Day 3: Generalization Error Summer STEM: Machine Learning

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Learning Objectives

- What is the difference between train error and test error?
- What is overfitting? How do we detect it?
- What is cross validation?
- How to find the optimal model order for my model?
- What is regularization? How does it prevent overfitting?



Outline

Review of Day 2

- 1 Review of Day 2
- 2 Lab: Robot Arm Calibration
- 3 Polynomial Regression
- 4 Train and Test Error, Overfitting
- 5 Model Order Selection
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Load and visualize data



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 - $(x_i, y_i), i = 1, ..., n$



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 - Select β_0, β_1 to minimize the error function $\beta_1 = \rho \frac{\sigma_y}{\sigma}, \quad \beta_0 = \bar{y} - \beta_1 \bar{x}$



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- Prediction: $y_{new} = \beta_0 + \beta_1 x_{new}$



Extending the Model to Multi-variable Data

■ Model:
$$\hat{y} = \beta_0 \times 1 + \beta_1 x_1 + \beta_2 x_2 + ... + \beta_D x_D$$

■ Design Matrix: Let,
$$A = \begin{bmatrix} 1 & x_{1_1} & \cdots & x_{1_D} \\ 1 & x_{2_1} & \cdots & x_{2_D} \\ \vdots & & \ddots & \\ 1 & x_{N_1} & \cdots & x_{N_D} \end{bmatrix}$$

■ We say β^* solves $\mathbf{y} = A\beta$ in the least squares sense, where

$$\boldsymbol{\beta}^{\star} = A^{\dagger} \mathbf{y}$$

■ This β^* minimizes the mean squared error



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Robot Arm Calibration

- Let's train a model based on the given data.
- In this lab we're going to:
 - Predict the *current* drawn
 - Predictors, X: Robot arm's joint angles, velocity, acceleration, strain gauge readings (load measurement).

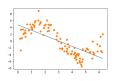


- Polynomial Regression
- 4 Train and Test Error, Overfitting



Polynomial Fitting

- We have been using linear model to fit our data. But it doesn't work well every time
- Some data have more complex relation that cannot be fitted well using a straight line
 - Ex: Projectile motion, Coulomb's law, Exponential growth/decay, ...



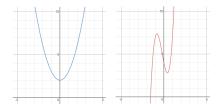
- Linear model does not look like a good fit for this data
- Can we use some other model to fit this data?



Polynomial Fitting

- Can we use a polynomial to fit our data?
- Polynomial: A sum of different powers of a variable

Examples:
$$y = x^2 + 2$$
, $y = 5x^3 - 3x^2 + 4$



Polynomial Model: $y = \beta_0 + \beta_1 x + \beta_2 x^2 + \beta_3 x^3 + \dots$



Polynomial Fitting

- Polynomial Model: $y = \beta_0 + \beta_1 x + \beta_2 x^2 + \beta_3 x^3 + ...$
- The process of fitting a polynomial is similar to linearly fitting multivariate data
- Recall the linear model for multivariable
- $v = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_3 x_3 + ...$
 - Where $x_1, x_2, x_3...$ are different features
- If we treat x^2 as our second feature, x^3 as our third feature. x^4 as our fourth feature.... We can use the same procedure in multivariate regression for linear fit!



Design Matrix for Linear:

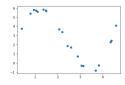
Lab: Robot Arm Calibration

$$A = \begin{bmatrix} 1 & x_1 \\ 1 & x_2 \\ \vdots & \vdots \\ 1 & x_N \end{bmatrix}$$

- Design Matrix for Polynomial: $A = \begin{bmatrix} 1 & x_1 & x_2^2 & \cdots & x_1^D \\ 1 & x_2 & x_2^2 & \cdots & x_2^D \\ \vdots & & \ddots & & \vdots \\ 1 & x_N & x_N^2 & \cdots & x_N^D \end{bmatrix}$
- For the polynomial fitting, we just added columns of features that are powers of the original feature



You are given the data set below with x and y values



- Try to fit the data using a polynomial with a certain degree
- Calculate mean square error between the sample y and your predicted y
- Try different polynomial degree and see if you can improve the mse
- Plot your polynomial over the data points



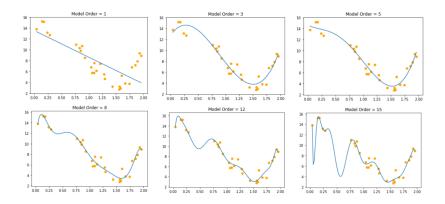
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- We learned how to fit our data using polynomials of different order
- With a higher model order, we can fit the data with increasing accuracy
- As you increase the model order, at certain point it is possible find a model that fits your data perfectly (ie. zero error)
- What could be the problem?



Overfitting

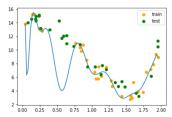


■ Which of these model do you think is the best? Why?



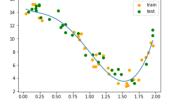
Overfitting

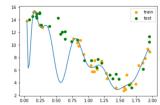
- The problem is that we are only fitting our model using data that is given
- Data usually contains noise
- When a model becomes too complex, it will start to fit the noise in the data
- What happens if we apply our model to predict some data that the model has never seen before? It will not work well.
- This is called over-fitting





- Split the data set into a train set and a test set
- Train set will be used to train the model
- The test set will not be seen by the model during the training process
- Use test set to evaluate the model when a model is trained



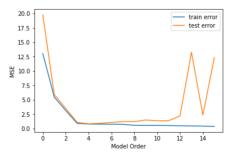


■ With the training and test sets shown, which one do you think is the better model now?



Train and Test Error

- Plot of train error and test error for different model order
- Initially both train and test error go down as model order increase
- But at a certain point, test error start to increase because of overfitting





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Model Order Selection

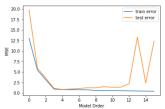
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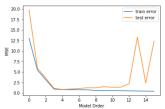


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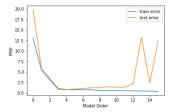
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Is optimizing our algorithm based on test error smart?



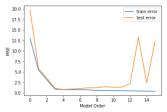
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- Is optimizing our algorithm based on test error smart?
 - We run into the same problem as overfitting
 - Tuning our algorithm on what should be unknown data!



Regularization

Cross-Validation

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 - Validation set: to tune hyper-parameters (model-order)



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 - **Test set**: to compute the performance of the algorithm (MSE)



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- Demo: MOS Attempt 1



Finding a Rule for Model Order Selection

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- Possible Answer: Fitting multiple datasets and averaging the validation error



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 - **1** Compute the model parameters (β)
 - 2 Compute the score on the val. set (MSE)



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 - Standard-Error (SE): (std-dev of lowest mean val. score) $/\sqrt{K-1}$



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Regularization

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- Is there another way? Talk among your classmates.

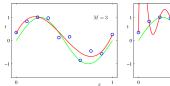


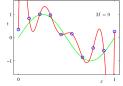
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 - We just covered regularization by model order selection
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 - Solution: We can change our cost function.



Weight Based Regularization

■ Looking back at the polynomial overfitting



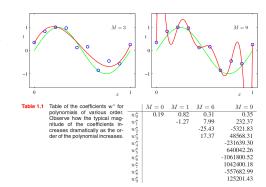


Model Order Selection



Weight Based Regularization

- Looking back at the polynomial overfitting
- Notice that weight-size increases with overfitting





Regularization

$$J = \sum_{i=1}^{N} (y_i - y_{i\,pred})^2$$



$$J = \sum_{i=1}^{N} (y_i - y_{i\,pred})^2 + \lambda \sum_{j=1}^{D} (w_j)^2$$



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Table 1.2	Table of the coefficients \mathbf{w}^{\star} for $M=$	
	9 polynomials with various values for	w_0^*
	the regularization parameter λ . Note	w_1^*
	that $\ln \lambda = -\infty$ corresponds to a	
	model with no regularization, i.e., to	w_2^*
	the graph at the bottom right in Fig-	w_3^{\star}
	ure 1.4. We see that, as the value of	w_4^{\star}
	λ increases, the typical magnitude of the coefficients gets smaller.	w_5^{\star}
	the coefficients gets smaller.	w_6^{\star}
		w_7^*
		10°

	$\ln \lambda = -\infty$	$\ln \lambda = -18$	$\ln \lambda = 0$
w_0^*	0.35	0.35	0.13
w_1^*	232.37	4.74	-0.05
w_2^*	-5321.83	-0.77	-0.06
w_3^{\star}	48568.31	-31.97	-0.05
w_4^{\star}	-231639.30	-3.89	-0.03
w_5^*	640042.26	55.28	-0.02
w_6^{\star}	-1061800.52	41.32	-0.01
w_7^*	1042400.18	-45.95	-0.00
w_8^*	-557682.99	-91.53	0.00
w_9^*	125201.43	72.68	0.01



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Thank You!

■ Next Class: Linear Classification

