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### Rapid thermal processing (RTP) chamber outgassing removal

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#### Abstract

Embodiments disclosed herein include a method of monitoring a condition of a chamber. In an embodiment, the method comprises processing a substrate in the chamber, providing substrate history and chamber data to a model of the chamber, where the model of the chamber is configured to predict a chamber cleanliness, comparing the predicted chamber cleanliness against a performance limit, and flagging the chamber for preventive maintenance (PM) when the predicted chamber cleanliness is above the performance limit.

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**Background/Summary**

CROSS-REFERENCE TO RELATED APPLICATIONS (1) This application claims the benefit of U.S. Provisional Application No. 63/415,817, filed on Oct. 13, 2022, the entire contents of which are hereby incorporated by reference herein.

**BACKGROUND**

- 1) Field  
(1) Embodiments relate to the field of semiconductor manufacturing and, in particular, to a rapid thermal processing (RTP) chamber with one or more algorithms to identify when preventative maintenance (PM) is needed and when to clean the RTP chamber.
- 2) Description of Related Art  
(2) Material outgassing in semiconductor processing chambers can lead to deposits on the interior surface of a chamber. In the case of a rapid thermal processing (RTP) tool, cold-wall surfaces are particularly prone to picking up deposits. For example, temperature sensor (e.g., pyrometers) mis-readings due to surface contamination can result in negative impacts to process control and can

lead to yield issues. That is, the temperature sensor may not read the true temperature of a surface, and feedback loops to control the voltage supplied to lamps in the RTP tool may operate on the incorrect information. This can result in temperatures of the RTP tool being too high in some instances.

(3) Accordingly, it is necessary to clean the RTP tool at regular intervals or when yield issues are discovered. The current cleaning solution relies on daily test wafer monitoring in order to trigger a tool down for preventative maintenance (PM). The cleaning may include a manual wet clean. This requires the chamber to be opened and retuned after cleaning. Further, a requalification of the process is also needed. To remove trace metals after chamber integrity is broken may require thousands of seasoning wafers to be run.

## SUMMARY

(4) Embodiments disclosed herein include a method of monitoring a condition of a chamber. In an embodiment, the method comprises processing a substrate in the chamber, providing substrate history and chamber data to a model of the chamber, where the model of the chamber is configured to predict a chamber cleanliness, comparing the predicted chamber cleanliness against a performance limit, and flagging the chamber for preventive maintenance (PM) when the predicted chamber cleanliness is above the performance limit.

(5) Embodiments may also include a method of cleaning a chamber. The method may comprise providing substrate history and chamber data to a model of the chamber, where the model of the chamber is configured to predict a chamber cleanliness, comparing the predicted chamber cleanliness against a performance limit, and cleaning the chamber when the predicted chamber cleanliness does not pass the performance limit.

(6) Embodiments may also include a rapid thermal processing (RTP) tool. In an embodiment, the RTP tool comprises a chamber, a reflector plate, a substrate support, an edge ring around the substrate support, a plurality of lamps above the reflector plate, and a model of the tool. In an embodiment, the model of the tool is configured to predict a chamber cleanliness by comparing the predicted chamber cleanliness against a performance limit, and flag the chamber for preventive maintenance (PM) when the predicted chamber cleanliness is above the performance limit.

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## Description

### BRIEF DESCRIPTION OF THE DRAWINGS

(1) FIG. 1 is a cross-sectional illustration of a rapid thermal processing (RTP) tool, in accordance with an embodiment.

(2) FIG. 2A is a plan view illustration of a dirty RTP tool looking down at the reflector and the edge ring, in accordance with an embodiment.

(3) FIG. 2B is a plan view illustration of a clean RTP tool looking down at the reflector and the edge ring, in accordance with an embodiment.

(4) FIG. 3A is a graph of the sheet resistance of substrates processed in a clean chamber, a chamber with a first level of coating, and a chamber with a second level of coating, in accordance with an embodiment.

(5) FIG. 3B is a graph of the resulting temperature variation and standard deviation for an RTP tool with a first level of a coating and a second level of the coating, in accordance with an embodiment.

(6) FIG. 4A is a graph of wafer to wafer modeling of an RTP tool with a first level of a coating and a second level of the coating, in accordance with an embodiment.

(7) FIG. 4B is a graph of wafer to wafer modeling of an RTP tool after a cleaning process, in accordance with an embodiment.

(8) FIG. 5A is a graph of wafer to wafer radiation sensor data for an RTP tool with a first level of a coating and a second level of the coating, in accordance with an embodiment.

- (9) FIG. 5B is a graph of wafer to wafer radiation sensor data for an RTP tool after a cleaning process, in accordance with an embodiment.
- (10) FIG. 6 is a process flow diagram of a process for identifying when a preventive maintenance (PM) operation on an RTP tool is needed, in accordance with an embodiment.
- (11) FIG. 7 is a process flow diagram of a process for identifying when a clean of an RTP tool is complete, in accordance with an embodiment.
- (12) FIG. 8 illustrates a block diagram of an exemplary computer system that may be used in conjunction with a processing tool, in accordance with an embodiment.

#### DETAILED DESCRIPTION

(13) Systems described herein include a rapid thermal processing (RTP) chamber with one or more algorithms to identify when preventative maintenance (PM) is needed and when to clean the RTP chamber. In the following description, numerous specific details are set forth in order to provide a thorough understanding of embodiments. It will be apparent to one skilled in the art that embodiments may be practiced without these specific details. In other instances, well-known aspects are not described in detail in order to not unnecessarily obscure embodiments. Furthermore, it is to be understood that the various embodiments shown in the accompanying drawings are illustrative representations and are not necessarily drawn to scale.

(14) As noted above, deposits on interior surfaces of a chamber negatively impact the process performance. This can lead to yield issues, and requires frequent cleaning. The cleaning may include opening the chamber and implementing a manual wet clean. This takes time and expertise. Additionally, subsequent to the cleaning, the chamber needs to be retuned and the process needs to be requalified.

(15) Accordingly, embodiments disclosed herein include a chamber monitoring and cleaning process that is automated. The state of the chamber, (i.e., the cleanliness of the chamber) can be monitored with one or more algorithms that map the state of the interior surfaces. When the surface coatings pass a threshold level that negatively impacts the process performance, a warning is triggered. The warning can then be used to initiate a self-cleaning operation. In a particular embodiment, the self-cleaning operation is a waferless clean process. That is, the cleaning is implemented without a wafer present in the chamber. The algorithm can also be used in order to monitor the clean, and can provide an indication when the cleaning is completed. Accordingly, the cleaning process can be implemented without opening the chamber. Therefore, tuning and requalification processes can be reduced in duration or omitted.

(16) Referring now to FIG. 1, a cross-sectional illustration of a semiconductor processing tool **100** is shown, in accordance with an embodiment. In an embodiment, the semiconductor processing tool **100** may be a RTP tool. That is, the semiconductor processing tool **100** may be configured to rapidly heat a substrate **140** in order to modify a surface of the substrate **140**. For example, a rapid thermal oxidation process may be implemented on the substrate **140**.

(17) In an embodiment, the substrate **140** may be a semiconductor substrate. For example, the substrate **140** may be a silicon wafer or the like. The substrate **140** may have any standard wafer form factor (e.g., 150 mm, 200 mm, 300 mm, 450 mm, etc.). Additionally, the substrate **140** may have other form factors besides round shapes in some embodiments.

(18) In an embodiment, the semiconductor processing tool **100** may comprise a chamber **105**. The chamber **105** may be any suitable material, such as stainless steel or the like. An interior surface of the chamber **105** may have a coating in some embodiments to protect the surfaces of the chamber **105**.

(19) In an embodiment, the semiconductor processing tool **100** may have a substrate support structure. The substrate support structure may include a base **120**. An insert **126** may be provided over the base **120**. In an embodiment, a reflector **125** may be provided over the insert **126**. The reflector **125** may be used to reflect radiation back to the substrate **140** in order to improve heating of the substrate **140**. The reflector **125** may be any reflective material. The support structure may

further comprise a substrate support **122**. The substrate support **122** may support the substrate **140** over the reflector **125**. There may be a space provided between the reflector **125** and the substrate **140**. In an embodiment, the substrate support **122** may be coupled to a lift mechanism **121** to raise or lower the substrate **140**. In an embodiment, an edge ring **127** may be provided around the perimeter of the substrate support **122** and the substrate **140**.

(20) In an embodiment, a fluidic path may be provided through the chamber **105**. As indicated by the arrows, a gas may flow into the chamber **105** through opening **106**, pass over the substrate **140**, and exit the chamber **105** through an exit **107**. The exit **107** may be coupled to a pump (not shown). The pump may be used to evacuate species from the chamber **105**.

(21) In an embodiment, a lamp housing **110** may be provided over the substrate **140**. The lamp housing **110** may include a plurality of lamps **115**. The lamps **115** may be distributed across a surface of the substrate **140**. The lamps **115** may be individually controllable in order to provide a desired heating profile over the substrate **140**. In an embodiment, any suitable lamp architecture may be used. The lamps **140** may be separated from the main chamber volume by a window **117**. For example, the window **117** may be a quartz window **117** or the like. As such, thermal energy from the lamps **140** passes through the window **117** to reach the substrate **140**. Thermal energy that passes through the substrate **140** may be reflected back to the substrate **140** by the reflector **125**.

(22) In an embodiment, one or more sensors may be provided in the semiconductor processing tool **100** in order to provide feedback control to the lamps **115**. For example, one or more pyrometers **130** may be included in the chamber **105**. The pyrometers **130** may pass through the base **120** and detect the temperature of the backside of the substrate **140**. The pyrometers **130** may be distributed across the back of the substrate **140** in order to provide spatial temperature measurements.

(23) In an embodiment, the interior surfaces of the chamber **105** (e.g., chamber sidewalls, the reflector **125**, the edge ring **127**, and the like) may be coated during use of the semiconductor processing tool **100**. For example, outgassing species from the substrate **140** may deposit on the surfaces. The deposition may be further enhanced due to some of the surfaces being considered cold-wall surfaces. That is, some of the surfaces may be actively cooled. Deposition of layers on the interior surfaces of the semiconductor processing tool **100** may negatively affect processing performance and device yield. For example, as coatings are applied over the pyrometers **130**, the measured temperatures may be offset from the real temperature of the system. This can lead to improper feedback to the voltage control of the lamps **115**, which can result in temperature overshoots.

(24) Referring now to FIG. 2A and FIG. 2B, plan view illustrations of the interior of a semiconductor processing tool **200** are shown, in accordance with an embodiment. In FIG. 2A, a coating is provided over the reflector **225**, the substrate support **222**, and the edge ring **227**. The coated surfaces are indicated as **225'**, **222'**, and **227'** in order to indicate that they have a coating over the surfaces. The coating may be carbon based coating. For example, as will be described in greater detail below, a carbon may outgas from the surface of the substrate and redeposit on the interior surfaces of the chamber. Referring now to FIG. 2B, a plan view illustration of a clean semiconductor processing tool **200** is shown, in accordance with an embodiment. As shown, the reflector **225**, the substrate support **222**, and the edge ring **227** are clean without the carbon coating.

(25) Referring now to FIG. 3A, a graph of the sheet resistance of various substrates is shown, in accordance with an embodiment. The first line **361** is a graph of the sheet resistance across the surface of a substrate when the chamber used is clean. The second line **362** is a graph of the sheet resistance across the surface of a substrate when the chamber has a first level of coating over the interior surface of the chamber. The third line **362** is a graph of the sheet resistance across the surface of a substrate when the chamber has a second level of coating over the interior surface of the chamber. The thickness of the second level of coating is greater than the thickness of the first level of coating. As shown, the sheet resistance decreases as a result of increased chamber coatings.

(26) In the embodiment shown in FIG. 3A, the chamber coatings are provided through a controlled

outgassing process. For the first level of coating, a substrate comprising an amorphous carbon film is provided in the chamber for a first duration at an elevated temperature (e.g., 500 degrees Celsius) in order to outgas carbon onto the interior surfaces. For the second level of coating a pair of substrates with an amorphous carbon film are outgassed into the chamber. As used herein the first level of coating may be referred to as a first dusting, and the second level of coating may be referred to as undergoing two dusting processes.

(27) Referring now to FIG. 3B, a graph of the change in temperature for the first dusting (left) and the pair of dustings (right) is shown. As indicated by bar **150**, the first dusting results in an average increase in temperature that is about 3.5 degrees Celsius with a standard deviation **151** of approximately 1 degree Celsius. The pair of dustings result in a temperature increase **152** that is approximately 7 degrees Celsius with a standard deviation **153** of approximately 1.5 degrees Celsius. Accordingly, the presence of carbon films over the interior surfaces of the chamber significantly alters the outcome of the processing operation.

(28) Referring now to FIG. 4A, a graph of a model of a semiconductor processing performance is shown, in accordance with an embodiment. The model may be an artificial intelligence (AI) or machine learning (ML) model of the state of the chamber. The model may represent the expected outcomes of wafers that are processed in the chamber. That is, the graph in FIG. 4A may be modeled data, and real wafers do not need to be processed in order to generate the graph shown in FIG. 4A.

(29) The X-axis is the number of the wafer that is being process. For example, a first set of wafers are processed in region **464**. Region **464** indicates a clean chamber. In region **465** a first dusting is done. As shown, the values in the first dusting region **465** the values are generally decreased to between -5 and -10. Region **466** is after a second dusting is done in the chamber. As shown, the second dusting region **466** has decreased values between -10 and -15.

(30) Referring now to FIG. 4B, a model is shown with a graph of wafer outcomes after a clean is implemented in the chamber. As shown, the values of region **467** return to about the same state shown in region **464** (i.e., a clean chamber). As such, it can be expected that subsequent to the cleaning operation, the performance of the chamber is reset back to within specification. In an embodiment, the cleaning operation may be any suitable cleaning process, depending on the specific coating provided by the dusting. In some embodiments, the cleaning process may be a waferless cleaning process. That is, the cleaning process is executed without a substrate or wafer in the chamber.

(31) Referring now to FIG. 5A, a graph of the wafer-to-wafer performance of a chamber is shown, in accordance with an embodiment. The data supplied in FIG. 5A may be actual sensor data from a plurality of substrates that are processed in a chamber. For example, the data may be from one or more pyrometers in some embodiments. In region **564**, the substrates are processed in a substantially clean chamber. In region **565**, the substrates are processed in a chamber that has undergone a first dusting. In region **566**, the substrate are processed in a chamber that has undergone a second dusting. The data shown in FIG. 5A substantially lines up with the model data shown in FIG. 4A. That is, the modeling process accurately matches the actual results of the processing in the chamber. A more detailed description of the model will be provided in greater detail below.

(32) As shown in FIG. 5B, region **567** is a measurement of the performance after a chamber clean. Similar to FIG. 4B, the chamber clean resets the performance so that it is similar to region **564** of a clean chamber. The cleaning process may be any cleaning process that is used in order to clean a specific type of coating. In an embodiment, the chamber cleaning process may be a waferless cleaning process.

(33) Referring now to FIG. 6, a process flow diagram of a process **670** for monitoring the cleanliness of a chamber is shown, in accordance with an embodiment. In an embodiment, the process may be implemented on fabrication facility (FAB) computers **671** and directly on the tool

**672.** In other embodiments, the entire process **670** may be executed locally on the tool **672**. The tool **672** may be a RTP tool **672** in some embodiments. In an embodiment, the recipe and/or lot information **673** may be supplied to the tool **672**. The recipe and/or lot information **673** may inform a run library **676**. The run library **676** may include the substrate history (e.g., the processes implemented on the substrates, the metrology performed on the substrates, and the like). The run library **676** may supply wafer history to the model **678**. The run library **676** and the model **678** may also have system data **674** inputs. The system data **674** may include sensor data from the tool **672**. For example, system data **674** may include a voltage value of one or more lamps in the chamber, a pyrometer reading of one or more pyrometers in the chamber, pumping data, and data from one or more witness sensors.

(34) In an embodiment, the model **678** may be an AI or ML model. Data obtained from one or more sensors within the tool **672** may be used to inform the model **678**. The model **678** may map a condition of the chamber. For example, the model may determine a state of cleanliness of the chamber. In a particular embodiment, a graph similar to the graph in FIG. 4A may be generated by the model in order to predict performance of the processing of substrates in the tool **672**. In an embodiment, the model **678** may be considered a digital twin of the tool **672**. As a digital twin, the model **678** uses inputs such as system data **674**, physics based equations to model the physics of the tool, and the like in order to accurately map the performance of the tool **672**.

(35) In an embodiment, the model **678** may output a performance prediction. The performance prediction may be an estimated wafer outcome from implementing a process in the chamber, such as an oxidation process. In an embodiment, the performance prediction may be sent to a performance information block **675** in the FAB **671**. Additionally, the performance prediction is sent to a decision block **680**. At block **680** the performance prediction is compared to a performance limit **677**. The performance limit **677** may be a worst case outcome that is acceptable. If the performance prediction is outside of the performance limit **677** (yes branch), then a predicted maintenance message **679** is generated. This is a flag that indicates a cleaning process is needed in the chamber. If the performance prediction is within the performance limit **677** (no branch), then the next wafer is processed at block **681**.

(36) After a predicted maintenance message **679** is generated, embodiments may include implementing a cleaning process in the chamber. In an embodiment, the cleaning process may be a waferless cleaning process. For example, cleaning gasses may be flown into the chamber in order to etch the coating on the chamber. The cleaning gasses may be dependent on the type of coating on the chamber. In a particular embodiment, the cleaning gas may include hydrogen (H.sub.2) and oxygen (O.sub.2). A pressure of the chamber may be provided at approximately 50 Torr or less. In a particular embodiment, the pressure may be approximately 10 Torr. The duration of the clean may be dependent on the thickness of the coating. For example, longer durations of the clean may be needed for thicker coatings. In a particular embodiment, the duration of the cleaning process may be approximately ten minutes or more.

(37) In an embodiment, the model may also be used to monitor the cleaning process. For example, the model may be used in order to indicate when the cleaning process has sufficiently cleaned the chamber so that production substrates can be continued to run on the tool. An example, of the process for monitoring the chamber cleaning process is shown in FIG. 7.

(38) Similar to the embodiment in FIG. 6, the process **780** may be implemented on both the FAB **781** server and locally on the tool **782**. In other embodiments, the process **780** may be entirely executed on the tool **782**. In an embodiment, the recipe and/or lot information **783** may be supplied to the tool **782**. The recipe and/or lot information **783** may inform a run library **786**. The run library **786** may include the substrate history (e.g., the processes implemented on the substrates, the metrology performed on the substrates, and the like). The run library **786** may supply wafer history to the model **788**. The run library **786** and the model **788** may also have system data **784** inputs. The system data **784** may include sensor data from the tool **782**. For example, the system data **784**

may include a voltage value of one or more lamps in the chamber, a pyrometer reading of one or more pyrometers in the chamber, pumping data, and data from one or more witness sensors.

(39) In an embodiment, the model **788** may be an AI or ML model. The model **788** may be substantially similar to the model **678** described in greater detail above. In an embodiment, the model **788** may be a digital twin in order to model performance of the tool **782**.

(40) In an embodiment, the model **788** may output a performance prediction. The performance prediction may be an estimated wafer outcome from implementing a process in the chamber, such as an oxidation process. In an embodiment, the performance prediction may be sent to a performance information block **785** in the FAB **781**. Additionally, the performance prediction is sent to a decision block **790**. At block **790** the performance prediction is compared to a performance limit **787**. The performance limit **787** may be a best case outcome that indicates a clean chamber. If the performance prediction is within the performance limit **787** (yes branch), then a maintenance complete message **789** is generated, and the cleaning process is completed. If the performance prediction is outside of the performance limit **787** (no branch), then the clean **791** is continued before the next wafer **792** is processed.

(41) Referring now to FIG. **8**, a block diagram of an exemplary computer system **800** of a processing tool is illustrated in accordance with an embodiment. In an embodiment, computer system **800** is coupled to and controls processing in the processing tool. Computer system **800** may be connected (e.g., networked) to other machines in a Local Area Network (LAN), an intranet, an extranet, or the Internet. Computer system **800** may operate in the capacity of a server or a client machine in a client-server network environment, or as a peer machine in a peer-to-peer (or distributed) network environment. Computer system **800** may be a personal computer (PC), a tablet PC, a set-top box (STB), a Personal Digital Assistant (PDA), a cellular telephone, a web appliance, a server, a network router, switch or bridge, or any machine capable of executing a set of instructions (sequential or otherwise) that specify actions to be taken by that machine. Further, while only a single machine is illustrated for computer system **800**, the term “machine” shall also be taken to include any collection of machines (e.g., computers) that individually or jointly execute a set (or multiple sets) of instructions to perform any one or more of the methodologies described herein.

(42) Computer system **800** may include a computer program product, or software **822**, having a non-transitory machine-readable medium having stored thereon instructions, which may be used to program computer system **800** (or other electronic devices) to perform a process according to embodiments. A machine-readable medium includes any mechanism for storing or transmitting information in a form readable by a machine (e.g., a computer). For example, a machine-readable (e.g., computer-readable) medium includes a machine (e.g., a computer) readable storage medium (e.g., read only memory (“ROM”), random access memory (“RAM”), magnetic disk storage media, optical storage media, flash memory devices, etc.), a machine (e.g., computer) readable transmission medium (electrical, optical, acoustical or other form of propagated signals (e.g., infrared signals, digital signals, etc.)), etc.

(43) In an embodiment, computer system **800** includes a system processor **802**, a main memory **804** (e.g., read-only memory (ROM), flash memory, dynamic random access memory (DRAM) such as synchronous DRAM (SDRAM) or Rambus DRAM (RDRAM), etc.), a static memory **806** (e.g., flash memory, static random access memory (SRAM), etc.), and a secondary memory **818** (e.g., a data storage device), which communicate with each other via a bus **830**.

(44) System processor **802** represents one or more general-purpose processing devices such as a microsystem processor, central processing unit, or the like. More particularly, the system processor may be a complex instruction set computing (CISC) microsystem processor, reduced instruction set computing (RISC) microsystem processor, very long instruction word (VLIW) microsystem processor, a system processor implementing other instruction sets, or system processors implementing a combination of instruction sets. System processor **802** may also be one or more



special-purpose processing devices such as an application specific integrated circuit (ASIC), a field programmable gate array (FPGA), a digital signal system processor (DSP), network system processor, or the like. System processor **802** is configured to execute the processing logic **826** for performing the operations described herein.

(45) The computer system **800** may further include a system network interface device **808** for communicating with other devices or machines. The computer system **800** may also include a video display unit **810** (e.g., a liquid crystal display (LCD), a light emitting diode display (LED), or a cathode ray tube (CRT)), an alphanumeric input device **812** (e.g., a keyboard), a cursor control device **814** (e.g., a mouse), and a signal generation device **816** (e.g., a speaker).

(46) The secondary memory **818** may include a machine-accessible storage medium **831** (or more specifically a computer-readable storage medium) on which is stored one or more sets of instructions (e.g., software **822**) embodying any one or more of the methodologies or functions described herein. The software **822** may also reside, completely or at least partially, within the main memory **804** and/or within the system processor **802** during execution thereof by the computer system **800**, the main memory **804** and the system processor **802** also constituting machine-readable storage media. The software **822** may further be transmitted or received over a network **861** via the system network interface device **808**. In an embodiment, the network interface device **808** may operate using RF coupling, optical coupling, acoustic coupling, or inductive coupling.

(47) While the machine-accessible storage medium **831** is shown in an exemplary embodiment to be a single medium, the term “machine-readable storage medium” should be taken to include a single medium or multiple media (e.g., a centralized or distributed database, and/or associated caches and servers) that store the one or more sets of instructions. The term “machine-readable storage medium” shall also be taken to include any medium that is capable of storing or encoding a set of instructions for execution by the machine and that cause the machine to perform any one or more of the methodologies. The term “machine-readable storage medium” shall accordingly be taken to include, but not be limited to, solid-state memories, and optical and magnetic media.

(48) In the foregoing specification, specific exemplary embodiments have been described. It will be evident that various modifications may be made thereto without departing from the scope of the following claims. The specification and drawings are, accordingly, to be regarded in an illustrative sense rather than a restrictive sense.

## Claims

1. A method of monitoring a condition of a chamber, comprising: processing a substrate in the chamber; providing substrate history and chamber data to a model of the chamber, wherein the model of the chamber is configured to predict a chamber cleanliness; comparing the predicted chamber cleanliness against a performance limit; and flagging the chamber for preventive maintenance (PM) when the predicted chamber cleanliness is above the performance limit.
2. The method of claim 1, wherein the substrate history includes a materials characterization of the surface of the substrate.
3. The method of claim 2, wherein the materials characterization includes an outgassing potential of the substrate.
4. The method of claim 1, wherein the chamber data comprises a voltage value for one or more lamps in the chamber.
5. The method of claim 1, wherein the chamber data comprises a pyrometer reading for one or more pyrometers in the chamber.
6. The method of claim 1, wherein the chamber data comprises pumping data.
7. The method of claim 1, wherein the chamber data comprises data from one or more witness sensors.
8. The method of claim 1, wherein the model of the chamber is a digital twin of the chamber.

9. The method of claim 1, wherein the chamber is part of a rapid thermal processing (RTP) tool.
  10. The method of claim 1, wherein the PM includes a chamber cleaning operation.
  11. The method of claim 10, wherein the chamber cleaning operation is a waferless chamber clean.
  12. The method of claim 10, wherein the model of the chamber determines when the chamber cleaning operation is complete.
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