Previous Questions

2025年6月27日

1 环境配置

见 1.py

2 向量与矩阵

2.1 旋转矩阵

代码实现部分见 2-1.py 相当于将向量 v 顺时针旋转 θ

2.2 矩阵指数

代码实现部分见 2-2.py

考虑泰勒展开 $e^{i\theta \hat{P}}$, 易计算验证泡利矩阵的平方都为 I, 即 $\hat{P}^2 = I$ 。故

$$e^{i\theta\hat{P}} = \sum_{k=0}^{+\infty} \frac{i^k \theta^k \hat{P}^k}{k!} = \sum_{k=0}^{+\infty} (-1)^k \frac{\theta^{2k}}{(2k)!} I + \sum_{k=0}^{+\infty} (-1)^k i \frac{\theta^{2k+1}}{(2k+1)!} \hat{P}$$

$$= \cos\theta I + i \sin\theta \hat{P}$$
(1)

只需 $\hat{P}^2 = I$ 即可。

2 向量与矩阵 2

2.3 矩阵关于向量的期望

代码实现部分见 2-3.pv

事实上泡利矩阵还满足厄米性质, 即 $\hat{P}^{\dagger} = \hat{P}$, 故

$$v^{\dagger} \hat{Q} v = (1,0)(\cos \theta/2I + i \sin \theta/2\hat{P})^{\dagger} \hat{Q}(\cos \theta/2I + i \sin \theta/2\hat{P})(1,0)^{T}$$

$$= (1,0)(\cos \theta/2\hat{Q} - i \sin \theta/2\hat{P}\hat{Q})(\cos \theta/2I + i \sin \theta/2\hat{P})(1,0)^{T}$$

$$= (1,0)(\cos^{2} \theta/2\hat{Q} + \sin^{2} \theta/2\hat{P}\hat{Q}\hat{P} + i \sin \theta/2\cos \theta/2(\hat{Q}\hat{P} - \hat{P}\hat{Q}))(1,0)^{T}$$
(2)

有两种情况:

1.
$$\hat{P} = \hat{Q}$$
, $\mathbb{M} \hat{P} \hat{Q} \hat{P} = \hat{Q}$, $\hat{P} \hat{Q} = \hat{Q} \hat{P}$.

2.
$$\hat{P}\hat{Q} = \pm i\hat{R}$$
,则 $\hat{P}\hat{Q}\hat{P} = \pm i\hat{R}\hat{P} = -\hat{Q}$, $\hat{P}\hat{Q} - \hat{Q}\hat{P} = \pm 2i\hat{R}$ (\hat{R} 也为泡利矩阵)

故

$$v^{\dagger} \hat{Q} v = \begin{cases} \hat{Q}_{1,1} & (\hat{P} = \hat{Q}) \\ \cos \theta \hat{Q}_{1,1} \pm \sin \theta \hat{R}_{1,1} & (\hat{P} \neq \hat{Q}) \end{cases}$$
(3)

总结一下可得

$$v^{\dagger} \hat{Q} v = \begin{cases} 1 & (\hat{P} = \hat{Q} = \sigma_z) \\ \cos \theta & (\hat{P} = \sigma_{x,y}, \hat{Q} = \sigma_z) \\ \sin \theta & (\hat{P} = \sigma_x, \hat{Q} = \sigma_y) \\ -\sin \theta & (\hat{P} = \sigma_y, \hat{Q} = \sigma_x) \\ 0 & (otherwise.) \end{cases}$$
(4)

2.4 张量积

代码实现部分见 2-4.py

2.5 狄拉克符号

2.5.1 旋转矩阵

$$|v\rangle = |0\rangle, |v'\rangle = R(\theta)|v\rangle$$

2 向量与矩阵 3

- 2.5.2 矩阵指数
- 2.5.3 矩阵关于向量的期望

$$|v_0\rangle = |0\rangle, |v\rangle = e^{i\frac{\theta}{2}\hat{P}}|v_0\rangle$$

 $E = \langle v|\hat{Q}|v\rangle$

2.5.4 张量积

$$E = \langle 0^n | H | 0^n \rangle$$

2.6 使用Tensorsircuit后端