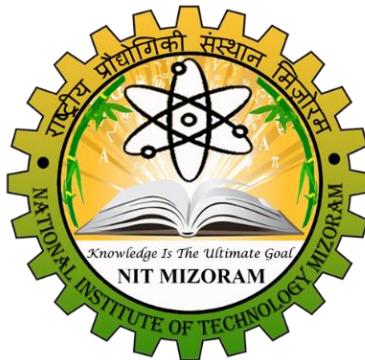


NATIONAL INSTITUTE OF TECHNOLOGY MIZORAM



Laboratory Report

EEP1603

Power Electronics Laboratory

SUBMITTED TO -

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Experiment - 1

- * Aim: Simulation of single-phase half-wave uncontrolled rectifier with R, RL and RLE load by using MATLAB simulink.
- * Requirement: MATLAB / Simulink
- * Theory: Single phase uncontrolled half-wave rectifier are the simplest and possibly the most widely used rectification circuit for small power levels as their output is heavily affected by the reactance of the connected load.
For supply voltage V_s , source current is, V_o & i_o to be diode voltage and current respectively. V_o and i_o is load and current respectively.

$$V_s = V_m \sin(\omega t)$$

→ In positive half cycle, the diode is forward biased and is turned ON at $\omega t = 0^\circ$.
At $\omega t = \pi$, the current through the diode falls to zero, i.e. below zero and simultaneously a reverse voltage appears across the diode and it turns OFF

$$\rightarrow 0 < \omega t < \pi$$

Diode = forward biased (ON)

$$V_D = 0V,$$

$$V_o = V_{ab} = V_m \sin(\omega t)$$

$$i_o = V_o/R = \frac{V_m \sin(\omega t)}{R}$$

* Diagram:

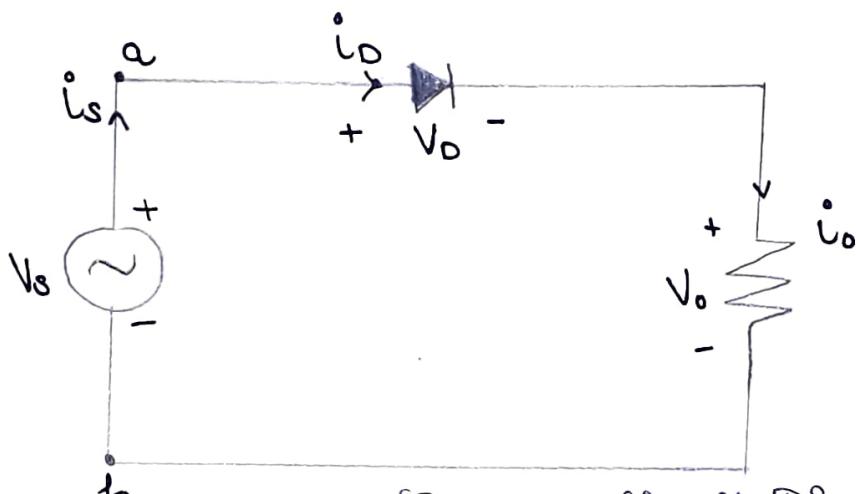


Figure 1.1: Circuit Diagram of 1 ϕ half wave uncontrolled rectifier

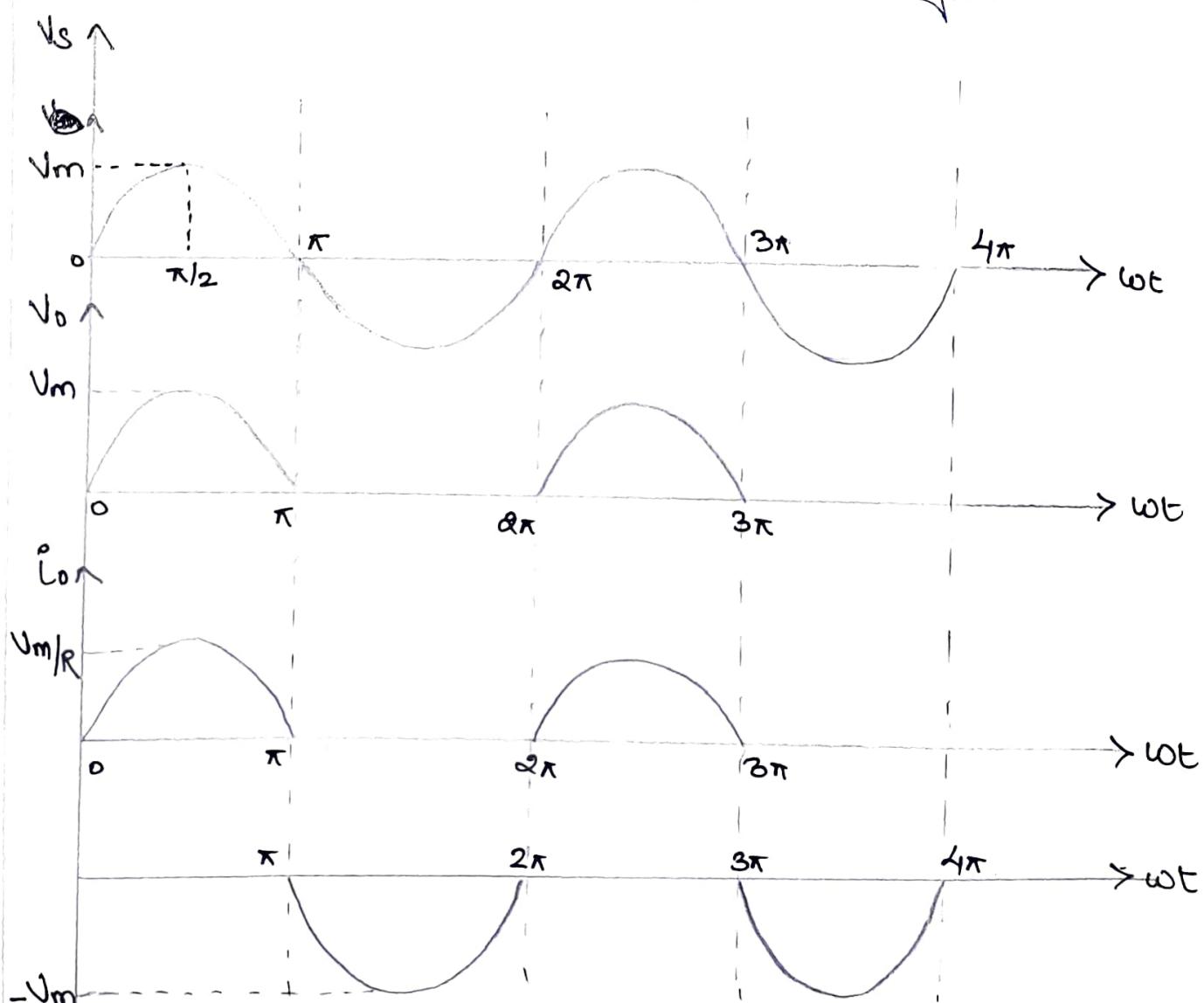


Figure 1.2: Waveform of 1 ϕ half wave uncontrolled rectifier.

$$\rightarrow \pi < wt < 2\pi$$

Diode = Reversed bias (OFF)

$$I_o = 0A$$

$$V_o = 0V$$

$$V_o = V_{ab} = V_m \sin(wt)$$

$$\rightarrow 2\pi < wt < 3\pi$$

Same as $0 < wt < \pi$

\rightarrow Average Values:

$$V_o(\text{avg}) = \frac{V_m}{\pi}$$

$$I_o(\text{avg}) = \frac{V_m}{\pi R}$$

\rightarrow RMS values:

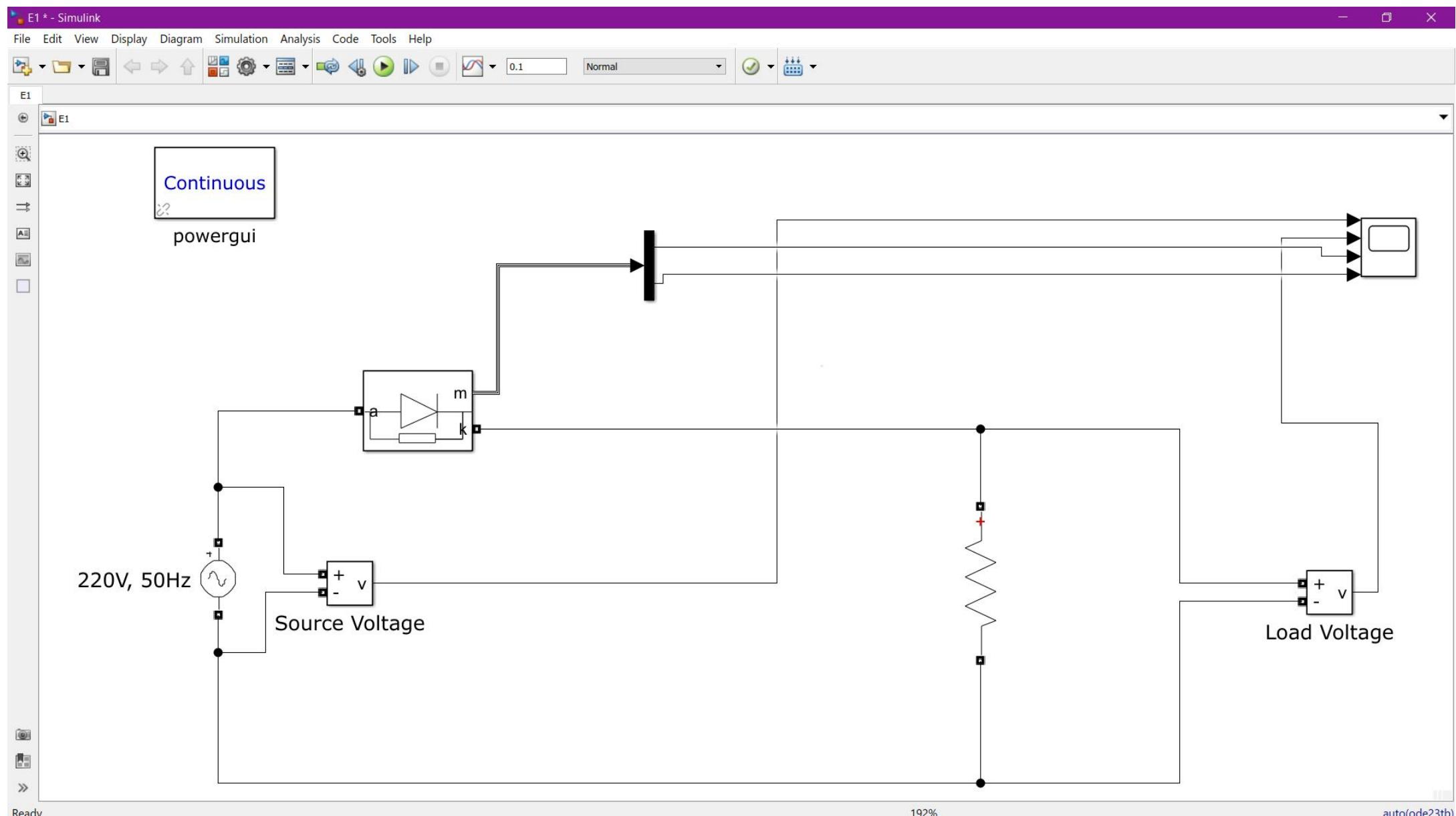
$$I_o(\text{rms}) = \frac{V_o(\text{rms})}{R}$$

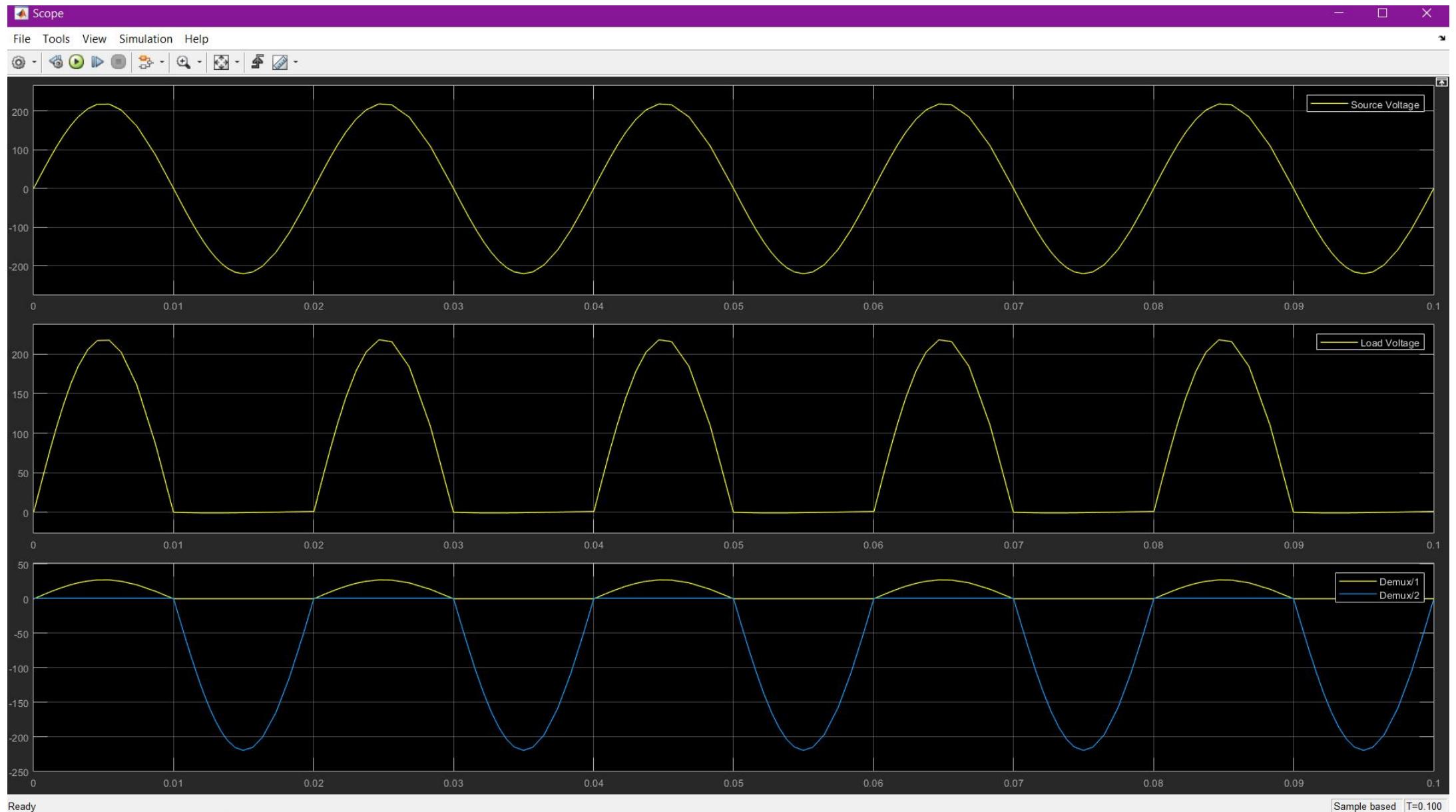
$$V_o(\text{rms}) = \sqrt{\frac{1}{2\pi} \int_0^{2\pi} [V_m \sin(wt)]^2 dt}$$

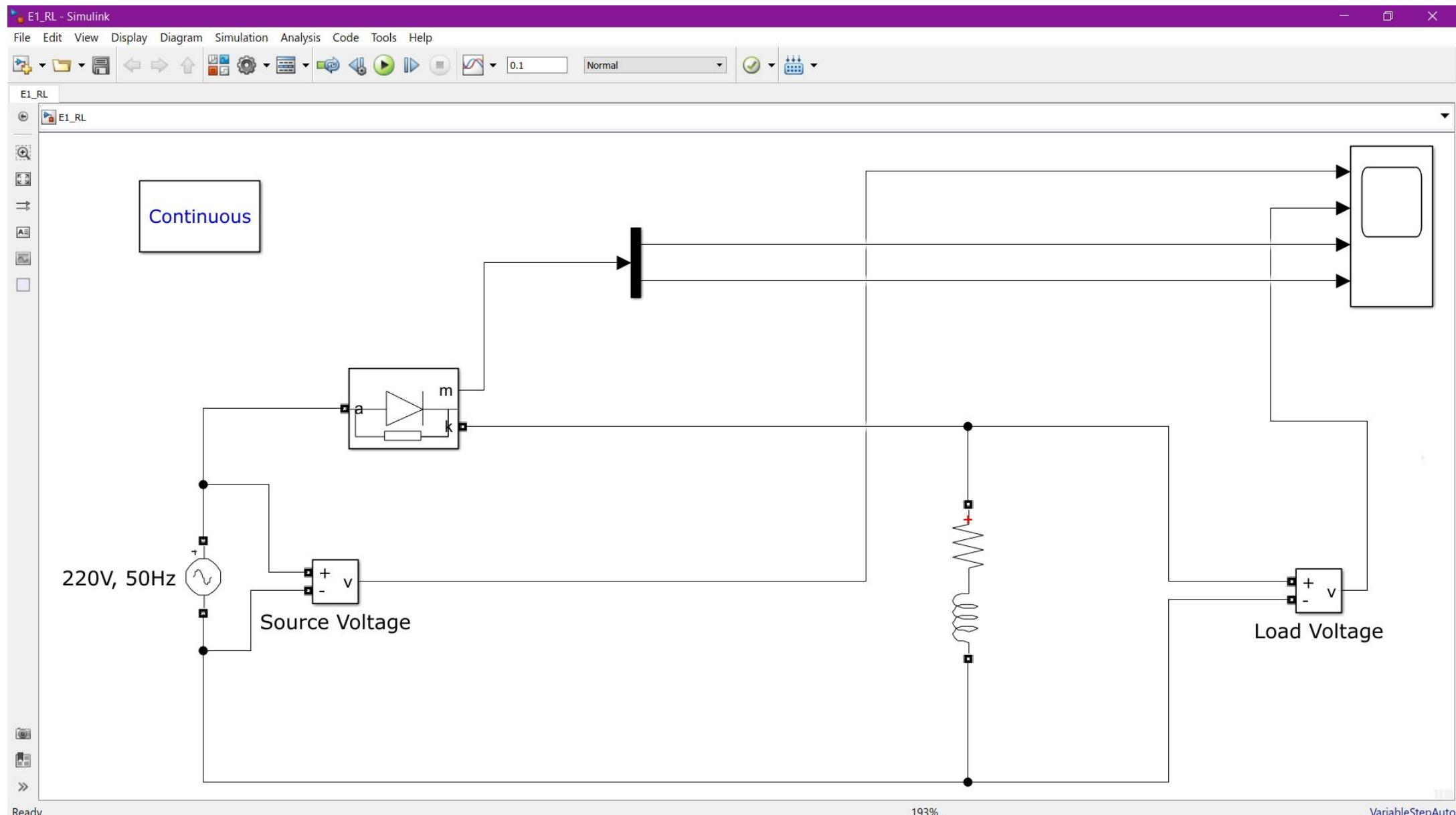
* Procedure:

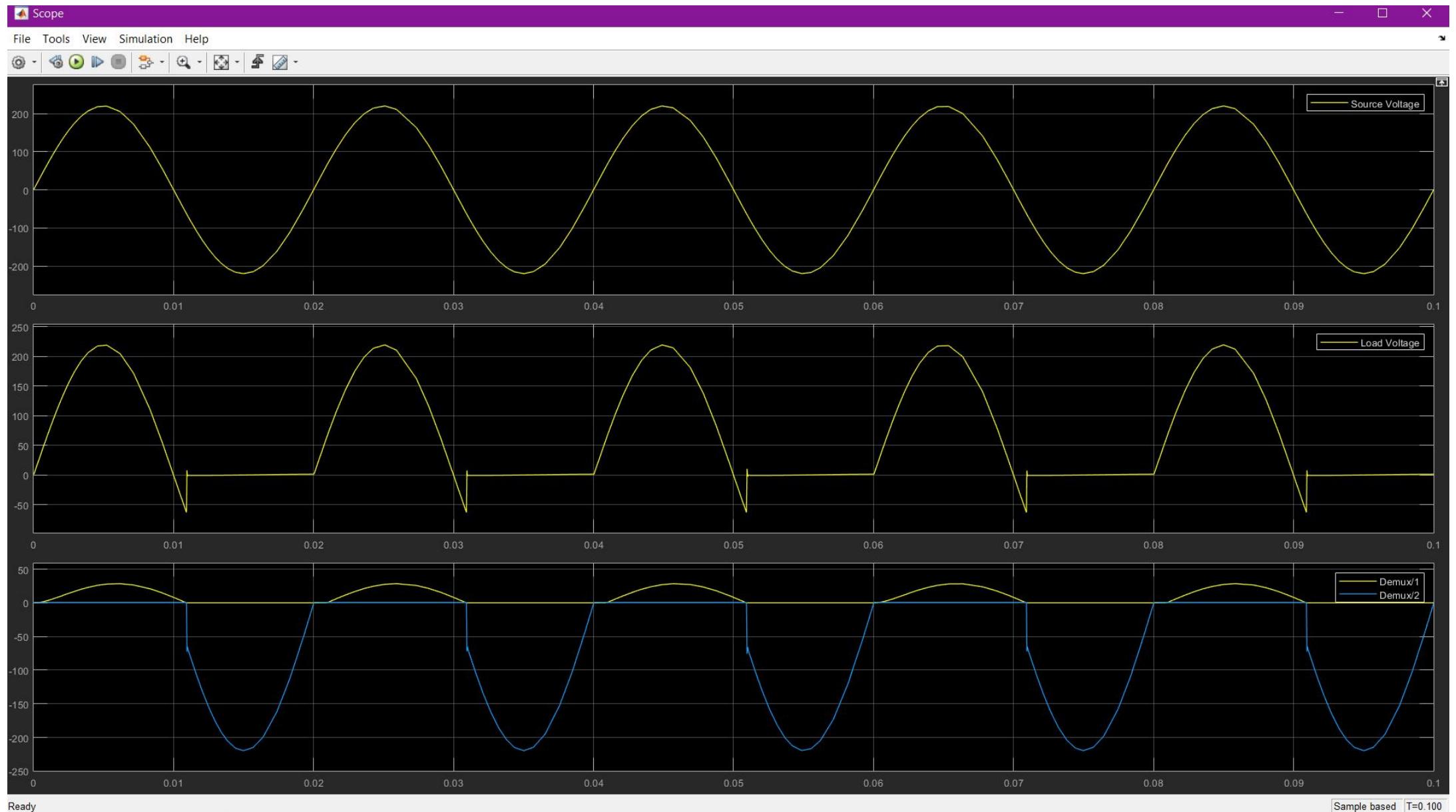
1. Make the required circuit in SIMULINK in MATLAB.
2. Simulate it for 1 ~~sec~~ seconds.
3. Observe the waveform from scope

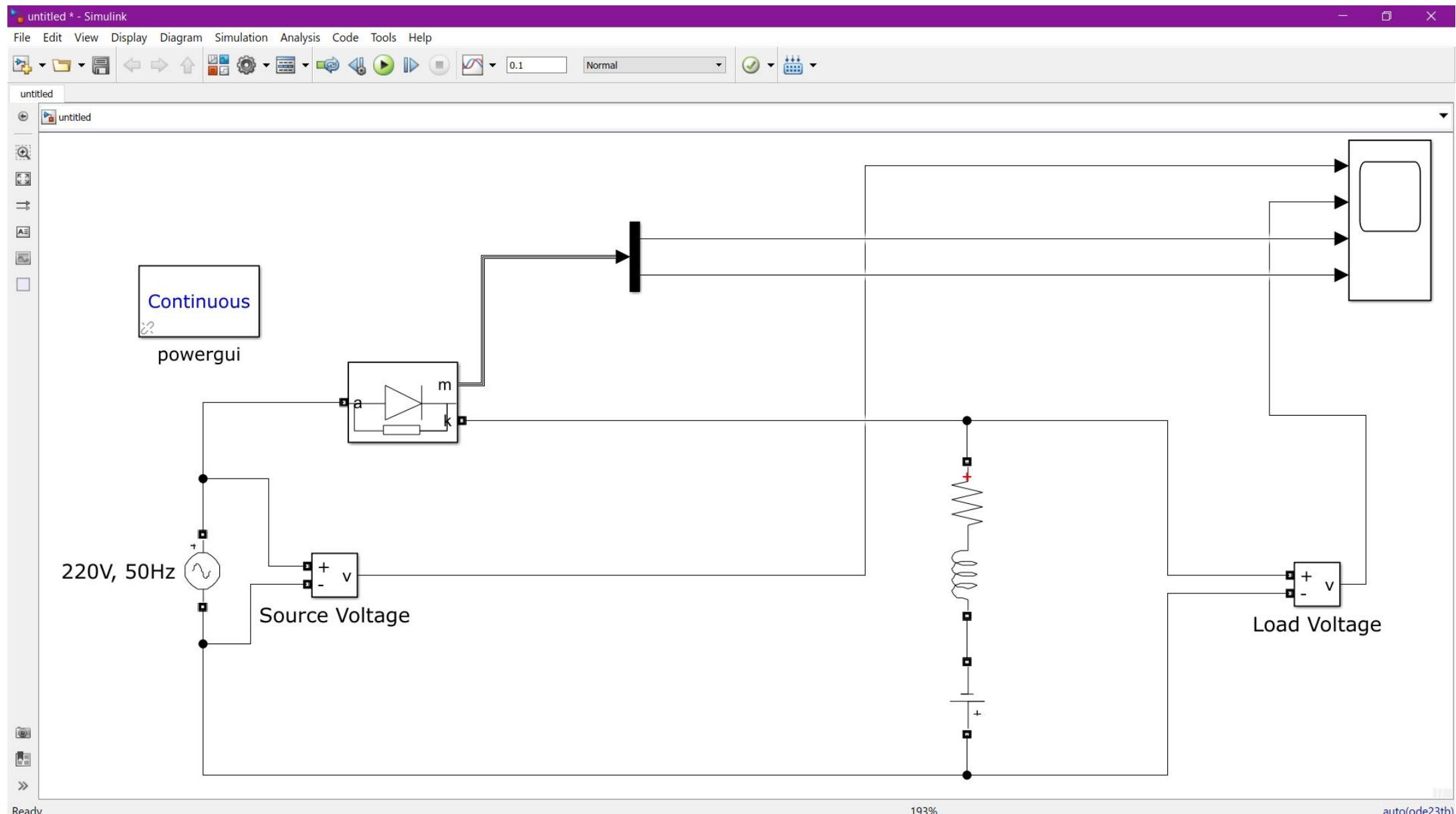
MATLAB Simulation

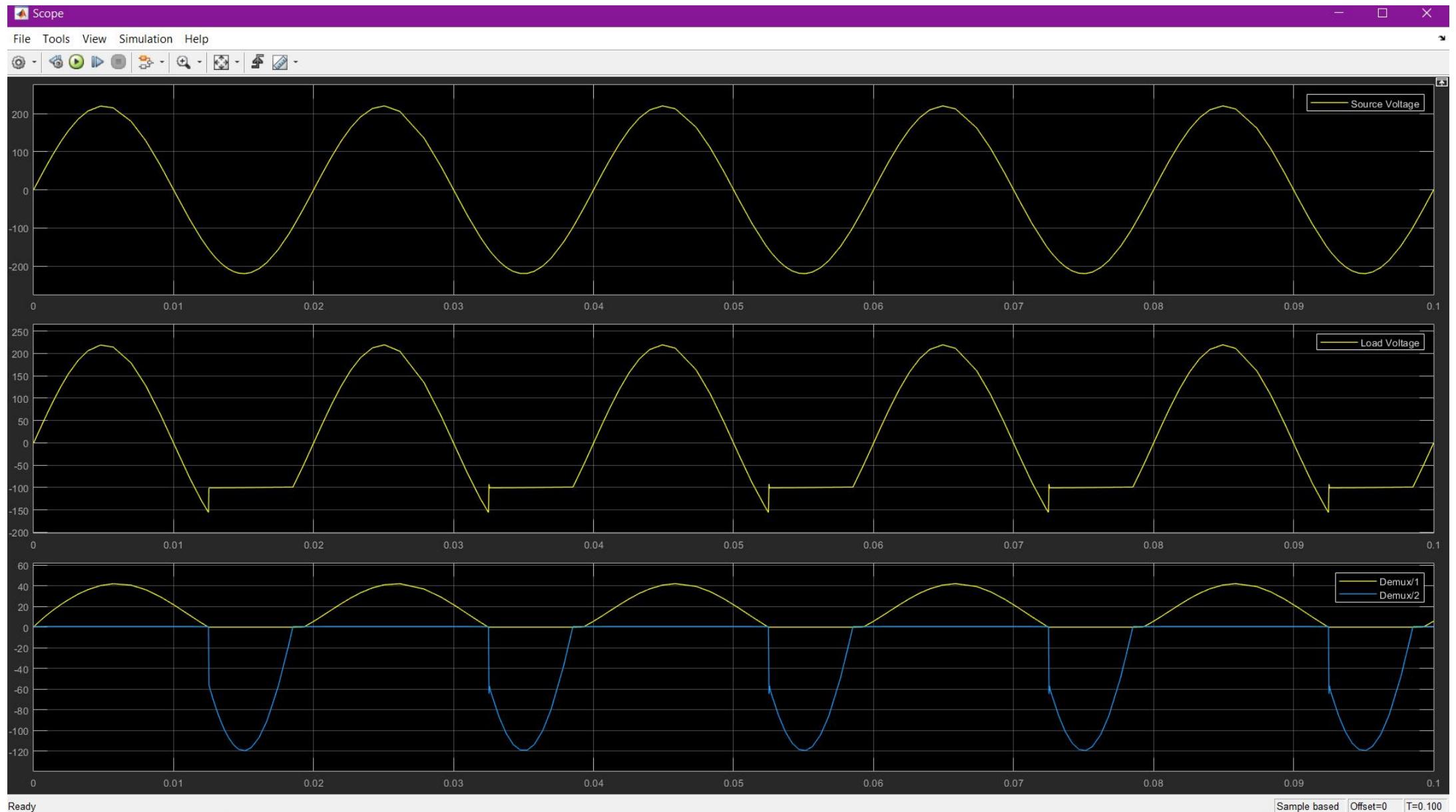












* Result: Simulated the single phase half wave uncontrolled rectifier with R, RL and RLE load by using MATLAB simulink.

* Precautions:

1. Use powergui to store the equivalent simulink circuit that represents the state-space equation of the model.
2. Always use closed circuit, never leave wire open.
3. MATLAB ~~is~~ takes time to respond, do not give multiple command at once.

Experiment - 2

- * Aim: To simulate a single phase full wave uncontrolled rectifier with R, RL and RLC load by using MATLAB - simulink.
- * Requirement: MATLAB - SIMULINK
- * Theory: Unlike the previous half-wave rectifier, the full-wave rectifier utilise both halves of the input sinusoidal waveform to provide a unidirectional output. More efficient than half wave uncontrolled rectifier.
During the positive input half cycle, diode D₁ and D₃ becomes forward biased whereas D₂ and D₄ are reverse biased, and vice versa in other half negative cycle.

$$V_s = V_m \sin(\omega t)$$

$$\rightarrow 0 < \omega t < \pi$$

Diode D₁ & D₃ = forward bias

$$\therefore V_o = V_m \sin(\omega t)$$

$$i_o = V_o / R$$

$$\rightarrow \pi < \omega t < 2\pi$$

Diode D₂ & D₄ = forward bias

$$V_o = V_m \sin(\omega t)$$

$$i_o = V_o / R$$

*

Diagram:

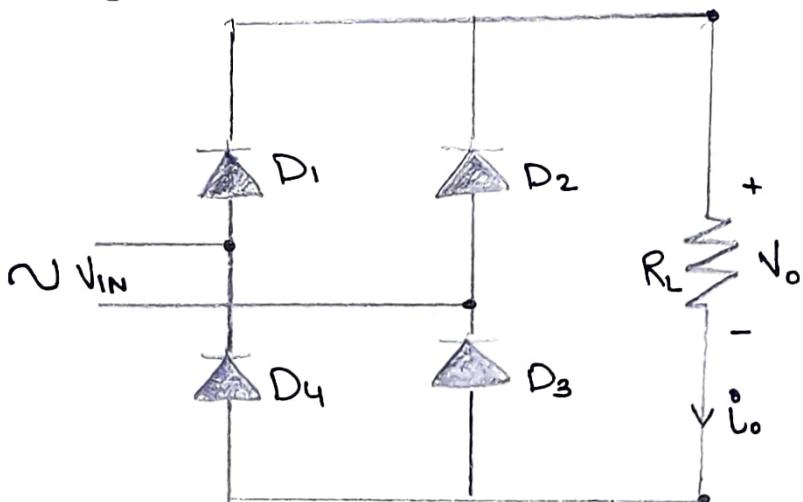


Figure 2.1: Circuit diagram of 1Φ full wave uncontrolled rectifier

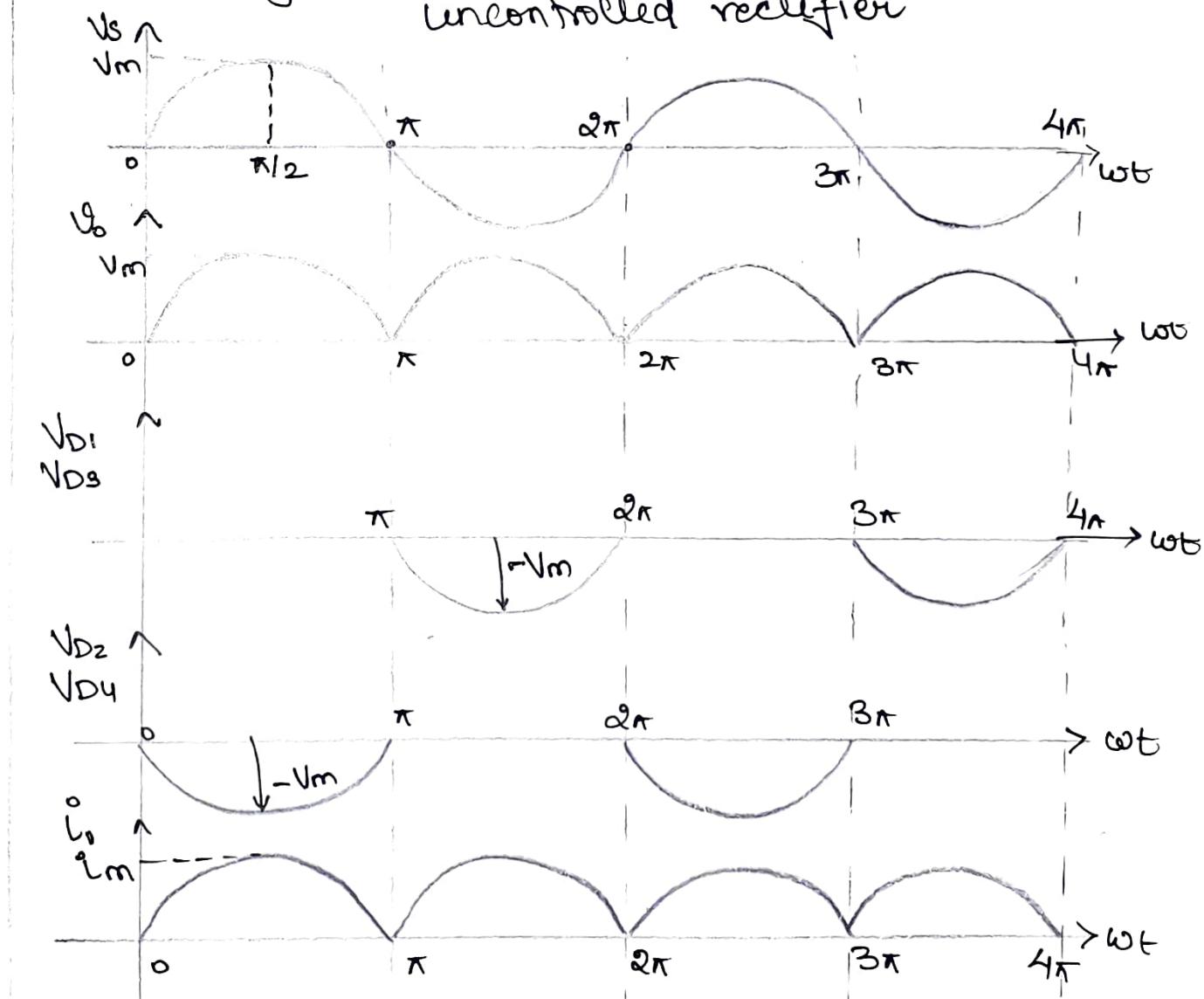


Figure 2.2: Waveform for the circuit

→ Average value

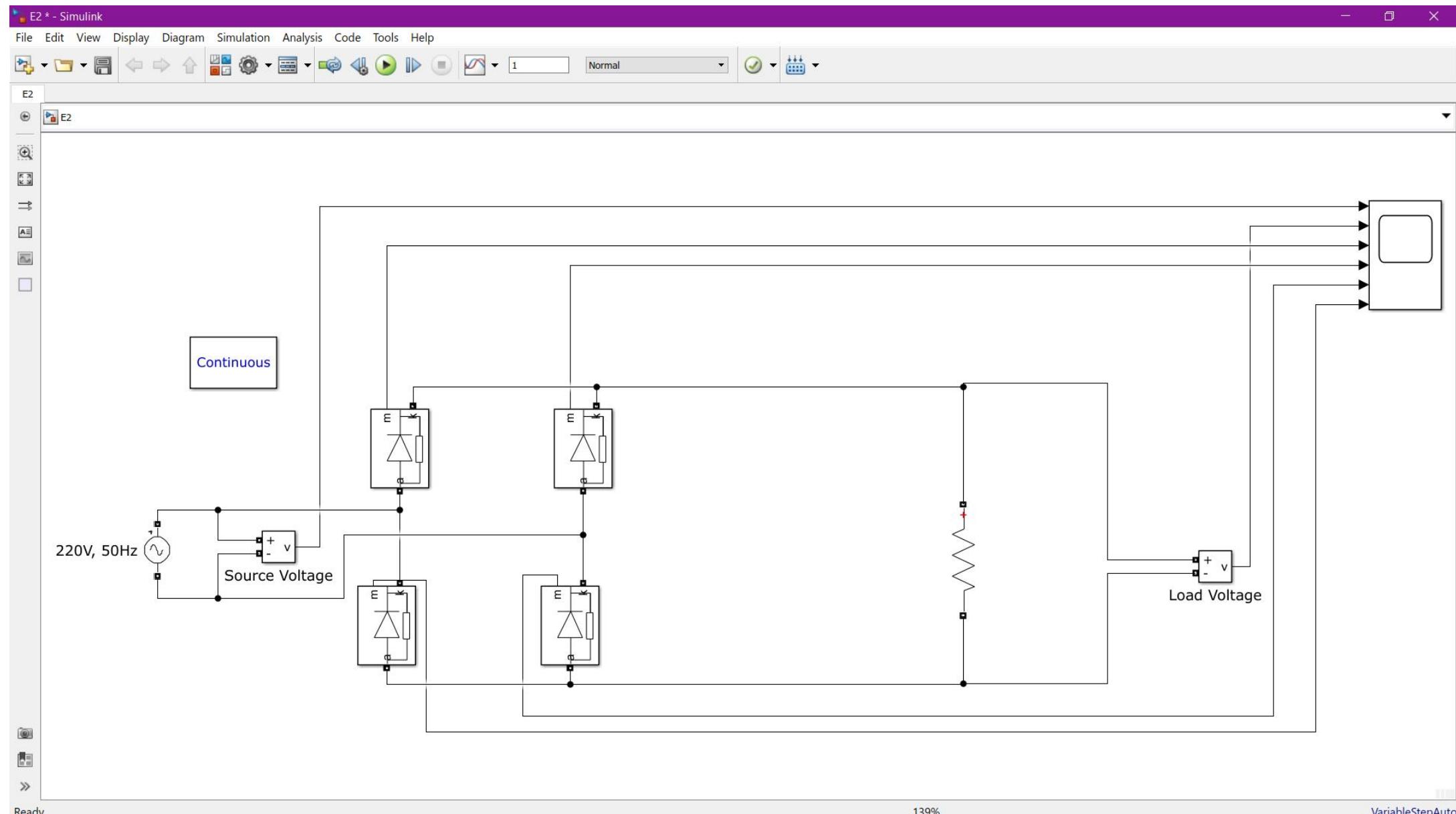
$$V_{avg} = 0.637 \text{ Vm}$$

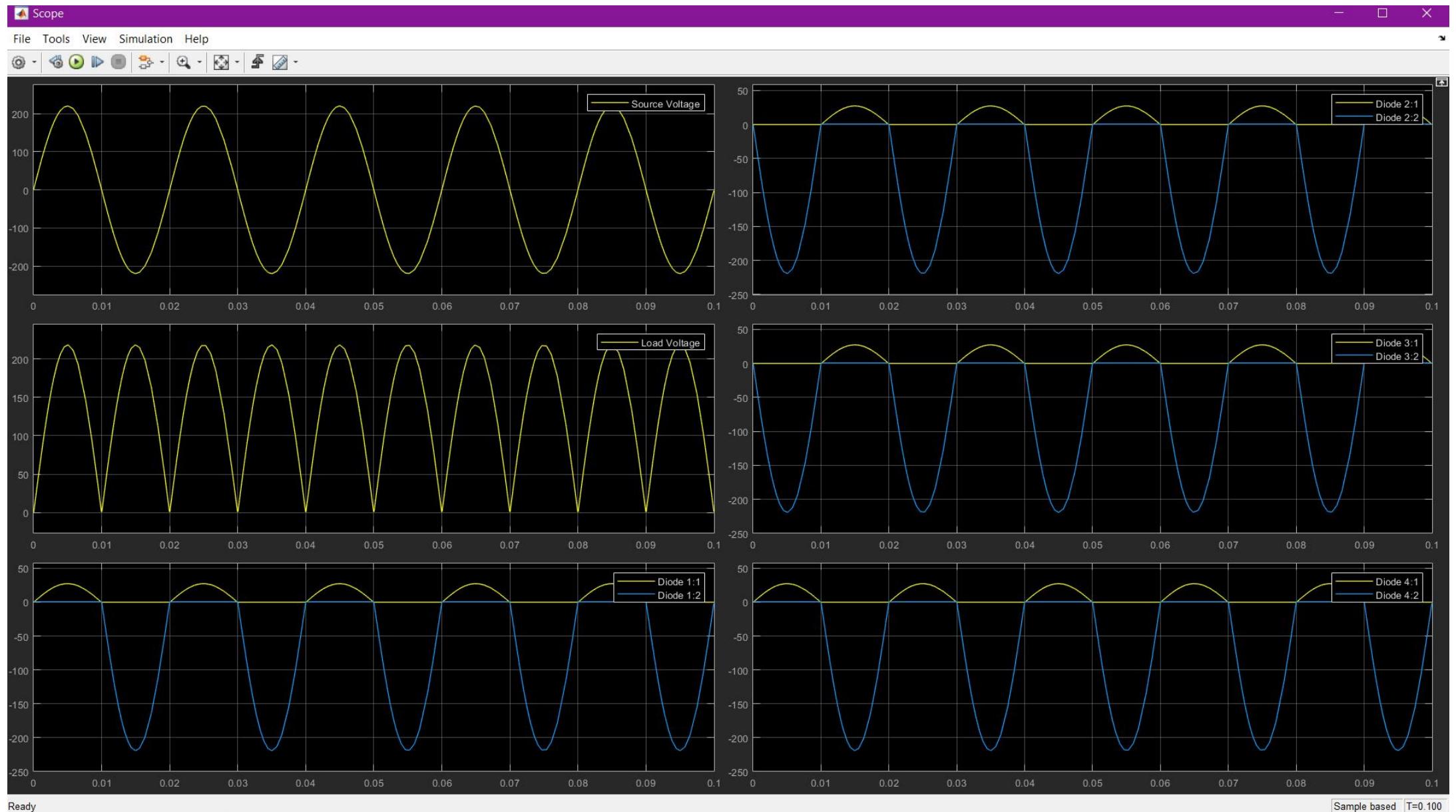
$$I_{o(\text{avg})} = 0.637 \text{ Im.}$$

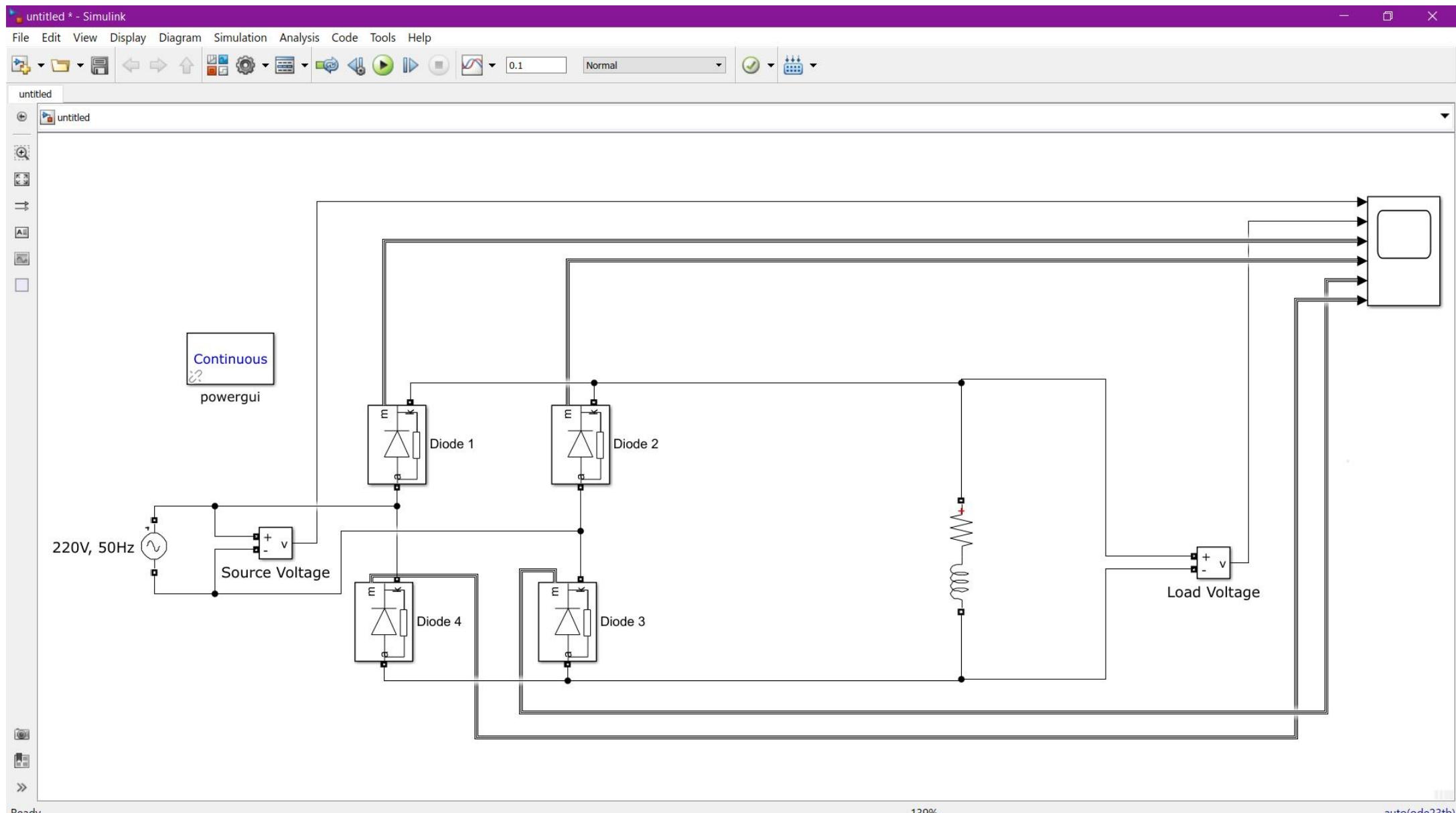
* Procedure:

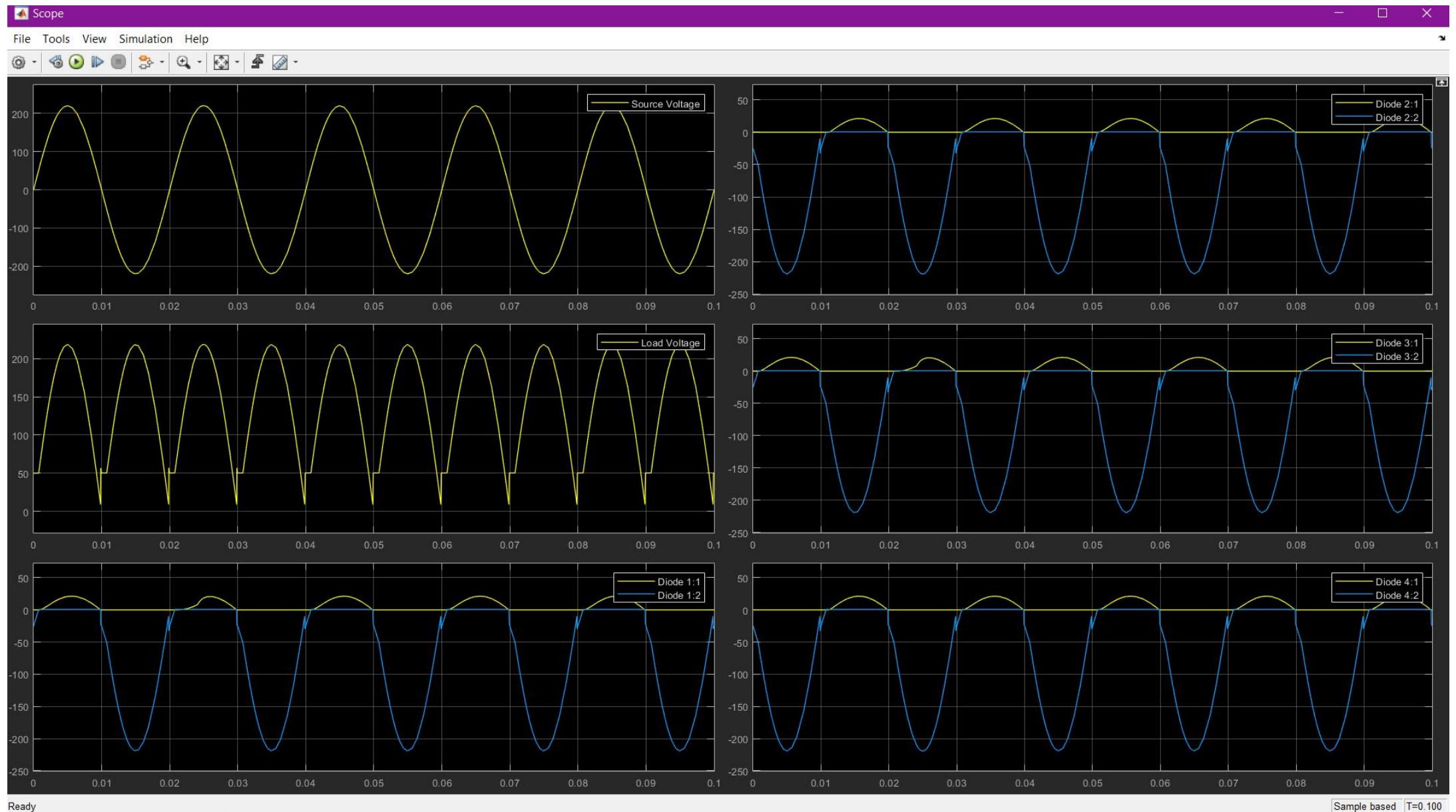
1. Make the required circuit in SIMULINK in MATLAB.
2. Simulate the circuit for 1 second.
3. Observe the waveform from the scope.

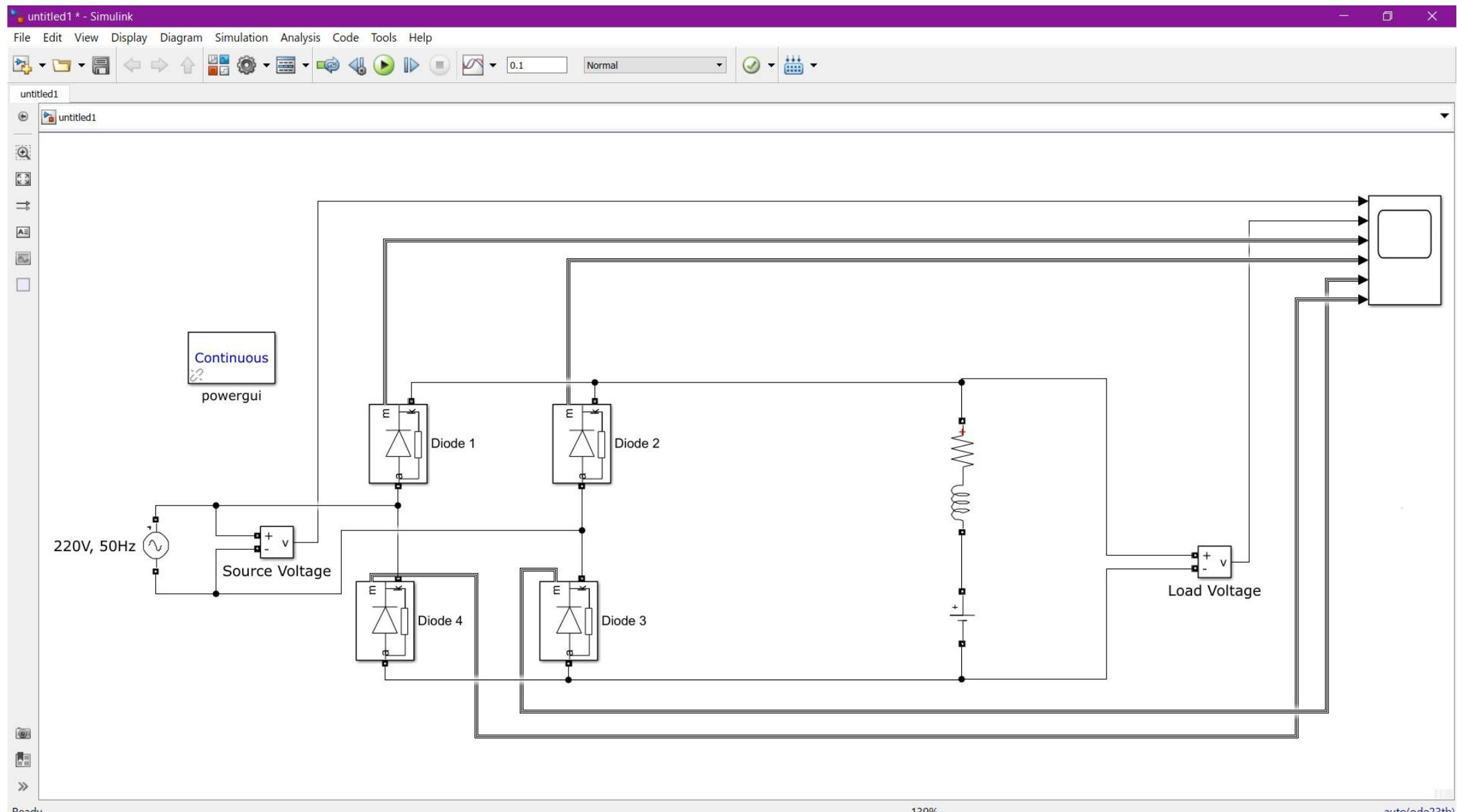
MATLAB Simulation

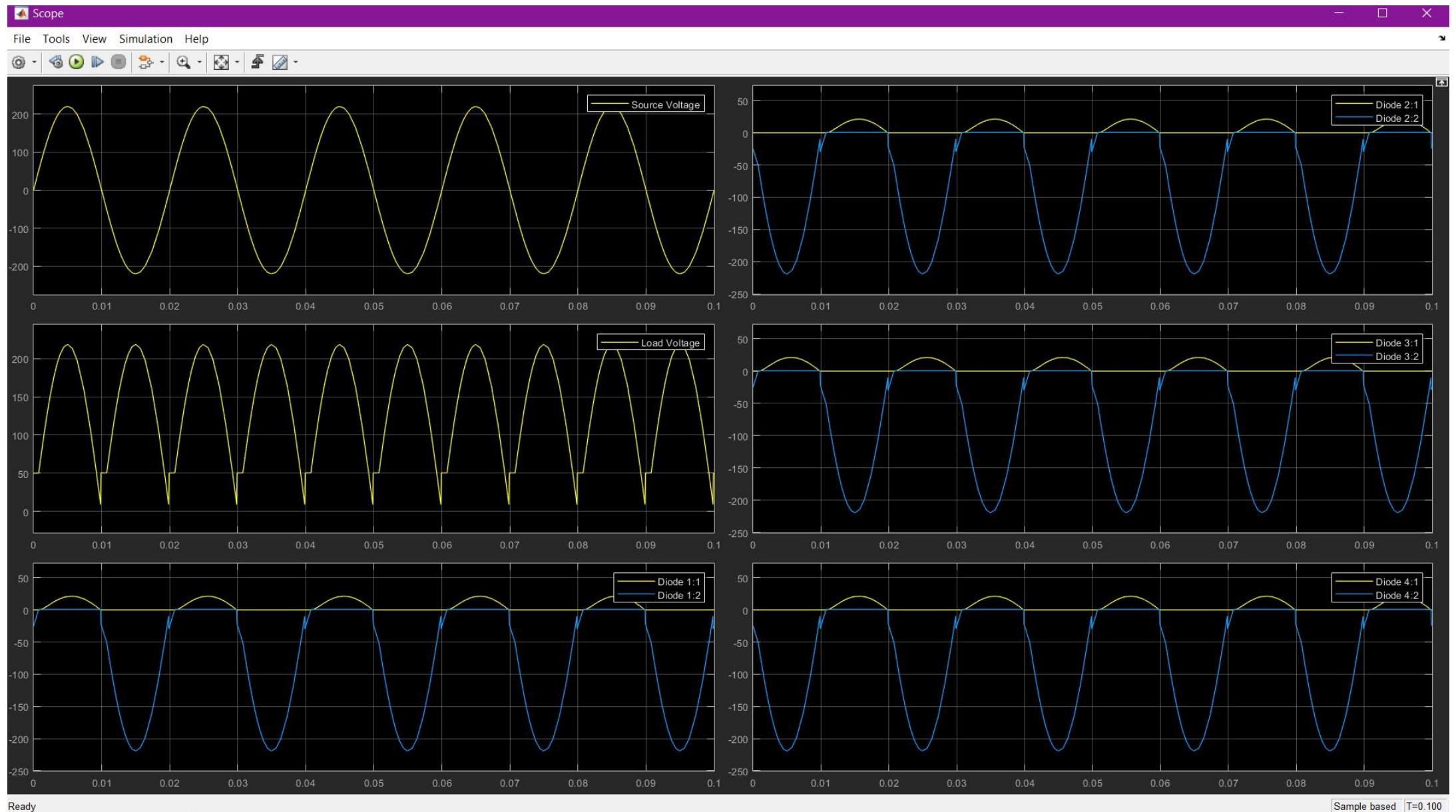












* Result: Simulated the single phase full wave uncontrolled rectifier with R, RL and RLC load by using MATLAB - simulink.

* Precautions:

1. Use powergui to store the equivalent simulink circuit that represents the state-space equation of the Model.
2. Always use closed circuit, never leave wire open.
3. MATLAB takes time to respond, do not give multiple command at once.

Experiment - 3

- * Aim: To simulate a three phase full wave uncontrolled rectifier in MATLAB Simulink with R, RL and RLC load
- * Requirement: MATLAB Simulink
- * Theory: A three phase full wave diode rectifier with ~~fixed~~ load uses diode to provide an average output voltage of fixed value relative to the value of the input AC voltage. It's commonly used in industry to produce a dc voltage and current for large loads.

$$V_{an} = V_m \sin(\omega t)$$

$$V_{bn} = V_m \sin(\omega t - 2\pi/3)$$

$$V_{cn} = V_m \sin(\omega t - 4\pi/3)$$

$$V_{ab} = V_{an} - V_{bn} = \sqrt{3} V_m \sin(\omega t + \pi/6)$$

$$V_{bc} = V_{bn} - V_{cn} = \sqrt{3} V_m \sin(\omega t - \pi/2)$$

$$V_{ca} = V_{cn} - V_{an} = \sqrt{3} V_m \sin(\omega t - 7\pi/6)$$

$$V_{dc} = \frac{3\sqrt{3} V_m}{\pi} = 1.654 V_m \quad V_{rms} = 1.655 V_m$$

$$I_{dc} = 1.654 \frac{V_m}{R} \quad I_{rms} = 0.718 I_m$$

$$I_D(rms) = 0.552 I_m$$

Average Power

where, $I_m = 1.73 V_m / R$

$$P_{dc} = V_{dc} I_{dc}$$

* Diagram:

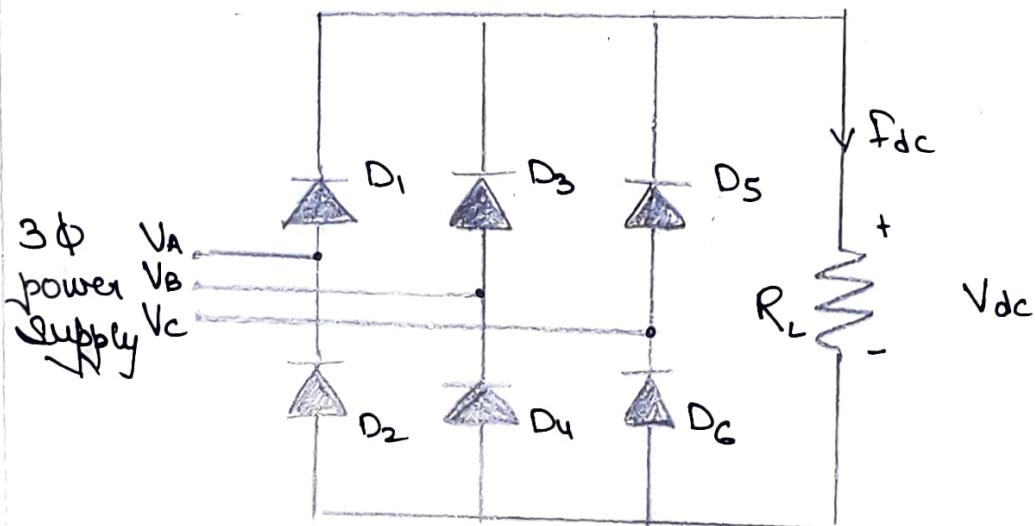
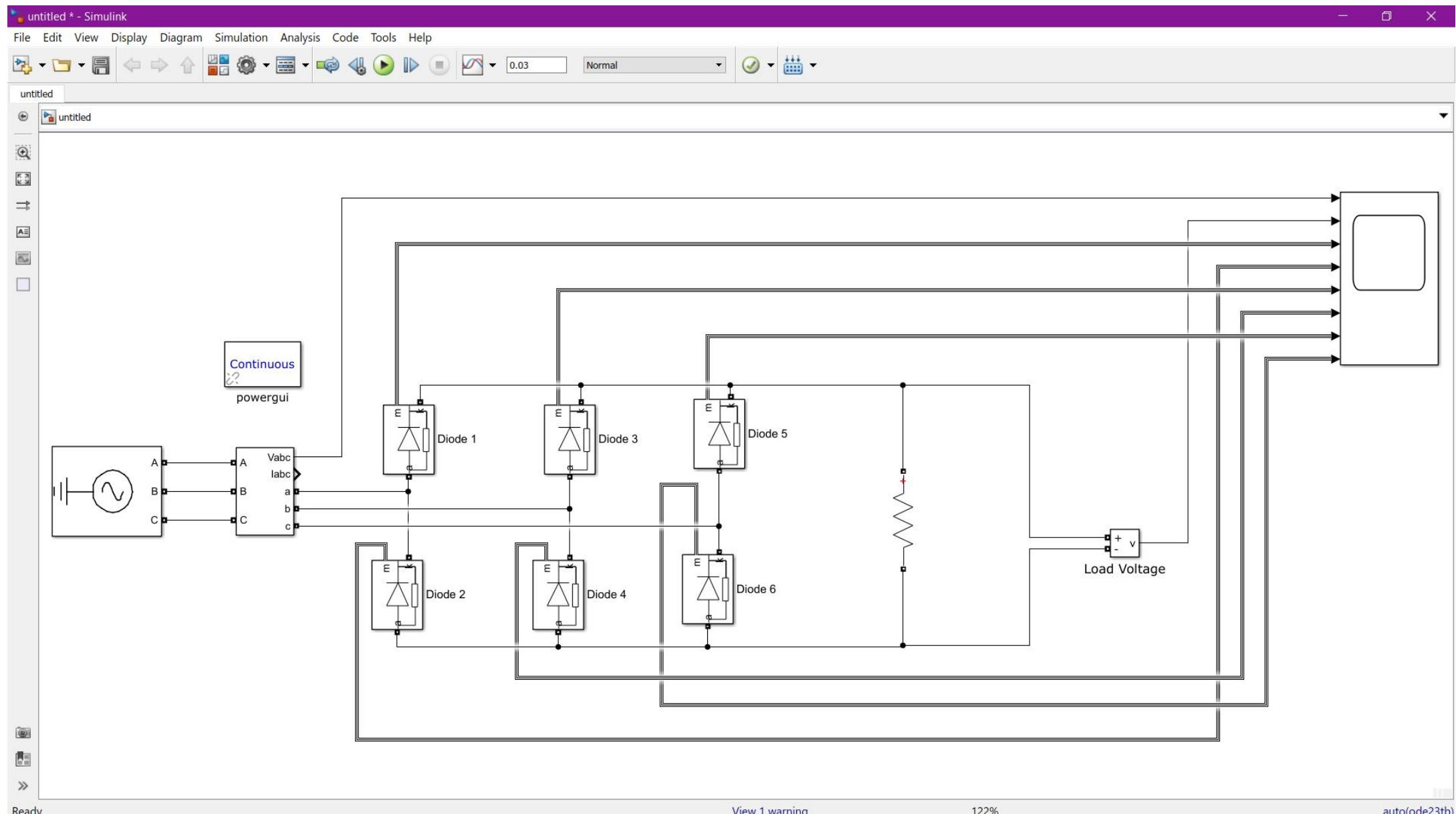
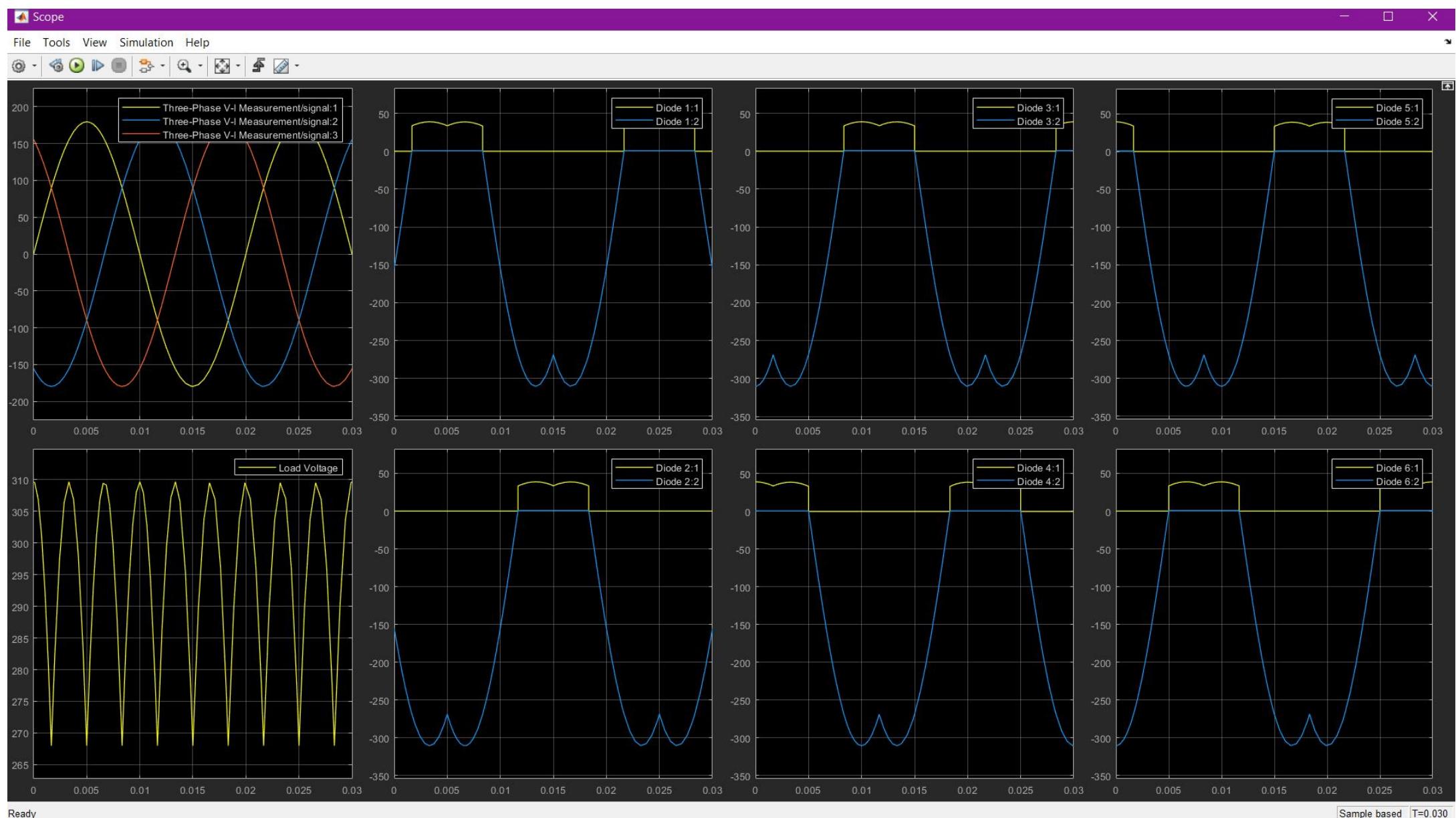
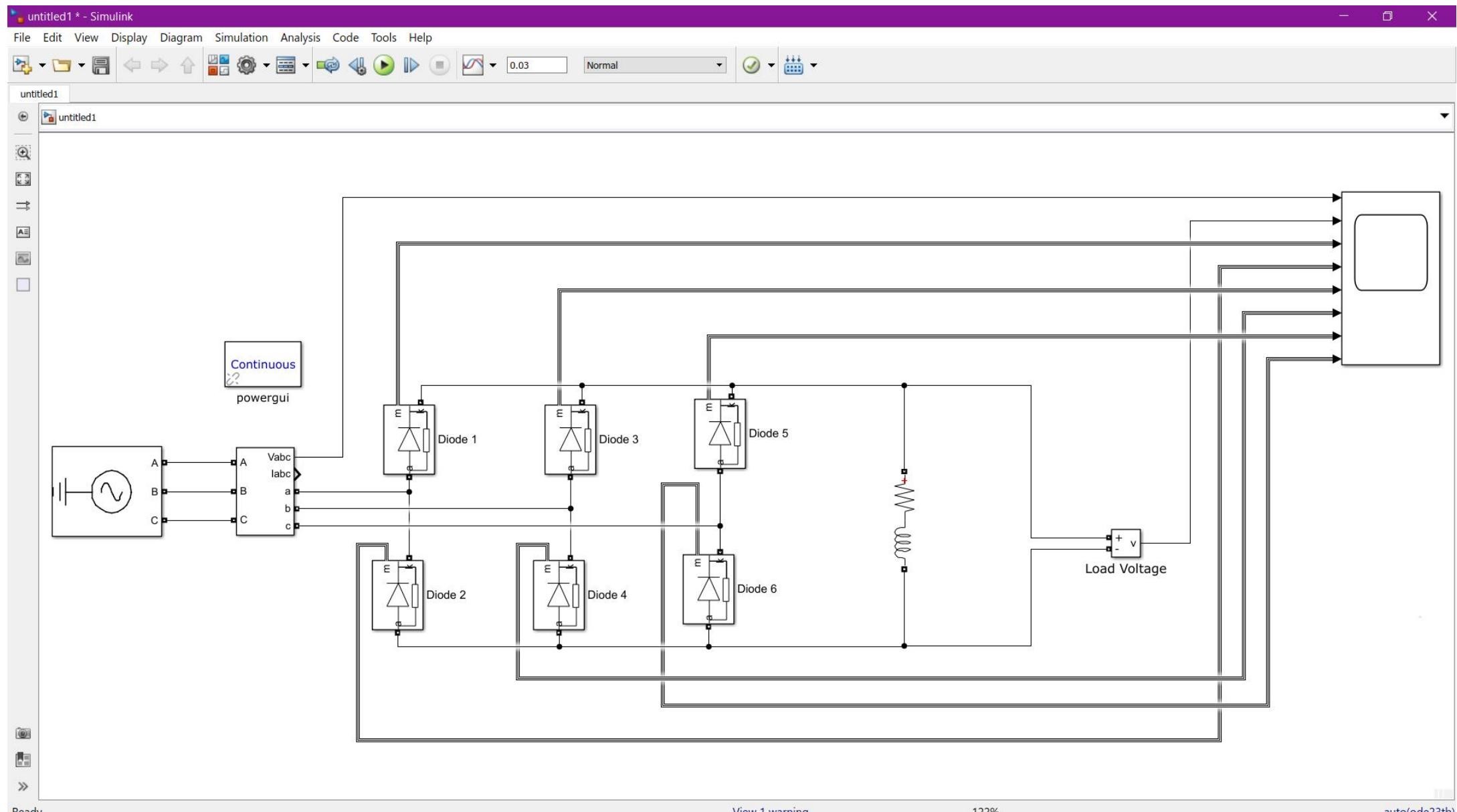


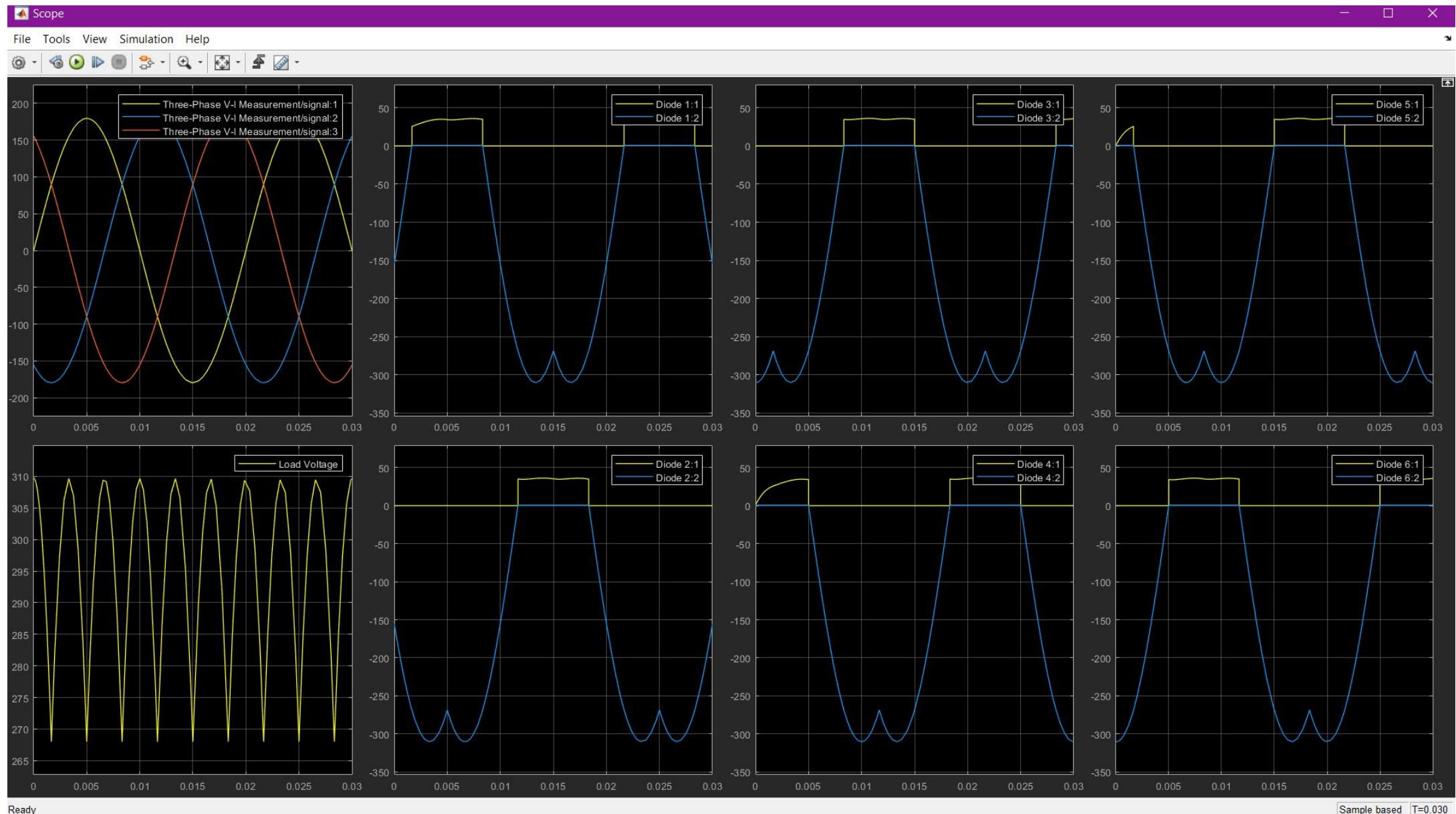
Figure 3.1: Circuit diagram for 3 ϕ full wave uncontrolled rectifier.

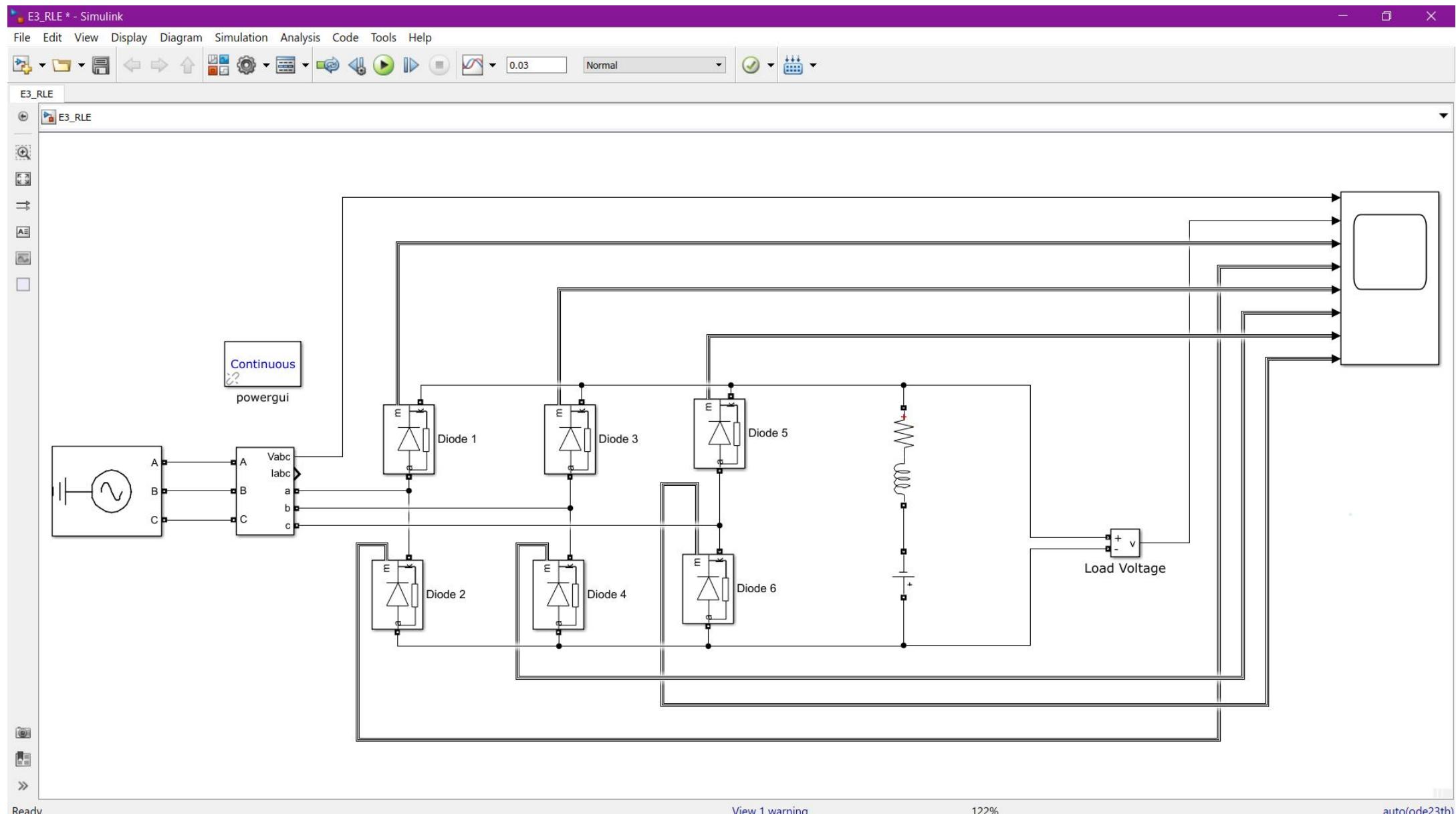
MATLAB Simulation

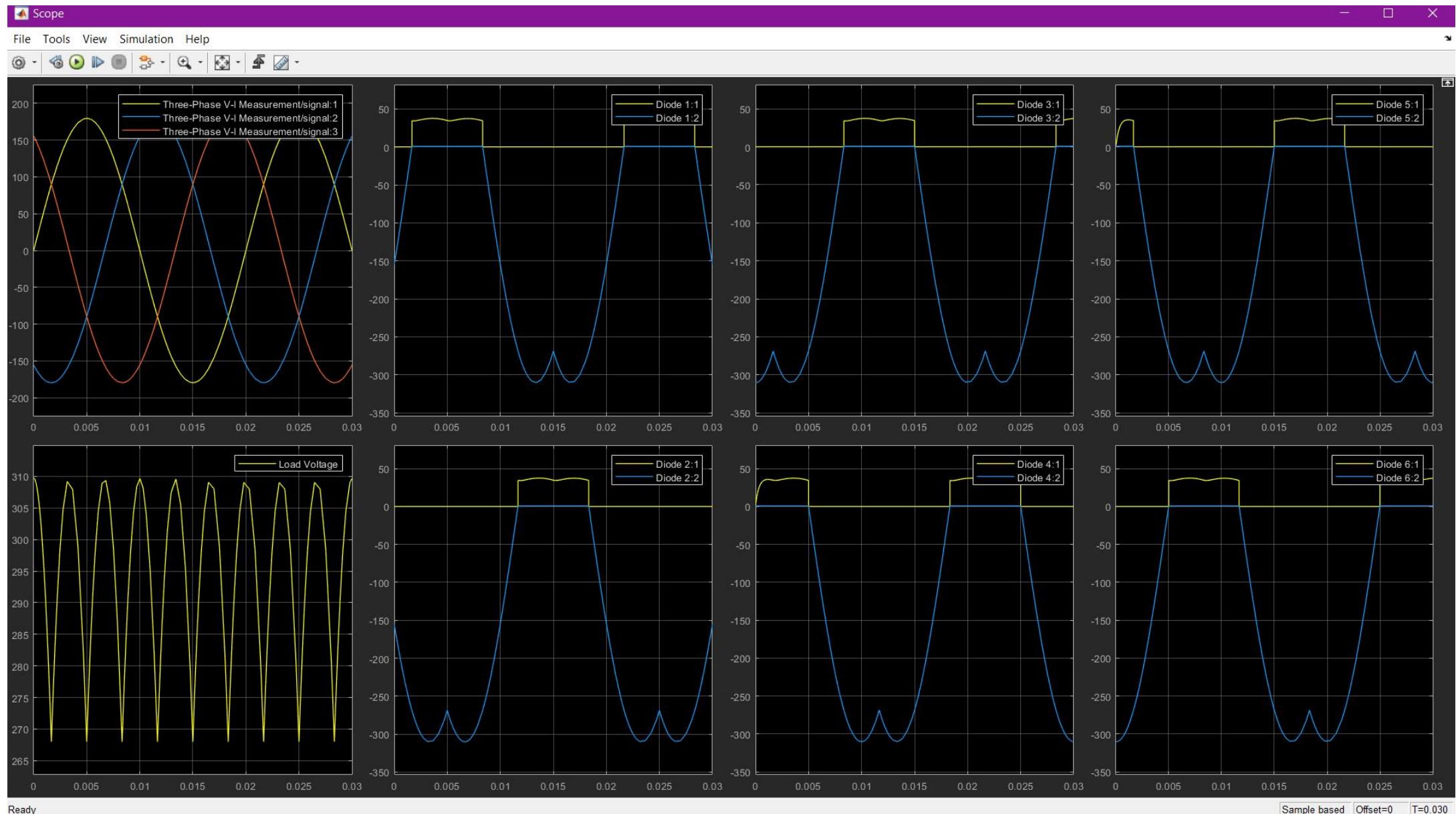












* Procedure:

1. Make the required circuit in SIMULINK in MATLAB.
2. Simulate the model for 1 seconds.
3. Observe the waveform from the scope.

* Result: Simulated a three phase full wave uncontrolled rectifier in MATLAB simulink with R, RL and RLE load.

* Precautions:

1. Use powergui to store the equipment simulink circuit that represents the state-space equation of the model.
2. Always use closed circuit, never leave wire open.
3. MATLAB takes time to respond, do not give multiple command at once.

Experiment -4

- * Gim: To simulate of single-phase half wave controlled rectifier for R, RL, RLE and also use free wheeling diode by using MATLAB-Simulink.
- * Requirement: MATLAB-Simulink.
- * Theory: A single phase half wave controlled rectifier circuit of SCR/thyristor, an AC voltage source and load. The load may be purely resistive, Inductive or a combination of resistance and inductance. For load output voltage V_o , load current i_o and voltage across the thyristor V_T .
$$V_S = V_m \sin(\omega t)$$

let us go ahead, assume that thyristor T is fired at a firing angle of α . This means when $\omega t = \alpha$, gate signal will be applied and SCR will start conducting. Thyristor T is forward biased for the positive half cycle of supply voltage. The load output voltage is zero till SCR is fired. At α , SCR starts conducting. At $\omega t = \pi$, voltage become zero, and after $\omega t = \pi$ SCR is reversed biased. till next firing thyristor will remain OFF.

$$V_o = V_m \sin(\omega t) \quad \text{for } \alpha \leq \omega t \leq \pi$$

$$i_o = \frac{V_m \sin(\omega t)}{R} \quad \text{for } \alpha \leq \omega t \leq \pi$$

* Diagram:

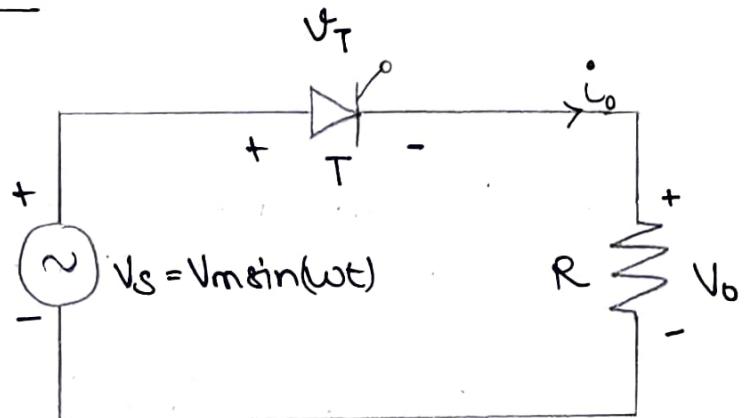


Figure 4.1: Circuit Diagram of 1φ half wave controlled rectifier.

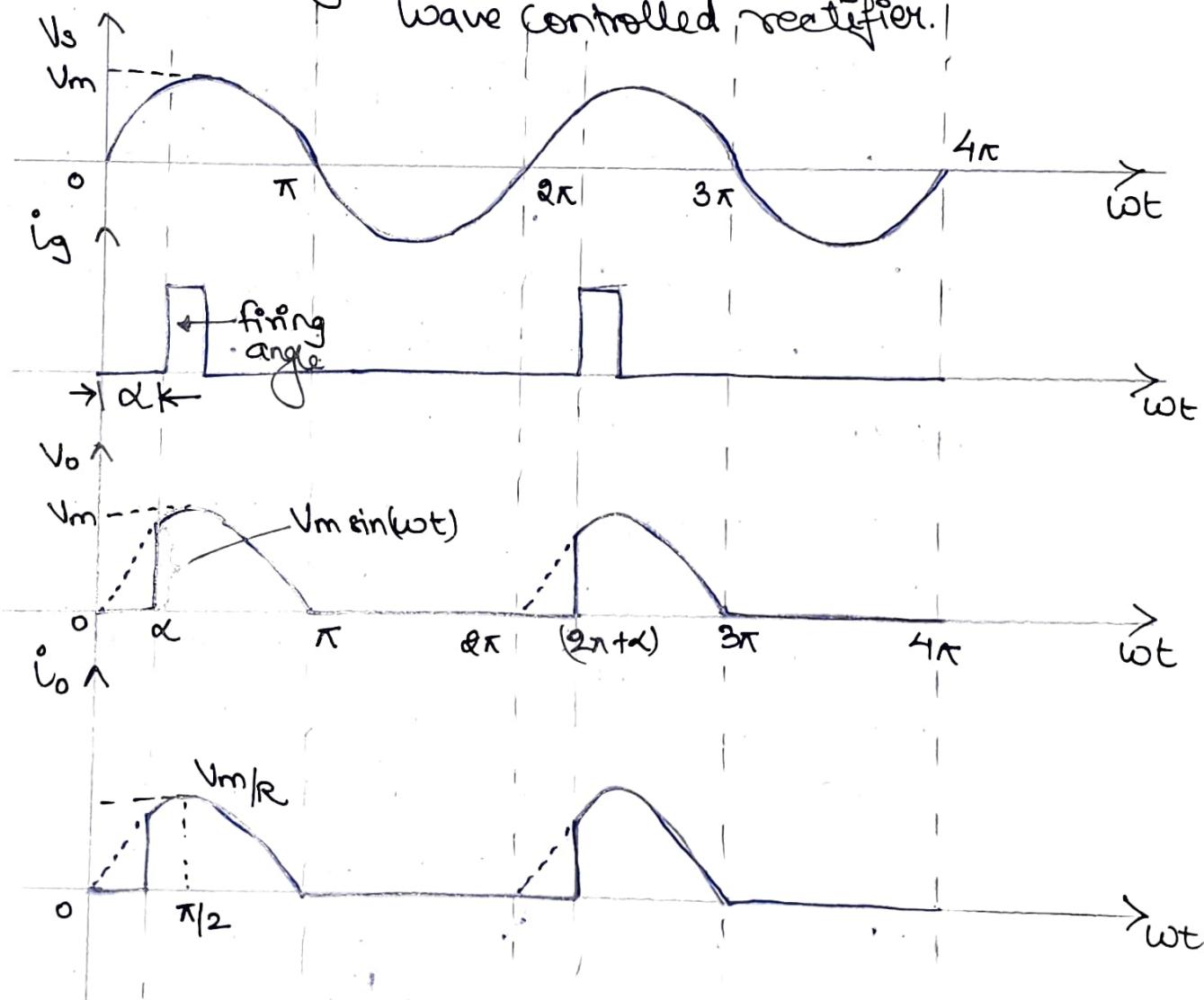


Figure 4.2: Waveform of 1φ half wave controlled rectifier.

→ Average value

$$V_o(\text{avg}) = \left(\frac{V_m}{2\pi} \right) [1 + \cos \alpha]$$

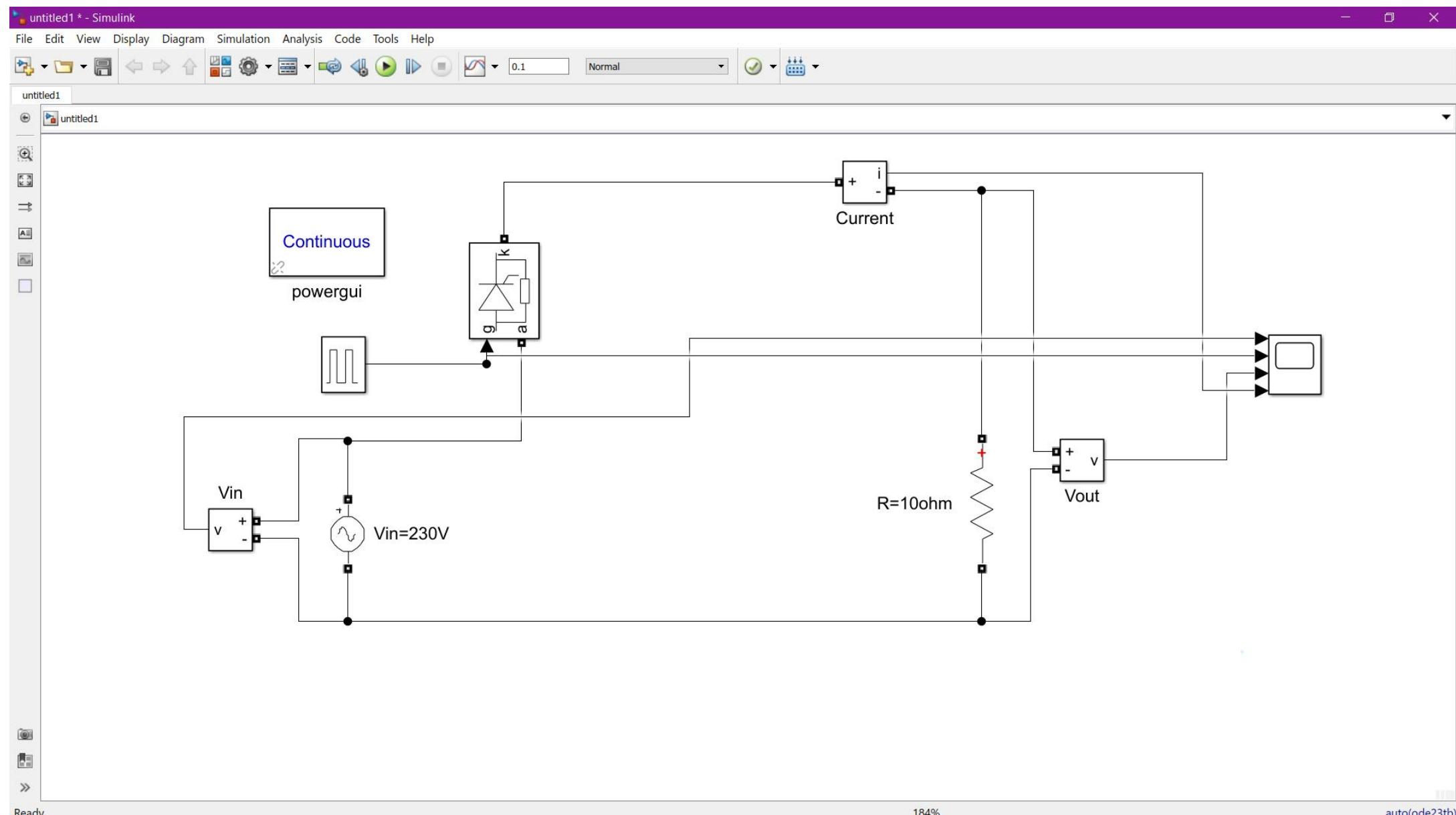
→ RMS value

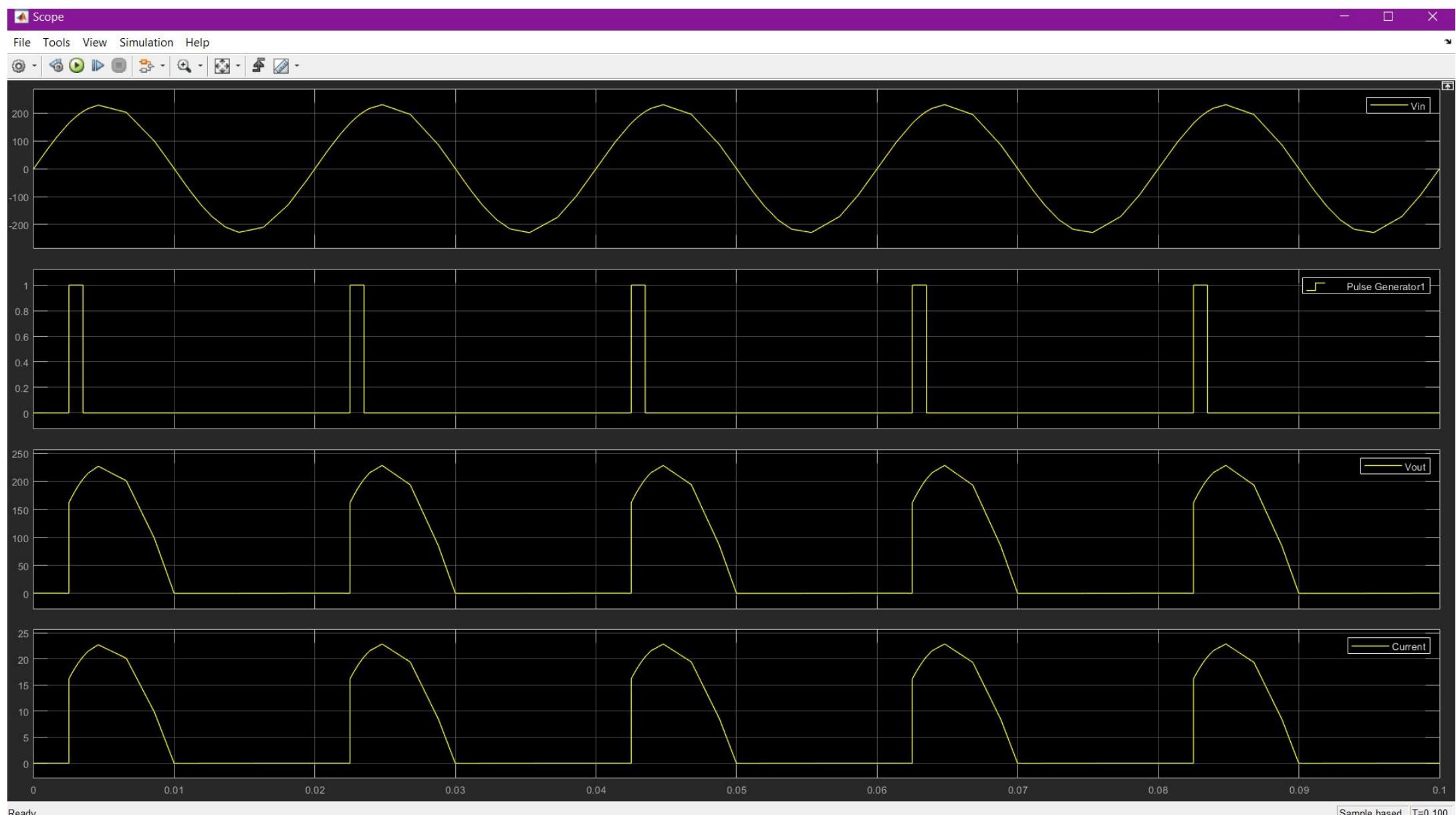
$$V_o(\text{rms}) = \frac{V_m}{2\sqrt{\pi}} \sqrt{(\pi - \alpha) + \frac{\sin 2\alpha}{2}}$$

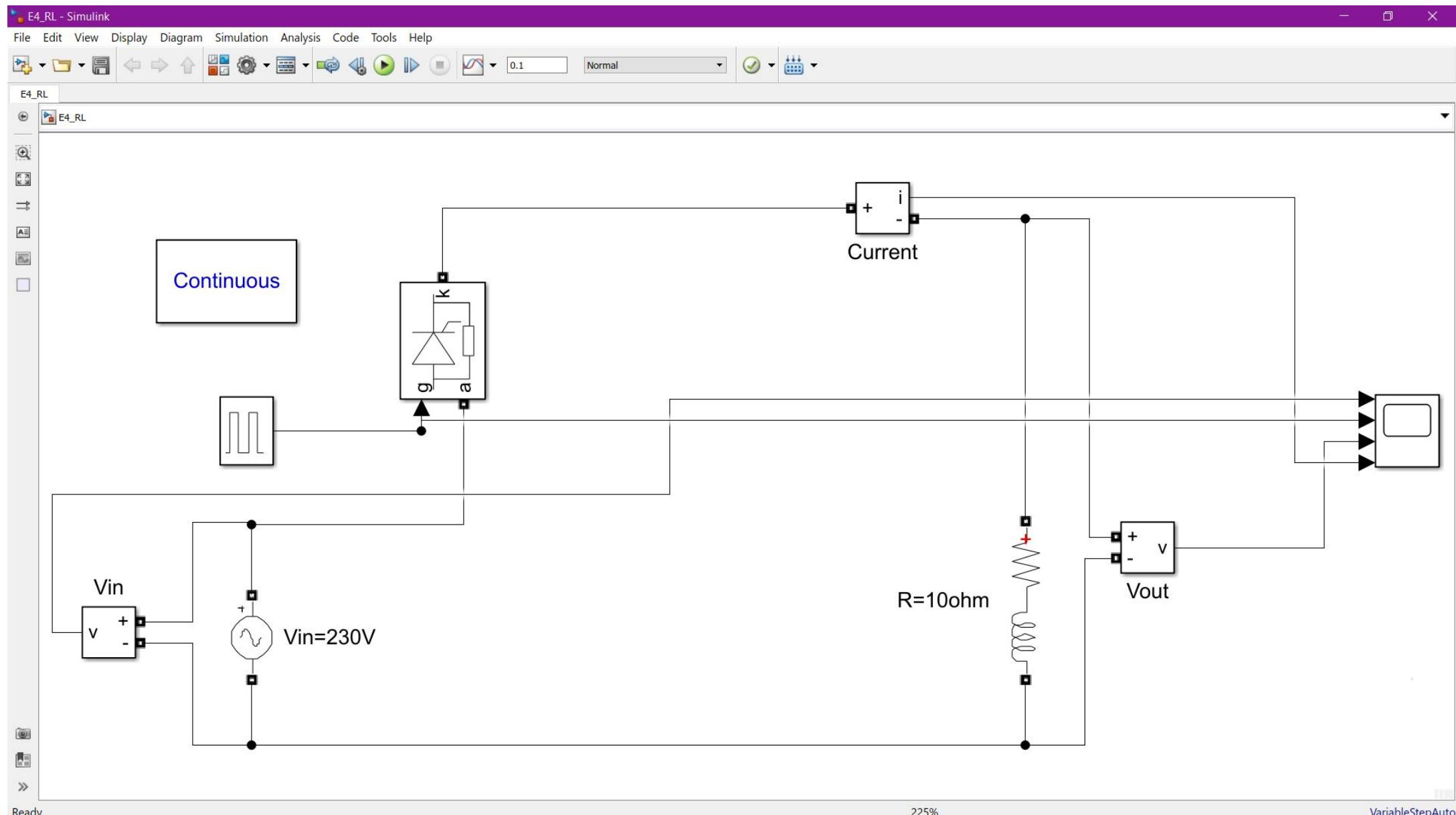
* Procedure:

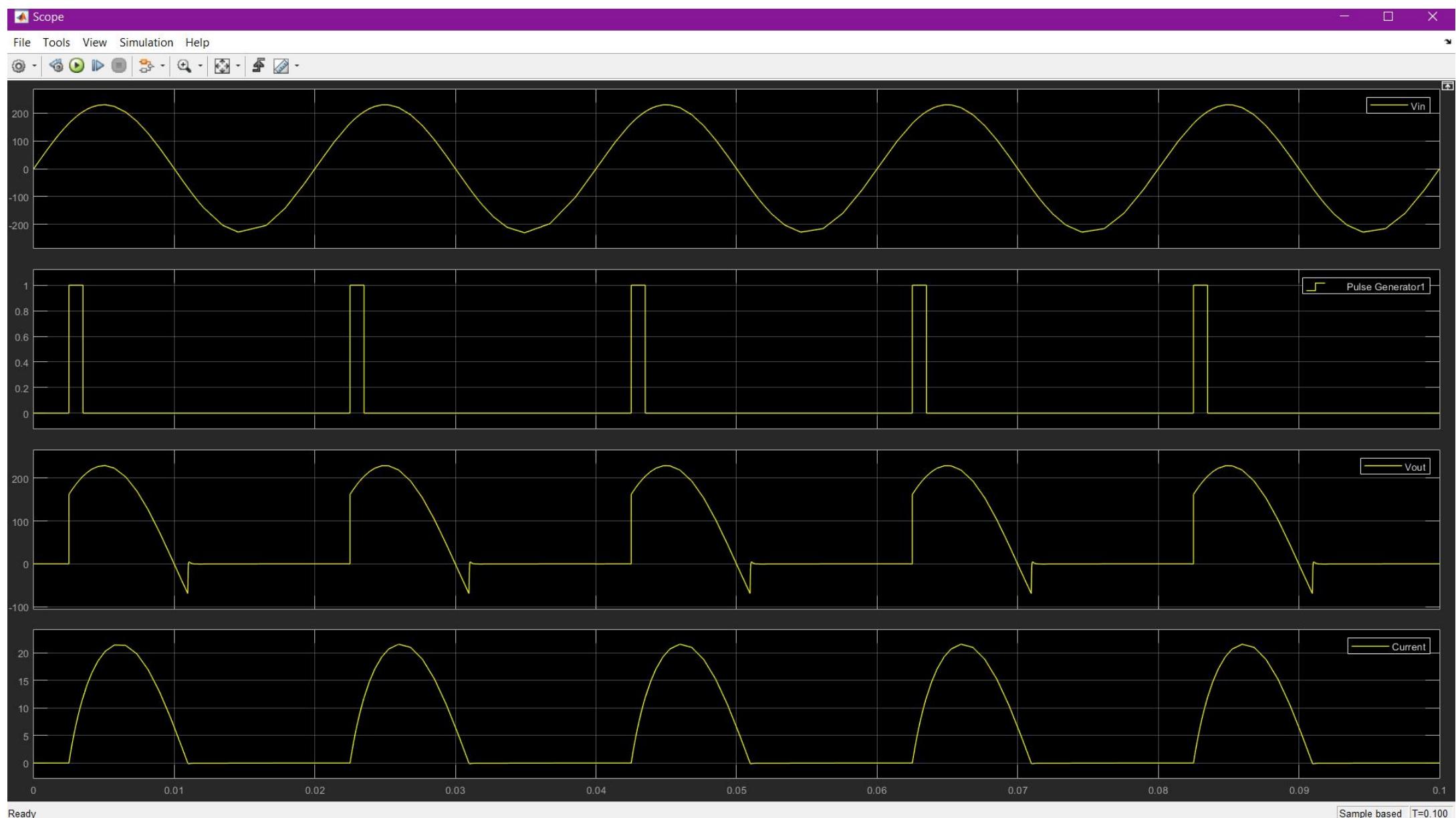
1. Make the required circuit in SIMULINK in MATLAB.
2. Simulate the circuit for 1 seconds.
3. Observe the waveform from scope.

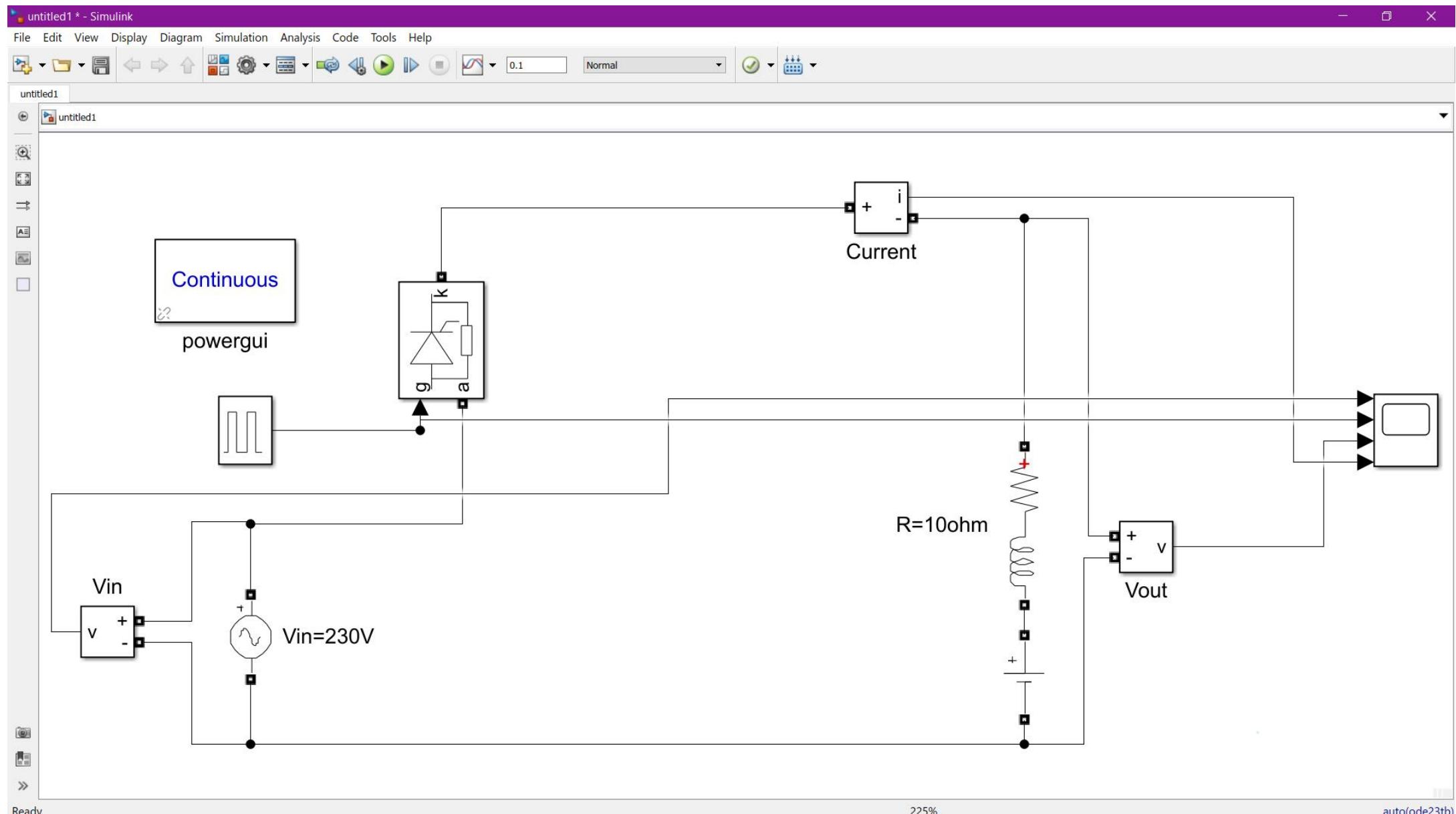
MATLAB Simulation

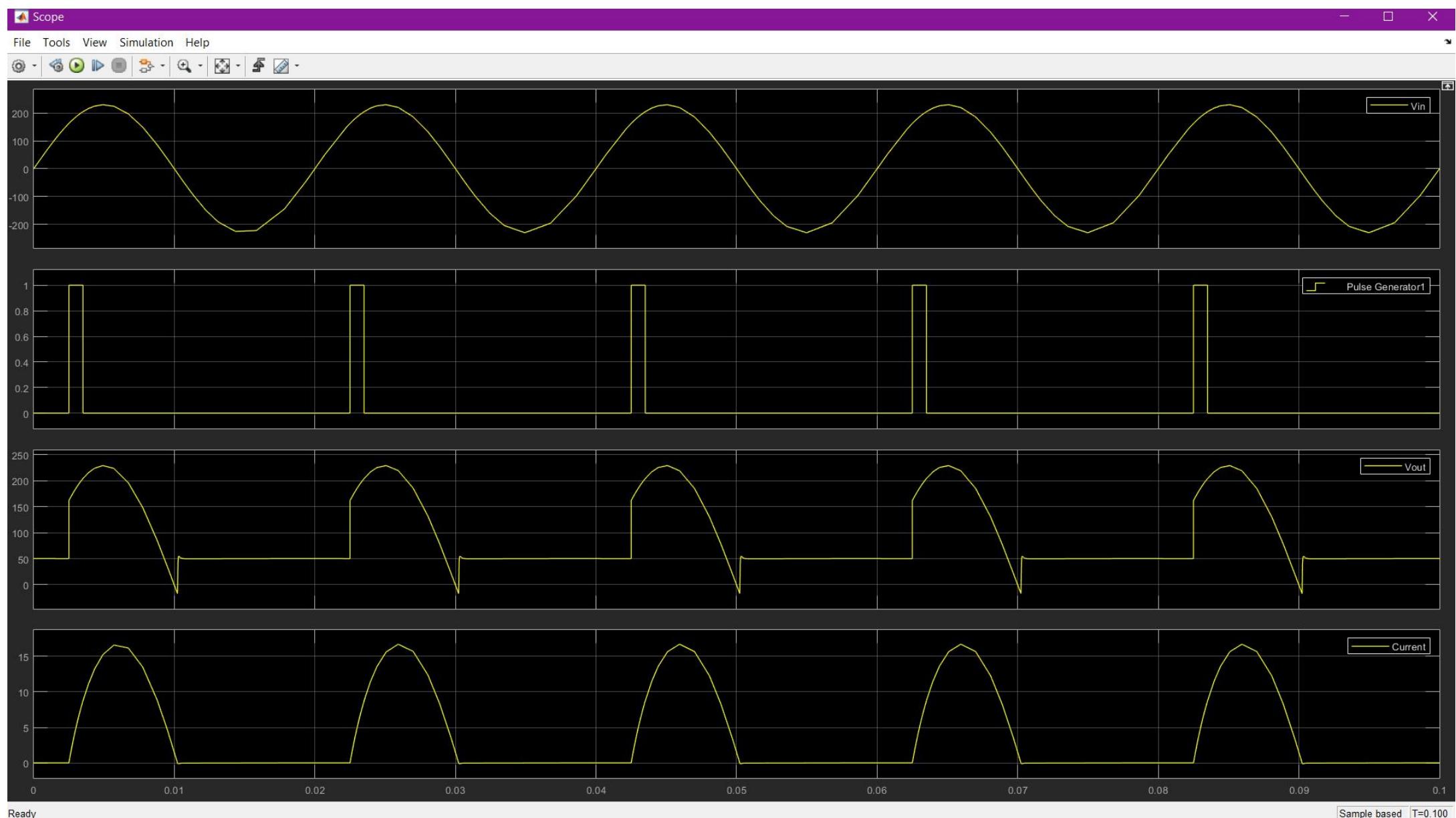


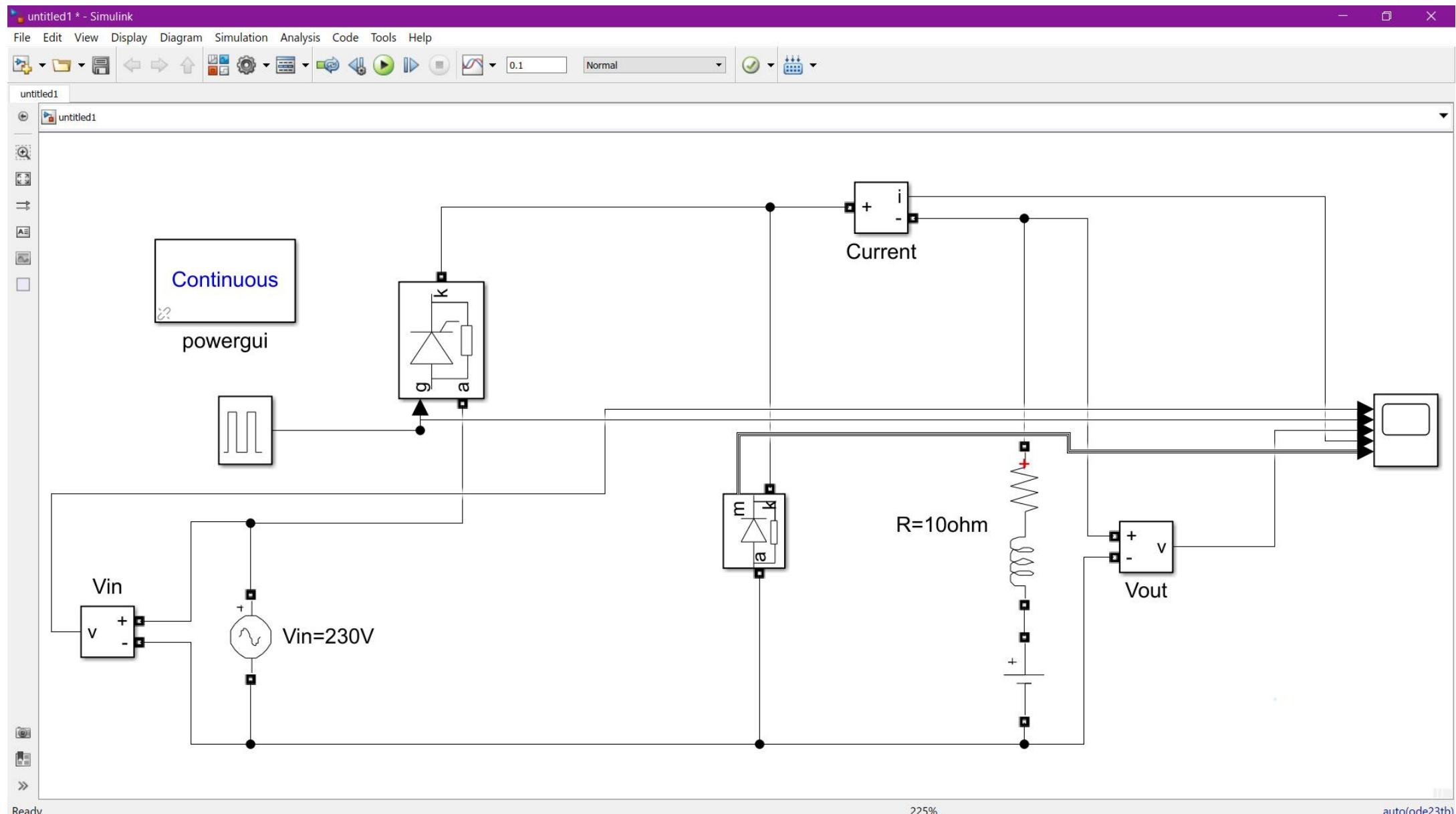














- * Result: Simulated the single-phase half wave controlled rectifier for R_i , RL , RLE and with free wheeling diode by using MATLAB SIMULINK.
- * Precautions:
 1. Use powergui to store the equipment equivalent simulink circuit that represents the state-space equations of the model.
 2. Always use closed circuit, never leave wire open.
 3. MATLAB takes time to respond, do not give multiple command at once.

Experiment - 5

* Aim: Simulate of single phase full wave controlled rectifier for R, RL, RLE and also use freewheeling diode by using MATLAB-Simulink.

* Requirement: MATLAB-Simulink

* Theory:

The figure shows a fully controlled bridge rectifier, which uses four thyristors to control the average load voltage.

Thyristors T_1 & T_2 must be fired simultaneously during the positive half wave of the source voltage V_s to allow conduction of current. To ensure simultaneous firing, thyristors T_1 & T_2 use the same firing signal.

Alternatively, thyristors T_3 and T_4 must be fired simultaneously during the negative half wave of the source voltage.

→ Average values.

$$V_{dc} = V_o = \frac{1}{\pi} \int_{\alpha}^{\pi} V_m \sin(\omega t) d(\omega t)$$
$$= \frac{V_m}{\pi} (1 + \cos \alpha)$$

$$I_{dc} = \frac{V_{dc}}{R} = \frac{V_m}{\pi R} (1 + \cos \alpha)$$

→ RMS Values

$$V_{rms} = \sqrt{\frac{1}{\pi} \int_{\alpha}^{\pi} (V_m \sin \omega t)^2 d\omega t}$$

* Diagram:

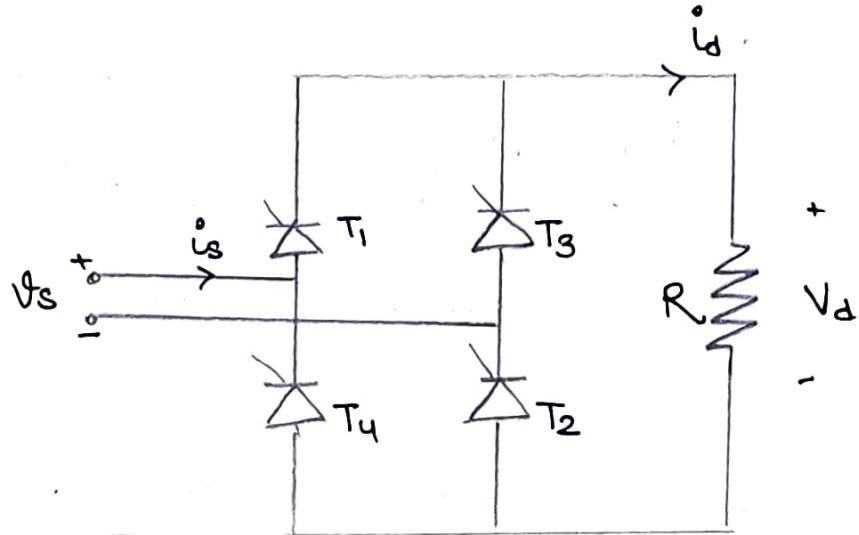


Figure 5.1: Circuit diagram of 1 ϕ full wave controlled rectifier.

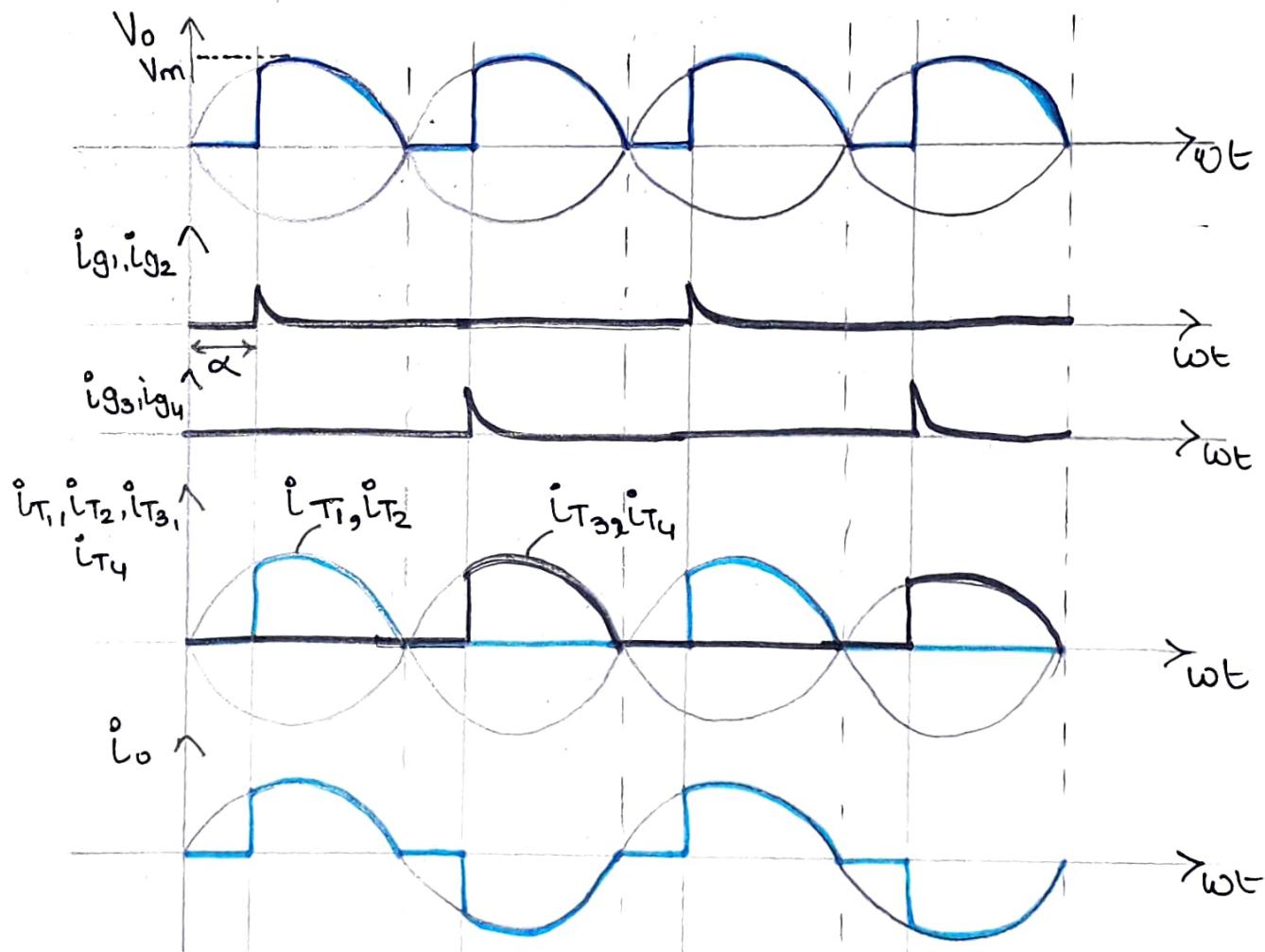


Figure 5.2: Waveform of 1 ϕ full wave controlled rectifier

$$= V_m \sqrt{\frac{1}{2} - \frac{\alpha}{2\pi} + \frac{\sin(2\alpha)}{4\pi}}$$

$$I_{rms} = \frac{V_{rms}}{R} = \frac{V_m}{R} \sqrt{\frac{1}{2} - \frac{\alpha}{2\pi} + \frac{\sin(2\alpha)}{4\pi}}$$

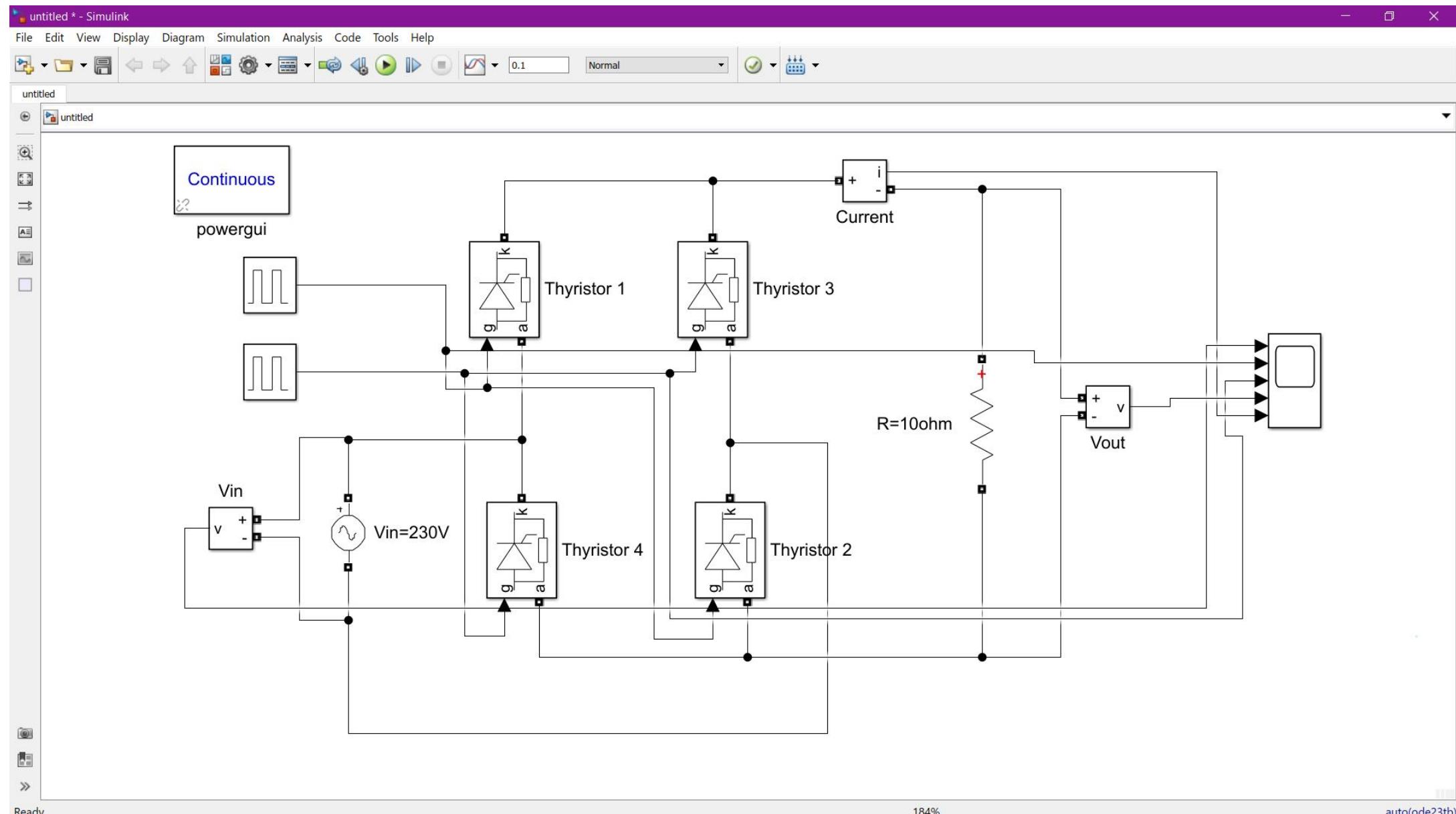
— ~~Re~~ Power delivered

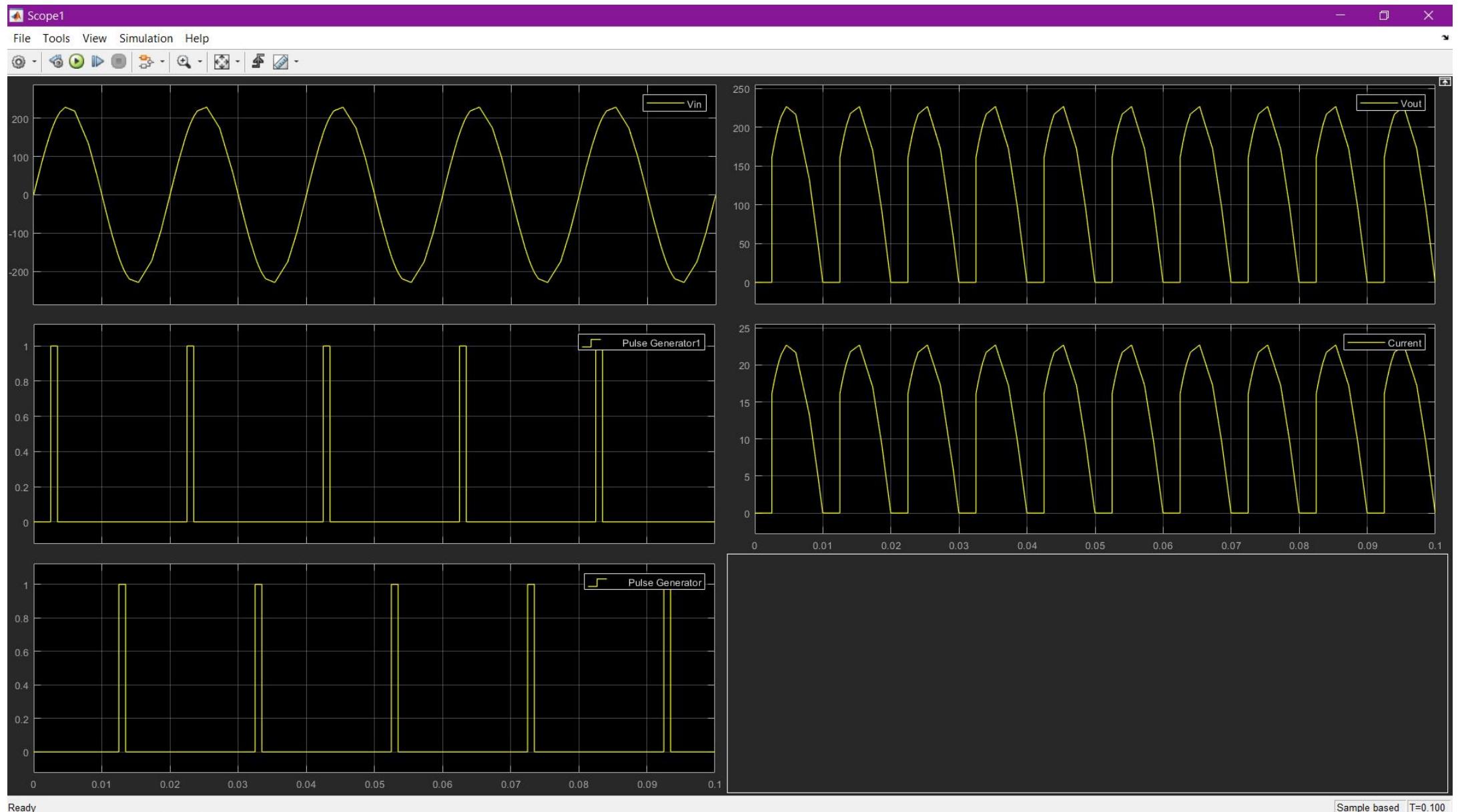
$$P = I_{rms}^2 R$$

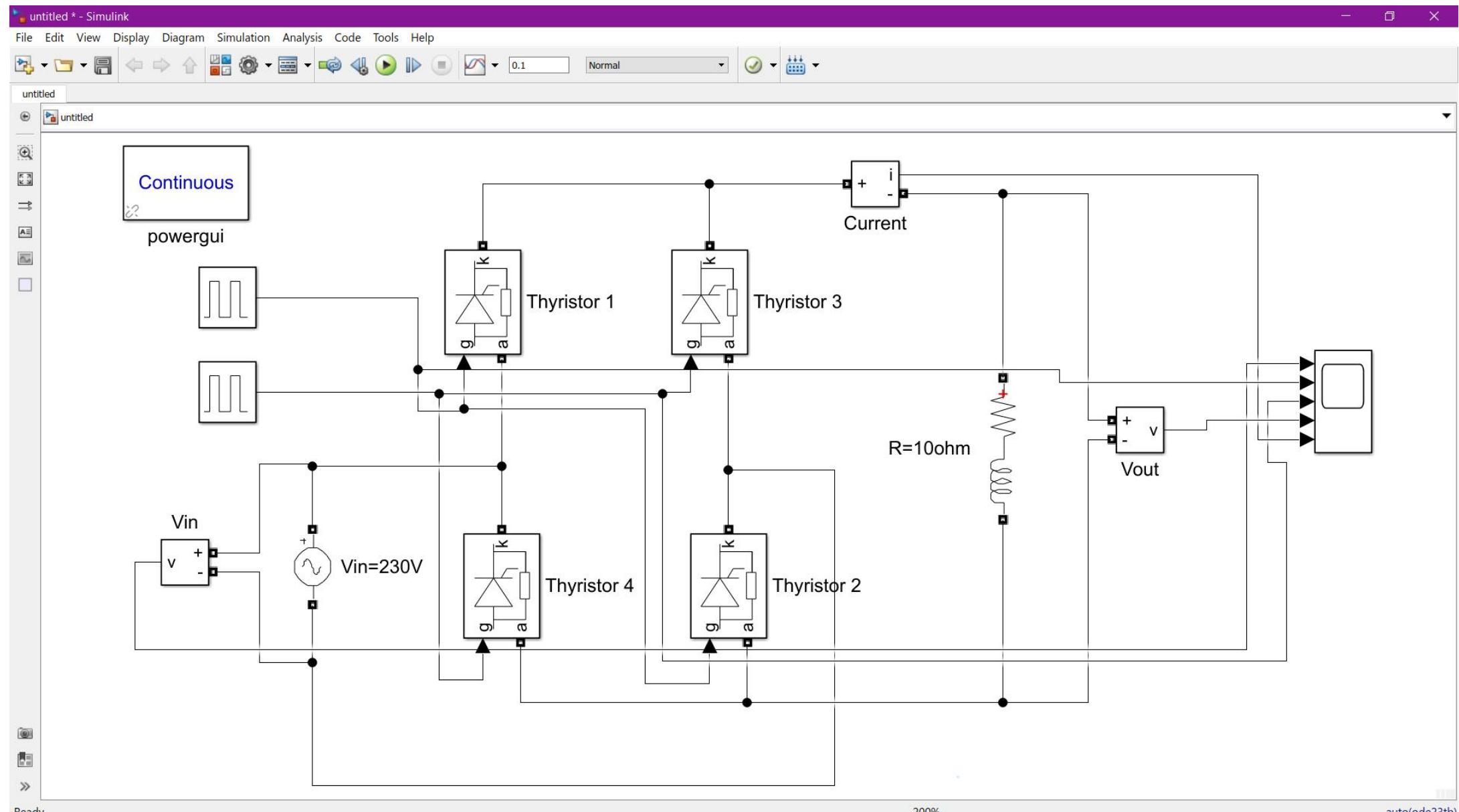
* Procedure:

1. Make the required circuit in SIMULINK in MATLAB.
2. Simulate the circuit for 1 seconds.
3. Observe the waveform from the scope.

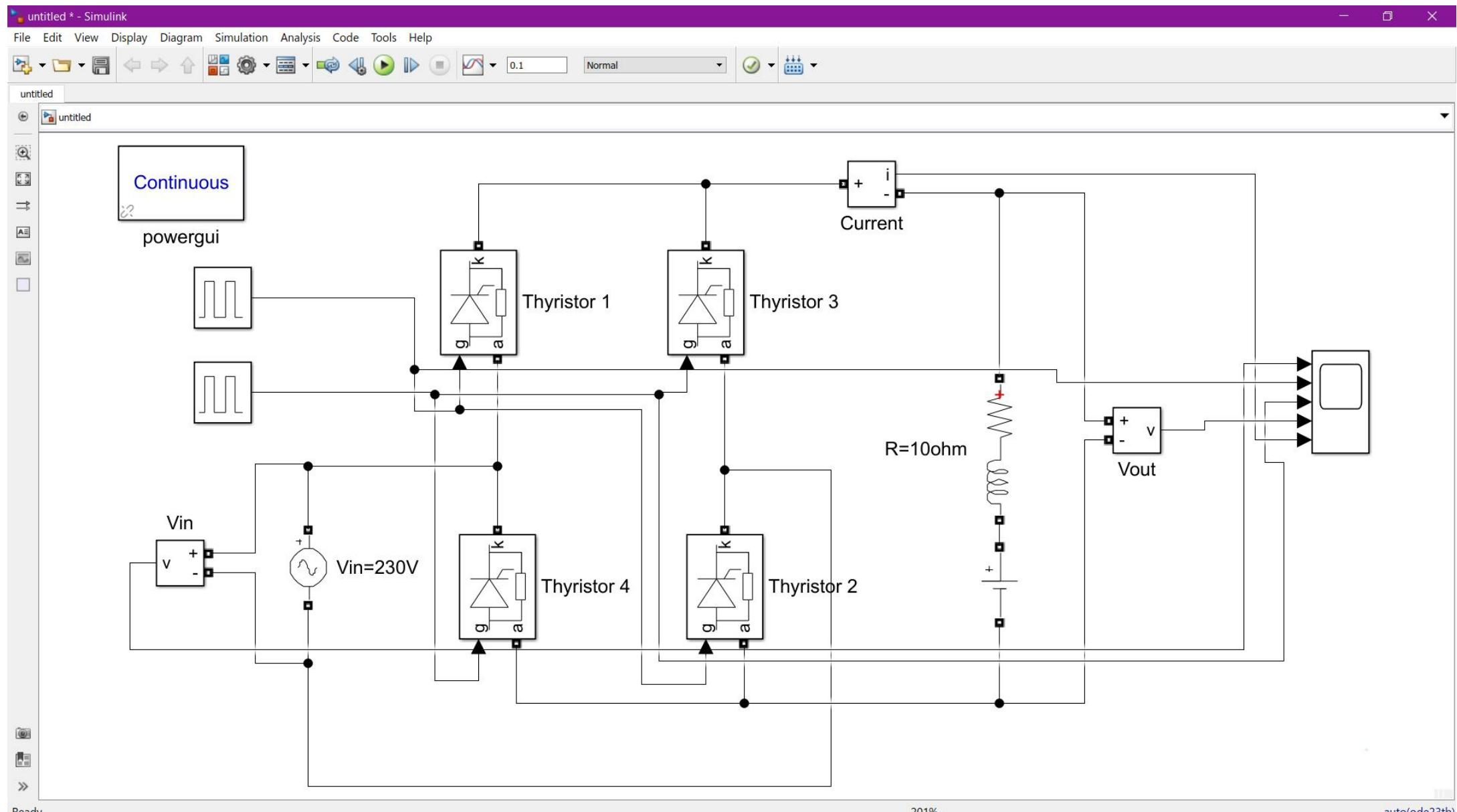
MATLAB Simulation

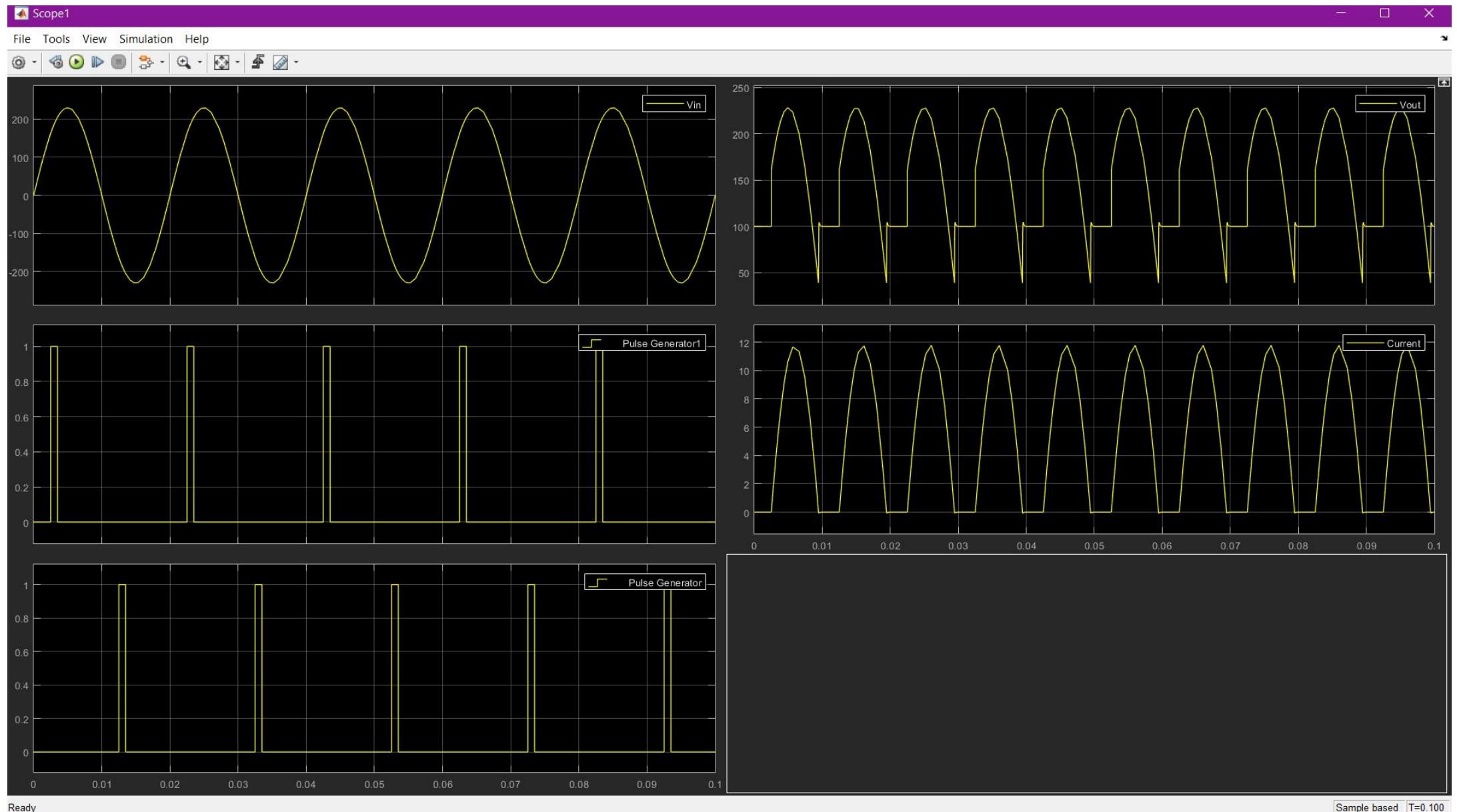


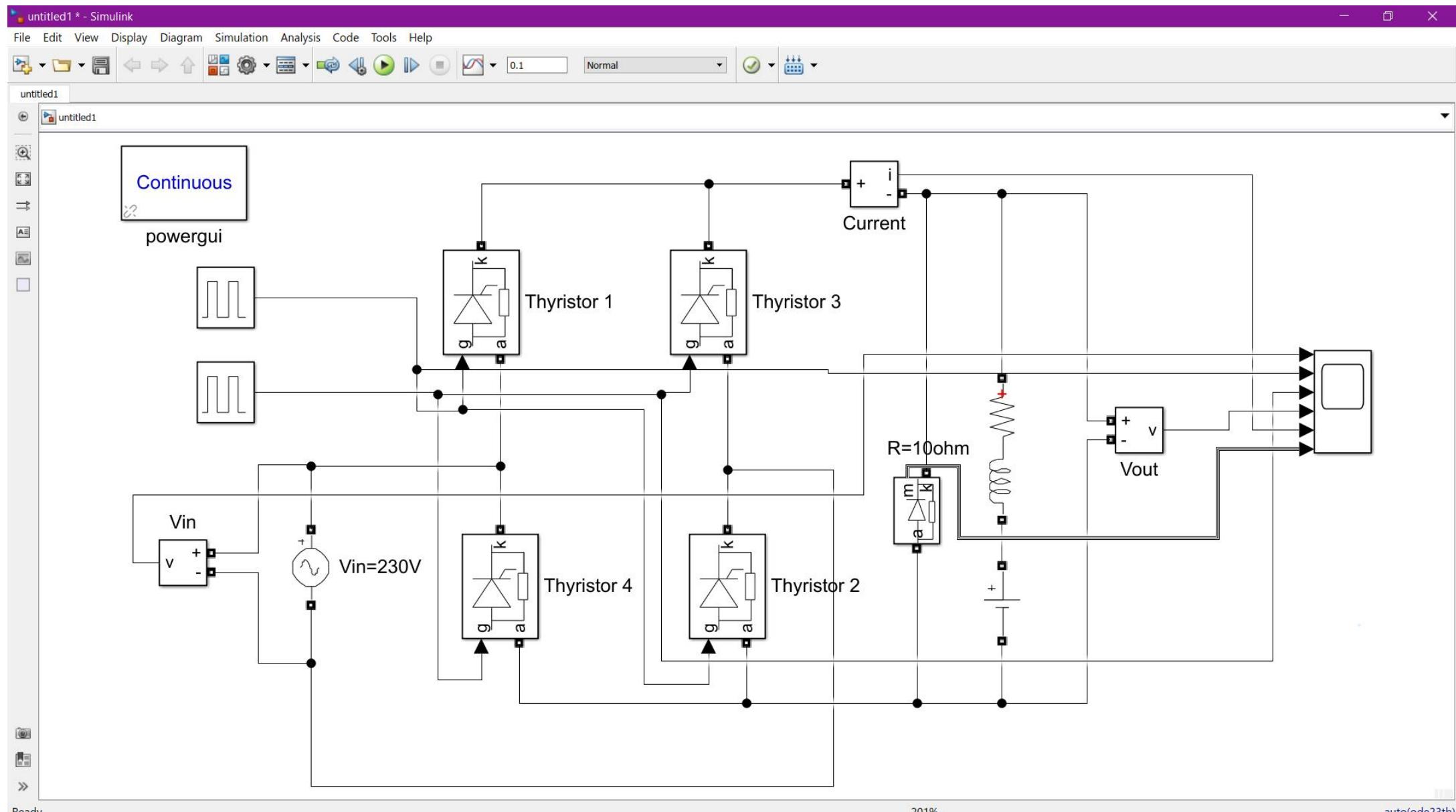


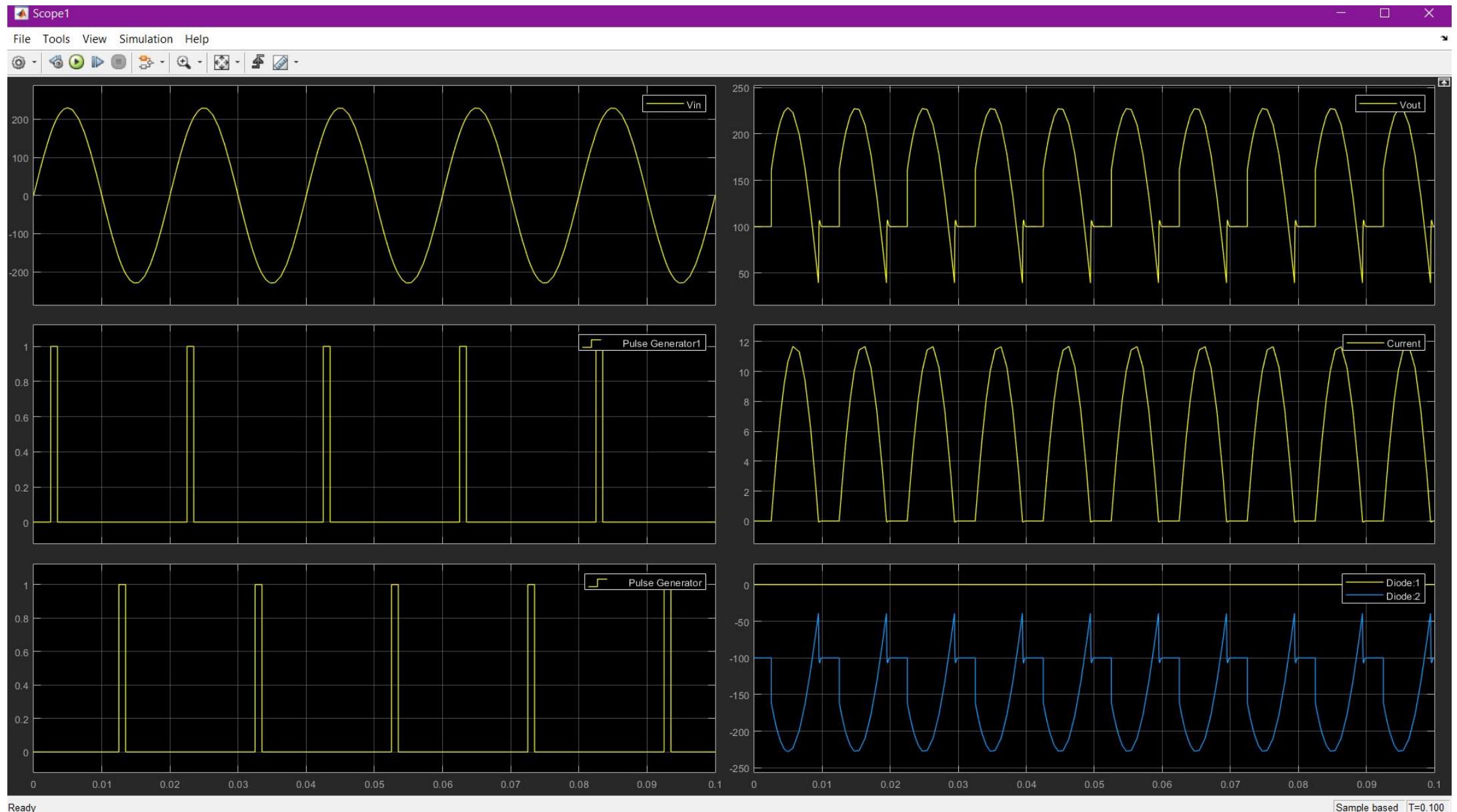












* Result: Simulated single phase full wave controlled rectifier for R, RL & RLC and free wheeling diode by using MATLAB- simulink.

* Precautions:

1. Use powergui to store the equivalent simulink circuit that represents the state-space equation of the model.
2. Always use closed circuit, never leave wire open.
3. MATLAB takes time to respond, do not give multiple command at once.

Experiment - 6

- * Aim: To simulate the three phase full-wave controlled rectifier for R, RL, RLC and use free wheeling diode by using MATLAB-Simulink.
- * Requirement: MATLAB - Simulink
- * Theory: Three phase full wave controlled rectifier is fully controlled bridge controlled rectifier using six thyristors connected in the form of a full wave bridge configuration. All the six thyristor are controlled switches which are turned on at a appropriate times by applying suitable gate trigger signals.
 - Three thyristors T_1, T_3 and T_5 & T_2, T_4 and T_6 will not work together at the same time.
 - Each thyristor is triggered at an interval of $2\pi/3$.
 - Each pair $T_1 \& T_6, T_1 \& T_2, T_2 \& T_3, T_3 \& T_4, T_4 \& T_5, T_5 \& T_6$ is triggered at an interval of $\pi/3$.
 - T is triggered at
 - $T_1 = 30 + \alpha$
 - $T_3 = 30 + \alpha + 120$
 - $T_5 = 30 + \alpha + 240$
 - $T_2 = 30 + \alpha + 240 + 180$
 - $T_4 = 30 + \alpha + 180$
 - $T_6 = 30 + \alpha + 120 + 180$

* Diagram:

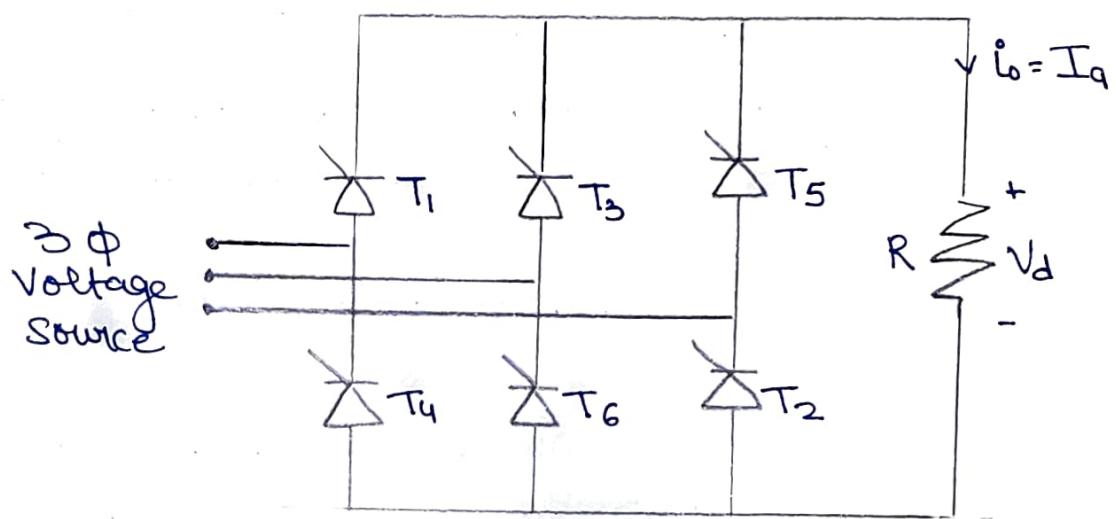


Figure 6.1: Circuit diagram of 3φ full wave rectifier.

→ Average value

$$V_{an} = V_m \sin(\omega t)$$

$$V_{bn} = V_m \sin(\omega t - 2\pi/3)$$

$$V_{cn} = V_m \sin(\omega t - 4\pi/3)$$

$$\Rightarrow V_{ab} = \sqrt{3} V_m \sin(\omega t + \frac{\pi}{6})$$

$$V_{bc} = \sqrt{3} V_m \sin(\omega t - \frac{\pi}{2})$$

$$V_{ca} = \sqrt{3} V_m \sin(\omega t - \frac{7\pi}{6})$$

$$V_{dc} = \frac{3\sqrt{3} V_m}{\pi} \cos \alpha$$

$$I_{dc} = \frac{3\sqrt{3} V_m}{\pi R} \cos \alpha$$

→ RMS Value

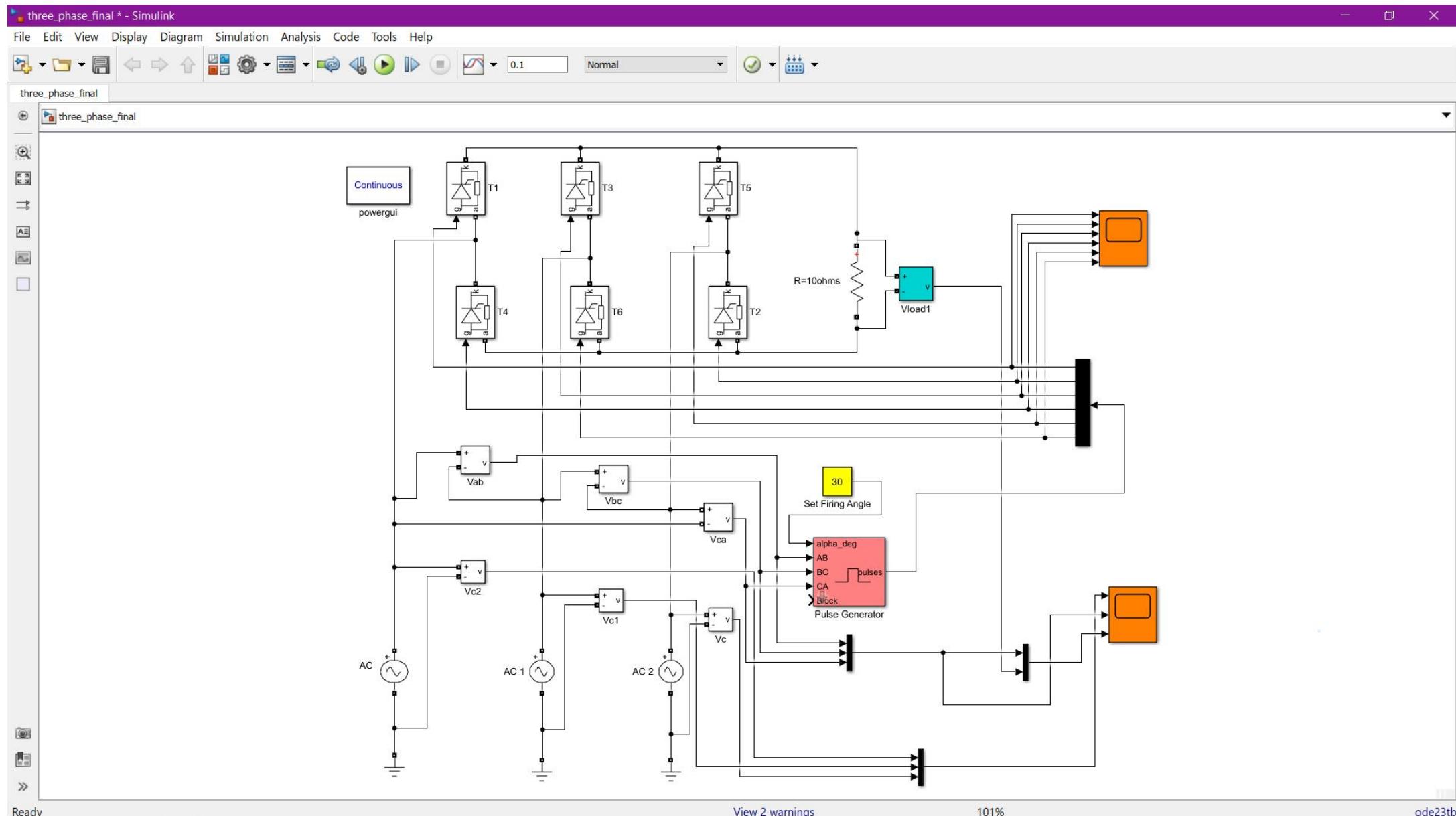
$$V_{rms} = \sqrt{3} V_m \sqrt{\frac{1}{2} + \frac{3\sqrt{3}}{4\pi} \cos 2\alpha}$$

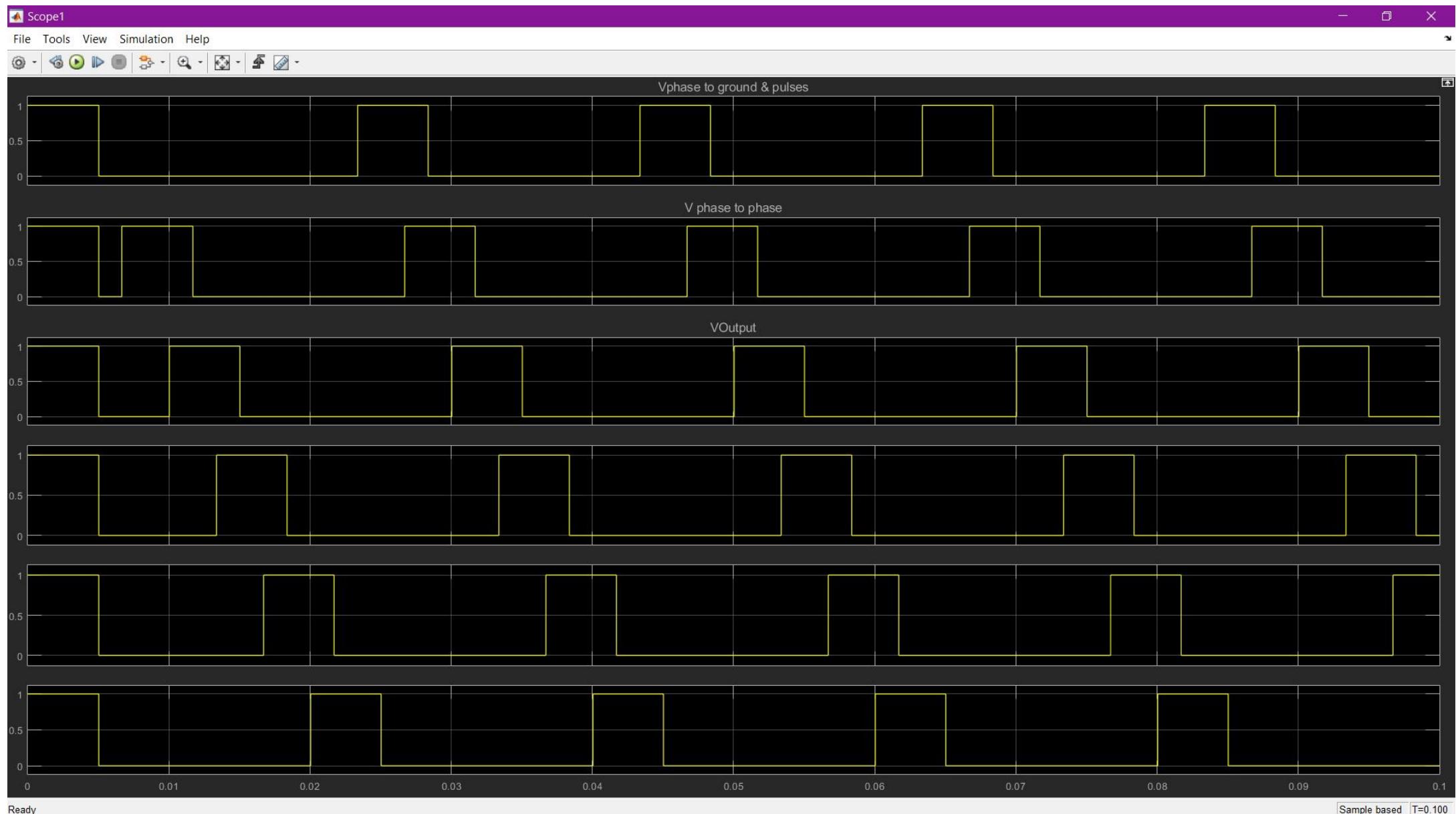
$$I_{rms} = \frac{V_{rms}}{\sqrt{R^2 + (\omega L)^2}}$$

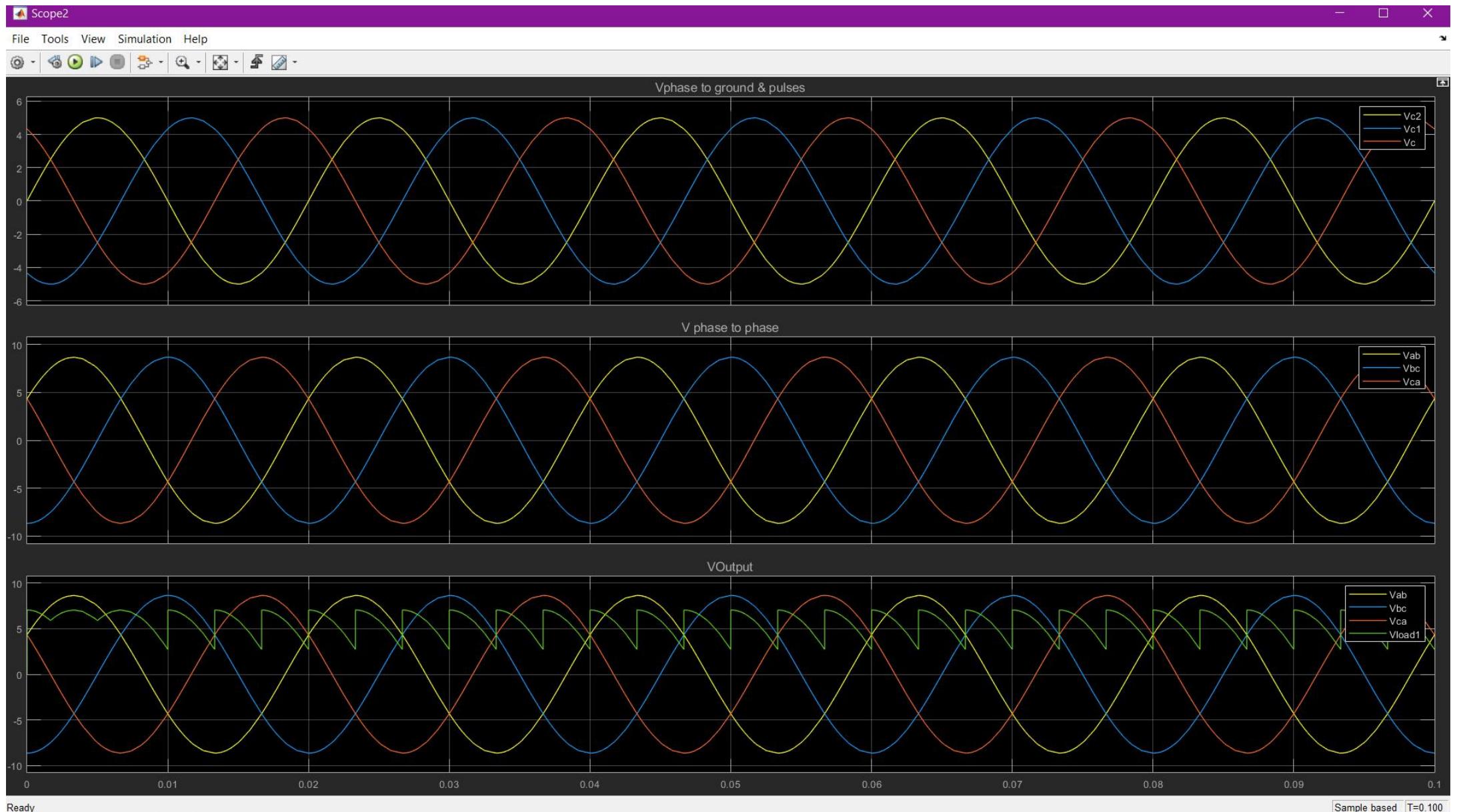
* Procedure:

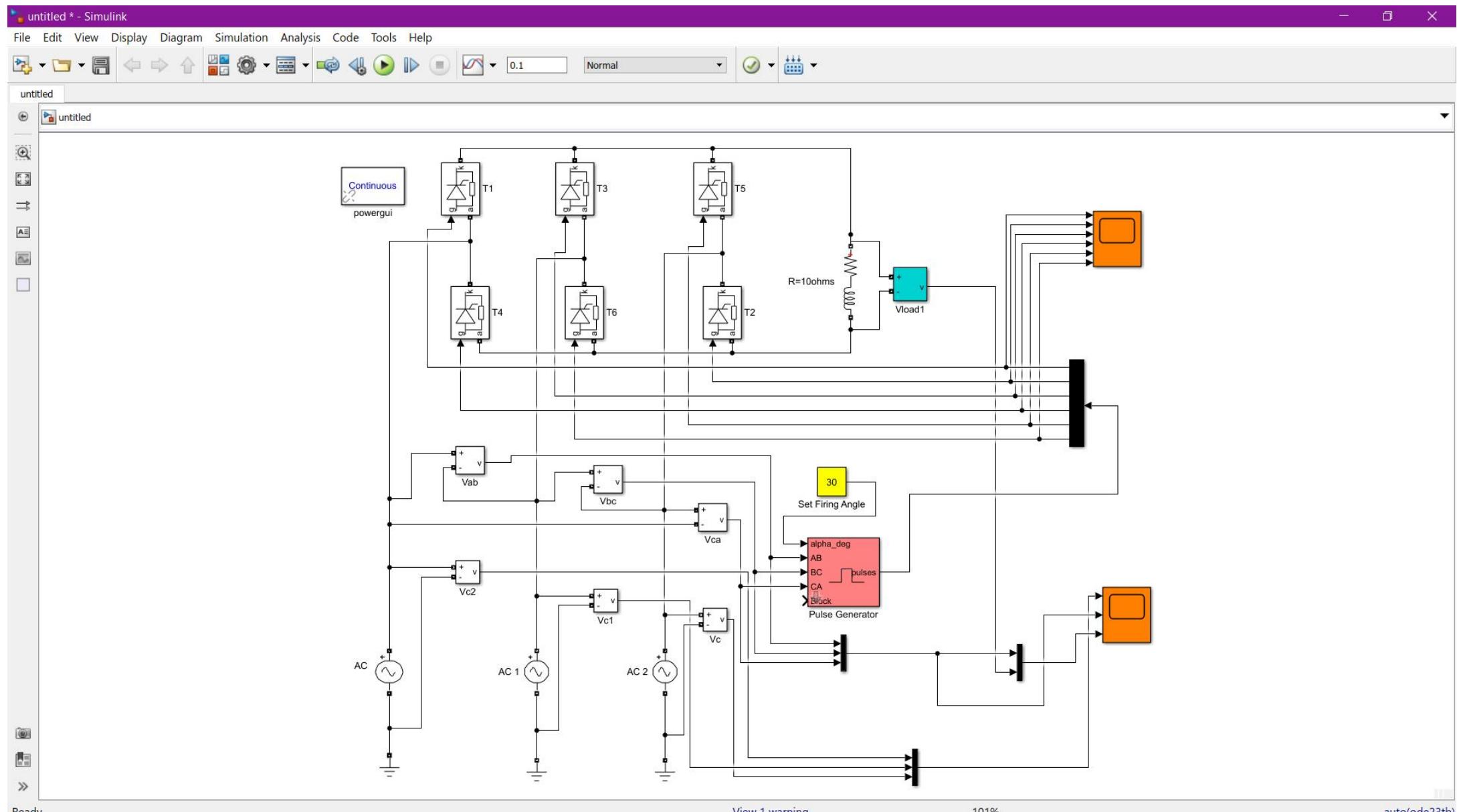
1. Make the required circuit in SIMULINK in MATLAB.
2. Simulate the circuit for 1 second.
3. Observe the waveform from the scope.

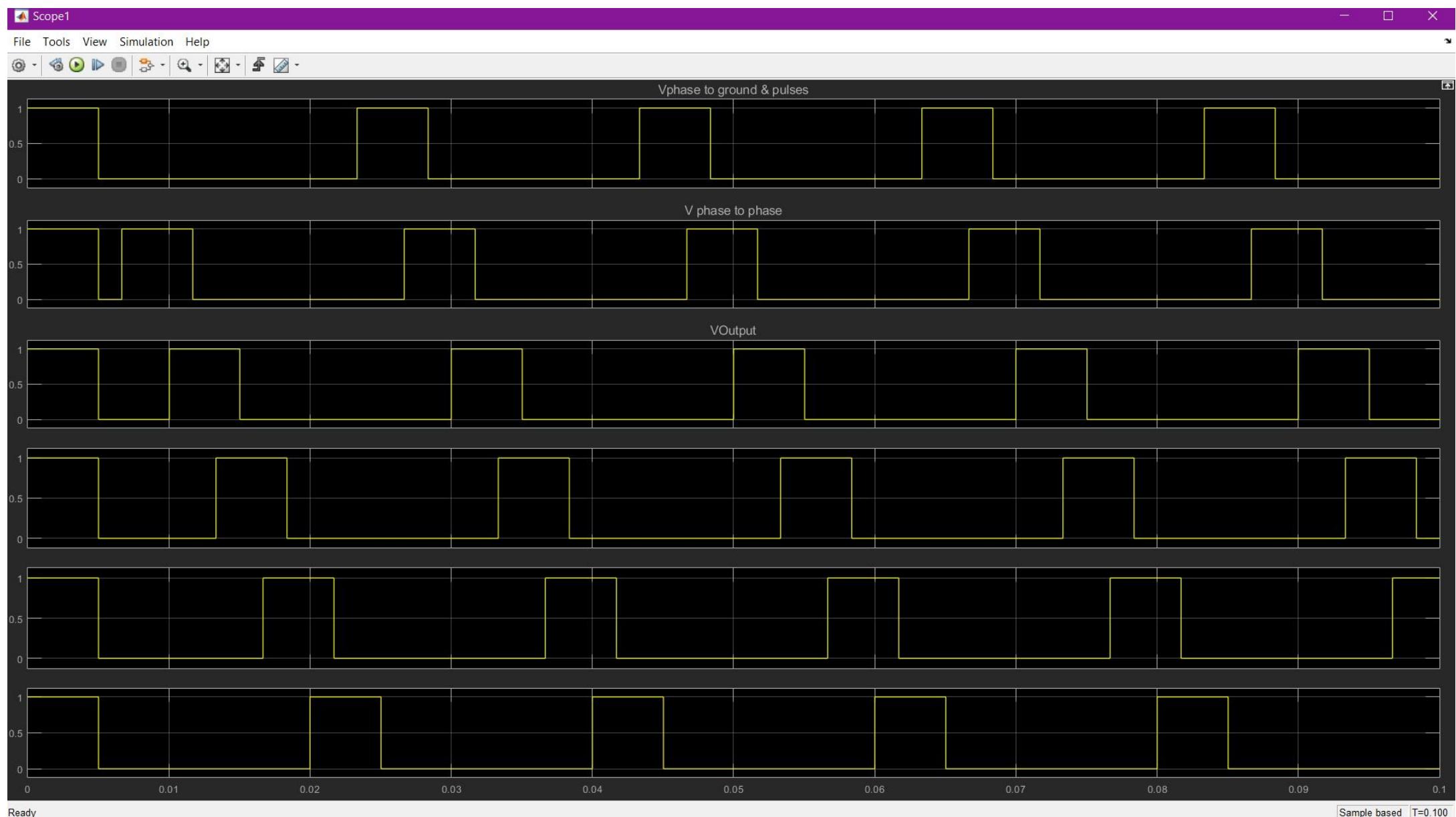
MATLAB Simulation

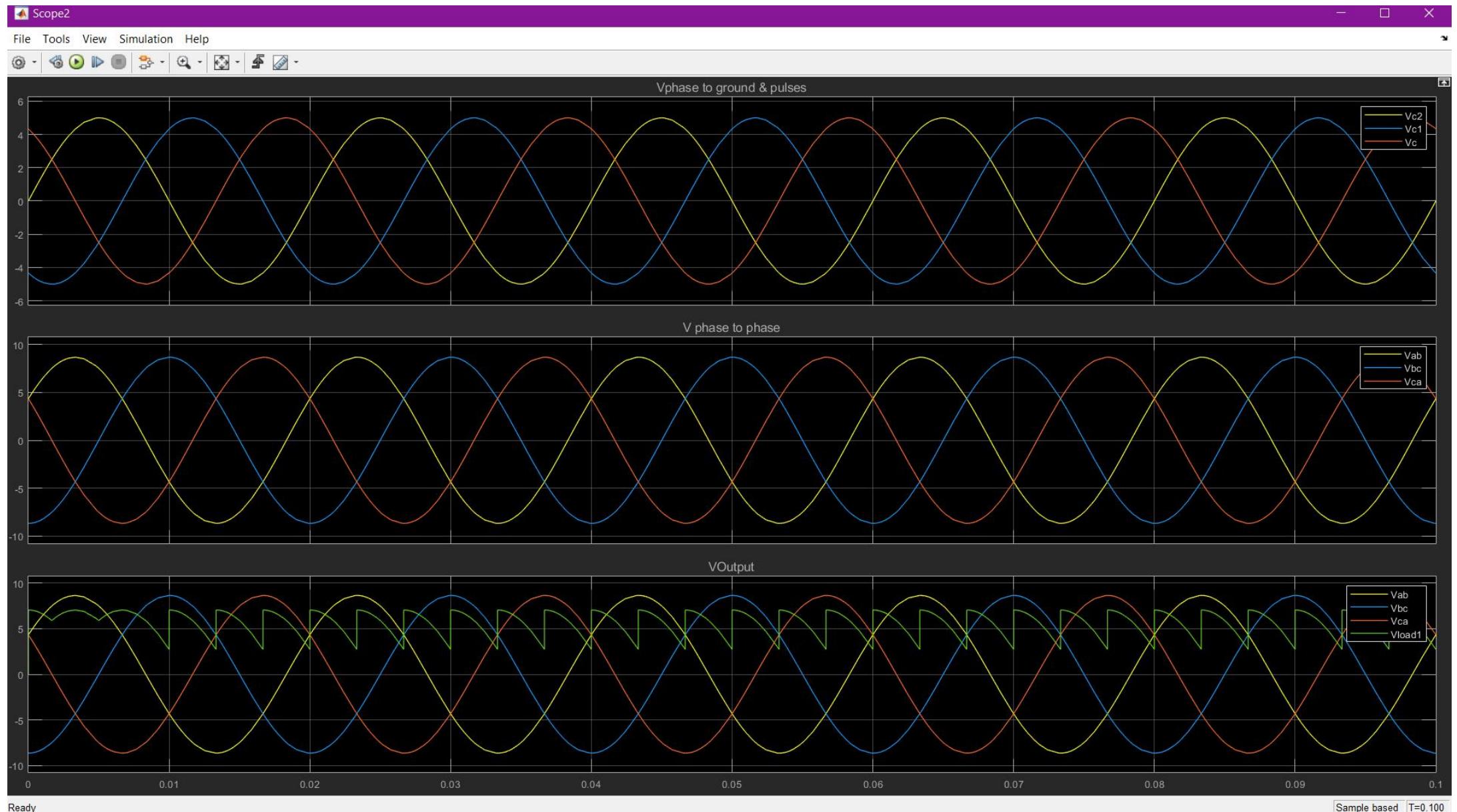


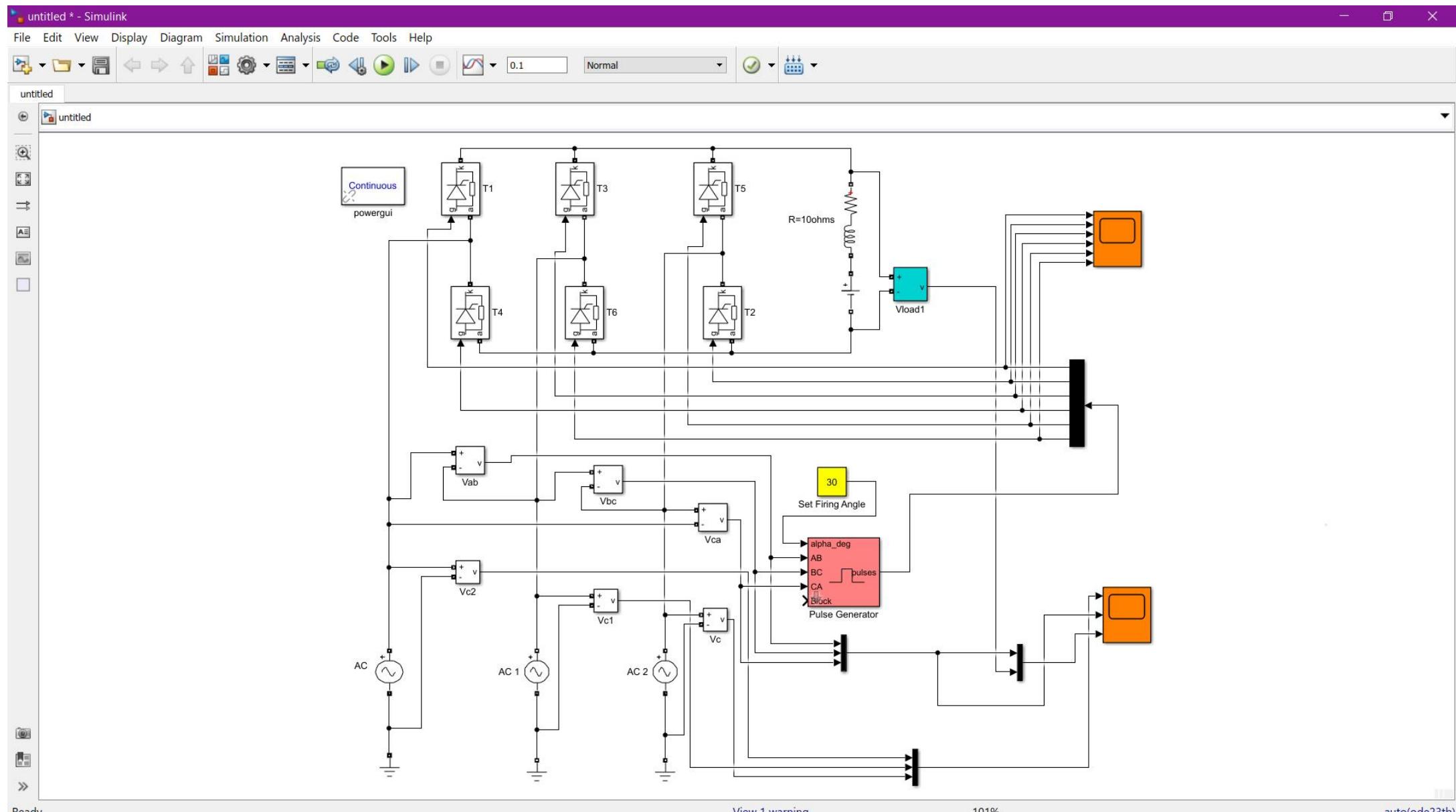


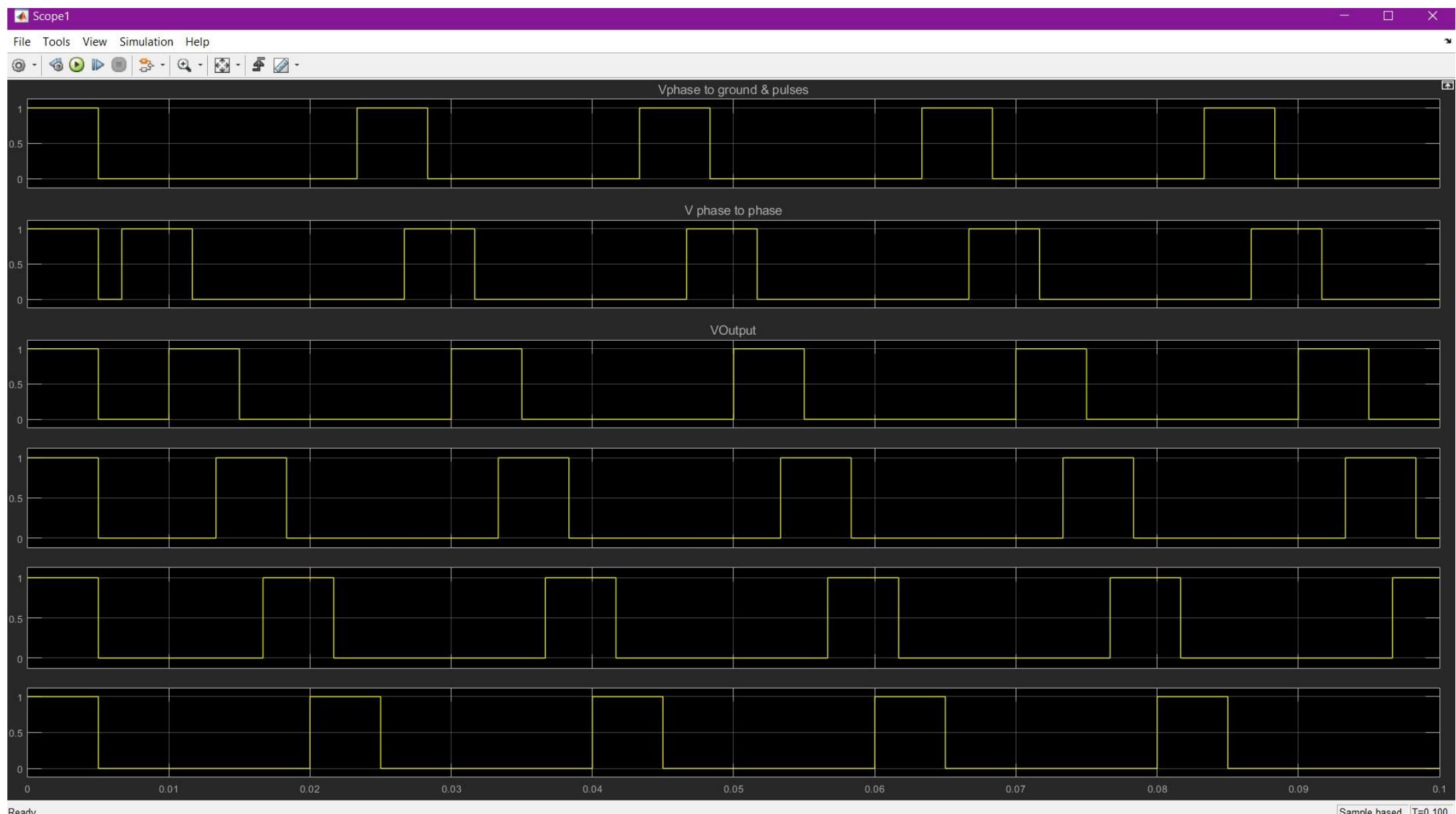


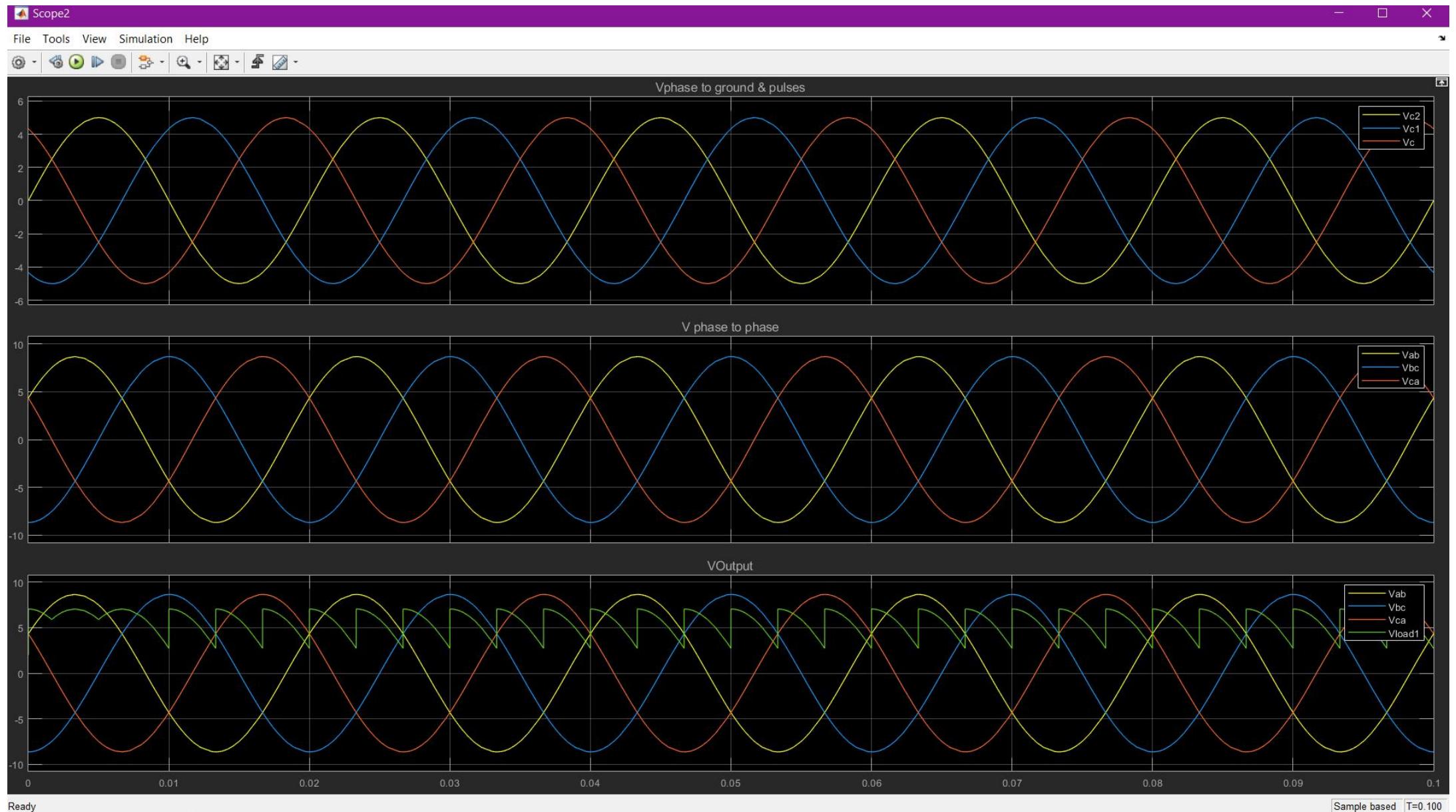


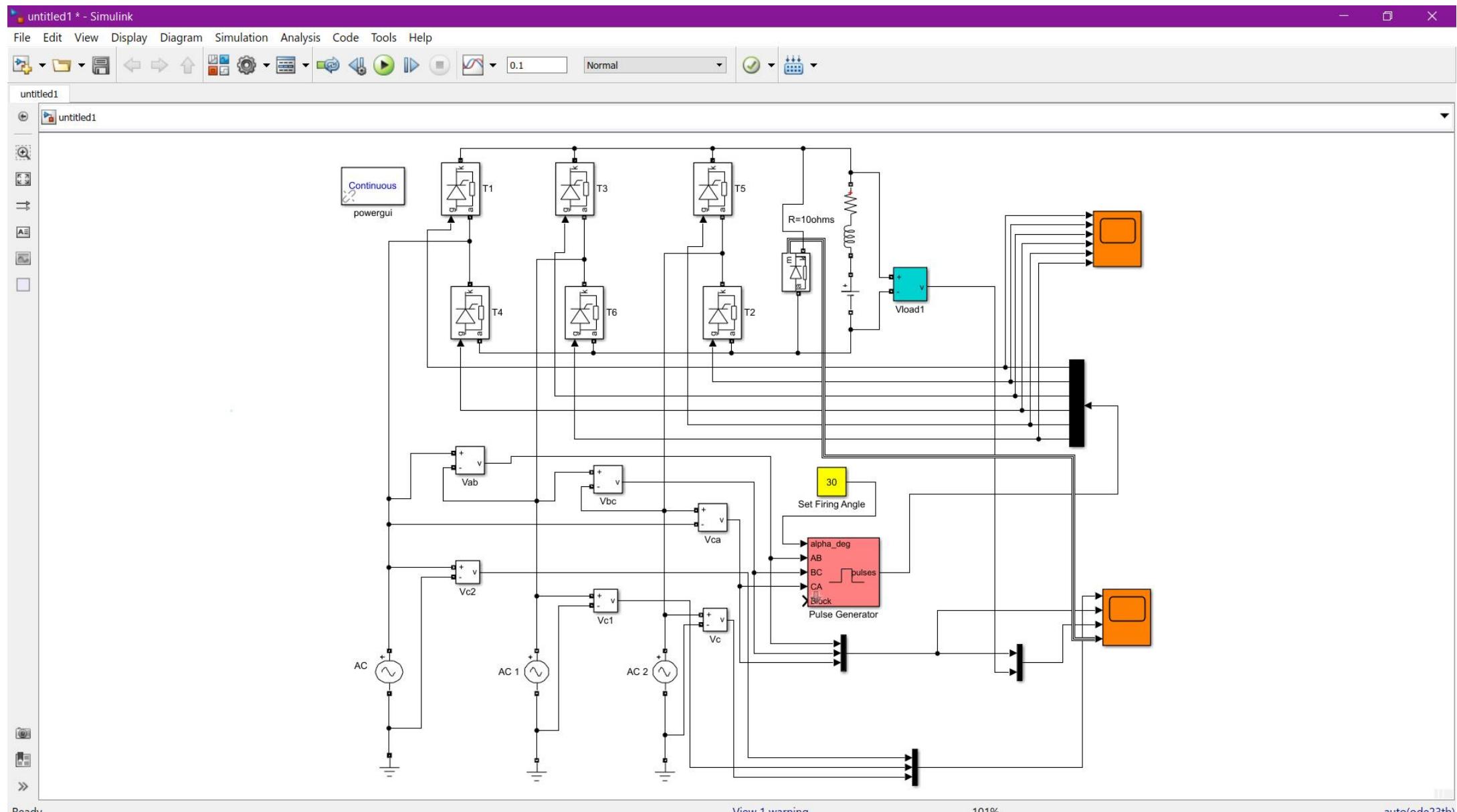


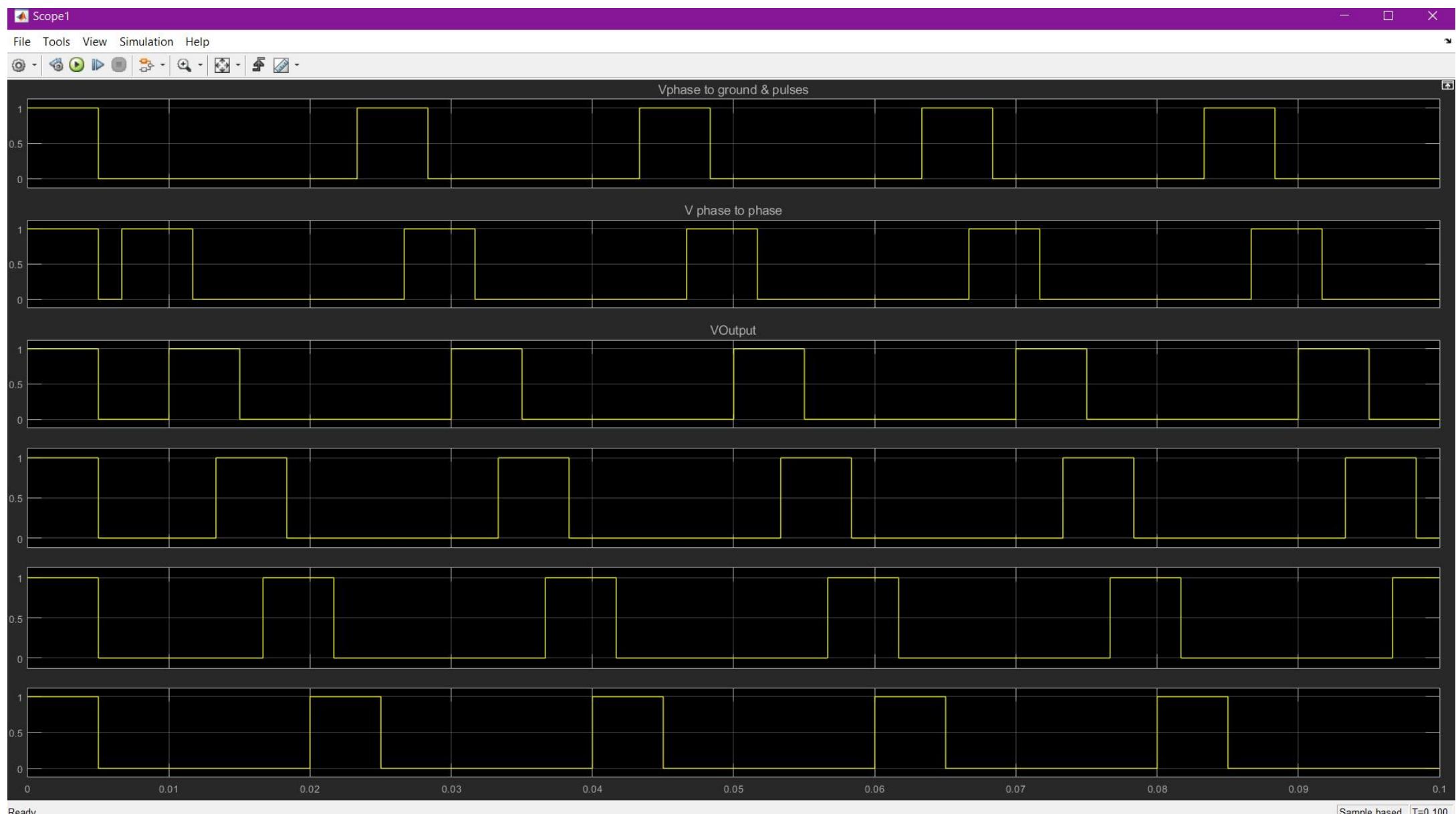


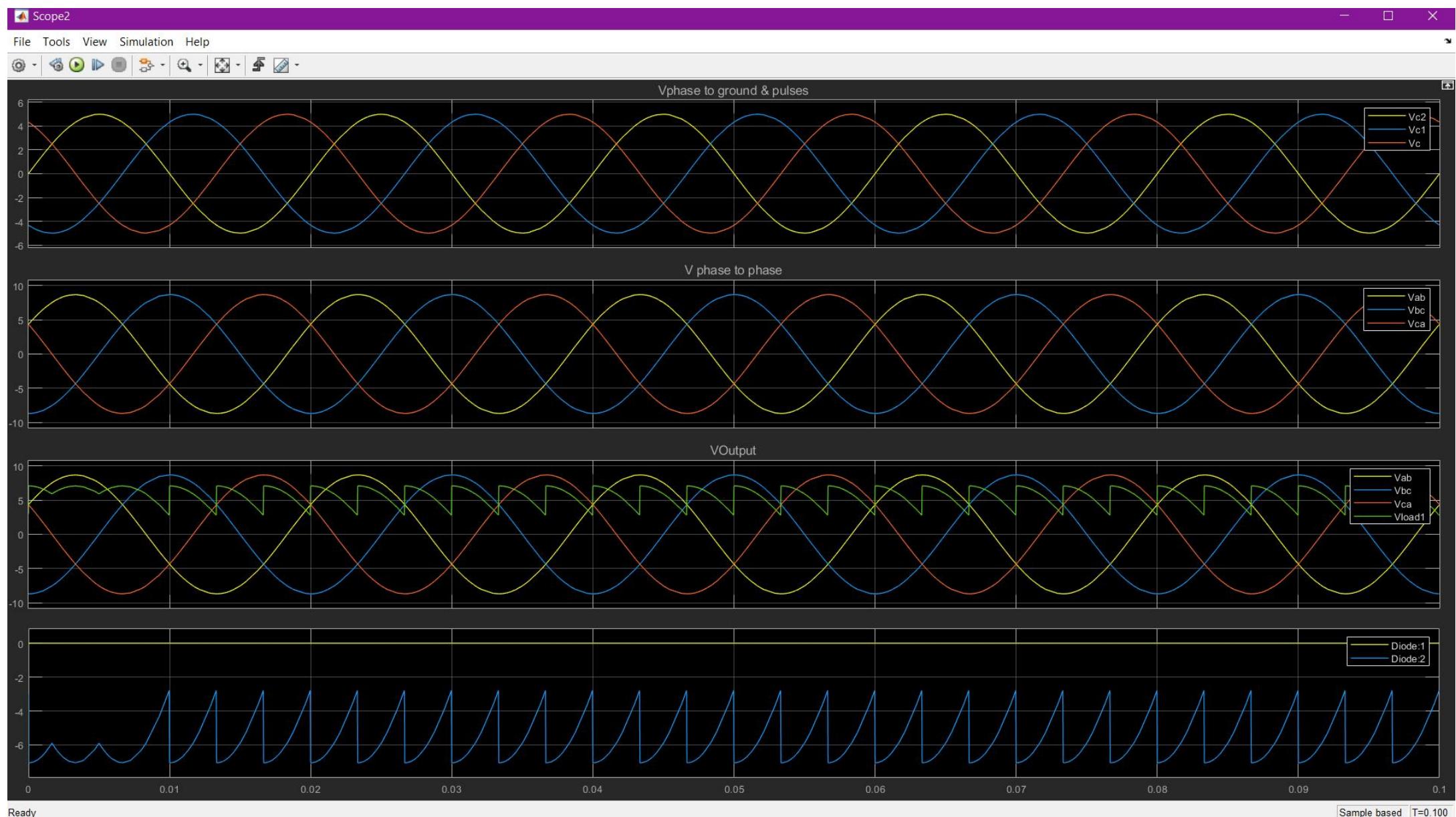












* Result: Simulated the three phase full-wave controlled rectifier for R, RL, RLE and use free wheeling diode by using MATLAB-Simulink.

* Precautions:

1. Use powergui to store the equivalent simulink circuit that represents the state-space equation of the model.
2. Always use closed circuit, never leave wire open.
3. MATLAB takes time to respond, do not give multiple command at once.

Experiment - 7

- * Aim: Simulate step up and step down chopper for R, RL and RLC load by using MATLAB simulink.
- * Requirement: MATLAB-Simulink
- * Theory: A chopper uses high speed to connect and disconnect from a source load. A fixed DC voltage is applied intermittently to the source load by continuously triggering the power switch ON/OFF.
 - Step up chopper
Also known as Boost converter. At the average voltage (V_o) in a step up chopper is greater than the voltage input (V_s). The figure below shows a configuration of a step up chopper.
 - The average output voltage is positive when chopper is switched ON and negative when the chopper is OFF.
 - T_{ON} - time interval when chopper is ON
 - T_{OFF} - time interval when chopper is OFF
 - V_L - Load voltage
 - V_s - source voltage
 - T - chopping time period = $T_{ON} + T_{OFF}$

* Diagram:

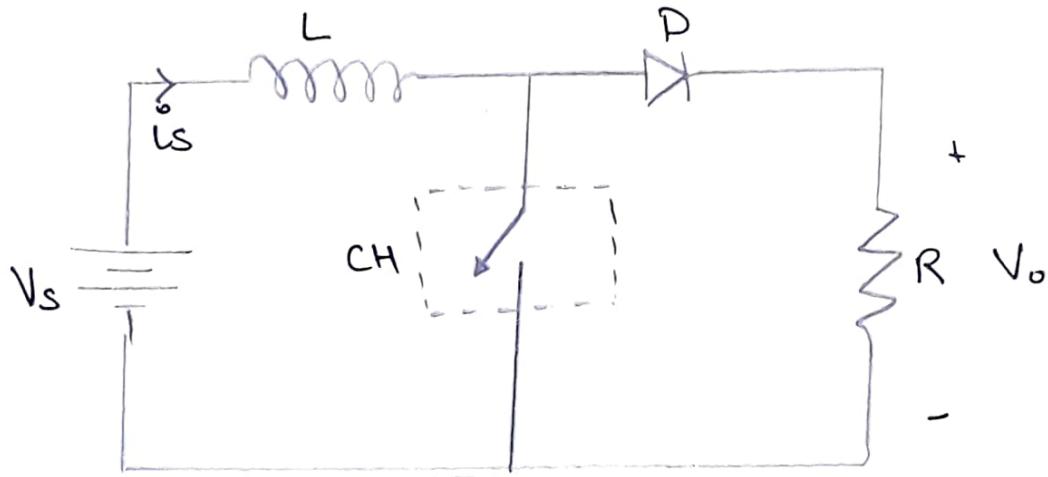


Figure 7.1: Circuit diagram of step-up chopper

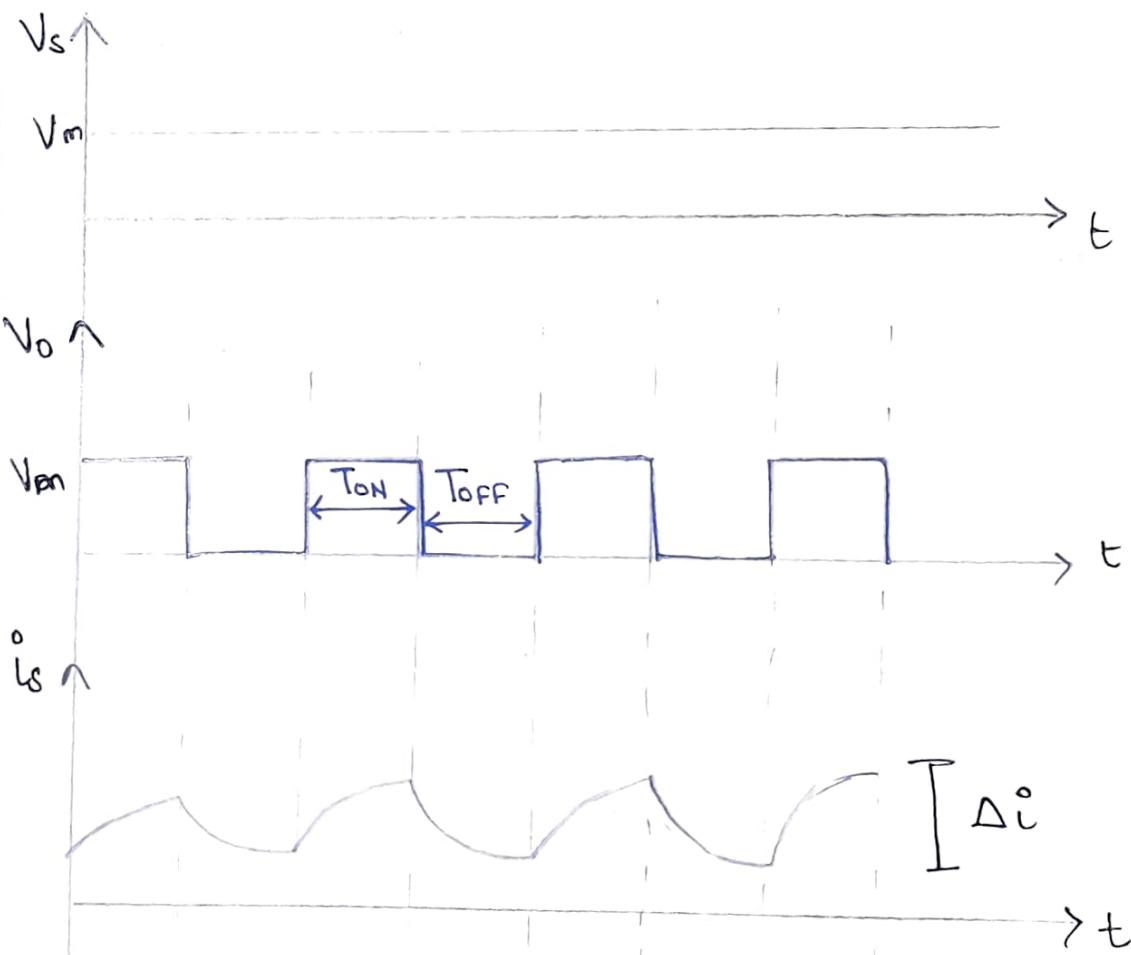


Figure 7.2: Waveform of Step up chopper

Average voltage output

$$V_o = \frac{V_s}{1-D}$$

$$D = \frac{T+T_{ON}}{T}$$

The equation proves that the output voltage will always be more than the voltage ~~as~~ input and hence, it boosts up or increases the voltage level.

Step down Chopper

Also known as buck converter. In this, the average voltage output V_o is less than the input voltage V_s .

When chopper is ON, $V_o = V_s$ and when the chopper is off, $V_o = 0$.

when chopper is ON

$$V_s = (V_L + V_o) \quad L \frac{di}{dt} = V_s - V_o$$

$$V_L = V_s - V_o \quad L \frac{\Delta i}{T_{ON}} = V_s + V_o$$

Thus, peak-to-peak current load is given by

$$\Delta i = \frac{V_s - V_o}{L} T_{ON}$$

Where FD is free-wheel diode, When chopper is OFF, polarity reversal and discharging occurs at the inductor.

Average voltage output

$$V_o = DV_s$$

$$D = \frac{T_{ON}}{T}$$

* Diagram:

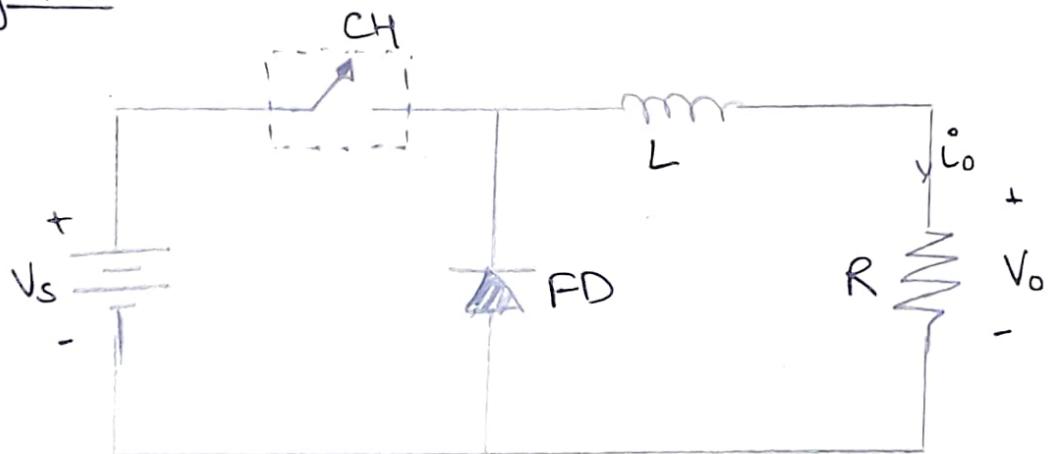


Figure 7.3: Circuit diagram of step down chopper.

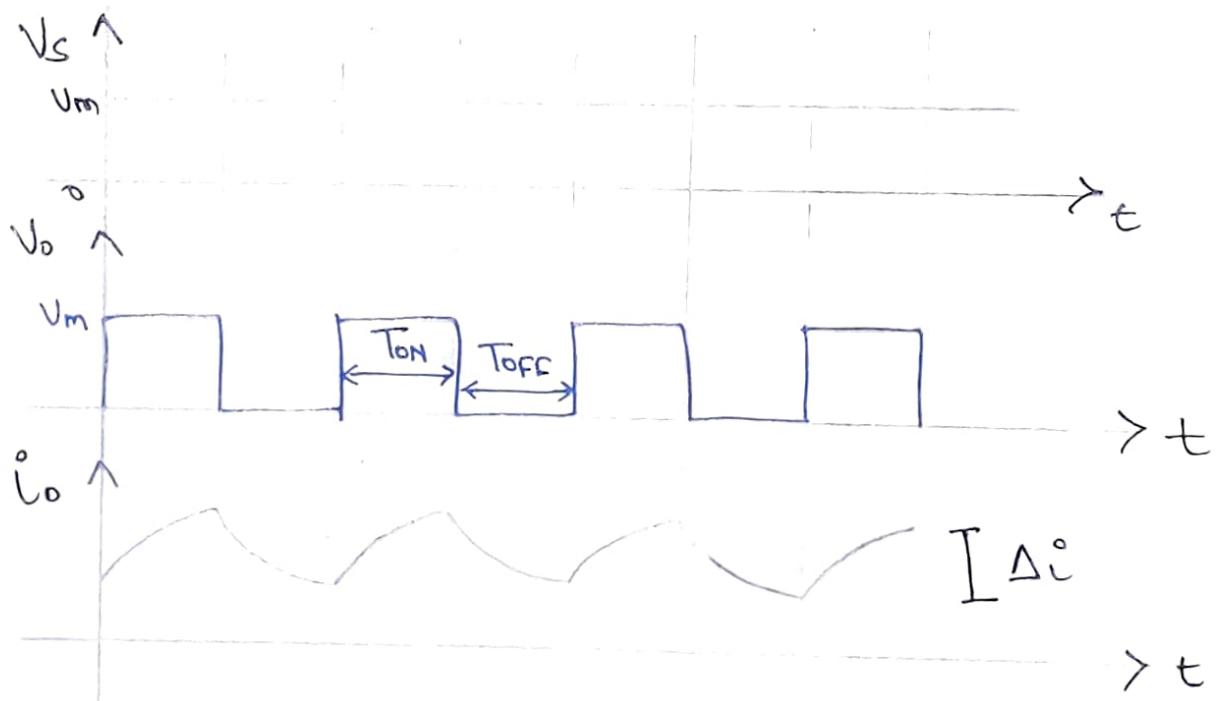


Figure 7.4: Waveforms of step down chopper

$$\Delta i = \frac{V_s - (1-D)V}{L_f}$$

$$D = \frac{T_{ON}}{T} \quad \text{and} \quad f = \frac{1}{T}$$

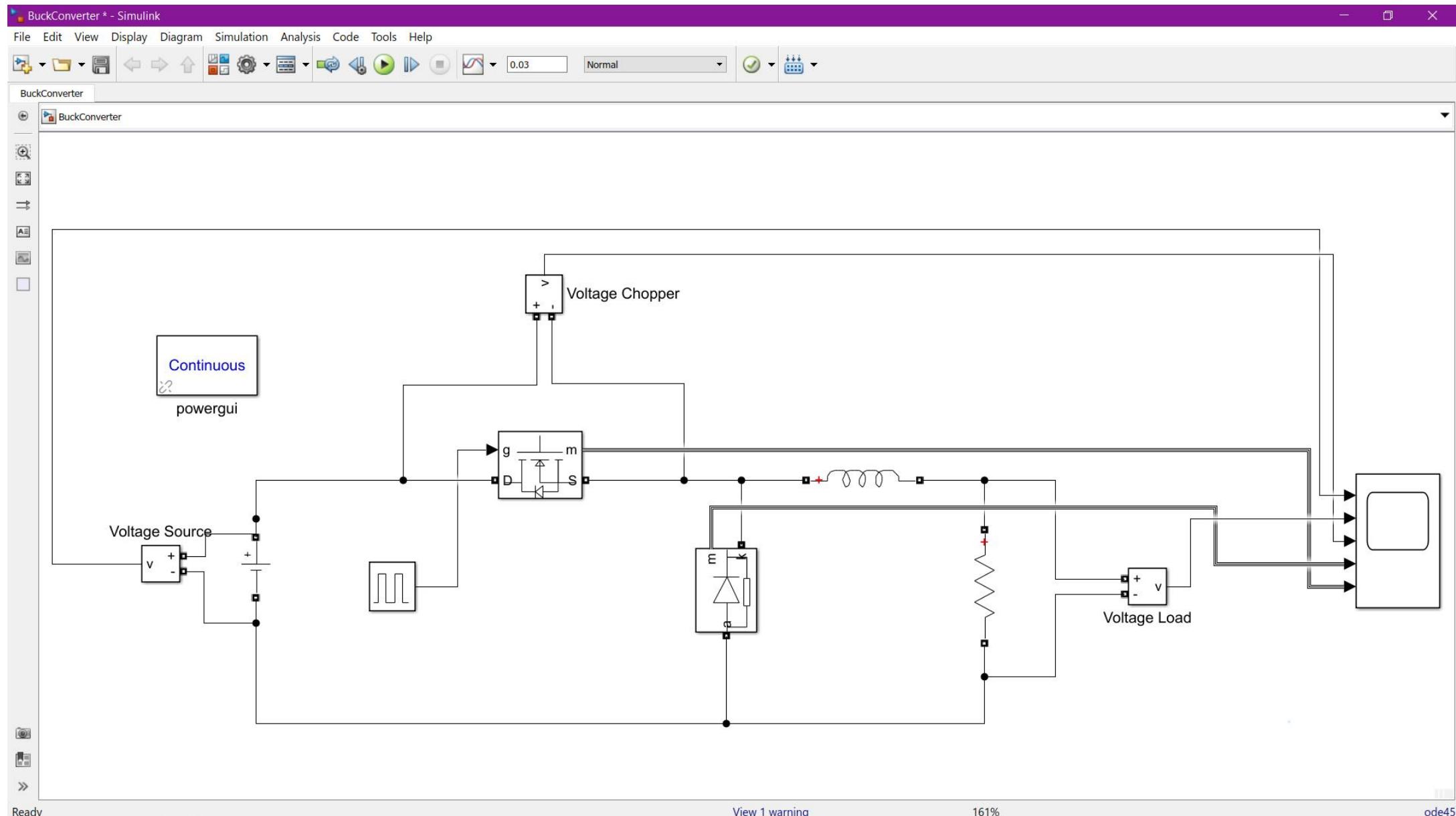
where, Δi is the inductor peak to peak current.

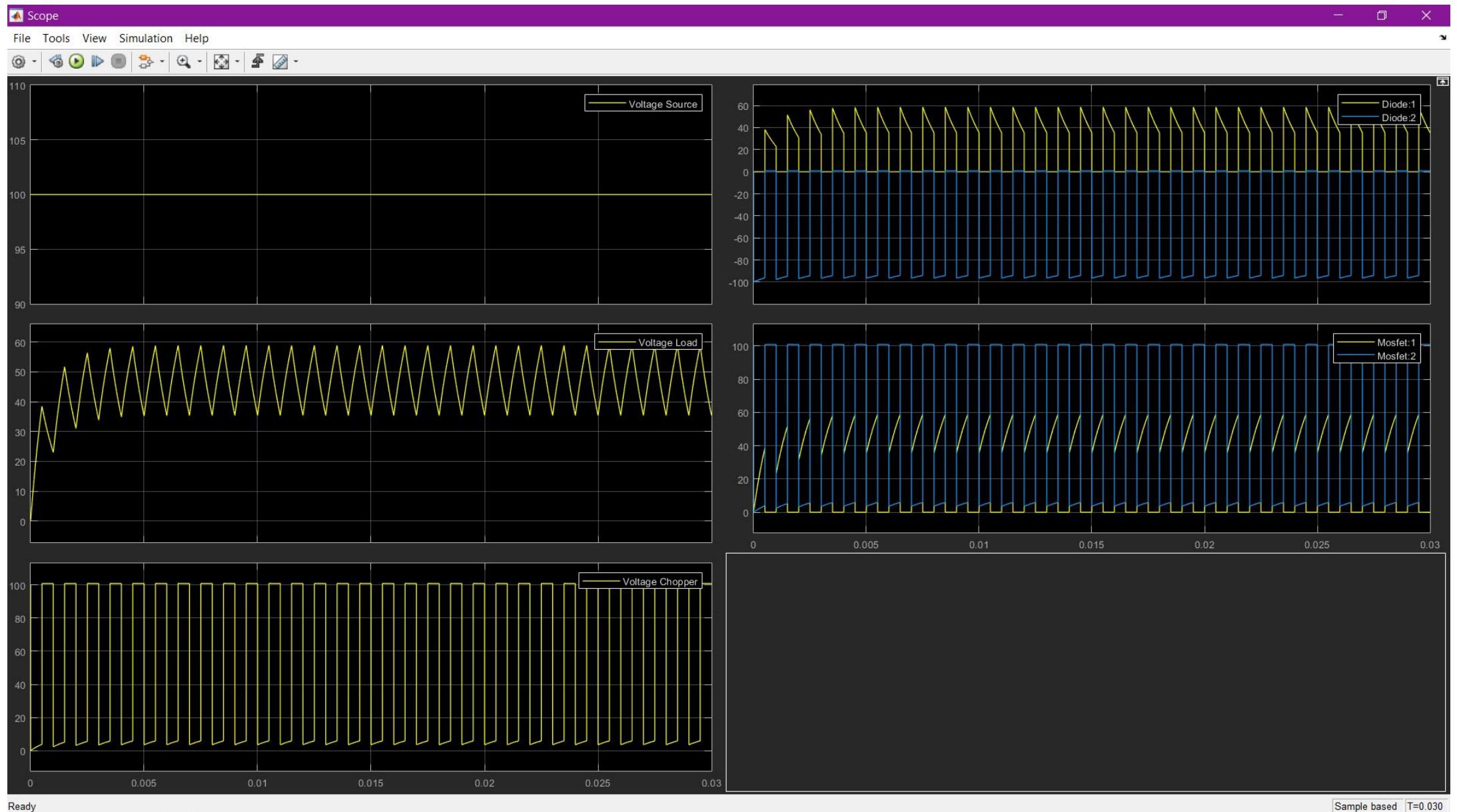
For step down chopper the voltage output is always less than the voltage input.

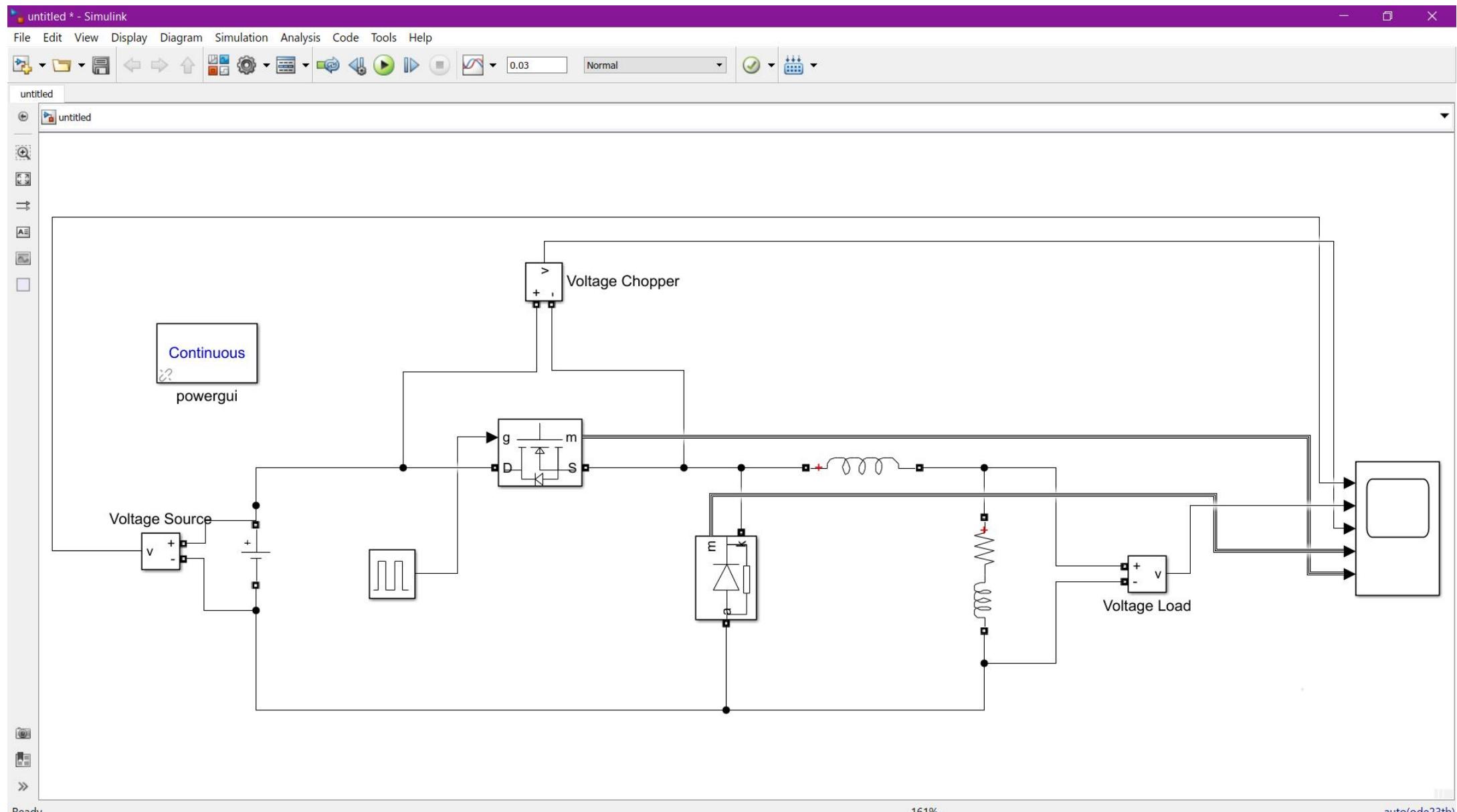
* Procedure:

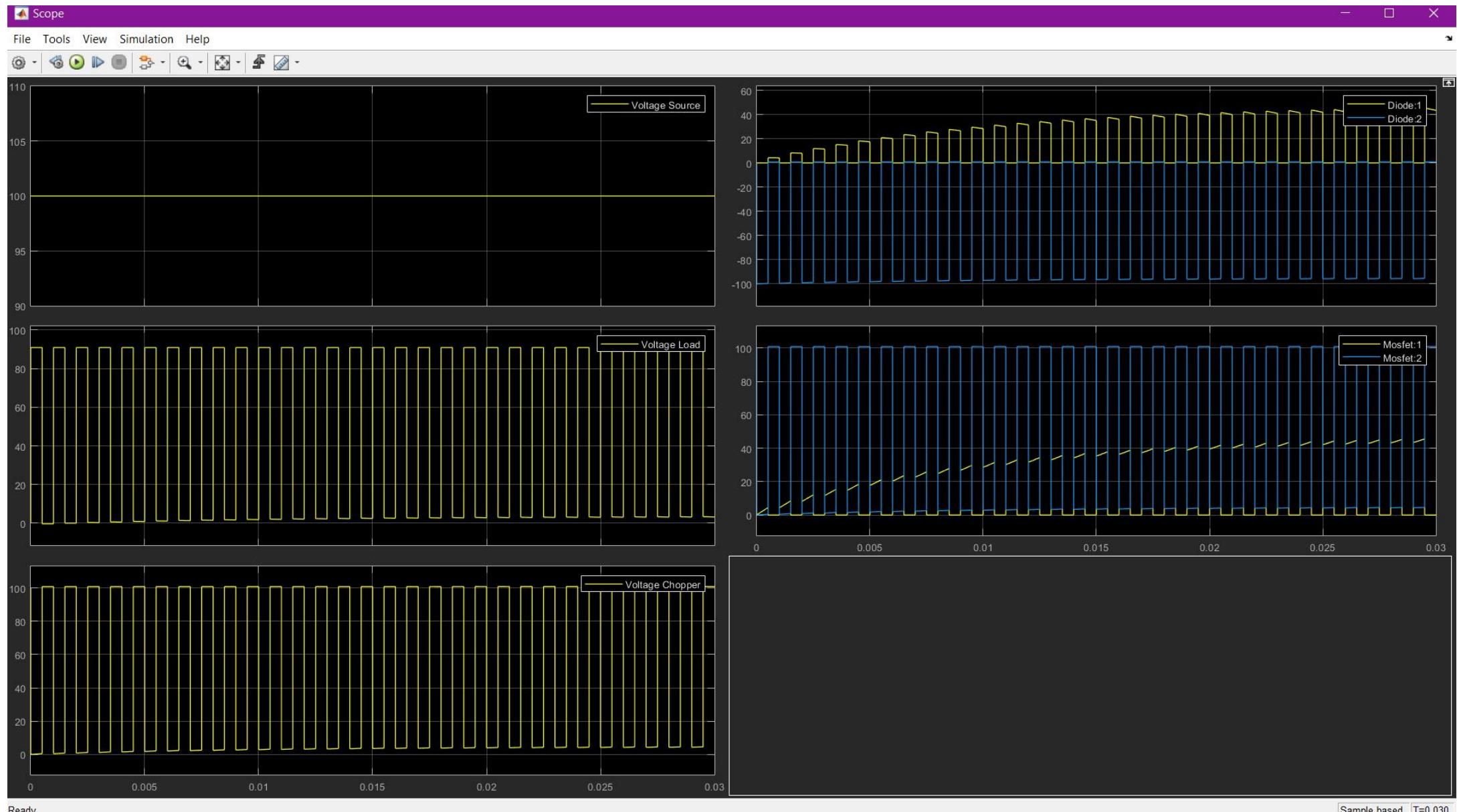
1. Make the required circuit in SIMULINK in MATLAB
~~Model~~ for step up chopper.
2. Simulate the circuit for 1 second.
3. Observe the waveform from the scope.
4. Now repeat the procedure for step down chopper.

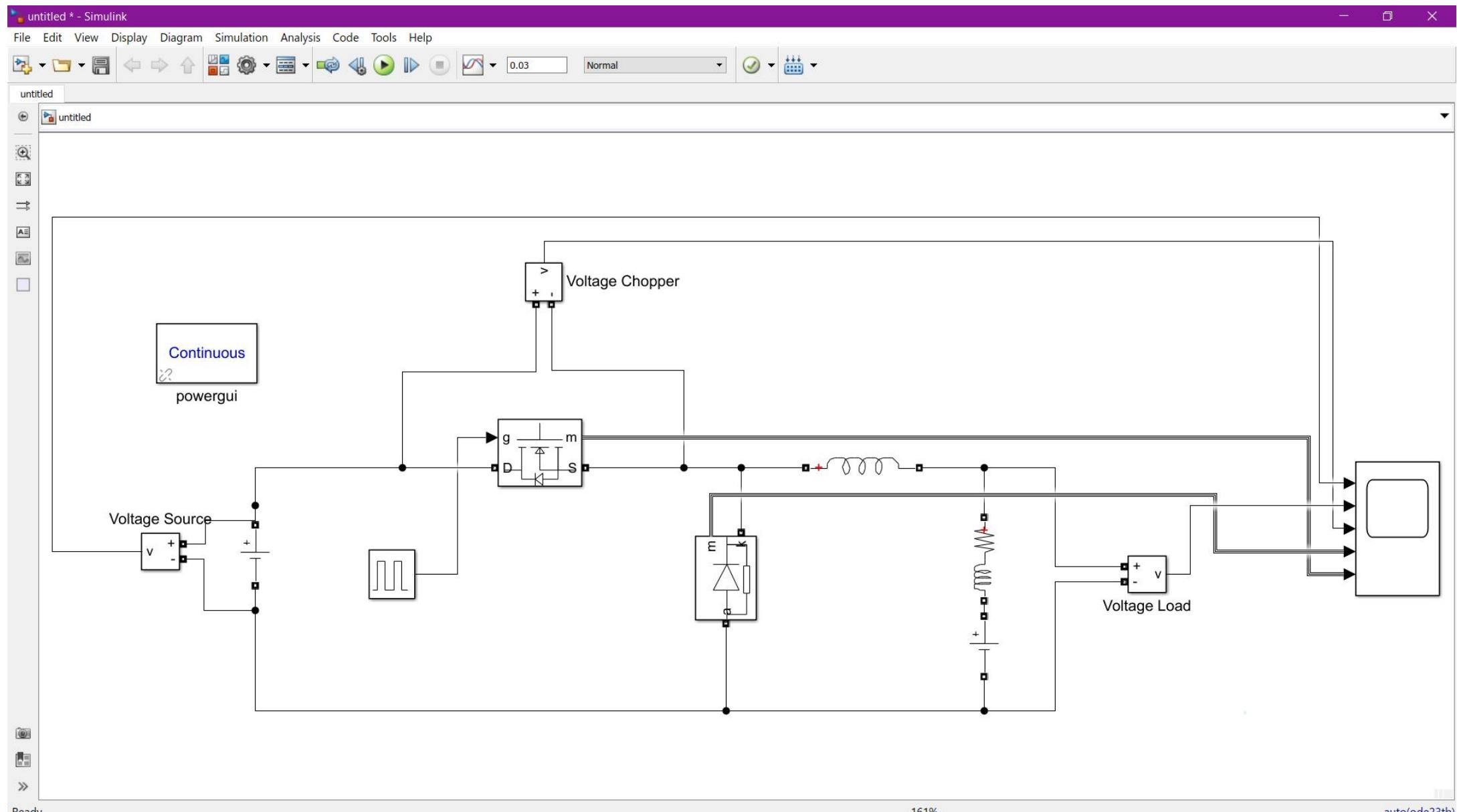
MATLAB Simulation

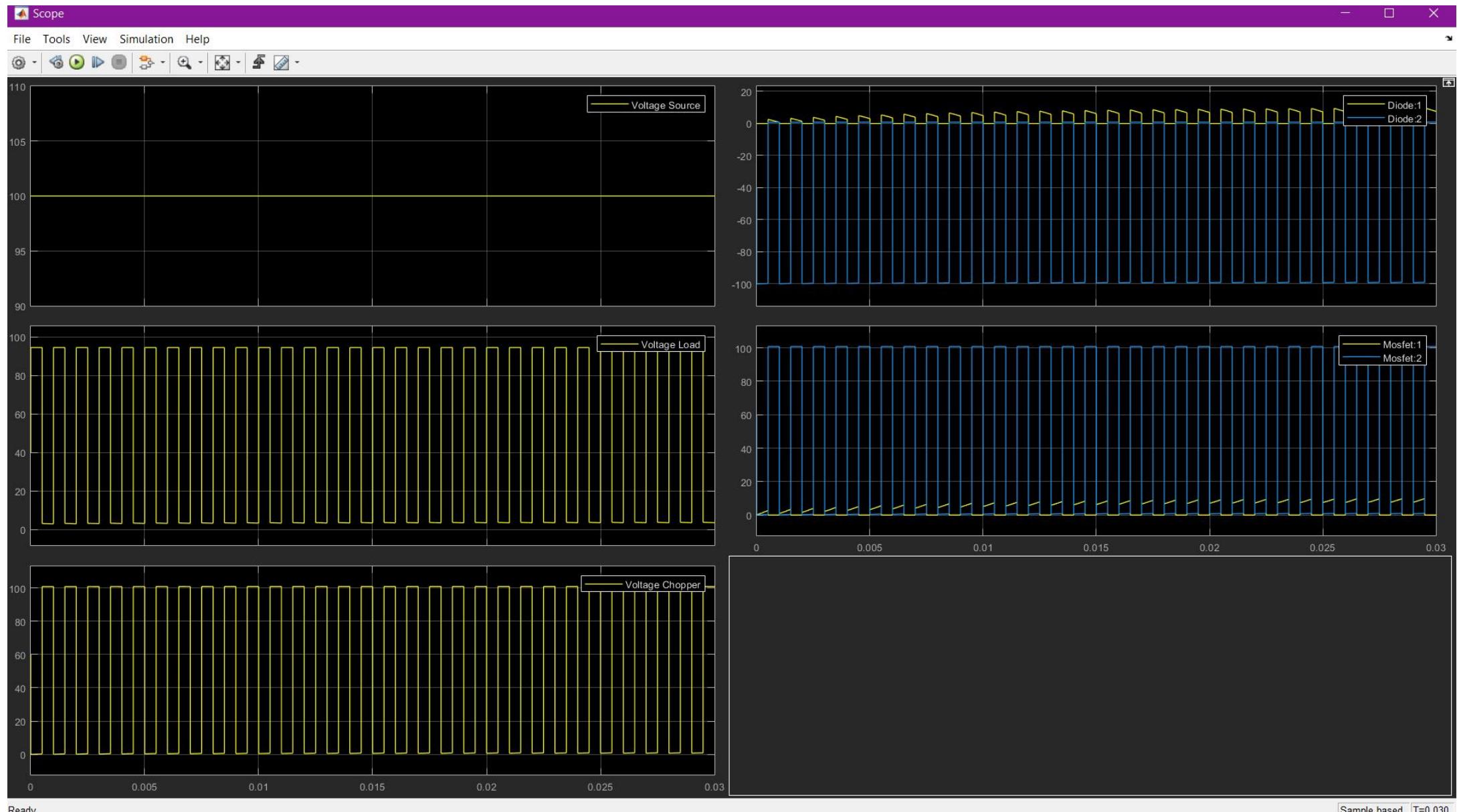


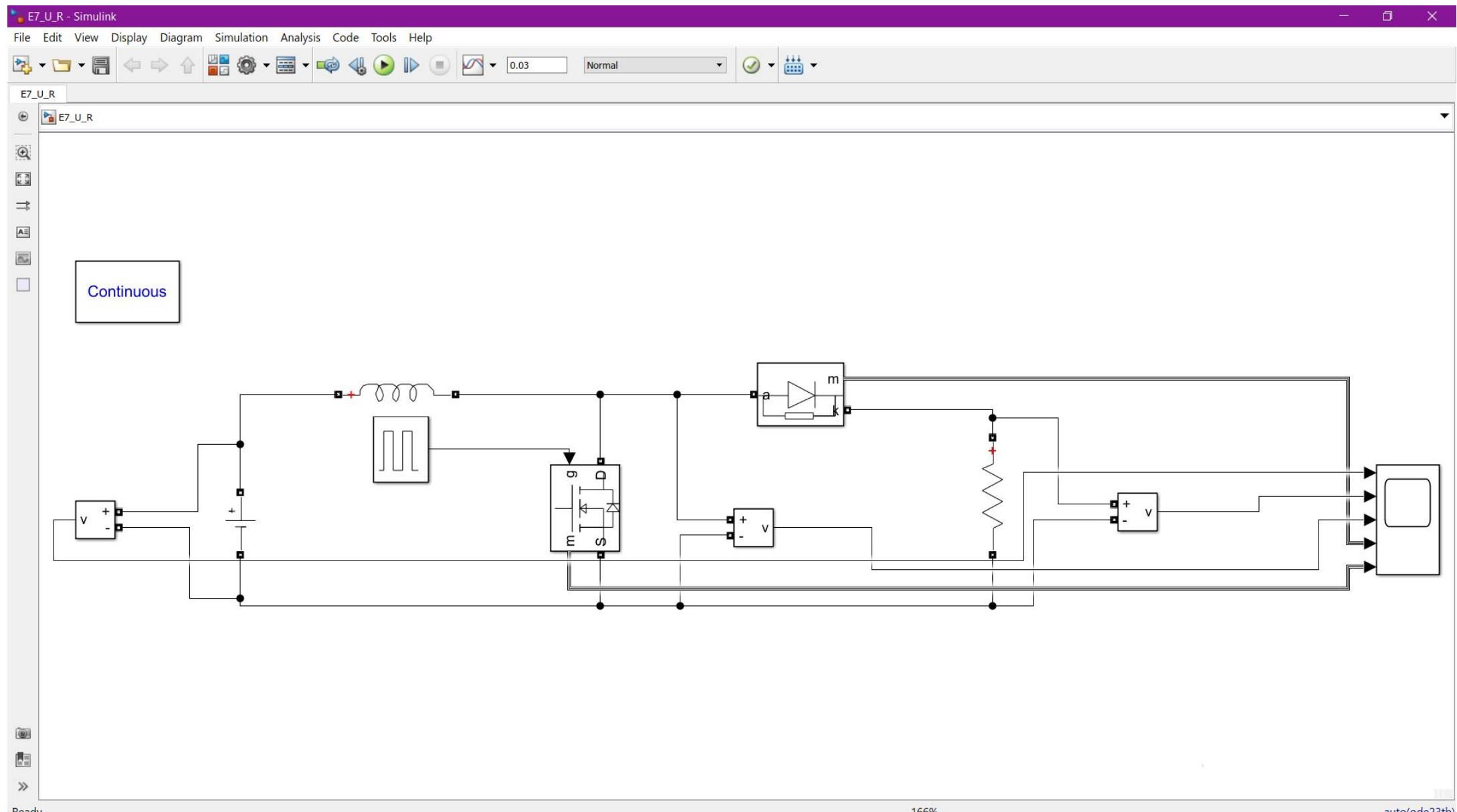


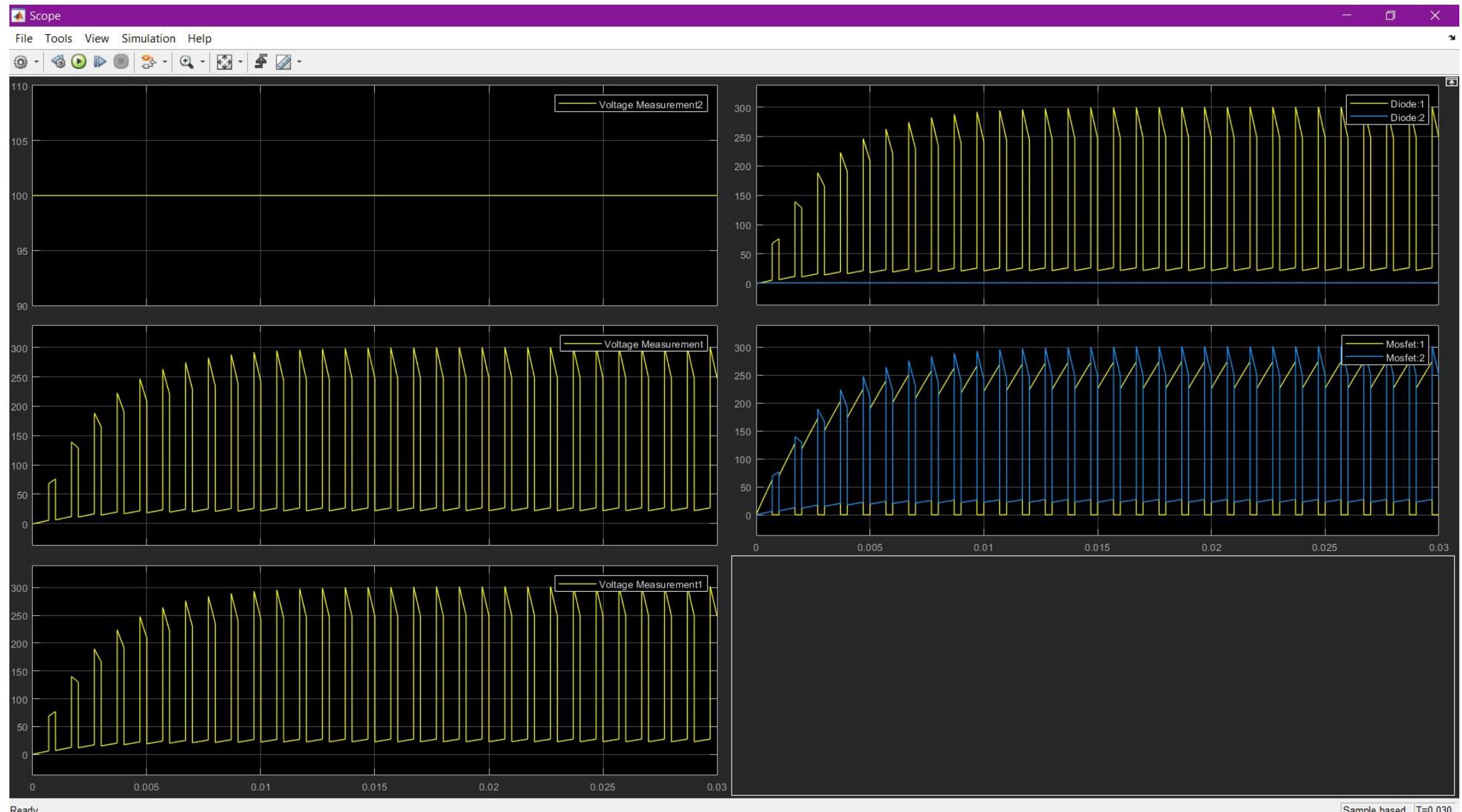


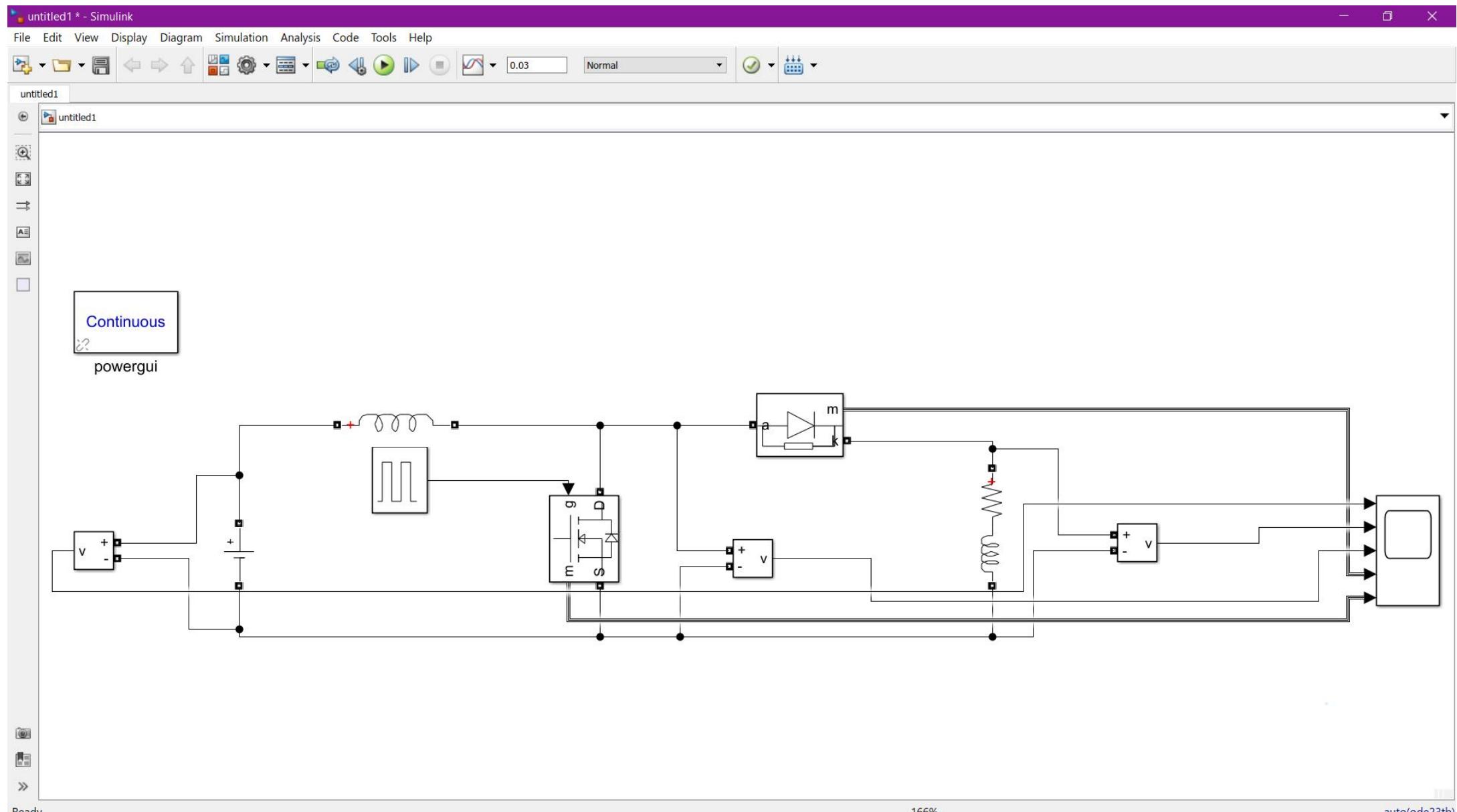


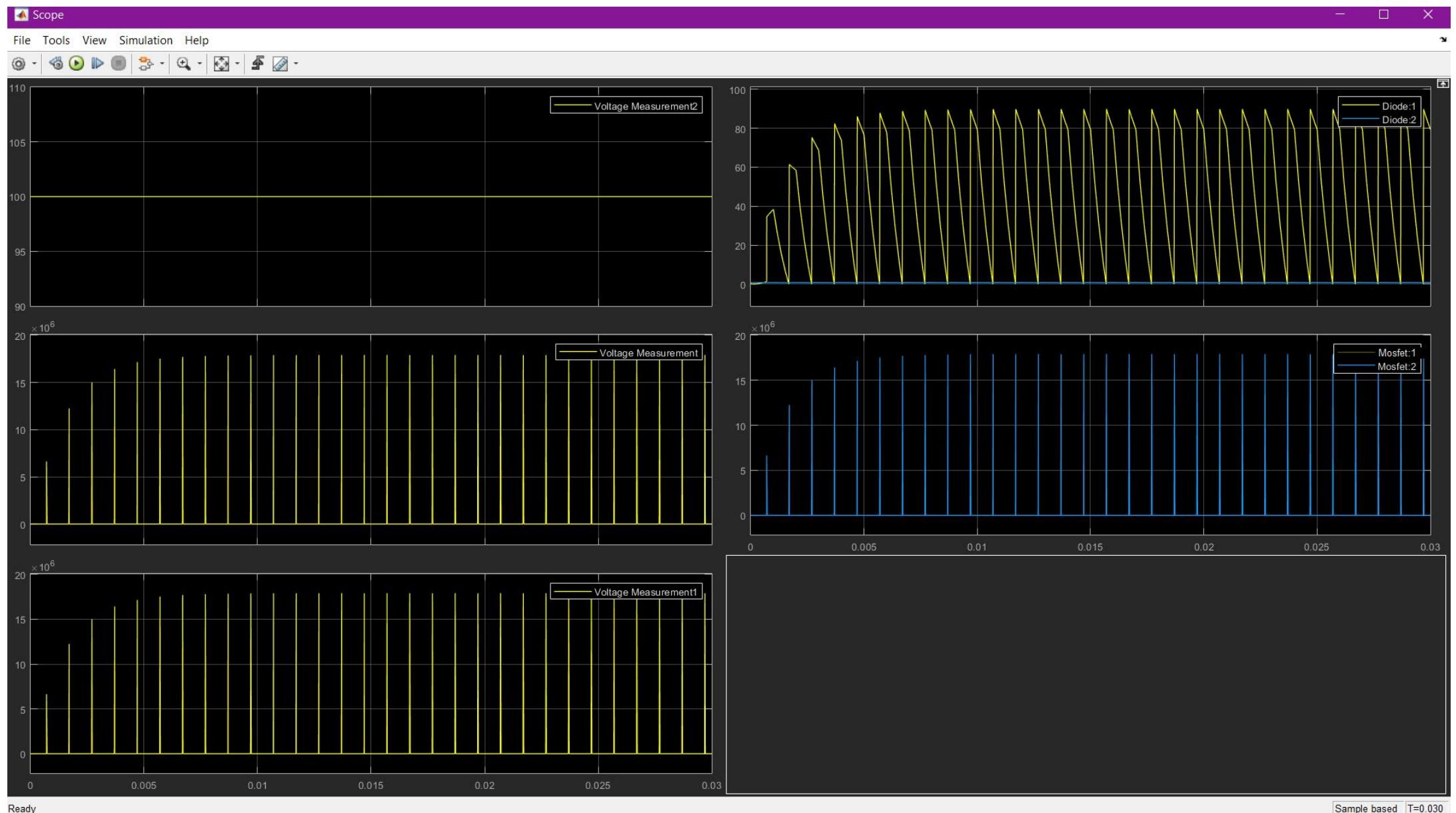


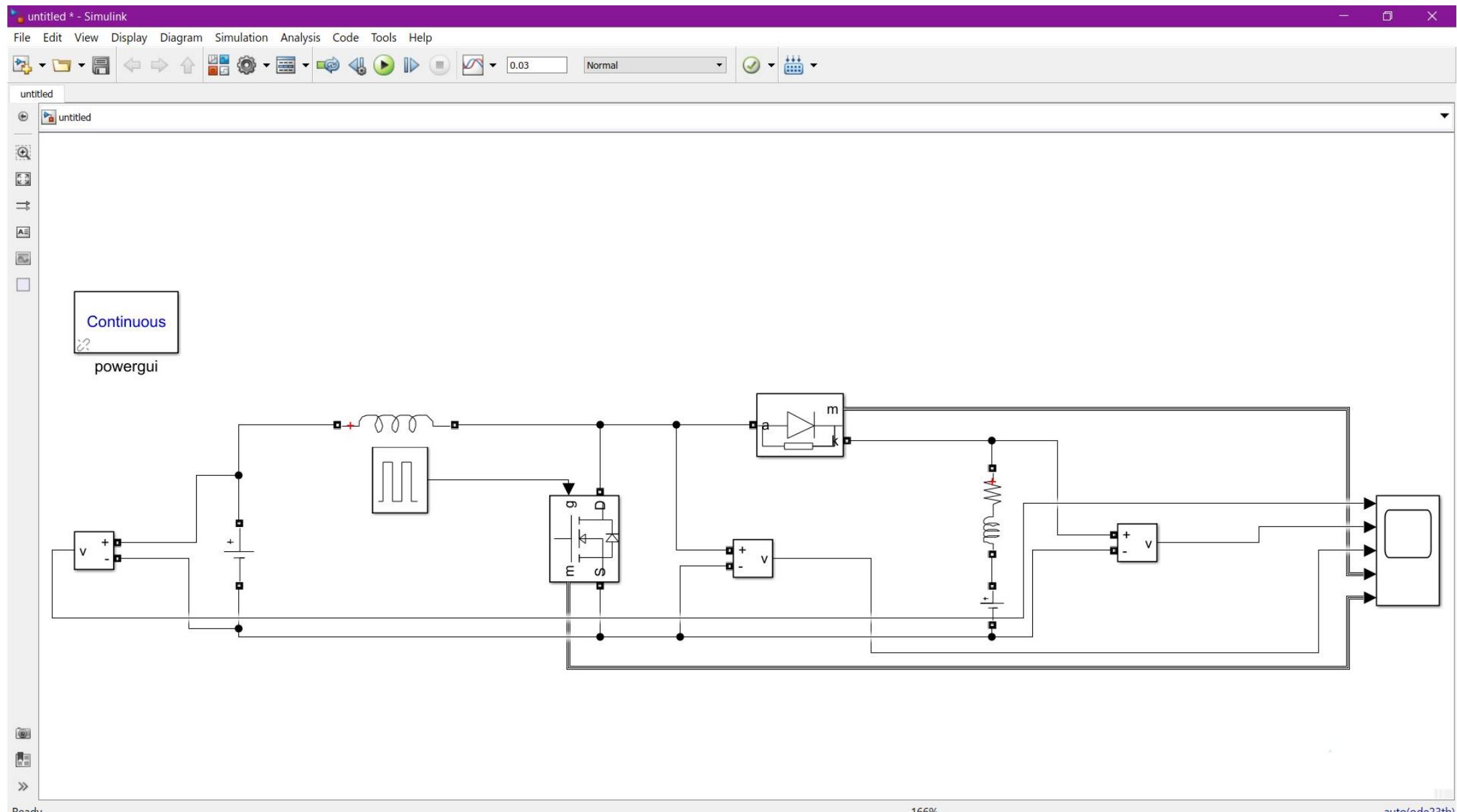


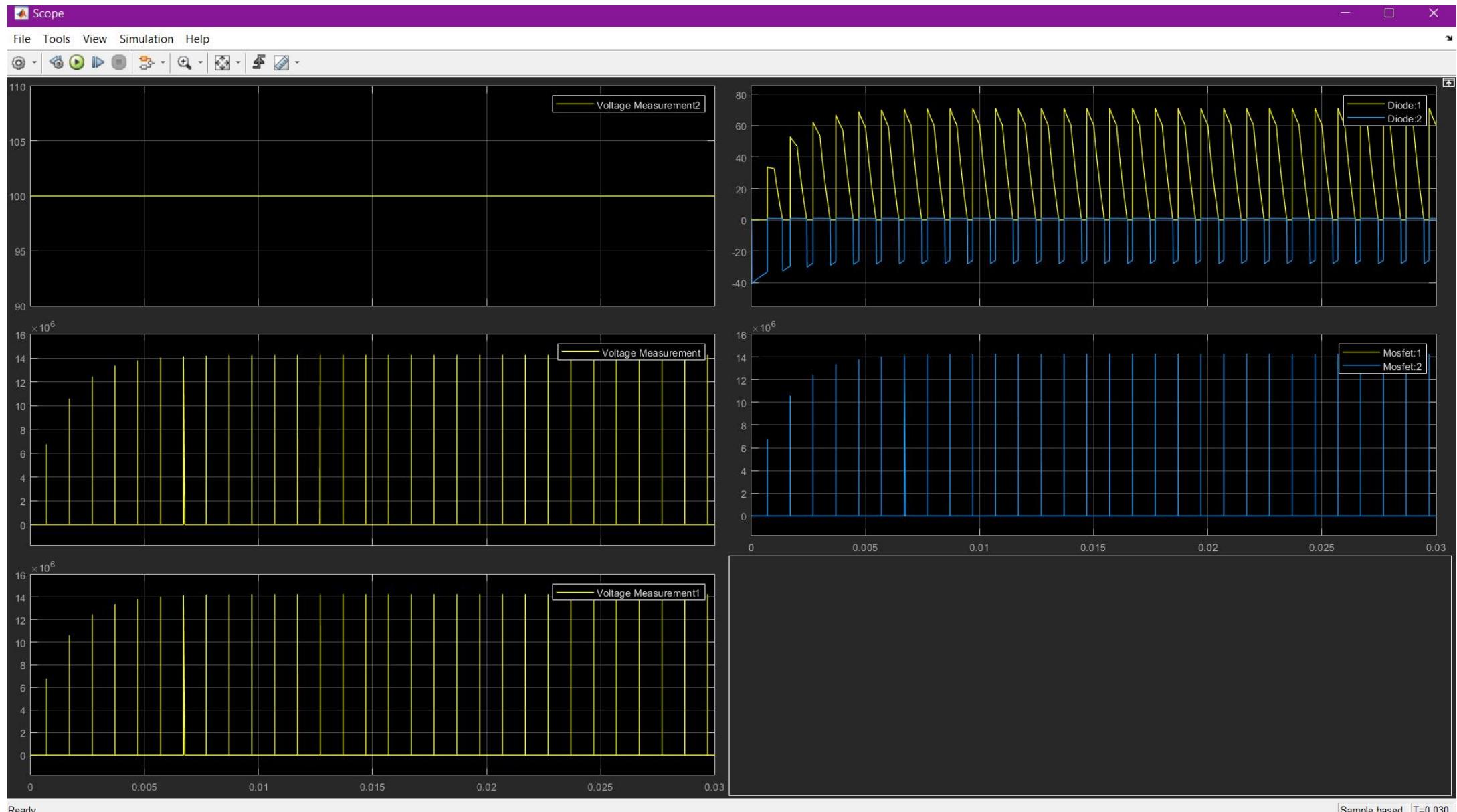












* Result: Simulated the step up and step down chopper for R , RL and RLC load using MATLAB. simulink

* Precautions:

1. Use powergui to store the equivalent simulink circuit that represents the State-Space equation of the model.
2. Always keep the circuit closed.
3. MATLAB takes time to respond, do not give multiple command at once.

Experiment - 8

- * Aim: To simulate the three phase bridge voltage source inverter (180° & 120° modes) with R & RL load using MATLAB Simulink.
- * Requirement: MATLAB Simulink
- * Theory: A three phase inverter converts DC input into a three phase AC output. Its three arms are normally delayed by an angle of 120° so as to generate a three phase AC supply. There are two types of Inverter.
 - 180° Mode of conduction
In this mode of conduction, every device is in conduction state of 180° , where they are switched ON at 60° intervals.
Firing scheme in this mode is:

Interval	Conducting Device	Incoming	Outgoing
I	5, 6, 1	1	4
II	6, 1, 2	2	5
III	1, 2, 3	3	6
IV	2, 3, 4	4	1
V	3, 4, 5	5	2
VI	4, 5, 6	6	3

* Diagram:

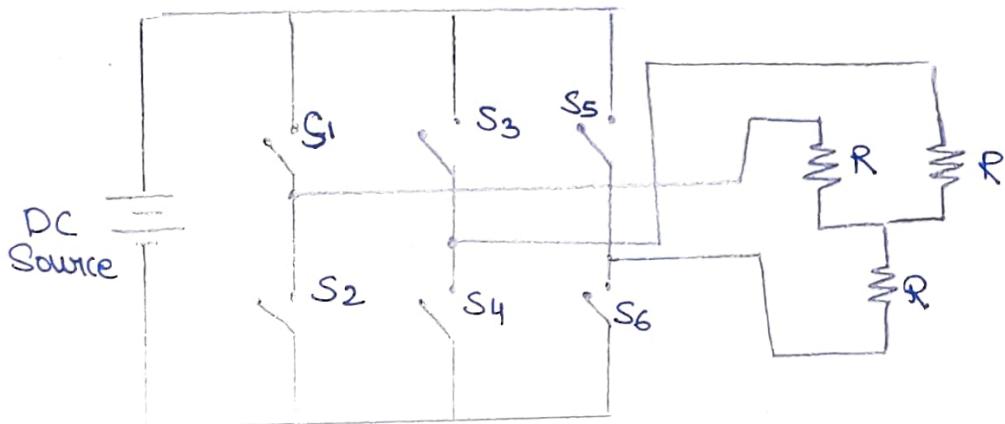


Fig 8.1: Circuit diagram of VSI

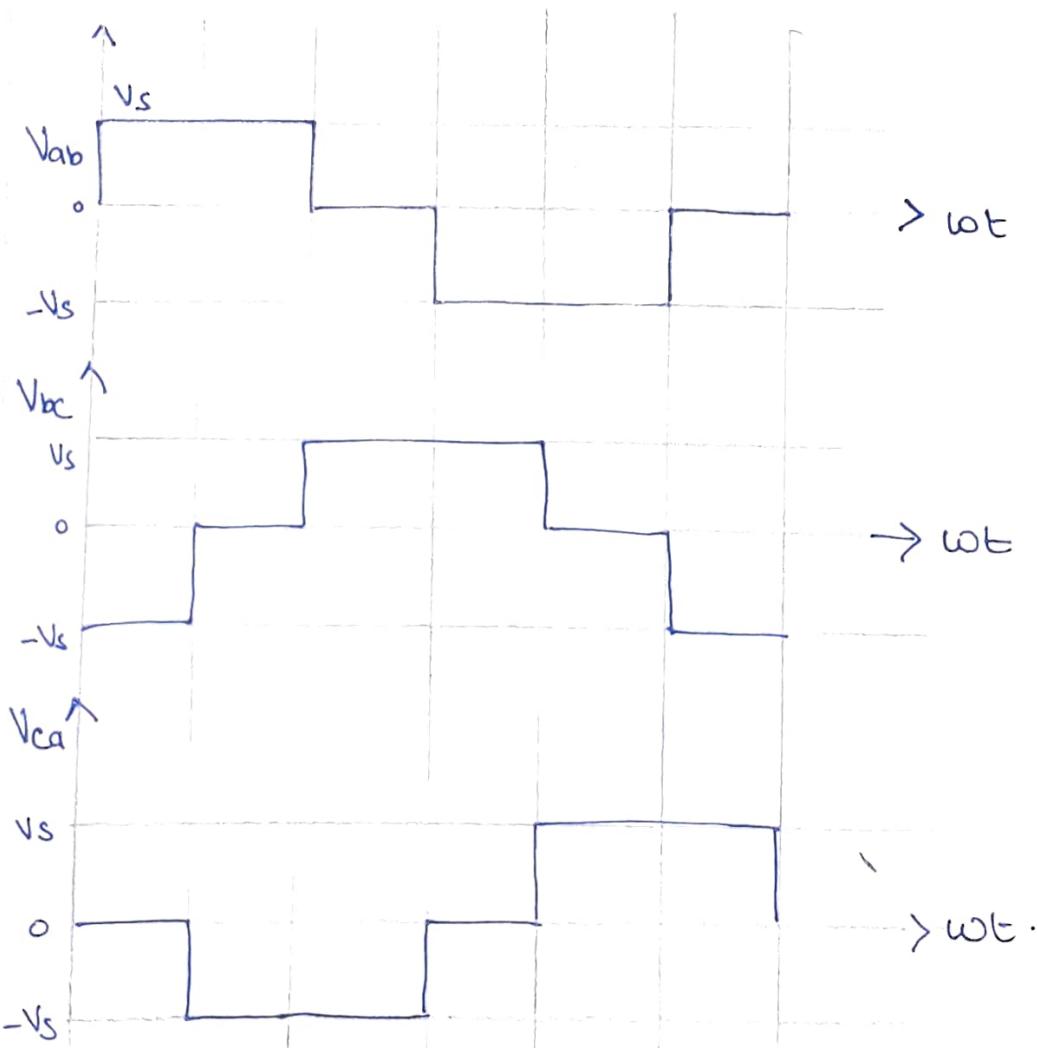


Fig 8.2: Waveforms of 180° mode. (phase-to-phase)

Interval I

$$R_{eq} = \frac{3R}{2}$$

$$I = \frac{2V_{dc}}{3R}$$

$$V_{an} = V_{cn} = \frac{IR}{2} = \frac{V_{dc}}{3}$$

$$V_{bn} = -IR = -\frac{2V_{dc}}{3}$$

$$\therefore V_{ab} = V_{dc}$$

$$V_{bc} = -V_{dc}$$

$$V_{ca} = 0$$

\therefore the phase to phase ~~and~~ and line voltage are:

Interval	V_{an}	V_{bn}	V_{cn}	V_{ab}	V_{bc}	V_{ca}
I	$\frac{V_{dc}}{3}$	$-2\frac{V_{dc}}{3}$	$\frac{V_{dc}}{3}$	V_{dc}	$-V_{dc}$	0
II	$\frac{2V_{dc}}{3}$	$-\frac{V_{dc}}{3}$	$-\frac{V_{dc}}{3}$	V_{dc}	0	$-V_{dc}$
III	$\frac{V_{dc}}{3}$	$\frac{V_{dc}}{3}$	$-2\frac{V_{dc}}{3}$	0	V_{dc}	$-V_{dc}$
IV	$-\frac{V_{dc}}{3}$	$\frac{2V_{dc}}{3}$	$-\frac{V_{dc}}{3}$	$-V_{dc}$	V_{dc}	0
V	$-2\frac{V_{dc}}{3}$	$\frac{V_{dc}}{3}$	$\frac{V_{dc}}{3}$	$-V_{dc}$	0	V_{dc}
VI	$-\frac{V_{dc}}{3}$	$-\frac{V_{dc}}{3}$	$\frac{2V_{dc}}{3}$	0	$-V_{dc}$	V_{dc}

120° Mode of Conduction

In this mode, each device is in conduction ~~mode~~ state of 120° . It is most suitable for a delta connected connection in a load because it results in a six step type of waveform.

firing scheme in this mode is:

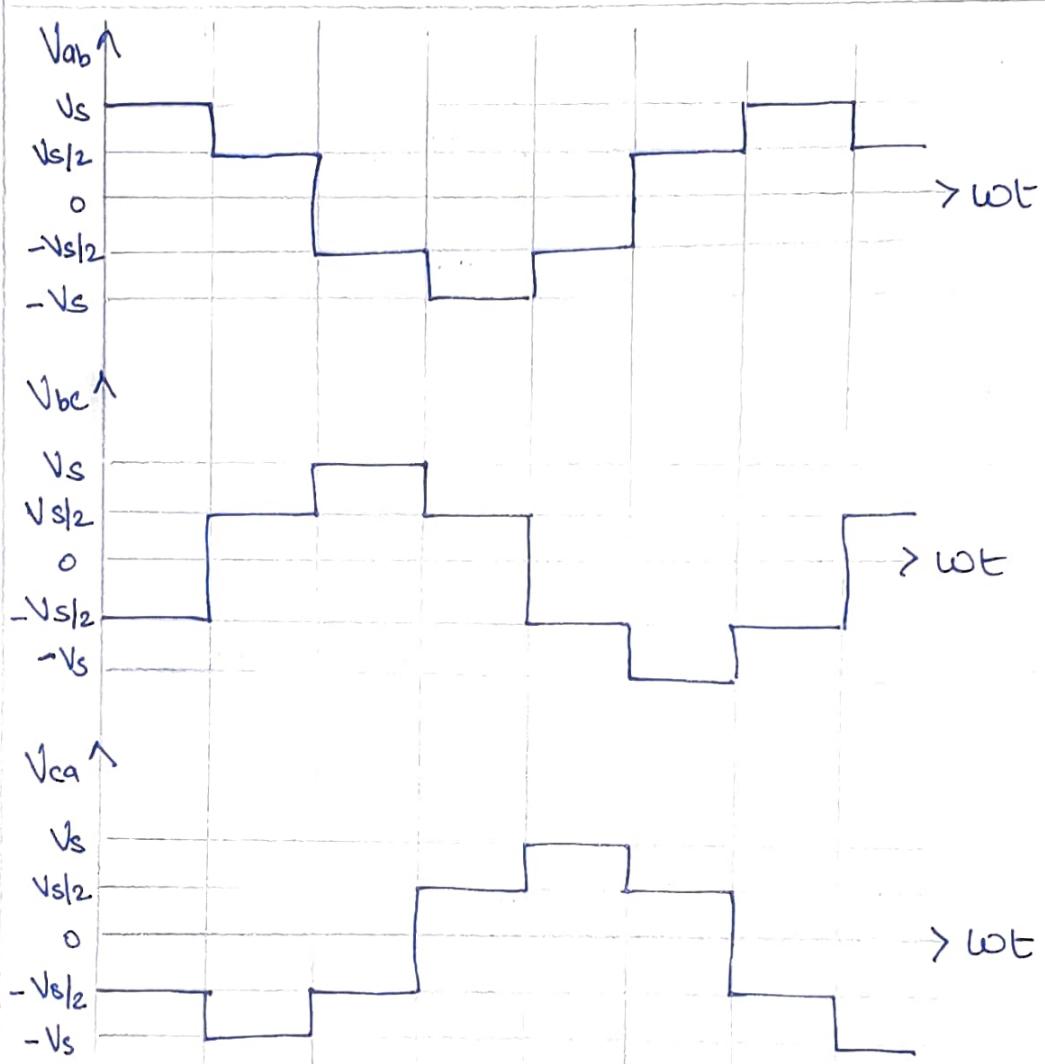


Fig 8.3: Waveform of 120° mode.

Interval	Conducting Device	Incoming	Outgoing
I	6, 1	1	6
II	1, 2	2	1
III	2, 3	3	2
IV	3, 4	4	3
V	4, 5	5	4
VI	5, 6	6	5

Interval I

$$I = \frac{V_{dc}}{R+R} = \frac{V_{dc}}{2R}$$

$$V_{an} = \frac{V_{dc}}{2} \quad V_{bn} = -\frac{V_{dc}}{2} \quad V_{cn} = 0$$

$$V_{AB} = V_{dc}$$

$$V_{BC} = -\frac{V_{dc}}{2}$$

$$V_{CA} = -\frac{V_{dc}}{2}$$

∴ the phase and line to line voltage are:

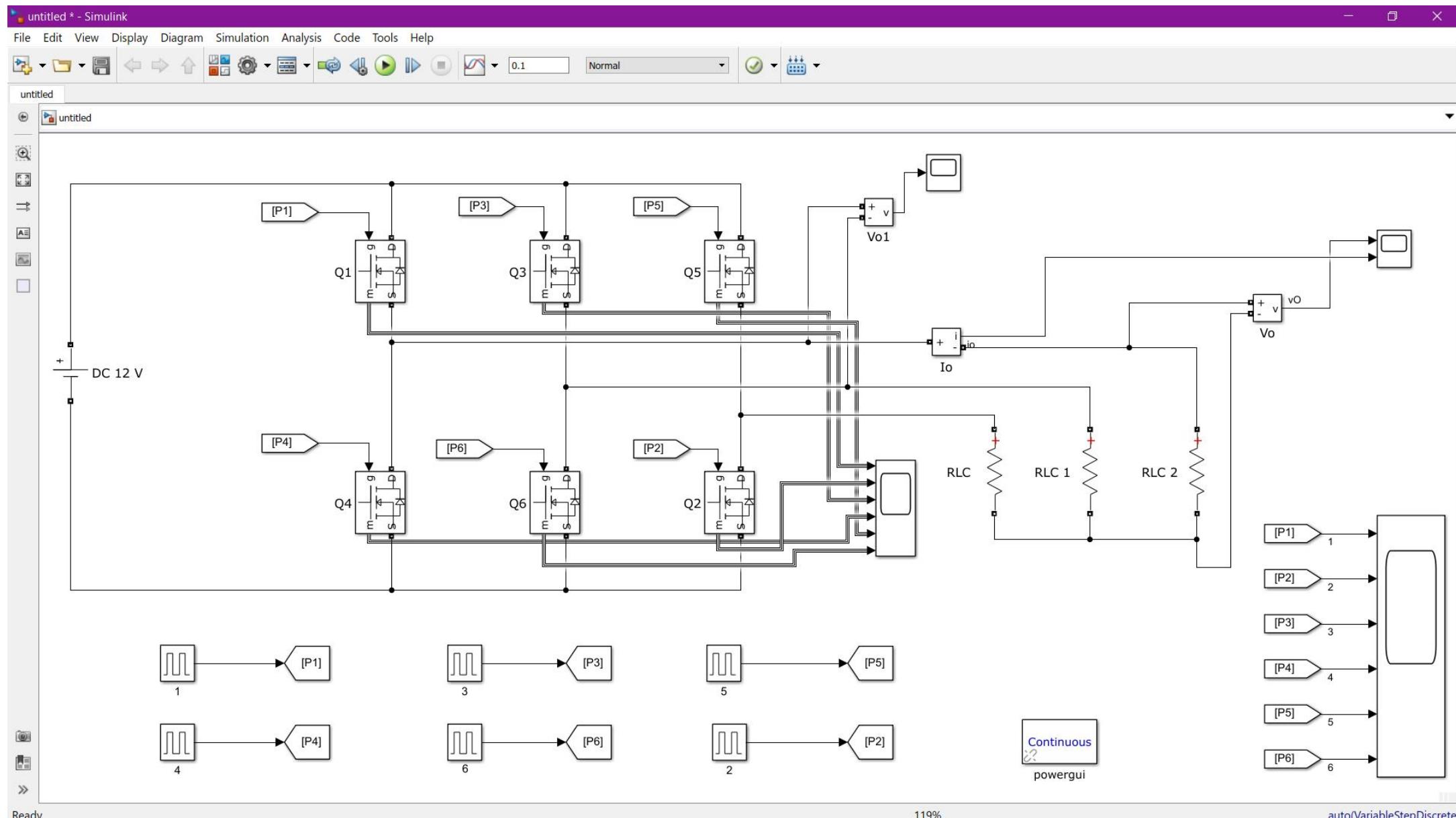
Interval	V_{an}	V_{bn}	V_{cn}	V_{ab}	V_{bc}	V_{ca}
I	$V_{dc}/2$	$-V_{dc}/2$	0	V_{dc}	$-V_{dc}/2$	$-V_{dc}/2$
II	$V_{dc}/2$	0	$-V_{dc}/2$	$V_{dc}/2$	$V_{dc}/2$	$-V_{dc}$
III	0	$-V_{dc}/2$	$-V_{dc}/2$	$-V_{dc}/2$	V_{dc}	$-V_{dc}/2$
IV	$-V_{dc}/2$	$V_{dc}/2$	0	$-V_{dc}$	$V_{dc}/2$	$V_{dc}/2$

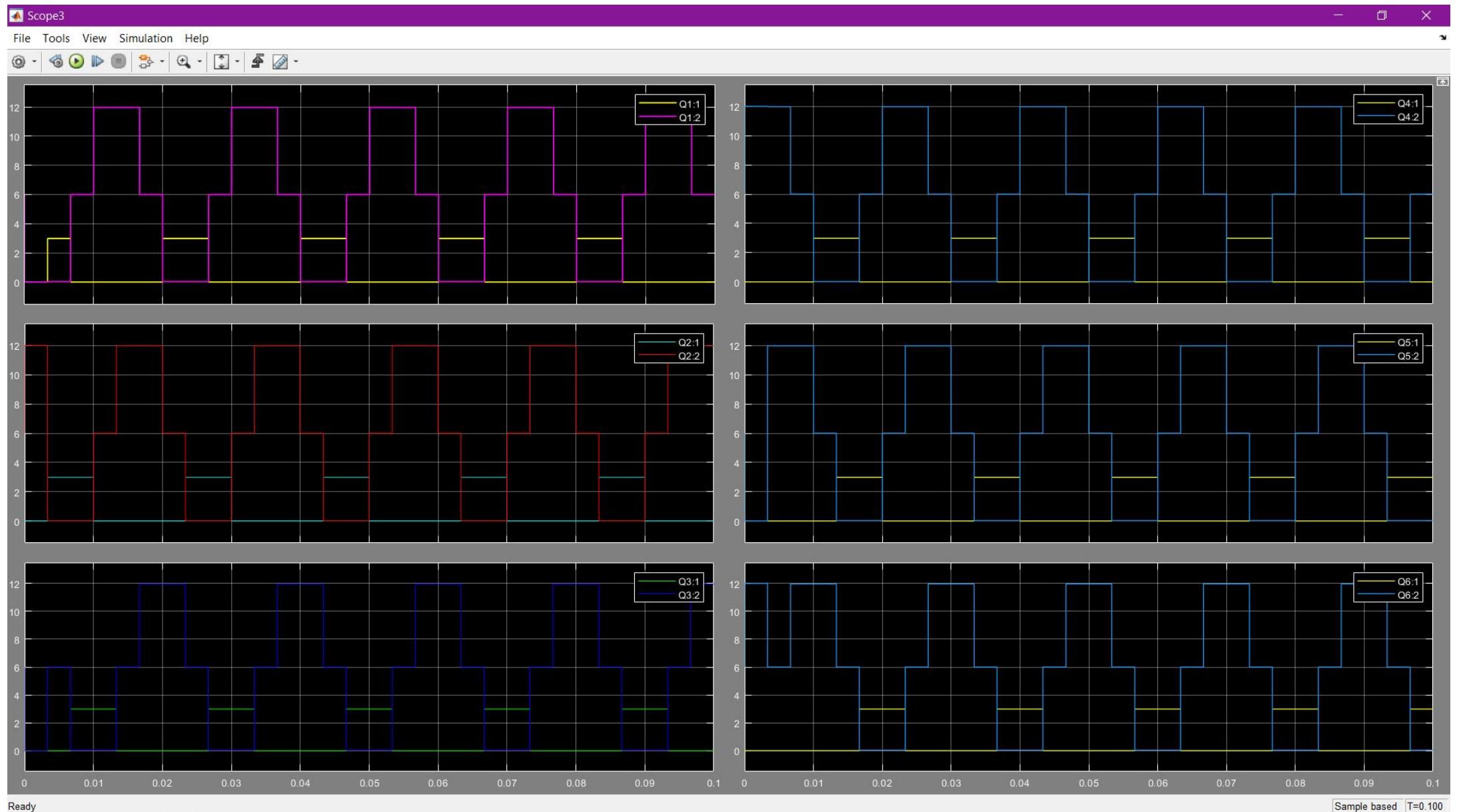
<u>V</u>	$-V_{dc}/2$	0	$V_{dc}/2$	$-V_{dc}/2$	$-V_{dc}/2$	$-V_{dc}$	$-V_{dc}/2$
<u>VI</u>	0	$-V_{dc}/2$	$V_{dc}/2$	$V_{dc}/2$	V_{dc}	$V_{dc}/2$	

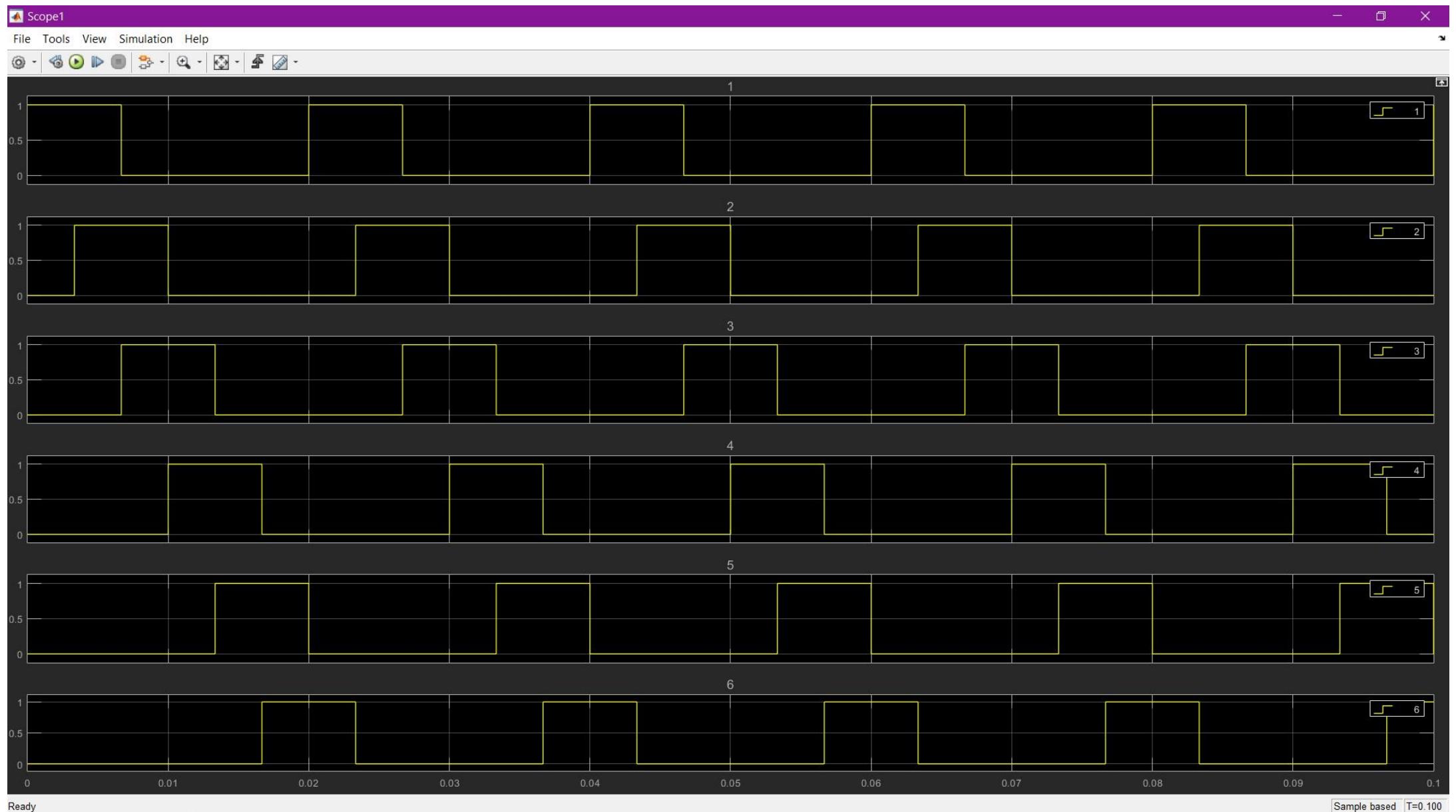
* Procedure:

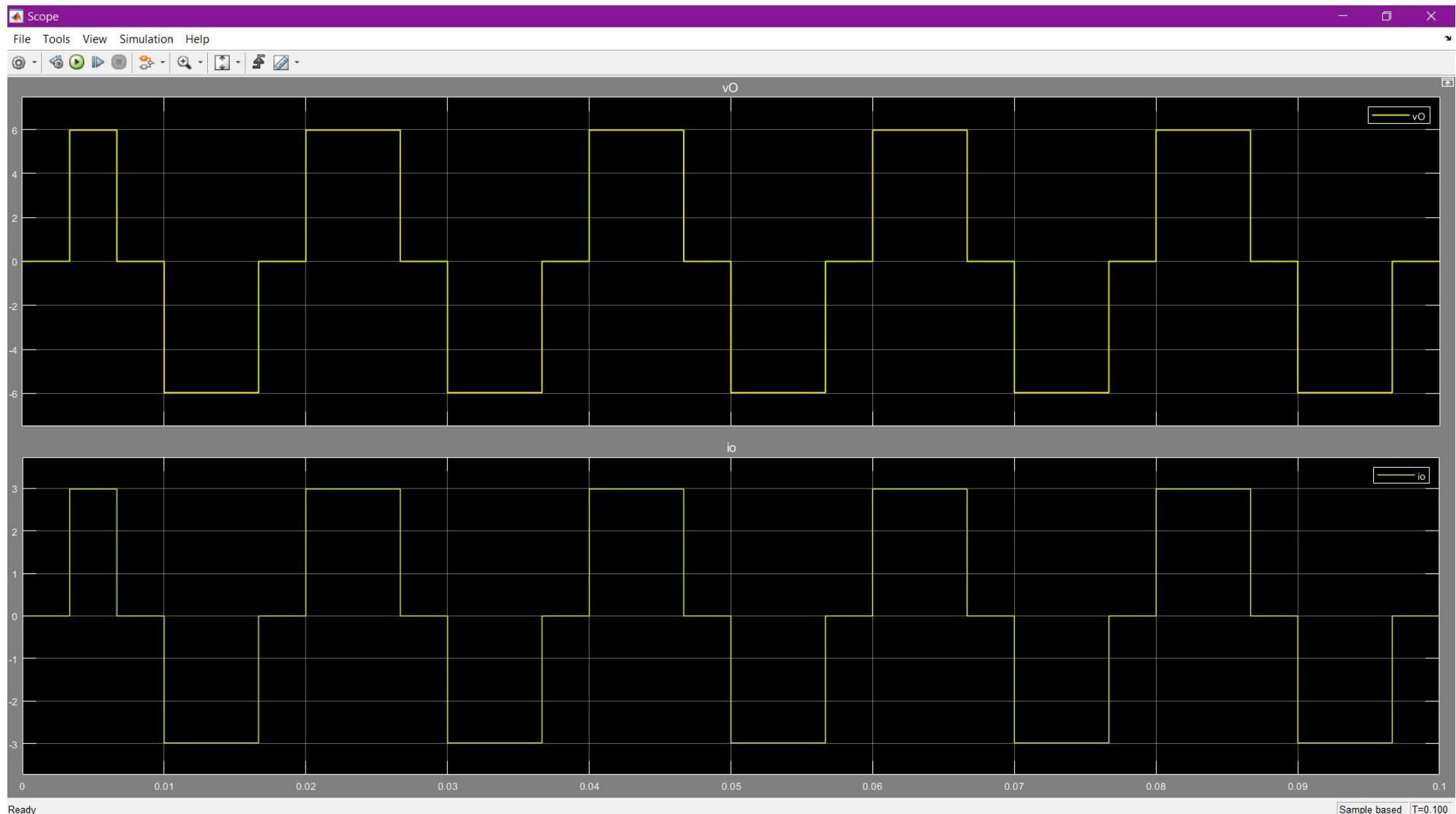
1. Make the required circuit in SIMULINK in MATLAB for 120° mode of VSI
2. Simulate the model.
3. Observe the waveform from the scope
4. Now, repeat the process for ~~at~~ 180° mode of VSI.

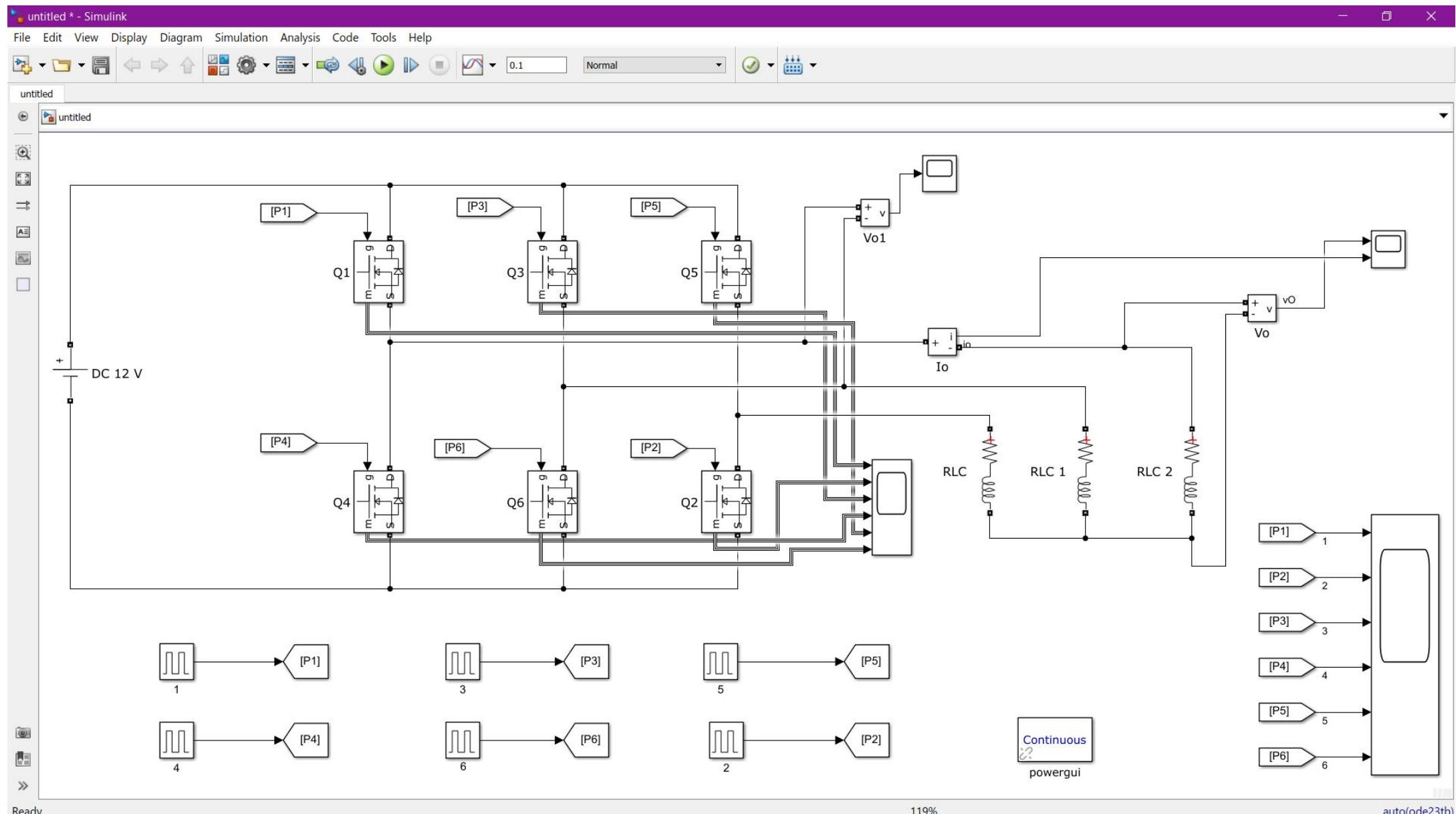
MATLAB Simulation

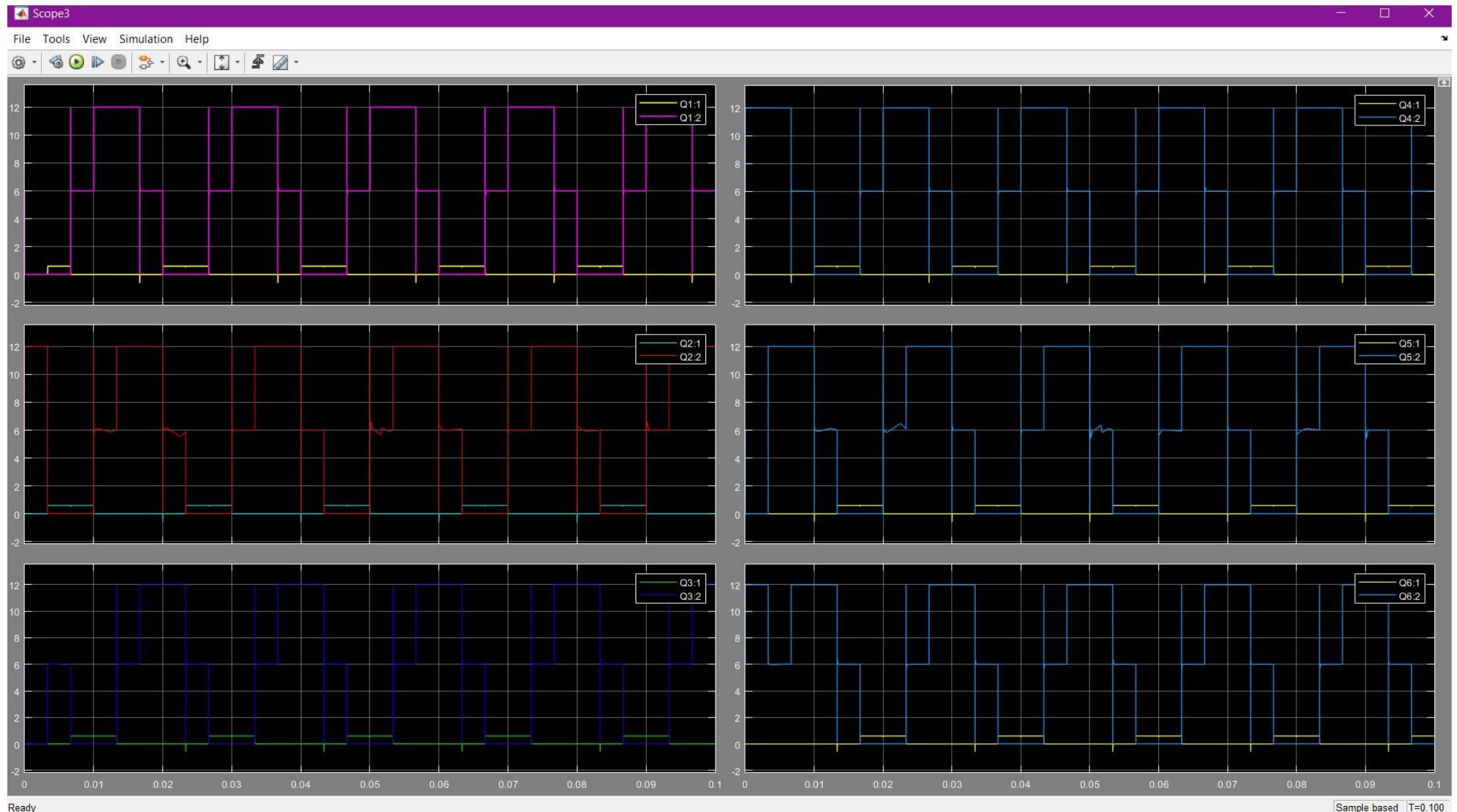


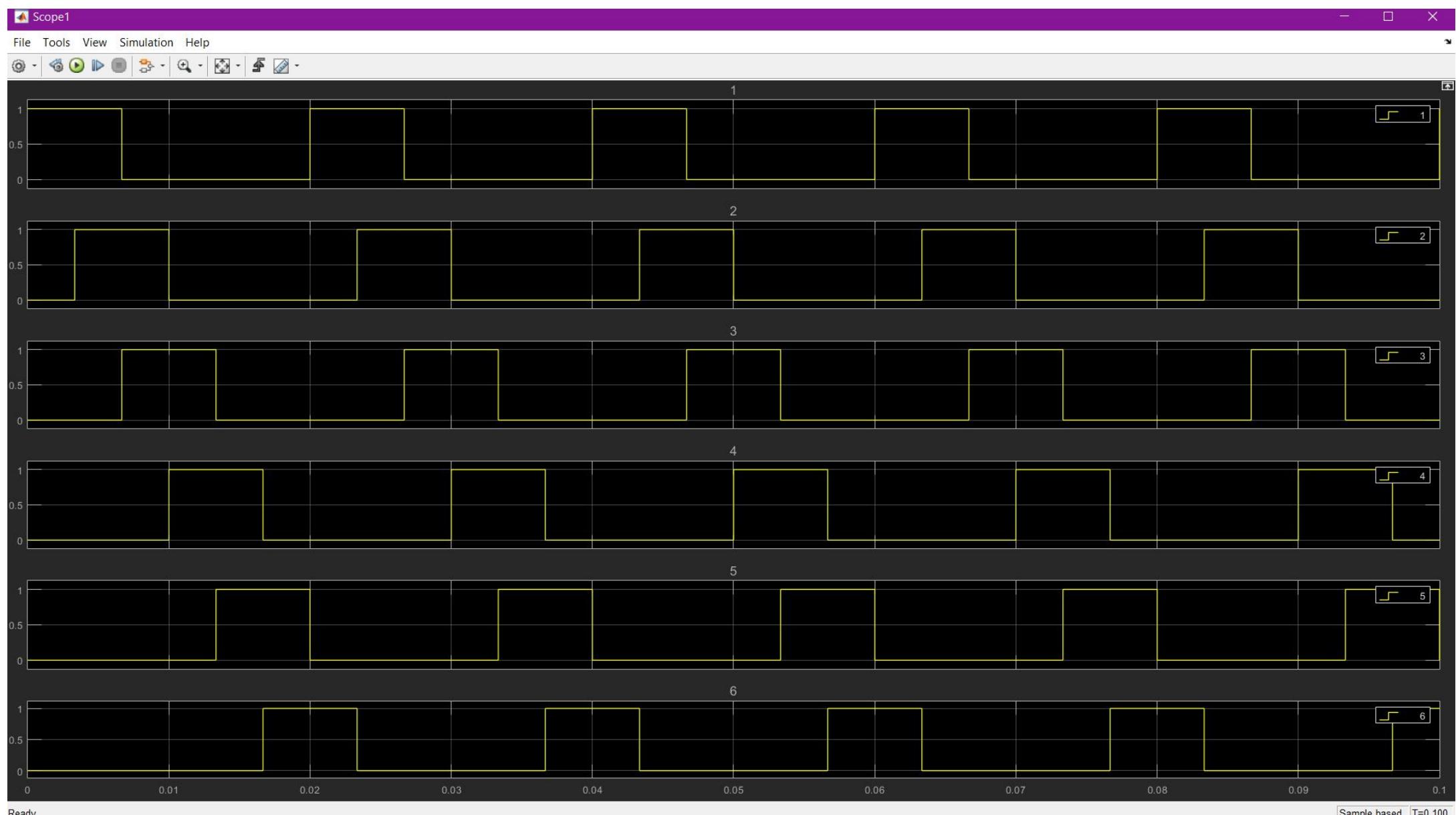


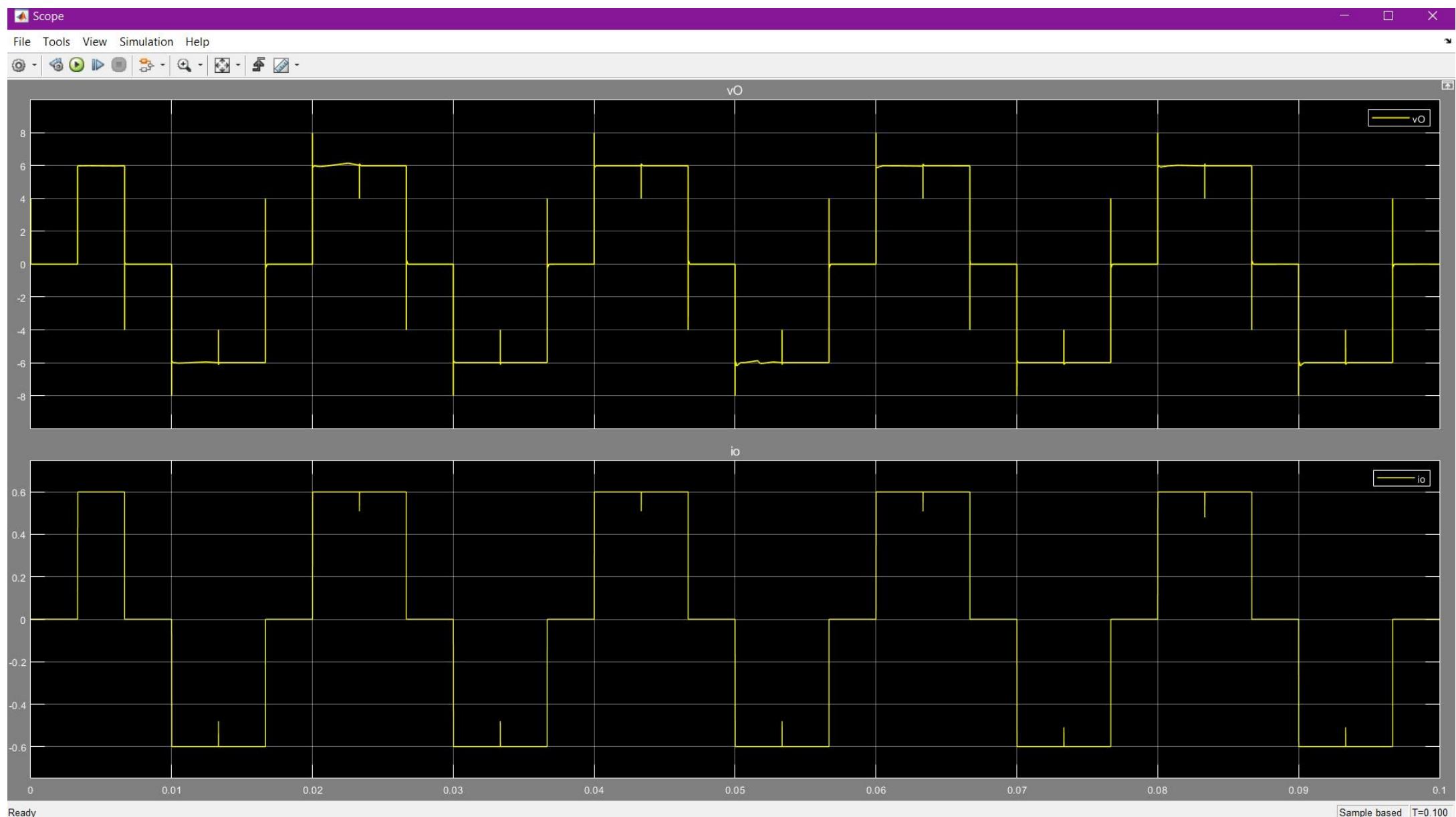


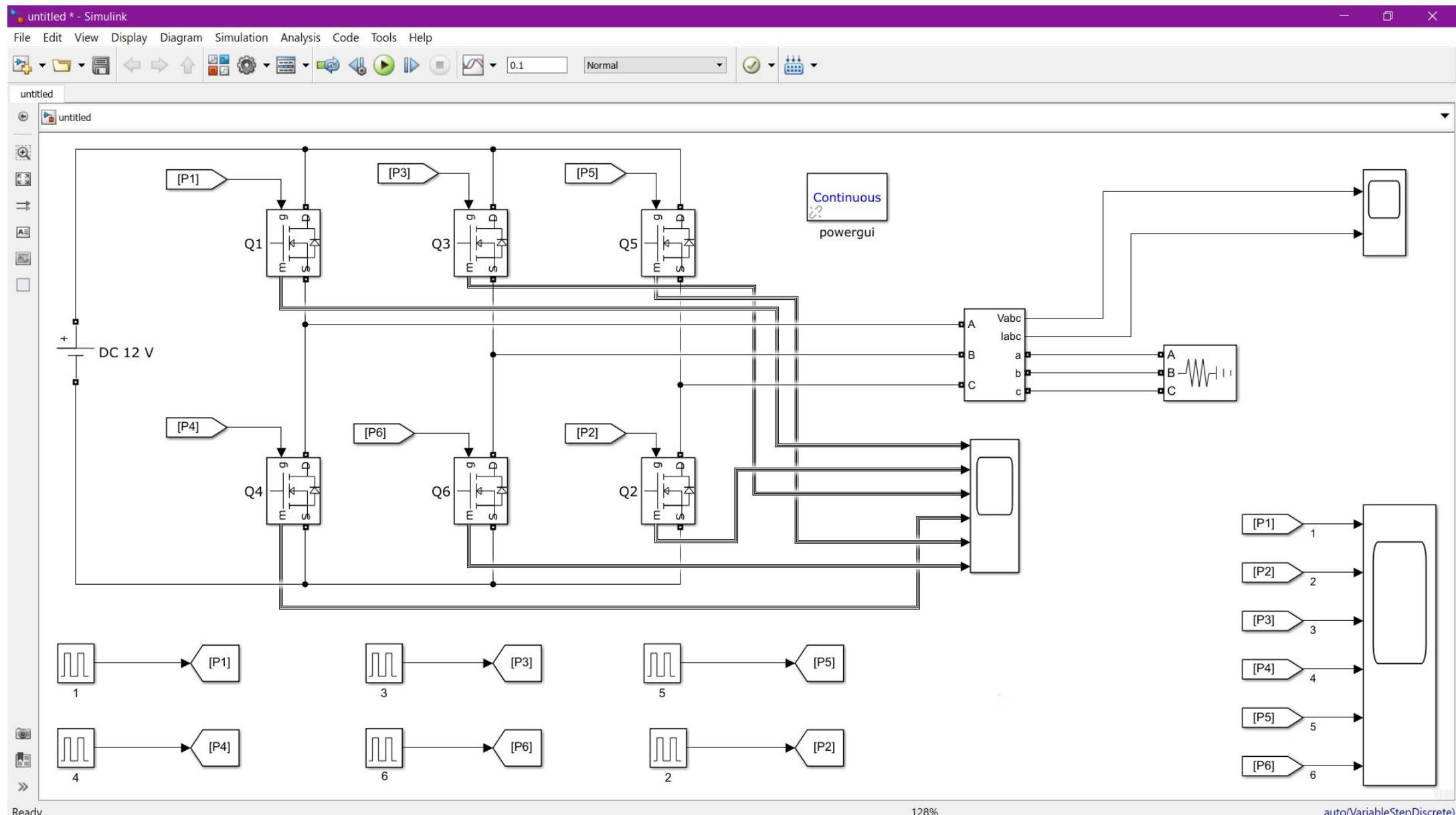


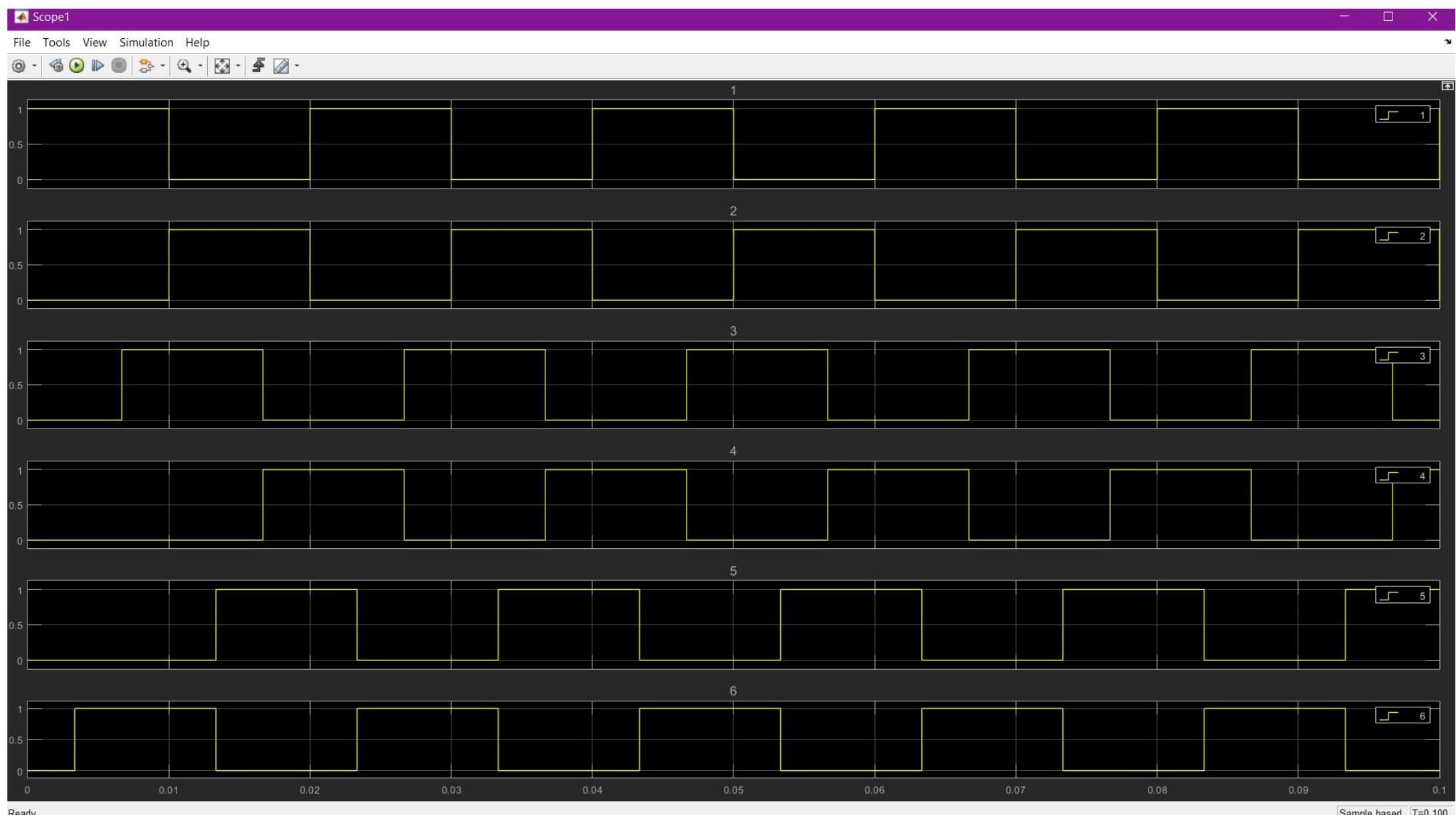


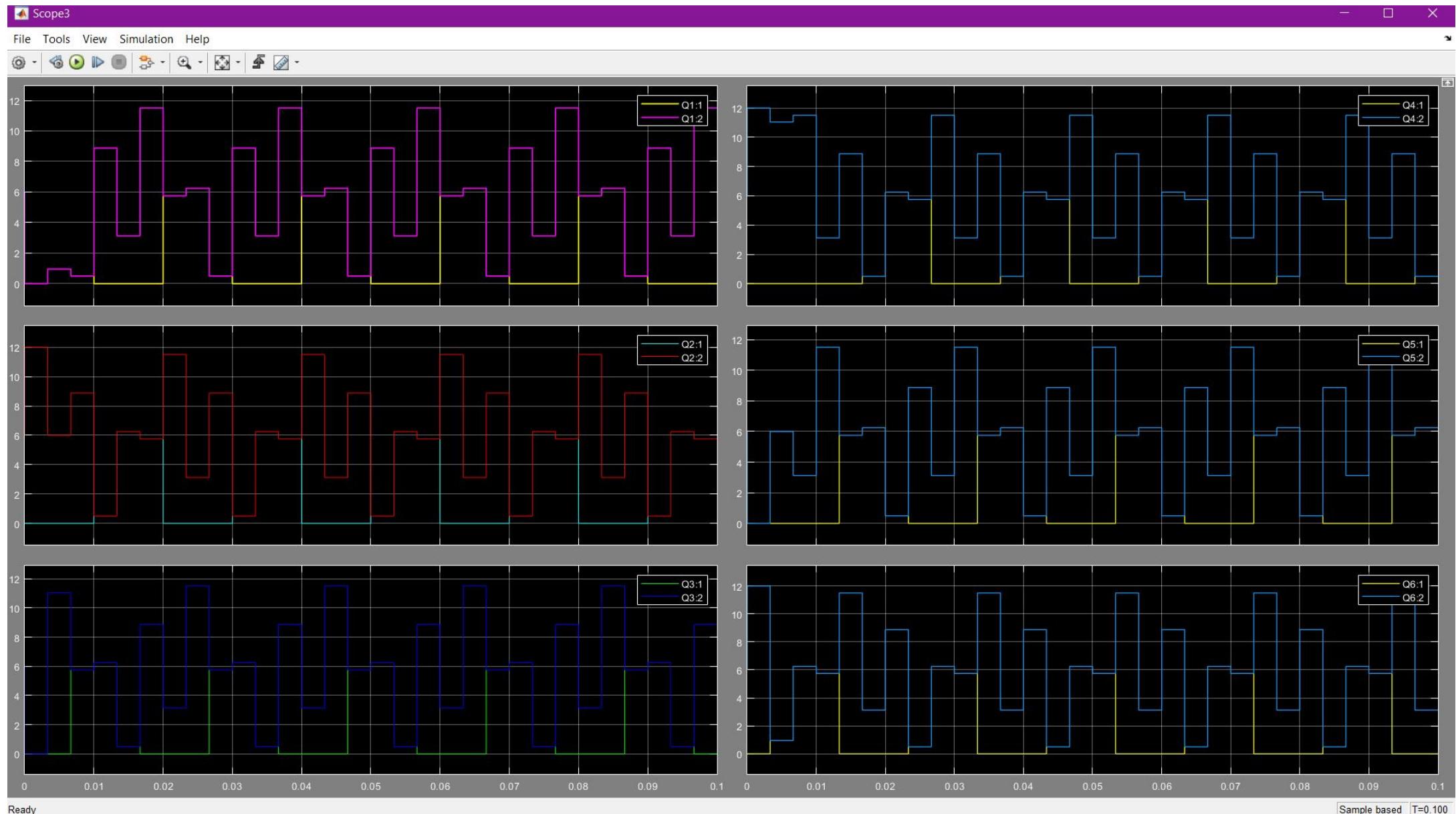


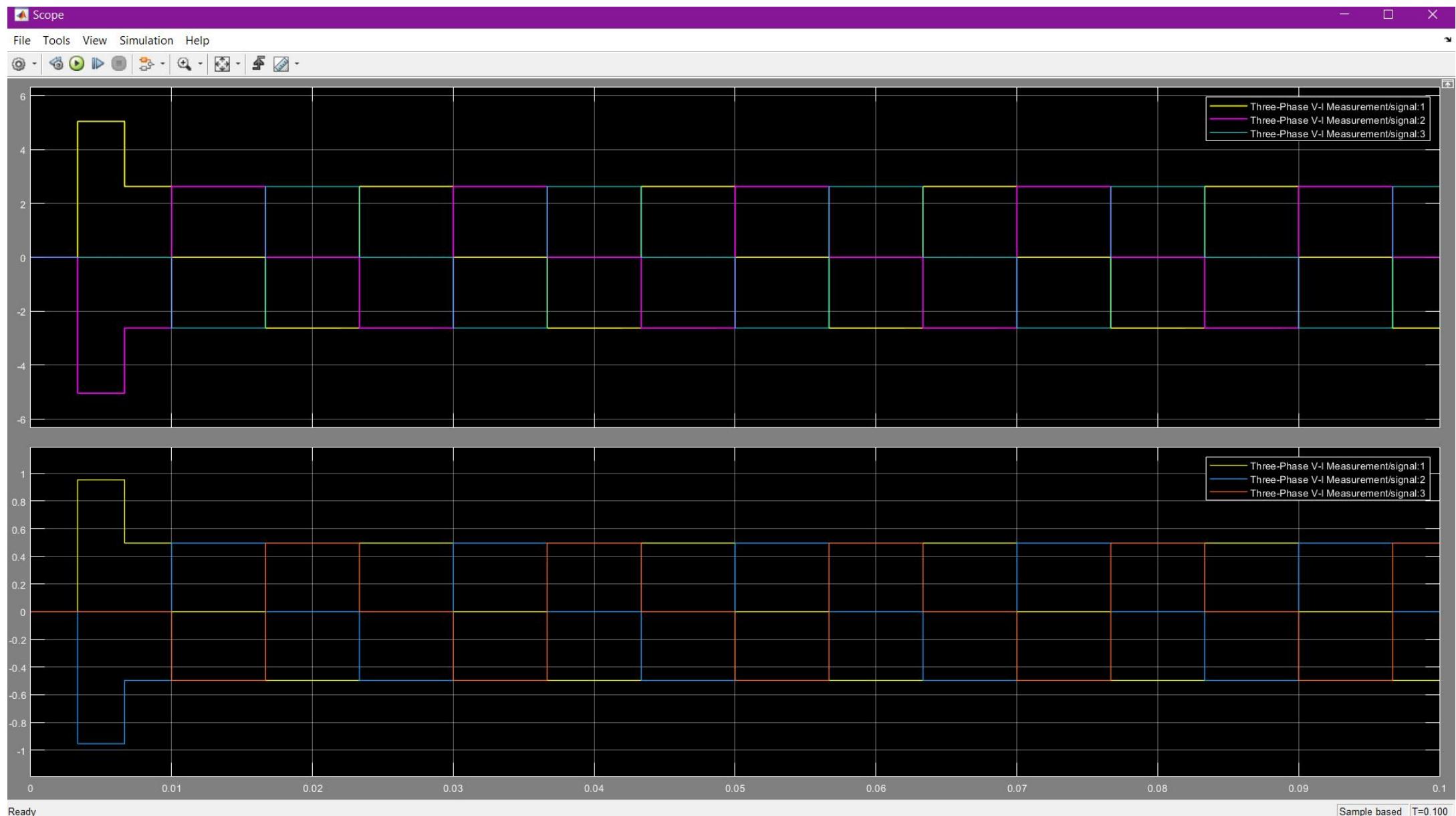


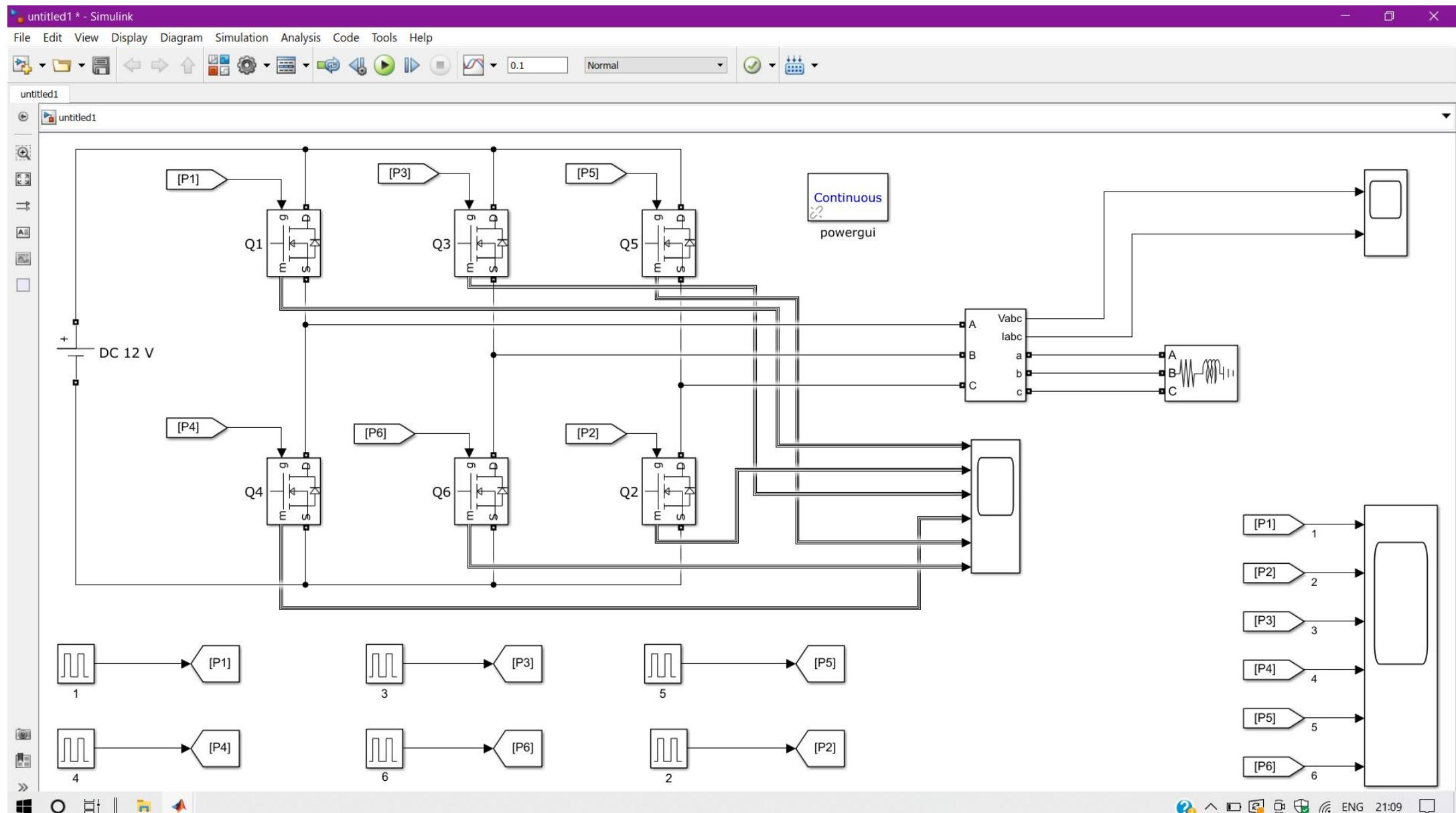


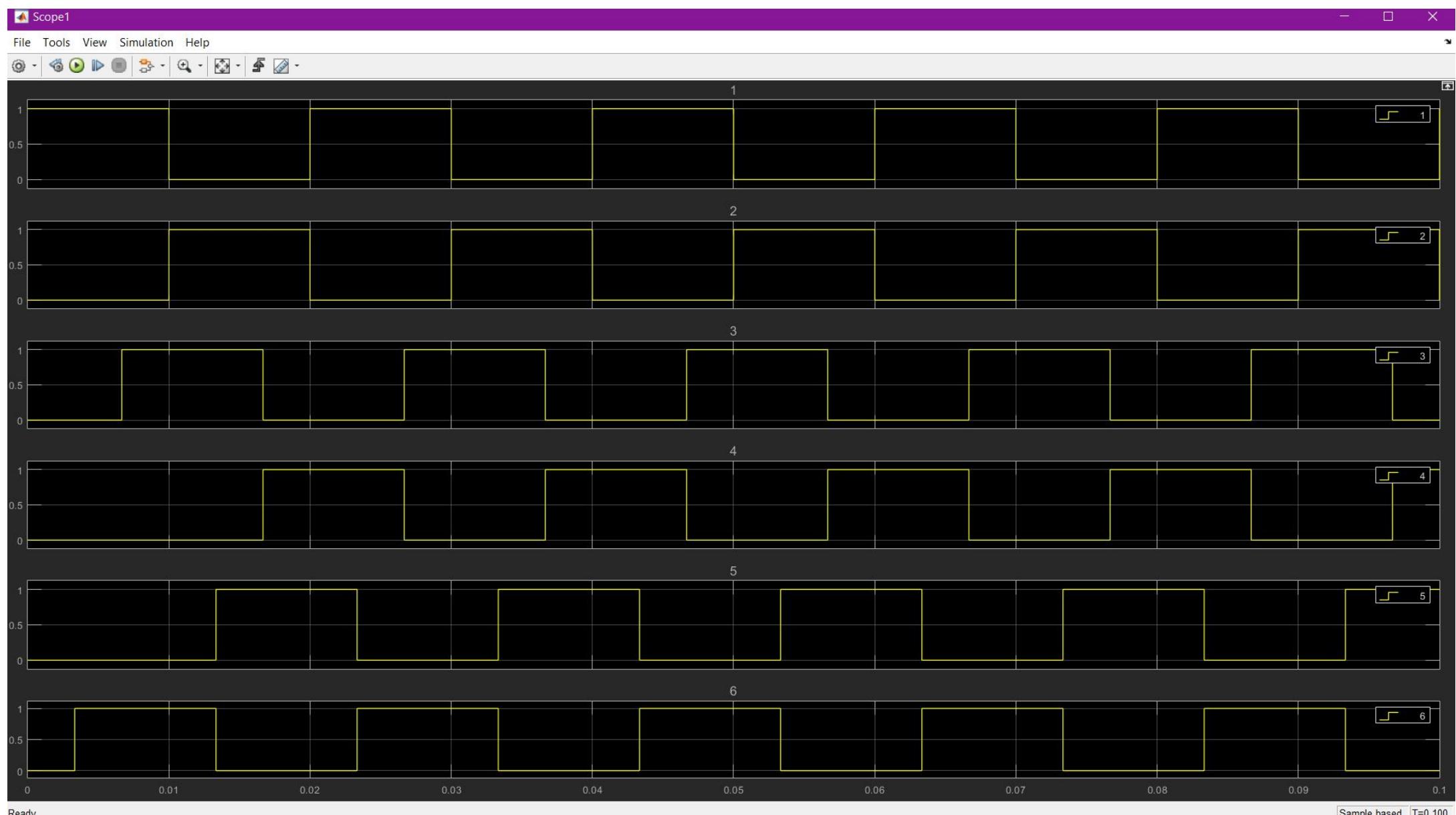


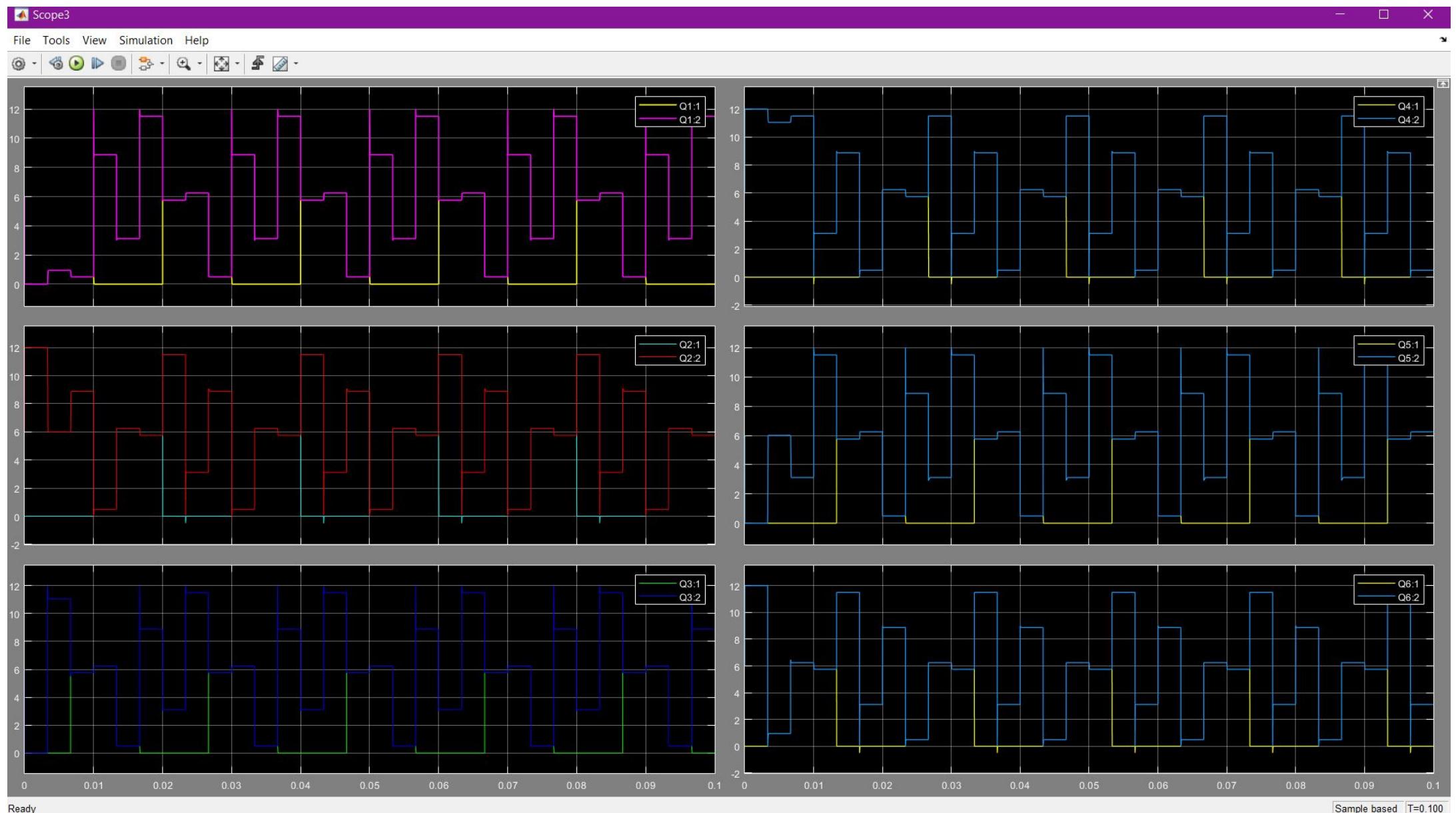


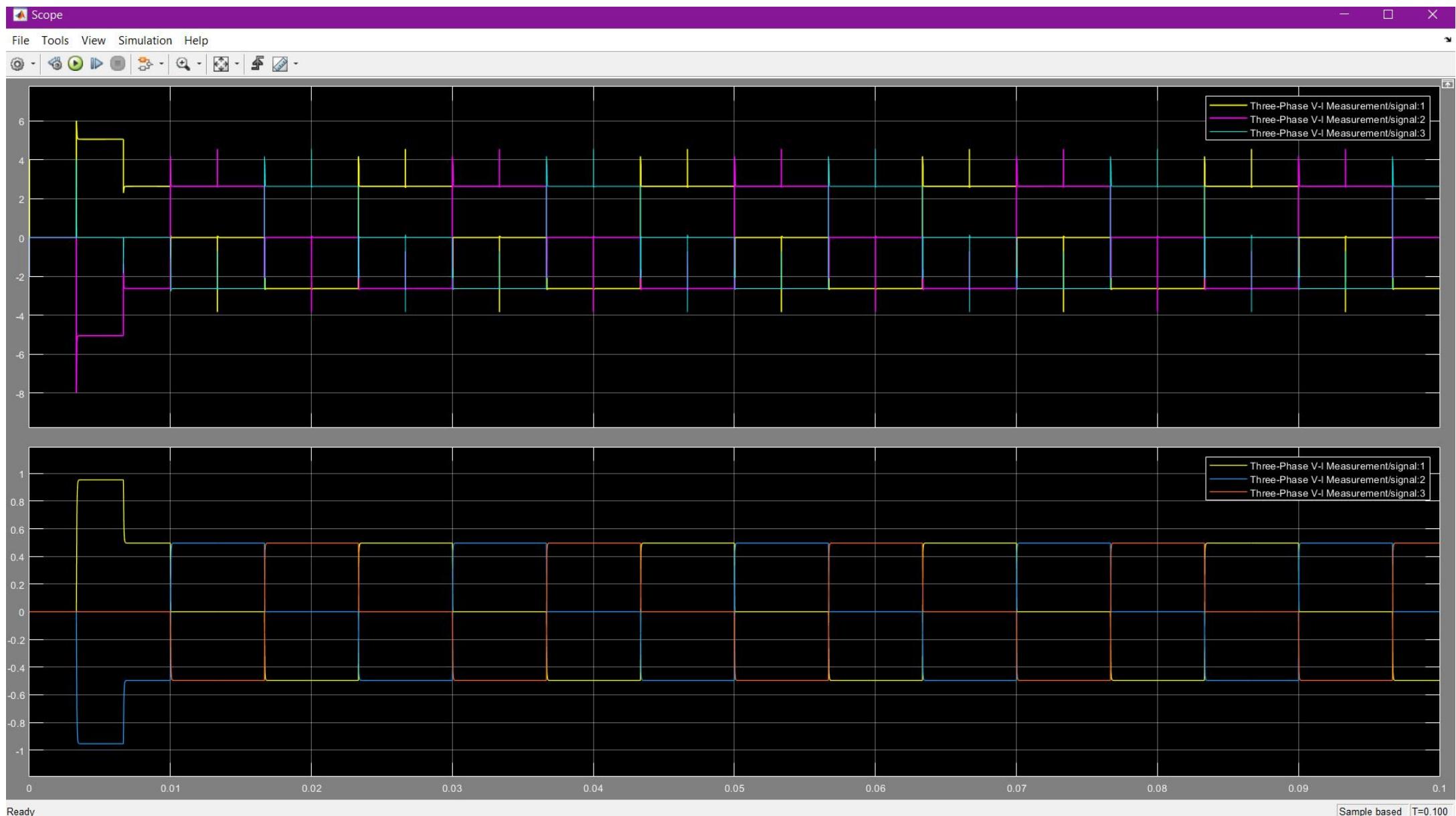












* Result: Simulated the 180° & 120° mode of conduction, voltage source inverter in R & RL load.

* Precautions:

1. Use powergui to store the equivalent simulink circuit that represents the state-space equation of the model.
2. Always keep the circuit closed.
3. MATLAB takes time to respond, do not give multiple ~~out~~ command at once.

Experiment - 9

- * Aim: To study and plot V-I characteristics of BJT using MATLAB.
- * Requirement: MATLAB software: SIMULINK
- * Theory: A BJT (bipolar Junction transistor) is a three terminal semiconductor device consisting of two p-n junction which are able to amplify or magnify a signal. It is a current controlled device. The three terminals of BJT are base, collector and emitter.

NPN BJT:

In a npn transistor, one p-type semiconductor resides between two n-type semiconductors. I_E , I_C is emitter current & collect current resp. V_{EB} and V_{CB} are emitter base & collector base voltage resp.

PNP BJT:

In a pnp transistor, one n-type semiconductor resides between two p-type semiconductor. Current enters into the transistor through the emitter terminal.

* Diagram:

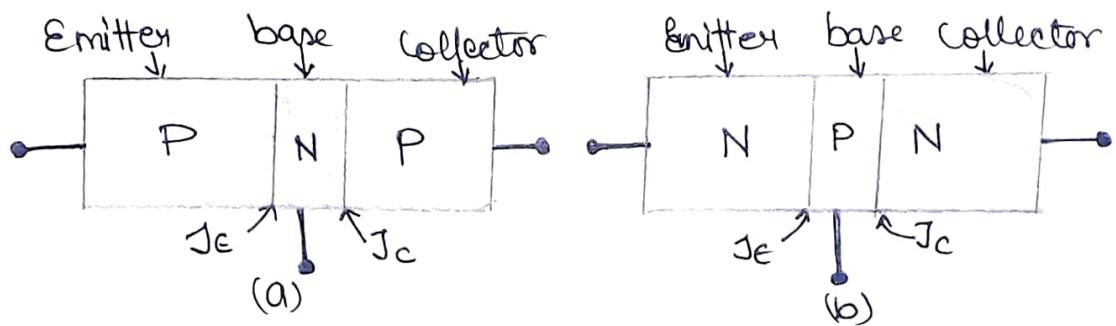


Fig.1: Diagram of BJT: (a) pnp & (b) npn

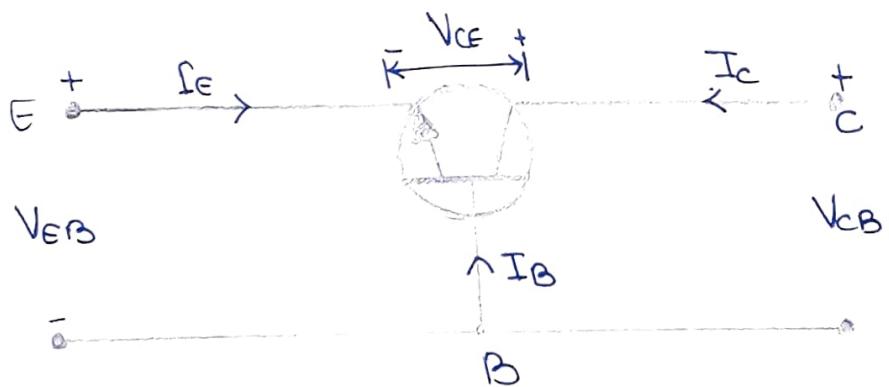


Fig.2: NPN BJT circuit

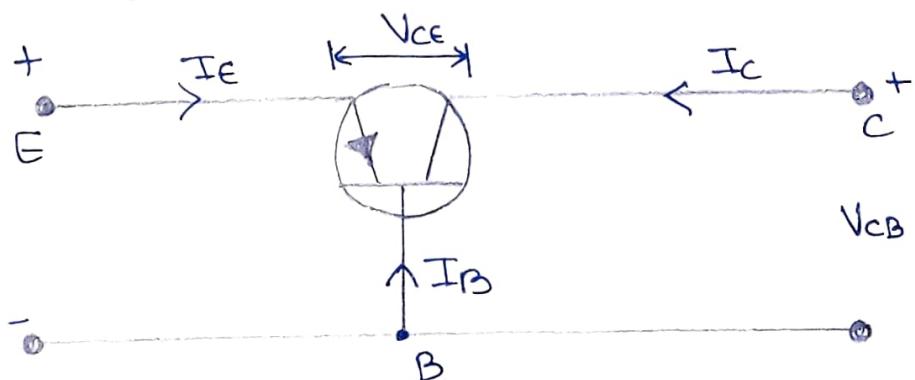
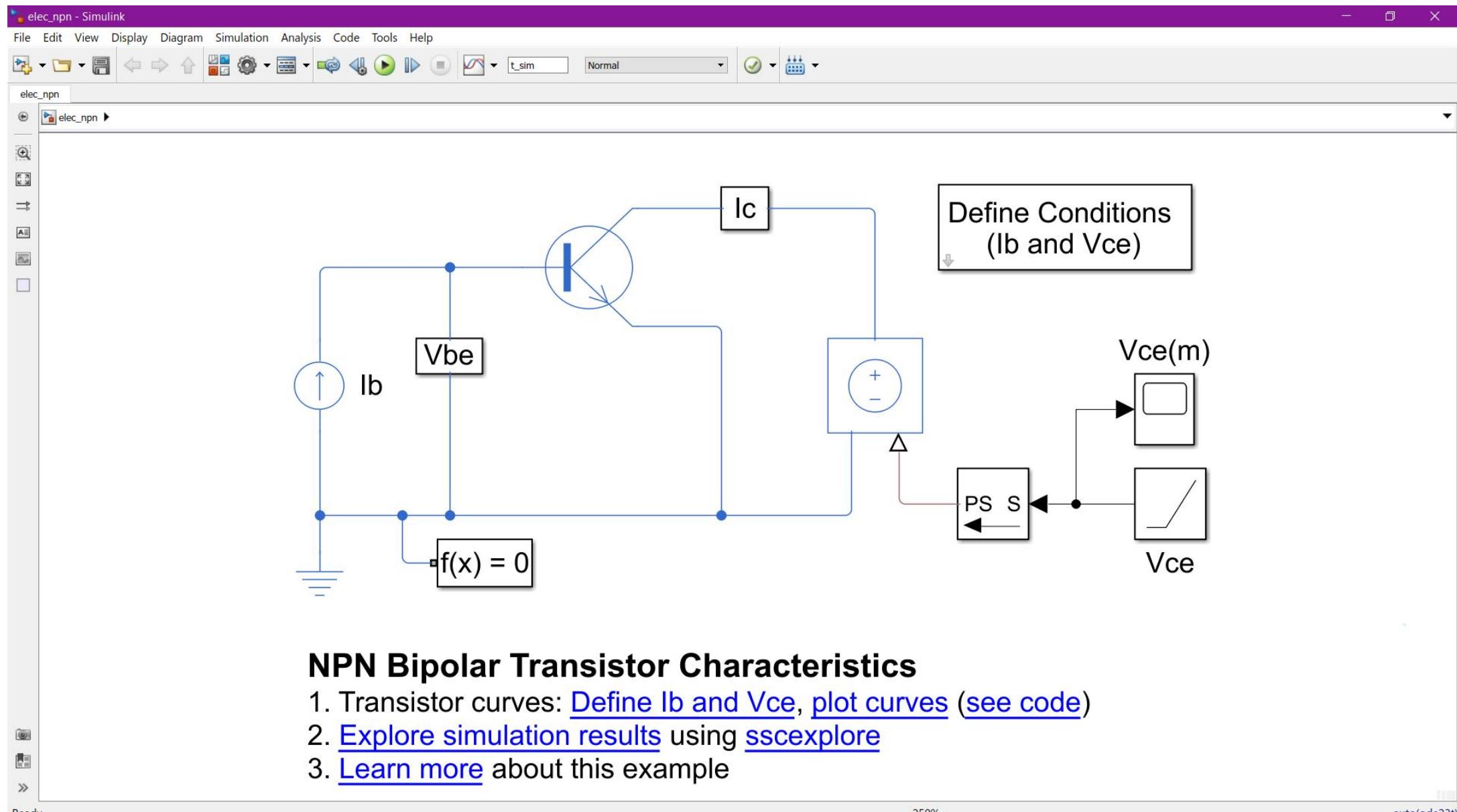


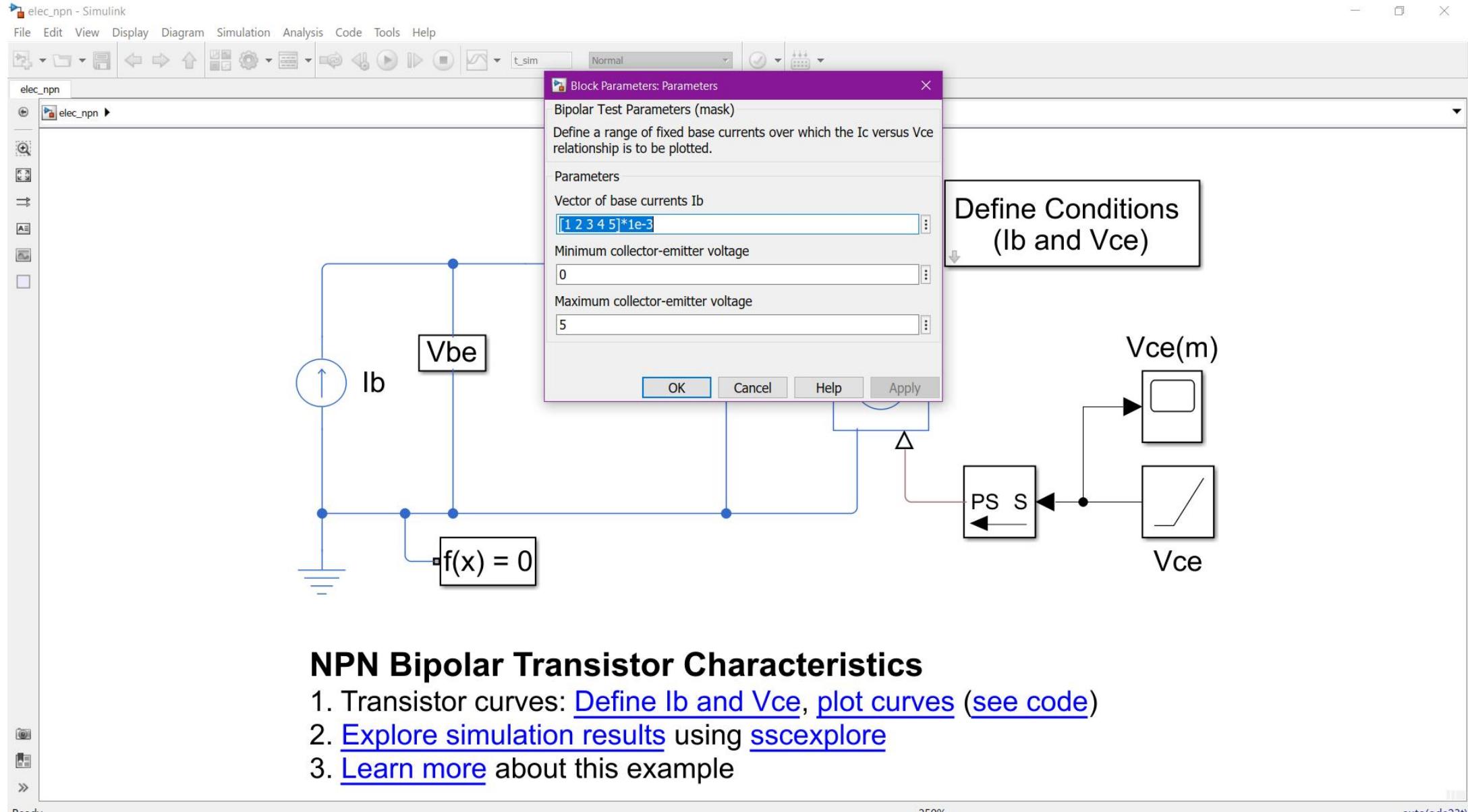
Fig.3: PNP BJT circuit

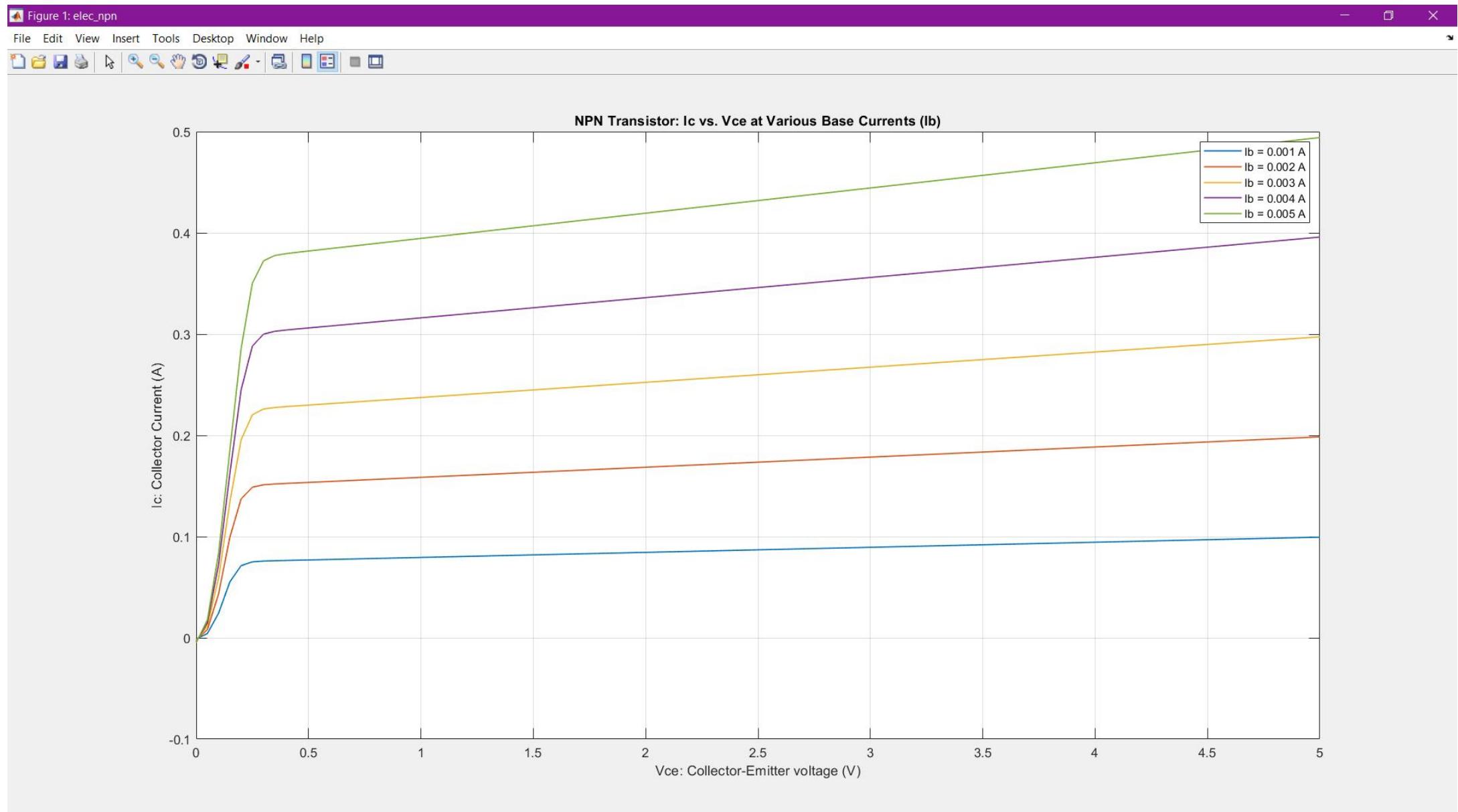
MATLAB Simulation

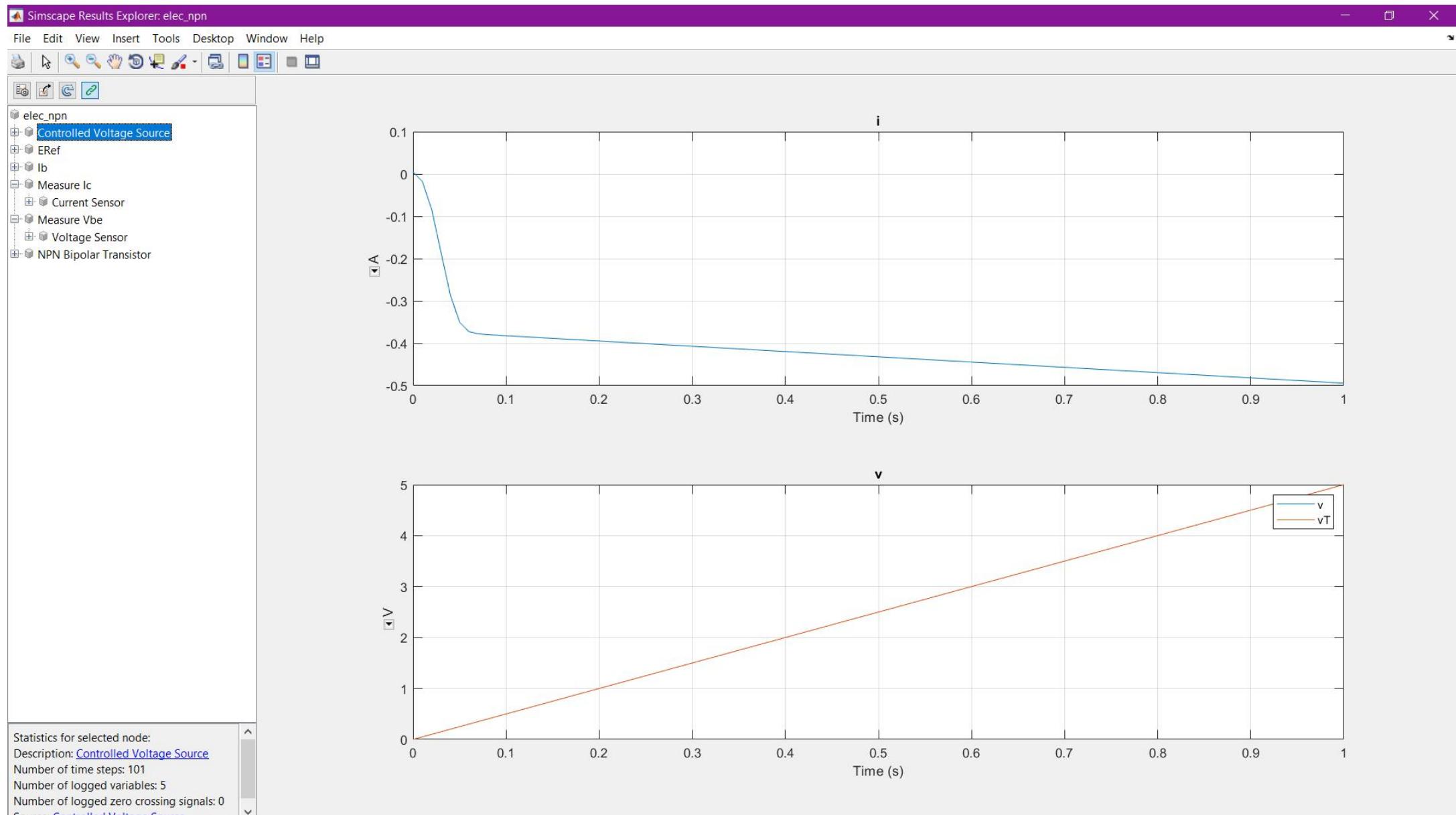


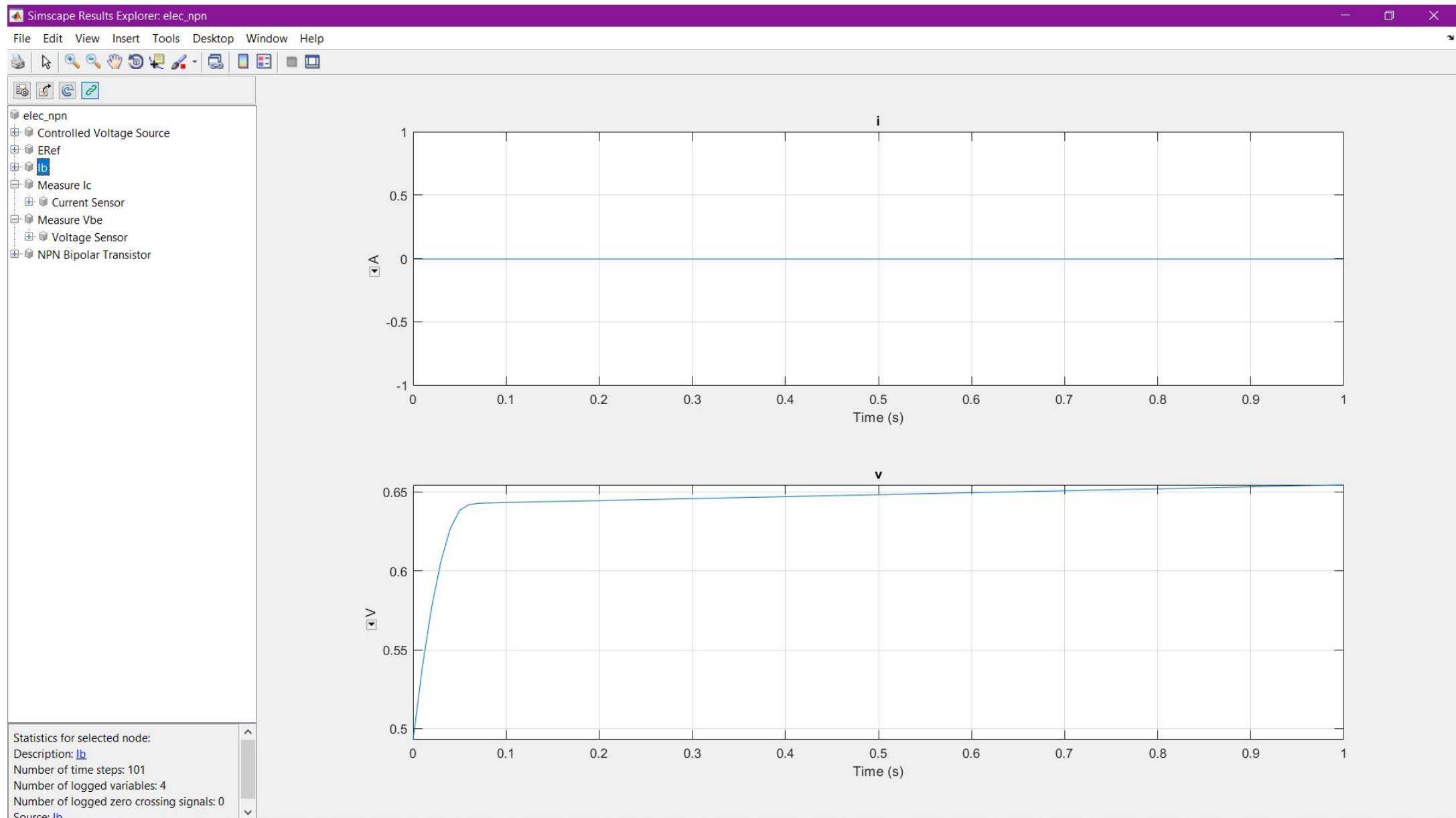
NPN Bipolar Transistor Characteristics

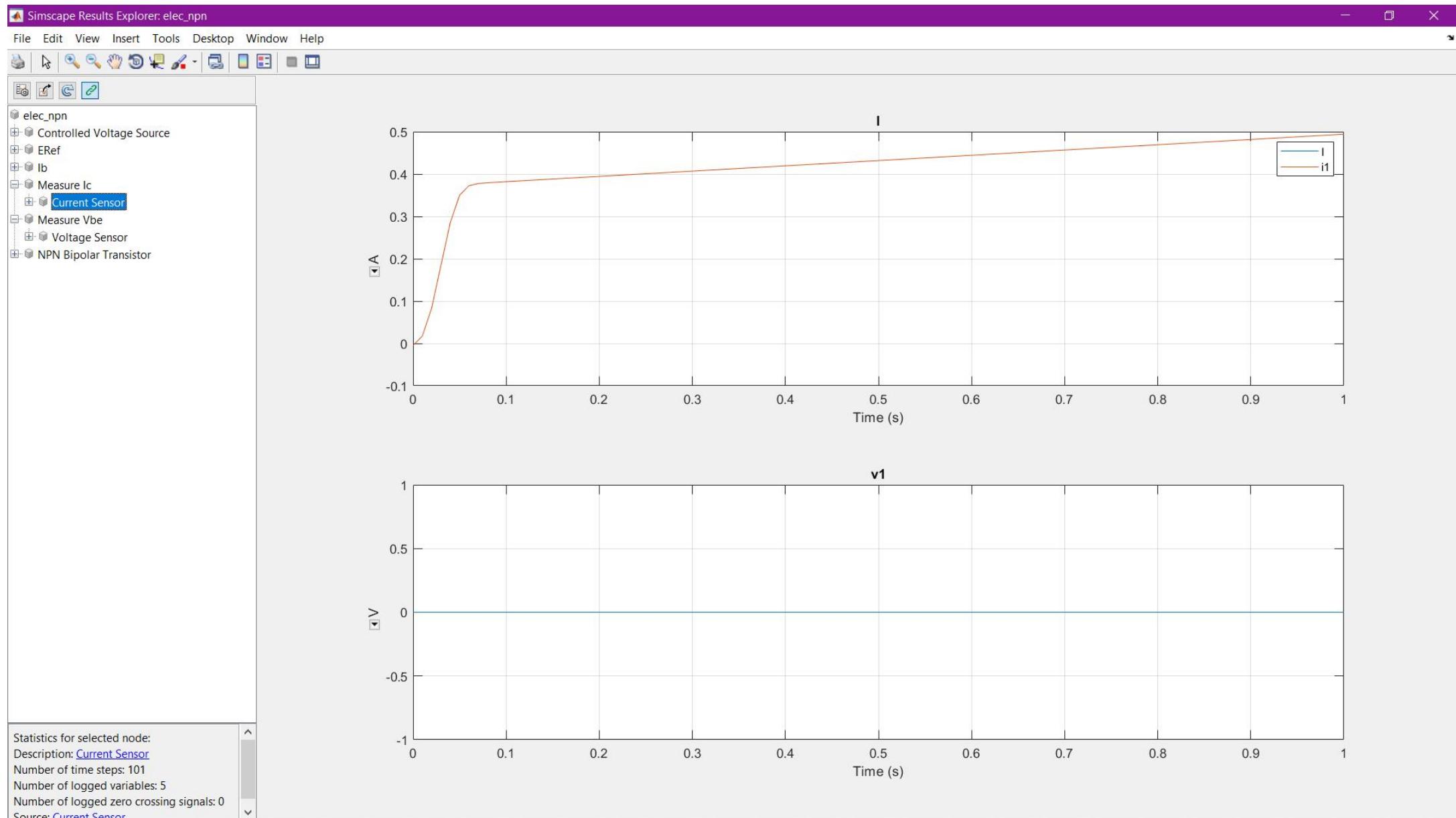
1. Transistor curves: [Define \$I_b\$ and \$V_{ce}\$, plot curves \(see code\)](#)
2. [Explore simulation results](#) using [sscexplore](#)
3. [Learn more](#) about this example

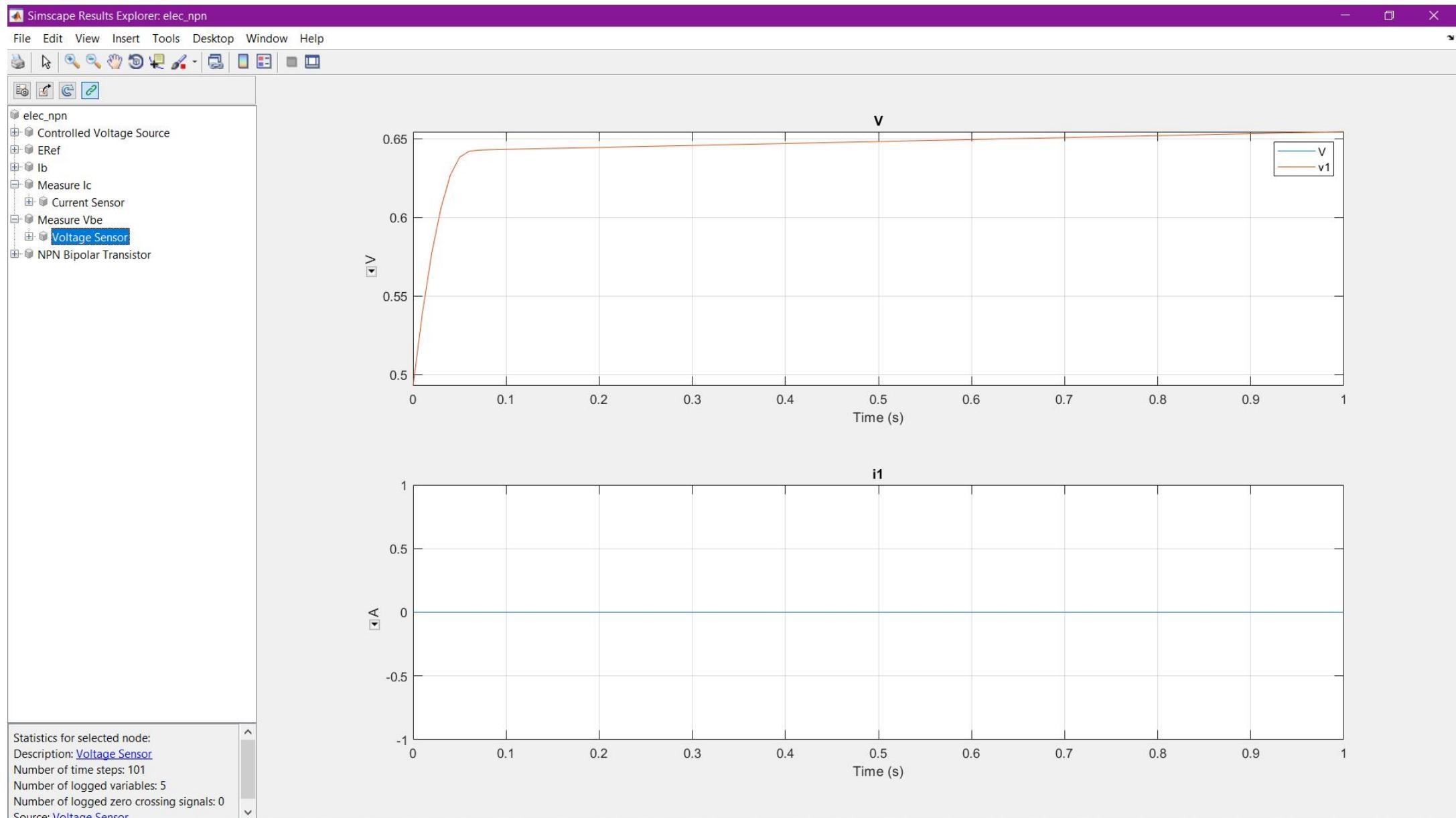


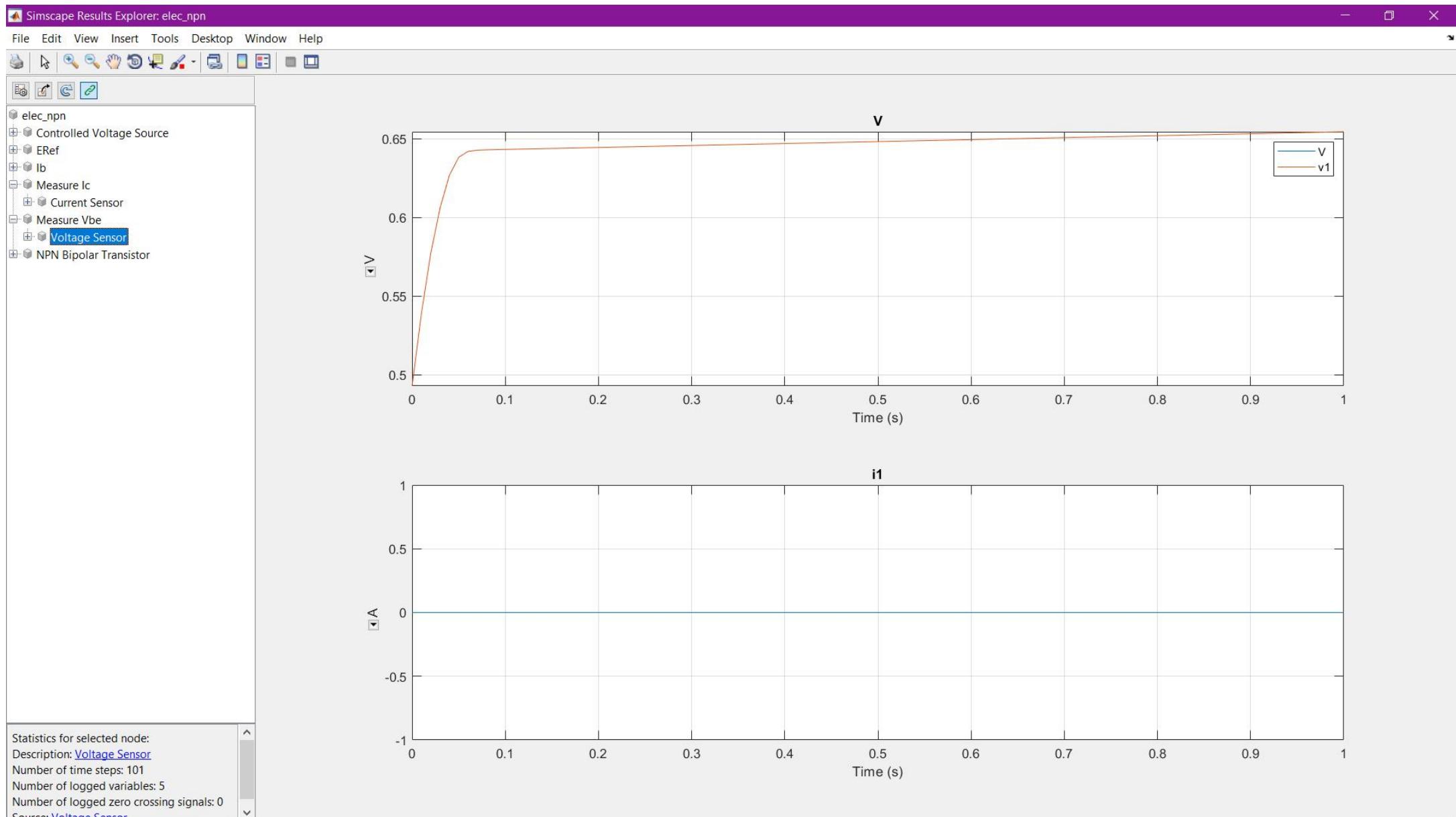




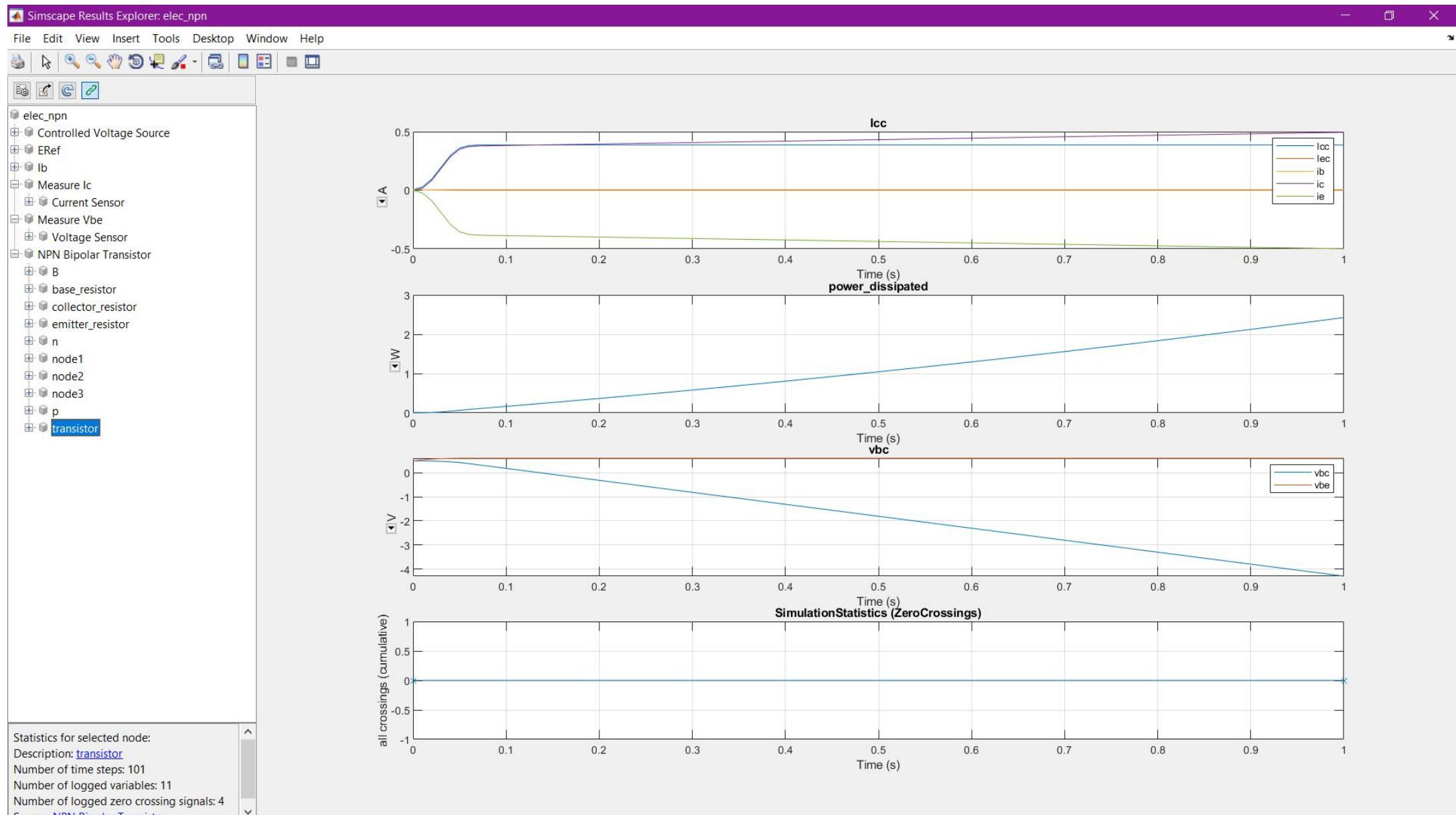


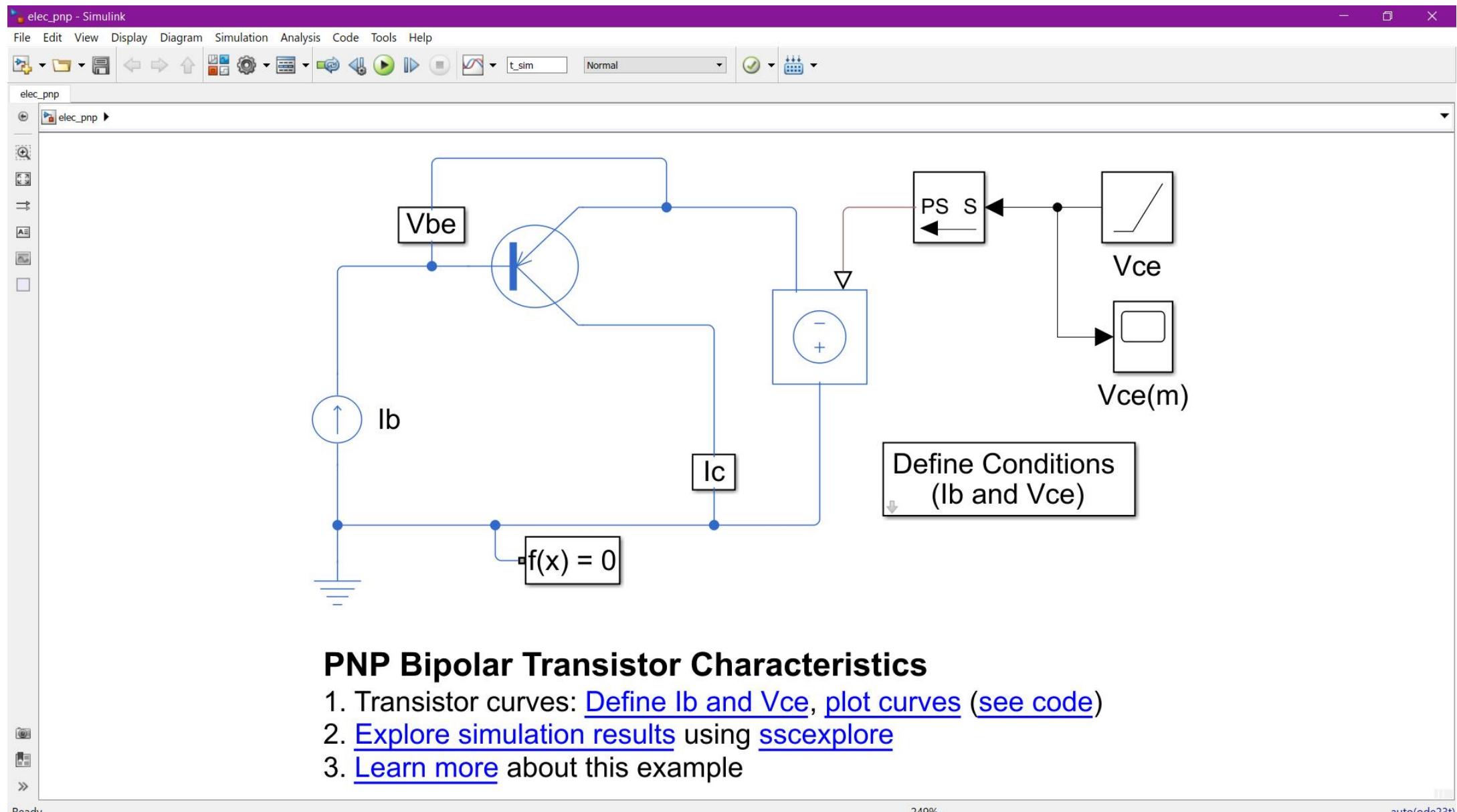






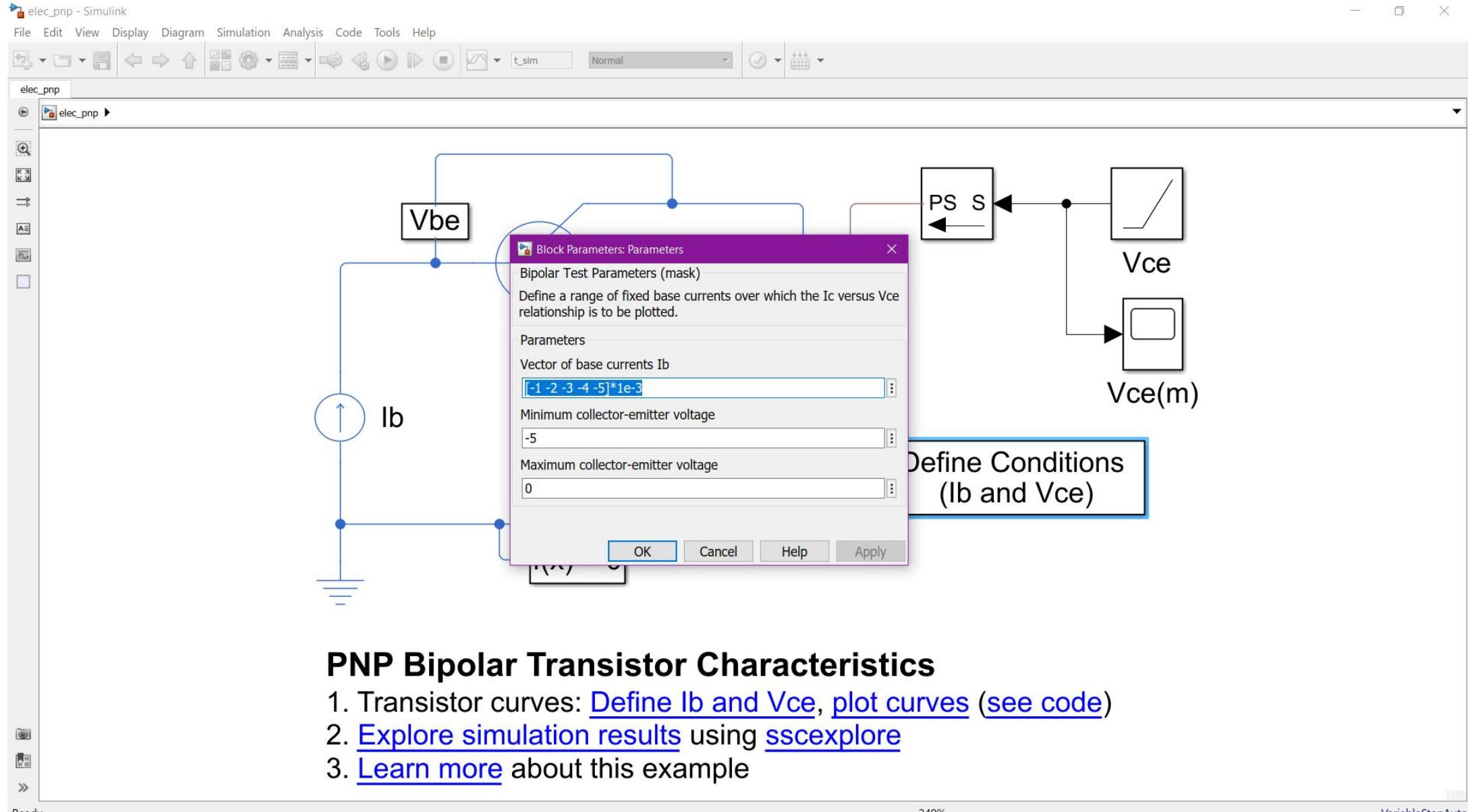
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Description: [Voltage Sensor](#)
Number of time steps: 101
Number of logged variables: 5
Number of logged zero crossing signals: 0
Source: [Voltage Sensor](#)





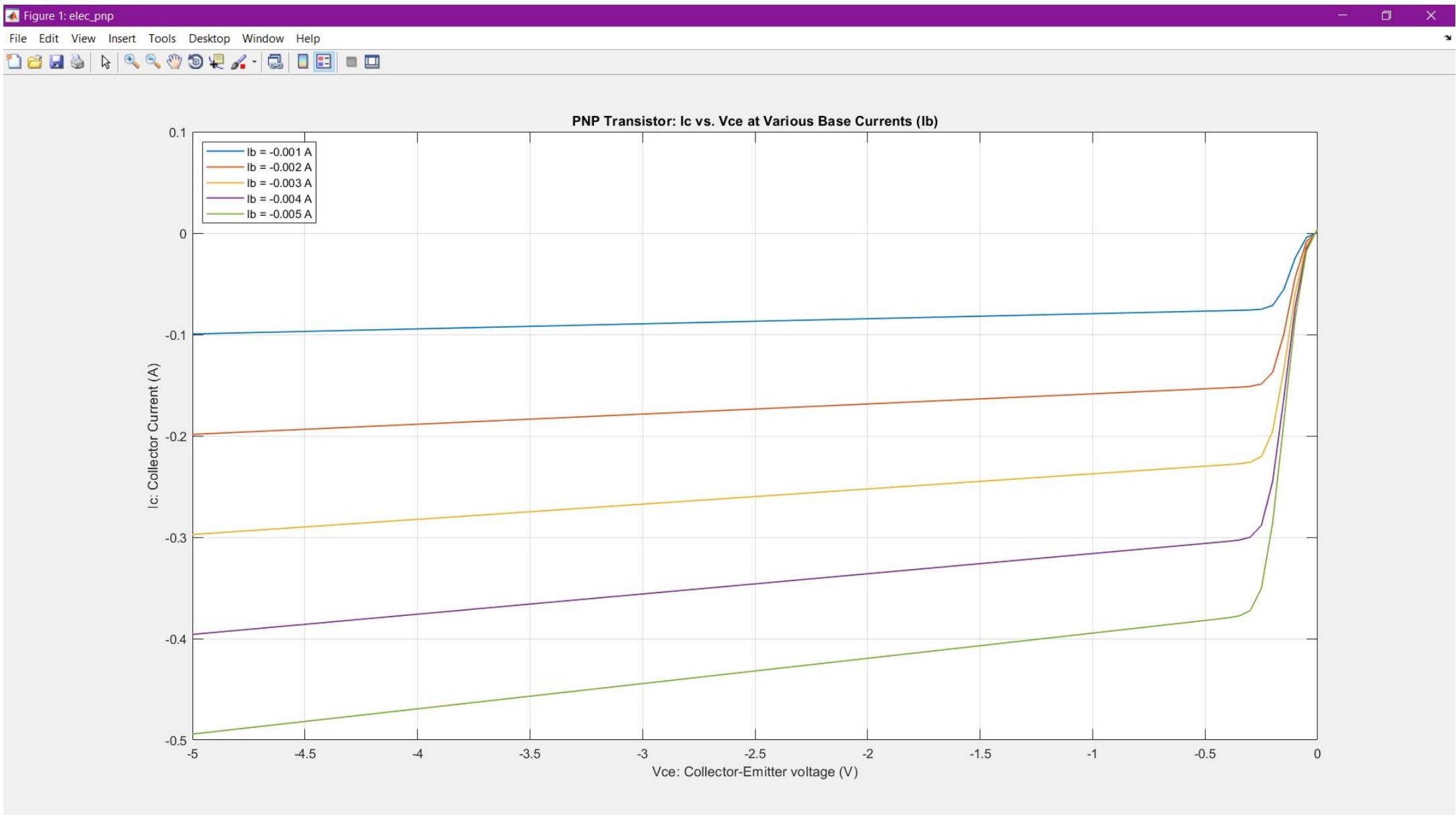
PNP Bipolar Transistor Characteristics

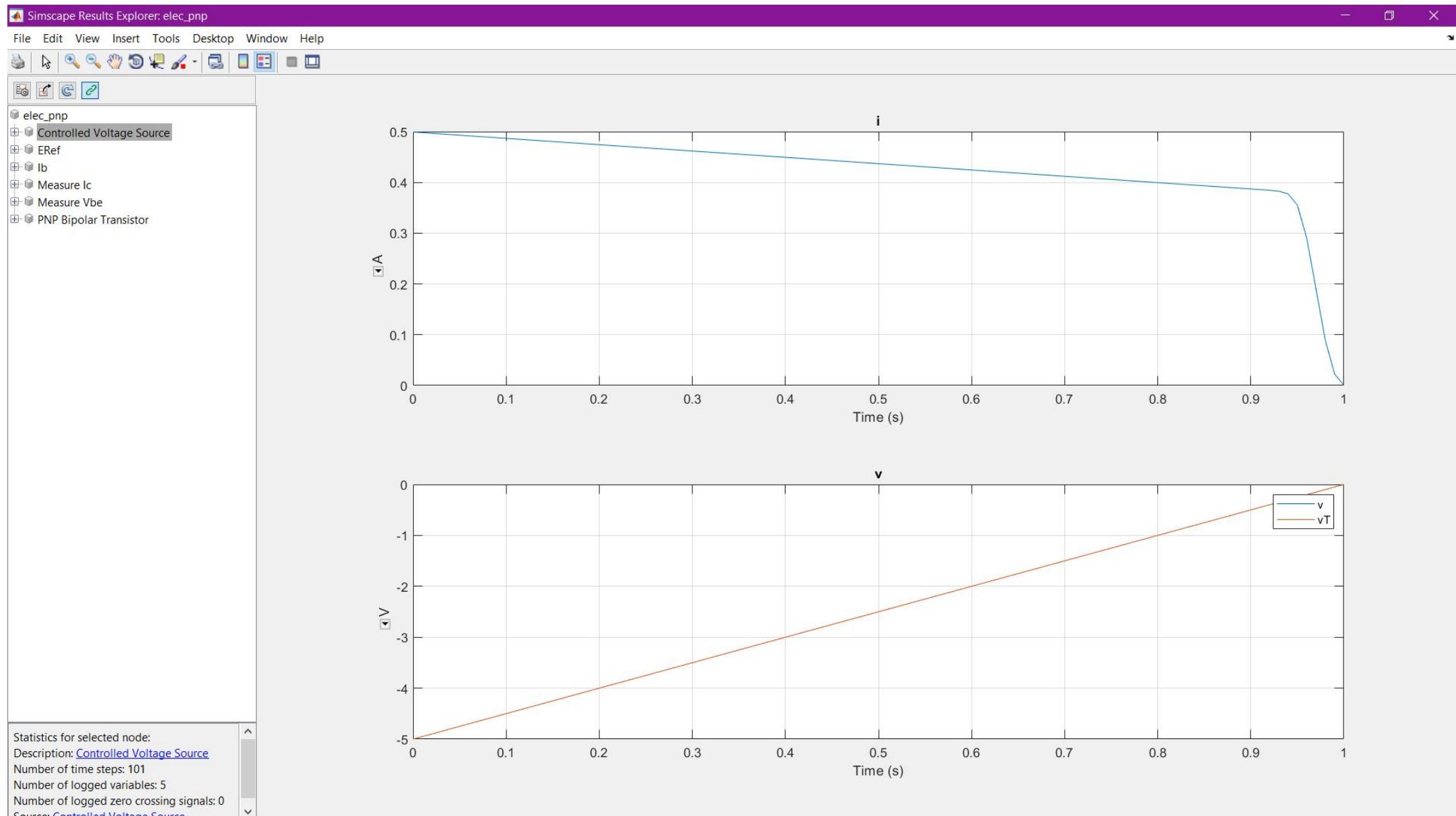
1. Transistor curves: [Define Ib and Vce, plot curves \(see code\)](#)
2. [Explore simulation results](#) using [ssceexplore](#)
3. [Learn more about this example](#)

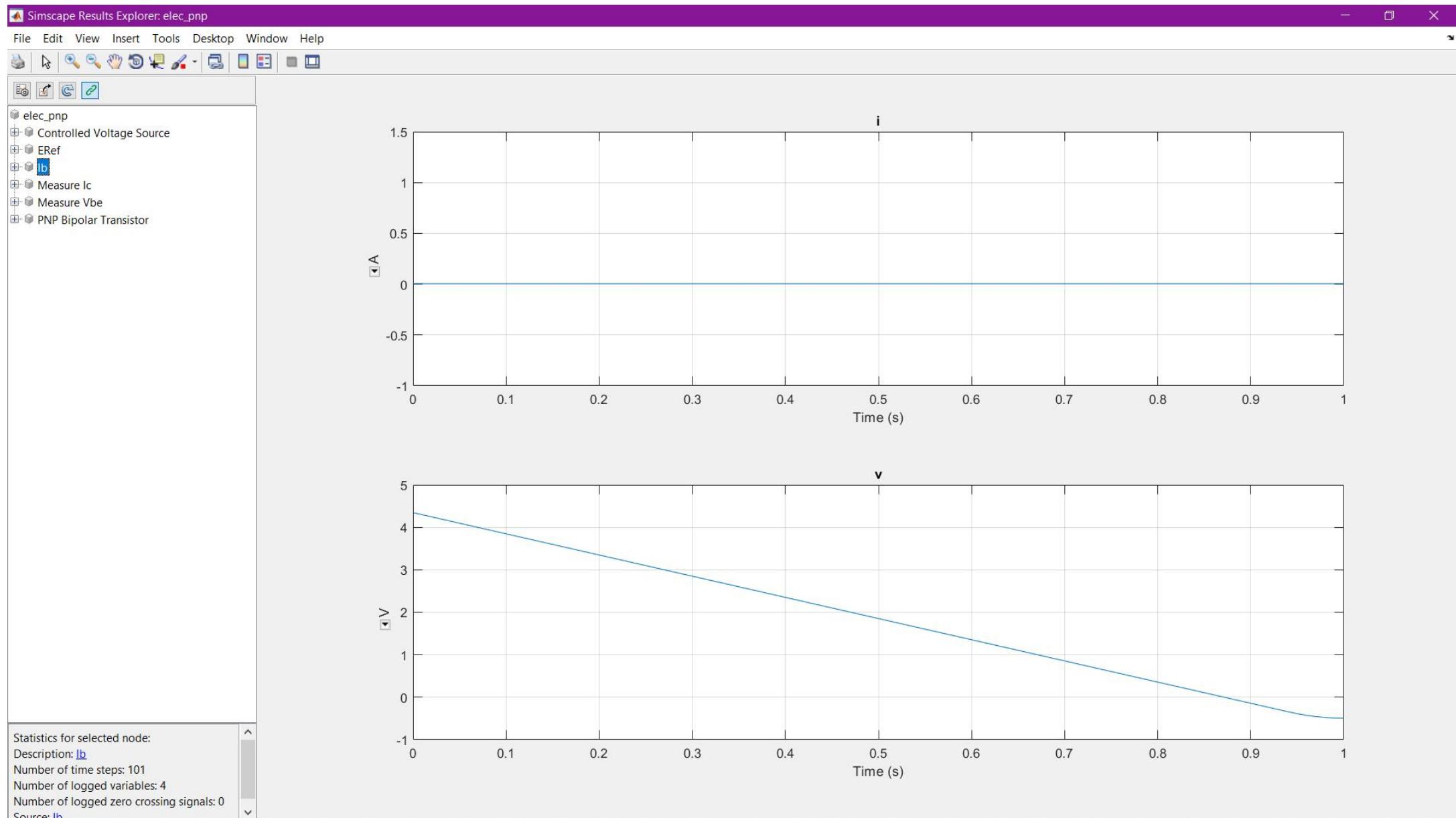


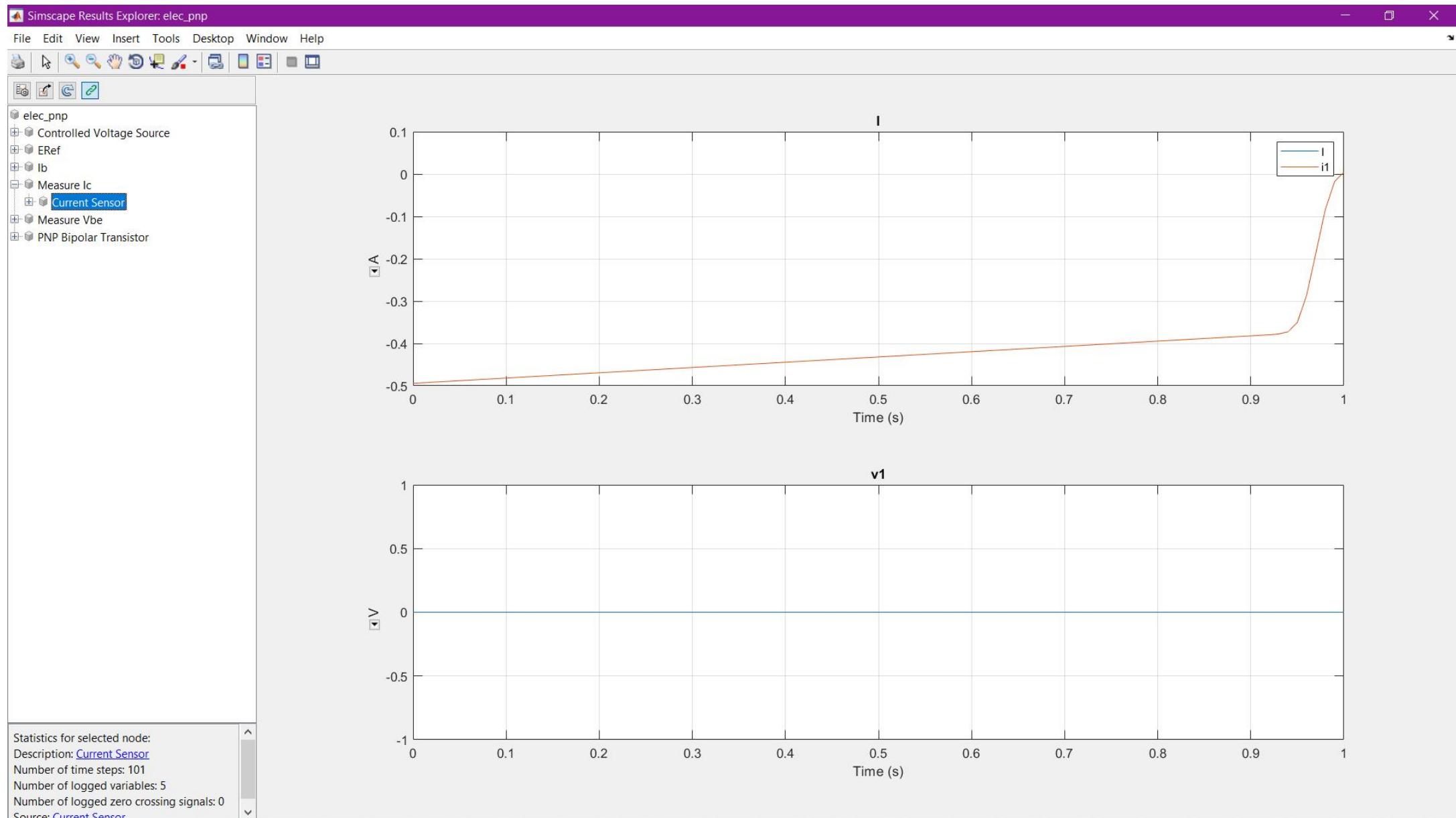
PNP Bipolar Transistor Characteristics

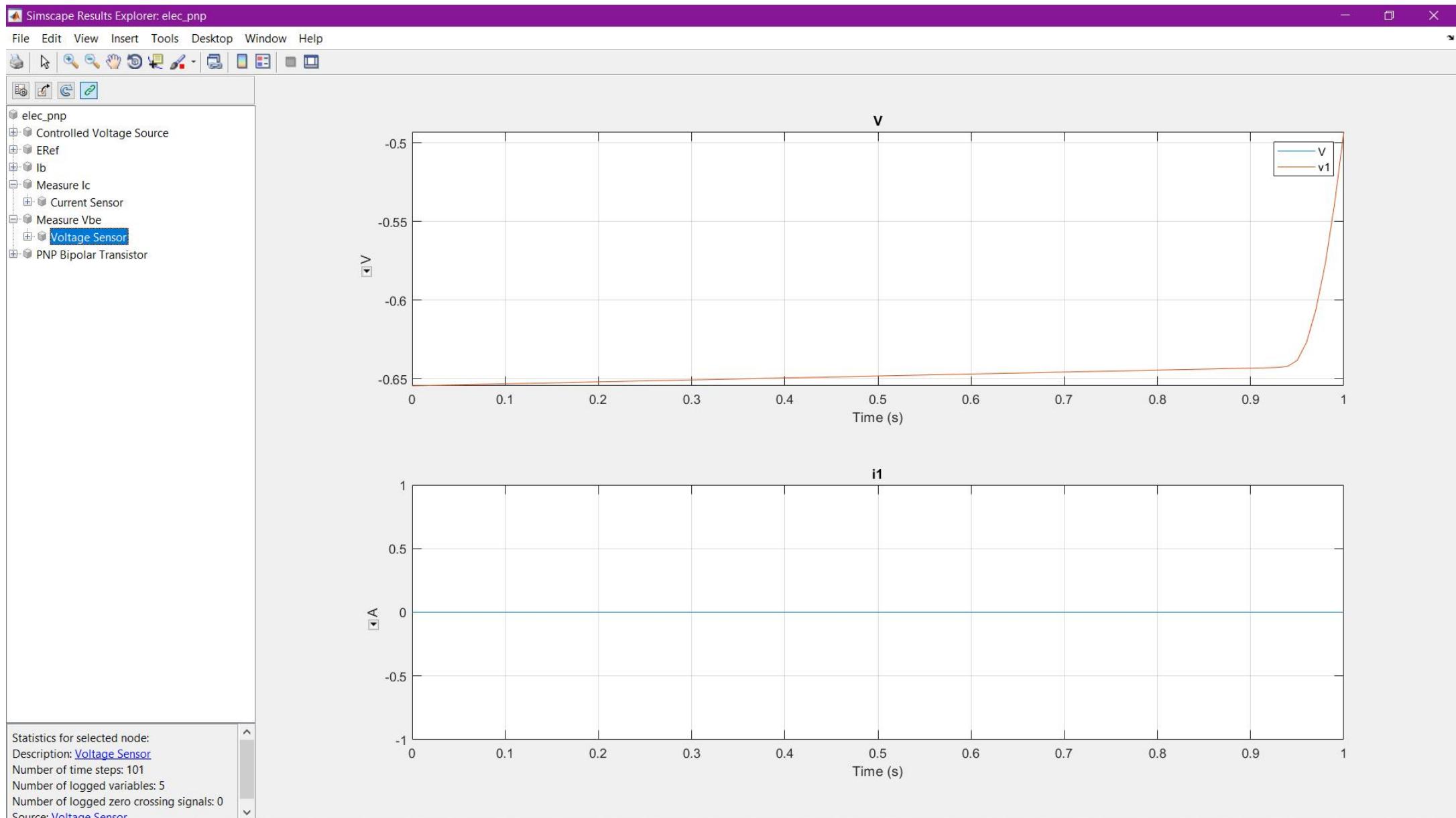
1. Transistor curves: [Define Ib and Vce, plot curves \(see code\)](#)
2. [Explore simulation results](#) using [ssceexplore](#)
3. [Learn more about this example](#)

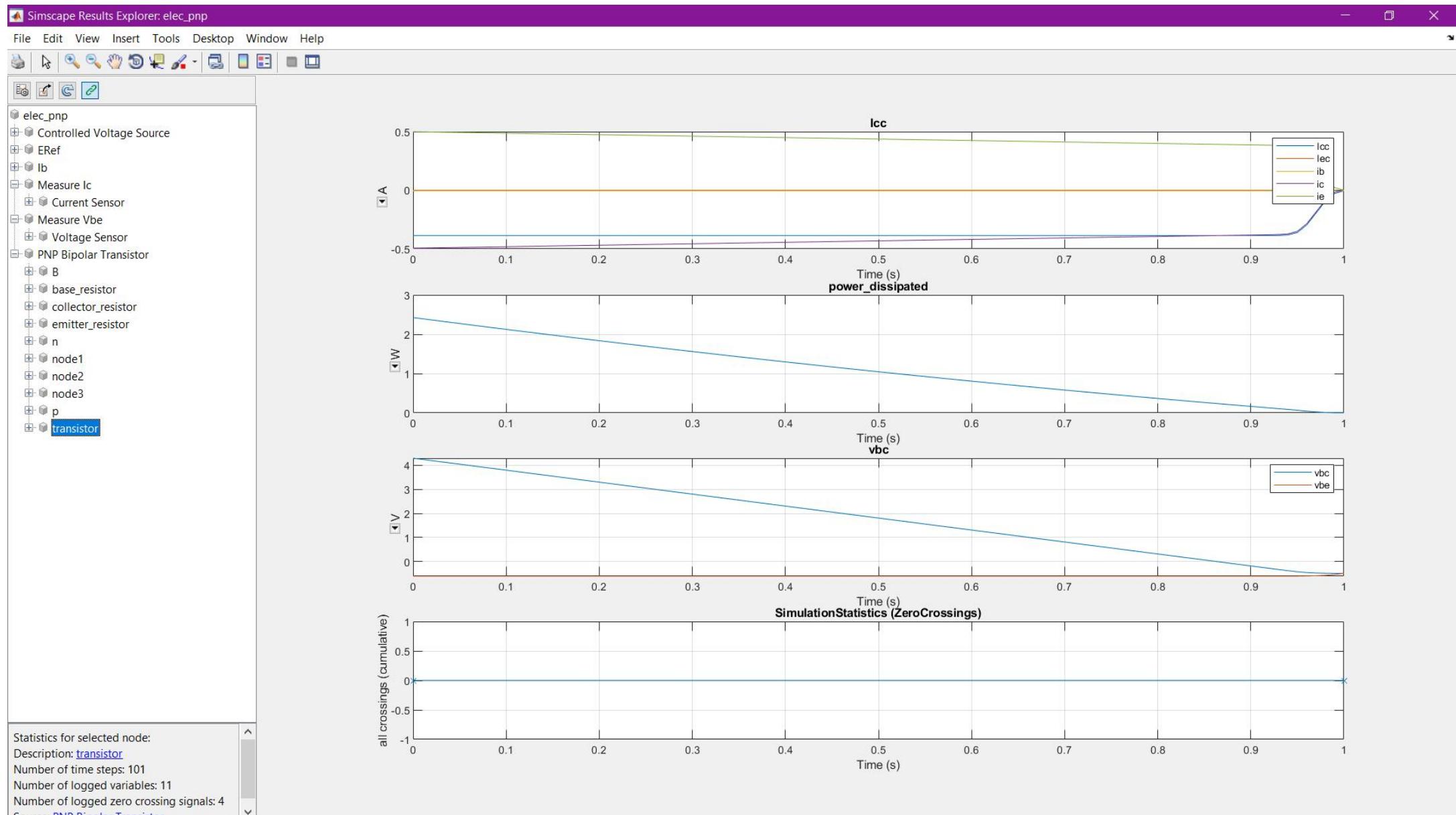












* Procedure:

1. Open MATLAB and in command window write : "elec_npn" (for npn bjt) and press enter.
2. A simulation circuit will appear ; (change the values if required) and run the simulation.
3. ~~You will~~ After simulation, click on plot curve and observe the characteristics graph.
4. For more observation click on Explore simulation results.
5. Repeat it for pnp bjt with code "elec-pnp".

* Result: Studied and observed VI characteristics of npn & pnp BJT transistor. Using MATLAB Simulink.

* Precautions:

1. Don't give multiple command at a time.
2. Do not change the circuit until required of the file as its inbuilt example.

Experiment - 10

- * Aim: To study the VI characteristics of MOSFET
- * Requirement: Software : MATLAB - Simulink.

* Theory:

Mosfet are tri-terminal, unipolar, voltage controlled high input impedance device. MOSFET i.e metal oxide semiconductor field effect transistor. In general Mosfet is seen to exhibit three operating regions

1. Cut-off region : OFF ; as there is no current flow. Mosfet behave like an open switch and is thus used when they are required to function as electronic switches.
2. Ohmic / Linear region: current I_{DS} increases with an increase value of V_{DS} . In this region it acts as an amplifier
3. Saturation region: I_{DS} become constant inspite of increase in V_{DS} , V_{DS} exceeds the value of pinch-off voltage V_p . Now it will acts as closed switch

*

Diagram :

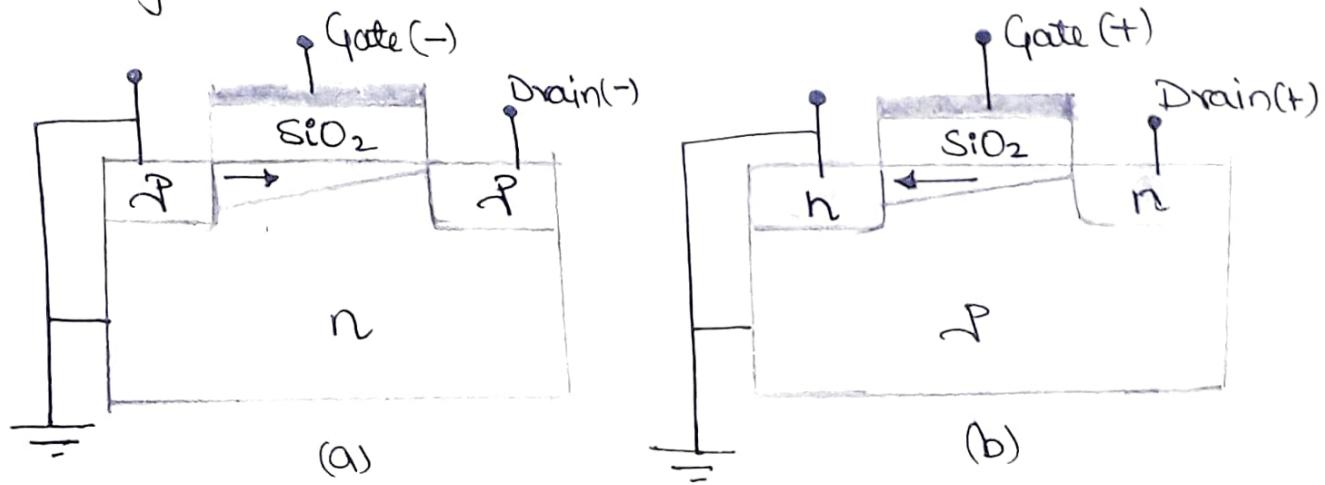
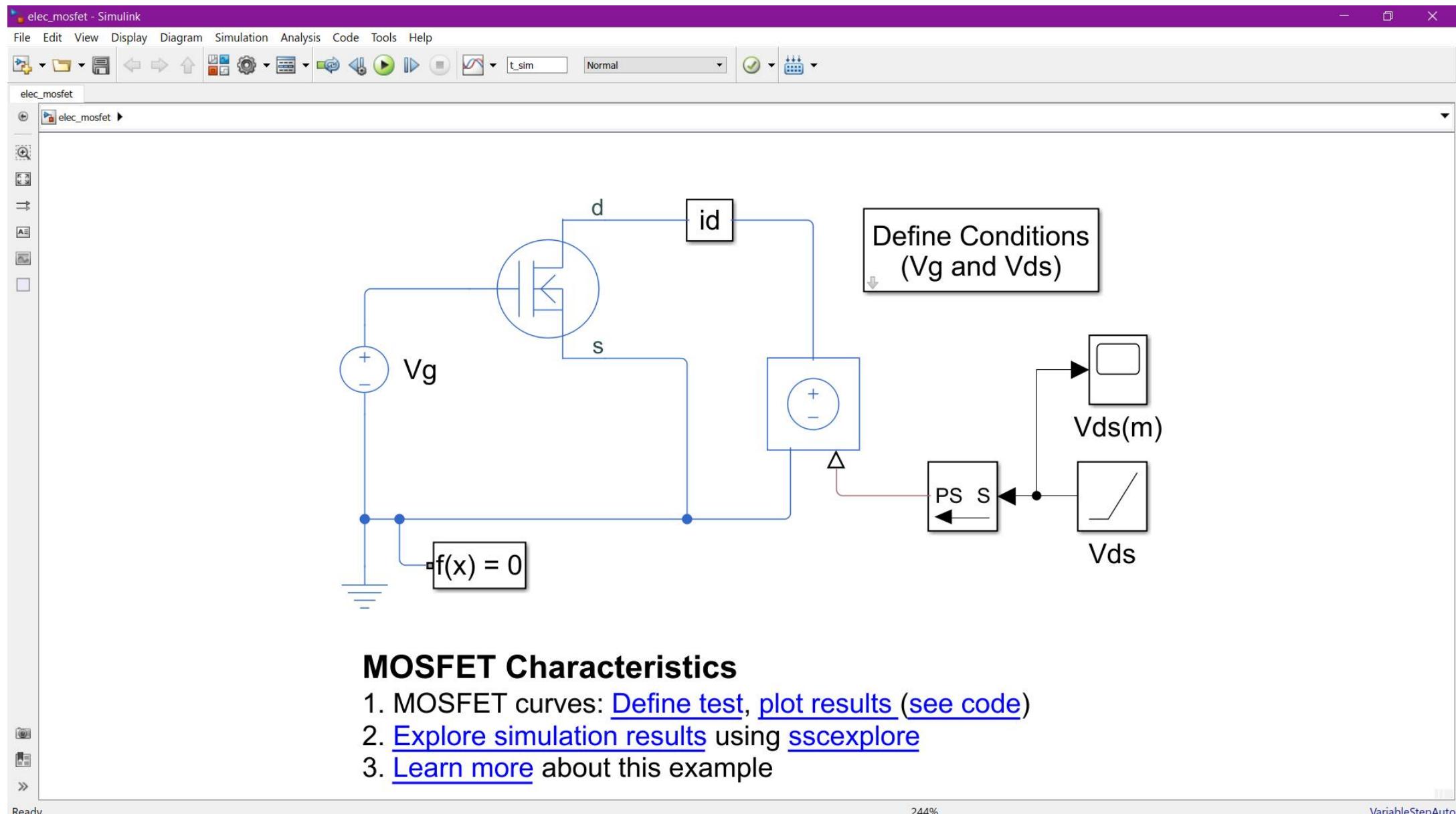


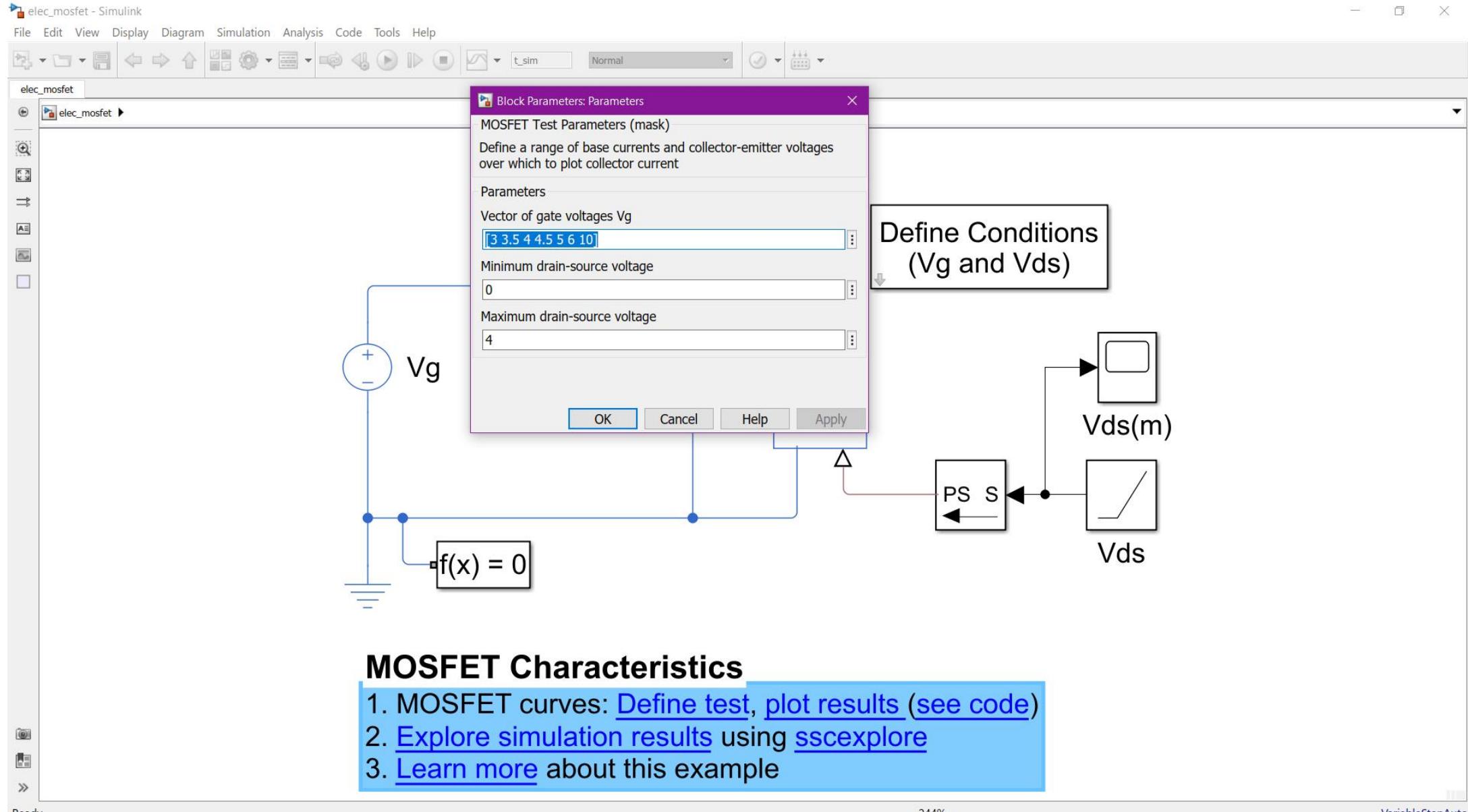
Fig 10.1 : Mosfet diagram : (a) p - Channel
enhancement mosfet (b) n - Channel
enhancement mosfet

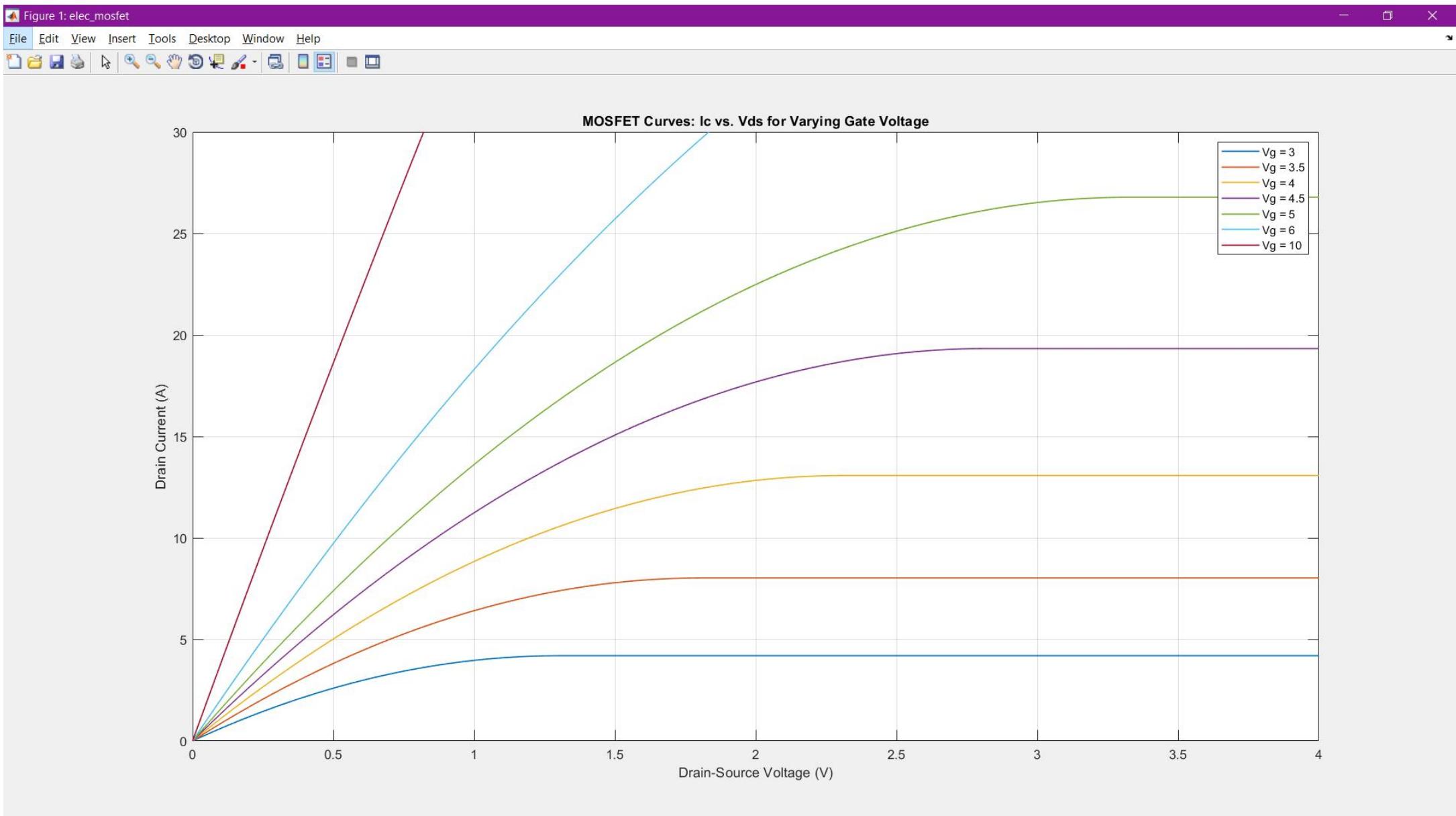
MATLAB Simulation

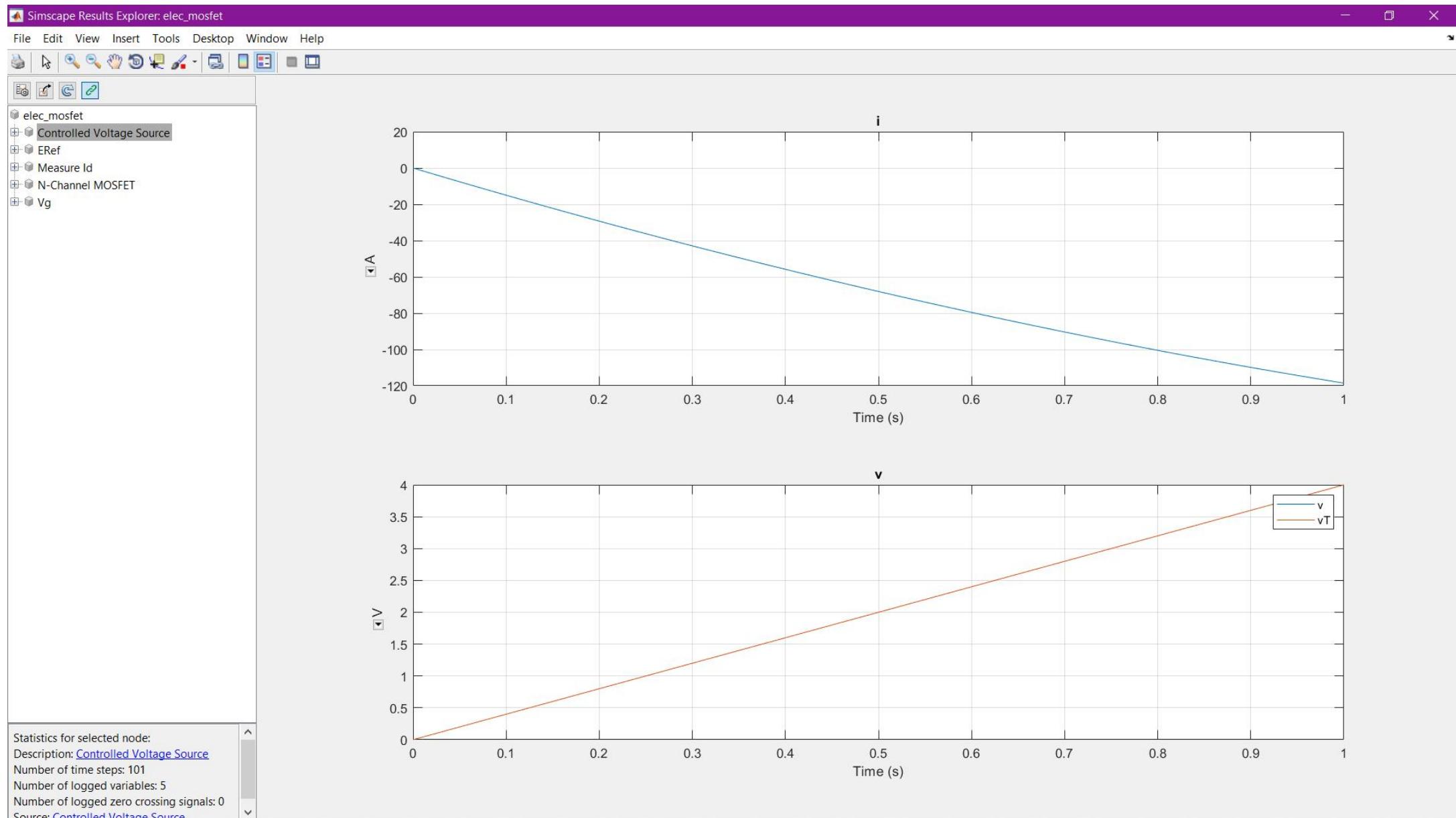


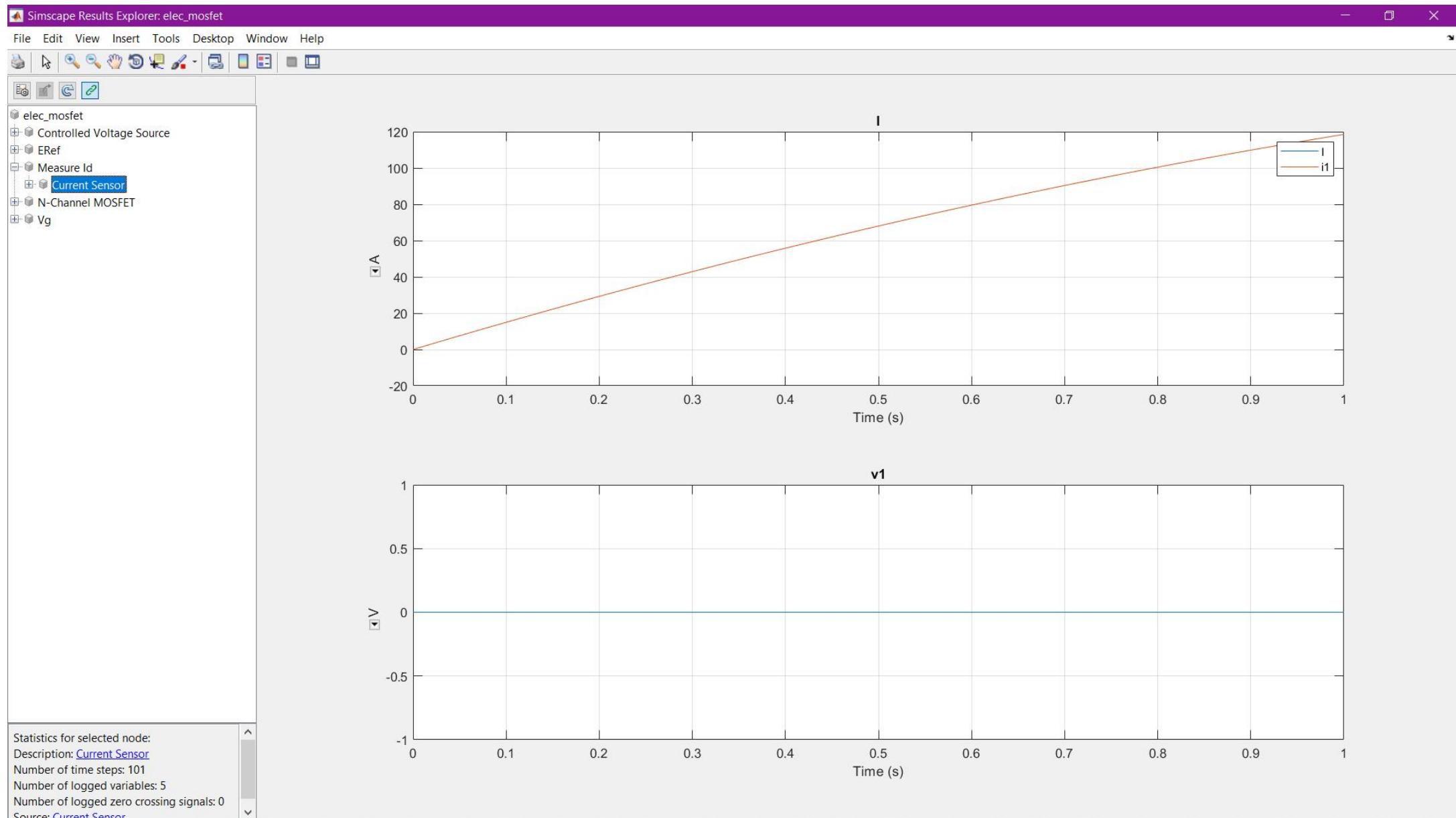
MOSFET Characteristics

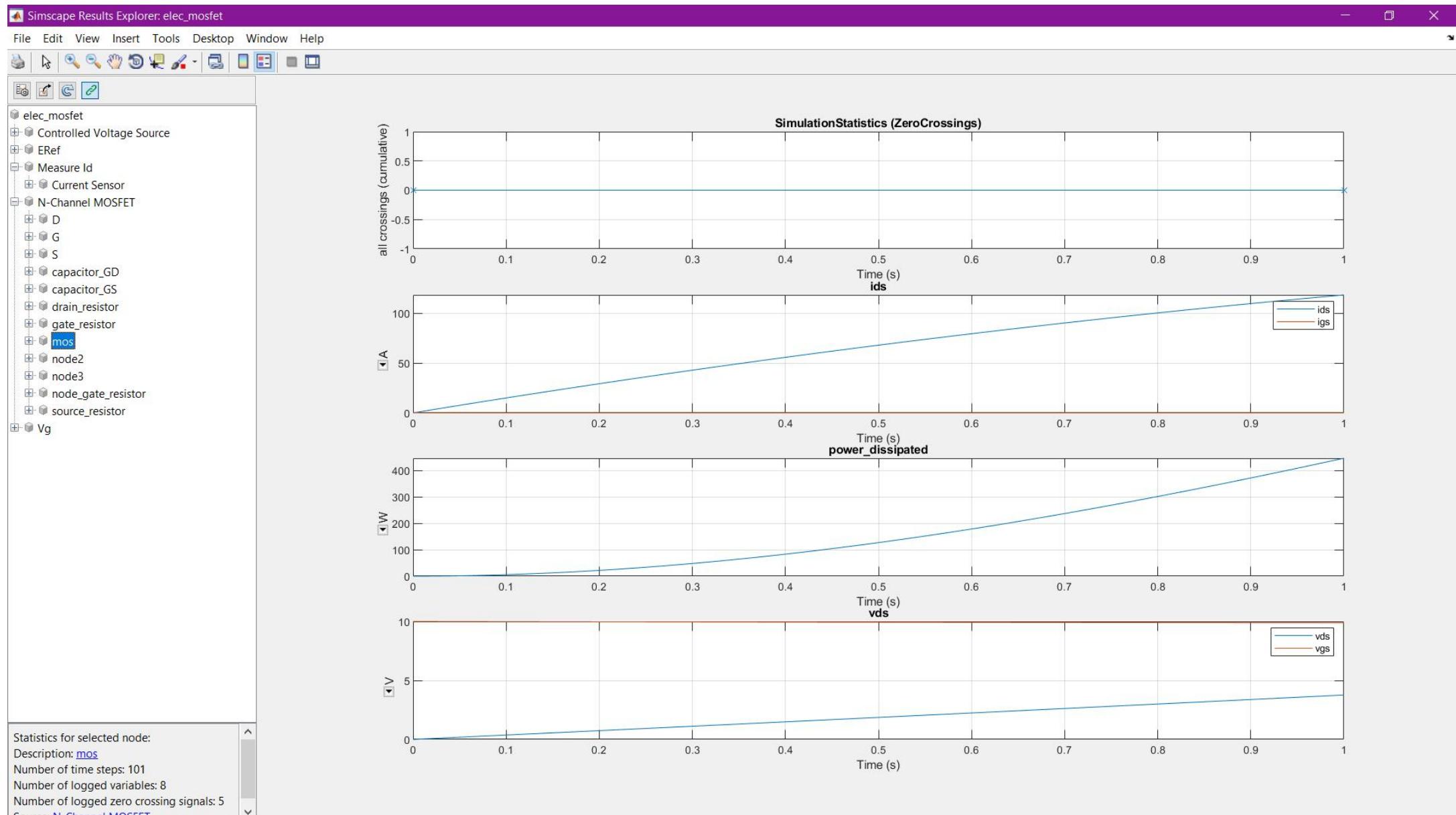
1. MOSFET curves: [Define test, plot results \(see code\)](#)
2. [Explore simulation results](#) using [sscexplore](#)
3. [Learn more](#) about this example

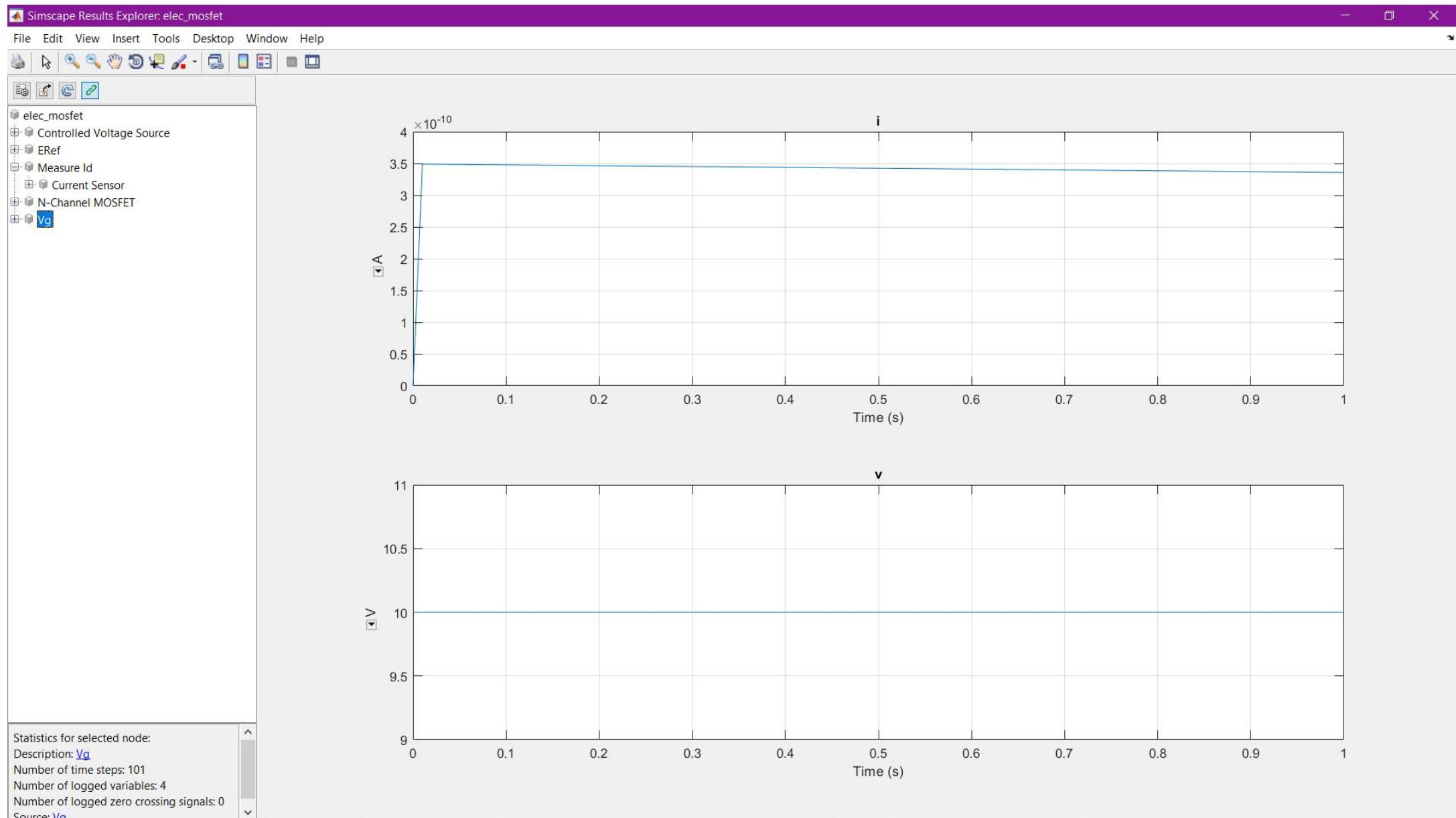












* Procedure:

1. Open MATLAB and in command window write:
"elec-mosfet" and press enter.
2. A simulation circuit will appear; change the values if required) and run the simulation.
3. After simulation, click on plot curve and observe the characteristics graph.
4. For more observation Click on Explore simulation results.

* Result: Studied and observed VI characteristics of mosfet using MATLAB simulink.

* Precautions:

1. Don't give multiple command at a time.
2. Do not change the circuit until required of the file as its Inbuilt example.

Experiment - II

* Gim: To study and plot V-I characteristics of SCR

* Equipment required:

1. NV6530 SCR characteristics trainer
2. 2mm pitch boards

* Theory:

A SCR is a four layered PNPN device, its prominent member of thyristor family. It consists of three diodes connected back to back with gate connections or two complementary transistors connected back to back.

It is widely used as a switching device in power control applications. It can switch ON for variable length of time and delivers amount of power to load.

It can control by the switching current OFF and ON upto many thousand times a second.

Hence, it possess arrays of RHEOSTAT and a switch with none of their advantages.

*

Diagram:

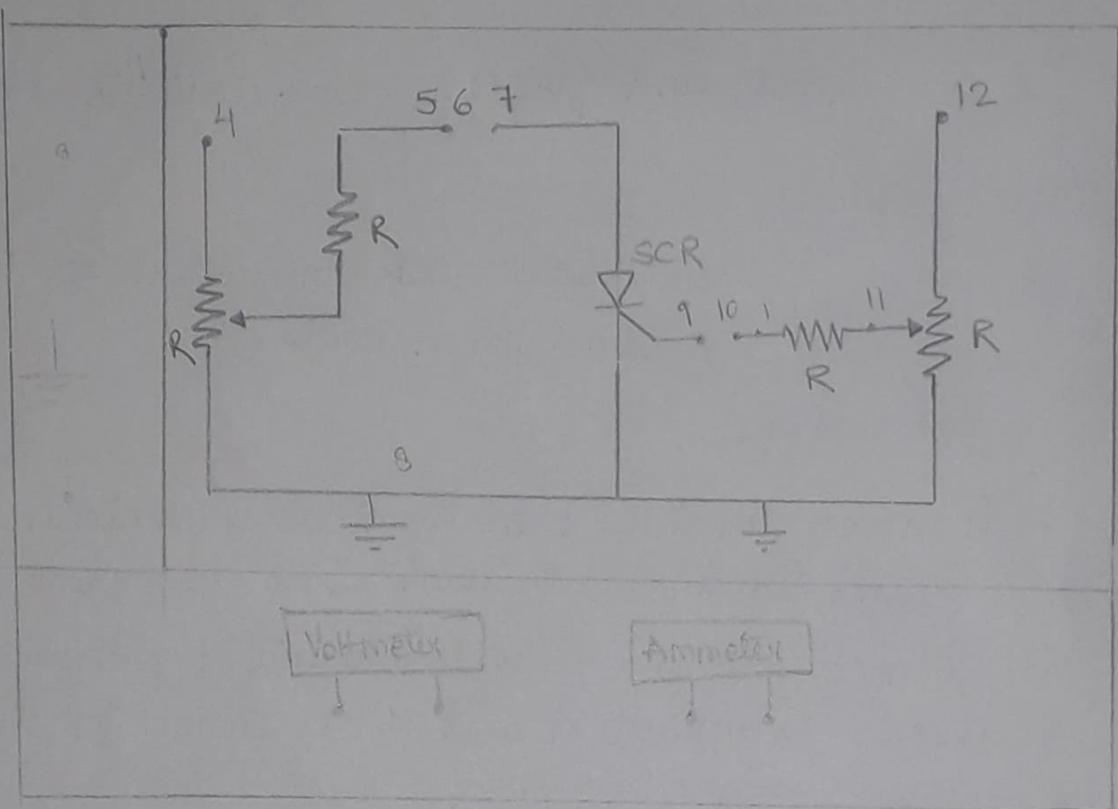


Fig 11.1 : Circuit diagram connection of SCR

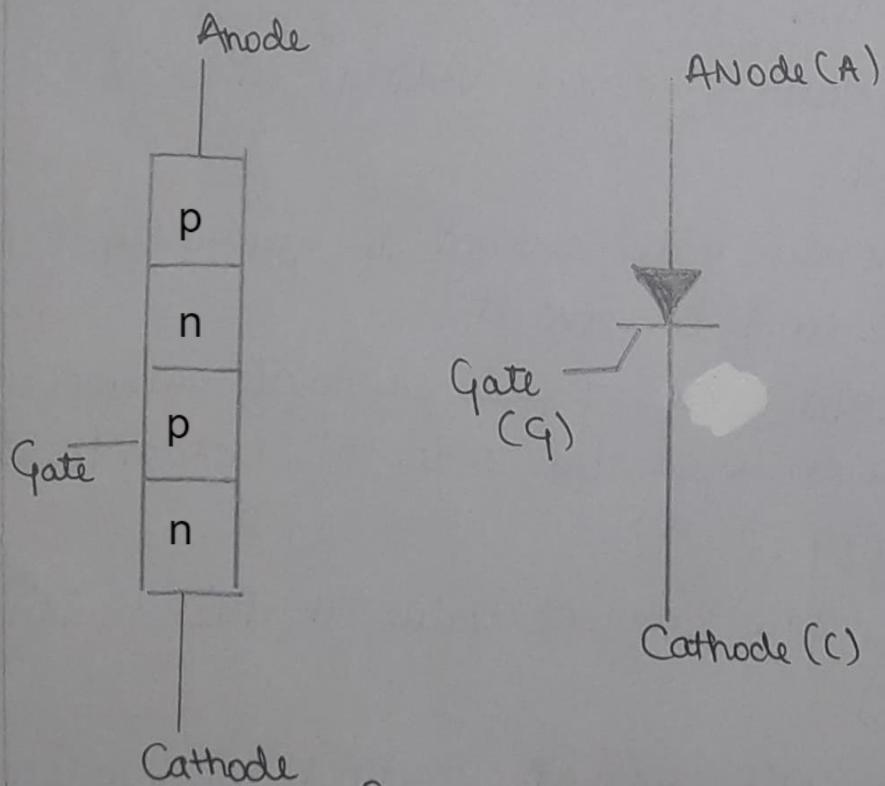


Fig 11.2 : SCR structure & symbol

* Procedure:

1. Connect terminal 1 to terminal 4, terminal 2 to terminal 8 and terminal 3 to terminal 12 as shown in figure.
2. Connect voltmeter across terminal 7 & 8 and Ammeter across terminal 9 and 10 as shown in figure.
3. Make short terminals 5 & 6.
4. Rotate the knob P1 & P2 fully in counter clockwise.
5. Switch "ON" the power supply.
6. Set the value of Anode Voltage at 35V by using the knob P1.
7. Now, Increase gate current I_g gradually by varying knob P2 and observe it.
8. At certain value of gate current, voltmeter reading falls down to almost zero. This action indicates the firing of SCR.
9. Note the gate current value at this position (firing of SCR).
10. Keep the gate current constant by shorting terminal 9 with 10 and connect Ammeter to the Terminal

5 and 6 (as in figure).

11. Rotate the potentiometer P_1 fully in counter clockwise.
12. Rotate knob P_1 (from initial position to its maximum limit) gradually and record Anode Current for respective value of anode voltages.
13. Plot the graph between anode voltage V_a and anode current I_a .

* Observation Table :

Sl. No.	Anode Voltage V_a (V)	Anode current I_a (mA)
1.	0	0
2.	0.5	0
3.	1.3	1
4.	7.4	0.2
5.	11.6	0.2
6.	13.5	8.5
7.	0.7	11.8
8.	0.7	21.2
9.	0.7	35.4
10.	0.7	39.5

*

Graph:

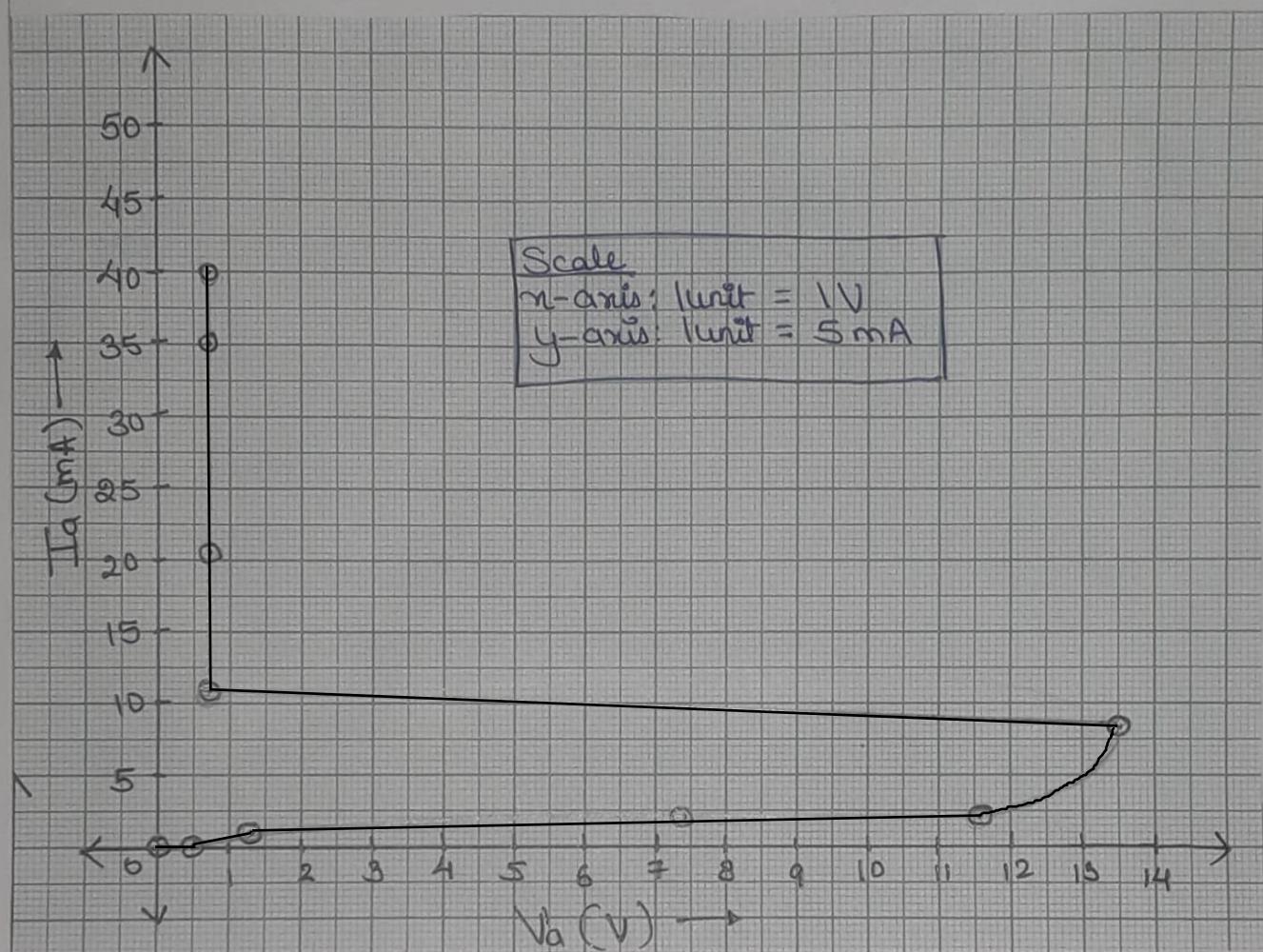


Fig 11.3: I_a vs V_a characteristics of SCR

* Result : Studied and plotted V-I characteristics of SCR.

* Precautions :

1. Connect the circuit carefully as per the given circuit diagram.
2. Verify the circuit before giving power supply
3. Switch off the power supply after the experiment and remove the connections.

Experiment - 12

* Aim: Study of the half-wave controlled rectifier with resistive load.

* Equipment Needed:

1. Power Electronics board, Scientech 2708
2. Oscilloscope - Scientech 803/831, or equivalent
3. 2mm patch cords
4. Multimeter

* Procedure:

Make sure that there should not be any connections by patch cord on the board.

1. Rotate the firing control pot in full clockwise directions
2. Switch 'On' the power.
3. Measure the ac voltage (V_{rms}) by voltmeter between point OV-15V and calculate E_m by:
$$E_m = 1.414 \times V_{rms}$$
4. Switch 'Off' the power.
5. Connects the circuit of half-wave rectifier as shown figure 8 using 2 mm patch cords
6. Switch 'On' the power supply
7. Connect the oscilloscope and voltmeter across the load.

* Circuit Diagram:

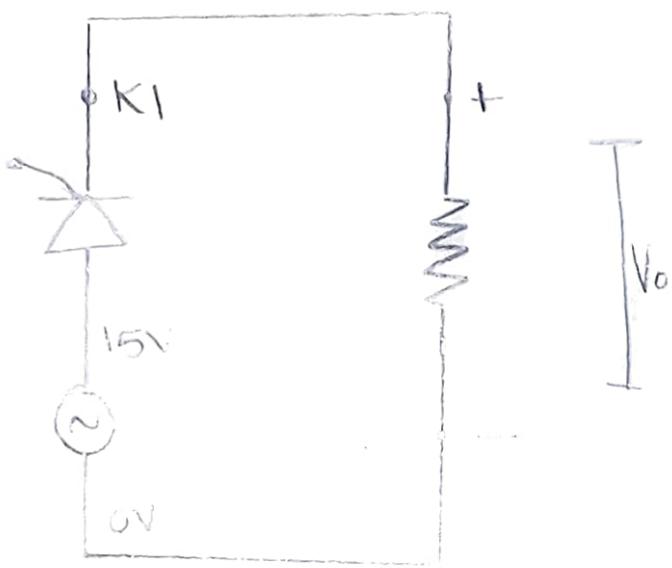


Fig 12.1: The circuit diagram of basic half-wave controlled rectifier circuit diagram.

8. Vary the firing control pot and set on 30° , 60° , 90° , 120° and 150° firing angles using equations (11).
9. Observe the output waveforms and note the reading of voltage across load on different firing angles.
10. Observe the waveforms across the SCR when firing angle is 90° .
11. Calculate the average load current and power P_{dc} from measured load voltage V_o .
12. Plot the input signal, gate pulse and drop signal across SCR and output waveform when firing angle is 90° .

* Observation Table

$$V_s = 15 \text{ V (ac)} \Rightarrow V_m = \sqrt{2} \times V_s = 21.21 \text{ V}$$

α (degree)	Practical			Theoretical			% Error
	O/P Voltage (V)	O/P Current (mA)	Power (W)	O/P Voltage (V)	O/P Current (mA)	Power (W)	
0	6.42	6.42	0.041	6.75	6.75	0.045	4.88%
30	6.09	6.09	0.037	6.30	6.30	0.039	3.33%
36	5.912	5.912	0.349	6.1	6.1	0.037	3.08%
45	5.62	5.62	0.315	5.76	5.76	0.033	2.43%
60	4.86	4.86	0.0236	5.06	5.06	0.0256	3.95%
90	3.59	3.59	0.0128	3.37	3.37	0.0113	6.5%
108	2.25	2.25	0.005	2.33	2.33	0.0054	3.43%
126	1.39	1.39	0.0019	1.391	1.391	0.0019	0.07%

$$V_o = \frac{V_m}{2\pi} (1 + \cos \alpha) ; R = 1 \times 10^3 \Omega$$

* Calculation:

1. $\alpha = 0^\circ$, $V_o = 6.42 V$

Practical: $I_o = \frac{\cancel{V_o}}{R} = \frac{6.42}{1 \times 10^3} = 6.42 \text{ mA}$

$$P_o = \frac{V_o^2}{R} = \frac{6.42^2}{10^3} = 0.041 W.$$

Theoretical:

$$V_o = \frac{21.21}{2\pi} (1 + \cos 0^\circ) = 6.75 V$$

$$I_o = \frac{6.75}{10^3} = 6.75 \text{ mA} ; P_o = \frac{6.75^2}{10^3} = 0.045 W$$

2. $\alpha = 30^\circ$; $V_o = 6.09 V$

Practical: $I_o = \frac{6.09}{10^3} = 6.09 \text{ mA}$ $P_o = \frac{6.09^2}{10^3} = 0.037 W$

Theoretical: $V_o = \frac{21.21}{2\pi} (1 + \cos 30^\circ) = 6.30 V$

$$I_o = \frac{6.30}{10^3} = 6.3 \text{ mA} \quad P_o = \frac{6.3^2}{10^3} = 0.039 W.$$

3. $\alpha = 36^\circ$; $V_o = 5.912 V$

Practical: $I_o = \frac{5.912}{10^3} = 5.912 \text{ mA}$; $P_o = \frac{5.912^2}{10^3} = 0.349 W$

Theoretical: $V_o = \frac{21.21}{2\pi} (1 + \cos 36^\circ) = 6.1 V$

$$I_o = 6.1 \text{ mA} \quad P_o = \frac{6.1^2}{10^3} = 0.037 W$$

4. $\alpha = 45^\circ$; $V_o = 5.62 V$

Practical: $I_o = 5.62 \text{ mA}$; $P_o = 0.0315 W$

Theoretical: $V_o = \frac{21.21}{2\pi} (1 + \cos 45^\circ) = 5.76 V$

$$I_o = 5.76 \text{ mA} \quad P_o = \frac{5.76^2}{10^3} = 0.033 W.$$

$$5. \alpha = 60^\circ; V_o = 4.86 \text{ V}$$

$$\text{Practical: } I_o = 4.86 \text{ mA} \quad P_o = \frac{4.86^2}{10^3} = 0.0236 \text{ W}$$

$$\text{Theoretical: } V_o = \frac{21.21}{2\pi} (1 + \cos 60^\circ) = 5.06 \text{ V}$$

$$I_o = 5.06 \text{ mA} \quad P_o = \frac{5.06^2}{10^3} = 0.0256 \text{ W}$$

$$6. \alpha = 90^\circ; V_o = 3.59 \text{ V}$$

$$\text{Practical: } I_o = 3.59 \text{ mA} \quad P_o = \frac{3.59^2}{10^3} = 0.0128 \text{ W}$$

$$\text{Theoretical: } V_o = \frac{21.21}{2\pi} (1 + \cos 90^\circ) = 3.37 \text{ V}$$

$$I_o = 3.37 \text{ mA} \quad P_o = \frac{3.37^2}{10^3} = 0.0113 \text{ W}$$

$$7. \alpha = 108^\circ; V_o = 2.25 \text{ V}$$

$$\text{Practical: } I_o = 2.25 \text{ mA} \quad P_o = \frac{2.25^2}{10^3} = 0.005 \text{ W}$$

$$\text{Theoretical: } V_o = \frac{21.21}{2\pi} (1 + \cos(108)) = 2.33 \text{ V}$$

$$I_o = 2.33 \text{ mA} \quad P_o = \frac{2.33^2}{10^3} = 0.0054 \text{ W}$$

$$8. \alpha = 126^\circ; V_o = 1.39 \text{ V}$$

$$\text{Practical: } I_o = 1.39 \text{ mA} \quad P_o = \frac{1.39^2}{10^3} = 0.0019 \text{ W}$$

$$\text{Theoretical: } V_o = \frac{21.21}{2\pi} (1 + \cos(126)) = 1.39 \text{ V}$$

$$I_o = 1.39 \text{ mA} \quad P_o = \frac{1.39^2}{10^3} = 0.0019 \text{ W}$$

* % Error

$$1 \rightarrow \frac{|16.42 - 6.75|}{6.75} \times 100 = 4.88\%$$

$$5 \rightarrow \frac{|14.86 - 5.06|}{5.06} \times 100 = 3.95\%$$

$$2 \rightarrow \frac{|16.09 - 6.30|}{6.30} \times 100 = 3.33\%$$

$$6 \rightarrow \frac{|13.59 - 3.37|}{3.37} \times 100 = \cancel{36.5}\%$$

$$3 \rightarrow \frac{|15.912 - 6.1|}{6.1} \times 100 = 3.08\%$$

$$7 \rightarrow \frac{|12.25 - 2.33|}{2.33} \times 100 = \cancel{3.43}\%$$

$$4 \rightarrow \frac{|15.62 - 5.76|}{5.76} \times 100 = 2.43\%$$

$$8 \rightarrow \frac{|11.39 - 1.391|}{1.391} \times 100 = 0.07\%$$

* ~~Waves~~ Waveform:

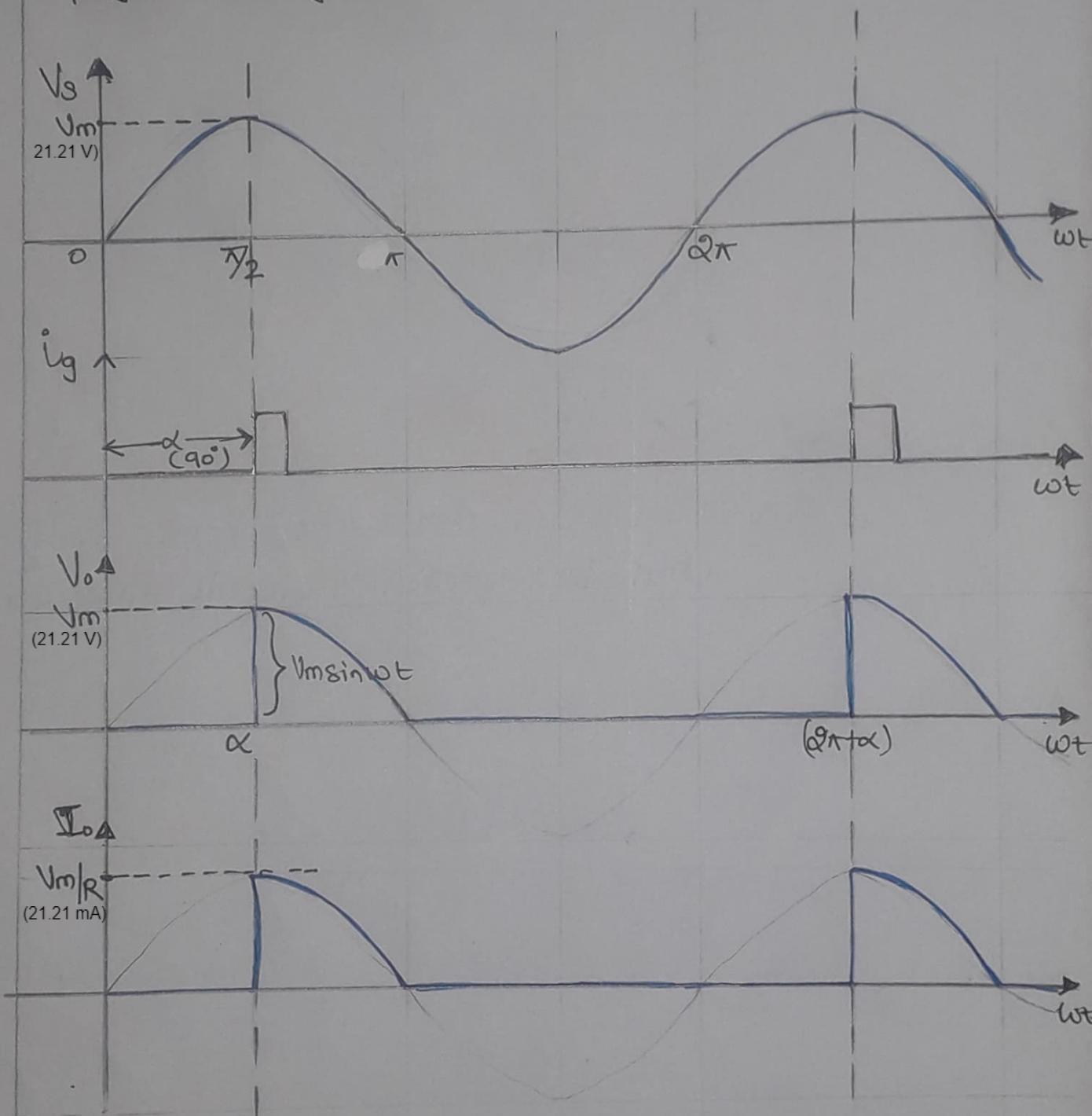


Fig 12.2: Waveform of half wave controlled rectifier
for $\alpha = 90^\circ$.

* Result: Studied and observed the waveform of the half wave controlled rectifier with resistive load using trainer kit.

* Precautions:

1. Make the connection tight.
2. Do not power on the supply until the connection is verified.