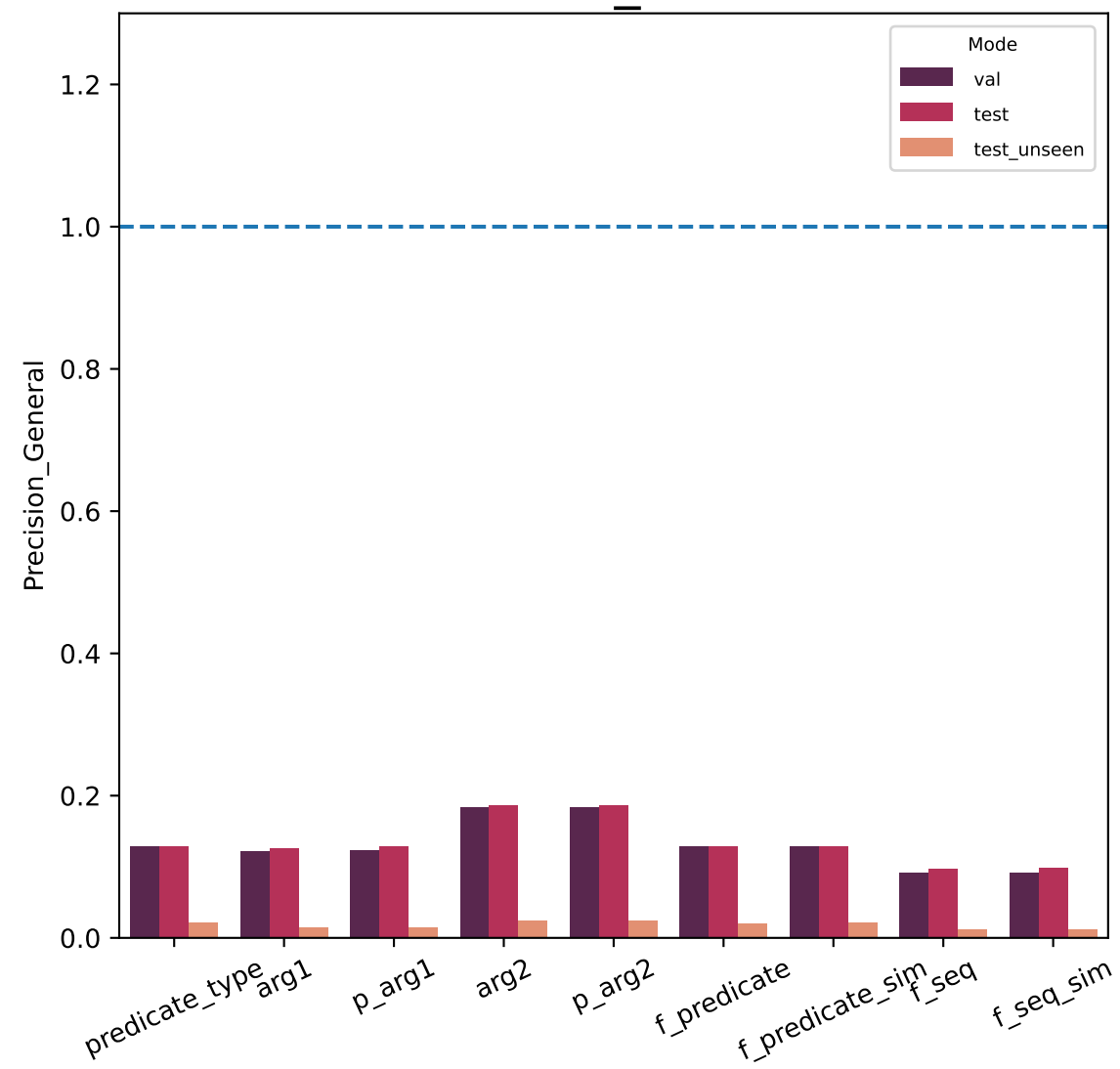
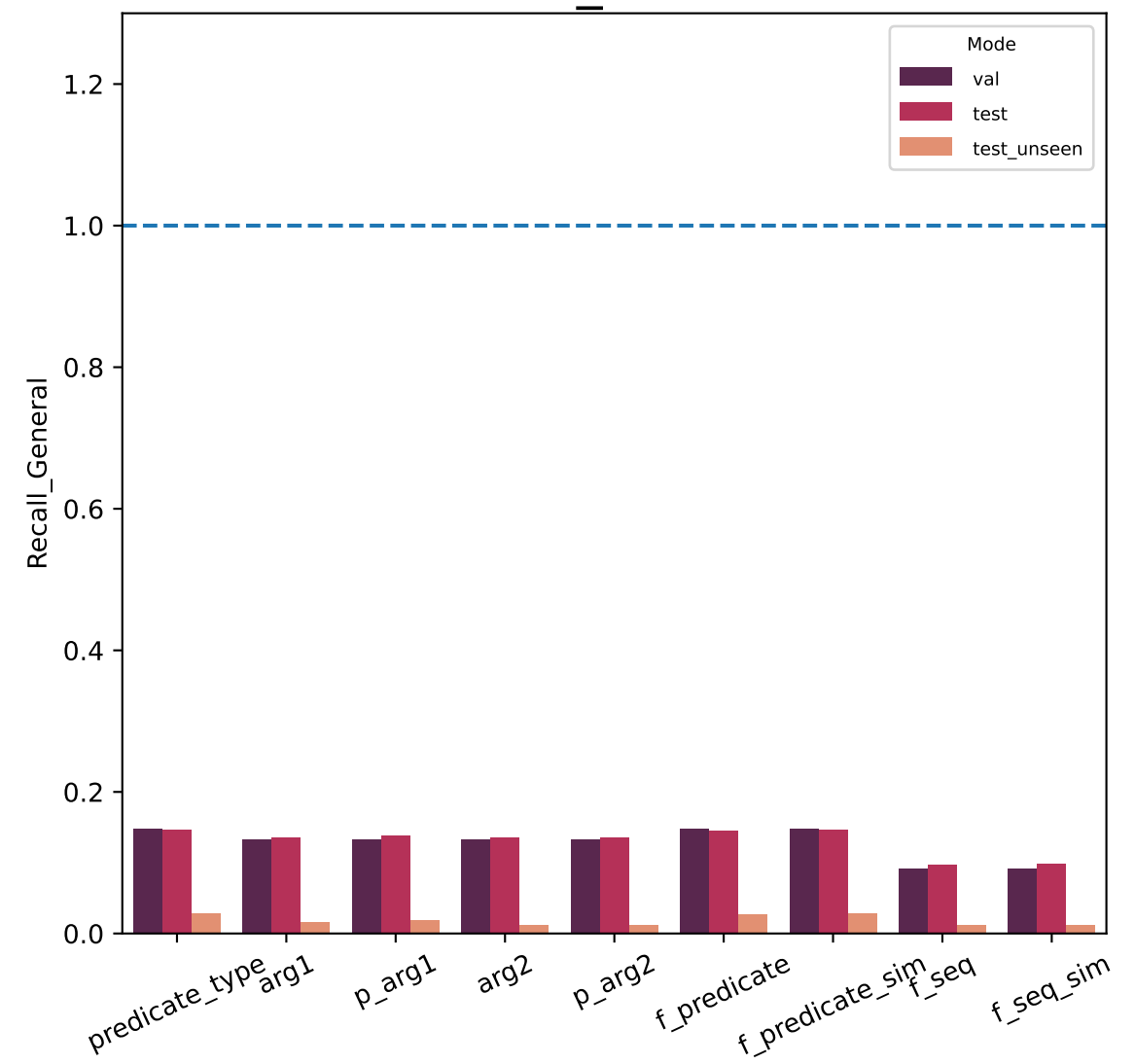


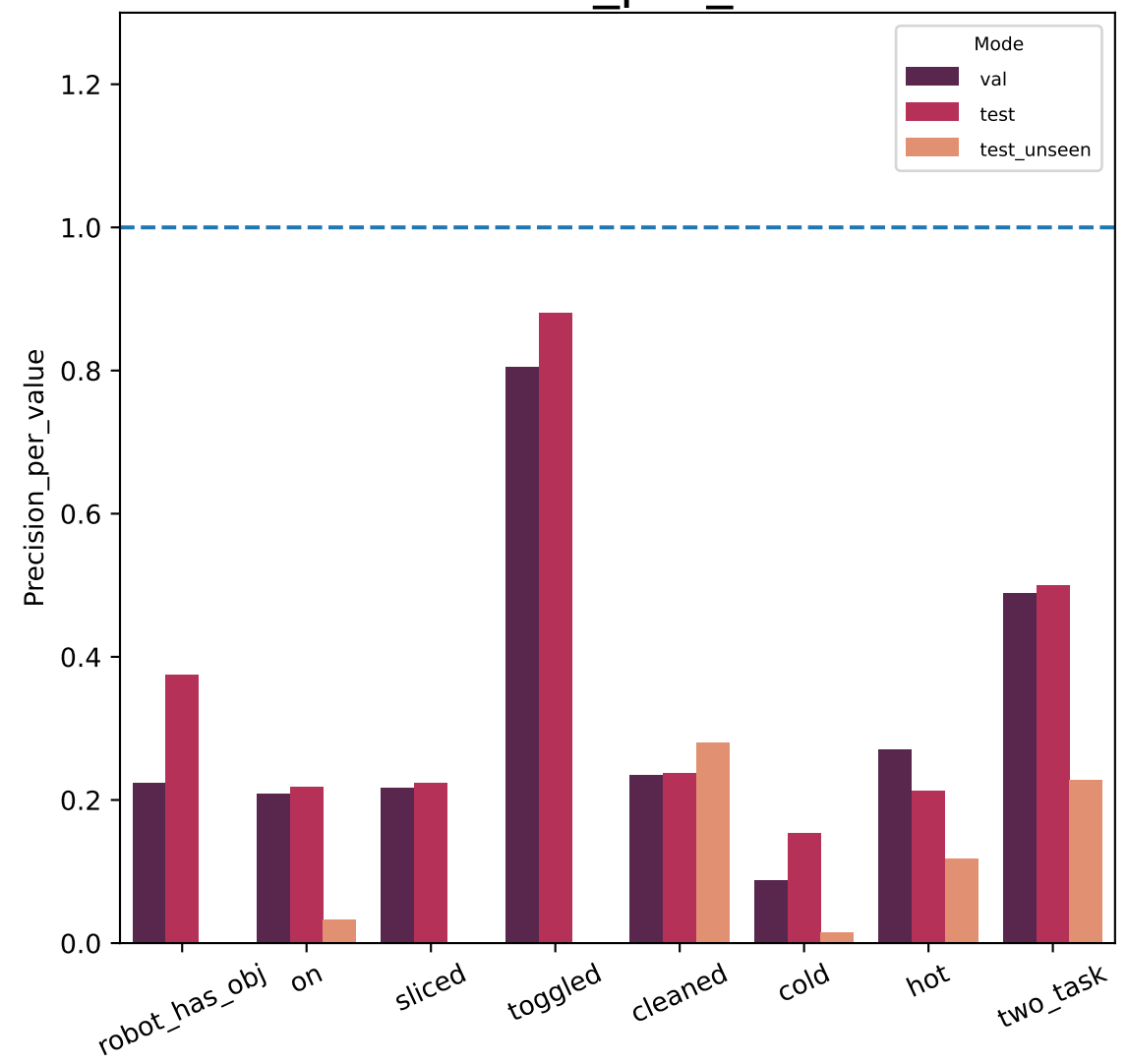
Precision_General



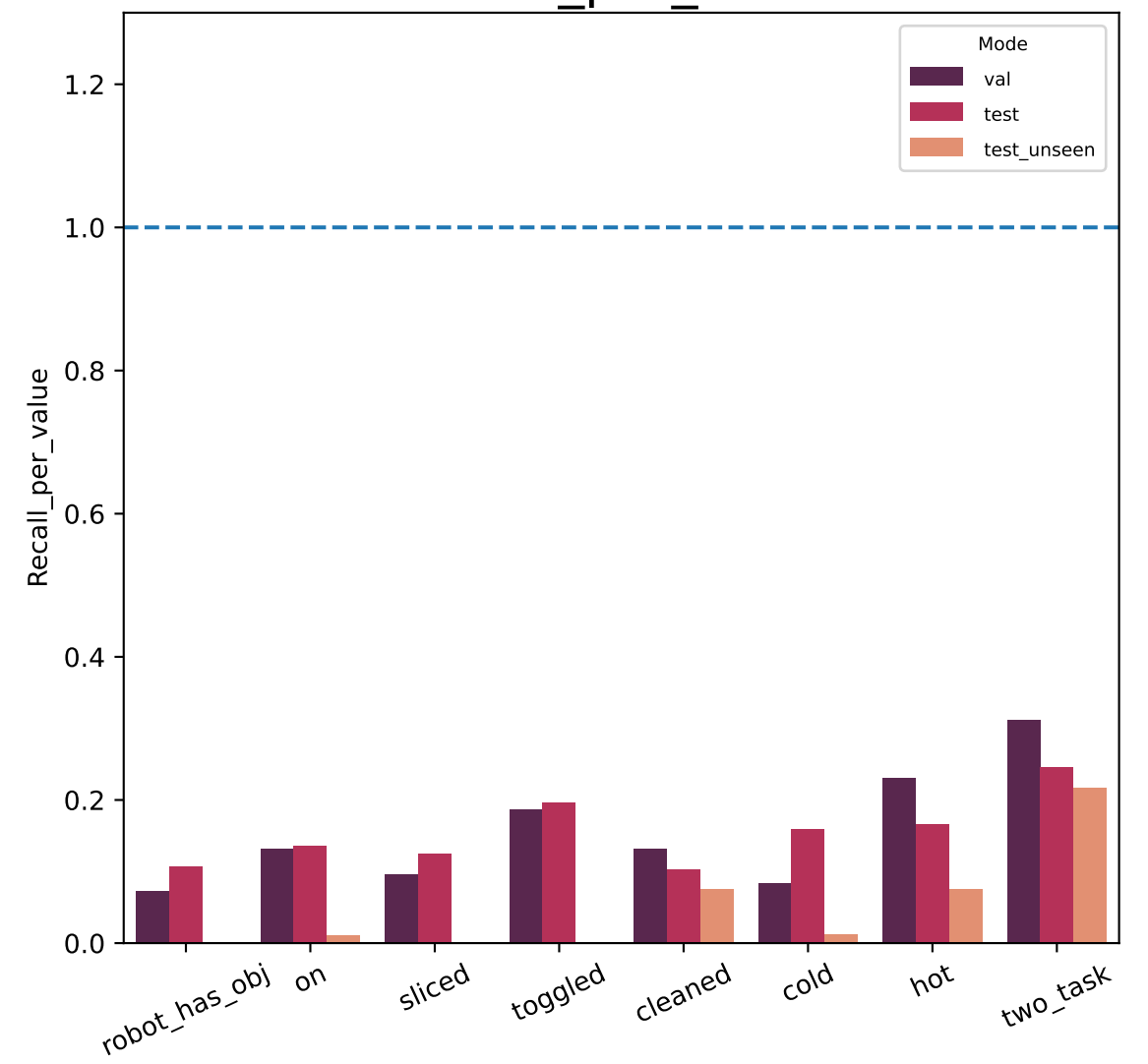
Recall_General



Precision_per_value



Recall_per_value



Precision_General_val								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.128	0.122	0.123	0.184	0.184	0.128	0.128	0.092	0.092

Precision_General_test								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.129	0.126	0.128	0.186	0.186	0.128	0.129	0.097	0.098

Precision_General_test_unseen								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.021	0.014	0.015	0.024	0.024	0.02	0.021	0.012	0.012

Recall_General_val								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.148	0.132	0.133	0.132	0.132	0.148	0.148	0.092	0.092

Recall_General_test								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.147	0.135	0.138	0.135	0.135	0.145	0.147	0.097	0.098

Recall_General_test_unseen								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.028	0.016	0.018	0.011	0.011	0.027	0.028	0.012	0.012

Precision_per_value_val								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.224	0.208	0.217	0.805	0.234	0.087	0.27	0.489	

Precision_per_value_test								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.375	0.218	0.224	0.88	0.237	0.154	0.212	0.5	

Precision_per_value_test_unseen								
on		cleaned		cold		hot		two_task
0.032		0.28		0.014		0.118		0.227

Recall_per_value_val								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.073	0.132	0.096	0.186	0.132	0.084	0.23	0.312	

Recall_per_value_test								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.107	0.135	0.124	0.196	0.102	0.159	0.166	0.246	

Recall_per_value_test_unseen								
on		cleaned		cold		hot		two_task
0.011		0.075		0.012		0.075		0.217