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Inventor(s)	Vovos; Robert J. et al.

Arc detection for high voltage system

Abstract

Methods and systems for arc detection are described. A controller can receive a bus voltage of a direct current (DC) bus connected to an energy source. The controller can determine whether the received bus voltage is less than a bus voltage threshold. The controller can, in response to determining the received bus voltage being less than the bus voltage threshold, determine an occurrence of an arc event in an apparatus that includes the DC bus and the energy source.

Inventors:	Vovos; Robert J. (Vestal, NY), Dupuy; James A. (Endicott, NY)
Applicant:	BAE Systems Controls Inc. (Endicott, NY)
Family ID:	1000008763227
Assignee:	BAE Systems Controls Inc. (Endicott, NY)
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Primary Examiner: Barnie; Rexford N

Assistant Examiner: Clark; Christopher J

Attorney, Agent or Firm: Scully Scott Murphy & Presser PC

Background/Summary

BACKGROUND

- (1) The present application relates to systems and methods for arc detection in high voltage apparatus that includes energy storage systems.
- (2) Arc events can be occurrences of electrical arcing in electronic systems. Electrical arcing can occur when a discharge of electricity is produced during an electrical breakdown of gases within the air, and this discharge can be continuous. In an example, when a current's intended path becomes disrupted, the current can travel between two points, either from one conductor to another, or to a grounded object nearby, creating an electrical arc. This conduction of electrical current can be uncontrolled and thus causes various hazardous risks and damages to both humans and hardware components in the electronic system.

SUMMARY

- (3) In one embodiment, a method for arc detection is generally described. The method can include receiving a bus voltage of a direct current (DC) bus connected to an energy source. The method can further include determining whether the received bus voltage is less than a bus voltage threshold. The method can further include, in response to determining the received bus voltage being less than the bus voltage threshold, determining an occurrence of an arc event in an apparatus that includes the DC bus and the energy source.
- (4) In one embodiment, an apparatus for arc detection is generally described. The apparatus can

include an energy source, a controller, and a direct current (DC) bus connected to the energy source and the controller. The controller can be configured to receive a bus voltage of the DC bus. The controller can be further configured to determine whether the received bus voltage is less than a bus voltage threshold. The controller can be further configured to, in response to a determination that the received bus voltage is less than the bus voltage threshold, determine an occurrence of an arc event in the apparatus that includes the DC bus and the energy source.

(5) In one embodiment, a controller for arc detection is generally described. The controller can include a memory and a processor. The memory can be configured to store measurements of a bus voltage of a direct current (DC) bus connected to an energy source. The processor can be configured to receive a bus voltage of the DC bus. The processor can be further configured to generate a bus voltage threshold based on the stored measurements of the bus voltage. The processor can be further configured to determine whether the received bus voltage is less than a bus voltage threshold. The processor can be further configured to, in response to a determination that the received bus voltage being less than the bus voltage threshold, determine an occurrence of an arc event in an apparatus that includes the DC bus and the energy source.

(6) Further features as well as the structure and operation of various embodiments are described in detail below with reference to the accompanying drawings. In the drawings, like reference numbers indicate identical or functionally similar elements.

Description

BRIEF DESCRIPTION OF THE DRAWINGS

(1) FIG. 1 illustrates an example system that can implement arc detection in high voltage systems in one embodiment.

(2) FIG. 2 illustrates an example of an arc detector in one embodiment.

(3) FIG. 3 illustrates a flow diagram for performing arc detection in high voltage systems in one embodiment.

(4) FIG. 4 illustrates a schematic of an example computer or processing system that may implement a system in one embodiment.

DETAILED DESCRIPTION

(5) FIG. 1 illustrates an example apparatus that can implement arc detection in high voltage systems in one embodiment. An apparatus **100** shown FIG. 1. Apparatus **100** can be, for example, a vehicle (e.g., fuel cell vehicle, hybrid electric vehicle, plug-in hybrid electric vehicle, all-electric vehicle), an aircraft, domestic or commercial appliances, or other types of equipment or machinery that utilizes a high-voltage platform (e.g., including components that required relatively high voltage energy, such as more than 60 volts (V) to operate). Apparatus **100** can include at least an energy storage system **102**, an engine **104**, an energy source **106**, a power distribution circuit **110**, and a controller **114**. Engine **104** can include a generator **111** and an inverter **112**. Energy source **106** can include a DC-DC converter **108**.

(6) Energy storage system **102** can be configured to store energy that are required for powering components of apparatus **100**. In one or more embodiments, energy storage system **102** can be embodied as a multi-cell lithium ion or other suitable battery pack. A high-voltage direct current (HVDC) bus **130** can connect energy storage system **102** to other components, such as power distribution circuit **110**, in apparatus **100**. HVDC bus can be a bus for transmitting high voltages (e.g., greater than 60V) to components of apparatus **100** that operate on high voltages. Energy storage system **102** can provide electrical energy to a component, such as engine **104**, via power distribution circuit **110**. Engine **104** can draw DC power from power distribution circuit **110**, and can also generate DC power to be provided to power distribution circuit **110** for distribution to components of apparatus **100**.

(7) Power distribution circuit **110** can be configured to receive power or energy from energy storage system **102** and/or energy source **106**, and distribute DC power (e.g., as direct current (DC) voltage) to different components of apparatus **100**. By way of example, power distribution circuit **110** can distribute power to one or more HVDC loads **113**, such as inverters and/or converters driving components of apparatus **100** including, but not limited to, air conditioning, motor, battery chargers, or the like. Energy source **106** can be, for example, a source of energy such as a fuel cell. Generator **111** in engine **104** can be configured to convert rotational energy of engine **104** into AC voltage and inverter **112** can convert the AC voltage into DC voltage to be distributed to other components in apparatus **100**. The converted DC voltage can be provided to power distribution circuit **110** and can be applied to HVDC bus **130** which in turn provides DC voltage (and power) to components of apparatus **100**. DC-DC converter **108** in energy **106** can be used for increasing or decreasing DC power being provided by energy source **106** to a level suitable for use by different components of apparatus **100**.

(8) A communication bus **132** (labeled as Comm Bus **132** in FIG. **1**) can be a dedicated high speed bus for communicating information associated with components of apparatus **100** to controller **114**. In one embodiment, communication bus **132** can be controller area network (CAN) bus. In one embodiment, communication bus **132** can be a bus for transmitting digital signals encoding values representing physical parameters, data, information and/or messages associated with apparatus **100**.

(9) Controller **114** can include a plurality of analog and digital circuitry configured to control various hardware components and software applications of apparatus **100**. By way of example, controller **114** can be an electronic control unit (ECU) if apparatus **100** is a vehicle. Controller **114** can include one or more circuits implementing computational devices, such as processors (e.g., microprocessors) and memory devices (e.g., read only memory (ROM), random access memory (RAM), electrically-erasable programmable read only memory (EEPROM), or other memory devices). Controller **114** can further include circuitry such as may also clocks, signal generators, analog-to-digital converters (ADC), digital-to-analog converters (DAC), input/output (I/O) circuitry and devices, filters, logic gates such as AND gates, OR gates, latches, or other circuitry. Controller **114** can be programmed with logic and/or program code for executing the methods described herein. Controller **114** can be configured to connect and disconnect energy storage system **102** from HVDC bus **130**.

(10) In an aspect, in high voltage systems, an arc can be developed by various types of faults or failure conditions. These faults can include, but not limited to, capacitor failure, cable failure, power electronics failure, or other types of faults. By way of example, a fault such as an insulation breakdown can occur between positive and negative conductors. The fault can form a gap between the positive and negative conductors and an arc can be developed in the gap. If the gap is relatively large, high impedance faults can occur in the high voltage system. Further, since energy storage system **102** and/or energy source **106** can supply energy into the fault, the arc can sustain as long as energy is available from a high voltage bus such as HVDC bus **130**.

(11) In one embodiment, controller **114** can include an arc detector **120**. Arc detector **120** can be implemented by analog circuitry, digital circuitry, or a combination of analog and digital circuitry. Arc detector **120** can be configured to detect an arc event while apparatus **100** operates in a normal voltage operating range. In response to detecting an arc event, arc detector **120** can output a signal, that can be read by controller **114**, and controller **114** can disable or disconnect energy sources (e.g., energy storage system **102** and/or energy source **106**) from apparatus **100** to terminate the energy being supplied into the fault. The termination of the energy being supplied into the fault can remove the arc, prevent potential damages to apparatus **100**, and prevent hazardous risk to operators or users of apparatus **100**. In one or more embodiments, controller **114** can disconnect energy sources by, for example, defueling engine **104**, open a DC contactor, trigger a pyro-disconnect device on DC voltage, shut down a fuel cell engine, or the like.

(12) Arc detector **120** can compare a measurement of a DC bus voltage of HVDC bus **130** with a

bus voltage threshold to determine an occurrence of an arc event, and to determine whether to terminate a supply of energy by disconnecting energy storage system **1002** and/or energy source **106**. In one embodiment, the bus voltage threshold can be set to half of a previous measurement of the DC bus voltage of HVDC bus **130**. In an aspect, the bus voltage threshold can be set to half of the previous measured DC bus voltage because maximum power transfer occurs when arc voltage is half of system voltage, and the arc would tend to self-extinguish if its impedance exceeds source impedance. The comparison of a measured bus voltage with a fraction of a previous measurement of the bus voltage can allow arc detector **120** to determine whether bus voltage of HVDC bus **130** is experiencing a sudden drop. A sudden drop of the bus voltage can be an indication that there is anomaly in apparatus **100** that causes unexpected amount of power to be drawn from HVDC bus **130**. For example, an occurrence of an arc event that develops an arc can draw power from HVDC bus **130**.

(13) FIG. 2 illustrates an example of an arc detector in one embodiment. An example embodiment of arc detector **120** is shown in FIG. 2. Controller **114** can include arc detector **120**, and arc detector can include filter **202**, a multiplier **204**, a comparator **206**, one or more logic gates such as an AND gate **210**, a persistency block **212**, and one or more logic circuits such as an SR latch **214**. Arc detector **120** can receive a bus voltage of HVDC bus **130** (in FIG. 1) from communication bus **132**. In one embodiment, components of arc detector **120** can be a part of a processor **220** of controller **114**.

(14) Filter **202** can receive V_{bus} from communication bus **132**. The received bus voltage V_{bus} can be a digital value representing a measurement of V_{bus} in present time. In one embodiment, communication bus **132** can be a CAN bus such that arc detector **120** can receive V_{bus} as part of a data packet under the CAN protocol. In one embodiment, if arc detector is implemented by program code being executed by controller **114**, filter **202** can be a digital filter such as a finite impulse response (FIR) filter. In another embodiment, if arc detector **120** is implemented by analog components, filter **202** can be a low pass filter and a DAC can receive the digital value representing V_{bus} from communication bus **132** and convert V_{bus} into analog signal for the low pass filter.

(15) An output of filter **202** can be fed to a multiplier **204**. In one embodiment, filter **202** can accumulate previous measurements of V_{bus} and store the accumulated previous measurements of V_{bus} . By way of example, filter **202** can be configured to accumulate measurements of V_{bus} within a past time interval τ (e.g., 1 second, 400 millisecond, etc.). In one embodiment, filter **202** can determined and store an average of the accumulated measurements of V_{bus} within the past time interval τ . In one embodiment, filter **202** can delay the input of V_{bus} based on the previous time interval τ to implement the accumulation and storing of previous measurements of V_{bus} . The output of filter **202** being fed to multiplier **204** can be a historical or previous value within the past time interval τ , and multiplier **204** can reduce the output of filter **202** by a factor. In the example shown in FIG. 2, multiplier **204** can reduce the output of filter **202** by half (e.g., multiplied by 0.5), to generate a bus voltage threshold **205** that is half of a previous measurement of V_{bus} (or half of an average of V_{bus} in the past time interval τ). In one embodiment, filter **202** can store measurements of V_{bus} in memory **222** of controller **114**.

(16) As a result of setting T to a predetermined time interval, and based on delays that may be applied by filter **202** and multiplier **204** on V_{bus} , comparator **206** can receive V_{bus} from communication bus **132**, and can receive the bus voltage threshold **205** from multiplier **204**. Comparator **206** can compare V_{bus} with bus voltage threshold **205**. If the comparison indicates V_{bus} is greater than bus voltage threshold **205**, then arc detector **120** can determine an absence of an arc event (or occurrence of an arc event is unlikely). In response to the absence of the arc event, comparator **206** can output a logic zero to AND gate **210** and AND gate **210** will also output a zero, and apparatus **100** (in FIG. 1) can continue its operation. The implementation of filter **202** as a low pass filter can provide a history of V_{bus} to separate the present measurement of V_{bus} from the historical V_{bus} values such that the present measurement of V_{bus} can be compared with the

historical Vbus values at comparator **206**.

(17) If the comparison indicates Vbus is less than bus voltage threshold **205**, then arc detector **120** can determine a presence of an arc event (or occurrence of an arc event is likely). In response to the presence of the arc event, comparator **206** can output a logic one to AND gate **210**. AND gate **210** can also receive a connection status **208** that indicated whether one or more energy sources (e.g., energy storage system **102**, energy source **106** in FIG. 1, or other energy source) are connected to HVDC bus **130**. If connection status **208** indicate that no energy source is connected to HVDC bus **130** (e.g., connection status **208** being a logic zero), AND gate **210** can output a zero despite comparator **206** outputting a logic one. If connection status **208** indicate that at least one energy source is connected to HVDC bus **130** (e.g., connection status **208** being a logic one), AND gate **210** can output a logic one since comparator **206** also outputted a logic one.

(18) The logic one output from AND gate **210** can be provided to persistency block **212**. In one embodiment, persistency block **212** can be a circuit configured to determine whether the presence of the arc event is persistent for a certain amount of time. By way of example, arc detector **120** can receive X measurements of Vbus within one second and comparator **206** can output X binary signals within the one second. If none of the X binary signals, or a relatively small portion (e.g., below a certain percentage) of the X binary signal, indicate an absence of the arc event, then persistency block **212** can determine that any potential arc event is resolved and there may be no potential risk of damages.

(19) If all of the X binary signals, or a relatively large portion (e.g., a continuous string of logic one signals, or more than a certain percentage) of the X binary signal, indicate the presence of the arc event, then persistency block **212** can determine that the arc event is sufficiently persistent to cause potential damages. In response to persistency block **212** determining the persistency of the arc event, SR latch **214** can be set and a signal **216** can be outputted to processor **220** or controller **114**. Signal **216** can be a signal indicating a need to disconnect energy sources that are connected to HVDC bus **130** (as indicated by connection status **208**). Controller **114** or processor **220** can receive signal **216** and disconnect the energy sources connected to HVDC bus **130**. In one embodiment, controller **114** can also defuel engine **104** (in FIG. 1) in response to receiving signal **216** to prevent engine **104** from supplying power to the arc event.

(20) In an aspect, maximum energy transfer during an arc event can occur when an arc voltage is half of an open circuit voltage (Voc) of HVDC bus **130**, and weak low impedance arcs can have a voltage less than half of Voc. Therefore, the comparison of Vbus with a bus voltage of half of a previous measurement of Vbus can allow arc detector **120** to function as a high pass filter that detects whether Vbus is experiencing a sudden drop, where sudden drop can indicate an occurrence of an arc event.

(21) Arc detector **120** can be implemented in a relatively simple manner when compared to conventional techniques. For example, arc detector **120** utilized measurements of Vbus that is readily available from communication bus **132** (e.g., a CAN bus) since existing power management or distribution chips in apparatus **100** utilizes the same Vbus measurement. Arc detector **120** may not need to rely on analog measurements of current being drawn, hence avoiding a need to add physical components that may require circuit board space. Arc detector **120** is also flexible in terms of implementation, as it can be implemented as software, hardware, or a combination of software and hardware.

(22) FIG. 3 illustrates a flow diagram for performing arc detection in high voltage systems in one embodiment. The process **300** in FIG. 3 may be implemented by controller **114** as discussed above. The process **300** can include one or more operations, actions, or functions as illustrated by one or more of blocks **302**, **304** and/or **306**. Although illustrated as discrete blocks, various blocks may be divided into additional blocks, combined into fewer blocks, eliminated, performed in different order, or performed in parallel, depending on the desired implementation.

(23) Process **300** can be performed by controller **114** shown in FIG. 1 and FIG. 2. Process **300** can

begin at block **302**. At block **302**, a controller can receive a bus voltage of a direct current (DC) bus connected to an energy source. In one embodiment, the bus voltage can be received from a controller area network (CAN) bus connected to the energy source.

(24) Process **300** can proceed from block **302** to block **304**. At block **304**, the controller can determine whether the received bus voltage is less than a bus voltage threshold. In one embodiment, the bus voltage threshold can be half of a previous measurement of the bus voltage. In one embodiment, the controller can store a previous measurement of the bus voltage and set half of the previous measurement of the bus voltage as the bus voltage threshold. In one embodiment, the controller can compare the bus voltage with half of the previous measurement of the bus voltage to determine whether the bus voltage of the communication bus is less than the bus voltage threshold. In one embodiment, the controller can filter the previous measurement of the bus voltage and reduce the filtered previous measurement of the bus voltage to half of the previous measurement of the bus voltage.

(25) Process **300** can proceed from block **304** to block **306**. At block **306**, the controller can, in response to determining the received bus voltage being less than the bus voltage threshold, determine an occurrence of an arc event in an apparatus that includes the DC bus and the energy source. In one embodiment, the controller can determine a connection status of the energy source to the DC bus. In response to the determination that the received bus voltage is less than the bus voltage threshold, and in response to the connection status indicating the energy source is connected to the DC bus, the controller can disconnect the energy source from the DC bus.

(26) The flowchart and block diagrams in the Figures illustrate the architecture, functionality, and operation of possible implementations of systems, methods, and computer program products according to various embodiments of the present invention. In this regard, each block in the flowchart or block diagrams may represent a module, segment, or portion of instructions, which comprises one or more executable instructions for implementing the specified logical function(s). In some alternative implementations, the functions noted in the block may occur out of the order noted in the figures. For example, two blocks shown in succession may, in fact, be implemented substantially concurrently, or the blocks may sometimes be implemented in the reverse order, depending upon the functionality involved. It will also be noted that each block of the block diagrams and/or flowchart illustration, and combinations of blocks in the block diagrams and/or flowchart illustration, can be implemented by special purpose hardware-based systems that perform the specified functions or acts or carry out combinations of special purpose hardware and computer instructions.

(27) FIG. 4 illustrates a schematic of an example computer or processing system that may implement a system in one embodiment. The computer system is only one example of a suitable processing system and is not intended to suggest any limitation as to the scope of use or functionality of embodiments of the methodology described herein. The processing system shown may be operational with numerous other general purpose or special purpose computing system environments or configurations. Examples of well-known computing systems, environments, and/or configurations that may be suitable for use with the processing system shown in FIG. 6 may include, but are not limited to, personal computer systems, server computer systems, thin clients, thick clients, handheld or laptop devices, multiprocessor systems, microprocessor-based systems, set top boxes, programmable consumer electronics, network PCs, minicomputer systems, mainframe computer systems, and distributed cloud computing environments that include any of the above systems or devices, and the like.

(28) The computer system may be described in the general context of computer system executable instructions, such as program modules, being run by a computer system. Generally, program modules may include routines, programs, objects, components, logic, data structures, and so on that perform particular tasks or implement particular abstract data types. The computer system may be practiced in distributed cloud computing environments where tasks are performed by remote

processing devices that are linked through a communications network. In a distributed cloud computing environment, program modules may be located in both local and remote computer system storage media including memory storage devices.

(29) The components of computer system may include, but are not limited to, one or more processors or processing units **12**, a system memory **16**, and a bus **14** that couples various system components including system memory **16** to processor **12**. The processor **12** may include a module **30** that performs the methods described herein. The module **30** may be programmed into the integrated circuits of the processor **12**, or loaded from memory **16**, storage device **18**, or network **24** or combinations thereof.

(30) Bus **14** may represent one or more of any of several types of bus structures, including a memory bus or memory controller, a peripheral bus, an accelerated graphics port, and a processor or local bus using any of a variety of bus architectures. By way of example, and not limitation, such architectures include Industry Standard Architecture (ISA) bus, Micro Channel Architecture (MCA) bus, Enhanced ISA (EISA) bus, Video Electronics Standards Association (VESA) local bus, Peripheral Component Interconnects (PCI) bus, and/or other bus in vehicle computing systems such as controller area network (CAN) bus, local interconnect network (LIN) bus, FlexRay bus, or other types of bus in vehicle computing systems.

(31) Computer system may include a variety of computer system readable media. Such media may be any available media that is accessible by computer system, and it may include both volatile and non-volatile media, removable and non-removable media.

(32) System memory **16** can include computer system readable media in the form of volatile memory, such as random access memory (RAM) and/or cache memory or others. Computer system may further include other removable/non-removable, volatile/non-volatile computer system storage media. By way of example only, storage system **18** can be provided for reading from and writing to a non-removable, non-volatile magnetic media (e.g., a “hard drive”). Although not shown, a magnetic disk drive for reading from and writing to a removable, non-volatile magnetic disk (e.g., a “floppy disk”), and an optical disk drive for reading from or writing to a removable, non-volatile optical disk such as a CD-ROM, DVD-ROM or other optical media can be provided. In such instances, each can be connected to bus **14** by one or more data media interfaces.

(33) Computer system may also communicate with one or more external devices **26** such as a keyboard, a pointing device, a display **28**, etc.; one or more devices that enable a user to interact with computer system; and/or any devices (e.g., network card, modem, etc.) that enable computer system to communicate with one or more other computing devices. Such communication can occur via Input/Output (I/O) interfaces **20**.

(34) Still yet, computer system can communicate with one or more networks **24** such as a local area network (LAN), a general wide area network (WAN), and/or a public network (e.g., the Internet) via network adapter **22**. As depicted, network adapter **22** communicates with the other components of computer system via bus **14**. It should be understood that although not shown, other hardware and/or software components could be used in conjunction with computer system. Examples include, but are not limited to: microcode, device drivers, redundant processing units, external disk drive arrays, RAID systems, tape drives, and data archival storage systems, etc.

(35) The terminology used herein is for the purpose of describing particular embodiments only and is not intended to be limiting of the invention. As used herein, the singular forms “a”, “an” and “the” are intended to include the plural forms as well, unless the context clearly indicates otherwise. It will be further understood that the terms “comprises” and/or “comprising,” when used in this specification, specify the presence of stated features, integers, steps, operations, elements, and/or components, but do not preclude the presence or addition of one or more other features, integers, steps, operations, elements, components, and/or groups thereof.

(36) The corresponding structures, materials, acts, and equivalents of all means or step plus function elements, if any, in the claims below are intended to include any structure, material, or act

for performing the function in combination with other claimed elements as specifically claimed. The description of the present invention has been presented for purposes of illustration and description, but is not intended to be exhaustive or limited to the invention in the form disclosed. Many modifications and variations will be apparent to those of ordinary skill in the art without departing from the scope and spirit of the invention. The embodiment was chosen and described in order to best explain the principles of the invention and the practical application, and to enable others of ordinary skill in the art to understand the invention for various embodiments with various modifications as are suited to the particular use contemplated.

Claims

1. A method comprising: receiving a bus voltage of a direct current (DC) bus connected to an energy source; determining whether the received bus voltage is less than a bus voltage threshold; in response to determining the received bus voltage being less than the bus voltage threshold, determining an occurrence of an arc event in an apparatus that includes the DC bus and the energy source; determining a connection status of the energy source to the DC bus; and in response to determining the received bus voltage is less than the bus voltage threshold, and in response to the connection status indicating the energy source is connected to the DC bus, disconnecting the energy source from the DC bus.
2. The method of claim 1, wherein the bus voltage threshold is half of a previous measurement of the bus voltage.
3. The method of claim 1, further comprising: storing a previous measurement of the bus voltage; and setting half of the previous measurement of the bus voltage as the bus voltage threshold.
4. The method of claim 3, wherein determining whether the bus voltage of the DC bus is less than the bus voltage threshold comprises comparing the bus voltage with half of the previous measurement of the bus voltage to determine whether the bus voltage of the DC bus is less than the bus voltage threshold.
5. The method of claim 3, further comprising: filtering the previous measurement of the bus voltage; and reducing the filtered previous measurement of the bus voltage to half of the previous measurement of the bus voltage.
6. The method of claim 1, wherein the bus voltage is received from a controller area network (CAN) bus connected to the energy source.
7. An apparatus comprising: an energy source; a controller; a direct current (DC) bus connected to the energy source and the controller; the controller being configured to: receive a bus voltage of the DC bus; determine a connection status between the energy source and the DC bus; determine whether the received bus voltage is less than a bus voltage threshold; in response to a determination that the received bus voltage is less than the bus voltage threshold, determine an occurrence of an arc event in the apparatus that includes the DC bus and the energy source; and in response to the determination that the received bus voltage is less than the bus voltage threshold, and in response to the connection status indicating the energy source is connected to the DC bus, disconnect the energy source from the DC bus.
8. The apparatus of claim 7, wherein the bus voltage threshold is half of a previous measurement of the bus voltage.
9. The apparatus of claim 7, wherein the controller is configured to: store a previous measurement of the bus voltage; and set half of the previous measurement of the bus voltage as the bus voltage threshold.
10. The apparatus of claim 9, wherein the controller is configured to compare the bus voltage with half of the previous measurement of the bus voltage to determine whether the bus voltage of the DC bus is less than the bus voltage threshold.
11. The apparatus of claim 9, wherein the controller is configured to: filter the previous

measurement of the bus voltage; and reduce the filtered previous measurement of the bus voltage to half of the previous measurement of the bus voltage.

12. The apparatus of claim 7, wherein the controller is configured to receive the bus voltage from a controller area network (CAN) bus connected to the energy source.

13. A controller comprising: a memory device configured to store measurements of a bus voltage of a direct current (DC) bus connected to an energy source; a processor configured to: receive a bus voltage of the DC bus; generate a bus voltage threshold based on the stored measurements of the bus voltage; determine whether the received bus voltage is less than a bus voltage threshold; determine a connection status of the energy source to the DC bus; in response to a determination that the received bus voltage being less than the bus voltage threshold, determine an occurrence of an arc event in an apparatus that includes the DC bus and the energy source; and in response to a determination that the received bus voltage is less than the bus voltage threshold, and in response to the connection status indicating the energy source is connected to the DC bus, generate a signal to disconnect the energy source from the DC bus.

14. The controller of claim 13, wherein: the stored measurements of the bus voltage comprise measurements of the bus voltage obtained in a predetermined amount of historical time; and the bus voltage threshold is half of the stored measurements of the bus voltage obtained in a predetermined amount of historical time.

15. The controller of claim 13, wherein the processor is configured to compare the bus voltage with the bus voltage threshold to determine whether the bus voltage of the DC bus is less than the bus voltage threshold.

16. The controller of claim 13, wherein the processor is configured to: filter the stored measurements of the bus voltage; and reduce the filtered stored measurement of the bus voltage to half to generate the bus voltage threshold.

17. The controller of claim 13, wherein the bus voltage is received from a controller area network (CAN) bus connected to the energy source.
