

CALCULUS

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1. Limits and Continuity
 2. Differentiation
 3. Definite Integrals
 4. Improper Integrals
 5. Partial Differentiation
 6. Multiple Integrals
 7. Vector Differentiation
 8. Vector Integration
 9. Fourier Series

Calculus is defined as science of acceleration, retardation and variation.

function: \rightarrow A relation between two sets 'A' & 'B' if $\forall x \in A$ \exists a unique $y \in B$ s.t. $f(x) = y$

(i) Explicit function: $\rightarrow z = f(x_1, x_2, \dots, x_n)$

(ii) Implicit function: $\rightarrow \phi(z, x_1, x_2, \dots, x_n) = C$

(iii) Composite function: \rightarrow If $z = f(x, y)$ where $x = \phi(t)$ & $y = \psi(t)$
 i.e. z is function of some function.

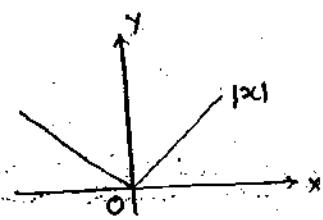
Some Special functions

(i) Even function: $\rightarrow f(-x) = f(x)$ Eg:- $\cos x, 1/x, \dots$

(ii) Odd function: $\rightarrow f(-x) = -f(x)$ Eg:- $\sin x, x, \dots$

(iii) Modulus function: \rightarrow

$$f(x) = |x| = \begin{cases} x & ; x > 0 \\ -x & ; x < 0 \\ 0 & ; x = 0 \end{cases}$$



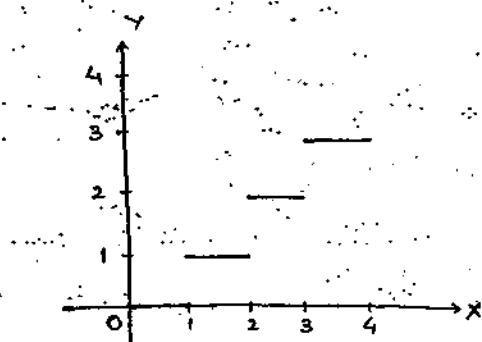
$$\frac{d}{dx} |x| = \frac{|x|}{x} \text{ for } x \neq 0$$

(iv) Step-function/Greatest Integer function

$$f(x) = [x] = n \in \mathbb{Z}$$

where, $n \leq x < n+1$

$$\text{Eg:- } [7.2] = 7, [7.999] = 7, [-1.2] = -2$$



Symmetric Properties of the curve:

Let $f(x, y) = c$ be the eqn of the curve

(i) If $f(x, y)$ contains only even powers of x i.e. $\frac{\partial^2 f}{\partial x^2} > 0$

$f(-x, y) = f(x, y)$ then it is symmetric about y -axis.

(ii) If $f(x, y)$ contains only even powers of y i.e. $f(x, -y) = f(x, y)$

then it is symmetric about x -axis.

(iii) If $f(x, y) = f(y, x)$, then, the curve is symmetric about $y=x$.

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1. Limit of a function: \rightarrow Let $f(x)$ be defined in deleted neighbourhood of $a \in R$, then, $l \in R$ is said to be limit of $f(x)$ as x approaches a if for given $\epsilon > 0$, $\exists \delta > 0$ such that $|f(x) - l| < \epsilon$ whenever $|x-a| < \delta$.

$$\boxed{\lim_{x \rightarrow a} f(x) = l}$$

Left limit: \rightarrow when $x < a$, $x \rightarrow a$

$$\lim_{x \rightarrow a^-} f(x) = \lim_{h \rightarrow 0} f(a-h)$$

Right Limit: \rightarrow when $x > a$, $x \rightarrow a$

$$\lim_{x \rightarrow a^+} f(x) = \lim_{h \rightarrow 0} f(a+h)$$

A limit exists iff $LHL = RHL$

Indeterminate form: $\rightarrow \frac{0}{0}, \frac{\infty}{\infty}, 0 \times \infty, \infty - \infty, 0^0, 1^\infty, \infty^0$

Whenever we have $\lim_{x \rightarrow a} \frac{f(x)}{g(x)}$ [as $\frac{0}{0}$ or $\frac{\infty}{\infty}$] = $\lim_{x \rightarrow a} \frac{f'(x)}{g'(x)}$

This rule is applied until we are free from indeterminate form. (This rule is called L'Hospital Rule)

Standard Limits:-

$$(i) \lim_{x \rightarrow a} \frac{x^n - a^n}{x - a} = n a^{n-1}$$

$$(ii) \lim_{x \rightarrow 0} \frac{e^{mx} - 1}{x} = m$$

$$(iii) \lim_{x \rightarrow 0} \frac{a^x - 1}{x} = \log a$$

$$(iv) \lim_{x \rightarrow 0} [1 + ax]^{1/x} = e^a$$

$$(v) \lim_{x \rightarrow \infty} \left[1 + \frac{a}{x}\right]^x = e^a$$

$$(vi) \lim_{x \rightarrow 0} \frac{\sin x}{x} = 1 \quad \text{or} \quad \lim_{x \rightarrow 0} \frac{\tan x}{x} = 1$$

$$(vii) \lim_{x \rightarrow \infty} \frac{\sin x}{x} = 0$$

$$(viii) \lim_{x \rightarrow 0} \frac{\sin mx}{x} = m$$

$$(ix) \lim_{x \rightarrow 0} \left[\frac{a^x + b^x}{2}\right]^{1/x} = \sqrt{ab}$$

$$(x) \lim_{x \rightarrow 0} [\cos x + a \sin bx]^{1/x} = e^{ab}$$

$$(xi) \lim_{x \rightarrow 0} \left[\frac{1 - \cos ax}{x^2}\right] = \frac{a^2}{2}$$

Questions: →

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$$1. \lim_{x \rightarrow 0} \frac{1 - \cos 3x}{x \sin 2x}$$

$$\text{Soln:} \rightarrow \lim_{x \rightarrow 0} \frac{1 - \cos 3x}{x \sin 2x} = \lim_{x \rightarrow 0} \frac{3 \sin 3x}{\sin 2x + 2x \cos 2x}$$

$$= \lim_{x \rightarrow 0} \frac{9 \cos 3x}{2 \cos 2x + 2 \cos 2x - 4x \sin 2x}$$

$$= \frac{9}{4}$$

OR

$$\lim_{x \rightarrow 0} \frac{(1 - \cos 3x)/x^2}{(\sin 2x)/x} = \frac{3^2/2}{2} = \frac{9}{4}$$

$$2. \lim_{x \rightarrow \frac{\pi}{2}} \frac{\sin^2 2x}{(x - \frac{\pi}{2})^2} \text{ is } \dots$$

- (a) 1 (b) 2 (c) 4 (d) -4

$$\text{Soln:} \rightarrow \lim_{x \rightarrow \frac{\pi}{2}} \frac{[\sin 2(\frac{\pi}{2} - x)]^2}{(\frac{\pi}{2} - x)^2}$$

Take, $\frac{\pi}{2} - x = t$, then

$$\lim_{t \rightarrow 0} \left[\frac{\sin 2t}{t} \right]^2 = (2)^2 = 4$$

$$3. \lim_{x \rightarrow 0} \frac{\log x}{\cot x}$$

$$\text{Soln:} \rightarrow \lim_{x \rightarrow 0} \frac{\log x}{\cot x} = \lim_{x \rightarrow 0} \frac{\frac{1}{x}}{-\csc^2 x} = - \left[\lim_{x \rightarrow 0} \left(\frac{\sin x}{x} \cdot \sin x \right) \right]$$

$$= -1 \times 0$$

$$4. \lim_{x \rightarrow \frac{\pi}{2}} \frac{\tan x}{\log(\cos x)}$$

$$\text{Soln:} \rightarrow \lim_{x \rightarrow \frac{\pi}{2}} \frac{\tan x}{\log(\cos x)} = \lim_{x \rightarrow \frac{\pi}{2}} \frac{\sec^2 x}{-\sec x \sin x} = - \lim_{x \rightarrow \frac{\pi}{2}} \frac{1}{\sin x \cos x} \\ = -\infty.$$

$$5. \lim_{x \rightarrow \frac{\pi}{2}} \tan x$$

$$\text{Soln:} \rightarrow \lim_{x \rightarrow \frac{\pi}{2}} \tan x = \lim_{x \rightarrow \frac{\pi}{2}} \frac{\sin x}{\cos x} \quad \text{limit doesn't exist} \quad (\because \text{LHL} \neq \text{RHL})$$

$$6. \lim_{x \rightarrow 0} \sin x \log x^2$$

$$\text{Soln:} \rightarrow \lim_{x \rightarrow 0} \sin x \log x^2 = \lim_{x \rightarrow 0} \frac{\log x^2}{\csc x} = \lim_{x \rightarrow 0} \frac{2/x}{-\csc x \cot x} \\ = \lim_{x \rightarrow 0} \left(-2 \times \frac{\sin x}{x} \times \tan x \right) \\ = -2 \times 1 \times 0 = 0.$$

Note: →

$$\log a^0 = \begin{cases} \infty & ; a < 1 \\ \dots & \dots \\ -\infty & ; a > 1 \end{cases}$$

$$7. \lim_{x \rightarrow 1} (x-1) \tan \frac{\pi x}{2}$$

$$\text{Soln:} \rightarrow \lim_{x \rightarrow 1} (x-1) \tan \frac{\pi x}{2} = \lim_{x \rightarrow 1} \frac{(x-1)}{\cot \frac{\pi x}{2}} = \lim_{x \rightarrow 1} \left[\frac{1}{-\frac{\pi}{2} \csc^2 \left(\frac{\pi x}{2} \right)} \right] \\ = -\frac{2}{\pi}.$$

Note: → (i) $\lim_{x \rightarrow 0} x \sin(1/x) = 0$

(ii) $\lim_{x \rightarrow \infty} x \sin(1/x) = 1$

(iii) $\lim_{x \rightarrow 0} \sin(1/x)$ does not

exists.

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8. $\lim_{x \rightarrow 0} \left[\frac{1}{x} - \frac{1}{x^2} \log(1+x) \right]$ is

- (a) $\frac{1}{2}$ (b) $\frac{1}{3}$ (c) $-\frac{1}{2}$ (d) $-\frac{1}{3}$

Solⁿ: $\lim_{x \rightarrow 0} \left[\frac{x - \log(1+x)}{x^2} \right] = \lim_{x \rightarrow 0} \left[\frac{1 - \frac{1}{1+x}}{\frac{2x}{2}} \right]$

$$= \lim_{x \rightarrow 0} \frac{1/(1+x)^2}{2} = \frac{1}{2}$$

9. $\lim_{x \rightarrow 0} \left[\frac{1}{x^2} - \frac{1}{\sin^2 x} \right]$ is

- (a) $\frac{1}{3}$ (b) $-\frac{1}{3}$ (c) $\frac{1}{2}$ (d) $\frac{1}{4}$

Solⁿ: $\lim_{x \rightarrow 0} \left[\frac{\sin^2 x - x^2}{x^2 \sin^2 x} \right] = \lim_{x \rightarrow 0} \left[\frac{\sin^2 x - x^2}{x^4 \cdot \frac{\sin^2 x}{x^2}} \right]$

$$= \lim_{x \rightarrow 0} \left[\frac{\sin^2 x - x^2}{x^4} \right]$$

$$= \lim_{x \rightarrow 0} \left[\frac{\sin 2x - 2x}{4x^3} \right]$$

$$= \lim_{x \rightarrow 0} \frac{2 \cos 2x - 2}{12x^2}$$

$$= -\frac{2}{12} \lim_{x \rightarrow 0} \left(\frac{1 - \cos 2x}{x^2} \right)$$

$$= -\frac{2}{12} \times \frac{4}{2} = -\frac{1}{3}$$

10. $\lim_{x \rightarrow 0} x^x$

Solⁿ: Let $y = x^x$

$$\Rightarrow \log y = x \log x$$

$$\Rightarrow \lim_{x \rightarrow 0} [\log y] = \lim_{x \rightarrow 0} (x \log x) = \log (\lim_{x \rightarrow 0} x^x) = 0$$

$$11. \lim_{x \rightarrow \frac{\pi}{2}} (\cos x)^{\frac{1}{\sin x}}$$

$$12. \lim_{x \rightarrow 1} [\log x]^{\frac{1}{\log x}}$$

Note: → If we have 1^∞ form, $\lim_{x \rightarrow a} [f(x)]^{g(x)} = e^{\lim_{x \rightarrow a} g(x)[f(x)-1]}$

$$13. \lim_{x \rightarrow 0} (1 - \sin x)^{\frac{1}{\sin x}}$$

$$\lim_{x \rightarrow 0} \frac{1}{\sin x} [1 - \sin x - 1]$$

$$\text{Soln: } \rightarrow e^{\lim_{x \rightarrow 0} \frac{1}{\sin x} [1 - \sin x - 1]} = e^{-1} = \frac{1}{e}$$

$$14. \lim_{x \rightarrow 0} (\cos x)^{\frac{1}{x^2}}$$

$$\text{Soln: } \rightarrow e^{\lim_{x \rightarrow 0} \frac{1}{x^2} [\cos x - 1]} = e^{-\lim_{x \rightarrow 0} \frac{[\cos x - 1]}{x^2}} = e^{-\frac{1}{2}} = e^{-\frac{1}{2}} = \frac{1}{\sqrt{e}}$$

$$15. \lim_{x \rightarrow 0} \left(\frac{2^x + 8^x}{2} \right)^{\frac{1}{x}} = \sqrt{ab} = \sqrt{2 \times 8} = \sqrt{16} = 4.$$

$$16. \lim_{x \rightarrow 0} \left(\frac{2^x + 4^x + 8^x}{3} \right)^{\frac{1}{x}} = \sqrt[3]{abc} = \sqrt[3]{2 \times 4 \times 8} = 4.$$

$$17. \lim_{x \rightarrow 0} [\cos x + 2 \sin 3x]^{1/x} = e^{ab} = e^{2 \times 3} = e^6.$$

Q. 18. $\lim_{x \rightarrow 0} [2 \cos x + 3 \sin 4x]^{1/x}$

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$$= \lim_{x \rightarrow 0} 2^{\frac{1}{x}} \left[\cos x + \frac{3}{2} \sin 4x \right]^{\frac{1}{x}} = \lim_{x \rightarrow 0} 2^{\frac{1}{x}} \cdot \lim_{x \rightarrow 0} \left[\cos x + \frac{3}{2} \sin 4x \right]^{\frac{1}{x}}$$

= does not exist. ($\because \text{LHL} \neq \text{RHL}$ for $\lim_{x \rightarrow 0} 2^{\frac{1}{x}}$)

19. $\lim_{x \rightarrow 0} \frac{|x|}{x} = ?$

Soln: $\rightarrow \text{LHL} = \lim_{x \rightarrow 0^-} \frac{|x|}{x} = \lim_{h \rightarrow 0} \frac{|-h|}{-h} = -1$

$\text{RHL} = \lim_{x \rightarrow 0^+} \frac{|x|}{x} = \lim_{h \rightarrow 0} \frac{|h|}{h} = 1$

$\therefore \text{LHL} \neq \text{RHL}$

$\therefore \text{limit doesn't exist}$

20. $\lim_{x \rightarrow a} [x]$ doesn't exist when 'a' is _____

- (a) Real no. (b) Rational no. (c) Integer (d) all of these

Soln: Let $a=2$

$\text{LHL} = \lim_{x \rightarrow 2^-} [x] = 1$

$\text{RHL} = \lim_{x \rightarrow 2^+} [x] = 2$

$\therefore \text{LHL} \neq \text{RHL} \Rightarrow \text{limit doesn't exist.}$

Continuity of a function:

(i) Continuity at a point: → A fun is said to be continuous at a point $x=a$, if $\lim_{x \rightarrow a} f(x) = f(a)$

(ii) Continuity in an interval: → A fun $f(x)$ is said to be continuous in $[a, b]$ if it satisfies the following three conditions:-

(a) $f(x)$ is continuous at $x \in (a, b)$

(b) $\lim_{x \rightarrow a^+} f(x) = f(a)$

(c) $\lim_{x \rightarrow b^-} f(x) = f(b)$

$$\text{Ex:- (i) If } f(x) = \begin{cases} \frac{x^2-4}{x-2} & \text{if } x \neq 2 \\ 2 & \text{if } x=2 \end{cases} \quad \text{check its continuity}$$

at $x=2$,

$$\lim_{x \rightarrow 2} f(x) = \lim_{x \rightarrow 2} \left(\frac{x^2-4}{x-2} \right) = \lim_{x \rightarrow 2} \left(\frac{2x}{1} \right) = 4$$

But at $x=2$, $f(x)=2$

∴ $f(x)$ is not continuous at $x=2$.

$$(ii) \text{ If } f(x) = \begin{cases} (1+3x)^{\frac{1}{3x}} & ; x \neq 0 \\ e^x & ; x=0 \end{cases}$$

$$\lim_{x \rightarrow 0} f(x) = \lim_{x \rightarrow 0} (1+3x)^{\frac{1}{3x}} = e^{\lim_{x \rightarrow 0} \frac{1}{3x} (1+3x-1)} = e^{1/3} = e$$

∴ $f(x)$ is continuous at $x=0$.

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Questions:-

$$\text{Ques. 1. If } f(x) = \begin{cases} 0 & ; x=0 \\ \frac{1}{2}-x & ; 0 < x < \frac{1}{2} \\ \frac{1}{2} & ; x=\frac{1}{2} \\ \frac{3}{2}-x & ; \frac{1}{2} < x < 1 \\ 1 & ; x \geq 1 \end{cases}$$

Then which of the following is true :-

- (a) $f(x)$ is right continuous at $x=0$
- (b) $f(x)$ is discontinuous at $x=\frac{1}{2}$
- (c) $f(x)$ is continuous at $x=1$
- (d) b & c

Soln:- (a) $f(0)=0$

2. Differentiation: \rightarrow A fun $f(x)$ is said to be differentiable at a pt.

$x=c$, if $\lim_{x \rightarrow c} \frac{f(x) - f(c)}{x - c}$ exists & finite. & is represented by $f'(c)$.

Left Hand Derivative: $\rightarrow \lim_{h \rightarrow 0} \frac{f(c-h) - f(c)}{-h}$

Right Hand Derivative: $\rightarrow \lim_{h \rightarrow 0} \frac{f(c+h) - f(c)}{h}$

Necessary condⁿ for a fun to be differentiable is $LHD = RHD$.

Note: \rightarrow (i) $f(x) = |x|$ is not differentiable at $x=0$

$$LHD = \lim_{h \rightarrow 0} \frac{f(0-h) - f(0)}{-h} = \lim_{h \rightarrow 0} \frac{|-h| - 0}{-h} = -1$$

$$RHD = \lim_{h \rightarrow 0} \frac{f(0+h) - f(0)}{h} = \lim_{h \rightarrow 0} \frac{|h| - 0}{h} = 1$$

$$\therefore LHD \neq RHD$$

\Rightarrow Not differentiable

(ii) $|x-a|$ is not differentiable at $x=a$.

(iii) $|ax+b|$ is not differentiable at $x=-b/a$.

Question: \rightarrow

1. $f(x) = |x| + |x+1| + |x-2|$ is differentiable at $x = \underline{\hspace{2cm}}$.

- (a) 0 (b) 1 (c) -1 (d) 2

2. Let $f(x) = |x+1|$ be defined in the interval $[0, 4]$ then,

(a) $f(x)$ is continuous & differentiable

(b) $f(x)$ is continuous but non-differentiable

(c) $f(x)$ is not continuous but differentiable

(d) $f(x)$ is neither differentiable nor continuous

3. If $f(x) = |x|^3$ where $x \in \mathbb{R}$, then, $f(x)$ at $x=0$ is _____ 7

- (a) continuous but not differential
- (b) Once differentiable but not twice
- (c) Twice differentiable but not thrice
- (d) Thrice differentiable

Soln:-

$$f(x) = |x|^3 = \begin{cases} x^3 & ; x > 0 \\ -x^3 & ; x < 0 \\ 0 & ; x = 0 \end{cases}$$

$f(0) = 0$, LHL = 0, RHL = 0 \Rightarrow continuous

$$\text{LHD} = \lim_{h \rightarrow 0^-} \frac{f(0-h) - f(0)}{-h} = \lim_{h \rightarrow 0^-} \frac{|-h|^3 - 0}{-h} = 0$$

$$\text{RHD} = \lim_{h \rightarrow 0^+} \frac{f(0+h) - f(0)}{h} = \lim_{h \rightarrow 0^+} \frac{|h|^3 - 0}{h} = 0$$

$\therefore \text{LHD} = \text{RHD} \Rightarrow$ differentiable

$$f'(x) = \begin{cases} 3x^2 & ; x > 0 \\ -3x^2 & ; x < 0 \\ 0 & ; x = 0 \end{cases}$$

$$f''(x) = \begin{cases} 6x & ; x > 0 \\ -6x & ; x < 0 \\ 0 & ; x = 0 \end{cases} = 6|x|$$

$$f'''(x) = \begin{cases} 6 & ; x > 0 \\ -6 & ; x < 0 \\ \text{not diff.} & ; x = 0 \end{cases}$$

4. If $f(x) = \begin{cases} 2+x & x \geq 0 \\ 2-x & x < 0 \end{cases}$ then $f(x)$ at $x=0$ is _____

- (a) Continuous & differentiable
- (b) continuous but not differentiable
- (c) Differentiable but not continuous
- (d) Neither diff. nor continuous

Soln: $\rightarrow f(0) = 2+0 = 2, LHL = 2-0 = 2, RHL = 2+0 = 2 \Rightarrow$ continuous

$$LHD = \lim_{h \rightarrow 0} \frac{[2-(-h)]-2}{-h} = -1 \quad \left. \right\} \text{Non-Differentiable.}$$

$$RHD = \lim_{h \rightarrow 0} \frac{[2+h-2]}{h} = 1 \quad \left. \right\}$$

Note: \rightarrow (i) Every differentiable fun is a continuous fun.

(ii) But every continuous fun is not differentiable.

Mean-Value Theorem:

(i) Rolle's Theorem: \rightarrow Let $f(x)$ be defined in $[a, b]$ s.t. it satisfies

three condn:-

(a) $f(x)$ is continuous fun in $[a, b]$

(b) $f(x)$ is differentiable fun in (a, b)

(c) $f(a) = f(b)$

then, there exists atleast one point $c \in (a, b)$ s.t.

$$f'(c) = 0$$

(ii) Lagrange's Mean Value Theorem: \rightarrow Let $f(x)$ be defined in $[a, b]$

s.t. it satisfies two condn:-

(a) $f(x)$ is continuous fun in $[a, b]$

(b) $f(x)$ is differentiable fun in (a, b)

then, \exists at least one point c in (a, b) s.t. $f'(c) = \frac{f(b) - f(a)}{b - a}$

Note: \rightarrow If $f(x)$ is defined in $[a, a+h]$ s.t.

- (a) $f(x)$ is continuous in $[a, a+h]$
- (b) $f(x)$ is differentiable in $(a, a+h)$

then $\exists \theta \in (0, 1)$ s.t.

$$f(a+h) = f(a) + h f'(a+\theta h)$$

$$\theta = \frac{c-a}{a-b}$$

Questions: \rightarrow

1. The mean-value 'c' for the fun. $f(x) = e^x (\sin x - \cos x)$ in $[\frac{\pi}{4}, \frac{5\pi}{4}]$ is

(a) 0 (b) $\frac{\pi}{3}$

(c) $\frac{\pi}{2}$

(d) π

Soln: $\rightarrow f(\frac{\pi}{4}) = e^{\frac{\pi}{4}} (\sin \frac{\pi}{4} - \cos \frac{\pi}{4}) = 0$

$$f(\frac{5\pi}{4}) = e^{\frac{5\pi}{4}} (\sin \frac{5\pi}{4} - \cos \frac{5\pi}{4}) = 0$$

$$f'(x) = e^x [\cos x + \sin x] + e^x [\sin x - \cos x] = 2e^x \sin x$$

$$\Rightarrow f'(c) = 2e^c \sin c = 0$$

$$\Rightarrow c = 0, \pm \pi, \pm 2\pi, \dots$$

2. The mean-value 'c' for the fun. $f(x) = x^3 - 6x^2 + 11x - 6$ in $[0, 4]$ is

(a) $2 + \frac{2}{\sqrt{3}}$ (b) $2 - \frac{2}{\sqrt{3}}$ (c) $2 \pm \frac{2}{\sqrt{3}}$ (d) None

Soln: $\rightarrow f(0) = -6$

$$f(4) = 64 - 96 + 44 - 6 = 6$$

$$f'(x) = 3x^2 - 12x + 11$$

$$\therefore f'(c) = 3c^2 - 12c + 11 = \frac{f(4) - f(0)}{4 - 0}$$

$$\Rightarrow 12c^2 - 48c + 44 = 12$$

$$\Rightarrow c = 2 \pm \frac{2}{\sqrt{3}}$$

3. The value of ζ of $f(b) - f(a) = (b-a)f'(\zeta)$ for the fun

$f(x) = Ax^2 + Bx + C$, in $[a, b]$ is ____.

(a) $\frac{b+a}{2}$

(b) $\frac{b-a}{2}$

(c) $b-a$

(d) $b+a$

Solⁿ: $f'(x) = 2Ax + B$

$$f'(\zeta) = \frac{f(b) - f(a)}{b-a}$$

$$\Rightarrow 2A\zeta + B = \frac{f(b) - f(a)}{b-a} = \frac{(Ab^2 + Bb + C) - (Aa^2 + Ba + C)}{b-a}$$

$$\Rightarrow 2A\zeta + B = (b+a)A + B$$

$$\Rightarrow \zeta = \frac{b+a}{2}$$

4. The mean-value 'c' for the fun $f(x) = 3x^2 + 5x + 11$ in the $\left[\frac{11}{2}, \frac{16}{2}\right]$ is ____.

Solⁿ: $c = \frac{\frac{11}{2} + \frac{16}{2}}{2} = \frac{27}{4}$

Note: If the fun $f(x)$ is polynomial of degree 2 i.e. quadratic

then, c will be the average value of the extreme value of the fun in given interval i.e. $c = \frac{a+b}{2}$ if $f(x)$ is defined in $[a, b]$.

5. The value of $\theta \in (0, 1)$ for the fun $f(x) = \log x$ in $[1, e]$ using an appropriate mean-value theorem is ____.

Solⁿ: $f'(x) = \frac{1}{x} \Rightarrow f'(c) = \frac{1}{c}$

$$f(1) = \log 1 = 0$$

$$f(e) = \log e = 1$$

$$\therefore \text{Using LMVT, } \frac{1}{c} = \frac{1-0}{e-1} \Rightarrow c = e-1$$

$$\therefore \theta = \frac{c-a}{b-a} = \frac{e-1-1}{e-1} = \frac{e-2}{e-1} \in (0, 1)$$

6. LMVT cannot be applied for $f(x) = x^{1/3}$ in $[-1, 1]$ because

- (a) $f(x)$ is not continuous in $[-1, 1]$
- (b) $f(x)$ is not differentiable in $(-1, 1)$
- (c) a & b
- (d) $f(-1) \neq f(1)$

$$\text{Soln: } f'(x) = \frac{1}{3}x^{-2/3} = \frac{1}{3x^{2/3}}$$

$\therefore f(x)$ is not differentiable at $x=0 \in (-1, 1)$

$$f(0) = 0$$

$$\text{LHL} = \lim_{h \rightarrow 0^-} f(0-h) = \lim_{h \rightarrow 0^-} (-h)^{1/3} = 0$$

$$\text{RHL} = \lim_{h \rightarrow 0^+} f(0+h) = \lim_{h \rightarrow 0^+} h^{1/3} = 0.$$

$$\text{LHL} = \text{RHL} = f(0) = 0 \Rightarrow \text{continuous.}$$

7. Rolle's Theorem cannot be applied for $f(x) = |x+2|$ in $[-2, 0]$.

- (a) $f(x)$ is not continuous in $[-2, 0]$
- (b) $f(x)$ is not differentiable in $(-2, 0)$
- (c) $f(-2) \neq f(0)$
- (d) b & c

8. If $f'(x) = \frac{1}{5-x^2}$ and $f(0) = 1$ then the lower & upper bounds of

$f(1)$ are _____.

Soln: Let $f(x)$ be defined in $[0, 1]$.

By LMVT, $\exists c \in (0, 1)$ st.

$$f'(c) = \frac{f(1) - f(0)}{1 - 0}$$

$$\Rightarrow f'(c) = f(1) - 1$$

$$\min\{f'(x)\} < f'(c) < \max\{f'(x)\} \quad 0 \leq x \leq 1$$

$$\min\{f'(x)\} < f'(c) < \max\{f'(x)\} \quad 0 \leq x \leq 1$$

$$\frac{1}{5} < f(1) - 1 < \frac{1}{4}$$

$$\Rightarrow 1 + \frac{1}{5} < f(1) < 1 + \frac{1}{4}$$

(iii) Cauchy's Mean Value Theorem: → Let $f(x)$ & $g(x)$ be defined in a closed interval $[a, b]$ s.t. they satisfy the cond'':-

(a) $f(x)$ & $g(x)$ are continuous in $[a, b]$

(b) $f(x)$ & $g(x)$ are differentiable in (a, b)

(c) $g'(x) \neq 0$ & $x \in (a, b)$, then,

$$\exists c \in (a, b) \text{ s.t. } \frac{f'(c)}{g'(c)} = \frac{f(b) - f(a)}{g(b) - g(a)}$$

Questions:→

1. The mean-value c for the fun $f(x) = e^x$ & $g(x) = \bar{e}^x$ in $[0, 1]$.

Ans

$$\text{Soln:} \rightarrow f'(x) = e^x \Rightarrow f'(c) = e^c$$

$$g'(x) = -\bar{e}^x \Rightarrow g'(c) = -\bar{e}^c$$

$$\therefore f(1) = e, f(0) = 1$$

$$\therefore g(1) = \frac{1}{e}, g(0) = 1$$

$$\therefore \frac{e^c}{-\bar{e}^c} = \frac{e-1}{(1/e)-1} \Rightarrow -e^{(1+1/e)c} = \frac{[e-1]}{1-e} e$$

$$\Rightarrow +e^{2c} = e \Rightarrow c = \frac{1}{2} \in [0, 1].$$

2. $f(x) = \sin x$ & $g(x) = \cos x$ in $[-\frac{\pi}{2}, 0]$ is _____.

Soln: $\rightarrow f'(x) = \cos x, g'(x) = -\sin x \neq 0 \quad \forall x \in (-\frac{\pi}{2}, 0)$

$$\frac{f'(c)}{g'(c)} = \frac{f(0) - f(-\pi/2)}{g(0) - g(-\pi/2)}$$

$$\Rightarrow \frac{\cos c}{-\sin c} = \frac{0 - (-1)}{1 - 0} \Rightarrow -\cot c = 1 \Rightarrow \cot c = -1$$

$$\Rightarrow c = -\frac{\pi}{4} \in (-\frac{\pi}{2}, 0)$$

(iv)

(iv) Taylor's Theorem: \rightarrow OR (Generalised Mean-Value Theorem)

Let $f(x)$ be defined in $[a, a+h]$. s.t.

(a) $f, f', f'', f''', \dots, f^{n-1}$ are continuous in $[a, a+h]$.

(b) $f, f', f'', \dots, f^{n-1}$ are differentiable in $(a, a+h)$

then $\exists \theta \in (0, 1)$, s.t.

$$f(a+h) = f(a) + h f'(a) + \frac{h^2}{2!} f''(a) + \dots + \frac{h^{n-1}}{(n-1)!} f^{n-1}(a) + R_n$$

$$\text{where } R_n = \frac{h^n}{(n-1)!} (1-\theta)^{n-p} f^n(a+\theta h)$$

for $p=n \rightarrow$ Long Lagrange's form of remainder

$p=1 \rightarrow$ Cauchy's form of remainder

Case I: when $p=n$, $R_n = \frac{h^n}{n!} f^n(a+\theta h)$.

Case II: when $p=1$, $R_n = \frac{h^n}{(n-1)!} (1-\theta)^{n-1} f^n(a+\theta h)$.

Taylor's Series: \rightarrow As $n \rightarrow \infty$, $R_n \rightarrow 0$, then

$$f(a+h) = f(a) + h f'(a) + \frac{h^2}{2!} f''(a) + \frac{h^3}{3!} f'''(a) + \dots$$

(i) $f(x) = f(a) + (x-a) f'(a) + \frac{(x-a)^2}{2!} f''(a) + \dots$ is a Taylor's series expansion of $f(x)$ about $x=a$.

(ii) $f(x) = f(0) + x f'(0) + \frac{x^2}{2!} f''(0) + \dots$ is a Taylor's series

expansion of $f(x)$ about $x=0$. (Maclaurian's Series)

Questions:-

1. The coeff. of x^2 in the Taylor's series expansion of $\cos^2 x$ about

$x=0$ is —

- (a) 0 (b) 1 (c) -1 (d) 2

Solⁿ:→ Coeff. of $x^2 = \frac{f''(0)}{2!} = \frac{-2}{2} = -1$

where, $f'(x) = -\sin 2x$

$f''(x) = -2\cos 2x \Rightarrow f''(0) = -2$

2. The coeff. of $(x-2)^4$ in the Taylor's series expansion of e^x about

$x=2$ is —

- (a) $\frac{e^2}{2!}$ (b) $\frac{e^2}{4!}$ (c) $\frac{e^4}{2!}$ (d) $\frac{e^4}{4!}$

Solⁿ:→ Coeff. of $(x-2)^4 = \frac{f'''(2)}{4!} = \frac{e^2}{4!}$

3. The coeff. of $(x-\pi)^3$ in the power series expansion of $e^x + \sin x$

in the ascending power of $(x-\pi)$ is —

- (a) $\frac{e^\pi}{6}$ (b) $\frac{e^\pi+1}{3}$ (c) $\frac{e^\pi-1}{3}$ (d) None

Solⁿ:→ Coeff. of $(x-\pi)^3 = \frac{f^3(\pi)}{3!} = \frac{e^\pi+1}{6}$

where, $f'(x) = e^x + \cos x$

$f''(x) = e^x - \sin x$

$f'''(x) = e^x - \cos x \Rightarrow f^3(\pi) = e^\pi + 1$

4. Which of the following fun would have only odd powers of x in its Taylor's Series expansion about $x=0$,

- (a) $\sin x^2$ (b) $\cos x^2$ (c) $\cos x^3$ (d) $\sin x^3$

$$\text{Soln: } \cos t = 1 - \frac{t^2}{2!} + \frac{t^4}{4!} - \dots$$

$$\sin t = t - \frac{t^3}{3!} + \frac{t^5}{5!} - \dots$$

5. The Taylor's Series expansion of $f(x) = \tan^{-1}x$ about $x=0$ is _____.

$$\text{Soln: } f(x) = f(0) + x f'(0) + \frac{x^2}{2!} f''(0) + \dots$$

$$f(x) = \tan^{-1}x$$

$$f(0) = \tan^{-1}0 = 0$$

$$f'(x) = \frac{1}{1+x^2} \Rightarrow f'(0) = 1$$

$$f''(x) = \frac{-2x}{(1+x^2)^2} \Rightarrow f''(0) = 0$$

$$f'''(x) = -2 \left[\frac{(1+x^2)^2 + x \cdot 2(1+x^2) \cdot 2x}{(1+x^2)^4} \right] = -2 \left[\frac{1+x^2 - 2x^2}{(1+x^2)^3} \right] = -2 \left[\frac{1-3x^2}{(1+x^2)^3} \right]$$

$$\Rightarrow f'''(0) = -2$$

$$\therefore \tan^{-1}x = x - \frac{2x^3}{3!} + \dots$$

$$= x - \frac{x^3}{3} + \frac{x^5}{5} - \dots$$

6. The power series expansion of $\frac{\sin x}{x-\pi}$ about $x=\pi$ is _____.

$$\text{Soln: } \text{Let, } x-\pi = t, \text{ then } f = \frac{\sin(\pi+t)}{t} \text{ about } t=0$$

$$= -\frac{\sin t}{t} \text{ about } t=0$$

$$= -\frac{1}{t} \left[t - \frac{t^3}{3!} + \frac{t^5}{5!} - \frac{t^7}{7!} + \dots \right]$$

$$= -1 + \frac{t^2}{2!} - \frac{t^4}{4!} + \frac{t^6}{6!} - \dots$$

$$= -1 + \frac{(x-\pi)^2}{2!} - \frac{(x-\pi)^4}{4!} + \frac{(x-\pi)^6}{6!} - \dots$$

7. For the fun e^{-x} , linear approximation around $x=2$ is _____.

- (a) $(3-x)e^{-2}$ (b) $(1-x)e^{-2}$ (c) $[\sqrt{3} + 2\sqrt{2} - (1+\sqrt{2})x]e^{-2}$

Soln: $\rightarrow f(x) = \underbrace{f(a) + (x-a)f'(a)}_{\text{Linear approx.}} + \frac{(x-a)^2}{2!} f''(a) + \dots$

$$\therefore e^{-x} = f(2) + (x-2) \left. \frac{d}{dx} e^{-x} \right|_{x=2} = e^{-2} + (x-2)(-1)e^{-2} \\ = e^{-2}(3-x)$$

3. Definite Integrals: \rightarrow

Theorem: \rightarrow Let $f(x)$ is a continuous fun defined in $[a, b]$ & $F(x)$ be the anti-derivative of $f(x)$ then $\int_a^b f(x) dx = F(b) - F(a)$.

Note: $\rightarrow \frac{d}{dx} \left[\int_{u(x)}^{v(x)} f(x) dx \right] = f(v) \frac{dv}{dx} - f(u) \frac{du}{dx}$

Properties of Definite Integrals: \rightarrow

$$(i) \int_a^b f(x) dx = - \int_b^a f(x) dx$$

$$(ii) \text{ If } c \in (a, b) \text{ then, } \int_a^b f(x) dx = \int_a^c f(x) dx + \int_c^b f(x) dx$$

$$(iii) \int_0^a f(x) dx = \int_0^a f(a-x) dx$$

$$(iv) \int_a^b \frac{f(x)}{f(x)+f(a+b-x)} dx = \frac{b-a}{2}$$

$$(v) \int_{-a}^a f(x) dx = \begin{cases} 2 \int_0^a f(x) dx & ; \text{ if } f(x) \text{ is even} \\ 0 & ; \text{ if } f(x) \text{ is odd} \end{cases}$$

$$(vi) \int_0^{2a} f(x) dx = \begin{cases} 2 \int_0^a f(x) dx & ; \text{ if } f(2a-x) = f(x) \\ 0 & ; \text{ if } f(2a-x) = -f(x) \end{cases} \quad 12$$

$$(vii) \int_0^a x f(x) dx = \frac{a}{2} \int_0^a f(x) dx ; \text{ if } f(a-x) = f(x)$$

$$(viii) \int_0^{na} f(x) dx = n \int_0^a f(x) dx ; \text{ if } f(x+a) = f(x)$$

$$(ix) \int_0^{\pi/2} \sin^n x dx = \int_0^{\pi/2} \cos^n x dx = \left[\frac{n-1}{n} \times \frac{n-3}{n-2} \times \dots \times \frac{2}{3} (or) \frac{1}{2} \right] K$$

$$\text{where, } K = \begin{cases} 1 & ; \text{ if } n \text{ is odd} \\ \frac{\pi}{2} & ; \text{ if } n \text{ is even} \end{cases}$$

$$(x) \int_0^{\pi/2} \sin^m x \cos^n x dx = \left\{ \frac{[(m-1)(m-3) \dots 2(0r)1][(n-1)(n-3) \dots 2(0r)1]}{[(m+n)(m+n-2) \dots 2(0r)1]} \right\}$$

$$\text{where, } K = \begin{cases} \frac{\pi}{2} & ; \text{ when } m \text{ & } n \text{ are even} \\ 0 & ; \text{ otherwise} \end{cases}$$

Questions: →

$$1. \int_0^{\pi/2} \frac{\tan x}{\tan x + \cot x} dx = \underline{\hspace{2cm}}$$

$$\text{Sol:} \rightarrow \text{let } f(x) = \tan x \Rightarrow f(0 + \frac{\pi}{2} - x) = \cot x$$

$$2. I = \int_0^{\pi/2} \frac{f(x)}{f(x) + f(0 + \frac{\pi}{2} - x)} dx = \frac{\frac{\pi}{2} - 0}{2} = \frac{\pi}{4}$$

2. $\int_0^{\pi/2} \frac{dx}{1 + \sqrt{\cot x}}$ is _____.

Solⁿ:→ $I = \int_0^{\pi/2} \frac{\sqrt{\sin x}}{\sqrt{\sin x} + \sqrt{\cos x}} dx = \frac{\frac{\pi}{2} - 0}{2} = \frac{\pi}{4}$

3. $\int_2^3 \frac{\sqrt{x}}{\sqrt{x} + \sqrt{5-x}} dx$ is _____.

Solⁿ:→ $I = \frac{3-2}{2} = \frac{1}{2}$

4. $\int_0^{\pi} |\cos x| dx$ is _____.

(a) 1 (b) 0 (c) 2 (d) None.

Solⁿ:→ $I = \int_0^{\pi/2} \cos x dx + \int_{\pi/2}^{\pi} -\cos x dx$
 $= \sin x \Big|_0^{\pi/2} - \sin x \Big|_{\pi/2}^{\pi}$
 $= 1 - (-1) = 2$

5. $\int_0^4 (|x| + |3-x|) dx$ is _____.

Solⁿ:→ $I = \int_0^4 x dx + \int_0^3 (3-x) dx + \int_3^4 (x-3) dx$
 $= \frac{x^2}{2} \Big|_0^4 + \left[3x - \frac{x^2}{2} \right]_0^3 + \left[\frac{x^2}{2} - 3x \right]_3^4$
 $= 8 + \left[9 - \frac{9}{2} \right] + \left[8 - 12 - \frac{9}{2} + 9 \right]$
 $= 34 - 21$

= 13

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6. $\int_0^n [x] dx$ is ____.

- (a) $\frac{n(n+1)}{2}$ (b) $\frac{n(n-1)}{2}$ (c) $\frac{n}{2}$ (d) None.

Solⁿ: $I = \int_0^1 0 \cdot dx + \int_1^2 1 \cdot dx + \int_2^3 2 \cdot dx + \dots + \int_{n-1}^n (n-1) \cdot dx$

$$= 0 + [2-1] + 2[3-2] + \dots + (n-1)[n-n+1]$$

$$= 1 + 2 + \dots + (n-1)$$

$$= \frac{n(n-1)}{2}$$

7. $\int_0^1 x(1-x)^5 dx$ is ____.

- (a) $\frac{1}{42}$ (b) $\frac{1}{30}$ (c) $\frac{1}{24}$ (d) None.

Solⁿ: $\int_0^a f(x) dx = \int_0^a f(a-x) dx$

$$\int_0^1 x(1-x)^5 dx = \int_0^1 (1-x)x^5 dx = \left[\frac{x^6}{6} \right]_0^1 - \left[\frac{x^7}{7} \right]_0^1 = \frac{1}{42}$$

8. $\int_0^{\pi/2} \log(\tan x) dx$ is ____.

Solⁿ: Replace x by $(\frac{\pi}{2}-x)$.

$$I = \int_0^{\pi/2} \log \cot x$$

$$2I = \int_0^{\pi/2} [\log \tan x + \log \cot x] dx = \int_0^{\pi/2} \log [\tan x \cdot \cot x] dx = 0$$

$$\Rightarrow I = 0.$$

9. $\int_0^{\pi/4} \log(1+\tan x) dx$ is _____.

- (a) $\frac{\pi}{8} \log 2$ (b) $\frac{\pi}{4} \log 2$ (c) $\frac{\pi}{2} \log 2$ (d) None

Solⁿ: $I = \int_0^{\pi/4} \log(1+\tan(\frac{\pi}{4}-x)) dx$

$$= \int_0^{\pi/4} \log\left(1 + \frac{1-\tan x}{1+\tan x}\right) dx$$

$$= \int_0^{\pi/4} \log\left(\frac{2}{1+\tan x}\right) dx$$

$$= \int_0^{\pi/4} [\log 2 - \log(1+\tan x)] dx = \int_0^{\pi/4} \log 2 dx - \underbrace{\int_0^{\pi/4} \log(1+\tan x) dx}_I$$

$$\Rightarrow 2I = \int_0^{\pi/4} \log 2 dx = \frac{\pi}{4} \log 2$$

$$\Rightarrow I = \frac{\pi}{8} \log 2$$

10. $\int_{-1}^1 \frac{|x|}{x} dx$ is _____.

Solⁿ: $I = 0$ (Odd fun)

11. $\int_{-\pi}^{\pi} \log \frac{(1+\sin x)}{(1-\sin x)} dx$ is _____.

Solⁿ: $f(-x) = \log \frac{(1-\sin x)}{(1+\sin x)} = -\log \frac{(1+\sin x)}{(1-\sin x)} = -f(x) \Rightarrow$ odd fun

$\therefore I = 0$.

12. $\int_0^{\pi} \frac{x \sin x}{1+\cos^2 x} dx$ is _____.

Solⁿ: $\int_0^a x f(x) dx = \frac{a}{2} \int_0^a f(x) dx$, if $f(a-x) = f(x)$

$$f(\pi-x) = \frac{\sin x}{1+\cos^2 x} = f(x)$$

$$\therefore I = \frac{\pi}{2} \int_0^\pi \frac{\sin x}{1+\cos^2 x} dx$$

$$\text{Put, } \cos x = t \Rightarrow -\sin x dx = dt$$

$$\Rightarrow I = \frac{\pi}{2} \int_{-1}^1 \frac{-dt}{1+t^2} = -\frac{\pi}{2} [\tan^{-1} t]_{-1}^1 = -\frac{\pi}{2} [\tan^{-1}(-1) - \tan^{-1}(1)]$$

$$= -\frac{\pi}{2} \left[-\frac{\pi}{4} - \frac{\pi}{4} \right] = \frac{\pi^2}{4}$$

13. $\int_0^\pi \frac{dx}{a^2 \cos^2 x + b^2 \sin^2 x}$ is _____.

(a) $\frac{\pi}{ab}$

(b) πab

(c) $\frac{2\pi}{ab}$

(d) None

Soln: $I = \int_0^\pi \frac{\sec^2 x dx}{a^2 + b^2 \tan^2 x}$

$$\int_0^{2a} f(x) dx = \begin{cases} 2 \int_0^a f(x) dx & \text{if, } f(2a-x) = f(x) \\ 0 & \text{if, } f(2a-x) = -f(x) \end{cases}$$

~~$f(\pi-x) = f(x)$~~

$$\therefore I = 2 \int_0^{\pi/2} \frac{\sec^2 x}{a^2 + b^2 \tan^2 x} dx$$

$$\text{Let, } \tan x = t$$

$$\sec^2 x dx = dt$$

$$\therefore I = 2 \int_0^\infty \frac{dt}{a^2 + (bt)^2} = 2 \times \frac{1}{a} \left[\frac{\tan^{-1}(bt/a)}{b} \right]_0^\infty = \frac{2}{ab} \left[\frac{\pi}{2} - 0 \right] = \frac{\pi}{ab}$$

14. If $f(t)$ is a continuous fun defined in $[0, 1]$ then $\lim_{t \rightarrow 0} \frac{1}{t} \int_0^t f(t) dt$

- (a) 0 (b) ∞ (c) $f(0)$ (d) $f(1)$

Soln: $\lim_{t \rightarrow 0} \frac{\int_0^t f(t) dt}{t} = \lim_{t \rightarrow 0} \frac{\frac{d}{dt} \left\{ \int_0^t f(t) dt \right\}}{t}$

$$= \lim_{t \rightarrow 0} [f(t) \times 1 - f(0) \times 0]$$

$$= f(0)$$

15. $\int_0^{\pi/2} \sin^8 x dx$

Soln: $I = \frac{7}{8} \times \frac{5}{6} \times \frac{3}{4} \times \frac{1}{2} \times \frac{\pi}{2}$

16. $\int_0^{\pi/2} \cos^7 x dx$

Soln: $I = \frac{6}{7} \times \frac{4}{5} \times \frac{2}{3} \times 1$

17. $\int_0^{\pi/2} \sin^5 x \cos^9 x dx$

Soln: $I = \frac{(4 \times 2) \times (8 \times 6 \times 4 \times 2)}{14 \times 12 \times 10 \times 8 \times 6 \times 4 \times 2} \times 1$

18. $\int_0^{\pi/2} \sin^6 x \cos^3 x dx$

Soln: $I = \frac{(5 \times 3 \times 1) \times (2)}{9 \times 7 \times 5 \times 3 \times 1} \times 1$

19. $\int_0^{\pi/2} \sin^5 x \cos^8 x dx$

Soln: $I = \frac{(4 \times 2) \times (7 \times 5 \times 3 \times 1)}{13 \times 11 \times 9 \times 7 \times 5 \times 3 \times 1} \times 1$

$$20. \int_0^{\pi/2} \sin^6 x \cdot \cos^8 x \, dx = \dots$$

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$$\text{Soln: } I = \frac{(5 \times 3 \times 1) (7 \times 5 \times 3 \times 1)}{14 \times 12 \times 10 \times 8 \times 6 \times 4 \times 2} \times \frac{\pi}{2} =$$

$$21. \int_{-\pi}^{\pi} \sin^4 x \, dx = \dots$$

$$\text{Soln: } I = 2 \int_0^{\pi} \sin^4 x \, dx$$

$$\int_0^{2a} f(x) \, dx = \begin{cases} 2 \int_0^a f(x) \, dx & ; \text{ if } f(2a-x) = f(x) \\ & ; \text{ if } f(2a-x) = -f(x) \end{cases}$$

$$\therefore \sin^4(\pi-x) = \sin^4 x$$

$$\therefore I = 2 \times 2 \times \int_0^{\pi/2} \sin^4 x \, dx = 4 \times \frac{3}{4} \times \frac{1}{2} \times \frac{\pi}{2} =$$

$$22. \int_0^{\pi} \sin^4 x \cos^3 x \, dx = \dots$$

$$\text{Soln: } f(\pi-x) = \sin^4 x (-\cos x)^3 = -f(x)$$

$$\therefore I = 0.$$

$$23. \int_0^{\pi} \sin^3 x \cos^4 x \, dx = \dots$$

$$\text{Soln: } f(\pi-x) = \sin^3 x \cos^4 x = f(x)$$

$$\therefore I = 2 \int_0^{\pi/2} \sin^3 x \cos^4 x \, dx = 2 \times \frac{(2 \times 3 \times 1)}{7 \times 5 \times 3 \times 1} \times 1 =$$

$$24. \int_{-\frac{2\pi}{3}}^{\frac{2\pi}{3}} \sin^4 x \cos^8 x \, dx$$

$$\text{Soln: } I = 2 \int_0^{\frac{\pi}{2}} \sin^4 x \cos^8 x \, dx = 2 \times 2 \times \int_0^{\frac{\pi}{2}} \sin^4 x \cos^8 x \, dx \\ = 2 \times 2 \times 2 \times \int_0^{\frac{\pi}{2}} \sin^4 x \cos^8 x \, dx \\ = 8 \times \frac{(3 \times 1) \times (7 \times 5 \times 3 \times 1)}{12 \times 10 \times 8 \times 6 \times 4 \times 2} \times \frac{\pi}{2}$$

$$\text{Note: } \int_a^b \sin^4 x \cos^8 x \, dx = K \int_0^{\frac{\pi}{2}} \sin^4 x \cos^8 x \, dx$$

$$\text{where, } K = \frac{b-a}{\frac{\pi}{2}}$$

$$25. \int_0^{\frac{\pi}{2}} \sin x \cos^3 x \, dx$$

Soln: Let $\sin x = t \Rightarrow \cos x \, dx = dt$

$$I = \int_0^1 \sqrt{t} (1-t^2) \, dt = \frac{t^{3/2}}{3/2} \Big|_0^1 - \frac{t^3}{3} \Big|_0^1 = \frac{2}{3} - \frac{2}{7} =$$

Improper Integrals:

First Kind: $\int_a^b f(x) \, dx$ if $a = -\infty$ (or) $b = \infty$ (or) both

$$\text{e.g. } \int_{-\infty}^b f(x) \, dx, \int_a^{\infty} f(x) \, dx, \int_{-\infty}^{\infty} f(x) \, dx$$

Second Kind: $\rightarrow \int_a^b f(x) dx$ if $a \leq b$ are finite but $f(x)$ is infinite for some $x \in [a, b]$. (10)

$$\text{Ex: } \int_{-1}^1 \log(1+x) dx, \quad \int_0^1 \frac{1+x}{1-x} dx, \quad \int_0^3 \frac{1}{x^2 - 5x + 4} dx$$

Convergence of an Improper Integrals:

(i) If $\int_a^b f(x) dx = \text{finite}$, then, it is a convergent improper integral.

(ii) If $\int_a^b f(x) dx = \text{infinite}$, then, it is a divergent improper integral.

Questions:

1. Find the convergence of following improper integrals

$$(i) \int_0^\infty \frac{1}{a^2 + x^2} dx$$

$$\text{Soln: } I = \frac{1}{a} \tan^{-1} \frac{x}{a} \Big|_0^\infty = \frac{1}{a} \left[\frac{\pi}{2} - 0 \right] = \frac{\pi}{2a} = \text{finite}$$

which is convergent.

$$(ii) \int_0^\infty x \sin x dx$$

$$\text{Soln: } I = x \left[(-\cos x) - (1) [-\sin x] \right] \Big|_0^\infty = \text{infinite}$$

which is divergent improper integral.

$$(iii) \int_{-\infty}^0 e^{ax} \cos px dx = \underline{\hspace{2cm}}$$

$$\text{Soln: } \int e^{ax} \cos bx dx = \frac{e^{ax}}{a^2 + b^2} [a \cos bx + b \sin bx]$$

$$\therefore I = \left[\frac{e^{ax}}{a^2 + p^2} [a \cos px + p \sin px] \right]_0^\infty$$

$$= \frac{a}{a^2 + p^2} - 0 = \text{finite}$$

i.e. convergence

$$(iv) \int_{-1}^1 \frac{1+x}{\sqrt{1-x^2}} dx$$

$$\begin{aligned} \text{Soln: } I &= \int_{-1}^1 \frac{1+x}{\sqrt{1-x^2}} dx = \int_{-1}^1 \frac{1}{\sqrt{1-x^2}} dx + \int_{-1}^1 \frac{x}{\sqrt{1-x^2}} dx \\ &= 2 \int_0^1 \frac{1}{\sqrt{1-x^2}} dx + 0 \end{aligned}$$

$$= 2 \left[\sin^{-1} x \right]_0^1 = 2 \cdot \frac{\pi}{2} = \pi = \text{finite}$$

i.e. convergent improper integral.

$$(v) \int_{-1}^1 \frac{1}{x^2} dx = \underline{\hspace{2cm}}$$

$$\text{Soln: } I = \int_{-1}^0 \frac{1}{x^2} dx + \int_0^1 \frac{1}{x^2} dx = \left[-\frac{1}{x} \right]_{-1}^0 + \left[-\frac{1}{x} \right]_0^1 = \text{infinite}$$

i.e. divergent improper integral

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$$(v) \int_0^3 \frac{1}{x^2 - 3x + 2} dx$$

$$\text{Soln: } \rightarrow 1 = \int_0^3 \frac{1}{(x-1)(x-2)} dx = \int_0^1 \frac{dx}{(x-1)(x-2)} + \int_1^2 \frac{dx}{(x-1)(x-2)} + \int_2^3 \frac{dx}{(x-1)(x-2)}$$

$$\int \frac{dx}{(x-1)(x-2)} = \int \frac{dx}{x-2} - \int \frac{dx}{x-1} = \log \left(\frac{x-2}{x-1} \right)$$

$$\therefore 1 = \log \left(\frac{x-2}{x-1} \right) \Big|_0^1 + \log \left(\frac{x-2}{x-1} \right) \Big|_1^2 + \log \left(\frac{x-2}{x-1} \right) \Big|_2^3 = \text{infinite}$$

i.e., divergent improper integral

Comparison Test:

for first kind of improper integrals:

(a) Let $0 \leq f(x) \leq g(x)$, then,

(i) $\int_a^b f(x) dx$ converges if $\int_a^b g(x) dx$ is convergent

(ii) $\int_a^b g(x) dx$ diverges if $\int_a^b f(x) dx$ is divergent

(b) Limit form: let $f(x)$ & $g(x)$ be two positive fun s.t.

$\lim_{x \rightarrow \infty} \frac{f(x)}{g(x)} = k$ (non-zero, finite) then $\int_a^b f(x) dx$ &

$\int_a^b g(x) dx$ both convergent or divergent together.

Question:

$$1. \int_1^\infty e^{-x^2} dx =$$

$$\text{Soln: } e^{x^2} \geq e^x \quad \forall x \geq 1$$

$$\Rightarrow e^{-x^2} \leq e^{-x} \quad \forall x \geq 1$$

$$\int_1^\infty e^{-x} dx = \left[-e^{-x} \right]_1^\infty = 1 \Rightarrow \int_1^\infty e^{-x} dx \text{ is convergent}$$

$\therefore \int_1^\infty e^{-x^2} dx$ is also convergent.

$$2. \int_2^\infty \frac{1}{\log x} dx$$

$$\text{Soln: } \log x < \infty \quad \forall x \geq 2$$

$$\Rightarrow \frac{1}{\log x} \geq \frac{1}{x} \quad \forall x \geq 2$$

$$\int_2^\infty \frac{1}{x} dx = \left[\log x \right]_2^\infty = \infty \Rightarrow \text{divergent}$$

$\therefore \int_2^\infty \frac{dx}{\log x}$ is also divergent.

$$3. \int_1^\infty \frac{1}{x^2(e^{-x}+1)} dx$$

$$\text{Soln: } x^2(e^{-x}+1) > x^2(0+1) \quad \forall x > 1$$

$$\Rightarrow \frac{1}{x^2(e^{-x}+1)} < \frac{1}{x^2} \quad \forall x > 1$$

} Method-1

$$\text{Method-II: Let } g(x) = x^2, \quad \frac{f(x)}{g(x)} = \frac{1}{e^{-x}+1}$$

so that, $\lim_{x \rightarrow \infty} \frac{f(x)}{g(x)} = 1$ thus, $g(x)$ will gives the nature of $f(x)$.

$$\therefore \int_1^\infty \frac{1}{x^2} dx = \left[-\frac{1}{x} \right]_1^\infty = 1 \Rightarrow \text{convergent}$$

Hence, $f(x)$ is also convergent.

$$Q. 4. \int_1^{\infty} \frac{x \tan^{-1} x}{\sqrt{4+x^3}} dx$$

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$$\text{Soln: } \rightarrow f(x) = \frac{x \tan^{-1} x}{x \sqrt{x} \sqrt{\frac{4}{x^3} + 1}} = \frac{\tan^{-1} x}{\sqrt{x} \sqrt{\frac{4}{x^3} + 1}}$$

$$\text{let } g(x) = \frac{1}{\sqrt{x}}$$

$$\frac{f(x)}{g(x)} = \frac{\tan^{-1} x}{\sqrt{\frac{4}{x^3} + 1}} \Rightarrow \lim_{x \rightarrow \infty} \frac{f(x)}{g(x)} = \pi/2$$

$$\int_1^{\infty} \frac{1}{\sqrt{x}} dx = 2\sqrt{x} \Big|_1^{\infty} = \text{infinite} \Rightarrow \text{divergent}$$

$\therefore f(x)$ is also divergent

Comparison Test for the second kind of improper integral :-

(b) Limit form: Let $f(x)$ & $g(x)$ be two +ve fun s.t.

(i) 'a' is a point of discontinuity and $\lim_{x \rightarrow a^+} \frac{f(x)}{g(x)} = l_1$
(non-zero & finite).

(ii) 'b' is a point of discontinuity and $\lim_{x \rightarrow b^-} \frac{f(x)}{g(x)} = l_2$
(non-zero & finite).

then, $\int_a^b f(x) dx$ & $\int_a^b g(x) dx$ both converge (or) diverge together.

Questions: →

$$1. \int_0^{\pi/2} \frac{\sin x}{x\sqrt{x}} dx \quad \dots$$

Soln: → $\frac{\sin x}{x} \leq 1 \quad \forall x > 0$

$$\Rightarrow \frac{\sin x}{x\sqrt{x}} \leq \frac{1}{\sqrt{x}} \quad \forall x > 0$$

$$\int_0^{\pi/2} \frac{1}{\sqrt{x}} dx = 2\sqrt{x} \Big|_0^{\pi/2} = 2\sqrt{\frac{\pi}{2}} = \text{finite} \Rightarrow \text{convergent}$$

∴ $\int_0^{\pi/2} \frac{\sin x}{x\sqrt{x}} dx$ is also convergent

$$2. \int_1^2 \frac{\sqrt{x}}{\log x} dx \quad \dots$$

Soln: → $\frac{1}{\log x} > \frac{1}{x} \quad \forall x > 1$

$$\Rightarrow \frac{\sqrt{x}}{\log x} > \frac{1}{\sqrt{x}} \quad \forall x > 1$$

$$\int_1^2 \frac{1}{\sqrt{x}} dx = 2\sqrt{x} \Big|_1^2 = 2\sqrt{2} - 2 = \text{finite} \Rightarrow \text{convergent}$$

∴ $\int_1^2 \frac{\sqrt{x}}{\log x} dx$ may/may not be convergent.

Thus, first method fails.

$$\lim_{x \rightarrow 1^+} \frac{f(x)}{g(x)} = 1$$

Let, $g(x) = \frac{1}{x \log x}$

$$\Rightarrow \frac{f(x)}{g(x)} = x \sqrt{x}$$

$$\int_1^2 \frac{1}{x \log x} dx ; \text{ Put } \log x = t$$

$$\Rightarrow \frac{1}{x} dx = dt$$

$$\int_1^2 \frac{1}{x \log x} dx = \int_0^{\log 2} \frac{1}{t} dt = \log t \Big|_0^{\log 2} = \text{infinite} \Rightarrow \text{divergent}$$

$\therefore \int_1^2 \frac{\sqrt{x}}{\log x} dx$ is also divergent

3. Which of the following fun is strictly bounded :-

- (a) x^2 (b) e^x (c) $\frac{1}{x}$ (d) e^{-x^2}

4. Which of the following integrals is unbounded :-

- (a) $\int_0^{\pi/4} \tan x dx$ (b) $\int_0^{\infty} \frac{1}{1+x^2} dx$ (c) $\int_0^1 \frac{1}{1-x} dx$ (d) $\int_0^{\infty} x e^{-x} dx$

Soln:— (a) $I = \log \sec x \Big|_0^{\pi/4} = \log \sqrt{2}$

(b) $I = \tan^{-1} x \Big|_0^{\infty} = \pi/2$

(c) $I = -\log(1-x) \Big|_0^1 = \text{infinite}$

(d) $I = x \frac{e^{-x}}{-1} \Big|_0^{\infty} - (1) \frac{e^{-x}}{(-1)^2} \Big|_0^{\infty} = 1$

5. Consider the integrals $I_1 = \int_1^{\infty} \frac{1}{x^2(e^x+1)} dx$ & $I_2 = \int_1^{\infty} \frac{x+1}{x \sqrt{x}} dx$

then which of the following is true :-

- (a) I_1 & I_2 are convergent ~~(b) I_1 & I_2 are divergent~~

- (b) I_1 is convergent, I_2 is divergent

- (c) I_1 is divergent, I_2 is convergent

- (d) I_1 & I_2 are divergent

$$\text{Soln: } x^2(e^x+1) > x^2(0+1) \quad \forall x \geq 1$$

$$\Rightarrow \frac{1}{x^2(e^x+1)} < \frac{1}{x^2} \quad \forall x \geq 1$$

$$\int_1^\infty \frac{1}{x^2} dx = -\frac{1}{x} \Big|_1^\infty = 1 \Rightarrow \text{convergent}$$

$\therefore I_1$ is convergent.

$$I_2 = \int_1^\infty \frac{x}{x\sqrt{x}} dx + \int_1^\infty \frac{1}{x\sqrt{x}} dx = \int_1^\infty \frac{1}{\sqrt{x}} dx + \int_1^\infty \frac{1}{x\sqrt{x}} dx$$

$$\downarrow$$

$$2\sqrt{x} \Big|_1^\infty \Rightarrow \text{Divergent}$$

$\therefore I_2$ is divergent.

6. Consider, $I_1 = \int_0^1 \frac{1}{x^{1/3}} dx, I_2 = \int_1^\infty \frac{1}{x} dx, I_3 = \int_0^1 x \log x dx$

then, which of the following is convergent:-

(a) $I_1 \& I_2$

(b) $I_2 \& I_3$

(c) $I_1 \& I_3$

(d) Only I_1

$$\text{Soln: } I_1 = \left. \frac{x^{2/3}}{2/3} \right|_0^1 = \text{finite}$$

$$I_2 = \int_0^\infty \frac{1}{x} dx + \int_0^\infty \frac{1}{x} dx = \log x \Big|_1^\infty + \log x \Big|_0^\infty = \text{infinite}$$

$$I_3 = \left. \log x \cdot \frac{x^2}{2} \right|_0^1 - \int_0^1 \frac{1}{x} \cdot \frac{x^2}{2} dx = \left[\frac{x^2}{2} \log x - \frac{x^2}{4} \right]_0^1$$

$$= -\frac{1}{4} - \left[\lim_{x \rightarrow 0} \frac{x^2 \log x}{2} \right]$$

$$\lim_{x \rightarrow 0} \frac{\log x}{2/x^2} = \lim_{x \rightarrow 0} \frac{1/x}{-4/x^3} = \lim_{x \rightarrow 0} -\frac{x^2}{4} = 0 \quad 20$$

$\therefore I_3 = \text{finite}$

Gamma Function: \rightarrow

$$\Gamma(n) = \int_0^\infty e^{-x} x^{n-1} dx \quad (n > 0)$$

Note: \rightarrow (i) $\Gamma(1) = 1$

$$(ii) \Gamma(\frac{1}{2}) = \sqrt{\pi}$$

$$(iii) \Gamma(n+1) = n\Gamma(n) \quad \forall n > 0$$

$$(iv) \Gamma(n+1) = n! \quad \forall n \in \mathbb{Z}^+$$

$$(v) \int_0^\infty e^{-ax} x^{n-1} dx = \frac{\Gamma(n)}{a^n}$$

Questions: \rightarrow

$$1. \int_0^\infty e^{-x^2} dx = \underline{\hspace{2cm}}$$

$$\text{Sol'n:} \rightarrow \text{Let } x^2 = t \Rightarrow 2x dx = dt \Rightarrow dx = \frac{1}{2} t^{-\frac{1}{2}} dt$$

$$\therefore I = \int_0^\infty e^{-t} \cdot \frac{1}{2} t^{-\frac{1}{2}} dt = \frac{1}{2} \int_0^\infty e^{-t} t^{\frac{1}{2}-1} dt = \frac{1}{2} \Gamma(\frac{1}{2}) = \frac{\sqrt{\pi}}{2}$$

$$\text{Note:} \rightarrow \int_{-\infty}^\infty e^{-x^2} dx = 2 \int_0^\infty e^{-x^2} dx = \sqrt{\pi}$$

$$2. \int_0^\infty e^{-2x^2} x^7 dx = \underline{\hspace{2cm}}$$

$$\text{Sol'n:} \rightarrow \text{Let } 2x^2 = t \Rightarrow 4x dx = dt$$

$$\therefore I = \int_0^\infty e^{-t} \left(\frac{t}{2}\right)^3 \frac{dt}{4} = \frac{1}{32} \int_0^\infty e^{-t} t^3 dt = \frac{1}{32} \Gamma(4) = \frac{3!}{32} = \frac{6}{32} = \frac{3}{16}$$

$$3. \int_0^1 (x \log x)^4 dx = \underline{\hspace{2cm}}$$

Soln: Let, $\log x = -t \Rightarrow x = e^{-t} \Rightarrow dx = -e^{-t} dt$

$$\therefore I = \int_{-\infty}^0 [e^{-t}(-t)]^4 (-e^{-t}) dt = \int_0^\infty e^{-st} t^{5-1} dt = \frac{\sqrt{5}}{5^5} = \frac{4!}{5^5}$$

$$4. \int_0^\infty \frac{-4x^2}{5} dx = \underline{\hspace{2cm}}$$

$$\text{Soln:} \text{ Let, } 5^{-4x^2} = e^{-t} \Rightarrow -4x^2 \log 5 = -t \Rightarrow x = \frac{1}{2\sqrt{\log 5}} t \Rightarrow dx = \frac{1}{2\sqrt{\log 5}} \frac{1}{2t} dt$$

$$\begin{aligned} I &= \int_0^\infty e^{-t} \cdot \frac{1}{2\sqrt{\log 5}} \cdot \frac{t^{-\frac{1}{2}}}{2} dt = \frac{1}{4\sqrt{\log 5}} \int_0^\infty e^{-t} t^{\frac{1}{2}-1} dt \\ &= \frac{\sqrt{\pi}}{4\sqrt{\log 5}} \end{aligned}$$

$$\text{Note:} \log a^0 = \begin{cases} \infty &; a < 1 \\ -\infty &; a > 1 \end{cases}$$

Beta function: →

$$\beta(m, n) = \int_0^1 x^{m-1} (1-x)^{n-1} dx \quad (m > 0, n > 0)$$

$$\text{Note:} (i) \beta(m, n) = \beta(n, m)$$

$$(ii) \beta(m, n) = \frac{\Gamma(m) \Gamma(n)}{\Gamma(m+n)}$$

$$(iii) \beta(m, n) = \int_0^\infty \frac{x^{m-1}}{(1+x)^{m+n}} dx = \int_0^\infty \frac{x^{n-1}}{(1+x)^{m+n}} dx$$

$$(iv) \beta(m, n) = 2 \int_0^{\pi/2} \sin^{2m-1}\theta \cos^{2n-1}\theta d\theta$$

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$$\text{i.e. } \int_0^{\pi/2} \sin^p \theta \cos^q \theta d\theta = \frac{1}{2} \beta\left(\frac{p+1}{2}, \frac{q+1}{2}\right)$$

$$(p > -\frac{1}{2}, q > -\frac{1}{2})$$

Questions:

$$1. \int_0^2 x^7 (16-x^4)^{10} dx = \underline{\hspace{2cm}}$$

$$\text{Soln:} \rightarrow \text{let, } x^4 = 16t \Rightarrow 4x^3 dx = 16 dt \Rightarrow x^3 dx = 4 dt$$

$$1 = \int_0^1 16t (16-16t)^{10} 4 dt = 16 \times 4 \int_0^1 t (1-t)^{10} dt$$

$$= 4 \times 16^{11} \times \beta(2, 11)$$

$$= 4 \times 16^{11} \times \frac{12!}{13}$$

$$= 4 \times 16^{11} \times \frac{1 \times 10!}{12!}$$

$$2. \int_0^\infty \frac{x^3 (1+x^5)}{(1+x)^{13}} dx = \underline{\hspace{2cm}}$$

$$\text{Soln:} \rightarrow \int_0^\infty \frac{x^3}{(1+x)^{13}} dx + \int_0^\infty \frac{x^8}{(1+x)^{13}} dx = \int_0^\infty \frac{4-1}{(1+x)^{4+9}} dx + \int_0^\infty \frac{x^{9-1}}{(1+x)^{9+4}} dx$$

$$= \beta(4, 9) + \beta(9, 4)$$

$$= 2 \beta(4, 9) = 2 \times \frac{14 \times 15}{13} = 2 \times \frac{3! \times 8!}{12!}$$

$$3. \int_0^{\infty} \left(\frac{x}{1+x^2} \right)^3 dx = \dots$$

Soln:— Let $x = \tan \theta \Rightarrow dx = \sec^2 \theta d\theta$

$$\begin{aligned} \therefore I &= \int_0^{\pi/2} \left(\frac{\tan \theta}{\sec^2 \theta} \right)^3 \sec^2 \theta d\theta = \int_0^{\pi/2} (\tan^3 \theta / \sec^4 \theta) d\theta \\ &= \int_0^{\pi/2} \sin^3 \theta \cos \theta d\theta \\ &= \frac{1}{2} \beta \left(\frac{3+1}{2}, \frac{1+1}{2} \right) = \frac{1}{2} \beta (2, 1) \\ &= \frac{1}{2} \times \frac{\sqrt{2} \sqrt{\pi}}{\sqrt{3}} = \frac{1}{2} \times \frac{1 \times 1}{2!} = \frac{1}{4} \end{aligned}$$

4. Partial Differentiation:—

Let $z = f(x, y)$ then

$$z_x = \frac{\partial z}{\partial x} = \lim_{h \rightarrow 0} \frac{f(x+h, y) - f(x, y)}{h}$$

$$z_y = \frac{\partial z}{\partial y} = \lim_{k \rightarrow 0} \frac{f(x, y+k) - f(x, y)}{k}$$

Similarly, $\frac{\partial^2 z}{\partial x^2}$, $\frac{\partial^2 z}{\partial y^2}$, $\frac{\partial^2 z}{\partial x \partial y}$ and so on.

Homogeneous Function:—

$$\text{Ex:— (i) } x^2 + xy + y^2 ; n = 2$$

$$(ii) 2x^3 + xy^2 + z^3 ; n = 3$$

$$(iii) \frac{xy^2 - y^3}{2x + 3y} ; n = 3-1 = 2$$

If $f(kx, ky) = k^n f(x, y)$ then $f(x, y)$ is a homogeneous function with degree 'n'.

Note :→ If $f(x, y)$ is a homogeneous function with degree ' n ', then,

$$f(x, y) = \begin{cases} x^n \phi(y/x) \\ y^n \psi(x/y) \end{cases}$$

Euler's Theorem :→ If $f(x, y)$ is a homogeneous function with degree ' n ', then,

$$(a) x \frac{\partial f}{\partial x} + y \frac{\partial f}{\partial y} = n f$$

$$(b) x^2 \frac{\partial^2 f}{\partial x^2} + 2xy \frac{\partial^2 f}{\partial x \partial y} + y^2 \frac{\partial^2 f}{\partial y^2} = n(n-1)f$$

Note :→ If $u(x, y) = f(x, y) + g(x, y) + h(x, y)$, where, f, g & h

are homogeneous functions with degree m, n & p respectively, then,

$$(a) x \frac{\partial u}{\partial x} + y \frac{\partial u}{\partial y} = mf + ng + ph$$

$$(b) x^2 \frac{\partial^2 u}{\partial x^2} + 2xy \frac{\partial^2 u}{\partial x \partial y} + y^2 \frac{\partial^2 u}{\partial y^2} = m(m-1)f + n(n-1)g + p(p-1)h$$

Note :→ If $f(u)$ is a homogeneous function in two variables x & y with degree ' n ', then,

$$(a) x \frac{\partial u}{\partial x} + y \frac{\partial u}{\partial y} = n \frac{f(u)}{f'(u)} = F(u)$$

$$(b) x^2 \frac{\partial^2 u}{\partial x^2} + 2xy \frac{\partial^2 u}{\partial x \partial y} + y^2 \frac{\partial^2 u}{\partial y^2} = F(u) [F'(u) - 1]$$

Total Differentiation :→ If $z = f(x, y)$, where $x = \phi(t)$, $y = \psi(t)$, then, the total derivative of ' z ' w.r.t. ' t ' is

$$\frac{dz}{dt} = \frac{\partial f}{\partial x} \cdot \frac{dx}{dt} + \frac{\partial f}{\partial y} \cdot \frac{dy}{dt}$$

Total differential coefficient,

$$dz = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy$$

Note: → (i) If $f(x, y) = c$ is an implicit fn, then,

$$\frac{dy}{dx} = -\frac{f_x}{f_y}$$

(ii) If $z = f(x, y)$, where $x = \phi(u, v)$ & $y = \psi(u, v)$, then,

$$\frac{\partial z}{\partial u} = \frac{\partial f}{\partial x} \cdot \frac{\partial x}{\partial u} + \frac{\partial f}{\partial y} \cdot \frac{\partial y}{\partial u}$$

$$\frac{\partial z}{\partial v} = \frac{\partial f}{\partial x} \cdot \frac{\partial x}{\partial v} + \frac{\partial f}{\partial y} \cdot \frac{\partial y}{\partial v}$$

Questions: →

1: If $z = e^x \sin y$, where $x = \log t$ & $y = t^2$, then, $\frac{dz}{dt} = ?$

$$\text{Soln: } \frac{dz}{dt} = \frac{\partial z}{\partial x} \cdot \frac{dx}{dt} + \frac{\partial z}{\partial y} \cdot \frac{dy}{dt}$$

$$= e^x \sin y \times \frac{1}{t} + e^x \cos y \times 2t$$

$$= \frac{e^x \sin y}{t} + 2te^x \cos y$$

$$= \frac{e^x}{t} (\sin y + 2t^2 \cos y)$$

$$= \sin y + 2y \cos y \quad \left\{ \because t = e^x \text{ & } t^2 = y \right\}$$

2. The total derivative of x^2y w.r.t. x , where, x & y are connected by the relation $x^2 + xy + y^2 = 1$ is _____.

Soln: → Let, $u = x^2y$

$$\frac{du}{dx} = \frac{\partial u}{\partial x} \cdot \frac{dx}{dx} + \frac{\partial u}{\partial y} \cdot \frac{dy}{dx}$$

$$= 2xy + x^2 \frac{dy}{dx}$$

Now, $f(x, y) = x^2 + xy + y^2 = 1$

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$$\therefore \frac{dy}{dx} = -\frac{fx}{fy} = -\frac{2x+y}{x+2y}$$

$$\therefore \frac{du}{dx} = 2xy + x^2 \left(-\frac{2x+y}{x+2y} \right) = 2xy - x^2 \left(\frac{2x+y}{x+2y} \right).$$

3. If $u = f(x+cy) + g(x-cy)$, then, $\frac{u_{xx}}{u_{yy}} = \dots$

- (a) c^{-2} (b) c^2 (c) $-c^2$ (d) $-c^2$

Soln: Let, $r = x+cy$, $s = x-cy$

$$u = f(r) + g(s)$$

$$u_x = f'(r) \frac{\partial r}{\partial x} + g'(s) \frac{\partial s}{\partial x} = f'(r) + g'(s)$$

$$u_{xx} = f''(r) + g''(s)$$

$$u_y = f'(r) \frac{\partial r}{\partial y} + g'(s) \frac{\partial s}{\partial y} = c f'(r) - c g'(s)$$

$$u_{yy} = c^2 f''(r) + c^2 g''(s)$$

$$\therefore \frac{u_{xx}}{u_{yy}} = \frac{1}{c^2} = c^{-2}$$

4. If $u = f(2x-3y, 3y-4z, 4z-2x)$, then, $6u_x + 4u_y = \dots$

- (a) $3u_z$ (b) $4u_z$ (c) $-3u_z$ (d) $-4u_z$

Soln: $r = 2x-3y$, $s = 3y-4z$, $t = 4z-2x$

$$u = f(r, s, t)$$

$$\begin{aligned} u_x &= \frac{\partial f}{\partial r} \cdot \frac{\partial r}{\partial x} + \frac{\partial f}{\partial s} \cdot \frac{\partial s}{\partial x} + \frac{\partial f}{\partial t} \cdot \frac{\partial t}{\partial x} \\ &= f_r(2) + f_s(0) + f_t(-2) \end{aligned}$$

$$\therefore 6u_x = 12f_r - 12f_t$$

$$u_y = \frac{\partial f}{\partial r} \cdot \frac{\partial r}{\partial y} + \frac{\partial f}{\partial s} \cdot \frac{\partial s}{\partial y} + \frac{\partial f}{\partial t} \cdot \frac{\partial t}{\partial y}$$

$$= f_r (-3) + f_s (3) + f_t (0)$$

$$\therefore 4u_y = -12f_r + 12f_s$$

$$\therefore 6u_x + 4u_y = 12f_s - 12f_t$$

$$u_z = \frac{\partial f}{\partial r} \cdot \frac{\partial r}{\partial z} + \frac{\partial f}{\partial s} \cdot \frac{\partial s}{\partial z} + \frac{\partial f}{\partial t} \cdot \frac{\partial t}{\partial z}$$

$$= f_r (0) + f_s (-4) + f_t (4)$$

$$= -4f_s + 4f_t$$

5. If $u = \frac{y}{z} + \frac{z}{x}$, then, $xu_x + yu_y + zu_z = \underline{\quad}$

- (a) $\frac{xy}{z^2}$ (b) $\frac{yz}{x^2}$ (c) $\frac{xz}{y^2}$ (d) $\checkmark 0$

Soln: $\rightarrow xu_x + yu_y + zu_z = 0 \cdot u = 0 \quad (\because n=0)$

6. If $\mu = \frac{x^2y}{x^{5/2} + y^{5/2}}$, then, $x^2\mu_{xx} + 2xy\mu_{xy} + y^2\mu_{yy} = \underline{\quad}$

- (a) $\frac{3}{4}\mu$ (b) $\checkmark -\frac{1}{4}\mu$ (c) $-\frac{3}{4}\mu$ (d) $\frac{1}{4}\mu$

Soln: $\rightarrow n = 3 - \frac{5}{2} = \frac{1}{2}$

$$x^2\mu_{xx} + 2xy\mu_{xy} + y^2\mu_{yy} = n(n-1)\mu = \frac{-1}{4}\mu$$

7. If $u = \operatorname{cosec}^{-1} \left[\frac{x^{1/4} - y^{1/4}}{x^{1/5} + y^{1/5}} \right]$, then, $xu_x + yu_y = \underline{\quad}$

- (a) $-\frac{1}{20}u$ (b) $-\frac{1}{20}\cot u$ (c) $\frac{1}{20}\tan u$ (d) $\frac{1}{20}\tan u$

Soln: $\rightarrow \operatorname{cosec} u = \frac{x^{1/4} - y^{1/4}}{x^{1/5} + y^{1/5}}$

$$\Rightarrow n = \frac{1}{4} - \frac{1}{5} = \frac{1}{20}$$

$$\therefore x u_x + y u_y = n \frac{f(u)}{f'(u)} = \frac{1}{20} \times \frac{\csc u}{-\csc u \cot u} = -\frac{1}{20} \tan u.$$

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$$8. \text{ If } u = \log \left(\frac{x^2}{y} \right), \text{ then, } x^2 u_{xx} + 2xy u_{xy} + y^2 u_{yy} = \underline{\quad}.$$

- (a) u (b) 0 (c) -1 (d) 1

$$\text{Soln: } \rightarrow e^u = \left(\frac{x^2}{y} \right) \Rightarrow n = 2-1 = 1$$

$$x u_x + y u_y = n \frac{f(u)}{f'(u)} = \frac{e^u}{e^u} = 1 = f(u).$$

$$\therefore x^2 u_{xx} + 2xy u_{xy} + y^2 u_{yy} = F(u) [F'(u)-1] = -1.$$

$$9. \text{ If } z = x^n f(y/x) + y^{-n} g(x/y), \text{ then, } x z_x + y z_y + x^2 z_{xx} + 2xy z_{xy} + y^2 z_{yy} = \underline{\quad}$$

$$z = \underline{\quad}.$$

- (a) $n(n-1)z$ (b) $n^2 z$ (c) $n(n+1)z$ (d) nz

Soln: \rightarrow The given fun is the sum of two homogeneous fun having degree n & $-n$ respectively.

$$\therefore x z_x + y z_y + x^2 z_{xx} + 2xy z_{xy} + y^2 z_{yy} = (nf - ng) + [n(n-1)f] \\ + [(-n)(-n-1)g]$$

$$= n^2 z$$

$$10. \text{ If } u = \sin^{-1}(xy) + \cos^{-1}(y/x), \text{ then, } \frac{u_x}{u_y} = \underline{\quad}.$$

- (a) $-\frac{y}{x}$ (b) $-\frac{x}{y}$ (c) $\frac{y}{x}$ (d) $\frac{x}{y}$

$$\text{Soln: } \rightarrow x u_x + y u_y = 0.4 = 0 \quad (\because n=0)$$

$$\Rightarrow \frac{u_x}{u_y} = -\frac{y}{x}.$$

Maxima & Minima:

for function of Single Variable:

$$f(x) \rightarrow \max \rightarrow x = c \text{ if } f(x) \leq f(c) \forall x$$

$$f(x) \rightarrow \min \rightarrow x = c \text{ if } f(x) \geq f(c) \forall x$$

Method: → (i) find $f'(x)$

(ii) Equate $f'(x) = 0$ for obtaining the stationary points

(iii) At each stationary pt. find $f''(x)$

(a) If $f''(x_0) > 0$ then $f(x)$ has minima at $x = x_0$.

(b) If $f''(x_0) < 0$ then $f(x)$ has maxima at $x = x_0$.

(c) If $f''(x_0) = 0$ then $f(x)$ has no extreme at $x = x_0$.

and it is called critical point.

Questions: →

1. The fun $f(x) = 2x^3 - 3x^2 - 36x + 10$ has a minimum value at
 $x = \underline{\hspace{2cm}}$.

- (a) 2 (b) \checkmark 3 (c) -2 (d) -3.

Soln: → $f'(x) = 6x^2 - 6x - 36 = 0$

$$\Rightarrow x^2 - x - 6 = 0$$

$$\Rightarrow x = -2, 3$$

$$f''(x) = 12x - 6$$

$f''(x)|_{x=-2} = 12(-2) - 6 = -24 - 6 < 0 \Rightarrow$ maxima at $x = -2$.

$f''(x)|_{x=3} = 12(3) - 6 > 0 \Rightarrow$ minima at $x = 3$.

2. The maximum value of fun $\frac{e^{\sin x}}{e^{\cos x}}$ is _____. where, $x \in \mathbb{R}$. 25

(a) $e^{\frac{1}{\sqrt{2}}}$

(b) $e^{-\frac{1}{\sqrt{2}}}$

(c) $e^{\sqrt{2}}$

(d) $e^{-\frac{1}{\sqrt{2}}}$

Soln: $f(x) = \frac{e^{\sin x}}{e^{\cos x}} = e^{(\sin x - \cos x)}$

$f(x)$ will have max. value when $(\sin x - \cos x)$ will be max.

let, $g(x) = \sin x - \cos x$

$g'(x) = \cos x + \sin x = 0 \Rightarrow x = -\frac{\pi}{4}, \frac{3\pi}{4}$

$g''(x) = -\sin x + \cos x$

$\therefore g''(x)|_{x=-\frac{\pi}{4}} = \frac{1}{\sqrt{2}} + \frac{1}{\sqrt{2}} > 0 \Rightarrow$ minima at $-\frac{\pi}{4}$

$g''(x)|_{x=\frac{3\pi}{4}} = -\frac{1}{\sqrt{2}} - \frac{1}{\sqrt{2}} < 0 \Rightarrow$ maxima at $\frac{3\pi}{4}$

$\therefore f\left(\frac{3\pi}{4}\right) = e^{\frac{1}{\sqrt{2}} - \left(-\frac{1}{\sqrt{2}}\right)} = e^{\sqrt{2}}$

3. For the fun $f(x) = x^x$, minimum appears at $x =$ ____.

(a) e

(b) $\frac{1}{e}$

(c) $e+1$

(d) $e-1$

Soln: let, $y = x^x \Rightarrow \log y = x \log x$

$$\Rightarrow \frac{1}{y} y' = x \cdot \frac{1}{x} + \log x = 1 + \log x$$

$$\Rightarrow y' = y(1 + \log x) = 0$$

$$\Rightarrow x = \frac{1}{e}$$

4. Consider $f(x) = (x^2 - 4)^2$ where $x \in \mathbb{R}$, then, $f(x)$ has

(a) Only one minima

(b) Only two minima

(c) Three minima

(d) Three maxima

Soln: $\rightarrow f(x) = (x^2 - 4)^2$

$$f'(x) = 2 \cdot 2x(x^2 - 4) = 0 \Rightarrow x = \pm 2, 0$$

$$f''(x) = 3x^2 - 4$$

$$f''(0) = -4 < 0 \Rightarrow \text{maxima at } x=0$$

$$f''(2) = 3 \times 4 - 4 > 0 \Rightarrow \text{minima at } x=2$$

$$f''(-2) = 3 \times 4 - 4 > 0 \Rightarrow \text{minima at } x=-2$$

5. If $f(x) = a \log x + bx^2 - x$ has an extreme value at $x=-1, 2$

then $a \& b$ is _____

- (a) $2, \frac{1}{2}$ (b) $-2, -\frac{1}{2}$ (c) $-2, \frac{1}{2}$ (d) $-2, -\frac{1}{2}$

Soln: $\rightarrow f'(x) = \frac{a}{x} + 2bx - 1 = 0$

$$\Rightarrow a + 2bx^2 - x = 0$$

$$\Rightarrow 2bx^2 - x + a = 0$$

$$\Rightarrow x^2 - \frac{1}{2b}x + \frac{a}{2b} = 0$$

$$\therefore \frac{1}{2b} = -1 + 2 = 1 \Rightarrow b = \frac{1}{2}$$

$$\frac{a}{2b} = -2 \Rightarrow a = -2$$

6. The maximum value of $f(x) = x^2 - x - 2$ in $[-4, 4]$ is _____.

- (a) 18 (b) 10 (c) -2.25 (d) indeterminate

Soln: $\rightarrow f'(x) = 2x - 1 = 0 \Rightarrow x = \frac{1}{2}$

$$f''(x) = 2 > 0 \Rightarrow \text{minima at } x = \frac{1}{2}$$

$$f(-4) = 18$$

$$f(4) = 10$$

Maxima & Minima for fun. of two variables:

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let $z = f(x, y)$,

consider, $P = \frac{\partial z}{\partial x}$, $Q = \frac{\partial z}{\partial y}$, $R = \frac{\partial^2 z}{\partial x^2}$, $S = \frac{\partial^2 z}{\partial x \partial y}$, $T = \frac{\partial^2 z}{\partial y^2}$

Method: → (i) Find $P, Q, R, S & T$

(ii) Equate $P & Q$ to zero for obtaining the stationary points

(iii) At each stationary point find $R, S & T$.

- (a) If $RT - S^2 > 0$, $R > 0$ then the $f(x, y)$ has a minimum at that stationary point.
- (b) If $RT - S^2 > 0$, $R < 0$ then $f(x, y)$ has a maximum at that stationary point.
- (c) If $RT - S^2 < 0$, then $f(x, y)$ has no extreme at that stationary point & it is known as Saddle point

Questions:

1. The fun $f(x, y) = x^2 + y^2 + 6x = 0$ has

(a) min. at $(-3, 0)$

(b) max. at $(-3, 0)$

(c) $(-3, 0)$ is a saddle point

(d) none

Solⁿ:

2. The funⁿ $f(x,y) = x^3 - 3x^2 + 4y^2 + 6$ has a minimum value at $x = \underline{\hspace{2cm}}$.

- (a) (0, 0) (b) (2, 0) (c) (2, 1) (d) (-2, 0)

Solⁿ: $\rightarrow p = \frac{\partial f}{\partial x} = 3x^2 - 6x = 0 \Rightarrow x = 0, 2.$

$$q = \frac{\partial f}{\partial y} = 8y = 0 \Rightarrow y = 0$$

$$r = \frac{\partial^2 f}{\partial x^2} = 6x - 6$$

$$s = \frac{\partial^2 f}{\partial x \partial y} = 0$$

$$t = \frac{\partial^2 f}{\partial y^2} = 8$$

At (0, 0) & (2, 0)

$$\lambda = -6 < 0$$

$$\lambda = 0$$

$$\lambda = 8$$

$$rt - s^2 < 0$$

saddle point

$$\lambda = 6 > 0$$

$$\lambda = 0$$

$$\lambda = 8$$

$$rt - s^2 > 0$$

minima at (2, 0)

3. The funⁿ $f(x,y) = x^3 + y^3 - 3axy$ has

(a) max. at (a, a)

(b) max. at (a, a) if $a < 0$

(c) min. at (a, a)

(d) max. at (a, a) if $a > 0$

Solⁿ: $\rightarrow p = 3x^2 - 3ay = 0 \Rightarrow x^2 = ay$ } solving

$$q = 3y^2 - 3ax = 0 \Rightarrow y^2 = ax$$

Q. 4: A rectangular box open at the top is to have a volume of 32 ft^3 , then, the dimensions of the box requiring the least material for its construction is _____.

- (a) 8, 2, 2 (b) $4, 4, 2$ (c) $16, 1, 2$ (d) $8, 8, \frac{1}{2}$

Soln: Let the dimension of the box is $x, y, z \Rightarrow xyz = 32$

$$\therefore S = xy + 2yz + 2xz$$

$$\text{i.e. } f(x, y) = xy + 2y \cdot \frac{32}{xy} + 2x \cdot \frac{32}{xy}$$

$$= xy + \frac{64}{x} + \frac{64}{y}$$

$$P = y - \frac{64}{x^2} = 0$$

$$q = x - \frac{64}{y^2} = 0$$

} solving $x=4, y=4$

Q. 5. The distance between the origin and a point nearest to it on the surface $z^2 = 1+xy$ is _____.

- (a) $\sqrt{3}$ (b) $\sqrt{2}$ (c) 1 (d) None

Soln: Let $P(x, y, z)$ be on the surface $z^2 = 1+xy$

$$\therefore D = \sqrt{x^2 + y^2 + z^2} = \sqrt{x^2 + y^2 + xy + 1}$$

Consider, $f = x^2 + y^2 + xy + 1$

$$P = 2x + y = 0 \quad \left. \begin{array}{l} \\ \end{array} \right\} \text{solving } x=0, y=0$$

$$q = 2y + x = 0$$

$$x=2$$

$$x=1$$

$$x=0$$

$$t=2$$

$$t=1$$

$$t=0$$

$$x^2 + y^2 = 4 - 1 = 3 > 0 \text{ also } t > 0$$

i.e. minima at $x=0, y=0$

at $x=0, y=0$ we have $z^2 = 1+0=1 \Rightarrow z = \pm 1$

$$\therefore D = \sqrt{1} = 1$$

Constrained Maxima & Minima:

Lagrange's method of undetermined multipliers:

Let $f(x, y, z)$ & $\phi(x, y, z) = c$, then

$$F(x, y, z) = f(x, y, z) + \lambda \phi(x, y, z) = 0$$

$$F_x = 0 \quad \text{i.e.} \quad \frac{\partial f}{\partial x} + \lambda \frac{\partial \phi}{\partial x} = 0$$

$$F_y = 0 \quad \text{i.e.} \quad \frac{\partial f}{\partial y} + \lambda \frac{\partial \phi}{\partial y} = 0$$

$$F_z = 0 \quad \text{i.e.} \quad \frac{\partial f}{\partial z} + \lambda \frac{\partial \phi}{\partial z} = 0$$

} Lagrange's eqn

$\lambda \rightarrow$ Lagrange's Multiplier

Questions:

1. The volume of the greatest parallelopiped that can be inscribed in an ellipse: $\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$ is _____.

- (a) $\frac{8abc}{3\sqrt{3}}$ (b) $\frac{4abc}{3\sqrt{3}}$ (c) $\frac{abc}{\sqrt{3}}$ (d) $\frac{abc}{3\sqrt{3}}$

Solⁿ: Let $2x, 2y, 2z$ be dimension of parallelopiped.

$$\text{volume} = 8xyz = f(x, y, z)$$

$$\phi(x, y, z) = \frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} - 1 = 0$$

$$\therefore F(x, y, z) = 8xyz + \lambda \left(\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} - 1 \right) = 0$$

$$F_x = 8yz + \frac{2\lambda x}{a^2} = 0 \Rightarrow -\lambda = \frac{a^2yz}{x}$$

$$F_y = 8xz + \frac{2\lambda y}{b^2} = 0 \Rightarrow -\lambda = \frac{b^2xz}{y}$$

$$F_z = 8xy + \frac{2\lambda z}{c^2} = 0 \Rightarrow -\lambda = \frac{c^2xy}{z}$$

$$\therefore \frac{a^2yz}{x} = \frac{b^2xz}{y} \quad \& \quad \frac{b^2xz}{y} = \frac{c^2xy}{z} \quad \& \quad \frac{c^2xy}{z} = \frac{a^2yz}{x}$$

$$\Rightarrow \frac{x^2}{a^2} = \frac{y^2}{b^2} \quad \& \quad \frac{y^2}{b^2} = \frac{z^2}{c^2} \quad \& \quad \frac{z^2}{c^2} = \frac{x^2}{a^2}$$

$$\Rightarrow \frac{3x^2}{a^2} = 1 \Rightarrow x = \frac{a}{\sqrt{3}} \quad \& \quad y = \frac{b}{\sqrt{3}}, z = \frac{c}{\sqrt{3}}$$

$$\therefore \text{volume}, V = 8xyz = \frac{8abc}{3\sqrt{3}}.$$

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2. The min value of $x^2+y^2+z^2$ where $x+y+z=1$ is ____.

- (A) $\frac{1}{3}$ (B) $\frac{1}{9}$ (C) $\frac{1}{27}$ (D) 1

$$\text{Soln: } \rightarrow f = (x^2+y^2+z^2) \text{ s.t. } x+y+z=1$$

$$\therefore F = f + \lambda \phi$$

$$\Rightarrow F_x = 2x + \lambda \Rightarrow -\lambda = 2x$$

$$F_y = 2y + \lambda \Rightarrow -\lambda = 2y$$

$$F_z = 2z + \lambda \Rightarrow -\lambda = 2z$$

$$\Rightarrow x=y=z$$

$$\therefore x = \frac{1}{3}, y = \frac{1}{3}, z = \frac{1}{3}$$

$$\therefore f_{\min} = x^2+y^2+z^2 = 3x^2 = \frac{1}{3}$$

5. Multiple Integrals:→

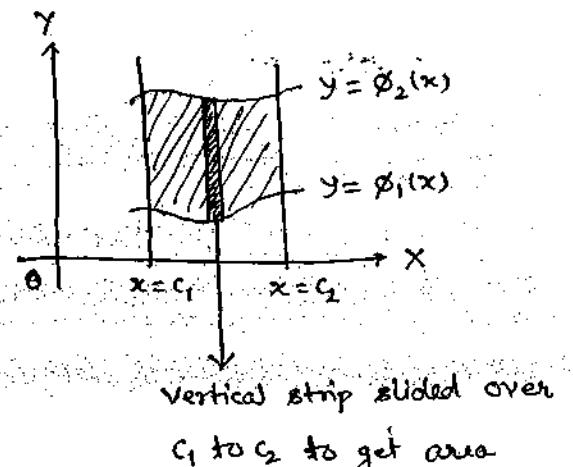
Double Integral:→ Let $f(x,y)$ be defined at each point in the given region R , then its double integral is, $\iint_R f(x,y) dx dy$; where, continuity of $f(x,y)$ in the region R ensures the existence of the integral.

Methods of Evaluation:→

Case 1:→ Let the limits of integration be $y=\phi_1(x)$ to $y=\phi_2(x)$ &

$$x=c_1 \text{ to } c_2.$$

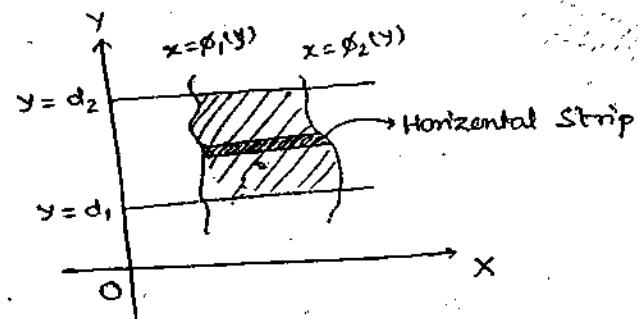
$$\iint_R f(x,y) dx dy = \int_{c_1}^{c_2} \left[\int_{\phi_1(x)}^{\phi_2(x)} f(x,y) dy \right] dx$$



Case 2— when the limits of integration are $x = \phi_1(y)$ & $x = \phi_2(y)$, and

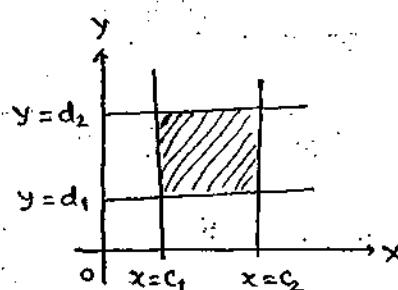
$y = d_1$ to $y = d_2$,

$$\iint_R f(x,y) dx dy = \int_{y=d_1}^{y=d_2} \left[\int_{x=\phi_1(y)}^{x=\phi_2(y)} f(x,y) dx \right] dy$$



Case 3— when the limits are $x = c_1$ to $x = c_2$ & $y = d_1$ to $y = d_2$,

$$\begin{aligned} \iint_R f(x,y) dx dy &= \int_{x=c_1}^{x=c_2} \left[\int_{y=d_1}^{y=d_2} f(x,y) dy \right] dx \\ &= \int_{y=d_1}^{y=d_2} \left[\int_{x=c_1}^{x=c_2} f(x,y) dx \right] dy. \end{aligned}$$



Questions:→

1. Evaluate the following

$$(i) \int_0^2 \int_0^2 (xy + x^3) dx dy. \quad (ii) \int_0^4 \left[\int_0^{x^2} e^{yx} dy \right] dx.$$

$$\text{Soln: } (i) \int_0^1 \left(\frac{x^2}{2}y + \frac{x^4}{4} \right)_0^2 dy = \int_0^1 (2y + 4) dy = [y^2 + 4y]_0^1 = 5.$$

$$(ii) \int_0^4 \left[\frac{e^{yx}}{1/x} \right]_0^{x^2} dx = \int_0^4 (x e^{x^2} - x) dx = \left[x e^{x^2} - e^x - \frac{x^2}{2} \right]_0^4 = [4e^4 - e^4 - 8] - [-1] = 3e^4 - 7.$$

2. The value of $\iint_R xy dx dy$, where, R is a region in the 1st+ve quadrant at the ellipse $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$ is _____.

- (a) $\frac{a^2 b^2}{8}$ (b) $\frac{ab}{8}$ (c) $\frac{a^3 b^3}{8}$ (d) $\frac{a^2 b^2}{4}$

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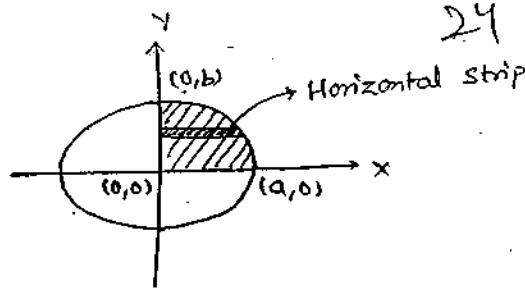
Soln: → Consider the horizontal strip,

$$x=0 \text{ to } x=\frac{a}{b} \sqrt{b^2-y^2}$$

$$y=0 \text{ to } y=b$$

$$b \frac{a}{b} \sqrt{b^2-y^2}$$

$$\iint_R xy \, dx \, dy = \int_{y=0}^b \int_{x=0}^{a \sqrt{b^2-y^2}} xy \, dx \, dy$$



$$= \int_{y=0}^b \left[\frac{x^2 y}{2} \right]_0^{a \sqrt{b^2-y^2}} \, dy$$

$$= \int_0^b \frac{\frac{a^2}{b^2} (b^2-y^2) y}{2} \, dy$$

$$= \left[\frac{a^2}{2} \cdot \frac{y^2}{2} - \frac{a^2}{2b^2} \cdot \frac{y^4}{4} \right]_0^b = \frac{a^2 b^2}{4} + \frac{a^2 b^2}{8} = \frac{a^2 b^2}{8}$$

3. The value of $\iint_R y \, dx \, dy$, where R is a region $y=x^2$, $x+y=2$

$x=0$ is _____.

$$\text{Soln: } x+x^2=2$$

$$\Rightarrow x^2+x-2=0$$

$$\Rightarrow (x-1)(x+2)=0$$

$$\Rightarrow x=1, -2$$

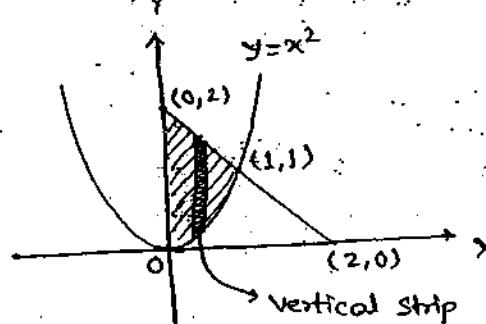
∴ pt. of intersection is $(1,1)$

Consider the vertical strip,

$$y=x^2 \text{ to } y=2-x$$

$$x=0 \text{ to } 1$$

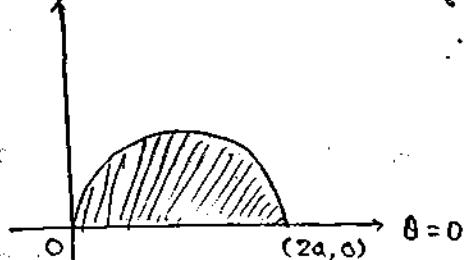
$$\iint_R y \, dx \, dy = \int_{x=0}^1 \int_{y=x^2}^{2-x} y \, dy \, dx = \int_0^1 \left[\frac{y^2}{2} \right]_{x^2}^{2-x} \, dx = \frac{16}{15}$$



Ques-4. The value of $\iint_R r^2 \sin\theta dr d\theta$, where, R is the region, bounded by the semicircle $r = 2a \cos\theta$ above the initial line is _____.

Solⁿ:→ $r = 0$ to $2a \cos\theta$
 $\theta = 0$ to $\pi/2$

$$\theta = \pi/2$$



$$\iint_R r^2 \sin\theta dr d\theta$$

$$= \int_{\theta=0}^{\pi/2} \int_{r=0}^{2a \cos\theta} r^2 \sin\theta dr d\theta$$

$$= \int_0^{\pi/2} \sin\theta \left[\frac{r^3}{3} \right]_0^{2a \cos\theta} d\theta$$

$$= \int_0^{\pi/2} \frac{8a^3 \cos^3\theta \sin\theta}{3} d\theta$$

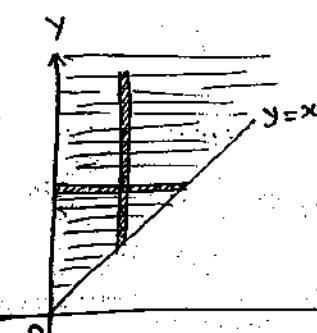
$$= -\frac{8a^3}{3} \left[\frac{\cos^4\theta}{4} \right]_0^{\pi/2} = \frac{2a^3}{3}$$

Change of order of integration:→

Questions:-

1. The value of $\iint_{x=0}^{\infty} \int_{y=x}^{\infty} \frac{e^{-y}}{y} dy dx$ is _____.

Solⁿ:→ Given limits are $y=x$ to $y=\infty$
 $x=0$ to $x=\infty$



Horizontal Strip:—

$$x=0, x=y$$

$$y=0, y=\infty$$

$$\iint_{x=0}^{\infty} \int_{y=x}^{\infty} \frac{e^{-y}}{y} dy dx = \int_{y=0}^{\infty} \left[\int_{x=0}^y \frac{e^{-y}}{y} dx \right] dy = \int_0^{\infty} \left[\frac{e^{-y} y}{y} \right]_0^{\infty} dy = \int_0^{\infty} e^{-y} dy$$

2. By reversing the order of integration $\int_0^2 \int_{x^2}^{2x} f(x,y) dy dx$ may be represented as.

$$(a) \int_0^2 \int_{x^2}^{2x} f(x,y) dy dx$$

$$(b) \int_0^2 \int_y^{2y} f(x,y) dx dy$$

$$(c) \int_0^4 \int_{y/2}^{\sqrt{y}} f(x,y) dx dy$$

$$(d) \int_{x^2}^{2x} \int_0^2 f(x,y) dx dy$$

Soln: Given limits are

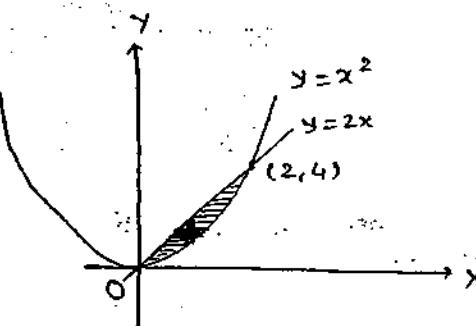
$$x=0 \text{ to } x=2$$

$$y=x^2 \text{ to } y=2x$$

Horizontal Strip:

$$y=0 \text{ to } y=4$$

$$x=\frac{y}{2} \text{ to } x=\sqrt{y}$$



3. By changing the order of integration $\int_0^8 \int_{x/4}^2 f(x,y) dy dx$ leads to

$$\int_p^q \int_0^y f(x,y) dx dy \text{ then } q \text{ is } \underline{\hspace{2cm}}$$

Soln: Given limits are

$$y=\frac{x}{4} \text{ to } y=2$$

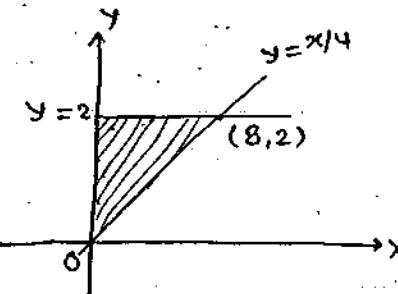
$$x=0 \text{ to } x=8$$

By changing limits,

$$y=0 \text{ to } y=2$$

$$x=0 \text{ to } x=4y$$

$$q=4y$$



Triple Integrals: Let $f(x, y, z)$ be defined at each point in the region R of space then its triple integral is $\iiint_R f(x, y, z) dx dy dz$.

Let $z = \phi_1(x, y)$ to $z = \phi_2(x, y)$

$y = \psi_1(x)$ to $y = \psi_2(x)$

$x = c_1$ to $x = c_2$, then

$$\iiint_R f(x, y, z) dx dy dz = \int_{c_1}^{c_2} \int_{\psi_1(x)}^{\psi_2(x)} \int_{\phi_1(x, y)}^{\phi_2(x, y)} f(x, y, z) dz dy dx$$

$x = c_1, y = \psi_1(x), z = \phi_1(x, y)$

Questions:

1. Evaluate $\int_0^2 \int_0^x \int_0^{\sqrt{x+y}} z dz dy dx$.

Soln: $I = \int_0^2 \int_0^x \left[\frac{z^2}{2} \right]_0^{\sqrt{x+y}} dy dx = \int_0^2 \left[\frac{(x+y)^2}{4} \right]_0^x dx = 2$.

2. The value of $\iiint_R y dz dy dx$, where R is the region bounded by

the plane $x=0, y=0, z=0$ & $x+y+z=1$ is _____.

Soln: $\int_0^1 \int_0^{1-x} \int_0^{1-x-y} y dz dy dx = \int_0^1 \int_0^{1-x} y(1-x-y) dy dx$

$$= \int_0^1 \left[y - xy - \frac{y^2}{2} \right]_0^{1-x} dx$$

$$= \int_0^1 \left[1-x - x+x^2 - \frac{(1-x)^2}{2} \right] dx$$

$$= \int_0^1 \left[\frac{(1-x)y^2}{2} - \frac{y^3}{3} \right]_0^{1-x} dx$$

$$= \int_0^1 \left[\frac{(1-x)^3}{2} - \frac{(1-x)^3}{3} \right] dx = \frac{(1-x)^4}{24} \Big|_0^1 = \frac{1}{24}$$

Change of variables :→ In a double integral, if $x = f(u, v)$ & $y = g(u, v)$

then, $\iint_R \phi(x, y) dx dy = \iint_R \phi(f, g) |J| du dv = \iint_R \phi(u, v) |J| du dv$

where, $|J| \rightarrow$ Jacobian of transformation used to transform one system to another.

$$|J| = J\left(\frac{x, y}{u, v}\right) = \frac{\partial(x, y)}{\partial(u, v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix}$$

Cartesian form → Polar form :→

$$(x, y) \rightarrow (r, \theta)$$

$$x = r \cos \theta, \quad y = r \sin \theta$$

$$|J| = \begin{vmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} \end{vmatrix} = \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix} = r$$

$$\Rightarrow \iint_R \phi(x, y) dx dy = \iint_R \psi(r, \theta) r dr d\theta$$

In a triple integral, if $x = f(u, v, w)$, $y = g(u, v, w)$ & $z = h(u, v, w)$

then,

$$\iiint_R f(x, y, z) dx dy dz = \iiint_R \psi(u, v, w) |J| du dv dw$$

$$\text{where, } |J| = J\left(\frac{x, y, z}{u, v, w}\right) = \frac{\partial(x, y, z)}{\partial(u, v, w)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} & \frac{\partial x}{\partial w} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} & \frac{\partial y}{\partial w} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} & \frac{\partial z}{\partial w} \end{vmatrix}$$

Cartesian to Cylindrical Polar Form : \rightarrow

$$(x, y, z) \quad (r, \theta, z)$$

$$x = r \cos \theta, \quad y = r \sin \theta, \quad z = z$$

$$|J| = \begin{vmatrix} \cos \theta & -r \sin \theta & 0 \\ \sin \theta & r \cos \theta & 0 \\ 0 & 0 & 1 \end{vmatrix} = r$$

$$\iiint_R \phi(x, y, z) dx dy dz = \iiint_R \psi(r, \theta, z) r dr d\theta dz$$

Cartesian to Spherical Polar Form : \rightarrow

$$(x, y, z) \quad (r, \theta, \phi)$$

$$x = r \sin \theta \cos \phi, \quad y = r \sin \theta \sin \phi, \quad z = r \cos \theta$$

$$|J| = \begin{vmatrix} \sin \theta \cos \phi & r \cos \theta \cos \phi & -r \sin \theta \sin \phi \\ \sin \theta \sin \phi & r \cos \theta \sin \phi & r \sin \theta \cos \phi \\ \cos \theta & -r \sin \theta & 0 \end{vmatrix} = r^2 \sin \theta$$

$$\iiint_R \phi(x, y, z) dx dy dz = \iiint_R \psi(r, \theta, \phi) r^2 \sin \theta dr d\theta d\phi$$

Questions : \rightarrow

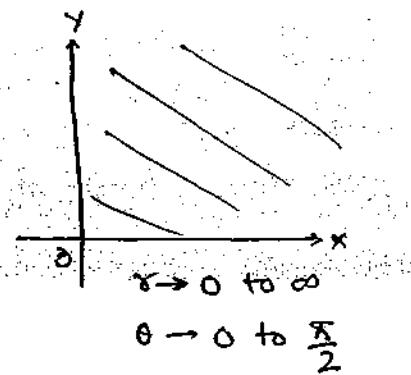
1. Evaluate $\int_0^\infty \int_0^\infty e^{-(x^2+y^2)} dx dy$

Soln : \rightarrow let $x = r \cos \theta, \quad y = r \sin \theta$, then $|J| = r$

$$\therefore x^2 + y^2 = r^2$$

$$\therefore \int_0^\infty \int_0^{\pi/2} e^{-r^2} \cdot r dr d\theta$$

$$\text{let } r^2 = t \Rightarrow r dr = \frac{dt}{2}$$



$$\Rightarrow \int_0^{\pi/2} \int_0^\infty e^{-t} \frac{dt}{2} d\theta = \int_0^{\pi/2} \left[\frac{e^{-t}}{2} \right]_0^\infty d\theta = \frac{1}{2} \int_0^{\pi/2} d\theta = \frac{\pi}{4}. \quad \text{B2}$$

2. Evaluate $\int_0^1 \int_0^{\sqrt{1-x^2}} \int_0^{\sqrt{1-x^2-y^2}} \frac{dz dy dx}{\sqrt{1-x^2-y^2-z^2}}$

Solⁿ: $\rightarrow z=0 \text{ to } z=\sqrt{1-x^2-y^2} \Rightarrow z^2=1-x^2-y^2 \Rightarrow x^2+y^2+z^2=1$

Using spherical coordinates,

$$x = r \sin\theta \cos\phi, \quad y = r \sin\theta \sin\phi, \quad z = r \cos\theta$$

$$x^2+y^2+z^2 = r^2$$

$$\Rightarrow r \rightarrow 0 \text{ to } 1$$

$$\theta \rightarrow 0 \text{ to } \pi/2$$

$$\phi \rightarrow 0 \text{ to } \pi/2$$

$$\begin{aligned} \int_0^{\pi/2} \int_0^{\pi/2} \int_0^1 \frac{r^2 \sin\theta dr d\theta d\phi}{\sqrt{1-r^2}} &= \int_0^{\pi/2} \int_0^{\pi/2} \int_0^1 \sin\theta \left[\frac{1}{\sqrt{1-r^2}} - \sqrt{1-r^2} \right] dr d\theta d\phi \\ &= \int_0^{\pi/2} \int_0^{\pi/2} \sin\theta \left[\sin^{-1} r - \left(\frac{r \sqrt{1-r^2}}{2} + \frac{1}{2} \sin^{-1}(r) \right) \right]_0^1 d\theta d\phi \\ &= \int_0^{\pi/2} \int_0^{\pi/2} \sin\theta \left[\frac{\pi}{4} \right] d\theta d\phi \\ &= \frac{\pi}{4} \int_0^{\pi/2} [-\cos\theta]_0^{\pi/2} d\phi = \frac{\pi}{4} \cdot \frac{\pi}{2} = \frac{\pi^2}{8}. \end{aligned}$$

3. By a change of variable $x(u,v) = uv$ & $y(u,v) = \frac{v}{u}$ in double integral
the integrand $f(x,y)$ changes to $f(uv, \frac{v}{u}) \phi(u,v)$ then $\phi(u,v)$ is
(a) $\frac{2v}{u}$ (b) $2uv$ (c) v^2 (d) $= 1$

Solⁿ: $\rightarrow \phi(u,v) = |J| = \begin{vmatrix} v & u \\ -\frac{v}{u^2} & \frac{1}{u} \end{vmatrix} = \frac{v}{u} + \frac{v}{u} = \frac{2v}{u}$

Lengths, Areas & Volumes:

(i) Length of an arc of a curve $y=f(x)$ between the lines $x=x_1$ & $x=x_2$

$$\text{is, } l = \int_{x_1}^{x_2} \sqrt{1 + \left(\frac{dy}{dx}\right)^2} dx$$

(ii) length of an arc of a curve $x=f(t)$ & $y=g(t)$ between $t=t_1$ to $t=t_2$

$$\text{is, } l = \int_{t_1}^{t_2} \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt$$

(iii) Area of the region bounded by the curve $y=f(x)$ & $y=g(x)$ between

$$x=x_1 \text{ & } x=x_2$$

$$A = \int_{x_1}^{x_2} [g(x) - f(x)] dx \quad (\text{or}) \quad \int_{x_1}^{x_2} \int dy dx$$

(iv) The volume of solid generated by revolving $y=f(x)$ between $x=x_1$ & $x=x_2$ about x -axis is,

$$V = \int_{x_1}^{x_2} \pi y^2 dx$$

$$\text{about } y\text{-axis: (i)} \quad V = \int_{y_1}^{y_2} \pi x^2 dy$$

In polar form: (i) about initial line (i.e. $\theta=0^\circ$)

$$V = \int_{\theta_1}^{\theta_2} \frac{2\pi}{3} r^3 \sin\theta d\theta$$

(ii) about line $\theta=\frac{\pi}{2}$

$$V = \int_{\theta_1}^{\theta_2} \frac{2\pi}{3} r^3 \cos\theta d\theta$$

Questions:

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1. The length of the curve $y = \frac{2}{3}x^{3/2}$ between $x=0$ & 1 is — .
 (a) 0.27 (b) 0.67 (c) 1 (d) 1.22

Solⁿ:— $\frac{dy}{dx} = \frac{2}{3} \cdot \frac{3}{2} x^{\frac{3}{2}-1} = x^{1/2}$

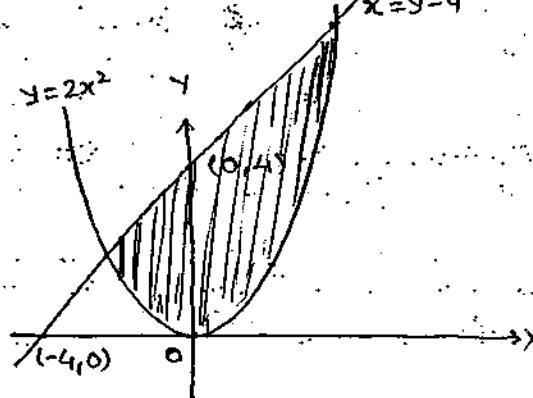
$$\therefore l = \int_{x_1}^{x_2} \sqrt{1 + \left(\frac{dy}{dx}\right)^2} dx = \int_0^1 \sqrt{1+x} dx = \left[\frac{(1+x)^{3/2}}{3/2} \right]_0^1 = 1.22$$

2. The length of the curve, $x = \cos^3\theta$, $y = \sin^3\theta$ between $\theta = 0$ & $\pi/2$ is —

Solⁿ:— $l = \int_0^{\pi/2} \sqrt{(3\cos^2\theta(-\sin\theta))^2 + (3\sin^2\theta\cos\theta)^2} d\theta$

$$= \int_0^{\pi/2} (3\sin\theta\cos\theta)\sqrt{\sin^2\theta + \cos^2\theta} d\theta = \frac{3}{2}$$

3. The area bounded by the parabola $y = 2x^2$ & st. line $x = y - 4$.



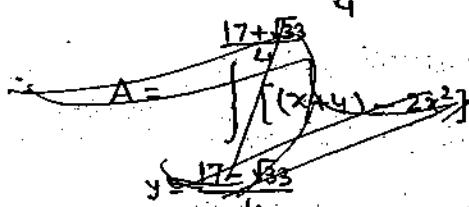
Solⁿ:— Pt. of intersection—

$$y = 2(y-4)^2$$

$$\Rightarrow y = 2(y^2 + 16 - 8y)$$

$$\Rightarrow 2y^2 - 17y + 32 = 0$$

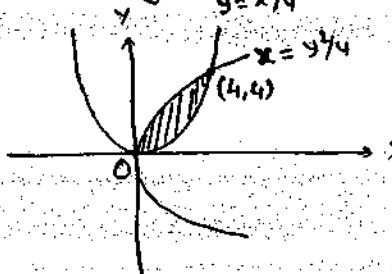
$$\Rightarrow y = \frac{17 \pm \sqrt{289 - 256}}{4} = \frac{17 \pm \sqrt{33}}{4}$$



$$\therefore A = \int_{\frac{17-\sqrt{33}}{4}}^{\frac{17+\sqrt{33}}{4}} [(y-4) - \frac{y^2}{2}] dy$$

4. The area between the curves $y^2 = 4x$ & $x^2 = 4y$ is —

Solⁿ:— $A = \int_0^4 (2\sqrt{x} - \frac{x^2}{4}) dx = \frac{16}{3}$.



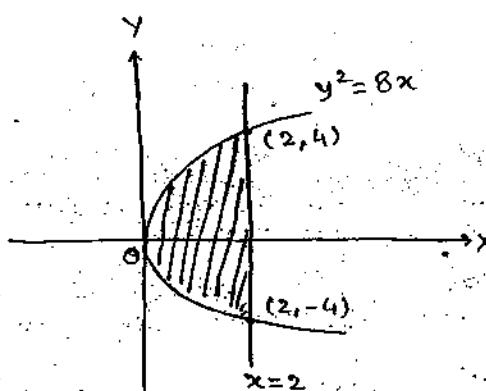
5. The volume generated by revolving the area bounded by parabola $y^2 = 8x$ and st. line $x=2$ about y-axis is _____.

- (a) $\frac{128\pi}{5}$ (b) $\frac{5\pi}{128}$ (c) $\frac{127\pi}{5}$ (d) none

$$\text{Soln: } \rightarrow V = \int_{y_1}^{y_2} \pi x^2 dy$$

$$= \int_{-4}^4 \pi \frac{y^4}{64} dy$$

$$= \frac{\pi}{64} \left[\frac{y^5}{5} \right]_{-4}^4 = \frac{32\pi}{5}$$



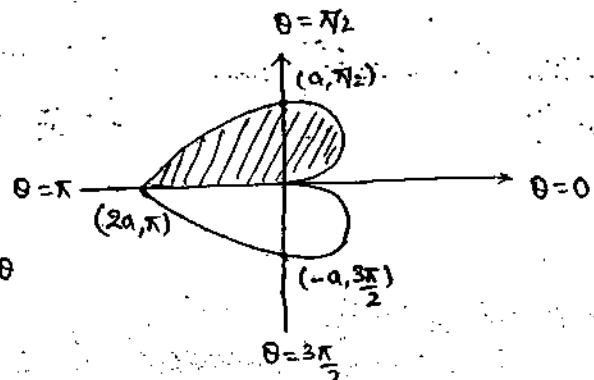
$$\text{Total volume} = \int_{-4}^4 \pi x^2 dy = \int_{-4}^4 \pi (2)^2 dy = 4\pi [y]_{-4}^4 = 32\pi$$

$$\therefore \text{Remaining volume} = 32\pi - \frac{32\pi}{5} = \frac{128\pi}{5}$$

6. The volume of solid generated by revolving the cardioid $r = a(1-\cos\theta)$ about the initial line is _____.

$$\text{Soln: } \rightarrow V = \int_{\theta_1}^{\theta_2} \frac{2\pi}{3} r^3 \sin\theta d\theta$$

$$= \int_0^{\pi} \frac{2\pi}{3} a^3 (1-\cos\theta)^3 \sin\theta d\theta$$



$$\text{Set } 1-\cos\theta = t \Rightarrow \sin\theta d\theta = dt$$

$$\text{as } \theta = 0, t = 0$$

$$\theta = \pi, t = 2$$

$$\therefore V = \int_0^2 \frac{2\pi}{3} a^3 t^3 dt = \frac{2\pi a^3}{3} \left[\frac{t^4}{4} \right]_0^2 = \frac{8\pi a^3}{3}$$

Vector Calculus:

Position Vector: → The position vector of the point $P(x, y, z)$ in the space is

$$\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}, \quad |\vec{r}| = \sqrt{x^2 + y^2 + z^2}$$

In parametric form,

$$\vec{r} = x(t)\hat{i} + y(t)\hat{j} + z(t)\hat{k}$$

$$\text{let } \vec{a} = a_1\hat{i} + a_2\hat{j} + a_3\hat{k}$$

$$\vec{b} = b_1\hat{i} + b_2\hat{j} + b_3\hat{k}$$

$$(i) \vec{a} \cdot \vec{b} = |\vec{a}| |\vec{b}| \cos(\vec{a}, \vec{b}) = a_1 b_1 + a_2 b_2 + a_3 b_3$$

$$(ii) \vec{a} \times \vec{b} = |\vec{a}| |\vec{b}| \sin(\vec{a}, \vec{b}) \hat{n} \quad \text{where } \hat{n} \text{ is vector of unit length perpendicular}$$

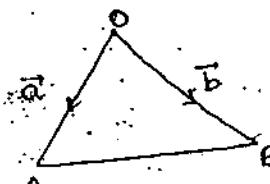
to the plane contains \vec{a} & \vec{b} .

$$\vec{a} \times \vec{b} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix}$$

Note: → (i) Area of $\triangle OAB$

$$= \frac{1}{2} |\vec{OA} \times \vec{OB}|$$

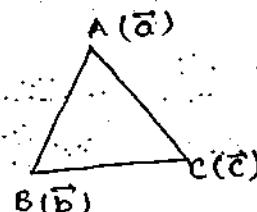
$$= \frac{1}{2} |\vec{a} \times \vec{b}|$$



(ii) Area of $\triangle ABC$

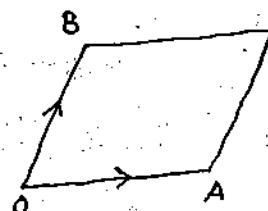
$$= \frac{1}{2} |\vec{AB} \times \vec{AC}|$$

$$= \frac{1}{2} |(\vec{b} - \vec{a}) \times (\vec{c} - \vec{a})|$$



(iii) Area of parallelogram

$$= |\vec{a} \times \vec{b}|$$



Scalar Triple Products:

$$(\vec{a} \times \vec{b}) \cdot \vec{c} = \vec{a} \cdot (\vec{b} \times \vec{c}) = [\vec{a} \vec{b} \vec{c}]$$

$$= \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix}$$

Note: → (i) Volume of parallelopiped, $V = |[\vec{a} \vec{b} \vec{c}]|$

(ii) Volume of tetrahedron, $V = \frac{1}{6} |[\vec{a} \vec{b} \vec{c}]|$

where, \vec{a} , \vec{b} & \vec{c} are edge vectors of ~~parallelopiped~~ parallelopipede.

Vector Triple Product: →

$$(\vec{a} \times \vec{b}) \times \vec{c} = (\vec{c} \cdot \vec{a}) \vec{b} - (\vec{c} \cdot \vec{b}) \vec{a}$$

$$\vec{a} \times (\vec{b} \times \vec{c}) = (\vec{c} \cdot \vec{a}) \vec{b} - (\vec{b} \cdot \vec{a}) \vec{c}$$

6. Vector Differentiation: → Let $\vec{r}(t) = \vec{f}(t)$ be the vector eqn of the curve

then $\frac{d\vec{r}}{dt} = \lim_{\Delta t \rightarrow 0} \frac{\vec{f}(t + \Delta t) - \vec{f}(t)}{\Delta t}$

If t is a time variable then $\frac{d\vec{r}}{dt}$ represents a velocity vector.

Note: → (i) $\frac{d\vec{r}}{dt}$ is a vector in the direction of tangent to the curve at that point.

(ii) $\vec{F}(t)$ is constant in magnitude then, $\vec{F} \cdot \frac{d\vec{F}}{dt} = 0$

(iii) $\vec{F}(t)$ vector with fixed direction then, $\vec{F} \times \frac{d\vec{F}}{dt} = 0$

Properties: → Let $\vec{a}(t)$ & $\vec{b}(t)$ be the vector fun of the scalar variable 't' and ϕ be a scalar fun then,

(i) $\frac{d}{dt} (\vec{a} \pm \vec{b}) = \frac{d\vec{a}}{dt} \pm \frac{d\vec{b}}{dt}$

(ii) $\frac{d}{dt} (\vec{a} \cdot \vec{b}) = \frac{d\vec{a}}{dt} \cdot \vec{b} + \vec{a} \cdot \frac{d\vec{b}}{dt}$

(iii) $\frac{d}{dt} (\vec{a} \times \vec{b}) = \left(\frac{d\vec{a}}{dt} \times \vec{b} \right) + \left(\vec{a} \times \frac{d\vec{b}}{dt} \right)$

(iv) $\frac{d}{dt} (\phi \vec{a}) = \frac{d\phi}{dt} \vec{a} + \phi \frac{d\vec{a}}{dt}$

Point function: \rightarrow If the value of function depends on position of point, then it is said to be point fun.

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Scalar Point function: \rightarrow If to each point $P(x,y,z)$ in region R of space \exists a unit scalar associated with it, then, $\phi(x,y,z)$ is a scalar-point function.

The set of all points in the region R of space together with the scalar values forms a scalar field.

Eg: \rightarrow The temp. $T(x,y,z)$ at any point on a body is a scalar point function and the medium it self is a scalar field.

Vector Point Function: \rightarrow The velocity at any time t of a particle in a fluid flow is a vector point fun.

Vector Differential Operator: \rightarrow (del) $\vec{\nabla}$

$$\vec{\nabla} = \hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z}$$

Level Surface: \rightarrow Let $\phi(x,y,z)$ be a scalar field in the region R , then the set of points satisfying $\phi(x,y,z) = c$, where, c is an arbitrary const, constitutes a family of surfaces called level surfaces.

Gradient of a Scalar function: \rightarrow Let $\phi(x,y,z)$ be a differentiable scalar pt. fun then gradient of scalar denoted by grad ϕ

$$(or) \vec{\nabla} \phi = \hat{i} \frac{\partial \phi}{\partial x} + \hat{j} \frac{\partial \phi}{\partial y} + \hat{k} \frac{\partial \phi}{\partial z}$$

vector normal to surface ϕ

$$\frac{\vec{\nabla} \phi}{|\vec{\nabla} \phi|} \rightarrow \text{unit vector normal to surface } \phi$$

~~1) $\vec{\nabla} \phi$~~

Questions: →

1. ∇r is _____. If $\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$

$$\text{Soln: } r = \sqrt{x^2 + y^2 + z^2} \Rightarrow \nabla r = \frac{\vec{r}}{|r|}$$

$$\text{Note: } \nabla f(r) = f'(r) \frac{\vec{r}}{r}$$

$$\text{Ex: } \nabla(\log r) = \frac{1}{r} \cdot \frac{\vec{r}}{r} = \frac{\vec{r}}{r^2}$$

$$\nabla(\sin \log r) = \frac{\cos \log r}{r} \cdot \frac{\vec{r}}{r} = \frac{\cos \log r \cdot \vec{r}}{r^2}$$

2. The unit vector normal to the surface $y^2 = 8x$ at $(1, 2)$ is ____.

$$\text{Soln: } \text{let } \phi = y^2 - 8x$$

$$\nabla \phi = -8\hat{i} + 2y\hat{j}$$

$$\nabla \phi|_{(1,2)} = -8\hat{i} + 4\hat{j}$$

$$\therefore \hat{n} = \frac{\nabla \phi}{|\nabla \phi|} = \frac{-8\hat{i} + 4\hat{j}}{\sqrt{64+16}} = \frac{-8\hat{i} + 4\hat{j}}{\sqrt{80}}$$

unit

3. A sphere of radius is centred at origin. The unit normal at a point $P(x,y,z)$ to the surface of the sphere is the vector

- (a) $(\frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}})$ (b) $(\frac{x}{\sqrt{3}}, \frac{y}{\sqrt{3}}, \frac{z}{\sqrt{3}})$ (c) (x, y, z) (d) $(\frac{x}{\sqrt{2}}, \frac{y}{\sqrt{2}}, \frac{z}{\sqrt{2}})$

$$\text{Soln: } x^2 + y^2 + z^2 = 1$$

$$\text{let } \phi = x^2 + y^2 + z^2$$

$$\nabla \phi = 2x\hat{i} + 2y\hat{j} + 2z\hat{k}$$

$$\frac{\nabla \phi}{|\nabla \phi|} = \frac{2x\hat{i} + 2y\hat{j} + 2z\hat{k}}{\sqrt{4x^2 + 4y^2 + 4z^2}} = x\hat{i} + y\hat{j} + z\hat{k}$$

Directional Derivative: \rightarrow The directional derivative of a differentiable scalar fun $\phi(x,y,z)$ in the direction of \vec{a} is given by,

$$D.D. = \vec{\nabla}\phi \cdot \frac{\vec{a}}{|\vec{a}|}$$

Let, $\vec{a} = \hat{i}$, then,

$$\begin{aligned} D.D. &= \vec{\nabla}\phi \cdot \frac{\hat{i}}{|\hat{i}|} = \left(\frac{\partial\phi}{\partial x} \hat{i} + \frac{\partial\phi}{\partial y} \hat{j} + \frac{\partial\phi}{\partial z} \hat{k} \right) \cdot \hat{i} \\ &= \frac{\partial\phi}{\partial x} \end{aligned}$$

Let, $\frac{\vec{a}}{|\vec{a}|} = \hat{b}$, then, $D.D. = \vec{\nabla}\phi \cdot \hat{b} = |\vec{\nabla}\phi| |\hat{b}| \cos\theta = |\vec{\nabla}\phi| \cos\theta$

The max. value of $\cos\theta = 1$ i.e. when $\theta = 0$ i.e. when \hat{b} is parallel to $\vec{\nabla}\phi$. Therefore the value of the directional derivative is maximum in the direction of normal to the surface ϕ , and the maximum value of directional derivative is $|\vec{\nabla}\phi|$.

Angle Between Surfaces: \rightarrow Angle between the normal to the surfaces at the pt. of intersection is taken as the angle between the surfaces. Let θ be the angle b/w the surfaces $\phi_1(x,y,z) = c_1$ & $\phi_2(x,y,z) = c_2$ then

$$\cos\theta = \frac{\vec{\nabla}\phi_1 \cdot \vec{\nabla}\phi_2}{|\vec{\nabla}\phi_1| |\vec{\nabla}\phi_2|}$$

Questions:

1. The directional derivative of $f(x,y) = x^2 - y^2$ at $(1,2)$ in the direction of $4\hat{i} + 3\hat{j}$ is

- (a) $\frac{4}{5}$ (b) $\frac{3}{5}$ (c) $-\frac{4}{5}$ (d) $-\frac{3}{5}$

Sol: $\rightarrow D.D. = \vec{\nabla}f \cdot \frac{\vec{a}}{|\vec{a}|} = (2x\hat{i} - 2y\hat{j}) \cdot \frac{(4\hat{i} + 3\hat{j})}{5} = \frac{8x - 6y}{5} \Big|_{(1,2)} = \frac{8 - 12}{5} = -\frac{4}{5}$

2. The directional derivative $\phi = x^2 - y^2 + 2z^2$ at $P(1, 2, 3)$ in direction \overrightarrow{PQ} where $Q = (5, 0, 4)$ _____.

$$\text{Soln: } \overrightarrow{PQ} = \overrightarrow{OQ} - \overrightarrow{OP} = (5, 0, 4) - (1, 2, 3) = (4, -2, 1)$$

$$\begin{aligned} A.A. &= \nabla \phi \cdot \frac{\overrightarrow{PQ}}{|\overrightarrow{PQ}|} = (2x\hat{i} - 2y\hat{j} + 4z\hat{k}) \cdot \frac{(4\hat{i} - 2\hat{j} + \hat{k})}{\sqrt{16+4+1}} \\ &= \frac{8x + 4y + 4z}{\sqrt{21}} \Big|_{(1, 2, 3)} = \frac{28}{\sqrt{21}}. \end{aligned}$$

3. The directional derivative $f = xy^2 + yz^2 + zx^2$ along to the tangent to the curve $x=t$, $y=t^2$ & $z=t^3$ at $(1, 1, 1)$ is _____.

Soln: Vector eqn of the curve is given by

$$\begin{aligned} \vec{x}(t) &= x(t)\hat{i} + y(t)\hat{j} + z(t)\hat{k} \\ &= t\hat{i} + t^2\hat{j} + t^3\hat{k} \end{aligned}$$

$$\frac{d\vec{x}}{dt} \Big|_{(1, 1, 1)} = \hat{i} + 2t\hat{j} + 3t^2\hat{k} \Big|_{t=1} = \hat{i} + 2\hat{j} + 3\hat{k} = \vec{a}$$

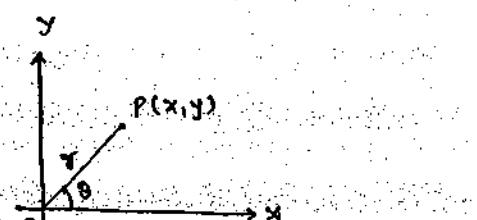
$$\begin{aligned} A.A. &= \nabla f \cdot \frac{\vec{a}}{|\vec{a}|} = [(y^2 + 2zx)\hat{i} + (2xy + z^2)\hat{j} + (2yz + x^2)\hat{k}] \cdot \frac{(\hat{i} + 2\hat{j} + 3\hat{k})}{\sqrt{1+4+9}} \\ &= \frac{18}{\sqrt{14}}. \end{aligned}$$

4. The directional derivative of $\phi = \frac{y}{x^2+y^2}$ along the line which makes angle 30° with positive x -axis is _____.

$$\text{Soln: } \vec{x} = x\hat{i} + y\hat{j}$$

$$\vec{x} = r\cos\theta\hat{i} + r\sin\theta\hat{j}$$

$$\Rightarrow \frac{\vec{x}}{r} = \cos\theta\hat{i} + \sin\theta\hat{j}$$



Note: The vector eqn of a st. line which makes an angle θ with +ve x -axis is $\cos\theta\hat{i} + \sin\theta\hat{j}$

$$\therefore \frac{\vec{r}}{r} = \cos 30^\circ \hat{i} + \sin 30^\circ \hat{j} = \frac{\sqrt{3}}{2} \hat{i} + \frac{1}{2} \hat{j}$$

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$$\therefore D.D. = \vec{\nabla} \phi \cdot \frac{\vec{r}}{r} = -\frac{1}{2}$$

5. The greatest rate of increase of $\phi = x^2yz$ at $(2, -1, 2)$ is _____.

$$\text{Soln: } \vec{\nabla} \phi = 2xyz \hat{i} + x^2z \hat{j} + x^2y \hat{k}$$

$$\therefore \vec{\nabla} \phi \Big|_{(2, -1, 2)} = -8\hat{i} + 8\hat{j} - 4\hat{k}$$

Greatest rate of increase (or) max. value of D.D. = $|\vec{\nabla} \phi|$

$$= \sqrt{64+64+16}$$

$$= \sqrt{144} = 12$$

6. The angle b/w the surfaces $x^2+y^2+z^2=9$ & $x^2+y^2-z=3$ at $(2, -1, 2)$ is _____.

$$\text{Soln: } \text{Let, } \phi_1 = x^2+y^2+z^2 \Rightarrow \vec{\nabla} \phi_1 = 2x\hat{i} + 2y\hat{j} + 2z\hat{k}$$

$$\Rightarrow \vec{\nabla} \phi_1 \Big|_{(2, -1, 2)} = 4\hat{i} - 2\hat{j} + 4\hat{k}$$

$$\text{Let, } \phi_2 = x^2+y^2-z \Rightarrow \vec{\nabla} \phi_2 = 2x\hat{i} + 2y\hat{j} - \hat{k}$$

$$\Rightarrow \vec{\nabla} \phi_2 \Big|_{(2, -1, 2)} = 4\hat{i} - 2\hat{j} - \hat{k}$$

$$\cos \theta = \frac{\vec{\nabla} \phi_1 \cdot \vec{\nabla} \phi_2}{|\vec{\nabla} \phi_1| |\vec{\nabla} \phi_2|} = \frac{16+4-4}{\sqrt{16+4+16} \sqrt{16+4+1}} = \frac{16}{\sqrt{36} \sqrt{21}} = \frac{16}{6\sqrt{21}}$$

$$\Rightarrow \theta = \cos^{-1} \left(\frac{8}{3\sqrt{21}} \right).$$

7. If \vec{a} & \vec{b} are two arbitrary vectors with magnitudes a & b respectively

$$\text{then, } |\vec{a} \times \vec{b}|^2 = \underline{\underline{\quad}}$$

$$\text{Soln: } \vec{a} \times \vec{b} = (\vec{a} + \vec{b}) \sin \theta \hat{n}$$

$$|\vec{a} \times \vec{b}|^2 = a^2 b^2 \sin^2 \theta = a^2 b^2 (1 - \cos^2 \theta) = a^2 b^2 \left(1 - \frac{(\vec{a} \cdot \vec{b})^2}{a^2 b^2} \right)$$

$$= a^2 b^2 - (\vec{a} \cdot \vec{b})^2$$

Divergence of a Vector function: → Let $\vec{F}(x, y, z) = F_1 \hat{i} + F_2 \hat{j} + F_3 \hat{k}$ be the differential vector point function then

$$\operatorname{div} \vec{F} = \nabla \cdot \vec{F} = \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z}$$

Note: → If $\nabla \cdot \vec{F} = 0$ then \vec{F} is called solenoidal vector.

Curl of a Vector function: →

$$\operatorname{curl} \vec{F} = \nabla \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_1 & F_2 & F_3 \end{vmatrix}$$

Note: → (i) If $\nabla \times \vec{F} = \vec{0}$ then \vec{F} is called irrotational vector.

(ii) If $\vec{v} \rightarrow$ velocity vector

$\vec{\omega} \rightarrow$ angular velocity

then, $\vec{v} = \vec{\omega} \times \vec{r}$

$$\operatorname{curl} \vec{v} = \nabla \times (\vec{\omega} \times \vec{r}) = 2\vec{\omega}$$

$$\Rightarrow \vec{\omega} = \frac{1}{2} \operatorname{curl} \vec{v}$$

Scalar Potential function: → For every rotation vector, there is a function ϕ scalar.

s.t. $\vec{F} = \nabla \phi$, then ϕ is said to be scalar potential fun.

Note: → (i) $\operatorname{curl}(\operatorname{grad} \phi) = \vec{0}$

(ii) $\operatorname{div}(\operatorname{curl} \vec{F}) = 0$

(iii) $\operatorname{div}(\operatorname{grad} \phi) = \nabla \cdot (\nabla \phi) = \nabla^2 \phi$

where, $\nabla^2 \rightarrow$ Laplacian operator

$$\nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$$

Questions:-

1. The value of $\nabla \cdot (\gamma^n \vec{r}) = \underline{\hspace{2cm}}$, where $\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$

- (a) $(n+3)\gamma^n$ (b) $(n-2)\gamma^n$ (c) $n\gamma^{n-3}$ (d) $(n+2)\gamma^{n-1}$

and hence which of the following is solenoidal

- (a) $\gamma^3 \vec{r}$ (b) $\gamma \vec{r}$ (c) $\frac{\vec{r}}{\gamma^3}$ (d) $\frac{\vec{r}}{\gamma^2}$

$$\text{Soln} \rightarrow \gamma^n \vec{r} = \underbrace{\gamma^n x \hat{i}}_{F_1} + \underbrace{\gamma^n y \hat{j}}_{F_2} + \underbrace{\gamma^n z \hat{k}}_{F_3}$$

$$\nabla \cdot (\gamma^n \vec{r}) = \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z}$$

$$\begin{aligned} \frac{\partial F_1}{\partial x} &= \frac{\partial}{\partial x} (\gamma^n x) = \gamma^n + x n \gamma^{n-1} \frac{\partial \gamma}{\partial x} \\ &= \gamma^n + n x \gamma^{n-1} \frac{x}{x} \\ &= \gamma^n + n x \gamma^{n-2} x^2 \end{aligned}$$

$$\text{Similarly, } \frac{\partial F_2}{\partial y} = \gamma^n + n \gamma^{n-2} y^2, \quad \frac{\partial F_3}{\partial z} = \gamma^n + n \gamma^{n-2} z^2$$

$$\begin{aligned} \therefore \nabla \cdot (\gamma^n \vec{r}) &= 3\gamma^n + n \gamma^{n-2} (x^2 + y^2 + z^2) = 3\gamma^n + n \gamma^{n-2} \cdot r^2 \\ &= 3\gamma^n + n \gamma^n = (n+3)\gamma^n \end{aligned}$$

Now, for solenoidal. $\nabla \cdot (\gamma^n \vec{r}) = 0$

$$\Rightarrow (n+3)\gamma^n = 0 \Rightarrow n = -3$$

$$2. \nabla \cdot \left(\frac{\vec{r}}{\gamma^3} \right) = 0.$$

2. If $\vec{F} = (8x^2 + 2y)\hat{i} - 4xz\hat{j} + 3xy^2\hat{k}$ represents a velocity vector then

corresponding angular velocity at $(2, 2, -1)$ is $\underline{\hspace{2cm}}$.

$$\text{Soln} \rightarrow \text{curl } \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 8x^2 + 2y & -4xz & 3xy^2 \end{vmatrix} = 32\hat{i} - 12\hat{j} + 2\hat{k}$$

$$\therefore \vec{\omega} = \frac{1}{2} \text{curl } \vec{F} = 16\hat{i} - 6\hat{j} + \hat{k}$$

3. If $\phi(x,y) = ax^2y - y^3$ & $\nabla^2\phi = 0$ then, $a = \underline{\hspace{2cm}}$.

- (a) 2 (b) 3 (c) -2 (d) -3

$$\text{Soln: } \rightarrow \nabla^2\phi = \frac{\partial^2\phi}{\partial x^2} + \frac{\partial^2\phi}{\partial y^2} + \frac{\partial^2\phi}{\partial z^2} = 0$$

$$\Rightarrow \cancel{2ay} - 6y = 0 \Rightarrow a = 3.$$

4. If $\vec{F} = (5x+7z^2)\hat{i} + (4x^2+\lambda y)\hat{j} + (7z-2xy)\hat{k}$ is solenoidal then $\lambda = \underline{\hspace{2cm}}$

$$\text{Soln: } \rightarrow \nabla \cdot \vec{F} = 0$$

$$\Rightarrow 5 + \lambda + 7 = 0 \Rightarrow \lambda = -12.$$

5. If $\vec{F} = 5x^2z\hat{i} - 7xy^2\hat{j} + (12x+7z)\hat{k}$ then $\nabla \cdot (\nabla \times \vec{F})$ at $(5,3,-2)$ is 0.

6. If $\vec{F} = (x+2y+az)\hat{i} + (bx-3y-z)\hat{j} + (4x+cy+2z)\hat{k}$ is irrotational vector

fun then $a,b,c = \underline{\hspace{2cm}}$.

$$\text{Soln: } \rightarrow \nabla \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x+2y+az & bx-3y-z & 4x+cy+2z \end{vmatrix}$$

$$= \hat{i}(b+1) + \hat{j}(4-a) + \hat{k}(b-2)$$

$$= 0$$

$$\therefore c = -1, a = 4, b = 2.$$

7. Vector Integration: \rightarrow

Line Integral: An integral evaluated over a curve is called line integral.

Let, $\vec{F}(x,y,z) = f_1\hat{i} + f_2\hat{j} + f_3\hat{k}$ be a differentiable point

function defined at each point on the curve 'c' then its line integral is

$$\int_C \vec{F} \cdot d\vec{r} = \int_C (f_1 dx + f_2 dy + f_3 dz)$$

Note:- If C is a closed curve, then line integral of \vec{F} over ' C ' is called circulation of \vec{F} , i.e. $\oint_C \vec{F} \cdot d\vec{r}$. 39

Work done by a force:- The total work done by a force \vec{F} in moving a particle along a curve ' C ' is $\int_C \vec{F} \cdot d\vec{r}$.

Note:- If \vec{F} is irrotational, then, the line integral of \vec{F} is independent of the path.

i.e. when \vec{F} is irrotational we have $\vec{F} = \nabla \phi$, where ϕ is

a scalar potential fn then,

$$\int_a^b \vec{F} \cdot d\vec{r} = \phi_b - \phi_a .$$

Questions:-

1. The value of $\int_C \vec{F} \cdot d\vec{r}$, where, $\vec{F} = 3xy\hat{i} - y^2\hat{j}$ if ' C ' is the curve $y=2x^2$ joining pts $(0,0)$ & $(1,2)$ is _____.

Soln:- $\int_C \vec{F} \cdot d\vec{r} = \int_C (F_1 dx + F_2 dy + F_3 dz) = \int_C (3xy dx - y^2 dy)$

$$= \int_0^1 [3x(2x^2) dx - 4x^4 \cdot 4x dx] \quad \left\{ \begin{array}{l} \Rightarrow y=2x^2 \\ \Rightarrow dy = 4x dx \end{array} \right\}$$

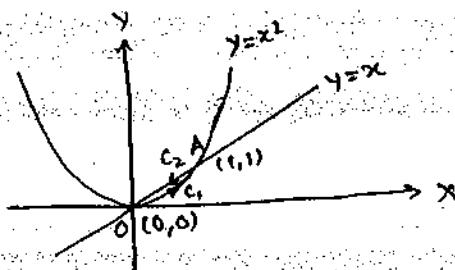
$$= \frac{6}{4} - \frac{16}{6} =$$

2. The value of $\int_C \vec{F} \cdot d\vec{r}$, where, $\vec{F} = 3xy\hat{i} - y^2\hat{j}$ if ' C ' is the curve bounded by $y=x$ & $y=x^2$ is _____.

Soln:- $\int_C \vec{F} \cdot d\vec{r} = \int_{C_1} \vec{F} \cdot d\vec{r} + \int_{C_2} \vec{F} \cdot d\vec{r}$

along C_1 , $y=x^2 \Rightarrow dy = 2x dx$

$$\int_{C_1} \vec{F} \cdot d\vec{r} = \int_{C_1} (3xy dx - y^2 dy)$$



$$= \int_0^1 [3x(x^2) dx - x^4 \cdot 2x dx] = \frac{5}{12}$$

Now, along C_2 , $y=x \Rightarrow dy=dx$

$$\therefore \int_{C_2} \vec{F} \cdot d\vec{x} = \int_1^0 [3x(x) dx - x^2 dx] = -\frac{2}{3}$$

$$\therefore \int \vec{F} \cdot d\vec{x} = \frac{5}{12} - \frac{2}{3} = -\frac{3}{12} = -\frac{1}{4}$$

3. The value of $\int_C [(3x+4y) dx + (2x-3y) dy]$ where, 'C' is the circle of radius 2, with centre at origin in x-y plane is _____.

- (a) 4π (b) 8π (c) -4π (d) -8π

Soln: Here, $C \rightarrow x^2 + y^2 = 2^2$

Whenever the curve is circle we will go for polar form.

$$\text{let, } x = 2\cos\theta ; y = 2\sin\theta$$

$$\Rightarrow dx = -2\sin\theta d\theta, dy = 2\cos\theta d\theta$$

$$\begin{aligned} & \int_0^{2\pi} [(3x \cdot 2\cos\theta + 4y \cdot 2\sin\theta)(-2\sin\theta d\theta) + (2x \cdot 2\cos\theta - 3y \cdot 2\sin\theta)(2\cos\theta d\theta)] \\ &= \int_0^{2\pi} [-12\sin\theta\cos\theta - 16\sin^2\theta d\theta + 8\cos^2\theta d\theta - 12\sin\theta\cos\theta d\theta] \end{aligned}$$

$$= \int_0^{2\pi} [-24\sin\theta\cos\theta d\theta - 16\sin^2\theta d\theta + 8\cos^2\theta d\theta]$$

4. The value of $\int_C \vec{F} \cdot d\vec{x}$, where, $\vec{F} = (2y+3)\hat{i} + xz\hat{j} + (yz-x)\hat{k}$ along the line joining

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(i) $(0,0,1)$ & $(0,1,1)$

(ii) $(0,1,1)$ & $(2,1,1)$

is _____.

Soln: → (i) Along that st. line $x=0, z=1 \Rightarrow dx=0, dz=0$

$$\int_C \vec{F} \cdot d\vec{x} = \int_C F_2 dy = \int_0^1 xz dy = 0.$$

(ii) $y=1, z=1 \Rightarrow dy=0, dz=0$

$$\int_C \vec{F} \cdot d\vec{x} = \int_C F_1 dx = \int_0^2 (2y+3) dx = \int_0^2 5 dx = 5x \Big|_0^2 = 10.$$

5. The total work done by a force $\vec{F} = (3x^2+6y)\hat{i} - 14yz\hat{j} + 20xz^2\hat{k}$ in moving a particle along a st. line joining the pts. $(0,0,0)$ & $(1,2,3)$

is _____.

Soln: → $\frac{x-x_1}{x_2-x_1} = \frac{y-y_1}{y_2-y_1} = \frac{z-z_1}{z_2-z_1} \Rightarrow \frac{x-0}{1-0} = \frac{y-0}{2-0} = \frac{z-0}{3-0} = t$

$$\Rightarrow x=t, y=2t, z=3t$$

$$dx=dt, dy=2dt, dz=3dt$$

$$\int_C \vec{F} \cdot d\vec{x} = \int_C (F_1 dx + F_2 dy + F_3 dz)$$

$$= \int_0^1 [(3t^2+12t)dt + (-14 \times 2t \times 3t)(2dt) + (20 \times t \times 9t^2)(3dt)]$$

$$= \frac{540}{4}$$

6. The line integral $\int \vec{F} \cdot d\vec{r}$ of fun $\vec{F} = 2xyz\hat{i} + x^2z\hat{j} + x^2y\hat{k}$ from the origin $(0,0,0)$ to the pt. $(1,1,1)$ is ____.

- (a) 0 (b) 1 (c) -1

(d) cannot be determined without specifying the path.

$$\text{Soln: } \rightarrow \nabla \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 2xyz & x^2z & x^2y \end{vmatrix} = \hat{i}(x^2 - x^2) - \hat{j}(2xy - 2xy) + \hat{k}(2xz - 2xz) = \vec{0}$$

$\Rightarrow F$ is irrotational.

$$\Rightarrow \vec{F} = \nabla \phi = \frac{\partial \phi}{\partial x} \hat{i} + \frac{\partial \phi}{\partial y} \hat{j} + \frac{\partial \phi}{\partial z} \hat{k}$$

$$\Rightarrow \frac{\partial \phi}{\partial x} = 2xyz, \frac{\partial \phi}{\partial y} = x^2z, \frac{\partial \phi}{\partial z} = x^2y$$

The total differentiation of ϕ ,

$$\begin{aligned} d\phi &= \frac{\partial \phi}{\partial x} dx + \frac{\partial \phi}{\partial y} dy + \frac{\partial \phi}{\partial z} dz \\ &= 2xyz dx + x^2z dy + x^2y dz \\ &= d(x^2yz) \end{aligned}$$

$$\Rightarrow \phi = x^2yz$$

$$\therefore \int_a^b \vec{F} \cdot d\vec{r} = \phi_b - \phi_a = \phi_{(1,1,1)} - \phi_{(0,0,0)} = 1.$$

Green's Theorem in a Plane: \rightarrow Let $M(x,y)$ & $N(x,y)$ be continuous fun

having continuous 1st order partial derivative defined in the closed region R bounded by the closed curve 'C' then,

$$\oint_C (M dx + N dy) = \iint_R \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dx dy$$

Questions:-

1. Evaluate $\oint_C (3x^2 - 8y^2) dx + (4y - 6xy) dy$, where, C is a curve bounded by $x=0, y=0$ & $x+y=1$.

u1

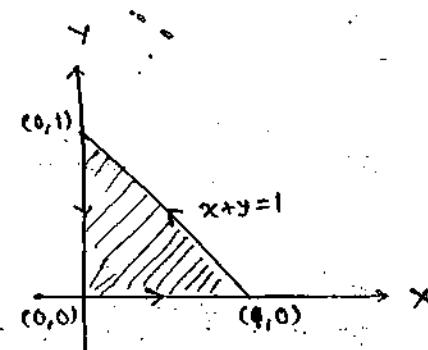
$$\text{Soln: } \rightarrow M = 3x^2 - 8y^2$$

$$\Rightarrow \frac{\partial M}{\partial y} = -16y$$

$$N = 4y - 6xy$$

$$\Rightarrow \frac{\partial N}{\partial x} = -6y$$

$$\therefore \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} = 10y$$



$$\therefore \oint_C M dx + N dy = \iint_R \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dx dy$$

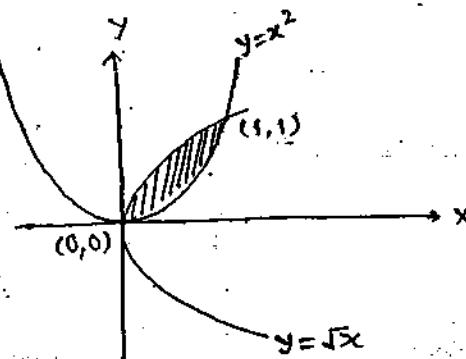
$$= \iint_0^{1-x} 10y \, dx \, dy = 5 \int_0^1 (1-x)^2 \, dx = \frac{5}{3}.$$

2. Evaluate $\oint_C (3x^2 - 8y^2) dx + (4y - 6xy) dy$, where, C is a curve bounded by $y=\sqrt{x}$ & $y=x^2$.

$$\text{Soln: } \rightarrow M = 3x^2 - 8y^2$$

$$\oint_C M dx + N dy = \iint_0^{\sqrt{x}} 10y \, dx \, dy$$

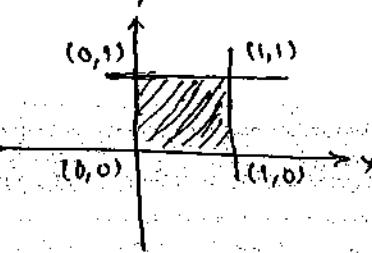
$$= 5 \int_0^1 (x - x^4) \, dx = \frac{3}{2}.$$



3. Evaluate $\oint_C xy \, dy - y^2 \, dx$, where, C is a square cut from the first quadrant from by the lines $x=1$ & $y=1$.

$$\text{Soln: } \rightarrow M = -y^2 \Rightarrow \frac{\partial M}{\partial y} = -2y$$

$$N = xy \Rightarrow \frac{\partial N}{\partial x} = y$$



$$\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} = 3y$$

$$\therefore \oint_C M dx + N dy = \iint_0^1 3y \, dx \, dy = \frac{3}{2}.$$

Surface Integral: → Let $\vec{F}(x, y, z) = f_1 \hat{i} + f_2 \hat{j} + f_3 \hat{k}$ be differentiable vector point fun defined over the surface S then, its surface integra

$$\text{is } \int_S \vec{F} \cdot d\vec{s} = \int_S \vec{F} \cdot \vec{n} \, ds$$

where, \vec{n} = unit outward drawn normal to the surface.

In cartesian form,

$$\int_S \vec{F} \cdot d\vec{s} = \int_S \vec{F} \cdot \vec{n} \, ds = \int (f_1 dy dz + f_2 dx dz + f_3 dx dy)$$

Methods of Evaluation:

(i) If R_1 is the projection of 'S' on to x-y plane then,

$$\int_S \vec{F} \cdot \vec{n} \, ds = \iint_{R_1} \vec{F} \cdot \vec{n} \frac{dx dy}{|\vec{n} \cdot \vec{k}|}$$

(ii) If $R_2 \rightarrow y-z$ plane then,

$$\int_S \vec{F} \cdot \vec{n} \, ds = \iint_{R_2} \vec{F} \cdot \vec{n} \frac{dy dz}{|\vec{n} \cdot \vec{i}|}$$

(iii) If $R_3 \rightarrow x-z$ plane then,

$$\int_S \vec{F} \cdot \vec{n} \, ds = \iint_{R_3} \vec{F} \cdot \vec{n} \frac{dx dz}{|\vec{n} \cdot \vec{j}|}$$

Questions:-

1. The value of $\int_S \vec{F} \cdot \vec{n} ds$, where, $\vec{F} = z\hat{i} + x\hat{j} - 3y^2z\hat{k}$ and S is the surface of the cylinder $x^2 + y^2 = 16$ included in the 1st octant between $x=0$ & $z=5$. 42

Soln:- Let $\phi = x^2 + y^2$

$$\vec{\nabla} \phi = 2x\hat{i} + 2y\hat{j}$$

$$\vec{n} = \frac{\vec{\nabla} \phi}{|\vec{\nabla} \phi|} = \frac{2x\hat{i} + 2y\hat{j}}{\sqrt{4x^2 + 4y^2}} = \frac{x\hat{i} + y\hat{j}}{\sqrt{x^2 + y^2}}$$

$$\vec{n} = \frac{x\hat{i} + y\hat{j}}{4}$$

$$\vec{F} \cdot \vec{n} = \frac{xz}{4} + \frac{xy}{4} = \frac{x}{4}(y+z)$$

Let, R \rightarrow y-z plane.

$$\begin{aligned} \int_S \vec{F} \cdot \vec{n} ds &= \iint_R \vec{F} \cdot \vec{n} \cdot \frac{dydz}{|\vec{n}|} = \iint_R \frac{x}{4}(y+z) \cdot \frac{dydz}{(x/4)} \\ &= \int_{z=0}^5 \int_{y=0}^4 (y+z) dy dz \\ &= \int_0^5 \left(\frac{y^2}{2} + yz\right)_0^4 dz = 90. \end{aligned}$$

2. The value of $\int_S \vec{F} \cdot \vec{n} ds$, where, $\vec{F} = 4xz\hat{i} - y^2\hat{j} + yz\hat{k}$ & S is surface of the cube bounded by $x=0, x=1, y=0, y=1, z=0$ & $z=1$, is _____

Soln:- Method I:-

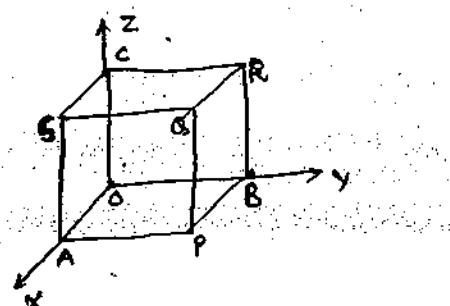
$$\int_S \vec{F} \cdot \vec{n} ds = \int_{S_1} + \int_{S_2} + \dots + \int_{S_6}$$

Over S_1 :- In x-y plane (OAPR):

$$z=0, \vec{n} = -\hat{k}$$

$$\vec{F} \cdot \vec{n} = -yz = 0$$

$$\therefore \int_{S_1} \vec{F} \cdot \vec{n} ds = 0$$



Over S_2 : - parallel to xy plane (SQRc)

$$z=1, \vec{n} = \hat{k}, \vec{F} \cdot \vec{n} = yz = y$$

$$\therefore \int_{S_2} \vec{F} \cdot \vec{n} ds = \iint_R \vec{F} \cdot \vec{n} \frac{dx dy}{|\vec{n} \cdot \hat{k}|} = \iint_0^1 y dx dy = \frac{1}{2}$$

over S_3 : - in $y-z$ plane (OBRC)

$$x=0, \vec{n} = -\hat{i}, \vec{F} \cdot \vec{n} = -4xz = 0$$

$$\therefore \int_{S_3} \vec{F} \cdot \vec{n} ds = 0$$

over S_4 : - parallel to $y-z$ plane (AP)

$$x=1, \vec{n} = \hat{i}, \vec{F} \cdot \vec{n} = 4xz = 4z$$

$$\therefore \int_{S_4} \vec{F} \cdot \vec{n} ds = \iint_R \vec{F} \cdot \vec{n} \frac{dy dz}{|\vec{n} \cdot \hat{i}|} = \iint_0^1 4z dy dz = 2$$

over S_5 : - in $x-z$ plane (OCSA)

$$y=0, \vec{n} = -\hat{j}, \vec{F} \cdot \vec{n} = y^2 = 0$$

$$\therefore \int_{S_5} \vec{F} \cdot \vec{n} ds = 0$$

over S_6 : - parallel to $x-z$ plane (BRQP)

$$y=1, \vec{n} = \hat{j}, \vec{F} \cdot \vec{n} = -y^2 = -1$$

$$\therefore \int_{S_6} \vec{F} \cdot \vec{n} ds = \iint_R \vec{F} \cdot \vec{n} \frac{dx dz}{|\vec{n} \cdot \hat{j}|} = \iint_0^1 (-1) dx dz = -1$$

~~Method~~ $\therefore \int_S \vec{F} \cdot \vec{n} ds = 0 + \frac{1}{2} + 0 + 2 + 0 - 1 = \frac{3}{2}$

Method 2:

$$\int_S \vec{F} \cdot \vec{n} ds = \iint_V \nabla \cdot \vec{F} dV \quad (\text{Divergence Theorem})$$

$$\nabla \cdot \vec{F} = 4z - 2y + y = 4z - y$$

$$\therefore \int_S \vec{F} \cdot \vec{n} ds = \iiint_0^1 (4z - y) dz dy dx = \frac{3}{2}$$

Volume Integral: Let $\vec{F}(x, y, z) = f_1 \hat{i} + f_2 \hat{j} + f_3 \hat{k}$ be the differentiable vector point fun defined in volume V , then, its volume integral is $\int_V \vec{F} \cdot dV$

Similarly, $\phi(x, y, z)$ is scalar point fun, then, $\int \phi dV$

Questions:

- Evaluate $\int_V \vec{F} \cdot dV$ where, $\vec{F} = (2x^2 - 3z) \hat{i} - 2xy \hat{j} - 4x \hat{k}$ and V is the region bounded by the planes $x=0, y=0, z=0$ & $2x+2y+z=4$.

Soln: $\nabla \cdot \vec{F} = 4x - 2z = 2x$

$$\int 2x dV = \int \int \int_{x=0, y=0, z=0}^{2x, 4-2x-2z} 2x dz dy dx = \frac{8}{3}$$

- The volume of an object expressed in spherical coordinate. $V = \int \int \int r^2 \sin\theta dr d\phi d\theta$, then V is _____.

- (a) $\frac{\pi}{3}$ (b) $\frac{\pi}{6}$ (c) $\frac{\pi}{2}$ (d) $\frac{\pi}{4}$

Soln: $V = \int_0^{2\pi} \int_0^{\pi} \int_0^r \sin\theta \frac{r^2}{2} dr d\theta = \frac{1}{2} \int_0^{2\pi} (-\cos\theta) \Big|_0^{\pi} d\theta = \frac{\pi}{3}$

Gauss-Divergence Theorem: Let S be a closed surface enclosing a volume V & $\vec{F}(x, y, z) = f_1 \hat{i} + f_2 \hat{j} + f_3 \hat{k}$ be the differentiable vector point fun defined over S , then,

$$\int_S \vec{F} \cdot d\vec{s} = \int_V \operatorname{div} \vec{F} dV$$

Questions:

- Evaluate $\int_S \vec{F} \cdot \vec{n} ds$, where, $\vec{F} = x \hat{i} + y \hat{j} + z \hat{k}$ & S is a closed surface

enclosing a volume V is _____.

- (a) V (b) $2V$ (c) $3V$ (d) $4V$

2. The value of $\int_S (x \, dy \, dz + y \, dx \, dz + z \, dx \, dy)$, where S is a surface,

(i) cylinder $x^2 + z^2 = 16$ & $y=0$ to $y=3$,

(ii) is a sphere $x^2 + y^2 + z^2 = 9$,

is _____.

$$\text{Soln: } \vec{F} = x\hat{i} + y\hat{j} + z\hat{k} \quad (\because \int_S \vec{x} \cdot \vec{n} \, ds = \int_S \vec{F} \cdot d\vec{s} = \int_S (F_1\hat{i} + F_2\hat{j} + F_3\hat{k}) \, d\vec{s})$$

$$\int \vec{x} \cdot \vec{n} \, ds = 3V$$

$$(i) \int \vec{x} \cdot \vec{n} \, ds = 3\pi r^2 h = 3\pi \times 4^2 \times 3 =$$

$$(ii) \int \vec{x} \cdot \vec{n} \, ds = \frac{4}{3}\pi r^3 = \frac{4}{3}\pi \times 3^3 =$$

3. Evaluate $\int_S (x^2 + 2y^2 + 3z^2) \, ds$, where, S is the surface $x^2 + y^2 + z^2 = 1$.

$$\text{Soln: } \vec{F} \cdot \vec{n} = x^2 + 2y^2 + 3z^2$$

$$\phi = x^2 + y^2 + z^2$$

$$\vec{n} = \frac{\nabla \phi}{|\nabla \phi|} = x\hat{i} + y\hat{j} + z\hat{k}$$

Let, $F_1\hat{i} + F_2\hat{j} + F_3\hat{k} = \vec{F}$, then,

$$\vec{F} \cdot \vec{n} = F_1 x + F_2 y + F_3 z = x^2 + 2y^2 + 3z^2$$

$$\Rightarrow F_1 = x, F_2 = 2y, F_3 = 3z$$

$$\therefore \vec{F} = x\hat{i} + 2y\hat{j} + 3z\hat{k}$$

$$\therefore \int_S \vec{F} \cdot d\vec{s} = \int_V \nabla \cdot \vec{F} \, dv = \int (1+2+3) \, dv = 6V = \frac{6 \times 4\pi \times 1}{3} = 8\pi.$$

4. The value of $\int_S \vec{F} \cdot \vec{n} \, ds$, where $\vec{F} = 4x^2\hat{i} - 3y\hat{j} + 8xz\hat{k}$ & S is a

surface $0 \leq x \leq 1, 0 \leq y \leq 2$, & $0 \leq z \leq 3$, is _____.

$$\text{Soln: } \nabla \cdot \vec{F} = 8x - 3 + 8x = 16x - 3$$

$$\int_S \vec{F} \cdot \vec{n} \, ds = \int_V \nabla \cdot \vec{F} \, dv = \int_{x=0}^1 \int_{y=0}^2 \int_{z=0}^3 (16x - 3) \, dx \, dy \, dz = 30.$$

5. Evaluate $\int_S \vec{F} \cdot \vec{n} ds$, where, $\vec{F} = 4x\hat{i} - 2y^2\hat{j} + z^2\hat{k}$, taken over the region bounded by $x^2 + y^2 = 4$ & $z=0$ to $z=3$.

$$\text{Soln: } \rightarrow \nabla \cdot \vec{F} = 4 - 4y + 2z$$

$$\begin{aligned}\therefore \int_S \vec{F} \cdot \vec{n} ds &= \int_V \nabla \cdot \vec{F} dV = \int_{x=-2}^2 \int_{y=-\sqrt{4-x^2}}^{\sqrt{4-x^2}} \int_{z=0}^3 (4 - 4y + 2z) dx dy dz \\ &= 2 \int_0^3 \int_{-2}^2 (4 + 2z) \sqrt{4-x^2} dx dz \\ &= 4 \int_0^3 \int_0^2 (4 + 2z) \sqrt{4-x^2} dx dz \\ &= 4 \int_0^3 (4 + 2z) \left[\frac{x\sqrt{4-x^2}}{2} + \frac{4}{2} \sin^{-1}\left(\frac{x}{2}\right) \right]_0^2 dz \\ &= 4\pi \int_0^3 (4 + 2z) dz = 84\pi.\end{aligned}$$

Note: → we can also solve the above problem in polar form.

6. Evaluate $\int_S \vec{F} \cdot \vec{n} ds$, where, $\vec{F} = 4x^2z\hat{i} - (yz-7)\hat{j} + xy^2z\hat{k}$, and S is the surface bounded by $y^2 + z^2 = 25$ & $x=0$ to $x=2$.

$$\text{Soln: } \rightarrow \int_S \nabla \times \vec{F} \cdot \vec{n} ds = \int_V \operatorname{div}(\nabla \times \vec{F}) dV = 0.$$

Stoke's Theorem: → Let S be an open surface bounded by a closed

curve ' C ' & $\vec{F}(x, y, z) = f_1\hat{i} + f_2\hat{j} + f_3\hat{k}$ be a differentiable vector function

$$\text{defined over 'S', then } \oint_C \vec{F} \cdot d\vec{s} = \int_S \nabla \times \vec{F} \cdot d\vec{s} = \int_S \nabla \times \vec{F} \cdot \vec{n} ds$$

$$\text{i.e. } \oint_C (f_1 dx + f_2 dy + f_3 dz) = \int_S (\nabla \times \vec{F}) \cdot \vec{n} ds$$

Question: → 1. The value of $\int_C \vec{F} \cdot d\vec{s}$, where $\vec{F} = yz\hat{i} + xz\hat{j} + xy\hat{k}$, if C is
a curve $x^2 + y^2 = 4$ in XY plane is _____.

- (a) 0 (b) $\frac{1}{2}$ (c) 2 (d) 3

$$\text{Soln: } \rightarrow \vec{\nabla} \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ yz & xz & xy \end{vmatrix} = \hat{i}(x-x) - \hat{j}(y-y) + \hat{k}(z-z) = \vec{0}$$

$$\therefore \int_C \vec{F} \cdot d\vec{s} = \int_S (\vec{\nabla} \times \vec{F}) \cdot \vec{n} ds = \int_S \vec{0} \cdot \vec{n} ds = 0.$$

2. The value of $\int_C \vec{F} \cdot d\vec{x}$, where $\vec{F} = -y^3\hat{i} + x^3\hat{j}$ if C is the circular disc
 $x^2 + y^2 \leq 1$, $z=0$ is _____.

$$\text{Soln: } \rightarrow \vec{\nabla} \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ -y^3 & x^3 & 0 \end{vmatrix} = \hat{i}(0-0) - \hat{j}(0-0) + \hat{k}(3x^2 + 3y^2) = 3(x^2 + y^2)\hat{k}$$

$$\therefore \vec{\nabla} \times \vec{F} \cdot \vec{n} = 3(x^2 + y^2) \quad \left\{ \because \vec{n} = \hat{k} \right\}$$

$$\therefore \int_C \vec{F} \cdot d\vec{x} = \int_S (\vec{\nabla} \times \vec{F}) \cdot \vec{n} ds$$

$$= \int_S 3(x^2 + y^2) ds$$

Let, $R \rightarrow$ XY plane

$$\int_C \vec{F} \cdot d\vec{x} = \iint_R 3(x^2 + y^2) \frac{dx dy}{|\vec{n} \cdot \hat{k}|} = \iint_R 3(x^2 + y^2) dx dy$$

Let $x = r \cos \theta$, $y = r \sin \theta$

$$x^2 + y^2 = r^2, |J| = r$$

$$\therefore \int_C \vec{F} \cdot d\vec{x} = \iint_0^{2\pi} \int_0^r 3r^2 r dr d\theta = \frac{3r^4}{2} \Big|_0^r = \frac{3r^4}{2}$$

3. Evaluate $\oint_C (y dx + z dy + x dz)$, where C is the curve of intersection

$$\text{of } x^2 + y^2 + z^2 = a^2 \text{ & } x+z=a.$$

Soln: $\vec{F} = y\hat{i} + z\hat{j} + x\hat{k}$

$$\vec{\nabla} \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ y & z & x \end{vmatrix} = \hat{i}(0-1) - \hat{j}(1-0) + \hat{k}(0-1) \\ = -\hat{i} - \hat{j} - \hat{k}$$

The intersection of sphere $x^2 + y^2 + z^2 = a^2$ with the plane $x+z=a$

is a circle in the plane $x+z=a$, with AB as diameter, where

$$A(a, 0, 0) \text{ & } B(0, 0, a)$$

$$AB = \sqrt{a^2 + a^2} = a\sqrt{2}$$

$$\Rightarrow \text{radius} = \frac{a}{\sqrt{2}}$$

$$\text{Let, } \phi = x+z$$

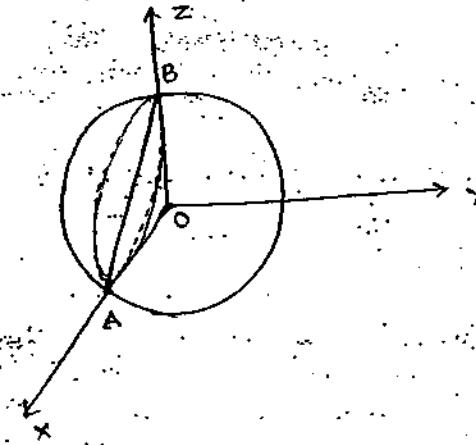
$$\vec{\nabla} \phi = \hat{i} + \hat{k}$$

$$\vec{n} = \frac{\vec{\nabla} \phi}{|\vec{\nabla} \phi|} = \frac{\hat{i} + \hat{k}}{\sqrt{2}}$$

$$(\vec{\nabla} \times \vec{F}) \cdot \vec{n} = (-\hat{i} - \hat{j} - \hat{k}) \cdot \frac{(\hat{i} + \hat{k})}{\sqrt{2}} = -\sqrt{2}$$

$$\oint_C (y dx + z dy + x dz) = \int_S (\vec{\nabla} \times \vec{F}) \cdot \vec{n} ds = \int_S -\sqrt{2} ds = -\sqrt{2} S$$

$$= -\sqrt{2} \pi \times \left(\frac{a}{\sqrt{2}}\right)^2 = -\frac{\pi a^2}{\sqrt{2}}$$



B. Fourier Series : \rightarrow Let $f(x)$ be a periodic fun defined in $(c; c+2l)$ with period $2l$, then, the fourier series of $f(x)$ is given by,

$$f(x) = \frac{a_0}{2} + \sum_{n=1}^{\infty} [a_n \cos \frac{n\pi x}{l} + b_n \sin \frac{n\pi x}{l}]$$

where, a_0, a_n & b_n are fourier coeff. given by,

$$a_0 = \frac{1}{l} \int_c^{c+2l} f(x) dx$$

$$a_n = \frac{1}{l} \int_c^{c+2l} f(x) \cos \frac{n\pi x}{l} dx$$

$$b_n = \frac{1}{l} \int_c^{c+2l} f(x) \sin \frac{n\pi x}{l} dx$$

Note: $\rightarrow [-l, l], [0, 2l], [-\pi, \pi]$ (or) $[0, 2\pi]$

Airchilet's Conditions: \rightarrow A. fun is said to satisfy dirichlet's cond if

- (i) $f(x)$ and its integrals are finite & single valued.
- (ii) $f(x)$ has finite no. of finite discontinuities.
- (iii) $f(x)$ has finite no. of maxima & minima.

Note: \rightarrow If $f(x)$ satisfies Dirichlet's cond then the fourier series is convergent.

Convergence: \rightarrow (i) If $f(x)$ is continuous at $x=c \in (a, b)$ then fourier series of $f(x)$ at $x=c$ converges to $f(c)$.

(ii) If $f(x)$ is discontinuous at $x=c \in (a, b)$ then fourier series of $f(x)$ at $x=c$ converges to $\frac{1}{2} [\lim_{x \rightarrow c^-} f(x) + \lim_{x \rightarrow c^+} f(x)]$

(iii) fourier series of $f(x)$ at the end pt's i.e. $x=a$ (or) b converges to $\frac{1}{2} [\lim_{x \rightarrow a^+} f(x) + \lim_{x \rightarrow b^-} f(x)]$

Fourier Series of Even & Odd function in $[-l, l]$ or $[-\pi, \pi]$:- 46

(i) Fourier Series of an even function :-

$$f(x) = \frac{a_0}{2} + \sum_{n=1}^{\infty} a_n \cos \frac{n\pi x}{l}$$

$$\text{where, } a_0 = \frac{2}{l} \int_0^l f(x) dx$$

$$a_n = \frac{2}{l} \int_0^l f(x) \cos \frac{n\pi x}{l} dx.$$

(ii) Fourier Series of an odd function :-

$$f(x) = \sum_{n=1}^{\infty} b_n \sin \frac{n\pi x}{l}$$

$$\text{where, } b_n = \frac{2}{l} \int_0^l f(x) \sin \frac{n\pi x}{l} dx.$$

Half-Range Series :-

(i) Half-Range cosine series in $[0, l]$:-

$$F(x) = \frac{a_0}{2} + \sum_{n=1}^{\infty} a_n \cos \frac{n\pi x}{l}$$

$$\text{where, } a_0 = \frac{2}{l} \int_0^l f(x) dx$$

$$a_n = \frac{2}{l} \int_0^l f(x) \cos \frac{n\pi x}{l} dx$$

(ii) Half-Range sine series in $[0, l]$:-

$$f(x) = \sum_{n=1}^{\infty} b_n \sin \frac{n\pi x}{l}$$

$$\text{where, } b_n = \frac{2}{l} \int_0^l f(x) \sin \frac{n\pi x}{l} dx$$

Questions: →

1. The coeff. of $\sin x$ in the fourier series expansion of $f(x) = x^2$, $x \in (-\pi, \pi)$.

(a) $\sum \frac{(-1)^n}{n^2}$ (b) $\sum \frac{1}{n^2}$ (c) $\frac{\pi^2}{6}$ (d) 0

Solⁿ: → Even funⁿ hence coeff. of $\sin x = 0$.

2. If $f(x) = \begin{cases} 0 & ; -2 \leq x < 0 \\ 1 & ; 0 < x \leq 2 \end{cases}$

then the term independent of x in the fourier series of $f(x)$ is —

(a) 0 (b) 1 (c) $\sqrt{2}$ (d) 2

Solⁿ: → Here, $(-2, 2) \Rightarrow l = 2$

$$a_0 = \frac{1}{l} \int_{-l}^{l} f(x) dx = \frac{1}{2} \int_{-2}^{2} 1 dx = 1$$

$$\therefore \text{Independent term} = \frac{a_0}{2} = \frac{1}{2}$$

3. The funⁿ $f(x) = \begin{cases} -x+1 & ; -\pi \leq x \leq 0 \\ x+1 & ; 0 \leq x \leq \pi \end{cases}$

then $f(x)$ has following terms in its expansion

(a) cosine (b) sine (c) both (d) cannot be determined

Solⁿ: → $f(-x) = \begin{cases} x+1 & ; -\pi \leq -x \leq 0 \\ -x+1 & ; 0 \leq -x \leq \pi \end{cases}$

$$= \begin{cases} x+1 & ; \pi \geq x \geq 0 \\ -x+1 & ; 0 \geq x \geq -\pi \end{cases}$$

$$\therefore f(-x) = -f(x)$$

⇒ Even funⁿ.

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4. If $f(x) = \begin{cases} 0 & -2 < x < 0 \\ 1 & 0 < x < 2 \end{cases}$

then the coeff. of $\cos \frac{n\pi x}{2}$ is _____.

- (a) 0 (b) $\frac{1}{n}$ (c) $\frac{1}{n^2}$ (d) $-\frac{1}{n}$

Solⁿ: $\Rightarrow (-2, 2) \Rightarrow l=2$

$$a_n = \frac{1}{l} \int_{-l}^l f(x) \cos \frac{n\pi x}{l} dx$$

$$= \frac{1}{2} \int_0^2 \cos \frac{n\pi x}{2} dx$$

$$= \frac{1}{2} \left[\frac{\sin \frac{n\pi x}{2}}{\frac{n\pi}{2}} \right]_0^2$$

$$= \frac{1}{2} \times \frac{2}{n\pi} [0 - 0] = 0$$

5. If $f(x) = x^2$ in $[-\pi, \pi]$ has its fourier expansion as $f(x) = \frac{\pi^2}{3} +$

$$4 \left[\frac{\cos x}{1^2} - \frac{\cos 2x}{2^2} + \frac{\cos 3x}{3^2} - \dots \right] \text{ then the value of}$$

$$\frac{1}{1^2} + \frac{1}{2^2} + \frac{1}{3^2} + \dots \text{ is } \dots$$

- (a) $\frac{\pi^2}{6}$ (b) $\frac{\pi^2}{12}$ (c) π^2 (d) None

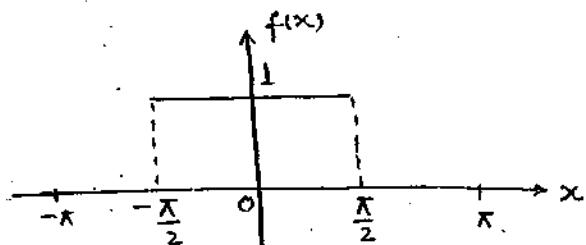
Solⁿ: At $x = \pi$, we have

$$\frac{\pi^2}{3} = 4 \left[\frac{1}{1^2} - \frac{1}{2^2} + \frac{1}{3^2} - \dots \right] = \frac{1}{2} \left[\lim_{x \rightarrow \pi^+} f(x) + \lim_{x \rightarrow \pi^-} f(x) \right]$$

$$= \frac{1}{2} [\pi^2 + \pi^2] = \pi^2$$

$$\Rightarrow \frac{1}{1^2} + \frac{1}{2^2} + \frac{1}{3^2} + \dots = \frac{1}{4} \left[\pi^2 - \frac{\pi^2}{3} \right] = \frac{\pi^2}{6}$$

6. A fun with period 2π is shown below



then fourier series is _____.

$$(a) f(x) = \sum_{n=1}^{\infty} \frac{2}{n\pi} \sin \frac{n\pi}{2} \cos nx$$

$$(b) f(x) = \frac{1}{2} + \sum_{n=1}^{\infty} \frac{2}{n\pi} \sin \frac{n\pi}{2} \sin nx$$

$$\checkmark (c) f(x) = \frac{1}{2} + \sum_{n=1}^{\infty} \frac{2}{n\pi} \sin \frac{n\pi}{2} \cos nx$$

$$(d) f(x) = \sum_{n=1}^{\infty} \frac{2}{n\pi} \sin \frac{n\pi}{2} \sin nx$$

Soln: →

$$f(x) = \begin{cases} 0 &; -\pi < x < -\frac{\pi}{2} \\ 1 &; -\frac{\pi}{2} < x < \frac{\pi}{2} \\ 0 &; \frac{\pi}{2} < x < \pi \end{cases}$$

$f(-x) = f(x) \Rightarrow$ Even fun \Rightarrow cosine series

$$a_0 = \frac{2}{\pi} \int_0^{\pi} f(x) dx = \frac{2}{\pi} \int_0^{\pi/2} 1 dx = 1$$

$$\therefore \frac{a_0}{2} = 1$$

7. In $[0, \pi]$ the constant term in the cosine series of $f(x) = x^2 + 2x$ is

- (a) $\pi(\frac{\pi}{3} - 1)$ (b) $\pi(\frac{2\pi}{3} + 1)$ (c) $\pi(\frac{\pi}{2} + 1)$ (d) None

Soln: → $a_0 = \frac{2}{\pi} \int_0^{\pi} f(x) dx = \frac{2}{\pi} \int_0^{\pi} [x^2 + 2x] dx = \frac{2}{\pi} \left[\frac{x^3}{3} + x^2 \right]$

$$= \frac{2\pi^2}{3} + \pi^2$$

$$= \pi \left(\frac{2\pi^2}{3} + 1 \right)$$

$$\therefore \frac{a_0}{2} = \frac{1}{\pi} \left(\frac{\pi^3}{3} + \pi^2 \right) = \pi \left(\frac{\pi}{3} + 1 \right).$$

8. If $f(x) = x$ is expressed on a half range cosine series in $[0, 2]$
then the coeff. of $\cos \pi x$ is ____.

(18)

- (a) $\frac{4}{\pi^2}$ (b) $\frac{2}{\pi^2}$ (c) 0 (d) None.

9. In the interval $[0, \pi]$ if a const. c is expressed as a half range sine series then coeff. of $\sin 5x$ is ____.

- (a) $\frac{2c}{5\pi}$ (b) 0 (c) $\frac{4c}{5\pi}$ (d) $\frac{c}{5\pi}$

Soln: $\rightarrow f(x) = \sum_{n=1}^{\infty} b_n \sin nx, \quad f(x) = c$

$$b_n = \frac{2}{\pi} \int_0^{\pi} f(x) \cdot \sin nx dx$$

$$= \frac{2}{\pi} \int_0^{\pi} c \cdot \sin 5x dx$$

$$= \frac{2c}{\pi} \left[-\frac{\cos 5x}{5} \right]_0^{\pi}$$

$$= \frac{4c}{5\pi}$$

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Differential Equations

* Differential Equations *

$$\text{eqn} - 2x + y = 2$$

$$\text{diff. eqn} - \frac{dy}{dx} + x + 2 = 0$$

$$\Rightarrow x=1 \quad \text{and} \quad y=1 \quad \text{so} \Rightarrow y=f(x)$$

differential eqn

ordinary diff. eqn

single variable

$$\frac{d^2y}{dx^2} + \left(\frac{dy}{dx}\right)^3 + 3y = 0$$

$$\frac{\partial^2 u}{\partial x^2} + \left(\frac{\partial^2 u}{\partial y^2}\right)^3 = 0$$

more than one var

order = highest derivative

order = 2

degree = highest power of highest degree

degree = 3

derivative should be free from radicals

order = 2; degree = 1 if fractions.

order - The highest derivative involved in diff. eqn.

$$\text{Radical} = \left(\frac{dy}{dx}\right)^{1/2, 1/3, 1/4}$$

fraction - derivative should not be in denominator

$$① \left(\frac{d^2y}{dx^2}\right)^2 = \left(x + \frac{dy}{dx}\right)^{9/2}$$

$$② \frac{dy}{dx} = x + e^t$$

$$\left(\frac{d^2y}{dx^2}\right)^4 = \left(x + \frac{dy}{dx}\right)^3$$

$$\left(\frac{dy}{dx}\right)^2 = x \frac{dt}{dx} + e^t$$

$$\therefore O = 2 \quad D = 4$$

$$O = 1, D = 2$$

* Differential Equations *

$$\text{Eqn} = \dots$$

$$\text{diff. eqn} \quad \frac{dy}{dx} + x + 2 = 0$$

$$\text{Soln} \rightarrow x + C \quad \text{so} \rightarrow y = f(x)$$

Differential eqn

Ordinary diff. eqn

Partial diff. eqn

single variable

$$\frac{d^2y}{dx^2} + \left(\frac{dy}{dx}\right)^3 + 3y = 0$$

more than one var

$$\frac{\partial^2 u}{\partial x^2} + \left(\frac{\partial^2 u}{\partial y^2}\right)^3 = 0$$

order = highest derivative

order = 2

degree = highest power of highest degree derivative should free from radical

order = 2 ; degree = 1 + fractions.

order - The highest derivative involved in diff. eqn.

Radical = $\left(\frac{dy}{dx}\right)^{\frac{1}{2}, \frac{1}{3}, \frac{1}{4}, \dots}$

fraction - derivative should not in denominator

$$D \left(\frac{d^2y}{dx^2}\right)^2 = \left(x + \frac{dy}{dx}\right)^{3/2}$$

$$① \quad \frac{dy}{dx} = x + e^t \quad \frac{dy}{dt}$$

$$\left(\frac{d^2y}{dx^2}\right)^4 = \left(x + \frac{dy}{dx}\right)^3$$

$$\left(\frac{d^2y}{dx^2}\right)^2 = x \frac{dy}{dx} + e^t$$

$$\therefore O = 2 \quad D = 4$$

$$O = 1, D = 2$$



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$$2 \left(\frac{d^3y}{dx^3} \right)^2 + \left(\frac{d^2y}{dx^2} \right)^3 + 3y = 0 \quad (4) \quad dy = (t + \sin t) dt$$

$$O=3, D=2$$

$$\frac{dy}{dt} = t + \sin t$$

$$2 \left(\frac{\partial^2 u}{\partial x^2} \right)^3 = c^2 \left(\frac{\partial^3 y}{\partial x^3} \right)^2 \quad O=1, D=1$$

$$O=3, D=2$$

Formation of differential eqns -

$$F(x, y, a, b) = 0 \quad (1)$$

Diff. (1) w.r.t. x

$$F_x(x, y, \frac{dy}{dx}, a, b) = 0 \quad (2)$$

Diff. (2) w.r.t. x

$$F_2(x, y, \frac{dy}{dx}, \frac{d^2y}{dx^2}, a, b) = 0 \quad (3)$$

Eliminate

a, b \Rightarrow

$$\phi(x, y, \frac{dy}{dx}, \frac{d^2y}{dx^2}) = 0$$

Note:

The no. of arbitrary constants eliminated should be equal to the order of resulting ordinary diff. eqns.

① The diff eqn of family of curves passing through origin is

$$\text{Ans} \quad \text{dy/dx} = \text{arbitrary}$$

$$\text{Q. } x \frac{dy}{dx} + y = 0$$

for sym

$$\frac{dy}{dx} = \frac{-y}{x}$$

$$y = \frac{dy}{dx} x$$

$$dy/x = dy/y$$

$$\int y dy = \int x dx$$

② Find the diff eqn of family of circles centred at (h, k) of radius a where h, k are arbitrary constants.

$$(x-h)^2 + (y-k)^2 = a^2 \quad (1)$$

diff w.r.t. x

$$2(x-h) + 2(y-k)y' = 0$$

diff w.r.t. y

$$2(x-h) + 2(y-k) + 2(y-k)y'' = 0$$

y''

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$$x - h = \frac{(1+y'^2)}{y''} \cdot y' \quad \textcircled{4}$$

Put $\textcircled{4}$ in $\textcircled{1}$

$$\frac{(1+y'^2)^2}{y''^2} y'^2 + \frac{(1+y'^2)^2}{y''^2} = a^2$$

$$(1+y'^2)^2 (y''^2 + 1) = a^2 y''^2$$

$$(1+y'^2)^3 = a^2 y''^2$$

$$\textcircled{3} \quad y = c(x-c)^2 \quad \textcircled{1}$$

Diff. w.r.t. x

$$y' = 2c(x-c) \quad \textcircled{2}$$

$$\frac{\textcircled{1}}{\textcircled{2}} \Rightarrow \frac{y}{y'} = \frac{c(x-c)}{2c(x-c)} = \frac{x-c}{2} \therefore x-c = \frac{2y}{y'}$$

$$c = x - \frac{2y}{y'} = \frac{xy' - 2y}{y'}$$

$$y = \frac{xy' - 2y}{y'} (x - \frac{xy' - 2y}{y'})^2 = \left(\frac{xy' - 2y}{y'}\right) \frac{y''^2}{y'^2}$$

$$y''' = (xy' - 2y)y''$$

Note:- If the given eqn is of the form $y = C_1 e^{at} + C_2 e^{bt} + C_3 e^{ct}$

Then D.E. is

$$(D-a)(D-b)(D-c)y = 0$$

$$D = \frac{d}{dx}, \quad D^2 = \frac{d^2}{dx^2}$$

e.g.

$$\textcircled{1} \quad y = C_1 e^{at} + C_2 e^{bt} + C_3 e^{ct}$$

$$(D+1)(D-3)(D-2)y = 0$$

$$(D^2 - 2D - 3)(D - 2)y = 0$$

$$(D^3 - 4D^2 + D + 6)y = 0$$

$$\frac{d^3y}{dx^3} - 4 \frac{d^2y}{dx^2} + \frac{dy}{dx} + 6y = 0$$

$$\textcircled{2} \quad i = C_1 e^{at} + C_2 e^{bt}$$

$$(D-2)(D+4)i = 0$$

$$(D^2 + 2D + 8)i = 0$$

$$\textcircled{3} \quad \frac{d^2i}{dt^2} + 2 \frac{di}{dt} - 8i = 0$$

S

Note:-

If the given eqn is of the form

$y = Af(x) + Bg(x)$ Then the D.E. is obtained by simplifying the following determinant

$$\begin{vmatrix} y & f(x) & g(x) \\ y' & f' & g' \\ y'' & f'' & g'' \end{vmatrix} = 0$$

e.g. ① $y = Ae^{2x} + Bx$

$$\begin{vmatrix} y & e^{2x} & x \\ y' & 2e^{2x} & 1 \\ y'' & 4e^{2x} & 0 \end{vmatrix} = 0 \quad \therefore y(-4e^{2x}) - e^{2x}(-y'') + x(2y'e^{2x}) - 4y''e^{2x} = 0$$

$$\therefore y''(1-2x) + 4xy' - 4y = 0$$

② $y = e^x (A \cos x + B \sin x) \quad -①$

$$y' = e^x (A \cos x + B \sin x) + e^x (-A \sin x + B \cos x) \quad -②$$

$$y' = y + e^x (-A \sin x + B \cos x)$$

$$y'' = y' + e^x (-A \sin x + B \cos x) + e^x (-A \cos x - B \sin x)$$

$$y'' = y' + (y' - y) - y$$

$$\therefore y'' - 2y' + 2y = 0$$

$$\frac{d^2y}{dt^2} = g$$

$$y(0) = c_1$$

$$\frac{dy}{dt} + gt = c_1 \quad \left\{ \begin{array}{l} \frac{dy}{dt} = \frac{c_1 - gt}{t} \\ y = \int \frac{c_1 - gt}{t} dt = c_2 - \frac{g}{2} t^2 + c_1 \end{array} \right.$$

$$y = \frac{1}{2}gt^2 + c_1 t + c_2 \quad (t=0, y=0 \Rightarrow c_2=0)$$

General sol
g: no of arbitrary
const

$$y = \frac{1}{2}gt^2 + c_1 t + c_2$$

$$\frac{d^2y}{dt^2} = g$$

$$(a) y = \frac{1}{2}gt^2 + c_1 e^t + c_2$$

$$(b) y = \frac{1}{2}gt^2 + gt^3 + c_2$$

$$(c) y = \frac{1}{2}gt^2 + ct + c$$

(d) None

First order first degree diff. eqns

Notation -

$$\frac{dy}{dx} = F(x, y)$$

$$M dx + N dy = 0$$

$$M(x, y) + N(y, x)$$

① Variable separable method

$$\frac{dy}{dx} = F(x, y)$$

$$f(x)dx = g(y)dy$$

$$\int f(x)dx = \int g(y)dy + C$$

$$\textcircled{1} \quad \log \left(\frac{dy}{dx} \right) = 2x - y$$

$$\textcircled{3} \quad \frac{dx}{dy} = e^{2y} + e^y \cdot y$$

→

$$\log dy - \log dx = 2x - y$$

$$\frac{dx}{dy} = e^{-x} (e^{-2y} + e^{-y})$$

$$\frac{dy}{dx} = e^{2x-y} = e^{2x} \cdot e^{-y}$$

$$\int \frac{dx}{e^x} \int (e^{-2y} + e^{-y}) dy$$

$$\int e^y dy = \int e^{2x} dx$$

$$-e^{-x} = \frac{e^{-2y}}{-2} + \frac{y^2}{2} + C$$

$$\boxed{e^y = \frac{e^{2x}}{2} + C}$$

$$\textcircled{4} \quad \frac{dy}{dx} = 1 + y^2$$

\textcircled{2}

$$\frac{dy}{dx} = \frac{y^2}{1-xy}$$

$$\int \frac{dy}{1+y^2} = \int dx$$

$$(1-xy) dy = y^2 dx$$

$$\tan^{-1} y = x + C$$

$$dy = y^2 dx + xy dy$$

$$\boxed{y = \tan(x+C)}$$

$$= y (\underbrace{y dx + x dy}_{d(xy)})$$

$$\textcircled{3} \quad \frac{dy}{dx} = -\frac{x}{y} \quad \text{at } x=1, y=\sqrt{3}$$

$$dy = y d(xy)$$

$$\int y dy = \int -x dx$$

$$\int \frac{dy}{y} = \int d(xy)$$

$$y^2 = -x^2 + 2C$$

$$3 = -1 = 2C$$

$$\boxed{\log y = 2x + C}$$

$$2C = 4$$

$$\boxed{C = 2}$$

$$\boxed{x^2 + y^2 = 4}$$

③ Find the curve passing through the point (0, 1) and satisfying $\sin\left(\frac{dy}{dx}\right) = b$

$$\sin\left(\frac{dy}{dx}\right) = b$$

$$\frac{dy}{dx} = \sin^b b$$

$$\int dy = \int \sin^b b dx$$

$$y = x \sin^b b + c$$

$$c=1$$

$$y = x \sin^b b + 1$$

$$\textcircled{a} \frac{dy}{dx} = e^{bx} \quad (\text{with } y(0)=1)$$

then find 'y' when $x=1$

$$\int e^y dy = \int e^x dx$$

$$-e^y = e^x + c$$

$$-e^{-1} = e^1 + c$$

$$\frac{-1}{e} - e = c$$

$$\textcircled{b} \frac{dx}{dt} + 3x = 0$$

$$\textcircled{a} x = 3e^{3t}$$

$$\textcircled{c} x = 2e^{-2t}$$

$$\textcircled{b} x = 3t^3$$

$$\checkmark \textcircled{d} x = 3e^{-3t}$$

$$\therefore c = \frac{-1 - e^2}{e}$$

$$\frac{dx}{dt} = -3x$$

$$-e^y = e^x - e^{-1}$$

$$\frac{dx}{dt} = -3dt$$

$$x = -1$$

$$\log x = -3t + \log c$$

$$-e^t = e^t - e^{-1}$$

$$x = e^{-3t}$$

$$e^{-4} = e$$

$$\boxed{x = 3e^{-3t}}$$

$$\begin{aligned} & -4 = 1 \\ & (e^{-3}) \end{aligned}$$

$$\textcircled{9} \quad \frac{dy}{dx} = 3x^2 - 2x \quad \text{at } x=1, y=1$$

$$\textcircled{10} \quad \frac{dy}{dx} = y^2 \sin x \quad \text{with } y(0)=1$$

then find $y(3) = ?$

$$\rightarrow \int dy = \int (3x^2 - 2x) dx$$

$$y = x^3 - x^2 + C$$

$$\boxed{C=1}$$

$$y = x^3 - x^2 - 1$$

$$y(3) = 27 - 9 + 1$$

$$\boxed{y(3) = 19}$$

$$\textcircled{a} \quad y \sin x = 1 \quad \textcircled{b} \quad y \cos x = 1$$

$$\textcircled{c} \quad y = \sin x$$

$$\textcircled{d} \quad x = \sin y$$

\textcircled{11} If the equation contains the terms like $\cos(xy)$, $\sin(xy)$, $(ax+by+c)^2$, etc. can be reduced to variable separable form with a substitution $xy=v$, $x+y=r$, $ax+by+c=v$ resp.

$$\textcircled{1} \quad \frac{dy}{dx} = (4x+y+1)^2 \quad \therefore \frac{dv}{dx} - 4 = v^2$$

$$4x+y+1 = v$$

$$4 + \frac{dy}{dx} = \frac{dv}{dx}$$

$$\frac{dy}{dx} = \frac{dv}{dx} - 4$$

$$\frac{dv}{(4+v^2)} = \int dx$$

$$= \frac{4x+y+1}{2}$$

$$\frac{1}{2} \tan^{-1} \frac{v}{2} = x + C$$

$$\tan^{-1} \frac{v}{2} = 2x + C \quad \therefore \tan(\frac{v}{2}) = \tan(2x+C)$$

Homogeneous diff method -

$$\frac{dy}{dx} = F(x, y)$$

Homogeneous of degree n

num. degree = den. degree

$$F(kx, ky) = k^n F(x, y)$$

$\frac{dy}{dx} = F(x, y)$ is said to be homogeneous diff eqn if $F(x, y)$ should be a homogeneous function of degree zero.

Note - Eqn $Mdx + Ndy = 0$ is said to be homogeneous diff eqn if all the terms of M & N should be of same degree.

$$x^2 + y^2 \Rightarrow (kx)^2 + (ky)^2 \therefore \text{degree} = 2.$$

Substitution $y = vx$ or $x = vy$ reduces homogeneous eqn to variable separation form.

$$\frac{dy}{dx} = \frac{x^2y - y^3}{ay^2} = \frac{x^2(y/a - y^2/a)}{ay^2}$$

Every homogeneous fn of degree zero can be written as fn of y/x or x/y & substitution reduces it to variable separation form.

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$$x \frac{dy}{dx} = y \log y - \log x + 1$$

$$\frac{dy}{dx} = \frac{y}{x} [\log(y) + 1]$$

$$y = vx$$

$$\frac{dy}{dx} = v + x \frac{dv}{dx}$$

$$v + x \frac{dv}{dx} = v [\log v + 1]$$

$$x \frac{dv}{dx} = v \log v$$

$$\therefore v = e^{cx}$$

$$\int \frac{1}{v \log v} dv = \int \frac{dx}{x}$$

$$\therefore \frac{y}{x} = e^{cx}$$

$$\log v = t$$

$$\therefore y = xe^{cx}$$

$$\frac{1}{t} dt = \frac{dx}{x}$$

$$\int \frac{1}{t} dt = \int \frac{dx}{x}$$

$$\log t = \log x + \log c$$

$$t = cx$$

$$\log t = \log cx$$

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Non-homogeneous diff. eqn method -

$$\frac{dy}{dx} = \frac{a_1x + b_1y + g}{a_2x + b_2y + g}$$

case I :-

$$\left[\frac{a_1}{a_2} = \frac{b_1}{b_2} \right]$$

There exists a subst. which reduces given eqn to variable separable form.

case II :-

$$\left[\frac{a_1}{a_2} \neq \frac{b_1}{b_2} \right]$$

$$x = X + h, \quad y = Y + K$$

$$dx = dX, \quad dy = dY$$

$$\frac{dy}{dx} = \frac{a_1(X+h) + b_1(Y+K) + g}{a_2(X+h) + b_2(Y+K) + g}$$

$$= \frac{a_1X + b_1Y + (a_1h + b_1K + g)}{a_2X + b_2Y + (a_2h + b_2K + g)}$$

choose h, K so that

$$a_1h + b_1K + g = 0$$

$$a_2h + b_2K + g = 0$$

$$\frac{dy}{dx} = \frac{a_1X + b_1Y}{a_2X + b_2Y} \quad \text{then } Y = vX$$

$$⑤ (2x+2y-1)dx = (x+y+1)dy$$

$$\frac{dy}{dx} = \frac{2x+2y-1}{x+y+1} \quad \left(\frac{a_1 - b_1}{a_2 - b_2} \right)$$
$$= \frac{2(x+y-1)}{(x+y)+1}$$

$$x+y = v$$

$$1 + \frac{dy}{dx} = \frac{dv}{dx}$$

$$\frac{dy}{dx} = \frac{dv}{dx} - 1$$

$$\frac{dv}{dx} - 1 = \frac{2v-1}{v+1}$$

$$\frac{dv}{dx} = \frac{2v-1+v+1}{v+1} = \frac{3v}{v+1}$$

$$\int \frac{(v+1)}{v} dv = \int 3dx$$

$$v + \log v = 3x + C$$

$$x+y + \log(x+y) = 3x + C$$

$$y - 2x + \log(x+y) = C$$

③ Which of following subst. reduces diff. eqn
 $\frac{dy}{dx} = \frac{y+x-2}{y-x-4}$ to homogeneous form



$$x = X + h, \quad y = Y + k$$

$$k + h - 2 = 0$$

$$k - h - 4 = 0$$

$$2k - 6 = 0$$

$$\underline{k=3}, \underline{h=-1}$$

$$\boxed{x = X - 1}, \boxed{y = Y + 3}$$

$$\frac{dy}{dx} = \frac{y+x}{y-x} \quad \text{Homo. form}$$

③ a) $x = X + h, \quad y = Y + k$ reduces $\frac{dy}{dx} = \frac{y+x-2}{y-x-4}$
 to homo. form then find h, k .

$$\text{Ans. } h = -1, \quad k = 3$$

b) $\frac{d^2y}{dx^2} + (h+3)\frac{dy}{dx} + (k-4)y = 0$

Exact differential eqn

$$Mdx + Ndy = 0$$

A differential eqn $Mdx + Ndy = 0$ is said to be exact if it is the total differential of some function.

$$d[f(x,y)] = Mdx + Ndy$$

$$\text{e.g. } y^2 dx + 2xy dy = 0$$

$$d[y^2] = y^2 dx + 2xy dy$$

The D-E $Mdx + Ndy = 0$ is exact $\Leftrightarrow \frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$

$$Mdx + Ndy = 0$$

$$\begin{cases} \text{exact} \\ \text{i.e. } \left(\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x} \right) \end{cases}$$

$\int Mdx + \int \text{[terms of } N \text{ without } dx]$

Integrate w.r.t. x

at constant

$$\text{D.P. } p dx = \int M dx + \text{constant}$$

$$\frac{\partial M}{\partial y}$$

$$\frac{\partial N}{\partial x}$$

$P dx - (1 + \sin^2 y + \cos^2 x) dy = 0$ is exact then find P .

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

$$\therefore \frac{\partial N}{\partial x} = \sin 2x$$

$$\therefore \frac{\partial P}{\partial y} = \sin 2x$$

$$\therefore \boxed{P = 4 \sin 2x} \quad \checkmark$$

$$P = 4 \sin 2x + C \cos x \quad \text{(ans)}$$

③ $(3a^2x^2 + by \cos x) dx + (2 \sin x - 4xy^3) dy = 0$ is exact then

a) Exactness depends on both a and b

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

b) Exactness depends only on a

c) Exactness depends only on b

d) Exactness not depends on both a & b .

$$④ (ax+bx+g)dx + (bx+by+f)dy = 0 \rightarrow \text{non homogeneous}$$

$$\frac{\partial M}{\partial y} = b, \quad \frac{\partial N}{\partial x} = b$$

$$\int (ax+bx+g)dx + \int (bx+by+f)dy = c$$

$$\frac{dx^2}{2} + bxydy + \frac{by^2}{2} + f dx + g dy = 0$$

$$⑤ [y(1+\frac{1}{x}) + \cos y]dx + [x+\log x - x\sin y]dy = 0$$

$$\frac{\partial M}{\partial y} = -\sin y + \left(1 + \frac{1}{x}\right), \quad \frac{\partial N}{\partial x} = 1 + \frac{1}{x} - \sin y$$

$$\int \left(y + \frac{1}{x} + \cos y\right)dx + \int 0 dx = c$$

$$\therefore yx + y\log x + x\cos y = c$$

$$⑥ ydx - xdy = 0 \quad \textcircled{1}$$

$$\frac{\partial M}{\partial y} = 1, \quad \frac{\partial N}{\partial x} = -1$$

multiply ① with $\frac{1}{yx}$

$$\frac{y}{y^2} dx - \frac{x}{y^2} dy = 0$$

$$\frac{1}{y} dx - \frac{x}{y^2} dy = 0$$

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$$\frac{\partial M}{\partial y} = -\frac{1}{y^2}, \quad \frac{\partial N}{\partial x} = -\frac{1}{y^2}$$

Integrating factor -

A non exact eqn is converted to the exact by multiplying it with a function $f(x,y)$. Then $f(x,y)$ is called integrating factor.

$$ydx - xdy = 0$$

I.F.

$$\frac{1}{y^2}, \frac{1}{x^2}, \frac{1}{xy}, \frac{1}{x^2+y^2}$$

A constant multiple of an integrating factor is also an integrating factor.

$$Mdx + Ndy = 0$$

Non exact eqn (i.e. $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$)

ii) All terms of M and N should be of same degree.

$$IF = \frac{1}{Mx+Ny}$$

$(Mx+Ny \neq 0)$

ii) The eqn is of the form

$$y f(x,y)dx + x g(x,y)dy = 0$$

$$IF = \frac{1}{Mx-Ny}$$

$(Mx-Ny \neq 0)$

$$\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x}$$

\neq

$$\int [f(x)dx]$$

$$\frac{\partial M}{\partial x} - \frac{\partial N}{\partial y}$$

\neq

(Factor)

IF = e^x

i) Inspection method

Note:

A non-exact homogeneous differential eqn individually is converted to exact by multiplying with C/M+N

q. Find integrated factor of

$$(4x^2 + y^2)dx + (xy^2 + 2y^3 - 4x)dy = 0$$

$$\frac{\partial M}{\partial y} = 4y^3 + 2, \quad \frac{\partial N}{\partial x} = 4x - 4$$

$$\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y}$$

$$4x - 4 - 4y^3 - 2$$

$$(-3y^3 - 2)$$

$$-3(y^3 + 2) = -3y^3 - 6$$

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$f(x)$

$\int f(x)dx$

$\frac{1}{x}$

x

$\frac{2}{x}$

x^2

$\frac{3}{x}$

x^3

$-\frac{1}{x}$

$x^{-1} = 1/x$

$-\frac{2}{x}$

$x^{-2} = 1/x^2$

$$\textcircled{1} \quad y(1-xy)dx - x(1+xy)dy = 0 \quad \textcircled{1}$$

$$Mx - Ny = xy - x^2y^2 + 2xy + x^2y^2 = 2xy$$

$$IF = \frac{1}{2xy} \quad \text{or} \quad IF = \frac{1}{xy}$$

Multiply $\textcircled{1}$ with $\frac{1}{xy}$

$$\frac{y(1-xy)}{xy} dx - \frac{x(1+xy)}{xy} dy = 0$$

$$\int \left(\frac{1}{x} - y\right) dx - \int \frac{1}{y} dy = c$$

$$\log x - xy - \log y = c$$

$$\boxed{\log x/y - xy = c}$$

$$I.F = e^{\int M(x,y)dx} = e^{\int (x^2+y^2)dx} = e^{x^3/3+y^2x}$$

$$\frac{\partial M}{\partial y}$$

$$\frac{\partial N}{\partial x} = 2x$$

$$\frac{\partial M}{\partial x} = \frac{\partial N}{\partial y}$$

$$x^2+y^2$$

$$x^2+y^2$$

$$I.F = y^2$$

$$x^2y dx + (x^3+y^3)dy = 0$$

$$\rightarrow Mx+Ny = x^3y - (x^3+y^3)y = -y^4$$

$$I.F = \frac{1}{y^4}$$

$$\frac{x^2y}{-y^4} dx + \frac{x^3+y^3}{y^4} dy = 0$$

$$-\int \frac{x^2y}{y^3} dx + \int \frac{1}{y^4} dy = 0$$

$$-\frac{x^3}{y^2} + \frac{1}{3y^3} = C$$

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$$* \quad ydx - xdy + (1+x)dx + x^2 \cos y dy = 0$$

Multiply with $\frac{1}{x^2}$

$$\frac{ydx - xdy}{x^2} + \frac{(1+x)dx}{x^2} + \frac{x^2 \cos y dy}{x^2} = 0$$

$$\int d\left[-\frac{1}{x}\right] + \int \left(\frac{1}{x^2} + \frac{1}{x}\right) dx + \int \cos y dy = 0$$

$$-\frac{1}{x} - \frac{1}{x} + \log x + \sin y = C$$

$$* \quad ydx - xdy + (y^2 + y)xdx + xy e^x dx = 0$$

Multiply with $\frac{1}{xy}$

$$\frac{ydx - xdy}{xy} + \frac{(y^2 + y)x dx}{xy} + \frac{xy e^x dx}{xy} = 0$$

$$\int d[\log(x/y)] + \int (y+1)dy + \int e^x dx = 0$$

$$\log(x/y) + \frac{y^2 + y}{2} + e^x = C$$

$$* \quad ydx + xdy + x e^x dx = 0$$

$$\int d(xy) + \int x e^x dx = 0$$

$$xy + x^2 e^x - C(x+1) = 0$$

$$y \frac{dy}{dx} + x^2 y^2 e^x = 0$$

Multiply with $\frac{1}{y^2}$,

$$\frac{y \frac{dy}{dx} + x^2 y^2 e^x}{y^2} = 0$$

$$\int d(\log(y)) + j x e^x dx = 0$$

$$\log(y) + x e^{x(2-1)} = C$$

* Linear differential eqns -

The differential eqn is said to be linear if it satisfies the following two conditions:

- i) The dependent variable and all its derivatives should be of 1st degree only i.e.

$$(y')^1, \left(\frac{dy}{dx}\right)^1, \left(\frac{d^2y}{dx^2}\right)^1$$

- ii) There is no product of the dependent variable and any of its higher derivative.

$$\frac{(y')^1}{(y')^1}, \frac{dy}{dx}, \frac{d^2y}{dx^2}$$

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$$* \frac{d^2y}{dx^2} + \frac{dy}{dx} + xy = x^3$$

\Rightarrow Linear

The eqn containing f^n of dependent variable is not linear in that variable.

e.g.

$$\frac{d^2y}{dx^2} + \frac{dy}{dx} + x e^y = x^3$$

\Rightarrow Non-linear

* Linear in y -

$$\boxed{\frac{dy}{dx} + py = q}$$

solⁿ \downarrow p and q are fⁿ of x or constant.

$$y \cdot e^{\int P dx} = \int Q e^{\int P dx} dx + C$$

$$IF = e^{\int P dx}$$

* Linear in x -

$$\boxed{\frac{dx}{dy} + px = q}$$

solⁿ, p and q are fⁿ of y or constant

$$\boxed{x = \left(C_1 e^{-\int P dy} \right) - \int Q e^{-\int P dy}}$$

$$y = x \frac{dy}{dx} + \frac{y}{x}$$

$$\frac{dy}{dx} + \frac{y}{x} = x^3$$

$$P = f(x) \quad Q = g(x)$$

$$\int \frac{1}{x} dx \\ e^{-\frac{1}{x}}$$

$$\therefore y \cdot x = \int x^3 \cdot x dx + C = \int x^4 dx + C$$

$$yx = \frac{x^5}{5} + C$$

$$\text{at } y(1) = 6/5$$

$$\frac{6}{5} = \frac{1}{5} + C$$

$$C = 1$$

$$y = \frac{x^4}{5} + \frac{1}{5}$$

$$* \frac{dy}{dx} + y(x\sin x + \cos x) = 1$$

$$\frac{dy}{dx} + \frac{(x\sin x + \cos x)y}{x\cos x} = 1$$

$$\frac{dy}{dx} + (\tan x + \frac{1}{x})y = \frac{1}{x\cos x}$$

$$e^{\int pdx} = e^{\int (\tan x + \frac{1}{x})dx} = e^{\log \sec x + \log x}$$

$$= e^{\log(\sec x \cdot x)}$$

$$\therefore e^{\int pdx} = x \sec x.$$

$$y \cdot x \sec x = \int \frac{1}{x\cos x} \cdot x \sec x dx + C$$

$$\therefore xy \sec x = \tan x + C$$

$$* x^2 \frac{dy}{dx} + 2xy = \frac{2 \log x}{x} \quad \text{with } y(1) = 0 \text{ then find } y \text{ when } x = e$$

→

$$\frac{dy}{dx} + \frac{2y}{x} = \frac{2 \log x}{x^3}$$

$$e^{\int pdx} = e^{\int \frac{2}{x} dx} = x^2$$

$$y \cdot x^2 = \int \frac{2 \log x}{x^3} \cdot x^2 dx + C$$

$$x = \log x = t \Rightarrow y dx = dt$$

$$x^2 y = \int 2t dt + c$$

$$x^2 y = t^2 + c$$

$$x^2 y = (\log x)^2 + c$$

$$\Rightarrow c = 0$$

$$x^2 y = (\log x)^2$$

when $x=e$ then

$$e^2 y = 1$$

$$\therefore \boxed{y = e^{-2}}$$

* $(x+2y^3) \frac{dy}{dx} = y$ with $y(1)=0$

$$\frac{x dy}{dx} + 2y^3 \frac{dy}{dx} = y \quad \frac{x+2y^3}{y} = \frac{dx}{dy}$$

$$\frac{dx}{dy} - \frac{x}{y} = 2y^2$$

$$e^{\int P dy} = e^{\int -\frac{1}{y} dy} = y$$

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$$x \cdot \frac{1}{y} = \int 2y^2 - \frac{1}{4} dy + c$$

$$\frac{x}{y} = y^2 + c$$

$$x(1) = 0$$



$$c = -1$$

$$\frac{x}{y} = y^2 - 1$$

$$x = y^3 - y$$

* $\frac{dy}{dx} + y = e^x$ with $y(0) = 1$ find $y(1) = ?$



$$e^x = \int 1 dx = e^x$$

$$y \cdot e^x = \int e^x \cdot e^x dx + c$$

$$y e^x = \frac{e^{2x}}{2} + c$$

$$y(0) = 1$$

$$\Rightarrow c = \frac{1}{2}$$

$$\therefore y e^x = \frac{e^{2x}}{2} + \frac{1}{2} \text{ AUS } y(0) = 1$$

$$\therefore y = e^x + \tilde{e}^x \quad \boxed{y = e^x + \tilde{e}^x}$$

* Bernoulli's differential eqn :-

$$\frac{dy}{dx} + P y = q \stackrel{y(0)}{\rightarrow} \text{Linear if } \underline{n=0}$$

p and q are fn of x (or) constants

$$y^{1-n} e^{\int (1-n) p dx} = \int (1-n) q e^{\int (1-n) p dx} dx + c$$

$$\text{Substitution}$$

The substitution $y^{F_n} = v$ reduces Bernoulli's eqn to linear eqn.

GATE

q
eqn

$y^{1/n} = v$ reduces the non-linear to which of the following near form.

dpt

dv

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1

卷之三

— 1 —

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$$\frac{1}{1-n} \frac{dv}{dx} + Pv = q$$

$$\boxed{\frac{dv}{dx} + (1-n)Pv = (1-n)q}$$

Q. Which of the following substitution reduces the non-linear eqn $x \frac{dx}{dy} + x^2y^2 = x^3y^3$ to linear form?

- (a) $y^1 = v$ (b) $y^{-2} = v$ (c) $x^1 = v$ (d) $x^{-2} = v$

$$\frac{dx}{dy} + xy^2 = x^2y^3$$

$$\therefore \underline{y^{-2}} = v$$

$$\therefore \underline{x^1} = v$$

Q. $\frac{dy}{dx} - y \tan x = -y^2 \sec x$ with $y(0) = 1$

$$e^{\int (1-2)(-\tan x) dx} = e^{\log \sec x} = \sec x$$

$$y^{-2} \sec x = \int (1-2)(-\sec x)(\sec x) dx + C$$

$$y^{-1} \sec x = \tan x + C$$

$$y(0) = 1 \Rightarrow C = 1$$

$$\boxed{y = \frac{\sec x}{1 + \tan x}}$$

* Equations of the form:

$$\boxed{f'(y) \frac{dy}{dx} + P f(y) = q} \rightarrow \text{Non-linear}$$

$$f(y) = v \implies f'(y) dy = \frac{dv}{dx}$$

$$\boxed{\frac{dv}{dx} + Pv = q} \rightarrow \text{Linear}$$

* What substitution reduces the non-linear eqns

$$\frac{dz}{dx} + \frac{z \log z}{x} = \frac{z (\log z)^2}{x^2} \quad \text{Also find I.F. of linear forms.}$$

$$\frac{1}{z (\log z)^2} \frac{dz}{dx} + \frac{1}{z} (\log z)^{-1} = \frac{1}{x^2}$$

$$(\log z)^{-1} = v$$

$$-\frac{1}{z} (\log z)^{-2} \frac{dz}{dx} = \frac{dv}{dx}$$

$$-\frac{dv}{dx} + \frac{1}{z} v = \frac{1}{x^2}$$

$$\frac{dv}{dx} - \frac{1}{z} v = -\frac{1}{x^2}$$

$$e^{\int \frac{1}{z} dx} = e^{\log z} = y$$

$$* \frac{dy}{dx} + y \log y = xy e^x$$

$$\rightarrow \frac{x}{y} \frac{dy}{dx} + \log y = xe^x$$

$$\log y = v$$

$$\frac{1}{y} \frac{dy}{dx} = \frac{dv}{dx}$$

$$x \frac{dv}{dx} + v = xe^x$$

$$\frac{dv}{dx} + \frac{1}{x} v = e^x$$

$$e^{\int \frac{1}{x} dx} = x$$

$$v \cdot x = \int e^x \cdot x dx + c$$

$$vx = e^x(x-1) + c$$

$$\log y = e^x(x-1) + c$$

* Clairaut's eqⁿ

$$y = x \frac{dy}{dx} + f\left(\frac{dy}{dx}\right)$$

$$y = px + f(p)$$

where $p = \frac{dy}{dx}$

\downarrow sp^n

Directly replace $\frac{dy}{dx}$ by 'c'

$$Y = cx + f(c)$$

$$*\left(y - x \frac{dy}{dx}\right)\left(\frac{dy}{dx} - 1\right) = \frac{dy}{dx}$$

\rightarrow

$$y - xy' = \frac{y'}{y'-1}$$

$$y = \frac{y'}{y'-1} + xy'$$

$$y = cx + \frac{c}{c-1}$$

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* $P = \sin(y - xp)$ where $P = \frac{dy}{dx}$

$$y - xp = \sin^{-1} P$$

$$y = xp + \sin^{-1} P$$

$$y = cx + \sin^{-1} c$$

* Higher order linear differential eqns with constant coefficients :-

$$\frac{d^n y}{dx^n} + k_1 \frac{d^{n-1} y}{dx^{n-1}} + \dots + k_{n-1} \frac{dy}{dx} + k_n y = x$$

k_1, k_2, \dots, k_n are constants

x - fn of x or constant.

$$D = \frac{d}{dx}, D^2 = \frac{d^2}{dx^2}, D^3 = \frac{d^3}{dx^3} \rightarrow \text{e.g. } D e^{2x} = 2 e^{2x}$$

$$\frac{1}{D} = \int, \frac{1}{D^2} = \iint \rightarrow \text{e.g. } \frac{1}{D} \cos 2x = \frac{\sin 2x}{2}$$

$$(D^n + k_1 D^{n-1} + \dots + k_{n-1} D + k_n) y = x$$

$$F(D) y = x$$

$$F(D) = D^n + k_1 D^{n-1} + \dots + k_{n-1} D + k_n$$

fn of differential operator

- ① The complete solⁿ of D.E. is
- ~~y~~ $y = \text{Complementary f}^n + \text{Particular integral}$
 $= C.F + P.I$
- ② If $x=0$ then $F(D)y=0$ is called homogeneous differential eqn.
- ③ If $x \neq 0$ then $F(D)y=x$ is called non-homogeneous linear differential eqn.
- ④ The solution of homogeneous linear differential eqn $F(D)y=0$ is called complementary fⁿ.
- The no. of arbitrary constants in the complementary fⁿ should be equal to the order of given differential eqn.
- ⑤ The particular integral of $F(D)y=x$ is
- $$P.I = \left[\frac{1}{F(D)} \right] x . \quad P.I \text{ will not contain any arbitrary constants.}$$
- ⑥ If $x=0$ then complete solⁿ of the given eqn is only complementary function.
- ⑦ By assuming 'D' as an algebraic quantity $F(D)=0$ becomes an algebraic eqn. And is called Auxiliary eqn.

x Procedure to find CF -

By solving an A.E. we get the roots based on nature of this roots we write the CF as follows:

| Nature of roots | CF |
|--|---|
| Real and distinct $\lambda = m_1, m_2, m_3$ | $CF = C_1 e^{m_1 x} + C_2 e^{m_2 x} + C_3 e^{m_3 x}$ |
| 2 Real & repeated $\lambda = m_1, m_1$ | $CF = (C_1 + C_2 x) e^{m_1 x}$ |
| 3 Complex & distinct $\lambda = a \pm ib$ | $CF = e^{ax} [C_1 \cos bx + C_2 \sin bx]$ |
| 4 Complex & repeated $\lambda = a \pm ib, a \pm ib$ | $CF = e^{ax} [(C_1 + C_2 x) \cos bx + (C_3 + C_4 x) \sin bx]$ |
| 5 Surds (Real no.) $\lambda = a \pm \sqrt{b}$ | $CF = C_1 e^{(a+\sqrt{b})x} + C_2 e^{(a-\sqrt{b})x}$ OR $CF = e^{ax} [C_1 \cosh \sqrt{b} x + C_2 \sinh \sqrt{b} x]$ |

Roots

$$\lambda = 1, -\frac{1}{2}, 2$$

$$CF = C_1 e^{\lambda x} + C_2 e^{-\frac{1}{2}x} + C_3 e^{2x}$$

$$\lambda = 2, -2, -2$$

$$CF = C_1 e^{2x} + (C_2 + C_3)x e^{-2x}$$

$$\lambda = 2 \pm 3i, \frac{1}{3}$$

$$CF = e^{\frac{1}{3}x} [C_1 \cos 3x + C_2 \sin 3x] + C_3 e^{2x}$$

$$\lambda = \pm 2i, \pm 4$$

$$CF = C_1 e^{4x} + C_2 e^{-4x} + [C_3 \cos 2x + C_4 \sin 2x]$$

$$* \frac{d^2y}{dx^2} - 5 \frac{dy}{dx} + 6y = 0$$

$$* \frac{d^4y}{dx^4} - 16y = 0$$

$$\rightarrow D^2 - 5D + 6 = 0$$

$$(D^4 - 16)Y = 0$$

$$\therefore D = +3, D = +2$$

$$D^4 - 16 = 0$$

$$CF = C_1 e^{+3x} + C_2 e^{+2x}$$

$$\textcircled{1} \textcircled{2} = 0$$

$$\textcircled{1} \textcircled{2} (D^2 - 4)(D^2 + 4) = 0$$

$$D = 2, -2, \pm 2i$$

$$CF = C_1 e^{2x} + C_2 e^{-2x} + [C_3 \cos 2x + C_4 \sin 2x]$$

$$\times \frac{d^2y}{dx^2} + 2P \frac{dy}{dx} + (P^2 + q^2)y = 0$$

→

$$D^2 + 2PD + (P^2 + q^2) = 0$$

$$D_1, D_2 = \frac{-2P \pm \sqrt{4P^2 - 4P^2 - 4q^2}}{2} = \frac{-2P \pm \sqrt{-4q^2}}{2}$$

$$= \frac{-2P \pm 2qi}{2}$$

$$D_1, D_2 = -P \pm qi$$

$$CF = e^{-Px} [C_1 \cos qx + C_2 \sin qx]$$

Note!

If $y = C_1 y_1 + C_2 y_2 + C_3 y_3 + \dots$ is the complete solution of homogeneous differential eqn $F(D)y = 0$
 then each one of y_1, y_2, y_3, \dots is linearly independent solution of the homogeneous of linear differential eqn $F(D)y = 0$

Ques: y_1, y_2 are linearly independent solns of the corresponding linear homogeneous eqn
 of $F(D)y = x$ then $y_1 - y_2$ is a soln of which of the following eqns

(a) $F(D)=0$ (b) $x=0$

(c) $F(D)y = x$ (d) $\underline{F(D)y = 0}$

$\{v_1, v_2, v_3\}$ is linearly independent

$$v_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

$$v_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

$$v_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$\{v_1, v_2, v_3\}$ is linearly independent

$\{v_1, v_2, v_3\}$ is linearly independent

Since v_1, v_2, v_3 are linearly independent.

CF is linearly independent

$$\lambda = \pm 3i$$

$$\lambda^2 = -9$$

$$(A^T A)^{-1} = 0$$

$$A^T A = 0$$

$A^T A = 0$ implies $A^T A^{-1} = 0$ and $A^{-1} = 0$

$$A^{-1} = 0$$

$$A^{-1} = 0$$

$A^{-1} = 0$ is a 3x3 matrix

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* e^{3x} , e^{-3x} are linearly independent soln of -

$$(a) \frac{d^2y}{dx^2} - 6\frac{dy}{dx} + 9y = 0 \quad (b) \frac{d^3y}{dx^3} + 2\frac{d^2y}{dx^2} + 3\frac{dy}{dx} + y = 0$$

(c) $\frac{d^4y}{dx^4} - 81y = 0$ (d) None

Order \geq No. of indep. solns

* $y''' - y' + y = 0$



$$D^3 + D^2 + D + 1 = 0$$

$$D^2(D+1) + (D+1) = 0 \quad \therefore (D^2+1)(D+1) = 0$$

$$D^2 = 0, \quad \therefore D^2 = -1, \quad D = -1$$

$$\therefore D = \pm i$$

$$y = C_1 e^{-x} + C_2 \cos x + C_3 \sin x$$

* $\frac{d^4y}{dx^4} + a^4y = 0$

$$D^4 + a^4 = 0$$

$$(D^2 + a^2)^2 - 2D^2 a^2 = 0$$

$$(D^2 + a^2)^2 - (\sqrt{2} Da)^2 = 0$$

$$(D^2 + a^2 + \sqrt{2}ad) (D^2 + a^2 - \sqrt{2}ad) = 0$$

$$D^2 + \sqrt{2}ad + a^2 = 0 \quad \text{and} \quad D^2 - \sqrt{2}ad + a^2 = 0$$

$$\frac{-\sqrt{2}a \pm \sqrt{4a^2 - 4a^2}}{2}$$

$$\frac{-\sqrt{2}a \pm \sqrt{-2a^2}}{2}$$

$$\frac{-\sqrt{2}a \pm i\sqrt{2}a}{2}$$

$$\frac{-a \pm ai}{\sqrt{2}} \quad \frac{a \pm ai}{\sqrt{2}}$$

$$y = e^{\frac{ax}{\sqrt{2}}} \left[C_1 \cos \frac{a}{\sqrt{2}}x + C_2 \sin \frac{a}{\sqrt{2}}x \right] + e^{\frac{a_1 x}{\sqrt{2}}} \left[C_3 \cos \frac{a_1}{\sqrt{2}}x + C_4 \sin \frac{a_1}{\sqrt{2}}x \right]$$

$$* \frac{d^2f}{dn^2} + 4 \frac{df}{dn} + 4f = 0$$

(a) $f_1 = e^{-2n}$, $f_2 = n e^{-2n}$ ✓ (c) $f_1 = n e^{-2n}$, $f_2 = e^{-2n}$

(b) $f_1 = e^{-2n}$, $f_2 = n e^{-2n}$ (d) $f_1 = n e^{-2n}$, $f_2 = e^{-2n}$

* The D.E. $\frac{d^2y}{dx^2} + 2 \cos adx - 3y = x^2$ is

(a) Homogeneous linear DE ✓ (b) Non-homogeneous linear DE
with constant coefficients

(c) Non Linear D.E. order 2 ✓ (d) Linear D.E.

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The solⁿ of

$$\frac{d^2i}{dt^2} + \frac{R}{L} \frac{di}{dt} + \frac{i}{LC} = 0 \text{ where } R^2C = 4L$$

(a) $e^{-\frac{Rt}{2L}}$ (b) $te^{-\frac{Rt}{2L}}$

(c) $e^{-\frac{Rt}{L}}$ \checkmark (d) $te^{-\frac{Rt}{2L}}$

$$D^2 + \frac{R}{L} D + \frac{1}{LC} = 0$$

$$D_1, D_2 = \frac{-\frac{R}{L} \pm \sqrt{\frac{R^2}{L^2} - \frac{4}{LC}}}{2}$$

$$= \frac{-\frac{R}{L} \pm \sqrt{\frac{R^2 C - 4L}{L^2 C}}}{2}$$

$$= \frac{-\frac{R}{L} \pm 0}{2}$$

$$D_1, D_2 = -\frac{R}{2L}, -\frac{R}{2L}$$

$$-\frac{R}{2L}$$

$$y = C_1 e^{(-\frac{R}{2L})t} + C_2 t e^{(-\frac{R}{2L})t}$$

$$\therefore y = C_1 e^{-\frac{Rt}{2L}} + C_2 t e^{-\frac{Rt}{2L}}$$

$$* \frac{d^2y}{dx^2} + 4\frac{dy}{dx} + 13y = 0$$

$$\text{with } y(0)=0 \quad \text{and} \quad y'(0)=1$$

$$D^2 + 4D + 13 = 0$$

$$D_1, D_2 = -\frac{4+6i}{2}$$

$$= -2 \pm 3i$$

$$y = e^{-2x} [c_1 \cos 3x + c_2 \sin 3x]$$

$$\text{at } x=0, y=0 \Rightarrow c_1=0$$

$$y = c_2 e^{-2x} \sin 3x$$

$$y' = c_2 [-2e^{-2x} \sin 3x + 3e^{-2x} \cos 3x]$$

$$y'(0) = 1$$

$$\therefore c_2 = \frac{1}{3}$$

| | |
|---------------------------------|---|
| $y = \frac{e^{-2x}}{3} \sin 3x$ | . |
|---------------------------------|---|

$$* \frac{9d^2y}{dx^2} - 6\frac{dy}{dx} + y = 0 \quad \text{with } y(0) = 3 \text{ & } y'(0) = 1$$

→

$$9D^2 - 6D + 1 = 0$$

$$\therefore D = \frac{1}{3}, \frac{1}{3}$$

$$y = (9 + c_2x) e^{\frac{x}{3}}$$

$$y(0) = 3 \Rightarrow 3 = 9$$

$$y = 3 + c_2x e^{\frac{x}{3}}$$

$$y' = 9 \left[\frac{2}{3}e^{\frac{x}{3}} + e^{\frac{x}{3}} \right]$$

$$y'(0) = 1$$

$$0 = c_2$$

$$y = (3 + 0x) e^{\frac{x}{3}}$$

$$y = 3 e^{\frac{x}{3}}$$

$$y = \frac{dy}{dx} + \frac{d^2y}{dx^2}$$

WIA

(A) $y = e^{rx}$

(B) $y = e^{-rx}$

(C) $y = e^{rx} \sin \theta$ (D) $y = e^{rx} \cos \theta$

* Direct put cond' in options i.e. Y(0)=0

* $\frac{dy}{dx} = n = 0$ where L is a constant of motion
 $\frac{d^2y}{dx^2} = 0$ $+ n(0) = 0$

(A) $n = kx$ (B) $n = k^2 e^{2x}$ Here check both cond'
 then c & d satisfies

(C) $n = k e^{-x/L}$ (D) $n = k e^{-x/L}$ so from parts of A-E
 (D) is ans.

$$\lambda = \pm \sqrt{k}$$

$$y = C_1 e^{\lambda x} + C_2 e^{-\lambda x}$$

* For which value of λ the DE $\frac{dy}{dx} = n$ with Y(0)=0

and $y(0) = 0$ will have non-trivial soln

$$(A) \lambda = -k$$

$$(B) \lambda = k$$

$\Rightarrow \text{Ans}$

$$(C) \lambda = 0$$

$$\sin \lambda n = 0$$

$$(D) \lambda = \pm k$$

$$(E) \lambda = \pm \sqrt{k}$$

$$\lambda = \pm \sqrt{k}$$

$$y = C_1 \cos \sqrt{k}x + C_2 \sin \sqrt{k}x$$

$$\lambda = n=1, 4, 9, \dots$$

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Linked

Q* The complete soln of the differential eqn

$$\frac{d^2y}{dx^2} + \frac{py}{dx} + qy = 0$$
 is $y = C_1 e^{-x} + C_2 e^{-3x}$ then
 values of p & q are -

(a) $p=3, q=3$ (b) $p=4, q=3$

(c) $p=4, q=4$ (d) $p=3, q=4$

$$(D+1)(D+3)y = 0$$

$$(D^2 + 4D + 3)y = 0$$

$$D^2y + 4Dy + 3y = 0$$

$$p=4, q=3$$

Q* The soln of $\frac{d^2y}{dx^2} + \frac{py}{dx} + (q+1)y = 0$ is

$$\rightarrow (a) xe^{2x} \quad (b) e^{2x} \quad (c) x e^{-2x} \quad (d) x^2 e^{-2x}$$

$$y'' + 4y' + 4y = 0$$

$$D^2 + 4D + 4 = 0$$

$$(D+2)^2 = 0$$

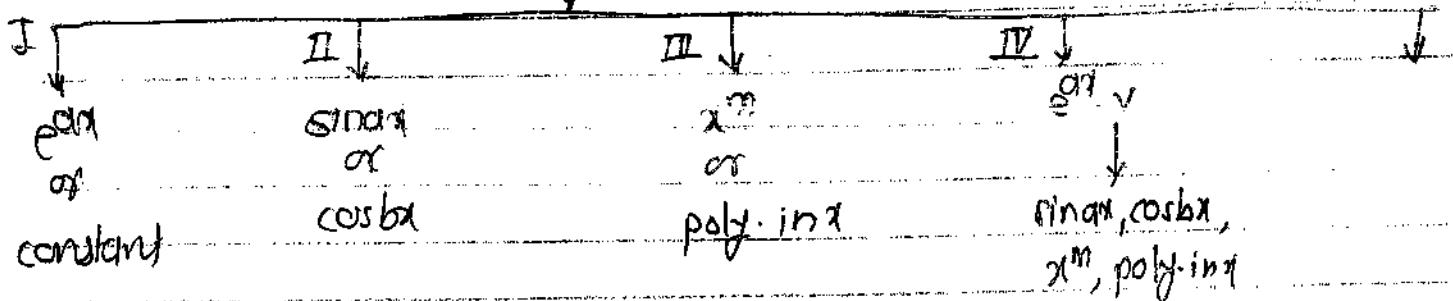
$$D = -2, -2$$

$$y = (C_1 + C_2 x)e^{-2x} = xe^{-2x} \quad \text{if } C_1 = 0, C_2 = 1$$

Particular integrals

$$F(D)Y = X$$

$$PI = \int \frac{1}{F(D)} \boxed{X}$$



Case I - $X = e^{ax}$ or constant

$$PI = \int \frac{1}{F(D)} \boxed{e^{ax}} = \frac{1}{F(a)} e^{ax} \quad (\text{where } F(a) \neq 0)$$

Replace 'D' by 'a' in $f^n f(D)$

if $f(a) = 0$ then

$$PI = \cancel{x} \int \frac{1}{F'(D)} \boxed{e^{ax}}$$

Replace 'D' by 'a' in $F'(D)$

$$PI = x \left[\frac{1}{F'(a)} \right] e^{ax} \quad (F'(a) \neq 0)$$

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$$\text{if } F'(a) = 0 \Rightarrow PI = x^2 \left(\frac{1}{F''(a)} \right) e^{ax} \quad (F''(a) \neq 0)$$

* P.I. of $\frac{d^2y}{dx^2} + 2\frac{dy}{dx} + 7y = e^{-2x}$



$$PI = \frac{1}{D^2 + 2D + 7} e^{-2x} = \frac{1}{(-2)^2 + 2(-2) + 7} e^{-2x}$$

$PI = \frac{e^{-2x}}{7}$

* P.I. of $\frac{d^2y}{dx^2} - 9y = e^{3x} + 3$

$$PI = \frac{1}{D^2 - 9} (e^{3x} + 3)$$

$$= x \left(\frac{1}{2D} \right) e^{3x} + \frac{3}{0-9} e^{0x}$$

$$= \frac{x e^{3x}}{6} + \frac{3}{-9}$$

$$\therefore PI = \frac{x e^{3x}}{6} - \frac{1}{3}$$

$$y \text{ P.I. of } \frac{dy}{dx^2} + 4\frac{dy}{dx} + 4y = e^{-2x}$$

$$\rightarrow P_1 = \left[\frac{1}{D^2 + 4D + 4} \right] e^{-2x} = \alpha \left(\frac{1}{(2D+4)} \right) e^{-2x} = x^2 \left(\frac{1}{2} \right)$$

~~(Case I)~~

$$\therefore P_2 = \frac{x^2}{2} e^{-2x}$$

* 'd' is the root of the A.E. of $F(D)y = e^{ax}$ then P.I. is
(k constant,

- (a) $k e^{ax}$
- (b) $k e^{ax}$
- (c) $k x e^{ax}$
- (d) $\sqrt{a} k e^{ax}$

* Case II -

$$x = \sin(ax) \cos(bx) (\sin(ax+b) \text{ or } \cos(ax+d))$$

$$P_1 = \left[\frac{1}{F(D)} \right] \sin ax = \left[\frac{1}{F(-a^2)} \right] \sin ax \quad (F(-a^2) =$$

Replace ' D^2 ' by ' $-a^2$ ' in $F(D)$

If $F(-a^2) = 0$ -

$$P_1 = \alpha \left[\frac{1}{F(D)} \right] \sin ax = \frac{\alpha}{F'(a^2)} \sin ax$$

Replace ' D^2 ' by ' $-a^2$ ' in $F'(0)$

2A

* PI of $\frac{dy}{dx^4} + \frac{d^2y}{dx^2} + 3y = \cos 3x$

$$\text{PI} = \frac{1}{D^4 + D^2 + 3} \cos 3x = \frac{1}{(-q)^2 + (-q) + 3} \cos 3x$$

$$\text{PI} = \frac{\cos 3x}{75}$$

* PI of $\frac{dy}{dx^2} + 4y = \cos(2x+4) + e^{-2x}$

$$\text{PI} = \frac{1}{D^2 + 4} (\cos(2x+4) + e^{-2x})$$

$$= x \left(\frac{1}{20} \right) \cos(2x+4) + \frac{1}{(-2)^2 + 4} e^{-2x}$$

$$= \frac{x}{2} \frac{\sin(2x+4)}{2} + \frac{e^{-2x}}{8}$$

$$\therefore \text{PI} = \frac{x \sin(2x+4)}{4} + \frac{e^{-2x}}{8}$$

* PI of $\frac{d^3y}{dx^3} + \frac{d^2y}{dx^2} + 2 \frac{dy}{dx} + 2y = \sin x$

$$\text{PI} = \frac{1}{D^3 + D^2 + 2D + 2} \sin x$$

$$(-1)^2 + (-1) + 2 \cdot 0 + 2$$

$\sin x = \sin A$

10
11

来构造 \mathbb{Z} $x = \frac{m}{n}$ or poly. in \mathbb{Z} (m is any integer)

$$P_1 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \quad P_2 = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

* is least ~~poor~~ common in F(D)

$$P_{21} = \frac{1}{2} \left(1 - \sqrt{\left(\frac{D_1}{D_2} \right)^2 + 1} \right)$$

$$\frac{1}{2} \left[1 + \left(\frac{W+2E}{2} \right) \right] = 4.375$$

30

$$= \frac{1}{2} \left[1 - \left(\frac{D^2 + 2D}{2} \right) + \left(\frac{D^2 + 2D}{2} \right)^2 \right] (x^2 + 2)$$

$$= \frac{1}{2} [D^2 + 2 - 1 - 2x + 2]$$

$$\therefore PI = \frac{x^2 - 2x + 3}{2}$$

* PI of $\frac{d^3y}{dx^3} + \frac{3d^2y}{dx^2} = x^3 + 3x$

 \rightarrow

$$PI = \frac{1}{D^3 + 3D^2} (x^3 + 3x) = \frac{1}{3D^2 \left[1 + \frac{D^3}{3D^2} \right]} (x^3 + 3x)$$

$$= \frac{1}{3D^2} \left[1 + \frac{D}{3} \right]^{-1} (x^3 + 3x)$$

$$= \frac{1}{3D^2} \left[1 - \frac{D}{3} + \frac{D^2}{9} - \frac{D^3}{27} \right] J(x^3 + 3x)$$

$$= \frac{1}{3D^2} \left[x^3 + 3x - \frac{3x^2}{3} - 1 + \frac{5x}{9} - \frac{6}{27} \right]$$

$$= \frac{1}{3D^2} \left[x^3 - x^2 + \frac{33x}{9} - \frac{33}{27} \right] = \frac{1}{3D^2} \left[x^3 - x^2 + \frac{11x}{3} - \frac{11}{9} \right]$$

$$= \frac{1}{3} \left[\frac{x^5}{20} - \frac{x^4}{12} + \frac{11x^3}{18} - \frac{11x^2}{18} \right]$$

* Code IV : $x = e^{\frac{dt}{D}} v$

$$PI = \left[\frac{1}{F(D)} \right] \left(e^{\frac{dt}{D}} v \right) = e^{\frac{dt}{D}} \left[\frac{1}{F(D+d)} \right] v$$

Replace 'D' by 'D+a' in F(D)

| | | |
|--------------------|-----|---|
| $\frac{1}{F(D+a)}$ | v | \rightarrow III if $v = \sin bt$ or $\cos bt$ |
|--------------------|-----|---|

| | | |
|--------------------|-----|---|
| $\frac{1}{F(D+a)}$ | v | \rightarrow III if $v = x^m$ or poly. ind |
|--------------------|-----|---|

DE

$$\textcircled{i} \quad \frac{d^2y}{dx^2} + x \left(\frac{dy}{dx} \right)^2 + 4y = 0 \quad - \text{ordinary DE}$$

since only one independent variable

$$\textcircled{ii} \quad \frac{\partial^2 u}{\partial x^2} + \left(\frac{\partial^2 u}{\partial y^2} \right)^3 = 0 \quad - \text{partial DE}$$

since 2 independent variables.

i) order :- The highest derivative involved in the DE is called order of DE.

ii) degree :- The highest power of highest derivative is called degree of DE (provided the derivatives of the dependent variable should free from radicals & fractions).

$$\textcircled{1} \quad \left(\frac{dy}{dx} \right)^2 = \left[x + 4 \left(\frac{dy}{dx} \right)^2 \right]^{3/2}$$

$$\left(\frac{dy}{dx} \right)^4 = \left[x + 4 \left(\frac{dy}{dx} \right)^2 \right]^3$$

order = 2 degree = 4

$$\textcircled{2} \quad \frac{dy}{dx} = x + \frac{2}{\frac{dy}{dx}}$$

$$\left(\frac{dy}{dx} \right)^2 = x \left(\frac{dy}{dx} \right) + 2 \quad \begin{matrix} \text{order} = 1 \\ \text{degree} = 2 \end{matrix}$$

$$\textcircled{3} \quad dr = (\theta + \cos\theta) d\theta$$

$$\frac{dr}{d\theta} = \theta + \cos\theta \quad \begin{matrix} \text{order} = 1 \\ \text{degree} = 1 \end{matrix}$$

$$\textcircled{4} \quad \frac{d^3y}{dx^3} + x \left(\frac{d^2y}{dx^2} \right)^2 + 3y = 0 \quad \begin{matrix} \text{order} = 3 \\ \text{degree} = 1 \end{matrix}$$

$$\textcircled{5} \quad \frac{\partial^2 u}{\partial x^2} = c^2 \left(\frac{\partial^2 u}{\partial y^2} \right)^4$$

order = 2

\Rightarrow Formation of ordinary DE :-

$$F(x, y, a, b) = 0 \quad \text{--- (1)}$$

diff (1) w.r.t. x.

$$F_1(x, y, \frac{dy}{dx}, a, b) = 0 \quad \text{--- (2)}$$

diff (2) w.r.t x

$$F_2(x, y, \frac{dy}{dx}, \frac{d^2y}{dx^2}, a, b) = 0 \quad \text{--- (3)}$$

eliminating a & b from above 3 eq,

$$\phi(x, y, \frac{dy}{dx}, \frac{d^2y}{dx^2}) = 0$$

The no. of arbitrary constants eliminated should be equal to the order of resulting ordinary DE.

* The DE of family of straight line passing through the origin is

(a) $y dy + x dx = 0$

b) none

~~c) $y dx - x dy = 0$~~

d) $y dy - x dx = 0$

$$y = mx$$

$$\frac{dy}{dx} = m \Rightarrow y = \frac{dy}{dx} \cdot x$$

$$y dx - x dy = 0$$

(*) $y = c(x-c)^2$ c is arbitrary const.

$$y' = \frac{dy}{dx} = 2c(x-c)$$

$$\frac{y}{y'} = \frac{x-c}{2} \Rightarrow x-c = \frac{2y}{y'}$$

$$x = \frac{2y}{y'}$$

④ DE of family of circles

Note : If the given eqn of the form $y = Af(x) + Bg(x)$
then the resulting DE is

$$\begin{vmatrix} y & f & g \\ y' & f' & g' \\ y'' & f'' & g'' \end{vmatrix} = 0.$$

⑤ $y = Ae^{2x} + Bx$

$$\begin{vmatrix} y & e^{2x} & x \\ y' & 2e^{2x} & 1 \\ y'' & 4e^{2x} & 0 \end{vmatrix} = 0$$

through $y(-4) - 1(0-y'') + x(Ay' - Ay'') = 0$

$4y^4(1-2x) + 4xy' - 4y = 0$

⑥ $y = e^x(A\cos x + B\sin x) \quad \text{--- ①}$

$$y' = e^x(-A\sin x + B\cos x) + e^x(A\cos x + B\sin x)$$

$$y' = e^x(-A\sin x + B\cos x) + y$$

$$y'' = y' + e^x(-A\cos x - B\sin x) +$$

$$e^x(-A\sin x + B\cos x)$$

$$y'' = y' - 2y + y' - 4y$$

$$y'' - 2y' + 4y = 0$$

Note :- If the given eq of the form

$y = c_1 e^{ax} + c_2 e^{bx} + c_3 e^{cx}$ then

$$(D-a)(D-b)(D-c)y = 0$$

$$D = \frac{d}{dx} \quad D^2 = \frac{d^2}{dx^2}$$

$$y = A e^{2x} + B e^{-3x}$$

$$(D-2)(D+3)y = 0$$

$$(D^2 + D - 6)y = 0$$

$$y'' + y' - 6y = 0$$

$$\textcircled{4} \quad y = c_1 e^{-x} + c_2 e^{-2x} + c_3 e^{-3x}$$

$$(D+1)(D+2)(D+3)y = 0$$

$$(D^3 + 3D^2 + 2D + 1)y = 0$$

$$(D^3 + 6D^2 + 11D + 6)y = 0$$

↓ ↓ ↓
1+2+3 1+2+3+3 1+2+3

$$y''' + 6y'' + 11y' + 6y = 0$$

> Solution of DE :-

$$\frac{d^2y}{dt^2} = g \quad y(0) = 0 \quad y'(0) = 0$$

$$\frac{dy}{dt} = gt + c_1$$

$$y = \frac{1}{2}gt^2 + c_1 t + c_2$$

$$y(0) = 0 \Rightarrow c_2 = 0$$

$$y'(0) = 0 \Rightarrow c_1 = 0$$

$$y = \frac{1}{2}gt^2$$

\Rightarrow 1st order 1st degree DE :-

$$\frac{dy}{dx} = F(x, y)$$

(@)

$$M(x, y) dx + N(x, y) dy = 0.$$

Variable - separable method :-

$$\textcircled{*} \quad \frac{dy}{dx} = e^{x-y} + x^3 e^{-y}$$
$$= e^{-y} (e^x + x^3).$$

$$\int e^y dy = \int (e^x + x^3) dx.$$

$$e^y = e^x + \frac{x^4}{4} + C.$$

$$\textcircled{**} \quad \log\left(\frac{dy}{dx}\right) = 2x + 3y.$$

$$\frac{dy}{dx} = e^{2x} \cdot e^{3y}.$$

$$\int e^{-3y} dy = \int e^{2x} dx.$$

$$\frac{-1}{3} e^{-3y} = \frac{e^{2x}}{2} + C.$$

$$\textcircled{***} \quad \frac{dy}{dx} \leq \frac{y^2}{1-xy}.$$

$$(1-xy) dy = y^2 dx$$

$$dy = y^2 dx + xy dy.$$

$$dy = y(y dx + x dy)$$

$$\int \frac{1}{y} dy = \int d(xy)$$

$$\log y = xy + C$$

$$\textcircled{****} \quad \frac{dy}{dx} = \frac{-x}{y} \quad \text{at } x=1, y=\sqrt{3}$$

$$\int y dy = \int -x dx.$$

$$\frac{y^2}{2} = \frac{-x^2}{2} + C \Rightarrow C = \frac{3}{2} + \frac{1}{2} = 2.$$

$$y^2 = -x^2 + 4.$$

$$\textcircled{*****} \quad \frac{dy}{dx} = y^2 \sin x \Rightarrow y(2\pi) = 1.$$

$$\text{or } y \sin x = 1 \quad \text{or } y \cos^2 x = 1$$

$$\int \frac{1}{y^2} dy = \int dx \sin x$$

$$-\frac{1}{y} = -\cos x + c \Rightarrow c = 0$$

$$y \cos x = 1.$$

$$\frac{dy}{dx} = 3x^2 - 2x \quad \text{passes through } (1,1) \text{ then}$$

find mag. of y when $x=3$

$$\int dy = \int 3x^2 - 2x dx$$

$$y = x^3 - x^2 + c.$$

$$(1,1) \Rightarrow c = 1.$$

$$y = x^3 - x^2 + 1.$$

$$\text{when } x=3 \Rightarrow y=19.$$

Bio transformation of an organic compound having conc. 'x' can be modelled using DE $\frac{dx}{dt} + kx^2 = 0$.

At $t=0$, the conc. is 'a' then the soln. is

$$\frac{dx}{dt} = -kx^2$$

$$\int \frac{1}{x^2} dx = -k/dt$$

$$-\frac{1}{x} = -kt + c \Rightarrow c = -\frac{1}{xa}$$

$$\frac{dx(t)}{dt} + kx(t) = 0$$

$$\int \frac{1}{x} dx = \int -k dt$$

$$\log x = -kt + \log c.$$

$$x = e^{-kt} e^{\log c}$$

$$\frac{dy}{dx} = 1+y^2$$

$$\int \frac{1}{1+y^2} dy = \int dx$$

$$\tan^2 y = x + c$$

$$y = \tan(x+c).$$

- ④ Find the curve passing through the point $(0, 1)$ satisfying $\sin\left(\frac{dy}{dx}\right) = b$.

$$\frac{dy}{dx} = \sin^2 b$$

$$\int dy = \int \sin^2 b dx$$

$$y = (\sin^2 b)x + c$$

$$(0, 1)$$

$$c = 1$$

- ⑤ $\frac{dy}{dx} = e^{x+y}$ given that for $x=1, y=1$;

find y when $x = -1$.

$$\int e^{-y} dy = \int e^x dx$$

$$-e^{-y} = e^x + c \Rightarrow c = -e^{-1} - e$$

$$\Rightarrow -e^{-y} = e^x - (e^{-1} + e)$$

$$\text{at } x=1 \Rightarrow -e^{-y} = e^1 - e^{-1} - ee$$

$$y = -1$$

- ⑥ $\frac{dy}{dx} = (4x+y+1)^2$

$$\frac{dv}{dx} = v^2 + 4$$

$$\int \frac{1}{v^2+4} dv = \int dx$$

$$\frac{1}{2} \tan^{-1}\left(\frac{v}{2}\right) = x + c$$

$$4x+y+1 = v$$

$$4 + \frac{dy}{dx} = \frac{dv}{dx}$$

$$\frac{dy}{dx} = \frac{dv - 4}{dx}$$

$$\frac{4x+y+1}{2} = \tan(2x+c)$$

$$4x+y+1 = 2\tan(2x+c)$$

homogeneous differential eqn :-

$$\frac{dy}{dx} = f(x, y)$$

is said to be homogeneous DE if $f(x, y)$ should be a homogenous fn of degree '0'.

e.g.: $Mdx + Ndy = 0$ is said to be homogeneous if all the terms of M & N should be same degree.

for variable - separable sub $y = vx \Rightarrow x = vy$.

$$x \frac{dy}{dx} = y \{ \log y - \log x + 1 \}$$

$$\therefore \frac{dy}{dx} = \frac{y}{x} \left\{ \log \left(\frac{y}{x} \right) + 1 \right\}$$

$$y = vx \Rightarrow \frac{dy}{dx} = v + x \frac{dv}{dx}$$

$$v + x \frac{dv}{dx} = v \{ \log v + 1 \}$$

$$x \frac{dv}{dx} = v \log v$$

$$\int \frac{1}{v \log v} dv = \int \frac{1}{x} dx$$

$$\log(\log v) = \log x + \log c$$

$$\log v = xc \Rightarrow v = e^{cx} \Rightarrow y = x e^{cx}$$

$$(x^3 + 3xy^2) dx + (y^3 + 3x^2y) dy = 0$$

Non-homogeneous DE

An eqn of the form

$$\frac{dy}{dx} = \frac{a_1x + b_1y + c_1}{a_2x + b_2y + c_2}$$

$$\text{case (i) :- } \frac{a_1}{a_2} = \frac{b_1}{b_2}$$

In this case there exists a substitution which reduces the given eqn to variable - separable form.

$$\text{case (ii) :- } \frac{a_1}{a_2} \neq \frac{b_1}{b_2}$$

Genous

be

$$\text{sub, } x = x + h, \quad y = y + k$$

$$dx = dx, \quad dy = dy$$

y.

$$\frac{dy}{dx} = \frac{a_1(x+h) + b_1(y+k) + c_1}{a_2(x+h) + b_2(y+k) + c_2}$$

$$\frac{dy}{dx} = \frac{a_1x + b_1y + (a_1h + b_1k + c_1)}{a_2x + b_2y + (a_2h + b_2k + c_2)}$$

choose h, k so that $a_1h + b_1k + c_1 = 0, a_2h + b_2k + c_2 = 0$

$$\frac{dy}{dx} = \frac{a_1x + b_1y}{a_2x + b_2y}$$

$$\textcircled{a} \quad (2x + 2y - 1) dx = (x + y + 1) dy$$

$$\frac{dy}{dx} = \frac{2x + 2y - 1}{x + y + 1} \quad \left(\frac{a_1}{a_2} = \frac{b_1}{b_2} \right)$$

$$\frac{dy}{dx} - 1 = \frac{2v - 1}{v + 1}$$

$$\frac{dv}{dx} = \frac{3v}{v+1}$$

$$x + y = v$$

$$1 + \frac{dy}{dx} = \frac{dv}{dx}$$

$$\int \frac{v+1}{v} dv = 3 \int dx \Rightarrow v + \log v = 3x + C$$

$$x + y + \log(x+y) = 3x + C \Rightarrow y - 2x + \log(x+y) =$$

\textcircled{b} which of the following sub reduces the

non-homogeneous eqn $\frac{dy}{dx} = y + x - 2$ to hom.

form

$$k+h-2=0 \quad k=3 \quad h=-1$$

$$k-h-4=0$$

$$x = (x+1) \quad y = (y+3)$$

$$\text{hom form} \Rightarrow \frac{dy}{dx} = \frac{y+x}{y-x}$$

Exact differential eqn :-

An eqn $Mdx + Ndy = 0$ is said to be an exact DE if

$\exists f(x,y)$ such that $d(f(x,y)) = Mdx + Ndy$.

condition to be exact

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

if this satisfies then

find soln.

$$Mdx + Ndy = 0$$

$$\int M dx + \int (terms \ of \ N \ dy \ without \ x) dy = c$$

Keep 'y' const ~~variable~~

④ $\left\{ y\left(1+\frac{1}{x}\right) + \cos y \right\} dx + \left\{ x + \log x - x \sin y \right\} dy = 0$

$$\frac{\partial M}{\partial y} = 1 + \frac{1}{x} - \sin y$$

$$\frac{\partial N}{\partial x} = 1 + \frac{1}{x} - \sin y$$

exact!!

solt.

$$\int \left(y\left(1+\frac{1}{x}\right) + \cos y \right) dx + \int 0 \cdot dy = c$$

y → const

$$y(x + \log x) + x \cos y + C = c$$

$$\textcircled{4} \quad y \sin 2x \, dx - (1 + y^2 + \cos^2 x) \, dy = 0.$$

M

N

$$\frac{\partial M}{\partial y} = \sin 2x \quad \frac{\partial N}{\partial x} = 2 \sin x \cos x \\ = \sin 2x$$

eqⁿ is exact.

so

$$\int y \left(\frac{-\cos 2x}{2} \right) + \int (-1 - y^2) \, dy = c.$$

$$-\frac{y \cos 2x}{2} - y - \frac{y^3}{3} = c.$$

\textcircled{5} The eqⁿ $P \, dx + (1 + \sin^2 y + \cos^2 x) \, dy = 0$ is exact then

a) $P = \cos 2x$

b) $P = \sin 2x$

c) $P = -\cos 2x$

~~d)~~ p = -sin 2x

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

$$P = -\sin 2x$$

\textcircled{6} $P \, dx + (1 + \cos^2 z + \sin^2 y) \, dy = 0$ is exact.

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

$$\frac{\partial (P)}{\partial y} = 2 \cos z (-\sin z) \\ = -\sin 2z$$

$$P = \int -\sin 2z \, dy$$

$$P = -y \sin 2z$$

\textcircled{7} The DE

$$(3ax^2 + by \cos z) \, dx + (2 \sin z - 4ay^3) \, dy = 0$$

is exact then

a) exactness depends on both a & b

b) " not

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

$$+ b \cos x = 2 \cos x$$

$b = +2$ not depends on 'a'
only depends on b .

Q) $y dx - x dy = 0$

$$\frac{\partial M}{\partial y} = 1 \quad \frac{\partial N}{\partial x} = -1$$

not exact.

to make it exact, multiply with $1/y^2$

$$\frac{1}{y} dx - \frac{x}{y^2} dy = 0$$

$$\frac{\partial M}{\partial y} = -\frac{1}{y^2} = \frac{\partial N}{\partial x} \text{ (exact)}$$

$\therefore 1/y^2$ is called integrating factor.

⇒ Integrating factor:- A non-exact eqn is converted to exact by multiplying a fn $f(x,y)$ then $f(x,y)$ is called integrating factor.

The integrating factors of $y dx - x dy = 0$ are

$$\frac{1}{y^2}, \frac{1}{x^2}, \frac{1}{xy}, \frac{1}{x^2+y^2}$$

$$M dx + N dy = 0$$

non-exact eq

$$\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$$

I

II

IV

All the terms eq is of the

of M & N should

form

$$\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} = f(x)$$

be of same

$$y f(xy) dx +$$

degree, then

$$x g(xy) dy = 0$$

only

$\int f(x) dx$

$\int g(y) dy$

IV

$$\frac{\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y}}{M} = g(y) \text{ only if constant}$$

$$\int g(y) dy.$$

IF = e

II Inspection method:

$$\textcircled{3} \quad y(xy - 2) dx + x(x^2y^2 + 2xy + 1) dy = 0 \quad \text{--- (1)}$$

$$(xy^2 - 2y) dx + (x^3y^2 + 2x^2y + x) dy = 0$$

$$\frac{\partial M}{\partial y} = 2xy - 2$$

$$\frac{\partial N}{\partial x} = 3x^2y^2 + 4xy + 1$$

from (1) it is in form $yf(xy) dx + xf(xy) dy = 0$

it is so IF = $\frac{1}{Mx - Ny}$

form II

$$f(xy) = x^2y^2, xy, \dots$$

$$f(x, y) = x^2y^3 + 2x, \dots$$

parted

n

$$\text{IF} = \frac{1}{x^2y^2 - 2xy - (x^3y^3 + 2x^2y^2 + xy)}$$

$$= \frac{-1}{x^3y^3 + 3x^2y^2 + 3xy}$$

$\textcircled{4}$ The non-exact homogeneous DE $Mdx + Ndy = 0$ is converted to exact by multiplying with which of following functions

Ans: $\frac{1}{Mx + Ny}$

given homogeneous so degrees of M & N will be same so use II.

$$\textcircled{5} \quad x^2y dx - (x^3 + y^3) dy = 0$$

$f(y)$
only
 dx

$$\frac{\partial M}{\partial y} = x^2 \quad \frac{\partial N}{\partial x} = -3x^2$$

all the M & N have same degree

$$\frac{x^3y}{-y^4} dx - \left(\frac{x^3+y^3}{-y^4} \right) dy = 0 \quad \rightarrow \text{exact}$$

$\int M dx + \int \text{terms no } x$

$$-\frac{x^3}{3y^3} + \log y = c \quad \text{is the soln.}$$

$$\textcircled{*} \quad x(x-2y) dy + (x^2+y^2+1) dx = 0$$

$$\frac{\partial M}{\partial y} = 2y \quad \frac{\partial N}{\partial x} = 2x - 2y$$

$$\frac{\partial M}{\partial y} + \frac{\partial N}{\partial x} = \frac{2y - 2x + 2y}{x(x-2y)} \\ = \frac{-2(x-2y)}{x(x-2y)}$$

$$= -\frac{2}{x} f(x)$$

$$\text{If } e^{-\int \frac{2}{x} dx} = e^{-2\log x} = \frac{1}{x^2}$$

$$\frac{x(x-2y)}{x^2} dy + \frac{(x^2+y^2+1)}{x^2} dx = 0$$

$$\text{soln: } x - \frac{y^2 - 1}{x} + \int f(x) dy$$

$$x - \left(\frac{1+y^2}{x} \right) + y = c$$

$$\int f(x) dx$$

$$\textcircled{*} \quad f(x)$$

$$c$$

$$\frac{1}{x}$$

$$x$$

$$\frac{2}{x}$$

$$x^2$$

$$\frac{3}{x}$$

$$x^3$$

$$\frac{-1}{x}$$

$$x^{-1} = \frac{1}{x}$$

$$\frac{-2}{x}$$

$$\sqrt{x^2}$$

$$\textcircled{2} \quad y(1-xy)dx - x(1+xy)dy = 0$$

$$\frac{\partial M}{\partial y} = 1-2xy \quad \frac{\partial N}{\partial x} = -1-2xy.$$

case (ii)

$$Mx-ny = xy - x^2y^2 + xy + x^2y^2 \\ = 2xy.$$

$$IF = \frac{1}{2xy}.$$

$$\frac{y(1-xy)}{2xy} - \frac{x(1+xy)}{2xy} = 0.$$

(don't cancel
variables — cancel
constants \Rightarrow

$$\frac{1-xy}{x} - \frac{1+xy}{y} = 0.$$

$$\text{soln is } \log x - xy - \int \frac{1}{y} dy$$

$$\log x - xy - \log y = c.$$

- * By multiplying ^{with} which of the following functions the eq $(y^4 + 2y)dx + (xy^3 + 2y^4 - 4x)dy = 0$ is converted to exact.

$$\frac{\partial M}{\partial y} = Ay^3 + 2 \quad \frac{\partial N}{\partial x} = y^3 - 4$$

case (4)

$$\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} = \frac{y^3 - 4 - 4y^3 - 2}{y^4 + 2y} \\ = -3(y^3 + 2)$$

$$IF = \frac{1}{y^3} \quad (\text{or}) \quad e^{\int -3/y dy} = e^{-3 \log y} = \frac{1}{y^3}$$

- * The IF of

$$y(x^2y^2 + 2y + 1)dx + 2(x^2y^2 - 2y + 1)dy = 0,$$

case ② since $x f(xy) + y g(xy) = 0$.

$$\begin{aligned} Mx - Ny &= x^3y^3 + x^2y^2 + xy - x^3y^3 + x^2y^2 - xy \\ &= 2x^2y^2 \end{aligned}$$

$$IF = \frac{1}{2x^2y^2} \quad @ \quad \frac{1}{x^2y^2} \quad (\text{const does not make difference})$$

$$④ ydx - xdy + (1+x^2)dx + x^2\sin y dy = 0.$$

$$(xd^y + ydx) + (dx + x^2\sin y dy) = 0$$

when there is $ydx - xdy$ is a part of DE

then simply multiply with $\frac{1}{x^2} \cdot \frac{1}{y^2} \cdot \frac{1}{xy} \cdot \frac{1}{x^2+y^2}$

& then integrate

By multiplying with $\frac{1}{x^2}$ we can easily integrate
it is not possible with other terms

Depending on the DE multiply with IF

Note:

$$\frac{ydx - xdy}{y^2} = d\left(\frac{x}{y}\right)$$

$$\int y e^y = e^y(y-1)$$

$$\frac{ydx - xdy}{x^2} = -d\left(\frac{x}{y}\right)$$

$$\int y e^{-y} = -e^{-y}(y+1)$$

$$\frac{ydx - xdy}{xy} = d\left[\log\left(\frac{x}{y}\right)\right]$$

$$\frac{ydx - xdy}{x^2+y^2} = d\left[\tan^{-1}\left(\frac{x}{y}\right)\right]$$

sol multiply with $\frac{1}{x^2}$

$$\frac{ydx - xdy}{x^2} + \left(\frac{1+x^2}{x^2}\right)dx + \frac{x^2\sin y dy}{x^2} = 0 \quad (a)$$

$$= -\frac{y}{x} - \frac{1}{x} + x + (-\cos y) = c$$

~~-xy~~

$$\textcircled{(2)} \quad y \underline{dx} - x \underline{dy} + y(1+x^2) dx + xy^2 e^y dy = 0$$

multiply with $\frac{1}{xy}$

~~snat
fence~~

$$y \underline{\frac{dx - x dy}{xy}} + \left(\frac{1+x^2}{x}\right) dx + \underline{ye^y dy} = 0$$

$$\int d\left[\log\left(\frac{x}{y}\right)\right] + \int \left(\frac{1}{x} + x\right) dx + \int ye^y dy = 0$$

$$\log\left(\frac{x}{y}\right) + \log x + \frac{x^2}{2} + e^y(y-1) = c$$

~~z~~

$$\textcircled{(3)} \quad y dx + x dy = d(xy)$$

$$\underline{\frac{y dx + x dy}{xy}} = d[\log(xy)]$$

~~z~~

$$\textcircled{(4)} \quad y dx + x dy + xy^2 e^{-y} dy = 0$$

multiply with $\frac{1}{xy}$

$$\int \underline{\frac{y dx + x dy}{xy}} + \int ye^{-y} dy = 0$$

$$\log(xy) - e^{-y}(y+1) = c$$

\Rightarrow Linear Differential Equations

A DE is said to be linear if the dependent variable & derivatives should be of 1st degree only & there should be no product of them.

(should) (y) , $(\frac{dy}{dx})$, $(\frac{d^2y}{dx^2})$... degree = 1.

(should not) $y \frac{dy}{dx}$, $\frac{d^2y}{dx^2} \frac{d^4y}{dx^4}$ (there should not be multiplication)

$$③ \frac{d^2y}{dx^2} + 4\left(\frac{dy}{dx}\right)^2 + e^y = 0$$

multiplication
came

is not a linear eqn bcoz ($e^y = 1 + y + y^2 + y^3$)

$$\frac{d^2y}{dx^2} + 4\left(\frac{dy}{dx}\right)^2 + 4y = 0 \quad \text{is the non-linear eq.}$$

$\frac{dy}{dx}, \frac{dy}{dx}$ multiplication
came.

⇒ Linear in y :-

$$\frac{dy}{dx} + Py = Q$$

P & Q are fns of x

or constants.

IF

sln.

$$ye^{\int P dx} = \int Q e^{\int P dx} dx + C$$

⇒ Linear in x :-

$$\frac{dx}{dy} + Px = Q$$

P & Q are fns
of y or constants

IF

sln is.

$$x e^{\int P dy} = \int Q e^{\int P dy} dy + C$$

$$) x \cos x \frac{dy}{dx} + y(x \sin x + \cos x) = 1$$

$$\frac{dy}{dx} + y \tan x + \frac{y}{x} = \frac{1}{x \cos x}$$

$$\frac{dy}{dx} + y \left(\tan x + \frac{1}{x} \right) = \frac{1}{x \cos x}$$

$P = \tan x + \frac{1}{x}$

$Q = \frac{1}{x \cos x}$

$I.F. = e^{\int (\tan x + \frac{1}{x}) dx} = e^{\log \sec x + \log x} = \sec x \cdot x$

sln

solution
comes

$$(y^2 + 3)$$

$$\text{soln} : y(x \sec x) = \int \frac{1}{x \cos x} x \sec x dx + C \\ = \int \sec^2 x dx$$

for eq.

$$xy \sec x = \tan x + C$$

$$\textcircled{2} \quad (x + 2y^3) \frac{dy}{dx} = y \quad \text{with} \quad x(1) = 0$$

Linear in x.

of x

$$x + 2y^3 = y \frac{dx}{dy}$$

$$\frac{dx}{dy} = \frac{x + 2y^3}{y}$$

$$\frac{dx}{dy} - \frac{x}{y} = 2y^2 \quad P = \frac{-1}{y}$$

$$\text{IF } e^{-\int \frac{1}{y} dy} = y$$

rhs
stands

$$\text{soln} : x \cdot \frac{1}{y} = \int 2y^2 \cdot \frac{1}{y} dy + C$$

$$\frac{x}{y} = y^2 + C \quad \text{at } y=1, x=0 \\ \frac{0}{1} = 1 + C \quad C = -1$$

$$x/y = y^2 - 1$$

$$\textcircled{3} \quad x^2 \frac{dy}{dx} + 2xy = \frac{2 \log x}{x}; \quad y(1)=0 \quad \text{find } y$$

when. $x = e$.

Linear in y:

$$\frac{dy}{dx} + \frac{2y}{x} = \frac{2 \log x}{x^3}$$

$$\text{IF } e^{\int \frac{2}{x} dx} = x^2$$

soln

$$4x^2 = \int \frac{2 \log x}{x^3} \cdot x^2 dx$$

$$\boxed{f(x) \cdot f'(x)} = f(x)^2$$

$$\text{at } x=1 ; y=0 \Rightarrow c=0$$

$$x^2y = (\log x)^2 + 0$$

$$\text{at } x=e \quad e^2y = (\log e)^2$$

$$e^2y = 1 \Rightarrow y = e^{-2}$$

④ $x \frac{dy}{dx} + y = x^4 \quad ; \quad g(1) = \frac{6}{5}$

$$\frac{dy}{dx} + \frac{y}{x} = x^3$$

$$IF = e^{\int \frac{1}{x} dx} = \frac{1}{x} \cdot x$$

Soln. $\frac{-y}{x} = \int x^3 \cdot \frac{1}{x} dx + C$

$$\frac{-y}{x} = -\frac{x^5}{5} + C$$

$$\text{at } x=1 \quad y=6/5 \Rightarrow C=1$$

$$xy = \frac{x^5}{5} + 1$$

$$y = \frac{x^4}{5} + \frac{1}{x}$$

$$\Rightarrow \frac{dy}{dx} + Py = Qy^n \rightarrow \text{is not a linear eq'}$$

↓ Sub $y^{1-n} = v$

reduces Bernoulli eq to linear eq.

$$y^{1-n} \int (1-n)P dx = \int (1-n)Q \cdot v^{\frac{n}{1-n}} dx + C$$

(If y^n is there, then multiply $(1-n)$ to every term in soln.)

④ The sub $y^{1-n} = v$ reduces the non-linear eq

$\frac{dy}{dx} + Py = Qy^n$ to which of following linear

$$\frac{1}{y^n} \frac{dy}{dx} + P \frac{y}{y^n} = Q.$$

$$y^{1-n} = v \Rightarrow (-n)y^{1-n-1} \frac{dy}{dx} = \frac{dv}{dx}$$

$$\Rightarrow \frac{1}{y^n} \frac{dy}{dx} = \frac{1}{1-n} \frac{dv}{dx}$$

$$\frac{1}{1-n} \frac{dv}{dx} + Pv = Q$$

$$\boxed{\frac{dv}{dx} + Pv(1-n) = Q(1-n)}.$$

- ② which of the following sub reduces the non-linear eqⁿ to linear form

$$y \frac{dy}{dx} + x^2 y^3 = x^3 y^3.$$

$$\frac{dy}{dx} + x^2 y^2 = x^3 y^2$$

$$y^{1-n} = v \Rightarrow y^{1-2} = v \Rightarrow y^{-1} = v$$

$$③ \frac{dy}{dx} - y \tan x = -y^2 \sec x$$

$$e^{\int (1-z)(-\tan x) dx} = e^{\log \sec x} = \sec x$$

$$y^{1-2} \sec x = \int (1-z)(-\sec x) \sec x dx$$

$$\frac{\sec x}{y} = \tan x + C$$

* eq

\Rightarrow Equation of the form

$$\boxed{f'(y) \frac{dy}{dx} + P f(y) = Q}$$

$$f(y) = v \Rightarrow f'(y) \frac{dy}{dx} = \frac{dv}{dx}$$

$$\frac{dv}{dx} + Pv = q$$

④ The sub $(\log z)^{-1} = v$ reduces the non-linear

$$\text{eq } \frac{dz}{dx} + \frac{z \log z}{x^2} = \frac{z (\log z)^2}{x^2}$$

$$\frac{1}{z (\log z)^2} \frac{dz}{dx} + \frac{(\log z)^{-1}}{x} = \frac{1}{x^2}$$

$$(\log z)^{-1} = v \Rightarrow -(\log z)^{-2} \frac{dz}{dx} = \frac{dv}{dx}$$

$$\frac{1}{z (\log z)^2} \frac{dz}{dx} = -\frac{dv}{dx}$$

$$-\frac{dv}{dx} + \frac{v}{x} = \frac{1}{x^2}$$

$$\frac{dv}{dx} - \frac{v}{x^2} = \frac{1}{x^2}$$

$$x \frac{dy}{dx} + y \log y = xy e^x$$

$$\frac{1}{y} \frac{dy}{dx} + \frac{\log y}{x} = e^x$$

$$\log y = v \Rightarrow \frac{1}{y} \frac{dy}{dx} = \frac{dv}{dx}$$

$$\frac{dv}{dx} + \frac{v}{x} = e^x$$

$$IF = e^{\int \frac{1}{x} dx} = x$$

$$v y x = \int e^x x dx$$

$$x \log y = e^x(x-1) + c.$$

→ Clairaut's eqn :-

An eq of the form

-Linear

$$y = x \frac{dy}{dx} + f\left(\frac{dy}{dx}\right).$$

$$\textcircled{a} \quad \left(\begin{array}{l} y = px + f(p) \\ \text{replace } \frac{dy}{dx} \rightarrow c. \end{array} \right)$$

$y = cx + f(c)$ is the soln.

$$\textcircled{b} \quad p = \sin(y - xp)$$

$$y - xp = \sin^{-1} p$$

$$y = xp + \sin^{-1} p$$

$$y = cx + \sin^{-1} c q \quad (c \& q \text{ const})$$

$$\textcircled{c} \quad (x-a)y'^2 + (x-y)y' - y = 0$$

$$xy'^2 - ay'^2 + xy' - yy' - y = 0$$

$$xy'(y'+1) - ay'^2 = y(y'+1)$$

$$xy' - \frac{ay'^2}{y'+1} = y$$

$$y = cx - \frac{ac^2}{1+c^2}$$

$$\textcircled{d} \quad \left(y - x \frac{dy}{dx} \right) \left(\frac{dy}{dx} - 1 \right) = \frac{dy}{dx}$$

$$(y - xy') (y' - 1) = y'$$

⇒ Higher order linear eqn with constant coefficients

$$\frac{d^n y}{dx^n} + k_1 \frac{d^{n-1} y}{dx^{n-1}} + \dots + k_{n-1} \frac{dy}{dx} + k_n y = x$$

k_1, k_2, \dots, k_{n-1} are constants

x is fn of x .

$$D = \frac{d}{dx} \quad \text{--- differential operator}$$

$$\frac{1}{D} = \int \quad \text{--- inverse differential operator.}$$

$$(D^n + k_1 D^{n-1} + \dots + k_{n-1} D + k_n) y = x$$

$$F(D) y = x$$

$$F(D) = D^n + k_1 D^{n-1} + \dots + k_{n-1} D + k_n = 0$$

is called auxillary eqn.

④ The complete solution of $F(D)y = x$ is

$y = \text{complementary fn} + \text{particular integral}$
(CF) (PI)

⑤ If $x = 0$ then $F(D)y = 0$ is called the homogenous linear DE.

⑥ If $x \neq 0$ then $F(D)y = x$ is called non-homogeneous DE.

⑦ The soln of homogenous linear DE

$(F(D)y = 0)$ is called CF.

The no. of arbitrary constants in the CF should

be equal to the higher order of given DE.

fficients

Pi will not contain any arbitrary constants.

- ② If $x=0$ the complete soln of $F(D)y = x$ is
is only CF.

⇒ Procedure to find the CF :-

By assuming 'D' as an algebraic quantity.

$F(D) = 0$ becomes an algebraic eqn & by solving it we get roots for these. Based on the nature of these roots we write CF as follows.

| Nature of roots | CF |
|--|--|
| 1. Real & Distinct $D = m_1, m_2, m_3$ | $CF = c_1 e^{m_1 x} + c_2 e^{m_2 x} + c_3 e^{m_3 x}$ |
| 2. Real & Repeated. $D = m_1, m_1, m_3$ | $CF = (c_1 + c_2 x) e^{m_1 x} + c_3 e^{m_3 x}$ |
| 3. complex & distinct $D = a+ib, m_3$ | $e^{ax} [c_1 \cos bx + c_2 \sin bx] + c_3 e^{m_3 x}$ |
| 4. complex & repeated $D = a+ib, a+ib, m_5$ | $e^{ax} [(c_1 + c_2 x) \cos bx + (c_3 + c_4 x) \sin bx] + c_5 e^{m_5 x}$ |

Eg:
roots.

$$D = 1, -1/2, 1/2$$

$$CF = c_1 e^x + c_2 e^{-1/2x} + c_3 e^{1/2x}$$

$$D = -2, -2, 1$$

$$CF = (c_1 + c_2 x) e^{-2x} + c_3 e^x$$

$$D = 3 \pm 4i, -1 \quad CF = e^{3x} [c_1 \cos 4x + c_2 \sin 4x] + c_3 e^{-x}$$

$$D = \pm 2i, \pm 3 \quad CF = [c_1 + c_2 \cos 2x + c_3 \sin 2x]$$

G

$$\textcircled{8} \quad \frac{d^2y}{dx^2} - 5 \frac{dy}{dx} + 6y = 0$$

$$D^2 - 5D + 6 = 0 \quad D = 3, 2$$

$$CF = C_1 e^{3x} + C_2 e^{2x}$$

\textcircled{9}

$$\frac{d^4y}{dx^4} - 81y = 0$$

$$D^4 - 81 = 0$$

$$(D^2 - 9)(D^2 + 9) = 0$$

$$D = \pm 3, \pm i3$$

$$y = C_1 e^{3x} + C_2 e^{-3x} + (C_3 \cos 3x + C_4 \sin 3x)$$

in option, it ~~will~~ maybe

$$e^{-3x} + \sin 3x$$

choosing different values

& C_1, C_2, C_3, C_4 ...

\textcircled{10}

$$y'' + 2pq' + (P^2 + q^2)y = 0$$

$$\therefore D^2 + 2PD + (P^2 + q^2) = 0$$

$$D = \frac{-2P \pm \sqrt{4P^2 - 4(P^2 + q^2)}}{2}$$

$$= -P \pm \sqrt{P^2 - P^2 - q^2}$$

$$= -P \pm iq$$

$$y = e^{-xp}(C_1 \cos qx + C_2 \sin qx)$$

\textcircled{11}

$$y''' - 4y'' + 5y' - 2y = 0$$

$$D^3 - 4D^2 + 5D - 2 = 0$$

$D = 1$ is root

| | | | | |
|---------|---|----|----|----|
| | 1 | -4 | 5 | -2 |
| $D = 1$ | 0 | 1 | -3 | 2 |

$$D^2 - 3D + 2 = 0$$

$$D = +1, +2$$

roots are 1, +1, +2



$$D-2 = 0 \rightarrow 2, -2$$

$$D(D-2) + 1(D-2) = 0$$

$$(D-1)(D-2) = 0$$

$$y = c_1 e^x + c_2 e^{2x} + c_3 e^{-2x}$$

$$y = (c_1 + c_2 x) e^x + c_3 e^{2x}$$

Note :- If $y = c_1 y_1 + c_2 y_2 + c_3 y_3 + \dots$ is a soln.

maybe
value

of $F(D)y = 0$, then each one y_1, y_2, y_3, \dots
is linearly independent soln of $F(D)y = 0$.

④ $\frac{d^2 f}{dt^2} - 4 \frac{df}{dt} + 4f = 0$

3x)

a) $f_1 = e^{2t}, f_2 = e^{-2t}, f_3 = e^{2t}, f_4 = t e^{2t}$

c) $f_1 = e^{-2t}, f_2 = t e^{-2t}, f_3 = e^{2t}, f_4 = t e^{2t}$

$$D^2 - 4D + 4 = 0$$

$$(D-2)^2 = 0$$

$$D = 2, 2$$

$$y = (c_1 + c_2 t) e^{2t}$$

$$c_1 e^{2t} + c_2 t e^{2t}$$

④ The DE $(D^2 + 4\cos 2D + 3)y = x^2$ is b.

a) homogenous DE

b) non-homogeneous DE
with const. coef.

~~c) Linear DE~~

d) Non-Linear DE

④ y_1, y_2 are linearly independent solns of

$F(D)y = 0$ then which of the following is
the soln of the same eqn.

④ y_1, y_2 are linearly independent soln of the corresponding homogenous eqⁿ of $F(D)y = x$ then $y_1 + y_2$ is the soln of which of following eqⁿ

a) $F(D)y = x$ b) $F(D)y = 0$

c) $x = 0$ d) $F(D)y = 0$

⑤ e^{2x}, e^{-3x} are the so linearly independent solns

$$D = 2, -3$$

$$(D-2)(D+3)y = 0$$

$$(D^2 + D - 6)y = 0$$

$$y'' + y' - 6y = 0$$

⑥ $e^{2x} + xe^{2x}$

$$= (C_1 + C_2 x)e^{2x}$$

$$(D-2)^2 y = 0$$

$$(D^2 - 4D + 4)y = 0 \Rightarrow y'' - 4y' + 4y = 0$$

⑦ e^{2x}, e^{-2x} are soln of which

$$D = 2, -2$$

(see option sub $D=2, -2$ which satisfies to eq) It may be

$$(D^2 - 4)y = 0 \Rightarrow y'' - 4y = 0 \quad \frac{d^4y}{dx^4} - 16y = 0$$

⑧ $\sin 3x, \cos 3x$ are LI soln of which of the

following DE

$$y = C_1 \cos 3x + C_2 \sin 3x$$

the
④ $y'' + 4y' + 13y = 0 ; y(0) = 0 \Rightarrow y'(0) = 1.$

then

$$(D^2 + 4D + 13) = 0.$$

egn

$$D = \frac{-4 \pm \sqrt{16 - 52}}{2}$$

$$= \frac{-4 \pm i\sqrt{36}}{2} = -2 \pm 3i.$$

solsns

$$y = e^{-2x} (C_1 \cos 3x + C_2 \sin 3x).$$

$$\text{at } x=0, y=0.$$

$$0 = C_1$$

$$y = e^{-2x} C_2 \sin 3x.$$

$$\therefore y' = C_2 \left[e^{-2x} (3 \cos 3x) + (-2)e^{-2x} \sin 3x \right]$$

$$\text{at } x=0, y' = 1.$$

$$1 = C_2 [3] \Rightarrow C_2 = \frac{1}{3}.$$

$$y = \frac{e^{-2x}}{3} \sin 3x.$$

⑤ which of the following is not a soln of

$$\frac{d^2i}{dt^2} + \frac{R}{L} \frac{di}{dt} + \frac{i}{LC} = 0.$$

where: $R^2C = 4L$. R, L, C be the constants.

which

a) $i = e^{-Rt/2L}$ b) $i = t e^{-Rt/2L}$

sy. = 0

c) $i = t e^{Rt/2L}$ d) $i = e^{-Rt/2L} + t e^{-Rt/2L}$

$$D^2 + \frac{R}{L} D + \frac{1}{LC} = 0$$

the

$$D = \frac{-R/L}{2} \pm \sqrt{\frac{R^2}{4L^2} - \frac{1}{LC}}$$

$$D = \frac{-R}{2L}, \frac{-R}{2L}$$

$$y = (c_1 + c_2 t) e^{-R/2L}$$

$$= e^{-R/2L} + t e^{-R/2L}$$

④ $\frac{d^2y}{dx^2} + \omega^2 y = 0; \quad y(0) = 0, \quad y(L) = 0.$

a) $y = \sum_n c_n \cos \frac{n\pi x}{L}$

b) $y = \sum_n c_n e^{\frac{n\pi x}{L}}$

~~c)~~ $y = \sum_n c_n \sin \frac{n\pi x}{L}$

d) $y = \sum_n c_n x^{\frac{n\pi}{L}}$

Sol sub $y = 0$ at $x=0$ & $x=L \Rightarrow y=0$.

④ $9y'' - 6y' + y = 0, \quad y(0) = 3, \quad y'(0) = 1$

$$(9D^2 - 6D + 1) y = 0$$

$$D = \frac{1}{3} \pm \frac{\sqrt{36 - 36}}{18}$$

$$D = \frac{1}{3}, \frac{4}{3}$$

$$y = (c_1 + c_2 x) e^{\frac{x}{3}}$$

$$y(0) = 3 \Rightarrow 3 = c_1$$

$$y'(0) = 1 \Rightarrow y' = c_2 e^{\frac{x}{3}} + (c_1 + c_2 x) e^{\frac{x}{3}} \cdot \frac{1}{3}$$

$$\Rightarrow 1 = c_2 + 3c_1$$

$$\Rightarrow c_2 = -8$$

$$y = (3 - 8x) e^{\frac{x}{3}}$$

For what value of λ the DE $(D^2 + \lambda^2)y = 0$

For $\lambda = 0 \Rightarrow y(x) = 0$ will have non-trivial soln.

$$y = (c_1 \cos \sqrt{\lambda}x + c_2 \sin \sqrt{\lambda}x)$$

$$y(0) = 0 \Rightarrow 0 = c_1$$

$$y(\pi) = 0 \Rightarrow 0 = c_2 \sin \pi \sqrt{\lambda}$$

$$\sin \pi \sqrt{\lambda} = 0$$

$$\pi \sqrt{\lambda} = n\pi$$

$$\cancel{x = 2, 4, 6, 8, 10, 12, 14, 16}$$

$$\lambda = 1, 4, 9, 16$$

(a) The complete soln of DE $\frac{d^2y}{dx^2} + p \frac{dy}{dx} + qy = 0$

$$(a) \quad y = c_1 e^{-x} + c_2 e^{-3x}$$

$$D = -1, -3$$

$$(D+1)(D+3)y = 0$$

$$(D^2 + 4D + 3)y = 0$$

$$\frac{d^2y}{dx^2} + \frac{4dy}{dx} + 3y = 0 \quad P = 4, Q = 3.$$

(b) The soln of $y'' + py' + (q+1)y = 0$

$$y'' + 4y' + 4y = 0$$

$$(D+2)^2 y = 0$$

$$D = -2, -2 \Rightarrow y = (c_1 + c_2 x)e^{-2x}$$

(c) $\frac{d^2n}{dx^2} + \frac{-n}{L^2} = 0 \Rightarrow n(0) = k, n(\infty) = 0$

$$(D^2 - \frac{1}{L^2})n = 0$$

$$D = \pm \frac{1}{L}$$

$$y = n(x)$$

$$y = c_1 e^{x/L} + c_2 e^{-x/L}$$

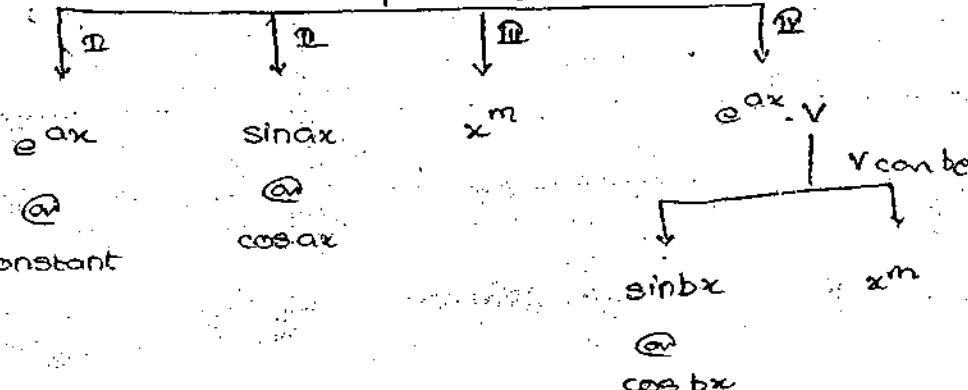
sub. conditions

* Particular integral :-

$$F(D)y = x$$

$$P.I. = \left(\frac{1}{F(D)} \right) x$$

x may be



case (I): $x = e^{ax}$ @.. constant

$$P.I. = \left[\frac{1}{F(D)} \right] e^{ax}$$

replace 'D' by 'a' in $F(D)$

$$\boxed{P.I. = \left[\frac{1}{F(a)} \right] e^{ax}} \quad (F(a) \neq 0)$$

if $F(a) = 0$:-

$$P.I. = x \left[\frac{1}{F'(D)} \right] e^{ax}$$

replace $D \rightarrow a$ in $F'(D)$

$$\boxed{P.I. = x \left[\frac{1}{F'(a)} \right] e^{ax}}$$

if $F'(a) = 0$

$$P.I. = x^2 \left[\frac{1}{F''(a)} \right] e^{ax}$$

④ Find PI of $y'' + 3y' - 2y = e^{2x} + 3$

$$PI = \left[\frac{1}{D^2 + 3D - 2} \right] (e^{2x} + 3)$$

$3 = 3\omega_0^2$

$$= \frac{1}{2^2 + 3(2)^2 - 2} e^{2x} + \frac{3}{0^2 + 3(0)^2 - 2} e^{0x}$$

$$= \frac{e^{2x}}{8} - \frac{3}{2} e^{0x}$$

⑤ PI of $y'' + 5y' + 6y = e^{-3x}$

$$PI = \left[\frac{1}{D^2 + 5D + 6} \right] e^{-3x}$$

(or is 0).

so differentiate.

$$= x \left(\frac{1}{2D+5} \right) e^{-3x}$$

$$= -x e^{-3x}$$

⑥ PI of $y'' + 4y' + 4y = e^{2x}$

$$PI = \left[\frac{1}{D^2 + 4D + 4} \right] e^{-2x} \quad (\text{Dr is } 0)$$

$$= \left(\frac{x}{2D+4} \right) e^{-2x} \quad (\text{Dr is } 0)$$

$$= \frac{x^2}{2!} e^{-2x}$$

case(2) :- $x = \sin ax @ \cos ax$

@ $\sin(ax+b)$ @ $\cos(ax+b)$

$$PI = \left[\frac{1}{F(D)} \right] \sin ax$$

replace D^2 by $-a^2$ in $F(D)$.

$$= \frac{1}{\sin ax}$$

if $F(-\alpha^2) = 0$

$$\text{then } P_1 = x \left[\frac{1}{F'(D)} \right] \sin \alpha x$$

$$P_1 = x \frac{1}{F'(-\alpha^2)} \sin \alpha x$$

④ $\frac{d^2y}{dx^2} + 5y = \cos(3x+2)$

$$P_1 = \left[\frac{1}{D^2 + 5} \right] \cos(3x+2)$$

$$= \frac{1}{-9 + 5} \cos(3x+2)$$

$$\Rightarrow -\frac{\cos(3x+2)}{4}$$

⑤ $y'' + 4y = \sin 2x$

$$P_1 = \left[\frac{1}{D^2 + 4} \right] \sin 2x \quad (\text{or } = 0)$$

$$= \frac{x}{2D} \sin 2x = \frac{x}{2} \cdot \left(\frac{1}{D} \sin 2x \right)$$

$$= \frac{x}{2} \left(-\frac{\cos 2x}{2} \right)$$

don't do integ. on x

only do on $\sin 2x$.

$$= -\frac{x \cos 2x}{4}$$

⑥ $(D^3 + D^2 + 2D + 2)y = \cos x$

$$P_1 = \left[\frac{1}{D^3 + D^2 + 2D + 2} \right] \cos x$$

$$\text{replace } D^2 = -\alpha^2 = -1$$

$$= \frac{1}{D^3 - D - 1 + 2D + 2} \cos x \quad (D = D \cdot D^2)$$

$$= \frac{1}{D^2 + D + 1} \cos x$$

$$= \frac{1}{D(D^2 + 1) + 1} \cos x$$

$$= \frac{1}{D^3 + D + 1} \cos x$$

$$\frac{D-1}{(D^2-1)} \cos x = \frac{(D-1)}{-2} \cos x$$

$$= \frac{1}{2} (\cos x + D(\cos x))$$

$$= \frac{1}{2} [\cos x - \sin x]$$

case : (3) :- $x = x^m$ @ poly. in x (m is +ve).

$$\begin{aligned} P1 &= \left[\frac{1}{F(D)} \right] x^m \\ &= \frac{1}{*} x^m * (1 + \phi(D)) \\ &= \frac{1}{*} [1 + \phi(D)]^{-1} x^m. \end{aligned}$$

(* is the least power in $F(D)$)

④ $\frac{d^2y}{dx^2} + 2y = x^3$

$$P1 = \left[\frac{1}{D^2 + 2} \right] x^3.$$

$$= \frac{1}{2} \left[\frac{1}{1 + 0.5D^2} \right] x^3$$

$$= \frac{1}{2} \left[1 + \frac{D^2}{2} \right]^{-1} x^3.$$

$$= \frac{1}{2} \left[1 - \frac{D^2}{2} + \frac{D^4}{4} \dots \right] x^3.$$

$$= \frac{1}{2} \left[x^3 - 3x + 0 \dots \right] = \frac{x^3 - 3x}{2}$$

⑤ $D^2 + D = x^2 + 2$

$$P1 \approx \left[\frac{1}{D^2 + D} \right] (x^2 + 2)$$

$$\begin{aligned}
 &= \frac{1}{D} \left(1 + \frac{D}{D+2} \right) \\
 &= \frac{1}{D} (1+D)^{-1} (x^2+2) \\
 &= \frac{1}{D} (1-D+D^2)(x^2+2) \\
 &= \frac{1}{D} \left\{ x^2+2 - 2x + 2 \right\} \\
 &= \frac{x^3}{3} + 4x - x^2
 \end{aligned}$$

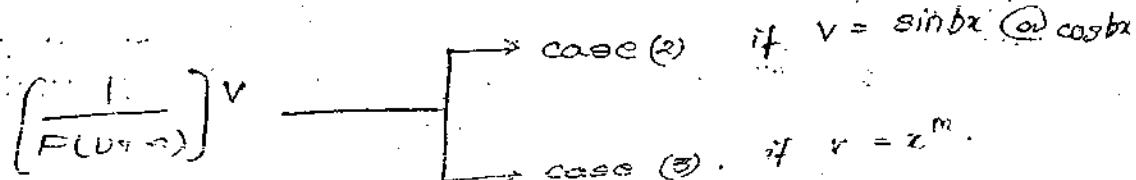
case (4): $x = e^{ax} \cdot v$

($v = \cos bx$ @ $\sin bx$) @ ($v = x^m$ @ poly in x)

$$p_1 = \left[\frac{1}{F(D)} \right] e^{ax} v$$

replace $D \rightarrow 'D+a'$ in $F(D)$

$$= e^{ax} \left[\frac{1}{F(D+a)} \right] v$$



* $\frac{d^2y}{dx^2} + 3y = e^x \sin 2x$

$$p_1 = \left[\frac{1}{D^2+3} \right] e^x \sin 2x$$

$$= e^x \left[\frac{1}{(D+1)^2+3} \right] \sin 2x$$

$$= e^x \left[\frac{1}{D^2+2D+4} \right] \sin 2x$$

$$= \frac{e^x}{2} \left(-\frac{\cos 2x}{2} \right)$$

$$= -\frac{e^x \cos 2x}{4}$$

④ $\frac{d^2y}{dx^2} - 4y = \cos^2 x$

$$F(D) = D^2 - 4 = 0 \quad D = \pm 2$$

$$CF = C_1 e^{2x} + C_2 e^{-2x}$$

$$PI = \frac{1}{(D^2 - 4)} \cos^2 x = \frac{1}{2} \left[\frac{1}{D^2 - 4} \right] (1 + \cos 2x)$$

$$= \frac{1}{2} \left[\frac{1}{-4} \right] + \frac{1}{2} \left[\frac{1}{-4+4} \right] \cos 2x$$

$$PI = \frac{-1}{8} - \frac{1}{16} \cos 2x$$

$$y = C_1 e^{2x} + C_2 e^{-2x} - \frac{1}{8} - \frac{1}{16} \cos 2x.$$

2. costbx
⑤ The PI of $\frac{d^2y}{dx^2} + a^2y = \sin ax$ is

$$PI = \frac{1}{D^2 + a^2} \sin ax = \frac{x}{2a} \sin ax$$

$$= \frac{-x}{2a} \cos ax.$$

⑥ The PI of $\frac{d^2y}{dx^2} + 4y = \sin 2x + \cos 3x$ is

$$(Ax \cos 2x + B \frac{\sin 3x}{3}) \quad A, B = \frac{1}{2}$$

$$(PI)_1 = \frac{x}{20} \sin 2x \quad (PI)_2 = \frac{1}{-5} \cos 3x$$

$$\textcircled{4} \quad (D-2)^3 y = x e^{2x}$$

$$D = 2, 2, 2$$

$$CF = (c_1 + c_2 x + c_3 x^2) e^{2x}$$

$$PI = \frac{1}{(D-2)^3} x e^{2x}$$

$$= e^{2x} \cdot \frac{1}{((D+2)-2)^3} x$$

$$= e^{2x} \cdot \frac{1}{D^3} x$$

$$= e^{2x} \cdot \frac{1}{2} \cdot \frac{1}{3} \cdot \frac{x^4}{4}$$

$$y = (c_1 + c_2 x + c_3 x^2) e^{2x} + \frac{x^4 e^{2x}}{24}$$

$$\textcircled{5} \quad y'' - 2y' + y = x-1$$

$$(D^2 - 2D + 1) = 0$$

$$(D-1)^2 = 0 \quad D = 1$$

$$CF = (c_1 + c_2 x) e^x$$

$$PI = \frac{1}{(D^2 - 2D + 1)} (x-1)$$

$$= (1 + D^2 - 2D)^{-1} (x-1)$$

$$= (1 + (D^2 - 2D)) (x-1)$$

$$PI = (x-1) + 2 = x+1$$

\textcircled{6}

$$\frac{dy}{dx^2} = e^x \cos x$$

$$P_1 = \frac{1}{D^2} e^x \cos x.$$

$$= e^x \frac{1}{(D+1)^2} \cos x.$$

$$= e^x \left[\frac{1}{D^2 + 2D + 1} \right] \cos x = \frac{e^x}{2} \sin x.$$

② $\frac{d^2y}{dx^2} + y = x$; at $x=0, y=1$
 $x=\pi/2, y=\pi/2$

$$D^2 + 1 = 0$$

$$D = \pm i$$

$$CF = (C_1 \cos x + C_2 \sin x)$$

$$P_1 = \frac{1}{D^2 + 1} x$$

$$= (1 + D^2)^{-1} x$$

$$= (1 - D^2)^{-1} x \Rightarrow x = 0 = x$$

$$y = C_1 \cos x + C_2 \sin x + x$$

$$x=0, y=1 \Rightarrow 1 = C_1$$

$$x=\pi/2, y=\pi/2 \Rightarrow \frac{\pi}{2} = C_2 + \pi/2 \Rightarrow C_2 = 0$$

$$y = \cos x + x$$

③ $y'' - 3y' + 2y = \cosh x$

$$= e^x + e^{-x}$$

$$D^2 - 3D + 2 = 0 \Rightarrow D^2 - 2D - D + 2 = 0$$

$$D = 1, 2$$

$$CF = C_1 e^x + C_2 e^{2x}$$

$$P_1 = 1 \int e^x + 1 \int e^{-x}$$

$$\textcircled{*} \quad y'' - 3y' + 2y = e^x ; \quad y = 3 \quad \text{&} \quad \frac{dy}{dx} = 3 \quad \text{at } x=0$$

$$D^2 - 3D + 2 = 0$$

$$D = 1, 2$$

$$CF = c_1 e^x + c_2 e^{2x}$$

$$P.I. = \left[\frac{1}{D^2 - 3D + 2} \right] e^x$$

$$= -xe^x.$$

$$y = c_1 e^x + c_2 e^{2x} - xe^x$$

$$y' = c_1 e^x + 2c_2 e^{2x} - e^x(x+1)$$

$$x=0, y=3 \Rightarrow 3 = c_1 + c_2$$

$$x=0, y'=3 \Rightarrow 3 = c_1 + 2c_2 - 1$$

$$c_2 - 1 = 0$$

$$c_2 = 1, \quad c_1 = 2$$

\Rightarrow Cauchy's homogenous D.Eqⁿ :-

$$x^n \frac{d^n y}{dx^n} + k_1 x^{n-1} \frac{d^{n-1} y}{dx^{n-1}} + \dots + k_{n-1} x \frac{dy}{dx} + k_n y = 0$$

k_1, k_2, \dots are constants.

$x = e^t$ x is function of t .

it reduces to linear DE with constant coeff.

$$\frac{dy}{dx} = D_1 y = \frac{dy}{dt}$$

$$x^2 \frac{d^2 y}{dx^2} = D_1(D_1 - 1)y$$

$$x^3 \frac{d^3 y}{dx^3} = D_1(D_1 - 1)(D_1 - 2)y$$

$$(D_1^2 + D_1 + 1)y = 4 \cos t$$

$$\frac{dy}{dx}$$

$$P_1 = \left[\frac{1}{D_1^2 + D_1 + 1} \right] 4 \cos t$$

$$= 4 \left[\frac{1}{D_1^2 + D_1 + 1} \cos t \right]$$

$$= 4 \sin t,$$

$$(D_1(D_1 - 1) + D_1 + 1)y = 4 \cos t$$

$$(D_1^2 + 1)y = 4 \cos t$$

$$P_1 = 4 \left(\frac{1}{D_1^2 + 1} \right) 4 \cos t$$

$$= 2t \sin t$$

$$= 2 \log(1+x) \sin(\log(1+x)).$$

⇒ Method of variation of parameters :-

This is a method to find the P1

of

$$\boxed{\frac{d^2y}{dx^2} + p \frac{dy}{dx} + qy = R}$$

$$1. \text{ CF} = C_1 y_1 + C_2 y_2$$

$$2. \text{ P1} = A y_1 + B y_2$$

$$A = - \int \frac{R y_2}{\omega} dx, \quad B = \int \frac{R y_1}{\omega} dx$$

$$\omega = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}, \quad y_1' = y_2 - y_1, \quad y_2' = y_1 - y_2$$

$$3. y = \text{CF} + \text{P1}$$

Note :- If P & Q are functions of x then we should know two independent soln y_1, y_2 of the corresponding homogenous eqⁿ
 $y'' + Py' + Qy = 0$ so that we can write CF
 $(CF = c_1 y_1 + c_2 y_2)$

Q) $y'' - 6y' + 9y = \frac{e^{3x}}{x^2}$

$$D^2 - 6D + 9 = 0$$

$$D = 3, 3$$

$$CF = c_1 e^{3x} + c_2 x e^{3x}$$

$$y_1 = e^{3x}, y_2 = x e^{3x}$$

$$W = \begin{pmatrix} e^{3x} & x e^{3x} \\ 3e^{3x} & e^{3x} + 3x e^{3x} \end{pmatrix}$$

$$= e^{6x} + 3x e^{6x} = 3x e^{6x}$$

$$W = e^{6x}$$

$$A = - \int \frac{e^{3x}}{x^2} \cdot x e^{3x} dx = - \int \frac{1}{x} dx = -\log x$$

$$B = + \int \frac{e^{3x}}{x^2} \cdot \frac{e^{3x}}{e^{6x}} dx = \frac{1}{x}$$

$$P_I = -\log x e^{3x} - \frac{1}{x} x e^{3x}$$

$$= -e^{3x} (\log x + 1)$$

The P.I. of $\frac{d^2y}{dx^2} + 4y = \sec^2 2x$ is $Ay_1 + By_2$

where $y_1 = \cos 2x, y_2 = \sin 2x$ find A & B

$$\textcircled{4} \quad x^2 \frac{d^2y}{dx^2} - 3x \frac{dy}{dx} + 4y = 0$$

$$\text{Sub. } x = e^t \Rightarrow \log x = t$$

$$(D_1(D_1-1) - 3D_1 + 4)y = 0$$

$$(D_1^2 - 4D_1 + 4)y = 0$$

$$D_1 = 2, 2$$

$$y = (c_1 + c_2 t) e^{2t}$$

$$y = (c_1 + c_2 \log x) x^2$$

$$\textcircled{5} \quad \text{Find } P_1 \text{ of } x^2 y'' - xy' + 3y = x^2 \log x$$

$$\text{Sub. } x = e^t \Rightarrow \log x = t$$

$$(D_1(D_1-1) - D_1 + 3)y = x^2 e^{2t} \cdot t$$

$$(D_1^2 - 2D_1 + 3)y = t^2 e^{2t}$$

$$D_1 = -1, 3$$

$$\begin{aligned} & -3 \\ & D^2 - 2D + 3 \\ & D(D-1)+3 \end{aligned}$$

$$P_1 = \left\{ \frac{1}{D_1^2 - 2D_1 + 3} \right\} t e^{2t}$$

$$= e^{2t} \left[\frac{1}{(D_1+2)^2 - 2(D_1+2) + 3} \right] t$$

$$= e^{2t} \left[\frac{1}{D_1^2 + 2D_1 + 3} \right] t$$

$$= \frac{e^{2t}}{3} \left[1 - \left(\frac{D_1^2}{3} + \frac{2D_1}{3} \right) \right] t$$

$$= \frac{e^{2t}}{3} \left[t - \frac{2}{3} \right]$$

$$\textcircled{6} \quad P_1 = \frac{x^2}{3} \left[\log x - \frac{2}{3} \right]$$

Legendre's eqⁿ :-

$$(a+bx)^n \frac{d^n y}{dx^n} + k_1 (a+bx)^{n-1} \frac{d^{n-1} y}{dx^{n-1}} + \dots + k_{n-1} (a+bx) \frac{dy}{dx} + k_n y = x.$$

$(a+bx) = e^t \downarrow$

Linear DE with const coef.

$$(a+bx) \frac{dy}{dx} = bD_1 y$$

$$t = \log(a+bx)$$

$$(a+bx)^2 \frac{d^2 y}{dx^2} = b^2 D_1 (D_1 - 1)y$$

$$(a+bx)^3 \frac{d^3 y}{dx^3} = b^3 D_1 (D_1 - 1)(D_1 - 2)y$$

$$D_1 = \frac{d}{dt}, \quad D_t^2 = \frac{d^2}{dt^2}$$

$$(1+2x)^2 y'' - 6(1+2x)y' + 16y = 0$$

$$4D_t(D_1 - 1) - 6(2)D_1 + 16 = 0$$

$$4D_t^2 - 8D_1 + 16 = 0 \quad (1+2x) = e^{2t}$$

$$D_1^2 - xD_1 + 4 = 0$$

$$D_1 = 2, 2$$

$$CF = (C_1 + C_2 t) e^{2t}$$

$$\cancel{D_1} = \cancel{(1+2x)}$$

$$CF = \left[C_1 + C_2 \log(1+2x) \right] (1+2x)^2$$

$$P.I. \text{ of } (1+x^2)^2 y'' + (1+x)y' + y = 4 \cos(\log(1+x))$$

$$(1+x) = e^t$$

D Res. of $f(z) = \frac{1}{(z^2+1)^2}$ @ $z = i$ is

$$f(z) = \frac{1}{(z+i)^2(z-i)^2} \rightarrow \text{At } z=i \quad \frac{d}{dz} \left\{ (z-i)^2 \times \frac{1}{(z+i)^2(z-i)^2} \right\}$$

$$\text{At } z=i \quad \frac{-2}{(z+i)^3} \Rightarrow \frac{-2}{(2i)^3} = \frac{-2}{8i^3} = \frac{1}{4i}$$

* f(z) = $\frac{z^2}{(z-1)^2(z+2)}$ calculate res. at each of the poles.

$$z = -1, z = -2$$

$$\text{Res at } z=1 \rightarrow \text{At } z=1 \quad \frac{d}{dz} \left\{ (z-1)^2 \frac{z^2}{(z-1)^2(z+2)} \right\}$$

$$\Rightarrow \text{At } z=1 \quad \frac{d}{dz} \left[\frac{z^2}{z+2} \right] \Rightarrow \text{At } z=1 \quad \left[\frac{2z}{z+2} - \frac{z^2}{(z+2)^2} \right]$$

$$= \frac{2}{3} - \frac{1}{9} = \frac{6-1}{9} = \frac{5}{9}$$

$$\text{Res at } z=-2 \rightarrow \text{At } z=-2 \quad \frac{(z+2)}{(z+2)^2(z+2)} \Rightarrow \frac{4}{9}$$

D Res. of $f(z) = \frac{1-2z}{z(z-1)(z-2)}$ at its poles

- a) $1/2, -1/2, 1$ b) $1/2, 1/2, -1$ ~~c) $1/2, 1, -3/2$~~ d) $1/2, -1, 3/2$

$$\text{At } z \rightarrow 0 \quad \text{At } z=0 \quad \frac{1-2z}{(z-1)(z-2)} = \frac{1}{2}$$

$$\text{At } z \rightarrow 1 \quad \text{At } z=1 \quad \frac{1-2z}{z(z-2)} = \frac{-1}{-1} = 1$$

$$\text{At } z \rightarrow 2 \quad \text{At } z=2 \quad \frac{1-2z}{z(z-1)} = \frac{-3}{2}$$

$$\textcircled{4} \quad f(z) = \frac{1}{(z+2)^2(z-2)^2} \quad \text{at } z=2 \text{ is}$$

$$\lim_{z \rightarrow 2} \frac{d}{dz} \left\{ (z-2)^2 \times \frac{1}{(z+2)^2(z-2)^2} \right\} \rightarrow \lim_{z \rightarrow 2} \frac{-2}{(z+2)^3} = \frac{-2}{64} = -\frac{1}{32}$$

Cauchy's Residue Theorem:

$f(z)$ is analytic in a closed curve c except at a finite no. of points, then $\int_C f(z) dz = 2\pi i \{ \text{sum of residues } f(z) \text{ at each of poles} \}$

$$\begin{aligned} \textcircled{5} \quad & \oint_C \frac{1}{(z+2)^2(z-2)^2} dz \quad |z|=5 \\ & = 2\pi i [\text{Res}(2) + \text{Res}(-2)] \\ & = 2\pi i \left[\lim_{z \rightarrow 2} \frac{d}{dz} \frac{1}{(z+2)^2} + \lim_{z \rightarrow -2} \frac{d}{dz} \frac{1}{(z-2)^2} \right] \\ & = 2\pi i \left[\lim_{z \rightarrow 2} \frac{-2}{(z+2)^3} + \lim_{z \rightarrow -2} \frac{-2}{(z-2)^3} \right] = 2\pi i \left[\frac{-2}{64} + \frac{2}{64} \right] = \underline{\underline{0}} \end{aligned}$$

$$\textcircled{6} \quad \oint_C \frac{e^z}{z^2+1} dz \quad \text{where } c \text{ is the region } |z|=2$$

$$\begin{aligned} \oint_C \frac{e^z}{(z-i)(z+i)} dz & = 2\pi i \{ \text{Res}(i) + \text{Res}(-i) \} \\ & = 2\pi i \left\{ \lim_{z \rightarrow i} \frac{e^z}{z+i} + \lim_{z \rightarrow -i} \frac{e^z}{z-i} \right\} \\ & = 2\pi i \left\{ \frac{e^i}{2i} + \frac{e^{-i}}{-2i} \right\} = \pi [e^i - e^{-i}] \end{aligned}$$

$$\textcircled{7} \quad \oint_C \frac{z^2+1}{z(az+i)} dz \quad |z|=1$$

$$\begin{aligned} \frac{1}{a} \oint_C \frac{z^2+1}{z(z+\frac{i}{a})} dz & = \frac{2\pi i}{2} \{ \text{Res}(0) + \text{Res}(-\frac{i}{a}) \} \\ & = \pi i \left\{ \lim_{z \rightarrow 0} \frac{z^2+1}{z+\frac{i}{a}} + \lim_{z \rightarrow -\frac{i}{a}} \frac{z^2+1}{z} \right\} \\ & = \pi i \left\{ 2 + \frac{-5}{2} \right\} = \underline{\underline{-\frac{7\pi i}{2}}} \end{aligned}$$

Graph Theory

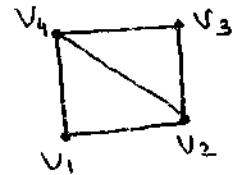
- **Graph** :- A graph G is defined by $G = (V, E)$ where

V = set of all vertices in G

E = set of all edges in G

$|V|$ = no. of vertices in G = order of G

$|E|$ = no. of edges in G = size of Graph



Nondirected (Undirected) graph

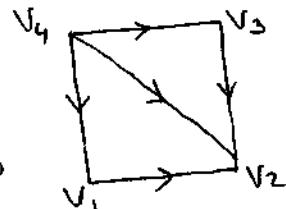
- In a nondirected graph, an edge is represented by set of two vertices

$\{v_i, v_j\}$ = An edge betⁿ v_i & v_j

Directed Graph :- (Diagraph)

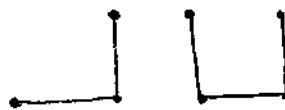
- In directed graph, an edge is represented by an ordered pair of two vertices.

(v_i, v_j) = An edge from v_i to v_j



Connected Graph :-

- A graph is said to be connected if there exist a path betⁿ every pair of vertices.
- The graph which is not connected will have 2 or more connected components.
- In a graph two vertices are said to be adjacent if there exist a path edge betⁿ the two vertices.
- Two edges are said to be adjacent if there is a common vertex for the two edges.



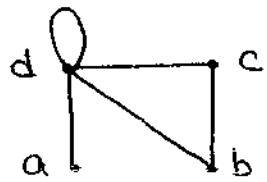
NULL GRAPH :-

- The graph with no edges is called Null graph / Empty graph

TRIVIAL GRAPH :-

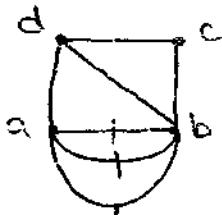
- The graph with one vertex and no edges

Loop :- An edge is drawn from a vertex to itself.

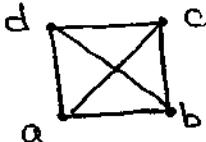


Parallel edges (Multiple edges) :-

- In a graph if a pair of vertex is allowed to join by more than 1 edge then those edges are called parallel edges and resulting graph is called a multigraph.



Simple Graph :- The graph with no loops and no parallel edges is called Simple Graph.



- Maximum no. of edges possible in a simple graph with n vertices = $\frac{n(n-1)}{2}$

$${}^6C_0 + {}^6C_5 + {}^6C_4 + {}^6C_3 + {}^6C_2 + {}^6C_1 + {}^6C_0 = 2^6$$

- No. of simple graphs possible with n vertices = $\frac{n(n-1)}{2}$

simple graphs

Ex: Max. no. of edges possible in a simple graph with 5 vertices and 3 edges is —

$$\rightarrow \text{Max. no. edges} = C(5, 2) = 10 \quad \left\{ \because \frac{n(n-1)}{2} = \frac{10 \times 2}{2} = 10 \right\}$$

$$\text{Req. no. Graphs} = C(10, 3)$$

$$= 120$$

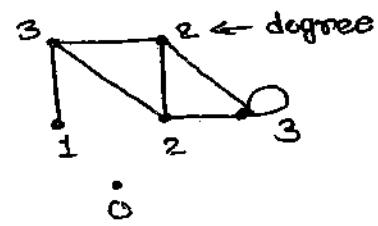
* No. of simple graphs possible with n vertices and m edges

$$= \frac{n(n-1)}{2} C_m$$

$$= C\left(\frac{n(n-1)}{2}, m\right)$$

* Degree of a vertex $v = \deg(v) =$ no. of edges incident with v

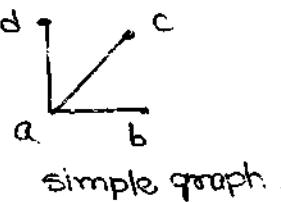
- In nondirected graph the loop at vertex is counted as two edges by writing degree of that vertex



* In a simple graph with n vertices, degree of any vertex $v = \deg(v) \leq (n-1)$ if $v \in G$

- In directed graph, indegree of a vertex is $\deg^+(v) =$ no. of edges incident to the vertex

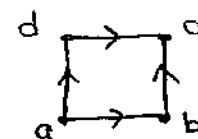
$$\deg^+(d) = 1$$



$$\text{outdegree} = \deg^-(v)$$

= no. of edges incident from the vertex

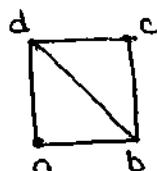
$$\deg^-(v) = \deg^-(d) = 1$$



* $\delta(G) =$ Minimum of the degrees of all vertices in G .

$$\delta(G) = \{2, 3, 2, 3\}$$

$$= 2$$



* $\Delta(G) =$ Max. of the degrees of all vertices in G

$$\Delta(G) = 3$$

* Degree Sequence :-

- If the degrees of all vertices in G are arranged in descending order then the seq. so obtained is called Degree seq. of the G .

$$D.S. = \{3, 3, 2, 2\}$$

* Regular Graph :-

- If all the vertices have same degree then the graph is called as Regular Graph.

- If the degree of each vertex is k then the graph is called as k - Regular graph.

- Every polygon is two Regular Graph.



2-regular



3-regular

Complete Graph :- In a simple graph with n mutually adjacent vertices is called complete graph.

- denoted by ' K_n '.

Ex:-

K_2



K_3



K_4



K_4



K_5

- Every complete graph is a regular graph but every regular graph need not be complete.

- A complete graph is a simple graph with max. no. of edges.

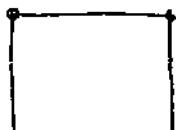
- No. of edges in $K_n = \frac{n(n-1)}{2}$

- Degree of each vertex = $(n-1)$

Cycle Graph :- A simple graph G with n vertices ($n \geq 3$) and n edges, is called a cycle graph, if all the edges form cycle of length n .



C_3



C_4

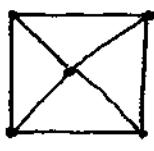


C_5

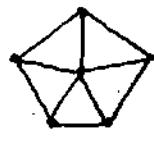
Wheel Graph :- A wheel graph with n vertices ($n \geq 4$) can be formed from a cycle graph C_{n-1} , by adding a new vertex (hub) which is adjacent to all vertices of C_{n-1} .



W.G.



W.G.



W.G.

- Number of edges in $W_n = 2(n-1)$

Cyclic Graph :- A simple graph with atleast one cycle is called a cyclic graph.



Acyclic Graph :- A simple graph with no cycles is called Acyclic graph.

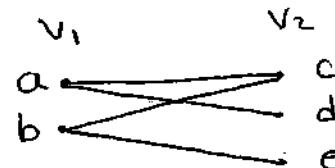


Tree : A connected graph with no cycle is called a tree

- * A tree with n vertices has $(n-1)$ edges.
- * Every tree has atleast two vertices of degree 1.

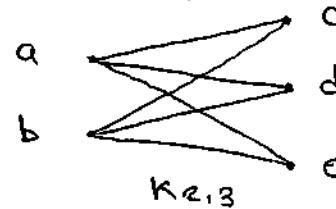
Bipartite Graph :- A simple graph $G = (V, E)$ with vertex partition $\{V_1, V_2\}$ is said to be a Bipartite graph, if every edge of G join a vertex in V_1 to a vertex in V_2 .

$$V = \{a, b, c, d, e\}$$



Complete Bipartite Graph :- A bipartite graph $G = \{V, E\}$ with vertex partition $\{V_1, V_2\}$ is said to be complete bipartite graph, if every vertex in V_1 is adjacent to every vertex in V_2 .

- If $|V_1| = m$ and $|V_2| = n$
then a complete bipartite graph from V_1 to V_2 is denoted by $K_{m,n}$



Note :- In general, A complete bipartite graph is not a complete graph.

- $K_{m,n}$ is a complete graph $\Leftrightarrow m = n = 1$

\longleftrightarrow (complete graph as well as $K_{1,1}$ & K_2 complete bipartite graph)

- $K_{m,n}$ has (mn) vertices and mn edges.
- Max. no. of edges possible in bipartite graph with n vertices is

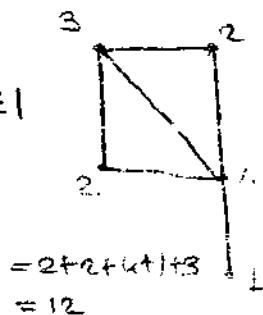
$$\begin{aligned}
 n &= 9 \\
 K_{5,4} &\rightarrow 20 \\
 K_{6,3} &\rightarrow 18
 \end{aligned}
 \quad \left\lfloor \frac{81}{4} \right\rfloor = \underline{\underline{20}}$$

Sum of degrees theorem :-

i.e. if $G = (V, E)$ be a non directed graph with

$$V = \{v_1, v_2, \dots, v_n\} \text{ then } \sum_{i=1}^n \deg(v_i) = 2 \cdot |E|$$

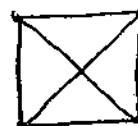
$$\begin{aligned}
 \deg(v) &= 2 \times 6 \\
 &= 12
 \end{aligned}$$



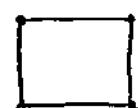
Corollary 1 : Let $G = (V, E)$ be a directed graph with $V = \{v_1, v_2, \dots, v_n\}$ then

$$\sum_{i=1}^n \deg^+(v_i) = \sum_{i=1}^n \deg^-(v_i) = |E|$$

Corollary 2 : In a nondirected graph, no. of vertices with odd degree is always even no. of vertices.



no. of vertices with odd degree = 4 (Even)



no. of vertices with odd degree = 0 (Even)

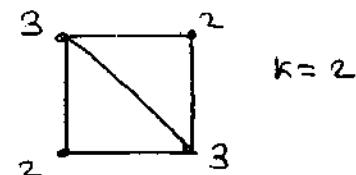
Corollary 3 : If G is a nondirected graph with degree of each vertex k , then $k \cdot |V| = 2|E|$

Corollary 4 : If G is a nondirectional graph with degree of each vertex atleast k ($\geq k$) then

$$k \cdot |V| \leq 2|E|$$

$$\therefore 2 \times 4 \leq 2 \times 5$$

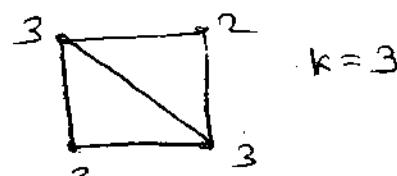
$$8 \leq 10$$



Corollary 5 : If G is a non directed graph with degree of each vertex atleast k ($\leq k$) then

$$k \cdot |V| \geq 2|E|$$

$$3 \cdot 4 \geq 2 \times 5$$



Note :- for a nondirected graph G

$$\delta(G) |V| \leq 2|E| \leq \Delta(G) |V|$$

↑

Min. degree

↑

Max. degree

Ex: A simple non directed graph G contains 21 edges, 3 vertices of degree 4, and other vertices are of degree 2. Then $|V| = ?$

$$\rightarrow \sum_{i=1}^n \deg(v_i) = 2|E| = 2 \times 21 = 42$$

$$\Rightarrow 3 \times 4 + (x-3) \times 2 = 42$$

$$2x - 6 = 30$$

$$2x = 36$$

$$\boxed{x = 18}$$

$$\therefore \text{no. of vertices} = |V| = 18$$

Ex: A simple non directed graph G has 34 edges and degrees of each vertex is 4. Then find the $|V| = ?$

$$\rightarrow \sum_{i=1}^n \deg(v_i) = 2 \times 34$$

$$4 \times |V| = 68$$

$$|V| = \frac{68}{4}$$

$$\boxed{|V| = 17}$$

Ex: A simple non directed graph G has 24 edges and degree of each vertex is k. Then X or Z? which of the following is possible no. of vertices?

- Ⓐ 20 Ⓑ 15 Ⓒ 10 Ⓓ 8

→ By corollary 3

$$k \cdot |V| = 2|E|$$

$$|V| = \frac{2 \times 24}{k} \quad (k = 1, 2, 3, 4, 6)$$

$$= \frac{48}{k} = \frac{48}{6} = 8 \quad (48, 24, 16, 12, 8)$$

in options

Ex: Maximum no. of vertices possible in a simple non-directed graph with 35 edges and degree of each vertex is atleast 3 is —

→ By cor. 4

$$k \cdot |V| \leq 2|E|$$

$$\Rightarrow 3 \cdot |V| \leq 2 \cdot 35$$

$$|V| \leq 28 \cdot \frac{3}{2}$$

$$|V| \leq 23$$

Ex: Min. no. of vertices or edges necessary in a simple non-directed graph, with 25 vertices and degree of each vertex is atleast 4 is —

→ By cor. 4

$$k \cdot |V| \leq 2|E|$$

$$4|E| \leq 2|E|$$

$$100 \leq 2|E|$$

$$50 \leq |E|$$

$$\therefore |E| = 50$$

For $k=5$ (atleast 5)

$$k|V| \leq 2|E|$$

$$5|V| \leq 2|E|$$

$$|E| \geq 02.5$$

$$|E| \geq 63$$

Ex: Min. no. of vertices necessary in a simple non directed graph with 13 edges and degree of each vertex is atleast 3 is —

$$\leq 3$$

→ By cor. 5

$$k \cdot |V| \geq 2|E|$$

$$\Rightarrow 3 \cdot |V| \geq 2|E|$$

$$3 \cdot |V| \geq 26$$

$$|V| \geq \frac{26}{3} \Rightarrow |V| \geq 8.66$$

$$|V| \geq 9$$

$$[8\cancel{6}/(X) \cancel{8}/8]$$

Ex: Which of the following degree sequences represent a simple non directed graph?

a) $\{2, 3, 3, 4, 4, 5\} \rightarrow \text{sum of degrees} = 21 \neq \text{even}$

(OR)

no. of vertices with odd degrees = 3 (not even)

\therefore not represent a simple non-directed graph.

b) $\{2, 3, 4, 4, 5\} \rightarrow \text{sum of degrees} = 18 = \text{even}$

and no. of vertices with odd degrees = 2 = Even

But it having 5 vertices and degree of each vertex must be ≤ 4 .

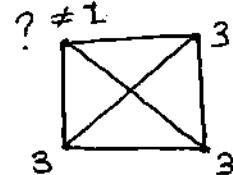
\therefore It is not simple non directed graph.

c) $\{3, 3, 3, 1\} \rightarrow \text{sum of degrees} = 10 = \text{even}$

and no. of vertices with odd degree = 4 = even

But if 3 vertices having 3 degree then remaining vertex cannot have degree 1

\therefore It is not simple graph.



d) $\{1, 3, 3, 4, 5, 6, 6\} \rightarrow \text{sum of degree} = 28$

and no. of vertices with odd degree = 4

But it cannot represent simple non directed graph because in simple graph with 7 vertex it have two vertices with degree 6 then vertex with degree 1 is not possible.

e) $\{0, 1, 2, \dots, n-1\}$

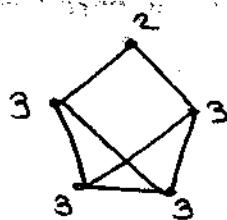
$v_1, v_2, v_3, \dots, v_n$

Simple graph with n vertices can not represent simple graph because a simple graph with n vertices we have vertex with degree $n-1$ then vertex with degree 0 is not possible.

* In a simple graph with $n \geq 2$ at least two vertices should have same degree.

f) $\{2, 3, 3, 3, 3\}$
 a b c d e

→ Simple Graph.



Havel - Hakimi result

Consider the degree sequences s_1 and s_2 , and assume that s_1 is in descending order.

$s_1) \{5, t_1, t_2, \dots, t_s, d_1, d_2, \dots, d_m\}$

$s_2) \{t_1-1, t_2-1, \dots, t_{s-1}-1, d_1, d_2, \dots, d_m\}$

s_1 is graphic $\Leftrightarrow s_2$ is graphic

Which of the following degree sequences represent a simple non directed graph?

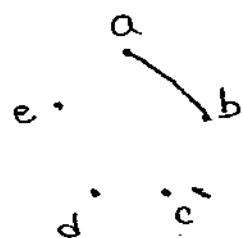
s1) $\{\underline{6, 6, 6, 6, 4, 3, 3, 0}\}$

$\{\underline{5, 5, 5, 3, 2, 2, 0}\}$

$\{\underline{4, 4, 2, 1, 1, 0}\}$

$\{\underline{3, 1, 0, 0, 0}\}$

a b c d e



The last seq. can not be represented by simple graph.

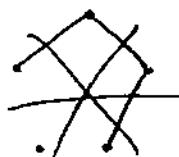
∴ Given seq. also can not be represented by a simple graph.

s2) $\{\underline{6, 5, 5, 4, 3, 3, 2, 2, 2}\}$

~~$\{\underline{6, 4, 3, 2, 2, 1, 1, 2, 2}\}$~~

~~$\{\underline{3, 2, 1, 1, 1, 1, 2, 2}\}$~~

~~$\{\underline{1, 0, 0, 1, 1, 2, 2}\}$~~



= $\{4, 4, 3, 2, 2, 1, 1, 2, 2\}$

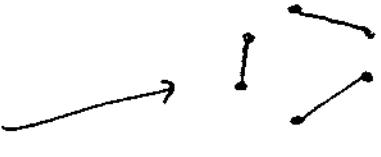
= $\{4, 4, 3, 2, 2, 2, 2, 1\}$

= $\{3, 2, 1, 1, 1, 2, 2, 1\}$

= $\{3, 2, 1, 2, 2, 1, 1, 1, 1\}$

= $\{1, 1, 1, 1, 1, 1, 1\}$

Reordering the Elements.



$$= \{1, 1, 1, 1, 0\}$$

$$= \{0, 1, 1, 0\}$$

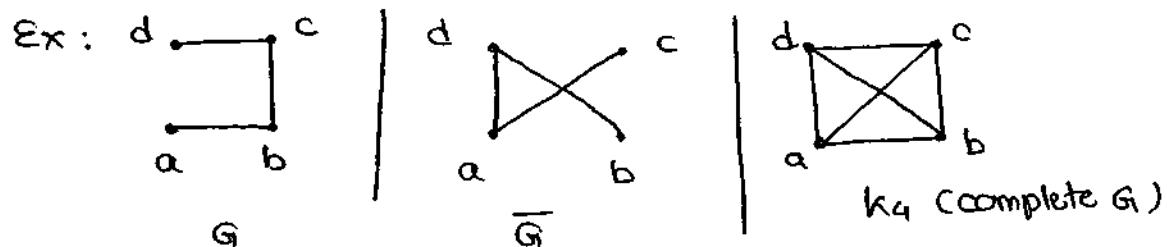
$$= \{1, 1, 0, 0\}$$

$$= \{0, 0, 0\}$$

∴ Given Graph is simple.

Complement of a graph :-

Let G be a simple non directed graph with n vertices. Complement of G , denoted by \bar{G} is a simple non directed graph with same vertices as that of G , and an edge $\{u, v\} \in \bar{G}$ iff $\{u, v\} \notin G$.



$$G \cup \bar{G} = K_n \quad \text{where } n = \text{no. of vertices}$$

$$* |E(G)| + |E(\bar{G})| = |E(K_n)| \quad \text{where } n = |V(G)|$$

Ex: A simple graph G has 10 vertices and 21 edges find no. of edges in \bar{G} ($|E(\bar{G})|$).

→ We have

$$|E(G)| + |E(\bar{G})| = |E(K_{10})|$$

$$21 + |E(\bar{G})| = \frac{n(n-1)}{2} = \frac{10 \times 9}{2} = 45$$

$$|E(\bar{G})| = 45 - 21$$

$$|E(\bar{G})| = 24$$

Ex: A simple graph G has 30 edges and \bar{G} has 36 edges then no. of vertices in G = ?

$$* n(n-1) = (12)(12-1)$$

$$\rightarrow |E(G)| + |E(\bar{G})| = |E(K_n)|$$

$$30 + 36 = \frac{n(n-1)}{2}$$

$$\therefore \boxed{n = 12}$$

Isomorphic Graphs :- Two Graphs G_1 & G_2 are said to be

isomorphic , if there exists a function $f : V(G_1) \rightarrow V(G_2)$
such that i) f is a bijection and
ii) f preserves adjacency

i.e. if $\{u, v\} \in E(G_1)$, then $\{f(u), f(v)\} \in E(G_2)$ then $G_1 \equiv G_2$

Note :- IF $G_1 \equiv G_2$, then

i) $|V(G_1)| = |V(G_2)|$

ii) $|E(G_1)| = |E(G_2)|$

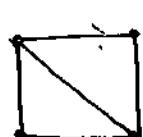
iii) Degree sequences of G_1 & G_2 are same .

iv) IF $\{v_1, v_2, \dots, v_k\}$ form a cycle in G_1 , then $\{f(v_1), f(v_2), f(v_3), \dots, f(v_k)\}$ should form a cycle in G_2 .

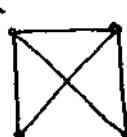
Result : $\boxed{G_1 \equiv G_2}$ iff $\overline{G}_1 \equiv \overline{G}_2$

- $(G_1 \equiv G_2)$ if the adjacency matrices of G_1 and G_2 are same
- $(G_1 \equiv G_2)$ iff the corresponding subgraphs (obtained by deleting a vertex in G_1 and it's image in G_2) are isomorphic .

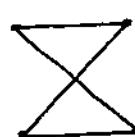
Ex : Which of the following graphs are isomorphic ?



G_1



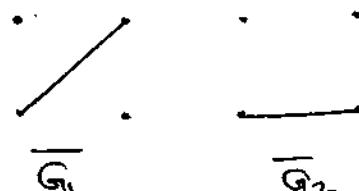
G_2



G_3

→ Graph G_3 has only 4 edges $\therefore G_3$ is not isomorphic to G_1 / G_2 .

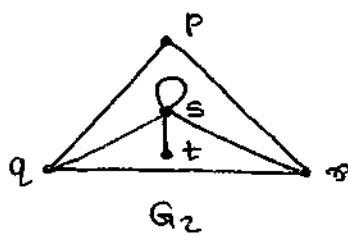
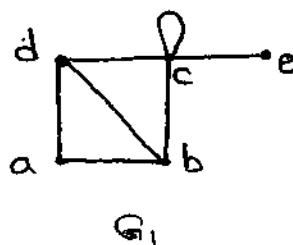
Now for G_1 & G_2



$$\overline{G}_1 \equiv \overline{G}_2$$

$$\therefore G_1 \equiv G_2$$

Ex: Find whether the following graphs are isomorphic?

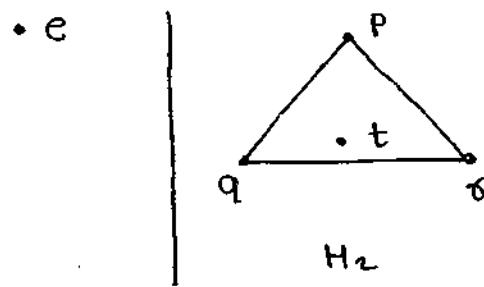
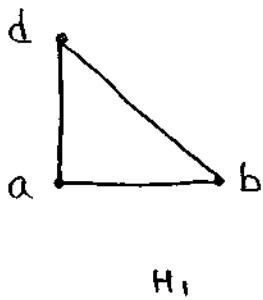


→ If $G_1 \cong G_2$,

Image of $C = S$

Further, c and s have similar neighbours.

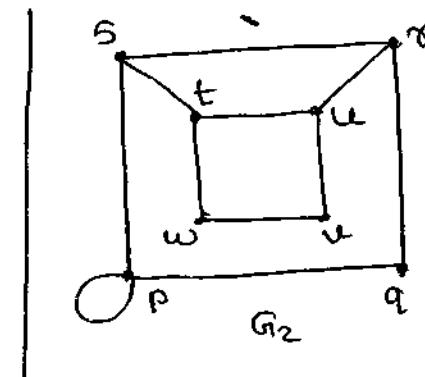
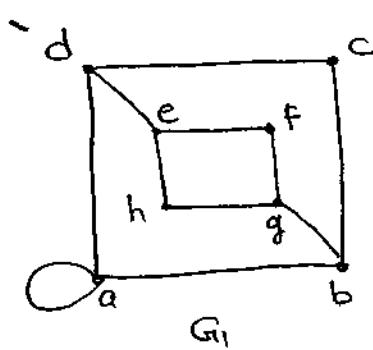
Deleting c and s from G_1 & G_2 we get,



Hence, $H_1 \cong H_2$

∴ $G_1 \cong G_2$

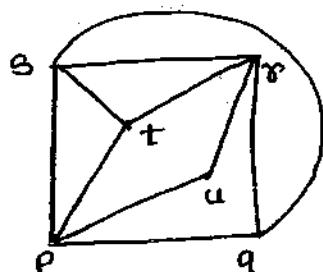
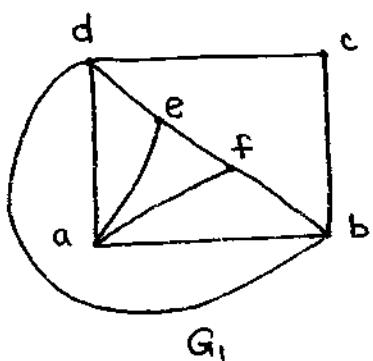
Ex: find whether the following graphs are isomorphic?



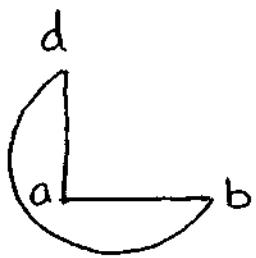
→ In G_2 all vertices form the cycle C_8 whereas in G_1 , there is no such cycle

∴ $G_1 \not\cong G_2$

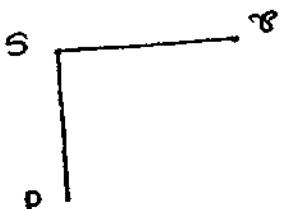
Ex: Find whether following graphs are isomorphic?



→ consider vertices with degree 4



(form cycle)



G_2
(Not cycle)

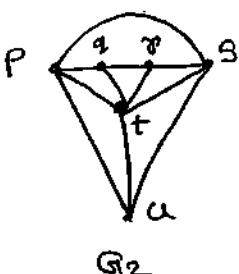
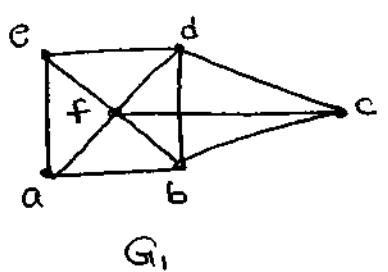
Comparing vertices of degree 4 we have in G_1 vertices form a cycle but in G_2 not.

$$\therefore G_1 \not\cong G_2$$

Comparing vertices of degree 3 we have in G_1 two vertices of degree 3 are adjacent whereas in G_2 are not.

$$\therefore G_1 \not\cong G_2$$

Ex: Find whether the following graphs are isomorphic?

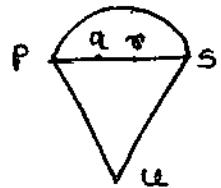
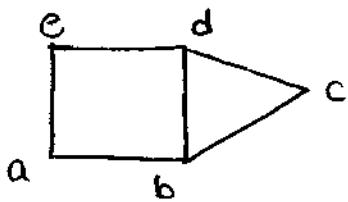


→ $G_1 \equiv G_2$ since Image of $f = t$

The vertices f & t has similar neighbours

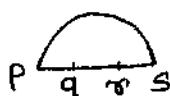
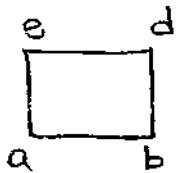
Deleting f & t from corresponding graphs

We get following,



$$G_{11} \equiv G_{21}$$

Image of $c = u$ \therefore Deleting c & e we get

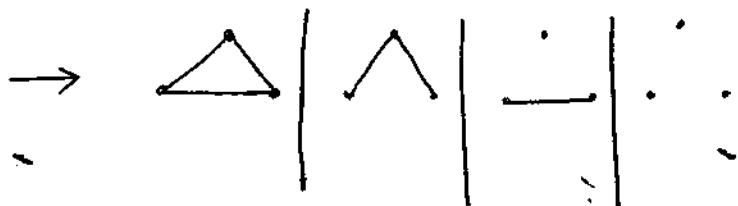


$$G_{111} \equiv G_{211}$$

$$\therefore G_1 \equiv G_2$$

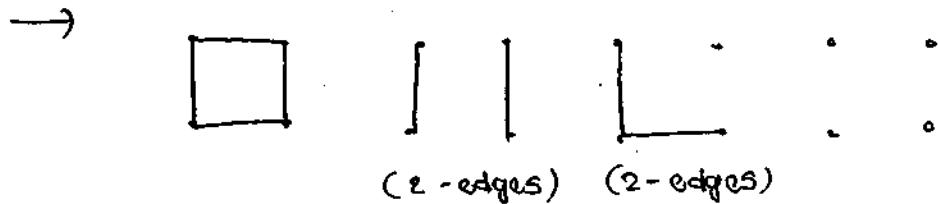
Ex : How many simple non isomorphic graphs (pairwise) are possible with 3 vertices ?

- a) 2 b) 3 c) 4 d) 6



Ex : How many simple non isomorphic graphs (pairwise) are possible with 4 vertices and 2 edges ?

- a) 2 b) 3 c) 4 d) 6

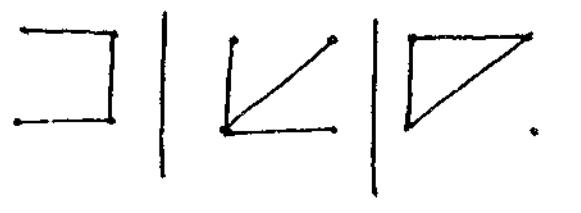


Two edges may be adjacent or non adjacent.

Ex: —ii— with 4 vertices and 3 edges?

- a) 2 b) 3 c) 4 d) 6

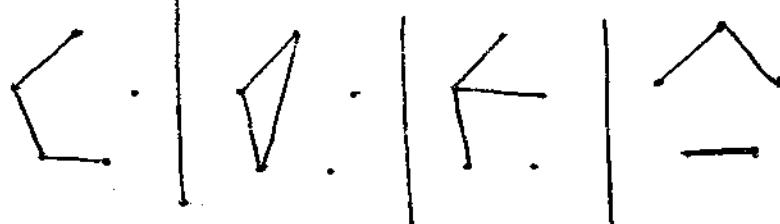
→



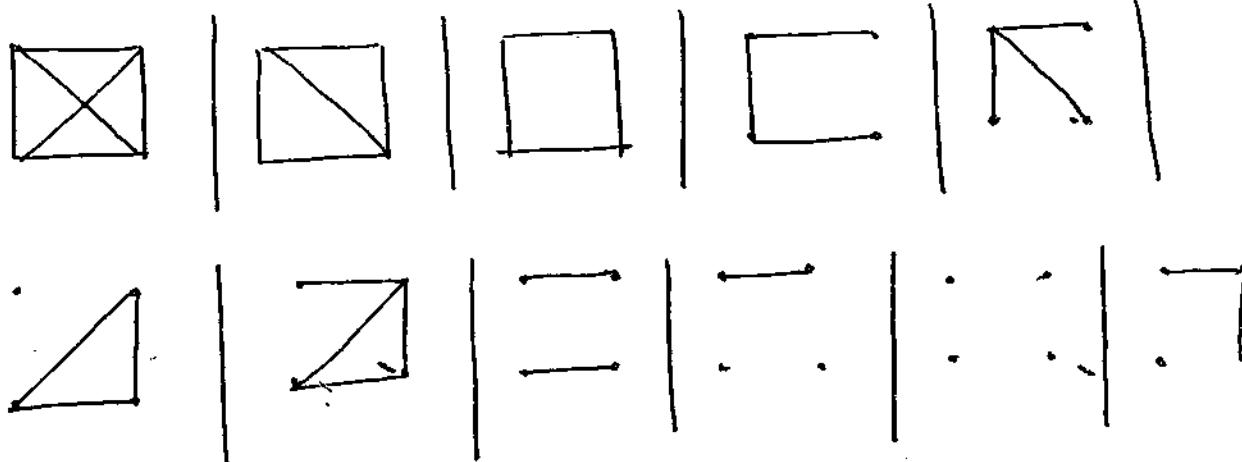
Ex: —ii— with 5 vertices and 3 edges?

- a) 2 b) 3 c) 4 d) 6

→



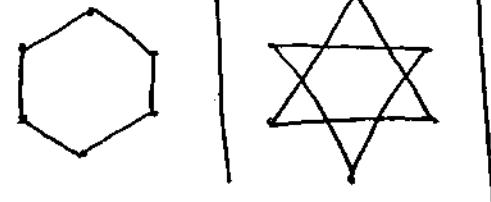
Ex: —ii— 4 vertices?



⇒ Ans = 11

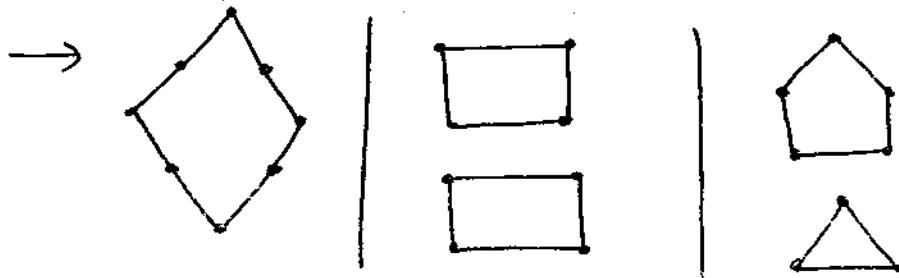
Ex: How many simple non isomorphic graphs (pairwise) are possible with 6 vertices, 6 edges and degree of each vertex is 2?

→



Ans : 2

Ex: $\text{---} \parallel \text{---}$ with 8 vertices , 8 edges and degree is 2 ?



Ans = 3

Ex: $\text{---} \parallel \text{---}$ with 10 vertices , 10 edges and degree is 2 ?

→

| | | | | |
|----------|-------|-------|-------|-------|
| C_{10} | C_5 | C_6 | C_7 | C_4 |
| | C_5 | C_4 | C_3 | C_3 |

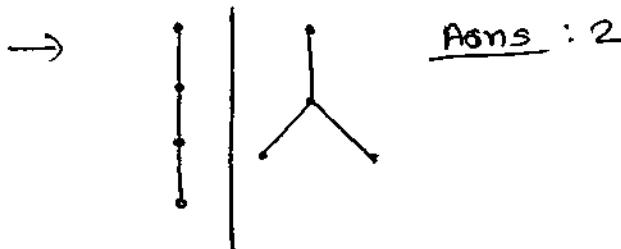
Ans = 5

Ex: How many simple non isomorphic trees (pairwise) are possible with 3 vertices ?



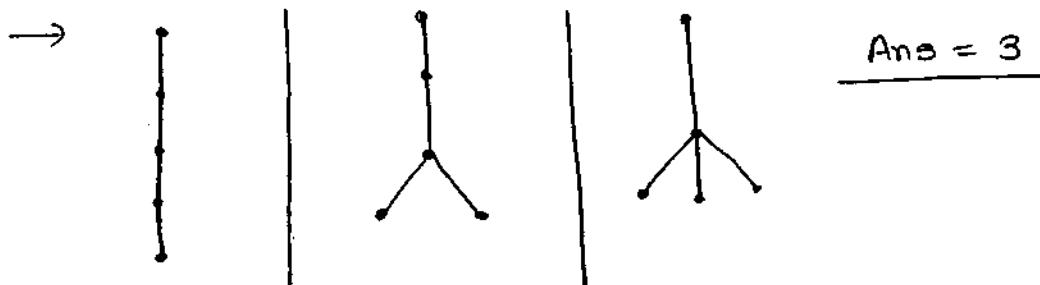
Ans = 1

Ex: $\text{---} \parallel \text{---}$ with 4 vertices ?



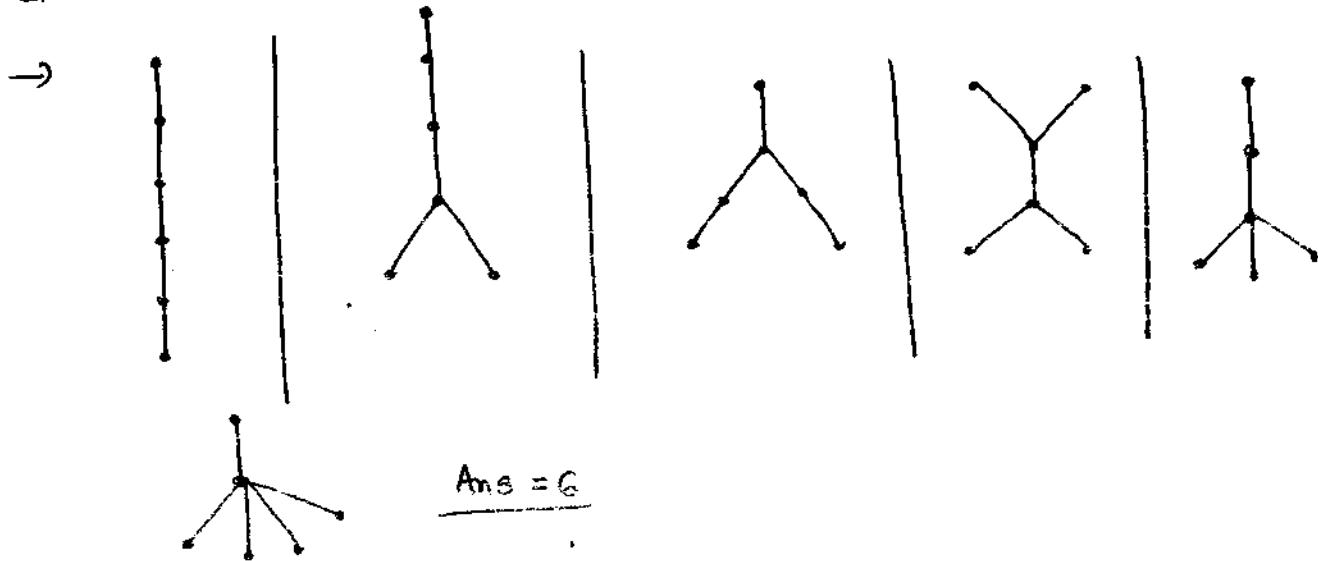
Ans : 2

Ex: $\text{---} \parallel \text{---}$ with 5 vertices ?

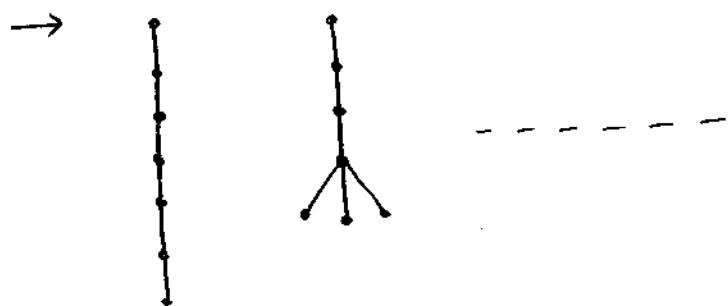


Ans = 3

Ex: ————— with 6 vertices?



Ex: ————— with 7 vertices? Ans = 12



* If a simple graph G is isomorphic to \bar{G} then

i) $|E(G)| = \frac{n(n-1)}{4}$ where n = no. of vertices in a graph

Why $|E(G)| + |E(\bar{G})| = \frac{n(n-1)}{2}$
 $\therefore 2|E(G)| = \frac{n(n-1)}{2}$ ($\because |E(G)| = |E(\bar{G})|$)

$\therefore |E(G)| = \frac{n(n-1)}{4}$

ii) $|V(G)| = 4k$ or $(4k+1)$ $k = 1, 2, 3, \dots$

Ex: If $C_n \equiv \overline{C_n}$ then $n = ?$

→ By the prev. result no. of edges in $C_n = \frac{n(n-1)}{4}$

$$|E(C_n)| = \frac{n(n-1)}{4}$$

$$n = \frac{n(n-1)}{4}$$

$$\boxed{n=5}$$



Ex: If $G \equiv \overline{G}$ then which of the following is not true?

a) $|V(G)| = 20$ b) $|V(G)| = 21$

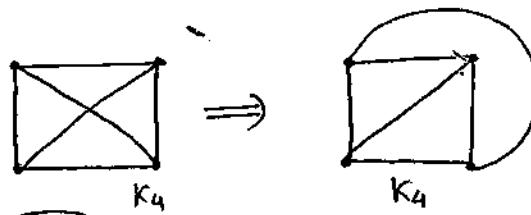
c) $|V(G)| = 25$ ~~d) $|V(G)| = 26$~~

⇒ $|V| = 4k$ or $4k+1$

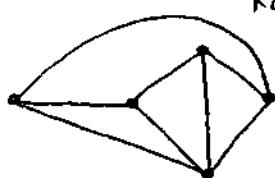
Planar Graphs

A graph G is said to be planar, if it can be drawn on a plane so that no two edges cross each other (at a non vertex point)

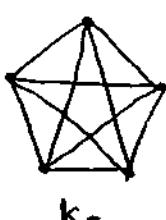
Ex:



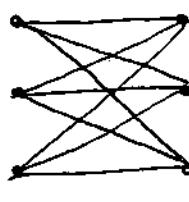
(Planar graph)



(Planar graph)



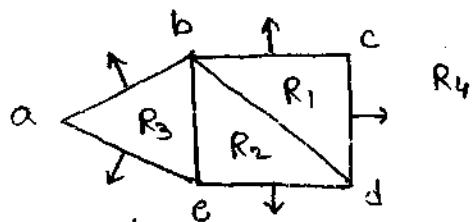
K5



K_{3,3}

(non planar graphs)

Regions : Every planer graph divide the plane into connected areas called Regions of the plane.



$$\deg(R_1) = \deg(R_2) = \deg(R_3)$$

$$= 3$$

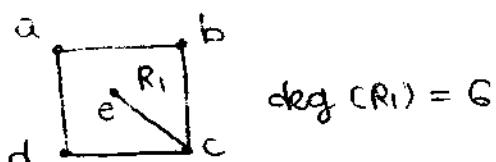
$$\deg(R_4) = 5$$

Degree of an interior region $\sigma = \deg(\sigma)$

= no. of edges enclosing the region σ

Degree of exterior region $\sigma = \deg(\sigma)$

= no. of edges exposed to the region σ .



Properties of Planar Graph :-

$$1) \sum_{i=1}^n \deg(v_i) = 2|E| \quad 2) \text{sum of degrees of regions theorem} :-$$

→ IF P is a planer graph with n regions

$$\sum_{i=1}^n \deg(\sigma_i) = 2|E|$$

2.1) In a planer graph if degree of each region is k then

$$k \cdot |R| = 2|E|$$

2.2) In a planer graph if degree of each region is $\geq k$ (atleast k) then $k \cdot |R| \leq 2|E|$

2.3) In a simple planer graph degree of each region ≥ 3 then

$$3 \cdot |R| \leq 2|E|$$

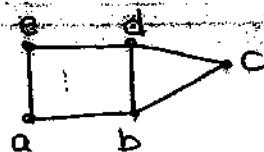
2.4) In a planer graph degree of each region $\leq k$ (atmost k) then $k \cdot |R| \geq 2|E|$

Euler's formula :-

If G is a connected planer graph, then

$$|V| + |R| = |E| + 2$$

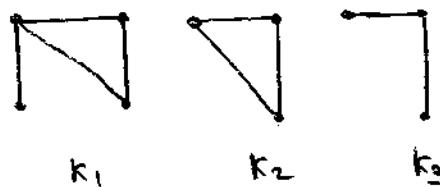
$$5+3=8+2$$



- If G is planar graph with k components

$$|V| + |R| = |E| + (k+1)$$

$$10 + 3 = 9 + (3+1)$$



- 4) If G is a simple connected planar graph, then

- i) $|E| \leq [3|V| - 6]$

- ii) $|R| \leq \{2|V| - 4\}$

- iii) There exists atleast one vertex $v \in G$ such that $\deg(v) \leq 5$

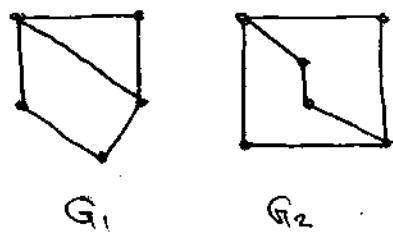
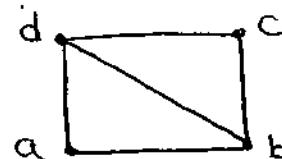
5) Polyhedral graph : A planar graph in which every interior region is polygon is called polyhedral graph.

- In a polyhedral graph degree of every vertex i.e. $\deg(v) \geq 3$ $\forall v \in G$
- For a polyhedral graph the following inequality must be holds :-

- i) $3|V| \leq 2|E|$ and ii) $3|R| \leq 2|E|$

6) Kuratowski's theorem :- A graph G is non planar iff G has a subgraph is homeomorphic to K_5 or $K_{3,3}$:

Homeomorphic : Two graph G_1 & G_2 are said to be homeomorphic to each other if each of these graphs can be obtained from a graph G by dividing some edges of G with more vertices



Note :- 1) Any graph with 4 or fewer vertices is planar.

2) Any graph with 8 or fewer edges is planar.

3) A non planar graph minimum no. of vertices is 5

4) A non planar graph with min. no. of edges is $k_{3,3}$

5) A complete graph K_n is planar iff $n \leq 4$

6) $K_{m,n}$ is planar. iff ($m \leq 2$ or $n \leq 2$)

- If two graphs are isomorphic then they are homeomorphic.

Ex. Let G be a connected planar graph with 25 vertices and 60 edges.

No. of regions in G is —

→ By Euler's Formula,

$$|V| + |R| = |E| + 2$$

$$\Rightarrow 25 + |R| = 60 + 2$$

$$\Rightarrow |R| = 37$$

Ex: Let G be a planar graph with 10 vertices, 3 components and 9 edges then $|R| = ?$

→

$$|V| + |R| = |E| + (K+1)$$

$$\Rightarrow 10 + |R| = 9 + (3+1)$$

$$\Rightarrow |R| = 3$$

Ex: Let G be a connected planar graph with 20 vertices, degree of each vertex is 3 then $|R| = ?$

→ By sum of vertices of degrees theorem

$$\sum \deg(v_i) = 2|E|$$

$$20 \times 3 = 2|E|$$

$$\boxed{|E| = 30}$$

$$|V| + |R| = |E| + 2$$

$$|R| = 32 - 20$$

$$\boxed{|R| = 12}$$

Ex: Let G be a connected planar graph with 35 regions, degree of each region is 6 then $|V| = ?$

$$\rightarrow \sum_{i=1}^{35} \deg(r_i) = 2|E|$$

$$35 \times 6 = 2|E|$$

$$|E| = 105$$

$$\therefore |V| + |R| = |E| + 2$$

$$|V| = 107 - 35 = 72$$

$$\boxed{|V| = 72}$$

Ex: Let G be a connected planar graph with 12 vertices & 80 edges and degree of each region is k then $k = ?$

$$|V| + |R| = |E| + 2$$

$$12 + |R| = 82$$

$$|R| = 70$$

By sum of degrees of regions theorem

$$20 \cdot k = 2|E|$$

$$k = \frac{60}{20}$$

$$\boxed{k = 3}$$

simple

Ex: Max. no. of regions possible in a planar graph with 10 edges is

→ By theorem 2.3

$$3|R| \leq 2|E|$$

$$3|R| \leq 20$$

$$|R| \leq \frac{20}{3}$$

$$|R| \leq 6.66$$

$$\Rightarrow |R| \leq 6$$

Ex: Min no. of edges necessary in a simple planar graph with 15 regions is —

→ By theorem 2.3

$$3|R| \leq 2|E|$$

$$3|R| \leq 2|E|$$

$$|E| \geq 22.5$$

$$\Rightarrow |E| \geq 23$$

Ex: Max. no. of edges possible in a simple connected planar graph with 8 vertices is —

→ By Theorem 4.1

$$|E| \leq \{3|V| - 6\}$$

$$3 \cdot 8 - 6$$

$$|E| \leq 18$$

Ex: Max. no of regions possible in simple planar connected graph with 13 vertices is —

→ By theorem 4.2

$$\blacksquare |R| \leq \{2|V| - 4\}$$

$$\therefore = \{2 \times 13 - 4\}$$

$$\Rightarrow |R| \leq 22$$

Ex: If G is simple connected planar graph, The $\delta(G)$ cannot be equal to —

- a) 3 b) 4 c) 5 d) 6

↓
Min. degree
of all vertices

By theorem 4.3

$\forall v \in G$ such that

$$\deg(v) \leq 5$$

$$\Rightarrow \delta(G) \leq 5$$

$$\Rightarrow \delta(G) \neq 6$$

Ex: Which of the following is not true?

- 5₁) A polyhedral graph with 30 edges and 11 regions does not exist.

→ By Euler's formula

$$|V| + |R| = |E| + 2$$

$$|V| + 11 = 30 + 2$$

$$|V| = 21$$

From polyhedral graph

$$3|V| \leq 2|E| \text{ and } 3|R| \leq 2|E|$$

$$\Rightarrow 3 \times 21 \leq 2(30) \quad 3 \times 11 \leq 2 \times 30$$

$$63 \leq 60$$

$$33 \leq 60$$

∴ True.

- 5₂) A polyhedral graph with 7 edges does not exist

→ $3|V| \leq 2|E| \text{ and } 3|R| \leq 2|E|$

$$|V| \leq 2 \times \frac{7}{3}$$

$$|R| \leq 4 \cdot 66$$

$$|V| \leq 4 \cdot 66$$

$$|R| \leq 4$$

$$|V| \leq 4$$

∴ By Euler's formula $\Rightarrow |V| + |R| = |E| + 2$

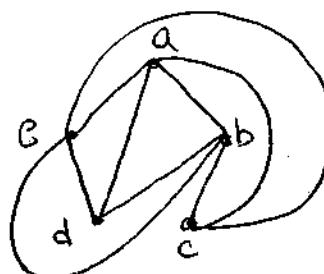
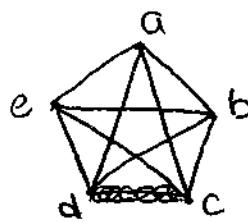
$$4 + 4 = 7 + 2$$

$$8 \neq 9 \quad (8 \nmid 9)$$

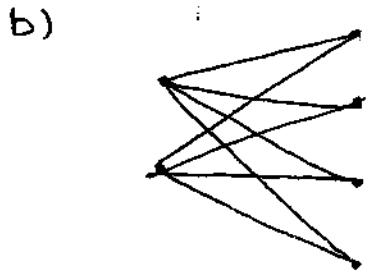
∴ True

Ex: Which of the following is not a planar graph?

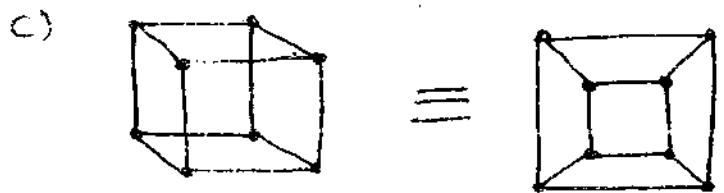
a)



Planar Graph



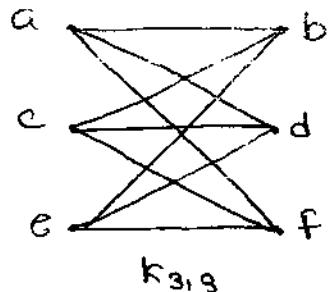
Non planar



planar



non planar?



Ex: G is a non planar graph with minimum no. of vertices then

- G has 6 vertices and 8 edges
- G has 5 ——— and 9 ———
- G has 6 ——— and 9 ———
- ~~G has 5 ——— and 10 ——— (K₅)~~

Ex: Let G be a non planar graph with minimum no. of edges then —

- G has 6 vertices and 8 edges
- G has 5 ——— and 9 ———
- ~~G has 6 ——— and 9 ——— (K_{3,3})~~
- G has 5 ——— and 10 ———

Graph Colouring :-

Vertex coloring :- An assignment of colors to the vertices of a graph G , so that no two adjacent vertices have same color is called vertex coloring.

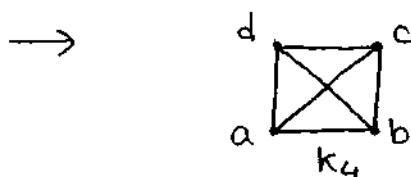
Chromatic Number : Min. no. of colors required for vertex coloring of a graph G is called as chromatic number and denoted by

$$G = \chi(G)$$

- * $\chi(G) = 1$ iff G is a null graph.
- * If G is not a null graph, Then $\chi(G) \geq 2$.
- * A graph G is said to be n -colorable, if there exist a vertex coloring that uses atmost n colors i.e. $\chi(G) \leq n$
- * Four color theorem
 - Every planar graph G is 4-colorable i.e. $\chi(G) \leq 4$
- * Welch - Powell's algorithm
 - 1) Arrange vertices of G in the descending order of their degrees.
 - 2) If 2 or more vertices of some degree, arrange those vertices in Alphabatical or numerical order. so that
 - 3) Assign colors to the vertices in that order so that no 2 adjacent vertices have same color.

Ex: Chromatic numbers of the complete graph K_n is —

- a) n b) $n-1$ c) $\lfloor \frac{n}{2} \rfloor$ d) $\lceil \frac{n}{2} \rceil$



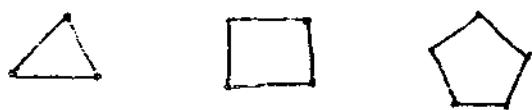
In K_n each vertex is adjacent to remaining $(n-1)$ vertices
∴ Each vertex requires a new color.

$$\therefore \chi(K_n) = n$$

Ex : Chromatic no. of the graph C_n is —
cycle

- a) 2 b) 3 ~~c) $n - 2 \lfloor n/2 \rfloor + 2$~~ d) $n - 2 \lceil n/2 \rceil + 1$

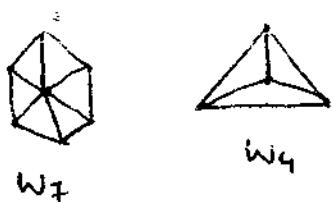
→



If n is odd then 3 } verify option for even & odd
If n is even then 2

Ex : Chromatic no. of the wheel graph W_m ($m \geq 4$) is —

→



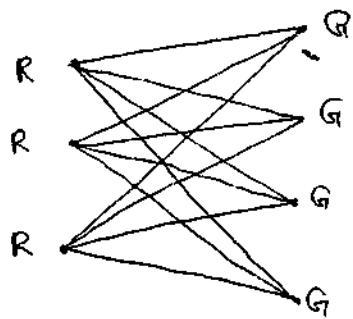
If n is even 4

If n is odd 3

Ex : Chromatic no. of the complete bipartite graph $K_{m,n}$ is —

- ~~a) 2~~ b) 4 c) $\min\{m, n\}$ d) $\max\{m, n\}$

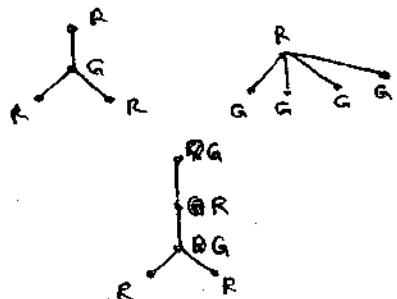
→



Ex : Chromatic no. of a tree T with n vertices ($n \geq 2$) is —

- ~~a) 2~~ b) 4 c) $\lceil n/2 \rceil$ d) $\lceil n/2 \rceil$

→



Every tree is bipartite graph

$$\therefore X(n) = 2$$

Ex: chromatic no. of the star graph with n vertices ($n \geq 2$) is —

- a) $\lceil n/2 \rceil$ b) 4 c) $\lfloor n/2 \rfloor$ d) $\lceil n/2 \rceil$

→



star graph is special case of bipartite graph.



$$\therefore \chi(n) = 2$$

$k_{1, n-1}$

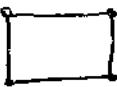
Ex: In a graph G if all the cycles are of even length then

$$\chi(n) = ?$$

→ when cycle of even length then it is bipartite graph.



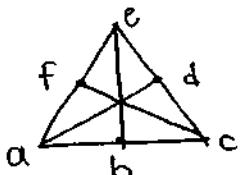
$K_{2,2}$



C_4

$$\chi(n) = 2$$

Ex: chromatic no. of the graph shown below is —



- a) 2 b) 3 c) 4 d) 5

| Vertex | a | b | c | d | e | f |
|--------|-------|-------|-------|-------|-------|-------|
| color | C_1 | C_2 | C_1 | C_2 | C_1 | C_2 |

$$\chi(G) \leq 2 \quad \text{--- ①}$$

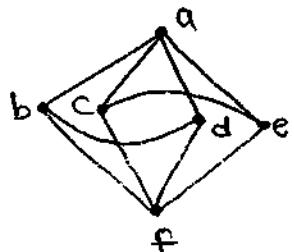
As G is not null graph

$$\therefore \chi(G) \geq 2$$

from ① & ②

$$\chi(G) = 2$$

Ex: Chromatic no. of the graph given below is



- a) 2 ✓ b) 3 c) 4 d) 5

$$\chi(G) \leq 3 \quad \text{--- ①}$$

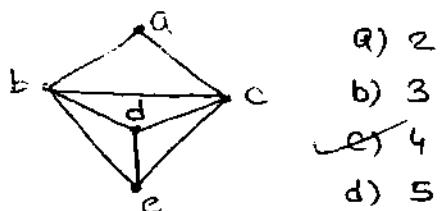
Further, we have 3 mutually adjacent vertices {a, b, d}

$$\therefore \chi(G) \geq 3 \quad \text{--- ②}$$

From ① & ②

$$\chi(G) = 3$$

Ex: Chromatic no. of the graph given below is



- a) 2
b) 3
✓ c) 4
d) 5

| | | | | | |
|--------|----------------|----------------|----------------|----------------|----------------|
| vertex | a | b | c | d | e |
| color | c ₁ | c ₂ | c ₃ | c ₁ | c ₄ |

Here graph is planar therefore by 4 color theorem

$$\text{Chromatic no. } \chi(G) \leq 4 \quad \text{--- ①}$$

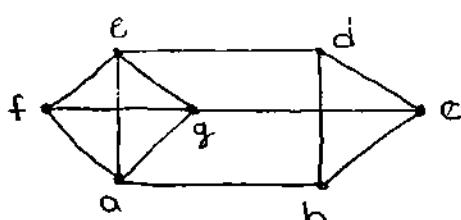
Further we have 4 mutually adjacent vertices {b, c, d, e}

$$\therefore \chi(G) \geq 4 \quad \text{--- ②}$$

From ① & ②

$$\chi(G) = 4$$

Ex:



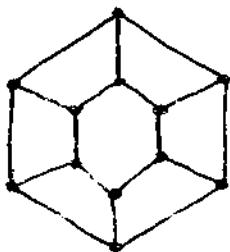
(Planar Graph)

| | | | | | | | |
|--------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|
| vertex | a | b | c | d | e | f | g |
| color | c ₁ | c ₂ | c ₁ | c ₄ | c ₂ | c ₃ | c ₄ |

- a) 2
b) 3
✓ c) 4
d) 5

Ex : Chromatic no. of the graph shown below is —

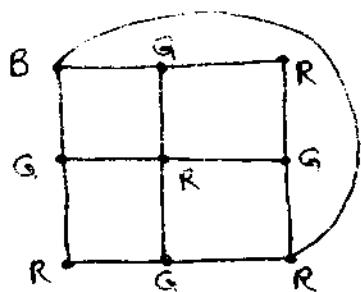
- a) 2 b) 3 c) 4 d) 5



In the graph all cycles are of even vertices

$$\therefore \chi(G) = 2$$

Ex :

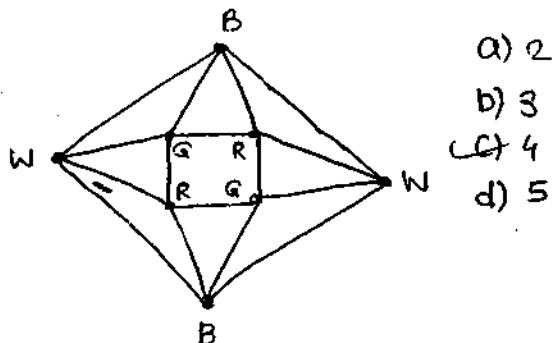


- a) 2
b) 3
c) 4
d) 5

The graph we have a cycle of odd length

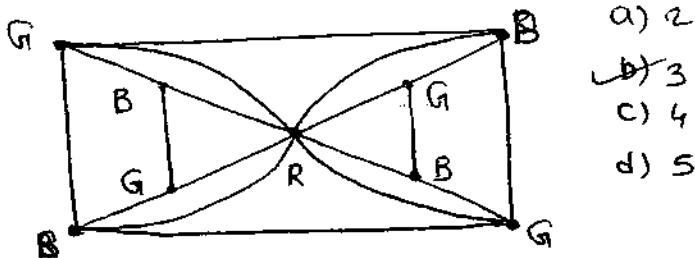
$$\therefore \chi(G) \geq 3$$

Ex : Chromatic no. of graph shown below is —



- a) 2
b) 3
c) 4
d) 5

Ex : Chromatic no. of the graph shown below is —

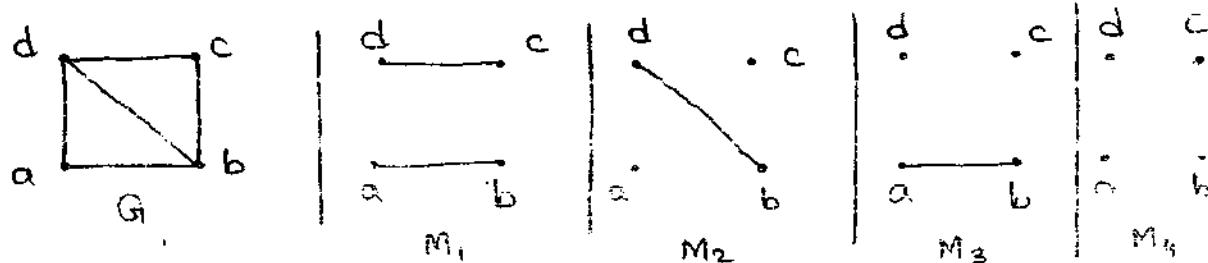


- a) 2
b) 3
c) 4
d) 5

Matching and Covering

Matching : Let G be a graph. A subgraph M of G is called a matching of G , if every vertex of G is incident with atmost one vertex in M .

i.e. $\deg(v) \leq 1 \quad \forall v \in G$



- In a matching, no two edges are adjacent

$$\deg(v) \leq 1$$

- Maximal Matching : A matching M of a graph G is said to be maximal, if no other edges of G can be added to M .

- In above example for the graph G M_1 & M_2 are maximal matching of G .

- Maximum Matching : A matching of a graph with maximum no. of (longest maximal matching) edges is called a maximum matching of G . For a graph given in above example M_1 is maximum matching.

- Matching Number : The no. of edges in a maximum matching of G .

$$\text{Matching no. of } M_1 = 2$$

- Perfect Matching : A matching of a graph in which every vertex is matched is called perfect match.

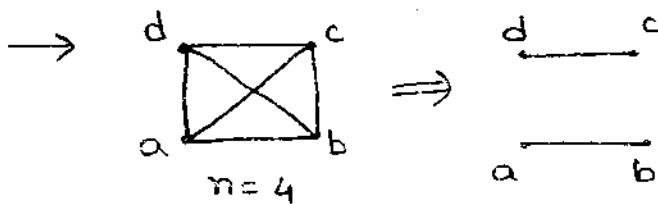
- Note :- Every Perfect Matching is Maximum Matching. (largest maximal matching). (not vice versa)

- Converse of above need not be true.

- If graph G has a perfect match then no. of vertices in G is even. (but not vice versa)

Ex: Matching number of K_n (~~n is even~~) is —

- a) $\lfloor \frac{n}{2} \rfloor$ b) $\lceil \frac{n}{2} \rceil$ c) $\lfloor \frac{n+1}{2} \rfloor$ d) $\lceil \frac{n+1}{2} \rceil$

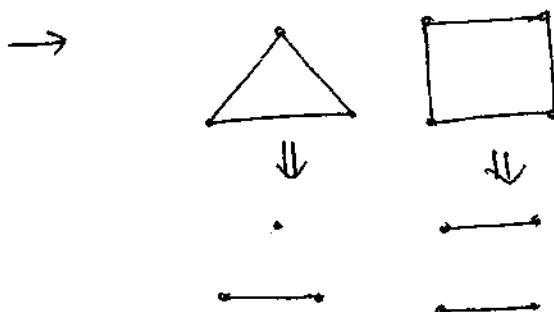


$$= \frac{n}{2} \text{ if } n \text{ is even}$$

$$= \frac{n-1}{2}, \text{ if } n \text{ is odd}$$

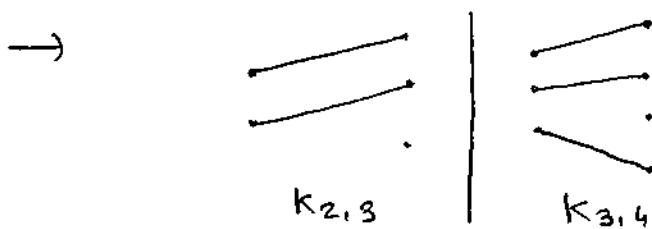
Ex: What is matching no. on ($n \geq 3$) is —

- a) $\lfloor \frac{n}{2} \rfloor$ b) $\lceil \frac{n}{2} \rceil$ c) $\lfloor \frac{n+1}{2} \rfloor$ d) $\lceil \frac{n+1}{2} \rceil$

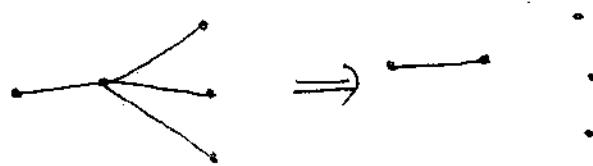


Ex: what is matching no. of K_{mn} is —

- a) Max of $\{m, n\}$ b) min of $\{m, n\}$
c) $|m-n|$ d) G.C.D of $\{m, n\}$



Ex: what is the matching no. of star graph with n vertices ($n \geq 2$) is

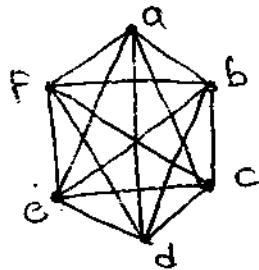


Star graph is
 $K_{1, n-1}$ Bipartite
graph

Ans: 1

* K_n has a perfect matching iff n is even.

Ex: How many no. of perfect matching in K_{2n} is —

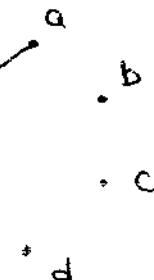


a \rightarrow 5 matches

b \rightarrow 3 \dots

c \rightarrow 1 \dots

\Rightarrow 15 matching no.



Generally, $v_1 \rightarrow (2n-1)$

$v_2 \rightarrow (2n-3)$

$v_3 \rightarrow (2n-5)$

⋮

⋮

\therefore total perfect matching no. $= (2n-1)(2n-3)(2n-5) \dots$

$$= \frac{1}{2^n (2n-2)(2n-4) \dots}$$

$$= \frac{1}{2^n n!}$$

Ex: How many perfect matching in K_8 is —

$$\rightarrow 2n = 8$$

$$\therefore \text{no.} = \frac{8!}{2^4 4!} = \frac{8 \times 7 \times 6 \times 5}{16 \times} = 105$$

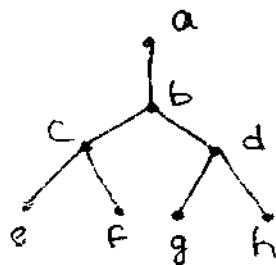
K_{mn} has a perfect matching iff $m=n$.

Ex: No. of perfect matching in $K_{n,m}$ ($n \geq 1$) is —

| | | |
|--------------------------|----------|-------------------------|
| n way $\leftarrow v_1$ | u_1 | $= n(n-1)(n-2) \dots 1$ |
| $(n-1)$ $\leftarrow v_2$ | u_2 | |
| $(n-2)$ $\leftarrow v_3$ | u_3 | $= n$ |
| \vdots | \vdots | |
| 1 $\leftarrow v_n$ | u_m | |

* A tree can have atmost 1 perfect matching.

Ex: No. of perfect matching in the tree shown below is —



a) 0

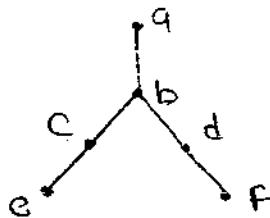
b) 1

c) 2

d) 3

In a perfect matching degree of every vertex is 1 therefore it we cannot delete any edge passing through leaf nodes.

Ex: No of perfect matching in the tree given below is —



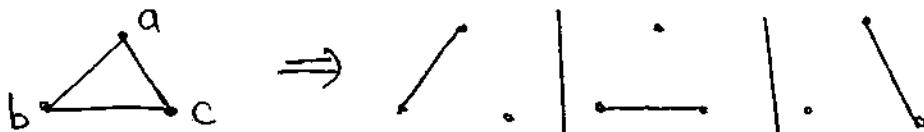
a) 0

b) 1

c) 2

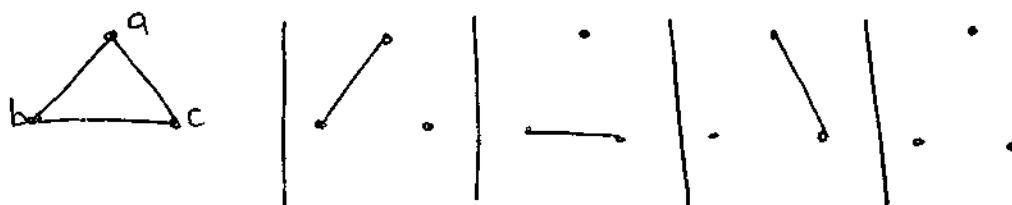
d) 3

Ex: No. of maximal matching in the graph shown below is —



Ans = 3

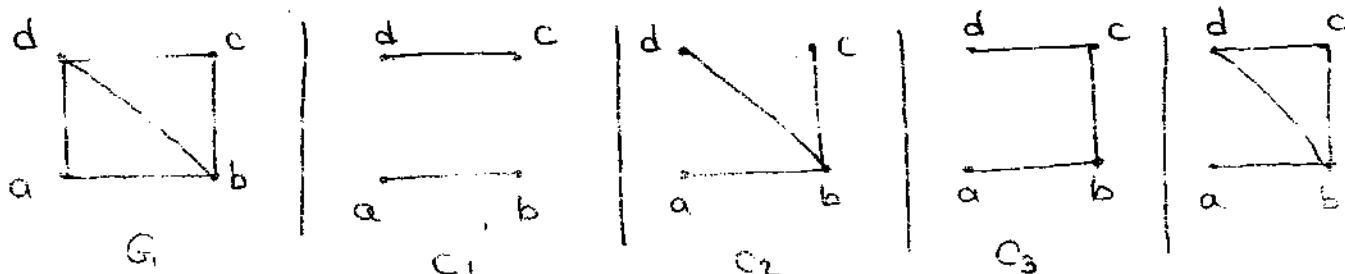
Ex: No. of matching in the graph shown below is 4.



Coverings :-

Line Covering :- Let $G = (V, E)$ be a graph. A subset C of E is called a line covering of G , if every vertex of G is incident with atleast one edge in C .

$$\text{i.e. } \deg(v) \geq 1 \quad \forall v \in G$$



— Line covering of a graph G does not exists iff G has an isolated vertex.



Minimal line covering : A line covering is said to be minimal, if no edge can be deleted from the line covering, without destroying its ability to cover the graph.

For the graph given in the above example C_1 & C_2 are minimal line covering.

Minimum Line covering : (smallest minimal line covering)

A line covering with minimum no. of edges is called a minimum line covering.

* The no. of edges in minimum line covering is called line covering number of a graph. $G = \alpha$,

The graph in above example has $\alpha_1 = 2$.

(C_1 graph is minimum line covering.)

* Line covering of graph with n vertices contains atleast $\lceil \frac{n}{2} \rceil$ edges.

* No minimal line covering can contain a cycle.

* In a line covering if there is no path of length 3 or more, then C is minimal.

- * In the line covering if there are no path of length 3 or more then all components of G is star graph. Then from star graph no edge can be deleted.

Independent line set :

Let $G = (V, E)$ be a graph. A subset L of E is called an independent, if no two edges in L are adjacent.



$$L_1 = \{(b,d)\}$$

$$L_2 = \{(b,d), (e,f)\}$$

$$L_3 = \{(a,d), (b,c), (e,f)\}$$

$$L_4 = \{(a,b), (e,f)\}$$

Maximal independent line set : An independent line set L of a graph G is said to be maximal, if no other edges of G can be added to L.

$$\text{Ex : } L_2 = \{(b,d), (e,f)\}$$

$L_3 = \{(a,d), (b,c), (e,f)\}$ one maximal independent line set because no other edges can be added to it.

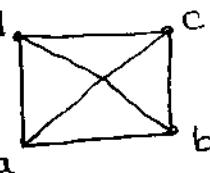
Maximum independent line set :- (largest Maximal independent line set) An independent line set L of a graph G, with maximum no. of edges is called Maximum independent line set -

- * No. of edges in Maximum independent line set is called line independent number of G denoted by β_1 (say)
- * Line independent no. = Matching no. of G.

For the graph in above example L_3 is a Maximum independent line set and $\beta_1 = 3$.

* For any graph G, $\alpha_1 + \beta_1 = |V|$

Ex : For the graph shown below which of the following is a minimal line covering?



- (A) $\{(a,b), (a,c), (b,d)\}$
- (B) $\{(a,b), (b,d), (d,c)\}$
- (C) $\{(a,b), (c,d), (a,c)\}$
- (D) $\{(a,b), (c,d), (a,c), (b,d)\}$

Ex: No. of edges in the line covering of the graph cannot exceed
(with n vertices)

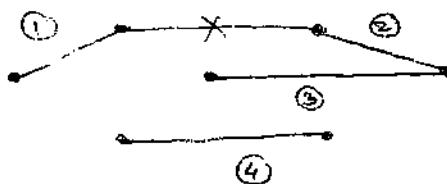
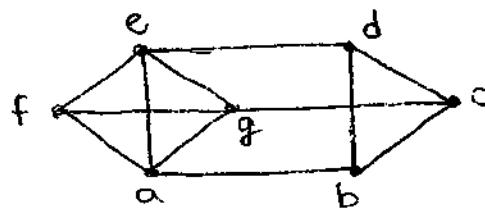
- a) $\lceil \frac{n}{2} \rceil$ b) $\lfloor \frac{n}{2} \rfloor$ c) $n-1$ d) $n-2$

Ex: For the graph shown below

$$\text{line covering no.} = \alpha_1 = 4$$

$$\text{line independent no.} = \beta_1 = 3$$

$$\begin{aligned}\beta_1 &= |V| - \alpha_1 \\ &= 7 - 4 \\ &= 3\end{aligned}$$



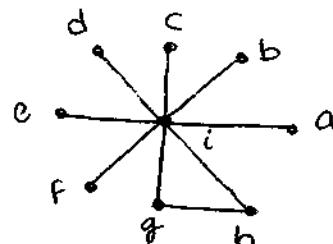
Ex: For the graph shown below

$$\alpha_1 = 7$$

$$\alpha_1 + \beta_1 = |V|$$

$$\beta_1 = 9 - 7$$

$$\beta_1 = 2$$

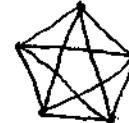


Ex: For the complete graph K_n find α_1, β_1

$$\alpha_1 = \lceil \frac{n}{2} \rceil$$

$$\beta_1 = \lfloor \frac{n}{2} \rfloor$$

$$\alpha_1 + \beta_1 = |V| = n$$



Ex: For the cycle graph C_n ($n \geq 3$) $\alpha_1, \beta_1 = ?$

$$\alpha_1 = \lceil \frac{n}{2} \rceil$$

$$\beta_1 = \lfloor \frac{n}{2} \rfloor$$

$$\alpha_1 + \beta_1 = n$$

Ex: wheel graph W_n ($n \geq 4$)

$$\alpha_1 = \lceil \frac{n}{2} \rceil$$

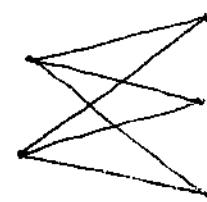
$$\beta_1 = \lfloor \frac{n}{2} \rfloor$$

Ex : For complete bipartite graph $K_{m,n}$.

$$\alpha_1 = \max(m, n)$$

$$\beta_1 = \min(m, n)$$

$$\alpha_1 + \beta_1 = m + n$$



Ex : For the star graph with n vertices ($n > 2$)

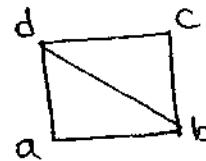
$$\alpha_1 = n - 1$$

$$\beta_1 = 1$$

$$\alpha_1 + \beta_1 = n$$



Vertex Covering :- Let $G = (V, E)$ be graph. A subset k of V is called a vertex covering of G , if every edge of G is incident with a vertex in k .



$$k_1 = \{b, d\}$$

$$k_2 = \{a, b, c\}$$

$$k_3 = \{b, c, d\}$$

Minimal Vertex Covering :- vertex covering k of a graph G is said to be minimal if no vertex can be deleted from k .
 k_1 & k_2 are minimal vertex covering.

Minimum vertex covering :- A vertex covering of a graph G with minimum number of vertices is called as Minimum vertex covering. (also called as smallest minimal vertex covering)
— No. of vertices in a minimum vertex covering is called vertex covering no. of Graph G , denoted by α_2

In above graph G of k_1 $\alpha_2 = 2$

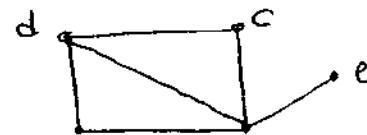
Independent Vertex set :-

Let $G = (V, E)$ be a graph. A subset S of V is called an independent set if no two vertices in S are adjacent.

$$S_1 = \{b\}$$

$$S_4 = \{a, c\}$$

$$S_2 = \{d, e\}$$



Maximal indep. vertex set :- An independent vertex set is said to be maximal, if no other vertex of G can be added to the set.

$$\text{Ex: } S_1 = \{b\}$$

$$S_2 = \{d, e\}$$

$$S_3 = \{a, c, e\}$$

Maximum indep. vertex set (Largest maximal indep. vertex set) :-

An indep. vertex set of graph G with maximum no. of vertices is called Maximum indep. vertex set.

- * The no. of vertices in Maximum indep. vertex set is called as indep. vertex indep. number of G denoted by β_2

$$\text{Ex: } S_3 = \{a, c, e\}$$

$$\therefore \beta_2 = 3$$

$$\text{* For any graph } \alpha_2 + \beta_2 = |V|$$

- * For any graph if S is independent set of G then $V-S$ = A vertex covering of G .

Ex: For a complete graph K_n , vertex covering no = α_2 = ?
vertex \in indep. no = β_2 = ?

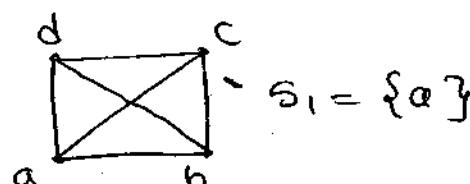
$$\rightarrow \alpha_2 + \beta_2 = |V| = n$$

$$\alpha_2 \leq 1 \quad \beta_2 = 1$$

(because in K_n every vertex adjacent to each other)

$$\therefore \alpha_2 = |V| - \beta_2$$

$$\alpha_2 = n-1$$

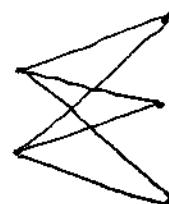


Ex: For the complete bipartite graph $K_{m,n}$

$$\alpha_2 = \min(m, n)$$

$$\beta_2 = \max(m, n)$$

$$\alpha_2 + \beta_2 = m+n$$



Ex: for the star graph with n vertices ($n \geq 2$)

$$\rightarrow \alpha_2 = 1$$

$$\beta_2 = n-1$$

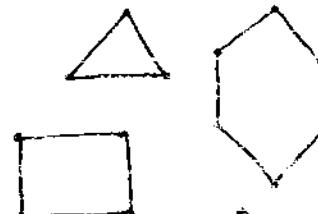
$$\alpha_2 + \beta_2 = n$$



Ex: for the cycle graph C_n ($n \geq 3$)

$$\alpha_2 = 0 [n/2]$$

$$\beta_2 = [n/2]$$



Ex: wheel graph W_n ($n \geq 4$)

$$\rightarrow \alpha_2 = \lceil \frac{n+1}{2} \rceil$$

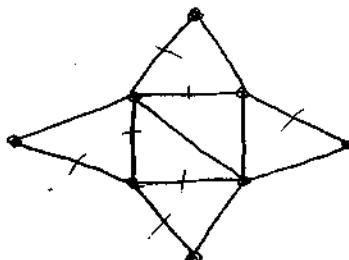
$$\beta_2 = \lfloor \frac{n-1}{2} \rfloor$$

$$\alpha_2 = 3 \\ \beta_2 = 1$$

$$\alpha_2 = 4 \\ \beta_2 = 2$$

$$\alpha_2 = 4 \\ \beta_2 = 2$$

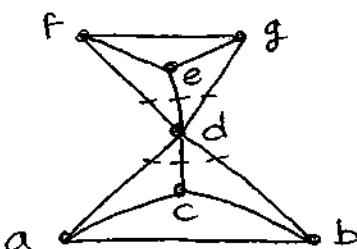
Ex: for the graph shown below



$$\beta_2 = 4$$

$$\alpha_2 = 4$$

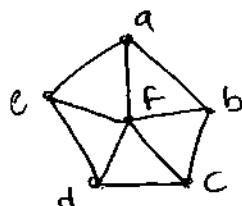
Ex:



which is not true?

- a) $\alpha_2 = 5$
- c) $\{a, e\}$ is a max. indep. set
- b) $\beta_2 = 2$ w.r.t. $\{a, c, e, f\}$ is vertex covering

Ex:

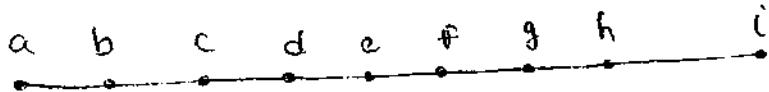


which of the following is not true?

- a) $\alpha_2 = 4$
- b) $\beta = 2$
- c) $\{b, d\}$ is max. indep. vertex set
- w.r.t. $\{a, c, f\}$ is a vertex covering.

Ex: The no. of vertices in the smallest maximal indep. vertex set in the chain of 9 nodes?

- a) 3 b) 4 c) 5 d) 2



$$S_1 = \{a, c, e, g, i\} \quad \text{largest Maximal}$$

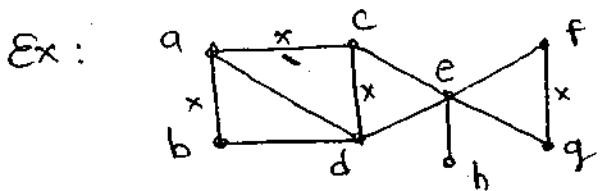
$$S_2 = \{b, d, f, h\}$$

$$S_3 = \{b, e, h\} \rightarrow \text{smallest}$$

Spanning Trees

Let G be a connected graph. A subgraph H of G is called a spanning tree of G , if i) H is a tree
ii) H contains all vertices of G

Circuit rank :- Let G be connected graph with n vertices and m edges. Any spanning tree of G contains $(n-1)$ edges
— The no. edges we have to delete from G to get spanning tree of G is equal to $\boxed{m - (n-1)}$ is called circuit rank of G .



Edges

$$\begin{aligned}\text{Circuit rank}(G) &= m - (n-1) \\ &= 11 - (8-1) \\ &= 4\end{aligned}$$

Ex: Let G be a connected graph with 6 vertices and degrees of each vertex is 3. Circuit rank of G = ?

$$\rightarrow \sum \deg(v_i) = 2|E|$$

$$18 = 2|E|$$

$$|E| = 9$$

$$\begin{aligned}\text{Circuit rank}(G) &= g - (n-1) \\ &= 9 - (6-1) \\ &= 4\end{aligned}$$

- Ex : Let G be connected graph with 5 vertices, max. no. of edges and all cycles in G are of even length. Find $C(G) = ?$
- If all cycles of even length then G is bipartite graph with max. no. edges and 5 vertices.

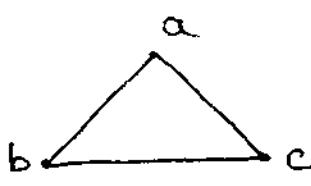
$$\therefore G = K_{3,2} \text{ or } K_{2,3}$$

$$\therefore \text{No. edges} = 6$$

$$C(G) = 6 - (5-1)$$

$$= 2$$

Ex . Number of spanning trees in the graph shown below is -

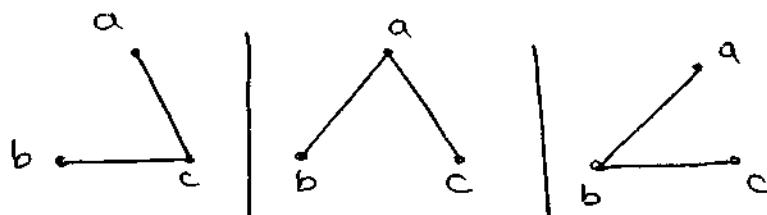


~~a) 3~~

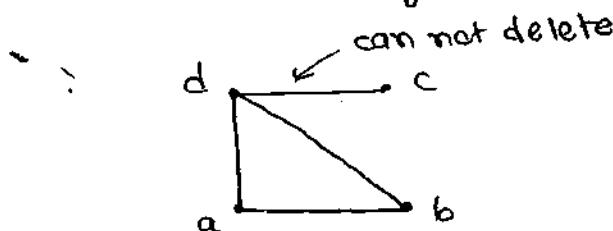
b) 4

c) 6

d) 8



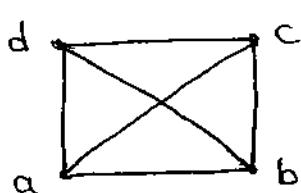
Ex : No. of spanning trees —



~~a) 3~~

c) 6
b) 4
d) 8

Ex : No. of spanning trees —

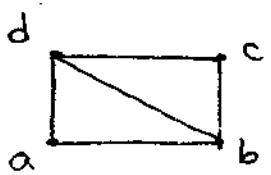


a) 6
b) 8
c) 12
~~d) 16~~

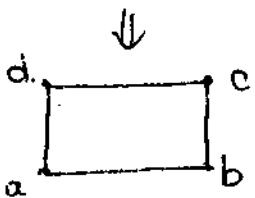
$$\begin{aligned} \text{No. of spanning trees in complete graph} &= n^{n-2} \quad (\text{Caley's formula}) \\ &= 4^{4-2} \\ &= 16 \end{aligned}$$

$$\text{Circuit rank} = m - (n-1) = 8 - (4-1) = 4$$

Ex: No. of spanning trees :-



- a) 6
 b) 8
 c) 10
 d) 4



Kirchoff's Theorem :-

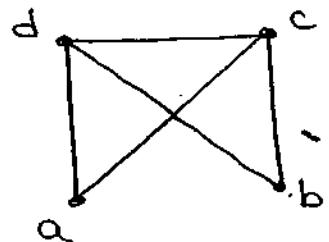
Let A be the adjacency matrix of a connected graph G .

Let M be the matrix obtained from A , by changing all 1's into -1 and replacing each element in the principle diagonal of A with the degree of ^{zero} corresponding vertex.

- cofactor of any element of M is equal to the no. of spanning trees in G .

Ex: No. of spanning trees in the graph shown below :-

$$A = \begin{bmatrix} a & b & c & d \\ a & 0 & 0 & 1 & 1 \\ b & 0 & 0 & -1 & 1 \\ c & 1 & 1 & 0 & 1 \\ d & 1 & 1 & 1 & 0 \end{bmatrix}$$

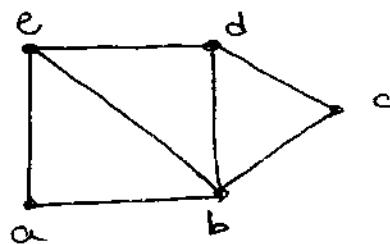


$$M = \begin{bmatrix} 2 & 0 & -1 & -1 \\ 0 & 2 & -1 & -1 \\ -1 & -1 & 3 & -1 \\ -1 & -1 & -1 & 3 \end{bmatrix}$$

$$\text{cofactor of } M_{11} = (-1)^{1+1} \begin{vmatrix} 2 & -1 & -1 \\ -1 & 3 & -1 \\ -1 & -1 & 3 \end{vmatrix} = 2(9 + 1) + 1(-2) - 1(1 + 3) = 16 - 2 - 4 - 2 = 8$$

Ex: No of spanning trees in the graph shown below :-

$$A = \begin{bmatrix} & a & b & c & d & e \\ a & 0 & 1 & 0 & 0 & 1 \\ b & 1 & 0 & 1 & 1 & 1 \\ c & 0 & 1 & 0 & 1 & 0 \\ d & 0 & 1 & 1 & 0 & 1 \\ e & 1 & 1 & 0 & 1 & 0 \end{bmatrix}$$



$$M = \begin{bmatrix} 2 & -1 & 0 & 0 & -1 \\ -1 & 4 & -1 & -1 & -1 \\ 0 & -1 & 2 & -1 & 0 \\ 0 & -1 & -1 & 3 & -1 \\ -1 & -1 & 0 & -1 & 3 \end{bmatrix}$$

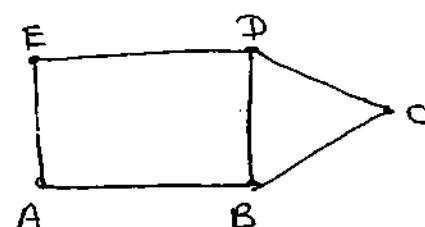
$$\text{cofactor of } M_{51} = (-1)^{5+1} \begin{vmatrix} -1 & 0 & 0 & -1 \\ 4 & -1 & -1 & -1 \\ -1 & 2 & -1 & 0 \\ -1 & -1 & 3 & -1 \end{vmatrix}$$

$$C_4 - C_1 \\ = \begin{vmatrix} -1 & 0 & 0 & 0 \\ 4 & -1 & -1 & -5 \\ -1 & 2 & -1 & 1 \\ -1 & -1 & 3 & 0 \end{vmatrix}$$

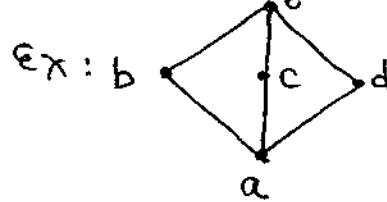
$$= (-1) \begin{vmatrix} -1 & -1 & -5 \\ 2 & -1 & 1 \\ -1 & 3 & 0 \end{vmatrix} = \begin{vmatrix} 1 & 1 & 5 \\ 2 & -1 & 1 \\ -1 & 3 & 0 \end{vmatrix} = 21$$

Ex: No. of spanning trees —

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 & 1 \\ 1 & 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 & 1 \\ 1 & 0 & 0 & 1 & 0 \end{bmatrix}$$



$$\underline{\underline{\text{Ans} = 11}}$$



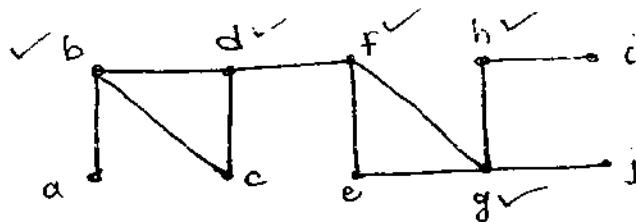
$$\underline{\underline{\text{Ans} = 12}}$$

W

BFS, DFS, Minimal spanning trees, Kruskal's algo, Prim's Algorithm, Traversability theorem, Euler circuit, Hamiltonian graph.

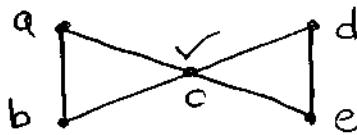
Connectivity :- A graph is not connected will have two or more connected components.

Cut Vertex :- Let G be a connected graph. A vertex $v \in G$ is called cut vertex of G if $(G-v)$ results in a disconnected graph.
Articulation point



Cut edge :- Let G be a connected graph and an edge $E \in G$ (Bridge) is called a cut edge of G if $(G-E)$ results in a disconnected graph.

- In a connected graph G if $E \in G$ is cut edge iff E is not part of any cycle in G.
- whenever cut edge exists cut vertex also exists and not vice versa. Because atleast one vertex of cut edge is a cut vertex.
- If cut vertex exists then cut edge may or may not be exists. Ex: vertex C.

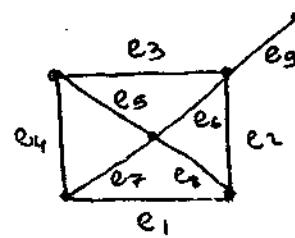


Cut set :- Let $G = (V, E)$ be a connected graph. A subset E' of E is called a cut set of G, iff ~~If deletion of E' to make G disconnected~~ If deletion of all the edges in E' makes G disconnected and deletion of no proper subset of E' from G, can make G disconnected.

Ex: For the graph shown below which of the following are cut set?

- a) $\{e_1, e_3, e_5, e_7\}$
 b) $\{e_2, e_5, e_6, e_8\}$
 c) $\{e_2, e_5, e_3, e_9\}$

↓
No need of e_9 .



because using e_2, e_5, e_6, e_8 it is disconnected graph.

- d) $\{e_9\}$
 e) $\{e_1, e_4, e_7\}$

Edge connectivity :- In a connected graph G , the min. no. of edges whose deletion makes G disconnected is called 'Edge connectivity of G '.

It is denoted by $\lambda(G)$.

- If G has a cut edge then edge connectivity $\lambda(G) = 1$
- The no. of edges in a smallest cut set of G is said to be edge connectivity of G .

Vertex Connectivity :- In a connected graph G , the min. no of vertices whose deletion makes graph disconnected or reduces G into a trivial graph is called vertex connectivity of a connected graph G .

It is denoted by $k(G)$

- If G has a cut vertex then $k(G) = 1$
- For any connected graph G ,

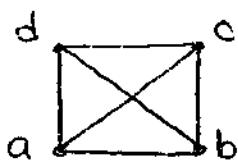
$$k(G) \leq \lambda(G) \leq \delta(G)$$

$\delta(G) = \text{min. of all the degrees of all vertices.}$

Ex: for complete graph K_n

vertex connectivity of $K_n = n-1$

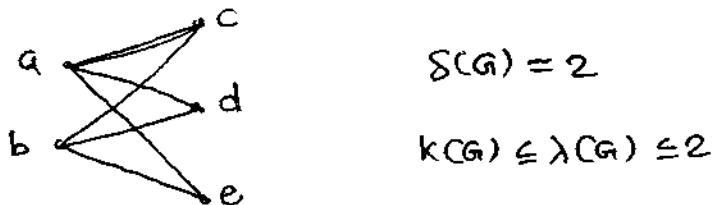
edge connectivity of $K_n = n-1$



Ex: for a complete bipartite graph $K_{m,n}$

vertex connectivity = $\min(m, n)$

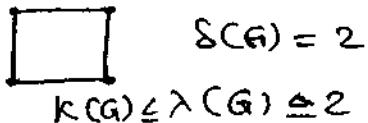
edge connectivity = $\min(m, n)$



Ex: for a cycle graph $C_n (n > 3)$

edge connectivity = 2

vertex connectivity = 2

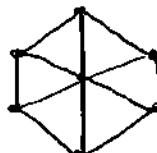


Ex: for the wheel graph $W_n (n \geq 4)$

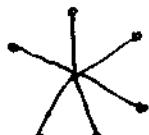
edge connectivity = 3

vertex connectivity = 3

$k(G) \leq \lambda(G) \leq \delta(G) = 3$



Ex: for the star graph ($n \geq 2$) ($K_{1,n-1}$)



edge connectivity = 1

vertex connectivity = 1

$\delta(G) = 1$

Ex: For a tree with n vertices ($n \geq 2$),

vertex connectivity = 1

edge connectivity = 1



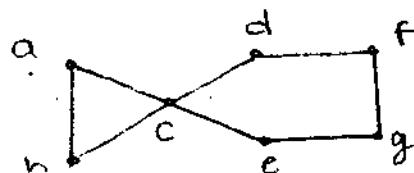
$$\delta(G) = 1$$

Ex: For the graph shown below

$$\delta(G) = 2$$

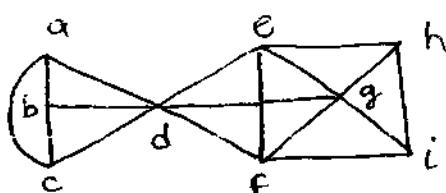
vertex connectivity = 1

edge connectivity = 2



Ex:

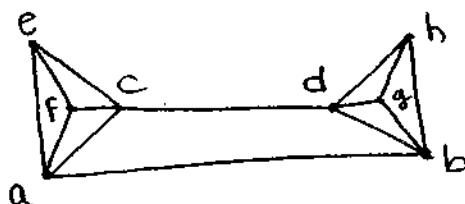
$$\delta(G) = 3$$



vertex conn. = 1

edge conn. = 3

Ex:



$$\delta(G) = 3$$

vertex conn. = 2

edge conn. = 2

* A simple graph G with n -vertices is necessarily connected if number of edges in G

$$|E(G)| > \left\{ \frac{(n-1)(n-2)}{2} \right\}$$

Ex: Which of the following Graphs are necessarily connected?

- (A) A Graph with 6 v and 10 E ($10 \neq 10$)
- (B) 7 vertices and 14 edges ($14 \neq 15$)
- (C) 8 vertices , 22 edges ($22 > 21$)
- (D) 9 vertices , 28 edges ($28 \neq 28$)

Ex: what is the min. no. of edges needed to guarantee the connectivity in a simple graph with 10 vertices?

- a) 37 b) 38 c) 34 d) 28

$$|E(G)| > \frac{(n-1)(n-2)}{2} \Rightarrow 9 \times 4 = 36$$

- * A simple graph with n -vertices and k -components has at least $(n - k)$ edges.

$$\text{i.e. } |E(G)| \geq (n - k)$$

- * A simple graph with n -vertices and k -components then the max. no. of edges of G is always at most $\frac{(n - k)(n - k + 1)}{2}$ edges.

$$|E(G)| \leq \frac{(n - k)(n - k + 1)}{2}$$

Ex: Min. no. of edges necessary in a simple graph with 10 v and 3 components.

$$\rightarrow |E(G)| \geq (n - k) \\ \geq (10 - 3)$$

$$|E(G)| \geq 7$$

Ex: Max. no. of edges necessary in a simple graph with 10 v and 3 components

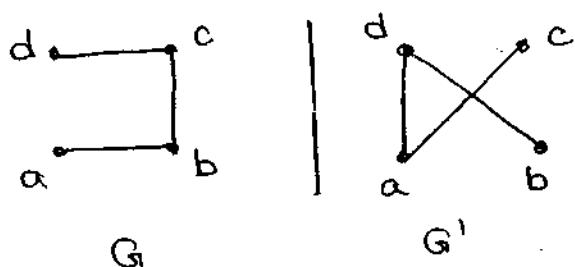
$$\text{a) 25 b) 28 c) 30 d) 37}$$

$$|E(G)| \leq \left[\frac{(10 - 3)(10 - 3 + 1)}{2} \right]$$

$$|E(G)| \leq 28$$

Ex: Which of the following is/are true?

- Ⓐ If a simple graph G is connected then \bar{G} is not connected.

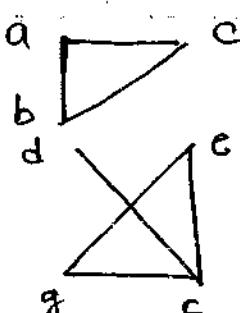


Here G & G' both connected.

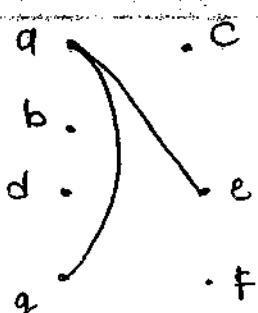
\therefore FALSE (Need not be always true)

- Ⓑ A simple graph G is not connected then \bar{G} is connected





G



G'

TRUE

- (c) In a complete graph G with n -vertices, if $\delta(G) \geq \left(\frac{n-1}{2}\right)$ then G is connected.

→ Suppose given stat. is False

i.e. $\delta(G) \geq \left(\frac{n-1}{2}\right)$ and G is not connected.

G has atleast two components G_1 & G_2

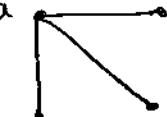
Let $v \in G_1$,

$$\deg(v) \geq \Theta\left(\frac{n-1}{2}\right)$$

$$\Rightarrow |V(G_1)| \geq \frac{n-1}{2} + 1$$

$$|V(G_1)| \geq \frac{n+1}{2}$$

$$\deg(a) = 3$$



Similarly, no. of vertices in G_2 is also $\geq \frac{n+1}{2}$

Now, No. of vertices in $G \geq |V(G_1)| + |V(G_2)|$

$$\geq \frac{n+1}{2} + \frac{n+1}{2}$$

$$|V(G)| \geq n+1$$

∴ It is contradiction.

∴ Given stat. is true.

TRUE

- (d) If a simple graph G has exactly two vertices of odd degree, then there exists a path b/w the 2 vertices.

→ The given stat. is true if G is connected graph.

If a graph is nonconnected then by sum of degree theorem the two vertices of odd degree belong to same components

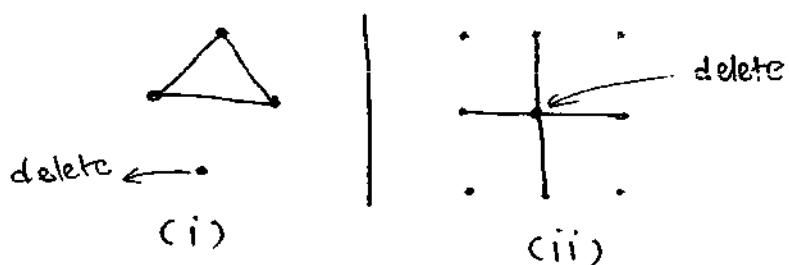
*: Let G be a graph with n vertices and k components.

If we delete a vertex in G , then the number of components in G , should lie between

- a) $n-k$ and $n-1$
- b) $k-1$ and $n-k$
- c) k and $n-k$ (~~✓~~) $k-1$ and $n-1$

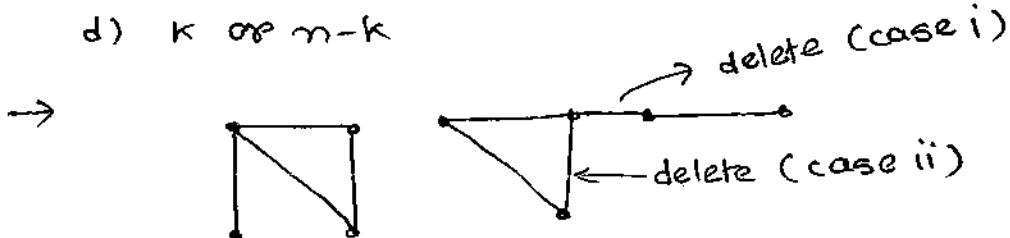
i) If the vertex we are deleting is the component of itself then the no. of components become $k-1$.

ii) If given graph is star graph with n vertices then by deleting cut vertex of star graph we get $n-1$ components.
max. no. component = $n-1$



Ex: Let G be a graph with n vertices and k -components. If we delete an edge in G , then the no. of components in G are —

- i) a) $k-1$ or k (~~✓~~) k or $k+1$ c) $k-1$ or $k+1$
- d) k or $n-k$

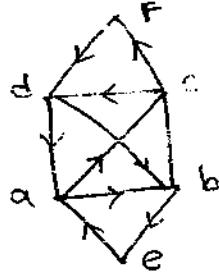


- i) If edge we are deleting is cut edge then no. of components become $k+1$.
- ii) If deleting edge is not cut edge then no. of components remains same i.e. k

Traversability :-

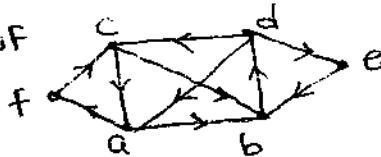
A graph G is said to be traversable, if there exist a path which contains each edge of G exactly once and each vertex of G atleast once such a path is called Euler path.

Euler Circuit :- An Euler path in which the starting vertex is same as ending path is called Euler circuit.



a - b - c - d - b - e -
a - c - f - d - a

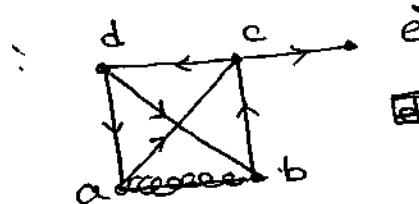
vertices of



a - b - d - c - a - f - c - b - d - e -
b - d - a

Theorem : A graph G is traversable, if no. of vertices with odd degree is exactly two or more zero.

- If graph G has exactly 2 vertices of odd degree then euler path exists but euler circuit does not exists.
- If graph G has no vertices of odd degree then euler circuit also exists.
- If graph has exactly two vertices of odd degree then the euler path begins with one odd vertex and ends with other odd vertex.

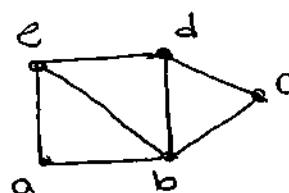


d - a - c - d - b - c - e

Hamiltonian graph :-

In a graph G , if there exists a cycle which contains each vertex of G exactly once, then the cycle is called Hamiltonian cycle and the graph is called hamiltonian graph.

Ex:



Ex:

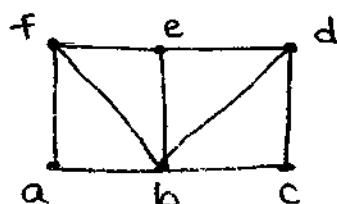


- In Euler circuit every edge is present exactly once but in hamiltonian cycle some edges of the graph may be skipped.

• Hamiltonian graphs and traversable graph both are connected graph.

Ex : for the graph shown below which of the following is true ?

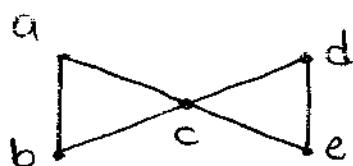
- Euler path exists
- Euler circuit exists
- Hamiltonian cycle exists
- Hamiltonian path exists



• The graph has no vertices with odd degree
∴ It is traversable
• Euler circuit does not exists

selected option here :

in the graph no. of
vertices with odd
degree is zero



∴ It is traversable and Euler circuit also exists.

• Euler path \Rightarrow Euler circuit

• Ham. cycle \Rightarrow Ham. path

• In hamiltonian cycle degree of each vertex is 2.

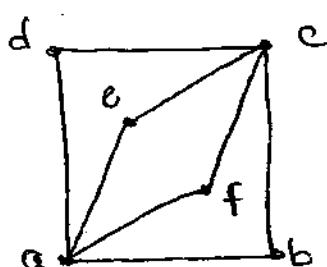
Therefore to construct hamiltonian in G we have to delete
2 edges of vertex C, then we are left with 5 vertices
& 4 edges \therefore a cycle graph with 5 vertices req. 5 edges.

Ham. path exists a-b-c-d-e which contains all
5 edges (Ham. circuit not exists)

• Which is / are true ?

The graph has no vertices
with odd degree

\therefore It is traversable
and Euler circuit also
exists.



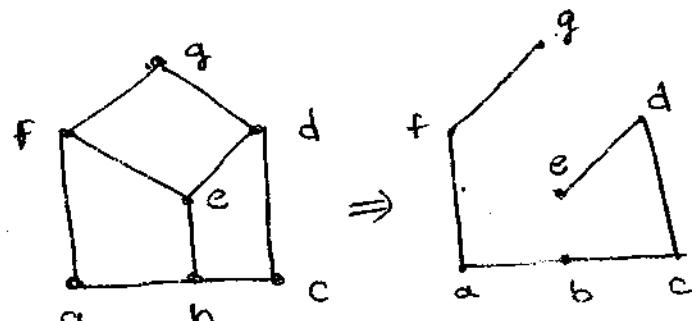
To construct ham. cycle for the graph we have to delete
two edges and such all other contains a 2

Then we are left with 6 vertices and 4 edges, therefore neither ham. cycle nor path exists.

Ex:

Odd degrees of vertices present

∴ No Euler path and Circuit present.



To construct ham. cycle for the graph we have to delete one edge at each of the vertices b, d, f then left with 6 edges & 7 vertices
ham. cycle is not possible. but ham. path exists.

Set theory & Algebra

- * sets
- * Relations
- * functions
- * Groups
- * lattice
- * Boolean Algebra

Set :- A well defined unordered collection of distinct elements.

$$A = \{x \mid x \text{ is an integer and } 1 \leq x \leq 10\}$$

$$= \{1, 2, 3, \dots, 10\}$$

Sets are denoted by upper case letters and elements denoted by lower case letters.

Null set :- A set with no elements.

It is denoted by \emptyset .

$$\text{Ex: } A = \{x \mid x \text{ is a prime no. and } 8 < x < 10\}$$

$$A = \{ \}$$

$$A = \emptyset$$

Subset : If A and B are sets, such that every element of A is also an element of B then A is a subset of B.

Denoted by $A \subseteq B$

For any set A, $A \subseteq A$ and $\emptyset \subseteq A$

proper subset :- Any subset of A, which is not a trivial subset of A is called proper subset of A.

Ex: $A = \{1, 2, 3\}$

$B = \{1, 2, 3, 4\}$ thus $A \subset B$

* IF $A \subseteq B$ and $B \subseteq A$, then $A = B$

Power set :- Let A be a set then power set of A denoted by $P(A) =$ set of all subsets of A

Let $A = \{1, 2, 3\}$

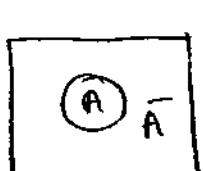
then $P(A) = \{\emptyset, \{1\}, \{2\}, \{3\}, \{1, 2\}, \{1, 3\}, \{2, 3\}, \{1, 2, 3\}\}$

Note : If $|A| = n$ then no. of elements in $P(A) = 2^n$

Universal set : Set of all objects under discussion (U)

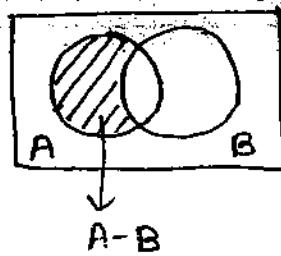
Complement of set :- A universal set U and a set A contained in U , then all elements that belong to U but not A is called complement of A (in U)

It is denoted by \bar{A}



Set difference :- (Relative complements)

$$A - B = \{x | x \in A \text{ and } x \notin B\}$$



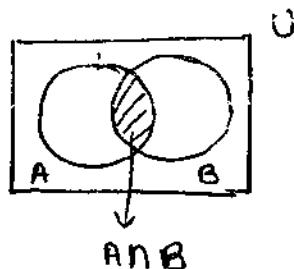
$$\text{IF } A = \{1, 2, 3, 4\}$$

$$B = \{2, 4, 5, 6\}$$

$$A - B = \{1, 3\}$$

Set intersection :

$$A \cap B = \{x | x \in A \text{ and } x \in B\}$$

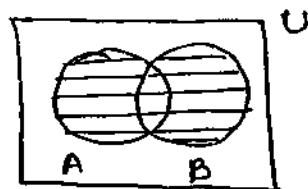


$$A \cap B \subseteq A \text{ and}$$

$$A \cap B \subseteq B$$

Set Union :

$$A \cup B = \{x | x \in A \text{ or } x \in B\}$$



$$A \subseteq (A \cup B) \text{ and}$$

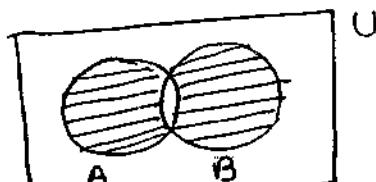
$$B \subseteq (A \cup B)$$

Symmetric Difference :- (Boolean sum)

$$A \Delta B = \{x | x \in A \text{ or } x \in B \text{ but } x \notin (A \cap B)\}$$

$$A \triangle B = (A \cup B) - (A \cap B)$$

$$A \oplus B = (A - B) \cup (B - A)$$



$$A = \{1, 2, 3, 4\}$$

$$B = \{1, 2, 3, 4, 5, 6\}$$

$$A \Delta B = \{5, 6\}$$

The laws of set theory :

1. commutative laws :

$$A \cup B = B \cup A$$

$$A \cap B = B \cap A$$

$$A \oplus B = B \oplus A$$

$$A - B \neq B - A$$

2. Associative laws :

$$(A \cup B) \cup C = A \cup (B \cup C)$$

$$(A \cap B) \cap C = A \cap (B \cap C)$$

$$(A \oplus B) \oplus C = A \oplus (B \oplus C)$$

$$A - B \neq B - A$$

3. Distributive law :

$$A \cup (B \cap C) = (A \cup B) \cap (A \cup C)$$

$$A \cap (B \cup C) = (A \cap B) \cup (A \cap C)$$

5. Idempotent Laws :-

$$A \cup A = A$$

$$A \cap A = A$$

6. Identities :-

$$A \cup \emptyset = A, A \cup U = U, A \cup \bar{A} = U$$

$$A \cap U = A, A \cap \bar{A} = \emptyset, A - B = A \cap \bar{B}$$

7. Absorption law :-

$$A \cup (A \cap B) = A$$

$$A \cap (A \cup B) = A$$

8. Modular law :-

$$A \cup (B \cap C) = (A \cup B) \cap C \text{ iff } A \subseteq C$$

$$\Rightarrow (A \cup B) \cap (A \cup C) = (A \cup B) \cap C$$

$$A \cup C = C$$

$$A \subseteq C$$

$$A \cap (B \cup C) = (A \cap B) \cup C \text{ iff } C \subseteq A$$

Note : * $P(A \cap B) = P(A) \cap P(B)$

* $P(A \cup B) \neq P(A) \cup P(B)$

* $A - (A - B) = A \cap B$

* $A - (A \cap B) = A - B$

Ex: which of the following is not true?

a) If $A \subseteq \emptyset$, then $A = \emptyset$ — true

b) $B \cup (A \cap B) = B$ — true

$$A \cap B \subseteq B$$

c) $(A \cap B) \cup (A \cap B^c) = A$

| | |
|--|--|
| $L.H.S = A \cap (B \cup B^c)$ $= A \cap U$ $= A = R.H.S$ | $ (A \cdot B) + (A \cdot \bar{B})$ $= A \cdot (B + \bar{B}) = A$ |
|--|--|

d) $(A \cap B) \cup (A \cap B^c) \cup (A^c \cap B) \cup (A^c \cap B^c) = A \cup B$

$$\begin{aligned}
 & (A \cdot B) + (A \cdot \bar{B}) + (\bar{A} \cdot B) + (\bar{A} \cdot \bar{B}) \\
 &= A \cdot (B + \bar{B}) + \bar{A} \cdot (B + \bar{B}) \\
 &= A + \bar{A} \\
 &= 1 \\
 &= U \neq A \cup B \quad \text{--- False.}
 \end{aligned}$$

Ex: If $A \subseteq B$ then, which of the following is not true?

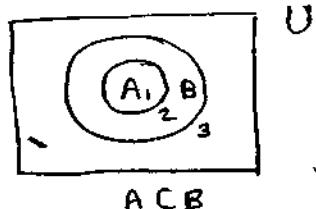
a) $B^c \subseteq A^c$

b) $A \cup B = B$

c) $A \cap B = A$

~~d) $A \cap B = A$~~

~~e) $B - A = \emptyset$~~



Ex: If $A \oplus B = (A - B) \cup (B - A)$ which is false?

a) $A \oplus A = \emptyset$

b) $A \oplus \emptyset = A$

c) $(A \oplus B) \oplus B = A$

$$L.H.S. = A \oplus (B \oplus B)$$

$$= A \oplus \emptyset$$

$$= A = R.H.S.$$

d) $A \oplus B = A$ iff $B = \emptyset$

$$\Rightarrow A \oplus B = A$$

$$A \oplus B = A \oplus \emptyset$$

~~or) $A \oplus B = (A \cap B^c) \cup (B \cap A^c)$~~

Ex: Let \emptyset be the empty set, then $|P\{P(\emptyset)\}| = ?$

$$\emptyset = \{\}$$

$$P(\emptyset) = \{\emptyset\}$$

$$P\{P(\emptyset)\} = \{\emptyset, \{\emptyset\}\}$$

$$|P\{P(\emptyset)\}| = 2$$

Ex: Consider $A = \{s \mid s \text{ is a set}\}$

$$B = \{s \mid s \text{ is a set and } s \notin s\}$$

which is true?

- a) A is a set and B is not a set
- b) B is a set and A ———
- c) Both A and B are sets
- ✓ d) Both A and B are not sets.

$\Rightarrow *$ Set of set is not set. (A set cannot be element of itself)

Ex: Let $A = \{1, 2, 3, 4, 5\}$ and $B = \{1, 3, 5, 7, 9\}$ are represented by the bit strings 1111100000 and

1010101010 resp. ($U = \{1, 2, 3, \dots, 10\}$)

$$= \{1111111111\} \quad \text{(missing bit 0)}$$

✓ a) $A \cup B = \begin{smallmatrix} 1 & 1 & 1 & 1 & 1 & 0 & 1 & 0 & 1 & 0 \\ 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 & 10 \end{smallmatrix}$

$$A \cup B = \{1, 3, 5, 2, 4, 7, 9\}$$

b) $A \cap B = \begin{smallmatrix} 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 1 & 3 & 5 \end{smallmatrix}$

$$A \cap B = \{1, 3, 5\}$$

✓ c) $A - B = \begin{smallmatrix} 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 2 & 4 \end{smallmatrix}$

$$A - B = \{2, 4\}$$

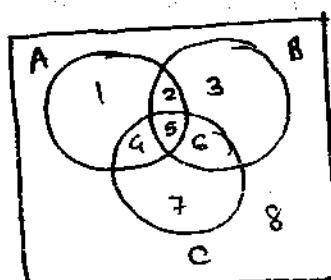
✓ d) $B^c = 0000011111$

$$B^c = \{2, 4, 6, 8, 10\}$$

$$= \begin{smallmatrix} 0 & 1 & 0 & 1 & 0 & 1 & 0 & 1 \\ 1 & 3 & 5 & 7 & 9 \end{smallmatrix}$$

Ex: Which is False?

$$\begin{aligned}
 a) \quad & \frac{(A - B) - C}{\downarrow} = \frac{(A - C) - (B - C)}{\downarrow} \\
 & \{1, 4\} - \{4, 5, 6, 7\} \\
 & = \{1\} \quad \quad \quad \{1, 2\} - \{2, 3\} \\
 & \quad \quad \quad = \{1\}
 \end{aligned}$$



True

$$b) (A - B) - C = (A - C) - B$$

$$\{1, 4\} - \{4, 5, 6, 7\} \quad \{1, 2\} - \{2, 3, 5, 6\}$$

$$= \{1\} \quad \quad \quad = \{1\}$$

TRUE

$$c) (A \cap B) - (B \cap C) = (A - (A \cap C)) - (A - B)$$

$$\{2, 5\} - \{5, 6\} \quad \left| \begin{array}{l} [\{1, 2, 4, 5\} - \{4, 5\}] - \{1, 4\} \\ = \{1, 2\} - \{1, 4\} \\ = \{2\} \end{array} \right.$$

TRUE

Multiset :- A unordered collection of object in which any object can appears more than ones is called Multiset.

$$\text{E.g. } \{a, a, b, b, b, c, c, c, c, d\} \\ = \{2a, 3b, 4c, d\}$$

$$\text{Let, } P = \{m_1 a_1, m_2 a_2, \dots, m_k a_k\}$$

where m_i = multiplicity of a_i

$$Q = \{n_1 a_1, n_2 a_2, \dots, n_k a_k\}$$

$P \cup Q$ = A multiset in which the multiplicity of $a_i = \max\{m_i, n_i\}$

$P \cap Q$ = _____ of $a_i = \min\{m_i, n_i\}$

$P - Q$ = A multiset of $a_i = \begin{cases} m_i - n_i & \text{if } m_i > n_i \\ 0 & \text{otherwise} \end{cases}$

$P + Q$ = A multiset of $a_i = m_i + n_i$

$$\text{Ex: } A = \{3a, 2b, 1c\}, B = \{2a, 3b, 4d\}$$

$$A \cup B = \{3a, 3b, 1c, 4d\}$$

$$A \cap B = \{2a, 2b\}$$

$$A - B = \{a, c\}$$

$$A + B = \{5a, 5b, 1c, 4d\}$$

Ex: The set $A = \{1, 2, 3, \dots, n\}$ then how many multisets are possible with the element A.

a) 2^n b) n^n c) $2^{(n^2)}$ d) unlimited

→ Each no. can appears many no. of times
∴ Multisets are unlimited.

Ex: If $A = \{1, 2, \dots, n\}$, then how many multisets of size 4 are possible with elements of A, so that at least one element appear exactly two.

$$\rightarrow \{a, b, c, d\} \quad \left[\begin{array}{l} \{a, a, b, c\} \\ \{a, a, b, b\} \end{array} \right]$$

Case 1 :- only one elements appears exactly twice

In this case the multiset is of the form $\{a, a, b, c\}$

$$\text{No. of multiset in this case} = {}^n C_3 \cdot 3C_1 \quad \text{or} \\ {}^n C_1 \cdot {}^{(n-1)} C_2$$

Case 2 :- Two elements appears exactly twice

$$\text{No. of Multisets in this case} = {}^n C_2$$

$$\begin{aligned}\text{Req. No. of multisets} &= {}^n C_3 \cdot 3C_1 + {}^n C_2 \\ &= \frac{n(n-1)(n-2)}{1 \cdot 2 \cdot 3} \times 3 + \frac{n(n-1)}{2} \\ &= \frac{n(n-1)^2}{2}\end{aligned}$$

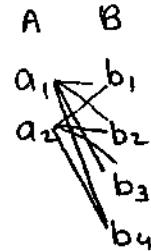
Cartesian Product :-

- If A and B are two sets, then the cartesian product of A and B defined as $A \times B = \{(a, b) | a \in A \text{ and } b \in B\}$
- If no. of elements in A is m and no. of elements in B is n then no. of elements in $A \times B$

$$|A \times B| = mn$$

$$= \text{In General } (A \times B) \neq (B \times A)$$

$$- \text{If } (A \times B) = (B \times A) \text{ then } A = B \text{ or } A = \emptyset \text{ or } B = \emptyset$$



Relation :-

- A and B are two sets then every subset of $(A \times B)$ is called a relation from A to B

$$A \times B = \{(a_1, b_1), (a_1, b_2), (a_1, b_3), (a_2, b_1), (a_2, b_2), (a_2, b_3)\}$$

$$\begin{array}{ccc} A & \rightarrow & B \\ a_1 & & b_1 \\ a_2 & & b_2 \\ & & b_3 \end{array}$$

* If $|A|=m$ and $|B|=n$, then
number of relations possible
from A to B = 2^{mn}

* A relation on set A to A is called a relation on A

* If $|A|=n$ then no. relations possible on A = 2^{n^2}

$$\begin{array}{ccc} A & \rightarrow & A \\ a_1 & & a_1 \\ a_2 & & a_2 \\ a_3 & & a_3 \end{array}$$

Inverse of a relation :-

If R is a relation from A to B , then

$R^{-1} = \{ \text{set of all order pairs } (b|a) | \text{for } (a,b) \in R \}$ is
a relation from B to A .

Complement of a relation :-

If R is a relation from A to B , then

$$\bar{R} = (A \times B) - R$$

Diagonal Relation :-

A relation R on set A is said to be diagonal relation.

$$\begin{aligned} \text{if } R &= \{(x,x) | x \in A\} \\ &= \Delta_A \end{aligned}$$

$$A \rightarrow A$$

$$a_1 \rightarrow a_1$$

$$a_2 \rightarrow a_2$$

$$a_3 \rightarrow a_3$$

$$R = \{(a_1, a_1), (a_2, a_2), (a_3, a_3)\}$$

Reflexive Relation :-

A relation R on set A is said to be reflexive if

$$x^R x \quad \forall x \in A$$

$$\text{i.e. } (x, x) \in R \quad \forall x \in A$$

* A diagonal relⁿ on set A is reflexive and every superset of diagonal relⁿ is also reflexive.

* Reflexive relⁿ may contains non-diagonal relⁿ.

Ex: $A = \{1, 2, 3\}$ then $R_1 = \{(1,1)(2,2)(3,3)\}$ — smallest reflex relⁿ

$$R_2 = \{(1,1), (2,2), (3,3), (1,2), (2,1)\}$$

(Δ_A)

$$R_3 = \textcircled{A} A \times A \quad \text{— Large reflex relⁿ}$$

Ex: If $A = \{1, \dots, n\}$ then no. of reflexive relⁿ possible on $A = ?$

$$\rightarrow \text{No. of non-diagonal pairs} = n^2 - n = n(n-1)$$

$$\text{No. of reflexive relⁿ possible} = 2^{n(n-1)}$$

- The relation \leq is reflexive on any set of real no.s.
- The relation \subseteq is reflexive on any collection of sets.
 - The relation 'divides' or 'is a divisor of' denoted by \mid is reflexive on any set of non zero real no.s.

IRREFLEXIVE RELATION :- A reln R on a set A is said to be irreflexive if $xRx \nabla x \in A$
i.e. $(x,x) \notin R \nabla x \in A$

Ex: $A = \{1, 2, 3\}$ then $R_1 = \{\emptyset, (1,2), (2,3), (3,2)\}$

- * Smallest irreflexive reln on A = \emptyset relation.
- * Largest ——— = $(A \times A) - \Delta_A$
- * If $A = \{1, \dots, n\}$ then no. of irreflexive reln = $2^{n(n-1)}$
- * The relations "is less than" and "is greater than" are irreflexive on set of all real no.s.
- * $R = \{(1,1), (2,3)\}$ on $A = \{1, 2, 3\}$ is ~~not~~ neither reflexive nor irreflexive.

Symmetric Relation :- A reln R on a set A is said to be symmetric if (xRy) and (yRx) $\nabla x, y \in A$. That is if $(x,y) \in R$ then $(y,x) \in R \nabla x, y \in A$. $\rightarrow y$ related to x

- Ex: If $A = \{1, 2, 3\}$ then $R = \{(1,1), (3,3), (1,2), (2,1)\}$ is a symmetric reln on A.

$R = \{(1,2), (2,1), (1,3)\}$ is not symmetric because $(1,3) \in R$ but $(3,1) \notin R$.

- * Smallest reln on A = Empty reln (\emptyset)
- * Largest ——— = $A \times A$
- * If $A = \{1, \dots, n\}$ then no. of symmetric relations are possible on A = $2^n \cdot 2^{\binom{n(n-1)}{2}} / 2$
 $= 2^{\binom{n(n+1)}{2}} / 2$
- * The relation x is "a complement of y " is symmetric in Boolean algebra.
- * The relation x is "perpendicular to" is symmetric for any two lines in a plane.
- * The relation x is "brother of" is symmetric for any

- Antisymmetric Relation :- A relation R on a set A is said to be antisymmetric if $(a,b) \in R$ and $(b,a) \in R$ then $a=b$
- * if R is not antisymmetric if there exists $a,b \in A$ such that $(a,b) \in R$ and $(b,a) \in R$ but $a \neq b$.
 - * In antisymmetric relⁿ only one of the pair of (x,y) or (y,x) can be present or both of the pairs may be present absent.
- Eg: if $A = \{1, 2, 3\}$ then $R = \{(1,1), (2,2), (2,1), (2,3)\}$
is a Antisymmetric relation.

- * smallest Antisymmetric relⁿ on A = Empty set \emptyset .
 - * No. of elements in a largest antisymmetric selection on $A = \frac{n(n+1)}{2} \quad (n(n+1)/2)$
 - * The relⁿ is $a \leq b$ and $b \leq a$ then $a=b$ is antisymmetric relⁿ on the set of all real no.
 - * if $A = \{1, \dots, n\}$ the no. of antisymmetric relⁿ possible on A
 $= 2^n \cdot 3^{\frac{[n(n-1)]}{2}}$
 - * $R = \{(1,1), (2,3)\}$ — symmetric also anti-symmetric.
 - * $R = \{(1,1), (2,2), (3,3), (1,2), (2,3), (3,1)\}$ — largest antisymmm.
- $\rightarrow \{(x,y) \leftarrow \begin{cases} (x,y) \\ (y,x) \\ - \end{cases}\right\} \quad \begin{array}{l} 3 \text{ possibilities} \\ \text{with non-diagonal pairs} \end{array}$

Ex: If $A = \{1, 2, 3\}$ then how many relⁿ on A are not antisymmetric.

$$\begin{aligned} \rightarrow &= 2^{(n^2)} - 2^n \cdot 3^{\frac{n(n-1)}{2}} \quad \text{where } n=3 \\ &= 2^9 - 2^3 \cdot 3^3 \\ &= 512 - 216 \\ &= 296 \end{aligned}$$

- * The relⁿ \leq is antisymmetric on any set of real no-s.
- * The relⁿ \subseteq is antisymmetric on any collection of sets.
- * The relⁿ $|$ is antisymmetric on any set of five integers.

Asymmetric Relation :- A relation R on a set A , is said to be asymmetric if (xRy) then $(yRx) \notin R$, $x, y \in A$. i.e. if $(x, y) \in R$ then $(y, x) \notin R$, $x, y \in A$.

* Every asymmetric relation is also antisymmetric.

* In asymmetric relation diagonal pairs are not allowed whereas in antisymmetric relation diagonal pairs can be present.

Ex: If $A = \{1, 2, 3\}$ then $R_1 = \{\}$ — smallest

$$R_2 = \{(1, 2), (2, 3)\}$$

$$R_3 = \{(1, 2), (3, 2), (1, 3)\}$$

* If $A = \{1, \dots, n\}$ then no. of asymmetric relations possible on $A = 3^{\frac{n(n-1)}{2}}$

* The relation $<$ is asymmetric on any set of real no.s.

* $\text{---} \parallel \text{---} > \text{---} \parallel \text{---} \parallel \text{---} \parallel \text{---}$.

Transitive Relation :- A relation R on a set A is said to be transitive if $(xRy \text{ and } yRz) \Rightarrow (xRz)$, $x, y, z \in A$.

\downarrow
 x related to z

* The relation \leq is transitive on any set of real no.s.

* $\text{---} \parallel \text{---} |$ is $\text{---} \parallel \text{---} \parallel \text{---}$.

* $\text{---} \parallel \text{---} \subseteq$ is $\text{---} \parallel \text{---}$ collection of sets.

Ex: If $A = \{1, 2, 3\}$ then $R_1 = \{\}$ — smallest

$$R_2 = \{(1, 1), (2, 2)\}$$

$$R_3 = \{(1, 2), (2, 3), (1, 3)\}$$

$$R_4 = A \times A — \text{largest.}$$

$$R_5 = \{(1, 2), (2, 1), (1, 1), (2, 2)\}$$

Ex: If $A = \{1, 2\}$ then no. of transitive reln possibles on $A = ?$

\rightarrow Reln which are not transitive are $R_1 = \{(1, 2), (2, 1)\}$

$$R_2 = \{(1, 2), (2, 1), (1, 1)\}$$

$$R_3 = \{(1, 2), (2, 1), (2, 2)\}$$

\therefore Transitive relⁿ = $2^{n^2} - 3$

$$\begin{aligned}&= 2^4 - 3 \\&= 16 - 3 \\&= 13\end{aligned}$$

Equivalence Relation :- A relⁿ R on a set A is said to be an equivalence relⁿ if R is reflexive, transitive and symmetric.

Ex: If $A = \{1, 2, 3\}$ then how many equivalence relⁿ are possible on A = ?

$\rightarrow R_1 = \{(1,1)(2,2)(3,3)\}$ — smallest equivalence relⁿ on A
 $R_2 = \{(1,1)(2,2)(3,3), (1,2)(2,1)\}$
 $R_3 = \{(1,1)(2,2)(3,3), (2,3), (3,2)\}$
 $R_4 = \{(1,1)(2,2)(3,3), (1,3), (3,1)\}$
 $R_5 = A \times A$ — largest equivalence relⁿ of A.

\therefore 5 equivalence relⁿ are possible.

Ex: If $A = \{1, 2, 3, 4\}$ then no. of equivalence relⁿ possible on A = ?

$\rightarrow 15$.

Ex: A relⁿ R on set of all real no. is defined by

$xRy \Leftrightarrow (x-y)$ is integer then R is an equivalence relation.

\rightarrow 1) we have $x-x=0$, an integer

$$\Rightarrow xRx \quad \forall x$$

$\therefore R$ is reflexive.

2) Let xRy

$$\Rightarrow (x-y)$$
 is an integer

$$\Rightarrow (y-x) \quad \text{---} \quad \text{---}$$

$$\Rightarrow yRx$$

$\Rightarrow R$ is symmetric

3) Let xRy and yRz

$$\Rightarrow (x-y) \text{ & } (y-z) \text{ is an integer}$$

$$\text{Now, } (x-z) = (x-y) + (y-z)$$

$$\Rightarrow (x-z) \text{ is an integer}$$

Ex: A reln R on set of all integers is defined by

$xRy \Leftrightarrow (x-y)$ is an even no. then R is an equivalence reln.

Ex: A reln R on set of all integers is defined by

$xRy \Leftrightarrow (x-y)$ is divisible by 5 then R is an equivalence reln.

Partial ordering relation :-

A relation R on a set A is said to be partial ordering relation if R is reflexive, antisymmetric, and transitive.

Partially ordered set (Poset) :- A set 'A' with partial ordering relation R defined on A, is called Poset and denoted by $[A; R]$

Ex: If A

- * The relation \leq is a partial ordering relation, on any set of real no.s A. i.e. $[A; \leq]$ is a poset.
- * The relation $|$ is a partial ordering reln on any set of the integers no.s. i.e. $[A; |]$ is a poset.
- * The relation \subseteq is a partial ordering reln on any collection of sets 'S' i.e. $[S; \subseteq]$ is a poset.

Totally ordered set :- A poset $[A; R]$ is called totally ordered set, if every pair of elements are comparable w.r.t. R.
- Also called as linearly ordered set or chain.

i.e. aRb or bRa $\forall a, b \in A$

Ex: If A is any set of real no. then the poset $[A; \leq]$ is a totally ordered set.

Ex: Let $A = \{1, 2, 3, \dots, 10\}$ then poset $[A; |]$ is not a totally ordered set.

Ex: ————— A = {1, 4, 8, 16, 32} ————— " ————— " is a totally ordered set.

Ex: If $A = \{1, 2\}$ then the poset $[P(A); \subseteq]$ is not a totally ordered set

$$\rightarrow P(A) = \{\emptyset, \{1\}, \{2\}, \{1, 2\}\}$$

not comparable

Ex: If $A = \{\emptyset, \{1\}, \{1, 2\}, \{1, 2, 3\}\}$ ^{the} poset $[S; \subseteq]$ is a totally ordered set.

x: Let $A = \{1, 2, 3\}$ R_1, R_2, R_3, R_4 are relations on A. which of the following is false?

- a) $R_1 = \{(1, 1), (3, 3)\}$ is symmetric and antisymmetric.
- b) $R_2 = \{(1, 2), (2, 1), (3, 2)\}$ is neither symmetric nor antisymmetric.
- c) $R_3 = \{(1, 2), (2, 3), (3, 2)\}$ is not symmetric but antisymmetric.
- d) $R_4 = \{(1, 2), (2, 1), (3, 3)\}$ is symmetric but not antisymmetric.

\therefore All stat. are true.

Ex: A reln R on a set $A = \{1, 2, 3, 4\}$ is given by

$$R = \{(1, 1), (2, 1), (2, 2), (2, 3), (2, 4), (3, 1), (3, 2), (3, 3), (3, 4)\}$$

is —

- (a) equivalence Relation
- (b) irreflexive, symmetric, transitive
- (c) irreflexive, symmetric, antisymmetric
- (d) Transitive

not becoz $(2, 2)$ diagonal present

\downarrow not
for $(2, 1)$

\downarrow not
 $(1, 2)$ not present

\downarrow not becoze $(2, 3)$ $(3, 2)$

Ex: Relation R on set of all integers is defined by

$a^R b \Leftrightarrow b = ak$ for some tve integer k. then which is true?

- (a) R is an equivalence relation
- (b) R is a partial ordering reln
- (c) R is total ordering reln
- (d) R is a compatibility reln

\hookrightarrow reflexive & symmetric but not transitive

→ i) we have, $a \equiv a$

$$\Rightarrow aRa \forall a$$

$\Rightarrow R$ is reflexive

Rel^n is not symmetric on set of all integers

Ex: $8R_2$ but $2R_8$ not

$$\Downarrow \\ 2^3 = 8 \text{ but } 2 = 8?$$

2) Let aRb and bRa

$$\Rightarrow b = a^{k_1} \text{ and } a = b^{k_2} \quad \text{--- (1)}$$

$$\Rightarrow a = (a^{k_1})^{k_2}$$

$$a = a^{k_1 k_2}$$

$$\Rightarrow k_1 k_2 = 1$$

$$\Rightarrow k_1 = 1 \text{ & } k_2 = 1$$

$\therefore b = a$ and $a = b$ (from (1))

$\therefore R$ is antisymmetric.

3) $b = a^{k_1}$ and $c = b^{k_2} \quad \text{--- (1)}$

$$\Rightarrow c = a^{k_1 k_2}$$

$$\Rightarrow aRc$$

$\therefore R$ is transitive.

The given rel^n is not a total order.

Ex: $2R_3 \notin 3R_2$

Ex: If $A = \{a, b, c\}$ then $R_1 = \{(a, a), (b, b), (c, c), (a, b), (b, a), (b, c), (c, b)\}$

is compatibility relation.

Ex: If $A = \{\text{cat, bat, book, dog}\}$ then $\text{rel}^n R$ on A is defined by word₁ R word₂ \Leftrightarrow The two words have a common letter

then R is compatibility rel^n on P(A) .

→

cat R bat and bat R book

but cat R book (no common letters)

Ex: which of the following statements is not true?

- a) If a reln R is symmetric and transitive then it is
Reflexive — FALSE

→ If $A = \{1, 2, 3\}$ then

$$R = \{(1,1), (2,2), (1,2), (2,1)\}$$

Symmetric, transitive but not reflexive.

- b) If R is reln on A is irreflexive and transitive then R is
antisymmetric. — TRUE

$$A = \{1, 2, 3\}$$

$$R = \{\}$$

→ Let R is irreflexive and transitive but not antisym.

Let $(x,y) \in R$ and $(y,x) \in R$
(if R is not antisym. then we get two pairs (x,y) and
 $\boxed{(y,x)} \in R$)

⇒ $(x,x) \in R$ — by transitivity

⇒ R is not irreflexive.

which is contradiction.

∴ given stat. is true.

- c) If R is antisymmetric relation on A, then $(R \cap S)$ is also
antisymmetric for any reln S on A. — TRUE

→ $R = \{(1,1), (2,3), (3,1)\}$

Every subset of antisym. is antisym.

$$(R \cap S) \subseteq R$$

∴ $R \cap S$ is also antisym.

- d) If R is reflexive then \bar{R} is irreflexive. — TRUE

→ $\bar{R} = (A \times A) - R$

Ex: which of the following stat. is not true?

a) If R and S are reflexive relⁿ on A, then (RNS) and (RUS) are reflexive $\rightarrow \underline{\text{TRUE}}$

\rightarrow for (RNS) & (RUS) — diagonal pairs are present.

b) If R and S are anti symmetric then (RUS) & (RNS) are also symmetric. $\rightarrow \underline{\text{TRUE}}$

$$R = \{(a,b), (b,a)\}$$

$$S = \{(a,b), (b,a), (a,c), (c,a)\}$$

$$RNS = R$$

$$RUS = \{\text{all}\}$$

\therefore symmetric.

c) If R and S are transitive then (RUS) & (RNS) are transitive.

$$\rightarrow R = \{(a,b)\} \rightarrow \text{always transitive}$$

$\hookrightarrow \underline{\text{FALSE}}$

$$S = \{(b,c)\}$$

$$RUS = \{(a,b), (b,c)\}$$

\downarrow
(a,c) absent

\therefore RUS is not transitive

$$RNS = \{\} \rightarrow \text{transitive}$$

d) If R and S are antisym. relⁿ on A, then (RUS) need not be antisym. but (RNS) is always antisym.

$$\rightarrow R = \{(a,b)\}$$

$$S = \{(b,a)\}$$

$$RUS = \{(a,b), (b,a)\} \rightarrow \text{Not antisym.}$$

$$RNS = \{\} \rightarrow \text{antisym.}$$

Transitive closure :- Let R be any reln on set A

Transitive closure of R is denoted by R^* is defined by = the smallest transitive reln on A which contains R .

Ex: Let $A = \{1, 2, 3\}$ and $R = \{(1, 2), (2, 3)\}$

then $R^* = \{(1, 2), (2, 3), (1, 3)\}$

If R is transitive reln then $R^* = R$

Reflexive closure :-

Reflexive closure of $R = R^{\#}$

= The smallest reflexive relation on A which contain R
 $= R \cup \Delta_A$

Ex: $A = \{1, 2, 3\}$

$R = \{(1, 2), (2, 3)\}$

then $R^{\#} = \{(1, 2), (2, 3), (1, 1), (2, 2), (3, 3)\}$

Symmetric closure :-

Symmetric closure of $R = R^{\oplus+}$

= The smallest symmetric reln on A which contain R .

$= R \cup R^{-1}$

Ex: $A = \{1, 2, 3\}$

$R = \{(1, 2), (2, 3)\}$

then $R^+ = \{(1, 2), (2, 3), (2, 1), (3, 2)\}$

Note :-

① Symmetric closure of reflexive closure closure of R :-

= Reflexive closure of symmetric closure of R .

Ex: $A = \{1, 2, 3\}$

$R = \{(1, 2), (1, 1), (2, 2), (3, 3)\}$ — Reflexive

— Symmetric

② Transitive closure of the reflexive closure of R

= Reflexive closure of the transitive closure of R

$$\text{Ex: } A = \{1, 2, 3\}$$

$$R = \{(1,2), (2,3)\}$$

$$R_1 = \{(1,2), (2,3), (1,3)\} \text{ --- transitive}$$

$$R_2 = \{(1,1) (2,2) (3,3) (1,2) (2,3) (1,3)\}$$

--- Reflexive clos. of trans. closure

- ③ Transitive closure of the symmetric closure of R need not be symmetric closure of the transitive closure of R.

$$\text{Let } A = \{1, 2, 3\}$$

$$R = \{(1,2) (2,3)\}$$

$$\begin{aligned} L.H.S. &= \{(1,2) (2,3) (2,1) (3,2) (1,3) (3,1) \\ &\quad (1,1) (2,2) (3,3)\} \end{aligned}$$

$$= A \times A$$

$$R \cdot H \cdot S = \{(1,2) (2,3) (1,3)\} \text{ --- transitive}$$

$$= \{(1,2) (2,3) (1,3) (2,1) (3,2) (3,1)\}$$

↳ symm. clos. of transitive clo

$$\neq A \times A$$

$$LHS \neq RHS$$

- Ex: $R = \{(x,y) \mid y = x+1 \text{ and } (x,y) \in \{0, 1, 2, \dots, \infty\}\}$
 then the reflexive transitive closure of R = ?

$$\rightarrow R = \{(0,1), (1,2), (2,3), (3,4), \dots\}$$

$$(0,2), (0,3), (0,4), \dots$$

$$(1,3), (1,4), (1,5), \dots$$

$$(2,4), (2,5), (2,6), \dots$$

$$(0,0), (1,1), (2,2), (3,3), \dots$$

$$\therefore \{(x,y) \mid y \geq x \text{ and } (x,y) \in \{0, 1, 2, \dots\}\}$$

Ex: Let $A = \{1, 2, 3\}$ and a relation R on A is defined by

$R = \{(1,1), (1,3), (2,2), (3,1), (3,2)\}$ then transitive

closure of R is —

→ The matrix corresponding to given relⁿ is

Warshall's
Algorithm

$$\begin{matrix} & \begin{matrix} 1 & 2 & 3 \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \end{matrix} & \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 1 & 0 \end{bmatrix} \xrightarrow{+(3,3)} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix} \end{matrix}$$

| Column | I | II | III |
|--------|------------|---------|---------------|
| Row | $\{1, 3\}$ | $\{2\}$ | $\{1, 2, 3\}$ |

| | | |
|-------|------------|---------------------------------|
| (1,1) | $\{2, 3\}$ | $\{1, 3\} \{1, 2, 3\} \{1, 3\}$ |
| (1,3) | $\{3, 2\}$ | $\{3, 1, 3\} \{3, 2\} \{3, 3\}$ |
| (3,1) | | |
| (3,3) | | |

$$\therefore R^* = \{(1,1), (1,3), (2,2), (3,1), (3,2), (3,3), (1,2)\}$$

$$= (AXA) - \{(2,1), (2,3)\}$$

Ex: Let $A = \{a, b, c, d\}$ and relⁿ R on the set A is defined by $R = \{(a,d), (b,a), (b,c), (c,c), (d,a), (d,c)\}$ find transitive closure of R .

$$\rightarrow \text{Matrix} = \begin{matrix} a & b & c & d \\ \begin{matrix} a \\ b \\ c \\ d \end{matrix} & \begin{bmatrix} 0 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} & \xrightarrow{\substack{+\{b|d\} \\ +\{d|a\} \\ +\{d|d\}}} & \begin{bmatrix} 0 & 0 & 0 & 1 \\ 1 & 0 & 1 & 1 \\ 1 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix} \end{matrix}$$

| Column | I | III | II | IV | |
|--------|----------------------|------------------------------|---------------------------------------|--------------------------------------|------------------|
| Row | $\{b, c\}$ | $\{b d\}$ | $\{3\}$ | $\{a e\}$ | $\{a, b, c, d\}$ |
| | $\checkmark \{b d\}$ | $\{b a\} \{d a\} \checkmark$ | $\{a, c\} \{a, a\} \{a, c\} \{a, d\}$ | $\{a, c\} \{b, a\} \{b, c\} \{b d\}$ | |
| | $\{c, d\}$ | $(b d) (d d)$ | $\{c, c\} \{c, d\} \{d, a\}$ | $\{c, a\} \{c, d\} \{d, d\}$ | |

$$R^* = \{(a,d), (b,a), (b,c), (c,c), (c,d), (d,a), (d,c), (a,c), (d|a), (d|d), (c,c)\}$$

Equivalence classes :- Let R be an equivalence Reln for a set A , for any element $x \in A$, equivalence class of A denoted by $[x]$, is defined as

$$[x] = \{y | y \in A \text{ and } x R y\}$$

Note : * We can have $[x] = [y]$ even though $x \neq y$

* Set of all distinct equivalence classes of A define a partition of A .

Partition of a set :- Let A be a set with n -elements ($n > 2$) A subdivision of A , $\{A_1, A_2, \dots, A_k\}$ into nonempty and non overlapping subset is called a partition

$$\text{if } A_1 \cup A_2 \cup A_3 \cup \dots \cup A_k = A$$

$$\text{Ex: } A = \{1, 2, 3, 4, 5\}$$

$$P_1 = \{(1, 2), (3, 4), (5)\}$$

(No common element is present).

Ex: An equivalence relation on the set $A = \{a, b, c, d, e, f\}$ is defined by $R = \{(a, a), (b, b), (c, c), (d, d), (e, e), (f, f), (a, d), (d, a), (a, e), (e, a), (b, c), (c, b), (b, e), (e, b), (c, d), (d, c)\}$
Find partition of A defined by R .

$$\begin{aligned} \rightarrow [a] &= \{a, b, d\} \quad \{a, f\} \\ [b] &= \{b, e\} \quad \{b, e\} \\ [c] &= \{c\} \\ [d] &= \{d\} \\ [e] &= \{e\} \quad \{e, b\} \\ [f] &= \{a, f\} \end{aligned}$$

distinct

$$\text{Required partition} = \{(a, f), (b, e), (c), (d)\}$$

Ex: Let $A = \{1, 2, 3, 4, 5\}$ and a partition of A is given as

$$P = \{(1, 3), (2, 5), (4)\}$$

w.r.t. P .

$$\rightarrow R = \{(1, 3) \times (1, 3), (2, 5) \times (2, 5), (4) \times (4)\}$$

$$R = \{(1, 1), (1, 3), (3, 1), (3, 3), (2, 2), (2, 5), (5, 2), (5, 5), (4, 4)\}$$

Ex: Let A = set of real no.s, An equivalence reln R on A is defined by $xRy \Leftrightarrow (x-y)$ is an even no. then
 $[1] = ?$

$$\rightarrow [x] = \{ y | (x-y) \text{ is an even no.} \}$$

$$[1] = \{ y | (1-y) \text{ is } \text{---} \text{---} \}$$

$$= \{ \pm 1, \pm 3, \pm 5, \dots \}$$

= set of all odd numbers.

$$[2] = \{ y | (2-y) \text{ is } \text{---} \text{---} \}$$

$$= \{ 0, \pm 2, \pm 4, \pm 6, \dots \}$$

= set of even no.s.

Ex: Let A = set of real no.s, An equivalence reln R on A is defined by $xRy \Leftrightarrow (x-y)$ is integer then
i) what is the equivalence class of 1?

$$\text{i)} [1] = ?$$

$$\rightarrow [x] = \{ y | x-y \text{ is integer} \}$$

$$[1] = \{ y | (1-y) \text{ is integer} \}$$

= set of all integers

$$[1/2] = \{ y | (1/2-y) \text{ is integer} \}$$

$$= \{ \pm 1/2, \pm 3/2, \pm 5/2, \dots \}$$

= odd multiple of $1/2$

$$= \{ (m+1/2) | m \text{ is any integer} \}$$

Ex: Let A = set of all integers

$xRy \Leftrightarrow (x-y)$ is divisible by 3. How many distinct equivalence classes are possible on A w.r.t R ?

$$\rightarrow [x] = \{ y | (x-y) \text{ is divisible by 3} \}$$

$$[0] = \{ \dots -9, -6, -3, 0, 3, 6, 9, \dots \}$$

$$[1] = \{ \dots -8, -5, -2, 1, 4, 7, 10, \dots \}$$

$$[2] = \{ \dots -7, -4, -1, 2, 5, 8, 11, \dots \}$$

$$A = \{1, 2, 3\}$$

$$P(A) = \{\emptyset, \{1\}, \{2\}, \{3\}, \{1, 2\}, \{1, 3\}, \{2, 3\}, A\}$$

Lattice Properties :- A lattice is denoted by $[L, U, \cap]$
 $\forall a, b, c \in L$

$$\begin{array}{ll} 1) a \cup b = b \cup a & 2) (a \cup b) \cup c = a \cup (b \cup c) \\ a \cap b = b \cap a & (a \cap b) \cap c = a \cap (b \cap c) \end{array}$$

$$\begin{array}{ll} 3) a \cup a = a & 4) a \cup (a \cap b) = a \\ a \cap a = a & a \cap (a \cup b) = a \\ b \cup (b \cap a) = b & \\ b \cap (b \cup a) = b & \end{array}$$

$$5) \text{ In a lattice } L, a \cup b = b \iff (a \cap b) = a \quad \forall a, b \in L$$

Sub lattice : Let $[L, U, \cap]$ be a lattice. A subset M of L is called a sublattice of L if

- i) $[M, U, \cap]$ is a lattice
- ii) LUB of (GLB) of any two elements a and b of M is same as LUB of a and b in L .

Distributive lattice : A lattice L is said to be distributive if

$$\begin{aligned} a \cup (b \cap c) &= (a \cup b) \cap (a \cup c) \\ a \cap (b \cup c) &= (a \cap b) \cup (a \cap c) \end{aligned} \quad \forall a, b, c \in L$$

Bounded lattice : Let M be lattice w.r.t. Reln R
if there exist an element $I \in L$ such that
 $a R I \quad \forall a \in L$ then I is called upper bound of L

Similarly, if there exist element $O \in L$ such that
 $O R a \quad \forall a \in L$ then O is called lower bound of L

In a lattice L if upper bound and lower bound exists then it is called Bounded Lattice.

- In a bounded lattice the upper bound (and lower bound) is unique.

In a bounded lattice L , following properties hold good :-

$$\begin{array}{l} \blacksquare a \cup I = I \\ a \cap I = a \end{array} \quad > \forall a \in L$$

$$\begin{array}{l} a \cup 0 = a \\ a \cap 0 = 0 \end{array} \quad > \forall a \in L$$

Complement :- Let L be a bounded lattice for element $a \in L$ if there exists an element $b \in L$ such that $a \cup b = I$ \wedge $a \cap b = 0$ then b is called complement of a .

* In a lattice complement of an element may or may not exists and need not be unique if exists.

Complemented Lattice :- In a lattice if each element has a complement, then it is called complemented lattice.

* In a complemented lattice each element has atleast one complement.

* In a distributive lattice complement of element if exists, then it is unique.

* In a distributive lattice each element has atmost one complement.

Boolean Algebra :- If a lattice is distributive and complemented then it is called Boolean algebra / Boolean lattice.

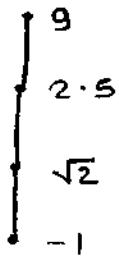
* In a Boolean Algebra each element has unique complement.

Hasse Diagram (Poset Diagram) :-

Let $[A; R]$ be a finite poset on the hasse diagram of A ,

- if
 - 1) There is a vertex corresponding to each element of A
 - 2) An edge betw two elements a and b is not present iff there is an element x such that aRx and xRb
 - 3) An edge betw a and b is present iff aRb and there is no element x such that aRx and xRb .

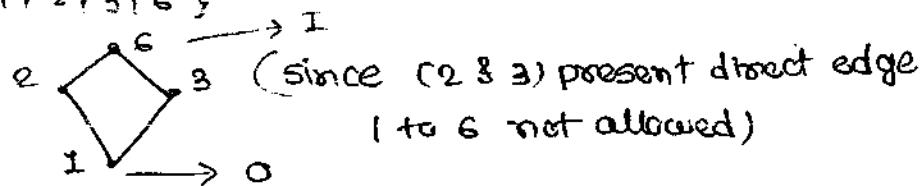
Ex: Draw Hasse dia. for the poset $[A, \leq]$ where $A = \{-1, \sqrt{2}, 2, 5, 9\}$



* In a total divided set complement exists only for lower bound and upper bound (Not a complemented lattice).

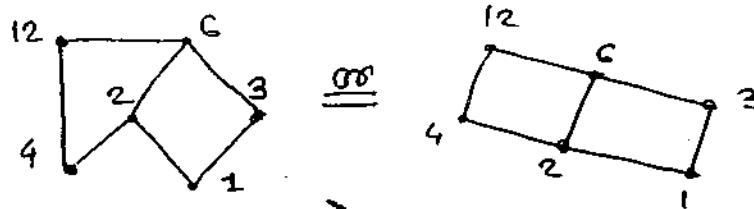
Ex: Draw Hasse dia. for the poset $[D_6; |]$ where

$$D_6 = \{1, 2, 3, 6\}$$



Ex: Draw Hasse Dia. for $[D_{12}; |]$

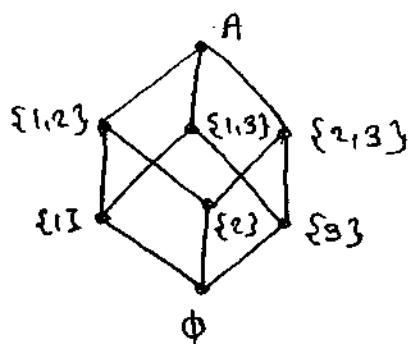
$$D_{12} = \{1, 2, 4, 3, 6, 12\}$$



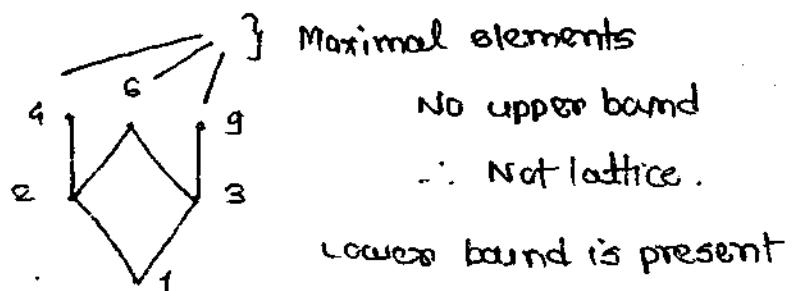
Ex: Draw Hasse Dia. $[P(A); \subseteq]$

where $A = \{1, 2, 3\}$

$$P(A) = \{\emptyset, \{1\}, \{2\}, \{3\}, \{1, 2\}, \{1, 3\}, \{2, 3\}, A\}$$



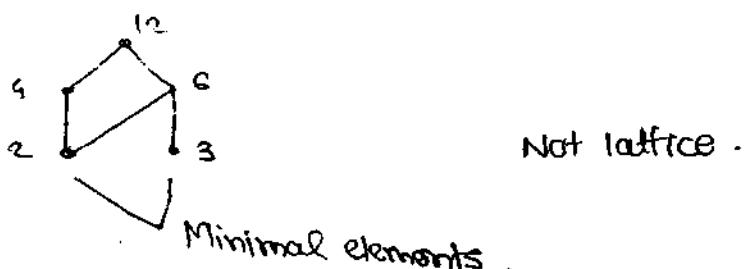
Ex: Draw the Hasse Dia. for $\{1, 2, 3, 4, 6, 9, 12\}$ w.r.t. ' $|$ '.



GLB exists for every pair of elements

\therefore It is meet semi-lattice.

Ex: Draw Hasse dia. for $\{2, 3, 4, 6, 12\}$ w.r.t. ' $|$ '.

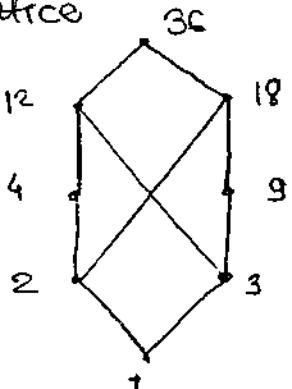


But it is join semi lattice

Ex: The poset $\{1, 2, 3, 4, 9, 12, 18, 36\}$ w.r.t. ' $|$ ' is —

a) a join semi lattice b) a meet semi lattice

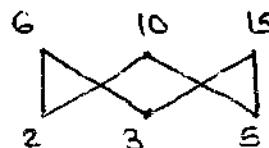
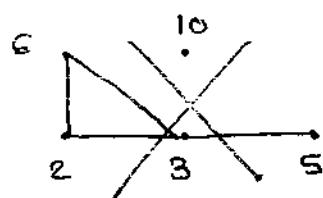
~~c) a lattice~~ ~~d) lattice~~



Not lattice
for 2 & 3 no LUB.
whenever there are cross
edges it is not lattice.

Ex: The poset $\{2, 3, 6, 10, 15\}$ w.r.t. $|$ is

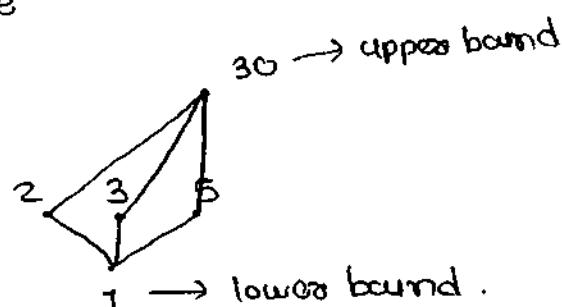
- a) a join semi lattice but not a meet semi lattice
- b) a meet semi lattice but not a join semi lattice
- c) a lattice
- d) not a semi lattice



3 - Minimal
3 - Maximal element
.. it is not a lattice

Ex: The poset $\{1, 2, 3, 5, 30\}$ w.r.t. $|$

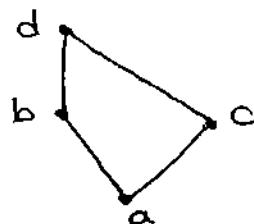
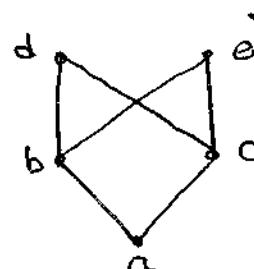
→ is a lattice



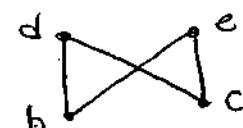
Ex: Consider the poset $P = \{a, b, c, d, e\}$ shown below

which of the following is false?

- a) P is not a lattice.
- b) The subset $\{a, b, c, d\}$ of P is a lattice.



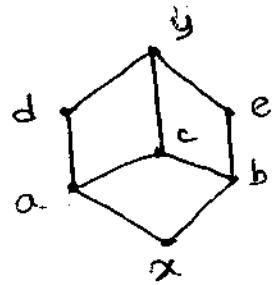
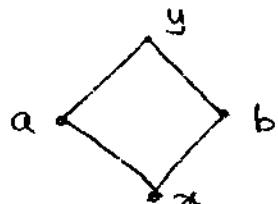
- c) The subset $\{b, c, d, e\}$ of P is a lattice.
- d) The subset $\{a, b, c, e\}$ of P is a lattice.



Ex: Consider lattice $L = \{x, a, b, c, d, e, y\}$ shown below.

which of the following subsets of L are sub lattice of L .

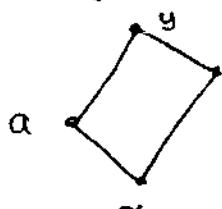
a) $L_1 = \{x, a, b, y\}$



\therefore Not sublattice because

LUB in this lattice is y but in given diagram it is 'c'
of $a \sqcup b$

b) $L_2 = \{x, a, e, y\}$

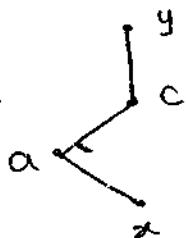


LUB of $a \sqcup e$ is y

$\therefore L_2$ is sublattice

for every pair of elements in L_2 LUB & GLB exists
and they are same as original lattice.

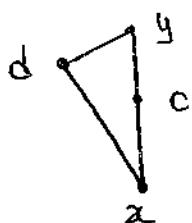
c) $L_3 = \{x, a, c, y\}$



It is a lattice

L_3 is sublattice of L , because for element
 $a \sqcup c$ LUB & GLB are same as L .

d) $L_4 = \{x, c, d, y\}$



Not sublattice

because for $d \sqcup c$ GLB is not same
as given lattice.

In L it is 'a' and in this dia. it is 'x'.

Ex: which of the following is not true?

- The upper bound of the lattice $[D_n; 1]$ is n where n is a +ve integer.
- The lower bound of the lattice $[D_n; 1]$ is 1 where n is a +ve integer.

c) The lower bound of the lattice $[P(A); \subseteq]$ is \emptyset where A is a finite set.

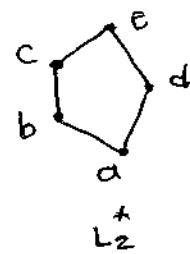
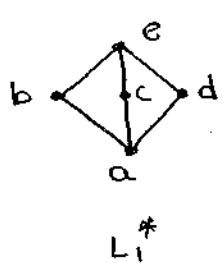
d) The upper bound of the lattice $[P(A); \subseteq]$ is A where A is a finite set.

Ans The upper bound of the lattice $[N; \leq]$ is ∞ where $N = \{1, 2, 3, \dots, \infty\}$.

It is false because upper bound not exist and ∞ is not +ve integers

f) The lower bound of the lattice $[N; \leq]$ is 1 where $N = \{1, 2, 3, \dots, \infty\}$

Ex: Which of the following is not a distributive lattice?



$$\begin{aligned} b \cup (c \cap d) &= (b \cup c) \cap (b \cup d) \\ b \cup a &\quad | \quad e \neq e \\ b &\neq e \\ L_1^* &\text{ Not distributive} \end{aligned}$$

\therefore Not distributive lattices.

For L_2^* ,

$$\begin{aligned} b \cup (c \cap d) &= (b \cup c) \cap (b \cup d) \\ b \cup a &\quad | \quad c \neq e \\ b &\neq c \\ L_2^* &\text{ also not distributive.} \end{aligned}$$

Theorem: A lattice L is not distributive iff L has a sublattice which is isomorphic to L_1^* or L_2^* .

Ex: which of the following lattice is NOT distributive?

a) $[P(A); \subseteq]$ where A is any finite set.

→ The elements of the power sets are sets. and for any ³ sets the distributive law holds good

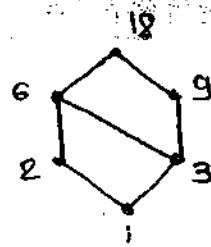
b) Every totally ordered set is a distributive lattice.

→ A totally ordered set can not have sublattice which is

c) $[D_{18}; \sqcup]$

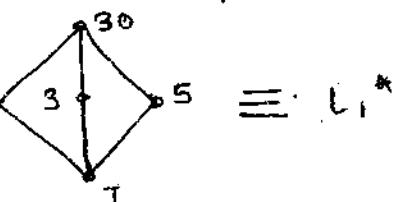
$$= \{1, 2, 3, 6, 9, 18\}$$

is a distributive lattice.



d) $[S_1, 2, 3, 5, 30; \sqcup]$

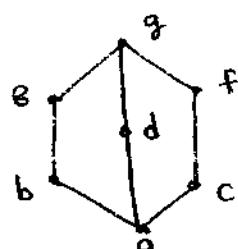
\therefore Not distributive. L_1^*



Ex: A lattice $L = \{a, b, c, d, e, f, g\}$ is shown below. How many complements does the element 'b' has?

- a) 1 b) 2 c) 3 d) 4

The complements of b are d, c, f.

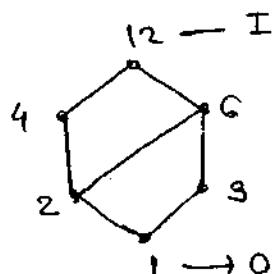


The complements of d are 4 i.e. b, c, e, f.

Note: The given lattice is a complemented lattice but not a distributed lattice.

Ex: For the lattice $[D_{12}; \sqcup]$, which of the following is not true?

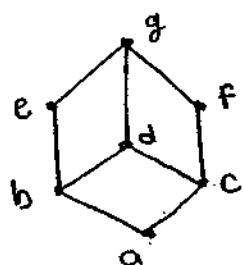
- a) Complement of 3 = 4
 b) $\neg\neg 1 = 1$
 c) $\neg\neg 1 = 1 = 12$
 d) $\neg\neg 1 = 6$ does not exist.



It is distributive lattice but not complemented lattice.

Ex: For the lattice shown below which of the following is true?

- a) distributive but not complemented
 b) Boolean algebra
 c) complement but not distributive



→ In a lattice, 'd' has no complement

∴ It is not complemented lattice.

'E' has two complements F & C

∴ It is not distributive.

Ex: If A is a finite set, then the poset $[P(A); \subseteq]$ is a boolean algebra.

→ If $X \in P(A)$, then

Complement of X = $A - X$

If $A = \{a, b, c\}$ then the poset $\{P(A); \subseteq\}$ is a boolean algebra

$$\begin{aligned}\text{Complement of } \{a, c\} &= A - \{a, c\} \\ &= \{b\}\end{aligned}$$

Square free integers :- A positive integer n is said to be square free, if D_n has no elements that are perfect square (except 1).

Ex: If n is a square free integer then the poset $[D_n; |]$ is a boolean algebra.

* If $[D_n; |]$ is a boolean algebra then complement of

$$\bar{x} = \frac{n}{x} \quad \forall x \in D_n$$

Ex: Which of the following Posets is not a boolean algebra?

a) $[D_{21}; |]$

$$= [\{1, 3, 7, 21\}; |]$$

As 21 is square free integer

∴ D_{21} is boolean algebra.

b) $[D_{90}; |]$

$$90 \Rightarrow 2 \cdot 3 \cdot 3 \cdot 5 \quad \text{prime}$$

(not product of distinct integers)

∴ Not a free integer
square

∴ D_{90} is not boolean algebra.

c) $[D_{10}; \cdot]$

$$110 = 2 \cdot 5 \cdot 11$$

$$\begin{array}{r} 2 | 110 \\ 5 | 55 \end{array}$$

\therefore square free integer.

$\therefore D_{10}$ is boolean algebra.

d) $[D_{30}; \cdot]$

$$30 = 2 \cdot 3 \cdot 5$$

D_{30} also boolean algebra.

Ex: In the boolean algebra $[D_{10}; \cdot]$,

$$\text{complement of } S = \frac{110}{S}$$

$$x = \frac{n}{x} \quad \forall x \in D_n$$

- a) 10 b) 11 c) 22 d) 55

Groups :-

Algebraic structure : A non empty set S is called an algebraic structure w.r.t. a binary operation $*$, if $(a * b) \in S \quad \forall a, b \in S$
i.e. $*$ is a closed operation on S
 $(S, *)$

$$N = \{1, 2, 3, \dots, \infty\}$$

Z = set of all integers

Q = set of rational no.s

R = set of all real no.s

Ex: $(N, +)$ is an algebraic structure.

Ex: (N, \cdot) is an algebraic structure.

Ex: $(N, -)$ not an algebraic structure.

Ex: $\{Z, +, \cdot, -\}$ an algebraic structure.

Ex: $\{Q, \div\}$ is not _____ !! _____

Ex: $\{Q^*, \div\}$ is an algebraic structure.

$$Q^* = Q - \{0\} = \text{set of all non zero rational no.}$$

Semi Group :- An algebraic structure $(S, *)$ is called a semigroup iff $a * (b * c) = (a * b) * c$, $\forall a, b, c \in S$
i.e. $*$ is associative on S .

$\Rightarrow (Q^*, \div)$ is not a semi group because \div is not associative

$$a \div (b \div c) \neq (a \div b) \div c$$

$\Rightarrow (Z, -)$ is not a semi group

$$a - (b - c) \neq (a - b) - c$$

$\Rightarrow (Z, +)$ is a semi group

$$a + (b + c) = (a + b) + c$$

$\Rightarrow (N, \cdot)$ is a semigroup.

$$(a \cdot b) \cdot c = a \cdot (b \cdot c)$$

Monoid :- A semi group $(S, *)$ is called a monoid if there exist an element $e \in S$, such that

$$a * e = e * a = a$$

i.e. e = Identity element of S w.r.t. $*$

Ex: $\{N, \cdot\}$ is a monoid, with identity element $1 \in N$

Ex: $\{N, +\}$ is not a monoid.

because $0 \notin N$.

Ex: $\{Z, +\}$ is a monoid

because $0 \in Z$

Group :- A monoid $(S, *)$ is called a group if to each element $a \in S$, there is an element $b \in S$, such that

$$(a * b) = (b * a) = e. \quad \text{here}$$

b = inverse of a

$$= a^{-1}$$

Ex: $(Z, +)$ is a group.

Ex: (\mathbb{Z}, \cdot) is not a group.

$$a^{-1} = \frac{1}{a}$$

$$a(\frac{1}{a}) = 1$$

Ex: (\mathbb{Q}, \cdot) is not a group

\circ has no inverse

Ex: (\mathbb{Q}^+, \cdot) is a group

$$\mathbb{Q}^* = \mathbb{Q} - \{0\}$$

Abelian Group :- (commutative group)

A group, is said to be abelian, if $a * b = b * a \forall a, b \in G$
 $(G, *)$

Ex: $(\mathbb{Z}, +)$ is abelian group :- $a+b = b+a \forall a, b \in \mathbb{Z}$

Ex: (\mathbb{Q}^*, \cdot) _____ . :- $(a \cdot b) = (b \cdot a) \forall a, b \in \mathbb{Q}^*$

Ex: Set of all non singular matrices of order n is a group
w.r.t. matrix multiplication but not a abelian group.

$$A \cdot B \neq B \cdot A$$

Ex: Set of all bijective functions on a set A is a group w.r.t.
function composition but not abelian group.

$$(f \circ g) \neq (g \circ f)$$

Ex: Let $A = \{2, 4, 6, 8, \dots\}$

$B = \{1, 3, 5, 7, \dots\}$ which of the following is not

a semigroup.

a) A w.r.t '+'

b) A w.r.t ' \cdot ' :

c) B w.r.t '+'

d) B w.r.t ' \cdot '

sum of two odd no. is even.

Ex: Let $A = \{1, 2, 3, \dots\}$ and $*$ denoted by $a * b = a^b$ then
 $(A, *)$ is

a) semigroup but not monoid

$$(a+b)*c = (a^b)*c = (a^b)^c = a^{bc}$$

b) monoid but not a group

$$a*(b*c) = a*(b^c) = a^{bc}$$

c) a group

$$a^{bc} \neq a^{(bc)}$$

d) not a semigroup.

Ex : Let $A = \{x | 2 \leq x \leq 5\}$ & no. of $0 \leq a \leq 1\}$ then $(A, *)$ is

\rightarrow we have $a \cdot b \in A \wedge a, b \in A$.

\therefore is closed operation.

Associativity holds for any 3 real no.s betⁿ 0 to 1

\therefore $*$ is associative.

1 is identity element w.r.t. $*$ & $1 \in A$

but inverse of elements not exists on group except 1.

\therefore Monoid but not a group

Ex : Let Z = set of all integers & a binary operation $*$ is defined

as : $a * b = \max^m \{a, b\}$ then $(Z, *)$ is —

\rightarrow we have $a * b = \max \{a, b\} \in Z \quad \forall a, b \in Z$

$\therefore *$ is closed on Z .

$$\text{also } (a * b) * c = a * (b * c)$$

$$(3 * 4) * 1 = 3 * (4 * 1)$$

$$9 * 1 = 3 * 4$$

$$4 = 4$$

$\therefore *$ is associative on Z

$$a * e = \max \{a, e\} = a \quad \forall a, e \in Z$$

\therefore The identity element w.r.t. $*$ is the smallest integer

which doesn't exists.

$\therefore (Z, *)$ is semi group.

Ex : Let $Q^+ =$ set of all the +ve rational no.s & a binary operation $*$ is defined as $(a * b) = \frac{ab}{3}$ then $(Q^+, *)$ is —

\rightarrow $*$ is closed & associative on Q^+

Let e = identity element

$$a * e = a \quad \forall a \in Q^+$$

$$\frac{ae}{3} = a$$

$$e = 3 \in Q^+$$

Let a^{-1} = inverse of a

$$a * a^{-1} = e \quad a \in Q^+$$

$$\frac{aa^{-1}}{3} = e$$

$$\therefore -a^{-1} \in Q^+$$

$\therefore (Q^+, *)$ is a group.

Properties :-

In a group $(G, *)$, the following properties hold good

- 1) The identity element e is unique.
- 2) The inverse of any element in G is unique.
- 3) ~~—~~ — identity element ' $e' = e$
- 4) The cancellation laws hold good

$$(a * b) = (a * c) = b = c$$

$$(a * x) = (b * x) = a = b$$

5) $(a * b)^{-1} = b^{-1} * a^{-1}$

Ex: which of the following is not true?

- a) In a group $(G, *)$, if $a * a = a$ then $a = e$
- b) In a group $(G, *)$, if $x^{-1} = x \ \forall x \in G$ then G is abelian.
consider, $(a * b)^{-1} = (b^{-1} * a^{-1}) \ \forall a, b \in G$
 $\therefore (a * b) = (b * a) \quad (\because x^{-1} = x)$
 $\therefore G$ is abelian.
- c) In a group $(G, *)$, if $(a * b)^2 = (a^2 * b^2)$ then G is abelian.
 \rightarrow Given that, $(a * b)^2 = (a^2 * b^2)$
 $\Rightarrow (a * b) * (a * b) = (a * a) * (b * b)$
 $a * (b * a) * b = a * (a * b) * b$
 $(b * a) = (a * b)$
 $\therefore G$ is abelian.
- d) In a group $(G, *)$, if $(a * b)^n = (a^n * b^n)$ then G is abelian.
where $n = \{2, 3, 4, \dots\}$ — TRUE

Finite Group :- A group with finite no. of elements.

Order of a group : $[G]$ = No. of elements in G .

Ex : $\{0\}$ is a group w.r.t. '+'

- The only finite group of real no.s w.r.t. '+' is $\{0\}$

Ex : $\{1\}$ is a group of order 1 w.r.t. multiplication.

Ex : $\{1, -1\}$ $\begin{array}{c} \text{---} \\ \text{---} \end{array}$ 2 $\begin{array}{c} \text{---} \\ \text{---} \end{array}$. $\begin{array}{c|cc} \cdot & 1 & -1 \\ \hline 1 & 1 & -1 \\ -1 & -1 & 1 \end{array}$

→ Inverse of $1 = 1$

→ $1 \cdot -1 = -1$

- The only finite group of real no. w.r.t. '*' are $\{1\}$ & $\{1, -1\}$

- In a group of order 2 : $a^{-1} = a$, $\forall a \in G$

Ex : The cube root of unity $\{1, \omega, \omega^2\}$ is a group of order 3

w.r.t. '*' :

| \circ | 1 | ω | ω^2 | |
|------------|------------|------------|------------|--|
| 1 | ① | ω | ω^2 | $\omega^3 = 1$ |
| ω | ω | ω^2 | ① | $\omega^3 = 1$ |
| ω^2 | ω^2 | ① | ω | $\omega^4 = \omega^3 \cdot \omega$ $\omega^4 = 1 \cdot \omega$ $\omega^4 = \omega$ |

Inverse of $1 = 1$ ($\because 1 \times 1 = 1$)

Inverse of $\omega = \omega^2$ ($\because \omega \times \omega^2 = 1$)

Inverse of $\omega^2 = \omega$ ($\because \omega^2 \times \omega = 1$)

∴ It is group of order 3.

Ex : The set $\{1, -1, i, -i\}$ is a group w.r.t. multiplication.

| \circ | 1 | -1 | i | -i |
|---------|----|----|----|----|
| 1 | ① | -1 | i | -i |
| -1 | -1 | ① | -i | i |
| i | i | -i | -1 | ① |
| -i | -i | i | ① | -1 |

Inverse of $1 = 1$

$1 \cdot -1 = -1$

$1 \cdot i = i$

$1 \cdot -i = -i$

∴ It is group of order 4.

Addition Modulo M, \oplus_m

If a and b are any two integers then $a \oplus_m b$ defined as

$$a \oplus_m b = \begin{cases} (a+b) & \text{if } (a+b) < m \\ r & \text{if } (a+b) \geq m \text{ where } r \text{ is remainder obtained by dividing } (a+b) \text{ with } m. \end{cases}$$

Ex : $m=6$

$$2 \oplus_6 3 = 5$$

$$3 \oplus_6 4 = 1$$

Ex : $\{0, 1, 2, \dots, m-1\}$ is a group w.r.t. \oplus_m

Multiplication Modulo M, \otimes_m

If a & b are any two tve integers then

$$a \otimes_m b = \begin{cases} (ab) & \text{if } (ab) < m \\ r & \text{if } (ab) \geq m \text{ where } r \text{ is remainder obtained by dividing } (ab) \text{ with } m. \end{cases}$$

Ex : $2 \otimes_7 3 = 6$

Ex : $5 \otimes_7 3 = 1$ \therefore

Ex : $\{1, 2, 3, \dots, p-1\}$ is a group w.r.t. \otimes_p where p is a prime no.

* If n is a tve integer, then $S_n =$ set of all tve integers which are less than n and relatively prime to n .

$$S_6 = \{1, 5\}$$

$$S_8 = \{1, 3, 5, 7\}, S_7 = \{1, 2, 3, 4, 5, 6\}$$

* If n is any tve integer then S_n is a group w.r.t. \oplus_n

Ex : The set $\{0, 1, 2, 3, 4, 5\}$ is a group w.r.t. \oplus_6 which of the following is NOT TRUE ?

(a) The inverse of $1 = 5$ (d) $\underline{\quad} \underline{\quad} \underline{\quad} 4 = 2$

(b) $\underline{\quad} \underline{\quad} \underline{\quad} 2 = 4$

(c) $1 \oplus_6 5 = 0$ but $3 \oplus_6 0 \neq 0$

* In a group of even order i.e. group of even no. of elements there exists atleast one element a ($a \neq e$) such that $a^{-1} = a$

Ex: The set $\{1, 2, 3, 4, 5, 6\}$ is group w.r.t. \otimes_7 which is false?

- (a) The inverse of $1 = 1$ $\bigoplus 1 \otimes_7 1 = 1 \rightarrow$ Identity element.
- (b) $_\!_\! \rightarrow 1 _\!_ 2 = 4$ $2 \otimes_7 4 = 1$
- (c) $_\!_ \rightarrow 1 _\!_ 3 = 5$ $3 \otimes_7 5 = 1$
- (d) $_\!_ \rightarrow 1 _\!_ 6 = 2$ $6 \otimes_7 2 \neq 1$

Ex: The set $\{1, 3, 5, 7\}$ \otimes_8 which is false?

- (a) The inverse of $1 = 1$ $1 \otimes_8 1 = 1$
- (b) $_\!_ \rightarrow 1 _\!_ 3 = 7$ $7 \otimes_8 3 \neq 1$
- (c) $_\!_ \rightarrow 1 _\!_ 5 = 5$ $5 \otimes_8 5 = 1$
- (d) $_\!_ \rightarrow 1 _\!_ 7 = 7$ $7 \otimes_8 7 = 1$

Ex: Consider a set $G = \{2, 4, 6, 8\}$ w.r.t. \otimes_{10} which is false?

- (a) G is group w.r.t. \otimes_{10}
- (b) The identity element of G is 6
- (c) The inverse of $2 = 4$
- (d) $_\!_ \rightarrow 1 _\!_ 4 = 4$

The inverse of $2 = 8$

$$\begin{aligned} _\!_ \rightarrow 1 _\!_ 4 &= 4 \\ _\!_ \rightarrow 1 _\!_ 6 &= 6 \\ _\!_ \rightarrow 1 _\!_ 8 &= 2 \end{aligned}$$

| \otimes_{10} | 2 | 4 | 6 | 8 |
|----------------|---|---|---|---|
| 2 | 4 | 8 | 6 | ⑥ |
| 4 | 8 | ⑥ | 4 | 2 |
| 6 | 2 | 4 | ⑥ | 8 |
| 8 | ⑥ | 2 | 8 | 4 |

Ex: Which of the following is not true? a group?

- a) $\{1, 2, 3, 4, 5\}$ w.r.t. \otimes_6

$2 \otimes_6 3 = 0 \notin A$
closure property fails
 \therefore Not a group.

- b) $\{0, 1, 2, 3, 4, 5\}$ w.r.t. \otimes_6

for '0' no multiplicative inverse exists

$$0 \otimes_6 x = 0$$

\therefore Not a group.

- c) $\{1, 2, 3, 4, 5\}$ w.r.t. \oplus_6

$$2 \oplus_6 4 = 0$$

\therefore Not a group.

d) $\{1, 2, 3, 4\}$ w.r.t \otimes_3

It is a group.

Order of an element of a group :-

Let $(G, *)$ be a group with identity element 'e'

for $a \in G$,

The order of $a = o(a)$ is defined as n

where n is smallest +ve integer such that $a^n = e$

Ex: In the group $\{1, -1\}$ w.r.t. multiplication.

$$o(1) = 1$$

$$o(-1) = 2$$

Ex: In the group $\{1, \omega, \omega^2\}$ w.r.t. multiplication.

$$o(1) = 1$$

$$o(\omega) = 3$$

$$o(\omega^2) = 3$$

Ex: In the group $\{1, \omega, \omega^2\}$ w.r.t. multiplication

* order of $a = \text{order of } a^1 \forall a \in G$.

Ex: In the group $\{1, -1, i, -i\}$ w.r.t multiplication

$$o(1) = 1 \quad o(i) = 4$$

$$o(-1) = 2 \quad o(-i) = 4$$

* In a group $(G, *)$ order of $a = \text{divisor of } o(G) \ \forall a \in G$.

Ex: In the group $\{0, 1, 2, 3\}$ w.r.t. \oplus_4 .

$$\text{order of } 0 = 1$$

$$-\underline{\underline{1}} - \underline{\underline{1}} = 4$$

$$-\underline{\underline{1}} - \underline{\underline{2}} = 2$$

$$-\underline{\underline{1}} - \underline{\underline{3}} = 4$$

$$2^2 = 2 \oplus_4 2 = 0$$

$$1^3 = (1 \oplus_4 1) \oplus_4 1$$

$$= 3$$

$$1^4 = 1^3 \oplus_4 1$$

$$= 3 \oplus_4 1$$

$$1^4 = 0$$

Ex: Group $\{1, 3, 5, 7\}$ w.r.t. \otimes_7

$$\begin{aligned}O(1) &= 1 \\O(3) &= 2 \\O(5) &= 2 \\O(7) &= 2\end{aligned}$$

$$3^2 = 3 \otimes_7 3 = 1$$

Subgroups :- Let $(G, *)$ be a group. A subset H of G is called a subgroup of G , if H is a group w.r.t. $*$.

Ex: $G = \{1, -1, i, -i\}$ is a group w.r.t. multiplication

$H_1 = \{1, -1\}$ is a subgroup of G .

$H_2 = \{1\}$ is a subgroup.

Note :- For the group $(G, *)$ with identity element e , G and $\{e\}$ are called trivial subgroups of G .

Proper Subgroup :- Any subgroup of $(G, *)$, which is not a trivial subgroup of G , is called as proper subgroup of G .

Theorem 1 : Let H be a non empty subset of a group $(G, *)$. H is a subgroup of G iff $(a * b^{-1}) \in H \quad \forall a, b \in H$

Theorem 2 : Let H be a non empty finite subset of a group $(G, *)$ then H is a subgroup of G iff $(a * b) \in H \quad \forall a, b \in H$

Theorem 3 : (Lagrange's theorem)

If H is a subgroup of a group $(G, *)$, Then $O(H)$ is a divisor of $O(G)$.

Ex: $G = \{1, 2, 3, 4, 5, 6\}$ is a group w.r.t. \otimes_7
which of the following one subgroup of G ?

- a) $\{1, 6\}$ ~~b) $\{1, 2, 4\}$~~
- b) $\{1, 8, 5\}$ d) $\{1, 3\}$

| | 1 | 2 | 4 |
|---|---|---|----|
| 1 | 1 | 2 | 4 |
| 2 | 2 | 4 | 1 |
| 4 | 4 | 1 | 02 |

Ex: $G = \{0, 1, 2, 3, 4, 5\}$ is a group w.r.t. \oplus .

which are subgroups?

a) $\{0, 3\}$ b) $\{0, 2, 4\}$

c) $\{0, 1, 5\}$ d) $\{0, 1, 2, 4, 5\}$

Ex: which of the following stat. is not true?

a) Every subgroup of an abelian group is also an abelian group.

b) Union of any two subgroups of a group G is also a subgroup of G .

c) Intersection ———

d) Union of 2 subgroups H_1 & H_2 of a group $(G, *)$ is also a subgroup of G , iff $H_1 \subseteq H_2$ or $H_2 \subseteq H_1$.

Ex: If $(G, *)$ is a group of order p , where p is a prime no. then no. of subgroups in $(G, *)$ is —

→ Let $(H, *)$ be a subgroup of G .

$$\text{Let } O(H) = n$$

By lagranges theorem n is divisible divisor by p .

$$\Rightarrow n=1 \text{ or } n=p$$

$$\Rightarrow H = \{e\} \text{ or } H = G$$

a) $p-1$

b) p

c) 2

d) 0

Cyclic Group :- Let $(G, *)$ be a group with identity element e . If there exists an element $a \in G$, such that every element of G can be written in the form a^n for some integer n , then G is called as cyclic group. and element a is called Generator of G .

respect to multiplication

Ex: The set $\{1, -1\}$ is a cyclic group with generator -1 .

$$\begin{array}{c} \downarrow \\ (-1)^2 \\ \downarrow \\ (-1)^1 \end{array}$$

Ex: $\{1, \omega, \omega^2\}$ w.r.t. Multi.

$$\text{Generator} = \omega, \omega^2$$

* In a cyclic group $(G, *)$ with a generator a , a^{-1} is also a generator of G .

Ex: The set $\{1, -1, i, -i\}$ is a cyclic group w.r.t. multiplication.

The generators = $i, -i$

* $O(G) = O(a)$ Identity elements can not be generators.

Ex: The set $\{0, 1, 2, 3\}$ is a cyclic group w.r.t. \oplus_4 .

$$\left. \begin{array}{l} 1^2 = 1 \oplus_4 1 = 2 \\ 1^3 = 1^2 \oplus_4 1 = 2 \oplus_4 1 = 3 \\ 1^4 = 1^3 \oplus_4 1 = 3 \oplus_4 1 = 0 \end{array} \right\} 1 \text{ is Generator.}$$

Generators is $1 \& 3$.

3 is inverse of 1.

Ex: The set $\{1, 2, 3, 4\}$ is a cyclic group w.r.t. \otimes_5 .

$$\left. \begin{array}{l} 2^2 = 2 \otimes_5 2 = 4 \\ 2^3 = 2^2 \otimes_5 2 = 4 \otimes_5 2 = 3 \\ 2^4 = 2^3 \otimes_5 2 = 3 \otimes_5 2 = 1 \end{array} \right\} 2 \text{ is Generator.}$$

As 3 is inverse of 2

$\therefore 3$ is also generator.

* Let $(G, *)$ be a cyclic group of order n , with generator a .

i), a^m is also a generator of G , if m and n are coprime
i.e. $\gcd(m, n) = 1$

ii) Number of generators in $G = \phi(n) =$ Euler function of n .
 $=$ no. of positive integers less than n and relatively prime to n .

Ex: Let $(G, *)$ be a cyclic group of order 8 with generator a
then how many generators are there and what are they?

$$\rightarrow \text{No. of generator} = \phi(8) \quad (\because \{1, 2, 3, 4, 5, 7\}) \\ = 4$$

The generators are $= a^1, a^3, a^5, a^7$.

Ex: Let $(G, *)$ be a cyclic group of order 70 then no. of
Generator in $G = ?$

$$\rightarrow \phi(70) = 70 \left\{ \frac{(2-1)(5-1)(7-1)}{2 \cdot 5 \cdot 7} \right\} \left| \begin{array}{c} 2 \mid 70 \\ 5 \mid 35 \\ 7 \mid 7 \end{array} \right.$$

$$* \Phi(n) = n \left[\frac{(p_1-1)(p_2-1)\dots(p_k-1)}{p_1 \cdot p_2 \cdot \dots \cdot p_k} \right] \text{ where } p_1, p_2, p_3, \dots, p_k \text{ are distinct prime factors of } n.$$

Ex: $\{0, 1, 2, 3, 4\}$ is a cyclic group of order 5 then how many generators are there & what are they? (w.r.t. \otimes_5)

$$\rightarrow \Phi(5) = 5-1 = 4 \quad \text{if } n \text{-prime no.}$$

$\Phi(5) = 4$ & The generators are 1, 2, 3, 4

Ex: The set $\{1, 2, 3, 4\}$ is a cyclic group w.r.t. \otimes_7 of order 6 then how many generators & what are they?

$$\rightarrow \therefore \Phi(6) = 2 \quad \{1, 2, 3, 4, 5, 6\}$$

$$2^2 = 2 \otimes_7 2 = 4$$

$$3^2 = 3 \otimes_7 3 = 2$$

$$2^3 = 2^2 \otimes_7 2 = 1$$

$$3^3 = 3^2 \otimes_7 3 = 2 \otimes_7 3 = 6$$

$$\Rightarrow \text{O}(2) = 3$$

$$3^5 = 3^4 \otimes_7 3 = 4 \otimes_7 3 = 5$$

$$3^6 = 3^5 \otimes_7 3 = 5 \otimes_7 3 = 1$$

$\therefore 3$ is a generator

Also 5 is generator as inverse of 3.

Ex: The group $\{1, 3, 5, 7\}$ w.r.t. \otimes_8 is NOT a cyclic group.
there is no generator for this group.

$$1^2 = 1 \otimes_8 1 = 1$$

$$3^2 = 3 \otimes_8 3 = 1$$

* Following properties hold good in cyclic group

- ① Every group of prime order is cyclic.
- ② Every abelian group is cyclic group.
- ③ Every group of prime order is abelian group.
- ④ Every subgroup of a cyclic group is cyclic.

Functions :-

- A relation f from A to B , is called a function, if each element of A is mapped with a unique element in B . f denoted by $F : A \rightarrow B$.
- Here $A \rightarrow$ domain of F and $B \rightarrow$ co-domain of F .
- Range of $F = \{y | y \in B \text{ and } (x, y) \in F\}$
- Range of $F \subseteq$ co-domain of F .
- If Range = co-domain, then it is an 'onto' function.
- A function $F : A \rightarrow A$ is called a function on A .
- If $|A| = m$ and $|B| = n$, then no. of functions possible from A to $B = n^m$.

One to one function (Injection) :-

- A function $f : A \rightarrow B$ is said to be one to one, if no two elements in A have same image in B . or if $f(a) = f(b) \Rightarrow a = b$
- * If A and B are finite sets then a 1 to 1 function from A to B is possible iff no. of elements in A i.e. $|A| \leq |B|$
- * If $|A| = m$ & $|B| = n$ then no. of 1 to 1 functions possible from A to B ($m \leq n$) ~~= P(n,m)~~ = $n P_m$.
- If $|A| = |B| = n$ then = $n P_n = n!$

On-to function

- A function $f : A \rightarrow B$ is said to be on-to if each element of B is mapped by atleast one element of A . i.e. Range of $f = B$ = codomain.
- If A and B are finite sets, then an onto function from A to B is possible iff $|B| \leq |A|$
- If $|A| = m$ and $|B| = n$ ($n < m$) then no. of onto functions possible = $n^m - nC_1 \cdot (n-1)^m + nC_2 \cdot (n-2)^m - nC_3 \cdot (n-3)^m + \dots - nC_{n-1} \cdot (-1)^{n-1} \cdot n^m$

Ex : For $m=6$ $n=3$

$$= 3^6 - 3C_1 \cdot 2^6 + 3C_2 \cdot 1^6$$

$$= 729 - 3 \cdot (64) + 3$$

= ...

Note :- If $|A|=|B|$ then every 1 to 1 function from $A \rightarrow B$ is onto and vice versa.

- IF $|A|=|B|=n$ then no. of onto functions = $n!$

Bijection :- A function $F: A \rightarrow B$ is said to be a bijection, if $F: A \rightarrow B$ is 1 to 1 and onto.

* If A and B are finite sets then a Bijection from A to B is possible iff $|A|=|B|$

* If $|A|=|B|=n$ then no. of bijection possible from A to B $= n!$

Inverse of a function :- If $F: A \rightarrow B$, then the inverse relation from B to A, is called a function (if the inverse reln F^{-1} from B to A is a function), then it is called inverse of F, and denoted by $F^{-1}: B \rightarrow A$

* Inverse of a function $F: A \rightarrow B$ exists iff $F: A \rightarrow B$ is a bijection.

Identity function :- $F: A \rightarrow B$ is called an identity function if $f(x) = x \quad \forall x \in A$

$I: A \rightarrow A$ or I_A

- Every identity function is a bijection.

function composition :-

$F: A \rightarrow A$ and $g: A \rightarrow A$, then

i) $(F \circ g): A \rightarrow A$ defined by $(F \circ g)(x) = F\{g(x)\}$

ii) $(g \circ F): A \rightarrow A$ defined by $(g \circ F)(x) = g\{F(x)\}$

- In general $(F \circ g) \neq (g \circ F)$

- IF $F: A \rightarrow A$ and $I: A \rightarrow A$ then

$$(F \circ I) = (I \circ F) = F$$

- If $F: A \rightarrow A$ is a bijection, then $(F \circ F^{-1}) = (F^{-1} \circ F) = I$

- If $F: A \rightarrow B$ and $g: B \rightarrow C$, then

i) $(g \circ F): A \rightarrow C$

ii) $(F \circ g)$ may not be defined

$(g \circ F): A \rightarrow A$ defined by

only when range of $g \subseteq$ domain of f .

- If $F: A \rightarrow B$ then i) $F \circ I_A = f$ and
ii) $I_B \circ f = f$

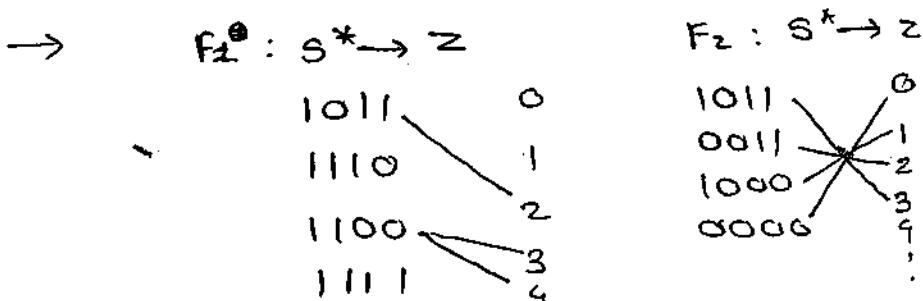
- If $F: A \rightarrow B$ is a bijection then i) $f \circ F^{-1} = I_B$ and $F^{-1} \circ f = I_A$
 $F^{-1} = B \rightarrow A$

Ex: which of the following is a function on set of all real no.s

- a) $F_1(x) = 1/x \rightarrow$ for the real no. '0' image does not exists.
- b) $F_2(x) = \sqrt{x} \rightarrow$ for -ve real no. in domain image not exists
- c) $F_3(x) = \pm \sqrt{x^2 + 1}$ --- for $1 < \frac{-\sqrt{2}}{\sqrt{2}}$ } two images of each element. Not function
- d) $F_4(x) = |x|$ $\begin{matrix} -1 \\ 1 \end{matrix} \rightarrow \begin{matrix} 1 \\ 1 \end{matrix}$ (for two elements one image)
 \therefore it is a function.

Ex: which of the following relations from set of all bit strings to set of all integers is a function

$$F_1(s) = \text{The position of a zero bit in the bit string } s$$
$$F_2(s) = \text{The no. of } 1 \text{ bits in the bit string } s$$



f_1 is not a function because a string with 2 or more '0' will have two or more images

for any bit string the no. of 1 bits is non-ve integer
 \therefore each string has only one image.

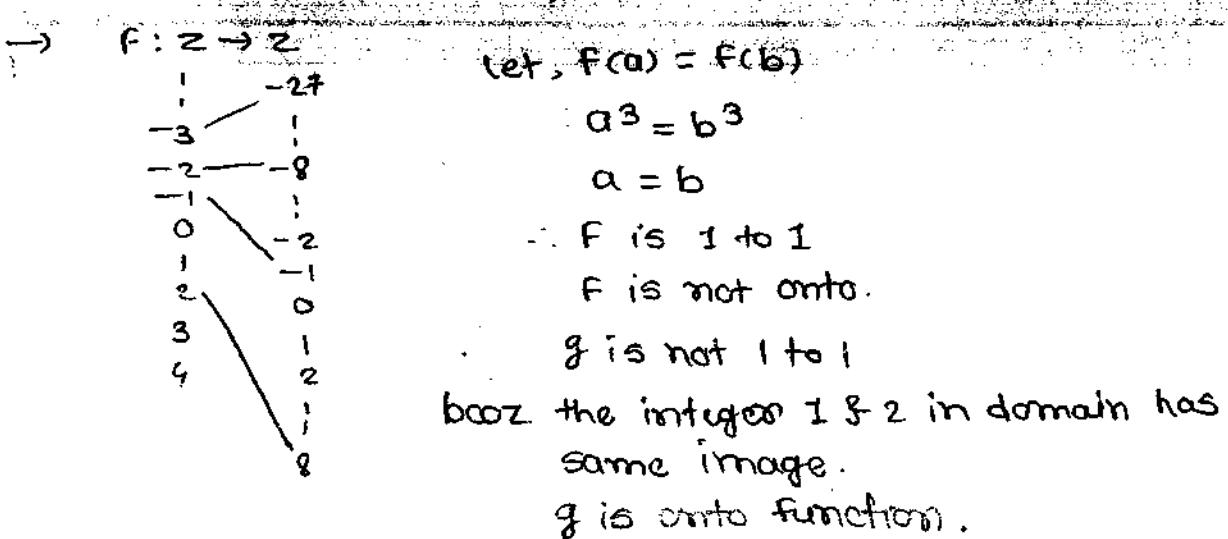
bit $\therefore f_2$ is a function.

Ex: Consider the following function on set of all integers.

$$f(x) = x^3 \text{ and } g(x) = \lceil \frac{x}{2} \rceil$$

which of the following stat. are true?

- S₁) f is 1 to 1
- S₂) f is onto
- S₃) g is 1 to 1



Ex. Let $A = \mathbb{R} - \{3\}$ and $B = \mathbb{R} - \{1\}$ where $f: A \rightarrow B$ is defined by $f(x) = \left(\frac{x-2}{x-3}\right)$ which is true?

- a) f is 1-1 but not onto
- b) f is onto but not 1-1
- c) f is a bijection
- d) f is neither 1-1 nor onto

→ $f(a) = f(b)$

$$\frac{a-2}{a-3} = \frac{b-2}{b-3}$$

$$(a-2)(b-3) = (b-2)(a-3)$$

$$a=b$$

∴ one to one function.

$$\text{Let } f(x) = \frac{x-2}{x-3} = y$$

$$x-2 = (x-3)y$$

$$x = \frac{2-3y}{1-y} \text{ — inverse of } f(x)$$

Check for inverse is a function (or) not. if inverse is a function for each value of real no. except 1

∴ f is onto

∴ f is bijection.

Ex: For which of the following function inverse is not defined on their range.

A. $f(x) = x^2$ — Not one to one \therefore No inverse exist.

B. $f(x) = x^3$ — One to one & onto \therefore inverse exists
 $f'(x) = x^{1/2}$

C. $f_1(x) = \sin x$, $x \in (0, \pi)$ — Not one to one \therefore inverse not exists.

$$\frac{\pi/4}{3\pi/4} > 1/\sqrt{2} \quad (\text{Two images})$$

D. $f(x) = 2^x$

$$2^x = y$$

$$x \log 2 = \log y$$

$$x = \log_2 y$$

$$F'(x) = \log_2 x \quad (\text{Inverse})$$

* Linear Algebra [3 M]

Topics :-

- Determinants
- Inverse of a matrix
- Rank of matrix
- Homogeneous & non-homogeneous linear eq'
- Eigen values & Eigen vectors
- Cayley - Hamilton theorem.

Textbook :-

Matrices by A.R. Vasistha

* Determinants *

* Properties of Determinants :-

Point I : Value of the determinant will not be change if rows and columns are interchanged.

$$\text{i.e., } |A| = |A^T|$$

Ex.

$$|A| = \begin{vmatrix} 5 & 4 \\ 3 & 2 \end{vmatrix} = 10 - 4 = 6$$

$$|A^T| = \begin{vmatrix} 5 & 3 \\ 4 & 2 \end{vmatrix} = 10 - 9 = 6$$

$$\therefore |A| = |A^T|$$

Point II : Value of the determinant is multiplied by -1 if two rows & two columns are interchanged.

Ex.

$$|A| = \begin{vmatrix} 1 & 2 \\ 3 & 4 \end{vmatrix} = 4 - 6 = -2$$

$$|A| = \begin{vmatrix} 3 & 4 \\ 1 & 2 \end{vmatrix} = 6 - 4 = 2$$

Point III : Value of the determinant can be zero in the following cases :-

i) The elements in two rows or two columns are identical.

Ex.

$$|A| = \begin{vmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 1 & 2 & 3 \end{vmatrix} = 0$$

some

ii) The elements in two rows or two columns are proportional to each other

Ex.

$$|A| = \begin{vmatrix} 1 & 2 & 3 \\ 0 & 1 & 5 \\ 3 & 6 & 9 \end{vmatrix} = 0$$

proportional

iii) All elements in a row or column are zeros

Ex

$$|A| = \begin{vmatrix} 1 & 2 & 3 \\ 0 & 0 & 0 \\ 4 & 7 & 3 \end{vmatrix} = 0$$

iv) The elements in a determinant are of consecutive order (continuous order)

→ valid for ~~all~~ 3×3 & high order matrices

Ex

$$|A| = \begin{vmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{vmatrix} = 0$$

We can start 1st element from any no.

Point IV: The determinant of upper triangular, lower triangular, diagonal, scalar & Identity matrix is the product of its diagonal elements.

⇒ Upper triangular matrix

Ex:

$$|A| = \begin{vmatrix} 1 & 2 & 3 \\ 0 & -4 & 2 \\ 0 & 0 & 7 \end{vmatrix} = 1 \times (-4) \times 7 = -28$$

⇒ Lower triangular matrix

Ex:

$$|A| = \begin{vmatrix} 1 & 0 & 0 \\ 2 & 3 & 0 \\ 4 & 5 & 7 \end{vmatrix} = 1 \times 3 \times 7 = 21$$

⇒ Diagonal matrix

Ex:

$$|A| = \begin{vmatrix} 3 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 5 \end{vmatrix} = 3 \times 2 \times 5 = 30$$

A matrix is diagonal iff at least one diagonal element should be non zero & all other non-diagonal elements should be zero.

4) Scalar matrix

Ex.

$$|A| = \begin{vmatrix} 3 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{vmatrix} = 3 \times 3 \times 3 = 27$$

→ Diagonal elements should be same

→ Non-diagonal elements should be zero

5) Identity matrix

Ex.

$$|I| = \begin{vmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{vmatrix} = 1 \times 1 \times 1 = 1$$

→ Determinant of Identity matrix is always 1.

Point V: If A is $N \times N$ matrix then

$$|KA| = k^n |A|$$

where n = order of matrix A

Ex.

$$|A| = \begin{vmatrix} 1 & 2 \\ 3 & 4 \end{vmatrix} = 4 - 6 = -2$$

$$\therefore |3A| = 3^2 \cdot |A| = 9 \times (-2) = -18$$

Point VI: If each element of a row or column contains sum of 2 elements then the determinant can be expressed as sum of two determinants of same order

Ex.

$$|A| = \begin{vmatrix} 1 & 1^2 & 1^3 + 1 \\ 2 & 2^2 & 2^3 + 4 \\ 3 & 3^2 & 3^3 + 5 \end{vmatrix}$$

$$= \begin{vmatrix} 1 & 1^2 & 1^3 \\ 2 & 2^2 & 2^3 \\ 3 & 3^2 & 3^3 \end{vmatrix} + \begin{vmatrix} 1 & 1^2 & 1 \\ 2 & 2^2 & 4 \\ 3 & 3^2 & 5 \end{vmatrix}$$

* Note 1: Consider the matrix

$$A = \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix}$$

Method I:

$$|A| = a_{11}(a_{22}a_{33} - a_{23}a_{32}) - a_{12}(a_{21}a_{33} - a_{23}a_{31}) + a_{13}(a_{21}a_{32} - a_{22}a_{31})$$

Method II:

$$\begin{matrix} a_{13} & a_{11} & a_{12} & a_{13} & a_{11} \\ a_{21} & a_{22} & a_{23} & a_{21} & a_{22} \\ a_{33} & a_{31} & a_{32} & a_{33} & a_{31} \end{matrix}$$

$$|A| = a_{13}a_{21}a_{32} + a_{11}a_{22}a_{33} + a_{12}a_{23}a_{31} - a_{33}a_{21}a_{12} - a_{31}a_{22}a_{13} - a_{32}a_{23}a_{11}$$

→ If determinant contains more no. of zeros
use method I.

Ex: 1) Find determinant of

$$A = \begin{pmatrix} 1 & 2 & 2 \\ 2 & 1 & 2 \\ 2 & 2 & 1 \end{pmatrix}$$

$$\begin{array}{r} 2 \quad 1 \quad 2 \quad 1 \\ -2 \quad 1 \quad 2 \\ 1 \quad 2 \quad 1 \quad 2 \end{array}$$

$$= 8 + 1 + 8 - 4 - 4 - 4 \\ = 5$$

Ex: 2) $A = \begin{pmatrix} 5 & 0 & 2 \\ 0 & 3^+ & 0 \\ 2 & 0 & 1 \end{pmatrix}$

$$= 3(5 - 4) = 3$$

~~Note~~
Ex: 3) The following represents eqn of straight line

$$\begin{array}{r|rrr} & x & 2 & 4 \\ \hline y & 8 & 0 & \\ & 1 & 1 & 1 \end{array} = 0$$

The line passes through

- a) (0,0) b) (3,4) c) (4,3) d) (4,4)

$$x(8) - 2(y) + 4(y - 8)$$

$$8x - 2y + 4y - 32 = 0$$

$$8x + 2y = 32$$

$$4x + y = 16$$

$$\therefore 4(3) + 4 = 16$$

$$x = 3 \quad \& \quad y = 4$$

Step 2 :- Consider the matrix

$$A = \begin{pmatrix} + & - & + & - \\ a_{11} & a_{12} & a_{13} & a_{14} \\ a_{21} & a_{22} & a_{23} & a_{24} \\ a_{31} & a_{32} & a_{33} & a_{34} \\ a_{41} & a_{42} & a_{43} & a_{44} \end{pmatrix}_{4 \times 4}$$

Method I :- (Complicated)

$$|A| = a_{11} \begin{vmatrix} a_{22} & a_{23} & a_{24} \\ a_{32} & a_{33} & a_{34} \\ a_{42} & a_{43} & a_{44} \end{vmatrix} - a_{12} \begin{vmatrix} a_{21} & a_{23} & a_{24} \\ a_{31} & a_{33} & a_{34} \\ a_{41} & a_{43} & a_{44} \end{vmatrix}$$

$$+ a_{13} \begin{vmatrix} a_{21} & a_{22} & a_{24} \\ a_{31} & a_{32} & a_{34} \\ a_{41} & a_{42} & a_{44} \end{vmatrix} - a_{14} \begin{vmatrix} a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \\ a_{41} & a_{42} & a_{43} \end{vmatrix}$$

Method II :- (Preferable)

Ex:-

$$A = \begin{pmatrix} a_{11} & a_{12} & a_{13} & a_{14} \\ a_{21} & a_{22} & a_{23} & a_{24} \\ a_{31} & a_{32} & a_{33} & a_{34} \\ a_{41} & a_{42} & a_{43} & a_{44} \end{pmatrix}_{4 \times 4}$$

Procedure:

Step 1 : Among the given elements of a matrix, select any non-zero element.

Step 2 : Make all elements above & below or left & right of the selected element as zero using row & column operations.

Therefore, the matrix is

$$A = \begin{pmatrix} a_{11}^+ & a_{12}^- & a_{13}^+ & a_{14}^- \\ 0^- & b_{22} & b_{23}^- & b_{24}^+ \\ 0^+ & b_{32}^- & b_{33} & b_{34}^+ \\ 0^- & b_{42} & b_{43}^- & b_{44}^+ \end{pmatrix}$$

→ 1st column has more no. of zeros so the determinant along 1st column.

$$|A| = a_{11} \begin{vmatrix} b_{22} & b_{23} & b_{24} \\ b_{32} & b_{33} & b_{34} \\ b_{42} & b_{43} & b_{44} \end{vmatrix}$$

Ex. 1) Find the determinant of.

$$A = \begin{pmatrix} 1 & -1 & 0 & 1 \\ 1 & 2 & 3 & 4 \\ 2 & 3 & 4 & 9 \\ 0 & 1 & 0 & 2 \end{pmatrix}$$

$$R_2 \rightarrow R_2 - R_1$$

$$R_3 \rightarrow R_3 - 2R_1$$

$$A = \begin{pmatrix} 1^+ & -1 & 0 & 1 \\ 0^- & 3 & 3 & 3 \\ 0^+ & 5 & 4 & 7 \\ 0^- & 1 & 0 & 2 \end{pmatrix}$$

$$2 \cdot |A| = 1 \begin{vmatrix} -3 & 3 & 3 \\ 5 & 4 & 7 \\ 1^+ & 0^- & 2^+ \end{vmatrix}$$

Since,

$$1 [21 - 12] + 2 [12 - 15]$$

$$9 + 2(-3)$$

$$9 - 6 = 3$$

Problem 1 :- If A has m rows & m+s columns & B has n rows and n-n columns. The orders of A and B if AB and BA are defined?

$$(A) m \times (m+s)$$

$$(B) n \times (n-n)$$

$$(B) n \times (n-n)$$

$$(A) m \times (m+s)$$

$$\therefore m+s = n$$

$$m-n = -5$$

$$n-n = 0$$

$$m+n = 11$$

$$2m = 6$$

$$m = 3$$

$$n = 8$$

Therefore, orders are A (3, 8) & B (8, 3) resp.

Problem 2 :- If $A = (a_{ij})_{m \times n}$ such that $a_{ij} = i+j, i, j$ then sum of all element of A is ?

$$A = \begin{pmatrix} 1+1 & 1+2 & 1+3 & \cdots & 1+n \\ 2+1 & 2+2 & 2+3 & \cdots & 2+n \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ m+1 & m+2 & m+3 & \cdots & m+n \end{pmatrix}$$

according to Point VI

$$A = \left(\begin{array}{cccc|c} 1 & 1 & \cdots & 1 & 1 \\ 2 & 2 & \cdots & 2 & 2 \\ 3 & 3 & \cdots & 3 & 3 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ m & m & \cdots & m & m \end{array} \right) + \left(\begin{array}{cccc|c} 1 & 2 & 3 & \cdots & n \\ 1 & 2 & 3 & \cdots & n \\ 1 & 2 & 3 & \cdots & n \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & 2 & 3 & \cdots & n \end{array} \right)$$

$$= mI_m + nJ_m$$

$$\frac{m(m+1)}{2} + \dots + \frac{m(m+1)}{2} \quad \frac{n(n+1)}{2} + \dots + \frac{n(n+1)}{2}$$

for n columns = $\frac{n \cdot m(m+1)}{2}$ for m rows = $\frac{m \cdot n(n+1)}{2}$ Q

So,

$$\frac{m^2(m+1)}{2} + \frac{m^2n(n+1)}{2}$$

$$m^2 [m+1+n+1]$$

$$m^2 [m+n+2]$$

Problem 8 :- If $A = (a_{ij})_{3 \times 3}$, $B = (b_{ij})_{3 \times 3}$ such that

$$b_{ij} = 2^{i+j} a_{ij} \quad i, j; |A| = 2; |B| = ?$$

$$\Rightarrow 2^1 \quad b \quad 2^2 \quad c \quad 2^1 \quad d \quad 2^3$$

$$|A| = \begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} = 2$$

$$|B| = \begin{vmatrix} 2^2 a_{11} & 2^3 a_{12} & 2^4 a_{13} \\ 2^3 a_{21} & 2^4 a_{22} & 2^5 a_{23} \\ 2^4 a_{31} & 2^5 a_{32} & 2^6 a_{33} \end{vmatrix}$$

$$2^2 \cdot 2^3 \cdot 2^4 \quad | 2 a_{11} \quad 2 a_{12} \quad 2^2 a_{13} | \quad 1 \\ | 2 a_{21} \quad 2 a_{22} \quad 2^2 a_{23} | \quad 2 \\ | 2 a_{31} \quad 2 a_{32} \quad 2^2 a_{33} | \quad 3$$

$$2^9 \cdot 2 \cdot 2^2 \quad | a_{11} \quad a_{12} \quad a_{13} | \\ | a_{21} \quad a_{22} \quad a_{23} | \\ | a_{31} \quad a_{32} \quad a_{33} |$$

$$\therefore i^2 - j^2 = 2^{12} \cdot 2 = 2^9$$

problem 4:- If $A = (a_{ij})_{n \times n}$ such that

$$\text{i)} a_{ij} = i^2 - j^2, \forall i, j$$

$$\text{ii)} a_{ij} = i^2 - j^2, \forall i, j$$

find sum of all elements of A



$$\text{iii)} A = \begin{pmatrix} 0 & -3 & -8 & \cdots & (1^2 - n^2) \\ 3 & 0 & -5 & \cdots & (2^2 - n^2) \\ 8 & 5 & 0 & \cdots & (3^2 - n^2) \\ \vdots & & & & \\ (n^2 - 1^2) & (n^2 - 2^2) & (n^2 - 3^2) & \cdots & 0 \end{pmatrix}$$

A is skew symmetric matrix.

→ In skew symmetric matrix all diagonal elements must be zero & non-diagonal elements should be real no.

Benefit :→ Sum of all elements of skew symmetric matrix is always zero.

e.g.

$$\text{iv)} A = \begin{pmatrix} 0 & -3 \\ 3 & 0 \end{pmatrix}_{2 \times 2} = \text{sum of all elements of skew sym. matrix} = 0$$

$$\text{v)} A = \begin{pmatrix} 0 & -3 & -8 \\ 3 & 0 & -5 \\ 8 & 5 & 0 \end{pmatrix}_{3 \times 3} = \text{sum} = 0$$

→ If i th row, j th column elem. of a matrix is in the form $a_{ij} = i^n - j^n$ ($n \geq 0$) then corresponding matrix is always skew symm.

* Note 3 :-

A matrix A is said to be symmetric if

$$A' = A \text{ or } a_{ij} = a_{ji}$$

* Note 4 :-

A matrix A is said to be skew symmetric

$$A' = -A \text{ or } a_{ij} = -a_{ji}$$

more
problem

The value of $\begin{vmatrix} 1+b & b & 1 \\ b & 1+b & 1 \\ 1 & 1 & 1 \end{vmatrix} = ?$

$$C_1 \rightarrow C_1 + C_2$$

$$\begin{vmatrix} 1+2b & b & 1 \\ 1+2b & 1+b & 1 \\ 1+2b & 2b & 1 \end{vmatrix} = 0$$

↑
proportional

Problem 2 :- Find the determinant of

$$\begin{vmatrix} 1/a & a & bc \\ 1/b & b & ca \\ 1/c & c & ab \end{vmatrix}$$

$$\begin{vmatrix} bc/abc & a & bc \\ ca/abc & b & ca \\ ab/abc & c & ab \end{vmatrix}$$

$$\begin{vmatrix} 1 & bc & a & bc \\ abc & ca & b & ca \\ ab & c & ab \end{vmatrix} = 0$$

↑
same

→ If there are no numbers inside determinant try to make
1 particular row or column same

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Problem 8 :- find the value of

$$\begin{vmatrix} x & a & a & a \\ a & x & a & a \\ a & a & x & a \\ a & a & a & x \end{vmatrix}$$

$$C_1 \rightarrow C_1 + C_2 + C_3 + C_4$$

$$= \begin{vmatrix} x+3a & a & a & a \\ x+3a & x & a & a \\ x+3a & a & x & a \\ x+3a & a & a & x \end{vmatrix}$$

$$= x+3a \begin{vmatrix} 1 & a & a & a \\ 1 & x & a & a \\ 1 & a & x & a \\ 1 & a & a & x \end{vmatrix}$$

$$R_2 \rightarrow R_2 - R_1 ; R_3 \rightarrow R_3 - R_1 ; R_4 \rightarrow R_4 - R_1$$

$$= x+3a \begin{vmatrix} 1 & a & a & a \\ 0 & x-a & 0 & 0 \\ 0 & 0 & x-a & 0 \\ 0 & 0 & 0 & x-a \end{vmatrix}$$

according to pt IV

$$= (x+3a) \{ 1 \times (x-a) \times (x-a) \times (x-a) \}$$

$$= (x+3a) (x-a)^3$$

* Short cut method :-

Procedure :-

→ If the diagonal elements are one category of same elements & non diagonal elements are other category of same elements

- 2) select the 1st row
 3) add all elements of 1st row
 4) take the product of (1st - 2nd) (1st - 3rd)
 (1st - 4th) ...

5) (3) × (4)

i.e.,

$$|A| = \begin{vmatrix} (x) & a & a & a \\ a & x & a & a \\ a & a & x & a \\ a & a & a & x \end{vmatrix}$$

Problem 1: The value of $A = \begin{pmatrix} 1+x & 2 & 3 & 4 \\ 1 & 2+x & 3 & 4 \\ 1 & 2 & 3+x & 4 \\ 1 & 2 & 3 & 4+x \end{pmatrix}$

$|A| = \begin{vmatrix} x+10 & 2 & 3 & 4 \\ x+10 & 2+x & 3 & 4 \\ x+10 & 2 & 3+x & 4 \\ x+10 & 2 & 3 & 4+x \end{vmatrix} = x+10 \begin{vmatrix} 1 & 2 & 3 & 4 \\ 1 & 2+x & 3 & 4 \\ 1 & 2 & 3+x & 4 \\ 1 & 2 & 3 & 4+x \end{vmatrix}$

$R_2 \rightarrow R_2 - R_1, \quad R_3 \rightarrow R_3 - R_1, \quad R_4 \rightarrow R_4 - R_1$

$(x+10) \begin{vmatrix} x+10 & 2 & 3 & 4 \\ 0 & x & 0 & 0 \\ 0 & 0 & x & 0 \\ 0 & 0 & 0 & x \end{vmatrix}$

$= (x+10) |x \ x \ x \ x|$
 $= x^3 (x+10)$

Problem 2:

$$A = \begin{vmatrix} 1+a & b & c & d \\ a & 1+b & c & d \\ a & b & 1+c & d \\ a & b & c & 1+d \end{vmatrix}$$

$$\therefore C_1 \rightarrow C_1 + C_2 + C_3 + C_4$$

$$= \begin{vmatrix} 1+a+b+c+d & b & c & d \\ 1+a+b+c+d & 1+b & c & d \\ 1+a+b+c+d & b & 1+c & d \\ 1+a+b+c+d & b & c & 1+d \end{vmatrix}$$

$$= (1+a+b+c+d) \begin{vmatrix} 1 & b & c & d \\ 1 & 1+b & c & d \\ 1 & b & 1+c & d \\ 1 & b & c & 1+d \end{vmatrix}$$

$$R_2 \rightarrow R_2 - R_1 ; R_3 \rightarrow R_3 - R_1 ; R_4 \rightarrow R_4 - f_1$$

$$= (1+a+b+c+d) \begin{vmatrix} 1 & b & c & d \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{vmatrix}$$

$$= 1+a+b+c+d \left[1 \left[\begin{smallmatrix} 1 & 1 \\ 1 & 1 \end{smallmatrix} \right] \right]$$

$$= 1+a+b+c+d$$

Problem 3: Find the value of

$$\begin{vmatrix} 1 & 1 & 1 \\ a & b & c \\ a^2 & b^2 & c^2 \end{vmatrix}$$

$$C_2 \rightarrow C_2 - C_1 \quad C_3 \rightarrow C_3 - C_1$$

$$A = \begin{vmatrix} + & - & + \\ 1 & 0 & 0 \\ a & b-a & c-a \\ a^2 & b^2-a^2 & c^2-a^2 \end{vmatrix}$$

$$= \left[(b-a)(c^2-a^2) - (c-a)(b^2-a^2) \right]$$

$$= (b-a)(c+a)(c-a) - (c-a)(b+a)(b-a)$$

$$= (b-a)(c-a) [c+a - b-a]$$

$$= (b-a)(c-a)(c-b)$$

$$= \{-(a-b)\} (c-a) \{-(b-c)\}$$

$$= (a-b)(b-c)(c-a)$$

* Shortcut method [for $(2 \times 2) (3 \times 3) \dots (n \times n)$]

If matrix is in the form

$$\begin{array}{ccccccc} 1 & 1 & 1 & 1 & \dots \\ \textcircled{a} & \textcircled{b} & \textcircled{c} & \textcircled{d} & \dots \\ a^2 & b^2 & c^2 & d^2 & \dots \\ a^3 & b^3 & c^3 & d^3 & \dots \\ \vdots & & & & \end{array}$$

then select the 2^{nd} row

& take $(2^{\text{nd}} - 1^{\text{st}}) (3^{\text{rd}} - 2^{\text{nd}}) \dots (\text{last} - 1^{\text{st}})$

$$\text{i.e., } (a-b)(b-c)(c-d)$$

* Inverse of a matrix *

Let $A = (a_{ij})$ be $n \times n$ matrix

i) Minor: Minor of an element a_{ij} is denoted by M_{ij} and is defined as

$$M_{ij} = (n-1)^{\text{th}} \text{ order determinant.}$$

ii) Cofactor: Cofactor of an element a_{ij} is denoted by A_{ij} and is defined as

$$A_{ij} = (-1)^{i+j} \cdot M_{ij}$$

Ex. Consider the matrix

$$A = \begin{pmatrix} 1 & 1 & 2 \\ 2 & 3 & 4 \\ 4 & 7 & -2 \end{pmatrix}$$

Consider the 2nd row 2nd element

$$a_{22} = 3$$

→ Minor of a_{22} is

$$M_{22} = \begin{pmatrix} 1 & 2 \\ 4 & -2 \end{pmatrix} = -2 - 8 = -10$$

→ Cofactor of a_{22} is

$$A_{22} = (-1)^{2+2} \times (-10) = -10$$

* Invertible matrix:

A matrix A is said to be invertible if we can find some other matrix B such that $AB = BA = I$ then B is called inverse of matrix A .

$$\begin{aligned} A^{-1} + B &= A^{-1} I \\ I + B &= A^{-1} I \\ \boxed{B = A^{-1}} \end{aligned}$$

* Singular matrix:

A matrix is said to be singular if $|A|=0$

* Non Singular matrix:

A matrix is said to be non singular if $|A| \neq 0$

Inverse of matrix exists if $|A| \neq 0$.

Note 1:

$$A^{-1} = \frac{\text{adj. } A}{|A|}$$

$$\Rightarrow \text{adj. } A = |A| \cdot A^{-1}$$

$$\Rightarrow A \cdot \text{adj. } A = A \cdot |A| \cdot A^{-1}$$

$$\Rightarrow A \cdot \text{adj. } A = |A| \cdot I = \text{adj. } A \cdot A$$

Note 2:

$$A^{-1} = \frac{\text{adj. } A}{|A|}$$

$$\Rightarrow (\text{adj. } A)^{-1} \cdot A^{-1} = (\text{adj. } A)^{-1} \cdot \frac{\text{adj. } A}{|A|}$$

$$\Rightarrow (\text{adj. } A)^{-1} \cdot A^{-1} = \frac{I}{|A|} \quad \because A \cdot A^{-1} = I$$

$$\Rightarrow (\text{adj. } A)^{-1} \cdot A^{-1} \cdot A = \frac{I \cdot A}{|A|}$$

$$\Rightarrow (\text{adj. } A)^{-1} = \frac{A}{|A|}$$

Note 3: Let A be an $n \times n$ matrix.

We know that

$$\begin{aligned} \text{adj } A &= |A| \cdot A^{-1} \\ \Rightarrow |\text{adj } A| &= \left| |A| \cdot \underset{k}{\underset{\downarrow}{A}} \right| \quad \boxed{|KA| = k^n |A|} \\ &\Rightarrow |A|^n \cdot |A^{-1}| \\ &\Rightarrow |A|^n \cdot |A|^{-1} \\ \therefore \boxed{|\text{adj } A| = |A|^{n-1}} \end{aligned}$$

Replacing A by $\text{adj } A$ in the above relation

$$\begin{aligned} |\text{adj } \text{adj } A| &= |\text{adj } A|^{n-1} \\ &= \{ |A|^{n-1} \}^{n-1} \end{aligned}$$

$$\therefore \boxed{|\text{adj } \text{adj } A| = |A|^{(n-1)^2}}$$

Similarly,

$$\therefore \boxed{|\text{adj } \text{adj } \text{adj } A| = |A|^{(n-1)^3}}$$

& so on..

Note 4: We know that

$$A \cdot \text{adj } A = |A| \cdot I$$

Replacing A by $\text{adj } A$

$$\Rightarrow \text{adj } A (\text{adj } \text{adj } A) = |\text{adj } A| \cdot I$$

$$\Rightarrow \text{adj } A (\text{adj } \text{adj } A) = |A|^{n-1} \cdot I$$

pre multiply both side by A

$$\Rightarrow A \cdot \text{adj } A (\text{adj } \text{adj } A) = A \cdot |A|^{n-1} \cdot I$$

$$\boxed{A \cdot I = A}$$

$$\Rightarrow |A| \cdot I (\text{adj } \text{adj } A) = |A|^{n-1} \cdot A$$

$$\Rightarrow \text{adj}(\text{adj} \cdot \text{adj} \cdot A) = |\text{A}|^{n-1} \cdot A$$

Pno

$$\Rightarrow \text{adj} \cdot \text{adj} \cdot A = \frac{|\text{A}|^{n-1} \cdot A}{|\text{A}|}$$

$$\Rightarrow \text{adj} \cdot \text{adj} \cdot A = |\text{A}|^{n-2} A$$

Note 5 :- A matrix A is said to be orthogonal if

$$\text{A}^T = \text{A}^{-1} \quad [A \cdot A^T = I]$$

$$A^{-1} \cdot A \cdot A^T = A^{-1} \cdot I$$

$$I \cdot A^T = A^{-1} \cdot I$$

$$\boxed{A^T = A^{-1}}$$

Note 6 :- If A is an orthogonal matrix then A^{-1} & A^T are also orthogonal matrices.

Date 2010
Mech 1M
problem 1

For the matrix $M = \begin{pmatrix} 3/5 & 4/5 \\ x & 3/5 \end{pmatrix}$ such that

$$M^T = M^{-1} \quad \text{The value of } x \text{ is ?}$$

$$\frac{3}{5}(x) + \frac{4}{5}\left(\frac{3}{5}\right) = 0$$

$$\boxed{x = -4/5}$$

Note :- If A is an orthogonal matrix then its rows & columns are pair wise orthogonal.
 But converse of the stmt may or may not be true.
 i.e., If rows & columns of matrix are pair wise orthogonal, then the matrix may or may not be orthogonal.

Problem : If $A = (a_{ij})$ $s \times s$ such that

$$i) a_{ij} = i - j, \quad \forall i, j$$

$$ii) a_{ij} = i^2 - j^2, \quad \forall i, j$$

find A^{-1} in each case

$$\Rightarrow a_{ij} = i - j$$

$$\begin{aligned} a_{ji} &= j - i \\ &= -(i - j) \end{aligned}$$

$$= -a_{ij}$$

$\therefore [a_{ij} = -a_{ji}] \quad \because A \Rightarrow \text{skew symmetric matrix}$

$$\therefore \Rightarrow A^T = -A$$

$$\Rightarrow |A^T| = |-A| \quad \text{as } |KA| = k^n |A|$$

$$\Rightarrow (-1)^s |A|$$

$$\therefore |A^T| = -1 |A|$$

$$|A| = -1 |A|$$

$$|A| + |A| = 0$$

$$2|A| = 0$$

$$2 \neq 0 \quad \therefore |A| = 0$$

$\therefore A^T$ does not exist.

Note : ① Inverse of any odd order skew symm matrix does not exist.

Reason : Since every odd order skew symm matrix is singular i.e., $|A| = 0$.

② Inverse of even order skew symm matrix exists.

Reason : Since every even order skew symm matrix is non singular i.e., $|A| \neq 0$.

5>

$$A = \begin{pmatrix} 0 & -3 \\ 3 & 0 \end{pmatrix}_{2 \times 2}$$

$$A^T = \begin{pmatrix} 0 & 3 \\ -3 & 0 \end{pmatrix} = -\begin{pmatrix} 0 & -3 \\ 3 & 0 \end{pmatrix}$$

$$A^T = -A$$

$$\therefore |A| = \begin{vmatrix} 0 & -3 \\ 3 & 0 \end{vmatrix} = 0 + 9 = (3)^2$$

\Rightarrow The determinant of even order skew-symm. matrix is a perfect square.

\Rightarrow If i^{th} row, j^{th} column element of a matrix is in the form

$a_{ij} = i^{\alpha} - j^{\beta}$ ($\alpha, \beta \geq 0$), the corresponding matrix is always skew-symmetric.

Grade 10
Instu 2m

problem 3:- If X and Y are two non zero matrices of the same order such that $XY = (0)_{n \times n}$, then

- A) $|X| \neq 0$; $|Y| = 0$
- B) $|X| = 0$; $|Y| \neq 0$
- C) $|X| \neq 0$; $|Y| \neq 0$
- D) $|X| = 0$; $|Y| = 0$

$$XY = 0$$

take determinants on b.s

$$|XY| = 0$$

$$|X||Y| = 0$$

then $|X|=0$ or $|Y|=0$ or both $|X|=0$ & $|Y|=0$

∴ C is omitted

Let $|X| = 0$, $|Y| \neq 0 \therefore Y^{-1} \Rightarrow$ exist

$$XY = 0 \Rightarrow XYY^{-1} = 0 \cdot Y^{-1}$$

$$\Rightarrow XI = 0$$

$\Rightarrow X = 0$ (contradiction to hypothesis)

$$\boxed{|X| = 0}$$

If we choose $|Y| = 0$, $|X| \neq 0$ then we get

$$\boxed{|X| = 0}$$

$$\therefore \boxed{|X| = |Y| = 0}$$

Problem 4: If A, B, C, D, E, F, G are non-singular matrices of the same order such that $CEDBGAFAE = I$ then B^{-1} is

$$\Rightarrow \overset{CE}{\overleftarrow{D}} \overset{B}{\overleftarrow{G}} \overset{A}{\overleftarrow{F}} \overset{A}{\overleftarrow{E}} = I$$

$$\overset{C}{\overleftarrow{C}} \overset{E}{\overleftarrow{D}} \overset{B}{\overleftarrow{G}} \overset{A}{\overleftarrow{F}} \overset{A}{\overleftarrow{E}} = \overset{C}{\overleftarrow{C}} I$$

$$I \overset{E}{\overleftarrow{D}} \overset{B}{\overleftarrow{G}} \overset{A}{\overleftarrow{F}} \overset{A}{\overleftarrow{E}} = \overset{C}{\overleftarrow{C}} I$$

$$EDBGAFAE = \overset{C}{\overleftarrow{C}}$$

$$E^T E D B G A F A E = E^T \overset{C}{\overleftarrow{C}}$$

$$IDBGAFAE = E^T \overset{C}{\overleftarrow{C}}$$

$$D^T D B G A F A E = D^T E^T \overset{C}{\overleftarrow{C}}$$

$$BGAFAE = D^T E^T \overset{C}{\overleftarrow{C}}$$

$$BGAFAE^T = D^T E^T \overset{C}{\overleftarrow{C}} E^T$$

$$BGAFAA^T = D^T E^T \overset{C}{\overleftarrow{C}} E^T A^T$$

$$BA^T = D^T E^T \overset{C}{\overleftarrow{C}} F^T A^T A^T$$

$$BGAFA^T = D^T E^T \overset{C}{\overleftarrow{C}} F^T A^T A^T G^T$$

$$\boxed{B = D^T E^T \overset{C}{\overleftarrow{C}} F^T A^T A^T G^T}$$

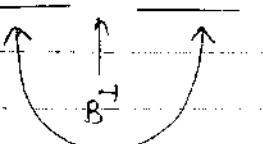
$$\boxed{(A^T)^{-1} = B^T A^{-1}}$$

$$\therefore \boxed{B^{-1} = (D^T E^T \overset{C}{\overleftarrow{C}} F^T A^T A^T G^T)^{-1}}$$

$$\boxed{B^{-1} = G A F C E D}$$

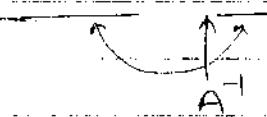
* Short cut method :-

$$\underline{C E D B G A F A E}$$



$$= G A F C E D$$

$$\text{CE DB G A F} = \text{F C E D B G}$$



By

$$\text{C E D B G A F} = \text{C E D B G A}$$

Prob No. 6. Let k be a true real no. & let

$$A = \begin{pmatrix} 2k-1 & 2\sqrt{k} & 2\sqrt{k} \\ 2\sqrt{k} & 1 & -2k \\ -2\sqrt{k} & 2k & -1 \end{pmatrix} \quad B = \begin{pmatrix} 0 & 2k-1 & \sqrt{k} \\ 1-2k & 0 & 2\sqrt{k} \\ -\sqrt{k} & -2\sqrt{k} & 0 \end{pmatrix}_{3 \times 3}$$

find i) $\det(\text{adj. } B)$ ii) $\det(\text{adj. } A)$

iii) If $\det(\text{adj. } A) = 10^6$, the value of $k = ?$

i)

$$|\text{adj. } B| = |B|^{n-1} = 0$$

\therefore determinant of odd order skew-sym. matrix
is zero.

ii)

$$|\text{adj. } A| = |A|^{n-1} = |A|^{8+1} = |A|^2 \quad \text{eq } (1)$$

$$|A| = \begin{vmatrix} 2k-1 & 2\sqrt{k} & 2\sqrt{k} \\ 2\sqrt{k} & 1 & -2k \\ -2\sqrt{k} & 2k & -1 \end{vmatrix}$$

$$R_2 \rightarrow R_2 + R_3$$

$$\begin{vmatrix} 2k-1 & 2\sqrt{k} & 2\sqrt{k} \\ 0 & 1+2k & -2k-1 \\ -2\sqrt{k} & 2k & -1 \end{vmatrix} \quad \text{EE-2M}$$

$$c_2 \rightarrow c_2 + c_3$$

$$\begin{vmatrix} 2k-1 & 4\sqrt{k} & 2\sqrt{k} \\ 0 & 0 & -(1+2k) \\ -2\sqrt{k} & 2k-1 & -1 \end{vmatrix}$$

$$\Rightarrow - \left\{ -(1+2k) \left((2k+1)^2 + 8k \right) \right\}$$

$$(1+2k) \left((2k+1)(2k+1) \right)$$

$$\Rightarrow (1+2k) (4k^2 - 4k + 1 + 8k)$$

$$\Rightarrow (1+2k) (4k^2 + 4k + 1)$$

$$\Rightarrow (2k+1) (2k+1)^2 = (2k+1)^3$$

put in eqⁿ(1)

$$\Rightarrow [(2k+1)^3]^2 = (2k+1)^6$$

iii) $|\text{adj. } A| = 10^6$
 $(2k+1)^6 = 10^6$

$$2k+1 = 10$$

$$2k = 9$$

$$\therefore k = 9/2$$

problem No. 5: If A, B, C, D are non singular matrices of the same order such that $ABCD = I$ then B^{-1} is?

$$\overbrace{A B C D}^{B^{-1}} = I$$

$$\therefore B^{-1} = CDA$$

Prob. No. 7:-

Find the inverse of foll. matrices -

EE-05
2m

$$A = \begin{pmatrix} 1 & 0 & -1 \\ 2 & 1 & -1 \\ 2 & 3 & 2 \end{pmatrix}$$

EE-05
2m H.W.

$$A = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 1 & -1 \\ 0 & 0 & 1 \end{pmatrix}$$

EE-98
2m

$$A = \begin{pmatrix} 5 & 0 & 2 \\ 0 & 3 & 0 \\ 2 & 0 & 1 \end{pmatrix}$$

→ →

$$A = \begin{pmatrix} 1 & 0 & -1 \\ 2 & 1 & -1 \\ 2 & 3 & 2 \end{pmatrix}$$

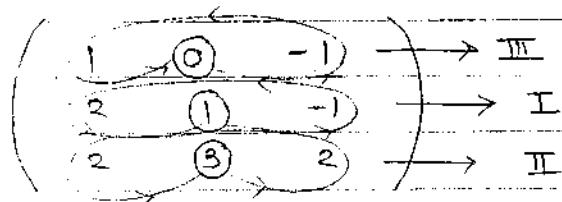
adj A

|A|

$$\rightarrow |A| = \begin{vmatrix} 1 & 0 & -1 \\ 2 & 1 & -1 \\ 2 & 3 & 2 \end{vmatrix}$$

$$= 1 [2+3] - 1 [6-2] = 5 - 4 = 1$$

→ adj A =



$$\left(\begin{array}{ccc} 1 & 3 & 0 \\ -1 & 2 & -1 \\ 2 & 2 & 1 \\ 1 & 3 & 0 \end{array} \right) \quad \therefore \text{adj } A = \begin{pmatrix} 5 & -3 & 1 \\ -6 & 6 & 1 \\ 4 & -3 & 1 \end{pmatrix}$$

$$\therefore A^{-1} = \begin{pmatrix} 5 & -3 & 1 \\ -6 & 6 & 1 \\ 4 & -3 & 1 \end{pmatrix}$$

Procedure : (3x3)

- Select the middle row middle element & move in anticlockwise direction to complete 1 cycle
 The corresponding element will be return in the 1st column separately

- 2) Select the 3rd row middle element & move in anti-clock wise direction to complete 1 cycle
The corresponding element will be return in the 2nd column separately.
- 3) Repeat the same process with 1st row also.
- 4) Copy 1st column as a last column & find det. of smaller matrices

Procedure : (2 × 2)

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \quad A^T = \frac{1}{ad - bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$$

~~EC-2008
2m~~

Prob. No.8 :- Given an orthogonal matrix

$$A = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & -1 & -1 \\ 1 & -1 & 0 & 0 \\ 0 & 0 & 1 & -1 \end{pmatrix} \text{ then } (A A^T)^{-1} \text{ is } ?$$

$$\text{Orthogonal} \Rightarrow (A A^T) = I \quad (A A^T)^{-1} = I^{-1}$$

but Inverse / Adj. of Identity matrix is
Identity matrix only

$$\therefore (A A^T)^{-1} = I$$

Prob. No.9 Find the inverse of $A = \begin{pmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix}$

→ Here A is an orthogonal matrix therefore,
 $A^{-1} = A^T$

* Rank of Matrix *

- * Submatrix: A matrix obtained by deleting some rows or columns or both is called as submatrix.
Ex. Consider the matrix.

$$\begin{aligned}
 A &= \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 1 & -1 & 0 \end{pmatrix} \\
 B_1 &= \begin{pmatrix} 1 & 2 \\ 4 & 5 \end{pmatrix} \quad B_2 = \begin{pmatrix} 2 & 3 \\ 5 & 6 \end{pmatrix} \quad B_3 = \begin{pmatrix} 4 & 5 & 6 \\ 1 & -1 & 0 \end{pmatrix}
 \end{aligned}$$

sub matrices of A

- * Minor: The determinant of square sub matrix is called its minor.

Ex.

$$\begin{aligned}
 |B_1| &= \begin{vmatrix} 1 & 2 \\ 4 & 5 \end{vmatrix} = 5 - 8 = -3 \\
 |B_2| &= \begin{vmatrix} 2 & 3 \\ 5 & 6 \end{vmatrix} = 12 - 15 = -3
 \end{aligned}$$

} minors of A

- * Rank: If the determinant of highest possible square matrix is not equal to zero then the order of the determinant is called rank of matrix.

Ex. Find the rank of

$$A = \begin{pmatrix} 1 & 3 & -2 & 1 \\ 2 & -1 & 4 & 2 \\ 1 & -11 & 14 & 5 \end{pmatrix}$$

3×4

$$\left| \begin{array}{ccc|c} 1 & 3 & -2 & 1 \\ 2 & -1 & 4 & 2 \\ 1 & -11 & 14 & 5 \end{array} \right| = 1[-14 + 44] - 3[28 - 4] + 2[-22 + 1] \\ = 30 - 72 + 42 \\ = 0$$

$$\left| \begin{array}{ccc|c} 3 & -2 & 1 & 3[28 - 28] + 2[-5 + 22] + 1[-14 + 44] \\ -1 & 4 & 2 & -24 + 34 + 30 = 40 \neq 0 \\ -11 & 14 & 5 & \end{array} \right| = 3 \times 3$$

\therefore Rank of $A = \rho(A) = 3$ i.e., order of matrix

* Row Echelon form:-

A matrix A is said to be in Row Echelon form iff

- i) zero rows should occupy the last rows, if any.
- ii) the no. of zeros before a non-zero element of each row is less than no. of such zeros before a non-zero element of the next row.

e.g. Ex

$$A = \begin{pmatrix} 0 & 1 & 2 & 3 & 4 & 0 \\ 0 & 0 & -1 & 0 & 2 & 0 \\ 0 & 0 & 0 & 4 & 5 & 0 \\ 0 & 0 & 0 & 7 & 9 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

6×6

Condition 1 satisfy

Note: The rank of Row Echelon form matrix is equal to no. of non zero rows.

$$\text{rank}(A) = 4 \leftarrow \text{Linearly Independent Row/Vector}$$

→ These non zero rows are called Linearly Independent rows / vector.

→ To reduce any matrix into row echelon form we should use only row operations.

→ Every upper triangular matrix is in R.E.form but every R.E. form will not be an upper triangular matrix. No

Ex. 1

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 0 & -4 & 2 \\ 0 & 0 & 7 \end{pmatrix}$$

Upper $\Delta^{1\text{st}}$ matrix

∴ A is in R.E.form

Ex. 2

$$A = \begin{pmatrix} 0 & 2 & 3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

Not Upper $\Delta^{1\text{st}}$ matrix

but A is in R.E.form

Upper $\Delta^{1\text{st}}$ matrix \Rightarrow R.E.form R.E.form $\not\Rightarrow$ Upper $\Delta^{1\text{st}}$ matrix

* Column Echelon form :-

A matrix A is said to be in column echelon form iff

i) zero ~~rows~~ columns should occupy the last columns, if any.

ii) The no. of zeros above a non zero element of each column is less than the no. of zeros above a

non zero element of the next column

Ex. Consider the matrix

$$A = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 2 & 0 & 0 & 0 \\ 1 & 2 & 3 & 0 & 0 \\ 1 & 2 & 3 & 4 & 0 \end{pmatrix}$$

Note:-

Rank of matrix in Column Echelon form is equal to no. of non zero columns.

$$\therefore R(A) = 4$$

- To reduce any matrix into column echelon form, we should use only column operations
- Every lower Δ^m matrix will be in column echelon form.
but every C.E. form will not be a lower Δ^m matrix.

Ex. 1

$$A = \begin{pmatrix} 1 & 0 & 0 \\ 3 & 5 & 0 \\ 9 & 4 & 5 \end{pmatrix}$$

Lower Δ^m matrix

Lower $\Delta^m \Rightarrow$ C.E. form

Ex. 2

$$A = \begin{pmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 2 & 1 & 0 \end{pmatrix}$$

C.E. form \neq Lower Δ^m matrix

Example : Consider the matrix $A = \begin{pmatrix} 1 & 3 & -2 \\ 2 & -1 & 4 \\ 1 & -11 & 14 \end{pmatrix}$

\Rightarrow Row Echelon form

$$R_2 \rightarrow R_2 - 2R_1 \quad R_3 \rightarrow R_3 - R_1$$

$$A = \begin{pmatrix} 1 & 3 & -2 \\ 0 & -7 & 8 \\ 0 & -14 & 16 \end{pmatrix} \quad R_3 \rightarrow R_3 - 2R_1$$

$$A = \begin{pmatrix} 1 & 3 & -2 \\ 0 & 7 & 8 \\ 0 & 0 & 0 \end{pmatrix} \quad \therefore |S(A)| = 2$$

\Rightarrow Column Echelon form

$$c_2 \rightarrow c_2 - 3c_1 \quad c_3 \rightarrow c_3 + 2c_1$$

$$A = \begin{pmatrix} 1 & 0 & 0 \\ 2 & -7 & 8 \\ 1 & -14 & 16 \end{pmatrix} \quad c_3 \rightarrow 7c_3 + 8c_2$$

$$A = \begin{pmatrix} 1 & 0 & 0 \\ 2 & -7 & 0 \\ 1 & -14 & 0 \end{pmatrix} \quad \therefore |S(A)| = 2$$

Note : Rank of matrix = no of non zero rows if
no of non zero columns.

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No 7

2)

$$A = \begin{pmatrix} 5 & 0 & 2 \\ 0 & 3 & 0 \\ 2 & 0 & 1 \end{pmatrix} \quad A^{-1} = \frac{\text{adj. } A}{|A|}$$

$$|A| = \begin{vmatrix} 5 & 0 & 2 \\ 0 & 3 & 0 \\ 2 & 0 & 1 \end{vmatrix} = 3[5 - 4] = -3$$

$$\text{adj. } |A| = \begin{pmatrix} 3 & 0 & 0 & 3 \\ 0 & 1 & 2 & 0 \\ 0 & 2 & 5 & 0 \\ 3 & 0 & 0 & 3 \end{pmatrix}$$

$$\text{adj. } A = \begin{pmatrix} 3 & 0 & -6 \\ 0 & 1 & 0 \\ -6 & 0 & 15 \end{pmatrix} \quad \therefore A^{-1} = \frac{1}{3} \begin{pmatrix} 3 & 0 & -6 \\ 0 & 1 & 0 \\ -6 & 0 & 15 \end{pmatrix}$$

$$3) \quad A = \begin{pmatrix} 1 & -1 & 0 \\ 1 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \quad A^{-1} = \frac{\text{adj. } A}{|A|}$$

$$|A| = \begin{vmatrix} 1 & -1 & 0 \\ 1 & 1 & 1 \\ 0 & 0 & 1 \end{vmatrix} = [1+1] = 2$$

$$\text{adj. } A = \begin{pmatrix} 1 & 0 & -1 & 1 \\ 1 & 1 & 0 & 1 \\ 1 & 0 & 1 & 1 \\ 1 & 0 & -1 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 1 & -1 & 1 \\ -1 & 1 & 1 & -1 \\ 0 & 0 & 2 & 0 \end{pmatrix}$$

$$\therefore A^{-1} = \frac{1}{2} \begin{pmatrix} 1 & 1 & -1 \\ -1 & 1 & 1 \\ 0 & 0 & 2 \end{pmatrix}$$

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2m
pm

* Information regarding rank of matrix :

$$1) \quad r(0_{n \times n}) = 0$$

$$2) \quad r(I_{n \times n}) = n$$

$$3) \quad r\{\text{adj. } I_{n \times n}\} = n$$

$$4) \quad r(A) = r(A^T)$$

$$5) \quad r(A+B) \leq r(A) + r(B)$$

$$6) \quad r(A-B) \geq r(A) - r(B)$$

7) $r(AB) \geq r(A) + r(B) - n$, if A & B are $n \times n$ matrices

$$8) \quad r(AB) \leq \min\{r(A), r(B)\}$$

9) If A is an $m \times n$ matrix, then $r(A) \leq \min(m, n)$

10) If $r(A_{n \times n}) = 0$, then $r(\text{adj. } A) = 0$

11) If $r(A_{n \times n}) = n-1$, then $r(\text{adj. } A) = 1$

12) If $r(A_{n \times n}) = n-2$, then $r(\text{adj. } A) = 0$

Qn

Problem 1: If $A = (a_{ij})_{m \times n}$, such that $a_{ij} = i \cdot j + i \cdot j$
then $r(A) = ?$

$$A = \begin{pmatrix} 1 & 2 & 3 & \dots & n \\ 2 & 4 & 6 & \dots & 2n \\ 3 & 6 & 9 & \dots & 3n \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ m & 2m & 3m & \dots & mn \end{pmatrix}_{m \times n}$$

To find $r(A)$, convert the matrix into Row Echelon form.

$$R_2 \rightarrow R_2 - 2R_1, \quad R_3 \rightarrow R_3 - 3R_1, \quad R_m \rightarrow R_m - mR_1$$

$$A = \begin{pmatrix} 1 & 2 & 3 & \dots & n \\ 0 & 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 0 \end{pmatrix}_{m \times n}$$

$r(A) = \text{No. of non-zero rows} = 1$

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Problem 2: If $y = (x_1, x_2, \dots, x_n)^T$ is n -tuple non zero vector then

$$\Rightarrow g(xx^T)$$

$$\Rightarrow g(x^Tx)$$

$$\therefore g(x^Tx)$$

$$x = (x_1, x_2, \dots, x_n)^T$$

$$x = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} \quad x^T = (x_1, x_2, \dots, x_n)_{n \times 1}$$

$$g(xx^T) \leq \min \{g(x), g(x^T)\}$$

$$g(xx^T) \leq \min \{1, 1\}$$

$$\Rightarrow g(xx^T) \leq 1 \leq \begin{cases} 1 & x \neq 0 \\ 0 & x = 0 \end{cases} \quad (x \rightarrow \text{Non zero vector})$$

$$\therefore \boxed{g(xx^T) = 1}$$

problem 3: The rank of 5×6 matrix Q is 4 then which of the foll statmt is true.

- a) Q will have 4 L.I. rows & 4 L.I. columns
- b) Q will have 4 L.I. rows & 5 L.I. columns
- c) $Q Q^T$ is invertible
- d) $Q^T Q$ is invertible

$$g(Q) = 4$$

\therefore 4 non zero rows or columns

option (a)

option (b): X

If det of matrix $\neq 0$, then order of matrix $\leq n$

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Page

option C

$$(Q)_{5 \times 6}, (Q)^T_{6 \times 5}$$

$$(QQ^T)_{5 \times 5} \rightarrow \text{Invertible}$$

$$(QQ^T)^{-1} \text{ exists}$$

$$|(QQ^T)_{5 \times 5}| \neq 0 \Rightarrow \rho(QQ^T) = 5 \quad (\text{contradiction to stat})$$

option D

$$(Q^T)_{6 \times 5}, (Q)_{5 \times 6}$$

$$(Q^T Q)_{6 \times 6} \rightarrow \text{Invertible}$$

$$(Q^T Q)^{-1} \text{ exists}$$

$$|(Q^T Q)_{6 \times 6}| \neq 0 \Rightarrow \rho(Q^T Q) = 6 \quad (\text{contradiction to stat})$$

* Linearly Dependent & Independent vectors *

Two vectors x_1 & x_2 are L.D. if one vector is expressed as multiple of other vector.

x_1 & $x_2 \Rightarrow$ same directional vectors

Example

$$x_1 = \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \quad x_2 = \begin{pmatrix} 3 \\ 6 \end{pmatrix}$$

$$x_2 = 3 \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$\boxed{x_2 = 3 x_1} \quad \text{or} \quad \boxed{x_1 = \frac{1}{3} x_2}$$

$\therefore x_1, x_2 \Rightarrow \text{L.D.}$

$\vec{x}_1 = \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \vec{x}_2 = \begin{pmatrix} 3 \\ 6 \end{pmatrix}$

\Rightarrow Two vectors in \mathbb{R}^2 are L.D. if and only if they are collinear.

\Rightarrow Three vectors in \mathbb{R}^3 are L.D. iff they are coplanar.

\Rightarrow Two vectors \vec{x}_1, \vec{x}_2 are L.I. iff it is not possible to express one vector as a multiple of other vector.

Example:

$$\vec{x}_1 = \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \quad \vec{x}_2 = \begin{pmatrix} 3 \\ 4 \end{pmatrix}$$

$$\vec{x}_1 \neq k\vec{x}_2 \quad \text{OR} \quad \vec{x}_2 \neq k\vec{x}_1$$

$$\therefore \vec{x}_1, \vec{x}_2 \Rightarrow \text{L.I.}$$

* Linearly Dependent vectors: (for 2 or more than 2 vectors)

A set of r n -vectors $\vec{x}_1, \vec{x}_2, \dots, \vec{x}_r$ are said to be linearly dependent if there exist r scalars k_1, k_2, \dots, k_r such that

$$k_1\vec{x}_1 + k_2\vec{x}_2 + \dots + k_r\vec{x}_r = 0$$

where k_1, k_2, \dots, k_r not all zeros.

(at least one k value is a non-zero no.)

* Linearly Independent vectors:

A set of r n -vectors $\vec{x}_1, \vec{x}_2, \dots, \vec{x}_r$ are said to be linearly independent if there exist r scalars k_1, k_2, \dots, k_r such that

$$k_1\vec{x}_1 + k_2\vec{x}_2 + \dots + k_r\vec{x}_r = 0$$

all zeros

* Criteria for L.I & L.D

→ If $\rho(A) = \text{no. of given vectors}$ or $|A| \neq 0$,
the given vectors are said to be L.I.

Ex.

Consider the vectors

$$x_1 = (1 \ 2 \ 2), \ x_2 = (2 \ 1 \ 2), \ x_3 = (2 \ 2 \ 1)$$

$$|A| = \begin{vmatrix} 1 & 2 & 2 \\ 2 & 1 & 2 \\ 2 & 2 & 1 \end{vmatrix} = 1(1-4) - 2(2-4) + 2(4-2) \\ = -3 + 4 + 4 \\ = 5$$

$$\therefore |A| = 5 \neq 0 \Rightarrow \text{L.I.}$$

2) If $\rho(A) < \text{no. of given vectors}$ or $|A| = 0$,
the given vectors are said to be L.D.

Ex.

Consider the vectors

$$x_1 = (1 \ 3 \ -2), \ x_2 = (2 \ -1 \ 4), \ x_3 = (1 \ -11 \ 14)$$

$$|A| = \begin{vmatrix} 1 & 3 & -2 \\ 2 & -1 & 4 \\ 1 & -11 & 14 \end{vmatrix} = 1(-14+44) - 3(28-4) - 2(-22+1) \\ = 30 - 72 + 42 \\ |A| = 0 \Rightarrow \text{L.D.}$$

3) If the given vectors are L.D. then any one of the vector can be expressed as linear combination of other vectors

diff. of ist

4) If the given vectors are L.I. then it is not possible to write any one of the vector as linear combination of other vectors.

at least one elem must be nonzero

∴ Every non zero vector is L.I. vector.

Ex.

Consider the vector

$$\begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix}$$

$$k \cdot x = 0$$

$$k \begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

Non zero vector

$$k \neq 0$$

$\therefore x \rightarrow$ L.I vector

columns/rows of Identity matrix

6) The set of unit vectors are always L.I.

Ex. Consider the set of vectors

$$x_1 = (1, 0, 0), x_2 = (0, 1, 0), x_3 = (0, 0, 1)$$

$$|A| = \begin{vmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{vmatrix} = 1$$

$$|A| = 1 \neq 0 \Rightarrow \text{L.I. vectors}$$

7) The set of vectors having at least one zero vector are L.D.

Ex. Consider the set of vectors

$$x_1 = (1, 2, 3), x_2 = (0, 0, 0), x_3 = (1, -1, 4)$$

$$|A| = \begin{vmatrix} 1 & 2 & 3 \\ 0 & 0 & 0 \\ 1 & -1 & 4 \end{vmatrix} = 0 \therefore x_1 = x_2 = x_3 \Rightarrow \text{L.D.}$$

$$|A| = 0 \Rightarrow \text{L.D.}$$

No. of vectors = r
No. of elements in each vector = n

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- 8) A set of r vectors with $r < n$ components (elements) are always L.I., provided the vectors should not be in the same direction.

Ex. Consider the vectors

$$(1 -1 2 1), (1 2 3 -4), (2 3 4 9)$$

$$r = 3$$

$$n = 4$$

here, $r < n \Rightarrow$ L.I.

- 9) A set of r vectors with $r > n$ components then given vectors are L.D.

Ex. consider the vectors

$$x_1 = (1 1 2)$$

$$x_2 = (1 -1 0) \quad r = 3$$

$$x_3 = (1 -1 5) \quad n = 3$$

$$x_4 = (9 -5 4) \quad \text{here, } r > n \Rightarrow \text{L.D.}$$

$\therefore x_1, x_2, x_3, x_4$ are L.D.

- 10) A set of r vectors with $r = n$ components may be L.I. or L.D.

* Dimension & Basis of the vectors

* Dimension :- It is defined as no. of L.I. vectors.

Dimension = No. of L.I. vectors = no. of non zero rows in Row Echelon form = no. of non zero columns in Column Echelon form.

* Basis :- It is defined as the set of L.I. vectors.

Basis = set of L.I. vectors = set of non zero rows in R.E. form = set of non zero columns in C.E. form.

Problem 1: Test whether the following vectors are L.D or L.I.
Also find their dimension & basis.

$$\begin{pmatrix} 1 & -1 & 0 \\ 4 & -3 & 1 \\ -6 & 2 & 2 \end{pmatrix}, \begin{pmatrix} 1 & 1 & 0 \\ 4 & -3 & 1 \\ -6 & 2 & 2 \end{pmatrix}$$

$n = 4$ here $r = n \therefore$ may be L.D or L.I.

$$A =$$

$$\left| \begin{array}{cccc} 1 & 1 & -1 & 0 \\ 4 & -3 & 1 & 1 \\ -6 & 2 & 2 & 2 \\ 9 & 9 & -6 & 3 \end{array} \right|$$

$$R_2 \rightarrow R_2 - 4R_1, \quad R_3 \rightarrow R_3 + 6R_1, \quad R_4 \rightarrow R_4 - 9R_1$$

Step 1

$$A =$$

$$\left| \begin{array}{cccc} 1 & 1 & -1 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 8 & -4 & 2 \\ 0 & 0 & 3 & 3 \end{array} \right|$$

$$-3+4$$

$$2+6 = 8$$

$$-6+9$$

$$R_2 \leftrightarrow R_3$$

$$A =$$

$$\left| \begin{array}{cccc} 1 & 1 & -1 & 0 \\ 0 & 8 & -4 & 2 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 3 & 3 \end{array} \right|$$

$$R_4 \rightarrow R_4 - 3R_3$$

$$A =$$

$$\left| \begin{array}{cccc} 1 & 1 & -1 & 0 \\ 0 & 8 & -4 & 2 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{array} \right|$$

3 L.I. Vectors

→ whenever a matrix is reduced to E.F.C.E form then rank of matrix = Dimension
 → Set of L.I vectors are called basis of the space

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 10/10

$$r(A) = 3 < \text{No. of given vectors (4)}$$

$$\therefore x_1, x_2, x_3, x_4 \Rightarrow \text{L.I.D}$$

or

$$\begin{vmatrix} 1 & 1 & -1 & 0 \\ 0 & 8 & -4 & 2 \\ 0 & 0 & 1 & 1 \end{vmatrix} \neq 0$$

$$\text{Dimension} = 3$$

$$\text{Basis} = \left\{ (1, 1, -1, 0), (0, 8, -4, 2), (0, 0, 1, 1) \right\}$$

Gate^(2m)

Problem: If q_1, q_2, \dots, q_m are n -dimensional vectors with $m < n$. The vectors are L.I.D. The matrix Q is q_1, q_2, \dots, q_m as columns. The rank of Q = ?
 1st col 2nd col ... mth col

a) m b) n c) between m & n d) ∞

$$q_1 = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$$

$$\therefore q_1, q_2, q_3, \dots, q_m$$

$$Q = \begin{pmatrix} | & | & | & | \\ q_1 & q_2 & q_3 & \cdots & q_m \\ | & | & | & | & | \end{pmatrix}_{n \times m} \Rightarrow (Q)_{n \times m}$$

$$r(Q_{n \times m}) \leq \min(n, m)$$

but $m < n$ — given

$$\therefore r(Q_{n \times m}) \leq m$$

$$\therefore \boxed{r(Q) \leq m}$$

from criteria (2)

Nullity of a matrix :-

(Page)

* Nullity:— It is denoted by $N(A)$.

It is defined as the difference b/w order of matrix and rank of matrix.

$$N(A) = n(A) - R(A)$$

↓ ↓ ↓
nullity order rank

→ Nullity of a non-singular matrix is always zero.

Let A be an $n \times n$ non singular matrix.

Then,

$$|A|_{n \times n} \neq 0$$

$$\therefore R(A) = n$$

$$N(A) = n(A) - R(A)$$

$$= n - n$$

$$\therefore N(A) = 0$$

Ques: The nullity of $A = \begin{pmatrix} k & 1 & 2 \\ 1 & -1 & -2 \\ 1 & 1 & 4 \end{pmatrix}$ is 4. The value of k is?

$$N(A) = n(A) - R(A)$$

$$1 = 3 - R(A)$$

$$R(A) = 2$$

for 3×3 matrix

if $R(A) = 3$ then $|A| \neq 0$

$$|A| = 0 \Rightarrow$$

$$\left| \begin{array}{ccc} k & 1 & 2 \\ 1 & -1 & -2 \\ 1 & 1 & 4 \end{array} \right| = 0$$

$$k = -1$$

$ax + by + cz = 0 \Rightarrow$ Homogeneous

$ax + by + cz = 2 \Rightarrow$ Non-Homogeneous

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Problem: The rank of matrix A is 5 & nullity of matrix is 3 then order of matrix = ?

$$N(A) = n(A) - r(A)$$

$$3 = n(A) - 5$$

$$n(A) = 8$$

* Non-homogeneous system of Linear Equation *

Consider the following non homogeneous system of m linear eq's in n unknowns.

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$

$$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2$$

$$\vdots$$

$$a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m$$

Procedure

- Write the given system of eq's in the form

$$AX = B$$

i.e.,

$$\begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & & & \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{pmatrix}$$

↑ ↑ ↑
coefficient matrix sol'n matrix column matrix
of constants.

- Write the elements of matrix B in the last column of matrix A. The resulting matrix is called Augmented matrix & is denoted by $(A|B)$

$$(A|B) = \left(\begin{array}{cccc|c} a_{11} & a_{12} & \dots & a_{1n} & b_1 \\ a_{21} & a_{22} & \dots & a_{2n} & b_2 \\ \vdots & & & & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} & b_m \end{array} \right)$$

- 3) Reduce the augmented matrix $(A|B)$ into Row Echelon form & hence find rank of A & rank of (AB)
- 4) If $r(A) < r(A|B)$ or $r(A|B) \neq r(A)$, the given system of equations ~~are said to have no solⁿ~~ (Ns) (inconsistent).
- 5) If $r(A|B) = r(A) = \text{no. of unknowns}$, the given system of eqⁿ have unique solution.
- 6) If $r(A|B) = r(A) < \text{no. of unknowns}$, the given system of eqⁿ have infinite no. of solutions.
- 7) If the given system of equations have a solⁿ (unique or infinite solⁿ).
ECE 20
Pno
 The solⁿ can be found by reducing the matrix AB into Row Echelon form & by using back code substitution, the variables x_1, x_2, \dots, x_n can be found.
- Note: If the total no. of eqⁿ < total no. of variables, the given system of eqⁿ have infinite no. of solⁿ Pno

These infinite no. of solⁿs can be found by assigning $(n-r)$ variables as arbitrary constants.
 These $(n-r)$ solⁿs are linearly independent solⁿs.

$$x+y=3$$

$$x=1, y=2$$

$$x < 0, n-r = 2-1 = 1$$

put $\boxed{y=c} \rightarrow L.I \text{ soln}$

$$\begin{array}{l|l} x+y=3 & x=3-c \\ x+c=3 & \\ x=3-c & \end{array} \quad \begin{array}{l} x=c \\ y=c \end{array}$$

Note: Consider the system of eqn.

$$ax+by=e$$

$$cx+dy=f$$

The above system of eqns. have

1) No soln if $\frac{a}{c} = \frac{b}{d} \neq \frac{e}{f}$

2) Unique soln if $\frac{a}{c} \neq \frac{b}{d}$

3) Infinite soln if $\frac{a}{c} = \frac{b}{d} = \frac{e}{f}$

ECE 2010
(1m)

Problem 1: The system of eqns.

$$4x+2y=7$$

$2x+y=6$ have

$$\frac{4}{2} = \frac{2}{1} \neq \frac{7}{6} \quad \left(\frac{a}{c} = \frac{b}{d} \neq \frac{e}{f} \right)$$

\therefore The given system of eqns. have no soln.

Problem 2: $x+2y=5$

$$2x+3y=9$$

$$\frac{1}{2} \neq \frac{2}{3} \neq \frac{5}{9}, \quad \frac{1}{2} \neq \frac{2}{1} \quad \left(\frac{a}{c} \neq \frac{b}{d} \right)$$

\therefore Unique soln

problem 3: $x + y = 3$

$$3x + 3y = 9$$

$$\therefore \frac{1}{3}x + \frac{1}{3}y = \frac{3}{9} \quad \therefore \text{Infinite soln}$$

problem 4: How many solutions does the following system
of eqns have

$$x + 5y = -1$$

$$x - y = 2$$

$$x + 3y = 3$$

- a) Infinite b) exactly 2 c) Unique soln d) No soln

$$(A|B) = \left(\begin{array}{ccc|c} -1 & 5 & -1 \\ 1 & -1 & 2 \\ 1 & 3 & 3 \end{array} \right)$$

$$R_2 \rightarrow R_2 + R_1 \quad R_3 \rightarrow R_3 + R_1$$

$$\therefore \left(\begin{array}{ccc|c} -1 & 5 & -1 \\ 0 & 4 & 1 \\ 0 & 8 & 2 \end{array} \right)$$

$$R_3 \rightarrow R_3 - 2R_2$$

$$\therefore \left(\begin{array}{ccc|c} -1 & 5 & -1 \\ 0 & 4 & 1 \\ 0 & 0 & 0 \end{array} \right)$$

$$g(A|B) = 2 \quad g(A) = 2$$

$g(A|B) = g(A) = \text{No. of unknowns} = 2$
 $\therefore \text{Unique soln}$

(cm)

Problem 5: Consider following non homogeneous system of Linear eqⁿ in 3 variables x_1, x_2, x_3 .

$$2x_1 - x_2 + 3x_3 = 1$$

$$3x_1 + 2x_2 + 5x_3 = 2$$

$$-x_1 + 4x_2 + x_3 = 3$$

The above system of eqⁿ have —

- a) No solⁿ
- b) unique solⁿ
- c) more than 1 but finite no. of solⁿ
- d) Infinite no. of solⁿ

$$(A|B) = \begin{pmatrix} 2 & -1 & 3 & 1 \\ 3 & 2 & 5 & 2 \\ -1 & 4 & 1 & 3 \end{pmatrix}$$

$$R_2 \rightarrow 2R_2 - 3R_1 \quad R_3 \rightarrow 2R_3 + R_1$$

$$(A|B) = \begin{pmatrix} 2 & -1 & 3 & 1 \\ 0 & 7 & 1 & 1 \\ 0 & 7 & 5 & 7 \end{pmatrix}$$

$$R_3 \rightarrow R_3 - R_2$$

$$(A|B) = \begin{pmatrix} 2 & -1 & 3 & 1 \\ 0 & 7 & 1 & 1 \\ 0 & 0 & 4 & 6 \end{pmatrix}$$

$$f(A|B) = 3 \quad f(A) = 3$$

No. of unknowns = 3

∴ Unique solⁿ

2010 Ver2

Problem 6: For the set of eq^{ns} $x_1 + 2x_2 + x_3 + x_4 = 2$

$$3x_1 + 6x_2 + 3x_3 + 3x_4 = 6$$

which of the foll. stmt is true —

1) There exist only trivial solⁿ

2) There are no solⁿ

3) Unique non trivial solⁿ

4) Infinite no. of non Trivial solⁿ

⇒ No. of eqns (r) = 2

No. of variables (n) = 4

here r < n

Infinite soln (Non trivial)

Pno

Problem 7: The value of x_3 obtained by solving the foll system of eqns.

$$x_1 + 2x_2 - 2x_3 = 4$$

$$2x_1 + x_2 + x_3 = -2$$

$$x_1 + x_2 - x_3 = 2$$

$$(A|B) = \left(\begin{array}{ccc|c} 1 & 2 & -2 & 4 \\ 2 & 1 & 1 & -2 \\ -1 & 1 & -1 & 2 \end{array} \right)$$

$$R_2 \rightarrow R_2 - 2R_1 \quad R_3 \rightarrow R_3 + R_1$$

$$(A|B) = \left(\begin{array}{ccc|c} 1 & 2 & -2 & 4 \\ 0 & -3 & 5 & -10 \\ 0 & 3 & -3 & 6 \end{array} \right)$$

$$R_3 \rightarrow R_3 + R_2$$

$$(A|B) = \left(\begin{array}{ccc|c} 1 & 2 & -2 & 4 \\ 0 & -3 & 5 & -10 \\ 0 & 0 & 2 & -4 \end{array} \right)$$

$$2x_3 = -4$$

$$\boxed{x_3 = -2}$$

(To find x_2)

$$-3x_2 + 5x_3 = -10$$

$$-3x_2 - 10 = -10$$

$$-3x_2 = 0$$

$$\boxed{x_2 = 0}$$

~~2011 (cont)~~

Problem 8 : find the values of λ, μ for which the following system of eqns

$$x + 4y + z = 6$$

$$x + 4y + 6z = 20$$

$$x + 4y + \lambda z = \mu \quad \text{have}$$

\Rightarrow No soln

\Rightarrow infinite soln

\Rightarrow Unique soln

$$(A|B) = \left(\begin{array}{ccc|c} 1 & 1 & 1 & 6 \\ 1 & 4 & 6 & 20 \\ 1 & 4 & \lambda & \mu \end{array} \right)$$

$$R_2 \rightarrow R_2 - R_1$$

$$R_3 \rightarrow R_3 - R_1$$

$$(A|B) = \left(\begin{array}{ccc|c} 1 & 1 & 1 & 6 \\ 0 & 3 & 5 & 14 \\ 0 & 3 & \lambda-1 & \mu-6 \end{array} \right)$$

$$R_3 \rightarrow R_3 - R_2$$

$$(A|B) = \left(\begin{array}{ccc|c} 1 & 1 & 1 & 6 \\ 0 & 3 & 5 & 14 \\ 0 & 0 & \lambda-6 & \mu-20 \end{array} \right)$$

$$\rho(A) = 3$$

$$\rho(A|B) = 3$$

\Rightarrow No soln : If $\rho(A) < \rho(A|B)$

If $\lambda = 6, \mu \neq 20$

$$\rho(A) = 2 \quad \rho(A|B) = 3$$

$$\Rightarrow \rho(A) < \rho(A|B) \rightarrow \text{No soln}$$

\Rightarrow Unique soln : If $\rho(A) = \rho(A|B) = \text{No of unknowns}$

For $\lambda \neq 6, \rho(A|B) = \text{any value if } \lambda = 6, \mu \neq 20$

3) Infinite no. of solⁿ :- If $r(A) = r(A|B) < \text{No. of unknowns}$

No. of unknowns = 3 must be 2

$r(A)$ & $r(A|B)$ should be less than 3 bcoz rank can't be 3

It is possible if

$r = 2$ & $n = 2$ \Rightarrow Infinite solⁿ set

Ans

problem 8 : find the values of A & B for which the following system of eqⁿs

$$x + 2y + 3z = 6$$

$$x + 3y + 5z = 9$$

$$2x + 5y + 9z = b \text{ have}$$

- 1) No solⁿ 2) Unique solⁿ 3) Infinite solⁿ

Solve
200

Prob

problem 9 : For what values of α & β , the following system of eqⁿs

$$x + y + z = 5 \quad \text{have infinite no}$$

$$2x + 3y + 3z = 9 \quad \text{of solⁿ ?}$$

$$x + 2y + \alpha z = \beta$$

a) $\alpha = 2, \beta = 7$ c) $\alpha = 3, \beta = 4$

b) $\alpha = 7, \beta = 2$ d) $\alpha = 4, \beta = 3$

$$(A|B) = \begin{pmatrix} 1 & 1 & 1 & 5 \\ 1 & 3 & 3 & 9 \\ 1 & 2 & \alpha & \beta \end{pmatrix}$$

$$R_2 \rightarrow R_2 - R_1, \quad R_3 \rightarrow R_3 - R_1,$$

$$\begin{pmatrix} 1 & 1 & 1 & 5 \\ 0 & 2 & 2 & 4 \\ 0 & 1 & \alpha-1 & \beta-5 \end{pmatrix}$$

$$R_3 \rightarrow 2R_3 - R_2$$

Non-homogeneous System \Rightarrow draw my mix
classmate

$$\text{Augmented Matrix: } \left(\begin{array}{ccc|c} 1 & 1 & 1 & 5 \\ 0 & -2 & 2 & 4 \\ 0 & 0 & 2\alpha-4 & 2\beta-14 \end{array} \right)$$

$$g(A) = g(A|B) < \text{No. of unknowns}$$

$$g(A) = g(A|B) < 3$$

$$2\alpha - 4 = 0$$

$$2\beta - 14 = 0$$

$$2\alpha = 4$$

$$2\beta = 14$$

$$\boxed{\alpha = 2}$$

$$\boxed{\beta = 7}$$

Problem II: If A is 3×4 matrix & the non homogeneous system of equations $Ax=B$ is inconsistent (No sol).
The highest possible rank of A is.



$$(A|B)$$

3×5

(A|B)

$$g\{(A|B)\}_{3 \times 5} \leq \min(3, 5)$$

$$g\{(A|B)\} \leq 3$$

= 3 Highest Possible Rank

But it is given that the given system of eqⁿ are inconsistent (No solⁿ)

for inconsistent $\rightarrow g(A) < g(A|B)$

$$g(A) < 3$$

$$g(A) \begin{cases} 2 \\ 1 \\ 0 \end{cases}$$

Highest possible rank of A = 2

* Homogeneous system of Linear Eqⁿ *

Consider the following homogeneous system of linear eqⁿs i.e. m equations of n unknowns.

$$\left. \begin{array}{l} a_{1,1}x_1 + a_{1,2}x_2 + a_{1,3}x_3 + \dots + a_{1,n}x_n = 0 \\ a_{2,1}x_1 + a_{2,2}x_2 + a_{2,3}x_3 + \dots + a_{2,n}x_n = 0 \\ \vdots \\ a_{m,1}x_1 + a_{m,2}x_2 + a_{m,3}x_3 + \dots + a_{m,n}x_n = 0 \end{array} \right\} \quad (I)$$

Procedure to solve problems :-

- 1) Write the given system of eqⁿs in the form $AX=0$

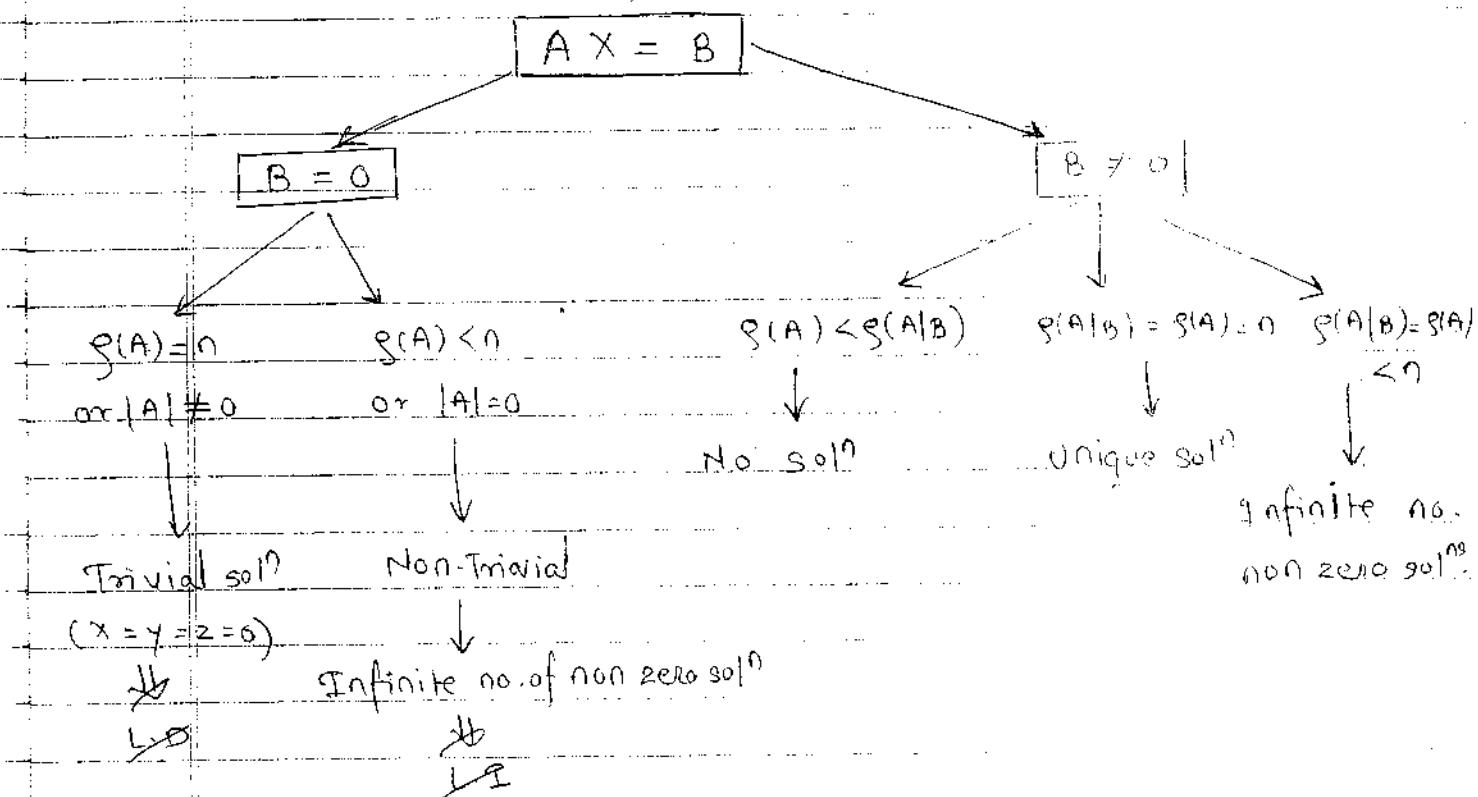
$$\begin{pmatrix} a_{1,1} & a_{1,2} & a_{1,3} & \dots & a_{1,n} \\ a_{2,1} & a_{2,2} & a_{2,3} & \dots & a_{2,n} \\ \vdots \\ a_{m,1} & a_{m,2} & a_{m,3} & \dots & a_{m,n} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

- 2) Reduce the matrix A into either row or column echelon form (but always row echelon form is preferable) OR find the determinant of matrix |A|.

- 3) If $\delta(A) = \text{No. of unknowns (variables)}$ OR
 $|A| \neq 0$ ($A \rightarrow \text{Non singular matrix}$),
the given system of eqⁿ have trivial soln
 $(x=y=z=0)$

- 4) If $\delta(A) < \text{No. of unknowns}$ OR
 $|A|=0$, the given system of eqⁿ have
infinite no. of soln.

All these infinite no. of solⁿ can be found by assigning $(n-r)$ variables as arbitrary constant. These $(n-r)$ solⁿs are called L.I. solⁿs.



problem 1: for what values of λ the system of eqⁿs

$$x + y + z = 0$$

$$(\lambda+1)x + y + (\lambda+1)z = 0$$

$$(\lambda^2 - 1)z = 0$$

have a L.I. solⁿ?



$$\text{No. of L.I. solⁿ} = n - r = 2$$

$$= 3 - r = 2$$

$$\therefore r = 1 \rightarrow \text{Rank of matrix}$$

$$\begin{pmatrix} 1 & 1 & 1 \\ \lambda+1 & 1 & \lambda+1 \\ \lambda^2 - 1 & 0 & 0 \end{pmatrix}$$

$$(A) = \begin{vmatrix} 1 & 1 & 1 \\ -1 & 0 & 1+1 \\ 0 & 1 & 1^2-1 \end{vmatrix} = 0 \Rightarrow \text{Upper } \Delta^{123}$$

$$\Rightarrow (\lambda+1)(\lambda^2-1) = 0$$

$$(\lambda+1)(\lambda+1)(\lambda-1) = 0$$

$$\lambda = -1, 1, -1$$

but in matrix in order to get

$$\det(A) = 1$$

Prob

problem 2 :- The rank of 3×3 matrix A is 1. The homogeneous system of eqns $AX=0$ has

- a) trivial solⁿ b) 1 L.I. solⁿ
- c) 2 L.I. solⁿs d) 3 L.I. solⁿs

(A)_{3x3} \Rightarrow 3 eqns & 3 variables

$$n = 3 \quad r = 1 \Rightarrow r < n$$

$$\therefore \text{L.I. sol}^n = n = r \\ = 3 - 1 \\ = 2$$

\Downarrow
Infinite solⁿ

2011 (sem)

problem 3 :- The system of eqns: $2x_1 + x_2 + x_3 = 0$

$$x_2 - x_3 = 0$$

$$x_1 + x_2 = 0 \text{ have}$$

- a) No non trivial solⁿ c) 5 Non trivial solⁿs
- b) Unique non trivial solⁿ d) Infinite non trivial solⁿs

$$\begin{vmatrix} 2 & 1 & 1 \\ 0 & 1 & -1 \\ 1 & 1 & 0 \end{vmatrix} = 2[1] - 1[0+1] + 1[0-1] \\ = 2 - 1 - 1 = 0$$

Infinite solⁿ.

Prob.

Problem 4: The system of eqⁿ

$$\begin{aligned} x + 3y - 2z &= 0 \\ 2x - y + 4z &= 0 \\ x - 11y + 14z &= 0 \end{aligned}$$

$$\left| \begin{array}{ccc|c} 1 & 3 & -2 & +[-14+44] = 2[28-4] + [-22+1] \\ 2 & -1 & 4 & = 80 - 72 + 42 \\ 1 & -11 & 14 & 1[-14+44] - 3[28-4] + 2[-22+1] \\ \hline 0 & 0 & 0 & = 80 - 72 + 42 = 0 \end{array} \right.$$

yet

problem 5: Find the values of k for which the following system of eqⁿ have infinite no. of non trivial solⁿ.

$$(3k-8)x + 3y + 3z = 0$$

$$|A| = 0$$

$$3x + (3k-8)y + 3z = 0$$

$$3x + 3y + (3k-8)z = 0$$

→ If $|A| = 0$, the given system of eqⁿ have infinite no. of non zero solⁿ.

$$\left| \begin{array}{ccc|c} 3k-8 & 3y & 3z & 0 \\ 3 & 3k-8 & 3z & = 0 \\ 3 & 3 & 3k-8 & 0 \end{array} \right.$$

$$\Rightarrow (3k-8+3y+3z)(3k-8-3z)(3k-8-3z) = 0$$

$$(3k-8)(3k-11)(3k-11) = 0$$

$$3k = 8 \quad 3k = 11$$

$$\therefore k = \frac{8}{3}, \frac{11}{3}$$

Problem 6: Find the real value of λ for which the foll system of eqns. have non-trivial solns

\Rightarrow infinite no. of non-trivial soln

$$x + 2y + 3z = \lambda x$$

$$3x + y + 2z = \lambda y$$

$$2x + 3y + z = \lambda z$$

$$\lambda = 6$$

* Eigen values & Eigen Vectors *

$$A = \begin{pmatrix} 4 & 2 \\ 2 & 4 \end{pmatrix}$$

$$A - \lambda I = \begin{pmatrix} 4 & 2 \\ 2 & 4 \end{pmatrix} - \lambda \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 4 & 2 \\ 2 & 4 \end{pmatrix} - \begin{pmatrix} \lambda & 0 \\ 0 & \lambda \end{pmatrix}$$

$$A - \lambda I = \begin{pmatrix} 4-\lambda & 2 \\ 2 & 4-\lambda \end{pmatrix}$$

characteristic matrix

ch. det

$$|A - \lambda I| = \begin{vmatrix} 4-\lambda & 2 \\ 2 & 4-\lambda \end{vmatrix} = (4-\lambda)^2 - 4$$

$$= \lambda^2 - 8\lambda + 16 - 4$$

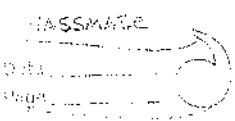
ch. poly. $|A - \lambda I| = 0 \Rightarrow \lambda^2 - 8\lambda + 12 = 0$

$$\therefore \lambda = 6, 2$$

ch. roots or

Eigen values

Method for finding Eigen values



* Eigen values: Let A be an $n \times n$ matrix. λ is a scalar (some constant). The matrix $A - \lambda I$ is called as characteristic matrix.

$|A - \lambda I|$ is called characteristic determinant or characteristic polynomial.

The roots of this ch. det. are called char roots or Eigen values or latent roots or proper values.

The set of eigen values of matrix A is called as spectrum of A .

* Eigen Vector: If λ is an eigen value of a matrix A then there exist a non zero vector x such that $AX = \lambda x$, then the non zero vector x is called as Eigen vector.

Note:

$$AX = \lambda X$$

$$AX = \lambda XI$$

$$AX - \lambda XI = 0$$

$$AX - \lambda IX = 0$$

$$(A - \lambda I)X = 0$$

Trivial sol $\Rightarrow |A - \lambda I| \neq 0$

Infinite sol $\Rightarrow |A - \lambda I| = 0$

Non trivial sol \Rightarrow



Eigen Vectors

Note: Consider the matrix

$$A = \begin{pmatrix} 4 & 2 \\ 2 & 4 \end{pmatrix}$$

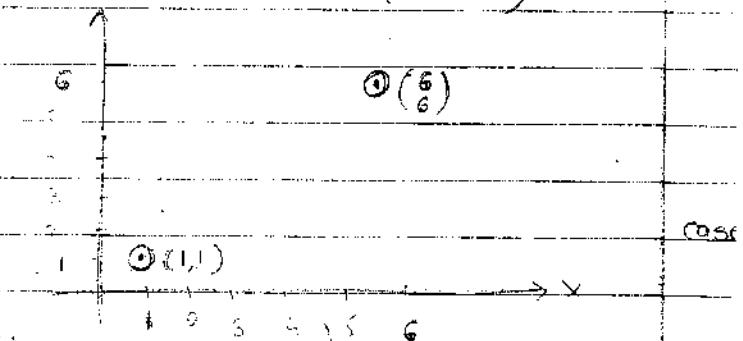
$$\begin{pmatrix} 4 & 2 \\ 2 & 4 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 4+2 \\ 2+4 \end{pmatrix} = \begin{pmatrix} 6 \\ 6 \end{pmatrix} = 6 \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$\downarrow \quad \downarrow \quad \uparrow \quad \uparrow$
 $A \quad X \quad \lambda \quad X$

(non zero vector)

$X = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ is eigen vector corresponding to eigen value $\lambda = 6$ for matrix $A = \begin{pmatrix} 4 & 2 \\ 2 & 4 \end{pmatrix}$

→ Any pt./vector exist along the same vector will also be an eigen vector corresponding to the same eigen value
Ex. $(2,2) (3,3) \dots (7,7) (8,8) \dots$



Ex. $A = \begin{pmatrix} 4 & 2 \\ 2 & 4 \end{pmatrix}$

$$\begin{pmatrix} 4 & 2 \\ 2 & 4 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} 4+4 \\ 2+8 \end{pmatrix} = \begin{pmatrix} 8 \\ 10 \end{pmatrix} = 2 \begin{pmatrix} 4 \\ 5 \end{pmatrix}$$

$\downarrow \quad \downarrow$
 $A \quad X$

Not same

$x = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$ is not eigen vector corresponding to eigen value 2

Problem: find the eigen values & eigen vector of

$$A = \begin{pmatrix} 3 & 4 \\ 4 & -3 \end{pmatrix}$$

Symmetric matrix

$$|A - \lambda I| = 0$$

$$\begin{vmatrix} 3-\lambda & 4 \\ 4 & -3-\lambda \end{vmatrix} = (3-\lambda)(-3-\lambda) - 16 = -9 - 3\lambda + 3\lambda + \lambda^2 - 16 = 0$$

$$\lambda^2 - 25 = 0$$

$$\lambda^2 = 25$$

$$\lambda = \pm 5$$

$$\therefore \text{Eigen values} = 5, -5$$

case i) $(A - \lambda I) X = 0$

$$\begin{pmatrix} 3-\lambda & 4 \\ 4 & -3-\lambda \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

put $\lambda = 5$ Eigen vectors

$$\begin{pmatrix} -2 & 4 \\ 4 & -8 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$-2x_1 + 4x_2 = 0 \quad \text{--- (1)}$$

$$4x_1 - 8x_2 = 0 \quad \text{--- (2)}$$

eqn (1) \Rightarrow divide b.s. by (-2)

$$x_1 - 2x_2 = 0$$

$$\frac{x_1}{x_2} = \frac{2}{1}$$

$$x_1 = 2x_2$$

$$\therefore x_1 = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

Case ii) when $\lambda = -5$

$$(A - \lambda E)x = 0$$

$$\begin{pmatrix} 8 & 4 \\ 4 & -3-\lambda \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

put $\lambda = -5$

$$\begin{pmatrix} 8 & 4 \\ 4 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$8x_1 + 4x_2 = 0 \quad \text{--- (1)}$$

$$4x_1 + 2x_2 = 0 \quad \text{--- (2)}$$

2 vectors are

not den.

only 1 vector is
den

$$2x_1 + x_2 = 0$$

$$2x_1 = -x_2$$

$$\frac{x_1}{x_2} = \frac{-1}{2}$$

$$x_2 = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} -1 \\ 2 \end{pmatrix}$$

$$x_1 = \begin{pmatrix} 2 \\ 1 \end{pmatrix} \quad x_2 = \begin{pmatrix} -1 \\ 2 \end{pmatrix}$$

$x_1^T \cdot x_2 = 0$ or $x_1 \cdot x_2^T = 0 \Rightarrow x_1 \& x_2$ are
orthogonal

$$x_1^T \cdot x_2 = \begin{pmatrix} 2 & 1 \end{pmatrix} \begin{pmatrix} -1 \\ 2 \end{pmatrix} = 2 \cdot -1 + 1 \cdot 2 = 0$$

$$(x_1^T \cdot x_2)_{1x_1} = -2 + 2 = 0$$

$\therefore x_1 \& x_2 \Rightarrow$ orthogonal vectors

E.N of Upper A, lower A, diag... diff
if diagonal elem. only

classmate

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Page _____

Note 1: The Eigen vectors corresponding to diff. eigen value of a real symmetric matrix are always orthogonal.

Note 2: If the Eigen vectors corresponding to diff. eigen values of any square matrix are always linearly independent.

$$x_1 = \begin{pmatrix} 2 \\ 1 \end{pmatrix} \quad x_2 = \begin{pmatrix} -1 \\ 2 \end{pmatrix}$$

$$x_1 \neq k x_2 \quad \text{or} \quad x_2 \neq k x_1$$

$$\therefore x_1 \neq L.I. \quad x_2 \quad (\text{accn to criteria (4)})$$

In the above ex. the eigen values of matrix are 5, -5 the corresponding eigen vectors are $\begin{pmatrix} 2 \\ 1 \end{pmatrix}$ & $\begin{pmatrix} -1 \\ 2 \end{pmatrix}$

* Consider the matrix $A = \begin{pmatrix} 2 & 3 \\ 0 & 2 \end{pmatrix}$

$$\lambda = 2, 2 \rightarrow \text{Repeated twice}$$

when $\lambda = 2$ Max. no. of L.I. v.e.s

$$(A - \lambda I)x = 0$$

$$\begin{pmatrix} 2-\lambda & 3 \\ 0 & 2-\lambda \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\text{put } \lambda = 2$$

$$\begin{pmatrix} 0 & 3 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$0x_1 + 3x_2 = 0$$

$$3x_2 = 0 \quad \therefore x_2 = 0$$

$$x_1 \neq 0$$

put $x_1 = c$

$$x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} c \\ 0 \end{pmatrix} \text{ where } c \neq 0.$$

Acc' to criteria (5)

every non zero vector is L.I. vector

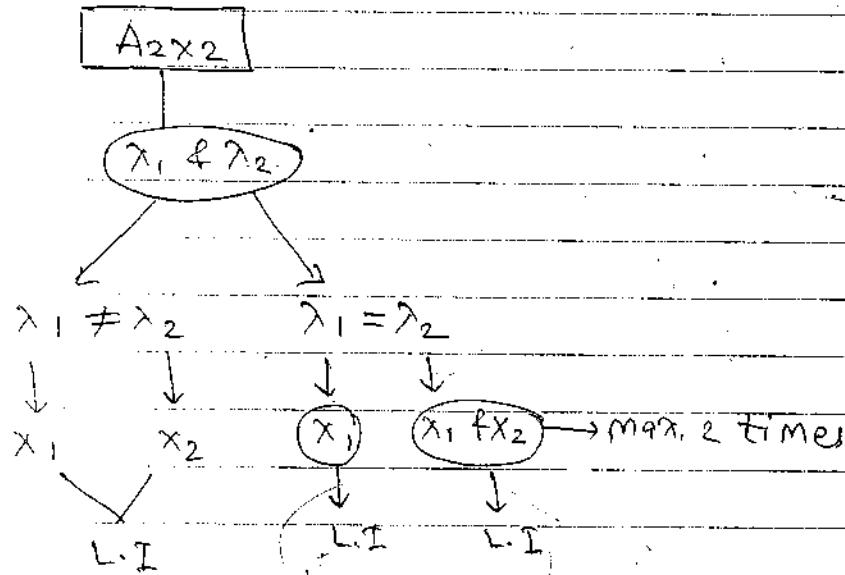
Note:- If some of the eigen value of a matrix are repeated then the eigen vectors corresponding to repeated eigen values may be L.I. or L.D.

If an eigen value λ is repeated n times the eigen vectors corresponding to repeated eigen values are always L.I. which are given by

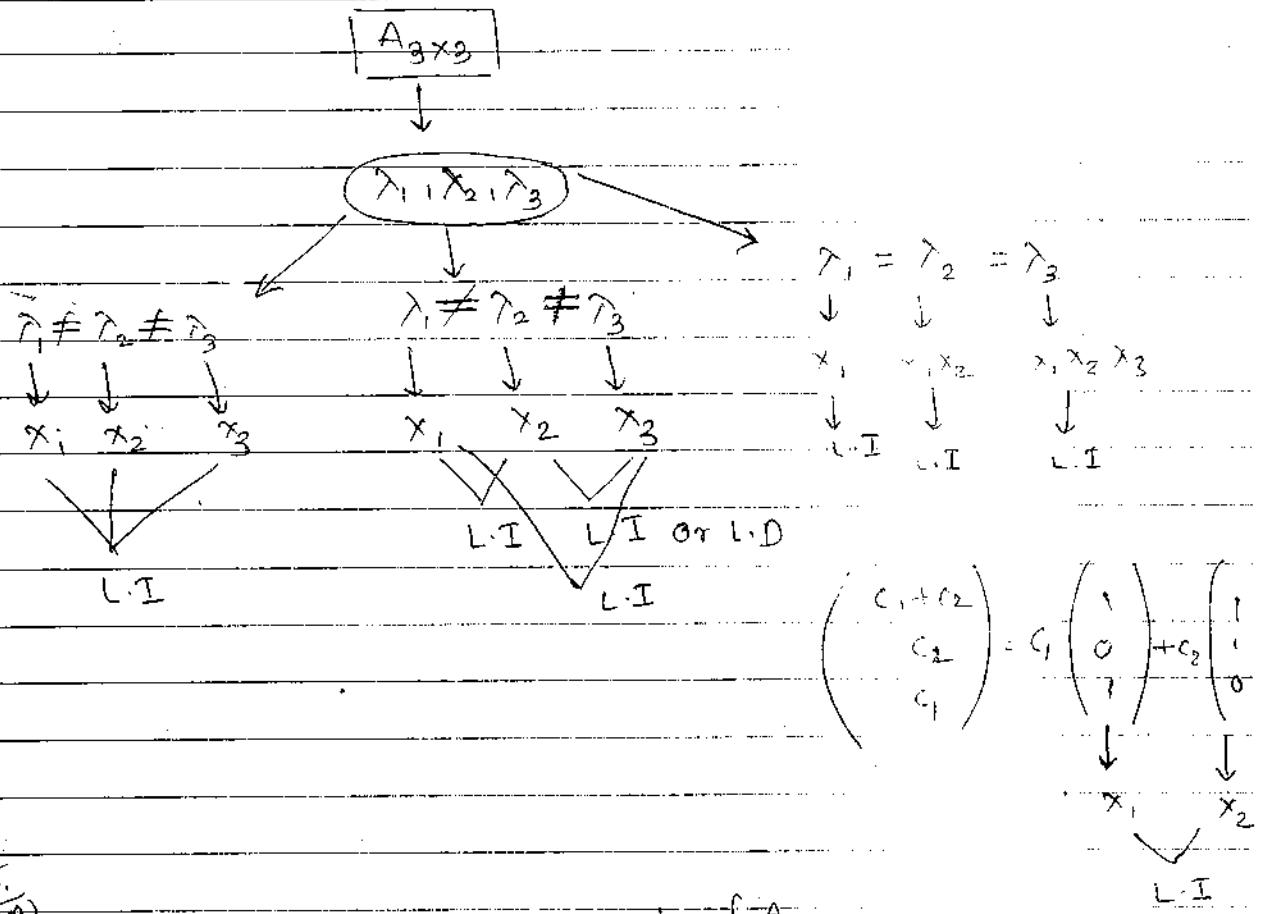
$$p = n - r \quad ; \quad 1 \leq p \leq m \quad \{ \text{max. } m \text{ times} \}$$

↓
no. of unknowns

or variables



9.



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instn.
(m))~~

Note:

$$A \cdot X = \lambda \otimes X$$

Eigen vector of A

Eigen value of A

$$A^{-1} \cdot A \cdot X = A^{-1} \cdot \lambda \cdot X$$

$$I \cdot X = A^{-1} \cdot \lambda \cdot X$$

$$X = \lambda \cdot A^{-1} \cdot X$$

$$\frac{X}{\lambda} = A^{-1} \cdot X$$

$$A^{-1} \cdot X = \frac{1}{\lambda} \otimes X$$

Eigen vector of A^{-1}

$$X = \lambda \otimes \frac{1}{\lambda} \otimes X$$

Eigen value of A^{-1}

If λ is eigen value of A & X is eigen vector of A but $\frac{1}{\lambda}$ is eigen value of A^{-1} and

X is eigen vector of A^T . Therefore, A & A^T have same eigen vectors.

A & A^T have same eigen vectors ($m \geq n$) corresponding to eigen values.

$$AX = \lambda X$$

$$A A X = A \lambda X$$

$$A^2 X = \lambda A X$$

$$A^2 X = \lambda^2 X$$

* Properties of Eigen Values & Eigen Vectors:-

1) Sum of eigen values is equal to trace of matrix.

i.e., if $\lambda_1, \lambda_2, \dots, \lambda_n$ are eigen values of a matrix A then

$$\text{① Trace } A = \lambda_1 + \lambda_2 + \dots + \lambda_n$$

$$2) |A| = \lambda_1 \cdot \lambda_2 \cdot \lambda_3 \cdot \dots \cdot \lambda_n$$

Ex. Consider the matrix

$$A = \begin{pmatrix} 5 & 4 \\ 1 & 2 \end{pmatrix}$$

$$5 \rightarrow 1$$

$$4 \rightarrow 2$$

$$(5-2)(2-2)-4$$

$$10 - 5 \cdot 2 + 2^2 - 4 = \lambda^2 - 7\lambda + 6$$

$$\lambda = 1, 6$$

$$\therefore 1+6 = 5+2 \therefore \text{Trace of } A = 7$$

$$\text{iii) } 1 \times 6 = 10 - 4 = 6 \therefore |A| = 6$$

3) The eigen values of upper triangular or lower triangular or diagonal or scalar or identity matrix is its diagonal elements.

1) $A = \begin{pmatrix} -1 & 2 & 3 \\ 0 & -4 & 2 \\ 0 & 0 & 7 \end{pmatrix}; \lambda = 1, -4, 7$

Upper Δ^{tar}

2) $A = \begin{pmatrix} 3 & 0 & 0 \\ 4 & 5 & 0 \\ 0 & 8 & 9 \end{pmatrix}; \lambda = 3, 5, 9$

Lower
 Δ^{tar}

3) $A = \begin{pmatrix} 3 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 5 \end{pmatrix}; \lambda = 3, 4, 5$

Diagonal matrix

4) $A = \begin{pmatrix} 3 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{pmatrix}; \lambda = 3, 3, 3$

scalar matrix

5) $A = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}; \lambda = 0, 0, 0$

scalar / Null
matrix

6) $A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}; \lambda = 1, 1, 1$

Identity matrix

- a) The eigen values of A & A^T are same

5) The eigen values of A & $P^{-1}AP$ are same where P is a non singular matrix.

6) The eigen values of real symmetric matrix are real.

7) The eigen values of skew symmetric matrix are purely imaginary OR zeros.

8) The eigen values of orthogonal matrix are of unit modulus i.e., ± 1 .

9) If λ is an eigen value of an orthogonal matrix then $\frac{1}{\lambda}$ is also one of its eigen value.

10) If λ is an eigen value of matrix A then

i) $k\lambda$ is an eigen value of kA .

ii) $\frac{1}{\lambda}$ is also an eigen value of A^{-1} .

iii) λ^2 is an eigen value of A^2 .

iv) λ^m is an eigen value of A^m .

v) $\frac{|A|}{\lambda}$ is an eigen value of $\text{adj. } A$

vi) $\lambda \pm k$ is an eigen value of $A \pm kI$

vii) $(\lambda \pm k)^2$ is an eigen value of $(A \pm kI)^2$

viii) $\frac{1}{\lambda \pm k}$ is an eigen value of $(A \pm kI)^{-1}$

Note: If A is a singular matrix i.e., $|A|=0$ then one of its eigen value should be zero

$$\lambda_1 \cdot \lambda_2 \cdot \lambda_3 = |A|$$

↓

$$0 \cdot \lambda_2 \cdot \lambda_3 = |A|$$

$$|A|=0$$

$|A|=0$ \therefore singular

Ques.

Problem 1: $A = \begin{pmatrix} -1 & 3 & 5 \\ -3 & -1 & 6 \\ 0 & 0 & 3 \end{pmatrix}$ are

$$j = \sqrt{-1}$$

A) $3, 3+5j, 6-j$

B) $-6+5j, 3-j, 3+j$

C) $3-j, 3+j, 5+j$

D) $3, -1+3j, -1-3j$

by Prop. 1 :

$$\text{Trace } A = \lambda_1 + \lambda_2 + \lambda_3$$

[cross check]

$$-1 - 1 + 3 = 3 - 1 + 3j - 1 - 3j$$

$$1 = 1$$

If 1 or more opt. satisfy then

Problem 2: The eigen values

& eigen vector of a 2×2 matrix are given by

Eigen value :

Eigen vector

$$\lambda_1 = 8$$

$$v_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\lambda_2 = 4$$

$$v_2 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

the matrix is —

a) $\begin{pmatrix} 6 & 2 \\ 2 & 6 \end{pmatrix}$ b) $\begin{pmatrix} 4 & 6 \\ 6 & 4 \end{pmatrix}$ c) $\begin{pmatrix} 2 & 6 \\ 4 & 4 \end{pmatrix} \therefore \begin{pmatrix} 4 & 6 \\ 8 & 4 \end{pmatrix}$

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problem 3: The vector $\begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix}$ is an eigen vector of the matrix

$$A = \begin{pmatrix} -2 & 2 & -3 \\ 2 & 1 & -6 \\ -1 & -2 & 0 \end{pmatrix} \quad \text{The eigen value corresponding to the eigen vector is -}$$

$$(A - \lambda I) X = 0$$

$$\begin{pmatrix} -2-\lambda & 2 & -3 \\ 2 & 1-\lambda & -6 \\ -1 & -2 & 0-\lambda \end{pmatrix} \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

value consider any 1 row & multiply it.

$$-1 - 4 + \lambda = 0$$

$$\lambda = 5$$

problem 4: For the matrix $\begin{pmatrix} -6 & 2 \\ 2 & 4 \end{pmatrix}$ the eigen value

corresponding to the eigen vector $\begin{pmatrix} 1 & 0 & 1 \\ 1 & 0 & 1 \end{pmatrix}$ is

$$(A - \lambda I) X = 0$$

$$\begin{pmatrix} -6-\lambda & 2 \\ 2 & 4-\lambda \end{pmatrix} \begin{pmatrix} 1 & 0 & 1 \\ 1 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$2 + 4 - \lambda = 0$$

$$\lambda = 6$$

Problem 5: The min & max eigen values of a matrix $\begin{pmatrix} 1 & 1 & 3 \\ 1 & 3 & 1 \\ 3 & 1 & 1 \end{pmatrix}$ are -2 & 6 resp what would be the 3rd eigen value

$$\text{Trace } A = \lambda_1 + \lambda_2 + \lambda_3$$

$$= 1+5+1 = -2+6-\lambda_3$$

$$\boxed{\lambda_3 = 3}$$

Problem 6: The matrix $\begin{pmatrix} 1 & 2 & 4 \\ 3 & 0 & 6 \\ 1 & 1 & p \end{pmatrix}$ has an eigen value = 3. Sum of other two eigen values is ---

$$1+0+p = 3 + \lambda_2 + \lambda_3$$

$$p+1-3 = \lambda_2 + \lambda_3$$

$$\boxed{\lambda_2 + \lambda_3 = p-2}$$

~~soln~~
Problem 7: Consider the following matrix

$A = \begin{pmatrix} 2 & 3 \\ x & 4 \end{pmatrix}$. The eigen values of A are = 4 & 8. The values of x, y are

$$\text{prop 1} \rightarrow 2+4 = 4+8$$

$$y = 12-2 = 10$$

$$\text{prop 2} \rightarrow 2 \times 40 = 20 \quad 4 \times 8 = 32$$

$$\begin{vmatrix} 2 & 3 \\ x & 10 \end{vmatrix} = 32 \quad x = -4$$

$$20 - 3x = 32$$

$$20 - 3x = 32 \quad x = \frac{-10}{3}$$

$$2x = -12 \quad x = -4$$

$$2y - 3x = 4 \times 8 \Rightarrow 2 \times 10 - 3x = 32$$

$$-3x = 32 - 20$$

$$-3x = 12$$

$$\boxed{x = -4}$$

P.3

Ques 8: If the eigen values of 3×3 matrix are given by 1, -3, 9. Find

i) Trace ($A^2 + A^T - \text{adj. } A$)

ii) det. ($A^2 + A^T - \text{adj. } A$)

$$\Rightarrow |A| = 1 \times -3 \times 9 = -27$$

$$A^2 + A^T - \text{adj. } A$$

$$\rightarrow \lambda^2 + \frac{1}{\lambda} = \frac{|A|}{\lambda} \quad \text{by prop. (10)}$$

$$\lambda^2 + \frac{1}{\lambda} - \frac{|A|}{\lambda} = \frac{\lambda^2 + 1}{\lambda} - \frac{(-27)}{\lambda} = \frac{29}{\lambda}$$

$$\lambda^2 + \frac{1}{\lambda} - \frac{|A|}{\lambda} = \frac{(-3)^2 + 1}{(-3)} - \frac{(-27)}{(-3)} = \frac{10}{(-3)} = \frac{(-27)}{(-3)} = \frac{27}{3} = 9$$

$$9 - \frac{1}{3} - \lambda = -\frac{1}{3}$$

$$9^2 + \frac{1}{9} - \frac{(-27)^2}{9} = \frac{81 + 1 + 729}{9} = \frac{81 + 1 + 27}{9} = \frac{757}{9}$$

$$81 + \frac{1}{9} + 3$$

$$\frac{729 + 1 + 27}{9} = \frac{757}{9}$$

∴ Trace ($A^2 + A^T - \text{adj. } A$) = $29 - \frac{1}{3} + \frac{757}{9}$

$$\text{ii) } \det(A^2 + A^{-1} - \text{adj } A) = 29 \times \left(\frac{-1}{3}\right) \times \frac{757}{9}$$

Prob. 9:- Given $A = \begin{pmatrix} 1 & 2 & -3 \\ 0 & 3 & 2 \\ 0 & 0 & -2 \end{pmatrix}$, the eigen values of $3A^3 + 5A^2 - 6A + 2I$ are

$\lambda = 1, 3, -2$

$$3A^3 + 5A^2 - 6A + 2I \Rightarrow 3\lambda^3 + 5\lambda^2 - 6\lambda + 2$$

$$\text{put } \lambda = 1$$

$$3(1)^3 + 5(1)^2 - 6(1) + 2$$

$$3 + 5 - 6 + 2 = 4$$

$$\text{put } \lambda = 3$$

$$3 \times 27 + 5 \times 9 - 18 + 2$$

$$81 + 45 - 16 = 126 - 16 = 110$$

$$\text{put } \lambda = -2$$

$$-(3 \times 8) + 20 + 12 + 2$$

$$-24 + 24 = 0$$

$$3 \times (-8) + 5 \times 4 + 12 + 2$$

$$-24 + 20 + 12 + 2 = 10$$

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(cm)

Prob. No. 10:- The eigen values of 2×2 matrix A are given by -2 & -3 resp. The eigen values of $(x+I)^{-1} \cdot (x+5I)$

(This is not possible)

$$\frac{57}{9} \Rightarrow (x+I)^{-1} \cdot (x+5I) = (x+I)^{-1} \{ (x+I) + 4I \}$$

$$= (x+I)^{-1} \cdot (x+I) + 4I \cdot (x+I)^{-1}$$

$$= I + 4(x+I)^{-1}$$

$$4(x+I)^{-1} + I \Rightarrow \frac{4}{1+4} + 1$$

$$\Rightarrow \frac{4}{1+1} + 1$$

$$\text{put } \lambda = -2 \quad \frac{4}{1-2} + 1 = -3$$

$$\text{put } \lambda = -1 \quad \frac{4}{1-3} + 1 = -1$$

20
Ans

Prob 14 :- The eigen vector of a 3×3 matrix are

$\begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}$ are orthogonal that will be the 3rd orthogonal eigen vector.

$$x_1 = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}, x_2 = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}, \text{ let } x_3 = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

here, 3 vectors are orthogonal

$$\therefore x_1^T \cdot x_3 = 0 \quad x_2^T \cdot x_3 = 0$$

$$(1 \ 0 \ 1) \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \quad (1 \ 0 \ -1) \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$x + z = 0 \quad \text{(i)} \quad x - z = 0 \quad \text{(ii)}$$

add (i) & (ii)

$$2x = 0$$

$$\therefore x = 0 \quad \text{put in (i)}$$

$$0 + z = 0$$

$$z = 0$$

$y \neq 0$ \because zero vector can't be eigen vector

$\Rightarrow \therefore y = c$ c - arbitrary constant & $c \neq 0$

\therefore The 3rd eigen vector is $\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ c \end{pmatrix}$

$$x = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

~~2068 (2m)~~
Prob. 12 :- The eigen vector of 2×2 matrix $\begin{pmatrix} 1 & 2 \\ 0 & 2 \end{pmatrix}$ are given by $\begin{pmatrix} 1 \\ a \end{pmatrix}, \begin{pmatrix} 1 \\ b \end{pmatrix}$, what is $(a+b)$?

$$\lambda = 1, 2$$

$$AX = \lambda X \quad \text{OR} \quad (A - \lambda I)X = 0$$

put $\lambda_1 = 1$

$$\begin{pmatrix} 1 & 2 \\ 0 & 2 \end{pmatrix} \begin{pmatrix} 1 \\ a \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix} \begin{pmatrix} 1 \\ a \end{pmatrix}$$

$$1 + 2a = 1$$

$$1 + 2a = 1 \quad [a = 0]$$

put $\lambda = 2$

$$\begin{pmatrix} 1 & 2 \\ 0 & 2 \end{pmatrix} \begin{pmatrix} 1 \\ b \end{pmatrix} = 2 \begin{pmatrix} 1 \\ b \end{pmatrix} = \begin{pmatrix} 2 \\ 2b \end{pmatrix}$$

$$1 + 2b = 2$$

$$2b = 1$$

$$b = 1/2$$

or

$c \neq 0$

Method I :-

Case 1 : when $\lambda = 1$

$$(A - \lambda I) X = 0$$

$$\begin{pmatrix} 1-1 & 2 \\ 0 & 2-1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 2 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$2x_2 = 0 \Rightarrow x_2 = 0$$

here $x_1 \neq 0$
 $\therefore x_1 = c$ $c \rightarrow \text{non zero arbitrary const}$

$$X = \begin{pmatrix} c \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

generally c is replaced by 1

Case 2 : when $\lambda = -2$

$$\begin{pmatrix} 1+2 & 2 \\ 0 & 2+2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} -1 & 2 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$-x_1 + 2x_2 = 0$$

$$2x_2 = x_1$$

$$\frac{x_1}{1} = \frac{x_2}{2}$$

$$x_2 = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$x_1 = 2 \quad x_2 = 1$$

$$\begin{matrix} x_1 & 1 \\ \hline x_2 & (1/2) \end{matrix}$$

$$x_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ a \end{pmatrix} \Rightarrow a = 0$$

$$x_2 = \begin{pmatrix} 1 \\ 1/2 \end{pmatrix} = \begin{pmatrix} 1 \\ b \end{pmatrix} \Rightarrow b = 1/2$$

Prob. 13: find eigen values & eigen vectors of foll.

a) $A = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 2 & 2 \\ 0 & 0 & 3 \end{pmatrix}$

$\rightarrow \lambda = 1, 2, 3$

zero

for distinct eigenvalues

\rightarrow put $\lambda = 1$

\rightarrow consider row 2

$$\begin{array}{ccc|c} x_1 & x_2 & x_3 & 1 \\ 1 & 0 & 0 & 1 \\ 1 & 2 & 0 & 1 \end{array}$$

\rightarrow make 2nd row 0

\rightarrow get 2nd row, 1st row

$$\frac{x_1}{2} = \frac{x_2}{0} = \frac{x_3}{0}$$

\rightarrow 1, 0, 0

$$x_1 = \begin{pmatrix} 2 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

other form of 1st eigen vector

\rightarrow put $\lambda = 2$

$$\begin{array}{ccc|c} x_1 & x_2 & x_3 & 2 \\ 1 & 0 & -1 & 0 \\ 0 & 2 & 0 & 0 \end{array}$$

\rightarrow put $\lambda = 3$

$$\begin{array}{ccc|c} x_1 & x_2 & x_3 & 3 \\ 1 & 0 & -2 & 1 \\ -1 & 2 & 0 & -1 \end{array}$$

$$\frac{x_1}{2} = \frac{x_2}{2} = \frac{x_3}{0}$$

$$\frac{x_1}{2} = \frac{x_2}{4} = \frac{x_3}{2}$$

$$x_2 = \begin{pmatrix} 2 \\ 2 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$$

$$x_3 = \begin{pmatrix} 2 \\ 4 \\ 2 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$$

b)

$$\left(\begin{array}{ccc} 1 & 2 & 3 \\ 0 & -4 & 2 \\ 0 & 0 & 7 \end{array} \right) \quad \text{Ans}$$

$$1 \quad -4 \quad 3$$

put $x_1 = 1$

$$\begin{array}{r} x_2 \\ 2 \\ -8 \end{array} \quad \begin{array}{r} x_3 \\ 0 \\ 2 \end{array}$$

$$-8 \quad 2 \quad 0 \quad -5$$

$$\begin{array}{r} x_2 \\ -8 \\ 0 \end{array} \quad \begin{array}{r} x_3 \\ 2 \\ 0 \end{array} \quad x_1 = \begin{pmatrix} 19 \\ 0 \\ 0 \end{pmatrix}$$

put $x_2 = 4$

$$\begin{array}{r} x_2 \\ 2 \\ -8 \end{array} \quad \begin{array}{r} x_3 \\ 3 \\ 2 \end{array}$$

$$\frac{x_1}{28} = \frac{x_2}{-10} = \frac{x_3}{-40} \quad x_2 = \begin{pmatrix} 28 \\ -10 \\ -40 \end{pmatrix}$$

put $x_2 = 7$

$$\begin{array}{r} x_2 \\ 2 \\ -11 \end{array} \quad \begin{array}{r} x_3 \\ 3 \\ 2 \end{array}$$

$$-11 \quad 2 \quad 0 \quad -11$$

$$\frac{x_1}{37} = \frac{x_2}{12} = \frac{x_3}{66} \quad x_3 = \begin{pmatrix} 37 \\ 12 \\ 66 \end{pmatrix}$$

Note:- To find the eigen vectors corresponding to nonrepeated eigen value of a matrix, we proceed as follows:-

- 1) Select the 1st two rows only
- 2) Start from the 1st row middle no. & move in anticlockwise direction to complete 1 cycle. If any element exist in the main diagonal while we are moving in anticlockwise direction, then the eigen value should be subtracted from the corresponding diagonal elements.

These elements will be return separately in row wise

- 3) Repeat the same procedure with 2nd row also.
- 4) Find eigen vectors

* Cayley - Hamilton theorem *

Statement :

Every square matrix satisfies its own characteristic eqⁿ

Ex. Consider the matrix $A = \begin{pmatrix} 4 & 2 \\ 2 & 4 \end{pmatrix}$

Its char. eq² is $\lambda^2 - 8\lambda + 12 = 0$

by cayley - Hamilton theorem, every square matrix satisfies its own char. eqⁿ.

i.e., $A^2 - 8A + 12I = 0$

Note : (2×2)

Consider the matrix $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$

$$|A - \lambda I| = 0$$

$$\begin{vmatrix} a-\lambda & b \\ c & d-\lambda \end{vmatrix} = 0$$

$$(a-\lambda)(d-\lambda) - bc = 0$$

$$ad - a\lambda - d\lambda + \lambda^2 - bc = 0$$

$$\lambda^2 - (a+d)\lambda + (ad - bc) = 0$$

$$\Rightarrow \lambda^2 - \lambda [\text{trace of } A] + |A| = 0$$

by cayley-hamilton theorem, it is

$$A^2 - A [\text{trace of } A] + |A| \cdot I = 0$$

Note: (3x3)

Consider the 3x3 matrix

$$A = \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix}, \text{ its characteristic eqn is} -$$

General procedure:-

$$\lambda^3 - \lambda^2 (\text{trace of } A) + \lambda \{ 111 + 111 + 111 \}$$

$$- |A| = 0$$

$$\begin{vmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{vmatrix}$$

$$\begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix}$$

$$\begin{vmatrix} a_{11} & a_{13} \\ a_{31} & a_{33} \end{vmatrix}$$

Using Cayley Hamilton theorem, we can find

→ Inverse of a matrix

→ Powers of a matrix.

* Positive powers of matrix

$$A = \begin{pmatrix} 4 & 2 \\ 2 & 4 \end{pmatrix}$$

$$\text{char. eq}^2 \rightarrow \lambda^2 - 8\lambda + 12 = 0$$

$$\text{Cayley Hamilton} \rightarrow A^2 - 8A + 12I = 0 \quad (1)$$

$$\text{theorem} \quad A^2 = 8A - 12I \quad (2)$$

$$A^3 = 8A^2 - 12A \quad (3)$$

$$A^4 = 8A^3 - 12A^2 \quad (4)$$

$$A^5 = 8A^4 - 12A^3 \quad (5)$$

⋮

is —

* Negative powers of matrix

$$A^2 - 8A + 12I = 0$$

$$A^2 \cdot A^{-1} - 8A \cdot A^{-1} + 12I \cdot A^{-1} = 0$$

$$A^{-2} - 8I + 12A^{-1} = 0$$

$$12A^{-1} = 8I - A$$

$$A^{-1} = \frac{1}{12} [-A + 8I]$$

$$A^{-1} \cdot A^{-1} = \frac{1}{12} [-A \cdot A + 8I \cdot A]$$

$$A^{-2} = \frac{1}{12} [-I + 8A^{-1}]$$

$$\bar{A}^1 \cdot \bar{A}^2 = \frac{1}{12} \left[-\bar{A}^1 \cdot I + 8 \bar{A}^1 \cdot \bar{A}^1 \right]$$

$$\frac{1}{12} \left[-\bar{A}^1 + 8 \bar{A}^2 \right]$$

Problem 1: — Find A^8 using Cayley hamilton theorem
for

$$A = \begin{pmatrix} 1 & 2 \\ 2 & -1 \end{pmatrix}$$

$$|A| = -1 - 4 = -5$$

$$\text{trace of } A = 1 + (-1) = 0$$

$$A^2 - A(\text{trace of } A) + |A| \cdot I = 0$$

$$A^2 - A(0) + (-5) \cdot I = 0$$

$$A^2 + A = 5I$$

$$A^2 - 5I = 0$$

$$A^2 = 5I$$

$$(A^2)^4 = (5I)^4 = 5^4 \cdot I^4$$

$$A^8 = 625I$$

$$= 625 \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$A^8 = \begin{pmatrix} 625 & 0 \\ 0 & 625 \end{pmatrix}$$

(u)
Problem 2:

Cayley-Hamilton theorem states that every square matrix satisfies its own characteristic eqn.

Consider the matrix

$$A = \begin{pmatrix} -3 & 2 \\ -1 & 0 \end{pmatrix}$$

once we get char. eqn after

replacing λ by A

1st time we get char eqn
we should not multiply it
by A^T .

i) A satisfies the relation

a) $A + 3I + 2A^T = 0$ b) $A^2 + 2A + 2I = 0$

c) $(A + I)(A + 2I) = 0$ d) $\exp(A)$

$$|A| = 0 + 2 = 2$$

$$\text{trace of } A = -3 + 0 = -3$$

$$\Rightarrow A^2 - A(\text{trace of } A) + |A| \cdot I = 0$$

$$A^2 + 3A + 2I = 0$$

$$A^2 + 2A$$

$$A^2 + 2AI + A + 2I = 0$$

$$A(A + 2I) + I(A + 2I) = 0$$

$$(A + 2I)(A + I) = 0$$

2) A^9 equals

a) $511A + 510I$ c) $154A + 155I$

b) $309A + 104I$ d) $\exp(9A)$



$$A^2 + 3A + 2I = 0$$

$$A^2 = -3A - 2I \quad \text{--- (1)}$$

$$A^3 = -3A^2 - 2A \quad \text{--- (2)}$$

(S>2)

$A^{(\text{even})} \rightarrow$ all +ve elem
 $A^{\text{odd}} \rightarrow$ all -ve elem

classmate

Date _____
 Page _____

$$\Rightarrow A^3 = -3(-3A - 2I) - 2A \quad (7>6)$$

$$\Rightarrow A^4 = 7A^2 + 6A$$

$$= 7[-3A - 2I] + 6A$$

$$= -21A - 14I + 6A$$

$$A^4 = -15A - 14I \quad (8)$$

$$\Rightarrow A^5 = -15A^2 - 14A$$

$$= -15[-3A - 2I] - 14A$$

$$= 45A + 30I - 14A$$

$$A^5 = 31A + 30I \quad (9)$$

~~Ans~~ * $A^{(\text{Higher Number})} \rightarrow A^{\text{smallest}}$, A^{10000}

* Method :-

$$\text{char eq} \Rightarrow \lambda^2 - (-3+0)\lambda + 2 = 0$$

$$\lambda^2 + 3\lambda + 2 = 0$$

$$\therefore \lambda = -1, -2$$

\Rightarrow If λ values are not repeated
 then

$$\lambda^n = a\lambda + b \quad (1)$$

$$\text{for } \lambda = -1 \quad (-1)^n = -a + b \quad (2)$$

$$\text{for } \lambda = -2 \quad (-2)^n = -2a + b \quad (3)$$

$$(-1)^n - (-2)^n a = a$$

$$\therefore a = (-1)^n - (-2)^n$$

$$\therefore b = (-1)^n + a$$

$$b = (-1)^n + a$$

$$= (-1)^n + (-1)^n - (-2)^n$$

$$= 2(-1)^n - (-2)^n$$

put a & b in eqn (1)

$$\lambda^n = [(-1)^n - (-2)^n] A + [2(-1)^n - (-2)^n]$$

by c-b theorem

$$[A^n = [(-1)^n - (-2)^n] A + [2(-1)^n - (-2)^n] I]$$

For ex put n = 9

$$A^9 = [(-1)^9 - (-2)^9] A + [2(-1)^9 - (-2)^9] I$$

$$= (-1 + 512) A + (-2 + 512) I$$

$$A^9 = 511 A + 510 I$$

Problem 3: The char eqn. of 3×3 matrix P is given by

$$d(\lambda) = |\lambda I - P| = \lambda^3 + \lambda^2 + 2\lambda + 1$$

where I denoted the Identity matrix. The inverse of the matrix P will be —

a) $P^2 + P + 2I$ c) $-(P^2 + P + I)$

b) $P^2 + P + I$ d) $-(P^2 + 2P + 2I)$

$$\lambda^3 + \lambda^2 + 2\lambda + 1$$

$$\Rightarrow P^3 + P^2 + 2P + 1 \cdot I = 0$$

$$\Rightarrow P = -I - P^2 - P^3$$

$$P^{-1} \cdot P^3 + P^{-1} \cdot P^2 + 2P^{-1} \cdot P + P^{-1} \cdot I = 0$$

$$P^2 + P + 2I + P^{-1} = 0$$

$$P^{-1} = -P^2 - P - 2I = -(P^2 + P + 2I)$$

Problem (E. value & E. vectors)

How many L.I. eigenvectors of $A = \begin{pmatrix} 2 & 1 \\ 0 & 2 \end{pmatrix}$

$$\lambda = 2, 2$$

No. of L.I. e.vectors $\Rightarrow 1 \leq p \leq m$ No. of times
e.value
2 repeated

$$P = n - r$$

no of unknowns

$$\mathfrak{F}(A - \lambda I)$$

$$(A - \lambda I) = \begin{pmatrix} 2-\lambda & 1 \\ 0 & 2-\lambda \end{pmatrix} \quad \lambda = 2$$

$$\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$$

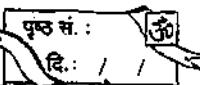
$$\mathfrak{F}(A - \lambda I) = 1$$

$$P = n - r$$

$$= 2 - 1 = \boxed{1}$$

λ

• 30



Numerical Methods (2 marks)

Topics :-

① Solutions to Algebraic and Transcendental Eqⁿ

- Bisection method

***** - Newton-Raphson Method

- Regula-false method

- Secant method

② Solutions to Systems of Linear Equation

* - Gauss Elimination Method

* - LU Decomposition

③ Solution to Integration of function

** - Trapezoidal Rule

- Simpson $\frac{1}{3}$ Rule

- Simpson $\frac{3}{8}$ th Rule

④ Solution to differential Equations

* - Euler's method

- forward

- backward

- Runge Kutta method

1987 - 2012

3 Question

2 Question

(Newton-Raphson
method)

4 Question

(Simpson
Rule)

2 Que

To

Decom

2 Que

Gauss

2 Que

Euler

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(I) Mathematical methods are of two types.

- ① Analytical method
- ② Numerical method

① Analytical method:-

Ex. 1. find roots of $x^2 - 5x + 6 = 0$ using analytical method

$$\rightarrow \text{Analytical sol}^n \text{ is } x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$\therefore x = 3, 2$$

Q. 2. find $\int_1^2 x dx$ using analytical method

$$\rightarrow \int_1^2 x dx = \left[\frac{x^2}{2} \right]_1^2$$

$$= \left[\frac{4}{2} - \frac{1}{2} \right]$$

$$= \frac{3}{2}$$

Q. 3. Solve $\frac{dy}{dx} = x$, Using analytical method.

$$\rightarrow \frac{dy}{dx} = x \quad \therefore dy = x dx$$

$$\text{Integrate } \int \frac{dy}{dx} dx = \int x dx \quad \int dy = \int x dx$$

$$y = \frac{x^2}{2} + C$$

Note: - Drawback of analytical method is, it is not applicable for higher degree equations & also not applicable for non-linear Eq's.

To overcome this, we use NUMERICAL METHODS.

- NUMERICAL METHODS provide Approximation value

[I] Solution to Algebraic and Transcendental Equation

* Intermediate Mean Value theorem :-

$f(x)$ is a continuous function defined on $[a, b]$.
 $f(a)$ & $f(b)$ having opposite signs. In such case there exist at least one Root of $f(x) = 0$ in $[a, b]$.

Let,

$$f(x) = x^3 - 4x - 9, \text{ in } [2, 3]$$

$$\therefore f(2) = 2^3 - 4(2) - 9$$

$$= -9$$

$$\therefore -9 < 0$$

$$\& f(3) = 3^3 - 4(3) - 9$$

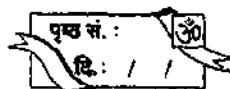
$$= 6 > 0$$

Since, $f(2) < 0$ & $f(3) > 0$

So, there exist atleast one root in $[2, 3]$

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\exists - there exists



* Bisection Method :-

Step 1 :- Let, $f(x)$ is a continuous on $[a, b]$

Step 2 :- $f(a) & f(b)$ having opposite signs

Say $f(a) < 0 & f(b) > 0$

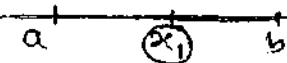
Using intermediate mean value theorem

There exist (\exists) atleast one root in $[a, b]$

Step 3 :- Let,

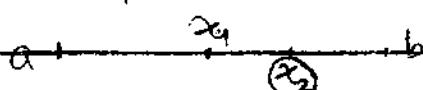
Approximation root is x_1 , and

$$x_1 = \frac{a+b}{2}$$



Case I :-

If $f(x_1) = 0 \implies x_1$ is root then
Stop process.



Case II :-

If $f(x_1) < 0$ and $f(b) > 0$

$$\text{then } x_2 = \frac{x_1+b}{2}$$

Continue this process until desired root is found

Case III :-

If $f(x_1) > 0$ and $f(a) < 0$

So \exists atleast one root between $[a, x_1]$

$$\text{Say, } x_3 = \frac{a+x_1}{2} \quad a \xrightarrow{x_3} x_4 \xrightarrow{} b$$

Continue this process until desired root is found

Q. find x_2 and x_3 using Bisection method where

$$f(x) = x^3 - 4x - 9, [2, 3]$$

→ Put intervals in $f(x)$

$$\begin{aligned} f(2) &= 2^3 - 4 \times 2 - 9 \\ &= -9 \end{aligned}$$

$$\therefore -9 < 0 \quad \therefore f(2) < 0$$

$$\begin{aligned} f(3) &= 3^3 - 4 \times 3 - 9 \\ &= 6 \end{aligned}$$

$$\therefore 6 > 0 \quad \therefore f(3) > 0$$

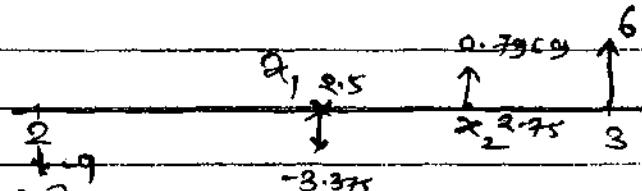
\exists at least one root between $[2, 3]$

$$x_1 = \frac{2+3}{2} = 2.5$$

$$\begin{aligned} f(2.5) &= (2.5)^3 - 4(2.5) - 9 \\ &= -3.375 \end{aligned}$$

$$\therefore -3.375 < 0 \quad \therefore f(2.5) < 0.$$

Since $f(2.5) < 0$ and $f(3) > 0$



\exists root b/w $[2.5, 3]$

$$\therefore \text{Let } x_2 = \frac{2.5+3}{2} = \frac{5.5}{2} = 2.75$$

$$\begin{aligned} f(x_2) &= f(2.75) = (2.75)^3 - 4(2.75) - 9 = 0.7969 \\ \therefore 0.7969 &> 0 \end{aligned}$$

Since $f(2.75) > 0$ & $f(2.5) < 0$

So f atleast one root in $[2.5, 2.75]$

Say,

$$x_3 = 2.5 + 2.75$$

2

$$x_3 = 2.62$$

* Newton Raphson Method :-

Step 1 :- let, $f(x)$ is continuous function $[a, b]$

Step 2 :- Newton Raphson iteration formula for finding root of $f(x) = 0$ is,

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$$

Q. find Newton raphson iteration formula for square root of tve real number 'c'.

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$$\Rightarrow \text{let, } x = \sqrt{c}$$

Squaring both sides.

$$x^2 = c$$

$$\therefore x^2 - c = 0$$

$$\therefore f(x) = x^2 - c \quad \therefore f(x_n) = x_n^2 - c$$

$$f'(x) = 2x \quad f'(x_n) = 2x_n$$

\therefore By Newton Raphson $x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$

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$$x_{n+1} = x_n - \frac{x_n^2 - c}{2x_n}$$

$$x_{n+1} = \frac{x_n^2 + c}{2x_n}$$

Q. find N-R iteration formula for $f(x) = x^2 - 117 = 0$

GATE 2009 $\rightarrow f(x) = x^2 - 117$; $f(x_0) = (x_0)^2 - 117$
 $f'(x) = 2x$; $f'(x_n) = 2x_n$

$$x_{n+1} = x_n - \frac{x_n^2 - 117}{2x_n}$$

$$x_{n+1} = \frac{x_n^2 + 117}{2x_n}$$

Q. If $f(x) = x^2 - 13$ and $x_0 = 3.5$, then
GATE 2010 Value of x_1 using N.R. iteration formula
 $f(x) = x^2 - 13$; $f(x_0) = x_0^2 - 13$
 $f'(x) = 2x$; $f'(x_n) = 2x_n$

$$\therefore x_{0+1} = x_0 - \frac{x_0^2 + 13}{2x_0}$$

$$x_1 = \frac{x_0^2 + 13}{2x_0}$$

$$x_1 = \frac{(3.5)^2 + 13}{2 \times 3.5} = \underline{\underline{3.607}}$$

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Q Newton Raphson iteration formula for finding
E

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396

$$\text{Let } x = \sqrt[3]{c}$$

Cubing

$$x^3 = c$$

$$x^3 - c = 0$$

$$f(x_1) = x^3 - c$$

$$f(x_0) = x_0^3 - c$$

$$f'(x) = 3x^2 - 0$$

$$f'(x_0) = 3x_0^2$$

$$\therefore x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$$

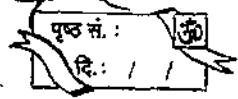
$$= x_0 - \frac{x_0^3 - c}{3x_0^2}$$

$$= 3x_n^3 - x_n^3 + C$$

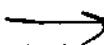
$$x_{n+1} = \frac{2x_n^3 + c}{3x_n^2}$$

Q The N-R method is used to find the root of
 $x^2 - 2 = 0$ Starting value is $x_0 = -1$;
 The iteration formula will be

Faster or Convergence is Rate of convergence



- ① Converges to -1 ② Converges to $-\sqrt{2}$
- ③ Converges to $\sqrt{2}$ ④ Not convergent



$$f(x) = x^2 - 2 \quad f'(x_n) = 2x_n - 2$$

$$f(x_0) = x_0^2 - 2 \quad f'(x_0) = 2x_0$$

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$$

$$x_{0+1} = x_0 - \frac{f(x_0)}{f'(x_0)}$$

$$x_1 = -1 - \frac{(-1)^2 - 2}{2(-1)}$$

$$= -1 - \frac{1 - 2}{-2}$$

$$= -1 + \frac{1}{2}$$

$$= -1 + 0.5$$

$$x_1 = -1 + 0.5$$

$$\therefore x_2 = \frac{x_1^2 + 2}{2x_1} = \frac{(-1.5)^2 + 2}{2(-1.5)} = -1.416$$

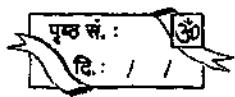
$$\therefore x_3 = \frac{x_2^2 + 2}{2x_2} = \frac{(-1.416)^2 + 2}{2(-1.416)} = -1.414$$

$$\text{If } x_4 = -1.414 \text{ i.e. } -\sqrt{2}$$

Recess

10.30 AM

अश्लील, गंदे विद्यारथी पुस्तक पढ़ना जहर पीने से भी ज्यादा खतरनाक है।



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प्रेम सबसे करो, बुरा किसीका न करो।

Q find Newton Raphson iteration formula, for x_n reciprocal of a where $a > 0$

GATE
2005

$$\rightarrow \text{Let, } x = \frac{1}{a}$$

$$\frac{1}{x} = a$$

$$\therefore \frac{1}{x} - a = 0$$

$$\therefore f(x) = \frac{1}{x} - a$$

$$f'(x) = \frac{-1}{x^2}$$

$$\begin{aligned} x_{n+1} &= x_n - \frac{f(x_n)}{f'(x_n)} \\ &= x_n - \frac{\left(\frac{1}{x_n} - a\right)}{\left(-\frac{1}{x_n^2}\right)} \\ &= x_n + x_n^2 \left(\frac{1}{x_n} - a\right) \end{aligned}$$

$$= x_n + x_n - ax_n^2$$

$$x_{n+1} = 2x_n - ax_n^2$$

Q Given $a > 0$, we wish to compute N-R iteration

GATE
2005

formula for reciprocal of a for $a = 7$ and $x_0 = 0.2$, then first two iteration will be :

- (A) 0.11, 0.1299 (B) 0.12, 0.1392

$$0.4 - 7, 0.0 \text{ अशलील, गंदे विचारवाले मुस्तक पढ़ना जहर पीने से भी ज्यादा खतरनाक है।}$$

$$= 0.4 - 35 = \frac{35}{0.12}$$

Given $x_2 = \frac{1}{a}$

$$\therefore \frac{1}{2} - a = f(x)$$

$$\therefore x_{n+1} = 2x_n - ax_n^2$$

$$x_{0+1} = 2x_0 - ax_0^2$$

$$= 2 \times 0.2 - 7(0.2)^2$$

$$\underline{x_1 = 0.12}$$

$$\begin{aligned} x_{n+1} &= x_n = 2x_1 - ax_1^2 \\ &= 2(0.12) - 7(0.12)^2 \\ &\approx 0.24 - 7 \times 0.0144 \\ &\underline{x_2 = 0.1392} \end{aligned}$$

t.w

Q. $f(x) = x - \cos x$, then $x_{n+1} = ?$
 Ans. $\Rightarrow x_{n+1} = \frac{(x_n - \cos x_n)}{1 + \sin x_n}$

t.w Q. $f(x) = x e^x - 2$, $x_0 = 0.8679$ then $x_1 = ?$
 Ans. $\Rightarrow x_1 = 0.853$

t.w Q. $f(x) = x^3 - x^2 + 4x - 4 = 0$, if $x_0 = 2$, then $x_1 = ?$
 Ans. $\Rightarrow x_1 = 4/3$

t.w Q. $f(x) = e^{x-1} - 1$, $x_0 = -1$, then $x_1 = ?$
 Ans. $\Rightarrow x_1 = 0.71828$

$$2x + y + z = 10$$

$$y + 3z = 6$$

$$-2z = -10$$

\therefore By Using Back Substitution,
we get $z = 5, y = -9, x = 7$

Case II :-

$$\text{If } R(A) = R(AB) = r$$

$$\text{but } r < n$$

* * (i) No. of linearly independent solutions
 $= n - r$.

(ii) No. of linearly dependent
solutions $= r$.

In this case system has infinitely many solutions.

Ex:- Same example only 3rd row elements are made zeros.

$$\therefore \left[\begin{array}{ccc|c} 2 & 1 & 1 & 10 \\ 0 & 1/2 & 3/2 & 3 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Here,

$$R(A) = 2 = R(AB)$$

(i) No. of linearly independent solns $= n - r$
 $= 3 - 2$

(ii) No. of linearly dependent
 \Rightarrow
 $= r$
 $= 2$.

अश्लील, गंदे विचारवाली पुस्तक पढ़ना जहर पीने से भी ज्यादा खतरनाक है।

$$\left[\begin{array}{ccc|c} 2 & 1 & 1 & 10 \\ 0 & 1/2 & 3/2 & 3 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$\left[\begin{array}{ccc|c} 2 & 1 & 1 & x \\ 0 & 1/2 & 3/2 & y \\ 0 & 0 & 0 & z \end{array} \right] = \left[\begin{array}{c} 10 \\ 3 \\ 0 \end{array} \right]$$

$$2x + y + z = 10 \quad \text{(i)}$$

$$y + 3z = 3 \quad \text{(ii)}$$

$$\therefore y = 3 - 3z \quad \text{(i)} \quad \begin{aligned} y &\text{ is dependent} \\ &\& z \text{ is independent} \end{aligned}$$

& from (i)

$$2x = 2 + z \quad \text{(ii)} \quad \begin{aligned} x &\text{ is dependent} \\ z &\text{ is independent} \end{aligned}$$

$$\therefore \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 2+z \\ 3-3z \\ z \end{bmatrix}$$

$$\therefore \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \\ 0 \end{bmatrix} + z \begin{bmatrix} 1 \\ -3 \\ 1 \end{bmatrix}$$

for different values of z we get different solⁿ. so system has infinite solⁿ.

S

Bisection f(x) [a, b]
 N.R f(x) x_0

$$\frac{d}{dx} \ln x = \frac{1}{x}$$

Q. $f(x) = x - e^{-x}$, then $x_{n+1} = ?$

~~2008~~ Ans. $\Rightarrow x_{n+1} = \frac{e^{-x_n}(1+x_n)}{1+e^{-x_n}}$

~~2011~~ Q. $f(x) = x + \sqrt{x-3}$, and $x_0 = 2$, then $x_1 = ?$

\Rightarrow Ans. $\Rightarrow x_1 = 1.8124$

~~1999~~ Q. The Newton Raphson method used to find the root of the equation and $f'(x)$ is derivative of f then the method is converges

(a) Always (b) Only if f' is polynomial

(c) Only if $f(x_0) < 0$

(d) None of the above

\Rightarrow Ans. = (d)

- Newton Raphson method is useful for finding roots of eqn whether curve is less to x axis, i.e. the curves which are generating high slopes we can get better results using N-R method

- If slope is less then N-R method is not providing accurate results

- The N-R method converging to the root if it satisfy the following eqn

$$|f(x) \cdot f'(x)| < |f'(x)|^2$$

* Regula-false Method :-

Step 1 : - Let, $f(x)$ is continuous function in $[a, b]$

Step 2 : - Let us assume that x_0 and x_1 are initial approximation values for the required root such that $f(x_0)$ and $f(x_1)$ having opposite signs
Say $f(x_0) < 0$, $f(x_1) > 0$

Step 3 : - Regula-false Iteration formula for finding root of $f(x) = 0$ in $[x_0, x_1]$ is

$$\text{if } x_n = \frac{f_n \cdot x_{n-1} - f_{n-1} \cdot x_n}{f_n - f_{n-1}}$$

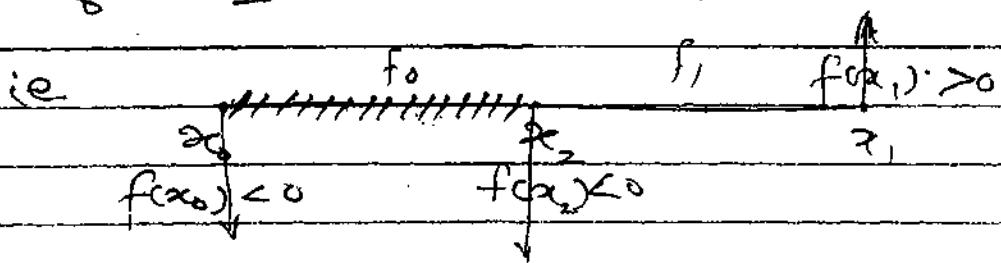
$$\text{In particular } x_2 = \frac{f_1 \cdot x_0 - f_0 \cdot x_1}{f_1 - f_0} \quad n=1 \quad (i)$$

Case I :-

If $f(x_2) = 0 \implies x_2$ is root, then Stop process

Case II :-

If $f(x_2) < 0$ and $f(x_1) > 0$



To find compute x'_3 , replace x'_0 by x_2

$$\therefore x_3 = \frac{f_1 x_2 - f_2 x_1}{f_1 - f_2}$$

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Case III :-

If $f(x_1) > 0$ and $f(x_0) < 0$

So to compute ' x_2 ', we have to replace ' x_1 ' by ' x_0 '
 'f' by f_2 in Eqn (i)

$$x_2 = \frac{f_2 \cdot x_0 - f_0 \cdot x_1}{f_2 - f_0}$$

Continue the process until desired accuracy is found

Q. $f(x) = x^3 + x - 1$ and $[0.5 \ 1]$ then
 find x_2, x_3 using Regula falsae method
 $\rightarrow [0.5, 1] = [x_0, x_1]$

$$f(x) = x^3 + x - 1$$

$$f(0.5) = (0.5)^3 + 0.5 - 1 = -0.375 \text{ i.e. } < 0$$

$$f(1) = 1^3 + 1 - 1 = 1 \text{ i.e. } > 0$$

$$\text{Let, } x_2 = \frac{f_1 x_0 - f_0 x_1}{f_1 - f_0}$$

$$= \frac{1 \times 0.5 - (-0.375) \times 1}{1 - (-0.375)}$$

$$x_2 = 0.64$$

$$\text{Now, } f_2 = f(x_2) = f(0.64) = (0.64)^3 + 0.64 - 1 \\ = -0.0979$$

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~~Rafala form~~
Secant form

Assume $[x_0, x_1] \rightarrow f(x_0) < 0$
 $[x_0, x_1], f(x_0), f(x_1) < 0$

$$\therefore x_3 = \frac{f_1 \cdot x_2 - f_2 \cdot x_1}{f_1 - f_2}$$

formula

$$x_3 = \frac{f_1 x_2 - f_2 x_1}{f_1 - f_2}$$

$$= -0.0979 \times 0.5 - (-0.375) \times (0.64)$$

$$= 0.0979 - (-0.375)$$

wrong.

$$= -0.0979 \times 0.5 + 0.375 \times 0.64$$

$$= 0.979 + 0.375$$

$$\boxed{\text{Ans.} = 0.672}$$

* Secant Method :-

The difference between Regula-falsi & Secant method is, in Secant method the initial Guess values x_0, x_1 need not satisfy the condition.

$$\text{Let, } [f(x_0) \times f(x_1)] < 0$$

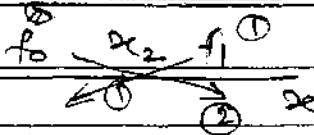
i.e. Secant method does not provide guarantee that the root is existing in the initial guess interval (x_0, x_1) .

Iteration formula for finding roots of Given eqn using Secant method is

$$x_{n+1} = \frac{f_n \cdot x_{n-1} - f_{n-1} \cdot x_n}{f_n - f_{n-1}}$$

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$x_0 \rightarrow x_1 \rightarrow x_2 \rightarrow x_3 \rightarrow x_4$



In particular,

$$\frac{x_2 - f_1 \cdot x_0 - f_0 \cdot x_1}{f_1 - f_0} \quad \text{--- (i)}$$

To compute x_3 , x_0 is replaced by x_1
 x_1 replaced by x_2 in eq (i)

Continue process until desired accuracy of root is found.

Q Using Secant Method, find 1st & 2nd approximation of the real root for the equation
 $x^3 - 2x - 5 = 0$, with [2, 3]

$$f(x) = x^3 - 2x - 5, f(x) =$$

$$f(2) = 2^3 - 2(2) - 5 = -1 < 0 \quad \text{--- } f_0$$

$$f(3) = 3^3 - 2(3) - 5 = 16 > 0 \quad \text{--- } f_1$$

$$x_2 = \frac{f_1 \cdot x_0 - f_0 \cdot x_1}{f_1 - f_0} = \frac{16 \times 2 - (-1) \times 3}{16(-) (-1)}$$

$$= \frac{32 + 3}{16}$$

$$= \frac{35}{16} \approx 2.1875$$

$$\begin{aligned} f(x_2) &= (2.1875)^3 - 2(2.1875) - 5 \\ &= -0.3996 \approx -0.4000 \end{aligned}$$

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$$x_3 = \frac{f_2 \cdot x_1 - f_1 \cdot x_2}{f_2 - f_1}$$



$$= -0.3907 \times 3 - 16 \times 2.058 \\ -0.3907 - 16$$

$$x_3 = 2.0812$$

* Method

Order of Convergence ↑

① Bisection Linear Convergence $\Rightarrow E_{n+1} = k \cdot E_n^{\frac{1}{2}}$
means of order 1

② Regula Falsi Linear Convergence $\Rightarrow E_{n+1} = k \cdot E_n^{\frac{1}{2}}$
 $-1/1 - -1/1 - 1$

③ Secant Method Quadratic Convergence $\Rightarrow E_{n+1} = k \cdot E_n^{\frac{1}{2}}$
 $0 - 1/1 - -1/1 - 1 \cdot 6^2$

④ Newton Raphson Quadratic Convergen. $\Rightarrow E_{n+1} = k \cdot E_n^{\frac{1}{2}}$
 $-1/1 - -1/1 - -2$

if $x_0 = 2.02$,

$$x_{n+1} = 2.004$$

$$\text{Error} = \text{Exact} - \text{Approx}$$

$$E_n = 2 - 2.02 \\ = -0.02$$

$$E_{n+1} = -0.004$$

$$E_{n+1} = E_n^{\frac{1}{2}}$$

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or and

$$x_n = 2.03$$

$$x_{n+1} = 2.06$$

$$E_{n+1} = 0.06$$

$$E_n = 0.03$$

$$\boxed{E_{n+1} = 2 E_n}$$

Note: Let us consider n^{th} degree polynomial
 $f(x) = 0$

- (a) The number of +ve real roots for ~~$f(x) > 0$~~
 $f(x) \leq 0$ The number of sign changes in ~~$f(x) = 0$~~
- (b) The number of -ve real roots for ~~$f(x) < 0$~~
 $f(x) \leq 0$ The number of sign changes in ~~$f(x) = 0$~~
- (c) The number of imaginary roots = ~~$\frac{n}{2}$~~
 $n - (\text{No. of +ve roots} + \text{No. of -ve roots})$

Q. Polynomial $f(x) = x^5 + x + 2$ has

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- (a) All real roots
- (b) Three real roots & 2 complex
- (c) 1 real & 4 complex roots
- (d) All complex roots

→ from Note (a)

No. of +ve \leq No. of sign changes in $f(x)$
 real roots

$$\therefore \text{No. of +ve real roots} = 0$$

from

Note (b) No. of -ve \leq No. of sign changes in $f(-x)$
 real roots

$$f(-x) = -x^5 - x + 2$$

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$$P(x) = 1 \text{ change}$$

\therefore '1' (-ve) real roots.

$$\begin{aligned}\text{Imaginary roots} &= n - [(\text{+ve}) + (\text{-ve}) \text{ roots}] \\ &= 5 - [0 + 1] \\ &= 4\end{aligned}$$

\therefore Ans. 1 Real root & 4 complex root

Q. If $\alpha_1, \alpha_2, \alpha_3, \dots, \alpha_n$ are n roots of Eq.

$$a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0 = 0$$

$$\textcircled{a} \sum_{i=1}^n \alpha_i = \textcircled{b} \sum_{i=1}^n \alpha_1 \alpha_2 = \dots$$

$$\textcircled{c} \sum \alpha_1 \alpha_2 \alpha_3 = \dots \textcircled{d} \alpha_1 \alpha_2 \dots \alpha_n = \frac{(-1)^{n-1} a_0}{a}$$

$$ax^2 + bx + c = 0$$

$$\therefore \alpha_1 + \alpha_2 = -\frac{b}{a}$$

$$\alpha_1 \alpha_2 = \frac{c}{a} = \frac{\text{const.}}{\text{coeff. of } x^2}$$

$$\therefore \alpha_1 \alpha_2 \alpha_3 = \frac{\text{const}}{\text{coeff. of } x^3}$$

$$\alpha_1 \alpha_2 \alpha_3 \dots \alpha_n = \frac{\text{const}}{\text{coeff. of } x^n}$$

$$\therefore \alpha_1 \alpha_2 \alpha_3 \dots \alpha_n = \frac{a_n}{a_0}$$

$$\therefore ax^3 + bx^2 + cx + d = 0.$$

$$\therefore \alpha_1 + \alpha_2 + \alpha_3 = \frac{\text{coefficient of } x^2}{\text{coefficient of } x^3}$$

$$= -\frac{b}{a} = -\frac{\alpha_1}{\alpha_0}$$

$$\sum \alpha_1 \cdot \alpha_2 = \frac{\alpha_2}{\alpha_0}$$

$$\therefore \sum \alpha_1 \cdot \alpha_2 \cdot \alpha_3 = -\frac{\alpha_3}{\alpha_0}$$

$$\therefore \sum_{i=1}^n \alpha_i = -\frac{\alpha_1}{\alpha_0}$$

$$\sum \alpha_1 \cdot \alpha_2 = \frac{\alpha_2}{\alpha_0}$$

$$\sum \alpha_1 \cdot \alpha_2 \cdot \alpha_3 = -\frac{\alpha_3}{\alpha_0}$$

$$\alpha_1 \cdot \alpha_2 \cdots \alpha_n = (-1)^n \frac{\alpha_n}{\alpha_0}$$

alternate
+ve, -ve
signs.

Q. It is known that the roots of the non-linear eq?

~~Ques~~ ~~Ans~~ ~~2008~~ ~~2008~~ are 1 & 3 thus 3rd root will be

$$\alpha_1 + \alpha_2 + \alpha_3 = -\frac{b}{a} \approx -\frac{(-6)}{1} = 6$$

$$\alpha_1 \cdot \alpha_2 \cdot \alpha_3 = \cancel{\alpha_1} \cdot \cancel{\alpha_2} \cdot \cancel{\alpha_3} = -6 = -6$$

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Here, $x^3 - 6x^2 + 11x - 6 = 0$

$$\therefore a_0 x^3 + a_1 x^2 + a_2 x + a_3 = 0$$

$$\alpha_1 \cdot \alpha_2 \cdot \alpha_3 = \frac{c}{a} = (-1)^3 (-6)$$

$$1 \times 3 \times \alpha_3 = (-1)(-6)$$

$$\alpha_3 = \frac{6}{3}$$

$\alpha_3 = 2$

24/08/12

पृष्ठ सं.:

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II Solutions to System of linear Equation

(A) Gauss Elimination :-

"MATRIX METHOD"

Q. Solve $2x + y + z = 10$

$$3x + 2y + 3z = 18$$

$$x + 4y + 9z = 16$$



Step I :- Construct Augmented matrix

$$\text{i.e } [A:B] = \left[\begin{array}{ccc|c} 2 & 1 & 1 & 10 \\ 3 & 2 & 3 & 18 \\ 1 & 4 & 9 & 16 \end{array} \right]$$

— A = Coefficient matrix

B = Constant matrix.

Step II :- Convert augmented matrix into an upper triangular matrix using elementary row operations

Here, in above prob we have to do Row operation
as, $R_2 - 3R_1$ and $R_3 - R_1$

$$\therefore [A:B] = \left[\begin{array}{ccc|c} 2 & 1 & 1 & 10 \\ 0 & \frac{1}{2} & \frac{8}{2} & 3 \\ 0 & \frac{7}{2} & \frac{17}{2} & 11 \end{array} \right]$$

अश्लील, गंदे विचारवाली पुस्तक पढ़ना जहर पीने से भी ज्यादा खतरनाक है।

$$R_3 - \frac{7}{2} R_2 = R_3 - 7R_2$$

$$\therefore \boxed{\text{Crossed out}} \approx \left[\begin{array}{ccc|c} 2 & 1 & 1 & 10 \\ 0 & \frac{1}{2} & \frac{3}{2} & 3 \\ 0 & 0 & -2 & -10 \end{array} \right]$$

Imp.

expected

Ques.

$\rho(A) = \text{No. of Non zero rows in an upper triangular matrix of } A$

Case I :-

$$\text{IF } \rho(A) = \rho(AB) = r = n$$

where, n is no. of unknowns

i.e. ($x, y, z \dots$ etc.)

Then the system is said to CONSISTENT
and it has a UNIQUE SOLUTION.

⇒ Continue to prob.

$$\therefore \left[\begin{array}{ccc|c} 2 & 1 & 1 & 10 \\ 0 & \frac{1}{2} & \frac{3}{2} & 3 \\ 0 & 0 & -2 & -10 \end{array} \right]$$

$$\text{Here } \rho(A) = \rho(AB) = 3 = n$$

So, it has a Unique sol.

$$\therefore \left[\begin{array}{ccc|c} 2 & 1 & 1 & 10 \\ 0 & \frac{1}{2} & \frac{3}{2} & 3 \\ 0 & 0 & -2 & -10 \end{array} \right] \left[\begin{array}{c} x \\ y \\ z \end{array} \right] = \left[\begin{array}{c} 10 \\ 3 \\ -10 \end{array} \right]$$

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Case (iii) :-

If $\rho(A) \neq \rho(AB)$ then

System is said to be "INCONSISTENT", then
it has "NO SOLUTION"

Ex:- Same example, but in constant matrix in
third row a const is present i.e -5.

$$\left[\begin{array}{ccc|c} 2 & 1 & 1 & 10 \\ 0 & 1/2 & 3/2 & 3 \\ 0 & 0 & 0 & -5 \end{array} \right]$$

$$\therefore \rho(A) = 2$$

$$\rho(AB) = 3$$

$\therefore \rho(A) \neq \rho(AB) \longrightarrow \text{NO SOLUTION}$

Gauss Elimination :-

⇒ "PIVOTAL SOLUTION"

Q. Solve :-

$$2x + y + z = 10$$

$$3x + 2y + 3z = 18$$

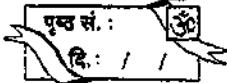
$$x + 4y + 9z = 16$$

Step I :- Construct augmented matrix

$$\text{i.e. } [A:B] = \left[\begin{array}{ccc|c} 2 & 1 & 1 & 10 \\ 3 & 2 & 3 & 18 \\ 1 & 4 & 9 & 16 \end{array} \right]$$

अश्लील, गंदे विचारवाली पुस्तक पढ़ना जहर पीने से भी ज्यादा खतरनाक है।

From $(2, 3, -10, 5, 1, -7)$ the largest absolute value
 is -10



absolute = |modulus|

Since, $a_{11} = 2$

Now, Scan entire 1st column and select
 largest absolute value and make it as
 "pivot". Exchange pivot element row with
1st row and then eliminate α from row 2 &
row 3.

$$R_2 \leftrightarrow R_1 \quad \left| \begin{array}{ccc|c} 3 & 2 & 3 & 18 \\ 2 & 1 & 1 & 10 \\ 1 & 4 & 9 & 16 \end{array} \right|$$

$$\frac{R_2 - 2R_1}{3} \quad \& \quad \frac{R_3 - R_1}{3}$$

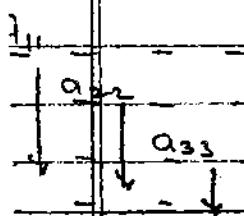
$$\left| \begin{array}{ccc|c} 3 & 2 & 3 & 18 \\ 0 & -1/3 & -1 & -2 \\ 0 & 10/3 & 8 & 16 \end{array} \right|$$

Since, $a_{22} = -1/3$

Now, Scan entire 2nd column α from a_{22}
 and select largest absolute value
 i.e. $\left| -\frac{1}{3} \right| < \left| \frac{10}{3} \right|$ and make it as pivot

Given
Date
2022

Exchange pivot element row with 2nd row
 and then eliminate γ from row 3



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$$R_2 \leftrightarrow R_3$$

$$\left[\begin{array}{ccc|c} 3 & 2 & 3 & 18 \\ 0 & 10/3 & 8 & 10 \\ 0 & -1/3 & -1 & -2 \end{array} \right]$$

$$R_3 + \frac{(\frac{1}{3})R_2}{(\frac{10}{3})} = R_3 + \frac{R_2}{10}$$

$$\approx \left[\begin{array}{ccc|c} 3 & 2 & 3 & 1 \\ 0 & 10/3 & 8 & 10 \\ 0 & 0 & -1/5 & -1 \end{array} \right]$$

$$\left[\begin{array}{ccc|c} 3 & 2 & 3 & x \\ 0 & 10/3 & 8 & y \\ 0 & 0 & -1/5 & z \end{array} \right] = \left[\begin{array}{c} 18 \\ 10 \\ -1 \end{array} \right]$$

By solving,
 $x = 5$
 $y = -9$
 $z = 7$

Q. In the solutions of the following set of linear equations by Gauss Elimination Using Pivotal sol'n the pivots for eliminating "x" & "y" resp.

$$5x + y + 2z = 34$$

$$4y - 3z = 12$$

$$10x - 2y + 2z = -4$$

(a) 10 & 4

(b) 10 & 2

(c) 5 & 4

(d) 5 & -4

| | | | |
|----|----|----|----|
| 5 | 1 | 2 | 34 |
| 0 | 4 | -3 | 12 |
| 10 | -2 | 1 | -4 |

| | | | | |
|----|----|----|----|--|
| 10 | -2 | 1 | -4 | |
| 0 | 4 | -3 | 12 | |
| 5 | 1 | 2 | 34 | |

~~R₃~~ R_{1/2}

| | | | | |
|----|--------------|----------------|---------------|--|
| 10 | -2 | 1 | -4 | |
| 0 | 4 | -3 | 12 | |
| 0 | 2 | 3/2 | 36 | |

$$\text{Ans. } Q_{11} = 10$$

$$Q_{12} = 4$$

∴ Ans. 10 & 4.

(B) LU Decomposition (Method of factorisation) or
Do-little method.

Step I :- Let us consider $a_{11}x_1 + a_{12}x_2 + a_{13}x_3 = b_1$,
 $a_{21}x_1 + a_{22}x_2 + a_{23}x_3 = b_2$,
 $a_{31}x_1 + a_{32}x_2 + a_{33}x_3 = b_3$.

Step II :- Matrix representation of given system of
equation is ~~is~~ $Ax = B$

$$Ax = B \longrightarrow (i)$$

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Let, $A = LU$ ————— (ii)

— where L = lower Unit Δ'wise matrix

$$i.e. L = \begin{bmatrix} 1 & 0 & 0 \\ l_{21} & 1 & 0 \\ l_{31} & l_{32} & 1 \end{bmatrix}$$

U = Upper Δ'wise matrix

$$= \begin{bmatrix} U_{11} & U_{12} & U_{13} \\ 0 & U_{22} & U_{23} \\ 0 & 0 & U_{33} \end{bmatrix}$$

i.e. (ii) $\Rightarrow LUX = B$ ————— (iii)

Let, $UX = Y$ ————— (iv)

where, $Y = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}$

$\therefore \cancel{LX} = B$.

$$\begin{bmatrix} 1 & 0 & 0 \\ l_{21} & 1 & 0 \\ l_{31} & l_{32} & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

By solving, we get, y_1, y_2, y_3 in terms of elements of lower unit Δ'wise matrix.

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$$\therefore \begin{bmatrix} U_{11} & U_{12} & U_{13} \\ 0 & U_{22} & U_{23} \\ 0 & 0 & U_{33} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}$$

in terms of

By Solving, we get x_1, x_2, x_3 the elements of
Upper Triangular and lower Unit Triangular matrix.

The order computing elements of L & U is
 $U_{11}, U_{12}, U_{13}, l_{21}, U_{22}, U_{23}, l_{31}, l_{32}, U_{33}$.

Note: CROUT's method is similar to Do-little method except that in Crout's method 'A' is decomposed with lower triangular matrix & Unit upper triangular matrix.

i.e. $L = \begin{bmatrix} l_{11} & 0 & 0 \\ l_{21} & l_{22} & 0 \\ l_{31} & l_{32} & l_{33} \end{bmatrix}$

$$U = \begin{bmatrix} 1 & U_{12} & U_{13} \\ 0 & 1 & U_{23} \\ 0 & 0 & 1 \end{bmatrix}$$

GATE Q In matrix A is $\begin{bmatrix} 2 & 1 \\ 4 & -1 \end{bmatrix}$ is decomposed into

product of lower and upper Dubois matrices

Using Croat's method The properly decomposed L & U matrices respectively

$$@ \begin{bmatrix} 1 & 0 \\ 4 & -1 \end{bmatrix} \textcircled{+} \begin{bmatrix} 1 & 0 \\ 0 & -2 \end{bmatrix}$$

$$\text{⑥} \quad \left[\begin{array}{cc} 2 & 0 \\ 4 & -3 \end{array} \right] \quad \left[\begin{array}{cc} 1 & 0.5 \\ 0 & 1 \end{array} \right]$$

$$\xrightarrow{\quad \Rightarrow \quad} \text{If } \begin{pmatrix} 2 & 1 \\ 4 & -1 \end{pmatrix} = \begin{pmatrix} l_{11} & 0 \\ l_{21} & l_{22} \end{pmatrix} \begin{pmatrix} 1 & 0_{12} \\ 0 & 1 \end{pmatrix}$$

$$\begin{array}{cc|c} 2 & 1 & l_{11} \\ 4 & -1 & l_{21} \end{array} = \begin{array}{cc} l_{11} & l_{11} \cdot U_{12} \\ l_{21} & l_{21} \cdot U_{12} + l_{22} \end{array}$$

$$\therefore l_1 = 2$$

$$l_1 \cup l_2 = 1$$

$$\therefore \text{O}_{12} = 1/2$$

$$l_{21} = 4$$

$$l_{21} \cdot 0_{12} + l_{22} = -1 \quad 4 \times \frac{1}{2} + l_{22} = -1$$

$$l_{22} = -3$$

$$\therefore \begin{bmatrix} l_{11} & 0 \\ l_{21} & l_{22} \end{bmatrix} \begin{bmatrix} 1 & v_{12} \\ 0 & 1 \end{bmatrix}$$

$$\left[\begin{array}{cc|cc} 2 & 0 & 1 & \frac{1}{2} \\ 4 & -8 & 0 & 1 \end{array} \right]$$

अश्लील, गंदे विचारवाली पुस्तक पढ़ना जहर पीने से भी ज्यादा खतरनाक है।

III Solution to Integration of function :-

Let us consider the given curve is $f(x)$ and ordinates on x axis is $x=a$ & $x=b$

The area bounded by the given curve and the ordinates is denoted by

$$\int_a^b f(x) dx \quad \text{---} \quad *$$

Divide $[a, b]$ into "n" equal subintervals where, length of each interval is " h " (Step Size)

$$x_0 = a$$

$$x_1 = x_0 + h$$

$$x_2 = x_1 + h = x_0 + h + h = x_0 + 2h$$

$$x_3 = x_2 + h = x_0 + 2h + h = x_0 + 3h$$

.

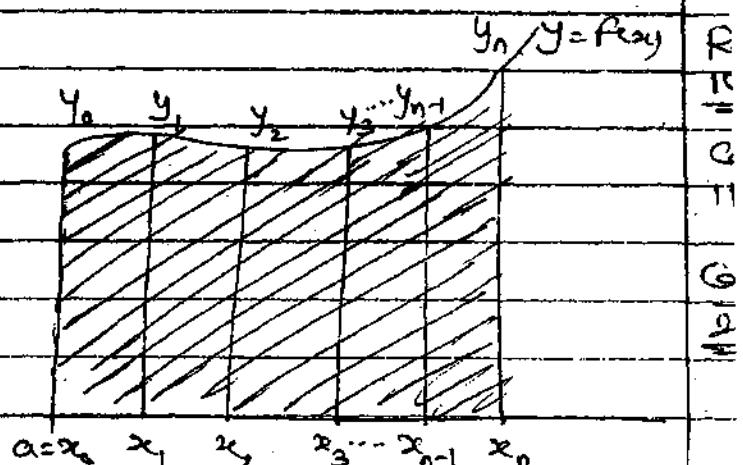
:

$$x_n = x_0 + nh$$

$$\text{i.e } b = x_0 + nh$$

$$\therefore x_n = x_0 + nh$$

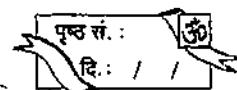
$$b = a + nh$$



$$\therefore n = \frac{b-a}{h}$$

प्रेम सबसे करो, बुरा किसीका न करो।

In Q., Only Simpson rule is mentioned then
take Simpson $\frac{1}{3}$ rd rule



Equation (*) Can be evaluated by using

1) Trapezoidal Rule

$$= \frac{h}{2} [(y_0 + y_n) + 2(y_1 + y_2 + y_3 + \dots + y_{n-1})]$$

2) Simpson $\frac{1}{3}$ Rule

$$= \frac{h}{3} [(y_0 + y_n) + 2(y_2 + y_4 + y_6 + \dots + y_{n-2}) + 4(y_1 + y_3 + y_5 + \dots + y_{n-1})]$$

3) Simpson $\frac{3}{8}$ th Rule

$$= \frac{3h}{8} [(y_0 + y_n) + 2(y_3 + y_6 + y_9 + \dots + y_{n-3}) +$$

$$3(y_1 + y_2 + y_4 + y_5 + y_7 + y_8 + y_{10} + y_{11} + \dots + y_{n-1})]$$

Revises.

10:40 am

Continue

11:15 am.

| Gate Q. | 2e | 0 | 0.25^x_1 | 0.5 | 0.75 | 1.0 |
|-------------|--------|-------|------------|-------|-------|-------|
| <u>2010</u> | $f(x)$ | 1 | 0.9412 | 0.8 | 0.64 | 0.5 |
| | | y_0 | y_1 | y_2 | y_3 | y_4 |

The value of the integrated betw the limits of
1 Using Simpson Rule (if not mentioned then
take $\frac{1}{3}$ rd rule)

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$$\begin{aligned}
 \text{Simpson's } \frac{1}{3} \text{ rule} &= \frac{h}{3} \left[(y_0 + y_n) + 2(y_2 + y_4 + \dots) + \right. \\
 &\quad \left. + (y_1 + y_3 + \dots) \right] \\
 &= \frac{0.25}{3} \left[(y_0 + y_4) + 2(y_2) + 4(y_1 + y_3) \right] \\
 &= \frac{0.25}{3} \left[(1+0.5) + 2(0.8) + 4(0.9412 + 0.64) \right] \\
 &= 0.7854
 \end{aligned}$$

Note: ① Simpson's Rule is applicable if the number of intervals are "EVEN"

② Simpson's 3rd Rule is applicable if the number of intervals are multiples of 3 i.e. $n = 3, 6, 9, 12, \dots$

③ Trapezoidal Rule is applicable for any number of intervals

Q. A 2nd degree polynomial $f(x)$ takes a following values

| | | | |
|-----------------------|---|---|----|
| <u>x</u> | 0 | 1 | 2 |
| $f(x)$ | 1 | 4 | 15 |

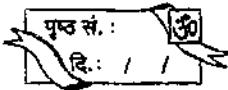
The integration $\int_a^b f(x) dx$ is

$\int_a^b f(x) dx$ is evaluated using

trapezoidal Rule then the error estimation is

- ① $4/3$ ② $-4/3$ ③ $2/3$ ④ $-2/3$

$$\text{Error} = \text{Exact value} - \text{Approximate value}$$



→ Here,

It is mentioned that 2nd degree polynomial.

$$\therefore f(x) = a_0 + a_1 x + a_2 x^2.$$

and it takes the following values — given.

$$\therefore f(0) = 1 \quad \text{i.e. } x=0, f(x)=1.$$

$$\therefore a_0 = 1$$

$$\therefore f(1) = 4$$

$$\therefore a_0 + a_1 + a_2 \cancel{x^2} = 4$$

$$1 + a_1 + a_2 = 4$$

$$a_1 + a_2 = 3. \quad \text{(i)}$$

$$f(2) = 15$$

$$a_0 + a_1 x_2 + a_2 x_2^2 = 15$$

$$2a_1 + 4a_2 = 14$$

$$a_1 + 2a_2 = 7 \quad \text{(ii)}$$

∴ Solve (i) & (ii)

~~$$a_2 =$$~~

$$a_2 = 4$$

$$a_1 = -1$$

$$\therefore a_0 = 1, a_1 = -1, a_2 = 4$$

$$\therefore f(x) = 1 - x + 4x^2.$$

$$\therefore \text{Exact value} = \int_0^2 f(x) dx = \int_0^2 (1 - x + 4x^2) dx$$

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$$= \left[\frac{2x - x^2}{2} + \frac{4x^3}{3} \right]_0^2$$

$$\text{Exact} = \frac{82}{3}$$

Approximate value \approx Trapezoidal Rule value

$$\therefore \text{T.R. value} = h \left[(y_0 + y_n) + 2(y_1 + y_2 + y_3 \dots) \right]$$

$$= \frac{1}{2} \left[(1+15) + 2(4) \right]$$

$$= 12$$

$$\therefore \text{Error} = \text{Exact} - \text{Approximate}$$

$$= \frac{82}{3} - 12$$

$$= -\frac{4}{3}$$

$\frac{2\pi}{8} \cdot \frac{\pi}{4} = 0, \frac{\pi}{4}, \frac{\pi}{2}, \frac{3\pi}{4}, \pi$ पृष्ठ सं.: 15
पृष्ठ 1 / 1
 5 significant digit = upto 5th decimal pt.

ME Q.

GATE
2007

{ Sin x dx is evaluated by T.R. Rule with
 Eight Equal intervals, with 5 Significant
 digits.

- (A) 0.00000 (B) 1.00000 (C) 0.00500 (D) 0.00025

$$\rightarrow \text{Here, } n=8, h = \frac{b-a}{n} = \frac{2\pi-0}{8} = \frac{\pi}{4}.$$

$$h = \frac{\pi}{4}$$

| x | $\sin x$ | y |
|------------------------|--------------|-------|
| $x_0 = 0$ | $\sin 0 = 0$ | y_0 |
| $x_1 = \frac{\pi}{4}$ | 0.70710 | y_1 |
| $x_2 = \frac{\pi}{2}$ | 1 | y_2 |
| $x_3 = \frac{3\pi}{4}$ | 0.70710 | y_3 |
| $x_4 = \pi$ | 0 | y_4 |
| $x_5 = \frac{5\pi}{4}$ | -0.70710 | y_5 |
| $x_6 = \frac{6\pi}{4}$ | -1 | y_6 |
| $x_7 = \frac{7\pi}{4}$ | -0.70710 | y_7 |
| $x_8 = 2\pi$ | 0 | y_8 |

$$\text{T.R. Rule} = \frac{h}{2} [(y_8 + y_0) + 2(y_1 + y_2 + y_3 + y_4 + y_5 + y_6 + y_7)]$$

$$= \frac{\pi}{4} \cdot \frac{1}{2} [(0+0) + 2(0.70710 + 1 + 0.70710 + 0 - 0.70710 - 1 - 0.70710)]$$

$$= 0.00000$$

अश्लील, गंदे विचारवाली पुस्तक पढ़ना जहर पीने से भी ज्यादा खतरनाक है।

| | | | | | | | | |
|------|---|---|------|------|-----|-----|------|-----|
| ME | 2 | 0 | 60 | 120 | 180 | 240 | 300 | 360 |
| DATE | 7 | 0 | 1068 | -323 | 0 | 323 | -355 | 0 |
| 10 | | | | | | | | |

Evaluate $\int_0^{\pi} y dx$ Using Simpson's rule

- (A) 542 (B) 995 (C) 1444 (D) 1986

$$\rightarrow = \frac{h}{3} \left[(y_0 + y_6) + 2(y_3 + y_5) + 4(y_1 + y_2 + y_4 + y_5 + y_6) \right]$$

$$h = \frac{b-a}{n} = \frac{\pi - 0}{6} = \frac{\pi}{6}$$

$$= \frac{\pi}{3} (y_0 +$$

$$y_6 + 2(y_3 + y_5) + 4(y_1 + y_2 + y_4)$$

$$= 995$$

Here $h = 60$.

But the Integration limit is in π term

∴ take $h = \frac{\pi}{3}$

$$\frac{1}{3} \cdot \frac{\pi}{3} \left[(y_0 + y_6) + 2(y_3) + 4(y_1 + y_2 + y_4 + y_5) \right]$$

$$= 995$$

| | | | | |
|---------------|---|-----|-----|-----|
| x | 0 | 1 | 2 | 3 |
| $\frac{1}{x}$ | 1 | 1/2 | 1/3 | 1/4 |

MEQ. The integral $\int_{1}^3 \frac{1}{x} dx$ when evaluated using
2011

GATE 1st rule on two equal intervals each of length 1.

(A) 1.000 (B) 1.111

$$\rightarrow \int_{1}^3 \frac{1}{x} dx \quad \therefore h = \frac{b-a}{n} = \frac{3-1}{2} = 1$$

$$1^{\text{rd}} = h \left[(y_0 + y_1) + \cancel{(y_2)} \right] = \frac{1}{3} \left[\frac{1}{1} + \frac{1}{2} \right] = \frac{1}{3} \cdot \frac{3}{2} = \frac{1}{2}$$

$$= \frac{1}{3} \left[\cancel{0} + \cancel{0.5} \right] \quad 1^{\text{nd}} = \frac{1}{3} \left[\left(1 + \frac{1}{3} \right) + 2(0) + 4(y_1) \right]$$

$$= \frac{1}{3} \left[\frac{4}{3} + 4 \times \frac{1}{2} \right]$$

$$= \frac{1}{3} \left[\frac{4}{3} + 2 \right]$$

$$= \frac{1}{3} \left[\frac{10}{3} \right]$$

$$= \frac{10}{9}$$

$$= 1.11$$

अश्लील, गंदे विचारवाली पुस्तक पढ़ना जहर पीने से भी ज्यादा खतरनाक है।

$$\begin{aligned} \text{Error order T-R rule} &= h^4 \\ \text{Error order Simpson } \frac{1}{3} &= h^4 \\ \text{Error order Simpson } \frac{3}{8} &= h^5 \end{aligned}$$

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End ④

~~25~~ Q
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2403

The minimum number of equal lengths of sub-interval needed to approximate

2

$\int x \cdot e^x dx$ to an accuracy of at least

1

1 x 10⁻⁶ Using T-R file

- a) 1000 · e b) 1000 c) 100 · e d) 100

DEP

$$f(x) = x \cdot e^x$$

$$\text{Note} - \text{Error in T.R. Rule } = - \frac{(b-a)}{12} \cdot h^2 \cdot \max f''(x)$$

$$\textcircled{6} \quad \text{Truncation Error } m = \frac{(b-a)}{12} \cdot h^2 \cdot \max [f''(x)]$$

T.R. Rule

At least means \geq

Here, Error ↑, Accuracy ↓.

Given; Accuracy $\geq 1 \times 10^{-6}$

$$\text{Truncation Error} \leq \frac{1}{3} \times 10^{-6}$$

$$\frac{(b-a)}{12} \cdot h^2 \cdot \max[f''(x)] \leq \frac{1}{3} \times 10^{-6}$$

Here,

$$f(x) = xe^x$$

$$f'(x) = xe^x + e^x$$

$$f''(x) = xe^x + e^x + e^x$$

$$\therefore f''(x) = 2e^x + xe^x$$

— Here, in $f''(x)$, e^x is Increasing function as x increases.
& xe^x is also.

$\therefore f''(x)$ is Increasing function in $(1, 2)$

$$\therefore f''(2) = 2xe^2 + 2xe^2 \\ = 4e^2.$$

Now, $n \geq b-a$

$$\therefore \frac{(2-1)}{12} \cdot \left(\frac{2-1}{n}\right)^2 \max f''(x) \leq \frac{1}{3} \times 10^{-6}$$

$$\frac{1}{12} \times \frac{1}{n^2} \times 4e^2 \leq \frac{1}{3} \times 10^{-6}$$

$$\frac{e^2}{n^2} \leq 10^{-6}$$

$$e^2 \times 10^{-6} \leq n^2$$

$$n^2 \geq e^2 \cdot (10^3)^2$$

$$n \geq e \cdot 10^3$$

$$n \geq 1000 \cdot e$$

$$\therefore n \geq 1000 \cdot e$$

अश्लील, गंदे विचारवाली पुस्तक पढ़ना जहर पीने से भी ज्यादा खतरनाक है।

Note -

$$\textcircled{1} \text{ Error in } \frac{S-1}{3} \text{ rule} = -\frac{(b-a)}{180} \cdot h^4 \cdot \max [f''(x)]$$

— Error order h^4

$$\textcircled{2} \text{ Error in } \frac{S-3}{8} \text{ Rule} = -\frac{3}{80} \cdot h^5 \cdot \max [f'''(x)]$$

— Error order h^5 .

IV. Solutions to differential Equation

Let us consider differential Eq.

$$\frac{dy}{dx} = f(x, y) \quad \text{where} \quad y(x_0) = y_0 \quad \textcircled{*}$$

Eq. $\textcircled{*}$ can be solved by using -

1) Euler's method

- forward Euler's method

- Backward Euler's method

2) Runge - kutta method

- Runge Kutta of 1st order - [Euler method]

- Runge Kutta of 2nd order - [modified Euler method]

Not asked in
GATE yet.

ζ - Runge Kutta of 3rd order

- Runge Kutta of 4th order

* Euler's Method :- (forward)

Euler's Iterative formula for finding solution curve to the eq? * is

$$y_{n+1} = y_n + h \cdot f(x_n, y_n)$$

In particular for $n=0$

$$y_1 = y_0 + h \cdot f(x_0, y_0)$$

Q. find an approximate value of 'y' corresponding to $x=0.2$ & $\frac{dy}{dx} = x+y$, $y=1$, when $x=0$. Using Euler's method

\rightarrow
 make it $f(x, y)$

where $h=0.1$

| x . | y | comment |
|---|--------------------------------------|--|
| $x_0 = 0$ | $y_0 = 1$ | Initial value. |
| $x_1 = x_0 + h$ $= 0 + 0.1$ $= 0.1$ | $y_1 = ?$ $\therefore y_1 = 0.1$ | $y_1 = y_0 + h \cdot f(x_0, y_0)$ $= 1 + 0.1 (x_0 + y_0)$ $= 1 + 0.1 (0 + 1)$ $y_1 = 1.1$ |
| $x_2 = x_1 + h$ $= 0.1 + 0.1$ $= 0.2$ | $y_2 = ?$ $\therefore y_2 = 1.22$ | $y_2 = y_1 + h \cdot f(x_1, y_1)$ $= 1.1 + 0.1 (0.1 + 1.1)$ $= 1.1 + 0.1 (0.2)$ $= 1.22$ |

Q. $\frac{dy}{dx} - y = x$ when $f(0) = 0$.
ATE where $h = 0.1$

Compute $y(0.3)$ using Euler's 1st order method.

→ i.e. Euler's forward method.

Ans. 0.031

| x | y | Comment |
|-------------|---------------|--|
| $x_0 = 0$ | 0 | $y_1 = y_0 + h f(x_0, y_0)$ |
| $x_1 = 0.1$ | $y_1 = 0$ | $y_1 = 0 + 0.1 (0+0)$ |
| $x_2 = 0.2$ | $y_2 = 0.01$ | $y_2 = y_1 + h f(x_1, y_1)$ $y_2 = 0 + 0.1 (0.1+0)$ $= 0.01$ |
| $x_3 = 0.3$ | $y_3 = 0.031$ | $y_3 = y_2 + h f(x_2, y_2)$ $y_3 = 0.01 + 0.1 (0.2+0)$ $= 0.01 + 0.1 \times 0.2$ $= 0.01 + 0.02$ $= 0.031$ |

03/09/

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* Euler's Backward Method :-

$$\text{Let, } \frac{dy}{dx} = f(x, y) \quad (*)$$

$$\text{where, } f(x_0) = y.$$

Euler's Backward iterative formula for solving eqn (*) i.e. $\frac{dy}{dx} = f(x, y)$

$$y_{i+1} = y_i + h f(x_{i+1}, y_{i+1})$$

Here, y_{i+1} is in both L.H.S & R.H.S.

Since, y_{i+1} is defined in function

Therefore, this method is called as Implicit Euler's method.

Q.1 find an appropriate value for $x = 0.2$ using

i) implicit Euler's method where, $\frac{dy}{dx} = x+y$, $y(0) = 1$
where step size $h = 0.1$

ii) Given, $\frac{dy}{dx} = x+y$

$$\therefore y_{i+1} = y_i + h f(x_{i+1}, y_{i+1})$$

$$y_{i+1} = y_i + h \cdot (x_{i+1} + y_{i+1})$$

$$(1-h) \cdot y_{i+1} = y_i + h \cdot x_{i+1}$$

$$y_{i+1} = \frac{y_i + h \cdot x_{i+1}}{(1-h)}$$

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In particular $x=0$ then

$$\text{Ans} \quad f_1 = \frac{y_0 + h \cdot x_1}{(1-h)}$$

\therefore Construct the table for respective values of x with y with x

| x | y | Comment. | G 2 |
|-----|-----|----------|-----|
|-----|-----|----------|-----|

$x_1 = 0$ $y_0 = 1$ Initial Condition

$$y_1 = 0.1$$

$$y_1 = 1.222$$

$$y_1 = y_0 + h \cdot x_1$$

$$(1-h)$$

$$= 1 + 0.1 \times 0.1$$

$$(1 - 0.1)$$

$$y_1 = 1.222$$

$$x_2 = 0.2$$

$$y_2 = 1.38$$

$$y_2 = \frac{y_1 + h \cdot x_2}{(1-h)}$$

$$= 1.222 + 0.1 \times 0.2$$

$$(1 - 0.1)$$

$$= 1.38$$

Note:- Euler's Backward method is more stable than forward method.

The exact solution for differential eq?

$$\frac{dy}{dx} = 2x + y \text{ with } y(0) = 1 \text{ is } y = 2e^x - x - 1$$

$$\text{at } x=1, y=3.44.$$

By observing forward & backward Euler's method you can say that Backward method is converging to required value very quickly.

GATE Q The diff. eqⁿ $\frac{dy}{dx} = 0.25y^2$ is to be solved using backward Euler's method with boundary conditions $y=1$ at $x=0$ and $h=1$ what would be the value of y at $x=1$.

- **(A) 1.33 (B) 1.67 (C) 2.0 (D) 2.33**

→ Here, $\frac{dy}{dx} = 0.25y^2$

$$y_{i+1} = y_i + h f(x_{i+1}, y_{i+1})$$

$$y_{i+1} - 1 [0.25 y_{i+1}^2] = y_i$$

$$\rightarrow 1 \times 0.25 y_{i+1}^2 - y_{i+1} + y_i = 0.$$

→ Here, value of $h=1$, ∴ No need to construct table.

$$0.25 y_{i+1}^2 - y_{i+1} + y_i = 0.$$

Comparing with $ax^2 + bx + c = 0$

∴ roots of Eqⁿ are

$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$x = -b \pm \sqrt{b^2 - 4ac}$$

$$2a$$

$$\therefore y_{i+1} = \frac{-(-1) \pm \sqrt{(-1)^2 - 4(0.25)(y_i)^2}}{2 \times 0.25}$$

$$y_{i+1} = \frac{1 \pm \sqrt{1 - y_i^2}}{0.5}$$

अशलील, यदि विचारवाली पुस्तक पढ़ना जहर पीने से भी ज्यादा खतरनाक है।

Put $i=0$,

$$y_1 = \frac{1 \pm \sqrt{1 - y_0}}{0.5} \quad \text{--- } y_0 = 1. \\ \text{i.e. } y(0) = 1 \text{ --- given}$$

$$\therefore y_1 = \frac{1 \pm \sqrt{1 - 1}}{0.5}$$

$$y_1 = \frac{1}{0.5}$$

$$\boxed{y_1 = 0.2}$$

Runge Kutta Method :-

Given diff. eqⁿ $\frac{dy}{dx} = x - y$ with $y(0) = 0$ then

1996

value of $y(0.1)$ using 2nd order runge kutta

method, with step size $h=0.1$

Runge kutta method of 2nd order Iterative formula for finding solⁿ curve to eqⁿ is

$$y_1 = y_0 + \frac{1}{2} (k_1 + k_2)$$

where

$$k_1 = h f(x_0, y_0)$$

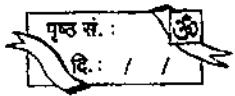
$$k_1 = 0.1 \times (x_0 - y_0) \\ = 0.1 \times (0 - 0)$$

$$\boxed{k_1 = 0}$$

$$k_2 = h f(x_0 + h, y_0 + k_1)$$

$$k_2 = 0.1 [(x_0 + h) - (y_0 + k_1)] \\ = 0.1 [(0 + 0.1) - (0 + 0)]$$

$$\boxed{k_2 = 0.01}$$



$$\therefore y_1 = y_0 + h f(x_0 + h) = y_0 + 0.1 f(0 + 0.1) = y_0 + 0.1 f(0.1)$$

$$y_1 = y_0 + \frac{1}{2} (k_1 + k_2)$$

$$= 0 + \frac{1}{2} (0 + 0.01)$$

$$= \frac{0.01}{2}$$

$$y_1 = 0.005$$

Q. 2. Apply Runge-Kutta method of 4th order where

$$\frac{dy}{dx} = x + y, \quad y=1 \text{ when } x=0, \quad h=0.2$$

R-K Compute $y(0.2)$

Runge-Kutta method of 4th order formula

$$y_1 = y_0 + \frac{1}{6} (k_1 + 2k_2 + 2k_3 + k_4)$$

where

$$\begin{aligned} k_1 &= h \cdot f(x_0, y_0) \\ &= 0.2 (x_0 + y_0) \\ &= 0.2 (0 + 1) \\ k_1 &= 0.2 \end{aligned}$$

$$\begin{aligned} k_2 &= h \cdot f\left(x_0 + \frac{h}{2}, y_0 + \frac{k_1}{2}\right) \\ &= 0.2 \left[0 + \frac{0.2}{2} + 1 + \frac{0.2}{2}\right] \\ k_2 &= 0.24 \end{aligned}$$

$$\begin{aligned} k_3 &= h \cdot f\left(x_0 + \frac{h}{2}, y_0 + \frac{k_2}{2}\right) \\ &= 0.2 \left[0 + \frac{0.2}{2} + 1 + \frac{0.24}{2}\right] \\ k_3 &= 0.244 \end{aligned}$$

Q

$$k_4 = h \cdot f(x_0 + h, y_0 + k_3)$$

$$= 0.2 [x_0 + h + y_0 + k_3]$$

$$= 0.2 [0 + 0.2 + 1 + 0.2 + 4]$$

$$k_4 = 0.2888$$

$$y_1 = y_0 + \frac{1}{6} [k_1 + 2k_2 + 2k_3 + k_4]$$

$$= 1 + \frac{1}{6} (0.2 + 2 \times 0.24 + 2 \times 0.244 + 0.288)$$

$$y_1 = 1.2428$$

Q. 3. Apply Runge Kutta method of 3rd order with 3rd order differential equation $\frac{dy}{dx} = 2x + y$, when $y=1$, $x=0$ & $h=0.2$ then

Q. 4. Compute $y(0.2)$

→ Runge Kutta method of 3rd order iterative formula for finding solution curve to the Eqⁿ is.

$$y_1 = y_0 + \frac{1}{6} (k_1 + 4k_2 + k_3)$$

where,

$$\begin{aligned} k_1 &= h \cdot f(x_0, y_0) \\ &= 0.2 (x_0 + y_0) \\ &= 0.2 (0 + 1) \end{aligned}$$

$$k_1 = 0.2$$

$$\begin{aligned} k_2 &= h \cdot f\left(x_0 + \frac{h}{2}, y_0 + \frac{k_1}{2}\right) \\ &= 0.2 \left[0 + \frac{0.2}{2} + 1 + \frac{0.2}{2}\right] \end{aligned}$$

$$k_2 = 0.24$$

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$$k_3 = h \cdot f(x_0 + h, y_0 + k')$$

where, $k' = 0$

$$k' = h \cdot f(x_0 + h, y_0 + k_1)$$

$$\therefore k' = 0.2 [0 + 0.2 + 1 + 0.2]$$

$$= 0.2 (1.4)$$

$$k' = 0.28$$

$$k_3 = 0.2 [0 + 0.2 + 1 + 0.28]$$

$$k_3 = 0.296$$

$$y_1 = y_0 + \frac{1}{6} [k_1 + 4k_2 + k_3]$$

$$\therefore y_0 = 1 + \frac{1}{6} [0.2 + 4 \times 0.24 + 0.296]$$

$$y_0 = 1.2428$$

Q. 4. The diff. eq. $\frac{dx}{dt} = 1 - x$ is evaluated using Euler's method with step size $h = \Delta T$, where $\Delta T > 0$

~~GATE 2007~~
what is the maximum value of ΔT , To ensure stability in S.O.P?

- (A) 1
- (B) $\frac{\pi}{2}$
- (C) π
- (D) 2π

→ Stable :-

An iterative method is said to be stable if the round off error is remains bounded as $n \rightarrow \infty$, where n is no. of iterations.

The Euler's method formulae

$y_{i+1} = y_i + h \cdot f(x_i, y_i)$ can be written as

$$y_{i+1} = E \cdot y_i + k \quad (*)$$

where,

k = terms which are involved in x or constants.

Eqn (*) is said to be stable, if $|E| < 1$

$$\text{i.e. } -1 < |E| < 1$$

$$\frac{dy}{dt} = 1-x$$

Similarly $\frac{dy}{dx} = \frac{1-y}{x}$

$$\therefore \frac{dy}{dx} = \frac{1-y}{x} = f(x, y)$$

$$\begin{aligned} \therefore y_{i+1} &= y_i + h \cdot f(x_i, y_i) \\ &= y_i + h \cdot \left(\frac{1-y_i}{x_i} \right) \end{aligned}$$

$$y_{i+1} = \left(1 - \frac{h}{x_i} \right) \cdot y_i + \frac{h}{x_i} \quad (I)$$

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E K

Eq (1) is stable if $|1 - \frac{h}{\tau}| < 1$

$$\therefore \left| 1 - \frac{h}{\tau} \right| < 1$$

$$\left| 1 - \frac{\Delta T}{\tau} \right| < 1$$

$$\text{i.e. } -1 < 1 - \frac{\Delta T}{\tau} < 1$$

Subtract 1 throughout to reduce 1 or Cancell
1 from middle term

$$\therefore -1 - 1 < 1 - 1 - \frac{\Delta T}{\tau} < 1 - 1$$

$$\therefore -2 < -\frac{\Delta T}{\tau} < 0$$

$$\therefore -2\tau < -\Delta T < 0$$

$\therefore 2\tau > \Delta T > 0$ ————— Removing Signs and
changing directions
i.e. $0 < \Delta T < 2\tau$ of Equality Signs.

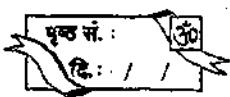
$$\therefore \Delta T < 2\tau$$

$$\text{Ans. } 2\tau$$

Q.1. The min. no. of Equal length subintervals needed
to appropriate $\int e^{2x} dx$ to an accuracy of
Rule

at least $\frac{8}{45} \times 10^{-8}$ Using Simpson's Rule

- अश्लील, गंदे विचारवाली, परस्तक पढ़ना जहर पीने से भी ज्यादा खतरनाक है।
- (A) 200 e (B) 200 (C) 2000 e (D) 2000



$$\rightarrow f(x) = e^{2x} \quad [a, b] = [0, 2]$$

Accuracy atleast means

$$\text{accuracy} \geq \frac{8}{45} \times 10^{-8}$$

Here, if Accuracy ↑ then Error ↓

$$\therefore \text{Error} \leq \frac{8}{45} \times 10^{-8}$$

In Numerical method error is controlled by
Simpson's Truncation method

| | |
|--------------------|------------------------------------|
| (Truncation Error) | $\leq \frac{8}{45} \times 10^{-8}$ |
| Simpson rule | |

$$\left| \frac{b-a}{180} \times h^4 \times \text{Max. } (f''(x)) \right| \leq \frac{8}{45} \times 10^{-8}$$

$$\text{But } h = \frac{b-a}{n}$$

$$\therefore \left| \frac{2-0}{180} \times \left(\frac{2-0}{n}\right)^4 \times \text{Max. } f''(x) \right| \leq \frac{8}{45} \times 10^{-8}$$

$$\text{Now, } f(x) = e^{2x}$$

$$\therefore f'(x) = 2 \cdot e^{2x}$$

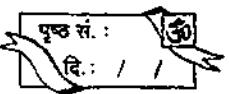
$$f''(x) = 4 \cdot e^{2x}$$

$$f'''(x) = 8 \cdot e^{2x}$$

$$f''''(x) = 16 \cdot e^{2x} = 16 \times e^{2x} = 16 \cdot e^4 - \frac{\text{limit}}{x \rightarrow 0}$$

$$\therefore \left| \frac{2-0}{180} \times \left(\frac{2-0}{n}\right)^4 \times 16 \cdot e^4 \right| \leq \frac{8}{45} \times 10^{-8}$$

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$$\therefore \left(\frac{2}{n} \right)^4 \cdot e^4 \leq \frac{8 \times 10^{-8}}{1}$$

$$\frac{16 \cdot e^4}{n^4} \leq \frac{8 \times 10^{-8}}{1}$$

$$\frac{16 \cdot e^4}{1 \times 10^{-8}} \leq n^4$$

$$|16 \times e^4 \times 10^{+8}| \leq n^4$$

$$\therefore n^4 \geq |16 \times e^4 \times 10^{+8}|$$

$$\therefore n^4 \geq |2^4 \times e^4 \times (10^2)^4|$$

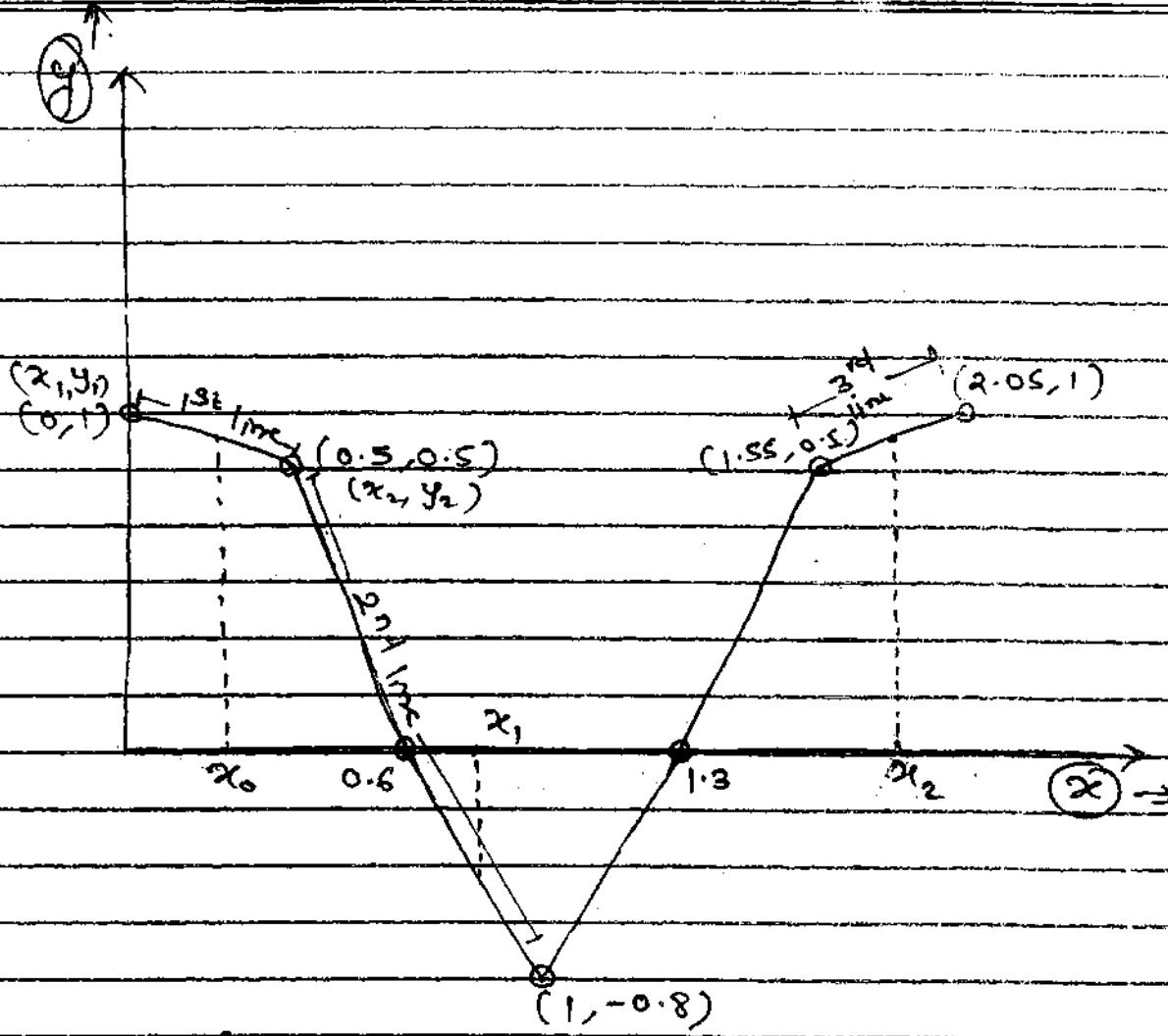
$$\therefore n \geq |2 \times e^4 \times 10^2|$$

$$n \geq 200 e^4 \quad \therefore \text{Ans.}$$

Q.2.

GATE If we use Newton raphson method to find roots $f(x)=0$, Using x_0, x_1 & x_2 respectively as initial guess values & then the roots obtained would be

- (A) 1.3, 0.6, 0.6
- (B) 0.6, 0.6, 1.3
- (C) 1.3, 1.3, 0.6
- (D) 1.3, 0.6, 1.3



→ 1st line for x_0

$$m = \frac{y_2 - y_1}{x_2 - x_1} = \frac{0.5 - 1}{0.5 - 0} = \frac{-0.5}{0.5} = -1$$

$$m = \frac{0.5 - 1}{0.5 - 0} = \frac{-0.5}{0.5} = -1$$

$$m = -1$$

$$\text{Eqn of 1st line} \Rightarrow (y - y_1) = m(x - x_1)$$

$$(y - 1) = -1(x - 0)$$

$$\underline{\underline{x + y = 1}} \Rightarrow \underline{\underline{y = -x + 1}}$$

$$\Rightarrow y = mx + c$$

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$\Rightarrow c \rightarrow 1$
 $\therefore \text{converges to } 1$

On x axis, $y = 0$,

So, $x=1$ which is near to 1.3 than 0.5 on x axis $\therefore \gamma_0$ is converging to 1.3.

- 2nd line for x_1 , (0.5, 0.5) (1, -0.5)

$$m = \frac{y_2 - y_1}{x_2 - x_1}$$

$$m = \frac{-0.8 - 0.5}{1 - 0.5}$$

$$m = -1.8$$

(0.5, 0.5)

(1, -0.5)

Eq of 2nd line $\Rightarrow (y - y_1) = m(x - x_1)$

$$(y - 0.5) = -1.8(x - 0.5)$$

$$y - 0.5 = -1.8x + 0.9$$

$$y + 1.8x = 0.9 + 0.5$$

$$\underline{y + 1.8x = 1.3}$$

$$\Rightarrow y = -1.8x + 1.3$$

$$\Rightarrow y = mx + c$$

$$\Rightarrow c \rightarrow 1.3.$$

\therefore Converges to 1.3.

- 3rd line for x_2 , (1.55, 0.5) (2.05, 1)

$$m = \frac{y_2 - y_1}{x_2 - x_1} = \frac{1 - 0.5}{2.05 - 1.55}$$

$$m = 0$$

\therefore a

Eqn of 3rd line

$$(y - y_1) = m(x - x_1)$$

$$y = 1.5x$$

$$(y - 0.5) = 0(x - 2.5)$$

$$y - 0.5 = 0$$

$$y = 0.5$$

$$\Rightarrow \therefore y = mx + c$$

$$\therefore c \Rightarrow 0.5$$

Converges to 0.6

PROBABILITY AND STATISTICS

Probability, r.v's

r. processes

Veerarajan

McGraw Hills

- (i) Basics.
- (ii) Probability
- (iii) Random Variable / Expectation.
- (iv) Distribution
 - Discrete
 - Continuous.
- (v) Mathematical

STATISTICS

- collection of data.
- Analysis of data
- Interpretation of data.

Definition: According to prof. R.A Fisher , Statistics is defined as a collection of data, analysis of data and interpretation of data.

TYPES OF DATA

- (i) Grouped and Ungrouped.
- (ii) closed and open data .

GROUPED DATA

If data is in the form of class intervals and frequency then the data is known as grouped data, or distributing the frequencies to their corresponding class intervals , then the data is known as Frequency distribution.

UNGROUDED DATA: If the data contains only observations, without any class intervals, then the data is known as ungrouped data or Raw Data.

CLOSED DATA: If the class intervals are in a continuous form without any discontinuity, then the data is known as closed data otherwise open data.

MEAN (AVERAGE)

$$\bar{X}_{UGD} = \frac{\sum_{i=1}^n x_i}{n}$$

$$\bar{X}_{GD} = \frac{\sum_{i=1}^n f_i x_i}{N}$$

n : → no of observations.

x : midpoint, $\frac{UL+LL}{2}$

N : sum of frequencies.

f : frequencies.

MEDIAN

- If n is odd, the middle observation itself is the median.
- If n is even, average between the middle observations provided
 - i) Data is rearranged either in increasing or decreasing order.
 - ii) No. of observations above the middle is equal to the number of observations below.

$$M_d = l + \frac{(N/2 - m)}{f} \times c$$

l :- Lower limit for the ideal class

f :- frequency for the ideal class.

cumulative frequency for the ideal class.

Q) Find the median for the following frequency data.

| C.I | FREQUENCY | CUMULATIVE FREQUENCY |
|-------|-----------|----------------------|
| 0-5 | 3 | 3 |
| 5-10 | 7 | 10 |
| 10-15 | 11 | 21 → Ideal class. |
| 15-20 | 8 | 29 |
| 20-25 | 2 | 31 |

$$N = 31$$

$$\frac{N}{2} = \frac{31}{2} = 15.5$$

$$M_d = 10 + \left(\frac{15.5 - 10}{11} \right) 5$$

$$= 10 + \frac{5.5 \times 5}{11} = 12.5$$

Note: If the first class itself is ideal, the cumulative frequency and frequency are ideal ($m=f$) $\Rightarrow M_d = l$

MODE

The most frequently repeated observation is known as Mode. 1, 2, 3, 4, 5, 2, 3, 11, 14, 2, 3, 21, 2, 16, 21, 3, 19

$$M_o = 2, 3 \rightarrow \text{Bimodal.}$$

For grouped data

$$M_o = 3M_d - 2 \text{ Mean}$$

$$M_o = l + \left(\frac{\Delta_1}{\Delta_1 + \Delta_2} \right) c$$

$$\Delta_1 = f - f_1$$

$$\Delta_2 = f - f_+$$

Q Find the mode for the following frequency distribution.

| C.I | Frequency |
|-------|-----------|
| 0-10 | 11 |
| 10-20 | 14 |
| 20-30 | 17 |
| 30-40 | 8 |
| 40-50 | 5 |
| 50-60 | 3 |

Frequency 17 can be treated as
ideal class [Highest frequency]

$$\Delta_1 = 17 - 14 = 3$$

$$\Delta_2 = 17 - 8 = 9$$

$$M_o = 20 + \left(\frac{3}{12} \right) \times 10 = \frac{45}{2} = \underline{\underline{22.5}}$$

- * If the maximum frequencies are repeated ~~itself~~, first, last and in between, select 'in between' as the ideal class.
- * If the maximum frequencies are repeated in between, select randomly (bimodal).
- * If all the frequencies are equal, Mode is undefined $\left[\frac{0}{0} \text{ form} \right]$
- If ~~the~~ the maximum frequencies are repeated first and last select randomly (bimodal).

MEASURES OF CENTRAL TENDENCIES

Among the 3 measures, Mean, mode and median,
Mean is the best measure.

MEASURES OF DISPERSION

→ Range → Standard Deviation. (SD)

→ Mean Deviation. → Coefficient of Variation. (C.V)

→ Deviation from —

Measures of dispersion helps us to identify the deviation within the data.

RANGE : $\boxed{\text{Max} - \text{Min.}}$
 $\boxed{\text{Greatest value} - \text{Least value}}$

STANDARD DEVIATION

$$\sqrt{\text{Variance}} = (\text{S.D})$$

$$\text{Variance} = (\text{S.D})^2 = \sigma_x^2$$

$$\boxed{\sigma_x^2 = \frac{\sum_{i=1}^n (x_i - \bar{x})^2}{n} = \frac{1}{n} \sum_{i=1}^n x_i^2 - (\bar{x})^2}$$

Variance is the sum of the squares of deviation from mean.

The differences or deviations within the data, is known as Variance.

Note:

- i Lesser Variance is more consistent or more uniform.
- ii Variance will never be negative.
- iii Variance of constant is 0.
- iv Sum of the differences from the mean is always Zero.

$$\boxed{\left[\sum_{i=1}^n (x_i - \bar{x}) \right] = 0}$$

- * If the variances are equal for the different groups, greater mean is more consistent.
- * Sum of the squares of the deviation from the mean should be minimum.

For grouped data

$$\sigma_x^2 = \frac{1}{N} \sum f_i x_i^2 - \left(\frac{1}{N} \sum f_i x_i \right)^2$$

GROUPED DATA

$$\sigma_x^2 = \frac{1}{N} \sum f_i (x_i - \bar{x})^2$$

VARIANCE

RELATION B/W QD / MD / SD

$$6 QD = 5 MD = 4 SD$$

$$QD = \frac{2}{3} \sigma , \quad MD = \frac{4}{5} \sigma$$

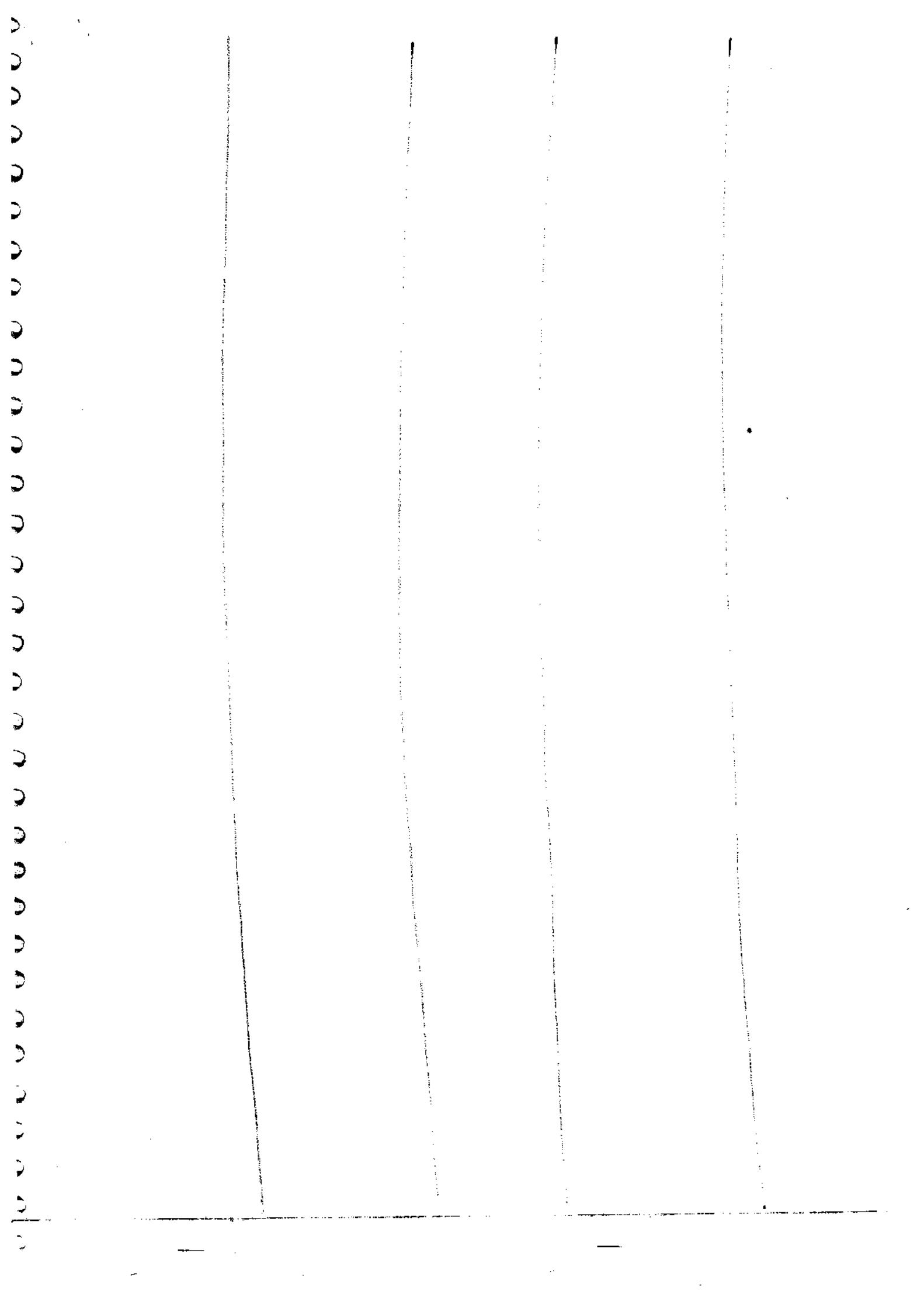
COEFFICIENT OF VARIATION (C.V)

$$C.V = \frac{\text{Standard Deviation}}{\text{Mean}} \times 100$$

$$C.V = \frac{\sigma}{\bar{x}} \times 100$$

Lesser σ implies lesser C.V \Rightarrow Data is more consistent or uniform.

in identifying the consistency within the data, which can be measured by standard deviation



Q. Find mean and variance for the first n natural numbers.

$$\bar{X} = \frac{[1+2+3+\dots+n]}{n}$$

$$= \frac{n(n+1)}{2n}$$

$$\bar{X} = \frac{n+1}{2}$$

$$\sigma_x^2 = \frac{1}{n} \sum x_i^2 - (\bar{X})^2$$

$$\frac{1}{n} \sum_{i=1}^n x_i^2 = \frac{1}{n} [1^2 + 2^2 + 3^2 + \dots + n^2]$$

$$= \frac{1}{n} \left[\frac{n(n+1)(2n+1)}{6} \right]$$

$$\sigma_x^2 = \frac{(n+1)(2n+1)}{6} - \left(\frac{n+1}{2}\right)^2$$

$$= \frac{n+1}{2} \left[\frac{2n+1}{3} - \frac{n+1}{2} \right] = \frac{n+1}{2} \left[\frac{4n+2-3n-3}{6} \right] = \frac{n+1}{2} \cdot \frac{n-1}{6} = \frac{n^2-1}{12}$$

$$\boxed{\bar{X} = \frac{n+1}{2}}$$

$$\boxed{\sigma_x^2 = \frac{n^2-1}{12}}$$

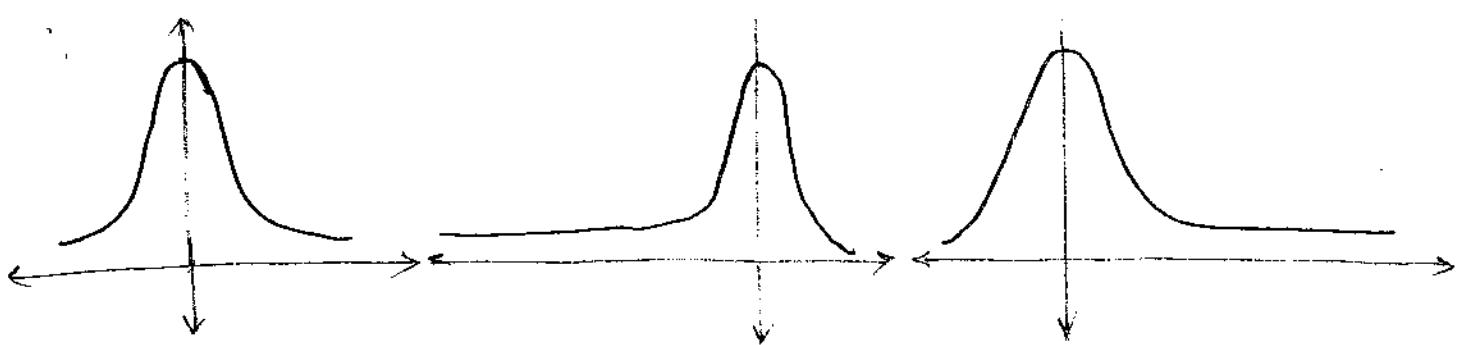
Mean of n
natural numbers

Variance of n
natural numbers.

In statistics, geometrical representations or graph representations purely helps us to determine the behaviour of grouped data.)

SKEWNESS : Opposite of Symmetry.

"Lack of symmetry".



Symmetry.

Negatively skewed.

Positively skewed.

→ To check the skewness of a distribution.

PEARSON'S COEFFICIENT OF SKEWNESS

$$S_{KP} = \frac{\text{Mean} - \text{Mode}}{\sigma}$$

$$S_{KP} = \frac{3(\text{Mean} - \text{Median})}{\sigma}$$

→ practical limit of S_{KP}

$$-3 \leq S_{KP} \leq 3$$

→ For Symmetry $S_{KP}=0$

Symmetry condition

Negative skewness

positive skewness

$$\text{Mode} \geq \text{Median} \geq \text{Mean}$$

$$\text{Mode} > \text{Median} > \text{Mean}$$

$$\text{Mode} < \text{Median} < \text{Mean}$$

PROBABILITY

RANDOM EXPERIMENT: Unpredictable outcomes of an experiment is known as a Random experiment.

e.g.: Tossing a unbiased coin.

Rolling a Die.

Drawing a card from the pack of 52.

SAMPLE SPACE: The collection of all possible outcomes of an experiment (S) is known as a sample space. It is denoted by S .

EVENT: The outcomes of an experiment is known as a event. Mathematically, event is the subset of Sample space.

DEFINITION OF PROBABILITY: The probability of an event is defined as the ratio of b/w the favourable cases to the event and the number of outcomes of an experiment. (The outcomes are mutually exclusive, exhaustive events)

$$\therefore P(E) = \frac{m}{n} \quad \text{where } m \leq n$$

AXIOMATIC APPROACH / PROBABILITY FUNCTION

Ie 1 $P(S) = 1$

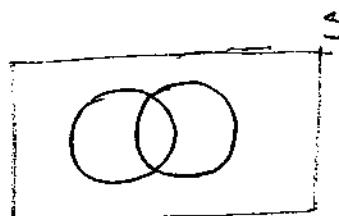
Ie 2 $0 < P(E) \leq 1$

$P(E) = 0 \therefore P(\emptyset) = 0 \rightarrow$ Impossible Event

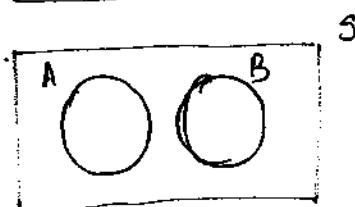
$P(E) = 1 \therefore$

$$\text{Rule 3 : } P\left(\bigcup_{i=1}^n E_i\right) = \sum_{i=1}^n P(E_i)$$

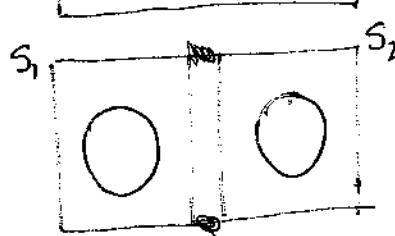
where E_i 's are disjoint/Mutually Exclusive.



Dependent.



Mutually Exclusive Events



Independent

Note: Occurrence of an event does not depends ~~not~~ upon the occurrence of the events in the same sample space, then such events are called Mutually Exclusive event.

→ Let A and B are mutually exclusive event.

$$A \cap B = \emptyset \quad \& \quad P(A \cap B) = 0$$

→ Occurrence of an event does not depends ~~not~~ upon the occurrence of same event in a different sample space, then those events are called Independent events.

→ Mutually Exclusive events never be independent, Independent events never be ~~not~~ equal to Mutually Exclusive.

RESULTS

1. Compliment theorem.

$$P(A^c) = 1 - P(A)$$

$$P(A) = 1 - P(A^c)$$

2. Addition Theorem.

If A, & B are two events (If nothing specified, take it as independent)

$$\underline{P(A \cup B)}$$

$$P(A \cup B) = P(A) + P(B) - P(A \cap B)$$

→ If A and B are mutually exclusive events

$$P(A \cup B) = P(A) + P(B)$$

$$P(A + B) = P(A) + P(B) \quad \text{X} \quad \text{Here it doesn't mean } '+' = \cup$$

If '+' sign is given
it is indirectly shown or it is
sure that A & B are mutually
exclusive. Only mutually
exclusive events can be added.

3. Multiplication Theorem for Dependent Events.

If A & B are two events,

$$P(A \cap B) = P(A) P(B/A)$$

conditional probability

→ Here A must be happened already.

→ Here B must be happened already.

if A, B and C are three events.

$$P(A \cap B \cap C) = P(A) P(B/A) P(C/A \cap B)$$

3. Multiplication Theorem for independent events.

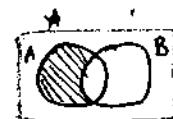
$$P(A \cap B) = P(A) \cdot P(B)$$



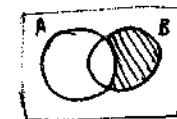
$$P(A \cap B \cap C) = P(A) P(B) P(C)$$

4. If A & B are 2 events.

$$P(A \cap B^c) = P(A) - P(A \cap B) \quad \text{only A}$$



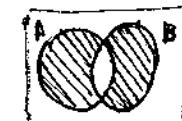
$$P(A^c \cap B) = P(B) - P(A \cap B) \quad \text{only B.}$$



$$P(A^c \cap B^c) = P(\overline{A \cup B}) = 1 - P(A \cup B) \quad \begin{matrix} \text{Neither A nor B} \\ \text{not in A or B} \end{matrix}$$



$$P(A \Delta B) = P(A \cap B^c) + P(A^c \cap B) \quad \text{only once}$$



$$P(A^c/B) = \frac{P(A^c \cap B)}{P(B)}$$

$$= \frac{P(B) - P(A \cap B)}{P(B)} = 1 - \frac{P(A \cap B)}{P(B)} = 1 - \frac{P(A)}{P(B)}$$

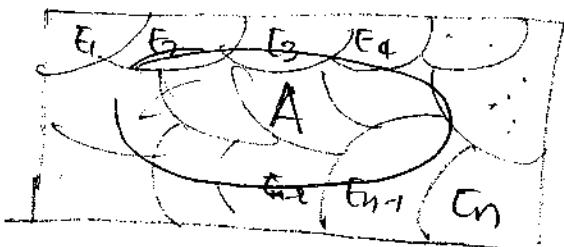
$$P(A/B^c) = \frac{P(A \cap B^c)}{P(B^c)} = \frac{P(A) - P(A \cap B)}{1 - P(B)} \quad (\because P(B) \neq 1)$$

$$P(A^c/B^c) = \frac{P(A^c \cap B^c)}{P(B^c)} = \frac{1 - P(A \cup B)}{1 - P(B)} \quad (\because P(B) \neq 1)$$

Note: If A and B are independent events, the probability of $P(A \cap B^c)$, $P(A^c \cap B)$ and $P(A^c \cap B^c)$ are also independent.

6. BAYE'S THEOREM

If $E_1, E_2, E_3, \dots, E_n$ are the mutually exclusive events ($P(E_i) \neq 0$) such that A is an arbitrary events which is a subset of " $\bigcup_{i=1}^n E_i$ ", then $P(A)$ is



$$P(A) = P(E_1 \cap A) + P(E_2 \cap A) + \dots + P(E_n \cap A)$$

$$P(A) = P(E_1) P(A/E_1) + P(E_2) P(A/E_2) + P(E_3) P(A/E_3) + \dots + P(E_n) P(A/E_n)$$

$$P(A) = \sum_{i=1}^n P(E_i) P(A/E_i)$$

Total probability
of unknown event.

Part (ii) of Bayes's theorem : Reverse probability.

$$P(E_i/A) = \frac{P(E_i \cap A)}{P(A)}$$

$$P(E_i/A) = \frac{P(E_i) P(A/E_i)}{\sum_{i=1}^n P(E_i) P(A/E_i)}$$

Indirectly
A is known.

steps in Bayes's theorem .

- S1 Identify the known events in the data (Mutually exclusive).
- S2 Select the unknown event (It is a part of known events).
- S3 Write the probability of unknown in terms of known.
- S4 Find the total probability of unknown events.
- S5 Compute Reverse probability for known events.

| | | |
|-----------|---------|--------|
| 'Atleast' | Minimum | \geq |
| 'Almost' | Maximum | \leq |
| 'And' | Product | \cap |
| 'OR' | Sum | \cup |

Application of addition theory

Cases with terminologies

- 'either - or'
- 'at least once'
- 'OR'

Application of Multiplication theory

Cases with terminologies

- 'Simultaneously'
- 'One after other'
- 'in sequence'
- 'successively'
- 'One by one'
- 'alternatively'
- 'and'

52 CARD CASE

Total 52 cards

13 Hearts + 13 Diamond + 13 club ~~spade~~ + 13 spade .

Each 13 contains 1, 2, 3, 4, ..., 10, J, Q, K
(1) (2) (3)

i.e., 10 number cards + 3 Face cards

Total no. of face cards = $4 \times 3 = 12$

Here 1 sample space =

Q. 3 coins are tossed at a time. Find the probability of getting at most one head for

$$S = \begin{array}{|c|} \hline \text{HHH} \\ \text{HHT} \\ \text{HTH} \\ \text{HTT} \\ \text{THH} \\ \text{THT} \\ \text{TTH} \\ \text{TTT} \\ \hline \end{array}$$

$$\begin{aligned} P(X \leq 1) &= P(X < 1) + P(X = 1) \\ &= \frac{1}{8} + \frac{3}{8} \\ &= \frac{4}{8} = \underline{\underline{\frac{1}{2}}} \end{aligned}$$

Q. Above data same, find the probability that atleast one tail.

$$\begin{aligned} P(X \geq 1) &= 1 - P(X < 1) \\ &= 1 - \frac{1}{8} \\ &= \underline{\underline{\frac{7}{8}}} \end{aligned}$$

Q. Find the probability that atleast one head and one tails

(atleast 1 head and atleast 1 tail min).

→ whenever "and" is used as the conjunction b/w any number of events, the all the ~~the~~ events must occur simultaneously in all ~~the~~ favourable cases.

$$P = \frac{6}{8} = \underline{\underline{\frac{3}{4}}}$$

Q, Same data . Find the probability that atleast one head and
atmost one ~~one~~ tail.

HHH, HHT, HTT, THH

$$P = \frac{4}{8} = \underline{\underline{\frac{1}{2}}}$$

Q, A player tosses 4 coins Find the probability that atleast 2 heads
and atleast 2 tails .

~~atmost~~

| |
|------|
| HHTT |
| HTTH |
| TTHH |
| THHT |
| THTH |
| HTHT |

$$\frac{4P_4}{2^4 2!} =$$

$$\frac{4!}{0!} = 6$$

$$\frac{4 \times 3 \times 2 \times 1}{4} = 6$$

= 6 = $4C_2$

→ repeated
→ favourable .

| H | No of cases | T |
|--------|-------------|--------|
| $4C_0$ | 1 | $4C_4$ |
| $4C_1$ | 4 | $4C_3$ |
| $4C_2$ | 6 | $4C_2$ |
| $4C_3$ | 4 | $4C_1$ |
| $4C_4$ | 1 | $4C_0$ |

$$nC_r = \frac{n!}{(n-r)! r!}$$

favourable case .

12

~~Atmost~~ Almost 2 head, Almost 2 tails = same = $\frac{6}{16}$

Q. A coin is tossed 6 times. Find the probability that the number of heads are more than the number of tails.

$$2^6 = 64$$

$$\underbrace{{}^6C_0 + {}^6C_1 + {}^6C_2 + {}^6C_3 + {}^6C_4 + {}^6C_5 + {}^6C_6}_{\text{Favourable cases of Head.}}$$

$$P = \frac{{}^6C_6 + {}^6C_5 + {}^6C_4}{64}$$

$$= \frac{1 + \frac{6!}{1 \times 5!} + \frac{6!}{2! 4!}}{64}$$

$$= \frac{1 + 6 + \frac{3 \times 6 \times 5}{2}}{64}$$

$$= \frac{1+6+15}{64}$$

$$= \frac{22}{64}$$

Q. A coin is repeated n times. Find the probability that the head appears in the odd terms.

$${}^nC_1 + {}^nC_3 + {}^nC_5 + \dots + {}^nC_{n-1} = 2^{n-1}$$

$$n_{C_0} + n_{C_2} + n_{C_4} + \dots + n_{C_n} = a^{n-1}$$

$$\text{Req prob} = \frac{2^{n-1}}{2^n} = \underline{\underline{\frac{1}{2}}}$$

two times.

1) Two dice are rolled, Find the probability that for getting a sum 7

- (i) atleast once
 - (ii) only once
 - (iii) twice .

$$\text{(i)} \quad \underbrace{1+6, 5+2, 4+3}_{3 \times 2 = 6}$$

$$\textcircled{6} \quad \textcircled{7} \quad \frac{5}{6} \times \frac{1}{6} = \frac{1}{6}$$

$$\text{sum in first : } P(A) = \frac{6}{36} = \frac{1}{6} \quad P(A^c) = \frac{5}{6}$$

$$\text{Answer: } P(B) = 6/36 = \frac{1}{6} \quad P(B^c) = \frac{5}{6}.$$

$$\begin{aligned}
 P(\text{at least one } c) &= P(A \cup B) = 1 - P(A^c \cap B^c) = 1 - P(A^c)P(B^c) \\
 &= 1 - \frac{5}{6} \times \frac{5}{6} \\
 &= 1 - \frac{25}{36}
 \end{aligned}$$

$P(\text{only once})$

$$= P(A \cap B^c) + P(B \cap A^c)$$

$$= P(A) P(B^c) + P(B) P(A^c)$$

$$= \frac{1}{6} \times \frac{5}{6} + \frac{5}{6} \times \frac{1}{6}$$

$$= \frac{10}{36}$$

$$P(\text{twice}) = P(A \cap B) = P(A) P(B)$$

$$= \frac{1}{6} \times \frac{1}{6} = \underline{\underline{\frac{1}{36}}}$$

Q. Two dice are rolled. Find the probability that the first die should contain a prime number or a total of eight.

~~$(6,2)(2,6), (5,3)(3,5), (4,4)$~~



② Prime 2, 3, 5,

$$2 \leftarrow (2,1) (2,2) \dots (2,6)$$

$$3 \leftarrow (3,1) (3,2) \dots (3,6)$$

$$5 \leftarrow (5,1) \dots (5,6)$$

$$6 \times 3 = 18 \quad P = \frac{18}{36}$$

Total 8

$(6,2)(2,6)(5,3)(3,5)(4,4)$

$$P = \frac{5}{36}$$

But A & B are \varnothing dependent.

Hence to find $P(A \cap B)$ =

i.e., Prime in first & sum 8

$$(5,3) (3,5), (2,6) \rightarrow 3 \text{ cases} \quad P(A \cap B) = \frac{3}{36}$$

We need to find

$$P(A \cup B) = P(A) + P(B) - P(A \cap B)$$

$$= \frac{18}{36} + \frac{5}{36} - \frac{3}{36}$$

$$= \underline{\underline{\frac{20}{36}}}$$

Two dice are rolled. Find the probability neither sum 9 nor sum 11

~~P~~ $P(\text{neither sum 9, nor 11})$

$$= 1 - P(\text{sum 9, and sum 11})$$

④

$$\text{sum 9} \rightarrow (5,4) (4,5) (6,3) (3,6) \rightarrow \frac{4}{36}$$

$$\text{sum 11} \rightarrow (5,6) (6,5) \rightarrow \frac{2}{36}$$

$$P(9^c \cap 11^c) = 1 - P(9 \cup 11)$$

$$= 1 - \left(\frac{4}{36} + \frac{2}{36} \right) = \frac{5}{36} = \frac{30}{36}$$

Q. A ~~4x4~~ matrix of order 2, with the elements 0, (and) or 1. Find the probability that the chosen det is non zero

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \quad S = \underline{\underline{2^4 = 16}}$$

$$\Delta \neq ad - bc$$

\therefore case $\Delta = 1$ $[a = d = 1 \text{ atleast one of } b \& c \text{ is } \neq 0]$

$$\Delta = 1 \quad \left| \begin{array}{|c|c|} \hline 1 & 0 \\ \hline 0 & 1 \\ \hline \end{array} \right| \quad \left| \begin{array}{|c|c|} \hline 1 & 1 \\ \hline 0 & 1 \\ \hline \end{array} \right| \quad \left| \begin{array}{|c|c|} \hline 1 & 0 \\ \hline 1 & 1 \\ \hline \end{array} \right| \quad \text{B1}$$

$= \underline{\underline{3 \text{ cases}}}$

(case II) $\Delta = -1$

$$ad = 0 \quad bc = 1$$

$[b = c = 1, \text{ atleast one of } ad \& d \neq 0 \text{ is } \neq 0]$

$$\left| \begin{array}{|c|c|} \hline 0 & 1 \\ \hline 1 & 0 \\ \hline \end{array} \right| \quad \left| \begin{array}{|c|c|} \hline 0 & 1 \\ \hline 1 & 1 \\ \hline \end{array} \right| \quad \left| \begin{array}{|c|c|} \hline 1 & 1 \\ \hline 1 & 0 \\ \hline \end{array} \right| \quad \Rightarrow 3 \text{ cases.}$$

$$P(\text{non zero } \Delta) = 3/16 + 3/16 = \underline{\underline{6/16}}$$

$$P(\text{non neg } \Delta) = 1 - 3/16 = \underline{\underline{13/16}}$$

$$P(\text{zero } \Delta) = 1 - \underline{\underline{6/16}} = \underline{\underline{10/16}}$$

Q) 4 cards are drawn ~~from~~ at random from a pack of 52 cards. Find the probability that

- All the 4 cards are drawn from same suit.
- No two cards are drawn from the same suit.

(i) $\text{S} = 52 C_4$

$$\frac{\cancel{4 \times} 13 C_4}{52 C_4} \quad (\text{at a time})$$

(ii) $\frac{13 C_1 \cdot 13 C_1 \cdot 13 C_1 \cdot 13 C_1}{52 C_4} = \frac{(13)^2}{52 C_4}$ (one by one).

~~+ 3 x 1~~

3) A card is drawn from a pack of 52 cards. Find the probability that ~~neither a diamond nor a face card~~.

- neither a diamond nor a face.
- neither a 10 nor a king

$$P(D^c \cap F_c^c) = 1 - P(D \cup F)$$

$$P(D) = 13/52$$

$$P(F) = 12/52$$

$$P(D \cup F) = 1 - \left[\frac{13}{52} + \frac{12}{52} - \frac{3}{52} \right] = \frac{30}{52} \quad \text{intersection}$$

$$(ii) P(10) = \frac{4}{52}$$

$$P(K) = \frac{4}{52}$$

$$P(10^c \cap K^c) = 1 - P(10 \cup K)$$

$$= 1 - \frac{4}{52} - \frac{4}{52}$$

$$= 1 - \frac{8}{52}$$

$$= \underline{\underline{\frac{44}{52}}}$$

10 & King
are
mutually
exclusive.

α , A and B are the two players rolling a die on the condition that one who gets the two first winning the game.

If A starts the game, what are the winning chances of player A, B.

\oplus ~~5~~

$$\frac{1}{6} + \frac{5}{6} \times \frac{1}{6} = \frac{5}{6} \times \frac{1}{6}$$

$$P(\alpha) = 1/6 \quad P(\alpha^c) = 5/6$$

Let getting α is P not q by q .

$$P(\text{win } B) = \cancel{qP} qP + q^3P + q^5P + \dots = qP + q^3P +$$

$$= P \left[q + q^3 + q^5 + \dots \right] = Pq \left[1 + q^2 + q^4 + \dots \right]$$

$$= (q/p) \times \frac{1}{(1-q^2)}$$

$$= \frac{1}{6} \times \frac{5}{6} \times \frac{1}{1 - \frac{25}{36}}$$

$$= \underline{\underline{\frac{5}{11}}}$$

$$P(\text{win A}) = p + q^2 p + q^4 p + \dots$$

$$= P \left[1 + q^2 + q^4 + \dots \right]$$

$$= P \times \frac{1}{1 - q^2} = \frac{1}{6} \times \frac{1}{1 - \frac{25}{36}}$$

$$= \frac{1}{6} \times \frac{36}{11}$$

$$= \underline{\underline{\frac{6}{11}}}$$

A, B, C are the 3 players in the order. Tossing the same coin on the condition that one who gets the head first winning game. If A starts the game, what are the winning chances of player C in 3rd trial.

~~$$P(\text{win C in 3rd trial}) = \left(\frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} \right) \times q^3 q^3 q^2 p$$~~

$$\begin{aligned} P(H) &= \frac{1}{2} & P(T) &= \frac{1}{2} \\ \rightarrow P &= \frac{1}{2} & (2) &= \left(\frac{1}{2} \right)^3 \left(\frac{1}{2} \right)^3 \times \left(\frac{1}{2} \right)^2 \times \frac{1}{2} \\ &= \frac{1}{8} \times \frac{1}{8} \times \frac{1}{8} \times \frac{1}{2} & (3) &= \frac{1}{512} \end{aligned}$$

Q) A number is chosen at random from 100 numbers,
 $\{00, 01, 02, 03, \dots, 99\}$

Let x denote the sum of the digits on the number, and y denotes product of the digits on the number. Find the probability that

$$P\left(\frac{x=9}{y=0}\right) = \frac{P(x=9 \wedge y=0)}{P(y=0)}$$

0 0 - 9

$$P(y=0) = \frac{2/100}{19/100} = \frac{2}{19}$$

~~9~~
+
~~10~~ → 0.

Q, 60% of the employees of the company are college graduates.

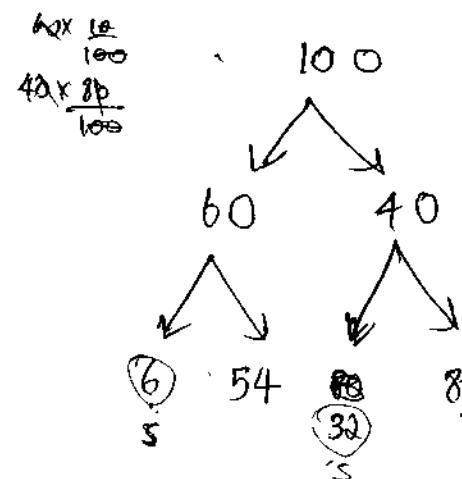
of these, 10% are in the sales department. of the employees who did not graduate from the college are 80% in the sales department. A person is selected at random. Find the probability that

(i) The person is in the sales department.

(ii) Neither in the sales department nor a college graduate.

(i) $\frac{38}{100}$ (pt can go)

(ii) $\frac{8}{100}$



$$\begin{aligned}
 \text{(i)} \quad P(\text{SD}) &= P(\text{CG} \cap \text{SD}) + P(\text{CG}^c \cap \text{SD}) \\
 &= P(\text{CG}) \cdot P(\text{SD}/\text{CG}) + P(\text{CG}^c) \cdot P(\text{SD}/\text{CG}^c) \\
 &= 0.6 \times 0.1 + 0.4 \times 0.8
 \end{aligned}$$

$$P(\text{SD}) = \underline{\underline{0.38}}$$

$$\begin{aligned}
 \text{(ii)} \quad P(\text{CG}^c \cap \text{SD}^c) &= 1 - P(\text{CG} \cup \text{SD}) \\
 &= 1 - [P(\text{CG}) + P(\text{SD}) - P(\text{CG} \cap \text{SD})] \\
 &= 1 - [P(\text{CG}) + P(\text{SD}) - P(\text{CG}) \cdot P(\text{SD}/\text{CG})] \\
 &= 1 - [0.6 + 0.38 - 0.6 \times 0.1] \\
 &= 1 - 0.92 \\
 &= \underline{\underline{0.08}} \quad \text{D}
 \end{aligned}$$

Q In answering a multiple choice qn, a student either knows the answer or guess the answer. Let P be the probability that student knowing the answer to the qn and $(1-P)$ be the probability that guessing the ans to a qn. Assume that if the student guess the answer to the question will be correct, with probability $\frac{1}{5}$. What is the conditional probability that if the student knew the ans to a qn, given that, he answered correctly?

$$P(K) = P$$

$$P(G) = 1-P$$

| Known | Guess |
|-------|----------|
| | correct. |

E: answering correctly.

$$P(K) = P$$

$$P(G) = 1 - P$$

$$P(E) = P(E \cap K) + P(E \cap G)$$

$$P(E) = P(E \cap K) + \cancel{P(G)} \cancel{P(E/G)} \rightarrow P(E \cap G)$$

$$P(E) = P(K) P(E/K) + P(G) P(E/G)$$

$$= P P(E/K) + (1-P) \cancel{P_G}$$

$$= P \times 1 + (1-P) \cancel{P_G}$$

$$= P + \cancel{P_G} - P_G$$

$$P(E) = \frac{4P+1}{5}$$

the probability

$$P(K/E) = \frac{P(K \cap E)}{P(E)}$$

$$= \frac{\cancel{P_E}}{\frac{4P+1}{5}}$$

In Qn. Find
known even \rightarrow correct ans.
unknown \rightarrow knowing ans.
Hence go for
Reverse probability.

Q. There are 3 coins. Of these two are unbiased. One is a biased coin with 2 heads. A coin is drawn at random and tossed two times. It appears head on both the ~~sides~~ times. Find the probability that it is from the biased coin.

~~U~~
B

$$\begin{matrix} UB \\ 2 \end{matrix} \quad \begin{matrix} B \\ 1 \end{matrix} = 3$$

$$P(UB) = \frac{2}{3} \quad P(B) = \frac{1}{3}$$

E: Getting a head, ^{two times.} is an unknown event.

$$P(E) = P(E \cap UB) + P(E \cap B)$$

$$= \cancel{P(DE)} \cdot \cancel{P(UB/E)} + \cancel{P(\cdot)}$$

$$= P(UB) P(E/UB) + P(B) P(E/B)$$

$$P(E/B) = 1$$

$$= \frac{2}{3} \times \frac{1}{4} + \frac{1}{3} \times 1$$

$$P(E/UB) = \frac{1}{2} \times \frac{1}{2} \\ = \frac{1}{4}$$

$$= \frac{1}{6} + \frac{1}{3}$$

$$P(E) = \underline{\underline{\frac{3}{6}}}$$

$$\text{Ans: } P(B/E) = \frac{P(E \cap B)}{P(E)}$$

$$= \frac{P(B) P(E/B)}{P(E)} = \frac{\frac{1}{3} \times 1}{\frac{1}{2}} = \frac{\frac{1}{3}}{\frac{1}{2}} = \frac{2}{3}$$

$$\text{Ans: } \frac{2}{3}$$

player A speaking truth 4 out of 7 times, A card is drawn from the pack of 52 cards. He reports that there is a diamond what is the probability that actually there was a diamond.

T: Player telling truth

$$P(A) = \frac{4}{7}$$

Lie probability

$$P(T) = \frac{4}{7}$$

$$P(L) = \frac{3}{7}$$

D: Reporting a diamond.

$$P(D) = P(T \wedge D) + P(L \wedge D)$$

$$= P(T) P(D|T) + P(L) P(D|L)$$

$$= \frac{4}{7} \times \cancel{\frac{1}{4}} \quad + \quad \frac{3}{7} \times \frac{3}{4}$$

$$= \frac{4+9}{28}$$

$$= \frac{13}{28}$$

$$P(D|T) = \frac{13}{52}$$

$$P(D|L) = \frac{39}{52}$$

~~$P(D|T) = P(T)$~~

$$P(T|D) = \frac{P(T \wedge D)}{P(D)}$$

$$= \frac{\frac{4}{7} \times \cancel{\frac{1}{4}}}{\frac{13}{28}} = \frac{4}{13}$$

Q A letter is known to ^{have} come from either Tatanagar or CALCUTTA ~~or~~. On the envelope, the just two consecutive letters visible. 'TA' are found. Find the probability that the letter has come from Tatanagar.

(3)

$$P(T) = \gamma_2 : P(C) = \gamma_7$$

E: Getting a TA consider as single letter.

$$P(E/T) = 2/8$$

$$P(E/C) = \gamma_7$$

$$P(E) = P(E \cap T) + P(C \cap E)$$

$$= P(T) P(E/T) + P(C) P(E/C)$$

$$= \gamma_2 \times 2/8 + \gamma_7 \times \gamma_7$$

$$= 11/56$$

$$\text{Qn } P(T/E) = \frac{P(T \cap E)}{P(E)} = \frac{\gamma_2 \times 2/8}{11/56} = \frac{7}{11}$$

Given only 1 letter is visible (which is a combination of 2 consecutive). Not more than 1 is visible.

1 2 3 4 5 6 7 8
T A T A N A G A R

CALCUTTA
1 2 3 4 5 6 7

Hence can take either one of 'TA' in TATANAGAR.

No need of confusion.

There are 3 bags A, B, C, with balls Blue, Red, and Green in the form of ~~1, 2, 3~~

~~B R G~~

| | | B | R | G | colour |
|---|---|---|---|---|--------|
| A | 1 | 2 | 3 | | |
| B | 2 | 3 | 1 | | |
| C | 3 | 1 | 2 | | |

A bag is drawn at random, and two balls are taken from it. They are found to be one blue and one red. Find the probability that the selected balls are from bag C.

$$P(A) = P(B) = P(C) = \frac{1}{3}$$

E : Getting one blue and one red.

$$P(E) = P(E \cap A) + P(E \cap B) + P(E \cap C)$$

$$= P(A) P(E/A) + P(B) P(E/B) + P(C) P(E/C)$$

$$= \frac{1}{3} \left[\frac{2}{15} + \frac{6}{15} + \frac{3}{15} \right] \quad P(E/A) = \frac{C_1 \times C_2}{6C_2} = \frac{2}{15}$$

$$= \frac{1}{3} \left[\frac{11}{15} \right]$$

$$= \frac{11}{45}$$

$$\text{Qn: } P(C/E) = \frac{P(C \cap E)}{P(E)}$$

$$= \frac{\frac{1}{3} \times \frac{3}{15}}{\frac{11}{45}} = \frac{3}{11}$$

Also others can be found out -

$$P(B/E) = \frac{Y_3 \times 6/15}{11/45} = \underline{\underline{\frac{6}{11}}}$$

$$P(A/E) = \frac{Y_3 \times 2/15}{11/45} = \underline{\underline{\frac{2}{11}}}$$

LEAP YEAR CONCEPT

LEAP YEAR

366 Days

52 weeks + 2 days

S-M
M-T
T-W
W-T
T-F
F-S
S-S

NON LEAP YEAR

365 Days

52 weeks + 1 day

$$P(53 \text{ sundays}) = \frac{1}{7}$$

$$P(53 \text{ sunday}) = \frac{2}{7}$$

Two dice.

$$P(\text{diff zero}) = P(\text{Doublets}) = \frac{6}{36} = \underline{\underline{\frac{1}{6}}}$$

$$P(1,1)$$

$$P(2,2)$$

⋮

$$P(6,6)$$

Three dice

$$P(\text{Triplet}) = \frac{6}{6^3} = \underline{\underline{\frac{1}{36}}}$$

$$(1,1,1)$$

$$(2,2,2)$$

⋮

$$(6,6,6)$$

Consider now

$$\{1, 2, 3, \dots, 200\}$$

$$P(\text{div 6 OR div by 8})$$

$$P(\text{div 6}) = \frac{33}{200}$$

$$P(\text{div 8}) = \frac{25}{200}$$

$$P(\text{div 6 AND div 8}) = \text{LCM}(6,8)$$

$$= 1 - P(\text{not div by 12}) = \frac{8}{200}$$

$$\begin{aligned}
 \text{Hence } P(\text{div by 6 OR div by 8}) &= P(6) + P(8) - P(6 \cap 8) \\
 &= \cancel{\frac{33}{200}} + \frac{25}{200} - \frac{8}{200} \\
 &= \frac{50}{200} = \underline{\underline{\frac{1}{4}}}
 \end{aligned}$$

RANDOM VARIABLE AND EXPECTATION

(R.V)

RANDOM VARIABLE : Connecting the outcomes of an experiment with real values is known as Random Variables.

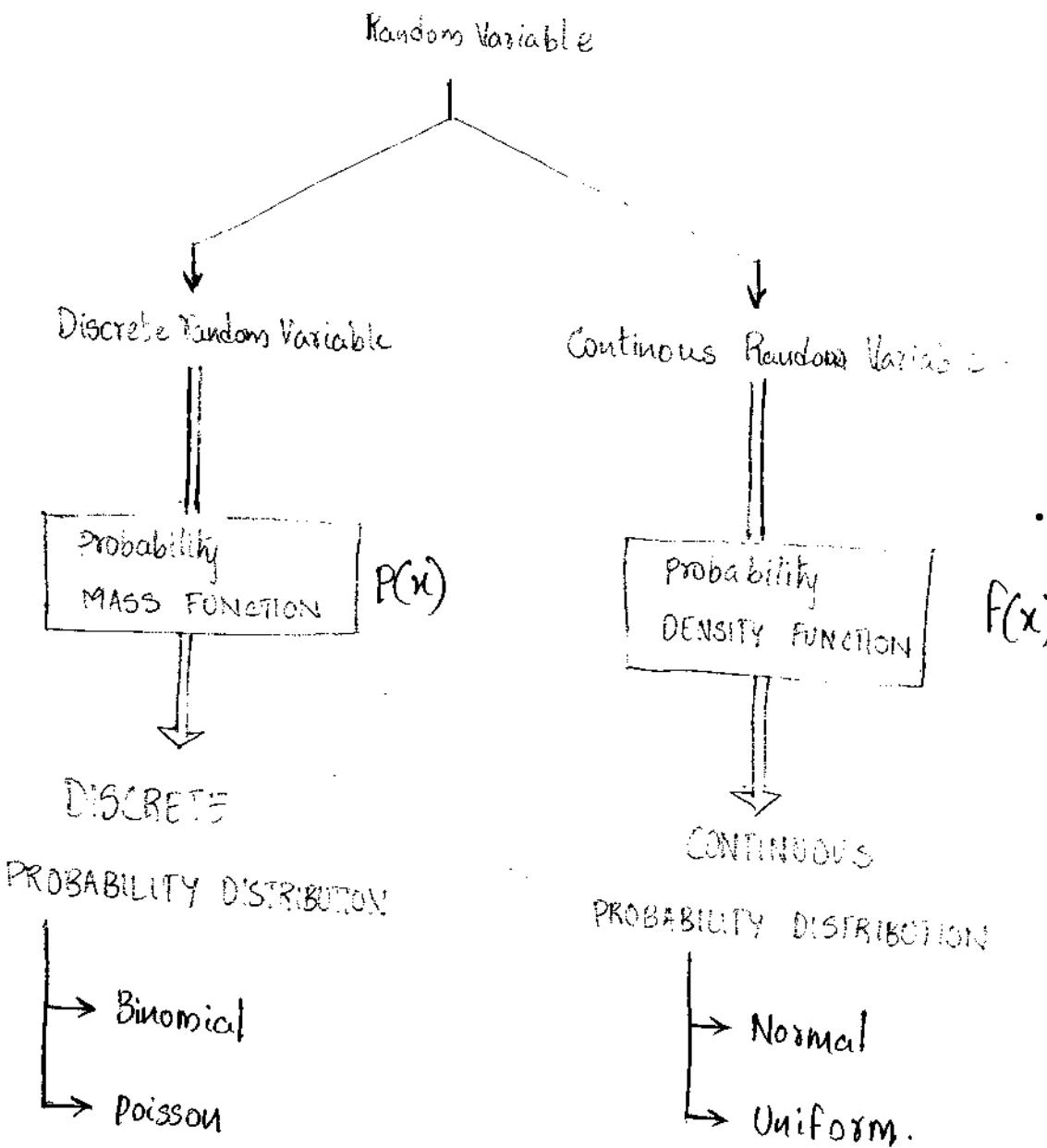
(It is a rule to assign Real numbers to the outcome
is known as ^{1D}Random Variable)

The corresponding data is known as univariate data.

2-D RANDOM VARIABLE : Connecting 2 outcomes at a time to the one real value provided those two outcomes are drawn from same Sample space.
The corresponding data is known as Bivariate data.

→ Similarly the concept of n-D Random variable which corresponds to an n-tuple.

TYPES OF RANDOM VARIABLE



Probability Mass Function $\rightarrow P(x)$

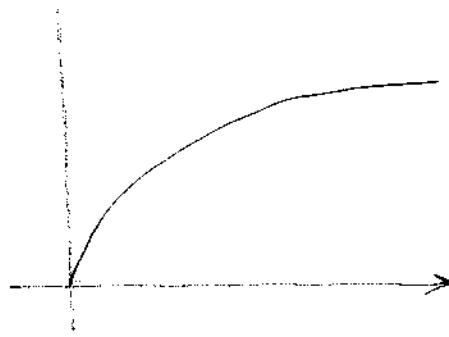
Probability Density Function $\rightarrow f(n)$

Distributive Function/Cumulative Function $\rightarrow F(n)$

$$\frac{dF(n)}{dn} = f(n),$$

$$\Phi \quad F(n) = \int_{-\infty}^n P(u) du.$$

Distribution function graph will always be a non decreasing function.



RANDOM PROCESS : Random variable along with time domain.

EXPECTATION

It is actually the mean in the probability ~~function~~ distribution.

$$E(x) = \sum_{n=0}^N x \cdot P(n) \quad \text{where } n \text{ is Discrete R.V}$$

$$E(x) = \int_{-\infty}^{\infty} x \cdot f(n) dn \quad \text{where } n \text{ is Continuous R.V}$$

The above relations are derived from Frequency distribution where freq is replaced by probability

$$\bar{x} = \frac{\sum f \cdot x}{\sum f}$$

$$\bar{x} = \frac{\sum P(n) \cdot x}{\sum P(n)}$$

But $\sum P(n) = 1$ \cancel{P}

$$\therefore \bar{x} = \sum x \cdot P(n) = E(n)$$

(ii) VARIANCE

From frequency distribution, the variance is given by .

$$\sigma^2 = \frac{1}{N} \sum f_i x_i^2 - \left(\frac{1}{N} \sum f_i x_i \right)^2$$

$$\frac{1}{N} \sum f_i x_i = E(x)$$

$$\frac{1}{N} \sum f_i x_i^2 = E(x^2)$$

In general

$$\boxed{\frac{1}{N} \sum f_i x^2 = E(x^2)}$$

In probability distribution,

$$V(x) = E(x^2) - (E(x))^2$$

$$V(x) = E(x - (E(x))^2)$$

$$V(x) = \sum x^2 p(x) - \left(\sum x \cdot p(x) \right)^2$$

where x is a discrete r.v

$$V(x) = \int_{-\infty}^{\infty} x^2 f(x) dx - \left(\int x f(x) dx \right)^2$$

where x is a continuous r.v.

PROPERTIES OF EXPECTATION

(i) If X is a RV and ' a ' is a constant,

$$\text{then } E(ax) = aE(x)$$

If X and Y are RV's.

(ii) Then $E(X+Y) = E(X) + E(Y)$

$$E(X-Y) = E(X) - E(Y)$$

(iii) If X & Y are RV's

$$E(X \cdot Y) = E(X) \cdot E(Y/X)$$

$$= E(Y) \cdot E(X/Y)$$

(iv) If X & Y are independent random variables,

$$E(X \cdot Y) = E(X) \cdot E(Y)$$

(v) If $Y = aX + b$, where a & b are constants,

$$\text{Then } E(Y) = aE(X) + b$$

(vi) ie, $E[\text{constant}] = \text{constant}$

ie, Mean of constant = That constant itself.

(vii) $E[E[E(X)]] = \text{constant} = E(X)$

PROPERTIES OF VARIANCE

i) If X is a r.v and 'a' is a constant,

$$V(ax) = a^2 V(x)$$

$$V(-y) = (-1)^2 V(y) = V(y)$$

If X and y are independent r.v's.

$$V(x+y) = V(x) + V(y)$$

$$V(x-y) = V(x) + V(-y)$$

$$\Rightarrow V(x-y) = V(x) + V(y)$$

$$\Rightarrow \boxed{V(x \pm y) = V(x) + V(y)}$$

If $a & b$ are constants, $X & Y$ are independent r.v's,

$$V(ax - by) = a^2 V(x) + b^2 V(y)$$

$$V(\gamma_a - \gamma_b) = \gamma_a^2 V(x) + \gamma_b^2 V(y)$$

f $y = ax + b$, where $a & b$ are constants,

$$V(y) = V(ax + b)$$

$$= V(ax) + V(b)$$

$$V(y) = a^2 V(x) + 0$$

i.e. $\underline{\underline{V\{ \text{constant} \}} = 0}}$

If X and Y are two random variables (Dependant r.v's).

$$V(X+Y) = V(X) + V(Y) + 2 \text{Cov}(X, Y)$$

where $\text{Cov}(X, Y) \rightarrow$ Covariance of X, Y

where

$$\text{Cov}(X, Y) = E(X \cdot Y) - E(X) \cdot E(Y)$$

$V(X, Y)$ is
meaningless

$$\rightarrow \text{Cov}(X, X) = V(X)$$

$$\rightarrow \text{Cov}(a, b) = E(ab) - E(a)E(b)$$

$$= ab - a \cdot b$$

$$= \underline{\underline{0}}$$

$$\boxed{\text{Cov}[a, b] = 0} \text{ where } a \text{ and } b \text{ are constants.}$$

1 If X and Y are independent r.v, then covariance of $X, Y = 0$

$$\text{Cov}(X, Y) = 0 \quad X, Y \text{ are independent}$$

But Converse of the statement is not true.

2 Variance and covariance are independent of change of origin, dependent of change of scale.

$$\mathbb{E}[ax+b] = \underline{a^2 V[x]}$$

Mean [Expectation] dependent of origin as well as
Dependent of change of scale.

$$\mathbb{E}[ax+b] = a^2 V[x] + b$$

SKEWNESS

$$\boxed{\beta_1 = \frac{\mu_3}{\mu_2^{\frac{3}{2}}}}$$

$\mu_3 \rightarrow 3^{\text{rd}}$ central moment.

$\mu_2 \rightarrow \text{Variance}$.

Skewness is defined in terms of ' μ_3 '

$$\gamma = \sqrt{\beta_1} \quad \gamma \text{ is also a measure of skewness.}$$

ie : If $\mu_3 = 0 \Rightarrow \beta_1 = 0$ Then the curve is SYMMETRY

If $\mu_3 \rightarrow -ve \Rightarrow$ Then the Curve is NEGATIVELY SKEWED

If $\mu_3 \rightarrow +ve \Rightarrow$ Then the curve is POSITIVELY SKEWED

Q Find the expectation of the number on a die when it is ~~thrown~~.

$$E(X) = \sum_{n=0}^{\infty} x p(x)$$

$$= 1 \times \frac{1}{6} + 2 \times \frac{1}{6} + 3 \times \frac{1}{6} + 4 \times \frac{1}{6} + 5 \times \frac{1}{6} + 6 \times \frac{1}{6}$$

$$= \frac{1}{6} [1+2+3+4+5+6]$$

$$= \frac{1}{6} \left[\frac{3(6+1)}{2} \right]$$

$$= \underline{\underline{2.5}} \quad \underline{\underline{3.5}}$$

| | | | | | | |
|--------|---------------|---------------|---------------|---------------|---------------|---------------|
| x | 1 | 2 | 3 | 4 | 5 | 6 |
| $y.v$ | | | | | | |
| $p(x)$ | $\frac{1}{6}$ | $\frac{1}{6}$ | $\frac{1}{6}$ | $\frac{1}{6}$ | $\frac{1}{6}$ | $\frac{1}{6}$ |

Q Find the variance for the single die

$$V(X) = E(X^2) - (E(X))^2$$

$$E(X^2) = \sum_{n=0}^{\infty} x^2 p(n)$$

$$= \frac{1}{6} [1^2 + 2^2 + 3^2 + 4^2 + 5^2 + 6^2]$$

$$= \frac{6(7)(13)}{6 \times 6}$$

$$= \frac{91}{6}$$

$$\therefore V(X) = \frac{91}{6} - (3.5)^2 = \frac{91}{6} - \frac{49}{4} = \frac{182 - 147}{12} = \frac{35}{12}$$

Note:

The mean and variance for the sum of the numbers on the ~~dies~~ dice is

$$E(X) = \frac{7n}{2}$$

$$V(X) = \frac{35}{12}n$$

where 'n' is the number dice rolled

Q. 3 unbiased dice are thrown. Find the mean ~~of~~ and variance for the sum of the numbers on them.

X : sum of numbers on 3 dice.

X : 2, 3, 4, ..., 18

$$E(X) = \frac{7n}{2} = \frac{7 \times 3}{2} = \underline{\underline{\frac{21}{2}}}$$

$$V(X) = \frac{35}{12}n = \frac{35 \times 3}{12} = \underline{\underline{\frac{35}{4}}}$$

Two unbiased dies are rolled. Find the expectation for sum 7 on them.

X : sum ~~of~~ for the number obtained on 2 dies.

Here X is assuming only 7.

Hence no need of addition.

$$E(\text{sum } 7) = 7 \cdot P(7)$$

$$= 7 \cdot \frac{6}{36} = \frac{7}{6}$$

| | |
|---------|--|
| 6 cases | 1, 6 6, 1 3, 4 4, 3 5, 2 2, 5 |
|---------|--|

Q. A player tosses 3 coins. He wins 500 rupees if 3 heads occur, 300 rs if 2 Heads occurs, 100 rs if only 1 head occurs. On the other hand he loses 1500 rs if 3 tails occur. Find value of the game.

$\text{X} : \text{No of head possibility}$

$$E(X) = \frac{500 \times 1}{8} +$$

| | | | | |
|------|---------------|---------------|---------------|---------------|
| X | 3 | 2 | 1 | 0 |
| P(x) | $\frac{1}{8}$ | $\frac{3}{8}$ | $\frac{3}{8}$ | $\frac{1}{8}$ |

$$\text{VALUE OF GAME} = \text{GAIN - LOSE} = \text{Gain} \times \text{its prob} - \text{Lose} \times \text{its prob.}$$

$$E(X) = 500 \times \frac{1}{8} + 300 \times \frac{3}{8} + 100 \times \frac{3}{8} - 1500 \times \frac{1}{8}$$

$$= \frac{1400 + 300 - 1500}{8}$$

$$= \frac{1700 - 1500}{8}$$

$$= \frac{200}{8} = \underline{\underline{25}}$$

NOTE :

If Game is said to be fair, the expected value of game is said to be 0. (no loss and no gain).

Q. A man has given n keys of which one ~~not~~ fits the lock. He tries them successively without replacement to open the lock. What is the probability that the lock will be open at the δ^{th} trial. Also determine mean and variance.

Note: with Replacement implies that it is Independent events.

without Replacement implies that it is Dependent Events.

prob of opening the lock in 1^{st} trial = y_n

" " 2^{nd} trial = y_{n-1}

" " 3^{rd} trial = y_{n-2}

⋮

prob of opening lock 1st success in 2^{nd} trial = $(1 - y_n) \frac{1}{n-1}$

$$= \frac{n-1}{n} \times \frac{1}{n-1} = \frac{1}{n}$$

prob of opening lock in 1st success in 3^{rd} trial = $(1 - y_n)(1 - y_{n-1}) \times \frac{1}{n-2}$

$$= \frac{n-1}{n} \times \frac{n-2}{n-1} \times \frac{1}{n-2}$$

$$= \underline{y_n}$$

hence

prob of opening lock 1st success δ^{th} trial = y_n

$$\text{Variance of } n \text{ natural numbers } V(x) = \frac{n^2 - 1}{12}$$

consider a value eg:

If keys numbered from 100 - 999

$$\text{Prob}(\underbrace{\text{450}^{\text{th}} \text{ trial without replacement}}_{\text{1st success in}}) = \frac{1}{900} \quad \begin{matrix} (100-999) \\ \text{mean } 0 \rightarrow 900 \end{matrix}$$

$$\text{Prob}(\text{1st success in } 450^{\text{th}} \text{ trial with replacement}) = (1 - \frac{1}{900}) \frac{449}{900}$$

i.e. in without replacements, they are dependent, ~~$\frac{899}{900} \times \frac{898}{899} \times \frac{897}{898}$~~

~~they cannot~~ they loss probabilities of $(x-1)$ trials
cancel each other and get only $\frac{1}{900}$.

But in with replacement, each trial is independent event,
Hence each ~~loss~~ of $(x-1)$ loss probabilities we need to multiply

$$\therefore q^{x-1} p^x$$

Note: The probability for the x^{th} success in the y^{th} trial with replacement is

$$\boxed{P(\text{1st success in } y^{\text{th}} \text{ trial with replacement}) = q^{y-1} p^x}$$

$q \rightarrow$ Failure prob

$p \rightarrow$ Success prob

Q if x is said to be a continuous variable and its probability function f

$$f(u) = Ku^2 \quad 0 < u < 1$$

(i) Find the value of K .

(ii) Find Mean & Variance.

(i) ~~Def~~ $\int_{-\infty}^{\infty} f(u) du = 1$

$$\int_0^1 Ku^2 du = 1$$

$$K \left[\frac{u^3}{3} \right]_0^1 = 1$$

$$\frac{K}{3} = 1$$

$$\underline{K = 3}$$

i) Mean = $E(x) = \int_{-\infty}^{\infty} u f(u) du$

$$= 3 \int_0^1 u^3 du$$

$$= 3 \left[\frac{u^4}{4} \right]_0^1$$

$$= 3 \cdot \frac{3}{4}$$

$$(iii) \text{ Variance } V(n) = E(x^2) - (E(n))^2$$

$$E(x^2) = \int_0^1 x^2 f(n) dn = 3 \int_0^1 n^4 dn = \frac{3}{5}$$

$$\text{Variance} = \frac{3}{5} - \left(\frac{3}{4}\right)^2$$

$$= \frac{3}{5} - \frac{9}{16}$$

$$= \frac{48 - 45}{80} = \underline{\underline{\frac{3}{80}}}$$

Q If x is a continuous r.v. and $f(x) = kx^2 e^{-x}$, $0 < x < \infty$

(i) Find the value k

(ii) Mean & Variance

$$(i) \int_{-\infty}^{\infty} f(n) dn = 0 \int_0^{\infty} kx^2 e^{-x} dx = 1$$

Use Gamma Function,

$$\Gamma_n = \int_0^{\infty} e^{-x} x^{n-1} dx, n > 0$$

$$\Gamma_n = (n-1) \Gamma_{n-1}$$

$= (n-1)!$ (only when n is a integer)

$$\Gamma_1 = 1$$

$$\Gamma_0 \text{ does not exist.}$$

So integral becomes

$$K \int_0^{\infty} = 1$$

$$K \alpha! = 1$$

$$\underline{K = Y_2}$$

(ii) Mean

$$\begin{aligned} E(X) &= \int_0^{\infty} u f(u) du \\ &= \frac{1}{2} \int_0^{\infty} u \cdot u^2 e^{-u} du \\ &= \frac{1}{2} \int_0^{\infty} u^3 e^{-u} du \\ &= \frac{1}{2} \Gamma(4) \\ &= \frac{1}{2} \times 3! = \underline{\underline{3}} \end{aligned}$$

Variance,

$$\begin{aligned} E(X^2) &= \int_0^{\infty} u^2 f(u) du \\ &= \frac{1}{2} \int_0^{\infty} u^2 \cdot u^2 e^{-u} du \\ &= \frac{1}{2} \int_0^{\infty} u^4 e^{-u} du \\ &= \frac{1}{2} \int_0^{\infty} u^4 e^{-u} du \\ &= \frac{1}{2} \Gamma(5) \\ &= \frac{1}{2} \underline{\underline{4!}} = 12 \end{aligned}$$

$$\text{Variance} = 12 - 3^2 \\ = 12 - 9 = \underline{\underline{3}}$$

$$② f(x) = |x| \quad -1 < x < +1$$

V(x) find variance.

$$V(x) = E(x^2) - (E(x))^2$$

$$E(x) = \int_{-1}^1 x f(u) du = \int_{-1}^1 x |u| du \\ = - \int_{-1}^0 u^2 du + \int_0^1 u^2 du \\ = \underline{\underline{0}}$$

odd fn \times even fn
= odd fn

$$\int_{-a}^a \text{odd fn} du = 0$$

$$E(x^2) = \int_{-1}^{+1} x^2 f(u) du \\ = \int_{-1}^{+1} x^2 |u| du \\ = 2x \int_0^1 x^2 du$$

$$= 2 \times \left[\frac{x^4}{4} \right]_0^1$$

$$= \cancel{2} \cancel{\times} \frac{1}{4} = \underline{\underline{\gamma_2}}$$

$x^2 |u| \rightarrow \text{even} \times \text{even}$
 \downarrow
even

$$\int_{-a}^a \text{even fn} = 2 \int_0^a \text{even fn}$$

$$\text{Variance} = \underline{\underline{\gamma_2}} - 0^2 = \cancel{\cancel{\gamma_2}} \underline{\underline{\gamma_2}}$$

Q. If X & Y are the r.v's mean of X is 10, variance of $X = 25$. Find positive values of a, b , such that $Y = aX - b$ has expectation is zero and variance is 1.

$$E(Y) = E[aX - b] = 0$$

$$\Rightarrow aE[X] - E[b] = 0$$

$$10a - b = 0$$

$$10a - b = 0$$

$$\underline{b = 10a}$$

$$V(Y) = V[aX - b] = a^2 V[X] = 1$$

$$= a^2 \cdot 25 = 1$$

$$\underline{a = \frac{1}{5}} \quad \text{Given +ve}$$

$$b = 10a$$

$$= 10 \times \underline{\frac{1}{5}}$$

$$= \underline{2}$$

$$\underline{a = \frac{1}{5}, \quad b = 2}$$

BIVARIATE DATA

Let x, y be two discrete r.v.s,

Their probability together given by Joint probability Mass Function (JP MF)

Let x, y be two continuous r.v.s

Their probability together given by Joint probability Density Function (JP DF)

Case (i) Continuous R.V's.

- If x and y are two continuous r.v.'s, and its probability function is known as Joint probability density function is denoted by $f(x, y)$.
- The marginal density functions are

$$f(x) = \int_y f(x, y) dy$$

$$f(y) = \int_x f(x, y) dx$$

Independent

- If x and y are 2-D continuous r.v.'s and its probability function is known as Joint iff,

$$f(x, y) = f(x) f(y)$$

i.e,

$$\text{JPDF} = \text{MDF}(x) \cdot \text{MDF}(y)$$

Joint Distribution Function or Cumulative Distribution Function

$F(x, y)$ is given by JDF

$$\frac{\partial^2}{\partial x \partial y} F(x, y) = f(x, y)$$

$$F(x, y) = \int_{-\infty}^x \int_{-\infty}^y f(u, v) du dv.$$

⇒ Conditional probability

$$f(x|y) = \frac{f(x, y)}{f(y)}, (f(y) \neq 0)$$

$$E(x|y) = \frac{E(x, y)}{E(y)}, (E(y) \neq 0)$$

Case (ii) Discrete R.V's.

If x and y are two dimensional r.v's and its probability function is known as joint probability function ~~PDF~~ is denoted by $P(x, y)$.

The marginal mass functions are

$$P(x) = \sum_y P(x, y)$$

$$P(y) = \sum_x P(x, y)$$

Q. If x and y are 2-D continuous r.v's and its probability function is given by

$$f(x,y) = xy$$

- * $0 < x < 1$
- $0 < y < 1$

(i) $E(x)$; ~~$V(y)$~~

(ii) $E(xy)$; $\text{cov}(x,y)$

(iii) $f(x|y)$; $E(x|y)$

(iv) check x & y are independent or not

$$(i) f(x) = \int_y f(x,y) dy = \int_0^1 xy dy = x \cdot y \Big|_0^1 = \frac{x}{2}$$

$$f(y) = \frac{y}{2}$$

$$E(x) = \int_0^1 x \cdot f(x) dx = \int_0^1 x^2/2 dx = \left[\frac{x^3}{6} \right]_0^1 = \frac{1}{6}$$

$$E(y) = \int_0^1 y f(y) dy = \int_0^1 \frac{y^2}{2} dy = \left[\frac{y^3}{6} \right]_0^1 = \frac{1}{6}$$

$$E(y^2) = \int_0^1 y^2 f(y) dy = \int_0^1 y^2 \cdot \frac{y}{2} dy = \frac{1}{8}$$

$$V(y) = \frac{1}{8} - \left(\frac{1}{6} \right)^2 = \frac{1}{8} - \frac{1}{36} = \frac{36-8}{8 \times 36} = \frac{28}{8 \times 36} = \frac{7}{72}$$

$$E(x \cdot y) = \int_{x=0}^1 \int_{y=0}^1 x \cdot y f(x,y) dx dy.$$

$$= \int_{x=0}^1 \int_{y=0}^1 x \cdot y (x \cdot y) dx dy$$

$$= \int_{x=0}^1 \int_{y=0}^1 x^2 y^2 dx dy$$

$$= \int_0^1 \frac{x^2}{3} dx = \underline{\underline{\frac{1}{9}}}$$

Covariance:

$$\text{Cov}(x,y) = E(x \cdot y) - E(x) \cdot E(y)$$

$$= \frac{1}{9} - \frac{1}{6} \times \frac{1}{6} = \frac{1}{9} - \frac{1}{36} = \frac{4-1}{36} = \underline{\underline{\frac{3}{36}}}$$

(iii)

$$f(x|y) = \frac{f(x,y)}{f(y)} = \frac{x \cdot y}{y/2} = \underline{\underline{\frac{x}{2}}}$$

$$E(x|y) = \frac{E(x \cdot y)}{E(y)} = \frac{\frac{1}{9}}{\frac{1}{6}} = \underline{\underline{\frac{2}{3}}}$$

$$f(x,y) = f(x) f(y)$$

$x \cdot y \neq \frac{x}{2} \cdot \frac{y}{2} \therefore x \& y \text{ are Dependant r.v's.}$

Q If x and y are 2-D Discrete r.v's and its joint probability mass function is

| $x \backslash y$ | -1 | 0 | +1 |
|------------------|---------------|---------------|---------------|
| -1 | $\frac{1}{4}$ | 0 | 0 |
| 0 | 0 | $\frac{1}{2}$ | 0 |
| +1 | 0 | 0 | $\frac{1}{4}$ |

(i) Find $P(x+y=2/x-y=0)$

$$P(x+y=2/x-y=0) = \frac{P(x+y=2 \wedge x-y=0)}{P(x-y=0)}$$

$$= \frac{P(x=1, y=1)}{P(x=1, y=-1) + P(x=0, y=0) + P(x=1, y=1)}$$

$$= \frac{\frac{1}{4}}{\frac{1}{4} + \frac{1}{2} + \frac{1}{4}}$$

$$P(x+y=2/x-y=0) = \underline{\underline{\frac{1}{4}}}$$

BINOMIAL DISTRIBUTION

Definition : If x is said to be a binomial random variable. It allows the values from 0 to n with the parameters (n, p) and its probability mass function is

$$B(x, n, p) = P(n) = \begin{cases} {}^n C_n p^x q^{n-x}, & 0 \leq x \leq n \\ 0, & \text{otherwise} \end{cases}$$

$p+q=1$
 $q=1-p$

Conditions

- Observations are independent, (n is small).
- The probability of success is constant (p is large)
- Mean is greater than the variance.

PROPERTIES

$$E(x) = \text{Mean} = np$$

$$V(x) = \mu_2 = npq$$

Var (variance) : $V(x) = npq(p+q-1)$

$$\beta_1 = \frac{\mu_3^2}{\mu_2^3} = \frac{n^2 p^2 q^2 (q-p)^2}{n^3 p^3 q^3}$$

$$\beta_1 = \frac{(1-2p)^2}{npq}$$

$$\gamma_1 = \frac{1-2p}{\sqrt{npq}}$$

① ∵ In het, $P = Y_2 \rightarrow$ symmetry.

$P < Y_2 \rightarrow$ positively skewed.

$P > Y_2 \rightarrow$ Negatively skewed.

Moment Generating Function (MGF)

$$M_X(t) = E[e^{tx}] = (q + pe^t)^n$$

→ Moment Generating Function is used for the taking the sum and difference of 2 r.v's along with the Binomial Distribution.

Characteristic Function

$$\phi_X(t) = E[e^{itx}] = (q + pe^{it})^n$$

Characteristic function is used for finding correlations and

ratio of 2 r.v's with binomial distribution.

Note:

$$\rightarrow P = Y_2 \Rightarrow \mu_3 = 0 \Rightarrow \beta_1 = 0$$

Then the Curve is Symmetry.

\rightarrow If $P < Y_2$, then the curve is Positively skewed.

\rightarrow If $P > Y_2$, then the curve is Negatively skewed.

The moment Generating function is used to find addition and differences b/w the r.v's with their corresponding probability function.

The characteristic function is used to finding the convolution and ratio b/w the r.v's with their probability function.

Sum of Independent Binomial r.v's is also a Binomial random variables.

Q, Find the probability of getting a 9 exactly 2 in 3 times with a pair of dice.

$$n = 3$$

$$x = 2$$

$$P(\text{sum } 9) = \cancel{(5,4)}(4,5)(6,3)(3,6)$$

$$= \frac{4}{36} = \underline{\underline{\frac{1}{9}}}$$

$$q = \underline{\underline{\frac{8}{9}}}$$

$$\text{Required prob} = {}^n C_x p^x q^{n-x}$$

$$= {}^3 C_2 \left(\frac{1}{9}\right)^2 \left(\frac{8}{9}\right)^1$$

$$= \cancel{\frac{3!}{2!1!}} \cdot \frac{8}{243}$$

Q, The probability of man hitting the target is $\frac{1}{3}$.

(i) If he fires five times, what is the probability of his hitting the target at least twice.

(ii) How many time must he fire so that the probability of his hitting the target atleast once is more than 90%?

(i) $n = 5, P = \frac{1}{3}, q = \frac{2}{3}$

$$P(X \geq 2) = 1 - P(X < 2)$$

$$= 1 - [P(X=1) + P(X=0)]$$

In binomial distribution

$$\begin{cases} P(X=0) = q^n \\ P(X=n) = p^n \end{cases}$$

Always.

$$P(X \geq 2) = 1 - \left[\left(\frac{2}{3}\right)^5 + {}^5C_1 \left(\frac{1}{3}\right) \left(\frac{2}{3}\right)^4 \right]$$

$$= 1 - \left[\left(\frac{2}{3}\right)^4 \left[\frac{2}{3} + \frac{5}{3} \right] \right]$$

$$= \frac{131}{243}$$

ii) $P(X \geq 1) > 90\%$

$$1 - P(X=0) > 0.9$$

$$P(X=0) < 0.1$$

$$q^n < 0.1$$

$$\left(\frac{2}{3}\right)^n < 0.1$$

Taking log on both sides

Here asked for number of trials

$$n = 5.14$$

$$\approx 6$$

Q If x and y are the binomial r.v.

$$x \sim B(2, p)$$

$$y \sim B(4, p)$$

$$\text{If } P(x \geq 1) = 5/9$$

$$\text{Find } P(y \geq 1) = ?$$

$$P(x \geq 1) = 5/9$$

$$1 - P(x=0) = 5/9$$

$$1 - (1-p)^n = 5/9$$

$$(1-p)^n = 4/9$$

$$q^n = 4/9$$

$$\text{Give } n_n = 2$$

$$q^2 = (1-p)^2 = 4/9$$

$$1-p = 2/3$$

$$p = \underline{\underline{1/3}}$$

$$\text{For } y \sim B(4, 1/3)$$

$$P(y \geq 1) = 1 - P(y=0)$$

$$= 1 - (2/3)^4$$

$$= 1 - \underline{(2/3)^4} + \frac{16}{81} = \frac{65}{81}$$

Q. 2 dies are rolled 120 times. Find the average no. of times in which the number on the first die exceeds the no. on the second die.

$$n = 120$$

$$P = ?$$

For finding P,

no. on first die exceeds the second die,

~~(2,1) (3,1)~~

equal case $\rightarrow \frac{6}{36}$, remaining $\frac{30}{36}$, Half will be
first die > second die.

$$\therefore P = \frac{15}{36}.$$

$$\therefore \text{Average} = \text{Mean} = E(X) = np = 120 \times \frac{15}{36} = \underline{\underline{50}}$$

Q. If x is a ~~binomial~~ binomial r.v. and $E(x) = 4$

$$V(x) = 4/3$$

Find i) $P(x \leq 2)$

ii) comment on P ,

i) $P(x \leq 2)$

$$E(x) = 4$$

$$np = 4$$

$$npq = \frac{4}{3}$$

$$q = \frac{1}{3}$$

$$p = \frac{2}{3}$$

$$\frac{2+2}{3} = \frac{4}{3}$$

$$n = 6$$

$$\begin{aligned}
 P(X \leq 2) &= P(X=0) + P(X=1) + P(X=2) \\
 &= \left(\frac{1}{3}\right)^6 + {}^6C_1 \left(\frac{1}{3}\right)^5 \left(\frac{2}{3}\right) + {}^6C_2 \left(\frac{1}{3}\right)^4 \left(\frac{2}{3}\right)^2 \\
 &= \frac{1}{36} [1 + 12 + 60] = \underline{\underline{\frac{73}{729}}}
 \end{aligned}$$

(ii) Given Data is very skewed since p value is more than γ_2 . $P = 2/3 > \gamma_2$.

Q, If X is a binomial random variable, then find the
values of

$$\sum_{n=0}^{\infty} \left(\frac{q}{n}\right) n C_n p^n q^{n-n}$$

$$= \frac{1}{n} \sum_{k=0}^n n C_n p^k q^{n-k}$$

$$= \frac{1}{n} \left[\sum_{n=0}^N x_n p(n) \right]$$

$$= \frac{1}{n} \times \text{Mean}.$$

$$= \frac{1}{n} \times \cancel{NP}$$

= P

POISSON DISTRIBUTION

Probability Function is given by

$$P(X; \lambda > 0) = P(x) = \begin{cases} \frac{e^{-\lambda} \lambda^x}{x!}, & \lambda > 0 \\ 0, & \text{otherwise.} \end{cases} \quad 0 \leq x < \infty$$

- It is used when observations are HIGH and success Probability is Low.
- It is Used to Find RARE OCCURANCES.
- Poisson's equation is time dependent distribution.
- ie, it is a Evolutionary Process.

Used to find Defect Probability.

Used to find Arrival Rate.

definition

If X is said to be poisson r.v defined in the interval $0 < x < \infty$ with a parameter $\lambda (\lambda > 0)$ and its probability mass function is

$$P(X; \lambda > 0) = P(x) = \begin{cases} \frac{e^{-\lambda} \lambda^x}{x!} & \lambda > 0 \\ 0 & 0 \leq x < \infty \\ 0 & \text{otherwise.} \end{cases}$$

conditions

- observations are infinitely large, ($n \rightarrow \infty$)
- probability of success is very small ($p \rightarrow 0$)
- $np = \lambda \Rightarrow p = \frac{\lambda}{n}$

$$\text{Then } P(x; n, p) = \frac{e^{-np} (np)^x}{x!}$$

It is approximation of binomial.

POISSON PROCESS

$$P(x; \lambda, t > 0) = \frac{e^{-\lambda t} (\lambda t)^x}{x!}$$

PROPERTIES

$$1. E(X) = \text{Mean} = \lambda$$

$$V(X) = \mu_2 = \lambda$$

$$\mu_3 = \lambda$$

$$\lambda > 0$$

$$\therefore \beta_1 = \frac{\mu_3^2}{\mu_2^3} = \frac{1}{\lambda}$$

i.e., Poisson's distribution is always positively skewed.

It can never be symmetric

→ highly skewed

2. MGF

$$M_x(t) = E[e^{tx}] = e^{\lambda(e^t - 1)}$$

3. Characteristic function.

$$\phi_n(t) = E[e^{itn}] = e^{\lambda(e^{it} - 1)}$$

Ex:

In ~~pos~~ Poisson's ~~dis~~ distribution.

• Mean = Variance = parameter λ .

It is always +vely skewed.

Sum of the independant poisson r.v's is also a poisson's r.v.

• Difference b/w the independant poisson's r.v's is not a poisson random variable.

Q A telephone switchboard receives 20 calls on an avg during an hour. Find the probability for a period of 5 min,

- (i) No call is received.
- (ii) Exactly 3 calls are received.
- (iii) At least 2 calls are received.

reach
arrive
error
defect } go for poisson's distribution

Soln

$$\text{avg} = \lambda \text{ (for 60 min)}$$

For 60 min $\rightarrow \lambda = 20 \text{ calls}$

$$\text{For 1 min} \rightarrow \frac{20}{60} = \underline{\underline{\frac{1}{3}}} = \lambda$$

$$\text{For 5 min} = \frac{1}{3} \times 5 = \underline{\underline{1.65}} = \lambda$$

$$(i) P(X=0) = \frac{e^{-1.65} (1.65)^0}{0!} \\ = \underline{\underline{\frac{e^{-1.65}}{1}}}$$

$$(ii) P(X=3) = \frac{e^{-1.65} (1.65)^3}{3!}$$

$$(iii) P(X \geq 2) = 1 - P(X < 2)$$

$$= 1 - \left[P(X=0) + P(X=1) \right] = 1 - \left[\frac{e^{-1.65}}{1} + \frac{1.65 e^{-1.65}}{1!} \right]$$

2. If x is a poisson r.v., then find the value of

$$\sum_{n=0}^{\infty} \left(\frac{x}{\lambda}\right) \frac{e^{-\lambda} \lambda^n}{n!}$$

$$\cancel{\sum_{n=0}^{\infty} x \lambda^n}$$

$$\frac{1}{\lambda} \sum_{n=0}^{\infty} n \left(\frac{e^{-\lambda} \lambda^n}{n!} \right)$$

$$\cancel{\frac{1}{\lambda}} \times E(x)$$

$$= \underline{\underline{\frac{1}{\lambda} \times \lambda = 1}}$$

NORMAL DISTRIBUTION (GAUSSIAN)

$$N(u; \mu, \sigma^2) = f(x) = \begin{cases} \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{1}{2} \left(\frac{x-\mu}{\sigma}\right)^2} & -\infty < x < \infty \\ 0, \text{ otherwise.} & \end{cases}$$

$-\infty < u < \infty$
 $-\infty < \mu < \infty$
 $0 < \sigma < \infty$

Definition: If x is said to be a normal r.v defined in the interval

$-\infty < x < \infty$ with mean equal to μ and variance is equal to σ^2 , Then the r.v is known as normal r.v.

And its density function is

$$N(u; \mu, \sigma^2) = f(u) = \begin{cases} \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{1}{2} \left(\frac{u-\mu}{\sigma}\right)^2} & -\infty < u < \infty \\ 0, \text{ otherwise.} & \end{cases}$$

$-\infty < u < \infty$
 $-\infty < \mu < \infty$
 $0 < \sigma < \infty$

STANDARD NORMAL RANDOM VARIABLE

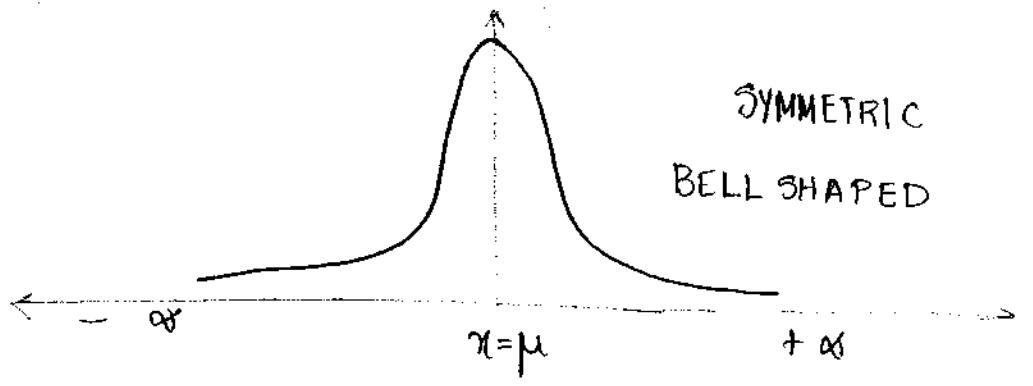
If x is a normal random variable with mean = 0 and variance = 1, then the random variable is known as standard normal random variable. Its density function is

$$N(0, 1) = f(u) = \frac{1}{\sqrt{2\pi}} e^{-\frac{u^2}{2}}$$

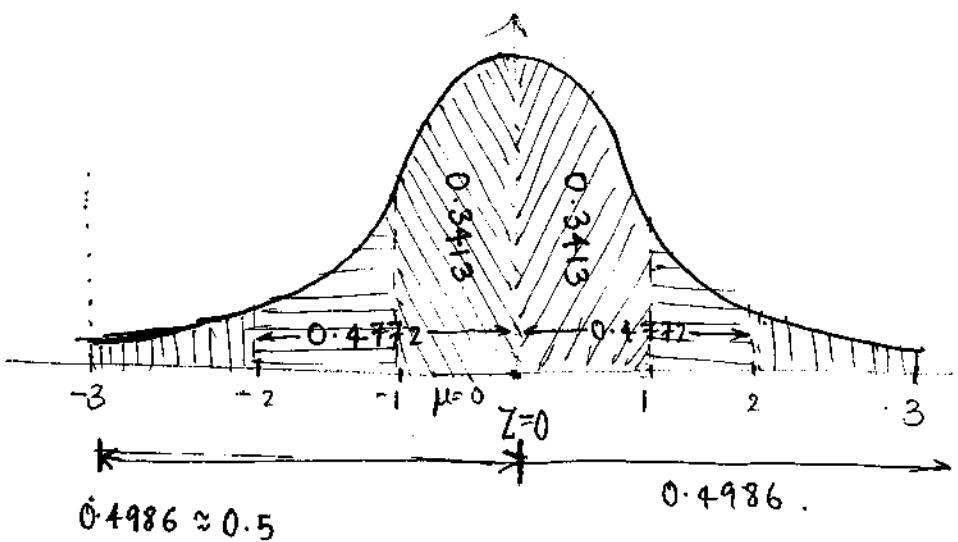
Mathematically a standard normal r.v is denoted by Z and

is equal to $Z = \frac{X - E(X)}{\sqrt{V(X)}}$

$$-3 \leq Z \leq +3$$

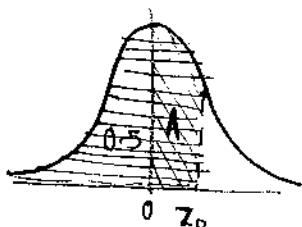


standard Normal Distribution



Areas under Normal Curve

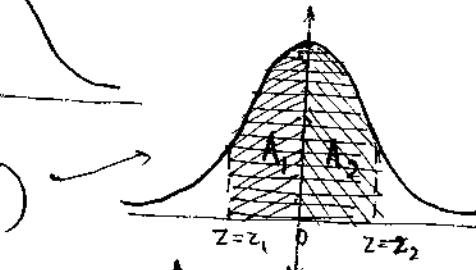
$$P(Z \leq z_0) = 0.5 + A(z_0 + ve)$$



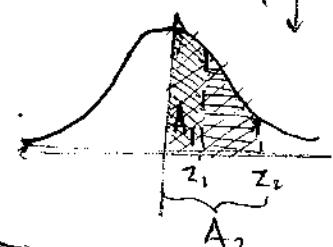
$$P(Z \leq z_0) = 0.5 - A(z_0 - ve)$$



$$P(z_1 \leq Z \leq z_2) = A_1 + A_2 \quad (z_1 - ve \text{ and } z_2 + ve)$$



$$P(z_1 \leq Z \leq z_2) = A_2 - A_1 \quad (z_1 \text{ and } z_2 + ve / -ve)$$



$$P(Z \geq z_0) = 0.5 + A(z_0 - ve)$$



$$P(Z \geq z_0) = 0.5 - A(z_0 + ve)$$



Q. If X is normally distributed with mean = 20 and std deviation
3.33. Find the probability b/w

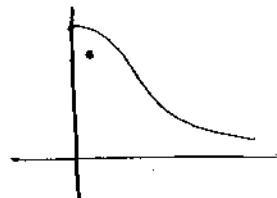
$P(21.11 \leq X \leq 26.66)$. The area under the curve ,

$Z_0 = 0$ to $Z = 0.33$ is 0.1293 .

$$Z_1 = \frac{X_1 - \mu}{\sigma} \quad Z_2 = \frac{X_2 - \mu}{\sigma}$$

$$Z_1 = \frac{1}{3} \quad Z_2 = 2 \\ = 0.33$$

$$P(21.11 \leq X \leq 26.66) = P(0.33 < Z < 2)$$



$$= 0.4772 - 0.1293$$

$$= \underline{\underline{0.3479}}$$

Q. If X is normally distributed with mean = 30 and std deviation
as 5. Find $P(|X-30| > 5)$

$$\Rightarrow \cancel{|X-30|} -5 < X-30 < 5$$

$$P(|X-30| > 5) = \cancel{P(|X-30|)}$$

$$1 - P(|X-30| < 5)$$

$$P(25 < X < 35)$$

$$Z_1 = \frac{25 - 30}{5} = \frac{-5}{5} = \underline{\underline{-1}}$$

$$Z_2 = \frac{35 - 30}{5} = \frac{5}{5} = \underline{\underline{1}}$$

$$P(-1 < Z < 1) = A_1 + A_2 = \underline{\underline{0.6826}}$$

2. A die is rolled 180 times. Using the normal distribution, find the probability that the face 4 will turn up at least 35 times.

$$P(X \geq 35) = ?$$

We can use Binomial Distribution, with $n=180$, $p=\frac{1}{6}$, $q=\frac{5}{6}$.

$$E(X) = np = \frac{180}{6} = 30$$

$$V(X) = npq = \frac{180}{6} \times \frac{5}{6} = \frac{25}{\cancel{6} \times \cancel{5}} = 30$$

$$Z = \frac{X - \mu}{\sigma} = \frac{35 - 30}{5} = \underline{\underline{1}}$$

$$P(Z \geq 1) = 0.5 - 0.3413$$

$$= \underline{\underline{0.1587}}$$

Properties

$$E(X) = \text{Mean} = \mu$$

$$V(X) = \text{Variance} = \mu_2 = \sigma^2$$

$$\mu_3 = 0 \Rightarrow \beta_1 = 0 \Rightarrow \text{Symmetry}.$$

MGF

$$M_X(t) = e^{t\mu + \frac{t^2\sigma^2}{2}}$$

(iv) characteristic

$$\phi_x(t) = e^{(it\mu - \frac{t^2\sigma^2}{2})}$$

properties of std Normal distribution.

$$\rightarrow X \sim N(0, 1)$$

$$\rightarrow E(X) = 0$$

$$\rightarrow V(X) = 1$$

$$\rightarrow M_x(t) = e^{t\mu + \frac{t^2\sigma^2}{2}}$$

$$\rightarrow \phi_x(t) = e^{-\frac{t^2}{2}}$$

Sum of the independent normal r.v.s is also a normal random variable.

The difference the independent normal r.v.s is also a normal random variable (Linear combination).

UNIFORM DISTRIBUTION [RECTANGULAR]

Definition: If X is a uniform r.v. in the interval $a < x < b$ ($a < b$) and its probability density function is

$$f(x) = \begin{cases} \frac{1}{b-a} & a < x < b \\ 0 & \text{otherwise} \end{cases}$$

MEAN $= E(X) = \frac{a+b}{2}$

VARIANCE $= V(X) = \frac{(b-a)^2}{12}$

If X is uniform random variable in the interval $-a < x < a$ and its density function is

$$f(x) = \frac{1}{2a}$$

Mean = 0

Variance = $\frac{a^2}{3}$

The shape of uniform curve is rectangular.

CORRELATION / REGRESSION

A = 0.7461
B = 1.1154

CORRELATION

Karl Pearson's Correlation.

The relation b/w the two dimensional r.v in bivariate data is known as regression (The degree of relation b/w the two variables is known as ~~correlation~~ ^{correlation})

- Types of correlation (i) Positive Correlation.
(ii) Negative Correlation.

positive Correlation: If the changes in the both the variables are in the same direction (increasing or decreasing) Then those variables are known as positively correlated variables.

Negative Correlation: If the changes in the one variable is affecting the changes of other variable in reverse direction, then those variables are known as negatively correlated.

Karl Pearson's Correlation eqn.

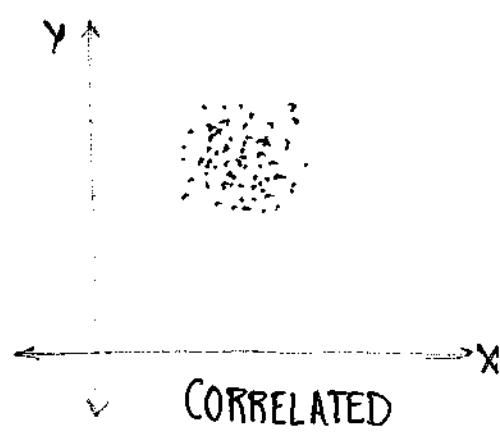
$$\gamma(x,y) = \frac{\text{Cov}(x,y)}{\sqrt{x} \sqrt{y}} \quad \text{where } \text{Cov}(x,y) = \frac{1}{n} \sum xy - \bar{x} \cdot \bar{y}$$

$$-1 \leq \gamma \leq 1$$

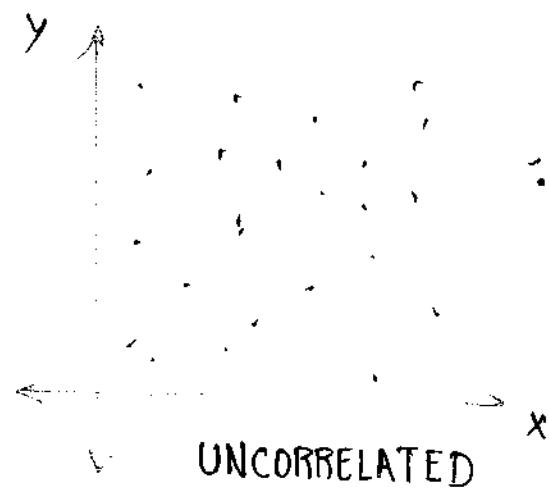
SCATTER DIAGRAM

It is a graphical representation of correlation. If the points are very close or thick on the XY plane then those points are correlated points.

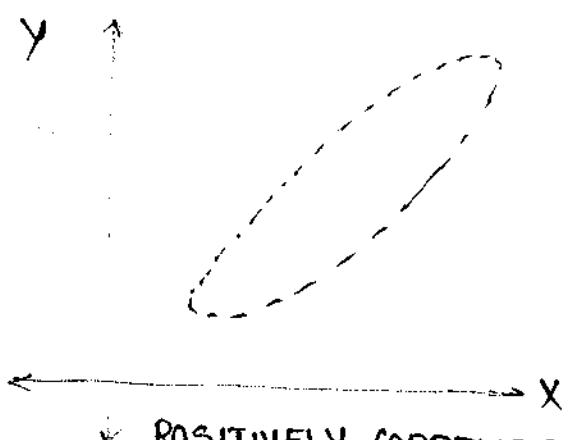
If the points are widely spreaded, then they are said to be uncorrelated.



CORRELATED



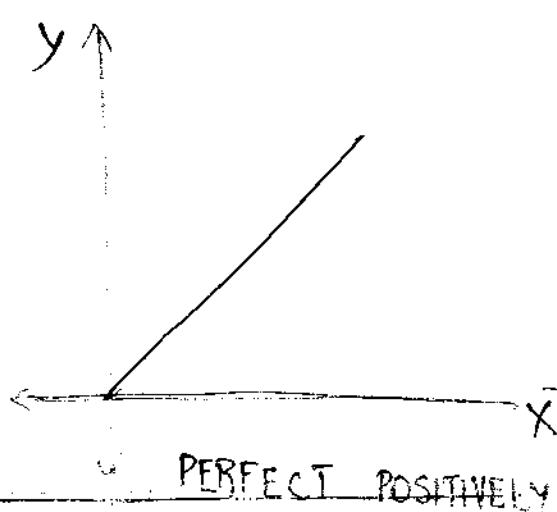
UNCORRELATED



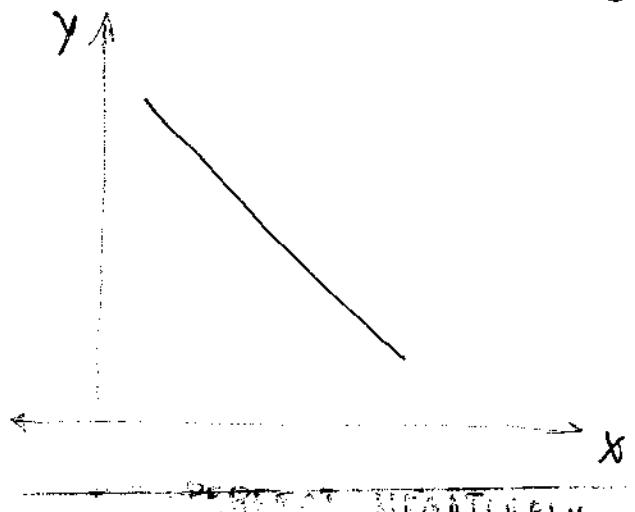
POSITIVELY CORRELATED



NEGATIVELY CORRELATED



PERFECT POSITIVELY



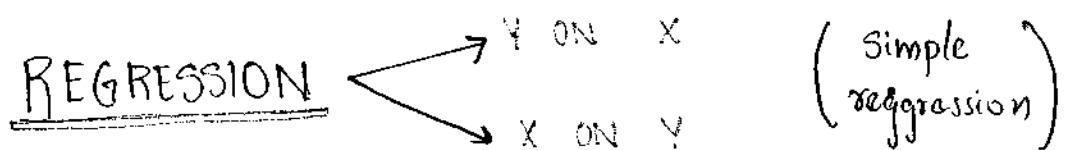
PERFECT NEGATIVELY

Note: \Rightarrow If x & y are independent r.v's then covariance is zero.

$$\text{i.e., } \boxed{\text{Cov}(x, y) = 0 \implies \gamma(x, y) = 0}$$

But converse of the statement is not true.

\Rightarrow Correlation coefficient is independent of origin as well independent of change of scale.



Definition: The linear relationship b/w the 2-D random variable is known as regression.

LINES OF REGRESSION

$$y - \bar{y} = \gamma \cdot \frac{\sigma_y}{\sigma_x} (x - \bar{x}) \quad Y \text{ ON } X$$

$$x - \bar{x} = \gamma \cdot \frac{\sigma_x}{\sigma_y} (y - \bar{y}) \quad X \text{ ON } Y$$

$$\left. \begin{aligned} \text{where } \gamma \cdot \frac{\sigma_y}{\sigma_x} &= b_{yx} \\ &\& \gamma \cdot \frac{\sigma_x}{\sigma_y} = b_{xy} \end{aligned} \right\} \text{Regression coefficients.}$$

→ Correlation coefficient is the Geometric mean b/w regression coefficients.

$$\gamma = \pm \sqrt{b_{yx} b_{xy}}$$

Note: Both the regression coefficients must have a same sign.

i.e., if both +ve $\Rightarrow \gamma$ is +ve.

If both -ve $\Rightarrow \gamma$ is -ve.

If $b_{yx} > 1 \Rightarrow b_{xy} < 1$ (vice versa).

If the regression coefficients are equal, their variances also equal.

$$b_{xy} = b_{yx} \Rightarrow \gamma \cdot \frac{\sigma_x}{\sigma_y} = \gamma \cdot \frac{\sigma_y}{\sigma_x}$$
$$\Rightarrow \sigma_y^2 = \sigma_x^2$$

Regression equations are passes through the point \bar{x}, \bar{y}

Regression Coefficient is independent of change of origin as well as dependent of change of scale.

Angle b/w Regression lines

$$\theta = \tan^{-1} \left(\frac{1-\gamma^2}{|\gamma|} \cdot \frac{\overline{Ox} \overline{Oy}}{(\overline{Ox})^2 + (\overline{Oy})^2} \right)$$

$$\gamma = 0 \Rightarrow \theta = \pi/2$$

$$\gamma = 1 \Rightarrow \theta = 0 \text{ or } \pi$$

Q. The regression equation are $3x + 2y = 1$.
 $2x + 4y = 0$

(i) Find γ ?

(ii) \bar{x}, \bar{y}

whichever the coefficient in the expression is higher then it is the DEPENDENT VARIABLE.

Consider $\uparrow 3x + 2y = 1$

Dependent variable

$\therefore X \text{ on } Y$

X on Y

$$3x + 2y = 1$$

$$3x = 1 - 2y$$

$$x = \frac{1}{3} - \frac{2}{3}y$$

$$\cancel{b_{xy} = -\frac{2}{3}}$$

Y on X

$$2x + 4y = 0$$

$$4y = -2x$$

$$y = -\frac{1}{2}x$$

$$\cancel{b_{yx} = -\frac{1}{2}}$$

- Positive

Hence γ also -ve

$$\alpha = \sqrt{\frac{2}{3} \times \frac{1}{2}}$$

$$\gamma = -\sqrt{\frac{2}{3}}$$

$$\beta = \underline{-\frac{1}{\sqrt{3}}}$$

(ii) Means \bar{x} & \bar{y} satisfies eqn.

$$6\bar{x} + 4\bar{y} = 2$$

$$2\bar{x} + 4\bar{y} = 0$$

$$4\bar{x} = 2$$

$$\bar{x} = \underline{\underline{\frac{1}{2}}}$$

$$\bar{y} = \underline{\underline{-\frac{1}{4}}}$$

$$\therefore \text{Means } (\bar{x}, \bar{y}) = (\underline{\underline{\frac{1}{2}}}, \underline{\underline{-\frac{1}{4}}})$$

$$x - 2y = 2$$

$$3x - y = 1$$

(i) \propto (ii) \bar{x}, \bar{y}

~~X~~ $\underline{\underline{Y \text{ on } X}}$

$$x - 2y = 2$$

$$x - 2 \Rightarrow 2y$$

$\frac{X \text{ on } Y}{3x = 1 + y}$

$$x = \underline{\underline{y_3 + y_1}}$$

$$\gamma = \sqrt{y_2 + y_3}$$

$$\gamma = \frac{1}{\sqrt{6}}$$

$$(ii) \quad \bar{x} - 2\bar{y} = 2$$

$$3\bar{x} - \bar{y} = 1$$

$$3\bar{x} - 6\bar{y} = 6$$

$$3\bar{x} - \bar{y} = 1$$

$$-5\bar{y} = 5$$

$$\bar{y} = \underline{-1}$$

$$3\bar{x} + \bar{x} = \cancel{\bar{x}}$$

$$\bar{x} = \underline{0}$$

$$(\bar{x}, \bar{y}) = \underline{(0, -1)}$$