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## INTERVENTIONAL SYSTEMS AND ASSOCIATED DEVICES AND METHODS

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### Abstract

According to some embodiments, the present technology includes device for removing obstructive material from a blood vessel lumen. For example, the device can comprise an elongated member, a cutting portion carried by a distal region of the elongated member, and a capture portion carried by the distal region of the elongated member. The cutting portion can comprise a blade configured to separate at least a portion of the obstructive material from the blood vessel wall, and the capture portion can comprise a mesh structure configured to enmesh and/or capture at least a portion of the obstructive material.

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## **Background/Summary**

CROSS-REFERENCE TO RELATED APPLICATION(S) [0001] This application is a continuation of U.S. patent application Ser. No. 18/916,474, filed Oct. 15, 2024, issued as U.S. Pat. No. 12,290,278 on May 6, 2025, which in turn is a continuation of U.S. patent application Ser. No. 17/654,398, filed Mar. 10, 2022, which claims the benefit of priority to U.S. Provisional Application No. 63/200,495, filed Mar. 10, 2021, each of which is incorporated by reference herein by reference in its entirety.

### **TECHNICAL FIELD**

[0002] The present technology relates generally to interventional systems and associated devices and methods.

### **BACKGROUND**

[0003] Deep vein thrombosis (DVT) is a condition comprising a blood clot in a deep vein, usually a leg vein though they can also occur in arm veins. Symptoms include pain, swelling, tenderness, and/or discoloration in the affected limb. If untreated, it can lead to worsening of symptoms and complications such as post-thrombotic syndrome with symptoms of chronic pain, swelling, and skin discoloration, or pulmonary embolism (PE), a very serious and life-threatening condition. Pharmacologic treatments include blood-thinning medications or thrombolytic drugs. More recently, percutaneous catheters have been developed for the more rapid removal of clot to remove the blockage and prevent PE. These include catheters which can deliver thrombolytic agents to the site of the clot, in some cases in combination with aspiration and/or the disruption of the clot into smaller pieces. Other catheters mechanically capture and remove clot without thrombolytic agents, thereby reducing the bleeding risk incurred by these drugs. An early example of this is the Fogarty Balloon Thrombectomy catheter. More recent examples include the ClotTrieve® (Inari Medical, Irvine, CA) and the ReVene® Thrombectomy Catheter (Vetex Medical, Galway, Ireland).

[0004] Unfortunately, many of these therapies have limited success for partial or full blockages caused by chronic thrombus (i.e., a thrombus over one or two months old). As the clot remains in the limb over a period of months, the initial thrombus transforms into a fibrin and/or collagen structure which is tougher and more firmly adhered to the wall. Chronic thrombus may take the form of fibrous trabeculae or membranes stretching into and across the vein lumen (also known as venous synechiae). Further, the thrombus becomes more firmly attached to the wall. Catheter-based thrombolysis or thrombectomy devices have a lower success rate in removing these blockages. Venous synechiae may also prevent optimal treatment of venous obstruction by balloon angioplasty or stenting, as the fibrous structures prevent permanent stretching of the vessel wall. There is a need for an improved endovascular thrombectomy device which is able to successfully remove chronic thrombus.

### **SUMMARY**

[0005] The subject technology is illustrated, for example, according to various aspects described below, including with reference to FIGS. 1-28B. Various examples of aspects of the subject technology are described as numbered clauses (1, 2, 3, etc.) for convenience. These are provided as examples and do not limit the subject technology. [0006] 1. A device for modifying and/or removing obstructive material from a lumen of a blood vessel, the device comprising: [0007] an elongated member having a proximal portion and a distal portion configured to be intravascularly

positioned at a treatment site in a blood vessel adjacent obstructive material; [0008] a cutting portion disposed at the distal portion of the elongated member, the cutting portion including a cutting element, wherein the cutting portion has a collapsed, low-profile state for delivery to the treatment site and a deployed state for cutting obstructive material at the treatment site, and wherein the cutting element extends radially away from the longitudinal axis of the elongated member in the deployed state; and [0009] a capturing portion disposed at the distal portion of the elongated member, wherein the capturing portion is configured to collect obstructive material that has been dislodged by the cutting portion. [0010] 2. The device of Clause 1, wherein the capturing portion is positioned distal of the cutting portion along the elongated member. [0011] 3. The device of Clause 1 or Clause 2, wherein the capturing portion is self-expandable. [0012] 4. The device of any one of Clauses 1 to 3, wherein the elongated member comprises a first elongated member and a second elongated member, and wherein the cutting portion is disposed at a distal portion of the first elongated member and the capturing portion is disposed at a distal portion of the second elongated member. [0013] 5. The device of Clause 4, wherein the first and second elongated members are configured to rotate and/or translate relative to one another. [0014] 6. The device of Clause 4 or Clause 5, wherein the second elongated member is configured to be slidably disposed within a lumen of the first elongated member. [0015] 7. The device of Clause 4 or Clause 5, wherein the first elongated member is configured to be slidably disposed within a lumen of the second elongated member. [0016] 8. The device of any one of Clauses 1 to 7, wherein the cutting portion comprises a blade disposed along a portion of the cutting element. [0017] 9. The device of Clause 8, wherein the blade is disposed along only a proximally facing surface of the cutting element. [0018] 10. The device of any one of Clauses 1 to 9, wherein a cutting edge of the cutting element is substantially linear. [0019] 11. The device of any one of Clauses 1 to 9, wherein the cutting element wraps around a longitudinal axis of the shaft. [0020] 12. The device of any one of Clauses 1 to 9, wherein the cutting element is a first cutting element and the device further comprises a second cutting element that is configured to extend radially away from the longitudinal axis of the elongated shaft in the deployed state. [0021] 13. The device of Clause 12, wherein an angle between the first and second cutting elements in the deployed state is less than 180 degrees. [0022] 14. The device of Clause 12, wherein an angle between the first and second cutting elements in the deployed state is from about 135 degrees to about 180 degrees. [0023] 15. The device of any one of Clauses 1 to 14, wherein the capturing portion and the cutting portion are independently deployable. [0024] 16. The device of any one of Clauses 1 to 15, wherein the capturing portion comprises has a closed distal end portion and an open proximal end portion. [0025] 17. The device of any one of Clauses 1 to 16, wherein the capturing portion comprises a mesh. [0026] 18. The device of any one of Clauses 1 to 17, wherein the capturing portion has a first region comprising a braid and a second region comprises a stent. [0027] 19. The device of any one of Clauses 1 to 18, wherein, in a deployed state, the cutting element has a proximally facing portion and a distally facing portion, and wherein a sharpened edge of the cutting element is disposed along only the proximally facing portion. [0028] 20. The device of any one of Clauses 1 to 18, wherein, in a deployed state, the cutting element has a proximally facing portion and a distally facing portion, and wherein a sharpened edge of the cutting element is disposed along only the distally facing portion. [0029] 21. A system for modifying and/or removing obstructive material from a lumen of a blood vessel, the system comprising: [0030] a first elongated member having a proximal portion and a distal portion configured to be intravascularly positioned at a treatment site in a blood vessel adjacent obstructive material; [0031] a second elongated member having a proximal portion and a distal portion configured to be intravascularly positioned at the treatment site; [0032] a cutting portion disposed at the distal portion of the first elongated member, the cutting portion including a cutting element, wherein the cutting portion has a collapsed, low-profile state for delivery to the treatment site and a deployed state for cutting obstructive material at the treatment site, and wherein the cutting element extends radially away from the longitudinal axis of the first elongated

member in the deployed state; and [0033] a capturing portion disposed at the distal portion of the second elongated member, wherein the capturing portion is configured to collect obstructive material that has been dislodged by the cutting portion. [0034] 22. The system of Clause 21, wherein the second elongated member is slidably disposed within a lumen of the first elongated member. [0035] 23. The system of Clause 21, wherein the first elongated member is slidably disposed within a lumen of the second elongated member. [0036] 24. The system of any one of Clauses 21 to 23, wherein a distal region of the cutting portion is axially fixed to the distal portion of the second elongated member and a proximal region of the cutting portion is configured to move axially along the second elongated member. [0037] 25. The system of any one of Clauses 21 to 14, wherein, in a deployed state, the cutting element has a proximally facing portion and a distally facing portion, and wherein a sharpened edge of the cutting element is disposed along only the proximally facing portion. [0038] 26. The system of any one of Clauses 21 to 24, wherein, in a deployed state, the cutting element has a proximally facing portion and a distally facing portion, and wherein a sharpened edge of the cutting element is disposed along only the distally facing portion. [0039] 27. The system of any one of Clauses 21 to 26, further comprising an introducer sheath, and wherein the first and second elongated members are configured to be slidably disposed in a lumen of the introducer sheath. [0040] 28. A device for modifying and/or removing obstructive material from a lumen of a blood vessel, the system comprising: [0041] a first elongated member having a proximal portion and a distal portion configured to be intravascularly positioned at a treatment site in a blood vessel adjacent obstructive material, wherein the first elongated member defines a lumen extending therethrough; [0042] a second elongated member having a proximal portion and a distal portion configured to be intravascularly positioned at the treatment site, wherein the second elongated member is configured to be rotatably disposed within the lumen of the first elongated member; [0043] a cutting element configured to cut obstructive material at the treatment site, the cutting element having a proximal end region at the distal portion of the first elongated member and a distal end region at the distal portion of the second elongated member, wherein rotation of the second elongated member relative to the first elongated member, or vice versa, causes the cutting element to expand away from a longitudinal axis of the second elongated member. [0044] 29. The device of Clause 28, wherein the cutting element wraps at least partially around the longitudinal axis of the second elongated member as it extends between the first elongated member and the second elongated member. [0045] 30. The device of Clause 28 or Clause 29, wherein the cutting element is a ribbon. [0046] 31. The device of any one of Clauses 28 to 30, wherein the cutting element has longitudinally extending edges, and wherein one or both longitudinally extending edges are sharpened. [0047] 32. The device of any one of Clauses 28 to 30, wherein the cutting element has a proximally facing longitudinal edge and a distally facing longitudinal edge, and wherein only one of the proximally facing or distally facing longitudinal edge is sharpened. [0048] 33. The device of any one of Clauses 28 to 32, wherein the cutting element is a first cutting element and the device comprises a second cutting element. [0049] 34. The device of Clause 33, wherein the second cutting element is positioned radially inwardly of the first cutting element. [0050] 35. The device of Clause 33, wherein the second cutting element is positioned radially outwardly of the first cutting element. [0051] 36. The device of any one of Clauses 33 to 35, wherein the second cutting element is substantially linear. [0052] 37. The device of any one of Clauses 33 to 35, wherein the second cutting element wraps at least partially around the longitudinal axis of the second elongated member. [0053] 38. The device of any one of Clauses 33 to 37, further comprising a third elongated member positioned between the first and second elongated members, and wherein the second cutting element is at a distal portion of the third elongated member.

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## Description

## BRIEF DESCRIPTION OF THE DRAWINGS

[0054] Many aspects of the present disclosure can be better understood with reference to the following drawings. The components in the drawings are not necessarily to scale. Instead, emphasis is placed on illustrating clearly the principles of the present disclosure.

[0055] FIG. 1 schematically depicts a treatment system configured in accordance with several embodiments of the present technology.

[0056] FIG. 2 schematically depicts a distal portion of a treatment system configured in accordance with several embodiments of the present technology.

[0057] FIGS. 3A and 3B are top views of a treatment assembly configured in accordance with several embodiments of the present technology, shown in a collapsed state and an expanded state, respectively.

[0058] FIG. 4 schematically depicts an end view of a cutting portion of a treatment assembly configured in accordance with several embodiments of the present technology, shown positioned in a blood vessel lumen in an expanded state.

[0059] FIG. 5 is a side view of a treatment assembly configured in accordance with several embodiments of the present technology, shown in an expanded state.

[0060] FIGS. 6 and 7 are side views of a treatment assembly configured in accordance with several embodiments of the present technology.

[0061] FIGS. 8 and 9A are side views of a treatment assembly configured in accordance with several embodiments of the present technology, shown in an expanded state.

[0062] FIG. 9B is a side view of a treatment assembly configured in accordance with several embodiments of the present technology, shown in a collapsed state.

[0063] FIG. 10 is a side view of a treatment assembly configured in accordance with several embodiments of the present technology.

[0064] FIG. 11 is a side view of a treatment assembly configured in accordance with several embodiments of the present technology, shown in an expanded state.

[0065] FIGS. 12A-12C are side views of a treatment system having a treatment device and an introducer sheath with a proximal funnel configured in accordance with several embodiments of the present technology.

[0066] FIGS. 13-16 are side view of capture portions configured in accordance with several embodiments of the present technology.

[0067] FIG. 17A is an isometric view of a cutting portion configured in accordance with the present technology, shown in an expanded state.

[0068] FIG. 17B is an end view of the cutting portion shown in FIG. 17A shown positioned within a blood vessel lumen in an expanded state.

[0069] FIG. 18A is an isometric view of a cutting portion configured in accordance with the present technology, shown in an expanded state.

[0070] FIG. 18B is an end view of the cutting portion shown in FIG. 18A shown positioned within a blood vessel lumen in an expanded state.

[0071] FIG. 19A is an exploded view of a blade assembly configured in accordance with several embodiments of the present technology.

[0072] FIG. 19B is an assembled view of a blade assembly configured in accordance with several embodiments of the present technology.

[0073] FIGS. 20A and 20B are perspective views of a treatment assembly configured in accordance with several embodiments of the present technology, shown in a collapsed state and an expanded state, respectively.

[0074] FIGS. 21A and 21B are perspective views of a treatment assembly configured in accordance with several embodiments of the present technology, shown in a collapsed state and an expanded state, respectively.

[0075] FIGS. 22A, 22B, and 22C are perspective views of a treatment assembly configured in accordance with several embodiments of the present technology, shown with various components removed for ease of explanation.

[0076] FIGS. 23A and 23B perspective views of a treatment assembly configured in accordance with several embodiments of the present technology, shown in a collapsed state and an expanded state, respectively.

[0077] FIG. 24 is a perspective view of a treatment assembly configured in accordance with several embodiments of the present technology, shown in an expanded state.

[0078] FIG. 25 is a perspective view of a treatment assembly configured in accordance with several embodiments of the present technology, shown in an expanded state.

[0079] FIG. 26 is a perspective view of a treatment assembly configured in accordance with several embodiments of the present technology.

[0080] FIGS. 27A and 27B are isometric views of a cutting portion configured in accordance with several embodiments of the present technology. FIG. 27A shows the cutting portion in a collapsed state. FIG. 27B shows the cutting portion in an expanded state.

[0081] FIGS. 27C and 27D are side views of an arm of the cutting portion shown in FIGS. 27A and 27B, shown isolated from the treatment assembly and configured in accordance with several embodiments of the present technology.

[0082] FIGS. 28A and 28B are isometric views of a cutting portion configured in accordance with several embodiments of the present technology. FIG. 28A shows the cutting portion in a collapsed state. FIG. 28B shows the cutting portion in an expanded state.

#### DETAILED DESCRIPTION

[0083] FIG. 1 schematically depicts a treatment system **10** (also referred to herein as “the system **10**”) configured in accordance with the present technology. The treatment system **10** is configured to access a body lumen (such as a vein or artery) and modify, capture, and/or remove obstructive material from the body lumen. As used herein, “obstruction” or “obstructive material” can comprise, for example, clot material, atherosclerotic plaque, and/or other flow-obstructing structures, including those derivative of clot material, such as fibrotic clot material, venous synechiae, fibrinous structures, collagenous structures, fibrous trabeculae, and/or others. As shown in FIG. 1, the system **10** may comprise a treatment device **101** (or “device **101**”) having a proximal portion **101a** configured to be positioned extracorporeally during the procedure, a distal portion **101b** configured to be positioned at a treatment site within a blood vessel, and one or more elongated members **102** extending between the proximal portion **101a** and the distal portion **101b**. The treatment device **101** can also include a handle **12** and a sleeve **112** extending distally from the handle **12**. The elongated member **102** can be configured to be slidably disposed within a lumen of the sleeve **112**. In several embodiments, the treatment device **101** does not include one of the sleeve **112** or the elongated member **102**. In these and other embodiments, the treatment device **101** includes two or more elongated members (for example, as described herein with respect to FIG. 2). The treatment device **101** may include a lumen **22** to accept a guidewire or other guide rail, so that the device **101** may be positioned over the guide to a treatment site. The lumen **22** may extend along the elongated member **102** (or any component thereof) and terminate distally at a distal opening. The lumen **22** may also be configured to receive a visualization device therethrough.

[0084] The treatment device **101** further includes a treatment assembly **100** (or “assembly **100**”) carried by a distal portion of the elongated member **102**. The treatment assembly **100** can comprise a capture portion **200** and a cutting portion **300**, which may be integral with one another or separate components. The cutting portion **300** can comprise one or more cutting elements configured to cut through obstructive material in the vessel lumen as the treatment assembly **100** is moved axially along the lumen, thereby separating and/or releasing obstructive material from the vessel wall and/or from other obstructive material. The capture portion **200** can comprise one or more expandable mesh structures configured to engage, trap, or otherwise become enmeshed with

obstructive material at the treatment site, before, during, or after engagement by the cutting portion **300**. The capture portion **200** can comprise any of the capture portions **200** described herein, and the cutting portion **300** can comprise any of the cutting portions **300** described herein. Additional details regarding the capture portion **200** and the cutting portion **300** are described below.

[0085] The treatment assembly **100** is transformable between a low-profile state for delivery to the vessel lumen and a deployed (e.g., expanded) state, as detailed herein. As used herein with reference to the treatment assembly **100**, “expanded” and “deployed” refer to a configuration of the treatment assembly **100** when one or both of the capture portion **200** and the cutting portion **300** are in a partially or fully expanded state. According to several embodiments described herein, the capture portion **200** and the cutting portion **300** are integrated into a single expandable device. In some of such embodiments, the treatment assembly **100** is self-expanding and coupled to a distal end portion of a single elongated member **102**. In other embodiments in which the capture portion **200** and the cutting portion **300** are integrated into a single expandable device, the treatment assembly **100** (regardless of whether the treatment assembly **100** is self-expanding or requires activation) is coupled to at least two elongated members **108**, **111**, as shown in FIG. 2. The sleeve **112** may be positioned over the treatment assembly **100** to radially constrain and/or protect the treatment assembly **100** while being introduced to the vessel lumen. In such embodiments, the sleeve **112** is withdrawn proximally to expose the treatment assembly **100** to allow one or more portions of the treatment assembly **100** to expand.

[0086] According to several aspects of the technology, the capture portion **200** and the cutting portion **300** are independently deployable. In such embodiments, both the capture portion **200** and the cutting portion **300** can be self-expanding and be coupled to the same elongated member **102** or may be coupled to separate elongated members.

[0087] In some embodiments the capture portion **200** and the cutting portion **300** comprise separately-formed components, both carried by the distal region of the elongated member **102**. One of many examples of such embodiments is shown in FIGS. 3A and 3B. In these embodiments, the capture portion **200** and the cutting portion **300** can be configured to collapse and expand independently of one another or via the same actuation mechanism. For example, the capture portion **200** can be a resilient structure configured to self-expand upon withdrawal of a sleeve **112**, while expansion of the cutting portion **300** may require an additional actuation step by the operator (as detailed herein). Likewise, the cutting portion **300** can be a resilient structure configured to self-expand upon withdrawal of the sleeve **112**, while expansion of the capture portion **200** may require an additional actuation step by the operator (as detailed herein). According to some examples, both the capture portion **200** and cutting portion **300** are resilient, self-expanding structures.

[0088] Referring still to FIG. 1, the handle **12** at the proximal portion **101a** of the treatment device **101** can be permanently or detachably coupled to one or more of the elongated members (such as the sleeve **112**, the elongated member **102**, the inner member **108**, the outer member **111**, etc.). The handle **12** can include one or more actuators for controlling movement of one or more portions of the treatment assembly **100**. For example, the handle **12** can include a first actuator **14** that is mechanically (e.g., via a push rod, push tube, and/or pull-wire) and/or electrically (e.g., via one or more wires) coupled to the capture portion **200** and a second actuator **16** that is mechanically (e.g., via a push rod, push tube, and/or pull-wire) and/or electrically (e.g., via one or more wires) coupled to the cutting portion **300**. Activation of the first actuator **14**, for example, can control one or more movements of the capture portion **200**. In some embodiments, the first actuator **14** controls the axial movement, rotational movement, and/or radial expansion/contraction of some or all of the capture portion **200**. In some embodiments, the second actuator **16** controls the axial movement, rotational movement, and/or radial expansion/contraction of some or all of the cutting portion **300**. In some embodiments, the first actuator **14** controls the axial movement, rotational movement, and/or radial expansion/contraction of some or all of the capture portion **200**. According to some aspects of the technology, the first and/or second actuators **14**, **16** and/or a third actuator (not

shown) controls the axial movement, rotational movement, and/or radial expansion/contraction of some or all of the capture portion **200** and some or all of the cutting portion **300**. For example, the handle **12** can include an actuator that is configured to move the cutting portion **300** axially with respect to the capture portion **200** (or vice versa).

[0089] In some embodiments, the first and/or second actuator **14**, **16**, or an additional actuator (not shown) at the handle **12** is coupled to the sleeve **112** and configured to control axial and/or rotational movement of the sleeve **112**. Such an actuator, for example, can be configured to axially advance or withdraw the sleeve **112** to selectively expose or cover all or a portion of the treatment assembly **100**. In some embodiments, the first and/or second actuator **14**, **16**, or an additional actuator (not shown) at the handle **12** is coupled to the elongated member **102** and configured to control axial and/or rotational movement of the elongated member **102**. In some embodiments, the first and/or second actuator **14**, **16**, or an additional actuator (not shown) at the handle **12** is coupled to the inner member **108** and configured to control axial and/or rotational movement of the inner member **108**. In some embodiments, the first and/or second actuator **14**, **16**, or an additional actuator (not shown) at the handle **12** is coupled to the outer member **111** and configured to control axial and/or rotational movement of the outer member **111**. The handle **12** can include more or fewer than two actuators (e.g., one actuator, three actuators, four actuators, five actuators, six actuators, etc.).

[0090] According to several aspects of the technology, the treatment system **10** optionally includes an introducer **103** for facilitating delivery of the treatment device **101** into the vessel lumen. The introducer **103** can comprise a proximal portion **103a**, a distal portion **103b**, a hub **105** at the proximal portion **103**, and an elongated sheath **110** extending distally from the hub **105** to the distal portion **103b** of the introducer **103**. In some embodiments, the hub **105** is configured to be coupled to the suction source **18** and/or the fluid source **20** (e.g., via one or more ports). The hub **105** and sheath **110** can be configured to receive a portion of the treatment device **101** therethrough. For example, the treatment assembly **100**, the elongated member **102**, and/or the sleeve **112** can be configured to be inserted through the hub **105** and slidably positioned within a lumen of the sheath **110**. In some embodiments, the hub **105** comprises a hemostatic valve. According to several embodiments, the introducer **103** includes a funnel at the distal end portion of the sheath **110**. Several examples of such embodiments are depicted at FIGS. **12A-12C**, **28A-28B**, etc. The funnel can be configured to expand into apposition with the vessel wall proximate the distal end portion of the sheath **110**, thereby preventing released obstructive material from traveling proximally of the introducer **103**. In some embodiments, the system **10** does not include an introducer **103**.

[0091] The treatment system **10** can optionally include a suction or aspiration source **18** (e.g., a syringe, a pump, etc.) configured to be fluidly coupled to a proximal portion of one or more of the introducer **103**, the sleeve **112**, and/or the elongated member **102** (and/or one or more subcomponents thereof) to apply negative pressure therethrough. In some embodiments, the treatment system **10** includes a fluid source **20** (e.g., a fluid reservoir, a syringe, pump, etc.) configured to be fluidly coupled to a proximal portion of one or more of the introducer **103**, the sleeve **112**, and/or the elongated member **102** (and/or one or more subcomponents thereof) to supply fluid to the treatment site. The fluid, for example, can be saline, contrast agents, a drug such as a thrombolytic agent, etc.

[0092] Actuators on the handle **12** or separate actuators connected directly to the suction source **18** and/or the fluid source **20** may control the application of aspiration and/or flushing through the system **10** to the treatment site. In some embodiments, a single actuator controls both aspiration and flushing.

[0093] In some methods of use, the system **10** can be introduced into the venous system from a proximal site (e.g., the common femoral vein or femoral vein) and advanced in a retrograde direction (against normal blood flow) to a treatment site in a vein of the patient's leg. The system **10** can also be introduced into the venous system from a distal site (e.g., a popliteal or more distal



vein) and advanced in an antegrade direction (same direction as blood flow) towards the target treatment site. In some embodiments, the system **10** is introduced into an artery.

[0094] FIGS. **3A** and **3B** are top views of a distal portion **101b** of a treatment device **101** with a treatment assembly **100** in various states of deployment, accordance with embodiments of the present technology. As shown in FIGS. **3A** and **3B**, the treatment assembly **100** can comprise a capture portion **200** and a cutting portion **300**. The capture portion **200** and the cutting portion **300** can be independently deployable. For example, the capture portion **200** is shown in a deployed (e.g., expanded) state in FIGS. **3A** and **3B**, and the cutting portion **300** is shown in a collapsed state in FIG. **3A** and a deployed state in FIG. **3B**.

[0095] The cutting portion **300** can comprise one or more cutting elements **302** configured to cut through obstructive material in the vessel lumen as the treatment assembly **100** is moved axially along the lumen, thereby separating and/or releasing obstructive material from the vessel wall and/or other obstructive material. FIG. **4** schematically depicts the device positioned within a blood vessel. The arms **304** of the cutting portion **300** may be canted towards each other (rather than extending 180 degree apart) when expanded so that the arms **304** and attached blades **302** are at an angle  $\theta$  that better approximates the curvature of the vessel wall. This geometry facilitates cutting obstructive material (such as chronic thrombus material) away from the curved vessel wall. In some embodiments, the angle between the two arms is less than 180 degrees. In some embodiments, the angle is between 135 and 180 degrees.

[0096] The capture portion **200** can comprise one or more expandable mesh structures configured to engage, trap, or otherwise become enmeshed with obstructive material at the treatment site. In some embodiments, for example as shown in FIGS. **3A** and **3B**, the cutting portion **300** can be positioned proximally of some or all of the capture portion **200** along the longitudinal axis of the assembly **100** and/or device **101** such that the portion(s) of the obstruction separated from the vessel wall by the axial movement of the cutting portion **300** are subsequently trapped in and/or become enmeshed with the capture portion **200** for removal from the patient's body. For example, in some embodiments, all or a portion of the cutting portion **300** is positioned distally of the obstructive material and move proximally, and in some embodiments all or a portion of the cutting portion **300** is positioned proximally of the obstructive material and is moves distally towards the capture portion **200**.

[0097] As depicted in FIGS. **3A** and **3B**, in some embodiments the capture portion **200** and the cutting portion **300** comprise separately-formed components, both carried by the distal region of the elongated member **102**. In such embodiments, the capture portion **200** and the cutting portion **300** can be configured to collapse and expand independently of one another or via the same actuation mechanism. For example, the capture portion **200** can be a resilient structure configured to self-expand upon withdrawal of a sleeve **112**, while expansion of the cutting portion **300** may require an additional actuation step by the operator (as detailed herein). Likewise, the cutting portion **300** can be a resilient structure configured to self-expand upon withdrawal of the sleeve **112**, while expansion of the capture portion **200** may require an additional actuation step by the operator (as detailed herein). According to some examples, both the capture portion **200** and cutting portion **300** are resilient, self-expanding structures.

[0098] In some embodiments of the present technology, for example as shown in FIGS. **3A** and **3B**, the elongated member **102** can comprise an outer member **111** and an inner member **108** positioned through a lumen of the outer member **111**. A proximal end of each of the outer member **111** and the inner member **108** can be disposed at the handle so that the inner and outer members **108**, **111** can be manipulated by an operator. In some embodiments, a distal end portion **200b** of the capture portion **200** is coupled to the distal region of the inner member **108**. In the embodiment shown in FIGS. **3A** and **3B**, for example, only the distal end portion **200b** of the capture portion **200** is coupled to the distal region of the inner member **108** and the proximal end portion **200a** is free to expand radially away from the inner member **108** when the sleeve **112** is withdrawn. As a result,

when the capture portion **200** is in the expanded state, the proximal end portion **200a** defines a proximal opening **206** through which obstructive material separated by the cutting portion **300** can pass to trap the obstructive material within an inner cavity defined by the capture portion **200**. In some embodiments, only the proximal end portion **200a** of the capture portion **200** is coupled to the inner member **108** and the distal end portion **200b** is free and defines a distal opening in the expanded state. In some embodiments, both the proximal end portion **200a** and the distal end portion **200b** are coupled to the inner member **108**.

[0099] Referring still to FIGS. **3A** and **3B**, a distal end portion **300b** of the cutting portion **300** can be coupled to the inner member **108**, and a proximal end portion **300a** of the cutting portion **300** can be coupled to a distal end portion of the outer member **111**. The distal end portion **300b** of the cutting portion **300** can be coupled to the inner member **108** at a location that is distal to, generally aligned with, or proximal to the proximal terminus of the capture portion **200**. In some embodiments, the distal end portion **300b** is slidable along the inner member **108**. In such embodiments, the inner member **108** may optionally include a distal and/or proximal stop to limit distal and/or proximal axial movement, respectively, of the cutting portion **300** along the inner member **108**. In any case, movement of the outer member **111** relative to the inner member **108** can cause the cutting portion **300** to radially expand and collapse. For example, axial movement of the outer member **111** relative to the inner member **108** in a distal direction can cause the cutting portion **300** to radially expand, while axial movement of the outer member **111** relative to the inner member **108** in a proximal direction can cause the cutting portion **300** to radially collapse.

[0100] According to several embodiments of the present technology, the cutting portion **300** may comprise a tube with one or more regions removed along the distal portion to form expandable arms **304** (labeled individually as **304a** and **304b**). In some embodiments, the outer member **111** and the tube forming the cutting portion **300** are different portions of the same continuous tube. As previously described, distal movement of the outer member **111** with respect to the inner member **108** causes the arms **304** to buckle and/or bend outwardly away from the longitudinal axis of the elongated member **102**, as shown in FIG. **3B**.

[0101] The arms **304** can include one or more segments **306a**, **306b**, **308a**, and **308b** (referred to collectively as “segments **309**”) and one or more joints **310**. The joints **310** can be positioned along the arms **304** between segments **309** and/or between a respective arm **304** and the rest of the tube from which the arms **304** are cut (e.g., the proximal and distal end portions of the arms **304**). The joints **310** can be portions of the arms **304** that are configured to preferentially flex or bend relative to the segments **309** and/or the proximal and distal end portions of the tube. In some embodiments, one or more of the joints **310** can be formed by opposing recesses at a desired location along the arm **304** (e.g., a living hinge), and in other embodiments one or more of the joints **310** can be one or more small pins, elastic polymeric elements, mechanical hinges and/or other devices that enable one segment to pivot or bend relative to another.

[0102] In the embodiment shown in FIGS. **3A** and **3B**, each of the arms **304** includes a distal joint at its distal end portion, a proximal joint at its proximal end portion, and an intermediate joint positioned along the length of the respective arm **304** between the distal and proximal joints. In response to longitudinal stresses caused by relative axial movement of the inner and outer members **108**, **110**, the arms **304** deform into a predetermined shape biased by the configuration and/or relative positions of the joints **310**. For example, in the illustrated embodiment, each of the arms **304**, when deployed, includes a generally linear distal segment **306a**, **306b** and a generally linear proximal segment **308a**, **308b**. In some embodiments, each of the arms **304**, when deployed, includes a generally curved distal segment **306a**, **306b** and/or a generally curved proximal segment **308a**, **308b**.

[0103] The cutting portion **300** can include one or more cutting elements, such as blades **302**, fixedly coupled to one or more segments of the arms. In the embodiment shown in FIGS. **3A** and **3B**, each of the blades **302** has a sharpened edge that faces proximally when the cutting portion **300**

is in the deployed and/or expanded state. The blades **302** may comprise a first material while the arms **304** and/or cutting portion **300** may comprise a second material different than the first material. For example, the blades **302** may comprise stainless steel while the arms **304** and/or cutting portion **300** may comprise a resilient and/or superelastic metal alloy, such as Nitinol, a cobalt-chromium alloy, and others. In some embodiments, the blades **302** comprise the same material as the arms **304**. According to several embodiments, the cutting elements are not separately-formed structures and instead are formed of a sharpened surface of the cutting portion **300**.

[0104] FIG. 5 is a side view of a distal portion **10b** of a treatment system **10** configured in accordance with several embodiments of the present technology, with the treatment assembly **100** shown in an expanded state. The assembly **100** can comprise an elongated member **102** and a cutting portion **300** that are generally similar to the elongated member **102** and cutting portion **300** discussed above with reference to FIGS. 3A and 3B. The capture portion **200** shown in FIG. 5 can be generally similar to the capture portion **200** shown in FIGS. 3A and 3B, except the capture portion **200** shown in FIG. 5 includes a flexible braided distal region **202** and a more rigid proximal region **204** formed of a laser-cut tube or sheet of material. The tube forming the proximal region **204** can be continuous with or separate from a distal region of the cutting portion **300**. The proximal region **204** can have a greater chronic outward force and/or radial resistive force as compared to the distal region **202**, which can be beneficial for maintaining the patency of the proximal opening **206** once the assembly **101** and/or device **101** is deployed. In some embodiments, the cutting portion **300** may be fixed to or integral to the capture portion **200**. For example, the proximal, open end region **204** of the capture portion **200** may be constructed from a cut nitinol tube. The main structure of the cutting portion **300** may also be constructed from a cut nitinol tube, as described above. The nitinol tube of region **204** and of cutting portion **300** may be the same nitinol tube with two sections of cut pattern. Alternately, nitinol tube of region **204** and of cutting portion **300** may be two separate tubes which are mechanically coupled, glued, soldered or welded, to fixedly couple the capture portion **200** with the cutting portion **300**.

[0105] FIGS. 6 and 7 shows a distal portion of a device **101** configured in accordance with several embodiments of the present technology. As shown in FIGS. 6 and 7, in some embodiments the cutting portion **300** and the capture portion **200** are separate components that are spaced apart and slidably coupled. In this embodiment, the blades of the cutting portion **300** of assembly **100** and/or device **101** can face proximally or face distally, depending on how the capture portion **200** and cutting portion **300** are configured to be used with respect to each other. In one variation, shown in FIG. 6, the cutter is oriented in the distal direction. According to some methods of use, the treatment assembly **100** is initially positioned in the blood vessel lumen such that both the capture portion **200** and cutting portion **300** are distal to the obstructive material. The two portions **200**, **300** can be expanded, for example, by retraction of a sheath, or by any of the expansion mechanisms described herein. The cutting portion **300** can be pulled proximally to cut through the obstructive material, and subsequently the capture portion **200** can be pulled proximally cut gather the cut obstructive material. In some embodiments, the cutting portion **300** and capture portion **200** can alternately and/or simultaneously be pulled back to cut and capture the obstructive material.

[0106] In another variation, as shown in FIG. 7, the blades **302** on the cutting portion face distally. According to some methods of use, the treatment assembly **100** is initially positioned in the blood vessel lumen such that the capture portion **200** is distal to the obstructive material and the cutting portion **300** is proximal to the obstructive material. In use, the cutting portion **300** can be moved axially towards the capture portion **200** to separate obstructive material from the wall and push the obstructive material into the capture portion **200**.

[0107] In some embodiments, the cutting portion **300** of the assembly **100** may be an expandable tubular structure with integrated cutting elements. FIG. 8, for example, shows an assembly **100** with a cutting portion **300** comprising a substantially tubular, stent-like portion **502** and a plurality

of arms **504** extending away from the stent-like portion **502** in a distal direction. The cutting portion **300** can further include a plurality of cutting elements **302**, each disposed at an end portion of a corresponding arm **502**. For example, in some embodiments, the cutting portion **300** is constructed from a cut nitinol tube with integrated cutting elements **302** (such as blades) arranged in a circular array. The arms **504** and cutting elements **302** may be spaced apart about a circumference of the cutting portion **300** such that the cutting portion **300** is configured to create a cut that extends circumferentially around the blood vessel wall. Such a feature may be advantageous in some situations due to the amount of obstructive material in the vessel and/or the difficulty with separating the obstructive material from the vessel wall. The cutting edge of the cutting elements **302** may be sharpened and configured to mechanically cut and/or otherwise modify the obstructive material. Additionally or alternatively, the cutting edge of the cutting elements may be configured to chemically cut and/or otherwise modify the obstructive material. [0108] In some embodiments, one, some, or all of the arms **504** are tapered. In some embodiments the arms **504** are not tapered and/or have a generally constant width and/or arc length along their lengths. In a collapsed state (not shown), the distal end portions can be circumferentially spaced apart while the intermediate portions of the projections circumferentially overlap with the circumferentially adjacent projections. In an expanded state (FIG. **8**), the end portions of the arms **504** can be circumferentially spaced apart by a greater arc length than when the device was in the collapsed state, and the intermediate portions circumferentially overlap to a lesser extent than in the collapsed state or do not overlap at all.

[0109] As shown in FIG. **8**, the arms **504** and/or cutting elements **302** can be directed distally towards the capture portion **200**. In several of such embodiments, the cutting portion **300** can be configured to move axially relative to the capture portion **200**. For example, the cutting portion **300** can be slidably coupled to an outer elongated member **111** while the capture portion **200** can be coupled to an inner elongated member **108**. Other configurations that allow independent movement of the capture portion **200** and the cutting portion **300** are possible. In use, the cutting portion **300** can be deployed and/or otherwise positioned proximally of the obstructive material with all or a portion of the capture portion **200** positioned distally of the obstructive material. The cutting portion **300** can be pushed distally to cut the obstructive material and separate the obstructive material from the vessel wall and/or from other obstructive material.

[0110] FIG. **9A** shows a treatment assembly **100** that is generally similar to the treatment assembly **100** of FIG. **8**, except in FIG. **9A** the plurality of arms **504** extend away from the stent-like portion **502** in a proximal direction. In use, the capture portion **200** and cutting portion **300** can be deployed and/or otherwise positioned distally of the obstructive material and pulled proximally to cut the obstructive material. FIG. **9B** depicts the treatment assembly **100** in a collapsed state within a sleeve **112** (shown in cross-section).

[0111] In some embodiments where the capture portion **200** and cutting portion **300** are separately-formed components, the capture portion **200** and the cutting portion **300** can be fixed to one another such that axial and/or rotational movement of one of the portions **200**, **300** causes axial movement of all or a portion of the other portion **200**, **300**. For example, a distal end portion **300b** of the cutting portion **300** can be fixedly coupled to a proximal end region **200a** of the capture portion **200**. If both the cutting portion **300** and the capture portion **200** are fairly rigid structures with high column strength (such as a laser-cut tube or sheet of material), axial movement of the cutting portion **300** will cause axial movement of the entire capture portion **200** and vice versa. If one of the capture portion **200** or the cutting portion **300** is a more flexible structure with low column strength (such as a braid) while the other is a more rigid structure, axial movement of the more rigid structure may cause an end region of the more flexible structure to collapse axially, while axial movement of the flexible structure may not cause any axial movement of the more rigid structure.

[0112] According to several embodiments, the capture portion **200** and the cutting portion **300** can

be rotated and/or moved axially independently of one another. For example, the elongated member **102** can comprise a first elongated member coupled to the capture portion **200** and a second elongated member coupled to the cutting portion **300**. The first and second elongated members can be configured to move axially relative to one another and/or rotate relative to one another (for example, where one elongated member is received within a lumen of the elongated member), thereby causing axial movement and/or rotation of the corresponding attached capture and cutting portions **200**, **300**. In some embodiments, the capture portion **200** and the cutting portion **300** can be mounted to the same elongated member, but one of the capture portion **200** or the cutting portion **300** is fixed axially and/or rotationally to the elongated member while the other is free to slide along and/or rotate about the elongated member. In some embodiments the capture portion **200** and cutting portion **300** are both fixed axially and/or rotationally to the elongated member. [0113] In any of the embodiments in which the capture portion **200** and the cutting portion **300** are separately-formed components, the capture portion **200** and the cutting portion **300** may be configured to radially expand and collapse independently of one another or via the same actuation mechanism, as discussed herein.

[0114] In some embodiments of the present technology, the cutting portion **300** is integrated within the structure of the capture portion **200** or vice versa. For example, as shown in FIG. **10**, the capture portion **200** can have one or more cutting elements facing proximally along a proximal surface of the capture portion and configured to cut obstructive material when the device is pulled back. The cutting elements may be angled with respect to the longitudinal axis of the elongated member **102** to optimize the ability of the blades to slide through the tough material as the device is pulled proximally. The cutting elements can be one or more separately-formed blades coupled to the proximal surface of the capture portion **200**. For example, the cutting elements can be separately-formed blades **302** that are mechanically attached to the capture portion **200** (for example via the latching configuration described with respect to FIGS. **19A** and **19B**). In such embodiments, the struts defining the proximal opening **206** of the capture portion **200** can have slots or other features to mechanically lock the blades **302** in place relative to the struts. Additionally or alternatively, the cutting elements can be formed of the same material and/or structure as the capture portion **200**. For example, the cutting elements can be formed of a sharpened, proximally facing surface of the capture portion **200**.

[0115] In some embodiments, for example as shown in FIG. **11**, the cutting elements and/or projections carrying the cutting elements are constructed from the same metal tube that comprises the proximal portion **204** of capture portion **200** and include protruding tapered elements that furl together when collapsed, similar to FIGS. **8-9B**. While the assembly **100** in FIG. **11** shows a capture portion **200** comprising a braid, in some embodiments the capture portion **200** may comprise a laser-cut stent.

[0116] Regarding FIGS. **8**, **9A**, **9B**, **11**, **27A**, **27B**, **28A**, and **28B**, one, some, or all of the projections (such as arms **504**, arms **652**, projections **1502**, etc.) can include a cutting element **302**. The cutting element can be coupled to the projection (such as a blade) or the cutting element can be cut into the tube forming the treatment assembly **100**. In some embodiments, the cutting elements are positioned at the distal end portions of the projections. In these and other embodiments, the cutting elements may be positioned along all or a portion of one or both side surfaces of a given projection.

[0117] When the treatment assembly **100** is in a collapsed state, the projections can be compressed together, and when the treatment assembly **100** is in an expanded state the projections can expand outward to contact and/or conform to the vessel wall. When the treatment assembly is pulled into and through the obstructive material, the cutting elements cut the obstructive material away from the vessel wall. The cutting elements may be configured to be angled such that pulling the device causes the cutting surface to slice across the obstructive material to improve the cutting action. The distal and/or side edges of one, some, or all of the projections **312** and/or blades can be generally

linear, generally curved, serrated, and other have suitable configurations.

[0118] The devices and systems of the present technology can optionally include a sheath **110** with a self-expanding funnel configured to extend distally from the distal opening of the sheath **110**. Such a feature can be beneficial for corralling the captured obstructive material into the sheath **110** as the treatment assembly **100** is withdrawn into the sheath **110**. An example system **10** including a funnel **700** is shown in FIGS. **12A** and **12B**. As shown in FIG. **12A**, the treatment device **101** with treatment assembly **100** can be delivered in a collapsed state through a sheath **110** with the funnel **700** in an expanded state. Once positioned, the sleeve **112** can be retracted to cause the treatment assembly to expand. FIG. **12B** shows the sleeve **112** partially retracted to show the capture portion **200** of the treatment assembly expanded **100**. FIG. **12C** shows the sleeve **112** fully retracted to show the cutting portion **300** of the treatment assembly **100** expanded. Additionally or alternatively, aspiration may be applied to the sheath **110** with or without a funnel to further reduce the risk of embolization. The funnel **700** can be used with any of the systems detailed herein.

#### A. Example Capture Portions

[0119] Several capture portion configurations are shown and described with respect to FIGS. **13-16**. The cutting portions **300** are not shown in FIGS. **13-16** for ease of viewing the capture portions **200**. It will be appreciated that the present disclosure is not limited to the capture portions **200** depicted in the drawings.

[0120] FIG. **13** shows a capture portion comprising a braided or woven capture portion **200** having a closed distal end portion and an opening at its proximal end portion. The braid has a tapered shape with a cross-sectional dimension that decreases in a distal direction. The distal end of the braid may be cinched together with a tip component **245**, that constrains the ends of the braid wires together. The tip component **245** may have a tapered or rounded distal edge to reduce the trauma to vessel wall as the assembly **100** and/or device **101** is delivered to the treatment site, and to facilitate crossing the device through chronic thrombus site. The tip component **254** may also affix the actuation member **102** to the distal end of the capture device.

[0121] FIG. **14** shows a capture portion **200** comprising a laser-cut mesh structure having a closed distal end portion and an opening at its proximal end portion. The mesh structure has a tapered shape with a cross-sectional dimension that decreases in a distal direction. The closed distal portion may be cinched closed with a tip component **245** that constrains the ends of the cut tube pattern together. As above, the tip component **245** may have a tapered or rounded distal end and also may be used to affix the elongated member **102** to the closed end of portion member **200**.

[0122] FIG. **15** shows a capture portion **200** comprising a flexible, tapered distal region **202** coupled to a more rigid proximal region **204**. The distal region can comprise a braid, and the proximal region **204** can comprise a laser-cut tube or sheet of material. The proximal region **204** can have a greater chronic outward force and/or radial resistive force as compared to the distal region **202**, which can be beneficial for maintaining the patency of the proximal opening **206** once the assembly **100** is deployed in the vessel lumen.

[0123] In any of the embodiments disclosed herein, the capture portion **200** can include an open cell framework or body. According to several embodiments, the entrance to the capture portion **200** is slanted to facilitate capture of the obstructive material into the capture portion **200**. In some embodiments, a distal portion **200b** of the capture portion **200** is generally tubular (e.g., cylindrical), and the proximal end portion **200a** of the capture portion **200** tapers proximally down to the elongated member **102** (or component thereof). Likewise, the proximal end portion **200a** of the capture portion **200** can be generally tubular (e.g., cylindrical), and the distal portion **200b** of the capture portion **200** tapers distally down to the elongated member **102** (or component thereof).

[0124] In some embodiments, the capture portion **200** can have an open proximal end and a closed distal end. In some embodiments, the capture portion **200** has an open proximal end and an open distal end. In some embodiments, the capture portion has a closed proximal end and an open distal end.

[0125] In some embodiments, the capture portion **200** comprises a single expandable mesh structure. In some embodiments, for example as depicted in FIG. **16**, the capture portion **200** comprises a plurality of expandable structures **200a**, **200b**. The different structures can have the same or different shapes, can expand to the same or different maximum cross-sectional dimensions, and/or can comprise the same or different type of mesh structure (e.g., a braid, a laser-cut tube, a laser-cut sheet, a weave, etc.).

[0126] In some embodiments, the capture portion **200** comprises a mesh structure formed of an elastic or spring material (e.g. stainless steel or cobalt chromium alloy), superelastic material (e.g., Nitinol,) or other resilient or self-expanding material configured to self-expand when released from the restraining sleeve **112**. For example, in some embodiments the mesh is a self-expanding stent and/or stentriever. According to several embodiments, the mesh structure is a laser-cut tube or sheet of material. The material, for example, can comprise a resilient, elastic, and/or superelastic metal alloy or polymer. In some embodiments, the mesh structure comprises a plurality of braided wires (e.g., filaments, threads, sutures, fibers or the like) that have been interwoven to form a structure having openings. The mesh and/or braid can be composed of metals, polymers, composites, and/or biologic materials. Polymer materials can include Dacron, polyester, polypropylene, nylon, Teflon, polytetrafluoroethylene (PTFE), tetrafluoroethylene, polyethylene terephthalate, polylactic acid (PLA) silicone, polyurethane, polyethylene, polycarbonate, styrene, polyimide, PEBA, Hytrel, polyvinyl chloride, high-density polyethylene, low-density polyethylene, polyether ether ketone (PEEK), rubber, latex, and/or other suitable polymers known in the art. Other materials known in the art of elastic implants can also be used. Metal materials can include, but are not limited to, nickel-titanium alloys (e.g. Nitinol), platinum, cobalt-chromium alloys, stainless steel, tungsten or titanium, or alloys of any of these metals. In certain embodiments, metal filaments may be highly polished and/or surface treated to further improve their hemocompatibility. The capture portion **200** can be constructed solely from metallic materials without the inclusion of any polymer materials, solely from polymer materials without the inclusion of any metallic materials, or a combination of polymer and metallic materials.

[0127] In some embodiments, some or all of the wires of the capture portion **200** are drawn-filled tube (“DFT”) wires having a radiopaque core (e.g., platinum, tantalum, gold, tungsten, etc.) surrounded by an elastic or superelastic material (e.g., Nitinol, a cobalt-chromium alloy, etc.). The radiopaque core may comprise about 5% to about 50% (e.g., 10%, 15%, 20%, 25%, 30%, 35%, 40%, 45%) of the total-cross-sectional area of the individual wires. Moreover, some or all of the wires may have a wire diameter of about 0.003 inches to about 0.015 inches (e.g., 0.008 inches, 0.009 inches, 0.01 inches, etc.). In some embodiments, all of the wires have the same diameter, and in other embodiments some of the wires have different diameters.

#### B. Example Cutting Portions

[0128] According to several embodiments of the present technology, the cutting portion **300** may comprise separate cutting element, such as blades, attached to an expandable structure forming the cutting portion **300**. As described previously, the cutting portion may face distally or proximally as shown in FIGS. **6** and **7**, and also in FIGS. **8** and **9A**, respectively. The cutting portion may also be and may be fixed to capture portion as shown in FIGS. **10** and **11**. The expandable structure can be configured to angle the cutting elements such that, when the device is pulled towards and then through the obstructive material, the cutting elements cut the obstructive material away from the vessel wall. Continued withdrawal of the device then pulls the obstructive material into the capture portion **200**. An example of a such an expandable structure is shown in FIG. **17A**. Similar to the cutting portion **300** described with respect to FIGS. **3A** and **3B**, the cutting portion **300** in FIG. **17A** can be formed of a tube having two or more longitudinally-extending slots that create at least two arms **304** configured to bend radially outwardly when the tube is shortened. The longitudinal slots can be formed such that the arms **304** have joints **310** that bend when the arms **304** are expanded.

[0129] As shown in FIG. **17B**, the arms **304** of the cutting portion **300** may be canted towards each

other (rather than extending 180 degree apart) when expanded so that the arms **304** and attached blades **302** are at an angle  $\theta$  that better approximates the curvature of the vessel wall. This geometry facilitates cutting obstructive material (such as chronic thrombus material) away from the curved vessel wall. In some embodiments, the angle between the two arms is less than 180 degrees. In some embodiments, the angle is between 135 and 180 degrees.

[0130] As shown in FIG. **18A**, in some embodiments the cutting portion **300** can include a positioning arm **314** disposed circumferentially between the two arms **304** having cutting elements. As depicted in FIG. **18B**, when the cutting portion **300** is in an expanded state, the positioning arm **314** pushes against a portion of the vessel wall opposite the elongated member **102** and improves the position of the cutting elements for cutting and/or separating the obstructive material from the vessel wall.

[0131] FIGS. **19A** and **19B** are exploded and assembled views, respectively, of an example blade attachment assembly configured in accordance with several embodiments of the present technology. The assembly includes a portion of an arm **304** (or other portion of the cutting portion **300** and/or capture portion **200**), a blade **302**, and a coupler **1400**. Any portion of the cutting portions **300** and capture portions **200** described herein can include one or more openings, such as openings **324** shown extending through arm **304**. The openings **324** can be configured to receive a corresponding tab **320** extending from the blade **302** in a direction away from the sharpened edge of the blade **302**. The tabs **320** can have one or more openings **322** configured to receive a corresponding protrusion **1302** positioned along the coupler **1400**. The tabs **320** on the blades **302** are positioned through the openings **324** on the arm **304** such that the openings **322** on the tabs **320** are exposed on the non-receiving side of the arm openings **324**. The protrusions **1302a**, **1302b**, and **1302c** on the coupler **1400** are then positioned through the tab openings **322**, thereby locking the blade **302** onto the arm **304**. The protrusions **1302** may also include features which allow the width of the protrusion to be increased and locked after insertion through slots **324**, to further secure coupler **1400** and blade **302** to arm **304**, as illustrated in the end protrusions **1302a** and **1302b**.

[0132] In some embodiments, as shown in FIGS. **20A** and **20B**, the treatment assembly **100** includes an elongated shaft **102** comprising first and second elongated members **111**, **108** and a cutting portion **300** comprising a cutting element **2010** that extends helically and/or spirally around the longitudinal axis of the elongated shaft **102**. The second elongated member **108** can be configured to be positioned within a lumen of the first elongated member **111** and extends distally beyond a distal terminus of the first elongated member **111**. In some embodiments the axial positions of the first and second elongated members **111**, **108** are fixed, and in some embodiments the first and second elongated members **111**, **108** are slidably disposed relative to one another. In any case, the first and second elongated members **111**, **108** may be configured to rotate relative to one another. The treatment assembly **100** may optionally include a tapered distal tip **2020** at the distal end portion **108b** of the second elongated member **108**.

[0133] The cutting element **2010** can have a proximal end portion **2010a** at a distal end portion **111b** of the first elongated member **111**, a distal end portion **2010b** at a distal end portion **108b** of the second elongated member **108**, and an intermediate portion **2010c** extending between the proximal and distal end portions **2010a**, **2010b**. The intermediate portion **2010c** wraps around the longitudinal axis of the treatment assembly **100**. The cutting element **2010** is transformable between a collapsed configuration (FIG. **20A**) and an expanded configuration (FIG. **20B**). In the collapsed configuration, the cutting element **2010** is wound around the second elongated member **108** and has an outer diameter slightly larger than that of the second elongated member **108**. The cutting element **2010** may wrap around the longitudinal axis less than one turn (360 degrees) or more than one turn (including multiple turns). When the second elongated member **108** is rotated with respect to the first elongated member **111** (or vice versa) in a first direction, the cutting element **2010** unwinds and expands radially outwardly, as shown in FIG. **20B**. Rotation of the second elongated member **108** with respect to the first elongated member **111** (or vice versa) in a



second direction opposite the first direction forces the cutting element **2010** to wind down onto the second elongated member **108**, thereby radially collapsing the cutting element **2010**. The amount of rotation controls the amount of expansion, with the actual expansion percentage depending on, for example, the initial diameter of the elongated shaft **102** and the length of the cutting element **2010**. [0134] In some embodiments, the cutting element **2010** comprises a ribbon having a width *w* (labeled in FIG. **20A**) and longitudinal sides **2012a**, **2012b** (referred to collectively as “longitudinal sides **2012**”). The width can be constant along the length of the ribbon or may vary. One of the longitudinal sides **2012** can be proximally facing **2012a** and one of the longitudinal sides can be distally facing **2012b**. The ribbon can be made from, for example, one or more resilient and/or superelastic metals or polymers. One or both longitudinal sides **2012** of the ribbon may be configured to cut obstructive material in a vessel lumen. For example, in some embodiments one or both longitudinal sides **2012** of the ribbon are sharpened. Additionally or alternatively, one or both longitudinal sides **2012** of the ribbon may be serrated. One or both longitudinal sides **2010** may have both serrated and sharpened portions to enhance the cutting ability of the cutting element **2010** when moved (e.g., rotated and/or translated) through obstructive material. In some cases it may be beneficial to have the proximally facing longitudinal side **2012a** sharpened and/or serrated and the distally facing longitudinal side **2012b** atraumatic and/or rounded. This configuration enables the device to cut through obstructive material when pulled and/or rotated in a proximal direction while reducing the risk of trauma to the vessel wall during advancement of the treatment assembly **100** to a treatment site. According to several embodiments, only the portion of the proximally facing longitudinal side **2012a** that is proximal of the maximum diameter of the cutting element **2010** (when the cutting element **2010** is in an expanded state) is configured to cut through obstructive material. This configuration can reduce trauma to the native vessel wall as the treatment assembly **100** is pulled proximally and/or rotated through a treatment site.

[0135] Once the cutting element **2010** is expanded, the treatment assembly **100** can be rotated, translated, or both in order to cut obstructive material. In some embodiments, expansion of the cutting element **2010** can cut obstructive material. The cutting element **2010** can be repeatedly expanded and collapsed to engage and cut obstructive material. Movement of the cutting element **2010** to cut obstructive material may be performed manually by the user, facilitated by actuators on handle **12**, or performed automatically with motors on handle **12**.

[0136] While only a single cutting element **2010** is shown in FIGS. **20A** and **20B**, the present technology includes treatment assemblies comprising more than one wrapped cutting element (e.g., two wrapped cutting elements, three wrapped cutting elements, four wrapped cutting elements, etc.). As but one example, FIGS. **21A** and **21B** show a treatment assembly **100** having first and second cutting elements **2010** and **2014**. The treatment assembly **100** is shown in a collapsed state in FIG. **21A** and an expanded state in FIG. **21B**. Each of the cutting elements **2010**, **2014** has a proximal end portion **2010a**, **2014a**, respectively (**2010a** not visible in FIGS. **21A** and **21B**), disposed at the distal end portion **111b** of the first elongated member **111**, and a distal end portion **2010b**, **2014b**, respectively, disposed at the distal end portion **108b** of the second elongated member **108**. The proximal end portions **2010a**, **2014a** can be coupled to the first elongated member **111** at different circumferential locations that are spaced apart about the circumference of the first elongated member **111**. Whether two or more than two cutting elements are utilized, the spacing may be the same between adjacent cutting elements **2010** or may be different. In some embodiments, the proximal end portions **2010a**, **2014a** are coupled to the first elongated member **111** at diametrically opposed locations. In other embodiments, the proximal end portions **2010a**, **2014a** have other circumferential spacings. Likewise, the distal end portions **2010b**, **2014b** can be coupled to the second elongated member **108** at different circumferential locations that are spaced apart about the circumference of the second elongated member **108**. The spacing may be the same between adjacent cutting elements **2010** or may be different. In some embodiments, the distal end portions **2010b**, **2014b** are coupled to the second elongated member **108** at diametrically opposed

locations. In other embodiments, the distal end portions **2010b**, **2014b** have other circumferential spacings. In those embodiments having two or more cutting elements **2010**, the different cutting elements **2010** can have the same or different widths.

[0137] The diameter of the elongated shaft **102** (and/or one or more components thereof), the number of cutting elements **2010**, the angle at which the cutting element **2010** couples to the elongated shaft **102** (and/or one or more components thereof), the number of windings, and the width of the cutting element **2010** may be varied to create a desired expanded cutting configuration. As used herein with respect to the wrapped cutting elements, “length” is measured along the longitudinal axis of the cutting element **2010** which extends through a cross-section of the cutting element **2010**. In some embodiments, the elongated shaft **102** is 3 mm in diameter, the length of the cutting element **2010** is 22 mm, the width of the cutting element **2010** is 2 mm, and the cutting element **2010** is coupled to the elongated shaft **102** at an angle of 60 degrees. In the collapsed state, the cutting element **2010** can be tightly wound around the elongated shaft **102** two times. In the expanded state (e.g., after rotation of the second elongated member **108**), the cutting element **2010** is unwound until it makes only one turn around the elongated shaft **102**, which approximately doubles the maximum diameter of the cutting element **2010** (in this case, to about 6 mm).

According to some embodiments, the cutting element **2010** is coupled to the elongated shaft **102** at an angle of 60 degrees, is 33 mm long and wound around the elongated shaft **102** approximately three times. In the expanded state, the cutting element **2010** is unwound until it makes one turn around the elongated shaft **102**, which approximately triples the maximum diameter of the cutting element **2010** (in this case, about 9 mm). In some embodiments, the cutting element **2010** has a length of 40 mm, is coupled to the elongated shaft **102** at an angle of 45 degrees, and is wound around the elongated shaft **102** approximately three times. In certain embodiments, the cutting element **2010** has a length of 57 mm, is coupled to the elongated shaft **102** at an angle of 30 degrees, and is wound around the elongated shaft **102** approximately 3 times. In the latter two examples, the cutting element **2010** can be unwound to its fully expanded diameter in which it has one turn and a diameter that is about 3 times its starting diameter (e.g., around 9 mm). However, because the attachment angle is less acute (as compared to the earlier examples), but over a longer length due to the less acute attachment angle. For example, at the 60 degree attachment angle, the helix length is about 16 mm, for the 45 degree attachment angle, the helix length is about 28 mm, and for the 30 degree attachment length the helix length is 49 mm, all over 3 windings.

[0138] The fully expanded diameter of the cutting element **2010** also depends on the design of the attachment of the proximal and distal end portions **2010a**, **2010b** of the cutting element **2010** to the first and second elongated members **111**, **108**, respectively, of the elongated shaft **102**. For example, if an end of the cutting element **2010** were fixedly welded or soldered to the corresponding first or second elongated member **111**, **108**, the cutting element **2010** would remain tangent or near tangent to the elongated shaft **102** as it was unwound, creating one slope angle of helical taper on each end of the cutting element **2010**. Whereas, if the cutting element **2010** were allowed to angle away from the elongated shaft **102** to a certain degree or was freely allowed to hinge at the elongated shaft **102**, the helical taper would be another slope angle. Each type of helical taper would alter the fully unwound diameter to some extent.

[0139] In some embodiments, the width of the cutting element **2010** can be selected based on a desired gap length *g* (see FIG. 20A) between windings when the cutting element **2010** is fully wound (e.g., in a collapsed state). Additionally or alternatively, the width *w* (see FIG. 20A) of the cutting element **2010** can depend on how many cutting elements **2010** there are in the treatment assembly **100**. If the treatment assembly **100** has more than one, the width of the individual cutting elements **2010** will be less than if only a single cutting element **2010** were used. The greater the width *w* of a given cutting element **2010**, the more resistance it will have to bending distortion when under load, and the more effectively it can cut obstructive material. As demonstrated, there are trade-offs between the number of cutting elements **2010** and performance of each cutting

element **2010**.

[0140] As discussed, the second elongated member **108** may rotate with respect to the first elongated member **111** when expanding the treatment assembly **100**, and in some embodiments the second elongated member **108** may also translate with respect to the first elongated member **111** to axially compress or elongate the cutting element **2010**. The ability of the cutting element **2010** to be axially compressed or elongated depends in part on how the proximal and distal end portions **2010a**, **2010b** of the cutting element **2010** are coupled to the first and second elongated members **111**, **108** of the elongated shaft **102**, and whether the attachment enables the attachment angle to vary, as axial compression or elongation of the cutting element **2010** increases or decreases the angle of attachment. The ability to axially compress and elongate the cutting element **2010** while in the expanded state improves the cutting efficiency of the treatment assembly **100**. For example, the treatment assembly **100** may separate and capture obstructive material from a combination of one or more expanded wrapped cutting elements rotating, translating, expanding, and/or compressing through obstructive material of a treatment site. Additionally, the cutting element **2010** may be partially unwound for a first cutting pass, and then further unwound to a more expanded and/or fully expanded state for a second cutting pass, and so forth for multiple cutting passes until the desired effect is achieved.

[0141] In some variations, the cutting element **2010** is integral to the first elongated member **111**. For example, the first elongated member **111** can comprise a tubular member that has been cut in a helical and/or spiral pattern at its distal portion to create one or more helical strips. As such, the first elongated member **111** and the cutting element **2010** can comprise the same material. The distal end portion **2010b** of the cutting element **2010**/distal end portion **111b** of the first elongated member **111** can be fixed to the distal end portion **108b** of the second elongated member **108**. When the second elongated member **108** is rotated with respect to the first elongated member **111**, the cut strip (now the cutting element **2010**) is unwound and expands outward. The foregoing embodiments advantageously do not require any attachment design and therefore reduce the number of manufacturing processes.

[0142] In another variation, the cutting element **2010** is formed from one material that has the required mechanical properties including the ability to be wound and unwound, sharpened, and hold sufficient rigidity to have an effective cutting action when manipulated as described above, and the first elongated member **111** is formed from a separate tube. The first elongated member **111** is then attached to a second tube that extends proximally from the treatment assembly **100** and that has suitable properties for a catheter shaft component, for example cost, flexibility, etc.

[0143] There are many possible methods to attach the proximal end portion **2010a** of the cutting element **2010** to the first elongated member **111** and the distal end portion **2010b** to the second elongated member **108**, for example via soldering, welding, gluing, mechanical attachment, or some combination thereof. As noted above, the method of attachment can affect the specific expansion performance and strength of attachment of the cutting element **2010** when it is expanded and used to remove obstructive material.

[0144] In some embodiments, for example as shown in FIGS. **22A**, **22B**, and **22C**, the distal end portion **2010b** of the cutting element **2010** is mechanically captured between the distal end portion of the second elongated member **108** and a securing element **2220**. The distal end portion **2010b** of the cutting element **2010** can be coupled to a cylindrical coupler **2210** (e.g., a dowel, a tube, or other cylindrical component) and extend from the coupler **2210** at an angle. The angle between the coupler **2210** and the cutting element **2010** forms the angle at which the cutting element **2010** extends from the second elongated member **108**. In some embodiments, the coupler **2210** is integral with the cutting element **2010**. For example, the coupler **2210** can be constructed by rolling the cutting element **2010** into a tight cylinder at the distal end portion **2010b**. In some embodiments, the coupler **2210** is a separate component that is attached to the distal end portion **2010b** of the cutting element **2010**. In any case, the coupler **2210** can be configured to be received

within a groove **2230** extending along a distal portion of the second elongated member **108**. The securing element **2220** can be a band that is configured to be slidably disposed over the outer surface of the second elongated member **108**. The securing element **2220** can have a slot **2225** extending along less than its entire length. The slot **2225** can be continuous with an opening at a distal end of the securing element **2220**.

[0145] As shown in FIG. **22B**, the cutting element **2010** can be mechanically captured at the distal end portion of the second elongated member **108** by inserting the coupler **2210** into the groove **2230** in the second elongated member **108**, and sliding the securing element **2220** upward to capture the coupler **2210** within the slot **2225**. The slot **2225** in the securing element **2220** can be wide enough to allow the cutting element **2010** to extend radially outwardly therethrough, but too narrow to allow passage of the coupler **2210**. The coupler **2210** is configured to rotate within the groove **2230**, thereby allowing the extension angle of the cutting element **2010** (relative to the second elongated member **108**) to vary. The width of the slot **2225** may be varied to allow a varied range of motion of the coupler **2210** (and thus the cutting element **2010**) in the groove **2230** when the treatment assembly **100** is expanded. In FIG. **22C** the groove **2230** is shown extending proximally beyond the securing element **2220**, but in other embodiments the groove **2230** may terminate at more distal locations (including aligned with or distal to a proximal terminus of the securing element **2220**). In some embodiments, the coupler **2210** is fixed within the groove **2230** such that it cannot rotate relative to the second elongated member **108**.

[0146] The second elongated member **108** can have a tapered distal tip **2020** at its distal end. The tapered distal tip **2020** is removed from view in FIG. **22B** to show the coupler **2210** in the groove **2230**, but shown in FIG. **22C** to illustrate how the coupler **2210** and cutting element **2010** are mechanically captured. The distal tip **2020** can prevent distal axial movement of the securing element **2220** and the coupler **2210**, thereby securing the coupler **2210** within the slot **2225** in the securing element **2220**. In some embodiments, the distal tip **2020** has a maximum diameter that is greater than the diameter of the second elongated member **108**. In some embodiments, the coupler **2210** is secured within the slot **2225** via other means, such as a non-tapered distal cap, tube, or other component to prevent securing element from sliding out of the slot **2225**. In these and any embodiments disclosed herein, the second elongated member **108** can have a lumen **22** extending therethrough. The distal tip **2020** can also include a lumen that is an extension of lumen **22**.

[0147] The securing element **2220** and/or second elongated member **108** can include one or more securing means so that when the securing element **2220** is in position over the coupler **2210**, the axial and rotational position of the securing element **2220** (and thus axial position of the coupler **2210**) is fixed relative to the second elongated member **108**. For example, the securing element **2220** may have one or more side holes (not shown) and the second elongated member **108** may have one or more protrusions that spring radially outwardly into the side holes when the side holes are aligned with the protrusions. In some embodiments, the securing element **2220** includes one or more tabs (not shown) which can be pushed radially inward to lock into one or more receptacles in the second elongated member **108**. Additionally or alternatively, the securing element **2220** can be soldered, welded, or glued to the second elongated member **108** to hold the securing element **2220** in place.

[0148] The proximal end portion **2010a** of the cutting element **2010** may be mechanically captured at a distal portion of the first elongated member **111**. For example, the first elongated member **111** may include a groove similar to the slot **2225** on the securing element **2220**. In such embodiments, the second elongated member **108** can have a recess in its outer surface so that the second elongated member **108** can rotate freely with respect to the first elongated member **111** to expand and collapse the cutting element(s) **2010**. As previously mentioned, in some embodiments the cutting element **2010** is integral with and an extension of the first elongated member **111**.

[0149] The coupler **2210** can have other shapes and configurations. For example, in some embodiments the distal end portion **2010b** of the cutting element **2010** may be cut (e.g., laser cut)

to have a T-shaped distal end that is configured to be received within the slit **2225** of the securing element **2220**. The T-shaped distal end (or portion thereof) is then trapped in place between the securing element **2220** and the second elongated member **108**. The treatment assembly **100** can include a distal tip to secure the T-shaped distal end in place.

[0150] In any of the embodiments including one or more cutting elements **2010**, the treatment assembly **100** may optionally include an expandable member (e.g., a balloon) (not shown) disposed radially inwardly of the cutting element **2010**. The expandable member can be configured to be expanded underneath the already-expanded (partially or completely) cutting element **2010** to add radial force to the cutting element **2010** and prevent or reduce distortion of the cutting element **2010** as the treatment assembly **100** is translated and/or rotated through the treatment site. The expandable member may be aligned with only the intermediate and/or distal portions of the cutting element **2010** (i.e., and not the proximal portion), so as not to interfere with the cutting action of the cutting element **2010** on the proximal aspect of the treatment assembly **100**.

[0151] In some embodiments, for example as shown in FIGS. **23A** and **23B**, the treatment device includes an elongated shaft **102** comprising first and second elongated members **111**, **108** and a cutting portion **300**. The first elongated member **111** comprises an elongated tube **2320**, a distal band **2330**, and two or more strips **2350** connecting the proximal tube **2320** to the distal band **2330**. In a collapsed state, the strips **2350** may be parallel to the axis of the elongated shaft **102**, or may be at a slight angle (e.g., between 0 and 20 degrees) from the axis of elongated shaft **102** (as shown in FIG. **23A**). The second elongated member **108** can be configured to be slidably disposed within a lumen of the first elongated member **111**. The second elongated member **2003** can extend through the proximal tube **2320** and the portion underlying the strips **2350**, and distally beyond the distal band **2330**. The treatment assembly **100** can comprise a distal tip **2020** coupled to the distal end of the second elongated member **2003** that has a maximum diameter larger than the diameter of the distal band **2330**. In some embodiments, the distal tip **2020** is locked to the distal band **2330** of the first elongated member **111** by means of locking elements on the second elongated member **108** and distal band **2330**. For example, the distal band **2330** can have side holes and the second elongated member **108** may have protrusions that spring outwards into the side holes. In some embodiments, the distal band **2330** has tabs which can be pushed radially inward to lock into receptacles in the second elongated member **108**. Additionally or alternatively, the second elongated member **108** and distal band **2330** can be attached, for example, via welding, glue, or soldering.

[0152] In any case, when the second elongated member **108** is pulled proximally, the distance between the distal band **2330** and the distal end of the proximal tube **2320** shortens and the strips **2350** on the first elongated member **111** bow radially outwardly to form expanded arms, as shown in FIG. **23B**. In those embodiments where the strips **2350** are attached to the first elongated member **111** at an angle (as shown in FIGS. **23A** and **23B**), the arms are somewhat twisted in the plane perpendicular to the elongated shaft **102**. The strips **2350** might have one or more edges that are sharpened and/or serrated. When expanded, the treatment assembly **100** may be rotated and/or translated to act as rotary blades to remove obstructive material from the treatment site. The amount of expansion depends on the amount of translation of the second elongated member **108** relative to the first elongated member **111**. In use, the arms may be partially extended outwards for a first pass, and then further expanded for a second pass, etc., to remove obstructive material more effectively.

[0153] The strips may be integral to the first elongated member **111**. As seen in FIG. **23A**, the first elongated member **111** can be cut (e.g., laser cut) to create one or more strips, parallel to or at a slight angle to the axis of the elongated shaft **102**. Optionally the cut pattern includes recessed portions **2360** along the length of one, some, or all of the strips **2350** to urge the strip **2350** to preferentially bend at the recessed portions **2360**. The recessed portions **2360** may be at the midpoint of the strip **2350**, to create a symmetric expanded geometry, or may be biased towards the

distal end of the strip **2350** to create an asymmetrical expanded geometry, as illustrated in FIG. **24**. The latter configuration may allow for a better cutting angle of the strip cutting edge against the obstructive material.

[0154] In some embodiments, the strips **2350** are not the cutting element. Instead, as seen in FIG. **25**, the strips **2350** contain tabs or other features that allow a second cutting element, such as a blade **1010**, to be attached to each strip **2350**. In this variation, the first elongated member **111** may be made from one material that is configured to be expanded and collapsed, and the blade **1010** may be made from a second material that is suited to have a sharpened blade edge. The blade **1010** may be secured to strips **2350** by means of a separate latch component (not shown). Additionally or alternatively, the blade **1010** may be soldered or welded to the strip **2350**.

[0155] In some instances, it may be desirable to have an additional cutting element orientated in the opposite direction of the existing cutting element to provide a counter-force during cutting of obstructive material. For example, in some embodiments the device may include one or more inner cutting elements (such as cutting element **2010**) positioned inside one or more outer cutting elements (such as cutting element **2010**). The inner cutting elements can be substantially linear (for example as shown in FIG. **23**) or may be helical and/or spiral (for example as shown in FIGS. **20A** and **20B**). The outer cutting elements can be substantially linear (for example as shown in FIG. **23**) or may be helical and/or spiral (for example as shown in FIGS. **20A** and **20B**). In some embodiments, the device **101** may comprise an inner elongated member **108**, an outer elongated member **111** with one or more cutting element(s) **2010**, and an elongated member located between the inner and outer elongated members **108**, **111** that comprises one or more cutting elements. In such embodiments, the cutting elements can be integral to the outer and intermediate elongated members, or may be separate elements attached to the outer and intermediate elongated members. The handle **12** of the device **101** (FIG. **1**) may have an actuator that controls the rotational movement of the outer and middle elongated members. For example, an actuator(s) on the handle **12** may be configured to turn the outer elongated member **111** in one direction while either keeping the inner cutting element (carried by the intermediate elongated member) stationary or rotating the inner cutting element in the opposite direction. In some embodiments, for example as shown in FIG. **26**, a cutting portion **300** of the treatment assembly **100** comprises an inner elongated member **108**, an outer elongated member **111** with one or more attached or integral cutting elements **2010**, and an intermediate member **2323** located between the inner elongated member **108** and the outer elongated member **111**, with corresponding cutting elements **2326** (labeled individually in FIG. **26** as **2326a-2326d**). In such embodiments, the handle **12** (FIG. **1**) can include one or more actuators to rotate the outer elongated member **111** in one direction with respect to the inner elongated member **108** while shortening the intermediate elongated member **2323** to expand the cutting elements **2326** radially outwardly during deployment. The handle **12** can be configured to further actuate the outer and intermediate elongated members **111**, **2326** to rotate and/or translate to cut the obstructive material. One, some, or all of the cutting elements **2010** can have a sharpened edge, and one, some, or all of the cutting elements **2326** can have a sharpened edge. In some embodiments, only the outer cutting elements **2010** or only the inner cutting elements **2326** may have a sharpened edge. In those embodiments including inner and outer cutting element(s) with sharpened edges, the sharpened edges can be configured to face each other. As such, the inner and outer cutting elements **2326**, **2010** can be configured to trap obstructive material as they move towards one another to cut the obstructive material. The inner and outer cutting elements **2326**, **2010** can thus provide a counterforce to the cutting force (or any force) exerted on the obstructive material by the other.

[0156] In a similar fashion, the embodiment shown in FIGS. **23A** and **23B** could have one or more expandable cutting elements located inside the outer cutting elements. The treatment assembly **100** can have an intermediate elongated member located between the inner elongated member **108** and the outer elongated member **111**, with corresponding expandable cutting elements. The inner and outer cutting elements could be configured such that when expanded, the cutting edges of the inner

cutting elements are canted in one direction and the cutting edges of the outer cutting elements are canted in the opposite direction. As above, the handle **12** can have an actuator that controls the rotational movement of the outer and intermediate elongated members. For example, the handle **12** may be configured to turn the outer elongated member **111** in one direction while either keeping the intermediate member stationary or rotating the intermediate member in the opposite direction.

[0157] In some embodiments, the cutting portion **300** can be configured as provided in FIGS. **27A-27D**. In such embodiments, the cutting portion **300** can be made from a superelastic tube such as nitinol or others, with a cut pattern than forms multiple (2 or more) arms **1502** protruding from the distal end of the nitinol tube. The arms **1502** can be heat-set to expand outward in a larger diameter than the base tube once a sleeve **112** is retracted. One, some, or all of the arms **1502** can be shape set to assume the shape shown in the side views of FIGS. **27C** and **27D**. As shown in FIG. **27C**, the arm **1502** can have a first substantially linear portion **1502a** extending from the tube, a second portion **1502b** extending distally and radially outwardly from the first portion **1502a**, and a third, distal-most portion **1502c** extending distally and radially inwardly from the second portion **1502b**. The curve between the second and third portions **1502b**, **1502c** forms an atraumatic surface that can slide along the vessel wall. In such embodiments, the cutting element **302** can project distally from the distal terminus **1504** of the arm **1502** and along a dimension that is substantially parallel to the vessel axis and along the direction of movement of the arm **1502** (indicated by arrow A). In some embodiments, for example as represented by FIG. **27D**, one, some, or all of the arms **1502** include a fourth portion **1502d** extending distally from the third portion **1502c** along a dimension that is substantially parallel to the vessel axis and along the direction of movement of the arm **1502** (indicated by arrow A).

[0158] One, some, or all of the arms **1502** can have a beveled and sharpened point. Like the cutting portion **300** in FIGS. **8-9B**, the cutting portions in the embodiments represented by FIGS. **27A-27D** form a circumferential pattern, although since the blades do not overlap in the collapsed configuration, the cuts will not be as close together. However, because they are not required to overlap in the collapsed configuration, the collapsed profile takes up less space, which can be advantageous for an endovascular device.

[0159] FIGS. **28A** and **28B** are isometric views of a cutting portion configured in accordance with several embodiments of the present technology. FIG. **28A** shows the cutting portion in a collapsed state. FIG. **28B** shows the cutting portion in an expanded state. The system **10** and/or assembly **100** of FIGS. **28A** and **28B** can be generally similar to the system **10** and/or assembly **100** of FIGS. **27A-27D**, except in FIGS. **28A** and **28B**, the system **10** includes a cover **1600** positioned over all or a portion of the cutting portion **300**. The cover **1600** can be a braid, a weave, a fabric, a polymer material, etc.

### C. Example Methods of Use

[0160] Various approaches may be used to gain intravascular access to the obstructive material within the vessel lumen. In some embodiments, the method includes percutaneously accessing the blood vessel lumen (such as a vein) with a guidewire, advancing the introducer sheath (such as any of the introducers disclosed herein) over the guidewire and through the access site, and inserting a treatment device (such as any of the treatment devices disclosed herein) through a lumen of the introducer sheath into the blood vessel lumen. The distal portion of the treatment device containing the treatment assembly can be advanced to a target treatment site within the vessel lumen. The access site can be at, for example, a femoral vein, an internal jugular vein, or a popliteal vein. In some embodiments the method includes aspirating or infusing a thrombolytic agent into or from the blood vessel before, during, or after extraction of the obstructive material.

[0161] In some embodiments, a guidewire may first be inserted into the blood vessel lumen and advanced through the obstructive material such that a distal terminus of the guidewire is distal of the obstructive material. Next, the introducer **103** (FIG. **1**) may be delivered over the guidewire so that a distal portion of the introducer **103** (FIG. **1**) is positioned within the vessel lumen proximal

of the obstructive material. In those introducer **103** embodiments which include a funnel at the distal end of sheath **110**, the funnel **700** be expanded into apposition with the blood vessel wall. The method can continue by inserting the treatment device **101** over the guidewire, through the introducer **103**, and into the vessel lumen. In some embodiments, the treatment device **101** can be advanced through the obstructive material such that some or all of the treatment assembly **100** of the treatment device **101** is distal of the obstructive material. In some embodiments, the treatment assembly **100** can be advanced to a location in the vessel such that some or all of the treatment assembly **100** is proximal of the obstructive material.

[0162] According to some embodiments, the treatment assembly **100** may be contained within the sleeve **112** during delivery. Once the distal portion of the treatment device **101** is positioned at a desired location relative to the obstructive material at the treatment site, the sleeve **112** of the device **101** can be pulled proximally relative to the treatment assembly **100** (or the treatment assembly pushed distally relative to the sleeve **112**) to release one or both of the cutting and capture portions of the treatment assembly **100**, thereby allowing the capture portion **200** and/or cutting portion **300** to self-expand. In some embodiments, the treatment assembly **100** may be expanded distal of the obstructive material such that no portion of the capture portion **200** and no portion of the cutting portion **300** engages the obstructive material during and/or immediately after expansion. In some embodiments, at least a portion of one or both of the capture portion **200** and the cutting portion **300** self-expand within the obstructive material. In some embodiments, the capture portion **200** is distal to the obstructive material and the cutting portion **300** is proximal to the obstructive material. As described elsewhere herein, in some embodiments one or both of the capture portion **200** and the cutting portion **300** are not self-expanding and require mechanical actuation.

[0163] While the capture and cutting portions **200**, **300** are in an expanded configuration, the cutting portion **300** can be pushed towards the capture portion **200** and/or the capture portion **200** can be pulled distally towards the cutting portion **300** (either serially, simultaneously or back and forth). Alternately, the capture and cutting portions **200** and **300** can be pulled in a proximal direction to simultaneously or serially cut and capture the obstructive material. Before, during, or after such movement, the entire treatment assembly **100** can be pushed distally or pulled proximally towards the sheath **110**. As the assembly **100** and/or device **101** is pulled proximally, the blades **302** of the cutting portion **300** cut through the obstructive material in a direction generally parallel to the longitudinal axis of the blood vessel, thereby separating the obstructive material from the vessel wall and/or other obstructive material. The capture portion **200** collects the separated obstructive material and is then pulled into the sheath **110** for removal from the patient. As previously mentioned, in some embodiments the system **10** does not include an introducer sheath. In embodiments with a funnel **700** on the distal end of sheath **110**, the funnel helps to capture all the obstructive material as the treatment device is pulled into the sheath and from them out of the of the blood vessel. In embodiments with aspiration capabilities, aspiration can be applied to one, some or all of the elongated shafts associated with the treatment system (e.g., the sheath **110**, the sleeve **112**, the outer member **111**, etc.) to reduce the chance of embolic complications.

[0164] As previously mentioned, both the capture portion and the cutting portion may be self-expanding, so that when the sheath is retracted, the capture and cutting portions self-expand into the expanded state. Additionally or alternatively, the capture portion and/or the cutting portion may be expanded by active actuation. For example, one or both of the capture portion **200** and the cutting portion **300** may be coupled to an actuation member that, when actuated by the operator (via a handle at a proximal portion of the treatment device **101**), causes the capture portion **200** and/or the cutting portion **300** to partially or fully expand. For example, in some embodiments the treatment device includes an actuation member that is coupled to a distal end region of a corresponding one of the capture portion **200** or cutting portion **300** and when pulled, shortens the length of that component which has the effect of expanding that component. In those embodiments



where the capture portion **200** and the cutting portion **300** are integrated within a single expandable component, a single actuation member may cause both to expand and/or collapse together. Likewise, in those embodiments where the capture portion **200** and the cutting portion **300** are separate components, a single actuation member may cause both to expand and/or collapse together. In some embodiments where the capture portion **200** and the cutting portion **300** are separate components, each of the capture portion **200** and the cutting portion **300** may be independently actuatable, whether by separate actuation members or by different mechanisms or timings via the same actuation member.

[0165] According to various embodiments, one of the capture portion **200** or the cutting portion **300** is self-expanding and the other of the capture portion **200** or the cutting portion **300** requires active expansion. For example, the capture portion **200** can self-expand when the sheath is retracted, while the cutting portion **300** requires expansion with an actuation member. In this example, the cutting portion **300** may be expanded for only the first portion of the thrombus removal step to facilitate initial removal of the thrombus from the wall, but is then retracted during the remainder of the thrombus removal step as it is no longer needed.

[0166] According to several embodiments, the treatment assembly **100** of the treatment device **101** is positioned distal to the obstructive material, expanded, and then manipulated such as rotated, translated, or both, to separate obstructive material from the wall. For example, the treatment assembly can comprise one or more cutting elements (FIGS. **20A**, **20B**, **21A**, etc.), and the inner elongated member is rotated to expand the cutting element to some or all of its expansion amount, and then manipulated to separate obstructive material from the treatment site. The treatment device can be readvanced for a further expansion and manipulation, in some cases to a larger expansion amount, for additional separation of obstructive material.

[0167] At any point before, during, or after the foregoing methods, aspiration may be applied at the treatment site to further reduce the risk of embolization.

[0168] At any point before, during, or after the foregoing methods, the treatment area may be flushed with or without aspiration to assist in separating and capturing occlusive material. The flush may be applied through treatment device via a fluid line connected to a flush source. Alternately, flush may be applied from the side arm of the introducer sheath.

[0169] In some embodiments, both aspiration and flush may be applied to the treatment site. For example, an aspiration source may be connected to the treatment device and a flush source may be connected to the introducer **103**. Conversely, an aspiration source may be connected to the introducer **103** and a flush source may be connected to the treatment device **101**. Alternately, both are connected to the treatment device **101**, or both are connected to the introducer **103**.

[0170] During separation and/or removal of obstructive material from a treatment site by the treatment assembly, the distal capture sheath may capture and contain any material that has not been aspirated or otherwise removed by treatment device.

[0171] During or after separation and/or removal of obstructive material from a treatment site by the treatment assembly, the treatment device can be removed from the introducer sheath **110** (FIG. **1**). Aspiration applied through the introducer sheath **110** can reduce embolic particles during device removal. Inclusion of a funnel on the introducer sheath **110** may also reduce the possibility of embolic particles remaining in the vasculature as the treatment device is removed.

[0172] At any point before, during, or after engagement of the cutting elements with the obstructive material, the treatment device and/or treatment assembly can be configured to deliver energy at the treatment site. For example, the treatment device and/or treatment assembly may be configured to vibrate and/or emit ultrasonic energy.

## Conclusion

[0173] Although many of the embodiments are described above with respect to systems, devices, and methods for retrieving clot material from a blood vessel lumen, the technology is applicable to other applications and/or other approaches, such as removal and/or modification of other structures

within any body lumen. Moreover, other embodiments in addition to those described herein are within the scope of the technology. Additionally, several other embodiments of the technology can have different configurations, components, or procedures than those described herein. A person of ordinary skill in the art, therefore, will accordingly understand that the technology can have other embodiments with additional elements, or the technology can have other embodiments without several of the features shown and described above with reference to FIGS. 1-28B.

[0174] The descriptions of embodiments of the technology are not intended to be exhaustive or to limit the technology to the precise form disclosed above. Where the context permits, singular or plural terms may also include the plural or singular term, respectively. Although specific embodiments of, and examples for, the technology are described above for illustrative purposes, various equivalent modifications are possible within the scope of the technology, as those skilled in the relevant art will recognize. For example, while steps are presented in a given order, alternative embodiments may perform steps in a different order. The various embodiments described herein may also be combined to provide further embodiments.

[0175] As used herein, the terms “generally,” “substantially,” “about,” and similar terms are used as terms of approximation and not as terms of degree, and are intended to account for the inherent variations in measured or calculated values that would be recognized by those of ordinary skill in the art.

[0176] Moreover, unless the word “or” is expressly limited to mean only a single item exclusive from the other items in reference to a list of two or more items, then the use of “or” in such a list is to be interpreted as including (a) any single item in the list, (b) all of the items in the list, or (c) any combination of the items in the list. Additionally, the term “comprising” is used throughout to mean including at least the recited feature(s) such that any greater number of the same feature and/or additional types of other features are not precluded. It will also be appreciated that specific embodiments have been described herein for purposes of illustration, but that various modifications may be made without deviating from the technology. Further, while advantages associated with certain embodiments of the technology have been described in the context of those embodiments, other embodiments may also exhibit such advantages, and not all embodiments need necessarily exhibit such advantages to fall within the scope of the technology. Accordingly, the disclosure and associated technology can encompass other embodiments not expressly shown or described herein.

## Claims

1. A system for modifying and/or removing obstructive material from a lumen of a blood vessel, the system comprising: a first elongated member having a proximal portion and a distal portion configured to be intravascularly positioned at a treatment site in the blood vessel adjacent the obstructive material, wherein the first elongated member defines a lumen extending therethrough; a second elongated member having a proximal portion and a distal portion configured to be intravascularly positioned at the treatment site, wherein the second elongated member is rotatably disposed within the lumen of the first elongated member; and a helical ribbon cutting element configured to cut obstructive material at the treatment site, the helical ribbon cutting element having a proximal end region at the distal portion of the first elongated member, a distal end region at the distal portion of the second elongated member, a sharpened proximal facing longitudinal edge, an atraumatic or blunted distal facing longitudinal edge; and an expandable tapered wire mesh with proximal opening and a closed distal portion, and a cross-sectional dimension therebetween that decreases in a distal direction and configured to be inserted through and out of the lumen of the first elongated member.

2. The system of claim 1, wherein the rotation of the second elongated member relative to the first elongated member causes the helical ribbon cutting element to expand away from a longitudinal axis of the second elongated member.

3. The system of claim 1, wherein the helical ribbon cutting element is wound more than one turn.
  4. The system of claim 1, wherein the helical ribbon cutting element comprises a resilient metal alloy.
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