

INFS7901

Database Principles

Binary Search Trees

Hassan Khosravi & Ash Rahimi

Notes

- Notebooks so far:
 - Asymptotic analysis
 - Sorting
 - Trees
- Project:
 - Read the project description and deadline for final submissions.
- RiPPLE:
 - Third round deadline was today, Check fourth round due
- Final exam (read the ECP)
 - Only two hours, Blackboard test, using ProctorU.

Learning Outcomes

Description	Tag
Describe the different operations that are supported by the dictionary ADT.	Dict-ADT
Demonstrate how arrays can be used for implementation of a dictionary ADT.	Dict-Array
Demonstrate how linked lists can be used for implementation of a dictionary ADT.	Dict-Linkedlist
Describe the properties of binary trees.	Dict-Trees
Describe the properties of Binary Search Trees (BSTs).	
Represent BSTs using linked data structures.	
Insert elements into a BST.	
Delete elements from a BST.	
search for an element in a BST.	
Determine if a given tree is an instance of a BST.	
Compare and contrast algorithms for storing and subsequently retrieving values from a dictionary ADT.	
Reflect on how BSTs and their extensions can be used in DBMS.	

Dictionary ADT

Tree Terminology

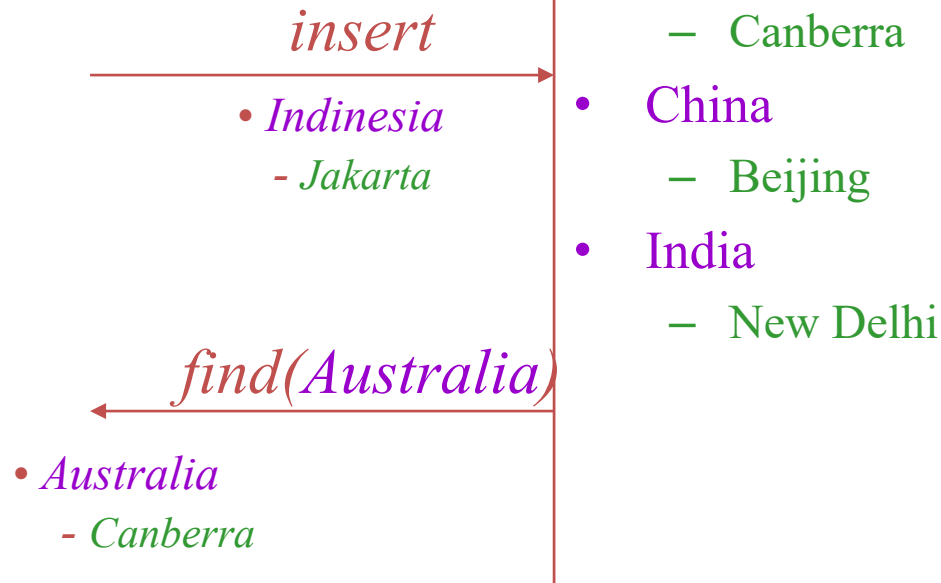
Binary Search Trees (BSTs)

Insertion and Deletion in BSTs

Dictionary Abstract Data type (ADT)

- Dictionary operations

- create
- destroy
- insert
- find
- Delete



- Stores *values* associated with user-specified *keys*
 - *values* may be any (homogenous) type
 - *keys* may be any (homogenous) comparable type

Search/Set ADT

- Dictionary operations

- create
- destroy
- insert
- find
- Delete

insert

• *Japan*

find(Malaysia)

NOT FOUND

- Australia
- China
- India
- Indonesia

- Stores **keys**

- keys may be any (homogenous) comparable
- quickly tests for membership

Naïve Implementations

- Unsorted Array

2	4	11	98	37	44	3			
---	---	----	----	----	----	---	--	--	--

Operation	Implementation	Running Time
Insert	Add after the current last value, if there is space available.	$O(1)$
Find	Scan the entire array	$O(n)$
Delete (index known)	Delete item, fill empty space with the last element	$O(1)$
Delete (value known)	Scan the entire array to find the item then delete	$O(n)$

Naïve Implementations

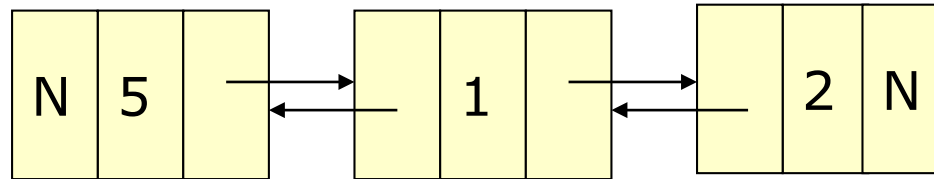
- Sorted Array

2	3	4	11	37	44	98			
---	---	---	----	----	----	----	--	--	--

Operation	Implementation	Running Time
Insert	Shift to make room for the insertion	$O(n)$
Find	Use binary search	$O(\log n)$
Delete (index known)	Shift to get rid of empty space	$O(n)$
Delete (value known)	Use binary search + shift	$O(n)$

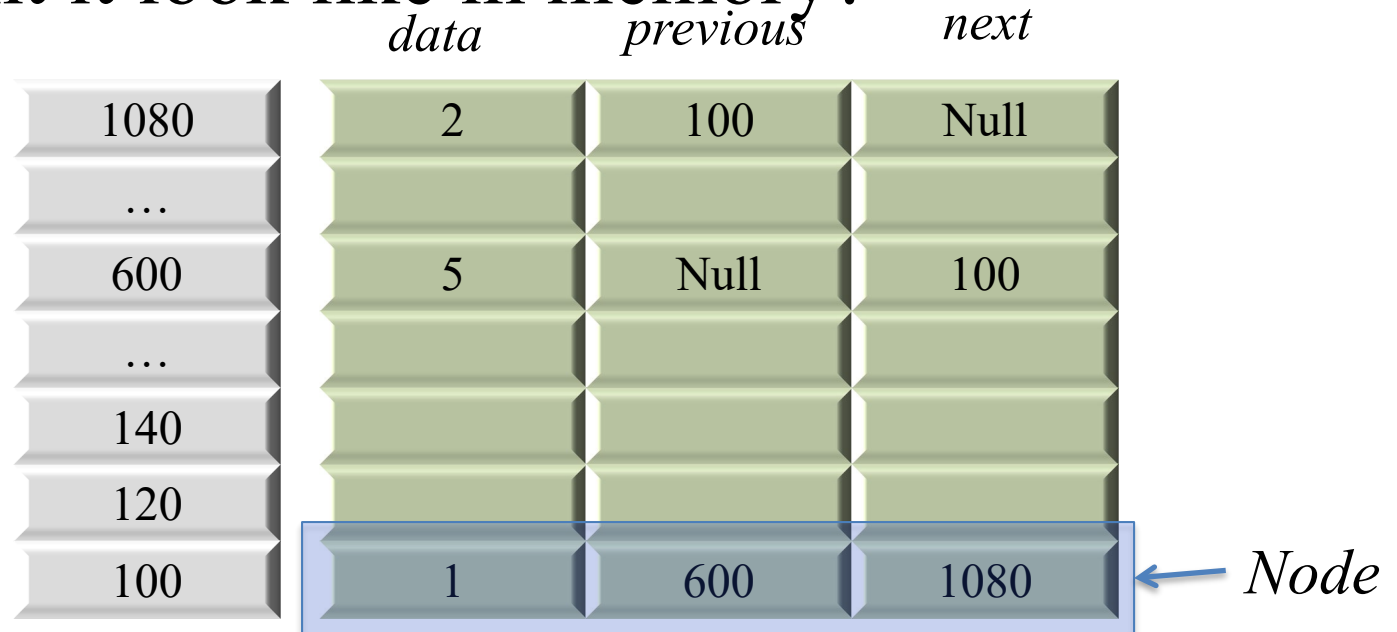
Linked Lists

- Consider the following abstraction, picturing a short linked list:

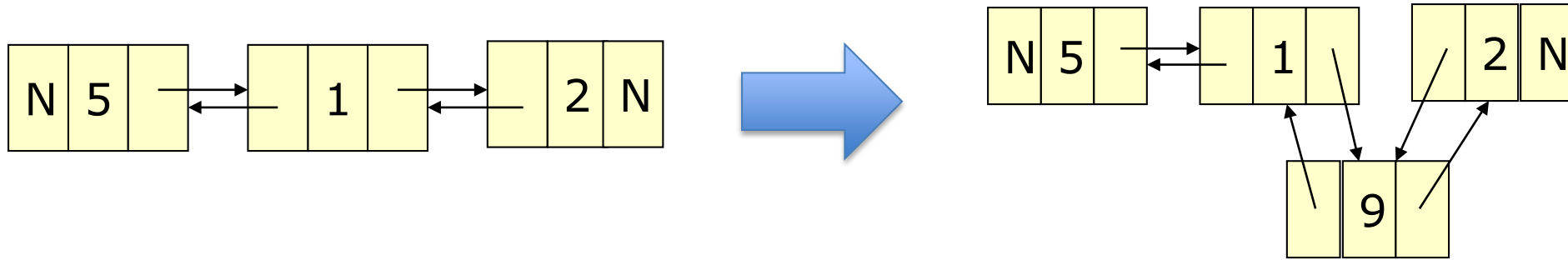


N represents NULL

- What might it look like in memory?

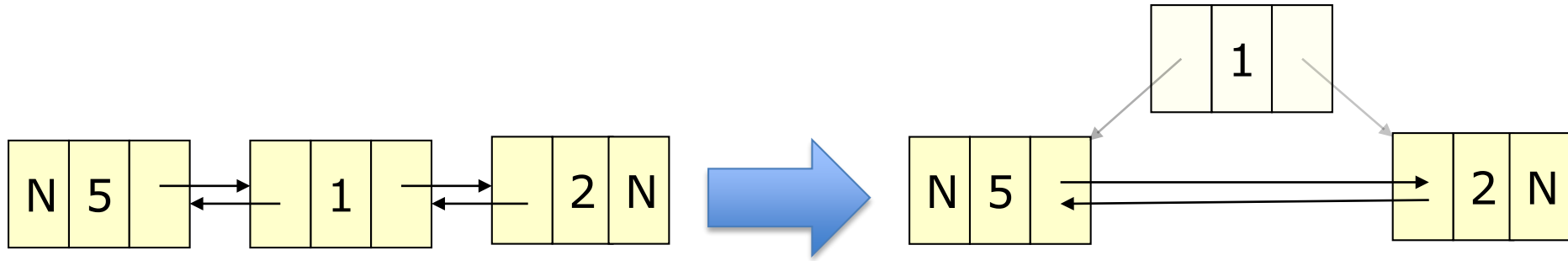


Inserting an Element to a Linked List



	<i>data</i>	<i>previous</i>	<i>next</i>
1080	2	140	Null
...			
600	5	Null	100
...			
140	9	100	1080
120			
100	1	600	140

Removing an Element from a Linked List

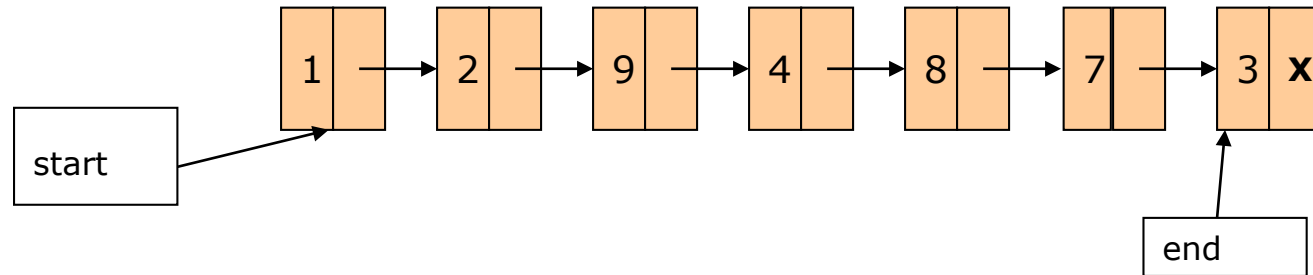


	<i>data</i>	<i>previous</i>	<i>next</i>	
1080	2	600	Null	
...				
600	5	Null	1080	
...				
140				
120				
100	1	600	1080	← delete

<https://visualgo.net/en/list>

Naïve Implementations

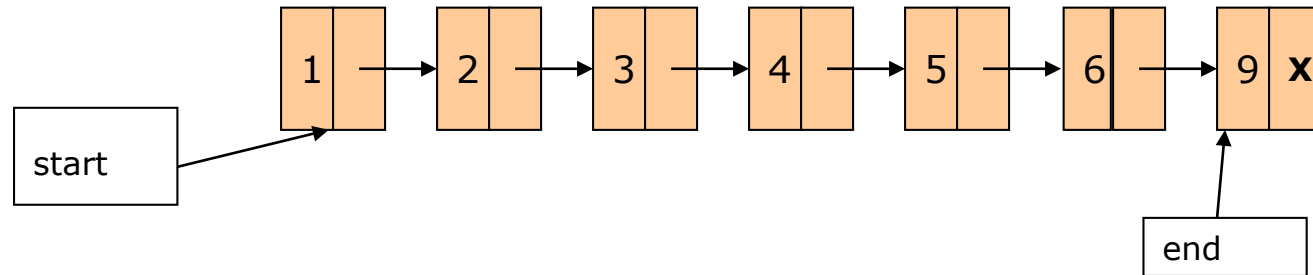
- Unsorted linked list



Operation	Implementation	Running Time
Insert	Add after end	$O(1)$
Find	Scan list	$O(n)$
Delete (Address known)	Remove and rechain	$O(1)$
Delete (value known)	Scan list + remove and rechain	$O(n)$

Naïve Implementations

- Sorted linked list



Operation	Implementation	Running Time
Insert	Scan list to find where to insert	$O(n)$
Find	Scan list	$O(n)$
Delete (Address known)	Remove and rechain	$O(1)$
Delete (value known)	Scan list + remove and rechain	$O(n)$

Naïve Implementations

	<i>insert</i>	<i>find</i>	<i>delete</i> <i>By value</i>	<i>delete</i> <i>By address</i>
• Linked list				
– Unsorted	$O(1)$	$O(n)$	$O(n)$	$O(1)$
– Sorted	$O(n)$	$O(n)$	$O(n)$	$O(1)$
• Array				
– Unsorted	$O(1)$	$O(n)$	$O(n)$	$O(1)$
– Sorted	$O(n)$	$O(\lg n)$	$O(n)$	$O(n)$

Can we do better?

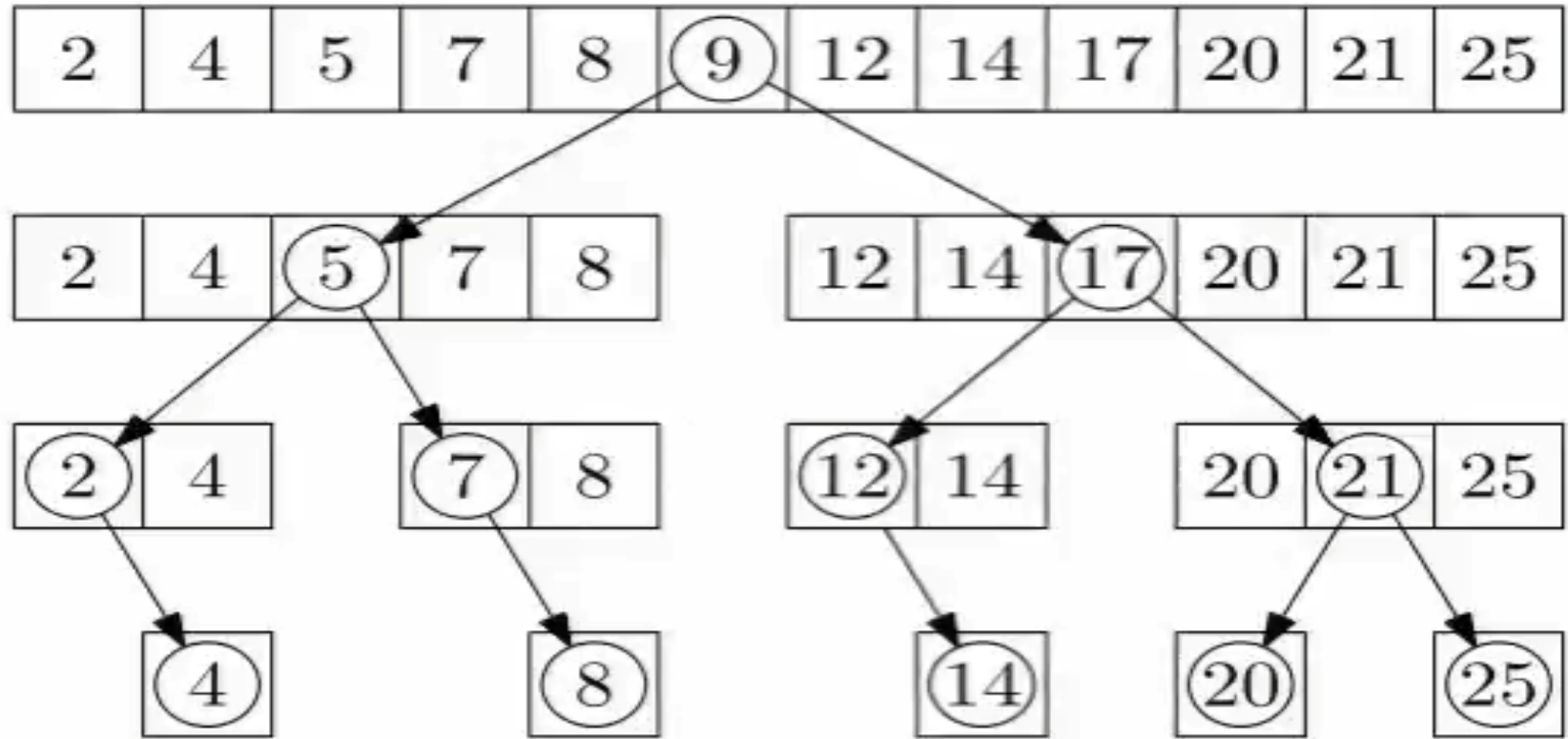
$O(\lg n)$

$O(\lg n)$

$O(\lg n)$

$O(\lg n)$

From Binary Search to Binary Search Trees



General idea (informally): You are allowed to shove new nodes into your list without having to shift things over.

Dictionary ADT

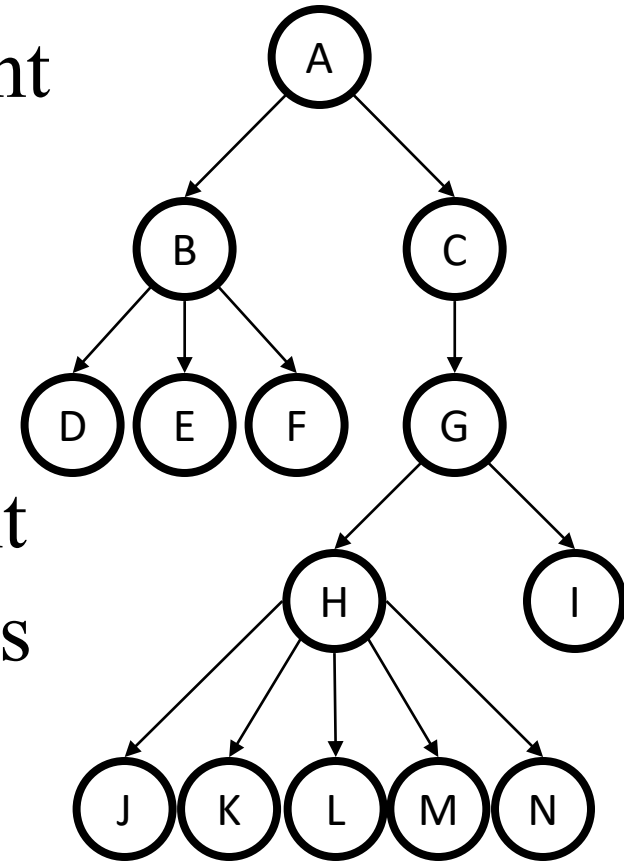
Tree Terminology

Binary Search Trees (BSTs)

Insertion and Deletion in BSTs

Tree Terminology

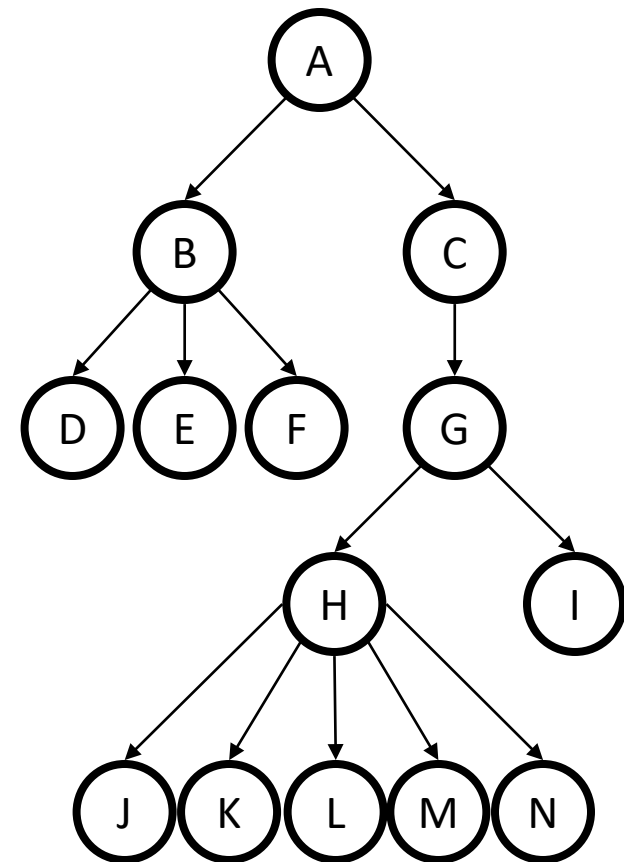
- *root*: the single node with no parent
- *leaf*: a node with no children
- *child*: a node pointed to by me
- *parent*: the node that points to me
- *Sibling*: another child of my parent
- *ancestor*: my parent or my parent's ancestor



- *descendent*: my child or my child's descendent
- *subtree*: a node and its descendants

Tree Terminology

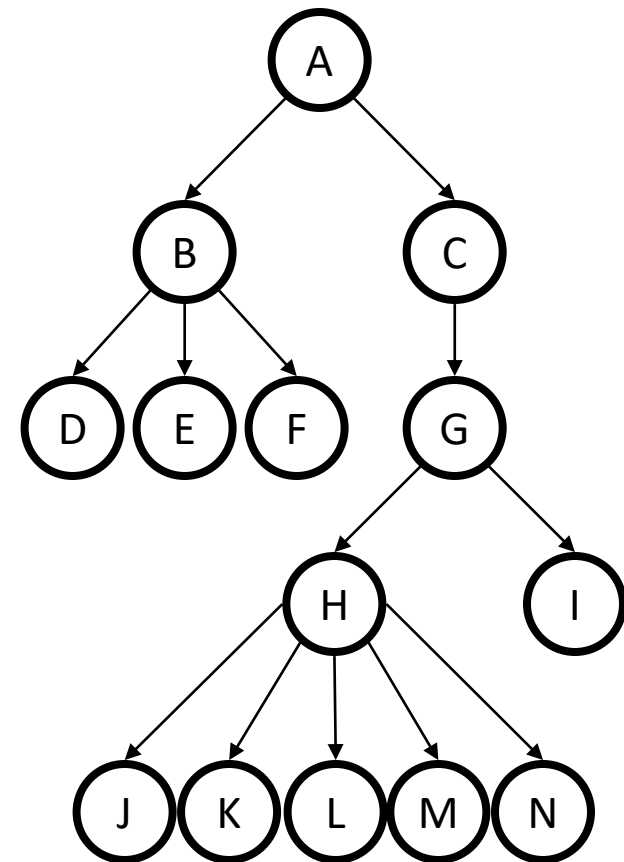
- *depth*: # of edges along path from root to node
 - *depth of H?*
 - 3
- *height*: # of edges along longest path from node to leaf or, for whole tree, from root to leaf
 - *height of tree?*
 - 4



Tree Terminology

- *degree*: # of children of a node
 - *degree of B?*
 - 3
- *branching factor*: maximum degree of any node in the tree

2 for binary trees,
5 for this weird tree

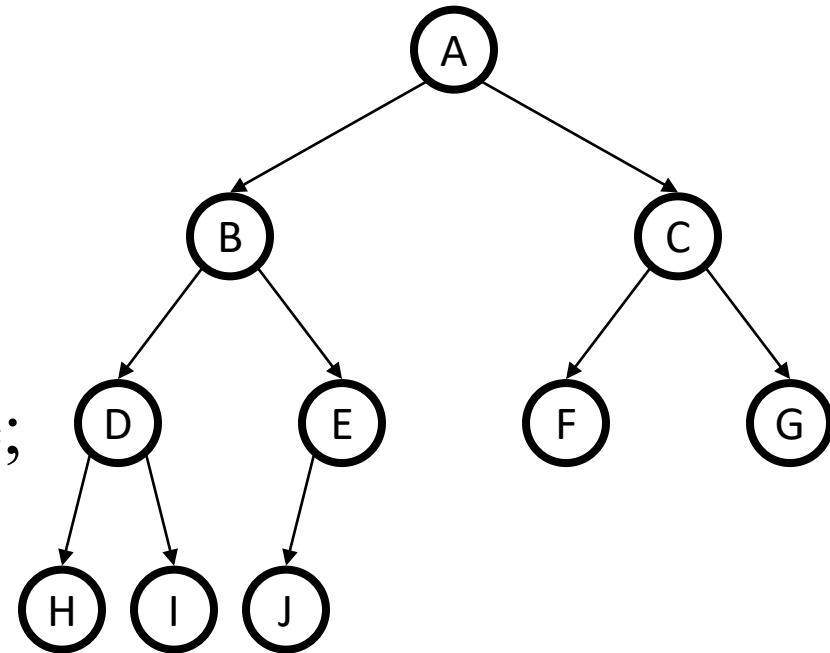


One More Tree Terminology Slide

- **binary**: branching factor of 2 (each child has at most 2 children)

- **n-ary**: branching factor of n

- **complete**: “packed” binary tree;
as many nodes as
possible for its height



- **nearly complete**: complete plus some nodes on the left at the bottom

Trees and (Structural) Recursion

A tree is either:

- the empty tree
- a root node and an ordered list of subtrees

Trees are a recursively defined structure, so it makes sense to operate on them recursively.

Dictionary ADT

Tree Terminology

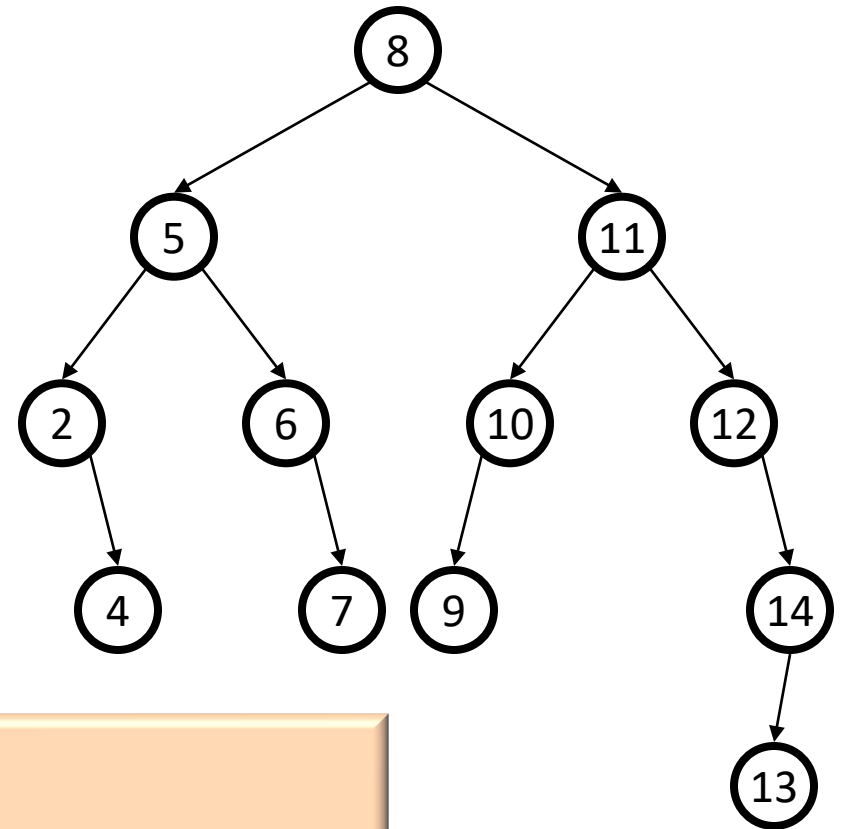
Binary Search Trees (BSTs)

Insertion and Deletion in BSTs

Binary Search Tree

- Binary tree property

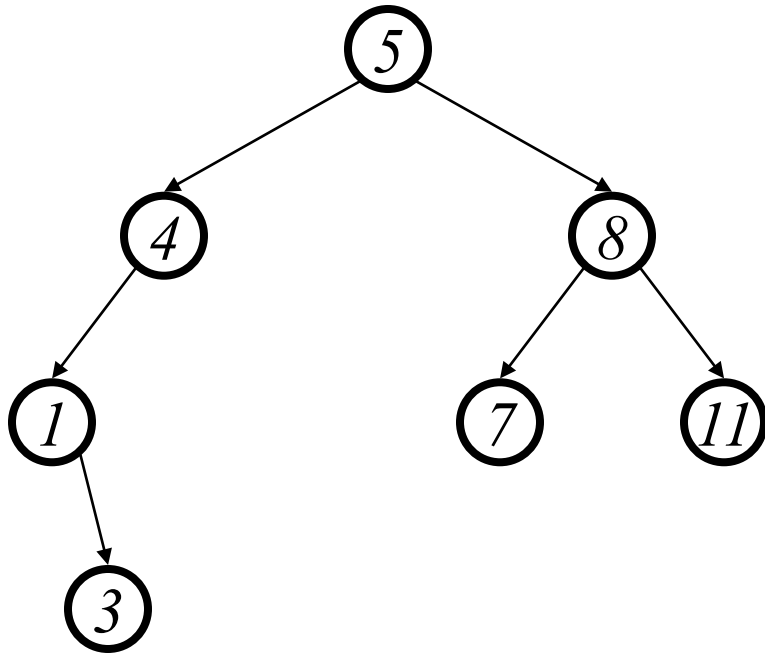
- each node has ≤ 2 children
- result:
 - operations are simple



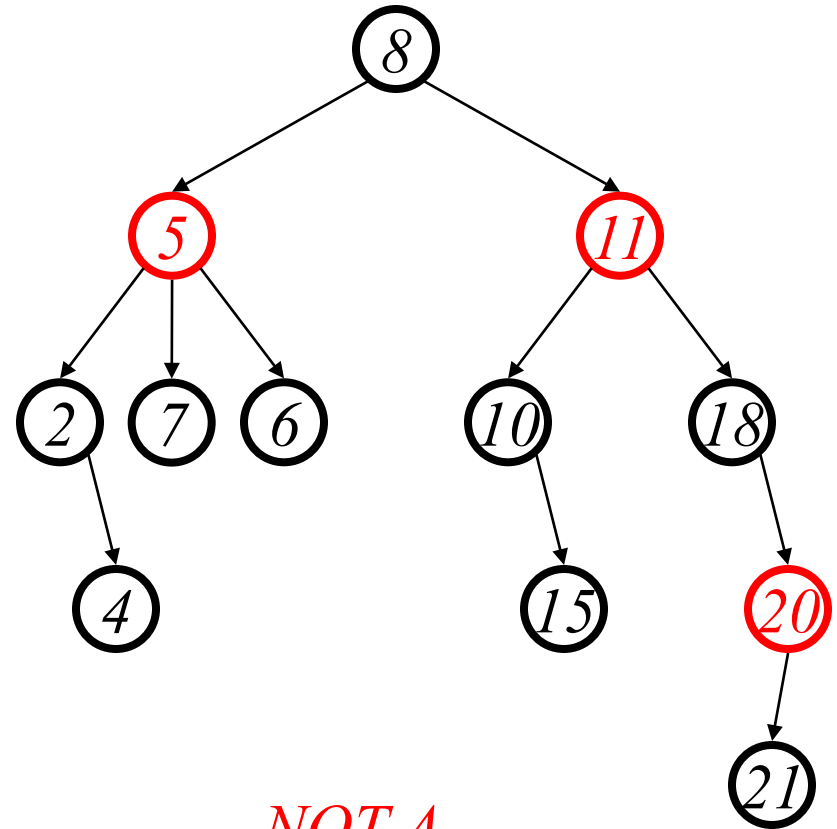
- Search tree property

- **all** keys in left subtree smaller than root's key
- **all** keys in right subtree larger than root's key
- result:
 - easy to find any given key

Example and Counter-Example



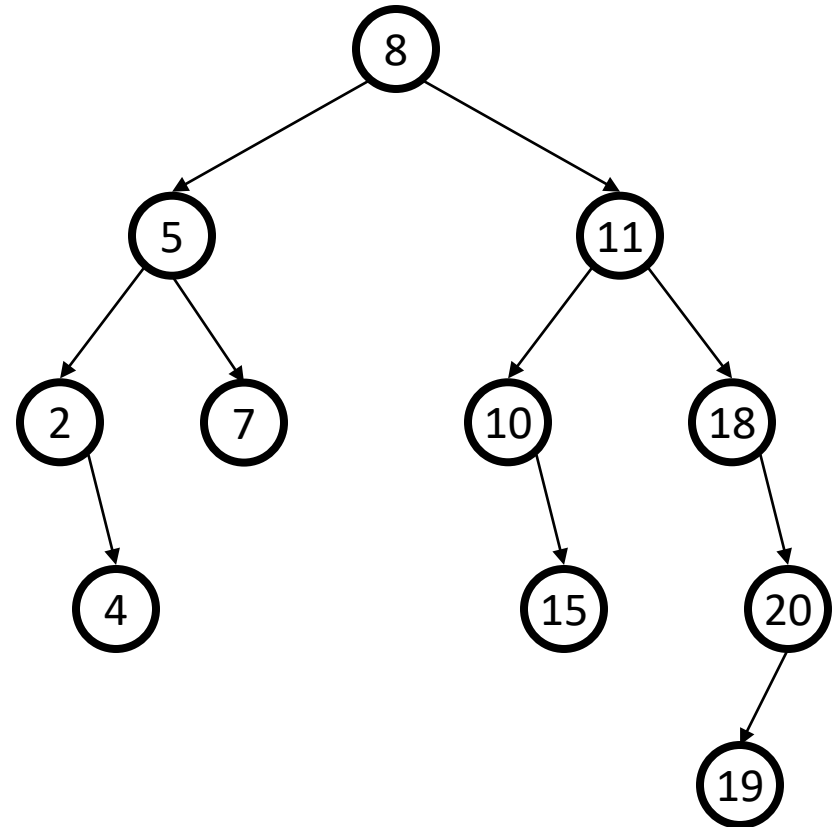
BINARY SEARCH TREE



*NOT A
BINARY SEARCH TREE*

Clicker Question

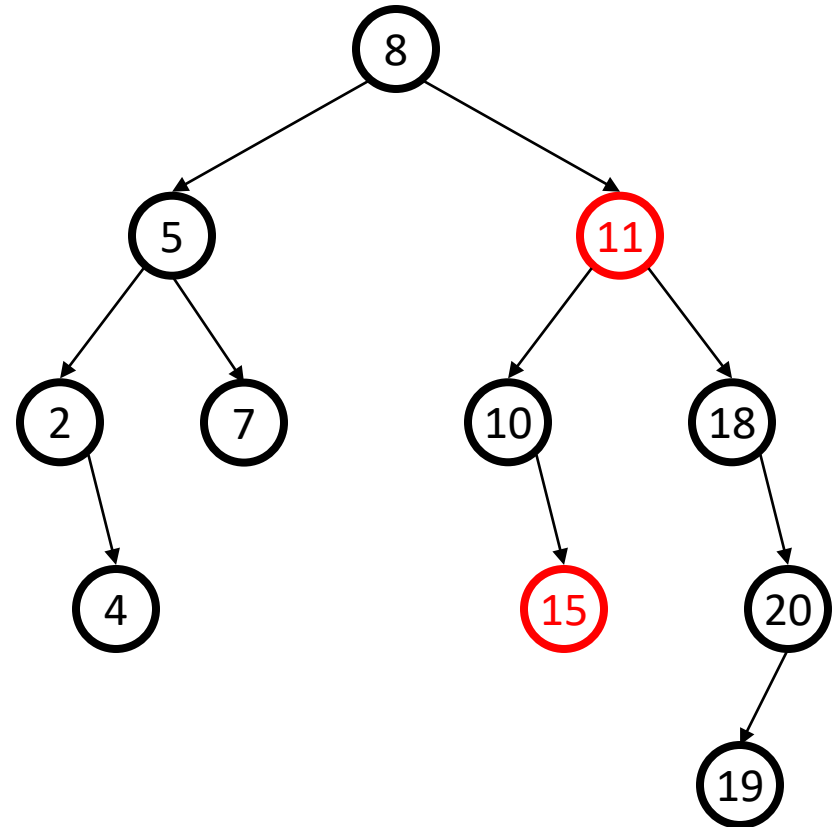
- The tree on the right is...



- A. a Binary Search Tree.
- B. not a Binary Search Tree.
- C. hmm... I don't know.

Clicker Question

- The tree on the right is...



- A. a Binary Search Tree.
- B. not a Binary Search Tree.
- C. hmm... I don't know.

Representing Binary Search Trees

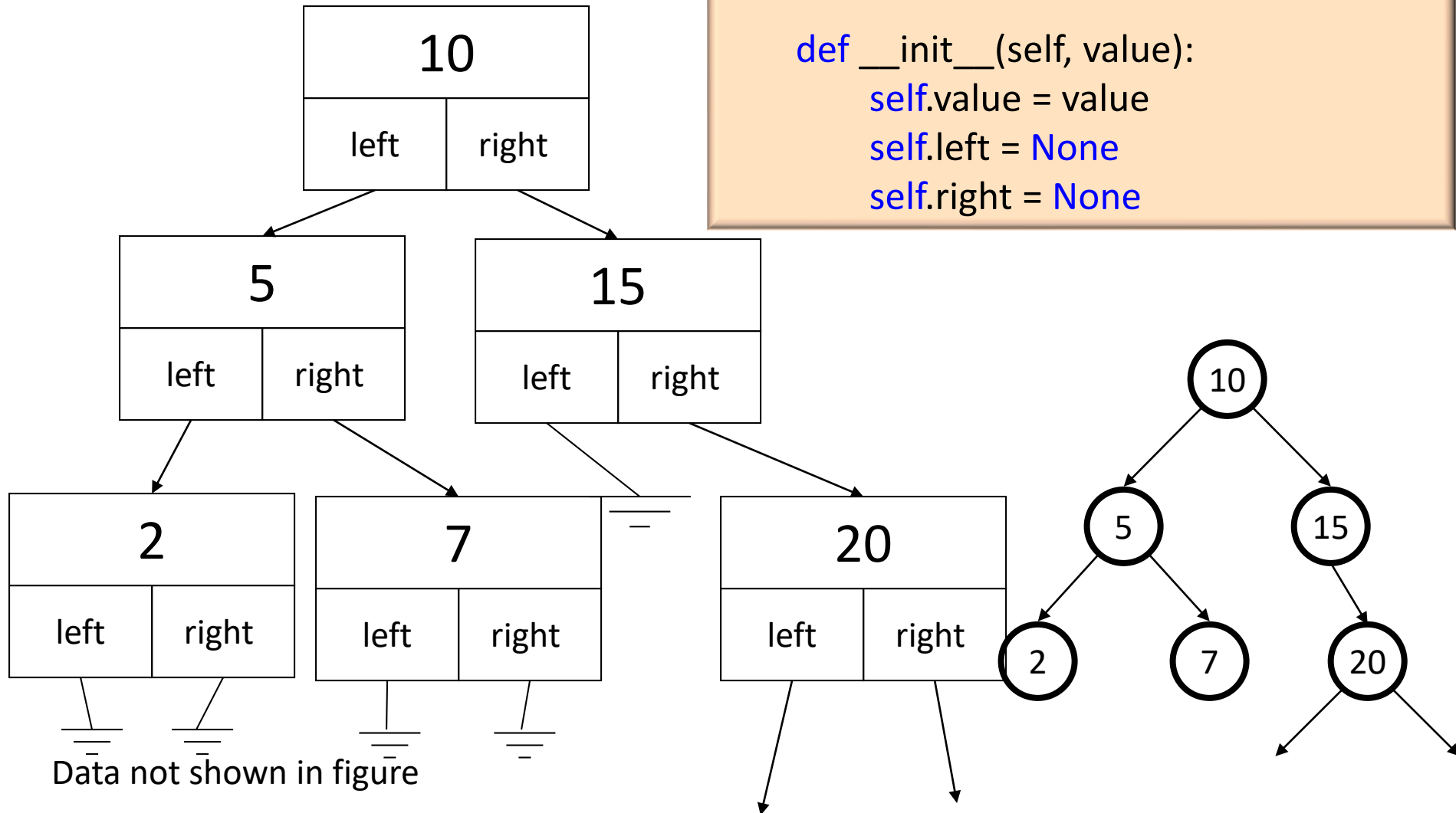
```
class Node2(object):
```

```
    def __init__(self, value):
```

```
        self.value = value
```

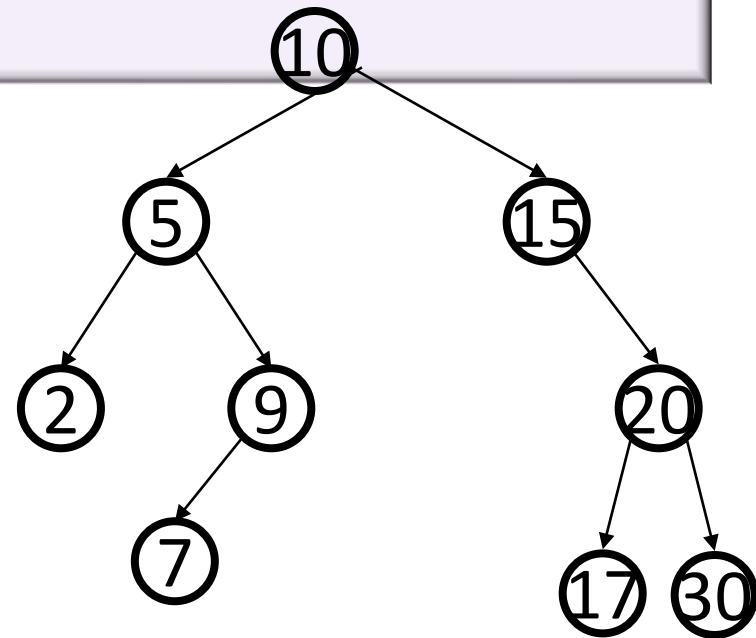
```
        self.left = None
```

```
        self.right = None
```

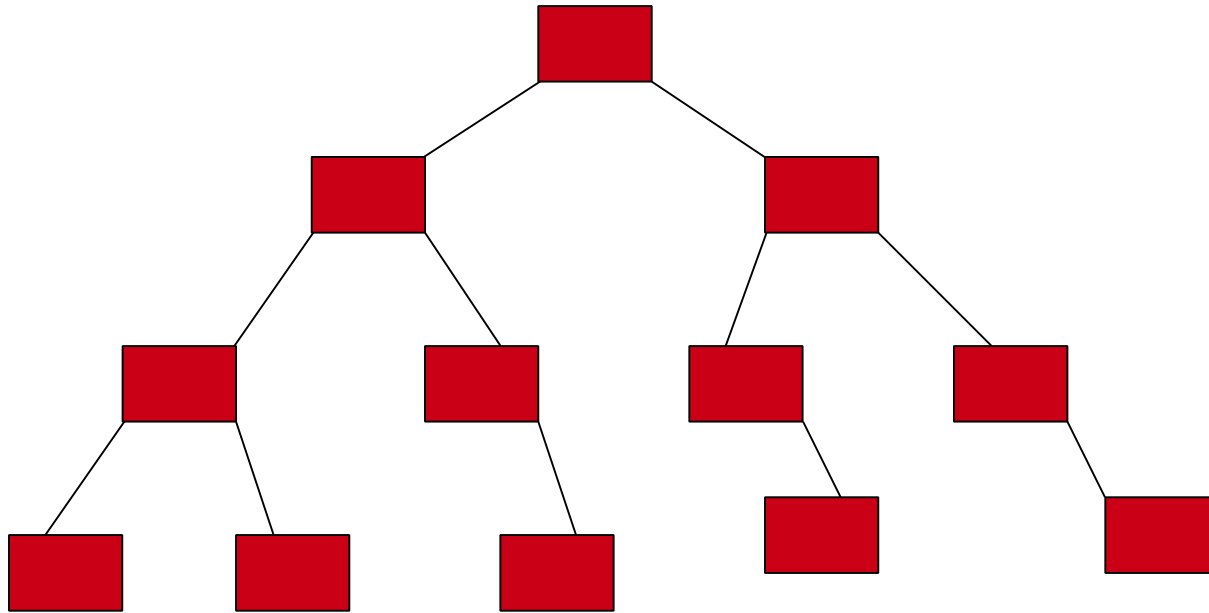


Finding a Node

```
def search(root,key):  
    # Base Cases: root is null or key is present at root  
    if root is None or root.value == key:  
        return root  
    # Key is greater than root's key  
    if root.value < key:  
        return search(root.right,key)  
    # Key is smaller than root's key  
    return search(root.left,key)
```

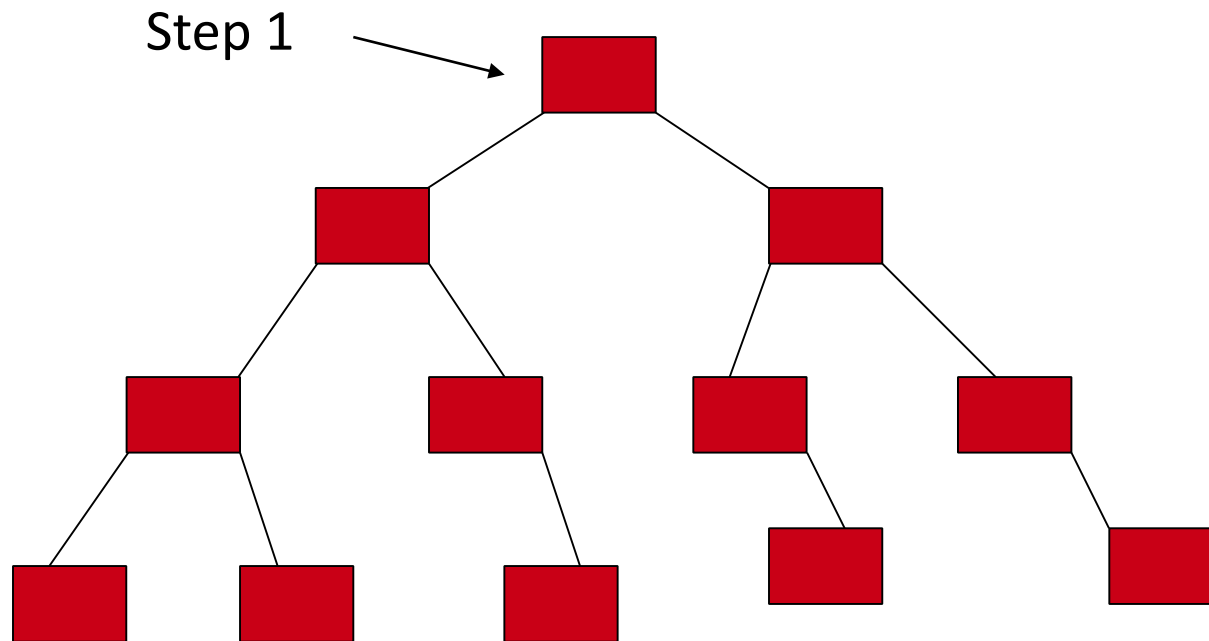


What Makes a Balanced BST Efficient for Searching?



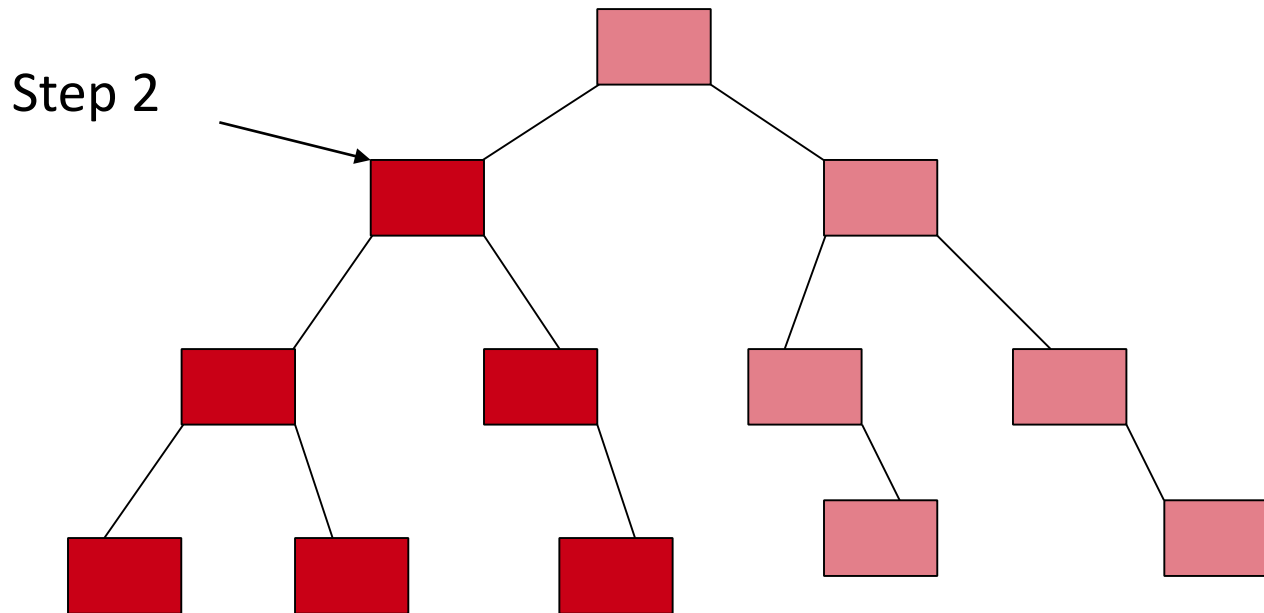
Each step we take as we search the tree reduces the remaining search space by half.

Sample Search



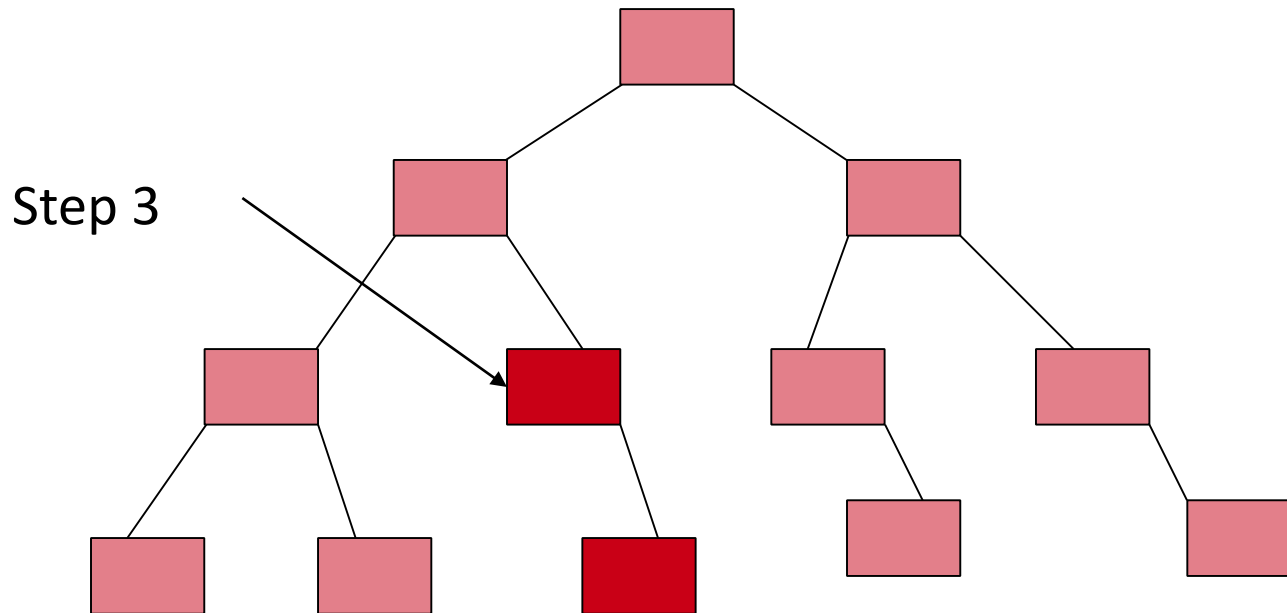
Each step we take as we search the tree reduces the remaining search space by half.

Sample Search



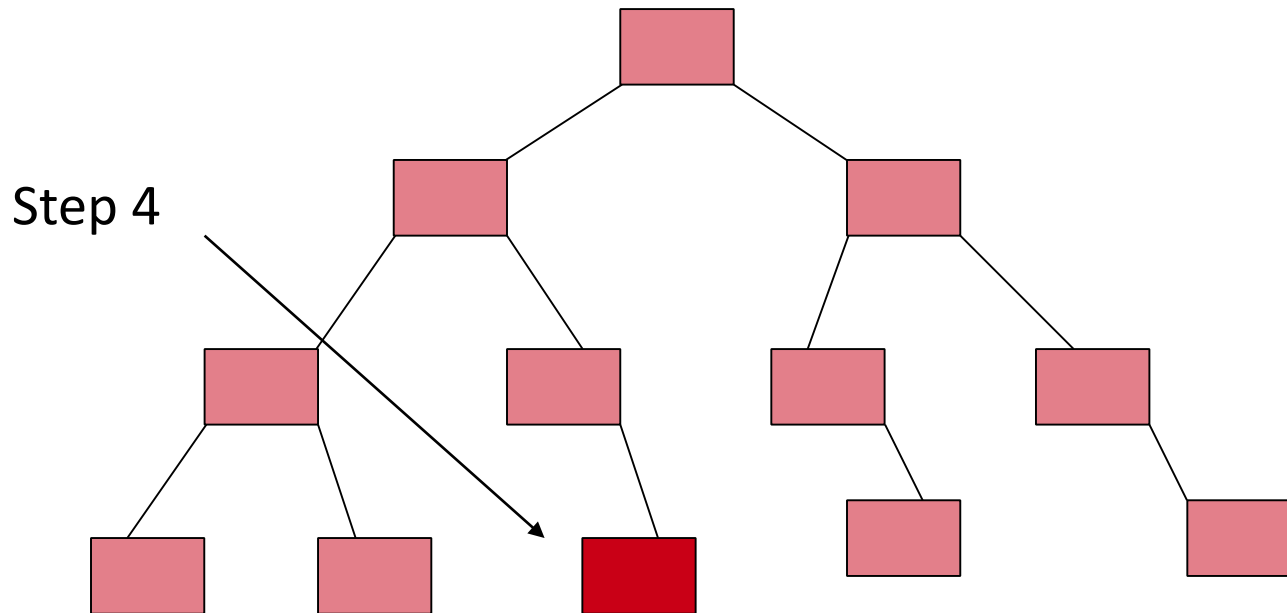
Each step we take as we search the tree reduces the remaining search space by half.

Sample Search



Each step we take as we search the tree reduces the remaining search space by half.

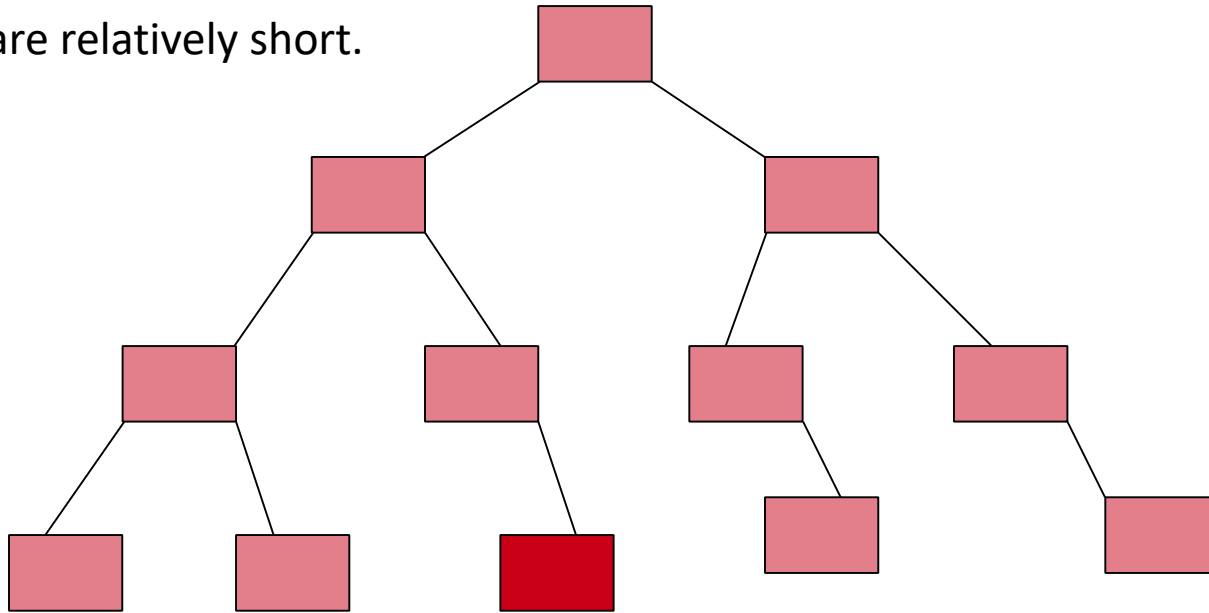
Sample Search



Each step we take as we search the tree reduces the remaining search space by half.

Sample Search

The tree has low height and all paths from the root node to other nodes are relatively short.



Each step we take as we search the tree reduces the remaining search space by half.

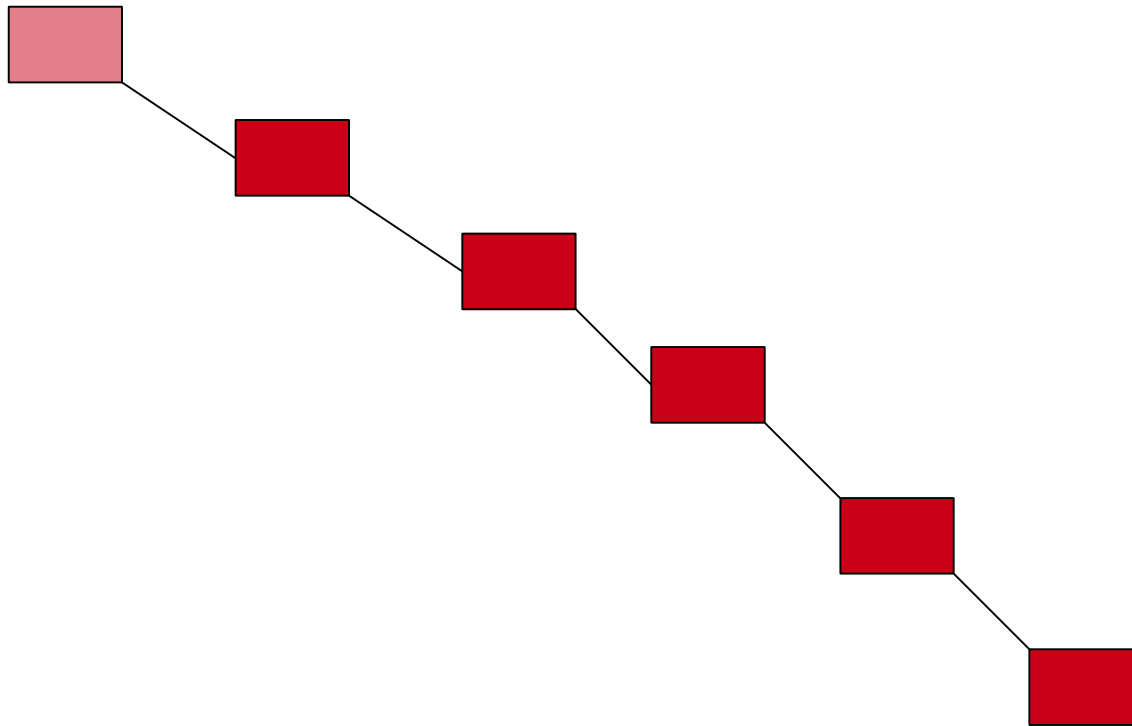
Clicker Question

- What is the running time of the find function in BSTs? (height represents the height of the tree)
- A. $\Theta(n)$
- B. $\Theta(\lg n)$
- C. $\Theta(\text{height})$
- D. $\Theta(n^2)$
- E. *None of the above*

Clicker Question

- What is the running time of the find function in BSTs? (height represents the height of the tree)
- A. $\Theta(n)$
- B. $\Theta(\lg n)$
- C. $\Theta(\text{height})$**
- D. $\Theta(n^2)$
- E. *None of the above*

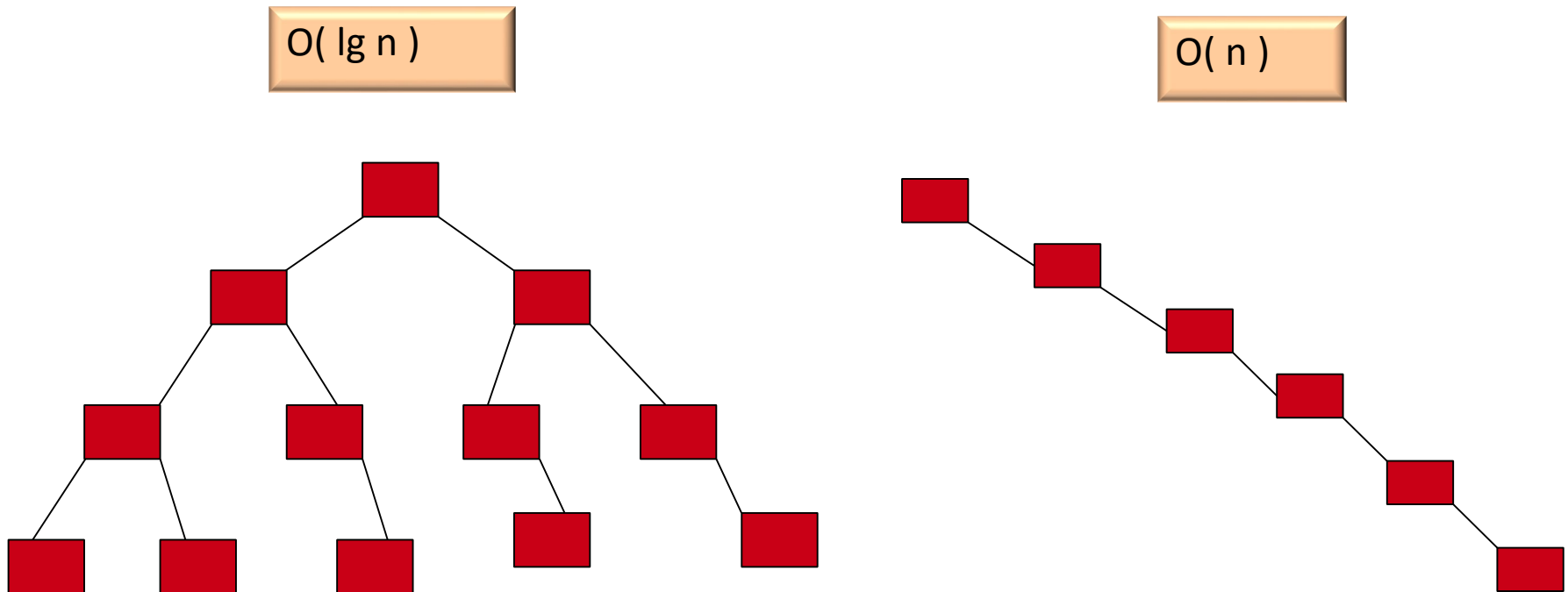
Unbalanced Trees



In contrast, this unbalanced tree has long paths from the root to other nodes. It essentially has degenerated to a linked list, which is very slow to search through. Now, with each step we take, we have only reduced the search space by one node.

Time of Search

- Time of search is proportional to the height of the tree



Time of Search

- What does this tell you about strengths and weaknesses of BSTs?
- Using BSTs is only efficient if they are fairly balanced. Whether BSTs are balanced is highly dependent on the order of the values being added.
- There are extensions and improvements to Binary Search Trees such as **AVL trees**, **B+ trees** or **red-black trees**. I encourage you to read about them, but they are outside of the scope of this course.

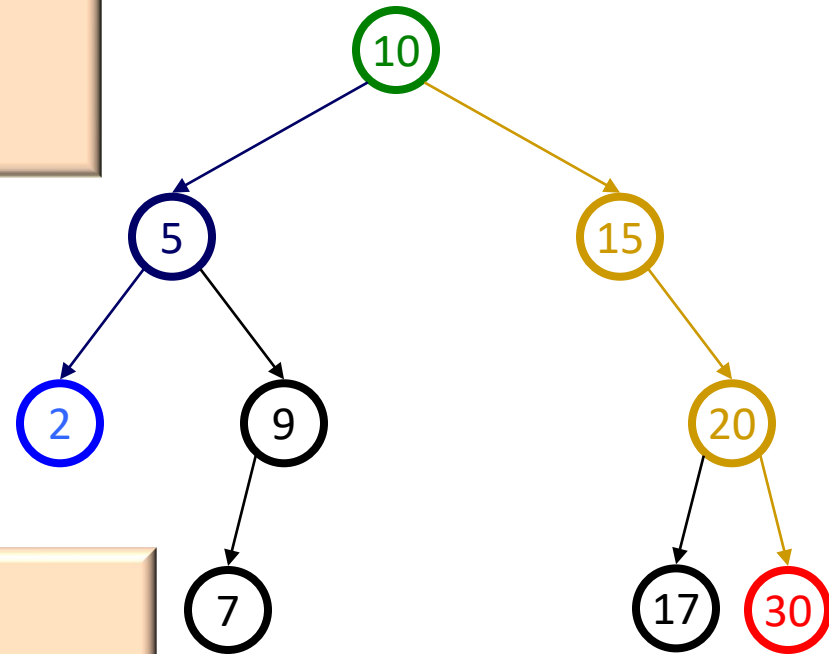
Bonus: FindMin/FindMax

- Find **minimum**

```
def find_min(root):  
    current_node = root  
    while current_node.left:  
        current_node = current_node.left  
    return current_node
```

- Find **maximum**

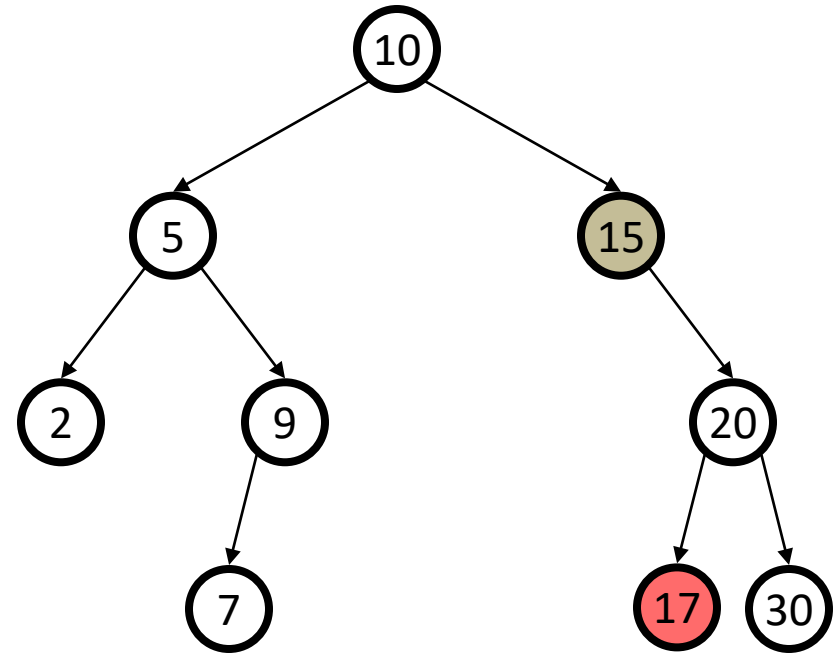
```
def find_max(root):  
    current_node = root  
    while current_node.right:  
        current_node = current_node.right  
    return current_node
```



Double Bonus: Successor

Find the next larger node
in a node's subtree.

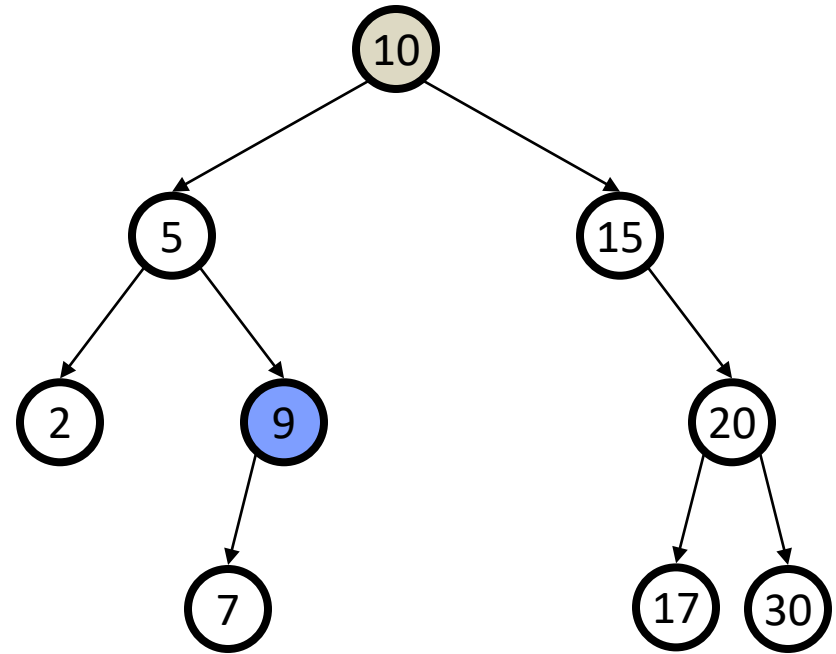
```
def succ (x):  
    return find_min(x.right)
```



More Double Bonus: Predecessor

Find the next smaller node
in a node's subtree.

```
def Pred (x):  
    return find_max(x.left)
```



Dictionary ADT

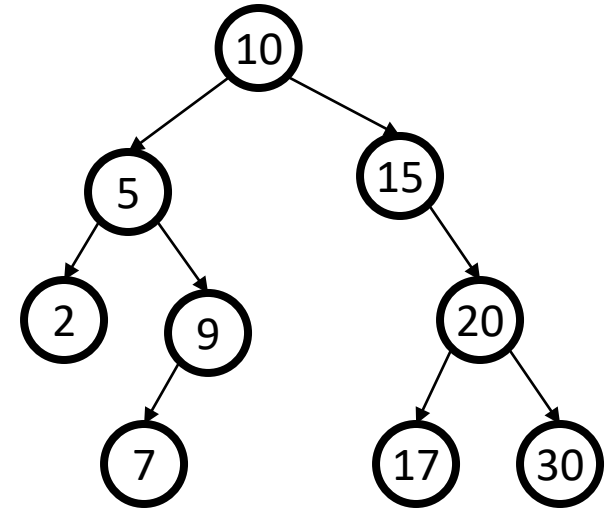
Tree Terminology

Binary Search Trees (BSTs)

Insertion and Deletion in BSTs

Insertion Algorithm

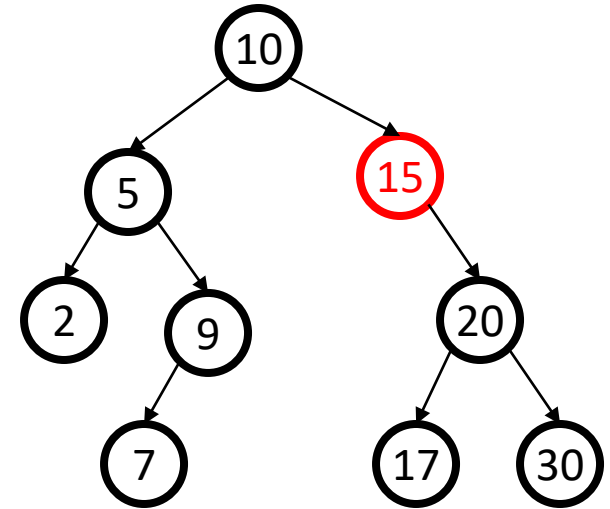
1. perform search for value X
2. if X is in tree
return
- // else search will end at a node. Call it Y*
3. if $X < Y$
insert X as new left subtree for Y
4. if $X > Y$
insert X as new right subtree for Y



Insertion Algorithm

1. perform search for value X
2. if X is in tree
return
- // else search will end at a node. Call it Y
3. if $X < Y$
insert X as new left subtree for Y
4. if $X > Y$
insert X as new right subtree for Y

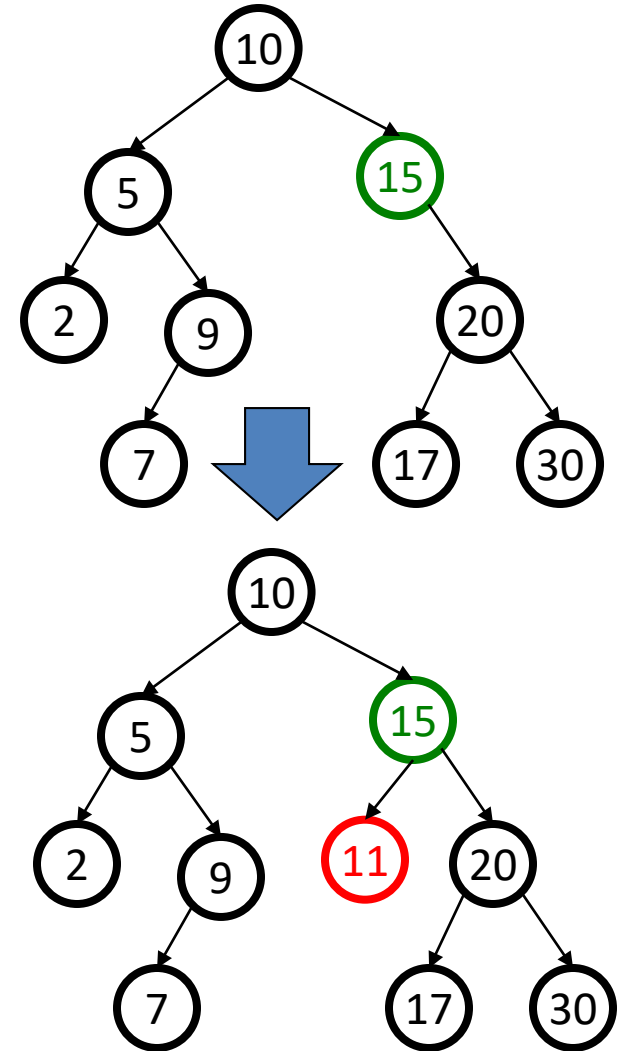
insert(15)



Insertion Algorithm

1. perform search for value X
2. if X is in tree
return
3. if $X < Y$
insert X as new left subtree for Y
4. if $X > Y$
insert X as new right subtree for Y

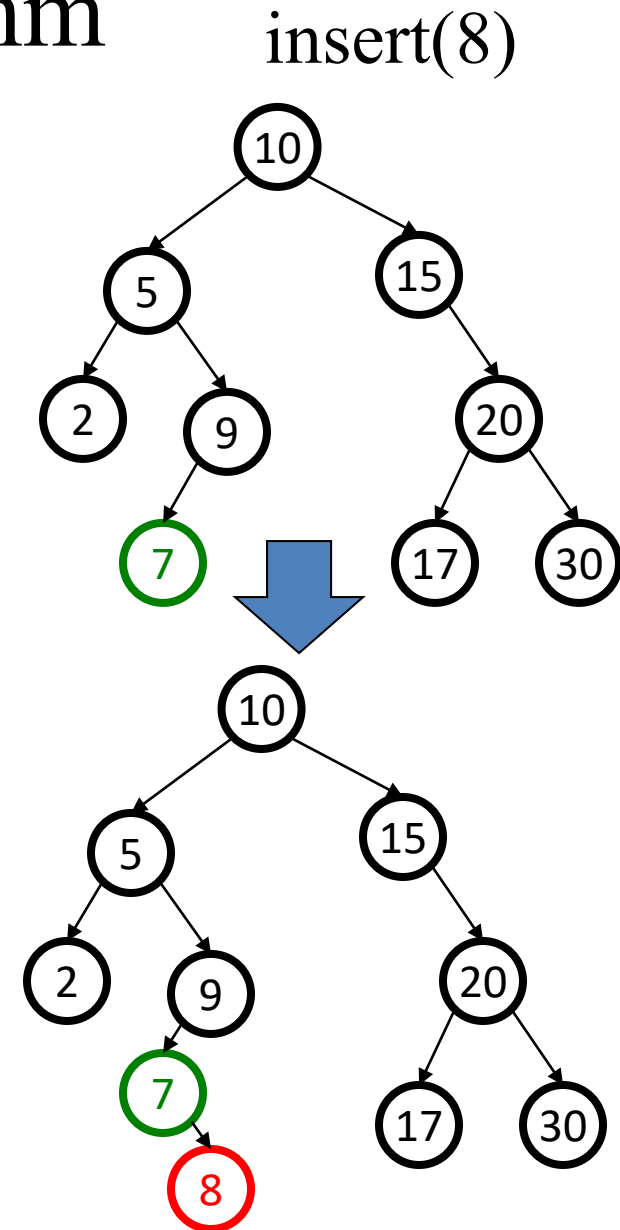
insert(11)



Insertion Algorithm

1. perform search for value X
2. if X is in tree
return
- // else search will end at a node. Call it Y*
3. if $X < Y$
insert X as new left subtree for Y
4. if $X > Y$
insert X as new right subtree for Y

Runtime?



Insertion Algorithm

```
def insert(root,node):  
    if root is None:  
        root = node  
    else:  
        if root.value == node.value: # already exists  
            return  
        # To be inserted on the right side of current root  
        elif root.value < node.value:  
            if root.right is None:  
                root.right = node  
            else:  
                insert(root.right, node)  
        # To be inserted on the left side of current root  
        else:  
            if root.left is None:  
                root.left = node  
            else:  
                insert(root.left, node)
```

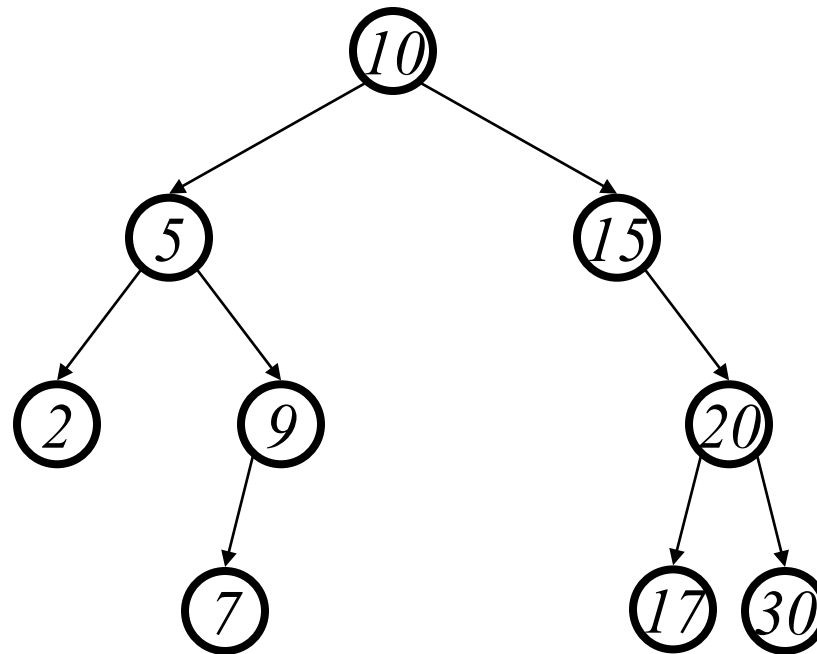

BuildTree for BSTs

- Suppose the data 1, 2, 3, 4, 5, 6, 7, 8, 9 is inserted into an initially empty BST:
 - in order (1, 2, 3, 4, 5, 6, 7, 8, 9)
 - in reverse order (9, 8, 7, 6, 5, 4, 3, 2, 1)
 - median first, then left median, right median, etc.
so: 5, 3, 8, 2, 4, 7, 9, 1, 6

Analysis of BuildTree

- Worst case: $O(n^2)$ as we've seen
- Average case assuming all orderings equally likely turns out to be $O(n \lg n)$.

Deletion



Why might deletion be harder than insertion?

Deletion Algorithm

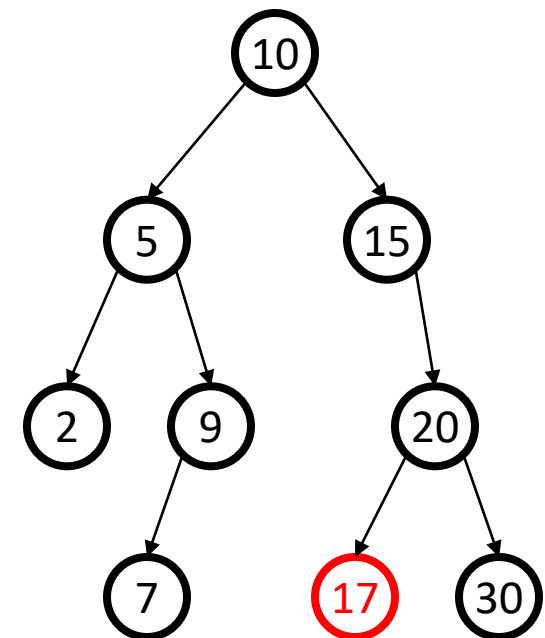
1. perform search for value X
2. if X is not in tree
 return

 //else X is in tree
3. if X has no children,
 delete X
4. else if X has only one child
 promote the unique child to X's place.
 delete X
5. else // X must have two children
 identify X's successor. Call it Y
 replace X with Y
 delete Y // $Y \leq 1$ children

Deletion Algorithm

1. perform search for value X
2. if X is not in tree
return
- //else X is in tree*
3. if X has no children,
delete X
4. else if X has only one child
promote the unique child to X's place.
delete X
5. else *// X must have two children*
identify X's successor. Call it Y
replace X with Y
delete Y *// Y ≤ 1 children*

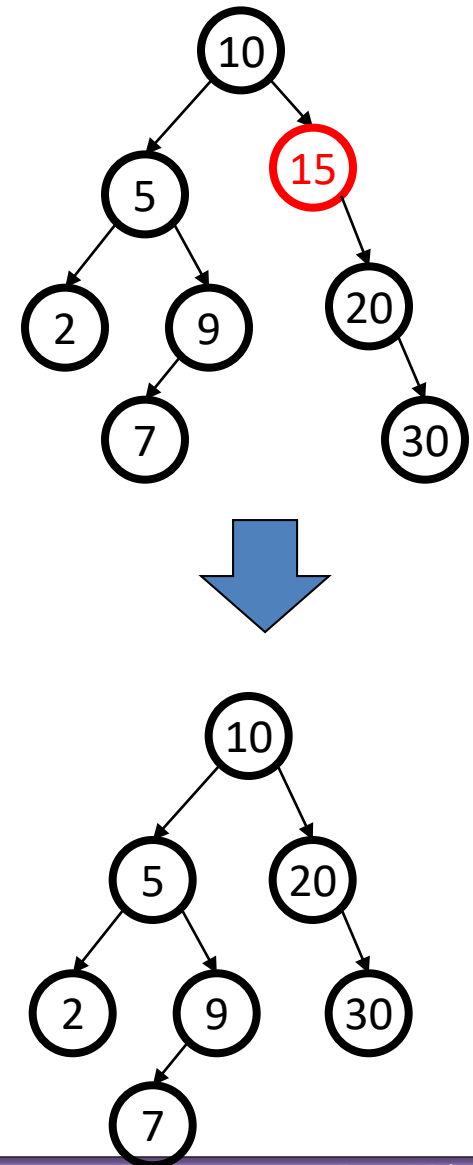
Delete(17)



Deletion Algorithm

Delete(15)

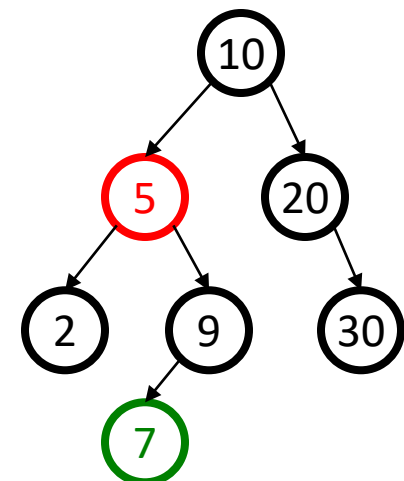
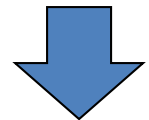
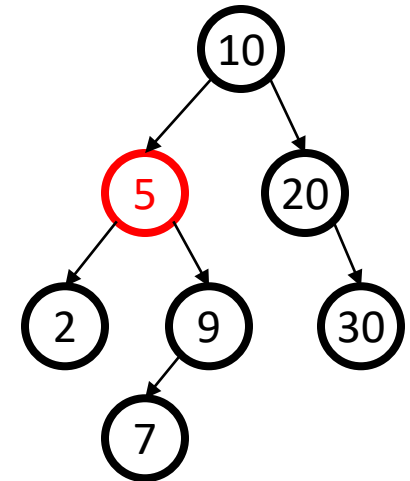
1. perform search for value X
2. if X is not in tree
return
- //else X is in tree*
3. if X has no children,
delete X
4. **else if X has only one child**
promote the unique child to X's place.
delete X
5. *else // X must have two children*
identify X's successor. Call it Y
replace X with Y
delete Y *// Y ≤ 1 children*



Deletion Algorithm

1. perform search for value X
2. if X is not in tree
return
- //else X is in tree*
3. if X has no children,
delete X
4. else if X has only one child
promote the unique child to X's place.
delete X
5. **else** *// X must have two children*
identify X's successor. Call it Y
replace X with Y
delete Y *// Y ≤ 1 children*

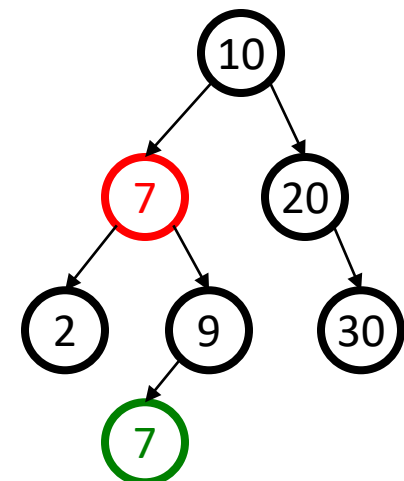
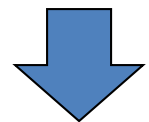
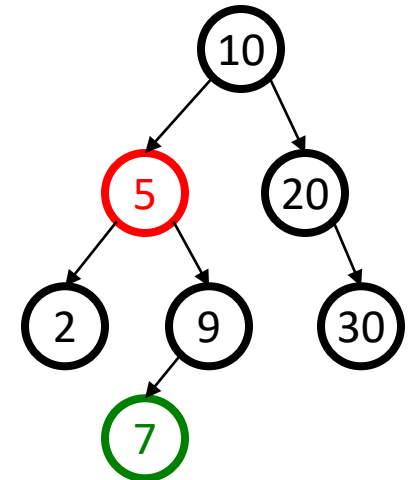
Delete(5)



Deletion Algorithm

1. perform search for value X
2. if X is not in tree
return
- //else X is in tree*
3. if X has no children,
delete X
4. else if X has only one child
promote the unique child to X's place.
delete X
5. **else** *// X must have two children*
identify X's successor. Call it Y
replace X with Y
delete Y *// Y ≤ 1 children*

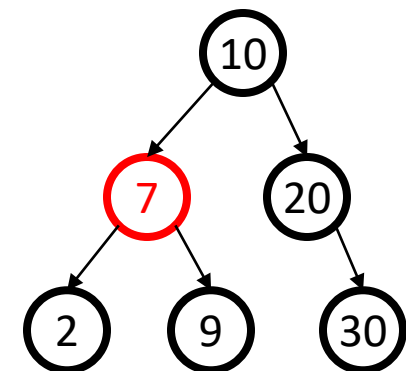
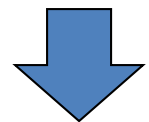
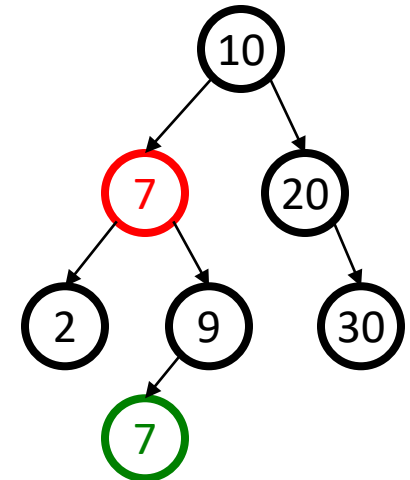
Delete(5)



Deletion Algorithm

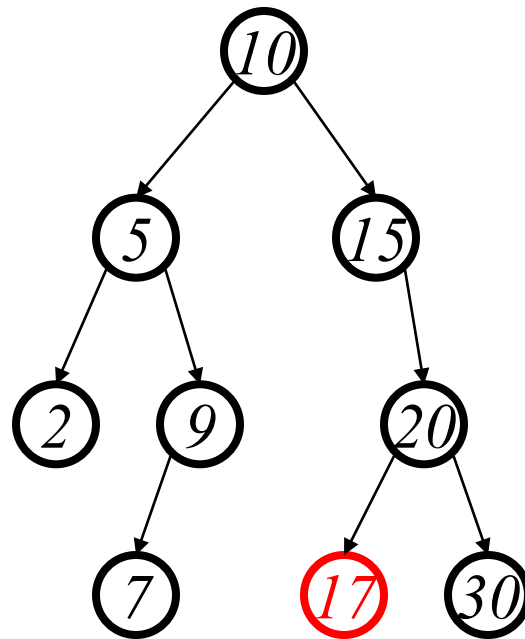
1. perform search for value X
2. if X is not in tree
return
- //else X is in tree*
3. if X has no children,
delete X
4. else if X has only one child
promote the unique child to X's place.
delete X
5. **else** *// X must have two children*
identify X's successor. Call it Y
replace X with Y
delete Y *// Y ≤ 1 children*

Delete(5)



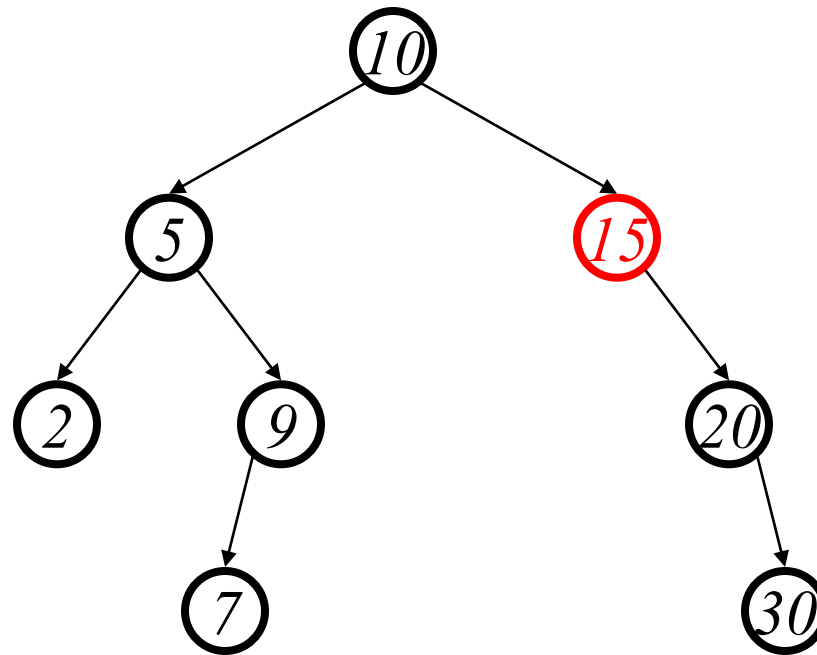
Deletion - Leaf Case

Delete(17)



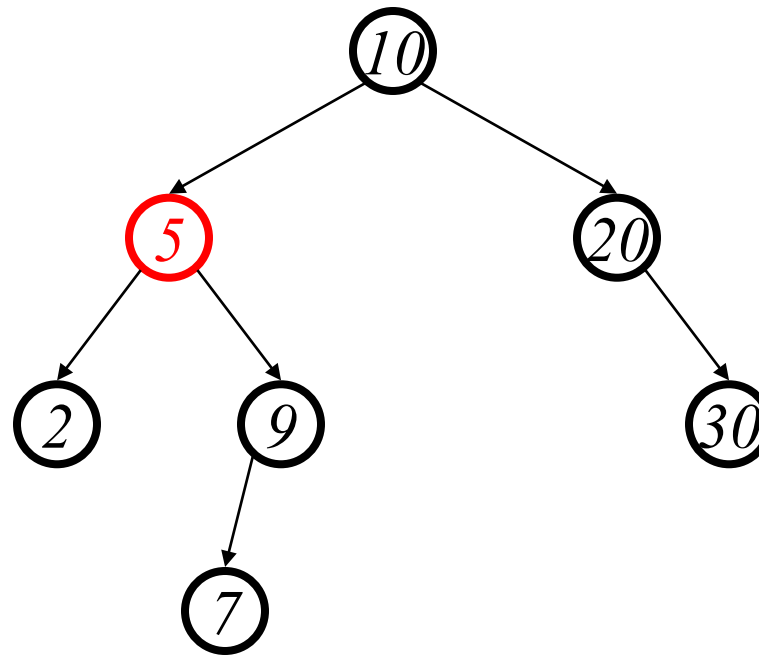
Deletion - One Child Case

Delete(15)



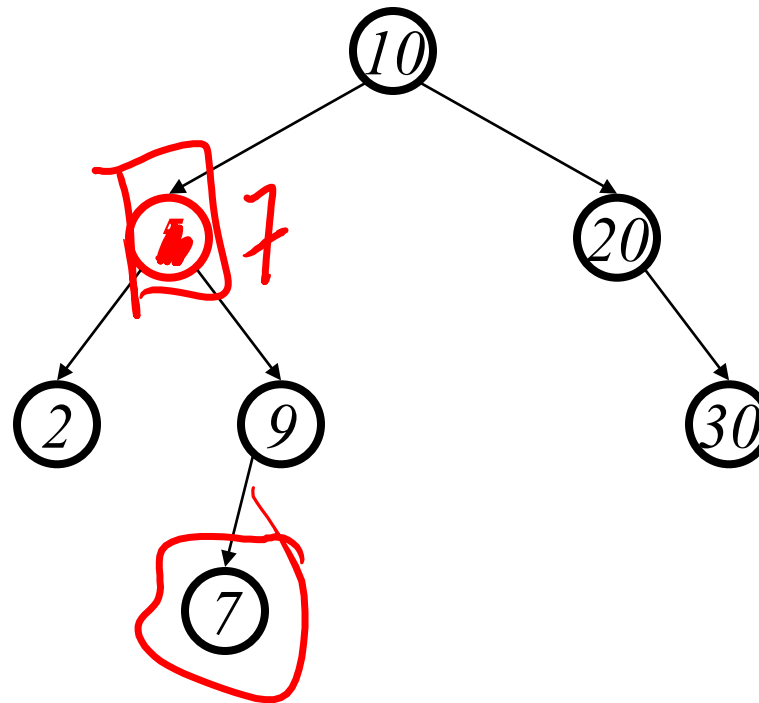
Deletion - Two Child Case

Delete(5)



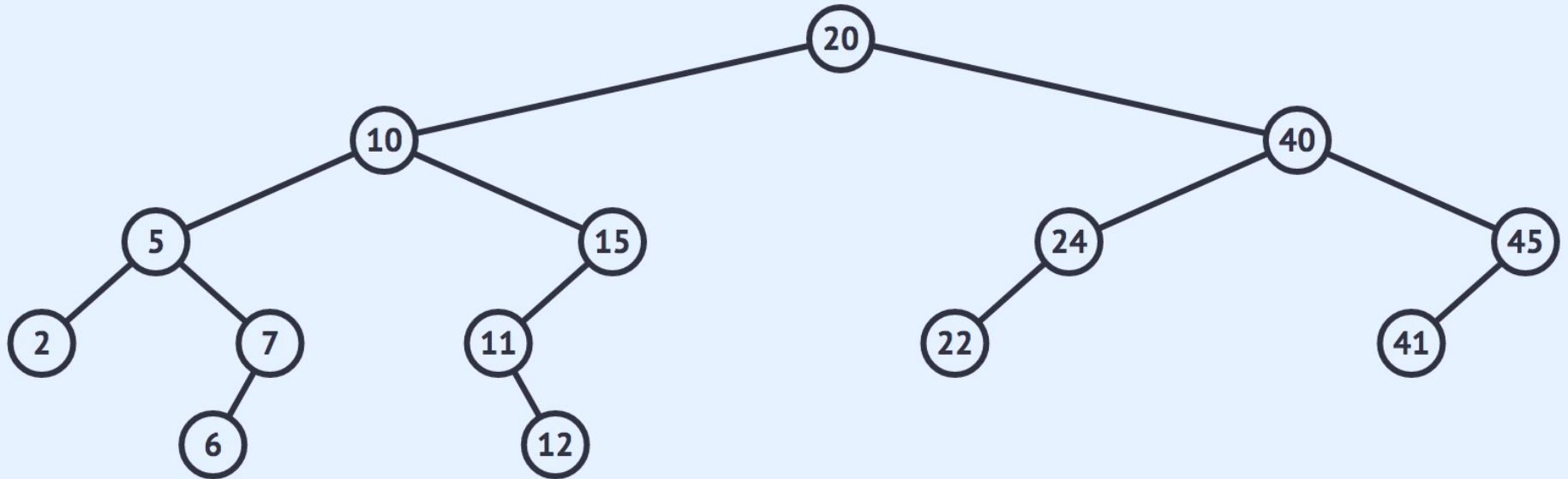
Deletion - Two Child Case

Delete(5)



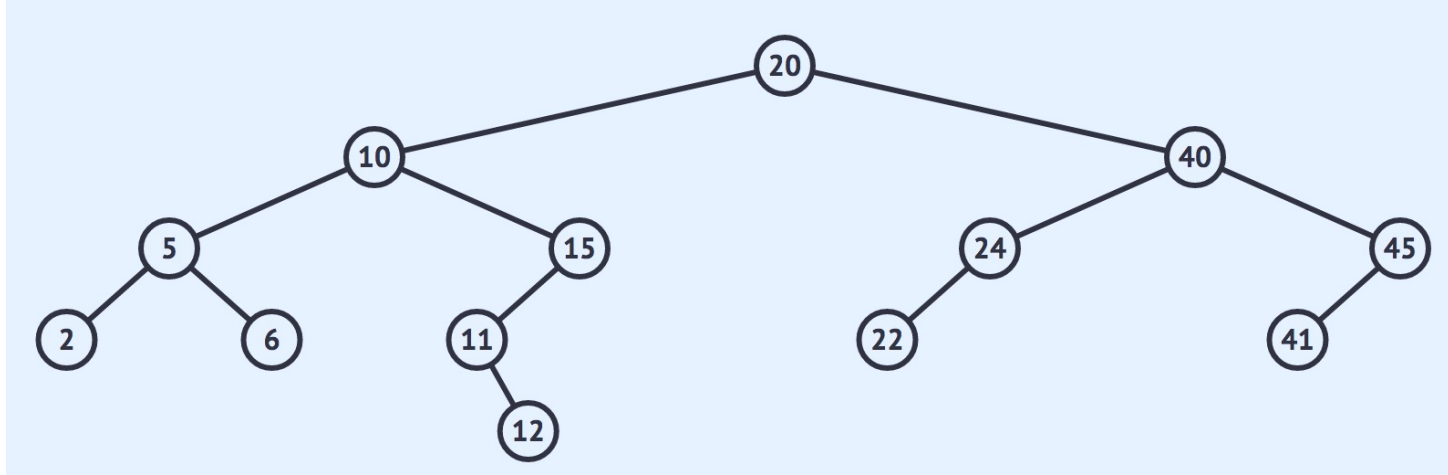
In-Class Exercise

- Draw the binary search tree, which results from adding the following keys in the given order:
 - 20, 10, 40, 5, 7, 2, 15, 11, 12, 6, 24, 22, 45, 41

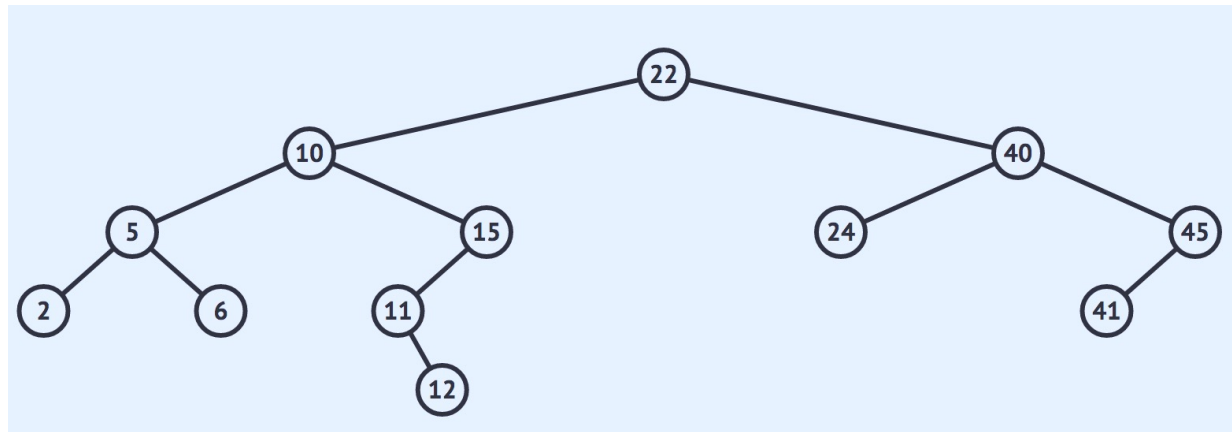


In-Class Exercise

- From your tree remove key with value 7



- From your tree remove key with value 20 (using successor)



Learning Outcomes

Description	Tag
Describe the different operations that are supported by the dictionary ADT.	Dict-ADT
Demonstrate how arrays can be used for implementation of a dictionary ADT.	Dict-Array
Demonstrate how linked lists can be used for implementation of a dictionary ADT.	Dict-Linkedlist
Describe the properties of binary trees.	Dict-Trees
Describe the properties of Binary Search Trees (BSTs).	
Represent BSTs using linked data structures.	
Insert elements into a BST.	
Delete elements from a BST.	
search for an element in a BST.	
Determine if a given tree is an instance of a BST.	
Compare and contrast algorithms for storing and subsequently retrieving values from a dictionary ADT.	
Reflect on how BSTs and their extensions can be used in DBMS.	