TT-Series

6in/8in

# TT-2100



TT-2100G TT-2100CMG



# 77-2100G

# Mass production of various workpieces with high accuracy!

Takisawa twin chucker **TT-2100G** is a parallel twin-spindle lathe which is equipped with high speed gantry loader and supports mass production with high accuracy in 6"/8" chuck work.

#### Flexibly Supporting Any Type of Production

Takisawa twin chucker TT-series supports any type of production such as simultaneous front & back machining, symmetrical machining, and full automatic machining by connecting machines/creating production line, and provides excellent efficiency and high productivity.



## Environment Friendly

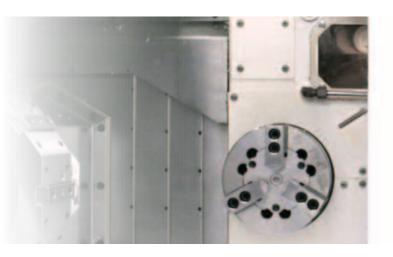
· Reduction of power consumption.

Regenerative energy system – the energy generated when the motor  $% \left( 1\right) =\left( 1\right) \left( 1\right) \left($ decelerates returns to the power supply - is applied.

Internal lighting shutoff function reduces standby power.

Control panel cooling design takes natural radiation amount into account to

- Coolant pump runs only when coolant is being used, reducing electric power.
- · Use of oil-water separator extends the coolant life.
- conventional machines.
- The powder coating machine for environmental concern.





#### Bed

The bed has a tank bed structure which can keep thermal displacement to the minimum all day.

Tank capacity = 350L

#### **Sliding Surface**

Wide rectangular slideways are used in the X-/Z-axes sliding

surfaces to realize stable machining with high accuracy over a long period of time.



#### Headstock

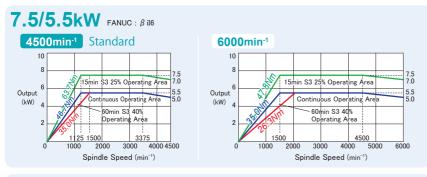
Both of stable cutting and high speed loader transfer are achieved by adopting a structure of low center of gravity in which the center height of the headstock from the floor surface kept low.

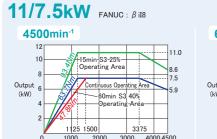
There are two types of specifications for high accuracy spindle on the headstock: "6" chuck specification" and "8" chuck specification", which are combined with FANUC's high performance spindle motors to provide excellent performance.

Movable partition covers are provided at the center between the two spindles to secure safety and workability.

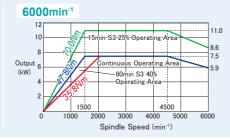


#### 6"Chuck Type

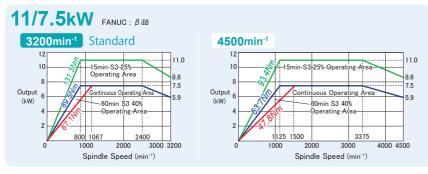




Spindle Speed (min-1)



#### 8"Chuck Type



## 6"Chuck Type

Spindle Stock and Spindle Moto
--------------------------------

Bearing Inside Diameter	φ 80		
Spindle Nose	φ140F		
Spindle Motor	7.5/5.5kW		
Culturally Constant	4500min <sup>-1</sup>		
Spindle Speed	6000min <sup>-1</sup>		
Spindle Motor	11/7.5kW		
Spindle Speed	4500min <sup>-1</sup>		
Spiritile Speed	6000min <sup>-1</sup>		

#### Standard Chuck and Cylinder

Chuck Type	H01MA6
Travel of Jaw (Diameter)	7mm
Max. Speed	4500min <sup>-1</sup>
Cylinder Type	HH9C100
Max. Speed	6500min <sup>-1</sup>

#### 8"Chuck Type

#### Spindle Stock and Spindle Motor

Bearing Inside Diameter	φ90
Spindle Nose	φ140F
Spindle Motor	11/7.5kW
	3200min <sup>-1</sup>
Spindle Speed	4500min <sup>-1</sup>

#### Standard Chuck and Cylinder

Chuck Type	H01MA8
Travel of Jaw (Diameter)	7mm
Max. Speed	4000min <sup>-1</sup>
Cylinder Type	HH9C125
Max. Speed	6000min <sup>-1</sup>

Red is Optional.

#### Turret

The turret is the all-holder powerful type with bolt clamping system.

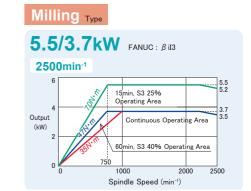
10-station turret (T10) is equipped as standard, and 12-station turret (T12) for multiple processes and 10-station milling turret (T10M) for milling processes are optionally available.

In a 10-station milling turret (T10M), milling holders can be equipped to five stations (every second station).

Items	Items	Items	6" Chuck Type	8" Chuck Type
10-Station Turret	T10	Height of Square Tool Shank	□20	□25
	(Standard)	Diameter of Boring Bar Shank	φ25	φ32
12-Station Turret	T12	Height of Square Tool Shank	□20	□25
	(Optional)	Diameter of Boring Bar Shank	φ25	φ32
10-Station Turret	T10M	Height of Square Tool Shank	□20	□25
	(Optional)	Diameter of Boring Bar Shank	φ25	φ32
		Max. Rotary Tool Shank Diameter	φ16	φ16





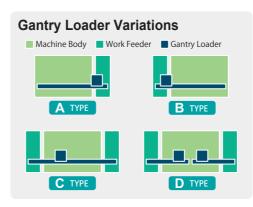


#### **Gantry Loader**

The machine's center of gravity is thoroughly lowered and the loader axis is improved to move faster and quieter to realize optimum cycle time.

Loader Cycle Time 19.6 sec

(6"Chuck Type、A Type Gantry)





Quality Chute (NG Chute)
The portion to pick workpieces
out to check the quality during
automatic operation.

Work Feeder

#### Loader Specification (A or B Type)

	Items		6" Chuck Type	8" Chuck Type	
Target	Outside Diameter	$\phi$ 80mm	φ160mm		
	Length	80mm	80mm		
	Workpiece	Weight	0.7kg (×2)	3kg (×2)	
Running X-Axis (Longitudinal)		200m/min	180m/min		
	Speed	Y-Axis (Vertical)	150m/min	150m/min	

#### Work Feeder Specifications

'		
Items	6" Chuck Type	8" Chuck Type
Number of Pallets	16	16
Loading Capacity (1 Pallet)	40kg	40kg
Maximum Height	450mm	450mm

#### Reversing Device

The device allows simultaneous front and back machining.

\* Unlike connecting two one-spindle lathes with a reversing device provided between them, even the space efficiency is obvious.



#### **Pursuing Operability**



#### · Dedicated Switch

A dedicated switch to call a desired function to the operation panel with one push is provided for smooth work.



#### 2 Program Reset Function

Left/right/loader programs can be reset and rewound.

#### 3 Zero Point Return Function

It allows left/right X- and Z-axes zero point return and loader X-, Y-, and Z-axes zero point

\*) Subject to some conditions. For details, contact us.

#### Function to minimize inputting error on right and left.

#### 4 Right/Left Selection Button

Operate the machine after selecting right or left with the button. Operation is possible only on the side with the indication lamp turned on. When both of the lamps are turned off, the machine cannot be operated.



#### Operation on Right Side

The information on the right side is displayed on the screen and you can operate the right side.





#### 5 Chuck Open/Close Switch





#### 6 Machine Operation Panel Screen

The machine operation panel is displayed on the screen. Buttons can be added and displayed/undisplayed easily.

#### 7 Information Display Window

"Right/left selection, indexed turret number of right/left machine, and number of workpieces on right/left" can be checked in the upper right of the screen.

#### · Information on Right and Left is Displayed Simultaneously (Specific Screen) On the tool offset screen and the workpiece shift screens, inputting errors are avoided by color coding of right/left, the zoom function and simultaneous display.

In addition, software pursuing operability is provided as standard to reduce nonproductive time during setup work.

# LT08

▲ Tool Offset Display

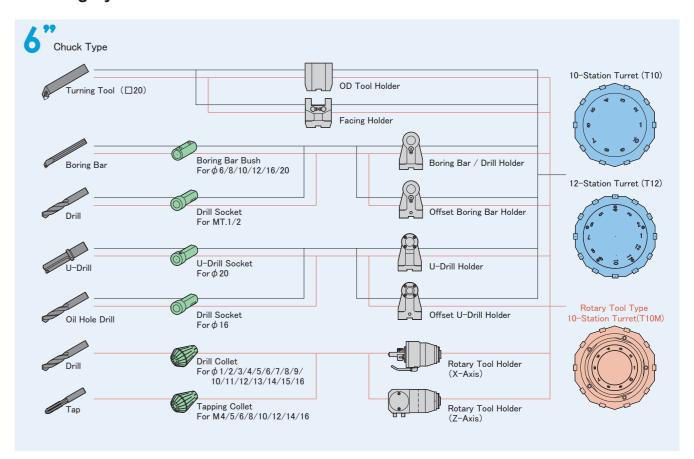
LT08 RT08

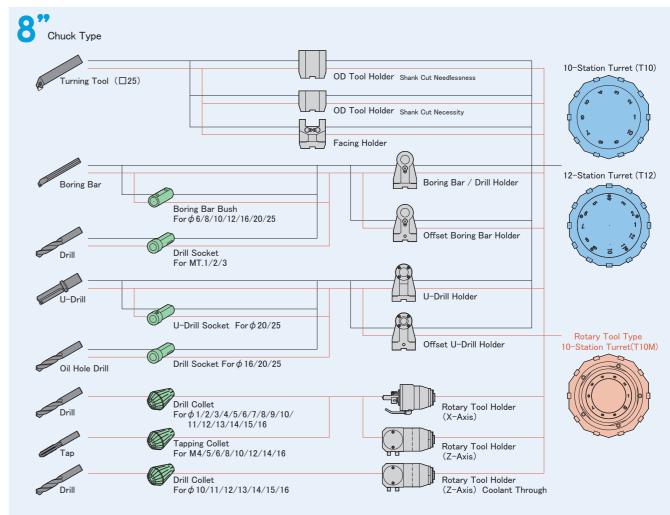
▲ Program Display

unn t :

In addition, software pursuing operability is provided as standard to reduce non-productive time during setup work. Refer to page 13.

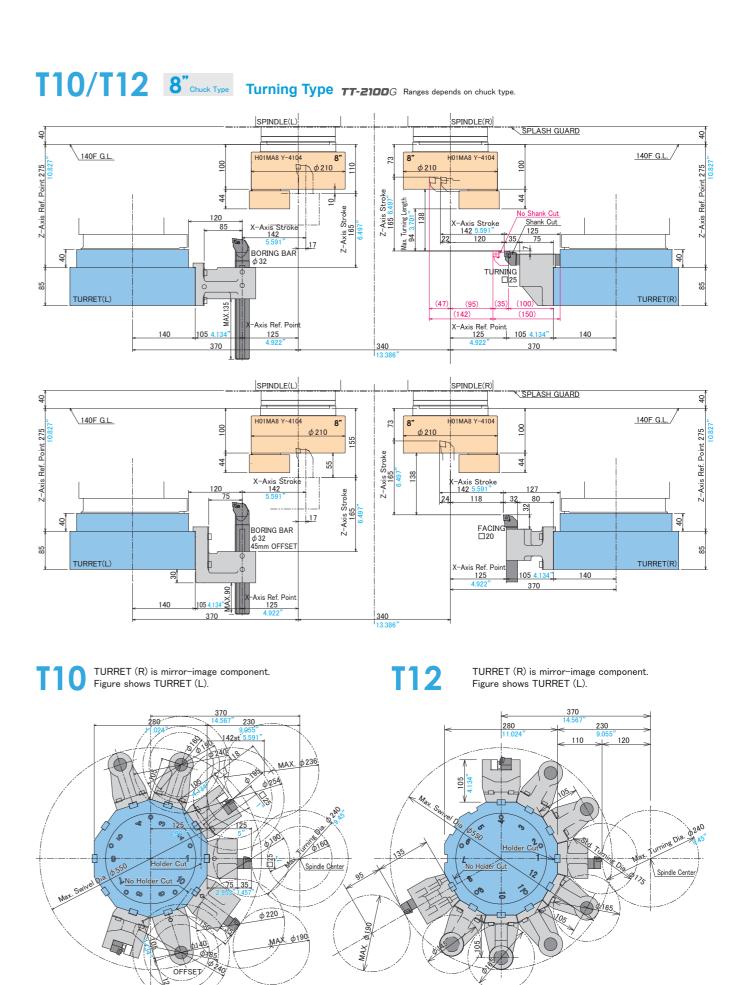
#### ■ Tooling System





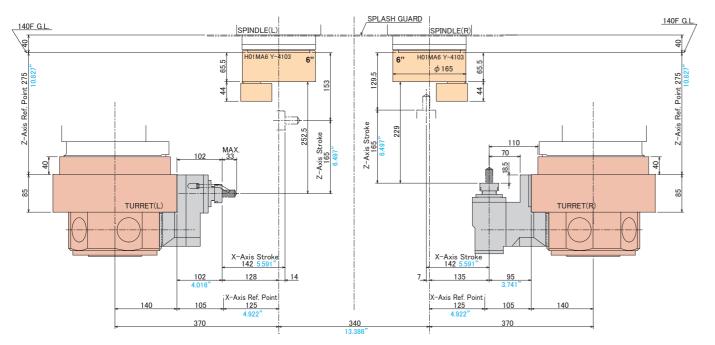
The contents of the catalog are subject to change for improvement without notice. Please make confirmation from our sales representatives when entering into the contract.

# T110/T12 6"Chuck Type Turning Type TT-2100G Ranges depends on chuck type. SPLASH GUARD 140F G.L. 140F G.L. BORING BAR TURRET(L) TURRET(R) (-Axis Ref. Point 140 XIf the tool cannot approach the chuck sufficiently, adjust the tool overhang with the end face holder. SPLASH GUARD 140F G.L. 140F G.L. Z-Axis Stroke 165 6.497" 142 5.591" 125 TURRET(F TURRET(L) TURRET (R) is mirror-image component. Figure shows TURRET (L). TURRET (R) is mirror-image component. Figure shows TURRET (L). 9.055 . 110

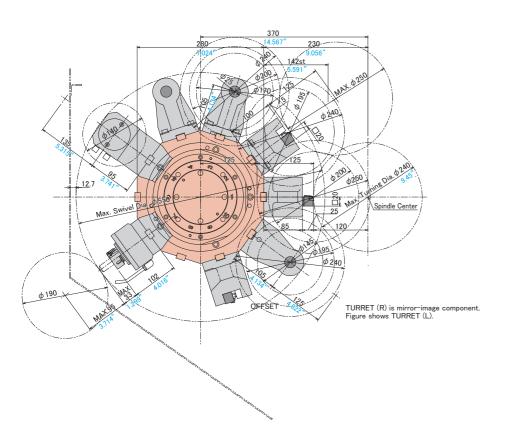


#### ■ Travel Range and Interference Unit: mm inch

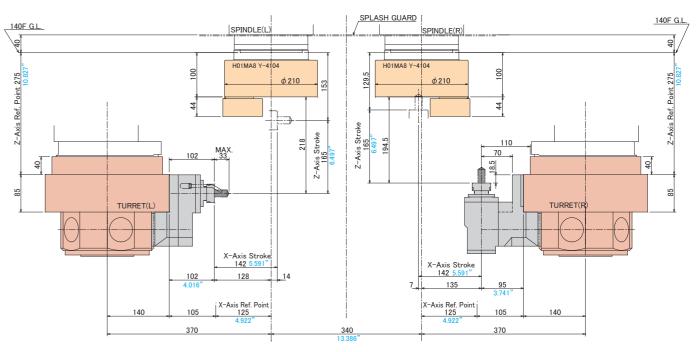
# T10M 6"Chuck Type Milling Type TT-2100CMG Ranges depends on chuck type.

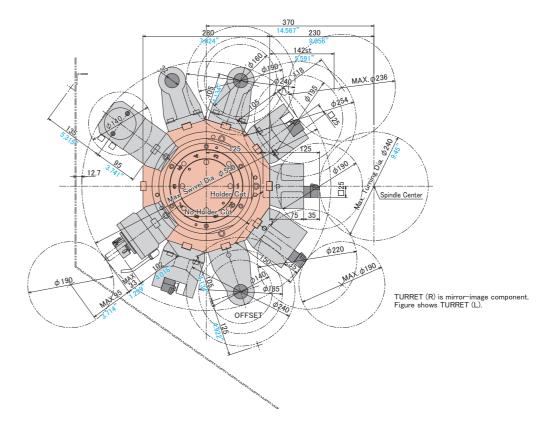


The contents of the catalog are subject to change for improvement without notice. Please make confirmation from our sales representatives when entering into the contract.









#### Machine Specifications (with A or B Type Loader)

Items		6" Chuck Type		8" Chuck Type				
			TT-21	00G	TT-2100CMG	TT-21	00G	TT-2100CMG
			T10	T12	T10	T10	T12	T10
0 1.111	Distance Between Spindles	mm inch		340 13.38	,		340 13.38"	•
Capability •	Max. Turning Diameter	mm inch		240 9.45"			240 9.45"	
Capacity	Max. Turning Length	mm inch		135.5 <b>5.33</b> "			94 3.7"	
Torrest	X-Axis Travel	mm inch	142 5.59"		142 5.59"			
Travel	Z-Axis Travel	mm inch		165 6.5"			165 6.5"	
	Number of Spindles		2			2		
	Spindle Speed	min <sup>-1</sup>		4500 6000			3200 4500	
Spindle	Min. Index Angle (Cs-Axis)	deg	_	-	0.001	-	-	0.001
Spinale	Spindle Nose (Nominal Code)			φ140F			φ140F	
	Through-Hole Diameter	mm inch		53 2.09"			53 2.09"	
	Bearing Inside Diameter	mm inch		80 3.15"			90 3.54"	
	Number of Turrets			2			2	
	Type of Turret (All-Holder Type)		10-Station	12-Station	10-Station	10-Station	12-Station	10-Station
Turret	Number of Attachable Tools		10+10	12+12	10+10	10+10	12+12	10+10
	Height of Square Tool Shank	mm inch	20 0.75"		25 1"			
	Diameter of Boring Bar Shank	mm inch	25 1"		32 1.25"			
	Number of Rotary Tools		- Alternate 5 pcs		-	-	Alternate 5 pc	
	Spindle Speed	min <sup>-1</sup>	- 2500		-	-	2500	
Rotary Tool	Maximum Tool Shank Diameter	mm inch	_	-	16 0.63"			16 0.63"
	Tool Spindle Taper Hole (Type, Nom, Cod	e)	_	-	AR25	-		AR25
	Tool Spindle Bearing Inside Diameter	mm inch	-	-	35 1.38"	-		35 1.38"
Feedrate	Rapid Traverse Rate	m/min ipm	X:24 / Z:24	-	/ Z:944.88"	X:24 / Z:24 X:944.88" / Z:944.88"		
reedrate	Jog Feedrate	mm/min ipm	X, Z	:0 ~ 1260 49	.61"	X, Z:0 ~ 1260 49.61"		
	Main Spindle Motor (15 min/coninuous) *6	kW HP	7.5/5.5 1	1/7.5 10/7.3	3 14.7/10	11/7.5 14.7/10		0
	Rotary Tool Spindle Motor	kW HP	_		5.5/3.7	_	_	5.5/3.7
Motor	(15 min/continuous)				7.3/4.9			7.3/4.9
WIOCOI	Feed Axis Motor	kW HP		Z:1.4 X:1.9		X:1.4 / Z:1.4 X:1.9 / Z:1.9		
	Hydraulic Pump Motor	kW HP		otors 2×2 M			lotors 2×2 M	
	Coolant Pump Motor	kW HP	0.25×2 M	lotors 0.3×2	Motors	0.25×2 M	lotors 0.3×2	Motors
Required	Electric Power	kVA		32 <b>37</b>			37	
Power	Air Pressure Source	MPa		0.4			0.4	
Tank	Hydraulic Unit Tank	L gal	20	) (×2) 5.28 (	×2)	20 (×2) 5.28 (×2)		<2)
Capacity	Lubricant Tank	L gal		6.5 1.72		6.5 1.72		
σαραστέχ	Coolant Tank	L gal		350 92.40		350 92.40		
	Machine Height	mm inch		2700 106.30	)"		2700 106.30	"
Machine Size	Floor to Spindle Center Height	mm inch		975 38.39	7	975 38.39"		
WIACITITIE SIZE		mm×mm inch×inch	2825×		2"×103.43"			2"×103.43"
	Machine Weight	kg lbs.	5200	11440	5400 11880	5200	11440	5400 11880

T			6" Chuck Type	e	8" Chuck Type		
[Loader S	Specifications (A or B Type)		TT-2100G	TT-2100CMG	TT-2100G	TT-2100CMG	
Taumat	Outside Diameter	mm inch	80 3.15" [160 6.3	3" *1]	160 6.3" [80 3.1	5" *2]	
Target Workpiece	Length	mm inch	80 3.15"		80 3.15"		
workpiece	Weight	kg lbs.	kg lbs. 0.7×2 1.5×2 [3×2 6.6×2 *1]		3×2 6.6×2 [0.7×2 1.5×2 *2]		
Travel	X-Axis (longitudinal)	mm inch (m/min ipm)	1540 60.63" (200 7874.02" [18	80 7086.61"*1])	1540 60.63" (180 7086.61" [20	00 7874.02"*2])	
(Running	Y-Axis (vertical)	mm inch (m/min ipm)	662 26.06" (150 590	05.51")	662 26.06" (150 59	05.51")	
Speed)	Z-Axis (cross)	mm inch (m/min ipm)	216 8.5" (50 1968	8.5")	216 8.5" (50 196	8.5")	
Hand	Туре		3-Jaws		3-Jaws		
nand	Stroke	mm inch	$\phi$ 28 1.1" [ $\phi$ 32 1	.25" *1]	$\phi$ 32 1.25" [ $\phi$ 28 1	.1" *2]	

#### [Work Feeder Specifications]

Number of Pallets		16	16
Loading Capacity (1 Pallet)	kg lbs.	40 88	40 88
Max. Height	mm inch	450 17.72"	450 17.72"

Red is Optional. [\*1] or [\*2] are options by a set.

#### ■ Machine Standard Accessories (with A or B Type Loader)

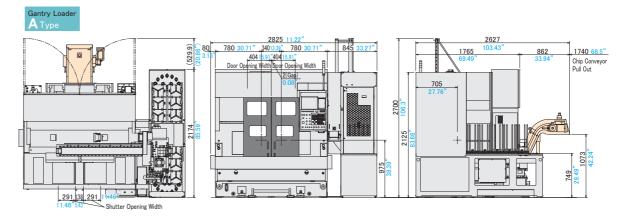
Items	Contents	6" Type	8" Type	
Called Observations of Ossilianda in	H01MA8 & HH9C125	L&R	×	•
Solid Chuck and Cylinder	H01MA6 & HH9C100	L&R	•	×
Chuck Open/Close M-Function	(Proximity)	L&R	•	•
Chuck Airblow	(Outside Spindle)	L&R	•	•
Signal Tower Light	(3-Color)	1 Pic	•	•
Chip Conveyor	(Caterpillar Type, Rear)	1 Set	•	•
Tool Holders	(Selectable for OD Turning & Facing, or Boring Bar/Drill)	L&R (Each 5)	•	•
Auto Power-Off System		1 Set	•	
Total Counter	(Display)		•	
Gantry Loader *3	(A or B Type)	1 Set	•	
Turnover Unit		1 Set	•	
NG Chute	(Quality)	1 Set	•	
Work Feeder	(16 Pallets/3 Guide Bar)	1 Set	•	•
Splashguard		1 Set	•	
Hydraulic Unit	(1.5kW)	L&R	•	
Coolant Unit	(250W)	L&R	•	•
Lighting Apparatus		1 Set	•	
Adjustment Tool		1 Set	•	
Instruction Manual		1 Set	•	•

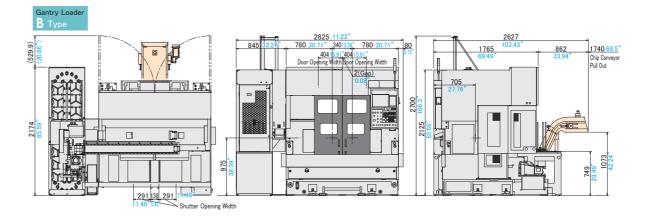
#### ■ Machine Optional Accessories

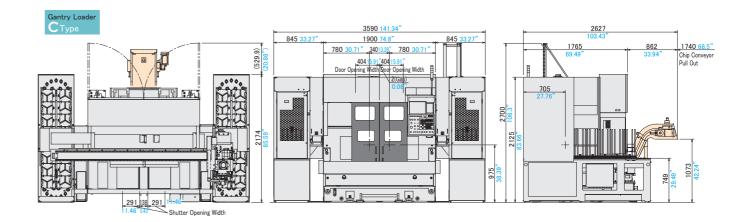
Rotary Tool Holder (for X-Axis) *4	Spindle Orientation *5
Rotary Tool Holder (for Z-Axis) *4	Coolant Unit (400W)
Collet (for Rotay Tool) *4	Spindle Above Coolan
Tool Holder	Hybrid Hydraulic Unit
Boring Bar / Drill Holder	Chip Bucket
Offset Boring Bar Holder	Tool Setter
U-Drill Holder	Spindle Motor
Offset U-Drill Holder	[6" Chuck Type]
Boring Bar Bush	7.5/5.5kW : 6000min
Drill and U-Drill Socket	11/7.5kW : 4500min
Special Chuck	11/7.5kW : 6000min <sup>-1</sup>
Foot Switch for Hydraulic Chuck	[8" Chuck Type]
· · · · · · · · · · · · · · · · · · ·	11/7.5kW : 4500min <sup>-1</sup>

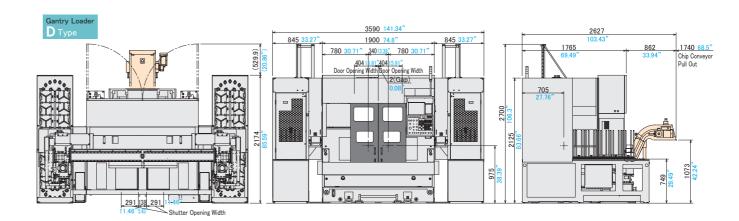
- \*3) Includes Safety Cover/Upper Auto Door/Door Interlock.
  \*4) Applied to TT-2100CMG
  \*5) Disk Brake Type (Max. 360 Point) with M-Function
  \*6) Please refer to "Electric-power-equipment Capacity" of 13 page.
- ※ For other optional accessories, please contact us.

#### Machine Dimensions Unit : mm inch









### **TT-2100**G

#### **NC Unit Specifications**

FANUC: Oi-TF



#### Software

\* The software specifications are subject to change for improvement without notice.

#### RAKU-RAKU Loader 4

#### [Standard Accessory]

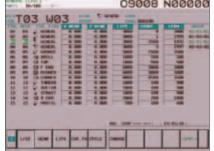
The loader operation settings can be changed simply by the operation from the dedicated screen without modifying the program.



▲ RAKU-RAKU Loader 4

#### **RAKU-RAKU Monitor 3**

[Standard Accessory] Easy and convenient multifunctional softwares which can perform tool life management, cutting load monitoring, group control, and also run information collection, Cp (process capability) calculation, and periodic offset addition.



#### **Measurement Monitor 3**

#### [Optional Accessory]

This function loads the measured data from a measuring unit and sets automatically the offset value. Also, various convenient functions such as graphical display, Cp (process capability) calculation, and data input/output are included.

#### **■** Electric-power-equipment Capacity

Spindle Motor	Gantry	6"Chuck Type	8" Chuck Type
Spiridle Motor	(Type)	TT-2100G, TT-2100CMG	
5.5/7.5kW	A, B, C	32.0kVA	32.0kVA
	D	33.0kVA	33.0kVA
7.5/11kW	A, B, C	37.0kVA	37.0kVA
	D	38.0kVA	38.0kVA

#### **■ Composition**

Specifications • Contents	TT-2100G	TT-2100CMG
(NC Unit)	11 21000	11 210001110
Screen (10.4"Color LCD/MDI (Horizontal, Small Type)	•	•
[Software]		
RAKU-RAKU Loader 4	•	•
RAKU-RAKU Monitor 3	•	•
Measurement Monitor 3 *1	0	0
[Safety Devices]		
Front Door Interlock	•	•
Front Door Locking Mechanism	0	0
Safety Relay	•	•
Control Panel Breaker with Tripper	•	•

pecifications • Contents  Controlled Axes   east Input Increment *2 lax. Programmable Dimension (±999999.999) is: Contouring Control corement System C *3 Inch/Metric Conversion interlock lachine Lock *4 mergency Stop tored Stroke Check 1 tored Stroke Check 2, 3 *5 tored Limit Check Before Move chuck and Tail Stock Barrier *6 lirror Image (Each Axis) chamfering ON/OFF inexpected Disturbance Torque Detection Function *7 losition Switch  Operation   Interpolation Prevention uffer Register rey Run ingle Block lanual Handle Feed, 1 Unit Interpolation Functions   Interpolation Functions   Interpolation Functions   Interpolation Functions   Interpolation Functions   Interpolation Search   Interpolation Prevention   Interpolation Prevention   Interpolation Functions   I	)
lax. Programmable Dimension (±999999.999)  Is Contouring Control Is Control I	
Is Contouring Control Increment System C *3 Inch/Metric Conversion Interlock Identine Lock *4 Identine Lock *4 Imergency Stop Itored Stroke Check 1 Itored Stroke Check 2, 3 *5 Itored Limit Check Before Move Induck and Tail Stock Barrier *6 Incror Image (Each Axis) Inhamfering ON/OFF Inexpected Disturbance Torque Detection Function *7 Indication Switch Identity Interpolation Interpolation Prevention Interpolation Prevention Interpolation Function Interpolation Functions Interpolation Function Interpolation Function Interpolation Functions Interpolation	)
Accidence of the content of the cont	
Inch/Metric Conversion Interlock Idachine Lock *4 Imergency Stop Itored Stroke Check 1 Itored Stroke Check 2, 3 *5 Itored Limit Check Before Move Inhuck and Tail Stock Barrier *6 Ilirror Image (Each Axis) Inhamfering ON/OFF Inexpected Disturbance Torque Detection Function *7 Iosition Switch IDI Operation INC Operation (Memory) IDI Operation *8 *9 INC Operation with Memory Card *9 *10 Irogram Number Search Inequence Number Search Inequence Number Comparison and Stop Irogram Restart Inequence Number Comparison and Stop Irogram Restart Inequence Number Search Inequence Number Search Inequence Number Search Inequence Number Comparison and Stop Irogram Restart Inequence Number Search Inequence Numb	М
Interlock Idachine Lock *4 Imergency Stop Itored Stroke Check 1 Itored Stroke Check 2, 3 *5 Itored Limit Check Before Move Inhuck and Tail Stock Barrier *6 Interor Image (Each Axis) Inhamfering ON/OFF Inexpected Disturbance Torque Detection Function *7 Iosition Switch Interpolation Interpolation (Memory) IDI Operation INC Operation *8 *9 INC Operation with Memory Card *9 *10 Irogram Number Search Interpolation Prevention Interpolation Prevention Interpolation Prevention Interpolation Setting without DOG Interpolation Functions I	
lachine Lock *4  mergency Stop  tored Stroke Check 1  tored Stroke Check 2, 3 *5  tored Limit Check Before Move  thuck and Tail Stock Barrier *6  lirror Image (Each Axis)  thamfering ON/OFF  mexpected Disturbance Torque Detection Function *7  osition Switch  Operation  NC Operation  NC Operation *8 *9  NC Operation with Memory Card *9 *10  rogram Number Search equence Number Search equence Number Comparison and Stop  rogram Restart  ool Retract and Recover  Arong Operation Prevention  uffer Register  rry Run ingle Block  lanual Continuous Feed (JOG)  lanual Reference Position Return leference Position Setting without DOG  lanual Handle Feed, 1 Unit  Interpolation Functions  ositioning (G00)	)
mergency Stop  tored Stroke Check 1  tored Stroke Check 2, 3 *5  tored Limit Check Before Move  thuck and Tail Stock Barrier *6  lirror Image (Each Axis)  thamfering ON/OFF  mexpected Disturbance Torque Detection Function *7  osition Switch  Operation  utomatic Operation (Memory)  IDI Operation  NC Operation *8 *9  NC Operation with Memory Card *9 *10  rogram Number Search equence Number Search equence Number Comparison and Stop  rogram Restart  ool Retract and Recover  Arong Operation Prevention  uffer Register  rry Run ingle Block  lanual Continuous Feed (JOG)  lanual Reference Position Return leference Position Setting without DOG  lanual Handle Feed, 1 Unit  Interpolation Functions  ositioning (G00)	)
tored Stroke Check 1  tored Stroke Check 2, 3 *5  tored Limit Check Before Move  thuck and Tail Stock Barrier *6  firror Image (Each Axis)  thamfering ON/OFF  Inexpected Disturbance Torque Detection Function *7  osition Switch  Operation  Into Operation  Into Operation  Into Operation *8 *9  Into Operation *8 *9  Into Operation with Memory Card *9 *10  Into Operation With Memory Card *9 *10  Into Operation With Operation operation on the operation of the operat	)
tored Stroke Check 2, 3 *5  tored Limit Check Before Move  thuck and Tail Stock Barrier *6  lirror Image (Each Axis)  thamfering ON/OFF Inexpected Disturbance Torque Detection Function *7  osition Switch  Operation  Introduction Operation (Memory)  IDI Operation  NC Operation *8 *9  NC Operation with Memory Card *9 *10  rogram Number Search equence Number Search equence Number Comparison and Stop  rogram Restart  ool Retract and Recover  Irong Operation Prevention  uffer Register  rry Run ingle Block  lanual Continuous Feed (JOG)  lanual Reference Position Return leference Position Setting without DOG  lanual Handle Feed, 1 Unit  Interpolation Functions  ositioning (G00)	)
tored Limit Check Before Move Chuck and Tail Stock Barrier *6  Ilirror Image (Each Axis) Chamfering ON/OFF Inexpected Disturbance Torque Detection Function *7 Iosition Switch  Operation  Utomatic Operation (Memory) IDI Operation NC Operation *8 *9 NC Operation with Memory Card *9 *10 Irogram Number Search Inequence Number Search Inequence Number Comparison and Stop Irogram Restart Inol Retract and Recover Irong Operation Prevention Interpolation Setting without DOG Inanual Reference Position Return Interpolation Functions Interp	)
thuck and Tail Stock Barrier *6  Ilirror Image (Each Axis)  thamfering ON/OFF Inexpected Disturbance Torque Detection Function *7  osition Switch  Operation  utomatic Operation (Memory)  IDI Operation  NC Operation *8 *9  NC Operation with Memory Card *9 *10  rogram Number Search equence Number Search equence Number Comparison and Stop  rogram Restart  ool Retract and Recover  Irong Operation Prevention  uffer Register  rry Run ingle Block Ianual Continuous Feed (JOG) Ianual Reference Position Return deference Position Setting without DOG Ianual Handle Feed, 1 Unit Interpolation Functions ositioning (G00)	
Inror Image (Each Axis) Inhamfering ON/OFF Inexpected Disturbance Torque Detection Function *7 Inexpected Disturbance Torque Detection Function *7 Inexpected Disturbance Torque Detection Function *7 Incomposition Switch  Operation Incomposition (Memory) IDI Operation INC Operation *8 *9 INC Operation with Memory Card *9 *10 Incomposition Number Search Incomposition Prevention Interpolation Prevention Interpolation Setting without DOG Incomposition Incomposition Incomposit	
chamfering ON/OFF Inexpected Disturbance Torque Detection Function *7 Inexpected Disturbance Torque Detection *7 Inexpected Disturbance Torque Disturbance Torque Disturbance Torque Disturbance Torque Disturbance Torque Disturbance Torque	
Inexpected Disturbance Torque Detection Function *7  osition Switch  Operation  utomatic Operation (Memory)  IDI Operation  NC Operation *8 *9  NC Operation with Memory Card *9 *10  rogram Number Search equence Number Search equence Number Comparison and Stop  rogram Restart  ool Retract and Recover  Arong Operation Prevention uffer Register  rry Run ingle Block Ianual Continuous Feed (JOG) Ianual Reference Position Return deference Position Setting without DOG Ianual Handle Feed, 1 Unit Interpolation Functions ositioning (G00)	
osition Switch  Operation J  utomatic Operation (Memory)  IDI Operation  NC Operation *8 *9  NC Operation with Memory Card *9 *10  rogram Number Search equence Number Search equence Number Comparison and Stop  rogram Restart fool Retract and Recover  Arong Operation Prevention  uffer Register  rry Run ingle Block Ianual Continuous Feed (JOG) Ianual Reference Position Return leference Position Setting without DOG Ianual Handle Feed, 1 Unit Interpolation Functions Iositioning (G00)	
Operation ]  uutomatic Operation (Memory)  IDI Operation  NC Operation *8 *9  NC Operation with Memory Card *9 *10  rogram Number Search equence Number Search equence Number Comparison and Stop  rogram Restart  cool Retract and Recover  frong Operation Prevention fuffer Register fry Run ingle Block Ianual Continuous Feed (JOG) Ianual Reference Position Return deference Position Setting without DOG Ianual Handle Feed, 1 Unit Interpolation Functions ositioning (G00)	
utomatic Operation (Memory)  IDI Operation  NC Operation *8 *9  NC Operation with Memory Card *9 *10  rogram Number Search equence Number Search equence Number Comparison and Stop  rogram Restart fool Retract and Recover  Arong Operation Prevention uffer Register rry Run ingle Block lanual Continuous Feed (JOG) lanual Reference Position Return leference Position Setting without DOG lanual Handle Feed, 1 Unit Interpolation Functions occupance of the search occupance occu	)
IDI Operation  NC Operation *8 *9  NC Operation with Memory Card *9 *10  rogram Number Search equence Number Search equence Number Comparison and Stop  rogram Restart fool Retract and Recover frong Operation Prevention fuffer Register fry Run ingle Block lanual Continuous Feed (JOG) lanual Reference Position Return leference Position Setting without DOG lanual Handle Feed, 1 Unit Interpolation Functions lositioning (G00)	
NC Operation *8 *9  NC Operation with Memory Card *9 *10  rogram Number Search equence Number Search equence Number Comparison and Stop  rogram Restart  ool Retract and Recover  /rong Operation Prevention uffer Register rry Run ingle Block lanual Continuous Feed (JOG) lanual Reference Position Return deference Position Setting without DOG lanual Handle Feed, 1 Unit Interpolation Functions occupance of the search of the search of the search occupance occupa	)
NC Operation with Memory Card *9 *10  rogram Number Search equence Number Search equence Number Comparison and Stop rogram Restart  ool Retract and Recover  frong Operation Prevention fuffer Register fry Run ingle Block lanual Continuous Feed (JOG) lanual Reference Position Return deference Position Setting without DOG lanual Handle Feed, 1 Unit Interpolation Functions occupance of the search of the searc	)
rogram Number Search equence Number Search equence Number Comparison and Stop rogram Restart cool Retract and Recover frong Operation Prevention fuffer Register fry Run ingle Block lanual Continuous Feed (JOG) lanual Reference Position Return deference Position Setting without DOG lanual Handle Feed, 1 Unit Interpolation Functions occupance of the provided search o	)
equence Number Search equence Number Comparison and Stop rogram Restart ool Retract and Recover /rong Operation Prevention uffer Register rry Run ingle Block lanual Continuous Feed (JOG) lanual Reference Position Return deference Position Setting without DOG lanual Handle Feed, 1 Unit Interpolation Functions ook ook ook ook ook ook ook ook ook oo	)
equence Number Comparison and Stop  rogram Restart  ool Retract and Recover  /rong Operation Prevention  uffer Register  ry Run  ingle Block  lanual Continuous Feed (JOG)  lanual Reference Position Return  deference Position Setting without DOG  lanual Handle Feed, 1 Unit  Interpolation Functions  oositioning (G00)	)
rogram Restart  ool Retract and Recover  /rong Operation Prevention  uffer Register  ry Run  ingle Block  lanual Continuous Feed (JOG)  lanual Reference Position Return  deference Position Setting without DOG  lanual Handle Feed, 1 Unit  Interpolation Functions  oositioning (G00)	)
ool Retract and Recover  Irong Operation Prevention  uffer Register  Iry Run  ingle Block  Ianual Continuous Feed (JOG)  Ianual Reference Position Return  deference Position Setting without DOG  Ianual Handle Feed, 1 Unit  Interpolation Functions  ositioning (G00)	)
Irong Operation Prevention  uffer Register  Iry Run  ingle Block Idenual Continuous Feed (JOG) Idenual Reference Position Return Interpolation Functions Interpolation Functions Institution Interpolation Interpolation Functions Institution Interpolation Interpolation Interpolation Interpolation Functions Interpolation Function	)
uffer Register  ry Run ingle Block Ianual Continuous Feed (JOG) Ianual Reference Position Return deference Position Setting without DOG Ianual Handle Feed, 1 Unit Interpolation Functions ositioning (G00)	
rry Run ingle Block Ianual Continuous Feed (JOG) Ianual Reference Position Return Reference Position Setting without DOG Ianual Handle Feed, 1 Unit Interpolation Functions ositioning (G00)	
ingle Block Idanual Continuous Feed (JOG) Idanual Reference Position Return Ideference Position Setting without DOG Idanual Handle Feed, 1 Unit Interpolation Functions Ideference Position Setting without DOG Idanual Handle Feed, 1 Unit Interpolation Functions Ideference Position Functions Ideference Position Return Ideference Position Setting Without DOG Ideference Position Setting Without DOG Ideference Position Return Ideference Position Return Ideference Position Setting Without DOG Ideference Position Setting Without DOG Ideference Position Setting Without DOG Ideference Position Functions Ideference Position Function Fun	)
lanual Continuous Feed (JOG)  lanual Reference Position Return  leference Position Setting without DOG  lanual Handle Feed, 1 Unit  linterpolation Functions  ositioning (G00)	)
lanual Reference Position Return leference Position Setting without DOG lanual Handle Feed, 1 Unit Interpolation Functions ositioning (G00)	)
leference Position Setting without DOG lanual Handle Feed, 1 Unit Interpolation Functions ositioning (G00)	)
lanual Handle Feed, 1 Unit Interpolation Functions ositioning (G00)	)
Interpolation Functions I ositioning (G00)	)
ositioning (G00)	)
xact Stop Mode (G61)	)
	)
apping Mode (G63)	)
autting Mode (G64)	)
xact Stop (G09)	
inear Interpolation (G01)	)
ircular I nterpolation (G02/03)	)
well (G04)	)
olar Coordinate Interpolation CN	М
ylindrical Interpolation CN	М
hread Cutting, Synchronous Cutting	)
Iulti Threading	)
hread Cutting Retract	
ontinuous Threading	_
ariable Lead Thread Cutting	
kip (G31) ©	)
deference Position Return (G28)	)

Specifications • Contents	TT 0100C
(Feed Functions)	TT-2100G
Rapid Traverse Override (F0,25%,50%,100%)	•
Feed Per Minute	•
Feed Per Revolution	•
Constant Tangential Speed Control	•
Cutting Feedrate Clamp	•
Automatic Acceleration/Deceleration	•
Rapid Traverse Bell-Shaped Acceleration/Deceleration Linear Acceleration/Deceleration After Cutting Feed Interpolation	
Feedrate Override (15 Steps)	
Jog Override (15 Steps)	•
Override Cancel	•
Manual per Revolution Feed	<b>A</b>
[Program Input]	
Program Code (EIA/ISO Auto Recognition)	•
Label Skip Parity Check	
Control In/Out	
Optional Block Skip, 1 Piece	•
Optional Block Skip (2 to 9 Pieces)	0
Program Number O4 Digits	•
Program File Name 32 Characters	•
Sequence Number N8 Digits	•
Absolute/Incremental Programming	•
Decimal Point Programming/Pocket Calculator Type Decimal Point Programming	•
Diameter/Radius Programming (X-Axis)	•
Plane Selection G17,G18,G19	CM
Coordinate System Setting (G50)	•
Automatic Coordinate System Setting *11	•
Workpiece Coordinate System(G54-G59) *12	<u> </u>
Direct Drawing Dmension Programming *13	
G-Code System A	•
G-Code System B/C Chamfering/Corner R *14	•
Programmable Data Input (G10)	•
Sub Program Call (10 Levels)	•
Custom Macro	•
Additional Custom Macro Common Variables	•
Canned Cycle	•
Multiple Repetitive Cycles	•
Multiple Repetitive Cycles II Canned Cycle for Drilling	
Circular Dnterpolation by R Programming	
Coordinate System Shift	•
Direct Input of Coordinate System Shift	•
[Auxiliary / Spindle Speed Function]	
M Function (M3 Digits)	•
2nd Auxiliary Functionn (B Function)	•
Multiple Command of Auxiliary Function (3 Pieces)	•
Spindle Speed Function (S-Function)	•
	•
Constant Surface Speed Control	•
Constant Surface Speed Control Spindle Override	
Constant Surface Speed Control	•
Constant Surface Speed Control Spindle Override Spindle Orientation	
Constant Surface Speed Control Spindle Override Spindle Orientation Rigid Tap (Spindle Center)	•
Constant Surface Speed Control Spindle Override Spindle Orientation Rigid Tap (Spindle Center) Rigid Tap (Rotary Tool)  [Tool Functions / Tool Compensation] Tool Function (T2+2 Digits)	•
Constant Surface Speed Control Spindle Override Spindle Orientation Rigid Tap (Spindle Center) Rigid Tap (Rotary Tool)  [Tool Functions / Tool Compensation] Tool Function (T2+2 Digits) Tool Offset Pairs 128-pairs (L/R Each 64-pairs)	CM
Constant Surface Speed Control Spindle Override Spindle Orientation Rigid Tap (Spindle Center) Rigid Tap (Rotary Tool)  [Tool Functions / Tool Compensation] Tool Function (T2+2 Digits) Tool Offset Pairs 128-pairs (L/R Each 64-pairs) Tool Offset Pairs 200-pairs (L/R Each 99-pairs)	CM
Constant Surface Speed Control Spindle Override Spindle Orientation Rigid Tap (Spindle Center) Rigid Tap (Rotary Tool)  [Tool Functions / Tool Compensation] Tool Function (T2+2 Digits) Tool Offset Pairs 128-pairs (L/R Each 64-pairs) Tool Offset Pairs 200-pairs (L/R Each 99-pairs) Tool Offset	CM
Constant Surface Speed Control Spindle Override Spindle Orientation Rigid Tap (Spindle Center) Rigid Tap (Rotary Tool)  [Tool Functions / Tool Compensation] Tool Function (T2+2 Digits) Tool Offset Pairs 128-pairs (L/R Each 64-pairs) Tool Offset Pairs 200-pairs (L/R Each 99-pairs) Tool Offset Tool Radius • Tool Nose Radius Compensation	CM
Constant Surface Speed Control Spindle Override Spindle Orientation Rigid Tap (Spindle Center) Rigid Tap (Rotary Tool)  [Tool Functions / Tool Compensation] Tool Function (T2+2 Digits) Tool Offset Pairs 128-pairs (L/R Each 64-pairs) Tool Offset Pairs 200-pairs (L/R Each 99-pairs) Tool Offset Tool Radius • Tool Nose Radius Compensation Tool Geometry/Wear Compensation	CM
Constant Surface Speed Control Spindle Override Spindle Orientation Rigid Tap (Spindle Center) Rigid Tap (Rotary Tool)  [Tool Functions / Tool Compensation] Tool Function (T2+2 Digits) Tool Offset Pairs 128-pairs (L/R Each 64-pairs) Tool Offset Pairs 200-pairs (L/R Each 99-pairs) Tool Offset Tool Radius • Tool Nose Radius Compensation	© CM
Constant Surface Speed Control Spindle Override Spindle Orientation Rigid Tap (Spindle Center) Rigid Tap (Rotary Tool)  [Tool Functions / Tool Compensation] Tool Function (T2+2 Digits) Tool Offset Pairs 128-pairs (L/R Each 64-pairs) Tool Offset Pairs 200-pairs (L/R Each 99-pairs) Tool Offset Tool Radius • Tool Nose Radius Compensation Tool Geometry/Wear Compensation Tool Offset Value Counter Input	CM  O  O
Constant Surface Speed Control Spindle Override Spindle Orientation Rigid Tap (Spindle Center) Rigid Tap (Rotary Tool)  [Tool Functions / Tool Compensation] Tool Function (T2+2 Digits) Tool Offset Pairs 128-pairs (L/R Each 64-pairs) Tool Offset Pairs 200-pairs (L/R Each 99-pairs) Tool Offset Tool Radius • Tool Nose Radius Compensation Tool Geometry/Wear Compensation Tool Offset Value Counter Input Direct Input of Tool Offset Value Measured	© CM
Constant Surface Speed Control Spindle Override Spindle Orientation Rigid Tap (Spindle Center) Rigid Tap (Rotary Tool)  [Tool Functions / Tool Compensation] Tool Function (T2+2 Digits) Tool Offset Pairs 128-pairs (L/R Each 64-pairs) Tool Offset Pairs 200-pairs (L/R Each 99-pairs) Tool Offset Tool Radius • Tool Nose Radius Compensation Tool Geometry/Wear Compensation Tool Offset Value Counter Input Direct Input of Tool Offset Value Measured Direct Input of Tool Offset Value Measured B *15 Tool Life Management *16 [Accuracy Offset Functions]	© CM
Constant Surface Speed Control Spindle Override Spindle Orientation Rigid Tap (Spindle Center) Rigid Tap (Rotary Tool)  [Tool Functions / Tool Compensation] Tool Function (T2+2 Digits) Tool Offset Pairs 128-pairs (L/R Each 64-pairs) Tool Offset Pairs 200-pairs (L/R Each 99-pairs) Tool Offset Tool Radius • Tool Nose Radius Compensation Tool Geometry/Wear Compensation Tool Offset Value Counter Input Direct Input of Tool Offset Value Measured Direct Input of Tool Offset Value Measured B *15 Tool Life Management *16 [Accuracy Offset Functions] Backlash Compensation	© CM
Constant Surface Speed Control Spindle Override Spindle Orientation Rigid Tap (Spindle Center) Rigid Tap (Rotary Tool)  [Tool Functions / Tool Compensation] Tool Function (T2+2 Digits) Tool Offset Pairs 128-pairs (L/R Each 64-pairs) Tool Offset Pairs 200-pairs (L/R Each 99-pairs) Tool Offset Tool Radius • Tool Nose Radius Compensation Tool Geometry/Wear Compensation Tool Offset Value Counter Input Direct Input of Tool Offset Value Measured Direct Input of Tool Offset Value Measured B *15 Tool Life Management *16 [Accuracy Offset Functions] Backlash Compensation for Each Rapid Traverse and Cutting Feed	© CM
Constant Surface Speed Control Spindle Override Spindle Orientation Rigid Tap (Spindle Center) Rigid Tap (Rotary Tool)  [Tool Functions / Tool Compensation] Tool Function (T2+2 Digits) Tool Offset Pairs 128-pairs (L/R Each 64-pairs) Tool Offset Pairs 200-pairs (L/R Each 99-pairs) Tool Offset Tool Radius • Tool Nose Radius Compensation Tool Geometry/Wear Compensation Tool Offset Value Counter Input Direct Input of Tool Offset Value Measured Direct Input of Tool Offset Value Measured B *15 Tool Life Management *16 [Accuracy Offset Functions] Backlash Compensation	© CM

The contents of the catalog are subject to change for improvement without notice. Please make confirmation from our sales representatives when entering into the contract.

Specifications • Contents	TT-21000
Number of Registerable Programs, 800 Programs *18	•
Number of Registerable Programs, 1000 Programs *18	0
Part Program Editing	•
Extended Part Program Editing	•
Program Protect	•
Playback	0
Machining Time Stamp	0
Background Editing	•
Multi Part Program Editting	•
[Setting / Display]	
Status Display	•
Clock Function	•
Current Position Display	•
Program Comment Display (31 Characters)	•
Parameter Setting and Display	•
Alarm Display	•
Alarm Log Display	•
Operation History Display	<b>A</b>
Run Hours and Parts Count Display	•
Actual Cutting Feedrate Display	•
Display of Spindle Speed and T Code at All Screens	•
Servo Setting Screen	•
Maintenance Information Screen	•
Data Protection Key, 1 Kind	•
Erase CRT Screen Display	•
Parameter Set Supporting Screen	•
Help Function	•
Self-diagnosis Function	•
Periodic Maintenance Screen	•
[Multi-language Display]	
English *19	•
Other Language *19 *20	<b>A</b>
Dynamic Display Language Switching	<b>A</b>
[Data I/O]	
RS-232C Interface for 1ch	0
Data Server Function *21	0
External Workpiece Number Search	0
Memory Card I/O	•
USB Memory I/O	•
One Touch Macro Call	0
Automatic Data Backup	•
[Communication Function]	
Embedded Ethernet	•
Fast Ethernet	0
[Other]	

●:Standard O:Optional ©:Special -:None

▲ :Parameter setting is required.

Touch Panel

(Note: Normally, the parameters need not to be changed. If the parameters are to be set or changed, understand completely the functions of such parameters. Wrong setting could cause the machine to be moved unexpectedly, resulting in machine or workpiece damage or personal injury.)

CM: C-Axis/Milling Standard Specification.

\*1) I/O addition and the PC change are necessary.

\*2) 0.001mm, 0.0001inch, 0.001deg

\*3) IS-C 0.0001mm, 0.0001deg, 0.00001inch.

\*4) Addition of switch is required.

\*5) Not coexistent with chuck tailstock barrier. \*6) Not coexistent with Stored Stroke Check 2, 3.

\*7) Required when RAKU-RAKU Monitor 3 is used.

\*8) RS-232C Interface is required.

\*9) DNC run mode transfer switch is required.

\*10) CF card and adaptor is required.

\*11) Not coexistent with Workpiece Coordinate System(G54-G59).

\*12) Not coexistent with Automatic Coordinate System Setting. \*13) Not coexistent with chamfering/corner R.

\*14) Not coexistent with direct drawing dmension programming.

\*15) Tool setter is required.

\*16) Cannot be used when RAKU-RAKU Monitor 3 is installed.

\*17) In the case of loader specification, about [ 262K-byte 655m ] is used for program store capacity by RAKU-RAKU loader 4 software.

\*18) In the case of loader specification, the 180 program number is used by RAKU-RAKU loader 4 software.

\*19) Cannot be simultaneously displayed with other languages.

\*20) Japanese, German, French, Spanish, Italian, Chinese (traditional), Chinese (simplified), Korean, Portuguese, Dutch, Danish, Swedish, Hungarian, Czech, Polish, Russian, Turkish, Romanian, Bulgarian, Slovak, Finnish

\*21) Optional board is required.

Reference Position return Check (G27)

2nd Reference Position Return (G30)

3rd, 4th Reference Position Return

# TT-2100G

## **TAKISAWA®**

#### TAKISAWA MACHINE TOOL CO., LTD.

983 Natsukawa, Kita-ku, Okayama 701-0164, JAPAN

Telephone : (81)86-293-1500 Fax : (81)86-293-5799

Website : http://www.takisawa.co.jp
E-mail : tkj-1@takisawa.co.jp (Americ

nail : tkj-1@takisawa.co.jp (America) tkj-2@takisawa.co.jp (Europe)

tkj-3@takisawa.co.jp (Asia)

Japanese laws prohibit this machine from being used to develop or manufacture "weapons of mass destruction" or "conventional arms", as well as from being used to recent expense and feet them.

used to process parts for them.

Export of the product may require the permission of governmental authorities of the country from where the product is exported.

Should you wish to resell, transfer or export the product, please notify Takisawa Machine Tool Co., Ltd. or our distributor in advance.

\*The appearance, specifications, and relevant software of the product are subject to change for improvement without notice.

\*Please make an inquiry to our sales representatives for details of the product.



ISO 9001 Certified

JQA-2010 (Head Office)



(Head Office)

#### Overseas Network

**THAILAND** Takisawa (Thailand) Co.,Ltd.

Telephone: (66)2-012-1530-2 Fax: (66)2-012-1533

INDONESIA PT. Takisawa Indonesia

Telephone: (62)21-45852466 Fax: (62)21-45852467

INDIA SAP Takisawa Machine Tools Private Ltd.

 $\label{eq:final_relation} \textbf{Telephone}: (91)80\text{--}26662386 \quad \ \ \textbf{Fax}: (91)80\text{--}26662392$ 

CHINA Takisawa (Shanghai) Co., Ltd.

Telephone: (86)21-6235-0938 Fax: (86)21-6235-0905

USA Takisawa, Inc.

 $\label{eq:fax} \textbf{Telephone}: \textbf{(1)} \textbf{847-419-0046} \hspace{0.5cm} \textbf{Fax}: \textbf{(1)} \textbf{847-419-0043}$ 

**GERMANY** Takisawa Machine Tool Germany Representative Office

Telephone: (49)2056-2598-15 Fax: (49)2056-5994-79