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United States Patent	12390777
Kind Code	B2
Date of Patent	August 19, 2025
Inventor(s)	Zaouk; Rabih et al.

Computer-controlled single manufacturing system for generating individualized mixtures

Abstract

There is disclosed a computer-controlled dispenser system. The system includes a first set of repositories for fluid components suitable for combination into different mixtures, a second set of repositories for viscous components suitable for combination into different mixtures, and a dispensing nozzle where the fluid and viscous components are dispensed. The system further includes a set of valves and pumps for moving fluid and viscous components to a dispensing nozzle and a scale for measuring an amount of fluid and viscous components dispensed from the dispensing nozzle. The system enables computer control to ensure accurate output of both fluid and viscous components according to the instructions received for their creation.

Inventors:	Zaouk; Rabih (Los Angeles, CA), Napoles; Erik (Torrance, CA)
Applicant:	eSalon.com, LLC (Culver City, CA)
Family ID:	1000008767782
Assignee:	eSalon.com, LLC (Culver City, CA)
Appl. No.:	18/582599
Filed:	February 20, 2024

Prior Publication Data

Document Identifier	Publication Date
US 20240189787 A1	Jun. 13, 2024

Related U.S. Application Data

continuation parent-doc US 17486525 20210927 US 11904285 20240220 child-doc US 18582599

Publication Classification

Int. Cl.: B01F35/21 (20220101); B01F33/84 (20220101); B01F35/22 (20220101); B01F35/221 (20220101)

U.S. Cl.:

CPC B01F33/8442 (20220101); B01F33/848 (20220101); B01F35/2117 (20220101); B01F35/2202 (20220101); B01F35/2211 (20220101); B01F35/2216 (20220101);

Field of Classification Search

CPC: B01F (33/848); B01F (33/846); B01F (35/2117); B01F (33/8442)

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Primary Examiner: Niesz; Jason K

Attorney, Agent or Firm: SoCal IP Law Group LLP

Background/Summary

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RELATED APPLICATION INFORMATION

(2) This patent is a continuation of application Ser. No. 17/486,525, filed Sep. 27, 2021, now U.S. Pat. No. 11,904,285, entitled COMPUTER-CONTROLLED SINGLE MANUFACTURING SYSTEM FOR GENERATING INDIVIDUALIZED MIXTURES, the entirety of which is incorporated herein by reference.

BACKGROUND

Field

(3) This disclosure relates to fluid and viscous component manufacturing and more particularly to unique one-off manufacturing of complex components with various viscosities.

Description of the Related Art

(4) Since the advent of assembly-line manufacturing, the vast majority of consumer products have been created on uniform assembly lines or other manufacturing lines that rely upon consistently churning out identical products, one after another. The benefits of mechanized manufacture have been rampant. The cost-per-unit has gone down, the necessity of hundreds or thousands of assembly-line workers has gradually reduced, and the overall quality and uniformity of products has increased over the last one hundred years or so.

(5) One example is an automotive assembly line. Automotive assembly lines generally are tooled so as to repeatedly create a particular automobile and a particular model of that automobile many times per day over the course of often weeks of manufacturing. Even if only a different model (e.g. a 2-door vs a 4-door version of the same automobile) or sometimes even simply a different color is desired, the assembly line must be stopped and retooled for that different assembly. Modern manufacturers have worked to reduce this downtime, doing as much of the work as possible ahead of time, making associated robotics simple to swap out, and cross-training workers or having multiple lines in each plant, so that lines may be swapped out intermittently with always at least one line operating. However, even among these models, the result has been significant uniformity for the consumer.

(6) Other products are very similar. Companies that manufacture dish soap create a formula or several formulas for that dish soap. The ingredients are placed within associated vats or holding chambers, then a computer controls how much of each ingredient enters a primary mixing chamber or vat. Thereafter, the ingredients are mixed, and one-by-one the resulting dish soap is dispensed until that vat is empty. The ingredients are set, the amounts of each are set, and the dispensing of the resulting mixture is, very intentionally, identical each time. If different dish soaps are desired, the ingredients are swapped out, but the system otherwise remains the same, churning out identical dish soap under the new ingredient list and dispensing identical mixtures to many receptacles.

(7) The same holds true for virtually every other product created at any scale in modern manufacturing. Cosmetics, hair dyes, tires, electronic components, cups, clocks, shoes, paint, and other products all rely on automation for production at scale and rely upon the uniform creation of the same product over-and-over to decrease manufacturing costs, increase consistency across products and over time, and to ensure quality controls have a standard measure to match.

(8) As a result of this automation, prices have generally gone down for many consumer products (e.g. televisions) relative to consumer income. But, humans have a desire for unique products that are special to them and them alone. This has resulted in the rise of interest in hand-made goods. Etsy.com is an example of a marketplace where one-off (or nearly one-off) goods have taken hold. People seek out products and goods in online and other marketplaces that support artists and creators with a view to having a good or product that is special to themselves. As a result, the products there are non-uniform and may run out of supply. One can only knit so quickly to satisfy demand.

(9) People have attempted to tackle the desire for unique products in a number of ways. The patentee has obtained several patents somewhat related to this concept, including U.S. Pat. Nos.

8,655,744 and 8,577,750 which relate to a process for ordering and reordering unique blends of hair colorant. The patentee has also obtained U.S. Pat. No. 10,532,335 for a system for creating hair colorant. Each of these inventions in some part deals with creation of one-off cosmetic products unique to each customer. However, as the number and types of components or ingredients increases, continuing to enable this type of one-off manufacturing capability likewise increases. Problems arise that must be solved in order to create other, more complex, products.

Description

DESCRIPTION OF THE DRAWINGS

- (1) FIG. 1 is an overview of a computer-controlled single manufacturing system for generating individualized mixtures.
- (2) FIG. 2 is a block diagram of an exemplary computing device.
- (3) FIG. 3 is a functional block diagram of several components of a computer-controlled single manufacturing system for generating individualized mixtures.
- (4) FIG. 4 is a side view of an example chambered reciprocating pump.
- (5) FIG. 5 is a flowchart for a process for computer-controlled generation of individualized mixtures using a system for computer-controlled single manufacturing.
- (6) FIG. 6 is a flowchart of a process for continuously and dynamically recalibrating pump and valve operation in a computer-controlled single manufacturing system for generating individualized mixtures.
- (7) FIG. 7 is a flowchart of a process for predictive overshoot compensation in operation of pumps in a computer-controlled single manufacturing system for generating individualized mixtures.
- (8) Throughout this description, elements appearing in figures are assigned three-digit reference designators, where the most significant digit is the figure number and the two least significant digits are specific to the element. An element that is not described in conjunction with a figure may be presumed to have the same characteristics and function as a previously-described element having a reference designator with the same least significant digits.

DETAILED DESCRIPTION

(9) Description of Apparatus

(10) Referring now to FIG. 1, an overview of a computer-controlled single manufacturing system **100** for generating individualized mixtures is shown. The system **100** includes order input **120**, a control computer **130**, fluid repositories **140**, valves **142**, a pressure source **144**, viscous repositories **150**, pumps **152**, a dispenser **160**, a conveyor **170**, a mixing system **180**, and a shipping system **190** all interconnected by a network **110**.

(11) The network **110** is a data communications channel connecting the various components of the system **100**. The network may be or include the Internet, but more likely is at least in part a wired ethernet connection or a wireless 802.11x connection. In addition, connections to baseline components such as valves **142** and pumps **152** may merely be electrical switches with either “on” or “off” or gradients of power levels (e.g. 40% to the pumps **152**). Those communications may be transmitted as a part of the network **110** in the form of a breadboard or customized controller board that operates under the instruction of the control computer **130** to indicate “on” or “off” settings or a desired output level.

(12) The other components such as the order input **120**, dispenser **160**, conveyor **170**, mixing system **180**, and shipping system **190** may communicate directly through communication systems like USB cables or other wired connections or may be wirelessly connected through an 802.11x connection or Bluetooth® connection. Some of those components may be connected electrically for “on” and “off” directions (e.g. conveyor **170** or mixing system **180**) controlled by the control computer **130**. The network **110** may include other types of network connections such as Zigbee®

protocols, custom communication protocols, infrared communications systems, or other systems suitable for short-range communication between the various components of the system **100**.

(13) The order input **120** is a hardware or software component that accepts input of orders and/or instructions from an instruction source to begin the process of one-off manufacturing. The instruction source may be an order created by a web server on the Internet. The order input **120** may be a part of the control computer **130**, connected to the Internet to receive orders from the Internet or from another controlling server located locally to the system **100** or the control computer **130**. It may be, in whole or in part, hardware or software. The order input **120** may be a standalone server in its own right with which order placers (e.g. customers) or manufacturing operators (e.g. a company using the system **100** to fill orders for others) use for providing instructions in manufacturing. There may be a translation generated by the order input **120** from user input (e.g. a product having these characteristics) into instructions for manufacturer (e.g. the mixture must have X amount of A chemical and Y amount of B chemical) before the instructions are provided to the control computer **130**.

(14) The control computer **130** is a computing device (see FIG. 2) that operates to control the system **100** and orchestrate the functions described herein (see FIGS. 5-7). It incorporates hardware and software, the hardware to enable it to communicate using the network **110** with the various components of the system **100** and the software to instruct the components of the system **100** how to operate to generate mixtures according to the instructions provided by the order input **120**. The control computer **130** includes a number of components discussed with reference to FIG. 3 below.

(15) As used herein, the word “fluid” means liquids that have a viscosity at or near the viscosity of water at room temperature. Water has a viscosity of 1 centipoise (cps). Milk has an approximate viscosity of 3 cps. In contrast, typical motor oil has viscosities between 85 and 1,000 cps, corn syrup has an approximate viscosity of 5,000 cps, while honey has an approximate viscosity of 10,000 cps. So, as used herein, a “fluid” is a liquid having a centipoise of less than approximately 50 cps. As used herein, the word “viscous” means a liquid having a centipoise of more than 50 cps and less than 200,000 cps (slightly thicker than the approximate centipoise of room temperature sour cream).

(16) The fluid repositories **140** are repositories of fluid components to be used in mixtures as fluid is defined herein. One of the key attributes of fluid components used in the present system **100** is that they are water-like or near-water like in their viscosity. As a result, they may be transmitted through tubing as controlled by valves **142** by the mere application of pressurization to the associated tubing. That pressurization is provided by a pressure source **144**.

(17) The pressure source **144** may be an electrically powered air pump that operates to maintain pressurization within a pressurized air chamber with a known pressure per square inch (PSI). That chamber may be connected to one or more of the tubing lines joining the fluid repositories **140** to the valves **142** and ultimately to the dispenser **160**. As a result, when the valves **142** are operated to an open position as directed by the control computer **130**, the associated fluid components are transmitted at a predictable rate through the tubing to the dispenser **160** because the associated pressurization is relatively uniform as maintained by the air pump. Other pressure source **144** possibilities include air (or other gas) tanks that are periodically filled to pressurize them or air pumps that have no associated air tank and operate electrically to pressurize the tubes as directed by the control computer **130**. The valves **142** may be opened and closed with known timings, generated over time based upon experience of flow rates of the particular fluid component, to dispense a known amount out of the dispenser **160**. Examples of fluid envisioned by the present claims include alkaline agents used in creating hair dyes, water, dyes, detergent dilutes and concentrates for cleaning, and similar fluids. The valves **142** are controlled by the control computer **130**.

(18) The viscous repositories **150** store viscous components for use in creating mixtures as viscous is defined herein. The viscous components are such that they are not suitable for pressurization of

the associated tubing. Pressurization tends to “clump” viscous repositories or cause “bursts” of viscous components to pop out of the dispenser **160**. Moving viscous components through narrow tubes require repositories subjected to large pressures (30-200 psi). High pressure large repositories are complex to make and can be dangerous to operate. As a result, for the viscous repositories **150**, pumps **152** are used.

(19) The pumps **152** generally operate under known parameters (e.g., a particular pump-rate or flow-rate). However, every kind of reciprocating pump has high and low points in its pumping stroke. A stroke, as used herein, is the full cycle or a sub-cycle of a pump that demonstrates variances in throughput from beginning to end. For example, a very simple pump is a piston pump. A simple piston pump operates by pulling a piston backwards within a tight, enclosed space. While pulling backwards, with a liquid source valve open, the desired liquid is sucked into the pump. Thereafter, the input valve is closed, the exit valve is opened, and the piston is forced forward in the tight, enclosed space. As that piston moves forward, it forces the liquid out through the exit valve. These types of pumps are used in engines to pull in air and fuel mixtures, then expelled in much the same way, but they may be used for liquids as well. There are variations of these types of pumps such that strokes are reversed in operation, axles cause the piston to move, or a series of pistons continuously pump with more even output.

(20) For a piston pump, the “stroke” is from the piston being at its furthest position to a base to the closest position and back to the furthest position. So, for the piston pump stroke, the material being pumped is moved forward virtually none at all during the fill stage while it is being pulled into the chamber. But, as the bottom of the stroke is reached and the chamber is completely filled, the piston begins moving upward and material starts moving through the system. Initially, at the beginning of the upstroke, the material moves only a little. But, once the piston's full speed is reached, the fluid moves relatively uniformly throughout the stroke until the piston reaches the far end of the chamber, where the piston slows down. Thus, the stroke of a piston pump may begin with zero movement of fluid, stay there for some time while the chamber is filled, ramp up to its full throughput, stay at full throughput as the piston moves towards the far end of the chamber, ramp down to zero movement of material, and then stay there for some time while the chamber is filled. The piston pump will continue in this way throughout its operation.

(21) In contrast lobe pumps or gear pups have a series of lobes or gears that extend outward and interact with the substance to be pumped. They are designed to operate much more continuously than piston pumps, but between lobes or points of gears there is a distinct loss of power. However, because these pumps are rotary and can continuously operate, these pumps stroke from a valley of a gear or lobe to a peak of the gear or lobe and back to the valley again. They have an output that may begin with obtaining the fluid, ramping up slowly to a maximum point, then inflecting down immediately to a lower power, hitting a valley which has the least throughput, and then immediately ramp up to more power. This stroke is much more variable, but consistent as the pump has no long downtime while the pump is being filled. These types of pumps generally have strongest throughput earliest in their strokes, with that throughput dissipating over the course of the stroke.

(22) The pumps **152** may be used to pump viscous components out of the viscous repositories. Rotary pumps, piston pumps, and other types of pumps can be used. However, unlike pressurization of the fluid pipes, the use of pumps and variability of pump throughput introduces problems in terms of predicting throughput for dispensing precise amounts of constituent elements of mixtures. Ways in which to deal with those issues are discussed more fully below. The pumps **152** are controlled by the control computer **130**.

(23) As described herein, and as claimed in claim **1**, specific, unique mixtures can be obtained by channeling fluid components and viscous components along different paths using different dispensing techniques designed to take into account the different flow of each component. The differentiated dispensing mechanisms rely upon pressurization of fluid component repositories and

flow tubing along with valves to control the dispensing itself. Viscous components rely upon precisely-controlled pumps and in some cases valves as well. The differentiated paths and systems enable much more precise control on the amounts of each component dispensed, and thus enable real-time creation of unique mixtures according to desired instructions detailing components and their relative amounts to create a desired mixture.

(24) The dispenser **160** is a location where the components from the fluid repositories **140** and the viscous repositories **150** are dispensed. The dispenser **160** may be a single nozzle into which all of the tubing joining the fluid repositories **140** and viscous repositories **150** flow or it may be a series of closely arranged nozzles, one for each of the repositories **140** and **150**. The dispenser **160** may simply be a nozzle or series of nozzles, but more likely, the dispenser **160** may include various valves and may be movable so as to properly dispense constituents into receptacles (e.g. bottles or vials).

(25) In at least one embodiment, the dispenser **160** is controlled by the control computer **130** and includes at least two valves for each fluid or viscous component. The valves close to the dispenser nozzle(s) help to ensure uniform flow of the component into a receptacle. In addition, the entire dispenser **160** may be mounted on a movable platform and may employ laser or image scanners to identify or obtain order information directly from a receptacle. As discussed in U.S. Pat. No. 10,532,335, owned by the assignee of this patent, directions for creating mixtures may be printed explicitly on the exterior of bottles into which the present system **100** deposits the desired mixture. A scanner or computer imaging that is a part of the order input **120** may be used to obtain the directions and may be a part of the dispenser **160**. The dispenser's movable platform may also ensure that the nozzle for a given fluid or viscous component is properly aligned with the opening in a receptacle for dispensing.

(26) The conveyor **170** is one or more automation systems designed to ensure that a viable receptacle is obtained, placed in the dispenser **160**, and then is transferred to the mixing system **180** and shipping system **190**. The conveyor **170** is shown as a single conveyor **170**, but may be many conveyors operating in unison. The conveyor **170** is a conveyor, but may also be or include other automation systems such as arms, claws, grips, clamps, belts, levers, ramps, and the like. The word conveyor **170** is used because it is familiar. It is a series of elements that move the receptacle into position to be filled and, once filled, through to shipping. The conveyor **170** is controlled by the control computer **130**.

(27) The mixing system **180** is a system for ensuring that the mixture created by the system **100** is adequately mixed. The mixing system **180** may interact with a receptacle of a given mixture to shake it, stir it, or otherwise ensure that it is adequately mixed. One issue introduced by the use of both fluid components and viscous components is that they do not naturally mix very well. In particular, those components tend to stay separate from one another. So, the mixing system **180** can ensure uniformity of the resulting mixture after all of its constituents are added to a receptacle. The mixing system **180** may be or include a centrifuge or centrifuge like mixing area where one or more receptacles are rapidly spun around a central point, thereby forcing the viscous components in particular to merge with the fluid ones. Shaking based mixing systems, as well as tumbling based mixing systems are also possible. The mixing system **180** can be controlled by the control computer **130**.

(28) The shipping system **190** is a system for preparing and/or shipping the resulting mixtures to their recipients. The shipping system **190** may be, in whole or in part, a shipment labelling system that prints out labels and applies them to the receptacle for the mixtures, or associated shipping boxes. The shipping system **190** may place the filled receptacles into the shipping boxes (e.g. using claws or other systems) and apply the labels automatically. The shipping system **190** may be in whole or in part reliant upon humans to place the receptacles in shipping boxes, to apply shipping labels, or to otherwise prepare them for shipping. The shipping system **190** is controlled by the control computer **130**.

(29) FIG. 2 is a block diagram of an exemplary computing device **200**, which may be a part of the self-contained colorant system **120** or the server **130** of FIG. 1. As shown in FIG. 2, the computing device **200** includes a processor **210**, memory **220**, a communications interface **230**, along with storage **240**, and an input/output interface **250**. Some of these elements may or may not be present, depending on the implementation. Further, although these elements are shown independently of one another, each may, in some cases, be integrated into another.

(30) The processor **210** may be or include one or more microprocessors, microcontrollers, digital signal processors, application specific integrated circuits (ASICs), or a systems-on-a-chip (SOCs). The memory **220** may include a combination of volatile and/or non-volatile memory including read-only memory (ROM), static, dynamic, and/or magnetoresistive random access memory (SRAM, DRAM, MRAM, respectively), and nonvolatile writable memory such as flash memory.

(31) The memory **220** may store software programs and routines for execution by the processor. These stored software programs may include an operating system software. The operating system may include functions to support the input/output interface **250**, such as protocol stacks, coding/decoding, compression/decompression, and encryption/decryption. The stored software programs may include an application or “app” to cause the computing device to perform portions of the processes and functions described herein. The word “memory”, as used herein, explicitly excludes propagating waveforms and transitory signals.

(32) The communications interface **230** may include one or more wired interfaces (e.g. a universal serial bus (USB), high definition multimedia interface (HDMI)), one or more connectors for storage devices such as hard disk drives, flash drives, or proprietary storage solutions. The communications interface **230** may also include a cellular telephone network interface, a wireless local area network (LAN) interface, and/or a wireless personal area network (PAN) interface. A cellular telephone network interface may use one or more cellular data protocols. A wireless LAN interface may use the WiFi® wireless communication protocol or another wireless local area network protocol. A wireless PAN interface may use a limited-range wireless communication protocol such as Bluetooth®, Wi-Fi®, ZigBee®, or some other public or proprietary wireless personal area network protocol. The cellular telephone network interface and/or the wireless LAN interface may be used to communicate with devices external to the computing device **200**.

(33) The communications interface **230** may include radio-frequency circuits, analog circuits, digital circuits, one or more antennas, and other hardware, firmware, and software necessary for communicating with external devices. The communications interface **230** may include one or more specialized processors to perform functions such as coding/decoding, compression/decompression, and encryption/decryption as necessary for communicating with external devices using selected communications protocols. The communications interface **230** may rely on the processor **210** to perform some or all of these function in whole or in part.

(34) Storage **240** may be or include non-volatile memory such as hard disk drives, flash memory devices designed for long-term storage, writable media, and proprietary storage media, such as media designed for long-term storage of data. The word “storage”, as used herein, explicitly excludes propagating waveforms and transitory signals.

(35) The input/output interface **250**, may include a display and one or more input devices such as a touch screen, keypad, keyboard, stylus or other input devices. The processes and apparatus may be implemented with any computing device. A computing device as used herein refers to any device with a processor, memory and a storage device that may execute instructions including, but not limited to, personal computers, server computers, computing tablets, set top boxes, video game systems, personal video recorders, telephones, personal digital assistants (PDAs), portable computers, and laptop computers. These computing devices may run an operating system, including, for example, variations of the Linux, Microsoft Windows, Symbian, and Apple Mac operating systems.

(36) The techniques may be implemented with machine readable storage media in a storage device

included with or otherwise coupled or attached to a computing device **200**. That is, the software may be stored in electronic, machine readable media. These storage media include, for example, magnetic media such as hard disks, optical media such as compact disks (CD-ROM and CD-RW) and digital versatile disks (DVD and DVD+RW), flash memory cards, and other storage media. As used herein, a storage device is a device that allows for reading and/or writing to a storage medium. Storage devices include hard disk drives, DVD drives, flash memory devices, and others.

(37) FIG. **3** is a functional block diagram of several components of a computer-controlled single manufacturing system **300** for generating individualized mixtures. The system **300** includes the order input **320**, the control computer **330**, and the dispenser **360**. The components are shown separately as divided by their respective functions, but some or all may be integrated into one another.

(38) The order input **320** is the order input **120** from FIG. **1** and includes a digital reader **322** and a communications interface **324**. As discussed above, the order input **320** may be or include the Internet and/or a website for accepting orders. That order input may be processed by the communications interface **324**. In such a mode of operation, an order, including the instructions for making a particular mixture, may be transmitted over the Internet or another network (e.g. from the control computer **330**) to the order input **320**.

(39) However, preferably, the order input **320** includes a digital reader **322** that may be a barcode, QR code, RFID, NFC, or other reader or may include a digital still or motion camera or infrared camera for reading information from a receptacle such as a bottle, can, or other object into which a mixture will be placed. In one mode of operation, a barcode reader may read a label that was previously printed for the receptacle, the label containing the instructions for creating a desired mixture. To be clear, these are the instructions (e.g. the amounts and type of each component of a given mixture) as opposed to a reference to a database wherein the instructions are stored. The label stores the instructions, not any reference to any other place where instructions are stored. This is in part because the present system **300** is capable of generating virtually any unique mixture as desired or directed by such instructions because it is intended for that purpose of uniqueness, unlike mass-production of the same mixture over-and-over again.

(40) The communications interface **324** is used to communicate with the other components of the system **300**, including the control computer **330** to accept instructions on how to operate and the dispenser **360**. The communications interface **324** may be or include the Internet or other wired or wireless networks.

(41) The control computer **330** is the control computer **130** from FIG. **1** and includes a user interface **332**, a communications interface **334**, a historical data database **336**, an adaptive pump system **337**, an adaptive valve control **338**, and monitoring systems **339**. The control computer **330** controls the entire operation of the system **300**, including receipt of instructions from the order input over the communications interface **334** and operation of the valves **142** and pumps **152** to create a mixture and eventual dispensing using the dispenser **360**.

(42) The control computer **330** uses the user interface **332** to accept commands. This user interface may be a touchscreen, and the control computer **330** may be a tablet computer or may be a microcomputer, such as a personal computer, an all-in-one computer such as a Raspberry® Pi® computer, or may take many other forms. The user interface **332** may be web-based such that the user interface **332** is transmitted over the communications interface **334** to another computing device for display thereon and interaction with the control computer **330** from that other computing device. The user interface **332** accepts commands, such as resetting the device, selecting creation or recreation of a particular mixture, priming pumps or opening and closing valves to correct errors, or otherwise interacting with the entire system **300**.

(43) The communications interface **334** is used by the control computer **330** to communication with the rest of the system **300**. The communications interface **334** may be or include the Internet or other local network connectivity. The communications interface **334** may in some cases merely be a

conduit through which control of elements like valves and pumps takes place, though the communication may, in such cases, merely be to turn the pumps and valves on or off.

(44) The historical data database **336** is used to store data regarding the status of the various repositories of components of the mixtures, for example, storing their capacities, the amount that has been used since each was last filled, the speed at which each component exits through the dispenser **360**, any irregularities in the speed of exit from the dispenser **360**, weight data (as weighed by scale **366**) for historical pump actuations or valve openings and closings, any differences in the viscosity of constituents across batches or due to ambient temperatures or pressures, and any inconsistencies having to do with pump operation or differences in pressurization of the tubing connecting repositories to the dispenser **360**. The data in the historical data database **336** is continuously updated as new mixtures are created based upon output by the scale **366** and the monitoring systems **339**.

(45) The adaptive pump system **337** may rely upon data from the historical data database **336** to dynamically alter the operation of the pumps or to account for inconsistent operation of the pumps in an effort to consistently create identical or near-identical output of the various viscous components from the viscous repositories **150** through the dispenser **360**. The adaptive pump system **337** may take into account discrepancies in the constituents, the temperature, the pressure, the distance from a pump to a valve or dispenser, and/or the throughput or efficiency of operation of the pumps so as to operate the pumps intelligently to ensure accurate dispensation of each constituent of a given mixture from the dispenser **360**. Other factors may also be considered the adaptive pump system **337** attempts to aid the control computer **330** in accurately controlling the pumps **152**.

(46) The adaptive valve control **338** performs a similar function for the valves, reliant upon data from the historical data database **336**, to control the opening and closing of the valves in response to changes in density, viscosity, temperature, and/or pressurization of the fluid repositories **140**. The adaptive valve control **338** attempts to inform the control computer **330** in accurately controlling the valves **142**.

(47) The monitoring systems **339** track one or more of the amount of time each valve **142** is open, the pressurization of the associated tubing, the time during which each pump **152** runs, the various data stored in the historical data database **336**, and any newly added information provided by the scale **366** to continuously update the historical data database **336**. The data may also be weighted so that more recent data may be weighed more heavily. Different batches of the constituent components from the fluid repositories **140** and viscous repositories **150** can have different densities, viscosities, and other characteristics that change when the repositories are re-filled after use. As such, the most relevant data is the most-recent data by a far margin when determining how long to operate a pump to achieve a certain amount of output or how long to leave a valve open at a given pressurization level. The monitoring systems **339** may update the data stored and inform the control computer **330** of the status of the overall system.

(48) The dispenser **360** is the dispenser **160** from FIG. **1** and includes a nozzle **362**, a communications interface **364**, and a scale **366**. The dispenser **360** dispenses the constituent components of a given mixture as directed by the control computer **330**.

(49) The nozzle **362** is the place from which the fluid components and viscous components exit and are dispensed into a receptacle or container. The nozzle **362** may be one nozzle or may be multiple nozzles and may include flow control valves, a platform for dispensing, and a series of valves. The inventors have discovered that a movable platform on which the nozzles are placed in an experimental embodiment for purposes of aligning the nozzle **362** with a receptacle resulted in inadvertent output as the platform was moved by motor actuators (also controlled by the control computer). To counteract this movement, the platform itself is preferably equipped with one or more flow control valves per nozzle to ensure that output of components only occurs when a valve is open or a pump is activated by the control computer **330**. Otherwise, incorrect elements may

enter the containers for a particular mixture. The flow control valves may be distinct and in addition to from the valves used to control flow of pressurized fluid components. The flow control valves may only be present on or in near proximity to the nozzle **362**.

(50) A communications interface **364** enables the control computer **330** to instruct the nozzle **362**, associated motor actuators, valves, the platform, and any other elements of the dispenser **360** so as to enable creation of desired mixtures. The digital reader **322** may also be a part of the dispenser **360** in some cases. The communications interface **364** may be or include the Internet or other network connectivity with the control computer **330**.

(51) The scale **366** is preferably a digital scale in communication with the control computer **330** to accurately measure and record the output from the various repositories as directed by the control computer **330**. The control computer **330** and monitoring systems **339** can then track the output and pump actuation and update the historical data database **336** for use in later dispensing of components. In addition, the scale **366** ensures that accurate amounts of each desired constituent part are added to a given mixture as directed by the instructions and provides opportunity for correction, for example, by adding more of the other constituents so that the associated ratios of each constituent are correct.

(52) FIG. **4** is a side view of an example chambered reciprocating pump **400**. The pump **400** has several chambers **414** within its casing **412** and is designed to operate in a rotary fashion. The pump **400** has an inlet **416** and an outlet **418**. One or both may be covered by valves that operate to ensure fluid does not move backward in the pump.

(53) As the pump turns, each chamber **414** moves over the inlet **416**, fills with viscous component, then moves in a rotary fashion along to an outlet through which viscous component is pushed outward until the chamber **414** is largely empty. The use of four chambers here in this pump is exemplary, other numbers of chambers may be used.

(54) As can be seen, when the pump is “between” chambers, there is no output or low output. When the outlet **418** is mid-chamber, the output is highest. As a result, the pump **400** operates in an uneven manner. In addition, different pumps operate at different efficiencies and with different levels of output altogether. The control computer **330** (FIG. **3**) may compensate for these irregularities.

(55) Description of Processes

(56) Referring now to FIG. **5** a flowchart for a process for computer-controlled generation of individualized mixtures using a system for computer-controlled single manufacturing. The flow chart has both a start **505** and an end **595**, but the process may be cyclical in nature, taking place over and over with each new mixture for which instructions are received.

(57) Following the start **505**, instructions for creation of a mixture are received at **510**. These instructions may come in the form of a computer-readable label that is printed on or otherwise affixed to or a part of the receptacle or container into which the mixture will be dispensed. Alternatively, the instructions may come from an internet server or from a database accessible to the system **100** (FIG. **1**). The instructions are preferably complete in themselves. That is, they are not a referral to a website or other database from where the operating parameters of the system **100** and amounts of each component of a given mixture may be obtained. Instead, they are the operating parameters and/or amounts of each component necessary to create the mixture. If necessary, the instructions are also ordered, so that components may be added in the most-beneficial order for the desired mixture result.

(58) Next, using the instructions, the types and amounts of each fluid and viscous component are determined at **520**. Because the instructions describe the process and components and amounts of components to make a desired mixture, the control computer **330** (FIG. **3**) can calculate the valve and pump timing **530** using the data from historical data database **336** (FIG. **3**).

(59) For example, to create a conditioner, a viscous base may be one component that makes up_% of an eventual mixture, while two or three viscous conditioning components may make up_%,

while water may make up_% and a liquid fragrance may make up_% of the eventual mixture. Using this information and the total size of the container, the control computer **330** can calculate the timings for how long each valve should be open for the fluid components and how long a pump should run for each viscous component. This may be based upon the historical data database **336** including any irregularities tracked about the particular components and their output.

(60) First, the viscous components are output at **540**. This involves the control computer **330** instructing the associated pump(s) **152** to operate, each in turn. So, in the example above, the viscous base pump, and the two or three viscous conditioning components associated pumps would each be operated in turn. The timings for each pump (how long to operate them to reach a desired output) are controlled by the control computer **330**.

(61) Once a viscous component is output through the nozzles of the dispenser **360**, then the component is weighed at **542** using the scale **366**. This step is to ensure that the viscous component is output in a desired amount, within tolerances that may be, for example, within 5% of a desired output. In addition, the weight information may be used to update the historical data database **336**. If the amount output is too much or too little, an optional step enables adjustment (e.g. by adding more or by adjusting at **544** the overall mixture to account for more than expected of one component).

(62) If there are other viscous components to be added (“No” at **545**), then the process returns to output the next viscous component at **540**. If the viscous components have all been added (“yes” at **545**) and that process is complete, then the process turns to the fluid components. The order of dispensing is not necessarily fixed. The fluid components may be added in some cases prior to the viscous components. Or, the two component types may take turns being dispensed.

(63) The first fluid component is added at **550**. It is added after the viscous components to aid in mixing later. The valves are opened at the direction of the control computer **330** for a pre-determined time based upon the instructions.

(64) Once the fluid component is added, the overall mixture is weighed to confirm that the correct amount has been output at **552**. This information can also be used to update the historical data database **336**. If there is some unexpected output (e.g. too much or too little of a given fluid component), then mixture may be adjusted at **554**. As with the pumps, this may involve adding more of a given fluid or adding more of the overall other components to compensate for the incorrect amount. The important point is to have the relative percentages the same. As with the pumps, there may be a threshold level of inaccuracy that is acceptable (e.g. 5% or 10%).

(65) If there remain other fluids to be added (“No” at **555**), then the next fluid component is output at **550** and the process continues. If the addition of fluids is complete (“Yes” at **555**), then the process continues.

(66) Following addition of all fluid and viscous components, the overall mixture is mixed at **560**. As indicated above, this mixture process may rely upon a shaking mixer, a tumbling mixer, a centrifuge or other spinning mixer. Other mixing systems **180** are possible as well. The mixing may be partially or fully automated such that conveyers move the finished mixture from the dispenser to a mixing station where mixing takes place. Humans may be involved as necessary or helpful.

(67) Finally, after the mixture is transported through the mixing system **180**, it is labeled and prepared for shipment at **570**. This process places the mixture in a box or other shipping container for shipping. A shipping label may be applied so that it is ready to be sent to its purchaser. As the focus of this system is on one-off, unique products specific for one customer, each label is unique as each product is unique. Large batches are generally not done in this system, but single batches for one user that are shipped individually to the requesting person.

(68) The process then ends at **595**.

(69) FIG. **6** is a flowchart of a process for continuously and dynamically recalibrating pump and valve operation in a computer-controlled single manufacturing system for generating individualized mixtures. The flow chart has both a start **605** and an end **695**, but the process may be cyclical in

nature, taking place over and over with each new mixture for which instructions are received.

(70) Following the start **605**, the process begins with operation of a pump or valve at **610**. The operation is monitored by the monitoring systems **339**. This includes access to the scale **366**, so that accurate measurements of the output of a given component for the mixture may be ascertained. The resulting output for a given pump operation time or valve open time is logged.

(71) Next, it is determined whether or not the resulting output is expected, within certain parameters (e.g. a threshold level of difference may be acceptable) at **615**. If all is as expected (“Yes” at **615**), then the process ends at **695**.

(72) If all is not as expected (“No” at **615**), then the process proceeds to determine the difference at **620**. At this step, the difference between expected and actual output is noted. This may be an over-pump or over-pour or it may be an under-pump or under-pour. That difference is stored at **630** in the historical data database **336**.

(73) Next, a weighted difference is generated at **640**. If the difference is minimal or if it is an unusual occurrence, no resulting change need be made. However, if there appears to be a pattern or a growing pattern, the system may note that as well. In order to do that, it may not weight a single occurrence of an over-pour or under-pump sufficiently to update the control computer's algorithms related to pump or valve timings for a given component. Instead, it may be required that it occur several times. In some cases, a single instance may be sufficient weight to alter the pump or valve timings at least partially.

(74) A determination by the control computer **330** is made at **645** whether the threshold level of difference has been exceeded by the weighted difference calculated at **640**. The threshold level of difference may be small in some cases (e.g. 0.5%) or may be large in other mixtures or with other components such as a conditioner base (e.g. 5% or 10%).

(75) Alternatively, another adaptive dispensing method may rely upon historical data to generate dispensing model for the pumps. That model may generate an output curve (e.g. because pumps vary in their output over a given stroke) so as to enable the system to predict output from the pump given its present status and the historical curve. This enables the system to model output for each particular “run” of the pump from its starting point in a given stroke to its end point in that same stroke, based upon the volume of viscous component required. This dispensing model may rely upon a curve fit method to predict how long it should dispense this particular formula. The model may instruct the system to pause to re-evaluate itself with a margin of safety to avoid over dispensing by a large amount. This model, or any model, may be tuned to prefer under dispensing, because under dispensing is easy to recover from by simply dispensing more of a desired component.

(76) Other adaptive methods may be used, reliant upon historical data regarding the pumps and the characteristics of the viscous components.

(77) If the threshold is not exceeded (“No” at **645**), then the process ends at **695**. If it is exceeded (“Yes” at **645**), then the pump/valve operating parameters are updated at **650**. This involves updating the historical data database **336**, using the adaptive pump system **337** or adaptive valve control **338** to alter the length of time the associated pump is activated for a given amount of viscous component or the associated valve is open for a given fluid component.

(78) As this process is taking place constantly while mixtures are being made, the mixture itself—which may be for a customer—may be adjusted as well at **660**. This may involve starting over completely, or merely adding more of one or more components to make the mixture's overall ratios within desired tolerances.

(79) Because the process is continual while mixtures are being created, the process never really ends. Its only breaks are when the overall system operates as expected for desired outputs from both the fluid and viscous component repositories.

(80) FIG. 7 is a flowchart of a process for predictive overshoot compensation in operation of pumps in a computer-controlled single manufacturing system for generating individualized

mixtures. The flow chart has both a start **705** and an end **795**, but the process may be cyclical in nature, taking place over and over as an associated pump operates.

(81) Following the start **705**, the process begins with a given pump receiving an operation instruction at **710**. This may be, for example, operate for 0.7 seconds (which may be associated with a throughput of approximately 3 ounces of a viscous component of a mixture through a dispenser and into a container). However, as discussed above, pump operation is not uniform throughout the stroke.

(82) So, before the pump actuates, the control computer **330** determines the position of the pump within the pump stroke **720**. In actuality, this position may simply be noted by tracking the throughput over time in the historical data database **336**. So, the control computer **330** may be able to estimate the stroke position for all pumps at any moment, because it has recently used the pumps and noted their throughput.

(83) Based upon the stroke position (or as may be known by the control computer **330**, the throughput curve for a given pump), the pump's operation time estimate of 0.7 seconds may be adjusted at **730**. For example, if the pump's stroke just finished and it will not pump anything for 0.2 seconds, then the operation time may be extended to 0.9 seconds. If the pump is mid-stroke and its entire stroke is 3 seconds, then no adjustment may be necessary because the full 0.7 seconds falls within that stroke's middle point. If the stroke is near its start and will have more throughput early, the overall timing may be adjusted down to 0.6 seconds to account for a strong start to the throughput. All of this may be with the goal of reaching approximately 3 ounces of eventual output. Each time a pump operation is requested by the control computer **330**, this process may take place before instructing the pump how long the pump should operate.

(84) Once the adjustment is calculated, the pump is operated with the adjustment at **740**. Thereafter, this process ends at **795**.

(85) Closing Comments

(86) Throughout this description, the embodiments and examples shown should be considered as exemplars, rather than limitations on the apparatus and procedures disclosed or claimed. Although many of the examples presented herein involve specific combinations of method acts or system elements, it should be understood that those acts and those elements may be combined in other ways to accomplish the same objectives. With regard to flowcharts, additional and fewer steps may be taken, and the steps as shown may be combined or further refined to achieve the methods described herein. Acts, elements and features discussed only in connection with one embodiment are not intended to be excluded from a similar role in other embodiments.

(87) As used herein, “plurality” means two or more. As used herein, a “set” of items may include one or more of such items. As used herein, whether in the written description or the claims, the terms “comprising”, “including”, “carrying”, “having”, “containing”, “involving”, and the like are to be understood to be open-ended, i.e., to mean including but not limited to. Only the transitional phrases “consisting of” and “consisting essentially of”, respectively, are closed or semi-closed transitional phrases with respect to claims. Use of ordinal terms such as “first”, “second”, “third”, etc., in the claims to modify a claim element does not by itself connote any priority, precedence, or order of one claim element over another or the temporal order in which acts of a method are performed, but are used merely as labels to distinguish one claim element having a certain name from another element having a same name (but for use of the ordinal term) to distinguish the claim elements. As used herein, “and/or” means that the listed items are alternatives, but the alternatives also include any combination of the listed items.

Claims

1. A computer-controlled dispenser system comprising: a plurality of repositories for fluid components and viscous components suitable for combination into different mixtures; a dispensing

nozzle from which the fluid and the viscous components are dispensed; at least one set of tubing connecting the series of repositories to the dispensing nozzle; at least one valve interposed between the series of repositories and the dispensing nozzle for fluidly controlling the fluid components through the at least one set of tubing to the dispensing nozzle as controlled by opening and closing the at least one valve; at least one pump coupled to the at least one set of tubing for controlling flow of the viscous components of the series of repositories through the at least one set of tubing to the dispensing nozzle as controlled by a control computer; a scale for measuring the amount of the fluid and the viscous components dispensed from the dispensing nozzle; and wherein a control computer receives instructions to dispense the fluid and the viscous components in desired amounts to create a mixture according to the instructions, the control computer causes the at least one pump and the at least one valve to combine at least one of each of the fluid and the viscous components to create the mixture.

2. The computer-controlled dispenser system of claim 1 wherein the fluid and viscous components are measured after being dispensed using the scale to ensure that an amount required by the instructions is dispensed into a container.

3. The computer-controlled dispenser system of claim 1 wherein, when one of the fluid components or the viscous components is over-dispensed, the control computer operates to cause an additional amount of another of the fluid components and the viscous components to be dispensed to cause the mixture to be appropriately proportioned.

4. The computer-controlled dispenser system of claim 1 wherein the control computer monitors the time that the at least one valve is open and that the at least one pump, pumps and continuously operates to self-calibrate based upon an amount of the fluid components and the viscous components output by the dispensing nozzle as measured by the scale.

5. The computer-controlled dispenser system of claim 4 wherein the control computer further monitors at least one of current ambient temperature, temperature of the fluid components or the viscous components, introduction of a new batch of one of the fluid components or one of the viscous components which may alter dispensing speed, and any unique characteristics of each of the at least one valve and each of the at least one pump.

6. The computer-controlled dispenser system of claim 4 wherein the control computer specifically monitors each stroke for each of the at least one pump to predict a position within a stroke so as to selectively disengage each of the at least one pump based upon a position within the stroke to enable accurate dispensing while accommodating uneven dispensing throughout the stroke.

7. A computer-controlled dispenser system comprising: a first set of repositories for fluid components joined to at least one pressurization source for moving the fluid components to a dispensing nozzle, the fluid components suitable for combination into different mixtures; a second set of repositories for viscous components joined to at least one pump for pumping the viscous components to a dispensing nozzle, the viscous components suitable for combination into different mixtures; the dispensing nozzle where the fluid and viscous components are dispensed; at least one valve interposed between the first set of repositories and the dispensing nozzle for controlling flow of the fluid components; the at least one pump coupled to the second set of repositories for controlling the flow of the viscous components; and a control computer for controlling the at least one pump to move at least one of the viscous components through the dispensing nozzle and controlling the at least one valve to dispense at least one of the fluid components through the dispensing nozzle according to instructions for a desired mixture.

8. The computer-controlled dispenser system of claim 7 further comprising a scale for measuring an amount of the fluid components and the viscous components dispensed from the dispensing nozzle.

9. The computer-controlled dispenser system of claim 7 wherein the control computer further receives second instructions for a second desired mixture, distinct from that of the desired mixture, to be created and thereafter operates to open a second valve of the at least one valve of a set of

tubing associated with one of the first set of repositories to enable the fluid component to be dispensed from the dispensing nozzle according to the second instructions and the control computer operates to cause a second pump of the at least one pump to pump the viscous component from one of the second set of repositories to be dispensed from the dispensing nozzle according to the second instructions to be combined with the fluid component and thereby create the second desired mixture.

10. The computer-controlled dispenser system of claim 9 wherein the control computer receives the second instructions to create a plurality of desired mixtures in serial, each with distinct instructions comprising components and relative amounts in the first set of repositories and the second set of repositories, and sequentially creates a unique mixture for each of the plurality of the desired mixtures.

11. The computer-controlled dispenser system of claim 10 wherein, when one of the fluid components or the viscous components is over-dispensed, the control computer operates to cause an additional amount of another of the fluid component and the viscous component to dispense to cause the desired mixture to be appropriately proportioned.

12. The computer-controlled dispenser system of claim 7 wherein the control computer monitors the time that the at least one valve is open for the first set of repositories and that the at least one pump pumps for the second set of repositories and continuously operates to self-calibrate based upon an amount of the fluid component and the viscous components output by the dispensing nozzle as measured by the scale.

13. The computer-controlled dispenser system of claim 12 wherein the control computer further monitors at least one of current ambient temperature, temperature of the fluid component or the viscous component, introduction of a new batch of one of the fluid components or one of the viscous components which may alter dispensing speed, and any unique characteristics of each of the at least one valve and each of the at least one pump.

14. The computer-controlled dispenser system of claim 12 wherein the control computer specifically monitors each stroke for each of the at least one pump to predict a position within a stroke so as to selectively disengage each of the at least one pump based upon a position within the stroke to enable accurate dispensing while accommodating uneven dispensing throughout the stroke.

15. A method for operating a computer-controlled dispenser system, the method comprising: receiving instructions for the creation of a desired mixture of fluid components and viscous components; operating an at least one valve coupled with a pressurization source to move the fluid components from a first set of repositories through a dispensing nozzle into a container; controlling an at least one pump to move the viscous component from a second set of repositories through the dispensing nozzle into the container; weighing each of the fluid components and the viscous components as they are dispensed to ensure that a desired amount has been dispensed using a scale; mixing the fluid components and the viscous components in the container to create the desired mixture.

16. The method of claim 15 wherein further comprising receiving a second instructions for a second desired mixture, distinct from that of the desired mixture, to be created and thereafter operating a second valve of the at least one valve coupled to the first set of repositories to enable the fluid component to be dispensed from the dispensing nozzle according to the second instructions and operating a second pump of the at least one pump to pump the viscous component from one of the second set of repositories to be dispensed from the dispensing nozzle according to the second instructions to be combined with the fluid component and thereby create the second desired mixture.

17. The method of claim 15 wherein further comprising receiving the second instructions to create a plurality of desired mixtures in serial, each with distinct instructions comprising components and relative amounts in the first set of repositories and the second set of repositories, and sequentially

creates a unique mixture for each of the plurality of the desired mixtures.

18. The method of claim 15 wherein further comprising monitoring the time that the at least one valve is open for the first set of repositories and that the at least one pump pumps for the second set of repositories and continuously operating to self-calibrate as the fluid components and the viscous components based upon an amount of the fluid components and the viscous components output by the dispensing nozzle as measured by the scale.

19. The method of claim 15 further comprising monitoring each stroke for each of the at least one pump to predict a position within a stroke so as to selectively disengage each of the at least one pump based upon a position within the stroke to enable accurate dispensing while accommodating uneven dispensing throughout the stroke.

20. The method of claim 15 wherein further comprising monitoring the time that the valve is open for the first set of repositories and that the at least one pump pumps for the second set of repositories and continuously operating to self-calibrate as fluid components and viscous components based upon an amount of the fluid components and the viscous components output by the dispensing nozzle as measured by the scale.
