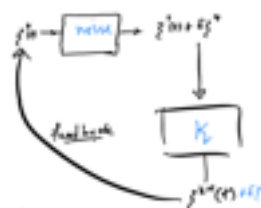


$$\langle \hat{p}^2 \rangle = \hbar^2 \langle \hat{p} \rangle^2$$

$$\hat{p}^2 = \hbar^2 \langle \hat{p} \rangle^2$$

$$\hat{p}^2 = \frac{1}{2} \int_{-\infty}^{\infty} \langle \hat{p}^2 \rangle \delta(x) dx$$

Start with  $\hat{p}^2 = \hat{p}^2$



Option #2



$$\delta J^*[\hat{p}] \geq 0 ?$$

$$\hat{p}_t^{(k)} = \hat{p}_p^{(k)} + \delta J$$

$$\langle \hat{p}_t^{(k)} \rangle = \langle \hat{p}_p^{(k)} \rangle + \langle \delta J \rangle \approx \langle \hat{p}_p^{(k)} \rangle + \langle \delta J \rangle$$

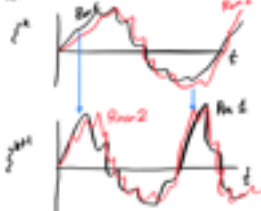
$$\langle \hat{p}_t^{(k)} \rangle = \langle \hat{p}_p^{(k)} \rangle + \langle \delta J \rangle$$

$$\delta J^* \approx \int dt (\hat{p}_t^{(k)} - \hat{p}_p^{(k)})$$

$$\delta J^* \approx \int dt (\hat{p}_t^{(k)} - \hat{p}_p^{(k)})$$

$$\langle \delta J^* \rangle \approx \int dt (\langle \hat{p}_t^{(k)} - \hat{p}_p^{(k)} \rangle) \approx \langle \delta J^* \rangle$$

I assumed that "noise" is not related to "mean"  $\Rightarrow \langle \delta J^* \rangle = 0$



$$\delta J^* = \int dt (\hat{p}_t^{(k)} - \hat{p}_p^{(k)})$$

$$\delta J^* = \int dt (\hat{p}_t^{(k)} - \hat{p}_p^{(k)})$$

$$\langle \delta J^* \rangle_{\text{ens}} = \int dt (\langle \hat{p}_t^{(k)} - \hat{p}_p^{(k)} \rangle)$$

$$\langle \delta J^* \rangle_{\text{ens}} = \int dt (\langle \hat{p}_t^{(k)} - \hat{p}_p^{(k)} \rangle)$$

I think this will be zero for low.



Q: Inside "blocks"  $\hat{p}$  is better uniform low?

N = # Repetitions

L = Leaky memory!

$$\begin{bmatrix} \{ \}^1 & \{ \}^2 & \{ \}^3 & \dots \end{bmatrix}$$

$$\downarrow$$

$$\begin{bmatrix} \{ \}^1 & \{ \}^2 & \dots \end{bmatrix}$$

One more thing to check

OPEN SYSTEM KROTON

$$|\dot{\psi}\rangle = -i A |\psi\rangle \rightarrow (1)$$

$$|\dot{\psi}\rangle = -i A^\dagger |\psi\rangle \rightarrow (2)$$

I have in Hilbert Space,

$$\dot{\psi} = -i [H(\psi), \psi] + \sum_k L_k^\dagger L_k \psi$$

This corresponds to eq(1) above.

What is

$$\dot{\psi} = -i [H(\psi), \psi] + \sum_k L_k^\dagger L_k \psi$$

$$\dot{\psi} = -i [H(\psi), \psi] + \sum_k L_k^\dagger L_k \psi$$

$$\text{SF } \dot{\psi} = A \psi$$

$$|\dot{\psi}\rangle = B^\dagger A |\psi\rangle$$

$$|\dot{\psi}\rangle = X |\psi\rangle$$

also instead of I had

$$|\dot{\psi}\rangle = X^\dagger |\psi\rangle$$

$$= B^\dagger A^\dagger |\psi\rangle$$

then the corresponding Hilbert

$$\dot{\psi} = A^\dagger B^\dagger \psi$$

$$= A^\dagger B^\dagger \psi$$

$$\text{Hence } |\dot{\psi}\rangle = A^\dagger |\psi\rangle$$

$$\Rightarrow \dot{\psi} = -i [H, \psi] + \sum_k L_k^\dagger L_k \psi$$

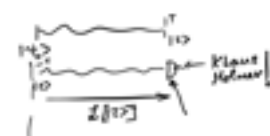
$$\dot{\psi} = -i [H, \psi] + \sum_k L_k^\dagger L_k \psi$$

→ need to be careful with the order!

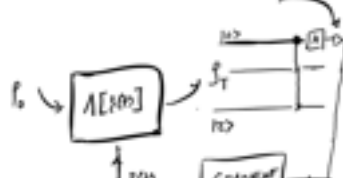
$$\dot{\psi} = -i [H, \psi] + \sum_k L_k^\dagger L_k \psi$$

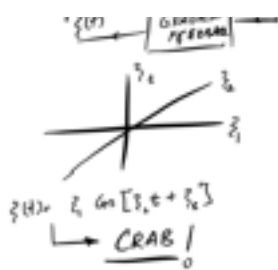
$$\frac{d\psi}{dt} = e^{-iHt} \psi$$

Bottom line is: Implementing of evolution is an issue on NISQ.



variety is freedom





16/10/20

$$\dot{z} = -i[H, z] = \sum_k [z, H_k] = \sum_k [z, \frac{p_k^2}{2m_k}]$$

$$\dot{z} = -i[H, z] = \sum_k [z, H_k] = \sum_k [z, \frac{p_k^2}{2m_k}]$$

Q: Can you "cancel" out the  $\frac{p_k^2}{2m_k}$  terms?

There are two different "cancel" out terms.

① The whole solution is very different looking equation.

② The whole solution is depending on time.

Now ②: on that ②, I suspect that  $\dot{z}$  is not physical. It's not a particle looking eq. is not physical.

If this is true, this is not a particle eq. is not physical.

→ important: "Not all" is true.

Consider  $z_1, z_2 = \frac{p_1^2}{2m_1}, \frac{p_2^2}{2m_2}$

ex:  $z_1, z_2, z_3, z_4, z_5$

$$z = \frac{p^2}{2m} = \frac{p^2}{2m} = \frac{p^2}{2m}$$

$$z = \frac{p^2}{2m} = \frac{p^2}{2m} = \frac{p^2}{2m}$$

$$\frac{p^2}{2m} = \frac{p^2}{2m} = \frac{p^2}{2m}$$

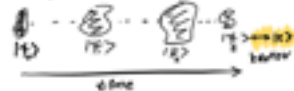
$$p^2 = p^2 = p^2$$

Is not a particle eq. is not physical.

So there is a time period possible of correct solutions.

Now ③: The solution is depending on time.

④ Model of Quantum Time Representation

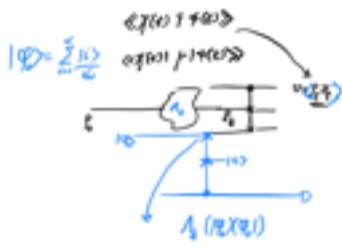


Mathematical representation



$$|\psi\rangle = \sum_k |k\rangle \langle k|\psi\rangle = \sum_k |k\rangle \langle k|\psi\rangle$$

$$|\psi\rangle = \sum_k |k\rangle \langle k|\psi\rangle = \sum_k |k\rangle \langle k|\psi\rangle$$



Tr[rho(t) rho(t)]

Tr[rho(t) rho(t)]

$$x \in [a, b] \times \mathbb{R}^n$$

$$i(\omega_1, \omega_2) \cdot A_{\omega}^* [f(\omega)]$$

$$\frac{A(y_1, x_2)}{x_1} \frac{f(\omega)}{f(\omega)}$$

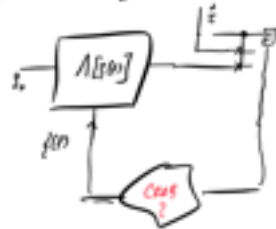
Problem

$$\begin{aligned} & \langle \xi | e^{-i g \hat{A} \hat{B}} | \xi \rangle = \langle \xi | e^{-i g \hat{A} \hat{B}} | \xi \rangle \\ & \approx \langle \xi | (1 - i g \hat{A} \hat{B}) | \xi \rangle \\ & \approx \langle \xi | \xi \rangle (1 - i g \langle \hat{A} \hat{B} \rangle) \\ & \approx \langle \xi | \xi \rangle [1 - i g \langle \hat{A} \hat{B} \rangle] \end{aligned}$$



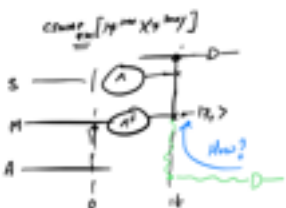
$$| \psi \rangle = \frac{1}{\sqrt{2}} (| \uparrow \rangle + | \downarrow \rangle)$$

- Notes
- Classical
  - Classical limit,  $\hbar \rightarrow 0$
  - Time limit,  $\hbar \rightarrow 0$ , Time dep. limit  $\hbar \rightarrow 0$



$$f(t) = \sum_{k=1}^N Q_k \sin(\omega_k t) + b_k \cos(\omega_k t)$$

$$| \psi \rangle = \frac{1}{\sqrt{2}} (| \uparrow \rangle + | \downarrow \rangle)$$



$$| \psi \rangle = \frac{1}{\sqrt{2}} (| \uparrow \rangle + | \downarrow \rangle)$$

$$e \in e \quad | \psi \rangle | \psi \rangle$$



Py

6

6

