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LOGIC DIE AND SEMICONDUCTOR DEVICE INCLUDING LOGIC DIE

Abstract

Provided are a logic die for supporting direct interfacing between a memory die and a memory controller via a through silicon via (TSV) and a semiconductor device including the logic die. The semiconductor device includes a logic die including a memory controller, an interface circuit, and a plurality of TSVs arranged in a TSV region. A plurality of memory dies stacked vertically on the logic die, and connected to the plurality of TSVs. The memory controller operates in a first voltage domain, and the plurality of memory dies operate in a second voltage domain. The interface circuit includes a plurality of TSV circuit blocks connected to the plurality of TSVs. Each TSV circuit block is configured to convert a voltage level of a signal, transmitted via a corresponding TSV, between a first voltage level in the first voltage domain and a second voltage level in the second voltage domain.

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Background/Summary

CROSS-REFERENCE TO RELATED APPLICATION

[0001] This application is based on and claims priority under 35 U.S.C. § 119 to Korean Patent Application Nos. 10-2024-0025310, filed on Feb. 21, 2024, and 10-2024-0052399, filed on Apr. 18, 2024, in the Korean Intellectual Property Office, the disclosures of which are incorporated by reference herein in their entireties.

BACKGROUND

[0002] Example semiconductor devices include dynamic random access memory (DRAM), which is a volatile memory that determines data based on electric charge stored in a capacitor. The DRAM can be high-bandwidth memory (HBM), which provides input and output in a multi-channel interface. HBM is used in various systems, such as graphics, servers, supercomputers, and networks that demand high performance and low power. HBM may include a base die and core dies stacked vertically on the base die, and the base die may be connected to the core dies via a plurality of through silicon vias (TSVs). Generally, communication through an interposer provides the interface between a memory controller of an external die and core dies of an HBM. This structure may cause latency during signal transmission and reception.

SUMMARY

[0003] The present disclosure provides a logic die, which supports direct interfacing between a memory controller and core dies using through silicon vias (TSVs), and a semiconductor device including the logic die.

[0004] In a first general aspect, a semiconductor device includes: a logic die including a memory controller, an interface circuit, and a plurality of TSVs arranged in a TSV region, wherein the memory controller operates in a first voltage domain, and a plurality of memory dies stacked vertically on the logic die, operating in a second voltage domain, and connected to the plurality of TSVs, wherein the interface circuit includes a plurality of TSV circuit blocks being in the TSV region and connected to the plurality of TSVs in the TSV region, and each of the plurality of TSV circuit blocks is configured to convert a voltage level of a signal transmitted via a corresponding TSV among the plurality of TSVs, between a first voltage level in the first voltage domain and a second voltage level in the second voltage domain.

[0005] In a second general aspect, a logic die includes: a memory controller operating in a first clock domain, a plurality of through silicon vias (TSVs) arranged in a TSV region and electrically connected to a plurality of memory dies operating in a second clock domain, and an interface circuit between the memory controller and the plurality of TSVs, wherein the interface circuit includes a plurality of TSV macros arranged, in the TSV region, in an array form and connected to the plurality of TSVs, and each of the plurality of TSV macros is configured to synchronize signals received from the plurality of memory dies with a controller clock according to the first clock domain or synchronize a signal received from the memory controller with a memory clock according to the second clock domain.

[0006] In a third general aspect, a logic die includes: a memory controller operating in a first

voltage domain, a plurality of through silicon vias (TSVs) arranged in a TSV region and electrically connected to a plurality of memory dies operating in a second voltage domain, and an interface circuit between the memory controller and the plurality of TSVs, wherein the interface circuit includes a plurality of TSV macros arranged, in the TSV region, in an array form and connected to the plurality of TSVs, and each of the plurality of TSV macros is configured to convert a voltage level of a signal, transmitted via a corresponding TSV among the plurality of TSVs, between a first voltage level in the first voltage domain and a second voltage level in the second voltage domain.

Description

BRIEF DESCRIPTION OF THE DRAWINGS

[0007] FIG. 1 is a block diagram showing an example of a semiconductor device.
[0008] FIG. 2 schematically shows an example of the structure of a semiconductor device.
[0009] FIGS. 3A and 3B illustrates examples of logic dies.
[0010] FIG. 4 shows an example of a through silicon via (TSV) macro array.
[0011] FIG. 5A illustrates an example of a high-bandwidth memory (HBM) system, and FIG. 5B illustrates an example of an HBM device.
[0012] FIG. 6 is a block diagram schematically showing an example of TSV macro.
[0013] FIG. 7 is a block diagram showing another example TSV macro.
[0014] FIGS. 8A to 8D are timing charts illustrating operation of the TSV macro of FIG. 7.
[0015] FIG. 9 is a block diagram schematically showing another example of a TSV macro.
[0016] FIG. 10 is a block diagram showing the TSV macro of FIG. 9.
[0017] FIG. 11A is a timing chart illustrating operation of the TSV macro of FIG. 10 when the second TSV macro of FIG. 10 is used as a write path.
[0018] FIG. 11B is a timing chart illustrating operation of the TSV macro of FIG. 10 when the second TSV macro of FIG. 10 is used as a read path.
[0019] FIG. 12 is a block diagram schematically showing another example of a TSV macro.
[0020] FIG. 13 is a block diagram showing the TSV macro of FIG. 12.
[0021] FIGS. 14A to 14D are timing charts illustrating an example of operation of the TSV macro of FIG. 13.
[0022] FIG. 15 is a block diagram showing another example of a TSV macro.
[0023] FIGS. 16A to 16E each show an example of a delay control logic.
[0024] FIG. 17 illustrates an example of a TSV region.
[0025] FIGS. 18A and 18B each show an example of a TSV macro array.
[0026] FIGS. 19A, 19B, and 19C each show an example of a TSV macro array.
[0027] FIGS. 20A, 20B, and 20C each show an example of a TSV macro array.
[0028] FIG. 21 shows an example of an HBM semiconductor device.
[0029] FIGS. 22A and 22B show examples of HBM semiconductor devices.
[0030] FIGS. 23A and 23B show examples of electronic systems including HBM semiconductor devices.
[0031] In the drawings, the same reference numerals are given to the same elements, and repeated descriptions thereof are omitted.

DETAILED DESCRIPTION

[0032] FIG. 1 is a block diagram showing an example of a semiconductor device 10.
[0033] Referring to FIG. 1, the semiconductor device 10 includes a logic die 100 and a memory die 200. In some implementations, the semiconductor device 10 may be referred to as a memory device, a memory system, a storage device, or a storage system. In some implementations, the logic die 100 may be referred to as a logic chip, a base die, a controller, a controller chip, a controller die,

or a host. In some implementations, the memory die **200** may be referred to as a memory chip or a core die. For example, the memory die **200** may include a plurality of memory dies or a plurality of core dies **200_1** to **200_N** (e.g., first core die **200_1** to Nth core die **200_N**) (where N is a natural number of 2 or more), each of which includes a memory cell array MCA. The number of core dies in the memory die **200** may vary.

[0034] The logic die **100** includes a memory controller **110** and an interface circuit **120**. The memory controller **110** may control all operations on the memory die **200**, including write operations and read operations on the memory die **200**. The interface circuit **120** may perform interfacing between the memory controller **110** and the memory die **200**. In some implementations, the interface circuit **120** may be referred to as a memory interface or a memory interface circuit. Specifically, the interface circuit **120** may support direct interfacing for data and clocks of a controller domain corresponding to the memory controller **110** and data and clocks of a memory domain corresponding to the memory die **200**.

[0035] The logic die **100** may transmit a command/address CMD/ADDR and a clock signal CK to the memory die **200** via the interface circuit **120**. For example, the command/address CMD/ADDR may include a column address CA and a row address RA, that is, a column/row address CA/RA. In addition, the logic die **100** may transmit data DQ, e.g., write data, to the memory die **200** via the interface circuit **120** or receive data DQ, e.g., read data, from the memory die **200**.

[0036] In some implementations, the semiconductor device **10** may be provided as a high-bandwidth memory (HBM). Also, the semiconductor device **10** may provide a wide interface architecture using a multi-channel interface between the logic die **100** and the memory die **200** for high-speed and low-power operation. For example, each of the plurality of core dies **200_1** to **200_N** may support 4-channels, and thus, the memory die **200** may support 16-channels. However, examples are not limited thereto, and each of the plurality of core dies **200_1** to **200_N** may support 1-channel, 2-channels, 4-channels, or more.

[0037] In some implementations, the logic die **100** and the plurality of core dies **200_1** to **200_N** may communicate with each other via through silicon vias (TSVs) and/or through backside vias (TBVs). Also, each of the plurality of core dies **200_1** to **200_N** may include a plurality of channels that independently communicate with the logic die **100**, and the TSVs and/or TBVs may be arranged so as to be physically separated from each other for the plurality of channels. For example, when the memory die **200** includes first to A-th channels CH1 to CHA and each of the plurality of core dies **200_1** to **200_N** includes two channels, A channels may correspond to $2 \times N$ channels (A is a natural number of 2 or more). Also, when each of the plurality of core dies **200_1** to **200_N** includes 4 channels, A channels may correspond to $4 \times N$ channels.

[0038] The interface circuit **120** may include a plurality of input/output blocks for communication between the memory controller **110** and the memory die **200**. Each of the input/output blocks may be connected to at least one TSV or at least one TBV and include at least one circuit for processing signals transmitted and received via the connected TSV or TBV. In this example, the memory controller **110** and the memory die **200** transmit and receive data via a plurality of TSVs. Accordingly, the input/output block may be referred to as a “TSV circuit block.” However, examples are not limited thereto, and the memory controller **110** and the memory die **200** can transmit and receive data via a plurality of TBVs.

[0039] In some implementations, the plurality of input/output blocks or the plurality of TSV circuit blocks may be provided as macros or hard macros and electrically connected to the plurality of TSVs. The hard macros may include various intellectual properties (IPs). The IP may refer to reusable blocks that are provided with layouts and interconnections designed to perform desired electrical functions. Accordingly, the input/output block or TSV circuit block may be referred to as a “TSV macro” or “TSV slice.” Hereinafter, the input/output block or TSV circuit block is referred to as a TSV macro.

[0040] In some implementations, the interface circuit **120** may include a plurality of input/output

blocks, that is, a plurality of TSV macros, and the plurality of TSV macros may include first to fourth TSV macros **TM1** to **TM4**. The first to fourth TSV macros **TM1** to **TM4** may be selectively arranged according to the types of signals transmitted and received via the connected TSV. The first to fourth TSV macros **TM1** to **TM4** are described below with reference to FIGS. 6 to 15.

[0041] In some implementations, the memory controller **110** of the logic die **100** may operate in a first voltage domain and the memory die **200** may operate in a second voltage domain. In this example, the “voltage domain” may refer to a group of logic elements operating at the same supply voltage level. The power-performance balance of each domain may be optimized by using different voltage levels for the various domains. For example, the memory controller **110** in the first voltage domain may operate at a first voltage level and the memory die **200** in the second voltage domain may operate at a second voltage level. For example, the second voltage level may be higher than the first voltage level.

[0042] The interface circuit **120** or each of the TSV macros may change the signal level of each of transmission signals transmitted from the memory controller **110** to the memory die **200**, for example, the command **CMD**, the address **ADDR**, the data **DQ**, and/or the clock signal **CK**, from the first voltage level in the first voltage domain to the second voltage level in the second voltage domain. For example, the interface circuit **120** or each of the TSV macros may increase the voltage level of the transmission signal from the first voltage level to the second voltage level. The interface circuit **120** or each of the TSV macros may change the signal levels of reception signals transmitted from the memory die **200** to the memory controller **110**, for example, the data **DQ** and/or the clock signal **CK**, from the second voltage level in the second voltage domain to the first voltage level in the first voltage domain.

[0043] In some implementations, the memory controller **110** of the logic die **100** may operate in a first clock domain and the memory die **200** may operate in a second clock domain. Specifically, the internal signals of the logic die **100**, that is, the signals transmitted to and received from the memory controller **110** inside the logic die **100**, for example, the command **CMD**, the address **ADDR**, the data **DQ**, and/or the clock signal **CK**, may be synchronized to a controller clock according to the first clock domain. As another example, the internal signals of the memory die **200** (i.e., signals transmitted and received inside the memory die **200**), for example, the command **CMD**, the address **ADDR**, the data **DQ**, and/or the clock signal **CK**, may be synchronized to a memory clock according to the second clock domain.

[0044] As described above, the logic to be synchronized between clock crossings has to be provided so as to exchange data or signals between different clock domains. The interface circuit **120** or each TSV macro may synchronize the transmission signal transmitted from the memory controller **110** to the memory die **200** with the memory clock according to the second clock domain and transmit the signal synchronized with the memory clock to the memory die **200**. In addition, the interface circuit **120** or each TSV macro may synchronize the reception signal transmitted from the memory die **200** to the memory controller **110** with the controller clock according to the first clock domain and transmit the signal synchronized with the controller clock to the memory controller **110**.

[0045] In some implementations, the memory controller **110** of the logic die **100** may operate in the first voltage domain and the first clock domain, and the memory die **200** may operate in the second voltage domain and the second clock domain. The interface circuit **120** or each TSV macro may change the signal level of the transmission signal transmitted from the memory controller **110** to the memory die **200** from the first voltage level in the first voltage domain to the second voltage level in the second voltage domain, synchronize the transmission signal with the memory clock according to the second clock domain, and transmit the signal synchronized with the memory clock to the memory die **200**. Also, the interface circuit **120** or each TSV macro may change the signal level of the reception signal transmitted from the memory die **200** to the memory controller **110** from the second voltage level in the second voltage domain to the first voltage level in the first

voltage domain, synchronize the reception signal to the controller clock according to the first clock domain, and transmit the signal synchronized with the controller clock to the memory controller **110**.

[0046] In some implementations, each TSV macro may process data and/or signals transmitted and received between the memory controller **110** and the memory die **200** via the corresponding TSV and thus support direct interfacing between the memory controller **110** and the memory die **200** via the TSV. Also, the difficulty in designing a memory interface may be reduced by arranging the plurality of TSV macros as being respectively connected to the plurality of TSVs in an array form. In addition, since the TSV macros are selectively arranged according to data and signals transmitted and received via the TSV, the design freedom of the memory interface may be increased. Furthermore, the number of TSVs corresponding to each TSV macro may change, and thus, the interface circuit **120** may be freely designed according to the size of the logic die **100** or the available area of the interface circuit **120** inside the logic die **100**.

[0047] The semiconductor device **10** may be configured inside a personal computer (PC), a mobile electronic device, or a data server. The mobile electronic device may be formed as a laptop computer, a mobile phone, a smartphone, a tablet PC, a personal digital assistant (PDA), an enterprise digital assistant (EDA), a digital still camera, a digital video camera, a portable multimedia player (PMP), a personal navigation device or portable navigation device (PND), a handheld game console, a mobile internet device (MID), a wearable computer, an Internet of Things (IoT) device, an Internet of Everything (IoE) device, or a drone.

[0048] The logic die **100** may include or correspond to an application specific integrated circuit (ASIC), a system on chip (SoC), an application processor (AP), a mobile AP, a chipset, etc. Also, the logic die **100** may further include at least one of other components that perform a function as a host, such as a central processing unit (CPU), a graphics processing unit (GPU), a neural processing unit (NPU), an accelerated processing unit (APU), a tensor processing unit (TPU), a field-programmable gate array (FPGA), a massively parallel processor array (MPPA), and a multi-processor system-on-chip (MPSoC).

[0049] The memory controller **110** may access the memory die **200** in response to a request from a host and communicate with the host using a variety of protocols. For example, the memory controller **110** may communicate with the host using an interface protocol, such as peripheral component interconnect-express (PCI-E), advanced technology attachment (ATA), serial ATA (SATA), parallel ATA (PATA), and a serial attached SCSI (SAS). In addition, other interface protocols, such as universal serial bus (USB), multi-media card (MMC), enhanced small disk interface (ESDI), and integrated drive electronics (IDE), may be applied to protocols between the host and the memory controller **110**.

[0050] The memory cell array MCA in each of the plurality of core dies **200_1** to **200_N** may include dynamic random access memory (DRAM) cells. In this example, the semiconductor device **10** may be referred to as HBM DRAM or HBM. For example, the memory cell array MCA may include double data rate synchronous dynamic random access memory (DDR SDRAM), low power double data rate (LPDDR) SDRAM, graphics double data rate (GDDR) SDRAM, rambus dynamic random access memory (RDRAM), etc. However, examples are not limited thereto. The memory cell array MCA may include volatile memory, such as static random access memory (SRAM), or non-volatile memory, such as flash memory, magnetic RAM (RAM), ferroelectric RAM (FeRAM), phase change RAM (PRAM), and resistive RAM (ReRAM).

[0051] Also, each of the plurality of core dies **200_1** to **200_N** may further include peripheral circuits for controlling write and read operations for the memory cell array MCA. In some implementations, each of the plurality of core dies **200_1** to **200_N** may further include an arithmetic circuit that performs arithmetic processing using data received from the logic die **100**.

[0052] FIG. 2 schematically shows the structure of an example of a semiconductor device **20**.

[0053] Referring to FIG. 2, the semiconductor device **20** includes a logic die **100a** and a memory

die **200a**, and the memory die **200a** may include first to fourth core dies **200_1** to **200_4** stacked on the logic die **100a** in a vertical direction VD. In some implementations, the semiconductor device **20** may be referred to as a 3-dimensional (or 3D) memory device or a stacked memory device. For example, the semiconductor device **20** may correspond to a 3-dimensional HBM device. The semiconductor device **20** may correspond to an example of the semiconductor device **10** of FIG. 1, and the descriptions given above with reference to FIG. 1 may also be applied to this example.

[0054] The logic die **100a** and each of the first to fourth core dies **200_1** to **200_4** may include TSVs. The TSVs in the logic die **100a** may extend through the logic die **100a** in the vertical direction VD and the TSVs of the first to fourth core dies **200_1** to **200_4** may extend respectively through the first to fourth core dies **200_1** to **200_4** in the vertical direction VD. Bumps BP may be arranged between the logic die **100a** and the first to fourth core dies **200_1** to **200_4**. For example, the bumps BP may include micro bumps. For example, the bumps BP may include conductive bumps containing copper, cobalt, nickel, etc. The logic die **100a** and the first to fourth core dies **200_1** to **200_4** may be electrically connected to each other via the TSVs and bumps BP.

[0055] The logic die **100a** may further include a memory controller **110** and an interface circuit **120**. The TSVs in the logic die **100a** may be arranged in a TSV region TSV_RG, and the interface circuit **120** may be arranged so as to be connected to the TSVs in the TSV region TSV_RG. For example, the interface circuit **120** may be disposed below the TSVs in the TSV region TSV_RG, and thus, the interface circuit **120** may be electrically connected to the first to fourth core dies **200_1** to **200_4** via the TSVs.

[0056] The interface circuit **120** may include a plurality of TSV macros. Each of the TSV macros may be connected to at least one TSV and process the data or signals transmitted and received via the connected TSV so as to perform input/output operations using the TSV. For example, each TSV macro may change the voltage level of data or signals transmitted via the TSV connected thereto to the voltage level according to the voltage domain of a die to which the data or signals are to be transmitted. For example, each TSV macro may synchronize data or signals transmitted via the TSV connected thereto with a clock according to the clock domain of a die to which the data or signals are to be transmitted, that is, the memory die **200a**. For example, each TSV macro may synchronize signals received via the TSV connected thereto with a clock according to the clock domain of a die to which the signals are to be transmitted, that is, the memory controller **110**.

[0057] The logic die **100a** may further include other logics **130**. For example, other logics **130** may include a CPU or GPU. For example, other logics **130** may include interface logics. Although FIG. 2 illustrates that the memory controller **110**, the interface circuit **120**, and other logics **130** are arranged in a first direction D1, examples are not limited thereto. In some implementations, the arrangement of the memory controller **110**, the interface circuit **120**, and other logics **130** may vary inside the logic die **100a**.

[0058] In addition, the logic die **100a** may further include backside vias, for example, TBVs. For example, the TBVs may be arranged so as to be connected to the interface circuit **120** in the TSV region TSV_RG. Accordingly, the interface circuit **120** may be electrically connected to the first to fourth core dies **200_1** to **200_4** via the TBVs and/or wires connected to the TBVs. In addition, the interface circuit **120** may be electrically connected, via the TBVs, to other components in the logic die **100a**, for example, the memory controller **110** and other logics **130** or to an external device.

[0059] FIG. 3A illustrates an example of a logic die **100b**.

[0060] Referring to FIG. 3A, the logic die **100b** includes a TSV region **101**, memory controllers **110a** and **110b**, a CPU **130a**, and a GPU **130b**. In this example, the logic die **100b** may correspond to an example of the logic die **100a** of FIG. 2, and the TSV region **101** may correspond to the TSV region TSV_RG of FIG. 2. The descriptions given above with reference to FIGS. 1 and 2 may also be applied to this example.

[0061] The logic die **100b** may further include a plurality of TSVs and an interface circuit **120** located in the TSV region **101**, and the interface circuit **120** may include a plurality of TSV macros

TM. Each of the TSV macros TM may be connected to at least one TSV. FIG. 3A shows that each TSV macro TM is connected to one TSV, but examples are not limited thereto. For example, TSV macro arrays described below with reference to FIGS. 18A to 19C.

[0062] In some implementations, the interface circuit 120 may include a TSV macro array TM_ARY. For example, a plurality of TSVs may be arranged in an array form in a first direction D1 and a second direction D2, and a plurality of TSV macros TM may be arranged in an array form in the first direction D1 and the second direction D2. Accordingly, the plurality of TSV macros TM may form the TSV macro array TM_ARY.

[0063] FIG. 3B illustrates an example of a logic die 100c.

[0064] Referring to FIG. 3B, the logic die 100c may correspond to a modified example of the logic die 100b of FIG. 3A. The TSV region TSV_RG of the logic die 100c includes first to fourth TSV regions 101a to 101d. A plurality of TSVs and a plurality of TSV macros TM may be arranged in each of the first to fourth TSV regions 101a to 101d. However, examples are not limited thereto, and the TSV region TSV_RG may be divided into five or more TSV regions or divided into less than four TSV regions.

[0065] Each of the first to fourth TSV regions 101a to 101d may correspond to a plurality of channels. For example, each of the first to fourth TSV regions 101a to 101d may correspond to four channels. For example, the first TSV region 101a may include an interface circuit 120a corresponding to two channels of the first core die (e.g., 200_1 in FIG. 2) and two channels of the third core die (e.g., 200_3 in FIG. 2). For example, the second TSV region 101b may include an interface circuit 120b corresponding to two channels of the second core die (e.g., 200_2 in FIG. 2) and two channels of the fourth core die (e.g., 200_4 in FIG. 2). For example, the third TSV region 101c may include an interface circuit 120c corresponding to the other two channels of the first core die 200_1 and the other two channels of the third core die 200_3. For example, the fourth TSV region 101d may include an interface circuit 120d corresponding to the other two channels of the second core die 200_2 and the other two channels of the fourth core die 200_4. The interface circuit located in each of the first to fourth TSV regions 101a to 101d may include a TSV macro array. For example, the interface circuit 120d located in the fourth TSV region 101d may include a TSV macro array TM_ARY' in which a plurality of TSV macros TM are arranged in an array form.

[0066] FIG. 4 shows an example of a TSV macro array TM_ARY''.

[0067] Referring to FIG. 4, the TSV macro array TM_ARY'' may include a plurality of TSV macros TM, and each of TSV macros TM may be connected to a corresponding TSV. The TSV macro array TM_ARY'' may be provided in the interface circuit of the logic die. For example, the TSV macro array TM_ARY'' may correspond to a modified example of the TSV macro array TM_ARY of FIG. 3A or the TSV macro array TM_ARY' of FIG. 3B.

[0068] M metal layers, where M is a natural number greater than 0, may be disposed above the TSV macro array TM_ARY'' in a vertical direction VD. In this example, lower metal layers adjacent to a substrate, for example, first to Kth metal layers, may be used as wires, signal wires, and/or power wires for interconnecting elements in the TSV macro array TM_ARY'', and some of upper metal layers, for example, (K+1)th to Mth metal layers, may be used as metal wires MR (K is a natural number greater than 0 and less than M). In this example, the metal wires MR may electrically connect components inside the logic die to each other. For example, the metal wires MR may be used as wires for transmitting clock, power, and/or data between the memory controllers 110a and 110b, the CPU 130a, and/or the GPU 130b of FIG. 3A or 3B.

[0069] FIG. 4 illustrates that the metal wires MR are disposed above the TSV macro array TM_ARY'' in the vertical direction VD, but examples are not limited thereto. In some implementations, the metal wires MR may be arranged adjacent to the TSV macro array TM_ARY'' in the horizontal direction. As described above, the metal wires MR may be positioned in various ways regardless of the arrangement of the TSV macro array TM_ARY''.

[0070] FIG. 5A illustrates an example of an HBM system 30A.

[0071] Referring to FIG. 5A, the HBM system 30A may include an SoC 310 and an HBM 320, and the HBM 320 may include a base die (or B-DIE) 321 and a plurality of core dies (or C-DIE) 322 arranged on the base die 321. In this example, the SoC 310 and the HBM 320 may be mounted on an interposer 330. The SoC 310 may include a controller 311 and a physical region (or PHY) 312, and the controller 311 and the physical region 312 may communicate commands/addresses and data according to a controller interface I/F_C, such as a DDR PHY Interface (DFI). The physical region 312 may communicate with a physical region 321a provided in the base die 321 of the HBM 320 via the interposer 330. For example, the SoC 310 and the HBM 320 may communicate commands/addresses and data via the interposer 330 on the basis of high-speed communication according to the Joint Electron Device Engineering Council (JEDEC) interface.

[0072] FIG. 5B illustrates an example of an HBM device 30B.

[0073] Referring to FIG. 5B, the HBM device 30B may include a logic die 340 and a plurality of core dies 322. For example, the HBM device 30B may correspond to the semiconductor device 10 of FIG. 1 or the semiconductor device 20 of FIG. 2, and the descriptions given above with reference to FIGS. 1 to 4 may be applied to this example.

[0074] The logic die 340 may include an HBM controller 341 and an HBM physical region 342. The HBM controller 341 and the HBM physical region 342 may communicate commands/addresses and data according to the controller interface I/F_C, such as DFI. The plurality of core dies 322 may be stacked on the logic die 340, and thus, the HBM physical region 342 may be referred to as a 3D HBM PHY region. The HBM controller 341 may correspond to the memory controller 110 of FIG. 1, and the HBM physical region 342 may correspond to the interface circuit 120 of FIG. 1.

[0075] Unlike FIG. 5A, the HBM device 30B may not include the SoC 310, the interposer 330, and the base die 321. The HBM physical region 342 may perform the functions of the physical region 312 of the SoC 310, the interposer 330, and the physical region 321a in the base die 321 of the HBM 320 of FIG. 5A. Therefore, there is no need to perform high-speed communication based on the JEDEC interface via an interposer when transmitting commands/addresses and data from the HBM controller 341 to the plurality of core dies 322.

[0076] Accordingly, the HBM physical region 342 of the logic die 340 may include an interface circuit (e.g., interface circuit 120 in FIG. 1), and the interface circuit may support direct interfacing between the HBM controller 341 and the core dies 322 via TSVs and/or TBVs. Specifically, as the HBM physical region 342 of the logic die 340 communicates with the core dies 322 via the TSVs and/or TBVs, the HBM physical region 342 of the logic die 340 may include a TSV input/output (I/O) circuit 343. The TSV I/O circuit 343 may change the voltage level of signals transmitted and received via the TSVs and/or TBVs between the voltage level according to the voltage domain of the logic die 340 and the voltage level according to the voltage domain of the core dies 322. Accordingly, the TSV I/O circuit 343 may be referred to as a level shifting TSV I/O circuit (or level shifting TSV_I/O).

[0077] FIG. 6 is a block diagram schematically showing an example of a first TSV macro TM1.

[0078] Referring to FIGS. 1 and 6 together, the first TSV macro TM1 may be connected to a first TSV TSV1, and the first TSV TSV1 may correspond to a TSV through which a signal transmitted from the logic die 100 is delivered to the memory die 200. For example, a signal transmitted from the logic die 100 to the memory die 200 may include column/row address CA/RA. In this example, the first TSV TSV1 may correspond to TSV_CA/RA through which the column/row address CA/RA is transmitted.

[0079] The first TSV macro TM1 may receive write data WD, a controller clock CLK_0 according to the first clock domain of the memory controller 110, and a memory clock CLK_*_MEM according to the second clock domain of the memory die 200. The first TSV macro TM1 may perform signal processing on the write data WD in order to transmit the write data WD to the memory die 200 via the first TSV TSV1. In some implementations, the first TSV macro TM1 may

include a synchronization circuit **410** and a TSV I/O circuit (or TSV_I/O) **420a**.

[0080] The synchronization circuit **410** may synchronize the write data WD received from the memory controller **110** with the memory clock CLK_*_MEM according to the second clock domain of the memory die **200** and thus generate a synchronized signal, for example a synchronized write data WD'. The TSV I/O circuit **420a** may include a level shifter **421a** and a transmitter **422a**. The level shifter **421a** may change the voltage level of the synchronized signal, for example, the write data WD' synchronized with the memory clock CLK_*_MEM, from the first voltage level in the first voltage domain of the memory controller **110** to the second voltage level in the second voltage domain of the memory die **200**. However, examples are not limited thereto, and the TSV I/O circuit **420a** may not include the level shifter **421a**.

[0081] In some implementations, the level shifter **421a** may be referred to as a logic level shifter or voltage level translation and defined as a circuit used to translate a signal from one logic level or voltage domain to another logic level or voltage domain. The compatibility between integrated circuits having different voltage requirements is allowed by using the level shifter **421a**. The transmitter **422a** may output write data having a changed voltage level to the first TSV TSV1.

[0082] FIG. 7 is a block diagram showing an example of a first TSV macro **40a**. FIGS. 8A to 8D are timing charts illustrating the operation of the first TSV macro **40a** of FIG. 7.

[0083] Referring to FIGS. 1 and 7 to 8D together, the first TSV macro **40a** may include flip-flops **411** and **412**, a delay control logic **430a**, and a TSV I/O circuit **420a**. The first TSV macro **40a** may correspond to an example of the first TSV macro TM1 of FIG. 6, and the descriptions given above with reference to FIG. 6 may be applied to this example. For example, the flip-flops **411** and **412** may correspond to the synchronization circuit **410** of FIG. 6. For example, the flip-flops **411** and **412** may include D flip-flops. For example, the first TSV TSV1 may correspond to the TSV through which the column/row address CA/RA transmitted from the logic die **100** is delivered to the memory die **200**, that is, the TSV_CA/RA.

[0084] The flip-flop **411** may receive write data WD from the memory controller **110**, receive a controller clock CLK_0 via a clock terminal, and output a first signal Q0. For example, the write data WD received by the flip-flop **411** may correspond to the column/row address CA/RA. The flip-flop **412** may receive the first signal Q0 from the flip-flop **411**, receive a memory clock CLK_*_MEM via a clock terminal, and output a second signal Q1. In this example, the flip-flop **412** may output the second signal Q1 by synchronizing the first signal Q0 with the memory clock CLK_*_MEM.

[0085] For example, the flip-flop **411** may output the first signal Q0 by latching the write data WD at the rising edge of the controller clock CLK_0. The flip-flop **412** may output the second signal Q1 by latching the first signal Q0 at the rising edge of a memory clock CLK_0_MEM. In this example, the phase difference between the controller clock CLK_0 and the memory clock CLK_*_MEM may vary. For example, in FIG. 8A, the memory clock CLK_0_MEM may have the same phase clock as the controller clock CLK_0. For example, in FIG. 8B, a memory clock CLK_90_MEM may have a phase difference of 90 degrees from the controller clock CLK_0. For example, in FIG. 8C, a memory clock CLK_180_MEM may have a phase difference of 180 degrees from the controller clock CLK_0. For example, in FIG. 8D, a memory clock CLK_270_MEM may have a phase difference of 270 degrees from the controller clock CLK_0.

[0086] The delay control logic **430a** may be located between the flip-flop **412** and the level shifter **421a** and include at least one delay element. The delay control logic **430a** may receive the second signal Q1 from the flip-flop **412** and generate a delayed signal by delaying the second signal Q1 for a certain period of time. The delay control logic **430a** may be configured in various ways, which are described below with reference to FIGS. 16A to 16E. In some implementations, the first TSV macro **40a** may not include the delay control logic **430a** and may not include at least one delay element.

[0087] The level shifter **421a** may receive the delayed signal from the delay control logic **430a** and

change the signal level of the delayed signal from a first voltage level in the first voltage domain of the memory controller **110** to a second voltage level in the second voltage domain of the memory die **200a**. The transmitter **422a** may transmit an output signal having a changed voltage level to the first TSV TSV1.

[0088] FIG. **9** is a block diagram schematically showing a second TSV macro TM2.

[0089] Referring to FIGS. **1** and **9** together, the second TSV macro TM2 may be connected to a second TSV TSV2, and the second TSV TSV2 may correspond to a TSV through which the data DQ transmitted and received between the logic die **100** and the memory die **200** is delivered. For example, the data DQ transmitted from the logic die **100** to the memory die **200** may include write data and the data DQ transmitted from the memory die **200** to the logic die **100** may include read data. In this example, the second TSV TSV2 may correspond to TSV_DQ through which the data DQ is transmitted.

[0090] The second TSV macro TM2 may be used as a write path for the data DQ and a read path for the data DQ. In some implementations, the second TSV macro TM2 may include a serializer circuit **440**, a deserializer circuit **450**, and a TSV I/O circuit **420b**. The TSV I/O circuit **420b** may include a level shifter **421b**, a transmitter **422b**, and a receiver (or RX) **423b**. However, examples are not limited thereto, and the TSV I/O circuit **420b** may not include the level shifter **421a**. When the second TSV macro TM2 is used as a write path for data DQ, the data DQ may be output to the second TSV TSV2 via the serializer circuit **440** and the TSV I/O circuit **420b**, and the serializer circuit **440** may be referred to as a “write path.” When the second TSV macro TM2 is used as a read path for data DQ, the data DQ received via the second TSV TSV2 may be output via the TSV I/O circuit **420b** and the deserializer circuit **450**, and the deserializer circuit **450** may be referred to as a “read path.”

[0091] When the second TSV macro TM2 is used as the write path for the data DQ, the second TSV macro TM2 may receive first and second write data WD0 and WD1, a controller clock CLK_0 according to the first clock domain of the memory controller **110**, and a memory clock CLK_0_MEM according to the second clock domain of the memory die **200** and may output the data DQ. The serializer circuit **440** may synchronize the first and second write data WD0 and WD1 received from the memory controller **110** with the memory clock CLK_0_MEM according to the second clock domain of the memory die **200** and generate serial write data WD_S from data synchronized with the memory clock CLK_0_MEM. The TSV I/O circuit **420b** may change the voltage level of the serial write data WD_S from the first voltage level in the first voltage domain of the memory controller **110** to the second voltage level in the second voltage domain of the memory die **200** and may output the data DQ that is to be transmitted to the memory die **200**.

[0092] When the second TSV macro TM2 is used as the read path for the data DQ, the second TSV macro TM2 may receive the data DQ, a controller clock CLK_0 according to the first clock domain of the memory controller **110**, and memory read clocks CRCK_0_MEM and CRCK_180_MEM according to the second clock domain of the memory die **200** and may output first and second read data RD0 and RD1. In this example, the memory read clocks CRCK_0_MEM and CRCK_180_MEM may correspond to an output signal of the fourth TSV macro (e.g., fourth TSV macro **40d** in FIG. **15**). The TSV I/O circuit **420b** (e.g., the receiver **423b**) may output read data RD from the data DQ received from the memory die **200** via the second TSV TSV2. In one example, the TSV I/O circuit **420b** may change the voltage level of the data DQ received from the receiver **423b** from the second voltage level in the second voltage domain of the memory die **200** to the first voltage level in the first voltage domain of the memory controller **110** and may output the read data RD that is to be transmitted to the deserializer circuit **450**. The deserializer circuit **450** may deserialize the read data RD on the basis of memory read clocks CRCK_0_MEM and CRCK_180_MEM and may output the first and second read data RD0 and RD1 by synchronizing the deserialized read data with the controller clock CLK_0.

[0093] FIG. **10** is a block diagram showing a second TSV macro **40b**. FIG. **11A** is a timing chart

illustrating the operation of the second TSV macro **40b** of FIG. **10** when the second TSV macro **40b** of FIG. **10** is used as a write path. FIG. **11B** is a timing chart illustrating the operation of the second TSV macro **40b** of FIG. **10** when the second TSV macro **40b** of FIG. **10** is used as a read path.

[0094] Referring to FIGS. **1** and **10** to **11B** together, the second TSV macro **40b** may include flip-flops **441a** and **441b**, a serializer (SER) **442**, a delay control logic **430b**, a TSV I/O circuit **420b**, flip-flops **451a** and **451b**, a first-in-first-out (FIFO) **452**, and a deserializer (DES) **453**. The second TSV macro **40b** may correspond to an example of the second TSV macro TM2 of FIG. **9**, and the descriptions given above with reference to FIG. **9** may be applied to this example. For example, the flip-flops **441a** and **441b** and the SER **442** may correspond to the serializer circuit **440** of FIG. **9**. For example, the flip-flops **451a** and **451b**, the FIFO **452**, and the DES **453** may correspond to the deserializer circuit **450** of FIG. **9**. For example, the second TSV TSV2 may correspond to a TSV through which data DQ transmitted and received between the logic die **100** and the memory die **200** is delivered, that is, TSV_DQ.

[0095] First, the operation of the second TSV macro **40b** is described when the second TSV macro **40b** is used as a write path for data DQ. The flip-flop **441a** may receive first write data WD0 from the memory controller **110**, receive a controller clock CLK_0 via a clock terminal, and output a first signal Q0_a. The flip-flop **441b** may receive second write data WD1 from the memory controller **110**, receive the controller clock CLK_0 via a clock terminal, and output a second signal Q1_a. For example, the flip-flop **441a** may output the first signal Q0_a by latching the first write data WD0 at the rising edge of the controller clock CLK_0 and the flip-flop **441b** may output the second signal Q1_a by latching the second write data WD1 at the rising edge of the controller clock CLK_0.

[0096] The SER **442** may generate serial data WD_S synchronized with the memory clock CLK_0_MEM from the first and second signals Q0_a and Q1_a. For example, the SER **442** may generate the serial data WD_S by latching the first signal Q0_a at the rising edge of the memory clock CLK_0_MEM and latching the second signal Q1_a at the falling edge of the memory clock CLK_0_MEM. The delay control logic **430b** may receive the serial data WD_S from the SER **442**, delay the serial data WD_S for a certain period of time, and generate the delayed serial data. In some implementations, the second TSV macro **40b** may not include the delay control logic **430b** and may not include at least one delay element.

[0097] The level shifter **421b** may receive the delayed serial data from the delay control logic **430b** and change the signal level of the delayed serial data from a first voltage level in the first voltage domain of the memory controller **110** to a second voltage level in the second voltage domain of the memory die **200**. The transmitter **422b** may be connected to the level shifter **421b** and may transmit the data DQ to the second TSV TSV2.

[0098] Next, the operation of the second TSV macro **40b** is described when the second TSV macro **40b** is used as a read path for data DQ. The TSV I/O circuit **420b** (e.g., the receiver **423b**) may receive data DQ via the second TSV TSV2. In one example, the level shifter **421b** may change the signal level of the data received from receiver **423b** from the second voltage level in the second voltage domain of the memory die **200** to the first voltage level in the first voltage domain of the memory controller **110** so as to output the data DQ. The delay control logic **430b** may output read data RD by delaying the data for a certain period of time. The DES **453** may generate first and second data DES_0 and DES_1 in parallel from the read data RD on the basis of memory read clocks CRCK_0_MEM and CRCK_180_MEM. For example, the DES **453** may generate the first data DES_0 by latching the read data RD at the rising edge of the memory read clock CRCK_0_MEM and generate the second data DES_1 by latching the read data RD at the rising edge of the memory read clock CRCK_180_MEM.

[0099] The second TSV macro **40b** may further include an inverter chain **454** in which a plurality of inverters are connected to each other in series. The inverter chain **454** may delay the memory

read clock CRCK_180_MEM by a delay time (Td) and output the delayed memory read clock CRCK_180_MEM_D. The FIFO 452 may output the first and second data FIFO_0 and FIFO_1 by buffering the first and second data DES_0 and DES_1 on the basis of the delayed memory read clock CRCK_180_MEM_D. For example, the FIFO 452 may output the first and second data FIFO_0 and FIFO_1 after a certain period of time (tfifo_delay), and thus, the read data may be output without loss of clock cycles.

[0100] The flip-flop 451a may receive the first data FIFO_0 from the FIFO 452 and receive the controller clock CLK_0 via a clock terminal. The flip-flop 451b may receive the second data FIFO_1 from the FIFO 452 and receive the controller clock CLK_0 via a clock terminal. For example, the flip-flop 451a may output first read data RD0 by latching the first data FIFO_0 at the rising edge of the controller clock CLK_0 and the flip-flop 451b may output second read data RD1 by latching the second data FIFO_1 at the rising edge of the controller clock CLK_0.

[0101] FIG. 12 is a block diagram schematically showing a third TSV macro TM3.

[0102] Referring to FIGS. 1 and 12 together, the third TSV macro TM3 may be connected to a third TSV TSV3, and the third TSV TSV3 may correspond to a TSV through which a signal transmitted from the logic die 100 is delivered to the memory die 200. For example, a signal transmitted from the logic die 100 to the memory die 200 may include a clock signal CK. In this example, the third TSV TSV3 may correspond to TSV_CK through which the clock signal CK is transmitted.

[0103] The third TSV macro TM3 may receive first and second write data WD0 and WD1, a controller clock CLK_0 according to the first clock domain of the memory controller 110, and a memory clock CLK_*_MEM according to the second clock domain of the memory die 200. For example, the first and second write data WD0 and WD1 may include a data pattern for generating the clock signal CK. In this example, the third TSV macro TM3 may generate the clock signal CK. In some implementations, the third TSV macro TM3 may include a serializer circuit 460 and a TSV I/O circuit 420c, and the TSV I/O circuit 420c may include a level shifter 421c and a transmitter 422c. However, examples are not limited thereto, and the TSV I/O circuit 420c may not include the level shifter 421a.

[0104] The serializer circuit 460 may generate a clock signal CKa from the first and second write data WD0 and WD1 received in parallel from the memory controller 110 on the basis of the memory clock CLK_*_MEM according to the second clock domain of the memory die 200. The level shifter 421c may change the voltage level of the clock signal CKa from a first voltage level in the first voltage domain of the memory controller 110 to a second voltage level in the second voltage domain of the memory die 200. The transmitter 422c may output the clock signal having a changed voltage level to the third TSV TSV3.

[0105] FIG. 13 is a block diagram showing a third TSV macro 40c. FIGS. 14A to 14D are timing charts illustrating an example of the operation of the third TSV macro 40c of FIG. 13.

[0106] Referring to FIGS. 1 and 13 to 14D together, the third TSV macro 40c may include flip-flops 461a and 461b, a SER 462, a delay control logic 430c, and a TSV I/O circuit 420c. The third TSV macro 40c may correspond to an example of the third TSV macro TM3 of FIG. 12, and the descriptions given above with reference to FIG. 12 may be applied to this example. For example, the flip-flops 461a and 461b and the SER 462 may correspond to the serializer circuit 460 of FIG. 12. For example, the third TSV TSV3 may correspond to the TSV through which the clock signal CK transmitted from the logic die 100 is delivered to the memory die 200, e.g., TSV TSV_CK.

[0107] The flip-flop 461a may receive first write data WD0 from the memory controller 110, receive a controller clock CLK_0 via a clock terminal, and output a first signal Q0_b. The flip-flop 461b may receive second write data WD1 from the memory controller 110, receive the controller clock CLK_0 via a clock terminal, and output a second signal Q1_b. For example, the first write data WD0 received by the flip-flop 461a may include a data pattern having a logic high level for a certain period, and the second write data WD1 received by the flip-flop 461b may include a data pattern having a logic low level. For example, the flip-flop 461a may output the first signal Q0_b

by latching the first write data WD0 at the rising edge of the controller clock CLK_0. The flip-flop **461b** may output the second signal Q1_b by latching the second write data WD1 at the rising edge of the controller clock CLK_0.

[0108] The SER **462** may generate the clock signal CKa synchronized with a memory clock CLK_*_MEM from the first and second signals Q0_b and Q1_b. For example, the SER **462** may generate the clock signal CKa by latching the first signal Q0_b at the rising edge of the memory clock CLK_*_MEM and latching the second signal Q1_b at the falling edge of the memory clock CLK_*_MEM. The delay control logic **430c** may receive the clock signal CKa from the SER **462** and delay the clock signal CKa for a certain period of time. In some implementations, the third TSV macro **40c** may not include the delay control logic **430c** and may not include at least one delay element.

[0109] In this example, the phase difference between the controller clock CLK_0 and the memory clock CLK_*_MEM may vary. For example, in FIG. **14A**, the memory clock CLK_0_MEM may have the same phase clock as the controller clock CLK_0. For example, in FIG. **14B**, a memory clock CLK_90_MEM may have a phase difference of 90 degrees from the controller clock CLK_0. For example, in FIG. **14C**, a memory clock CLK_180_MEM may have a phase difference of 180 degrees from the controller clock CLK_0. For example, in FIG. **14D**, a memory clock CLK_270_MEM may have a phase difference of 270 degrees from the controller clock CLK_0.

[0110] The level shifter **421c** may change the voltage level of the clock signal, which is received from the delay control logic **430c**, from a first voltage level in the first voltage domain of the memory controller **110** to a second voltage level in the second voltage domain of the memory die **200a**. The transmitter **422c** may output the clock signal CK having a changed voltage level to the third TSV TSV3. For example, the clock signal CK transmitted via the third TSV TSV3 may include a memory clock CLK_MEM, a memory write clock WCK, and/or a memory read clock BRCK. For example, the memory clock CLK_MEM may include a clock signal that always toggles, and the memory write clock WCK and the memory read clock BRCK may include a clock signal that toggles only in a specific period. For example, the memory write clock WCK may include a clock signal that toggles only in a write period, and the memory read clock BRCK may include a clock signal that toggles in a read period.

[0111] FIG. **15** is a block diagram showing a fourth TSV macro **40d**.

[0112] Referring to FIGS. **1** and **15** together, the fourth TSV macro **40d** may be connected to a fourth TSV TSV4, and the fourth TSV TSV4 may correspond to a TSV through which a signal transmitted from the memory die **200** is delivered to the logic die **100**. For example, the signal transmitted from the memory die **200** to the logic die **100** may include a read clock signal CRCK. For example, the read clock signal CRCK may correspond to a clock signal used during a read operation in the memory die **200**. In this example, the fourth TSV TSV4 may correspond to TSV_CRCK through which the read clock signal CRCK is transmitted.

[0113] In some implementations, the fourth TSV macro **40d** may include a TSV I/O circuit **420d** and a delay control logic **430d**, and the TSV I/O circuit **420d** may include a receiver **421d**. The receiver **421d** may receive the read clock signal CRCK via the fourth TSV TSV4. The delay control logic **430d** may output a memory read clock signal CRCK_*_MEM by delaying the read clock signal CRCK for a certain period of time. For example, the memory read clock signal CRCK_*_MEM may be applied to the second TSV macro TM2 (e.g., **40b** in FIG. **10**).

[0114] FIGS. **16A** to **16E** each show an example of delay control logic.

[0115] Referring to FIG. **16A**, a delay control logic **50a** may include a delay line **510** only in a write path. In some implementations, the delay line **510** may include a plurality of delay elements, for example, a plurality of NOT-AND (NAND) gates. The delay control logic **50a** may generate an output signal WD_OUT by delaying, for a certain period of time, a signal WD_IN received via the write path. The delay control logic **50a** may transmit a signal RD_IN received via a read path as an output signal RD_OUT without delay. For example, the delay control logic **430a** of the first TSV

macro **TM1** or **40a** and/or the delay control logic **430c** of the third TSV macro **TM3** or **40c** may be provided as the delay control logic **50a**, but examples are not limited thereto.

[0116] Referring to FIG. **16B**, the delay control logic **50b** may include a delay line **520** only in a read path. In some implementations, the delay line **520** may include a plurality of delay elements, for example, a plurality of NAND gates. The delay control logic **50b** may generate an output signal **RD_OUT** by delaying, for a certain period of time, a signal **RD_IN** received via the read path. The delay control logic **50b** may transmit a signal **WD_IN** received via a write path as an output signal **WD_OUT** without delay. For example, the delay control logic **430d** of the fourth TSV macro **TM4** or **40d** may be provided as the delay control logic **50b**, but examples are not limited thereto.

[0117] Referring to FIG. **16C**, a delay control logic **50c** may include a delay line **510** in a write path and a delay line **520** in a read path. The delay control logic **50c** may generate an output signal **WD_OUT** by delaying, for a certain period of time, a signal **WD_IN** received via the write path. The delay control logic **50c** may generate an output signal **RD_OUT** by delaying, for a certain period of time, a signal **RD_IN** received via the read path. For example, the delay control logic **430b** of the second TSV macro **TM2** or **40b** may be provided as the delay control logic **50c**, but examples are not limited thereto.

[0118] Referring to FIG. **16D**, the delay control logic **50d** may include a delay line **530** and selectors **540** and **550**, and the delay line **530** may be used for both a write path and a read path. The selectors **540** and **550** may perform a selection operation on input signals according to a read enable signal **RD_EN** activated in the read path. For example, each of the selectors **540** and **550** may include a multiplexer.

[0119] For example, the read enable signal **RD_EN** may have a logic low level during a write operation, and the selector **540** may select a signal **WD_IN** received via the write path. The delay line **530** may generate an output signal **WD_OUT** by delaying, for a certain period of time, the signal **WD_IN** output from the selector **540**. For example, the read enable signal **RD_EN** may have a logic high level during a read operation, and the selector **540** may select the signal **RD_IN** received via the read path. The delay line **530** may delay the signal **RD_IN** output from the selector **540** for a certain period of time, and the selector **550** may select and provide the output of the delay line **530** as the output signal **RD_OUT**. For example, the delay control logic **430b** of the second TSV macro **TM2** or **40b** may be provided as the delay control logic **50d**, but examples are not limited thereto.

[0120] Referring to FIG. **16E**, in some implementations, the delay control logic **50e** may not use a delay line for a write path and a read path. The delay control logic **50e** may transmit a signal **WD_IN** received via the write path as an output signal **WD_OUT** without delay. Also, the delay control logic **50e** may transmit a signal **RD_IN** received via the read path as an output signal **RD_OUT** without delay.

[0121] As described above with reference to FIGS. **16A** to **16E**, the delay control logic may be provided as various forms. For example, the delay control logic may be provided as one of the delay control logics **50a** to **50e**, depending on the size of the logic die, the available area of the TSV region, the complexity of the TSV macro logic, or the size of the space between TSVs. For example, the delay control logic **430b** of FIG. **10** may be provided as the delay control logic **50e**.

[0122] FIG. **17** illustrates an example of a TSV region **60**.

[0123] Referring to FIGS. **1** and **17** together, the TSV region **60** may correspond to a partial region of the logic die **100**, for example, may correspond to one of the TSV region **TSV_RG** of FIG. **2**, the TSV region **101** of FIG. **3A**, and the first to fourth TSV regions **101a** to **101d** of FIG. **3B**. The TSV region **60** includes a plurality of first regions **REG1**, a plurality of second regions **REG2**, a plurality of third regions **REG3**, and a plurality of fourth regions **REG4**.

[0124] A plurality of first TSV macros **TM1** may be arranged in the first regions **REG1**, and each of the first TSV macros **TM1** may be provided as the first TSV macro **40a** of FIG. **7**. A plurality of second TSV macros **TM2** may be arranged in the second regions **REG2**, and each of the second

TSV macros **TM2** may be provided as the second TSV macro **40b** of FIG. **10**. A plurality of third TSV macros **TM3** may be arranged in the third regions **REG3**, and each of the third TSV macros **TM3** may be provided as the third TSV macro **40c** of FIG. **13**. A plurality of fourth TSV macros **TM4** may be arranged in the fourth regions **REG4**, and each of the fourth TSV macros **TM4** may be provided as the fourth TSV macro **40d** of FIG. **15**.

[0125] FIGS. **18A** and **18B** each show an example of a TSV macro array.

[0126] Referring to FIGS. **18A** and **18B**, a TSV macro array **70a** may include a plurality of TSV macros **TM**, and each of the TSV macros **TM** may be connected to two TSVs spaced apart from each other in a first direction **D1**. Accordingly, each TSV macro **TM** may have a shape extending in the first direction **D1**. A TSV macro array **70b** may include a plurality of TSV macros **TM**, and each TSV macro **TM** may be connected to two TSVs spaced apart from each other in a second direction **D2**. Accordingly, each TSV macro **TM** may have a shape extending in the second direction **D2**. In this case, the size of the TSV macro array may be reduced compared to when the TSV macro is connected to one TSV.

[0127] FIGS. **19A**, **19B**, and **19C** each show an example of a TSV macro array.

[0128] Referring to FIGS. **19A** to **19C**, a TSV macro array **80a** may include a plurality of TSV macros **TM**, and each TSV macro **TM** may be connected to four TSVs. A TSV macro array **80b** may include a plurality of TSV macros **TM**, and each TSV macro **TM** may be connected to four TSVs spaced apart from each other in a first direction **D1**. Accordingly, each TSV macro **TM** may have a shape extending in the first direction **D1**. A TSV macro array **80c** may include a plurality of TSV macros **TM**, and each TSV macro **TM** may be connected to four TSVs spaced apart from each other in a second direction **D2**. Accordingly, each TSV macro **TM** may have a shape extending in the second direction **D2**. In this case, the size of the TSV macro array may be reduced compared to when the TSV macro is connected to one TSV, e.g., a single TSV, or connected to two TSVs.

[0129] As illustrated in FIGS. **18A** to **19C**, the number of TSVs arranged above the TSV macro **TM** and connected to the TSV macro **TM** may vary. In some implementations, the number of TSVs arranged above the TSV macro **TM** and connected to the TSV macro **TM** may be 8 or more. In some implementations, the number of TSVs arranged above the TSV macro **TM** and connected to the TSV macro **TM** may be an odd number, such as 3 or 5.

[0130] FIGS. **20A** to **20C** each show an example of a TSV macro array.

[0131] Referring to FIGS. **20A** to **20C**, a TSV macro array **90a** may include TSV macros **TM** and first signal processing blocks **SP1**, and each of the TSV macros **TM** may be connected to at least one TSV. Each of the first signal processing blocks **SP1** may be located between two TSV macros **TM** adjacent to each other in a first direction **D1**. A TSV macro array **90b** may include TSV macros **TM** and second signal processing blocks **SP2**, and each of the TSV macros **TM** may be connected to at least one TSV. Each of the second signal processing blocks **SP2** may be located between two TSV macros **TM** adjacent to each other in a second direction **D2**. A TSV macro array **90c** may include TSV macros **TM**, first signal processing blocks **SP1**, and second signal processing blocks **SP2**, and each of the TSV macros **TM** may be connected to at least one TSV. Each of the first signal processing blocks **SP1** may be located between two TSV macros **TM** adjacent to each other in the first direction **D1** and each of the second signal processing blocks **SP2** may be located between two TSV macros **TM** adjacent to each other in the second direction **D2**.

[0132] In some implementations, the first and second signal processing blocks **SP1** and **SP2** may be provided as soft macros. Accordingly, the first and second signal processing blocks **SP1** and **SP2** may be referred to as first and second soft macros, respectively. The first and second signal processing blocks **SP1** and **SP2** may process various signals received from the memory controller and provide these signals to the TSV macros **TM**. For example, the first and/or second signal processing blocks **SP1** and/or **SP2** may preprocess the column/row address **CA/RA** on the basis of the phase of a signal transmitted by the TSV macro **TM** and provide this signal to the TSV macro **TM**. For example, the first and/or second signal processing blocks **SP1** and/or **SP2** may provide a

delay control signal that is provided to the delay control logic in the TSV macro TM. For example, the first and/or second signal processing blocks SP1 and/or SP2 may decode information about the temperature of a memory die. For example, the first and/or second signal processing blocks SP1 and/or SP2 may perform a TSV repair function.

[0133] FIG. 21 shows an example of an HBM semiconductor device 600.

[0134] Referring to FIG. 21, the HBM semiconductor device 600 includes first and second HBMs HBM1 and HBM2 disposed on a substrate SUB. For example, the first and second HBMs HBM1 and HBM2 may be arranged on the upper surface of the substrate SUB and adjacent to each other in a first direction D1, and the first and second HBMs HBM1 and HBM2 may be electrically connected to the substrate SUB via bumps BP. A plurality of connection terminals, for example, bumps BP_a, may be disposed on the lower surface of the substrate SUB, and the substrate SUB may be electrically connected to an external device, for example, a printed circuit board (PCB), via the bumps BP_a.

[0135] The first HBM HBM1 may include a first logic die LD1 and a plurality of memory dies MD_A stacked on the first logic die LD1 in the vertical direction VD. The second HBM HBM2 may include a second logic die LD2 and a plurality of memory dies MD_B stacked on the second logic die LD2 in the vertical direction VD. For example, each of the plurality of memory dies MD_A and the plurality of memory dies MD_B may include first to fourth core dies C-DIE1 to C-DIE4. The first to fourth core dies C-DIE1 to C-DIE4 may include a plurality of channels having independent interfaces, and thus, each of the first and second HBMs HBM1 and HBM2 may have the increased bandwidth.

[0136] The first and second HBMs HBM1 and HBM2 may include logic dies according to the examples described above with reference to FIGS. 1 to 20C. Specifically, the first logic die LD1 of the first HBM HBM1 may include a memory controller MC1, an interface circuit IF1, and core logics OL1. For example, the core logics OL1 may include CPU, GPU, NPU, etc. The second logic die LD2 of the second HBM HBM2 may include a memory controller MC2, an interface circuit IF2, and interface logics OL2. For example, the interface logics OL2 may include a universal chiplet interconnect express (UCIe) module to support an interface protocol between semiconductor chips or semiconductor dies. For example, the interface circuits IF1 and IF2 may include the TSV macros illustrated in FIGS. 1 to 20C.

[0137] The first and second HBMs HBM1 and HBM2 may be used for data processing for various purposes. Also, in some implementations, the first and second HBMs HBM1 and HBM2 may be used for neural network operation. For example, the first and second HBMs HBM1 and HBM2 may perform neural network operation, on the basis of other types of models, such as convolutional neural networks (CNN), recurrent neural networks (RNN), multi-layer perceptron (MLP), deep belief networks, and restricted Boltzman machine.

[0138] FIGS. 22A and 22B show examples of HBM semiconductor devices.

[0139] Referring to FIG. 22A, an HBM semiconductor device 700A includes a logic die 710a and HBM core dies 720a. For example, the core dies 720a can be stacked on the logic die 710a. The logic die 710a may control memory operations for the core dies 720a in response to requests from an external host. For example, the external host may include a CPU, a GPU, an NPU, an APU, and/or an AP. The logic die 710a may be electrically connected to a PCB via a plurality of bumps or connection terminals, and the HBM semiconductor device 700A may be provided as a semiconductor package including a PCB. The logic die 710a may include a memory controller (or MC) 711a and an interface circuit (or I/F) 712a, and the interface circuit 712a may include the I/O blocks, the TSV circuit blocks, or the TSV macros illustrated in FIGS. 1 to 20C.

[0140] Referring to FIG. 22B, an HBM semiconductor device 700B includes a logic die 710b and HBM core dies 720b. For example, the core dies 720b can be stacked on the logic die 710b. The logic die 710b itself may perform a function as a host and thus control memory operations for the core dies 720b. Particularly, the logic die 710b may include a memory controller (or MC) 711b and

an interface circuit (or I/F) **712b**, and the interface circuit **712b** may include the I/O blocks, the TSV circuit blocks, or the TSV macros illustrated in FIGS. **1** to **20C**. Also, the logic die **710b** may perform a function as a host and thus include various processing devices, such as a GPU **713** and an NPU **714**.

[0141] FIGS. **23A** and **23B** show examples of electronic systems including HBM semiconductor devices.

[0142] Referring to FIG. **23A**, an electronic system **800A** includes one or more HBMs **810** and a host **820**. The HBMs **810** and the host **820** are mounted on an interposer **830**, and the interposer **830** equipped with the HBMs **810** and the host **820** may be mounted on a package substrate **840**. The host **820** may correspond to various semiconductor devices that request memory access.

[0143] Each of the HBMs **810** may be provided as a semiconductor device according to the examples described above, and thus, the HBM **810** may include a logic die LD and a plurality of core dies stacked on the logic die LD. In some implementations, the logic die LD may include an interface circuit **811** and a memory controller **812**, and the interface circuit **811** may include a plurality of TSV macros respectively connected to a plurality of TSVs in a TSV region. The interface circuit **811** may be configured according to the examples illustrated in FIGS. **1** to **20C**. Accordingly, each of the TSV macros may process data and/or signals transmitted and received between the logic die LD and the plurality of core dies via the corresponding TSV, thereby supporting direct interfacing between the memory controller and the plurality of core dies via the TSV.

[0144] Also, when the HBM **810** includes a direct access (DA) region, a test signal may be provided into the HBM **810** via the DA region and a conductive means (e.g., a solder ball **850**) mounted on the lower portion of the package substrate **840**. The interposer **830** may be provided in various forms, such as silicon (TSV) form, PCB form organic, and non-TSV form embedded multi-die interconnect bridge (EMIB).

[0145] Referring to FIG. **23B**, an electronic system **800B** includes one or more HBMs **810**. The HBMs **810** may be mounted on a package substrate **840**. For example, each of the HBMs **810** may autonomously function as a host. For example, each of the HBMs **810** may be provided as the HBM semiconductor device **700B** of FIG. **22B**. The logic die in each HBM **810** may be configured according to the examples illustrated in FIGS. **1** to **20C**. Accordingly, each of the TSV macros may process data and/or signals transmitted and received between the memory controller and the memory die via the corresponding TSV, thereby supporting direct interfacing between the memory controller and the plurality of core dies via the TSV.

[0146] While this disclosure contains many specific implementation details, these should not be construed as limitations on the scope of what may be claimed. Certain features that are described in this disclosure in the context of separate implementations can also be implemented in combination in a single implementation. Conversely, various features that are described in the context of a single implementation can also be implemented in multiple implementations separately or in any suitable subcombination. Moreover, although features may be described above as acting in certain combinations, one or more features from a combination can in some cases be excised from the combination, and the combination may be directed to a subcombination or variation of a subcombination.

[0147] While particular examples are shown and described with reference to the figures, it will be understood that various changes in form and details may be made therein without departing from the spirit and scope of the following claims.

Claims

1. A semiconductor device comprising: a logic die comprising a memory controller, an interface circuit, and a plurality of through silicon vias (TSVs) arranged in a TSV region, wherein the

memory controller is configured to operate in a first voltage domain; and a plurality of memory dies stacked vertically on the logic die, and connected to the plurality of TSVs, wherein the plurality of memory dies is configured to operate in a second voltage domain, wherein the interface circuit comprises a plurality of TSV circuit blocks being in the TSV region and connected to the plurality of TSVs, and wherein each of the plurality of TSV circuit blocks is configured to convert a voltage level of a signal transmitted via a corresponding TSV among the plurality of TSVs, the voltage level being configured to be converted between a first voltage level in the first voltage domain and a second voltage level in the second voltage domain.

2. The semiconductor device of claim 1, wherein each of the plurality of TSV circuit blocks comprises a TSV macro comprising a hard macro, and the interface circuit comprises a TSV macro array comprising a plurality of TSV macros arranged in an array form.

3. The semiconductor device of claim 1, wherein the logic die further comprises a metal layer configured to electrically connect components in the logic die to each other.

4. The semiconductor device of claim 1, wherein each of the plurality of TSV circuit blocks comprises: a level shifter configured to change the first voltage level of the signal transmitted via the corresponding TSV to the second voltage level; and at least one of a receiver or a transmitter, the receiver being configured to receive the signal having the second voltage level via the corresponding TSV, and the transmitter being configured to transmit the signal having the second voltage level to the plurality of memory dies via the corresponding TSV.

5. The semiconductor device of claim 1, wherein the memory controller is configured to operate in a first clock domain, wherein the plurality of memory dies is configured to operate in a second clock domain, and wherein each of the plurality of TSV circuit blocks is configured to: synchronize signals received from the plurality of memory dies with a controller clock in the first clock domain; or synchronize a signal received from the memory controller with a memory clock in the second clock domain.

6. The semiconductor device of claim 5, wherein the plurality of TSV circuit blocks comprise a first TSV macro connected to a first TSV among the plurality of TSVs, and the first TSV macro comprises: a synchronization circuit configured to generate, from a first signal received from the memory controller, a synchronized signal synchronized with the memory clock; and a level shifter configured to change a voltage level of the synchronized signal from the first voltage level to the second voltage level.

7. The semiconductor device of claim 6, wherein the first TSV macro further comprises a delay control logic comprising at least one delay element located between the synchronization circuit and the level shifter.

8. The semiconductor device of claim 6, wherein the signal received from the memory controller comprises a command or address.

9. The semiconductor device of claim 5, wherein the plurality of TSV circuit blocks comprise a second TSV macro connected to a second TSV among the plurality of TSVs, and wherein the second TSV macro comprises: a write path configured to generate, from write data received from the memory controller, first synchronized data synchronized with the memory clock; and a level shifter configured to change a voltage level of the first synchronized data from the first voltage level to the second voltage level.

10. The semiconductor device of claim 9, wherein the write data comprises first write data and second write data, wherein the first write data and the second write data are received in parallel from the memory controller, and wherein the write path is configured to generate, from the first write data and the second write data, serial write data synchronized with the memory clock as the first synchronized data.

11. The semiconductor device of claim 9, wherein the second TSV macro further comprises a read path configured to generate, from read data received via the second TSV, second synchronized data synchronized with the controller clock.

- 12.** The semiconductor device of claim 11, wherein the read path generates, from the read data, first read data and second read data in parallel, and wherein the first and second read data are synchronized with the controller clock.
- 13.** The semiconductor device of claim 11, wherein the second TSV macro further comprises a delay control logic comprising at least one delay element located between the level shifter and at least one of the write path or the read path.
- 14.** The semiconductor device of claim 5, wherein the plurality of TSV circuit blocks comprise a third TSV macro connected to a third TSV among the plurality of TSVs, and the third TSV macro comprises: a serializer circuit configured to generate, from first write data and second write data received in parallel from the memory controller, a clock signal synchronized with the memory clock; and a level shifter configured to change a voltage level of the clock signal from the first voltage level to the second voltage level.
- 15.** The semiconductor device of claim 14, wherein the third TSV macro further comprises a delay control logic comprising at least one delay element located between the serializer circuit and the level shifter.
- 16.** The semiconductor device of claim 14, wherein the third TSV macro further comprises a transmitter configured to output, to the third TSV, the clock signal having the voltage level changed by the level shifter.
- 17.** The semiconductor device of claim 5, wherein the plurality of TSV circuit blocks comprise a fourth TSV macro connected to a fourth TSV among the plurality of TSVs, and the fourth TSV macro comprises: a receiver configured to receive a read clock signal in the second clock domain from the plurality of memory dies; and a delay control logic configured to generate a memory read clock signal by delaying the read clock signal for a certain period of time.
- 18.** The semiconductor device of claim 1, wherein each of the plurality of TSV circuit blocks is connected to one TSV of the plurality of TSVs.
- 19.-21.** (canceled)
- 22.** A logic die comprising: a memory controller configured to operate in a first clock domain; a plurality of through silicon vias (TSVs) arranged in a TSV region and electrically connected to a plurality of memory dies configured to operate in a second clock domain; and an interface circuit between the memory controller and the plurality of TSVs, wherein the interface circuit comprises a plurality of TSV macros arranged, in the TSV region, in an array form and connected to the plurality of TSVs, and wherein each of the plurality of TSV macros is configured to: synchronize signals received from the plurality of memory dies with a controller clock in the first clock domain, or synchronize a signal received from the memory controller with a memory clock in the second clock domain.
- 23.-24.** (canceled)
- 25.** A logic die comprising: a memory controller configured to operate in a first voltage domain; a plurality of through silicon vias (TSVs) arranged in a TSV region and electrically connected to a plurality of memory dies configured to operate in a second voltage domain; and an interface circuit between the memory controller and the plurality of TSVs, wherein the interface circuit comprises a plurality of TSV macros arranged, in the TSV region, in an array form and connected to the plurality of TSVs, and wherein each of the plurality of TSV macros is configured to convert a voltage level of a signal, transmitted via a corresponding TSV among the plurality of TSVs, to a converted level between a first voltage level in the first voltage domain and a second voltage level in the second voltage domain.
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