



(19) **United States**

(12) **Patent Application Publication**  
**Rossi et al.**

(10) **Pub. No.: US 2025/0256130 A1**

(43) **Pub. Date: Aug. 14, 2025**

(54) **RADIATION DOSE VOLUME AND  
RADIATION DOSE RATE VOLUME  
CALCULATION APPARATUS AND METHOD**

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(21) Appl. No.: **18/440,739**

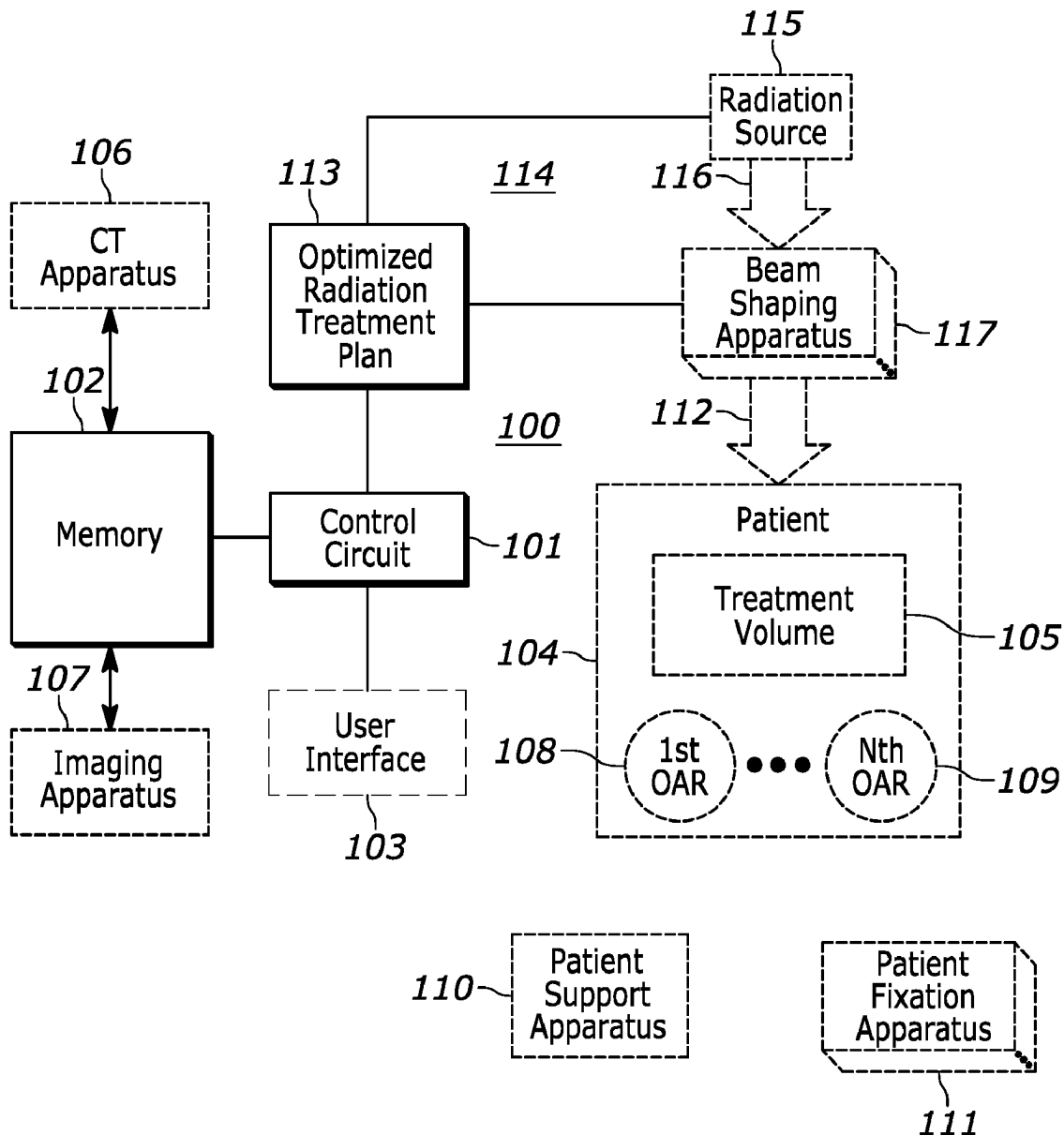
(22) Filed: **Feb. 13, 2024**

**Publication Classification**

(51) **Int. Cl.**  
*A61N 5/10* (2006.01)  
*G16H 20/40* (2018.01)  
(52) **U.S. Cl.**  
CPC ..... *A61N 5/1071* (2013.01); *G16H 20/40*  
(2018.01); *A61N 2005/1034* (2013.01); *A61N*  
*2005/1087* (2013.01)

(57) **ABSTRACT**

A control circuit accesses information regarding radiation delivery parameters and a calculation algorithm and calculates both radiation dose and radiation dose rate volumes using the calculation algorithm and the information regarding radiation delivery parameters to provide at least one calculated radiation dose volume and at least one calculated radiation dose rate volume.



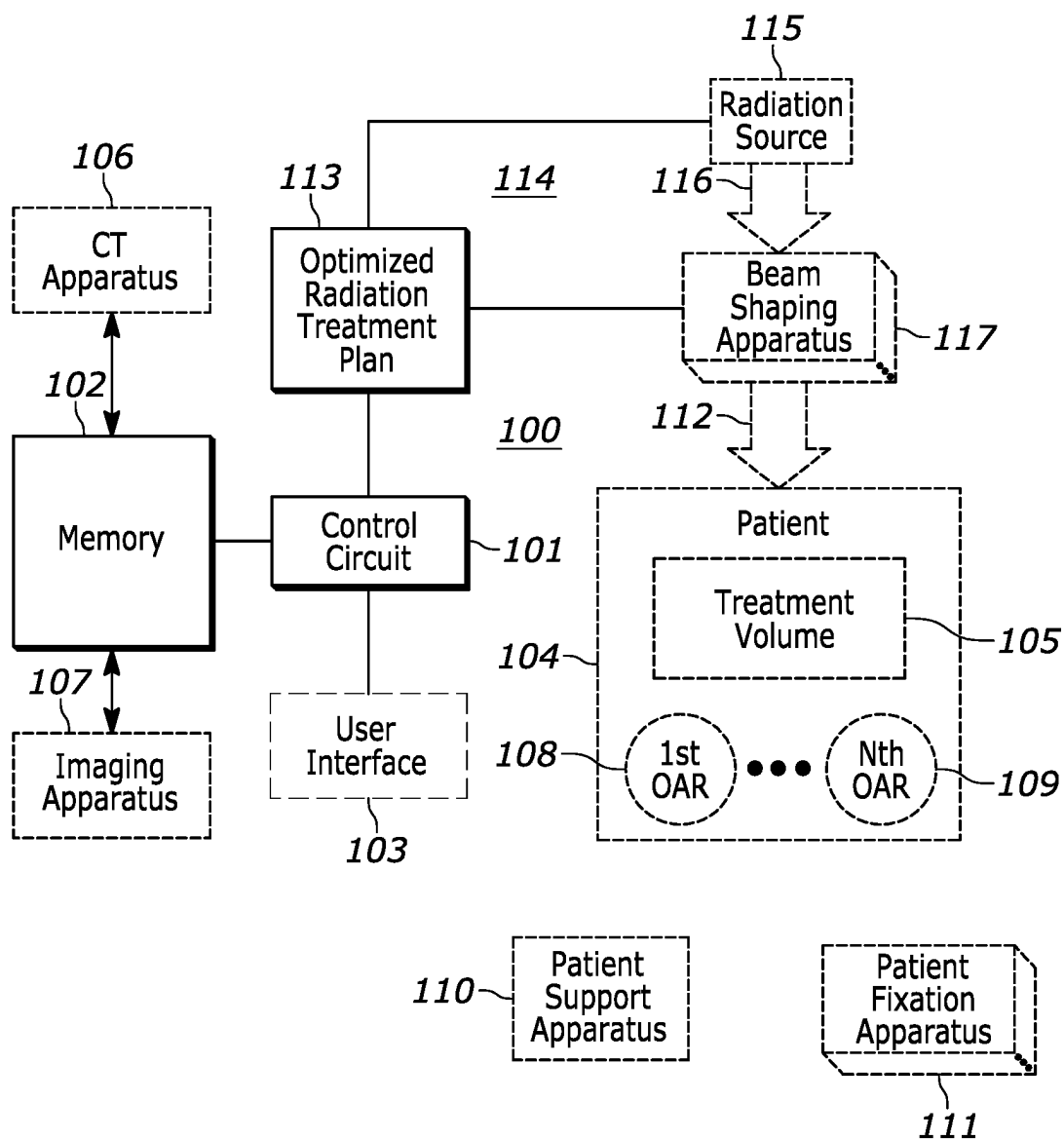
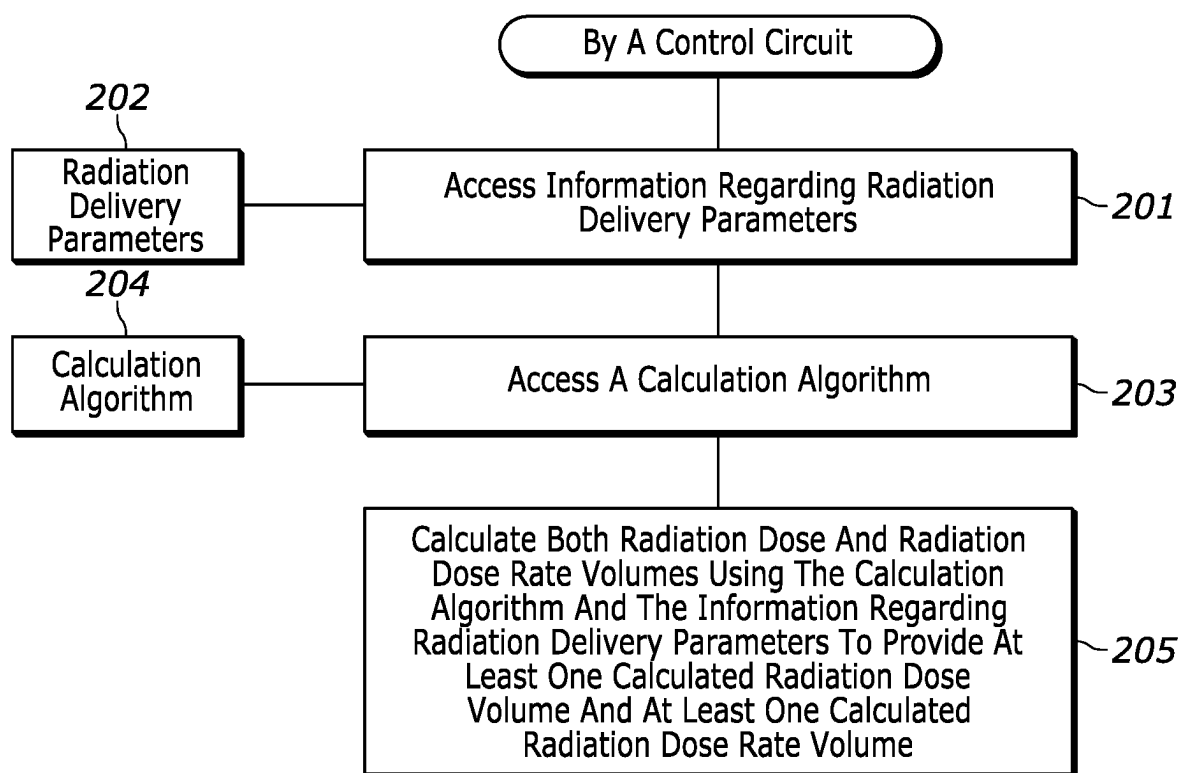


FIG. 1



200

FIG. 2

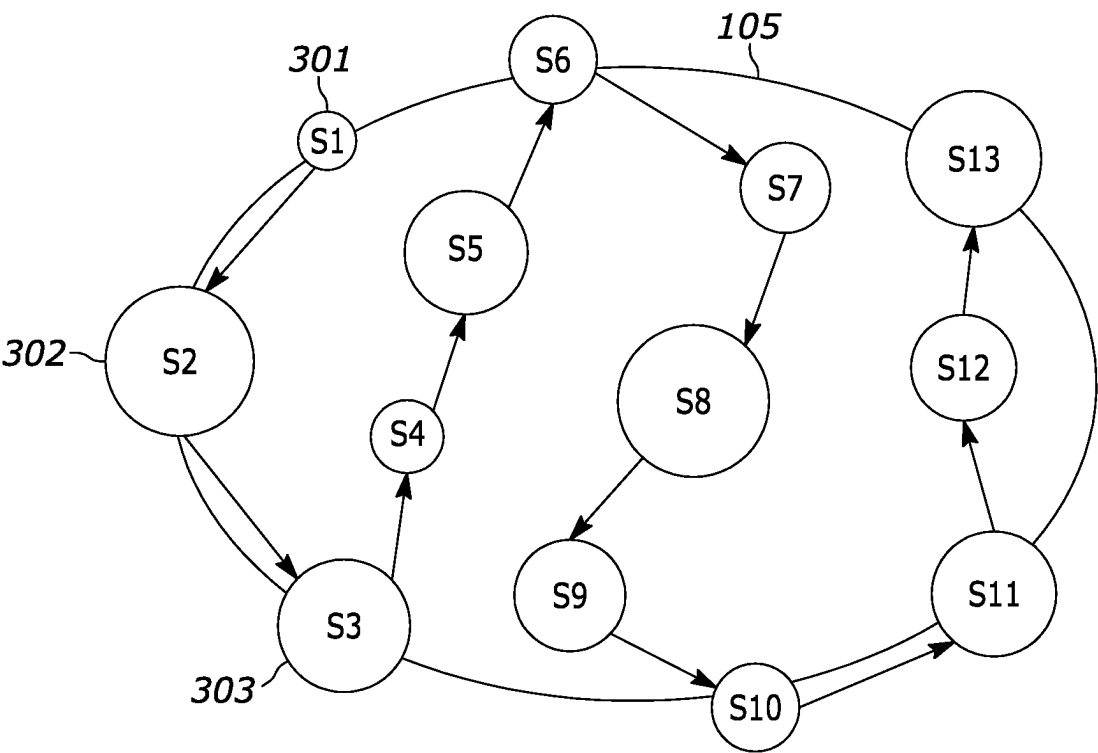
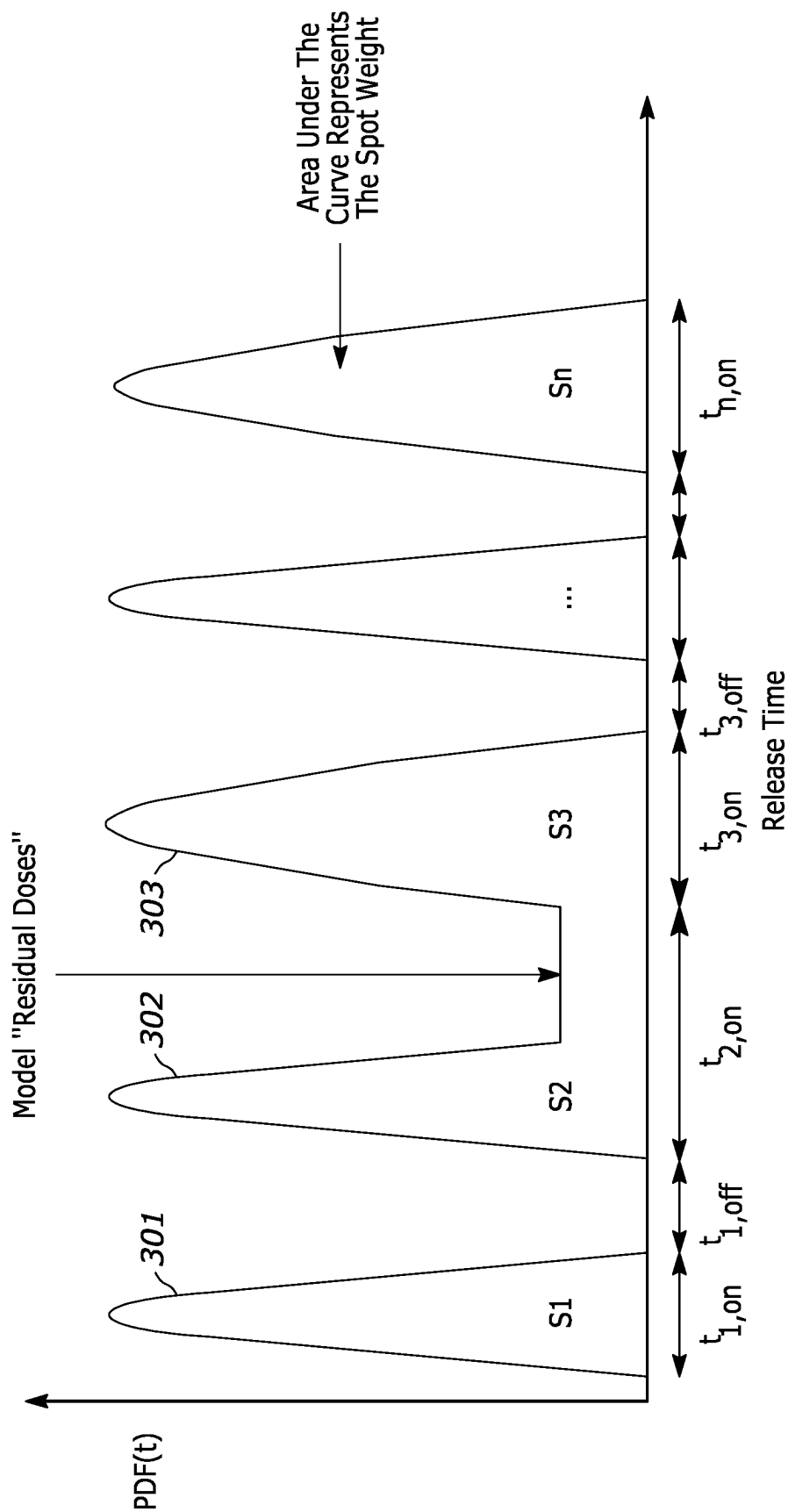


FIG. 3

400

Spot	Position	Time
S1	$\vec{r}_1$	$t_1$
S2	$\vec{r}_2$	$t_2$
S...	$\vec{r}_{...}$	$t_{...}$
Sn	$\vec{r}_n$	$t_n$

FIG. 4



501

FIG. 5

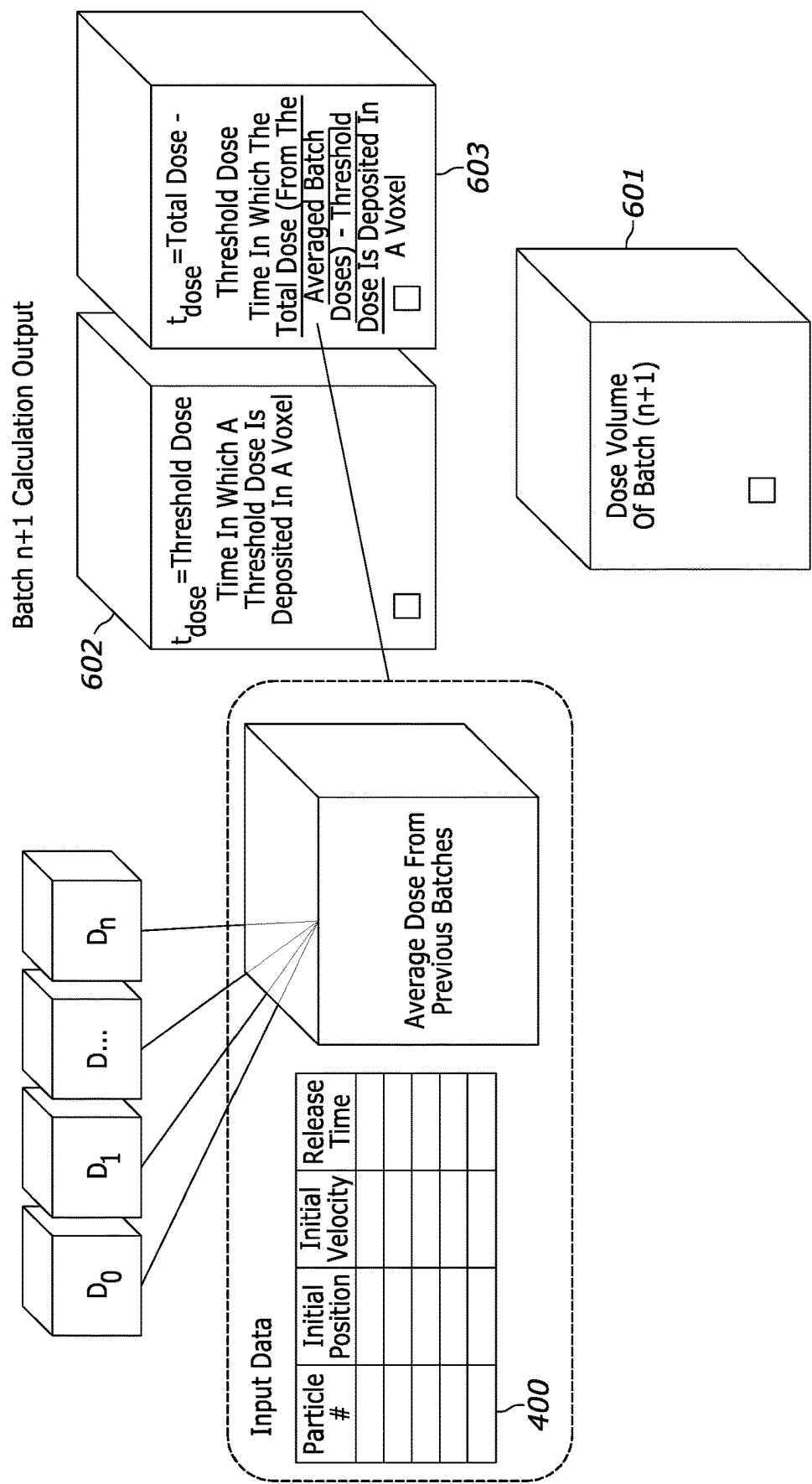


FIG. 6

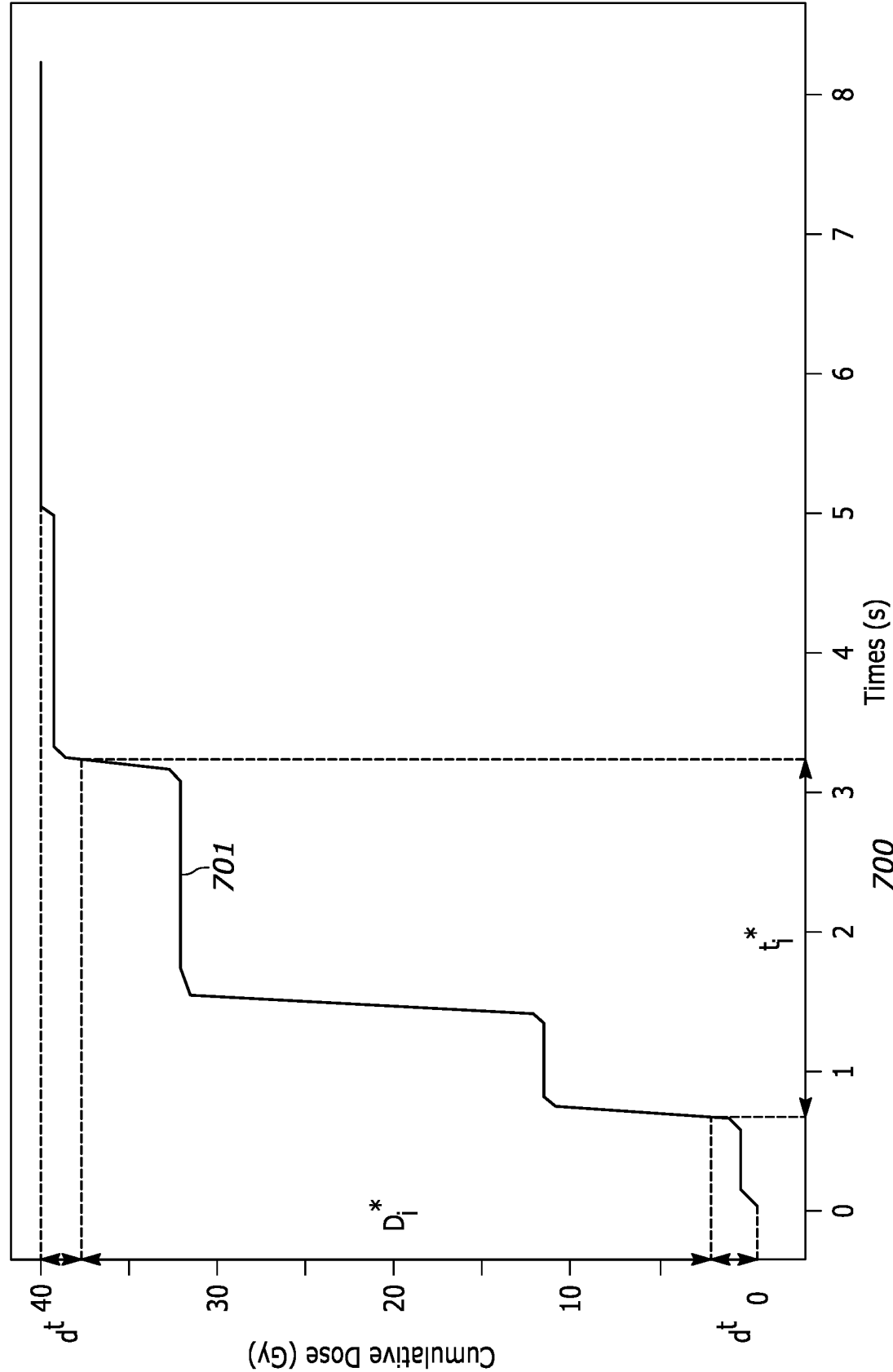


FIG. 7

## RADIATION DOSE VOLUME AND RADIATION DOSE RATE VOLUME CALCULATION APPARATUS AND METHOD

### TECHNICAL FIELD

[0001] These teachings relate generally to treating a patient's planning target volume with energy pursuant to an energy-based treatment plan and more particularly to the optimization of an energy-based treatment plan.

### BACKGROUND

[0002] The use of energy to treat medical conditions comprises a known area of prior art endeavor. For example, radiation therapy comprises an important component of many treatment plans for reducing or eliminating unwanted tumors. Unfortunately, applied energy (such as photons or protons) does not inherently discriminate between unwanted material and adjacent tissues, organs, or the like that are desired or even critical to continued survival of the patient. As a result, energy such as radiation is ordinarily applied in a carefully administered manner to at least attempt to restrict the energy to a given target volume. A so-called radiation treatment plan often serves in the foregoing regards.

[0003] A radiation treatment plan typically comprises specified values for each of a variety of treatment-platform parameters during each of a plurality of sequential fields. Treatment plans for radiation treatment sessions are often automatically generated through a so-called optimization process. As used herein, "optimization" will be understood to refer to improving a candidate treatment plan without necessarily ensuring that the optimized result is, in fact, the singular best solution. Such optimization often includes automatically adjusting one or more physical treatment parameters (often while observing one or more corresponding limits in these regards) and mathematically calculating a likely corresponding treatment result (such as a level of dosing) to identify a given set of treatment parameters that represent a good compromise between the desired therapeutic result and avoidance of undesired collateral effects.

[0004] It can be important to assess the quality of an optimized radiation treatment plan before administering radiation in accordance with that plan. Such an assessment may make use of dose volume and dose rate volume calculations. Unfortunately, calculating such values can be computationally expensive and hence either necessitate the availability of expensive computational platforms and/or require considerable time to make the calculations.

### BRIEF DESCRIPTION OF THE DRAWINGS

[0005] The above needs are at least partially met through provision of the radiation dose volume and radiation dose rate volume calculation apparatus and method described in the following detailed description, particularly when studied in conjunction with the drawings, wherein:

[0006] FIG. 1 comprises a block diagram as configured in accordance with various embodiments of these teachings;

[0007] FIG. 2 comprises a flow diagram as configured in accordance with various embodiments of these teachings;

[0008] FIG. 3 comprises a schematic representation as configured in accordance with various embodiments of these teachings;

[0009] FIG. 4 comprises a table as configured in accordance with various embodiments of these teachings;

[0010] FIG. 5 comprises a graph as configured in accordance with various embodiments of these teachings;

[0011] FIG. 6 comprises a schematic representation as configured in accordance with various embodiments of these teachings; and

[0012] FIG. 7 comprises a graph as configured in accordance with various embodiments of the invention.

[0013] Elements in the figures are illustrated for simplicity and clarity and have not necessarily been drawn to scale. For example, the dimensions and/or relative positioning of some of the elements in the figures may be exaggerated relative to other elements to help to improve understanding of various embodiments of the present teachings. Also, common but well-understood elements that are useful or necessary in a commercially feasible embodiment are often not depicted in order to facilitate a less obstructed view of these various embodiments of the present teachings. Certain actions and/or steps may be described or depicted in a particular order of occurrence while those skilled in the art will understand that such specificity with respect to sequence is not actually required. The terms and expressions used herein have the ordinary technical meaning as is accorded to such terms and expressions by persons skilled in the technical field as set forth above except where different specific meanings have otherwise been set forth herein. The word "or" when used herein shall be interpreted as having a disjunctive construction rather than a conjunctive construction unless otherwise specifically indicated.

### DETAILED DESCRIPTION

[0014] Generally speaking, pursuant to these various embodiments a control circuit accesses information regarding radiation delivery parameters and a calculation algorithm and calculates both radiation dose and radiation dose rate volumes using the calculation algorithm and the information regarding radiation delivery parameters to provide at least one calculated radiation dose volume and at least one calculated radiation dose rate volume.

[0015] The aforementioned radiation delivery parameters can include, for example, radiation beam delivery parameters such as, but not limited to, proton beam delivery parameters. (including position information for particles such as initial position information), velocity information for particles, energy, directional information for the particles, and/or temporal information corresponding to the particles.

[0016] The aforementioned calculation algorithm may comprise, by one approach, a probabilistic computation (such as, but not limited to, a Monte Carlo simulation), and/or, may include radiation beam delivery logic.

[0017] The calculated radiation dose volume and at least one calculated radiation dose rate volume can be employed, for example, when optimizing a radiation treatment plan for a particular patient (in particular, by providing a useful basis for evaluating the quality of an optimized plan), which optimized plan can then be utilized to administer therapeutic radiation to that patient.

[0018] So configured, and by one approach, these teachings will accommodate fast dose volume dose rate volume calculations by integrating beam delivery dynamics into Monte Carlo particle transport in radiation therapy treatment planning. The present teachings can be especially useful when both the dose volume and the dose rate volume are needed to evaluate the quality of an optimized radiation



treatment plan because these teachings provide for reducing the computational cost of state-of-the-art calculations by performing both the dose volume and dose rate volume calculations simultaneously. By allowing a central processing unit or graphics processing unit to do similar operations in a row and by better cache usage, the dose and dose rate calculation can be significantly sped up.

**[0019]** These and other benefits may become clearer upon making a thorough review and study of the following detailed description. Referring now to the drawings, and in particular to FIG. 1, an illustrative apparatus **100** that is compatible with many of these teachings will first be presented.

**[0020]** In this particular example, the enabling apparatus **100** includes a control circuit **101**. Being a “circuit,” the control circuit **101** therefore comprises structure that includes at least one (and typically many) electrically-conductive paths (such as paths comprised of a conductive metal such as copper or silver) that convey electricity in an ordered manner, which path(s) will also typically include corresponding electrical components (both passive (such as resistors and capacitors) and active (such as any of a variety of semiconductor-based devices) as appropriate) to permit the circuit to effect the control aspect of these teachings.

**[0021]** Such a control circuit **101** can comprise a fixed-purpose hard-wired hardware platform (including but not limited to an application-specific integrated circuit (ASIC) (which is an integrated circuit that is customized by design for a particular use, rather than intended for general-purpose use), a field-programmable gate array (FPGA), and the like) or can comprise a partially or wholly-programmable hardware platform (including but not limited to microcontrollers, microprocessors, and the like). These architectural options for such structures are well known and understood in the art and require no further description here. This control circuit **101** is configured (for example, by using corresponding programming as will be well understood by those skilled in the art) to carry out one or more of the steps, actions, and/or functions described herein.

**[0022]** The control circuit **101** operably couples to a memory **102**. This memory **102** may be integral to the control circuit **101** or can be physically discrete (in whole or in part) from the control circuit **101** as desired. This memory **102** can also be local with respect to the control circuit **101** (where, for example, both share a common circuit board, chassis, power supply, and/or housing) or can be partially or wholly remote with respect to the control circuit **101** (where, for example, the memory **102** is physically located in another facility, metropolitan area, or even country as compared to the control circuit **101**).

**[0023]** In addition to information such as optimization information for a particular patient and information regarding a particular radiation treatment platform as described herein, this memory **102** can serve, for example, to non-transitorily store the computer instructions that, when executed by the control circuit **101**, cause the control circuit **101** to behave as described herein. (As used herein, this reference to “non-transitorily” will be understood to refer to a non-ephemeral state for the stored contents (and hence excludes when the stored contents merely constitute signals or waves) rather than volatility of the storage media itself and hence includes both non-volatile memory (such as read-only memory (ROM) as well as volatile memory (such as a dynamic random access memory (DRAM)).)

**[0024]** By one optional approach the control circuit **101** also operably couples to a user interface **103**. This user interface **103** can comprise any of a variety of user-input mechanisms (such as, but not limited to, keyboards and keypads, cursor-control devices, touch-sensitive displays, speech-recognition interfaces, gesture-recognition interfaces, and so forth) and/or user-output mechanisms (such as, but not limited to, visual displays, audio transducers, printers, and so forth) to facilitate receiving information and/or instructions from a user and/or providing information to a user.

**[0025]** If desired the control circuit **101** can also operably couple to a network interface (not shown). So configured the control circuit **101** can communicate with other elements (both within the apparatus **100** and external thereto) via the network interface. Network interfaces, including both wireless and non-wireless platforms, are well understood in the art and require no particular elaboration here.

**[0026]** By one approach, a computed tomography apparatus **106** and/or other imaging apparatus **107** as are known in the art can source some or all of any desired patient-related imaging information.

**[0027]** In this illustrative example the control circuit **101** is configured to ultimately output an optimized energy-based treatment plan (such as, for example, an optimized radiation treatment plan **113**). This energy-based treatment plan typically comprises specified values for each of a variety of treatment-platform parameters during each of a plurality of sequential exposure fields. In this case the energy-based treatment plan is generated through an optimization process, examples of which are provided further herein.

**[0028]** By one approach the control circuit **101** can operably couple to an energy-based treatment platform **114** that is configured to deliver therapeutic energy **112** to a corresponding patient **104** having at least one treatment volume **105** and also one or more organs-at-risk (represented in FIG. 1 by a first through an Nth organ-at-risk **108** and **109**) in accordance with the optimized energy-based treatment plan **113**. These teachings are generally applicable for use with any of a wide variety of energy-based treatment platforms/apparatuses. In a typical application setting the energy-based treatment platform **114** will include an energy source such as a radiation source **115** of ionizing radiation **116**.

**[0029]** By one approach this radiation source **115** can be selectively moved via a gantry along an arcuate pathway (where the pathway encompasses, at least to some extent, the patient themselves during administration of the treatment). The arcuate pathway may comprise a complete or nearly complete circle as desired. By one approach the control circuit **101** controls the movement of the radiation source **115** along that arcuate pathway, and may accordingly control when the radiation source **115** starts moving, stops moving, accelerates, de-accelerates, and/or a velocity at which the radiation source **115** travels along the arcuate pathway.

**[0030]** As one illustrative example, the radiation source **115** can comprise, for example, a radio-frequency (RF) linear particle accelerator-based (linac-based) x-ray source. A linac is a type of particle accelerator that greatly increases the kinetic energy of charged subatomic particles or ions by subjecting the charged particles to a series of oscillating electric potentials along a linear beamline, which can be used to generate ionizing radiation (e.g., X-rays) **116** and high energy electrons. These teachings will also support

proton beam radiotherapy, in which case, the radiation source **115** may comprise a cyclotron or synchrotron that accelerates protons to high speeds. Those protons can then be directed through a series of magnets that shape and focus the proton beam.

**[0031]** A typical energy-based treatment platform **114** may also include one or more support apparatuses **110** (such as a couch) to support the patient **104** during the treatment session, one or more patient fixation apparatuses **111**, a gantry or other movable mechanism to permit selective movement of the radiation source **115**, and one or more energy-shaping apparatuses (for example, beam-shaping apparatuses **117** such as jaws, multi-leaf collimators, and so forth) to provide selective energy shaping and/or energy modulation as desired.

**[0032]** In a typical application setting, it is presumed herein that the patient support apparatus **110** is selectively controllable to move in any direction (i.e., any X, Y, or Z direction) during an energy-based treatment session by the control circuit **101**. As the foregoing elements and systems are well understood in the art, further elaboration in these regards is not provided here except where otherwise relevant to the description.

**[0033]** Referring now to FIG. 2, a process **200** that can be carried out, for example, in conjunction with the above-described application setting (and more particularly via the aforementioned control circuit **101**) will be described. Generally speaking, this process **200** serves to facilitate providing an optimized radiation treatment plan **113** (such as a proton beam radiation treatment plan) to thereby facilitate treating a particular patient with therapeutic radiation using a particular radiation treatment platform per that optimized radiation treatment plan **113**.

**[0034]** For the sake of an illustrative example, it is presumed in the description below that the radiation treatment at issue comprises a proton-based radiation treatment. Proton beam radiotherapy is a form of radiation therapy that utilizes protons, which are positively charged particles, to deliver high-energy radiation to cancer cells. Unlike traditional radiation therapy that uses X-rays or photons, proton beam therapy allows for more precise targeting of tumors while minimizing damage to surrounding healthy tissues. This is at least partly because protons have a unique property called the Bragg peak, which allows the protons to deposit most of their energy at a specific depth within the body.

**[0035]** It should also be noted that the foregoing proton beam radiotherapy may comprise so-called FLASH radiotherapy. FLASH energy treatment is a known area of prior art endeavor, albeit a relatively new area of consideration. FLASH radiotherapy is a technique (at least for photon and proton treatments) that employs very brief, very high dose rates (utilizing large beam currents). FLASH treatments hold the promise of shortening treatment time to just one to three 1-second sessions while also potentially reducing side effects, perhaps considerably. For example, a significant sparing of normal tissue notwithstanding iso-effective tumor growth delay has been demonstrated through very brief irradiation at dose rates on the order of 40 Gy's. This sparing of normal tissue has been dubbed the FLASH effect.

**[0036]** At block **201**, this process **200** accesses information regarding radiation delivery parameters **202** (by accessing, for example, the aforementioned memory **102**). These teachings will accommodate a variety of different radiation delivery parameters, including, but not limited to, proton

beam delivery parameters (including position information for particles such as initial position information), velocity information for particles, energy and directional information for the particles, and/or temporal information corresponding to the particles (where the temporal information may comprise, for example, temporal information corresponding to dose accumulation in each voxel such as, by way of non-limiting examples, volume(s) related to a first instance of time when dose is received in each voxel and/or volume(s) information related to a final instance of time when a total dose is received in each voxel). Any one or more of the foregoing, for example, can comprise the accessed information.

**[0037]** At block **203**, the control circuit **101** accesses a calculation algorithm **204** (again, by one approach, by accessing the aforementioned memory **102**). This accessed calculation algorithm may comprise, by one approach, a probabilistic computation (such as, but not limited to, a Monte Carlo simulation), or, by another approach, may include radiation beam delivery logic. (Further description in these regards appears below.)

**[0038]** At block **205**, the control circuit **101** calculates both radiation dose and radiation dose rate volumes using the accessed calculation algorithm **204** and the information regarding radiation delivery parameters **202** to provide at least one calculated radiation dose volume and at least one calculated radiation dose rate volume.

**[0039]** Further details that comport with these teachings will now be presented. It will be understood that the specific details of these examples are intended to serve an illustrative purpose and are not intended to suggest any particular limitations with respect to these teachings.

**[0040]** In modulated scanning proton FLASH radiotherapy, the dose rate used is often calculated, in part, by employing an influence matrix. The latter is typically generated by calculating the dose contribution of each spot and storing the results as an array of dose volumes. Deterministic or stochastic calculation models can be used for this. The dose rate for each voxel can then be calculated using that influence matrix. Calculating an influence matrix, however, can be computationally expensive in terms of both memory and time usage because the dose distribution is isolated for each spot. (As used herein, a "spot" refers to a location along the path of a proton beam where energy is deposited.) The present teachings can obviate calculating an influence matrix. These teachings can also combine the dose and dose rate calculation steps into a single step.

**[0041]** As one illustrative example, the dose and dose rate calculation task sequence can be as follows.

- [0042]** 1. The beam line is calculated and/or optimized. The spots that cover the target are populated and/or optimized for plan dose quality.
- [0043]** 2. A treatment plan is optimized, with the spots being modulated to optimize the dose.
- [0044]** 3. (Optional) The dose rate is optimized. This step can be integrated in step 2 when the plan is optimized. The dose rate can be optimized, for example, by reorganizing the spots or adjusting the monitor unit rates and/or spot positions.
- [0045]** 4. Postprocessing. The raw spot list can be analyzed and filtered to ensure that the treatment delivery is able to deliver the spots. A final spot list is created.

[0046] 5. The dose and dose rate are calculated with a Monte Carlo particle transport calculation that includes:

[0047] a. A beam delivery dynamics calculation;

[0048] b. Particle generation; and

[0049] c. The dose and dose rate calculation.

[0050] In the following example, a first step in a Monte Carlo-based dose calculation is particle generation where a very large number of random particles are sampled whose initial positions and initial velocity distributions match the radiation source being modeled. The batch of primary particles is then propagated in the medium in a stepwise fashion where the particles experience interactions with the medium deflecting them and slowing them down. As the particles slow down, they deposit energy (i.e., dose) to the medium. Primary particles can also kick off further secondary particles to be tracked.

[0051] In this example, the particle generation step employs the aforementioned radiation delivery parameters 202 regarding the machine delivery dynamics. This can mean that in addition to initial particle position and velocity information, a particle can have an associated time at which that particle is released from the source. In these regards, by integrating the treatment delivery system's beam delivery dynamics, the time at which a given particle is released from the source can be obtained and associated with that particle.

[0052] FIG. 3 presents a schematic depiction of a distribution of a plurality of spots (denoted S1 through S13 in this illustrative example) and their order of delivery within a patient's treatment volume 105. By calculating the aforementioned beam delivery dynamics, the instances of time when the beam is positioned at a certain location can be determined (as presented in this illustrative example of a corresponding table 400 presented in FIG. 4). The latter, in turn, supports generating a positional and temporal probability distribution function (PDF) for the particle generation (with FIG. 5 presenting an illustrative example in those regards).

[0053] A positional and temporal PDF 501 can model the different ways that spots are delivered. For example, the beam can be kept on only at a certain spot (say spot S1 301 in FIGS. 3 and 5) and the beam can also be kept on in between two spots (such as spots S2 302 and S3 303 in FIGS. 3 and 5).

[0054] By one approach as regards a Monte Carlo dose calculation, only the initial particle positions and velocities or initial positions, energy, and directions are the core information needed. For the Monte Carlo dose rate calculation, the additional information needed for the particle is the associated time at which the particle was released.

[0055] Large number of particles can be generated for each batch calculation. By one approach, the generated particles are sorted by their corresponding times of release. Each particle is then propagated in the medium. The first instant of time and the last instant of time are stored at which energy is deposited in a given position in the medium (or, by one approach, in a voxel) that represents the position in the medium. Those instances of time can then be associated to each particle's time of release. It may be noted that, in a typical application setting, the timescales of the particle transport in the medium will be significantly smaller and incomparable to the timescales in the beam delivery dynamics.

[0056] By one approach, a source particles array contains information about the initial position, direction, energy, and weight of each particle and the time in which each particle is released, thus allowing the dose rate to be simultaneously calculated with the dose.

[0057] By one approach, three volume information components to be used for the Monte Carlo dose rate calculation are the dose volume, a first time volume that records the instance of time in which the voxel receives the threshold dose, and a second time volume that records the instance of time in which the voxel receives the total dose (from a previous calculation batch) minus the threshold dose. These three volumes are denoted in FIG. 6 by reference numerals 601-603, respectively.

[0058] In this example, the dose  $D_i$  in every voxel is first calculated by summing the influence matrix over the spot indices:

$$D_i = \sum_{j=1}^n (d_{ij} MU_j),$$

[0059] where  $i$  refer to the voxel indices,  $j$  refer to the spot indices,  $d_{ij}$  is the influence matrix [Gy/MU] (i.e., the dose from spot  $j$  in voxel  $i$ ), and  $MU_j$  is the monitor units of spot  $j$  [MU].

[0060] A pencil beam scanning dose rate can then be calculated for each voxel as:

$$\dot{D}_i = \begin{cases} 0, & \text{if } D_i \leq 3 \cdot d^* \\ \frac{D_i^*}{t_i^*}, & \text{if } D_i > 3 \cdot d^* \end{cases}$$

where  $D_i^* = D_i - 2 \cdot d^*$  [Gy],  $d^*$  is an arbitrary dose threshold [Gy] defined in the calculation options (a default value could be, for example, 0.01 Gy), and  $t_i^*$  is the time needed for the accumulated dose to rise from  $d^*$  to  $D_i - d^*$  [s], interpolated linearly as depicted in FIG. 7 (which presents a graph 700 that comprises an illustrative example of dose 701 accumulated in a single voxel as a function of time, where the dose rate is calculated as  $D_i^*/t_i^*$ ). This information comprises the time difference of the last and first instance of time recorded in the time volume information component.

[0061] Those skilled in the art will recognize that a wide variety of modifications, alterations, and combinations can be made with respect to the above described embodiments without departing from the scope of the invention, and that such modifications, alterations, and combinations are to be viewed as being within the ambit of the inventive concept.

What is claimed is:

1. A method comprising:

by a control circuit:

accessing information regarding radiation delivery parameters;

accessing a calculation algorithm; and

calculating both radiation dose and radiation dose rate volumes using the calculation algorithm and the information regarding radiation delivery parameters to provide at least one calculated radiation dose volume and at least one calculated radiation dose rate volume.

2. The method of claim 1 wherein the radiation delivery parameters include radiation beam delivery parameters.

3. The method of claim 2 wherein the radiation beam delivery parameters comprise proton beam delivery parameters.

4. The method of claim 3 wherein the proton beam delivery parameters include position information for particles.

5. The method of claim 4 wherein the position information for the particles includes initial position information.

6. The method of claim 4 wherein the proton beam delivery parameters include:

velocity information for the particles; and/or

energy and directional information for the particles.

7. The method of claim 4 wherein the proton beam delivery parameters include temporal information corresponding to the particles.

8. The method of claim 1 wherein the calculation algorithm comprises a probabilistic computation.

9. The method of claim 8 wherein the calculation algorithm comprises a Monte Carlo simulation.

10. The method of claim 1 wherein the calculation algorithm includes radiation beam delivery logic.

11. An apparatus comprising:

a memory having information regarding radiation delivery parameters and a calculation algorithm stored therein;

a control circuit operably coupled to the memory and configured to:

access the memory to access the information regarding the radiation delivery parameters;

access the calculation algorithm; and

calculate both radiation dose and radiation dose rate volumes using the calculation algorithm and the

information regarding radiation delivery parameters to provide at least one calculated radiation dose volume and at least one calculated radiation dose rate volume.

12. The apparatus of claim 11 wherein the radiation delivery parameters include radiation beam delivery parameters.

13. The apparatus of claim 12 wherein the radiation beam delivery parameters comprise proton beam delivery parameters.

14. The apparatus of claim 13 wherein the proton beam delivery parameters include position information for particles.

15. The apparatus of claim 14 wherein the position information for the particles includes initial position information.

16. The apparatus of claim 14 wherein the proton beam delivery parameters include:

velocity information for the particles; and/or

energy and directional information for the particles.

17. The apparatus of claim 14 wherein the proton beam delivery parameters include temporal information corresponding to the particles.

18. The apparatus of claim 11 wherein the calculation algorithm comprises a probabilistic computation.

19. The apparatus of claim 18 wherein the probabilistic computation comprises a probabilistic computation of temporal information of beam particles as a function, at least in part of beam delivery dynamics and parameters.

20. The apparatus of claim 18 wherein the calculation algorithm comprises a Monte Carlo simulation.

\* \* \* \* \*