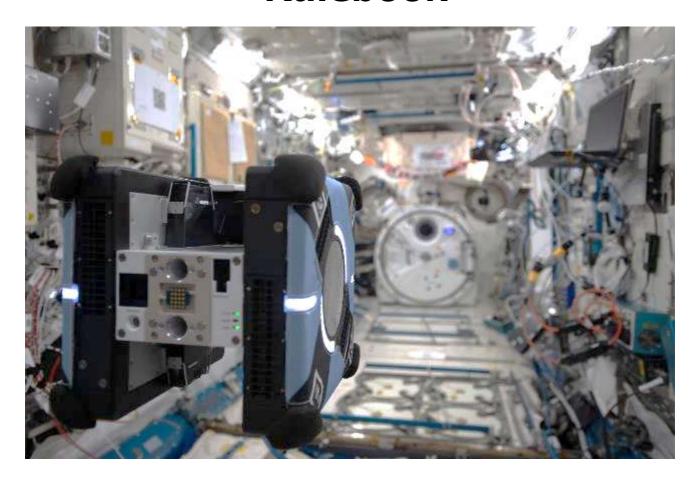


The 6th Kibo Robot Programming Challenge

Rulebook



Version 1.1 (Revision date: May 27, 2025)

Japan Aerospace Exploration Agency (JAXA)



Revision History

Revision history is listed below.

| Revision Date | Version | Paragraph | Revision Location |
|---------------|---------|---------------------------------------|---------------------------------|
| April 1, 2025 | 1.0 | All | - |
| May 27, 2025 | 1.1 | 2.3 ~ 2.5 Change index numbers to 2.2 | |
| | | 2.2.5-1 | Translate Japanese into English |
| | | 2.4.1 Delete the last sentence | |
| | | 2.4.2 Add 2.4.2 | |
| | | Appendix 1 | Translate Japanese into English |



Table of Contents

| 1. Introduction | 1 |
|--|----|
| 2. Preliminary Round | |
| 2.1. Preliminary Round Period | |
| 2.2.1. Game Flow | |
| | |
| 2.2.2. Preconditions | |
| 2.2.3. Objects | 7 |
| 2.2.4. Mission Completion Report | 11 |
| 2.2.5. Keep-In-Zone (KIZ) & Oasis Zone | 11 |
| 2.2.6. 10 Automatic Executions per APK | 15 |
| 2.3. Scoring | 16 |
| 2.3.1. Factors | |
| 2.4. Participation in the Preliminary Round | |
| 2.4.1. How to Participate in the Preliminary Round | 18 |
| 2.4.2. How to submit APK | 18 |
| 3. Final Round | |
| 3.1. Final Round Schedule | |
| 3.2.1. Game Flow | |
| 3.2.2. Preconditions | 23 |
| 3.2.3. Objects | 23 |
| 3.2.4. Mission Complete Report | 23 |
| 3.2.5. Keep-In-Zone (KIZ) and Oasis Zone | 23 |
| 3.2.6. 1 Run per APK | 23 |
| 3.2.7. 5 Minute Time Limit | 24 |
| 3.2.8. APK Operation on the Day of the Final Round | 24 |
| 3.2.9. Final Round Run Order | 25 |
| 3.3. Scoring | 27 |
| 3.3.1. Factors | 27 |
| 3.3.2. Judging | 27 |
| 3.4. Participating in the Final Round | |
| 3.4.1. Submit APK and Source Code | 30 |
| 3.5. Organizing the Event | 30 |

| T 7 | • | - 1 | -1 |
|------------|-------|-----|-----|
| V/ (A) | ∙sion | ۱ I | - 1 |
| | | | |



| Annendiy 1 | | • |
|------------|-------|------|
| Appendix 1 | ••••• | |
| | | |



1. Introduction

The 6th Kibo Robot Programming Challenge (Kibo-RPC) is here. Create the best program to see if you can win.

A preliminary round will be held in each country/region to select their representatives. Participants compete using programs they have developed beforehand using JAXA's simulation environment. Game rules and scoring are basically the same in each country/region, although some have adopted their own evaluation criteria, so be sure to check your local Kibo-RPC website for details. Information regarding venue and dates will be made available by the point of contact (POC) in each country/region. This Rulebook contains general rules for all participants.

The winning teams from each preliminary round get to compete to be the best in the world in the final round where they will program and operate an Astrobee free-flying robot in the Japanese Experiment Module KIBO, which is part of the International Space Station (ISS).



2. Preliminary Round

2.1. Preliminary Round Period

The preliminary rounds will be held separately in each country/region during the period, so please participate in the preliminary round held in the country/region where you are registered. The preliminary round information for each country/region can be found on the official Kibo-RPC website (https://jaxa.krpc.jp/). For more information, please contact your country/region POC.

Question Acceptance Deadline*1: June 19, 2025, 12:00 (JST)

APK Submission Period: May 27-June 19, 2025, 23:59 (JST)

Preliminary Round Period: June 20 to July 6, 2025

*1 Any questions submitted after this date will receive a delayed response.

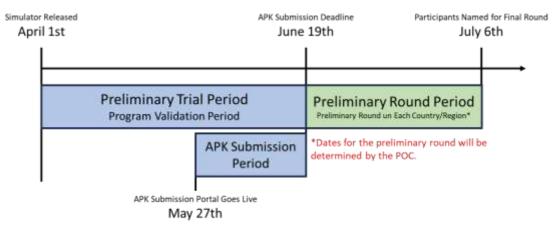


Figure 2.1-1 Preliminary Round Period



2.2. Game Rules

2.2.1. Game Flow

To control NASA's Astrobee in the Preliminary round, please create a program to complete the following game using JAXA's web simulation environment.

Within a time limit, Astrobee will be moved from the starting position (dock station) to a candidate location in Kibo where the treasure is hidden, and all images will be read. Astrobee will then be moved to the astronauts' site, where it will read the images of the treasure and landmarks in the astronauts' possession to provide clues to locate the real treasure. After reading the images, the player moves to the location where the real treasure is hidden, takes a picture of the treasure, flashes the Signal Lights to signal that he/she has found the treasure, and tells the astronaut where the treasure is hidden to complete the mission.

- 1. Start from the docking station.
- 2. After starting, Astrobee will patrol several candidate sites aboard Kibo where treasures are hidden.
- 3. Each team may choose a route through the Oasis Zones*1, where they receive points for passing through, and report what they find at each candidate location for hidden treasures.
- 4. Once all Astrobee has visited all of the sites, go to the astronaut and read the im-age of the real treasure and its nearby landmark. This will reveal the identity of the real treasure.
- 5. Go to the real treasure and take a picture.
- 6. After taking the photo, activate the Signal Lights to inform the astronaut of the treasure's location, and the mission is complete.
- 7. *1Oasis Zone: Points will be added as long as Astrobee is moving through this area.

^{*1}Oasis Zone... Points will be added as long as Astrobee is moving through this area.



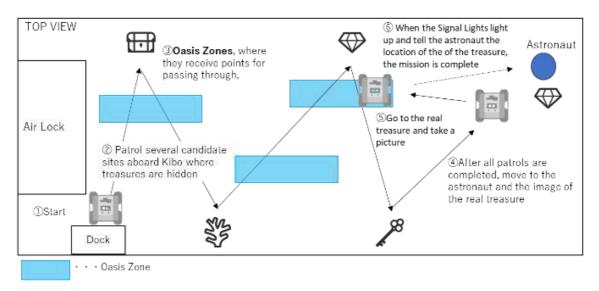


Figure 2.2.1-1 Game Flow



2.2.2. Preconditions

Table 2.2.2-1 Preconditions for Preliminary Round

| # | Content |
|---|---|
| 1 | The starting position is the Dock Station, and the timer starts once Astrobee undocks. |
| 2 | There are 11 types of Lost Item images placed in each area. Breakdown: (3 Tresure Items, 8 Landmark Items) Prepare an AR tag on the same plane as the printed surface of Lost Item. The search area for Lost Item (hereinafter referred to as "Area") is limited to four locations. The area is specified as a plane, and one Lost Item is placed somewhere within the Area. Lost Item placement is random. |
| 3 | The Target Item is randomly selected from one of the Tresure Items in the game. |
| 4 | The following information will be presented to participants in advance. For more information on AR tags and Lost Item, please refer to section 2.2.3. 1. Orientation of the position of the starting point (StartPoint) 2. Report position to an astronaut (RoundingCompletionPoint) 3. Location and size of each area 4. Total number of Areas 5. Types of images to be placed and examples of difficulty levels 6. Location and size of the oasis zones 7. Parameters for a given angle and distance |
| 5 | Oasis Zones are set up along the route, where points are added according to the time spent in the zone. This oasis zone is given as a precondition. Please see section 2.2.5 for details. *Depending on the team's strategy, Astrobee does not have to go through the Oasis Zone. |



Table 2.2.2-2 Coordinates (StartPoint and RoundingCompletionPoint to the astronaut)

| Point | Coordinates | | | Orientation | | | |
|-----------|-------------|---------|--------|-------------|---|-------|-------|
| Polit | Х | у | Z | Х | у | Z | W |
| Start | 9.815 | -9.806 | 4.293 | 1 | 0 | 0 | 0 |
| Astronaut | 11.143 | -6.7607 | 4.9654 | 0 | 0 | 0.707 | 0.707 |

Table 2.2.2-3 Coordinate Information (Area)

| | | x_min | y_min | z_min | x_max | y_max | z_max |
|-------|---|----------|--------|---------|----------|--------|---------|
| | 1 | 10.42 | -10.58 | 4.82 | 11.48 | -10.58 | 5.57 |
| Area* | 2 | 10.3 | -9.25 | 3.76203 | 11.55 | -8.5 | 3.76203 |
| Area | 3 | 10.3 | -8.4 | 3.76093 | 11.55 | -7.45 | 3.76093 |
| | 4 | 9.866984 | -7.34 | 4.32 | 9.866984 | -6.365 | 5.57 |

^{*}Area is displayed as a plane.

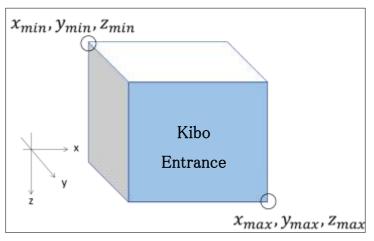


Figure 2.2.2-1 Definition of a Coordinate

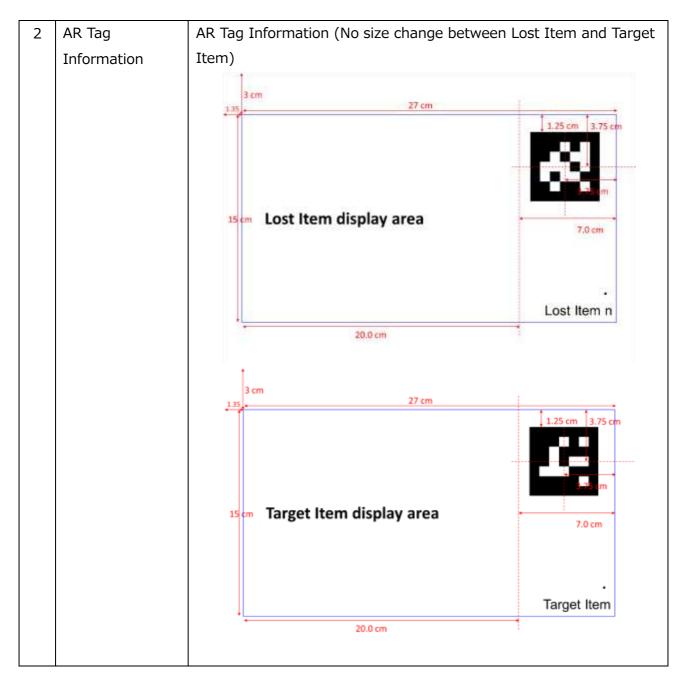


2.2.3. Objects

Table 2.2.3-1 Objects for Preliminary Round

| # | Object Name | Process | | | | | | |
|---|----------------|---|-------------------|---------|--|--|--|--|
| 1 | Lost Item List | Tresure Item (3 types) | | | | | | |
| | | crystal | diamond | emerald | | | | |
| | | | \Leftrightarrow | | | | | |
| | | Landmark Item (8 type | es) | | | | | |
| | | coin | compass | coral | | | | |
| | | | | SAS SAS | | | | |
| | | fossil | key | letter | | | | |
| | | 6 | 1 88 | | | | | |
| | | shell | treasure_box | | | | | |
| | | | | | | | | |
| | | *The size of the Lost Item placed in the Area changes depending | | | | | | |
| | | on the image difficulty | level. | | | | | |







| 3 | List of Lost Item |
|---|-------------------|
| | image levels |
| | placed in each |
| | area |
| | (Landmark |
| | Items only) |

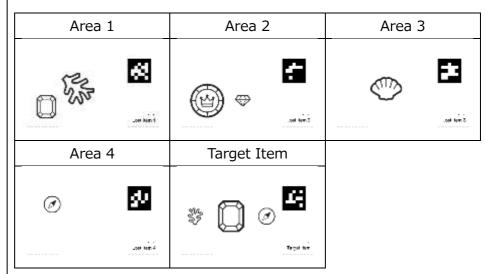
| Level | Image Examples | | | | | | |
|-------|----------------------------------|--|--|--|--|--|--|
| 1 | Loor her 1 Loor her 1 Loor her 1 | | | | | | |
| 2 | | | | | | | |
| 3 | | | | | | | |
| 4 | | | | | | | |



| List of Lost Item | | | | | | | |
|--|---|--|--|--|--|--|--|
| | Level | Image Examples | | | | | |
| _ | 1 | 1 Level 1 image of Lost Items including Tresure Item are | | | | | |
| area | | not available. | | | | | |
| (When Landmark Items and Tresure Items are | 2 | | | | | | |
| displayed) | 3 | | | | | | |
| | | | | | | | |
| | 4 | | | | | | |
| | *Levels a | are subject to change based on all participants. | | | | | |
| Example of | | | | | | | |
| | | | | | | | |
| display | | | | | | | |
| | | Target Item | | | | | |
| | *Levels are subject to change based on all participants. | | | | | | |
| | *Target Item displays two types of items: Tresure Item and | | | | | | |
| | Landmar | | | | | | |
| | (When Landmark Items and Tresure Items are displayed) Example of Target Item | image levels placed in each area (When Landmark Items and Tresure Items are displayed) *Level *Level **Levels are **Target Item display **Levels are **Target Item * | | | | | |



6 Examples of images displayed in each Area and as Target Item



^{*}The level of Lost Item placed depends on the difficulty level of the simulator.

2.2.4. Mission Completion Report

To complete the mission, you need to create a report using the QR code you scan. Please see takeTargetItemSnapshot() in chapter 7 of the Programming Manual for the API to use in the Mission Completion Report.

2.2.5. Keep-In-Zone (KIZ) & Oasis Zone

Astrobees may move within Keep-In-Zones (KIZ), which means basically within the walls of Kibo. These are the Astrobee's pre-set boundaries, and if the destination set is outside a KIZ, the command will be rejected. In other words, it is necessary to program the Astrobee to move only within the KIZs.

Oasis Zones are areas within the KIZ where Astrobee will be scored based on the time it spends in that zone. 6th Kibo-RPC will add Oasis Zones, which will require participants to be more strategic in designing Astrobee's travel routes. (Figure 2.2.5-1, 2.2.5-2, 2.2.5-3, Table 2.2.5-1)

^{*}One Tresure Item and two Landmark Items are placed in the Target Item. One of the Landmark Items is placed with the Tresure Item in the Area, but the other is different.



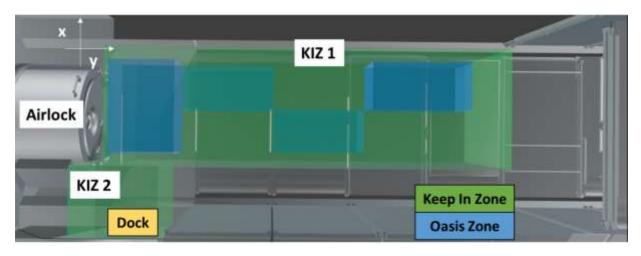


Figure 2.2.5-1 KIZ and Oasis Zone for the Preliminary Round (Top View)

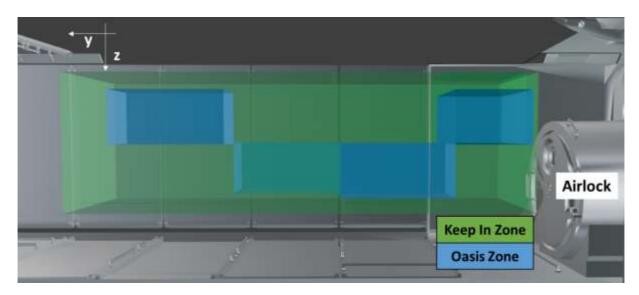


Figure 2.2.5-2 KIZ and Oasis Zone for the Preliminary Round (Side View)



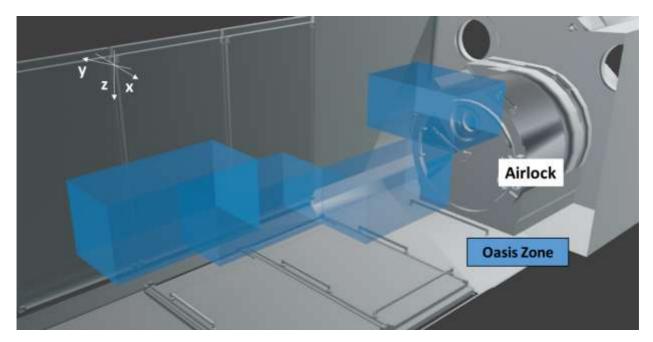


Figure 2.2.5-3 Oasis Zone for the Preliminary Round (Diagonal View)

Table 2.2.5-1 shows the coordinates of KOZ and KIZ. Figure 2.2.5-4 shows the definition of coordinates (x_min, y_min, z_min) and (x_max, y_maxm z_max).

Table 2.2.5-1 Location Coordinates of Obstacles

| | | x_min | y_min | z_min | x_max | y_max | z_max |
|------------|--------------|--------|-------|-------|--------|-------|-------|
| | Oasis Zone 1 | 10.425 | -10.2 | 4.445 | 11.425 | -9.5 | 4.945 |
| Oasis Zone | Oasis Zone 2 | 10.925 | -9.5 | 4.945 | 11.425 | -8.45 | 5.445 |
| Oasis Zone | Oasis Zone 3 | 10.425 | -8.45 | 4.945 | 10.975 | -7.4 | 5.445 |
| | Oasis Zone 4 | 10.925 | -7.4 | 4.425 | 11.425 | -6.35 | 4.945 |
| K17 | KIZ 1 | 10.3 | -10.2 | 4.32 | 11.55 | -6.0 | 5.57 |
| KIZ | KIZ 2 | 9.5 | -10.5 | 4.02 | 10.5 | -9.6 | 4.8 |

^{*}The origin of the coordinate axis is set outside of Kibo.



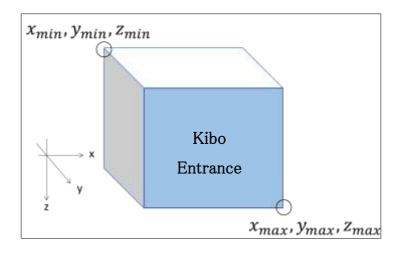


Figure 2.2.5-4 Definition of Coordinates



2.2.6. 10 Automatic Executions per APK

In the preliminary round, each Android Application Package (APK) will be automatically executed 10 times and will include random elements to make it fair for everyone. The image generation patterns, and random elements will be different for every run. Therefore, rankings will be determined using the average value instead.

This allows all participants to compete on the same terms, regardless of whether their results happen to be good or bad. Please see Section 2.3 for details regarding scoring criteria.

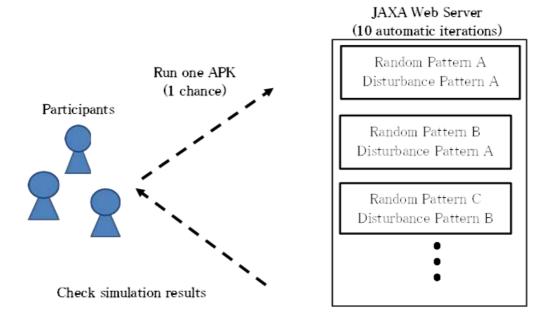


Figure 2.2.6-1 10 Runs



2.3. Scoring

2.3.1. Factors

Your team's score will be calculated based on the following factors

Table 2.3.1-1 Scoring Factors for Preliminary Round

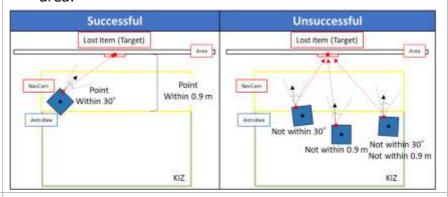
| # | Criteria | Details | |
|---|---|--|--|
| 1 | Matching of Area and Item | Points will be awarded if the type and number of Lost Items randomly placed in each Area are accurately processed and recognized. Lost Item displays are divided into difficulty levels, with higher levels (more difficult image processing) resulting in higher scores. Please note that Treasure Items may be displayed along with Landmark Items, but no points are awarded for matching a Treasure Item to an Area. Successful Unsuccessful Area 1 There is a treasure box on the area 1. | |
| 2 | Reporting coordinate of the patrol's completion | Scoring is based on the arrival coordinate when the patrol's completion report is submitted. Points will be awarded if the coordinates reached are within 0.30m from the given coordinates. Successful Unsuccessful Crew Point Within 0.3 m | |



3 Photo Angle and Position of Target
Item

Scoring based on the angle of view of the camera and the coordinates when reporting the location of the Target Item. Points will be awarded when both I and II below are satisfied.

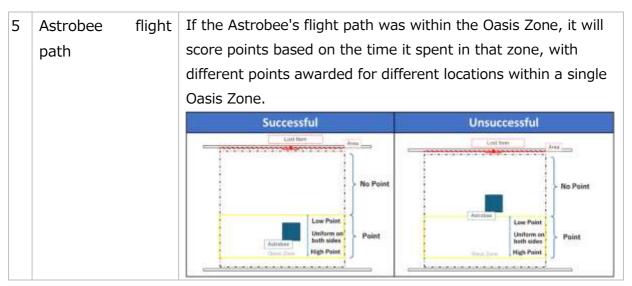
- I. Scores are based on the angle of view of the camera at the time the Target Item is reported. The angle of view is determined based on the acquired NavCam position and orientation of the Target Item, and points will be awarded if the angle of view is within the 30° angle of view.
- II. Scoring is based on the coordinates at the time the Target Item is reported. Points will be awarded if the coordinates obtained are within 0.9 m of the plane of the area.



4 Mission Time Remaining

The time limit remaining at the time of reporting the Target Item is converted into points and additional points are awarded. There is a limit to the additional points based on the remaining time. If you complete the mission with a certain amount of time remaining, you will receive a uniform amount of additional points.





^{*}Scores are calculated starting from the center of Astrobee.

2.4. Participation in the Preliminary Round

2.4.1. How to Participate in the Preliminary Round

Participants must submit APKs for the preliminary Round by the submission deadline.

Detailed submission instructions will be announced at a later date.

2.4.2. How to submit APK

Participants may participate in the Preliminary Round by writing the code and submitting it by the deadline. Even after submitting an APK once, the participants may resubmit an APK anytime they want within the deadline.



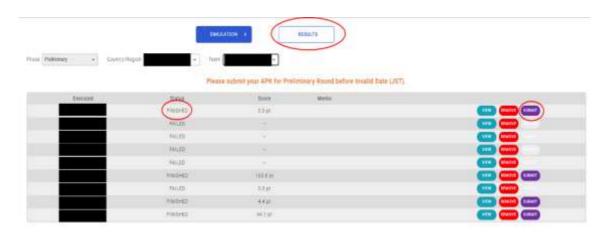


Figure 2.4.2-1 Preliminary Round

The result screen of the web simulator will change to that shown in Figure 2.4.2–1 before the preliminary round period starts. The participants need to run their APK in the "Preliminary" simulator before submitting their APK. After that, select the APK you want to submit from the "Preliminary" results list on the "RESULTS" screen and press the newly added "SUBMIT" button to submit your APK. When you press the "SUBMIT" button, it will switch to the "CANCEL" button, and you can resubmit another APK by pressing the "CANCEL" button before the deadline.

Please be aware that the team can cancel the submitted APK on the "RESULTS" page, but the team must be careful of the deadline, as the "SUBMIT" and "CANCEL" buttons will become inaccessible after the deadline.

NOTICE:

The "SUBMIT" button can only be pressed for APKs that are in "FINISHED" status on the "Preliminary" screen. If you only have an APK in "FAILED" status, the team cannot submit their APK and will not be able to participate in the preliminary round. Please make sure that the status of the APK is marked as "FINISHED" on the "Preliminary" screen.



3. Final Round

3.1. Final Round Schedule

Only representative teams can participate in the final round. Teams may refine their programs from the Preliminary Round for the APK Final Run (on ISS) and submit the APK and source code before the deadline. Please see Section 3.4 for details.

- 1) Draft source code submission deadline: Late July 2025 (JST)*1)
- 2) APK Final Run program submission deadline: Late August 2025 (JST)*2)
 - *1) JAXA will check APK source codes to ensure that they will not have a negative impact on the Astrobee and if necessary ask participants to modify the code.
 - <u>Please submit only the source code for the pre-check.</u> Submission instructions will be provided at a later date.
 - Due to the short revision period, please make arrangements in advance.

(Many revisions have occurred in previous years.)

*2) You will be required to **submit both APK and source code when submitting** the final version.

Submission instructions will be provided at a later date, but please refer to section 3.4.

Failure to submit by the deadline may result in not being able to participate in the APK Final Run, so please be sure to submit on time.



3.2. Game Rules

3.2.1. Game Flow

In the Final Round, the Astrobee on the ISS will be required to patrol each area from the starting position within a time limit^{*1} and recognize the placement of the Lost Item. Then, the Astrobee moves to the Astronaut and asks for clues to the treasure. Finally, each team will create a program to move to the vicinity of the treasure, photograph it, and then report the results. Basically, the process is the same as in the preliminary round, but Astrobee's behavior when reporting mission completion is different. There is no change in the program, but in the real environment, Astrobee will run SignalLights according to the API.

- ① Start from Dock Station.
- ② After starting, Astrobee will patrol several candidate sites aboard Kibo where treasures are hidden.
- ③ Each team may choose a route through the Oasis Zones*1, where they receive points for passing through, and report what they find at each candidate location for hidden treasures.
- ④ Once all Astrobee has visited all of the sites, go to the astronaut and read the im-age of the real treasure and its nearby landmark. This will reveal the identity of the real treasure.
- ⑤ Go to the real treasure and take a picture.
- ⑥ After taking the photo, activate the Signal Lights to inform the astronaut of the treasure's location, and the mission is complete.

 $^{^{*1}}$ Oasis Zone... Points will be added as long as Astrobee is moving through this area.



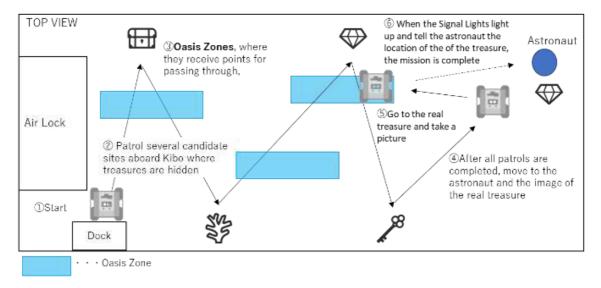


Figure 3.2.1-1 Final Round Game Flow



3.2.2. Preconditions

Table 3.2.2 Preconditions for Final Round

| # | Content |
|-----|---|
| | Conditions for start and finish positions, Area, etc. are the same as for the |
| 1-4 | Preliminary round. Please refer to section 2.2.2 for details. |
| | *Coordinate information may be revised in the future. |
| F | Some information on KIZ or Oasis Zone may change from the preliminary |
| 5 | round. We will release details as soon as they are finalized. |

Creating a program that can perform well in the actual environment on board the ISS is important as the environmental conditions in orbit differ from those of the simulation.

3.2.3. Objects

There will be no major changes from the preliminary round. Details will be released as soon as they are finalized.

3.2.4. Mission Complete Report

There will be no major changes from the preliminary round. Details will be released as soon as they are finalized.

3.2.5. Keep-In-Zone (KIZ) and Oasis Zone

Details will be released as soon as they are finalized.

3.2.6. 1 Run per APK

In the same way as in the preliminary round, teams will submit one APK, but in the final round it will only be run once on the ISS using the Astrobee. It will be impossible to redo or stop once started, so do your best because this will be a one-off chance.



If the Astrobee experiences a problem such as getting stuck, under the rules in Section 3.2.9 you will be given the opportunity for a re-run.

3.2.7. 5 Minute Time Limit

If the time limit is exceeded, the APK will automatically shut down. Please program to complete the mission within the time limit. Even if the time limit is not reached, the game is automatically considered over if the Astrobee gets stuck or loses its self-position. The system may also terminate without waiting for the time limit when it is judged that no further operation can be expected for any reason.

3.2.8. APK Operation on the Day of the Final Round

Participants may not operate their APKs on the day of the final round. Submitted APK will be checked by the JAXA/NASA technical team and preinstalled on the Astrobee. APKs are started with an execution command from ground operators.



3.2.9. Final Round Run Order

In the final round, teams will be divided into three tiers according to the results of the preliminary round and runs will be performed in that order. An example of team tier grouping is shown in Table 3.2.9.

- *Please note that changes may be made to the tiers.
- *Tier divisions are subject to change.

Table 3.2.9 Team Divisions

| Tier | Preliminary Round Score Results | | |
|----------|---------------------------------|--|--|
| 1st Tier | 1 st place | | |
| | 2 nd place | | |
| | 3 rd place | | |
| | 4 th place | | |
| 2nd Tier | 5 th place | | |
| | 6 th place | | |
| | 7 th place | | |
| | 8 th place | | |
| 3rd Tier | 9 th place | | |
| | 10 th place | | |
| | 11 th place | | |
| | 12 th place | | |

If the Astrobee gets stuck due to a problem in orbit, the team will be given another chance to run the mission again before moving on to the next tier as long as there is enough time left in the event. However, if the problem is caused by the APK created by the participant, there will be no rerun. Please note that there is limited time to conduct the competition in orbit, and teams with lower rankings in the preliminary round may not be able to run their mission on the day of the final round. For more information, please refer to Figure 3.2.9.



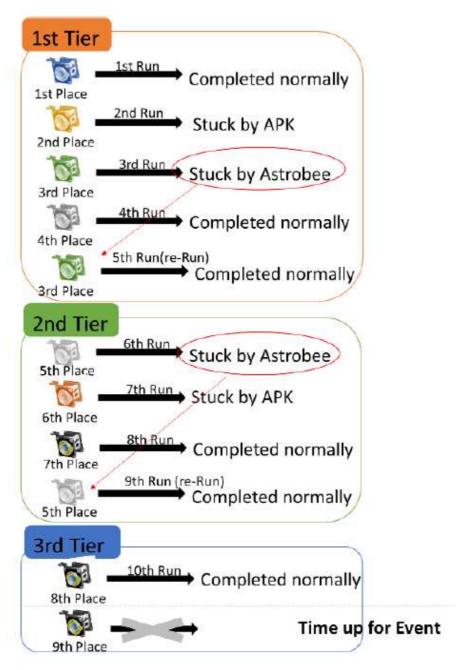


Figure 3.2.9 Example of Team Order for Final Round



3.3. Scoring

3.3.1. Factors

The scoring criteria are the same as in the qualifying round. Please refer to section 2.3.1 for details.

3.3.2. Judging

Only one run is allowed for the in-orbit final. As a result, the team's score will be the result of 1 run, not the average.

3.4. Participating in the Final Round

Participants in the final round must do the following.

(1) Change APK application ID and APK name
You must change the APK application ID and name as shown in Table 4.4
and included your country/region name. When submitting your APK,
check that you have made the changes before uploading it to the Web
Simulator. The Kibo-RPC Secretariat uses these names to identify the file
when installing and executing the APK. Please refer to Section 3.3.3 of the
Programming Manual for details on how to set the application ID, etc.



Table 4.4 Various Naming Conventions

| Country | Application ID | APK name | APK file name | Short |
|-------------|--------------------------------|-------------|-----------------|-------------|
| | | | | name |
| Australia | jp.jaxa.iss.kibo.rpc.australia | australia | australia.apk | australia |
| Bangladesh | jp.jaxa.iss.kibo.rpc.banglad | banglades | bangladesh.ap | banglades |
| | esh | h | k | h |
| Indonesia | jp.jaxa.iss.kibo.rpc.Indonesi | Indonesia | Indonesia | Indonesia |
| | a | | | |
| Japan | jp.jaxa.iss.kibo.rpc.japan | japan | japan.apk | japan |
| Malaysia | jp.jaxa.iss.kibo.rpc.malaysia | malaysia | malaysia.apk | malaysia |
| Nepal | jp.jaxa.iss.kibo.rpc.nepal | nepal | nepal.apk | nepal |
| Philippines | jp.jaxa.iss.kibo.rpc.philippin | philippines | philippines.apk | philippines |
| | es | | | |
| Singapore | jp.jaxa.iss.kibo.rpc.singapor | singapore | singapore.apk | singapore |
| | е | | | |
| Taiwan | jp.jaxa.iss.kibo.rpc.taiwan | taiwan | taiwan.apk | taiwan |
| Thailand | jp.jaxa.iss.kibo.rpc.thailand | thailand | thailand.apk | thailand |
| UNOOSA | jp.jaxa.iss.kibo.rpc.unoosa | unoosa | unoosa.apk | unoosa |
| USA | jp.jaxa.iss.kibo.rpc.usa | usa | usa.apk | usa |
| Vietnam | jp.jaxa.iss.kibo.rpc.vietnam | vietnam | Vietnam.apk | vietnam |

(2) Send APK and source code

Please refer to section 3.4.1 of this rulebook.

(3) Confirm that everything is completed

Follow the checklist in Table 3.4-2 to confirm that you have completed the items to be performed for the Final Round.

(4) Update the API

Please comply with the instructions of the Secretariat with regard to any API updates.



Table 4.4-2 Checklist

| No. | Item | Description | Related Section(s) | |
|-----|----------------|--|---------------------------|--|
| 1 | Application ID | Change the application ID of the APK | Section 3.4 | |
| 1 | Application ID | | PG Manual Section 3.3.3 | |
| 2 | Rename the | Rename APK as per the regulations | Section 3.4 | |
| | APK | | PG Manual Section 3.3.3 | |
| 3 | Rename the | Rename the APK file according to the | Section 3.4 | |
| | APK File | rules | | |
| | Change the | Change the short name of the APK in | Section 3.4 | |
| 4 | APK short | accordance with the rules | PG Manual Section 3.3.3 | |
| | name | decordance with the rules | 1 G Haridai Section 5.5.5 | |
| 5 | MD5 | Create the APK's MD5 | Section 3.4.1(2) | |
| 6 | Submission | Submit the APK | Section 3.4.1(1) | |
| 0 | | Submit the source code | Section 3.4.1(2) | |
| | | The startmission function is called at the | PG Manual Section 7.1 | |
| | | beginning of the program | PG Manual Section 7.1 | |
| | Completion of | After recognizing the Target Item, | | |
| 7 | the | notifyRecognitionItem is called when | PG Manual Section 7.1 | |
| | Competition | moving to the Lost Item that matches | | |
| | | the Target Item | | |
| | | takeTargetItemSnapshot is called | PG Manual Section 7.1 | |
| | | Infinite loop with for or while is not | PG Manual Section 5.1 | |
| 8 | Software | implemented | . O Hariaal Section St. | |
| | Safety | No danger of infinite loops due to | PG Manual Section 5.1 | |
| | | recursion | | |
| 9 | Resource Load | No extra resources in the source code | _ | |



3.4.1. Submit APK and Source Code

You need to submit your program by the deadline for the final round. After submission, JAXA and NASA will review the source code in advance for safety reasons. Therefore, please submit the APK and source code according to the following procedure. (At the time of the preliminary review, only the source code will be submitted)

Due to the short time available for code modifications, please keep your schedules clear.

(Many revisions have occurred in previous years.)

Detailed submission instructions will be announced at a later date.

3.5. Organizing the Event

The 6th Kibo-RPC will be held in a similar format as that of the 5rd Kibo-RPC, which is shown in Figure 4.5. JAXA will run the Astrobee and finalists' APKs in advance. Footage of the competition is scheduled to be broadcast live, and finalists will be able to watch footage of their own runs. A final round event, featuring commentary by experts watching the pre-run footage, will be held at a later date. Finalists will be contacted by the Secretariat via email with more details..

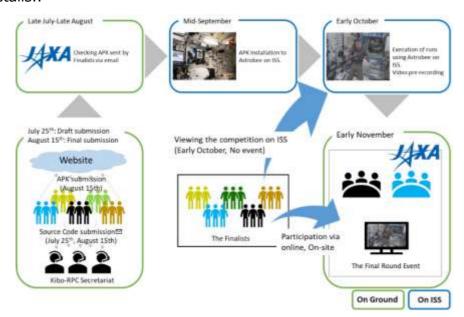


Figure 3.5 Flow up to the day of the event



Appendix 1

This will be the definition of terms used in the 6th Kibo-RPC.

| Term | Definition |
|------------------|--|
| Kibo-RPC | Abbreviation for Kibo Robot Programming Challenge, a programming competition using robots on the ISS. |
| ISS | Abbreviation for International Space Station. |
| Kibo | The Japanese Experiment Module developed by JAXA on the ISS. Also known as JEM (Japanese Experiment Module), this is where this game will take place. |
| Astrobee | Free-flyer robot developed by NASA that will be used in this game. |
| Area | A plane representing a potential location for a Lost Item, set on an ISS wall or Airlock. |
| Lost Item | A collective term for the images placed in each Area. Lost Items are categorized into two types: Treasure Items and Landmark Items. |
| Target Item | In the game, this word represents the real treasure the astronaut is searching for. |
| Tresure | One type of Lost Item, of which there are three different images. In this |
| Item | game, two or more are placed in each Area, but the real treasure the astronaut is searching for will be randomly chosen from these. |
| Landmark Item | One type of Lost Item, of which there are eight different images. In this game, points are awarded for accurately reporting the type and number of Landmark Items located in each Area to the astronaut. |
| AR Tag | An AR marker used to identify the location and orientation of an Item. |
| KIZ | Abbreviation for Keep-In-Zone, the range within which an Astrobee can move. |
| Oasis Zone | Located within KIZ, points are awarded based on the time spent in this zone. The points earned can vary depending on the specific location within a single Oasis Zone. |
| Crew | Used interchangeably with astronaut. |