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(54) **PROTECTIVE APPARATUS, ENERGY STORAGE APPARATUS, AND METHOD FOR PROTECTING ENERGY STORAGE DEVICE**

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(58) **Field of Classification Search**

None

See application file for complete search history.

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Primary Examiner — Jonathan Crepeau

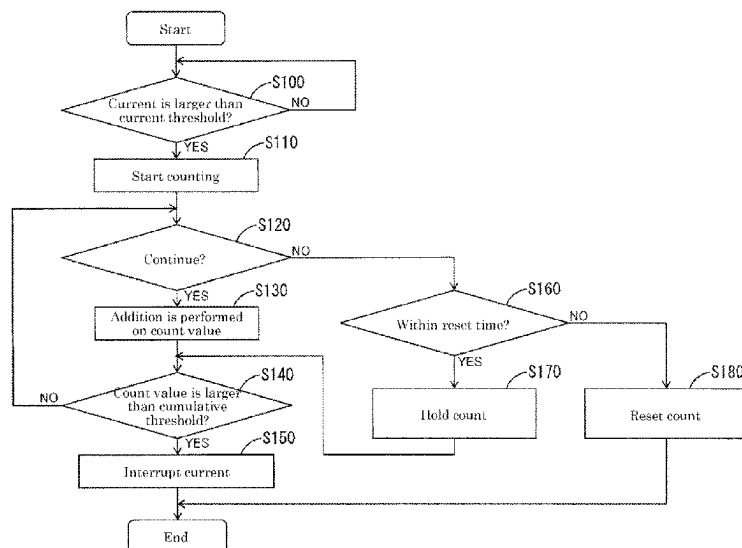
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(57)

ABSTRACT

A protective apparatus of an energy storage device includes a current breaker that interrupts the current of the energy storage device, and a control part. There are a plurality of conditions having different current thresholds and cumulative thresholds, and the control part calculates a cumulative value N of times during which the current exceeds any one of the current thresholds Is, and executes current interruption processing of interrupting the current when the calculated cumulative value N exceeds one of the cumulative thresholds Ns associated with the current threshold Is.

6 Claims, 14 Drawing Sheets



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H01M 50/583 (2021.01)
H02H 3/02 (2006.01)
H02H 3/08 (2006.01)
H02H 3/093 (2006.01)
H02H 7/18 (2006.01)

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(2013.01); **H02H 3/08** (2013.01); **H02H 3/093**
(2013.01); **H02H 7/18** (2013.01); **H02J**
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Fig. 1

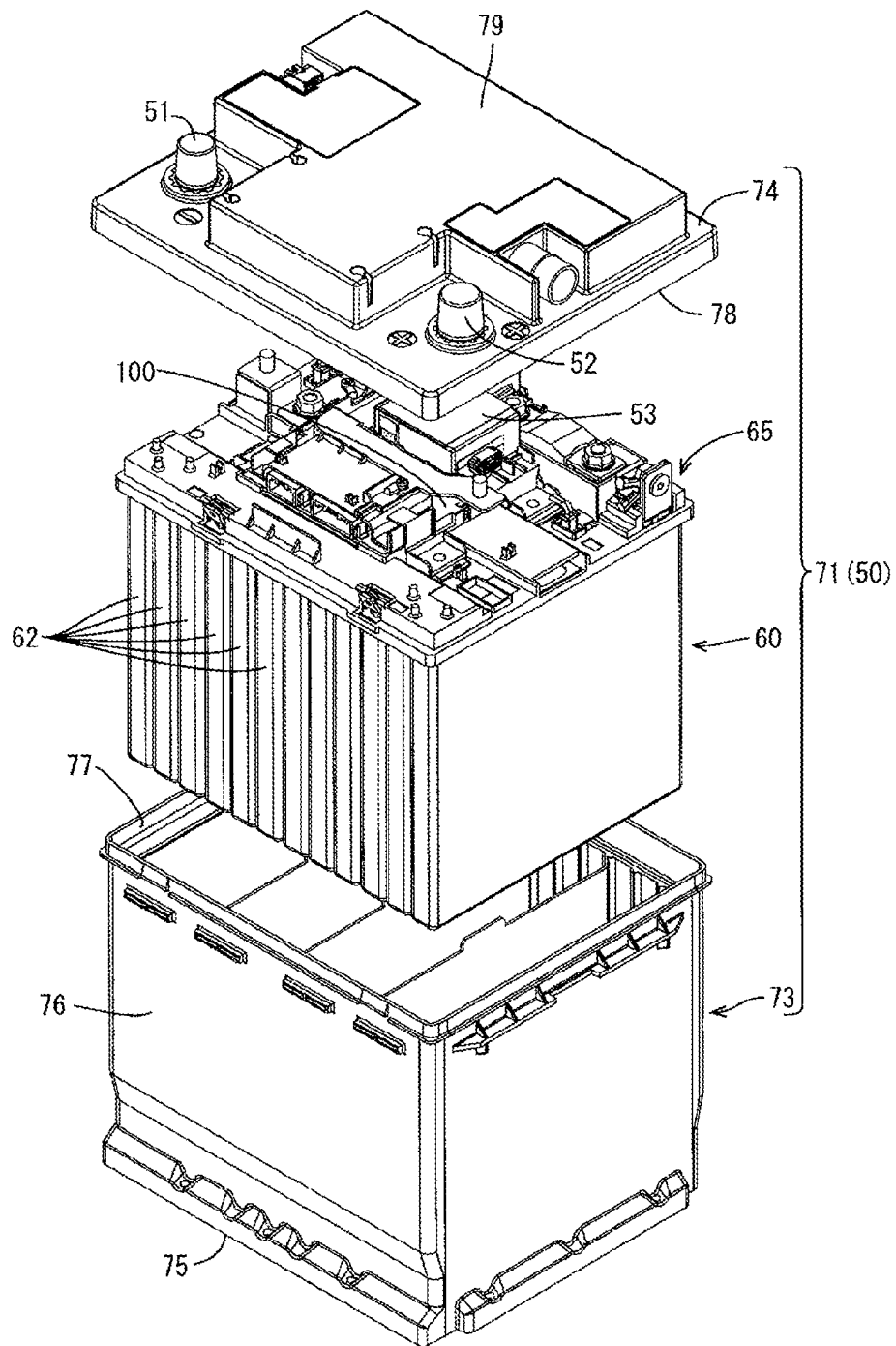


Fig. 2

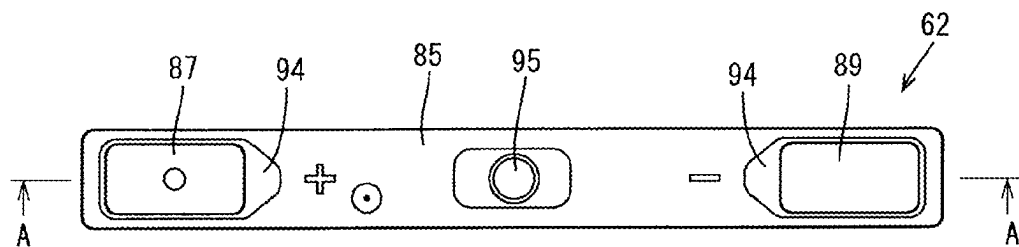


Fig. 3

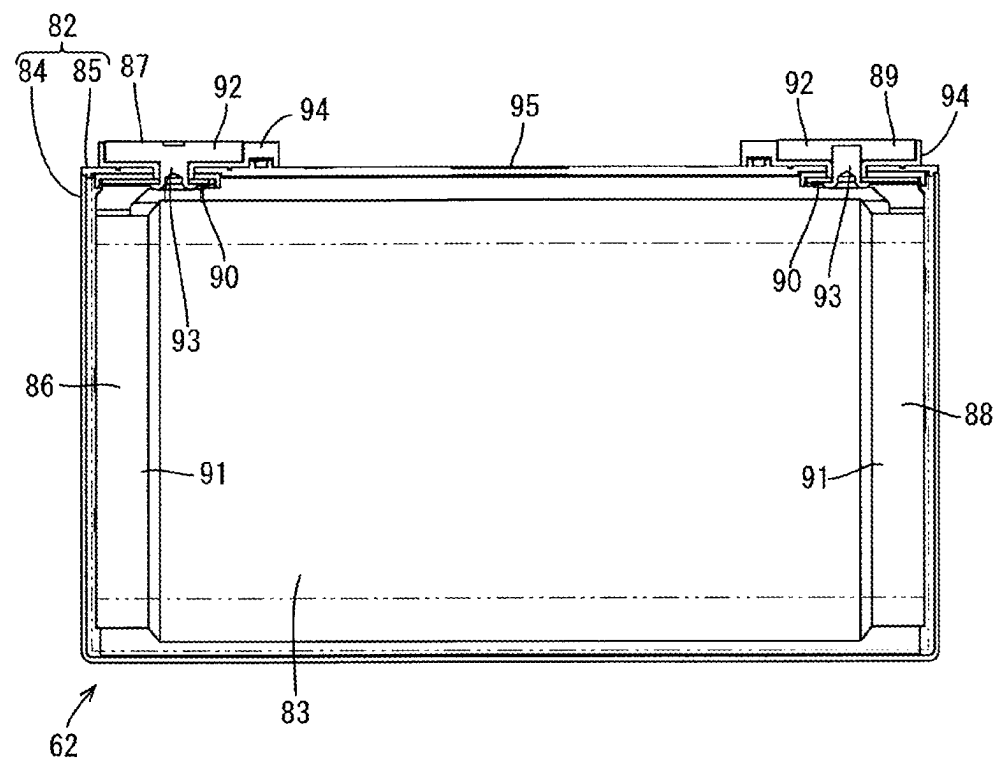
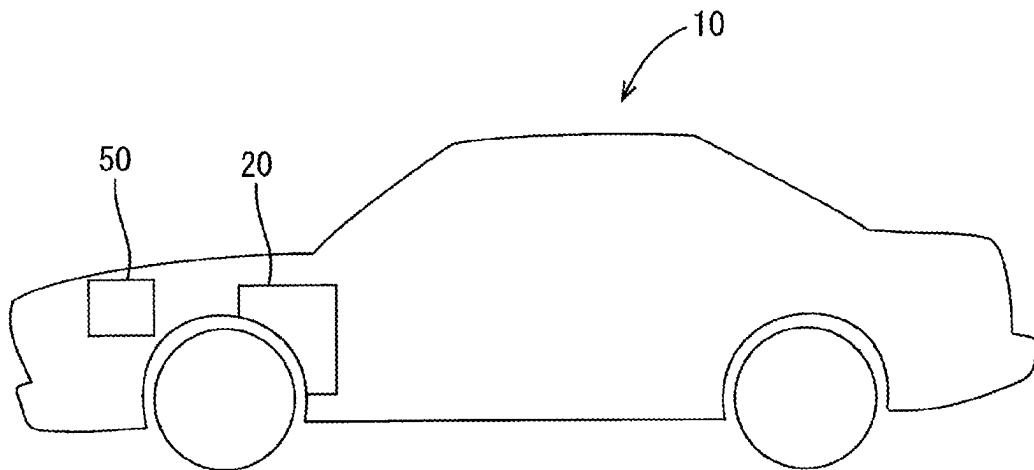


Fig. 4



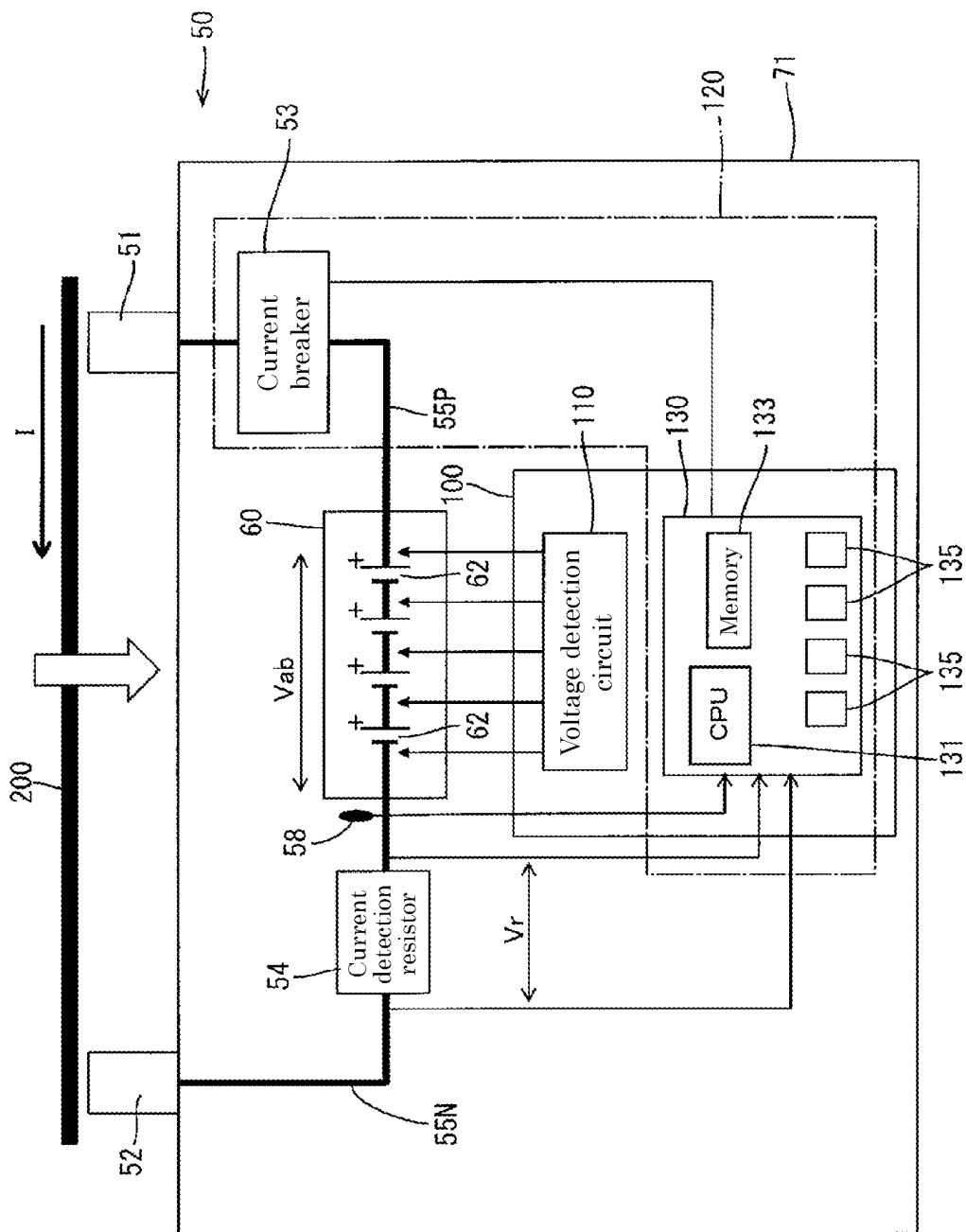
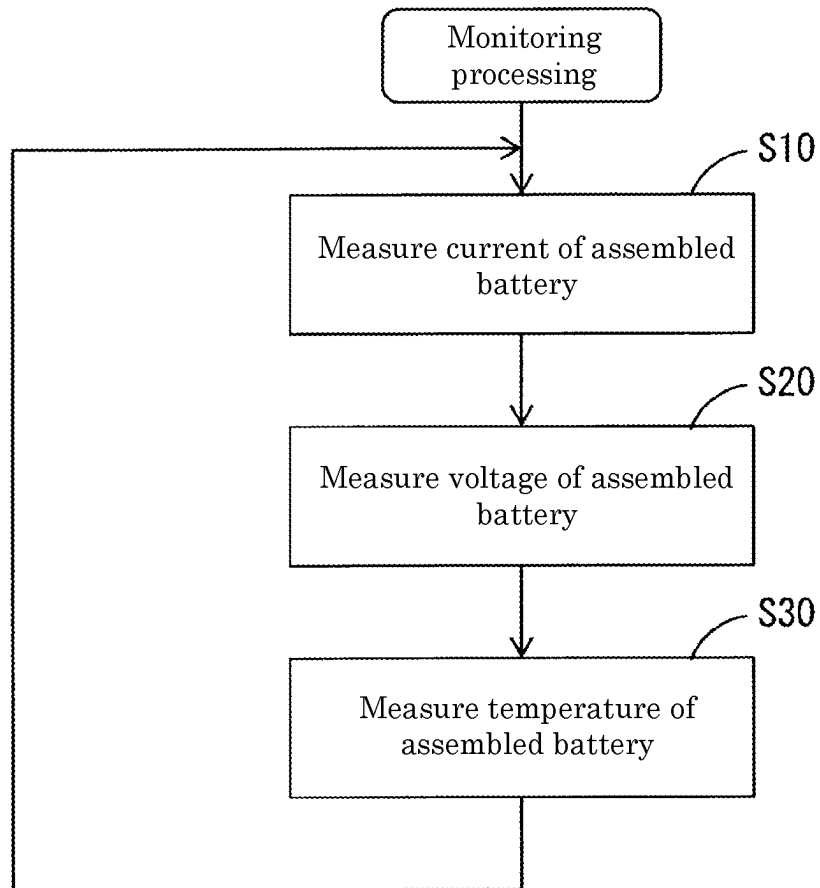


Fig. 5

Fig. 6



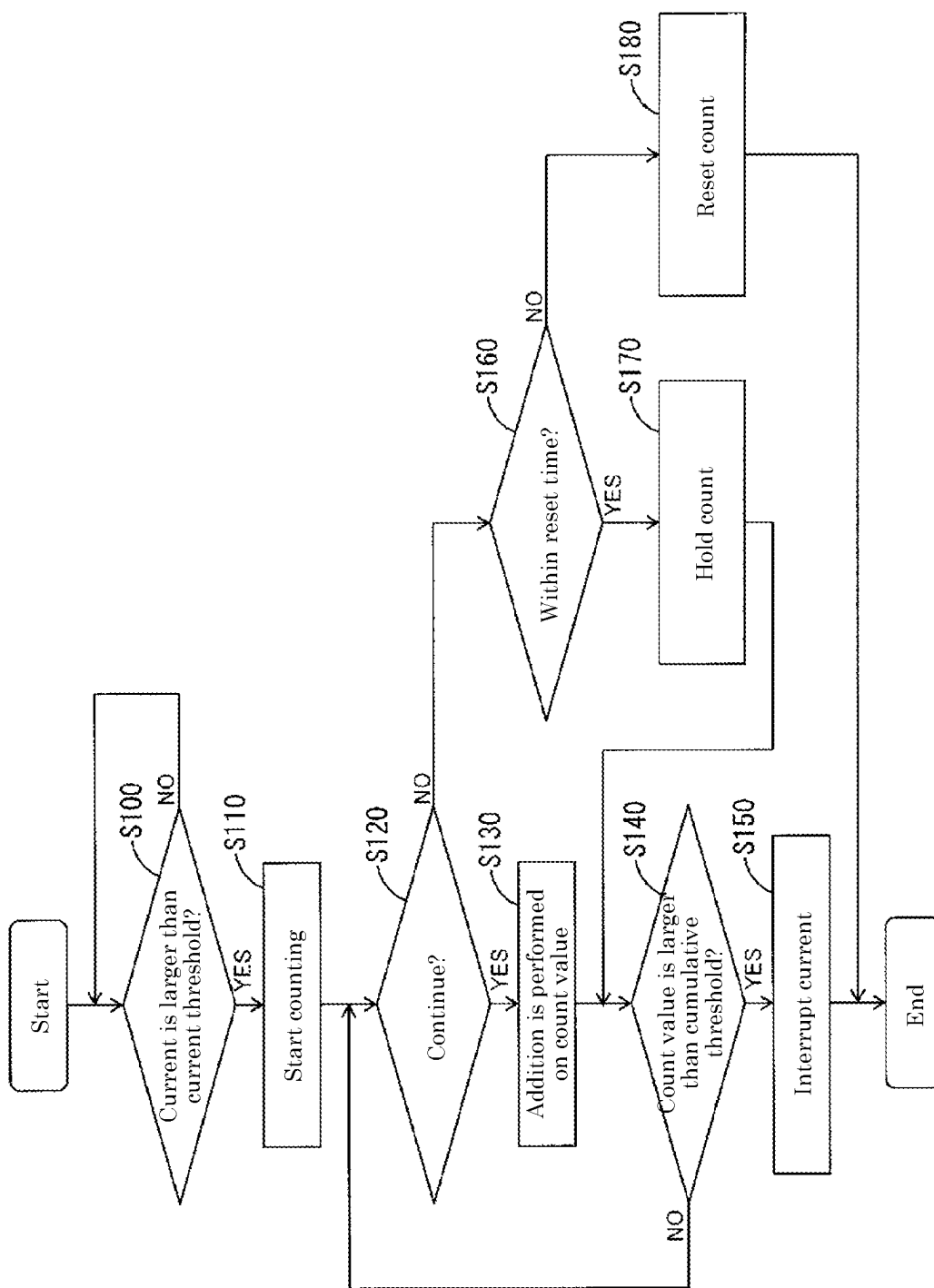


Fig. 7

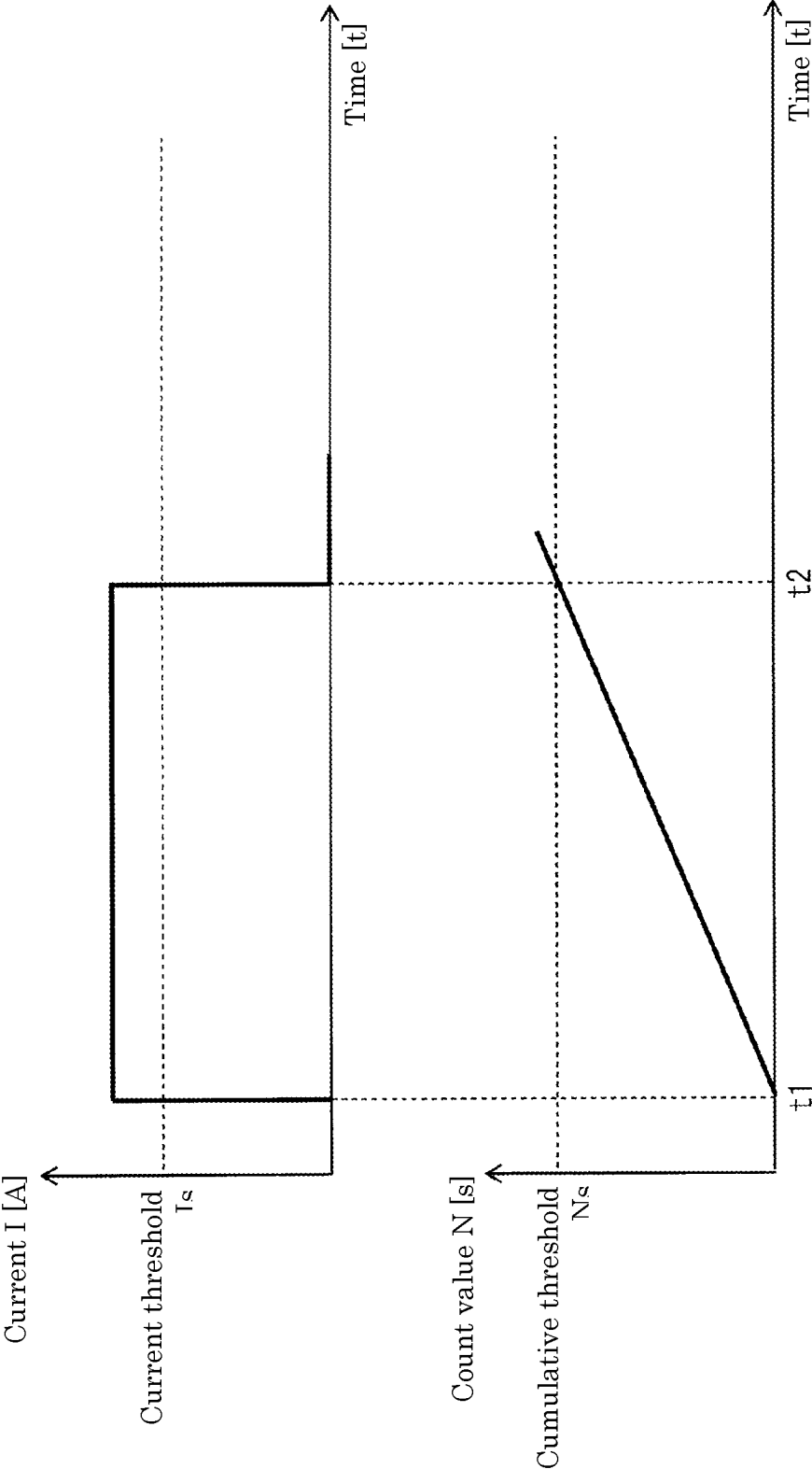


Fig. 8

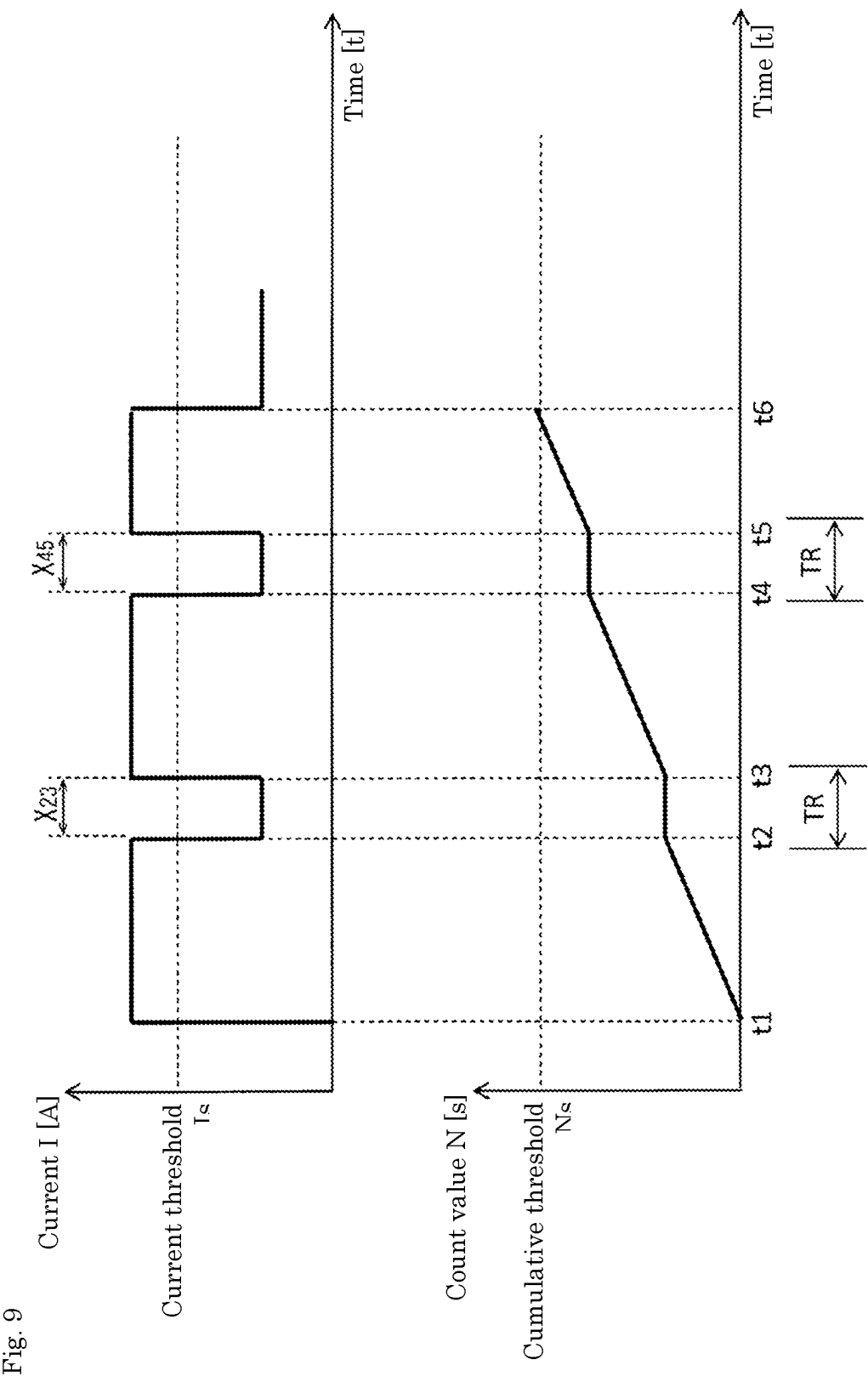


Fig. 10

	Current threshold I_s	Cumulative threshold N_s	Reset time T_R
Current interruption condition 1	1450 A	10 msec	1 sec
Current interruption condition 2	900 A	2 sec	1 sec
Current interruption condition 3	700 A	40 sec	1 sec
Current interruption condition 4	300 A	60 sec	1 sec

Fig. 11

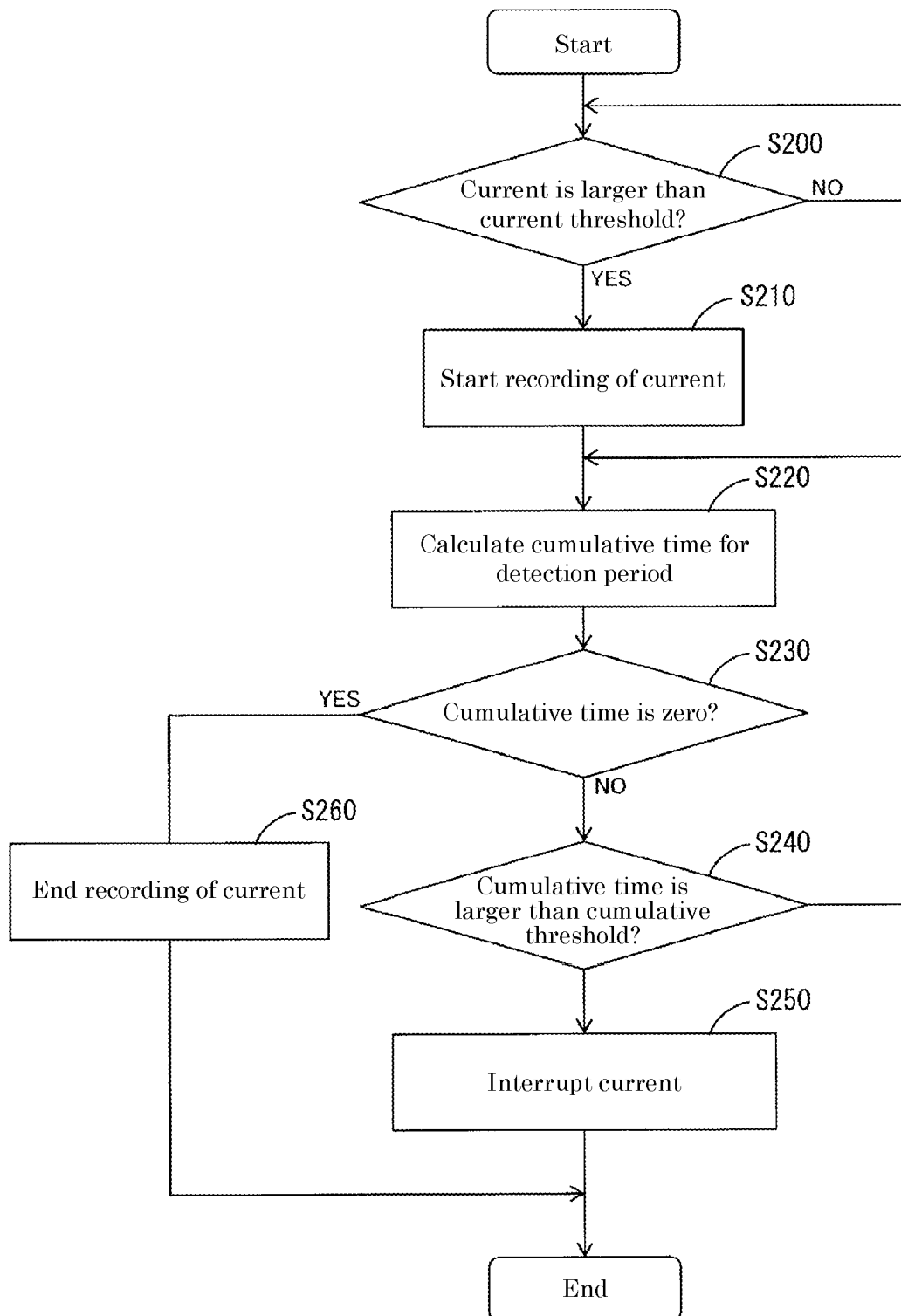
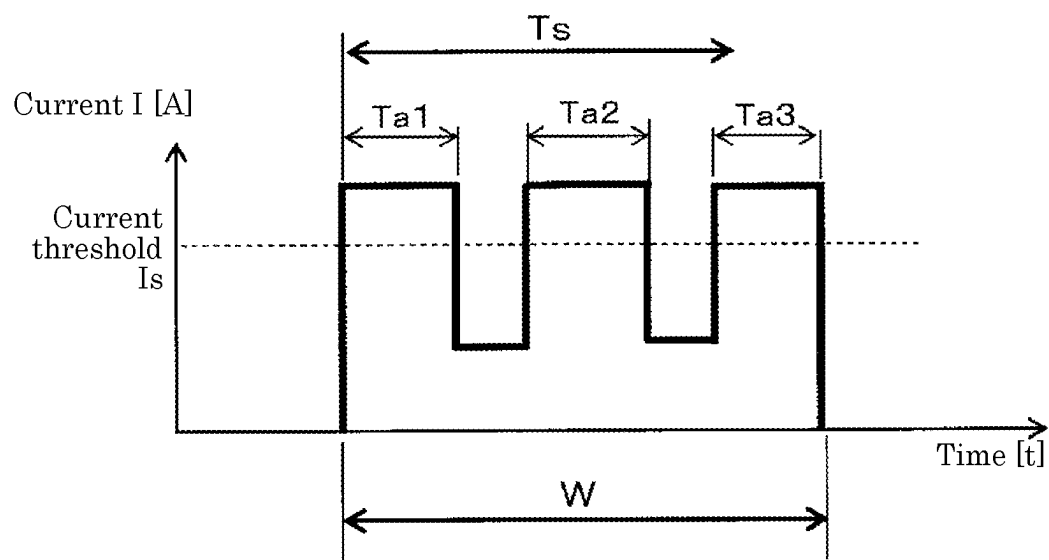


Fig. 12



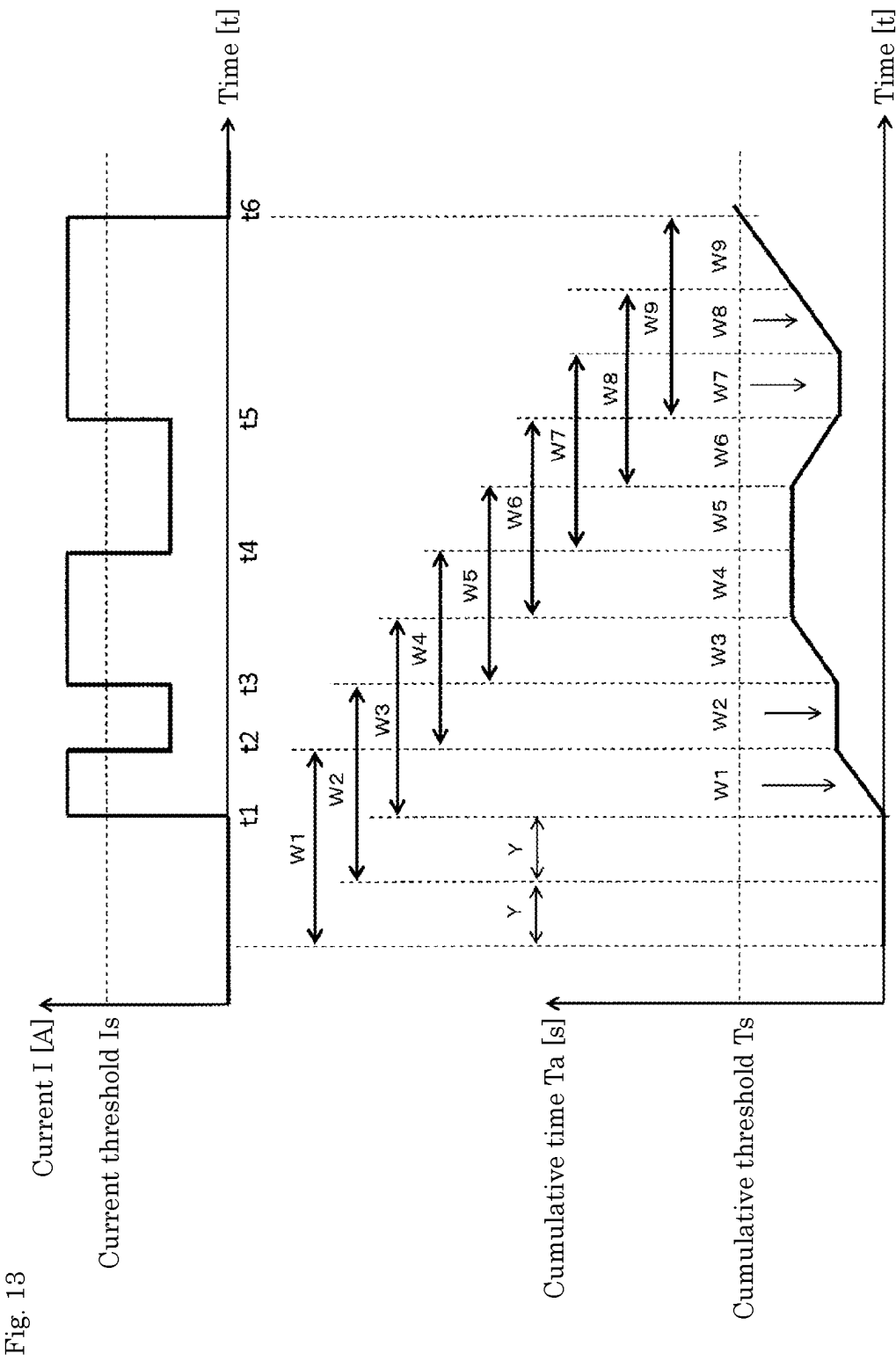


Fig. 14

	Current threshold I_s	Cumulative threshold T_s	Detection period W
Current interruption condition 1	1450 A	10 msec	15 msec
Current interruption condition 2	900 A	2 sec	3 sec
Current interruption condition 3	700 A	40 sec	60 sec
Current interruption condition 4	300 A	60 sec	90 sec

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PROTECTIVE APPARATUS, ENERGY STORAGE APPARATUS, AND METHOD FOR PROTECTING ENERGY STORAGE DEVICE

TECHNICAL FIELD

The present invention relates to a technique for protecting an energy storage device from an overcurrent.

BACKGROUND ART

The energy storage apparatus may be short-circuited between terminals by a tool at the time of assembling work or the like. The energy storage apparatus includes a current breaker such as a relay or a field-effect transistor (FET), and interrupts a current when a short circuit occurs to protect components constituting the energy storage apparatus. Patent Document 1 below describes that when a current continuously exceeds a current threshold for a time longer than a predetermined time, the current is interrupted.

PRIOR ART DOCUMENT

Patent Document

Patent Document 1: WO 2015/182515

SUMMARY OF THE INVENTION

Problems to be Solved by the Invention

In a case where the interruption of a current is determined based on a duration in which a current equal to or larger than a current threshold continuously flows, it may not be possible to interrupt a discontinuous overcurrent in which a current temporarily falls below the current threshold. When there is only one current interruption condition, the current can be interrupted only under one condition, so that the protection of the energy storage device may be insufficient.

An object of the present invention is to protect an energy storage apparatus by interrupting a current against a discontinuous overcurrent.

Means for Solving the Problems

A protective apparatus for an energy storage device according to one aspect of the present invention includes: a current breaker that interrupts a current of the energy storage device; and a control part. There are a plurality of conditions having different current thresholds and cumulative thresholds, and the control part calculates a cumulative value of times during which the current exceeds any one of the current thresholds, and executes current interruption processing of interrupting the current when the calculated cumulative value exceeds one of the cumulative thresholds associated with the current threshold.

A protective apparatus for an energy storage device according to another aspect of the present invention includes: a current breaker that interrupts a current of the energy storage device; a control part; and a communication part. There are a plurality of conditions having different current thresholds and cumulative thresholds, and the control part calculates a cumulative value of times during which the current exceeds any one of the current thresholds, and causes the communication part to transmit an alarm signal when the calculated cumulative value exceeds one of the cumulative thresholds associated with the current threshold.

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The present technique can be applied to a method for protecting an energy storage device, a protection program, and a recording medium on which the protection program has been recorded.

Advantages of the Invention

According to the above aspect, a current can be interrupted to protect the energy storage device against a discontinuous overcurrent.

BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1 is an exploded perspective view of a battery.

FIG. 2 is a plan view of a secondary battery.

FIG. 3 is a cross-sectional view taken along line A-A in FIG. 2.

FIG. 4 is a side view of a vehicle.

FIG. 5 is a block diagram illustrating the electrical configuration of the battery.

FIG. 6 is a flowchart of monitoring processing.

FIG. 7 is a flowchart of protection processing.

FIG. 8 is a diagram illustrating a waveform and a count value of an overcurrent.

FIG. 9 is a diagram illustrating a waveform and a count value of an overcurrent.

FIG. 10 is an explanatory diagram of a current interruption condition.

FIG. 11 is a flowchart of protection processing.

FIG. 12 is an explanatory diagram of a cumulative time.

FIG. 13 is a diagram illustrating a waveform of an overcurrent and a cumulative time.

FIG. 14 is an explanatory diagram of current interruption conditions.

FIG. 15 is a block diagram illustrating the electrical configuration of the battery.

MODE FOR CARRYING OUT THE INVENTION

A protective apparatus for an energy storage device includes: a current breaker that interrupts a current of the energy storage device; and a control part. There are a plurality of conditions having different current thresholds and cumulative thresholds, and the control part calculates a cumulative value of times during which the current exceeds any one of the current thresholds, and executes current interruption processing of interrupting the current when the calculated cumulative value exceeds one of the cumulative thresholds associated with the current threshold.

When the cumulative value of times when the current threshold is exceeded exceeds the cumulative threshold, the current interruption processing is executed, so that the energy storage device can be protected from a discontinuous overcurrent. By preparing a plurality of current interruption conditions having different current thresholds and cumulative thresholds, the number of combinations of the current threshold and the cumulative threshold, with which the current can be interrupted, increases as compared to when there is only one condition. Hence, the protection performance of the energy storage device against an overcurrent can be enhanced as compared to a case where there is only one condition.

The control part may calculate a cumulative value of times during which the current exceeds the current threshold for each condition, and execute current interruption processing of interrupting the current when the calculated cumulative value exceeds the cumulative threshold associated with

the current threshold under any condition. The current interruption processing is executed when the cumulative threshold is exceeded under any one of the plurality of conditions, so that the energy storage device can be protected from an overcurrent with different current values and durations.

A protective apparatus for an energy storage device includes: a current breaker that interrupts a current of the energy storage device; a control part; and a communication part. There are a plurality of conditions having different current thresholds and cumulative thresholds, and the control part calculates a cumulative value of times during which the current exceeds any one of the current thresholds, and causes the communication part to transmit an alarm signal when the calculated cumulative value exceeds one of the cumulative thresholds associated with the current threshold.

For equipment to which the energy storage apparatus supplies power (e.g., electronic or electric equipment mounted on a vehicle), it is undesirable to come into a state where the current from the energy storage apparatus be interrupted to cause a power failure. In some cases, the purpose of protecting a machine that requires power of an energy storage apparatus, such as a vehicle, is prioritized over the purpose of protecting the energy storage apparatus. In such a case, instead of executing the current interruption processing at a time point when the interruption condition is satisfied, equipment outside the energy storage apparatus is notified that the interruption condition is satisfied, that is, an alarm signal is transmitted to the equipment. In this manner, the control part can determine whether or not to execute the current interruption processing based on a purpose that should be prioritized in a situation such as an emergency in cooperation with the equipment outside the energy storage apparatus. Upon reception of the alarm signal from the energy storage apparatus, the equipment outside the energy storage apparatus can proceed with preparation for the current interruption processing and other problem-solving processing.

The current breaker may be provided in a current path connecting the energy storage device and an external terminal, and the conditions may at least include a first condition for determining that a short circuit of the external terminal occurs, and a second condition for determining that a short circuit of a load connected to the external terminal occurs. The current can be interrupted to protect the energy storage device at the time of short circuit between the external terminals or at the time of load short circuit.

The control part may count, as the cumulative value, times during which the current continuously exceeds the current threshold, and in a case where the current falls from a state of exceeding the current threshold, the control part may hold the cumulative value when a time during which the current is below the current threshold is equal to or shorter than a reset time.

When the time during which the current is below the current threshold is equal to or shorter than the reset time, the cumulative value is held. That is, the cumulative value is not reset, and thereafter, when the cumulative value exceeds the cumulative threshold, the current interruption processing is executed. It is thereby possible to protect the energy storage device from the discontinuous overcurrent.

The control part may calculate the cumulative value for each detection period, and may execute the current interruption processing when the cumulative value exceeds the cumulative threshold.

When the cumulative value exceeds the cumulative threshold within the detection period, the current interrup-

tion processing is executed. It is thereby possible to protect the energy storage device from the discontinuous overcurrent.

First Embodiment

1. Description of battery 50

As illustrated in FIG. 1, a battery 50 includes an assembled battery 60, a circuit board unit 65, and a housing 71.

The housing 71 includes a body 73 made of a synthetic resin material and a lid body 74. The body 73 has a bottomed cylindrical shape. The body 73 includes a bottom surface portion 75 and four side surface portions 76. An upper opening 77 is formed in an upper-end portion by the four side surface portions 76.

The housing 71 houses the assembled battery 60 and a circuit board unit 65. The assembled battery 60 has twelve secondary batteries 62. The twelve secondary batteries 62 are connected with three in parallel and four in series. The circuit board unit 65 is disposed in the upper portion of the assembled battery 60.

The lid body 74 closes the upper opening 77 of the body 73. An outer peripheral wall 78 is provided around the lid body 74. The lid body 74 has a protrusion 79 in a substantially T-shape in a plan view. An external terminal 51 of the positive electrode is fixed to one corner of the front portion of the lid body 74, and an external terminal 52 of the negative electrode is fixed to the other corner.

As illustrated in FIGS. 2 and 3, the secondary battery 62 houses an electrode assembly 83 together with a nonaqueous electrolyte in a case 82 having a rectangular parallelepiped shape. The secondary battery 62 is, for example, a lithium ion secondary battery. The case 82 has a case body 84 and a lid 85 for closing an opening at the top of the case body 84.

Although not illustrated in detail, the electrode assembly 83 has a separator, made of a porous resin film, disposed between a negative electrode element formed by applying an active material to a substrate made of copper foil and a positive electrode element formed by applying an active material to a substrate made of aluminum foil. These are all belt-shaped, and are wound in a flat shape so as to be able to be housed in the case body 84 in a state where the negative electrode element and the positive electrode element are displaced from each other on the opposite sides in the width direction with respect to the separator.

The positive electrode element is connected to a positive electrode terminal 87 via a positive current collector 86, and the negative electrode element is connected to a negative electrode terminal 89 via a negative current collector 88. Each of the positive current collector 86 and the negative current collector 88 is made up of a plate-shaped base 90 and legs 91 extending from the base 90. A through hole is formed in the base 90. The leg 91 is connected to the positive electrode element or the negative electrode element. Each of the positive electrode terminal 87 and the negative electrode terminal 89 is made up of a terminal body portion 92 and a shaft 93 protruding downward from the center portion of the lower surface of the terminal body portion 92. Among those, the terminal body portion 92 and the shaft 93 of the positive electrode terminal 87 are integrally formed of aluminum (single material). The negative electrode terminal 89 has the terminal body portion 92 made of aluminum and the shaft 93 made of copper and is assembled with these. The terminal body portions 92 of the positive electrode terminal 87 and the negative electrode terminal 89 are disposed at both ends

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of the lid **85** via gaskets **94** made of an insulating material and are exposed outward from the gaskets **94**.

The lid **85** has a pressure release valve **95**. As illustrated in FIG. 2, the pressure release valve **95** is located between the positive electrode terminal **87** and the negative electrode terminal **89**. The pressure release valve **95** is opened when the internal pressure of the case **82** exceeds a limit value to lower the internal pressure of the case **82**.

As illustrated in FIG. 4, the battery **50** can be used by being mounted on a vehicle **10**. The battery **50** may be for starting an engine **20** mounted on the vehicle **10**. The vehicle **10** may be an automobile or a motorcycle.

FIG. 5 is a block diagram illustrating the electrical configuration of the battery **50**. The battery **50** includes an assembled battery **60**, a current detection resistor **54**, a current breaker **53**, a voltage detection circuit **110**, a management part **130**, and a temperature sensor **58** that detects the temperature of the assembled battery **60**.

The assembled battery **60** includes a plurality of secondary batteries **62**. The twelve secondary batteries **62** are connected with three in parallel and four in series. In FIG. 5, three secondary batteries **62** connected in parallel are represented by one battery symbol. The secondary battery **62** is an example of the “energy storage device”. The battery **50** is rated at 12 V. In the battery **50** rated at 12 V, the distance between the external terminal **51** of the positive electrode and the external terminal **52** of the negative electrode tends to be narrow, and at the time of assembling the battery **50** to the vehicle or some other time, a short circuit (dead short circuit) between the terminals due to a metal material such as a tool is likely to occur as compared to a larger energy storage apparatus.

The assembled battery **60**, the current breaker **53**, and the current detection resistor **54** are connected in series via a power line **55P** and a power line **55N**. The power line **55P** and the power line **55N** are examples of current paths.

The power line **55P** is a power line for connecting the external terminal **51** of the positive electrode and the positive electrode of the assembled battery **60**. The power line **55N** is a power line for connecting the external terminal **52** of the negative electrode to the negative electrode of the assembled battery **60**.

The current breaker **53** is located on the positive electrode side of the assembled battery **60** and is provided on the power line **55P** on the positive electrode side. The current breaker **53** is a semiconductor switch such as FET or a relay. By opening the current breaker **53**, the current of the battery **50** can be interrupted. The current breaker **53** is controlled so as to be closed in a normal state.

The current detection resistor **54** is located on the negative electrode side of the assembled battery **60** and provided on the power line **55N** on the negative electrode. A current **I** of the assembled battery **60** can be measured by detecting a voltage **Vr** between both ends of the current detection resistor **54**.

The voltage detection circuit **110** can detect a voltage **V** of each secondary battery **62** and a total voltage **Vab** of the assembled battery **60**.

The management part **130** is mounted on the circuit board **100** and includes a CPU **131**, a memory **133**, and four counters **135**. The management part **130** performs monitoring processing for the battery **50** based on the outputs of the voltage detection circuit **110**, the current detection resistor **54**, and the temperature sensor **58**.

FIG. 6 is a flowchart of the monitoring processing for the battery **50**. The monitoring processing for the battery **50** includes S10 to S30. The monitoring processing for the

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battery **50** is always executed at a predetermined measurement cycle during the activation of the management part **130** regardless of whether or not the battery **50** is mounted on the vehicle **10**.

In S10, the management part **130** measures the current **I** of the assembled battery **60** based on the voltage **Vr** between both ends of the current detection resistor **54**. The management part **130** measures the voltage **V** of each secondary battery **62** based on the output of the voltage detection circuit **110** in S20, and measures the temperature of the assembled battery **60** based on the output of the temperature sensor **58** in S30.

The management part **130** operates using the assembled battery **60** as a power source, and constantly monitors the state of the battery **60** based on the data of the current **I**, the voltage **V**, and the temperature measured at a predetermined measurement cycle so long as there is no abnormality such as the total voltage **Vab** of the assembled battery **50** falling below the operating voltage.

When the abnormality of the battery **50** is detected, the management part **130** gives a command to the current breaker **53** to interrupt the current **I** and performs the protection operation for the battery **50**. The current breaker **53** and the management part **130** are a protective apparatus **120** of the battery **50**. The management part **130** is an example of a control part.

2. External Short Circuit and Battery Protection

When a metal material such as a tool **200** short-circuits the two external terminals **51**, **52** during assembling work or the like, an overcurrent flows through the assembled battery **60**. When the overcurrent flows, the assembled battery **60** abnormally generates heat. The value of the overcurrent at the time of discharge due to an external short circuit is much larger than the current value in the case of charge abnormality. However, at the time of starting the engine or the like, a very large current value is measured while the discharge is normal. Therefore, at the time of discharge, it is not easy to determine whether an abnormality such as an external short circuit has occurred, or the energy storage apparatus is normally operating from only the current value. The dead short circuit caused by the tool **200** or the like may occur intermittently such that the tool **200** is instantaneously separated from the external terminals **51**, **52** and comes into contact therewith again. Even when the dead short circuit is instantaneously released, the state of the battery **50** does not recover immediately, and damage remains in the battery **50** such that the state of charge (SOC) has deteriorated remarkably.

FIG. 7 is a flowchart of protection processing for the battery **50**. The protection processing for the battery **50** includes S10 to S180. The protection processing for the battery **50** is always executed during the activation of the management part **130** regardless of whether or not the battery **50** is mounted on the vehicle **10**.

In step S100, the management part **130** compares the current **I** measured in the monitoring processing with a current threshold **Is**. When the current **I** is equal to or smaller than the current threshold **Is** (S100: NO), the comparison processing in S100 is executed every time the current measurement is performed in the monitoring processing. The current threshold **Is** is a threshold for determining whether or not the current **I** is an overcurrent.

In the case of the overcurrent (S100: YES), the processing proceeds to S110. When the processing proceeds to S110, the management part **130** starts counting by the counter **135**. The counter **135** is for measuring a cumulative time during which the overcurrent is flowing.

After the counting is started, the processing proceeds to S120. When the processing proceeds to S120, the management part 130 compares the current I measured in the next measurement cycle of the monitoring processing with the current threshold Is and determines whether the overcurrent continues.

When the overcurrent continues (S120: YES), the processing proceeds to S130. When the processing proceeds to S130, the management part 130 adds "+1" to a count value N of the counter 135.

Thereafter, in S140, the management part 130 compares the count value N with a cumulative threshold Ns. When the count value N is smaller than the cumulative threshold Ns (S140: NO), the processing returns to S120. The cumulative threshold Ns is a threshold for determining the accumulation of the overcurrent.

Thereafter, when the overcurrent continues to flow, the count value N is added with "+1" for each measurement cycle of the monitoring processing. The count value N is a cumulative value of times during which the current I exceeds the current threshold Is.

When the count value N reaches the cumulative threshold Ns, YES is determined in the determination processing of S140, and the processing proceeds to S150. When the processing proceeds to S150, the management part 130 gives a command to the current breaker 53 to interrupt the overcurrent (current interruption processing).

When the overcurrent does not continue, that is, when the current I is below the current threshold Is (S120: NO), the processing proceeds to S160.

When the processing proceeds to S160, the management part 130 measures a time during which the current I is below the current threshold Is, and compares the measured time with a reset time TR.

Then, when the time during which the current is below the current threshold Is is shorter than the reset time TR, the processing proceeds to S170. When the processing proceeds to S170, the management part 130 holds the count value N.

Thereafter, the processing proceeds to S140, and when an overcurrent is detected, the management part 130 restarts the counting by the counter 135, and the count value N is subjected to the addition from the held value.

On the other hand, when the time during which the current is below the current threshold Is is longer than the reset time TR, the processing proceeds to S180. When the processing proceeds to S180, the management part 130 resets the count value N. Thereby, the count value N returns to zero.

FIG. 8 is a diagram illustrating a waveform of an overcurrent and transition of the count value N. The waveform of the overcurrent is a continuous waveform that always exceeds the current threshold Is. The count value N is cumulatively subjected to the addition to increase after time t1 at which the overcurrent starts to flow, and the count value N reaches the cumulative threshold Ns at time t2.

When the count value N reaches the cumulative threshold Ns at time t2, current interruption processing (S150) is executed by the management part 130, and the overcurrent is interrupted. The battery 50 can be protected by blocking the overcurrent.

FIG. 9 is a diagram illustrating a current waveform of an overcurrent and transition of the count value N. The waveform of the overcurrent is a discontinuous pulse-like waveform, and the current I is below the current threshold Is from t2 to t3 and from t4 to t5. The lengths of period X₂₃ and period X₄₅ are shorter than the reset time TR.

During a period from time t1 at which the overcurrent starts to flow to time t2, the current I exceeds the current

threshold Is, and the count value N is subjected to the addition every time S130 is executed, to increase with the lapse of time.

In period X₂₃ from time t2 to time t3, the current I is below the current threshold Is, but period X₂₃ is shorter than the reset time TR, so that the count value N is held without being reset.

With the current I exceeding the current threshold Is during a period from time t3 to time t4, the count value N is subjected to the addition every time S130 is executed, to increase from the held value.

In period X₄₅ from time t4 to time t5, the current I is below the current threshold Is, but period X₄₅ is shorter than the reset time TR, so that the count value N is held without being reset.

With the current I exceeding the current threshold Is after time t6, the count value N is subjected to the addition every time S130 is executed, to increase from the held value. Then, the count value N reaches the cumulative threshold Ns at time t6.

When the count value N reaches the cumulative threshold Ns at time t6, current interruption processing (S150) is executed by the management part 130, and the overcurrent is interrupted.

Even when the current I is below the current threshold Is, the count value N is not reset and is held so long as the current I falls within the reset time TR. Therefore, even in a discontinuous overcurrent in which there is a period during which the current I temporarily decreases, it is possible to prevent the count value N from being reset every time the current I falls below the current threshold Is, and it is possible to interrupt the overcurrent when the count value N reaches the cumulative threshold Ns.

FIG. 10 is a diagram illustrating current interruption conditions. The current interruption condition includes items of the current threshold Is, the cumulative threshold Ns, and the reset time TR. There are four current interruption conditions 1 to 4, and the current threshold Is and the cumulative threshold Ns are different from each other. The reset time TR is common to all the conditions 1 to 4.

The current interruption condition 1 is a condition for determining that a short circuit has occurred between the two external terminals 51, 52 (or a condition for interrupting the external short circuit), and each of the current interruption conditions 2 to 4 is a condition for determining that a short circuit has occurred in a load connected to the external terminals 51, 52 (or a condition for interrupting the load short circuit). In the current interruption condition 1, the current threshold Is is 1450 A, and the cumulative threshold Ns is 10 msec. The current interruption condition 1 has a larger current threshold Is and a shorter cumulative threshold Ns than those of the current interruption conditions 2 to 4.

In the current interruption conditions 2 to 4, since the magnitude of the short-circuit current varies depending on how the load is short-circuited, the current threshold Is is set in three stages, and the smaller the current threshold Is, the longer the cumulative threshold Ns.

The management part 130 simultaneously performs the protection processing (S100 to S150) illustrated in FIG. 7 in parallel by using the four counters 135 for the current interruption conditions 1 to 4 and executes the current interruption processing of S150 to interrupt the overcurrent when the count value N reaches the cumulative threshold Ns under any of the current interruption conditions 1 to 4.

By preparing a plurality of current interruption conditions, the number of combinations of the current threshold Is

and the cumulative threshold N_s increases as compared to the case of one condition. Therefore, the current I can be interrupted in any event of a short circuit of the external terminal or a load short circuit.

Second Embodiment

FIG. 11 is a flowchart of the protection processing for the battery 50. The protection processing for the battery 50 is always executed during the activation of the management part 130 regardless of whether or not the battery 50 is mounted on the vehicle 10.

The management part 130 compares the current I measured in the monitoring processing with the current threshold I_s (S200). The current threshold I_s is a threshold for determining whether or not the current I is an overcurrent.

In the case of overcurrent (S200: YES), the management part 130 starts the recording of the current I (S210). The current I is recorded in the memory 133.

After starting the recording, the management part 130 calculates a cumulative time T_a during which the overcurrent flowed in a detection period W (S220). The cumulative time T_a is a cumulative value of the times during which the current I exceeds the current threshold I_s in the detection period W .

As illustrated in FIG. 12, for example, in the detection period W , when there are three periods in which the current I exceeds the current threshold I_s , the total time ($T_{a1}+T_{a2}+T_{a3}$) of three times is the cumulative time T_a .

Thereafter, the management part 130 determines whether the cumulative time T_a is 0 (S230), and when the cumulative time T_a is not 0, the management part 130 determines whether the cumulative time T_a is equal to or longer than the cumulative threshold T_s (S240).

When the cumulative time T_a is 0 (S230: YES), the management part 130 ends the recording of the current I (S260). When the cumulative time T_a is equal to or longer than the cumulative threshold T_s (S240: YES), the current interruption processing of interrupting the current I is performed by the current breaker 53 (S250).

When the cumulative time T_a is smaller than the cumulative threshold T_s (NO in S240), the processing returns to S220, and the management part 130 executes the processing of S220 to S240 for the next detection period W .

FIG. 13 is a diagram illustrating the current waveform of the overcurrent and the transition of the cumulative time T_a . The waveform of the overcurrent is a discontinuous pulse-like waveform, and the current I is below the current threshold I_s from t_2 to t_3 and from t_4 to t_5 .

The recording of the current I is started from time t_1 when the current I exceeds the current threshold I_s . The management part 130 calculates the cumulative time T_a for the detection period W_1 and compares the cumulative time T_a with the cumulative threshold value T_s . When the cumulative time T_a does not exceed the cumulative threshold T_s , the cumulative time T_a is calculated and compared with the cumulative threshold T_s for the next detection period W_2 .

The cumulative time T_a does not reach the cumulative threshold T_s in the detection periods W_1 to W_8 and reaches the cumulative threshold T_s in the detection period W_9 . Thus, at time t_6 when the detection period W_9 has elapsed, the current interruption processing (S250) is executed by the management part 130, and the overcurrent is interrupted.

Each of the detection periods W_1 to W_9 is shifted by cycle Y and is continuous while overlapping each other. In this way, the detection interval of the cumulative time T_a can be

shortened, so that the current interruption processing (S250) can be quickly executed when a short circuit occurs.

FIG. 14 is a diagram illustrating current interruption conditions. The current interruption condition includes items of the current threshold I_s , the cumulative threshold T_s , and the detection period W . There are four types, 1 to 4, of current interruption conditions, and the current threshold I_s , the cumulative threshold T_s , and the detection period W are different among the conditions.

The current interruption condition 1 is a first condition for interrupting a short circuit between the two external terminals 51, 52. Each of the current interruption conditions 2 to 4 is a second condition for interrupting a short circuit of a load connected to the external terminals 51, 52.

The management part 130 simultaneously performs the protection processing (S200 to S260) illustrated in FIG. 11 in parallel for the current interruption conditions 1 to 4 and performs the current interruption processing of S250 to interrupt the overcurrent when the cumulative time T_a reaches the cumulative threshold T_s under any of the current interruption conditions.

Other Embodiments

The present invention is not restricted to the embodiments described in the above description and the drawings, but, for example, the following embodiments are included in the technical scope of the present invention.

(1) In the above embodiment, the secondary battery 62 has been exemplified as an example of the energy storage device. The energy storage device is not limited to the secondary battery 62 but may be a capacitor. The secondary battery 62 is not limited to a lithium ion secondary battery but may be another nonaqueous electrolyte secondary battery. A lead-acid battery or the like can also be used. The energy storage device is not limited to a case where a plurality of energy storage devices are connected in series but may be connected in series or may have a single cell structure.

(2) In the above embodiments, the battery 50 has been used for a vehicle. The use of the battery 50 is not limited to a specific use. The battery 50 may be used for various uses such as a use for a moving body (a vehicle, a ship, an automatic guided vehicle (AGV), etc.) and an industrial use (an energy storage apparatus for an uninterruptible power system or a photovoltaic power generating system).

(3) In the above embodiment, the management part 130 has been provided inside the battery 50. The battery 50 only needs to include at least meters such as the current detection resistor 54 and the voltage detection circuit 110 and the current breaker 53, and the management part 130 may be outside the apparatus of the battery 50.

(4) In the above embodiment, the current breaker 53 has been disposed in the power line 55P of the positive electrode, and the current detection resistor 54 has been disposed in the power line 55N of the negative electrode. Conversely, the current detection resistor 53 may be disposed in the power line 55P of the positive electrode, and the current detection resistor 54 may be disposed in the power line 55N of the negative electrode.

(5) In the above embodiment, the protection processing (S200 to S260) has been simultaneously performed in parallel for the current interruption conditions 1 to 4, and the current interruption processing has been executed to interrupt the overcurrent when the cumulative time T_a reaches the cumulative threshold T_s under any of the current interruption conditions. In addition, the protection processing

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(S200 to S260) may be performed for any one of the four conditions of the current interruption conditions 1 to 4, and the current interruption processing may be executed to interrupt the overcurrent when the count value N reaches the cumulative threshold Ns. For example, when it is predicted that the external short circuit is likely to occur, the protection processing (S200 to S260) may be executed only for the current interruption condition 1, and the current interruption processing may be executed to interrupt the overcurrent when the count value N reaches the cumulative threshold Ns. When the current interruption condition is selected, a current interruption condition corresponding to a short circuit having a high occurrence probability may be selected. The number of current interruption conditions to be selected is not limited to one but may be two. That is, at least one or more conditions may be selected. The management part 130 may calculate a cumulative value of times during which the current I exceeds any of the current thresholds Is, and execute the current interruption processing when the calculated cumulative value exceeds one of the cumulative thresholds associated with the current threshold Is.

(6) In the above embodiment, the control part has calculated the cumulative value of the times during which the current exceeds any of the current thresholds, and executed the current interruption processing of interrupting the current when the calculated cumulative value exceeds a cumulative threshold associated with the current threshold. Alternatively, the control part may calculate a cumulative value of times during which the current exceeds any of the current thresholds, and cause the communication part to transmit an alarm signal when the calculated cumulative value exceeds a cumulative threshold associated with the current threshold.

As illustrated in FIG. 15, the protective apparatus 120 may include a communication part 137 controlled by the management part 130. The housing 71 may include a communication connector 138 on the lid body 74, for example. The communication part 137 may be communicably connected to a controller of the vehicle outside the battery, such as an electronic control unit (ECU), via the communication connector 138.

Instead of executing the current interruption processing when the interruption condition is satisfied, the management part 130 notifies the ECU outside the battery that the interruption condition has been satisfied via the communication part 137, that is, transmits an alarm signal, and determines whether or not to execute the current interruption processing in cooperation with the ECU. Upon reception of the alarm signal, the ECU can proceed with preparation for the current interruption processing, processing for avoiding the current interruption processing such as stopping the operation of some loads, and other problem-solving processing.

(7) The present technique can be applied to a protection program for an energy storage device. The protection estimation program for the energy storage device is a program for causing a computer to execute the following processing. The protection estimation program is a program for causing the computer to execute current interruption processing in which a current interruption condition for interrupting a current of an energy storage device includes a plurality of conditions with different current thresholds and cumulative thresholds, and the control part calculates a cumulative value of times during which the current exceeds any one of the current thresholds, and interrupts the current when the calculated cumulative value exceeds one of the cumulative thresholds associated with the current threshold. The present technique can be applied to a recording medium in which the

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protection program for the energy storage device is recorded. The computer is, for example, the management part 130. The energy storage device is, for example, the secondary battery 62. The protection program can be recorded in a recording medium such as a read-only memory (ROM).

DESCRIPTION OF REFERENCE SIGNS

10: vehicle
 50: battery (energy storage apparatus)
 53: current breaker
 54: current detection resistor
 60: assembled battery
 62: secondary battery (energy storage device)
 120: protective apparatus
 130: management part (control part)
 131: CPU
 133: memory
 135: counter
 N: count value (cumulative value)
 Ns: cumulative threshold
 Is: current threshold
 Ta: cumulative time (cumulative value)
 Ts: cumulative threshold

The invention claimed is:

1. A protective apparatus for an energy storage device, comprising:
 - a current breaker that interrupts a current of the energy storage device; and
 - a control part,
 wherein the control part calculates a cumulative value of times during which the current exceeds a current threshold, and executes current interruption processing of interrupting the current when the calculated cumulative value exceeds a cumulative threshold associated with the current threshold, and
- the control part counts, as the cumulative value, times during which the current continuously exceeds the current threshold, and in a case where the current falls from a state of exceeding the current threshold, the control part holds the cumulative value when a time during which the current is below the current threshold is equal to or shorter than a reset time.
2. A protective apparatus for an energy storage device, comprising:
 - a current breaker that interrupts a current of the energy storage device; and
 - a control part,
 wherein there are a plurality of conditions having different current thresholds and cumulative thresholds, and the control part calculates a cumulative value of times during which the current exceeds any one of the current thresholds, and executes current interruption processing of interrupting the current when the calculated cumulative value exceeds one of the cumulative thresholds associated with the current threshold,
- the current breaker is provided in a current path connecting the energy storage device and an external terminal, and
- the conditions at least include
 - a first condition for determining that a short circuit of the external terminal occurs, and
 - a second condition for determining that a short circuit of a load connected to the external terminal occurs.

3. An energy storage apparatus comprising:
an energy storage device; and
the protective apparatus according to claim 1.
4. The energy storage apparatus according to claim 3,
wherein the energy storage apparatus is rated at 12 V. 5
5. A method for protecting an energy storage device, the
method comprising:
by a control part, calculating a cumulative value of times
during which the current exceeds a current threshold,
and executing current interruption processing of inter- 10
rupting the current when the calculated cumulative
value exceeds a cumulative threshold associated with
the current threshold, and
calculating, as the cumulative value, times during which
the current continuously exceeds the current threshold, 15
and in a case where the current falls from a state of
exceeding the current threshold, holding the cumulative
value when a time during which the current is below the
current threshold is equal to or shorter than a reset time.
6. A non-transitory computer readable medium storing 20
computer executable instructions according to the method of
claim 5.

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