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Purchase et al.

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(54) **TRANSFER PRINTING STAMPS AND METHODS OF STAMP DELAMINATION**

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(22) Filed: **Oct. 10, 2023**

(65) **Prior Publication Data**

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Related U.S. Application Data

(63) Continuation-in-part of application No. 17/886,985, filed on Aug. 12, 2022.

(60) Provisional application No. 63/414,985, filed on Oct. 11, 2022, provisional application No. 63/233,946, filed on Aug. 17, 2021.

(51) **Int. Cl.**
H01L 23/00 (2006.01)
H01L 21/683 (2006.01)

(52) **U.S. Cl.**
CPC **H01L 21/6835** (2013.01); **H01L 24/75** (2013.01); **H01L 24/94** (2013.01); **H01L 2221/68318** (2013.01); **H01L 2224/75305** (2013.01); **H01L 2224/75315** (2013.01); **H01L 2224/94** (2013.01)

(58) **Field of Classification Search**
CPC H01L 21/6835; H01L 24/75; H01L 24/94; H01L 2221/68318; H01L 2224/75305; H01L 2224/75315; H01L 2224/94
See application file for complete search history.

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Primary Examiner — Christopher E Mahoney

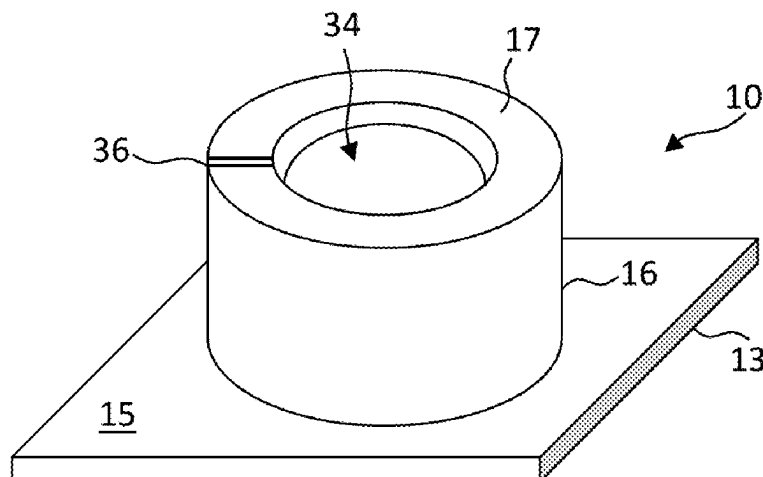
Assistant Examiner — Marissa Ferguson-Samreth

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(57) **ABSTRACT**

A stamp for micro-transfer printing includes a support having a support surface and posts disposed on the support surface. Each post has a proximal end in contact with the support and a distal end extending away from the support. The post has a post surface on the distal end. The post surface is a structured surface comprising spatially separated ridges that extend in a ridge direction entirely across the post surface and can be operable to form multiple delamination fronts when a first side of a micro-device is in contact with the post surface, a second side of the micro-device is in contact with a target surface of a target substrate, and the support is moved in a horizontal direction parallel to the target substrate surface. The post surface or ridges can be rectangular or non-rectangular with opposing edges having different lengths.

22 Claims, 26 Drawing Sheets



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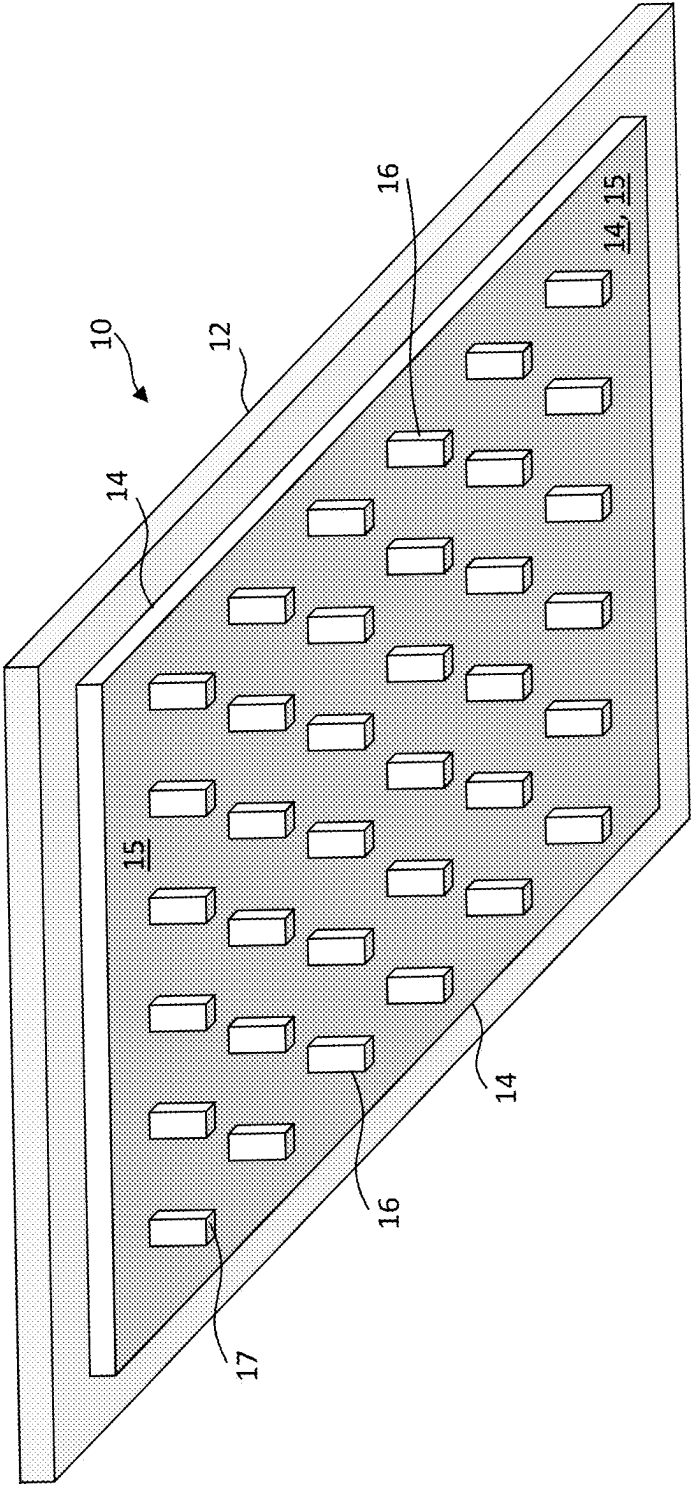


FIG. 1A

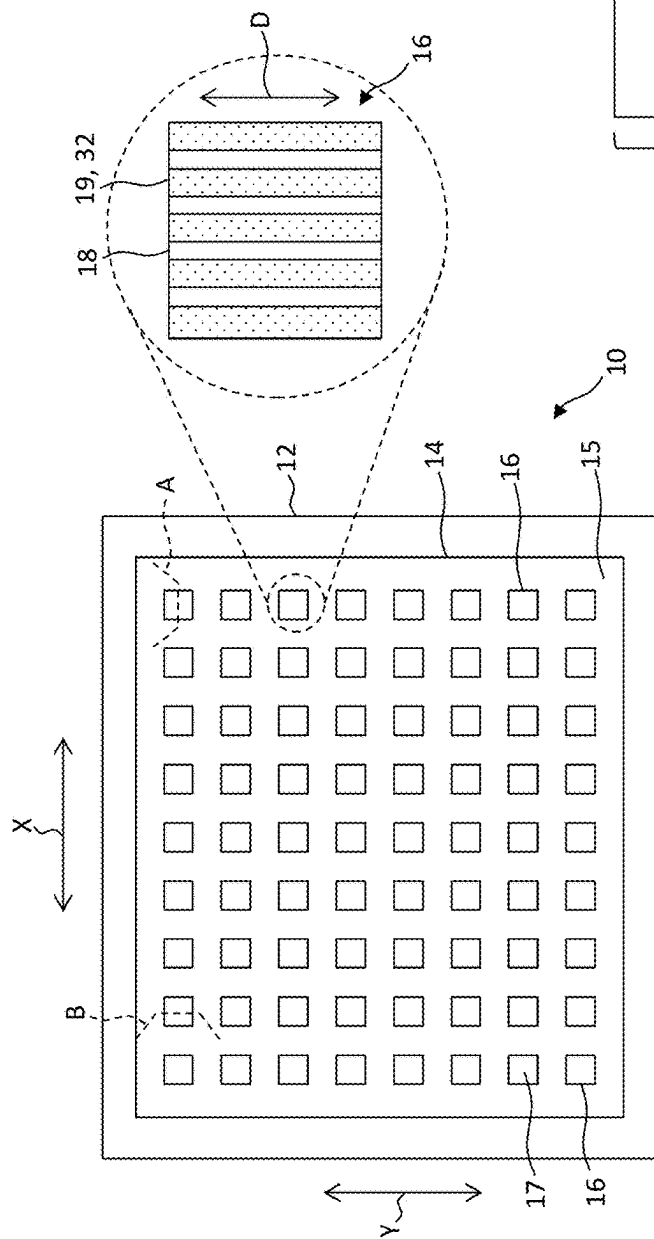


FIG. 1B

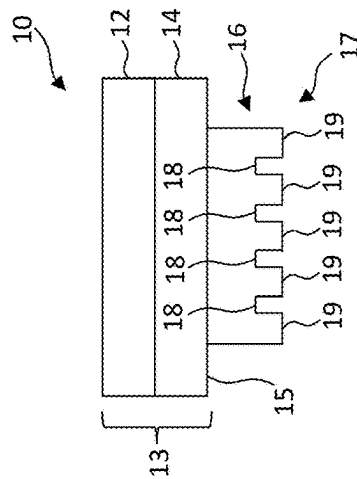


FIG. 1C

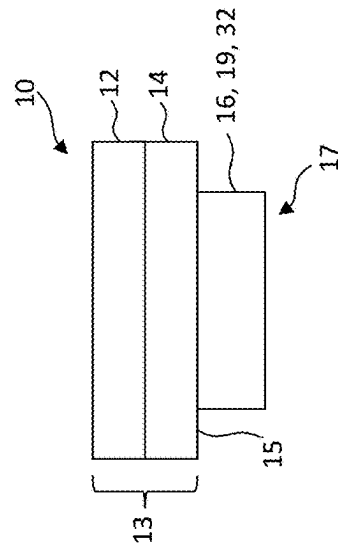


FIG. 1D

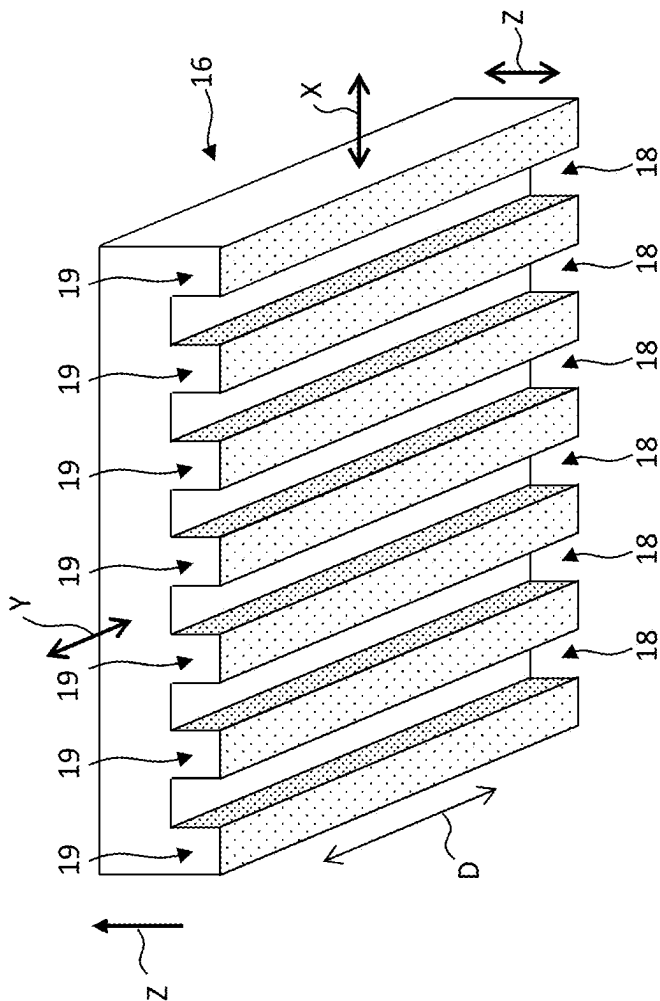


FIG. 2

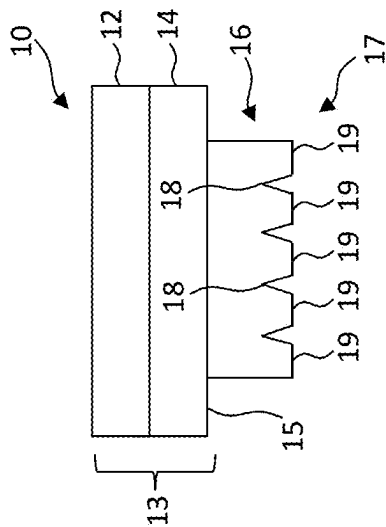


FIG. 3A

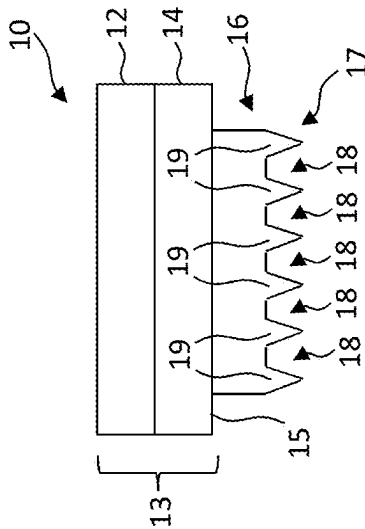
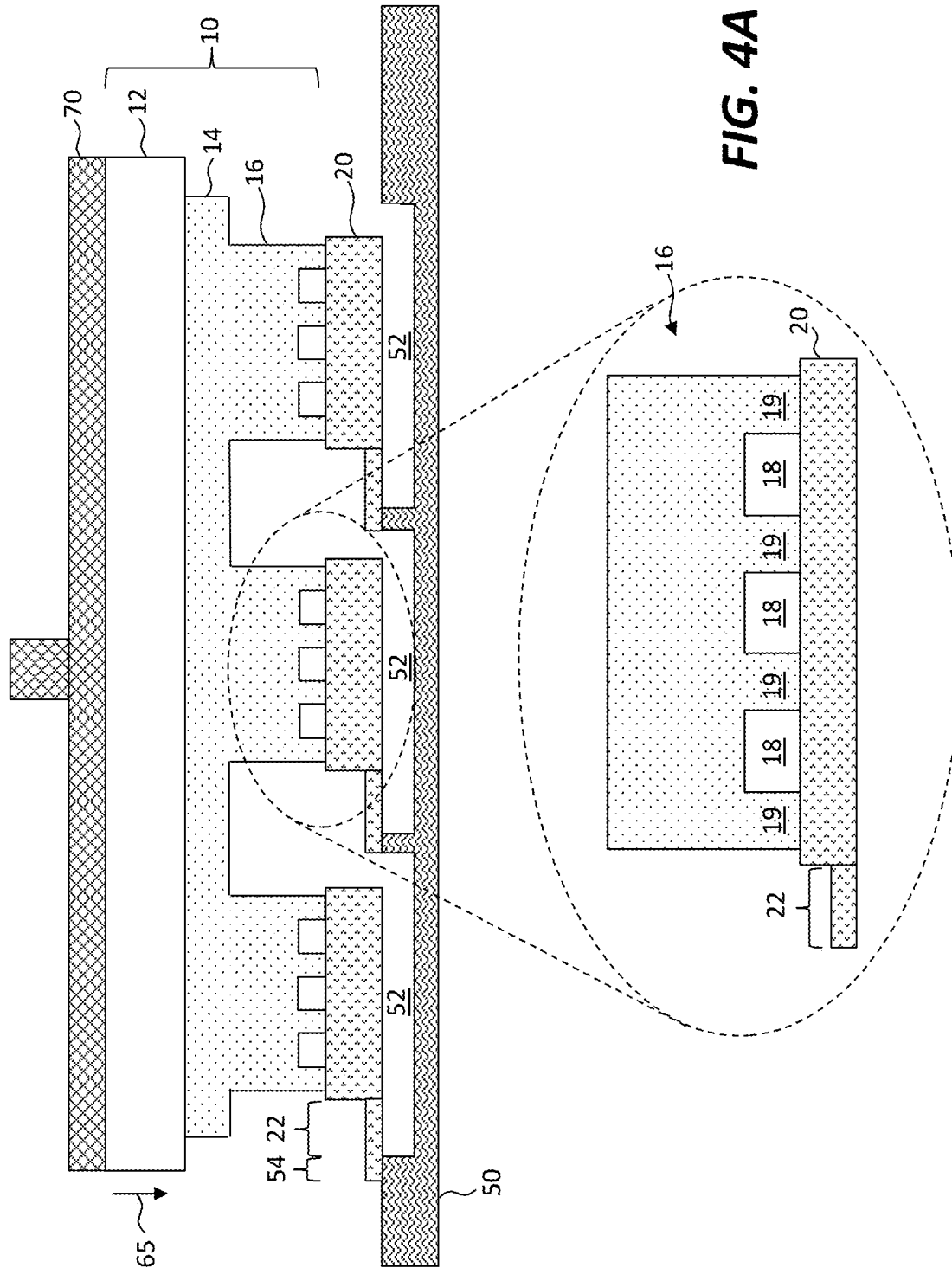
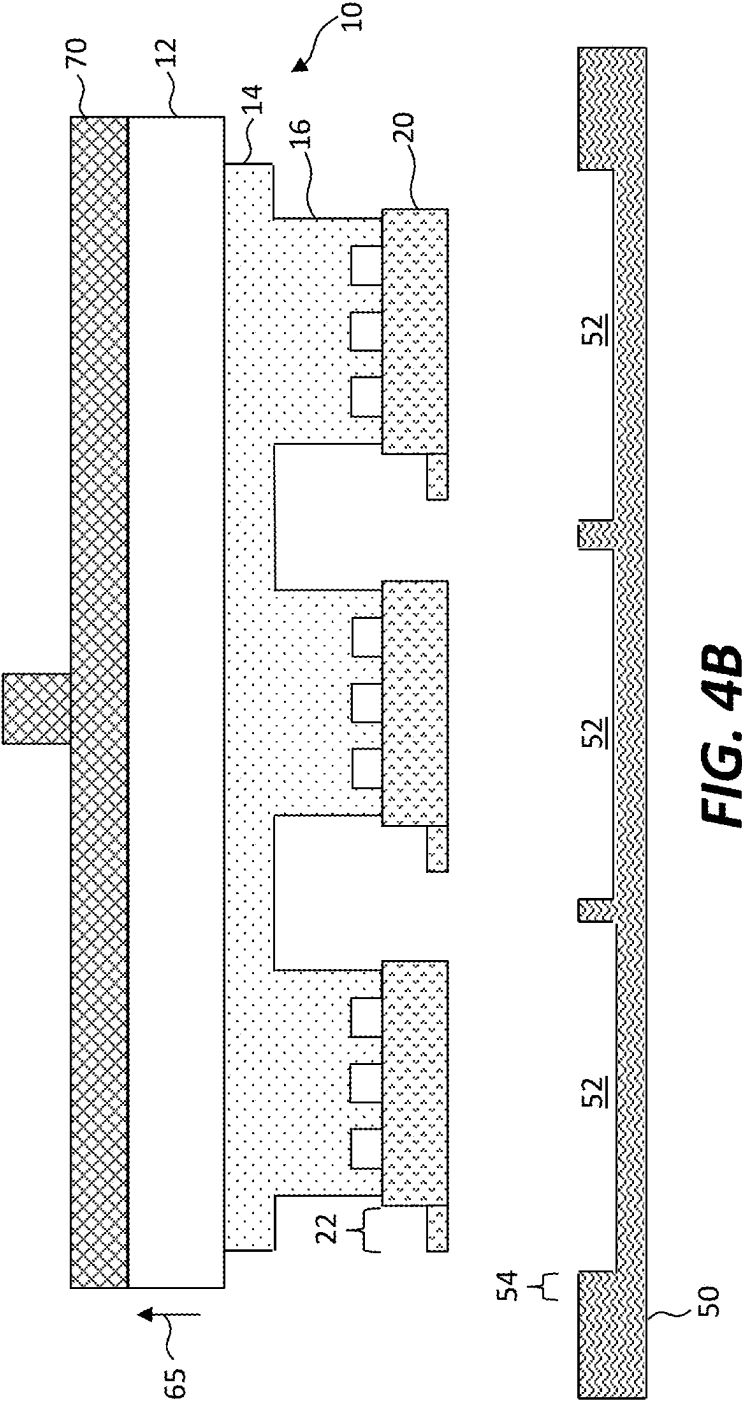


FIG. 3B





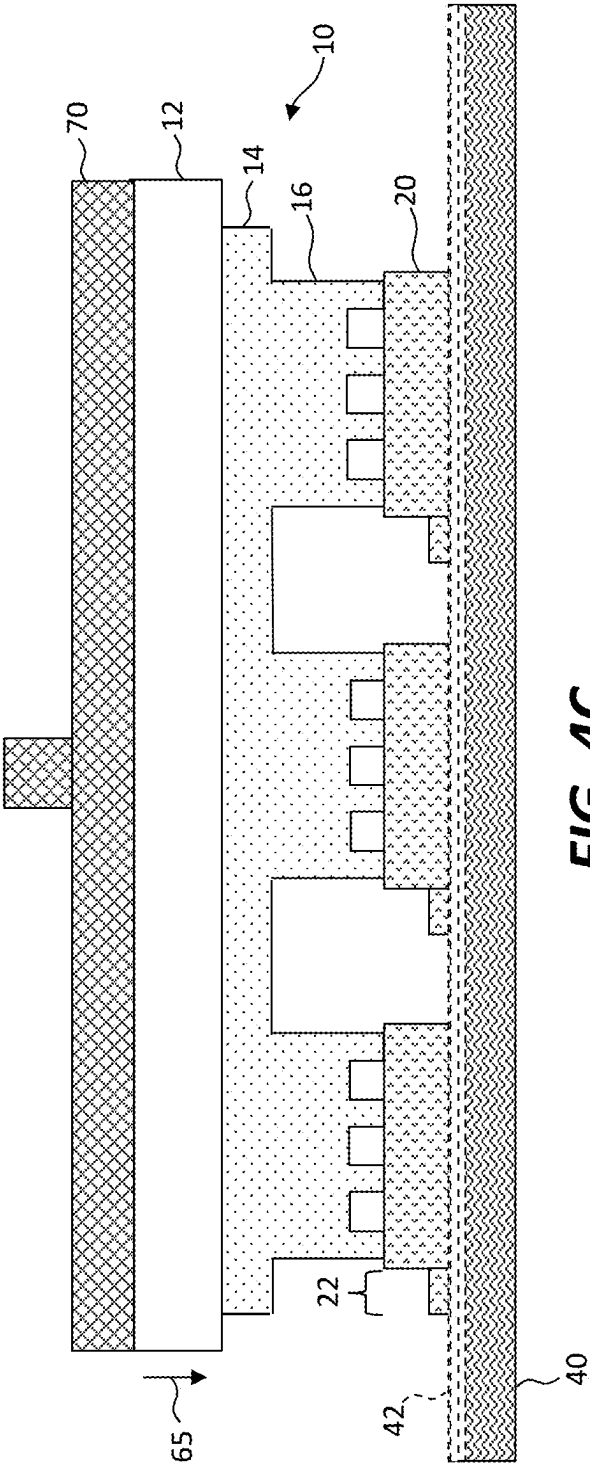
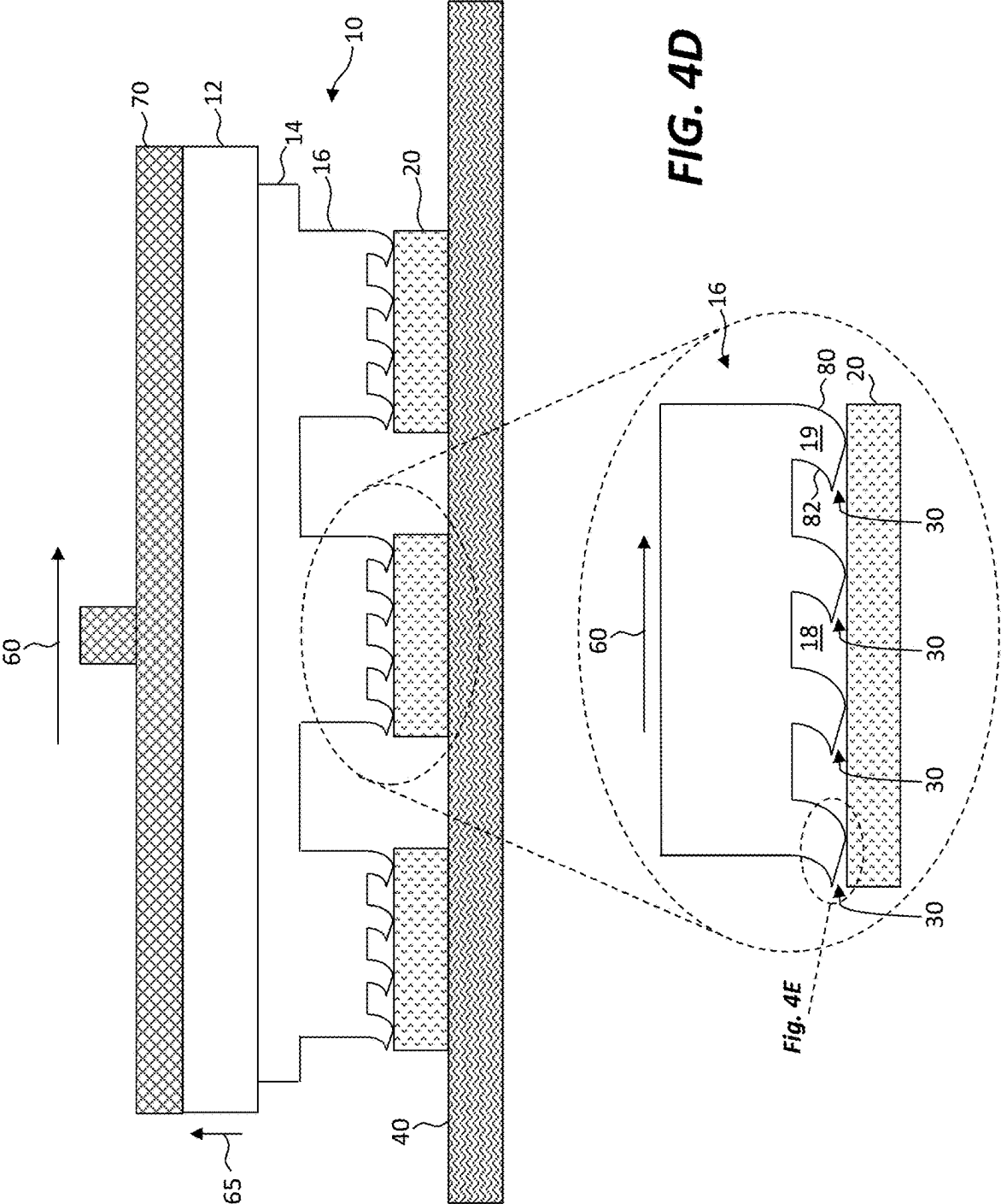


FIG. 4C



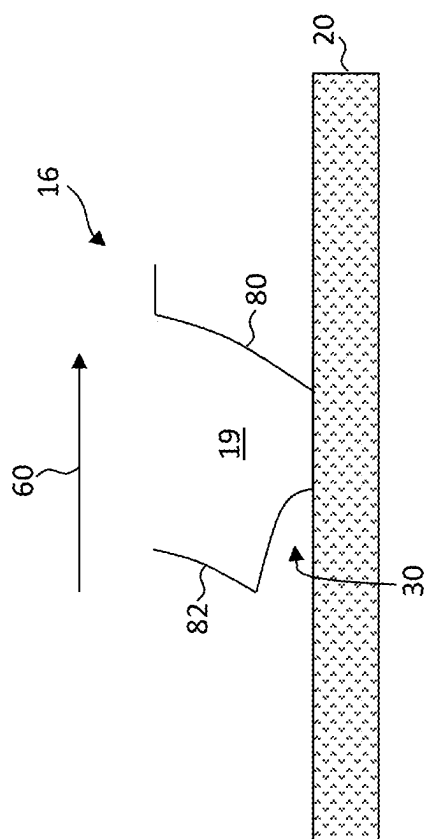


FIG. 4E

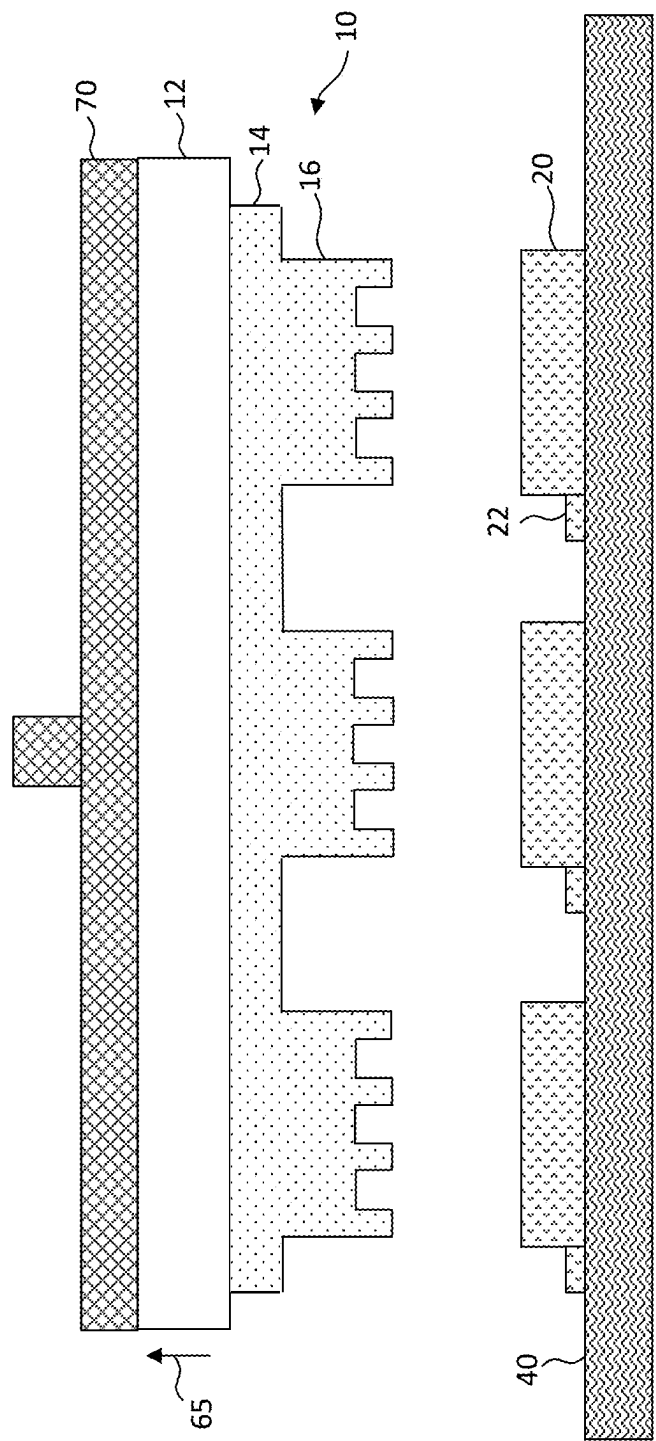
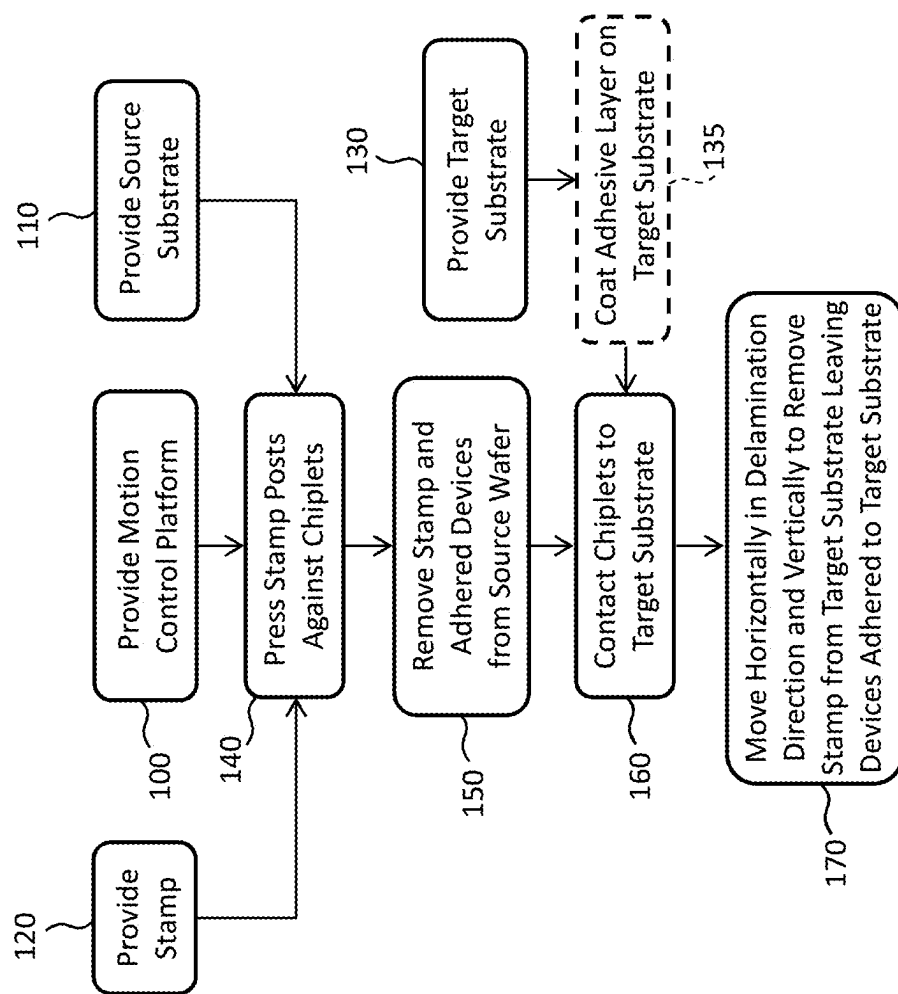


FIG. 4F

**FIG. 5**

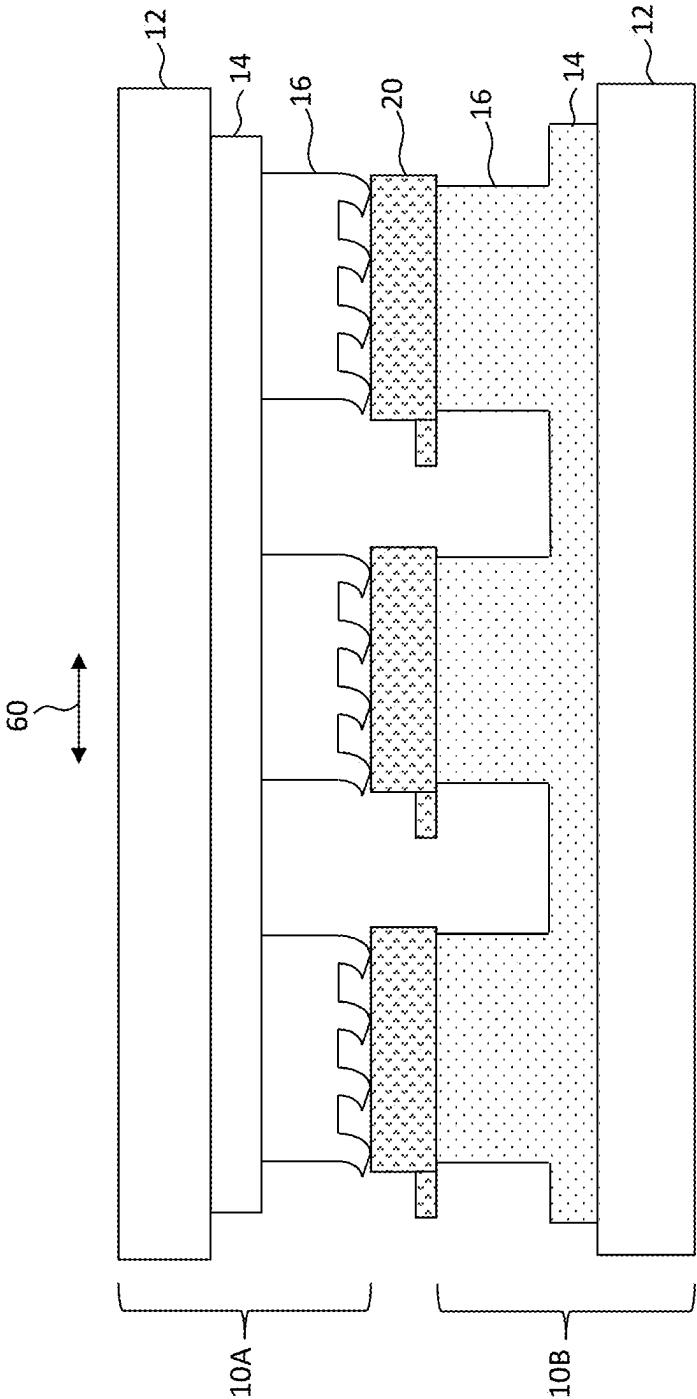
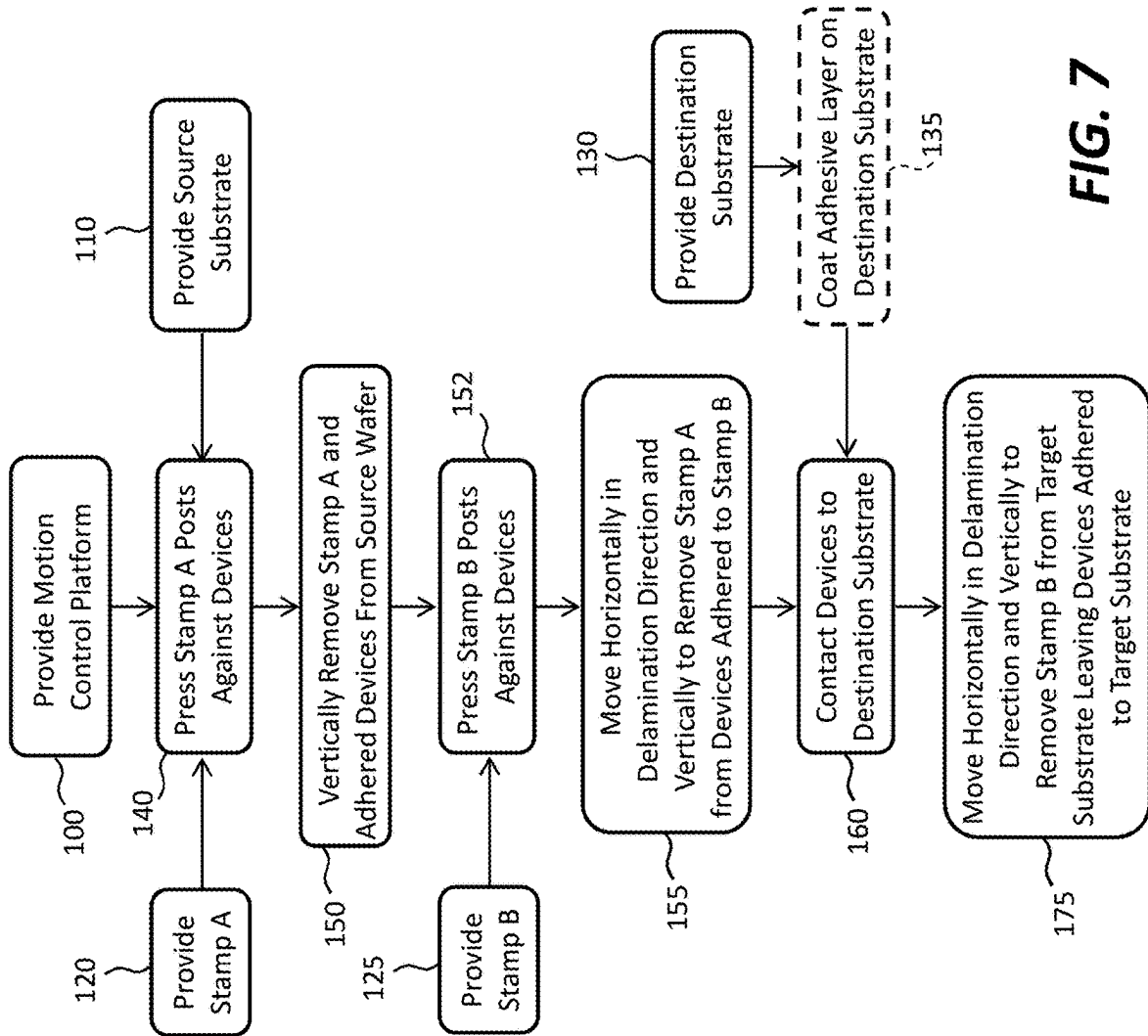


FIG. 6



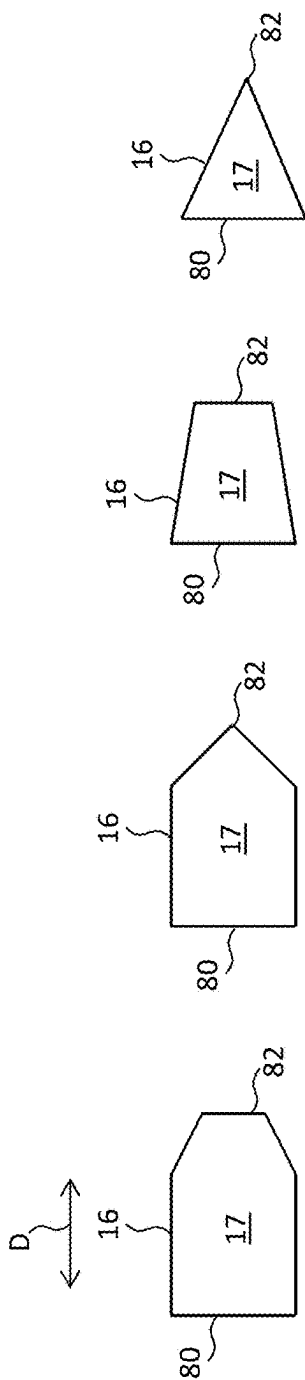


FIG. 8E

FIG. 8D

FIG. 8C

FIG. 8B

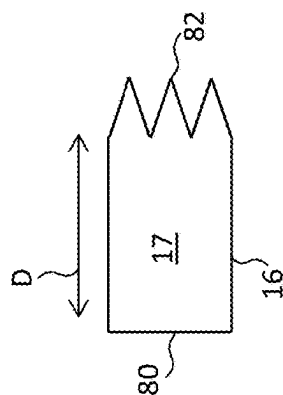


FIG. 8F

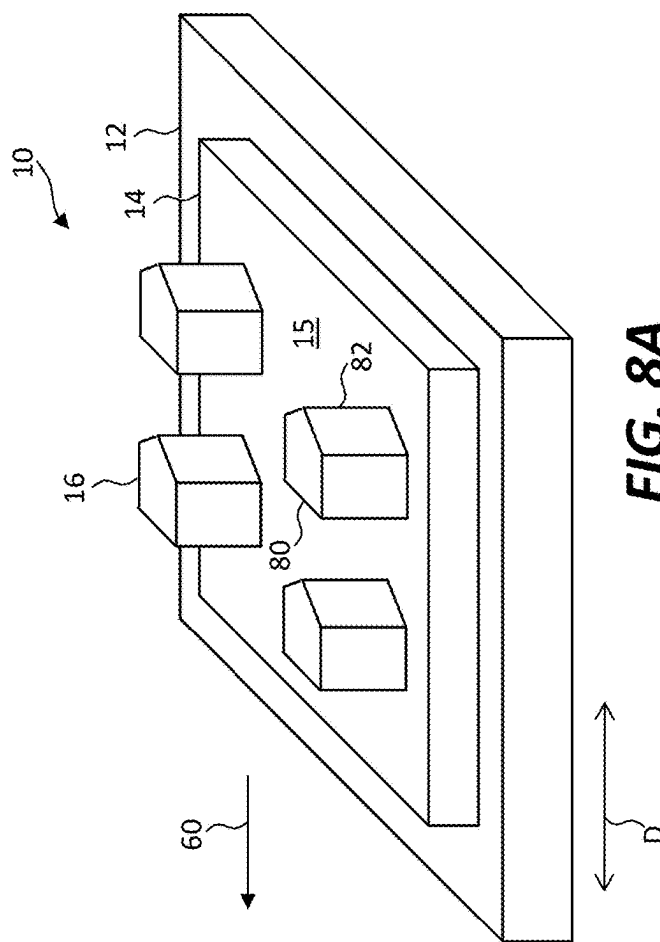


FIG. 8A

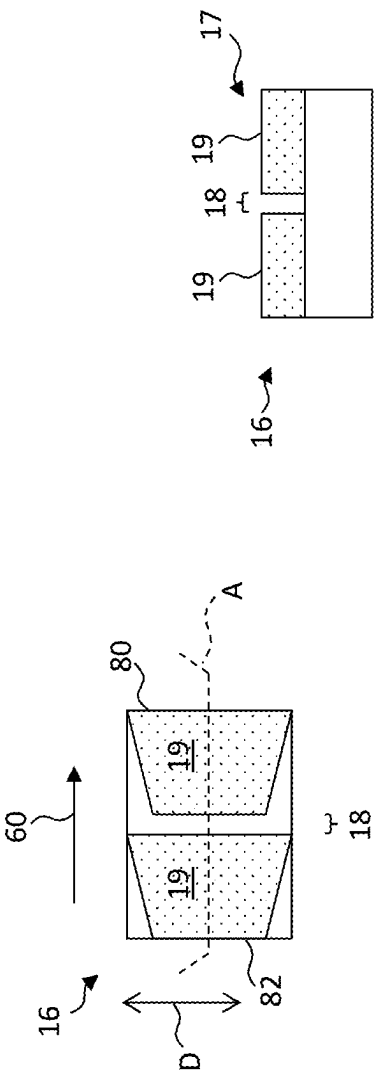


FIG. 9A

FIG. 9B

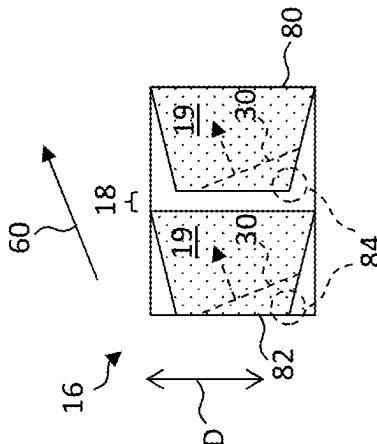
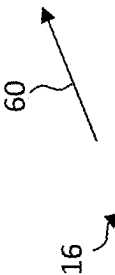
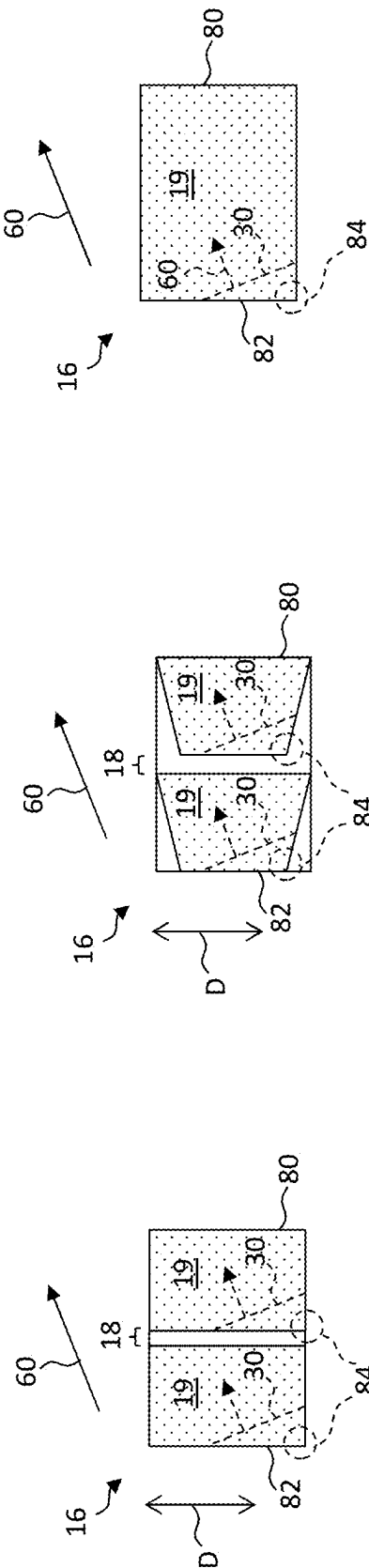


FIG. 10A

FIG. 10B

FIG. 10C

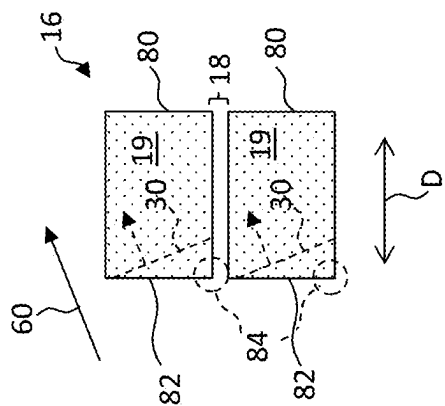


FIG. 11

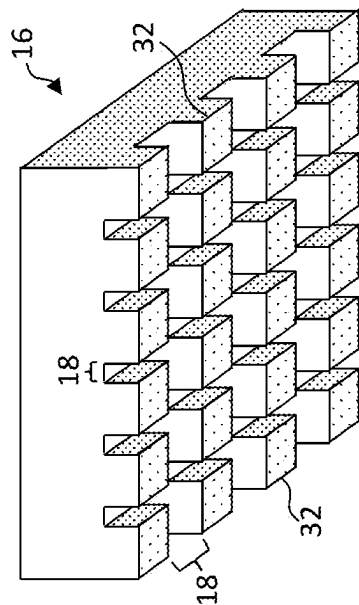


FIG. 12A

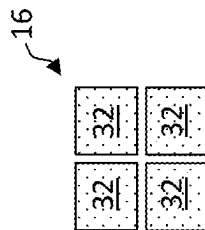


FIG. 12B

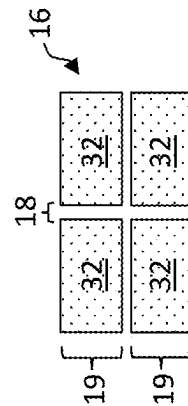
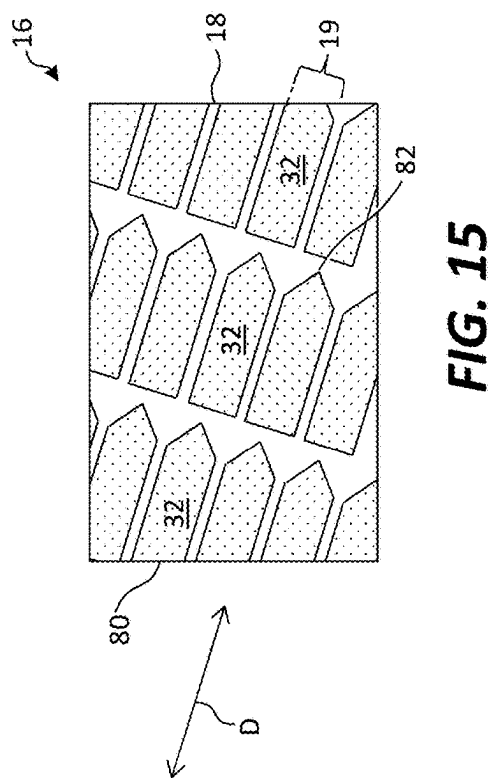
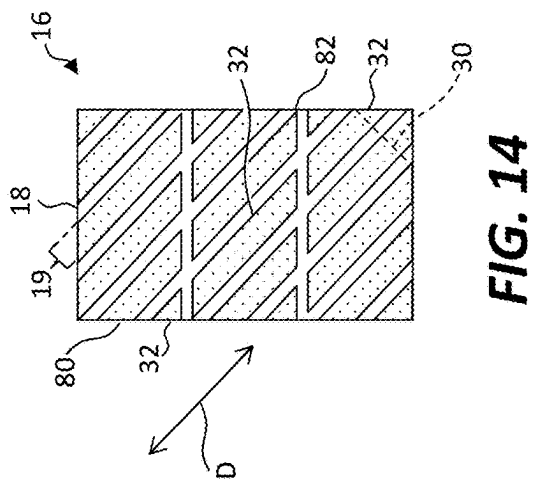
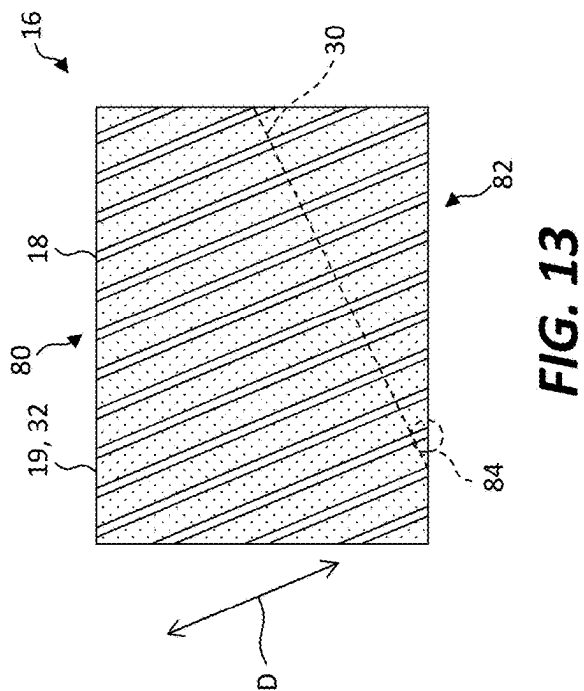


FIG. 12C



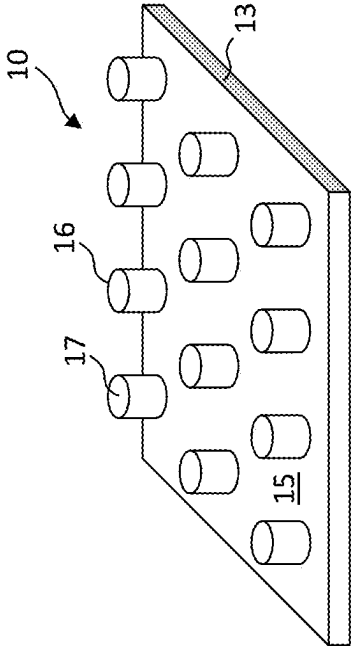


FIG. 16A

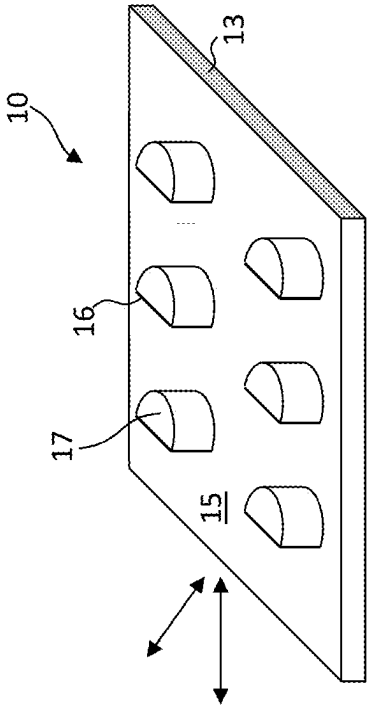


FIG. 16B

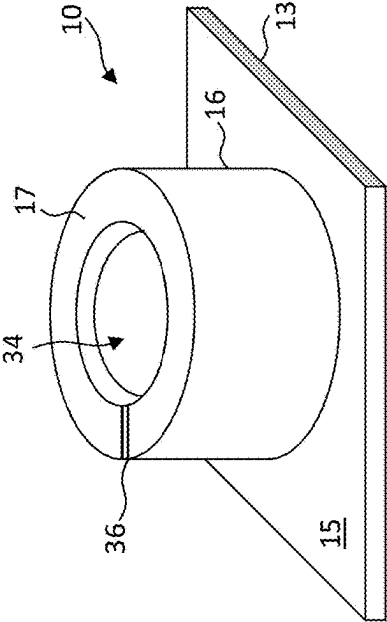


FIG. 17A

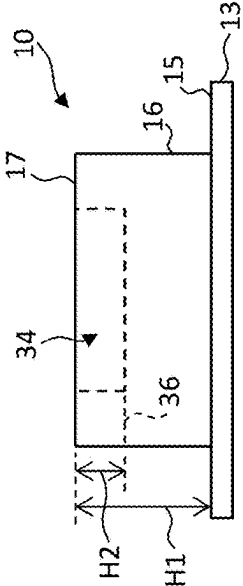


FIG. 17B

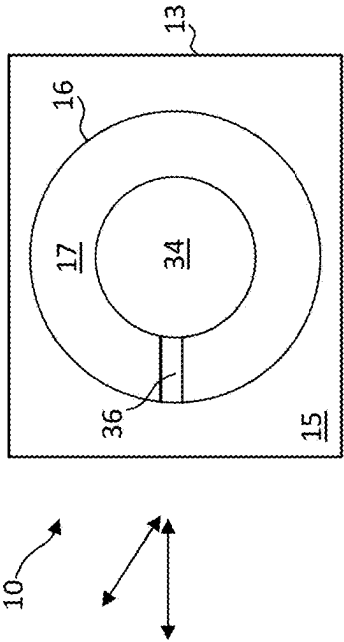


FIG. 17C

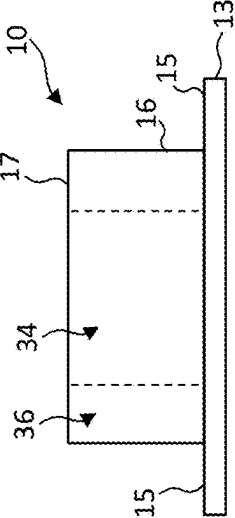
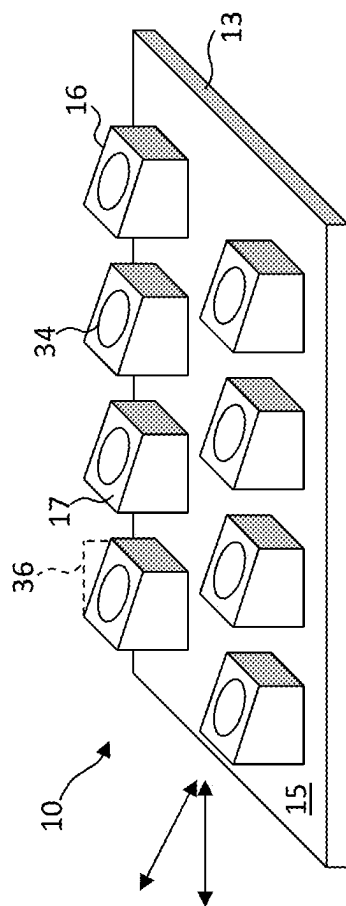
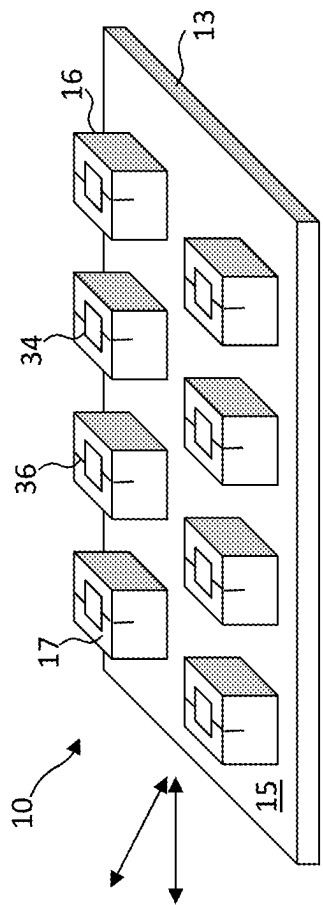


FIG. 17D



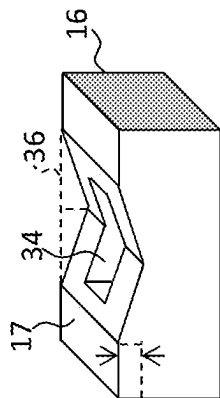


FIG. 18C

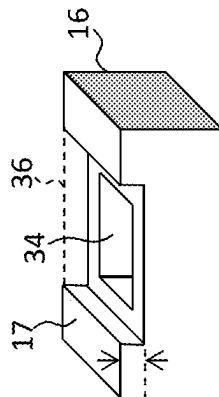


FIG. 18E

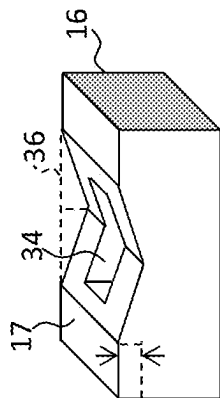


FIG. 18D

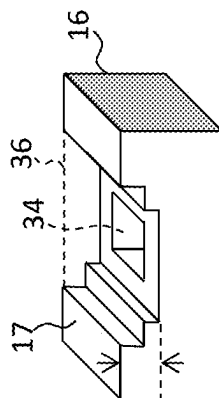


FIG. 18F

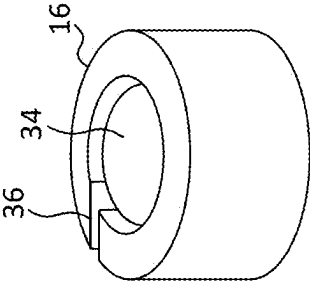


FIG. 18G

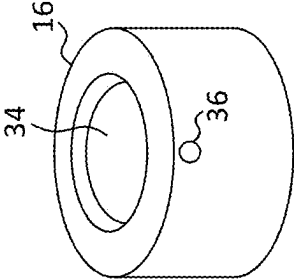


FIG. 18I

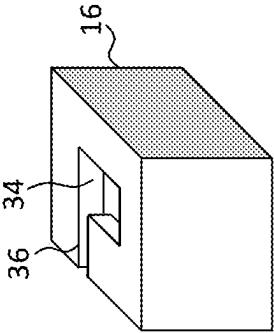


FIG. 18H

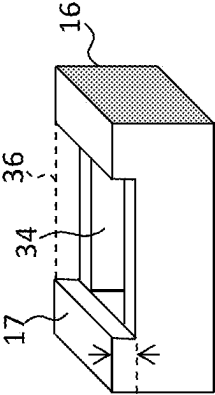


FIG. 18J

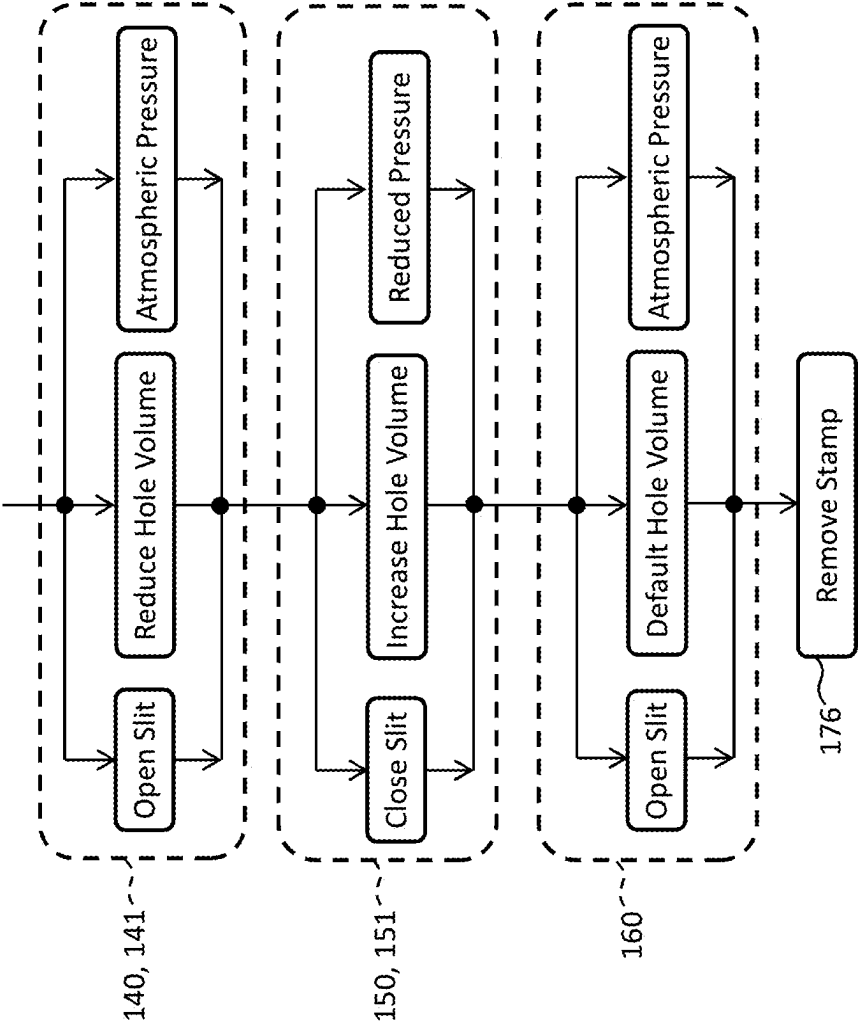


FIG. 19

FIG. 20A

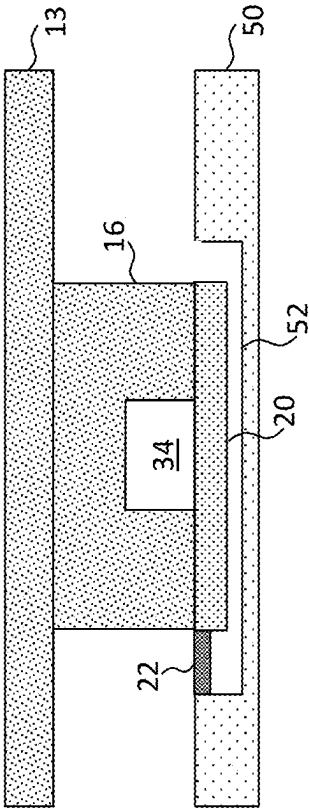


FIG. 20B

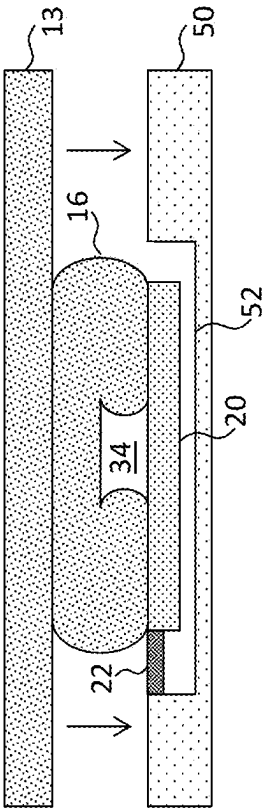
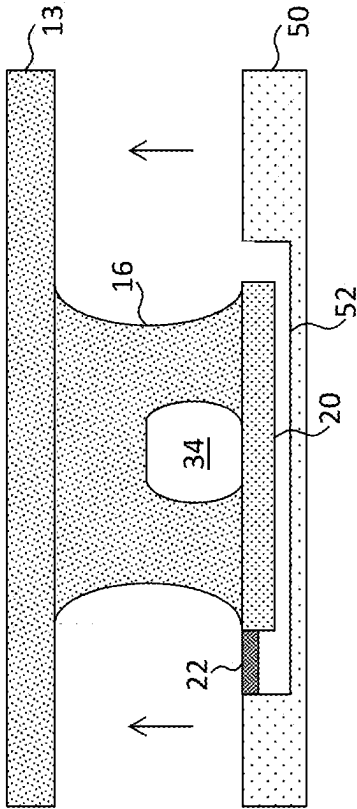
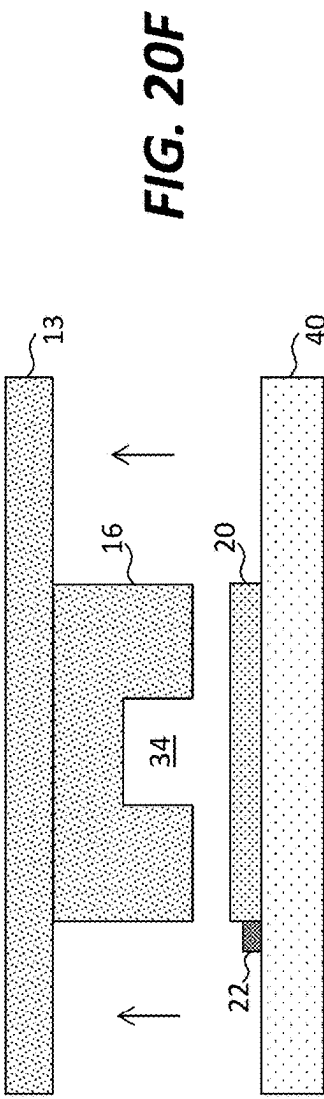
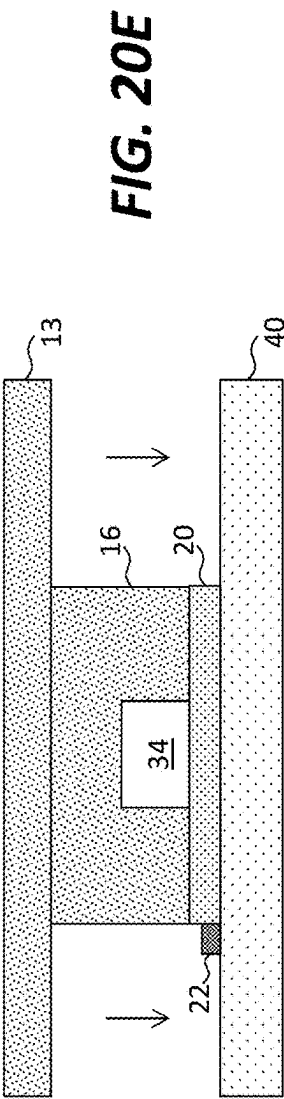
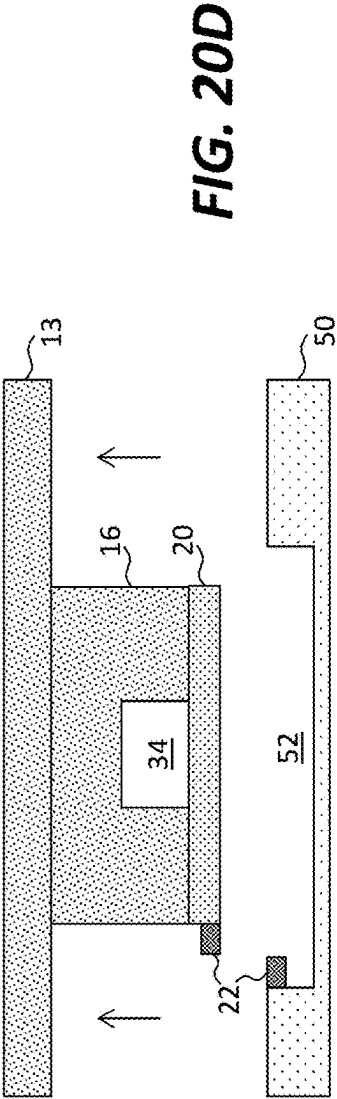


FIG. 20C





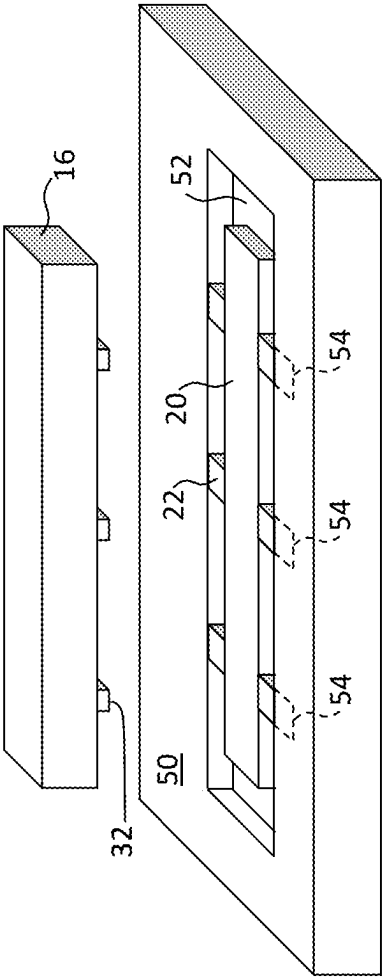


FIG. 21A

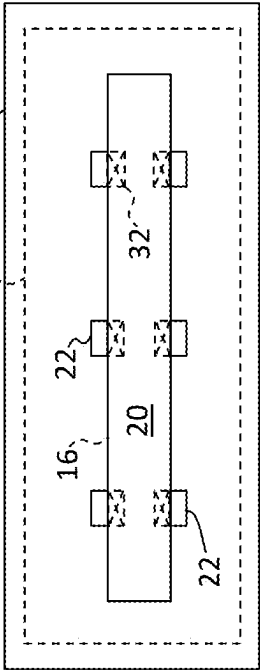


FIG. 21B

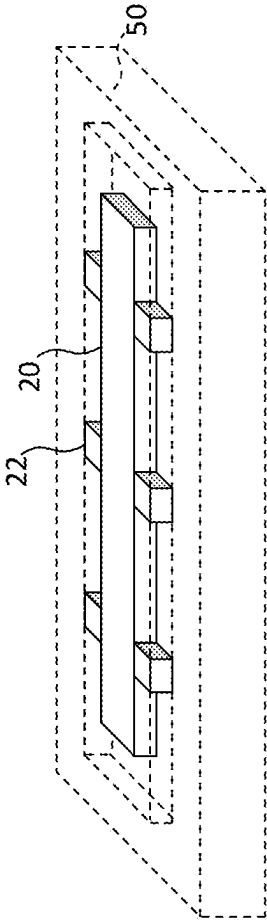


FIG. 21C

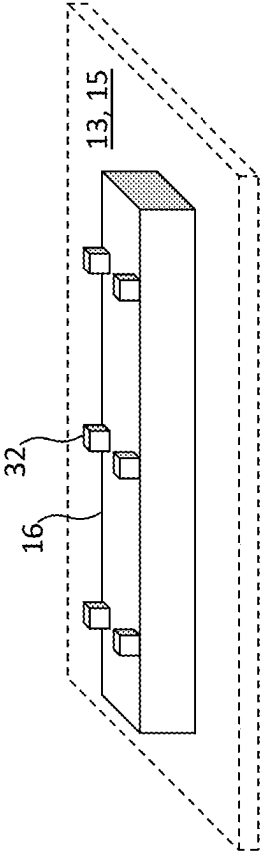


FIG. 21D

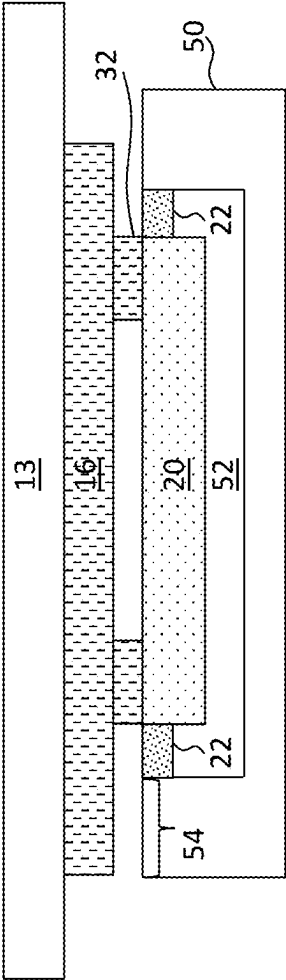


FIG. 21E

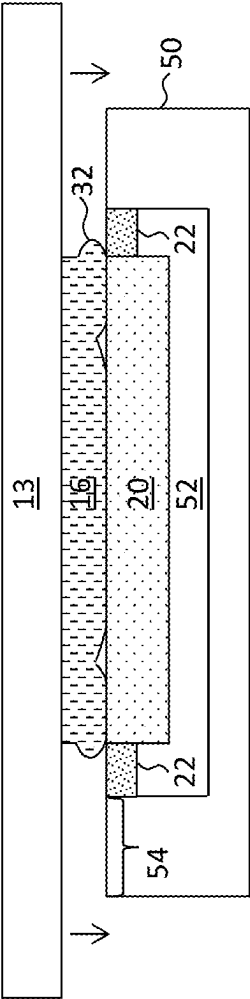


FIG. 21F

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TRANSFER PRINTING STAMPS AND METHODS OF STAMP DELAMINATION

CROSS-REFERENCE TO RELATED APPLICATION

This application is a continuation-in-part of U.S. patent application Ser. No. 17/886,985, filed Aug. 12, 2022, entitled Transfer Printing Stamps with Multiple Delamination Fronts, which claims priority to U.S. Provisional Application No. 63/233,946, filed Aug. 17, 2021, entitled Transfer Printing Stamps and Methods of Stamp Delamination. This application also claims priority to U.S. Provisional Application No. 63/414,985, filed Oct. 11, 2022, entitled Transfer Printing Stamps and Methods of Stamp Delamination. The disclosures of each of the above-referenced applications are incorporated by reference herein in their entireties.

TECHNICAL FIELD

The present disclosure relates to stamps used in micro-transfer printing.

BACKGROUND

Conventional methods for applying integrated circuits to a destination substrate, such as pick-and-place, are limited to relatively large devices, for example having a dimension of a millimeter or more. It is often difficult to pick up and place ultra-thin, fragile, or small micro-devices using such conventional technologies. More recently, micro-transfer printing methods have been developed that permit the selection and application of these ultra-thin, fragile, or small micro-devices without causing damage to the micro-devices themselves.

Micro-transfer-printing enables deterministically removing arrays of micro-scale, high-performance micro-devices from a native source wafer, typically a semiconductor wafer on which the micro-devices are constructed and assembling and integrating the micro-devices onto non-native target (destination) substrates. Embodiments of micro-transfer-printing processes leverage engineered elastomer stamps coupled with high-precision motion-controlled print-heads to selectively pick-up and print large arrays of micro-scale devices from a source native wafer onto non-native target substrates.

Adhesion between an elastomer transfer device (e.g., stamp) and a printable element can be selectively tuned by varying the speed of the print-head on which the stamp is mounted. This rate-dependent adhesion is a consequence of the viscoelastic nature of the elastomer used to construct the stamp. When the stamp is moved quickly away from a bonded interface, the adhesion is large enough to “pick” the printable elements away from their native substrates, and conversely, when the stamp is moved slowly away from a bonded interface the adhesion is low enough to “let go” or “print” the element onto a foreign, non-native surface. This process may be performed in massively parallel operations in which the stamps can transfer, for example, hundreds to thousands of discrete structures in a single pick-up and print operation. Element printing can be enhanced by using shear offset between the stamp and the target substrate, for example as described in U.S. Pat. No. 8,506,867, whose contents are incorporated by reference herein.

Micro-structured stamps may be used to pick up micro-devices from a source wafer, transport the micro-devices to the target substrate, and print the micro-devices onto the

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target substrate. The transfer device (e.g., micro-structured stamp) can be made using various materials. Posts on the transfer device can be constructed to pick up material from a pick-able object and then print the material to the target substrate. The posts can be generated in an array fashion and can have a range of heights depending on the size of the printable material. Embodiments of micro-transfer printing stamps are described, for example, in U.S. Pat. Nos. 8,506,867, 7,943,491, 9,412,727, 7,195,733 and 9,704,821.

Micro-transfer printing enables parallel assembly of high-performance semiconductor micro-devices onto virtually any substrate material, including glass, plastics, metals, or semiconductors. The substrates may be flexible, thereby permitting the production of flexible systems. Flexible substrates may be integrated in a large number of configurations, including configurations not possible with brittle silicon-based electronic micro-devices. Additionally, plastic substrates, for example, are mechanically rugged and may be used to provide electronic, opto-electronic, or photonic systems that are less susceptible to damage or performance degradation caused by mechanical stress. Moreover, micro-transfer printing techniques can print semiconductor micro-devices at temperatures compatible with assembly on plastic polymer substrates. Thus, these materials may be used to fabricate electronic, opto-electronic, or photonic systems by continuous, high-speed, printing techniques capable of disposing electronic, opto-electronic, or photonic micro-devices over large substrate areas at low cost (e.g., roll-to-roll manufacturing).

In some applications, in particular photonic or opto-electronic systems, alignment between printed micro-devices on a target substrate or between a printed micro-device and a structure on a target substrate is important. Moreover, it is important to print with a high yield to reduce manufacturing costs. There is a need, therefore, for stamps having an improved accuracy and yield in printing micro-devices on a target substrate.

SUMMARY

The present disclosure provides, inter alia, structures and methods that enable micro-transfer printing for micro-devices (e.g., a component) provided on a source wafer (e.g., a micro-device source wafer or a component source wafer). (As used herein, the terms micro-devices and components can be used interchangeably.) The micro-devices on the source wafer are contacted by a stamp to adhere the micro-devices to the stamp and release them from the source wafer. The micro-devices are then pressed against a target (or destination) substrate to adhere the micro-devices to the target substrate. The stamp is moved away from the target substrate, leaving the micro-devices on the target substrate. In some embodiments, an adhesive layer is disposed on the target substrate to enhance adhesion between the micro-devices and the target substrate. In some embodiments, no adhesive layer is disposed on the target substrate and the micro-devices are adhered directly to the target substrate. The present disclosure provides, among other things, stamps used for micro-transfer printing that have an improved accuracy and yield in printing micro-devices to a desired location on a non-native target substrate with or without an adhesive layer disposed on the target substrate.

According to embodiments of the present disclosure, a stamp for micro-transfer printing comprises a support having a support surface and posts disposed on the support surface, each of the posts comprising a distal end extending away from the support, the post having a post surface on the

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distal end. The posts can be compressible and can return to their former shape after compression (or tension) is removed, e.g., the posts can exhibit elastic deformation. The post surface can be a structured surface comprising spatially separated ridges that extend in a ridge direction entirely across the post surface. The ridges can be separated by grooves that extend in the ridge direction entirely across the post surface [e.g., wherein area of the ridges is greater than area of the grooves (e.g., at least twice, at least four times, at least six times, or at least eight times greater)]. The grooves can have a rectangular cross section in a direction that is orthogonal to the ridge direction and to the support surface. The grooves can have a triangular cross section in a direction that is orthogonal to the ridge direction and to the support surface. The ridges can have a rectangular or trapezoidal cross section in a direction that is orthogonal to the ridge direction and to the support surface. The ridges can have a triangular cross section in a direction that is orthogonal to the ridge direction and to the support surface. Each of the ridges can have a same shape, some of the ridges can have a shape different from others of the ridges, or a surface of the ridges can have a rectangular shape or forms a line. In some embodiments, the ridges have a first end and an opposing second end in a direction that is orthogonal to the ridge direction and parallel to the support surface, and the first end has a length that is different from a length of the second end.

According to embodiments of the present disclosure, the support or a layer of the support and the posts can comprise polydimethylsiloxane. At least a portion of the support and the posts can be a common structure (e.g., formed in a single molding step).

According to embodiments of the present disclosure, a stamp for micro-transfer printing can comprise a support having a support surface and posts disposed on the support surface. Each of the posts can comprise a distal end extending away from the support and a post surface on the distal end. A proximal end of the post can be in contact with or supported by the support. The post surface can be a surface structured such that, when the post surface is being separated from a component temporarily adhered to the surface, multiple delamination fronts are formed at the post surface. The post surface can be structured such that the multiple delamination fronts are formed when separation is performed while the component is at least partially in contact with a target surface of a target substrate. The post surface can be structured such that the multiple delamination fronts are formed when the support is moved at least partially in a horizontal direction.

According to embodiments of the present disclosure, a stamp for micro-transfer printing comprises a support having a support surface and posts disposed on the support surface. Each of the posts can comprise a distal end extending away from the support and a post surface on the distal end. The post surface can be non-rectangular and can have opposing edges with different lengths. In some embodiments, the post surface is triangular or trapezoidal or has an edge that is triangular or trapezoidal.

According to embodiments of the present disclosure, a stamp for micro-transfer printing comprises a support having a support surface and posts disposed on the support surface. Each of the posts can comprise a distal end extending away from the support and a post surface on the distal end. The post surface can have a first edge and a second edge and the first edge can be longer than the opposing second edge or point (e.g., the post surface has a triangular, trapezoidal, or house-shaped pentagonal shape). The post sur-

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face can be a structured surface comprising spatially separated ridges that extend in a ridge direction entirely across the post surface.

According to embodiments of the present disclosure, a method of micro-transfer printing comprises providing a stamp, a source wafer comprising components (e.g., micro-devices) disposed in an arrangement corresponding to an arrangement of the posts, and a target substrate, contacting the posts to the micro-devices, removing the components from the source wafer, and contacting the components to a substrate surface of the target substrate. Contacting the components to the substrate surface can comprise moving the components toward and in contact with the target substrate, moving the components in a direction parallel to the substrate surface, and moving the stamp away from the target substrate. The direction parallel to the substrate surface can be orthogonal or diagonal to the ridge direction.

A method of micro-transfer printing can comprise providing a stamp comprising posts, components temporarily adhered to the posts, and a target substrate, and separating the stamp from the components to print the components to the target substrate. Separating the stamp can comprise forming multiple delamination fronts for each of the posts. Contact surfaces of the posts that temporarily adheres the components (e.g., post surfaces) can be structured surfaces comprising spatially separated ridges. Separating the stamp can comprise moving the stamp horizontally relative to the target substrate (e.g., shearing the stamp from the components), moving the stamp vertically, or both.

Methods of the present disclosure can comprise providing a motion-control platform attached to the stamp for controlling the stamp. Contacting the posts to the components, removing the components from the source wafer, and contacting the components to the substrate surface can be performed using the motion-control platform.

Methods of the present disclosure can comprise providing a first stamp and a first side of a micro-device temporarily adhered to each of the posts of the first stamp, providing a second stamp, the second stamp comprising a support having a support surface and posts disposed on the support surface, each of the posts comprising a distal end extending away from the support, the post having a post surface on the distal end, providing a motion-control platform attached to the first stamp or the second stamp, and using the motion-control platform to contact and adhere the posts of the second stamp to a second side of the micro-devices opposite the first side and remove the micro-devices from the first stamp. Removing the micro-devices from the first stamp can comprise moving the first stamp relative to the second stamp in a direction at least partially orthogonal to the ridge direction, at least partially orthogonal to the delamination fronts, or at least partially in a direction orthogonal to one of the opposing sides. The second stamp can be a stamp having a structured distal end and the second stamp can be rotated with respect to the first stamp. The direction parallel to the substrate surface can be orthogonal or diagonal to the ridge direction of the first stamp.

Methods of the present disclosure can comprise providing a first stamp comprising posts, components temporarily adhered to the posts of the first stamp, and a second stamp comprising posts, and separating the first stamp from the components to transfer the components to the posts of the second stamp, wherein separating the stamp comprises forming multiple delamination fronts for each of the posts of the first stamp. Contact surfaces of the posts of the first stamp that temporarily adheres the components (e.g., post surfaces) can be structured surfaces comprising spatially

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separated ridges. Separating the stamp can comprise moving the first stamp horizontally relative to the second stamp (e.g., shearing the first stamp from the components). The posts of the second stamp can have unstructured (e.g., flat) surfaces or can have structured surface having spatially separated ridges aligned in a different direction from spatially separated ridges comprised in structure surfaces of the posts of the first stamp (e.g., aligned orthogonally to each other). Methods of the present disclosure can comprise printing the components to a target substrate from the second stamp.

Methods of the present disclosure can comprise providing a stamp comprising a support having a support surface and posts disposed on the support surface, each of the posts comprising a distal end extending away from the support, the post having a post surface on the distal end, the post surface having edges and corners, and a micro-device temporarily adhered to each post surface, providing a target substrate having a target substrate surface, providing a motion-control platform attached to the stamp, and using the motion-control platform to contact the micro-devices to the target substrate surface. Contacting the micro-devices to the target substrate surface can comprise moving the micro-devices toward and in contact with the target substrate surface, moving the micro-devices in a direction parallel to the target substrate surface at least partially in a direction non-parallel to one of the edges, and moving the stamp away from the target substrate. The post surface can be a structured surface comprising spatially separated ridges that extend in a ridge direction entirely across the post surface and the direction parallel to the substrate surface can be orthogonal, diagonal, or diagonally at 45 degrees with respect to the ridge direction.

Methods of the present disclosure can comprise providing a stamp comprising posts, components temporarily adhered to the posts of the stamp, and a target substrate, and separating the stamp from the components to print the components to the target substrate. The posts can have a post surface to which the components are temporarily adhered. The post surface can comprise edges and corners and separating the stamp can comprise moving the stamp in a direction non-parallel to one of the edges.

Methods of the present disclosure can comprise providing a first stamp comprising posts, providing components temporarily adhered to the posts of the first stamp, providing a second stamp comprising posts, and separating the first stamp from the components to transfer the components to the posts of the second stamp, wherein the posts of the first stamp have a post surface to which the components are temporarily adhered, the post surface comprises edges and corners, and separating the first stamp comprises moving the first stamp in a direction non-parallel to one of the edges.

According to some embodiments of the present disclosure, a stamp for micro-transfer printing comprises a support having a support surface and posts disposed on the support surface. Each post can comprise a proximal end in contact with the support and a distal end extending away from the support. The post can have a post surface on the distal end that has a first edge having a first length and a second edge opposing the first edge having a second length less than the first length. The second length can be a point or multiple points, the post surface can form a triangle or a trapezoid, and the post surface can form a quadrilateral, a five-sided area, or a six-sided area.

According to some embodiments of the present disclosure, a stamp for micro-transfer printing can comprise a support having a support surface and posts disposed on the support surface. Each post can comprise a proximal end in

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contact with the support and a distal end extending away from the support. The post can have a post surface on the distal end that is a structured surface comprising an array of sub-posts and the sub-posts cover no less than one half, no less than one third, no less than one quarter, no less than one fifth, or no less than one tenth of the post surface. The array of sub-posts can be a one-dimensional array or a two-dimensional array. The sub-posts can have a flat distal end.

According to embodiments of the present disclosure, a stamp for micro-transfer printing comprises a support having a support surface and posts disposed on the support surface. Each of the posts can comprise a distal end extending away from the support, the post having a post surface with a curved edge or a straight edge on the distal end. The curved edge can substantially form a portion of a circle or a semicircle.

According to embodiments of the present disclosure, a stamp for micro-transfer printing comprises a support having a support surface and posts disposed on the support surface. Each of the posts can comprise a distal end extending away from the support, a post surface on the distal end, and a hole extending to the post surface. The hole can be a blind hole that does not extend through the support. In some embodiments, a cutout extends from the hole to an exterior edge of the post and can extend only partially through the post. The cutout can be a channel or opening in the post. The cutout can extend from a post surface of the post, where the post surface is parallel to the substrate surface. In some embodiments, a cutout extends from the hole to an exterior edge, surface, or perimeter of the post. In some embodiments, at least a portion of the post surface is non-parallel to the support surface. In some embodiments, the cutout is disposed along a line intersecting a center of the hole. In some embodiments, the cutout is disposed along a line that does not intersect a center of the hole. In some embodiments, the cutout is disposed along a line tangent to the hole. In some embodiments, the cutout is disposed along a line parallel to and in contact with an edge of the hole.

The post can have a circular cross section except for the cutout. The hole can have a circular cross section except for the cutout. In some embodiments, the hole extends to the support surface, e.g., from the post surface. In some embodiments, the hole extends less than all of the way (e.g., less than entirely) to the support surface, e.g., from the post surface, for example no greater than halfway, no greater than one quarter of the way, or no greater than one tenth of the way. The hole can have a circular cross section and the post can have a polygonal cross section, e.g., a rectangular cross section. In some embodiments, the hole has a polygonal (e.g., rectangular or square) cross section and the post has a polygonal (e.g., rectangular or square) cross section.

The cutout can have a height greater than a width or a width greater than a height (where height is in a direction orthogonal to the support surface and width is parallel to the support surface). The post surface can be parallel to the support surface or can be non-parallel to the support surface, or only portions of the post surface can be parallel to the support surface. If one or more portions of the post surface are non-parallel to the support surface, the non-parallel portion(s) can form cutouts that extend to an edge of the post surface (e.g., to an edge perpendicular to the support surface). According to embodiments of the present disclosure, a method of micro-transfer printing comprises providing a stamp with a post with a cutout, providing a micro-device (e.g., a component) physically connected to a micro-device source wafer (e.g., a component source wafer) by a tether, pressing the post against the micro-device thereby com-

pressing the post and open (or keeping open) the cutout, and removing the micro-device (e.g., component) from the source wafer (e.g., component source wafer). The step of removing can comprise pulling the support surface away from the micro-device (e.g., pulling apart the support surface from the micro-device) thereby tensioning the post and close the cutout (e.g., seal the hole) and remove the micro-device from the micro-device source wafer, thereby breaking or separating the tether. Compressing the post can temporarily reduce the volume of the hole. Tensioning (e.g., stretching, elongating, or pulling on) the post can temporarily increase the volume of the hole, reducing the air pressure in the hole. Thus, in some embodiments, the air pressure within the hole is greater when the post is in compression and smaller when the post is in tension.

Embodiments can comprise providing a target substrate, contacting the micro-device to the target substrate, and moving the stamp at least horizontally with respect to the target substrate. In some embodiments, the direction of motion opens the cutout or increases the area of the cutout. Some embodiments can comprise providing a target substrate, pressing the micro-device to the target substrate, and removing the stamp from the micro-device, thereby printing the micro-device to the target substrate. Pressing the micro-device to the target substrate can comprise moving the micro-device horizontally (e.g., parallel) with respect to a surface of the target substrate against which the micro-device is pressed. In some embodiments, the post is pressed against the micro-device on the micro-device source wafer with a first force and the post is pressed against the micro-device on the target substrate with a second force less than the first force. In some such embodiments, pressing the stamp post against the micro-device on the micro-device wafer reduces the volume of the hole more than pressing the stamp post against the micro-device on the target substrate. In some embodiments, pressing the stamp post against the micro-device on the target substrate does not substantially compress the stamp post or substantially reduce the volume of the hole, at least in comparison to pressing the stamp post against the micro-device on the micro-device wafer. Thus, in embodiments, the air pressure in the hole is relatively less when the micro-device is removed from the micro-device source wafer and relatively greater when the stamp is removed from the micro-device.

In some embodiments, a method of printing a component comprises removing a component from a component source wafer with a stamp by simultaneously applying adhesion and suction to the component with a compressible post of the stamp while separating the stamp and the component source wafer from each other. In some embodiments, the post is elastomeric, compressible, or exhibits elastic deformation.

In some embodiments, the adhesion is a rate-dependent adhesion.

In some embodiments, the component is initially physically connected to the component source wafer and the removing comprises breaking or fracturing the tether while the stamp and the component source wafer are relatively separated from each other.

In some embodiments, removing comprises contacting the post to the component by pressing the post against the component thereby compressing the post and tensioning the post while separating the stamp and the component source wafer such that the post applies the adhesion and the suction to the component. In some embodiments, the adhesion is insufficient to break or separate the tether but the adhesion and the suction together are sufficient to break or separate the tether.

In some embodiments, the post comprises a blind hole (e.g., does not extend entirely through the stamp) and the suction is applied to the component by (i) contacting the blind hole to component to seal the blind hole and (ii) placing the blind hole under tension. Some embodiments comprise printing the component to a target substrate, and the printing comprises releasing the suction. Some embodiments comprise applying horizontal (e.g., and vertical) motion between the stamp and the component source wafer, and the horizontal motion causes the suction to be released. A system for micro-transfer printing can comprise a component source wafer comprising a sacrificial portion, a micro-device disposed completely and directly over the sacrificial portion, tethers connecting the micro-device to one or more anchor portions of the micro-device source wafer at tether locations, and a stamp comprising a stamp support having a support surface and one or more posts disposed on the support surface. The distal end of the post can have a structured three-dimensional surface comprising sub-posts that extend away from the support surface at sub-post locations. The sub-post locations can be disposed adjacent to the tether locations when the sub-posts are in contact with the micro-device when the micro-device is disposed on the micro-device source wafer.

In some embodiments, the component is native to the component source wafer.

According to some embodiments of the present disclosure, a system for micro-transfer printing comprises a component attached to a component source wafer exclusively by tethers and a stamp comprising a stamp post comprising sub-posts. Each of the sub-posts can be disposed on a distal end of the stamp post to correspond to one of the tethers for one of the one or more components. Some embodiments comprise a plurality of components each attached to the component source wafer exclusively by tethers and the stamp comprises a plurality of stamp posts each comprising sub-posts disposed on a distal end of the stamp post to correspond to one of the tethers for one of the plurality of components.

According to some embodiments, the component is native to the component source wafer. In some embodiments, the stamp posts are elastomeric. In some embodiments, the sub-posts are compressible and portions of the distal end of the post between the sub-posts are in a common plane when the sub-posts are under mechanical pressure. In some embodiments, the micro-posts are compressible and portions of the distal end of the post between the sub-posts and the sub-posts are in a common plane when the sub-posts are under mechanical pressure. The sub-posts can be pyramidal, cylindrical, cubic, or have rectangular or polygonal faces and, in some embodiments, can have holes with or without cutouts.

According to some embodiments of the present disclosure, a stamp for micro-transfer printing comprises a support having a support surface and posts disposed on the support surface, each post comprising a distal end extending away from the support, the post having a post surface on the distal end. The post surface can have a first edge and a second edge and a third edge both opposing the first edge. The first edge can have a first length, the second edge can have a second length, the third edge can have a third length, and a total of the second length and the third length can be less than the first length. In some embodiments, the second edge is a point, the third edge is a point, or both the second edge and the third edge are each a point. In some embodiments, the second edge and the third edge are coplanar with a line parallel to the first edge.

In some embodiments, the post surface further has a fourth edge that has a fourth length, the fourth edge is also opposing the first edge, and a total of the second length, the third length, and the fourth length is less than the first length. In some embodiments, the fourth edge is a point.

According to some embodiments of the present disclosure, a stamp for micro-transfer printing comprises a support having a support surface and posts disposed on the support surface. Each post can have a distal end extending away from the support, the post having a post surface on the distal end. The post surface can be a structured surface comprising an array of sub-posts and the sub-posts can cover no less than one tenth (e.g., no less than one fifth, no less than one quarter, no less than one third, or no less than one half) of the post surface. The array of sub-posts can be a one-dimensional array. The array of sub-posts can be a two-dimensional array. In some embodiments, the sub-posts have a flat distal end.

Embodiments of the present disclosure provide stamps with improved print yields and accuracy.

BRIEF DESCRIPTION OF THE DRAWINGS

The foregoing and other objects, aspects, features, and advantages of the present disclosure will become more apparent and better understood by referring to the following description taken in conjunction with the accompanying drawings, in which:

FIG. 1A is a perspective of the bottom side of a micro-transfer printing stamp, FIG. 1B is a bottom plan view of a micro-transfer printing stamp with a detail view of a micro-transfer printing stamp post surface, FIG. 1C is a cross section taken along cross section line A of a micro-transfer printing stamp post of FIG. 1B, and FIG. 1D is a cross section taken along cross section line B of a micro-transfer printing stamp post of FIG. 1B according to illustrative embodiments of the present disclosure;

FIG. 2 is a perspective of a micro-transfer printing stamp post and post surface according to illustrative embodiments of the present disclosure;

FIGS. 3A and 3B are cross sections of a micro-transfer printing stamp post and post surface according to illustrative embodiments of the present disclosure;

FIGS. 4A-4F are successive cross sections of a method and structures for micro-transfer printing according to illustrative embodiments of the present disclosure, where FIG. 4A shows a printing system with a motion platform and stamp with stamp posts in contact with micro-devices on a source wafer with a detail of a stamp post and micro-device, FIG. 4B shows micro-devices adhered to stamp posts removed from the source wafer, FIG. 4C shows micro-devices adhered to stamp posts in contact with a target substrate, FIG. 4D shows horizontal shear offset between the stamp and the target substrate, FIG. 4E is a detail illustrating delamination of a single post of FIG. 4D, FIG. 4F shows the stamp removed from and the micro-devices adhered to the target substrate;

FIG. 5 is a flow diagram of micro-transfer printing from a source wafer to a target substrate according to illustrative embodiments of the present disclosure;

FIG. 6 is a cross section of a first stamp transferring micro-devices to a second stamp according to illustrative embodiments of the present disclosure;

FIG. 7 is a flow diagram of picking up micro-devices from a source wafer with a first stamp, transferring the micro-

devices to a second stamp, and printing the micro-devices to a target substrate according to illustrative embodiments of the present disclosure;

FIG. 8A is a perspective of a stamp with posts and FIGS. 8B-8F are plan views of stamp posts having different post surface shapes with different-length opposing edges according to illustrative embodiments of the present disclosure;

FIG. 9A is a plan view and FIG. 9B is a corresponding cross section taken across cross section line A of a stamp post having ridges with different-length opposing sides according to illustrative embodiments of the present disclosure;

FIGS. 10A-10C are plan views of stamp posts according to illustrative embodiments of the present disclosure;

FIG. 11 is a plan view of the distal end of a stamp post according to illustrative embodiments of the present disclosure;

FIG. 12A is a perspective of a stamp post having a two-dimensional array of sub-posts and FIG. 12B is a plan view of the distal end of a portion of the stamp post of FIG. 12A, according to illustrative embodiments of the present disclosure;

FIG. 12C is a plan views of distal ends of stamp posts having sub-posts with rectangular cross sections according to illustrative embodiments of the present disclosure;

FIGS. 13-15 are plan views of the distal end of a stamp post according to illustrative embodiments of the present disclosure;

FIG. 16A is a perspective of a stamp with cylindrical posts and FIG. 16B is a perspective of a stamp with semi-cylindrical posts, according to illustrative embodiments of the present disclosure;

FIG. 17A is a perspective, FIG. 17B is a cross section through the cutout of FIG. 17A, FIG. 17C is a top view, and FIG. 17D is a cross section of a stamp comprising a cylindrical post with a hole and a cutout according to illustrative embodiments of the present disclosure;

FIG. 18A is a perspective of a stamp comprising a cubic post with a hole according to illustrative embodiments of the present disclosure;

FIG. 18B is a perspective of a stamp comprising a post with an angled post surface and a hole according to illustrative embodiments of the present disclosure;

FIGS. 18C-18J are perspectives of stamp posts with a hole according to illustrative embodiments of the present disclosure;

FIG. 19 is a flow diagram of methods according to illustrative embodiments of the present disclosure;

FIGS. 20A-20F are successive cross sections corresponding to the flow diagram of FIG. 19 according to illustrative embodiments of the present disclosure; and

FIG. 21A is perspective of a system comprising a micro-device and stamp, FIG. 21B is a bottom view of the system, FIG. 21C is a perspective detail of the micro-device, FIG. 21D is an inverted perspective detail of the stamp, FIG. 21E is a cross section along the width of the system, and FIG. 21F is a cross section along the width of the system under compression according to illustrative embodiments of the present disclosure.

Features and advantages of the present disclosure will become more apparent from the detailed description set forth below when taken in conjunction with the drawings, in which like reference characters identify corresponding elements throughout. In the drawings, like reference numbers generally indicate identical, functionally similar, or structurally similar elements. The figures are not drawn to scale

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since the variation in size of various elements in the Figures is too great to permit depiction to scale.

DETAILED DESCRIPTION OF CERTAIN EMBODIMENTS

The present disclosure provides, inter alia, structures and methods that enable micro-transfer printing for micro-devices (chipllets) provided on a source wafer. The terms “micro-device” and “chipllet” are used interchangeably and have the same meaning herein. Generally, the following description refers to printing “micro-devices” as an example of printing components, which can be micro-devices or can be not micro-devices, for example a mass of material (e.g., seed crystal or piezoelectric material) or a passive electronic component (e.g., jumper). The micro-devices are formed on the source wafer, released from the source wafer, contacted by a stamp to adhere the micro-devices to the stamp, removed from the source wafer, and pressed against a target (or destination) substrate to adhere the micro-devices to the target substrate. The stamp is then moved away from the target substrate, leaving the micro-devices adhered to the target substrate. The micro-devices can be disposed on the target substrate with improved accuracy and yield. In some embodiments, an adhesive layer is disposed on the target substrate to enhance adhesion between the micro-devices and the target substrate. In some embodiments, no adhesive layer is disposed on the target substrate and the micro-devices are adhered directly to the target substrate. The present disclosure provides, among other things, stamps used for micro-transfer printing that have an improved accuracy and yield in printing micro-devices to a desired location on a non-native target substrate with or without an adhesive layer disposed on the target substrate.

Materials used in micro-transfer printing stamps can comprise visco-elastic and elastomeric materials such as polydimethylsiloxane (PDMS). As shown in FIG. 1A, a stamp 10 typically includes a rigid support 12 and, optionally, a body from which a post 16 (sometimes called a pillar) extends. Each post 16 is used to contact a single component 20 (e.g., micro-device 20) (shown in FIG. 4A, discussed below) or micro-structure such as a chiplet 20, and each micro-device 20 is contacted by a single post 16 to perform a release and print of micro-device 20 from a source wafer 50 (shown in FIG. 4A, discussed below) to a non-native target substrate 40 (shown in FIG. 4C, discussed below). According to some embodiments, the optional body of stamp 10 comprises a mesa 14 or pedestal disposed on rigid support 12 and posts 16 extend from mesa 14. In some embodiments, posts 16 extend directly from rigid support 12 or stamp 10 comprises multiple separate mesas 14 from each of which posts 16 extend. Rigid support 12 and any one or more mesas 14, or stamp body, form a support 13 having a support surface 15 on which posts 16 are disposed and from which posts 16 extend. In some embodiments, support 13 does not comprise a rigid support 12. As shown in FIGS. 1B-1D, posts 16 comprise a proximal end in contact with support 13 and a distal end extending away from support 13 and support surface 15. Post 16 has a post surface 17 on the distal end. According to some embodiments of the present disclosure and as discussed below with respect to FIGS. 6A-6E, post 16 has a non-rectangular cross section parallel to support surface 15 and post surface 17 is non-structured and substantially planar.

According to some embodiments of the present disclosure and as discussed below with respect to FIGS. 8A-8E, post 16 can have a non-rectangular cross section parallel to support

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surface 15 and post surface 17 is non-structured and substantially planar. According to some embodiments of the present disclosure and as illustrated in FIGS. 1B and 1C, post 16 can have a rectangular cross section parallel to support surface 15 and post surface 17 is non-planar and has a structured surface comprising spatially separated ridges 19 that extend in a ridge direction D entirely across post surface 17. Post surface 17 has opposing sides or edges and ridges 19 extend from one side (or edge) of post surface 17 to an opposite side (or edge) of post surface 17. For example, ridges 19 can be separated by grooves 18 that likewise extend entirely and all of the way across post surface 17 so that both ridges 19 and grooves 18 contact an edge or side of post 16 and post surface 17 at two or more spatially separate locations. Ridges 19 can each be a sub-post 32 extending from a distal end of post 16. By extending entirely across post surface 17 is meant that post surface 17 has opposing sides or edges and ridges 19 extend from one side (or edge) of post surface 17 to an opposite side (or edge) of post surface 17. For example, ridges 19 can be separated by grooves 18 that likewise extend entirely and all of the way across post surface 17 so that both ridges 19 and grooves 18 contact an edge or side of post 16 and post surface 17 at two or more spatially separate locations. For example, if post 16 has a rectangular cross section parallel to support surface 15 with parallel opposing sides, ridges 19 extend from one side to the parallel opposing side of post surface 17. However, posts 16 are not limited to structures with rectangular cross sections and can have, for example, a quadrilateral or other polygonal, curved, or irregular cross section. Ridges 19 can, but do not necessarily, extend substantially or entirely (e.g., all the way) from one side (or edge) of post surface 17 to another, different side (or edge) of post surface 17, for example a different side parallel to the one side. By substantially is meant that ridges 19 extend far enough across post surface 17 so that each ridge 19 at the same time can effectively delaminate from a common chiplet 20 when micro-transfer printing chiplet 20 to a target substrate 40 by moving stamp 10 in a horizontal direction 60 parallel to a surface of chiplet 20 or parallel to a surface of target substrate 40 (shown in more detail in, e.g., FIGS. 4A-4E discussed below). As shown in FIGS. 1B and 1D, ridges 19 are continuous and contiguous and each form a single sub-post 32. In some embodiments, and as discussed further below, ridges 19 comprise multiple spatially separate sub-posts 32.

FIG. 1A is a perspective bottom view of stamp 10 having a rigid support 12 with a mesa 14 disposed on rigid support 12. Rigid support 12 can comprise, for example glass. Posts 16 are disposed on mesa 14 and extend away from mesa 14 and rigid support 12, for example in a direction orthogonal to a surface of mesa 14. Mesa 14 (and optionally rigid support 12, or vice versa) provides a support 13 having a support surface 15 on which posts 16 are disposed and from which posts 16 extend. Mesa 14 (if present) and posts 16 can comprise a common material, for example polydimethylsiloxane (PDMS), that has a greater coefficient of thermal expansion than rigid support 12. At least a portion of support 13 (e.g., excluding rigid support 12) and posts 16 can be a common structure (e.g., formed in a single molding step). In some embodiments, mesa 14 can comprise a different material or material with different component concentrations than posts 16 and a different, e.g., larger, coefficient of thermal expansion than posts 16. FIG. 1B is a bottom plan view of stamp 10 with posts 16 on mesa 14 and rigid support 12. The FIG. 1B inset illustrates a structured distal end of a post 16 with parallel ridges 19 spatially separated by grooves 18

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extending in a ridge direction D across post surface 17. The cross sections of FIGS. 1C and 1D taken across cross section lines A and B, respectively, of FIG. 1B show post surface 17 at the distal end of post 16 with grooves 18 and ridges 19 both with rectangular cross sections taken in a direction orthogonal to ridge direction D and orthogonal to support surface 15.

FIG. 2 is a perspective of the distal end of a post 16 with a post surface 17 structured with rectangular-cross-section ridges 19 and grooves 18. Ridges 19 and grooves 18 extending in ridge direction D are arbitrarily labeled as a direction or dimension Y and the direction or dimension orthogonal to ridge direction D is consequently labeled X. Directions X and Y define a horizontal plane and the vertical direction Z is the direction in which posts 16 extend from support surface 15. FIGS. 3A and 3B illustrate embodiments of the present disclosure in which ridges 19 have a trapezoidal cross section and grooves 18 have a triangular cross section (as shown in FIG. 3A) or ridges 19 have a triangular cross section and grooves 18 have a trapezoidal cross section (as shown in FIG. 3B) cross section spatially separated by grooves 18 with a triangular cross section in a direction orthogonal to ridge direction D and orthogonal to support surface 15. In general, there is no limitation to the cross sectional shapes of ridges 19 or grooves 18. Nor is there a limitation on the shape of ridges 19 on the distal end of post 16. For example, a surface of ridges 19 can have a rectangular shape (e.g., as in FIGS. 2 and 3A) or can form a line (e.g., as in FIG. 3B).

According to some embodiments, all of ridges 19 or grooves 18 have a same shape. In some embodiments, some of ridges 19 or grooves 18 can have different shapes. According to some embodiments, and as discussed further below with respect to FIGS. 8A-8E, ridges 19 can have first and second sides (edges) 80, 82 that extend in a direction parallel to ridge direction D, are opposed (e.g., are on opposite sides of post 16 or ridge 19) in a direction orthogonal to ridge direction D and orthogonal to the direction of first and second sides 80, 82 (e.g., in direction X), and first edge 80 has a length that is different from a length of second edge 82. For example, a distal surface of post 16 can comprise one or more trapezoidal or triangular cross sections. According to some embodiments, each ridge 19 or post 16 has a post surface 17 with a shape comprising any one of the shapes illustrated in FIGS. 8A-8E, for example a trapezoidal or triangular cross section or has a trailing second edge 82 that is shorter than a leading first edge 80 or comes to one or more points on a side of post 16 that is opposite leading first edge 80. According to embodiments, second edge 82 can be one or more points. According to embodiments, one or more ridges 19 or posts 16 has a post surface 17 that is a quadrilateral, a five-sided shape or area, or a six-sided shape or area, for example a rectangle with a trapezoid or a triangle on one edge of the rectangle. Ridges 19 can have the same shape or some ridges 19 in a post 16 can have a different shape 19 in the post 19.

According to embodiments of the present disclosure and as illustrated in the successive cross sections of FIGS. 4A-4F and the flow diagram of FIG. 5, stamps 10 can be used for micro-transfer printing micro-devices 20 (e.g., micro-modules, chiplets, or micro-components) from a source wafer 50 to a target substrate 40 (a destination substrate). A motion-control platform 70 is provided in step 100, a chiplet source wafer (e.g., a source substrate) is provided in step 110, a stamp 10 is provided in step 120, and a target substrate 40 is provided in step 130. As shown in FIG. 4A, chiplet source wafer 50 can comprise a sacrificial layer comprising sacri-

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ficial portions 52 separated by anchors 54 attached to chiplets 20 by chiplet tethers 22. Chiplets 20 are disposed directly and entirely over sacrificial portions 52. Chiplets 20 are released from source wafer 50 by etching sacrificial portions 52 to form gaps between chiplets 20 and source wafer 50. Stamp 10 comprising rigid substrate 12, optional mesa 14, and posts 16 with a structured post surface 17 comprising ridges 19 spatially separated by grooves 18 is moved by motion-control platform 70 into position in a vertical direction 65 toward and in alignment with source wafer 50 so that the distal end of posts 16 and at least a portion of ridges 19 contact chiplets 20, temporarily adhering chiplets 20 to posts 16, in step 140 and as shown in FIG. 4A. Motion-control platform 70 then removes stamp 10 from source wafer 50 with chiplets 20 adhered to posts 16 in step 150 by moving stamp 10 and chiplets adhered to stamp 10 away from source wafer 50 as shown in FIG. 4B, fracturing or separating chiplet tethers 22 and detaching chiplets 20 from source wafer 50. The stamp motion can be in a vertical direction 65 or a combination vertical 65 and horizontal 60 direction either at the same time or sequentially.

In step 160, motion-control platform 70 moves stamp 10 vertically in direction 65 toward target substrate 40 so that chiplets 20 adhered to posts 16 contact target substrate A layer 42 of adhesive can, but is not necessarily, coated in optional step 135 on target substrate 40 before chiplets 20 are contacted to target substrate 40 (or to adhesive layer 42 if present) as shown in FIG. 4C. Motion-control platform 70 can also move stamp in a horizontal direction 60 (direction X or direction Y or a combination of directions X and Y) parallel to a surface of target substrate 40 in step 160. As used herein, a stamp movement is a relative movement of stamp 10 with respect to a substrate (e.g., target substrate 40) and in some embodiments, the substrate is moved instead of stamp 10 in a direction opposite to the stamp movement. Horizontal can mean substantially horizontal, for example within the tolerance of mechanical motion-control platform 70, for example no greater than ten, no greater than five, no greater than two, or no greater than one degrees of a motion parallel to target substrate 40 surface (an in-plane motion). Horizontal motion can be at any effective rate, for example motion at a rate of 1 mm/s or more. Horizontal motion can be a distance of no less than one, five, ten, twenty, fifty microns, or no greater than one hundred microns.

In step 170 and as shown in FIG. 4D, chiplets 20 adhered to target substrate 40 (and optionally adhesive layer 42) are removed from stamp posts 16. Motion-control platform 70 moves stamp 10 in a horizontal direction 60 parallel to a surface of target substrate 40 and, at the same time, or subsequently, moves stamp 10 in a vertical direction 65 away from target substrate 40. Horizontal motion 60 is at least partially orthogonal to ridge direction D so that the stress of relative horizontal motion 60 between chiplets 20 (adhered to target substrate 40 or adhesive layer 42) and posts 16 causes delamination between ridges 19 on the distal end of posts 16, for example on the trailing edge of posts 16 with respect to the relative stamp 10 motion as shown in FIG. 4D and the detail of FIG. 4E, separating posts 16 from chiplets 20 and leaving chiplets 20 disposed on target substrate 40, as shown in FIG. 4F. Stamp 10 horizontal and vertical movement in steps 160 and 170 can be, but is not necessarily, continuous and can be separate or combined motions. Stamp 10 horizontal and vertical movement in step 170 can be continuous or separate motions and can be

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combined so that stamp 10 moves both horizontally along and vertically away from target substrate surface at the same time.

According to embodiments of the present disclosure, the presence of multiple ridges 19 on the distal end of posts 16 causes multiple delamination fronts 30 to form, e.g., one delamination front 30 for each ridge 19, decreasing the adhesion between chiplets 20 and the distal end of posts 16. A delamination front 30 is a line separating a portion of post 16 (or ridge 19) in contact with chiplet 20 from a portion of post 16 (or ridge 19) that is not in contact with and is separated from chiplet 20 at a given time. Local delamination between post 16 or ridge 19 and chiplet 20 progresses over time along the surface of chiplet 20 as ridge 19 (and post 16) is peeled from chiplet 20 in a direction substantially parallel to horizontal motion 60 so that delamination front 30 progresses from a starting point or edge 82 of post 16 or ridge 19 and proceeds along a surface of post 16 or ridge 19 until post 16 or ridge 19 is completely separated from chiplet 20. Multiple delamination fronts 30 reduce the adhesion between chiplets 20 and the distal end of posts 16 relative to a non-structured post surface 17, thereby increasing the likelihood that chiplet 20 will adhere to target substrate 40 or adhesive layer 42 rather than remaining attached to stamp 10 (improving print yields) and reducing the amount of shear offset experienced or needed by chiplet 20 (e.g., the distance chiplet 20 moves with respect to target substrate 40), thereby improving print accuracy. Grooves 18 can be narrower than ridges 19 in a direction orthogonal to ridge direction D. In some embodiments, the area of ridges 19 is greater than the area of grooves 18 (for example much greater, e.g., twice, four times, six times, eight times greater, or more). Consequently, initial adhesion between chiplets 20 and posts 16 when detaching (picking) chiplets 20 from source wafer 50 is not greatly reduced (since the area of ridges 19 can be only slightly less than the area of post surface 17) and print accuracy and yield are improved.

Thus, according to embodiments of the present disclosure, a stamp 10 for micro-transfer printing can comprise a support 13 having a support surface 15 and posts 16 disposed on support surface 15 (e.g., as shown in FIGS. 1C, 1D, 3A, and 3B). Each post 16 comprises a proximal end in contact with support 13 and a distal end extending away from support 13 and support surface 15. The distal end of post 16 can comprise a post surface 17. Post surface 17 can be a structured surface operable to form multiple delamination fronts 30 when (i) a first side of a micro-device 20 (e.g., chiplet 20) is in contact with at least a portion of post surface 17, (ii) a second side of the micro-device 20 (e.g., chiplet 20) opposed to the first side is at least partially in contact with a target surface of a target substrate 40 (or a layer such as adhesive layer 42 disposed on target substrate 40) or another structure having a target surface, and (iii) support 13 is moved at least partially in a horizontal direction 60 parallel to the target surface. The direction of horizontal motion 60 can be orthogonal to a direction of delamination fronts 30 and in a direction of the propagation of delamination fronts 30. The delamination fronts 30 are between chiplets 20 and post surface 17 (a surface of ridges 19). Delamination front 30 can extend in ridge direction D and propagate in a direction orthogonal to direction D or in the direction of horizontal motion 60, as shown in FIG. 4E. Delamination is similar to or the equivalent of peeling post 16 from chiplet 20.

According to some embodiments of the present disclosure, micro-devices 20 (chiplets 20) can be disposed in an upside-down configuration on target substrate 40 with

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respect to the configuration of chiplets 20 on source wafer 50. Such an upside-down configuration can be implemented by picking up chiplets 20 from source wafer 50 with a first stamp 10A, transferring chiplets 20 from first stamp 10A to a second stamp 10B, and printing chiplets 20 from second stamp 10B to target substrate 40. The transfer of chiplets from first stamp 10A to second stamp 10B is illustrated in the cross section of FIG. 6. The relative motion between first stamp 10A and second stamp 10B can be in a direction that is not parallel to ridge direction D of first stamp 10A, for example orthogonal or diagonal to ridge direction D of first stamp 10A. Thus, adhesion between the first side of chiplets 20 and first stamp 10A can be less than adhesion between the second side of chiplets 20 and second stamp 10B, transferring chiplets 20 from first stamp 10A to second stamp 10B. According to some embodiments, the distal end (e.g., post surface 17) of second stamp B is not structured. According to some embodiments, the distal end (e.g., post surface 17) of second stamp B is structured and second stamp 10B is similar or identical to first stamp 10A, but is spatially rotated, for example orthogonally, about an axis perpendicular to support surface 15 with respect to first stamp 10A. Moving first stamp 10A in a direction orthogonal to ridge direction D of first stamp 10A relative to second stamp 10B can move second stamp 10B relative to first stamp 10A in a direction parallel to ridge direction D of second stamp 10B. Thus, first stamp 10A can experience multiple delamination fronts 30 (reducing adhesion between chiplet 20 and first stamp posts 16) while second stamp 10B does not experience multiple delamination fronts (and does not experience reduced adhesion between chiplet 20 and second stamp 10B posts 16), thus transferring chiplets 20 from first stamp 10A to second stamp 10B.

FIG. 7 is a flow diagram illustrating the process. According to embodiments of the present disclosure and as illustrated in the successive cross sections of FIGS. 4A-4F, FIG. 6, and the flow diagram of FIG. 7, first and second stamps 10A, 10B can be used for micro-transfer printing chiplets (micro-devices) 20 from a source wafer 50 to a target substrate 40. A motion-control platform 70 is provided in step 100, a chiplet source wafer is provided in step 110, a first stamp 10A is provided in step 120, a second stamp 10B is provided in step 125, and a target substrate 40 is provided in step 130. Chiplet source wafer 50 can comprise a sacrificial layer comprising sacrificial portions 52 separated by anchors 54 attached to chiplets 20 by tethers 22. Chiplets 20 are disposed directly and entirely over sacrificial portions 52. Chiplets 20 are released from source wafer 50 by etching sacrificial portions 52 to form gaps. First stamp 10A comprising rigid substrate 12, optional mesa 14, and posts 16 with a structured post surface 17 comprising ridges 19 spatially separated by grooves 18 is moved by motion-control platform 70 into position in a vertical direction 65 toward and in alignment with source wafer 50 so that the distal end of posts 16 and at least a portion of ridges 19 contact a first side of chiplets 20, temporarily adhering chiplets 20 to posts 16, in step 140 as shown in FIG. 4A. Motion-control platform 70 then removes first stamp 10A from source wafer 50 with chiplets 20 adhered to posts 16 in step 150 by moving first stamp 10A and chiplets 20 adhered to first stamp 10A in a vertical direction 65 away from source wafer 50 as shown in FIG. 4B. The stamp motion can be only in a vertical direction 65 or a combination vertical 65 and horizontal 60 direction either at the same time or sequentially in one or more straight lines or curves.

In step 152, motion-control platform 70 contacts posts 16 of second stamp 10B to a second side of chiplets 20 opposite

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the first side. Motion-control platform 70 then horizontally moves first stamp 10A relative to second stamp 10B in a direction non-parallel (e.g., orthogonal or diagonal) to ridge direction D of first stamp 10A, as shown in FIG. 6. At the same time or subsequently, motion-control platform 70 can move first stamp 10A relative to second stamp 10B in a vertical direction 65 to separate first stamp from second stamp 10B and chiplets 20 adhered to second stamp 10B posts 16 in step 155. Because the relative horizontal motion 60 between first stamp 10A and second stamp 10B can form multiple delamination fronts 30 between posts 16 of first stamp 10A, reducing the adhesion of chiplets 20 to posts 16 of first stamp 10A, chiplets 20 can preferentially adhere to posts 16 of second stamp 10B. In some embodiments, second stamp 10B is similar or identical to first stamp 10A (e.g., has a post surface 17 comprising spatially separated ridges 19 that extend entirely across post surface 17) and, during the transfer in step 152 and as illustrated in FIG. 6, is rotated (e.g., orthogonally) with respect to first stamp 10A so that, during step 152, post surface 17 of posts 16 of first stamp 10A experience multiple delamination fronts 30 and second post surface 17 of posts 16 of second stamp 10B does not, or at least experiences fewer or smaller delamination fronts 30, so that chiplets 20 can preferentially adhere to posts 16 of second stamp 10B.

In step 160, motion-control platform 70 moves second stamp 10B vertically in direction 65 toward target substrate 40 so that chiplets 20 adhered to posts 16 of second stamp 10B contact target substrate 40. A layer 42 of adhesive can, but is not necessarily, coated in optional step 135 on target substrate 40 before chiplets 20 are contacted to target substrate 40 (or to adhesive layer 42 if present) as shown in FIG. 4C. Motion-control platform 70 can also move second stamp 10B in a horizontal direction 60 (direction X or direction Y or a combination of directions X and Y) parallel to a surface of target substrate 40 in step 160. As used herein, a stamp movement is a relative movement of stamp 10 with respect to a substrate (e.g., target substrate 40 or another stamp) and in some embodiments, the substrate or other stamp is moved instead of stamp in a direction opposite to the direction of stamp movement.

In step 175 and as shown in FIG. 4D, chiplets 20 adhered to target substrate 40 (and optionally adhesive layer 42) are removed from stamp posts 16. Motion-control platform 70 optionally moves second stamp 10B in a horizontal direction 60 parallel to a surface of target substrate 40 and, at the same time, before, or after moves second stamp in a vertical direction 65 away from target substrate 40 leaving chiplets 20 adhered to target substrate 40. If second stamp 10B comprises spatially separated ridges 19 on the distal end of posts 16, horizontal stamp motion 60 can be at least partially orthogonal to ridge direction D so that the stress of the relative horizontal motion 60 between chiplets (adhered to target substrate 40 or adhesive layer 42) and posts 16 causes delamination between ridges 19 on the distal end of posts 16, for example on the trailing edge of posts 16 with respect to the relative stamp 10 motion, separating chiplets 20 from posts 16. If second stamp 10B comprises multiple ridges 19 on the distal end of posts 16, the presence of multiple ridges 19 causes multiple delamination fronts 30 to form, decreasing the adhesion between chiplets 20 and the distal end of posts 16. Stamp 10 horizontal and vertical movements in steps 155, 160, and 175 can be, but are not necessarily, continuous and can be separate or combined motions in linear or curved directions. Stamp 10 horizontal and vertical movement in steps 155 and 175 can be continuous or separate, linear or curved, movements and can be combined

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so that stamp 10 moves both horizontally along and vertically away from target substrate 40 surface at the same time or separately. Similarly, step 160 can comprise both a vertical motion toward and a horizontal motion along the target substrate 40 surface in either continuous or separate movements.

Multiple delamination fronts 30 reduce the adhesion between chiplets 20 and the distal end of posts 16 relative to a non-structured post surface 17, thereby increasing the likelihood that chiplet 20 will adhere to target substrate 40 or adhesive layer 42 (improving print yields) and reducing the amount of shear offset necessary to or experienced by chiplet 20 (e.g., the distance chiplet 20 moves with respect to target substrate 40), thereby improving print accuracy. Grooves 18 can be narrower than ridges 19 in a direction orthogonal to ridge direction D. In some embodiments, the area of ridges 19 is greater than the area of grooves 18 (for example much greater, e.g., twice, four times, six times, eight times greater, or more). Consequently, adhesion between chiplets 20 and posts 16 is not greatly reduced (since the area of ridges 19 is only slightly less than the area of post surface 17) and print accuracy and yield are improved.

Relative motion between a stamp 10 and target substrate 40 (or between a first stamp 10A and second stamp 10B) can form delamination fronts 30 along the trailing edge of each ridge 19, as illustrated in FIGS. 4D and 6. If the relative motion is orthogonal to ridge direction D, the delamination fronts 30 will initially form along a line corresponding to an edge of ridges 19 in contact with chiplets 20. However, if the relative motion has a diagonal component (e.g., neither parallel nor orthogonal to ridge direction D), the greatest trailing edge delamination stress can be at a corner of ridges 19, for example on an edge or side of post 16. Thus, delamination can begin at a corner of ridge 19, theoretically at a point, that has less resistance to delamination because the adhesion at the corner of ridge 19 is much smaller and has a much smaller area (theoretically a point) than the adhesion along the edge of ridges 19 (theoretically a line). Thus, posts 16 can delaminate from chiplet 20 easier. Therefore, according to embodiments of the present disclosure, relative motion between a stamp 10 and chiplet 20 or target substrate can be in a diagonal, non-perpendicular, and non-parallel direction relative to ridge direction D of stamp 10. The diagonal direction can be, but is not necessarily, at 45 degrees to the ridge direction D.

The use of a diagonal relative motion is generally useful when printing from a stamp 10 having posts 16 with cross sections parallel to support surface 15 that have straight edges and corners (e.g., a rectangular cross section) where the diagonal motion is diagonal with respect to an edge (or side) of post surface 17. In such embodiments, posts 16 of stamps 10 are peeled from a corner of post 16 to detach chiplets 20 from posts 16. Thus, according to embodiments of the present disclosure, a method of micro-transfer printing comprises providing a stamp 10 comprising a support 13 having a support surface 15 and posts 16 disposed on support surface 15, providing a target substrate 40 having a target substrate surface, and providing a motion-control platform 70 attached to stamp 10. Each post 16 comprises a proximal end in contact with support 13 and a distal end extending away from support 13. Post 16 has a post surface 17 on the distal end of post 16 having edges and corners. A micro-device 20 (e.g., a chiplet 20) is temporarily adhered to each post surface 17. Motion-control platform 70 contacts micro-devices 20 to the target substrate surface. Contacting the micro-devices 20 to the target substrate surface comprises moving micro-devices 20 toward and in contact with

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the target substrate surface, moving micro-devices 20 in a direction parallel to the target substrate surface at least partially in a direction non-parallel to an edge (e.g., diagonally), and moving stamp 10 away from target substrate 40. Moving stamp 10 away from target substrate 40 can be done at the same time, before, or after moving the micro-devices 20 in a direction parallel to the target substrate surface at least partially in a direction non-parallel to an edge. Where stamp 10 comprises posts 16 with structured post surface 17 having spatially separated ridges 19, the direction parallel to the target substrate surface can be orthogonal, diagonal (e.g., at 45 degrees) to ridge direction D.

Separation between posts 16 and chiplets 20 is achieved with less force where delamination fronts 30 can propagate from a corner of post surface 17 or corners of ridges 19 by moving stamp 10 diagonally with respect to an edge of post surface 17 or ridge direction D compared to moving stamp 10 orthogonally to the edge of post surface 17 or ridge direction D. Similarly, separation between posts 16 and chiplets 20 is achieved with less force and in less distance where multiple delamination fronts 30 can propagate from an edge of post surface 17 or edges of ridges 19 by moving stamp 10 orthogonally with respect to an edge of post surface 17 or ridge direction D compared to moving stamp 10 vertically (in vertical direction 65) away from target substrate 40.

Embodiments of the present disclosure have been constructed and demonstrated to micro-transfer print chiplets 20 onto a substrate both without an adhesive layer and with an adhesive layer, for example a 30-60 nm adhesive layer on the substrate.

According to some embodiments, if post 16 has a cross section parallel to support surface 15 that has a point or a shorter trailing edge with respect to a direction of stamp movement, the point or shorter edge can delaminate easier, e.g., requiring less force, so that less force is needed to initially remove stamp 10 from chiplets 20. As delamination proceeds across the post surface 17 of post 16, the delamination front can increase in length from a smaller length (e.g., a point) to a larger length so that the delamination force is initially smaller but increases as the delamination front increases in length. In some embodiments, delamination fronts can grow smaller in length from a greater length to a smaller length (e.g., to a point) so that the delamination force is initially relatively greater but requires less force as delamination proceeds.

As shown in FIGS. 8A-8E, posts 16 can have a cross section parallel to support surface 15 that has first and second edges (sides or ends) 80, 82 in a horizontal stamp motion 60 (delamination direction 60). First edge 80 is the leading edge 80 and second edge 82 is the trailing edge 82 of horizontal stamp motion 60 relative to a chiplet 20 or target substrate 40. Thus, horizontal stamp motion 60 can be in a direction orthogonal to first edge 80 or second edge 82. As shown, first edge 80 is longer than second edge 82, where second edge 82 is the portion of the post edge farthest from the first edge. Second edge 82 can be a line segment, multiple line segments, a point, or multiple points. Thus, the trailing edge (second edge 82) is shorter than the leading edge (first edge 80) so that delamination occurs with less force. FIG. 8A is a perspective illustrating stamp 10 with posts 16 that has a second edge 82 that is a point. FIG. 8B is a plan view of a post 16 with post surface 17 having a shorter edge, FIG. 8C has a point at trailing second edge 82 (corresponding to FIG. 8A), FIG. 8D is a plan view of a post 16 with a trailing second edge 82 forming a trapezoidal post surface 17, FIG. 8E is a plan view of a post 16 with a trailing

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second edge 82 forming a point of a triangular trapezoidal post surface 17, and FIG. 8F is a plan view of a post 16 with a trailing second edge 82 forming multiple points. The trailing point(s) or second edge 82 can concentrate stress from post 16 movement with respect to chiplets 20 that can more readily initiate delamination between post 16 and chiplet 20 when post 16 is moved in a horizontal direction 60 orthogonal to first edge or second edge 82. When moved in direction D, stress at the trailing point(s) or second edge 82 can be reduced. Thus stamps 10 comprising posts 16 with trailing point or second edge 82 can require different amounts of force to detach from chiplets 20 when moved in different directions with respect to chiplets 20, enabling chiplet 20 transfer from first stamp 10A to second stamp 10B, as shown in FIG. 6. According to some embodiments, each post 16 can comprise a single ridge 19 that can extend in a length direction of ridge 19 (e.g., where length is greater than width), for example as shown in FIGS. 8A-8F.

According to some embodiments, stamps 10 comprising posts 16 with one or multiple ridges 19 and grooves 18, a trailing point, or second edge 82 can require less force to micro-transfer print to a target substrate 40, enabling chiplet 20 transfer to target substrate 40 with higher accuracy and precision. According to some embodiments, such transfers can be done to a target substrate 40 with no optional adhesive layer 42 or with a thinner optional adhesive layer 42. According to some embodiments, such transfers can be done to a target substrate 40 having reduced contact adhesion, for example reduced vander Waals forces such as relatively rougher surfaces (e.g., having an RMS surface roughness greater than 0.5 nm) or surfaces comprising metal or a metal alloy.

Thus, according to embodiments of the present disclosure, a stamp 10 for micro-transfer printing can comprise a support 13 having a support surface 15 and posts 16 disposed on support surface 15. Each post 16 comprises a proximal end in contact with support 13 and a distal end extending away from support 13 and has a post surface 17 on the distal end. Post surface 17 (e.g., a cross section of post 16 in a direction parallel to support surface 15) is non-rectangular and has opposing edges or sides with different lengths. Post surface 17 can be triangular or trapezoidal, can have an edge or a side that is triangular or trapezoidal, or can come to a point or corner. A point or corner can be considered to have a length of zero and therefore a post surface 17 with a point on a second edge or side 82 opposing a first edge or side 80 has a different length than the first edge or side 80. A length of the trailing second edge 82 can be shorter or less than the length of the leading first edge 80. Thus, in some embodiments, a stamp 10 for micro-transfer printing comprises a support 13 having a support surface 15 and posts 16 disposed on support surface 15. Each post 16 comprises a proximal end in contact with support 13 and a distal end extending away from support 13. Post 16 has a post surface 17 on the distal end. Post surface 17 can have a first edge 80 having a first length and a second edge 82 opposing first edge 80 having a second length less than the first length. When using stamp 10 for micro-transfer printing, moving stamp 10 in horizontal direction 60 will delaminate from chiplet 20 more readily than moving stamp 10 horizontally in direction D thus enabling transfer with less force or a transfer from one stamp 10 to another rotated stamp 10 as illustrated in FIG. 6.

Non-rectangular post surface 17 shapes as shown in FIGS. 8A-8E can be ridges 19 in stamps 10 according to embodiments of the present disclosure. FIG. 9A is a plan view and FIG. 9B a corresponding cross section taken along

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cross section line A of FIG. 9A of post 16 having spatially separated non-rectangular ridges 19 with opposing sides (e.g., first edge or side 80 and second edge or side 82) having different lengths separated by grooves 18.

FIGS. 10A and 10B are plan views illustrating delamination corners 84 for posts 16 moved in a diagonal delamination direction 60 for a post 16 with rectangular ridges 19 (as shown in FIG. 10A) and a post 16 with non-rectangular ridges 19 (as shown in FIG. 10B). FIG. 10C illustrates diagonal delamination for post 16 with a single rectangular post surface 17. As stamp 10 and post 16 move in delamination direction 60, post 16 can delaminate from chiplets 20 starting at delamination corners 84 and progressing in delamination direction 60 with delamination fronts 30 orthogonal to delamination direction 60.

FIG. 11 illustrates a stamp post 16 where ridges 19 extend in a direction D orthogonal to the direction D of FIGS. 10A and 10B. This arrangement is equivalent to FIG. 10A rotated by 90 degrees. The posts 16 of FIGS. 10A and 11 can both provide multiple delamination fronts and different amounts of adhesion depending on horizontal direction 60 of shear offset.

FIGS. 12A-C illustrate a post 16 with a two-dimensional array of sub-posts 32. Each row or column of sub-posts 32 can be a ridge 19 that is separated into separate sub-posts 32. A two-dimensional array of sub-posts 32 extending across post 16 to define post surface 17 can provide a greater number of delamination fronts 30 during printing. If the spaces (e.g., grooves 18) between sub-posts 32 are relatively small compared to the area of sub-posts 32 and/or post surface 17, the use of sub-posts 32 does not significantly reduce the area of post 16 in contact with chiplet 20. For example, a total surface area of sub-posts 30 at a post surface at a distal end of post 16 can be at least 50%, at least 60%, at least 70%, at least 80%, at least 90%, at least 95%, or at least 98% of a total area of a cross section of a post surface at a distal end of post 16. Sub-posts 32 can have a square cross section at post surface 17, as shown in FIG. 12A and FIG. 12B, or can have a rectangular cross section, as shown in FIG. 12C and can have asymmetric adhesion in different directions, for example as shown in FIG. 11. FIG. 12C illustrates sub-posts 32 in a row (or column) forming ridge 19 (a discontinuous ridge), where the ridge is defined by the long direction of sub-posts 32. Hence, ridges 19 can comprise separate and individual sub-posts 32. In some embodiments, movement of post 16 during printing can be parallel to ridge direction D (where ridge direction D is the length greater than the width of ridge 19). In some embodiments, movement of post 16 during printing can be orthogonal to ridge direction D.

In some embodiments of the present disclosure, ridges 19 comprising one or more sub-posts 32 can extend in a ridge direction D parallel to a print direction of offset shear. FIG. 13 shows a post 16 with ridges 19 each comprising multiple sub-posts 32 arranged in a ridge direction D so that delamination fronts 30 orthogonal to ridge direction D and print direction can move in direction D during printing with offset shear, thus decreasing adhesion between post 16 and component 20 (not shown in FIG. 13) and potentially optimizing or maximizing print yield. FIG. 14 shows ridges 19 each with multiple sub-posts 32. FIG. 15 illustrates embodiments in which each sub-post 32 can have a single point as a trailing edge 82, e.g., as shown in FIGS. 8A, 8C, and 8E. Aligning ridge direction D with the horizontal direction 60 of stamp post 16 movement can improve print yields. In

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some embodiments, the single point can be the leading edge to improve final delamination rather than initial delamination.

In some embodiments, and as illustrated in FIG. 16A, stamp posts 16 can have curved edges, can be cylindrical, or can have a curved cross section parallel to support surface 15 that is at least partially or completely circular, ellipsoidal, or oval. As shown in FIG. 16B, stamp posts 16 can have a combination of planes and curved structures, for example a semi-cylinder with a semicircular cross section parallel to support surface 15. Thus, according to embodiments of the present disclosure, a stamp 10 for micro-transfer printing can comprise a support 13 having a support surface 15 and posts 16 (e.g., stamp posts 16) disposed on support surface 15. Each of posts 16 comprises a distal end extending away from support surface 15 and a post surface 17 on the distal end. The post surface 17 can have a curved or partially curved edge or a portion of post surface 17 can be curved. Post surface 17 can have a straight edge or a portion of post surface 17 can be straight. A curved edge of post surface 17 can substantially form a portion of a circle or a semicircle, an oval, an ellipse, or a curve. Support 13 can comprise multiple layers, for example mesa 14 and flexible or rigid support 12, as shown, for example, in FIG. 1D and elsewhere in the Figures. A surface of any such layer from which post(s) 16 extend is a support surface 15, in some embodiments.

As shown with the arrows of FIG. 16B, stamp 10 can move in a horizontal direction orthogonal to a straight, planar face of stamp posts 16 to print components 20 (not shown in FIGS. 16A, 16B). A trailing edge of stamp post 16 can be curved, thus reducing the initial force necessary to commence peeling post surface 17 from a component 20, delaminating component 20 from post surface 17. In some embodiments, stamp 10 can move in a horizontal direction that is angled with respect to and is not orthogonal to a straight, planar vertical face of stamp posts 16 to print components 20 (where vertical is orthogonal to substrate surface 15). Thus, a trailing edge of stamp post 16 can begin peeling at a point (e.g., a corner of a flat face of stamp post 16) or at a curve, thus reducing the initial force necessary to commence and complete peeling post surface 17 from a component 20.

In some embodiments of the present disclosure and as shown in FIGS. 17A-17D, a stamp 10 for micro-transfer printing can comprise a support 13 having support surface 15 and a compressible (e.g., elastomeric) post 16 disposed on support surface 15. Post 16 can comprise a proximal end in contact with support surface 15 and a distal end with post surface 17 extending away from support 13 and support surface 15 so that post 16 protrudes from support surface 15 to post surface 17 on the distal end of post 16. Post 16 can comprise a blind hole 34 that extends from post surface 17 into post 16. (Hole 34 is not a through hole through stamp 10. That is, a vacuum force cannot be applied through stamp 10 via hole 34.) In some embodiments, post 16 comprises a cutout 36 extending from blind hole 34 to an exterior edge of post 16, for example so that air can pass from hole 34 through post 16 to the local ambient environment. In some embodiments, hole 34 extends less than all of the way from support surface 15 to post surface 17, for example extends only partially from distal end post surface 17 to support surface 15, as shown in FIGS. 17A, 17B. In some embodiments, hole 34 extends entirely from distal end post surface 17 to support surface 15 as shown in FIG. 17D. Post surface 17 can be parallel to support surface 15, for example as shown in FIGS. 17A-18A.

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According to embodiments of the present disclosure, cutout 36 is an absence of material extending from hole 34 through post 16 (e.g., through a wall of post 16) to an exterior edge or side of post 16 (e.g., to a perimeter of post 16) so that gas (e.g., the local atmosphere) can pass in from and out of hole 34 when cutout 36 is open (e.g., not compressed onto component 20). Cutout 36 can refer to material absent from an otherwise planar surface of post 16 parallel to support surface 15 or the material that would have to be added to post 16 to form a planar surface of post 16 parallel to support surface 15. Cutout 36 can be an open (exposed) channel through a portion of post 16, a slit in post 16, or a tunnel (e.g., a closed channel) in post 16 extending from hole 34 in post 16 to a perimeter or exterior surface of post 16. FIGS. 17A-17D illustrate a cutout 36 that forms a high-aspect ratio slit in a wall of post 16.

FIGS. 18A-18B illustrate embodiments with an array of posts 16 on support surface 15 with cutouts 36 in posts 16. FIG. 18A illustrates a cutout 36 that forms a high-aspect ratio slit in a wall of post 16 and FIG. 18B shows a triangular cutout 36 extending from what would otherwise be a flat post surface 17 parallel to support surface 15, e.g., as with portions of post 16 shown in FIG. 18C-18H. In some embodiments, post 16 has a hole 34 extending to post surface 17, as shown in FIG. 17D. Cutout 36 can extend from an exterior of post 16 on one side to hole 34, as shown in FIGS. 17A-17D, or can extend to an exterior of post 16 on two sides as shown in FIG. 18A, for example from one side of post 16 to another, for example opposite, side in a direction parallel to support surface 15.

In some embodiments, the slit is shaped and sized to be open, thereby allowing gas to exit the hole, when the post is compressed and to be closed, thereby preventing gas from entering the hole, when the post is tensioned. In some embodiments, the cutout is shaped and sized to be open, thereby allowing gas to exit the hole, when the post is compressed and to be closed, thereby preventing gas from entering the hole, when the post is tensioned. In some embodiments, the cutout has a width and a height and the width is more than the height (e.g., at least twice the height). In some embodiments, the height of the cutout is no more than 20% (e.g., no more than 10%) of a height of the post. In some embodiments, the post has a height (length) no greater than twenty, ten, five, two, or one microns. In some embodiments, post 16 can be a cylinder or portion of a cylinder or have a circular, oval, or ellipsoidal cross section or portion of a circular, oval, or ellipsoidal cross section parallel to support surface 15, for example as shown in FIGS. 16A-16B, except for cutout 36, for example as shown in FIGS. 17A-17B. In some embodiments, post 16 can be a cube or other rectangular solid or can have a polygonal cross section, sides, or faces, e.g., a rectangular cross section, as shown in FIG. 18A. In some embodiments and as shown in FIGS. 17A-17D, blind hole 34 can be a cylinder or portion of a cylinder or have a circular, oval, or ellipsoidal cross section or portion of a circular, oval, or ellipsoidal cross section parallel to support surface 15, except for cutout 36. In some embodiments, hole 34 can be a cube or other rectangular solid or can have a polygonal cross section, sides, or faces, e.g., a rectangular cross section, as shown in FIG. 18A. A rectangular solid can be a solid with rectangular sides or faces.

In some embodiments, post surface 17 is not, or is not entirely, parallel to support surface 15. FIG. 18B shows post surface 17 entirely non-parallel to support surface 15. In some embodiments and as shown in FIG. 18C, some portions but not all of post surface 17 of post 16 can be parallel

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to support surface 15. FIG. 18C shows examples of post surfaces 17 with a single angled (non-parallel to support surface 15) face and a single parallel face (parallel to support surface 15) with a triangular cutout 36. (Here the shape of cutout 36 is taken as a cross section orthogonal to support surface 15 from the distal end of post 16, e.g., along the length of post 16.) FIGS. 18D-18F illustrate embodiments with two portions of post surface 17 of post 16 parallel to support surface 15 spatially separated by cutout 36 (indicated with the dashed lines). FIG. 18D shows examples of post surfaces 17 with two angled (non-parallel to support surface 15) faces and two spatially separated parallel faces (parallel to support surface 15) separated by a wide V-shaped cutout 36. FIG. 18E shows examples of post surfaces 17 with two spatially separated parallel faces (parallel to support surface 15) separated by a rectangular cutout 36. FIG. 18F shows examples of post surfaces 17 with two spatially separated parallel faces (parallel to support surface 15) separated by a rectangular stepped cutout 36. Thus, cutouts 36 can be wider or larger at post surface 17 (at the top, distal end) than where cutout 36 is closer to support surface 15 (towards the bottom, proximal end). It can be difficult to construct angled faces (non-parallel or non-orthogonal to a process surface) such as a V-shape as shown in FIGS. 18C and 18D. An angled surface can be approximated with a series of small stair-steps (e.g., as shown in FIGS. 18E, 18F) and any reference to an angled surface herein can refer to a series of stair steps (alternating vertical and horizontal surfaces) extending from post surface 17 to hole 34 or forming cutout 36. In these embodiments, cutout 36 can be wider than it is high. In some embodiments, cutout(s) 36 can be higher than they are wide (as shown in FIGS. 17A-17D), e.g., cutouts 36 can be relatively shallow with respect to the height of posts 16. FIG. 18I illustrates a cutout 36 that is a tunnel through a wall of post 16 to hole 34. FIG. 18J illustrate a hole 34 that extends to a step in post surface 17 so that cutout 36 has a rectangular cross section one two sides of post 16 (as shown) or can be present on only one side of post 16 (not shown in the Figures). In some embodiments, cutout 36 has a width and a height and the width is more than the height (e.g., at least twice the height). In some embodiments, a height of cutout 36 is no more than 20% (e.g., no more than 10%) of a height of its post 16.

In some embodiments and as shown in FIGS. 17A-18A, cutout 36 is arranged on a diagonal of hole 34 or is arranged on a line that intersects a center of hole 34. In some embodiments, cutout 36 can be arranged so that it is not on a line that intersects a center of hole 34, for example cutout 36 can be arranged on a tangent to hole 34 or extends parallel to and in contact with an edge of hole 34, as shown in FIGS. 18G and 18H. The location of cutout 36 with respect to hole 34 can enable the opening and closing of cutout 36 when picking up components 20 from source wafer or when printing component 20 to target substrate 40, and can help to control delamination during shear, for example a diagonal shear. In some embodiments, cutout 36 can be disposed on a side of post 16 that is at the leading edge of the delamination front so as to open as quickly as possible during printing, e.g., during post 16 horizontal (e.g., shear) movement, thereby releasing any suction between post 16 and component 20.

Blank hole 34 in post 16 provides an ambient gas (e.g., air) reservoir (hole 34) that, when post 16 is compressible, can decrease in size when post 16 is compressed or increase in size when post 16 is tensioned (e.g., stretched or elongated from support surface 15 to post surface 17 in a direction orthogonal to support surface 15). Cutouts 36, as

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shown in FIGS. 17A-18F, can open or remain open and allow gas (e.g., air) to exit hole 34 when post 16 is compressed and cutout 36 can close to seal hole 34 and prevent gas from entering hole 34 when post 16 is tensioned. Thus, suction can be applied to component 20 when post 16 contacts component 20 and hole 34 is under tension, for example due to change in volume of hole 34 while hole 34 is sealed. In some embodiments, for example in which cutout 36 is wider than high, post 16 can be compressed to an extent (e.g., as shown with the arrows in FIGS. 18C-18F) so that the entire perimeter of hole 34 is in contact with a component 20 so that when post 16 is tensioned (for example, stretched or elongated) the entire perimeter of hole 34 is in contact with component 20, at least initially or in part, so that gas is prevented or inhibited from entering hole 34, providing suction between component 20 and stamp post 16. The inhibition or prevention of gas flow into hole 34 need only be momentary to enable increased force between stamp post 16 and component 20, for example during the pick-up portion of a micro-transfer printing process.

The post 16 structures with holes 34 can be applied to sub-posts 32 so that one or more sub-posts 32 comprise a hole 34 and cutout 36. The hole 34 and cutout 36 in sub-posts 32 can operate similarly to hole 34 and cutout 36 in posts 16.

As shown in the flow diagrams of FIGS. 5, 7, and 19 and the successive cross sections of FIGS. 20A-20F, methods of the present disclosure can comprise providing a stamp 10 having a post 16 with a hole 34 and cutout 36 on a support surface 15 in step 120, providing a component 20 (component 20) physically connected to a component source wafer 50 by a component tether 22 in step 110, providing a motion-control platform 70 in step 100 (shown in FIGS. 4A-4F), pressing post 16 against component 20 with motion-control platform 70 (shown in FIG. 20A) in step 140 to compress post 16 with an open cutout 36 in step 141 (shown in FIG. 20B), and pulling support surface 15 away from component 20 to tension post 16 with a sealed hole 34 (closed cutout 36) (shown in FIG. 20C) in step 151 and remove component 20 from component source wafer with motion-control platform 70 in step 150 (shown in FIG. 20D). Stamp 10 and source wafer 50 can be separated from each other by moving stamp 10 away from source wafer 50, moving source wafer 50 away from stamp 10, or moving both stamp 10 and source wafer 50 in relative motion away from each other.

In some embodiments, for example if cutout 36 is higher than wide, for example as shown in FIGS. 17A-17D, 18A, compressing post 16 compresses hole 34 and opens cutout 36 to allow the flow of gas (e.g., ambient gas such as air or an ambient local atmospheric gas) from hole 34 and cutout 36 to the local environment external to post 16 in step 141, so that the gas (e.g., air) pressure in hole 34 and cutout 36 is the ambient, atmospheric pressure. In some embodiments, for example where cutout 36 is wider than high as shown in FIGS. 18B-18F, cutout 36 is open when initially compressing post 16 to allow the flow of gas (e.g., ambient gas, such as air) from hole 34 and cutout 36 to the local environment external to post 16 and then closes when post 16 is compressed until a perimeter of hole 34 is in contact with component 20 thereby sealing hole 34 (shown with the arrows in FIGS. 18C-18F), so that the air pressure in hole 34 and cutout 36 is the ambient, atmospheric pressure. In some embodiments, compressing post 16 reduces the volume of hole 34 and thus the quantity of gas (e.g., air) in hole 34. In some embodiments, compressing post 16 reduces the volume of cutout 36 and the quantity of gas (e.g., air) in cutout

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36. In some embodiments, compressing post 16 reduces the volume of hole 34 and cutout 36 and the quantity of gas (e.g., air) in hole 34 and cutout 36. Thus, in some embodiments, cutout 36 is continuously open to allow equilibration with ambient until hole 34 becomes sealed against component 20 and, in some embodiments, cutout 36 opens under compression only while hole 34 is sealed against component 20 to allow gas to exit hole 34 (e.g., which may lead to equilibration depending on the amount of time sufficient compression is applied). In cases where cutout 36 is substantially sealed against component 20, rapid separation of stamp 10 from source wafer 50 (e.g., as is normal during pick-up in micro-transfer printing) can cause suction, due to tension on post 16, to be applied before re-equilibration of gas pressure in hole 34 occurs.

Post 16 can be compressed by the movement of stamp 10 controlled by motion-control platform 70 pressing post 16 against component 20 on component source wafer in step 141. Post 16 can be tensioned (e.g., stretched or elongated) in a direction orthogonal to a surface of component 20 in contact with post 16) by the relatively rapid movement of stamp 10 controlled by motion-control platform 70 pulling post 16 away from component source wafer 50 in step 151. Post surface 17 of post 16 can remain adhered to the surface of component 20 by means of van der Waals forces so that motion-control platform 70 pulls post 16 and post 16 pulls component 20 physically connected to component source wafer 50 with component tether 22 away from component source wafer 50 relatively quickly, increasing the rate-dependent adhesion between post 16 and component 20. Since component source wafer 50 is firmly held in position by motion-control platform 70, motion-control platform 70 provides tension in post 16 by pulling stamp 10 away from component source wafer 50 as component source wafer 50 is held in position. This tension stretches and elongates post 16 (as shown in FIG. 20C), enlarging and increasing the volume of hole 34, and optionally cutout 36, thereby reducing the air pressure in hole 34, since hole 34 is sealed and gas is prevented or is at least inhibited from flowing into hole 34, thus providing at least momentary suction between post 16 and component 20, increasing the force (e.g., tension) applied between post 16 and component 20. The suction due to reduced gas pressure in hole 34 can be greater than the additional adhesion of post 16 to component 20 if hole 34 were not present and hole 34 in contact with component 20 was filled with post 16 material (e.g., PDMS). Thus, the gas pressure within hole 34 is greater when post 16 is in compression and smaller when post 16 is in tension so that embodiments of the present disclosure provide greater force between post 16 and component 20 when removing component 20 from component source wafer 50 (steps 140, 141), increasing process yields for removing component 20 from component source wafer 50 with stamp 10 under the control of motion-control platform 70.

Once component 20 is removed from component source wafer 50 (e.g., once tether 22 is broken or separated), no tension is applied between post 16, component 20, and component source wafer 50 so that post 16 material relaxes and cutout 36 can open, allowing ambient gas (air, atmosphere) to enter cutout 36 and hole 34, so that the air pressure in hole 34 and cutout 36 is at ambient atmospheric pressure and no longer at a reduced pressure, as shown in FIG. 20D. Once that has happened, in some embodiments, for example as illustrated with the posts in FIGS. 18B-18F, the post surface 17 area of post 16 in contact with component 20 is also reduced, reducing the adhesion between post surface 17 and component 20. In some embodiments, the

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suction is too strong to permit relaxation of post 16 material to open cutout 36 without further force applied to stamp 10 or component 20. Such suction may increase the force between post 16 and component to the point that successful printing of component 20 to target substrate 40 could be inhibited or prevented. That is, even employing rate-dependent adhesion using a vertical movement to print component 20, the adhesion between target substrate 40 and component 20 (e.g., especially where no adhesive is used on target substrate 40) can be too weak to release component 20 from stamp 10 onto target substrate 40 when suction remains. To solve this problem, in some embodiments, cutout 36 can be opened during printing to release the suction, for example when printing with shear. The shear applied as component 20 contacts target substrate 40 can act to open cutout 36 if cutout 36 did not open as post 16 did. As it can be difficult to assess whether cutout 36 opens or remains closed due to suction during normal transit of components 20 between source wafer 50 and target substrate 40, in some embodiments, shear is employed during printing regardless of the state of cutout 36 to ensure opening.

In some embodiments, further compression is applied to post 16 at target substrate to open cutout 36 and release any suction. Slow separation of stamp 10 from source wafer 50 can ensure that pressure in hole 34 equilibrates with ambient to sufficiently reduce or eliminate any suction. Shear can be used to delaminate post surface 17 from component even if cutout 36 has already been opened after pick-up of components 20 from source wafer 50 and no suction remains, even if the shear would not otherwise be sufficient to open cutout 36 on its own.

Embodiments of the present disclosure can comprise providing a target substrate 40 in step 130 and contacting component 20 to target substrate 40 in step 160, as shown in FIG. 20E. As shown in FIG. 20F, in step 176, stamp 10 is removed relatively slowly from component 20 to print component 20 to target substrate 40. Some embodiments comprise moving stamp 10 vertically from target substrate 40 to adhere component 20 to target substrate 40. The force provided by contacting component 20 to target substrate 40 can be less than the force provided by contacting post 16 to component 20 in steps 140, 141 so that cutout 36 remains open. Thus, force between component 20 and post 16 is smaller when component 20 is contacted to target substrate 40 in step 160 than when component 20 is removed from component source wafer 50 and adhered to post 16 in step 150 because air pressure in hole 34 is less than ambient atmospheric pressure so that no or little suction is present and, optionally, the area of post 16 in contact with component 20 is smaller, reducing the vander Waals force adhering component 20 to post 16.

Some embodiments comprise moving stamp 10 at least horizontally with respect to target substrate 40 and the direction of motion opens cutout 36 or causes cutout 36 to remain open, thus avoiding any suction due to air pressure between component 20 and post 16.

(For clarity of illustration posts 16 and support surface 15 are shown inverted or upside-down in FIGS. 16A-18F with respect to their position when picking or printing components 20.) As shown in FIGS. 21A-21F, sub-posts 32 of stamp posts 16 can be aligned with and adjacent to component tethers 22 so that mechanical stress created by sub-posts 32 of stamp posts 16 pressing or pulling component 20 with respect to component source wafer can preferentially stress and fracture component tethers 22 instead of stressing the body of component 20 during removal of component 20 from component source wafer 50, thereby increasing trans-

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fer yields and decreasing damage, or at least stress, to components 20. Such techniques can be especially useful for components 20 with two or more component tethers 22 and components 20 with large length-by-width aspect ratios, for example micro-lasers. FIG. 21F illustrates post 16 and sub-post 32 compressed with respect to the cross section of FIG. 21E.

Thus, according to embodiments of the present disclosure, a system for micro-transfer printing comprises a component source wafer 50 (component source wafer 50) comprising a sacrificial portion 52, a component 20 (e.g., component 20 or component disposed completely and directly over sacrificial portion 52, and tethers 22 connecting component 20 to anchor portions 54 of component source wafer 50 at tether locations, and a stamp 10 comprising a stamp support 12 having a support surface 15 and one or more posts 16 disposed on support surface 15. The distal end of post 16 has a structured three-dimensional surface comprising sub-posts 32 (micro-posts 32) that extend away from support surface 15 at sub-post locations. The sub-post locations are disposed adjacent to the tether locations when sub-posts 32 are in contact with component 20. A tether location can be an area of component source wafer 50 comprising only tether 22 and a sub-post location can be an area of component source wafer 50 comprising only the area of component source wafer 50 in contact with sub-post 32. A sub-post location adjacent to a tether location can be in contact with the tether location (e.g., an edge of a sub-post location can be coterminous with an edge of a tether location, e.g., having a common border), can be closer to a tether location than to a center of component 20, or can be closer to a tether location than to any other tether location).

Sub-posts 32 can be compressible and portions of the distal end of post 16 between sub-posts 32 and sub-posts 32 can be in a common plane when sub-posts 32 are under mechanical pressure, thereby increasing the area of post surface 17 in physical contact with component 20, as shown in FIG. 21F. Sub-posts 32 can be pyramidal, cylindrical, cubic, or have polygonal surfaces or faces. Furthermore, such sub-post structures 32 can enable improved contact between post 16 and components 20 when components 20 have some curl and are not substantially flat.

Embodiments of the present disclosure enable micro-transfer printing with transfer stamps having both improved pickup and improved printing. A typical unstructured stamp post 16 has an area of a distal end of stamp post 16 in contact with a micro-device for pickup and print. By using viscoelastic materials and rate-dependent adhesion, stamp post 16 can pick up micro-device 20 at a pickup rate greater than a print rate for printing micro-device 20 on a target substrate 40. A larger area of stamp post 16 in contact with micro-device 20 improves pickup but makes printing more difficult. A smaller area of stamp post 16 in contact with micro-device 20 improves printing but makes pickup more difficult. Using a structured stamp post 16 according to embodiments of the present disclosure enables further differentiation between the pickup process and the print process (e.g., a larger process window), for example in pickup and print rate differences and in the amount of shear offset, thus improving yields on both pickup and printing by providing multiple delamination fronts for printing. Thus, a larger stamp area for post 16 can improve pickup yields and at the same time improve print yields by using multiple delamination fronts 30.

According to some embodiments of the present disclosure, a method of making a stamp 10 for micro-transfer printing comprises providing a mold defining optional mesa

14 and one or more posts 16 disposed on and in direct contact with mesa 14 that extend away from mesa 14, providing a rigid support 12 in or in contact with the mold, providing liquid curable stamp material in the mold (e.g., by injecting at approximately psi pressure), curing the curable stamp material at a cure temperature (e.g., at approximately 60° C. for approximately 240 minutes in an oven) to form cured stamp material, and cooling rigid support 12 and cured stamp material to an operating temperature different from the cure temperature. In some embodiments, methods of the present disclosure comprise removing the mold to provide a stamp 10 for micro-transfer printing. Posts 16 can be disposed in a regular array over rigid support 12 and mesa 14 and posts 16 extending away from mesa 14 and rigid support 12 can be collectively disposed in a regular array over mesa 14 and rigid support 12. Rigid support 12 can have a coefficient of thermal expansion (CTE) that is greater than a post 16 or mesa 14 material CTE. Mesa 14 and posts 16 can comprise a common material (e.g., PDMS). Rigid substrate can be glass. Molds can be silicon masters formed in a silicon substrate (wafer) using photolithographic methods and materials.

The present disclosure provides structures and methods that facilitate micro-transfer printing of micro-devices (chips) 20 on a source wafer 50 (e.g., as shown in FIG. 4A), especially substrates such with an extensive surface as an integrated circuit wafer. Micro-devices 20 are formed on a source wafer 50, each micro-device 20 is contacted by a different post 16 of a stamp 10 under the control of a motion-control platform 70 to detach micro-devices 20 from source wafer 50 and adhere micro-devices to posts 16 of stamp 10, and micro-devices 20 are pressed against a target substrate 40 to adhere micro-devices 20 to target substrate 40, forming a micro-transfer printed system. Stamp 10 is then moved away from target substrate 40, leaving micro-devices 20 on target substrate 40. Different stamp steps can be applied to micro-devices 20 from different source wafers 50, for example thereby forming a heterogeneous micro-system on target substrate 40 comprising a variety of different micro-devices 20 constructed in different materials, for example silicon and various compound semiconductors such as GaN or GaAs.

Micro-transfer printable micro-devices 20 can have, for example, one or more of a width from 1-200 μm (e.g., 1-8 μm), a length from 1-400 μm (e.g., 5-10 μm), or a height from 0.5-50 μm (e.g., 0.5-20 μm or 0.5-3 μm). More generally, micro-transfer printable micro-devices 20 can comprise or be a variety of chiplets 20 comprising conductor or semiconductor structures, including, but not limited to, active components such as any one or more of a diode, a light-emitting diode (LED), a transistor, a laser, an integrated circuit, a photonic integrated circuit, and active electrical components, or passive electrical components such as any one or more of resistors, capacitors, conductors, and electrical jumpers. Micro-transfer printable micro-device 20 can be an unpackaged die. In some embodiments, micro-transfer printable micro-device 20 is a compound element having a plurality of active or passive elements, such as multiple semiconductor micro-devices 20 with separate substrates, each with one or more active elements or passive elements, or both. In certain embodiments, the plurality of elements is disposed and interconnected on a compound element substrate separate from the substrates of any semiconductor micro-devices 20 or a different substrate. The compound element can be a micro-device 20 and can be micro-transfer printed itself after the elements have been arranged and interconnected thereon. The micro-transfer

printable micro-device 20 can be, include, or comprise electronic processors, controllers, drivers, light-emitting diodes, photodiodes, light-control micro-devices 20, or light-management micro-devices 20.

Micro-transfer printing enables printed structures with low-cost, high-performance heterogeneous arrays of electrically connected micro-devices 20 such as integrated circuits, photonic elements such as lasers, sensors, photodiodes, light pipes, or micro-light-emitting diodes (LEDs) useful, for example, in display or photonic systems. Micro-transfer printable micro-devices 20 can be light emitters or integrated circuits, for example CMOS integrated circuits made on or in a silicon source wafer 50, light-emitting diodes (LEDs) or lasers, for example made on or in a GaN, GaAs, or InP compound semiconductor source wafer 50, or silicon photodiodes. For example, described herein are micro-assembled heterogeneous arrays of micro-devices 20, such as integrated circuits, lasers, or micro-LEDs, that are too small, numerous, or fragile to be assembled by conventional means. Rather, these arrays are assembled using micro-transfer printing technology.

Components 20 (e.g., micro-devices 20) may be prepared on a native source wafer 50 and printed to a target substrate 40 (e.g., plastic, metal, glass, ceramic, sapphire, transparent materials, opaque materials, rigid materials, or flexible materials), thereby obviating the manufacture of micro-devices 20 on target substrate 40. Source wafers 50 can have a dimension (e.g., a diameter) no less than 25 mm (e.g., no less than 51 mm, no less than 76 mm, no less than 10 mm, no less than 150 mm, no less than 200 mm, no less than 300 mm, no less than 450 mm, or no less than 675 mm, e.g., a 2-inch, 4-inch, 8-inch, or 12-inch wafer).

Chiplets 20 (e.g., components 20) can be small integrated circuits. Chiplets 20 can be unpackaged dies released and detached from a source wafer 50 and can be micro-transfer printed and incorporate a broken (e.g., fractured) or separated chiplet tether 22. Chiplets (micro-devices) 20 can have at least one of a width, a length, and a height of, for example, from 2 μm to 1 mm (e.g., 2 to 5 μm , 5 to 10 μm , 10 to 20 μm , 20 to 50 μm , 50 μm to 100 μm , 100 μm to 250 μm , 250 μm to 500 μm , or 500 μm to 1000 μm). Chiplets can, for example, have a doped or undoped semiconductor substrate thickness of 2 to μm , 5 to 10 μm , 10 to 20 μm , or 20 to 50 μm . Chiplets 20 or micro-transfer printable micro-devices 20 can have a length greater than width, for example having an aspect ratio greater than or equal to 2, 4, 8, 10, 20, or 50 and component contact pads that are adjacent to the ends of micro-transfer-printable micro-devices 20 along the length of micro-transfer-printable micro-devices 20.

Components 20 can be any of a wide variety of devices, such as, for example but not limited to, electronic, optical, optoelectronic, mechanical, or piezoelectric devices. Components 20 can be optically emissive or responsive and can be light emitters (such as LEDs), light sensors (such as photodiodes), lasers, or electrical jumpers. Components 20 can be integrated circuits (for example CMOS, bipolar, or mixed circuits) and comprise electronically active or passive electronic elements or both. Components 20 can be constructed using photolithographic methods and materials. Components 20 can have, for example, at least one of a width, length, and height from 2 μm to 1000 μm (for example 2 to 5 μm , 5 to 10 μm , 10 to 20 μm , 20 to 50 μm , 50 μm to 100 μm , 100 μm to 250 μm , 250 μm to 500 μm , or 500 μm to 1000 μm). Components 20, for example, can have a substrate thickness from 2 μm to 50 μm (for example from 2 to 5 μm , 5 to 10 μm , 10 to μm , or 20 to 50 μm). Components 20 can have a length greater than width, for

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example having an aspect ratio greater than or equal to 2 (for example greater than or equal to 4, 8, 10, 20, or 50).

A component **20** can be an active circuit component, for example including one or more active electronic components such as electronic transistors or diodes or light-emitting diodes or photodiodes that produce an electrical current in response to ambient light. A component **20** can be a passive component, for example including one or more passive elements such as resistors, capacitors, or conductors. In some embodiments, a component **20** includes both active and passive elements. A component **20** can be a semiconductor device having one or more semiconductor layers, such as an integrated circuit. A component **20** can be an unpackaged die. In some embodiments, a component **20** is a compound device **20** having a plurality of active or passive elements, such as multiple semiconductor components with separate substrates, each with one or more active elements or passive elements, or both. Components **20** can be or include, for example, electronic processors, controllers, drivers, light-emitting diodes, photodiodes, light-control devices, light-management devices, piezoelectric devices, acoustic wave devices (e.g., acoustic wave filters), optoelectronic devices, electromechanical devices (e.g., microelectromechanical devices), photovoltaic devices, sensor devices, photonic devices, magnetic devices (e.g., memory devices), or elements thereof.

In certain embodiments, formation of a printable micro-device **20** begins while the semiconductor structure remains on a substrate, such as a sapphire substrate. After partially forming printable micro-device **20**, a handle substrate is attached to the semiconductor structure opposite the substrate such that the semiconductor structure is secured to the handle substrate. The substrate, such as the sapphire substrate, may then be removed from the system using various techniques, such as laser ablation, grinding, etching, and polishing. After the substrate is removed, formation of the semiconductor structure can be completed, if necessary, to form printable micro-device **20** and printable micro-device **20** may be micro-transfer printed to a target substrate **40**, thereby enabling parallel assembly of high-performance semiconductor micro-devices **20** (e.g., to form micro-LED displays or photonic systems) onto virtually any substrate material (e.g., target substrate **40**), including glass, plastics, metals, other semiconductor materials, or other non-semiconductor materials.

Micro-structured stamps **10** (e.g., elastomeric, electrostatic stamps, or hybrid elastomeric/electrostatic stamps) can be used to pick up the disclosed micro-devices **20**, transport micro-devices **20** to a destination, and print micro-devices **20** onto a target substrate **40**. In some embodiments, surface adhesion forces are used to control the selection and printing of these micro-devices **20** onto destination substrate **40**. This process may be performed massively in parallel. Stamps **10** can be designed to transfer a single micro-device **20** or hundreds to thousands of micro-devices **20** or other discrete structures in a single pick-up and print operation. For a discussion of micro-transfer printing generally, see U.S. Pat. Nos. 7,622,367 and 8,506,867, each of which is hereby incorporated by reference in its entirety. Moreover, these micro-transfer printing techniques can be used to print semiconductor micro-devices **20** at temperatures compatible with assembly on plastic polymer substrates (e.g., target substrates **40**). In addition, semiconductor materials may be printed onto large areas of target substrates **40** thereby enabling continuous, high-speed printing of micro-devices **20**.

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Posts **16** extend from optional mesa **14**, if present, in a direction away from mesa **14** and away from rigid substrate **12**. Stamp posts **16** can have, for example, a length ranging from 5 μm to 100 μm (e.g., 20 μm). Posts **16** can have an aspect ratio (height-to-width) of, for example from 1:4 to 4:1. Posts **16** can have a size that is larger or smaller than the size of a micro-device **20** that posts **16** are designed to contact. Each post **16** is designed to contact a single different micro-device **20** so that each stamp post **16** contacts only one micro-device **20** and each micro-device **20** is contacted by only one stamp post **16**. In some embodiments, multiple stamp posts **16** can contact a single micro-device **20**. For example, posts **16** can have a length extending from mesa **14** that is no greater than 200 μm (e.g., no greater than 100 μm , no greater than 50 μm , no greater than 20 μm , no greater than 10 μm , no greater than 5 μm , no greater than 3 μm , no greater than 2 μm , no greater than 1 μm , or no greater than 0.5 μm). These ranges and values are illustrative and not limiting and other materials and sizes are contemplated in the present disclosure. Additionally, posts **16** can have a shape that is the same as or different from the shape of micro-device **20** that is picked up by stamp **10**. For example, in an embodiment a circular post **16** is used to pick up an 85 μm square chiplet **20**. In some embodiments, for example, a 60 μm square post **16** is used to pick up an 85 μm square micro-device **20**.

In some embodiments, optional mesa **14** can have a range of thickness from 100 μm to 10 mm. Mesas **14** or posts **16** of the present disclosure can comprise or be made of conformal materials such as a visco-elastic material or an elastomer, for example polydimethylsiloxane (PDMS), an optically clear polymeric organosilicon compound. The stiffness and CTE of PDMS can be controlled by forming PDMS with different ratios of constituents. For example, Dow Sylgard 184 Elastomer Base and Curing Agent by Dow Corning Corporation of Auburn, MI, can be mixed at a ratio from 1 part elastomer base to 1 part curing agent by weight to 50 parts elastomer base to 1 part curing agent by weight (e.g., ten parts elastomer base to one part curing agent by weight) to provide PDMS with varying stiffness and CTE.

Mesas **14** and posts **16** can be formed from a mixture having a ratio of elastomer to curing agent in a range of 1:1 to 15:1, for example made in a ratio of about 10:1 elastomer to curing agent (e.g., varying no more than 10% from a ratio of 10:1). In some embodiments, mesa **14** is made of the same material in the same proportions as posts **16** and have the same stiffness and CTE. Alternatively, mesa **14** includes the same material as posts **16** but in different proportions or includes different materials. Using the same materials in different proportions in mesa **14** and posts **16** enables the stiffness and CTEs of the different layers to be separately controlled. For example, in some embodiments, mesa **14** is stiffer than posts **16** or has a smaller CTE than posts **16**. Thus, in some embodiments, mesa **14** is more rigid than posts **16** and the mesa CTE is smaller than the post CTE. For example, mesa **14** can be made with a ratio of 2:1 to 8:1 elastomer to curing agent, for example about 5:1, and posts **16** can be made in a ratio of 8:1 to 14:1 elastomer to curing agent, for example about 10:1.

According to some embodiments of the present disclosure, rigid support **12** has a dimension (e.g., diameter, length, or width) no less than 25 mm (e.g., no less than 50 mm, no less than 100 mm, no less than 150 mm, no less than 200 mm, no less than 300 mm, no less than 450 mm, or no greater than 675 mm) or a thickness no less than 0.5 mm (e.g., no less than 0.75 mm, no less than 1 mm, no less than 2, no less than 5 mm, or no less than 10 mm). These ranges are illustrative and not limiting and other materials and sizes

are contemplated in the present disclosure. According to some embodiments of the present disclosure, rigid support **12** can be or comprise glass (e.g., a portion of a flat-panel display substrate), soda-lime glass, borosilicate glass, quartz, sapphire, pyrex, metal, ceramic, polymer, a cured epoxy, or a semiconductor (e.g., a wafer or portion of a wafer). Rigid support **12** can be made from, for example, glass or plastic (e.g., polycarbonate (PC), poly(methyl methacrylate) (PMMA), polyethylene terephthalate (PET), or polyethylene naphthlate (PEN)). Rigid support **12** can be thicker, the same thickness as, or thinner than mesa **14**. Rigid support **12** can be, for example, no less than 500 microns thick (for example no less than 700 microns, 1 mm, 2 mm, 3 mm, 5 mm, or 1 cm thick). The linear CTE can be from $5 \times 10^{-6}/K$ to $10 \times 10^{-6}/K$ (e.g., approximately $8.5 \times 10^{-6}/K$). In some embodiments, the CTE of rigid support **12** can be approximately equal to the CTE of micro-devices **20** or target substrate **40**, for example within 10%.

The micro-transfer printable micro-devices **20** can include active elements such as electronic circuits formed using lithographic processes and can include passive elements such as electrical connections, e.g., wires. In some embodiments, micro-transfer printable micro-devices **20** are small integrated circuits, for example chiplets **20**, having a thin substrate with a thickness of only a few microns, for example less than or equal to 25 microns, less than or equal to 15 microns, or less than or equal to 10 microns, and a width or length of 5-10 microns, 10-50 microns, 50-100 microns, or 100-1000 microns. Such chiplet **20** printable component structures can be made in a semiconductor source wafer (e.g., a silicon or GaN wafer) having a process side and a back side used to handle and transport source wafer **50**. Micro-transfer printable micro-devices **20** are formed using lithographic processes in an active layer on or in the process side of source wafer **50**. An empty release layer space (e.g., sacrificial portion **52**) is formed beneath micro-transfer printable micro-devices **20** with tethers **22** connecting micro-transfer printable micro-devices **20** to source wafer **50** in such a way that pressure applied against micro-transfer printable micro-devices **20** breaks (e.g., fractures) or separates tethers **22** to detach micro-transfer printable micro-device **20** from source wafer **50** (e.g., with stamp **10**). Methods of forming such structures are described, for example, in Cok et al., "AMOLED Displays using Transfer-Printed Integrated Circuits," Society for Information Display, Vol. 40, Issue 1, pp. 947-950, and U.S. Pat. No. 8,889,485, entitled Methods of Surface Attachment of Flipped Active Components, issued Nov. 18, 2014.

According to various embodiments, a native source wafer **50** can be provided with micro-transfer printable micro-devices **20**, release layer (e.g., a layer of native source wafer **50** comprising sacrificial portion **52**), and tethers **22** already formed, or they can be constructed as part of a process of the present disclosure.

Source wafer **50** and micro-transfer printable micro-device **20**, stamp **10**, motion-control platform **70**, and target substrate **40** can be made separately and at different times or in different temporal orders or locations and provided in various process states.

Methods, in some embodiments, can be iteratively applied to a single or multiple target substrates **40**. By repeatedly transferring sub-arrays of micro-transfer printable micro-device **20** from a source wafer **50** to a target substrate **40** with a stamp **10** and relatively moving stamp **10** and target substrate **40** between stamping operations by a distance equal to the spacing of the selected micro-transfer printable micro-devices **20** in the transferred sub-array between each

transfer of micro-transfer printable micro-device an array of micro-transfer printable micro-device **20** formed at a high density on a source wafer **50** can be transferred to a target substrate **40** at a much lower density. In practice, source wafer **50** is likely to be expensive, and forming micro-transfer printable micro-devices **20** with a high density on source wafer **50** will reduce the cost of micro-transfer printable micro-devices **20**, especially as compared to forming components on target substrate **40**. Transferring micro-transfer printable micro-device **20** to a lower-density target substrate **40** can be used, for example, if micro-transfer printable micro-devices **20** manage elements distributed over target substrate **40**, for example in a display, digital radiographic plate, or photovoltaic system.

In particular, in the case wherein active micro-transfer printable micro-device **20** is an integrated circuit formed in a crystalline semiconductor material, the integrated circuit substrate provides sufficient cohesion, strength, and flexibility that it can adhere to target substrate **40** without breaking as transfer stamp **10** is removed.

In comparison to thin-film manufacturing methods, using densely populated source wafers **50** and transferring micro-transfer printable micro-devices **20** to a target substrate **40** that requires only a sparse array of micro-transfer printable micro-devices **20** located thereon does not waste or require active layer material on a target substrate **40**. The present invention can also be used in transferring micro-transfer printable micro-devices **20** made with crystalline semiconductor materials that have higher performance than thin-film active components. Furthermore, the flatness, smoothness, chemical stability, and heat stability requirements for a target substrate **40** used in certain embodiments of the present disclosure may be reduced because the adhesion and transfer process is not substantially limited by the material properties of the target substrate **40**. Manufacturing and material costs may be reduced because of high utilization rates of more expensive materials (e.g., the source wafer **50**) and reduced material and processing requirements for target substrate **40**.

Having described certain implementations of embodiments, it will now become apparent to one of skill in the art that other implementations incorporating the concepts of the disclosure may be used. Therefore, the disclosure should not be limited to certain implementations, but rather should be limited only by the spirit and scope of the following claims.

Throughout the description, where apparatus and systems are described as having, including, or comprising specific components, or where processes and methods are described as having, including, or comprising specific steps, it is contemplated that, additionally, there are apparatus, and systems of the disclosed technology that consist essentially of, or consist of, the recited components, and that there are processes and methods according to the disclosed technology that consist essentially of, or consist of, the recited processing steps.

It should be understood that the order of steps or order for performing certain action is immaterial so long as operability is maintained. Moreover, two or more steps or actions in some circumstances can be conducted simultaneously.

PARTS LIST

A cross section line
 B cross section line
 D ridge direction
 X x dimension/x direction
 Y y dimension/y direction

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Z z dimension/z direction
 10 stamp
 10A first stamp
 10B second stamp
 12 rigid support/stamp support
 13 support
 14 mesa/pedestal
 15 support surface
 16 post
 17 post surface
 18 groove
 19 ridge
 20 chiplet/micro-device/component
 22 tether/chiplet tether
 30 delamination front
 32 sub-post
 34 blind hole/hole
 36 cutout
 40 target (destination) substrate
 42 optional adhesive layer
 50 source wafer
 52 sacrificial portion/gap
 54 anchor/anchor portion
 60 horizontal direction/horizontal stamp motion/delamination direction
 65 vertical stamp motion
 70 motion-control platform
 80 first edge/leading edge/first side
 82 second edge/trailing edge/second side
 84 delamination corner
 100 provide motion-control platform step
 110 provide source wafer step
 120 provide stamp step/provide stamp A step
 125 provide stamp B step
 130 provide target substrate step
 135 optional coat adhesive layer on destination substrate step
 140 press stamp posts against micro-devices step
 141 compress stamp posts step
 150 vertically remove stamp A from source wafer step
 151 tension stamp posts step
 152 press stamp B posts against micro-devices step
 155 move horizontally in delamination direction and vertically to remove stamp A from micro-devices step
 160 contact micro-devices to destination substrate step
 170 move horizontally in delamination direction and vertically to remove stamp from destination substrate step
 175 move horizontally in delamination direction and vertically to remove stamp B from destination substrate step
 176 move vertically to remove stamp from destination substrate step
 What is claimed:
 1. A stamp for micro-transfer printing, comprising:
 a support having a support surface; and

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a compressible post disposed on the support surface, the post comprising a distal end extending away from the support, the post having a post surface on the distal end, wherein the post has a blind hole extending into an interior of the post from the post surface and a cutout extending from the blind hole through the post to an exterior surface of the post.
 2. The stamp of claim 1, wherein the post surface has a curved edge.
 3. The stamp of claim 2, wherein the post surface also has a straight edge.
 4. The stamp of claim 2, wherein the curved edge defines at least a portion of a circle.
 5. The stamp of claim 1, wherein at least a portion of the post surface is not parallel to the support surface.
 6. The stamp of claim 1, wherein the cutout is disposed along a line intersecting a center of the blind hole.
 7. The stamp of claim 1, wherein the cutout is disposed along a line that does not intersect a center of the blind hole.
 8. The stamp of claim 1, wherein the cutout is disposed along a line tangent to the blind hole.
 9. The stamp of claim 1, wherein the cutout is disposed along a line parallel to and in contact with an edge of the blind hole.
 10. The stamp of claim 1, wherein the post has a circular outer perimeter except for the cutout.
 11. The stamp of claim 1, wherein the blind hole has a circular cross section except for the cutout.
 12. The stamp of claim 1, wherein the blind hole has a circular cross section.
 13. The stamp of claim 1, wherein the blind hole extends through the post to the support surface.
 14. The stamp of claim 1, wherein the blind hole extends through the post less than entirely to the support surface.
 15. The stamp of claim 1, wherein the blind hole has a circular cross section and the post has a polygonal cross section.
 16. The stamp of claim 1, wherein the cutout is a channel.
 17. The stamp of claim 1, wherein the cutout is a tunnel.
 18. The stamp of claim 1, wherein the cutout is a slit.
 19. The stamp of claim 18, wherein the slit is shaped and sized to be open, thereby allowing gas to exit the blind hole, when the post is compressed and to be closed, thereby preventing gas from entering the blind hole, when the post is tensioned.
 20. The stamp of claim 1, wherein the cutout is shaped and sized to be open, thereby allowing gas to exit the blind hole, when the post is compressed and to be closed, thereby preventing gas from entering the blind hole, when the post is tensioned.
 21. The stamp of claim 1, wherein the cutout has a width and a height and the width is more than the height.
 22. The stamp of claim 1, wherein a height of the cutout is no more than 20% of a height of the post.

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