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Telescopic apparatus

Abstract

To provide a telescopic apparatus which is helically wound to reduce stress generated in two belts forming a pipe structure. A telescopic apparatus according to an embodiment of the present disclosure includes: a telescopic pipe structure formed by helically winding a first belt and a second belt about an axis, the second belt being arranged inside the first belt; a first belt case for housing a part of the first belt which does not form the pipe structure in a spiral form; and a second belt case for housing a part of the second belt which does not form the pipe structure in a spiral form. The first belt case and the second belt case are integrally formed as one component, and the thickness of the first belt is thinner than that of the second belt.

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Background/Summary

CROSS REFERENCE TO RELATED APPLICATIONS

(1) This application is based upon and claims the benefit of priority from Japanese patent application No. 2023-067764, filed on Apr. 18, 2023, the disclosure of which is incorporated herein in its entirety by reference.

BACKGROUND

(2) The present disclosure relates to a telescopic apparatus.
(3) Japanese Patent No. 4607772 discloses a technique for forming a telescopic pipe structure by helically winding a first belt and a second belt arranged inside the first belt.

SUMMARY

(4) Since the first belt is arranged on the outer side of the second belt, the helix radius of the first belt forming the pipe structure is larger than the helix radius of the second belt forming the pipe structure. The lengths of the first belt and the second belt forming the pipe structure of a predetermined length are different from each other, causing a problem that stress is generated in at

least one of the first belt and the second belt.

(5) The present disclosure has been made in view of the problem mentioned above, and according to the present disclosure, it is possible to realize a telescopic apparatus which reduces stress generated in two belts forming a pipe structure by helically winding one belt on the other.

(6) According to an aspect of the present disclosure, a telescopic apparatus includes: a telescopic pipe structure formed by helically winding a first belt and a second belt about an axis, the second belt being arranged inside the first belt; a first belt case for housing a part of the first belt which does not form the pipe structure in a spiral form; and a second belt case for housing a part of the second belt which does not form the pipe structure in a spiral form, wherein the first belt case and the second belt case are formed integrally as one component, and a thickness of the first belt is thinner than a thickness of the second belt.

(7) According to the present disclosure, it is possible to realize a telescopic apparatus which reduces stress generated in two belts forming a pipe structure by helically winding one belt on the other.

(8) The above and other objects, features and advantages of the present disclosure will become more fully understood from the detailed description given hereinbelow and the accompanying drawings which are given by way of illustration only, and thus are not to be considered as limiting the present disclosure.

Description

BRIEF DESCRIPTION OF DRAWINGS

(1) FIG. 1 is an explanatory diagram showing a configuration of a telescopic apparatus according to a reference example;

(2) FIG. 2 is an explanatory diagram showing a configuration of a telescopic apparatus according to the reference example;

(3) FIG. 3 is an explanatory diagram showing a cross section of a pipe structure according to the reference example;

(4) FIG. 4 is an explanatory diagram showing a configuration of a telescopic apparatus according to a first embodiment;

(5) FIG. 5 is an explanatory diagram showing a configuration of a belt case according to the first embodiment; and

(6) FIG. 6 is an explanatory view showing a configuration of a first belt and a second belt according to the first embodiment.

DESCRIPTION OF EMBODIMENTS

Reference Example

(7) Referring to FIGS. 1 to 3, a telescopic apparatus **60** according to a reference example will be described. FIG. 1 is an explanatory diagram showing a configuration of the telescopic apparatus **60** including a pipe structure.

(8) The telescopic apparatus **60** according to this reference example includes a pipe structure **100**, a first belt case **10**, a second belt case **20**, a guiding unit **30**, a drive unit **40**, and a mounting unit **50**. The pipe structure **100** is formed by helically winding the first belt **110** around the second belt **120**. The first belt case **10** houses a part of the first belt **110** which does not form the pipe structure **100** in a spiral form. The second belt case **20** houses a part of the second belt **120** which does not form the pipe structure **100** in a spiral form. The guiding unit **30** guides the first belt **110** and the second belt **120** so as to helically wind the first belt **110** around the second belt **120**. The drive unit **40** rotates the guiding member **32** of the guiding unit **30**. The mounting unit **50** is attached to the tip of the pipe structure **100**.

(9) When the guiding member **32** rotates in one direction driven by the drive unit **40**, the first belt

110 and the second belt **120** are guided by the guiding member **32** and so that the first belt **10** is helically wound around the second belt **120**, forming the pipe structure **100** that is elongated upward in FIG. 1. When the guiding member **32** rotates in the reverse direction, the winding of the first belt **110** and the second belt **120** is loosened and the first belt **110** and the second belt **120** are housed in the first belt case **10** and the second belt case **20**, respectively, shortening the pipe structure **100**. In addition, instead of rotating the guiding member **32**, the pipe structure **100** itself may be rotated whereby the pipe structure is expanded and contracted. The first belt **110** and the second belt **120** may be made of metal (e.g., a metal having spring properties such as spring stainless steel). The first belt **110** and the second belt **120** may be made of other materials such as deformable resin.

(10) FIG. 2 is an explanatory view showing how the pipe structure **100** is formed by winding the first belt **110** around the second belt **120**. In FIG. 2, the outer shape of the second belt **120** is drawn in dashed lines for the sake of convenience of illustration. The upper left drawing in FIG. 2 shows the state before winding the belts, and the upper right drawing shows the overlapped state of the first belt **110** and the second belt **120** in the wound state in a plane view.

(11) The pipe structure **100** is formed by helically winding the first belt **110** and the second belt **120** arranged inside the first belt **110** about the axis CX. The first belt **110** has a first flat part **111** and a plurality of first engaging parts **112** arranged in a plurality of rows along the longitudinal direction of the first belt **110**. The first flat part **111** is a flat strip-like part without any projections or recesses. The first engaging parts **112** are arranged in two rows at regular intervals along the longitudinal direction of the first belt **110**. The second belt **120** has a second flat part **121** and a plurality of second engaging parts **122** arranged in a plurality of rows along the longitudinal direction of the second belt **120**. The second flat part **121** is a flat strip-like part without any projections or recesses. The second engaging parts **122** are arranged in two rows at regular intervals along the longitudinal direction of the second belt **120**.

(12) In the pipe structure **100** shown in the drawings at the bottom of FIG. 2, the first belt **110** is wound at a constant pitch P_t along the axis CX. The distance L_e between the two rows of the first engaging parts **112** along the direction of the axis CX is equal to $\frac{1}{2}$ of the winding pitch P_t . These configurations are similar to those of the second belt **120**.

(13) The first belt **110** has a width W_1 and the second belt **120** has a width W_2 . These widths W_1 and W_2 are approximately equal, and are set to a value slightly smaller than the winding pitch P_t .

(14) The first belt **110** and the second belt **120** are superimposed on each other and helically wound in a state in which the first belt **110** is wound around the second belt **120** with a displacement of $\frac{1}{2}$ of the winding pitch P_t . As a result, the first engaging parts **112** of the two rows of the first belt **110** engage with the second engaging parts of the two second belts **120** superimposed on the inside of the first belt **110**.

(15) Referring to FIG. 1, the first belt case **10** is rotatably supported about the axis CX. The first belt case **10** rotates according to the length of the first belt **110** pulled out from the first belt case **10**. Similarly, the second belt case **20** is rotatably supported about the axis CX. The second belt case **20** rotates according to the length of the second belt **120** pulled out from the second belt case **20**.

(16) The telescopic apparatus **60** may transport the load placed on the mounting unit **50**.

(17) FIG. 3 is a cross-sectional view of the pipe structure **100** in the reference example. The first engaging part **112** of the first belt **110** is formed as a first hollow projection **114** (hollow truncated cone projection part) projecting toward the axis CX. The first engaging part **112** has an opening **116** in the center. The opening **116** may be omitted. That is, tip end of the first hollow projection **114** may be closed.

(18) The second engaging part **122** of the second belt **120** is configured to be fitted with the first engaging part **112** of the first belt **110**. In the reference example, the second engaging part **122**, like the first engaging part **112**, is also configured as a second hollow projection **124** (hollow truncated

cone projection part) projecting toward the axis CX, and has an opening **126** in the center thereof. The opening **126** may be omitted. That is, tip end of the second hollow projection **124** may be blocked. The second engaging part **122** may be configured to have an almost identical shape to the first engaging part **112**, and the projection part of the second engaging part **122** is preferably configured to be slightly larger than that of the first engaging part **112**.

(19) The inner surface of the first hollow projection **114** and the outer surface of the second hollow projection **124** are configured to come into contact with each other. In this configuration, the contact pressure can be relaxed compared with the case where the two engaging parts come into point contact. As a result, deformation due to contact can be reduced, and noise and vibration can be reduced.

(20) The angle θ formed between the first hollow projection **114** and the first flat part **111** is preferably set in the range of 30 degrees to 85 degrees. The same applies to the second hollow projection **124**.

(21) The first engaging part **112** projects inward (on the axis CX-side) from the inner surface **111i** of the first flat part **111**. On the other hand, there is no part projecting outward from the outer surface **111o** of the first flat part **111**. These configurations are similar to those of the second belt **120**.

(22) The projection height of the first hollow projection **114** and the projection height of the second hollow projection **124** are equal to each other. Therefore, the thickness of the first belt **110** and the thickness of the second belt **120** are equal to each other.

First Embodiment

(23) First, the problems found by the inventors of the present disclosure regarding the telescopic apparatus **60** of the aforementioned reference example will be explained. Since the first belt **110** is arranged on the outer side of the second belt **120** in the pipe structure **100**, the helix radius of the first belt **110** forming the pipe structure **100** is larger than the helix radius of the second belt forming the pipe structure **100**. Since the first belt **110** forming the pipe structure **100** is longer than the second belt **120**, the amount of rotation of the first belt case **10** is larger than the amount of rotation of the second belt case **20**. Therefore, when the first belt case **10** and the second belt case **20** are integrated, there is a problem that the tensile stress generated in the first belt **110** is large and the compressive stress generated in the second belt **120** is large. Therefore, the telescopic apparatus according to the first embodiment realizes a configuration in which the stress generated in the first belt **110** and the second belt **120** is reduced.

(24) Hereinafter, the telescopic apparatus according to the first embodiment will be described focusing on the differences with a telescopic apparatus according to a comparative example. The same structural elements/components are denoted by the same reference symbols, and descriptions thereof are omitted where appropriate.

(25) FIG. 4 is an explanatory diagram showing a configuration of a telescopic apparatus **200** according to the first embodiment. The telescopic apparatus **200** includes a belt case **80** in which the first belt case **10** and the second belt case **20** are integrally formed.

(26) FIG. 5 is an explanatory view showing a cross section of the belt case **80**. The belt case **80** is provided with a housing **81** constituting a tubular body having a top and a bottom, and a partition **82** dividing a space inside the housing **81** into two upper and lower stages. The housing **81** and the partition **82** are provided with a through hole through which the guiding member **32** passes. The belt case **80** is supported in a rotatable state with respect to the guiding member **32**. The upper stage of the belt case **80** corresponds to the first belt case **10**, and the lower stage corresponds to the second belt case **20**. The diameter of the first belt case **10** and the diameter of the second belt case **20** may be equal to each other. One end of the first belt **110** and one end of the second belt **120** may be fixed to the inner surface of the housing **81**.

(27) FIG. 6 is an explanatory view showing the configuration of the first belt **110** and the second belt **120** according to the first embodiment. The thickness T1 of the first belt **110** is smaller than the

thickness **T2** of the second belt **120**. For example, the projection height of the first hollow projection **114** may be lower than the projection height of the second hollow projection **124**. Alternatively, the first flat part **111** may be thinner than the second flat part **121**.

(28) Since the thickness **T1** is smaller than the thickness **T2**, when the belt case **80** is viewed from the upper surface side thereof, the spiral configuration of the first belt **110** (referred to as a first spiral configuration) is arranged on the outer side of the spiral configuration of the second belt **120** (referred to as a second spiral configuration). In other words, when the first spiral configuration is approximated by a plurality of first concentric circles and the second spiral configuration is approximated by a plurality of second concentric circles, the radius of each first concentric circle is larger than the radius of the corresponding second concentric circle.

(29) In this case, the length of the first belt **110** pulled out when the first belt case **10** is rotated once increases. In other words, assuming that the first belt case **10** and the second belt case **20** are formed as separate components, the amount of rotation of the first belt case **10** decreases. Thus, when the first belt case **10** and the second belt case are formed integrally as one component, the tensile stress generated in the first belt **110** and the compressive stress generated in the second belt **120** decrease.

(30) Since the first belt case **10** and the second belt case **20** are formed integrally, the size of the belt case can be reduced. In addition, the number of parts is reduced, thereby reducing cost.

(31) Next, study by the inventors of the present disclosure will be described using mathematical expressions. When the pipe structure **100** has a predetermined length h , the lengths of the first belt **110** and the second belt **120** forming the pipe structure **100** are expressed by Expressions (1) and (2), respectively. Specifically, the predetermined length h is the length when the pipe structure **100** is at its most elongated position.

$$(32) [\text{Expression1}] \quad l_1 = h * \sqrt{1 + (2 \frac{r_1}{p})^2} \quad (1) \quad [\text{Expression2}] \quad l_2 = h * \sqrt{1 + (2 \frac{r_2}{p})^2} \quad (2)$$

wherein, $l_{\text{sub.1}}$ and $l_{\text{sub.2}}$ represent the lengths of the first belt **110** and the second belt **120** forming the pipe structure **100**, respectively, $r_{\text{sub.1}}$ and $r_{\text{sub.2}}$ represent the helix radii of the first belt **110** and the second belt **120**, respectively, $r_{\text{sub.1}}$ is larger than $r_{\text{sub.2}}$, and p represents the winding pitch of each belt.

(33) On the other hand, the first belt **110** and the second belt **120** are housed spirally in the belt case **80**. The length of each belt housed in the belt case **80** is expressed by Expression (3).

$$(34) [\text{Expression3}] \quad l = \sum_{j=1}^n 2 r_j \quad (3)$$

wherein, l denotes the length of each belt, j denotes a subscript representing each winding, n denotes the number of windings, and $r_{\text{sub.j}}$ denotes the radius of the concentric circle corresponding to each winding. The radius of the innermost concentric circle is referred to as $R_{\text{sub.i}}$, and the radius of the outermost concentric circle is referred to as $R_{\text{sub.o}}$. $R_{\text{sub.o}}$ and $R_{\text{sub.i}}$ may correspond to the outer and inner diameters of the belt case **80**, respectively. $R_{\text{sub.o}}$ of the first belt **110** is also referred to as $R_{\text{sub.o1}}$, and $R_{\text{sub.o}}$ of the second belt **120** is also referred to as $R_{\text{sub.o2}}$. Similarly, $R_{\text{sub.i}}$ of the first belt **110** is also referred to as $R_{\text{sub.i1}}$, and $R_{\text{sub.i}}$ of the second belt **120** is also referred to as $R_{\text{sub.i2}}$.

(35) When the interval between the windings is t , the number of turns n is expressed as $n = (R_{\text{sub.o}} - R_{\text{sub.i}})/t$, and $r_{\text{sub.j}} = R_{\text{sub.i}} + j * t$. Note that t for the first belt **110** is also referred to as $t_{\text{sub.1}}$, and t for the second belt **120** is also referred to as $t_{\text{sub.2}}$. By transforming Expression (3), Expression (4) can be obtained.

$$(36) [\text{Expression4}] \quad l = \sum_{j=1}^n 2 (R_i + j * t) = \frac{1}{t} (R_o - R_i) (R_o + R_i - t) \quad (4)$$

Expressions (5) and (6) are obtained from Expressions (1) and (4).

$$(37) [\text{Expression5}] \quad h * \sqrt{1 + (2 \frac{r_1}{p})^2} = \frac{1}{t_1} (R_{o1} - R_{i1}) (R_{o1} + R_{i1} - t_1) \quad (5) \quad [\text{Expression6}]$$

$$h * \sqrt{1 + (2 \frac{r_2}{p})^2} = \frac{r_2}{t_2} (R_{o2} - R_{i2}) (R_{o2} + R_{i2} - t_2) \quad (6)$$

(38) Further, since the number of windings n of the first belt **110** and the number of windings n of the second belt **120** are equal to each other, Expression (7) can be obtained.

$$(39) [\text{Expression 7}] \quad n = \frac{R_{o1} - R_{i1}}{t_1} = \frac{R_{o2} - R_{i2}}{t_2} \quad (7)$$

(40) When the first belt case **10** and the second belt case **20** are formed as separate components and Expressions (5) to (7) are satisfied, the amount of rotation of the first belt case **10** coincides with amount of rotation of the second belt case **20** during the period when the pipe structure **100** is elongated from the shortest length thereof to the longest length thereof. Therefore, when the first belt case **10** and the second belt case **20** are integrated, the tensile stress generated in the first belt **110** and the compressive stress generated in the second belt **120** decrease.

(41) Ideally, when the first belt case **10** and the second belt case **20** are formed as separate components, the amount of rotation of the first belt case **10** and amount of rotation of the second belt case **20** until the pipe structure **100** is elongated to an arbitrary length should coincide with each other. However, when the thickness of the first belt **110** and that of the second belt **120** are fixed, it is difficult to completely match the rotational speed of the first belt case with that of the second belt case **20**. Therefore, the thickness of the first belt **110** may change in the extension direction of the first belt **110**, or the thickness of the second belt **120** may change in the extension direction of the second belt **120** so that the amount of rotation of the first belt case **10** and the amount of rotation of the second belt case **20** coincide until the pipe structure **100** is elongated to an arbitrary length.

(42) In the telescopic apparatus according to the first embodiment, by making the first belt **110** thinner than the second belt **120**, the stress generated in the first belt **110** and the second belt **120** can be reduced.

(43) It should be noted that the present disclosure is not limited to the above embodiments and can be suitably changed to the extent that it does not deviate from the gist of thereof.

(44) From the disclosure thus described, it will be obvious that the embodiments of the disclosure may be varied in many ways. Such variations are not to be regarded as a departure from the spirit and scope of the disclosure, and all such modifications as would be obvious to one skilled in the art are intended for inclusion within the scope of the following claims.

Claims

1. A telescopic apparatus, comprising: a telescopic pipe structure formed by helically winding a first belt and a second belt about an axis, the second belt being arranged inside the first belt; a first belt case for housing a part of the first belt which does not form the pipe structure in a spiral form; and a second belt case for housing a part of the second belt which does not form the pipe structure in a spiral form, wherein the first belt case and the second belt case are formed integrally as one component, a thickness of the first belt is thinner than a thickness of the second belt, the first belt is provided with a first hollow projection and the second belt is provided with a second hollow projection, the first hollow projection and the second hollow projection being fitted with each other, and a projection height of the first hollow projection is lower than a projection height of the second hollow projection.

2. The telescopic apparatus according to claim 1, wherein a diameter of the first belt case and a diameter of the second belt case are equal to each other.
