



US012391149B2

(12) **United States Patent**  
**Strashny et al.**

(10) **Patent No.:** **US 12,391,149 B2**  
(45) **Date of Patent:** **Aug. 19, 2025**

(54) **RELOCATABLE BASE FOR ELEVATED  
POWER RAILS AND METHOD OF  
DEPLOYMENT**

(71) Applicant: **Caterpillar Global Mining Equipment  
LLC**, Denison, TX (US)

(72) Inventors: **Igor Strashny**, Tucson, AZ (US); **Brian  
Robert Weller**, Chillicothe, IL (US)

(73) Assignee: **Caterpillar Global Mining Equipment  
LLC**, Denison, TX (US)

(\*) Notice: Subject to any disclaimer, the term of this  
patent is extended or adjusted under 35  
U.S.C. 154(b) by 843 days.

(21) Appl. No.: **17/563,317**

(22) Filed: **Dec. 28, 2021**

(65) **Prior Publication Data**

US 2023/0202348 A1 Jun. 29, 2023

(51) **Int. Cl.**  
**B60M 1/02** (2006.01)  
**B60M 1/30** (2006.01)

(52) **U.S. Cl.**  
CPC ..... **B60M 1/02** (2013.01); **B60M 1/30**  
(2013.01)

(58) **Field of Classification Search**  
CPC ..... B60M 1/02; B60M 1/30  
See application file for complete search history.

(56) **References Cited**

U.S. PATENT DOCUMENTS

3,080,982 A 3/1963 Borchardt  
3,352,491 A 11/1967 Permil

3,826,881 A 7/1974 Springer  
4,681,302 A 7/1987 Thompson  
4,954,009 A \* 9/1990 Kellison ..... E01F 15/083  
404/6

4,955,753 A \* 9/1990 McKay ..... E01F 15/088  
404/6

5,011,325 A 4/1991 Antonioli  
(Continued)

**FOREIGN PATENT DOCUMENTS**

AU 2009353352 B2 \* 10/2013 ..... E01F 15/083  
AU 751778 B2 \* 3/2014

(Continued)

**OTHER PUBLICATIONS**

Written Opinion and International Search Report for Int'l. Patent  
Appl. No. PCT/US2022/051790, mailed Apr. 20, 2023 (12 pgs).

(Continued)

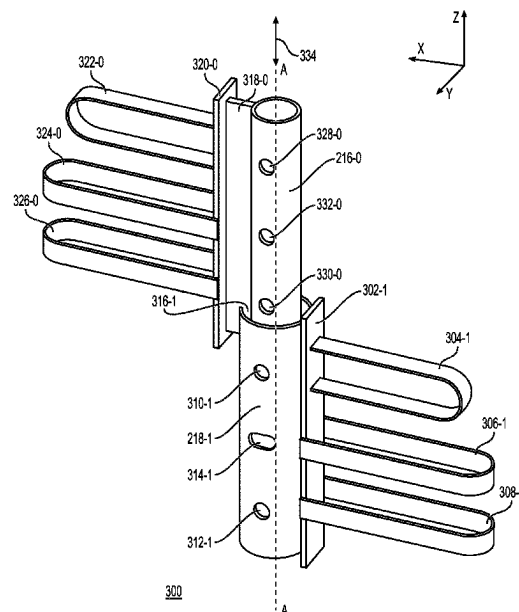
*Primary Examiner* — Jason C Smith

(74) *Attorney, Agent, or Firm* — Lee & Hayes

(57) **ABSTRACT**

A modular structure supports elevated rail segments for delivering electrical power to a moving work machine, such as a hauler at a mining site. Opposite ends of a roadside barrier contain complementary tubular couplers arranged vertically, one having a first diameter supported by an arm and the other having a larger second diameter and a vertical slot. Couplers on adjacent barriers can be mated together concentrically along a central axis. The mated couplers help restrict longitudinal displacement, lateral displacement, slope change, and lateral rotation between adjacent barriers during placement. One barrier may be used as a temporary alignment structure to position barriers spaced alternately along a haul route for the work machine.

**20 Claims, 14 Drawing Sheets**



(56)

**References Cited****U.S. PATENT DOCUMENTS**

5,074,704 A \* 12/1991 McKay ..... E01F 15/006  
404/6

5,123,773 A 6/1992 Yodock

6,848,857 B1 \* 2/2005 McColl ..... E01F 15/088  
404/6

8,152,408 B1 \* 4/2012 Tullis ..... E01F 13/12  
404/6

8,556,189 B2 \* 10/2013 Zhou ..... B60M 1/305  
238/14.6

2004/0168873 A1 \* 9/2004 Nunlist ..... B60M 1/305  
191/22 R

2007/0110517 A1 5/2007 Wasserstrom et al.

2008/0286041 A1 11/2008 Yodock, Jr. et al.

2014/0027603 A1 \* 1/2014 McCoy ..... H02G 3/30  
248/562

2015/0037991 A1 \* 2/2015 Bonzi ..... H01R 13/035  
439/216

2015/0337508 A1 11/2015 Torres, Jr.

2016/0264000 A1 9/2016 Zimmerman et al.

2017/0166084 A1 \* 6/2017 Tajima ..... B60L 53/35

2023/0202348 A1 \* 6/2023 Strashny ..... E01F 15/088  
104/2

2023/0203761 A1 \* 6/2023 Strashny ..... E01F 15/083  
104/2

**FOREIGN PATENT DOCUMENTS**

AU 2012307080 A1 \* 3/2014 ..... E01F 15/006

CA 1276911 C \* 11/1990 ..... E01F 15/006

CA 2536011 A1 8/2007

CH 443387 A 9/1967

CN 202623959 U 12/2012

CN 207257430 U 4/2018

EP 0428097 A1 5/1991

EP 1164222 A1 12/2001

EP 1182296 B1 \* 6/2004 ..... E01F 15/043

EP 1157167 B1 \* 11/2006 ..... E01F 15/086

EP 1766141 B1 \* 2/2008 ..... E01F 15/025

EP 2284635 A1 2/2011

EP 3091655 A1 11/2016

GB 2219332 A 12/1989

JP 05035454 5/1993

JP 5864173 B2 4/2013

JP 6138425 B2 11/2013

KR 20010088760 A 9/2001

KR 20100114310 A 10/2010

KR 20130001809 A 1/2013

KR 101689115 B1 12/2016

KR 20170118281 A \* 10/2017

KR 102094970 B1 \* 3/2020

WO 2013033766 A1 3/2013

WO 2013148536 A1 10/2013

WO WO-2020186296 A1 \* 9/2020

WO WO-2020249978 A1 \* 12/2020 ..... B60J 11/06

WO 2023129334 A1 7/2023

**OTHER PUBLICATIONS**

Written Opinion and International Search Report for Int'l. Patent Appln. No. PCT/US2022/080990, mailed Apr. 20, 2023 (9 pgs).

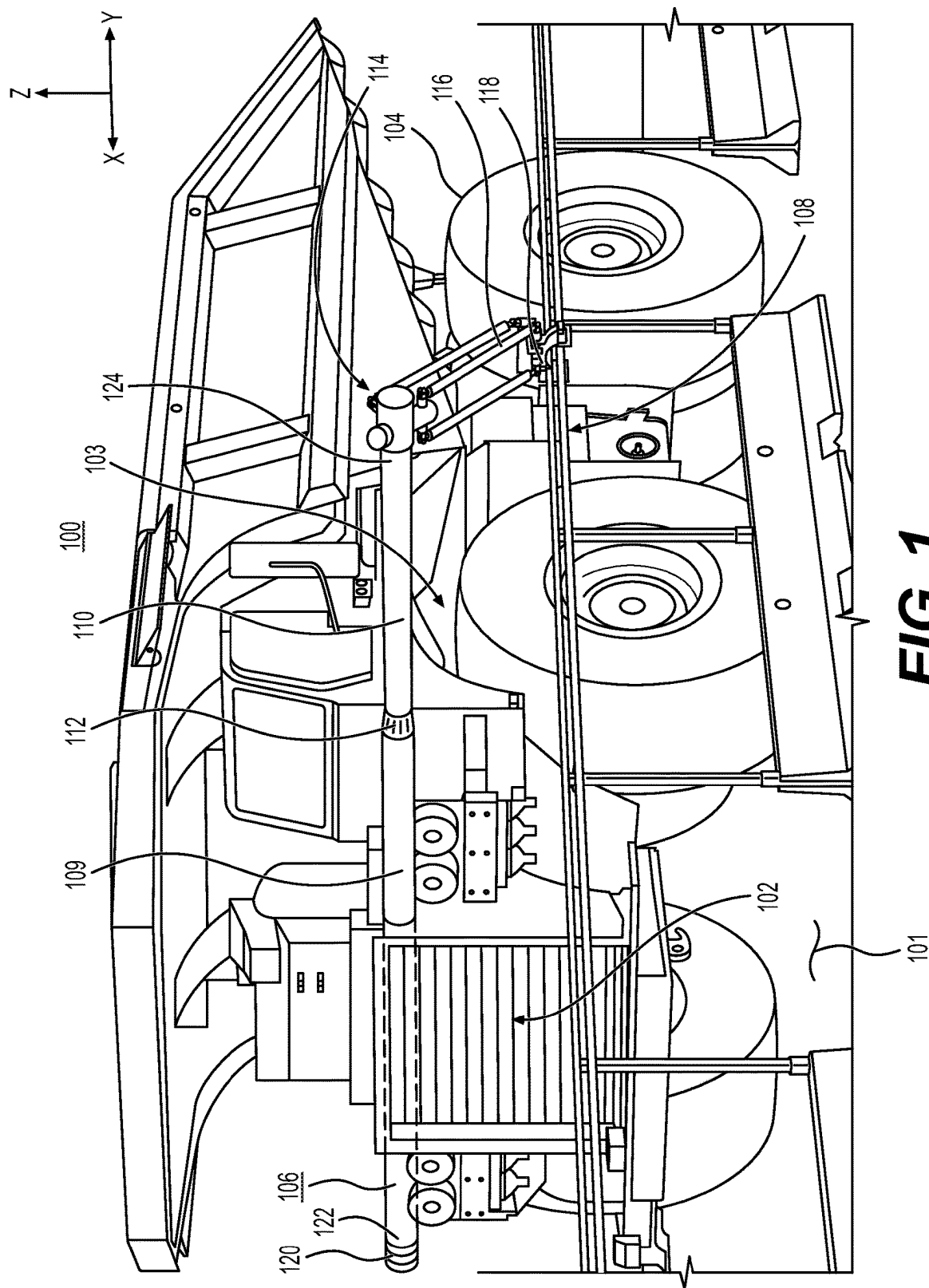
Written Opinion and International Search Report for Int'l. Patent Appln. No. PCT/US2022/051796 mailed Dec. 5, 2023 (11 pgs).

European Patent Office Search Reports for EP Patent Applications No. 24216965.4 & 24216967.0, mailed Mar. 3, 2025.

Written Opinion and European Search Report for EP Patent Appln. No. 24167967.9, mailed Jan. 1, 2025 (10 pgs).

Australian Road Barriers—Product Manual < URL: <https://web.archive.org/web/20210312022800/http://www.roadbarriers.com.au/docs/Australian-Road-Barriers-Product-Manual-Final.pdf>> Published on Mar. 12, 2021 as per Wayback Machine.

\* cited by examiner



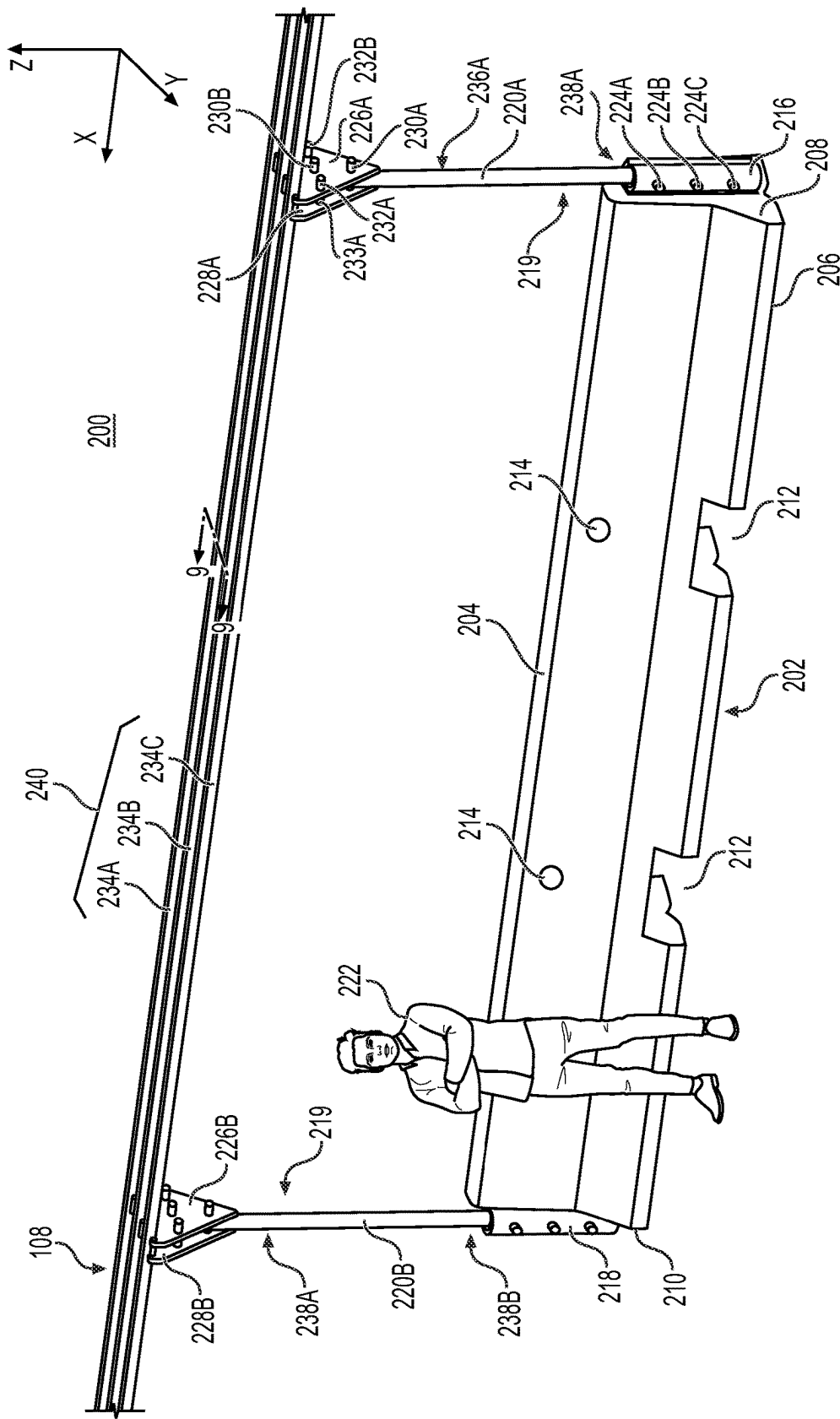
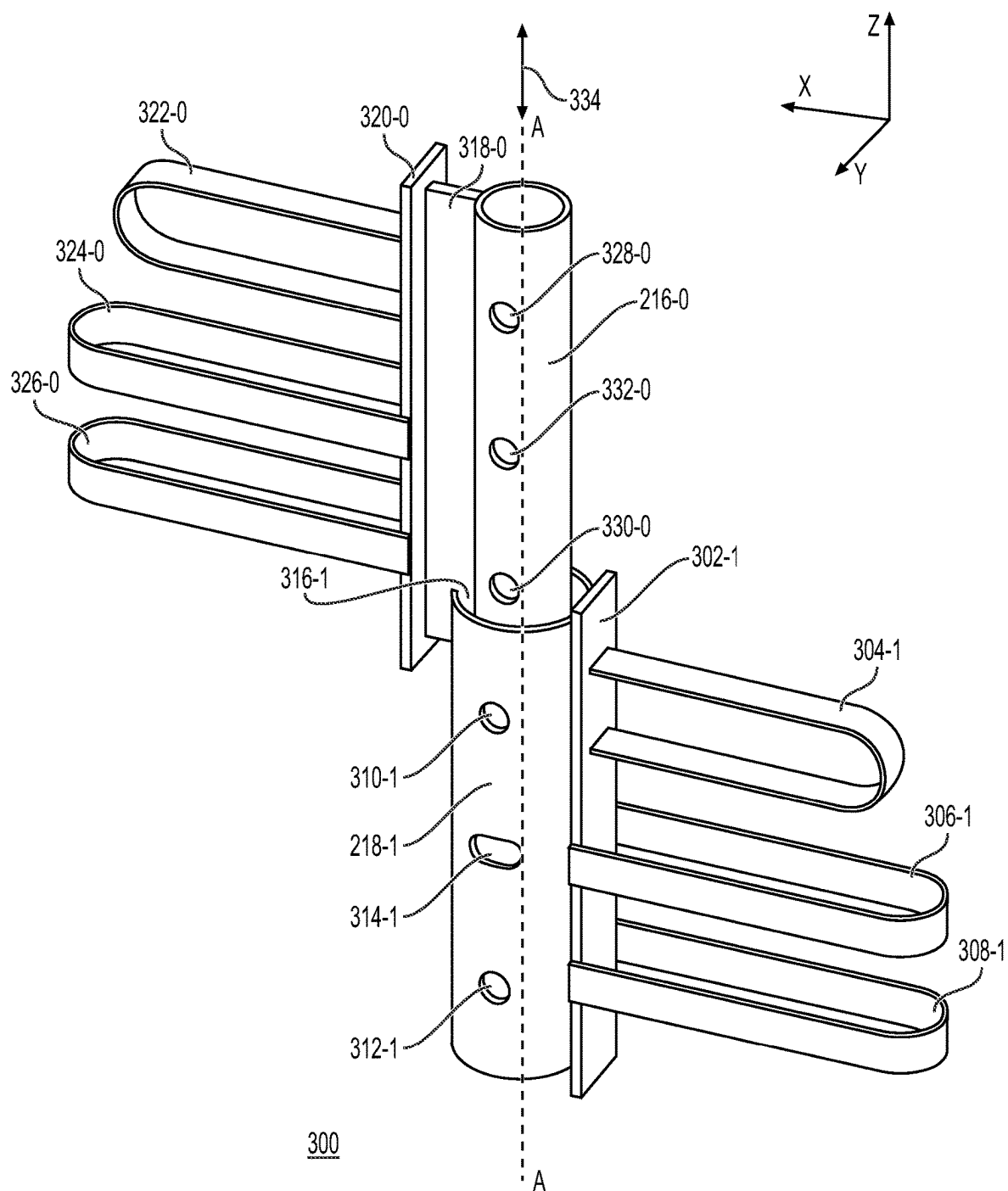
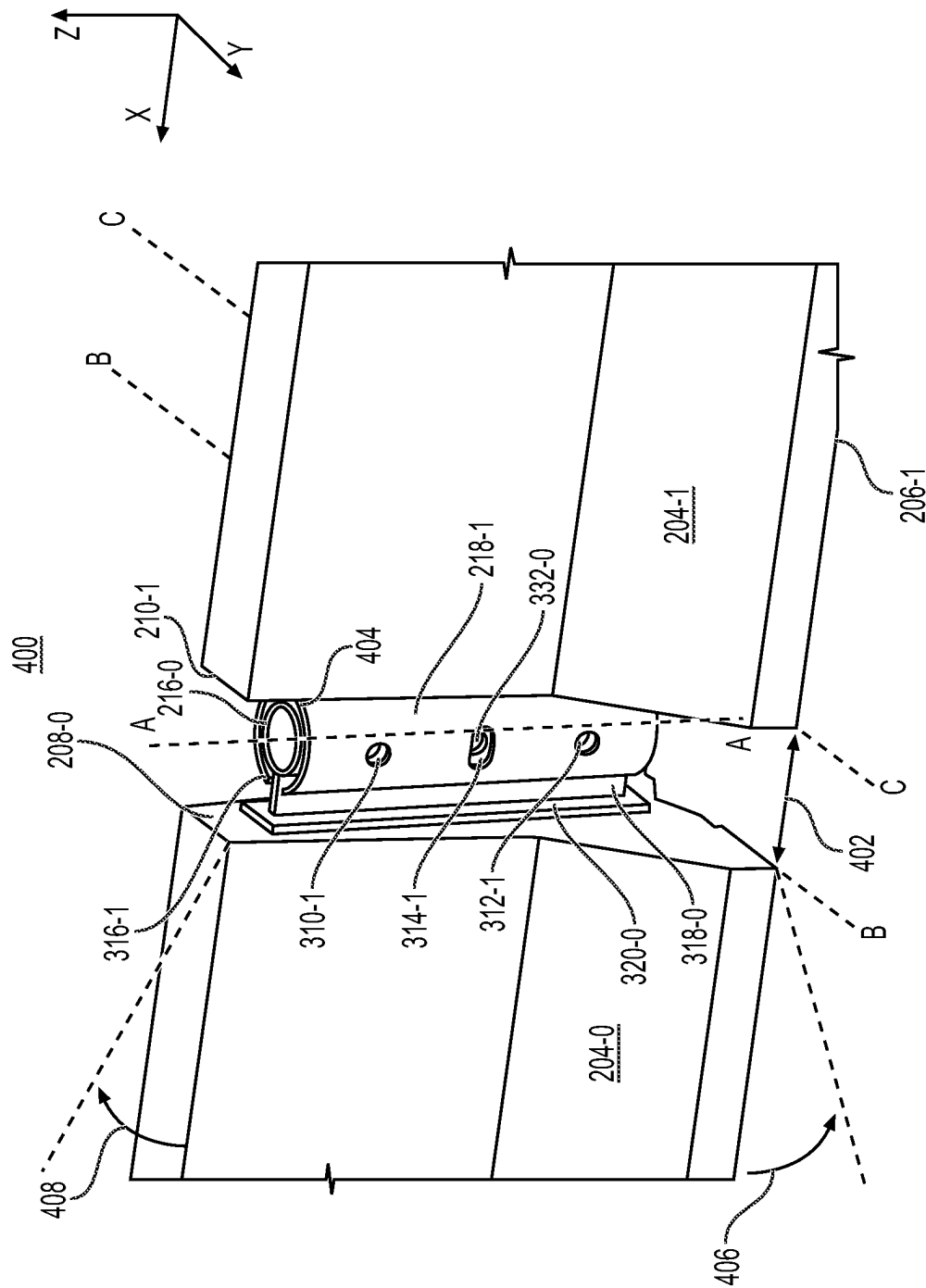


FIG. 2



**FIG. 3**



**FIG. 4**

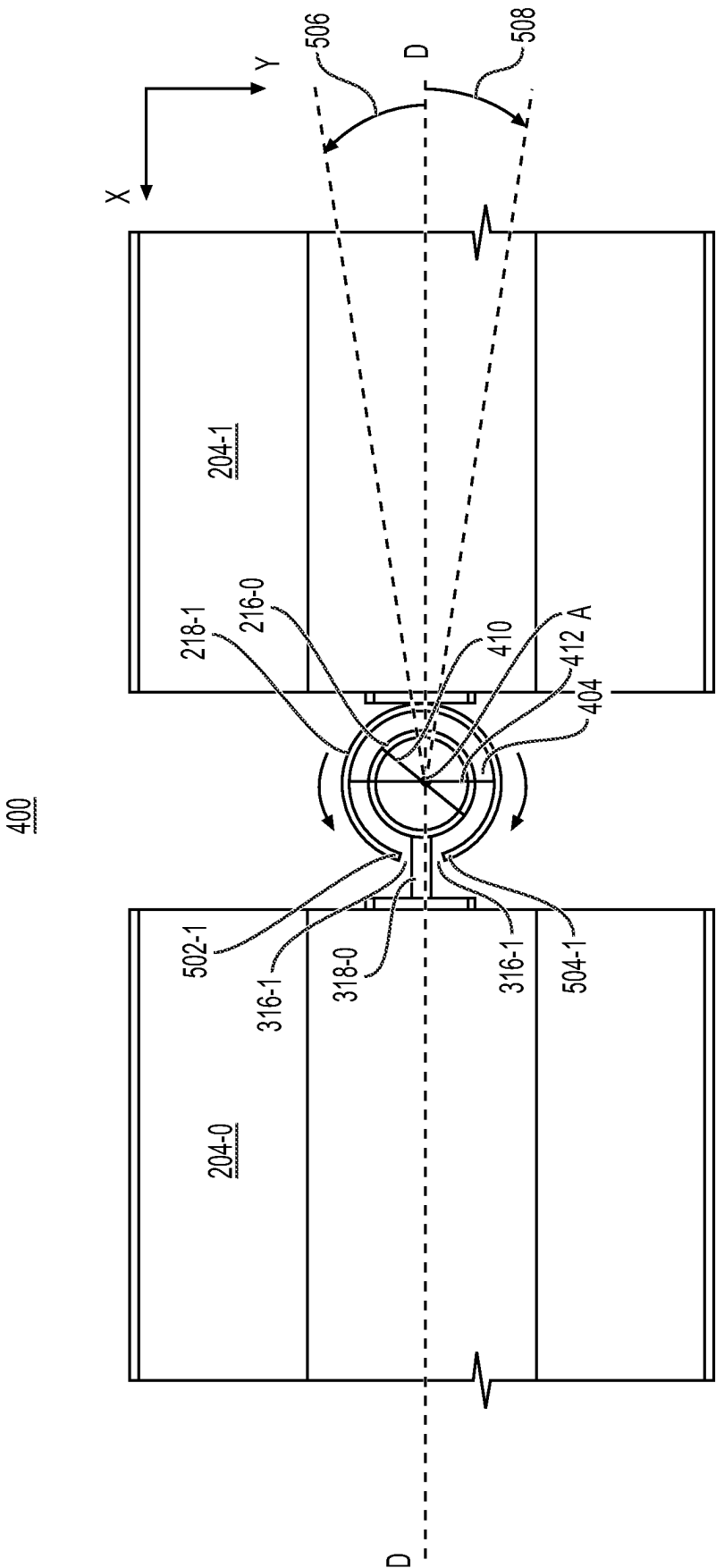


FIG. 5

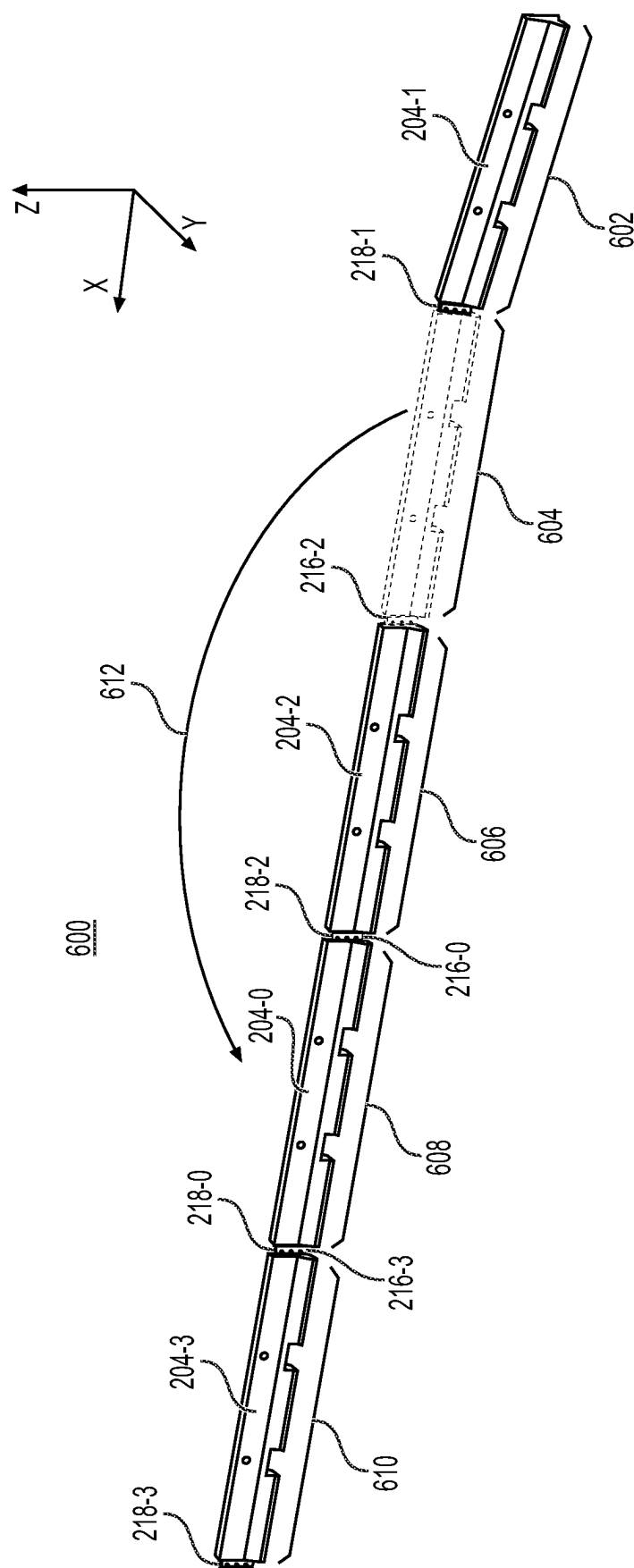
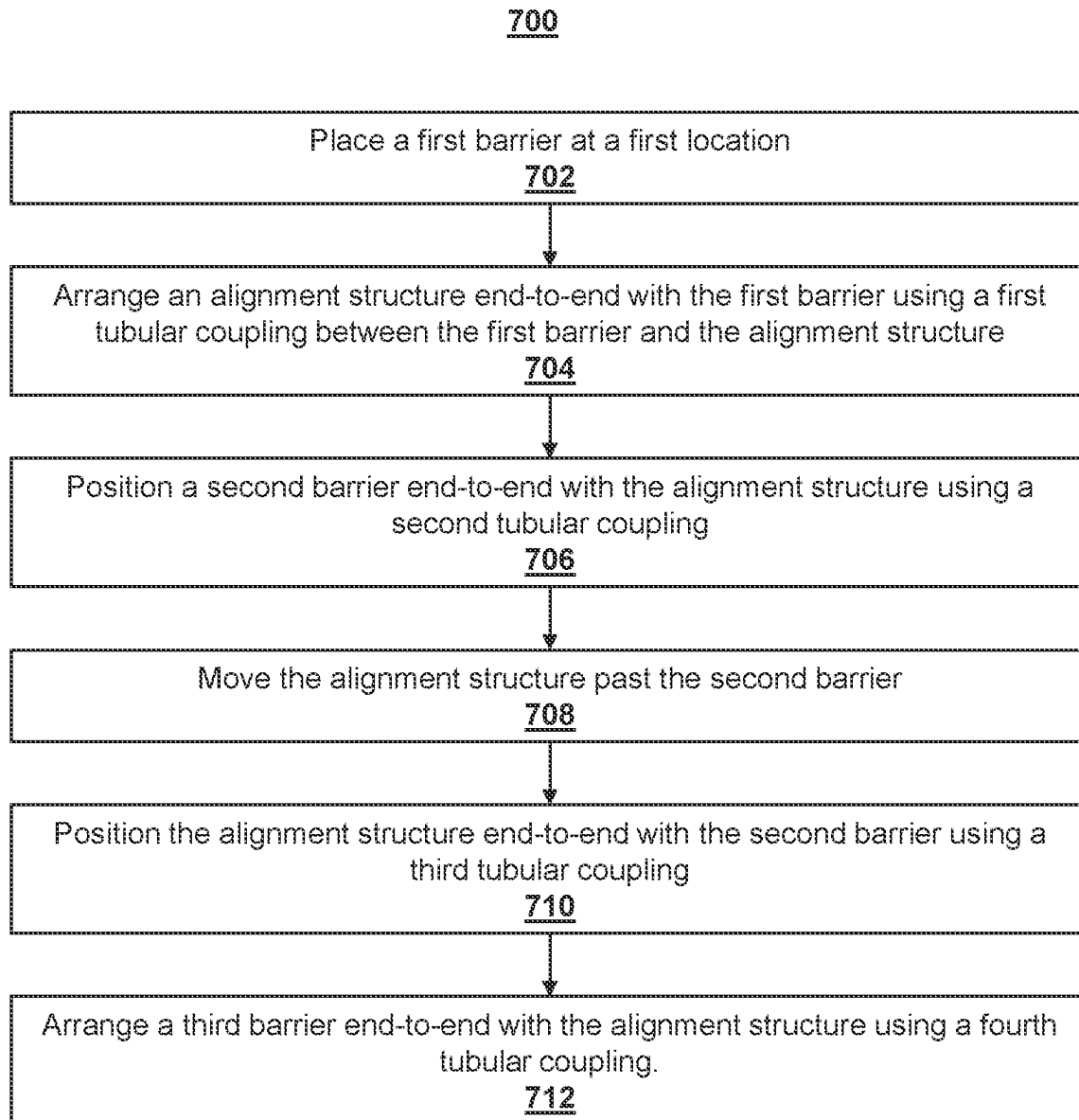
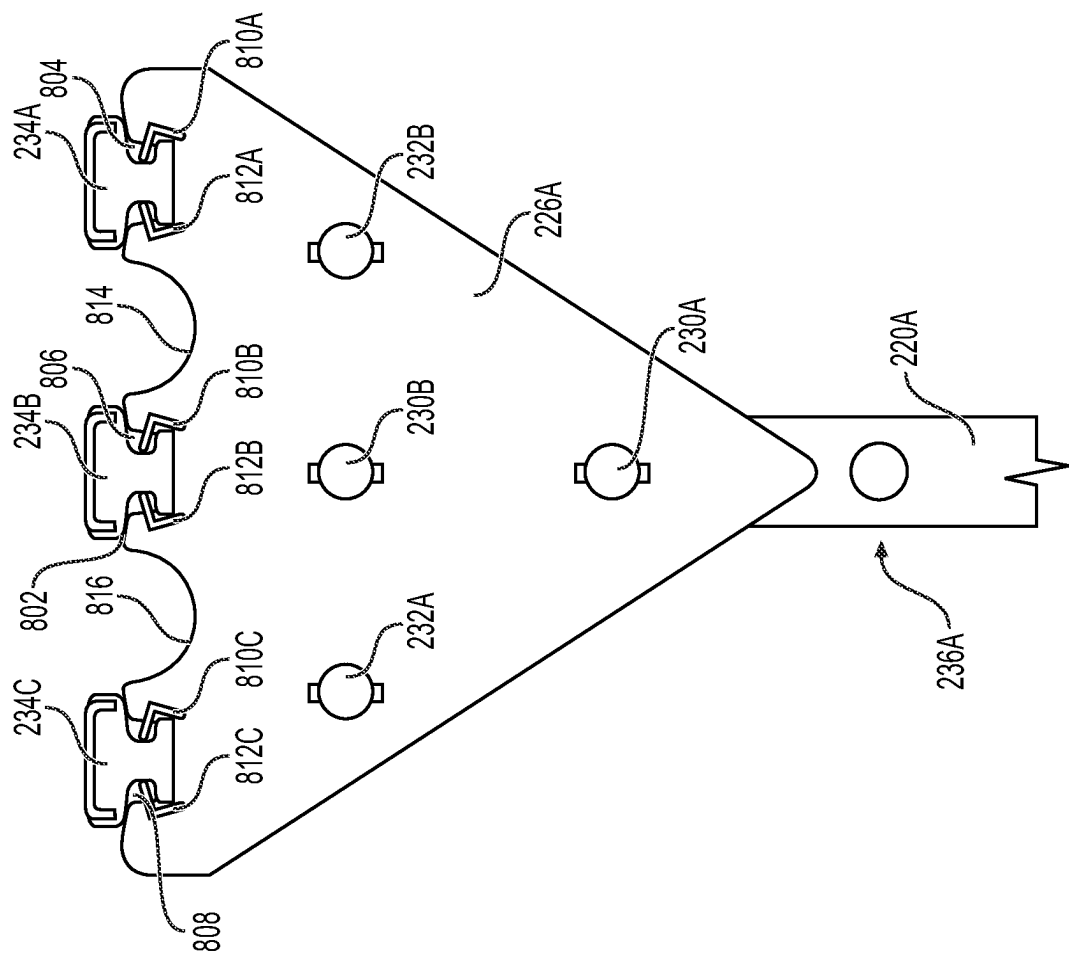


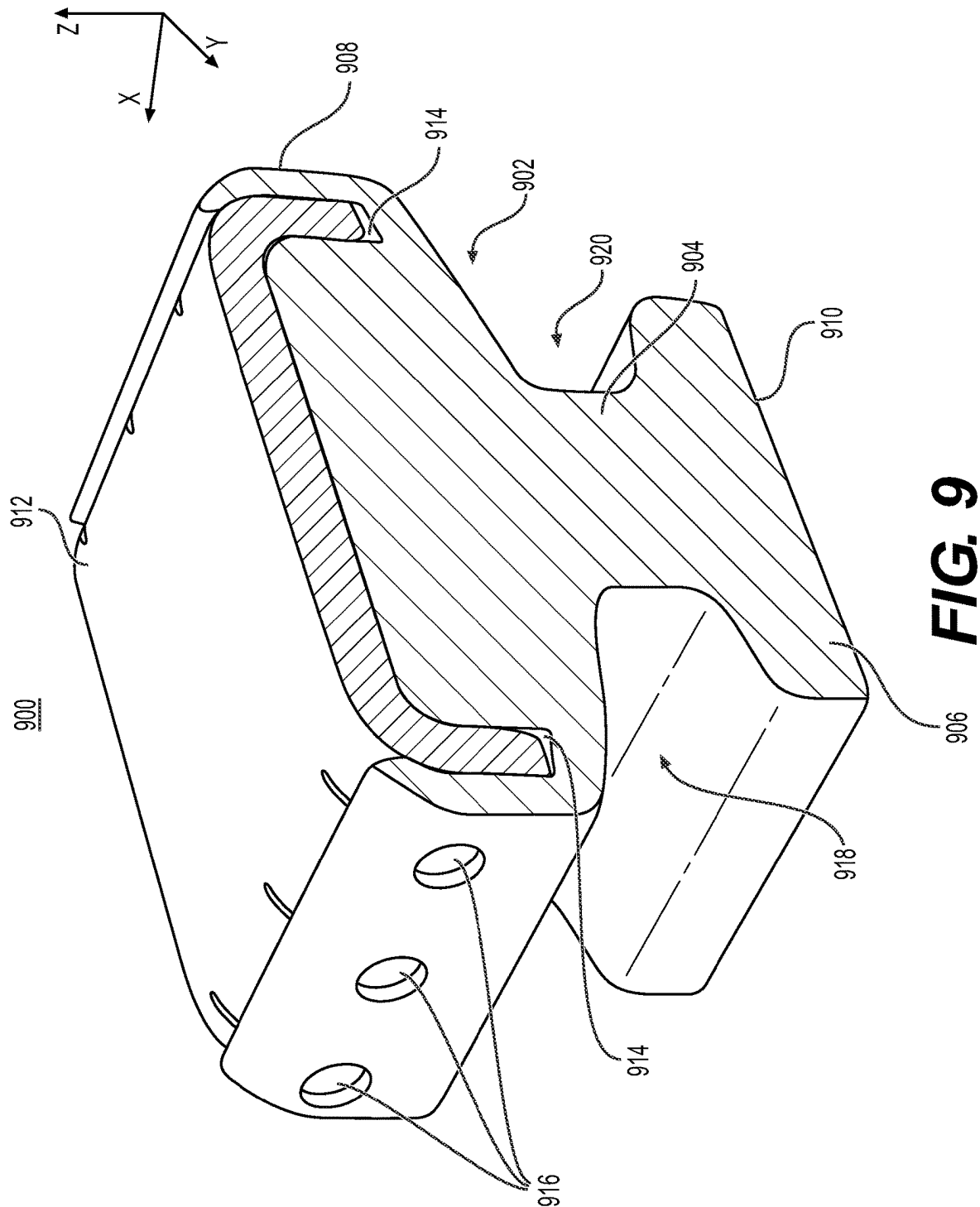
FIG. 6

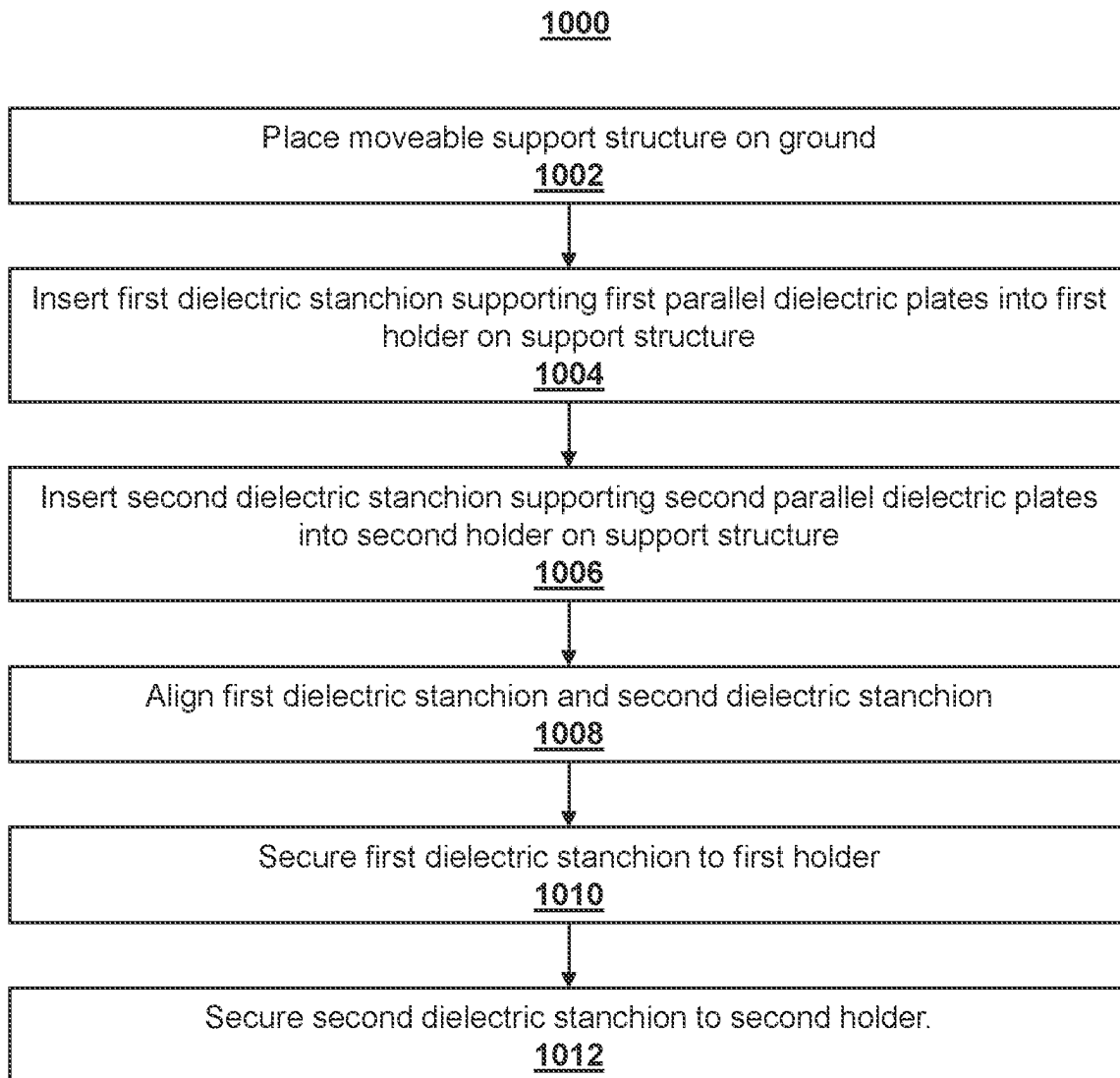


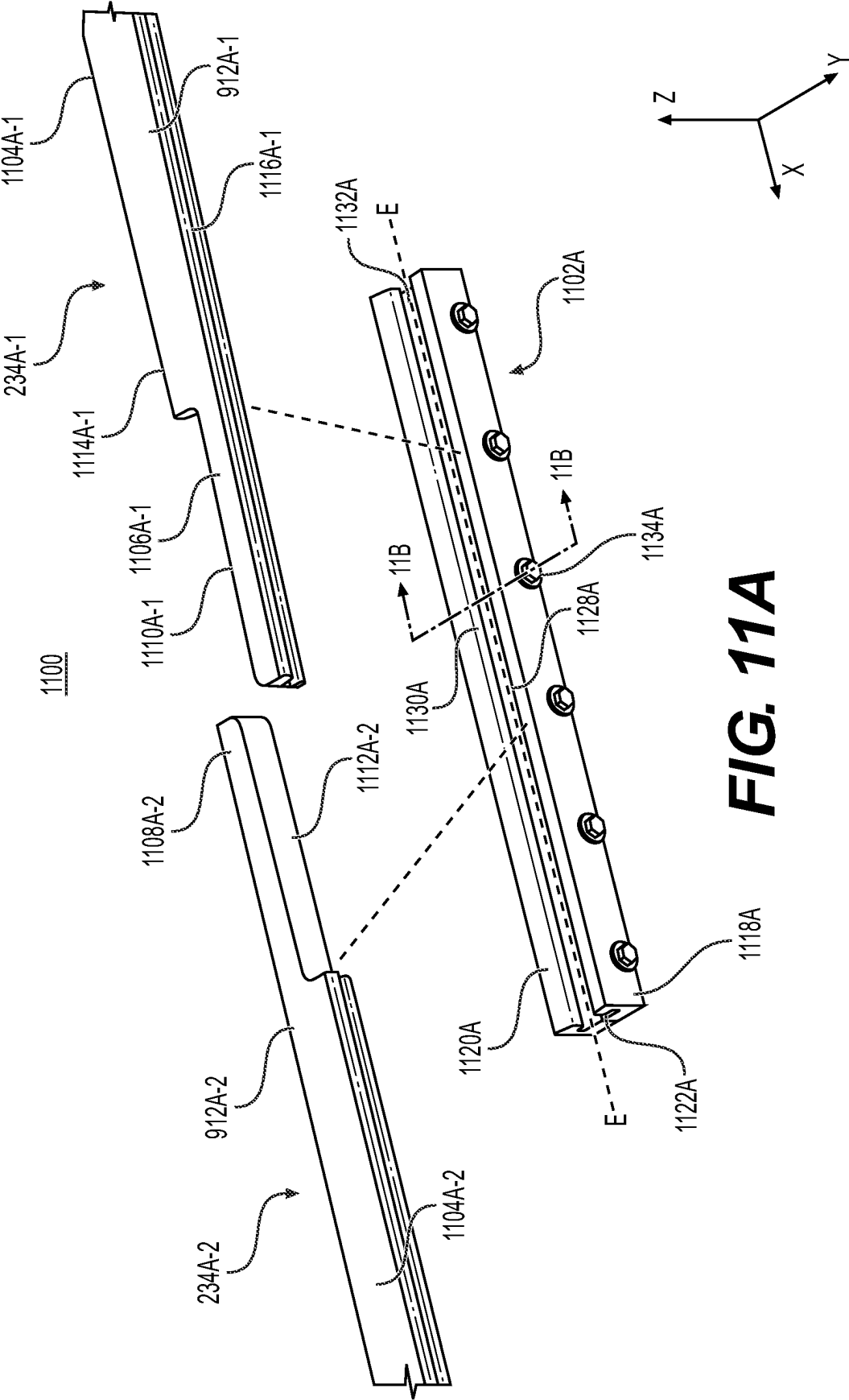
**FIG. 7**

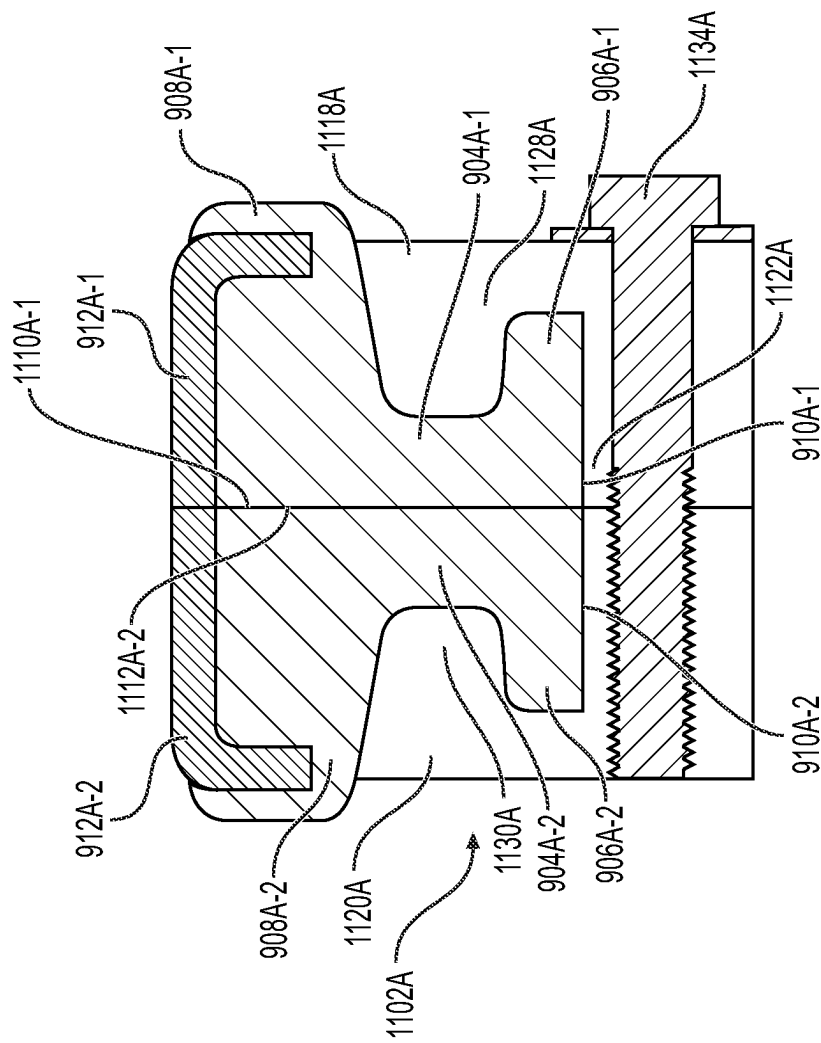


**FIG. 8**



**FIG. 10**





**FIG. 11B**

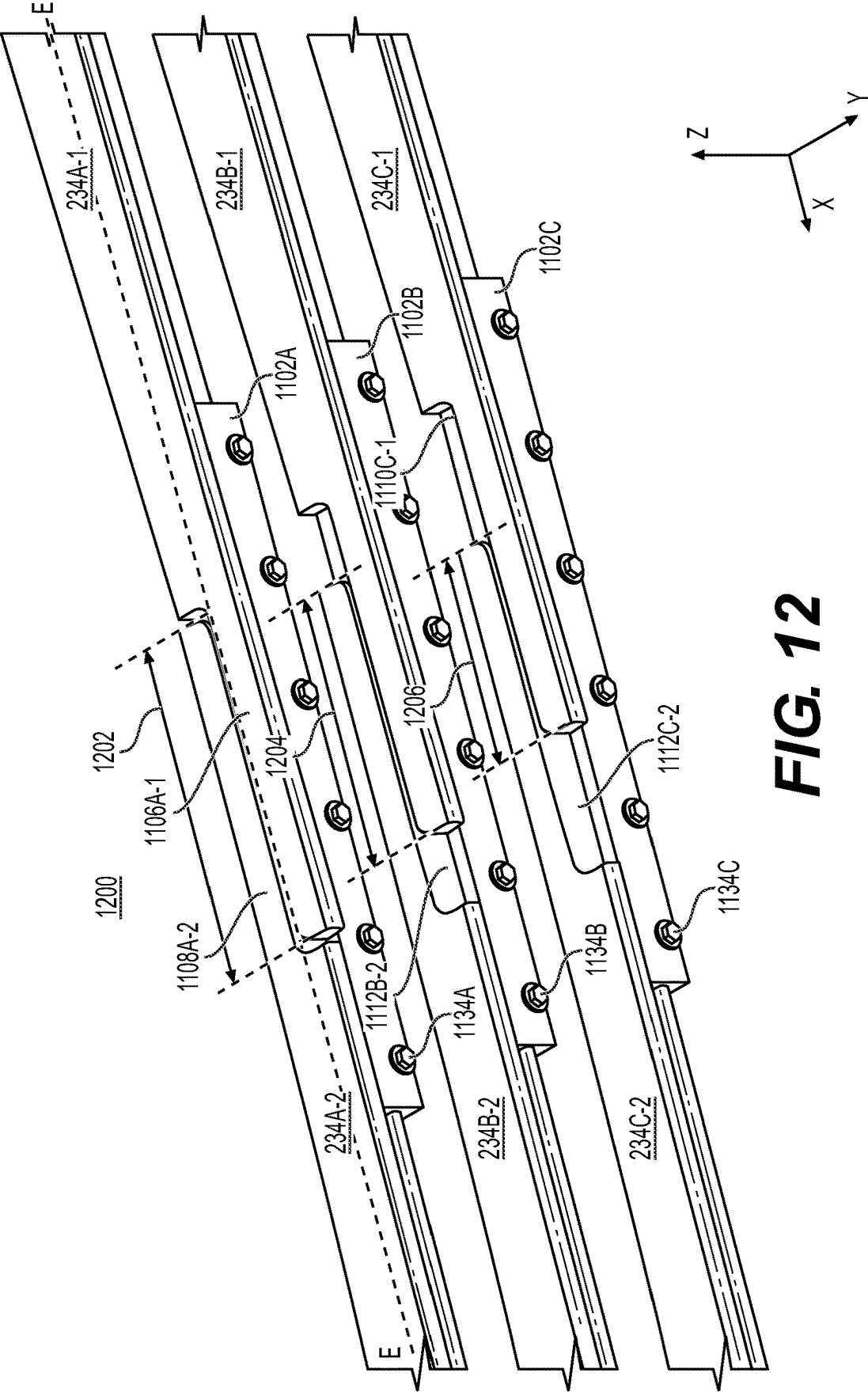
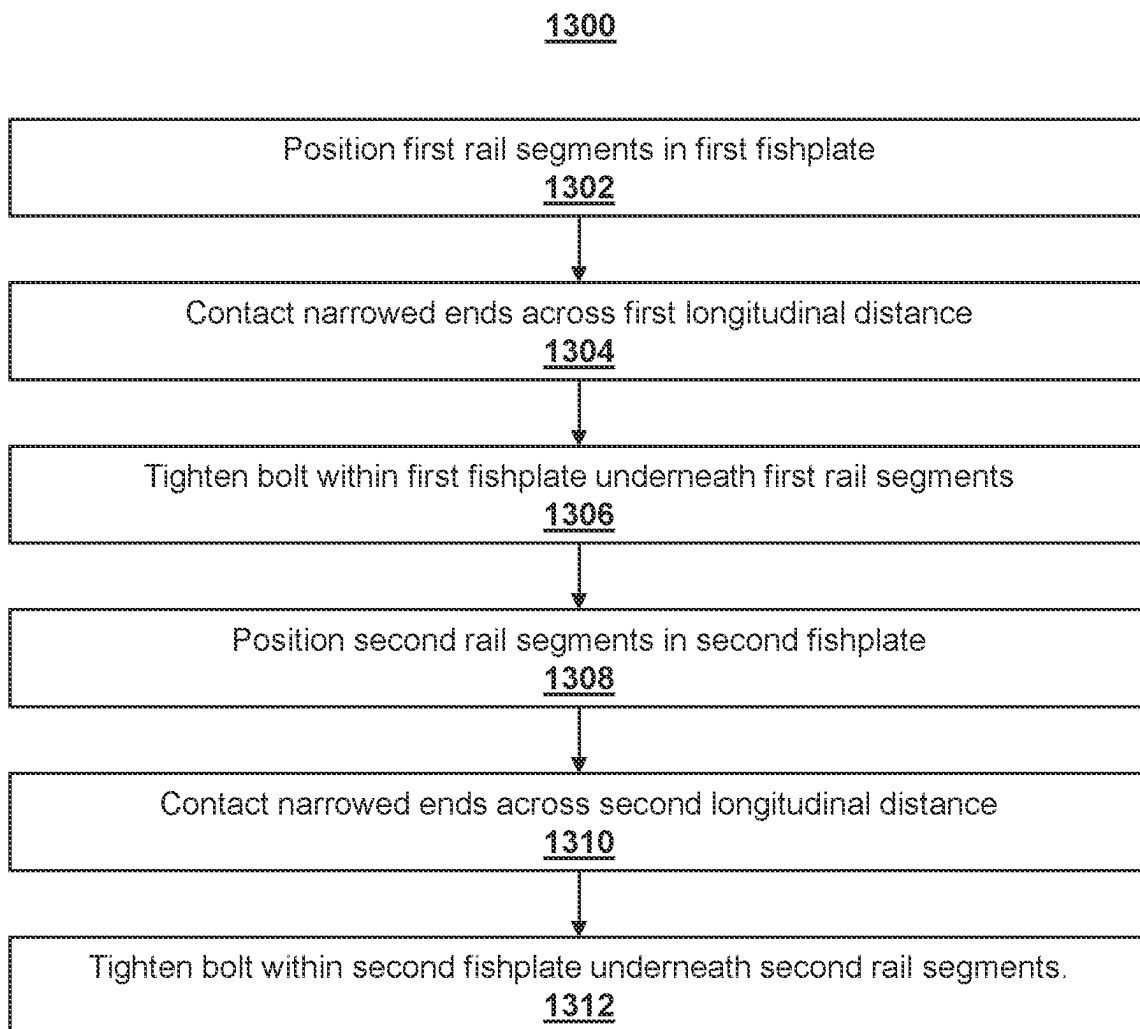


FIG. 12

**FIG. 13**



1

# RELOCATABLE BASE FOR ELEVATED POWER RAILS AND METHOD OF DEPLOYMENT

## TECHNICAL FIELD

The present disclosure relates to a system and method for supporting rails providing electrical power at a position elevated above ground using barriers. More specifically, the present disclosure relates to a modular support structure for power rails including one or more ground barriers having nested couplers configured to hold support posts and to adjust positioning of adjacent barriers in multiple dimensions.

## BACKGROUND

Heavy work machines, such as earth-moving vehicles or hauling trucks, require significant power to carry out their functions. The machines themselves can be of substantial weight, and their loads require large amounts of power to move. Diesel engines typically provide that power, but they can have disadvantages. For instance, in some implementations, heavy work machines may need to travel large distances through rugged terrain. At a remote mining site, for example, groups of these machines are often employed to ferry extreme loads along roadways, or haul routes, extending between various locations within the mining site. Supplies of diesel fuel may be far away from such locations or not easily delivered to such locations. In addition, the groups of diesel machines can generate significant pollution.

A power rail based on the ground may provide electrical power to traveling vehicles such as heavy work machines. In some environments, such as with trains or subways that travel on a fixed track, precise alignment between the fixed track and the power rail can ensure reliable delivery of electrical power as the vehicle moves. For a heavy work machine that is freely steerable, however, establishing and maintaining an electrical connection with a power rail can be particularly challenging.

In some environments, such as a mining site, the terrain can interfere with continuous connection with power rails for a freely steerable work machine along a haul route. The haul route may be uneven, hilly, and pocked, which can lead to steering deviations that could cause the machine to disconnect from the rail. Placement of power rails in some environments is temporary and relocatable, and curvatures and slopes within the haul route can lead to unexpected changes in position by the power rails. These variations can cause the machine to disconnect from the rail, detracting from the value of rail-based delivery of electrical power.

One approach for providing electrical power to a work machine while traveling on a roadway is described in International Patent App. Pub. No. WO 2020/186296A1 ("the '296 application"). The '296 application describes an electrical delivery system at a mine site for a moving vehicle where two or more conductors are anchored on the side of relocatable roadside barriers. According to the '296 application, the barriers may be connected by joints that are either compliant in one or more axes or, as shown in the disclosed embodiment, fully rigid for implementation on a relatively even road surface. The delivery system of the '296 application does not contemplate the angular positioning between barriers, such as with curvatures or slopes in the haul route, and the challenges of maintaining contact with the conductors. As a result, the barrier system of the '296 application

2

is not desirable for delivering electrical power to heavy work machines traveling across a haul route that may vary over diverse terrain.

Examples of the present disclosure are directed to overcoming deficiencies of such systems.

## SUMMARY

In an aspect of the present disclosure, a rail support module includes a barrier having a first end, a second end, and a base extending longitudinally between the first end and the second end. A first coupler is affixed to the first end and has an arm joining a first tubular portion to the first end. The first tubular portion extends about a first axis substantially orthogonal to the base and has an inner diameter and an outer diameter. A second coupler is affixed to the second end and has a second tubular portion extending about a second axis substantially orthogonal to the base. The second tubular portion has a first vertical edge and a second vertical edge extending substantially parallel to the second axis. The first vertical edge is separated from the second vertical edge by a gap, and the second tubular portion has an inner diameter greater than the outer diameter of the first tubular portion.

In another aspect of the present disclosure, a support assembly includes a first barrier having a first end extending substantially perpendicular to a first base and a second barrier having a second end, a third end opposite the second end, and a second base. The second end and the third end extend substantially perpendicular to the second base. The support assembly further includes a nested coupling between the first barrier and the second barrier. The nested coupling includes an exterior tubular structure affixed to the first end and extending with a first inner diameter about a vertical axis substantially perpendicular to the first base and a first vertical edge and a second vertical edge running substantially parallel to the vertical axis. The first vertical edge and the second vertical edge define a gap along the exterior tubular structure. The nested coupling also includes an arm affixed to the second end and positioned within the gap, and an interior tubular structure affixed to the arm. The interior tubular structure extends substantially perpendicular to the second base within the first inner diameter of the exterior tubular structure.

In yet another aspect of the present disclosure, a method includes placing a first support of oblong shape on ground surface substantially parallel to a vehicle travel path defined by the ground surface, where the first support has a first longitudinal axis, and arranging an alignment structure of the oblong shape end-to-end with the first support using a first tubular coupling. The first tubular coupling is configured such that the first longitudinal axis is substantially colinear with an alignment axis passing longitudinally through the alignment structure. The method includes positioning a second support of the oblong shape end-to-end with the alignment structure using a second tubular coupling, where the second tubular coupling is configured such that the alignment axis is substantially colinear with a second longitudinal axis of the second support. Further, the alignment structure is moved past the second support with respect to the vehicle travel path and positioned end-to-end with the second support using a third tubular coupling. The third tubular coupling is configured such that the alignment axis is substantially colinear with a third longitudinal axis of the third support.

## BRIEF DESCRIPTION OF DRAWINGS

FIG. 1 is an isometric view of an electrically powered work machine coupled to a roadside power source in accordance with an example of the present disclosure.

FIG. 2 is an isometric view of rail support module with power rails in accordance with an example of the present disclosure.

FIG. 3 is an isometric view of an engagement of an open coupler and a closed coupler between barrier assemblies in accordance with an example of the present disclosure.

FIG. 4 is an isometric view of a coupling between adjacent barrier assemblies in accordance with an example of the present disclosure.

FIG. 5 is a top view of the coupling between adjacent barrier assemblies of FIG. 4 in accordance with an example of the present disclosure.

FIG. 6 is a schematic of a deployment layout for barrier assemblies in accordance with an example of the present disclosure.

FIG. 7 is flowchart depicting a method for deploying barrier assemblies in accordance with an example of the present disclosure.

FIG. 8 is a partial front view of a support assembly with rail segments in accordance with an example of the present disclosure.

FIG. 9 is a partial cross-sectional view of a rail segment in FIG. 2 in accordance with an example of the present disclosure.

FIG. 10 is a flowchart of a method of deploying power rails in accordance with an example of the present disclosure.

FIG. 11A is an exploded view of a single rail joint of two rail segments within a fishplate in accordance with an example of the present disclosure.

FIG. 11B is a cross-sectional view of the single rail joint of FIG. 11A within a fishplate in accordance with an example of the present disclosure.

FIG. 12 is an isometric view of a collective rail joint of three rail segments within three fishplates traversing a curvature in accordance with an example of the present disclosure.

FIG. 13 is a flowchart of a method for joining rail segments in accordance with an example of the present disclosure.

## DETAILED DESCRIPTION

Wherever possible, the same reference numbers will be used throughout the drawings to refer to same or like parts. Multiple instances of like parts within a figure may be distinguished using a letter suffix. FIG. 1 illustrates an isometric view of a work machine 100 within an XYZ coordinate system as one example suitable for carrying out the principles discussed in the present disclosure. Exemplary work machine 100 travels parallel to the X axis along a roadway, also termed a haul route 101, typically from a source to a destination within a worksite. In one implementation as illustrated, work machine 100 is a hauling machine that hauls a load within or from a worksite within a mining operation. For instance, work machine 100 may haul excavated ore or other earthen materials from an excavation area along haul route 101 to dump sites and then return to the excavation area. In this arrangement, work machine 100 may be one of many similar machines configured to ferry earthen material in a trolley arrangement. While a large mining truck in this instance, work machine 100 may be any

machine that carries a load between different locations within a worksite, examples of which include an articulated truck, an off-highway truck, an on-highway dump truck, a wheel tractor scraper, or any other similar machine. Alternatively, work machine 100 may be an off-highway truck, on-highway truck, a dump truck, an articulated truck, a loader, an excavator, a pipe layer, or a motor grader. In other implementations, work machine 100 need not haul a load and may be any machine associated with various industrial applications including, but not limited to, mining, agriculture, forestry, construction, and other industrial applications.

Referring to FIG. 1, an example work machine 100 includes a frame 103 powered by electric engine 102 to cause rotation of traction devices 104. Traction devices 104 are typically four or more wheels with tires, although tracks or other mechanisms for engagement with the ground along haul route 101 are possible. Electric engine 102 functions to provide mechanical energy to work machine 100 based on an external electrical power source, such as described in further detail below. An example of mechanical energy provided by electric engine 102 includes propelling traction devices 104 to cause movement of work machine 100 along haul route 101, but electric engine 102 also includes components sufficient to power other affiliated operations within work machine 100. For instance, in some implementations, electric engine 102 includes equipment for converting electrical energy to provide pneumatic or hydraulic actions within work machine 100. While electric engine 102 is configured to operate from an external electrical power source, electric engine 102 typically includes one or more batteries for storing electrical energy for auxiliary or backup operations.

In accordance with the principles of the present disclosure, work machine 100 further includes a conductor rod 106 configured to receive electrical power from a power rail 108. In some examples, power rail 108 is one or more beams of metal arranged substantially parallel to and at a distance above the ground. In FIG. 1, power rail 108 is positioned to be substantially parallel to the X axis and the direction of travel of work machine 100. Support mechanisms hold power rail 108 in place along a distance at the side of haul route 101 for work machine 100 to traverse. The support mechanisms and power rail 108 may be modular in construction, enabling their disassembly and reassembly at different locations or their repositioning along the existing haul route 101. In many examples, such as within a mining site, power rail 108 will not be configured continuously at a fixed distance along a side of haul route 101 and at a fixed height above the ground due, at least in part, to the variation of the terrain. Therefore, it is expected that the vertical, horizontal, and angular positions of the surface of power rail 108 in the XYZ planes will vary along haul route 101. Moreover, while shown in FIG. 1 to the left of work machine 100 as work machine 100 travels in the direction of the X axis, power rail 108 may be installed to the right of work machine 100 or in other locations suitable to the particular implementation.

Power rail 108 provides a source of electrical power for work machine 100 as either AC or DC. In some examples, power rail 108 has two or more conductors, each providing voltage and current at a different electrical pole. In one implementation (e.g., an implementation in which the power rail 108 includes three conductors), one conductor provides positive DC voltage, a second conductor provides negative DC voltage, and a third conductor provides 0 volts relative to the other two conductors. The two powered conductors within power rail 108 provide +1500 VDC and 1500 VDC.

5

These values are exemplary, and other physical and electrical configurations for power rail 108 are available and within the knowledge of those of ordinary skill in the art.

Conductor rod 106 enables electrical connection between work machine 100 and power rail 108, including during movement of work machine 100 along haul route 101. In the example shown in FIG. 1, conductor rod 106 is an elongated arm resembling a pole. FIG. 1 shows conductor rod 106 positioned along a front side of work machine 100, with respect to the direction of travel of work machine 100 in the direction of the X axis. In this arrangement, conductor rod 106 is located in FIG. 1 in the Y-Z plane essentially along the Y axis with a first end near a right side of work machine 100 and a second end at a left side of work machine 100. Conductor rod 106 may be attached to any convenient location within work machine 100, such as to frame 103, in a manner to couple conductor rod 106 to power rail 108. Shown in FIG. 1 as extending to a left side of work machine 100 toward power rail 108, conductor rod 106 may alternatively be arranged to extend to a right side and at any desired angle from work machine 100 such that conductor rod 106 may be coupled to power rail 108 for obtaining electrical power.

As embodied in FIG. 1, conductor rod 106 includes a barrel 109 mounted to frame 103 of work machine 100. Barrel 109 has a hollow interior and may be a conductive metal having suitable mechanical strength and resiliency, such as aluminum. Within barrel 109, an arm 110 is retained. Arm 110 is slidably engaged within conductor rod 106 such that it may be extended or retracted axially, i.e., along the Y axis in FIG. 1, to adjust the reach of conductor rod 106. Specifically, in a retracted position, arm 110 is caused to slide within barrel 109 of conductor rod 106 such that a length of conductor rod 106 roughly spans the width of work machine 100. A junction 112 serves as the interface between arm 110 and barrel 109, which is the main body of conductor rod 106. When arm 110 is fully retracted or collapsed into barrel 109, junction 112 essentially becomes the left edge of conductor rod 106. On the other hand, when arm 110 is extended from barrel 109 of conductor rod 106, arm 110 may reach from work machine 100 to proximate power rail 108 on the side of haul route 101.

Within, and possibly including barrel 109, conductor rod 106 includes a series of electrical conductors passing longitudinally, at least from a head 122 at a proximal end to a tip 124 at a distal end. Typically, the conductors within conductor rod 106 are formed of a metallic material and are rigid. In some examples, the conductors are concentric tubes, or hollow cylinders, of solid metal such as aluminum nested together and sized to provide electrical capacity sufficient for powering work machine 100. Tubular conductors within arm 110 slidably engage with corresponding tubular conductors within barrel 109 to maintain electrical continuity as arm 110 is extended or retracted.

At a position away from work machine 100 at tip 124, a connector assembly 114 provides an interface to power rail 108 via trailing arms 116 and contactor 118. Power rail 108 is typically arranged along a side of haul route 101, and work machine 100 is steered so that it traverses haul route 101 substantially in parallel with power rail 108. Thus, in reference to FIG. 1, power rail 108 and a travel path for work machine 100 are substantially in parallel with each other, and with the X axis. Contactor 118 is configured to maintain an electrical connection with power rail 108 while sliding along its surface in the direction of the X axis as work machine 100 moves. In some examples, trailing arms 116 are conductors coupled to contactor 118, each conducting

6

voltage and current at a different electrical pole and corresponding to the conductors within conductor rod 106. In operation, electrical power is accessed from power rail 108 via contactor 118, which remain in contact during movement of work machine 100, and the electrical power is conducted through trailing arms 116 into connector assembly 114.

From connector assembly 114, the electrical power is conveyed at tip 124 through the nested tubular conductors within arm 110 and barrel 109 to head 122 of conductor rod 106 and through a head-end interface 120 to work machine 100. Head-end interface 120 provides at least an electrical connection between conductor rod 106 and work machine 100 for powering electric engine 102 and otherwise enabling operations within work machine 100. In some examples, head-end interface 120 may also provide an interface for inputs to control mechanical operation of conductor rod 106, such as passageways for pressurized air of a pneumatic control system to extend and retract arm 110 or signaling for electronic controls.

While FIG. 1 illustrates a general arrangement for work machine 100 to access electrical power from power rail 108 while moving, the reliability of a connection between contactor 118 and power rail 108 can be influenced by stable positioning for power rail 108 along the side of haul route 101. In some examples, power rail 108 is kept at a relatively constant distance from a side of haul route 101 and height above the ground along haul route 101 to minimize risk of disconnection. Moreover, the positioning of power rail 108 along haul route 101 should be generally impervious to external factors such as rain or wind, as changes in positioning can affect the connection between contactor 118 and power rail 108. FIG. 2 depicts an exemplary arrangement for stably and safely supporting power rail 108 along a side of haul route 101.

Compared with FIG. 1, FIG. 2 provides a view of rail support module 200 from the same side of power rail 108, but at an angle looking slightly in the direction of forward travel for work machine 100 along haul route 101 (i.e., in the direction of the X axis). As generally embodied in FIG. 2, rail support module 200 is an example of one instance in a series of support assemblies implemented together for securely positioning power rail 108 along a side of haul route 101. When implemented for an overall transportation route, such as within a mining site, barrier assembly 202 would be one component within a series or chain of structures providing mechanical stability to power rail 108 along a path for conduction of electrical power. FIGS. 3-6, discussed below, provide detail regarding the use of multiple ones of rail support module 200 in a series along a path for electrical power along haul route 101.

In general, rail support module 200 for power rail 108 includes a barrier assembly 202, which includes a barrier 204, a closed coupler 216, and open coupler 218. As illustrated, barrier 204 is a roadside barrier, such as a so-called "Jersey barrier," commonly used in highway construction. Barrier 204, however, may be any form of moveable, yet stable support structure typically of a substantially oblong shape. In the illustrated example, barrier 204 includes and/or rests on a base 206 at its bottom that extends between a first end 208 and a second end 210. The oblong or rectangular shape can help barrier 204 stabilize power rail 108 across a longitudinal distance parallel to base 206. In the illustrated example, barrier 204 is approximately 20 feet in length along base 206 and two feet in width across base 206 at first end 208 and at second end 210. These dimensions, as

well as others provided in this disclosure, are representative only. Other values are readily usable for achieving similar results.

In one example, barrier **204** is made primarily of concrete with reinforcing steel bars (not shown) set within the concrete to enhance solidity of barrier **204**. In other examples, barrier **204** is a different composition, such as a plastic filled with weighted material, or a different shape. Various compositions and shapes for barrier **204** may be employed without departing from the principles of the present disclosure. In an example of concrete, barrier **204** weighs about 8,000 pounds. With this substantial weight, which helps deter unintended movement after placement, barrier **204** includes base gap **212** for lifting and placement by a forklift or similar machine. In addition, barrier **204** has at least one strap hole **214**, which may be used for feeding a strap or similar implement to assist in lifting and placing barrier **204**. Additionally, the shape of barrier **204** enables use of commercially available barrier clamp tools, which may grip barrier **204** through a scissor action for machine lifting without need for base gap **212** or strap hole **214**. Therefore, barrier **204** is modular, moveable, and relocatable, yet also stable if impacted by most outside forces such as from movement of power rail **108** or haul route **101** or from weather.

Barrier assembly **202** further includes closed coupler **216** attached to first end **208** and open coupler **218** attached to second end **210**. Discussed in detail below with respect to FIGS. 3-5, closed coupler **216** and open coupler **218** in some examples have generally tubular configurations in which closed coupler **216** has an outer diameter smaller than an inner diameter of the open coupler **218**, and can fit concentrically within open coupler **218**. In addition, as shown in FIG. 2, the structure for closed coupler **216** and open coupler **218** enable the insertion and retention of support assembly **219** via support posts within the tubular configurations. Described further below, support assembly **219** includes a variety of components such as posts and plates for supporting power rail **108** at an elevated position above ground from barrier assembly **202**. In the illustrated example, support assembly **219** includes first support pole **220A** mounted via first lower portion **238A** and secured within closed coupler **216**, and second support pole **220B** mounted via second lower portion **238B** and secured within open coupler **218**. Specifically, first coupler pin **224A**, second coupler pin **224B**, and third coupler pin **224C** are made of a pultruded fiberglass-reinforced polymer (FRP) and inserted within horizontal holes (see FIG. 3) to secure first support pole **220A** in place within closed coupler **216** as part of barrier assembly **202**. Other electrically insulative or dielectric materials may alternatively be used. Although not shown in FIG. 2, similar attachments may exist between second support pole **220B** and open coupler **218**.

First support pole **220A** and second support pole **220B**, as part of support assembly **219** and rail support module **200**, are rods, poles, posts, cylinders, stanchions, or similar structures made of dielectric material and having a length for elevating and supporting power rail **108** above ground. In some examples, first support pole **220A** and second support pole **220B** are pipes made of a pultruded FRP, or similar dielectric or electrically insulative materials, having lengths sufficient to stabilize power rail **108** about eight feet off the ground. Person **222** in FIG. 2 depicts a relative height of power rail **108** enabled by first support pole **220A** and second support pole **220B**. By elevating power rail **108** above the typical reach of person **222**, first support pole **220A** and second support pole **220B** help improve safety for

the delivery of electrical power for work machine **100**. Although power rail **108** may be electrically isolated in a manner to avoid risks of electrocution, the height of power rail **108** also precludes individuals such as person **222** from easily touching power rail **108** while grounded. In addition, the elevated position minimizes the risk of contamination by ground debris or contact from animals or unauthorized individuals on the ground.

At first upper portion **236A** of first support pole **220A**, a first front plate **226A** and a first rear plate **228A** within support assembly **219** provide a bracketing structure for holding power rail **108** in place at a position vertically above first end **208**. A second front plate **226B** and a second rear plate **228B** provide a similar structure and function for power rail **108** at second upper portion **236B** of second support pole **220B** vertically above second end **210**. In one example, first front plate **226A**, first rear plate **228A**, second front plate **226B**, and second rear plate **228B** are made of pultruded FRP and may be secured respectively to first support pole **220A** and second support pole **220B** using additional lock pins, such as first plate pin **230A** and second plate pin **230B** shown in FIG. 2. Additionally, as first front plate **226A** and first rear plate **228A** face each other on opposite sides of first support pole **220A**, in some examples, first lateral pin **232A** and second lateral pin **232B** pass between first front plate **226A** and first rear plate **228A** to provide lateral stability and lock the two plates parallel to each other. First lateral pin **232A** and second lateral pin **232B** pass through fiberglass **233** that can provide a separation or buffer between first front plate **226A** and first rear plate **228A**. Alternative securing mechanisms are within the principles of the present disclosure and known to those of ordinary skill in the field. The bracketing structure, such as formed by first front plate **226A** and first rear plate **228A**, is discussed in more detail below with respect to FIGS. 7 and 8.

These various components of support assembly **219** function together to hold power rail **108** from below in a position longitudinally along a path between first support pole **220A** and second support pole **220B** formed by base **206** of barrier **204**. In some examples, such as in a mining site, power rail **108** can extend along haul route **101** for miles. Accordingly, in the example of FIG. 2, power rail **108** is divided into a series of segments associated with a barrier, such as inner rail segment **234A**, middle rail segment **234B**, and outer rail segment **234C**. Although three rail segments are shown and discussed, fewer or more rails are possible. In the example illustrated, inner rail segment **234A**, middle rail segment **234B**, and outer rail segment **234C** are each 41 feet long. Therefore, with an exemplary barrier **204** having a length of 20 feet, about 25% of each of inner rail segment **234A**, middle rail segment **234B**, and outer rail segment **234C** extends beyond first support pole **220A** and second support pole **220B**. These dimensions and ratios are representative only and other lengths are possible for different implementations in achieving similar results. The combination of rail support module **200**, inner rail segment **234A**, middle rail segment **234B**, and outer rail segment **234C** forms a modular unit that can be replicated along haul route **101** to form a collective support structure and continuous path for electrical power. In one example, multiple rail segments such as inner rail segment **234A**, middle rail segment **234B**, and outer rail segment **234C** are connected end-to-end to form power rail **108** in a manner discussed below in the context of FIGS. 9 and 10.

Combining multiple ones of rail support module **200** in a chain along haul route **101** can be accomplished in many

ways. In one example, different ones of barrier **204** can be positioned end-to-end, i.e., longitudinally in a line, and loosely connected via couplers at the ends of the barriers. FIG. 3 illustrates an example of an association between two representative couplers, designated as closed coupler **216-0** and open coupler **218-1**. In FIG. 3 and other drawings, the suffix “-n” designates an association of a part with a barrier or support assembly represented by the suffix. Closed coupler **216-0** refers to a closed coupler **216** associated with a barrier “-0,” while closed coupler **216-1** refers to a closed coupler **216** associated with a different barrier “-1.” As discussed in more detail below with respect to FIG. 6, in some examples, the barrier having suffix “-0” can be a barrier or similar alignment structure used for deploying other barriers **204** in the system but not necessarily used as part of the installed structure supporting power rail **108** along haul route **101**.

Positioning multiple barriers in a chain can entail, for example, linking multiple ones of barrier assembly **202** together along haul route **101**. FIG. 3 depicts an engagement **300** of two couplers, closed coupler **216-0** and open coupler **218-1**, from associated barriers positioned end-to-end. Closed coupler **216-0** and open coupler **218-1** are depicted without their corresponding barriers, barrier **204-0** and barrier **204-1**, to which they are attached during deployment. As illustrated in FIG. 3, open coupler **218-1** would reside on a left side of barrier **204-1** (not shown), and closed coupler **216-0** would reside on a right side of barrier **204-0** (not shown).

Open coupler **218-1** generally has a shape of a tube or a hollow cylinder formed about an axis A-A that runs parallel in FIG. 3 to the Z-axis and orthogonal to base **206**. Open coupler **218-1** may be made of any structurally resilient material, such as steel or other metals. On one side, the tubular shape of open coupler **218-1** is attached to a first end plate **302-1**. First end plate **302-1** in some examples is a metal, such as steel, and abuts first end **208-1** (not shown) on barrier **204-1** opposite to open coupler **218-1**. First end plate **302-1** is integrally formed with one or more reinforcement bars that pass within the body of barrier **204-1**, namely, first reinforcement **304-1**, second reinforcement **306-1**, and third reinforcement **308-1**, and provide structural support for open coupler **218-1**. Open coupler **218-1** also includes top hole **310-1** and bottom hole **312-1** positioned vertically along the A-A axis in one implementation. Similarly, alignment hole **314-1** is positioned vertically along the A-A axis and may have an oval or oblong shape for reasons discussed below. Moreover, while open coupler **218-1** is substantially tubular in shape, in some examples, the tube includes a central slot **316-1** that runs vertically in parallel to the axis A-A giving it an open configuration. In this context, “substantially” means that the shape of open coupler **218-1** generally approximates a hollow cylinder, although it may have a cross section that is out of round, such as being an oval, or have various indentations. Central slot **316-1** can be viewed as a gap between parallel edges of open coupler **218-1** (FIG. 5) or as an open seam within the tubular form of open coupler **218-1**.

Corresponding to open coupler **218-1**, closed coupler **216-0** also has a shape of a tube or a hollow cylinder formed about axis A-A in the illustrated example. On one side, the tubular shape of closed coupler **216-0** is attached to an arm **318-0**, which in turn is attached at substantially a right angle with a second end plate **320-0**. Second end plate **320-0** abuts second end **210-0** (not shown) on barrier **204-0** opposite to arm **318-0**. Second end plate **320-0** is integrally formed with one or more reinforcement bars that pass within the body of

barrier **204-0**, namely, first reinforcement **322-0**, second reinforcement **324-0**, and third reinforcement **326-0**, and provide structural support for closed coupler **216-0**. Closed coupler **216-0**, arm **318-0**, second end plate **320-0**, first reinforcement **322-0**, second reinforcement **324-0**, and third reinforcement **326-0** may be made of any structurally resilient materials, such as steel or other metals. Closed coupler **216-0** also includes top hole **328-0** and bottom hole **330-0** positioned vertically along the A-A axis in one implementation. Similarly, alignment hole **332-0** is positioned vertically along the A-A axis.

As indicated by top hole **328** in FIG. 3, closed coupler **216-0** as part of barrier assembly **202-0** may be moved vertically along axis A-A into engagement with open coupler **218-1**. Although not shown in FIG. 3, in some examples, barrier **204-1** associated with open coupler **218-1** is resting on the ground, and barrier **204-0** associated with closed coupler **216-0** is lowered from a raised position using a forklift or similar equipment. Dimensions for open coupler **218-1**, central slot **316-1**, closed coupler **216-0**, and arm **318-0** can determine at least the mating relationship for engagement. In the illustrated example, an outer diameter **410** (FIG. 4) of closed coupler **216-0** is smaller than an inner diameter **412** (FIG. 4) of open coupler **218-1**, such that closed coupler **216-0** can be lowered vertically along axis A-A into open coupler **218-1**. Moreover, central slot **316-1** has a width between vertical edges of open coupler **218-1**, and arm **318-0** is dimensioned with a thickness less than the width of central slot **316-1**. As a result, as barrier **204-0** is lowered, arm **318-0** may pass freely through central slot **316-1** and closed coupler **216-0** may pass freely into open coupler **218-1**. While engagement **300** in FIG. 3 depicts a lowering of closed coupler **216-0**, movement of open coupler **218-1** relative to closed coupler **216-0** could alternatively occur, such as a lowering of open coupler **218-1** over open coupler **218-0**. Accordingly, closed coupler **216-0** and open coupler **218-1** form complementary connector halves that mate in a loose configuration and help in positioning two barriers, such as barrier **204-0** and barrier **204-1**, in an end-to-end relationship.

While FIG. 3 depicts engagement **300** for closed coupler **216-0** and open coupler **218-1** based on their illustrated shapes as tubes having different diameters, closed coupler **216-0** and open coupler **218-1** can also help guard against undesired angular positions of barrier **204-0** with respect to barrier **204-1**. In general, sharp deviations in the positioning of power rail **108** can lead to a disconnection of contactor **118** if maneuverability or steering of work machine **100** becomes difficult, and alignment of conductor rod **106** and trailing arms **116** with power rail **108** may erode. Moreover, excess curvature to power rail **108** can impact the installation and life of the rails or require that rail segments have specialized shapes or dimensions. For example, bends in haul route **101** that are sharp, which may correspond to a radius of curvature of about 10 degrees per 20 feet or more, or slopes in haul route **101** that are steep, which may correspond to a slope change of about 3.5 degrees per 20 feet or more, could increase the risk of disconnection between contactor **118** and power rail **108** or otherwise impact the use of power rail **108**. FIGS. 4 and 5 illustrate how closed coupler **216-0** and open coupler **218-1** can avoid extreme bends or slopes for power rail **108**, in some examples, by restricting the angular position of adjacent barriers.

FIG. 4 shows a barrier connection **400** with a completed coupling between closed coupler **216-0** of barrier **204-0** and open coupler **218-1** of barrier **204-1**. As illustrated, an outer diameter **410** of closed coupler **216-0** fits within an inner

11

diameter 412 of open coupler 218-1 such that open coupler 218-1 and closed coupler 216-0 are arranged concentrically about axis A-A. In this position, a barrier separation 402 between barrier 204-0 and barrier 204-1 is established longitudinally, i.e., along the X axis in FIG. 4, which is driven by the size and shape of closed coupler 216-0 and open coupler 218-1. In particular, barrier separation 402 will be defined by a distance between first end 208-0 and a center of closed coupler 216-0 along axis A-A plus a distance between second end 210-1 and a center of open coupler 218-1 along the axis A-A. The size of an annular gap 404 between closed coupler 216-0 and open coupler 218-1 provides a tolerance for barrier separation 402 in the event closed coupler 216-0 and open coupler 218-1 are not aligned exactly about the same centerline, as in axis A-A. Annular gap 404 also defines a permitted deviation laterally between barrier 204-0 and barrier 204-1, i.e., along the Y axis in FIG. 4. As a result, in one example, barrier connection 400 using closed coupler 216-0 and open coupler 218-1 provides for precise longitudinal and lateral positioning of barrier 204-0 with respect to barrier 204-1 within a tolerance built into the geometry of the coupling.

Barrier connection 400 additionally ensures that barrier 204-0 and barrier 204-1 are not positioned on a surface with too large of a slope change, such as exceeding 3.5 degrees per 20 feet. Slope change in the context of FIG. 4 refers to, for example, rotation or tilt of barrier connection 400 about the Y axis in the X-Z plane, such as if barrier 204-0 were uphill or downhill from barrier 204-1. In one example, barrier 204-0 could rest on a slope such that barrier 204-0 essentially pivots around an axis B-B with respect to barrier 204-1, shown in FIG. 4 as being parallel to the Y axis. Barrier 204-0 could rest on a downhill slope relative to base 206-1, such as shown by downslope angle 406, or on an uphill slope, such as shown by upslope angle 408. If barrier 204-0 rests on a downslope, for instance, base 206-0 will be positioned around axis B-B at downslope angle 406. In that situation, closed coupler 216-0 will likewise be rotated or tilted at an angle similarly as downslope angle 406 with respect to open coupler 218-1. At a predetermined amount of slope change, closed coupler 216-0 will have rotated sufficiently through annular gap 404 to contact open coupler 218-1 at an upper portion of both tubes. The contact between the tubes will provide an outer limit to the amount of slope change for barrier 204-0 permitted by the coupling. In one example, the size of annular gap 404 and a height for closed coupler 216-0 and open coupler 218-1 are determined such that downslope angle 406 is about 3.5 degrees. This dimensioning of closed coupler 216-0 and open coupler 218-1 may vary based on the configuration chosen for the couplers and is within the knowledge of those of ordinary skill in the art. Similar behavior and dimensioning will apply to a rotation or tilt for barrier 204-0 on an uphill slope across upslope angle 408. Also, it will be understood that, for the same reasons, the concentric tubes of closed coupler 216-0 and open coupler 218-1 and annular gap 404 also provide a limit to excessive slope changes for barrier 204-1 relative to barrier 204-0 that may occur about axis C-C in FIG. 4.

In addition to assisting with longitudinal displacement, lateral displacement, and slope change, barrier connection 400 can also ensure that barrier 204-0 and barrier 204-1 are not arranged with too large of a lateral rotation about axis A-A, which may lead to undue stress on power rail 108. This angle of lateral rotation can translate into a curvature for power rail 108, which in the context of FIG. 4 refers to, for example, rotation about the Z axis in the X-Y plane. FIG. 5 shows a top view of barrier connection 400 and indicates the

12

positional restrictions provided by closed coupler 216-0 and open coupler 218-1 in the X-Y plane.

Referring to FIG. 5, while having a general tubular shape overall, open coupler 218-1 at a top view as in FIG. 5 also has a C-shape as its circumference spans from first vertical edge 502-1 to second vertical edge 504-1. Central slot 316-1 is defined by a first vertical edge 502-1 and a second vertical edge 504-1 and runs vertically and parallel to axis A-A. In the X-Y plane, central slot 316-1 spans the distance between first vertical edge 502-1 and second vertical edge 504-1 and defines a space for accommodating lateral rotation of barrier 204-1 relative to barrier 204-0, or vice versa. When barrier 204-0 and barrier 204-1 are aligned, such as along axis D-D in FIG. 5, central slot 316-1 is bisected by arm 318-0 of barrier 204-0. If barrier 204-1, for example, is displaced upwards with respect to barrier 204-0 in the X-Y plane in FIG. 5 around axis A-A, open coupler 218-1 will be displaced about axis A-A as well. The portion of central slot 316-1 between first vertical edge 502-1 and arm 318-0 permits angular placement about axis A-A up to a first curvature angle 506. At first curvature angle 506, first vertical edge 502-1 will contact arm 318-0 and prevent further lateral rotation of barrier 204-1 relative to barrier 204-0. Similarly, barrier 204-1 may be displaced downwards in FIG. 5 around axis A-A with respect to barrier 204-0 to a position where second vertical edge 504-1 contacts arm 318-0, corresponding to a second curvature angle 508. In one example, closed coupler 216-0 and open coupler 218-1 are dimensioned so that first curvature angle 506 and second curvature angle 508 are both about 3.5 degrees for the 20 feet of barrier 204-1. Similar behavior and dimensioning will apply to a lateral rotation for barrier 204-1 with respect to barrier 204-0, as arm 318-0 is displaced into contact with either first vertical edge 502-1 or second vertical edge 504-1 and blocking lateral rotation beyond first curvature angle 506 or second curvature angle 508.

Referring again to FIG. 4, in some examples, alignment hole 314-1 within open coupler 218-1 provides an additional feature to assist with alignment of barrier 204-0 with respect to barrier 204-1. In some examples, alignment hole 314-1 is oblong in shape, such as an elongated circle or an oval. When closed coupler 216-0 is mated with open coupler 218-0, such as in engagement 300, and barrier 204-0 and barrier 204-1 are laterally and longitudinally aligned on a level surface, alignment hole 314-1 and alignment hole 332-0 will share a common central axis (not shown). A bolt or plug (not shown) can be inserted through alignment hole 314-1 and alignment hole 332-0 through the common central axis to confirm the alignment. As barrier 204-0 or barrier 204-1 deviate from alignment—whether through longitudinal displacement, lateral displacement, slope change, or lateral rotation—the alignment between alignment hole 314-1 and alignment hole 332-0 will decrease. At a point in which the positional deviation of barrier 204-0 and barrier 204-1 with respect to each other are beyond a designed value, alignment hole 314-1 and alignment hole 332-0 will lose their alignment to the point a bolt or plug cannot be inserted through them. This feature, which may loosely be equated with a keyed relationship between alignment hole 314-1 and alignment hole 332-0, provides an additional guide for an operator to ensure that barrier 204-0 and barrier 204-1 are properly arranged before mounting additional equipment such as support assembly 219 or power rail 108.

Accordingly, as illustrated in FIGS. 2-5, adjacent barriers may be loosely joined through closed coupler 216 and open coupler 218 to set their positioning and adjust as needed their longitudinal displacement, lateral displacement, slope

13

change, and lateral rotation. Following engagement **300**, sequential engagements of other barriers may be accomplished end-to-end along a path intended for power rail **108**. Support posts, such as first support pole **220A** and second support pole **220B** in FIG. **2**, may be inserted along axis A-A for each coupling. A consistent and stable support structure for power rail **108** can thereby be installed.

FIG. **6** illustrates an exemplary scheme for deploying a support structure using rail support module **200** that reduces the number of barriers employed. As embodied in FIG. **6**, a deployment layout **600** indicates that a line of end-to-end barrier assemblies, coupled in a chain via a closed coupler **216** and an open coupler **218**, could each occupy a select position along haul route **101**. For example, a beginning of the chain may be defined as first location **602**, followed by second location **604**, third location **606**, fourth location **608**, and fifth location **610** moving from the right to the left in FIG. **6**. A method for deploying barrier assemblies within deployment layout **600** is defined by representative steps consistent with the present disclosure in the flowchart of FIG. **7**. For the method of FIG. **7**, as well as other methods described in this disclosure, the steps in which the method is described are not intended to be construed as a limitation. Any number of steps can be combined in any order to implement the disclosed method, can be performed in parallel to implement the processes, and in some embodiments, one or more blocks of the process can be omitted entirely. Moreover, the processes can be combined in whole or in part with other methods.

Referring to FIGS. **6** and **7** together, the method **700** in FIG. **7** begins with a first step **702** of placing a first barrier at a first location. As shown in FIG. **6**, placement of a first barrier may entail situating barrier **204-1** on the ground at first location **602** using a forklift, crane, or similar equipment. Barrier **204-1** includes closed coupler **216-1** and open coupler **218-1** at opposing first end **208-1** and second end **210-1** of barrier **204-1**. At a second step **704** in method **700**, an alignment structure is arranged end-to-end with the first barrier in single-file formation using a first tubular coupling between the first barrier and the alignment structure. Specifically, barrier **204-0** may have an identical structure and composition as barrier **204-1** and be placed at second location **604** immediately next to barrier **204-1** at first location **602**. Alternatively, barrier **204-0** may have a different composition than barrier **204-1**, such as being lighter and more easily moved than barrier **204-1**. As with barrier **204-1**, barrier **204-0** includes closed coupler **216-0** and open coupler **218-0** at its opposing first end **208-0** and second end **210-0** (FIG. **2**). Following the teachings of FIGS. **3-5**, closed coupler **216-0** on barrier assembly **202-0** may be lowered vertically into engagement with open coupler **218-1** on barrier assembly **202-1** at second location **604**, forming a coupling of concentric tubes. At this point, the alignment of barrier assembly **202-0** with respect to barrier assembly **202-1** may be checked based on the arrangement of closed coupler **216-0** within open coupler **218-1** as well as the keyed relationship of alignment hole **314-1** and alignment hole **332-0**. Adjustments may be made to the ground or the deployment location in general if the coupling does not indicate an appropriate alignment between barrier assembly **202-0** and barrier assembly **202-1**.

Continuing with method **700**, a step **706** includes positioning a second barrier end-to-end with the alignment structure in the single-file formation using a second tubular coupling between the second barrier and the alignment structure. Following this step, a chain of at least three barriers would be formed including a sequence of barrier

14

**204-1**, barrier **204-0**, and then barrier **204-2**. Barrier **204-0** may be lowered to the left of barrier **204-0** into third location **606** with closed coupler **216-2** engaging with open coupler **218-0**. The coupling formed by the tubular forms within closed coupler **216-2** and open coupler **218-0** may be checked along with alignment hole **314-0** and alignment hole **332-2** to ensure that barrier **204-0** and barrier **204-2** are appropriately aligned with respect to longitudinal displacement, lateral displacement, slope change, and lateral rotation, as discussed above.

In step **708** of method **700**, the alignment structure is moved past the second barrier in the single-file formation and positioned end-to-end with the second barrier. FIG. **6** illustrates with relocation arrow **612** movement of barrier assembly **202-0** from second location **604** to fourth location **608**, leapfrogging over barrier **204-2** at third location **606**. Phantom lines at second location **604** indicate the previous placement of barrier assembly **202-0** at second location **604**. Barrier assembly **202-0** may be moved using a forklift, crane, or similar equipment. Or if barrier assembly **202-0** is embodied as a lighter structure, movement of barrier assembly **202-0** may be accomplished with lifting force not requiring a powered machine. As the position of barrier **204-1** has been confirmed as acceptable, barrier **204-1** is left in place at first location **602**. Barrier assembly **202-0** in FIG. **6** is lowered to the left barrier **204-2** so that closed coupler **216-0** aligns vertically with open coupler **218-2** to form concentric tubes. As previously discussed for other barrier assemblies, the positioning of barrier **204-2** can be checked relative to barrier **204-0** and, therefore, the ground conditions at third location **606** and fourth location **608** can be confirmed as acceptable for the support structure of power rail **108**.

In step **712** of FIG. **7**, a third barrier is arranged end-to-end with the alignment structure using a fourth tubular coupling. In particular, barrier **204-3** is added, typically using heavy lifting equipment, into fifth location **610** to be longitudinally adjacent barrier assembly **202-0** at fourth location **608**, as shown in FIG. **6**. The fourth tubular coupling in some examples includes the vertical mating of closed coupler **216-3** with open coupler **218-0**. Checking of the alignment through the coupling, such as via alignment hole **314-3**, can indicate whether the positioning of closed coupler **216-3** and barrier assembly **202-0** are acceptable with respect to each other.

The sequence of FIG. **7** may be continued indefinitely along haul route **101**. As a result, method **700** enables positioning of multiple ones of barrier assembly **202** on a path for constant and stable support of power rail **108**. Excesses in at least longitudinal displacement, lateral displacement, slope change, and lateral rotation can be avoided using closed coupler **216** and open coupler **218**. Moreover, using barrier assembly **202-0** as an alignment structure in the manner of FIGS. **6** and **7**, where barrier assembly **202-0** is repeatedly placed between two other barrier assemblies **202** for an alignment check and then moved as with relocation arrow **612**, a support structure for power rail **108** can be built using up to half of the barrier assemblies **202** employed for a continuous wall. The support structure resulting from FIGS. **6** and **7** would in essence be an alternating sequence of barrier assemblies **202** and empty spaces. For example, in a final assembly from FIG. **6**, rail support module **200** would occupy first location **602**, third location **606**, and fifth location **610**, while second location **604** and fourth location **608** would be empty. As will be appreciated, because rail segments **240** in the example of rail support module **200** extend beyond first support pole **220A** and second support

15

pole **220B** by about 25%, ends of the rail segments **240** from one rail support module **200**, such as a rail segment **234-1** of rail support module **200-1** at first location **602**, can be joined with ends of the rail segments **240** in the next rail support module **200**, such as a rail segment **234-2** of rail support module **200-2** at third location **606**. FIGS. **11** and **12** and the discussion about them below explain examples for joining ends of rail segments **240** for this support structure.

Following or during deployment of barrier assembly **202**, first support pole **220A** and second support pole **220B** may be installed within closed coupler **216** and open coupler **218** at opposite ends first end **208** and second end **210** of barrier **204**. In some examples, an inner diameter **412** of closed coupler **216** and an inner diameter of open coupler **218** (FIGS. **3** and **4**) each are sufficient to receive and retain first lower portion **238A** of first support pole **220A** and second lower portion **238B** of second support pole **220B**, respectively. Once installed vertically along axes A-A in closed coupler **216** and open coupler **218**, first support pole **220A** and second support pole **220B** are secured in place using plugs or bolts, such as one or more of first coupler pin **224A**, second coupler pin **224B**, and third coupler pin **224C**.

First upper portion **236A** of first support pole **220A**, for example, distal from barrier **204** includes a mounting structure formed by first front plate **226A** and first rear plate **228A** (FIG. **2**) for holding rail segments **240** safely in place. FIG. **8** is a front view of first support pole **220A** and first front plate **226A** from the perspective looking in the direction of forward travel for work machine **100**, i.e., parallel to the X axis. In some examples, first front plate **226A** is a flat structure made of pultruded FRP, as mentioned above, although other dielectric materials may be alternatives. First front plate **226A** is attached to first support pole **220A** by way of first plate pin **230A** and second plate pin **230B**. As first support pole **220A** may have a round cross-section and a curved surface, first lateral pin **232A** and second lateral pin **232B** connect first front plate **226A** to first rear plate **228A** (FIG. **2**) and provide lateral stability for first front plate **226A** and second front plate **226B**.

In the example illustrated, first front plate **226A** has a triangular shape residing in the Y-Z plane of FIG. **8**. Parallel to the Y axis and ultimately to base **206** of barrier **204** and ground, top edge **802** forms one side of the triangular shape for first front plate **226A** as a horizontal surface that provides direct support for rail segments **240**. In some examples, top edge **802** includes a series of cuts or openings along its surface. In particular, top edge **802** includes one or more slots for holding rail segments **240**, such as inner rail recess **804**, middle rail recess **806**, and outer rail recess **808** in the example of FIG. **8**. Besides providing a structural base for **234**, the one or more slots are separated sufficiently across top edge **802** to exceed relevant rail-to-rail clearance criteria. In one example, a center-to-center distance between adjacent slots, such as between inner rail recess **804** and middle rail recess **806**, is 200 mm.

FIG. **9** illustrates the structure of example rail segments **240** held within inner rail recess **804**, middle rail recess **806**, and outer rail recess **808** of first front plate **226A**. A representative portion **900** of inner rail segment **234A** has a rail body **902** in the form of a modified I-beam made of aluminum. A rail web **904** in the center of representative portion **900** separates a lower flange **906** from an upper flange **908**, forming a first rail groove **918** and a second rail groove **920** on opposite sides of rail web **904**. A rail bottom **910** is at an underside of rail body **902**. An upper plate **912**, which is stainless steel, is curved into an upside-down U-shape and positioned on lateral sides of upper flange **908**.

16

Crimping, as reflected by crimp pocks **916** in FIG. **9**, can secure upper plate **912** within slots **914**.

Turning back to FIG. **8**, inner rail recess **804** is configured to receive at least lower flange **906** of inner rail segment **234A** and allow rail bottom **910** of inner rail segment **234A** to rest on top edge **802**. In some examples, as shown in FIG. **7**, rail web **904** also rests within inner rail recess **804**, although rail web **904** may also extend above top edge **802**, for instance due to a shallowness of inner rail recess **804** or a height of inner rail segment **234A**. In this configuration, the exposure of upper plate **912** vertically above top edge **802** enables unobstructed engagement by contactor **118** with inner rail segment **234A** without excess maneuvering by conductor rod **106** on work machine **100**. To help stabilize inner rail segment **234A** within inner rail recess **804**, a first inner insert **810A** and a second middle insert **812B** are pressed into grooves in the sides of inner rail recess **804** to frictionally lock inner rail segment **234A** in place. First inner insert **810A** and second middle insert **812B** are made of dielectric material, such as FRP. While depicted in FIG. **8** as angles, first inner insert **810A** and second middle insert **812B** may have other shapes or forms. In some examples, the frictional locking of inner rail segment **234A** provides some pliability to the attachment of rail segments **240** to first front plate **226A** to accommodate small movements that may occur with either inner rail segment **234A** or first front plate **226A**. Similar arrangements exist in FIG. **8** for other ones of rail segments **240** that may be implemented in rail support module **200**, such as first middle insert **810B** and second middle insert **812B** for middle rail segment **234B** within middle rail recess **806** and first outer insert **810C** and second outer insert **812C** for outer rail segment **234C** within outer rail recess **808**. Also, while not depicted in FIG. **8**, a matching configuration is provided for first rear plate **228A** on the opposite side of first support pole **220A** (FIG. **2**).

Between respective recesses, first front plate **226A** includes curvatures within top edge **802**. As shown in FIG. **8**, first concavity **814** is located on top edge **802** between inner rail recess **804** and middle rail recess **806**, and second concavity **816** is located between middle rail recess **806** and outer rail recess **808**. By being curved, first concavity **814** and second concavity **816** provide increased distance through first front plate **226A** between adjacent rail segments. The depth, curvature, and overall shape of first concavity **814** and second concavity **816** may be selected by the skilled artisan to accomplish the objectives of increasing creepage beyond criteria while maintaining mechanical resiliency to first front plate **226A**. While not shown, similar concavities exist within opposing first rear plate **228A** between inner rail segment **234A**, middle rail segment **234B**, and outer rail segment **234C**.

A method **1000** for deploying power rails for a work machine is defined by representative steps consistent with the present disclosure in the flowchart of FIG. **10**. For method **1000**, as well as other methods described in this disclosure, the steps in which the method is described are not intended to be construed as a limitation. Any number of steps can be combined in any order to implement the disclosed method, can be performed in parallel to implement the processes, and in some embodiments, one or more blocks of the process can be omitted entirely. Moreover, the processes such as **1000** can be combined in whole or in part with other methods. In a first step **1002**, a moveable support structure is placed on the ground. For instance, as described above, a barrier **204** may be located along a side of a haul route **101** using a forklift, crane, or other lifting equipment. barrier **204** may include closed coupler **216** and open



17

coupler **218** at opposite ends that are separated along a horizontal axis by a base **206**. At a step **1004**, a lower portion of a first dielectric stanchion is inserted into a first holder affixed to the support structure, where the first dielectric stanchion has an upper portion supporting first parallel dielectric plates on opposite sides of the first dielectric stanchion. In one example, a first upper portion **236A** of a first support pole **220A** is inserted into closed coupler **216** that is affixed to first end **208** on barrier **204**. first front plate **226A** and first rear plate **228A** are attached in parallel on opposite sides of first support pole **220A** using first plate pin **230A** and second plate pin **230B**, as well as first lateral pin **232A** and second lateral pin **232B**.

In FIG. **10**, method **1000** continues with step **1006** of inserting a lower portion of a second dielectric stanchion into a second holder affixed to the support structure, the second dielectric stanchion having an upper portion supporting second parallel dielectric plates on opposite sides of the second dielectric stanchion. In some examples, a second upper portion **236B** of a second support pole **220B** is inserted into open coupler **218** that is affixed to second end **210** on barrier **204**. second front plate **226B** and second rear plate **228B** are attached in parallel on opposite sides of second support pole **220B**, as shown in FIG. **2**. In step **1008**, a first pair of rail recesses on the first parallel dielectric plates and a second pair of rail recesses on the second parallel dielectric plates are aligned according to the lower portion of the first dielectric stanchion in the first holder and the lower portion of the second dielectric stanchion in the second holder. As indicated for FIG. **8**, first front plate **226A** includes inner rail recess **804**, middle rail recess **806**, and outer rail recess **808**, as do first rear plate **228A**, second front plate **226B**, and second rear plate **228B**.

Alignment of the four sets of inner rail recess **804**, four sets of middle rail recess **806**, and four sets of outer rail recess **808** within support assembly **219** can occur in various means. In one approach, the openings within the recesses may be visually or optically aligned during installation of barrier **204**. In another approach, the alignment of the recesses may be preconfigured into the position of the attachment devices securing the stanchions to the coupling devices as a keyed relationship. For example, top hole **328** and bottom hole **330** on closed coupler **216** and top hole **310** and bottom hole **312** on open coupler **218** may be coordinated in advance with the positions of corresponding holes in first support pole **220A** and second support pole **220B** so that the holes align when the rail recesses at first upper portion **236A** of first support pole **220A** and second upper portion **236B** of second support pole **220B** align. Therefore, attaching first support pole **220A** using first coupler pin **224A** and third coupler pin **224C** and attaching second support pole **220B** using first coupler pin **224A** and third coupler pin **224C** can indicate alignment of the rail recesses. As a result, method **1000** concludes with securing the lower portion of the first dielectric stanchion to the first holder (step **1010**) and securing the lower portion of the second dielectric stanchion to the second holder (step **1012**).

Accordingly, consistent with the principles of the present disclosure, after being situated as desired on the ground, barrier **204** may be enhanced with support assembly **219** to provide a foundation for positioning and holding power rail **108**. first support pole **220A** and second support pole **220B** enable power rail **108** to be elevated from the ground outside the normal reach of a person **222** to enhance safety for personnel and to protect power rail **108** from debris or undesired manipulation. After two or more second inner insert **812A**, second middle insert **812B**, and second outer

18

insert **812C** are aligned, inner rail segment **234A**, middle rail segment **234B**, and outer rail segment **234C** may be installed within the recesses and lodged into place, for example, using first inner insert **810A** and second inner insert **812A** for inner rail segment **234A**. At this stage, the combination rail segments **240**, support assembly **219**, and **234** results in a complete assembly for rail support module **200**.

In at least one example, rail segments **240** are manufactured, or at least installed, being pre-bent, i.e. having a curvature in the X-Y plane. In this example, rail segments **240** are 41 feet in length and are pre-bent longitudinally to have 10 degrees of curvature in the X-Y plane. When installed along a straight section of haul route **101**, rail segments **240** would be straightened, such as by hand, during installation into rail support module **200** to have 0 degrees of curvature. For installations along a curve in haul route **101**, rail segments **240** could remain pre-bent at 10 degrees of curvature or additionally bent to up to 20 degrees of curvature as required to match the shape of haul route **101**. The same curvatures could be attained by reversing the direction or orientation of the rail segment. As a result, a generic component for rail segments **240** could be used throughout haul route **101** to adapt to degrees of curvature along the path ranging from -20 degrees (e.g., a rail segment pre-bent by 10 degrees in the X-Y plane towards the -Y axis being additionally bent by 10 degrees towards the -Y axis) to +20 degrees of curvature (e.g., a rail segment pre-bent by 10 degrees in the X-Y plane towards the +Y axis being additionally bent by 10 degrees towards the +Y axis). Besides helping to adapt to curvatures in haul route **101**, pre-bending of rail segments **240** can also help accommodate thermal expansion and contraction of power rail **108**.

With each rail support module **200** placed at alternating positions along a path, such as at first location **602**, third location **606**, and fifth location **610** in FIG. **6**, a remaining step to establish continuity for delivering electrical power through power rail **108** is joining ends of rail segments **240** between adjacent ones of rail support module **200**. FIGS. **11-13** illustrate one example for joining ends of rail segments **240**.

FIG. **11A** is an exploded view of a single rail joint **1100** bringing together representative inner rail segment **234A-1** and inner rail segment **234A-2** within a fishplate **1102A**, while FIG. **11B** is a cross-sectional view of the single rail joint **1100** along the cutaway lines shown in FIG. **11A**. While FIGS. **11A** and **11B** show inner rail segment **234A** and components affiliated with inner rail segment **234A** (also bearing the suffix "A" relating to the inner rail), the arrangement depicted for inner rail segment **234A** would also apply to middle rail segment **234B** and outer rail segment **234C**. Consistent with the nomenclature explained above, in these examples, inner rail segment **234A-1** is the rail segment on the inner side of rail support module **200-1** at first location **602** in FIG. **6** (i.e., closest to haul route **101**), while inner rail segment **234A-2** is the rail segment in the same position on rail support module **200-2** at third location **606**. Inner rail segment **234A-1** includes a main section **1104A-1** and a first end **1106A-1**, while inner rail segment **234A-2** includes a main section **1104A-2** and a second end **1108A-2** in FIG. **11A**. While not shown in FIG. **6**, inner rail segment **234A-1** includes a second end **1108A-1** at an opposite tip of its rail segment, and inner rail segment **234A-2** includes a first end **1106A-2** at an opposite tip of that rail segment.

In one example, main section **1104A-1** and main section **1104B-2** correspond to representative portion **900** in FIG. **9** with a length (parallel to the X axis in FIG. **11A**) of roughly 39 feet and a width across rail body **902** (parallel to the Y

axis in FIG. 11A) of about 90 mm. First end **1106A-1** and second end **1108A-2**, as shown, are regions of reduced width along each end of the rail segments. In one example, first end **1106A-1** and second end **1108A-2** are about 14.5 inches in length from the tip of the respective rail segment and generally half the width of main section **1104A-1** and main section **1104A-2**, i.e. about 45 mm. These dimensions are representative only and other values may be chosen without departing from the principles of the present disclosure. First end **1106A-1** and second end **1108A-2** may be manufactured as shown, formed by dividing a single rail segment, or formed by removing sections from main section **1104A-1** and main section **1104A-2**, among other options. In some examples, as depicted in FIG. 11A, first end **1106A-1** and second end **1108A-2** are symmetrical and include first face **1110A-1** and second face **1112A-2**, respectively. First face **1110A-1** and second face **1112A-2** at least in part run longitudinally through each rail segment, i.e., generally parallel to outer sides of the respective rail segment, such as first outer side **1114A-1** and second outer side **1116A-1** for inner rail segment **234A-1**.

FIG. 11A depicts a main section **1104A-1A** on inner rail segment **234A-1** and a first end **1106A-2** on inner rail segment **234A-2** being joined within inner fishplate **1102A**. Inner fishplate **1102A** is divided into a first longitudinal half **1118A** and a second longitudinal half **1120A**. A structurally resilient material such as steel, inner fishplate **1102A** has an inner fishplate base **1122A** along a bottom where first longitudinal half **1118A** and second longitudinal half **1120A** meet and a first edge **1124A** and a second edge **1126A** at opposite longitudinal ends. Resembling a lipped channel in some examples, inner fishplate **1102A** has a first lip **1128A** and a second lip **1130A** defining a fishplate groove **1132A** that extends along the length of inner fishplate **1102A**. One or more attachment devices, such as first bolt **1134A** extends between first longitudinal half **1118A** and second longitudinal half **1120A** through inner fishplate base **1122A**. Engaging first bolt **1134A** helps draw first longitudinal half **1118A** and first lip **1128A** against second longitudinal half **1120A** and second lip **1130A** in a pinching action.

FIG. 11B shows the cross-section of single rail joint **1100**. As discussed above, a connector such as first bolt **1134A** or similar device pulls first lip **1128A** of first longitudinal half **1118A** and second lip **1130A** of second longitudinal half **1120A** toward each other. Passing beneath inner rail segment **234A-1**, first bolt **1134A** thereby urges first lip **1128A** against rail web **904A-1** and second lip **1130A** against rail web **904A-2**. Rail bottom **910A-1** and rail bottom **910A-2** rest on inner fishplate base **1122A**, while first face **1110A-1** abuts second face **1112A-2**. As well, upper plate **912A-1** and upper plate **912A-2** also abut and form a generally combined surface at the top of single rail joint **1100** for contactor **118**.

In an assembly step, first longitudinal half **1118A** is positioned along first end **1106A-1** so first lip **1128A** fits within first rail groove **918** and rail web **904** and lower flange **906** fit within fishplate groove **1132A**. Similarly, second longitudinal half **1120A** is positioned along second end **1108A-2** so second lip **1130A** fits within second rail groove **920**. Tightening of first bolt **1134A** draws first longitudinal half **1118A** and second longitudinal half **1120A** together, pinching first face **1110A-1** against second face **1112A-2**. Accordingly, a single rail joint **1100** or splice between inner rail segment **234A-1** and inner rail segment **234A-2** is accomplished while maintaining lateral overlap across upper plate **912A-1** along first end **1106A-1** and second end **1108A-2** where first face **1110A-1** and second face **1112A-2** engage. The overlapping portions of the rails

permit slippage longitudinally (parallel to the X axis) between inner rail segment **234A-1** and inner rail segment **234A-2** in adjusting the length of power rail **108** during installation, while ensuring electrical conductivity between **234A-1** and **234A-2**.

The split structure of inner fishplate **1102A** can additionally accommodate bends in rail segments **240** that are brought together within single rail joint **1100**. FIG. 12 illustrates this feature with a collective rail joint **1200** as a group of six rail segments **240** being connected through three fishplates. At the right side of FIG. 12, inner rail segment **234A-1**, middle rail segment **234B-1**, and outer rail segment **234C-1** are provided from rail support module **200-1**, which may be installed at first location **602** (FIG. 6), for instance. First end **1106A-1**, first end **1106B-1**, and first end **1106C-1** extend beyond rail support module **200-1** at first location **602**, such as to a position in about the middle of second location **604**. At the left side of FIG. 12, inner rail segment **234A-2**, middle rail segment **234B-2**, and outer rail segment **234C-2** are provided from rail support module **200-2**, which may be installed at third location **606**, for instance. Second end **1108A-2**, second end **1108B-2**, and second end **1108C-2** extend beyond rail support module **200-2** to the position in about the middle of second location **604** (FIG. 6) for connection with the rail segments from rail support module **200-1**. Shown in a state just prior to final tightening, inner fishplate **1102A**, middle fishplate **1102B**, and outer fishplate **1102C** combine and pull together first end **1106A-1** and second end **1108A-2**, first end **1106B-1** and second end **1108B-2**, and first end **1106C-1** and second end **1108C-2** in the same manner as discussed above for the inner rail in FIG. 11A.

The rail segments in the example of FIG. 12 are installed within a curve in haul route **101** of about 20 degrees per 40 feet. The curve bends in the X-Y plane in FIG. 12 with the ends of the rail segments bending in the direction of the -Y axis. This curvature would correspond, for example, to a right turn within haul route **101** of 20 degrees, with inner rail segment **234A** being at an inner position of the curve and outer rail segment **234C** being at an outer position of the curve. With each of the rail segments being pre-bent at about 10 degrees per 40 feet, the rail segments in FIG. 12 would be bent an additional 10 degrees per 40 feet during installation. Typically, this additional bending could be achieved manually, although mechanized assistance for bending is possible. In some examples, the ends of each rail segment, including for instance the first ends **1106** and second ends **1108**, may be kept straight to assist with the splicing into single rail joint **1100** and can extend about 20 inches from the tips of the segments.

As shown in FIG. 12, the ability to slide rail segments longitudinally with respect to each other within inner fishplate **1102A**, middle fishplate **1102B**, and outer fishplate **1102C** enables refined positioning within collective rail joint **1200** to accommodate curves in haul route **101**. For instance, inner rail segment **234A-1** and inner rail segment **234A-2**, at the inner position of the 20 degree curvature, can be slid within fishplate groove **1132A** closer together than outer rail segment **234C-1** and outer rail segment **234C-2** within fishplate groove **1132C**, which are at the outer position of the 20 degree curvature. This positioning leads to more overlap between first face **1110A-1** and second face **1112A-2** than between second face **1110C-1** and second face **1112C-2**. Specifically, as shown in FIG. 12, corresponding to these overlaps, inner longitudinal distance **1202** is longer than middle longitudinal distance **1204**, which is longer than outer longitudinal distance **1206**, as the rails within collec-

21

tive rail joint **1200** form a 20 degree curvature. Thus, the inside rail, the middle rail, and the outer rail have progressively longer distances within the curvature along haul route **101**. While the example of FIG. **12** shows a curvature of 20 degrees per 40 feet, the same principles apply to curvatures of other degrees or directions. For instance, for a joint within a left turn of 10 degrees on haul route **101**, the pre-bent rail segments would not need to be bent additionally on installation and would each be placed to curve in the X-Y plane toward the Y axis in FIG. **12**. In that situation, outer longitudinal distance **1206** would be longer than middle longitudinal distance **1204**, which would be longer than inner longitudinal distance **1202**. Accordingly, the configuration of FIGS. **11** and **12** enable the same rails to be adapted for use in any position or curvature along haul route **101** and avoid the need for rail segments of special shape to be used.

A method **1300** for joining rail segments is defined by representative steps consistent with the present disclosure in the flowchart of FIG. **13**. For method **1300**, as well as other methods described in this disclosure, the steps in which the method is described are not intended to be construed as a limitation. Any number of steps can be combined in any order to implement the disclosed method, can be performed in parallel to implement the processes, and in some embodiments, one or more blocks of the process can be omitted entirely. Moreover, the processes such as **1300** can be combined in whole or in part with other methods. Beginning with a step **1302**, rail segments, such as a first narrowed end of a first rail segment and a second narrowed end of a second rail segment of an inner rail, are positioned within a first fishplate. As explained above, first end **1106A-1** and second end **1108A-2** may be arranged within inner fishplate **1102A** to be joined. In step **1304**, the first narrowed end and the second narrowed end are contacted laterally across a first longitudinal distance within the first fishplate. FIG. **12** illustrates one example where overlapping narrowed ends, such as first end **1106A-1** and second end **1108A-2**, are made to contact each other across inner longitudinal distance **1202**. Further, in step **1306**, at least one first bolt is tightened within the first fishplate and extends beneath at least one of the first rail segment and the second rail segment. The one first bolt may, in some examples, be first bolt **1134A**, which extends through inner fishplate base **1122A** of inner fishplate **1102A**.

Method **1300** continues with step **1308** of positioning other rail segments, such as a third narrowed end of a third rail segment and a fourth narrowed end of a fourth rail segment of an outer rail, within a second fishplate parallel to the first fishplate. For instance, first end **1106C-1** and second end **1108C-2** may be arranged within outer fishplate **1102C** to be joined, as shown in FIG. **12**. In step **1310**, the third narrowed end and the fourth narrowed end are contacted laterally across a second longitudinal distance within the second fishplate, and in step **1312**, at least one second bolt is tightened within the second fishplate extending beneath at least one of the third rail segment and the fourth rail segment. First end **1106C-1** and second end **1108C-2** can be placed in contact across outer longitudinal distance **1206**, with third bolt **1134C** being tightened to pull together second face **1110C-1** and second face **1112C-2**.

Those of ordinary skill in the field will appreciate that the principles of this disclosure are not limited to the specific examples discussed or illustrated in the figures. For example, while rail segments **234** have been discussed in terms of I-beam cross-sections, other configurations for the rails is feasible. Moreover, rail segments **234** are discussed as having a standard shape for all portions of power rails

22

**108**, rail segments **234** may be customized into other types as needed. Moreover, while the present disclosure addresses power rails **108** as having three conductors, implementations have more or fewer conductors are contemplated. In addition, the principles disclosed are not limited to implementation on a work machine. Any moving vehicle deriving electrical power from a ground-based conductor rail could benefit from the examples and techniques disclosed and claimed.

## INDUSTRIAL APPLICABILITY

The present disclosure provides systems and methods for supporting and deploying elevated power rails. A modular structure supports elevated rail segments that connected together deliver electrical power to a moving work machine, such as a hauler at a mining site. Roadside barriers provide a base of support for the rails and are relocatable as needed. To help ensure appropriate positioning for the barriers, and thus the rails, complementary tubular couplers are arranged vertically on opposite ends of the barriers. One coupler has a first diameter supported by an arm and the other has a larger second diameter and a vertical slot. Mating the couplers together concentrically along a central axis can help restrict longitudinal displacement, lateral displacement, slope change, and lateral rotation of adjacent barriers during positioning. Moreover, using one barrier as a temporary alignment structure to position barriers spaced alternately along a haul route can reduce by half the number of barriers used, significantly decreasing material costs.

As noted above with respect to FIGS. **1-7**, an example rail support module generally includes a barrier **204** having a base **206** extending longitudinally between a first end **208** and a second end **210**. A closed coupler **216** is affixed to the first end and has an arm **318** with a thickness joining a first tubular shape. The first tubular shape extends along a first axis A-A substantially orthogonal to the base **206** and has an inner diameter and an outer diameter **410** across the first axis. An open coupler **218** is affixed to second end **210** and has a second tubular shape substantially orthogonal to base **206**. The open coupler includes a gap **316** within the second tubular shape running vertically with a width greater than the thickness of arm **318**. The second tubular shape for the open coupler **218** has an inner diameter **412** larger than outer diameter **410** of the first tubular shape for closed coupler **216**.

In the examples of the present disclosure, the barrier assemblies **202** enable interchangeable placement of rail support modules **200** to deliver electrical power to a moving work machine **100** through elevated power rail **108**. Rail support modules **200** are relocatable and configurable at a worksite along a desired haul route **101** for the work machine **100**. First support pole **220A** and second support pole **220B** keep power rail **108** elevated above normal reach for a person, enhancing safety. Couplers **216** and **218** at ends of barrier **204** mate with couplers on similar barriers, ensuring that adjacent barriers are arranged along the haul route **101** within designed limits for longitudinal displacement, lateral displacement, slope change, and lateral rotation. As a result, undue stress on power rail **108** is minimized from curvatures and slopes along haul route **101** and the risk of disconnection of contactor **118** from power rail **108** as work machine **100** is maneuvered is decreased. Also, using couplers **216** and **218** on one barrier as a temporary alignment structure **202-0** can enable rail support modules **200** to be

placed alternately along haul route **101**, cutting in half the number of support structures otherwise needed for power rail **108**.

Unless explicitly excluded, the use of the singular to describe a component, structure, or operation does not exclude the use of plural such components, structures, or operations or their equivalents. As used herein, the word “or” refers to any possible permutation of a set of items. For example, the phrase “A, B, or C” refers to at least one of A, B, C, or any combination thereof, such as any of: A; B; C; A and B; A and C; B and C; A, B, and C; or multiple of any item such as A and A; B, B, and C; A, A, B, C, and C; etc.

Terms of approximation are meant to include ranges of values that do not change the function or result of the disclosed structure or process. For instance, the term “about” generally refers to a range of numeric values that one of skill in the art would consider equivalent to the recited numeric value or having the same function or result. Similarly, the antecedent “substantially” means largely, but not wholly, the same form, manner or degree, and the particular element will have a range of configurations as a person of ordinary skill in the art would consider as having the same function or result. As an example, “substantially parallel” need not be exactly 180 degrees, but may also encompass slight variations of a few degrees based on the context.

While aspects of the present disclosure have been particularly shown and described with reference to the embodiments above, it will be understood by those skilled in the art that various additional embodiments may be contemplated by the modification of the disclosed machines, systems and methods without departing from the spirit and scope of what is disclosed. Such embodiments should be understood to fall within the scope of the present disclosure as determined based upon the claims and any equivalents thereof.

What is claimed is:

1. A rail support module, comprising:
  - a barrier having a first end, a second end, and a base extending longitudinally between the first end and the second end;
  - a first coupler affixed to the first end, the first coupler including a first hollow cylinder and an arm joining the first hollow cylinder to the first end, the first hollow cylinder extending about a first axis substantially orthogonal to the base and having an inner diameter and an outer diameter; and
  - a second coupler affixed to the second end, the second coupler having a second hollow cylinder extending about a second axis substantially orthogonal to the base, the second hollow cylinder having an inner diameter greater than the outer diameter of the first hollow cylinder, the second hollow cylinder having a central slot extending parallel to the second axis, the central slot having a width within the second hollow cylinder less than the outer diameter of the first hollow cylinder.
2. The rail support module of claim 1, further comprising a first rail pole extending about the first axis within the first coupler and a second rail pole extending about the second axis within the second coupler.
3. The rail support module of claim 2, the first coupler defining a hole having a central axis extending substantially perpendicular to the first axis, the rail support module further including an insert at least partially disposed in the hole, the insert affixing the first rail pole to the first coupler.
4. The rail support module of claim 2, further comprising one or more rail segments between upper ends of the first rail

pole and the second rail pole, the one or more rail segments extending beyond the first end and the second end of the barrier.

5. A rail support assembly, comprising:

- a first barrier having a first end extending substantially perpendicular to a first base;
- a second barrier having a second end, a third end opposite the second end, and a second base, the second end and the third end extending substantially perpendicular to the second base; and

concentric tubes positioned between the first barrier and the second barrier, the concentric tubes comprising:

an exterior tube having a first wall affixed to the first end and extending with a first inner diameter about a vertical axis substantially perpendicular to the first base, the first wall having a central slot defined by a first vertical edge and a second vertical edge, the central slot running substantially parallel to the vertical axis,

an arm affixed to the second end and positioned within the gap central slot, and

an interior tube having a second wall affixed to the arm, the interior tube extending substantially perpendicular to the second base within the first inner diameter of the exterior tube, wherein an annular gap separates the first wall from the second wall and permits lateral movement of the first barrier and the second barrier with respect to each other.

6. The rail support assembly of claim 5, wherein the second barrier further comprises:

a second exterior tube attached to the third end, the second exterior tube extending perpendicular to the second base and having a same size and shape as the exterior tube attached to the first end.

7. The rail support assembly of claim 5, wherein the interior tube has a second inner diameter dimensioned to receive a pole for supporting elevated power rails.

8. The rail support assembly of claim 5, wherein a distance between the arm and one of the first vertical edge and the second vertical edge limits lateral orientation of the first barrier in a horizontal plane about the vertical axis with respect to the second barrier.

9. The rail support assembly of claim 8, wherein the first base extends along a first longitudinal axis and the second base extends along a second longitudinal axis, and wherein the arm, the first vertical edge, and the second vertical edge limit the lateral orientation between the first longitudinal axis and the second longitudinal axis to between about 170 degrees and 190 degrees.

10. The rail support assembly of claim 5, wherein a radial distance between the inner diameter of the exterior tube and an outer diameter of the interior tube limits slope orientation between the first barrier and the second barrier in a vertical plane about a horizontal axis.

11. The rail support assembly of claim 10, wherein the vertical plane bisects the first barrier longitudinally and the horizontal axis extends along an intersection of the first base and the first end.

12. The rail support assembly of claim 10, wherein the vertical plane bisects the second barrier longitudinally and the horizontal axis extends along an intersection of the second base and the second end.

13. The rail support assembly of claim 5, wherein the exterior tube includes an exterior hole having an oblong shape, and the interior tube includes an interior hole having a central axis extending substantially perpendicular to the vertical axis and through the exterior hole.

25

14. A method, comprising:

placing a first support of oblong shape on ground surface substantially parallel to a vehicle travel path defined by the ground surface, the first support having a first longitudinal axis;

arranging an alignment structure of the oblong shape end-to-end with the first support using a first tubular coupling, the first tubular coupling comprising first concentric tubes configured such that the first longitudinal axis is substantially colinear with an alignment axis passing longitudinally through the alignment structure;

positioning a second support of the oblong shape end-to-end with the alignment structure using a second tubular coupling, the second tubular coupling comprising second concentric tubes configured such that the alignment axis is substantially colinear with a second longitudinal axis of the second support;

moving the alignment structure past the second support with respect to the vehicle travel path; and

positioning the alignment structure end-to-end with the second support using a third tubular coupling, the third tubular coupling comprising third concentric tubes configured such that the alignment axis is substantially colinear with a third longitudinal axis of the third support.

26

15. The method of claim 14, wherein the first tubular coupling, the second tubular coupling, and the third tubular coupling have a same size and shape.

16. The method of claim 14, wherein arranging using the first tubular coupling comprises mating a first tubular coupler affixed to the first support with a second tubular coupler affixed to a first end of the alignment structure along a first axis parallel to the first end.

17. The method of claim 16, wherein positioning the second support using the second tubular coupling comprises mating a third tubular coupler affixed to a second end of the alignment structure with a fourth tubular coupler affixed to a near end of the second support along a second axis parallel to the second end.

18. The method of claim 17, wherein positioning the alignment structure using the third tubular coupling comprises mating the second tubular coupler of the alignment structure with a fifth tubular coupler affixed to a far end of the second support along the first axis.

19. The method of claim 18, further comprising:  
moving the alignment structure past the second support with respect to the vehicle travel path; and  
inserting a rail pole into one of the first tubular coupler, the fourth tubular coupler, and the fifth tubular coupler.

20. The method of claim 14, further comprising splicing first rail segments positioned above the first support with second rail segments positioned above the second support.

\* \* \* \* \*