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(54) **SYSTEMS AND METHODS FOR IMAGE PROCESSING**

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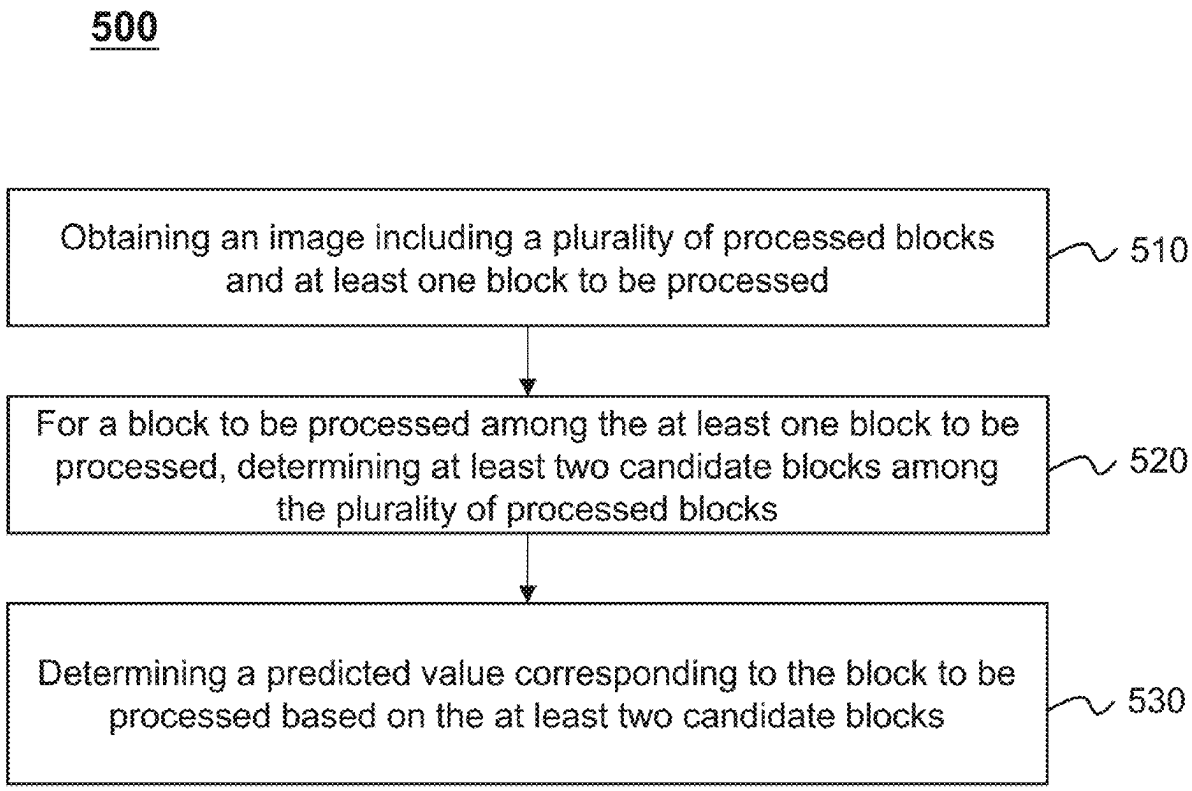
(57) **ABSTRACT**

The present disclosure provides a system and a method for image processing. The system may include at least one storage device including a set of instructions; and at least one processor is in communication with the at least one storage device, wherein when executing the set of instructions, the at least one processor is directed to cause the system to perform operations, including: obtaining an image including a plurality of processed blocks and at least one block to be processed; for a block to be processed among the at least one block to be processed, determining at least two candidate blocks among the plurality of processed blocks; and determining a predicted value corresponding to the block to be processed based on the at least two candidate blocks.



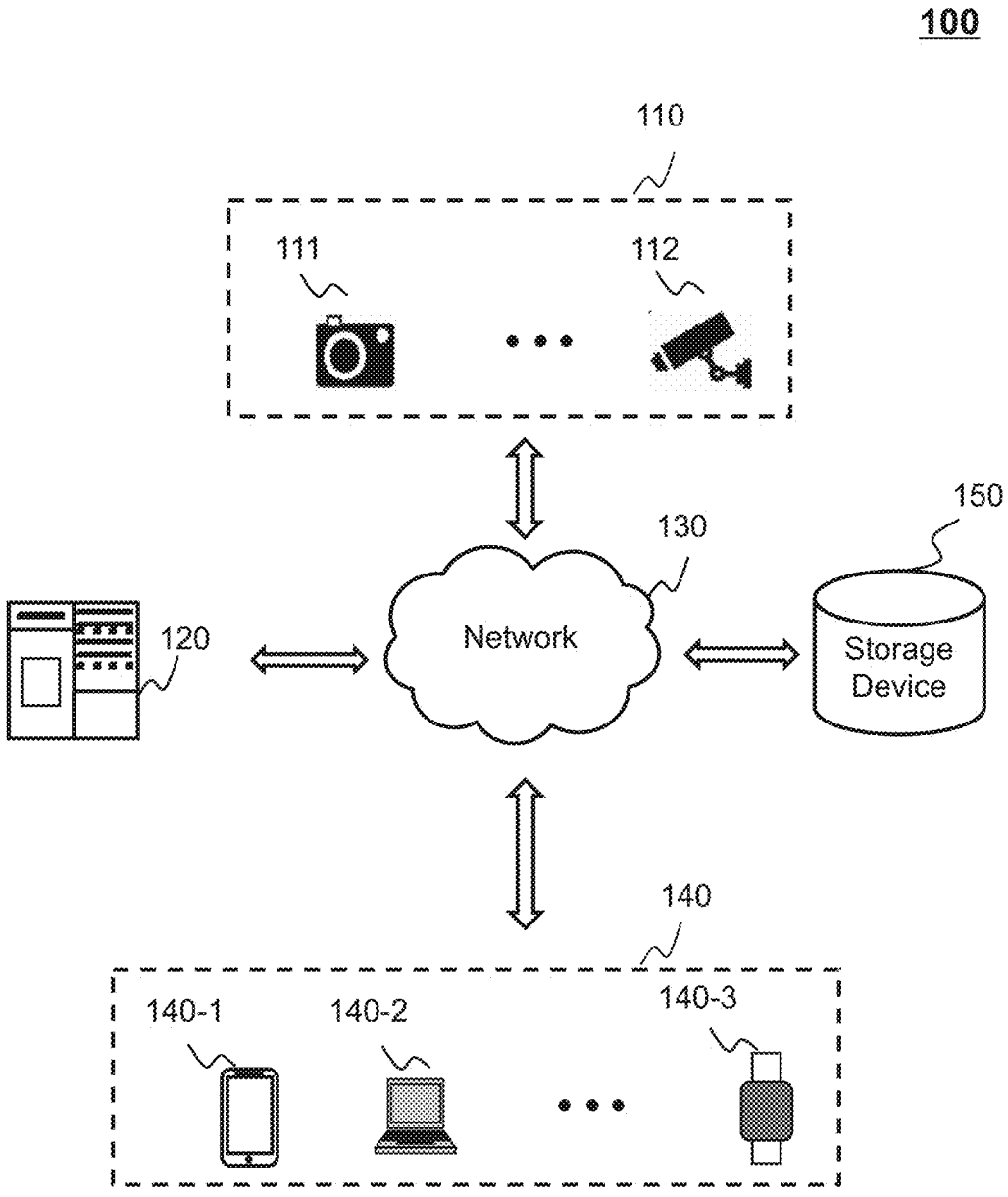

100
110
111
112
150
130
120
Network
Storage Device
140
140-1
140-2
140-3

FIG. 1

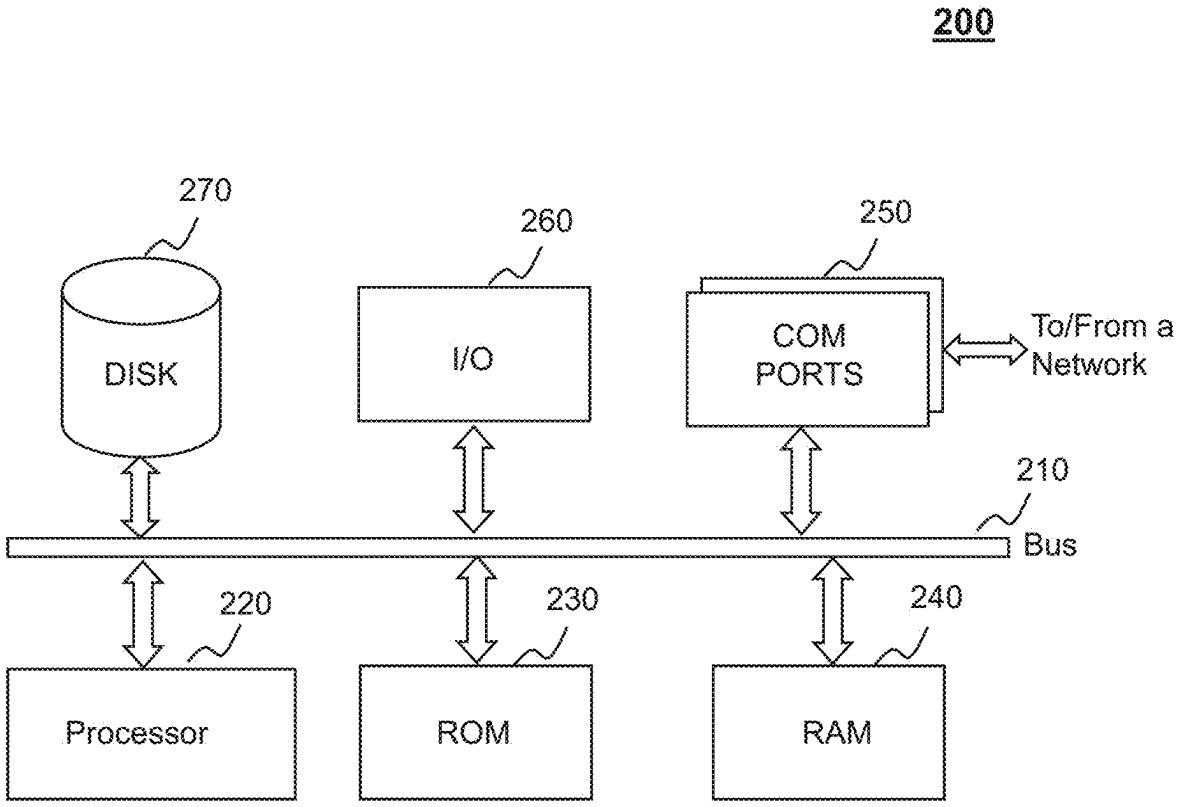

200
270
260
250
DISK
I/O
COM
PORTS
To/From a
Network
210
Bus
220
230
240
Processor
ROM
RAM

FIG. 2

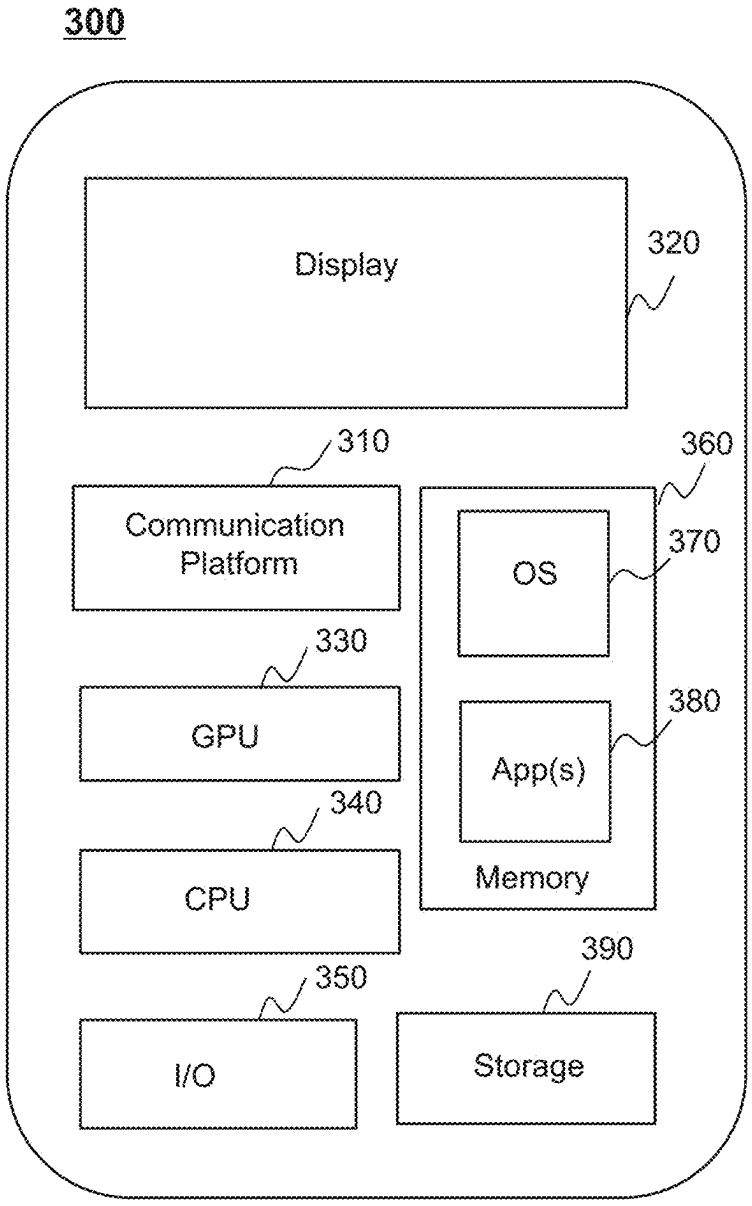

300
Display
320
310
Communication Platform
360
OS
370
330
GPU
380
App(s)
340
CPU
Memory
390
350
I/O
Storage

FIG. 3

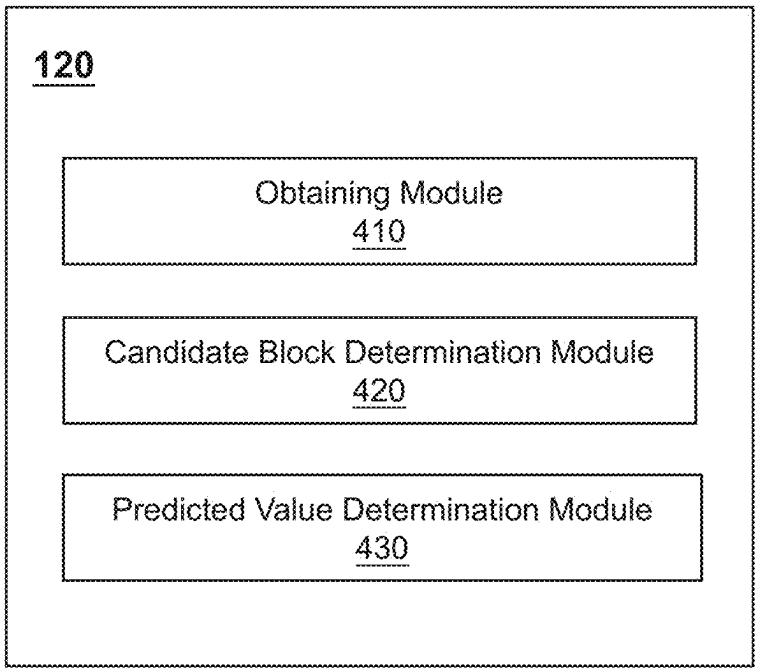

120
Obtaining Module
410
Candidate Block Determination Module
420
Predicted Value Determination Module
430

FIG. 4

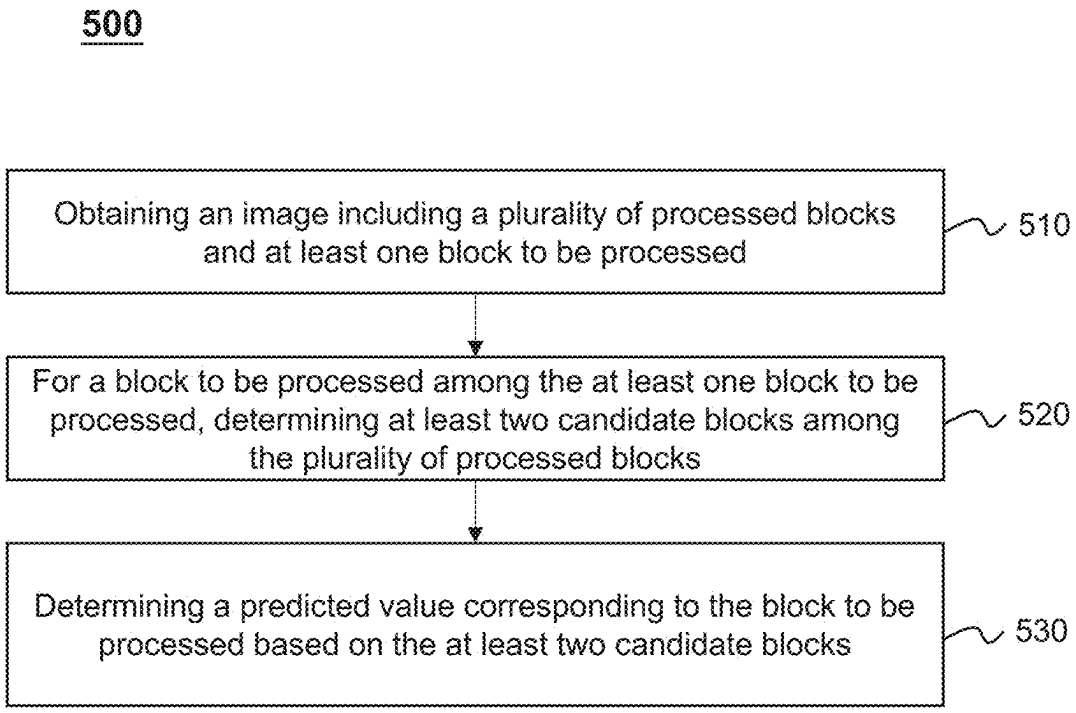

500
Obtaining an image including a plurality of processed blocks and at least one block to be processed
510
For a block to be processed among the at least one block to be processed, determining at least two candidate blocks among the plurality of processed blocks
520
Determining a predicted value corresponding to the block to be processed based on the at least two candidate blocks
530

FIG. 5

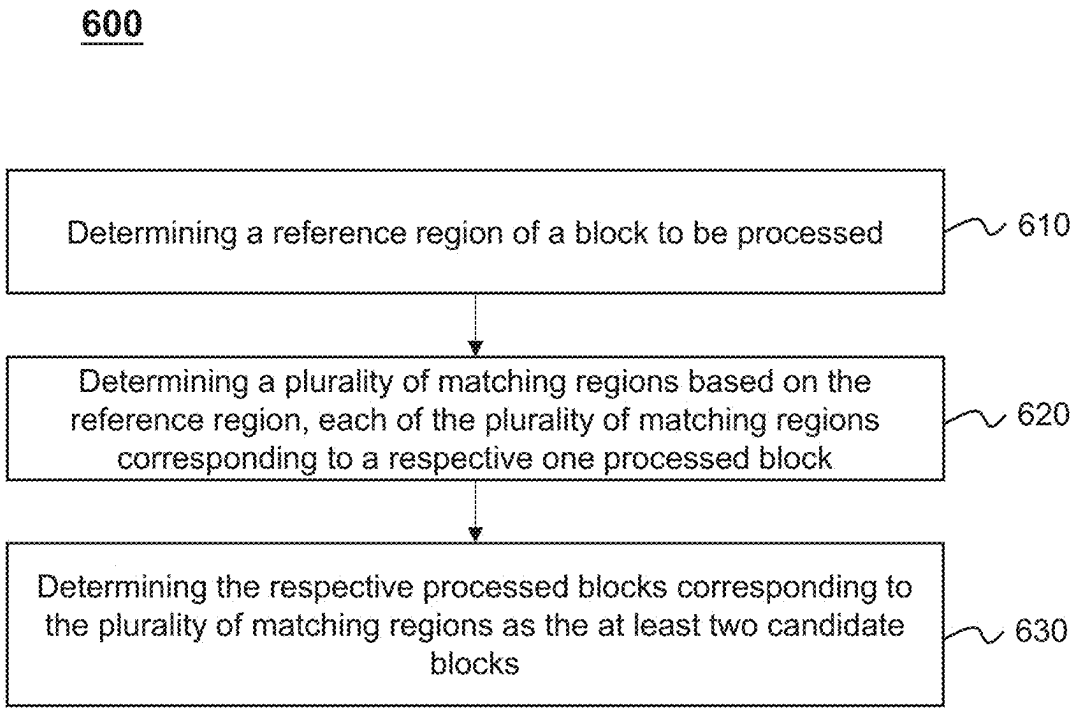

600
Determining a reference region of a block to be processed
610
Determining a plurality of matching regions based on the reference region, each of the plurality of matching regions corresponding to a respective one processed block
620
Determining the respective processed blocks corresponding to the plurality of matching regions as the at least two candidate blocks
630

FIG. 6

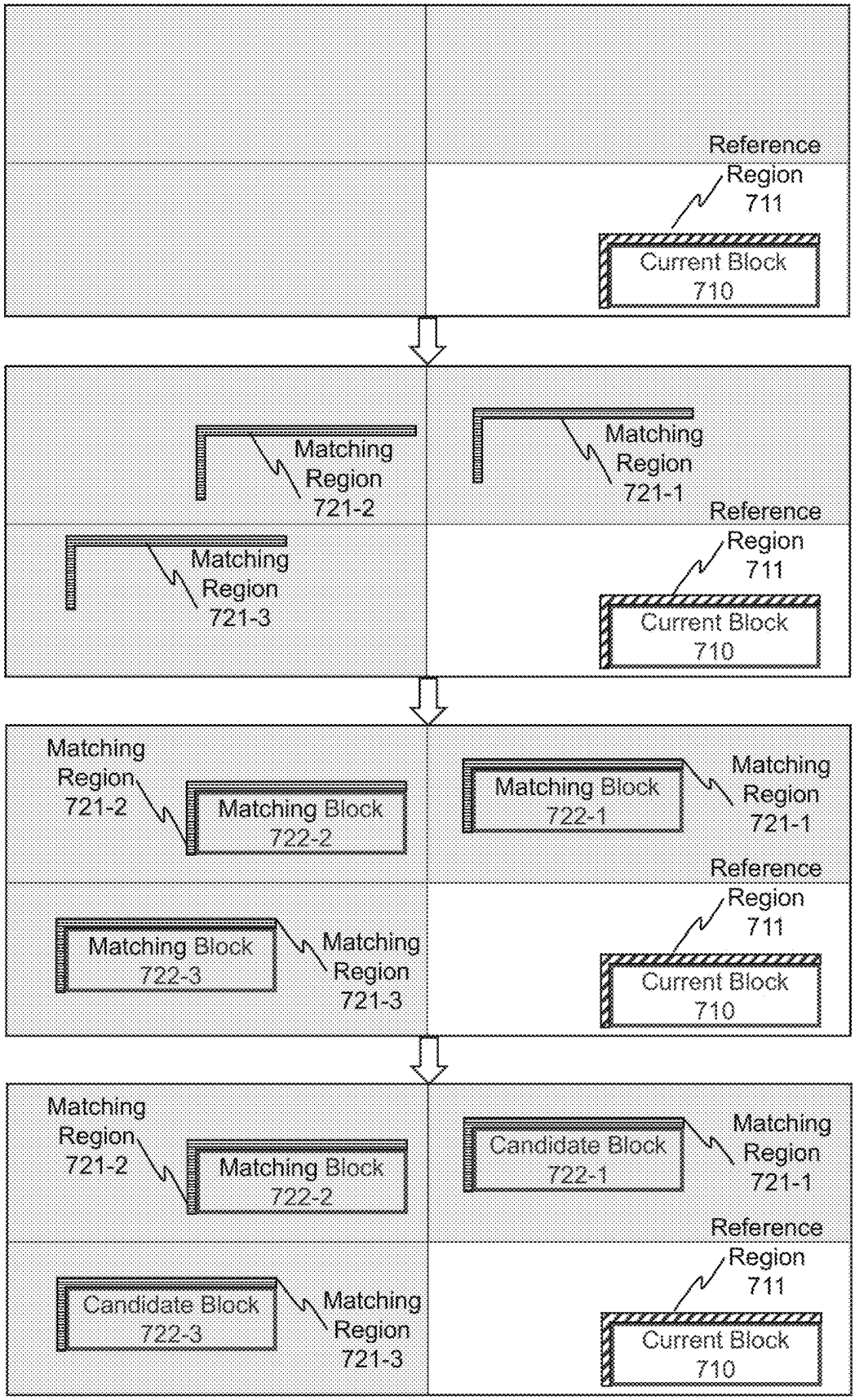

Reference Region 711
Current Block 710
Matching Region 721-2
Matching Region 721-1
Matching Region 721-3
Reference Region 711
Current Block 710
Matching Region 721-2
Matching Block 722-2
Matching Block 722-1
Matching Region 721-1
Matching Block 722-3
Matching Region 721-3
Reference Region 711
Current Block 710
Matching Region 721-2
Matching Block 722-2
Candidate Block 722-1
Matching Region 721-1
Candidate Block 722-3
Matching Region 721-3
Reference Region 711
Current Block 710

FIG. 7

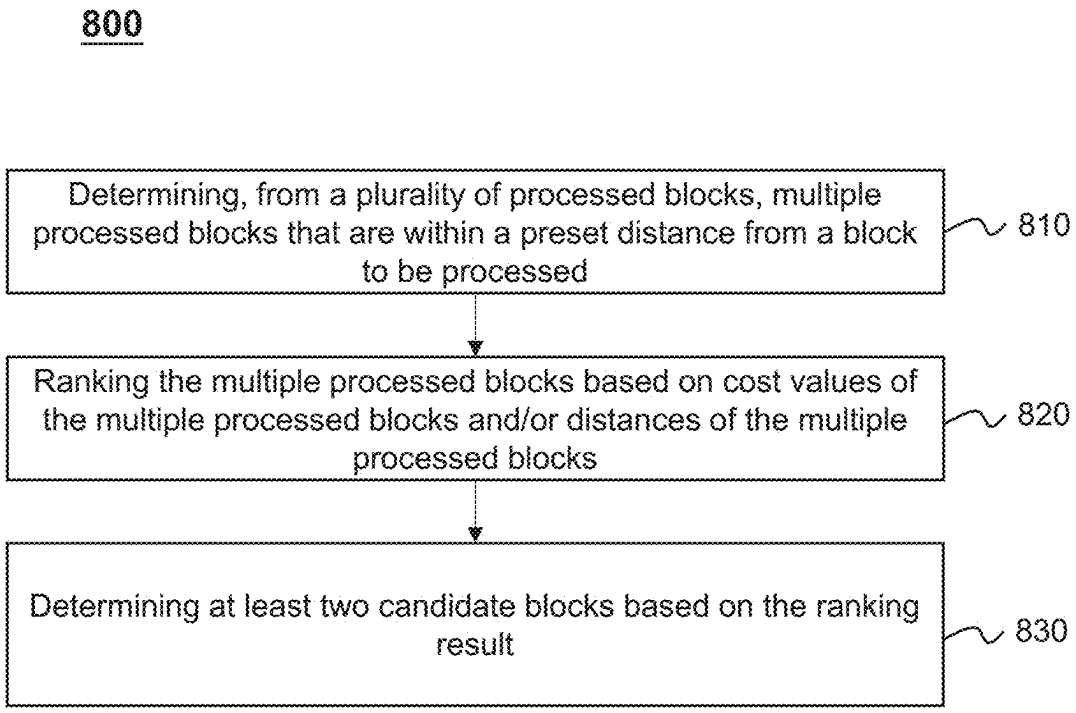

800
Determining, from a plurality of processed blocks, multiple processed blocks that are within a preset distance from a block to be processed
810
Ranking the multiple processed blocks based on cost values of the multiple processed blocks and/or distances of the multiple processed blocks
820
Determining at least two candidate blocks based on the ranking result
830

FIG. 8

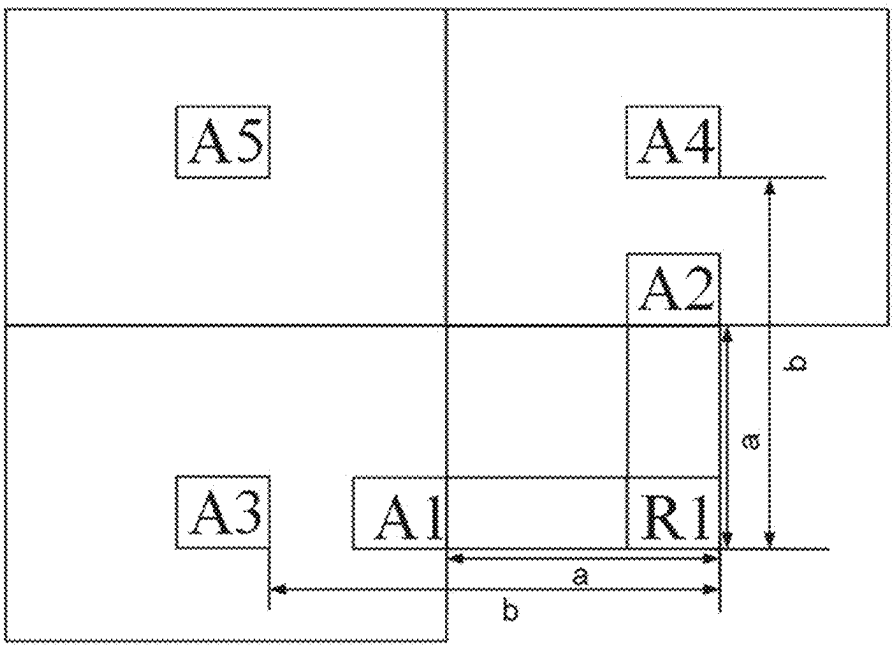


FIG. 9

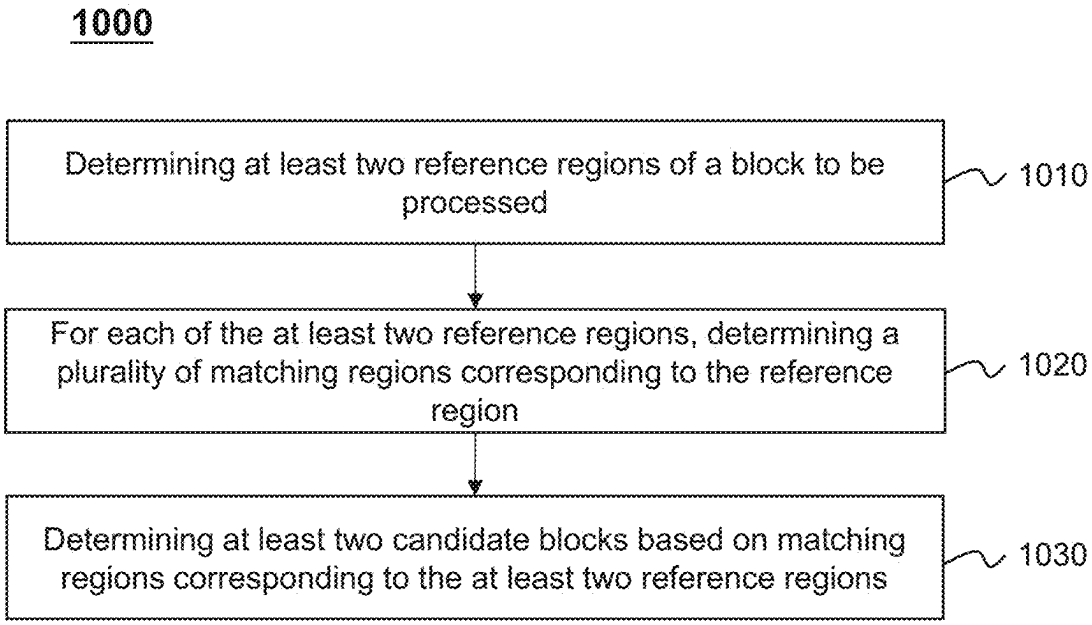

1000
Determining at least two reference regions of a block to be processed
1010
For each of the at least two reference regions, determining a plurality of matching regions corresponding to the reference region
1020
Determining at least two candidate blocks based on matching regions corresponding to the at least two reference regions
1030

FIG. 10

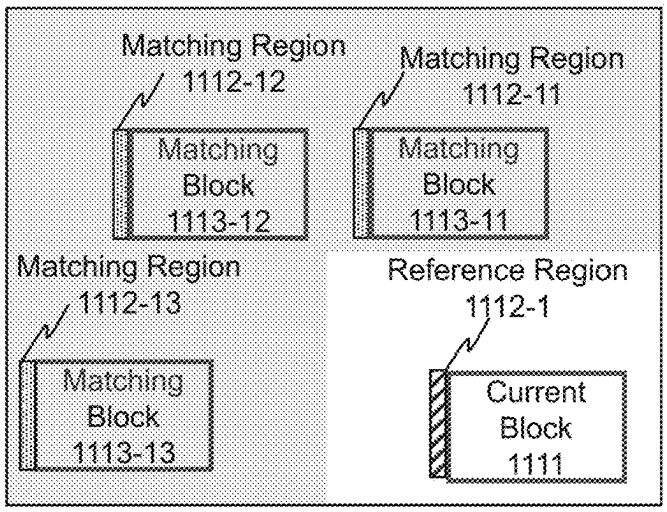


FIG. 11A

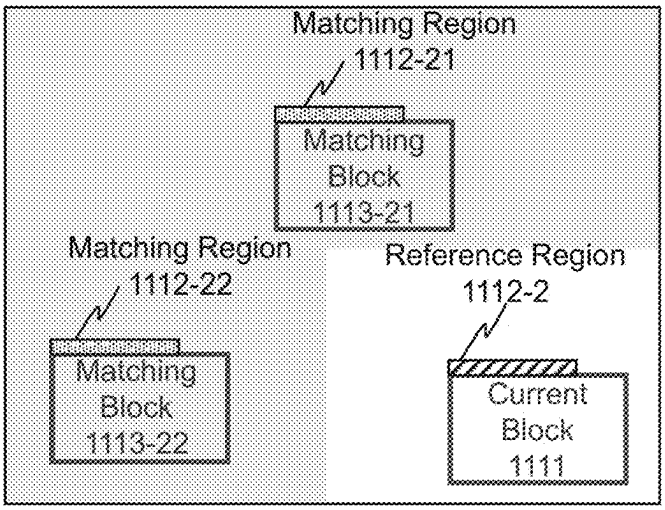


FIG. 11B

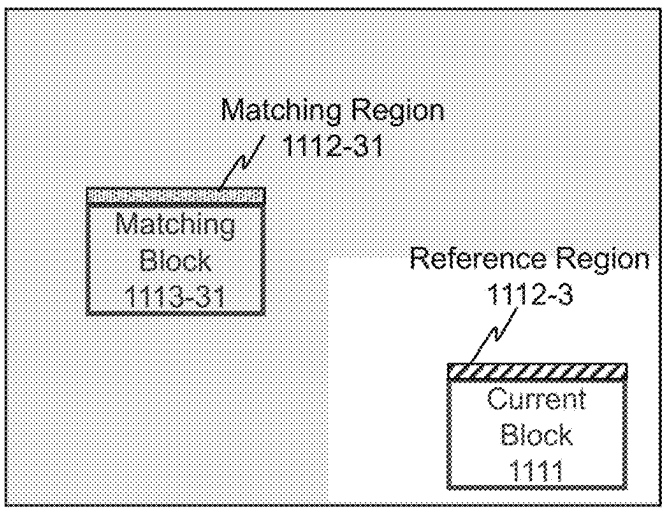


FIG. 11C

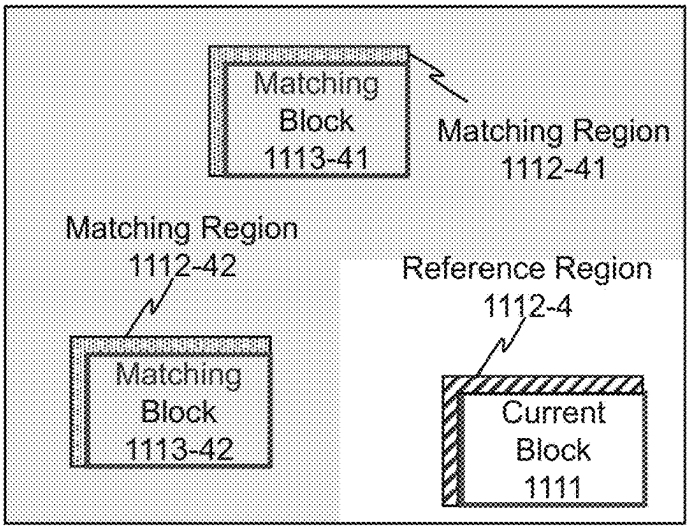


FIG. 11D

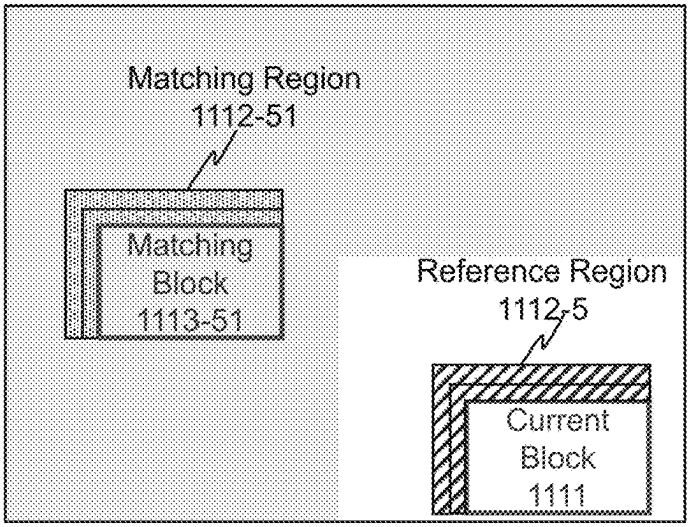


FIG. 11E

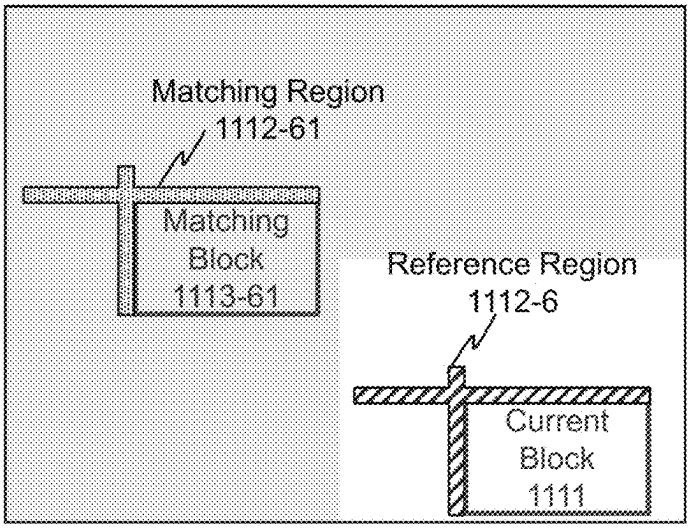


FIG. 11F

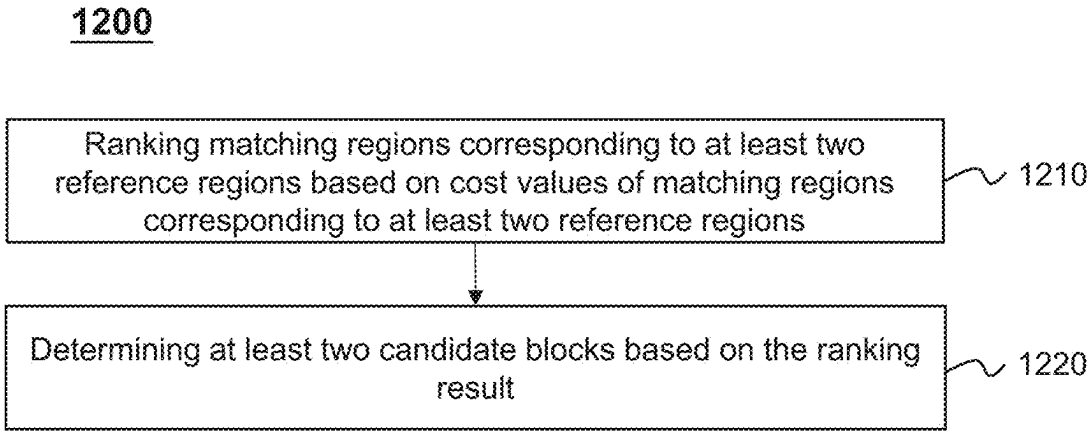

1200
Ranking matching regions corresponding to at least two reference regions based on cost values of matching regions corresponding to at least two reference regions
1210
Determining at least two candidate blocks based on the ranking result
1220

FIG. 12

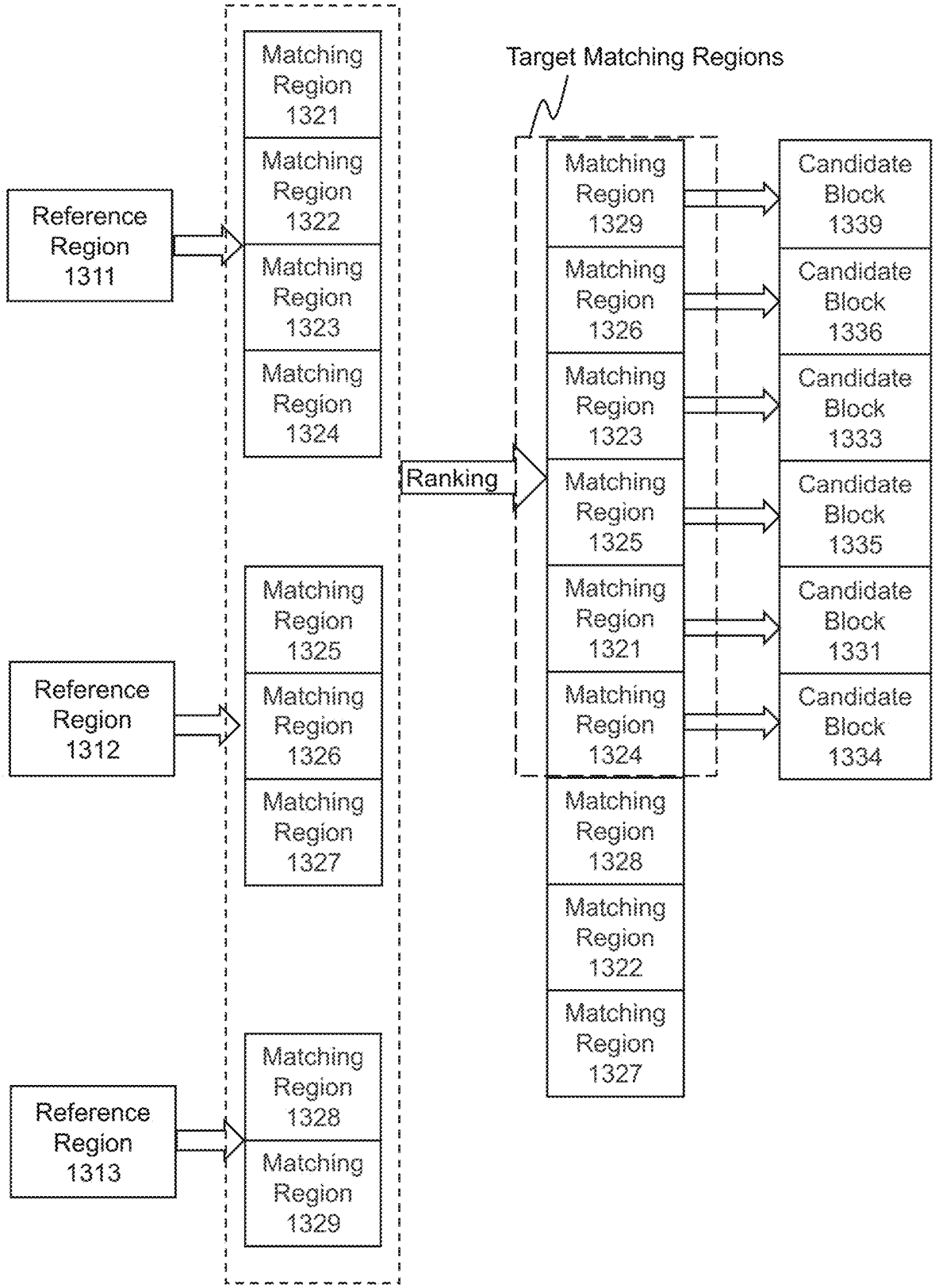

Reference Region 1311
Reference Region 1312
Reference Region 1313
Matching Region 1321
Matching Region 1322
Matching Region 1323
Matching Region 1324
Matching Region 1325
Matching Region 1326
Matching Region 1327
Matching Region 1328
Matching Region 1329
Ranking
Target Matching Regions
Matching Region 1329
Matching Region 1326
Matching Region 1323
Matching Region 1325
Matching Region 1321
Matching Region 1324
Matching Region 1328
Matching Region 1322
Matching Region 1327
Candidate Block 1339
Candidate Block 1336
Candidate Block 1333
Candidate Block 1335
Candidate Block 1331
Candidate Block 1334

FIG. 13

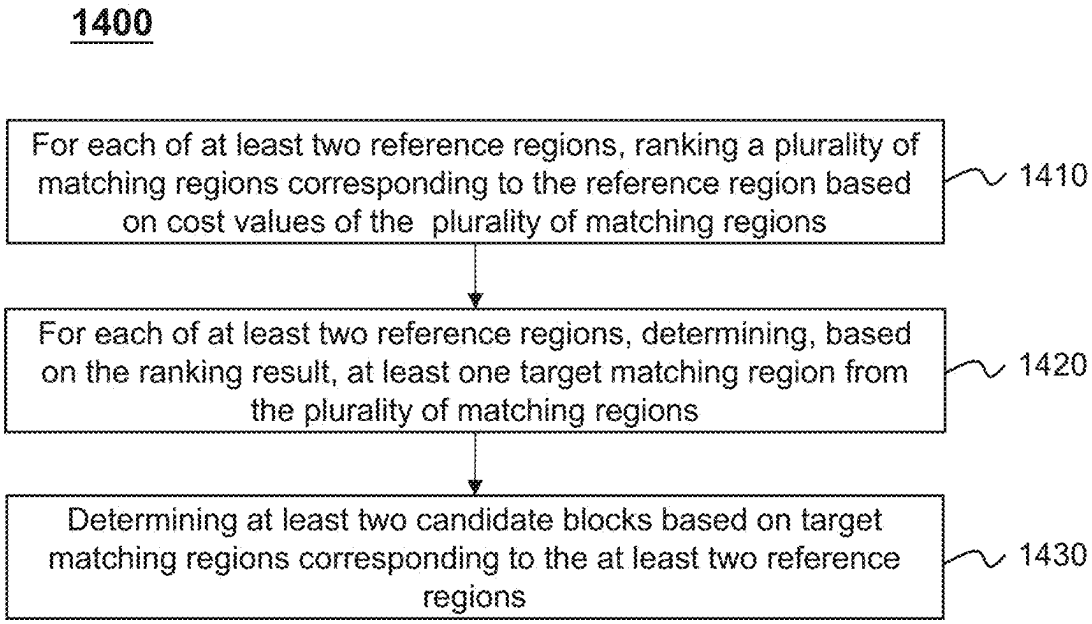

1400
For each of at least two reference regions, ranking a plurality of matching regions corresponding to the reference region based on cost values of the plurality of matching regions
1410
For each of at least two reference regions, determining, based on the ranking result, at least one target matching region from the plurality of matching regions
1420
Determining at least two candidate blocks based on target matching regions corresponding to the at least two reference regions
1430

FIG. 14

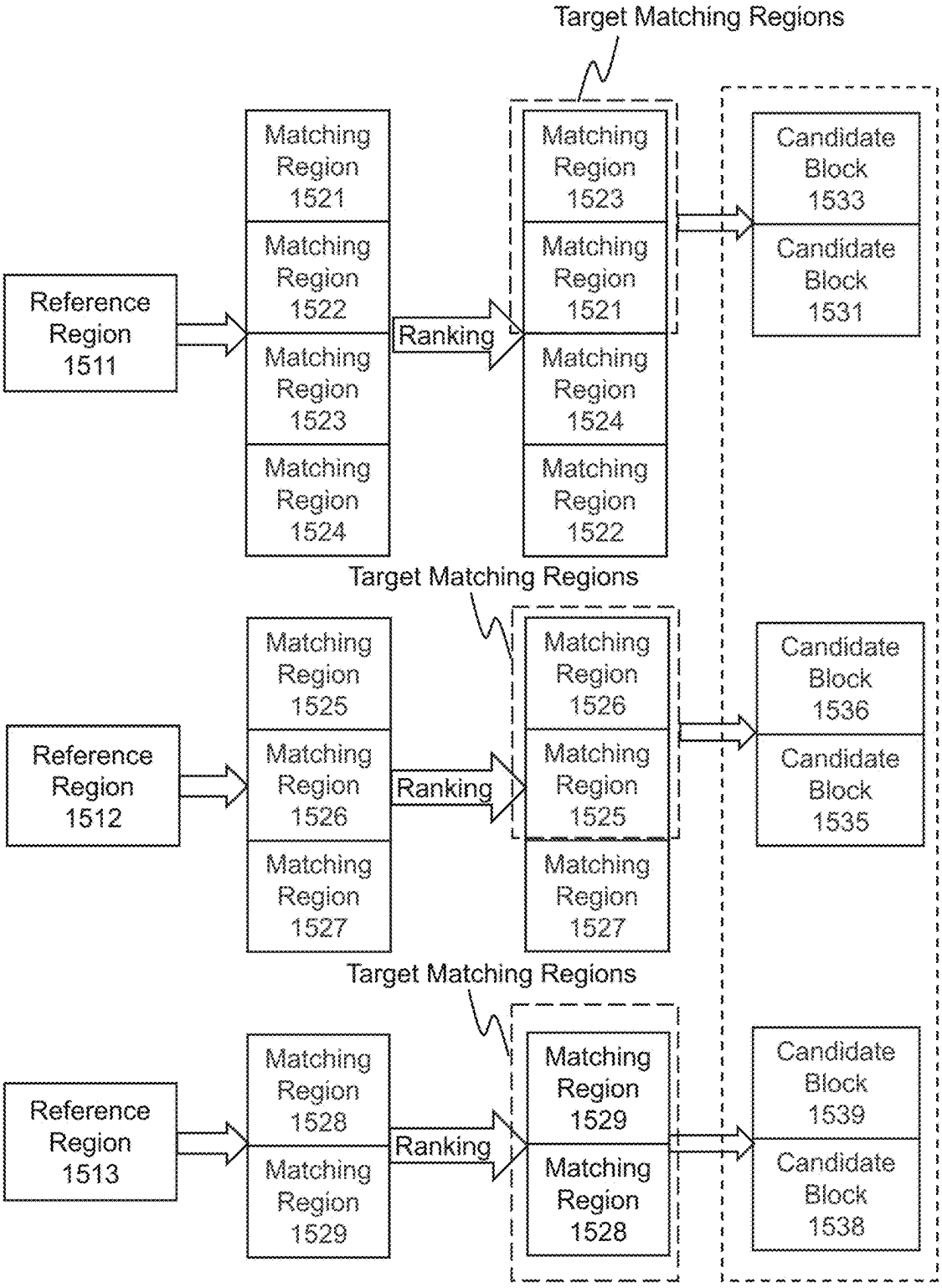

Target Matching Regions
Reference Region 1511
Matching Region 1521
Matching Region 1522
Matching Region 1523
Matching Region 1524
Ranking
Matching Region 1523
Matching Region 1521
Matching Region 1524
Matching Region 1522
Candidate Block 1533
Candidate Block 1531
Target Matching Regions
Reference Region 1512
Matching Region 1525
Matching Region 1526
Matching Region 1527
Ranking
Matching Region 1526
Matching Region 1525
Matching Region 1527
Candidate Block 1536
Candidate Block 1535
Target Matching Regions
Reference Region 1513
Matching Region 1528
Matching Region 1529
Ranking
Matching Region 1529
Matching Region 1528
Candidate Block 1539
Candidate Block 1538

FIG. 15

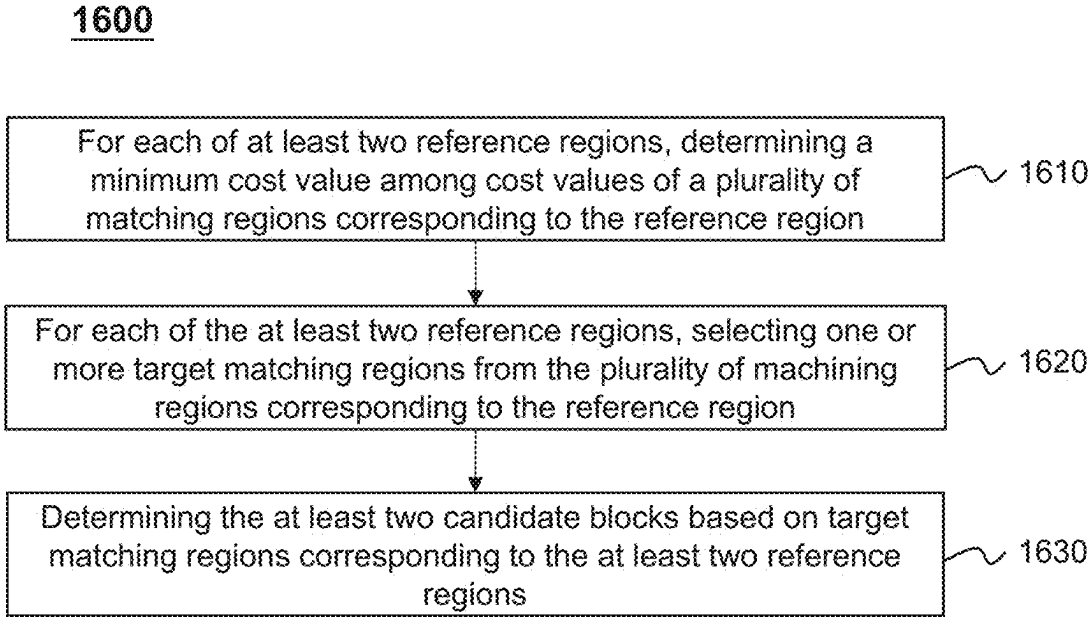

1600
For each of at least two reference regions, determining a minimum cost value among cost values of a plurality of matching regions corresponding to the reference region
1610
For each of the at least two reference regions, selecting one or more target matching regions from the plurality of machining regions corresponding to the reference region
1620
Determining the at least two candidate blocks based on target matching regions corresponding to the at least two reference regions
1630

FIG. 16

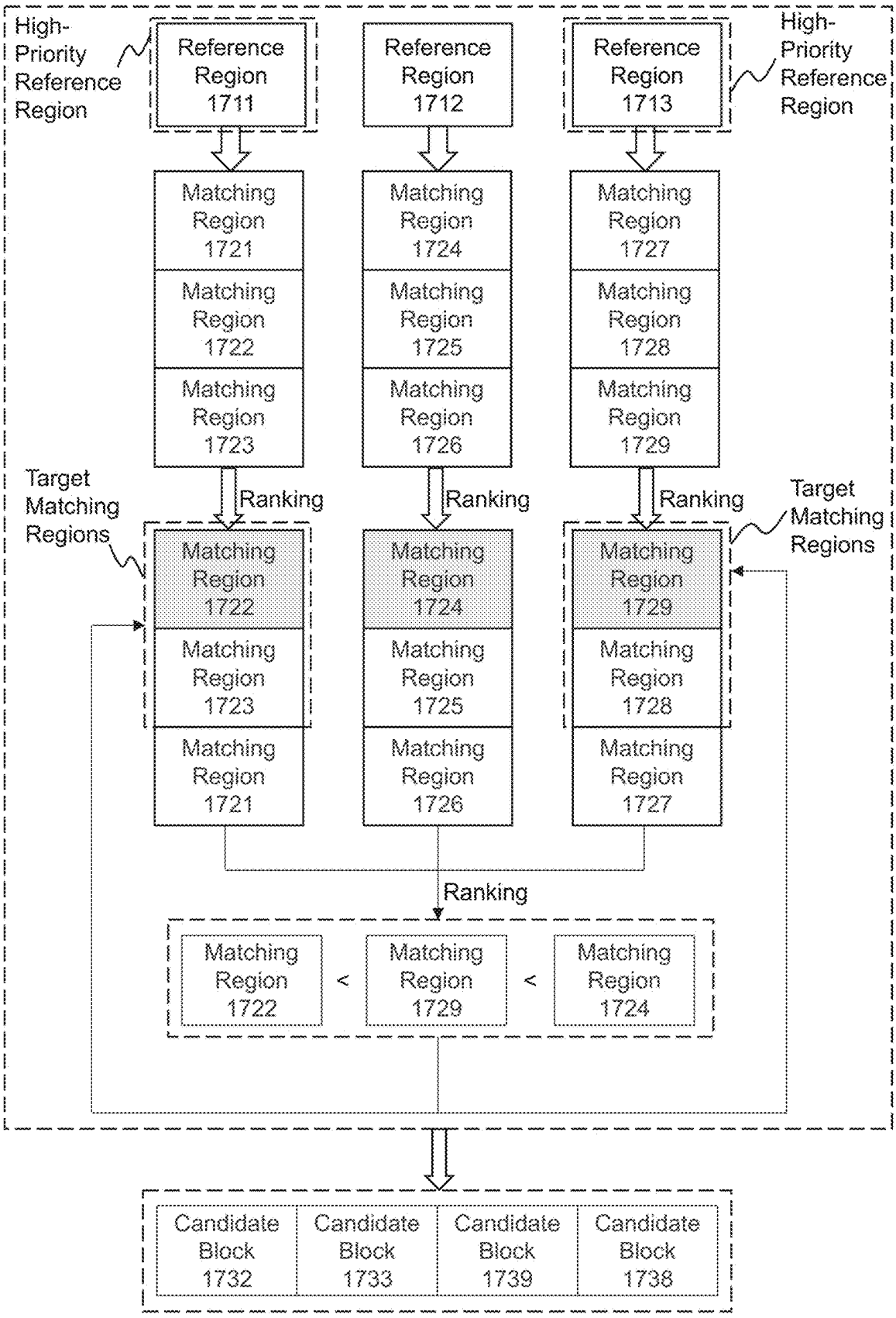

High-Priority Reference Region
Reference Region 1711
Reference Region 1712
Reference Region 1713
High-Priority Reference Region
Matching Region 1721
Matching Region 1722
Matching Region 1723
Matching Region 1724
Matching Region 1725
Matching Region 1726
Matching Region 1727
Matching Region 1728
Matching Region 1729
Ranking
Ranking
Ranking
Target Matching Regions
Target Matching Regions
Matching Region 1722
Matching Region 1723
Matching Region 1721
Matching Region 1724
Matching Region 1725
Matching Region 1726
Matching Region 1729
Matching Region 1728
Matching Region 1727
Ranking
Matching Region 1722
<
Matching Region 1729
<
Matching Region 1724
Candidate Block 1732
Candidate Block 1733
Candidate Block 1739
Candidate Block 1738

FIG. 17A

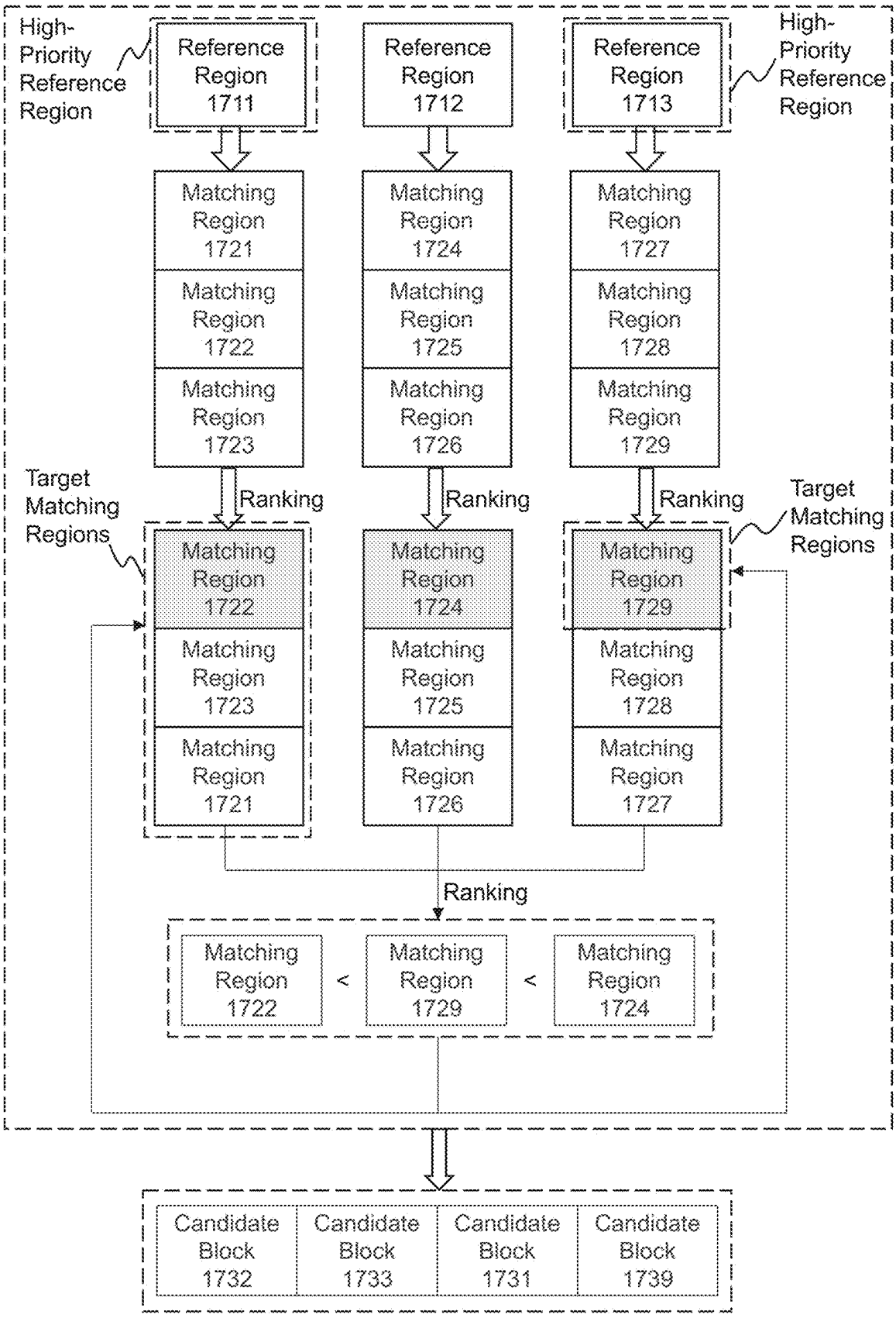

High-Priority Reference Region
Reference Region 1711
Reference Region 1712
Reference Region 1713
High-Priority Reference Region
Matching Region 1721
Matching Region 1722
Matching Region 1723
Matching Region 1724
Matching Region 1725
Matching Region 1726
Matching Region 1727
Matching Region 1728
Matching Region 1729
Target Matching Regions
Ranking
Ranking
Ranking
Target Matching Regions
Matching Region 1722
Matching Region 1723
Matching Region 1721
Matching Region 1724
Matching Region 1725
Matching Region 1726
Matching Region 1729
Matching Region 1728
Matching Region 1727
Ranking
Matching Region 1722
<
Matching Region 1729
<
Matching Region 1724
Candidate Block 1732
Candidate Block 1733
Candidate Block 1731
Candidate Block 1739

FIG. 17B

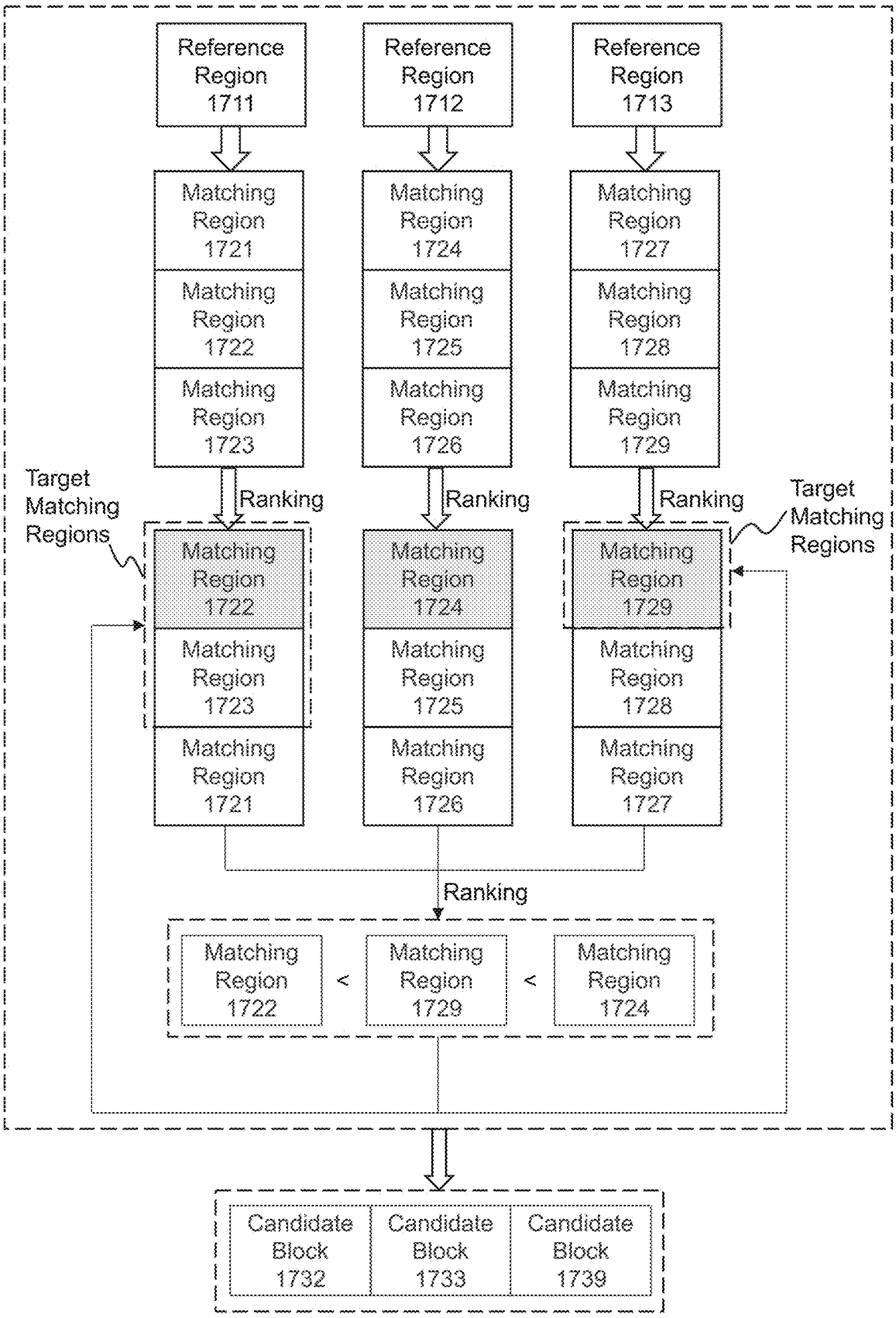

Reference Region 1711
Reference Region 1712
Reference Region 1713
Matching Region 1721
Matching Region 1722
Matching Region 1723
Matching Region 1724
Matching Region 1725
Matching Region 1726
Matching Region 1727
Matching Region 1728
Matching Region 1729
Target Matching Regions
Ranking
Ranking
Ranking
Target Matching Regions
Matching Region 1722
Matching Region 1723
Matching Region 1721
Matching Region 1724
Matching Region 1725
Matching Region 1726
Matching Region 1729
Matching Region 1728
Matching Region 1727
Ranking
Matching Region 1722
<
Matching Region 1729
<
Matching Region 1724
Candidate Block 1732
Candidate Block 1733
Candidate Block 1739

FIG. 17C

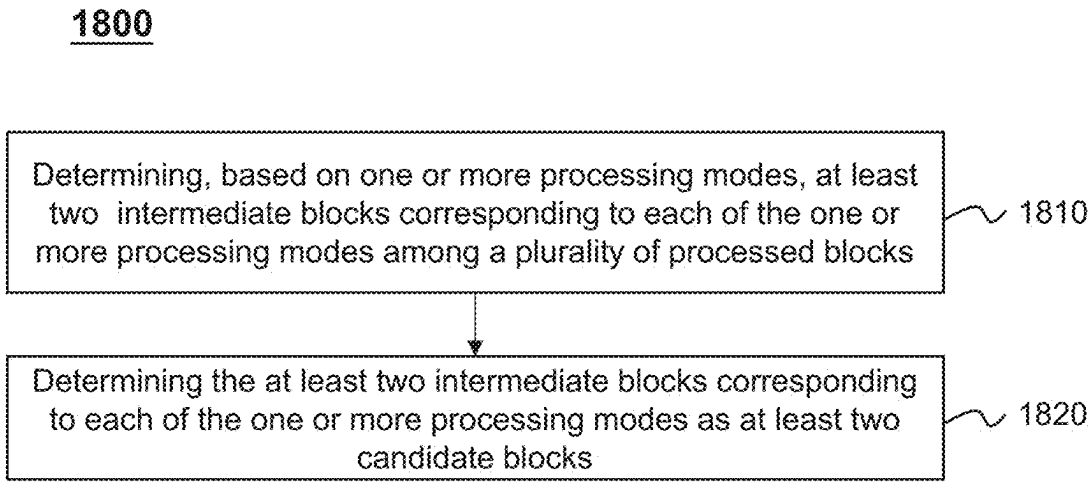

1800
Determining, based on one or more processing modes, at least two intermediate blocks corresponding to each of the one or more processing modes among a plurality of processed blocks
1810
Determining the at least two intermediate blocks corresponding to each of the one or more processing modes as at least two candidate blocks
1820

FIG. 18

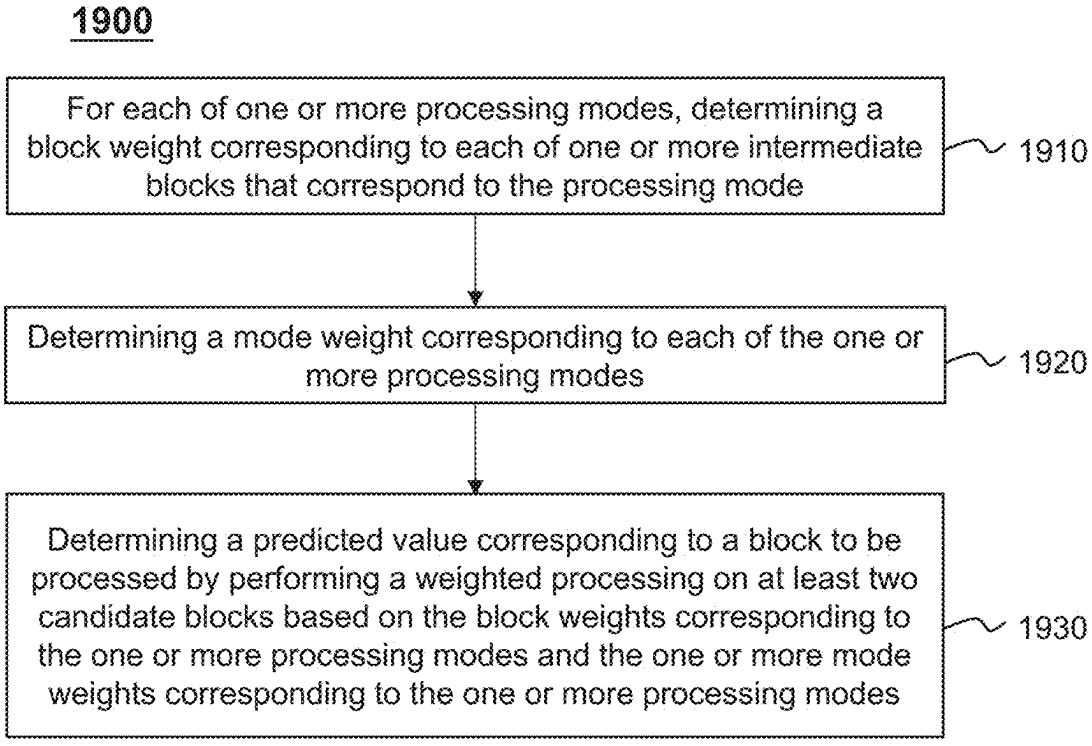

1900
For each of one or more processing modes, determining a block weight corresponding to each of one or more intermediate blocks that correspond to the processing mode
1910
Determining a mode weight corresponding to each of the one or more processing modes
1920
Determining a predicted value corresponding to a block to be processed by performing a weighted processing on at least two candidate blocks based on the block weights corresponding to the one or more processing modes and the one or more mode weights corresponding to the one or more processing modes
1930

FIG. 19

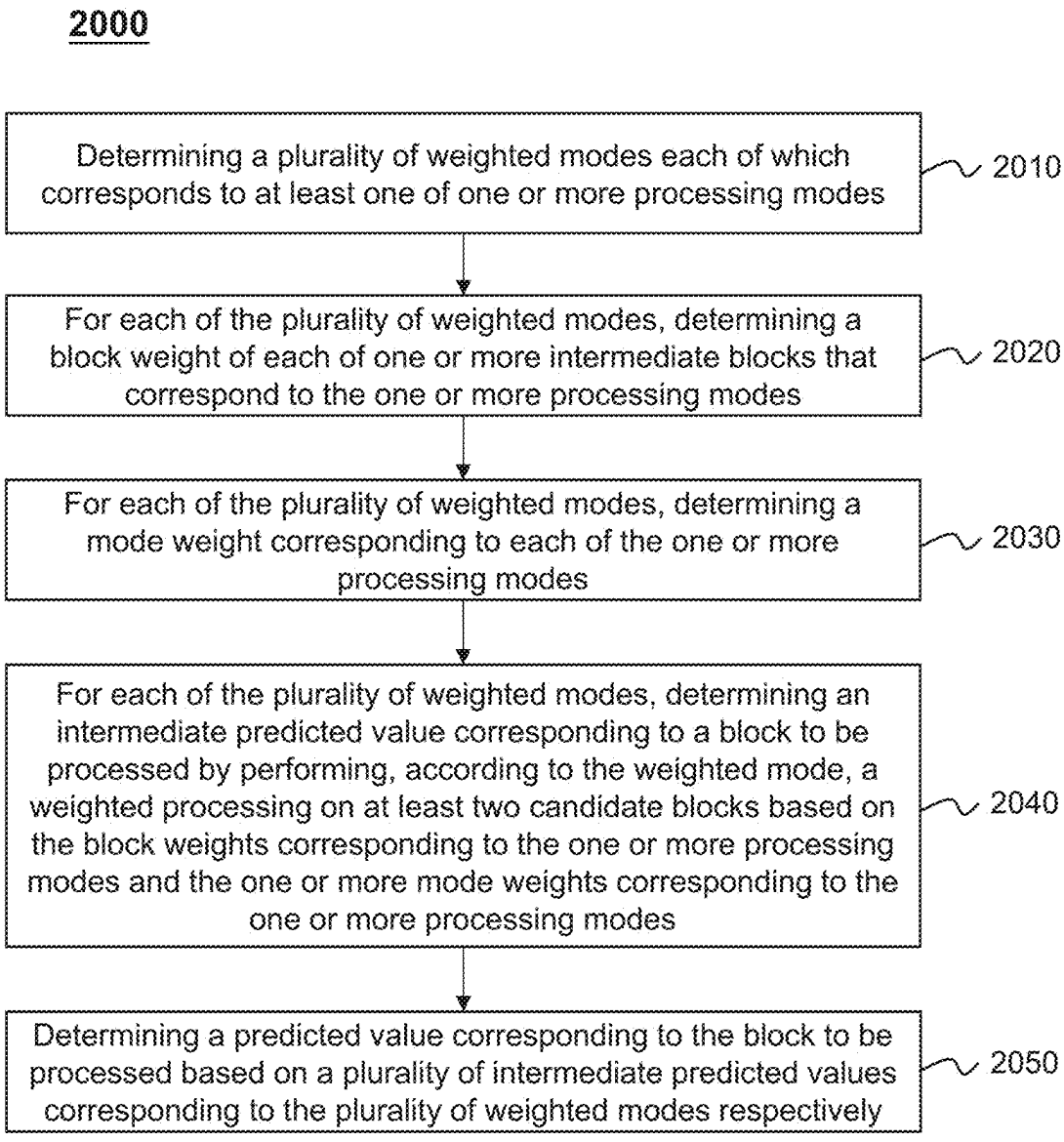

2000
Determining a plurality of weighted modes each of which corresponds to at least one of one or more processing modes
2010
For each of the plurality of weighted modes, determining a block weight of each of one or more intermediate blocks that correspond to the one or more processing modes
2020
For each of the plurality of weighted modes, determining a mode weight corresponding to each of the one or more processing modes
2030
For each of the plurality of weighted modes, determining an intermediate predicted value corresponding to a block to be processed by performing, according to the weighted mode, a weighted processing on at least two candidate blocks based on the block weights corresponding to the one or more processing modes and the one or more mode weights corresponding to the one or more processing modes
2040
Determining a predicted value corresponding to the block to be processed based on a plurality of intermediate predicted values corresponding to the plurality of weighted modes respectively
2050

FIG. 20

SYSTEMS AND METHODS FOR IMAGE PROCESSING

CROSS-REFERENCE TO RELATED APPLICATIONS

[0001] This application is a Continuation of International Application No. PCT/CN2023/132292 filed on Nov. 17, 2023, which claims priority to Chinese Patent Application No. 202211463047.2, filed on Nov. 21, 2022, and Chinese Patent Application No. 202211743995.1, filed on Dec. 30, 2022, the entire contents of each of which are incorporated herein by reference.

TECHNICAL FIELD

[0002] The present disclosure generally relates to video encoding and decoding technology, and in particular, to systems and methods for image processing using intra prediction.

BACKGROUND

[0003] With the development of communication technologies, video compression (e.g., video coding) becomes more and more important for storage requirements or transmission requirements. For example, a traditional intra prediction manner is used to determine a predicted value of a current block based on a single processed block, which may be inaccurate or inefficient. Therefore, it is desirable to provide improved systems and methods for image processing using intra prediction, thereby improving the prediction accuracy and the compression efficiency.

SUMMARY

[0004] According to one embodiment of the present disclosure, a system for image processing is provided. The system includes at least one storage device including a set of instructions; and at least one processor in communication with the at least one storage device, wherein when executing the set of instructions, the at least one processor is directed to cause the system to perform operations including: obtaining an image including a plurality of processed blocks and at least one block to be processed; for a block to be processed among the at least one block to be processed, determining at least two candidate blocks among the plurality of processed blocks; and determining a predicted value corresponding to the block to be processed based on the at least two candidate blocks.

[0005] According to one embodiment of the present disclosure, a method for image processing is provided, the method is implemented on a computing device including at least one storage device and at least one processor. The method includes: obtaining the image including the plurality of processed blocks and the at least one block to be processed; for the block to be processed among the at least one block to be processed, determining at least two candidate blocks among the plurality of processed blocks; and determining the predicted value corresponding to the block to be processed based on the at least two candidate blocks. According to one embodiment of the present disclosure, a non-transitory computer readable medium is provided, the medium includes executable instructions that, when executed by at least one processor, direct the at least one processor to perform the method. The method includes: obtaining the image including a plurality of processed blocks and the at least one block to be processed; for the block to be processed among the at least one block to be processed, determining the at least two candidate blocks among the plurality of processed blocks; and determining the predicted value corresponding to the block to be processed based on the at least two candidate blocks.

[0006] Additional features will be set forth in part in the description which follows, and in part will become apparent to those skilled in the art upon examination of the following and the accompanying drawings or may be learned by production or operation of the examples. The features of the present disclosure may be realized and attained by practice or use of various aspects of the methodologies, instrumentalities, and combinations set forth in the detailed examples discussed below.

BRIEF DESCRIPTION OF THE DRAWINGS

[0007] The methods, systems, and/or programming described herein are further described in terms of exemplary embodiments. These exemplary embodiments are described in detail with reference to the drawings. These embodiments are non-limiting exemplary embodiments, in which like reference numerals represent similar structures throughout the several views of the drawings, and wherein:

[0008] FIG. **1** is a schematic diagram illustrating an exemplary image processing system according to some embodiments of the present disclosure;

[0009] FIG. **2** is a schematic diagram illustrating exemplary hardware and/or software components of an exemplary computing device according to some embodiments of the present disclosure;

[0010] FIG. **3** is a schematic diagram illustrating exemplary hardware and/or software components of an exemplary mobile device according to some embodiments of the present disclosure;

[0011] FIG. **4** is a block diagram illustrating an exemplary processing device according to some embodiments of the present disclosure;

[0012] FIG. **5** is a flowchart illustrating an exemplary process for image processing according to some embodiments of the present disclosure;

[0013] FIG. **6** is a flowchart illustrating an exemplary process for determining at least two candidate blocks according to some embodiments of the present disclosure;

[0014] FIG. **7** is a schematic diagram illustrating an exemplary process for determining at least two candidate blocks according to some embodiments of the present disclosure;

[0015] FIG. **8** is a flowchart illustrating an exemplary process for determining at least two candidate blocks according to some embodiments of the present disclosure;

[0016] FIG. **9** is a schematic diagram illustrating an exemplary process for determining at least two candidate blocks according to some embodiments of the present disclosure;

[0017] FIG. **10** is a flowchart illustrating an exemplary process for determining at least two candidate blocks according to some embodiments of the present disclosure;

[0018] FIG. **11**A is a schematic diagram illustrating an exemplary process for determining at least two candidate blocks according to some embodiments of the present disclosure;

[0019] FIG. **11**B is a schematic diagram illustrating another exemplary process for determining at least two candidate blocks according to some embodiments of the present disclosure;

[0020] FIG. **11**C is a schematic diagram illustrating another exemplary process for determining at least two candidate blocks according to some embodiments of the present disclosure;

[0021] FIG. **11**D is a schematic diagram illustrating another exemplary process for determining at least two candidate blocks according to some embodiments of the present disclosure;

[0022] FIG. **11**E is a schematic diagram illustrating another exemplary process for determining at least two candidate blocks according to some embodiments of the present disclosure;

[0023] FIG. **11**F is a schematic diagram illustrating another exemplary process for determining at least two candidate blocks according to some embodiments of the present disclosure;

[0024] FIG. **12** is a flowchart illustrating an exemplary process for determining at least two candidate blocks according to some embodiments of the present disclosure;

[0025] FIG. **13** is a schematic diagram illustrating an exemplary process for determining at least two candidate blocks according to some embodiments of the present disclosure;

[0026] FIG. **14** is a flowchart illustrating an exemplary process for determining at least two candidate blocks according to some embodiments of the present disclosure;

[0027] FIG. **15** is a schematic diagram illustrating an exemplary process for determining at least two candidate blocks according to some embodiments of the present disclosure;

[0028] FIG. **16** is a flowchart illustrating an exemplary process for determining at least two candidate blocks according to some embodiments of the present disclosure;

[0029] FIG. **17**A is a schematic diagram illustrating an exemplary process for determining at least two candidate blocks according to some embodiments of the present disclosure;

[0030] FIG. **17**B is a schematic diagram illustrating another exemplary process for determining at least two candidate blocks according to some embodiments of the present disclosure;

[0031] FIG. **17**C is a schematic diagram illustrating another exemplary process for determining at least two candidate blocks according to some embodiments of the present disclosure;

[0032] FIG. **18** is a flowchart illustrating an exemplary process for determining at least two candidate blocks according to some embodiments of the present disclosure;

[0033] FIG. **19** is a flowchart illustrating an exemplary process for determining a predicted value corresponding to a block to be processed according to some embodiments of the present disclosure; and

[0034] FIG. **20** is a flowchart illustrating an exemplary process for determining a predicted value corresponding to a block to be processed according to some embodiments of the present disclosure.

DETAILED DESCRIPTION

[0035] In the following detailed description, numerous specific details are set forth by way of examples in order to provide a thorough understanding of the relevant disclosure. However, it should be apparent to those skilled in the art that the present disclosure may be practiced without such details. In other instances, well-known methods, procedures, systems, components, and/or circuitry have been described at a relatively high-level, without detail, in order to avoid unnecessarily obscuring aspects of the present disclosure. Various modifications to the disclosed embodiments will be readily apparent to those skilled in the art, and the general principles defined herein may be applied to other embodiments and applications without departing from the spirit and scope of the present disclosure. Thus, the present disclosure is not limited to the embodiments shown, but to be accorded the widest scope consistent with the claims.

[0036] It will be understood that the terms "system," "engine," "unit," "module," and/or "block" used herein are one method to distinguish different components, elements, parts, sections, or assemblies of different levels in ascending order. However, the terms may be displaced by other expression(s) if they may achieve the same purpose.

[0037] Generally, the words "module," "unit," or "block," as used herein, refer to logic embodied in hardware or firmware, or to a collection of software instructions. A module, a unit, or a block described herein may be implemented as software and/or hardware and may be stored in any type of non-transitory computer-readable medium or other storage device(s). In some embodiments, a software module/unit/block may be compiled and linked into an executable program. It will be appreciated that software modules can be callable from other modules/units/blocks or from themselves, and/or may be invoked in response to detected events or interrupts. Software modules/units/blocks configured for execution on computing devices may be provided on a computer-readable medium, such as a compact disc, a digital video disc, a flash drive, a magnetic disc, or any other tangible medium, or as a digital download (and can be originally stored in a compressed or installable format that needs installation, decompression, or decryption prior to execution). Such software code may be stored, partially or fully, on a storage device of the executing computing device, for execution by the computing device. Software instructions may be embedded in firmware, such as an EPROM. It will be further appreciated that hardware modules (or units or blocks) may be included in connected logic components, such as gates and flip-flops, and/or can be included in programmable units, such as programmable gate arrays or processors. The modules (or units or blocks) or computing device functionality described herein may be implemented as software modules (or units or blocks), but may be represented in hardware or firmware. In general, the modules (or units or blocks) described herein refer to logical modules (or units or blocks) that may be combined with other modules (or units or blocks) or divided into sub-modules (or sub-units or sub-blocks) despite their physical organization or storage.

[0038] It will be understood that when a unit, engine, module, or block is referred to as being "on," "connected to," or "coupled to" another unit, engine, module, or block, it may be directly on, connected or coupled to, or communicate with the other unit, engine, module, or block, or an intervening unit, engine, module, or block may be present, unless the context clearly indicates otherwise. As used herein, the term "and/or" includes any and all combinations of one or more of the associated listed items.

[0039] The terminology used herein is for the purposes of describing particular examples and embodiments only and is not intended to be limiting. As used herein, the singular forms "a," "an," and "the" may be intended to include the

plural forms as well, unless the context clearly indicates otherwise. It will be further understood that the terms "include" and/or "comprise," when used in this disclosure, specify the presence of integers, devices, behaviors, stated features, steps, elements, operations, and/or components, but do not exclude the presence or addition of one or more other integers, devices, behaviors, features, steps, elements, operations, components, and/or groups thereof.

[0040] In the present disclosure, a representation of an object (e.g., a person, a vehicle, a license plate, a road, a lane line) in an image may be referred to as an "object" for brevity. For instance, a representation of a license plate in an image may be referred to as a "license plate" for brevity. Further, an operation performed on a representation of an object in an image may be referred to as an "operation performed on the object" for brevity. For instance, an identification of a portion of an image including a representation of a lane line from the image may be referred to as an "identification of a lane line" for brevity.

[0041] An aspect of the present disclosure relates to a system and method for image processing. The system may obtain an image including a plurality of processed blocks and at least one block to be processed. For a block to be processed among the at least one block to be processed, the system may determine at least two candidate blocks among the plurality of processed blocks, and determine a predicted value corresponding to the block to be processed based on the at least two candidate blocks.

[0042] According to some embodiments of the present disclosure, at least two candidate blocks corresponding to a current block may be determined and block weights may be allocated for the at least two candidate blocks (e.g., according to cost values of the at least two candidate blocks). Further, a predicted value corresponding to the current block may be determined based on the at least two candidate blocks and the block weights thereof for encoding the current block. As more block information is used, the determined predicted value corresponding to the current block may be closer to the true value of the current block than a predicted value determined based on a single candidate block, thus the compression rate of the encoded bitstream of the current block and the decoded image quality of the current block can be efficiently improved.

[0043] FIG. **1** is a schematic diagram illustrating an exemplary image processing system according to some embodiments of the present disclosure. As illustrated in FIG. **1**, the image processing system **100** may include an image acquisition device **110**, a processing device **120**, a network **130**, a terminal device **140**, and a storage device **150**.

[0044] The image acquisition device **110** may be configured to capture an image or video. In some embodiments, the image acquisition device **110** may include a camera **111**, a video acquisition device **112**, or the like, or any combination thereof. In some embodiments, the image acquisition device **110** may transmit captured images or videos to one or more components (e.g., the processing device **120**, the terminal device **140**, the storage device **150**) of the image processing system **100**.

[0045] The processing device **120** may be a single server or a server group. The server group may be centralized or distributed (e.g., the processing device **120** may be a distributed system). In some embodiments, the processing device **120** may be local or remote. For example, the processing device **120** may access information and/or data stored in the image acquisition device **110**, the terminal device **140**, and/or the storage device **150** via the network **130**. As another example, the processing device **120** may be directly connected to the image acquisition device **110**, the terminal device **140**, and/or the storage device **150** to access stored information and/or data. In some embodiments, the processing device **120** may be implemented on a cloud platform. Merely by way of example, the cloud platform may include a private cloud, a public cloud, a hybrid cloud, a community cloud, a distributed cloud, an inter-cloud, a multi-cloud, or the like, or any combination thereof. In some embodiments, the processing device **120** may be implemented on a computing device **200** including one or more components illustrated in FIG. **2** of the present disclosure.

[0046] In some embodiments, the processing device **120** may process information and/or data relating to image processing to perform one or more functions described in the present disclosure. For example, the processing device **120** may obtain an image including a plurality of processed blocks and at least one block to be processed. For a block to be processed among the at least one block to be processed, the processing device **120** may determine at least two candidate blocks among the plurality of processed blocks. Further, the processing device **120** may determine a predicted value corresponding to the block to be processed based on the at least two candidate blocks. In some embodiments, the processing device **120** may include one or more processing devices (e.g., single-core processing device(s) or multi-core processor(s)). Merely by way of example, the processing device **120** may include a central processing unit (CPU), an application-specific integrated circuit (ASIC), an application-specific instruction-set processor (ASIP), a graphics processing unit (GPU), a physics processing unit (PPU), a digital signal processor (DSP), a field programmable gate array (FPGA), a programmable logic device (PLD), a controller, a microcontroller unit, a reduced instruction-set computer (RISC), a microprocessor, or the like, or any combination thereof.

[0047] The network **130** may facilitate exchange of information and/or data for the image processing system **100**. In some embodiments, one or more components (e.g., the processing device **120**, the image acquisition device **110**, the terminal device **140**, the storage device **150**) of the image processing system **100** may transmit information and/or data to other component(s) of the image processing system **100** via the network **130**. For example, the processing device **120** may obtain the image from the image acquisition device **110** via the network **130**. As another example, the processing device **120** may transmit an encoded image to the terminal device **140** via the network **130**. In some embodiments, the network **130** may be any type of wired or wireless network, or combination thereof.

[0048] The terminal device **140** may be configured to receive information and/or data from the image acquisition device **110**, the processing device **120**, and/or the storage device **150** via the network **130**. For example, the terminal device **140** may receive the encoded image from the processing device **120**. In some embodiments, the terminal device **140** may process information and/or data received from the image acquisition device **110**, the processing device **120**, and/or the storage device **150** via the network **130**. For example, the terminal device **140** may decode the encoded image received from the processing device **120** for display. In some embodiments, the terminal device **140** may

provide a user interface via which a user may view information and/or input data and/or instructions to the image processing system **100**. For example, the user may view the decoded image via the user interface. In some embodiments, the terminal device **140** may include a mobile phone **140-1**, a computer **140-2**, a wearable device **140-3**, or the like, or any combination thereof.

[0049] The storage device **150** may be configured to store data and/or instructions. The data and/or instructions may be obtained from, for example, the image acquisition device **110**, the processing device **120**, the terminal device **140**, and/or any other component of the image processing system **100**. In some embodiments, the storage device **150** may store data and/or instructions that the processing device **120** may execute or use to perform exemplary methods described in the present disclosure. In some embodiments, the storage device **150** may include a mass storage, a removable storage, a volatile read-and-write memory, a read-only memory (ROM), or the like, or any combination thereof. In some embodiments, the storage device **150** may be implemented on a cloud platform. Merely by way of example, the cloud platform may include a private cloud, a public cloud, a hybrid cloud, a community cloud, a distributed cloud, an inter-cloud, a multi-cloud, or the like, or any combination thereof.

[0050] In some embodiments, the storage device **150** may be connected to the network **130** to communicate with one or more components (e.g., the image acquisition device **110**, the processing device **120**, the terminal device **140**) of the image processing system **100**. One or more components of the image processing system **100** may access the data or instructions stored in the storage device **150** via the network **130**. In some embodiments, the storage device **150** may be directly connected to or communicate with one or more components (e.g., the image acquisition device **110**, the processing device **120**, the terminal device **140**) of the image processing system **100**. In some embodiments, the storage device **150** may be part of other components of the image processing system **100**, such as the image acquisition device **110**, the processing device **120**, or the terminal device **140**.

[0051] It should be noted that the above description is merely provided for the purposes of illustration, and not intended to limit the scope of the present disclosure. For persons having ordinary skills in the art, multiple variations and modifications may be made under the teachings of the present disclosure. However, those variations and modifications do not depart from the scope of the present disclosure. In some embodiments, one or more components of the image processing system **100** may be integrated into one component or be omitted. In some embodiments, one or more additional components may be added in the image processing system **100**. Such variations are within the scope of the present disclosure.

[0052] FIG. **2** is a schematic diagram illustrating exemplary hardware and/or software components of an exemplary computing device according to some embodiments of the present disclosure. In some embodiments, the processing device **120** may be implemented on the computing device **200**.

[0053] The computing device **200** may be used to implement any component of the image processing system **100** as described herein. For example, the processing device **120** may be implemented on the computing device **200**, via its hardware, software program, firmware, or a combination thereof. Although only one such computer is shown, for convenience, the computer functions relating to image processing as described herein may be implemented in a distributed fashion on a number of similar platforms to distribute the processing load.

[0054] The computing device **200**, for example, may include COM ports **250** connected to and from a network connected thereto to facilitate data communications. The computing device **200** may also include a processor (e.g., a processor **220**), in the form of one or more processors (e.g., logic circuits), for executing program instructions. For example, the processor **220** may include interface circuits and processing circuits therein. The interface circuits may be configured to receive electronic signals from a bus **210**, wherein the electronic signals encode structured data and/or instructions for the processing circuits to process. The processing circuits may conduct logic calculations, and then determine a conclusion, a result, and/or an instruction encoded as electronic signals. Then the interface circuits may send out the electronic signals from the processing circuits via the bus **210**.

[0055] The computing device **200** may further include program storage and data storage of different forms including, for example, a disk **270**, a read-only memory (ROM) **230**, or a random-access memory (RAM) **240**, for storing various data files to be processed and/or transmitted by the computing device **200**. The computing device **200** may also include program instructions stored in the ROM **230**, RAM **240**, and/or another type of non-transitory storage medium to be executed by the processor **220**. The methods and/or processes of the present disclosure may be implemented as the program instructions. The computing device **200** may also include an I/O component **260**, supporting input/output between the computing device **200** and other components. The computing device **200** may also receive programming and data via network communications.

[0056] Merely for illustration, only one processor is illustrated in FIG. **2**. Multiple processors **220** are also contemplated; thus, operations and/or method steps performed by one processor **220** as described in the present disclosure may also be jointly or separately performed by the multiple processors. For example, if in the present disclosure the processor **220** of the computing device **200** executes both step A and step B, it should be understood that step A and step B may also be performed by two different processors **220** jointly or separately in the computing device **200** (e.g., a first processor executes step A and a second processor executes step B, or the first and second processors jointly execute steps A and B).

[0057] FIG. **3** is a schematic diagram illustrating exemplary hardware and/or software components of an exemplary mobile device according to some embodiments of the present disclosure. In some embodiments, the terminal device **140** may be implemented on the mobile device **300** shown in FIG. **3**.

[0058] As illustrated in FIG. **3**, the mobile device **300** may include a communication platform **310**, a display **320**, a graphic processing unit (GPU) **330**, a central processing unit (CPU) **340**, an I/O **350**, a memory **360**, and a storage **390**. In some embodiments, any other suitable component, including but not limited to a system bus or a controller (not shown), may also be included in the mobile device **300**.

[0059] In some embodiments, an operating system (OS) **370** (e.g., iOS™, Android™, Windows Phone™) and one or

more applications (Apps) **380** may be loaded into the memory **360** from the storage **390** in order to be executed by the CPU **340**. The applications **380** may include a browser or any other suitable mobile apps for receiving and rendering information relating to image processing or other information from the processing device **120**. User interactions may be achieved via the I/O **350** and provided to the processing device **120** and/or other components of the image processing system **100** via the network **130**.

[0060] FIG. **4** is a block diagram illustrating an exemplary processing device according to some embodiments of the present disclosure. As shown in FIG. **4**, the processing device **120** may include an obtaining module **410**, a candidate block determination module **420**, and a predicted value determination module **430**.

[0061] The obtaining module **410** may be configured to obtain data and/or information from one or more components of the image processing system **100**. The obtaining module **410** may obtain an image (or a frame of a video) including a plurality of processed blocks and at least one block to be processed. More descriptions regarding the obtaining of the image, the processed blocks, and the block to be processed may be found elsewhere in the present disclosure.

[0062] The candidate block determination module **420** may be configured to determine at least two candidate blocks among the plurality of processed blocks. More descriptions regarding the determination of the at least two candidate blocks may be found elsewhere in the present disclosure (e.g., operation **520**, FIGS. **6-18**, and relevant descriptions thereof).

[0063] The predicted value determination module **430** may be configured to determine a predicted value corresponding to the block to be processed based on the at least two candidate blocks. More descriptions regarding the determination of the predicted value may be found elsewhere in the present disclosure (e.g., operation **530**, FIGS. **19** and **20**, and relevant descriptions thereof).

[0064] The modules in the processing device **120** may be connected to or communicated with each other via a wired connection or a wireless connection. The wired connection may include a metal cable, an optical cable, a hybrid cable, or the like, or any combination thereof. The wireless connection may include a Local Area Network (LAN), a Wide Area Network (WAN), a Bluetooth, a ZigBee, a Near Field Communication (NFC), or the like, or any combination thereof. Two or more of the modules may be combined into a single module, and any one of the modules may be divided into two or more units. In some embodiments, the processing device **120** may include one or more additional modules. For example, the processing device **120** may include an encoding module configured to encode the at least one block to be processed based on the predicted value(s) corresponding to the at least one block to be processed. As another example, the processing device **120** may include a communication module configured to transmit the encoded block(s) to one or more components (e.g., the terminal device **140**) of the image processing system **100**. As still another example, the processing device **120** may include a storage module (not shown) for storing information and/or data (e.g., the coded image or the coded block) generated by the processing device **120**.

[0065] FIG. **5** is a flowchart illustrating an exemplary process for image processing according to some embodiments of the present disclosure. In some embodiments, the image processing may include a process of intra prediction coding (or coding by intra prediction mode). In some embodiments, one or more operations in the process **500** may be implemented by the image processing system **100** illustrated in FIG. **1**. For example, one or more operations in the process **500** may be stored in a storage device (e.g., the storage device **150**, the ROM **230**, the RAM **240**, and/or the storage **390**) as a form of instructions, and invoked and/or executed by the processing device **120** (e.g., the processor **220**, the CPU **340**, and/or one or more modules illustrated FIG. **4**). The operations of the illustrated process presented below are intended to be illustrative. In some embodiments, the process may be accomplished with one or more additional operations not described, and/or without one or more of the operations discussed. Additionally, the order in which the operations of the process as illustrated in FIG. **5** and described below is not intended to be limiting.

[0066] In **510**, the processing device **120** (e.g., the obtaining module **410**) may obtain an image including a plurality of processed blocks and at least one block to be processed.

[0067] In some embodiments, the image may include a discrete image or a video frame to be encoded. In some embodiments, the image may be divided into a plurality of blocks according to a coding order (e.g., from left to right and from top to bottom). In some embodiments, a block of the image may include a square block or a non-square block (e.g., a rectangle block). In some embodiments, a size of the block may be 4×4, 8×8, 16×8, 8×16, etc. In some embodiments, the sizes of the plurality of blocks may be the same or different. For example, the numbers (or counts) of the pixels included in the plurality of blocks may be the same or different. In some embodiments, the shapes of the plurality of blocks may be the same or different.

[0068] In some embodiments, the plurality of blocks may include the plurality of processed blocks and the at least one block to be processed. As used herein, a processed block may refer to a block that has been coded and includes a plurality of coded pixels, and a block to be processed may refer to a block to be coded (also referred to as a current block) and includes a plurality of un-coded pixels. In some embodiments, the number (or count) of the plurality of processed blocks may be the same as or different from the number (or count) of at least one block to be processed. In some embodiments, the sizes of the plurality of processed blocks may be the same as or different from the size(s) of the at least one block to be processed.

[0069] In some embodiments, the image may be stored in a storage device (e.g., the storage device **150**, the ROM **230**, the RAM **240**, and/or the storage **390**). The processing device **120** may retrieve the image from the storage device. In some embodiments, the image may be acquired by an image acquisition device (e.g., the image acquisition device **110**). The processing device **120** may directly obtain the image from the image acquisition device.

[0070] In **520**, for a block to be processed among the at least one block to be processed, the processing device **120** (e.g., the candidate block determination module **420**) may determine at least two candidate blocks among the plurality of processed blocks.

[0071] As used herein, a candidate block refers to a processed block that is determined from the plurality of processed blocks and has a matching relation with the at least one block to be processed (e.g., the candidate block can

be used for coding the at least one block to be processed). In some embodiments, the candidate block may also be referred to as a matching block.

[0072] In some embodiments, the processing device **120** may determine the at least two candidate blocks among the plurality of processed blocks for the block to be processed according to one or more processing modes (also referred to as searching modes).

[0073] For example, the processing device **120** may determine the at least two candidate blocks among the plurality of processed blocks for the block to be processed according to a first processing mode. The first processing mode may include determining a reference region (also referred to as a template region) of the block to be processed and determining the at least two candidate blocks among the plurality of processed blocks based on the reference region of the block to be processed, more descriptions of which can be found elsewhere in the present disclosure (e.g., FIGS. **6** and **7** and the relevant descriptions thereof).

[0074] As another example, the processing device **120** may determine the at least two candidate blocks among the plurality of processed blocks for the block to be processed according to a second processing mode. The second processing mode may include determining multiple processed blocks that are within a preset distance from the block to be processed and determining the at least two candidate blocks from the multiple processed blocks, more descriptions of which can be found elsewhere in the present disclosure (e.g., FIGS. **8** and **9** and the relevant descriptions thereof).

[0075] As still another example, the processing device **120** may determine the at least two candidate blocks among the plurality of processed blocks for the block to be processed according to a third processing mode. The third processing mode may include determining at least two reference regions of the block to be processed and determining the at least two candidate blocks based on the at least two reference regions, more descriptions of which can be found elsewhere in the present disclosure (e.g., FIGS. **10-17** and the relevant descriptions thereof).

[0076] In some embodiments, the processing device **120** may determine, based on the one or more processing modes, one or more intermediate blocks corresponding to each of the one or more processing modes among the plurality of processed blocks. Then the processing device **120** may determine the one or more intermediate blocks corresponding to each of the one or more processing modes as the at least two candidate blocks, more descriptions of which can be found elsewhere in the present disclosure (e.g., FIG. **18** and the relevant description thereof).

[0077] In **530**, the processing device **120** (e.g., the predicted value determination module **430**) may determine a predicted value corresponding to the block to be processed based on the at least two candidate blocks.

[0078] As used herein, the predicted value corresponding to the block to be processed may be used to encode the current block.

[0079] In some embodiments, the processing device **120** may determine block weights for the at least two candidate blocks and determine the predicted value corresponding to the block to be processed based on the block weights and the at least two candidate blocks. As used herein, a block weight corresponding to a candidate block may indicate a contribution degree of the candidate block in determining the predicted value corresponding to the block to be processed.

[0080] In some embodiments, the processing device **120** may determine the block weights for the at least two candidate blocks according to a difference value between each of the at least two candidate blocks and the block to be processed. As used herein, the difference value between a candidate block and the block to be processed may indicate a difference (e.g., a pixel difference) between the candidate block and the block to be processed. The smaller the difference value is, the smaller the difference between the candidate block and the block to be processed may be. In some embodiments, the processing device **120** may rank the at least two candidate blocks based on the difference values (e.g., cost values) of the at least two candidate blocks in ascending order or a descending order. As used herein, in ascending order, a candidate block corresponding to a small difference value is ranked before a candidate block corresponding to a great difference value; and in descending order, the candidate block corresponding to the small difference value is ranked after the candidate block corresponding to the great difference value. Then the processing device **120** may determine the block weights for the at least two candidate blocks based on the ranking result.

[0081] In some embodiments, the difference value may be determined based on at least one of a cost value of the candidate block or a distance between the candidate block and the block to be processed. As used herein, the cost value may reflect a difference between a candidate block and the block to be processed or a difference between a matching region (e.g., a processed region matching with the reference region) and the reference region of the block to be processed. Merely by way of example, the cost value may be denoted by a sum of absolute difference (SAD) between the matching region and the reference region. Alternatively, the cost value may be positively related to the SAD between the matching region and the reference region. More descriptions regarding the matching region and/or the reference region may be found elsewhere in the present disclosure (e.g., FIG. **6** and relevant description thereof).

[0082] In some embodiments, as described in connection with above, for each of the one or more processing modes, the processing device **120** may determine a block weight corresponding to each of one or more intermediate blocks that correspond to the processing mode. For each of the one or more processing modes, the processing device **120** may determine a mode weight corresponding to the processing mode. Then processing device **120** may determine the predicted value corresponding to the block to be processed by performing a weighting processing on the at least two candidate blocks based on the block weights corresponding to the one or more processing modes and the one or more mode weights corresponding to the one or more processing modes, more descriptions of which can be found elsewhere in the present disclosure (e.g., FIG. **19** and the description thereof).

[0083] In some embodiments, the processing device **120** may determine a plurality of weighting modes each of which corresponds to at least one of the one or more processing modes. For each of the plurality of weighting modes, the processing device **120** may determine a block weight of each of one or more intermediate blocks that correspond to the one or more processing modes, determine a mode weight corresponding to each of the one or more processing modes, and determine an intermediate predicted value corresponding to the block to be processed by performing, according to

the weighting mode, a weighting processing on the at least two candidate blocks based on the block weights corresponding to the one or more processing modes and the one or more mode weights corresponding to the one or more processing modes. Then the processing device **120** may determine the predicted value corresponding to the block to be processed based on a plurality of intermediate predicted values corresponding to the plurality of weighting modes respectively, more descriptions of which can be found elsewhere in the present disclosure (e.g., FIG. **20** and the relevant description thereof).

[0084] In some embodiments, after the predicted value is determined, the processing device **120** (e.g., the encoding module thereof) may encode the block to be processed based the predicted value corresponding to the block to be processed into an encoded bitstream. In some embodiments, the encoded bitstream can reflect residual information between the block to be processed and the predicted value corresponding to the block to be processed. In some embodiments, the encoded bitstream may be transmitted to a receiving end (e.g., an encoder). The receiving end may decode the residual information in the encoded bitstream and determine the block to be processed based on the residual information and the predicted value corresponding to the coding block. More descriptions regarding the encoding and decoding can be found elsewhere in the present disclosure (e.g., FIG. **19** and FIG. **20** and relevant descriptions thereof).

[0085] According to the embodiments of the present disclosure, by obtaining the at least two candidate blocks and allocating block weights for the candidate blocks according to the difference between the candidate blocks and the block to be processed, the block to be processed can be predicted using more intra information. The predicted value corresponding to the block to be processed may be determined based on the candidate blocks and the block weights thereof, and the block to be processed may be encoded based on the predicted value. As the determined predicted value utilizes more candidate block information, the predicted value may be closer to the block to be processed than a predicted value which is determined based on a single candidate block, thereby the compression rate of the encoded bitstream and the image quality of the block to be processed obtained after decoding can be improved. In addition, by obtaining the predicted value using the one or more reference regions, more image information can be used for intra prediction.

[0086] It should be noted that the above description is merely provided for the purposes of illustration, and not intended to limit the scope of the present disclosure. For persons having ordinary skills in the art, multiple variations or modifications may be made under the teachings of the present disclosure. However, those variations and modifications do not depart from the scope of the present disclosure. In some embodiments, after operation **530**, the process **500** may include an encoding operation for encoding the at least one block to be processed.

[0087] FIG. **6** is a flowchart illustrating an exemplary process for determining at least two candidate blocks according to some embodiments of the present disclosure. In some embodiments, one or more operations in the process **600** may be implemented by the image processing system **100** illustrated in FIG. **1**. For example, one or more operations in the process **600** may be stored in a storage device (e.g., the storage device **150**, the ROM **230**, the RAM **240**, and/or the storage **390**) as a form of instructions, and invoked and/or executed by the processing device **120** (e.g., the processor **220**, the CPU **340**, and/or one or more modules illustrated FIG. **4**). The operations of the illustrated process presented below are intended to be illustrative. In some embodiments, the process may be accomplished with one or more additional operations not described, and/or without one or more of the operations discussed. Additionally, the order in which the operations of the process as illustrated in FIG. **6** and described below is not intended to be limiting. In some embodiments, operation **520** in FIG. **5** may be achieved by operations of the process **600**. As described in connection with operation **520**, the process **600** may correspond to the first processing mode.

[0088] In some embodiments, the processing device **120** (e.g., the candidate block determination module **420**) may determine a reference region of a block to be processed.

[0089] As used herein, the reference region may refer to a coded region in a vicinity of the block to be processed is located. For example, the processing device **120** may determine at least one of a left region of the block to be processed, an upper region of the block to be processed, or a left-upper region of the block to be processed as the reference region of the block to be processed. The left region of the block to be processed may include one or more coded pixels adjacent and/or close to the block to be processed on the left side of the block to be processed. The one or more coded pixels of the left region may be arranged in one or more columns. The reference region including only the left region may also be referred to as a reference region of a first type. The upper region of the block to be processed may include one or more coded pixels adjacent and/or close to the block to be processed on the upper side of the block to be processed. The one or more coded pixels of the upper region may be arranged in one or more rows. The reference region including only the upper region may also be referred to as a reference region of a second type. The left-upper region of the block to be processed may include one or more coded pixels adjacent and/or close to the block to be processed on the left side of the block to be processed and one or more coded pixels adjacent and/or close to the block to be processed on the upper side of the block to be processed. The one or more coded pixels of the left-upper region on the left side of the block to be processed may be arranged in one or more columns, and the one or more coded pixels of the left-upper region on the upper side of the block to be processed may be in arranged in one or more rows. The reference region including the left-upper region may also be referred to as a reference region of a third type.

[0090] Merely by way of example, as shown in FIG. **7**, a current block **710** may the block to be processed, and a reference region **711** may be a left-upper region of the current block **710**. It should be noted that the reference region **711** in FIG. **7** with an L-shape is provided for illustration purposes, the shape of the reference region **711** may be other shapes as long as the reference region **711** includes one or more coded pixels adjacent and/or close to the current block **710** on the left side of current block **710** and one or more coded pixels adjacent and/or close to the current block **710** on the upper side of the current block **710**. In some embodiments, the coded pixels in the reference region may be continuous or discontinuous. For example,

for the reference region including a left region of the block to be processed, the reference region may include a column of coded pixels.

[0091] In **620**, the processing device **120** (e.g., the candidate block determination module **420**) may determine a plurality of matching regions based on the reference region.

[0092] As used herein, a matching region may be a region having a same shape and a same size as the reference region, and a similarity between the matching region and the reference region is larger than a similarity threshold.

[0093] In some embodiments, the processing device **120** may determine the plurality of matching regions in the image based on the reference region and a preset condition. The preset condition may include that a difference (e.g., a cost value or a sum of absolute difference (SAD)) between each of the plurality of matching regions and the reference region is less than or equal to a preset difference (e.g., each of the plurality of matching regions has similar luminance and/or chrominance as the reference region), a distance between each of the plurality of matching regions and the reference region is less than or equal to a preset distance, or the like, or any combination thereof. For example, as illustrated in FIG. **7**, the processing device **120** may determine matching regions **721-1**, **721-2**, and **721-3** based on the reference region **711** according to a searching strategy (e.g., a fast searching strategy a global searching strategy).

[0094] In some embodiments, each of the plurality of matching regions may correspond to a respective one processed block. As used herein, a relative position relationship between the matching region and its corresponding processed block may be the same as a relative position relationship between the reference region and the block to be processed. In some embodiments, a respective processed block corresponding to a matching region may also be referred to as a matching block corresponding to the matching region.

[0095] In **630**, the processing device **120** (e.g., the candidate block determination module **420**) may determine the respective processed blocks corresponding to the plurality of matching regions as the at least two candidate blocks.

[0096] In some embodiments, as mentioned above, a relative position relationship between the matching region and the respective matching block may be the same as a relative position relationship between the reference region and the block to be processed. Accordingly, the processing device **120** may determine the relative position relationship) between the reference region and the block to be processed, and for each of the plurality of matching regions, the processing device **120** may determine a respective processed block (i.e., a respective matching block) based on the matching region and the relative position relationship between the reference region and the block to be processed. For example, as illustrated in FIG. **7**, the processing device **120** may determine respective matching blocks **722-1**, **722-2**, and **722-3** corresponding to the matching regions **721-1**, **721-2**, and **721-3** respectively based on a relative position relationship between the reference region **711** and the current block **710**.

[0097] In some embodiments, the processing device **120** may designate the respective matching blocks corresponding to the plurality of matching regions as the at least two candidate blocks. In some embodiments, the processing device **120** may determine a portion of the respective matching blocks as the at least two candidate blocks. For example, the processing device **120** may rank the plurality of matching regions according to cost values of the plurality of matching regions in ascending order. Then the processing device **120** may determine a preset count of the at least two candidate blocks and designate matching blocks corresponding to the top-ranked matching regions with the preset count as the at least two candidate blocks. For example, as illustrated in FIG. **7**, the processing device **120** may rank the matching regions **721-1**, **721-2**, and **721-3** based on corresponding cost values and designate the matching blocks **722-1** and **722-3** as the at least two candidate blocks based on the ranking result.

[0098] It should be noted that the above description is merely provided for the purposes of illustration, and not intended to limit the scope of the present disclosure. For persons having ordinary skills in the art, multiple variations or modifications may be made under the teachings of the present disclosure. However, those variations and modifications do not depart from the scope of the present disclosure.

[0099] FIG. **8** is a flowchart illustrating an exemplary process for determining at least two candidate blocks according to some embodiments of the present disclosure. In some embodiments, one or more operations in the process **800** may be implemented by the image processing system **100** illustrated in FIG. **1**. For example, one or more operations in the process **600** may be stored in a storage device (e.g., the storage device **150**, the ROM **230**, the RAM **240**, and/or the storage **390**) as a form of instructions, and invoked and/or executed by the processing device **120** (e.g., the processor **220**, the CPU **340**, and/or one or more modules illustrated FIG. **4**). The operations of the illustrated process presented below are intended to be illustrative. In some embodiments, the process may be accomplished with one or more additional operations not described, and/or without one or more of the operations discussed. Additionally, the order in which the operations of the process as illustrated in FIG. **8** and described below is not intended to be limiting. In some embodiments, operation **520** in FIG. **5** may be achieved by operations of the process **800**. As described in connection with operation **520**, the process **800** may correspond to the second processing mode.

[0100] In **810**, the processing device **120** (e.g., the candidate block determination module **420**) may determine, from a plurality of processed blocks, multiple processed blocks (also referred to as multiple matching blocks) that are within a preset distance from a block to be processed.

[0101] As used herein, a distance from the block to be processed to a processed block may be represented by a count of pixels between the block to be processed and the processed block. For example, the distance from the block to be processed to the processed block may be 16384pixels. The distance from the block to be processed to the processed block (also referred to as the distance of the processed block for brevity) may be denoted as a difference value between the block to be processed and the processed block.

[0102] In some embodiments, the processing device **120** may select, from the plurality of processed blocks, initial processed blocks having the same size as the block to be processed. Then the processing device **120** may determine the distance from the block to be processed to each of the initial processed blocks. Further, the processing device **120** may determine, from the initial processed blocks, the multiple processed blocks that are within the preset distance

from the block to be processed. The preset distance may be a default setting of the image processing system **100** or adjustable according to different situations. For example, the preset distance may be 8192 pixels.

[0103] In **820**, the processing device **120** (e.g., the candidate block determination module **420**) may rank the multiple processed blocks based on cost values of the multiple processed blocks and/or distances of the multiple processed blocks.

[0104] In some embodiments, the processing device **120** may rank the multiple processed blocks based on the distances of the multiple processed blocks in ascending order. In some embodiments, if distances of two processed blocks are equal to each other, the two processed blocks may be ranked according to a preset rule (e.g., a processed block on the left side of the block to be processed may be ranked before a processed block on the upper side of the block to be processed).

[0105] In some embodiments, the processing device **120** may determine multiple matching regions corresponding to the multiple processed blocks respectively based on a reference region corresponding to the block to be processed. For example, as mentioned above, a relative position relationship between the reference region and the block to be processed may be the same as a relative position relationship between a matching region and its corresponding processed block. The processing device **120** may determine a cost value between the reference region corresponding to the block to be processed and each of the multiple matching regions. Then the processing device **120** may rank the multiple processed blocks according to the cost values of the multiple matching regions in ascending order.

[0106] In **830**, the processing device **120** (e.g., the candidate block determination module **420**) may determine at least two candidate blocks based on the ranking result.

[0107] In some embodiments, the processing device **120** may select at least two processed blocks among the multiple processed blocks based on the ranking result as the at least two candidate blocks. For example, the processing device **120** may designate at least two top-ranked processed blocks as the at least two candidate blocks.

[0108] For example, as shown in FIG. **9**, a current block R**1** may be a block to be processed and blocks A**1**, A**2**, A**3**, A**4**, and A**5** may be the selected multiple processed blocks. It can be seen that a distance between the current block R**1** to each of the blocks A**1** and A**2** is a, a distance between the current block R**1** to each of the blocks A**3** and A**4** is b (b>a), and a distance between the current block R**1** and the block A**5** is greater than b. As the distances of the blocks A**1** and A**2** are the same and the distances of the blocks A**3** and A**4** are the same, the blocks A**1**, A**2**, A**3**, A**4**, and A**5** may be ranked according to the preset rule (e.g., "the left side, the upper side, and the left and upper side") as A**1**, A**2**, A**3**, A**4**, and A**5**. Further, the top three blocks A**1**, A**2**, and A**3** may be determined as the at least two candidate blocks based on the ranking result.

[0109] It should be noted that the above description is merely provided for the purposes of illustration, and not intended to limit the scope of the present disclosure. For persons having ordinary skills in the art, multiple variations or modifications may be made under the teachings of the present disclosure. However, those variations and modifications do not depart from the scope of the present disclosure.

[0110] FIG. **10** is a flowchart illustrating an exemplary process for determining at least two candidate blocks according to some embodiments of the present disclosure. In some embodiments, one or more operations in the process **1000** may be implemented by the image processing system **100** illustrated in FIG. **1**. For example, one or more operations in the process **600** may be stored in a storage device (e.g., the storage device **150**, the ROM **230**, the RAM **240**, and/or the storage **390**) as a form of instructions, and invoked and/or executed by the processing device **120** (e.g., the processor **220**, the CPU **340**, and/or one or more modules illustrated FIG. **4**). The operations of the illustrated process presented below are intended to be illustrative. In some embodiments, the process may be accomplished with one or more additional operations not described, and/or without one or more of the operations discussed. Additionally, the order in which the operations of the process as illustrated in FIG. **10** and described below is not intended to be limiting. In some embodiments, operation **520** in FIG. **5** may be achieved by operations of the process **1000**. As described in connection with operation **520**, the process **1000** may correspond to the third processing mode.

[0111] In **1010**, the processing device **120** (e.g., the candidate block determination module **420**) may determine at least two reference regions of a block to be processed.

[0112] As described in connection with operation **610**, the at least two reference regions may include at least two of a left region of the block to be processed, an upper region of the block to be processed, or a left-upper region of the block to be processed, that is, the at least two reference regions may include at least two regions with different types (e.g., the first type, the second type, the third type). Alternatively, the at least two reference regions may include different reference regions with the same type. For example, for at least one of the three types, the processing device **120** may determine two or more reference regions (e.g., reference regions with different sizes) of the block to be processed. Accordingly, the processing device **120** may determine at least two reference regions with the same type.

[0113] In some embodiments, sizes of the at least two reference regions, positions of the at least two reference regions, and/or a count of the at least two reference regions may be adjusted adaptively, for example, according to parameters (e.g., a size, a shape) of the block to be processed and/or encoding needs (e.g., a compression rate, a compression quality) of the block to be processed. That is, the processing device **120** may determine and/or adjust the at least two reference regions according to the parameters and/or encoding needs of the block to be processed.

[0114] For example, the reference region of the first type may include coded pixels arranged in one or more columns. A length of the reference region of the first type along the column may be equal to, greater than, or less than a left side length of the block to be processed according to actual encoding needs. As another example, the reference region of the second type may include coded pixels arranged in one or more rows. A length of the reference region of the second type along the row may be equal to, greater than, or less than an upper side length of the block to be processed according to actual encoding needs. As still another example, the reference region of the third type may include coded pixels arranged in one or more columns on the left side of the block to be processed and coded pixels arranged in one or more rows on the upper side of the block to be processed. A length

(also can be referred to as a column length) of the reference region of the third type along the column may be equal to, greater than, or less than the left side length of the block to be processed, and a length (also can be referred to as a row length) of the reference region of the third type along the row may be equal to, greater than, or less than the upper side length of the block to be processed according to actual encoding needs.

[0115] For illustration purposes, FIGS. **11**A-**11**F illustrate different reference regions of a current block **1111**. As shown in FIG. **1**A, a length of a reference region **1112-1** of the first type is equal to a left side length the current block **1111**. As shown in FIG. **11**B, a length of a reference region **1112-2** of the second type is less than an upper side length of the current block **1111**. As shown in FIG. **11**C, a length of a reference region **1112-3** of the second type is equal to the upper side length of the current block **1111**. It can be seen that a count of coded pixels in the reference region **1112-2** is less than a count of the coded pixels in the reference region **1112-3**. As shown in FIG. **11**D, a column length and a row length of a reference region **1112-4** of the third type (e.g., an L-shaped reference region) are equal to the left side length and the upper side length of the current block **1111** respectively. As shown in FIG. **11**E, a reference region **1112-5** of the third type has coded pixels arranged in two columns and two rows. Accordingly, a column length and a row length of the reference region **1112-5** are greater the left side length and the upper side length of the current block **1111** respectively. As shown in FIG. **11**F, a reference region **1112-6** of the third type has a cross shape, and a column length and a row length of the reference region **1112-6** are greater the left side length and the upper side length of the current block **1111** respectively.

[0116] In **1020**, for each of the at least two reference regions, the processing device **120** (e.g., the candidate block determination module **420**) may determine a plurality of matching regions corresponding to the reference region. More descriptions regarding the determination of the plurality of matching regions can be found elsewhere in the present disclosure (e.g., operation **620** in FIG. **6** and the relevant description thereof).

[0117] In some embodiments, for the at least two reference regions, the corresponding counts of matching regions may be the same or different. For example, as shown in FIGS. **11**A-**11**F, the reference region **1112-1** corresponds to three matching regions **1112-11**, **1112-12**, and **1112-13**; the reference region **1112-2** corresponds to two matching regions **1112-21** and **1112-22**; the reference region **1112-3** corresponds to a matching region **1112-31**; the reference region **1112-4** corresponds to two matching regions **1112-41** and **1112-42**; the reference region **1112-5** corresponds to a matching region **1112-51**; and the reference region **1112-6** corresponds a matching region **1112-61**. The matching regions **1112-11**, **1112-12**, **1112-13**, **1112-21**, **1112-22**, **1112-31**, **1112-41**, **1112-42**, **1112-51**, and **1112-61** may correspond to matching blocks **1113-11**, **1113-12**, **1113-13**, **1113-21**, **1113-22**, **1113-31**, **1113-41**, **1113-42**, **1113-51**, and **1113-61**, respectively.

[0118] In **1030**, the processing device **120** (e.g., the candidate block determination module **420**) may determine the at least two candidate blocks based on matching regions corresponding to the at least two reference regions.

[0119] In some embodiments, the processing device **120** may rank the matching regions corresponding to the at least two reference regions based on cost values of the matching regions corresponding to the at least two reference regions. Then the processing device **120** may determine the at least two candidate blocks based on the ranking result, more descriptions of which can be found elsewhere in the present disclosure (e.g., FIGS. **12** and **13** and the descriptions thereof).

[0120] In some embodiments, for each of the at least two reference regions, the processing device **120** may determine at least one target matching region from the plurality of matching regions. Then the processing device **120** may determine the at least two candidate blocks based on the target matching regions corresponding to the at least two reference regions, more descriptions of which can be found elsewhere in the present disclosure (e.g., FIGS. **14** and **15** and relevant descriptions thereof).

[0121] In some embodiments, for each of the at least two reference regions, the processing device **120** may determine a minimum cost value among cost values of the plurality of matching regions corresponding to the reference region; and select one or more target matching regions from the plurality of machining regions corresponding to the reference region based on the minimum cost value, wherein a count of the one or more target matching regions is negatively related to the minimum cost value corresponding to the reference region. Then the processing device **120** may determine the at least two candidate blocks based on the target machining regions corresponding to the at least two reference regions, more descriptions of which can be found elsewhere in the present disclosure (e.g., FIGS. **16** and **17** and relevant descriptions thereof).

[0122] For illustration purposes, as shown in FIGS. **11**A-**11**B, for each of the matching regions corresponding to the at least two reference regions, the processing device **121** may determine a matching block based on the matching region and the relation between the matching region and the current block **1111**.

[0123] It should be noted that the above description is merely provided for the purposes of illustration, and not intended to limit the scope of the present disclosure. For persons having ordinary skills in the art, multiple variations or modifications may be made under the teachings of the present disclosure. However, those variations and modifications do not depart from the scope of the present disclosure.

[0124] FIG. **12** is a flowchart illustrating an exemplary process for determining at least two candidate blocks according to some embodiments of the present disclosure. In some embodiments, one or more operations in the process **1200** may be implemented by the image processing system **100** illustrated in FIG. **1**. For example, one or more operations in the process **1200** may be stored in a storage device (e.g., the storage device **150**, the ROM **230**, the RAM **240**, and/or the storage **390**) as a form of instructions, and invoked and/or executed by the processing device **120** (e.g., the processor **220**, the CPU **340**, and/or one or more modules illustrated FIG. **4**). The operations of the illustrated process presented below are intended to be illustrative. In some embodiments, the process may be accomplished with one or more additional operations not described, and/or without one or more of the operations discussed. Additionally, the order in which the operations of the process as illustrated in FIG. **12** and described below is not intended to be limiting.

In some embodiments, operation **1030** in FIG. **10** may be achieved by operations of the process **1200**.

[0125] In **1210**, the processing device **120** (e.g., the candidate block determination module **420**) may rank matching regions corresponding to at least two reference regions based on cost values of the matching regions corresponding to the at least two reference regions.

[0126] In some embodiments, for each of the matching regions, the processing device **120** may determine a cost value of the matching region based on the matching region and a reference region corresponding to the matching region (e.g., designate a sum of absolute difference (SAD) between the matching region and the reference region as the cost value of the matching region). The processing device **120** may rank the matching regions corresponding to the at least two reference regions according to the cost values of the matching regions. For example, as shown in FIG. **13**, there are three reference regions **1311**, **1312**, and **1313** corresponding to a current block (not shown). The reference region **1311** corresponds to four matching regions **1321**, **1322**, **1323**, and **1324**. The reference region **1312** corresponds to three matching regions **1325**, **1326**, and **1327**. The reference region **1313** corresponds to two matching regions **1328** and **1329**. The matching regions **1321-1329** are ranked according to the cost values of the matching regions in ascending order.

[0127] In **1220**, the processing device **120** (e.g., the candidate block determination module **420**) may determine the at least two candidate blocks based on the ranking result.

[0128] In some embodiments, the processing device **120** may determine a preset count of target matching regions from the matching regions based on the ranking result. The preset count may be an integer equal to or greater than 2. The preset count may be a default setting of the image processing system **100** or adjustable in different situations. For example, if the matching regions are ranked according to the cost values of the matching region in ascending order, the processing device **120** may determine the preset count of top-ranked matching regions as the target matching regions. Further, the processing device **120** may determine matching blocks corresponding to the target matching regions as the at least two candidate blocks of the block to be processed. For example, as shown in FIG. **13**, the preset count may be 6, and the top six ranked matching regions **1329**, **1326**, **1323**, **1325**, **1321**, and **1324** are determined as target matching regions. Accordingly, matching blocks **1339**, **1336**, **1333**, **1335**, **1331**, and **1334** corresponding to the target matching regions are designated as the at least two candidate blocks of the current block.

[0129] It should be noted that the above description is merely provided for the purposes of illustration, and not intended to limit the scope of the present disclosure. For persons having ordinary skills in the art, multiple variations or modifications may be made under the teachings of the present disclosure. However, those variations and modifications do not depart from the scope of the present disclosure.

[0130] FIG. **14** is a flowchart illustrating an exemplary process for determining at least two candidate blocks according to some embodiments of the present disclosure. In some embodiments, one or more operations in the process **1400** may be implemented by the image processing system **100** illustrated in FIG. **1**. For example, one or more operations in the process **1400** may be stored in a storage device (e.g., the storage device **150**, the ROM **230**, the RAM **240**, and/or the storage **390**) as a form of instructions, and invoked and/or executed by the processing device **120** (e.g., the processor **220**, the CPU **340**, and/or one or more modules illustrated FIG. **4**). The operations of the illustrated process presented below are intended to be illustrative. In some embodiments, the process may be accomplished with one or more additional operations not described, and/or without one or more of the operations discussed. Additionally, the order in which the operations of the process as illustrated in FIG. **14** and described below is not intended to be limiting. In some embodiments, operation **1030** in FIG. **10** may be achieved by operations of the process **1400**.

[0131] In **1410**, for each of at least two reference regions, the processing device **120** (e.g., the candidate block determination module **420**) may rank a plurality of matching regions corresponding to the reference region based on cost values of the plurality of matching regions.

[0132] In some embodiments, the ranking operation is similar to operation **1210** in FIG. **12**. For example, as shown in FIG. **15**, there are three reference regions **1511**, **1512**, and **1513** corresponding to a current block (not shown). The reference region **1511** corresponds to four matching regions **1521**, **1522**, **1523**, and **1524**. The matching regions **1521**, **1522**, **1523**, and **1524** are ranked according to cost values thereof in ascending order. The reference region **1512** corresponds to three matching regions **1525**, **1526**, and **1527**. The matching regions **1525**, **1526**, and **1527** are ranked according to cost values thereof in ascending order. The reference region **1513** corresponds to two matching regions **1528** and **1529**. The matching region **1528** and **1529** are ranked according to cost values thereof in ascending order.

[0133] In **1420**, for each of the at least two reference regions, the processing device **120** (e.g., the candidate block determination module **420**) may determine, based on the ranking result, at least one target matching region from the plurality of matching regions.

[0134] In some embodiments, the target matching region (s) may be selected in a manner similar to operation **1220** in FIG. **12**. In some embodiments, different reference regions may correspond to the same count of target matching regions or different counts of target matching regions. For example, as shown in FIG. **15**, each of the reference regions **1511**, **1512**, and **1513** corresponds to two target matching regions. Two top-ranked matching regions **1523** and **1521** are determined as the target matching regions corresponding to the reference region **1511**. Two top-ranked matching regions **1526** and **1527** are determined as the target matching regions corresponding to the reference region **1512**. Two top-ranked matching regions **1529** and **1528** are determined as the target matching regions corresponding to the reference region **1513**.

[0135] In **1430**, the processing device **120** (e.g., the candidate block determination module **420**) may determine the at least two candidate blocks based on target matching regions corresponding to the at least two reference regions.

[0136] In some embodiments, for each of the target matching regions, the processing device **120** may determine a matching block corresponding to the target matching region. The processing device **120** may designate matching blocks corresponding to the target matching regions as the at least two candidate blocks. For example, as shown in FIG. **15**, candidate blocks **1533**, **1531**, **1536**, **1535**, **1539**, and **1538**

corresponding to the target matching regions are designated as the at least two candidate blocks of the current block.

[0137] In some embodiments, the processing device **120** may rank the target matching regions according to the cost values thereof in ascending order. The processing device **120** may determine matching blocks corresponding to a preset count of top-ranked target matching regions as the at least two candidate blocks. The preset count of top-ranked target matching regions may be a default setting of the image processing system **100** or adjustable according to different situations.

[0138] It should be noted that the above description is merely provided for the purposes of illustration, and not intended to limit the scope of the present disclosure. For persons having ordinary skills in the art, multiple variations or modifications may be made under the teachings of the present disclosure. However, those variations and modifications do not depart from the scope of the present disclosure.

[0139] FIG. **16** is a flowchart illustrating an exemplary process for determining at least two candidate blocks according to some embodiments of the present disclosure. In some embodiments, one or more operations in the process **1600** may be implemented by the image processing system **100** illustrated in FIG. **1**. For example, one or more operations in the process **1600** may be stored in a storage device (e.g., the storage device **150**, the ROM **230**, the RAM **240**, and/or the storage **390**) as a form of instructions, and invoked and/or executed by the processing device **120** (e.g., the processor **220**, the CPU **340**, and/or one or more modules illustrated FIG. **4**). The operations of the illustrated process presented below are intended to be illustrative. In some embodiments, the process may be accomplished with one or more additional operations not described, and/or without one or more of the operations discussed. Additionally, the order in which the operations of the process as illustrated in FIG. **16** and described below is not intended to be limiting. In some embodiments, operation **1030** in FIG. **10** may be achieved by operations of the process **1600**.

[0140] In **1610**, for each of at least two reference regions, the processing device **120** (e.g., the candidate block determination module **420**) may determine a minimum cost value among cost values of a plurality of matching regions corresponding to the reference region.

[0141] In some embodiments, for each of the at least two reference regions, the processing device **120** may rank the plurality of matching regions corresponding to the reference region according to the cost values of the plurality of matching regions in ascending order. The processing device **120** may determine a cost value of the top matching region as the minimum cost value. In some embodiments, the matching region corresponding to the minimum cost value may also be referred to as an optimal matching region corresponding to the reference region, and a matching block corresponding to the optimal region may also be referred to as an optimal candidate block corresponding to the reference region.

[0142] In **1620**, for each of the at least two reference regions, the processing device **120** (e.g., the candidate block determination module **420**) may select one or more target matching regions from the plurality of machining regions corresponding to the reference region.

[0143] In some embodiments, for at least two reference regions, the priority of each reference region may be determined according to the cost value of an optimal matching region corresponding to each of the at least two reference region, and the reference region with the least cost value of the optimal matching region has higher priority. In some embodiments, a first count of reference regions with highest priority may be determined as high-priority reference regions to determine the target matching region. The first count may be preset, e.g., the first count may be preset as 1, 2 or 3, etc.

[0144] In some embodiments, a count of the target matching regions selected from the matching regions corresponding to each high-priority reference region (hereinafter may be referred to as a second count) may be the same. The second count may be preset, e.g., the first count may be preset as 1, 2 or 3, etc. Exemplarily, assuming that the second count is preset as 2, for each high-priority reference region, top two ranked matching regions may be selected from theirs corresponding matching regions as the target matching regions. It may be understood that, if a count of the matching regions corresponding to a high-priority reference may be less than the second count, and all matching regions corresponding to the high-priority reference may be determined as the target reference region.

[0145] For example, as shown in FIG. **17**A, there are three reference regions **1711**, **1712**, and **1713** corresponding to a current block (not shown). The reference region **1711** corresponds to three matching regions **1721**, **1722**, and **1723**. The matching regions **1721**, **1722**, and **1723** are ranked according to cost values thereof in ascending order and the matching region **1722** corresponds to the minimum cost value among cost values of the matching regions **1721**, **1722**, and **1723**. The reference region **1712** corresponds to three matching regions **1724**, **1725**, and **1726**. The matching regions **1724**, **1725**, and **1726** are ranked according to cost values thereof in ascending order and the matching region **1724** corresponds to the minimum cost value among cost values of the matching regions **1724**, **1725**, and **1726**. The reference region **1713** corresponds to three matching regions **1727**, **1728**, and **1729**. The matching regions **1727**, **1728**, and **1729** are ranked according to cost values thereof in ascending order and the matching region **1729** corresponds to the minimum cost value among cost values of the matching regions **1727**, **1728**, and **1729**. The cost value of the matching region **1722** is less than the cost value of the matching region **1729**, and the cost value of the matching **1729** is less than the cost value of the matching region **1724**. That is, the priority of the reference region **1711** is the highest, the priority of the reference region **1713** is middle, and the priority of the reference region **1712** is the lowest. Assuming that the first count and the second count are both preset as two, the reference region **1711** and the reference region **1713** may be determined as high-priority references according to a priority order of each reference region and the first counts of the each reference region; top-ranked matching regions **1722** and **1723** may be determined as the target matching regions according to a sorting result of the matching regions corresponding to the reference region **1711** and the second count of the reference region **1711**; and top-ranked matching regions **1728** and **1729** may be determined as the target matching regions according to a sorting result of the matching regions corresponding to the reference region **1713** and the second count of the reference region **1711**.

[0146] In some embodiments, the count of the one or more matching regions selected form the matching regions corresponding to each high-priority reference region may be different. The count may be determined based on preset count rules. For example, if the preset count rules may be that "for the each high-priority reference region, three matching regions are selected as the target matching regions form the matching regions corresponding to the high priority reference region with the highest priority; and for the other high-priority reference regions, one matching region is respectively selected as the target matching region from the matching regions corresponding to the other high-priority reference regions.

[0147] Continuing from the previous example, assuming the preset count rules mentioned in the previous example are adopted and the first count is preset as 2, exemplarily, as shown in FIG. **17**B (in FIG. **17**B, a correspondence between the current block and the reference regions, a correspondence between the each reference region and the matching regions, a size relationship between the cost values of the each matching region, a size order of the optimal matching regions, and a priority relationship of the each reference region are the same as those in FIG. **17**A, which may be found in FIG. **17**A and the relevant descriptions thereof), the reference regions **1711** and **1713** may be determined as the high-priority references according to the priority order of each reference region and the first counts of the each reference region; according to the above preset count rules, since the priority of the reference region **1711** is the highest, three top-ranked matching regions of the matching regions corresponding to the reference region **1711** may be determined as the target matching regions; and one top-ranked matching region (i.e., the matching region **1729**) of the matching regions corresponding to the reference region **1713** may be determined as the target matching region.

[0148] In some embodiments, for each of the at least two reference regions, a count of the one or more target matching regions may be negatively related to the minimum cost value corresponding to the reference region. That is, the less the minimum cost value corresponding to the reference region is, the greater the count of the one or more target matching regions selected from the plurality of matching regions corresponding to the reference region may be; and the greater the minimum cost value corresponding to the reference region is, the less the count of the one or more target matching regions selected from the plurality of matching regions corresponding to the reference region may be.

[0149] In some embodiments, the at least two reference regions may correspond to different priorities. For example, the processing device **120** may rank the at least two reference regions according to the minimum cost values thereof in ascending order. The higher a reference region is ranked, the higher the priority of the reference region may be. In some embodiments, the reference regions with different priorities may correspond to different preset counts (which may be an integer greater than or equal to 0) of target matching regions. The higher the priority of the reference is, the more the preset count of target matching regions may be. For example, for a reference region with a first priority (i.e., the minimum cost value corresponding to the reference region is minimum), the count of target matching regions may be m; for a reference region with a second priority, the preset count of target matching regions may be m-1; and so on.

[0150] For example, as shown in FIG. **17**C (in FIG. **17**C, the correspondence between the current block and the reference region, the correspondence between the each reference region and the matching regions, the size relationship between the cost values of the each matching region, the size order of the optimal matching regions, and the priority relationship of the each reference region are the same as those in FIG. **17**A, which may be found in FIG. **17**A and the relevant descriptions thereof), two matching regions **1722** and **1723** corresponding to the reference region **1711** and the matching region **1729** corresponding to the reference region **1713** are determined as target matching regions.

[0151] Merely by way of example, assuming that there are three reference regions (e.g., a reference region of the first type, a reference region of the second type, and a reference region of the third type), for the reference region of the first type, the processing device **120** may determine a first plurality of matching regions corresponding to the reference region of the first type. Then the processing device **120** may determine cost values {MVlt0, MVlt1, . . . , MVltn} of the first plurality of matching regions respectively. MVlt0 may be the minimum cost value among the cost values {MVlt0, MVlt1, . . . , MVltn}. For the reference region of the second type, the processing device **120** may determine a second plurality of matching regions corresponding to the reference region of the second type. Then the processing device **120** may determine cost values {MVl0, MVl1, . . . , MVln} of the second plurality of matching regions respectively. MVl0 may be the minimum cost value among the cost values {MVl0, MVl1, . . . , MVln}. For the reference region of the third type, the processing device **120** may determine a third plurality of matching regions corresponding to the reference region of the third type. Then the processing device **120** may determine cost values {MVt0, MVt1, . . . , MVtn} of the third plurality of matching regions respectively. MVt0 may be the minimum cost value of the cost values {MVt0, MVt1, . . . , MVtn}. MVl0 may be less than MVlt0, and MVlt0 may be less than MVt0, that is, MVl0<MVlt0<MVt0. Accordingly, the priorities of the three references from high to low may be the reference region of the second type, the reference region of the first type, and the reference region of the third type. Assuming that only two types of reference regions are needed, the reference region of the second type and the reference region of the first type may be selected. A count of target matching regions corresponding to the reference region of the second type may be greater than a count of target matching regions corresponding to the reference region of the first type.

[0152] In **1630**, the processing device **120** (e.g., the candidate block determination module **420**) may determine at least two candidate blocks based on target matching regions corresponding the at least two reference regions.

[0153] In some embodiments, the determination of the at least two candidate blocks is the same as or similar to the operation **1430** in FIG. **14**.

[0154] For example, as shown in FIG. **17**A, the candidate blocks **1732**, **1733**, **1739**, and **1738** corresponding to the target matching regions **1722**, **1723**, **1729**, and **1728** may be respectively determined as the at least two candidate blocks for the current block.

[0155] As another example, as shown in FIG. **17**B, the candidate blocks **1732**, **1733**, **1731**, and **1739** corresponding

to the target matching regions **1722**, **1723**, **1721**, and **1729** may be respectively determined as the at least two candidate blocks for the current block.

[0156] As another example, as shown in FIG. **17**C, candidate blocks **1732**, **1733**, and **1739** corresponding to the target matching regions **1722**, **1723**, and **1729** respectively are designated as at least two candidate blocks of the current block.

[0157] It should be noted that the above description is merely provided for the purposes of illustration, and not intended to limit the scope of the present disclosure. For persons having ordinary skills in the art, multiple variations or modifications may be made under the teachings of the present disclosure. However, those variations and modifications do not depart from the scope of the present disclosure.

[0158] FIG. **18** is a flowchart illustrating an exemplary process for determining at least two candidate blocks according to some embodiments of the present disclosure. In some embodiments, one or more operations in the process **1400** may be implemented by the image processing system **100** illustrated in FIG. **1**. For example, one or more operations in the process **1800** may be stored in a storage device (e.g., the storage device **150**, the ROM **230**, the RAM **240**, and/or the storage **390**) as a form of instructions, and invoked and/or executed by the processing device **120** (e.g., the processor **220**, the CPU **340**, and/or one or more modules illustrated FIG. **4**). The operations of the illustrated process **1800** presented below are intended to be illustrative. In some embodiments, the process may be accomplished with one or more additional operations not described, and/or without one or more of the operations discussed. Additionally, the order in which the operations of the process as illustrated in FIG. **14** and described below is not intended to be limiting. In some embodiments, operation **520** in FIG. **5** may be achieved by operations of the process **1800**.

[0159] In **1810**, the processing device **120** (e.g., the candidate block determination module **420**) may determine, based on one or more processing modes, one or more intermediate blocks corresponding to each of the one or more processing modes among a plurality of processed blocks.

[0160] As described in connection with FIGS. **6**, **8**, and **10** and the descriptions thereof, the one or more processing modes may include the first processing mode, the second processing mode, the third processing mode, or the like, or any combination thereof. Merely by way of example, the one or more processing modes may include the first processing mode and the second processing mode. The processing device **120** may determine one or more first intermediate blocks corresponding to the first processing mode and one or more second intermediate blocks corresponding to the second processing mode.

[0161] In some embodiments, when only one processing mode is used, the intermediate block may be equivalent to the candidate block. The processing device **120** may determine at least two intermediate blocks (i.e., at least two candidate blocks) corresponding to the processing mode.

[0162] In **1820**, the processing device **120** (e.g., the candidate block determination module **420**) may determine the one or more intermediate blocks corresponding to each of the one or more processing modes as the at least two candidate blocks.

[0163] In some embodiments, the processing device **120** may designate a part or all of the intermediate block(s) corresponding to each of the one or more processing modes as the at least two candidate blocks. That is, the at least two candidate blocks may include a part or all of the intermediate blocks. For example, the processing device **120** may designate all the one or more intermediate blocks corresponding to each of the one or more processing modes as the at least two candidate blocks. As another example, the processing device **120** may rank all the one or more intermediate blocks corresponding to each of the one or more processing modes according to cost values thereof in ascending order. The processing device **120** may designate a preset count of top-ranked intermediate blocks as the at least two candidate blocks. The preset count may be a default setting of the image processing system **100** or adjustable according to different situations.

[0164] It should be noted that the above description is merely provided for the purposes of illustration, and not intended to limit the scope of the present disclosure. For persons having ordinary skills in the art, multiple variations or modifications may be made under the teachings of the present disclosure. However, those variations and modifications do not depart from the scope of the present disclosure.

[0165] FIG. **19** is a flowchart illustrating an exemplary process for determining a predicted value corresponding to a block to be processed according to some embodiments of the present disclosure. In some embodiments, one or more operations in the process **1900** may be implemented by the image processing system **100** illustrated in FIG. **1**. For example, one or more operations in the process **1900** may be stored in a storage device (e.g., the storage device **150**, the ROM **230**, the RAM **240**, and/or the storage **390**) as a form of instructions, and invoked and/or executed by the processing device **120** (e.g., the processor **220**, the CPU **340**, and/or one or more modules illustrated FIG. **4**). The operations of the illustrated process presented below are intended to be illustrative. In some embodiments, the process may be accomplished with one or more additional operations not described, and/or without one or more of the operations discussed. Additionally, the order in which the operations of the process as illustrated in FIG. **19** and described below is not intended to be limiting. In some embodiments, operation **530** in FIG. **5** may be achieved by operations of the process **1900**.

[0166] In **1910**, for each of one or more processing modes, the processing device **120** (e.g., the predicted value determination module **430**) may determine a block weight corresponding to each of one or more intermediate blocks that correspond to the processing mode.

[0167] In some embodiments, for a processing mode, the processing device **120** may determine the block weight corresponding to each of one or more intermediate blocks that correspond to the processing mode based on a difference value (e.g., a cost value, a distance) between the intermediate block and the block to be processed. For example, a block weight corresponding to an intermediate block may be negatively related to a difference value between the intermediate block and the block to be processed. That is, the greater the difference value between the intermediate block and the block to be processed is, the less the block weight corresponding to the intermediate block may be.

[0168] In **1920**, the processing device **120** (e.g., the predicted value determination module **430**) may determine a mode weight corresponding to each of the one or more processing modes.

[0169] In some embodiments, the processing device **120** may determine a mode weight corresponding to a processing mode based on block weights corresponding to the one or more intermediate blocks that correspond to the processing mode. For example, the processing device **120** may determine the mode weight corresponding to the processing mode by weighting the block weights corresponding to the one or more intermediate blocks that correspond to the processing mode.

[0170] In some embodiments, the mode weight corresponding to a processing mode may be a default setting of the image processing system **100**. For example, the mode weight corresponding to the first processing mode may be 0.5, the mode weight corresponding to the second processing mode may be 0.3, and the mode weight corresponding to the third processing mode may be 0.2. As another example, the mode weight corresponding to the first processing mode may be 0.8, the mode weight corresponding to the second processing mode may be 0.2, and the mode weight corresponding to the third processing mode may be 0.

[0171] In some embodiments, the mode weight corresponding to a processing mode may be adjustable under different situations, for example, according to actual coding needs, according to application scenarios, etc.

[0172] In **1930**, the processing device **120** (e.g., the predicted value determination module **430**) may determine a predicted value corresponding to the block to be processed by performing a weighting processing on at least two candidate blocks based on the block weights corresponding to the one or more processing modes and the one or more mode weights corresponding to the one or more processing modes.

[0173] For example, the one or more processing modes may include the first processing mode, the second processing mode, and the third processing mode. The at least two candidate blocks may include two intermediate blocks P0 and P1 corresponding to the first processing mode, two intermediate blocks P2 and P3, and two intermediate blocks P4 and P5. Block weights corresponding to the first processing mode may be 0.6 corresponding to P0 and 0.4 corresponding to P1. Block weights corresponding to the second processing mode may be 0.7 corresponding to P2 and 0.3 corresponding to P3. Block weights corresponding to the third processing mode may be 0.9 corresponding to P4 and 0.1 corresponding to P5. The mode weights corresponding to the first processing mode, the second processing mode, and the third processing mode may be 0.5, 0.3, and 0.2, respectively. Accordingly, the predicted value (denoted by P) corresponding to the block to be processing may be determined as follows: P=(P0*0.6+P1*0.4)*0.5+(P2*0.7+P3*0.3)*0.3+(P4*0.9+P5*0.1)*0.2.

[0174] It should be noted that the above description is merely provided for the purposes of illustration, and not intended to limit the scope of the present disclosure. For persons having ordinary skills in the art, multiple variations or modifications may be made under the teachings of the present disclosure. However, those variations and modifications do not depart from the scope of the present disclosure.

[0175] FIG. **20** is a flowchart illustrating an exemplary process for determining a predicted value corresponding to a block to be processed according to some embodiments of the present disclosure. In some embodiments, one or more operations in the process **2000** may be implemented by the image processing system **100** illustrated in FIG. **1**. For example, one or more operations in the process **2000** may be stored in a storage device (e.g., the storage device **150**, the ROM **230**, the RAM **240**, and/or the storage **390**) as a form of instructions, and invoked and/or executed by the processing device **120** (e.g., the processor **220**, the CPU **340**, and/or one or more modules illustrated FIG. **4**). The operations of the illustrated process presented below are intended to be illustrative. In some embodiments, the process may be accomplished with one or more additional operations not described, and/or without one or more of the operations discussed. Additionally, the order in which the operations of the process as illustrated in FIG. **20** and described below is not intended to be limiting. In some embodiments, operation **530** in FIG. **5** may be achieved by operations of the process **2000**.

[0176] In **2010**, the processing device **120** (e.g., the predicted value determination module **430**) may determine a plurality of weighting modes each of which corresponds to at least one of one or more processing modes. As used herein, a weighting mode may refer to a combination mode of one or more processing modes. If there is only one processing mode, the weighing mode can be considered as the processing mode itself.

[0177] Merely by way of example, the plurality weighting modes may include a first weighting mode, a second weighting mode, etc. The first weighting mode may be a combination of two processing modes (e.g., the first processing mode and the second processing mode, the first processing mode and the third processing mode, or the second processing mode and the third processing mode). The second weighting mode may be a combination of three processing modes (e.g., the first processing mode, the second processing mode, and the third processing mode).

[0178] In **2020**, for each of the plurality of weighting modes, the processing device **120** (e.g., the predicted value determination module **430**) may determine a block weight of each of one or more intermediate blocks that correspond to the one or more processing modes.

[0179] In some embodiments, the determination of the block weights is the same as or similar to operation **1910** in FIG. **19**.

[0180] In **2030**, for each of the plurality of weighting modes, the processing device **120** (e.g., the predicted value determination module **430**) may determine a mode weight corresponding to each of the one or more processing modes.

[0181] In some embodiments, the determination of the mode weights is the same as or similar to operation **1920** in FIG. **19**.

[0182] In **2040**, for each of the plurality of weighting modes, the processing device **120** (e.g., the predicted value determination module **430**) may determine an intermediate predicted value corresponding to a block to be processed by performing, according to the weighting mode, a weighting processing on at least two candidate blocks based on the block weights corresponding to the one or more processing modes and the one or more mode weights corresponding to the one or more processing modes.

[0183] In some embodiments, for each of the plurality of weighting modes, the processing device **120** may determine an intermediate predicted value corresponding to the block to be processed by performing a weighting processing on at least two candidate blocks corresponding to the two or more processing modes based on the block weights corresponding to two or more processing modes and the mode weights corresponding to the two or more processing modes, which is the same as or similar to the determination of the predicted value in operation **1930** in FIG. **19**.

[0184] In **2050**, the processing device **120** (e.g., the predicted value determination module **430**) may determine a predicted value corresponding to the block to be processed based on a plurality of intermediate predicted values corresponding to the plurality of weighting modes respectively.

[0185] In some embodiments, for each of the plurality of weighting modes, the processing device **120** may determine a difference value (e.g., a cost value) between the bock to be processed and the intermediate predicted value corresponding to the weighting mode. The processing device **120** may determine a minimum difference value among the difference values corresponding to the plurality of weighting modes. Then processing device **120** may determine the weighting mode corresponding to the minimum difference value as an optimal weighting mode and designate the intermediate predicted value corresponding to the optimal weighting mode as the predicted value corresponding to the block to be processed for encoding the block to be processed.

[0186] According to some embodiments of the present disclosure, by using the one or more weighting modes, the determined predicted value corresponding to the block to be processed may be closer to the true value of the block to be processed, thereby improving the image quality during encoding and decoding.

[0187] In some embodiments, the processing device **120** may determine residual information between the block to be processed and the predicted value corresponding to the block to be processed. The processing device **120** may encode the block to be processed into an encoded bitstream by encoding the residual information. A receiving end may decode the block to be processed in the encoded bitstream by encoding the residual information.

[0188] In some embodiments, as described above, since different processing modes and/or different weighting modes may be used, identification information (e.g., identifier) may be set for distinguishing the different processing modes and/or different weighting modes.

[0189] In some embodiments, a first identifier may be set for indicating that weighting modes are used. As described in connection with FIG. **20**, if the weighting modes are not compared or ranked to determine the optimal weighting mode, each of the weighting modes may correspond to the same weight. For example, there may be two weighting modes, and a weight of each of the two weighting modes may be 50%. As another example, there may be four weighting modes, and a weight of each of the four weighting modes may be 25%.

[0190] Further, also as described in connection with FIG. **20**, if the weighting modes are compared or ranked to determine the optimal weighting mode, a second identifier may be set for distinguishing the type of the optimal weighting mode that is finally used for encoding. For example, when the second identifier is 1, the second identifier may indicate that the optimal weighting mode corresponds to a combination of the first processing mode with a weight of 75% and the second processing mode with a weight of 25%. When the second identifier is 2, the second identifier may indicate that the optimal weighting mode corresponds a combination of the first processing mode with a weight of 80% and the second processing mode with a weight of 20%. When the second identifier is 3, the second identifier may indicate that the optimal weighting mode corresponds to a combination of the first processing mode with a weight of 30%, the second processing mode with a weight of 30%, and the third processing mode with a weight of 40%.

[0191] In some embodiments, the processing device **120** may encode the block to be processed based on the predicted value corresponding to the block to be processed and the identification information to obtain an encoded bitstream. For example, when a specific weighting mode is determined for prediction, the processing device **120** may encode the predicted value determined using the specific weighting mode and the identification information of the specific weighting mode to the encoded bitstream of the block to be processed, such that the receiving end can distinguish that the current block is encoded based on the specific weighting mode.

[0192] In some embodiments, during the encoding process, a block-level syntax identifier may be set. For example, the syntax identifier of intraTMP_weight_mode may be used. The intraTMP_weight_mode of 0 may indicate that an existing intraTMP is used (e.g., the current block is predicted using coded pixels on the left side and the upper side of the current block to obtain a single candidate block), and intraTMP_weight_mode of 1 may indicate that a weighing mode in the present disclosure is used. As another example, for the weighting modes in the present disclosure, the syntax identifier of intraTMP_weigh_sub may be used. Merely by way of example, the intraTMP_weigh_sub of 0 (i.e., intraTMP_weigh_sub=0) may represent the first processing mode. The intraTMP_weigh_sub of 1 (i.e., intraTMP_weigh_sub=1) may represent the second processing mode.

[0193] In some embodiments, during the decoding process, the receiving end may obtain the encoded bitstream that is determined as described above. The receiving end may determine at least two candidate blocks corresponding to the current block based on the encoded bitstream. For example, the processing device **120** may determine the specific weighting mode that is used to predict the current block. The receiving end may use the specific weighting mode to determine the at least two candidate blocks corresponding to the current block, operations of which may be similar to the encoding process as described elsewhere in the present disclosure. The receiving end may allocate block weights for the at least two candidate blocks according to a difference value between each of the at least two candidate blocks and the current block, which is similar to the determination of the block weights during the encoding process. The receiving end may determine the predicted value corresponding to the current block based on the block weights of the at least two candidate blocks, which is similar to the determination of the predicted value during the encoding process. Further, the receiving end may obtain the current block based on the encoded bitstream and the predicted value corresponding to the current block. For example, the

receiving end may obtain the current block based on the predicted value and residual information in the encoded bitstream.

[0194] It should be noted that the above description is merely provided for the purposes of illustration, and not intended to limit the scope of the present disclosure. For persons having ordinary skills in the art, multiple variations or modifications may be made under the teachings of the present disclosure. However, those variations and modifications do not depart from the scope of the present disclosure.

[0195] In some embodiments, after the predicted value corresponding to the current block is determined, the processing device **120** may adaptively adjust reference region(s) of a next block to be processed according to feedback of the predicted value corresponding to the current block. For example, the processing device **120** may adjust the sizes and/or counts of the reference region(s) of the next block to be processed based on a difference between a cost value corresponding to the predicted value of the current block and a cost value threshold according to preset adjustment rule. In some embodiments, after the predicted value corresponding to the current block is determined, the processing device **120** may determine a similarity between the next block to be processed and the current block (and/or one or more encoded blocks before the next block). In response to determining that the similarity is less than or equal to a preset threshold, the processing device **120** may use the optimal weighting mode corresponding to the current block (or the one or more encoded blocks before the next block) to determine a predicted value corresponding to the next block to be processed. In response to determining that the similarity is greater than the preset threshold, the processing device **120** may determine the optimal weighting mode corresponding to the next block to be processed according to operations in FIG. **20**. In such cases, the computing amount during intra prediction can be reduced.

[0196] Having thus described the basic concepts, it may be rather apparent to those skilled in the art after reading this detailed disclosure that the foregoing detailed disclosure is intended to be presented by way of example only and is not limiting. Various alterations, improvements, and modifications may occur and are intended to those skilled in the art, though not expressly stated herein. These alterations, improvements, and modifications are intended to be suggested by the present disclosure, and are within the spirit and scope of the exemplary embodiments of the present disclosure.

[0197] Moreover, certain terminology has been used to describe embodiments of the present disclosure. For example, the terms "one embodiment", "an embodiment" and/or "some embodiments" mean that a particular feature, structure or characteristic described in connection with the embodiment is included in at least one embodiment of the present disclosure. Therefore, it is emphasized and should be appreciated that two or more references to "an embodiment", "one embodiment" or "an alternative embodiment" in various portions of this specification are not necessarily all referring to the same embodiment. Furthermore, the particular features, structures or characteristics may be combined as suitable in one or more embodiments of the present disclosure.

[0198] Further, it will be appreciated by one skilled in the art, aspects of the present disclosure may be illustrated and described herein in any of a number of patentable classes or context including any new and useful process, machine, manufacture, or composition of matter, or any new and useful improvement thereof. Accordingly, aspects of the present disclosure may be implemented entirely hardware, entirely software (including firmware, resident software, micro-code, etc.) or combining software and hardware implementation that may all generally be referred to herein as a "block", "module", "engine", "unit", "component" or "system". Furthermore, aspects of the present disclosure may take the form of a computer program product embodied in one or more computer-readable media having computer-readable program code embodied thereon.

[0199] A computer-readable signal medium may include a propagated data signal with computer readable program code embodied therein, for example, in baseband or as part of a carrier wave. Such a propagated signal may take any of a variety of forms, including electro-magnetic, optical, or the like, or any suitable combination thereof. A computer-readable signal medium may be any computer-readable medium that is not a computer-readable storage medium and that may communicate, propagate, or transport a program for use by or in connection with an instruction execution system, apparatus, or device. Program code embodied on a computer-readable signal medium may be transmitted using any appropriate medium, including wireless, wireline, optical fiber cable, RF, or the like, or any suitable combination of the foregoing.

[0200] Computer program code for carrying out operations for aspects of the present disclosure may be written in any combination of one or more programming languages, including an object-oriented programming language such as Java, Scala, Smalltalk, Eiffel, JADE, Emerald, C ++, C #, VB.NET, Python or the like, conventional procedural programming languages, such as the "C" programming language, Visual Basic, Fortran 1703, Perl, COBOL 1702, PHP, ABAP, dynamic programming languages such as Python, Ruby and Groovy, or other programming languages. The program code may execute entirely on the user's computer, partly on the user's computer, as a stand-alone software package, partly on the user's computer and partly on a remote computer or entirely on the remote computer or server. In the latter scenario, the remote computer may be connected to the user's computer through any type of network, including a local area network (LAN) or a wide area network (WAN), or the connection may be made to an external computer (for example, through the Internet using an Internet Service Provider) or in a cloud computing environment or offered as a service such as a software as a service (SaaS).

[0201] Furthermore, the recited order of processing elements or sequences, or the use of numbers, letters, or other designations therefore, is not intended to limit the claimed processes and methods to any order except as may be specified in the claims. Although the above disclosure discusses through various examples what is currently considered to be a variety of useful embodiments of the disclosure, it is to be understood that such detail is solely for that purpose, and that the appended claims are not limited to the disclosed embodiments, but, on the contrary, are intended to cover modifications and equivalent arrangements that are within the spirit and scope of the disclosed embodiments. For example, although the implementation of various components described above may be embodied in a hardware

device, it may also be implemented as a software-only solution—e.g., an installation on an existing server or mobile device.

[0202] Similarly, it should be appreciated that in the foregoing description of embodiments of the present disclosure, various features are sometimes grouped together in a single embodiment, figure, or description thereof for the purpose of streamlining the disclosure aiding in the understanding of one or more of the various embodiments. This method of disclosure, however, is not to be interpreted as reflecting an intention that the claimed subject matter requires more features than are expressly recited in each claim. Rather, claimed subject matter may lie in less than all features of a single foregoing disclosed embodiment.

What is claimed is:

1. A system for image processing, comprising:

at least one storage device including a set of instructions; and

at least one processor in communication with the at least one storage device, wherein when executing the set of instructions, the at least one processor is directed to cause the system to perform operations including:

obtaining an image including a plurality of processed blocks and at least one block to be processed;

for a block to be processed among the at least one block to be processed, determining at least two candidate blocks among the plurality of processed blocks; and

determining a predicted value corresponding to the block to be processed based on the at least two candidate blocks.

2. The system of claim **1**, wherein the determining at least two candidate blocks among the plurality of processed blocks includes:

determining a reference region of the block to be processed;

determining a plurality of matching regions based on the reference region, each of the plurality of matching regions corresponding to a respective one processed block; and

determining the respective processed blocks corresponding to the plurality of matching regions as the at least two candidate blocks.

3. The system of claim **1**, wherein the determining at least two candidate blocks among the plurality of processed blocks includes:

determining, from the plurality of processed blocks, multiple processed blocks that are within a preset distance from the block to be processed;

ranking the multiple processed blocks based on cost values of the multiple processed blocks and/or distances of the multiple processed blocks; and

determining the at least two candidate blocks based on the ranking result.

4. The system of claim **1**, wherein the determining at least two candidate blocks among the plurality of processed blocks includes:

determining at least two reference regions of the block to be processed;

for each of the at least two reference regions, determining a plurality of matching regions corresponding to the reference region, each of the plurality of matching regions corresponding to a respective one processed block; and

determining the at least two candidate blocks based on matching regions corresponding to the at least two reference regions.

5. The system of claim **4**, wherein the at least two reference regions include at least two of a left region of the block to be processed, an upper region of the block to be processed, or a left-upper region of the block to be processed.

6. The system of claim **4**, wherein sizes of the at least two reference regions, positions of the at least two reference regions, and/or a count of the at least two reference regions are adjusted adaptively.

7. The system of claim **4**, wherein the determining the at least two candidate blocks based on matching regions corresponding to the at least two reference regions includes:

ranking the matching regions corresponding to the at least two reference regions based on cost values of the matching regions corresponding to the at least two reference regions; and

determining the at least two candidate blocks based on the ranking result.

8. The system of claim **4**, wherein the determining the at least two candidate blocks based on matching regions corresponding to the at least two reference regions includes:

for each of the at least two reference regions,

ranking the plurality of matching regions corresponding to the reference region based on cost values of the plurality of matching regions; and

determining, based on the ranking result, at least one target matching region from the plurality of matching regions; and

determining the at least two candidate blocks based on target matching regions corresponding to the at least two reference regions.

9. The system of claim **4**, wherein the determining the at least two candidate blocks based on matching regions corresponding to the at least two reference regions includes:

for each of the at least two reference regions,

determining a minimum cost value among cost values of the plurality of matching regions corresponding to the reference region;

selecting one or more target matching regions from the plurality of machining regions corresponding to the reference region, wherein a count of target matching regions selected form each of the reference regions are same or different; and

determining the at least two candidate blocks based on target matching regions corresponding to the at least two reference regions.

10. The system of claim **1**, wherein the determining at least two candidate blocks among the plurality of processed blocks includes:

determining, based on one or more processing modes, one or more intermediate blocks corresponding to each of the one or more processing modes among the plurality of processed blocks; and

determining the one or more intermediate blocks corresponding to each of the one or more processing modes as the at least two candidate blocks.

11. The system of claim **10**, wherein the determining a predicted value corresponding to the block to be processed based on the at least two candidate blocks includes:

for each of the one or more processing modes,

determining a block weight corresponding to each of the one or more intermediate blocks that correspond to the processing mode; and

determining a mode weight corresponding to the processing mode; and

determining the predicted value corresponding to the block to be processed by performing a weighting processing on the at least two candidate blocks based on the block weights corresponding to the one or more processing modes and the one or more mode weights corresponding to the one or more processing modes.

12. The system of claim **10**, wherein the determining a predicted value corresponding to the block to be processed based on the at least two candidate blocks includes:

determining a plurality of weighting modes each of which corresponds to at least one of the one or more processing modes;

for each of the plurality of weighting modes,

determining a block weight of each of the one or more intermediate blocks that correspond to the one or more processing modes;

determining a mode weight corresponding to each of the one or more processing modes;

determining an intermediate predicted value corresponding to the block to be processed by performing, according to the weighting mode, a weighting processing on the at least two candidate blocks based on the block weights corresponding to the one or more processing modes and the one or more mode weights corresponding to the one or more processing modes; and

determining the predicted value corresponding to the block to be processed based on a plurality of intermediate predicted values corresponding to the plurality of weighting modes respectively.

13. A method for image processing, implemented on a computing device including at least one storage device and at least one processor, the method including:

obtaining an image including a plurality of processed blocks and at least one block to be processed;

for a block to be processed among the at least one block to be processed, determining at least two candidate blocks among the plurality of processed blocks; and

determining a predicted value corresponding to the block to be processed based on the at least two candidate blocks.

14. The method of claim **13**, wherein the determining at least two candidate blocks among the plurality of processed blocks includes:

determining a reference region of the block to be processed;

determining a plurality of matching regions based on the reference region, each of the plurality of matching regions corresponding to a respective one processed block; and

determining the respective processed blocks corresponding to the plurality of matching regions as the at least two candidate blocks.

15. The method of claim **13**, wherein the determining at least two candidate blocks among the plurality of processed blocks includes:

determining, from the plurality of processed blocks, multiple processed blocks that are within a preset distance from the block to be processed;

ranking the multiple processed blocks based on cost values of the multiple processed blocks and/or distances of the multiple processed blocks; and

determining the at least two candidate blocks based on the ranking result.

16. The method of claim **13**, wherein the determining at least two candidate blocks among the plurality of processed blocks includes:

determining at least two reference regions of the block to be processed;

for each of the at least two reference regions, determining a plurality of matching regions corresponding to the reference region, each of the plurality of matching regions corresponding to a respective one processed block; and

determining the at least two candidate blocks based on matching regions corresponding to the at least two reference regions.

17. The method of claim **16**, wherein sizes of the at least two reference regions, positions of the at least two reference regions, and/or a count of the at least two reference regions are adjusted adaptively.

18. The method of claim **16**, wherein the determining the at least two candidate blocks based on matching regions corresponding to the at least two reference regions includes:

ranking the matching regions corresponding to the at least two reference regions based on cost values of the matching regions corresponding to the at least two reference regions; and

determining the at least two candidate blocks based on the ranking result.

19. The method of claim **16**, wherein the determining the at least two candidate blocks based on matching regions corresponding to the at least two reference regions includes:

for each of the at least two reference regions,

determining a minimum cost value among cost values of the plurality of matching regions corresponding to the reference region;

selecting one or more target matching regions from the plurality of machining regions corresponding to the reference region, wherein a count of the one or more target matching regions is negatively related to the minimum cost value corresponding to the reference region, wherein a count of target matching regions selected form each of the reference regions are same or different; and

determining the at least two candidate blocks based on target matching regions corresponding to the at least two reference regions.

20. A non-transitory computer readable medium, comprising executable instructions that, when executed by at least one processor, direct the at least one processor to perform a method, the method comprising:

obtaining an image including a plurality of processed blocks and at least one block to be processed;

for a block to be processed among the at least one block to be processed, determining at least two candidate blocks among the plurality of processed blocks; and

determining a predicted value corresponding to the block to be processed based on the at least two candidate blocks.

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