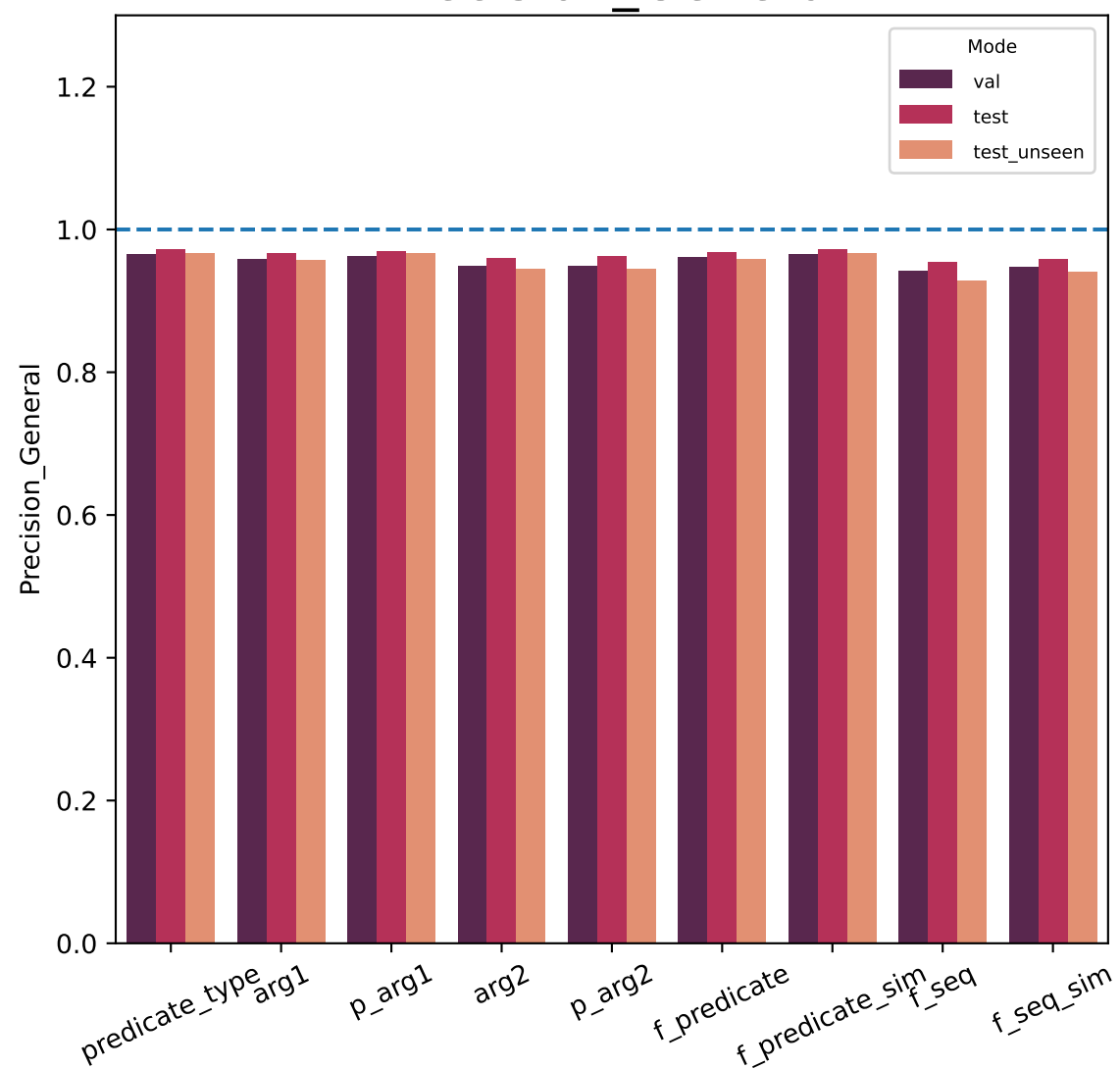
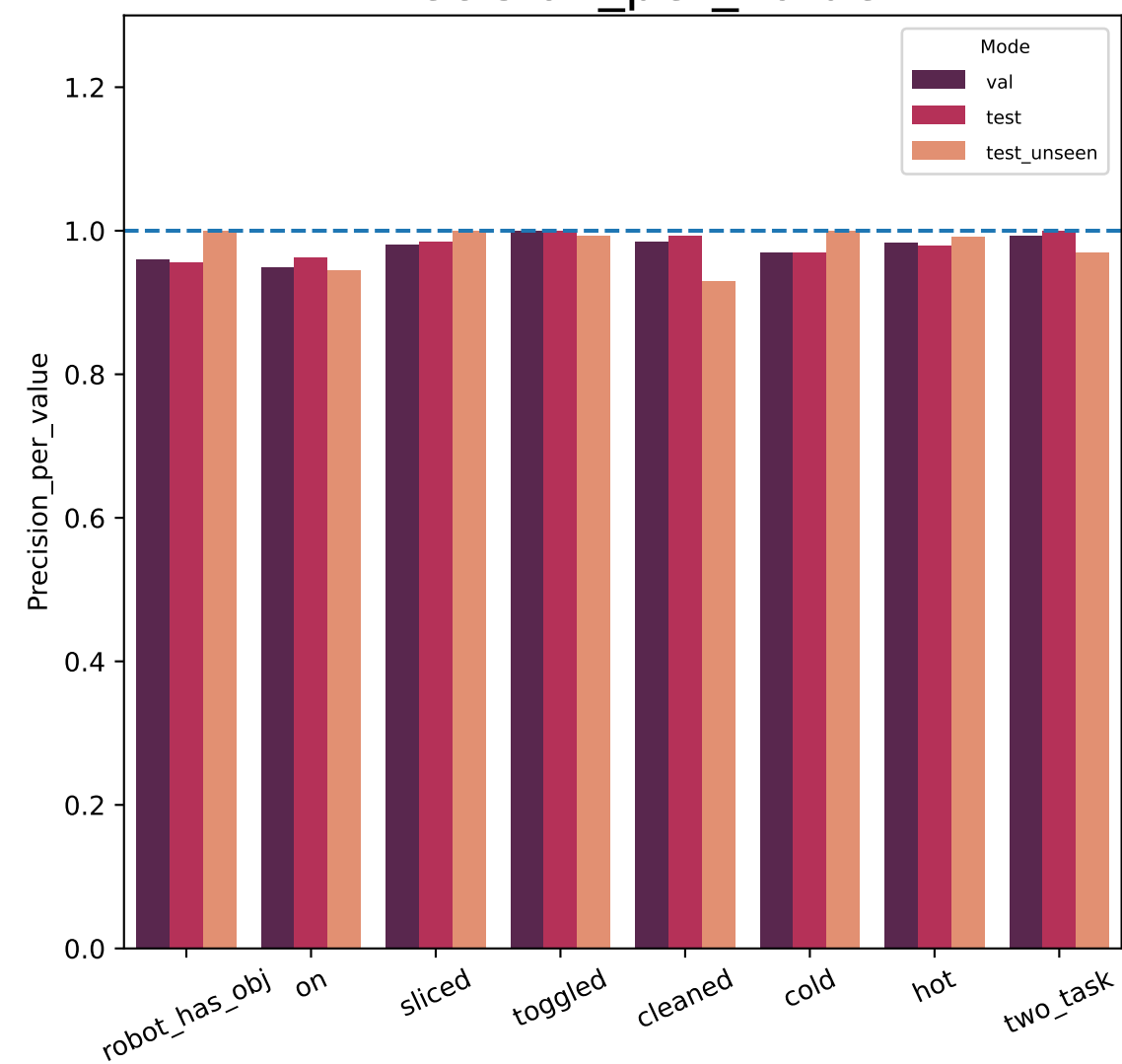


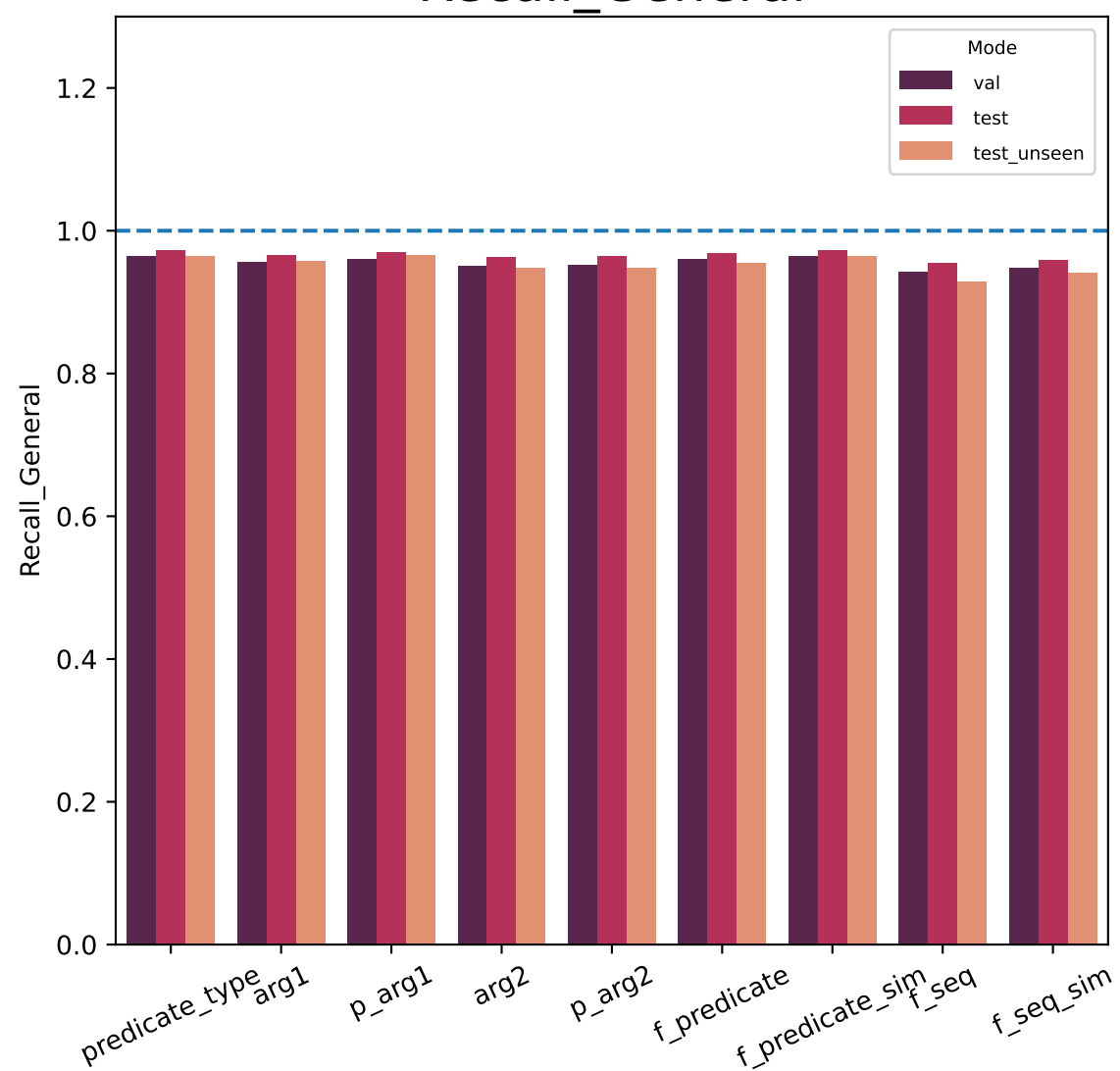
Precision\_General



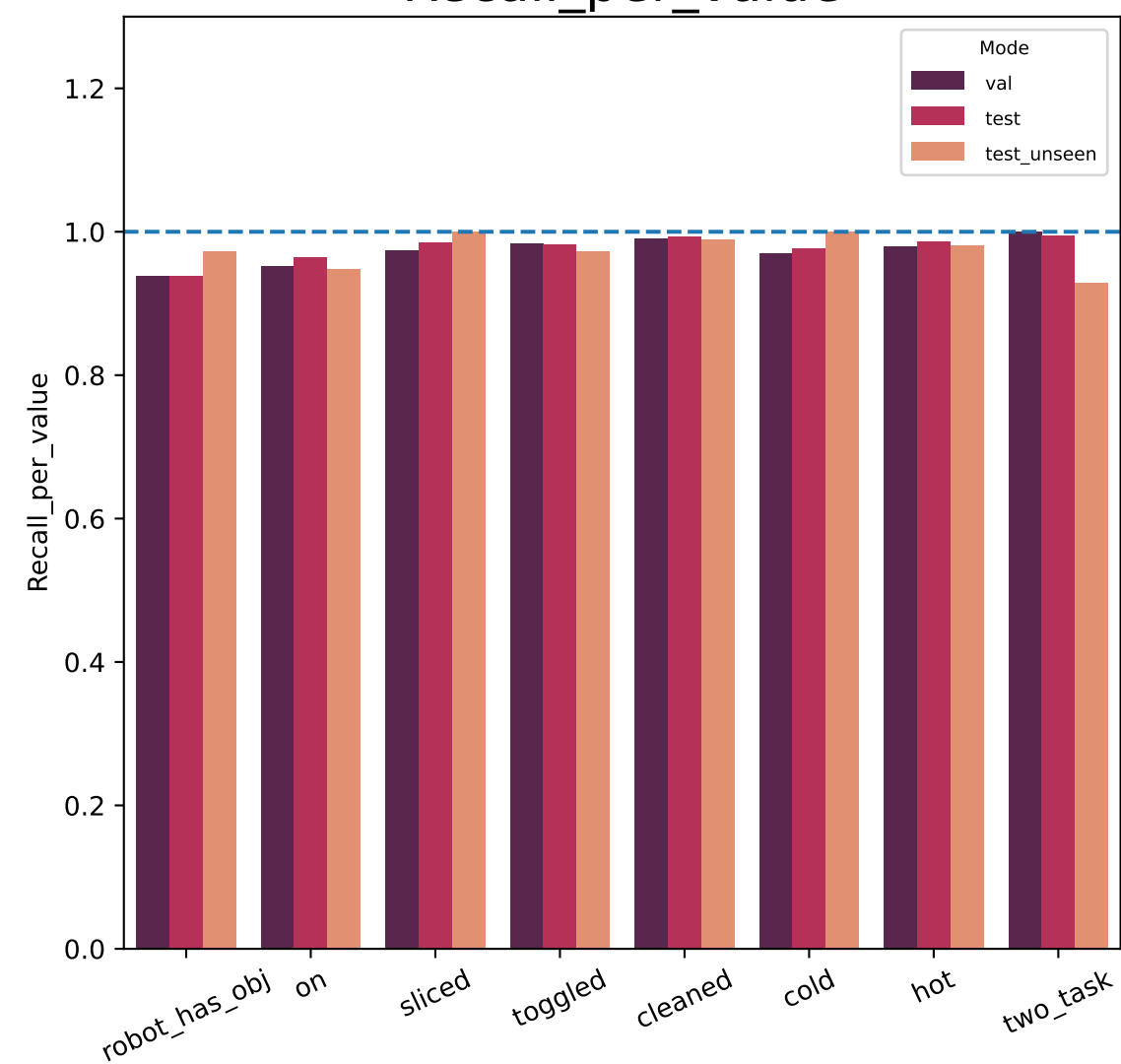
Precision\_per\_value



Recall\_General



Recall\_per\_value



Precision_General_val								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.965	0.958	0.962	0.949	0.949	0.961	0.965	0.942	0.947

Precision_General_test								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.972	0.966	0.97	0.96	0.962	0.968	0.972	0.954	0.958

Precision_General_test_unseen								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.966	0.957	0.966	0.945	0.945	0.958	0.966	0.928	0.941

Precision_per_value_val								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.96	0.949	0.981	1.0	0.985	0.97	0.983	0.993	

Precision_per_value_test								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.955	0.962	0.985	1.0	0.993	0.969	0.979	1.0	

Precision_per_value_test_unseen								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
1.0	0.945	1.0	0.993	0.929	1.0	0.991	0.97	

Recall_General_val								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.964	0.956	0.96	0.95	0.951	0.96	0.964	0.942	0.947

Recall_General_test								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.972	0.966	0.97	0.962	0.964	0.968	0.972	0.954	0.958

Recall_General_test_unseen								
predicate_type	arg1	p_arg1	arg2	p_arg2	f_predicate	f_predicate_sim	f_seq	f_seq_sim
0.964	0.957	0.966	0.948	0.948	0.955	0.964	0.928	0.941

Recall_per_value_val								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.938	0.951	0.973	0.983	0.99	0.97	0.979	1.0	

Recall_per_value_test								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.938	0.964	0.985	0.982	0.993	0.976	0.986	0.994	

Recall_per_value_test_unseen								
robot_has_obj	on	sliced	toggled	cleaned	cold	hot	two_task	
0.972	0.948	1.0	0.972	0.989	1.0	0.981	0.928	