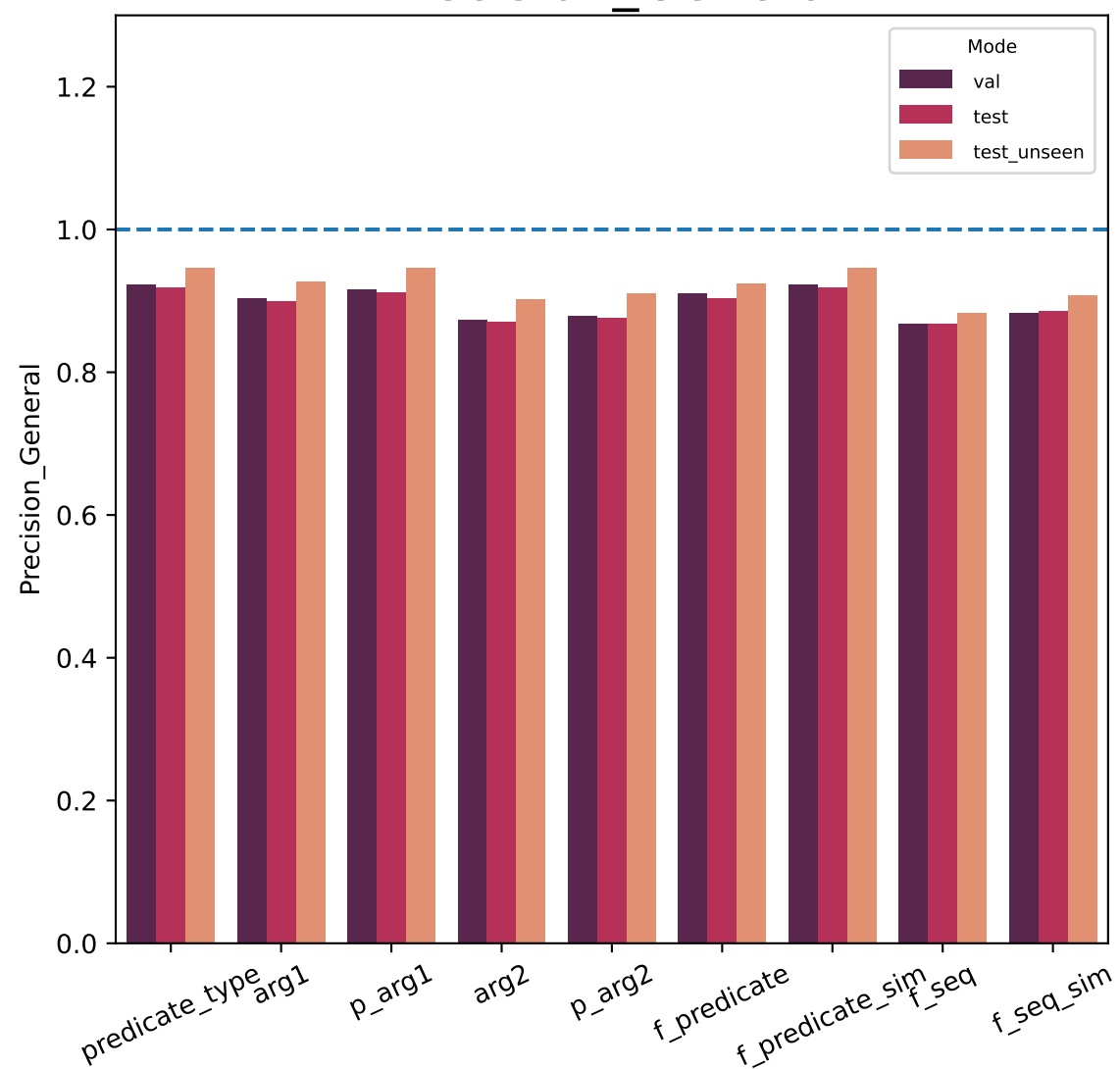
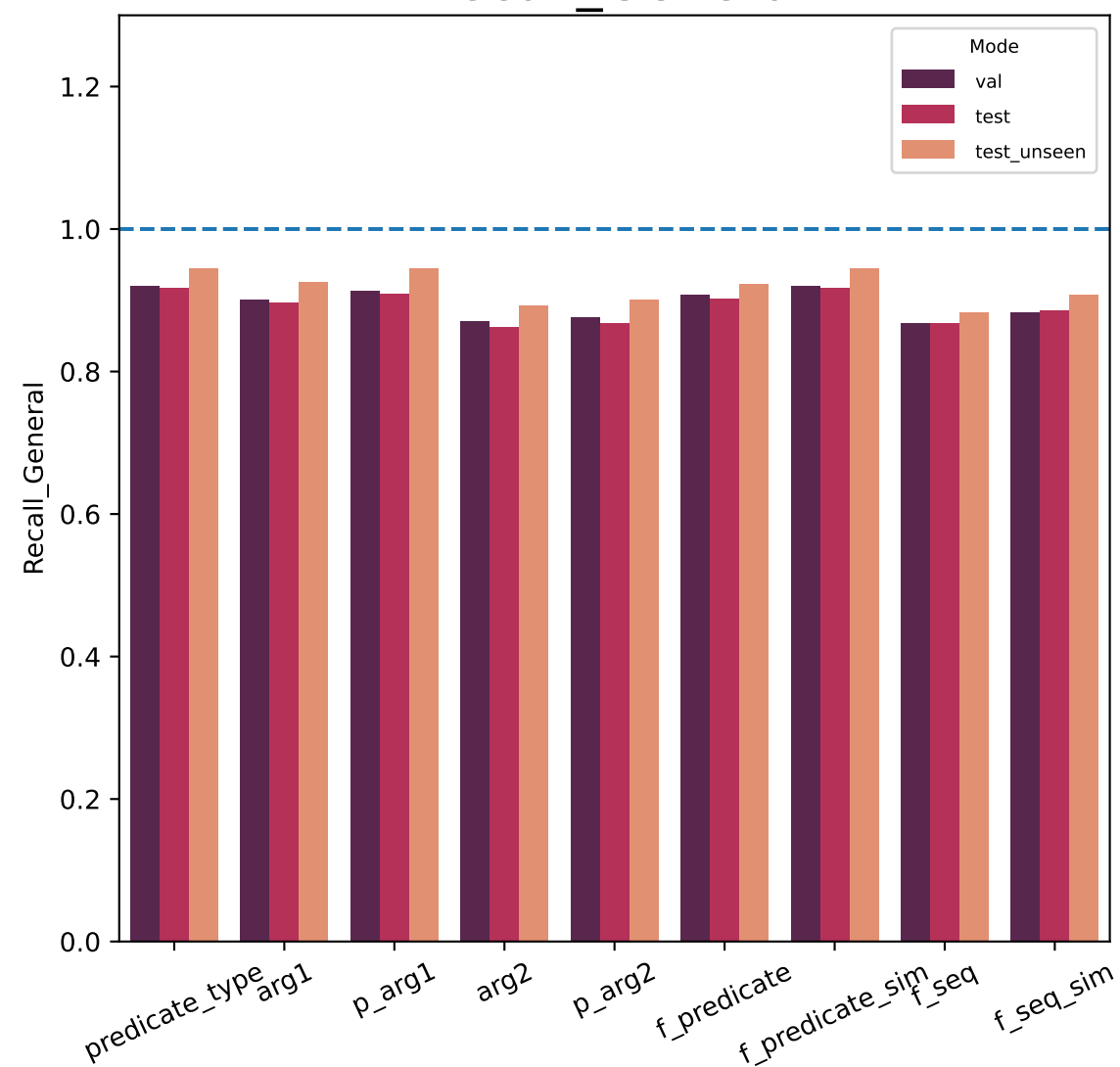


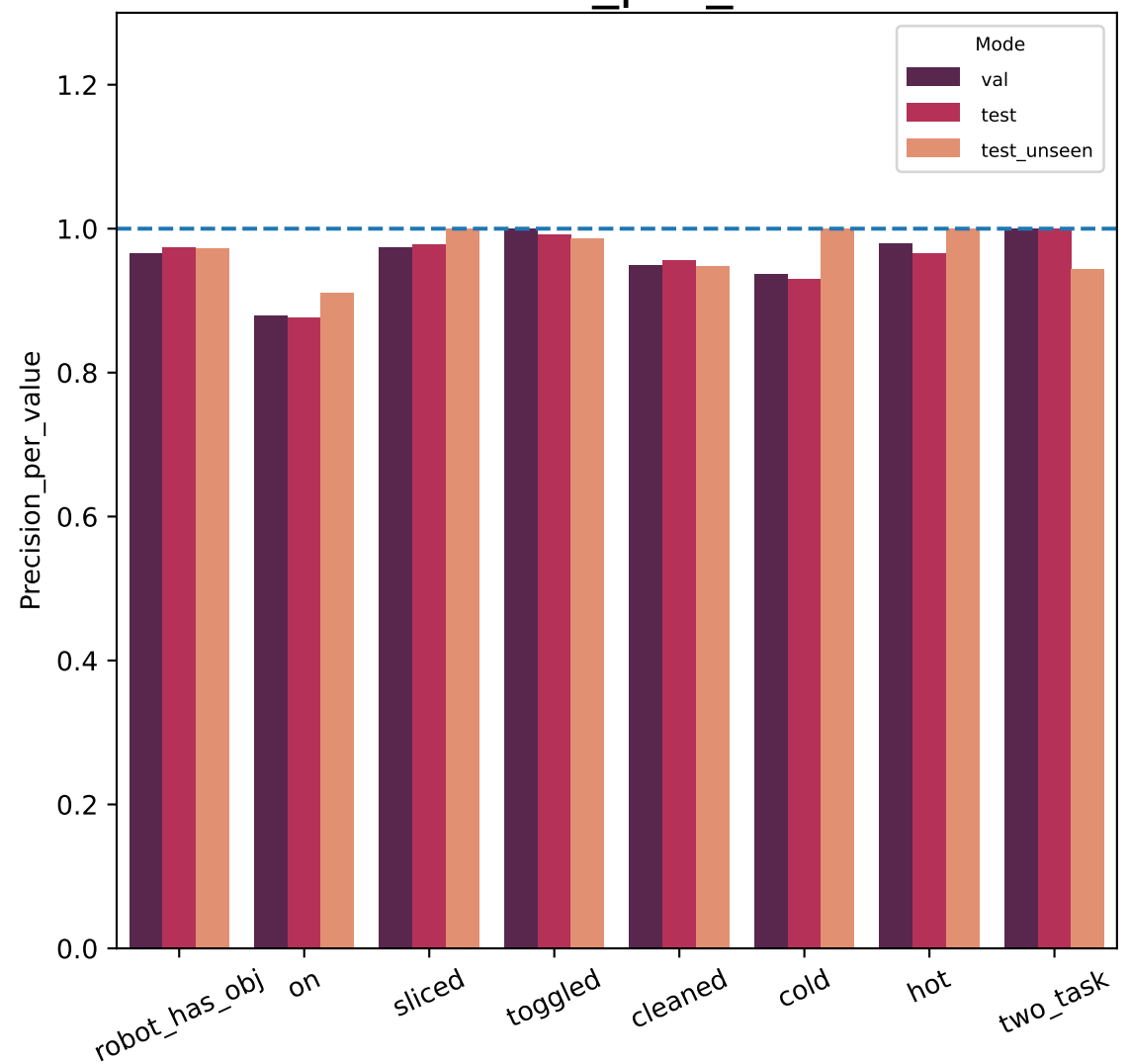
Precision_General



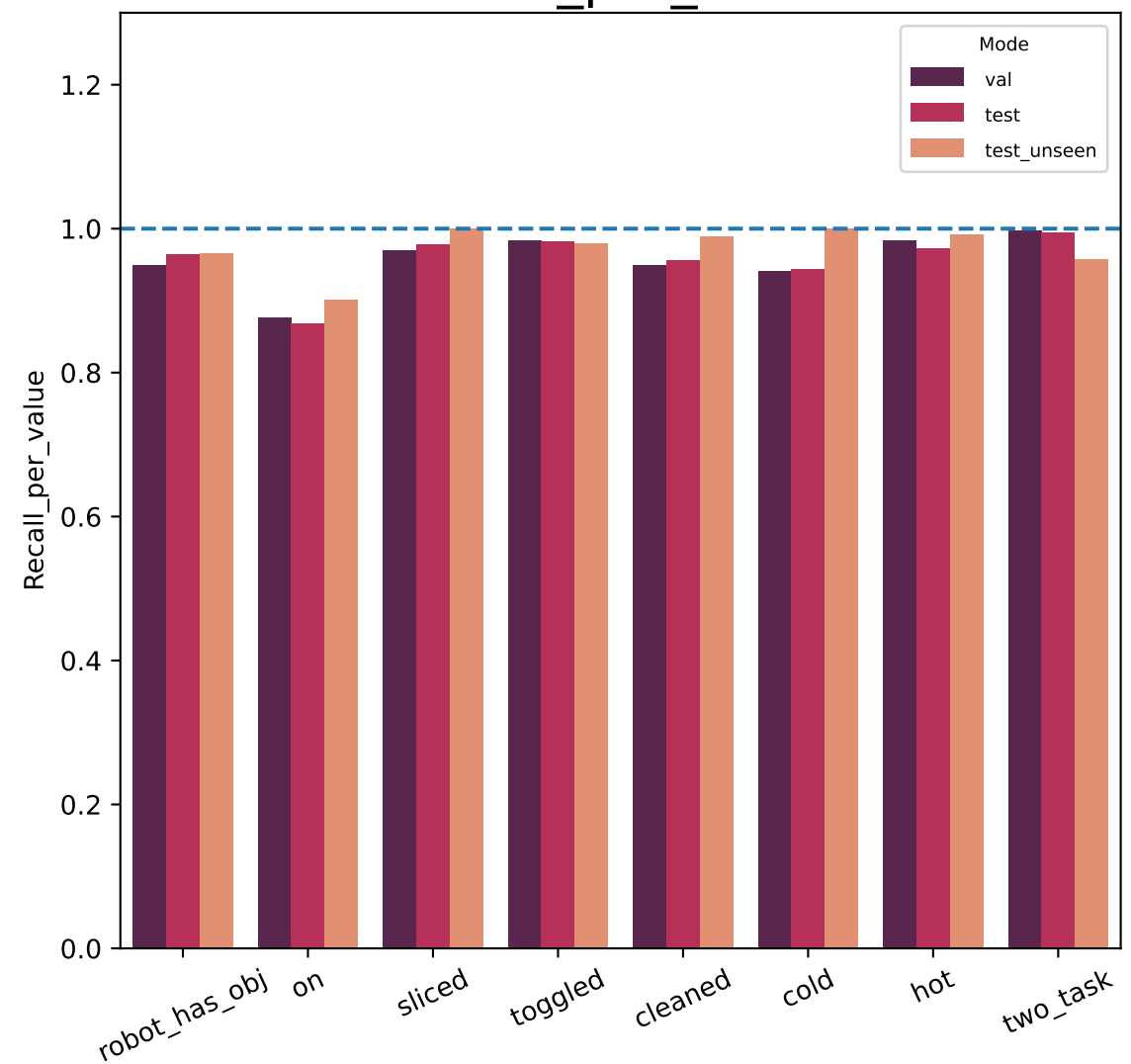
Recall_General



Precision_per_value



Recall_per_value



Precision_General_val								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.923	0.904	0.916	0.873	0.879	0.91	0.923	0.868	0.883

Precision_General_test								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.919	0.899	0.912	0.871	0.876	0.904	0.919	0.867	0.886

Precision_General_test_unseen								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.946	0.927	0.946	0.902	0.91	0.924	0.946	0.883	0.908

Recall_General_val								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.92	0.901	0.913	0.87	0.876	0.907	0.92	0.868	0.883

Recall_General_test								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.917	0.896	0.909	0.862	0.868	0.902	0.917	0.867	0.886

Recall_General_test_unseen								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.944	0.925	0.944	0.893	0.901	0.923	0.944	0.883	0.908

Precision_per_value_val								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.966	0.879	0.973	1.0	0.949	0.937	0.979	1.0	

Precision_per_value_test								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.973	0.876	0.978	0.991	0.956	0.93	0.966	1.0	

Precision_per_value_test_unseen								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.972	0.91	1.0	0.986	0.948	1.0	1.0	0.943	

Recall_per_value_val								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.949	0.876	0.969	0.983	0.949	0.941	0.983	0.997	

Recall_per_value_test								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.964	0.868	0.978	0.982	0.956	0.944	0.972	0.994	

Recall_per_value_test_unseen								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.965	0.901	1.0	0.979	0.989	1.0	0.991	0.957	