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System for mobile user terminal triggered handover

Abstract

A constellation of satellites provides communication services to user terminals (UTs). Some UTs may be mobile. Each satellite provides communication services to discrete geographic areas or “spots” on and above the Earth. The mobile UT determines it will be moving from a current spot to a destination spot based on one or more of geographic position and the geometry of the spots, or signal strength of received signals from one or more satellites associated with the destination spot. The mobile UT sends a handover request. Responsive to the handover request, communication resources associated with a handover time and the destination spot are allocated to the mobile UT. This information is provided to the mobile UT for use after the handover time. During this process, the exact position of the mobile UT remains unknown to the satellites and associated systems managing the constellation and handover.

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Background/Summary

BACKGROUND

(1) A constellation of satellites may provide communication services to many user terminals. Some user terminals may be mobile.

Description

BRIEF DESCRIPTION OF FIGURES

(1) The detailed description is set forth with reference to the accompanying figures. In the figures, the left-most digit(s) of a reference number identifies the figure in which the reference number first appears. The use of the same reference numbers in different figures indicates similar or identical items or features. The figures are not necessarily drawn to scale, and in some figures, the proportions or other aspects may be exaggerated to facilitate comprehension of particular aspects.

(2) FIG. 1 illustrates a satellite system to support a mobile user terminal (UT) triggered handover from one spot to another, according to some implementations.

(3) FIG. 2 is a block diagram of some systems associated with the satellite, according to some implementations.

(4) FIG. 3 illustrates spots providing communication service to a mobile user terminal and an intrasatellite handover and an intersatellite handover, according to some implementations.

(5) FIG. 4 illustrates state data and spot data that may be used to determine a handover request, according to some implementations.

(6) FIG. 5 illustrates a handover request, handover data, and grant data, according to some implementations.

(7) FIG. 6 depicts a flow diagram of a process to handover provisioning of communication service to a mobile UT from one spot to another, according to some implementations.

(8) FIG. 7 depicts a flow diagram of a system using the handover request sent by the mobile UT to handover provisioning from one spot to another, according to some implementations.

(9) While implementations are described herein by way of example, those skilled in the art will recognize that the implementations are not limited to the examples or figures described. It should be understood that the figures and detailed description thereto are not intended to limit implementations to the particular form disclosed but, on the contrary, the intention is to cover all

modifications, equivalents, and alternatives falling within the spirit and scope as defined by the appended claims. The headings used herein are for organizational purposes only and are not meant to be used to limit the scope of the description or the claims. As used throughout this application, the word “may” is used in a permissive sense (i.e., meaning having the potential to), rather than the mandatory sense (i.e., meaning must). Similarly, the words “include”, “including”, and “includes” mean “including, but not limited to”.

DETAILED DESCRIPTION

(10) A communications system may utilize a constellation of satellites to wirelessly transfer data between user terminals (UTs) and ground stations that in turn connect to other networks, such as the Internet. Some of these user terminals may remain stationary during operation, while others are mobile user terminals that change their position over time while maintaining communication with the constellation.

(11) Signals between the UT and the satellite are limited to travelling at the speed of light. The farther away a satellite is from the UT, the longer it takes for a signal to travel to the satellite and then travel back to Earth. For example, a hop (sending a signal to the satellite and back down to the ground, or vice versa) to a geosynchronous satellite introduces a delay of at least 240 milliseconds (ms). Additional delays due to signal processing, buffering, and so forth are also present. Such delays, or latency, are undesirable for many types of communication. For example, time-sensitive communication activities such as remote control of devices, industrial reporting and control, gaming, and so forth may be adversely affected by these latencies. In comparison, a hop involving a non-geosynchronous orbit (NGO) satellite at an altitude of 600 km only introduces about 4 ms of latency comprising 2 ms up to the satellite and 2 ms down to the UT. As a result, compared to using geosynchronous satellites, the use of NGO satellites significantly reduces latencies due to signal travel times.

(12) Using a constellation of many NGO satellites offers significant benefits compared to a geosynchronous satellite. Latency is dramatically reduced, improving usefulness for communication. Shorter distances between the UT and the satellite allow for increased UT density by allowing greater frequency re-use and sharing. Power and antenna gain requirements for both the UT and the satellites are also reduced due to the shorter distances compared to communication using geosynchronous satellites. This allows for relatively smaller and less expensive satellites to be used.

(13) The Earth may be divided into “spots”. Each spot may be represented by one or more of a specific geographic area or may be associated with parameters of communication resources that are allocated to provide communication in a “signal footprint” that is within and near those specific geographic areas. The geographic areas may be tessellated and non-overlapping. For example, the surface of the Earth may be divided into hexagonal cells.

(14) In comparison the geographic area associated with the respective communication resources may differ from the boundaries of those geographic areas. For example, given the parameters of communication resources such as antenna gain, frequency, transmit power levels, co-channel interference, antenna position, antenna direction, and so forth, signal coverage or a “signal footprint” on the Earth may extend beyond the edges of the respective geographic area. In another example, terrain such as high mountains may “shadow” or block coverage and reduce signal coverage to within the edges of the respective geographic area.

(15) Given the relatively short distances and gain provided by antennas on NGO satellites, the overall size of these spots may be relatively small. For example, a spot provided by a geosynchronous satellite may include an area that is thousands of miles on a side. In comparison, a spot provided by an NGO satellite may be tens of kilometers on a side.

(16) To maximize the utilization of the communication resources with a satellite, a UT may report current position data indicative of where the UT is located. The current position data may be determined by a navigation system. In one implementation the navigation system may comprise a

global navigation satellite system (GNSS) such as the Global Positioning System (GPS) that provides current position data that is accurate to within a few meters or less. Based on this information the UT may be allocated communication resources to send upstream data on an uplink to the satellite and communication resources for sending downstream data to the UT.

(17) While operating in a normal mode a mobile UT (MUT) provides precision current position data to at least a portion of the communication system, such as to a satellite. Based on the current position data, a resource scheduler allocates communication resources associated with access to a downlink and uplink in a single spot that the MUT is currently within. As the MUT approaches a border with another spot, handover data is generated based on the current position data and sent to the resource scheduler. Based on the current position data, speed, direction, and other information, handover data may be generated and provided to the MUT, allowing a seamless transfer of communication services while the MUT moves from one spot to another while minimizing overallocation of resources that would reduce overall system efficiency.

(18) In some circumstances it is advisable for the MUT to not report current position data. For example, an uncrewed aerial vehicle or other asset may include an MUT to provide communication service. The operator of the vehicle may choose to not provide precise current position data about the vehicle to the communication system.

(19) Described in this disclosure are systems and techniques to provide a self-triggered handover mode to an MUT that avoids the MUT sending information about the precise position of the MUT while still facilitating handovers of communication services from one spot to another. During operation in the self-triggered handover mode, the MUT determines state data such as current position, heading, velocity, distance to adjacent spots, received signal strength (RSS) for signals associated with spots, and so forth. If the MUT determines that it has moved from a first spot to a second spot, or predicts it will move to the second spot, a handover request is sent. The handover request omits geolocation-specific information, such as the current or predicted position of the MUT, avoiding disclosure of its specific position. In response to the handover request, other portions of the system determine handover data. The handover data is then sent to the MUT which utilizes the handover data to perform a handover from the first spot to the second spot at a specified handover time. The other portions of the system, such as one or more satellites associated with the handover, may also be operated based on the handover data. For example, a satellite that will provide service to the MUT after the handover may allocate communication resources such as timeslots, particular frequencies, and so forth for use by the MUT.

(20) By using the system and techniques described in this disclosure, disclosure of precision information about the whereabouts of an MUT is prevented while the ability to seamlessly handover communication service from one spot to another is maintained. As a result, operational security of the MUT may be substantially improved.

Illustrative System

(21) The ability to communicate between two or more locations that are physically separated provides substantial benefits. Communications over areas ranging from counties, states, continents, oceans, and the entire planet are used to enable a variety of activities including remote sensing, remote operation of devices, and so forth.

(22) Communications facilitated by electronics use electromagnetic signals, such as radio waves or light to send information over a distance. These electromagnetic signals have a maximum speed in a vacuum of 299,792,458 meters per second, known as the “speed of light” and abbreviated “c”. Electromagnetic signals may travel, or propagate, best when there is an unobstructed path between the antenna of the transmitter and the antenna of the receiver. This path may be referred to as a “line of sight”. While electromagnetic signals may bend or bounce, the ideal situation for communication is often a line of sight that is unobstructed. Electromagnetic signals will also experience some spreading or dispersion. Just as ripples in a pond will spread out, a radio signal or a spot of light from a laser will spread out at progressively larger distances.

(23) As height above ground increases, the area on the ground that is visible from that elevated point increases. For example, the higher you go in a building or on a mountain, the farther you can see. The same is true for the electromagnetic signals used to provide communication services. A relay station having a radio receiver and transmitter with their antennas placed high above the ground is able to “see” more ground and provide communication service to a larger area.

(24) There are limits to how tall a structure can be built and where. For example, it is not cost effective to build a 2000 meter tall tower in a remote area to provide communication service to a small number of users. However, if that relay station is placed on a satellite high in space, that satellite is able to “see” a large area, potentially providing communication services to many users across a large geographic area. In this situation, the cost of building and operating the satellite is distributed across many different users and becomes cost effective.

(25) A satellite may be maintained in space for months or years by placing it into orbit around the Earth. The movement of the satellite in orbit is directly related to the height above ground. For example, the greater the altitude the longer the period of time it takes for a satellite to complete a single orbit. A satellite in a geosynchronous orbit at an altitude of 35,800 km may appear to be fixed with respect to the ground because the period of the geosynchronous orbit matches the rotation of the Earth. In comparison, a satellite in a non-geosynchronous orbit (NGO) will appear to move with respect to the Earth. For example, a satellite in a circular orbit at 600 km will circle the Earth about every 96 minutes. To an observer on the ground, the satellite in the 600 km orbit will speed by, moving from horizon to horizon in a matter of minutes.

(26) Building, launching, and operating a satellite is costly. Traditionally, geosynchronous satellites have been used for broadcast and communication services because they appear stationary to users on or near the Earth and they can cover very large areas. This simplifies the equipment needed by a station on or near the ground to track the satellite.

(27) However, there are limits as to how many geosynchronous satellites may be provided. For example, the number of “slots” or orbital positions that can be occupied by geosynchronous satellites is limited due to technical requirements, regulations, treaties, and so forth. It is also costly in terms of fuel to place a satellite in such a high orbit, increasing the cost of launching the satellite.

(28) The high altitude of the geosynchronous satellite can introduce another problem when it comes to sharing electromagnetic spectrum. The geosynchronous satellite can “see” so much of the Earth that special antennas may be needed to focus radio signals to particular areas, such as a particular portion of a continent or ocean, to avoid interfering with radio services on the ground in other areas that are using the same radio frequencies. As a result, the “footprint” of a radio signal emitted from a geosynchronous satellite may cover a very large area of the Earth. For example, a relatively narrow beam from a geosynchronous satellite's antennas may cover several thousands of square kilometers of the Earth.

(29) Using a geosynchronous satellite to provide communication services also introduces a significant latency or delay because of the time it takes for a signal to travel up to the satellite in geosynchronous orbit and back down to a device on or near the ground. The latency due to signal propagation time of a single hop can be at least 240 milliseconds (ms). This latency can be unacceptable in situations where the data is time sensitive, such as for remote control of equipment or to provide near-realtime tracking data.

(30) To alleviate these and other issues, satellites in NGOs may be used. The altitude of an NGO is high enough to provide an individual satellite with a coverage of a relatively large portion of the ground, while remaining low enough to minimize latency due to signal propagation time. For example, the lower altitude of the satellite in NGO, compared to a geosynchronous orbit, provides coverage over a much smaller portion of the Earth. The lower altitude also reduces the distance the electromagnetic signal has to travel. For example, the satellite at 600 km only introduces 4 ms of latency for a single hop. Compared to the geosynchronous orbit, the reduced distance of the NGO reduces the dispersion of electromagnetic signals. As a result, the portion of the Earth that is

covered by a signal transmitted from the satellite in the NGO, or “footprint”, may be much smaller than that of a geosynchronous satellite. For example, a footprint of a signal transmitted by the antenna array of an NGO satellite may be tens of kilometers or smaller on a side, compared to the thousands of kilometers of a spot of an antenna array onboard a geosynchronous satellite. This allows the satellite in NGO as well as the device communicating with the satellite to use a less powerful transmitter, use smaller antennas, and so forth.

(31) The system **100** shown here comprises a plurality (or “constellation”) of communication satellites **102(1)**, **102(2)**, . . . , **102(S)**, each communication satellite **102** being in orbit **104**. Also shown is a ground station **106**, user terminals (UTs) **108**, and computing devices **110**. Each computing device **110** may execute one or more application modules **196**. For example, the application modules **196** may comprise email applications, telephony applications, videoconferencing applications, telemetry applications, remote sensing applications, telecontrol applications, and so forth.

(32) The constellation may comprise hundreds or thousands of satellites **102**, in various orbits **104**. For example, one or more of these satellites **102** may be in non-geosynchronous orbits (NGOs) in which they are in constant motion with respect to the Earth, such as a low earth orbit (LEO). In this illustration, orbit **104** is depicted with an arc pointed to the right. A first satellite (SAT1) **102(1)** is leading (ahead of) a second satellite (SAT2) **102(2)** in the orbit **104**.

(33) Each satellite **102** may include a link module **114** and resource scheduler **116**. The link module **114** is used to establish communication with other devices. The link module **114** may include one or more processors, transmitters, receivers, antennas, digital signal processors, and so forth. The resource scheduler **116** may comprise one or more processors executing instructions to manage the link module **114** and maintain communication service such as a radio communication link with other devices. For example, the resource scheduler **116** may receive requests for allocation of uplink resources from individual UTs **108**, determine grant data **194** allocating uplink resources to the requesting UTs **108**, send the grant data **194** to the requesting UTs **108**, receive and respond to a handover request **192**, and so forth. The resource scheduler **116** may also allocate downlink resources during operation. Operation of the resource schedulers **116** onboard a plurality of satellites **102** may also be responsive to handover requests **192** associated with one or more mobile UTs (MUTs) **108(M)** as described below. The satellite **102** is discussed in more detail with regard to FIG. 2.

(34) The resource scheduler **116** may determine resource allocation such as timeslot, frequency, and so forth that are allocated to particular spots. A spot may be associated with a particular geographic area and the communication resources allocated to that geographic area. In some implementations, the footprint of the spot may extend beyond, or may be within, the geographic area associated with that spot. For example, actual coverage of a signal transmitted by the satellite using the spot may extend beyond the edges of the geographic area.

(35) A ground segment of the system **100** may comprise one or more ground stations **106** that are in communication with one or more satellites **102**. The ground stations **106** may pass data between the satellites **102**, a management system **150**, networks **144** such as the Internet, and so forth. The ground stations **106** may be emplaced on land, on vehicles, at sea, and so forth. Each ground station **106** may comprise a communication system **140**. Each ground station **106** may use the communication system **140** to establish communication with one or more satellites **102**, other ground stations **106**, and so forth. The ground segment may include or utilize one or more communication networks **144**. For example, the ground station **106** may connect to a terrestrial fiber optic communication network **144**. The ground station **106** may act as a network gateway, passing data between the one or more communication networks **144** and the satellites **102**, between ground stations **106**, and so forth. Such data may be processed by the ground station **106** and communicated via the communication system **140**. The communication system **140** of a ground station **106** may include components similar to those of the communication system of a satellite

102 and may perform similar communication functionalities. For example, the communication system **140** may include one or more modems, digital signal processors, power amplifiers, antennas (including at least one antenna that implements multiple antenna elements, such as a phased antenna arrays), processors, memories, storage devices, communications peripherals, interface buses, and so forth.

(36) The ground stations **106** are in communication with a management system **150**. The management system **150** is also in communication, via the ground stations **106**, with the satellites **102** and the UTs **108**. The management system **150** coordinates operation of the satellites **102**, ground stations **106**, UTs **108**, and other resources of the system **100**. The management system **150** may comprise one or more of an orbital mechanics system **152** or a scheduling system **156**. The management system **150** may comprise one or more servers or other computing devices. In some implementations, the management system **150** may determine if a handover request **192** received from an MUT **108(M)** is valid, and responsive to that may provide handover data **164**. The management system **150** may send data to the associated satellites **102** to facilitate the handover.

(37) The orbital mechanics system **152** determines orbital data **154** that is indicative of a state of a particular satellite **102** at a specified time. In one implementation, the orbital mechanics system **152** may use orbital elements that represent characteristics of the orbit **104** of the satellites **102** in the constellation to determine the orbital data **154** that predicts position, velocity, and so forth of particular satellites **102** at particular times or time intervals. For example, the orbital mechanics system **152** may use data obtained from actual observations from tracking stations, data from the satellites **102**, scheduled maneuvers, and so forth to determine the orbital elements. The orbital mechanics system **152** may also consider other data, such as space weather, collision mitigation, orbital elements of known debris, and so forth.

(38) The scheduling system **156** schedules resources to provide communication to the UTs **108**. For example, the scheduling system **156** may determine handover data **164** that indicates when communication is to be transferred from a first spot to a second spot. An intrasatellite handover occurs when the first and second spots are provided by the same satellite **102**. An intersatellite handover occurs when the first and second spots are provided by different satellites. In implementations in which the MUT **108(M)** is operated in a self-triggered handover mode, the handover data **164** may be determined responsive to receipt of the handover request **192** from the MUT **108(M)**.

(39) The scheduling system **156** may also specify in the handover data **164** communication parameters such as frequency, timeslot indicative of when transmission is permitted, and so forth. During operation, the scheduling system **156** may use information such as the orbital data **154**, system status data **158**, user terminal data **160**, and so forth. In some implementations, the scheduling system **156** may implement one or more of the operations described with respect to the resource scheduler **116**. For example, responsive to a handover request **192** that is associated with an intrasatellite handover, the resource scheduler **116** of that satellite **102** may determine the handover data **164**.

(40) The system status data **158** may comprise information such as which UTs **108** are currently transferring data, satellite availability, current satellites **102** in use by respective UTs **108**, capacity available at particular ground stations **106**, and so forth. For example, the satellite availability may comprise information indicative of satellites **102** that are available to provide communication service or those satellites **102** that are unavailable for communication service. Continuing the example, a satellite **102** may be unavailable due to malfunction, previous tasking, maneuvering, and so forth. The system status data **158** may be indicative of past status, predictions of future status, and so forth. For example, the system status data **158** may include information such as projected data traffic for a specified interval of time based on previous transfers of data. In another example, the system status data **158** may be indicative of future status, such as a satellite **102** being unavailable to provide communication service due to scheduled maneuvering, scheduled

maintenance, scheduled decommissioning, and so forth.

(41) The user terminal data **160** may comprise information such as a geographic position (geolocation) of a particular UT **108** operating in a normal mode. This may comprise current position data or predicted position data. The current position data is associated with a first accuracy of the reported position relative to a ground truth or absolute position. For example, the current position data may comprise information about a particular MUT **108(M)** that is accurate (relative to the Earth) to less than a specified threshold, such as 100 meters. While operating in the self-triggered handover mode, the user terminal data **160** may be limited to information such as a current spot identifier indicative of the spot currently used to provide communication service to the MUT **108(M)**, distance data between the MUT **108(M)** and a specified reference point such as a center of a geographic area associated with a spot, received signal strength data (RSS) of a signal associated with one or more spots, and so forth. In some implementations, while operating in the self-triggered handover mode, the user terminal data **160** that is determined based on operation of the system **100** or based on information received from the MUT **108(M)** may be limited such that precise position of the MUT **108(M)** may not be derived.

(42) The user terminal data **160** may also include other information such as a current operating mode, priority assigned to data associated with that UT **108**, a type or category of UT that is indicative of the communication capabilities of that particular UT **108**, and so forth. For example, a first mobile UT **108(1)** may be a first category of device that has more powerful transmitters, backup power supply, and so forth and that is used on a search and rescue aircraft. Continuing the example, a second mobile UT **108(2)** may be in a second category of device, using less expensive and less powerful transmitters, omitting the backup power supply, and used on an uncrewed aerial vehicle. The user terminal data **160** may also include information such as a priority allocation associated with a particular UT **108**. For example, the first UT **108(1)** may be assigned a higher priority relative to the second UT **108(2)**. Over time, different versions, types, or categories of UTs **108** may be deployed, having different communication capabilities such as being able to operate at particular frequencies, supporting different signal encoding schemes, having different antenna configurations, and so forth.

(43) The handover data **164** is indicative of information such as a UT identifier indicative of a particular UT **108**, a handover time indicative of when a handover is to occur, a next satellite identifier (ID) that is indicative of the next satellite **102** that will be providing communication service to the specified UT **108**, and so forth. The handover data **164** facilitates an orderly transition of the UT **108** from a first satellite **102(1)** to a second satellite **102(2)**. In some implementations, the handover data **164** may be determined by the management system **150** responsive to current position data. For example, for fixed UTs **108** or MUTs **108(M)** operating in a normal mode that are providing or have provided current position data, the management system **150** may determine the handover data **164** without a handover request **192**. In implementations in which the self-triggered handover mode is used by the MUT **108(M)**, the management system **150** may determine the handover data **164** based on the handover request **192**. For example, responsive to the handover request, the management system **150** or another portion of the system **100** may determine the handover data **164** that is then provided to the requesting MUT **108(M)** and other associated devices such as the satellites **102** associated with the handover.

(44) While providing communication services to a first set of UTs **108** that may include an MUT **108(M)** operating in the self-triggered handover mode, the resource scheduler **116** of the first satellite **102(1)** manages access. This may include managing access by the first set of UTs **108** to one or more of an uplink or a downlink. This management may include, but is not limited to, allocating communication resources of the uplink to the individual UTs **108** in the first set of UTs **108**. For example, the first UT **108(1)** may request uplink resources to send 50 MB of data, while the MUT **108(M)** requests uplink resources to send 1 GB of data, and so forth.

(45) For UTs **108** operating in the normal mode, the scheduling system **156** may determine

handover data **164** at regular intervals. For example, handover data **164** may be generated for handover assessment intervals that are five seconds long. In other implementations, the handover data **164** may be determined on demand, at irregular intervals, and so forth. For example, for MUTs **108(M)** operating in the self-triggered handover mode, the scheduling system **156** may determine the handover data **164** responsive to a handover request **192**.

(46) In one implementation, the handover data **164** may involve the scheduling system **156** using the orbital data **154** and the geolocation of the UTs **108** to determine which UTs **108** will be moving out of range of the satellites **102** currently providing communication services to those UTs **108**. Based on the orbital data **154** and the geolocation of each UT **108**, the next satellite **102** may be determined. For example, this may be a satellite **102** that is already in range, or will be in range, at the handover time. In some implementations, the handover data **164** may include a set of next satellites **102**. For example, the handover data **164** may comprise a set of satellite IDs that indicate a primary satellite and a secondary satellite. Continuing the example, the second satellite **102(2)** may be designated as the primary satellite expected to begin providing communication service to the UT **108** at the handover time. In the event the satellite **102(2)** is unable to allocate resources to provide communication service to the UT **108**, exception data indicative of this may be generated and provided to one or more of the network management system **150**, a secondary satellite **102(3)**, the UT **108**, or other devices. For example, the second satellite **102(2)** may use a UT **108** to relay the exception data to the first satellite **102(1)** and the secondary satellite **102(3)**. The first satellite **102(1)** may send the exception data to the UT **108**. The secondary satellite **102(3)** may then allocate resources to provide communication service to the UT **108**, and may subsequently provide the communication service beginning at the handover time.

(47) The satellite **102** providing communication services may manage its uplink by providing grant data **194** to UTs **108**. The grant data **194** is indicative of one or more parameters associated with uplink communication between the UT **108** and the satellite **102**. For example, the grant data **194** may indicate the uplink frequency, downlink frequency, assigned timeslot, signal encoding, quantity of data permitted to be sent, and forth. In one implementation, the grant data **194** may be generated by the satellite **102**. For example, the satellite **102(1)** may receive uplink requests and responsive to those uplink requests send grant data **194**.

(48) The UT **108** includes a communication system **180** to establish communication with one or more satellites **102** and transfer data. The communication system **180** may comprise a network interface. The UT **108** passes data between the constellation of satellites **102** and the computing device **110**. The computing device **110** may execute one or more application modules **196**. The data transferred includes upstream data **112** sent by the computing device **110** or downstream data **142** that is addressed to the UT **108** or the computing device **110**. For example, during operation the application module **196** may send upstream data **112** and receive downstream data **142**. The upstream data **112** and the downstream data **142** each may comprise header data and payload data. The UT **108** may be fixed or in motion. For example, the UT **108** may be used at a residence, business, or on a vehicle such as a car, boat, aerostat, drone, airplane, remotely operated vehicle, uncrewed vehicle, and so forth.

(49) During operation, the communication system **180** may utilize one or more of the handover data **164** or the grant data **194** received from the satellite **102**. For example, the communication system **180** may use the handover data **164** that is received to perform a handover from a first spot to a second spot. In another example, the UT **108** may request uplink resources to send the upstream data **112**. Responsive to the request, the satellite **102** may send grant data **194** allocating uplink resources for the UT **108** to use to send the upstream data **112** to the satellite **102**.

(50) The communication system **180** of the UT **108** may include components similar to those of the communication system of a satellite **102** and may perform similar communication functionalities. For example, the communication system **180** may include one or more modems, digital signal processors, power amplifiers, antennas (including at least one antenna that implements multiple

antenna elements, such as a phased antenna array), processors, memories, storage devices, communications peripherals, interface buses, and so forth. Continuing the example, the network interface may comprise the communication system **180**.

(51) The communication system **180** of the UT **108** may also allow for operation in various modes such as a normal mode or the self-triggered handover mode. In some implementations, the mode used by the communication system **180** may be determined based on data received from the application module **196** or another control input. In other implementations, the mode used by the communication system **180** may be remotely configured, such as upon receiving a control message from the satellite **102** or the management system **150**. For example, to further obscure the presence and operation of a particular MUT **108(M)** operating in self-triggered handover mode, the management system **150** may remotely transition several other UTs **108** to operate in the self-triggered handover mode at the same time.

(52) The UT **108** includes a tracking system **182**. The tracking system **182** uses ephemeris data **184** to determine tracking data **186**. The ephemeris data **184** provides information indicative of orbital elements of the orbit **104** of one or more satellites **102**. For example, the ephemeris data **184** may comprise orbital elements such as “two-line element” data for the satellites **102** in the constellation that are broadcast or otherwise sent to the UTs **108** using the communication system **180**.

(53) The tracking system **182** may use the current position data indicative of the current position of the UT **108** with high accuracy and the ephemeris data **184** to determine the tracking data **186** for the satellite **102**. For example, based on the current position of the UT **108** and the predicted position and movement of the satellites **102**, the tracking system **182** is able to calculate the tracking data **186**. The tracking data **186** may include information indicative of azimuth, elevation, distance to the second satellite **102(2)**, time of flight correction, or other information associated with a specified time. The determination of the tracking data **186** may be ongoing. For example, the first UT **108** may determine tracking data **186** every 100 ms, every second, every five seconds, or at other intervals.

(54) With regard to FIG. **1**, the uplink is a communication link which allows data to be sent to a satellite **102** from a ground station **106**, UT **108**, or device other than another satellite **102**. Uplinks are designated as UL1, UL2, UL3 and so forth. For example, UL1 is a first uplink from the ground station **106** to the second satellite **102(2)**. In comparison, a downlink is a communication link which allows data to be sent from the satellite **102** to a ground station **106**, UT **108**, or device other than another satellite **102**. For example, DL1 is a first downlink from the second satellite **102(2)** to the ground station **106**.

(55) In some implementations, the satellites **102** may also be in communication with one another. For example, an intersatellite link (ISL) **198** may provide for communication between satellites **102** in the constellation. In some implementations, the ISL **198** may be used to exchange information between satellites **102** to determine handover data **164**, coordinate the handovers of an MUT **108(M)**, and so forth.

(56) The UT **108** may send upstream data **112** using the system **100**. For example, the upstream data **112** may originate from the UT **108**, or may be received by the UT **108** from the computing device **110**. The upstream data **112** may comprise a single packet or other unit of data transfer, or a plurality of packets or other units of data transfer. The upstream data **112** may be addressed to a device. The device that the upstream data **112** is addressed to may be accessible using one or more networks **144**, such as the Internet.

(57) The UT **108** may include a mobility management system **188** that utilizes state data **190** to determine handover requests **192**. The state data **190** comprises information about the state of the mobile UT **108**. For example, the state data **190** may comprise a current position as determined by a navigation system of the UT **108**, received signal strength of one or more spots, and so forth. The state data **190** is discussed in more detail with regard to FIG. **4**.

(58) In one implementation, the mobility management system **188** may determine, based on the

state data **190**, that the MUT **108(M)** will be moving from one spot to another, or would be better served by transitioning from one spot to another. Based on this determination, the mobility management system **188** may determine a handover request **192**. The handover request **192** is discussed in more detail with regard to FIG. 5. Operation of the mobility management system **188** is discussed in more detail with regard to FIGS. 6 and 7.

(59) The handover request **192** is then sent via the communication system **180** to other portions of the system **100**, such as the satellite **102** currently providing communication service, the management system **150**, and so forth. Responsive to the handover request **192**, the handover data **164** is received by the communication system **180** at the MUT **108(M)**. Responsive to the handover data **164**, the communication system **180** proceeds to establish communication at or after the handover time using the spot or other information provided by the handover data **164**.

(60) Ground stations **106** may have more substantial communication infrastructure, such as uplink transmitters with greater power than a UT **108**, antennas with greater gain than a UT **108**, sites that provide clear line of sight from horizon to horizon, and so forth. A ground station **106** may be in communication with a plurality of satellites **102** at a time. In some implementations, the ground station **106** may implement the resource scheduler **116** as described herein.

(61) The system **100** may include one or more point of presence (PoP) systems **146**. Each PoP system **146** may comprise one or more servers or other computing devices. Separate PoP systems **146** may be located at different locations. In one implementation, a PoP system **146** may be associated with providing service to a plurality of UTs **108** that are located in a particular geographic region.

(62) The PoP systems **146** may manage communication between the system **100** and the network **144**. For example, a first PoP system **146** may receive the upstream data **112** and send that upstream data **112** to the network **144**. In another example, the first PoP system **146** may receive the downstream data **142** and proceed to attempt delivery of the downstream data **142** to the UT **108**.

(63) The PoP system **146** is in communication with one or more ground stations **106(1)**, **106(2)**, . . . , **106(G)** and the management system **150**. In some implementations one or more functions may be combined. For example, the PoP system **146** may perform one or more functions of the management system **150**. In another example, the PoP system **146** may be included in an integrated ground station **106**.

(64) The PoP system **146** may determine the UT **108** that the downstream data **142** is addressed to and determine first communication resource data. The first communication resource data specifies the communication resources, such as the ground station **106**, uplink modem at the ground station **106**, satellite **102**, downlink modem on the satellite **102**, and so forth that would result in delivery of the downstream data **142** to the UT **108**. The downstream data **142** may comprise a single packet or other unit of data transfer, or a plurality of packets or other units of data transfer that are associated with delivery to the particular UT **108**.

(65) In some implementations, traffic associated with a particular UT **108**, such as an MUT **108(M)**, may be routed through a single network point, such as a master PoP, firewall, traffic shaper, and so forth. Downstream data **142** received via one or more ground stations **106** in different physical locations may be forwarded to a master PoP and processed before sending to the network **144**. This processing may include removing or replacing packet header data, reordering packets, and so forth. The processing may serve to remove information that would otherwise indicate one or more of the particular ground station **106** or PoP **146** that was used to receive the downstream data **142**.

(66) The satellite **102**, the ground station **106**, the user terminal **108**, the computing device **110**, the management system **150**, the PoP system **146**, or other systems described herein may include one or more computer devices or computer systems comprising one or more hardware processors, computer-readable storage media, and so forth. For example, the hardware processors may include

application specific integrated circuits (ASICs), field-programmable gate arrays (FPGAs), digital signal processors (DSPs), and so forth. Embodiments may be provided as a software program or computer program including a non-transitory computer-readable storage medium having stored thereon instructions (in compressed or uncompressed form) that may be used to program a computer (or other electronic device) to perform the processes or methods described herein. The computer-readable storage medium may be one or more of an electronic storage medium, a magnetic storage medium, an optical storage medium, a quantum storage medium, and so forth. For example, the computer-readable storage medium may include, but is not limited to, hard drives, optical disks, read-only memories (ROMs), random access memories (RAMs), erasable programmable ROMs (EPROMs), electrically erasable programmable ROMs (EEPROMs), flash memory, magnetic or optical cards, solid-state memory devices, or other types of physical media suitable for storing electronic instructions. Further embodiments may also be provided as a computer program product including a transitory machine-readable signal (in compressed or uncompressed form). Examples of transitory machine-readable signals, whether modulated using a carrier or unmodulated, include, but are not limited to, signals that a computer system or machine hosting or running a computer program can be configured to access, including signals transferred by one or more networks **144**. For example, the transitory machine-readable signal may comprise transmission of software by the Internet.

(67) FIG. **2** is a block diagram **200** of some systems associated with the satellite **102**, according to some implementations. The satellite **102** may comprise a structural system **202**, a control system **204**, a power system **206**, a maneuvering system **208**, one or more sensors **210**, and a communication system **212**. A pulse per second (PPS) system **214** may be used to provide timing reference to the systems onboard the satellite **102**. One or more buses **216** may be used to transfer data between the systems onboard the satellite **102**. In some implementations, redundant buses **216** may be provided. The buses **216** may include, but are not limited to, data buses such as Controller Area Network Flexible Data Rate (CAN FD), Ethernet, Serial Peripheral Interface (SPI), and so forth. In some implementations the buses **216** may carry other signals. For example, a radio frequency bus may comprise coaxial cable, waveguides, and so forth to transfer radio signals from one part of the satellite **102** to another. In other implementations, some systems may be omitted or other systems added. One or more of these systems may be communicatively coupled with one another in various combinations.

(68) The structural system **202** comprises one or more structural elements to support operation of the satellite **102**. For example, the structural system **202** may include trusses, struts, panels, and so forth. The components of other systems may be affixed to, or housed by, the structural system **202**. For example, the structural system **202** may provide mechanical mounting and support for solar panels in the power system **206**. The structural system **202** may also provide for thermal control to maintain components of the satellite **102** within operational temperature ranges. For example, the structural system **202** may include louvers, heat sinks, radiators, and so forth.

(69) The control system **204** provides various services, such as operating the onboard systems, resource management, providing telemetry, processing commands, and so forth. For example, the control system **204** may direct operation of the communication system **212**. The control system **204** may include one or more flight control processors **220**. The flight control processors **220** may comprise one or more processors, FPGAs, and so forth. A tracking, telemetry, and control (TTC) system **222** may include one or more processors, radios, and so forth. For example, the TTC system **222** may comprise a dedicated radio transmitter and receiver to receive commands from a ground station **106**, send telemetry to the ground station **106**, and so forth. A power management and distribution (PMAD) system **224** may direct operation of the power system **206**, control distribution of power to the systems of the satellite **102**, control battery **234** charging, and so forth.

(70) The power system **206** provides electrical power for operation of the components onboard the satellite **102**. The power system **206** may include components to generate electrical energy. For

example, the power system **206** may comprise one or more photovoltaic arrays **230** comprising a plurality of photovoltaic cells, thermoelectric devices, fuel cells, and so forth. One or more PV array actuators **232** may be used to change the orientation of the photovoltaic array(s) **230** relative to the satellite **102**. For example, the PV array actuator **232** may comprise a motor. The power system **206** may include components to store electrical energy. For example, the power system **206** may comprise one or more batteries **234**, fuel cells, and so forth.

(71) The maneuvering system **208** maintains the satellite **102** in one or more of a specified orientation or orbit **104**. For example, the maneuvering system **208** may stabilize the satellite **102** with respect to one or more axes. In another example, the maneuvering system **208** may move the satellite **102** to a specified orbit **104**. The maneuvering system **208** may include one or more of reaction wheel(s) **240**, thrusters **242**, magnetic torque rods **244**, solar sails, drag devices, and so forth. The thrusters **242** may include, but are not limited to, cold gas thrusters, hypergolic thrusters, solid-fuel thrusters, ion thrusters, arcjet thrusters, electrothermal thrusters, and so forth. During operation, the thrusters **242** may expend propellant. For example, an electrothermal thruster may use water as propellant, using electrical power obtained from the power system **206** to expel the water and produce thrust. During operation, the maneuvering system **208** may use data obtained from one or more of the sensors **210**.

(72) The satellite **102** includes one or more sensors **210**. The sensors **210** may include one or more engineering cameras **250**. For example, an engineering camera **250** may be mounted on the satellite **102** to provide images of at least a portion of the photovoltaic array **230**. Accelerometers **252** provide information about acceleration of the satellite **102** along one or more axes. Gyroscopes **254** provide information about rotation of the satellite **102** with respect to one or more axes. The sensors **210** may include a global navigation satellite system (GNSS) **256** receiver, such as a Global Positioning System (GPS) receiver, to provide information about the position of the satellite **102** relative to Earth. In some implementations, the GNSS **256** may also provide information indicative of velocity, orientation, and so forth. One or more star trackers **258** may be used to determine an orientation of the satellite **102**. A coarse sun sensor **260** may be used to detect the sun, provide information on the relative position of the sun with respect to the satellite **102**, and so forth. The satellite **102** may include other sensors **210** as well. For example, the satellite **102** may include a horizon detector, radar, lidar, and so forth.

(73) The communication system **212** provides communication with one or more other devices, such as other satellites **102**, ground stations **106**, user terminals **108**, and so forth. The communication system **212** may comprise one or more processors **292** to execute instructions. The communication system **212** may comprise the link module **114** and the resource scheduler **116**. In one implementation, the link module **114** may comprise an antenna **282** such as a phased antenna array (PAA) that is capable of simultaneously providing multiple subbeams or gain patterns in different directions. A spot may comprise a particular subbeam that is targeted to cover a specified portion of the Earth (including the airspace above that portion) (see FIG. 3) while the satellite **102** is in a particular portion of the orbit **104**. In one implementation, the link module **114** may adjust or steer the direction of the subbeam relative to the satellite **102** to keep the subbeam pointed at a target location on the Earth while the satellite **102** is above the horizon and in range of that target location. As the satellite **102** moves out of range of the target location, the subbeam may be retargeted to another target location that is moving into range. The different subbeams on the satellite **102** may be directed to different spots. In another implementation, the subbeam may continuously sweep across the surface of the Earth, such as in a line parallel to a ground track of the satellite **102**.

(74) The communication system **212** may include one or more modems **276**, digital signal processors, power amplifiers, antennas (including at least one antenna that implements multiple antenna elements, such as a phased antenna array) **282**, processors **292**, memories, storage devices, communications peripherals, interface buses **216**, and so forth. Such components support

communications with other satellites **102**, ground stations **106**, user terminals **108**, and so forth using radio frequencies within a desired frequency spectrum. The communications may involve multiplexing, encoding, and compressing data to be transmitted, modulating the data to a desired radio frequency, and amplifying it for transmission. The communications may also involve demodulating received signals and performing any necessary de-multiplexing, decoding, decompressing, error correction, and formatting of the signals. Data decoded by the communication system **212** may be output to other systems, such as to the control system **204**, for further processing. Output from a system, such as the control system **204**, may be provided to the communication system **212** for transmission. The modems **276** operate in conjunction with other components, such as receivers, transmitters, and one or more antennas **282** to one or more of send or receive data.

(75) Each satellite **102** may use one or more antennas **282** or antenna elements to provide a beam for transmission and reception of radio signals. For example, the satellite **102** may have a phased antenna array that allows for gain in a particular direction, producing an antenna gain pattern. Compared to a non-directional radiator, this gain directs the energy of transmitted radio frequency signals in that particular direction. This increases the strength of the signal at a receiver in the UT **108**, ground station **106**, and so forth. Likewise, the gain results in improved received signal strength at the satellite **102**.

(76) The beam provided by the satellite **102** may comprise a plurality of subbeams. Subbeams on a satellite **102** may use different frequencies, timeslots, and so forth, to communicate with the UT **108**. Each subbeam provides coverage of a particular spot comprising a geographic area. Compared to a single beam, subbeams provide several advantages. For example, by using subbeams, radio frequencies may be reused by the same satellite **102** and other satellites **102** to service different areas. This allows increased density of UTs **108** and bandwidth.

(77) During a pass over of a particular location on the Earth, each subbeam may be targeted to a geographic location on the Earth. While that target spot is in range of the satellite **102**, the subbeam tracks the target spot. As the satellite **102** moves in orbit **104**, the boundary of the footprint of the subbeam on the surface changes due to the relative angle between the satellite **102** and the Earth. For example, the footprint boundary of the subbeam may change from approximately an oval shape while the satellite **102** is low on the horizon relative to the target location, to a circular shape while directly overhead, then to an oval shape as the satellite **102** nears the opposite horizon. As the satellite **102** moves, a subbeam may be retargeted to another target location. In this configuration, instead of the subbeam sweeping along the ground track of the satellite **102**, the subbeam loiters on a first area relative to the Earth, then is redirected to a second area.

(78) In some implementations, a particular modem **276** or set of modems **276** may be allocated to a particular subbeam and the corresponding spot. For example, a first modem **276(1)** provides communication to UTs **108** in a first spot using a first subbeam while a second modem **276(2)** provides communication to UTs **108** in a second spot using a second subbeam.

(79) In some implementations, the communication system **212** may include hardware to support the intersatellite link **198**. For example, an intersatellite link FPGA **270** may be used to modulate data that is sent and received by an ISL transceiver **272** to send data between satellites **102**. The ISL transceiver **272** may operate using radio frequencies, optical frequencies, and so forth.

(80) A communication FPGA **274** may be used to facilitate communication between the satellite **102** and the ground stations **106**, UTs **108**, and so forth. For example, the communication FPGA **274** may direct operation of a modem **276** to modulate signals sent using a downlink transmitter **278** and demodulate signals received using an uplink receiver **280**. The satellite **102** may include one or more antennas **282**. For example, one or more parabolic antennas may be used to provide communication between the satellite **102** and one or more ground stations **106**. In another example, a phased antenna array may be used to provide communication between the satellite **102** and the UTs **108**.

(81) The communication system **212** may determine one or more of handover data **164** or grant data **194**. For example, the handover data **164** may be determined by the communication system **212** for an intrasatellite handover that specifies the spot to handover to and parameters associated with using that spot. In another example, the grant data **194** may be determined that specifies uplink resources for a UT **108** to communicate with the satellite **102**. For example, the communication FPGA **274** may process a grant request that is received from a UT **108** by the uplink receiver **280**. Responsive to the grant request, and subject to the resource scheduler **116**, the communications FPGA **274** may determine grant data **194** that is then sent using the downlink transmitter **278**. In another example, the resource scheduler **116** may determine grant data **194** without a grant request.

(82) FIG. 3 illustrates at **300** spots providing communication service to a mobile user terminal **108(M)** and an intrasatellite handover **302** and an intersatellite handover **304**, according to some implementations. A UT current position **306** is shown, depicting the geographic position or geolocation of the MUT **108(M)**. The UT current position **306** is within a current spot **318**. A destination spot **320** may be designated as the spot **310** that the UT **108** has either moved into, or is predicted to move into at a future time.

(83) An intrasatellite handover **302** is shown in which communication service provided to an MUT **108(M)** transitions from a first spot **310** to a second spot **310** provided by the same satellite **102**. The relative position of the spots **310** with respect to one another and the satellite **102** are also shown.

(84) A spot **310** may comprise one or more of a spatial location, geographic area **312**, communication resources (not shown) allocated to provide communication within and near the geographic area **312**, and signal footprint **314** associated with those communication resources. For example, the spatial location may comprise a portion of an orbit **104**, a geographic area may comprise a specified area on Earth, and so forth. In the implementation depicted here, the spot **310** may comprise a geographic area **312** on the Earth and the airspace or volume corresponding with that geographic area **312**. One or more UTs **108** may be present within one or more spots **310**.

(85) The geographic areas **312** associated with the spots **310(1)**, **310(2)**, . . . , **310(S)** may be arranged to cover at least a portion of a surface, physical area such as a portion of the sky, and so forth. For example, the Earth may be tessellated into geographic areas **312** that are hexagonal or some other space filling polygon arrangement. In some implementations, the geographic areas **312** of the spot **310** may be sized to correspond to the signal footprint **314** of a subbeam. For example, the spot **310** may be based on the signal footprint **314** or area on the surface of the Earth that corresponds to signal coverage at a specified metric such as signal to noise level or received power of an uplink subbeam and a downlink subbeam. In implementations in which the spots **310** are directed towards space, each spot **310** is associated with a respective physical area such as a solid angle of the sky, portion of an orbit **104**, and so forth.

(86) The geographic areas **312** associated with respective spots **310** may be tessellated and non-overlapping. In comparison, the signal footprint **314** covered by the respective communication resources may differ from the boundaries of those geographic areas **312**. For example, given the parameters of communication resources such as antenna gain, frequency, transmit power levels, co-channel interference, and so forth, signal coverage may extend beyond the edges of the respective geographic area **312**. In another example, terrain such as high mountains may “shadow” or block coverage and reduce signal coverage to within the edges of the respective geographic area. In this illustration, the signal footprints **314** for some of the spots **310** are depicted. Others are omitted for clarity of illustration and not as a limitation. Near the edges of a geographic area **312** a UT **108** may be within two or more signal footprints **314** associated with different spots **310**.

(87) Each of the geographic areas **312** or the signal footprints **314** may be associated with one or more points. For example, each of the geographic areas **312** has a corresponding spot geometric center **316**. In another example, each signal footprint **314** may have a corresponding footprint

center (not shown).

(88) In some implementations, the handover request **192** may be indicative of the approximate location of the MUT **108(M)** as a distance relative to one or more of points, spot identifier, and so forth. For example, the handover request **192** may indicate a distance between the UT current position **306** and the spot geometric center **316(1)** of the current spot **318**, a distance between the UT current position **306** and the spot geometric center **316(3)** of the destination spot **320**, and so forth.

(89) By way of illustration, and not as a limitation, the MUT **108(M)** is shown at a geographic location that is within the spot **310(1)**. Each satellite **102** may provide communication services in a plurality of spots **310**. In this illustration satellite **102(1)** provides coverage in spots **310(1)**, **310(2)**, and **310(3)**. In comparison satellite **102(2)** provides coverage in spots **310(4)** and **310(8)**. The number and distribution of spots **310** is for illustration only, and is not provided as a limitation.

(90) While operating in the normal mode, the MUT **108(M)** may provide data that is indicative of a geolocation of the MUT **108(M)** with a relatively high accuracy, such as the UT current position **306** data. While in the normal mode, the system **100** allocates communication resources to the current spot **310** that the MUT **108(M)** is located within. As shown here, a single satellite **102(1)** that is providing service to spot **310(1)** at this time is used to send downstream data **142** and is also providing grant data **194** and associated uplink resources to the MUT **108(M)**. As the MUT **108(M)** operating in normal mode moves, the management system **150** uses the information about the movement to anticipate a handover and determine handover data **164**. As a result, the operation of the system **100** is highly efficient.

(91) In comparison, while in the self-triggered handover mode, the handover data **164** is determined responsive to the handover request **192** received from the MUT **108(M)**. While this may result in a slight reduction in the efficiency of the system **100**, it provides a substantial reduction in the amount of information about the position of the MUT **108(M)** that is available to the system **100** or a third party. For example, the management system **150** may only maintain user terminal data **160** that is indicative of the MUT **108(M)** being provided service by a particular spot **310**.

(92) With regard to the intrasatellite handover **302**, the MUT **108(M)** will be moving from spot **310(1)** to spot **310(3)**. Because both spot **310(1)** and spot **310(3)** are provided by the same satellite, satellite **102(1)**, this is an intrasatellite handover.

(93) In one implementation, a handover request **192** that involves an intrasatellite handover **302** may be responded to by the resource scheduler **116** or other system operating on the serving satellite **102** that is providing the spots **310**. In this implementation, the serving satellite **102** may determine and send the handover data **164** to the MUT **108(M)**.

(94) In comparison, with regard to the intersatellite handover **304**, the MUT **108(M)** will be moving from spot **310(3)** to spot **310(4)**. Spot **310(4)** is provided by a different satellite, satellite **102(2)**. Because spot **310(3)** and **310(4)** are provided by the different satellites, satellite **102(1)** and satellite **102(2)** respectively, this is an intersatellite handover.

(95) In one implementation, a handover request **192** that involves an intersatellite handover **304** may be forwarded to the management system **150** for determination of the handover data **164**.

(96) During operation, the MUT **108(M)** may determine state data **190** that is indicative of received signal strength (RSS) of signals associated with respective spots **310** in a set of one or more spots **310**. The set of spots may include the current spot **318** and one or more adjacent spots **310**, such as the destination spot **320**.

(97) The communication system **180** may utilize a directional antenna, such as a phased array antenna. The directional antenna may be operated to direct a receive or transmit pattern towards a particular satellite **102** at a particular time. Depending upon the construction and configuration, the directional antenna may exhibit some delay or latency when changing from pointing in a first direction to pointing in a second direction. For example, a mechanically steered parabolic antenna

or log periodic array will require some time to move from a first direction aimed at the first satellite **102(1)** to a second direction aimed at the second satellite **102(2)**.

(98) In some implementations, to minimize the latency associated with repointing the directional antenna, the MUT **108(M)** may acquire RSS information for signals associated with spots **310** that are provided by a single satellite **102** serving the current spot **318**. For example, as shown in FIG. 3 the MUT **108(M)** may acquire RSS information for spots **310(1)**, **310(2)**, and **310(3)** that are provided by the first satellite **102(1)**. Continuing the example, attempting to repoint the directional antenna to acquire RSS data about signals associated with spots **310(4)** and **310(8)** that are provided by the second satellite **102(2)** may result in latencies that are too long, and may interfere with ongoing communication between the MUT **108(M)** and the first satellite **102(1)** using the current spot **318**.

(99) In implementations in which the latency associated with repointing the directional antenna is minimal or can be accommodated, the MUT **108(M)** may acquire RSS information for spots **310** provided by a plurality of satellites **102**. For example, if the directional antenna comprises digital beamformers that allows for two different pointing directions to be accommodated simultaneously, the RSS information may be obtained for spots **310** associated with two or more satellites **102**. Continuing the example, one pointing direction may be used to maintain ongoing communication with the current spot **318** while obtaining RSS information for others spots **310** provided by the serving satellite **102**. The second pointing direction may be used to obtain RSS information for other spots **310** provided by other satellites **102**.

(100) By way of illustration, and not as a limitation, each satellite **102** is depicted as serving a particular spot **310** at the time shown. It is understood that a satellite **102** may provide a plurality of spots **310** during a particular time interval. For example, satellite **102(2)** may provide communication services to spots **310(1)-(7)** while satellite **102(2)** provides communication services to spots **310(8)-(15)** and so forth. It is also understood that different satellites **102** may service the same or different spots **310** at the same or different times. For example, satellite **102(1)** and satellite **102(2)** may provide service to spot **310(3)** during the same time interval. This redundancy in coverage may be provided for reasons including, but not limited to, providing disparity of path to allow for reliable communication due to obstacles local to the UT **108** such as a mountain or building, to mitigate radio frequency interference, and so forth.

(101) FIG. 4 illustrates at **400** state data **190** and spot data **450** that may be used to determine a handover request **192**, according to some implementations. During operation the UT **108** may determine state data **190**. The state data **190** may be updated on a regular schedule, on demand, or a combination thereof. For example, the state data **190** may be updated every 100 ms, or upon occurrence of an interrupt. The mobility management system **188** uses at least a portion of the state data **190** during operation to determine the handover request **192**.

(102) The state data **190** may comprise a timestamp **402** indicative of a time associated with the state data **190**. In some implementations, individual values **408** may be associated with respective individual timestamps **402**.

(103) The state data **190** may comprise a UT identifier **404** that is indicative of the UT **108**. For example, the UT identifier **404** may comprise a serial number assigned at manufacture.

(104) The state data **190** may comprise one or more parameters **406** and associated values **408**. The parameters **406** may include one or more of the following. In some implementations the state data **190** may comprise, or the mobility management system **188** may utilize, a subset of the available parameters **406**.

(105) A current position may be indicative of a geolocation of the UT **108** with respect to a specified datum. The current position may be determined based on output from a navigational system. For example, a GNSS may comprise a GPS receiver that provides the current latitude and longitude of the UT **108**. In another example the navigational system may utilize dead reckoning or inertial navigation to determine the current position.

(106) A current altitude may be indicative of an altitude of the UT **108** with respect to a specified datum. For example, the current altitude may be determined based on output from a barometric altimeter, radar altimeter, laser altimeter, GNSS receiver, or other device. In another example dead reckoning or inertial navigation may be used to determine the current altitude.

(107) A current heading is indicative of a direction, relative to a reference direction such as true north, of the UT **108**. For example, the current heading may be determined based on output from a magnetic compass, GNSS receiver, inertial navigation system, or other device.

(108) A current speed is indicative of a speed, relative to a reference datum, of the UT **108**. For example, the current speed may be determined based on output from a pitot system, GNSS receiver, inertial navigation system, or other device.

(109) A predicted position is indicative of a predicted geolocation of the UT **108** at a future time. For example, the predicted position may be indicative of a predicted geolocation of the UT **108** at a next handover interval. In some implementations, the predicted position may be calculated based on the current position, current heading, and current speed. In other implementations, the predicted position may be determined based on this or other information, such as a flight plan, sailing plan, set of waypoints indicative of a planned route, and so forth.

(110) A predicted altitude is indicative of a predicted altitude of the UT **108** at a future time. This may be determined similar to that of the predicted position.

(111) A current spot identifier (ID) is indicative of the current spot **318** that is currently providing service to the UT **108**.

(112) A current spot RSS indicates a received signal strength of a signal associated with the current spot **318**. For example, the current spot RSS may be indicative of a received signal strength of a broadcast transmission associated with the current spot **318**.

(113) The state data **190** may include one or more adjacent spot IDs and associated RSS values. In some implementations, the mobility management system **188** may determine a set of spots **310** comprising at least a portion of the spots **310** that are adjacent to the current spot **318**. The set of spots **310** may include the destination spot **320**. The mobility management system **188** may determine the destination spot **320** based on the predicted position. For example, the destination spot **320** may comprise the spot **310** that the predicted position is within.

(114) As described above with regard to FIG. 3, the MUT **108(M)** may acquire RSS information for other spots **310**. This RSS information may be included in the state data **190**.

(115) The mobility management system **188** may use spot data **450** during operation. The spot data **450** may comprise information about one or more of the spots **310**. In one implementation, the spot data **450** may comprise information about the geographic areas **312** associated with respective spots **310**. The spot data **450** may comprise a spot ID and associated information such as a spot geometric center **316** and coordinates indicative of the geolocation of the geographic area **312**. The spot data **450** may comprise other information such as a spot shape, radius, length, width, or other dimensional information.

(116) FIG. 5 illustrates at **500** the handover request **192**, the handover data **164**, and the grant data **194**, according to some implementations. As described below with regard to FIG. 6, based on the state data **190** the mobility management system **188** determines the handover request **192**. While operating in the self-triggered handover mode, the handover request **192** is then sent to other elements of the system **100**, such as the satellite **102** providing the current spot **318**, which may then be sent to the management system **150**.

(117) The handover request **192** may comprise one or more parameters **502** and associated values **504**. The parameters **504** may include one or more of the following. In some implementations, the handover request **192** may comprise, or the other elements of the system **100** may utilize, a subset of the parameters **502** shown here or otherwise available.

(118) The UT identifier, as with the UT identifier **404** described above, is indicative of the UT **108** that has issued the handover request **192**. In some implementations this data may be provided in a

separate data element, such as in a packet header.

(119) The mobility management system **118** may determine the destination spot **320**. This may be determined based on one or more of the predicted position or the RSS information. The handover request **192** may comprise a primary destination spot ID that is indicative of the destination spot **320**. In some situations, the management system **150** may disregard this information, and provide handover data **164** indicative of a different spot **310**.

(120) The handover request **192** may comprise information indicative of one or more distances from a position of the UT **108** to one or more specified points. The position may be the current position or the predicted position. The point may be specified with respect to the spot **310**, such as the spot geometric center **316**, a particular vertex of the geographic area **312**, and so forth.

(121) A distance from the UT current position **306** or the predicted position to the current spot (geometric) center **316** may be included in the handover request **192**.

(122) A distance from the UT current position **306** or the predicted position to the destination spot (geometric) center **316** may be included in the handover request **192**.

(123) In some implementations information about additional spots may be included in the handover request **192**. For example, information about other adjacent spots **310** such as a secondary destination spot ID indicative of an alternative destination spot **310** may be included. Distance information associated with this secondary destination spot may also be included.

(124) Current spot **318** received signal strength (RSS) may comprise information indicative of a signal strength, as received by the MUT **108(M)**, of a signal associated with the current spot **318**.

(125) The handover request **192** may also include RSS data associated with other spots, such as the primary destination spot, the secondary destination spot, and so forth.

(126) In some implementations, particular combinations of information may be avoided in the handover request **192** that is sent. For example, to avoid revealing information that may be used to derive the position of the UT **108**, the handover request **192** may omit including more than one distance to a specified point, RSS information from more than one spot, and so forth.

(127) In some implementations, the values **504** included in the handover request **192** may be indicative of a ranking rather than a particular measurement. For example, instead of providing linear measurements such as kilometers in the distances, the distances may be ranked in ascending order of lowest to greatest distance. Continuing the example shown the “distance to destination spot center” may have a value **504** of rank “1”, while “distance to current spot center” has a value **504** of rank “2”, and “distance to secondary destination spot center” has a value **504** of rank “3”. Likewise, the RSS values may be ranked in descending order of greatest to lowest received signal strength. With this example, “primary destination spot RSS” has a value **504** of rank “1”, “current spot RSS” has a value **504** of rank “2”, and so forth.

(128) In one implementation, a set of spots that are adjacent to the current spot may be determined. The handover request **192** may include values **504** indicative of one or more of a first set of rank values or a second set of rank values. The first set of rank values may be determined by the UT **108**. Each rank value in the first set of rank values may be indicative of a distance from the UT **108** to a point associated with respective ones of the set of spots. The second set of rank values may be determined by the UT **108**. Each rank value in the second set of rank values may be indicative of a received signal strength of a received signal associated with the respective one of the set of spots.

(129) The handover data **164** may comprise one or more parameters **542** and associated values **544**. The parameters **542** may include one or more of the following. In some implementations the handover data **164** may comprise a subset of the parameters **542** shown here.

(130) The UT identifier, as with the UT identifier **404** described above, is indicative of the UT **108** that has issued the handover request **192**. In some implementations this data may be provided in a separate data element, such as in a packet header.

(131) A handover time is indicative of the time when the handover is to occur.

(132) A next satellite ID is indicative of the next satellite that will be providing the next spot **310**

after the handover time. In the case of an intrasatellite handover, there may be no change in satellite **102** after the handover.

(133) A next spot ID is indicative of the next spot **310** that will be providing service to the MUT **108(M)** after the handover time.

(134) Other information such as data indicative of a particular subbeam, random access channel allocation, cryptographic credentials such as a spot cryptographic key associated with the next spot **310**, broadcast channel associated with the destination spot **310**, and so forth may be included in the handover data **164**.

(135) The grant data **194** may comprise one or more parameters **562** and associated values **564**. The parameters **562** may include one or more of the following. In some implementations the grant data **194** may comprise a subset of the parameters **562** shown here. During operation, the communication system **180** may use the grant data **194** to send upstream data **112**, receive downstream data **142**, and so forth.

(136) The UT identifier, as with the UT identifier **404** described above, is indicative of the UT **108** that has issued the handover request **192**. In some implementations this data may be provided in a separate data element, such as in a packet header.

(137) In some implementations a temporary UT identifier may be used. A temporary UT identifier may be assigned to a particular UT **108** within a particular spot **310**. If that same UT **108** transfers to use a different spot **310** or subbeam therein, a different temporary UT identifier would be issued. For example, the UT **108** having the UT identifier of “568451998873” may be assigned a first temporary UT ID of “15” while using spot **310(1)** and then assigned a second temporary UT ID of “3” while using spot **310(2)**. Use of the temporary UT identifier may reduce the quantity of data transmitted. For example, instead of a 64 byte UT identifier a 4 bit value may be used.

(138) The satellite Id is indicative of the satellite **102** providing the spot **310**.

(139) A next handover time may indicate the next time a handover may occur.

(140) The synchronization data provides information to the UT **108** about the time synchronization signal used to synchronize the UT **108** with the spot **310** or a subbeam thereof. For example, the synchronization data may indicate a frequency, encoding, or other parameter to allow the UT **108** to determine the time synchronization to be used.

(141) The subbeam identifier provides information about the subbeam to be made available to the UT **108** for use.

(142) The grant data **194** may include uplink frequencies for use by the UT **108** to send to the satellite **102** while the downlink frequencies are for use by the UT **108** to receive from the satellite **102**.

(143) The timeslot may indicate an interval of time during which communication between the UT **108** and the satellite **102** is allocated to take place. The timing of a timeslot may be relative to the time synchronization signal. For example, each second may be divided into ten 100 ms timeslots. The first UT **108** may be allocated to send and receive traffic during the fifth timeslot, while other UTs **108** are allocated the remaining time slots for use.

(144) A grant expiration time may be indicative of when the grant data **194** is no longer valid. In other implementations, the grant data **194** may comprise additional information.

(145) FIG. 6 depicts at **600** a flow diagram of a process to handover provisioning of communication service to a mobile UT **108(M)** from a first spot **310(1)** to a second spot **310(2)**, according to some implementations. The process may be implemented by one or more satellites **102**, ground stations **106**, user terminals **108**, the management system **150**, and so forth. This process is associated with the self-triggered handover mode in which the UT **108** does not provide precise information about its current position to the system **100**.

(146) At **602** state data **190** associated with a mobile UT **108(M)** is determined. The MUT **108(M)** is located in a first spot **310(1)** at a first time. For example, the MUT **108(M)** may be within the geographic area **312** of the current spot **318**, may be within the signal footprint **314** of the current

spot, or both. The state data **190** may be determined by one or more systems of the MUT **108(M)**. For example, the mobility management system **188** may determine the state data **190** or receive portions thereof from other systems.

(147) At **604** a handover request **192** is determined based at least in part on the state data **190**. For example, the mobility management system **188** may determine the handover request **192**. In some implementations, the determination of the handover request **192** may be based on geometry, received signal strength, or a combination thereof. One implementation of this determination is described below with regard to operations **620-634**.

(148) At **606** the handover request **192** is sent. For example, the mobility management system **188** may send the handover request **192** to the communication system **180**. The communication system **180** may then send the handover request **192** to the serving satellite **102** using a transmitter coupled to an antenna.

(149) At **608** handover data **164** is received. For example, the communication system **180** may comprise a receiver coupled to the antenna that is used to receive the signal conveying the handover data **164**. The handover data **164** is indicative of a second spot **310(2)** that will provide communication service to the MUT **108(M)** at or after a handover time.

(150) At **610** communication is established based on the handover data **164**. For example, the communication system **180** may use the handover data **164** to transition at or after the handover time from using the first spot **310(1)** to using the second spot **310(2)**.

(151) Returning to **604**, the handover request **192** may be determined based on the state data **190**. Information about the geometry of the MUT **108(M)** relative to one or more geographic areas **312** may be assessed to determine if the MUT **108(M)** has moved from a geographic area **312(1)** of a first spot **310(1)** into a geographic area **312(2)** of a second spot **310(2)**.

(152) At **620** a first distance is determined from a position of the UT **108** to a first point in the first spot **310(1)**. The position may be a UT current position **306** or a predicted position. In one implementation, the first point may comprise a geometric center of one or more of a geographic area **312**, or a signal footprint **314**. In other implementations, other points may be specified, such as a northwestern most vertex of each hexagon of the geographic area **312**.

(153) At **622** a second distance is determined from the position of the UT **108** to a second point in a second spot **310(2)**. The position may be a UT current position **306** or a predicted position. In one implementation, the second point may comprise a geometric center of one or more of a geographic area **312**, or a signal footprint **314**. In other implementations other points may be specified.

(154) At **624** a determination is made as to whether the first distance is greater than the second distance. If yes, the process may proceed to **626**. In another implementation not shown, if yes the process may conclude and utilize the second spot **310(2)** as the destination spot **320**. If at **624** the determination is no, the process may proceed to **634**.

(155) At **626** a first received signal strength (RSS) of a first signal associated with the first spot **310(1)** is determined. For example, the RSS of a beacon transmission of the first spot **310(1)** may be acquired using the receiver of the MUT **108(M)**.

(156) At **628** a second RSS of a second signal associated with the second spot **310(2)** is determined. For example, the RSS of a beacon transmission of the second spot **310(2)** may be acquired using the receiver of the MUT **108(M)**.

(157) At **630** a determination is made as to whether the first RSS is less than the second RSS. If yes, the process may proceed to **632**. If at **630** the determination is no, the process may proceed to **634**.

(158) At **632** a handover may be deemed to be triggered, and the handover request **192** is determined. In some implementations the handover request **192** may be indicative of the second spot **310(2)** that may represent the destination spot **320**.

(159) At **634** no action is taken. For example, the MUT **108(M)** may continue to use the current spot **318**. The process may then return to **602**.

(160) In some implementations, one or more of the operations with respect to **620-634** may be omitted or reordered. For example, **626-630** may occur before **620-624** with corresponding adjustment to the process.

(161) FIG. 7 depicts at **700** a flow diagram of a system using the handover request **192** sent by the mobile UT **108(M)** to handover provisioning from a first spot **310(1)** to a second spot **310(2)**, according to some implementations. The process may be implemented by one or more satellites **102**, ground stations **106**, user terminals **108**, the management system **150**, and so forth. This process is associated with the self-triggered handover mode in which the UT **108** does not provide precise information about its current position to the system **100**.

(162) At **702** the MUT **108(M)** determines a handover request **192**. For example, as described with regard to FIG. 6, the mobility management system **188** may determine the handover request **192** based at least in part on the state data **190**.

(163) At **704** the handover request **192** is sent. For example, the MUT **108(M)** may send the handover request **192** using the first spot **310(1)** provided by a first satellite **102(1)**.

(164) In the instance of an intersatellite handover **304** as described above, the handover request **192** may be sent from the first satellite **102(1)** to the management system **150**.

(165) In the instance of an intrasatellite handover **302** as described above, the operation of **706** may be performed by the resource scheduler **116** or other system of the first satellite **102(1)**.

(166) At **706** the management system **150**, or a portion thereof such as the scheduling system **156**, determines handover data **164** indicative of a first plurality of communication resources that are allocated to the mobile UT **108(M)** for use at or after a handover time.

(167) The handover data **164** is determined based at least in part on the data included in the handover request **192**. Other data that may be considered in determining the handover data **164** may include the orbital data **154**, the system status data **158**, the user terminal data **160**, and so forth.

(168) In one implementation, the handover data **164** may include one or more of a primary destination spot ID, secondary spot ID, and so forth of spots **310** determined by the mobility management system **188** as destination spots **320** for use after the handover. The management system **150** may determine if communication resources will be available after the handover time within one or more of the proposed destination spots **310** included in the handover request **192** and allocate accordingly. For example, if communication resources are available in the primary destination spot after the handover time, the management system **150** may allocate the communication resources associated with the spot **310** indicated by the primary destination spot ID. If not, the management system **150** may allocate the communication resources associated with the spot **310** indicated by the secondary destination spot ID, or specify another spot ID that may not have been indicated by the handover request **192**.

(169) In some implementations, the management system **150** may determine the destination spot **320** to be indicated by the handover data **164** based on one or more of information associated with geometry or received signal strength that is associated with the MUT **108(M)** sending the handover request **192**. This process may be similar to that described above with respect to FIG. 6, in particular operations **620-634**.

(170) For example, if the first distance from a position of the MUT **108(M)** to a first point in the current spot **318** is greater than a second distance from the position of the MUT **108(M)** to a second point in an adjacent spot **310**, the adjacent spot **310** may be deemed to be the destination spot **320**, and communication resources allocated accordingly. The position may be a current or predicted position of the MUT **108(M)**. The point may comprise a specified point relative to one or more of the geographic area **312** or the signal footprint **314**. For example, the point may be the spot geometric center **316**.

(171) In another example, if the first RSS associated with the current spot **318** is less than a second RSS associated with an adjacent spot **310**, then the adjacent spot **310** may be deemed to be the

destination spot **320**, and communication resources allocated accordingly.

(172) In other examples, various combinations of comparisons based on position and RSS may be used. For example, the distance may be compared as described above, and then the RSS may be compared to determine the destination spot **320** that will be specified in the handover data **164**.

(173) The examples describe a single adjacent spot **310** for ease of illustration and not as a limitation. During operation of the system **100**, the determination of the handover data **164** may assess a plurality of spots **310** to determine the destination spot **318** indicated in the handover data **164**. One or more of the techniques described may be used to assess a set of spots **310** comprising a plurality of spots **310** to be assessed to determine the destination spot **320** used after the handover time. This assessment may comprise comparisons or rankings of information associated with the current spot **318** and ones of the set of spots **310**. For example, each adjacent spot **310** in the set of spots **310** may be ranked in ascending order of distance, descending order of RSS, and so forth.

(174) In one implementation the set of spots **310** may comprise spots **310** that are adjacent to the current spot **318**. In another implementation the set of spots **310** may comprise spots **310** that are non-adjacent to the current spot **318**. In still another implementation the set of spots **310** may comprise spots **310** that are adjacent and non-adjacent to the current spot **318**.

(175) In the event of an intrasatellite handover **302**, based on the handover data **164** at **708** the first satellite **102(1)** may allocate resources associated with the next spot **310** for use by the mobile UT **108(M)** at or after the handover time. The first satellite **102(1)** sends the handover data **164** to the MUT **108(M)** using the first spot **310(1)**.

(176) In the event of an intersatellite handover **304** shown here, based on the handover data **164** at **710** the second satellite **102(2)** allocates satellite communication resources associated with the fourth spot **310(4)** for use by the mobile UT **108(M)** at or after the handover time.

(177) At **712** the MUT **108(M)** establishes communication based on the handover data **164**. For example, the communication system **180** may use the handover data **164** to transfer communication services from the first spot **310(1)** to the fourth spot **310(4)** at or after the handover time.

(178) At **714** the MUT **108(M)** may send upstream data **112** using the fourth spot **310(4)** to the second satellite **102(2)**. The second satellite **102(2)** may then send the data to its destination, such as to another UT **108**, to a ground station **106**, to another satellite **102** in the constellation, and so forth.

(179) At **716** the management system **150** or other systems may send downstream data **142** addressed to the MUT **108(M)** to the second satellite **102(2)**. The second satellite **102(2)** may use the fourth spot **310(4)** to send the downstream data **142** to the MUT **108(M)**.

(180) At **718** the MUT **108(M)** receives the downstream data **142** sent via the fourth spot **310(4)**.

(181) The second satellite **102(2)** may also send grant data **194** (not shown) to the MUT **108(M)**. The grant data **194** is indicative of the communication resources that have been allocated to provide uplink access to the mobile UT **108(M)** on the uplink to the second satellite **102(2)** while in the fourth spot **310(4)**.

(182) In comparison to the self-triggered handover mode depicted in this figure, during normal mode the MUT **108(M)** may send current position data, and based on the current position data the management system **150**, the resource scheduler **116**, or other portions of the system **100** determines handover data **164**.

(183) Times, intervals, durations, and the like as used in this disclosure may be specified with respect to actual clock time, system time, system timing references, discrete timeslots or interval indicators, and so forth. For example, time ticks may be specified relative to an epoch that resets at 10-minute intervals. In another example, actual clock time obtained from a GNSS receiver may be used to coordinate operation of one or more elements of the system **100**.

(184) The processes and methods discussed in this disclosure may be implemented in hardware, software, or a combination thereof. In the context of software, the described operations represent computer-executable instructions stored on one or more computer-readable storage media that,

when executed by one or more hardware processors, perform the recited operations. Generally, computer-executable instructions include routines, programs, objects, components, data structures, and the like that perform particular functions or implement particular abstract data types. Those having ordinary skill in the art will readily recognize that certain steps or operations illustrated in the figures above may be eliminated, combined, or performed in an alternate order. Any steps or operations may be performed serially or in parallel. Furthermore, the order in which the operations are described is not intended to be construed as a limitation.

(185) Embodiments may be provided as a software program or computer program product including a non-transitory computer-readable storage medium having stored thereon instructions (in compressed or uncompressed form) that may be used to program a computer (or other electronic device) to perform processes or methods described herein. The computer-readable storage medium may be one or more of an electronic storage medium, a magnetic storage medium, an optical storage medium, a quantum storage medium, and so forth. For example, the computer-readable storage medium may include, but is not limited to, hard drives, optical disks, read-only memories (ROMs), random access memories (RAMs), erasable programmable ROMs (EPROMs), electrically erasable programmable ROMs (EEPROMs), flash memory, magnetic or optical cards, solid-state memory devices, or other types of physical media suitable for storing electronic instructions. Further embodiments may also be provided as a computer program product including a transitory machine-readable signal (in compressed or uncompressed form). Examples of transitory machine-readable signals, whether modulated using a carrier or unmodulated, include, but are not limited to, signals that a computer system or machine hosting or running a computer program can be configured to access, including signals transferred by one or more networks. For example, the transitory machine-readable signal may comprise transmission of software by the Internet.

(186) Separate instances of these programs can be executed on or distributed across any number of separate computer systems. Thus, although certain steps have been described as being performed by certain devices, software programs, processes, or entities, this need not be the case, and a variety of alternative implementations will be understood by those having ordinary skill in the art.

(187) Additionally, those having ordinary skill in the art will readily recognize that the techniques described above can be utilized in a variety of devices, physical spaces, and situations. Although the subject matter has been described in language specific to structural features or methodological acts, it is to be understood that the subject matter defined in the appended claims is not necessarily limited to the specific features or acts described. Rather, the specific features and acts are disclosed as illustrative forms of implementing the claims.

Claims

1. A system comprising: a first set of one or more processors executing instructions to: receive a handover request from a first user terminal (UT) that is located within a first geographic area, wherein the handover request comprises first data; determine, based on the first data, a second geographic area; determine handover data indicative of the second geographic area and associated with a first time; send the handover data to the first UT; and establish communication with the first UT that is located in the second geographic area on or after the first time, based at least in part on the handover data.
2. The system of claim 1, the first data comprising one or more of: second data indicative of the second geographic area; third data indicative of a current distance from a current position of the first UT to a geometric center of the first geographic area; fourth data indicative of a current distance from the current position of the first UT to a geometric center of the second geographic area; fifth data indicative of a first predicted distance from a predicted position of the first UT at the first time to the geometric center of the first geographic area; sixth data indicative of a second

predicted distance from the predicted position of the first UT at the first time to the geometric center of the second geographic area; seventh data indicative of a first received signal strength, at the first UT, of a first signal associated with the first geographic area; or eighth data indicative of a second received signal strength, at the first UT, of a second signal associated with the second geographic area.

3. The system of claim 1, the first data comprising one or more of: a first set of rank values, wherein each rank value of the first set of rank values is based on a distance, determined by the first UT, from the first UT to a point associated with a respective one of a set of geographic areas; or a second set of rank values, wherein each rank value of the second set of rank values is based on a received signal strength, determined by the first UT, of a received signal associated with the respective one of the set of geographic areas.

4. The system of claim 1, wherein the first data is indicative of: a first distance from a first position of the first UT to a first point within the first geographic area; and a second distance from the first position of the first UT to a second point within the second geographic area; and the first set of one or more processors executing instructions to: determine the second geographic area based on the first distance being greater than the second distance.

5. The system of claim 1, wherein the first data is indicative of: a first received signal strength, at the first UT, of a first signal associated with the first geographic area; and a second received signal strength, at the first UT, of a second signal associated with the second geographic area; and the first set of one or more processors executing instructions to: determine the second geographic area based on the first received signal strength being less than the second received signal strength.

6. The system of claim 1, wherein the first data is indicative of: a set of geographic areas that are adjacent to the first geographic area, wherein the set of geographic areas includes the second geographic area; and one or more of: a distance, determined by the first UT, from the first UT to a point associated with a respective one of the set of geographic areas; or a received signal strength, determined by the first UT, of a received signal associated with the respective one of the set of geographic areas.

7. A method comprising: determining state data associated with a first user terminal (UT), wherein the state data is associated with the first UT obtaining communication service using a first spot of a first satellite in a constellation of satellites; determining, based on the state data, a handover request; sending the handover request to the first satellite using the first spot; receiving handover data from the first satellite using the first spot, wherein the handover data is indicative of a second spot and a handover time; and based on the handover data, establishing communication with at least one satellite of the constellation of satellites using the second spot at the handover time.

8. The method of claim 7, further comprising: determining, based on the state data, one or more of: a first set of rank values, wherein each rank value of the first set of rank values is based on a distance, determined by the first UT, from the first UT to a point associated with a respective one of a set of geographic areas; or a second set of rank values, wherein each rank value of the second set of rank values is based on a received signal strength, determined by the first UT, of a received signal associated with the respective one of the set of geographic areas; and wherein the handover request comprises one or more of the first set of rank values or the second set of rank values.

9. The method of claim 7, further comprising: determining a current position of the first UT; determining that the current position of the first UT is within a first geographic area that is associated with the first spot; determining, based on the state data, a predicted position of the first UT at or after the handover time; and determining the handover request based on the predicted position being outside the first geographic area.

10. The method of claim 7, further comprising: determining, using the first UT, a first received signal strength of a first signal associated with the first spot; determining, using the first UT, a second received signal strength of a second signal associated with the second spot; and determining the handover request based on the first received signal strength being less than the second received

signal strength.

11. The method of claim 7, further comprising: determining a set of spots, wherein each spot of the set of spots is provided by a single satellite; determining, at the first UT, a set of received signal strengths, wherein each received signal strength, of the set of received signal strengths, is associated with a respective spot of the set of spots, further wherein the set of spots includes the second spot; and wherein the state data comprises the set of received signal strengths.

12. The method of claim 7, further comprising: determining a set of spots comprising the second spot of a second satellite and a third spot of a third satellite; and determining, at the first UT, a set of received signal strengths comprising a first received signal strength of the second spot and a third received signal strength of the third spot; and wherein the state data comprises the set of received signal strengths.

13. The method of claim 7, further comprising: determining the handover request based on the state data indicating one or more of: a position of the first UT; or a set of received signal strengths determined by the first UT, wherein each received signal strength, of the set of received signal strengths, is associated with a respective spot of a set of spots, further wherein the set of spots includes the second spot.

14. The method of claim 7, further comprising: determining a set of spots that are adjacent to the first spot; determining a destination spot based on one or more of: a position of the first UT; or a set of received signal strengths of signals received by the first UT, wherein each received signal strength is associated with a respective spot of the set of spots, further wherein the set of spots includes the second spot; wherein the handover request comprises data indicative of the destination spot; and wherein the second spot is the destination spot.

15. A system comprising: a constellation of satellites comprising a first communication satellite; and a first user terminal (UT) comprising: a navigation system; a first antenna; a first transmitter coupled to the first antenna; a first receiver coupled to the first antenna; and a first set of one or more processors executing instructions to: determine first data associated with the first UT, wherein the first data is associated with the first UT obtaining communication service using a first spot of the first communication satellite; determine, based on the first data, a handover request; send the handover request to the first communication satellite using the first spot; receive handover data from the first communication satellite using the first spot, wherein the handover data is indicative of a second spot and a handover time; and based on the handover data, establish communication with at least one satellite of the constellation of satellites using the second spot at the handover time.

16. The system of claim 15, the handover request comprising one or more of: second data indicative of the second spot; third data indicative of a current distance from a current position of the first UT indicated by the navigation system to a geometric center of the first spot; fourth data indicative of a current distance from the current position of the first UT to a geometric center of the second spot; fifth data indicative of a first predicted distance from a predicted position of the first UT at a first time to the geometric center of the first spot; sixth data indicative of a second predicted distance from the predicted position of the first UT at the first time to the geometric center of the second spot; seventh data indicative of a first received signal strength, at the first receiver, of a first signal associated with the first spot; or eighth data indicative of a second received signal strength, at the first receiver, of a second signal associated with the second spot.

17. The system of claim 15, the first set of one or more processors executing instructions to: determine a current position of the first UT based on output from the navigation system; determine that the current position of the first UT is within a first geographic area that is associated with the first spot; determine, based on the first data, a predicted position of the first UT at or after the handover time; and determine the handover request based on the predicted position being outside the first geographic area.

18. The system of claim 15, the first set of one or more processors executing instructions to:

determine, using the first receiver, a first received signal strength of a first signal associated with the first spot; determine, using the first receiver, a second received signal strength of a second signal associated with the second spot; and determine the handover request based on the first received signal strength being less than the second received signal strength.

19. The system of claim 15, the first set of one or more processors executing instructions to: determine the handover request based on the first data indicating one or more of: a position of the first UT based at least in part on output from the navigation system; or a set of received signal strengths of signals received by the first receiver, wherein each received signal strength is associated with a respective spot of a set of spots, further wherein the set of spots includes the second spot.

20. The system of claim 15, the first set of one or more processors executing instructions to: determine a set of spots that are adjacent to the first spot; determine a destination spot based on one or more of: a position of the first UT based at least in part on output from the navigation system; or a set of received signal strengths of signals received by the first receiver, wherein each received signal strength is associated with a respective spot of the set of spots, further wherein the set of spots includes the second spot; wherein the handover request comprises data indicative of the destination spot; and wherein the second spot is the destination spot.
