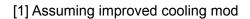
Copy this spreadsheet to customize your analysis!	Speed Constant (Kv)	Max Current*	Max voltage	Phase Resistance	Price (qty e 1pc)	Mass	Link	Torque	No-l	load speed		ower at se speed	Motor size constant (Km)	Force	Linear Velocity	Linear Acceleration	Time to base speed	Distance to base speed	Base speed kinetic energy	Encoder freq. (base speed)	
(feilds highlighted in blue are inputs)	rpm/V	Α	V	mOhm	USD	g		Nm	RPM	Rad	l/s	W	Nm/sqrt(W)	N	m/s	m/s^2	ms	mm	J	kHz	
ODrive Robotics D5065 - 270kv	270					42	0 https://odr	<u>iv</u> 1.99			04.78	1801	0.13	208.49	8.64	69.57					
ODrive Robotics D6374 - 150kv	150		48			89	0 https://odr	3.86	57	760 60	03.19	2328	0.23	404.15	5.76	134.87	42.71	123.00	31.52	196.608	
Tarot 4008 330kv	330	25	24	1	32	8	0 https://www	0.63	79	920 82	29.38	520		65.61	7.92	21.89	361.74	1,432.50	59.59	270.336	
Turnigy Aerodrive SK3 - 4250-350kv	350		20		36	26	6 https://hobb	<u>y</u> 1.18	70		33.04	866		123.72	7.00	41.29		5 593.42	2 46.55	238.9333333	
ACK 5312CP - 330KV	330		30		41	23	0 https://hobb	<u>y</u> 1.25	99	900 1,03	36.73	1299		131.22	9.90	43.79	226.09	1,119.14	93.11	337.92	
Turnigy Aerodrive SK3 - 5065-275kv	275	60	40	)	66	53	0 https://hobb	1.80	105	560 1,10	05.84	1995		188.95	10.56	63.05	167.47	7 884.26	105.94	360.448	
KEDA 63-64 190KV	190	50	40	)	49	67	0 https://hobb	2.18	72		64.04	1663		227.90	7.30	76.05	95.93	349.97	50.57	249.0368	
Turnigy Aerodrive SK3 - 6374-149kv	149	68	48	3	90	84	0 https://hobb	<u>y</u> 3.77	57	722 59	99.16	2261		395.23	5.72	131.89	43.38	124.10	31.10	195.29728	
9235-100KV Turnigy Multistar	100	57	48	3	103	67	4 https://hobb	*		340 40	02.12	1896		493.63	3.84	164.73	23.31	1 44.76	14.01	131.072	
Hoverboard Hub-motor	16	25 [1]	48	3	40	a lo	https://www	12.92	6	614 6	64.34	831		1,353.16	0.61	451.56	1.36	0.42	0.36	20.97152	
		*Note that to	orque and c	urrent rating	gs are with Ext	remely god	od forced air	cooling													
		See Torque																			
Parameter	Value	1/									_			250	)						
Bus voltage	48		5								_  _										
Max modulation	0.8									•	_								1995	•	_
Load mass	1.9	_							3.77	7 3.86	86			200						801	1896
Rotor inertia [2]	1.00E-04	_	4						•	•					)			1663			•
Pulley circumference or screw pitch		mm/rev	-								-  -									•	
Radius	0.009549296		-											150			1299				
Reflected inertia	1.10		Ē °										<b>E</b> (	0							
Peak brake power	1200		e e			2.	.18	1.99			-  -			ē							
Brake resistor resistance	1.92	ohm	Torque (Nm)					.80			_			§ 100			866				
Conversion constants					1	.18 <sup>1.25</sup>					-					ŧ	520				
by kv to Nm	8.269933431	1	_ 1		0.63	• •								500	)		•				
			'		0.03																
Encoder											_										
Encoder resolution	2048	ppr	0								_  _			(	)						
inear resolution	7.32	um		)	25		50	75		100					0	25		50	75		00
Max speed	15000	RPM					Price (\$)											Price (\$)			
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			orque (Nm)				1.99		·												
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			'		1.25, .18																
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			0,1	)	200	4	00	600		800	-  -										
			H	,	200			000		000	_										
							Weight (g)														



[2] Note: We should measure inertia of each individual motor. This is an estimate of 5065 size motors.