Master Degree in Computer Science
Master Degree in Data Science and Economics

Information Retrieval



Evaluation in information retrieval

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The goal of the evaluation activity is to assess the quality of results obtained by an IR system

The notion of *quality of results* depends on the task at hand, e.g., search, classification, knowledge extraction, etc.

A general issue concerning the evaluation is that it is based on a **ground truth** (or **gold standard**), that is an **annotated corpus** where, for each document, we know if the document is **relevant** with respect to the task

Ground truth may be created by manually annotating documents and/or derived from data with a reference annotation system





Given a corpus C and a query q, the task of document search is to find the set of documents $A_{q,C}$ that match q

We call $A_{q,c}$ the answers to q

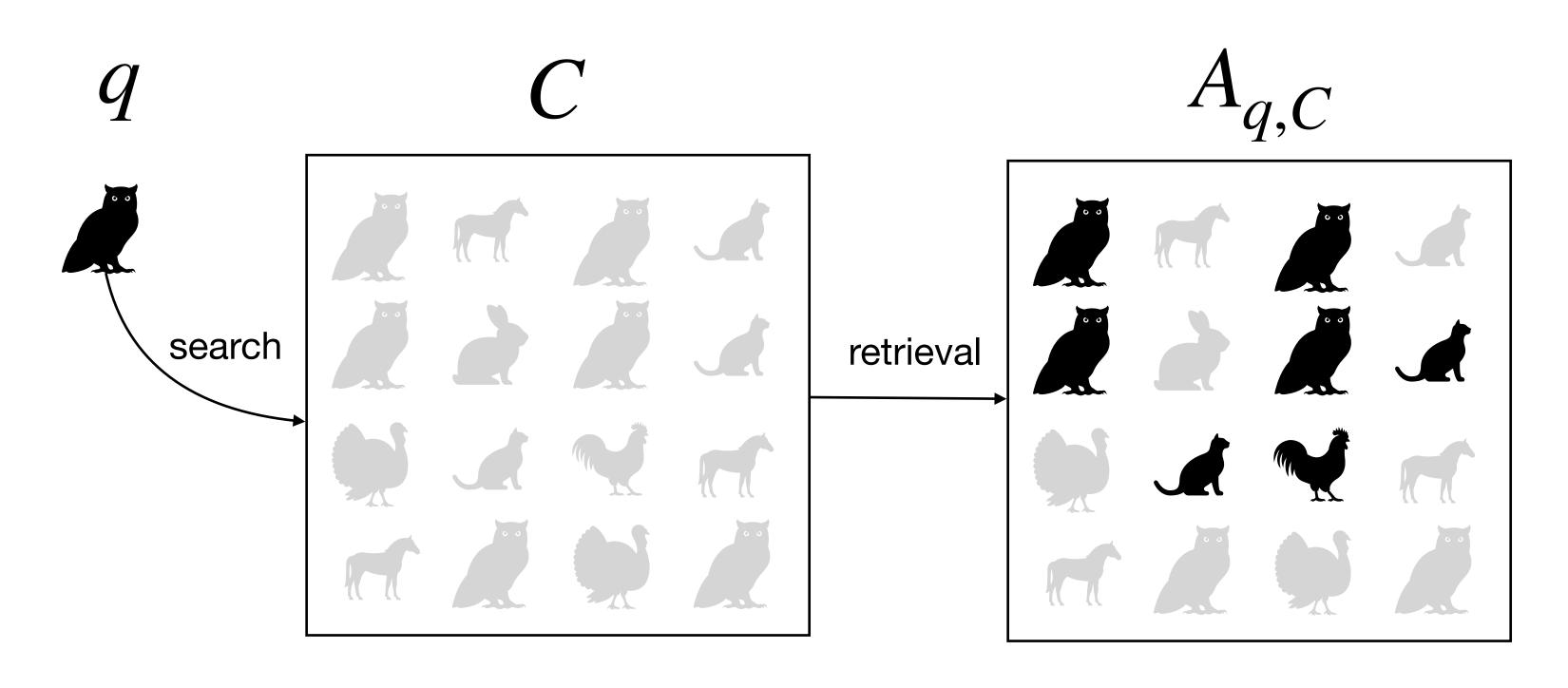
Question: when we say that the search answers $A_{q,c}$ are good?



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Definition 1: when the documents contained in $A_{q,c}$ are relevant to q

Remember: in order to know if a document is actually relevant, we need a ground truth (or a user feedback)



We retrieved 7 documents of which 4 are correct

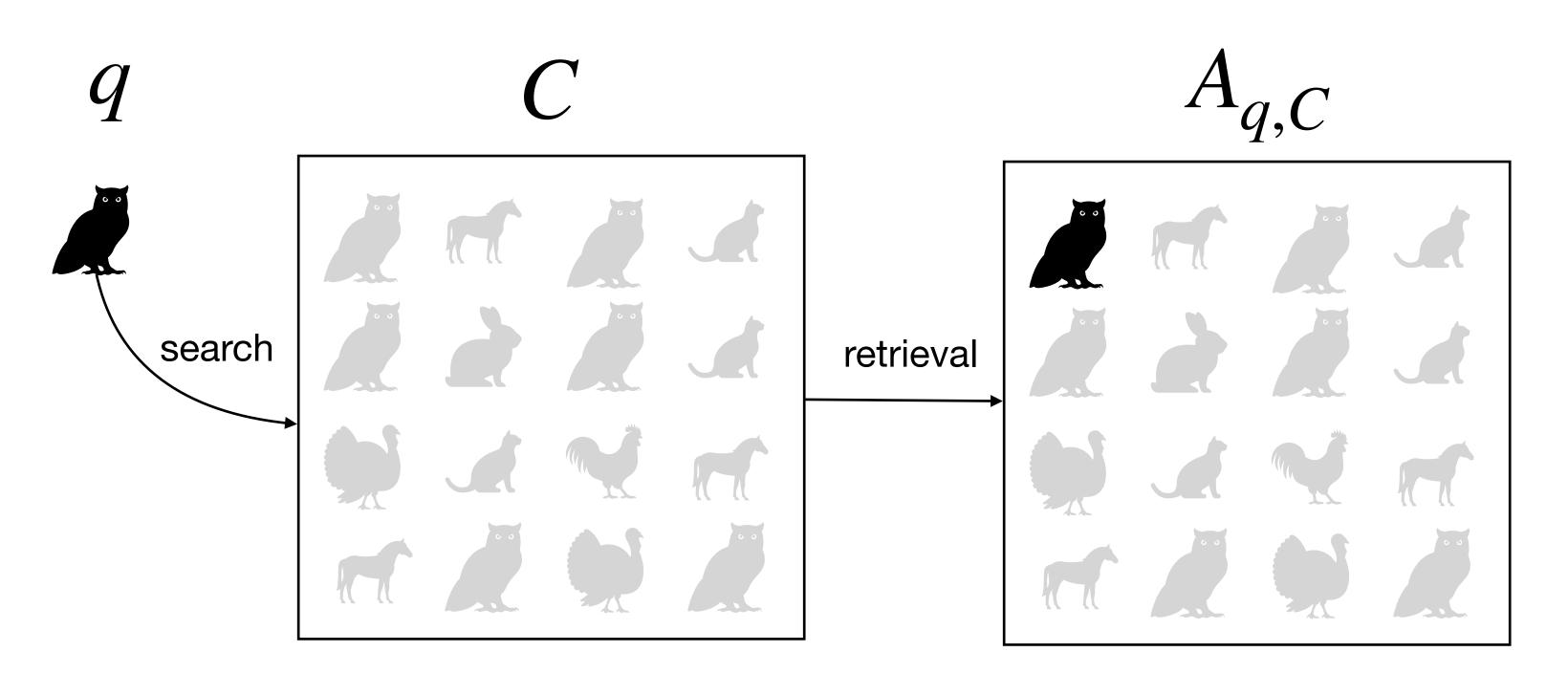
We can measure the quality of our system according to this notion of quality, called **Precision**

$$Prec = \frac{relevant\ retrieved}{retrieved}$$

$$Prec_q = \frac{4}{7} = 0.57$$



Question: why **Precision** is a **necessary** but **not sufficient** property of a good search system?



We retrieved only 1 document and it is correct

However, many relevant documents arre missing

$$Prec = \frac{relevant\ retrieved}{retrieved}$$

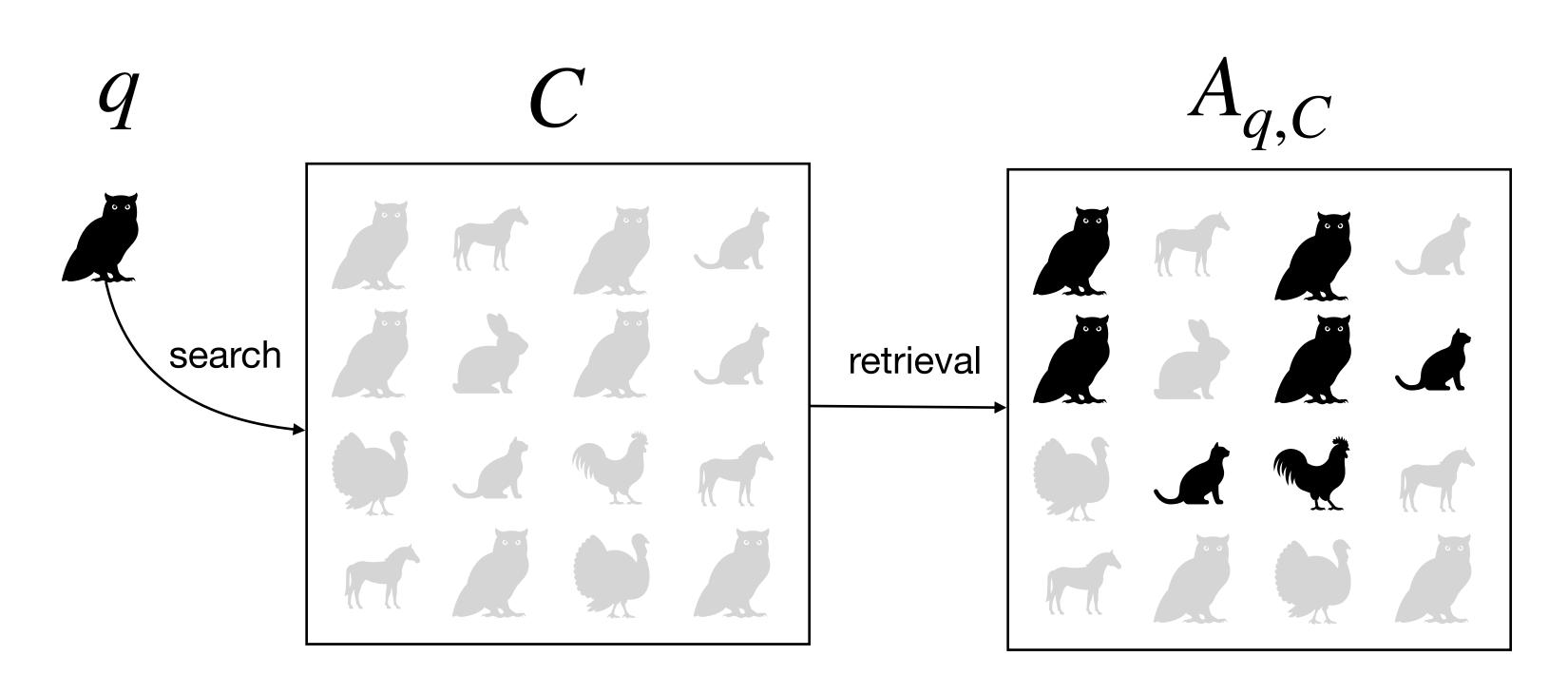
$$Prec_q = \frac{1}{1} = 1$$



Question: when we say that the search answers $A_{q,c}$ are good?

Definition 2: when all the relevant documents contained in **C** are retrieved by **q**

Remember: in order to know if a document is actually relevant, we need a ground truth (or a user feedback)



We retrieved 4 relevant documents from a corpus which contains 6 relevant documents

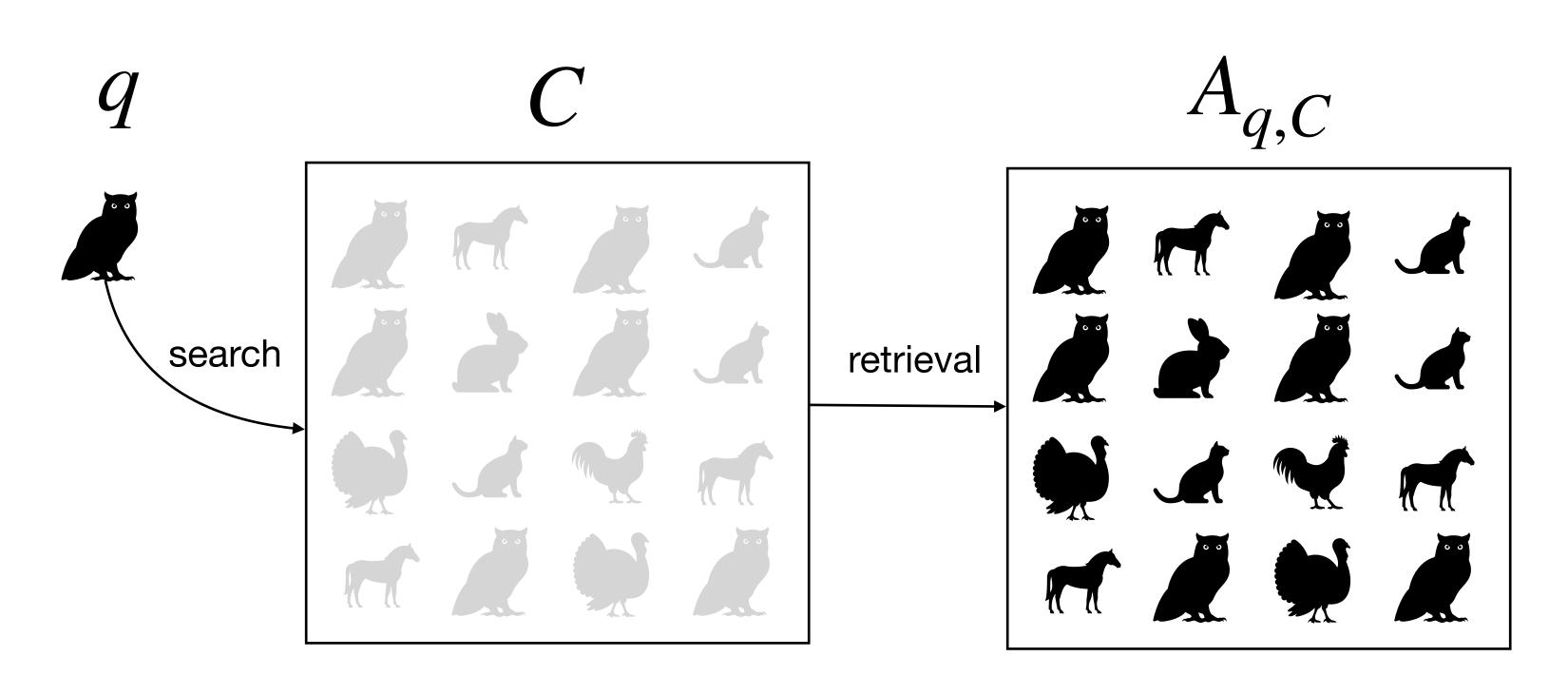
We can measure the quality of our system according to this notion of quality, called **Recall**

$$Rec = \frac{relevant \ retrieved}{relevant}$$

$$Rec_q = \frac{4}{6} = 0.66$$



Question: why **Recall** is a **necessary** but **not sufficient** property of a good search system?



We retrieved all the documents and this means to retrieve all the relevant ones by definition

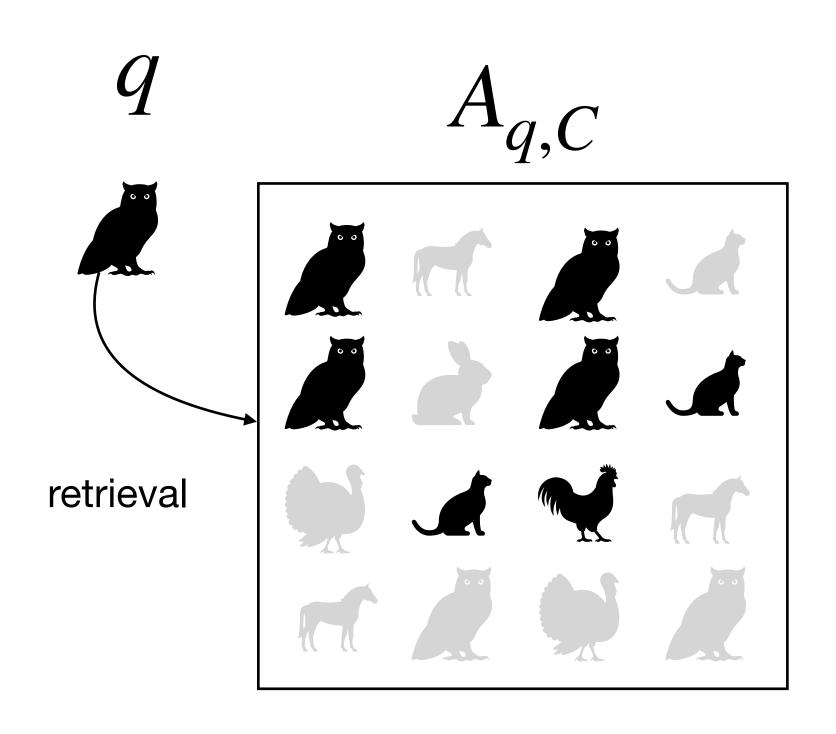
However, there are a lot of wrong results

$$Rec = \frac{relevant \ retrieved}{relevant}$$

$$Rec_q = \frac{6}{6} = 1$$



Definition 3: we aim at a system with a good tradeoff between precision and recall; this can be measured by the **f1-score**



$$F1 = \frac{2 \cdot Prec \cdot Rec}{Prec + Rec} = \frac{2 \cdot 0.57 \cdot 0.66}{0.57 + 0.66} = 0.61$$

Question: when the numbers we obtain from these measures are good? Try to perform search by tossing a coin...

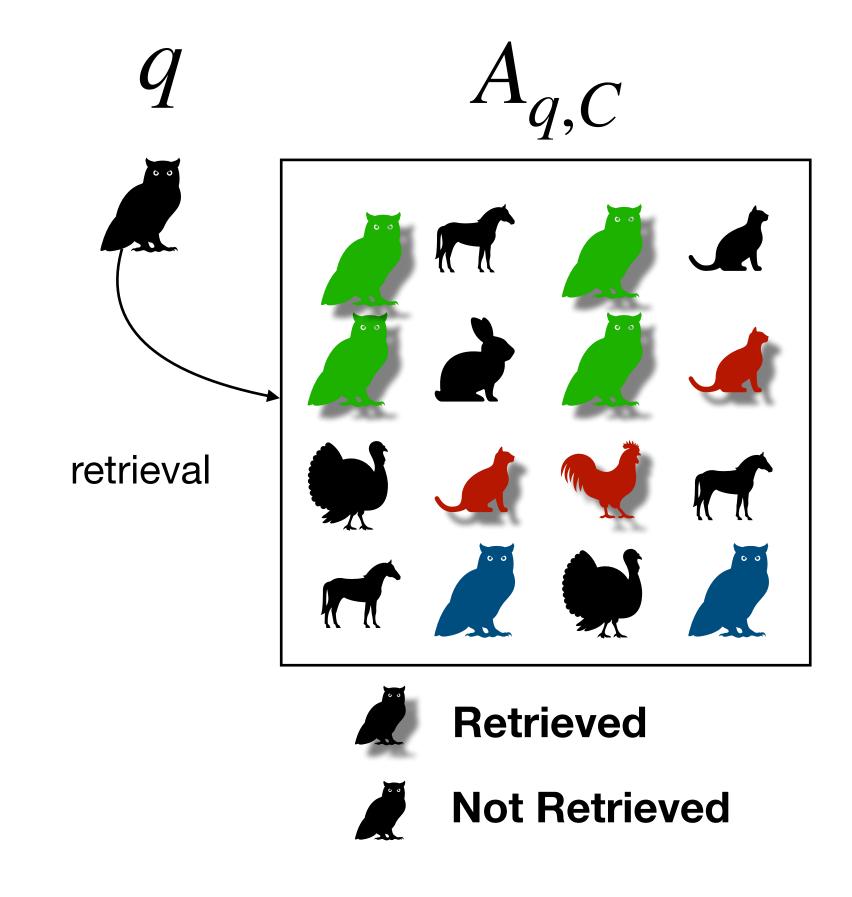


A more formal definition of Precision and Recall

Given a query q and a ground truth providing the set E_q of relevant documents for q, we denote A_q the set of query answers provided by the system under evaluation For each document d:

	$d \in E_q$	$d \not\in E_q$	
$d \in A_q$	TP True Positive	FP False Positive	Retrieved
$d \not\in A_q$	FN False Negative	TN True Negative	Not retrieved
	Relevant	Not Relevant	

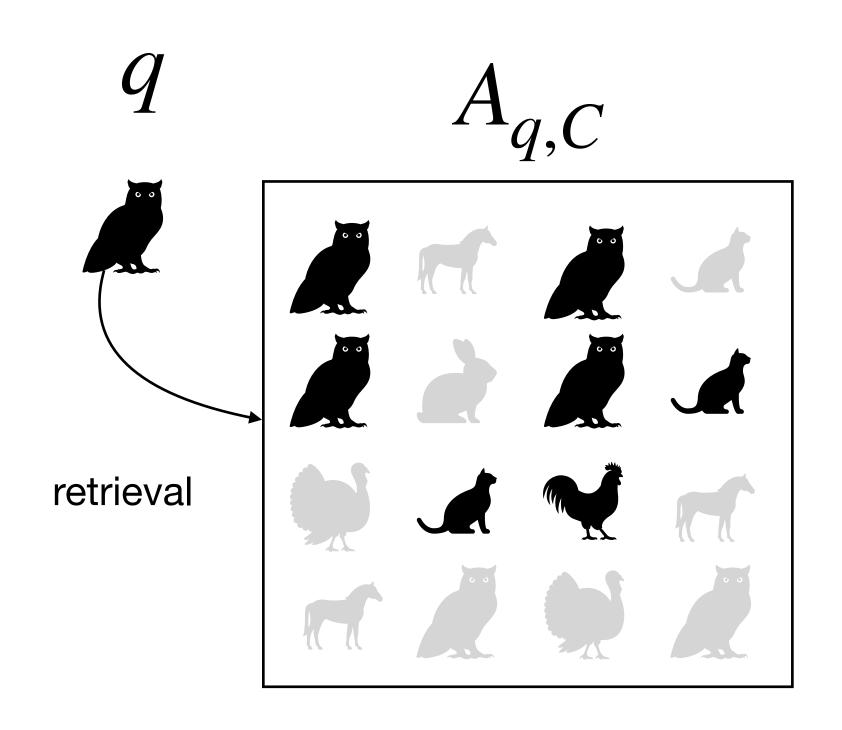
$$Prec = \frac{TP}{TP + FP}; \ Rec = \frac{TP}{TP + FN}; \ F1 = \frac{TP}{TP + \frac{1}{2}(FP + FN)}$$



Confusion Matrix



When evaluating a search system, it is important to understand in which cases we have errors: it is more the retrieval of wrong documents (FP) or instead the fact that we miss many documents (FN)



		Groun	d truth	•
Ø	\boldsymbol{q}	R = 1	R = 0	
d values	R = 1	TP=4	FP = 3	7
Predicted	R = 0	FN = 2	TN = 7	9
		6	10	16

R is the variable that represent the document relevance to the query

Search evaluation: confusion matrix and other measures



specificity	negative predictive miss rate value		fall-out	false discovery rate	false omission rate	critical success index		
$TNR = \frac{TN}{TN + FP}$	$NPV = \frac{TN}{TN + FN}$	$FNR = \frac{FN}{FN + TP}$	$FPR = \frac{FP}{FP + TN}$	$FDR = \frac{FP}{FP + TP}$	$FOR = \frac{FN}{FN + TN}$	$TS = \frac{TP}{TP + FN + FP}$		

Prevalence threshold

Accuracy Balanced accuracy Informedness

Markedness

$$PT = \frac{\sqrt{Rec(1-TNR)} + TNR - 1}{Rec + TNR - 1} \quad ACC = \frac{TP + TN}{TP + TN + FP + FN} \quad BA = \frac{Rec + TNR}{2} \quad BM = Rec + TNR - 1 \quad MK = Prec + NPV - 1$$

$$BA = \frac{Rec + TNR}{2}$$

$$BM = Rec + TNR - 1$$

$$MK = Prec + NPV - 1$$

Matthews correlation coefficient

$$MCC = \frac{TP \cdot TN - FP \cdot FN}{\sqrt{(TP + FP)(TP + FN)(TN + FP)(TN + FN)}}$$

Fowlkes-Mallows index

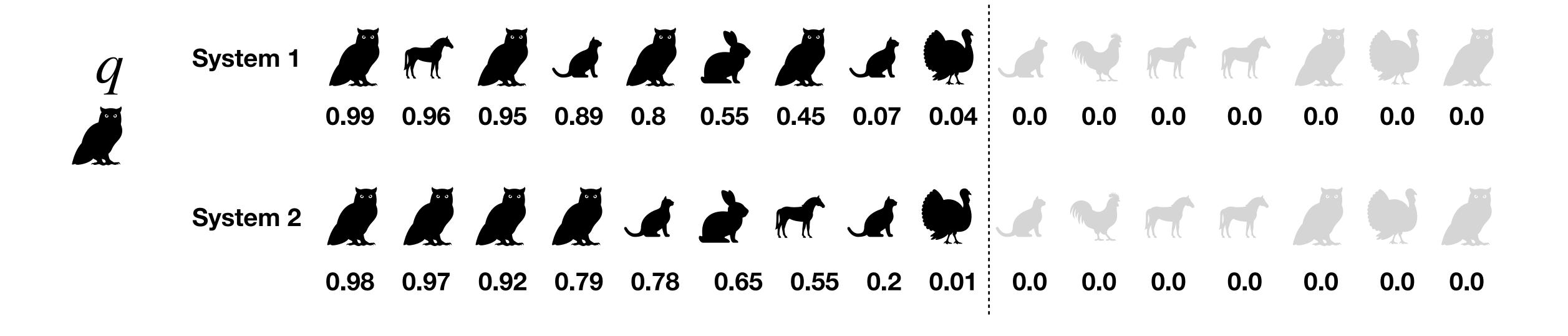
$$FM = \sqrt{\frac{2TP}{(TP + FP)(TP + FN)}}$$

Quick summary: https://en.wikipedia.org/wiki/Evaluation measures (information retrieval)

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Evaluation of ranking systems

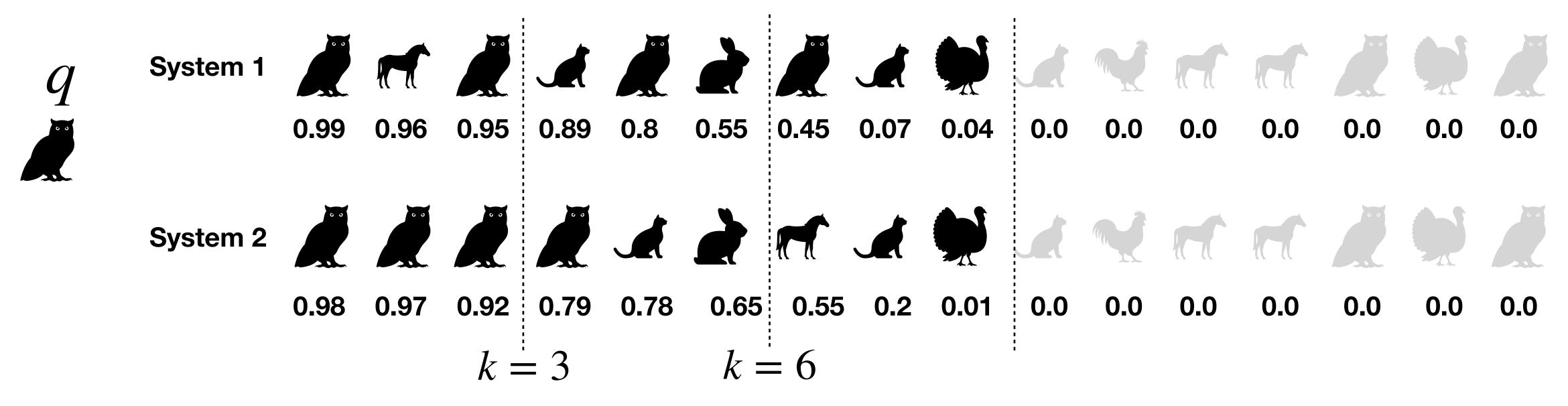
The answer of a non boolean search system is not a set of retrieved documents, rather a rank of documents with a relevance score (that is typically the cosine similarity between the query and the document). **How do we evaluate the system in this case?**



Note that the two systems achieve the same Precision and Recall. However, the second system is better.



Solution 1: we could set a threshold too select the top-k results and use them to evaluate precision and recall. But where should we put the threshold?



Precision at k

System 1:
$$Prec_{k=3} = \frac{2}{3}$$
; $Prec_{k=6} = \frac{1}{2}$ **System 2:** $Prec_{k=3} = 1$; $Prec_{k=6} = \frac{2}{3}$

System 2:
$$Prec_{k=3} = 1$$
; $Prec_{k=6} = \frac{2}{3}$

Still the order of results is not completely taken into account



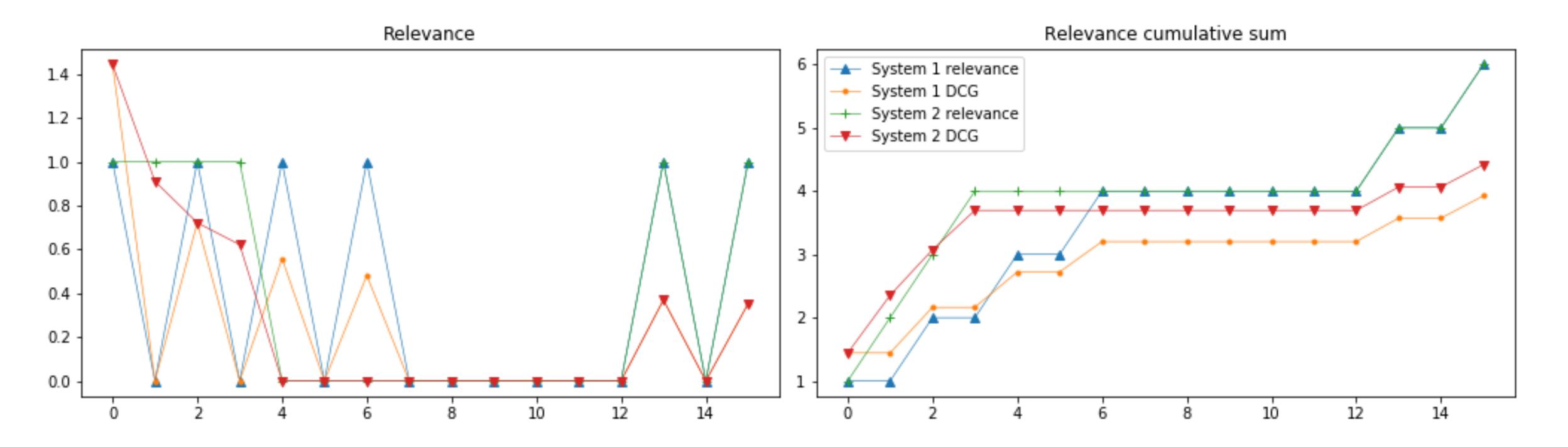
Solution 2: **Discounted cumulative gain**: we discount the relevance of each document according to its position in the ranking



Discounted cumulative gain:
$$DCG = \sum_{i=1}^{n} \frac{R_i}{\log(i+1)}$$



Solution 2: **Discounted cumulative gain**: we discount the relevance of each document according to its position in the ranking



System 1: 3.93 System 2: 4.42



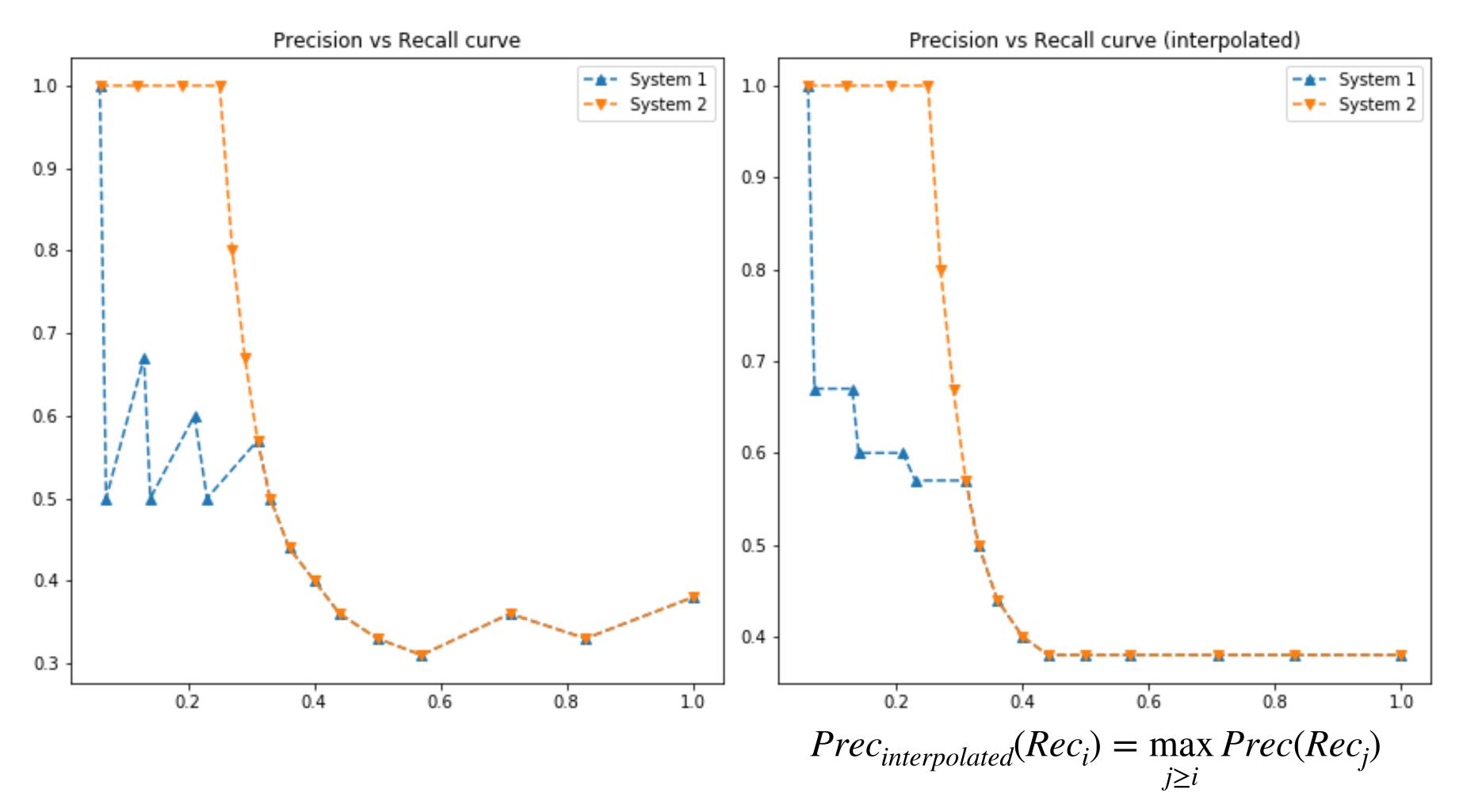
Solution 3: Precision Vs Recall. When moving along the ranking from top to bottom, the **Recall** increases by definition. We can just measure the **Precision** scored for different levels of recall.

			0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
		TP	1.00	1.00	2.00	2.00	3.00	3.00	4.00	4.00	4.00	4.0	4.00	4.00	4.00	5.00	5.00	6.00
System 1		FP	0.00	1.00	1.00	2.00	2.00	3.00	3.00	4.00	5.00	6.0	7.00	8.00	9.00	9.00	10.00	10.00
	System 1	FN	15.00	14.00	13.00	12.00	11.00	10.00	9.00	8.00	7.00	6.0	5.00	4.00	3.00	2.00	1.00	0.00
		P	1.00	0.50	0.67	0.50	0.60	0.50	0.57	0.50	0.44	0.4	0.36	0.33	0.31	0.36	0.33	0.38
		R	0.06	0.07	0.13	0.14	0.21	0.23	0.31	0.33	0.36	0.4	0.44	0.50	0.57	0.71	0.83	1.00
			_	_	_	_										_		_
			0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
		TP	1.00	2.00	2	4.00	4	5	6	7	8	9	10	11	12	13	14 5.00	15 6.00
		TP FP	0	1	2	3	4	4.00	4.00	4.00	4.00	4.0	4.00	4.00	4.00	5.00	14	15 6.00
	Svstem 2	FP	1.00	2.00 0.00	3.00 0.00	4.00 0.00	4.00 1.00	4.00 2.00	4.00 3.00	4.00 4.00	4.00 5.00	4.0 6.0	4.00 7.00	4.00 8.00	4.00 9.00	5.00 9.00	5.00	6.00
	System 2	FP	1.00 0.00	2.00 0.00	3.00 0.00	4.00 0.00	4.00 1.00	4.00 2.00 10.00	4.00 3.00 9.00	4.00 4.00 8.00	4.00 5.00 7.00	4.0 6.0 6.0	4.00 7.00 5.00	4.00 8.00	4.00 9.00 3.00	5.00 9.00 2.00	5.00 10.00	6.00 10.00
	System 2	FP FN P	1.00 0.00 15.00	2.00 0.00 14.00	3.00 0.00 13.00 1.00	4.00 0.00 12.00 1.00	4.00 1.00 11.00	4.00 2.00 10.00 0.67	4.00 3.00 9.00 0.57	4.00 4.00 8.00 0.50	4.00 5.00 7.00 0.44	4.0 6.0 6.0 0.4	4.00 7.00 5.00 0.36	4.00 8.00 4.00 0.33	4.00 9.00 3.00 0.31	5.00 9.00 2.00 0.36	5.00 10.00 1.00	6.00 10.00 0.00 0.38

Precision vs Recall curve



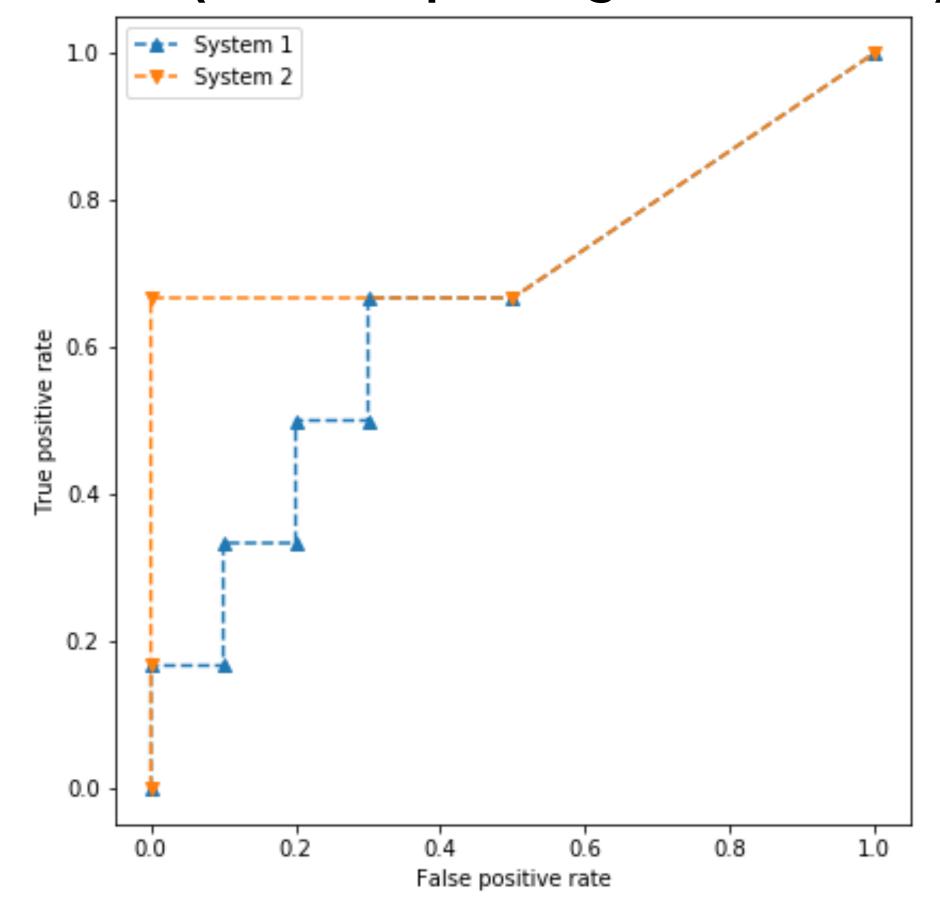
$$AvgP = \int_0^1 P(R)dR \approx \sum_{k=1}^n P(k)\Delta R(k)$$
, where $\Delta R(k)$ is the change in R from $k-1$ to k





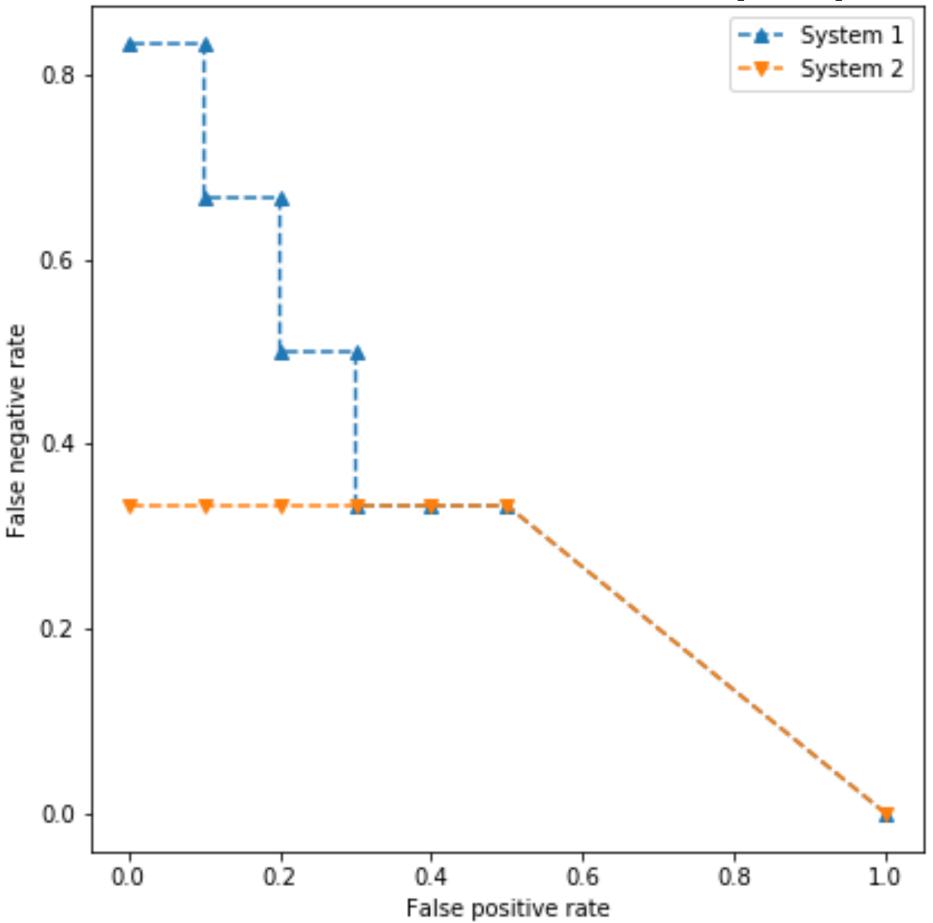
The ROC (receiver operating characteristic) curve is created by plotting the true positive rate (TPR) (Recall) against the false positive rate (FPR) (FP / (FP + TN)) at various threshold settings.

ROC (receiver operating characteristic)



Detection Error Tradeoff (DET)





The **Detection Error Tradeoff (DET)** curve is created by plotting the **false negative rate (FNR) (FN / (FN + TP)** against the **false positive rate (FPR) (FP / (FP + TN))** at various threshold settings.