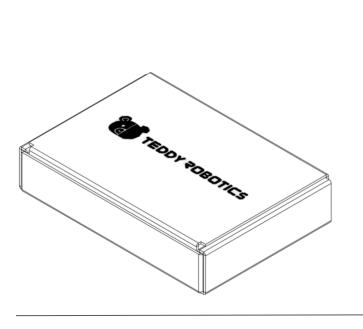
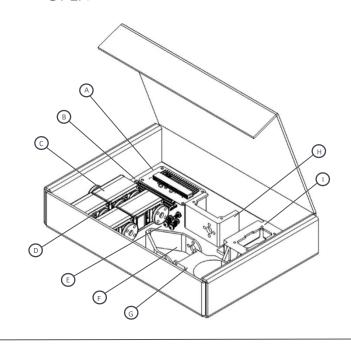


ASSEMBLY GUIDE

CLOSE



OPEN



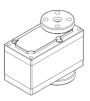
- PART LIST
- A. Commerson



B. Motor Cables x4



C. Smart Servo Motors X 4



D. Motor Screw (M2X11 or #1x3/8" Sheetmetal screw, 8 per motor)



E. Machine Screw (M3x6, 8 per motor)



F. SAMPLE BRACKET1 X 1



G. SAMPLE BRACKET2 x 2



H. SAMPLE BRACKET3 X 1



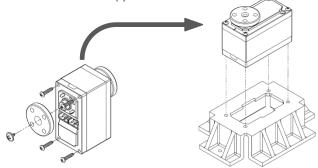
I. SAMPLE BRACKET4 X 1



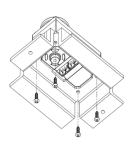
Note: Brackets are 3d printed. Kit meant for makers to utilize motors for their own convenience

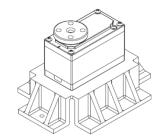


- MOTOR AND SAMPLE BRACKET ASSEMBLY
- Unscrew Bearing hub out of one of the motors, all Motors Screws (D) as shown below. Then, Align Motor to Sample Bracket4 (I).

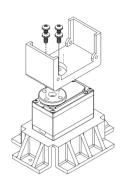




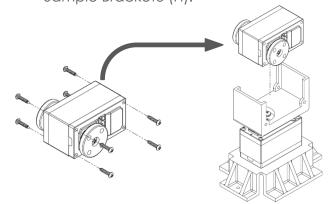




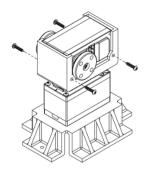
3. Use Machine Screws (E) to attach Sample Bracket3 (H) to Motor (C).



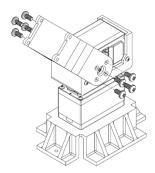
4. Unscrew Motors Screws (D) from one of the Motor (C), the Insert motor into Sample Bracket3 (H).



5. Use Motor Screws (D) to attach Motor (C) to Sample Bracket3 (H).



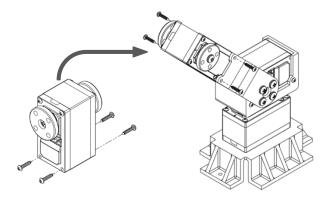
6. Use Sample Bracket2 (G) and attach it to Motor (C) by using Machine Screws (E).



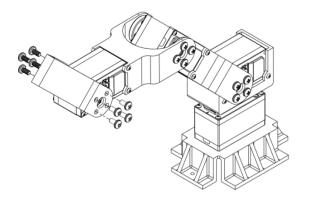
Note: Brackets are 3d printed. Kit meant for makers to utilize motors for their own convenience



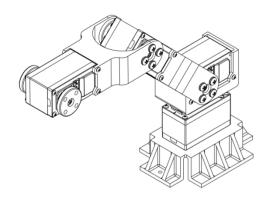
- MOTOR AND SAMPLE BRACKET ASSEMBLY
- 7. Unscrew bottom Motor Screws (D), and attach Motor (C) to Sample Bracket2 (G)



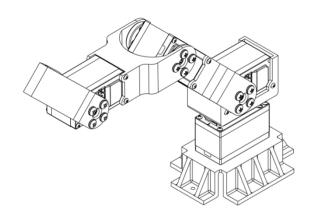
9. Use Sample Bracket (F) to attach to Motor (C)



8. Repeat Step 6 & 7 to Attach Sample Bracket3 (G) to Motor(C).



10. Final assembly completed

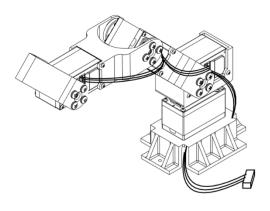


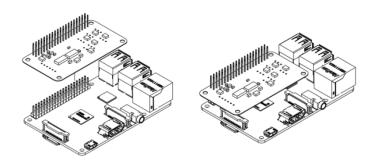
Note: Brackets are 3d printed. Kit meant for makers to utilize motors for their own convenience



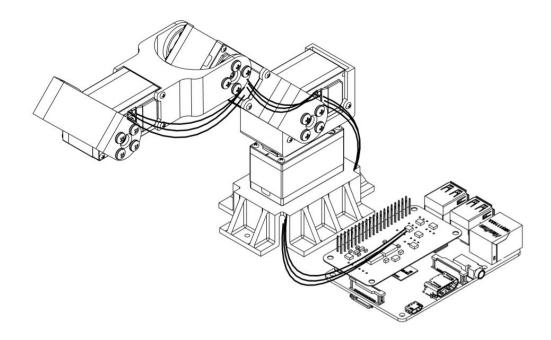
- MOTOR, COMMERSON AND RASPBERRY PI WIRING
- 1. Use Cables (B) to daisy Chain Motors.







3. Finally connect Motor Cable(B) to Commerson (A)



Note: Daisy Chain not necessary. Smart servo motors can be connected to Commerson separately