

Directed Graphs

→ DIGRAPH: graph with ONLY directed edges

→ Reachability problem: Not nodes have an edge to connect them

→ Strongly connected: all nodes have edges between them

→ Transitive closure of graph $G = G^*$
→ DIGRAPH with same vertices as G

→ Floyd Warshall algo: Trans. closure

→ n steps: paths of length 1 to n , no more

Give you an example → $O(n^3)$: doesn't depend on number of edges
→ still really slow

→ if $(v_i, v_k) \in G_{k-1} \wedge (v_k, v_j) \in G_{k-1} \wedge (v_i, v_j) \notin G_{k-1}$
add new connection between

→ BFS, DFS: work the same way but we need to it according to DIRECTIONS

→ DFS: edges = (discovery ^(tree) \vee ^{non-tree}) types

→ Discovery edges form a tree rooted at starting vertex
→ no loops

→ Non tree:
→ Backtrack
→ Forward
→ Cross

→ DDFS: garbage collection

→ memory deallocation: mark and sweep

① Assign (live & live) mark to detect ~~the~~ DDFS

② EXAM: Floyd Warshall, DDFS

→ Eulerian trail: path in finite graph where each edge visited exactly once

→ Pen has to leave the paper when drawing edges: NOT Eulerian

→ nodes MUST have even degree of edges (think about it...)



