CS 582: Distributed Systems

NTP and Logical Clocks



Dr. Zafar Ayyub Qazi Fall 2024

Recap: Clock Synchronization

- Computers track physical time with a quartz clock
- Due to clock drift, clock error gradually increases
- Clock skew: different between two clocks at a point in time
- Solution: Periodically get the current time from a server that has a more time source (e.g., atomic clock)

Recap: How do we synchronize time?

Synchronization in synchronous settings

$$\circ T_c = T_s + \frac{\min + \max}{2}$$

Cristian's algorithm

$$\circ T_c = T_s + \frac{RTT}{2}$$

- Berkeley algorithm
 - Use Cristian's algorithm to estimate time at each client
 - Average all local times
 - Send offsets

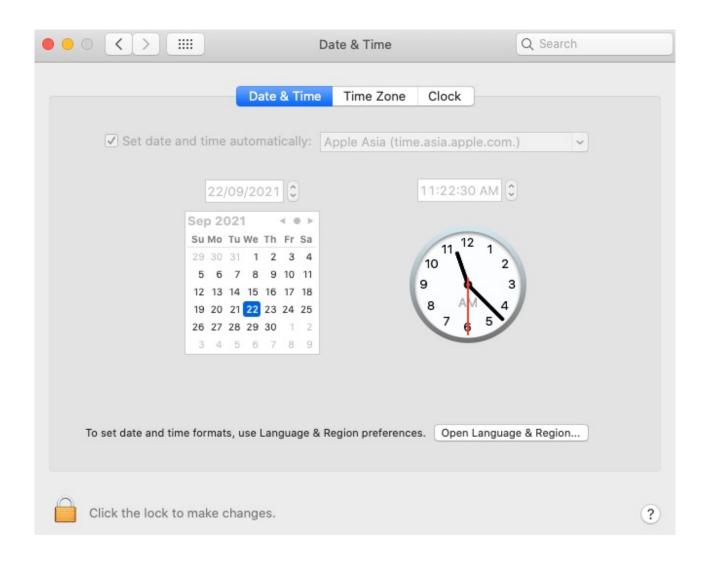
Today's Agenda

- Network Time Protocol (NTP)
- Logical Clock
 - Lamport Clock

Specific learning outcomes

| By the end of today's lecture, you should be able to: |
|--|
| Describe how NTP works |
| Analyze when and why NTP time can cause correctness issues in a program |
| Explain the happens-before relation |
| Analyze why happens-before can only guarantee a partial order |
| Explain what is a causal order |
| Describe how the Lamport clock algorithm works |
| lueCorrectly apply Lamport clock timestamps to a given set of events in a distributed system |
| Explain how the Lamport clock algorithm can be extended to implement a total order |

Network Time Protocol (NTP)

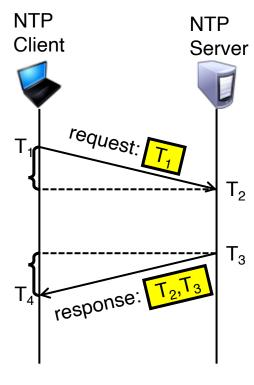


Network Time Protocol (NTP)

- Used by default in many operating systems
- Hierarchy of clock servers arranged into strata:
 - Stratum 0: atomic clock or GPS receiver
 - Stratum 1: synced directly with stratum 0 device
 - o Stratum 2: servers that sync with stratum 1, etc
 - 0 ...
- May contact multiple servers, discard outliers, average rest
- Makes multiple requests to the same servers, uses min RTT to reduce errors due to network delay variations

Estimating time over the network

- Round-trip network delay, $\alpha = (T_4 T_1) (T_3 T_2)$
- Offset = $\alpha/2$
- Estimated server time when client receives response = $T_3 + \alpha/2$
- Estimated clock skew = $\theta = T_3 + \alpha/2 T_4 = (T_2 T_1 + T_3 T_4)/2$



Time ↓

NTP: Apply correction to clock

- Once the client has estimated clock θ , it needs to apply that correction to its clock
 - $_{\circ}$ If μ < 125ms, slew the clock:
 - Slightly speed up or slow it down
 - Brings clocks in sync within ~5mins
 - $_{\circ}$ If 125ms <= μ < 1000s, step the clock
 - Suddenly reset client clock to estimated server timestamp
 - $_{\circ}$ If $\mu > 1000$ s, panic and do nothing
 - o Leave the problem for a human operator to resolve
- Systems that rely on clock sync need to monitor clock skew

Time-of-day clocks and monotonic time

Time of day clock

- Time since a fixed date (e.g., 1 Jan 1970)
- May suddenly move forwards or backwards (e.g., because of NTP step)
- Timestamps can be compared across nodes (if synced)
- Linux: clock_gettime(CLOCK_REALTIME)

Monotonic clock

- Time since an arbitrary point (e.g., when machine booted)
- Always moves forward at a constant rate
- o Good for measuring elapsed time on a single node
- Linux: clock_gettime (CLOCK_MONOTONIC)

Real synchronization is imperfect

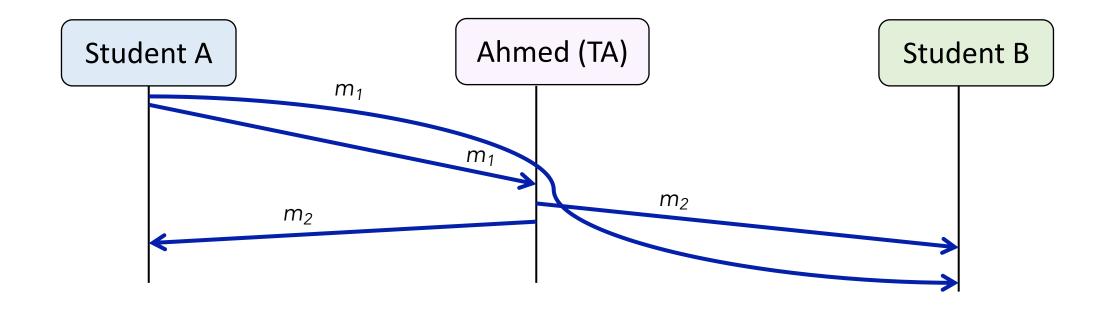
Clocks may never be exactly synchronized

 Q: Can we always use real time stamps to order events across nodes in a distributed system?

Ordering of Events

 Let's revisit our Slack example in which we wanted to order messages using timestamps

Example: Slack like Application

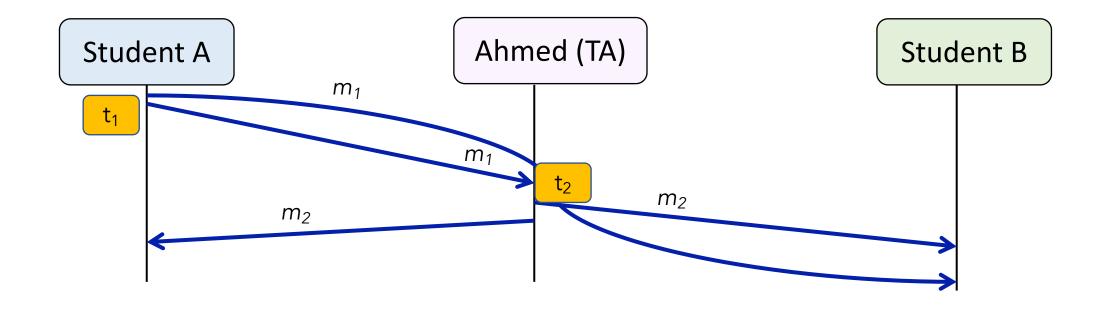


 m_1 : "Do we have a quiz on Mon?"

*m*₂: "No"

Student B sees m_2 first, m_1 second, even though logically m_1 happened before m_2

Ordering of messages using timestamps?



 m_1 : (t_1 , "Do we have a quiz on Mon?")

 m_2 : (t_2 , "No")

Problem: If the clocks are not synchronized, it is possible $t_2 < t_1$, which will result in an ordering that is inconsistent with the expected ordering

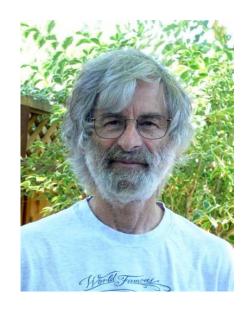
Driving question of the lecture

• Can we avoid synchronizing physical time altogether and order events in a distributed system?

Idea: Logical clocks

- Landmark 1978 paper by Leslie Lamport*
- Insight: only the events themselves matter

Idea: Disregard the physical clock time Instead, capture just a "happens before" relation between a pair of events



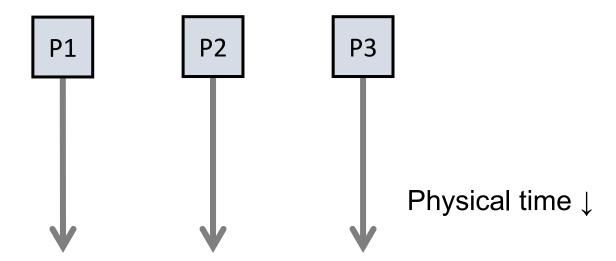
^{* &}quot;Time, Clocks and the Ordering of Events in Distributed Systems" by Lamport

^{*} Lamport was awarded the **Turing award in 2013** for his contributions in distributed systems

- An event is something happening at one node (sending or receiving a message, or a local execution step)
- If event a happens before event b, we write it as $a \rightarrow b$

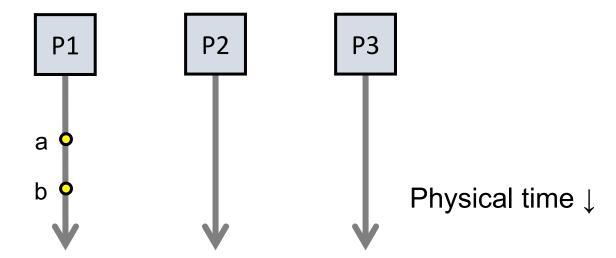
Defining "happens-before" relation (->)

• Consider three processes (on different nodes): P1, P2, and P3



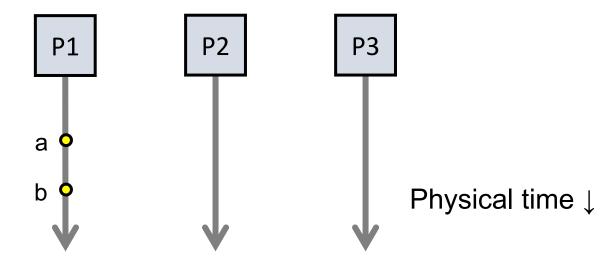
Defining "happens-before" relation (->)

1. Can observe event order at a single process

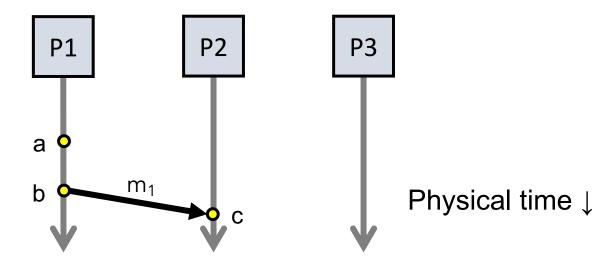


Defining "happens-before" relation (->)

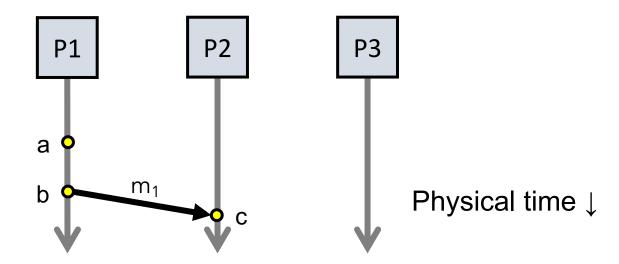
1. If same process and a occurs before b, then $a \rightarrow b$



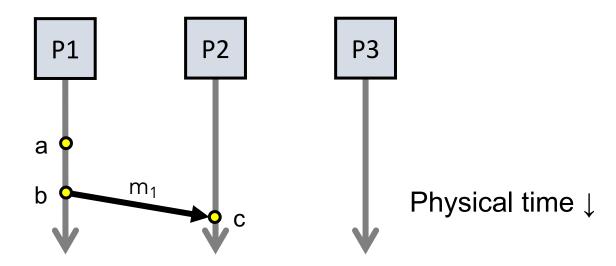
- 1. If same process and a occurs before b, then $a \rightarrow b$
- 2. Can observe ordering when processes communicate



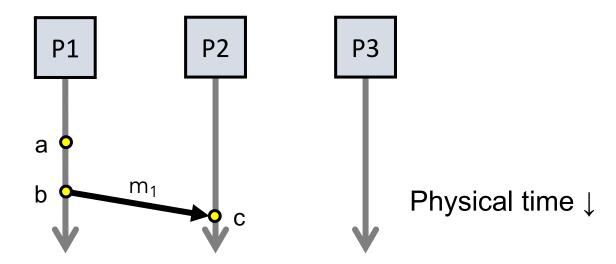
- 1. If same process and a occurs before b, then $a \rightarrow b$
- 2. If c is a message receipt of b, then $b \rightarrow c$



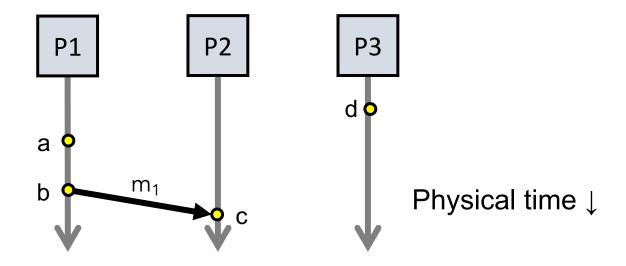
- 1. If same process and a occurs before b, then $a \rightarrow b$
- 2. If c is a message receipt of b, then $b \rightarrow c$
- 3. Can observe ordering transitively



- 1. If same process and a occurs before b, then $a \rightarrow b$
- 2. If c is a message receipt of b, then $b \rightarrow c$
- 3. If $a \rightarrow b$ and $b \rightarrow c$, then $a \rightarrow c$



How are events a and d related?



Are all events related by \rightarrow ?

Summary: "happens-before" relation (\rightarrow)

- We say a happens before event b (written $a \rightarrow b$) iff:
 - \circ a and b occurred at the same process, and a occurred before b in that process's local order, or
 - \circ Event a is the sending of some message m, and event b is the receipt of the same message m, or
 - \circ There exists an event c such that $a \rightarrow c$ and $c \rightarrow b$
 - Transitivity applies
- The happens-before relation is a <u>partial order</u>
 - \circ It is possible that neither $a \rightarrow b$ nor $b \rightarrow a$
 - \circ In that case, a and b are **concurrent** (written as $a \mid\mid b$)

Total Order

Potential Causality

- When $a \rightarrow b$, then a might have caused b
- When $a \parallel b$, we know that a could not have caused b
- Happens-before relation encodes potential causality

- - \circ If $a \rightarrow b => (a < b)$ then \prec is a causal order
 - Or < is "consistent with causality"

Questions

Lamport Clocks: Objective

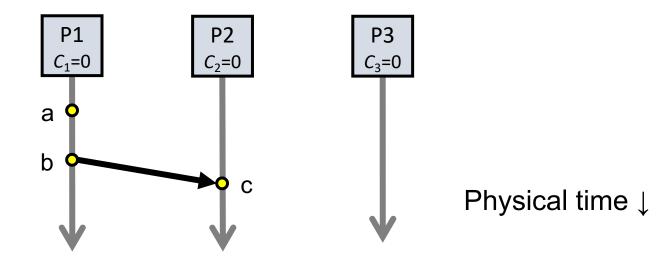
• We seek a clock time C(a) for every event a

Plan: Tag events with clock times; use clock times to make distributed system correct

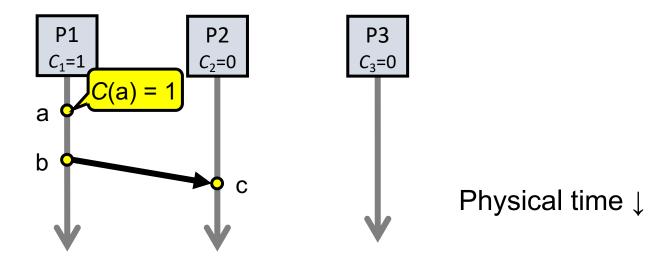
• Clock condition: If $a \to b$, then C(a) < C(b)

- Each process maintain an event counter
 - We refer to this event counter as the process's Lamport/local clock

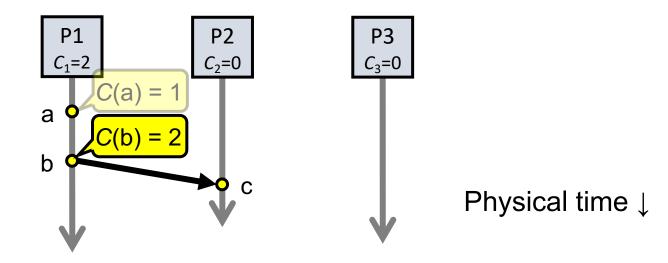
- Each process P_i maintains a local clock C_i
- 1. Before executing an event, $C_i \leftarrow Ci_{+1}$



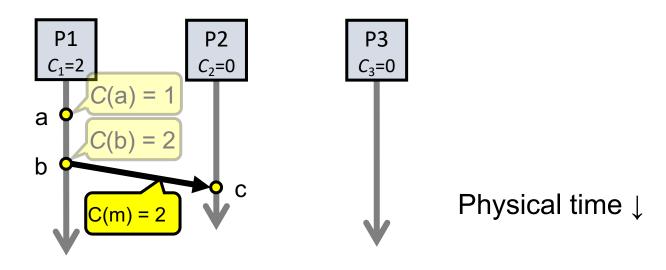
- 1. Before executing an event a, $C_i \leftarrow Ci_{+1}$:
 - ∘ Set event time $C(a) \leftarrow Ci$



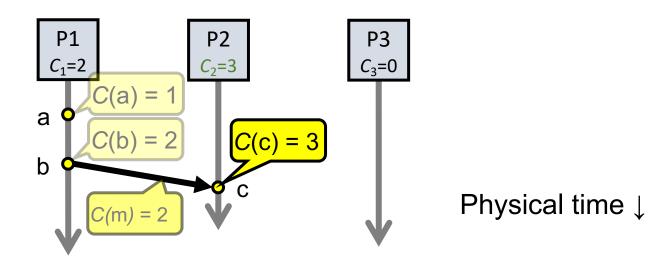
- 1. Before executing an event b, $C_i \leftarrow Ci + 1$:
 - \circ Set event time $C(b) \leftarrow C_i$



- 1. Before executing an event b, $C_i \leftarrow C_i + 1$
- 2. Send the local clock in the message m



- 3.On process P_j receiving a message m:
 - ∘ Set C_j and receive event time $C(c) \leftarrow 1 + \max\{C_j, C(m)\}$



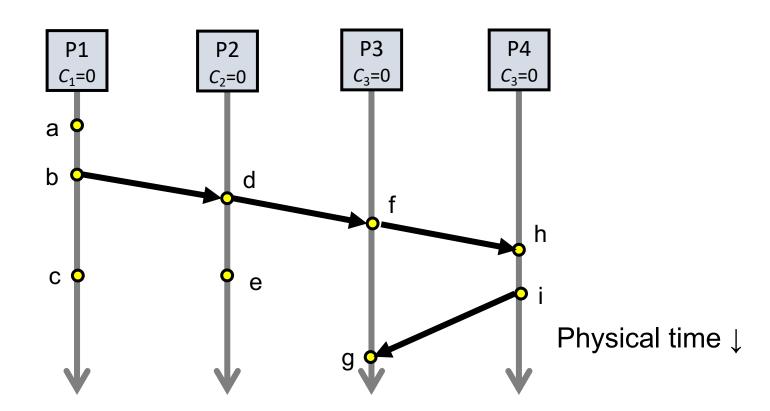
Summary: Lamport Clock Algorithm

- Each process maintains an event counter
- Before executing an event, increment the counter
- Whenever a process sends a message, include the counter
- When a message is received, set the counter to:
 - max(local_counter, received_counter) + 1

Lamport Clocks and Total Order

 How can we extend Lamport Clocks to guarantee total ordering of events?

Class Exercise: Order all these events



Summary: Happens-before and Lamport Clock

- Happens-before relation (a > b)
 - 1. Local update: If same process and a occurs before b, then $a \rightarrow b$
 - 2. Message communication: If b is a message receipt of a, then $a \rightarrow b$
 - 3. Transitivity: If $a \rightarrow c$ and $c \rightarrow b$, then $a \rightarrow b$

- Each process maintains an event counter
- Before executing an event, increment the counter
- o Whenever a process sends a message, include the counter value
- When a message is received, set the counter to:
 - o max(local_counter,received_counter) + 1

Take-away points: Lamport Clocks

- Can totally order events in a distributed system: that's useful!
- But: while by construction, a \rightarrow b implies C(a) < C(b),
 - The converse is not necessarily true:
 - C(a) < C(b) does not imply a → b (possibly, a II b)

Can't use Lamport clock timestamps to infer potential causal relationships between events

Next Lecture: Inferring potential causality

• Given two timestamps C(a) and C(z), want to know whether there's a chain of events linking them:

$$a \rightarrow b \rightarrow ... \rightarrow y \rightarrow z$$

Next Lecture

- Application of Lamport clocks
 - o Totally-ordered multicast for multi-site database replication
- Vector Clocks
 - o Can be used to infer potential causal relationships from timestamps