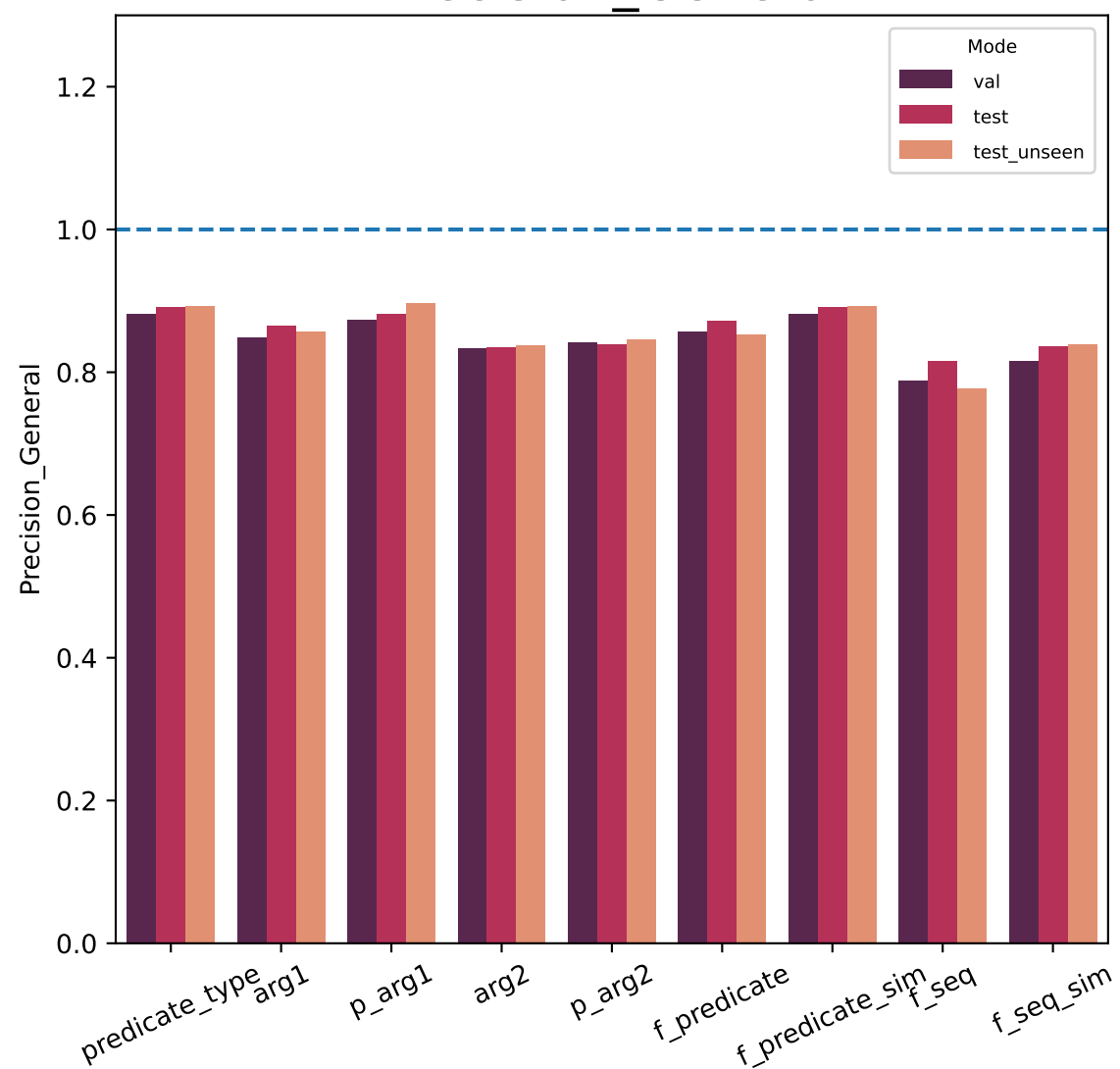
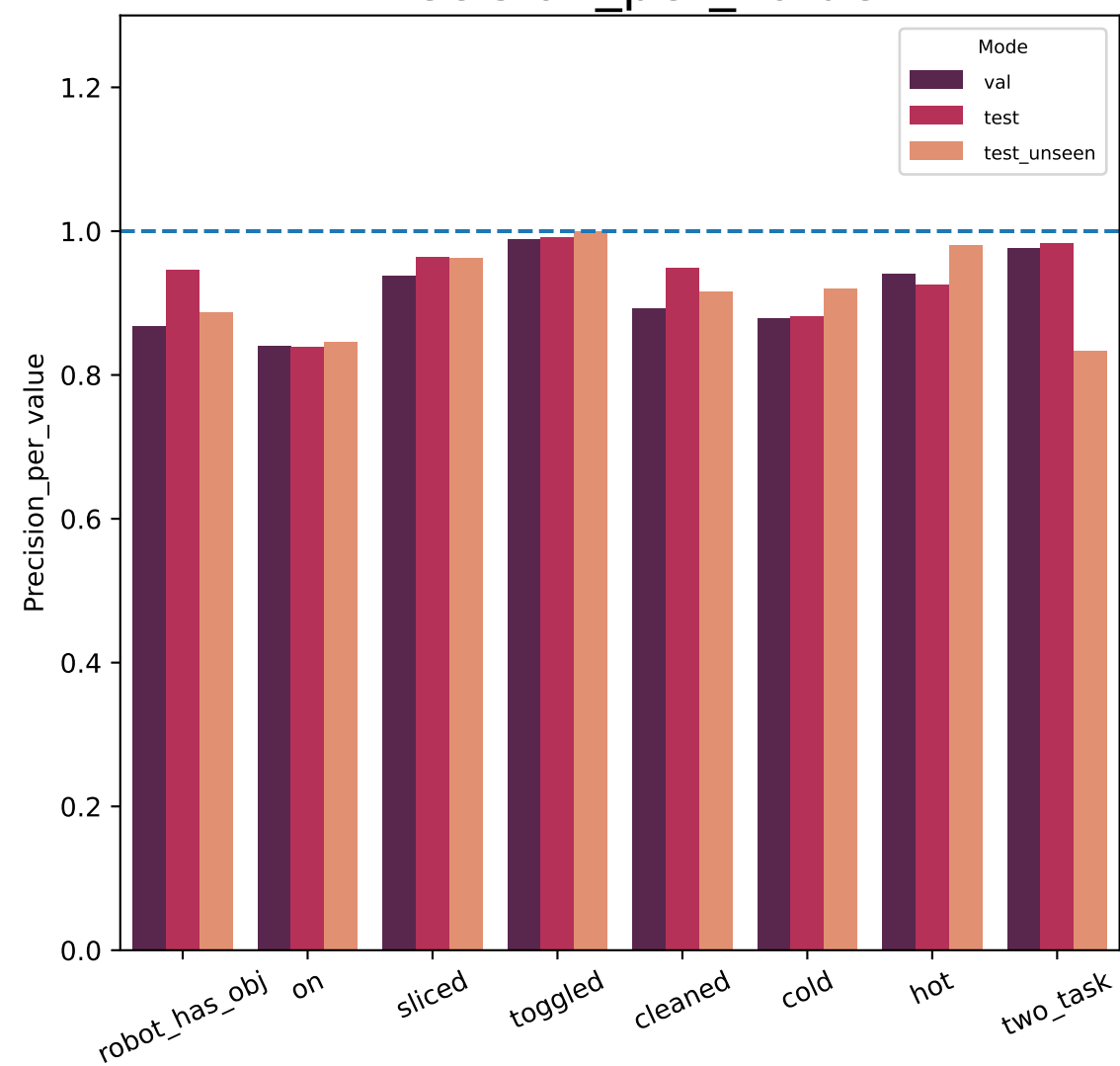


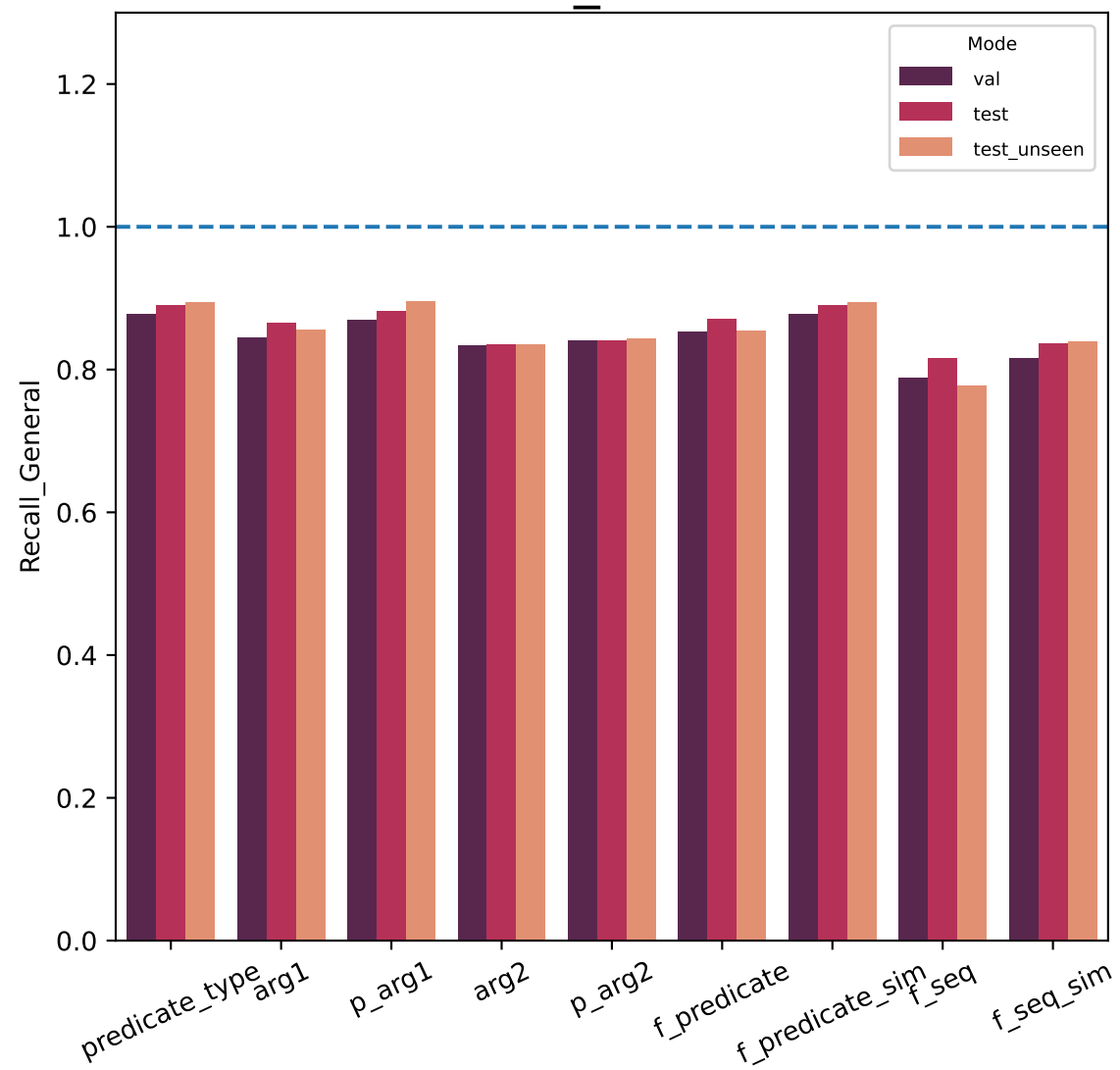
Precision_General



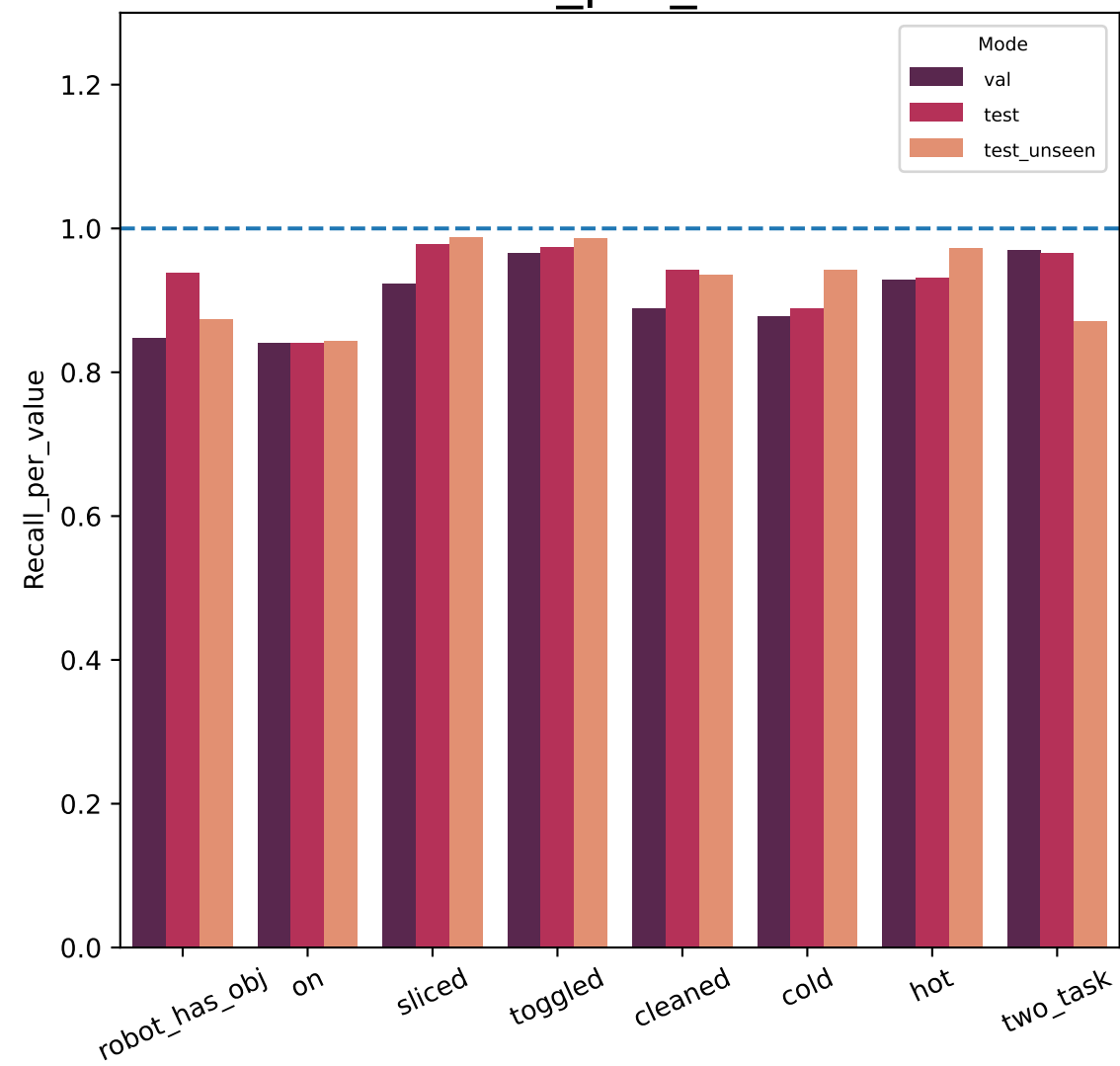
Precision_per_value



Recall_General



Recall_per_value



Precision_General_val								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.881	0.848	0.873	0.833	0.841	0.856	0.881	0.788	0.816

Precision_General_test								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.891	0.865	0.882	0.835	0.839	0.872	0.891	0.815	0.836

Precision_General_test_unseen								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.893	0.857	0.896	0.837	0.845	0.853	0.893	0.777	0.839

Precision_per_value_val								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.867	0.84	0.938	0.988	0.893	0.878	0.94	0.976	

Precision_per_value_test								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.946	0.839	0.964	0.991	0.949	0.882	0.925	0.983	

Precision_per_value_test_unseen								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.887	0.845	0.963	1.0	0.916	0.92	0.981	0.833	

Recall_General_val								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.878	0.845	0.869	0.834	0.841	0.853	0.878	0.788	0.816

Recall_General_test								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.89	0.865	0.882	0.835	0.84	0.871	0.89	0.815	0.836

Recall_General_test_unseen								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.894	0.856	0.895	0.835	0.843	0.854	0.894	0.777	0.839

Recall_per_value_val								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.847	0.841	0.923	0.966	0.888	0.878	0.928	0.969	

Recall_per_value_test								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.938	0.84	0.978	0.973	0.942	0.889	0.931	0.966	

Recall_per_value_test_unseen								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.874	0.843	0.987	0.986	0.935	0.942	0.972	0.87	