For example, the material feeder **104** may be a housing configured to store material of the metal feedstock **114** and release the metal feedstock **114** at a controlled rate (e.g., at a predefined rate) during deposition. The material feeder **104** may drop the metal feedstock **114** into the feedstock guide **110** and spot weld the metal feedstock **114** provided into the feedstock guide **110** to form a continuous wire of metal feedstock **114** that extends through the feedstock guide **110**. The metal feedstock **114** may be released when the drive system **106** rotates the metal feedstock **114** during deposition. The drive system **106**, described below, may aid in controlling the rate at which the metal feedstock **114** is released.

(15) The drive system **106** is configured, when turned on, to rotate the metal feedstock when the induction coil(s) **118** are powered. The drive system **106** may include a drill press that rotates or spins the metal feedstock **114** and presses the metal feedstock **114** onto a substrate or surface **152** during deposition. FIG. **1B** illustrates rotation **154** of the metal feedstock **114** near a substrate/surface **152** on which material of the metal feedstock **114** is deposited. The substrate/surface **152** may be an initial surface on which material is deposited or a previous layer of the deposited material. The drive system **106** may cause the feedstock **114** to be released from the material feeder **104** during rotation. The drive system **106** may apply a downward force **160** during deposition. The drive system **106** may be controlled manually or by an integrated or separate control system (e.g., control system **510** illustrated in FIG. **5**, described below).

(16) The feedstock guide **110** is a strong hollow conduit configured to guide the metal feedstock **114** from the material feeder **104**. Metal feedstock **114** extends beyond a terminal end **156** of the feedstock guide **110**. The feedstock guide **110** may be made of a strong material, such as diamond or a diamond-containing material. The terminal end **156** of the feedstock guide **110** is configured to couple to the ceramic collar **116**.

(17) The induction controller **108** includes electronics and other components for powering the induction coil(s) **118**. For example, the induction controller **108** may include a liquid coolant system (e.g., coolant system **504** of FIG. **5**) that provides flow of cooled liquid coolant through the induction coil(s) **118** while the induction coil(s) **118** are powered. The induction controller **108** may include a current source (e.g., EMF generator **502** of FIG. **5**) that passes an electrical current through, or “powers,” the induction coil(s) **118**. The induction controller **108** may be operated manually (e.g., using a knob, as illustrated in FIG. **1A**) or through an integrated or separate control system (e.g., control system **510** illustrated in FIG. **5**, described below).

(18) The ceramic guide block **112** is a block of ceramic material with an opening to hold the feedstock guide **110** in place near or adjacent to the surface **152** where deposition is performed. The ceramic guide block **112** is made of a ceramic material to prevent the ceramic guide block **112** from being heated by the induction coil(s) **118**. The ceramic guide block **112** may be coupled to the frame **102** or affixed to an industrial robot, a CNC machine, or the like. The ceramic guide block

**112** may be stationary or movable.

(19) The metal feedstock **114** is generally a piece of the material (e.g., a metal or alloy wire) that is deposited using the material deposition system **100**. The metal feedstock **114** is typically a metal or alloy (e.g., aluminum, steel, etc.). In some embodiments, the metal feedstock **114** is a refractory material with a softening temperature of greater than 1500° F. In some embodiments, the metal feedstock **114** is a refractory material with a softening temperature of greater than 2000° F. In some embodiments, the metal feedstock **114** is a refractory material with a softening temperature of greater than 3000° F. In some embodiments, the metal feedstock **114** is a refractory material with a softening temperature of greater than 4000° F. As non-limiting examples, the metal feedstock **114** may be rhenium-containing alloy or a titanium-aluminum alloy. As described above, a softening temperature is the temperature at which a material softens sufficiently to perform deposition. For instance, a softening temperature may correspond to a temperature at which a material's strength decreases by 50%, 60%, 70%, 80%, 90% or more compared to its strength at room temperature. The metal feedstock **114** can generally have any cross-sectional shape. However, in some embodiments, the metal feedstock **114** has an approximately round cross section.

(20) The ceramic collar **116** is a hollow piece of ceramic material that can accommodate the metal feedstock **114** passing therethrough. The ceramic collar **116** has collar a shape with a central void through which the metal feedstock **114** passes. The ceramic collar **116** is disposed at the terminal end **156** of the feedstock guide **110** and guides the metal feedstock **114** extending from the terminal end **156** to a deposition outlet **158** of the ceramic collar **116** (see FIG. 1B).

(21) The induction coil(s) **118** may be hollow metallic (e.g., copper) tubes that are disposed adjacent to the ceramic collar **116** and configured, when powered by the induction controller **108**, to heat a portion of the metal feedstock **114** within the ceramic collar **116**. This inductive heating may occur primarily in the heat zone **162** illustrated in FIG. 1B that extends approximately the length of the induction coil(s) **118**. This inductive heating allows the material of the metal feedstock **114** to be deposited on the substrate/surface **152** from the deposition end **158** of the ceramic collar **116**. A liquid coolant may flow through the induction coil(s) **118** during inductive heating of the metal feedstock **114**. In some cases, inductive heating may be combined with a downward mechanical force **160** provided by the drive system **106**. For example, the heat zone **162** may be inductively heated to near the softening temperature of the material of the metal feedstock **114**, and additional heating up to the softening temperature may be provided through friction between the metal feedstock **114** and the substrate/surface **152**.

(22) FIGS. 2A and 2B show another example material deposition system **200** in which the ceramic guide block **112** has a different configuration (see ceramic guide block **202**) that has an integrated ceramic collar **204** that accommodates ceramic bearings **206**, which guide the metal feedstock **114** near the substrate/surface **152**. The material deposition system **200** includes the frame **102**, the material feeder **104**, the drive system **106**, the induction controller **108**, the feedstock guide **110**, the feedstock **114**, and the one or more induction coils **118** described above with respect to FIGS. 1A and 1B. The material deposition system **200** includes the different ceramic guide block **202** that has an integrated ceramic collar **204** within ceramic bearings **204** guide the metal feedstock **114**. Similarly to FIG. 1B, FIG. 2B illustrates region **250** near the end of the feedstock guide **110** with ceramic collar **204** and bearings **206** shown in greater detail. Exemplary operation of the material deposition system **200** is described in greater detail with respect to FIGS. 3 and 4 below. A system that includes the material deposition system **200** as a subcomponent is described in greater detail with respect to FIG. 5.

(23) As shown in FIG. 2B, the ceramic collar **204** and ceramic bearings **206** are positioned around the metal feedstock **114** that extends from the terminal end **156** of the feedstock guide **110**. The ceramic collar **204** extends at least partially around the ceramic bearings **206**, thereby holding the ceramic bearings **206** in place. The ceramic bearings **206** may be free to rotate such that the ceramic bearings **206** can guide the metal feedstock extending from the terminal end **156** of the

feedstock guide to the deposition outlet **158** of the ceramic collar **204**. The induction coil(s) **118** are disposed adjacent to (e.g., touching or within a few millimeters, centimeters, or the like) of the ceramic collar **204**. When the induction coil(s) **118** are powered (see description of induction controller **108** with respect to FIGS. **1A** and **1B** above), a portion of the metal feedstock **114** surrounded by the ceramic bearings **206** is heated (e.g., in the heat zone **162**). This inductive heating allows material of the metal feedstock **114** to be deposited on the substrate/surface **152** from the deposition end **158** of the ceramic collar **204**.

(24) Example of Operation of Material Deposition Systems

(25) FIG. **3** illustrates an example operation of a material deposition system **100**, **200**. To deposit material from the metal feedstock **114**, the metal feedstock **114** may be contacted to a substrate or previously deposited layer **310**. For example, an end of the portion of the metal feedstock **114** that extends beyond the ceramic collar **116**, **204** may contact the substrate or previously deposited layer **310**. The substrate of previously deposited layer **310** may be the substrate/surface **152** of FIGS. **1B** and **2B**, described above, or a layer of the material from the metal feedstock **114** that was already deposited on such a substrate/surface **152**.

(26) Inductive heating **302** of the metal feedstock within the ceramic collar **116**, **204** is then performed as described above with respect to FIGS. **1A,B** and **2A,B**. For example, the induction controller **108** may power the induction coil(s) **118** adjacent to the ceramic collar **116** (e.g., by providing current through the induction coil(s) **118**) to heat the metal feedstock **114** in the heat zone **162**. While performing inductive heating **302** of the portion of the metal feedstock **114**, rotation **304** of the metal feedstock **114** is performed, resulting in the deposition of material from the metal feedstock **114** on the substrate or previously deposited layer **310**. The drive system **106** may provide rotation **304** of the metal feedstock **114** (see FIGS. **1A,B**, and **2A,B** and corresponding description above). Rotation **304** may correspond to rotation **154** illustrated in FIGS. **1B** and **2B**. The metal feedstock **114** may also be released from the material feeder **104** while rotating the metal feedstock **114**.

(27) The substrate or previously deposited layer **310** may be held on a movable table **300**. The movable table **300** can perform vertical movement **308** to adjust the distance between the substrate or previously deposited layer **310** and the metal feedstock **114**. For example, the movable table **300** may be moved upwards toward the metal feedstock **114** to begin deposition. The movable table **300** can also perform lateral movements **310** in order to deposit the layer **312** of the material of the metal feedstock **114**. In the example of FIG. **3**, the movable table **300** is moving to the left to deposit layer **312** of the material of the metal feedstock **114**. Layer **312** may be any thickness. For example, the layer **312** may be about 20,000<sup>sup</sup>.th of an inch in some cases. The thickness of the deposited layer **312** may be adjusted as appropriate to obtain a desired final structure. After the layer **312** is complete, the movable table **300** may move down and back to a starting lateral position to deposit a subsequent layer (not illustrated) on top of layer **312**.

(28) In some embodiments, an infrared thermometer **314** may be used to measure a heat zone temperature **316** corresponding to a temperature of the heat zone **162**. An amount of inductive heating **302** provided to the portion of the metal feedstock **114** within the ceramic collar **116**, **204** may be adjusted based on the measured heat zone temperature **316**. For example, the power provided to the induction coil(s) may be adjusted using any appropriate feedback control strategy (e.g., proportional control proportional-integral, etc.) to maintain the heat zone temperature at or near a target temperature (e.g., target temperature **428** of FIG. **5**).

(29) The example operations described with respect to FIG. **3** may be coordinated by a user (e.g., by adjusting controllable rate of movement of the movable table **300**, a rate of rotation **302** provided by drive system **106**, an amount heating provided by the induction coil(s) **118**, etc.) and/or automated using a control system (e.g., the control system **510** of FIG. **5**).

(30) FIG. **4** illustrates an example method **400** of operating a material deposition system **100**, **200**. The method **400** may begin at step **402**, where a substrate **152** is mounted on a movable table **300**.



At step **404**, the metal feedstock **114** is loaded into the material feeder **104** of the material deposition system **100**. At step **406**, the movable table **300** is moved vertically such that the metal feedstock **114** extending from the deposition end **158** of the ceramic collar **116**, **204** contacts the substrate **152**.

(31) At step **408**, the induction coil(s) **118** are powered (e.g., by passing a current through the induction coil(s) **118**), resulting in a temperature increase in the heat zone **162**. At step **410**, a determination may be made of whether a target temperature (e.g., target temperature **528** of FIG. 5 is reached). For example, a heat zone temperature **316** may be measured with an infrared thermometer **314** and compared to the target temperature. If the heat zone temperature **316** is not within a threshold range of the target temperature, the induction power may be adjusted at step **412**. For example, a current provided to the induction coil(s) **118** may be increased or decreased to either increase or decrease, respectively, the temperature in the heat zone **162**.

(32) When the target temperature is reached at step **410**, the method **400** proceeds to step **414** where the metal feedstock is rotated. For example, the drive system **106** may be activated to rotate the metal feedstock **114** at a predefined rotation rate, resulting in deposition of the inductively heated metal feedstock **114** on the substrate **152**. At step **416**, the movable table **300** may be moved laterally (see lateral movement **306** of FIG. 3) to deposit a layer **312** of the material of the metal feedstock **114**. At step **418**, metal feedstock **114** is released from the material feeder **104** to facilitate continued deposition of the layer **312** of the material of the metal feedstock **114**.

(33) Example of Control System

(34) FIG. 5 illustrates an exemplary system **500** that includes a material deposition system **100**, **200**, a movable table system **506**, an infrared thermometer **314**, and a control system **510**. The material deposition system **100**, **200** is described above with respect to FIGS. 1A-4. The material deposition system **100**, **200** includes a controllable drive system **106** and induction controller **108**. The induction controller **108** may include an EMF generator or current source **502** and coolant system **504**. The EMF generator/current source **502** is used to power the induction coil(s) **118**, and the coolant system **504** provides a flow of cooled coolant through the induction coil(s) **118** while the induction coil(s) **118** are powered. The control system **510** provides control signals (e.g., drive control instructions **522** and induction control instructions **524**) for operating the drive system **106** and the induction controller **108**.

(35) The movable table system **506** includes the movable table **300** of FIG. 3 along with a movement motor **508**. The movable table **300** holds a substrate **152** on which the material of the metal feedstock **114** is deposited. The movement motor **508** is any electromechanical motor that can cause movement (e.g., lateral, or horizontal, movement **306** and vertical movement **308**) of the moveable table **300**. The control system **510** provides control signals (e.g., movement control instructions **526**) for operating the movement motor **508**.

(36) The infrared thermometer **314** measures a heat zone temperature **316** of the heated portion of the metal feedstock **114**. The infrared thermometer **314** is in communication with the control system **510**. The control system **510** receives the heat zone temperature **316** measured by the infrared thermometer **314** and adjusts the induction control instructions **524**, such that an adjusted power (or current) is provided to the induction coil(s) **118** based on a comparison of the heat zone temperature **316** and a target temperature **528**. For example, if the heat zone temperature **316** is less than the target temperature **528** (e.g., by at least a threshold value), the current provided to the induction coil(s) **118** (i.e., as indicated by the induction control instructions **524**) is increased. If the heat zone temperature **316** is greater than the target temperature **528** (e.g., by at least a threshold value), the current provided to the induction coil(s) **118** (i.e., as indicated by the induction control instructions **524**) is decreased.

(37) The control system **510** includes a processor **512**, a memory **514**, and an interface **516**. The processor **512** includes one or more processors. The processor **512** is any electronic circuitry including, but not limited to, state machines, one or more central processing unit (CPU) chips, logic

units, cores (e.g. a multi-core processor), field-programmable gate array (FPGAs), application specific integrated circuits (ASICs), or digital signal processors (DSPs). The processor **512** may be a programmable logic device, a microcontroller, a microprocessor, or any suitable combination of the preceding. The processor **512** is communicatively coupled to and in signal communication with the memory **514** and interface **516**. The processor **512** may be 8-bit, 16-bit, 32-bit, 64-bit or of any other suitable architecture. The processor **512** may include an arithmetic logic unit (ALU) for performing arithmetic and logic operations, processor registers that supply operands to the ALU and store the results of ALU operations, and a control unit that fetches instructions from memory **514** and executes them by directing the coordinated operations of the ALU, registers, and other components.

(38) The memory **514** is operable to store any data, instructions, logic, rules, or code operable to execute the functions of the system **500**. For example, the memory may store a component map file **520**, drive control instructions **522**, induction control instructions **524**, movement control instructions **526**, and target temperature **528**. The component map file **520** may be a three-dimensional representation of a component to be prepared by the system **500**. For example, the component map file **520** may include a computer-aided design (CAD) representation of the component that is to be prepared using the material of the metal feedstock **114**. The control system **510** may use the component map file **520** to determine appropriate drive control instructions **522**, induction control instructions **524**, movement control instructions **526**, and target temperature **528** for preparing the component indicated by the component map file **520**. The drive control instructions **522** indicate how the drive system **106** operates (e.g., to rotate and/or provide mechanic force) during deposition. The induction control instructions **524** provide instructions for powering the induction coil(s) **118** during deposition. The movement control instructions **526**, when provided to the movement motor **508**, cause the movable table **300** to move while the material of the metal feedstock **114** is deposited. The memory **514** includes one or more disks, tape drives, or solid-state drives, and may be used as an over-flow data storage device, to store programs when such programs are selected for execution, and to store instructions and data that are read during program execution. The memory **514** may be volatile or non-volatile and may comprise read-only memory (ROM), random-access memory (RAM), ternary content-addressable memory (TCAM), dynamic random-access memory (DRAM), and static random-access memory (SRAM).

(39) The interface **516** is configured to enable wired and/or wireless communications. The interface **516** is configured to communicate data between the control system **510** and other components of the system **500**, such as the material deposition system **100**, **200**, the movable table system **506**, and/or the infrared thermometer **314**. The interface **516** is an electronic circuit that is configured to enable communications between devices. For example, the interface **516** may include one or more serial ports (e.g., USB ports or the like) and/or parallel ports (e.g., any type of multi-pin port) for facilitating this communication. As a further example, the interface **516** may include a WIFI interface, a local area network (LAN) interface, a wide area network (WAN) interface, a modem, a switch, or a router. The processor **512** is configured to send and receive data using the interface **516**. The interface **516** may be configured to use any suitable type of communication protocol as would be appreciated by one of ordinary skill in the art.

(40) In sum, the systems and operations described herein may facilitate improved deposition of materials and particularly of refractory materials with relatively high softening temperatures. As a result, components can be prepared from and/or modified with refractory materials in a manner that was not possible using previous technology. Although primarily described as a process for preparing components, portions of the disclosed operations can be used to modify and/or repair an existing component. Since inductive heating is largely constrained to the portion of the metal feedstock **114** in the heated zone **162**, a refractory material can be effectively deposited on substrates that have lower softening temperatures than that of the refractory material with little or no impact on the quality of the substrate (e.g., with little or no damage, softening, etc. of the

substrate).

(41) Herein, “or” is inclusive and not exclusive, unless expressly indicated otherwise or indicated otherwise by context. Therefore, herein, “A or B” means “A, B, or both,” unless expressly indicated otherwise or indicated otherwise by context. Moreover, “and” is both joint and several, unless expressly indicated otherwise or indicated otherwise by context. Therefore, herein, “A and B” means “A and B, jointly or severally,” unless expressly indicated otherwise or indicated otherwise by context. The term “approximate” refers to being within about 30%, 20%, 10%, 5%, or less of a given value or another measurable characteristic. For example, an approximately circular cross section of a metal feedstock may have a roundness of at least 0.7, 0.8, 0.9, 0.95, or greater.

(42) While the disclosed subject matter is described herein in terms of certain embodiments, those skilled in the art will recognize that various modifications and improvements can be made to the disclosed subject matter without departing from the scope thereof. Additional features known in the art likewise can be incorporated. Moreover, although individual features of one embodiment of the disclosed subject matter can be discussed herein or shown in the drawings of the one embodiment and not in other embodiments, it should be apparent that individual features of one embodiment can be combined with one or more features of another embodiment or features from a plurality of embodiments.

(43) In addition to the various embodiments depicted and claimed, the disclosed subject matter is also directed to other embodiments having any other possible combination of the features disclosed and claimed herein. As such, the particular features presented herein can be combined with each other in other manners within the scope of the disclosed subject matter such that the disclosed subject matter includes any suitable combination of the features disclosed herein. The foregoing description of specific embodiments of the disclosed subject matter has been presented for purposes of illustration and description. It is not intended to be exhaustive or to limit the disclosed subject matter to those embodiments disclosed.

(44) It will be apparent to those skilled in the art that various modifications and variations can be made in the method and system of the disclosed subject matter without departing from the spirit or scope of the disclosed subject matter. Thus, it is intended that the disclosed subject matter include modifications and variations that are within the scope of the appended claims and their equivalents.

## Claims

1. A material deposition system, comprising: a feedstock guide comprising a plurality of ceramic bearings, the feedstock guide configured to guide a metal feedstock from a material feeder to extend beyond a terminal end of the feedstock guide; a ceramic collar disposed at the terminal end of the feedstock guide and configured to guide the metal feedstock extending from the terminal end of the feedstock guide to a deposition outlet of the ceramic collar; and at least one induction coil disposed adjacent to the ceramic collar and configured to: heat a portion of the metal feedstock surrounded by the ceramic bearings; and allow material of the metal feedstock to be deposited on a surface from the deposition end of the ceramic collar.
2. The system of claim 1, further comprising a drive system configured to rotate the metal feedstock when the at least one induction coil is powered.
3. The system of claim 2, wherein the material feeder is configured to store the metal feedstock and release the metal feedstock at a controlled rate when the drive system rotates the metal feedstock.
4. The system of claim 1, further comprising: a movable table configured to hold a substrate on which the material of the metal feedstock is deposited; and a control system configured to cause the movable table to move while the material of the metal feedstock is deposited.
5. The system of claim 1, further comprising an infrared thermometer configured to measure a temperature of the heated portion of the metal feedstock.
6. The system of claim 5, further comprising a control system configured to: receive the

temperature measured by the infrared thermometer; and adjust power provided to the induction coil based on a comparison of the temperature and a target temperature.

7. The system of claim 1, wherein the metal feedstock is a metal or alloy wire.

8. The system of claim 1, wherein the material of the metal feedstock is an alloy with a softening temperature of 1500° F. or greater.

9. A material deposition system, comprising: a feedstock guide configured to guide a metal feedstock from a material feeder to extend beyond a terminal end of the feedstock guide; a ceramic guide comprising an integrated ceramic collar disposed around the metal feedstock extending from the terminal end of the feedstock guide and extending at least partially around a plurality of ceramic bearings configured to guide the metal feedstock extending from the terminal end of the feedstock guide to a deposition outlet of the ceramic collar; and at least one induction coil disposed adjacent to the ceramic collar and configured to: heat a portion of the metal feedstock surrounded by the ceramic bearings; and allow material of the metal feedstock to be deposited on a surface from the deposition end of the ceramic collar.

10. The system of claim 9, further comprising a drive system configured to rotate the metal feedstock when the at least one induction coil is powered.

11. The system of claim 10, wherein the material feeder is configured to store the metal feedstock and release the metal feedstock at a controlled rate when the drive system rotates the metal feedstock.

12. The system of claim 9, further comprising: a movable table configured to hold a substrate on which the material of the metal feedstock is deposited; and a control system configured to cause the movable table to move while the material of the metal feedstock is deposited.

13. The system of claim 9, further comprising: an infrared thermometer configured to measure a temperature of the heated portion of the metal feedstock; and a control system configured to: receive the temperature measured by the infrared thermometer; and adjust the power provided to the induction coil based on a comparison of the temperature and a target temperature.

14. The system of claim 9, wherein the metal feedstock is a metal or alloy wire.

15. The system of claim 9, wherein the material of the metal feedstock is an alloy with a softening temperature of 1500° F. or greater.

16. A method of depositing material from a metal feedstock, the method comprising: forcing a metal feedstock through a ceramic collar comprising a plurality of ceramic bearings; contacting the metal feedstock extending from a deposition end of a ceramic collar to a surface; inductively heating a portion of the metal feedstock surrounded by the ceramic bearings; and while inductively heating the portion of the metal feedstock, rotating the metal feedstock, thereby depositing material of the metal feedstock on the surface.

17. The method of claim 16, further comprising releasing the metal feedstock from a material feeder at a controlled rate while rotating the metal feedstock.

18. The method of claim 16, further comprising moving a table holding the surface while the material of the metal feedstock is deposited on the surface.

19. The method of claim 16, further comprising: measuring a temperature of the heated portion of the metal feedstock; and adjusting an amount of induction heating provided to the portion of the metal feedstock within the ceramic collar based on a comparison of the measured temperature and a target temperature.

20. The method of claim 16, further comprising heating the portion of the metal feedstock within the ceramic collar by providing power to an induction coil positioned adjacent to the ceramic collar.

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