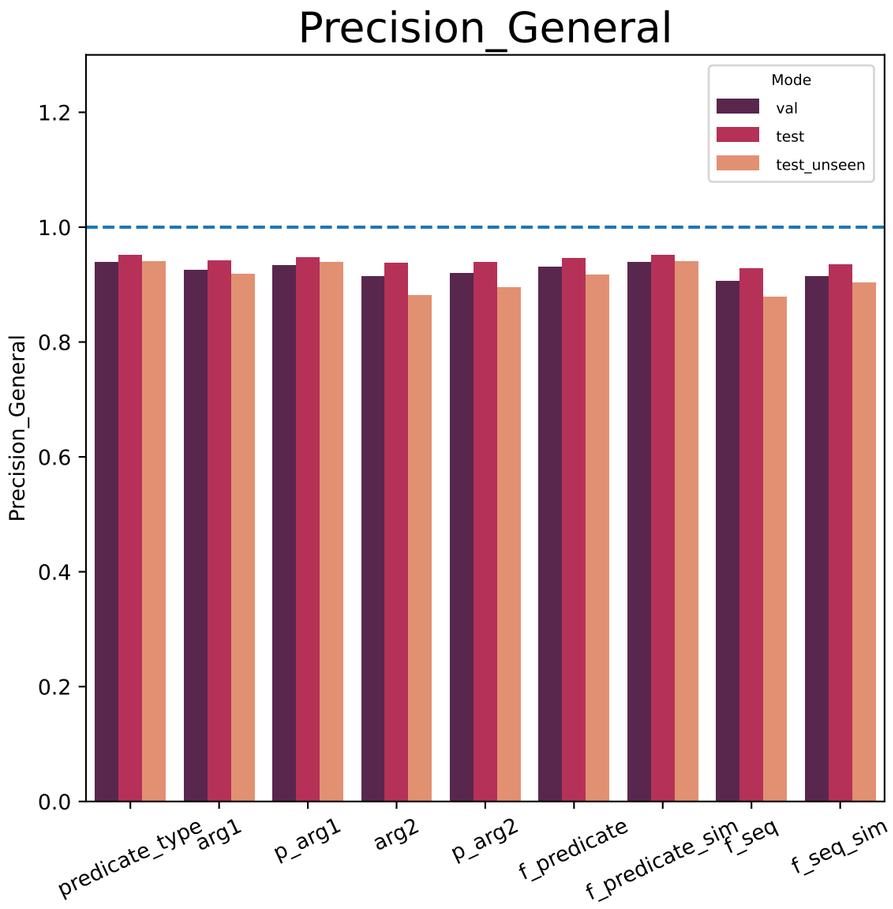
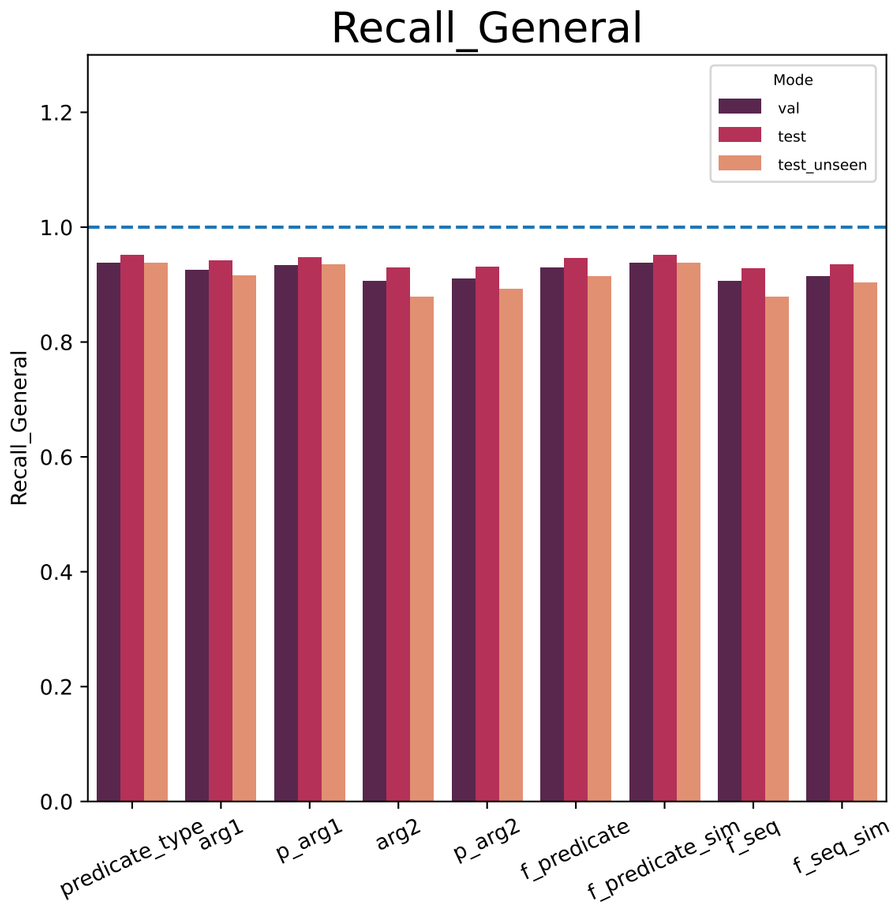
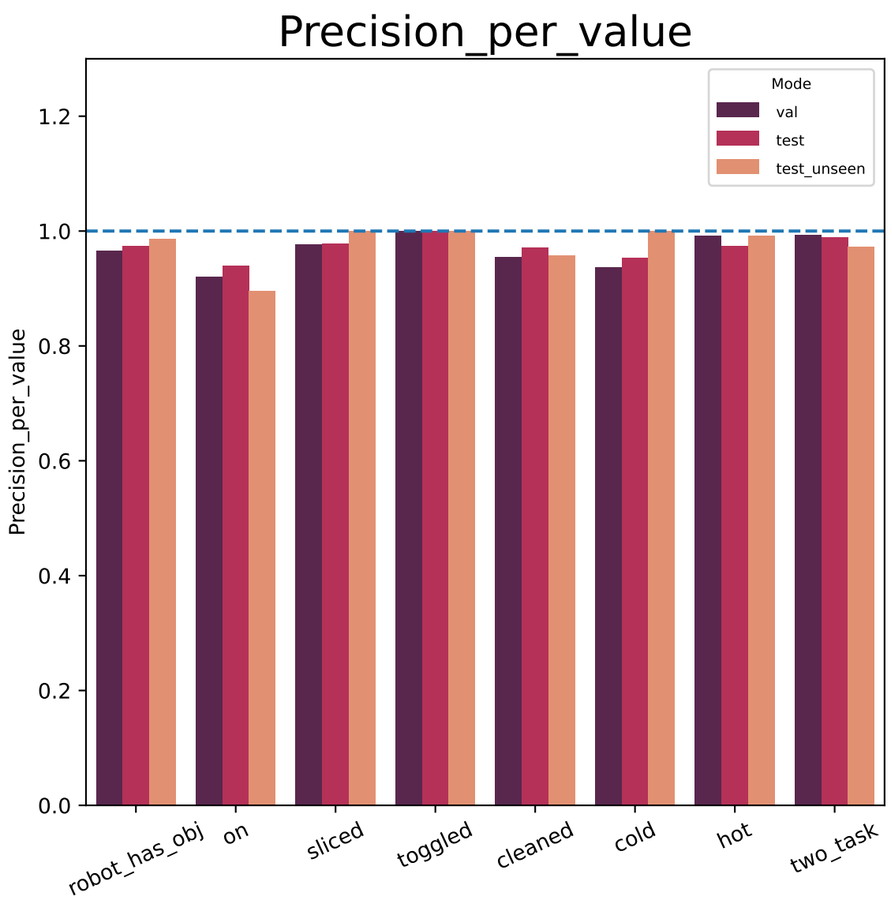
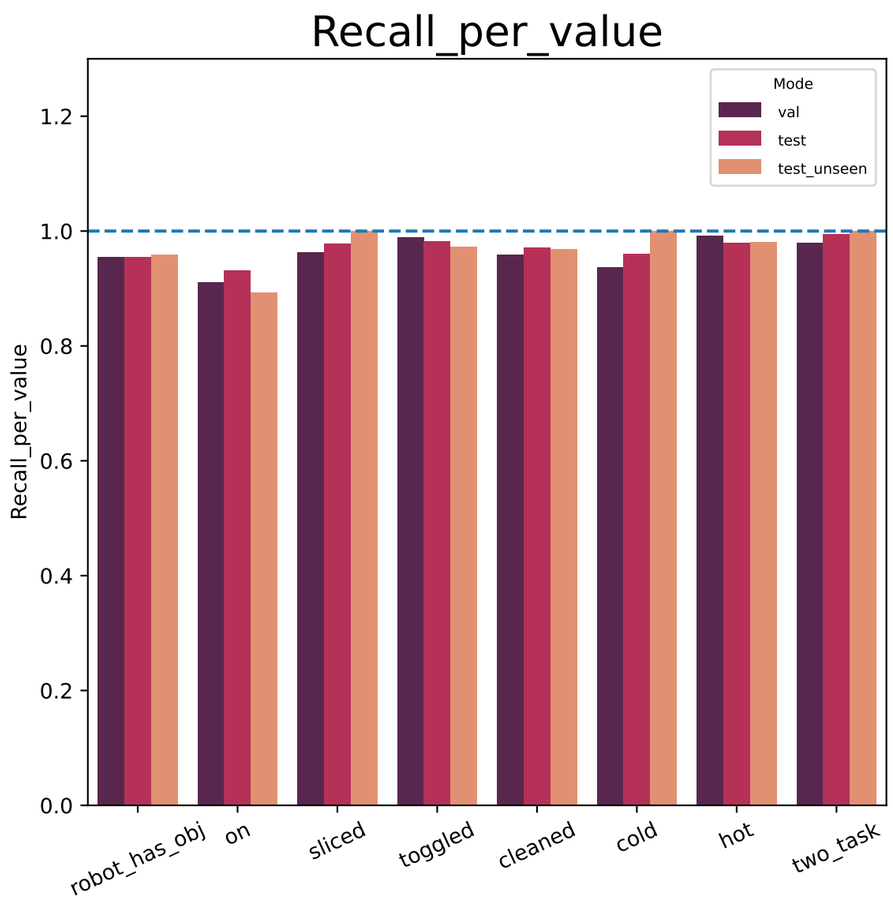

Precision_General
Mode
val
test
test_unseen
Precision_General
1.2
1.0
0.8
0.6
0.4
0.2
0.0
predicate_type
arg1
p_arg1
arg2
p_arg2
f_predicate
f_predicate_sim
f_seq
f_seq_sim


Recall_General
Mode
val
test
test_unseen
Recall_General
1.2
1.0
0.8
0.6
0.4
0.2
0.0
predicate_type
arg1
p_arg1
arg2
p_arg2
f_predicate
f_predicate_sim
f_seq
f_seq_sim


Precision_per_value
Mode
val
test
test_unseen
Precision_per_value
1.2
1.0
0.8
0.6
0.4
0.2
0.0
robot_has_obj
on
sliced
toggled
cleaned
cold
hot
two_task


Recall_per_value
Mode
val
test
test_unseen
Recall_per_value
1.2
1.0
0.8
0.6
0.4
0.2
0.0
robot_has_obj
on
sliced
toggled
cleaned
cold
hot
two_task

Precision_General_val

| predicate_type | arg1 | p_arg1 | arg2 | p_arg2 | f_predicate | f_predicate_sim | f_seq | f_seq_sim |
|---|---|---|---|---|---|---|---|---|
| 0.939 | 0.926 | 0.934 | 0.915 | 0.92 | 0.931 | 0.939 | 0.906 | 0.915 |

Precision_General_test

| predicate_type | arg1 | p_arg1 | arg2 | p_arg2 | f_predicate | f_predicate_sim | f_seq | f_seq_sim |
|---|---|---|---|---|---|---|---|---|
| 0.952 | 0.942 | 0.948 | 0.938 | 0.939 | 0.946 | 0.952 | 0.928 | 0.935 |

Precision_General_test_unseen

| predicate_type | arg1 | p_arg1 | arg2 | p_arg2 | f_predicate | f_predicate_sim | f_seq | f_seq_sim |
|---|---|---|---|---|---|---|---|---|
| 0.941 | 0.919 | 0.939 | 0.882 | 0.895 | 0.917 | 0.941 | 0.878 | 0.903 |

Recall_General_val

| predicate_type | arg1 | p_arg1 | arg2 | p_arg2 | f_predicate | f_predicate_sim | f_seq | f_seq_sim |
|---|---|---|---|---|---|---|---|---|
| 0.938 | 0.925 | 0.934 | 0.906 | 0.91 | 0.929 | 0.938 | 0.906 | 0.915 |

Recall_General_test

| predicate_type | arg1 | p_arg1 | arg2 | p_arg2 | f_predicate | f_predicate_sim | f_seq | f_seq_sim |
|---|---|---|---|---|---|---|---|---|
| 0.952 | 0.942 | 0.948 | 0.93 | 0.931 | 0.946 | 0.952 | 0.928 | 0.935 |

Recall_General_test_unseen

| predicate_type | arg1 | p_arg1 | arg2 | p_arg2 | f_predicate | f_predicate_sim | f_seq | f_seq_sim |
|---|---|---|---|---|---|---|---|---|
| 0.938 | 0.916 | 0.935 | 0.879 | 0.892 | 0.915 | 0.938 | 0.878 | 0.903 |

Precision_per_value_val

| robot_has_obj | on | sliced | toggled | cleaned | cold | hot | two_task |
|---|---|---|---|---|---|---|---|
| 0.966 | 0.92 | 0.977 | 1.0 | 0.955 | 0.937 | 0.991 | 0.993 |

Precision_per_value_test

| robot_has_obj | on | sliced | toggled | cleaned | cold | hot | two_task |
|---|---|---|---|---|---|---|---|
| 0.973 | 0.939 | 0.978 | 1.0 | 0.971 | 0.953 | 0.973 | 0.989 |

Precision_per_value_test_unseen

| robot_has_obj | on | sliced | toggled | cleaned | cold | hot | two_task |
|---|---|---|---|---|---|---|---|
| 0.986 | 0.895 | 1.0 | 1.0 | 0.957 | 1.0 | 0.991 | 0.972 |

Recall_per_value_val

| robot_has_obj | on | sliced | toggled | cleaned | cold | hot | two_task |
|---|---|---|---|---|---|---|---|
| 0.955 | 0.91 | 0.962 | 0.989 | 0.959 | 0.937 | 0.991 | 0.979 |

Recall_per_value_test

| robot_has_obj | on | sliced | toggled | cleaned | cold | hot | two_task |
|---|---|---|---|---|---|---|---|
| 0.955 | 0.931 | 0.978 | 0.982 | 0.971 | 0.96 | 0.979 | 0.994 |

Recall_per_value_test_unseen

| robot_has_obj | on | sliced | toggled | cleaned | cold | hot | two_task |
|---|---|---|---|---|---|---|---|
| 0.958 | 0.892 | 1.0 | 0.972 | 0.968 | 1.0 | 0.981 | 1.0 |