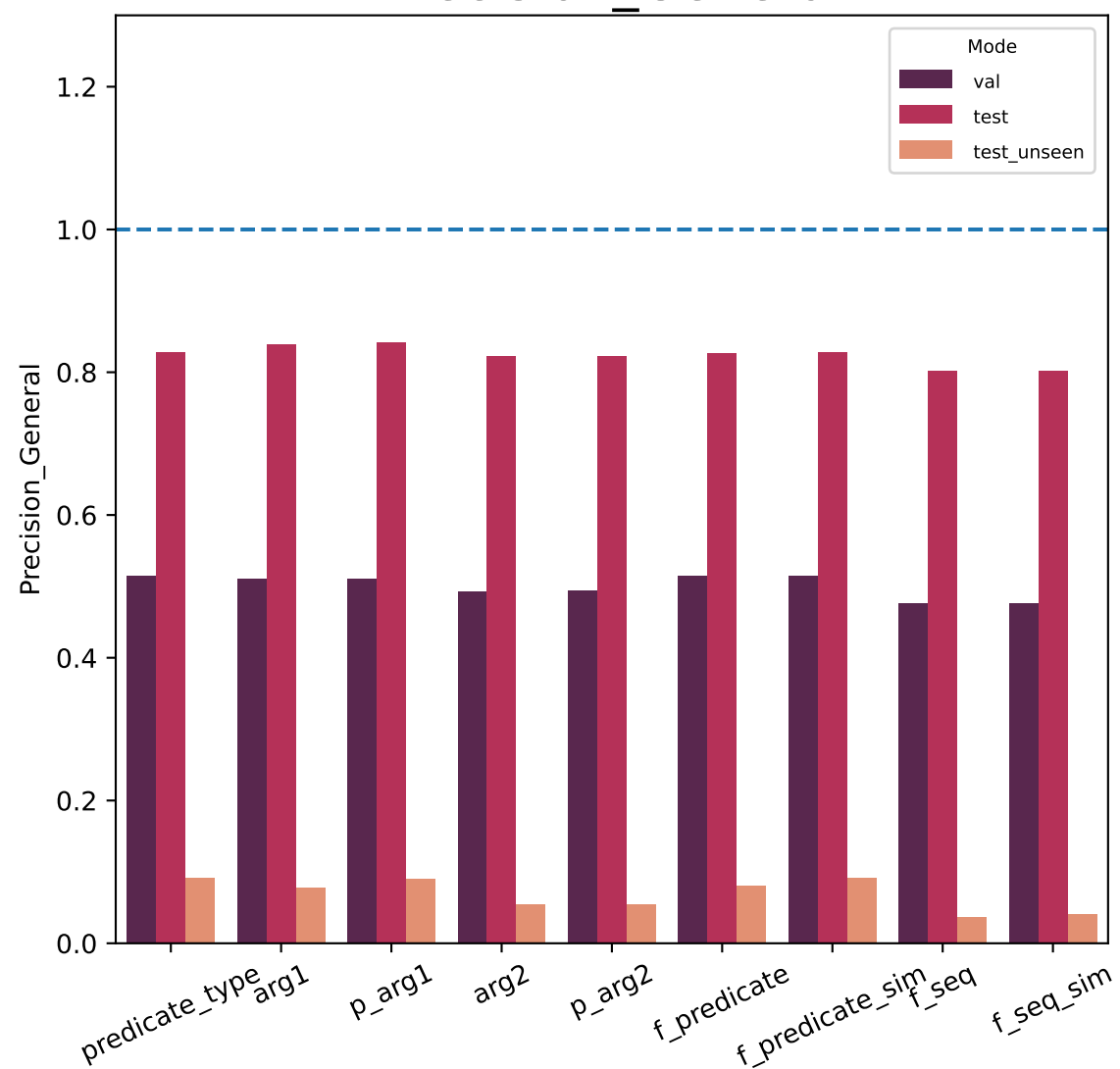
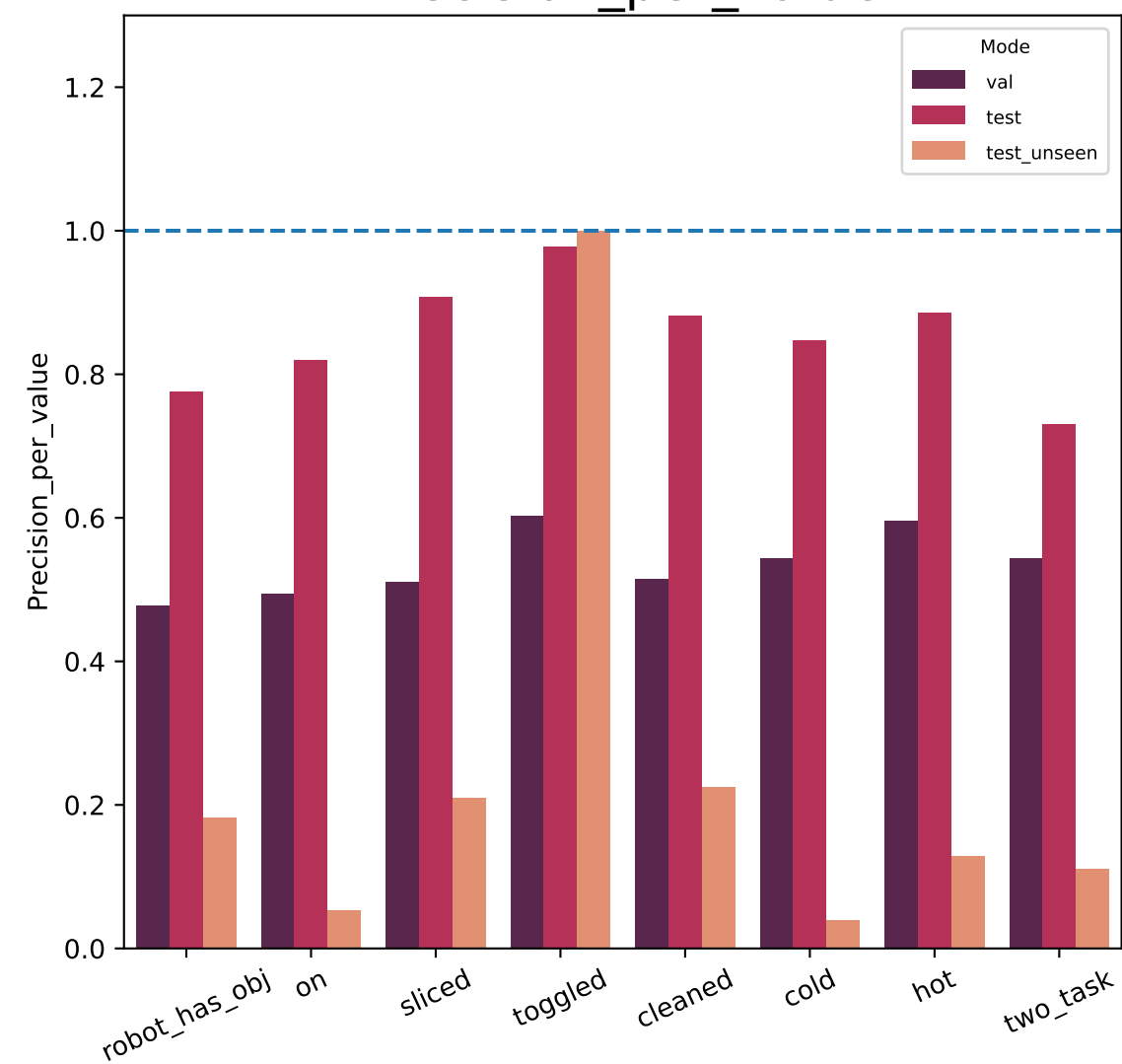


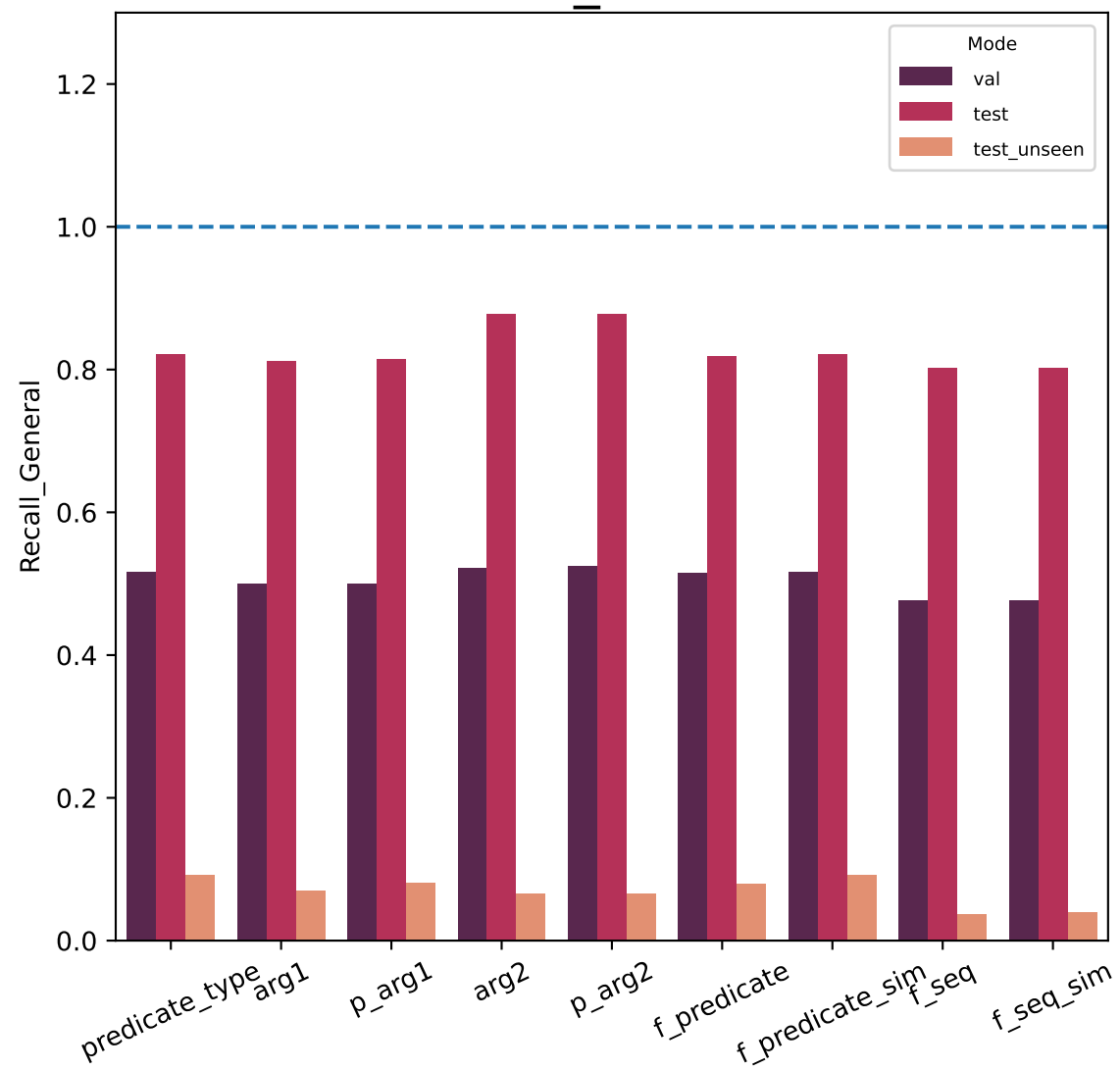
Precision_General



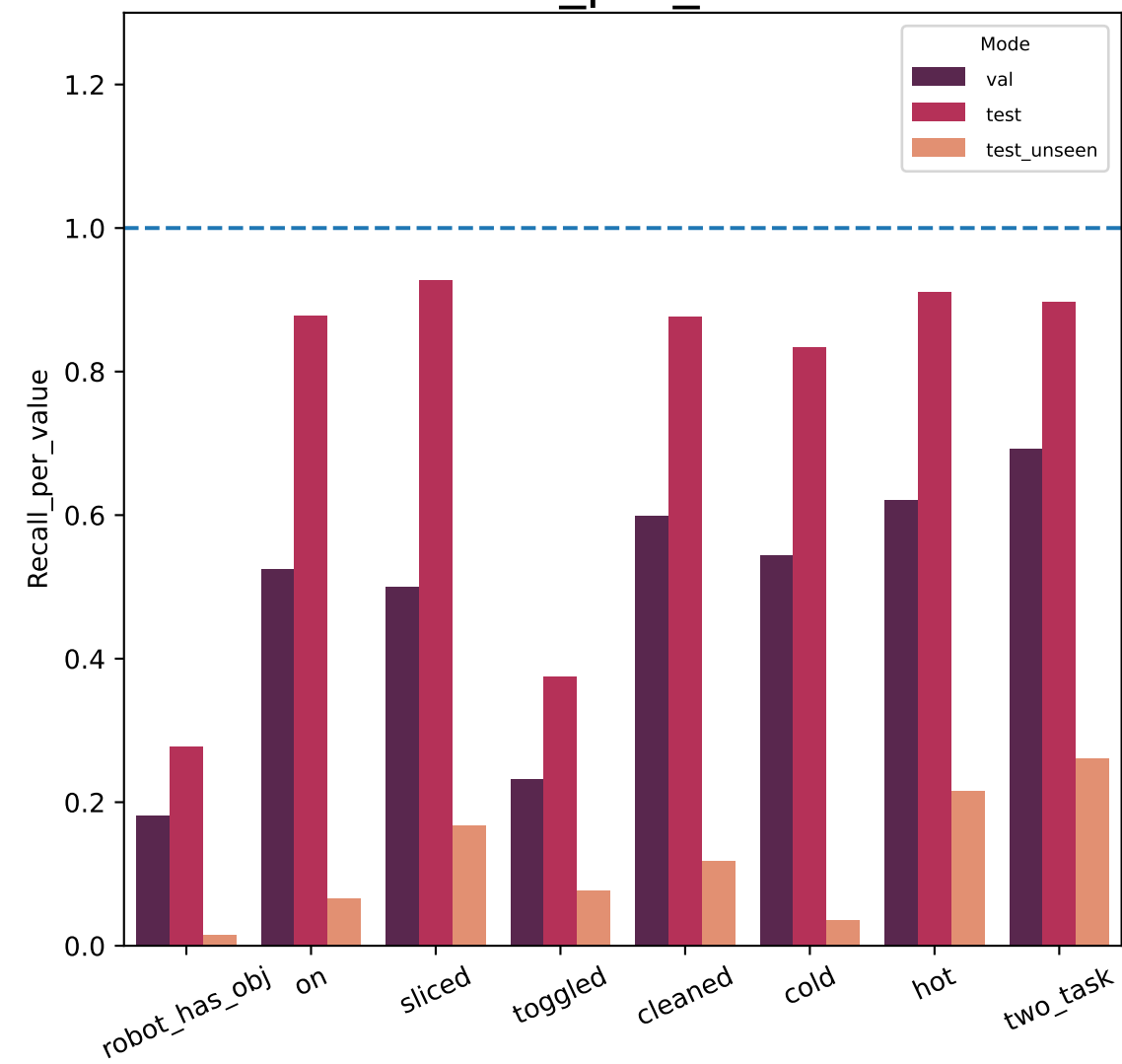
Precision_per_value



Recall_General



Recall_per_value



Precision_General_val								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.515	0.511	0.511	0.492	0.494	0.514	0.515	0.476	0.476

Precision_General_test								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.828	0.839	0.841	0.822	0.822	0.826	0.828	0.802	0.802

Precision_General_test_unseen								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.092	0.077	0.09	0.054	0.054	0.081	0.092	0.037	0.04

Precision_per_value_val								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.478	0.494	0.51	0.603	0.515	0.544	0.596	0.543	

Precision_per_value_test								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.775	0.82	0.907	0.977	0.882	0.847	0.886	0.73	

Precision_per_value_test_unseen								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.182	0.053	0.21	1.0	0.224	0.039	0.129	0.11	

Recall_General_val								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.516	0.499	0.499	0.522	0.524	0.515	0.516	0.476	0.476

Recall_General_test								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.821	0.812	0.814	0.878	0.878	0.819	0.821	0.802	0.802

Recall_General_test_unseen								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.091	0.07	0.081	0.065	0.065	0.079	0.091	0.037	0.04

Recall_per_value_val								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.181	0.524	0.5	0.232	0.599	0.544	0.621	0.692	

Recall_per_value_test								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.277	0.878	0.927	0.375	0.876	0.833	0.91	0.897	

Recall_per_value_test_unseen								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.014	0.065	0.167	0.077	0.118	0.035	0.215	0.261	