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### INPUT/OUTPUT CALIBRATION OF PUMP

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#### Abstract

A method of calibrating a pump system can include providing a pump, calibrating a pump input with an input device connected to the pump, and calibrating a pump output with an output device connected to the pump. Calibrating the pump input can include selecting a first input signal value, generating a transmitted input signal corresponding to the first input signal value, and setting a nominative pump input value to the first input signal value. Calibrating the pump output can include receiving a received output signal outputted from the pump, and setting a nominative pump output value to the first input signal value.

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## Background/Summary

INCORPORATION BY REFERENCE TO ANY PRIORITY APPLICATIONS [0001] This application is a continuation of U.S. patent application Ser. No. 17/654,206, filed Mar. 9, 2022, and entitled “INPUT/OUTPUT CALIBRATION OF PUMP.” The disclosure of each application cited in this paragraph is hereby incorporated by reference in its entirety.

### BACKGROUND

#### Field

[0002] The present disclosure relates generally to calibration of pumps. More particularly, the present disclosure relates to pump systems with improved calibration and methods of calibrating a pump system.

#### Description of the Related Art

[0003] Pumps can be used to deliver fluids (e.g., liquid chemicals) for a variety of applications, including industrial, aquatic, and municipal applications. Pumps can be connected to other equipment. There is a need to calibrate the pumps with the connected devices.

### SUMMARY

[0004] Pumps can create pressure to move fluids. A pump can include a motor that runs based on input signals. As an example, a relatively low input signal, such as a low current, can cause a motor to run at a relatively low speed, and a relatively high input signal, such as a high current, can cause a motor to run at a relatively high speed. By changing the signal sent to the pump, users can desirably control the speed of the pump.

[0005] Users can connect a pump in their system including one or more devices to remotely control the speed of the pump, e.g., by changing the signal sent to the pump. Users may measure the signal at different locations in their system (e.g., at the location remotely controlling the pump and/or at the location of the pump). The signal may change by the time it reaches the pump and/or reaches other equipment connected to the pump. If users do not measure an expected value for the signal they send or receive, they may adjust their systems. However, some such adjustments may be unnecessary if the pump is calibrated with the other equipment.

[0006] Various implementations provide a method of calibrating a pump system. The method can include providing a pump, calibrating a pump input with a signal source connected to the pump, and calibrating a pump output with an output meter connected to the pump. Calibrating the pump input can include selecting a first input signal value, generating a transmitted input signal corresponding to the first input signal value, measuring a received input signal value, and setting a nominative pump input value corresponding to the received input signal value, such that the nominative pump input value is the first input signal value. Calibrating the pump output can include receiving a received output signal outputted from the pump, measuring a received output signal value, and setting a nominative pump output value corresponding to the received output signal value, such that the nominative pump output value is the first input signal value.

[0007] In various implementations, the method can further include calibrating the pump input for a second input signal value. In various implementations, the method can further include calibrating the pump output for the second input signal value.

[0008] In some instances, the first input signal value and the second input signal value can correspond to minimum and maximum input signal values which can control the pump.

[0009] In some methods, the first input signal value can correspond to a value in the range of 2-6 mA and the second input signal value can correspond to a value in the range of 18-22 mA. For

example, the first input signal value can correspond to 4 mA and the second input signal value can correspond to 20 mA.

[0010] In some instances, calibrating the pump input can further comprise setting the pump to run at a speed in the range of 0-20% speed when the pump is set at the first input signal value and setting the pump to run at a speed in the range of 80-100% speed when the pump is set at the second input signal value.

[0011] For example, calibrating the pump input can further comprise setting the pump to run at 0% speed when the pump is set at the first input signal value and setting the pump to run at 100% speed when the pump is set at the second input signal value.

[0012] In some methods, measuring the received input signal value can comprise measuring the received input signal value at the pump.

[0013] In some instances, the method can further include displaying the nominative pump output value.

[0014] Various implementations provide a pump system. The pump system can include a pump and a processor in communication with the pump. The pump can be connected to a signal source configured to generate a transmitted input signal corresponding to a first input signal value. The transmitted input signal can have a received input signal value. The pump can be further connected to an output meter configured to measure a received output signal value. The processor can be configured to calibrate a pump input by setting a nominative pump input value corresponding to the received input signal value, such that the nominative pump input value is the first input signal value. The processor can also be configured to calibrate a pump output with the output meter by setting a nominative pump output value corresponding to the received output signal value, such that the nominative pump output value is the first input signal value.

[0015] In various implementations, the processor can be configured to calibrate the pump input for a second input signal value. In various implementations, the processor can be configured to calibrate the pump output for the second input signal value.

[0016] In some instances, the first input signal value and the second input signal value can correspond to minimum and maximum input signal values which can control the pump.

[0017] In some systems, the first input signal value can correspond to a value in the range of 2-6 mA and the second input signal value can correspond to a value in the range of 18-22 mA. For example, the first input signal value can correspond to 4 mA and the second input signal value can correspond to 20 mA.

[0018] In some instances, the processor can be further configured to set the pump to run at a speed in the range of 0-20% speed when the pump is set at the first input signal value and to set the pump to run at a speed in the range of 80-100% speed when the pump is set at the second input signal value.

[0019] For example, the processor can be further configured to set the pump to run at 0% speed when the pump is set at the first input signal value and to set the pump to run at 100% speed when the pump is set at the second input signal value.

[0020] In some instances, the system can further include a display configured to present the nominative pump output value.

[0021] In some systems, the pump can be a peristaltic pump.

[0022] In some instances, the system can further comprise an input meter configured to measure the received input signal value. In some instances, the input meter can be configured to measure the received input signal value at the pump.

[0023] In some instances, the system can further comprise the output meter configured to measure the received output signal value.

[0024] Various implementations provide a method of calibrating a pump system. The method can include providing a pump, calibrating a pump input with an input device connected to the pump, and calibrating a pump output with an output meter connected to the pump. Calibrating the pump

input can include selecting a first input signal value; generating a transmitted input signal corresponding to the first input signal value, and setting a nominative pump input value to the first input signal value. Calibrating the pump output can include receiving a received output signal outputted from the pump, and setting a nominative pump output value to the first input signal value.

[0025] In various implementations, the method can further include calibrating the pump input for a second input signal value. In various implementations, the method can further include calibrating the pump output for the second input signal value.

[0026] In some instances, the first input signal value and the second input signal value can correspond to minimum and maximum input signal values which can control the pump.

[0027] In some methods, the first input signal value can correspond to a value in the range of 2-6 mA and the second input signal value can correspond to a value in the range of 18-22 mA. For example, the first input signal value can correspond to 4 mA and the second input signal value can correspond to 20 mA.

[0028] In some instances, calibrating the pump input can further comprise setting the pump to run at a speed in the range of 0-20% speed when the pump is set at the first input signal value and setting the pump to run at a speed in the range of 80-100% speed when the pump is set at the second input signal value.

[0029] For example, calibrating the pump input can further comprise setting the pump to run at 0% speed when the pump is set at the first input signal value and setting the pump to run at 100% speed when the pump is set at the second input signal value.

[0030] In some instances, the method can further include displaying the nominative pump output value.

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## Description

### BRIEF DESCRIPTION OF THE DRAWINGS

[0031] The features disclosed herein are described below with reference to the drawings of some implementations. The illustrated implementations are intended to illustrate, but not to limit the inventions. The drawings contain the following figures:

[0032] FIG. 1 is a perspective view of an example pump that can be calibrated according to various implementations described herein.

[0033] FIG. 2 is a block diagram illustrating an example connection between a user interface in communication with a pump via a processor.

[0034] FIG. 3 shows an example user interface used to calibrate a pump according to various implementations described herein.

[0035] FIGS. 4A and 4B schematically illustrate example pump systems including a pump that can be connected to input and output devices.

[0036] FIG. 5 is a flowchart of an example method of calibrating a pump system.

[0037] FIG. 6 is a flowchart of an example method of calibrating a pump input with an input device connected to the pump.

[0038] FIGS. 7, 8, 9, 10, and 11 show examples of various steps of an example method of calibrating a pump input.

[0039] FIG. 12 is a flowchart of an example method of calibrating a pump output with an output device connected to the pump.

[0040] FIGS. 13, 14, 15 and 16 show examples of various steps of an example method of calibrating a pump output.

### DETAILED DESCRIPTION

[0041] While the present description sets forth specific details of various implementations, it will

be appreciated that the description is illustrative only and should not be construed in any way as limiting. Furthermore, various applications of such implementations and modifications thereto, which may occur to those who are skilled in the art, are also encompassed by the general concepts described herein.

[0042] As described herein, a pump can be calibrated with other devices connected to the pump, e.g., devices connected to the input and/or output of the pump. FIG. 1 is a perspective view of an example pump **10** that can be calibrated according to various implementations described herein. The illustrated pump **10** is a peristaltic pump. However, other types of pumps can be calibrated as described herein. In various implementations, the pump **10** can have a pump head **12** that includes a rotor **14** surrounded by a housing **16**. The rotor **14** can compress a pump tubing **18** against the housing **16** in a peristaltic squeezing action as the rotor **14** rotates, thereby driving fluid through the pump tubing **18**. The dimensions of the pump tubing **18** and the rotational speed of the rotor **14** can determine the volumetric output of the pump **10**.

[0043] The pump **10** can include a user interface **20** to allow a user to control and/or configure the pump **10** (e.g., via a processor, such as processing electronics, in communication with the pump **10**). In this example, the user interface **20** (and connected processor) is integrated with the pump **10**. In other examples, the user interface **20** (and/or connected processor) may be separate from the pump **10**. For simplicity, FIG. 2 is a block diagram illustrating an example connection between the user interface **20** in communication with the pump **10** via a processor **21**.

[0044] FIG. 3 shows an example user interface **20**. In some implementations, the user interface **20** can include a display **22** (e.g., LCD display, LED display, an OLED display, etc.). The display **22** can present various information and/or operational parameters, for example, pump name, time, tube information, pump status, fluid being pumped, rotation direction, run time, etc.

[0045] The user interface **20** can allow the user to control operational parameters of the pump, such as the rotational speed of the rotor **14** via an electronic speed-control system. For example, the user interface **20** can include one or more input stations **24** (e.g., buttons, switches, dials, etc.). In some aspects, the one or more input stations **24** can be arranged as one or more buttons on the display **22** (e.g., one or more buttons on a touch screen display). In some aspects, the one or more input stations **24** can be arranged as a membrane keypad. Other examples are possible. The speed-control system can include a processor, e.g., a microprocessor, configured to receive a command signal from the one or more input stations **24** and transmit a control signal to an electric motor of the pump **10** (which controls the rotor **14**) based on the command signal received from the one or more input stations **24**. In this way, the speed-control system can allow a user to adjust an operational parameter of the pump **10** through the user interface **20**. The processor **21** can include processing electronics. An example processor that can be used include ST's STM32F401 microcontroller. In some instances, it can use an ARM Cortex M4 CPU. The processor can convert an analog signal (e.g., mA) into a digital signal that is processed into a motor revolutions per minute (rpm) at which to run the pump. The processor can perform other functions as well. The main circuit board of the pump **10** can receive the signal inputs from the processor **21** and drive the motor at a determined speed accordingly.

[0046] In various implementations, the user interface **20** can access the processor **21** to control the pump **10** local to the pump **10**. In various implementations, the pump **10** can additionally or alternatively be controlled at a location remote from the pump **10**. For example, the user interface **20** can configure the pump **10** to allow the user to remotely control the pump **10** with incoming signals. As will be described herein, the user interface **20** can set one or more input signals for one or more given operational parameters (e.g., motor speed, flow rate, revolutions per minute, etc.).

[0047] FIG. 4A schematically illustrates an example pump system **100** including a pump **10** that can be connected to an input device **110** used to remotely control the pump **10**. The input device **110**, such as a remote control, can include a signal source and can be configured to generate a transmitted input signal **101**. An example input device **110** can include a multimeter, such as a

Fluke 789 ProcessMeter, which can provide the input signal to control the pump. In various instances, the input device **110** can receive a first input signal value selected by the user, and can generate a transmitted input signal **101** corresponding to the first input signal value. The pump **10** can receive a received input signal **101** which can be used to control the pump **10**.

[0048] With continued reference to FIG. **4A**, the pump **10** can also be connected to an output device **112**. In some examples, the output device **112** can be an output meter, e.g., a multimeter in some instances, located at the remote location near the input device **110**. The output device **112** can be separate or integrated with the input device **110**. The output device **112** can be configured to measure a received output signal **102** from the pump **10** so as to determine a received output signal value. If the received output signal value is not equal to the first input signal value, the user may adjust equipment in the system. However, in various implementations, the pump **10** can be calibrated to account for the difference between the first input signal value and the received output signal value, reducing the need for adjustments.

[0049] FIG. **4B** schematically illustrates another example pump system **100**, which is similar to that in FIG. **4A**, but including an additional device such as an input meter **111** at or near the location of the pump **10** to measure a received input signal value corresponding to the transmitted input signal **101**. The input meter **111**, e.g., a multimeter in some instances, can be separate or integrated with the pump **10**. In some variations, the input meter **111** can be located anywhere along the path before or at the input of the pump **10**. In some variations, the output meter **112** can also be located anywhere along the path after the output of the pump **10**.

[0050] FIG. **5** shows a flowchart of an example method of calibrating a pump system. The method **200** can include providing a pump, as shown in block **210**. As described herein, the pump can be a peristaltic pump as shown in FIG. **1** or other type of pump. As shown in block **220**, the method **200** can include calibrating a pump input with an input device connected to the pump, as shown in block **220**, and calibrating a pump output with an output device connected to the pump, as shown in block **230**. FIG. **6** is a flowchart of an example method of calibrating the pump input, with examples of the various steps shown in FIGS. **7-11**. FIG. **12** is a flowchart of an example method of calibrating the pump output, with examples of the various steps shown in FIGS. **13-16**. In various implementations, the processor can be configured to perform any one or more of the method steps described herein to calibrate the pump input and/or pump output. In various instances, the processor can be configured to execute one or more software applications, e.g., one or more software applications on a computer-readable medium.

[0051] To begin calibration, as shown in FIG. **7**, the user can select one of the input stations **25** (e.g., Settings button) on the display **22** of the user interface **20** of the pump **10**. In FIG. **8**, the user can configure the pump **10** to respond to incoming signals in a certain manner. For example, the user can set one or more input signal values for one or more given operational parameters (e.g., motor speed, flow rate, revolutions per minute, etc.). In some instances, the pump **10** can be calibrated for a range of input signal values, such as input signal values corresponding to the minimum and maximum input signal values for the pump **10**. In various examples, the input signal value can be set for a certain motor speed, flow rate, or revolutions per minute. For example, the pump **10** can be configured to set the minimum and maximum input signal values to 0% and 100% speed of the pump respectively.

[0052] The input signal value is not particularly limited and can have any value for the particular application. In some instances, the input signal value can be a value in the range of 0-25 mA (e.g., 0 mA, 0.5 mA, 1 mA, 2 mA, 3 mA, 4 mA, . . . 20 mA, 21 mA, 22 mA, 23 mA, 24 mA, 25 mA, etc.) or in any range therebetween (e.g., 0.5 mA-25 mA, 1 mA-24 mA, 2 mA-23 mA, 3 mA-22 mA, 4 mA-20 mA, etc.). In some instances, the motor speed can be any percentage in the range of 0-100% speed (e.g., 0%, 1%, 2%, 3%, 4%, 5%, . . . 95%, 96%, 97%, 98%, 99%, 100%, etc.) or in any range therebetween.

[0053] In the example shown in FIG. **8**, the user can set two input signal values **26** to operate at

two different motor speeds **27**. In particular, the user can set the pump to run at 0% speed when the pump receives a first received input signal and set the pump to run at 100% speed when the pump receives the second received input signal. The example shows a 4 mA received input signal equal to 0% motor speed and a 20 mA received input signal equal to 100% motor speed. As set forth herein, other examples are possible. For example, at the low end, the input signal value can correspond to a value in the range of 0-6 mA, 1-6 mA, 2-6 mA (e.g., 0.5 mA, 1 mA, 1.5 mA, 2 mA, 2.5 mA, 3 mA, 3.5 mA, 4 mA, 4.5 mA, 5 mA, 5.5 mA, 6 mA, etc.), or in any range formed by any of these values. As another example, at the high end, the input signal value can correspond to a value in the range of 18-22 mA, 18-24 mA, 18 mA-25 mA (e.g., 18 mA, 19 mA, 20 mA, 21 mA, 22 mA, 23 mA, 24 mA, 25 mA), or in any range formed by any of these values.

[0054] In some instances, the user may set only one received input signal to correspond to a given motor speed (e.g., 50% motor speed, 75% motor speed, 100% motor speed, etc.). As another example, the user may set three input signal values for three different motor speeds. In some instances, the user can set one or more input signal values, not necessarily the minimum or maximum input signal value, to an operational parameter, not necessarily the minimum or maximum for the operational parameter. In various instances, a linear relationship can define the relationship between the input signal value and the operational parameter. In other instances, a non-linear relationship can define the relationship between the input signal value and the operational parameter.

[0055] In some examples, when initially configuring the pump **10**, the user interface **22** can display a default or a previously used setting, which can be changed by the user. After the intended configuration is inputted, the user can select an appropriate input station **28** to accept the configuration and proceed to input calibration.

[0056] With reference to FIG. **6**, the method **220** of calibrating the pump input can include selecting a first input signal value, as shown in block **221**, and generating a transmitted input signal corresponding to the first input signal value, as shown in block **222**. In the example shown in FIG. **9**, the user interface **20** on the pump **10** can prompt the user to ensure the equipment (e.g., input device **110** shown in FIGS. **4A** and **4B**) is properly connected to the pump **10** and to generate a transmitted input signal (e.g., transmitted input signal **101** shown in FIGS. **4A** and **4B**) corresponding to the first input signal value. In the example shown in FIG. **9**, the input device **110** can generate a transmitted input signal **101** corresponding to the first input signal value of 4 mA (e.g., the minimum input signal value in this example).

[0057] Referring back to FIG. **6**, the method can optionally include measuring the received input signal value, as shown in block **223**. For example, an input meter **111** (e.g., as shown in FIG. **4B**) can measure the received input signal **101** so as to determine the received input signal value. Although the user may have intended to send an 4 mA input signal, the actual received input signal value may deviate from this value, e.g., the actual received input signal value may be 4.1 mA or 3.9 mA.

[0058] Referring back to FIG. **6**, the method can include setting a nominative pump input value corresponding to the received input signal value, such that the nominative pump input value is the first input signal value, as shown in block **224**. For example, the pump **10** can have a nominative pump input value corresponding to the received input signal value. However, to calibrate the pump input with the input device **110**, the nominative pump input value can be set to the first input signal value. In the example shown in FIG. **9**, the nominative pump input value can be set to a 4.00 mA Current Signal Value as shown on the display **22** by selecting the appropriate input station **31** (Set 4 mA Input). Accordingly, when the user sends an intended signal of 4 mA, the pump **10** can be calibrated such that the nominative pump input value is 4.00 mA. In other words, the received input signal value, which may or may not be 4.00 mA, can be calibrated as 4.00 mA as expected by the user.

[0059] As described herein, the method **220** can include calibrating the pump input for a second

input signal value. In the example shown in FIG. 10, the input device **110** can generate a transmitted input signal **101** for an input signal value of 20 mA (e.g., the maximum input signal value in this example). By selecting an appropriate input station **32** (Set 20 mA Input), the nominative pump input value can be set to a 20.00 mA Current Signal Value as shown on the display **22**. Accordingly, when the user sends an intended signal of 20 mA, the pump **10** can be calibrated such that the nominative pump input value is 20.00 mA. In other words, the received input signal value, which may or may not be 20.00 mA, can be calibrated as 20.00 mA as expected by the user.

[0060] In various implementations, the processor can be configured to not calibrate the pump input when the received input signal value (e.g., measured from the input meter **111** shown in FIG. 4B) is greater than a threshold value from the selected input signal value (e.g., too far off from the expected value). For example, the processor may not calibrate the pump input when the received input signal value is greater than 1 mA, 1.5 mA, 2 mA, 2.5 mA, 3 mA, etc. from the selected input signal value. In the example shown in FIG. 11, the input stations **31**, **32** to set the nominative pump input value are not selectable if the received input signal value (e.g., shown as 12.00 mA on the display **22**) is far off (e.g., greater than  $\pm 1$  mA in this example) from the one or more selected input signal values (e.g., 4 mA or 20 mA).

[0061] The method can also calibrate the pump output with an output device. In various implementations, the user can configure the pump **10** such that the output device **112** shown in FIGS. 4A and 4B responds as expected to the received output signals **102**. In the example shown in FIG. 13, the user can indicate one or more operational parameters **36** (e.g., speed, flow rates, revolutions per minute, etc.) that operate at a certain signal value **37**. For example, the user can set two motor speeds that operate at two different signal values. In particular, the user can set the minimum and maximum motor speeds to the minimum and maximum signal values, respectively. The example shows that the pump runs at 0% motor speed when the pump receives 4 mA input signal and that the pump runs at 100% motor speed when the pump receives 20 mA input signal, which are the responses expected by the user based on the input configuration shown in FIG. 8. The user can select an appropriate input station **38** to accept the configuration and proceed to output calibration.

[0062] With reference to FIG. 12, the method **230** of calibrating the pump output can include receiving a received output signal outputted from the pump, as shown in block **231**. In the example shown in FIG. 14, the user interface **20** on the pump **10** can prompt the user to ensure the equipment (e.g., output device **112** shown in FIGS. 4A and 4B) is properly connected to the pump **10** and to generate an output signal (e.g., the received output signal **102** shown in FIGS. 4A and 4B) from the pump **10**. In this example, the pump **10** can generate an output signal corresponding to the motor speed at which it operated.

[0063] Referring back to FIG. 12, the method **230** can optionally include measuring the received output signal value, as shown in block **232**. For example, an output device such as an output meter **112** (e.g., as shown in FIGS. 4A and 4B) can measure the received output signal **102** so as to determine the received output signal value. The received output signal value may or may not equal the selected input signal value (or the transmitted signal value). For example, the user may enter 4 mA as the first input signal value, and the received output signal value may be 4.1 mA.

[0064] With continued reference to FIG. 12, the method **230** can include setting a nominative pump output value corresponding to the received output signal value, such that the nominative pump output value is the first input signal value, as shown in block **233**. For example, the pump **10** can have a nominative pump output value corresponding to the signal value of the signal **102** received by the output device **112**, e.g., the received output signal value. However, to calibrate the pump output with the output device **112**, the nominative pump output value can be set to the first input signal value. To calibrate the pump output, in the example shown in FIG. 14, the user can select the appropriate input station **41** (Generate 4 mA Output) to generate the output signal from the pump



**10.** In some instances, the user can enter the received output signal value in the allocated space **42** on the display **22** (e.g., measured as 4.1 mA in this example).

[0065] As described herein, in the example shown in FIG. **15**, the pump output can be calibrated for a second output signal value. The user can select the appropriate input station **43** (Generate 20 mA Output) to generate a second output signal from the pump **10**. In this example, the user can enter the received output signal value in the allocated space **44** on the display **22** (e.g., measured as 19.9 mA in this example).

[0066] In the example shown in FIG. **16**, the user can select the appropriate input station **48** (Save) on the display **22** to save the calibrated values into the pump **10**. As such, the processor can set a nominative pump output value corresponding to the received output signal value, such that the nominative pump output value is the selected input signal value (e.g., as shown as 4.00 mA Current Signal Value on the display **22**). Accordingly, when the user sends an intended signal of 4 mA, the pump **10** can be calibrated such that the nominative pump input value is 4.00 mA and the nominative pump output value is also 4.00 mA. In other words, the actual received output signal value, which may or may not be 4.00 mA, can be calibrated as 4.00 mA. In some examples, the pump system can further include a display (e.g., on the output device **112**) to present the nominative pump output value. In various implementations, when a user enters a certain input signal value (e.g., 4 mA), the pump input and pump output can be calibrated so that when the user receives the nominative pump output value (e.g., 4.00 mA), the user can know that the pump is working as expected and thus, reducing the need for unnecessary adjustments.

[0067] Although these inventions have been disclosed in the context of certain preferred embodiments and examples, it will be understood by those skilled in the art that the present inventions extend beyond the specifically disclosed embodiments to other alternative embodiments and/or uses of the inventions and obvious modifications and equivalents thereof. In addition, while several variations of the inventions have been shown and described in detail, other modifications, which are within the scope of these inventions, will be readily apparent to those of skill in the art based upon this disclosure. It is also contemplated that various combination or sub-combinations of the specific features and aspects of the embodiments may be made and still fall within the scope of the inventions. It should be understood that various features and aspects of the disclosed embodiments can be combined with or substituted for one another in order to form varying modes of the disclosed inventions. Thus, it is intended that the scope of at least some of the present inventions herein disclosed should not be limited by the particular disclosed embodiments described above.

## Claims

**1.-32.** (canceled)

**33.** A method of controlling a pump, comprising: providing a pump; providing an input device connected to the pump, wherein the input device is configured to provide an input signal to control the pump; generating a first input signal having a first value; generating a second input signal having a second value, wherein the first value is smaller than the second value; setting the pump to run at a speed in the range of 0-20% speed when the input signal is at the first value; and setting the pump to run at a speed in the range of 80-100% speed when the input signal is at the second value.

**34.** The method of controlling a pump of claim 33, further comprising: not running the pump when the input signal is lower than the first value and not running the pump when the input signal is higher than the second value.

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