

Figure 1

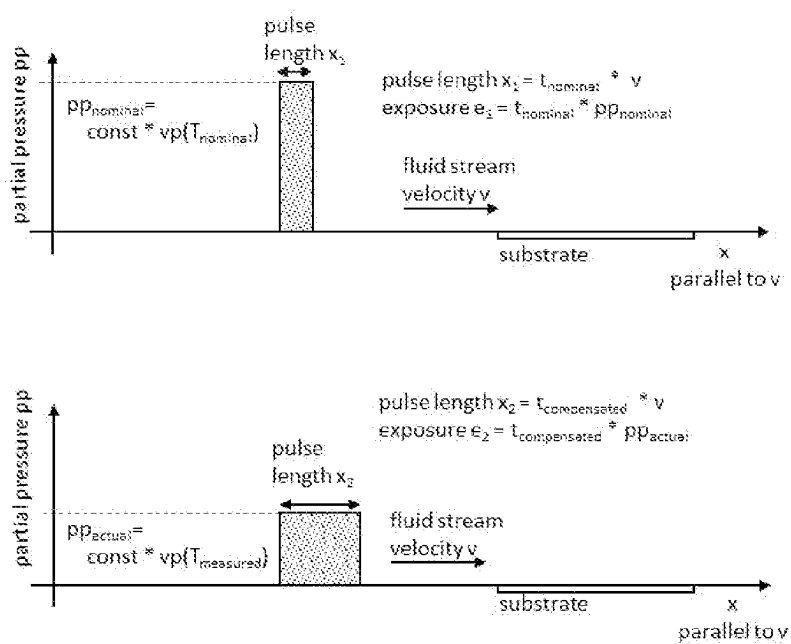


Figure 2

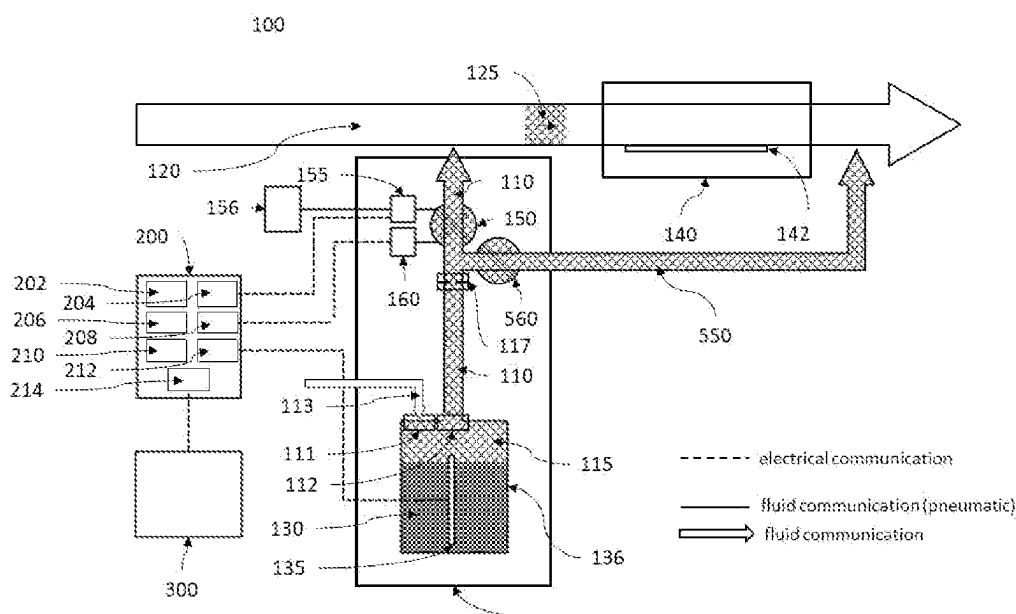


Figure 3

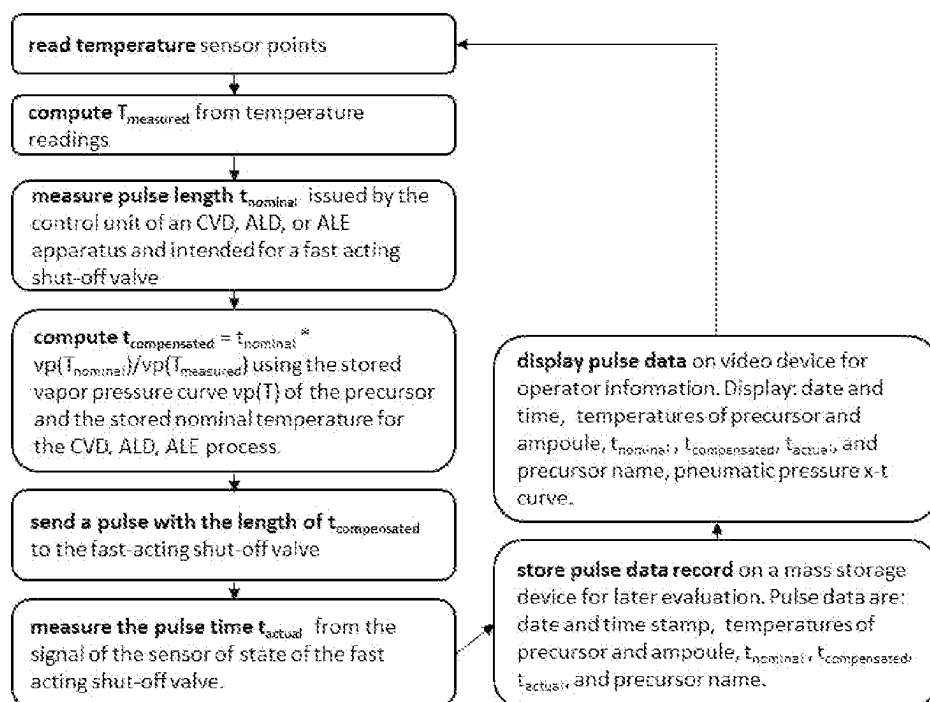


Figure 4

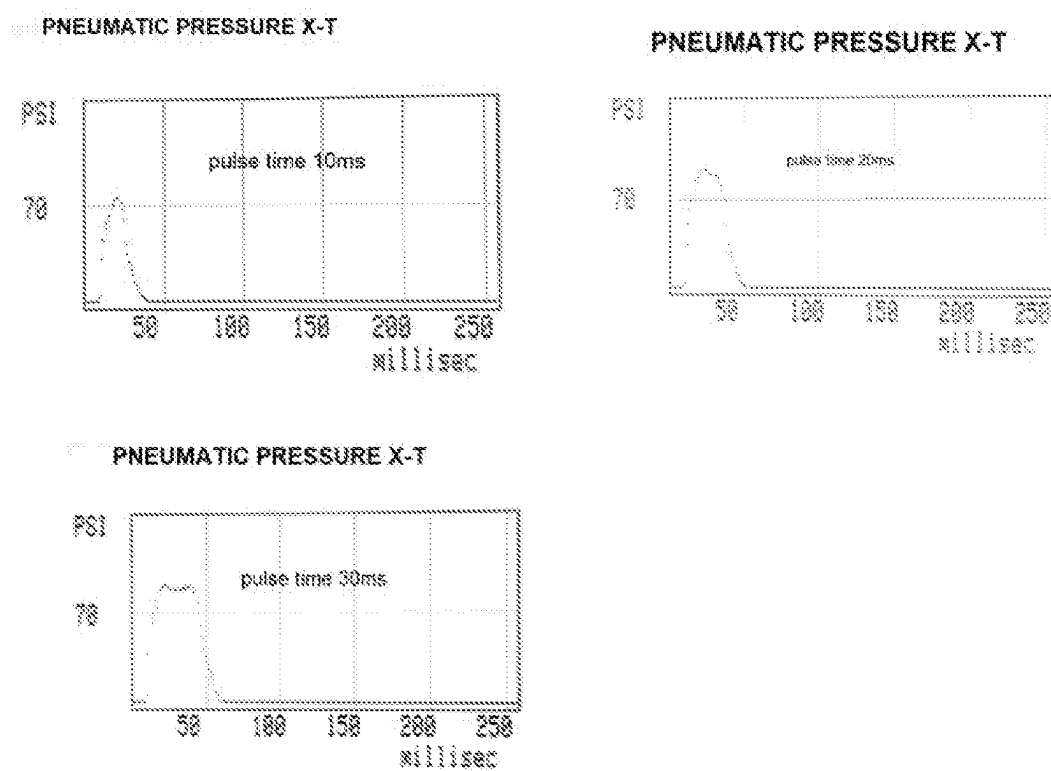


Figure 5

PRECURSOR DELIVERY SYSTEM

CROSS-REFERENCE TO RELATED APPLICATIONS

[0001] This application claims the benefit of U.S. Provisional Application No. 63/484,562, filed Feb. 13, 2023, entitled "Precursor Delivery System," the entire contents of which is hereby incorporated herein by reference.

PRIOR ART

[0002] U.S. Pat. No. 11,560,624 B2

BACKGROUND OF THE INVENTION

[0003] Chemical Vapor Deposition CVD and Atomic Layer Deposition ALD and Atomic Layer Etching ALE rely on the sequencing of multiple controlled fluid streams. These fluid streams are generally gaseous. The apparatus that is used for CVD, ALD, and ALE provides the plumbing to generate a plurality of such controlled fluid streams-such as suitable controls, conduits, meters, transducers, pumps, heating and cooling. Generally, the largest of those streams is a continuous stream of a gas that is chemically inert with respect to the CVD, ALD, and ALE process under consideration. This fluid stream is called the main fluid stream and has a predetermined velocity. Further, the apparatus provides the plumbing to add a plurality of reactive fluid streams to the main fluid stream for individually predetermined amounts of time. This results in a composite fluid stream. The apparatus provides tubing and pipes to direct this composite fluid stream across a surface of a substrate that is located inside a reaction chamber which is also part of the apparatus. The composition of the composite fluid stream changes according to the predetermined combination of the individual streams. Further, the apparatus provides a means to maintain the substrate at a predetermined temperature.

[0004] The composite fluid stream chemically reacts with the surface of the substrate. In CVD and ALD the reaction forms a solid material layer. The thickness of this layer or the coverage of the substrate with respect to a constituent that makes up the layer is proportional to the partial pressure of the respective precursor in the fluid stream and the time that this precursor is present in the composite fluid stream.

[0005] In CVD and ALD the composition of the solid layer that is formed in this process can be controlled by two methods. A first method comprises the exposure of the substrate to a fluid stream of a predetermined composition. The constituent atoms of the solid layer are incorporated proportional to their reactivity with the substrate surface and their partial pressure in the stream.

[0006] A second method comprises the sequential exposure of the substrate to only one precursor at a time. The exposure to a first precursor for a first predetermined period of time is followed by the exposure to a second precursor for a second predetermined period of time followed by the exposure to a third, fourth or more precursors as needed to make the desired solid layer.

[0007] In ALE the chemical reaction removes material layers from the surface. The amount of material removed depends on the partial pressure of a reactive gas in the gas phase. The exposure to a first reactive gas (called a first precursor in CVD and ALD terms) forms a first activated surface on a substrate. The subsequent exposure of the first activated surface to a second reactive gas (precursor)

removes one layer of the material of the substrate and restores the initial surface and the cycle is repeated.

[0008] The CVD, ALD and ALE apparatus provides the sensors and actuators to set a predetermined pressure in the reaction chamber. The pressure of the streams inside the reactor chamber ranges from 50 Pa to 100,000 Pa and the velocity of the stream normal to a cross section of the reaction chamber ranges from 0.01 m s^{-1} to 10 m s^{-1} .

SUMMARY OF THE INVENTION

[0009] The invention is used in the field of Chemical Vapor Deposition and Atomic Layer Deposition and more broadly in any application where a fluid stream that contains one or more reactive chemicals covers or modifies the surface of a substrate. The invention describes an apparatus and a method to compensate for an error in the partial pressure of a reactive species in the fluid stream. The compensation is based on the theory that for a chemical vapor deposition and for an atomic layer deposition the number hits by reactive gas species on the surface of the substrate needs to be precisely controlled. The present invention measures the concentration of a given species in the gas phase by measuring the vapor pressure of the liquid or solid source of that species. It subsequently divides a predetermined nominal (also recipe, target, intended) concentration by the measured concentration to obtain a factor f . Analysis yields that f is the [vapor pressure of source at nominal temperature] divided by the [vapor pressure of source at the measured temperature]. The factor f is subsequently applied to the nominal (also recipe, target, intended) duration of exposure pulse. In other words: if the concentration (or temperature) of a precursor species is higher then intended the time of the exposure time to the substrate surface is shortened accordingly. If the concentration (or temperature) of a precursor species is lower than intended the exposure time to the substrate is extended.

BRIEF DESCRIPTION OF DRAWINGS

[0010] FIG. 1 shows a first embodiment of a precursor delivery system

[0011] FIG. 2 shows the compensation principle

[0012] FIG. 3 shows a second embodiment of a precursor delivery system

[0013] FIG. 4 shows the flow diagram for a method to operate a precursor delivery system

[0014] FIG. 5 shows the response of a fast acting shut-off valve to a pneumatic pilot pulse

DETAILED DESCRIPTION OF THE INVENTION

[0015] A delivery system 100 is capable to deliver a precursor 130 to an CVD or ALD process. The precursor 130 is stored in an ampoule 136 that has at least one inlet 111 and one outlet 112. The precursor 130 can either be liquid or solid at the temperature at which it is stored inside ampoule 136. The ampoule 136 is located inside a temperature-controlled enclosure 137. A carrier gas stream 113 can be admitted to the ampoule via the inlet 111. The carrier gas stream 113 is varied so that the fluid in the headspace of ampoule 136 is maintained at a predetermined pressure. A temperature sensor 135 is located inside the ampoule 136. The vapor over the precursor 130 is thus entrained in a first fluid stream 110 that consists of the carrier gas and the

precursor vapor. The first fluid stream **110** that contains the precursor vapor is contained in a suitable conduit that connects the outlet **112** of ampoule **136** with a flow controlling device **117**. The flow controlling device **117** is in fluid communication with a fast-acting shut-off valve **150**. A second fluid stream **120** is contained by a suitable conduit that is in fluid communication with the fast-acting shut-off valve **150** and a reaction chamber **140**. The fast acting shut-off valve **150** can be opened by an electric control pulse that is provided by a pulse controller **200**. A sensor-of-state **160** is connected to the stem of the fast-acting shut-off valve **150**. The sensor-of-state **160** is in communication with the pulse controller **200** and is configured to transmit a signal that indicates the state of the fast-acting valve **150**.

[0016] The pulse controller **200** comprises at least seven functional blocks: an interface **204** for the fast-acting shut-off valve **150**, an interface **208** for the sensor-of-state **160**, an interface **212** for the temperature sensor **135**, an interface **214** for a control unit of a CVD or ALD apparatus **300**, a mass storage device **210**, such as an SD card, an input and display device **202**, all of which are connected individually to a microcontroller unit (MCU) **206**.

[0017] The MCU **206** is configured so that a nominal temperature $T_{nominal}$ can be stored and is available for computations. Further, the pulse controller is configured so that a plurality of vapor pressure curves can be stored, one of them being the vapor pressure curve of the specific precursor **130**. Further, the MCU **206** is configured to measure the length of and electrical pulse that it receives from the control unit of a CVD, ALD, or ALE apparatus **300**. The MCU **206** is further capable to execute the required computations. It is capable to display computed data and other information on the display device **202** store computed data on the mass storage device **210**.

[0018] In operation the second fluid stream **120** is set at an invariable predetermined velocity v . Provided that the pressure in the second fluid stream **120** is lower than the pressure in the first fluid stream **110**, the opening of the fast-acting shut-off valve **150** for a predetermined amount of time t generates a precursor pulse **125** of a predetermined length in the second fluid stream **120**. The time of the opening is called the exposure time t . The spatial length x of the precursor pulse **125** is given by the formula $x=v*t$. The partial pressure pp of the precursor in the precursor pulse **125** is determined by the temperature of the precursor **130** in ampoule **136**. A temperature sensor **135** is immersed in the liquid or solid precursor **130** to obtain the precursor temperature. The temperature sensor **135** is in communication with the pulse controller **200**. The temperature sensor **135** is configured to measure the temperature at least at one but generally at more than one points within the precursor **130** and inside ampoule **136**. Specifically, the measurement of the temperature at five different points may be useful to determine the temperature uniformity inside the bulk of the precursor **130** and the headspace **115**. As many as ten different points may be useful to measure a temperature field inside the ampoule **136** or more generally in the thermal enclosure **137**.

[0019] The second fluid stream **120** with the precursor pulse **125** is directed toward the surface of a substrate **142** inside the reaction chamber **140**. The flow velocity v of the second fluid stream **120** and the precursor pulse **125** may change as they travel through the precursor delivery system **100**. The spatial pulse length of the pulse **125** increases when

the cross section of the second fluid stream **120** is reduced and decreases when the cross section of the second fluid stream is widened. The exposure time $t=x/v$ that the pulse is present at any given cross section of the second fluid stream **120** remains constant. The flow velocity of the second fluid stream normal to the cross section of the reactor chamber **140** may be ranging from 0.01 m s^{-1} to 10 m s^{-1} .

[0020] The total pressure of the second fluid stream **120** may change while it travels through the precursor delivery system **100**. The pressure of the second fluid stream **120** inside the reaction chamber **140** can be in the range from 10 Pa to 100,000 Pa.

[0021] The partial pressure pp of the precursor in precursor pulse **125** is proportional to the vapor pressure vp of the precursor **130** at a temperature T and can be presented as $pp=\text{const}*vp(T)$. The vapor pressure vp of the precursor **130** is a function of the temperature of the surface of the precursor **130** inside ampoule **136**. The measurement of the temperature of the precursor **130** near evaporating surface can be used to compute the vapor pressure vp and the partial pressure pp of the precursor in the precursor pulse **125**. In general, when designing a CVD or ALD process, a nominal partial pressure $pp_{nominal}$ in the precursor pulse **125** is calculated from a nominal temperature $T_{nominal}$ of precursor **130**. When the precursor **130** is at that nominal temperature $T_{nominal}$ the partial pressure $pp_{nominal}$ of the precursor in the precursor pulse **125** is precisely what the CVD or ALD process requires to form a perfect layer. The temperature controlled enclosure **137** is generally set to the nominal temperature $T_{nominal}$. Those skilled in the art know that for a number of reasons the precursor is almost never at the nominal temperature. The difference between the measured temperature $T_{measured}$ of the precursor and the nominal temperature $T_{nominal}$ of the process design can be as large as ± 10 degrees C. and not uniform throughout the bulk of the precursor **130**.

[0022] In operation of the precursor delivery system **100**, the pulse controller **200** continuously collects the measurements from temperature sensor **135** inside the ampoule and stores them to be available for computations. The pulse controller **200** is programmed to determine the temperature $T_{measured}$ that is most closely related to the evaporation or sublimation of precursor **130**. A first method to determine $T_{measured}$ is to take the coldest of the plurality of temperatures. A second method to determine $T_{measured}$ is to take the average of the temperatures at each of the points of temperature sensor **135**. Evaporation and sublimation require heat. This heat is taken from the solid or liquid precursor **130** close to the surface where the evaporation takes place. This makes the surface of the precursor the coldest point inside ampoule **136**. When using the first method to determine $T_{measured}$ it is the temperature of a point that is closest to a surface where evaporation takes place and determines the vapor pressure and the partial pressure of the precursor in precursor pulse **125**.

[0023] In operation, $T_{measured}$ of the precursor source **100** shifts for various reasons. One of these reasons is the consumption of the precursor **130**. This leads to a change in the geometry of the precursor with the associated change in heat flows and temperature. Another reason is a change of precursor delivery system **100** from an idle state in which no precursor is drawn to a use state in which precursor is drawn. After that change the temperature inside the precursor **130** settles into a new steady state. It takes anywhere from 30 to

120 minutes for the precursor **130** to reach the new steady state. The often used approximation that $T_{nominal}$ equals $T_{measured}$ at all times is only valid in a few instances.

[0024] The unintended deviation of $T_{measured}$ from the nominal temperature $T_{nominal}$ and the associated deviation from the nominal partial pressure $pp_{nominal}$ of the precursor in precursor pulse **125** lead to the growth of an material layer which is different from one that the nominal process would have yielded. A compensation mechanism is needed that compensates for the deviation of partial pressure pp over the substrate **142** from the nominal partial pressure $pp_{nominal}$.

[0025] FIG. 2 illustrates the underlying principle for providing this compensation. The growth rate of a layer and the speed at which one mono layer is formed proportional to the partial pressure pp of the precursor in the precursor pulse **125**. The effect of precursor pulse on the surface is $e=pp \cdot t$. The CVD or ALD process is designed to achieve effect $e=pp_{nominal} \cdot t_{nominal}$. The precursor **130** is at temperature $T_{measured}$ which produces a partial pressure in precursor pulse **125** of $pp_{actual} = \text{const} \cdot vp(T_{measured})$, instead of $pp_{nominal} = \text{const} \cdot vp(T_{nominal})$. In order to achieve the same effect e on the surface, $e = \text{const} \cdot vp(T_{nominal}) \cdot t_{nominal} = \text{const} \cdot vp(T_{measured}) \cdot t_{compensated}$. This gives the compensated pulse length $t_{compensated} = t_{nominal} \cdot vp(T_{nominal}) / vp(T_{measured})$. A lower than intended partial pressure pp is thus compensated by a proportionally longer pulse length. The effect e can be measured as the layer thickness or by the coverage in percent in case of a deposition of less than one atomic layer or possibly by some other measurements.

[0026] The compensation is provided by the precursor delivery system **100** of this disclosure. The pulse controller **200** is programed to calculate a compensated pulse length $t_{compensated}$ according the formula $t_{compensated} = t_{nominal} \cdot vp(T_{nominal}) / vp(T_{measured})$.

[0027] In first embodiment of FIG. 1. the fast-acting shut-off valve **150** is configured with a solenoid actuator. The sensor-of-state **160** is configured as a continuous linear position sensor. The sensor-of-state **160** may also be configured as a two-point position sensor.

[0028] In a second embodiment as shown in FIG. 3. the fast acting shut-off valve **150** is configured with a pneumatic actuator. The pneumatic actuator of valve **150** is in pneumatic communication with a pilot valve **155**. The pilot valve **155** is a solenoid valve that is also in pneumatic communication with a pneumatic pressure supply **156**. Further, the pneumatic actuator of fast-acting shut-off valve **150** is in pneumatic communication with the sensor-of-state **160**. In the embodiment represented in FIG. 3 the sensor-of-state is a pressure transducer. The pressure transducer as a sensor-of-state to the fast-acting shut-off valve sends a pressure signal to the pulse controller **200**. The pneumatic pressure in the actuator of a pneumatically driven valve is an indication for the state of the valve. When the pneumatic pressure exceeds a specific pressure (that is provided by the manufacturer of the valve) the valve is guaranteed to be open.

[0029] The pulse controller **200** is programmed to measure the time that passes between the moment when the pressure transducer **160** exceeds the specific opening pressure of the fast acting shut-off valve **150** and the moment when it falls below it. This length of time is called the actual pulse time t_{actual} . t_{actual} should always be equal to $t_{compensated}$ when the pulse time is longer than 10 milliseconds. Otherwise a problem with the fast acting shut-off valve **150** can be detected. For a pulse time of less than 10 milliseconds t_{actual}

can be used for analyzing the response of the fast acting shut-off valve. FIG. 5 shows the pneumatic response to a 10, 20, and 30 millisecond pulse time. The combination of pneumatic pilot valve and pneumatic actuator stops responding to pulse times shorter than 3 milliseconds. The pneumatic solenoid valve is unable to open for such short periods of time.

[0030] Further, in the second embodiment the precursor delivery system **100** comprises a waste fluid stream **550**. A fast acting shut-off valve **560** controls the waste fluid stream **550**. The fast acting shut-off valve **560** is operated inversely to fast-acting shut-off valve **150**. This means that the fast acting shut-off valve **560** is open when fast acting shut-off valve is closed and vice versa. The waste fluid stream **550** enables a steady state stream through the ampoule **130** and eliminates transients of the first fluid stream **110** between zero flow and the flow that is determined by the adjustable flow controlling device **117**. The waste fluid stream **550** joins the second fluid stream **120** downstream of the reaction chamber **140**.

1. A precursor delivery system comprising:

- a precursor source comprising an ampoule configured to contain a liquid or solid precursor, the ampoule having an inlet and an outlet;
- a pulse controller configured to measure the duration of a valve control pulse, further configured to drive a fast valve, further configured to receive a signal from a temperature sensor, further configured to receive a sensor-of-state of a fast valve;
- a fast-acting shut-off valve driven by the pulse controller, the upstream side of the fast valve being in fluid communication with the outlet of the ampoule through a suitable conduit, the downstream side of the fast valve being in fluid communication with a second fluid stream contained by a suitable conduit;
- a temperature sensor being immersed in the precursor inside the ampoule, and the temperature sensor being in communication with the pulse controller; and
- a sensor-of-state of the fast valve being in communication with the pulse controller.

2. A precursor delivery system according to claim 1. that uses a temperature sensor comprising a plurality of measurement points along a line, the cross section normal to the line not exceeding 12 square millimeters, and each of the measurement points having a temperature resolution of less than 30 milli Kelvin.

3. A precursor delivery system according to claim 2, where the temperature sensor is immersed in a precursor so that at least one of the plurality of measurement points is not more than 20 millimeters from the of the surface of the precursor.

4. A precursor delivery system according to claim 1, where the fast valve is a pneumatically driven valve with a specified pneumatic pressure for operation.

5. A precursor delivery system according to claim 1.that uses a solenoid valve to generate an pneumatic pilot pulse for the pneumatic fast valve.

6. A precursor delivery system according to claim 1. that uses a fast pressure transducer as a sensor-of-state for a pneumatic fast valve, the pressure transducer being configured to have a resolution of at least 0.5 psi (3.4 kPa) and a response time of not more than 0.5 milliseconds.

7. A method for exposing a surface to a precursor comprising:

to generate a first fluid stream consisting of a carrier fluid and a vapor from a liquid or solid precursor being generated by evaporation or sublimation;

to establish a nominal temperature $T_{nominal}$ for the precursor;

to generate a second fluid stream with a predetermined velocity;

to add the first fluid stream to the second fluid stream for a predetermined length of time $t_{nominal}$ when the precursor is at the nominal temperature $T_{nominal}$; and

to direct the combined fluid stream across the surface of a substrate.

8. A method according to claim 7 where a temperature $T_{measured}$ is measured inside the bulk of a precursor;

where the nominal control pulse length $t_{nominal}$ is measured, with $t_{nominal}$ being in the range from 0.1 (zero point one) millisecond, 1 (one), 10 (ten), 100 (hundred), 1000 (thousand) to 10000 (ten thousand) milliseconds;

where a compensated control pulse length $t_{compensated}$ is computed from the nominal control pulse length $t_{nominal}$, the nominal temperature $T_{nominal}$ and the measured

temperature T measured by using the temperature dependent vapor pressure $vp(T)$ of the precursor according the formula

$$t_{compensated} = t_{nominal} * vp(T_{nominal}) / vp(T_{measured}); \text{ and}$$

where the first fluid stream is added to the second fluid stream for the compensated control pulse length $t_{compensated}$ instead of the nominal control pulse length $t_{nominal}$.

9. A method of claim 7 where the precursor in the combined fluid stream can chemically react with a surface of a substrate to form a solid.

10. A method according to claim 8 where the precursor in the combined fluid stream chemically reacts with the surface to form a liquid.

11. A method according to claim 8 where the molar concentration c of the vapor in the first fluid stream is in a range between 0.1% and 95%.

12. A method according to claim 8 where the actual pulse length t_{actual} is determined as the interval between the time when the pilot pressure rises above the operating pressure of the pneumatic fast valve and the time when the pilot pressure drops below the operating pressure of the pneumatic fast valve.

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