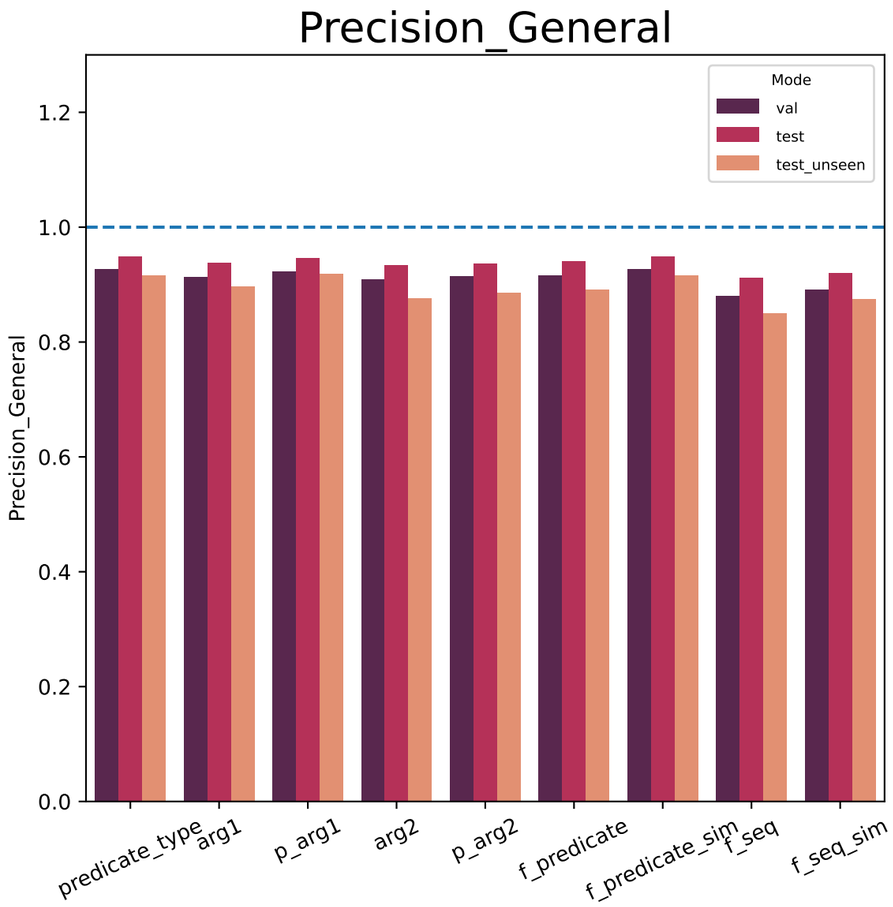
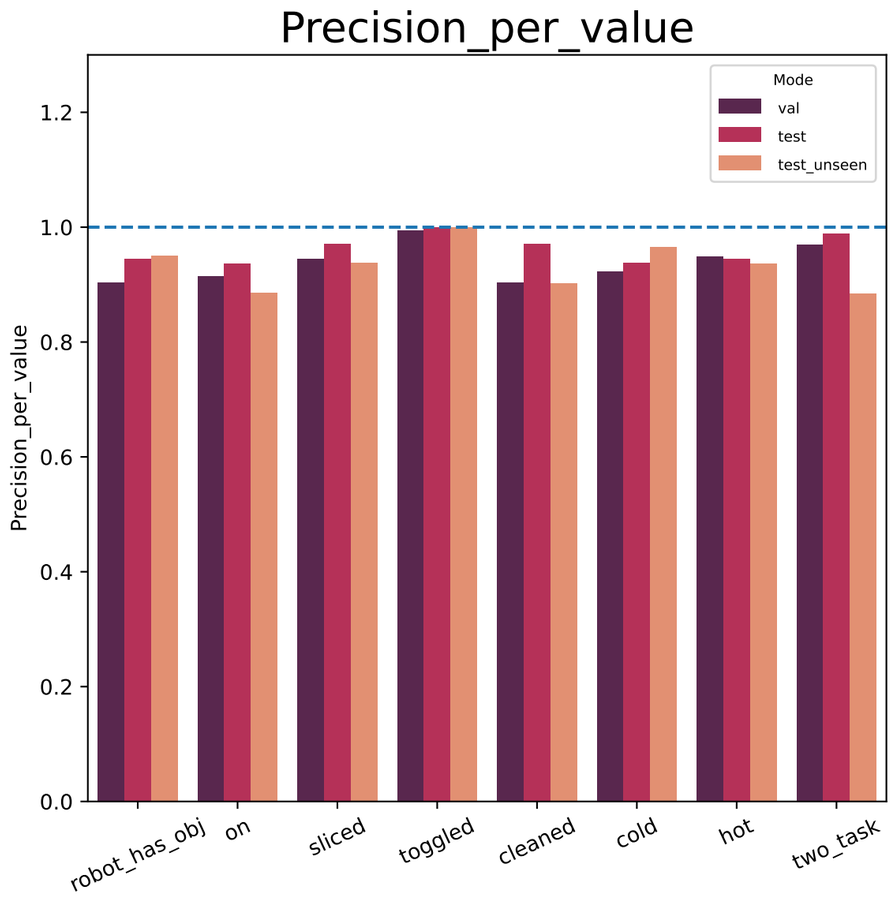
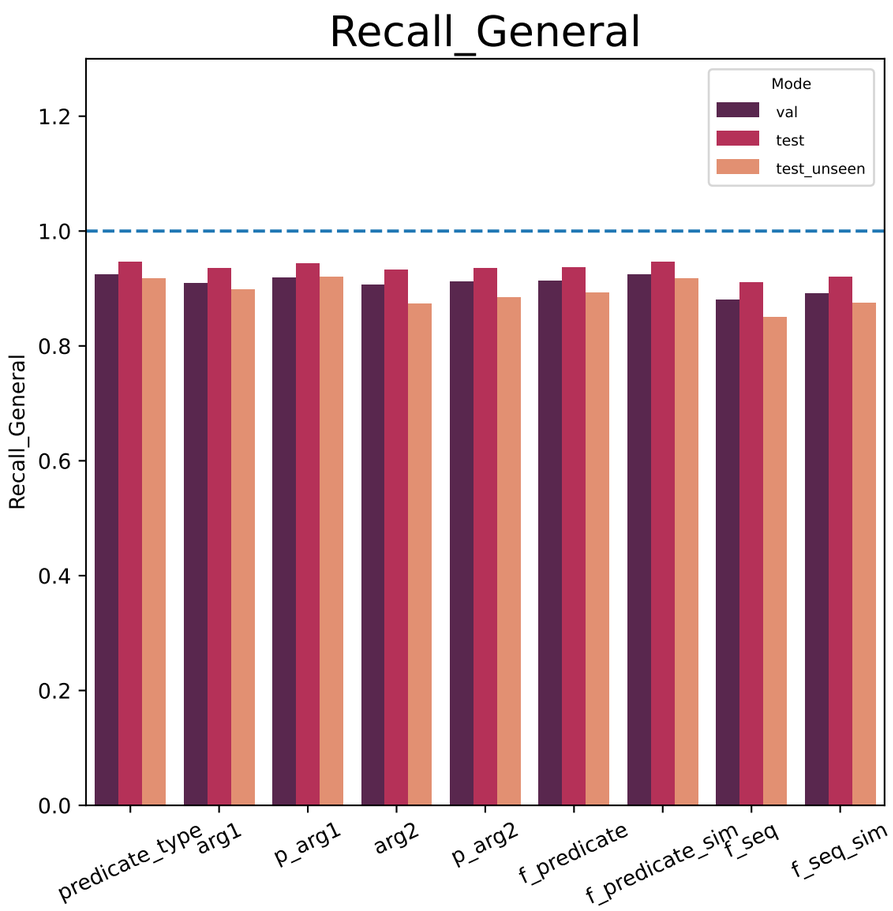

Precision_General
Mode
val
test
test_unseen
Precision_General
1.2
1.0
0.8
0.6
0.4
0.2
0.0
predicate_type
arg1
p_arg1
arg2
p_arg2
f_predicate
f_predicate_sim
f_seq
f_seq_sim


Precision_per_value
Mode
val
test
test_unseen
Precision_per_value
1.2
1.0
0.8
0.6
0.4
0.2
0.0
robot_has_obj
on
sliced
toggled
cleaned
cold
hot
two_task


Recall_General
Mode
val
test
test_unseen
Recall_General
1.2
1.0
0.8
0.6
0.4
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predicate_type
arg1
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f_predicate_sim
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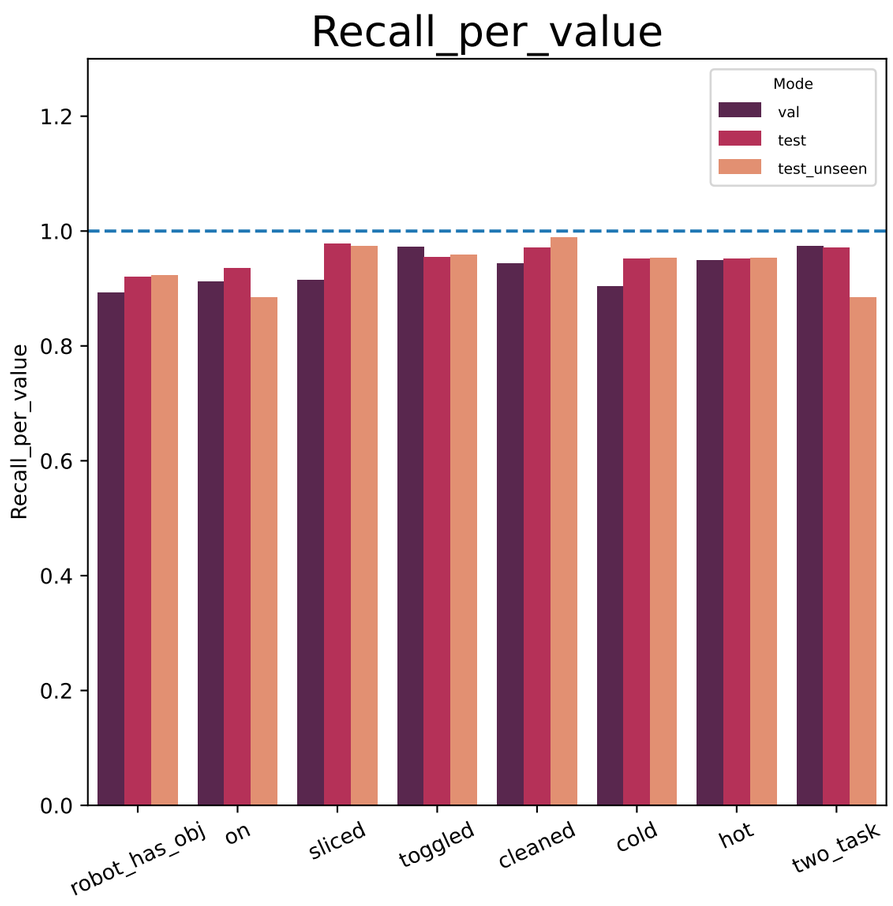
Recall_per_value
Mode
val
test
test_unseen
Recall_per_value
1.2
1.0
0.8
0.6
0.4
0.2
0.0
robot_has_obj
on
sliced
toggled
cleaned
cold
hot
two_task

Precision_General_val

predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.927	0.913	0.923	0.909	0.914	0.916	0.927	0.88	0.891

Precision_General_test

predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.949	0.938	0.946	0.933	0.936	0.941	0.949	0.911	0.92

Precision_General_test_unseen

predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.916	0.897	0.919	0.876	0.885	0.891	0.916	0.85	0.875

Precision_per_value_val

robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task
0.903	0.914	0.944	0.994	0.903	0.922	0.949	0.969

Precision_per_value_test

robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task
0.945	0.936	0.971	1.0	0.971	0.938	0.945	0.988

Precision_per_value_test_unseen

robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task
0.95	0.885	0.938	1.0	0.902	0.965	0.936	0.884

Recall_General_val

predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.924	0.909	0.919	0.907	0.912	0.913	0.924	0.88	0.891

Recall_General_test

predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.946	0.935	0.943	0.932	0.935	0.937	0.946	0.911	0.92

Recall_General_test_unseen

predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.918	0.898	0.92	0.874	0.884	0.893	0.918	0.85	0.875

Recall_per_value_val

robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task
0.893	0.912	0.915	0.972	0.944	0.903	0.949	0.973

Recall_per_value_test

robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task
0.92	0.935	0.978	0.955	0.971	0.952	0.952	0.971

Recall_per_value_test_unseen

robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task
0.923	0.884	0.974	0.958	0.989	0.953	0.953	0.884