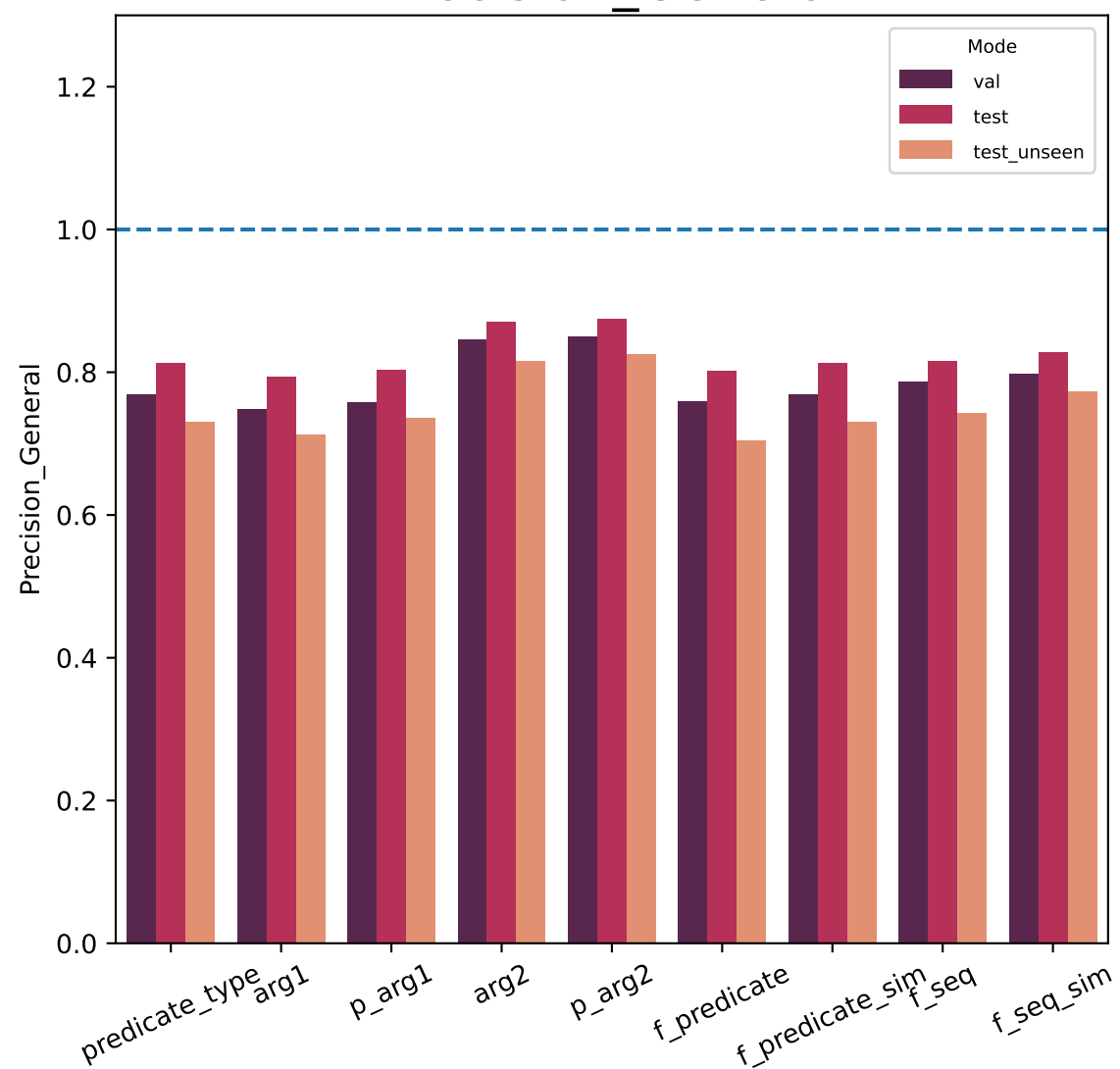
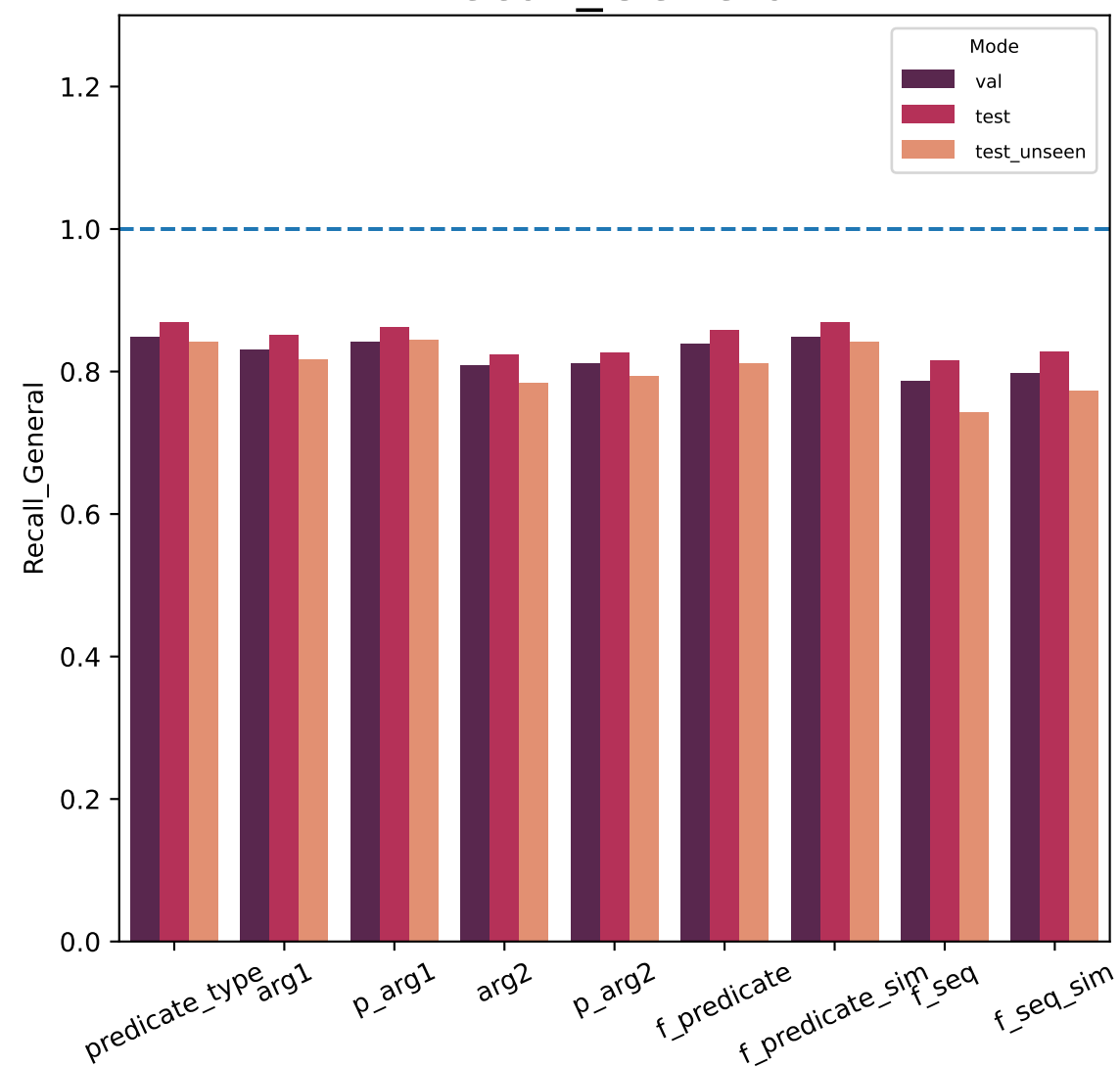


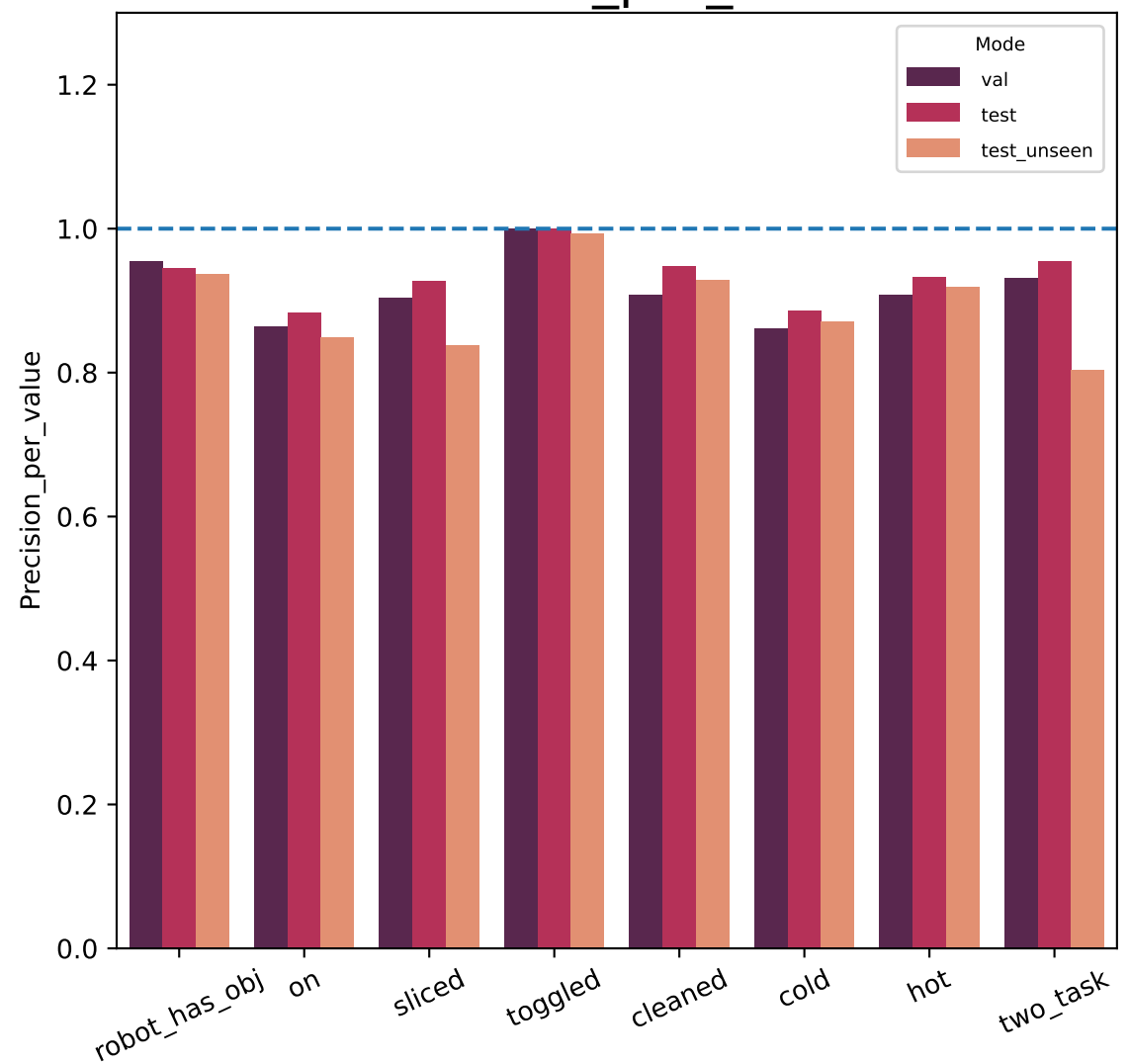
Precision_General



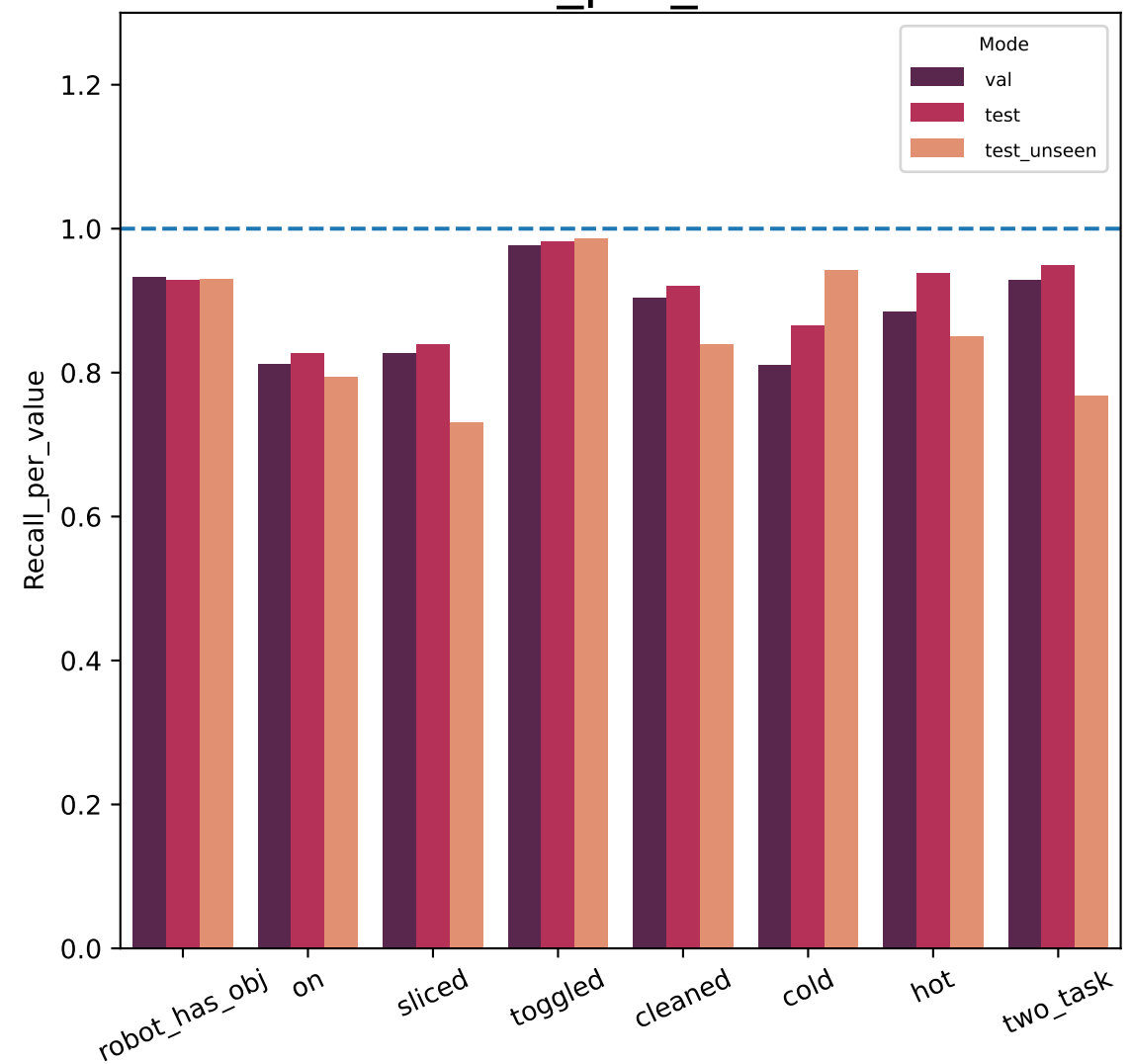
Recall_General



Precision_per_value



Recall_per_value



Precision_General_val								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.769	0.748	0.758	0.845	0.85	0.759	0.769	0.787	0.798

Precision_General_test								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.813	0.793	0.803	0.871	0.874	0.802	0.813	0.815	0.828

Precision_General_test_unseen								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.73	0.712	0.736	0.815	0.825	0.704	0.73	0.742	0.773

Recall_General_val								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.849	0.831	0.842	0.808	0.812	0.839	0.849	0.787	0.798

Recall_General_test								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.869	0.851	0.862	0.824	0.827	0.858	0.869	0.815	0.828

Recall_General_test_unseen								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.841	0.817	0.844	0.784	0.793	0.812	0.841	0.742	0.773

Precision_per_value_val								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.954	0.864	0.903	1.0	0.908	0.861	0.908	0.931	

Precision_per_value_test								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.945	0.883	0.927	1.0	0.947	0.886	0.932	0.954	

Precision_per_value_test_unseen								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.937	0.849	0.838	0.993	0.929	0.871	0.919	0.803	

Recall_per_value_val								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.932	0.812	0.827	0.977	0.904	0.81	0.885	0.928	

Recall_per_value_test								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.929	0.827	0.839	0.982	0.92	0.865	0.938	0.949	

Recall_per_value_test_unseen								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.93	0.793	0.731	0.986	0.839	0.942	0.85	0.768	