



## Belief Propagation

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Belief Propagation

## SAT

- ▶ SAT formula in CNF

$$\mathcal{F} = (x_1 \vee x_2 \vee \overline{x_3}) \wedge (x_3 \vee x_4)$$

- ▶ Boolean variables  $x_1, x_2, \dots, x_n$
  - ▶ Negations  $\overline{x_1}, \dots, \overline{x_n}$
  - ▶ Clauses: Disjunction of variables and their negations
  - ▶  $\mathcal{F}$ : Conjunction of clauses
- ▶ Is there an assignment of the variables that satisfies  $\mathcal{F}$ ?
- ▶ How does the assignment look like?

## Factor Graphs

Factor graphs represent a function's factorization

- ▶ Function  $f(X)$  over variables  $X = \{x_1, x_2, \dots, x_n\}$
- ▶ Global function  $f$  factorizes to local functions

$$f(X) = \prod_{j=1}^m f_j(S_j)$$

- ▶ Local functions have smaller input  $S_j \subset X$

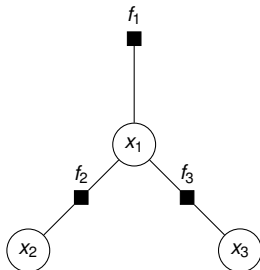
## Factor Graphs

Factor graphs represent a function's factorization

- ▶ Two types of nodes
  - ▶ Variable nodes: represent variables
  - ▶ Factor nodes : represent local functions
- ▶ Edges connect variable and factor nodes
- ▶ Factor nodes are connected to all variable nodes of their input variables

## Example

$$\begin{aligned} f(x_1, x_2, x_3) &= x_1^3 - x_1^2 x_2 + x_1^2 x_3 - x_1 x_2 x_3 \\ &= \underbrace{(x_1)}_{f_1(x_1)} * \underbrace{(x_1 - x_2)}_{f_2(x_1, x_2)} * \underbrace{(x_1 + x_3)}_{f_3(x_1, x_2)} \end{aligned}$$

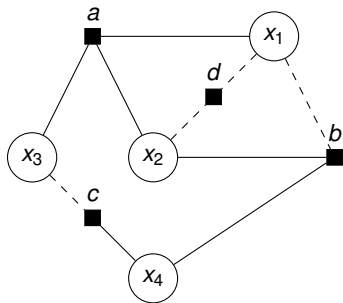


## Factor Graphs

Factor Graph of a CNF formula

$$\mathcal{F} = (x_1 \vee x_2 \vee x_3) \wedge (\overline{x_1} \vee x_2 \vee x_4) \\ \wedge (\overline{x_3} \vee x_4) \wedge (\overline{x_1} \vee \overline{x_2})$$

- $\mathcal{F}$  is a product of clauses
- Clauses  $\cong$  local functions



## Message Passing

### Message Passing Algorithms on factor graphs

- ▶ Nodes communicate through messages
- ▶ Messages are passed over the graph's edges
- ▶ Two types of messages
  - ▶  $\mu_{i \rightarrow a}$  sent from factor  $a$  to variable  $i$
  - ▶  $\mu_{a \rightarrow i}$  sent from variable  $i$  to factor  $a$

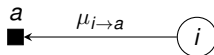




## Message Passing

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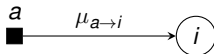
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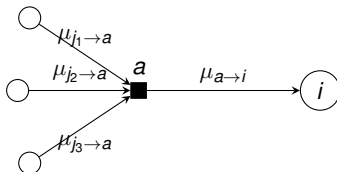
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## Message Passing

### Message Passing Algorithms on factor graphs

- ▶ Message  $\mu_{a \rightarrow i}$  determined by incoming messages  $\mu_{j \rightarrow a}$  from neighbours  $j \neq i$
- ▶ Computation Rule depends on application

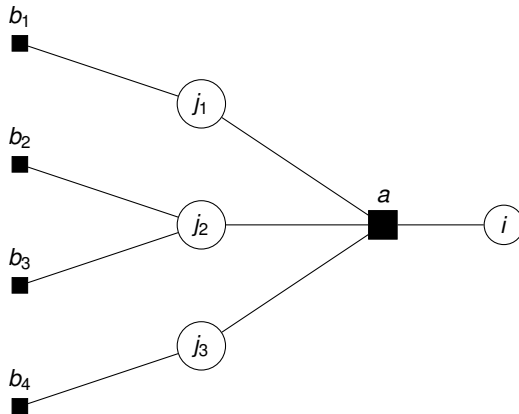


## Message Passing

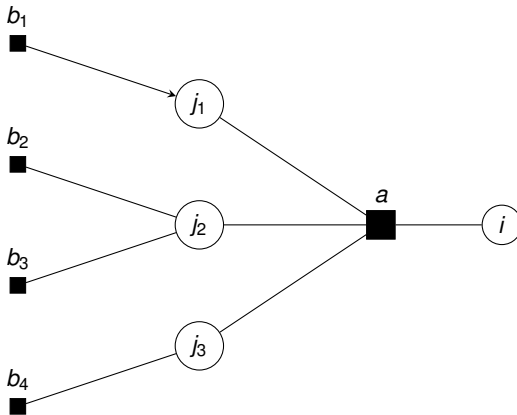
### Message Passing Algorithms on trees

- ▶ Messages generated bottom up
- ▶ Leaves start sending messages
- ▶ Messages are propagated forward in the tree
- ▶ Does **not** work on graphs with cycles

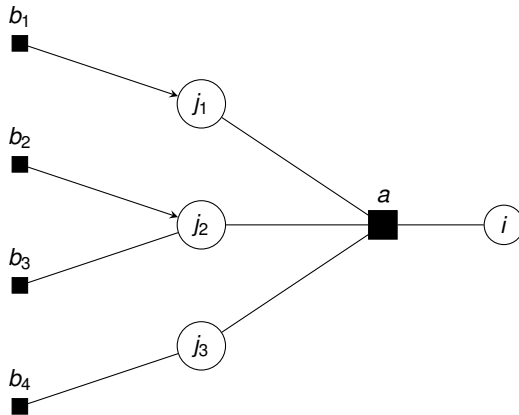
## Example



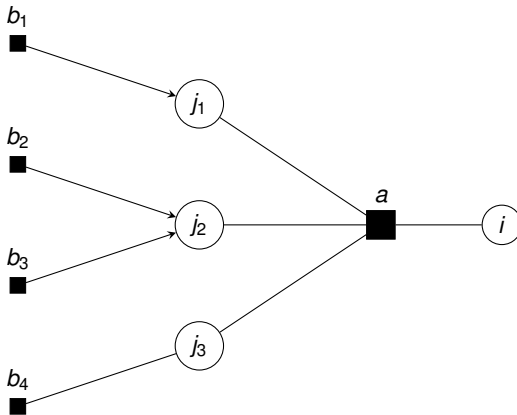
## Example



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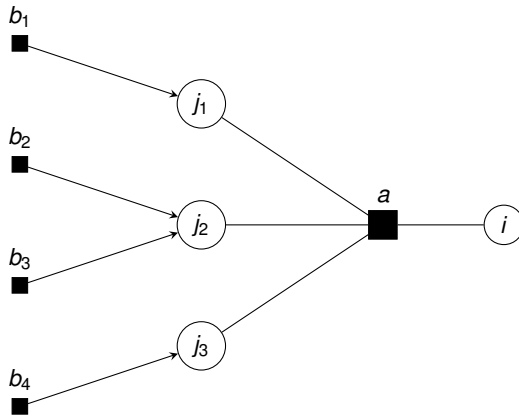


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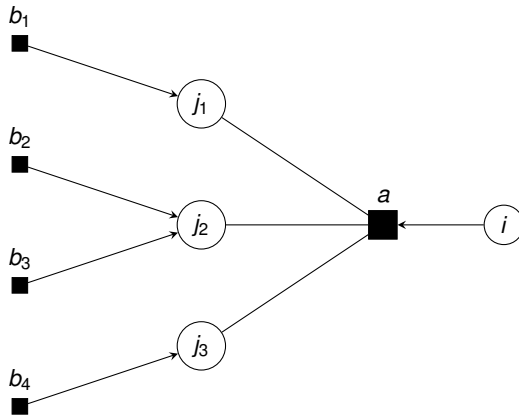




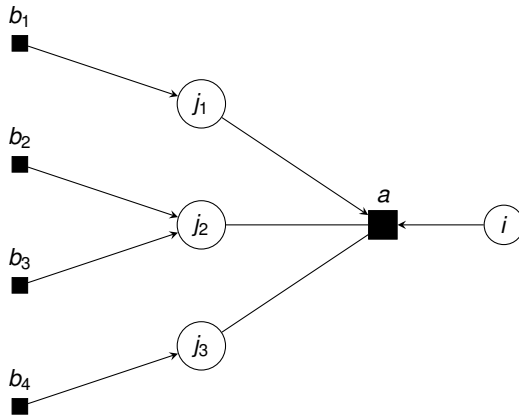
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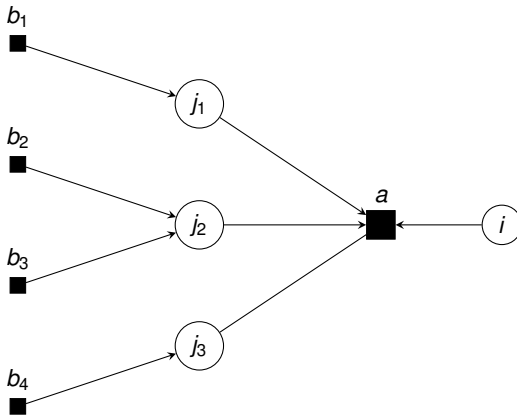
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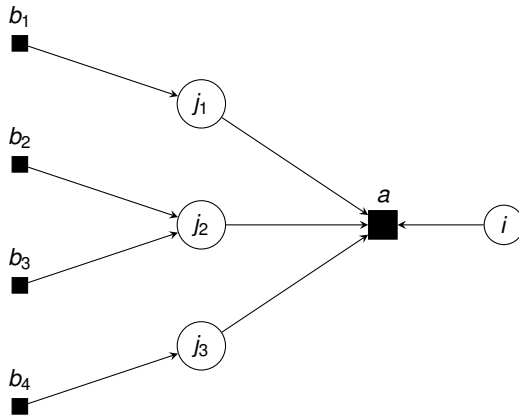
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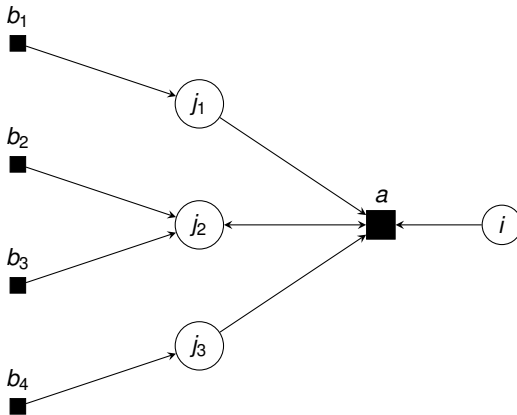
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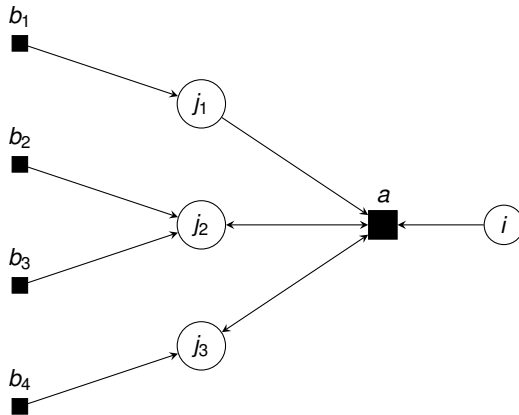
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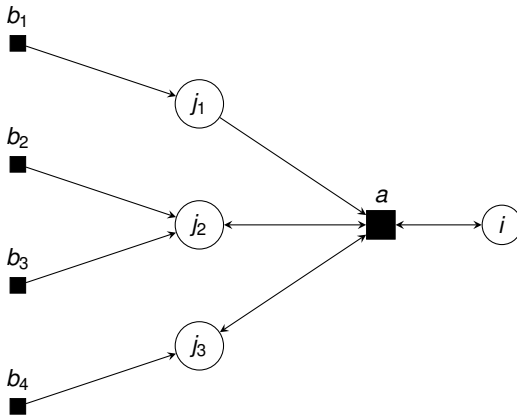
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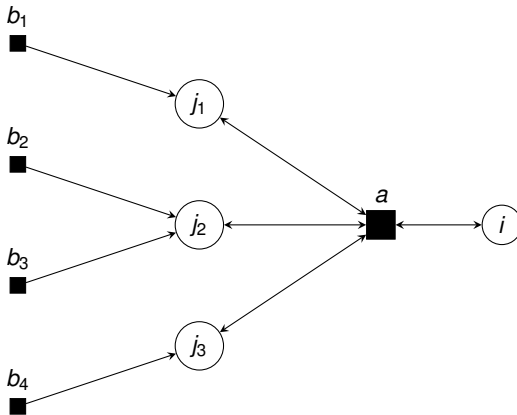


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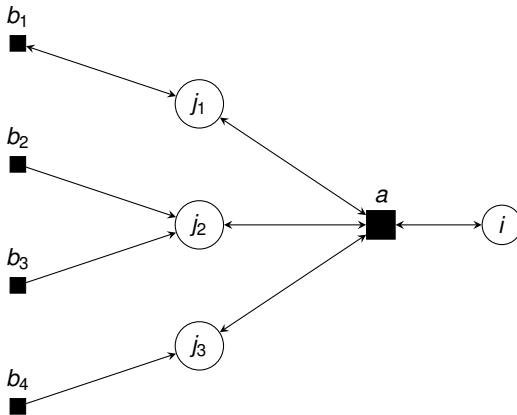




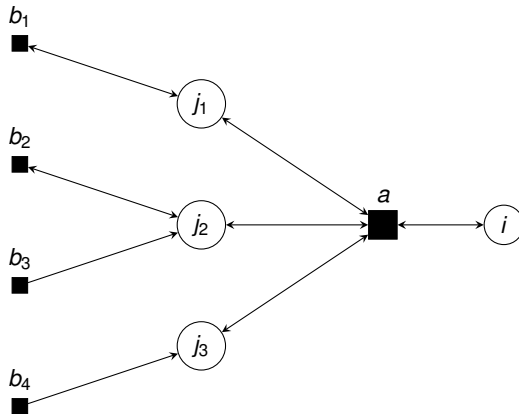
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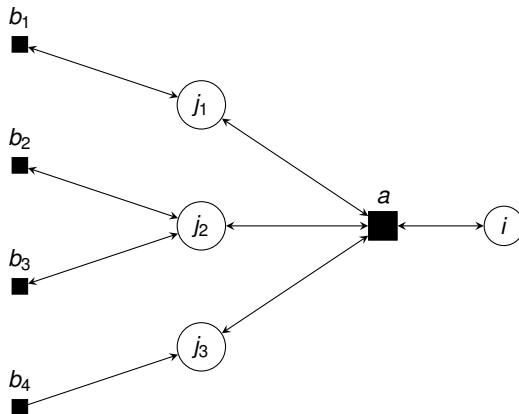
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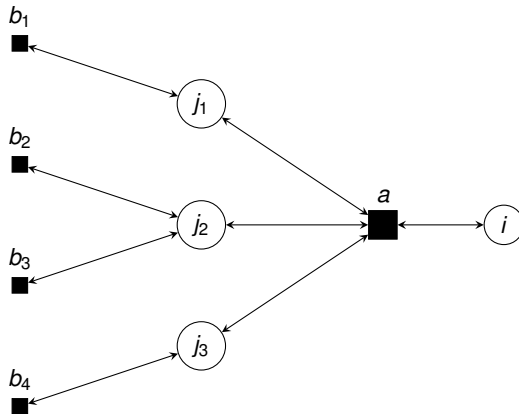
## Example



## Example



## Example



## Message Passing

- ▶ In general graphs: *Loopy* Message Passing
- ▶ Randomly initialize all messages
- ▶ Apply the Update rule until messages have converged
- ▶ Scheduling important

## Message Passing

### Generic Message Passing Algorithm

1. Randomly initialize all warnings  $\mu_{i \rightarrow a}, \mu_{a \rightarrow i}$
2. For  $t = 0$  to  $t_{max}$ 
  - 2.1 Apply the update rule to all edges in random order
  - 2.2 If no message has changed goto 3
3. If  $t = t_{max}$  return UNGONVERGED  
Else return the converged messages

## Message Passing

- ▶ Loopy Message Passing converges on trees
- ▶ On cyclic graphs
  - ▶ no guarantee of convergence
  - ▶ no guarantee of correctness
- ▶ Can be used as heuristics
- ▶ In practice often correct



## Warning Propagation Algorithm

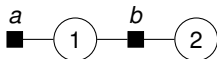
Apply Message Passing to SAT

- ▶ Input: Formula in CNF and its Factor Graph
- ▶ Output: Valid variable assignment

## Warning Propagation Algorithm

### Apply Message Passing to SAT

- ▶ Clause  $a$  can send a *warning*  $u_{a \rightarrow i} \in \{0, 1\}$  to its variables  $i$
- ▶ If  $u_{a \rightarrow i}^* = 1$ ,  $i$  **must** satisfy  $a$   
e.g  $\mathcal{F} = (\overline{x_1}) \wedge (x_1 \vee x_2)$   
 $x_1$  has to satisfy the first clause



- ▶ The clause  $a$  *fixes* the variable  $i$  to a value

## Warning Propagation Algorithm

### Apply Message Passing to SAT

- ▶ Variables send their preferred state to factors
- ▶ *Cavity Field*  $h_{i \rightarrow a}$ 
  - ▶  $> 0$ , if  $i$  prefers the value 1
  - ▶  $< 0$  if  $i$  prefers the value 0
- ▶ Messages
  - ▶ Warnings  $u_{a \rightarrow i} \in \{0, 1\}$
  - ▶ Cavity Fields  $h_{i \rightarrow a} \in \mathbb{Z}$

## Update Rule - Cavity Field

- Count how often  $i$  is fixed to 1 by clauses  $b \neq a$

$$\sum_{b \in V_+(i) \setminus a} u_{b \rightarrow i}$$

- Count how often  $i$  is fixed to 0 by clauses  $b \neq a$

$$\sum_{b \in V_-(i) \setminus a} u_{b \rightarrow i}$$

- Send the difference to  $a$

$$h_{i \rightarrow a} = \sum_{b \in V_+(i) \setminus a} u_{b \rightarrow i} - \sum_{b \in V_-(i) \setminus a} u_{b \rightarrow i}$$

## Update Rule - Warnings

- ▶  $a$  sends a warning to  $i$ , if its variables  $j \neq i$  prefer to violate  $a$
- ▶ Define  $J_j^a = \begin{cases} -1, & \text{if } x_j = 1 \text{ satisfies } a \\ 1, & \text{if } x_j = 0 \text{ satisfies } a \end{cases}$
- ▶  $j$  prefers to violate  $a$ , if  $J_j^a h_{j \rightarrow a} > 0$
- ▶ Define  $\theta(x) = \begin{cases} 1, & x > 0 \\ , & x \leq 0 \end{cases}$

## Update Rule - Warnings

- ▶  $j$  prefers to violate  $a$ , if  $J_j^a h_{j \rightarrow a} > 0$
- ▶ Define  $\theta(x) = \begin{cases} 1, & x > 0 \\ 0, & x \leq 0 \end{cases}$
- ▶ Warnings can be computed as

$$u_{a \rightarrow i} = \prod_{j \in V(a) \setminus i} \theta(J_j^a h_{j \rightarrow a})$$

## Update Rule - Summary

$$h_{i \rightarrow a} = \sum_{b \in V_+(i) \setminus a} u_{b \rightarrow i} - \sum_{b \in V_-(i) \setminus a} u_{b \rightarrow i}$$
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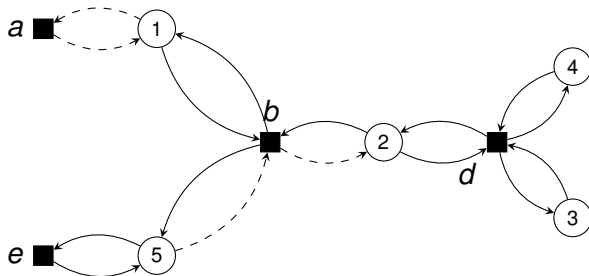
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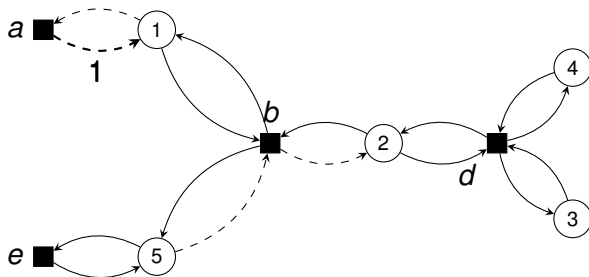
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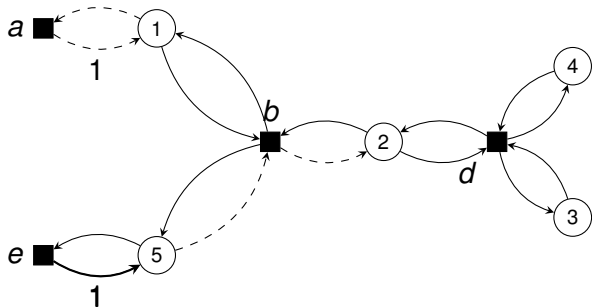
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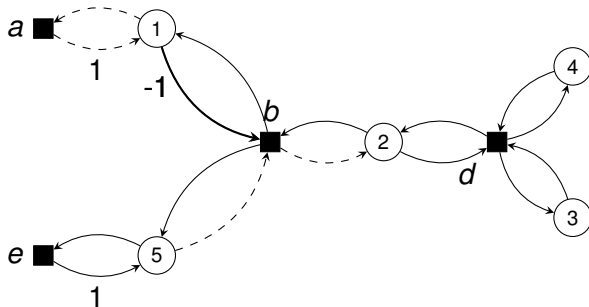
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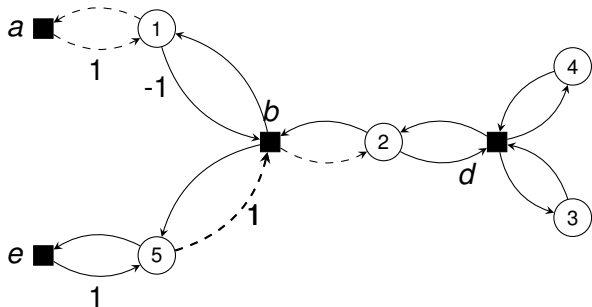
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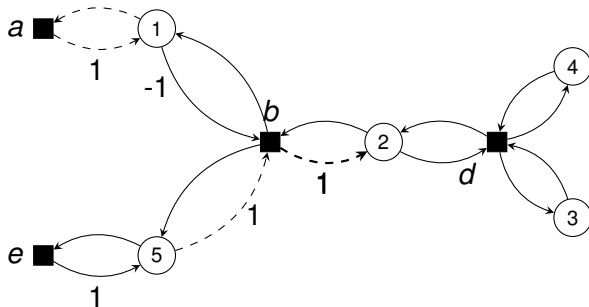
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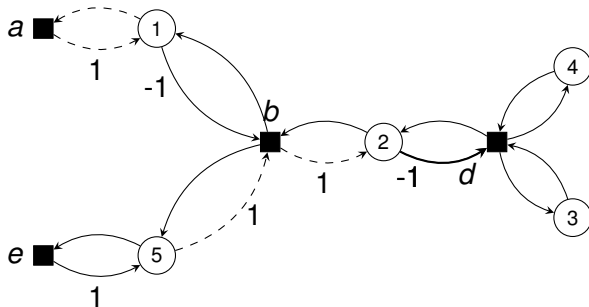
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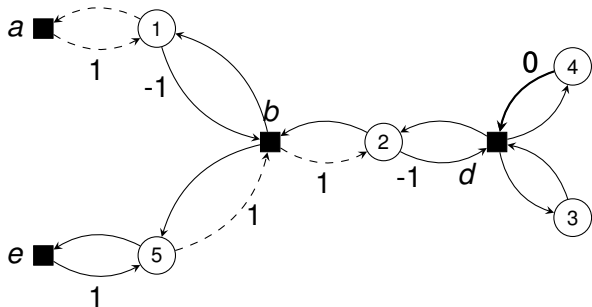
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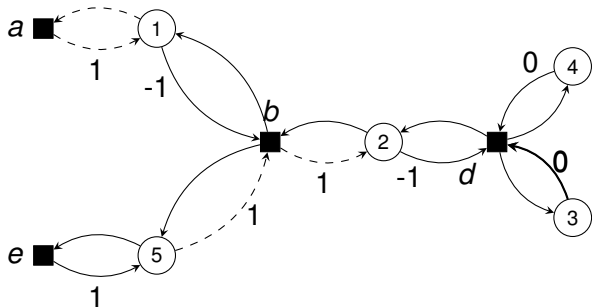


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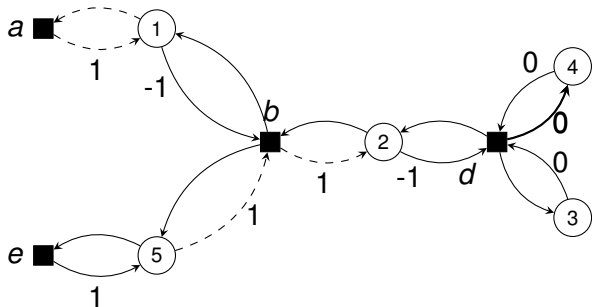




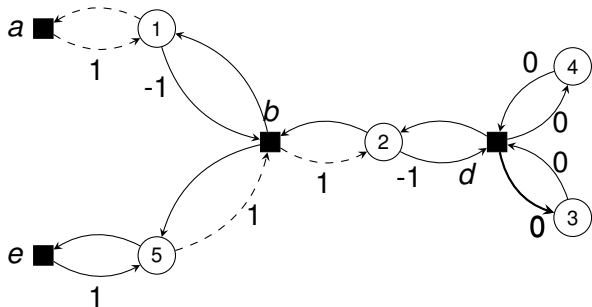
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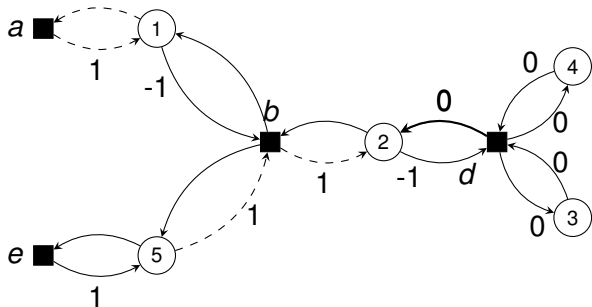
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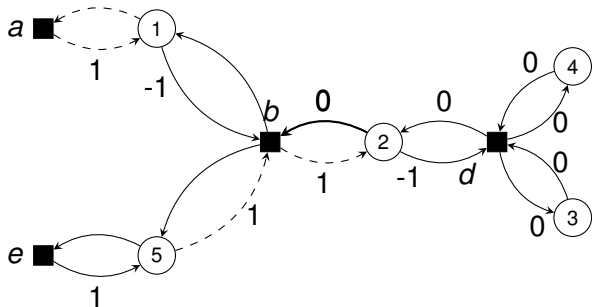
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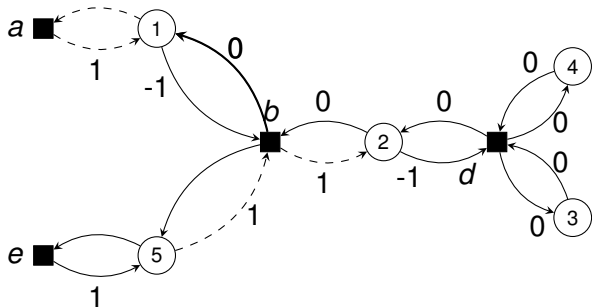
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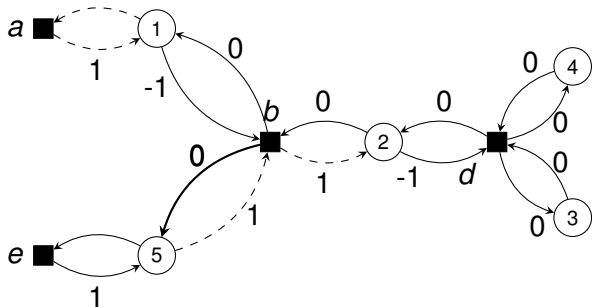
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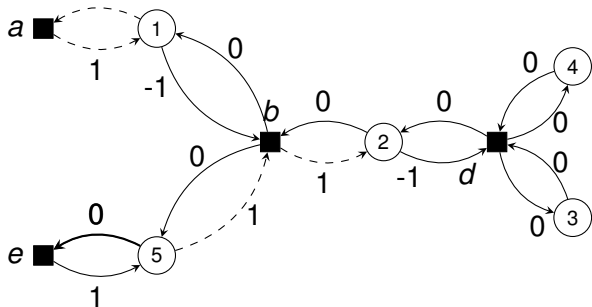
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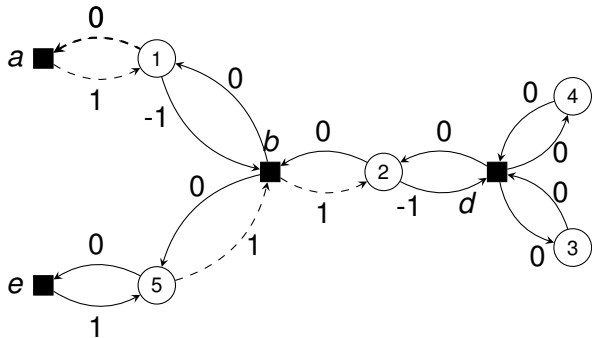


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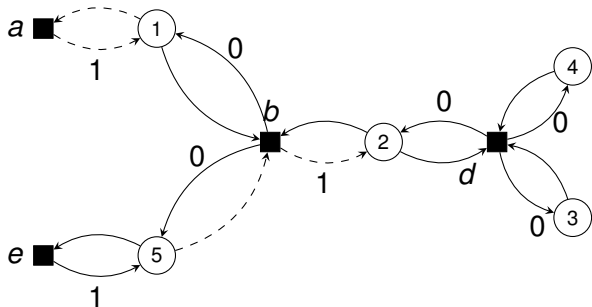




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## Decimation Algorithm

- ▶ If a variable is fixed to different values,  $\mathcal{F}$  is not satisfiable
- ▶ If not, the warnings lead to a partial assignment:
  - ▶ Assign each variable with active warnings the value it was fixed to
  - ▶ If all warnings are 0, assign a random value to a random variable

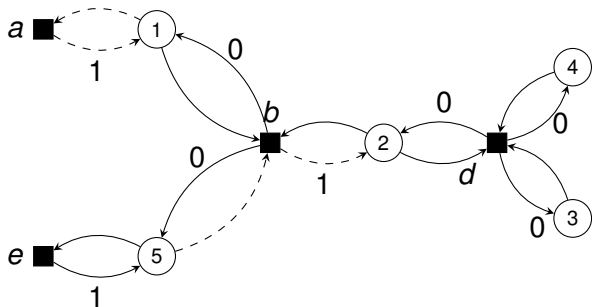
## Message Passing

### Warning Inspired Decimation Algorithm

1. While there are unassigned variables
2.     Run the WP Algorithm
3.     If WP does not converge  
        return UNCONVERGED
4.     If at least one variable is fixed  
        to different values return UNSAT
5.     Choose a partial assignment
6.     Clean the graph
7. Return the complete assignment

## Example

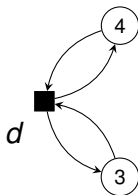
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Assign  $x_1 = 0$ ,  $x_2 = 0$ ,  $x_5 = 1$

## Example

- ▶ Cleaned formula:  $\mathcal{F} = (x_3 \vee x_4)$
- ▶ Cleaned graph:



## Belief Propagation Algorithm

- ▶ General Algorithm for approximating marginal probabilities on factor graphs
- ▶ Applied in many different areas
- ▶ Can be viewed as generalization of Warning Propagation

## Belief Propagation Algorithm

Probability space built by all valid variable assignments  $X = (x_1, \dots, x_n)$  of a formula  $\mathcal{F}$ .

- Uniform distribution on all assignments

$$P(X) = \frac{1}{2^n}$$

- Restriction on valid assignments

$$P(X \mid X \text{ satisfies } \mathcal{F}) = \frac{1}{\mathcal{N}} \prod_{a \in A} f_a(X)$$

- Goal: Compute  $P(x_i = 1 \mid X \text{ satisfies } \mathcal{F})$



## Messages

- ▶ WP:  $u_{a \rightarrow i}$  is 1 if all neighbours  $j \in V(a) \setminus i$  violate  $a$
- ▶ BP:  $\delta_{a \rightarrow i}$  is the *probability* for this event

## Messages

- ▶ WP:  $h_{i \rightarrow j}$ : preferred value of  $i$
- ▶ BP:  $\gamma_{a \rightarrow i}$ : *probability* for  $i$  to violate  $a$