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Inventor(s)	Smith; Roger E.

Ambulatory infusion pumps and assemblies for use with same

Abstract

According to an aspect, a cannula insertion mechanism includes a seal and a cannula carrier. The seal is configured to surround an opening of a housing, the seal including a first seal surface and a second seal surface, the first seal surface facing toward the opening, and the second seal surface facing away from the opening. The cannula carrier is configured to drive a cannula in a first direction through the opening of the housing, the cannula carrier having a first carrier surface and a second carrier surface, the first carrier surface being configured to exert a compression force on the second seal surface when the cannula carrier drives the cannula in the first direction, thereby causing the first seal surface to expand in a second direction to engage the second carrier surface via a clamping force.

Inventors:	Smith; Roger E. (Ivins, UT)
Applicant:	MEDTRONIC MINIMED, INC. (Northridge, CA)
Family ID:	1000008764208
Assignee:	MEDTRONIC MINIMED, INC. (Northridge, CA)
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Primary Examiner: Fredrickson; Courtney B

Attorney, Agent or Firm: Fortem IP LLP

Background/Summary

CROSS-REFERENCE TO RELATED APPLICATIONS (1) This application is a continuation of U.S. application Ser. No. 16/038,049, filed Jul. 17, 2018, which claims the benefit of and priority to previously filed U.S. Provisional Patent Application Ser. No. 62/528,486, filed Jul. 4, 2017, which is incorporated herein by reference in its entirety.

FIELD

(1) The present devices and methods relate generally to ambulatory infusion pumps and inserters and seals for those pumps.

BACKGROUND

(2) Ambulatory infusion pumps (also referred to herein simply as “infusion pumps”) are relatively small, at least substantially self-contained devices that are used to introduce drugs and other infusible substances (collectively “medicament”) into patients' bodies. Some infusion pumps are configured to be worn on a belt, carried in a clothing pocket, or the like. Other infusion pumps are configured to be adhered to skin in patch-like fashion. Infusion pumps are advantageous in that they may be used to, for example, subcutaneously introduce (or “infuse”) medicament on an ongoing or even continuous basis outside of a clinical environment. Infusion pumps are also advantageous in that they greatly reduce the frequency of subcutaneous access events such as needle-based shots. One example of a medicament that may be introduced by an infusion pump is a liquid formulation of insulin. Other exemplary medicaments that may be introduced by an infusion

pump include, but are not limited to, drugs that treat cancers and drugs that suppress the perception of pain.

(3) Many conventional infusion pumps have improved patient health and quality of life. Nevertheless, the present inventors have determined that conventional infusion pumps are susceptible to a wide range of improvements. By way of example, but not limitation, the present inventors have determined that it would be desirable to provide an infusion pump that is smaller, simpler, more reliable, and less costly than conventional infusion pumps, while also being more accurate and user-friendly than conventional infusion pumps.

SUMMARY

(4) The techniques of this disclosure generally relate to cannula insertion mechanisms. In one aspect, the present disclosure provides a cannula insertion mechanism including a seal and a cannula carrier. The seal is configured to surround an opening of a housing, the seal including a first seal surface and a second seal surface, the first seal surface facing toward the opening, and the second seal surface facing away from the opening. The cannula carrier is configured to drive a cannula in a first direction through the opening of the housing, the cannula carrier having a first carrier surface and a second carrier surface, the first carrier surface being configured to exert a compression force on the second seal surface when the cannula carrier drives the cannula in the first direction, thereby causing the first seal surface to expand in a second direction to engage the second carrier surface via a clamping force.

(5) In another aspect, the disclosure provides a fluid delivery device that includes a housing and a cannula insertion mechanism. The cannula insertion mechanism includes a seal and a cannula carrier. The seal is configured to surround an opening of the housing, the seal including a first seal surface and a second seal surface, the first seal surface facing toward the opening, and the second seal surface facing away from the opening. The cannula carrier is configured to drive a cannula in a first direction through the opening of the housing, the cannula carrier having a first carrier surface and a second carrier surface, the first carrier surface being configured to exert a compression force on the second seal surface when the cannula carrier drives the cannula in the first direction, thereby causing the first seal surface to expand in a second direction to engage the second carrier surface via a clamping force.

Description

BRIEF DESCRIPTION OF THE DRAWINGS

(1) Detailed description of exemplary embodiments will be made with reference to the accompanying drawings.

(2) FIG. 1A is a perspective view of an exemplary infusion pump system in an assembled state.

(3) FIG. 1B is an exploded perspective view of the infusion pump system illustrated in FIG. 1A, including a durable assembly and a disposable assembly.

(4) FIG. 2 is a top view of certain components of the infusion pump system illustrated in FIGS. 1A and 1B.

(5) FIG. 2A is a schematic view showing a use of the infusion pump system illustrated in FIGS. 1A and 1B.

(6) FIG. 2B is a schematic view showing another use of the infusion pump system illustrated in FIGS. 1A and 1B.

(7) FIG. 3A is a perspective view of an exemplary durable assembly.

(8) FIG. 3B is a perspective view of certain components of the durable assembly illustrated in FIG. 3A.

(9) FIG. 4A is a perspective view of an exemplary disposable assembly.

(10) FIG. 4B is a perspective view of certain components of the disposable assembly illustrated in

FIG. 4A.

(11) FIG. 5A is a perspective view of certain components of a durable assembly and a disposable assembly of an exemplary infusion pump system.

(12) FIG. 5B is a perspective view of the components of the exemplary durable assembly illustrated in FIG. 5A.

(13) FIG. 5C is a perspective view of the components of the exemplary disposable assembly illustrated in FIG. 5A.

(14) FIG. 6 is a perspective section view of components of the exemplary infusion pump system of FIG. 5A, revealing a gap between certain components of the durable and disposable assemblies.

(15) FIG. 7 is a front view showing a patient's skin being cleaned.

(16) FIG. 8 is a flow chart illustrating an exemplary disposable assembly removal and replacement method.

(17) FIG. 9A is a perspective view of another exemplary infusion pump system in an assembled state.

(18) FIG. 9B is a perspective view of an exemplary durable assembly of the infusion pump system of FIG. 9A.

(19) FIG. 9C is a perspective view of certain components of the durable assembly illustrated in FIG. 9.

(20) FIG. 9D is a perspective view of an exemplary disposable assembly of the infusion pump system of FIG. 9A.

(21) FIG. 9E is a perspective view of certain components of the disposable assembly illustrated in FIG. 9D.

(22) FIG. 10A is a perspective view of another exemplary infusion pump system, shown in assembled state one, before pull-before-use plug, PBUP 517, is removed.

(23) FIG. 10B is a perspective view of the bottom of the infusion pump system of 10A.

(24) FIG. 10C is a perspective view of an exemplary durable assembly of the infusion pump system of FIGS. 10A and 10B.

(25) FIGS. 10D and 10E are perspective views of certain components of the durable assembly illustrated in FIG. 10C.

(26) FIG. 10F is a perspective view of an exemplary disposable assembly of the infusion pump system of FIG. 10A.

(27) FIG. 10G is a perspective view of certain components of the disposable assembly illustrated in FIG. 10F.

(28) FIG. 10H is a section view showing certain components of the disposable assembly illustrated in FIG. 10G, shown in state one.

(29) FIGS. 11A and 11B are perspective views of certain exemplary components of a disposable assembly, shown in state two, before cannula insertion.

(30) FIG. 11C is a side view showing additional exemplary components for use with the components of FIGS. 11A and 11B, shown in position before cannula insertion

(31) FIG. 11D is a section view showing additional exemplary components for use with the components of FIGS. 11A-11C, shown in position before cannula insertion.

(32) FIG. 12A is a section view of the components of FIG. 11D, shown in state three, after cannula insertion but before trocar retraction

(33) FIG. 12B is a perspective view showing additional exemplary components for use with the components of FIG. 12A, shown in position after cannula insertion but before trocar retraction.

(34) FIG. 13A is a section view of the components of FIGS. 11D and 12A, shown in state four, after cannula insertion and after trocar retraction.

(35) FIG. 13B is a perspective view showing additional exemplary components for use with the components of FIG. 13A, shown in position after cannula insertion and after trocar retraction.

(36) FIGS. 13C and 13D are section views of certain exemplary components of the assembly of

FIG. 3A.

(37) FIG. 14A is a section view showing certain alternative components of a disposable assembly, shown in state one, before pull-before-use plug, PBUP 517a, is removed.

(38) FIG. 14B is a perspective section view showing further alternative components of the disposable assembly of FIG. 14A, shown in state two, after PBUP 517a is removed but before cannula insertion.

(39) FIGS. 14C and 14D are section views of certain components and features of FIG. 14B, shown during transition from state two to state three, as the cannula is being inserted.

(40) FIG. 14E is a section view of certain components and features of FIG. 14B, shown in state three, once the cannula is inserted.

(41) FIG. 14F is a section view of the certain components and features of FIG. 14B, shown in state four, after cannula insertion and after trocar retraction.

DETAILED DESCRIPTION

(42) The following is a detailed description of the best presently known modes of carrying out the inventions. This description is not to be taken in a limiting sense, but is made merely for the purpose of illustrating the general principles of the inventions.

(43) It should also be noted here that the specification describes structures and methods that are especially well-suited for the subcutaneous delivery of high concentration insulin (i.e., U-200 insulin and above) such as U-500 insulin as well as lower concentration insulin such as U-100 insulin. Nevertheless, it should be appreciated that the present inventions are applicable to a wide variety of infusion pumps and medicaments. By way of example, but not limitation, the inventions may employ, for fluid displacement, a reservoir with a plunger, a fluid displacement device in the form of a plunger pusher, and a drive mechanism that includes a motor, or other fluid displacement devices, regardless of the type of reservoir employed, piston pumps (e.g., electromagnet pumps), MEMS pumps, peristaltic pumps and any other suitable pumps as well as corresponding drive mechanisms. Exemplary infusion pumps that include a reservoir with a plunger, sometimes in combination with a fluid displacement device in the form of a plunger pusher, and a drive mechanism, are described in U.S. patent application Ser. No. 12/890,207, filed Sep. 24, 2010, and corresponding U.S. Pat. No. 8,777,901, both of which are incorporated by reference in their entireties; in U.S. provisional patent application Ser. No. 62/057,273, filed Sep. 30, 2014, corresponding U.S. patent application Ser. No. 14/869,906, filed Sep. 29, 2015, and corresponding U.S. patent publication number 2016/0089491, each of which are incorporated by reference in their entireties; in U.S. provisional patent application Ser. No. 62/117,565, filed Feb. 18, 2015, corresponding U.S. patent application Ser. No. 15/042,093, filed Feb. 11, 2016, and corresponding U.S. patent publication number 2016/0235913, each of which are also incorporated by reference in their entireties; and in U.S. provisional patent application Ser. No. 62/294,941, filed Feb. 12, 2016, and corresponding U.S. patent application Ser. No. 15/430,513, filed Feb. 12, 2017, both of which are also incorporated by reference in their entireties. The present inventions are also applicable to medicaments such as, for example, drugs to mask pain, chemotherapy and other cancer related drugs, antibiotics, hormones, GLP-1, glucagon, various other drugs that include large molecules and proteins that may require a high level of delivery accuracy, as well as to relatively high concentration insulin (i.e., U-200 insulin and above) such as U-500 insulin, as well as lower concentration insulin, such as U-100 insulin. U.S. application Ser. No. 13/475,843, filed May 18, 2012, and corresponding U.S. Pat. No. 9,114,208, as well as aforementioned U.S. Pat. No. 8,777,901, aforementioned U.S. patent publication number 2016/0089491, and aforementioned U.S. patent application Ser. No. 15/430,513 each also describe patient interaction with and use of infusion pumps such as the exemplary infusion pumps described herein.

(44) As noted above, some ambulatory infusion pumps are intended to be worn on a belt, carried in a pocket, or otherwise supported within a holder of some kind (referred to collectively as “pocket pumps”). Such infusion pumps transfer fluid from a reservoir to an infusion set by way of an

elongate tube. Subcutaneous access may be obtained by way of a cannula in the infusion set. Other ambulatory infusion pumps are intended to be adhered to the skin above the delivery site (sometimes referred to as “patch pumps”). Here, the cannula or other subcutaneous access device may extend directly from the infusion device. In either case, these pumps infuse medicament through a cannula subcutaneously at a depth of approximately 6 mm. Given these modes of use, patients typically prefer the device to be as small as possible so it is more comfortable, less obtrusive, and less visible. In addition, patients want a device that is easy and convenient to use.

(45) An exemplary ambulatory infusion system, which is generally represented by reference numeral **100** in FIGS. **1A**, **1B**, and **2**, includes a durable assembly **200** and a disposable assembly **300**. Exemplary durable assembly **200** includes a housing **202**, one or more batteries or other energy supply **221**, one or more capacitors or other energy storage **222**, a microprocessor **223**, a coil assembly **224** (which functions as a motor stator), and one or more Hall-effect sensors **225**. Exemplary disposable assembly **300** includes a baseplate **350** supporting components such as a magnetic motor rotor **331**, a gear train **332** including lead screw drive gear **333** in a reservoir support block **337**, and a lead screw **334** attached to plunger **335**, which is positioned in a medicament reservoir **336** that is mounted to the reservoir support block **337**. The exemplary plunger **335** includes a core and a plurality of seals on the core. A cover **302**, under which some or all of the magnetic motor rotor **331**, gear train **332** (with drive gear **333**), lead screw **334**, plunger **335**, and medicament reservoir **336** are located in various embodiments, may be mounted to the baseplate **350**.

(46) The lead screw drive gear **333**, lead screw **334**, plunger **335**, medicament reservoir **336** and reservoir support block **337** may also be referred to collectively as a “reservoir assembly.” Other exemplary reservoir assemblies, durable assemblies, disposable assemblies, and seal assemblies that may be employed in, for example, infusion system **100** are described below with reference to FIGS. **9A-9D**, and in FIGS. **10A-10H**.

(47) The exemplary disposable assembly **300** may be secured to the exemplary durable assembly **200**, as shown in FIGS. **1A** and **2**. To that end, the exemplary housing **202** includes a top wall **204**, bottom walls **206a** and **206b** and a side wall **208** that together define a relatively thin housing portion **210** and a relatively thick housing portion **212**. An indentation **214** is formed in the relatively thick portion **212**. The exemplary cover **302** includes top walls **304a** and **304b** and a side wall **306** that together define a relatively thin cover portion **308** and a relatively thick cover portion **310**. A portion of the baseplate **350** is not covered by the cover **302**, thereby defining a recess **312** that is bordered by a wall **314** that extends around the baseplate (see also FIG. **4B**). When the durable and disposable assemblies **200** and **300** are secured to one another in the manner illustrated in FIG. **1A**, the relatively thick portion **212** of the housing **202** will reside in the recess **312** of the disposable assembly **300** (with the wall **314** in the indentation **214**). The relatively thin portion **210** of the housing **202** will reside on the top wall **304b** of the cover **302**. The cover **302** also includes a projection **316** that mates with a recess **216** on the housing **202**. Additionally, as is discussed in greater detail below, the disposable assembly **300** may be configured for different medicaments, such as different medicament concentrations, different medicament amounts, or different modes of system operation.

(48) In other implementations, the cover **302** may be configured to cover fewer than all components on the baseplate **350**. For example, a cover may be configured such that the magnetic motor rotor **331** and a portion of the gear train **332** are not under the cover, while the remaining components are under the cover. In still other implementations, the cover **302** may be omitted and the durable assembly **200** may be configured to cover all components on the baseplate **350**. In yet other implementations, what is referred to in the present application as the “durable” assembly, may be disposable, resulting in a fully disposable system.

(49) As discussed in U.S. Pat. No. 8,777,901 described above, and in U.S. application Ser. No. 13/300,574, filed Nov. 19, 2011, and corresponding U.S. Pat. No. 8,905,972, and in U.S.

application Ser. No. 13/475,843, filed May 18, 2012, and corresponding U.S. Pat. No. 9,114,208, each of which are incorporated by reference in their entireties, ambulatory infusion systems that employ a reservoir on a baseplate may be configured for different types of use. For example, disposable assembly **300** may be adhered to the patient's skin and may be used in conjunction with a cannula (not shown) that is operatively connected to the reservoir **336** so that the system **100** may be deployed as a "patch-pump," as shown in FIG. 2A. Alternatively, as shown in FIG. 2B, the baseplate **350** of disposable assembly **300** may be configured to operably connect the reservoir **336** to an infusion set **382** (e.g., by way of the illustrated infusion set tube and a connector **380** shown in FIGS. 1B and 2) so that the system **100** may be deployed as a "pocket pump," a "belt-worn pump" or some other wearable pump. In other words, using the same durable assembly **200**, the user may configure the system for use as "pocket pump" or a "patch pump" by simply selecting the appropriate disposable assembly and attaching the disposable assembly to the durable assembly. The user may also switch from one configuration to another, by simply removing one disposable assembly and replacing it with another disposable assembly. The connector **380** may also be used as a fill port, as discussed below.

(50) It should therefore be noted that the present inventions include kits that contain various combinations of disposable assemblies, where at least two of the disposable assemblies may be different. Additionally or alternatively, kits or other packages may include various disposable assembly components, such as an infusion set and/or cannula inserter. Kits may also include a durable assembly. The disposable assemblies in such kits may also include the detection/identification instrumentalities discussed below. The components of the present kits (e.g., combination of various disposable assemblies and/or components) may be stored in a common package, with individual packages for each component if necessary, and provided to the user in the common package. Other components that may be provided in such kits include, but are not limited to, inserters that are preloaded with a cannula, and cleaning swabs. A recharger may also be provided in a kit that includes a durable assembly.

(51) In addition to disposable assembly packaging and labeling, the different disposable assemblies may include visual cues to differentiate the various disposable assemblies. For instance, disposable assemblies with different concentrations of medicament or different medicament fill volumes may use different colors for the reservoir and/or baseplate of the disposable assembly, or mechanical features that ensure disposables are only able to attach to correctly programmed durables.

(52) It should also be noted here that, but for the issue of priming, the dispensing procedures associated with an infusion system "patch pump" configuration, which may include a durable assembly **200** and a disposable assembly **300**, are substantially the same as the dispensing procedures associated with a "pocket pump" configuration, which may also include an infusion set **382** (see FIG. 2B). With a "patch pump" configuration, priming is not necessary because the volume of the associated cannula will be very small and there is a direct connection between the cannula and the medicament reservoir. Priming is, however, required to fill the infusion set tube (FIG. 2B) in a "pocket pump" configuration before the onset of medicament delivery. For instance, 20-30 μ l may be required to fill the entire infusion set tube and, accordingly, the priming procedure may involve the rapid delivery of 10-15 IUs of U-500 insulin to the tube. The present inventors have determined that it would be advantageous to prevent users from initiating a priming procedure when the system is in the "patch pump" configuration, with a cannula positioned to deliver medicament essentially directly from the medicament reservoir to the patient, because rapidly delivering 10-15 IUs of insulin to the patient could adversely affect patient health.

(53) To prevent such undesirable outcomes, and for user convenience in other situations involving the choice between a variety of disposable assemblies (such as disposable assemblies with reservoirs containing different medicaments, different concentrations of a medicament, and/or varying amounts of medicaments), at least some of the present disposable assemblies may be provided with a baseplate identification device and at least some of the present disposable

assemblies may be provided with structure that cooperate with a baseplate identification device in such a manner that the durable assembly microprocessor/controller can make a “baseplate type” determination. Exemplary baseplate identification instrumentalities and methodologies may be as described in aforementioned U.S. Pat. Nos. 8,777,901; 8,905,972; and 9,114,208. In addition, baseplate identification may be performed mechanically. For instance, a pin or rib may prevent attachment of certain disposable assemblies with certain durable assemblies. Additionally or alternatively, certain durable assemblies will simply not function with certain disposable assemblies.

(54) Alternatively, the patient or a clinician may program the system, such as via a remote control, to indicate the type of disposable assembly attached. In a manner such as this, a patient can access a variety of medicaments for use with a single durable assembly.

(55) Once the “baseplate type” determination is made (e.g., “patch pump” disposable assembly **300** versus a “pocket pump” with infusion set **382** attached), the durable assembly will proceed in a manner, or mode of operation, that is appropriate for the attached disposable assembly. For example, if “patch pump” disposable assembly **300** is detected, the durable assembly controller will not include priming as part of the delivery process and, in some implementations, will prevent the user from manually implementing a priming procedure. If, on the other hand, a “pocket pump” disposable assembly is detected, then the delivery process may include appropriate priming of the infusion set tube.

(56) Whether configured as a “pocket pump” or a “patch pump,” the system may be configured to provide basal delivery of medicament in accordance with a delivery profile provided by a physician by way of a clinician's programming unit. For example, the system may include a program that stores a number of delivery profiles (e.g., delivery profiles associated with a 24-hour delivery cycle, delivery profiles for particular situations such as sleep or illness, and the like). Each delivery profile specifies multiple doses (or pump “operations”) over time, e.g., a particular number of doses at particular times or a particular number of doses per unit time. In some implementations, a dose may be the volume associated with the minimum controllable displacement of the plunger **335**. The system may also be configured to provide bolus delivery in response to an instruction from a patient remote control **1000** (FIG. 2A). A bolus instruction may come in response to a high glucose level measurement in the case of a diabetic patient, an increase in pain level in the case of a pain management patient, or some other symptom. The system may also be configured to perform other functions, such as ending medicament delivery in response to instructions from patient remote control **1000**.

(57) The present infusion pumps may be used in conjunction with a wide variety of remote controls. Such remote controls may be used to, for example, allow the user to transmit instructions to the durable assembly **200** or facilitate communication between durable assembly **200** and the user (e.g., an alarm condition message or other message concerning the conditions of system **100**). An exemplary remote control **1000** (FIG. 2A) may be configured to facilitate one, some, or all of the following operations: (1) turning the remote control **1000** on or off, (2) associating (or “assigning”) the remote control **1000** to the durable assembly **200**, (3) obtaining status information such as medicament level, battery charge level, and/or alarm conditions, (4) silencing the durable assembly's alarm, (5) selecting options that may be associated with the durable assembly's alarm such as type of alarm (audible, palpable, visible or combinations thereof) and strength/volume of alarm, (6) connecting remote control **1000** to a computer to, for example, update remote control or durable assembly firmware, load and delete delivery profiles stored in the durable assembly or remote control, and otherwise reprogram the durable assembly or remote control, (7) selecting medicament options such as medicament concentrations, (8) selecting and initiating a stored medicament delivery profile, (9) increasing and decreasing medicament dose rate, and/or (10) pausing a dispensing operation. A user may pause delivery in order to remove or replace a patient applied structure (e.g., a disposable assembly), adjust for a current or anticipated changed body

condition (e.g., low glucose, vigorous exercise), follow a physician's suggestion, or disconnect the durable assembly from the body for any other reason.

(58) The exemplary remote control **1000** (FIG. 2A) may be configured to generate an indicator, based on information from a microprocessor **223** for durable assembly **200**, that is indicative of, for instance, the amount of time remaining in the current dispensing program, the amount of time until the next disposable assembly replacement, etc. The indicator may be audible, visible, palpable or combinations thereof. A time remaining indicator may be useful for a variety of reasons. For example, knowledge of the time remaining before the next disposable assembly replacement allows the patient to determine, based at least in part on the current time of day and upcoming events (e.g., travel or sleep), whether or not it would be more convenient to replace the disposable assembly at a time before the end of the dispensing program.

(59) As described above, parts of the present systems may be considered the reusable parts, while other parts may be considered the disposable parts. In the illustrated embodiments, the durable assembly **200**, which may include structures such as microprocessor **223** and coil assembly **224**, is reusable, while exemplary disposable assemblies **300**, which may include structures such as a motor rotor **331** and reservoir **336** on a baseplate **350**, are disposable. In other embodiments, the present systems may be fully disposable.

(60) With respect to dimensions, some embodiments of the exemplary infusion pump system **100** and the embodiments below may have the following dimensions: length dimensions of about 35-60 mm; width dimensions of about 30-45 mm; and overall thickness or height dimensions of about 8-18 mm. Suitable housing materials include, but are not limited to, plastic or other materials having a modulus of elasticity of 0.2-1.0 million psi.

(61) Exemplary durable assembly microprocessors and associated circuitry; rechargeable batteries and associated battery rechargers and recharging methods; battery and recharging management; temperature sensors; and exemplary alarms and alarm conditions are described in more detail in aforementioned U.S. Pat. Nos. 8,777,901; 8,905,972; and 9,114,208.

(62) Turning now to FIGS. 3A and 3B, an exemplary durable assembly **200** may include a power source such as one or more batteries **221**, temporary power storage such as one or more capacitors **222** (see FIGS. 2 and 5B), a controller such as microprocessor **223**, a coil assembly **224**, and a Hall-effect sensor **225**. Those of skill in the art will appreciate that including the motor's coil assembly **224** and all other electronics within the durable assembly **200** reduces the cost and complexity of disposable assembly **300**. In addition, the microprocessor **223** provides flexibility to include features such as user data storage, programs, programmability, adjustability, a display, buttons, wireless communication protocols, or the like to the pump **100**. Durable assembly **200** may also be molded with locking features that snap onto the disposable assembly **300**, but that also allow removal of the durable assembly **200** from the disposable assembly **300** either while the disposable assembly remains in place on the patient (after medicament delivery has been paused), or after the entire system has been removed from the patient.

(63) The power source may be one or more commercially available batteries, such as a commercially available zinc-air battery or lithium polymer battery. The batteries may be selected to have sufficient capacity to operate the system for certain delivery amounts or delivery times, such as for over 400 units of delivered insulin. The optional power storage may be one or more commercially available capacitors or super-capacitors or other temporary storage device(s).

(64) Turning now to FIGS. 4A and 4B, an exemplary disposable assembly **300** may include baseplate **350** and components such as a reservoir **336**, a plunger **335** within the reservoir and connected to lead screw **334**, and a magnetic motor rotor **331** mechanically attached through gear train **332** to affect rotation of the lead screw drive gear **333**, which causes translation of the lead screw **334** and plunger **335** within reservoir **336**. The cover **302** is positioned over these components in the illustrated embodiment. The exemplary baseplate **350** includes an adhesive backing for attachment to the patient with a removable adhesive cover. The baseplate **350** may also

be molded with baseplate locking features that snap onto the durable assembly **200** (such as magnets molded into the housings of each assembly), and that also allows removal of the durable assembly **200** from the disposable assembly **300**.

(65) Referring to FIGS. **2** and **4B**, the exemplary reservoir **336** includes a barrel **338** with an inner surface **340** defining a fluid storage volume **342** and an oval cross-section, but other shapes (such as circular) are possible as is discussed below with reference to FIG. **9E**. A plunger **335** with a matching cross-sectional shape fits within the barrel and carries a fluid seal such as, but not limited to, o-rings, to seal the medicament within the storage volume **342**. Exemplary plunger **335** may be formed from, e.g., rubber and include three o-ring seals. The reservoir **336** includes the aforementioned connector **380** that may be used for filling reservoir **336**, or for attaching a cannula for “patch-pump” type configurations, or for connecting (potentially via an appropriate adapter(s)) an infusion set for “pocket-pump” type configurations. The plunger **335** moves within the barrel **338** to vary the volume of medicament within the storage volume **342**. Reservoir **336** may be, for instance, prefilled or user-filled with U-500 insulin in various volumes to suit the patient use profile. In other instances, lower concentrations of insulin, such as U-100 insulin and U-200 insulin, may be employed. A plug may be inserted in the connector **380** to maintain a sterile environment until use. The plug may be removed by the patient before use, or connector **380** may be configured for one use (sealed until penetrated), or other possibilities, including those described in more detail in aforementioned U.S. patent application Ser. No. 15/430,513.

(66) Additional exemplary baseplates for use with the disposable assemblies of the present inventions, as well as exemplary cannula designs, fluidic connection between a medicament reservoir and the cannula, cooperation between the cannula and disposable assemblies (for instance, to prevent axial movement of the cannula relative to the baseplate and patient), attachment of an infusion set to the reservoir of the disposable assembly, configurations and uses of a non-delivery baseplate, arrangements and structures for attaching disposable and durable assemblies, skin adhesive designs, and various occlusion sensors, may be as described in U.S. patent application Ser. No. 12/890,207, filed Sep. 24, 2010 and corresponding U.S. Pat. No. 8,777,901, as well as aforementioned U.S. Pat. Nos. 8,905,972 and 9,114,208.

(67) Turning now to FIGS. **5A-5C** and the illustrated two-piece motor, the motor's coil assembly **224** (and a Hall-effect sensor **225**) of the durable assembly **200** are positioned above the magnetic motor rotor **331** that is part of the disposable assembly **300**. An exemplary multi-pole motor rotor **331** may be disc-shaped and have a 9.8 mm outer diameter, 5.2 mm inner diameter, and 0.8 mm thickness. Another example motor rotor may have an 11 mm outer diameter, 5 mm inner diameter, and 1.2 mm thickness. Multi-pole motor rotors of this type typically cost less than 5 cents per piece, helping control the total cost of disposable assembly **200**. The motor rotor **331** is also parallel to the baseplate **350**, i.e., the motor rotor axis of rotation is perpendicular to the baseplate, in the illustrated embodiment. The microprocessor **223** directs rotation of motor rotor **331** by sequentially energizing the coils of motor coil assembly **224** to create an electromagnetic torque coupling between the motor coil assembly **224** and the motor rotor **331**. The position/orientation of the rotor's poles relative to the rotating magnetic field generator (coil assembly **224**) is measured by back EMF, a rotary encoder, a Hall-effect sensor **225** (FIG. **5A**), or the like. For instance, a Hall-effect sensor mounted on the coil windings may be used to supply the microprocessor a count, a tachometer signal, or rotor position, allowing low-cost closed-loop control of the rotor speed. Brushless motors of this type are typically 85-90% or more efficient, and run very cool. While there may be variations in construction, the face-to-face stator coils and flat rotor plate shown in FIGS. **5A-5C** provide a compact design. In addition, more coils and/or Hall-effect sensors may be used.

(68) As can best be seen in FIG. **6**, between the motor coil assembly **224** and motor rotor **331** is a gap **240**. Some or all of the gap **240** may be defined by (and occupied by) portions of the housing **202** and the cover **302**, i.e., the housing bottom wall **206a** and the cover top wall **304b** in the

illustrated implementation. In other implementations, the gap **240** between the motor coil assembly **224** and motor rotor **331** may be occupied by only a portion of the durable assembly housing, or only a portion of the disposable assembly cover, or no structure at all and may simply be an air gap. The size of the gap, which is defined by the distance between the motor coil assembly **224** and the motor rotor **331**, is typically about 0.5 mm to 2.0 mm. As such, there is no gear engagement or other mechanical connection between the durable assembly **200** and disposable assembly **300**. And as described earlier, all electronics may be positioned within the durable assembly **200**, with the energy needed by the disposable assembly **300** transferred by electromagnetic torque coupling, which is a coupling without direct mechanical coupling or electrical contact from the durable assembly **200**. This exemplary design affords the additional advantage of being relatively simple to make waterproof, or at least water resistant.

(69) As described above, rotation of motor rotor **331** drives gear train **332**, causing rotation of lead screw drive gear **333**, which in turn affects translation of the lead screw **334** and plunger **335**, which is attached to lead screw **334**. In this manner, electromagnetically generated torque is created when electromagnetic energy supplied by durable assembly **200** is transformed into mechanical forces within the disposable assembly **300** that advance plunger **335**. A ratchet (not shown) or other similar device may be used to prevent back-driving of gear train **332**. As plunger **335** is driven through reservoir **336**, medicament is dispensed precisely, corresponding to the precision movements of the gears and motor rotor. With the entire gear train, lead screw drive gear, lead screw, and plunger all permanently contained in the disposable assembly **300**, there is no need to retract any plunger components into the durable assembly **200** before separation from the disposable assembly **300**. As a result, a further advantage of this exemplary design (and those below) is greatly reduced energy consumption, which allows use of, for instance, a primary battery(ies) as a power source.

(70) Use of an exemplary system **100** will now be described. At the most basic level, a patient's use of the exemplary infusion pump systems (e.g., system **100** in FIGS. **1A-2B**) involves obtaining a new disposable assembly **300**, connecting the disposable assembly to the durable assembly **200**, peeling the liner from the baseplate adhesive layer, gaining subcutaneous access, and initiating a medicament delivery operation. In some instances, use may involve additional steps such as attaching a cannula to connector **380** of the disposable assembly and removing a cannula cap, if necessary. Various aspects of the basic operation of the present systems are described below. Operation of a system does not necessarily require all the steps each time the system is deployed, and the order of some of the steps may be changed. Operation is also discussed below, in the exemplary context of the above-described durable assembly **200** and disposable assembly **300** used as a patch pump, via a flow chart (FIG. **8**). The discussion is, however, equally applicable to other patch pump implementations, such as described in FIGS. **10A-10H**, as well as to pocket pump implementations with minor variations. Also, unless otherwise indicated, the actions and determinations performed by the durable assembly **200** are controlled by the durable assembly microprocessor and further references to the controller are limited in the interest of brevity.

(71) Referring to FIG. **8**, use of the present systems may involve removal of a disposable assembly from a durable assembly and the replacement of the disposable assembly. This may occur when the medicament reservoir is empty (as described in more detail in U.S. patent application Ser. No. 12/890,207 and corresponding U.S. Pat. No. 8,777,901) (Step **S101**) and a “replace disposable assembly” message or alert is presented on remote control **1000** (Step **S102**), or when a buzzer or other alarm (audible, palpable, visible or combinations thereof) from the durable or disposable assembly may signal the need for disposable assembly replacement. Alternatively, the durable assembly controller may receive a user-initiated “replace disposable assembly” signal from a remote control **1000** (Step **S103**). The user may desire to replace a disposable assembly before the medicament reservoir is empty for a variety of reasons such as, for example, to accommodate the user's sleep or travel schedule, when the medicament exhibits a loss of effectiveness, when a

dispensing problem arises, or due to a prescribed change in medicament

(72) The user may then obtain, possibly from storage in a refrigerator depending on medicament requirements, a new pre-filled disposable assembly **300** or may then obtain a new disposable assembly and fill the reservoir in the disposable assembly with medicament (Step **S104**).

Alternatively, the reservoir may be filled after the disposable assembly **300** is attached to durable assembly **200**, as described below. The durable assembly **200** and disposable assembly **300** may then be removed from the skin, separated, and the used disposable assembly **300** discarded (Steps **S106** and **S107**).

(73) Next, the new disposable assembly **300** may be attached to the durable assembly **200** (Step **S109**). In the case of disposable assemblies with user-filled reservoirs, if not filled earlier, the user then injects medicament from a syringe into the reservoir (Step **S112**). Medicament may be injected until the reservoir is full, or the user may choose to introduce a specific amount of medicament from the syringe. Since an unknown amount of medicament may be injected into a user-filled reservoir, a plunger-pusher zeroing procedure (Step **S113**), such as described in U.S. patent application Ser. No. 12/890,207, and corresponding U.S. Pat. No. 8,777,901, may then be user-initiated or may be an automatic aspect of pump operation. If the results of the zeroing procedure are negative, the disposable assembly **300** may be removed and discarded, a new disposable assembly attached and filled, and the zeroing procedure repeated. A slightly altered zeroing procedure is described in more detail below

(74) In either a user-filled or pre-filled configuration, the user should then clean the skin surface **S** onto which the baseplate **350** of disposable assembly **300** will be adhered (FIG. 7, and Step **S116** of FIG. 8). Then the user peels off the baseplate adhesive liner to expose the baseplate adhesive layer (Step **S117**) and removes the pull-before-use plug, PBUP **517**, when present (Step **S118**). These last two steps **S117** and **S118** may be performed in reverse order, as required or desired

(75) The system **100** including durable assembly **200** and disposable assembly **300** may be positioned over the chosen body location and pressed gently to adhere the adhesive layer to the skin surface **S**. Once the system has been adhered, the inserter may be actuated (Step **S119**), as described in more detail below, to position the end of a cannula about 6 mm below the skin. Finally, if necessary, the remote control **1000** may be used to initiate a particular medicament delivery operation (Step **S120**). The delivery operation may follow a predetermined delivery profile (e.g. a particular basal rate, a series of time-spaced bolus deliveries, or some combination thereof) that is equated to motor rotor rotations, at particular rates and times, required to deliver medicament in accordance with the profile. Alternatively, the profile may be input by the user with the remote control **1000** and stored by the durable assembly microprocessor. For example, the remote control may store a number of different delivery profiles and bolus deliveries from which the patient can choose. Such profiles may correspond to, for example and depending on the medicament, days where vigorous exercise is expected, days where it is not, incidences of increased pain, etc. Alternatively, or in addition, the profile stored in the durable assembly microprocessor may be set by a clinician's programming unit. In such a case, as in the case of different disposable assemblies **300** provided with different specified delivery rates, a remote control may not be needed to initiate, e.g., basal delivery.

(76) The discussion above is also applicable to use of the "pocket pump" system as shown in FIG. 2B. Minor variations in the above-described procedure include, for example, use of an infusion set **382** instead of a cannula, attaching the infusion set to connector **380**, potentially via an adapter (which may vary with the type of infusion set **382**), and priming of the tube of infusion set **382**.

(77) Another exemplary ambulatory infusion system, which is generally represented by reference numeral **100a** in FIG. 9A, includes a durable assembly **200a** and a disposable assembly **400**.

System **100a** is substantially similar to system **100**. Here, however, the intersection of the top walls is primarily linear. Additionally, the disposable assembly **400** has a recess **316a** which mates with a corresponding projection **216a** on the durable assembly **200a**. The projection **216a** and recess **316a**

are located at the outer perimeter of the assembled system **100a**.

(78) Exemplary durable assembly **200a**, shown in more detail in FIGS. **9B** and **9C**, may include a housing **202a**, one or more batteries or other energy supply **221a**, one or more capacitors or other energy storage (not shown), a microprocessor (not shown), and a coil assembly **224a** including one or more Hall-effect sensors (not shown). Exemplary disposable assembly **400**, shown in more detail in FIGS. **9D** and **9E**, may include a baseplate **450** supporting components such as a magnetic motor rotor **431**, a gear train **432** including lead screw drive gear **433**, and a lead screw **434** attached to plunger assembly **435** which is positioned in a medicament reservoir **436** having a circular cross-section. The magnetic motor rotor **431** may be mechanically attached through gear train **432** to affect rotation of the lead screw drive gear **433**, which causes translation of the lead screw **434** and the plunger **435** within reservoir **436**. Reservoir **436** may be, for instance, prefilled with U-500 insulin or U-100 insulin or other concentrations of insulin to suit different patient use profiles, or may be user-fillable via a fill port **415**. A reservoir outlet **438** is in fluid communication with reservoir **436**. Disposable assembly **400** may be secured to durable assembly **200a**, as shown in FIG. **9A** and as further described in U.S. provisional patent application Ser. No. 62/057,273, corresponding U.S. patent application Ser. No. 14/869,906, and corresponding U.S. patent publication number 2016/0089491.

(79) Another exemplary ambulatory infusion system, which is generally represented by reference numeral **100b** in FIGS. **10A** and **10B**, includes a durable assembly **200b** and a disposable assembly **500**. System **100b** is substantially like systems **100** and **100a**. Here, the intersection of the top and inside walls is linear in places and curved in others. Also shown in FIGS. **10A** and **10B** are adhesive pad **501** with adhesive backing **503** attached, fill port **515**, pull-before-use plug (PBUP) **517**, and cannula trigger button **520**. These features are described in more detail below.

(80) Exemplary durable assembly **200b**, shown in more detail in FIGS. **10C-10E**, may include a housing **202b**, a buzzer or other alarm device **227**, one or more batteries or other energy supply **221b**, a microprocessor (not shown), and a coil assembly **224b** (which functions as a motor stator) including one or more Hall-effect sensors **225b**. In this embodiment, energy supply **221b** is a rechargeable battery, such as a rechargeable lithium battery, with enough power to drive the motor continuously without needing a capacitor or other additional energy storage device. As mentioned earlier, exemplary durable assembly microprocessors and associated circuitry; rechargeable batteries and associated battery rechargers and recharging methods; battery and recharging management; temperature sensors; and exemplary alarms and alarm conditions are described in more detail in aforementioned U.S. Pat. Nos. 8,777,901; 8,905,972; and 9,114,208.

(81) Returning to FIG. **10E**, coil assembly **224b** is positioned around durable housing portion **228**, which is configured to fit over disposable housing portion **528** (FIG. **10F**), which in turn fits over magnetic motor rotor **531** (FIG. **10G**). In this two-piece motor, the motor's coil assembly **224b** is in durable assembly **200b** and is positioned around motor rotor **531** that is part of the disposable assembly **500**. Hall-effect sensors **225b** are positioned above coil assembly **224b** in durable assembly **200b**. In this configuration, there is a gap between motor coil assembly **224b** and motor rotor **531**. Some or all of the gap may be defined by (and occupied by) housing portions, e.g., durable housing portion **228** and disposable housing portion **528** in the illustrated implementation. In other implementations, the gap between the motor coil assembly **224b** and motor rotor **531** may be occupied by only a portion of the durable assembly housing, or only a portion of the disposable assembly cover, or no structure at all and may simply be an air gap. The size of the gap, which is defined by the distance between the motor coil assembly **224b** and the motor rotor **531**, is typically about 0.5 mm to 2.0 mm. As such and as described earlier, there is no gear engagement or other mechanical connection between the durable assembly **200b** and disposable assembly **500**. Also as described earlier, all electronics may be positioned within the durable assembly **200b**, with the energy needed by disposable assembly **500** transferred by electromagnetic torque coupling, which is a coupling without direct mechanical coupling or electrical contact from the durable assembly

200b. These exemplary designs afford the additional advantage of being relatively simple to make waterproof, or at least water resistant.

(82) An exemplary motor rotor **531** may be a 2-pole, cylinder-shaped, rare earth (such as neodymium) rotor, magnetized across the diameter, with a 5 mm diameter and 5 mm height. Other suitable motor rotors may be larger or smaller, or be multi-pole. Motor rotors of this type typically cost about 5 cents per piece, helping control the total cost of disposable assembly **500**. The microprocessor (not shown) directs rotation of motor rotor **531** by sequentially energizing the coils of motor coil assembly **224b** to create an electromagnetic torque coupling between the motor coil assembly **224b** and the motor rotor **531**. The position/orientation of the rotor's poles relative to the rotating magnetic field generator (coil assembly **224b**) is measured by back EMF, a rotary encoder(s), one or more Hall-effect sensors **225b**, or the like. For instance, the Hall-effect sensors **225b** mounted above the coil windings **224b** may be used to supply the microprocessor a count, a tachometer signal, or rotor position, allowing low-cost, closed-loop control of the rotor speed. As stated earlier, brushless motors of this type are efficient and run very cool. While there may be variations in construction, the configuration shown in FIGS. **10D-10G** provides a compact design.

(83) Exemplary disposable assembly **500**, shown in more detail in FIGS. **10F** and **10G**, may include a baseplate **550** supporting components such as above-described magnetic motor rotor **531** and a gear train **532**. Gear train **532** is attached to a plunger assembly **535** that is positioned in a medicament reservoir **536**. Plunger assembly **535** comprises, among other items, plunger pusher **535a** and plunger **535b**. The magnetic motor rotor **531** may be mechanically attached through gear train **532** to affect translation of plunger pusher **535a** (and plunger **535b**, when attached to plunger pusher **535a**) within reservoir **536**. Reservoir **536** may be, for instance, prefilled with U-100 insulin or U-500 insulin or other concentrations of insulin to suit different patient use profiles, or may be user-fillable by way of a fill port **515**. A reservoir outlet fitting **548** is in fluid communication with reservoir **536**. A cannula trigger button **520**, when pressed, causes rotation of a trigger link **547** that is positioned above reservoir outlet fitting **548**, triggering cannula insertion (as described in more detail below). Reservoir outlet fitting **548** is made from a drug-compatible material, such as, but not limited to, polypropylene, cyclic olefin polymer (COP) or polyethylene. Cannula trigger button **520** and trigger link **547** may be made of a strong, lightweight material, such as polycarbonate, nylon, acetal (Delrin®) or the like. Disposable assembly **500** may be secured to durable assembly **200b**, as shown in FIG. **10A** and as further described above or in aforementioned U.S. patent publication number 2016/0089491.

(84) As best seen in FIG. **10G**, gear train **532** of exemplary disposable assembly **500** is slightly different from the gear trains in the embodiments described above. In this embodiment, gear train **532** includes a worm drive comprised of worm screw **533a** and worm gear **533b**, and also a fine-pitch lead screw (not shown) and lead screw nut **534a**. The worm gear **533b** is coupled to the lead screw via the lead screw nut **534a**, which encloses the lead screw. Protrusions **534b** on the lead screw nut **534a** correspond with recesses (not shown) inside worm gear **533b**, and a threaded portion (not shown) inside lead screw nut **534a** pairs with the thread on the lead screw enclosed by the lead screw nut **534a**. The configuration of gear train **532** prevents back-driving, eliminating the need for a clutch or other locking mechanism. Suitable materials for the components of gear train **532** include, but are not limited to, stainless steel or high strength plastic, such as nylon, acetal (Delrin®) or polycarbonate.

(85) As also seen in FIG. **10F**, exemplary disposable assembly **500** also differs from the above embodiments in that plunger assembly **535** includes a plunger pusher **535a** in addition to a plunger **535b**. Exemplary infusion pumps that include a reservoir with a plunger in combination with a fluid displacement device in the form of a plunger pusher are described in aforementioned U.S. Pat. No. 8,777,901. In the case of disposable assemblies with user-filled reservoirs, the user may completely fill the reservoir to capacity with medicament, or the user may choose to introduce less medicament, and not completely fill the reservoir. As described earlier, since an unknown amount

of medicament may be injected into a user-filled reservoir, a plunger-pusher zeroing procedure, such as described in U.S. Pat. No. 8,777,901, may be user-initiated or may be an automatic aspect of pump operation. The pusher zeroing procedure precisely determines and/or sets, before any medicament dispensing, exactly how far plunger pusher **535a** must travel before it engages plunger **535b**, allowing a calculation to determine the amount of medicament in the reservoir and, therefore, an estimate of time-to-empty and need for disposable assembly replacement.

(86) FIG. **10G** shows the plunger assembly **535** before any medicament is introduced into reservoir **536**. At this point, and until pusher zeroing is complete, plunger **535b** is free-floating within reservoir **536**, and PBUP **517** must be in place, as shown in FIG. **10H**. Plunger pusher **535a** is, at all times, attached to lead screw **534a**, and begins in the fully-retracted position. As medicament is introduced into reservoir **536** via fill port **515**, plunger **535b** is pushed towards plunger pusher **535a**. If the reservoir is filled to capacity, plunger **535b** will be pushed into contact with plunger pusher **535a**, causing hooks **537** (or other suitable method of attachment) on pusher **535b** to engage with and permanently lock pusher **535b** to plunger pusher **535a**. If reservoir **536** is not filled to capacity, plunger **535b** will be positioned at some unknown point within reservoir **536** until plunger zeroing is complete. Once the user has introduced medicament into reservoir **536**, plunger zeroing is user-initiated or may be an automatic aspect of pump operation (e.g., when disposable assembly **500** is attached to a durable assembly). When the pusher-zeroing procedure is initiated, the motor advances plunger pusher **535a** until it contacts pusher **535b**, and they lock together with plunger hooks **537**, or other suitable method of attachment, as described earlier. Reservoir **536** and plunger **535b** may be made of cyclic olefin polymer (COP), polypropylene or other drug-compatible polymeric material. Suitable materials for the plunger pusher **535a** include, but are not limited to, stainless steel, COP, nylon, and polycarbonate.

(87) As described earlier, the zeroing procedure is performed when flow from cartridge **536** is blocked by PBUP **517**. Given there may be tolerances associated with cartridge manufacture and variation in medicament filling, the distance that plunger pusher **535a** must travel, from its initial home position, before it engages plunger **535b** and begins to drive medicament out of the reservoir, may vary. Under microprocessor control, the motor advances plunger pusher **535a** into engagement with plunger **535b**, causing increased fluid path pressure. The Hall-effect sensors **225b**, an encoder, or other monitoring/sensing device is sampled to determine when a motor stall occurs as pusher **535a** is advanced. Lack of signals from the Hall-effect sensors **225** evidences that the motor is not turning. The motor stall is presumed to be due to hydraulic lock and, therefore, indicative of plunger pusher **535a** engaging the plunger **535b** of a plugged cartridge **536**. As described in detail in aforementioned U.S. Pat. No. 8,777,901, the procedure may employ two or more speeds for advancing the pusher. Also, pusher **535a** may be advanced at a controlled torque, or limited force, so that the motor will stall with the least amount of force possible for reliable results, in order to reduce the load on the system (e.g., the bearings and the battery). As stated above, knowing the distance plunger pusher **535a** traveled before engaging plunger **535b** allows calculations of medicament volume and estimated time until disposable assembly **500** replacement will be required.

(88) Insertion mechanism **600** is a 4-state system. FIGS. **10A-10H** show insertion mechanism **600** in its first state: the cocked position, before the patient removes PBUP **517** (FIG. **10H**) and pushes cannula trigger button **520** (FIG. **10G**) to insert the cannula. In this state, PBUP **517** is positioned to occlude the fluid path from the reservoir **536** (FIG. **10G**) and cannula carrier **612** is held up above and spaced apart from cannula seal **630** (FIG. **10H**), as described further below. In this state, and as best seen in FIG. **10G**, the plunger-pusher zeroing procedure described above can advance the pusher **535a** into contact with the plunger **535b**, slightly pressurizing the reservoir **536**, without injecting medicament into the patient. As best seen in FIG. **10H**, seal is formed between seal rings **631** and the outer surface of PBUP **517**, allowing the pressures required for the plunger-pusher zeroing procedure.

(89) To prevent accidental depression of cannula trigger button **520**, a button guard may be inserted between button **520** and the housing of disposable assembly **500**. For instance, as best seen in FIGS. **10A** and **10B**, PBUP **517** may include a trigger button guard **518** that curves up from the underside of infusion system **100b** through an opening in adhesive pad **501**, and fits under cannula trigger button **520**. With button guard **518** in place, it is not possible to depress trigger button **520** to initiate cannula insertion. PBUP **517** may be made of COP, polypropylene or other similar drug-compatible material. Button guard **518** may be made of the same material as PBUP **517** (and they may be one piece), or it may be made of a different material, such as polycarbonate.

(90) Turning now to FIGS. **11A-11D**, exemplary disposable assembly **500** includes baseplate **550**, reservoir outlet fitting **548**, and insertion mechanism **600**, shown with cannula trigger button **520** and trigger link **547** removed for clarity. As can be seen from these and the earlier figures, infusion system **100b** (and all infusion systems shown in the figures) is extremely compact, limiting available spring energy and the volume available for the fluid interconnect between the cannula and reservoir. That fluid connection must be extremely reliable and created with little energy. Thus, the insertion mechanism **600** must be extremely efficient and reliable.

(91) FIGS. **11A-11D** show insertion mechanism **600** in its second state: PBUP **517** has been removed and insertion mechanism **600** is ready to fire. The fluid path from reservoir **536** (FIG. **10G**) is open to the atmosphere, and any residual pressure is vented before cannula insertion.

(92) In simple terms, after removal of PBUP **517**, when the patient pushes cannula trigger button **520**, insertion mechanism **600** first causes trocar **647** and cannula **641** (best seen in FIG. **11D**) to project out of disposable assembly **500** (that is state three, shown in FIGS. **12A** and **12B**), and then causes trocar **647** to retract back into insertion mechanism **600**, leaving cannula **641** in place (which is state four, shown in FIGS. **13A-13D**). Trocar **647**, which includes an elongate rod with a sharp distal tip, may be made of metal, such as stainless steel, or other relatively rigid biocompatible material, such as rigid plastic, ceramic, or other rigid biocompatible material, and is used to penetrate the skin and a short distance into the flesh, to make a channel for cannula **641**. Cannula **641** may be made of polytetrafluoroethylene (PTFE), such as TEFLON® PTFE, or other biocompatible polymeric material. The components involved and details of how insertion mechanism **600** performs these actions are described in more detail below.

(93) As best seen in FIG. **11A**, insertion mechanism **600** includes main insertion spring **610** and cannula carrier **612**, which is supported on guide housing **620**. Referring also to FIGS. **11B-11D**, insertion mechanism **600** also includes trocar carrier **674**, trocar seal **680**, trocar retraction spring **682**, cannula seal **630**, and cannula seal retainer **634**. As described further below, these components provide a highly efficient cannula seal with low cannula insertion forces and a highly reliable medicament seal.

(94) FIG. **11B** shows insertion mechanism **600** with main insertion spring **610** and guide housing **620** removed. In FIG. **11C**, main insertion spring **610** is removed and guide housing **620** is semi-transparent. FIG. **11D** is a section view of the components of FIG. **11C**. Main insertion spring **610** may provide travel of about 7 mm with a starting force of about 15 newtons (N) and an ending force of about 7 N, and may be made of, for instance, 0.75 mm diameter music wire, with 6 turns and an outside dimension of 13.25 mm. Trocar retraction spring **682** may provide travel of about 7 mm with a starting force of about 4 N and an ending force of about 1 N, and may be made of, for instance, 0.5 mm diameter music wire, with 6 turns and an outside dimension of 3 mm. Guide housing **620** and cannula seal retainer **634** may be made of high strength plastic, such as nylon, acetal (Delrin®) or polycarbonate. Cannula carrier **612** and trocar carrier **674** may be made of COP, polypropylene or other similar drug-compatible material. Trocar seal **680** and cannula seal **630** may be made of elastomer, rubber, such as silicone rubber or bromobutyl rubber, or other relatively conformable sealing material that is also drug-compatible.

(95) As mentioned above, FIGS. **11A-11D** show insertion mechanism **600** in state two, the cocked position, before the patient pushes cannula trigger button **520** to cause cannula carrier **612** to drive

cannula **641** into an inserted position. Before insertion, cannula carrier **612** is supported on support ledge **622** of guide housing **620** (best seen in FIG. **11D**), which in turn holds main insertion spring **610** in a compressed state. Note that guide housing **620** does not move during cannula insertion. (96) When the user presses cannula trigger button **520**, it pushes on trigger link **547**, causing trigger link **547** to rotate. When trigger link **547** rotates, it pushes cannula carrier **612** counter-clockwise, causing cannula carrier **612** to slide off support ledge **622** of guide housing **620**, and carrier tabs **613** to align with guide housing slots **624** (shown in FIGS. **11A** and **11C**). Once cannula carrier **612** is no longer supported by guide housing ledge **622**, cannula carrier **612** can no longer resist the force of main insertion spring **610**, and the elastic energy contained in main insertion spring **610** is converted to motion. Main insertion spring **610** then drives cannula carrier **612** with attached cannula **641**, trocar carrier **674** with attached trocar **647**, trocar seal **680**, and trocar retraction spring **682** downward. As these components move downward, the sharp distal tip of trocar **647**, which extends slightly beyond the distal end of cannula **641**, penetrates the patient's skin, and cannula **641**, which surrounds trocar **647**, is inserted so the end of cannula **641** is about 6 mm below the surface of the patient's skin. At this point, insertion mechanism **600** in state three, as seen in FIGS. **12A** and **12B**.

(97) As best seen in FIGS. **11B**, **12B** and **13B**, cannula carrier **612** and trocar carrier **674** include features to lock them together before and during cannula insertion. Trocar carrier **674** includes locking ledges **675** that fit beneath locking bosses **615** on cannula carrier **612**. When cannula carrier **612** and trocar carrier **674** are locked together, trocar retraction spring **682** is held in a compressed state. In addition, trocar carrier **674** includes locking ledge walls **677** that contact locking boss walls **617** on cannula carrier **612**. These walls ensure that trocar carrier **674** moves only counter-clockwise together with cannula carrier **612**, so trocar carrier's locking ledges **675** cannot accidentally slide out from under cannula carrier's locking bosses **615** and unintentionally trigger penetration of trocar **647**.

(98) Once cannula carrier **612** and trocar carrier **674** are rotated to begin cannula insertion, and begin to move downward toward the patient, the angled edge **679** of trocar carrier tabs **678** contact corners **635** on seal retainer **634**. As trocar carrier **674** moves downward, the contact between corners **635** and angled edges **679** causes trocar carrier **674** to rotate further and further counter-clockwise during cannula insertion. As cannula carrier **612** moves downward, carrier tabs **613** are positioned within guide housing slots **624** (shown in FIGS. **11A** and **11C**), allowing cannula carrier **612** to slide downward while preventing additional rotation of cannula carrier **612**. As trocar carrier **674** rotates further counter-clockwise, trocar carrier's locking ledges **675** slide out from under cannula carrier's locking bosses **615**.

(99) FIGS. **12A** and **12B** show insertion mechanism **600** in state three: FIG. **12A** shows main insertion spring **610** fully fired, cannula carrier **612** fully down, and cannula **641** fully inserted, at the instant trocar carrier **674** is released and before trocar retraction spring **682** drives trocar carrier **674** and trocar **647** upward. (As shown, the skin is pierced at about 90 degrees and the end of the cannula is positioned about 6 mm below the surface of the skin.) FIG. **12B** shows the same instant, with main insertion spring **610** and guide housing **620** removed. This view shows the moment trocar carrier's locking ledges **675** are released from under cannula carrier's locking bosses **615**.

(100) Once trocar carrier's locking ledges **675** are released from under cannula carrier's locking bosses **615** (this is also the moment that cannula **641** is fully inserted, and insertion mechanism **600** in state three, as seen in FIGS. **12A** and **12B**), trocar carrier **674** can no longer resist the force of trocar retraction spring **682**. The elastic energy contained in trocar retraction spring **682** is converted to motion, and trocar retraction spring **682** drives trocar carrier **674** with attached trocar **647** upward. As trocar carrier **674** moves upward, trocar **647** is removed from the patient and retracted back into insertion mechanism **600**, leaving cannula **641** inserted. This is state four, as seen in FIGS. **13A-13D**.

(101) FIG. **13A** is a section view showing insertion mechanism **600** fully fired and trocar **647** fully

retracted. FIG. 13B shows more details of the fully fired insertion mechanism **600**, with main insertion spring **610** and guide housing **620** removed. This is the position of the components of insertion mechanism **600** while exemplary ambulatory infusion system **100b** is in use by the patient. The medicament path is best seen in FIGS. **13A** and **13C**. Broadly stated, medicament flows from the reservoir (not shown), to outlet fitting **548**, into cannula seal **630**, through channel **614** in cannula carrier **612**, through trocar seal **680**, and into cannula **641** for delivery to the patient. (102) Best seen in FIGS. **13C** and **13D** is the highly efficient radial compression hydraulic seal formed between cannula carrier **612** and upper and lower seal rings **631** of cannula seal **630**. Upper and lower seal rings **631** are separated by about 2.5 mm. Tapering of cannula seal **630** to the small contact areas of seal rings **631** concentrates surface stresses where the seal rings **631** contact cannula carrier **612**, to provide a good seal. Additional upper and lower seal rings are possible, but could increase space requirements. To enhance the seal at seal rings **631**, main insertion spring **610** exerts force on cannula carrier **612**, holding it down against baseplate **550** and causing cannula carrier internal surface **616** to push on the top surface of cannula seal **630**, as described in more detail below.

(103) During the transition from state two to state three of insertion, cannula carrier internal surface **616** begins contacting the top of cannula seal **630** before the bottom surface of cannula carrier **612** contacts baseplate **550**. When state three is reached, the bottom surface of cannula carrier **612** is held against baseplate **550** and cannula seal **630** is compressed from above. High-energy main insertion spring **610** improves sealing reliability, and cannula seal **630** acts as a bumper as it is compressed, helping dissipate the energy of insertion. Rather than being wasted, or converted to user-perceptible noise and feeling, residual energy from firing of main insertion spring **610** is converted from kinetic energy to enhanced radial compression of cannula seal **630**.

(104) In addition, the contact between cannula carrier internal surface **616** and the top surface of cannula seal **630** forms a secondary face seal. In state three, main insertion spring **610** continues pushing down on cannula carrier **612**, with approximately 7-10 N of force. This force, spread over the top surface of cannula seal **630**, results in a fluid seal capable of sealing approximately 3 bar, in addition to the seal maintained at the upper seal ring **631**.

(105) To further enhance this seal, seal retainer **634** provides radial support, acting as a fixed backing ring/clamp, increasing the radial compression around cannula seal **630**. Even further enhancing the seal, cannula carrier **612** provides additional radial compression with clamping force on cannula seal **630**, acting as an additional backing ring/clamp. The 7-10 N residual force derived from main insertion spring **610** results in downward (axial) compression on cannula seal **630**, causing radial deformation of cannula seal **630**, further improving the seal formed between cannula carrier **612** and seal rings **631**. In state three, since cannula seal **630** is radially constrained by seal retainer **634** and cannula carrier **612**, axial compression of cannula seal **630** causes radial deformation of seal **630**, increasing the sealing force on sealing rings **631**. All of this results in a highly efficient and reliable hydraulic cannula seal.

(106) Turning now to FIG. **13C**, the medicament path also includes a compression-type fitting **690** formed from clamp-portion **636** of seal retainer **634** clamping ferrule **632** of cannula seal **630** down onto barb **549** of outlet fitting **548**. As an alternative, a separate component can be utilized to deliver the clamping forces provided by clamp-portion **636** of seal retainer **634**. In addition, ferrule **632** of cannula seal **630** and barb **549** of outlet fitting **548** can be separate ferrule and barb components, but would introduce additional component interfaces along the medicament path, each requiring additional sealing features. In the configuration shown, cannula seal **630** seals cannula **641**, absorbs energy during firing by compressing when struck by cannula carrier **612**, and helps seal the reservoir with ferrule **632**.

(107) As best seen in FIG. **13D**, medicament next flows through ferrule **632**, through cannula seal **630**, through channel **614** in cannula carrier **612**, through trocar seal inlet **681**, through trocar seal channel **683**, and through cannula **641** for delivery to the patient. As can be seen from comparing

FIGS. 11D, 12A, and 13A, trocar seal **680** remains in one position within cannula carrier **612** before, during, and after the insertion process, and remains in that position during patient use of exemplary ambulatory infusion system **100b**. Trocar seal **680** includes sidewall seal rings **684** and base seal rings **686**. Sidewall seal rings **684** prevent medicament leakage into cannula carrier **612** and, ultimately, into exemplary ambulatory infusion system **100b**. Base seal rings **686** prevent leakage from around cannula **641**, and ensure that medicament flowing from trocar seal inlet **681** and through trocar seal channel **683** is directed into cannula **641**. FIG. 13D shows a pair of sidewall seal rings **684** and a pair of base seal rings **686**, but additional seals may be used for additional leak protection.

(108) Insertion mechanism **600** provides a highly efficient, highly reliable medicament seal with low insertion forces, all in a compact space. The energy supplied to insert cannula **641** is provided by main insertion spring **610**, and needs to be sufficient to (a) allow trocar **647** to quickly and cleanly pierce the patient's skin for cannula insertion, (b) overcome friction forces during movement of cannula carrier **612** surfaces against cannula seal **630** surfaces and seal retainer **634** surfaces, and (c) result in compression and radial forces making a reliable medicament seal. Excess energy is absorbed by compression of cannula seal **630**, which radially expands cannula seal **630**, increasing the radial forces exerted by seal rings **631** against the surface of cannula carrier **612** and exerted by cannula seal **630** against seal retainer **634**, as explained in more detail below. Energy requirements and expenditures are also described in more detail presently.

(109) During operation, as insertion mechanism **600** transitions from state two to state three, the radial compression forces exerted on cannula seal **630** increase. As cannula carrier **612** begins moving downward, it first contacts upper cannula seal ring **631**, and, generally, begins to capture and surround cannula seal **630** between the surfaces of cannula carrier **612** and seal retainer **634**. Seal retainer **634** acts as a fixed backing ring, providing radial support for cannula seal **630**, contributing to the radial clamping forces applied to cannula seal **630**. However, in some alternatives, there may be a small gap between seal retainer **634** and cannula seal **630** until cannula seal **630** is compressed downward and expanded radially, as explained momentarily. The radial forces applied to cannula seal **630** increase as cannula carrier **612** continues moving downward, since the amount of contact, and therefore radial force, continues increasing between (i) the surfaces of cannula carrier **612** and cannula seal rings **631**, (ii) seal retainer **634** and cannula seal **630**, and (iii) in some alternatives, the surfaces of cannula carrier **612** and seal retainer **634**. Contact between cannula carrier **612** and seal rings **631** during transition from state two to state three is also described in more detail below, in relation to the next embodiment.

(110) As cannula carrier **612** continues moving downward, contact is made between the top surface of cannula seal **630** and carrier internal surface **616** (see FIGS. 11D and 13D). As explained above, this initial contact occurs while cannula carrier **612** is still moving downward. Therefore, as cannula carrier **612** continues moving downward, carrier internal surface **616** exerts increasing downward force on cannula seal **630**, and as it does, cannula seal **630** is increasingly compressed as cannula carrier **612** continues moving. As carrier internal surface **616** pushes more and more on cannula seal **630** from above, cannula seal **630** expands more and more radially, resulting in additional radial compression forces between (i) seal rings **631** and cannula carrier **612** and (ii) cannula seal **630** and seal retainer **634**. Cannula seal **630** may ultimately radially expand by, for instance, 0.5 mm. (In alternatives where there was a small gap between seal retainer **634** and cannula seal **630**, this gap decreases until it is eliminated as cannula seal **630** expands radial due to downward compression of cannula seal **630** by carrier internal surface **616**.) In addition, as described above, contact between cannula carrier internal surface **616** and the top surface of cannula seal **630** forms a secondary face seal. As such, a highly efficient and highly reliable cannula seal is achieved by (1) this face seal formed at cannula carrier internal surface **616** and the top surface of cannula seal **630**, (2) contact between seal rings **631** and cannula carrier **612**, (3) radial clamping forces exerted on cannula seal **630** by seal retainer **634**, (4) increased radial

clamping forces exerted by cannula carrier **612**, acting as an additional backing ring (in addition to seal retainer **634**) and providing increased radial compression of cannula seal **630**, and (5) downward force exerted on the top of cannula seal **630** by cannula carrier **612** at cannula carrier internal surface **616**, which expands cannula seal **630** radially and increases the radial forces exerted (a) by seal rings **631** against the surface of cannula carrier **612** and (b) by cannula seal **630** against seal retainer **634**.

(111) Another exemplary embodiment of an insertion mechanism **600a** for a disposable assembly of an ambulatory infusion system is shown in FIGS. **14A-14F**. This embodiment uses a moveable backing structure (part of cannula carrier **612a**) that engages cannula seal **630a** in state three, whereas the above embodiment uses a fixed backing ring (seal retainer **634**) in addition to a moveable backing structure (part of cannula carrier **612**). As described further below, this embodiment also provides a highly efficient radial compression seal with low cannula insertion forces and a highly reliable medicament seal.

(112) As above, the energy supplied to insert cannula **641a** is provided by a main insertion spring **610a** (see FIGS. **14B** and **14F**), and needs to be sufficient to (a) allow trocar **647a** to quickly and cleanly pierce the patient's skin for cannula insertion, (b) overcome friction forces during movement of cannula carrier **612a** surfaces against cannula seal **630a** surfaces, and (c) result in compression and radial forces making a reliable medicament seal. As above, excess energy is absorbed by compression of cannula seal **630a**, which radially expands cannula seal **630a**, increasing the radial forces exerted by seal rings **631a** against cannula carrier **612a** and exerted by cannula seal **630a** against the angled surface of cannula carrier **612a**, as explained in more detail below. As such and as above, rather than being wasted, or converted to user-perceptible noise and feeling, residual energy from firing of main insertion spring **610a** is converted from kinetic energy to enhanced radial compression by cannula seal **630a**.

(113) FIG. **14A** is a section view certain components and features of insertion mechanism **600a** shown in state one, before firing, and before pull-before-use plug, PBUP **517a**, is removed. FIG. **14B** is a section view of insertion mechanism **600a** in state two, after PBUP **517a** is removed but before firing of insertion mechanism **600a**. FIGS. **14C** and **14D** are section views of certain components and features of FIG. **14B**, shown during transition from state two to state three, as cannula **641a** is being inserted. These views show details of cannula carrier **612a** interaction with cannula seal **630a** using a moveable backing structure. FIG. **14E** is a section view of certain components and features of FIG. **14B**, shown in state three, once cannula **641a** is inserted but before trocar **647a** is retracted. FIG. **14F** is a closeup section view showing cannula carrier **612a**, cannula seal **630a**, and trocar seal **680a** in state four, after firing of insertion mechanism **600a**, cannula **641a** insertion, and trocar **647a** retraction. Some details of insertion mechanism **600a** are omitted to simplify the views in FIGS. **14A-14F**. For instance, insertion mechanism **600a** may use a locking mechanism for cannula carrier **612a** and trocar carrier **674a** like that used by insertion mechanism **600**, but those detailed features are not shown in FIGS. **14A-14F**. Similarly, insertion mechanism **600a** may use a cannula trigger button and trigger link like those used by insertion mechanism **600**, and trocar seal **680a** may include seal rings like those on trocar seal **680**. Materials used for the components of insertion mechanism **600a** may be similar to those described above for insertion mechanism **600**.

(114) FIGS. **14A** and **14B** show cannula carrier **612a** supported on guide housing **620a**, trocar **647a**, trocar carrier **674a**, trocar seal **680a**, trocar retraction spring **682a**, cannula seal **630a**, seal rings **631a**, and cannula **641a**. FIG. **14A** also shows PBUP **517a**, and FIG. **14B** also shows main insertion spring **610a**. In this embodiment and as best seen in FIG. **14B**, guide housing slots **624a** include one or more tapers **624b** that engage features on trocar carrier **674a**, causing trocar carrier **674a** to rotate further than cannula carrier **612a**, so trocar carrier **674a** disengages from cannula carrier **612a**, allowing trocar retraction spring **682a** to retract trocar into insertion mechanism **600a** after cannula insertion.

(115) In this embodiment, insertion mechanism **600a** provides a cannula seal **630a** that is radially unsupported before firing, because there is no cannula seal retainer. Instead, cannula carrier **612a** provides all the radial compression forces in this embodiment. In other words, the previous embodiment uses a fixed backing ring (seal retainer **634**), whereas this embodiment uses a moveable backing structure (part of cannula carrier **612a**) that engages cannula seal **630a** during transition from state two to state three, and remains engaged in state four. Insertion mechanism **600a** still provides a highly efficient radial compression seal with low cannula insertion forces and a highly reliable medicament seal. That is, the radial compression forces exerted on seal **630a** result in a reliable medicament seal following the insertion operation.

(116) FIGS. **14C-14F** show details of cannula carrier **612a** interaction with cannula seal **630a** in this embodiment that uses a moveable backing structure (part of cannula carrier **612a**). FIG. **14C** shows insertion mechanism **600a** beginning to transition from state two to state three. As cannula carrier **612a** begins traveling downwards, it first contacts upper seal ring **631a** of cannula seal **630a** and begins to capture and surround cannula seal **630a** between the surfaces of cannula carrier **612a**. FIG. **14D** shows cannula carrier **612a** after it has radially expanded upper seal ring **631a** and is beginning to contact lower seal ring **631a**. Upper and lower seal rings **631a** are separated by about 2.5 mm. FIG. **14E** shows insertion mechanism **600a** in state three, with cannula **641a** inserted but before trocar **647a** retraction. In this state, and in state four, the initially expanded cannula seal **630a** is in contact with the moveable backing structure of cannula carrier **612a**, and has forced upper seal ring **631a** into tight contact with cannula carrier **612a**. The cannula carrier **612a** has an angled inwardly facing surface (i.e., a surface that is not parallel or perpendicular to the downward movement direction, such as a frusto-conical surface) and the cannula seal **630a** has an angled outwardly facing surface (i.e., a surface that is not parallel or perpendicular to the downward movement direction, such as a frusto-conical surface). The radial forces applied to cannula seal **630a** increase as cannula carrier **612a** moves downward, since the amount of contact, and therefore radial force, increases between (i) the vertical surface of cannula carrier **612a** and cannula seal rings **631a** and (ii) the angled surfaces of cannula carrier **612a** and cannula seal **630a**. A similar concept applies to the previous embodiment, where the amount of contact, and therefore radial force, increases, as cannula carrier **612** moves from state two to state four, between (i) the vertical surface of cannula carrier **612** and cannula seal rings **631** and (ii) cannula seal **630** and both seal retainer **634** and cannula carrier **612**.

(117) Also similar to the embodiment directly above, as cannula carrier **612** continues moving downward, contact is made between the top surface of cannula seal **630a** and carrier internal surface **616a** (see FIGS. **14A** and **14B**). This initial contact occurs while cannula carrier **612a** is still moving downward. Therefore, as cannula carrier **612a** continues moving downward, carrier internal surface **616a** exerts increasing downward force on cannula seal **630a**, and as it does, cannula seal **630a** is increasingly compressed as cannula carrier **612a** continues moving. As described above, this contact between cannula carrier internal surface **616a** and the top surface of cannula seal **630a** forms a secondary face seal. Also, as carrier internal surface **616a** pushes more and more on cannula seal **630a** from above, cannula seal **630a** expands more and more radially, resulting in additional radial compression forces between (i) seal rings **631a** and cannula carrier **612a** and (ii) cannula seal **630a** and the angled surface of cannula carrier **612a**. Cannula seal **630a** may ultimately radially expand by, for instance, 0.5 mm.

(118) As such, a highly efficient and highly reliable cannula seal is achieved by (1) the face seal formed at cannula carrier internal surface **616a** and the top surface of cannula seal **630a**, (2) contact between seal rings **631a** and cannula carrier **612a**, (3) radial clamping forces exerted by cannula carrier **612a**, acting as a moveable backing ring and providing radial compression of cannula seal **630a**, and (4) downward force exerted on the top of cannula seal **630a** by cannula carrier **612a** at cannula carrier internal surface **616a**, which expands cannula seal **630a** radially and increases the radial forces exerted (a) by seal rings **631a** against cannula carrier **612a** and (b) by cannula seal

630a against the angled surface of cannula carrier **612a**. This allows lower insertion forces for insertion of cannula carrier **612a**, cannula **641a**, trocar seal **680a**, and trocar **647a** into cannula seal **630a** during firing, while the clamping action of cannula carrier **612a** generates large radial forces on cannula seal **630a**, maintaining a highly reliable hydraulic seal for leak-free operation. The minimized insertion forces may further allow minimizing of main insertion spring **610a** size.

(119) The energy required to transition the above insertion mechanisms between states will now be described. This explanation applies to insertion mechanism **600** and insertion mechanism **600a**.

(120) The energy required to transition from state one to state two is supplied by the user physically removing PBUP **517/517a**. The energy required to transition insertion mechanism **600/600a** from state two to state three is supplied by main insertion spring **610/610a**. This energy is composed mainly of skin piercing energy and seal insertion energy, and secondarily of mechanism friction, compression of cannula seal **630/630a**, and triggering of trocar retraction. The energy to transition from state three to state four is supplied by trocar retraction spring **682/682a**. This discussion focuses on the transition from state two to state three, when the cannula is inserted and sealing of the medicament path is accomplished.

(121) Skin piercing energy was modeled, based on the forces required to pierce the skin and move the cannula to the correct insertion depth. As mentioned earlier, the tip (distal end) of cannula **641/641a** is inserted to a depth of about 6 mm. Skin piercing force begins at 0 N, rises to a maximum of approximately 5 N when the tip is about 2 mm subcutaneous, then drops to approximately 3 N when the tip reaches its final 6 mm position. This results in approximately 21 N-mm energy for skin piercing.

(122) Seal insertion energy should be minimized. In the two embodiments directly above, the sealing surface of cannula carrier **612/612a** has a diameter of about 5 mm, and requires cannula seals spaced approximately 2.5 mm apart. This means upper seal ring **631/631a** engages cannula carrier **612/612a** when cannula carrier **612/612a** still has about 3.5 mm to travel before cannula **641/641a** reaches state three (about 6 mm below the surface of the patient's skin) and lower seal ring **631/631a** engages cannula carrier **612/612a** about 1.0 mm before cannula **641/641a** reaches state three.

(123) Effective seal design requires the seal contact stress to be at least the pressure of the fluid to be sealed. As an example, if maximum medicament fluid pressure is 3 bar (gauge), and seal rings **631/631a** have a contact width of about 1 mm each (and diameter of about 5 mm, as stated above), this results in a seal radial force of about 4.8 N minimum each for the upper and lower seals. Factoring in design margins/tolerances and an assumed coefficient of friction of 0.8 for elastomers on plastics, this results in a calculated design insertion force of approximately 5 N for each seal ring **631/631a**. From an energy view, this represents about 17.5 N-mm (3.5 mm×5 N) for upper seal ring **631/631a** and 5 N-mm (1 mm×5 N) for lower seal ring **631/631a** for the transition between state two and state three.

(124) The mechanisms of insertion mechanism **600/600a** are linear, with low friction losses. In the example given earlier, the main insertion spring provides 77 N-mm total energy. Given about 21 N-mm for skin piercing energy, about 17.5 N-mm for upper seal ring seal insertion energy, and about 5 N-mm for lower seal ring insertion energy, totaling about 43.5 N-mm, this leaves about 33.5 N-mm for friction, compression of cannula seal **630/630a**, and for triggering the trocar retraction mechanism. This amount of reserve energy may not be necessary, so less spring force may be sufficient. The insertion mechanisms proposed herein are energy-efficient, as well as highly reliable, compact, inexpensive, and user-friendly.

(125) Various methodologies and systems are presented here in the context of the exemplary structures described in the preceding sections, and illustrated in the various figures, for the purpose of explanation only. Although the present methodologies and systems may employ the structures described above, they are not limited thereto. Additionally, embodiments of the present inventions may incorporate any one, combinations of less than all, or all of the methodologies or devices

referenced above.

(126) Although the inventions disclosed herein have been described in terms of the preferred embodiments above, numerous modifications and/or additions to the above-described preferred embodiments would be readily apparent to one skilled in the art. By way of example, but not limitation, the present inserter and sealing assemblies may be incorporated into fully disposable infusion pumps. It is intended that the scope of the present inventions extends to all such modifications and/or additions and that the scope of the present inventions is limited solely by the claims set forth below or later added.

(127) Finally, with respect to terminology that may be used herein, whether in the description or the claims, the following should be noted. The terms “comprising,” “including,” “carrying,” “having,” “containing,” “involving,” and the like are open-ended and mean “including but not limited to.” Ordinal terms such as “first,” “second,” “third,” do not, in and of themselves, connote any priority, precedence, or order of one element over another or temporal order in which steps of a method are performed. Instead, such terms are merely labels to distinguish one element having a certain name from another element having a same name (but for the ordinal term) to distinguish the elements. “And/or” means that the listed items are alternatives, but the alternatives also include any combination of the listed items. The terms “approximately,” “about,” “substantially” and “generally” allow for a certain amount of variation from any exact dimensions, measurements, and arrangements, and should be understood within the context of the description and operation of the invention as disclosed herein. Terms such as “top,” “bottom,” “upper,” “lower,” “above,” and “below” are terms of convenience that denote the spatial relationships of parts relative to each other rather than to any specific spatial or gravitational orientation. Thus, the terms are intended to encompass an assembly of component parts regardless of whether the assembly is oriented in the particular orientation shown in the drawings and described in the specification, upside down from that orientation, or any other rotational variation therefrom.

Claims

1. A cannula insertion mechanism, comprising: a seal configured to surround an opening of a housing, the seal including a first seal surface and a second seal surface, the first seal surface facing toward the opening, and the second seal surface facing away from the opening; and a cannula; a cannula carrier surrounding at least a portion of the cannula and configured to drive the cannula in a first direction through the opening of the housing, the cannula carrier having a first carrier surface and a second carrier surface, the first carrier surface being configured to exert a compression force on the second seal surface when the cannula carrier drives the cannula in the first direction, thereby causing the first seal surface to expand in a second direction to engage the second carrier surface such that, when the cannula carrier is seated within the housing with the cannula in an inserted position, the cannula carrier radially compresses the seal.
2. The cannula insertion mechanism of claim 1, wherein the first seal surface comprises one or more seal rings.
3. The cannula insertion mechanism of claim 1, wherein the first seal surface is substantially perpendicular to the second seal surface, and wherein the first direction is substantially perpendicular to the second direction.
4. The cannula insertion mechanism of claim 1, further comprising a seal retainer configured to exert a clamping force on the seal at a third seal surface that is opposite the first seal surface.
5. The cannula insertion mechanism of claim 1, wherein the cannula carrier includes a third carrier surface configured to exert a clamping force on the seal at a third seal surface.
6. The cannula insertion mechanism of claim 5, wherein the third carrier surface and the third seal surface are angled surfaces configured to engage each other.
7. The cannula insertion mechanism of claim 1, further comprising a trocar carrier configured to be

coupled to the cannula carrier until the cannula is driven through the opening of the housing.

8. The cannula insertion mechanism of claim 7, further comprising: a trocar retraction spring that is held in a compressed state between the trocar carrier and the cannula carrier when the trocar carrier is coupled to the cannula carrier.

9. The cannula insertion mechanism of claim 8, wherein the trocar carrier is configured to decouple from the cannula carrier based on rotation relative to the cannula carrier, the rotation allowing the trocar retraction spring to drive the trocar carrier in a third direction opposite the first direction.

10. The cannula insertion mechanism of claim 9, wherein the rotation is caused by an angled surface of the trocar carrier engaging a fixed surface as the cannula is driven in the first direction.

11. A fluid delivery device comprising: a housing; a cannula; and a cannula insertion mechanism comprising: a seal configured to surround an opening of the housing, the seal including a first seal surface and a second seal surface, the first seal surface facing toward the opening, and the second seal surface facing away from the opening; and a cannula carrier surrounding at least a portion of the cannula and configured to drive the cannula in a first direction through the opening of the housing, the cannula carrier having a first carrier surface and a second carrier surface, the first carrier surface being configured to exert a compression force on the second seal surface when the cannula carrier drives the cannula in the first direction, thereby causing the first seal surface to expand in a second direction to engage the second carrier surface, such that, when the cannula carrier is seated within the housing with the cannula in an inserted position, the cannula carrier radially compresses the seal.

12. The fluid delivery device of claim 11, wherein the first seal surface comprises one or more seal rings.

13. The fluid delivery device of claim 11, wherein the first seal surface is substantially perpendicular to the second seal surface, and wherein the first direction is substantially perpendicular to the second direction.

14. The fluid delivery device of claim 11, further comprising a seal retainer configured to exert a clamping force on the seal at a third seal surface that is opposite the first seal surface.

15. The fluid delivery device of claim 11, wherein the cannula carrier includes a third carrier surface configured to exert a clamping force on the seal at a third seal surface.

16. The fluid delivery device of claim 15, wherein the third carrier surface and the third seal surface are angled surfaces configured to engage each other.

17. The fluid delivery device of claim 11, further comprising a trocar carrier configured to be coupled to the cannula carrier until the cannula is driven through the opening of the housing.

18. The fluid delivery device of claim 17, further comprising: a trocar retraction spring that is held in a compressed state between the trocar carrier and the cannula carrier when the trocar carrier is coupled to the cannula carrier.

19. The fluid delivery device of claim 18, wherein the trocar carrier is configured to decouple from the cannula carrier based on rotation relative to the cannula carrier, the rotation allowing the trocar retraction spring to drive the trocar carrier in a third direction opposite the first direction.

20. The fluid delivery device of claim 19, wherein the rotation is caused by an angled surface of the trocar carrier engaging a fixed surface as the cannula is driven in the first direction.
