

US Patent & Trademark Office

Patent Public Search | Text View

United States Patent	12390872
Kind Code	B2
Date of Patent	August 19, 2025
Inventor(s)	Choi; Jae Joon et al.

Laser bonding apparatus for three-dimensional molded sculptures

Abstract

Disclosed are a laser bonding apparatus and a laser bonding method capable of bonding an electronic component to a three-dimensional structure having a regular or irregular shape in a curved portion such as an automobile tail lamp or a headlamp. The laser bonding apparatus and method for a three-dimensional structure may prevent misalignment and poor bonding of the electronic component with respect to the three-dimensional structure.

Inventors:	Choi; Jae Joon (Gwangju-si, KR), Kim; Byung Rock (Incheon, KR)
Applicant:	LASERSSEL CO., LTD. (Asan-si, KR)
Family ID:	1000008768148
Assignee:	LASERSSEL CO., LTD. (Asan-si, KR)
Appl. No.:	18/377450
Filed:	October 06, 2023

Prior Publication Data

Document Identifier	Publication Date
US 20240033840 A1	Feb. 01, 2024

Related U.S. Application Data

division parent-doc US 16921339 20200706 US 11813688 child-doc US 18377450
division parent-doc US 15577859 US 10748773 20200818 WO PCT/KR2017/006584 20170622
child-doc US 16921339

Publication Classification

Int. Cl.: **B23K1/005** (20060101); **B23K3/08** (20060101); **B23K26/08** (20140101); **B23K35/02** (20060101); **H01L21/268** (20060101); **H01L21/52** (20060101); **H01L21/677** (20060101); **H01L23/00** (20060101); **H05K13/04** (20060101); H01L21/60 (20060101)

U.S. Cl.:

CPC **B23K1/0056** (20130101); **B23K3/08** (20130101); **B23K3/087** (20130101); **B23K26/0823** (20130101); **B23K35/025** (20130101); **H01L21/268** (20130101); **H01L21/52** (20130101); **H01L21/67721** (20130101); **H01L21/6773** (20130101); **H01L24/04** (20130101); **H01L24/741** (20130101); **H01L24/75** (20130101); **H01L24/81** (20130101); **H05K13/0465** (20130101); **H05K13/0469** (20130101); H01L2021/60112 (20130101); H01L2021/60292 (20130101); H01L2224/75261 (20130101); H01L2224/75651 (20130101)

Field of Classification Search

CPC: B23K (1/0056); B23K (3/08); B23K (3/087); B23K (26/0823); B23K (35/025); B23K (1/0016); B23K (1/20); B23K (26/082); B23K (37/047); H01L (21/268); H01L (21/52); H01L (21/67721); H01L (21/6773); H01L (24/04); H01L (24/741); H01L (24/75); H01L (24/81); H01L (2021/60112); H01L (2021/60292); H01L (2224/75261); H01L (2224/75651); H01L (2224/75263); H01L (2224/7598); H01L (2224/75983); H01L (21/67115); H01L (21/67333); H01L (21/677); H01L (21/681); H01L (24/83); H01L (2224/75611); H01L (2224/75753); H01L (2224/75804); H01L (2224/75824); H01L (2224/83224); H01L (2224/83815); H01L (2224/83862); H01L (2224/97); H01L (2924/15156); H01L (2924/15159); H01L (2924/3512); H01L (24/82); H05K (13/0465); H05K (13/0469); H05K (13/046); H10H (20/036); F21S (41/151); F21S (41/192); F21S (43/14); F21S (43/15); F21S (43/195)

References Cited

U.S. PATENT DOCUMENTS

Patent No.	Issued Date	Patentee Name	U.S. Cl.	CPC
5188280	12/1992	Nakao	228/123.1	H01L 24/81
7774929	12/2009	Jacobs	N/A	N/A
11213913	12/2021	Choi et al.	N/A	N/A
11257783	12/2021	Kim	N/A	H01L 24/83
2011/0038150	12/2010	Woodgate et al.	N/A	N/A
2011/0309057	12/2010	Lin	N/A	N/A
2016/0004938	12/2015	Sasaki	N/A	N/A
2018/0233496	12/2017	Yoo et al.	N/A	N/A
2019/0067235	12/2018	Choi et al.	N/A	N/A

FOREIGN PATENT DOCUMENTS

Patent No.	Application Date	Country	CPC
3303832	12/2001	JP	N/A
4409136	12/2009	JP	N/A
2011-216503	12/2010	JP	N/A
2012-227293	12/2011	JP	N/A
2013-197273	12/2012	JP	N/A
2015-527935	12/2014	JP	N/A

10-2006-0085523	12/2005	KR	N/A
10-0638824	12/2005	KR	N/A
10-0913579	12/2008	KR	N/A
10-2011-0108128	12/2010	KR	N/A
10-2012-0106051	12/2011	KR	N/A
10-1280605	12/2012	KR	N/A
10-2014-0012812	12/2013	KR	N/A

OTHER PUBLICATIONS

International Search Report dated Sep. 4, 2017, issued in corresponding International Application No. PCT/KR2017/006584. cited by applicant

Japanese Office Action mailed on Dec. 11, 2018, in connection with the Japanese Patent Application No. 2017-562751. cited by applicant

Primary Examiner: Rodela; Eduardo A

Attorney, Agent or Firm: Hauptman Ham, LLP

Background/Summary

CROSS REFERENCE TO RELATED APPLICATION (1) This application is a Divisional Application of U.S. application Ser. No. 16/921,339 filed on Jul. 6, 2020, which is a Divisional Application of U.S. application Ser. No. 15/577,859 filed Nov. 29, 2017 which is a national stage filing under U.S.C § 371 of PCT application number PCT/KR2017/006584 filed on Jun. 22, 2017 which is based upon and claims the benefit of priority to Korean Patent Application No. 10-2016-0136477 filed on Oct. 20, 2016 in the Korean Intellectual Property Office. The disclosures of the above-listed applications are hereby incorporated by reference herein in their entireties.

TECHNICAL FIELD

(1) The present invention relates to a laser bonding technique, and more particularly, to a laser bonding apparatus and a bonding method capable of bonding a semiconductor wafer to a three-dimensional structure having a regular or irregular shape in a curved portion such as an automobile tail lamp or a headlamp.

BACKGROUND

(2) A laser bonding is preferred to the conventional wire bonding since the electronic devices become smaller and more sophisticated and the semiconductor packaging technology for protecting semiconductor chips from various external environments such as dust, moisture or electrical/mechanical loads has encountered limitations in making the devices lighter, thinner and smaller by the conventional wire bonding method. The laser bonding is a method in which a semiconductor chip is attached to a circuit pattern on a circuit board or a circuit tape and is bonded using a laser.

(3) Japanese Patent Registration No. 3303832 discloses a laser bonding technique for collectively connecting each electrode of a semiconductor chip to a substrate. According to Japanese Patent No. 3303832, an adsorption head for adsorbing a semiconductor chip is made of glass through which a laser beam is transmitted, and a Peltier element is coupled to the stage. The semiconductor chip is rapidly heated by directly heating the entire semiconductor chip by the laser beam. The substrate is rapidly heated and cooled by the Peltier element coupled to the stage.

(4) U.S. Patent Publication No. 2016/004938 relates to semiconductor chip packaging, and discloses a bonding technique using a laser for connecting a semiconductor chip die to a circuit

board. According to U.S. Patent Publication No. 2016/004938, a bump reflow step is disclosed in which a laser beam is directed toward a semiconductor die to volatilize flux and electrically connect a bump to a circuit pattern.

(5) In Korean Patent No. 10-0913579, a device for bonding a driving circuit board such as FPC (Flexible Printed Circuit), TCP (Tape Carrier Package), CBF (Common Block Flexible Printed Circuit), Driver IC (Driver Integrated Circuit) is disclosed. According to Korean Patent No. 10-0913579, a board to be bonded with a driving circuit board is transferred to and from a bonding operation position to be bonded with the driving circuit board, thereby reducing a tact time and speeding up the operation.

(6) In general, a reflow apparatus is used for attaching a device including an electronic component such as a semiconductor chip or integrated circuit (IC), a transistor (TR), a resistance element (R), and a capacitor (C) to a printed circuit board. Currently, the reflow apparatus may be classified into mass reflow type and laser reflow type.

(7) A mass reflow apparatus mounts a plurality of substrates with solder material such as solder balls, solder pads, or solder paste on the conveyor belt and drives the conveyor belt. The substrate is passed along the conveyor belt through a heating zone equipped with an infrared or ceramic heater. The infrared heaters are provided on the upper and lower sides of the conveyor belt to apply heat to the solder material on the substrate to attach the semiconductor elements thereto.

(8) According to the mass reflow apparatus, the electronic component or device is subject to thermal stress for about 210 seconds at a high temperature of about 50° C. or up to 230 to 290° C. Accordingly, there is a problem that the electronic component or device may be damaged by heat, thereby deteriorating the characteristics or lifetime of the electronic component or device. In addition, there is a problem that it takes a long time of about 3 to 10 minutes for the infrared heater to heat the solder material to bond the electronic component or device to the substrate, which is not economical. In addition, the mass reflow process may cause defects by applying heat to all components on the substrate including the ones that are susceptible to heat, and cause thermal deformation on the overall substrate since heat is applied to the entire substrate.

(9) Meanwhile, automotive headlights have recently been replaced by LEDs. The structures of the substrate for LED headlight vary from two-dimensional to three-dimensional shapes. In the case of an irregular substrate such as a step-shaped or a bowl-shaped substrate on which the LED is mounted, when the LED is bonded to the irregular substrate through the mass reflow process the heat energy is unevenly distributed on the substrate to cause bonding defects, and thermal energy is applied to the substrate as a whole thereby increasing the possibility that thermal deformation may occur throughout the entire substrate.

(10) In addition to automobile headlights, it is difficult to avoid disadvantages of the mass reflow process when the shape of the substrate for bonding semiconductor chips is three-dimensional or irregular.

(11) Therefore, when the substrate is three-dimensional or irregular a laser reflow technique can be a very useful solution. The laser reflow technique is capable of irradiating a homogenized laser beam for each bonding site and easily adjusting each irradiation region of the laser beam.

(12) Nevertheless, the laser reflow technique so far has only been applied to substrates having a generally planar shape, such as PCBs and glass substrates used in devices such as mobile phones and TVs. If the substrate is not provided in a planar form, or if the locations where the semiconductor element is attached are totally irregular, the conventional laser bonding apparatus cannot operate on such substrate.

(13) Accordingly, there is a need for a new laser bonding apparatus and method that can effectively bond electronic components or elements to any shape of three-dimensional structures including automotive tail lamps or headlamps as shown in FIG. 1.

SUMMARY

Technical Problem

(14) It is an object of the present invention to provide a laser bonding apparatus and method for a three-dimensional structure capable of bonding electronic elements to any type of three-dimensional structure. The present invention may apply not only to a substrate having a planar shape such as a flat PCB substrate and a glass substrate but also to a three-dimensional substrate including a curved portion of a regular or irregular shape.

(15) Another object of the present invention is to provide a laser bonding apparatus and method for a three-dimensional structure that can prevent misalignment of a three-dimensional structure with respect to an electronic component and a bonding failure caused thereby.

(16) Other objects of the present invention will become readily apparent from the following description of the embodiments.

Technical Solution

(17) According to some embodiments, a laser bonding apparatus for three-dimensional structures comprises: a three-dimensional structure providing unit for providing a plurality of three-dimensional structures to which adhesives are applied and electronic components are attached, and a laser bonding unit for bonding the electronic components to the three-dimensional structures by irradiating a laser beam to the electronic components attached to the three-dimensional structures.

(18) According to some embodiments, a laser bonding apparatus for three-dimensional structures comprises: an electronic component providing unit for mounting and transporting a plurality of electronic components, a three-dimensional structure providing unit for supporting and conveying a plurality of three-dimensional structures, an adhesive material applying unit for applying adhesive material to one of the three-dimensional structures, an electronic component attaching unit for attaching an electronic component to the three-dimensional structure on which the adhesive material is applied, and a laser bonding unit for bonding the electronic component to the three-dimensional structure by irradiating a laser beam to the electronic component attached to the three-dimensional structure.

(19) In the above embodiments, the three-dimensional structure have a curved portion with regular or irregular shape. Specifically the three-dimensional structure is a structure for an automobile tail lamp or an automobile headlamp.

(20) According to some embodiments, a laser bonding method for a three-dimensional structure comprises the steps of: mounting a plurality of three-dimensional structures to a working table; conveying the working table on which the three-dimensional structures are mounted by a working table conveying unit; applying adhesive material to one of the three-dimensional structures; picking up and attaching an electronic component to the three-dimensional structure on which the adhesive material is applied; and bonding the electronic component to the three-dimensional structure by irradiating a laser beam to the electronic component attached to the three-dimensional structure. The adhesive material is solder paste or NCP and the three-dimensional structure is a structure for an automobile tail lamp or an automobile headlamp.

Effects of the Invention

(21) The laser bonding apparatus for a three-dimensional structure according to the present invention provides the following effects.

(22) First, it is possible to laser bond an electronic component to a three-dimensional structure including a curved portion of a regular or irregular shape.

(23) Second, it is possible to prevent misalignment of a three-dimensional structure with respect to an electronic component and bonding failure caused thereby, as well as to prevent defective application of an adhesive material and poor adhesion of the electronic component to the three-dimensional structure.

(24) It should be understood that the effects of the present invention are not limited to the effects described above, but include all effects that can be induced from the details of specification or the configuration of the invention described in the claims.

Description

BRIEF DESCRIPTION OF THE DRAWINGS

- (1) FIG. 1 is an exemplary view for explaining a three-dimensional structure.
- (2) FIG. 2 is an exemplary view for explaining a laser bonding apparatus for a three-dimensional structure according to the present invention.
- (3) FIG. 3 is an exemplary view for explaining the operation of the laser bonding apparatus for a three-dimensional structure according to the present invention.
- (4) FIG. 4 is an exemplary view illustrating a process of bonding an electronic component to a three-dimensional structure using a laser bonding apparatus for a three-dimensional structure according to the present invention.
- (5) FIG. 5 is an exemplary view for explaining a three-dimensional structure providing unit used for providing a three-dimensional structure having an irregular shape.
- (6) FIG. 6 is a flowchart illustrating a laser bonding method for a three-dimensional structure according to the present invention.

DESCRIPTION OF EMBODIMENTS

- (7) Hereinafter, the present invention will be described with reference to the accompanying drawings. The present invention may, however, be embodied in many different forms and should not be construed as limited to the embodiments set forth herein.
- (8) Throughout the specification, when a member or an element is referred to as being “connected” (connected, combined or coupled) with another member, it may be referred to as not only “directly connected” but also “indirectly connected”. When a member “comprises” a certain element, it means that it can include other element unless specifically stated otherwise.
- (9) The terminology used herein is for the purpose of describing particular embodiments only and is not intended to be a limitation to the present invention. A singular form such as “a,” “an,” and “the” may include plural referents unless the context clearly dictates otherwise. In this specification, the terms “comprise”, “including” or “having” and the like are intended to specify that there are stated features, numbers, steps, operations, elements, parts or combinations thereof. The use of the terms “comprise”, “including” or “having” and the like do not preclude the presence or addition of one or more other features, numbers, steps, operations, components, parts, or combinations thereof.
- (10) The laser bonding apparatus for a three-dimensional structure according to the present invention is implemented to laser-bond an electronic component to a three-dimensional structure (e.g., an automotive taillight or a headlight) as shown in FIG. 1. The three-dimensional structure can be implemented as a mold manufactured by injection molding. In the past, bonding of three-dimensional structures was done by soldering, but the inventor(s) of the present application developed a laser bonding apparatus for a three-dimensional structure in order to reduce the manufacturing time as the paradigm of a manufacturing industry is being gradually changed to a new concept of a smart factory and customized mass production.
- (11) The laser bonding apparatus **200** for a three-dimensional structure according to an embodiment of the present invention comprises a three-dimensional structure providing unit for providing a plurality of three-dimensional structures applied with an adhesive material to which electronic components are to be attached, and a laser bonding unit for bonding the electronic components attached to the plurality of three-dimensional structures by irradiating a laser beam. According to this embodiment, the process of applying the adhesive material on the surface of the three-dimensional structure and attaching the electronic component device to the adhesive material can be performed by a separate apparatus. In this case, the three-dimensional structure providing unit of the laser bonding apparatus **200** for a plurality of three-dimensional structures according to the present invention will only perform the operation of transporting the plurality of three-dimensional

structures to their bonding positions.

(12) Referring to FIG. 2, the laser bonding apparatus **200** for a three-dimensional structure according to the present invention includes not only an electronic component providing unit **210** but also a three-dimensional structure providing unit **250**, an adhesive material applying unit **220**, an electronic component attaching unit **230**, and a laser bonding unit **240**.

(13) The electronic component providing unit **210** mounts and transports a plurality of electronic components. The electronic component may include at least one of a semiconductor chip, an IC, an LED element, a resistor, a capacitor, an inductor, a transformer, a relay and so forth. The electronic component providing unit **210** includes a tray **211** on which a plurality of electronic components are mounted and a tray transporting unit **212** for transporting the tray **211** in a predetermined direction.

(14) The three-dimensional structure providing unit **250** supports and conveys a plurality of three-dimensional structures in a predetermined direction. A plurality of three-dimensional structures may include a three-dimensional structure (for example, an automobile tail lamp or a headlight instrument) in which the bent portions have both a regular or irregular shape.

(15) The three-dimensional structure providing unit **250** may be implemented to include a working table **251** for supporting a plurality of three-dimensional structures and a working table conveying unit **252** for conveying the working table on which the plurality of three-dimensional structures are mounted.

(16) The adhesive material applying unit **220** applies, for example, solder paste or non-conductive adhesive (NCP) to the plurality of three-dimensional structures. Non-conductive adhesives, hereinafter referred to as “NCP”, can be implemented, for example, with N-methyl-3-amino propyltrimethoxysilane as a coupling agent and polyester acrylate as an adhesion promoter.

(17) The adhesive material applying unit **220** includes a dispenser **223** for applying solder paste or NCP to the plurality of three-dimensional structures placed on the working table **251**, a first transfer unit **222** that transfers the dispenser **223** both vertically and horizontally within a plane perpendicular to the tray transporting direction, and a first gantry **221** that supports the first transfer unit **222**.

(18) The adhesive material applying unit **220** may be implemented by further including a first monitoring unit that detects an alignment state of the dispenser with respect to the three-dimensional structure and an application state of a solder paste or NCP. The first monitoring unit may include a CCD camera and a capture board for capturing an image, and a control unit for comparing the image input from the image processing board with the reference image to determine whether the alignment and application states are within normal ranges.

(19) The electronic component attaching unit **230** attaches the electronic component to a portion of the three-dimensional structure to which solder paste or NCP is applied. The electronic component may include at least one of a semiconductor chip, an IC, an LED element, a resistor, a capacitor, an inductor, a transformer, or a relay.

(20) The electronic component attaching unit **230** includes a component attach **233** for picking up an electronic component from the tray **211** and attaching it to a portion of a plurality of three-dimensional structure to which solder paste or NCP is applied. The electronic component attaching unit **230** further includes a second transfer unit **232** that transfers the component attach **233** both vertically and horizontally within a plane perpendicular to the tray transporting direction, and a second gantry **231** that supports the second transfer unit **232**.

(21) The electronic component attaching unit **230** may further include a second monitoring unit that detects an alignment state of the electronic component with respect to the three-dimensional structure and an attachment state of the electronic component to the three-dimensional structure. The second monitoring unit may include a CCD camera and a capture board for capturing an image, and a control unit for comparing the image input from the image processing board with the reference image to determine whether the alignment and attachment states are within normal

ranges.

(22) The laser bonding unit **240** irradiates laser beam of line or square type to the electronic component attached to the three-dimensional structure to bond them each other. An exemplary laser bonding unit **240** includes a laser beam irradiating unit **243**, a third transfer unit **242** for moving the laser beam irradiating unit **243** vertically and horizontally within a plane perpendicular to the direction of tray transport, a third gantry **241** that supports the third transfer unit **242**.

(23) The laser beam irradiating unit **243** may include a laser oscillator that emits a laser beam to an electronic component attached to the three-dimensional structure, and a beam shaper and an optical system for converting a laser beam having Gaussian distribution outputted from the laser oscillator into square or rectangular surface beam having a uniform energy distribution.

(24) The beam shaper may be embodied as a light guide forming a homogenized rectangular beam. The light guide may be installed to have a distance of 0.2 to 0.5 mm from the optical fiber that conveys the laser beam from the laser oscillator. The light guide may have a length between 1.0 to 1.5 meters. If the length of the light guide is less than 1.0 m, the optical homogeneity of the laser light outputted from the light guide after undergoing diffused reflection inside the light guide can be decreased thereby degrading the uniformity in the temperature distribution in the irradiation region of the workpiece (P). On the other hand, if the length of the light guide is set to be more than 1.5, the optical homogeneity of the laser beam becomes very good. However, the total length of the optical homogenization module including the beam shaper and optical system becomes too much long, which increases the manufacturing cost and inconvenience in storing and transporting the optical homogenization module.

(25) No optical lens is required between the light guide and the optical fiber to make the laser beam uniform. Since the distance between the light guide and the optical fiber is between 0.2 and 0.5 mm and the numerical aperture (NA) of the optical fiber is within 0.2 to 0.3 range, all of the laser beam emitted from the optical fiber can be incident into the light guide.

(26) The light guide is formed as a rectangular parallelepiped having a rectangular cross section using a base material having a high transmittance through which the laser light can pass. A total reflection coating film is formed on the sidewall parallel to the optical axis of the laser beam. An anti-reflective coating film is formed on both the upper and lower surfaces that are perpendicular to the optical axis. Thus, the laser beam passing through the light guide can be prevented from being lost outwardly.

(27) The optical system can be realized, for example, by a condensing lens for condensing the divergent uniformized rectangular beam emitted from the light guide and a diverging lens for diverging the condensed uniformized rectangular beam while maintaining the uniformity of the beam up to a certain working distance. The combination of the radii of curvature of the condensing lens and the diverging lens allows the control of the size of the uniformized rectangular beam and the working distance.

(28) The laser bonding unit **240** may include a third monitoring unit that detects an alignment state of the laser irradiating unit **243** with respect to the three-dimensional structure and a bonding state of the electronic component to the three-dimensional structure. The third monitoring unit may include a CCD camera and a capture board for capturing an image, and a control unit for comparing the image input from the image processing board with the reference image to determine whether the alignment and bonding states are within normal ranges.

(29) The laser bonding unit **240** may be implemented to adjust the irradiation intensity and the irradiation region of the laser beam according to the shape of the three-dimensional structure as the working table **251** on which the plurality three-dimensional structures are placed is being moved. Accordingly, even when the shape of the substrate is three-dimensional or irregular, it is possible to irradiate a uniformized laser beam to each bonding site and easily adjust each irradiation region of the laser beam.

(30) FIG. 3 is an exemplary view for explaining the operation of the laser bonding apparatus for a

three-dimensional structure having a regular shape, and FIG. 4 is an exemplary view for explaining a process for bonding electronic components to the three-dimensional structure having a regular shape using the laser bonding apparatus in FIG. 3.

(31) Referring to FIG. 3, the laser bonding apparatus for a three-dimensional structure having a regular shape includes first and second working tables **251** and **261** for respectively supporting a plurality of three-dimensional structures **110**, and first and second working table conveying units **252** and **262** for conveying the first and second working tables **251** and **261**, respectively. The number of working tables and working table conveying units can vary depending on the amount of required production of the device to be bonded.

(32) The tray transporting unit **212** for transporting the tray **211** on which the plurality of electronic components are mounted can be installed separately from the first and second working table conveying units **252** and **262** as shown in FIG. 3. The tray **211** is loaded on the tray transporting unit **212** to be transported, and is discharged to the outside when used up.

(33) The first and second working tables **251** and **261** are conveyed by the first and second working table conveying units **252** and **262** to pass the first gantry **221**. The dispenser **223** for applying solder paste or NCP to the plurality of three-dimensional structures **110** and the first transfer unit **222** for transferring the dispenser **223** both vertically and horizontally within a plane perpendicular to the tray transporting direction are installed in the first gantry **221**. A vision module for detecting an alignment state of the dispenser with respect to the three-dimensional structure and an application state of a solder paste or NCP may be further installed in the first gantry **221**.

(34) When the solder paste or NCP is applied to the plurality of three-dimensional structures, the first and second working tables **251**, **261** are conveyed by the first and second working table conveying units **252**, **262**, respectively, to pass the second gantry **231**. The component attach **233** and the second transfer unit **232** are installed in the second gantry **231**. The component attach **233** is used for picking up an electronic component from the tray **211** and attaching it to a portion of the three-dimensional structure to which solder paste or NCP is applied, and the second transfer unit **232** is used for transferring the component attach **233** both vertically and horizontally within a plane perpendicular to the tray transporting direction. A vision module for detecting an alignment state of the component attach **233** with respect to the three-dimensional structure **110** and an attachment state of the electronic component to the three-dimensional structure **110** may be further installed in the second gantry **231**.

(35) When the electronic components are attached to the three-dimensional structures **110**, the first and the second working tables **251**, **261** are conveyed by the first and the second working table conveying units **252**, **262** to pass the third gantry **241**. The laser beam irradiating unit **243** and the third transfer unit **242** are installed in the third gantry **241**. A vision module for detecting an alignment state of the laser beam irradiating unit **243** with respect to the three-dimensional structure **110** and an a laser bonding state of the electronic component to the three-dimensional structure **110** may be further installed in the third gantry **241**.

(36) Referring to FIG. 4, the three-dimensional structures **110** are mounted on the working table **251** to be conveyed by the working table conveying unit. In a sequential order, a solder paste or NCP **30** is applied by the dispenser **223** to the three-dimensional structures **110**, the electronic component **40** is attached by the component attach **233** to the solder paste or the NCP **30**, and the electronic component **40** is bonded by the laser beam irradiating unit **243** to the three-dimensional structure.

(37) Heretofore, the apparatus and method for bonding electronic components to a plurality of three-dimensional structures having a regular shape using three-dimensional structure providing unit with regard to FIGS. 3 and 4.

(38) Hereinafter, a three-dimensional structure providing unit for handling three-dimensional structures having irregular shape will be explained with reference to FIG. 5.

(39) Referring to FIG. 5, the three-dimensional structure providing unit includes a seat **511** on

which a plurality of three-dimensional structures **120** having irregular shape are seated, a driving shaft **512** connected to the seat **511**, a driving belt **513** connected to the driving shaft **512**, a first motor **521** for rotating the driving belt **513**, a coupler **514** coupled to the driving shaft **512**, a support to which the coupler **514** is rotatably coupled, and a second motor **522** connected to the coupler **514** to rotate the coupler **514** with regard to its axis.

(40) Although not shown in FIG. 5, the laser bonding apparatus for three-dimensional structure according to the present invention may be implemented to comprise a storage unit for storing operation file for driving the first and the second motors **521**, **522** and motor driving unit for driving the first and second motors according to the operation file.

(41) As shown in FIG. 6, the laser bonding method performed in the laser bonding apparatus for a three-dimensional structure according to FIGS. 3 and 4 includes a loading step, an applying step, a pickup and attach step, a bonding step, and an unloading step.

(42) The loading step **S611** includes the step of placing a plurality of three-dimensional structures on a working table. The applying step includes the step **S612** of conveying the working table on which the plurality of three-dimensional structures are mounted by a working table conveying unit and a step **S613** of applying solder paste or NCP to the three-dimensional structures. For example, the distance, speed and position of conveying the working table may be preset and stored in the storage unit of the laser bonding apparatus. However, a monitoring unit including a vision module may be used to check whether the working table has been exactly conveyed to the preset position and to correct the misalignment, if any. After the step **S613**, a step of detecting the state of application of the solder paste or NCP by a monitoring unit to determine whether the application state is within a normal range.

(43) The picking-up and attaching step includes a step **S614** of conveying the working table and a step **S615** of picking up electronic components from the tray and attaching it to the three-dimensional structures. For example, the distance, speed and position of conveying the working table may be preset and stored in the storage unit of the laser bonding apparatus. However, a monitoring unit including a vision module may be used to check whether the working table has been exactly conveyed to the preset position and to correct the misalignment, if any. After the step **S615**, a step of detecting the state of attachment of the electronic component by a monitoring unit to determine whether the attachment state is within a normal range.

(44) The bonding step includes the step **S616** of conveying the working table and a step **S617** of laser bonding the electronic component to the three-dimensional structures. For example, the distance, speed and position of conveying the working table may be preset and stored in the storage unit of the laser bonding apparatus. However, a monitoring unit including a vision module may be used to check whether the working table has been exactly conveyed to the preset position and to correct the misalignment, if any. After the step **S617**, a step of detecting the bonding state of the electronic component by a monitoring unit to determine whether the bonding state is within a normal range.

(45) The unloading step **S618** unloads the three-dimensional structures from the working table after the bonding of the electronic components to the three-dimensional structures.

(46) It will be understood by those having ordinary skill in the art that various changes and modifications may be made without departing from the spirit and scope of the present invention as defined by the following claims.

(47) For example, each element or step in the above-explained embodiments may be implemented by a plurality of distributed or separated elements or steps.

(48) At the same time, the elements or step described to be distributed or separated in the above-explained embodiments may be implemented in a connected, coupled or combined form

NUMBERS IN THE DRAWINGS

(49) **30**: solder paste or non-conductive adhesive (NCP) **40**: electronic component **110**: three-dimensional structure **200**: laser bonding device for three-dimensional structures **210**: electronic

component providing unit **211**: tray **212**: tray transporting unit **211**: tray **212**: tray transporting unit **220**: adhesive material applying unit **221**: a first gantry **222**: a first transfer unit **223**: dispenser **230**: electronic component attaching unit **231**: a second gantry **232**: a second transfer unit **233**: component attach **240**: laser bonding unit **241**: a third gantry **242**: a third transfer unit **243**: laser beam irradiating unit **251**: a first working table **252**: a first working table conveying unit **261**: a second working table **262**: second working table conveying unit

BEST MODE

(50) Heretofore, the embodiments were explained in their best modes.

INDUSTRIAL APPLICABILITY

(51) The disclosed techniques could be used in an apparatus for laser bonding.

Claims

1. A laser bonding method for a three-dimensional structure comprising: transporting, by an electronic component providing unit, a plurality of electronic components; providing, by a three-dimensional structure providing unit, a plurality of three-dimensional structures on a working table; conveying, by a working table conveying unit, the working table on which the plurality of three-dimensional structures are mounted; applying, by an adhesive material applying unit, adhesive material to one of the three-dimensional structures; attaching, by an electronic component attaching unit, an electronic component among the transported electronic components to the one of three-dimensional structures on which the adhesive material is applied; and laser bonding, by a laser bonding unit, the attached electronic component to the one of three-dimensional structures by irradiating a laser beam to the electronic component attached to the one of three-dimensional structures, wherein the transporting of the plurality of electronic components includes: mounting the plurality of electronic components on a tray; and transporting the tray in a predetermined direction.
 2. The laser bonding method according to claim 1, wherein the applying of the adhesive material comprises: applying, by a dispenser, solder paste or NCP to the one of three-dimensional structures mounted on the working table; and transferring, by a first transfer unit, the dispenser vertically and horizontally within a plane perpendicular to a tray transporting direction.
 3. The laser bonding method according to claim 2, wherein the applying of the adhesive material further comprises: detecting, by a first monitoring unit, the alignment state of the dispenser with respect to the three-dimensional structures and application state of the solder paste or NCP to the three-dimension structures.
 4. A laser bonding method for a three-dimensional structure comprising: mounting a plurality of three-dimensional structures to a working table; conveying, by a working table conveying unit, the working table on which the three-dimensional structures are mounted; applying, by an adhesive material applying unit, adhesive material to one of the three-dimensional structures; picking up and attaching, by an electronic component attaching unit, an electronic component to the one of three-dimensional structures on which the adhesive material is applied; and bonding, by a laser bonding unit, the electronic component to the one of three-dimensional structures by irradiating a laser beam to the electronic component attached to the three-dimensional structure.
 5. The laser bonding method according to claim 4, wherein the adhesive material is solder paste or NCP.
 6. The laser bonding method according to claim 4, wherein the plurality of three-dimensional structures is a structure for an automobile tail lamp or an automobile headlamp.
-