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### Spreader distribution compensation through material flow manipulation

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#### Abstract

A residue distribution system includes a flow channel having a first lateral side and a second lateral side disposed. A spreader is positioned proximate a downstream end of the flow channel, and broadcasts the flow of the crop residue. A residue distributor is positioned within the flow channel and upstream of the spreader for directing the crop residue toward one of the first lateral side or the second lateral side of the flow channel to increase a mass of the crop residue that side of the spreader, whereby a discharge density of the crop residue on that side of the spreader is increased to overcome effects of a crosswind or an uphill side-slope on broadcast distribution of the crop residue.

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## Background/Summary

CROSS-REFERENCE TO RELATED APPLICATIONS (1) This application claims the benefit of U.S. Provisional Patent Application Ser. No. 63/261,734, filed on Sep. 28, 2021, the disclosure of which is hereby incorporated by reference.

### TECHNICAL FIELD

(1) The disclosure generally relates to a harvester implement for harvesting crop material from a field, and more particularly to a residue distribution system of the harvester implement.

### BACKGROUND

(2) Crops may be harvested from a field with a harvester implement. One example of a harvester implement combines reaping, threshing, and cleaning of the harvested crop material into a single implement. Such implements may be referred to as “combine harvesters”, or simply as “combines”. The harvester implements often separate the crop material into grains and straw. The straw may be considered the crop residue. The straw or crop residue is deposited back onto the ground surface of the field.

(3) Often, the straw is chopped and broadcast from the harvester implement to spread the crop

residue across the field. It is desirable to evenly spread the crop residue across a width of the field that is approximately equal to a harvest width. However, a side-slope angle of the ground surface and/or a crosswind while broadcasting the crop residue may negatively effect or prevent an even distribution of the crop residue over the ground surface, causing the crop residue to settle on a downhill side or downwind side of the ground surface.

#### SUMMARY

(4) A residue distribution system for a harvester implement is provided. The residue distribution system includes a housing defining a flow channel. The flow channel extends along a longitudinal axis and is configured for conducting a flow of a crop residue therethrough. The flow channel directs the crop residue in a direction moving from an upstream end of the flow channel toward a downstream end of the flow channel. The flow channel includes a first lateral side disposed on a first side of the longitudinal axis, and a second lateral side disposed on a second side of the longitudinal axis. A spreader is positioned proximate the downstream end of the flow channel. The spreader is operable to broadcast the flow of the crop residue across a residue distribution width extending perpendicular to the longitudinal axis. A residue distributor is positioned within the flow channel and upstream of the spreader. The residue distributor is operable to direct the flow of the crop residue toward one of the first lateral side and the second lateral side of the flow channel to increase a mass flow rate of the crop residue passing through the spreader on the one of the first lateral side and the second lateral side of the flow channel, whereby a discharge density of the flow of the crop residue on the one of the first lateral side and the second lateral side is increased.

(5) In one implementation of the disclosure, the residue distributor may include at least one fin that is selectively controllable between a first position and a second position. When the fin is disposed in the first position, the fin is operable to direct the flow of the crop residue toward the first lateral side of the flow channel. When the fin is disposed in the second position, the fin is operable to direct the flow of the crop residue toward the second lateral side of the flow channel. The at least one fin may include only a single fin. However, in other implementations, the at least one fin may include a plurality of fins, with the plurality of fins arranged across a width of the flow channel transverse to the longitudinal axis.

(6) In another aspect of the disclosure, the at least one fin may be selectively controllable into at least one intermediate position. The intermediate position is disposed between the first position and the second position. For example, the intermediate position may be approximately half way between the first position and the second position and configured to not effect the path of the flow of the crop residue, i.e., not direct the flow of the crop residue toward either the first lateral side or the second lateral side of the flow channel. It should be appreciated that the at least one intermediate position may include multiple positions between the first position and the second position, with each respective one of the plurality of intermediate positions directing the flow of the crop residue, to a varying amount, toward one of the first lateral side or the second lateral side of the flow channel.

(7) In one aspect of the disclosure, the residue distributor may include a fin actuator. The fin actuator may be either directly or indirectly coupled to the fin(s). The fin actuator may be configured to move the fin(s) between the first position and the second position. In one implementation, the fin actuator may include one of a linear actuator or a rotary actuator. The linear actuator may be configured to extend in a first linear direction and retract in a second linear direction that is opposite the first linear direction. The rotary actuator may be configured to rotate in a first rotational direction and a second rotational direction opposite the first rotational direction. The fin actuator may include, but is not limited to, an electrically activated system, a hydraulically actuated system, or a pneumatically actuated system.

(8) In one aspect of the disclosure, the residue distribution system may include a slope sensor. The slope sensor may be arranged to detect data related to a slope angle of a ground surface. The slope angle is an angle formed between the ground surface and a horizontal plane in a direction

perpendicular to the longitudinal axis. The slope sensor may include one or more components, and may be mounted directly to the harvester implement, may be located remotely from the harvester implement, or may include some components located remotely from the harvester implement and additional components mounted on the harvester implement.

(9) In one implementation of the disclosure, the slope sensor may include, but is not limited to, a roll angle sensor. The roll angle sensor may be coupled to the housing and operable to detect a roll angle of the housing relative to the horizontal plane. In other implementations of the disclosure, the slope sensor may include a Global Positioning System (GPS) sensor operable to detect a location of the housing on the ground surface, and topographic data or map related to an elevation profile of the ground surface in a region surrounding the location of the housing. A controller or other computing device may then use the GPS location of the housing and the elevation profile to determine the slope angle of the ground surface in the region surrounding the harvester implement.

(10) In one aspect of the disclosure, the residue distribution system may include a controller. The controller may be disposed in communication with the slope sensor and the fin actuator. The controller may include a processor and a memory having a distribution algorithm stored thereon. The processor is operable to execute the distribution algorithm to control the fin(s) between the first position and the second position based on the slope angle detected by the slope sensor.

(11) In one aspect of the disclosure, the residue distribution system may include a weather sensor. The weather sensor may be arranged to detect data related to a wind vector. The wind vector includes a wind velocity relative to the harvester implement and/or the housing, and a wind direction relative to the longitudinal axis of the harvester implement. The weather sensor may include one or more components, and may be mounted directly to the harvester implement, may be located remotely from the harvester implement, or may include some components located remotely from the harvester implement and additional components mounted on the harvester implement.

(12) In one aspect of the disclosure, the controller may be disposed in communication with the weather sensor and the fin actuator. The controller includes the processor and the memory having the distribution algorithm stored thereon. The processor may be operable to execute the distribution algorithm to control the fin(s) between the first position and the second position based on the wind vector, i.e., the wind direction relative to the longitudinal axis of the harvester implement and the wind velocity relative to the housing.

(13) In one aspect of the disclosure, the residue distribution system may further include a chopper. The chopper is configured to cut the crop residue into smaller pieces. The chopper is positioned within the flow channel, between the residue distributor and the spreader, such that the residue distributor is positioned upstream of the chopper. Accordingly, the residue distributor may direct the flow of the crop residue to either the first lateral side or the second lateral side upstream of the chopper and the spreader.

(14) In one implementation of the disclosure, the residue distributor may include an air system positioned to discharge a flow of pressurized air into the flow channel. The air system is selectively controllable between a first configuration and a second configuration. When disposed in the first configuration, the air system is configured to direct the flow of the crop residue toward the first lateral side of the flow channel. When disposed in the second configuration, the air system is configured to direct the flow of the crop residue toward the second lateral side of the flow channel.

(15) In one implementation, the residue distributor may include a conveyor system. The conveyor system may be positioned within the flow channel and operable to move in a first lateral direction or a second lateral direction relative to the longitudinal axis. The conveyor system may move in the first lateral direction relative to the longitudinal axis to direct the flow of the crop residue toward the first lateral side of the flow channel. The conveyor system may move in the second lateral direction relative to the longitudinal axis to direct the flow of the crop residue toward the second lateral side of the flow channel. The conveyor system may include, but is not limited to, and endless belt rotating in a transverse direction relative to the longitudinal axis, and having a plurality

of flights for engaging and directing the flow of the crop residue.

(16) In one aspect of the disclosure, the residue distributor may include the controller being disposed in communication with a crop separator of the harvesting implement. The crop separator may be configured to separate grains from straw, with the straw forming the crop residue. The controller may be configured to control a speed of the crop separator to direct the flow of the crop residue toward one of the first lateral side or the second lateral side of the flow channel.

(17) A harvester implement for harvesting a crop is also provided. The harvester implement includes a frame extending along a longitudinal axis. The longitudinal axis extends between a forward end and a rearward end of the frame relative to a direction of travel of the harvester implement. A harvester head is coupled to the frame. The harvester head is operable to reap the crop. A separator is attached to the frame. The separator is positioned to receive the crop from the harvester head. The separator is operable to separate the crop material into a grain portion and a crop residue. The harvester implement further includes a housing. The housing defines a flow channel extending along the longitudinal axis. The flow channel is positioned to receive a flow of the crop residue from the separator. The flow channel is configured for conducting the flow of the crop residue through the flow channel in a direction moving from an upstream end of the flow channel proximate the separator toward a downstream end of the flow channel. The flow channel includes a first lateral side disposed on a first side of the longitudinal axis, and a second lateral side disposed on a second side of the longitudinal axis. A spreader is positioned proximate the downstream end of the flow channel. The spreader is operable to broadcast the flow of the crop residue across a residue distribution width. The residue distribution width extends perpendicular to the longitudinal axis. A residue distributor is positioned within the flow channel and upstream of the spreader. The residue distributor is operable to direct the flow of the crop residue toward one of the first lateral side and the second lateral side of the flow channel to increase a mass flow rate of the crop residue passing through the spreader on the one of the first lateral side and the second lateral side of the flow channel, whereby a discharge density of the flow of the crop residue on the one of the first lateral side and the second lateral side is increased.

(18) Increasing the discharge density of the flow of the crop residue decreases a deceleration rate of the crop residue, enabling the crop residue to travel through the air farther over a given time. By increasing the discharge density of the flow of crop residue, the effects of a crosswind or an uphill ground slope may be counter-acted, thereby enabling an even distribution of the crop residue over the entire residue distribution width. In other words, when a crosswind or an uphill ground slope are encountered, the residue distributor may be controlled to direct the flow of the crop residue to one of the first lateral side or the second lateral side of the flow channel, thereby increasing the discharge density on that side of the flow channel. Increasing the discharge density on that side of the harvester implement allows the crop residue to travel a greater distance through the air than would occur at a lower discharge density, thereby counter-acting effects of the crosswind or an uphill ground slope.

(19) In one aspect of the disclosure, the harvester implement may include a controller. The controller may include a processor and a memory having a distribution algorithm stored thereon. The processor is operable to execute the distribution algorithm to control the residue distributor between a first position and a second position. When the residue distributor is controlled to the first position, the residue distributor is operable to direct the flow of the crop residue toward the first lateral side of the flow channel. When the residue distributor is controlled to the second position, the residue distributor is operable to direct the flow of the crop residue toward the second lateral side of the flow channel.

(20) In one aspect of the disclosure, the harvester implement may include a slope sensor. The slope sensor may be arranged to detect data related to a slope angle of a ground surface. The slope angle is an angle formed between the ground surface and a horizontal plane in a direction perpendicular to the longitudinal axis. The processor may be operable to execute the distribution algorithm to

control the residue distributor between the first position and the second position based on the slope angle detected by the slope sensor. For example, the processor may control the residue distributor to an uphill one of the first lateral side or the second lateral side relative to the slope angle to counteract the effects of gravity acting on the broadcast crop residue.

(21) In one aspect of the disclosure, the harvester implement may include weather sensor. The weather sensor may be arranged to detect data related to a wind vector. The wind vector may include a wind velocity relative to the housing, and a wind direction relative to the longitudinal axis. The processor may be operable to execute the distribution algorithm to control the residue distributor between the first position and the second position based on the wind vector, e.g., the wind direction relative to the longitudinal axis and the wind velocity relative to the housing. For example, the processor may control the residue distributor to an up-wind one of the first lateral side and the second lateral side of the flow channel relative to the wind vector to counter-act a crosswind acting on the broadcast crop residue.

(22) In one implementation of the disclosure, the residue distributor may include at least one fin selectively controllable between the first position operable to direct the flow of the crop residue toward the first lateral side of the flow channel, and the second position operable to direct the flow of the crop residue toward the second lateral side of the flow channel. In one implementation, the at least one fin includes a plurality of fins arranged across a width of the flow channel transverse to the longitudinal axis. The residue distributor may further include a fin actuator coupled to the fin(s). The fin actuator is operable to move the fin(s) between the first position and the second position.

(23) In one implementation of the disclosure, the harvester implement may include a chopper. The chopper may be operable to cut the crop residue into smaller pieces. The chopper is positioned within the flow channel, between the residue distributor and the spreader. As such, the residue distributor is positioned upstream of the chopper.

(24) The above features and advantages and other features and advantages of the present teachings are readily apparent from the following detailed description of the best modes for carrying out the teachings when taken in connection with the accompanying drawings.

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## Description

### BRIEF DESCRIPTION OF THE DRAWINGS

- (1) FIG. 1 is a schematic plan view of a harvester implement in a field showing a wind vector relative to the harvester implement.
- (2) FIG. 2 is a schematic side profile view of the harvester implement.
- (3) FIG. 3 is a schematic rear profile view of the harvester implement showing a ground slope relative to the harvester implement.
- (4) FIG. 4 is a schematic plan view of the harvester implement showing a residue distributor in a first position.
- (5) FIG. 5 is a schematic plan view of the harvester implement showing the residue distributor in a second position.
- (6) FIG. 6 is a schematic plan view of the harvester implement showing the residue distributor in an intermediate position.
- (7) FIG. 7 is a schematic cross sectional view of the harvester implement showing a first alternative embodiment of the residue distributor.
- (8) FIG. 8 is a schematic cross sectional view of the harvester implement showing a second alternative embodiment of the residue distributor.

### DETAILED DESCRIPTION

- (9) Those having ordinary skill in the art will recognize that terms such as “above,” “below,”

“upward,” “downward,” “top,” “bottom,” etc., are used descriptively for the figures, and do not represent limitations on the scope of the disclosure, as defined by the appended claims. Furthermore, the teachings may be described herein in terms of functional and/or logical block components and/or various processing steps. It should be realized that such block components may be comprised of any number of hardware, software, and/or firmware components configured to perform the specified functions.

(10) Terms of degree, such as “generally”, “substantially” or “approximately” are understood by those of ordinary skill to refer to reasonable ranges outside of a given value or orientation, for example, general tolerances or positional relationships associated with manufacturing, assembly, and use of the described embodiments.

(11) Referring to the Figures, wherein like numerals indicate like parts throughout the several views, a harvester implement is generally shown at **20**. Referring to FIG. **1**, the harvester implement **20** is configured for harvesting a crop **22** from a field **24**. The crop **22** may include, but is not limited to flax, corn, sunflowers, soybeans, sorghum, wheat canola, barley, pulses, oats, rye, etc. The harvester implement **20** may be configured to separate the grains, kernels, and/or beans from a residual crop **22** material. The residual crop **22** material may include straw, stalks and/or chaff, and may be referred to herein as a crop residue **26**. The example implementation of the harvester implement **20** shown in the Figures and described herein may be referred to as a “combine harvester” or a “combine”. However, it should be appreciated that the harvester implement **20** may be configured and/or named differently than the example implementation described herein.

(12) Referring to FIG. **2**, the harvester implement **20** includes a frame **28**, which supports that various components of the harvester implement **20**. The frame **28** may include various structural components, such as but not limited to rails, braces, brackets, walls, panels, etc. The frame **28** may be shaped and/or configured in a suitable manner for the particular application of the harvester implement **20**. The frame **28** extends along a longitudinal axis **30**, between a forward end **32** and a rearward end **34**. The forward end **32** and the rearward end **34** of the frame **28** are defined relative to a direction of travel **36** of the harvester implement **20** while harvesting the crop **22**. The longitudinal axis **30** may be defined by an axis that passes through a center of gravity of the harvester implement **20** in a long direction of the frame **28**, between the forward end **32** and the rearward end **34** of the harvester implement **20**.

(13) A harvester head **38** is coupled to the frame **28** adjacent the forward end **32** of the frame **28**. The harvester head **38** is configured to reap the crop **22** from the field **24**. As such, the harvester head **38** may cut crop **22** and move the crop **22** rearward through the harvester implement **20** for further processing, as described briefly below. The harvester head **38** is configured to cut the crop **22** across a harvest width **40**. The harvest width **40** extends a distance perpendicular to the longitudinal axis **30** of the frame **28**, and may vary between applications. The features, components and operation of the harvester head **38** are dependent upon the specific crop **22** being harvested, are known to those skilled in the art, are not pertinent to the teachings of this disclosure, and are therefore not described in greater detail herein.

(14) The harvester implement **20** may include a feeder house **42** that is attached to the frame **28**. The feeder house **42** is positioned rearward of the harvester head **38** along the longitudinal axis **30**, in a position to receive the crop **22** from the harvester head **38**. The feeder house **42** may include a device capable of receiving the crop **22** from the harvester head **38** and moving the crop **22** rearward relative to the longitudinal axis **30**. The features, components and operation of the feeder house **42** are known to those skilled in the art, are not pertinent to the teachings of this disclosure, and are therefore not described in greater detail herein.

(15) The feeder house **42** directs the crop **22** rearward to a separator **44**. The separator **44** is attached to the frame **28** and is positioned to receive the crop **22** from the feeder house **42** and/or harvester head **38**. The separator **44** is operable to separate the grains, kernels, and/or beans of the

crop **22** from the crop residue **26**. The grains, kernels and/or beans of the crop **22** may be collected in a grain tank **46** or otherwise unloaded onto a grain cart (not shown). The crop residue **26** is discharged from the separator **44** and conveyed to a residue distribution system **48**. The features, components and operation of the separator **44** are known to those skilled in the art, are not pertinent to the teachings of this disclosure, and are therefore not described in greater detail herein.

(16) The residue distribution system **48** is positioned to receive the crop residue **26** from the separator **44** and broadcast the crop residue **26** onto a ground surface **50** of the field **24**. Generally, the crop **22** and the crop residue **26** moves through the harvester implement **20** along a flow path from the harvester head **38** toward the rearward end **34** of the harvester implement **20**. This movement defines a flow or stream of the crop **22** and the crop residue **26** in a general direction rearward through the harvester implement **20**. As used herein, the term “upstream” is a relative descriptor referring to a direction or position located nearer the forward end **32** of the frame **28** and/or the beginning of the flow or stream of the crop **22** and/or crop residue **26**. As used herein, the term “downstream” is a relative descriptor referring to a direction or position located nearer the rearward end **34** of the frame **28** and/or a location of the harvester implement **20** from which the crop residue **26** is broadcast from the harvester implement **20** onto the ground surface **50** of the field **24**.

(17) The residue distribution system **48** may include at least one sensor **52**, **54**, **142**. The sensor may include, but is not limited to, a slope sensor **52**, a weather sensor **54**, and/or a residue distribution sensor **142**. The sensor **52**, **54**, **142** may be arranged and/or positioned to detect data related to one of a slope angle **56**, a wind vector **58**, or a distribution of the crop residue (**26**). Referring to FIG. **3**, the slope angle **56** is an angle formed between the ground surface **50** and a horizontal plane **60** in a direction perpendicular to the longitudinal axis **30** in the region of the ground surface **50** adjacent the rearward end **34** of the frame **28**. The slope angle **56** may be considered the ground slope in a direction perpendicular to the longitudinal axis **30** of the frame **28**. Referring to FIG. **1**, the wind vector **58** includes a wind velocity and a wind direction. The wind velocity of the wind vector **58** is the wind speed measured relative to the harvester implement **20**, e.g., a housing **70** of the harvester implement **20**, which is described in greater detail below. The wind direction of the wind vector **58** is measured horizontally relative to the longitudinal axis **30** of the frame **28**. The wind vector **58** may include a longitudinal component **62** parallel with the longitudinal axis **30**, and a transverse component **64** perpendicular to the longitudinal axis **30**. As used herein, reference to the wind velocity and/or the wind direction refers to the transverse component **64** of the wind vector **58** unless otherwise noted.

(18) As noted above, the residue distribution system **48** may include the slope sensor **52**. The slope sensor **52** may be positioned and/or arranged to detect data related to the slope angle **56** of the ground surface **50** relative to harvester implement **20**. For example, in one implementation, the slope sensor **52** may include a roll angle sensor coupled to the frame **28**, the housing **70**, or some other component of the harvester implement **20**. Referring to FIG. **3**, the roll angle sensor may be configured to detect data related to a roll angle **66** of the frame **28**, the housing **70**, etc., relative to the horizontal plane **60**. It should be appreciated that the roll angle **66** is an angle of rotation of the harvester implement **20** about the longitudinal axis **30**. When the harvester implement **20** is directly supported or resting on the ground surface **50**, the roll angle **66** of the harvester implement **20** is directly related to the slope angle **56** of the ground surface **50**.

(19) In another implementation, the slope sensor **52** may include a Global Positioning System (GPS) sensor that is operable to detect a geographic location of the frame **28**, the housing **70**, or some other component of the harvester implement **20** on the ground surface **50**. This detected location may be compared to topographic map or data related to an elevation profile of the ground surface **50** in a region surrounding the location of the housing **70**. The controller **68** may use the detected location of the harvester implement **20**, a direction of travel of the harvester implement, and elevation profile from the topographic map to determine the slope angle **56** of the ground



surface **50**.

(20) The slope sensor **52** may be located on the harvester implement **20**, may be located remote from the harvester implement **20**, or may include multiple components, with one component located on the harvester implement **20** and another component located remote from the harvester implement **20**. The slope sensor **52**, and any components thereof, may be disposed in communication with a controller **68**, described in greater detail below, for communicating the data related to the slope angle **56** thereto.

(21) As noted above, the residue distribution system **48** may include the weather sensor **54**. As shown in FIG. **1**, the weather sensor **54** may be positioned and/or arranged to detect data related to the wind vector **58**, e.g., the wind velocity relative to the harvester implement **20** and/or the wind direction relative to the longitudinal axis **30**. In one implementation, the weather sensor **54** may include a weather station. The weather station may be located on the harvester implement **20**, or may be located remotely from the harvester implement **20** and disposed in communication with the controller **68** for communicating the data related to the wind vector **58**. For example, the weather station may be positioned near the harvester implement **20**, such as but not limited to a field **24** the harvester implement **20** is working. In another implementation, the weather sensor **54** may include a communication link with a remote weather service that is configured for communication data related to the wind vector **58** to the controller **68** of the harvester implement **20**.

(22) As noted above, the residue distribution system **48** may include the residue distribution sensor **142**. As shown in FIG. **1**, the residue distribution sensor **142** may be positioned and/or arranged to detect data related to distribution of the crop residue **26** in a direction perpendicular to the longitudinal axis **30**. As used herein, the term “distribution” of the crop residue **26** may include, but is not limited to, a width left and/or right of the longitudinal axis **30** over which the crop residue **26** is spread, broadcast or distributed. When combined with movement of the harvester implement **20** in the direction of travel **36**, the term “distribution” of the crop residue may include, but is not limited to, an area over which the crop residue **26** is broadcast or spread, i.e., the width left and/or right of the longitudinal axis **30** over a length of movement along the direction of travel **36**. Additionally, the term “distribution” of the crop residue may include a relative quantity or amount of material aspect, e.g., a density, mass, or volume of the crop residue.

(23) In one implementation, the residue distribution sensor **142** includes a camera operable to detect an image of the crop residue **26** either dispersed on the field, while moving through the air, or while moving through the harvester implement **20**. For example, in one implementation, the residue distribution sensor **142** may be positioned and configured to capture an image of the crop residue **26** disposed on the field. In other implementations, the residue distribution sensor **142** may capture an image of the crop residue **26** while the crop residue **26** is moving through the air, after being broadcast from the spreader **78** and prior to contacting the ground. In other implementations, the residue distribution sensor **142** may capture an image of the crop residue **26** while the crop residue **26** is moving through the harvester implement, e.g., through the flow channel **72**. The controller may analyze the image to determine the distribution of the crop residue **26** on either side, i.e., left or right, of the longitudinal axis **30**. The controller **68** may then control the residue distributor **96** based on the detected distribution of the crop residue **26** perpendicular to the longitudinal axis **30**. While the residue distribution sensor **142** has been described herein as a camera operable to capture an image, it should be appreciated that the residue distribution sensor **142** may include some other type and/or configuration of sensor operable to sense data other than an image, such as but not limited to a weight, a force, a reflected light wave, a reflected radio wave, a reflected sound waves, etc. For example, other implementations of the residue distribution sensor **142** may alternatively be configured as, but are not limited to, a radar sensor, a lidar sensor, a thermal sensor, and IR light sensor/camera, or some other similar sensing device. It should be appreciated that the residue distribution sensor **142** may include some other device for sensing other types of data related to the distribution of the crop residue **26** other than the examples

described herein.

(24) As noted above, with reference to FIG. 2, the harvester implement **20** includes the housing **70**. The housing **70** defines a flow channel **72** that extends along the longitudinal axis **30**. The housing **70** may include, but is not limited to, interior and/or exterior panels, wall members, supports, braces, the frame **28**, etc. It should be appreciated that the housing **70** may include and/or define other portions of the harvester implement **20** other than the flow channel **72**. The flow channel **72** is configured for conducting the flow of the crop residue **26** therethrough in a direction moving from an upstream end **74** of the flow channel **72** toward a downstream end **76** of the flow channel **72**. The upstream end **74** of the flow channel **72** is positioned to receive the crop residue **26** from the separator **44**. The downstream end **76** of the flow channel **72** is positioned proximate a spreader **78**, and directs the crop residue **26** to the spreader **78**. The flow channel **72** may be formed by one or more components positioned to form a boundary for guiding the crop residue **26** between the separator **44** and the spreader **78**. The flow channel **72** may be formed by one or more components of the housing **70** including, but not limited to walls, panels, plates, belts, etc. It should be appreciated that the flow channel **72** may further be defined by other components and/or features of the harvester implement **20**, other than the housing **70**.

(25) Referring to FIGS. 4-6, the flow channel **72** generally extends along the longitudinal axis **30**, and includes a first lateral side **80** and a second lateral side **82**. The first lateral side **80** and the second lateral side **82** are disposed on opposing sides of the flow channel **72**, e.g., left and right sides respectively. In one implementation, the flow channel **72** is generally longitudinally centered with the longitudinal axis **30**, such that the first lateral side **80** of the flow channel **72** is disposed on a first side **84** of the longitudinal axis **30**, and the second lateral side **82** of the flow channel **72** is disposed on a second side **86** of the longitudinal axis **30**.

(26) As described above, the spreader **78** is positioned proximate the downstream end **76** of the flow channel **72**. Referring to FIG. 1, the spreader **78** is operable to broadcast the flow of the crop residue **26** onto the field **24**, across a residue distribution width **88**. The spreader **78** may include any device that is capable of spreading or broadcasting the crop residue **26** onto the field **24**. For example, the spreader **78** may include, but is not limited to, one or more of a spinner, active shrouds, and/or moveable vanes. In the example implementation shown in the Figures, the spreader **78** includes one or more adjustable guide vanes **90**. However, it should be appreciated that the spreader **78** may be configured differently in other implementations. The features, components, and operation of the spreader **78** are known to those skilled in the art, are not pertinent to the teachings of this disclosure, and are therefore not described in greater detail herein.

(27) The residue distribution width **88** is a distance extending perpendicular to the longitudinal axis **30**. In one implementation, the residue distribution width **88** is approximately equal to the harvest width **40** of the harvester head **38**. In the example implementation described herein, the adjustable guide vanes **90** are operable to control a distribution or broadcast angle **92** of the crop residue **26**. A position of the guide vanes **90** may be controlled via a respective actuator to direct the flow of the crop residue **26** relative to the longitudinal axis **30** to broadcast the crop residue **26** across the residue distribution width **88**. For example, the guide vanes **90** may be positioned to direct the crop residue **26** at a larger angle relative to the longitudinal axis **30** to direct the crop residue **26** farther from the longitudinal axis **30**, or may be positioned to direct the crop residue **26** at a lesser angle relative to the longitudinal axis **30** to direct the crop residue **26** nearer the longitudinal axis **30**. The position of the guide vanes **90** may be controlled by the controller **68**.

(28) Referring to FIG. 2, the residue distribution system **48** may further include a chopper **94**. The chopper **94** is operable to further cut and/or chop the crop residue **26** into smaller segments and/or portions. The chopper **94** may be positioned within the flow channel **72** between the residue distributor **96** and the spreader **78**, such that the residue distributor **96** is positioned upstream of the chopper **94** and downstream of the separator **44**. As such, the chopper **94** may be positioned to receive the flow of the crop residue **26** from the separator **44** via the flow channel **72**, and then

discharge the flow of the crop residue **26** back into the flow channel **72** upstream of the spreader **78**. The spreader **78** may then receive the flow of the crop residue **26** from the chopper **94** via the flow channel **72**. The features, components and operation of the spreader **78** are known to those skilled in the art, are not pertinent to the teachings of this disclosure, and are therefore not described in greater detail herein.

(29) Referring to FIG. **1**, with no or very light wind acting on the crop residue **26** broadcast from the spreader **78**, and when being broadcast onto flat terrain, the spreader **78** evenly distributes the crop residue **26** across the residue distribution width **88**. However, cross winds, i.e., winds blowing transverse to the longitudinal axis **30**, may blow the broadcast crop residue **26** toward a downwind side **124** of the harvester implement **20**, thereby preventing the broadcast crop residue **26** distributed in the upwind direction from fully spreading across the residue distribution width **88** and blowing the crop residue **26** broadcast in the downwind direction beyond the residue distribution width **88**.

(30) Referring to FIG. **3**, when the harvester implement **20** is traversing across a side slope of the ground surface **50**, i.e., moving perpendicular to the slope angle **56** of the ground surface **50**, the crop residue **26** broadcast on an uphill side **118** of the harvester implement **20** will have a shorter or lesser drop distance than the crop residue **26** broadcast on a downhill side **120** of the harvester implement **20**. The drop distance may be defined as the vertical distance traveled by the crop residue **26** from the spreader **78** to the ground surface **50**. The reduced drop distance on the uphill side **118** of the harvester implement **20**, caused by the slope angle **56** of the ground surface **50**, will cause the crop residue **26** to contact the ground surface **50** sooner than the crop residue **26** broadcast on the downhill side **120** of the harvester implement **20**, which has an increased drop distance caused by the ground surface **50**. By reducing the time it takes for the crop residue **26** to contact the ground surface **50** on the uphill side **118** of the harvester implement **20**, the crop residue **26** spends less time traveling through the air, and therefore travels a shorter lateral distance from the spreader **78**. This may result in the crop residue **26** broadcast on the uphill side **118** of the harvester implement **20** failing to fully spread across the residue distribution width **88** on the uphill side **118** of the harvester implement **20**. In contrast, the increased drop distance on the downhill side **120** of the harvester implement **20** increases the time the crop **22** material takes to contact the ground surface **50**, thereby enabling the crop residue **26** broadcast on the downhill side **120** of the harvester implement **20** to travel farther, which increases the lateral distribution distance from the spreader **78** and potentially distributing the crop residue **26** on the downhill side **120** of the harvester implement **20** outside the residue distribution width **88**.

(31) While the guide vanes **90** of the spreader **78** may be employed to counter act the effects of a crosswind and/or the effects of the slope angle **56** on the distribution of the crop residue **26**, by changing the trajectory of the crop residue **26** from the spreader **78** relative to the longitudinal axis **30**, the guide vanes **90** do not affect deceleration of the crop residue **26** due to air resistance, i.e., movement through the air. The deceleration of the crop residue **26** due to air resistance is increased on the upwind side **122** of a cross wind due to the relative air speed of the crop residue **26** on the upwind side **122** of the harvester implement **20**.

(32) The flow of the crop residue **26** is comprised of many very small and light individual pieces. Due to their respective small weight or mass, each individual piece of the crop residue **26** carries very little momentum, and therefore decelerates rapidly due to air resistance when moving against the cross wind. However, when the individual pieces of the crop residue **26** are “grouped” together, the effect of air resistance on the group of crop residue **26** is lessened. In other words, the increased weight or mass of the group or flow of the crop residue **26** carries more momentum through the air, thereby decreasing the effect of air resistance on the crop residue **26**. In other words, when the crop residue **26** moves through the air in a tightly packed group of small pieces, the effects of air resistance on the group is lessened, thereby allowing the crop residue **26** to resist the effects of air resistance and slowing the deceleration of the crop residue **26**. Slowing the deceleration of the crop

residue **26** enables the crop residue **26** to travel farther in a given amount of time.

(33) Referring to FIGS. **4-6**, in order to counteract the effects of the cross wind and/or the slope angle **56** of the ground surface **50**, the residue distribution system **48** may further include a residue distributor **96**. The residue distributor **96** is positioned within the flow channel **72** and upstream of the spreader **78**. If the residue distribution system **48** is equipped with the chopper **94**, the residue distributor **96** may be positioned upstream of the chopper **94**. The residue distributor **96** is operable to direct the flow of the crop residue **26** toward one of the first lateral side **80** and the second lateral side **82** of the flow channel **72**. By directing the flow of the crop residue **26** toward one of the first lateral side **80** or the second lateral side **82** of the flow channel **72**, a mass flow rate of the crop residue **26** passing through the spreader **78** on that side of the flow channel **72**, i.e., the one of the first lateral side **80** and the second lateral side **82** of the flow channel **72**, is increased. As used herein, the “mass flow rate” of the crop residue **26** is defined as the mass of the crop residue **26** passing through a specified portion of the flow channel **72** per unit of time. Increasing the mass flow rate of the crop residue **26** on that side of the flow channel **72**, i.e., on the one of the first lateral side **80** or the second lateral side **82**, increases a discharge density of the flow of the crop residue **26** on that side of the flow channel **72**. As used herein, the “discharge density” is defined as the mass of the crop residue **26** being moved through the flow channel **72** or discharged by the spreader **78** per a unit of volume at a given time.

(34) Accordingly, the residue distributor **96** increases a percentage of the flow of the crop residue **26** positioned within the flow channel **72** on one of the first lateral side **80** or the second lateral side **82**. By increasing the percentage of the crop residue **26** on a selected one of the first lateral side **80** or the second lateral side **82**, the mass of the crop residue **26** on that side increases. Increasing the mass of the crop residue **26** on the selected side of the flow channel **72** increase the density of the crop residue **26** on that side, i.e., the mass by unit volume. By directing more of the crop residue **26** to the selected side of the flow channel **72**, the amount or percentage of the crop **22** material on that side of the flow channel **72** moves through the spreader **78** on that side of the flow channel **72**, thereby increasing the amount or percentage of the crop residue **26** that is distributed by the spreader **78** on the selected side of the flow channel **72**. This in turn increases the density of the crop residue **26** broadcast from the spreader **78**. As described above, increasing the mass or density of the bunched together flow of the crop **22** material decreases deceleration of the broadcast crop **22** material moving through the air, because the larger mass and/or density of the crop residue **26** moving as a group increases the momentum of the crop residue **26**, thereby allowing the crop residue **26** to travel farther in a given period of time.

(35) Because gravity is a constant acting on the broadcast crop residue **26**, the amount of time it takes to fall the drop distance is generally fixed. However, by decreasing the deceleration of the crop residue **26**, thereby allowing the crop residue **26** to travel farther in the amount of time it takes the crop residue **26** to fall the drop distance, the crop residue **26** may travel farther from the longitudinal axis **30**. By doing so, the effect of the cross wind and/or the slope angle **56** may be counter-acted, and the crop residue **26** evenly spread across the residue distribution width **88**.

(36) Referring to FIGS. **4-6**, in one example implementation, the residue distributor **96** may include at least one vane or fin **98**. The fin **98** is selectively controllable between a first position **100**, shown in FIG. **4**, and a second position **102**, shown in FIG. **5**. When the fin **98** is disposed in the first position **100**, the fin **98** is operable to direct the flow of the crop residue **26** toward the first lateral side **80** of the flow channel **72**. When the fin **98** is disposed in the second position **102**, the fin **98** is positioned and operable to direct the flow of the crop residue **26** toward the second lateral side **82** of the flow channel **72**. Additionally, the fin **98** may be selectively controllable into at least one intermediate position **104**, shown in FIG. **6**. The intermediate position **104** is located between the first position **100** and the second position **102**. In one implementation, the intermediate position **104** may include an infinite number of positions between the first position **100** and the second position **102**. In another implementation, the intermediate position **104** may include or be defined

as a center position disposed equidistant from each of the first position **100** and the second position **102**.

(37) In the example implementation shown in FIGS. **4-6**, the at least one fin **98** includes a plurality of fins **98**. The plurality of fins **98** are arranged across a width of the flow channel **72** in a direction transverse to the longitudinal axis **30**. The plurality of fins **98** may be equidistantly spaced from each other. In one implementation, the plurality of fins **98** may be coupled together with a linkage **108** to provide common movement between the first position **100**, the second position **102** and/or the intermediate position **104**. In other implementations, each of the plurality of fins **98** may be independently controllable and/or moveable relative to remaining plurality of fins **98**. In yet other implementations, the plurality of fins **98** may be arranged in multiple groups of the fins **98**, with each group controllable and moveable relative to the other groups of the fins **98**. For example, the plurality of fins **98** may be arranged with a first group of fins **98** on the first half of the flow channel **72**, and a second group of fins **98** on the second half of the flow channel **72**. The first group may be coupled together for movement together. The second group may also be coupled together for movement together. The first group may be moveable independently of the second group.

(38) Referring to FIGS. **4-6**, the example implementation of the residue distributor **96** further includes a fin actuator **110**. The fin actuator **110** is coupled to the fins **98**. The fin actuator **110** is operable to move the fins **98** between the first position **100**, the second position **102**, and the intermediate position **104**. The fin actuator **110** may include, but is not limited to, one of a linear actuator operable to extend in a first linear direction and retract in a second linear direction opposite the first linear direction, or a rotary actuator operable to rotate in a first rotational direction and a second rotational direction opposite the first rotational direction. The fin actuator **110** may include an electrically powered device, a hydraulically powered device, a pneumatically powered device. The fin actuator **110** may be coupled to the fins **98** directly, or through a drivetrain, gear system, linkage **108** system, etc.

(39) The fin actuator **110** may be actuated via and/or responsive to a control signal from the controller **68**. The control signal is dependent upon the specific configuration of the fin actuator **110**. For example, if the fin actuator **110** is implemented as an electric motor, the control signal may include an electronic signal. If the fin actuator **110** is implemented as a hydraulic motor, the control signal may include a flow of a hydraulic fluid. It should be appreciated that the control signal may vary from the example implementations noted herein.

(40) As noted above, the harvester implement **20** may include the controller **68**. The controller **68** may be disposed in communication with the sensor **52**, **54**, **142** e.g., the slope sensor **52** and/or the weather sensor **54**. Additionally, the controller **68** may be disposed in communication with the residue distributor **96** for controlling the residue distributor **96**, e.g., the fin actuator **110**. The controller **68** may be operable to receive data signals from the slope sensor **52** and/or the weather sensor **54**, and communicate a control signal to the residue distributor **96**, e.g., the fin actuator **110**. While the controller **68** is generally described herein as a singular device, it should be appreciated that the controller **68** may include multiple devices linked together to share and/or communicate information therebetween. Furthermore, it should be appreciated that the controller **68** may be located on the harvester implement **20** or located remotely from the harvester implement **20**.

(41) The controller **68** may alternatively be referred to as a computing device, a computer, a control unit, a control module, a module, etc. The controller **68** includes a processor **112**, a memory **114**, and all software, hardware, algorithms, connections, sensors, etc., necessary to manage and control the operation of the residue distributor **96**. As such, a method may be embodied as a program or algorithm operable on the controller **68**. It should be appreciated that the controller **68** may include any device capable of analyzing data from various sensors, comparing data, making decisions, and executing the required tasks.

(42) As used herein, “controller” is intended to be used consistent with how the term is used by a

person of skill in the art, and refers to a computing component with processing, memory, and communication capabilities, which is utilized to execute instructions (i.e., stored on the memory or received via the communication capabilities) to control or communicate with one or more other components. In certain embodiments, the controller **68** may be configured to receive input signals in various formats (e.g., hydraulic signals, voltage signals, current signals, CAN messages, optical signals, radio signals), and to output command or communication signals in various formats (e.g., hydraulic signals, voltage signals, current signals, CAN messages, optical signals, radio signals).

(43) The controller **68** may be in communication with other components on the harvester implement **20**, such as hydraulic components, electrical components, and operator inputs within an operator station of an associated work vehicle. The controller **68** may be electrically connected to these other components by a wiring harness such that messages, commands, and electrical power may be transmitted between the controller **68** and the other components. Although the controller **68** is referenced in the singular, in alternative embodiments the configuration and functionality described herein can be split across multiple devices using techniques known to a person of ordinary skill in the art.

(44) The controller **68** may be embodied as one or multiple digital computers or host machines each having one or more processors, read only memory (ROM), random access memory (RAM), electrically-programmable read only memory (EPROM), optical drives, magnetic drives, etc., a high-speed clock, analog-to-digital (A/D) circuitry, digital-to-analog (D/A) circuitry, and any required input/output (I/O) circuitry, I/O devices, and communication interfaces, as well as signal conditioning and buffer electronics.

(45) The computer-readable memory **114** may include any non-transitory/tangible medium which participates in providing data or computer-readable instructions. The memory **114** may be non-volatile or volatile. Non-volatile media may include, for example, optical or magnetic disks and other persistent memory. Example volatile media may include dynamic random access memory (DRAM), which may constitute a main memory. Other examples of embodiments for memory **114** include a floppy, flexible disk, or hard disk, magnetic tape or other magnetic medium, a CD-ROM, DVD, and/or any other optical medium, as well as other possible memory devices such as flash memory.

(46) The controller **68** includes the tangible, non-transitory memory **114** on which are recorded computer-executable instructions, including a distribution algorithm **116**. The processor **112** of the computing device is configured for executing the distribution algorithm **116**. The distribution algorithm **116** implements a method of distributing the crop residue **26** from the harvester implement **20**, described in detail below.

(47) The controller **68** is configured to receive data from the sensors **52**, **54**, **142** related to at least one of the slope angle **56** detected by the slope sensor **52** and/or the wind vector **58**, i.e., the wind direction relative to the longitudinal axis **30** and the wind velocity relative to the housing **70**, detected by the weather sensor **54**. It should be appreciated that the controller **68** may use one or both the slope sensor **52** and/or the weather sensor **54** to control the position of the residue distributor **96**. In the example implementation described herein, the residue distribution system **48** includes both the slope sensor **52** and the weather sensor **54**. However, in other implementations, the residue distribution system **48** may include only the slope sensor **52**, or only the weather sensor **54**.

(48) The controller **68** may determine the slope angle **56** and the wind vector **58** from the data received from the slope sensor **52** and the weather sensor **54** respectively. Once the slope angle **56** and the wind vector **58** have been determined, the controller **68** may then determine a desired position of the residue distributor **96** based on the slope angle **56** and the wind vector **58**. For example, referring to FIG. **3**, the controller **68** may identify an uphill side **118** and a downhill side **120** of the harvester implement **20**, and communicate the control signal to the fin actuator **110** to move the fins **98** into the one of the first position **100** or the second position **102** located on the

uphill side **118** of the harvester implement **20**. By so doing, the residue distributor **96** increases the discharge density on the uphill side **118** of the harvester implement **20** to counteract the effects of gravity on the broadcast crop residue **26** as described above. Alternatively, referring to FIG. **1**, the controller **68** may identify an upwind side **122** and a downwind side **124** of the harvester implement **20**, and communicate the control signal to the fin actuator **110** to move the fins **98** into the one of the first position **100** or the second position **102** located on the upwind side **122** of the harvester implement **20**. By so doing, the residue distributor **96** increases the discharge density on the upwind side **122** of the harvester implement **20** to counteract the effects of the wind on the broadcast crop residue **26** as described above.

(49) It should be appreciated that the uphill side **118** of the harvester implement **20** and the upwind side **122** of the harvester implement **20** may be located on the same side of the harvester implement **20**, or may be located on different sides of the harvester implement **20**. When the upwind side **122** and the uphill side **118** are located on the same side of the harvester implement **20**, the effects of the wind vector **58** and the effects of gravity on the broadcast crop residue **26** are combined, thereby requiring a higher discharge density on that side of the harvester implement **20**. However, if the upwind side **122** and the uphill side **118** of the harvester implement **20** are located on different side of the harvester implement **20**, the effects of the wind vector **58** and the effects of gravity on the broadcast crop residue **26** act in opposition to each other, and the discharge density may not need to be increased significantly in order to evenly distribute the crop residue **26** over the residue distribution width **88**.

(50) It should be appreciated that the controller **68** may control the residue distributor **96** into one or more intermediate positions **104** based on a magnitude of the slope angle **56** and/or the wind vector **58**. For example, the controller **68** may control the residue distributor **96** into the first position **100** when the wind vector **58** and/or the slope angle **56** are greater than a defined threshold, and position the residue distributor **96** into one or more intermediate positions **104**, such as shown in FIG. **6**, when the wind vector **58** and/or the slope angle **56** are greater than a minimum value but less than the defined threshold. As such, the position of the residue distributor **96** may be controlled based on a magnitude of the wind vector **58** and/or the slope angle **56**.

(51) One example implementation of the residue distributor **96** is described above and shown in FIGS. **4-6**. However, it should be appreciated that the residue distributor **96** may be configured differently than the example implementation described above. For example, referring to FIG. **7**, in another implementation, the residue distributor **96** may include an air system **126** positioned to discharge a flow of pressurized air **128** into the flow channel **72** through one or more nozzles **130**. The air system **126** may be selectively controllable between a first configuration to direct the flow of the crop residue **26** toward the first lateral side **80** of the flow channel **72**, and a second configuration to direct the flow of the crop residue **26** toward the second lateral side **82** of the flow channel **72**. The air system **126** may be controlled to vary a pressure of the flow of pressurized air **128** to vary and/or control the percentage of the crop residue **26** moved laterally relative to the longitudinal axis **30**, and thereby vary and/or control the discharge density.

(52) In yet another implementation, referring to FIG. **8**, the residue distributor **96** may include a conveyor system **132**. The conveyor system **132** may be positioned within the flow channel **72**. The conveyor system **132** may include an endless belt **134** having a plurality of flights **136** that move laterally across the flow channel **72**. The conveyor system **132** may be configured to rotate or move in a first lateral direction **138** relative to the longitudinal axis **30** to direct the flow of the crop residue **26** toward the first lateral side **80** of the flow channel **72**, and move in an opposite second lateral direction **140** relative to the longitudinal axis **30** to direct the flow of the crop residue **26** toward the second lateral side **82** of the flow channel **72**. The conveyor system **132** may be controlled to vary a speed of the endless belt **134** to vary and/or control the percentage of the crop residue **26** moved laterally relative to the longitudinal axis **30**, and thereby vary and/or control the discharge density.

(53) In yet another implementation, the residue distributor **96** may include the controller **68** in communication with the separator **44** of the harvester implement **20**. The controller **68** may be configured to control a speed of the crop **22** separator **44** to direct the flow of the crop residue **26** toward one of the first lateral side **80** or the second lateral side **82** of the flow channel **72**. For example, the separator **44** may include a pair of parallel separators **44** extending along the longitudinal axis **30** and positioned on opposing sides of the flow channel **72**, i.e., one separator **44** on the first lateral side **80**, and a second separator **44** on the second lateral side **82**. By increasing the speed of one of the separators **44**, the output from the separator **44** on that side of the flow channel **72** may be increased, thereby directing the crop residue **26** toward that side of the flow channel **72**.

(54) While different implementations of the residue distributor **96** are described herein, it should be appreciated that the residue distributor **96** is not limited to any one implementation, and that the residue distributor **96** may be configured differently than the example implementations described herein.

(55) As used herein, “e.g.” is utilized to non-exhaustively list examples, and carries the same meaning as alternative illustrative phrases such as “including,” “including, but not limited to,” and “including without limitation.” As used herein, unless otherwise limited or modified, lists with elements that are separated by conjunctive terms (e.g., “and”) and that are also preceded by the phrase “one or more of,” “at least one of,” “at least,” or a like phrase, indicate configurations or arrangements that potentially include individual elements of the list, or any combination thereof. For example, “at least one of A, B, and C” and “one or more of A, B, and C” each indicate the possibility of only A, only B, only C, or any combination of two or more of A, B, and C (A and B; A and C; B and C; or A, B, and C). As used herein, the singular forms “a”, “an” and “the” are intended to include the plural forms as well, unless the context clearly indicates otherwise. Further, “comprises,” “includes,” and like phrases are intended to specify the presence of stated features, steps, operations, elements, and/or components, but do not preclude the presence or addition of one or more other features, steps, operations, elements, components, and/or groups thereof.

(56) The detailed description and the drawings or figures are supportive and descriptive of the disclosure, but the scope of the disclosure is defined solely by the claims. While some of the best modes and other embodiments for carrying out the claimed teachings have been described in detail, various alternative designs and embodiments exist for practicing the disclosure defined in the appended claims.

## Claims

1. A residue distribution system for a harvester implement, the residue distribution system comprising: a housing defining a flow channel extending along a longitudinal axis and configured for conducting a flow of a crop residue therethrough in a direction moving from an upstream end of the flow channel toward a downstream end of the flow channel, the flow channel having a first lateral side disposed on a first side of the longitudinal axis, and a second lateral side disposed on a second side of the longitudinal axis; a spreader positioned proximate the downstream end of the flow channel and operable to broadcast the flow of the crop residue across a residue distribution width extending perpendicular to the longitudinal axis; a residue distributor positioned within the flow channel and upstream of the spreader, wherein the residue distributor is configured to direct the flow of the crop residue toward one of the first lateral side and the second lateral side of the flow channel to increase a mass flow rate of the crop residue passing through the spreader on the one of the first lateral side and the second lateral side of the flow channel, whereby a discharge density of the flow of the crop residue on the one of the first lateral side and the second lateral side is increased; and a chopper operable to cut the crop residue, wherein the chopper is positioned within the flow channel between the residue distributor and the spreader, such that the residue



distributor is positioned upstream of the chopper.

2. The residue distribution system set forth in claim 1, wherein the residue distributor includes at least one fin selectively controllable between a first position operable to direct the flow of the crop residue toward the first lateral side of the flow channel, and a second position operable to direct the flow of the crop residue toward the second lateral side of the flow channel.
3. The residue distribution system set forth in claim 2, wherein the at least one fin includes a plurality of fins arranged across a width of the flow channel transverse to the longitudinal axis.
4. The residue distribution system set forth in claim 2, wherein the at least one fin is selectively controllable into at least one intermediate position disposed between the first position and the second position.
5. The residue distribution system set forth in claim 2, further comprising a fin actuator coupled to the at least one fin and operable to move the at least one fin between the first position and the second position.
6. The residue distribution system set forth in claim 5, wherein the fin actuator includes one of a linear actuator operable to extend in a first linear direction and retract in a second linear direction opposite the first linear direction, and a rotary actuator operable to rotate in a first rotational direction and a second rotational direction opposite the first rotational direction.
7. The residue distribution system set forth in claim 5, further comprising a slope sensor arranged to detect data related to a slope angle of a ground surface, wherein the slope angle is an angle formed between the ground surface and a horizontal plane in a direction perpendicular to the longitudinal axis.
8. The residue distribution system set forth in claim 7, wherein the slope sensor includes a roll angle sensor operable to detect a roll angle of the housing relative to the horizontal plane.
9. The residue distribution system set forth in claim 7, wherein the slope sensor includes a Global Positioning System sensor operable to detect a location of the housing on the ground surface, and topographic data related to an elevation profile of the ground surface in a region surrounding the location of the housing.
10. The residue distribution system set forth in claim 7, further comprising a controller in communication with the slope sensor and the fin actuator, wherein the controller includes a processor and a memory having a distribution algorithm stored thereon, wherein the processor is operable to execute the distribution algorithm to control the at least one fin between the first position and the second position based on the slope angle detected by the slope sensor.
11. The residue distribution system set forth in claim 5, further comprising a weather sensor arranged to detect data related to a wind velocity relative to the housing and a wind direction relative to the longitudinal axis.
12. The residue distribution system set forth in claim 11, further comprising a controller in communication with the weather sensor and the fin actuator, wherein the controller includes a processor and a memory having a distribution algorithm stored thereon, wherein the processor is operable to execute the distribution algorithm to control the at least one fin between the first position and the second position based on the wind direction relative to the longitudinal axis and the wind velocity relative to the housing.
13. The residue distribution system set forth in claim 5, further comprising a residue distribution sensor positioned to detect data related to distribution of the crop residue perpendicular to the longitudinal axis.
14. The residue distribution system set forth in claim 13, wherein the residue distribution sensor includes one of a camera, a lidar sensor, a radar sensor, a thermal sensor, or an infrared light sensor.
15. The residue distribution system set forth in claim 13, further comprising a controller in communication with the residue distribution sensor and the fin actuator, wherein the controller includes a processor and a memory having a distribution algorithm stored thereon, wherein the processor is operable to execute the distribution algorithm to control the at least one fin between

the first position and the second position based on the distribution of the crop residue perpendicular to the longitudinal axis.

16. A harvester implement for harvesting a crop, the harvester implement comprising: a frame extending along a longitudinal axis; a harvester head coupled to the frame and operable to reap the crop; a separator attached to the frame and positioned to receive the crop from the harvester head, wherein the separator is operable to separate the crop material into a grain portion and a crop residue; a housing defining a flow channel extending along the longitudinal axis, wherein the flow channel is positioned to receive a flow of the crop residue from the separator, and is configured for conducting the flow of the crop residue therethrough in a direction moving from an upstream end of the flow channel proximate the separator toward a downstream end of the flow channel, the flow channel having a first lateral side disposed on a first side of the longitudinal axis, and a second lateral side disposed on a second side of the longitudinal axis; a spreader positioned proximate the downstream end of the flow channel and operable to broadcast the flow of the crop residue across a residue distribution width extending perpendicular to the longitudinal axis; a residue distributor positioned within the flow channel and upstream of the spreader, wherein the residue distributor is configured to direct the flow of the crop residue toward one of the first lateral side and the second lateral side of the flow channel to increase a mass flow rate of the crop residue passing through the spreader on the one of the first lateral side and the second lateral side of the flow channel, whereby a discharge density of the flow of the crop residue on the one of the first lateral side and the second lateral side is increased; and a chopper operable to cut the crop residue, wherein the chopper is positioned within the flow channel between the residue distributor and the spreader, such that the residue distributor is positioned upstream of the chopper.

17. The harvester implement set forth in claim 16, further comprising a controller including a processor and a memory having a distribution algorithm stored thereon, wherein the processor is operable to execute the distribution algorithm to control the residue distributor between a first position operable to direct the flow of the crop residue toward the first lateral side of the flow channel, and a second position operable to direct the flow of the crop residue toward the second lateral side of the flow channel.

18. The harvester implement set forth in claim 17, further comprising a slope sensor arranged to detect data related to a slope angle of a ground surface, wherein the slope angle is an angle formed between the ground surface and a horizontal plane in a direction perpendicular to the longitudinal axis, wherein the processor is operable to execute the distribution algorithm to control the residue distributor between the first position and the second position based on the slope angle detected by the slope sensor.

19. The harvester implement set forth in claim 17, further comprising a weather sensor arranged to detect data related to a wind velocity relative to the housing and a wind direction relative to the longitudinal axis, wherein the processor is operable to execute the distribution algorithm to control the residue distributor between the first position and the second position based on the wind direction relative to the longitudinal axis and the wind velocity relative to the housing.

20. The harvester implement set forth in claim 17, further comprising a residue distribution sensor positioned to detect data related to distribution of the crop residue perpendicular to the longitudinal axis, wherein the processor is operable to execute the distribution algorithm to control the residue distributor between the first position and the second position based on the distribution of the crop residue perpendicular to the longitudinal axis.

21. The harvester implement set forth in claim 16, wherein the residue distributor includes at least one fin selectively controllable between a first position operable to direct the flow of the crop residue toward the first lateral side of the flow channel, and a second position operable to direct the flow of the crop residue toward the second lateral side of the flow channel.

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