TEJORAM VIVEKANANDAN

10, Kalyani Nagar, Tirunelveli, Tamil Nadu, India - 627011 (+91)7010893334 ● tejoram1999@gmail.com ● https://tejoramv.github.io/

Education

B.E. Electronics and Communication Engineering, Coimbatore Institute of Technology, 2020

- CGPA 8.66/10 (First class with distinction)
- RELEVANT COURSEWORK: Robotics, Digital Image Processing, Data Structures & Algorithms, Probability & Random Process, Computer Organization & Microprocessor, Microcontroller Based System Design, C Programming, Programming in JAVA.

Experience

Computational Imaging Lab – Indian Institute of Technology, Madras

Chennai, India

Research Assistant

September 2021 – Present

- Research Topic: "Restoring extreme dark night-time images and Stereo depth estimation in real-time for Autonomous Vehicle"
- Developed a neural model with inspirations from U-Net which enhances images of low light and also predicts depth.
- The architecture is 100x faster and 20x computationally cheaper than that of state of art low light restoration.

NASA – Jet Propulsion Laboratory

Pasadena, California

Research Intern

September 2020 – September 2021

- Research Topic: "Correlation between color changes in Jupiter's storm "Oval BA", cloud heights and ultraviolet exposure"
- Implemented an algorithm for image processing pipeline automation which processed data of more than two decades.
- Used Nodding technique to suppress the background emission of the Jupiter sky.
- Obtained groundbreaking results with a correlation of 92.44% applying Minnaert function which validates that Oval BA storm's color changes are due to cloud heights.

NRSC - Indian Space Research Organisation

Hyderabad, India

Research Intern

November 2019 – August 2020

- Research Topic: "Shadow Detection and Radiometric Restoration in VHR Satellite Imagery"
- Detected shadows of Cartosat -2E satellite images using Color Invariant Index and Variance.
- Restored shadows through Gamma correction, Linear Correction, and Histogram Matching.
- Implemented region-based image segmentation and achieved average restoration accuracy of 96%.

Ministry of Electronics and Information Technology

Chennai, India

Research Intern

May 2019 – June 2019

- Research Topic: "Accelerated Life Testing"
- Designed algorithms by the application of Arrhenius, Eyring and Inverse Power Law relations, to extrapolate the end-use reliability characteristics of the products.

Publications

- Tejoram V et al., "Shadow Detection and Restoration in VHR Satellite Imagery", Journal of the Indian Society of Remote Sensing, 2020 [Under Review]
- Tejoram V et al., "Autonomous Vehicle Using Artificial Intelligence", Proc. Springer Int. Conference -Smart Materials and Techniques for Sustainable Development, 2019
- Tejoram V, "Advanced Space Vehicle and Defense Robot", Proc. IEEE Int. Conference Electrical, Communication, Electronics, Instrumentation and Computing, 2019

Handwritten Digit Recognition

2021

- Removed background through edge detection, localization and perspective transform.
- Computed ROI bounding box after thresholding.
- Developed a deep neural network to recognize the digits through classification.

Fruits classification using Deep Learning

2020

- Developed a custom CNN to classify different kinds of fruits and to facilitate real-time automated billing in grocery shops.
- Done a similar project of classification of bird species for the Ministry of Environment, India.

Autonomous vehicle using Artificial Intelligence

2019

- Designed an autonomous robot to perform lane detection and route traversal using image processing and CNN.
- Equipped it with a Raspberry Pi for processing, a camera, and four ultrasonic sensors for perception.
- Attained 95% decision accuracy using softmax activation function with 256 hidden layer nodes.

Advanced space and defense vehicle

2018

- Devised a robot for defense applications without any communication range restrictions by DTMF technology.
- Equipped it with video streaming, data logging and the ability to handle signal jammers.

Path follower industrial robot

2017

- Designed a robot with an array of Infrared sensors for a predefined route in industries of automated manufacturing.
- Minimized the Interference caused by the IR band of sunlight.

Skills

- Programming: C++, Python, Java, MATLAB
- Deep Learning frameworks: Keras, Tensorflow, Pytorch

Awards & Honors

2nd Prize in Project Expo on Road safety

Robert Bosch

April 2019

• Topic: "Autonomous vehicle using Artificial Intelligence"

3rd Prize in Paper Presentation

Government College of Technology

March 2019

• Topic: "Bird Species Classification using Machine Learning"

1st Prize in South Zone Innovators Meet

Institution of Electronics and Telecommunication Engineers (IETE)

April 2018

Topic: "Advanced vehicle and Defense Drone"

3rd Prize in Project Presentation

Coimbatore Institute of Technology

February 2018

Topic: "DTMF Controlled and Line Follower Robot"

2nd Prize in Project Presentation

Thiagaraja College of Engineering

February 2018

Topic: "Advanced space and defense vehicle"