LINEAR ALGEBRA

D'P' contains all the polynomials and Q' is the subspace of Q, then Q should have zero polynomial.

(1, 'P' has zoro polynomial as Q.

$$Q = \{f(x) | f(0) = f(1) = 0\}$$

O polynomial lies in a or flo) = 0'

ve have to prove $g(x) + h(x) \in Q$.

Consider P(x) = h(x) + g(x)

$$b(0) = p(0) + b(0) = 0$$

P(x) EQ.

(ii) Let $\gamma(x) \in Q = \{f(x) \mid f(0) = f(i) = 0\}$

Consider CER.

to prove C. T(x) EQ.

check x = 0, (. x(0) = 0

x=1, C.x(i) =0

.. C. 8 (x) Satisty.

the conditions of subspace.

Jesus
$$U = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$

Zero vector in 5.

$$\begin{bmatrix} 0 & 0 & 0 \\ 2 \\ 1 \end{bmatrix} = 0.$$

So $0 + 1 = 0$

So $1 = [a + b]$
 $1 = [a + b]$

3) Gren vertors are [6], [1], [-1], [3] if it spons R3 then for any x, y, ze R there exist Ci, Cz, C3, C4 such that (x, y, z) = a (1,0,1)+ (2 (1,1,1),+ (3 (1,2,1) + (0, 3, 0). 2 000 · . ronk of matin = 2. Since the rank of matern is 2 it does not spon the sp subspace R3.

4) Given
$$V = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$
, $W = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$, $O = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

(a) $\int O Y$

det $V_1 = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

(b) $\int V Y$
 $V_1 = \begin{bmatrix} 2 \\ 0 \end{bmatrix}$
 $A_1 = 0$
 $A_2 = 0$
 $A_3 = 0$
 $A_4 = 0$
 $A_4 = 0$
 $A_4 = 0$

(c) $\int \{w, o\}$

ony set which contains a provector is linearly dependent.

(d) $\int V_1 \circ Y_2 \circ Y_3 \circ Y_4 \circ Y_4 \circ Y_5 \circ$

from (1), (2), (3) a=b=0. - fo, wy is linearly independent-(f) (v, w, oy -) lineally de pundent. i. dineasly dependent vectors a, c, d, F. 5) Given U, w are subspaces of V. Let U= (di /dz/ds) [non-zoro vector in U] W = (B, B2, B3) [non 3010 vector in v] for for wy to be linearly independent. Ou+ bw = 0 0 0 0 = 0 2 b = 0. a(a, a, a, x3) + b(B, B, B, B) = (0,0,0). (ax, +bB,, ax, + BB, + ax, +bB) = (0,0,0). ax, + bB, = 0 ad2 + bB, = 0. a a3+bB3 = 0 as By [a] = 0. ronk = 2, as there are no tree variables a=0 & b=0 i. fo, wy are timearly independent

G) Given
$$A = \begin{bmatrix} 4 & 0 & -2 \\ 2 & 0 & 4 \\ 0 & 0 & 4 \end{bmatrix}$$

Characteristic equation of motion A y

 $\begin{vmatrix} A - \lambda T \end{vmatrix} = 0$
 $\begin{vmatrix} 4 - \lambda & 0 & -2 \\ 2 & 5 - \lambda & 4 \\ 0 & 0 & 5 - \lambda \end{vmatrix} = 0$

Characteristic equation of motion A y

 $\begin{vmatrix} 4 - \lambda & 0 & -2 \\ 2 & 5 - \lambda & 4 \\ 0 & 0 & 5 - \lambda \end{vmatrix} = 0$

Characteristic equation of motion A y

 $\begin{vmatrix} 4 - \lambda & 0 & -2 \\ 2 & 5 - \lambda & 4 \\ 0 & 0 & 5 - \lambda \end{vmatrix} = 0$

Characteristic equation of motion A y

 $\begin{vmatrix} 4 - \lambda & 0 & -2 \\ 2 & 5 - \lambda & 4 \\ 0 & 0 & 5 - \lambda \end{vmatrix} = 0$

Characteristic equation of motion A y

 $\begin{vmatrix} 4 - \lambda & 0 & -2 \\ 2 & 5 - \lambda & 4 \\ 0 & 0 & 5 - \lambda \end{vmatrix} = 0$

Characteristic equation of motion A y

 $\begin{vmatrix} 4 - \lambda & 0 & -2 \\ 2 & 5 - \lambda & 4 \\ 0 & 0 & 5 - \lambda \end{vmatrix} = 0$

Characteristic equation of motion A y

 $\begin{vmatrix} 4 - \lambda & 0 & -2 \\ 2 & 5 - \lambda & 4 \\ 0 & 0 & 5 - \lambda \end{vmatrix} = 0$

Characteristic equation of motion A y

 $\begin{vmatrix} 4 - \lambda & 0 & -2 \\ 2 & 5 - \lambda & 4 \\ 0 & 0 & 5 - \lambda \end{vmatrix} = 0$

Characteristic equation of motion A y

 $\begin{vmatrix} 4 - \lambda & 0 & -2 \\ 2 & 5 - \lambda & 4 \\ 0 & 0 & 5 - \lambda \end{vmatrix} = 0$

Characteristic equation of motion A y

 $\begin{vmatrix} 4 - \lambda & 0 & -2 \\ 2 & 5 - \lambda & 4 \\ 0 & 0 & 5 - \lambda \end{vmatrix} = 0$

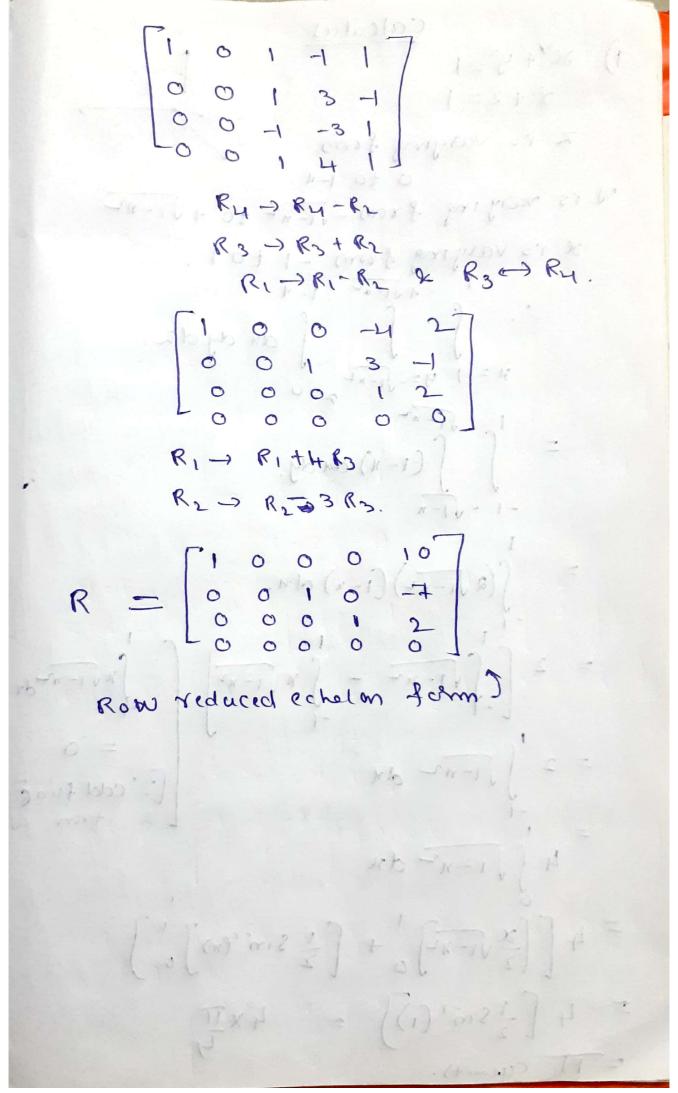
Characteristic equation of motion A y

 $\begin{vmatrix} 4 - \lambda & 0 & -2 \\ 2 & 5 - \lambda & 4 \\ 0 & 0 & 5 - \lambda \end{vmatrix} = 0$

Characteristic equation of motion A y

 $\begin{vmatrix} 4 - \lambda & 0 & -2 \\ 2 & 5 - \lambda & 4 \\ 0 & 0 & 5 - \lambda \end{vmatrix} = 0$

Characteristic equation of A and A is a second of



Calculus

$$2 + x = 1$$

$$2 + x = 1$$

$$2 + x = 1$$

$$3 + x = 1$$

$$4 + x$$

(2)
$$x^{2} + y^{2} = q$$
.

 $x = 312$
 $A = 3 \int_{Q-x^{2}} dx$.

 $x = 3e 3 \cos \theta$, $dx = -3 \sin \theta d\theta$.

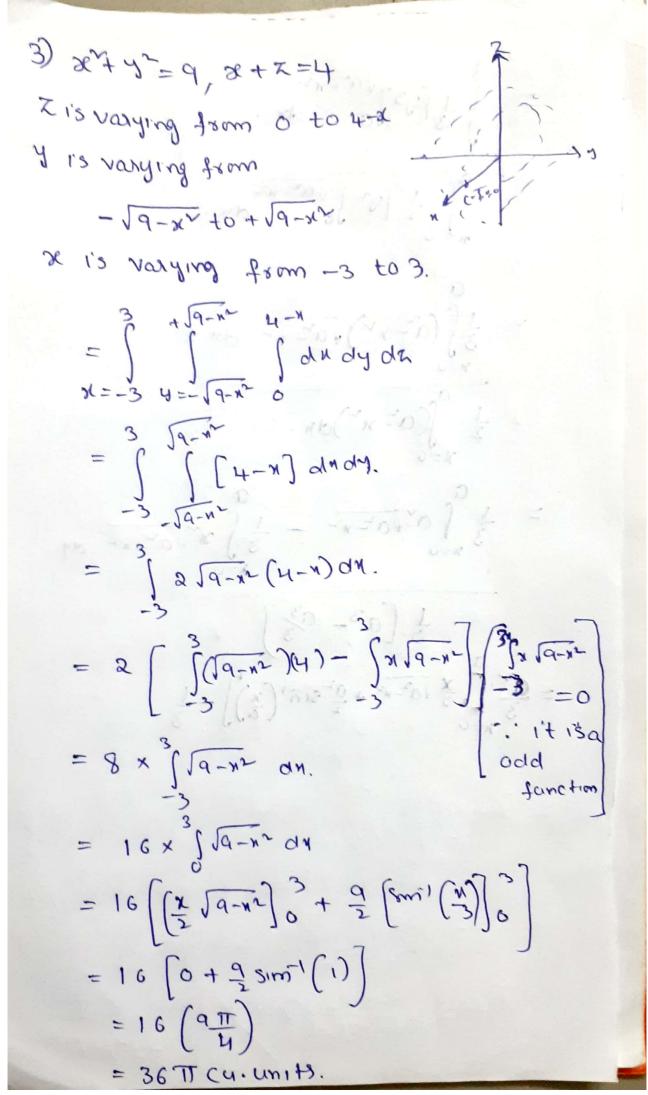
 $x = 3e 3 \cos \theta$, $dx = -3 \sin \theta d\theta$.

 $x = 3e 3 \cos \theta$, $dx = -3 \sin \theta d\theta$.

 $x = 3e 3 \cos \theta$, $dx = -3 \cos \theta$
 $x = 3e 3 \cos \theta$, $dx = -3 \cos \theta$
 $x = 4e \cos \theta$, $dx = -3 \cos \theta$
 $x = 4e \cos \theta$, $dx = -3 \cos \theta$
 $x = 4e \cos \theta$, $dx = -3 \cos \theta$
 $x = 4e \cos \theta$, $dx = -3 \cos \theta$
 $x = 4e \cos \theta$, $dx = -3 \cos \theta$
 $x = 4e \cos \theta$, $dx = -3 \cos \theta$
 $x = 4e \cos \theta$, $dx = -3 \cos \theta$
 $x = 4e \cos \theta$
 $x = 4e \cos \theta$, $dx = -3 \cos \theta$
 $x = 4e \cos \theta$, $dx = -3 \cos \theta$
 $x = 4e \cos \theta$, $dx = -3 \cos \theta$
 $x = 4e \cos \theta$, $dx = -3 \cos \theta$
 $x = 4e \cos \theta$

1- (withing of there's will pollution.

Scanned with CamScanner



$$\frac{1}{x^{2}} = \frac{1}{3} =$$

$$\ddot{y} = \frac{\pi \alpha y}{16}$$

$$\ddot{y} = \frac{3\alpha \pi}{16}$$

5)
$$T = \int_{(2-x)/3}^{1} \frac{1}{(2-x)/3} dx$$

it is on impropor integral of type 2.

$$T = \int_{(2-x)/3}^{1} \frac{1}{(2-x)/3} dx + \int_{(2-x)/3}^{1} \frac{1}{(2-x)/3} dy$$

$$T = \int_{(2-x)/3}^{1} \frac{1}{(2-x)/3} dx + \int_{(2-x)/3}^{1} \frac{1}{(2-x)/3} dy$$

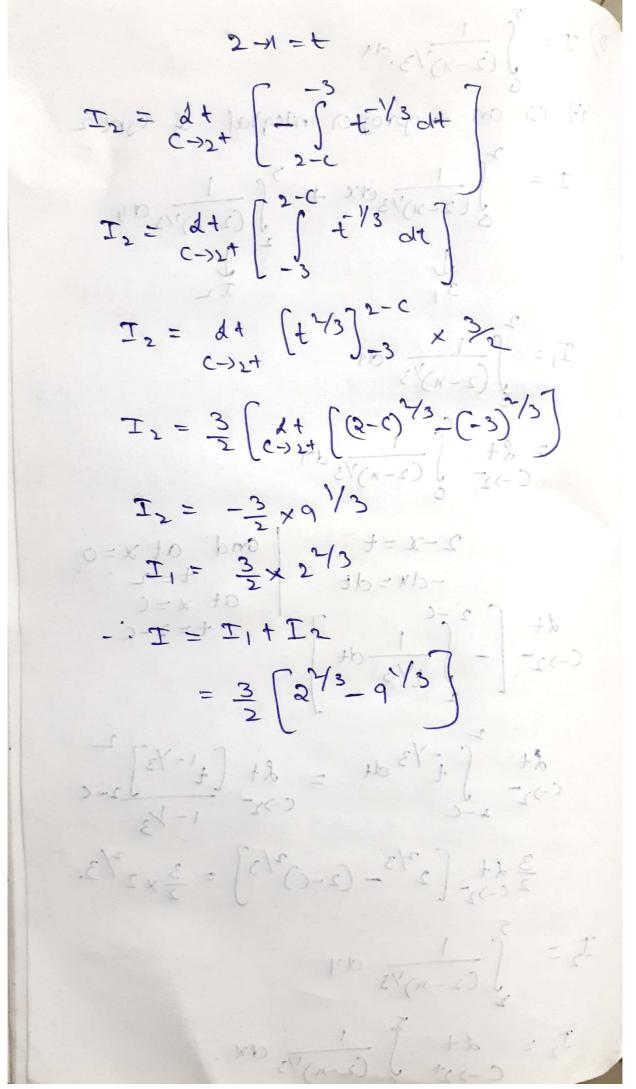
$$T = \int_{(2-x)/3}^{1} \frac{1}{(2-x)/3} dx + \int_{(2-x)/3}^{1} \frac{1}{(2-x)/3} dx$$

$$T = \int_{(2-x)/3}^{1} \frac{1}{(2-x)/3} dx = \int_{(2-x)/3}^{1} \frac{1}{(2-x)/3} dx$$

$$T = \int_{(2-x)/3}^{1} \frac{1}{(2-x)/3} dx$$

$$T = \int_{(2-x)/3}^{1} \frac{1}{(2-x)/3} dx$$

$$T = \int_{(2-x)/3}^{1} \frac{1}{(2-x)/3} dx$$



G) given
$$f(x) = x^3$$
 and $g(x) = tanil(x)$.

In intual [0,1]

Cauchy's mem value thedren.

 $\frac{f(b) - f(a)}{2} = \frac{g'(c)}{2}$

$$\frac{3(p)-3(a)}{3(c)}=\frac{3(c)}{3(c)}$$

$$\frac{1-0}{4} = \frac{3c^{2}}{1+c^{2}}$$

$$t = -3 \pm \sqrt{9 + 4 \times 3 \times 4}$$

+ should be positive.

$$-\frac{1}{4} = -3 + \sqrt{9 + \frac{48}{11}}$$

$$C = \sqrt{\frac{-3+\sqrt{9+44}}{6}}$$