

# A SEMILINEAR PARTIAL DIFFERENTIAL EQUATION INDUCED BY HERMITIAN YANG-MILLS METRICS \*

Yuxuan LI

*School of Mathematical Sciences, Tongji University, Shanghai, 200092, China*

*E-mail: 1653454@tongji.edu.cn*

Wubin ZHOU

*School of Mathematical Sciences, Tongji University, Shanghai, 200092, China*

*E-mail: wubzhou@tongji.edu.cn*

**Abstract** This paper will discuss a class of semilinear partial differential equations induced by studying the limiting behaviour of Hermitian Yang-Mills metrics. We will study the radial symmetry of the  $C^2$  global solution of this equation in  $\mathbb{R}^2$  and the existence of  $C^{2,\alpha}$  solution of the Dirichlet boundary value problem in any bounded domain.

**Key words** Hermitian Yang-Mills metric;  $C^k$ -estimates; Boundary value problems

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## 1 Introduction

Let  $X$  be a Kähler manifold with a family of Kähler metrics  $\omega_\varepsilon$ , and let  $V$  be a slope stable holomorphic vector bundle over  $X$ . According to the Donaldson-Uhlenbeck-Yau theorem [5],  $V$  admits unique fully irreducible Hermitian-Yang-Mills metrics  $H_\varepsilon$  associated to each  $\omega_\varepsilon$ . Similar to study the limiting behaviour Ricci flat metrics, Professor Jixiang Fu [2] studied the limiting behaviour of Hermitian Yang-Mills metrics  $H_\varepsilon$  when  $\omega_\varepsilon$  goes to a large Kähler metric limit. A critical step in [2] is to explicitly construct a family of Hermitian Yang-Mills metrics by solving the following semilinear partial differential equation in unit ball  $B_1(0)$  of  $\mathbb{R}^2$

$$\begin{cases} \Delta u = \varepsilon^{-2} (e^u - (x^2 + y^2) e^{-u}) & \text{in } B_1(0), \\ u = 0 & \text{on } \partial B_1(0). \end{cases} \quad (1.1)$$

Here  $\varepsilon$  is a constant and  $(x, y)$  is the coordinate of  $\mathbb{R}^2$ . By the symmetry of the domain  $B_1(0)$  and using reference [3], Jixiang Fu proved the equation (1.1) has a unique radially symmetric solution. However, this method can not be applied to non-symmetric domain  $\Omega$  in  $\mathbb{R}^2$ .

In this paper, we first study the following equation defined in a bounded connected domain  $\Omega \subset \mathbb{R}^2$  with Dirichlet boundary value

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$$\begin{cases} \Delta u = \varepsilon^{-2} (e^u - (x^2 + y^2) e^{-u}) & \text{in } \Omega, \\ u = g & \text{on } \partial\Omega. \end{cases} \quad (1.2)$$

For existence and uniqueness of the solution of (1.2), we have the following theorem

**Theorem 1.1** If  $\partial\Omega$  is  $C^{2,\alpha}$  and  $g \in C^{2,\alpha}(\partial\Omega)$ , there is a unique solution  $u \in C^{2,\alpha}(\Omega)$  to equation (1.2). Especially if  $\partial\Omega$  and  $g$  is smooth, the solution  $u$  is smooth.

This theorem will give a Hermitian Yang-Mills metric on a certain Kähler manifold given by [2]. On the other hand, the equation (1.1) can be defined in whole space  $\mathbb{R}^2$ . It is natural to explore whether the global solution of (1.1) is radially symmetric. The symmetry of global solutions of some semilinear equations has been investigated in [1] and [3] under the assumption  $u(x, y)$  decays to zero at a certain rate as  $r^2 = x^2 + y^2 \rightarrow +\infty$ . But they do not fit the equation (1.1) since one can see the global solution  $u$  is not bounded. Similar to [1, 3], by using moving plane method and maximum principle, we get the following theorem

**Theorem 1.2** For any given constant  $c$ , if the global  $C^2$  solution  $u$  of

$$\Delta u = \varepsilon^{-2} (e^u - (x^2 + y^2) e^{-u}) \quad \text{in } \mathbb{R}^2 \quad (1.3)$$

satisfies

$$u(s) - u(t) \rightarrow 0 \quad \text{as } |s|, |t| \rightarrow \infty \quad \text{and} \quad |s| - |t| = c,$$

then  $u$  is radially symmetric and  $\frac{\partial u}{\partial r} \geq 0$ . Here  $s, t \in \mathbb{R}^2$ .

One may observe  $\frac{1}{2} \log(x^2 + y^2)$  is a singular solution to the equation (1.3) and also satisfies  $\log(|s|) - \log(|t|) \rightarrow 0$  as  $|t| - |s| = c$  and  $|s|, |t| \rightarrow \infty$ , so the assumption of Theorem 1.2 is natural and reasonable.

The next part of this paper will give the detailed proof of Theorem 1.1 and Theorem 1.2.

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## 2 Existence of solution of the Dirichlet boundary value problem

In this section we will prove Theorem 1.1. One can use Chapter 14 in [6] to show the existence of the equation 1.2 by using variational method. Here we take Leray-Schauder existence theorem to prove it.

Let  $\Omega$  be a  $C^{2,\alpha}$  bounded domain in  $\mathbb{R}^2$  and  $g \in C^{2,\alpha}(\partial\Omega)$  with  $\alpha \in (0, 1)$ . We first have a  $C^0(\Omega)$  estimate.

**Lemma 2.1** Let  $\Phi$  be the  $C^{2,\alpha}$  solution of Dirichlet boundary value problem

$$\begin{cases} \Delta \Phi = \varepsilon^{-2} (1 - (x^2 + y^2)) & \text{in } \Omega, \\ \Phi = g & \text{on } \partial\Omega. \end{cases} \quad (2.1)$$

Then a solution  $u$  to (1.2) satisfies

$$\sup_{\bar{\Omega}} |u| \leq \sup_{\bar{\Omega}} 2|\Phi|. \quad (2.2)$$

**Proof** The existence of  $\Phi$  is from Green formula (one can see [4]). Consider  $u - \Phi$  for  $u > 0$ . Note that on  $\mathcal{O} = \{x \in \Omega : u(x) > 0\}$

$$\Delta(u - \Phi) = \varepsilon^{-2} (e^u - 1 + (x^2 + y^2) (1 - e^{-u})) > 0.$$

By maximum principle, we have

$$\sup_{\mathcal{O}}(u - \Phi) = \sup_{\partial\mathcal{O}}(u - \Phi) \leq \sup_{\Omega}\{-\Phi, 0\} \leq \sup_{\Omega}|\Phi|.$$

It follows

$$\sup_{\Omega} u \leq \sup_{\Omega} 2|\Phi|. \quad (2.3)$$

Similarly, if  $u < 0$ ,

$$\Delta(u - \Phi) = \varepsilon^{-2}(e^u - 1 + (x^2 + y^2)(1 - e^{-u})) < 0.$$

Hence we obtain on  $\mathcal{O}^- = \{x \in \Omega : u(x) < 0\}$

$$\sup_{\mathcal{O}^-}(\Phi - u) = \sup_{\partial\mathcal{O}^-}(\Phi - u) \leq \sup_{\Omega}\{\Phi, 0\} \leq \sup_{\Omega}|\Phi|$$

which implies

$$\sup_{\Omega} -u \leq \sup_{\Omega} 2|\Phi|. \quad (2.4)$$

Therefore from (2.3) and (2.4) one can get the estimate (2.2).

Second, we give the gradient estimate of  $u$ .

**Lemma 2.2** Suppose  $u \in C^2(\Omega)$  satisfies the equation (1.2) in  $\Omega$ , then there is positive constant  $C$  depend only on  $\Omega$  and  $g$  such that

$$\sup_{\Omega} |\nabla u| \leq C. \quad (2.5)$$

**Proof** From the equation (1.2) and by standard regularity, one can see  $u$  is  $C^4$  since  $u$  and  $g$  are  $C^2$ . Then we have

$$\begin{aligned} \Delta|\nabla u|^2 &= \langle \nabla \Delta u, \nabla u \rangle + |\nabla^2 u|^2 \\ &= \varepsilon^{-2}(e^u + r^2 e^{-u})|\nabla u|^2 - \varepsilon^{-2}e^{-u} \langle \nabla r^2, \nabla u \rangle + |\nabla^2 u|^2. \end{aligned} \quad (2.6)$$

If  $|\nabla u|^2$  attains its maximum on the boundary  $\partial\Omega$ , we have  $\sup |\nabla u| = \sup |\nabla g|$  which leads to (2.5). Now assume  $|\nabla u|^2$  attains its maximum at  $z_0 \in \Omega$ . Then from (2.6), at the point  $z_0$  we have

$$\varepsilon^{-2}(e^u + r^2 e^{-u})|\nabla u|^2 - \varepsilon^{-2}e^{-u} \langle \nabla r^2, \nabla u \rangle \leq 0$$

or

$$(e^u + r^2 e^{-u})|\nabla u|^2 \leq e^{-u}|\nabla r^2||\nabla u|.$$

Since  $|u|$  is bounded from Lemma 2.1, there is a constant  $C$  dependent on  $\Omega$  and  $g$  such that

$$|\nabla u|(z_0) \leq C.$$

Then we finish the proof.

Now we give the proof of Theorem 1.1.

**Proof** Let  $\sigma \in [0, 1]$ , we claim if  $u_{\sigma} \in C^{2,\alpha}(\Omega)$  is the solution of boundary value problem

$$\begin{cases} \Delta u = \sigma \varepsilon^{-2} (e^u - (x^2 + y^2) e^{-u}) & \text{in } \Omega, \\ u = \sigma g & \text{on } \partial\Omega, \end{cases} \quad (2.7)$$

then there is a constant  $M$  independent of  $u_\sigma$  and  $\sigma$  such that

$$\|u_\sigma\|_{C^{1,\alpha}(\bar{\Omega})} \leq M. \quad (2.8)$$

Then one can use the Leray-Schauder existence theorem (see Theorem 6.23 in [4]) to show the Dirichlet problem (1.2) is solvable in  $C^{2,\alpha}(\bar{\Omega})$ .

In fact, one can see  $\sigma\Phi$  solves

$$\begin{cases} \Delta\Phi = \sigma\varepsilon^{-2}(1 - (x^2 + y^2)) & \text{in } \Omega, \\ \Phi = \sigma g & \text{on } \partial\Omega. \end{cases} \quad (2.9)$$

Then from Lemma 2.1, we have

$$\|u_\sigma\|_{C^0(\bar{\Omega})} \leq \sup_{\Omega} 2|\sigma\Phi| \leq \sup_{\Omega} 2|\Phi|. \quad (2.10)$$

Therefore, from (2.7), there is a constant  $C$  independent on  $\sigma$  and  $u_\sigma$ , such that

$$|\Delta u| \leq C.$$

This means  $|\nabla^2 u|$  is also bounded. From Lemma 2.2 and using interpolation inequality in Hölder space, there is a constant  $M$  independent on  $u$  and  $\sigma$  such that (2.8) is satisfied.

In the end, by standard bootstrap argument of the regularity we have  $u$  is smooth if  $\Omega$  and  $g$  are smooth. This finishes the proof.

### 3 Radial symmetry of the global $C^2$ solution of the equation in $\mathbb{R}^2$

In this section we will prove Theorem 1.2. In [3] and [1], the radially symmetry of the  $C^2$  positive solutions of the following second order elliptic equation is studied

$$\Delta u + f(u) = 0 \text{ in } \mathbb{R}^n$$

under the assumption on  $f$  and  $u$ . For example, they assumed  $u(x) \rightarrow 0$  as  $x \rightarrow \infty$ . Obviously, our equation (1.2) is different from this type since  $e^u - r^2 e^{-u}$  has the term  $r^2$ . Also we cannot assume  $|u| \rightarrow 0$  as  $r \rightarrow +\infty$ . In fact, it will lead  $\Delta u \rightarrow -\infty$  and then  $u$  is unbounded. It contradicts the hypothesis. In this paper, we assume for any finite constant  $c$

$$u(s) - u(t) \rightarrow 0 \quad \text{and} \quad |s| - |t| = c, \quad \text{as} \quad |s|, |t| \rightarrow \infty \quad (3.1)$$

where  $s, t \in \mathbb{R}^2$ .

**Proof Proof of Theorem 1.2** Since the partial differential equation (1.3) is rotationally symmetric, we only have to prove the symmetry about a line across origin. Here we choose the line  $y$  axis. Define

$$\Sigma(\lambda) = \{(x, y) \in \mathbb{R}^2 \mid x < \lambda\}$$

and let

$$v = u(2\lambda - x, y), \quad x^\lambda = 2\lambda - x.$$

In  $\Sigma(\lambda)$  we define

$$w = v(x) - u(x).$$

When  $\lambda = 0$  and  $x \in \Sigma(\lambda)$ , we have  $x + x^\lambda = 0$  and  $x < x^\lambda$ . Then

$$x^2 = (x^\lambda)^2$$

and

$$\Delta v - \varepsilon^{-2} (e^v - ((x^\lambda)^2 + y^2) e^{-v}) = \Delta v - \varepsilon^{-2} (e^v - (x^2 + y^2) e^{-v}) = 0. \quad (3.2)$$

By the mean value theorem, we have

$$\Delta w + \bar{c}w = 0$$

where

$$\bar{c} = - \int_0^1 \varepsilon^{-2} (e^{u+tw} + r^2 e^{-u-wt}) dt < 0.$$

Then from the assumption (3.1) and  $w(0, 0) = 0$  on the  $y$  axis, we have by maximum principle and minimum principle

$$w = 0$$

in  $\Sigma(0)$ . That's to say the global solution of (1.3) in  $\mathbb{R}^2$  is symmetric about  $y$  axis.

In the end, assuming  $\lambda > 0$  and  $x \in \Sigma(\lambda)$ , then we have  $x + x^\lambda > 0$  and  $x < x^\lambda$ . It follows

$$x^2 < (x^\lambda)^2$$

which implies

$$\Delta v - \varepsilon^{-2} (e^v - (x^2 + y^2) e^{-v}) < 0. \quad (3.3)$$

Then by mean value theorem, in  $\Sigma(\lambda)$

$$\Delta w + \bar{c}w < 0$$

with  $c < 0$ . Using the infinite boundary condition (3.1) and  $w(\lambda, \lambda) = 0$ , we have by maximum principle, in  $\Sigma(\lambda)$

$$w \geq 0.$$

Then if  $x > 0$  and let  $x_\lambda \rightarrow x$ , we have  $\frac{\partial u}{\partial x} \geq 0$ . Since  $u$  is radially symmetric and from

$$\frac{\partial u}{\partial x} = \frac{\partial u}{\partial r} \frac{\partial r}{\partial x} = \frac{\partial u}{\partial r} \frac{x}{r}$$

it follows  $\frac{\partial u}{\partial r} \geq 0$  and we finish the proof.

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