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Hirano et al.

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(54) **ARMATURE AND ELECTRIC MOTOR**

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H02K 3/52 (2006.01)

H02K 41/03 (2006.01)

(52) **U.S. Cl.**

CPC **H02K 3/28** (2013.01); **H02K 3/18** (2013.01); **H02K 3/522** (2013.01); **H02K 41/031** (2013.01); **H02K 2203/12** (2013.01)

(58) **Field of Classification Search**

CPC .. H02K 3/04; H02K 3/12; H02K 3/18; H02K 3/28; H02K 3/52-522

USPC 310/12.21, 12.22, 184, 198, 208
See application file for complete search history.

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Primary Examiner — Oluseye Iwarere

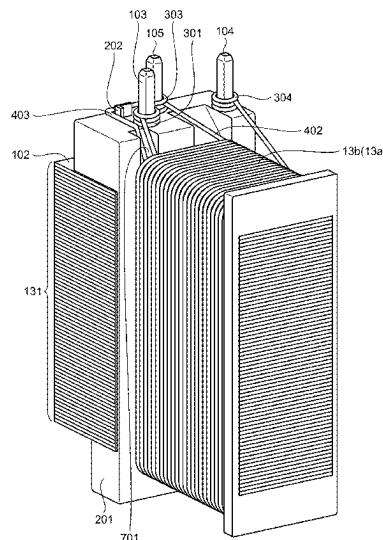
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(57) **ABSTRACT**

A movable element that is an armature includes teeth including iron cores, an insulating holding member, and winding portions in which a coil is formed by winding an electric wire around the iron cores on the insulating holding member, the teeth include the teeth that are first teeth including the winding portions for only a coil of a single phase and the tooth that is a second tooth including the winding portions for coils of two phases different from each other, and a single electric wire forms the winding portions in the tooth that is the second tooth and is continuously wound via an intermediate fixing member provided on the insulating holding member.

12 Claims, 17 Drawing Sheets



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FIG.1

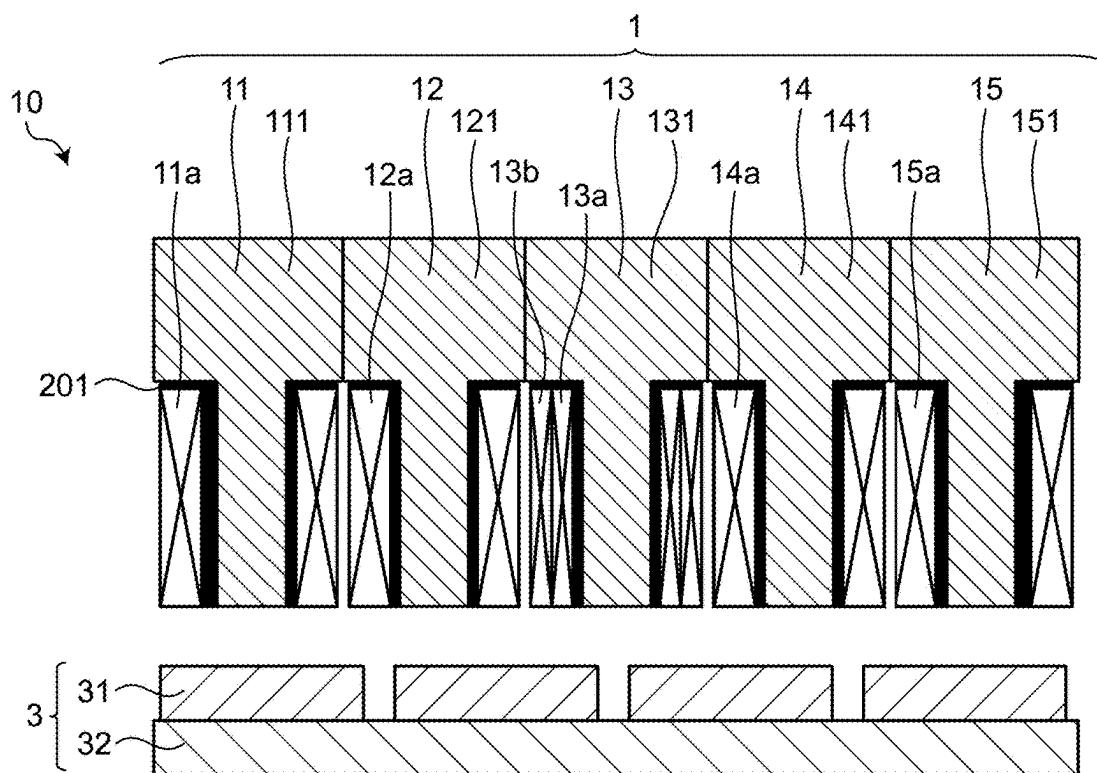


FIG.2

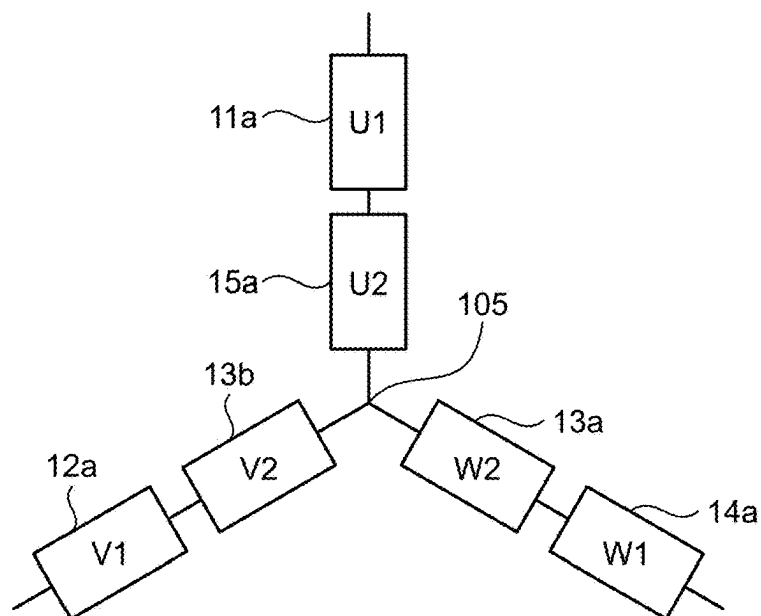


FIG.3

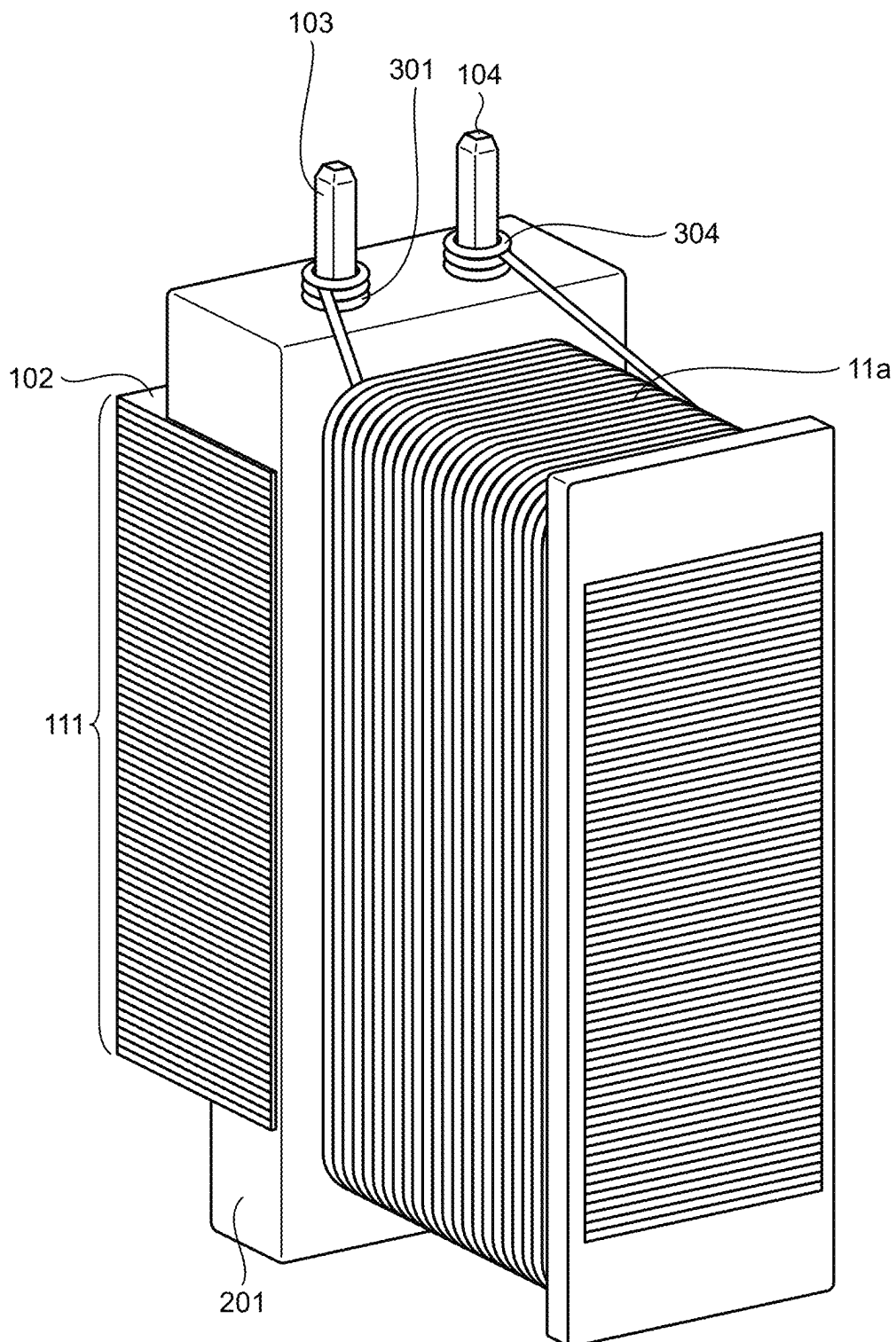


FIG. 4

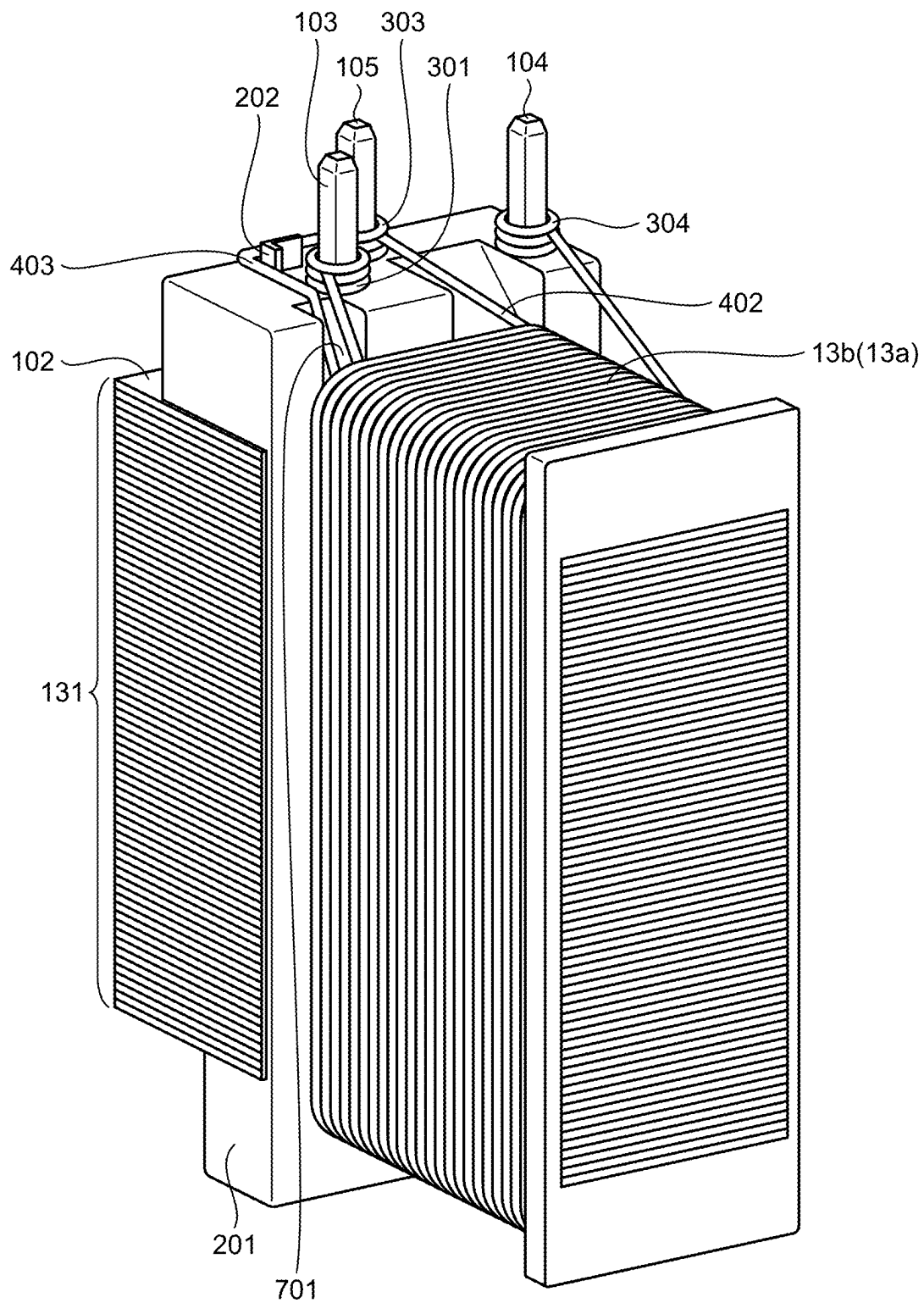


FIG. 5

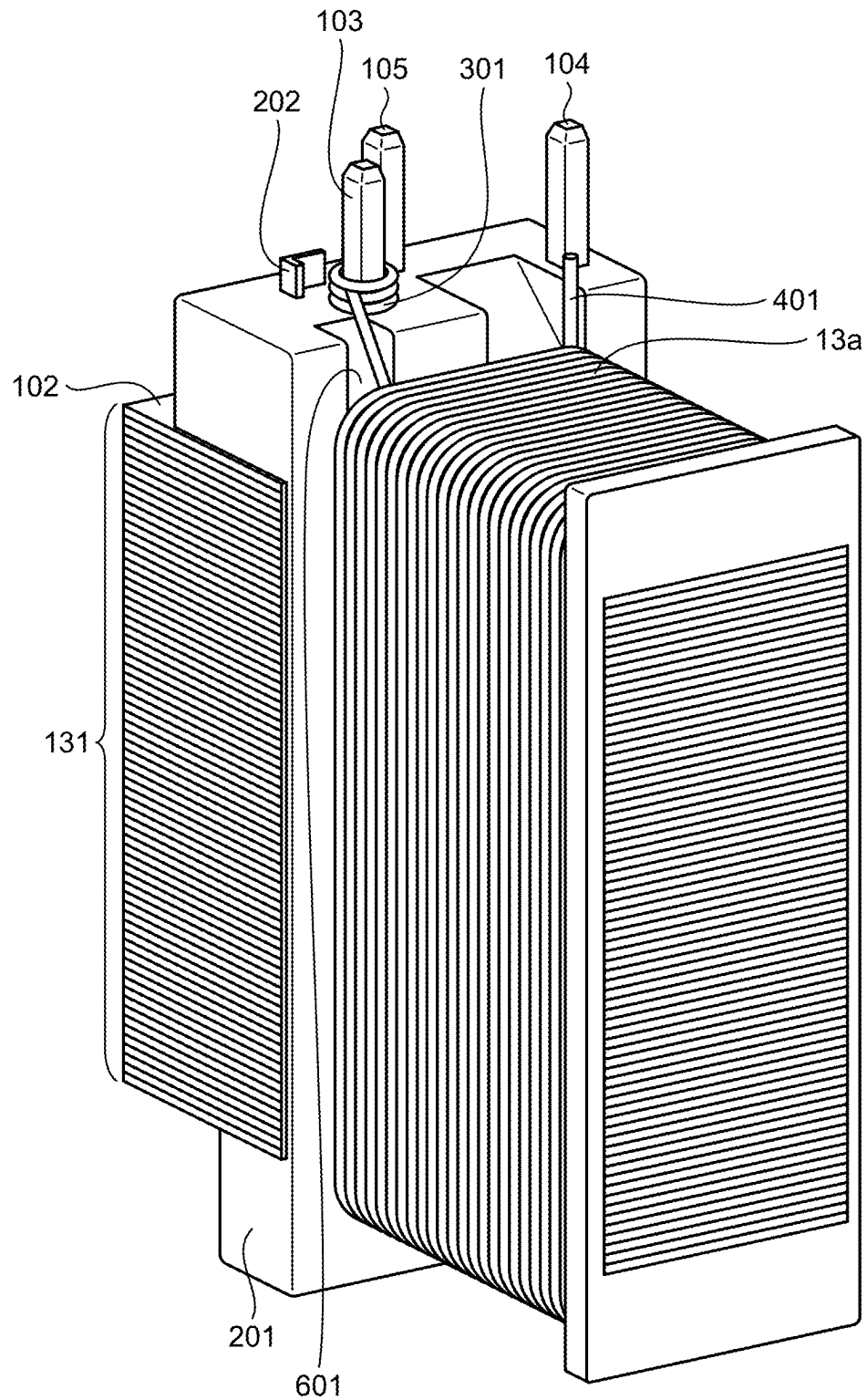


FIG.6

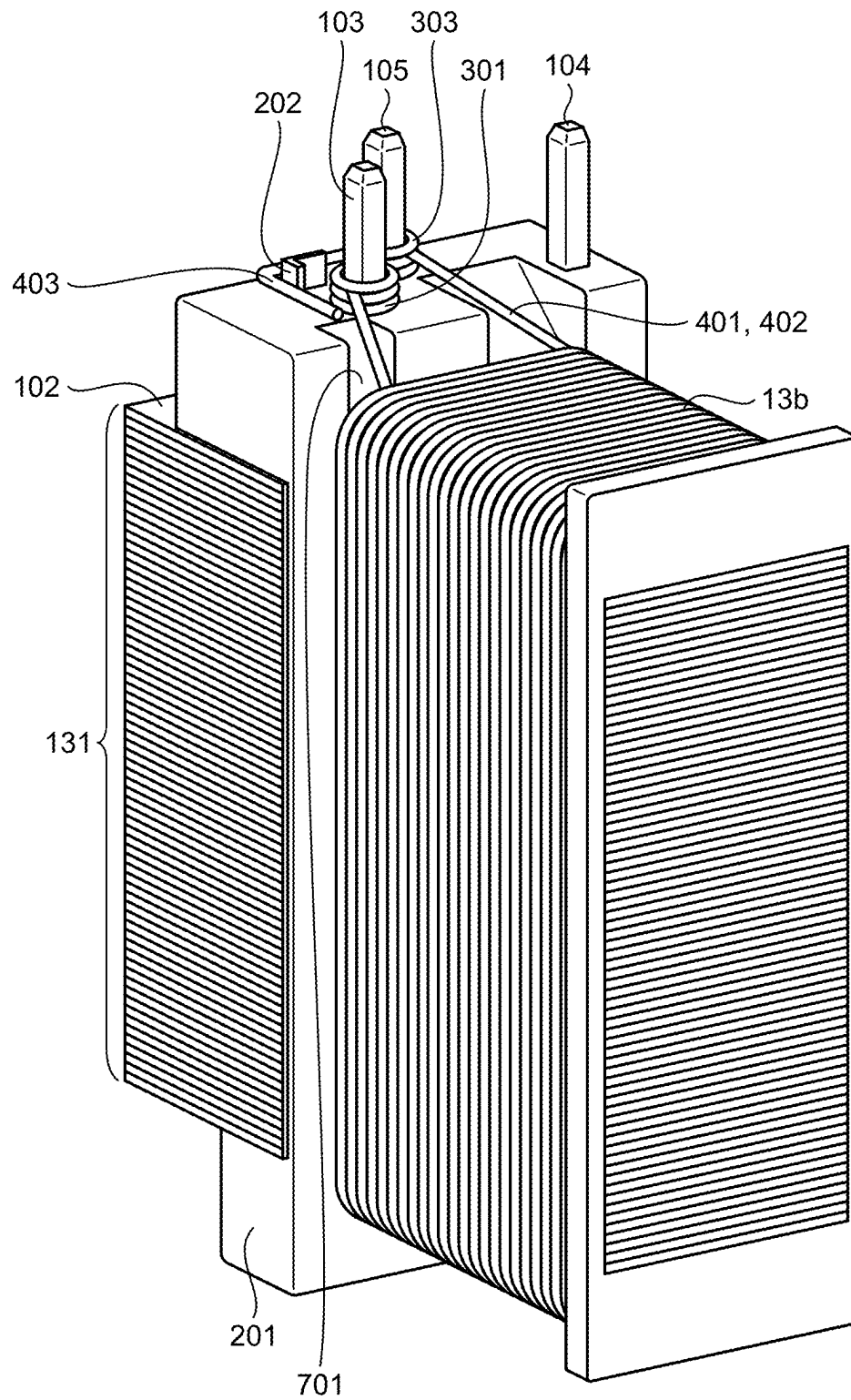


FIG.7

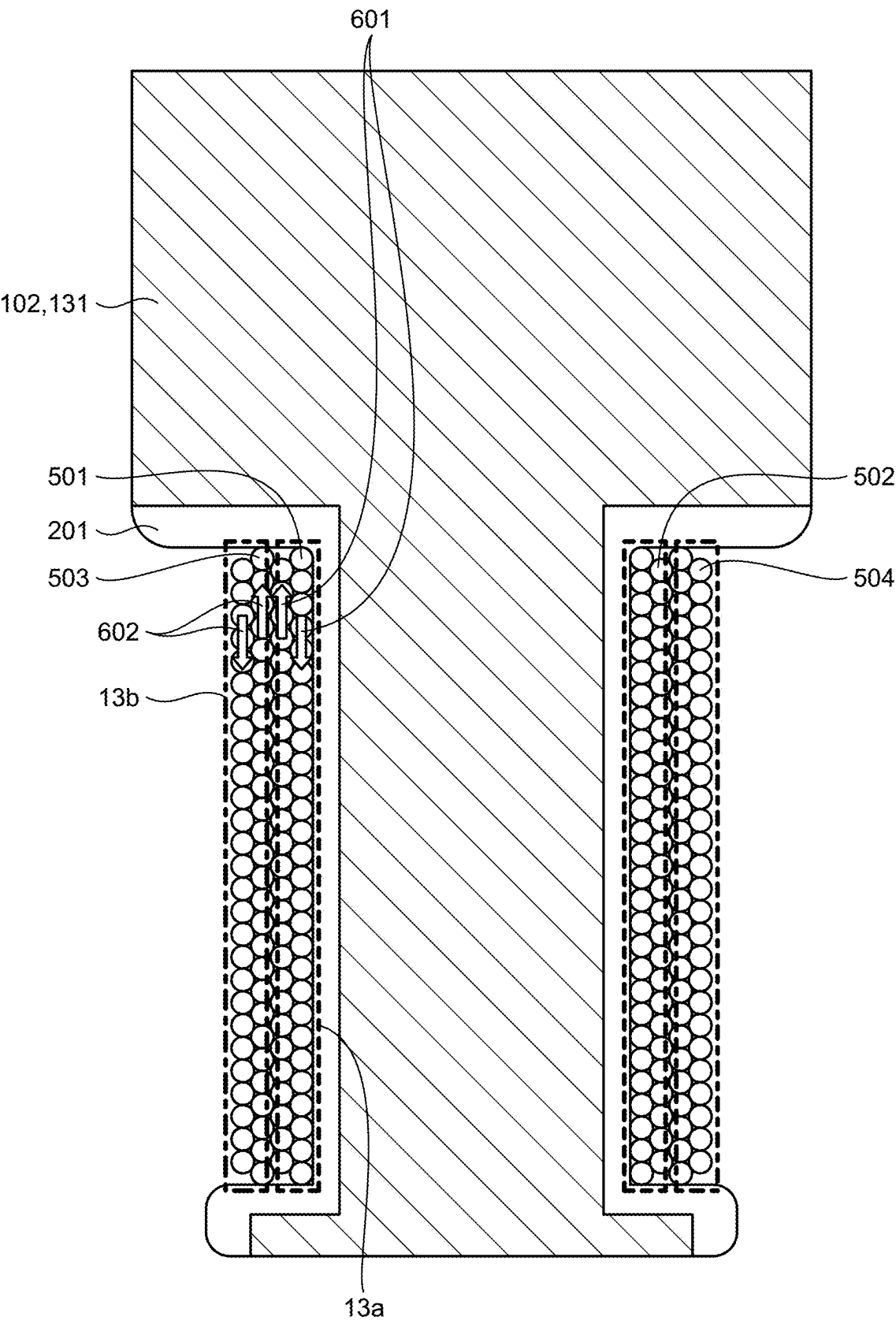


FIG.8

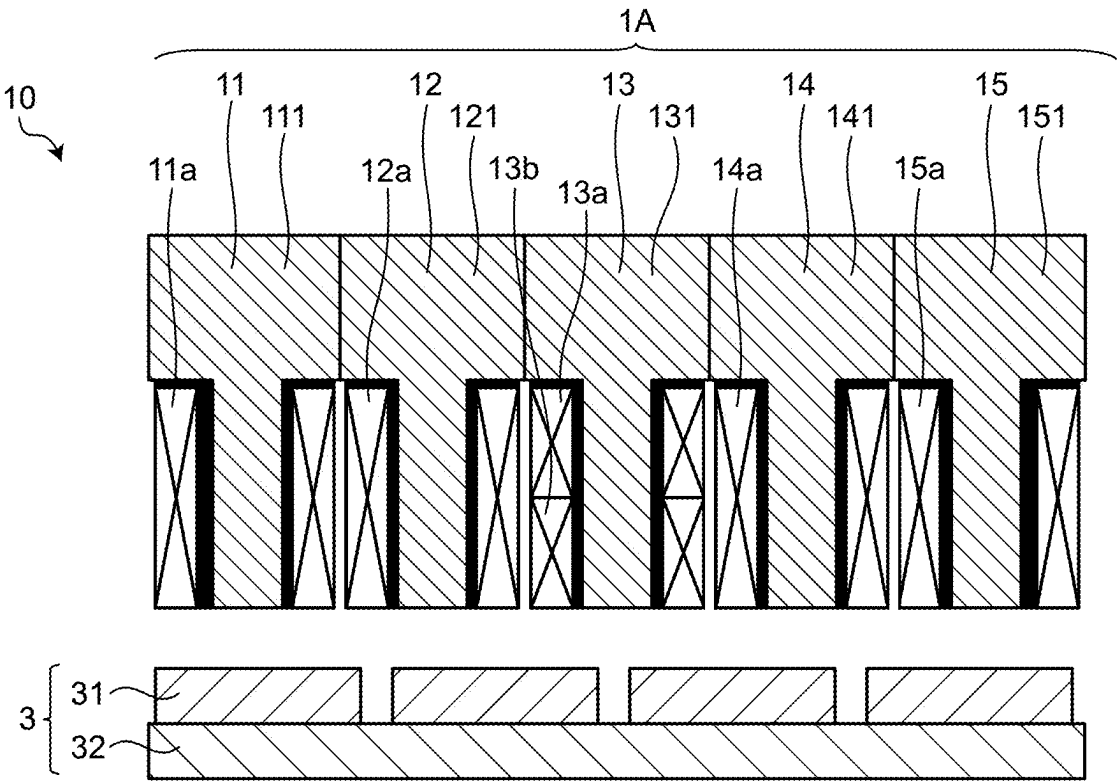


FIG. 9

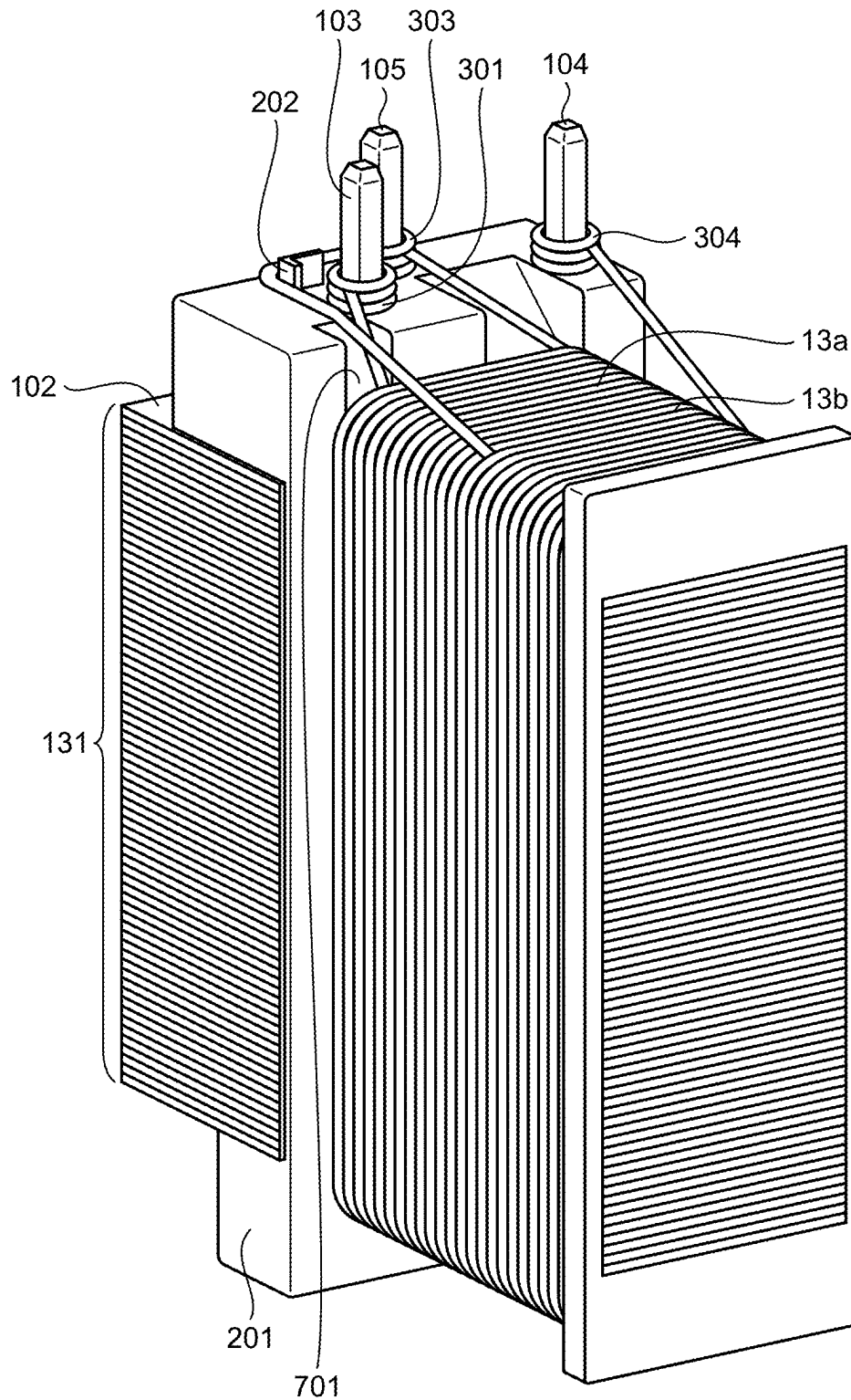


FIG. 10

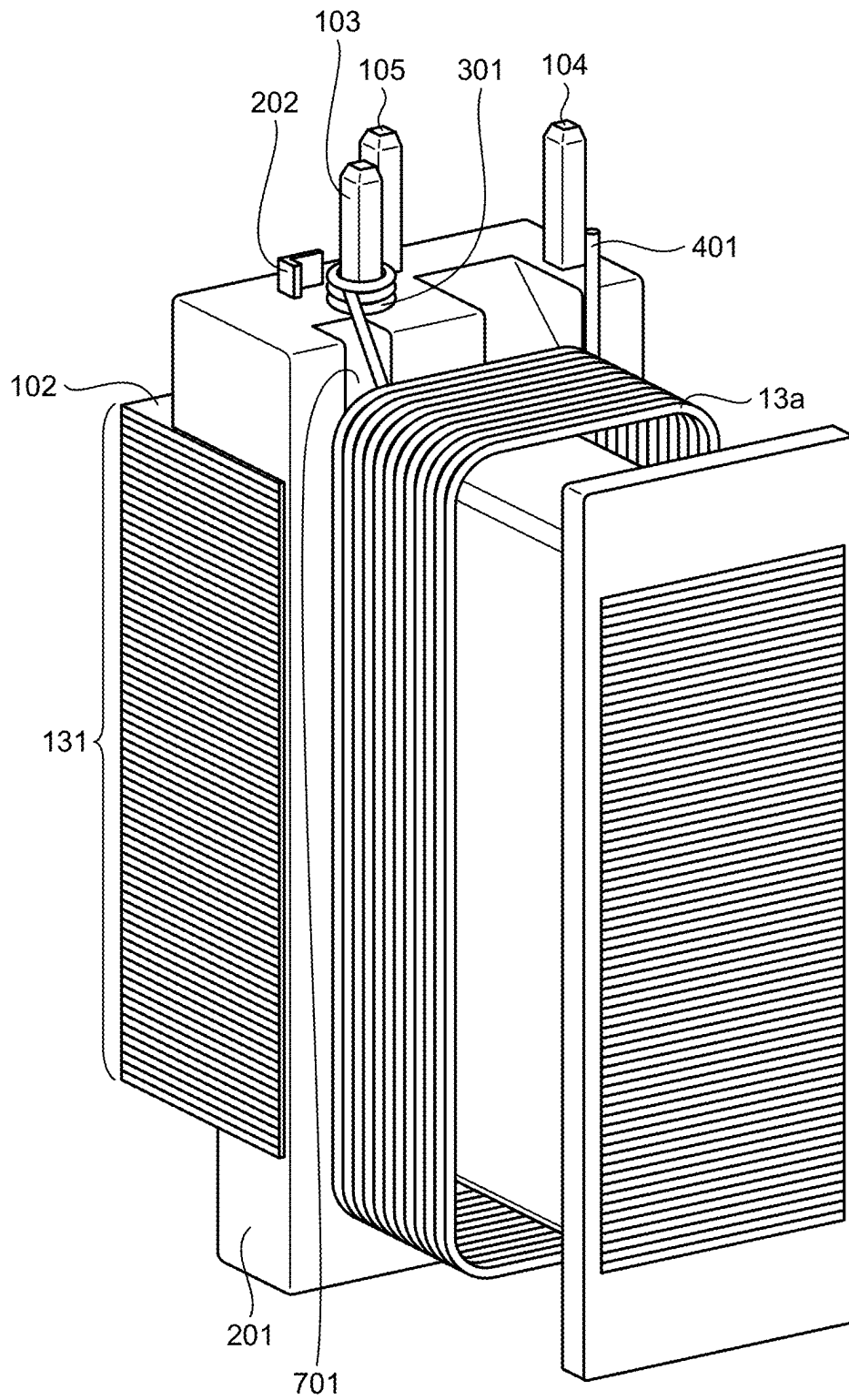


FIG. 11

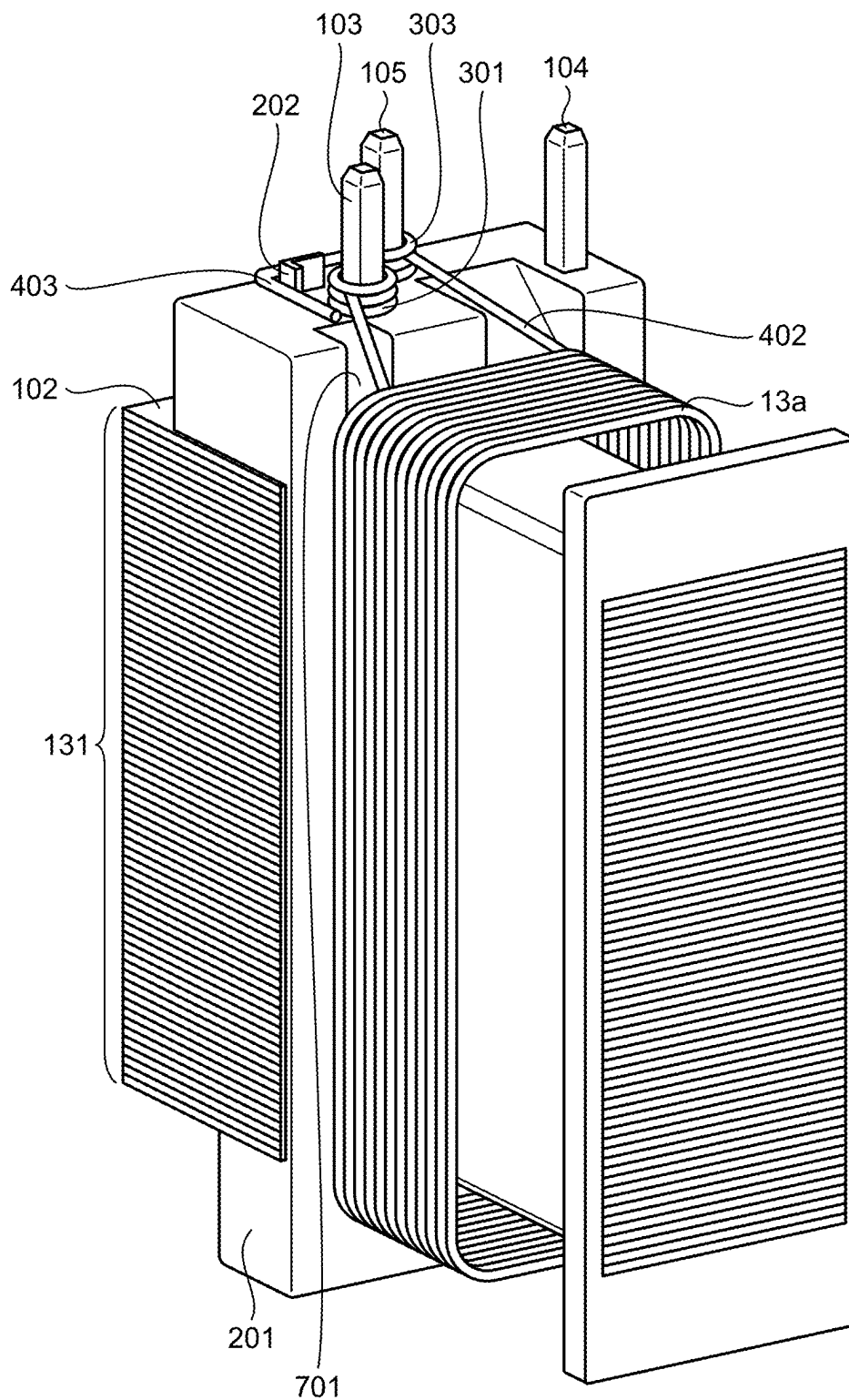


FIG.12

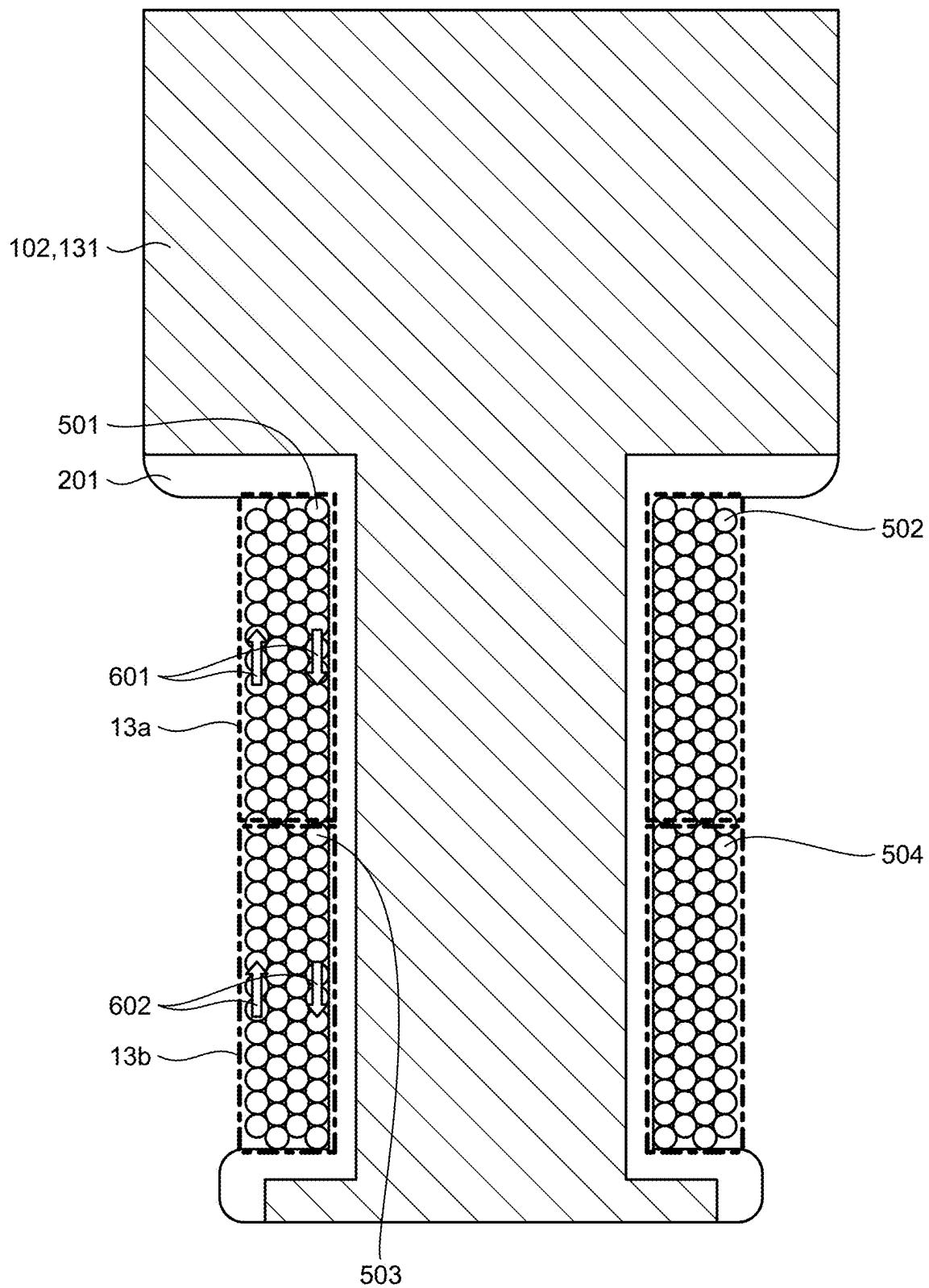


FIG.13

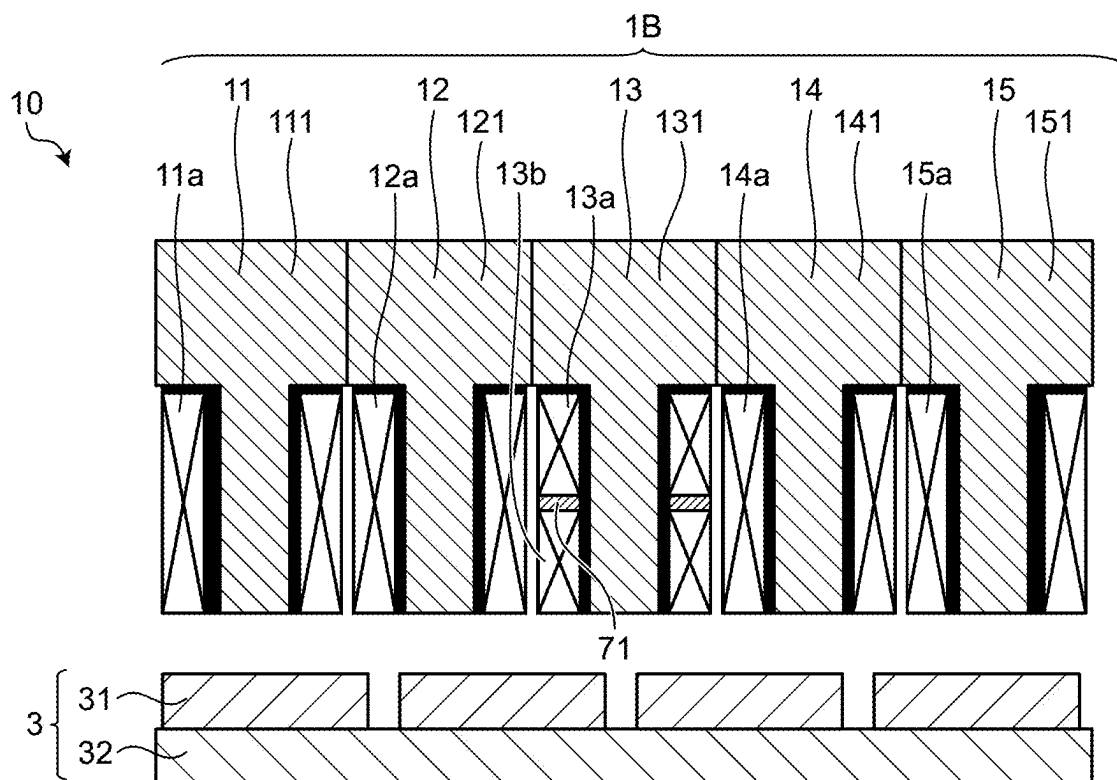


FIG. 14

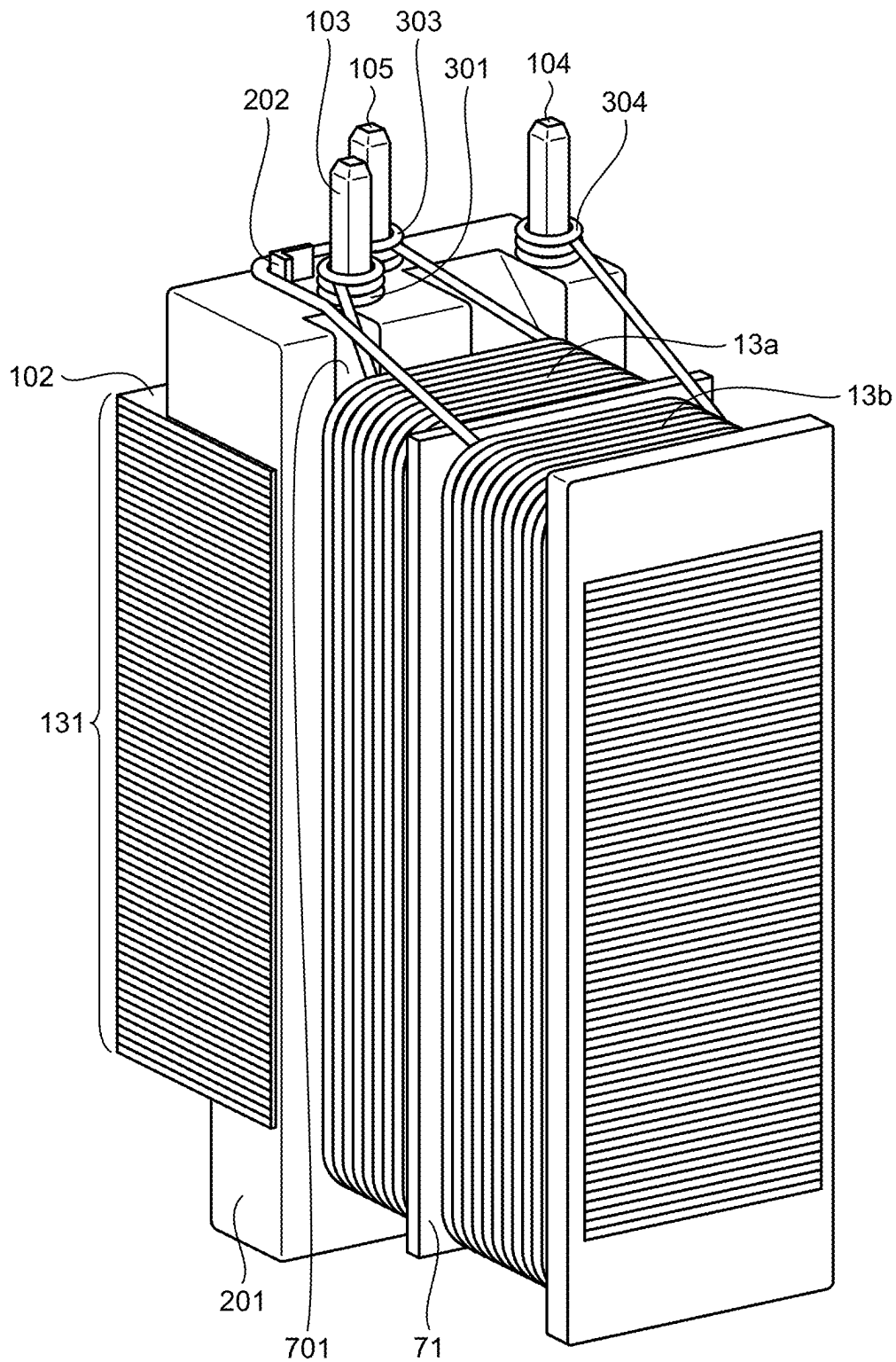


FIG. 15

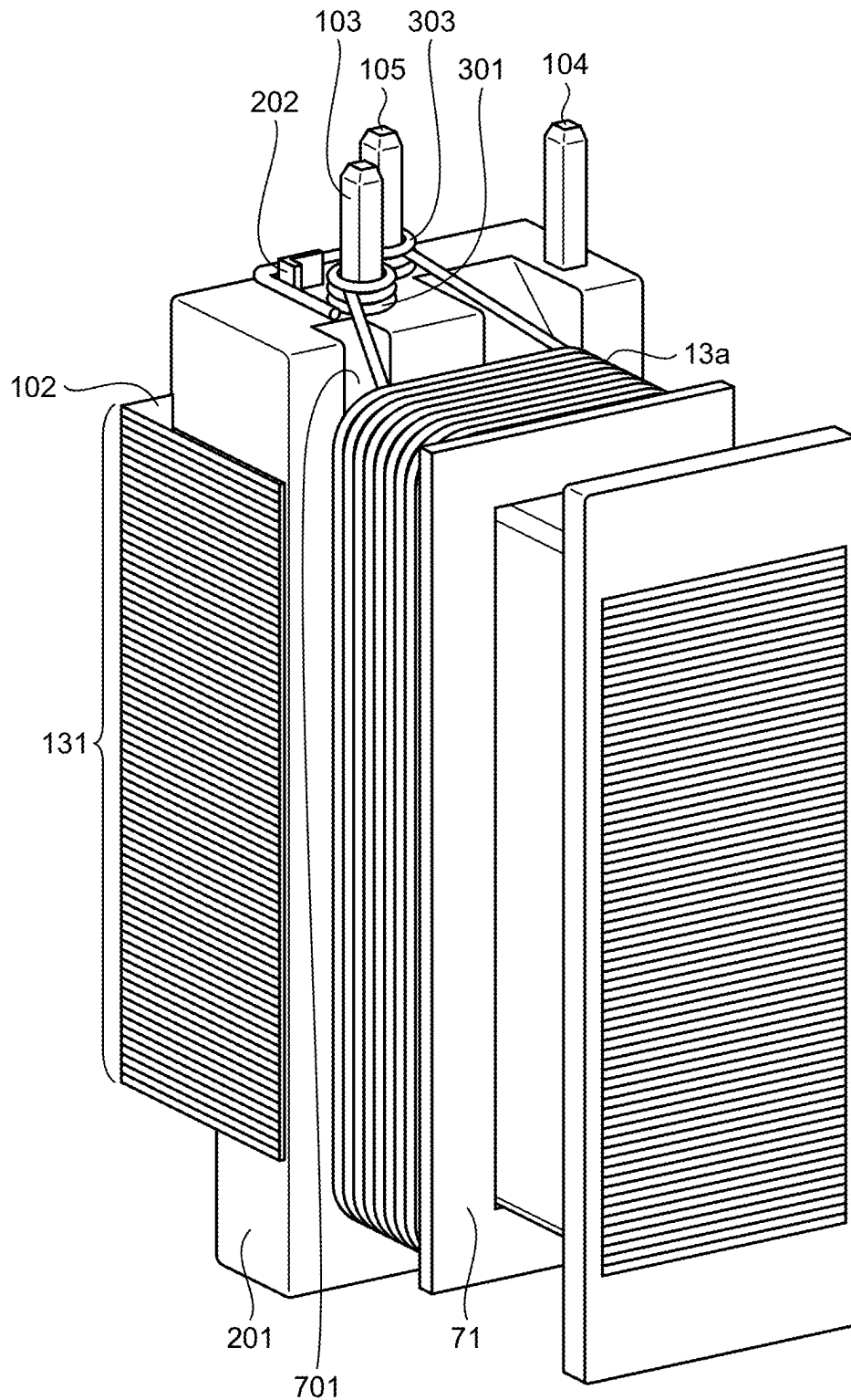


FIG.16

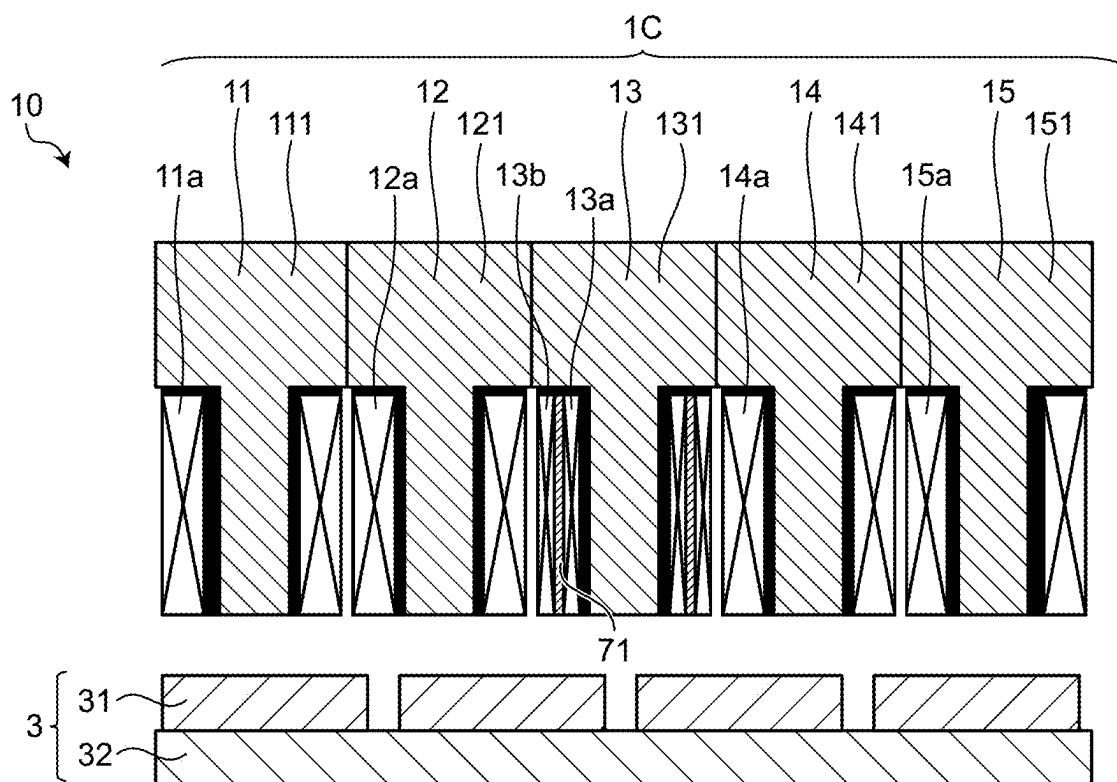


FIG.17

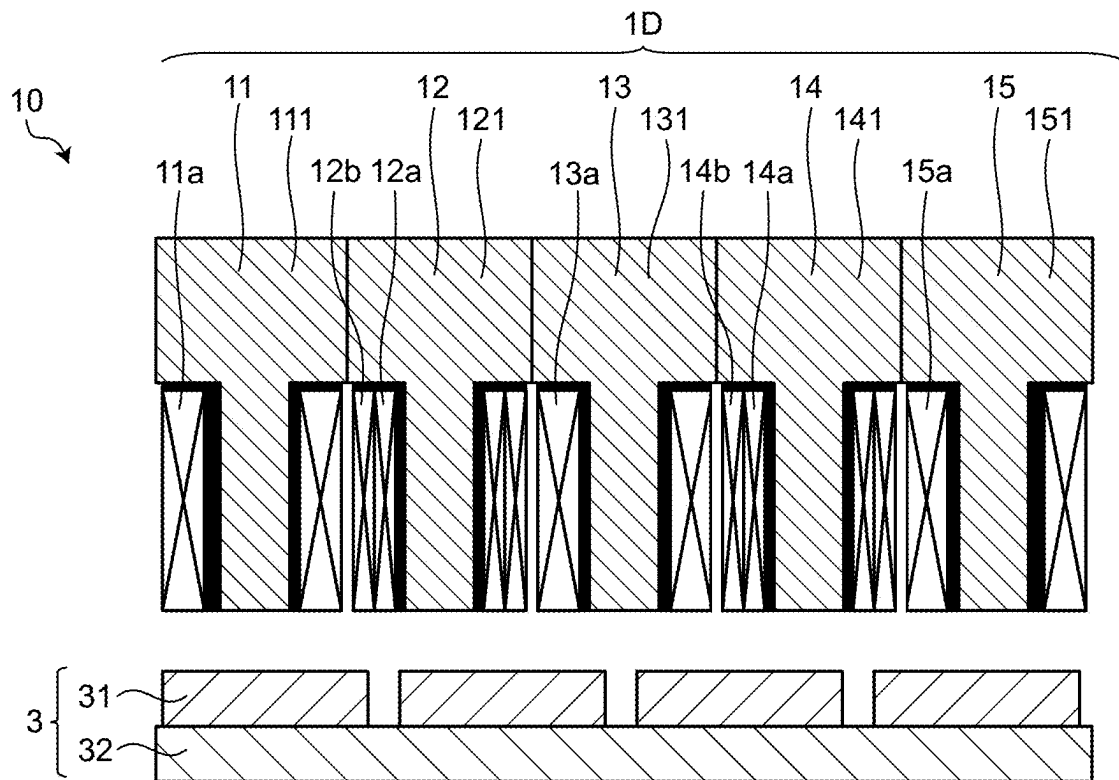


FIG.18

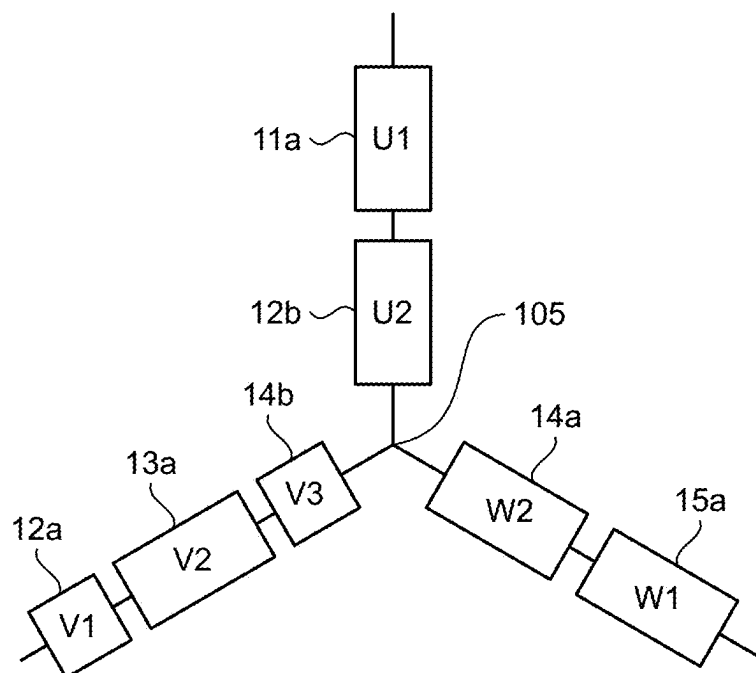
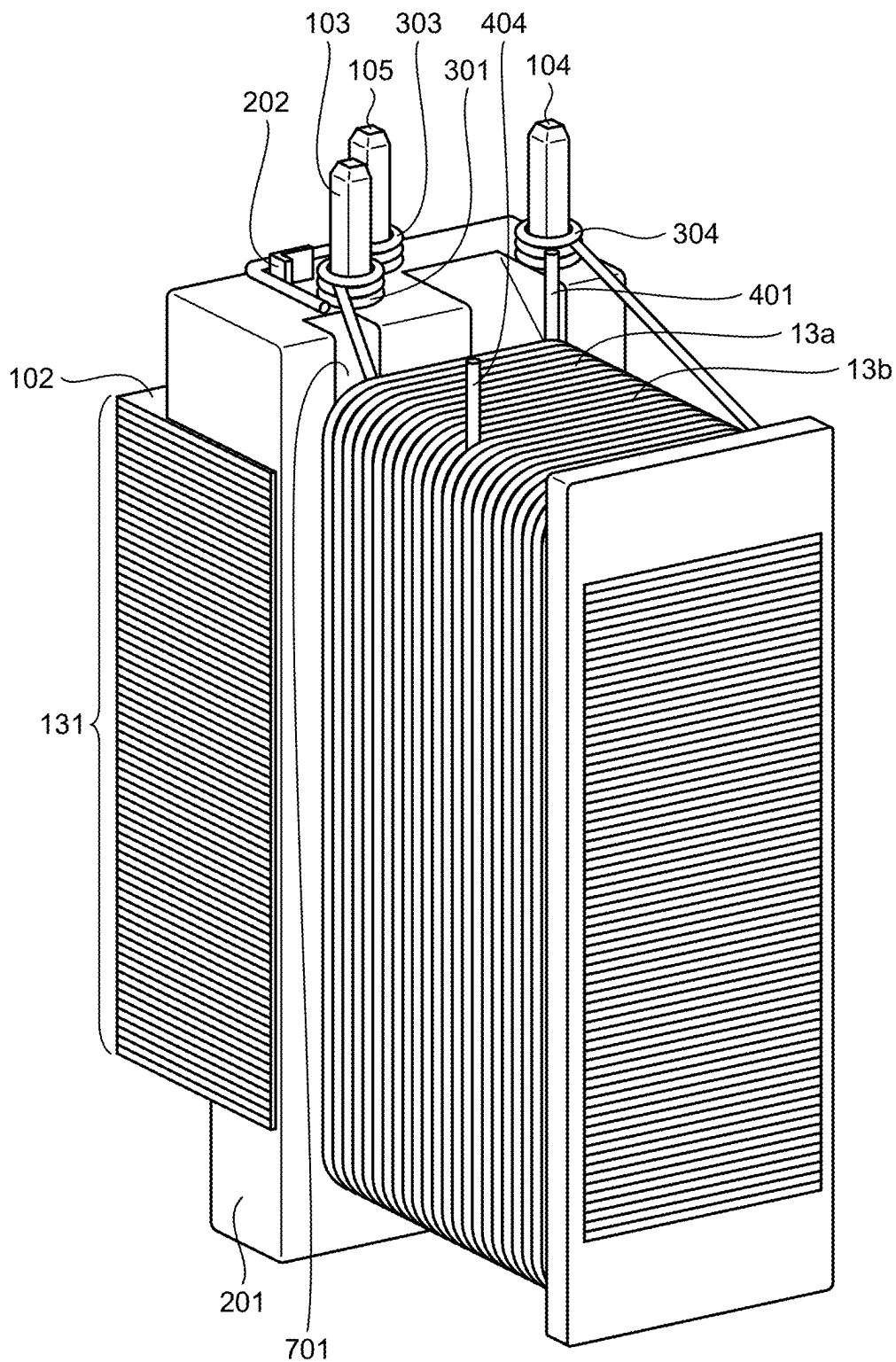


FIG. 19



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ARMATURE AND ELECTRIC MOTOR**CROSS-REFERENCE TO RELATED APPLICATION**

This application is a national stage application, pursuant to 35 U.S.C. § 371, of International Patent Application No. PCT/JP2022/045983, filed Dec. 14, 2022, the entire contents of which are incorporated herein by reference.

FIELD

The present disclosure relates to an armature in which an electric wire is wound around a tooth and an electric motor including the armature.

BACKGROUND

Typically, for an electric motor including teeth wound by an electric wire, a structure has been known in which coils having a plurality of phases are wound around a single tooth in order to balance a cogging thrust or a cogging torque with a magnetomotive force.

Patent Literature 1 discloses a technique for reducing a connection process after winding, by winding coils of two different phases around a single tooth and winding the coils of phases by a single electric wire.

CITATION LIST**Patent Literature**

Patent Literature 1: Japanese Patent Application Laid-open No. 10-225035

SUMMARY OF INVENTION**Problem to be Solved by the Invention**

However, the technique disclosed in Patent Literature 1 has a problem in that, after winding an electric wire of a coil for one phase, an electric wire of a coil for another different phase is wound, and therefore, the number of winding processes and connection processes increases.

The present disclosure has been made in view of the above, and an object of the present disclosure is to obtain an armature that reduces the number of winding processes and the number of connection processes after winding.

Means to Solve the Problem

To solve the above problems and achieve the object, an armature according to the present disclosure is arranged to face a field system via an air gap and is driven by three-phase AC excitation. The armature includes a plurality of teeth including an iron core, an insulating holding member attached to the iron core, and a winding portion in which a coil is formed by winding an electric wire having an insulating cover around the iron core on the insulating holding member. The plurality of teeth includes a first tooth including only the winding portion for a single-phase coil and a second tooth including the winding portions for coils of two phases different from each other. In the second tooth, the winding portions of the two phases different from each other are configured by a single electric wire, and the electric

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wire is continuously wound via an intermediate fixing member provided on the insulating holding member.

Effects of the Invention

An armature according to the present disclosure achieves an effect that it is possible to reduce the number of winding processes and the number of connection processes after winding.

BRIEF DESCRIPTION OF DRAWINGS

FIG. 1 is a schematic diagram of a cross section of a linear motor according to a first embodiment.

FIG. 2 is a connection diagram of the linear motor according to the first embodiment.

FIG. 3 is a perspective view of first tooth of the linear motor according to the first embodiment.

FIG. 4 is a perspective view of second tooth of an electric motor according to the first embodiment.

FIG. 5 is a diagram illustrating a second tooth manufacturing process of the electric motor according to the first embodiment.

FIG. 6 is a diagram illustrating the second tooth manufacturing process of the electric motor according to the first embodiment.

FIG. 7 is a schematic diagram illustrating a cross section of the second tooth of the linear motor according to the first embodiment.

FIG. 8 is a schematic diagram of the cross section of the linear motor according to a second embodiment.

FIG. 9 is a perspective view of the second tooth of the linear motor according to the second embodiment.

FIG. 10 is a diagram illustrating the second tooth manufacturing process of the linear motor according to the second embodiment.

FIG. 11 is a diagram illustrating the second tooth manufacturing process of the linear motor according to the second embodiment.

FIG. 12 is a schematic diagram illustrating the cross section of the second tooth of the linear motor according to the second embodiment.

FIG. 13 is a schematic diagram of the cross section of the linear motor according to a third embodiment.

FIG. 14 is a perspective view of the second tooth of the linear motor according to the third embodiment.

FIG. 15 is a diagram illustrating the second tooth manufacturing process of the linear motor according to the third embodiment.

FIG. 16 is a schematic diagram of the cross section of the linear motor according to a modification of the third embodiment.

FIG. 17 is a schematic diagram of the cross section of the linear motor according to a fourth embodiment.

FIG. 18 is a connection diagram of the linear motor according to the fourth embodiment.

FIG. 19 is a perspective view of the second tooth of the linear motor according to the fourth embodiment.

DESCRIPTION OF EMBODIMENTS

Hereinafter, an armature and an electric motor according to embodiments will be described in detail with reference to the drawings.

First Embodiment

FIG. 1 is a schematic diagram of a cross section of a linear motor according to a first embodiment. A linear motor 10

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according to the first embodiment includes a movable element **1** that is an armature and a stator **3** that is a field system facing the movable element **1** via an air gap. The stator **3** includes a permanent magnet **31** and an attachment seat **32** to which the permanent magnet **31** is fixed. The movable element **1** includes teeth **11**, **12**, **13**, **14**, and **15**. The teeth **11**, **12**, **13**, **14**, and **15** respectively include iron cores **111**, **121**, **131**, **141**, and **151**, an insulating holding member **201** having a function for holding an electric wire and an insulating function, and winding portions **11a**, **12a**, **13a**, **13b**, **14a**, and **15a** in which the electric wire having an insulating film is wound around the iron cores **111**, **121**, **131**, **141**, and **151** and the insulating holding member **201** on the insulating holding member **201** so as to form coils.

FIG. **2** is a connection diagram of the linear motor according to the first embodiment. The winding portions **11a** and **15a** form U-phase coils, the winding portions **12a** and **13b** form V-phase coils, and the winding portions **13a** and **14a** form W-phase coils. The winding portions **11a** and **15a** that are the U-phase coils, the winding portions **12a** and **13b** that are the V-phase coils, and the winding portions **14a** and **13a** that are the W-phase coils are each connected to each other in series, and the coils of the phases are connected by Y connection via a neutral point. That is, the tooth **13** includes winding portions of two different phases, including the winding portion **13b** that is the V-phase coil and the winding portion **13a** that is the W-phase coil. The winding portions **13a** and **13b** of the two different phases included in the tooth **13** are coils that are directly connected to the neutral point.

In a general electric motor driven by three-phase AC excitation having a concentrated winding structure, a single winding portion formed by winding the electric wire around a teeth iron core forms a single-phase coil. That is, in the general electric motor, the single tooth includes the single winding portion. On the other hand, the linear motor **10** according to the first embodiment has a structure in which the number of teeth is not a multiple of three, in order to achieve both of miniaturization and low thrust pulsation. The tooth **13** of the teeth **11**, **12**, **13**, **14**, and **15** includes the winding portions **13a** and **13b** for the coils with the two different phases.

Here, each of the teeth **11**, **12**, **14**, and **15** respectively including the winding portions **11a**, **12a**, **14a**, and **15a** for only the coil of single phase is referred to as a first tooth, and the tooth **13** including the winding portions **13a** and **13b** for the coils of the two different phases is referred to as second tooth.

FIG. **3** is a perspective view of the first tooth of the linear motor according to the first embodiment. The iron core **111** is formed by stacking a plurality of electromagnetic steel sheets **102**. Here, a winding start fixing member **103** and a winding end fixing member **104** are members that fix the electric wire by drawing and winding the electric wire in a winding process and are both fixed to the insulating holding member **201**. The winding start fixing member **103** is used to fix the electric wire at the start of winding of the electric wire, and the winding end fixing member **104** is used at the end of the winding of the electric wire.

Here, a process for forming the coil in the first tooth will be described using the tooth **11** as an example. First, the electric wire is wound around the winding start fixing member **103**, and a winding start portion **301** is formed. Then, the electric wire of a preset number of turns is wound around the insulating holding member **201** counterclockwise, and the winding portion **11a** that generates a magnetic flux in the tooth **11** is formed. By forming the winding start

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portion **301** in advance, it is possible to prevent the electric wire from falling off from the insulating holding member **201** at the time of a winding process for forming the winding portion **11a**. Thereafter, by winding the electric wire around the winding end fixing member **104** provided on the insulating holding member **201** similarly to the winding start portion **301**, a winding end portion **304** is formed, and formation of the coil on the tooth **11** is completed. In this way, the coil of the tooth **11** includes only the winding portion **11a** of the single phase. Note that, in each of the teeth **12**, **14**, and **15** that is also the first tooth, a coil is formed in the same process as the tooth **11**.

FIG. **4** is a perspective view of the second tooth of the electric motor according to the first embodiment. FIGS. **5** and **6** are diagrams illustrating a second tooth manufacturing process of the electric motor according to the first embodiment. In the tooth **13** that is the second tooth including the winding portions **13a** and **13b** for the coils of the two different phases, as illustrated in FIG. **4**, the insulating holding member **201** includes an intermediate fixing member **105**, a crossover projection **202** used to arrange the electric wire therealong when a winding process of the winding portion **13b** with the second phase to be described later is performed, and a winding start groove **701** that determines a position of a winding start electric wire of the winding portion **13b**. The iron core **131** is formed by stacking the plurality of electromagnetic steel sheets **102**.

First, an example of a winding process of a first phase is described. As illustrated in FIG. **5**, the electric wire is wound around the winding start fixing member **103** so as to form the winding start portion **301**. Thereafter, the electric wire of the preset number of turns is wound around the insulating holding member **201** counterclockwise so as to form the winding portion **13a** that is the first phase. Note that, at this stage, unlike FIG. **4**, a winding end electric wire **401** of the winding portion **13a** is not wound around the winding end fixing member **104** and is in a freely movable state.

Next, winding of an intermediate portion **303** is performed to form the winding portion **13b** that is the second phase. As illustrated in FIG. **6**, the winding end electric wire **401** of the winding portion **13a** is wound around the intermediate fixing member **105** provided between the winding start fixing member **103** and the winding end fixing member **104**, and a crossover line **402** that connects the winding portion **13a** and the intermediate portion **303** and the intermediate portion **303** that is an electric wire wound around the intermediate fixing member **105** are formed, and the electric wire is arranged in the winding start groove **701**. At this time, the electric wire is arranged along the crossover projection **202** that is provided on the insulating holding member **201** so as not to have contact with the winding start fixing member **103**, and a crossover line **403** that connects the neutral point and winding start of the winding portion **13b** is formed. Thereafter, the electric wire is wound a preset number of times in the same direction as the winding portion **13a** so as to overlap the winding portion **13a** so as to form the winding portion **13b**. Finally, the electric wire is wound around the winding end fixing member **104**, and the winding end portion **304** is formed, and then, the electric wire is cut.

In this way, in the linear motor **10** according to the first embodiment, the single electric wire can be continuously wound around the winding portion **13a** that is the first phase and the winding portion **13b** that is the second phase, and it is possible to reduce the number of winding processes. Furthermore, as illustrated in FIG. **2**, since the winding portions **13a** and **13b** are the coils directly connected to the neutral point, the intermediate fixing member **105** can serve

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as the neutral point at the time of connection. As a result, the number of end points of the electric wires forming the winding portions **11a**, **12a**, **13a**, **13b**, **14a**, and **15a** for the phases is reduced, and it is possible to reduce the number of connection processes.

FIG. 7 is a schematic diagram illustrating a cross section of the second tooth of the linear motor according to the first embodiment. The winding portion **13a** that is the first phase is wound in counterclockwise so that the winding start electric wire **501** is used at the start of winding and a winding end electric wire **502** is used at the end the winding of the winding portion **13a** that is the first phase. The winding portion **13b** that is the second phase is wound in a winding direction similar to the winding portion **13a** that is the first phase, so that a winding start electric wire **503** is used at the start winding and a winding end electric wire **504** is used at the end the winding.

Here, since the winding end electric wire **502** of the winding portion **13a** that is the first phase is connected to the neutral point, a current flowing in the winding portion **13a** is in a direction from the winding start electric wire **501** of the winding portion **13a** to the winding end electric wire **502** of the winding portion **13a**, that is, a direction of a current direction **601**. On the other hand, since the winding start electric wire **503** of the winding portion **13b** that is the second phase is connected to the neutral point, the current flowing direction is a direction from the winding end electric wire **504** to the winding start electric wire **503**, that is, a direction of a current direction **602**.

At this time, since the winding end electric wire **502** of the winding portion **13a** and the winding start electric wire **503** of the winding portion **13b** that are contact portions between the winding portion **13a** that is the first phase and the winding portion **13b** that is the second phase are connected to the side of the neutral point, a potential difference between the contact portions of the winding portions **13a** and **13b** caused by a surge voltage generated at the time of current excitation is smaller than that in a case where the winding end electric wire **502** of the winding portion **13a** and the winding start electric wire **503** of the winding portion **13b** are not connected to the neutral point. Due to a relative decrease in the potential difference between the winding portions **13a** and **13b**, in the contact portion between the winding portions **13a** and **13b**, it is possible to secure interphase insulation performance without providing an insulating member such as an insulating paper, for example. Therefore, it is possible to secure interphase insulation at the same time without lowering a winding space factor.

Note that, in the linear motor **10** according to the first embodiment, as illustrated in FIG. 4, the intermediate fixing member **105** is arranged between the winding start fixing member **103** and the winding end fixing member **104**. However, it is sufficient to arrange the intermediate fixing member **105** in a state of being separated with a necessary insulation distance, the intermediate fixing member **105** does not necessarily need to be arranged between the winding start fixing member **103** and the winding end fixing member **104**.

Furthermore, in the linear motor **10** according to the first embodiment, each of the winding portions **13a** and **13b** is wound counterclockwise. However, even if each of the winding portions **13a** and **13b** is wound clockwise, similar effects can be obtained. Furthermore, even if one of the winding portions **13a** and **13b** is wound clockwise and the other one is wound counterclockwise, the similar effects can be obtained. That is, in the tooth **13** that is the second tooth,

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the winding portions **13a** and **13b** of the two different phases may be wound around the iron core **131** and the insulating holding member **201** in the same winding direction or may be wound around the iron core **131** and the insulating holding member **201** in different winding directions from each other.

Furthermore, in the first embodiment, the linear motor **10** of which a field magnet of the stator **3** has four poles and the movable element **1** that is the armature has six phases has been described as an example. However, a combination of magnets and phases of the armature may be any combination as long as the linear motor **10** is appropriately driven.

Furthermore, although the linear motor **10** is described as an example in the first embodiment, the same can be implemented for a rotary electric machine.

With the linear motor **10** according to the first embodiment, it is possible to reduce the number of winding processes by continuously winding the winding portion **13a** that is the first phase and the winding portion **13b** that is the second phase, and it is possible to reduce the number of connection processes after winding, by providing the intermediate portion **303** between the winding portions **13a** and **13b**.

Second Embodiment

FIG. 8 is a schematic diagram of the cross section of the linear motor according to a second embodiment. Connection of a movable element **1A** of the linear motor **10** according to the second embodiment is similar to that of the movable element **1** of the linear motor **10** according to the first embodiment. The tooth **13** is a second tooth including the winding portion **13b** that is the V-phase coil and the winding portion **13a** that is the W-phase coil, and the winding portions **13a** and **13b** are wound in a state of having contact with each other. In a case where the winding portions **13a** and **13b** constituting the coils of the two different phases are arranged along an arrangement direction of the movable element **1A** and the stator **3**, the winding portion **13a** is closer to a core back portion of the tooth **13** than the winding portion **13b**, and more magnetic fluxes pass therethrough. Therefore, the W phase having the winding portion **13a** as a component has a higher induced voltage than the V phase having the winding portion **13b** as a component.

FIG. 9 is a perspective view of the second tooth of the linear motor according to the second embodiment. FIGS. **10** and **11** are diagrams illustrating the manufacturing process of the second tooth of the linear motor according to the second embodiment. A process for forming a coil of the second tooth will be described from a winding process of the winding portion **13a** that is the first phase. As illustrated in FIG. **10**, the electric wire is wound around the winding start fixing member **103** so as to form the winding start portion **301**. Thereafter, the electric wire of the preset number of turns is wound around the insulating holding member **201** counterclockwise so as to form the winding portion **13a** that is the first phase. At this time, in order to perform winding of the second phase, a space is provided on a side of the stator **3** than the winding portion **13a**, in the arrangement direction of the movable element **1A** and the stator **3**. At this stage, as illustrated in FIG. **10**, the winding end electric wire **401** of the winding portion **13a** that is the first phase is not wound around the winding end fixing member **104** and is in a freely movable state.

Next, winding of the intermediate portion **303** is performed to form the winding portion **13b** that is the second phase. As illustrated in FIG. **11**, the intermediate portion **303**

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is formed by winding the winding end electric wire **401** of the winding portion **13a** around the intermediate fixing member **105** provided between the winding start fixing member **103** and the winding end fixing member **104**, and the electric wire is disposed in the winding start groove **701**. At this time, the electric wire is wound along the crossover projection **202** provided on the insulating holding member **201** so as not to have contact with the winding start fixing member **103**. Thereafter, after the winding portion **13b** is formed on a side of the stator **3** than the winding portion **13a**, in the arrangement direction of the movable element **1A** and the stator **3**, by winding the electric wire counterclockwise a preset number of turns, the winding end portion **304** is formed by winding the electric wire around the winding end fixing member **104**. By cutting the electric wire after forming the winding end portion **304**, a winding state illustrated in FIG. **9** is obtained.

FIG. **12** is a schematic diagram illustrating the cross section of the second tooth of the linear motor according to the second embodiment. The winding portion **13a** that is the first phase is wound counterclockwise from the winding start electric wire **501** to the winding end electric wire **502**. The winding portion **13b** that is the second phase is wound counterclockwise from the winding start electric wire **503** to the winding end electric wire **504**, similarly to the winding portion **13a** with the first phase.

Here, since the winding end electric wire **502** of the winding portion **13a** is connected to the neutral point, the direction of the current flowing in the winding portion **13a** is in the direction from the winding start electric wire **501** of the winding portion **13a** to the winding end electric wire **502**, that is, the direction of the current direction **601**. On the other hand, since the winding start electric wire **503** of the winding portion **13b** is connected to the neutral point, the current flowing direction is the direction from the winding end electric wire **504** to the winding start electric wire **503**, that is, the direction of the current direction **602**. Therefore, in the linear motor **10** according to the second embodiment, it is possible to arrange the winding start electric wire **501** of the winding portion **13a** and the winding end electric wire **504** of the winding portion **13b** to be away from each other, and it is possible to avoid an insulation failure due to a sudden surge voltage, without providing the insulating member such as the insulating paper between the winding portions **13a** and **13b**. Therefore, it is possible to improve the winding space factor, and it is possible to reduce an effect on a temperature increase due to a copper loss on an electric motor having the same size.

In the linear motor **10** according to the second embodiment, since the winding portions **13a** and **13b** are arranged along the arrangement direction of the movable element **1A** and the stator **3**, it is possible to finely adjust the induced voltage in each phase, and it is possible to improve a degree of design freedom.

Third Embodiment

FIG. **13** is a schematic diagram of the cross section of the linear motor according to a third embodiment. In a movable element **1B** of the linear motor **10** according to the third embodiment, a tooth **13** is a second tooth including the winding portion **13b** that is the V-phase coil and the winding portion **13a** that is the W-phase coil. The winding portions **13b** and **13a** are wound with an insulating member **71** interposed therebetween.

FIG. **14** is a perspective view of the second tooth of the linear motor according to the third embodiment. FIG. **15** is

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a diagram illustrating the second tooth manufacturing process of the linear motor according to the third embodiment. A process for forming a coil of the second tooth will be described from a winding process of the winding portion **13a** with the first phase. A process after the winding portion **13a** is wound and before the electric wire is arranged in the winding start groove **701** is similar to that of the movable element **1A** of the linear motor **10** according to the second embodiment. After disposing the electric wire in the winding start groove **701** after the winding portion **13a** is wound, the second tooth is formed by winding the winding portion **13b** that is the second phase, after disposing the insulating member **71** on a side of the stator **3** of the winding portion **13a** in an arrangement direction of the movable element **1B** and the stator **3**. As in the movable element **1B** of the linear motor **10** according to the third embodiment, by disposing the insulating member **71** between the winding portions **13a** and **13b** forming the coils having the different phases. This makes it possible to improve insulation resistance performance while reducing the number of winding processes.

FIG. **16** is a schematic diagram of the cross section of the linear motor according to a modification of the third embodiment. In the movable element **1B** of the linear motor **10** according to the third embodiment, the winding portions **13a** and **13b** are arranged along the arrangement direction of the movable element **1B** and the stator **3**. However, even if the winding portions **13a** and **13b** are arranged in a winding center direction, as in a movable element **1C** of the linear motor **10** according to the modification of the third embodiment, similar effects can be obtained.

Fourth Embodiment

FIG. **17** is a schematic diagram of the cross section of the linear motor according to a fourth embodiment. FIG. **18** is a connection diagram of the linear motor according to the fourth embodiment. The tooth **12** is the second tooth including a winding portion **12b** that is a U-phase coil and the winding portion **12a** that is a V-phase coil. The tooth **14** is the second tooth including a winding portion **14b** that is a V-phase coil and the winding portion **14a** that is a W-phase coil. That is, in the linear motor **10** according to the fourth embodiment, a movable element **1D** that is an armature includes the two second teeth. A winding process of the teeth **12** and **14** is similar to that of the teeth **13** of the linear motor **10** according to the first embodiment.

FIG. **19** is a perspective view of the second tooth of the linear motor according to the fourth embodiment. A winding process of the winding portion **13a** that is a first phase is similar to the tooth **13** according to the first embodiment illustrated in FIG. **4**. After winding of the winding portion **13a** is completed, the crossover line **402** that connects the winding portion **13a** and the intermediate portion **303** and the crossover line **403** that connects the intermediate portion **303** and the winding portion **13b** are cut.

In the linear motor **10** according to the fourth embodiment, by cutting the crossover line **402** that connects the winding portion **13a** and the intermediate portion **303** and the crossover line **403** that connects the intermediate portion **303** and the winding portion **13b**, it is possible to separate the winding end electric wire **401** of the winding portion **13a** and the winding start electric wire **404** of the winding portion **13b** from the intermediate fixing member **105**, it is not necessary to connect the winding end electric wire **401** of the winding portion **13a** and the winding start electric wire **404** of the winding portion **13b** to the neutral point, and it is possible to improve the degree of design freedom.

The configurations described in the above embodiments indicate an example of content and can be combined with other known techniques. Furthermore, the configurations described in the embodiments can be partially omitted or changed without departing from the gist.

REFERENCE SIGNS LIST

1, 1A, 1B, 1C, 1D movable element; 3 stator; 10 linear motor; 11, 12, 13, 14, 15 teeth; 11a, 12a, 12b, 13a, 13b, 14a, 14b, 15a winding portion; 31 permanent magnet; 32 attachment seat; 71 insulating member; 102 electromagnetic steel sheet; 103 winding start fixing member; 104 winding end fixing member; 105 intermediate fixing member; 111, 121, 131, 141, 151 iron core; 201 insulating holding member; 202 crossover projection; 301 winding start portion; 303 intermediate portion; 304 winding end portion; 401, 502, 504 winding end electric wire; 404, 501, 503 winding start electric wire; 402, 403 crossover line; 601, 602 current direction; 701 winding start groove.

The invention claimed is:

1. An armature that is arranged to face a field system via an air gap and is driven by three-phase AC excitation, the armature comprising:

a plurality of teeth including an iron core, an insulating holding member attached to the iron core, and a winding portion in which an electric wire having an insulating cover is wound around the iron core on the insulating holding member and a plurality of coils are formed, wherein

the plurality of teeth includes a first tooth including the winding portion for only a one-phase coil in the plurality of coils and a second tooth including the winding portions for coils of two different phases from each other in the plurality of coils, and

in the second tooth, the winding portions of the two different phases from each other include a single electric wire and are continuously wound via an intermediate fixing member provided on the insulating holding member.

2. The armature according to claim 1, wherein the intermediate fixing member is an electronic neutral point of a connection structure.

3. The armature according to claim 2, wherein the winding portions of the two different phases from each other in the second tooth are wound around the iron core and the insulating holding member in a same winding direction or in winding directions different from each other.

4. An electric motor comprising:

the field system; and

the armature according to claim 3.

5. An electric motor comprising:

the field system; and

the armature according to claim 2.

6. The armature according to claim 1, wherein the winding portions forming the coils of the two different phases from each other are wound to overlap on the iron core and the insulating holding member.

7. An electric motor comprising:

the field system; and

the armature according to claim 6.

8. The armature according to claim 1, wherein the winding portions forming the coils of the two different phases from each other are wound around the iron core and the insulating holding member so as to be arranged in an arrangement direction of the armature and the field system.

9. An electric motor comprising:

the field system; and

the armature according to claim 8.

10. The armature according to claim 1, wherein the winding portions forming the coils of the two different phases from each other have direct contact with each other.

11. An electric motor comprising:

the field system; and

the armature according to claim 10.

12. An electric motor comprising:

the field system; and

the armature according to claim 1.

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