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### Laser level with internal adjustable platform

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#### Abstract

A laser level emits one or more planar lasers that can be self-leveled via one or more internal leveling systems. The motors bias a platform to rotate the laser emitters to a targeted orientation, such as via the motors collectively rotating the laser emitters in response to instructions to rotate with respect to one or more axes.

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## Background/Summary

CROSS-REFERENCE TO RELATED PATENT APPLICATION (1) The present application is a continuation of International Application No. PCT/US2022/082425, filed on Dec. 27, 2022, which claims the benefit of and priority to U.S. Provisional Application No. 63/294,612, filed on Dec. 29, 2021, which is incorporated herein by reference in its entirety.

## BACKGROUND OF THE INVENTION

(1) The present disclosure is directed generally to laser levels. The present disclosure relates specifically to point line plane laser levels.

## SUMMARY OF THE INVENTION

(2) One embodiment of the invention relates to a laser generating device including a housing, an arm pivotally coupled to the housing, a platform coupled to the arm, a first laser emitting device coupled to the platform, a second laser emitting device coupled to the platform, a first motor configured to exert a first force on the platform along a first axis, and a second motor configured to exert a second force on the platform along a second axis distinct from the first axis. The platform is configured to be rotated with respect to the housing about both a first rotational axis and a second rotational axis distinct from the first rotational axis. The first laser emitting device is operable to generate a first output beam along a first plane. The second laser emitting device is operable to generate a second output beam along a second plane. Both the first motor and the second motor are activated to exert force on the platform when the platform is rotated with respect to the housing about the first rotational axis, and both the first motor and the second motor are activated to exert force on the platform when the laser generating device rotates the platform with respect to the housing about the second rotational axis.

(3) Another embodiment of the invention relates to a laser generating device including a housing, an arm pivotally coupled to the housing, a platform coupled to the arm, a first laser emitting device coupled to the platform, a second laser emitting device coupled to the platform, and a first motor configured to exert a first force on the platform along a first axis. The platform is configured to be rotated with respect to the housing about both a first rotational axis and a second rotational axis distinct from the first rotational axis. The first laser emitting device is operable to generate a first output beam along a first plane. The second laser emitting device is operable to generate a second output beam along a second plane. The first motor is configured to exert a first force on the platform along a first axis. Rotating the platform with respect to the housing around the first rotational axis includes the first motor exerting a force on the platform in a first direction along the first axis, and rotating the platform with respect to the housing around the second rotational axis includes the first motor exerting a force on the platform in a second direction along the first axis opposite the first direction.

(4) Another embodiment of the invention relates to a laser generating device including a housing, an arm pivotally coupled to the housing, a base coupled to the arm such that the base rotates with respect to the housing about both a first rotational axis and a second rotational axis distinct from the first rotational axis, a platform coupled to the base, a first laser emitting device coupled to the platform, the first laser emitting device operable to generate a first output beam along a first plane, and a second laser emitting device, the second laser emitting device operable to generate a second output beam along a second plane. The base includes a first protrusion and a second protrusion. The platform is rotatable with respect to the base about a third rotational axis. The first rotational axis extends parallel to an X-axis in a Cartesian Coordinate System, the second rotational axis extends parallel to an Y-axis in the Cartesian Coordinate System, and the third rotational axis extends parallel to a Z-axis in the Cartesian Coordinate System. The platform includes an interior recessed surface and an opposing exterior recessed surface. When the platform is rotating with respect to the base about the first rotational axis the interior recessed surface interfaces with and moves with respect to the first protrusion and the exterior recessed surface interfaces with and moves with respect to the second protrusion.

(5) Another embodiment of the invention relates to a laser generating device. The laser generating device includes a housing, an arm pivotally coupled to the housing, and a platform coupled to the arm. The platform is configured to be rotated with respect to the housing about a first rotational axis and a second rotational axis perpendicular to the first rotational axis. The laser generating

device further includes a first laser emitting device coupled to the platform, the first laser emitting device operable to generate a first output beam along a first plane, and a second laser emitting device coupled to the platform, the second laser emitting device operable to generate a second output beam along a second plane. The laser generating device further includes a first motor configured to exert a first force on the platform along a third axis, and a second motor configured to exert a second force on the platform along a fourth axis distinct from the third axis. Rotating the platform with respect to the housing around the first rotational axis includes the first motor exerting a force on the platform in a first direction along the third axis and the second motor exerting a force on the platform in a second direction along the fourth axis. Rotating the platform with respect to the housing around the second rotational axis includes the first motor exerting a force on the platform in the first direction along the third axis and the second motor exerting a force on the platform in a third direction opposite the second direction.

(6) Another embodiment of the invention relates to a laser generating device. The laser generating device includes a housing, an arm pivotally coupled to the housing, a plate coupled to the arm, the plate including a first protrusion and a second protrusion. The laser generating device further includes a first laser emitting device, the first laser emitting device operable to generate a first output beam along a first plane, and a second laser emitting device, the second laser emitting device operable to generate a second output beam along a second plane. The laser generating device further includes a platform coupled to the plate, the first laser emitting device and the second laser emitting device. The platform is configured to be rotated with respect to the plate and the arm about a first rotational axis. The platform includes an interior surface and an opposing peripheral surface. The interior surface is configured to interface with the first protrusion and the peripheral surface is configured to interface with the second protrusion when the platform is rotating with respect to the plate about the first rotational axis.

(7) In various embodiments, the interior surface includes a first central recessed portion that extends along a length of the interior surface, and the peripheral surface includes a second central recessed portion that extends along a length of the peripheral surface.

(8) Additional features and advantages will be set forth in the detailed description which follows, and, in part, will be readily apparent to those skilled in the art from the description or recognized by practicing the embodiments as described in the written description included, as well as the appended drawings. It is to be understood that both the foregoing general description and the following detailed description are exemplary.

(9) The accompanying drawings are included to provide further understanding and are incorporated in and constitute a part of this specification. The drawings illustrate one or more embodiments and, together with the description, serve to explain principles and operation of the various embodiments.

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## Description

### BRIEF DESCRIPTION OF THE DRAWINGS

(1) This application will become more fully understood from the following detailed description, taken in conjunction with the accompanying figures, wherein like reference numerals refer to like elements in which:

(2) FIG. 1 is a perspective view of a laser level, according to an exemplary embodiment.

(3) FIG. 2 is a perspective view of an interior of the laser level of FIG. 1, according to an exemplary embodiment.

(4) FIG. 3 is a perspective view of an interior of the laser level of FIG. 1 from the opposite perspective of FIG. 2, according to an exemplary embodiment.

(5) FIG. 4 is a detailed perspective view of an interior of the laser level of FIG. 1, according to an exemplary embodiment.

(6) FIG. 5 is a front view of an interior of the laser level of FIG. 1, according to an exemplary embodiment.

(7) FIG. 6 is a side view of an interior of the laser level of FIG. 1, according to an exemplary embodiment.

(8) FIG. 7 is a top view of an interior of the laser level of FIG. 1, according to an exemplary embodiment.

(9) FIG. 8 is a top view of an interior of the laser level of FIG. 1, according to an exemplary embodiment.

(10) FIG. 9 is a detailed top view of an interior of the laser level of FIG. 1, according to an exemplary embodiment.

(11) FIG. 10 is a perspective view of the platform of the laser level of FIG. 1, according to an exemplary embodiment.

(12) FIG. 11 is a perspective view of the platform of the laser level of FIG. 1, according to an exemplary embodiment.

#### DETAILED DESCRIPTION

(13) Referring generally to the figures, a laser level is provided, such as a point line and plane laser level. As will generally be understood, laser level systems, including laser emitters and laser targets, are used to align objects or features in an area (e.g., such as holes along a wall, pipe, conduit, etc.).

(14) In various embodiments, the laser level described herein is configured to be precisely adjusted along two or more distinct axes. In one embodiment, the laser level includes a housing that emits one or more planar beams of light. The laser emitters are coupled to a platform, which is pivotally coupled to the housing. The platform is configured to be adjusted along multiple axes via two motors or more cooperatively rotating the platform with respect to the housing. Applicant has observed that the internal configuration described herein provides a more compact structure to provide a self-leveling laser level compared to other laser level internal configurations. In various embodiments, at least two motors rotate a platform coupled to laser emitters via such each motor affects orientation of the platform with respect to more than one axis, which is in contrast to laser levels where each motor is responsible for adjusting a single axis.

(15) Referring to FIGS. 1-4, a laser emitter and/or laser beam generating device, shown as laser level 110, is shown. Laser level 110 includes housing 120, an arm 121 pivotally coupled to the housing 120, a platform 122 coupled to the arm 121 (e.g., rigidly coupled to the arm 121), a first light generator coupled to platform 122, shown as laser emitter 112 that is operable to generate output beam 113 along plane 114, and a second laser light generator coupled to platform 122, shown as laser emitter 116 that is operable to generate output beam 117 along plane 118. In various embodiments, plane 114 is perpendicular to plane 118.

(16) Laser level 110 includes one or more orientation measuring devices, shown as electronic bubble vials. In various embodiments, laser level 110 includes electronic bubble vial 192, electronic bubble vial 194, and electronic bubble vial 196. Laser level 110 receives signals from electronic bubble vial 192, electronic bubble vial 194, and/or electronic bubble vial 196 and based on those signals laser level 110 orients laser emitter 112 and laser emitter 116 to a targeted orientation.

(17) Referring to FIG. 2, laser level 110 includes motor 186 that adjusts the orientation of laser emitter 112 and laser emitter 116. In particular, motor 186 exerts a force along axis 187 on platform 122 coupled to laser emitter 112 and laser emitter 116. In various embodiments, axis 183 is distinct from axis 187 (e.g., axis 183 and axis 187 are not aligned). In various embodiments, axis 183 and axis 187 are parallel to each other. As will be explained, motor 186 exerting a force along axis 187, such as in direction 188, rotates laser emitter 112 and laser emitter 116 with respect to housing 120.

(18) Referring to FIG. 3, laser level 110 is configured to rotate platform 122, laser emitter 112, and laser emitter 116 along one or more axes. In particular, laser level 110 is configured to rotate

platform **122** with respect to housing **120** about rotational axis **150**, rotational axis **160**, and rotational axis **170**. In various embodiments, laser emitter **112** and laser emitter **116** are coupled to arm **121** via platform **122** and arm **121** is pivotally coupled to housing **120**. The rotation of platform **122** to adjust laser emitter **112** and laser emitter **116** also rotates arm **121** with respect to housing **120**.

(19) Platform **122** is configured to be rotated with respect to the housing **120** about both rotational axis **150** and rotational axis **160**, which is distinct from rotational axis **150** (e.g., rotational axis **150** and rotational axis **160** are not aligned with each other). In various embodiments, rotational axis **150** and rotational axis **160** are not planar with respect to each other (e.g., rotational axis **150** and rotational axis **160** are skew with respect to each other; stated another way, no plane exists that encompasses each of rotational axis **150** and rotational axis **160**) and thus do not intersect.

(20) Referring to FIGS. 3-4, laser level **110** includes motor **182** (e.g., coupled to housing **120**) that adjusts the orientation of laser emitter **112** and laser emitter **116**. In particular, motor **182** exerts a force on platform **122** along axis **183**. As will be explained, motor **182** exerting a force along axis **183**, such as in direction **184**, rotates laser emitter **112** and laser emitter **116** with respect to housing **120**.

(21) In various embodiments, laser emitter **112** and laser emitter **116** are coupled to platform **122**, such as fixedly coupled. Platform **122** is coupled to base **126**, such as pivotally coupled to plate, and base **126** is coupled to arm **121** such that base **126** rotates with respect to housing **120** about both rotational axis **150** and rotational **160** axis distinct from rotational axis **150**. Motor **182** exerts a force on platform **122** via pins **185** of motor **182** exerting a force to pin **134** extending from base **126** (FIG. 4).

(22) In various embodiments, laser level **110** includes base **126**, the platform **122** coupled to the arm **121** via the base **126** (e.g., platform **122** is coupled to base **126**, and base **126** is coupled to arm **121**), and the base **126** and the platform **122** are collectively configured to be rotated with respect to the housing **120** about both rotational axis **150** and rotational axis **160**. The platform **122** rotates with respect to base **126** about rotational axis **170**. In various embodiments, rotational axis **150** extends parallel to an X-axis in a Cartesian Coordinate System, rotational axis **160** extends parallel to an Y-axis in the (same) Cartesian Coordinate System, and rotational axis **170** extends parallel to a Z-axis in the (same) Cartesian Coordinate System. Stated another way, in various embodiments, rotational axis **150** is perpendicular to rotational axis **160** when viewed along rotational axis **170**, rotational axis **150** is perpendicular to rotational axis **170** when viewed along rotational axis **160**, and rotational axis **160** is perpendicular to rotational axis **170** when viewed along rotational axis **150**. In various embodiments, plane **114** and plane **118** each include the entire rotational axis **170** (e.g., rotational axis **170** extends entirely within plane **114**, and rotational axis **170** extends entirely within plane **118**).

(23) Referring to FIGS. 5-6, motor **182** and motor **186** are configured to cooperatively rotate laser emitter **112** and laser emitter **116** with respect to housing **120**. In various embodiments, rotating platform **122**, laser emitter **112**, and laser emitter **116** with respect to the housing **120** around rotational axis **150** includes motor **182** exerting a force on platform **122** in a first direction **184** along axis **183**, and rotating platform **122**, laser emitter **112**, and laser emitter **116** with respect to housing **120** around rotational axis **160** includes motor **182** exerting a force on platform **122** in a second direction **179** along axis **183** opposite the first direction **184**. In various embodiments, rotating platform **122**, laser emitter **112**, and laser emitter **116** with respect to housing **120** around rotational axis **150** includes motor **186** exerting a force on platform **122** in direction **188** along axis **187**, and rotating platform **122** with respect to housing **120** around rotational axis **160** includes motor **186** exerting a force on platform **122** in the third direction **188** along axis **187**. It will be understood that to rotate platform **122** in the opposite directions to those described herein, motor **182** and motor **186** will each exert a force in the opposite direction along their respective axis **183**, **187**.

(24) In various embodiments, both motor **182** and motor **186** are activated to exert force on platform **122** (e.g., to change a position and/or orientation of platform **122**) when laser generating device **110** rotates platform **122** with respect to housing **120** about the first rotational axis **150**, and both motor **182** and motor **186** are activated to exert force on platform **122** (e.g., to change a position and/or orientation of platform **122**) when laser generating device **110** rotates platform **122** with respect to housing **120** about rotational axis **160**.

(25) Stated another way, motor **182** and motor **186** exert forces on platform **122** in opposing directions (e.g., one up and one down, from the perspective of FIG. 5) to rotate platform **122** about rotational axis **150** with respect to housing **120**. As will be explained, this is in contrast to how motor **182** and motor **186** operate when rotating platform **122** about rotational axis **160** with respect to housing **120**.

(26) In particular, to rotate laser emitter **112** and laser emitter **116** in direction **162** around rotational axis **160**, motor **182** exerts a force on platform **122** in direction **179** opposite direction **184** along axis **183** (e.g., down from the perspective of FIGS. 5-6) and motor **186** exerts a force on platform **122** in direction **190** opposite direction **188** along axis **187** (e.g., down from the perspective of FIGS. 5-6). Stated another way, motor **182** and motor **186** exert forces on platform **122** in the same directions (e.g., both up or both down, from the perspective of FIG. 5) to rotate platform **122** about rotational axis **160** with respect to housing **120**. Thus, motor **182** and motor **186** cooperatively rotate platform **122** with respect to housing **120** about each of rotational axis **150** and rotational axis **160**.

(27) In various embodiments, laser level **110** is configured to be placed on a surface, such as a floor, in multiple configurations. For example, (a) laser level **110** is configured to be placed on a surface such that plane **114** is perpendicular to gravity, (b) laser level **110** is configured to be placed on a surface such that plane **118** is perpendicular to gravity, (c) laser level **110** is configured to be placed on a surface such that neither plane **114** nor plane **118** is perpendicular to gravity (e.g., plane **114** and plane **118** are parallel to gravity).

(28) Referring to FIGS. 5-6, in various embodiments, the first motor **182** and the second motor **186** are coupled to the platform **122** such that an intersecting axis **181** intersects each of the first rotational axis **150** and the second rotational axis **160** and the intersecting axis **181** is perpendicular to each of the first rotational axis **150** and the second rotational axis **160**, and the rotational axis **150** and rotational axis **160** are perpendicular to each other when viewed from a perspective along the intersecting axis **181**. Stated another way, rotational axis **150** and rotational axis **160** define an intersecting axis **181** that intersects each of rotational axis **150** and rotational axis **160** and that is perpendicular to each of rotational axis **150** and rotational axis **160**. In various embodiments, rotational axis **150** and rotational axis **160** are perpendicular to each other when viewed from a perspective along the intersecting axis **181** (e.g., if a user travels up axis **181** from the perspective of FIG. 5, and subsequently the user looked back along axis **181**, rotational axis **150** and rotational axis **160** would appear perpendicular to each other). In various embodiments, axis **181** is parallel to plane **114**. In various embodiments, axis **181** is parallel to plane **118**. In various embodiments, axis **181** is parallel to plane **114** and plane **118**.

(29) Stated another way, rotational axis **150** and rotational axis **160** each reside in planes (e.g., horizontal planes) that are parallel to each other and that are each perpendicular to intersecting axis **181**. For example, rotational axis **160** resides in a plane projecting through the page of FIG. 5 at rotational axis **160**, and rotational axis **150** resides in a plane projecting through the page of FIG. 6 at rotational axis **150**. The projection of rotational axis **150** onto the respective plane of rotational axis **160** is perpendicular to rotational axis **160**, and the projection of rotational axis **160** onto the respective plane of rotational axis **150** is perpendicular to rotational axis **150**.

(30) Stated yet another way, intersecting axis **181** extends along the shortest possible path between rotational axis **150** and rotational axis **160**. Further, intersecting axis **181** and rotational axis **150** define a first plane **198** (FIG. 5) that is perpendicular to rotational axis **160** (e.g., a vertical plane



projecting through the page of FIG. 5 at intersecting axis **181**), and intersecting axis **181** and rotational axis **160** define a second plane **199** (FIG. 6) that is perpendicular to rotational axis **150** (e.g., a vertical plane projecting through the page of FIG. 6 at intersecting axis **181**).

(31) Referring to FIGS. 7-9, first laser emitter **112** and second laser emitter **116** are each coupled to platform **122**, such as rigidly coupled. In various embodiments, platform **122** includes aperture **124**. Laser level **110** includes motor **174**, a first arm **176** coupled to the first motor **174**, and a first spring **177** coupled to the first arm **176**, and the first spring **177** is received in the aperture **124**. To rotate first laser emitter **112** and second laser emitter **116** about rotational axis **170**, such as in direction **172**, motor **174** exerts a force on platform **122**.

(32) Motor **174** exerts on a force on arm **175** along axis **178** extending from motor **174** to rotate platform **122** about rotational axis **170** with respect to base **126**. Arm **175** exerts a force on arm **176**, and that force is translated into a biasing element, shown as spring **177**, which is engaged within aperture **124** of platform **122**. Spring **177** is configured to engage with opposing sides of aperture **124** of platform **122**, thereby reducing and/or minimizing slop and/or movement of motor **174** not being translated into movement of platform **122**.

(33) Base **126** includes a protrusion, shown as internal spring-loaded ball **136**, extending from base **126**, that is spring-biased against platform **122**, and one or more protrusions, shown as balls **142**, extending from base **126** that are spring-biased against platform **122**. Spring-loaded ball **136** is configured to exert a force on platform **122** in direction **140**. As a result of the force from spring-loaded ball **136**, platform **122** engages against peripheral balls **142**. As will be explained, the engagement between platform **122** and balls **136** and **142** reduces an amount that platform **122** moves in a direction orthogonal to rotational axis **170** while platform **122** is being rotated about rotational axis **170**.

(34) Referring to FIGS. 10-11, various aspects of platform **122** are shown. In particular, platform **122** includes body **132** extending between coupler **128** and coupler **130**. First laser emitter **112** is coupled to coupler **128**, and second laser emitter **116** is coupled to coupler **130**.

(35) Balls **136** and **142** engage against surfaces of platform **122** to reduce and/or minimize platform **122** moving up or down from the perspective of FIGS. 10-11. In particular, balls **136**, **142** engage within recesses **139**, **145**, and/or **147** to reduce and/or minimize the vertical movement of platform **122** while platform **122** is being rotated about rotational axis **170**.

(36) Platform **122** includes interior recessed surface **138** and opposing exterior recessed surfaces **144**, **146**. Interior recessed surface **138** includes a recess **139**, such as a centrally located recessed portion, that extends along a length of interior recessed surface **138**. Exterior recessed surface **144** includes a recess **145**, such as a centrally located recessed portion, that extends along a length of exterior recessed surface **144**, and exterior recessed surface **146** includes a recess **147**, such as a centrally located recessed portion, that extends along a length of exterior recessed surface **146**.

(37) It should be understood that the figures illustrate the exemplary embodiments in detail, and it should be understood that the present application is not limited to the details or methodology set forth in the description or illustrated in the figures. It should also be understood that the terminology is for description purposes only and should not be regarded as limiting.

(38) Further modifications and alternative embodiments of various aspects of the disclosure will be apparent to those skilled in the art in view of this description. Accordingly, this description is to be construed as illustrative only. The construction and arrangements, shown in the various exemplary embodiments, are illustrative only. Although only a few embodiments have been described in detail in this disclosure, many modifications are possible (e.g., variations in sizes, dimensions, structures, shapes and proportions of the various elements, values of parameters, mounting arrangements, use of materials, colors, orientations, etc.) without materially departing from the novel teachings and advantages of the subject matter described herein. Some elements shown as integrally formed may be constructed of multiple parts or elements, the position of elements may be reversed or otherwise varied, and the nature or number of discrete elements or positions may be altered or varied. The

order or sequence of any process, logical algorithm, or method steps may be varied or re-sequenced according to alternative embodiments. Other substitutions, modifications, changes and omissions may also be made in the design, operating conditions and arrangement of the various exemplary embodiments without departing from the scope of the present disclosure.

(39) Unless otherwise expressly stated, it is in no way intended that any method set forth herein be construed as requiring that its steps be performed in a specific order. Accordingly, where a method claim does not actually recite an order to be followed by its steps or it is not otherwise specifically stated in the claims or descriptions that the steps are to be limited to a specific order, it is in no way intended that any particular order be inferred. In addition, as used herein, the article “a” is intended to include one or more component or element, and is not intended to be construed as meaning only one. As used herein, “rigidly coupled” refers to two components being coupled in a manner such that the components move together in a fixed positional relationship when acted upon by a force.

(40) Various embodiments of the disclosure relate to any combination of any of the features, and any such combination of features may be claimed in this or future applications. Any of the features, elements or components of any of the exemplary embodiments discussed above may be utilized alone or in combination with any of the features, elements or components of any of the other embodiments discussed above.

(41) For purposes of this disclosure, the term “coupled” means the joining of two components directly or indirectly to one another. Such joining may be stationary in nature or movable in nature. Such joining may be achieved with the two members and any additional intermediate members being integrally formed as a single unitary body with one another or with the two members or the two members and any additional member being attached to one another. Such joining may be permanent in nature or alternatively may be removable or releasable in nature.

(42) While the current application recites particular combinations of features in the claims appended hereto, various embodiments of the invention relate to any combination of any of the features described herein whether or not such combination is currently claimed, and any such combination of features may be claimed in this or future applications. Any of the features, elements, or components of any of the exemplary embodiments discussed above may be used alone or in combination with any of the features, elements, or components of any of the other embodiments discussed above.

(43) In various exemplary embodiments, the relative dimensions, including angles, lengths and radii, as shown in the Figures are to scale. Actual measurements of the Figures will disclose relative dimensions, angles and proportions of the various exemplary embodiments. Various exemplary embodiments extend to various ranges around the absolute and relative dimensions, angles and proportions that may be determined from the Figures. Various exemplary embodiments include any combination of one or more relative dimensions or angles that may be determined from the Figures. Further, actual dimensions not expressly set out in this description can be determined by using the ratios of dimensions measured in the Figures in combination with the express dimensions set out in this description.

## Claims

1. A laser generating device comprising: a housing; an arm pivotally coupled to the housing; a platform coupled to the arm, the platform configured to be rotated with respect to the housing about both a first rotational axis and a second rotational axis distinct from the first rotational axis; a first laser emitting device coupled to the platform, the first laser emitting device operable to generate a first output beam along a first plane; a second laser emitting device coupled to the platform, the second laser emitting device operable to generate a second output beam along a second plane; a first motor configured to exert a first force on the platform along a first axis; and a second motor configured to exert a second force on the platform along a second axis distinct from the first axis;

wherein both the first motor and the second motor are activated to exert force on the platform when the platform is rotated with respect to the housing about the first rotational axis, and wherein both the first motor and the second motor are activated to exert force on the platform when the laser generating device rotates the platform with respect to the housing about the second rotational axis.

2. The laser generating device of claim 1, wherein the first rotational axis and the second rotational axis are not planar with respect to each other.
3. The laser generating device of claim 2, wherein the first motor and the second motor are coupled to the platform such that an intersecting axis intersects each of the first rotational axis and the second rotational axis and the intersecting axis is perpendicular to each of the first rotational axis and the second rotational axis, wherein the intersecting axis and the first rotational axis define a third plane that is perpendicular to the second rotational axis, and the intersecting axis and second rotational axis define a fourth plane that is perpendicular to the first rotational axis.
4. The laser generating device of claim 3, wherein the intersecting axis is parallel to the first plane.
5. The laser generating device of claim 3, wherein the intersecting axis is parallel to each of the first plane and the second plane.
6. The laser generating device of claim 1, wherein the first motor and the second motor are coupled to the platform such that an intersecting axis intersects each of the first rotational axis and the second rotational axis and the intersecting axis is perpendicular to each of the first rotational axis and the second rotational axis, wherein the intersecting axis and the first rotational axis define a third plane that is perpendicular to the second rotational axis, and the intersecting axis and the second rotational axis define a fourth plane that is perpendicular to the first rotational axis.
7. The laser generating device of claim 6, wherein the intersecting axis is parallel to each of the first plane and the second plane.
8. The laser generating device of claim 1, comprising a base, the platform coupled to the arm via the base, the base and the platform are configured to be rotated with respect to the housing about both the first rotational axis and the second rotational axis by the first motor and the second motor, wherein the platform rotates with respect to the base about a third rotational axis.
9. The laser generating device of claim 8, wherein the first plane and the second plane each include the entire third rotational axis.
10. The laser generating device of claim 9, wherein rotating the platform with respect to the housing around the first rotational axis comprises the first motor exerting a force on the platform in a first direction along the first axis, and rotating the platform with respect to the housing around the second rotational axis comprises the first motor exerting a force on the platform in a second direction along the first axis opposite the first direction.
11. The laser generating device of claim 10, wherein rotating the platform with respect to the housing around the first rotational axis comprises the second motor exerting a force on the platform in a third direction along the second axis, and rotating the platform with respect to the housing around the second rotational axis comprises the second motor exerting a force on the platform in the third direction along the second axis.
12. The laser generating device of claim 8, wherein rotating the platform with respect to the housing around the first rotational axis comprises the second motor exerting a force on the platform in a third direction along the second axis, and rotating the platform with respect to the housing around the second rotational axis comprises the second motor exerting a force on the platform in the third direction along the second axis.
13. The laser generating device of claim 1, wherein the first axis and the second axis are parallel to each other.
14. A laser generating device comprising: a housing; an arm pivotally coupled to the housing; a platform coupled to the arm, the platform configured to be rotated with respect to the housing about both a first rotational axis and a second rotational axis distinct from the first rotational axis; a first laser emitting device coupled to the platform, the first laser emitting device operable to generate a

first output beam along a first plane; a second laser emitting device coupled to the platform, the second laser emitting device operable to generate a second output beam along a second plane; and a first motor configured to exert a first force on the platform along a first axis; wherein rotating the platform with respect to the housing around the first rotational axis comprises the first motor exerting a force on the platform in a first direction along the first axis, and rotating the platform with respect to the housing around the second rotational axis comprises the first motor exerting a force on the platform in a second direction along the first axis opposite the first direction.

15. The laser generating device of claim 14, wherein the first rotational axis and the second rotational axis are not planar with respect to each other, wherein the first motor is coupled to the platform such that an intersecting axis intersects each of the first rotational axis and the second rotational axis and the intersecting axis is perpendicular to each of the first rotational axis and the second rotational axis, wherein the intersecting axis and the first rotational axis define a third plane that is perpendicular to the second rotational axis, and the intersecting axis and second rotational axis define a fourth plane that is perpendicular to the first rotational axis.

16. The laser generating device of claim 15, wherein the intersecting axis is parallel to each of the first plane and the second plane.

17. The laser generating device of claim 14, comprising a second motor configured to exert a second force on the platform along a second axis distinct from the first axis, wherein rotating the platform with respect to the housing around the first rotational axis comprises the second motor exerting a force on the platform in a third direction along the second axis, and rotating the platform with respect to the housing around the second rotational axis comprises the second motor exerting a force on the platform in the third direction along the second axis.

18. A laser generating device comprising: a housing; an arm pivotally coupled to the housing; a base coupled to the arm such that the base rotates with respect to the housing about both a first rotational axis and a second rotational axis distinct from the first rotational axis, the base including a first protrusion and a second protrusion; a platform coupled to the base, the platform rotatable with respect to the base about a third rotational axis, the first rotational axis extending parallel to an X-axis in a Cartesian Coordinate System, the second rotational axis extending parallel to an Y-axis in the Cartesian Coordinate System, and the third rotational axis extending parallel to a Z-axis in the Cartesian Coordinate System, the platform comprising an interior recessed surface and an opposing exterior recessed surface, wherein when the platform is rotating with respect to the base about the first rotational axis the interior recessed surface interfaces with and moves with respect to the first protrusion and the exterior recessed surface interfaces with and moves with respect to the second protrusion; a first laser emitting device coupled to the platform, the first laser emitting device operable to generate a first output beam along a first plane; and a second laser emitting device, the second laser emitting device operable to generate a second output beam along a second plane.

19. The laser generating device of claim 18, the platform defining an aperture, the laser generating device comprising a first motor, a first arm coupled to the first motor, and a first spring coupled to the first arm, wherein the first spring is received in the aperture, and wherein the first motor exerts a force along a first axis to rotate the platform about the third rotational axis with respect to the base.

20. The laser generating device of claim 18, the first protrusion comprising a first ball that is spring-biased against the platform, the second protrusion comprising a second ball that is spring-biased against the platform.

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