

Brain Hemorrhage Classification of CT Scan Images Using CNNs

Matrix Methods in Data Analysis & Machine Learning

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Project Introduction

- Goal: To train a Convolutional Neural Network (CNN) model for image classification of CT scan images.
- Data Source: Zeta Surgical
- Application: When provided with an unlabeled brain CT image, the model will show us an accurate prediction of the class that has bleeding.

	Intraparenchymal	Intraventricular	Subarachnoid	Subdural	Epidural
Location	Inside of the brain	Inside of the ventricle	Between the arachnoid and the pia mater	Between the Dura and the arachnoid	Between the dura and the skull
Imaging					
Mechanism	High blood pressure, trauma, arteriovenous malformation, tumor, etc	Can be associated with both intraparenchymal and subarachnoid hemorrhages	Rupture of aneurysms or arteriovenous malformations or trauma	Trauma	Trauma or after surger
Source	Arterial or venous	Arterial or venous	Predominantly arterial	Venous (bridging veins)	Arterial
Shape	Typically rounded	Conforms to ventricular shape	Tracks along the sulci and fissures	Crescent	Lentiform
Presentation	Acute (sudden onset of headache, nausea, vomiting)	Acute (sudden onset of headache, nausea, vomiting)	Acute (worst headache of life)	May be insidious (worsening headache)	Acute (skull fracture ar altered mental status

Methodology

- 1. Load the labeled dataset.
 - Use a random sample of 1000 for intraventricular class.
- 2. Convert the images to grayscale.
- 3. Split the dataset into training, testing, and validation sets (80, 15, 5).
- 4. Down-sample by factor of 16.
 - ♦ (512, 512) -> (128, 128)
- 5 Analyze the results on CNN, testing the performance using various optimizers.
 - Model structure kept constant.
 - 3 epochs due to hardware constraints.



Keras Model Structure

- First model had 1.8 million parameters
 - Reduced complexity
- Input shape of (128, 128)
- 6 classes (5 classes plus multi)
- Drop-out: 50%

```
Model: "sequential
Layer (type)
                             Output Shape
conv2d (Conv2D)
                              (None, 126, 126, 32)
max pooling2d (MaxPooling2D) (None, 63, 63, 32)
conv2d 1 (Conv2D)
                             (None, 61, 61, 64)
                                                         18496
max pooling2d 1 (MaxPooling2 (None, 30, 30, 64)
flatten (Flatten)
                              (None, 57600)
dense (Dense)
                              (None, 16)
                                                         921616
dropout (Dropout)
                              (None, 16)
Trainable params: 940,534
Non-trainable params: 0
```

```
model_cnn_adam = keras.models.Sequential()
model_cnn_adam.add(keras.layers.Conv2D(32, (3,3), padding = 'valid', input_shape=(128,128,1), activation = 'relu'))
model_cnn_adam.add(keras.layers.MaxPooling2D((2,2)))
model_cnn_adam.add(keras.layers.Conv2D(64, (3,3), padding = 'valid', activation = 'relu'))
model_cnn_adam.add(keras.layers.MaxPooling2D((2,2)))
model_cnn_adam.add(keras.layers.Flatten())
model_cnn_adam.add(keras.layers.Dense(16))
model_cnn_adam.add(keras.layers.Dropout(0.5))
model_cnn_adam.add(keras.layers.Dense(6))
```

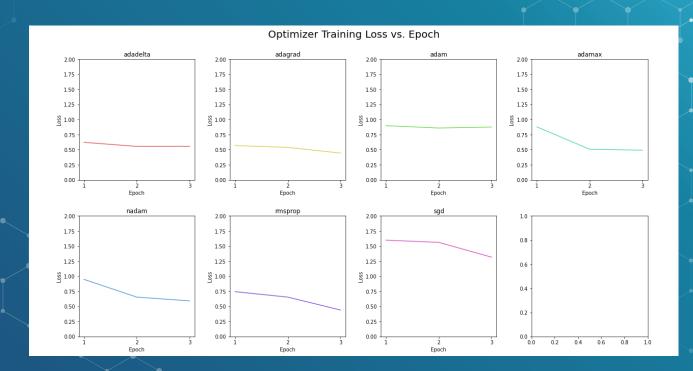
Model Results

```
model_cnn_adam.evaluate(X_test, yds_test)
[0.3242693841457367, 0.9798816442489624]
model cnn sgd.evaluate(X test, yds test)
423/423 [============= ] - 18s 43ms/step - loss: 0.3243 - accuracy: 0.9799
[0.3242693841457367, 0.9798816442489624]
model cnn adamax.evaluate(X test, yds test)
423/423 [================== ] - 19s 44ms/step - loss: 0.1120 - accuracy: 0.9393
[0.11202788352966309, 0.9393491148948669]
model_cnn_adadelta.evaluate(X_test, yds_test)
423/423 [=================] - 18s 43ms/step - loss: 0.7936 - accuracy: 0.9385
[0.7935603260993958, 0.9385355114936829]
model cnn adagrad.evaluate(X test, yds test)
[0.1120600700378418, 0.9375]
model_cnn_nadam.evaluate(X_test, yds_test)
423/423 [=============== ] - 18s 42ms/step - loss: 0.1236 - accuracy: 0.9375
[0.1236410140991211, 0.9375]
```

```
# finding best learning rate
plt.plot(expon lr cnn sgd.rates, expon lr cnn sgd.losses)
plt.gca().set xscale('log')
plt.hlines(min(expon_lr_cnn_sgd.losses), min(expon_lr_cnn_sgd.rates), max(expon_lr_cnn_sgd.rates))
plt.axis([min(expon_lr_cnn_sgd.rates), max(expon_lr_cnn_sgd.rates), 0, expon_lr_cnn_sgd.losses[0]))
plt.grid()
plt.xlabel("Learning rate")
plt.ylabel("Loss")
plt.show
<function matplotlib.pyplot.show(close=None, block=None)>
 1 75
 1.50
Š 1.00
 0.50
              1.1 × 10<sup>-3</sup> 1.2 × 10<sup>-3</sup> 1.3 × 10<sup>-3</sup> 1.4 × 10<sup>-3</sup> 1.5 × 10<sup>-3</sup>
min(expon_lr_cnn_sgd.losses)
1.286063313484192
expon_lr_cnn_sgd.rates[np.argmin(expon_lr_cnn_sgd.losses)]
```



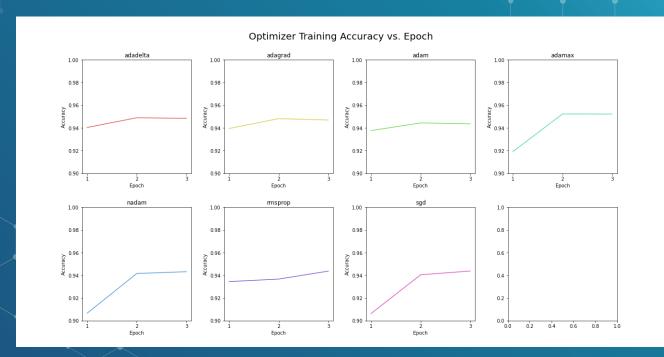
Loss vs. Epoch by Optimizer



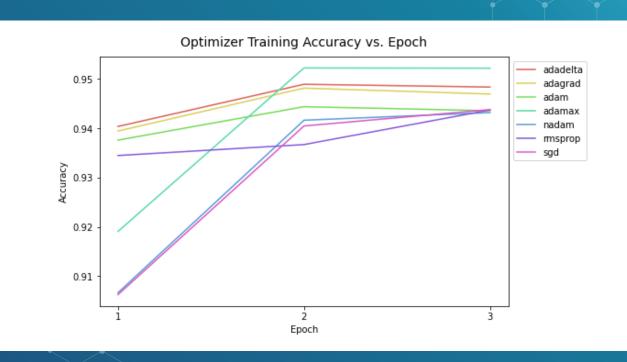
Loss vs. Epoch, All Optimizers



Accuracy vs. Epoch by Optimizer



Accuracy vs. Epoch, All Optimizers

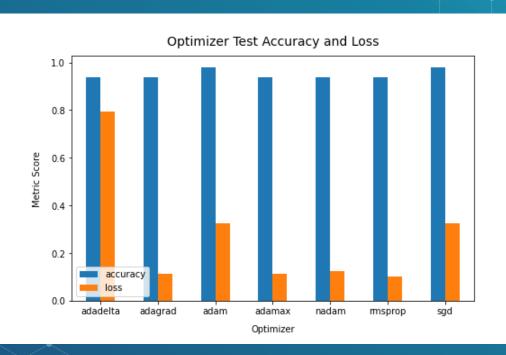


Accuracy vs. Val Accuracy Over Epoch, by Optimizer





Test Accuracy and Loss by Optimizer





Conclusion & Reflection

What we achieved:

- Best optimizer found to be Adam.
 - ♦ Training & training accuracy: 0.98
- SGD is close, but loss is slightly larger across multiple runs.

What we can improve on:

- Testing and validation accuracy is higher than training accuracy.
- Train more epochs using more data.
- Expand the scope to perform image segmentation on hemorrhages.
- Active Contour segmentation (supervised)
- Simple Linear Iterative Clustering (unsupervised)