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High power and data delivery in a communications network with safety and fault protection

Abstract

In one embodiment, a method includes receiving at a remote network device, power and data from a central network device, wherein the power is used to power the remote network device, performing auto-negotiation with the central network device, wherein the auto-negotiation includes operating the remote network device in a low voltage mode during fault sensing of a power circuit at the remote network device, and selecting a power operating mode, wherein selecting the power operating mode includes selecting a high voltage mode if no fault is detected during the fault sensing, the high voltage mode comprising DC (direct current) pulse power. An apparatus is also disclosed herein.

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Background/Summary

CROSS REFERENCE TO RELATED APPLICATIONS (1) The present application is a continuation of U.S. application Ser. No. 17/560,446, filed Dec. 23, 2021, which is a continuation of U.S. application Ser. No. 16/913,792, filed Jun. 26, 2020, now U.S. Pat. No. 11,258,520, which is a continuation of U.S. application Ser. No. 15/971,729, entitled HIGH POWER AND DATA DELIVERY IN A COMMUNICATIONS NETWORK WITH SAFETY AND FAULT PROTECTION, filed May 4, 2018, now U.S. Pat. No. 10,735,105, each of which is hereby incorporated by reference in its entirety.

TECHNICAL FIELD

(1) The present disclosure relates generally to communications networks, and more particularly, to safety and fault protection in a communications network with combined high power and data delivery.

BACKGROUND

(2) Power over Ethernet (PoE) is a technology for providing electrical power over a wired telecommunications network from power sourcing equipment (PSE) to a powered device (PD) over a link section. In conventional PoE systems, power is delivered over the cables used by the data over a range from a few meters to about one hundred meters. When a greater distance is needed or fiber optic cables are used, power must be supplied through a local power source such as a wall outlet due to limitations with conventional PoE. Furthermore, today's PoE systems have limited power capacity, which may be inadequate for many classes of devices.

Description

BRIEF DESCRIPTION OF THE DRAWINGS

- (1) FIG. 1 illustrates an example of a network in which embodiments described herein may be implemented.
- (2) FIG. 2 depicts an example of a network device useful in implementing embodiments described herein.
- (3) FIG. 3 is a block diagram illustrating components of a power safety and fault protection system, in accordance with one embodiment.
- (4) FIG. 4 is a flowchart illustrating an overview of a process for low voltage startup with fault detection and digital interlock in a combined power and data delivery system, in accordance with one embodiment.
- (5) FIG. 5 is a flowchart illustrating an overview of a process for pulse power with fault detection between pulses in a combined power and data delivery system, in accordance with one embodiment.
- (6) FIG. 6 is a diagram illustrating a circuit for use with pulse load current and auto-negotiation, in accordance with one embodiment.
- (7) FIG. 7 is a timing diagram for the circuit shown in FIG. 6, in accordance with one embodiment.
- (8) FIG. 8 is a diagram illustrating a circuit for use with unipolar pulse power and auto-negotiation, in accordance with one embodiment.

- (9) FIG. 9 is a timing diagram for the circuit shown in FIG. 8, in accordance with one embodiment.
- (10) FIG. 10 is a diagram illustrating a circuit for use with bipolar pulse power and auto-negotiation, in accordance with one embodiment.
- (11) FIG. 11 is a timing diagram for the circuit shown in FIG. 10, in accordance with one embodiment.
- (12) FIG. 12 is a diagram illustrating line-to-ground fault detection, in accordance with one embodiment.
- (13) FIG. 13 is a diagram illustrating line-to-line fault detection, in accordance with one embodiment.
- (14) FIG. 14 is a diagram illustrating line-to-line fault detection, in accordance with another embodiment.
- (15) FIG. 15 is a diagram illustrating line-to-line fault detection, in accordance with yet another embodiment.
- (16) Corresponding reference characters indicate corresponding parts throughout the several views of the drawings.

DESCRIPTION OF EXAMPLE EMBODIMENTS

Overview

- (17) In one embodiment, a method includes receiving power at an optical transceiver module at a remote network device on a cable delivering power and data from a central network device, operating the remote network device in a low voltage mode during fault sensing at the remote network device, transmitting on the cable, a data signal to the central network device, the data signal indicating an operating status based on the fault sensing, and receiving high voltage power from the central network device on the cable at the remote network device upon transmitting an indication of a safe operating status of the remote network device, wherein the remote network device is powered by the high voltage power.
- (18) In another embodiment, a method generally comprises delivering high voltage direct current (HVDC) pulse power from power sourcing equipment to a powered device over a cable delivering power and optical data, testing a power circuit between the power sourcing equipment and the powered device between pulses, and communicating with the powered device over the cable to identify an operating mode at the powered device based on the testing.
- (19) In yet another embodiment, an apparatus generally comprises an optical interface for receiving optical signals on an optical fiber in a power and data cable at an optical transceiver, an electrical interface for receiving power on an electrical wire in the power and data cable at the optical transceiver for powering the apparatus in a high power mode, and a power module for testing a power circuit and delivering data comprising an operating status of the power circuit over the power and data cable to a combined power and data source. The power module is configured for testing the power circuit in a low voltage power mode.
- (20) Further understanding of the features and advantages of the embodiments described herein may be realized by reference to the remaining portions of the specification and the attached drawings.

Example Embodiments

- (21) The following description is presented to enable one of ordinary skill in the art to make and use the embodiments. Descriptions of specific embodiments and applications are provided only as examples, and various modifications will be readily apparent to those skilled in the art. The general principles described herein may be applied to other applications without departing from the scope of the embodiments. Thus, the embodiments are not to be limited to those shown, but are to be accorded the widest scope consistent with the principles and features described herein. For purpose of clarity, details relating to technical material that is known in the technical fields related to the embodiments have not been described in detail.
- (22) In conventional Power over Ethernet (PoE) systems used to simultaneously transmit power

and data communications, power is delivered over the same twisted pair cable used for data. These systems are limited in range to a few meters to about 100 meters. The maximum power delivery capacity of standard PoE is approximately 100 Watts, but many classes of powered devices would benefit from power delivery of 1000 Watts or more. In conventional systems, when a longer distance is needed, fiber optic cabling is used to deliver data and when larger power delivery ratings are needed, power is supplied to a remote device through a local power source.

(23) As previously noted, it is desirable to increase the power available over multi-function cables to hundreds and even thousands of watts. This capability may enable many new choices in network deployments where major devices such as workgroup routers, multi-socket servers, large displays, wireless access points, fog nodes, or other devices are operated over multi-function cables. This capability would greatly decrease installation complexity and improve the total cost of ownership of a much wider set of devices that have their power and data connectivity needs met from a central hub.

(24) In order to overcome the above issues, power and data delivery systems may be designed to carry higher data rates and higher power delivery (and may also carry integrated thermal management cooling) combined into a single cable, as described in U.S. patent application Ser. No. 15/910,203 (“Combined Power, Data, and Cooling Delivery in a Communications Network”), filed Mar. 2, 2018, which is incorporated herein by reference in its entirety. These connections may be point-to-point, such as from a central hub to one or more remote devices (e.g., full hub and spoke layout). In another example, a single combined function cable may run most of the way to a cluster of powered devices and then split, as described in U.S. patent application Ser. No. 15/918,972 (“Splitting of Combined Delivery Power, Data, and Cooling in a Communications Network”), filed Mar. 12, 2018, which is incorporated herein by reference in its entirety. With high power applications, further safety concerns arise. Additional fault detection and safety protections are needed to prevent a life safety event or an equipment malfunction that may cause serious damage.

(25) The embodiments described herein provide high power delivery over a data system (also referred to herein as advanced power over data) in a communications network with fault detection and safety protection (e.g., touch-safe fault protection). In one embodiment, fault sensing is performed through a low voltage safety check combined with a digital interlock that uses the data system to provide feedback on the power system status and set a power operation mode. The fault sensing may be performed, for example, during a low voltage startup or between high power pulses in a pulse power system. As described in detail below, the pulse power may comprise source voltage pulse power (unipolar or bipolar) or load current pulse power with low voltage fault detection between high voltage power pulses. Fault sensing may include, for example, line-to-line fault detection with low voltage sensing of the cable or powered device and line-to-ground fault detection with midpoint grounding. Touch-safe fault protection may also be provided through cable and connector designs that are touch-safe even with high voltage applied. The power safety features provide for safe system operation and installation and removal (disconnect) of components.

(26) Referring now to the drawings, and first to FIG. 1, an example of a network in which embodiments described herein may be implemented is shown. For simplification, only a small number of nodes are shown. The embodiments operate in the context of a data communications network including multiple network devices. The network may include any number of network devices in communication via any number of nodes (e.g., routers, switches, gateways, controllers, access points, or other network devices), which facilitate passage of data within the network. The network devices may communicate over or be in communication with one or more networks (e.g., local area network (LAN), metropolitan area network (MAN), wide area network (WAN), virtual private network (VPN) (e.g., Ethernet virtual private network (EVPN), layer 2 virtual private network (L2VPN)), virtual local area network (VLAN), wireless network, enterprise network, corporate network, data center, Internet of Things (IoT) network, Internet, intranet, or any other

network).

(27) The network is configured to pass electrical power along with data to provide both data connectivity and electric power to network devices such as switches **14**, routers, access points **15**, or other electronic components and devices. Signals may be exchanged among communications equipment and power transmitted from power sourcing equipment (PSE) **10** to powered devices (PDs) **14**, **15**. As described in detail below, the advanced power over data system delivers power to and from a network (e.g., switch/router system) using an interface module **16** (e.g., optical transceiver module) configured to receive and transmit both data (fiber delivered data) and electrical power (high power energy). In one or more embodiments, the power and data may be delivered over a cable comprising both optical fibers and electrical wires (e.g., copper wires), as described in U.S. patent application Ser. No. 15/707,976 (“Power Delivery Through an Optical System”), filed Sep. 18, 2017, which is incorporated herein by reference in its entirety. In one or more embodiments, the system may further provide cooling and deliver combined power, data, and cooling within a single hybrid cable system, as described, for example, in U.S. patent application Ser. Nos. 15/910,203 and 15/918,972, referenced above.

(28) As shown in the example of FIG. **1**, the advanced power over data system may use building power supplied to a central network device (hub) (e.g., PSE) **10**, which may be located in a premise/entry room, for example. The power may be transmitted from the building entry point to end points (switches **14**, access points **15**), which may be located at distances greater than 100 meters (e.g., 1 km (kilometer), 10 km, or any other distance), and/or at greater power levels than 100 W (watts) (e.g., 250 W, 500 W, 1000 W, 2000 W or any other power level). The central network device **10** comprises a power supply unit (PSU) **11** for receiving and distributing power (e.g., building power from a power grid, renewable energy source, generator, or battery) and a network interface (e.g., fabric **12**, line cards **13**). In the example shown in FIG. **1**, line card A receives data from outside of the building (e.g., from street or other location) and line cards B, C, and D distribute power and data.

(29) The central hub (combined power and data source) **10** is operable to provide high capacity power from an internal power system (e.g., PSU **11** capable of delivering power over and including 5 kW, 100 kW, etc., and driving the plurality of devices **14**, **15**, each in the 100 W-3000 W range (e.g., 100 W or greater, 900 W or greater, 1000 W or greater), or any other suitable power range. The PSU **11** may provide, for example, PoE (Power over Ethernet), PoF (Power over Fiber), HVDC (high voltage direct current), pulse power HVDC, or AC (alternating current). The central network device **10** is operable to receive external power and transmit power over combined delivery power and data cables **18** in the communications network (e.g., network comprising central hub **10** (PSE) and a plurality of network devices **14**, **15** (PDs)). The central network device **10** may comprise, for example, a router, convergence system, or any other suitable line card system. It is to be understood that this is only an example and any other network device operable to transmit power and optical data may be used. One or more of the line cards **13** may also include an interface module **16** (shown at the remote network devices **14**, **15**) operable to transmit power and data on the cables **18**.

(30) The network may include any number or arrangement of network communications devices (e.g., switches **14**, access points **15**, routers, or other devices operable to route (switch, forward) data communications). In one example, the network comprises a plurality of groups of access points **15**, with each group located on a different floor or zone. One or more of the network devices **14**, **15** may also deliver power to equipment using PoE. For example, one or more of the network devices **14**, **15** may deliver power using PoE to electronic components such as IP (Internet Protocol) cameras, VoIP (Voice over IP) phones, video cameras, point-of-sale devices, security access control devices, residential devices, building automation devices, industrial automation devices, factory equipment, lights (building lights, streetlights), traffic signals, fog nodes, IoT devices, sensors, and many other electrical components and devices. In one or more embodiments,

a redundant central hub (not shown) may provide backup or additional power or bandwidth, as needed in the network. In this case, the remote network device **14, 15** would include another interface module **16** for connection with another cable **18** delivering power and data from the redundant central hub.

(31) As previously noted, the central hub **10** may deliver power and data directly to each network device **14** (point-to-point connection as shown for the switches **14** connected to line cards B and D in FIG. 1) or one or more splitting devices (not shown) may be used to connect a plurality of network devices and allow the network to go beyond point-to-point topologies and build passive stars, busses, tapers, multi-layer trees, etc. For example, a single long cable **18** may run to a conveniently located intermediary splitter device (e.g., passive splitter) servicing a cluster of physically close endpoint devices (e.g., access points **15** connected to line card C in FIG. 1). One or more control systems for the power and data may interact between the central hub **10** and the remote devices **15** (and their interface modules **16**) to ensure that each device receives its fair share of each resource from the splitting device, as described in U.S. patent application Ser. No. 15/918,972, referenced above.

(32) Cables (combined cable, multi-function cable, multi-use cable, hybrid cable) **18** extending from the network device **10** to the switches **14** and access points **15** are configured to transmit power and data, and include both optical fibers and electrical wires. The cable **18** may include, for example, two power lines (conductors) and two data lines (optical fibers). It is to be understood that that this is only an example and the cable **18** may contain any number of power or data lines. For example, instead of using two optical fiber paths to transfer data from the central hub **10** to the remote device **14, 15** and from the remote device to the central hub, a bidirectional optical system may be utilized with one wavelength of light going downstream (from central hub **10** to remote device **14, 15**) and a different wavelength of light going upstream (from remote device **14, 15** to central hub **10**), thereby reducing the fiber count in the cable from two to one. The cable **18** may also include additional optical fibers or power lines. The cables **18** may be formed from any material suitable to carry both electrical power and optical data (e.g., copper, fiber) and may carry any number of electrical wires and optical fibers in any arrangement.

(33) As previously noted, the cables **18** may also carry cooling for thermal management of the remote network communications devices **14, 15**. For example, in one or more embodiments, the cables **18** extending from the central hub **10** to the remote network devices **14, 15** may be configured to transmit combined delivery power, data, and cooling in a single cable. In this embodiment, the cables **18** may be formed from any material suitable to carry electrical power, data (e.g., copper, fiber), and coolant (liquid, gas, or multi-phase) and may carry any number of electrical wires, optical fibers, and cooling tubes in any arrangement.

(34) The cables **18** comprise a connector at each end configured to couple with the interface module **16** at the network devices **10, 14, 15**. The connector may comprise, for example, a combined power and data connector (hybrid copper and fiber) configured to connect to an optical transceiver, as described in U.S. patent application Ser. No. 15/707,976, referenced above. The connector may comprise, for example, a modified RJ-45 type connector.

(35) In one or more embodiments, the connector and cable **18** are configured to meet standard safety requirements for line-to-ground protection and line-to-line protection at relevant high voltage by means including clearance and creepage distances, and touch-safe techniques. The connector may comprise safety features, including, for example, short-pin for hot-plug and hot-unplug without current surge or interruption for connector arcing protection. The connector may further include additional insulation material for hot-plug and hot-unplug with current surge or interruption with arc-flash protection and reliability life with arcing. The insulated cable power connector terminals are preferably configured to meet touch voltage or current accessibility requirements.

(36) Each network device **10, 14, 15** comprises an interface module **16** (connected to line card **13** at

the central network device **10**) operable to deliver the combined power and data from the PSE **10** or receive the combined power and data at the PD **14, 15**. In one or more embodiments, the interface module **16** may comprise an optical transceiver module configured to deliver (or receive) power along with the optical data. For example, in one embodiment, the interface module **16** comprises a transceiver module modified along with a fiber connector system to incorporate copper wires to deliver power through the optical transceiver to the powered device **14, 15** for use by the network communications devices, as described in U.S. patent application Ser. No. 15/707,976, referenced above or in U.S. patent application Ser. No. 15/942,015 (“Interface Module for Combined Delivery Power, Data, and Cooling at a Network Device”), filed Mar. 30, 2018, which is incorporated herein by reference in its entirety. It is to be understood that these are only examples of interface modules that may be used to deliver or receive high power and optical data.

(37) The interface module **16** (optical module, optical transceiver, optical transceiver module, optical device, optics module, silicon photonics module) is configured to source or receive power. The interface module **16** operates as an engine that bidirectionally converts optical signals to electrical signals or in general as an interface to the network element copper wire or optical fiber. In one or more embodiments, the interface module **16** may comprise a pluggable transceiver module in any form factor (e.g., SFP (Small Form-Factor Pluggable), QSFP (Quad Small Form-Factor Pluggable), CFP (C Form-Factor Pluggable), and the like), and may support data rates up to 400 Gbps, for example. Hosts for these pluggable optical modules include line cards **13** on the central network device **10**, switches **14**, access points **15**, or other network devices. The host may include a printed circuit board (PCB) and electronic components and circuits operable to interface telecommunications lines in a telecommunications network. The host may be configured to perform one or more operations and receive any number or type of pluggable transceiver modules configured for transmitting and receiving signals.

(38) Also, it may be noted that the interface module **16** may be configured for operation in point-to-multipoint or multipoint-to-point topology. For example, QFSP may breakout to SFP+. One or more embodiments may be configured to allow for load shifting. The interface module **16** may also be configured for operation with AOC (Active Optical Cable) and form factors used in UWB (Ultra-Wideband) applications, including for example, Ultra HDMI (High-Definition Multimedia Interface), serial high bandwidth cables (e.g., thunderbolt), and other form factors.

(39) The interface module (optical transceiver) **16** provides for power to be delivered to the switches **14** and access points **15** in locations where standard power is not available. The interface module **16** may be configured to tap some of the energy and make intelligent decisions so that the power source **10** knows when it is safe to increase power on the wires without damaging the system or endangering an operator, as described below. The interface module **16** may include one or more sensors, monitors, or controllers for use in monitoring and controlling the power and data, as described in detail below with respect to FIG. 3.

(40) In one or more embodiments, there is no need for additional electrical wiring for the communications network and all of the network communications devices operate using the power provided by the advanced power over data system. In addition to the network devices **14, 15** comprising interface modules **16** operable to receive and transmit power over electrical wires and optical data over fibers, the network may also include one or more network devices comprising conventional optical modules that only process and transmit the optical data. These network devices would receive electrical power from a local power source such as a wall outlet. Similarly, specialized variants of transceivers **16** may eliminate the optical data interfaces, and only interconnect power (e.g., moving data interconnection to wireless networks). As previously noted, one or more of the network devices may also receive cooling over cable **18** in addition to power, data, or power and data.

(41) In one or more embodiments, a distributed control system comprising components located on the central hub's controller and on the remote device's processor may communicate over the fiber

links in the combined cable **18**. Monitoring information from power sensors (e.g., current, voltage) or data usage (e.g., bandwidth, buffer/queue size) may be used by the control system in managing or allocating power or data.

(42) As previously noted, the advanced power over data system may be configured to deliver PoE, PoF, high voltage DC (HVDC), AC power, or any combination thereof. The HVDC power may comprise steady state HVDC or pulse power HVDC. The steady state and pulse power HVDC may be unipolar or bipolar (switching DC). In one or more embodiments, the system may employ a dual-power mode that detects and negotiates between the power source **10** and powered device **14**, **15**, as described below with respect to FIG. **3**. This negotiation distinguishes between and accommodates different power-delivery schemes, such as standard PoE or PoF, high power, pulse power, or other power modes capable of power delivery through the interface module **16**. For example, standard PoE distribution may be used for remote network devices rated less than about 100 W. For higher power remote powered devices, pulse power or other higher voltage techniques may be used to create an efficient energy distribution network.

(43) The remote network device **14**, **15** may use a small amount of power at startup to communicate its power and data requirements to the central network device **10**. The powered device **14**, **15** may then configure itself accordingly for full power operation. In one example, power type, safety operation of the module, and data rates are negotiated between the central hub **10** and network device **14**, **15** through data communications signals on the optical fiber. The interface module **16** communicates any operational fault, including the loss of data. Such fault may result in power immediately being turned off or switching to a low power (low voltage) mode. Full power supply may not be reestablished until the powered device is able to communicate back in low power mode that higher power may be safely applied.

(44) As described in detail below, the advanced power over data system may test the network devices or cables to identify faults or safety issues. In one embodiment, a low voltage power mode may be used during startup (or restart) to test the network and components (as described below with respect to the flowchart of FIG. **4**). In another embodiment, testing is performed between high voltage pulses in a pulse power system (as described below with respect to the flowchart of FIG. **5**). The off time between pulses may be used for line-to-line resistance testing for faults and the pulse width may be proportional to DC line-to-line voltage to provide touch-safe fault protection (e.g., about 1 ms at about 1000 V).

(45) The testing (fault detection, fault protection, fault sensing, touch-safe protection) may comprise auto-negotiation between the PSE (central hub **10**) and PDs (remote network devices **14**, **15**). For example, the network may be configured using auto-negotiation before receiving a digital indication (interlock) that it is safe to apply and maintain high power. The auto-negotiation may comprise low voltage sensing of a PD power circuit or cable for line-to-line fault detection (described below with respect to FIGS. **13** and **14**). Low voltage (e.g., less than or equal to 12 VDC (volts direct current), 5-12 VDC, or any other suitable low voltage (e.g., >60 VDC)) resistance analysis may be used for auto-negotiation. The pulse power high voltage DC may be used with a pulse-to-pulse decision for touch-safe line-to-line fault interrogation between pulses for personal safety. Line-to-line touch shock protection may be provided with a source pulse off-time between pulses for resistance across line detection between pulses.

(46) Ground-fault-detection (GFD) and ground-fault-isolation (GFI) line-to-ground fault detection may be performed to provide fast high voltage interruption with ground fault protection (shock protection) during high voltage operation as part of using a high-resistance midpoint ground circuit (described below with respect to FIG. **12**). A high voltage DC supply line-to-ground fault protection circuit may be used to turn off power quickly to provide touch-safe shock protection. GFD and GFI may provide shut off in approximately 10 μ s (microseconds), for example. A midpoint grounding method by the power source may also be used to allow higher peak pulse line-line voltage within the wire/conductor insulation and isolation ratings for line-ground protection

and also provide touch-safe line-to-ground fault for personal safety and to meet safety standards. The system may also be designed for adjustable time and current versus voltage for personal shock protection.

(47) The system may be configured to meet safety standards, including, for example, IEC (International Electrotechnical Commission) standard Nos. 62368-3:2017 (“Audio/video information and communication technology equipment—Part 3: Safety aspects for DC power transfer through communication cables and ports”), IEC 60950-1:2005 (“Information technology equipment—Safety— Part 1: General requirements”), IEC 60947 (“Low-voltage switchgear and controlgear”), or any other applicable standard to provide touch-safe shock protection for personnel for high voltage (higher power) applications in the advanced power over data system. The system may be configured, for example, to limit shock current with line-to-ground fault limit of about 5 mA (e.g., less than 10 mA) and line-to-line fault limit of about 0.5 A for 1 ms using about 2.5 kohms across HVDC power. Appropriate techniques (e.g., fail-safe Safety Agency Approved Listed components, redundant circuits or components) may be employed in order to meet safety standards. The embodiments described herein may be configured to meet single fault protection or other safety requirements. It is to be understood that the standards and limits discussed herein are only provided as examples and other safety limits or standards may be used, without departing from the scope of the embodiments.

(48) It is to be understood that the network devices and topology shown in FIG. 1, and described above is only an example and the embodiments described herein may be implemented in networks comprising different network topologies or network devices, without departing from the scope of the embodiments. For example, the network may comprise any number or type of network communications devices that facilitate passage of data over the network (e.g., routers, switches, gateways, controllers), network elements that operate as endpoints or hosts (e.g., servers, virtual machines, clients), and any number of network sites or domains in communication with any number of networks. Thus, network nodes may be used in any suitable network topology, which may include any number of servers, virtual machines, switches, routers, or other nodes interconnected to form a large and complex network, which may include cloud or fog computing. Nodes may be coupled to other nodes or networks through one or more interfaces employing any suitable connection, which provides a viable pathway for electronic communications along with power.

(49) FIG. 2 illustrates an example of a network device **20** (e.g., central hub **10**, switch **14**, access point **15** in FIG. 1) that may be used to implement the embodiments described herein. In one embodiment, the network device **20** is a programmable machine that may be implemented in hardware, software, or any combination thereof. The network device **20** includes one or more processors **22**, memory **24**, interface **26**, optical module **28** (e.g., power+optics interface module **16** in FIG. 1), and power module (controller) **29**. The network device may also comprise one or more cooling components **21** (sensors, control valves, pumps, etc.) if the system is configured for combined power, data, and cooling delivery.

(50) Memory **24** may be a volatile memory or non-volatile storage, which stores various applications, operating systems, modules, and data for execution and use by the processor **22**. For example, components of the optical module **28** (e.g., code, logic, or firmware, etc.) may be stored in the memory **24**. The network device **20** may include any number of memory components.

(51) The network device **20** may include any number of processors **22** (e.g., single or multi-processor computing device or system), which may communicate with a forwarding engine or packet forwarder operable to process a packet or packet header. The processor **22** may receive instructions from a software application or module, which causes the processor to perform functions of one or more embodiments described herein. The processor **22** may also operate one or more components of the power control module **29** for fault detection, auto-negotiation, digital interlock, etc. The control system may comprise components (modules, code, software, logic)

located at the central hub **10** and the remote device **14**, **15**, and interconnected through the combined power and data cable **18** (FIGS. **1** and **2**). The control system may also receive input from power sensors or data monitoring devices, as described below with respect to FIG. **3**. The power module **29** may communicate with the control system at the central network device **10** to auto-negotiate the status of the power system, identify any faults in the power system (e.g., cables or powered device), and select a power operating mode. As previously noted, the auto-negotiation may be performed during a low voltage startup or between pulses in a pulse power system. One or more control system or power module components may be located at the optical module **28**.

(52) Logic may be encoded in one or more tangible media for execution by the processor **22**. For example, the processor **22** may execute codes stored in a computer-readable medium such as memory **24**. The computer-readable medium may be, for example, electronic (e.g., RAM (random access memory), ROM (read-only memory), EPROM (erasable programmable read-only memory)), magnetic, optical (e.g., CD, DVD), electromagnetic, semiconductor technology, or any other suitable medium. In one example, the computer-readable medium comprises a non-transitory computer-readable medium. Logic may be used to perform one or more functions described below with respect to the flowcharts of FIGS. **4** and **5**. The network device **20** may include any number of processors **22**.

(53) The interface **26** may comprise any number of network interfaces (line cards, ports, connectors) for receiving data or power, or transmitting data or power to other devices. The network interface may be configured to transmit or receive data using a variety of different communications protocols and may include mechanical, electrical, and signaling circuitry for communicating data over physical links coupled to the network interfaces. For example, line cards may include port processors and port processor controllers. The interface **26** may also comprise fluid ports if the system is configured for cooling. One or more of the interfaces **26** may be configured for PoE+F+C (Power over Ethernet+Fiber+Cooling), PoE+F, PoE, PoF, or similar operation.

(54) The optical module **28** may include logic, firmware, software, etc. for use in monitoring or controlling the advanced power over data system, as described below. For example, the optical module **28** may comprise hardware or software for use in power detection, power monitor and control, or power enable/disable. The optical module **28** may further comprise one or more of the processor or memory components, or interface **26** for receiving or delivering power and data. As previously described, power is supplied to the optical module by power supply **27** and the optical module **28** provides power to the rest of the components at the network device **20**.

(55) It is to be understood that the network device **20** shown in FIG. **2** and described above is only an example and that different configurations of network devices may be used. For example, the network device **20** may further include any suitable combination of hardware, software, algorithms, processors, devices, components, or elements operable to facilitate the capabilities described herein.

(56) FIG. **3** is a block diagram illustrating components for use in power monitor and control, auto-negotiation, and fault protection at a network device **30**, in accordance with one embodiment. One or more of the components shown in FIG. **3** may be located at the interface module **16** or in communication with one or more components of the interface module (FIGS. **1** and **3**). The cable **18** carrying the high power and data is shown with cable connector **36** coupled to the interface module in FIG. **3**. The power is received at an electrical interface **37** and the data is received and transmitted at an optical interface **38**. Connector **36** may comprise a single physical component or a single component with modular parts for each function, for example.

(57) The network device **30** includes optical/electrical components **31** for receiving optical data and converting it to electrical signals (or converting electrical signals to optical data) and power components including, power detection modules **32a**, **32b**, power monitor and control modules **33**, and power enable/disable modules **34**. Although PoE and pulse power are described in conjunction

with detection elements **32a**, **32b**, it should be understood that other power delivery schemes including AC, DC, and USB may be supported with similar elements. The power components may be isolated from the optical components **31** via an isolation component (e.g., isolation material or element), which electromagnetically isolates the power circuit from the optical components to prevent interference with operation of the optics. The network device **30** includes an auto detection module **35** that operates with the pulse power detection module **32a** and PoE detection module **32b**. One or more functions of the detection elements **32a**, **32b**, auto detection module **35**, power monitor and control modules **33**, or auto-negotiation module **39** (described below) may be combined into a power module and operate within the interface module.

(58) The auto-negotiate/digital interlock module **39** may be used in performing one or more fault detection, auto-negotiation, or digital interlock processes described herein. As described in detail below, auto-negotiation may include communication between the central network device and the remote network device and interaction between controllers at the central network device and remote network device. One or more control signals or monitoring information may be transmitted over the data line (e.g., optical fibers) in the combined power and data cable **18** to provide an operating status (e.g., fault/no fault) of the network device, cable, or power circuit.

(59) In the example shown in FIG. **3**, each module **32a**, **32b** is in communication with its own power monitor and control module **33** and power enable/disable module **34**. The circuit detects the type of power applied to the network device **30**, determines if PoE or pulsed power is a more efficient power delivery method, and then uses the selected power delivery mode. As noted above, additional modes may support other power+data standards (e.g., USB (Universal Serial Bus)).

(60) The network device **30** is configured to calculate available power and prevent the cabling system from being energized when it should not be powered. The power monitor and control modules **33** continuously monitor power delivery to ensure that the system can support the needed power delivery and no safety limits (e.g., voltage, current) are exceeded. The power monitor and control modules **33** may also monitor optical signaling and disable power if there is a lack of optical transitions or communication with the power source. Power monitor and control functions may sense the voltage and current flow, and report these readings to a central control function. In one embodiment, the network device **30** uses a small amount of power (e.g., $\leq 12\text{V}$, $\leq 60\text{V}$) at startup or restart to communicate its power and data requirements and status. The network device **30** may then be configured for full power operation (e.g., $> 60\text{V}$, $\geq 500\text{V}$, $\geq 1000\text{V}$) (e.g., at high power enable/disable module **34**) if no faults or safety conditions are detected. If a fault is detected, full power operation may not be established until the network device communicates in low power mode that high power can be safely applied. As described below, the auto-negotiate (fault detection module) **39** may be used to test the network and components for touch-safe interrogation between pulses in a pulse power system or during a low voltage startup mode. The auto-negotiation module **39** communicates with a control system at the central network device to select a safe operating mode (e.g., determine that it is safe to apply high voltage power), identify a fault in the circuit (e.g., line-to-line or line-to-ground fault detection), and shutdown power if a fault is identified.

(61) FIG. **4** is a flowchart illustrating an overview of an auto-negotiation startup process with safety interlock, in accordance with one embodiment. At step **40**, a remote network device (e.g., switch **14** in FIG. **1**) receives combined delivery power and data from a central network device (e.g., combined power and data source **10** in FIG. **1**). The power is received at an optical transceiver module **16**. The remote network device **14** operates in a low voltage startup mode during fault sensing (detection) at the remote network device (step **42**). The low voltage mode may be, for example, $\leq 12\text{V}$ (volts), for example. The fault sensing may be performed to check the operational status of a power circuit extending between the central network device **10** over the combined delivery cable **18** to the remote network device **14**. As described below, the fault sensing may be performed using control circuits at the remote network device **14**, central network device **10**, or both network devices. The remote network device **14** transmits a data signal to the central

network device **10** over the combined delivery cable **18** indicating an operating status based on the fault sensing (step **44**). This may include, for example, an auto-negotiation process (auto-negotiating) performed between the central network device **10** and remote network device **14**. If no faults are present at the network device, the remote network device converts to high power operation and a digital interlock is set between the central network device **10** and remote network device **14** (steps **46** and **48**). The high power operation may comprise, for example, power $\geq 100\text{V}$, $\geq 500\text{V}$, about 1000V (differential voltage), $\geq 100\text{ W}$, about 1000 W (load power), or any other suitable high power. The remote network device **14** receives high voltage power from the central network device **10** on the cable **18** upon transmitting an indication of a safe operating status at the remote network device, and the network device is powered by the high voltage power. If a fault is detected, the process may be repeated after a specified interval or for a specified number of times to determine if there was an error in the testing or a fault is still present in the power circuit. As described below with respect to FIG. 5, a pulse load current may be applied at the remote network device **14** and fault detection performed between pulses after the startup process is performed.

(62) FIG. 5 illustrates an overview of a fault protection process using fault sensing between power pulses in a combined delivery power and data system, in accordance with one embodiment. At step **50** a PSE (e.g., central hub **10** in FIG. 1) delivers high voltage direct current (HVDC) pulse power to a powered device (e.g., remote network device **14** in FIG. 1) over a cable **18** delivering power and data. A power circuit between the PSE and PD is tested between pulses (step **52**). The PSE communicates with the PD over the cable to identify an operating mode at the PD **14** based on the testing (step **54**). If no faults are detected, the PD **14** operates with HVDC pulse power and the process continues with fault detection and auto-negotiation performed between pulses. If a fault is detected, power to the PD may be shut-off or the PD may switch to a low power mode. As described below, the pulse power may be HVDC load pulse power (FIGS. 6 and 7), source unipolar pulse power (FIGS. 8 and 9), or source bipolar (switched) power (FIGS. 10 and 11).

(63) It is to be understood that the processes shown in FIGS. 4 and 5 and described above are only examples and that steps may be added, modified, removed, or combined, without departing from the scope of the embodiments.

(64) FIGS. 6, 8, and 10 illustrate examples of circuits that may be used for fault detection with pulse power in the advanced power over data system described herein. FIG. 6 illustrates a circuit that may be used with HVDC pulse load current with off-time auto-negotiation and shut-down for touch-safe protection. FIGS. 8 and 10 illustrate circuits that may be used with HVDC unipolar source pulse power and HVDC bipolar source pulse power, respectively, with cable discharge pulse and open circuit off-time fault sensing and auto-negotiation. FIGS. 7, 9, and 11 illustrate timing examples for auto-negotiation in the circuits shown in FIGS. 6, 8, and 10, respectively. As previously described, a low voltage startup process may be performed to check for faults at startup before pulse power is applied and auto-negotiation is performed between pulses. The low voltage testing (at startup or between pulses) may include low voltage line-to-line sensing, as described below with respect to FIGS. 13 and 14. In addition to the low voltage sensing, a high voltage, line-to-ground test may be performed, as described below with respect to FIG. 12.

(65) FIG. 6 illustrates a circuit for use with HVDC pulse load current with off-time auto-negotiation, in accordance with one embodiment. The input power is received at an isolation stage **60** at the PSE, generally indicated at **61**, and output power is delivered at an isolation stage **62** at the PD, generally indicated at **63**. The PSE **61** provides power to the PD **63** over a combined power and data cable, generally indicated at **65**, which in this example comprises a 4 pair cable (e.g., 100 m, 4 pair cable, or any other suitable cable configured to deliver high voltage power and data). The PSE **61** may provide, for example, regulated or unregulated 550 VDC with a 1 KW load and $\pm 275\text{ VDC}$ power (e.g., about 1042 W , 543V , 1.92 A at the PD **63**). The steady state power may be unipolar or bipolar. It is to be understood that the power, voltage, current values, and cable described herein are only provided as examples and that high voltage power may be provided at

different power levels or other cable configurations may be used over different distances without departing from the scope of the embodiments.

(66) As shown in FIG. 6, the PSE **61** includes a sensing/control circuit **64** and the PD **63** includes a soft-start/voltage control circuit **66**. The soft-start/voltage control circuit **66** may be used, for example, to limit the voltage applied at the powered device during startup. The PSE **61** further comprises a PSE modulator switch **Q1**, source capacitor **Cs**, resistors **R1**, **R2**, **R3** and auto-negotiate current sense circuit **69**. The PD **63** portion of the power circuit comprises a load capacitor **C1**, diode **D1**, inductor **L1**, and PD isolation modulator switch **Q2**. Switches **Q1**, **Q2** may comprise, for example, a solid state switch or any other suitable device. In one example, PSE switch **Q1** is switched on to provide continuous HVDC power unless a fault is detected during auto-negotiation of cable resistance when PD isolation switch **Q2** is switched off, as described below with respect to the timing diagram shown in FIG. 7.

(67) It is to be understood that the circuit shown in FIG. 6 is only an example and that other arrangements or combinations of components (e.g., resistors (**R1**, **R2**, **R3**), capacitors (**Cs**, **C1**), diodes (**D1**, **D2**), inductor (**L1**), switches (**Q1**, **Q2**), or number of pairs in cable) may be used without departing from the scope of the embodiments.

(68) FIG. 7 illustrates an example of a timing diagram for auto-negotiation in the circuit of FIG. 6, in accordance with one embodiment. As shown in FIG. 7, **Q1** voltage is on and continuous (as indicated at **70**) until a fault is detected during **Q2** off-time. In this example, **Q2** on-time (**72**) is 1.0 ms (millisecond). The resistance analysis and auto-negotiation time (**74**) is 100 μ s (microsecond). If no faults are identified during the analysis and auto-negotiation period **74**, the cycle is repeated with **Q2** on for 1.0 ms (**72**). In this example, the period covers 1.1 ms with a 90.9% duty cycle.

(69) In another example, PSE switch **Q1** in FIG. 6 may be switched on for a high voltage pulse (e.g., for 1 ms) and switched off (e.g., for 100 μ s) for auto-negotiation of cable resistance with PD isolation switch **Q2** off. Voltage may be measured across the capacitors **Cs**, **C1** during testing. When the switches **Q1**, **Q2** are turned off (circuit open), the voltage across the capacitor **C1** will decay as it is discharged through the resistor. If the voltage decays too quickly or too slowly, a fault may be present. Calculated line resistance may also be used and compared to a specified value to determine if there is a fault in the power circuit (cable, PSE, or PD). In one example, **R1** and **R2** may be rated at 560 kohms each and the auto-negotiate current sense circuit **69** may comprise a 220 kohm resistor **R3** and 12V power. It should be noted that these values are only provided as examples and other resistance or voltage values may be used.

(70) FIG. 8 shows a circuit for use with HVDC unipolar source pulse power, in accordance with one embodiment. The system provides cable discharge pulse and open circuit off-time fault sensing line-to-ground or line-to-line abnormal resistance auto-negotiate for touch-safe protection. As described above with respect to FIG. 6, the input power is received at an isolation stage **80** of the PSE, generally indicated at **81**, and power is output from an isolation stage **82** at the PD, generally indicated at **83**. The source **80** operates as both a low voltage source for startup (e.g., 56 VDC or other low voltage (≤ 60 VDC)) and a high voltage source (e.g., 250-550 VDC) for pulsing with switch **Q1** operating as a modulator. The PSE **81** and PD **83** communicate over a combined high power and data cable, generally indicated at **85**. The PSE **81** includes a sensing/control circuit **84** and the PD **83** includes a soft-start/voltage control circuit **86**. The sensing control circuit **84** may include touch-safe circuits for line-to-line shock with low voltage (e.g., about 12-56V) and measures resistance at the PD as an interlock connection to enable high voltage startup and auto-negotiation between pulses with touch shock protection (e.g., 1-10 kohm) that inhibits the next high voltage pulse. The sensing circuit **84** may also include touch-safe circuits for line-to-ground shock with high resistance midpoint ground unbalance that inhibits high voltage during pulse.

(71) As shown in FIG. 8, the PSE **81** comprises switches **Q1** and **Q2**, capacitor **Cs**, and resistors **R1** and **R2**. Cable discharge transistor **Q2** may incorporate controlled turn-on or other means to limit peak discharge current and cable ringing. In one example, the PSE **81** provides 1000 VDC for a 1

kW load at the PD **3** with +1.1 kV pulse power. The PD circuit comprises a capacitor Cf, diode Dfw, inductor Lf, resistor R3 (for PD connection resistor detect), and switch Q3. Switch Q3 may provide soft-start, off-time isolation, and regulation. In one example, resistors R1 and R2 comprise 560 kohms resistors and R3 is a 100 kohm resistor.

(72) It is to be understood that the circuit shown in FIG. **8** is only an example and that other arrangements or combinations of components (e.g., resistors (R1, R2, R3), capacitors (Cs, Cf), diode (Dfw), inductor (Lf), or switches (Q1, Q2, Q3)) may be used without departing from the scope of the embodiments. Also, different resistance or voltage values may be used.

(73) FIG. **9** shows a timing diagram with a 1.0 ms-on/0.1 ms-off duty cycle for the circuit shown in FIG. **8**. Q1 and Q3 power on-time in this example is 1.0 ms (indicated at **90**). The Q2 cable discharge time (**92**) is 50 μ s and the resistance analysis and auto-negotiation time (**94**) is 50 μ s. This period is repeated every 1.1 ms for a 90.9% duty cycle.

(74) FIG. **10** illustrates a circuit for use with HVDC bipolar pulse power in accordance with one embodiment. The system provides cable discharge pulse open circuit off-time fault sensing line-to-line or line-to-ground abnormal resistance auto-negotiate for touch-safe protection. The circuit includes isolation stage **100** at the PSE, generally indicated at **101**, and isolation stage **102** at the PD, generally indicated at **103**. The PSE **101** and PD **103** are in communication over combined power and data cable, generally indicated at **105**. In one example, the current may be limited to about 1-1.2 amps to allow use of a 4-pair cable. The PSE **101** comprises a sensing/control circuit **104** and the PD **103** includes a soft-start/voltage control circuit **106**, as previously described. The PSE **101** comprises switches Q1, Q2, Q3, Q4 that may be used to provide a low voltage startup or fault detection between pulses, as described below with respect to FIG. **11**. The PSE power circuit further includes resistors R1, R2 (e.g., 560 kohm or any other suitable resistance), and an auto-negotiate current sense circuit **109**, which may provide resistance (R3) (e.g., 220 kohm or other suitable resistance) and 12V (low voltage) power. In the example shown in FIG. **10**, the low voltage auto-negotiate current sense circuit further includes a high voltage blocking switch (Q5).

(75) It is to be understood that the circuit shown in FIG. **10** is only an example and that other arrangements or combinations of components (e.g., resistors (R1, R2, R3), capacitors (C1, C2, C3, C4), diodes (D1, D2, D3, D4), inductors (L1, L2), and switches (Q1, Q2, Q3, Q4, Q5)) may be used without departing from the scope of the embodiments.

(76) FIG. **11** illustrates a timing diagram for the circuit shown in FIG. **10**, in accordance with one embodiment. Q1/Q4 power is on for 0.5 ms (**110**) and Q3/Q2 power is on for 0.5 ms (**112**). Q2/Q4 cable discharge time (**114**) is 50 μ s and resistance analysis and auto-negotiation time (**116**) is 50 μ s. The 1.1 ms time period is repeated for a 90.9% duty cycle.

(77) It is to be understood that the timing diagrams shown in FIGS. **7**, **9**, and **11** are only examples and that the timing or duty cycle may be different than shown without departing from the scope of the embodiments. For example, the pulse power duty cycle may be between 90% and 95%.

(78) FIGS. **12-13** illustrate examples of touch-safe protection from line-to-ground (FIG. **12**) and line-to-line (FIGS. **13** and **14**) electrical shock. In one or more embodiments, a midpoint grounding line-ground (GFI/GFD) shock protection sensing circuit may be used during high voltage operation. Line-to-ground (GFI/GFD) fault sensing may also be provided during low voltage operation to prevent a high voltage pulse. In one or more embodiments, high voltage pulse power is only allowed after auto-negotiation of safe PD connection (e.g., secure with PD resistance value of about 100 kohms) and no line-to-line body resistance fault (e.g., less than about 8 kohms at startup and for next high voltage pulse). This minimizes the chance for any contact with exposed electrical contacts. The short high voltage pulse time before another auto-negotiation period between high voltage pulses mitigates the risk of high unsafe currents and electric shock danger.

(79) FIG. **12** illustrates line-to-ground fault detection, in accordance with one embodiment. In one example, the PSE provides source regulated or unregulated HVDC (e.g., 550 VDC) and the PD has load regulated HVDC (e.g., 215 VDC). The PSE and PD are connected over a combined delivery

power and data cable, as previously described. The line-to-ground fault detection may be used with continuous power or with pulse power when the high voltage is on. Fast high voltage interruption is provided with ground fault protection (shock protection) during high voltage. In one example, 800 k-1.4 k-8 kohms body resistance at 550 VDC for about 1 mA, results in an interrupt in <1 ms. A PSE control circuit **120** controls a PSE pulse modulator switch **Q1**, PSE cable discharge switch **Q2**, and GF (ground fault) comparators **124**. PD control circuit **122** controls converter isolation switch **Q3** that has an initial low voltage startup delay before turn-on with the low voltage power, or wait for the first high voltage pulse to startup. The PD DC/DC converter isolation switch **Q3** isolates the DC/DC converter high and low voltages from the low voltage auto-negotiation line-to-line circuit sensing the cable circuit resistance for safe PD connection and no low resistance of a body resistance fault. This switch circuit may include operation as a soft-start inrush control, reverse polarity protection and also as a PWM (pulse-width modulation) voltage controller. The PD power circuit also includes a PD connection resistor detect resistor **R1**.

(80) FIGS. **13** and **14** illustrate two examples of circuits for use in line-to-line fault detection. High voltage touch-safe protection is provided for line-to-line shock for pulse power applications while low voltage is on between high voltage pulses or low power mode during startup. For example, during startup auto-negotiation may be performed using sensing of PD connection with correct resistor detection. Low voltage auto-negotiation may also be performed for line-to-line fault protection (shock protection) before next high voltage pulse. In one example, 800 k-1.4 k-8 kohms body resistance is assumed during low voltage test before next pulse. The circuits shown in FIGS. **13** and **14** each include control circuits **130**, **132** at the PSE and PD, respectively. In the circuit shown in the example of FIG. **13**, a fault sense comparator **134** and current sense amplifier **136** are used in line-to-line fault detection at the PSE. In the circuit shown in the example of FIG. **14**, fault sensing is performed to identify an open cable (e.g., about 11.1V), cable to PD fault (e.g., about 6.5V), or body fault (e.g., less than about 1.8V). The PSE circuit includes a PSE pulse modulator switch **Q1** and PSE cable discharge switch **Q2**. The PD circuit includes PD DC/DC converter isolation switch **Q3** and resistor **R1** for use in PD connector resistor detection, as previously described.

(81) FIG. **15** illustrates another example of a circuit for use in line-to-line fault detection, in accordance with one embodiment. High voltage is turned off and the PD load circuit is isolated, as previously described. The cable voltage capacitance discharge RC-time for resistance is then evaluated to characterize the normal or safe cable capacitance and the circuit resistances. Auto-negotiation is performed during high voltage off time for line-line fault protection (shock protection) before next high voltage pulse by looking at the cable capacitance voltage RC-time droop slope to an unsafe (fault) level. The circuit includes source control circuit **150**, load control circuit **152** and auto-negotiate logic **154**. The source control circuit **150** performs fault sensing with the auto-negotiate logic **154**, PSE modulator switch **Q1**, and crowbar cable discharge switch **Q2**. The load control circuit **152** is in communication with PD DC/DC converter isolation switch **Q3**. The auto-negotiate logic includes a process for determining capacitance of the cable. In one embodiment, a safe-level off-time/RC time voltage droop level is established based on the R5 PD detect resistance of 100 kohm, for example, with actual cable capacitance at initial startup with first high voltage pulse. Auto-negotiation is then performed for subsequent off-time RC time droop level. In one example, if the droop level is <10 times the safe level from a resistance example of <10 kohm then it is a fault-level and there is no next high voltage pulse, and then trigger **Q2** crowbar/discharge of cable capacitance voltage is set to a safe level. In this example, the source includes resistors **R1**, **R2**, **R3**, **R4** (e.g., **R1** and **R4** at 560 kohm, and **R2** and **R3** at 10 kohm). The load circuit includes inductor **Lf**, capacitor **Cf**, and PD connection resistor detect **R5** (e.g., 100 kohm).

(82) It is to be understood that the circuits shown in FIGS. **12**, **13**, **14**, and **15** are only examples and that other arrangements or combinations of components (e.g., resistors, capacitors, diodes,

inductors, or switches) may be used without departing from the scope of the embodiments. Also, additional circuits or components may be included as needed. For example, in the circuits described above, other than the circuit shown in FIG. 6, the PSU modulator switch Q1 is synced on/off with the Q3 PD isolation switch on/off through data communication or with PD sensing input voltage/current to switch off and isolate the cable for auto-negotiation. However, when high voltage power is off and low voltage power is on at startup, Q3 is off, so an additional circuit may be included to get power before Q3 to power up with a low voltage circuit.

(83) Although the method and apparatus have been described in accordance with the embodiments shown, one of ordinary skill in the art will readily recognize that there could be variations made to the embodiments without departing from the scope of the invention. Accordingly, it is intended that all matter contained in the above description and shown in the accompanying drawings shall be interpreted as illustrative and not in a limiting sense.

Claims

1. A method comprising: at a location remote from a central hub, receiving power and data from a central hub via a single cable, the single cable comprising an optical fiber component for the data and an electrically conductive component for the power, wherein the power received via the electrically conductive component comprises a series of high voltage power pulses separated by fault sensing periods; performing an operational sensing procedure during the fault sensing periods between the high voltage power pulses; transmitting on the single cable a data signal to the central hub, the data signal indicating an operating status based upon the operational sensing procedure performed between the high voltage power pulses; and using the power received via the electrically conductive component of the single cable to supply power to an optical transceiver module.
2. The method of claim 1, further comprising supplying signals encoding the data transmitted via the optical fiber component of the single cable to the optical transceiver module.
3. The method of claim 1, wherein a voltage applied to at least one part of the electrically conductive component of the single cable during a pulse of the series of high voltage power pulses is greater than 250 volts.
4. The method of claim 1, wherein the power received via the electrically conductive component of the single cable during the series of high voltage power pulses is greater than 100 watts.
5. The method of claim 4, wherein the power received via the electrically conductive component of the single cable during the series of high voltage power pulses is greater than 500 watts.
6. The method of claim 4, wherein the power received via the electrically conductive component of the single cable during the series of high voltage power pulses is greater than 1000 watts.
7. The method of claim 1, wherein there is a low voltage applied to the electrically conductive component during the fault sensing periods between the high voltage power pulses.
8. The method of claim 1, wherein the single cable has a length that is greater than 100 meters.
9. The method of claim 1, wherein the optical fiber component of the single cable comprises a plurality of optical fibers and wherein the electrically conductive component of the single cable comprises a plurality of electrical wires.
10. The method of claim 1, wherein each high voltage power pulse in the series of high voltage power pulses has a duration proportional to a voltage level during pulse power periods to limit shock current of a line to ground fault to less than 10 mA.
11. The method of claim 1, wherein each high voltage power pulse in the series of high voltage power pulses has a duration proportional to a voltage level during pulse power periods to limit a line-to-line fault to about 0.5A for 1 millisecond.
12. The method of claim 1, wherein the operational sensing procedure comprises identifying a loss of data transmitted to the location remote from the central hub.
13. A system comprising: at a location remote from a central hub, a power receiver operable to

receive power comprising a series of high voltage power pulses separated by fault sensing periods sent over an electrically conductive medium; an optical transceiver module operable to send and receive data over an optical fiber transmission medium; and a single cable comprising an electrically conductive component and an optical fiber component, wherein the electrically conductive component is connected to the power receiver and the optical fiber component is connected to the optical transceiver module; wherein the system is operable to receive power and data from the central hub over the single cable; wherein the power receiver is operational to perform an operational sensing procedure during the fault sensing periods between the high voltage power pulses; wherein a low voltage is applied to the electrically conductive component during the fault sensing periods between the high voltage power pulses, and wherein the power receiver is operable to: transmit on the single cable a data signal to the central hub, the data signal indicating an operating status based upon the operational sensing procedure performed between the high voltage power pulses, and use the power received via the electrically conductive component of the single cable to supply power to the optical transceiver module.

14. The system of claim 13, wherein a voltage applied to at least one part of the electrically conductive component of the single cable during a pulse of the series of high voltage power pulses is greater than 250 volts.

15. The system of claim 13, wherein the power received via the electrically conductive component of the single cable during the series of high voltage power pulses is greater than 100 watts.

16. The system of claim 13, wherein the power received via the electrically conductive component of the single cable during the series of high voltage power pulses is greater than 500 watts.

17. The system of claim 13, wherein the power received via the electrically conductive component of the single cable during the series of high voltage power pulses is greater than 1000 watts.

18. The system of claim 13, wherein the single cable has a length greater than 100 meters.

19. The system of claim 13, wherein the optical fiber component of the single cable comprises a plurality of optical fibers and wherein the electrically conductive component of the single cable comprises a plurality of electrical wires.

20. The system of claim 13, wherein the operational sensing procedure comprises identifying a loss of data transmitted to the power receiver.

21. A system comprising: at a location remote from a central hub, a power receiver operable to receive power comprising a series of high voltage power pulses separated by fault sensing periods sent over an electrically conductive medium, wherein each high voltage power pulse in the series of high voltage power pulses has a duration proportional to a voltage level during pulse power periods to limit shock current of a line to ground fault to less than 10 mA; an optical transceiver module operable to send and receive data over an optical fiber transmission medium; and a single cable comprising an electrically conductive component and an optical fiber component, wherein the electrically conductive component is connected to the power receiver and the optical fiber component is connected to the optical transceiver module; wherein the system is operable to receive power and data from the central hub over the single cable; wherein the power receiver is operational to perform an operational sensing procedure during the fault sensing periods between the high voltage power pulses; wherein the power receiver is operable to: transmit on the single cable a data signal to the central hub, the data signal indicating an operating status based upon the operational sensing procedure performed between the high voltage power pulses, and use the power received via the electrically conductive component of the single cable to supply power to the optical transceiver module.

22. A system comprising: at a location remote from a central hub, a power receiver operable to receive power comprising a series of high voltage power pulses separated by fault sensing periods sent over an electrically conductive medium, wherein each high voltage power pulse in the series of high voltage power pulses has a duration proportional to a voltage level during pulse power periods to limit a line-to-line fault to about 0.5A for 1 millisecond; an optical transceiver module operable

to send and receive data over an optical fiber transmission medium; and a single cable comprising an electrically conductive component and an optical fiber component, wherein the electrically conductive component is connected to the power receiver and the optical fiber component is connected to the optical transceiver module; wherein the system is operable to receive power and data from the central hub over the single cable; wherein the power receiver is operational to perform an operational sensing procedure during the fault sensing periods between the high voltage power pulses; wherein the power receiver is operable to: transmit on the single cable a data signal to the central hub, the data signal indicating an operating status based upon the operational sensing procedure performed between the high voltage power pulses, and use the power received via the electrically conductive component of the single cable to supply power to the optical transceiver module.

23. An apparatus comprising: a processor and a memory; a connector for a combined cable for data and power, the combined cable comprising an electrically conductive component and an optical fiber component; and a power receiver; wherein the memory contains instructions which, when executed by the processor, cause the apparatus to: receive a series of high voltage power pulses separated by fault sensing periods sent over the electrically conductive component of the combined cable; perform an operational sensing procedure during the fault sensing periods between the high voltage power pulses; transmit on the combined cable a data signal to a central hub, the data signal indicating an operating status based upon the operational sensing procedure performed between the high voltage power pulses; and supply power to an optical transceiver module operable to send and receive data over the optical fiber component of the combined cable.

24. The apparatus of claim 23, wherein a voltage applied to at least one part of the electrically conductive component of the combined cable during a pulse of the series of high voltage power pulses is greater than 250 volts.

25. The apparatus of claim 23, wherein the power received by the apparatus during the series of high voltage power pulses is greater than 100 watts.

26. The apparatus of claim 23, wherein the power received by the apparatus during the series of high voltage power pulses is greater than 500 watts.

27. The apparatus of claim 23, wherein the optical fiber component of the combined cable comprises a plurality of optical fibers and wherein the electrically conductive component of the combined cable comprises a plurality of electrical wires.

28. The apparatus of claim 23, wherein the operational sensing procedure comprises identifying a loss of data transmitted along the combined cable.
